

WEAK STABILITY OF THE PLASMA-VACUUM INTERFACE PROBLEM

DAVIDE CATANIA^{1,2}, MARCELLO D'ABBICCO¹, PAOLO SECCHI¹

ABSTRACT. We consider the free boundary problem for the two-dimensional plasma-vacuum interface in ideal compressible magnetohydrodynamics (MHD). In the plasma region, the flow is governed by the usual compressible MHD equations, while in the vacuum region we consider the Maxwell system for the electric and the magnetic fields. At the free interface, driven by the plasma velocity, the total pressure is continuous and the magnetic field on both sides is tangent to the boundary.

We study the linear stability of rectilinear plasma-vacuum interfaces by computing the Kreiss–Lopatinskiĭ determinant of an associated linearized boundary value problem. Apart from possible resonances, we obtain that the piecewise constant plasma-vacuum interfaces are always weakly linearly stable, independently of the size of tangential velocity, magnetic and electric fields on both sides of the characteristic discontinuity.

We also prove that solutions to the linearized problem obey an energy estimate with a loss of regularity with respect to the source terms, both in the interior domain and on the boundary, due to the failure of the uniform Kreiss–Lopatinskiĭ condition, as the Kreiss–Lopatinskiĭ determinant associated with this linearized boundary value problem has roots on the boundary of the frequency space. In the proof of the a priori estimates, a crucial part is played by the construction of symmetrizers for a reduced differential system, which has poles at which the Kreiss–Lopatinskiĭ condition may fail simultaneously.

1. INTRODUCTION

Plasma-vacuum interface problems appear in the mathematical modeling of plasma confinement by magnetic fields in thermonuclear energy production (as in Tokamaks, Stellarators; see, e.g., [11]). There are also important applications in astrophysics, where the plasma-vacuum interface problem can be used for modeling the motion of a star or the solar corona when magnetic fields are taken into account.

In [17, 18], the authors obtained the local-in-time existence and uniqueness of solutions to the free boundary problem for the plasma-vacuum interface in ideal compressible magnetohydrodynamics (MHD), by considering the *pre-Maxwell dynamics* for the magnetic field in the vacuum region, as usually assumed in the classical formulation. The linearized stability of the relativistic case has been addressed by Trakhinin in [22], in the case of plasma expansion in vacuum. The paper [2] is devoted to the study of the linearized stability for the non-relativistic case, but, instead of the pre-Maxwell dynamics, in the vacuum region the displacement current was taken into account and the complete system of *Maxwell equations* for the electric and the magnetic fields was considered. The introduction of this model aims at investigating the influence of the electric field in vacuum on the well-posedness of the problem, as in the classical pre-Maxwell dynamics such an influence is hidden. See also [14] for a similar problem.

For the relativistic plasma-vacuum problem, Trakhinin [22] has shown the possible ill-posedness in the presence of a sufficiently strong vacuum electric field. Since relativistic effects play a rather passive role in the analysis of [22], it is natural to expect the same for the non-relativistic problem. On the

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contrary, in [2] it was shown that a *sufficiently weak* vacuum electric field precludes ill-posedness and gives the well-posedness of the linearized problem, thus somehow justifying the practice of neglecting the displacement current in the classical pre-Maxwell formulation when the vacuum electric field is weak enough.

In all the previously cited papers [2, 14, 17, 18, 22] the analysis is performed under a suitable stability condition stating that at each point of the free interface the magnetic fields on both sides are not parallel, see also [1, 4, 6, 19, 21] for the similar condition on current-vortex sheets. These works show that non-parallel magnetic fields may stabilize the motion. The main technical reason of why the stabilization occurs is that the non-collinearity of the magnetic fields is a sufficient condition for the ellipticity of the symbol of the boundary operator, namely the operator that is obtained from the boundary conditions and applies to the function describing the free interface, and this gives a control of the space-time gradient of such a function.

On the other hand, one could guess that the well-posedness could be guaranteed as well for problems without ellipticity of the boundary operator, and necessarily with less regularity of the free interface, provided a suitable stability condition is assumed.

In this regard, in the recent paper [23] Y. Trakhinin considered the three dimensional plasma-vacuum interface problem in the classical pre-Maxwell dynamics formulation with non-elliptic interface symbol. In [23] a basic L^2 a priori estimate was derived for the linearized problem with variable coefficients, in the case that the unperturbed plasma and vacuum magnetic fields are everywhere parallel on the interface, provided a Rayleigh-Taylor sign condition on the jump of the normal derivative of the total pressure is satisfied at each point of the interface. The general case when the plasma and vacuum magnetic fields are collinear somewhere on the interface, but not everywhere, is still an open problem.

In this paper we consider the two dimensional plasma-vacuum interface in ideal compressible magnetohydrodynamics (MHD). In the plasma region, the flow is governed by the usual compressible MHD equations, while in the vacuum region we consider the Maxwell system for the electric and the magnetic fields. At the free interface, driven by the plasma velocity, the total pressure is continuous and the magnetic field on both sides is tangent to the boundary. In particular, in two dimensions the magnetic fields obviously belong to the same plane, thus the condition that magnetic fields are tangential at the free boundary necessarily implies that they are parallel.

We study the linear stability of rectilinear plasma-vacuum interfaces by computing the Kreiss–Lopatinskiĭ determinant of an associated linearized boundary value problem. Apart from possible resonances, we obtain that the piecewise constant plasma-vacuum interfaces are *always* weakly linearly stable, independently of the size of tangential velocity, magnetic and electric fields on both sides of the characteristic discontinuity. In particular, violent instability never occurs.

In comparison with the possible ill-posedness in three dimensions in presence of a sufficiently strong vacuum electric field for the relativistic plasma-vacuum problem [22], and the similar result for the non-relativistic problem, our study shows that, even with parallel magnetic fields, the two-dimensional plasma-vacuum interfaces are more stable than the three-dimensional ones. This can be explained by noticing that in the two dimensional case the vacuum electric field has only one component $\mathcal{E} = \mathcal{E}_3$, orthogonal to the plane of motion, while the crucial role in the appearance of violent instability in the three dimensional case is played by the normal component \mathcal{E}_1 to the interface (which is zero by definition in the 2D case).

In the present paper we also prove that solutions to the linearized problem obey an energy estimate with a loss of regularity with respect to the source terms, both in the interior domain and on the boundary, due to the failure of the uniform Kreiss–Lopatinskiĭ condition.

It would be interesting to extend the normal modes analysis with the computation of the Kreiss–Lopatinskiĭ determinant to the three-dimensional problem, in order to get a complete description of the region of weak stability/instability. However, the great algebraic complexity makes it a very difficult task.

There are essential difficulties in the study of our problem. First, the problem of compressible plasma-vacuum interfaces is a nonlinear hyperbolic problem with a free boundary, since the interface is part of the unknowns; moreover, this free boundary is characteristic and we only expect a partial control of the trace of the solution, namely of the so-called noncharacteristic part of the solution.

When we take the Laplace transform of the solution with respect to time and the Fourier transform with respect to the tangential space variable, we obtain an ODE system only for the transform of the noncharacteristic part of the solution. As a consequence of the characteristic boundary, the symbol of the ODE has poles. The Kreiss–Lopatinskiĭ determinant associated to the ODE has no root in the interior of the frequency space (if this happened, the problem would be violently unstable, i.e. ill-posed), but it has some roots on the boundary and consequently the Kreiss–Lopatinskiĭ condition may only hold in weak form. An additional difficulty comes from the fact that some poles of the symbol coincide with the roots of the determinant. Under suitable restrictions on the basic state, such resonances are not allowed and the roots may be only simple. The case of multiple roots may typically occur at the transition to instability, see [7], and gives a loss of regularity of higher order in the a priori estimate.

Following the approach of [8], we prove the energy estimate of solutions to the linearized problem by the construction of a degenerate Kreiss symmetrizer associated with the reduced boundary value problem. However, here the situation is more complicated than for the two-dimensional compressible vortex sheets [8], because there are more poles and roots of the Kreiss–Lopatinskiĭ determinant, and they can coincide.

The paper is organized as follows. In Section 2 we give the formulation of the free boundary problem, the reduction to the fixed domain with flat boundary and its linearization. The main result of the paper is stated in Section 3. In Section 4 we apply to the problem the Laplace transform in the time variable and the Fourier transform in the tangential space variable. Then we eliminate the unknown front with the help of the ellipticity of the boundary conditions for the front. In Section 5 we reduce the linearized problem into a boundary value problem of the homogeneous ordinary differential equations, with respect to the normal space variable, for the noncharacteristic part of the solution. In Section 6 we compute the roots of the associated Kreiss–Lopatinskiĭ determinant and in Section 7 we construct the Kreiss symmetrizer for this boundary value problem, proceeding as in [3, 5, 8, 12, 16].

Special attention is required for the poles of the symbol of the reduced boundary value problem, which split in two categories: points that are poles of the symbol where the Lopatinskiĭ condition is satisfied, and points that are poles of the symbol and simultaneously roots of the Kreiss–Lopatinskiĭ determinant. To deal with the difficulty arising from these poles in the construction of symmetrizers, we use an approach inspired by Majda and Osher [15], as in [24]. Finally, in Section 8, we derive the energy estimates of solutions to the linearized problem by using the constructed symmetrizer.

2. FORMULATION OF THE PROBLEM

We consider the case when the whole space \mathbb{R}^2 is split into two regions by a smooth hypersurface $\Gamma(t) := \{(t, x_1, x_2) \in (0, \infty) \times \mathbb{R}^2 : F(t, x) = 0\} = \{x_1 = \varphi(t, x_2)\}$, and define $\Omega^\pm(t) := \{(t, x_1, x_2) \in (0, \infty) \times \mathbb{R}^2 : x_1 \gtrless \varphi(t, x_2)\}$. We assume the presence of ideal compressible plasma in $\Omega^+(t)$ and vacuum in $\Omega^-(t)$.

We assume that plasma is governed by the ideal compressible MHD system, that in 3D reads

$$(1) \quad \begin{cases} \rho_t + \operatorname{div}(\rho v) = 0, \\ \rho(\partial_t v + (v \cdot \nabla)v) - (H \cdot \nabla)H + \nabla q = 0, \\ \partial_t H - \nabla \times (v \times H) = 0, \\ \partial_t(\rho e + |H|^2/2) + \operatorname{div}((\rho e + p)v + H \times (v \times H)) = 0, \end{cases}$$

where ρ is the density, v and H are the velocity and (plasma) magnetic fields, $q = p + |H|^2/2$ is the total pressure, with p denoting the pressure. Moreover $e = E + |v|^2/2$ denotes the total energy, with E the internal energy. The subscript t denotes differentiation with respect to the time variable t . This system is supplemented by the divergence constraint

$$\operatorname{div} H = 0$$

on the initial data. Given state equations of gases $\rho = \rho(p, S)$ and $E = E(p, S)$, where S is the entropy, and the first principle of thermodynamics, (1) is a closed system.

Since we are interested in the 2D planar case, we assume that no variable depends on x_3 , so that the terms with ∂_3 are zero, and that $v_3 = H_3 = 0$. Choosing as unknown the vector $U = U(t, x) = (q, v, H, S)^\top$, the two dimensional version of the plasma system (1) can be written in symmetric form as (see [2, 17])

$$A_0(U)\partial_t U + \sum_{j=1}^2 A_j(U)\partial_j U = 0, \quad \text{in } \Omega^+(t),$$

where the explicit expressions of the matrices A_j 's are given below in (3)–(5). This system is symmetric hyperbolic provided that A_0 is positive definite, i.e. if $\rho > 0$ and $\rho_p := \partial_p \rho > 0$. In particular, if ρ is uniformly bounded away from 0 in $\Omega^+(t)$, this yields that the density has a jump across the interface, because it vanishes in the vacuum region.

In the vacuum region, the electric field \mathcal{E} and the magnetic field \mathcal{H} are governed by the Maxwell equations that, in a three dimensional domain, can be written in nondimensional form as (see [2, 14])

$$(2) \quad \begin{cases} \varepsilon \partial_t \mathcal{H} + \nabla \times \mathcal{E} = 0, & \varepsilon \partial_t \mathcal{E} - \nabla \times \mathcal{H} = 0, \\ \operatorname{div} \mathcal{H} = 0, & \operatorname{div} \mathcal{E} = 0, \quad \text{at } t = 0, \end{cases}$$

where \mathcal{E}, \mathcal{H} are the (vacuum) electric and magnetic fields, $\varepsilon := \bar{v}/c_L$, c_L is the speed of light, while \bar{v} is the velocity of a reference uniform flow, for instance the sound speed.

Again, in order to obtain the two dimensional version of the problem we are considering, we assume that no variable depends on x_3 and that $\mathcal{E}_1 = \mathcal{E}_2 = \mathcal{H}_3 = 0$ in $\Omega^-(t)$. As far as the vacuum is concerned, we apply a reflection with respect to x_1 (in particular, ∂_1 becomes $-\partial_1$) in order to have again equations that hold in $\Omega^+(t)$. Consequently, the system (2) reduces to

$$\begin{cases} \varepsilon \partial_t \mathcal{H}_1 + \partial_2 \mathcal{E}_3 = 0, & \text{in } \Omega^+(t), \\ \varepsilon \partial_t \mathcal{H}_2 + \partial_1 \mathcal{E}_3 = 0, \\ \varepsilon \partial_t \mathcal{E}_3 + \partial_1 \mathcal{H}_2 + \partial_2 \mathcal{H}_1 = 0. \end{cases}$$

As usual, the divergence constraint on \mathcal{H} is just a restriction on the initial data.

We assume that the unknown interface $\Gamma(t)$ moves according to the plasma velocity, i.e.

$$\frac{dF}{dt} = 0, \quad \text{on } \Gamma(t),$$

and that at the interface the total pressure is continuous, while the magnetic fields can manifest only a tangential discontinuity. In a three dimensional domain, such conditions can be written as

$$[q] = 0, \quad H \cdot N = 0, \quad \mathcal{H} \cdot N = 0, \quad N \times \mathcal{E} = \varepsilon(N \cdot v)\mathcal{H} \quad \text{on } \Gamma(t)$$

where $N = \nabla F$ and $[q] = q|_{\Gamma} - \frac{1}{2}|\mathcal{H}|_{\Gamma}^2 + \frac{1}{2}|\mathcal{E}|_{\Gamma}^2$ denotes the jump of the total pressure across the interface. For a discussion on the boundary conditions see [11].

Recalling the parametrization of $\Gamma(t) = \{x_1 = \varphi(t, x_2)\}$, we have $N = (1, -\varphi_2, 0)$, and in the two dimensional case, the boundary conditions become

$$\begin{aligned} \varphi_t = v_N = v_1 - \varphi_2 v_2, \quad [q] = 0, \quad 0 = H_N = H_1 - \varphi_2 H_2, \\ 0 = \mathcal{H}_N = \mathcal{H}_1 - \varphi_2 \mathcal{H}_2, \quad \mathcal{E}_3 + \varepsilon \varphi_t \mathcal{H}_2 = 0 \end{aligned}$$

(we are omitting $\varphi_2 \mathcal{E}_3 + \varepsilon \varphi_t \mathcal{H}_1 = 0$, since it can be obtained by summing the last two conditions, respectively multiplied by $\varepsilon \varphi_t$ and φ_2).

From now on, we neglect the third component of the vector functions v, H, \mathcal{H}, N , that now are vectors in \mathbb{R}^2 , while \mathcal{E} is a scalar function. Notice that, even if \mathcal{E} is a scalar, we write $\partial_j \mathcal{E}$ to denote derivatives in order to keep consistency with previous papers. Otherwise, subscripts denote components of vector quantities, but derivatives of scalar functions. Moreover, sometimes we will use the notation $\partial_0 = \partial_t$ to denote the partial derivative with respect to t .

Reduction to a fixed domain. In order to reduce the problem to a fixed domain with flat boundary, independent of time,

$$\Omega^+ := \mathbb{R}^2 \cap \{x_1 > 0\}, \quad \Gamma := \mathbb{R}^2 \cap \{x_1 = 0\},$$

we need the diffeomorphism provided by the following lemma.

Lemma 1. *Let $m \geq 3$ be an integer. For any $T > 0$, and for any*

$$\varphi \in \cap_{j=0}^{m-1} \mathcal{C}^j([0, T]; H^{m-j-\frac{1}{2}}(\mathbb{R})),$$

satisfying without loss of generality $\|\varphi\|_{\mathcal{C}([0, T]; H^2(\mathbb{R}))} \leq 1$, there exists a function

$$\Psi \in \cap_{j=0}^{m-1} \mathcal{C}^j([0, T]; H^{m-j}(\Omega^+))$$

such that the function

$$\Phi(t, x) := (x_1 + \Psi(t, x), x_2), \quad (t, x) \in [0, T] \times \Omega^+,$$

defines an H^m -diffeomorphism of Ω^+ for all $t \in [0, T]$. Moreover, there holds

$$\partial_t^j (\Phi - Id) \in \mathcal{C}([0, T]; H^{m-j}(\Omega^+))$$

for $j = 0, \dots, m-1$, $\Phi(t, 0, x_2) = (\varphi(t, x_2), x_2)$, $\partial_1 \Phi(t, 0, x_2) = (1, 0)$, as well as

$$\|\partial_t^j \Phi(t, \cdot)\|_{L^\infty(\Omega^+)} \leq \frac{1}{\sqrt{2\pi}} \|\partial_t^j \varphi(t, \cdot)\|_{H^{\frac{3}{2}}(\mathbb{R})} \quad t \in [0, T],$$

$$\|\Psi_1(t, \cdot)\|_{L^\infty(\Omega^+)} \leq \frac{1}{2} \quad t \in [0, T],$$

for $j = 1, \dots, m-2$.

Proof. See Appendix A. □

We introduce a change of variables by setting

$$\tilde{U}(t, x) := U(t, \Phi(t, x)), \quad \tilde{\mathcal{H}}(t, x) := \mathcal{H}(t, \Phi(t, x)), \quad \tilde{\mathcal{E}}(t, x) := \mathcal{E}(t, \Phi(t, x));$$

then, we conveniently drop the tilde sign. The (reflected) vacuum equations, in Ω^+ , become

$$\begin{cases} \varepsilon \partial_t \mathcal{H}_1 + \partial_2 \mathcal{E} - \frac{1}{1+\Psi_1} (\varepsilon \Psi_t \partial_1 \mathcal{H}_1 + \Psi_2 \partial_1 \mathcal{E}) = 0, \\ \varepsilon \partial_t \mathcal{H}_2 - \frac{1}{1+\Psi_1} (\varepsilon \Psi_t \partial_1 \mathcal{H}_2 - \partial_1 \mathcal{E}) = 0, \\ \varepsilon \partial_t \mathcal{E} + \partial_2 \mathcal{H}_1 - \frac{1}{1+\Psi_1} (\varepsilon \Psi_t \partial_1 \mathcal{E} - \partial_1 \mathcal{H}_2 + \Psi_2 \partial_1 \mathcal{H}_1) = 0. \end{cases}$$

Setting $\mathcal{W} = (\mathcal{H}_1, \mathcal{H}_2, \mathcal{E})^\top$, the previous equations can be written as a symmetric system:

$$\varepsilon \partial_t \mathcal{W} + B_1(\Psi) \partial_1 \mathcal{W} + B_2 \partial_2 \mathcal{W} = 0,$$

where

$$B_1(\Psi) = -\frac{1}{1+\Psi_1} \begin{pmatrix} \varepsilon \Psi_t & 0 & \Psi_2 \\ 0 & \varepsilon \Psi_t & -1 \\ \Psi_2 & -1 & \varepsilon \Psi_t \end{pmatrix}, \quad B_2 = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}.$$

As for plasma, we have $U = (q, v_1, v_2, H_1, H_2, S)^\top$ that satisfies, before the change of variables,

$$\sum_{j=0,1,2} A_j(U) \partial_j U = 0,$$

where

$$(3) \quad A_0(U) = \begin{pmatrix} \rho_p/\rho & 0 & 0 & -H_1 \rho_p/\rho & -H_2 \rho_p/\rho & 0 \\ 0 & \rho & 0 & 0 & 0 & 0 \\ 0 & 0 & \rho & 0 & 0 & 0 \\ -H_1 \rho_p/\rho & 0 & 0 & 1 + H_1^2 \rho_p/\rho & H_1 H_2 \rho_p/\rho & 0 \\ -H_2 \rho_p/\rho & 0 & 0 & H_1 H_2 \rho_p/\rho & 1 + H_2^2 \rho_p/\rho & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix},$$

$$(4) \quad A_1(U) = \begin{pmatrix} v_1 \rho_p/\rho & 1 & 0 & -H_1 v_1 \rho_p/\rho & -H_2 v_1 \rho_p/\rho & 0 \\ 1 & \rho v_1 & 0 & -H_1 & 0 & 0 \\ 0 & 0 & \rho v_1 & 0 & -H_1 & 0 \\ -H_1 v_1 \rho_p/\rho & -H_1 & 0 & (1 + H_1^2 \rho_p/\rho) v_1 & H_1 H_2 v_1 \rho_p/\rho & 0 \\ -H_2 v_1 \rho_p/\rho & 0 & -H_1 & H_1 H_2 v_1 \rho_p/\rho & (1 + H_2^2 \rho_p/\rho) v_1 & 0 \\ 0 & 0 & 0 & 0 & 0 & v_1 \end{pmatrix},$$

$$(5) \quad A_2(U) = \begin{pmatrix} v_2 \rho_p/\rho & 0 & 1 & -H_1 v_2 \rho_p/\rho & -H_2 v_2 \rho_p/\rho & 0 \\ 0 & \rho v_2 & 0 & -H_2 & 0 & 0 \\ 1 & 0 & \rho v_2 & 0 & -H_2 & 0 \\ -H_1 v_2 \rho_p/\rho & -H_2 & 0 & (1 + H_1^2 \rho_p/\rho) v_2 & H_1 H_2 v_2 \rho_p/\rho & 0 \\ -H_2 v_2 \rho_p/\rho & 0 & -H_2 & H_1 H_2 v_2 \rho_p/\rho & (1 + H_2^2 \rho_p/\rho) v_2 & 0 \\ 0 & 0 & 0 & 0 & 0 & v_2 \end{pmatrix}.$$

After changing the variables and removing the tilde from \tilde{U} , we have

$$\sum_{j=0,2} A_j(U) \partial_j U + \tilde{A}_1(U) \partial_1 U = 0, \quad \tilde{A}_1 = \frac{1}{1+\Psi_1} (A_1 - \Psi_t A_0 - \Psi_2 A_2).$$

Linearization. We linearize the problem about a piecewise constant basic state $\dot{U} = (\dot{q}, \dot{v}, \dot{H}, \dot{S})$, denoted by a dot sign, with $\dot{\varphi} = 0$, so that we can take $\dot{\Psi} = 0$. Consequently, $\dot{N} = (1, 0)$ and $\dot{v}_N = v_1 = 0$, since $\dot{\varphi}_t = 0$. We obtain:

$$\dot{H}_1 \equiv \dot{H}_N = 0, \quad \dot{\mathcal{H}}_1 \equiv \dot{\mathcal{H}}_N = 0, \quad \dot{\mathcal{E}} = -\varepsilon \dot{\varphi}_t \dot{\mathcal{H}}_2 = 0.$$

To summarize,

$$\dot{\varphi} = 0, \quad \dot{N} = (1, 0), \quad \dot{v} = (0, \dot{v}_2), \quad \dot{H} = (0, \dot{H}_2), \quad \dot{\mathcal{H}} = (0, \dot{\mathcal{H}}_2), \quad \dot{\mathcal{E}} = 0.$$

To simplify notations, from now on we will omit subscripts in $\dot{v}_2, \dot{H}_2, \dot{\mathcal{H}}_2$, and we will denote by \dot{U} the variable $\dot{U} = (\dot{q}, \dot{v}_2, \dot{H}_2, \dot{S}) = (\dot{q}, \dot{v}, \dot{H}, \dot{S}) \in \mathbb{R}^4$. We denote by $\dot{\rho}$ the corresponding value of the density, $\dot{\rho} = \rho(\dot{q} - \dot{H}_2^2/2, \dot{S})$, and with \dot{c} the sound speed defined by $\dot{c} = \sqrt{p'_\rho(\dot{\rho}, \dot{S})}$.

