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Zero-Voltage Switching PWM Strategy Based Capacitor Current-Balancing Control for Half-Bridge Three-Level DC/DC Converter

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Abstract— The current imbalance among the two input capacitors is one of the important issues of the half-bridge three-level (HBTL) DC/DC converter, which would affect system performance and reliability. In this paper, a zero-voltage switching (ZVS) pulse-wide modulation (PWM) strategy including two operation modes is proposed. Based on the proposed ZVS PWM strategy, a capacitor current-balancing control is proposed for the HBTL DC/DC converter, where the currents on the two input capacitors can be kept balanced by alternating the two operation modes of the proposed ZVS PWM strategy. Therefore, the proposed control strategy can improve the performance and reliability of the converter in the aspect of balancing the thermal stresses and lifetimes among the two input capacitors. Finally, simulation and experimental studies are conducted and results verify the proposed control strategy.

Index Terms—Capacitor current-balancing control, DC/DC converter, three-level (TL).

I. INTRODUCTION

Due to the merits of the DC transmission such as no reactive power, no frequency stability, high conversion efficiency, and easy system control [1-3], DC distribution systems and DC micro-grids have been proposed as the promising solution for future smart-grid systems. Furthermore, DC data centers and residential systems have been increasingly developed recently [4], [5]. In DC transmission systems and DC grids, DC/DC converters play an important role in delivering the power and changing voltage levels [6-8].

Generally, in order to reduce the power losses and increase the power capability, a reasonable high DC voltage is preferred for the DC distribution systems and DC micro-grids. So far, a number of studies about the DC/DC converters with high input voltage for the DC distribution systems have been reported in literature. The three-level (TL) DC/DC converter is acknowledged as one of the promising solutions for the DC

distribution system development because the power switches in the TL converter only need to withstand half of the input voltage [9-12]. The TL circuit structure was firstly applied into the DC/DC converter in [13], [14]. Based on the conventional TL DC/DC converter, many other studies about TL DC/DC converters have been presented in [15-29]. Reference [24] proposed a novel four-switch HBTL DC/DC converter with zero-voltage switching (ZVS) control strategy, which only added one DC-blocking capacitor but removed two clamped diodes in comparison with the conventional TL DC/DC converter. Due to the low cost and compact circuit structure, the four-switch HBTL DC/DC converter has become attractive for industrial applications [25-28]. Reference [25] presented new solutions to achieve the wide range soft-switching based on the four-switch HBTL converter, in which four kinds of new pulse-wide modulation PWM TL DC/DC converters were proposed for the industrial application. In [26], a new PWM TL combined DC/DC converter was proposed to achieve wide range soft-switching. A secondary-side phase-shift controlled ZVS DC/DC converter with wide voltage gain and a three-phase DC/DC converter with low voltage stress on the power switches were proposed in [27] and [28] for the high voltage applications. In addition, reference [29] presented a new control strategy to balance the voltages on the two input capacitors for the four-switch HBTL DC/DC converter.

The above literatures mainly focus on the topics about improving the converter's performance by increasing the efficiency or enhancing the converter's reliability by balancing the input capacitor voltages. Unfortunately, there is few studies about the currents flowing through the input capacitors of the four-switch HBTL DC/DC converter, which would make significant influences on the reliability of the converter [30], [31]. In [24], it is analyzed that the currents among the two input capacitors in the four-switch HBTL converter are balanced based on the assumption that the input power supply is regarded as an ideal voltage source, which means that the input current can change abruptly along with the switching actions. However, in the real applications, these abrupt changes of the input current in the switching period are impractical because of the effect from the output inductance of the input power supply and the inductance of the input line on the input current, which would result in the current imbalance

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among the two input capacitors in the four-switch HBTL DC/DC converter. Furthermore, this current imbalance would become larger along with the output power increasing and input voltage increasing, and make influence on the converter's reliability in aspects of the thermal stress imbalance and lifetime imbalance among the two input capacitors.

In this paper, a ZVS PWM strategy and a capacitor current-balancing control are proposed for the four-switch HBTL DC/DC converter. The proposed ZVS PWM strategy is composed of two operation modes. Based on the proposed ZVS PWM strategy, a capacitor current-balancing control is proposed by alternating the two operation modes of the proposed PWM strategy, which can effectively eliminate the current imbalance among the two input capacitors. In addition, the switching losses caused by the hard switching at the light load situation can be distributed evenly among the four power switches by using the proposed control strategy. Therefore, the proposed control can balance the thermal stresses, lifetimes among the two input capacitors and balance the thermal stresses among the four power switches at the light load situation, which thus can improve the converter's performance and reliability. The currents on the two input capacitors of the four-switch HBTL DC/DC converter are analyzed in detail when considering the effect from the output inductance of the input power supply and inductance of the input line on the input current.

This paper is organized as follows. Section II analyzes the current imbalance issue in the four-bridge HBTL DC/DC converter under the conventional control strategy. Section III proposes the ZVS PWM strategy including the two operation modes and analyzes the performances of the four-switch HBTL DC/DC converter under the proposed ZVS PWM strategy. Section IV proposes the capacitor current-balancing control and analyzes the performances of the four-switch HBTL DC/DC converter under the proposed capacitor current-balancing control. Section V presents the simulation and experimental results to verify the proposed control strategy. Finally, the main contributions are summarized in Section VI.

II. CAPACITOR CURRENT IMBALANCE UNDER CONVENTIONAL CONTROL STRATEGY

A. Converter Structure and Conventional Control Strategy

Fig. 1(a) shows the structure of the four-switch HBTL DC/DC converter. In the primary side, two input capacitors C_1 and C_2 are used to split the input voltage V_{in} into two voltages V_1 and V_2 ; $S_1 - S_4$ and $D_1 - D_4$ are power switches and diodes; T_r is the high frequency transformer (HFT); L_r is the leakage inductance of T_r ; $C_{s1} - C_{s4}$ are the parasitic capacitors of $S_1 - S_4$; C_b is the DC-blocking capacitor. In the secondary side, there are four rectifier diodes $D_{r1} - D_{r4}$, one output filter inductor L_o , and one output filter capacitor C_o . In Fig. 1(a), i_{in} is the input current; i_{c1} and i_{c2} are the currents flowing through C_1 and C_2 , respectively; V_{pri} and i_p are the primary voltage and current of the transformer T_r ; i_{L_o} is the current through L_o ; V_{cb} is the voltage on the DC-blocking capacitor C_b ; i_o and V_o are

the output current and output voltage; V_{ab} is the voltage between point a and b; n is the turns ratio of the transformer T_r .

Fig. 1(b) shows the conventional control strategy [24] and main waveforms of the four-switch HBTL DC/DC converter. In Fig. 1(b), $d_{rv1} - d_{rv4}$ are four driving signals of the power switches $S_1 - S_4$, where (S_1, S_2) and (S_3, S_4) are complementary switch pairs. d_1 and d_2 are duty ratios in one switching period T_s , where d_2 is bigger than d_1 in the normal operations.

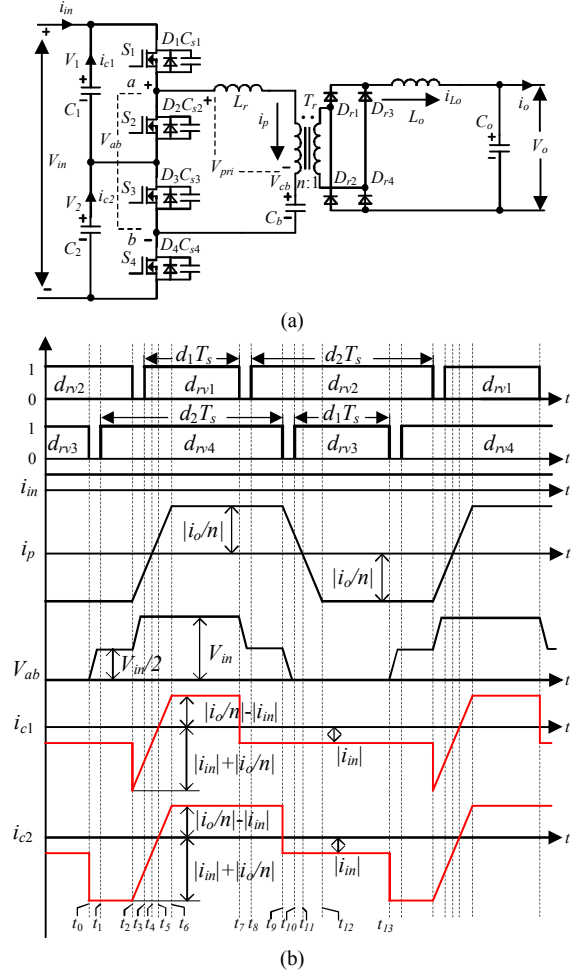


Fig. 1. (a) Structure of four-switch HBTL DC/DC converter. (b) Conventional control strategy with main waveforms.

