

Article

Retrieval of Melt Ponds on Arctic Multiyear Sea Ice in Summer from TerraSAR-X Dual-Polarization Data Using Machine Learning Approaches: A Case Study in the Chukchi Sea with Mid-Incidence Angle Data

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Abstract: Melt ponds, a common feature on Arctic sea ice, absorb most of the incoming solar radiation and have a large effect on the melting rate of sea ice, which significantly influences climate change. Therefore, it is very important to monitor melt ponds in order to better understand the sea ice-climate interaction. In this study, melt pond retrieval models were developed using the TerraSAR-X dual-polarization synthetic aperture radar (SAR) data with mid-incidence angle obtained in a summer multiyear sea ice area in the Chukchi Sea, the Western Arctic, based on two rule-based machine learning approaches-decision trees (DT) and random forest (RF)-in order to derive melt pond statistics at high spatial resolution and to identify key polarimetric parameters for melt pond detection. Melt ponds, sea ice and open water were delineated from the airborne SAR images (0.3-m resolution), which were used as a reference dataset. A total of eight polarimetric parameters (HH and VV backscattering coefficients, co-polarization ratio, co-polarization phase difference, co-polarization correlation coefficient, alpha angle, entropy and anisotropy) were derived from the TerraSAR-X dual-polarization data and then used as input variables for the machine learning models. The DT and RF models could not effectively discriminate melt ponds from open water when using only the polarimetric parameters. This is because melt ponds showed similar polarimetric signatures to open water. The average and standard deviation of the polarimetric parameters based on a 15×15 pixel window were supplemented to the input variables in order to consider the difference between the spatial texture of melt ponds and open water. Both the DT and RF models using the polarimetric parameters and their texture features produced improved performance for the retrieval of melt ponds, and RF was superior to DT. The HH backscattering coefficient was identified as the variable contributing the most, and its spatial standard deviation was the next most contributing one to the classification of open water, sea ice and melt ponds in the RF model. The average of the co-polarization phase difference and the alpha angle in a mid-incidence angle were also identified as the important variables in the RF model. The melt pond fraction and sea ice concentration retrieved from the RF-derived melt pond map showed root mean square deviations of 2.4% and 4.9%, respectively, compared to those from the reference melt pond maps. This indicates that there is potential to accurately monitor melt ponds on multiyear sea ice in the summer season at a local scale using high-resolution dual-polarization SAR data.



Keywords: Arctic; Chukchi Sea; melt ponds; multiyear sea ice; melt pond fraction; polarimetric SAR; machine learning; TerraSAR-X

1. Introduction

The sea ice cover in the Arctic has declined since the beginning of satellite observation in 1979 [1–6], which has a strong influence on the changes of climate systems, marine ecosystems and maritime resource development [7–9]. The seasonal decline of the Arctic sea ice extent has been dramatic from summer $(-70.1 \pm 7.8 \times 10^3 \text{ km}^2 \cdot \text{y}^{-1})$ to autumn $(-57.3 \pm 5.7 \times 10^3 \text{ km}^2 \cdot \text{y}^{-1})$ for the past 30 years [1]. The Arctic sea ice decline in summer and autumn can be amplified by the development of melt ponds that can cover up to 50%–60% of the sea ice area [10,11]. While snow-covered and bare sea ice have a high surface albedo, melt ponds reflect ~20% of the incident solar radiation and absorb four-times more solar energy than sea ice [12,13]. Ponded ice experiences more melting than snow-covered and bare sea ice in the Arctic [14–16]. Therefore, an accurate observation of melt ponds on the Arctic sea ice is critical in order to better understand the dynamics of sea ice decline and to provide important parameters for climate change research.

Optical satellite data with medium-low resolution (30 m–1 km), such as the Terra/Aqua Moderate Resolution Imaging Spectroradiometer (MODIS), the ENVISAT Medium Resolution Imaging Spectrometer (MERIS) and the Landsat-7 Enhanced Thematic Mapper Plus (ETM+), multispectral images have been used to observe melt ponds on widely-distributed sea ice in the Arctic [17–23]. Based on the distinctive spectral albedo of melt pond between sea ice and open water [22], the previous studies estimated the fraction of ponds by analyzing the albedo of ponded ice. The melt pond fraction estimated from the optical data resulted in a root mean square error (RMSE) of ~15% when compared to *in situ* observation and aerial photography [17,19–21,23], and it was used as an important predictor of sea ice cover and climate change [16,24,25]. However, the applicability of such optical images is restricted to daytime and clear skies, which provides few chances to observe the sea ice surface in the Arctic.