After the linearization, the system for \mathcal{W} in Ω^+ becomes

$$\varepsilon \partial_t \mathcal{W} + B_1 \partial_1 \mathcal{W} + B_2 \partial_2 \mathcal{W} = 0,$$

where

$$B_1 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}, \quad B_2 = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}.$$

The system for U is instead

$$\sum_{j=0,1,2} A_j(\dot{U}) \partial_j U = 0,$$

where, setting $\dot{\alpha} := (\dot{\rho} \dot{c}^2)^{-1}$, we have

$$A_0(\dot{U}) = \begin{pmatrix} \dot{\alpha} & 0 & 0 & 0 & -\dot{\alpha} \dot{H} & 0 \\ 0 & \dot{\rho} & 0 & 0 & 0 & 0 \\ 0 & 0 & \dot{\rho} & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ -\dot{\alpha} \dot{H} & 0 & 0 & 0 & 1 + \dot{\alpha} \dot{H}^2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix},$$

$$A_1(\dot{U}) = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix},$$

$$A_2(\dot{U}) = \begin{pmatrix} \dot{\alpha} \dot{v} & 0 & 1 & 0 & -\dot{\alpha} \dot{v} \dot{H} & 0 \\ 0 & \dot{\rho} \dot{v} & 0 & -\dot{H} & 0 & 0 \\ 1 & 0 & \dot{\rho} \dot{v} & 0 & -\dot{H} & 0 \\ 0 & -\dot{H} & 0 & \dot{v} & 0 & 0 \\ -\dot{\alpha} \dot{v} \dot{H} & 0 & -\dot{H} & 0 & (1 + \dot{\alpha} \dot{H}^2) \dot{v} & 0 \\ 0 & 0 & 0 & 0 & 0 & \dot{v} \end{pmatrix}.$$

Observe that the equation for the entropy can now be decoupled from the system, since the coefficients depend just on the basic state:

$$S_t + \dot{v} S_2 = 0.$$

From now on, we will omit the component S in U , and will consider the new variable

$$U = (q, v_1, v_2, H_1, H_2)^\top \in \mathbb{R}^5$$

(for simplicity, we keep the same notation U). Similarly, $A_j(\dot{U})$ will denote the 5×5 north-west block in the previous matrices, while \dot{U} is still the element of \mathbb{R}^4 written above.

The linearized boundary conditions are

$$(6) \quad \varphi_t = v_1 - \dot{v} \varphi_2 + g_1, \quad q = \dot{\mathcal{H}} \mathcal{H}_2 + g_2, \quad \mathcal{E} = -\varepsilon \dot{\mathcal{H}} \varphi_t + g_3$$

(the other conditions, i.e. the normal components of the magnetic fields equal to zero, can be recovered by imposing them at the initial time).

We set $V = (U, \mathcal{W})^\top$ and distinguish between characteristic (V^c) and noncharacteristic (V^{nc}) variables

$$V^c = (v_2, H_1, H_2, \mathcal{H}_1), \quad V^{\text{nc}} = (q, v_1, \mathcal{H}_2, \mathcal{E}).$$

Notice that characteristic variables do not appear in the boundary conditions. If we define

$$\begin{aligned} \mathcal{L} &= \begin{pmatrix} \sum_{j=0,1,2} A_j(\dot{U})\partial_j & 0 \\ 0 & \varepsilon\partial_t + B_1\partial_1 + B_2\partial_2 \end{pmatrix} \equiv \sum_{j=0,1,2} A_j(\dot{U})\partial_j, \\ M &= \begin{pmatrix} 0 & -1 & 0 & 0 \\ 1 & 0 & -\dot{\mathcal{H}} & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}, \quad b(\partial_t, \partial_2) = \begin{pmatrix} \partial_t + \dot{v}\partial_2 \\ 0 \\ \varepsilon\dot{\mathcal{H}}\partial_t \end{pmatrix}, \\ \Omega &= \mathbb{R} \times \Omega^+, \quad \omega = \mathbb{R} \times \Gamma, \end{aligned}$$

the inhomogeneous linearized problem can be written as

$$(7) \quad \mathcal{L}V = f, \quad \text{in } \Omega$$

$$(8) \quad \mathcal{B}(V^{\text{nc}}, \varphi) := MV^{\text{nc}} + b\varphi = g, \quad \text{on } \omega.$$

3. MAIN RESULTS

First, we define some function spaces and the corresponding norms.

Definition 1. For every $s \geq 0$ and $\gamma \geq 1$, we set

$$H_\gamma^s(\mathbb{R}^2) := \{u \in \mathcal{D}'(\mathbb{R}_{t,x_2}^2) : e^{-\gamma t}u \in H^s(\mathbb{R}_{t,x_2}^2)\},$$

with (equivalent) norm

$$\|u\|_{H_\gamma^s(\mathbb{R}^2)}^2 := \|e^{-\gamma t}u\|_{s,\gamma}^2, \quad \|v\|_{s,\gamma} := \int_{\mathbb{R}^2} (\gamma^2 + \delta^2 + \eta^2)^s |\hat{v}(\delta, \eta)|^2 d\delta d\eta,$$

where \hat{v} is the Fourier transform of v and δ, η are the dual variables of t, x_2 .

We also define $L^2((0, \infty), H_\gamma^s(\mathbb{R}^2))$, briefly denoted by $L^2(H_\gamma^s)$, as the space of distributions with finite $L^2(H_\gamma^s)$ -norm, where

$$\|u\|_{L^2(H_\gamma^s)}^2 := \int_0^\infty \|u(\cdot, x_1, \cdot)\|_{H_\gamma^s(\mathbb{R}^2)}^2 dx_1,$$

and set

$$\|v\|_{0,s,\gamma}^2 := \int_0^\infty \|v(\cdot, x_1, \cdot)\|_{s,\gamma}^2 dx_1.$$

Finally, we set $L_\gamma^2(\mathbb{R}^2) = H_\gamma^0(\mathbb{R}^2)$ and $L_\gamma^2(\Omega) = L^2(H_\gamma^0)$. Notice that $\|u\|_{L^2(H_\gamma^s)} = \|e^{-\gamma t}u\|_{0,s,\gamma}$ and $\|u\|_{L_\gamma^2} = \|e^{-\gamma t}u\|_{L^2}$.

Assumptions on the basic state. We assume:

$$(9) \quad \dot{v} \neq 0, \quad \dot{\mathcal{H}} \neq 0,$$

$$(10) \quad \dot{\rho} > 0, \quad \dot{H} \neq 0,$$

$$(11) \quad \dot{\alpha}\dot{H}^2 \neq 1,$$

$$(12) \quad |\dot{v}| \neq \frac{|\dot{H}|}{\sqrt{\dot{\rho}}},$$

$$(13) \quad |\dot{v}| \neq \frac{|\dot{H}|}{\sqrt{\dot{\rho}(1 + \dot{\alpha}\dot{H}^2)}},$$

$$(14) \quad \dot{\rho}v^2 \neq \frac{\dot{\alpha}(\dot{H}^4 - \dot{\mathcal{H}}^4) + 2\dot{H}^2 \pm \sqrt{\dot{\alpha}^2(\dot{H}^4 - \dot{\mathcal{H}}^4)^2 + 4\dot{H}^4}}{2(1 + \dot{\alpha}\dot{H}^2)} \quad \text{if} \quad \dot{H}^2 < \min\{\dot{\alpha}^{-1}, \dot{\rho}v^2\},$$

where (11) and (12) respectively mean that the sound speed \dot{c} and the velocity \dot{v} do not coincide with the Alfvén velocity $|\dot{H}|/\sqrt{\dot{\rho}}$.

The usefulness of these conditions will be clear in the following, but we observe immediately that they avoid trivial cases (vanishing velocity or magnetic fields) and prevent the appearance of resonances, i.e. multiple roots of the Lopatinskiĭ determinant (see Section 6; (14) corresponds to (47)).

The main result that we obtain can be stated as follows.

Theorem 1. *Assume that the conditions (9)–(14) on the basic state are satisfied.*

Then there exist constants $\varepsilon_0 > 0, C > 0$ such that, for every $0 < \varepsilon < \varepsilon_0, \gamma \geq 1$ and every function $(V, \varphi) \in H_\gamma^2(\Omega) \times H_\gamma^2(\Gamma)$, there holds the estimate

$$\gamma \|V\|_{L_\gamma^2(\Omega)}^2 + \|V_{x_1=0}^{\text{nc}}\|_{L_\gamma^2(\Gamma)}^2 + \|\varphi\|_{H_\gamma^1(\Gamma)}^2 \leq C \left(\frac{1}{\gamma^3} \|\mathcal{L}V\|_{L^2(H_\gamma^1)}^2 + \frac{1}{\gamma^2} \|\mathcal{B}(V^{\text{nc}}, \varphi)\|_{H_\gamma^1(\Gamma)}^2 \right).$$

Now, for any $\gamma \geq 1$, let us define

$$\mathcal{L}^\gamma := \mathcal{L} + \gamma \mathcal{A}_0, \quad b^\gamma(\partial_t, \partial_2) := b(\partial_t + \gamma, \partial_2), \quad \mathcal{B}^\gamma(V^{\text{nc}}, \varphi) := MV^{\text{nc}} + b^\gamma \varphi = g.$$

It is easily shown that Theorem 1 admits the following equivalent proposition.

Proposition 2. *Assume that the conditions (9)–(14) on the basic state are satisfied.*

Then there exist constants $\varepsilon_0 > 0, C > 0$ such that, for every $0 < \varepsilon < \varepsilon_0, \gamma \geq 1$ and every function $(V, \varphi) \in H^2(\Omega) \times H^2(\Gamma)$, there holds the estimate

$$(15) \quad \gamma \|V\|_{L^2(\Omega)}^2 + \|V_{x_1=0}^{\text{nc}}\|_{L^2(\Gamma)}^2 + \|\varphi\|_{H^1(\Gamma)}^2 \leq C \left(\frac{1}{\gamma^3} \|\mathcal{L}^\gamma V\|_{0,1,\gamma}^2 + \frac{1}{\gamma^2} \|\mathcal{B}^\gamma(V^{\text{nc}}, \varphi)\|_{1,\gamma}^2 \right).$$

The rest of the paper is devoted to the proof of Theorem 1 in the equivalent form of Proposition 2.

4. SOME REDUCTIONS

Partial homogenization. As in [8, 15], in order to prove (15) we first remove the forcing term f in $\mathcal{L}^\gamma V = f$. Given $(V, \varphi) \in H^2(\Omega) \times H^2(\Gamma)$, set $f := \mathcal{L}^\gamma V \in H^1(\Omega), g := \mathcal{B}^\gamma(V^{\text{nc}}, \varphi) \in H^1(\Gamma)$ and consider the auxiliary problem

$$\begin{cases} \mathcal{L}^\gamma V_1 = f, & x_1 > 0, \\ M^{\text{aux}} V_1^{\text{nc}} = 0, & x_1 = 0, \end{cases}$$

where

$$M^{\text{aux}} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix},$$

which corresponds to the boundary conditions $q = 0$ and $\mathcal{E} = 0$. Hence, if $V_1 = (U, \mathcal{W})^\top$, at the boundary we have $A_1 U \cdot U = 2qv_1 = 0$ and $B_1 \mathcal{W} \cdot \mathcal{W} = 2\mathcal{E}\mathcal{H}_2 = 0$, so that the boundary matrix $-\mathcal{A}_1(\dot{U})$ made of A_1 and B_1 is nonnegative. Moreover, it is maximally nonnegative, since both A_1 and B_1 have exactly one positive ($\lambda = 1$) and one negative ($\lambda = -1$) eigenvalue, while the other ones equal zero. This means that the stable subspace (corresponding to the negative eigenvalues) has dimension 2, which is the correct dimension that provides maximality.

Since the boundary conditions are maximally dissipative, the standard theory for hyperbolic systems [13] guarantees the existence of a unique solution $V_1 \in L^2(\mathbb{R}^+; H^1(\Gamma))$ of the problem above, with trace of V_1^{nc} in $H^1(\Gamma)$ and

$$(16) \quad \gamma \|V_1\|_{L^2(\Omega)}^2 \leq \frac{C}{\gamma} \|f\|_{L^2(\Omega)}^2, \quad \|V_1^{\text{nc}}|_{x_1=0}\|_{1,\gamma}^2 \leq \frac{C}{\gamma} \|f\|_{0,1,\gamma}^2.$$

We obtain that $V_2 := V - V_1$ satisfies the system

$$\begin{cases} \mathcal{L}^\gamma V_2 = 0, & x_1 > 0, \\ \mathcal{B}^\gamma(V_2^{\text{nc}}, \varphi) = g - MV_1^{\text{nc}}|_{x_1=0} & x_1 = 0, \end{cases}$$

where

$$(17) \quad \|g - MV_1^{\text{nc}}|_{x_1=0}\|_{1,\gamma}^2 \leq 2\|g\|_{1,\gamma}^2 + \frac{C}{\gamma}\|f\|_{0,1,\gamma}^2.$$

Consequently, it will be sufficient to prove (15) in the case $\mathcal{L}^\gamma V = 0$. By abuse of notation, we continue to write g for $g - MV_1^{\text{nc}}|_{x_1=0}$ and V for V_2 .

Eliminating the front. We proceed as in [8]. We perform a Fourier transform with respect to the variables t, x_2 , whose dual variables will be δ, η , of

$$\mathcal{L}^\gamma V = 0, \quad MV^{\text{nc}} + b^\gamma \varphi = g.$$

Setting

$$\tau = \gamma + i\delta,$$

we obtain

$$(18) \quad \begin{cases} (\tau \mathcal{A}_0 + i\eta \mathcal{A}_2 + \mathcal{A}_1 \frac{d}{dx_1}) \widehat{V} = 0 & x_1 > 0, \\ M\widehat{V}^{\text{nc}}(\delta, 0, \eta) + b(\tau, i\eta) \widehat{\varphi}(\delta, \eta) = \widehat{g}(\delta, \eta) & x_1 = 0, \end{cases}$$

where

$$b(\tau, i\eta) = \begin{pmatrix} \tau + i\dot{v}\eta \\ 0 \\ \varepsilon \dot{\mathcal{H}} \tau \end{pmatrix},$$

which is homogeneous of degree 1 with respect to (τ, η) . In order to take into account homogeneity, we consider the hemisphere

$$\Sigma = \{(\tau, \eta) \in \mathbb{C} \times \mathbb{R} : |\tau|^2 + \eta^2 = 1, \operatorname{Re} \tau \geq 0\},$$

and set

$$\Xi = \{(\gamma, \delta, \eta) \in [0, +\infty) \times \mathbb{R}^2\} \setminus \{(0, 0, 0)\} = (0, +\infty) \cdot \Sigma$$

(essentially, we are partitioning the halfspace Ξ using hemispheres with radius $r \in (0, +\infty)$). Notice that the symbol $b(\tau, i\eta)$ is elliptic, i.e. it is always different from zero on Σ .

We set $k = \sqrt{|\tau|^2 + \eta^2}$ and define, in Ξ ,

$$(19) \quad Q = \frac{1}{k} \begin{pmatrix} 0 & k & 0 \\ -\varepsilon \dot{\mathcal{H}} \tau & 0 & \tau + i\dot{v}\eta \\ \bar{\tau} - i\dot{v}\eta & 0 & \varepsilon \dot{\mathcal{H}} \bar{\tau} \end{pmatrix},$$

where the bar sign denotes complex conjugation, so that $Q \in \mathcal{C}^\infty(\Xi, GL_3(\mathbb{C}))$ is homogeneous of degree 0 in (τ, η) and $Q(\tau, \eta)b(\tau, i\eta) = (0, 0, \theta(\tau, \eta))$ is homogeneous of degree 1, with

$$\theta(\tau, \eta) = k^{-1}|b(\tau, i\eta)|^2, \quad \min_{\Sigma} |\theta(\tau, \eta)| > 0,$$

since the third line of Q is $k^{-1}\bar{b}(\tau, i\eta)^\top$. More precisely, on Σ (where $k = 1$), we have

$$\theta(\tau, \eta) = (1 + \varepsilon^2 \dot{\mathcal{H}}^2)|\tau|^2 + \dot{v}^2 \eta^2 + 2\dot{v}\eta\delta = \gamma^2 + \varepsilon^2 \dot{\mathcal{H}}^2|\tau|^2 + (\delta + \dot{v}\eta)^2,$$

which is zero if and only if

$$\begin{cases} \gamma = 0, \\ \dot{\mathcal{H}}^2 \delta^2 = 0, \\ \delta = -\dot{v}\eta; \end{cases}$$

thanks to (9), $\theta > 0$ on Σ .

From the boundary conditions in (18) we have

$$(20) \quad \begin{pmatrix} 0 \\ 0 \\ \theta(\tau, \eta) \end{pmatrix} \widehat{\varphi}(\delta, \eta) + \begin{pmatrix} \beta(\tau, \eta) \\ \ell(\tau, \eta) \end{pmatrix} \widehat{V}^{\text{nc}}(\delta, 0, \eta) = Q(\tau, \eta) \widehat{g}(\delta, \eta),$$

where β is a 2×4 matrix and ℓ is a covector in \mathbb{R}^4 such that

$$Q(\tau, \eta)M = \begin{pmatrix} \beta(\tau, \eta) \\ \ell(\tau, \eta) \end{pmatrix}.$$

From now on, we assume to work on Σ , where $k = 1$ (otherwise the first line of β below has to be multiplied by k), and we have

$$\begin{aligned} \det Q &= \varepsilon^2 \dot{\mathcal{H}}^2 |\tau|^2 + |\tau + i\dot{v}\eta|^2 = |b(\tau, i\eta)|^2, \\ \theta(\tau, \eta) &= |b(\tau, i\eta)|^2, \\ \beta &= \begin{pmatrix} 1 & 0 & -\dot{\mathcal{H}} & 0 \\ 0 & \varepsilon \dot{\mathcal{H}} \tau & 0 & \tau + i\dot{v}\eta \end{pmatrix}, \\ \ell &= (0 \quad -\bar{\tau} + i\dot{v}\eta \quad 0 \quad \varepsilon \dot{\mathcal{H}} \bar{\tau}). \end{aligned}$$

The third line of (20) is

$$\theta(\tau, \eta) \widehat{\varphi} + \ell(\tau, \eta) \widehat{V}^{\text{nc}}(0) = \bar{b}(\tau, i\eta)^\top \widehat{g}.$$

Now, we proceed as in [8]. From the ellipticity of b and the uniform boundedness of ℓ and b , we obtain

$$k^2 |\widehat{\varphi}|^2 \leq C (|\widehat{V}^{\text{nc}}(0)|^2 + |\widehat{g}|^2)$$

in Ξ . Integrating over $(\delta, \eta) \in \mathbb{R}^2$ and using Plancherel's Theorem, we deduce

$$(21) \quad \|\varphi\|_{1, \gamma}^2 \leq C \left(\|V_{x_1=0}^{\text{nc}}\|_{L^2(\mathbb{R}^2)}^2 + \frac{1}{\gamma^2} \|g\|_{1, \gamma}^2 \right).$$

Consequently, in order to prove Proposition 2, it is sufficient to consider

$$(22) \quad \left(\tau \mathcal{A}_0 + i\eta \mathcal{A}_2 + \mathcal{A}_1 \frac{d}{dx_1} \right) \widehat{V} = 0 \quad x_1 > 0,$$

$$(23) \quad \beta(\tau, \eta) \widehat{V}^{\text{nc}} = Q(\tau, \eta) \widehat{g} \quad x_1 = 0,$$

neglecting the front term in the boundary condition.