B. Capacitor Current Imbalance Analysis

Before discussing about the currents on the two input capacitors of the four-switch HBTL DC/DC converter, several assumptions are made as below to simplify the analysis.

- 1) The inductance of the output filter inductor L_o is large enough to be considered as a current source;
- 2) The power switches $S_1 - S_4$ are ideal, which means that the effects of the parasitic capacitors are neglected;
- 3) The input current i_{in} is considered as a constant in the switching period due to the effect from the output inductance of the input power supply and inductance of the input line on the input current.

According to Fig. 1(b), i_{c1} and i_{c2} in one switching period T_s can be expressed as

$$i_{c1} = \begin{cases} -i_{in} & t_0 \leq t < t_2 \\ i_p - i_{in} & t_2 \leq t < t_7 \\ -i_{in} & t_7 \leq t < t_{13} \end{cases} \quad (1)$$

$$i_{c2} = \begin{cases} i_p - i_{in} & t_0 \leq t < t_9 \\ -i_{in} & t_9 \leq t < t_{13} \end{cases} \quad (2)$$

According to Fig. 1(b), the primary current i_p in one switching period T_s can be described as

$$i_p = \begin{cases} -\frac{i_o}{n} & t_0 \leq t < t_2 \\ -\frac{i_o}{n} + \frac{V_{in}}{2 \cdot L_r} \cdot (t - t_2) & t_2 \leq t < t_6 \\ \frac{i_o}{n} & t_6 \leq t < t_9 \\ \frac{i_o}{n} - \frac{V_{in}}{2 \cdot L_r} \cdot (t - t_9) & t_9 \leq t < t_{12} \\ -\frac{i_o}{n} & t_{12} \leq t < t_{13} \end{cases} \quad (3)$$

Substituting (3) into (1) and (2), i_{c1} and i_{c2} in one switching period can be rewritten as

$$i_{c1} = \begin{cases} -i_{in} & t_0 \leq t < t_2 \\ \frac{V_{in}}{2 \cdot L_r} \cdot (t - t_2) - \frac{i_o}{n} - i_{in} & t_2 \leq t < t_6 \\ \frac{i_o}{n} - i_{in} & t_6 \leq t < t_7 \\ -i_{in} & t_7 \leq t < t_{13} \end{cases} \quad (4)$$

$$i_{c1_rms_con} = \sqrt{i_{in}^2 + \frac{i_o^2 \cdot d_1}{n^2} + \frac{8 \cdot L_r \cdot i_{in} \cdot i_o^2}{n^2 \cdot V_{in} \cdot T_s} - \frac{2 \cdot i_{in} \cdot i_o \cdot d_1}{n} - \frac{8 \cdot L_r \cdot i_o^3}{3 \cdot n^3 \cdot V_{in} \cdot T_s}} \quad (7)$$

$$i_{c2_rms_con} = \sqrt{i_{in}^2 + \frac{i_o^2 \cdot d_2}{n^2} + \frac{8 \cdot L_r \cdot i_{in} \cdot i_o^2}{n^2 \cdot V_{in} \cdot T_s} - \frac{2 \cdot i_{in} \cdot i_o \cdot d_1}{n} - \frac{8 \cdot L_r \cdot i_o^3}{3 \cdot n^3 \cdot V_{in} \cdot T_s}} \quad (8)$$

$$\Delta i_{c_rms_con} = |i_{c1_rms_con} - i_{c2_rms_con}| = \frac{i_o^2 \cdot (d_2 - d_1)}{n^2 \cdot (i_{c1_rms_con} + i_{c2_rms_con})} \quad (9)$$

TABLE I
THEORETICAL CALCULATION FORMULAS OF RMS VALUES OF i_{c1} AND i_{c2}

Control Strategy	RMS Value	Theoretical Calculation Formula
Conventional Control Strategy	$i_{c1_rms_con}$	$\sqrt{i_{in}^2 + \frac{i_o^2 \cdot d_1}{n^2} + \frac{8 \cdot L_r \cdot i_{in} \cdot i_o^2}{n^2 \cdot V_{in} \cdot T_s} - \frac{2 \cdot i_{in} \cdot i_o \cdot d_1}{n} - \frac{8 \cdot L_r \cdot i_o^3}{3 \cdot n^3 \cdot V_{in} \cdot T_s}}$
	$i_{c2_rms_con}$	$\sqrt{i_{in}^2 + \frac{i_o^2 \cdot d_2}{n^2} + \frac{8 \cdot L_r \cdot i_{in} \cdot i_o^2}{n^2 \cdot V_{in} \cdot T_s} - \frac{2 \cdot i_{in} \cdot i_o \cdot d_1}{n} - \frac{8 \cdot L_r \cdot i_o^3}{3 \cdot n^3 \cdot V_{in} \cdot T_s}}$
	$\Delta i_{c_rms_con}$	$\frac{i_o^2 \cdot (d_2 - d_1)}{n^2 \cdot (i_{c1_rms_con} + i_{c2_rms_con})}$
Proposed Control Strategy	$i_{c1_rms_pro}$ $i_{c2_rms_pro}$	$\sqrt{i_{in}^2 + \frac{i_o^2}{2 \cdot n^2} + \frac{8 \cdot L_r \cdot i_{in} \cdot i_o^2}{n^2 \cdot V_{in} \cdot T_s} - \frac{2 \cdot i_{in} \cdot i_o \cdot d_1}{n} - \frac{8 \cdot L_r \cdot i_o^3}{3 \cdot n^3 \cdot V_{in} \cdot T_s}}$

$$i_{c2} = \begin{cases} -\frac{i_o}{n} - i_{in} & t_0 \leq t < t_2 \\ \frac{V_{in}}{2 \cdot L_r} \cdot (t - t_2) - \frac{i_o}{n} - i_{in} & t_2 \leq t < t_6 \\ \frac{i_o}{n} - i_{in} & t_6 \leq t < t_9 \\ -i_{in} & t_9 \leq t < t_{13} \end{cases} \quad (5)$$

In the steady-state situation, the time intervals $[t_2-t_6]$ and $[t_9-t_{12}]$ are the same as shown in Fig. 1(b), which can be calculated by

$$t_6 - t_2 = t_{12} - t_9 = \frac{4 \cdot L_r \cdot i_o}{n \cdot V_{in}} \quad (6)$$

According to (4) ~ (6), the root-mean-square (RMS) values of i_{c1} and i_{c2} under the conventional control strategy namely $i_{c1_rms_con}$ and $i_{c2_rms_con}$ can be calculated by (7) and (8), which are listed in Table I.

Based on (7) and (8), the difference between $i_{c1_rms_con}$ and $i_{c2_rms_con}$ namely $\Delta i_{c_rms_con}$ can be calculated by (9), which is also listed in Table I.

From (7) and (8), it can be seen that the currents on the two input capacitors i_{c1} and i_{c2} are imbalanced under the conventional control strategy and $i_{c2_rms_con}$ is bigger than $i_{c1_rms_con}$ because d_2 is bigger than d_1 in the normal operations. What is worse, this current imbalance issue would result in the thermal stress imbalance and lifetime imbalance among the two input capacitors, which would affect the reliability of the converter.

III. PROPOSED ZVS PWM STRATEGY

A. Proposed ZVS PWM Strategy

Fig. 2 shows the proposed ZVS PWM strategy for the four-switch HBTL DC/DC converter, which includes two operation modes.