Synthetic aperture radar (SAR) has been widely used to observe sea ice and melt ponds because it provides surface images regardless of weather conditions and sun altitudes. Yackel and Barber [26] investigated the utility of radar backscattering to detect melt ponds using RADARSAT-1 SAR images in HH polarization. They found that the RADARSAT-1 HH backscattering coefficient and melt pond fraction of first-year sea ice in the Canadian Archipelago showed a strong positive relationship under windy conditions, but a very weak positive relationship under low wind speed. Mäkynen et al. [27] compared the backscattering coefficient of ENVISAT wide swath mode (WSM) SAR images in HH polarization to the melt pond fraction of the Arctic sea ice derived from MODIS images. Their results showed that the correlation between the backscattering coefficient and melt pond fraction was very low due to the low resolution of the WSM images (100 m). Kim et al. [28] retrieved the melt pond fraction of sea ice in the northern Chukchi Sea from a TerraSAR-X HH-polarized SAR amplitude image obtained in Stripmap mode. Although the TerraSAR-X Stripmap image has a fine spatial resolution (3 m), the melt pond fraction was largely underestimated. The previous studies with single-polarization SAR data have limitations in the retrieval of melt ponds. This is because the single-polarized backscattering coefficient depends mainly on surface roughness, and thus, it has limited information for identifying the ponds.

Polarimetric SAR measures radar backscattering from multi-polarization channels, which can provide a number of parameters representing various physical properties of a target that have been widely used for land cover classification [29–31]. Several studies demonstrated that a co-polarization ratio (the ratio of backscattering derived from VV and HH polarization), one of the polarimetric parameters, can identify melt ponds on first-year sea ice due to an obvious contrast of the dielectric

property between the ponds and ice [32,33]. Scharien *et al.* [34] estimated the melt pond fraction on first-year ice in the Canadian Archipelago using the co- and cross-polarization ratios of RADARSAT-2 dual-polarimetric SAR data based on surface scattering theory. However, their approach showed weak performance for the sea ice with wet snow, which produced values similar to the polarization ratio for melt ponds.

As stated above, most of the previous studies using SAR had limitations for retrieving melt ponds because the backscattering coefficient and the polarization ratio were not enough to discriminate melt ponds from sea ice and open water. The use of a combination of polarimetric parameters computed from multi-polarization SAR can provide more physical properties of the ice surface than single polarimetric parameters [35,36]. Therefore, high-resolution polarimetric parameters can improve the performance of melt pond retrieval from SAR data, which can produce accurate statistics for melt ponds and sea ice. Most of the previous studies using polarimetric SAR focused on melt ponds on first-year ice [32–34], while few studies were performed for multiyear ice. Melt ponds on multiyear ice show different physical and microwave scattering characteristics from those on first-year ice [37]. Since polarimetric features from melt ponds on multiyear ice are likely different from those on first-year ice, melt pond retrievals from polarimetric SAR data should be further examined and evaluated for multiyear ice.

The objectives of this paper are to: (1) develop a novel approach to the retrieval of melt ponds on summer multiyear ice in the Chukchi Sea, the Western Arctic, for deriving accurate pond statistics using various polarimetric parameters derived from TerraSAR-X dual-polarization data based on the rule-based machine learning algorithms; (2) evaluate the performance of machine learning models for retrieving melt ponds; (3) identify key contributing variables for melt pond retrievals; and (4) investigate the robustness of the pond statistics obtained from high-resolution multi-polarization SAR data. The TerraSAR-X dual-polarization data and airborne SAR images used in this study and a brief explanation of the sea ice conditions in the study area are presented in Section 2. The methodology for developing melt pond detection models using the TerraSAR-X dual-polarization data based on machine learning approaches is described in Section 3. Results from the melt pond detection models and a discussion are covered in Section 4. Section 5 concludes this paper.