Lemma 3. *Assume that there exists a positive constant C such that the solution of (22), (23) fulfills the estimate*

$$(24) \quad \|V_{x_1=0}^{\text{nc}}\|_{L^2(\mathbb{R}^2)}^2 \leq \frac{C}{\gamma^2} \|g\|_{1, \gamma}^2.$$

Then the thesis of Propositions 2 is satisfied.

Proof. We recall that all matrices \mathcal{A}_j are symmetric and that \mathcal{A}_0 is positive definite. Taking the scalar product of (22) with \widehat{V} and integrating yields the following inequality

$$(25) \quad \gamma \|V\|_{L^2(\Omega)}^2 \leq C \|V_{x_1=0}^{\text{nc}}\|_{L^2(\mathbb{R}^2)}^2.$$

Combining (16), (17), (21) with (24), (25) gives (15). \square

Therefore, for the derivation of the estimate (15) it is sufficient to get an estimate of the trace of \widehat{V}^{nc} on $x_1 = 0$ of the form (24).

5. NORMAL MODES ANALYSIS

We begin by distinguishing a few cases, since each one needs a different analysis. We recall that $\tau = \gamma + i\delta$ and set

$$\mu := \tau + i\dot{v}\eta.$$

We introduce the following cases:

$$(P1) \quad \mu = 0, \quad \text{i.e.} \quad \gamma = 0 \quad \text{and} \quad \delta = -\dot{v}\eta \quad (\eta \neq 0);$$

$$(P2) \quad \gamma = 0 \quad \text{and} \quad \delta = -\dot{v}\eta \pm \frac{\dot{H}}{\sqrt{\dot{\rho}(1 + \dot{\alpha}\dot{H}^2)}} \eta \quad (\eta \neq 0);$$

$$(P3) \quad \tau = 0, \quad \text{i.e.} \quad \gamma = 0 \quad \text{and} \quad \delta = 0 \quad (\eta \neq 0);$$

$$(P0) \quad \text{all other possibilities.}$$

Notice that, in (P1)–(P3), we always have $\eta \neq 0$, since $\eta = 0$ would imply also $\delta = 0$ and hence $(\gamma, \delta, \eta) = (0, 0, 0) \notin \Sigma$.

Moreover, these three cases are mutually exclusive, thanks to the hypotheses on the basic state. Actually, (P1) and (P2) would coincide only if $\eta = 0$, since by assumption $\dot{H} \neq 0$. Similarly, (P1) and (P3) can not hold at the same time (using $\dot{v} \neq 0$), while (P2) and (P3) coincide if and only if

$$\dot{v} = \pm \frac{\dot{H}}{\sqrt{\dot{\rho}(1 + \dot{\alpha}\dot{H}^2)}},$$

which is prevented thanks to (13).

In this section, we consider only (P0): the other cases correspond to poles for the symbol $\mathcal{A}(\tau, \eta)$ in (40) and will be handled later on (see Subsections 7.9, 7.7, 7.8), see also Remark 1.

We introduce the following quantities, whose meaning and relevance will be clear from the following computations:

$$(26) \quad a_{12}(\tau, \eta) = -\frac{\mu^2 \dot{\rho} + \eta^2 \dot{H}^2}{\mu}, \quad a_{21}(\tau, \eta) = -\frac{\mu(\dot{\alpha}\dot{\rho}\mu^2 + \eta^2)}{(\mu^2 \dot{\rho}\dot{\alpha} + \eta^2)\dot{H}^2 + \mu^2 \dot{\rho}},$$

$$(27) \quad a_{34}(\tau, \eta) = -\frac{\varepsilon^2 \tau^2 + \eta^2}{\varepsilon \tau}, \quad a_{43}(\tau, \eta) = -\varepsilon \tau.$$

From the plasma part of (22), we obtain the following algebraic equations:

$$\begin{aligned} \tau \dot{\rho} \hat{v}_2 + i\eta(\hat{q} + \dot{\rho} \hat{v}_2 - \dot{H} \hat{H}_2) &= 0, \\ \tau \hat{H}_1 + i\eta(-\dot{H} \hat{v}_1 + \dot{v} \hat{H}_1) &= 0, \\ \tau(-\dot{\alpha} \dot{H} \hat{q} + (1 + \dot{\alpha} \dot{H}^2) \hat{H}_2) + i\eta(-\dot{\alpha} \dot{v} \dot{H} \hat{q} - \dot{H} \hat{v}_2 + (1 + \dot{\alpha} \dot{H}^2) \dot{v} \hat{H}_2) &= 0, \end{aligned}$$

or

$$(28) \quad \mu \dot{\rho} \hat{v}_2 + i\eta(\hat{q} - \dot{H} \hat{H}_2) = 0,$$

$$(29) \quad \mu \hat{H}_1 - i\eta \dot{H} \hat{v}_1 = 0,$$

$$(30) \quad \mu(-\dot{\alpha} \dot{H} \hat{q} + (1 + \dot{\alpha} \dot{H}^2) \hat{H}_2) - i\eta \dot{H} \hat{v}_2 = 0.$$

Since we are not in (P1), from (29) we obtain

$$(31) \quad \hat{H}_1 = i \frac{\eta}{\mu} \dot{H} \hat{v}_1.$$

Multiplying (28) by $i\eta\dot{H}$ and adding (30) multiplied by $\mu\dot{\rho}$, we have

$$\begin{aligned}\mu\dot{\rho}\widehat{v}_2 + i\eta(\widehat{q} - \dot{H}\widehat{H}_2) &= 0, \\ \mu^2\dot{\rho}(-\dot{\alpha}\dot{H}\widehat{q} + (1 + \dot{\alpha}\dot{H}^2)\widehat{H}_2) - \eta^2\dot{H}(\widehat{q} - \dot{H}\widehat{H}_2) &= 0,\end{aligned}$$

from which

$$(32) \quad \widehat{H}_2 = \frac{(\mu^2\dot{\rho}\dot{\alpha} + \eta^2)\dot{H}}{\mu^2\dot{\rho}(1 + \dot{\alpha}\dot{H}^2) + \eta^2\dot{H}^2}\widehat{q} = \frac{(\mu^2\dot{\rho}\dot{\alpha} + \eta^2)\dot{H}}{(\mu^2\dot{\rho}\dot{\alpha} + \eta^2)\dot{H}^2 + \mu^2\dot{\rho}}\widehat{q},$$

$$(33) \quad \widehat{v}_2 = -i\frac{\eta}{\mu\dot{\rho}}(\widehat{q} - \dot{H}\widehat{H}_2) = -i\frac{\eta\mu}{(\mu^2\dot{\rho}\dot{\alpha} + \eta^2)\dot{H}^2 + \mu^2\dot{\rho}}\widehat{q},$$

provided

$$(34) \quad \mu^2\dot{\rho}(1 + \dot{\alpha}\dot{H}^2) + \eta^2\dot{H}^2 \neq 0.$$

Recalling that $\mu = \gamma + i(\delta + \dot{v}\eta)$, we have that if $\gamma \neq 0$, then (34) surely holds, since the imaginary part in the left-hand side is different from zero if $\delta \neq -\dot{v}\eta$, otherwise $\mu^2 = \gamma^2 > 0$ and we have the sum of positive quantities. If $\gamma = 0$, (34) becomes

$$(35) \quad \eta^2\dot{H}^2 - (\delta + \dot{v}\eta)^2\dot{\rho}(1 + \dot{\alpha}\dot{H}^2) \neq 0,$$

which is true since we are not in (P2).

The plasma system also provides two differential equations for $\widehat{q}, \widehat{v}_1$:

$$(36) \quad \tau\dot{\alpha}(\widehat{q} - \dot{H}\widehat{H}_2) + i\eta(\dot{\alpha}\dot{v}\widehat{q} + \widehat{v}_2 - \dot{\alpha}\dot{v}\dot{H}\widehat{H}_2) + \frac{d\widehat{v}_1}{dx_1} = 0,$$

$$(37) \quad \tau\dot{\rho}\widehat{v}_1 + i\eta(\dot{\rho}\dot{v}\widehat{v}_1 - \dot{H}\widehat{H}_1) + \frac{d\widehat{q}}{dx_1} = 0.$$

Substituting (31), (32), (33) in (36), we obtain

$$(38) \quad \begin{aligned}\frac{d\widehat{q}}{dx_1} &= -\mu\dot{\rho}\widehat{v}_1 + i\eta\dot{H}\widehat{H}_1 \\ &= -\mu\dot{\rho}\widehat{v}_1 - \frac{\eta^2}{\mu}\dot{H}^2\widehat{v}_1 = -\frac{\mu^2\dot{\rho} + \eta^2\dot{H}^2}{\mu}\widehat{v}_1 = a_{12}(\tau, \eta)\widehat{v}_1, \\ \frac{d\widehat{v}_1}{dx_1} &= -\mu\dot{\alpha}\widehat{q} + \mu\dot{\alpha}\dot{H}\widehat{H}_2 - i\eta\widehat{v}_2 \\ &= \frac{-\mu\dot{\alpha}((\mu^2\dot{\rho}\dot{\alpha} + \eta^2)\dot{H}^2 + \mu^2\dot{\rho}) + \mu\dot{\alpha}\dot{H}^2(\mu^2\dot{\rho}\dot{\alpha} + \eta^2) - \eta^2\mu}{(\mu^2\dot{\rho}\dot{\alpha} + \eta^2)\dot{H}^2 + \mu^2\dot{\rho}}\widehat{q} \\ &= -\frac{\mu(\dot{\alpha}\dot{\rho}\mu^2 + \eta^2)}{(\mu^2\dot{\rho}\dot{\alpha} + \eta^2)\dot{H}^2 + \mu^2\dot{\rho}}\widehat{q} = a_{21}(\tau, \eta)\widehat{q},\end{aligned}$$

where we have used (26). Notice that

$$a_{12} = -\frac{\mu^2\dot{\rho} + \eta^2\dot{H}^2}{\mu}$$

is well-defined, since $\mu \neq 0$, and different from zero. Indeed, if $\delta \neq -\dot{v}\eta$, we have

$$\text{Im}(\mu^2\dot{\rho} + \eta^2\dot{H}^2) = 2\gamma\dot{\rho}(\delta + \dot{v}\eta) \neq 0,$$

while if $\delta = -\dot{v}\eta$, then $\mu = \gamma$ and

$$a_{12} = -\frac{\gamma^2\dot{\rho} + \eta^2\dot{H}^2}{\gamma} \neq 0.$$

As far as a_{21} is concerned, we have already proved that the denominator is different from zero, since this is equivalent to (35). Similar arguments show that also the numerator of a_{21} is different from zero.

Now, let us consider the vacuum block of (22). Substituting the algebraic equation

$$(39) \quad \varepsilon\tau\widehat{\mathcal{H}}_1 + i\eta\widehat{\mathcal{E}} = 0, \quad \text{i.e.} \quad \widehat{\mathcal{H}}_1 = -i\frac{\eta}{\varepsilon\tau}\widehat{\mathcal{E}},$$

we have (since we are not in (P3), $\tau \neq 0$, that is $\gamma \neq 0$ or $\delta \neq 0$):

$$\begin{aligned} \frac{d\widehat{\mathcal{H}}_2}{dx_1} &= -\varepsilon\tau\widehat{\mathcal{E}} - i\eta\widehat{\mathcal{H}}_1 = -\frac{\varepsilon^2\tau^2 + \eta^2}{\varepsilon\tau}\widehat{\mathcal{E}} = a_{34}(\tau, \eta)\widehat{\mathcal{E}}, \\ \frac{d\widehat{\mathcal{E}}}{dx_1} &= -\varepsilon\tau\widehat{\mathcal{H}}_2 = a_{43}(\tau)\widehat{\mathcal{H}}_2. \end{aligned}$$

Both a_{34}, a_{43} , defined in (27), are finite and different from zero.

Consequently, in (P0), we have

$$(40) \quad \frac{d}{dx_1}\widehat{V}^{\text{nc}} = \mathcal{A}(\tau, \eta)\widehat{V}^{\text{nc}}, \quad \mathcal{A} := \begin{pmatrix} 0 & a_{12} & 0 & 0 \\ a_{21} & 0 & 0 & 0 \\ 0 & 0 & 0 & a_{34} \\ 0 & 0 & a_{43} & 0 \end{pmatrix}, \quad x_1 > 0.$$

Remark 1. We notice that (P1) ($\mu = 0$) corresponds to a pole for the coefficient a_{12} , (P2) (yielding $\dot{\rho}(1 + \dot{\alpha}\dot{H}^2)\mu^2 + \eta^2\dot{H}^2 = 0$) corresponds to a pole for the coefficient a_{21} , and (P3) ($\tau = 0$) corresponds to a pole for the coefficient a_{34} . For this reason such cases need a different analysis, see Subsections 7.7, 7.8, 7.9.

The eigenvalues of \mathcal{A} are given by the complex roots of

$$(41) \quad \omega^2 = a_{12}a_{21} = \frac{(\mu^2\dot{\rho} + \eta^2\dot{H}^2)(\dot{\alpha}\dot{\rho}\mu^2 + \eta^2)}{(\mu^2\dot{\rho}\dot{\alpha} + \eta^2)\dot{H}^2 + \mu^2\dot{\rho}} = \eta^2 + \frac{\mu^4\dot{\alpha}\dot{\rho}^2}{(\mu^2\dot{\rho}\dot{\alpha} + \eta^2)\dot{H}^2 + \mu^2\dot{\rho}}$$

and

$$(42) \quad \omega^2 = a_{34}a_{43} = \varepsilon^2\tau^2 + \eta^2 = \varepsilon^2(\gamma^2 - \delta^2) + \eta^2 + 2i\varepsilon^2\delta\gamma.$$

The classical results of Hersh [10] for hyperbolic systems, generalized by Majda–Osher [15] for free boundary problems with characteristic boundary of constant multiplicity (which is the case we are considering, since we have assumed a piecewise constant basic state), imply that there are two couples $\pm\omega_1, \pm\omega_2$ of eigenvalues with nonvanishing real part as long as $\gamma = \text{Re } \tau > 0$.

Notice that this means that ω_j^2 is not a negative real number. For the vacuum part, this can be verified with ease, since if $\delta \neq 0$, then $\text{Im } a_{34}a_{43} = 2\varepsilon^2\delta\gamma \neq 0$, while if $\delta = 0$, we have $a_{34}a_{43} = \varepsilon^2\gamma^2 + \eta^2 > 0$.

We denote by ω_1 and ω_2 the eigenvalues with strictly positive real part for $\gamma > 0$, respectively corresponding to the plasma and vacuum blocks. We denote by χ the complex root of

$$\frac{(\mu^2\dot{\rho}\dot{\alpha} + \eta^2)\dot{H}^2 + \mu^2\dot{\rho}}{\mu^2\dot{\rho} + \eta^2\dot{H}^2}$$

with positive real part or, if the real part is zero, with positive imaginary part. Notice that $\chi \neq 0$, otherwise we are in (P2), as one can easily verify.

Now, we consider $-\omega_1, -\omega_2$, which have strictly negative real part, and choose the corresponding eigenvectors

$$\begin{aligned} e_1 &= \mu\chi(a_{12}, -\omega_1, 0, 0)^\top, \\ e_2 &= (0, 0, \omega_2, \varepsilon\tau)^\top \end{aligned}$$

as generators of the stable subspace $E^-(\tau, \eta)$ of $\mathcal{A}(\tau, \eta)$. Notice that

$$|\mu\chi a_{12}| = |(\mu^2\dot{\rho}\dot{\alpha} + \eta^2)\dot{H}^2 + \mu^2\dot{\rho}|^{\frac{1}{2}} |\mu^2\dot{\rho} + \eta^2\dot{H}^2|^{\frac{1}{2}}, \quad |\mu\chi\omega_1| = |\mu| |\dot{\alpha}\dot{\rho}\mu^2 + \eta^2|^{\frac{1}{2}},$$

so that e_1 is finite. Moreover, e_1 never vanishes. Actually, if $\mu = 0$, then $|\mu\chi a_{12}| = \eta^2 \dot{H}^2 \neq 0$ because of (10) (otherwise $\gamma = \delta = \eta = 0$ and we are not in Σ). On the other hand, if $\eta^2 = -\dot{\alpha}\dot{\rho}\mu^2$, then

$$|\mu\chi a_{12}| = |\mu|^2 \dot{\rho} |1 - \dot{\alpha}\dot{H}^2|^{\frac{1}{2}} \neq 0$$

thanks to (11). Even more easily, we have that also e_2 is finite and different from zero in every point, because $|\omega_2| = |\varepsilon^2 \tau^2 + \eta^2|^{\frac{1}{2}}$.

Remark 2. We conclude this section by noticing that $\omega_1 = 0$ in each of the following cases:

$$(43) \quad \gamma = 0 \quad \text{and} \quad \delta = -\dot{v}\eta \pm \eta \dot{H} / \sqrt{\dot{\rho}}, \quad \text{i.e.} \quad a_{12} = 0,$$

$$(44) \quad \gamma = 0 \quad \text{and} \quad \delta = -\dot{v}\eta \pm \eta / \sqrt{\dot{\alpha}\dot{\rho}}, \quad \text{i.e.} \quad \mu \neq 0, a_{21} = 0,$$

while $\omega_2 = 0$ when

$$(45) \quad \gamma = 0 \quad \text{and} \quad \delta = \pm \eta / \varepsilon, \quad \text{i.e.} \quad a_{34} = 0.$$

By virtue of (11), conditions (43) and (44) cannot be verified at the same time, i.e. we never have $a_{12} = a_{21} = 0$. Also, for sufficiently small ε we may exclude that (45) is verified at the same time of one of the previous two conditions.

6. THE LOPATINSKIĬ DETERMINANT

Following Majda–Osher [15], we define the Kreiss–Lopatinskiĭ determinant, for brevity Lopatinskiĭ determinant, associated with the boundary condition β as

$$\begin{aligned} \Delta(\tau, \eta) &:= \det[\beta(e_1, e_2)] = \det \left[\begin{pmatrix} 1 & 0 & -\dot{H} & 0 \\ 0 & \varepsilon \dot{H} \tau & 0 & \mu \end{pmatrix} \begin{pmatrix} \mu\chi a_{12} & 0 \\ -\mu\chi\omega_1 & 0 \\ 0 & \omega_2 \\ 0 & \varepsilon\tau \end{pmatrix} \right] \\ &= \det \begin{pmatrix} \mu\chi a_{12} & -\omega_2 \dot{H} \\ -\mu\varepsilon\tau\chi\omega_1 \dot{H} & \mu\varepsilon\tau \end{pmatrix} = \mu\varepsilon\tau(\mu\chi a_{12} - \chi\omega_1\omega_2 \dot{H}^2). \end{aligned}$$

The Lopatinskiĭ determinant is a continuous function defined over Σ . To derive our energy estimate, we shall study the zeros of $\Delta(\tau, \eta)$. An immediate consequence of the above formula is in the following lemma.

Lemma 4. *The Lopatinskiĭ determinant $\Delta(\tau, \eta)$ vanishes on Σ for*

- $\mu = 0$, that is $(\gamma, \delta, \eta) = (1 + \dot{v}^2)^{-1}(0, -\dot{v}, 1)$,
- $\tau = 0$, that is $(\gamma, \delta, \eta) = (0, 0, 1)$,
- and at the possible zeros of

$$\mu\chi a_{12} - \chi\omega_1\omega_2 \dot{H}^2 = 0.$$

Remark 3. The first two cases will be studied apart in Subsections 7.9 and 7.7, so we exclude them now. As for the last case, we remark that if $\chi = 0$, i.e. we assume (P2), then $\mu\chi a_{12} = 0$, but $(\chi\omega_1)\omega_2 \neq 0$, so that we do not find zeros of $\Delta(\tau, \eta) = 0$. Therefore, we may conclude that $\chi \neq 0$ and reduce to study $\mu a_{12} - \omega_1\omega_2 \dot{H}^2 = 0$, i.e. the zeros of

$$(46) \quad -\mu^2 \dot{\rho} - \eta^2 \dot{H}^2 = \omega_1\omega_2 \dot{H}^2.$$

We have the following.

Lemma 5. *Let us assume the conditions (9)–(13) on the basic state. Then there exists a sufficiently small $\varepsilon_0 > 0$ such that, for any $\varepsilon \in (0, \varepsilon_0)$, we may distinguish two cases.*

- If $\dot{H}^2 < \min\{\dot{\alpha}^{-1}, \dot{\rho}\dot{v}^2\}$, then there exist exactly two roots (τ, η) of (46); moreover, they lie at the boundary of Σ (i.e., $\gamma = 0$), and they do not coincide with the zeros of ω_1 or ω_2 , nor with the poles in (P1), (P2); moreover, if

$$(47) \quad \dot{\rho}\dot{v}^2 \neq \frac{\dot{\alpha}(\dot{H}^4 - \dot{\mathcal{H}}^4) + 2\dot{H}^2 \pm \sqrt{\dot{\alpha}^2(\dot{H}^4 - \dot{\mathcal{H}}^4)^2 + 4\dot{H}^4}}{2(1 + \dot{\alpha}\dot{H}^2)},$$

they do not coincide with the poles in (P3); this means that $\mu = 0, \tau = 0$ are simple roots.