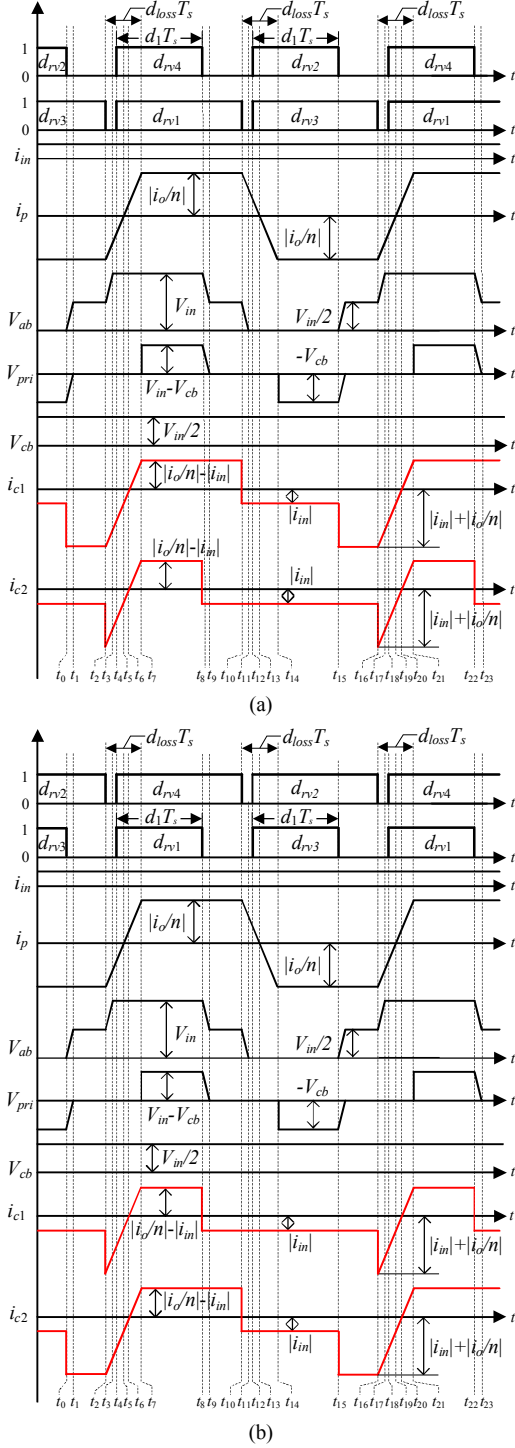


Fig. 2. Proposed ZVS PWM strategy with main waveforms. (a) Operation mode I. (b) Operation mode II.

In Fig. 2, d_{rv1} - d_{rv4} are four driving signals of the power switches S_1 - S_4 , d_1 is the duty ratio in one switching period, and

d_{loss} is the duty cycle loss. In the operation mode I, the duty ratios of d_{rv1} and d_{rv3} are both 0.5, and the duty ratios of d_{rv2} and d_{rv4} are both d_1 . Contrarily, in the operation mode II, the duty ratios of d_{rv2} and d_{rv4} are both 0.5, and the duty ratios of d_{rv1} and d_{rv3} are both d_1 . The maximum value of d_1 is 0.5 in the two operation modes, which avoids the short currents through the switch pairs (S_1, S_2) and (S_3, S_4). In addition, the two operation modes have the same output characteristics because the primary currents i_p and primary voltages V_{ab} in the two operation modes are the same as shown in Fig. 2.

Fig. 3 shows equivalent circuits to explain the operation principle of the operation mode I.

Stage 0 [before t_0] During this stage, both S_2 and S_3 are on-state, therefore the primary current i_p flows through S_2, S_3 , and C_b , the voltage V_{ab} is 0 V. The power from C_b is transferred to the output through T_r, D_{r2} , and D_{r3} .

Stage 1 [t_0 - t_1] At t_0 , the switch S_2 is turned off. The capacitor C_{s2} starts to charge, and the capacitor C_{s1} begins to discharge. This stage finishes until the voltage on C_{s2} increases to $V_{in}/2$ and the voltage on C_{s1} decreases to 0 V.

Stage 2 [t_1 - t_2] At t_1 , the voltage on C_{s2} becomes 0 V and the diode D_1 begins to conduct. The circuit operates in a free-wheeling mode with the primary current i_p flowing through L_r, D_1, C_1, S_3, C_b , and T_r . During this stage, the primary current i_p is kept at $-i_o/n$.

Stage 3 [t_2 - t_3] At t_2 , the switch S_3 is turned off. The capacitor C_{s3} starts to charge, and the capacitor C_{s4} begins to discharge. This stage finishes until the voltage on C_{s3} increases to $V_{in}/2$ and the voltage on C_{s4} decreases to 0 V. The primary current i_p starts to increase, and it is not enough to provide i_o , so the rectifier diodes D_{r1} - D_{r4} conduct simultaneously.

Stage 4 [t_3 - t_4] At t_3 , the voltage on C_{s4} becomes 0 V and the diode D_4 begins to conduct. The circuit operates in a free-wheeling mode with the primary current i_p flowing through $L_r, D_1, C_1, C_2, D_4, C_b$, and T_r .

Stage 5 [t_4 - t_5] At t_4 , the switches S_1 and S_4 are turned on at zero-voltage. The primary current i_p flows through $L_r, S_1, C_1, C_2, S_4, C_b$, and T_r .

Stage 6 [t_5 - t_6] At t_5 , the primary current i_p increases to 0 A and continues to increase linearly, which means the direction of i_p begins to change.

Stage 7 [t_6 - t_7] At t_6 , the primary currents i_{c1} and i_{c2} increases to 0 A, which means the directions of i_{c1} and i_{c2} begin to change.

Stage 8 [t_7 - t_8] At t_7 , the primary current i_p increases to i_o/n , D_{r2} and D_{r3} turn off, then the input power begins to be transferred to the output through T_r, D_{r1} , and D_{r4} . During this stage, the primary current i_p is kept at i_o/n .

Stage 9 [t_8 - t_9] At t_8 , the switch S_4 is turned off. The capacitor C_{s4} starts to charge, and the capacitor C_{s3} begins to discharge. This stage finishes until the voltage on C_{s4} increases to $V_{in}/2$ and the voltage on C_{s3} decreases to 0 V.

Stage 10 [t_9 - t_{10}] At t_9 , the voltage on C_{s3} decreases to 0 V and diode D_3 begins to conduct. The circuit operates in a free-wheeling mode with the primary current i_p flowing through L_r, T_r, C_b, D_3, C_1 , and S_1 .