2. Materials

2.1. Airborne SAR Survey Data

Airborne X-band SAR (with a center frequency of 10.25 GHz) images with 0.3-m resolution acquired on 12 August 2011 in the northern Chukchi Sea (Figure 1) were used to construct a reference dataset for developing the melt pond detection models. The airborne SAR system was equipped with a Global Positioning System/inertial measurement units (GPS/IMUs) and a gimbal-mounted phased array antenna, which was mounted on a helicopter (Bell 206 Jet Ranger) and surveyed from 04:48 coordinated universal time (UTC) for 1 h. Due to technical problems, the airborne SAR images could not be combined into a perfectly continuous strip image [28]. Each original airborne SAR image has a size of approximately 600 m in the range direction by 350 m in the azimuth direction. However, the near-range part of the SAR images was cropped, leaving a size of approximately 400 m in the range direction by 350 m in the azimuth direction, due to no backscattered signal in a predetermined time domain [28]. In order to reduce speckle noise, the resolution of the original SAR images was downgraded to 0.6 m.

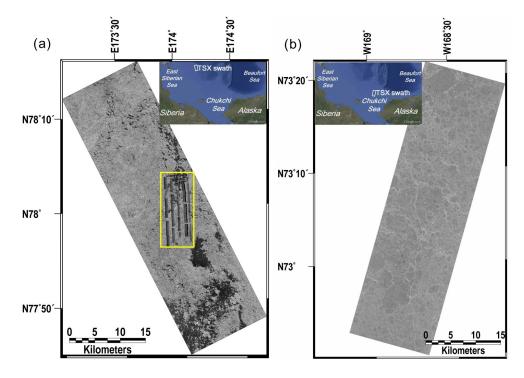


Figure 1. TerraSAR-X (TSX) amplitude images (HH-polarization) obtained in the Chukchi Sea on (a) 12 August 2011 and (b) 21 July 2010, respectively. The airborne SAR images are overlaid on the 2011 TerraSAR-X amplitude image (yellow box). The TerraSAR-X imaging area corresponds to the white solid box in each map.

2.2. TerraSAR-X Dual-Polarization Data

TerraSAR-X is equipped with X-band SAR, a center frequency of 9.65 GHz, which provides high-resolution images in different imaging modes: 1 m in High-resolution Spotlight (HS), 2 m in Spotlight (SL), 3 m in most of Stripmap (SM) and 18 m in ScanSAR (SC) mode [38,39]. Dual-polarization data can be acquired in the TerraSAR-X imaging modes except for SC. In this study, two TerraSAR-X SM dual-polarization (HH and VV polarization) data with a mid-incidence angle of 32.7° acquired in a descending orbit at 18:15 UTC on 21 July 2010 and in an ascending orbit at 04:55 UTC on 12 August 2011 (the same date as the airborne SAR survey) were used for melt pond detection from summer multiyear sea ice in the northern Chukchi Sea (Figure 1). The swath width of the TerraSAR-X data was about 17 km. The TerraSAR-X data obtained in 2011 (Figure 1a) were used to develop and validate melt pond retrieval models based on machine learning approaches using the airborne SAR images. The other 2010 TerraSAR-X data were used to evaluate the machine learning model developed from the TerraSAR-X data in 2011. The TerraSAR-X data were delivered in a single-look complex (SLC) format. A 5 by 5 Lee filter [40] was applied to the TerraSAR-X SLC data in order to reduce speckle noise. The backscattering coefficients and different polarimetric parameters were derived from the filtered SLC data. The noise equivalent sigma zero (NESZ) of our TerraSAR-X data is -25 dB. A detailed description of the computation of the polarimetric parameters will be presented in Section 3.