- If $\dot{H}^2 > \min\{\dot{\alpha}^{-1}, \dot{\rho}\dot{v}^2\}$, then there exist no roots of (46).

We emphasize that $\varepsilon_0 \rightarrow 0$ as $\dot{\alpha}\dot{H}^2 \rightarrow 1$.

Remark 4. We recall that $\dot{\alpha}\dot{H}^2 \neq 1$ and $\dot{\rho}\dot{v}^2 \neq \dot{H}^2$ thanks to (11) and (12), so that $\dot{H}^2 \neq \min\{\dot{\alpha}^{-1}, \dot{\rho}\dot{v}^2\}$.

Proof. Multiplying the equation $-\mu^2\dot{\rho} - \eta^2\dot{H}^2 - \omega_1\omega_2\dot{\mathcal{H}}^2 = 0$ by the expression

$$(48) \quad -\mu^2\dot{\rho} - \eta^2\dot{H}^2 + \omega_1\omega_2\dot{\mathcal{H}}^2,$$

we may replace the explicit expression of $\omega_1^2\omega_2^2$, obtaining:

$$(49) \quad \mu^2\dot{\rho} + \eta^2\dot{H}^2 = (\varepsilon^2\tau^2 + \eta^2) \frac{\dot{\alpha}\dot{\rho}\mu^2 + \eta^2}{(\dot{\alpha}\dot{\rho}\mu^2 + \eta^2)\dot{H}^2 + \mu^2\dot{\rho}} \dot{\mathcal{H}}^4.$$

Let us show that for ε small enough there is no root of the above equation if $\eta = 0$. Indeed, (49) would reduce to the relation

$$\dot{\rho} = \varepsilon^2 \frac{\dot{\alpha}}{\dot{\alpha}\dot{H}^2 + 1} \dot{\mathcal{H}}^4,$$

which can be excluded for sufficiently small ε . Therefore, we may assume $\eta \neq 0$; setting $V := \frac{\tau}{i\eta} + \dot{v}$, (it yields $\mu = i\eta V$), we may write (49) in the form

$$(\dot{H}^2 - \dot{\rho}V^2)\{\dot{H}^2 - \dot{\rho}(1 + \dot{\alpha}\dot{H}^2)V^2\} = (1 - \dot{\rho}\dot{\alpha}V^2)\dot{\mathcal{H}}^4\{1 - \varepsilon^2(V - \dot{v})^2\},$$

i.e. we obtain a fourth-order equation in V :

$$(50) \quad \{\dot{\rho}^2(1 + \dot{\alpha}\dot{H}^2) - \varepsilon^2\dot{\rho}\dot{\alpha}\dot{\mathcal{H}}^4\}V^4 + 2\varepsilon^2\dot{\rho}\dot{\alpha}\dot{v}\dot{\mathcal{H}}^4V^3 + \{(\varepsilon^2 + \dot{\rho}\dot{\alpha} - \varepsilon^2\dot{\rho}\dot{\alpha}\dot{v}^2)\dot{\mathcal{H}}^4 - \dot{\rho}\dot{H}^2(2 + \dot{\alpha}\dot{H}^2)\}V^2 - 2\varepsilon^2\dot{v}\dot{\mathcal{H}}^4V + \{\dot{H}^4 - (1 - \varepsilon^2\dot{v}^2)\dot{\mathcal{H}}^4\} = 0.$$

We may prove that, for sufficiently small ε , (50) admits four distinct roots.

(I) We first consider the case $\dot{H}^2 \neq \dot{\mathcal{H}}^2$. For $\varepsilon = 0$, (50) reduces to the biquadratic equation

$$(51) \quad \dot{\rho}^2(1 + \dot{\alpha}\dot{H}^2)\bar{V}^4 + (\dot{\rho}\dot{\alpha}\dot{\mathcal{H}}^4 - \dot{\rho}\dot{H}^2(2 + \dot{\alpha}\dot{H}^2))\bar{V}^2 + (\dot{H}^4 - \dot{\mathcal{H}}^4) = 0.$$

Setting $z = \dot{\rho}\bar{V}^2$ (in particular, $\dot{\rho}\mu^2 = -z\eta^2$), we may rewrite (51) as a second degree equation in z :

$$(52) \quad z^2(1 + \dot{\alpha}\dot{H}^2) - z(\dot{\alpha}\dot{H}^4 - \dot{\alpha}\dot{\mathcal{H}}^4 + 2\dot{H}^2) + \dot{H}^4 - \dot{\mathcal{H}}^4 = 0,$$

whose solutions are given by

$$(53) \quad z_{\pm} = \frac{\dot{\alpha}(\dot{H}^4 - \dot{\mathcal{H}}^4) + 2\dot{H}^2 \pm \sqrt{D}}{2(1 + \dot{\alpha}\dot{H}^2)},$$

where

$$\begin{aligned} D &:= (\dot{\alpha}\dot{H}^4 - \dot{\alpha}\dot{\mathcal{H}}^4 + 2\dot{H}^2)^2 - 4(1 + \dot{\alpha}\dot{H}^2)(\dot{H}^4 - \dot{\mathcal{H}}^4) \\ &= \dot{\alpha}^2(\dot{H}^4 - \dot{\mathcal{H}}^4)^2 + 4\dot{H}^4 > 0. \end{aligned}$$

It is clear that $z_+ > 0$, so that $\bar{V} = \pm\sqrt{\dot{\rho}^{-1}z_+}$ are two real, distinct roots of (51). On the other hand, $z_- > 0$ if $\dot{H}^2 > \dot{\mathcal{H}}^2$ and $z_- < 0$ if $\dot{H}^2 < \dot{\mathcal{H}}^2$. In the first case, we find two more real, distinct

roots $\bar{V} = \pm\sqrt{\dot{\rho}^{-1}z_-}$ of (51), in the second one we find two complex-valued (purely imaginary) conjugated roots of (51).

From the previous results we thus have two cases:

- if $\dot{H}^2 > \dot{\mathcal{H}}^2$, then the four roots of (51) are real and distinct;
- if $\dot{H}^2 < \dot{\mathcal{H}}^2$, then (51) admits two distinct real roots and two complex-valued, conjugated roots.

The same result can be obtained by means of the general theory of quartic equations. We recall that the type, real or complex, of solutions of a generic quartic equation

$$(54) \quad a_4x^4 + a_3x^3 + a_2x^2 + a_1x + a_0 = 0$$

depends on the sign of the discriminant Δ (whose long expression is of no interest here) and of the quantities P, Q , defined by

$$P = 8a_4a_2 - 3a_3^2, \quad Q = 64a_4^3a_0 - 16a_4^2a_2^2 + 16a_4a_3^2a_2 - 16a_4^2a_3a_1 - 3a_3^4.$$

Equation (51) has the form (54) with $a_3 = a_1 = 0$, which yields the simple formulæ

$$\Delta = 16a_4a_0(4a_4a_0 - a_2^2)^2, \quad P = 8a_4a_2, \quad Q = 16a_4^2(4a_4a_0 - a_2^2).$$

From the algebraic theory of quartic equations, the previous result for $\varepsilon = 0$ is easily obtained:

- if $\dot{H}^2 > \dot{\mathcal{H}}^2$, then $\Delta > 0, P < 0, Q < 0$ and the four roots of (51) are real and distinct;
- if $\dot{H}^2 < \dot{\mathcal{H}}^2$, then $\Delta < 0$ and (51) admits two distinct real roots and two complex-valued, conjugated roots.

Now we consider the general case (50) with $\varepsilon \neq 0$ and notice that the coefficients of (50) are continuous functions of ε . Hence, also Δ, P, Q are continuous functions of ε .

Being non-zero at $\varepsilon = 0$, the discriminant of (50) remains non-zero and with the same sign of the discriminant of (51) for sufficiently small ε . The same holds true also for the quantities P, Q , so that we still have the same cases for the complete equation (50):

- if $\dot{H}^2 > \dot{\mathcal{H}}^2$, then the four roots of (50) are real and distinct;
- if $\dot{H}^2 < \dot{\mathcal{H}}^2$, then (50) admits two distinct real roots and two complex-valued, conjugated roots.

Once we fix the four distinct roots \bar{V}_i of (51), for sufficiently small $\varepsilon_0 > 0$, there exist four separate neighborhood \mathcal{V}_i of \bar{V}_i such that for any $\varepsilon \in (0, \varepsilon_0)$, (50) admits four roots $V_i(\varepsilon)$, continuously depending on ε , with $V_i(\varepsilon) \in \mathcal{V}_i$. In this sense, we may say that each root of (50) corresponds to a root of (51).

Among the four roots of (50), we may look for the solutions to (46).

First of all, let us see that the two complex conjugated roots of case $\dot{H}^2 < \dot{\mathcal{H}}^2$ do not give a solution to the equation (46), for small enough ε . Thus, let us assume $\dot{H}^2 < \dot{\mathcal{H}}^2$ and let V be a complex-valued root of (50) with $\gamma = -\eta \operatorname{Im} V > 0$ (this corresponds to a point in the interior of Σ). We claim that such a V (corresponding to a complex solution \bar{V} of (51)), does not provide a solution of (46), for sufficiently small ε . In fact, for sufficiently small ε , by continuity it holds $\operatorname{Re}(\omega_1\omega_2) > 0$, due to

$$\operatorname{Re}(\omega_1\omega_2) = |\eta| \operatorname{Re} \omega_1 > 0, \quad \text{for } \varepsilon = 0$$

(in this case $\omega_1 \neq 0$, recalling Remark 2, and $\eta \neq 0$, as we have already observed). Therefore, from (46) we derive that $\dot{\rho} \operatorname{Re}(\mu^2) + \eta^2 \dot{H}^2 < 0$; hence $-\dot{\rho} \operatorname{Re}(V^2) + \dot{H}^2 < 0$, which is absurd, since $-\dot{\rho} \operatorname{Re}(V^2)$ is close to $-\dot{\rho} \operatorname{Re}(\bar{V}^2) = -\dot{\rho} \bar{V}^2 = -z_- > 0$ for small ε .

Therefore, for sufficiently small ε any possible solution V of (46) on Σ is real, i.e. it verifies $\gamma = 0$. Due to $\eta \neq 0$, for sufficiently small ε we see that $\omega_2 = \sqrt{\eta^2 - \varepsilon^2 \delta^2} > 0$. Then, by (46) it follows that ω_1

is real as it happens for $-\mu^2\dot{\rho} - \eta^2\dot{H}^2 = \eta^2(\dot{\rho}V^2 - \dot{H}^2)$; hence, $\omega_1 > 0$, as a consequence of $\omega_1 \neq 0$ (we will show below that $\omega_1 \neq 0$ when the Lopatinskiĭ determinant vanishes) and $\operatorname{Re} \omega_1 \geq 0$. It follows that

$$(55) \quad \dot{\rho}V^2 > \dot{H}^2$$

for small ε . This implies that we find a couple of real roots to (50) if, and only if, setting $\varepsilon = 0$ we get $z_+ > \dot{H}^2$. Indeed, $z_- < \dot{H}^2$, therefore the two corresponding roots are excluded (thus z_- is excluded in both cases $\dot{H}^2 \gtrless \dot{\mathcal{H}}^2$). The condition $z_+ > \dot{H}^2$ corresponds to $\sqrt{D} > \dot{\alpha}(\dot{H}^4 + \dot{\mathcal{H}}^4)$, i.e.

$$\dot{\alpha}\dot{H}^2 < 1.$$

It remains to prove that if $z_+ > \dot{H}^2$, then we effectively find two real roots of (46), in suitable neighborhoods of $\pm\sqrt{\dot{\rho}^{-1}z_+}$, for sufficiently small ε . In order to do that, it is sufficient to prove that they are not real roots of (48). But this follows as an immediate consequence of $\dot{\rho}V^2 > \dot{H}^2$: being $\omega_1\omega_2 > 0$, the quantity in (48) is positive, in particular it is not zero.

(II) Now let $\dot{\mathcal{H}}^2 = \dot{H}^2$; the equation in (50) has the coefficient of zero degree proportional to ε^2 :

$$(56) \quad \{\dot{\rho}^2(1 + \dot{\alpha}\dot{H}^2) - \varepsilon^2\dot{\rho}\dot{\alpha}\dot{H}^4\}V^4 + 2\varepsilon^2\dot{\rho}\dot{\alpha}\dot{v}\dot{H}^4V^3 + \{\varepsilon^2(1 - \dot{\rho}\dot{\alpha}\dot{v}^2)\dot{H}^4 - 2\dot{\rho}\dot{H}^2\}V^2 - 2\varepsilon^2\dot{v}\dot{H}^4V + \varepsilon^2\dot{v}^2\dot{H}^4 = 0,$$

in particular the discriminant vanishes for $\varepsilon = 0$. However, it is easy to check that its discriminant verifies

$$\Delta = 16\varepsilon^2\dot{\rho}^2(1 + \dot{\alpha}\dot{H}^2)(2\dot{\rho}\dot{H}^2)^4\dot{v}^2\dot{H}^4 + O(\varepsilon^4),$$

in particular, $\Delta > 0$ for sufficiently small, nonzero ε . Then we have four distinct roots. Moreover, they are all real-valued for small, nonzero, ε , due to:

$$P = -16\dot{\rho}^2(1 + \dot{\alpha}\dot{H}^2)\dot{\rho}\dot{H}^2 + O(\varepsilon^2), \quad Q = -16(\dot{\rho}^2(1 + \dot{\alpha}\dot{H}^2))^2(2\dot{\rho}\dot{H}^2)^2 + O(\varepsilon^2),$$

so that $P < 0$ and $Q < 0$ for sufficiently small ε (see the discussion above). These four roots will be close to the four real roots of (50) at $\varepsilon = 0$, i.e.

$$\dot{\rho}^2(1 + \dot{\alpha}\dot{H}^2)V^4 - 2\dot{\rho}\dot{H}^2V^2 = 0.$$

In particular, two of them will be close to 0, thus they do not satisfy (55), whereas the other two are close to $\pm\sqrt{z_+/\dot{\rho}}$, where we put

$$(57) \quad z_+ = \frac{2\dot{H}^2}{1 + \dot{\alpha}\dot{H}^2}.$$

Clearly, z_+ in (57) coincides with z_+ in (53), setting $\dot{\mathcal{H}}^2 = \dot{H}^2$. Again, $z_+ > \dot{H}^2$ if, and only if, $\dot{\alpha}\dot{H}^2 < 1$, as it happens for $\dot{H}^2 \neq \dot{\mathcal{H}}^2$.

Summarizing, if $\dot{\alpha}\dot{H}^2 > 1$, then, for sufficiently small ε , (46) admits no solution in Σ ; on the other hand, if $\dot{\alpha}\dot{H}^2 < 1$, then, for sufficiently small ε , (46) admits exactly two solutions, and they are on the boundary of Σ .

It remains to prove that, in the first case, the two roots do not coincide with the poles, i.e.

$$\mu = 0, \quad \mu = \pm i \frac{\dot{H}}{\sqrt{\dot{\rho}(1 + \dot{\alpha}\dot{H}^2)}}, \quad \tau = 0,$$

or with the zeros of ω_1, ω_2 .

The case $\mu = 0$ corresponds to $V = 0$, thus (55) is trivially false. The second case gives

$$V = \pm \frac{\dot{H}}{\sqrt{\dot{\rho}(1 + \alpha\dot{H}^2)}}; \quad \text{hence,} \quad \dot{\rho}V^2 = \frac{\dot{H}^2}{1 + \alpha\dot{H}^2} < \dot{H}^2,$$

and (55) is violated once again. The case $\tau = 0$, i.e. $\eta = 1$, implies $\mu = i\dot{v}$, so that

$$\dot{\rho}V^2 = \dot{\rho}\dot{v}^2,$$

and (55) might be satisfied. However, setting $\varepsilon = 0$ and replacing $z_+ = \dot{\rho}\dot{v}^2$ in (53), we derive

$$(58) \quad \dot{\rho}\dot{v}^2 = \frac{\dot{\alpha}(\dot{H}^4 - \dot{H}^4) + 2\dot{H}^2 \pm \sqrt{D}}{2(1 + \dot{\alpha}\dot{H}^2)}.$$

Therefore, if (47) holds, the two roots are not given by $\pm(0, 0, 1)$ for sufficiently small ε . Notice that it is not necessary to prevent (58) if $\dot{\alpha}\dot{H}^2 > 1$ or $\dot{H}^2 > \dot{\rho}\dot{v}^2$, that is, if $\dot{H}^2 > \min\{\dot{\alpha}^{-1}, \dot{\rho}\dot{v}^2\}$.

If (43) holds, then $V = \pm\dot{H}/\sqrt{\dot{\rho}}$, i.e. $\dot{\rho}V^2 = \dot{H}^2$, so that (55) is violated. If (44) holds, then $V = \pm(\dot{\alpha}\dot{\rho})^{-\frac{1}{2}}$. At $\varepsilon = 0$, we obtain $z = \dot{\alpha}^{-1}$ which, replaced in (53), gives $\dot{\alpha}\dot{H}^2 = 1$, which contradicts (11). Due to (11), we may exclude that the roots satisfy (44) for sufficiently small ε . If (45) holds, then $V = \dot{v} \pm \varepsilon^{-1}$, in particular $V^2 \rightarrow \infty$ as $\varepsilon \rightarrow 0$, and this contradicts the fact that the coefficients in (50) are bounded for $\varepsilon \in [0, 1]$. \square

7. CONSTRUCTING A SYMMETRIZER

7.1. Classification of the points on Σ . We now turn to the construction of our degenerate Kreiss' symmetrizer, proceeding as in [8]. The construction is microlocal and is achieved near any point $(\tau_0, \eta_0) \in \Sigma$. The analysis is rather long since one has to distinguish between many different cases. In the end, we shall consider a partition of unity to patch things together and derive our energy estimate.

We classify the points as follows and construct a symmetrizer in a suitable neighborhood of any point of Σ , with the exception of poles, that will be treated in a different way.

- (1) Interior points, where $\gamma > 0$ and the Lopatinskiĭ condition holds, i.e. $\Delta \neq 0$ (Subsection 7.3). \mathcal{A} is diagonalizable.
- (2) Boundary points, where $\gamma = 0$, which are not poles and such that $\omega_1\omega_2 \neq 0$ and the Lopatinskiĭ condition holds (Subsection 7.4). \mathcal{A} is diagonalizable.
- (3) Boundary points, where $\gamma = 0$, which are not poles and such that $\omega_1\omega_2 \neq 0$ and the Lopatinskiĭ condition does not hold, i.e. $\Delta = 0$ (Subsection 7.5). \mathcal{A} is diagonalizable.
- (4) Points where $\omega_1 = 0$, i.e. $\gamma = 0$ and either $\delta + \dot{v}\eta = \pm\dot{H}\eta/\sqrt{\dot{\rho}}$, or $\delta + \dot{v}\eta = \pm\eta/\sqrt{\dot{\alpha}\dot{\rho}}$ (Subsection 7.6). The points are not poles and \mathcal{A} is not diagonalizable: the block in the Jordan matrix corresponding to ω_1 is given by $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$. The Lopatinskiĭ condition holds.
- (5) Points where $\omega_2 = 0$, i.e. $\gamma = 0$ and $\eta = \pm\varepsilon\delta$ (Subsection 7.6). The points are not poles and \mathcal{A} is not diagonalizable: the block in the Jordan matrix corresponding to ω_2 is given by $\begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$. The Lopatinskiĭ condition holds.
- (6) Poles (CASE 1, CASE 2, CASE 3, see respectively Subsections 7.9, 7.7, 7.8)

$$\tau = 0, \quad \mu = 0, \quad \mu = \pm i \frac{\dot{H}}{\sqrt{\dot{\rho}(1 + \dot{\alpha}\dot{H}^2)}} \eta.$$

The Lopatinskiĭ condition does not hold in poles $\tau = 0$ and $\mu = 0$, while it is satisfied in the third case.

We recall that we assumed ε to be sufficiently small. Moreover, in the following, we will denote by κ a generic, positive, constant.

We begin with some useful results.