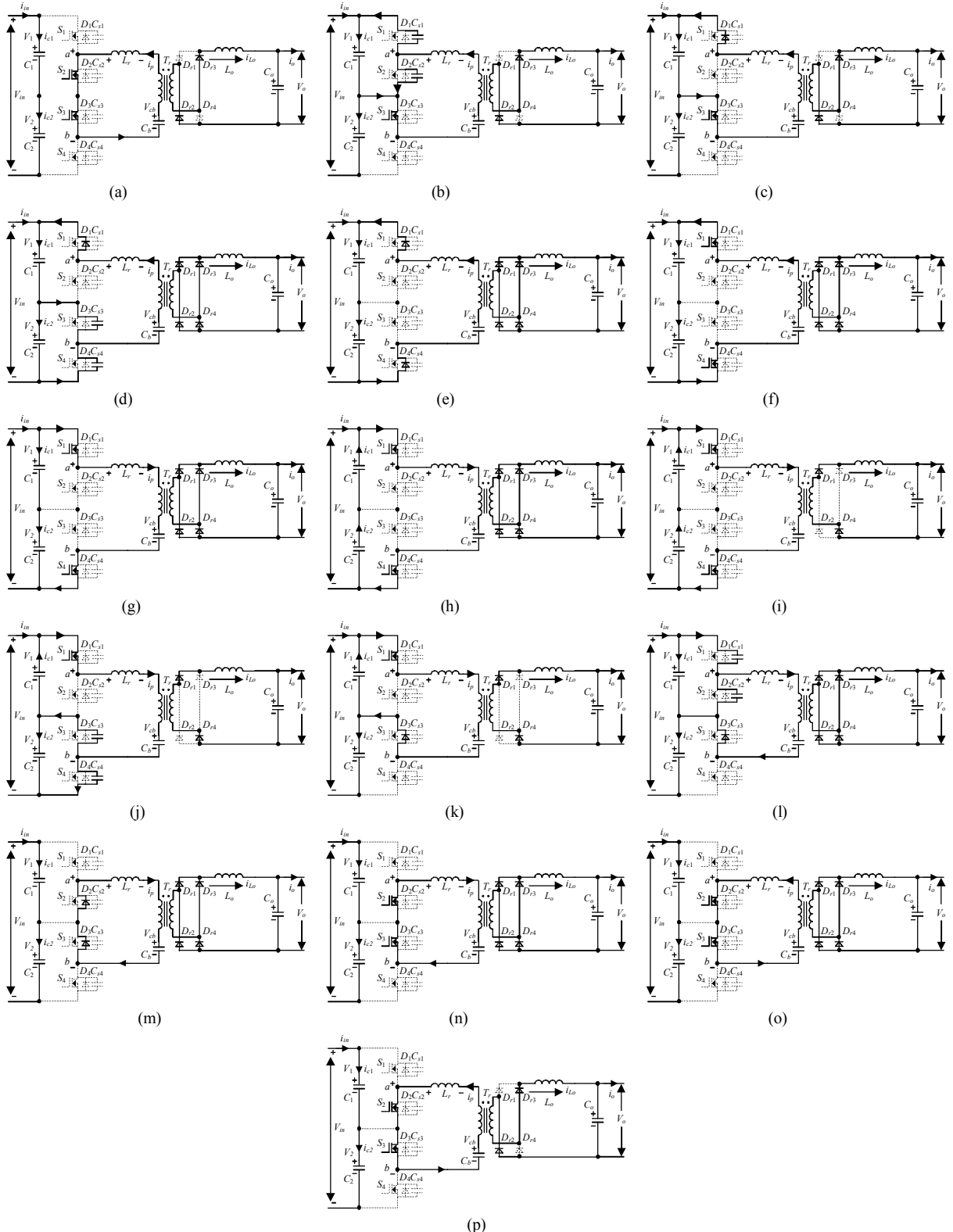


Fig. 3. Equivalent circuits in the operation mode I. (a) [before t_0]. (b) [$t_0 - t_1$]. (c) [$t_1 - t_2$]. (d) [$t_2 - t_3$]. (e) [$t_3 - t_4$]. (f) [$t_4 - t_5$]. (g) [$t_5 - t_6$]. (h) [$t_6 - t_7$]. (i) [$t_7 - t_8$]. (j) [$t_8 - t_9$]. (k) [$t_9 - t_{10}$]. (l) [$t_{10} - t_{11}$]. (m) [$t_{11} - t_{12}$]. (n) [$t_{12} - t_{13}$]. (o) [$t_{13} - t_{14}$]. (p) [$t_{14} - t_{15}$].

Stage 11 [t_{10} - t_{11}] At t_{10} , the switch S_1 is turned off. The capacitor C_{s1} starts to charge, and the capacitor C_{s2} begins to discharge. This stage finishes until the voltage on C_{s1} increases to $V_{in}/2$ and the voltage on C_{s2} decreases to 0 V. The primary

current i_p starts to decrease, and it is not enough to provide i_o , so the rectifier diodes D_{r1} - D_{r4} conduct simultaneously. The current i_{c1} decreases to $-i_{in}$.

Stage 12 [t_{11} - t_{12}] At t_{11} , the voltage on C_{s2} becomes 0 V and diode D_2 begins to conduct. The circuit operates in a free-wheeling mode with the primary current i_p flowing through L_r , T_r , C_b , D_3 , and D_2 . During this stage, both current i_{c1} and i_{c2} are $-i_{in}$.

Stage 13 [t_{12} - t_{13}] At t_{12} , the switches S_2 and S_3 are turned on at zero-voltage. The primary current i_p would flow through L_r , T_r , C_b , S_3 , and S_2 .

Stage 14 [t_{13} - t_{14}] At t_{13} , the primary current i_p decreases to 0 A and continues to decrease linearly, which means the direction of primary current i_p begins to change.

Stage 15 [t_{14} - t_{15}] At t_{14} , the primary current i_p decreases to $-i_o/n$, D_{r1} and D_{r4} turn off, then the power from C_b is transferred to the output through T_r , D_{r2} , and D_{r3} . During this stage, the primary current i_p is kept at $-i_o/n$.

At t_{15} , the following work operation in the next period starts, which is the same as the first switching period. The main difference between the operation mode I and operation mode II is that the currents i_{c1} and i_{c2} shift each other as figured by red color in Fig. 2. The operation principle analysis of the operation mode II is similar to that of the operation mode I, which is not repeated here.

B. Conditions of ZVS Achievement

Before discussing the conditions of the ZVS achievement, one assumption is made that the four power switches S_1 - S_4 have the same parasitic capacitors namely C_s .

$$C_{s1} = C_{s2} = C_{s3} = C_{s4} = C_s \quad (10)$$

In the operation mode I, in order to ensure S_1 or S_3 realizing zero-voltage switch-on, the energy E_1 is needed to fully discharge the parasitic capacitor of the in-coming switch and charge the parasitic capacitor of the out-going switch. Taking t_8 in Fig. 2(a) as example, E_1 for the switch S_3 to achieve zero-voltage switch-on can be expressed as (11) according to the energy of these two parasitic capacitors.

$$E_1 = \frac{1}{2} \cdot C_{s3} \cdot \left(\frac{V_{in}}{2}\right)^2 + \frac{1}{2} \cdot C_{s4} \cdot \left(\frac{V_{in}}{2}\right)^2 = \frac{1}{4} \cdot C_s \cdot V_{in}^2 \quad (11)$$

During the time internal [t_8 - t_{10}] as shown in Fig. 2(a), the output filter inductor is reflected to the primary side and is in series with the leakage inductance of the transformer. Therefore, the energy to achieve zero-voltage switch-on for S_1 and S_3 is provided by both the output filter inductance and the leakage inductance of the transformer. Normally, the output filter inductance is large enough to realize the zero-voltage switch-on for S_1 and S_3 even at light load.

The energy E_2 from the leakage inductance of the transformer is used to achieve zero-voltage switch-on of switches S_2 and S_4 . In order to achieve the zero-voltage switch-on of S_2 or S_4 , the energy E_2 should satisfy the requirement of (12) to fully discharge the parasitic capacitor of the in-coming switch and charge the parasitic capacitor of the out-going switch. The switches S_2 and S_4 are more difficult to achieve zero-voltage switch-on than that of S_1 and S_3 since the leakage inductance L_r is quite smaller than the reflected output filter inductance.

$$E_2 = \frac{1}{2} \cdot L_r \cdot \left(\frac{I_o}{n}\right)^2 \geq \frac{1}{4} \cdot C_s \cdot V_{in}^2 \quad (12)$$

In the operation mode II, the energy from both the output filter inductance and leakage inductance of the transformer is provided for the switches S_2 , S_4 to realize the zero-voltage switch-on, and the energy from the leakage inductance of the transformer is provided for the switches S_1 , S_3 to achieve the zero-voltage switch-on, which is just contrary to the operation mode I. The analysis of the ZVS achievement conditions in the operation mode II is similar to that in the operation mode I, which is not repeated here.

The ZVS achievement conditions under the proposed PWM strategy are almost the same as that under the conventional control strategy. For instance, the needed energy to achieve ZVS for the switch pairs S_2 , S_4 and S_1 , S_3 in the operation mode II is the same as that for the switch pairs S_2 , S_4 and S_1 , S_3 in the conventional control strategy shown in Fig. 1(b). Therefore, the switching losses under the conventional control strategy and proposed ZVS PWM strategy are almost the same.

C. Proposed ZVS PWM Strategy Analysis

Assuming that the DC-blocking capacitor is large enough to be considered as a voltage source, the voltage on the DC-blocking capacitor V_{cb} in the steady states is

$$V_{cb} = \frac{V_{in}}{2} \quad (13)$$

If neglecting the duty cycle loss d_{loss} , the output voltage V_o can be obtained by (14) according to Fig. 2.

$$V_o = \frac{1}{n} \cdot [(V_{in} - V_{cb}) \cdot d_1 + V_{cb} \cdot d_1] \quad (14)$$

Substituting (13) into (14), then the output voltage V_o can be rewritten as

$$V_o = \frac{V_{in}}{n} \cdot d_1 \quad (15)$$

In the real operation, the duty cycle loss d_{loss} as shown in Fig. 2 would affect the output voltage V_o , which can be calculated by

$$d_{loss} = \frac{t_7 - t_2}{T_s} = \frac{4 \cdot L_r \cdot i_o}{n \cdot V_{in} \cdot T_s} \quad (16)$$

After considering the effect of the duty cycle loss d_{loss} , the output voltage V_o can be further expressed as (17) according to (15) and (16).

$$V_o = \frac{V_{in}}{n} \cdot (d_1 - d_{loss}) = \frac{V_{in}}{n} \cdot \left(d_1 - \frac{4 \cdot L_r \cdot i_o}{n \cdot V_{in} \cdot T_s}\right) \quad (17)$$

IV. PROPOSED CAPACITOR CURRENT-BALANCING CONTROL

A. Proposed Capacitor Current-Balancing Control

According to the analysis in the Section III, the main difference between the two operation modes of the proposed ZVS PWM strategy is the currents flowing through the two input capacitors. The RMS value of i_{c1} is bigger than that of i_{c2} in the operation mode I, but the RMS value of i_{c1} is smaller than that of i_{c2} in the operation mode II. Therefore, based on

this difference between the two operation modes of the proposed ZVS PWM strategy, a capacitor current-balancing control for balancing the two currents i_{c1} and i_{c2} is proposed by alternating the two operation modes as shown in Fig. 4.