2.3. Sea Ice Conditions

While a field survey of sea ice conditions in the area of TerraSAR-X data in 2010 was not performed, sea ice in the area was visually examined through analyzing the amplitude image (Figure 1a). In the 2010 TerraSAR-X image, large multiyear ice floes that hold numerous melt ponds, seen as dark in small sized and some large and dark open water, were observed. Kim *et al.* [28] provided sea ice conditions in the area of the TerraSAR-X data obtained in 2011 through the analysis of the aerial photographs acquired coincident with the airborne SAR survey (see Figures 4 and 9 in [28]). The study area consists

of two sea ice conditions: one is large and thick multiyear ice floes that hold many melt ponds (more than 1000 per square kilometer) on the surface, while the other is heavily-melted small ice fragments of about 100 m in size that hold few melt ponds on the surface [28]. The aerial photographs showed that most of the melt ponds were interconnected by small channels. Such small channels could not be detected in the airborne SAR images, but would not significantly affect the estimation of the melt ponds observed in the airborne SAR images appeared in a very dark tone, which indicates that the wind speed was low, and thus, the surface of the ponds and open water would be smooth. Few shadow areas on the sea ice surface were observed from the airborne SAR images, which implies that the spatial variation of the ice topography was low.

3. Methodology

In this study, machine learning-based classification approaches were used to retrieve melt ponds on multiyear ice, in which the backscattering and polarimetric parameters of the TerraSAR-X dual-polarization data were used as input variables. Figure 2 shows the processing flow of the classification approach. This section presents the construction method of the reference dataset from the airborne SAR images, the computation of different polarimetric parameters and two rule-based machine learning approaches used for the classification of open water, sea ice and melt pond. The computation of various statistics for melt ponds is also described in this section.

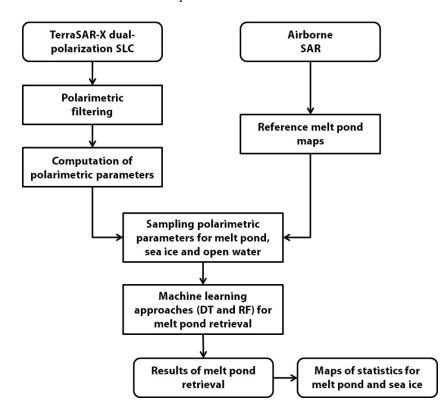


Figure 2. Processing flow of the melt pond retrieval from the classification of the TerraSAR-X dual-polarization SAR data based on machine learning approaches. SLC, single-look complex; DT, decision tree; RF, random forest.

3.1. Construction of the Reference Dataset

In order to construct a reference dataset for the classification of open water, sea ice and melt pond, the objects of each class were delineated from the airborne SAR images using a combination of multiscale segmentation and aggregation methods, as described in Kim *et al.* [28]. First, water and ice

were classified from the object extraction procedure. The water objects within the ice were defined as melt ponds, while other water objects were defined as open water. In some airborne SAR images, open water within interconnected ice floes was misclassified as a melt pond. To reduce the misclassification of open water, the melt pond objects with an area larger than 700 m² were considered to be open water [28]. This filtering process can change some large melt ponds to open water. However, such large melt ponds account for only 4% of the total number of melt ponds [28].

Kim *et al.* [28] evaluated the results of melt pond extraction from the airborne SAR images by one-to-one visual comparison with the aerial photographs (see Figure 9 in [28]). The shape and the size of melt ponds extracted from the airborne SAR images agreed with those from the aerial photographs. Some melt ponds were interconnected by small channels, which were identified in the aerial photographs. The small channels were not detected in the airborne SAR images, which would affect the estimation of pond circularity. However, the estimation of pond areas would not be significantly affected [28]. This suggests that the classification results of the airborne SAR images were accurate enough to be used as a reference dataset for the classification of the TerraSAR-X data.

The statistics for melt ponds, *i.e.*, melt pond fraction (F_p), number density of ponds (N_d), mean pond size (S_p) and sea ice concentration, were computed from the individual airborne SAR images. F_p is defined as the percentage of total ice area covered by melt ponds, which is computed by [14]:

$$F_p = A_p / \left(A_i + A_p \right) \tag{1}$$

where A_p is the fraction of melt ponds within an airborne SAR image and A_i is the fraction of sea ice excluding melt pond areas within the image. N_d is defined as the number of melt ponds divided by the area of sea ice including melt ponds $(A_i + A_p)$, with units of km⁻² [14]. Sea ice concentration is defined as the fraction of sea ice including melt pond areas within the image.