7.2. Preliminary lemmas.

Lemma 6. *Let $\gamma = 0$. Then $a_{12}, a_{21} \in i\mathbb{R}$, $\partial_\gamma a_{12}, \partial_\gamma a_{21} \in \mathbb{R}$ and $\partial_\gamma \omega_1^2 \in i\mathbb{R}$.*

Proof. In the following we put

$$(59) \quad \delta + i\eta = \pm\sqrt{K}\eta,$$

for some $K \geq 0$ if $\eta \neq 0$. If $\eta = 0$, so that $\delta \neq 0$, we formally set $K = \infty$ and we replace the undetermined object $\pm\sqrt{K}\eta$ by δ , where needed. Due to $\mu^2 = -K\eta^2$, we get:

$$\begin{aligned} a_{12} &= \pm \frac{K\dot{\rho} - \dot{H}^2}{i\sqrt{K}} \eta, \\ a_{21} &= -\frac{\pm i\sqrt{K}(1 - \dot{\alpha}\dot{\rho}K)}{(1 - \dot{\alpha}\dot{\rho}K)\dot{H}^2 - \dot{\rho}K} \eta. \end{aligned}$$

In view of

$$\partial_\gamma \mu|_{\gamma=0} = \partial_\gamma \bar{\mu}|_{\gamma=0} = 1, \quad \mu \partial_\gamma (\mu^2)|_{\gamma=0} = -2K\eta^2,$$

setting

$$k = (1 - \dot{\alpha}\dot{\rho}K)\dot{H}^2 - \dot{\rho}K,$$

we derive:

$$\begin{aligned} \partial_\gamma a_{12} &= -\frac{-K\dot{\rho} + \dot{H}^2}{-K} + 2K \frac{\dot{\rho}(-K) - (-K\dot{\rho} + \dot{H}^2)}{K^2} = -\frac{K\dot{\rho} + \dot{H}^2}{K}, \\ \partial_\gamma a_{21} &= -\frac{1 - \dot{\alpha}\dot{\rho}K}{k} + 2K \frac{\dot{\alpha}\dot{\rho}k - (1 - \dot{\alpha}\dot{\rho}K)\dot{\rho}(\dot{\alpha}\dot{H}^2 + 1)}{k^2} \\ &= \frac{(3\dot{\alpha}\dot{\rho}K - 1)k - 2K(1 - \dot{\alpha}\dot{\rho}K)\dot{\rho}(\dot{\alpha}\dot{H}^2 + 1)}{k^2} \\ &= \frac{-\dot{\alpha}^2\dot{\rho}^2\dot{H}^2K^2 - \dot{\alpha}\dot{\rho}^2K^2 + 2\dot{\alpha}\dot{\rho}K\dot{H}^2 - \dot{\rho}K - \dot{H}^2}{k^2} \\ &= \frac{-(\dot{\alpha}\dot{\rho}K - 1)^2\dot{H}^2 - \dot{\alpha}\dot{\rho}^2K^2 - \dot{\rho}K}{k^2}. \end{aligned}$$

Finally, we get

$$\partial_\gamma \omega_1^2 = a_{12}\partial_\gamma a_{21} + a_{21}\partial_\gamma a_{12} \in i\mathbb{R},$$

which proves our claim. \square

From Lemma 6, we derive the following.

Lemma 7. *Let $\gamma = 0$. Then:*

- *If we are not in (P2) and $\omega_1 \in i\mathbb{R} \setminus \{0\}$, then $\partial_\gamma \omega_1(\tau, \eta) \in \mathbb{R} \setminus \{0\}$;*
- *If $\omega_2 \in i\mathbb{R} \setminus \{0\}$, then $\partial_\gamma \omega_2(\tau, \eta) \in \mathbb{R} \setminus \{0\}$.*

Remark 5. Being the real part of ω_1 strictly positive for $\gamma > 0$, we have $\text{Re } \omega_1 \geq 0$ for all points of Σ . There are two possibilities: if in a given point of Σ there holds $\text{Re } \omega_1 > 0$, then in a sufficiently small neighborhood \mathcal{V} we have $\text{Re } \omega_1 \geq \kappa$ for some $\kappa > 0$. Because $\gamma \in [0, 1]$ on Σ , the inequality $\text{Re } \omega_1 \geq \kappa\gamma$ holds as well. Alternatively, if in a given point of Σ (excluding (P2)) there holds $\text{Re } \omega_1 = 0$, then, by Lemma 7, in a sufficiently small neighborhood \mathcal{V} it follows that $\text{Re } \omega_1 \geq \kappa\gamma$. Similarly, $\text{Re } \omega_2 \geq \kappa\gamma$ for any point on Σ . See [8].

Proof. Let us compute ω_1^2 when $\gamma_0 = 0$. We set K as in (59), and

$$k = (1 - \dot{\alpha}\rho K)\dot{H}^2 - \dot{\rho}K,$$

which is nonzero thanks to the fact that we excluded (P2). Then

$$\omega_1^2(\tau, \eta) = -\frac{(K\dot{\rho} - \dot{H}^2)(1 - \dot{\alpha}\rho K)}{k}\eta^2 = \eta^2 \left(1 + \frac{\dot{\alpha}\dot{\rho}^2 K^2}{k}\right).$$

We notice that K may not be zero, i.e. we can exclude (P1), otherwise $\omega_1^2 = \eta^2 > 0$.

By $\omega_1^2(\tau, \eta) < 0$, we deduce $k < 0$ and $\eta \neq 0$. Moreover,

$$(60) \quad 0 < -k < \dot{\alpha}\dot{\rho}^2 K^2.$$

From $2\omega_1\partial_\gamma(\omega_1) = \partial_\gamma(\omega_1^2) \in i\mathbb{R}$, thanks to Lemma 6, and recalling that $\omega_1 \in i\mathbb{R}$, we derive that $\partial_\gamma(\omega_1) \in \mathbb{R}$. Taking the derivative of

$$\omega_1^2 = \eta^2 + \frac{\mu^4 \dot{\alpha}\dot{\rho}^2}{(\mu^2 \dot{\rho}\dot{\alpha} + \eta^2)\dot{H}^2 + \mu^2 \dot{\rho}},$$

replacing $\gamma = 0$ and $\delta + \dot{\nu}\eta = \pm\sqrt{K}\eta$, we get

$$\begin{aligned} \partial_\gamma(\omega_1^2) &= \pm 2i\sqrt{K}\eta \frac{-2\dot{\alpha}\dot{\rho}Kk - \dot{\alpha}\dot{\rho}^2(1 + \dot{\alpha}\dot{H}^2)K^2}{k^2} \\ &= \pm 2i\sqrt{K}\eta \dot{\alpha}\dot{\rho}^2 \frac{K}{k^2} [\dot{\rho}(1 + \dot{\alpha}\dot{H}^2)K - 2\dot{H}^2]. \end{aligned}$$

By contradiction, let $\partial_\gamma(\omega_1^2) = 0$. Then,

$$2\dot{H}^2 = \dot{\rho}(1 + \dot{\alpha}\dot{H}^2)K = -2k.$$

Replacing the expressions so obtained for k and K in (60), we get:

$$\dot{H}^2 = -k < \dot{\alpha}\dot{\rho}^2 K^2 = \frac{4\dot{\alpha}\dot{H}^4}{(1 + \dot{\alpha}\dot{H}^2)^2},$$

which is false, being it equivalent to $(1 - \dot{\alpha}\dot{H}^2)^2 < 0$.

If $\omega_2 \in i\mathbb{R} \setminus 0$, then $\omega_2^2 < 0$ and

$$2\omega_2\partial_\gamma\omega_2 = \partial_\gamma(\omega_2^2) = 2\varepsilon^2(\gamma + i\delta),$$

in particular $\omega_2\partial_\gamma\omega_2 = i\varepsilon^2\delta \in i\mathbb{R}$ for $\gamma = 0$. Therefore, $\partial_\gamma\omega_2 \in \mathbb{R}$. It can not be zero, otherwise $\tau = 0$ and we derive the contradiction $\eta^2 = \omega_2^2 < 0$. \square

Lemma 8. *If $\gamma = 0$, then $\partial_\gamma(\omega_j^2) \in i\mathbb{R} \setminus \{0\}$ for $j = 1, 2$.*

Proof. From Lemma 6, we already have $\partial_\gamma(\omega_1^2) \in i\mathbb{R}$. Now, by contradiction, let $\partial_\gamma(\omega_1^2) = 0$ when (44) holds, that is, $\dot{\alpha}\dot{\rho}K = 1$. Then:

$$0 = \dot{\rho}(1 + \dot{\alpha}\dot{H}^2)K - 2\dot{H}^2 = \dot{\rho}K - \dot{H}^2 = \frac{1}{\dot{\alpha}}(1 - \dot{\alpha}\dot{H}^2),$$

which contradicts (11). Similarly if (43) holds, that is, $\dot{\rho}K = \dot{H}^2$.

On the other hand, when $\gamma = 0$, we have $\partial_\gamma(\omega_2^2) = 2i\varepsilon^2\delta \in i\mathbb{R} \setminus 0$ by an explicit computation. \square

Thanks to Lemma 6, we get another useful result.

Lemma 9. *We have the following properties:*

- if $a_{12} = 0$, then $\partial_\gamma a_{12}, \partial_\gamma a_{21} \neq 0$,
- if $a_{21} = 0$, then $\partial_\gamma a_{12}, \partial_\gamma a_{21} \neq 0$,
- if $a_{34} = 0$, then $\partial_\gamma a_{34} \neq 0$.

We remark that $a_{43} = -\varepsilon\tau \neq 0$ if we are not in (P3), and that $\partial_\gamma a_{43} = -\varepsilon \neq 0$. Thanks to (11), it follows that (43) and (44) are not verified at the same time.

Proof. First, we assume (43). We set K as in (59), that is, $K = \dot{H}^2/\dot{\rho}$; hence,

$$\partial_\gamma a_{12}|_{\dot{\rho}K=\dot{H}^2} = -2\dot{\rho} \neq 0,$$

$$\partial_\gamma a_{21}|_{\dot{\rho}K=\dot{H}^2} = \frac{-(\dot{\alpha}\dot{H}^2 - 1)^2\dot{H}^2 - \dot{\alpha}\dot{H}^4 - \dot{H}^2}{\dot{\alpha}^2\dot{H}^8} = -\frac{\dot{\alpha}^2\dot{H}^4 - \dot{\alpha}\dot{H}^2 + 2}{\dot{\alpha}^2\dot{H}^6} = -\frac{(\dot{\alpha}\dot{H}^2 - 1)^2 + \dot{\alpha}\dot{H}^2 + 1}{\dot{\alpha}^2\dot{H}^6} \neq 0.$$

On the other hand, if we assume (44), then $K = 1/(\dot{\alpha}\dot{\rho})$ and

$$\partial_\gamma a_{12}|_{\dot{\alpha}\dot{\rho}K=1} = -\dot{\rho}(1 + \dot{\alpha}\dot{H}^2) \neq 0,$$

$$\partial_\gamma a_{21}|_{\dot{\alpha}\dot{\rho}K=1} = -2\dot{\alpha} \neq 0.$$

If $0 = a_{34} = \varepsilon^2\tau^2 + \eta^2 = 0$, then

$$\partial_\gamma a_{34} = -\varepsilon + \frac{\eta^2}{\varepsilon\tau^2} = -2\varepsilon \neq 0.$$

□

Now we proceed with the construction of the degenerate Kreiss' symmetrizer, following the classification of points given in Subsection 7.1. After that, we will consider the special case of poles.

7.3. Interior points. We consider a point $P_0 = (\tau_0, \eta_0) \in \Sigma$ with $\gamma_0 := \operatorname{Re} \tau_0 > 0$, i.e. in the internal part of Σ . The Lopatinskiĭ condition holds and $\mathcal{A}(\tau, \eta)$ is diagonalizable in a neighborhood \mathcal{V} of P_0 . Besides

$$e_1 = \mu\chi(a_{12}, -\omega_1, 0, 0)^\top,$$

$$e_2 = (0, 0, \omega_2, \varepsilon\tau)^\top,$$

we introduce

$$e_3 = \mu\chi(a_{12}, \omega_1, 0, 0)^\top,$$

$$e_4 = (0, 0, \omega_2, -\varepsilon\tau)^\top,$$

and we define in \mathcal{V} the invertible matrix $T(\tau, \eta)$, given by $T^{-1} = T^{-1}(\tau, \eta) = (e_1 \ e_3 \ e_2 \ e_4)$. Notice the inverted order between the eigenvectors e_2, e_3 , introduced in order to separate the plasma block from the vacuum one.

Clearly, the eigenvectors are smooth, $T \in \mathcal{C}^\infty(\mathcal{V}, M_4)$ has a nonzero determinant and

$$(61) \quad T\mathcal{A}T^{-1} = \begin{pmatrix} -\omega_1 & 0 & 0 & 0 \\ 0 & \omega_1 & 0 & 0 \\ 0 & 0 & -\omega_2 & 0 \\ 0 & 0 & 0 & \omega_2 \end{pmatrix}.$$

We define the symmetrizer

$$r(\tau, \eta) = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & K' & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & K' \end{pmatrix},$$

with $K' \geq 1$ to be fixed sufficiently large, so that

$$rT\mathcal{A}T^{-1} = \begin{pmatrix} \omega_1 & 0 & 0 & 0 \\ 0 & K'\omega_1 & 0 & 0 \\ 0 & 0 & \omega_2 & 0 \\ 0 & 0 & 0 & K'\omega_2 \end{pmatrix}.$$

Due to $\operatorname{Re} \omega_j \geq \kappa$, $j = 1, 2$, in \mathcal{V} for some $\kappa > 0$, we immediately derive

$$(62) \quad \operatorname{Re}(r(\tau, \eta)T(\tau, \eta)\mathcal{A}(\tau, \eta)T(\tau, \eta)^{-1}) \geq \kappa \mathbf{I}, \quad \forall (\tau, \eta) \in \mathcal{V},$$

where $\operatorname{Re} M = (M + M^*)/2$ for any $M \in M_4(\mathbb{C})$. On the other hand, as in [8] we show that there holds

$$(63) \quad r(\tau, \eta) + C\tilde{\beta}(\tau, \eta)^*\tilde{\beta}(\tau, \eta) \geq \mathbf{I}, \quad \forall (\tau, \eta) \in \mathcal{V},$$

where C is a positive constant and $\tilde{\beta} := \beta T^{-1}$, for sufficiently large $K' \geq 1$. In order to prove it, let us recall that the first and the third columns of T^{-1} are the generators e_1, e_2 of the stable subspace $E^-(\tau, \eta)$ of $\mathcal{A}(\tau, \eta)$. Since the Lopatinskiĭ determinant does not vanish at (τ_0, η_0) , there exists a constant C_0 independent of $(\tau, \eta) \in \mathcal{V}$ such that

$$|Z_1|^2 + |Z_3|^2 \leq C_0(|Z_2|^2 + |Z_4|^2 + |\tilde{\beta}(\tau, \eta)Z|^2)$$

for all $Z \in \mathbb{C}^4$. Then

$$\begin{aligned} & \langle r(\tau, \eta)Z, Z \rangle_{\mathbb{C}^4} + 2C_0|\tilde{\beta}(\tau, \eta)Z|^2 \\ &= -|Z_1|^2 - |Z_3|^2 + K'(|Z_2|^2 + |Z_4|^2) + 2C_0|\tilde{\beta}(\tau, \eta)Z|^2 \\ &\geq |Z_1|^2 + |Z_3|^2 + (K' - 2C_0)(|Z_2|^2 + |Z_4|^2), \end{aligned}$$

which gives (63) for K' large enough (e.g. $K' = 2C_0 + 1$).

7.4. Boundary points where the Lopatinskiĭ condition holds (except poles or $\omega_1\omega_2 = 0$). We consider a point $P_0 = (\tau_0, \eta_0) \in \Sigma$ with $\gamma_0 := \operatorname{Re} \tau_0 = 0$, which is not a pole, such that the Lopatinskiĭ condition holds at P_0 , i.e. $\Delta(\tau_0, \eta_0) \neq 0$, and $\mathcal{A}(P_0)$ is diagonalizable. We fix a sufficiently small neighborhood \mathcal{V} of P_0 , not containing any pole, in which the Lopatinskiĭ condition holds and \mathcal{A} is diagonalizable. We may proceed as we did for the interior points, but now we only have $\operatorname{Re} \omega_j \geq \kappa\gamma$, $j = 1, 2$, in \mathcal{V} , for a suitable constant $\kappa > 0$. This is due to Lemma 7, see also Remark 5. Therefore we may replace (62) by

$$(64) \quad \operatorname{Re}(r(\tau, \eta)T(\tau, \eta)\mathcal{A}(\tau, \eta)T(\tau, \eta)^{-1}) \geq \kappa\gamma \mathbf{I}, \quad \forall (\tau, \eta) \in \mathcal{V},$$

whereas (63) still holds true, because of the Lopatinskiĭ condition. In the interior points considered in Subsection 7.3 estimate (64) holds as well, because (62) trivially implies (64), since $\gamma \in [0, 1]$ on Σ .

7.5. Boundary points where the Lopatinskiĭ condition does not hold (except poles or $\omega_1\omega_2 = 0$). We consider a point $P_0 = (\tau_0, \eta_0) \in \Sigma$ with $\gamma_0 := \operatorname{Re} \tau_0 = 0$, which is not a pole and such that the Lopatinskiĭ condition does not hold at P_0 , that is $\Delta(\tau_0, \eta_0) = 0$. From Lemma 5 it follows that $\mathcal{A}(P_0)$ is diagonalizable. We fix a neighborhood \mathcal{V} of P_0 , not containing any pole, in which \mathcal{A} is diagonalizable. We construct T as we did for the interior points, obtaining (61), but now we define the symmetrizer

$$r(\tau, \eta) = \begin{pmatrix} -\gamma^2 & 0 & 0 & 0 \\ 0 & K' & 0 & 0 \\ 0 & 0 & -\gamma^2 & 0 \\ 0 & 0 & 0 & K' \end{pmatrix},$$

where $K' \geq 1$ is taken sufficiently large, so that

$$rT\mathcal{A}T^{-1} = \begin{pmatrix} \gamma^2\omega_1 & 0 & 0 & 0 \\ 0 & K'\omega_1 & 0 & 0 \\ 0 & 0 & \gamma^2\omega_2 & 0 \\ 0 & 0 & 0 & K'\omega_2 \end{pmatrix}.$$

Taking into account of Lemma 7 once again, it follows that (64) is replaced by

$$(65) \quad \operatorname{Re}(r(\tau, \eta)T(\tau, \eta)\mathcal{A}(\tau, \eta)T(\tau, \eta)^{-1}) \geq \kappa\gamma^3\mathbf{I}, \quad \forall(\tau, \eta) \in \mathcal{V}.$$

On the other hand, due to the fact that the roots of Lopatinskiĭ determinant are simple, we may derive the estimate

$$|\beta(\tau, \eta)(e_1(\tau, \eta), e_2(\tau, \eta))Z'|^2 \geq \kappa_0\gamma^2|Z'|^2, \quad \forall Z' \in \mathbb{C}^2,$$

which implies

$$\kappa_0\gamma^2(|Z_1|^2 + |Z_3|^2) \leq C_0(|Z_2|^2 + |Z_4|^2 + |\tilde{\beta}(\tau, \eta)Z|^2),$$

for all $Z \in \mathbb{C}^4$, where $\tilde{\beta} := \beta T^{-1}$. Then, following [8], we modify the proof given in Subsection 7.3 and obtain

$$(66) \quad r(\tau, \eta) + C\tilde{\beta}(\tau, \eta)^*\tilde{\beta}(\tau, \eta) \geq \gamma^2\mathbf{I}, \quad \forall(\tau, \eta) \in \mathcal{V},$$

which replaces (63).

7.6. Boundary points where $\omega_1\omega_2 = 0$. We consider a point $P_0 = (\tau_0, \eta_0) \in \Sigma$ with $\gamma_0 := \operatorname{Re} \tau_0 = 0$, which is not a pole but such that $\mathcal{A}(P_0)$ is not diagonalizable. It follows that the Lopatinskiĭ condition holds at P_0 . We fix a neighborhood \mathcal{V} of P_0 , not containing any pole, and such that the Lopatinskiĭ condition holds in every point.

Let us assume (44). Thanks to (11), it is not restrictive to assume that (43) is nowhere verified in \mathcal{V} . Also, we may assume that (45) is nowhere verified in \mathcal{V} , provided ε is sufficiently small. We replace the matrix T , used to deal with points where \mathcal{A} was diagonalizable, with a new matrix T , invertible on \mathcal{V} . We define:

$$T = \begin{pmatrix} a_{12}^{-1} & 0 & 0 & 0 \\ a_{21} & -i & 0 & 0 \\ 0 & 0 & (2\omega_2)^{-1} & (2\varepsilon\tau)^{-1} \\ 0 & 0 & (2\omega_2)^{-1} & -(2\varepsilon\tau)^{-1} \end{pmatrix},$$

so that

$$(67) \quad T^{-1} = \begin{pmatrix} a_{12} & 0 & 0 & 0 \\ -i\omega_1^2 & i & 0 & 0 \\ 0 & 0 & \omega_2 & \omega_2 \\ 0 & 0 & \varepsilon\tau & -\varepsilon\tau \end{pmatrix}, \quad T\mathcal{A}T^{-1} = \begin{pmatrix} -i\omega_1^2 & i & 0 & 0 \\ -i\omega_1^4 - i\omega_1^2 & i\omega_1^2 & 0 & 0 \\ 0 & 0 & -\omega_2 & 0 \\ 0 & 0 & 0 & \omega_2 \end{pmatrix}.$$

Notice that we have modified only the first two columns of T , and consequently of T^{-1} . We can proceed similarly if we assume that (43) holds, setting

$$T = \begin{pmatrix} -i & a_{12} & 0 & 0 \\ 0 & a_{21}^{-1} & 0 & 0 \\ 0 & 0 & (2\omega_2)^{-1} & (2\varepsilon\tau)^{-1} \\ 0 & 0 & (2\omega_2)^{-1} & -(2\varepsilon\tau)^{-1} \end{pmatrix},$$

so that

$$T^{-1} = \begin{pmatrix} i & -i\omega_1^2 & 0 & 0 \\ 0 & a_{21} & 0 & 0 \\ 0 & 0 & \omega_2 & \omega_2 \\ 0 & 0 & \varepsilon\tau & -\varepsilon\tau \end{pmatrix}, \quad T\mathcal{A}T^{-1} = \begin{pmatrix} i\omega_1^2 & -i\omega_1^4 - i\omega_1^2 & 0 & 0 \\ i & -i\omega_1^2 & 0 & 0 \\ 0 & 0 & -\omega_2 & 0 \\ 0 & 0 & 0 & \omega_2 \end{pmatrix}.$$

Moreover, if (45) holds, then we follow the same reasoning by defining

$$T = \begin{pmatrix} (2\mu\chi a_{12})^{-1} & -(2\mu\chi\omega_1)^{-1} & 0 & 0 \\ (2\mu\chi a_{12})^{-1} & (2\mu\chi\omega_1)^{-1} & 0 & 0 \\ 0 & 0 & -i & a_{34} \\ 0 & 0 & 0 & a_{43}^{-1} \end{pmatrix},$$

so that

$$T^{-1} = \begin{pmatrix} \mu\chi a_{12} & \mu\chi a_{12} & 0 & 0 \\ -\mu\chi\omega_1 & \mu\chi\omega_1 & 0 & 0 \\ 0 & 0 & i & -i\omega_2^2 \\ 0 & 0 & 0 & a_{43} \end{pmatrix}, \quad T\mathcal{A}T^{-1} = \begin{pmatrix} -\omega_1 & 0 & 0 & 0 \\ 0 & \omega_1 & 0 & 0 \\ 0 & 0 & i\omega_2^2 & -i\omega_2^4 - i\omega_2^2 \\ 0 & 0 & i & -i\omega_2^2 \end{pmatrix}.$$

In this last case we have modified only the last two columns of T .