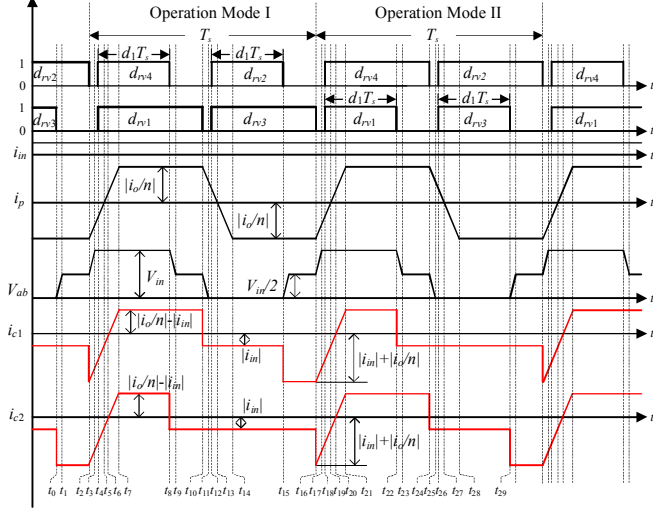


Fig. 4. Proposed capacitor current-balancing control with main waveforms.

In the proposed control, the operation mode I is used in the first switching period and the operation mode II is used in the second switching period, which achieves that the currents on the two input capacitors are the same in every two switching periods as shown in Fig. 4.

The proposed capacitor current-balancing control operates by alternating the two operation modes of the proposed ZVS PWM strategy, so the ZVS achievement conditions of the proposed capacitor current-balancing control are the combination of the ZVS achievement conditions of the two operation modes. In the first switching period, as shown in Fig. 4 (Operation Mode I), the energy from both the output filter inductance and leakage inductance of the transformer is provided for S_3, S_4 to realize the zero-voltage switch-on, and the energy from the leakage inductance of the transformer is provided for S_1, S_2 to achieve the zero-voltage switch-on. In the second switching period, as shown in Fig. 4 (Operation Mode II), the ZVS achievement conditions are just contrary to that in the first switching period, which means the energy from both the output filter inductance and leakage inductance of the transformer is provided for S_1, S_2 to realize the zero-voltage switch-on, and the energy from the leakage inductance of the transformer is provided for S_3, S_4 to achieve the zero-voltage switch-on.

B. Input Capacitor Current Analysis

In Fig. 4, the currents on the two input capacitors i_{c1} and i_{c2} in two switching periods can be expressed as

$$i_{c1} = \begin{cases} -i_{in} & t_0 \leq t < t_2 \\ i_p - i_{in} & t_2 \leq t < t_{10} \\ -i_{in} & t_{10} \leq t < t_{15} \\ i_p - i_{in} & t_{15} \leq t < t_{22} \\ -i_{in} & t_{22} \leq t < t_{29} \end{cases} \quad (18)$$

$$i_{c2} = \begin{cases} i_p - i_{in} & t_0 \leq t < t_8 \\ -i_{in} & t_8 \leq t < t_{16} \\ i_p - i_{in} & t_{16} \leq t < t_{24} \\ -i_{in} & t_{24} \leq t < t_{29} \end{cases} \quad (19)$$

According to Fig. 4, the primary current i_p in one switching period can be expressed as

$$i_p = \begin{cases} -\frac{i_o}{n} & t_0 \leq t < t_2 \\ -\frac{i_o}{n} + \frac{V_{in}}{2 \cdot L_r} \cdot (t - t_2) & t_2 \leq t < t_7 \\ \frac{i_o}{n} & t_7 \leq t < t_{10} \\ \frac{i_o}{n} - \frac{V_{in}}{2 \cdot L_r} \cdot (t - t_2) & t_{10} \leq t < t_{14} \\ -\frac{i_o}{n} & t_{14} \leq t < t_{15} \end{cases} \quad (20)$$

Substituting (20) into (18) and (19), i_{c1} and i_{c2} in two switching periods can be rewritten as

$$i_{c1} = \begin{cases} -i_{in} & t_0 \leq t < t_2 \\ \frac{V_{in}}{2 \cdot L_r} \cdot (t - t_2) - \frac{i_o}{n} - i_{in} & t_2 \leq t < t_7 \\ \frac{i_o}{n} - i_{in} & t_7 \leq t < t_{10} \\ -i_{in} & t_{10} \leq t < t_{15} \\ -\frac{i_o}{n} - i_{in} & t_{15} \leq t < t_{16} \\ \frac{V_{in}}{2 \cdot L_r} \cdot (t - t_2) - \frac{i_o}{n} - i_{in} & t_{16} \leq t < t_{21} \\ \frac{i_o}{n} - i_{in} & t_{21} \leq t < t_{22} \\ -i_{in} & t_{22} \leq t < t_{29} \end{cases} \quad (21)$$

$$i_{c2} = \begin{cases} -\frac{i_o}{n} - i_{in} & t_0 \leq t < t_2 \\ \frac{V_{in}}{2 \cdot L_r} \cdot (t - t_2) - \frac{i_o}{n} - i_{in} & t_2 \leq t < t_7 \\ \frac{i_o}{n} - i_{in} & t_7 \leq t < t_8 \\ -i_{in} & t_8 \leq t < t_{16} \\ \frac{V_{in}}{2 \cdot L_r} \cdot (t - t_2) - \frac{i_o}{n} - i_{in} & t_{16} \leq t < t_{21} \\ \frac{i_o}{n} - i_{in} & t_{21} \leq t < t_{24} \\ -i_{in} & t_{24} \leq t < t_{29} \end{cases} \quad (22)$$

In Fig. 4, the time intervals $[t_2 - t_7]$ and $[t_{16} - t_{21}]$ are the same, which can be described as

$$t_7 - t_2 = t_{21} - t_{16} = \frac{4 \cdot L_r \cdot i_o}{n \cdot V_{in}} \quad (23)$$

According to (21) ~ (23), the RMS values of i_{c1} and i_{c2}

under the proposed capacitor current-balancing control namely $i_{c1_rms_pro}$ and $i_{c2_rms_pro}$ can be calculated by (24), which is listed in Table I.

$$i_{c1_rms_pro} = i_{c2_rms_pro} = \sqrt{\frac{i_{in}^2 + \frac{i_o^2}{2 \cdot n^2} + \frac{8 \cdot L_r \cdot i_{in} \cdot i_o^2}{n^2 \cdot V_{in} \cdot T_s}}{\frac{2 \cdot i_{in} \cdot i_o \cdot d_1}{n} - \frac{8 \cdot L_r \cdot i_o^3}{3 \cdot n^3 \cdot V_{in} \cdot T_s}}} \quad (24)$$

From Table I, it can be observed that: 1) under the conventional control strategy, the RMS values of i_{c1} and i_{c2} are imbalanced, and the RMS value of i_{c1} is smaller than that of i_{c2} because d_2 is bigger than d_1 in the normal operations; 2) after utilizing the proposed control, the RMS values of i_{c1} and i_{c2} become the same, which means that the current imbalance among the two input capacitors in the four-switch HBTL DC/DC converter is eliminated by utilizing the proposed capacitor current-balancing control. One thing need to be mentioned is that (7), (8), and (24) are derived based on the continuous primary current i_p , therefore these equations are only suitable for the continuous conduction mode (CCM).

By putting the circuit parameters in the Appendix into (7), (8), and (24), the calculated RMS values of i_{c1} and i_{c2} with various output power and output voltages are presented in Fig. 5 when the output voltage is 50 V. In addition, the calculated results by (9) about the difference between the RMS values of i_{c1} and i_{c2} under the conventional control strategy $\Delta i_{c_rms_con}$ are shown in Fig. 6.