3.2. Polarimetric Parameters

Polarimetric parameters derived from multi-polarization SAR data provide informative descriptions of the scattering mechanism of a target, and thus, can be very useful for the classification of different surface types. In this study, the dual-polarimetric 2 × 2 coherency matrix (T_2) for the TerraSAR-X data was applied as follows [41]:

$$T_{2} = \frac{1}{2} \begin{vmatrix} \langle (S_{HH} + S_{VV}) (S_{HH} + S_{VV})^{*} \rangle & \langle (S_{HH} + S_{VV}) (S_{HH} - S_{VV})^{*} \rangle \\ \langle (S_{HH} - S_{VV}) (S_{HH} + S_{VV})^{*} \rangle & \langle (S_{HH} - S_{VV}) (S_{HH} - S_{VV})^{*} \rangle \end{vmatrix}$$
(2)

where S_{XX} is the scattering matrix complex element and superscript * indicates the complex conjugation. Subscript XX indicates polarization. $\langle \rangle$ represents the ensemble average of the complex product. The drawback of the T_2 matrix is that it cannot provide information about the cross-polarization correlation coefficient and phase difference as obtainable from fully-polarimetric SAR data. Nevertheless, the dual-polarization SAR data can produce various polarimetric parameters. A total of 8 polarimetric parameters, including HH and VV backscattering coefficients, co-polarization ratio, co-polarization phase difference, co-polarization correlation coefficient, alpha angle, entropy and anisotropy, were derived from the TerraSAR-X dual-polarization data. The backscattering coefficients at HH (σ_{HH}^0) and VV polarization ($\sigma_{VV}^0/\sigma_{HH}^0$ in dB) was calculated from the filtered TerraSAR-X SLC data. The co-polarization ratio ($\sigma_{VV}^0/\sigma_{HH}^0$ in dB) was calculated from the backscattering coefficients. The phase difference (ϕ_{HHVV}) and the correlation coefficient (ρ_{HHVV}) were calculated as:

$$\phi_{HHVV} = \arg\left(\langle S_{HH} S_{VV}^* \rangle\right) \tag{3}$$

$$\rho_{HHVV} = \frac{\left|\left\langle S_{HH}S_{VV}^{*}\right\rangle\right|}{\sqrt{\sigma_{VV}^{0}\sigma_{HH}^{0}}} \tag{4}$$

where || stands for the modulus of the complex product.

The entropy (*H*)/anisotropy (*A*)/alpha angle ($\overline{\alpha}$) decomposition [42] is based on the well-known polarimetric decomposition theorem that is useful in characterizing the scattering properties of various scattering media and, thus, widely used for land cover and land use classification [36,43]. *H* indicates the randomness of scattering mechanisms. *A* describes the relative power of secondary and tertiary scattering mechanisms for quad polarization data, but it is not defined for dual polarization data. For dual polarization data, *A* can be interpreted in terms of the number of scattering mechanisms by explaining with *H* [44]. $\overline{\alpha}$ is an indicator of the type of scattering mechanism. The *H*/*A*/ $\overline{\alpha}$ decomposition was originally proposed for full-polarization data, but Cloude [45] modified the theory for dual-polarization data. *H* and *A* were calculated using the eigenvalues λ_1 and λ_2 of the T_2 matrix evaluated from the linear combinations of the scattering matrix elements as follows [45]:

$$H = -P_1 \log_2 (P_1) - P_2 \log_2 (P_2)$$
(5)

$$A = \frac{P_1 - P_2}{P_1 + P_2} \tag{6}$$

where P_i (i = 1, 2) is the probability of each eigenvalue contribution, defined as:

$$P_1 = \frac{\lambda_1}{\lambda_1 + \lambda_2}, P_2 = \frac{\lambda_2}{\lambda_1 + \lambda_2}$$
(7)

 $\overline{\alpha}$ was calculated using the dominant scattering alpha angle (α) as follows [45]:

$$\overline{\alpha} = P_1 \alpha + P_2 \left(\frac{\pi}{2} - \alpha\right), \alpha = \cos^{-1} \frac{|x_1|}{|v_1|}$$
(8)

where x_1 is the first coordinate of the first eigenvector and $|v_1|$ is the norm of the first eigenvector. The detailed evaluation of the coherency matrix, including the eigenvalue-eigenvector analysis, is described in Cloude and Pottier [42], Cloude [45] and Lee and Pottier [41]. All polarimetric parameters were projected into a Universal Transverse Mercator (UTM) projection (Zone 59 North) with a pixel size of 3 m.