From Proposition 8, $\partial_\gamma(\omega_j^2) \in i\mathbb{R} \setminus \{0\}$ and it trivially follows that $\partial_\gamma(\omega_j^4 + \omega_j^2) \in i\mathbb{R} \setminus \{0\}$ as well. Moreover, we recall that $\omega_1 = 0$ or $\omega_2 = 0$ implies $\gamma = 0$.

In the following, we assume that $P_0 = (\tau_0, \eta_0)$ verifies (44), in particular $\gamma_0 := \operatorname{Re} \tau_0 = 0$, being the other cases analogous. We look for a symmetrizer r under the form

$$r(\tau, \eta) = \begin{pmatrix} s(\tau, \eta) & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & K' \end{pmatrix},$$

where $K' \geq 1$ is a real number, and s is some 2×2 hermitian matrix, smoothly depending on (τ, η) . Let us focus on the first block of $T\mathcal{A}T^{-1}$ in (67),

$$a' := \begin{pmatrix} -i\omega_1^2 & i \\ -i\omega_1^4 - i\omega_1^2 & i\omega_1^2 \end{pmatrix},$$

as we may symmetrize the second block as we did previously. Recall that a' is purely imaginary when $\gamma = 0$. Let

$$s(\tau, \eta) = \underbrace{\begin{pmatrix} 0 & \epsilon_1 \\ \epsilon_1 & \epsilon_2 \end{pmatrix}}_E + \underbrace{\begin{pmatrix} f(\tau, \eta) & 0 \\ 0 & 0 \end{pmatrix}}_{F(\tau, \eta)} - i\gamma \underbrace{\begin{pmatrix} 0 & -g \\ g & 0 \end{pmatrix}}_G,$$

for suitable real numbers $\epsilon_1, \epsilon_2, g$ and f real valued C^∞ function such that $f(\tau_0, \eta_0) = 0$. By virtue of Proposition 8, we may fix

$$(68) \quad \epsilon_1 = i(\partial_\gamma(\omega_1^2)(\tau_0, \eta_0))^{-1} \in \mathbb{R} \setminus \{0\},$$

The form of s yields ($\gamma_0 = 0$)

$$r(\tau_0, \eta_0) = \begin{pmatrix} 0 & \epsilon_1 & 0 & 0 \\ \epsilon_1 & \epsilon_2 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & K' \end{pmatrix}.$$

Next, we notice that the third column of T^{-1} in (67) is simply e_2 and that the first one evaluated at (τ_0, η_0) (where $\omega_1 = 0$) equals $(a_{12}, 0, 0, 0)^\top$ with $a_{12}(\tau_0, \eta_0) \neq 0$. On the other hand, we have $e_1(\tau_0, \eta_0) = (\mu\chi a_{12}, 0, 0, 0)^\top$ with $\mu\chi a_{12}(\tau_0, \eta_0) \neq 0$. It follows that the two vectors are parallel. Thanks to the Lopatinskiĭ condition, we can find a constant κ_0 such that

$$|\beta(\tau_0, \eta_0)((a_{12}(\tau_0, \eta_0), 0, 0, 0)^\top, e_2(\tau_0, \eta_0))Z'|^2 \geq \kappa_0|Z'|^2, \quad \forall Z' \in \mathbb{C}^2,$$

and consequently there exists a constant C_0 such that

$$|Z_1|^2 + |Z_3|^2 \leq C_0(|Z_2|^2 + |Z_4|^2 + |\tilde{\beta}(\tau_0, \eta_0)Z|^2),$$

for all $Z \in \mathbb{C}^4$. Then

$$\begin{aligned} & \langle r(\tau_0, \eta_0)Z, Z \rangle_{\mathbb{C}^4} + C' C_0 |\tilde{\beta}(\tau_0, \eta_0)Z|^2 \\ &= 2\epsilon_1 \operatorname{Re} \langle Z_1, Z_2 \rangle_{\mathbb{C}^4} + \epsilon_2 |Z_2|^2 - |Z_3|^2 + K'|Z_4|^2 + C' C_0 |\tilde{\beta}(\tau_0, \eta_0)Z|^2 \\ &\geq (C' - \max\{|\epsilon_1|, 1\})(|Z_1|^2 + |Z_3|^2) + (\epsilon_2 - |\epsilon_1| - C' C_0)|Z_2|^2 + (K' - C' C_0)|Z_4|^2. \end{aligned}$$

We choose $C' = \max\{|\epsilon_1|, 1\} + 2$, $\epsilon_2 = |\epsilon_1| + C'C_0 + 2$, $K' = C'C_02 + 2$, and obtain

$$r(\tau_0, \eta_0) + C'C_0\tilde{\beta}^*(\tau_0, \eta_0)\tilde{\beta}(\tau_0, \eta_0) \geq 2\mathbf{I}.$$

Up to shrinking \mathcal{V} we have thus derived the estimate

$$r(\tau, \eta) + C\tilde{\beta}(\tau, \eta)^*\tilde{\beta}(\tau, \eta) \geq \mathbf{I}, \quad \forall (\tau, \eta) \in \mathcal{V},$$

for a suitable constant C .

By Taylor's formula at $(i\delta, \eta)$ with respect to the variable γ , we may write:

$$a'(\tau, \eta) = a'(i\delta, \eta) + \gamma\partial_\gamma a'(i\delta, \eta) + \gamma^2 M(\tau, \eta),$$

for a suitable continuous function M . Recalling that $a'(i\delta, \eta)$ is purely imaginary, we may choose $f := -2\epsilon_1\omega_1^2 - \epsilon_2(\omega_1^4 + \omega_1^2)$, so that the matrix

$$-i(E + F(\tau, \eta))a'(i\delta, \eta) = \begin{pmatrix} -f\omega_1^2 - \epsilon_1(\omega_1^4 + \omega_1^2) & f + \epsilon_1\omega_1^2 \\ -\epsilon_1\omega_1^2 - \epsilon_2(\omega_1^4 + \omega_1^2) & \epsilon_1 + \epsilon_2\omega_1^2 \end{pmatrix}$$

is real and symmetric for all (τ, η) . Therefore, being $\partial_\gamma a'(i\delta, \eta)$ real from Proposition 8, we get

$$\operatorname{Re}(s(\tau, \eta)a'(\tau, \eta)) = \gamma \operatorname{Re}(-iGa' + (E + F)\partial_\gamma a') + \gamma^2 \operatorname{Re}(sM).$$

Setting

$$N := \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad N_1 := a'(i\delta, \eta) - a'(\tau_0, \eta_0),$$

so that $a'(i\delta, \eta) = iN + N_1$, we may write

$$\operatorname{Re}(s(\tau, \eta)a'(\tau, \eta)) = \gamma(GN + E\partial_\gamma a'(i\delta, \eta) + L(\tau, \eta)),$$

where $L(\tau_0, \eta_0) = 0$ (notice that $N_1, F, \gamma M$ are included in L since they vanish at $(\tau_0, \eta_0) = (i\delta_0, \eta_0)$). Having in mind (68), we obtain

$$GN + E\partial_\gamma a'(i\delta_0, \eta_0) = \begin{pmatrix} 0 & 0 \\ 0 & g \end{pmatrix} + \begin{pmatrix} 1 & -1 \\ 1 + \epsilon_2/\epsilon_1 & -\epsilon_2/\epsilon_1 \end{pmatrix}.$$

For g sufficiently large, it is not restrictive to assume that

$$\operatorname{Re}(s(\tau, \eta)a'(\tau, \eta)) \geq \frac{1}{2}\gamma\mathbf{I}, \quad \text{so that} \quad \operatorname{Re}(r(\tau, \eta)T(\tau, \eta)\mathcal{A}(\tau, \eta)T(\tau, \eta)^{-1}) \geq \kappa\gamma\mathbf{I},$$

in \mathcal{V} , for a suitable constant κ . Summarizing, we obtained (63) and (64).

7.7. Pole $\mu = 0$. We consider a point $P_0 = (\tau_0, \eta_0) \in \Sigma$ with $\tau_0 + i\dot{\nu}\eta_0 = \mu_0 = 0$. This is a simple pole for the plasma part of $\mathcal{A}(P_0)$, specifically for a_{12} . In this point the other coefficient a_{21} of the plasma block vanishes and $\omega_1 = |\eta_0| \neq 0$. Moreover, P_0 is a point where the Lopatinskiĭ condition doesn't hold because the Lopatinskiĭ determinant vanishes. We fix a small neighborhood \mathcal{V} of P_0 , not containing any other critical point. From (41), (42) we can assume that both eigenvalues ω_1, ω_2 are bounded and different from zero in \mathcal{V} ; the inequality for ω_2 is true provided ε is taken sufficiently small.

Inspired by [8, 25], we use a different approach to derive the energy estimate by converting problem (40) into a system of simple form. Let us consider the new variables

$$(69) \quad W = \Lambda V^{\text{nc}} := \begin{pmatrix} 1 & 1 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} V^{\text{nc}}.$$

It follows from (40) that

$$(70) \quad \frac{d}{dx_1} \widehat{W} = \Lambda \mathcal{A} \Lambda^{-1} \widehat{W} = \begin{pmatrix} m_1 & -m_2 & 0 & 0 \\ m_2 & -m_1 & 0 & 0 \\ 0 & 0 & 0 & a_{34} \\ 0 & 0 & a_{43} & 0 \end{pmatrix} \widehat{W},$$

where we have set

$$(71) \quad m_1 = \frac{a_{21} + a_{12}}{2}, \quad m_2 = \frac{a_{21} - a_{12}}{2}.$$

Notice that both coefficients m_1 and m_2 have a pole in P_0 . We also remark that $\omega_1^2 = m_1^2 - m_2^2$. The reader may recognize in the plasma block of (70) the form of the symbol in [8], see (4.12).

We define a new matrix T , invertible on \mathcal{V} , in the following way:

$$(72) \quad T^{-1} = \begin{pmatrix} \tilde{T}^{-1} & 0 & 0 \\ 0 & \omega_2 & \omega_2 \\ 0 & \varepsilon\tau & -\varepsilon\tau \end{pmatrix},$$

where

$$\tilde{T}^{-1} = \begin{pmatrix} \mu(m_1 - \omega_1) & -\mu m_2 \\ \mu m_2 & \mu(m_1 - \omega_1) \end{pmatrix}.$$

We have finite

$$\det \tilde{T}^{-1} = \mu^2(m_1 - \omega_1)^2 + \mu^2 m_2^2 = 2m_1 \mu^2(m_1 - \omega_1) \neq 0 \quad \forall (\tau, \eta) \in \mathcal{V},$$

and

$$T = \begin{pmatrix} \tilde{T} & 0 & 0 \\ 0 & (2\omega_2)^{-1} & (2\varepsilon\tau)^{-1} \\ 0 & (2\omega_2)^{-1} & -(2\varepsilon\tau)^{-1} \end{pmatrix},$$

where

$$\tilde{T} = \frac{1}{\det \tilde{T}^{-1}} \begin{pmatrix} \mu(m_1 - \omega_1) & \mu m_2 \\ -\mu m_2 & \mu(m_1 - \omega_1) \end{pmatrix}.$$

The matrix T is such that

$$(73) \quad T \begin{pmatrix} m_1 & -m_2 & 0 & 0 \\ m_2 & -m_1 & 0 & 0 \\ 0 & 0 & 0 & a_{34} \\ 0 & 0 & a_{43} & 0 \end{pmatrix} T^{-1} = \mathcal{A}' := \begin{pmatrix} -\omega_1 & -2m_2 & 0 & 0 \\ 0 & \omega_1 & 0 & 0 \\ 0 & 0 & -\omega_2 & 0 \\ 0 & 0 & 0 & \omega_2 \end{pmatrix}, \quad \forall (\tau, \eta) \in \mathcal{V}.$$

We shall derive the energy estimates directly by making use of the ODE system derived by the above transformation, instead of constructing the symmetrizer of this problem. This will be done in the Subsection 8.0.3.

7.8. Pole of (P2). We consider a point $P_0 = (\tau_0, \eta_0) \in \Sigma$ with $\gamma_0 = 0$ and $\delta_0 + \dot{\nu}\eta_0 = +\frac{|\dot{H}|}{\sqrt{\dot{\rho}(1+\dot{\alpha}H^2)}}\eta_0$, with $\eta_0 > 0$. (We shall not detail the case $\gamma_0 = 0$, $\delta_0 + \dot{\nu}\eta_0 = -\frac{|\dot{H}|}{\sqrt{\dot{\rho}(1+\dot{\alpha}H^2)}}\eta_0$, that is entirely similar.)

This is a simple pole for the plasma part of $\mathcal{A}(P_0)$, specifically for a_{21} , and the eigenvalues $\pm\omega_1$ have a simple pole as well. In this point the other coefficient a_{12} of the plasma block is well defined and different from zero. In P_0 the quantity χ vanishes, and $\chi\omega_1$ is well defined and different from zero because

$$\chi^2 \omega_1^2(P_0) = \eta_0^2 / (1 + \dot{\alpha} \dot{H}^2) > 0.$$

Moreover, at P_0 the Lopatinskiĭ condition is satisfied. We fix a small neighborhood \mathcal{V} of P_0 , not containing any other critical point, where we assume that $a_{12} \neq 0$ and $\chi\omega_1 \neq 0$.

We deal with this case by using an argument inspired by the work of Majda and Osher [15], see also [24].

Let us set

$$\tilde{\tau} = \gamma + i\tilde{\delta} := \mu - i \frac{|\dot{H}|}{\sqrt{\dot{\rho}(1 + \dot{\alpha}\dot{H}^2)}} \eta,$$

which means that P_0 corresponds to $\tilde{\tau} = 0$. Let us consider the variables W defined in (69), with the ODE (70).

Recalling that $m_1 - m_2 = a_{12} \neq 0$, we define a new matrix T , invertible on \mathcal{V} , in the following way:

$$(74) \quad T^{-1} = \begin{pmatrix} 1 & i(m_1 - m_2)^{-1} & 0 & 0 \\ -1 & i(m_1 - m_2)^{-1} & 0 & 0 \\ 0 & 0 & \omega_2 & \omega_2 \\ 0 & 0 & \varepsilon\tau & -\varepsilon\tau \end{pmatrix}.$$

The matrix T is such that

$$(75) \quad T \begin{pmatrix} m_1 & -m_2 & 0 & 0 \\ m_2 & -m_1 & 0 & 0 \\ 0 & 0 & 0 & a_{34} \\ 0 & 0 & a_{43} & 0 \end{pmatrix} T^{-1} = \mathcal{A}'' := \begin{pmatrix} 0 & i & 0 & 0 \\ -i\omega_1^2 & 0 & 0 & 0 \\ 0 & 0 & -\omega_2 & 0 \\ 0 & 0 & 0 & \omega_2 \end{pmatrix}, \quad \forall (\tau, \eta) \in \mathcal{V}.$$

Denote by

$$\omega_0(\tau, \eta) = -\omega_1^2 \tilde{\tau} = ie_0(i\delta, \eta) + \gamma d_0(\tau, \eta)$$

with $e_0(i\delta, \eta) \in \mathbb{R}$. By a direct computation and (41) it follows that

$$\omega_0(\tau_0, \eta_0) = i \frac{|\dot{H}|}{\sqrt{\dot{\rho}}} \frac{\dot{\alpha}\dot{H}^2}{2(1 + \dot{\alpha}\dot{H}^2)^{5/2}} \eta_0^3,$$

which implies $e_0(i\delta, \eta) > 0$, because $\eta_0 > 0$. As in [24] we look for a symmetrizer r under the form

$$r(\tau, \eta) = \begin{pmatrix} \tilde{r}(\tau, \eta) & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & K' \end{pmatrix},$$

where $K' \geq 2$ is a real number, and \tilde{r} is a 2×2 hermitian matrix

$$\tilde{r}(\tau, \eta) = \begin{pmatrix} d_1 & d_2 + i\gamma s \\ d_2 - i\gamma s & d_1 \frac{\tilde{\delta}}{e_0} \end{pmatrix},$$

with $d_1 > 0, d_2 < 0$ and $s > 0$ constants to be determined later. We easily obtain

$$(76) \quad \begin{aligned} \operatorname{Re}(r(\tau, \eta)\mathcal{A}''(\tau, \eta)) &= \operatorname{Re} \begin{pmatrix} (d_2 + i\gamma s) \frac{i\omega_0}{\tilde{\tau}} & id_1 & 0 & 0 \\ id_1 \frac{\tilde{\delta}\omega_0}{e_0\tilde{\tau}} & \gamma s + id_2 & 0 & 0 \\ 0 & 0 & \omega_2 & 0 \\ 0 & 0 & 0 & K'\omega_2 \end{pmatrix} \\ &= \begin{pmatrix} R(\tau, \eta) & \bar{J}(\tau, \eta) & 0 & 0 \\ J(\tau, \eta) & \gamma s & 0 & 0 \\ 0 & 0 & \operatorname{Re}\omega_2 & 0 \\ 0 & 0 & 0 & K' \operatorname{Re}\omega_2 \end{pmatrix}, \end{aligned}$$

where

$$R(\tau, \eta) = \frac{1}{2} \left((d_2 + i\gamma s) \frac{i\omega_0}{\tilde{\tau}} + (d_2 - i\gamma s) \frac{\overline{i\omega_0}}{\bar{\tilde{\tau}}} \right), \quad J(\tau, \eta) = \frac{id_1}{2} \left(\frac{\tilde{\delta}\omega_0}{e_0\tilde{\tau}} - 1 \right).$$

By calculation we get

$$\begin{aligned} R(\tau, \eta) &= \frac{1}{2|\tilde{\tau}|^2} \left\{ (d_2 + i\gamma s)(-e_0 + i\gamma d_0)(\gamma - i\tilde{\delta}) + (d_2 - i\gamma s)(-e_0 - i\gamma \bar{d}_0)(\gamma + i\tilde{\delta}) \right\} \\ &= \frac{1}{2|\tilde{\tau}|^2} \left\{ d_2(-e_0 - \gamma \operatorname{Im} d_0 + \tilde{\delta} \operatorname{Re} d_0) - s(\gamma^2 \operatorname{Re} d_0 + \tilde{\delta} e_0 + \gamma \tilde{\delta} \operatorname{Im} d_0) \right\}. \end{aligned}$$

By observing that in \mathcal{V} , $e_0(i\delta, \eta) > 0$, γ and $\tilde{\delta}$ are very small and $\operatorname{Re} d_0, \operatorname{Im} d_0$ are bounded, we easily obtain the following inequalities

$$R(\tau, \eta) \geq \frac{\gamma}{|\tilde{\tau}|^2} \left(-\frac{e_0}{2} d_2 - C_1 |\tilde{\tau}| s \right), \quad |J(\tau, \eta)| \leq \frac{d_1 \gamma}{|\tilde{\tau}|}, \quad \forall (\tau, \eta) \in \mathcal{V},$$

for a suitable positive constant C_1 . It follows that for all $Z = (Z_1, Z_2)^\top \in \mathbb{C}^2$,

$$\begin{aligned} (77) \quad \bar{Z}^\top \begin{pmatrix} R(\tau, \eta) & \bar{J}(\tau, \eta) \\ J(\tau, \eta) & \gamma s \end{pmatrix} Z &= R(\tau, \eta) |Z_1|^2 + \gamma s |Z_2|^2 + 2 \operatorname{Re}(J(\tau, \eta) Z_1 \bar{Z}_2) \\ &\geq R(\tau, \eta) |Z_1|^2 + \gamma s |Z_2|^2 - 2 \frac{d_1 \gamma}{|\tilde{\tau}|} |Z_1| |Z_2| \\ &\geq R(\tau, \eta) |Z_1|^2 + \gamma s |Z_2|^2 - \left(\frac{\epsilon \gamma}{|\tilde{\tau}|^2} |Z_1|^2 + \frac{\gamma d_1^2}{\epsilon} |Z_2|^2 \right) \\ &\geq \left(-\frac{e_0}{2} d_2 - C_1 |\tilde{\tau}| s - \epsilon \right) \frac{\gamma}{|\tilde{\tau}|^2} |Z_1|^2 + \gamma \left(s - \frac{d_1^2}{\epsilon} \right) |Z_2|^2, \end{aligned}$$

for $\epsilon > 0$ to be determined later.