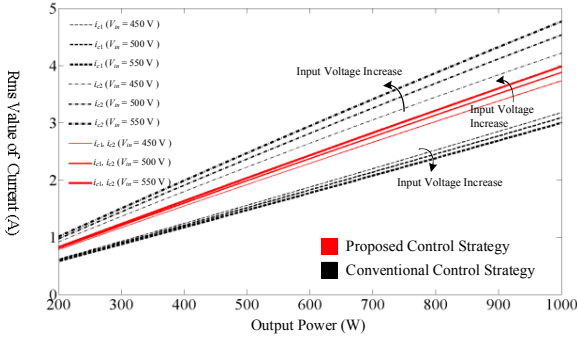


Fig. 5. Calculated RMS values of i_{c1} and i_{c2} with various input voltages and output power.

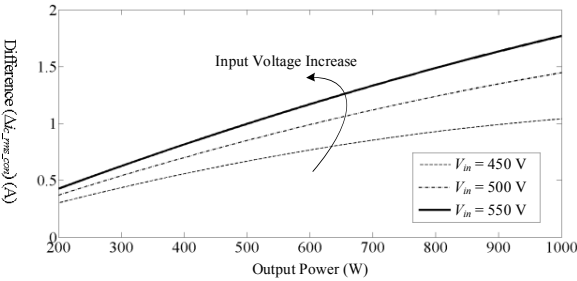


Fig. 6. Calculated difference between the RMS values of i_{c1} and i_{c2} with various input voltages and output power under the conventional control strategy.

From Figs. 5 and 6, it can be seen that: 1) under the conventional control strategy, the RMS values of i_{c1} and i_{c2} are imbalanced, the RMS value of i_{c2} is bigger than that of i_{c1} ; 2) such capacitor current imbalance under the conventional

control strategy becomes larger along with the output power increasing and input voltage increasing as shown in Fig. 6, and the largest difference reaches 1.77 A when the output power increases to 1-kW and the input voltage increases to 550 V; 3) under the proposed control, the RMS values of i_{c1} and i_{c2} are kept balanced along with the output power increasing and output voltage increasing, and these RMS values of i_{c1} and i_{c2} range between the RMS values of i_{c1} and i_{c2} under the conventional control strategy.

C. Switching Loss Distribution Analysis

Based on the above analysis, it can be observed that the two power switches whose energy to achieve ZVS is from the leakage inductance of the transformer would firstly lose ZVS in comparison with the other two power switches whose energy to achieve ZVS is from the both the output filter inductance and leakage inductance of the transformer at the light load situation. As to the conventional control strategy as shown in Fig. 1(b), S_1 and S_3 would always firstly lose zero-voltage switch-on at the light load while S_2 , S_4 can still realize zero-voltage switch-on, which means that the switching losses of S_1 and S_3 are more than that of S_2 and S_4 . However, as to the proposed capacitor current-balancing control as show in Fig. 4, S_1 , S_2 would firstly lose zero-voltage switch-on in the first switching period but S_3 , S_4 would firstly lose zero-voltage switch-on in the second switching period according to the above theoretical analysis in the Section IV-A, which means the ZVS achievement conditions of (S_1 , S_2) and (S_3 , S_4) are shifted each other in every two switching periods. Therefore, the switching losses caused by the hard switching at the light load situation can be distributed evenly among the four power switches under the proposed capacitor current-balancing control.

In order to simplify the theoretical calculation about the switching losses of the power switches at the light load situation, one assumption is made that the two switches of the four switches would firstly lose zero-voltage switch-on when the energy of the leakage inductance E_2 as (12) decreases to ten percentage of the energy that can fully realize zero-voltage switch-on. Therefore, two switches are not able to realize zero-voltage switch-on when the output power is about 200 W according to (12) and the circuit parameters in the Appendix. Based on [32], the theoretical calculation about the switching losses of the four power switches under the conventional control strategy and proposed control strategy is shown in Fig. 7, where the output power is 200 W. From Fig. 7, it can be observed that: 1) the switching losses of S_1 and S_3 are bigger than that of S_2 and S_4 under the conventional control strategy; 2) the switching loss of each switch is the same under the proposed control. Therefore, the thermal stresses on the four power switches S_1 - S_4 would be more balanced under the proposed capacitor current-balancing control than that under the conventional control strategy at the light load situation, which can improve the reliability of the converter.

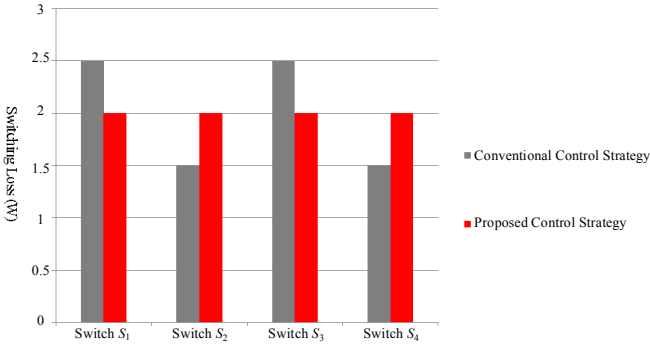


Fig. 7. Calculated switching losses of the four power switches when the output power is 200 W.

V. SIMULATION AND EXPERIMENTAL VERIFICATION

A. Simulation Verification

In order to verify the proposed control strategy, a simulation model of the four-switch HBTL DC/DC converter is built in PLECS, whose circuit parameters are listed in the Appendix. In the simulation, the input voltage is 550 V, the output voltage is 50 V, and the output power is 1-kW.

Fig. 8(a) shows the performances under the conventional control strategy, where i_{c1} and i_{c2} are imbalanced. Under the conventional control strategy, the RMS values of i_{c1} and i_{c2} are 3.05 A and 5.11 A, and their average values are both 0 A. Fig. 8(b) shows the performances under the proposed control strategy, where i_{c1} and i_{c2} are kept balanced. Under the proposed control strategy, the RMS values of i_{c1} and i_{c2} are both 4.2 A, and their average values are both 0 A. From Fig. 8, it can be also observed that the currents i_{c1} and i_{c2} are kept same in every two switching periods as marked in Fig. 8(b), which is consistent with the above theoretical analysis. In summary, the simulation results verify that the current imbalance among the two input capacitors is effectively eliminated with the help of the proposed capacitor current-balancing control.

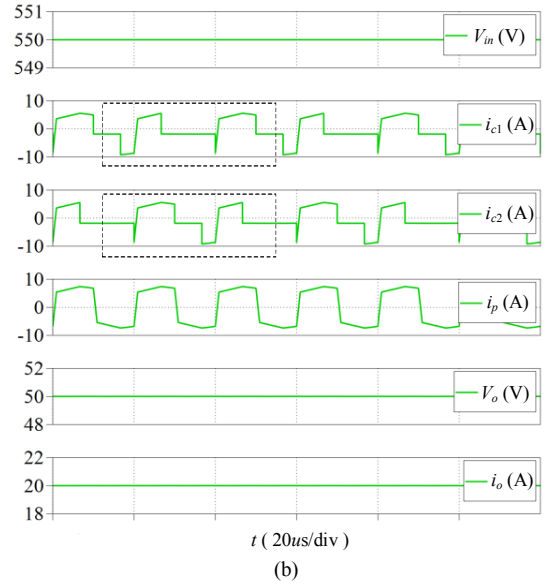
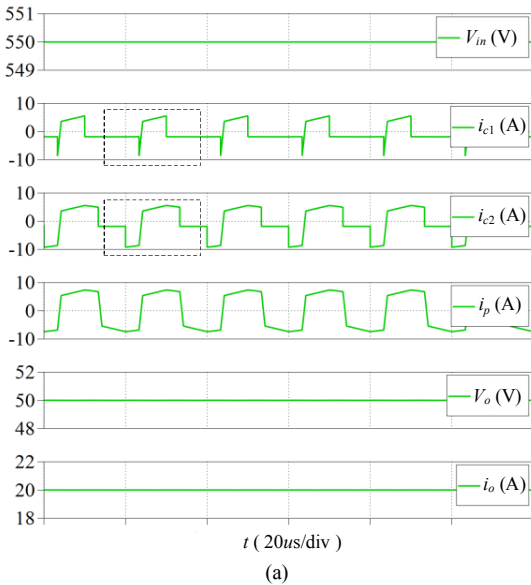
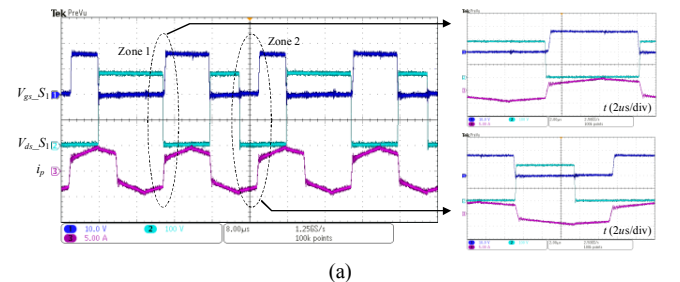


Fig. 8. Simulation results including V_{in} , V_o , i_{c1} , i_{c2} , i_p , and i_o . (a) Conventional control strategy. (b) Proposed control strategy.

B. Experimental Verification

A 1-kW four-switch HBTL DC/DC converter prototype is built to verify the proposed control strategy. The specifications of the built prototype are listed in the Appendix. In the experiments, the input voltage is 450 V ~ 550 V, and the output voltage V_o is 50 V.

Figs. 9 and 10 show the ZVS achievement conditions under the proposed control strategy. Fig. 9 shows the primary current i_p , driving signal V_{gs_S1} , and drain-source voltage V_{ds_S1} of the power switch S_1 , which illustrates that S_1 realizes ZVS and its voltage stress is half of the input voltage. Figs. 9(a) and (b) show ZVS of S_1 under 500 W and 1-kW, respectively. In Fig. 9, the energy from the leakage inductance of the transformer is provided for S_1 to achieve the zero-voltage switch-on at zone 1, and the energy from both the output filter inductance and leakage inductance of the transformer is provided for S_1 to realize the zero-voltage switch-on at zone 2. Fig. 10 shows the primary current i_p , driving signal V_{gs_S3} , and drain-source voltage V_{ds_S3} of the power switch S_3 , which illustrates that S_3 realizes ZVS and its voltage stress is half of the input voltage. Figs. 10(a) and (b) show ZVS of S_3 under 500 W and 1-kW, respectively. In Fig. 10, the energy from both the output filter inductance and leakage inductance of the transformer is provided for S_3 to achieve the zero-voltage switch-on at zone 1, and the energy from the leakage inductance of the transformer is provided for S_3 to realize the zero-voltage switch-on at zone 2.



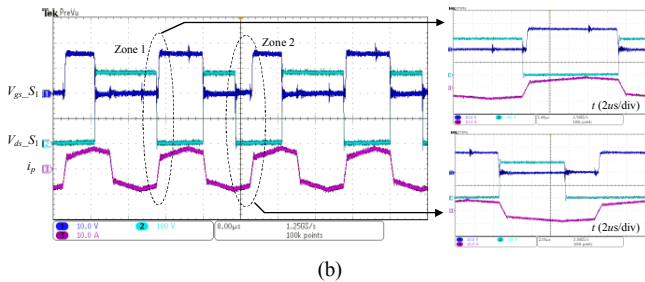
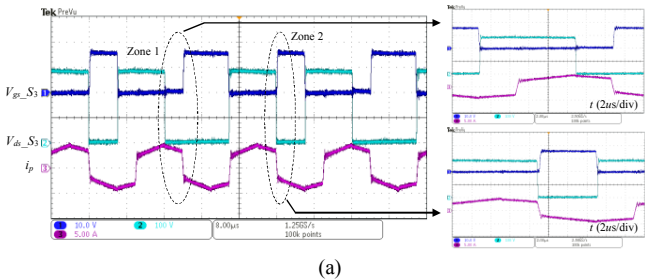
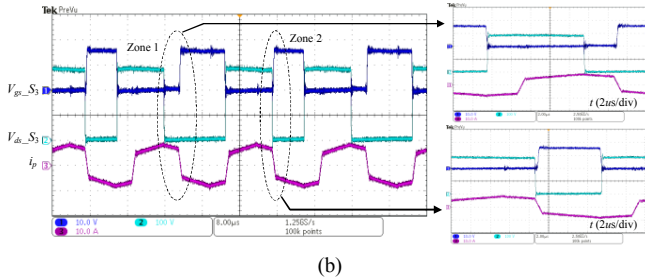


Fig. 9. Driving signal and drain-source voltage of switch S_1 , and primary current i_p . (a) at $V_{in} = 550$ V and $P_o = 500$ W. (b) at $V_{in} = 550$ V and $P_o = 1$ -kW.



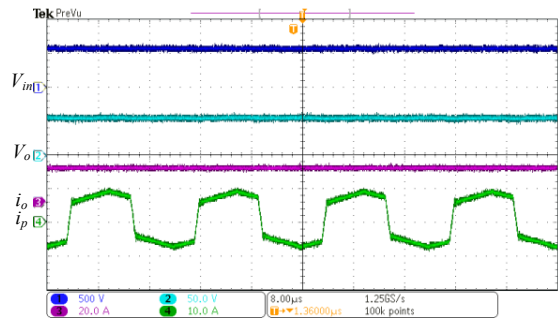
(a)



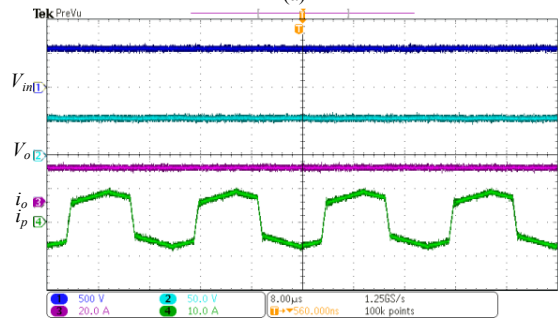
(b)

Fig. 10. Driving signal and drain-source voltage of switch S_3 , and primary current i_p . (a) at $V_{in} = 550$ V and $P_o = 500$ W. (b) at $V_{in} = 550$ V and $P_o = 1$ -kW.

Figs. 11 - 13 show the performances of the prototype under the working conditions that the input voltage V_{in} is 550 V and the output power namely P_o is 1-kW. Figs. 11(a) and (b) show the currents i_p , i_o and voltages V_{in} , V_o under the conventional control strategy and proposed control strategy, respectively. From Fig. 11, it can be seen that the primary currents i_p are almost the same under the two control strategies. Figs. 12(a) and (b) show the voltages on the two input capacitors V_1 , V_2 , the voltage on the DC-blocking capacitor V_{cb} , and current i_{c2} under the conventional and proposed control strategy, respectively. From Fig. 12, it can be observed that V_1 and V_2 are constant and balanced in the steady states under the two control strategies. The measured average values of the capacitor voltages V_1 and V_2 are both 271 V under the conventional control strategy, and they are both 273 V under the proposed control strategy. Fig. 13(a) shows that the currents through the two input capacitors i_{c1} and i_{c2} are imbalanced under the conventional control strategy, whose RMS values are 3.16 A, 5.18 A and average values are 125 mA, 160 mA. Therefore, the difference between the RMS values of i_{c1} and i_{c2} is 2.02 A under the conventional control strategy. Fig. 13(b) shows that under the proposed control i_{c1} and i_{c2} are kept same in every two switching periods as marked in Fig. 13(b), their RMS values are both 4.37 A and average values are 135 mA, 155 mA, which is consistent with the theoretical analysis in the Section IV.

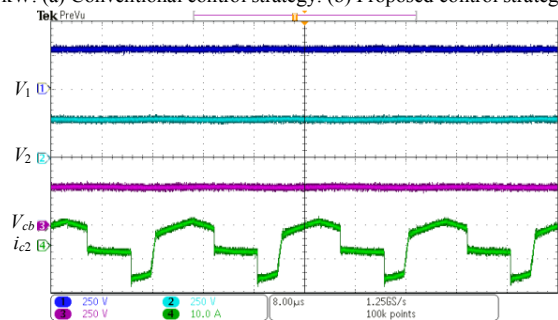


(a)

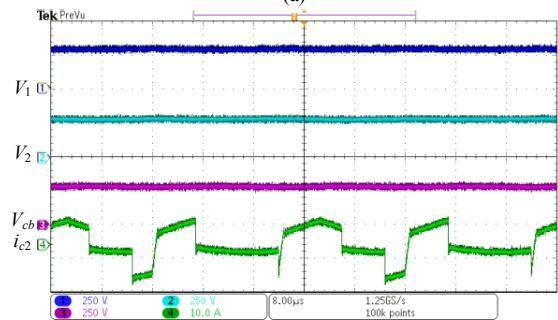


(b)

Fig. 11. Experimental results including V_{in} , V_o , i_o , and i_p at $V_{in} = 550$ V and $P_o = 1$ -kW. (a) Conventional control strategy. (b) Proposed control strategy.