Now we consider the matrix $\Lambda^{-1} T^{-1}$, for Λ defined in (69) and T as in (74). We compute

$$\Lambda^{-1} T^{-1}(\tau_0, \eta_0) = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & ia_{12}(\tau_0, \eta_0)^{-1} & 0 & 0 \\ 0 & 0 & \omega_2(\tau_0, \eta_0) & \omega_2(\tau_0, \eta_0) \\ 0 & 0 & \varepsilon \tau_0 & -\varepsilon \tau_0 \end{pmatrix},$$

where we notice that the third column of the matrix is the eigenvector $e_2(\tau_0, \eta_0)$. At P_0 we have

$$e_1(\tau_0, \eta_0) = -(0, \mu \chi \omega_1(\tau_0, \eta_0), 0, 0)^\top \neq 0,$$

which is therefore parallel to the second column of the above matrix. Since at P_0 the Lopatinskiĭ condition is satisfied, it follows that there exists a constant C_0 such that

$$(78) \quad |(Z_2, Z_3)|^2 \leq C_0 (|(Z_1, Z_4)|^2 + |\beta(\tau_0, \eta_0) \Lambda^{-1} T^{-1}(\tau_0, \eta_0) Z|^2)$$

for all $Z = (Z_1, Z_2, Z_3, Z_4)^\top \in \mathbb{C}^4$. Moreover, recalling that at P_0 it holds $\gamma = \tilde{\delta} = 0$, we have

$$\begin{aligned} \langle r(\tau_0, \eta_0) Z, Z \rangle_{\mathbb{C}^4} &= d_1 |Z_1|^2 - |Z_3|^2 + K' |Z_4|^2 + 2d_2 \operatorname{Re}(Z_1 \bar{Z}_2) \\ &\geq (d_1 + d_2) |Z_1|^2 + d_2 |Z_2|^2 - |Z_3|^2 + K' |Z_4|^2. \end{aligned}$$

It implies

$$\begin{aligned} \langle r(\tau_0, \eta_0) Z, Z \rangle_{\mathbb{C}^4} - 2d_2 C_0 |\beta(\tau_0, \eta_0) \Lambda^{-1} T^{-1}(\tau_0, \eta_0) Z|^2 \\ \geq (d_1 + (1 + 2C_0)d_2) |Z_1|^2 - d_2 |Z_2|^2 - (2d_2 + 1) |Z_3|^2 + (K' + 2d_2 C_0) |Z_4|^2. \end{aligned}$$

Now, we choose $d_2 < -2$, $d_1 > -2(1 + C_0)d_2$, $\epsilon = -\frac{e_0}{4} d_2$, $s > \frac{d_1^2}{\epsilon}$ and K' large enough. We obtain

$$r(\tau_0, \eta_0) + C(\beta(\tau_0, \eta_0) \Lambda^{-1} T^{-1}(\tau_0, \eta_0))^* \beta(\tau_0, \eta_0) \Lambda^{-1} T^{-1}(\tau_0, \eta_0) \geq 2\mathbf{I},$$

for a suitable constant C . Up to shrinking \mathcal{V} we have thus derived the estimate

$$(79) \quad r(\tau, \eta) + C(\beta(\tau, \eta) \Lambda^{-1} T^{-1}(\tau, \eta))^* \beta(\tau, \eta) \Lambda^{-1} T^{-1}(\tau, \eta) \geq \mathbf{I}, \quad \forall (\tau, \eta) \in \mathcal{V}.$$

Moreover, from (75), (76), (77) we have

$$\begin{aligned}
& \operatorname{Re} (r(\tau, \eta) T(\tau, \eta) \Lambda \mathcal{A}(\tau, \eta) (T(\tau, \eta) \Lambda)^{-1}) \\
(80) \quad & = \operatorname{Re} (r(\tau, \eta) T(\tau, \eta) \mathcal{A}''(\tau, \eta) T(\tau, \eta)^{-1}) \geq \kappa \begin{pmatrix} \frac{\gamma}{|\tilde{\tau}|^2} & 0 & 0 & 0 \\ 0 & \gamma & 0 & 0 \\ 0 & 0 & \gamma & 0 \\ 0 & 0 & 0 & \gamma \end{pmatrix}, \quad \forall (\tau, \eta) \in \mathcal{V},
\end{aligned}$$

for a positive constant κ .

7.9. Pole $\tau = 0$. We consider a point $P_0 = (\tau_0, \eta_0) \in \Sigma$ with $\tau_0 = 0$. This is a simple pole for the vacuum part of $\mathcal{A}(P_0)$, specifically for a_{34} . In this point the other coefficient a_{43} of the vacuum block vanishes and $\omega_2 = |\eta_0| \neq 0$. Moreover, P_0 is a point where the Lopatinskiĭ condition doesn't hold because the Lopatinskiĭ determinant vanishes. We fix a small neighborhood \mathcal{V} of P_0 , not containing any other critical point. From (41), (42) we can assume that both eigenvalues ω_1, ω_2 are bounded and different from zero in \mathcal{V} .

We use the same approach of Subsection 7.7 to derive the energy estimate by converting problem (40) into a system of simple form. Let us consider the new variables

$$(81) \quad W = \Lambda' V^{\text{nc}} := \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & -1 & 1 \end{pmatrix} V^{\text{nc}}.$$

It follows from (40) that

$$(82) \quad \frac{d}{dx_1} \widehat{W} = \begin{pmatrix} 0 & a_{12} & 0 & 0 \\ a_{21} & 0 & 0 & 0 \\ 0 & 0 & n_1 & -n_2 \\ 0 & 0 & n_2 & -n_1 \end{pmatrix} \widehat{W},$$

where we have set

$$(83) \quad n_1 = \frac{a_{43} + a_{34}}{2}, \quad n_2 = \frac{a_{43} - a_{34}}{2}.$$

Notice that both coefficients n_1 and n_2 have a pole in P_0 . We also remark that $\omega_2^2 = n_1^2 - n_2^2$. We define a new matrix T , invertible on \mathcal{V} , in the following way:

$$T^{-1} = \begin{pmatrix} \mu\chi a_{12} & \mu\chi a_{12} & 0 \\ -\mu\chi\omega_1 & \mu\chi\omega_1 & 0 \\ 0 & 0 & \tilde{T}^{-1} \end{pmatrix},$$

where

$$\tilde{T}^{-1} = \begin{pmatrix} \tau(n_1 - \omega_2) & -\tau n_2 \\ \tau n_2 & \tau(n_1 - \omega_2) \end{pmatrix}.$$

We have

$$\det \tilde{T}^{-1} = \tau^2(n_1 - \omega_2)^2 + \tau^2 n_2^2 = 2\tau^2 n_1(n_1 - \omega_2) \neq 0 \quad \forall (\tau, \eta) \in \mathcal{V},$$

and

$$T = \begin{pmatrix} (2\mu\chi a_{12})^{-1} & -(2\mu\chi\omega_1)^{-1} & 0 \\ (2\mu\chi a_{12})^{-1} & (2\mu\chi\omega_1)^{-1} & 0 \\ 0 & 0 & \tilde{T} \end{pmatrix},$$

where

$$\tilde{T} = \frac{1}{\det \tilde{T}^{-1}} \begin{pmatrix} \tau(n_1 - \omega_2) & \tau n_2 \\ -\tau n_2 & \tau(n_1 - \omega_2) \end{pmatrix}.$$

The matrix T is such that

$$(84) \quad T \begin{pmatrix} 0 & a_{12} & 0 & 0 \\ a_{21} & 0 & 0 & 0 \\ 0 & 0 & n_1 & -n_2 \\ 0 & 0 & n_2 & -n_1 \end{pmatrix} T^{-1} = \mathcal{A}''' := \begin{pmatrix} -\omega_1 & 0 & 0 & 0 \\ 0 & \omega_1 & 0 & 0 \\ 0 & 0 & -\omega_2 & -2n_2 \\ 0 & 0 & 0 & \omega_2 \end{pmatrix}, \quad \forall (\tau, \eta) \in \mathcal{V}.$$

As for the case $\mu = 0$, we shall derive the energy estimates directly by making use of the ODE system derived by the above transformation, instead of constructing the symmetrizer of this problem. This will be done in the Subsection 8.0.5.

8. ENERGY ESTIMATE

We now turn to the derivation of the estimate (24). After the reduction of the problem to the homogeneous equation and the elimination of the front, recall that we are considering a function $V \in H^1(\Omega)$ such that

$$\begin{cases} (\tau \mathcal{A}_0 + i\eta \mathcal{A}_2 + \mathcal{A}_1 \partial_1) \widehat{V} = 0 & x_1 > 0, \\ \beta(\tau, \eta) \widehat{V}^{\text{nc}} = \widehat{h} & x_1 = 0, \end{cases}$$

where

$$\widehat{h} = Q(\tau, \eta) \widehat{g} = \begin{pmatrix} 0 & 1 & 0 \\ -\varepsilon \dot{\mathcal{H}} \tau & 0 & \tau + i\dot{v}\eta \\ \bar{\tau} - i\dot{v}\eta & 0 & \varepsilon \dot{\mathcal{H}} \bar{\tau} \end{pmatrix} \widehat{g}, \quad \forall (\tau, \eta) \in \Sigma.$$

The previous analysis shows that for all $(\tau_0, \eta_0) \in \Sigma$, there exists a neighborhood \mathcal{V} of (τ_0, η_0) and mappings defined on this neighborhood that satisfy suitable properties. Because Σ is a C^∞ compact manifold, there exists a finite covering $(\mathcal{V}_1, \dots, \mathcal{V}_I)$ of Σ by such neighborhoods, and a smooth partition of unity (χ_1, \dots, χ_I) associated with this covering. The χ_i 's are nonnegative C^∞ functions with

$$\text{supp } \chi_i \subset \mathcal{V}_i, \quad \sum_{i=1}^I \chi_i^2 = 1.$$

We consider the different cases.

8.0.1. *The first case.* \mathcal{V}_i is a neighborhood of an interior point or a neighborhood of a boundary point corresponding to cases in Subsections 7.4 or 7.6, that is boundary points that are not poles and such that the Lopatinskiĭ condition is satisfied.

On such a neighborhood there exist two C^∞ mappings $r_i \in T_i$ such that r_i is hermitian, T_i has values in $GL_4(\mathbb{C})$, and the following estimates hold for all $(\tau, \eta) \in \mathcal{V}_i$:

$$(85a) \quad \text{Re}(r_i(\tau, \eta) T_i(\tau, \eta) \mathcal{A}(\tau, \eta) T_i(\tau, \eta)^{-1}) \geq \kappa_i \gamma \mathbf{I},$$

$$(85b) \quad r_i(\tau, \eta) + C(\beta(\tau, \eta) T_i(\tau, \eta)^{-1})^* (\beta(\tau, \eta) T_i(\tau, \eta)^{-1}) \geq \mathbf{I},$$

see (63), (64).

We define

$$U_i(\tau, x_1, \eta) := \chi_i(\tau, \eta) T_i(\tau, \eta) \widehat{V}^{\text{nc}}(\tau, x_1, \eta).$$

Here r_i and T_i are only defined on \mathcal{V}_i , but for convenience we first extend the definition to the whole Σ , then extend χ_i, r_i and T_i to the whole set of frequencies Ξ , as homogeneous mappings of degree 0 with respect to (τ, η) . We easily show that U_i satisfies

$$\begin{cases} \frac{dU_i}{dx_1} = T_i(\tau, \eta) \mathcal{A}(\tau, \eta) T_i(\tau, \eta)^{-1} U_i & x_1 > 0, \\ \beta(\tau, \eta) T_i(\tau, \eta)^{-1} U_i = \chi_i \widehat{h} & x_1 = 0. \end{cases}$$

We take the scalar product of the above ordinary differential equation with $r_i U_i$ and integrate w.r.t. x_1 on $[0, +\infty)$. Then we take the real part and use (85a) to obtain

$$\operatorname{Re} \int_0^{+\infty} \langle r_i U_i, \frac{dU_i}{dx_1} \rangle dx_1 = \operatorname{Re} \int_0^{+\infty} \langle U_i, r_i T_i \mathcal{A} T_i^{-1} U_i \rangle dx_1 \geq \kappa_i \gamma \int_0^{+\infty} |U_i(\tau, x_1, \eta)|^2 dx_1.$$

On the other hand, from (85b) we get

$$\operatorname{Re} \int_0^{+\infty} \langle r_i U_i, \frac{dU_i}{dx_1} \rangle dx_1 = -\frac{1}{2} r_i |U_i(\tau, 0, \eta)|^2 \leq \frac{C}{2} |\beta T_i^{-1} U_i(\tau, 0, \eta)|^2 - \frac{1}{2} |U_i(\tau, 0, \eta)|^2.$$

This yields the classical Kreiss' estimate

$$(86) \quad \kappa_i \gamma \int_0^{+\infty} |U_i(\tau, x_1, \eta)|^2 dx_1 + \frac{1}{2} |U_i(\tau, 0, \eta)|^2 \leq C_i \chi_i(\tau, \eta)^2 |\widehat{h}|^2.$$

Now we use the definition of U_i and a uniform bound for $\|T_i(\tau, \eta)^{-1}\|$ on the support of χ_i to derive

$$(87) \quad \gamma \chi_i(\tau, \eta)^2 \int_0^{+\infty} |\widehat{V}^{\text{nc}}(\tau, x_1, \eta)|^2 dx_1 + \chi_i(\tau, \eta)^2 |\widehat{V}^{\text{nc}}(\tau, 0, \eta)|^2 \leq C_i \chi_i(\tau, \eta)^2 |\widehat{h}|^2,$$

for all $(\tau, \eta) \in \mathbb{R}^+ \cdot \mathcal{V}_i$.

8.0.2. *The second case.* \mathcal{V}_i is a neighborhood of a boundary point which is a zero of the Lopatinskiĭ determinant but not a pole, see Subsection 7.5.

On such a neighborhood there exist two C^∞ mappings r_i e T_i such that r_i is hermitian, T_i has values in $GL_4(\mathbb{C})$, and the following estimates hold for all $(\tau, \eta) \in \mathcal{V}_i$:

$$(88a) \quad \operatorname{Re}(r_i(\tau, \eta) T_i(\tau, \eta) \mathcal{A}(\tau, \eta) T_i(\tau, \eta)^{-1}) \geq \kappa_i \gamma^3 \mathbf{I},$$

$$(88b) \quad r_i(\tau, \eta) + C(\beta(\tau, \eta) T_i(\tau, \eta)^{-1})^* (\beta(\tau, \eta) T_i(\tau, \eta)^{-1}) \geq \gamma^2 \mathbf{I},$$

see (65), (66). As done before, we first extend the definition of r_i and T_i to the whole hemisphere Σ . Then we extend χ_i and T_i to the whole set of frequencies Ξ , as homogeneous mappings of degree 0 with respect to (τ, η) , and we extend r_i to the whole set of frequencies Ξ , as homogeneous mappings of degree 2 with respect to (τ, η) . Thus (88) reads

$$(89a) \quad \operatorname{Re}(r_i(\tau, \eta) T_i(\tau, \eta) \mathcal{A}(\tau, \eta) T_i(\tau, \eta)^{-1}) \geq \kappa_i \gamma^3 \mathbf{I},$$

$$(89b) \quad r_i(\tau, \eta) + C(|\tau|^2 + \eta^2) (\beta(\tau, \eta) T_i(\tau, \eta)^{-1})^* (\beta(\tau, \eta) T_i(\tau, \eta)^{-1}) \geq \gamma^2 \mathbf{I},$$

for all $(\tau, \eta) \in \mathbb{R}^+ \cdot \mathcal{V}_i$. We define

$$U_i(\tau, x_1, \eta) := \chi_i(\tau, \eta) T_i(\tau, \eta) \widehat{V}^{\text{nc}}(\tau, x_1, \eta).$$

Because \mathcal{V}_i does not contain any pole we still have

$$\begin{cases} \frac{dU_i}{dx_1} = T_i(\tau, \eta) \mathcal{A}(\tau, \eta) T_i(\tau, \eta)^{-1} U_i & x_1 > 0, \\ \beta(\tau, \eta) T_i(\tau, \eta)^{-1} U_i = \chi_i \widehat{h} & x_1 = 0, \end{cases}$$

Performing the same calculations as above, with only (89) instead of (85), yields

$$(90) \quad \gamma \chi_i(\tau, \eta)^2 \int_0^{+\infty} |\widehat{V}^{\text{nc}}(\tau, x_1, \eta)|^2 dx_1 + \chi_i(\tau, \eta)^2 |\widehat{V}^{\text{nc}}(\tau, 0, \eta)|^2 \leq \frac{C_i}{\gamma^2} (|\tau|^2 + \eta^2) \chi_i(\tau, \eta)^2 |\widehat{h}|^2,$$

for all $(\tau, \eta) \in \mathbb{R}^+ \cdot \mathcal{V}_i$.

8.0.3. *The third case.* \mathcal{V}_i is a neighborhood of the boundary point $P_0 = (\tau_0, \eta_0)$ with $\mu_0 = \tau_0 + i\dot{\nu}\eta_0 = 0$. This is a pole for the plasma part of \mathcal{A} , specifically for a_{12} , and it is a zero for the Lopatinskiĭ determinant.

On such a neighborhood there exists a C^∞ mapping T_i defined on \mathcal{V}_i with values in $GL_4(\mathbb{C})$, see (72), and such that for the matrix defined in (70), the equation (73) is satisfied. As done above, we first extend the definition of T_i to the whole hemisphere Σ . Then we extend χ_i and T_i to the whole set of frequencies Ξ , as homogeneous mappings of degree 0 with respect to (τ, η) .

We define

$$U_i(\tau, x_1, \eta) := \chi_i(\tau, \eta) T_i(\tau, \eta) \Lambda \widehat{V}^{\text{nc}}(\tau, x_1, \eta),$$

where the 4×4 constant matrix Λ is defined in (69). We deduce from (23), (70), (73) the following problem for U_i

$$(91) \quad \begin{cases} \frac{dU_i}{dx_1} = \mathcal{A}'(\tau, \eta) U_i & x_1 > 0, \\ \beta(\tau, \eta) \Lambda^{-1} T(\tau, \eta)^{-1} U_i = \chi_i \widehat{h} & x_1 = 0. \end{cases}$$

More specifically, the ODE system reads

$$(92a) \quad \frac{dU_{i,1}}{dx_1} = -\omega_1 U_{i,1} - 2m_2 U_{i,2},$$

$$(92b) \quad \frac{dU_{i,2}}{dx_1} = \omega_1 U_{i,2},$$

$$(92c) \quad \frac{dU_{i,3}}{dx_1} = -\omega_2 U_{i,3},$$

$$(92d) \quad \frac{dU_{i,4}}{dx_1} = \omega_2 U_{i,4}.$$

Recall that m_2 is defined in (71) and that it has a pole at P_0 . \mathcal{V}_i is sufficiently small so that we may assume that

$$\operatorname{Re} \omega_1(\tau, \eta) \geq \kappa_i (|\tau|^2 + \eta^2)^{1/2}, \quad \operatorname{Re} \omega_2(\tau, \eta) \geq \kappa_i (|\tau|^2 + \eta^2)^{1/2}, \quad \forall (\tau, \eta) \in \mathbb{R}^+ \cdot \mathcal{V}_i,$$

for a suitable constant $\kappa_i > 0$. The above inequality for ω_1 is obvious because $\omega_1(P_0) = |\eta_0| \neq 0$. The inequality concerning ω_2 is true provided ϵ is taken sufficiently small, as it follows from $\omega_2^2(\tau_0, \eta_0) = \eta_0^2(1 - \epsilon^2 \dot{\nu}^2)$.

Since $U_{i,2}(x_1)$ and $U_{i,4}(x_1)$ belong to $L^2(\mathbb{R}^+)$, from (92b) and (92d) we get $U_{i,2} \equiv 0$ and $U_{i,4} \equiv 0$. Hence, even if m_2 has a pole in P_0 , the first equation (92a) is well defined and actually reads

$$(93) \quad \frac{dU_{i,1}}{dx_1} = -\omega_1 U_{i,1}.$$

From (92c), (93) and the above properties of ω_1 and ω_2 we derive

$$(94) \quad \begin{aligned} (|\tau|^2 + \eta^2)^{1/2} \int_0^{+\infty} |U_{i,1}(\tau, x_1, \eta)|^2 dx_1 &\leq C |U_{i,1}(\tau, 0, \eta)|^2, \\ (|\tau|^2 + \eta^2)^{1/2} \int_0^{+\infty} |U_{i,3}(\tau, x_1, \eta)|^2 dx_1 &\leq C |U_{i,3}(\tau, 0, \eta)|^2, \end{aligned}$$

for all $(\tau, \eta) \in \mathbb{R}^+ \cdot \mathcal{V}_i$. On the other hand, the boundary condition in (91) reduces to

$$(95) \quad \begin{pmatrix} \frac{1}{2} \mu (m_1 - \omega_1 - m_2) & -\dot{\mathcal{H}} \omega_2 \\ \frac{1}{2} \epsilon \dot{\mathcal{H}} \tau \mu (m_1 - \omega_1 + m_2) & \epsilon \tau \mu \end{pmatrix} \begin{pmatrix} U_{i,1} \\ U_{i,3} \end{pmatrix} = \chi_i \widehat{h}.$$

Let us denote by $\Delta'(\tau, \eta)$ the determinant of the matrix in (95). Substituting (71) in the calculation of this determinant gives

$$\Delta'(\tau, \eta) := \frac{1}{2} \varepsilon \tau \mu \left(\mu a_{12} - \mu \omega_1 + \mathcal{H}^2 \omega_2 (a_{21} - \omega_1) \right).$$

If \mathcal{V}_i is taken sufficiently small, it is easily verified that there exists a positive constant C such that

$$|\Delta'(\tau, \eta)| \geq C\gamma, \quad \forall (\tau, \eta) \in \mathcal{V}_i.$$

Even if from its definition $\Delta'(\tau, \eta)$ appears as a homogeneous function of degree 4 with respect to (τ, η) , actually it is a homogeneous function of degree 0, as follows from the extension of T_i that we did to the whole set of frequencies Ξ . Therefore we have

$$|\Delta'(\tau, \eta)| \geq C\gamma(|\tau|^2 + \eta^2)^{-1/2}, \quad \forall (\tau, \eta) \in \mathbb{R}^+ \cdot \mathcal{V}_i,$$

and from (95) it follows

$$(96) \quad |U_{i,1}(\tau, 0, \eta)| + |U_{i,3}(\tau, 0, \eta)| \leq C \frac{(|\tau|^2 + \eta^2)^{1/2}}{\gamma} |\chi_i \widehat{h}|.$$

Now, combining (94), (96) and using $(|\tau|^2 + \eta^2)^{1/2} \geq \gamma$ gives

$$\begin{aligned} \gamma \int_0^{+\infty} (|U_{i,1}(\tau, x_1, \eta)|^2 + |U_{i,3}(\tau, x_1, \eta)|^2) dx_1 \\ + |U_{i,1}(\tau, 0, \eta)|^2 + |U_{i,3}(\tau, 0, \eta)|^2 \leq \frac{C_i}{\gamma^2} (|\tau|^2 + \eta^2) |\chi_i(\tau, \eta) \widehat{h}|^2, \end{aligned}$$

for all $(\tau, \eta) \in \mathbb{R}^+ \cdot \mathcal{V}_i$. Finally, also recalling that $U_{i,2} \equiv 0$ and $U_{i,4} \equiv 0$, we obtain

$$(97) \quad \gamma \chi_i(\tau, \eta)^2 \int_0^{+\infty} |\widehat{V}^{\text{nc}}(\tau, x_1, \eta)|^2 dx_1 + \chi_i(\tau, \eta)^2 |\widehat{V}^{\text{nc}}(\tau, 0, \eta)|^2 \leq \frac{C_i}{\gamma^2} (|\tau|^2 + \eta^2) \chi_i(\tau, \eta)^2 |\widehat{h}|^2,$$

for all $(\tau, \eta) \in \mathbb{R}^+ \cdot \mathcal{V}_i$.

8.0.4. *The fourth case.* \mathcal{V}_i is a neighborhood of the boundary point $P_0 = (\tau_0, \eta_0)$ with $\gamma_0 = 0$ and $\delta_0 + \dot{\nu}\eta_0 = +\frac{|\dot{H}|}{\sqrt{\dot{\rho}(1+\dot{\alpha}\dot{H}^2)}}\eta_0$, with $\eta_0 > 0$. (The case $\gamma_0 = 0$, $\delta_0 + \dot{\nu}\eta_0 = -\frac{|\dot{H}|}{\sqrt{\dot{\rho}(1+\dot{\alpha}\dot{H}^2)}}\eta_0$ can be studied similarly.) This is a pole for the plasma part of $\mathcal{A}(P_0)$, specifically for a_{21} , and the eigenvalues $\pm\omega_1$ have a pole as well. Moreover, at P_0 the Lopatinskiĭ condition is satisfied.

On such a neighborhood there exist two C^∞ mappings r_i and T_i (defined in (74)) such that r_i is hermitian, T_i has values in $GL_4(\mathbb{C})$, and such that the inequalities (79), (80) are satisfied.

As done above, we first extend the definition of r_i and T_i to the whole hemisphere Σ . Then we extend χ_i, r_i and T_i to the whole set of frequencies Ξ , as homogeneous mappings of degree 0 with respect to (τ, η) . Consequently, r_i and T_i satisfy

$$\text{Re} (r_i(\tau, \eta) T_i(\tau, \eta) \Lambda \mathcal{A}(\tau, \eta) (T_i(\tau, \eta) \Lambda)^{-1}) \geq \kappa_i \begin{pmatrix} \gamma \frac{|\tau|^2 + \eta^2}{|\widehat{\tau}|^2} & 0 & 0 & 0 \\ 0 & \gamma & 0 & 0 \\ 0 & 0 & \gamma & 0 \\ 0 & 0 & 0 & \gamma \end{pmatrix},$$

$$r_i(\tau, \eta) + C (\beta(\tau, \eta) \Lambda^{-1} T_i^{-1}(\tau, \eta))^* \beta(\tau, \eta) \Lambda^{-1} T_i^{-1}(\tau, \eta) \geq \text{I},$$

for all $(\tau, \eta) \in \mathbb{R}^+ \cdot \mathcal{V}_i$. We define

$$U_i(\tau, x_1, \eta) := \chi_i(\tau, \eta) T_i(\tau, \eta) \Lambda \widehat{V}^{\text{nc}}(\tau, x_1, \eta).$$

Using the same argument as in *the first case*, see 8.0.1, we get the estimate

$$(98) \quad \gamma \chi_i(\tau, \eta)^2 \int_0^{+\infty} |\widehat{V}^{\text{nc}}(\tau, x_1, \eta)|^2 dx_1 + \chi_i(\tau, \eta)^2 |\widehat{V}^{\text{nc}}(\tau, 0, \eta)|^2 \leq C_i \chi_i(\tau, \eta)^2 |\widehat{h}|^2,$$

for all $(\tau, \eta) \in \mathbb{R}^+ \cdot \mathcal{V}_i$.

8.0.5. *The fifth case.* \mathcal{V}_i is a neighborhood of the boundary point $P_0 = (\tau_0, \eta_0)$ with $\tau_0 = 0$. This is a pole for the vacuum part of \mathcal{A} , specifically for a_{34} , and it is a zero for the Lopatinskiĭ determinant.

On such a neighborhood there exists a C^∞ mapping T_i defined on \mathcal{V}_i with values in $GL_4(\mathbb{C})$, and such that for the matrix defined in (82), the equation (84) is satisfied. As done above, we first extend the definition of T_i to the whole hemisphere Σ . Then we extend χ_i and T_i to the whole set of frequencies Ξ , as homogeneous mappings of degree 0 with respect to (τ, η) .

We define

$$U_i(\tau, x_1, \eta) := \chi_i(\tau, \eta) T_i(\tau, \eta) \Lambda' \widehat{V}^{\text{nc}}(\tau, x_1, \eta),$$

where the 4×4 constant matrix Λ' is defined in (81). We deduce from (23), (82), (84) the following problem for U_i

$$(99) \quad \begin{cases} \frac{dU_i}{dx_1} = \mathcal{A}'(\tau, \eta) U_i & x_1 > 0, \\ \beta(\tau, \eta) \Lambda'^{-1} T(\tau, \eta)^{-1} U_i = \chi_i \widehat{h} & x_1 = 0. \end{cases}$$

More specifically, the ODE system reads

$$(100a) \quad \frac{dU_{i,1}}{dx_1} = -\omega_1 U_{i,1},$$

$$(100b) \quad \frac{dU_{i,2}}{dx_1} = \omega_1 U_{i,2},$$

$$(100c) \quad \frac{dU_{i,3}}{dx_1} = -\omega_2 U_{i,3} - 2n_2 U_{i,4},$$

$$(100d) \quad \frac{dU_{i,4}}{dx_1} = \omega_2 U_{i,4}.$$

Recall that n_2 is defined in (83) and that it has a pole at P_0 . \mathcal{V}_i is sufficiently small so that we may assume that

$$\text{Re } \omega_1(\tau, \eta) \geq \kappa_i \gamma, \quad \text{Re } \omega_2(\tau, \eta) \geq \kappa_i (|\tau|^2 + \eta^2)^{1/2}, \quad \forall (\tau, \eta) \in \mathbb{R}^+ \cdot \mathcal{V}_i,$$

for a suitable constant $\kappa_i > 0$. The inequality concerning ω_1 follows from Remark 5. The above inequality for ω_2 is obvious because $\omega_2(P_0) = |\eta_0| \neq 0$.

As in Subsection 8.0.3 we show that $U_{i,2} \equiv 0$ and $U_{i,4} \equiv 0$, and (100c) reduces to

$$(101) \quad \frac{dU_{i,3}}{dx_1} = -\omega_2 U_{i,3}.$$

From (100a), (101) and the above properties of ω_1 and ω_2 we derive

$$(102) \quad \begin{aligned} \gamma \int_0^{+\infty} |U_{i,1}(\tau, x_1, \eta)|^2 dx_1 &\leq C |U_{i,1}(\tau, 0, \eta)|^2, \\ (|\tau|^2 + \eta^2)^{1/2} \int_0^{+\infty} |U_{i,3}(\tau, x_1, \eta)|^2 dx_1 &\leq C |U_{i,3}(\tau, 0, \eta)|^2, \end{aligned}$$

for all $(\tau, \eta) \in \mathbb{R}^+ \cdot \mathcal{V}_i$. On the other hand, the boundary condition in (99) reduces to

$$(103) \quad \begin{pmatrix} \mu \chi a_{12} & -\frac{1}{2} \dot{\mathcal{H}} \tau (n_1 - \omega_2 - n_2) \\ -\epsilon \dot{\mathcal{H}} \tau \mu \chi \omega_1 & \frac{1}{2} \mu \tau (n_1 - \omega_2 + n_2) \end{pmatrix} \begin{pmatrix} U_{i,1} \\ U_{i,3} \end{pmatrix} = \chi_i \widehat{h}.$$

Let us denote by $\Delta''(\tau, \eta)$ the determinant of the matrix in (95). Substituting (83) in the calculation of this determinant gives

$$\Delta''(\tau, \eta) := \frac{1}{2} \chi \tau \mu \left(\mu a_{12} (a_{43} - \omega_2) - \varepsilon \dot{\mathcal{H}}^2 \omega_1 (\tau a_{34} - \tau \omega_2) \right).$$

If \mathcal{V}_i is taken sufficiently small, it is easily verified that there exists a positive constant C such that

$$|\Delta''(\tau, \eta)| \geq C\gamma, \quad \forall (\tau, \eta) \in \mathcal{V}_i.$$

Even if from its definition $\Delta''(\tau, \eta)$ appears as a homogeneous function of degree 5 with respect to (τ, η) , actually it is a homogeneous function of degree 0, as follows from the extension of T_i that we did to the whole set of frequencies Ξ . Therefore we have

$$|\Delta''(\tau, \eta)| \geq C\gamma(|\tau|^2 + \eta^2)^{-1/2}, \quad \forall (\tau, \eta) \in \mathbb{R}^+ \cdot \mathcal{V}_i,$$

and from (103) it follows

$$(104) \quad |U_{i,1}(\tau, 0, \eta)| + |U_{i,3}(\tau, 0, \eta)| \leq C \frac{(|\tau|^2 + \eta^2)^{1/2}}{\gamma} |\chi_i \widehat{h}|.$$

Now, combining (102), (104) and using $(|\tau|^2 + \eta^2)^{1/2} \geq \gamma$ gives

$$\gamma \int_0^{+\infty} (|U_{i,1}(\tau, x_1, \eta)|^2 + |U_{i,3}(\tau, x_1, \eta)|^2) dx_1 + |U_{i,1}(\tau, 0, \eta)|^2 + |U_{i,3}(\tau, 0, \eta)|^2 \leq \frac{C_i}{\gamma^2} (|\tau|^2 + \eta^2) |\chi_i(\tau, \eta) \widehat{h}|^2,$$

for all $(\tau, \eta) \in \mathbb{R}^+ \cdot \mathcal{V}_i$. Finally, also recalling that $U_{i,2} \equiv 0$ and $U_{i,4} \equiv 0$, we obtain

$$(105) \quad \gamma \chi_i(\tau, \eta)^2 \int_0^{+\infty} |\widehat{V}^{\text{nc}}(\tau, x_1, \eta)|^2 dx_1 + \chi_i(\tau, \eta)^2 |\widehat{V}^{\text{nc}}(\tau, 0, \eta)|^2 \leq \frac{C_i}{\gamma^2} (|\tau|^2 + \eta^2) \chi_i(\tau, \eta)^2 |\widehat{h}|^2,$$

for all $(\tau, \eta) \in \mathbb{R}^+ \cdot \mathcal{V}_i$.

8.0.6. *Proof of estimate (24).* Adding (87), (90), (97), (98), (105), and using the partition of unity gives

$$\gamma \int_0^{+\infty} |\widehat{V}^{\text{nc}}(\tau, x_1, \eta)|^2 dx_1 + |\widehat{V}^{\text{nc}}(\tau, 0, \eta)|^2 \leq \frac{C_i}{\gamma^2} (|\tau|^2 + \eta^2) |\widehat{h}|^2,$$

for all $(\tau, \eta) \in \Xi$. We integrate with respect to $(\delta, \eta) \in \mathbb{R}^2$ and obtain the estimate

$$\gamma \|V^{\text{nc}}\|_{L^2(\Omega)}^2 + \|V_{x_1=0}^{\text{nc}}\|_{L^2(\mathbb{R}^2)}^2 \leq \frac{C}{\gamma^2} \|g\|_{1,\gamma}^2,$$

which yields (24).

APPENDIX A. PROOF OF LEMMA 1

The proof is similar to that one of Lemma 3 in [17]. We first proof the following result.

Lemma 10. *Let $m \geq 3$. For all $\varepsilon > 0$ there exists a continuous linear map $\varphi \in H^{m-0.5}(\mathbb{R}) \mapsto \Psi \in H^m(\Omega^+)$ such that $\Psi(0, x_2) = \varphi(x_2)$, $\partial_1 \Psi(0, x_2) = 0$ on Γ , and*

$$(106) \quad \|\partial_1 \Psi\|_{L^\infty(\Omega^+)} \leq \varepsilon \|\varphi\|_{H^2(\mathbb{R})}.$$

Proof. The first part of the proof is similar to the proof of Lemma 1 in [17] and we repeat it here for reader's convenience. Given an even function $\chi \in C_0^\infty(\mathbb{R})$, with $\chi = 1$ on $[-1, 1]$, we define

$$(107) \quad \Psi(x_1, x_2) := \chi(x_1 \langle D \rangle) \varphi(x_2),$$

where $\chi(x_1 \langle D \rangle)$ is the pseudo-differential operator with $\langle D \rangle = (1 + |D|^2)^{1/2}$ being the Fourier multiplier in the variables x_2 . From the definition it readily follows that $\Psi(0, x_2) = \varphi(x_2)$ for all $x_2 \in \mathbb{R}$. Moreover,

$$(108) \quad \partial_1 \Psi(x_1, x_2) = \chi'(x_1 \langle D \rangle) \langle D \rangle \varphi(x_2),$$

which vanishes if $x_1 = 0$. We compute

$$\|\Psi(x_1, \cdot)\|_{H^m(\mathbb{R})}^2 = \int_{\mathbb{R}} \langle \xi \rangle^{2m} \chi^2(x_1 \langle \xi \rangle) |\hat{\varphi}(\xi)|^2 d\xi,$$

where $\hat{\varphi}(\xi)$ denotes the Fourier transform in x_2 of φ . It follows that

$$\begin{aligned} \|\Psi\|_{L^2(\mathbb{R}_x^+; H^m(\mathbb{R}))}^2 &= \int_{\mathbb{R}} \int_{\mathbb{R}} \langle \xi \rangle^{2m} \chi^2(x_1 \langle \xi \rangle) |\hat{\varphi}(\xi)|^2 d\xi dx_1 \\ &= \int_{\mathbb{R}} \int_{\mathbb{R}} \langle \xi \rangle^{2m-1} \chi^2(s) |\hat{\varphi}(\xi)|^2 d\xi ds \leq C \|\varphi\|_{H^{m-0.5}(\mathbb{R})}^2. \end{aligned}$$

In a similar way, from (108), we obtain

$$\begin{aligned} \|\partial_1 \Psi\|_{L^2(\mathbb{R}_x^+; H^{m-1}(\mathbb{R}))}^2 &= \int_{\mathbb{R}} \int_{\mathbb{R}} \langle \xi \rangle^{2m-2} |\chi'(x_1 \langle \xi \rangle)|^2 |\hat{\varphi}(\xi)|^2 d\xi dx_1 \\ &= \int_{\mathbb{R}} \int_{\mathbb{R}} \langle \xi \rangle^{2m-1} |\chi'(s)|^2 |\hat{\varphi}(\xi)|^2 d\xi ds \leq C \|\varphi\|_{H^{m-0.5}(\mathbb{R})}^2. \end{aligned}$$

Iterating the same argument yields

$$\|\partial_1^j \Psi\|_{L^2(\mathbb{R}_x^+; H^{m-j}(\mathbb{R}))}^2 \leq C \|\varphi\|_{H^{m-0.5}(\mathbb{R})}^2, \quad j = 0, \dots, m.$$

Adding over $j = 0, \dots, m$ finally gives $\Psi \in H^m(\Omega^+)$ and the continuity of the map $\varphi \mapsto \Psi$.

We now show that the cut-off function χ , and accordingly the map $\varphi \mapsto \Psi$, can be chosen to give (106). From (108) we have

$$\partial_1 \Psi(x_1, x_2) = (2\pi)^{-1} \int_{\mathbb{R}} e^{i\xi \cdot x_2} \chi'(x_1 \langle \xi \rangle) \langle \xi \rangle \hat{\varphi}(\xi) d\xi.$$

By the Cauchy-Schwarz inequality and writing $\rho = |\xi|$ we get

$$\begin{aligned} |\partial_1 \Psi(x)| &\leq C \|\varphi\|_{H^2(\mathbb{R})} \left(\int_{\mathbb{R}} |\chi'(x_1 \langle \xi \rangle)|^2 \langle \xi \rangle^{-2} d\xi \right)^{1/2} \\ &= C \|\varphi\|_{H^2(\mathbb{R})} \left(\int_0^\infty |\chi'(x_1 \langle \rho \rangle)|^2 \langle \rho \rangle^{-2} d\rho \right)^{1/2}. \end{aligned}$$

We change variables in the integral above by setting $s = x_1 \langle \rho \rangle$. It follows that

$$(109) \quad |\partial_1 \Psi(x)| \leq C \|\varphi\|_{H^2(\mathbb{R})} \left(\int_{x_1}^\infty |\chi'(s)|^2 \frac{x_1}{s \sqrt{s^2 - x_1^2}} ds \right)^{1/2}.$$

Given any $M > 1$, we choose χ such that $\chi(s) = 0$ for $|s| \geq M$, and $|\chi'(s)| \leq 2/M$ for every s . Analyzing the above integral for all possible values of $x_1 > 0$ with respect to 1 and M gives

$$\int_{x_1}^\infty |\chi'(s)|^2 \frac{x_1}{s \sqrt{s^2 - x_1^2}} ds \leq CM^{-3/2} \quad \forall x_1 > 0.$$

Then from (109) one gets

$$|\partial_1 \Psi(x)| \leq CM^{-3/4} \|\varphi\|_{H^2(\mathbb{R})}.$$

Given any $\varepsilon > 0$, if M is such that $CM^{-3/4} < \varepsilon$, then (106) immediately follows. \square

The following lemma gives the time-dependent version of Lemma 10.

Lemma 11. *Let $m \geq 3$ be an integer and let $T > 0$. For all $\varepsilon > 0$ there exists a continuous linear map $\varphi \in \cap_{j=0}^{m-1} \mathcal{C}^j([0, T]; H^{m-j-0.5}(\mathbb{R})) \mapsto \Psi \in \cap_{j=0}^{m-1} \mathcal{C}^j([0, T]; H^{m-j}(\Omega^+))$ such that $\Psi(t, 0, x_2) = \varphi(t, x_2)$, $\partial_1 \Psi(t, 0, x_2) = 0$ on Γ , and*

$$(110) \quad \|\partial_1 \Psi\|_{\mathcal{C}([0, T]; L^\infty(\Omega^+))} \leq \varepsilon \|\varphi\|_{\mathcal{C}([0, T]; H^2(\mathbb{R}))}.$$

Furthermore, there exists a constant $C > 0$ that is independent of T and only depends on m , such that

$$\forall \varphi \in \cap_{j=0}^{m-1} \mathcal{C}^j([0, T]; H^{m-j-0.5}(\mathbb{R})), \quad \forall j = 0, \dots, m-1, \quad \forall t \in [0, T],$$

$$\|\partial_t^j \Psi(t, \cdot)\|_{H^{m-j}(\Omega^+)} \leq C \|\partial_t^j \varphi(t, \cdot)\|_{H^{m-j-0.5}(\mathbb{R})}.$$

Proof. The proof of Lemma 11 follows from Lemma 10, with t as a parameter. Notice also that the map $\varphi \rightarrow \Psi$, defined by (107), is linear and that the time regularity is conserved because, with obvious notation, $\Psi(\partial_t^j \varphi) = \partial_t^j \Psi(\varphi)$. The conclusions of Lemma 11 follow directly. \square

Proof of Lemma 1. The proof follows directly from Lemma 11 because

$$\partial_1 \Phi_1(t, x) = 1 + \partial_1 \Psi(t, x) \geq 1 - \|\partial_1 \Psi(t, \cdot)\|_{\mathcal{C}([0, T]; L^\infty(\Omega^+))} \geq 1 - \varepsilon \|\varphi\|_{\mathcal{C}([0, T]; H^2(\mathbb{R}))} \geq 1/2,$$

provided ε is taken sufficiently small, e.g. $\varepsilon < 1/2$. The other properties of Φ follow directly from Lemma 11. \square

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E-mail address: `davide.catania@unibs.it`

E-mail address: `marcello.dabbicco@unibs.it`

E-mail address: `paolo.secchi@unibs.it`

¹ DICATAM, MATHEMATICAL DIVISION, UNIVERSITY OF BRESCIA, VIA VALOTTI 9, 25133 BRESCIA, ITALY

² SMART ENGINEERING SOLUTIONS & TECHNOLOGIES (SMARTEST) RESEARCH CENTRE, ECAMPUS UNIVERSITY, VIA ISIMBARDI 10, 22060 NOVEDRATE (CO), ITALY