(a)



(b)

Fig. 12. Experimental results including V_1 , V_2 , V_{cb} , and i_{c2} at $V_{in} = 550$ V and $P_o = 1$ -kW. (a) Conventional control strategy. (b) Proposed control strategy.

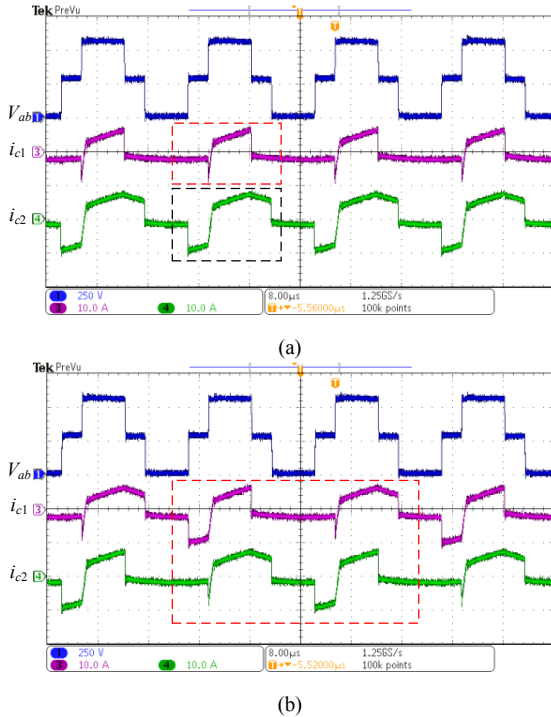


Fig. 13. Experimental results including V_{ab} , i_{c1} , and i_{c2} at $V_{in} = 550$ V and $P_o = 1$ -kW. (a) Conventional control strategy. (b) Proposed control strategy.

Fig. 14 shows the measured RMS values of i_{c1} and i_{c2} under various input voltages, where the output voltage is 50 V and the output power P_o is 1-kW. From Fig. 14, it can be seen that: 1) the RMS values of i_{c1} and i_{c2} are imbalanced under the conventional control strategy; 2) with the input voltage increasing, the current imbalance between the RMS values of i_{c1} and i_{c2} becomes larger under the conventional control strategy, and the biggest difference reaches 2.02 A while the input voltage increases to 550 V; 3) under the proposed control strategy, the RMS values of i_{c1} and i_{c2} are almost the same along with the input voltage increasing and range between the RMS values of i_{c1} and i_{c2} under the conventional control strategy; 4) the experimental results about the currents on the two input capacitors are consistent with the theoretical analysis in the Section IV-B. Based on the experimental results shown in Fig. 14, it can be concluded that the current imbalance among the two input capacitors in the four-switch HBTL DC/DC converter can be eliminated by utilizing the proposed control strategy.

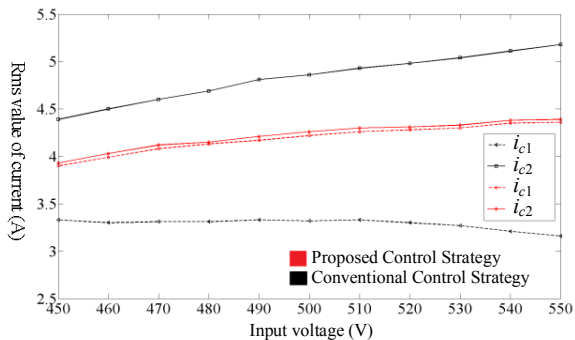


Fig. 14. Measured RMS values of i_{c1} and i_{c2} under various input voltages when $V_o = 50$ V and $P_o = 1$ -kW.

Fig. 15 shows the dynamic performance of the proposed control strategy. In Fig. 15, the output load changes from 1-kW to 500 W and finally gets back to 1-kW when the input voltage V_{in} is 550 V and output voltage V_o is 50 V. From Fig. 15, it can be observed that the voltages on the two input capacitors V_1 , V_2 and the voltage on the DC-blocking capacitor V_{cb} are all constant under the proposed control strategy when the load changes.

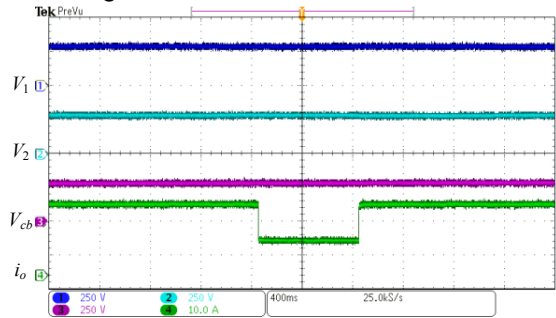


Fig. 15. Dynamic performance under load changes when $V_{in} = 550$ V and $V_o = 50$ V.

The measured efficiency curves with various input voltages (450 V, 500 V, and 550 V) are presented in Fig. 16 when the output voltage V_o is 50 V.

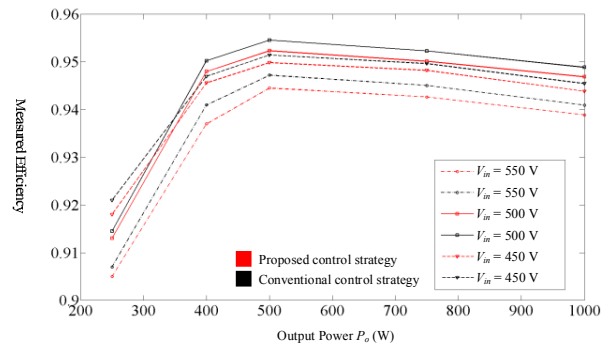


Fig. 16. Measured efficiency curves with various input voltages when $V_o = 50$ V.

The peak efficiency under the proposed control strategy is over 95%. With the input voltage V_{in} increasing while the output power is constant, 1) the conduction losses of the primary side would decrease because the input current would decrease; 2) the switching losses would increase because ZVS achievement conditions would become worse. Whether the efficiency of the converter would increase or decrease with the input voltage increasing is decided by the combination of 1) and 2). Therefore, the reason why the efficiency under 500 V is higher than that under 550 V in Fig. 16 is that the value of the increasing switching losses is higher than that of the decreasing conduction losses when the input voltage V_{in} changes from 500 V to 550 V. In addition, the efficiencies under the proposed control strategy are slightly lower than that under the conventional control strategy, whose reason is that MOSFET is used for the power switches in the built prototype. For MOSFET, the primary current i_p flows through the body diodes of the power switches instead of the power switches in the free-wheeling time under the proposed control, which would increase the conduction losses comparing with the

conventional control strategy. If the input voltage increases and IGBT is selected for the power switches, the efficiencies under the two control strategies would be almost the same.

VI. CONCLUSION

This paper proposes a ZVS PWM strategy and a capacitor current-balancing control for the HBTL DC/DC converter. Under the conventional control strategy, there exists a current imbalance among the two input capacitors in the four-switch HBTL DC/DC converter due to the effect from the output inductance of the input power supply and the inductance of the input line on the input current, which would make influence on the converter's reliability. The proposed ZVS PWM strategy is composed of two operation modes. Based on the proposed ZVS PWM strategy, a capacitor current-balancing control is proposed by alternating the two operation modes of the proposed PWM strategy, which can effectively eliminate the current imbalance among the two input capacitors. Therefore, the performance and reliability of the converter can be improved by balancing the thermal stresses and lifetimes among the two input capacitors. Finally, the simulation and experimental results verify the feasibility and effectiveness of the proposed control strategy.

APPENDIX

See Table II.

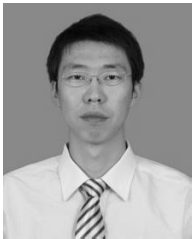
TABLE II
PARAMETERS OF THE SIMULATION MODEL AND EXPERIMENTAL PROTOTYPE

Description	Parameter
Power Switches $S_1 - S_4$	SPW47N60C3
Rectifier Diodes $D_{r1} - D_{r4}$	MBR40250TG
Turns Ratio of Transformer T_r	25 : 8
Leakage Inductance L_r (μH)	20.7
Output Filter Capacitor C_o (μF)	470
Output Filter Inductor L_o (μH)	140
Input Capacitors C_1 and C_2 (μF)	14.4
DC-blocking Capacitor C_b (μF)	12
Switching Frequency (kHz)	50
Dead Time (ns)	400
Input Inductance (μH) (Including the output inductance of the input power supply and inductance of the input line)	60

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