3.3. Machine Learning Approaches for Melt Pond Retrieval

The surface type of the study area (open water, sea ice and melt pond) was set to a dependent variable for classification. To train and validate the machine learning-based classification models, a total of 37,152 samples (*i.e.*, pixels) of polarimetric parameters for open water, sea ice and melt pond (12,384 samples for each class) were selected from the TerraSAR-X dual-polarization data by referring to the location of the objects of each class delineated from the airborne SAR images. As melt ponds on sea ice formed in a much smaller size than open water, the average and standard deviation of the polarimetric parameters might contribute to improve the machine learning-based classification models. In this study, the average and standard deviation (texture features) of the polarimetric parameters computed within a moving window with a size ranging from 5×5 to 35×35 pixels were calculated and used as additional input variables for the machine learning models. As the polarimetric parameters were projected with a pixel spacing of 3 m, objects with a size larger than 3×3 m were referred from the airborne SAR images. Eighty percent of the samples for each class (9907 samples) were randomly selected to be used as a training dataset, while the remaining samples (2477 samples for each class) were used as a test dataset in order to validate the models.

Machine learning is a novel approach used in various remote sensing applications, including land cover/land use classification [46–52], change detection [53,54], geological mapping [55], vegetation mapping [56–59], hydrological studies [60–62] and atmospheric studies [63,64]. In this study, two rule-based machine learning approaches—decision tree (DT) and random forest (RF)—were used for the classification of open water, sea ice and melt pond from the TerraSAR-X dual-polarization

data. See5, developed by RuleQuest Research, Inc. (Empire Bay, Australia) [65], was used to carry out the DT-based classification. See5 uses repeated binary splits based on an entropy-related metric to develop a tree. The generated tree can be simplified and converted into a series of if-then rules, which makes it easy to analyze the classification results. RF creates multiple bootstrapped samples of the original training data and builds a set of no pruning classification and regression trees (CART) [66] from each set of bootstrapped samples, which is a rule-based decision tree. The numerous independent trees are grown by randomly selecting a subset of the training samples for each tree and a subset of splitting variables at each node of the tree, which overcomes the well-known limitation of CART that classification results largely depend on the configuration and quality of training samples [67]. For classification, each tree gives a unit vote for the most popular class at each input instance. A final conclusion from the independent decision trees is determined by using either a simple majority voting or weighted majority voting strategy. In this study, RF was implemented using an add-on package in the R software. See5 and RF produce information on the relative importance of input variables with attribute usage and mean decrease accuracy, respectively. The attribute usage information indicates how often each variable is used in the rules, while mean decrease accuracy represents the decrease in the accuracy of the model using out-of-bag data when a variable is randomly permuted. In other words, the attribute usage in See5 is reported by the percentage of the training cases where an attribute (*i.e.*, the input variables) is used in predicting a class. The mean decrease accuracy in random forest is obtained by subtracting the number of correctly-classified cases for the variable-permuted out-of-bag data from the number of cases for original out-of-bag data and averaging the numbers for every tree in the forest. Therefore, the mean decrease accuracy means the average increase in the misclassification rate as a percentage. DT and RF are quickly trained, and it is easy to understand the model that was built for classification. Moreover, in general, RF outperforms artificial neural networks and the maximum likelihood classifier, especially when faced with a limited number of training samples and a large number of input variables [68].

To evaluate the performance of the machine learning models, typical accuracy metrics, including user's accuracy, producer's accuracy, overall accuracy and the kappa coefficient of agreement, were computed from a confusion matrix of the test dataset. User's and producer's accuracies show how well individual classes were classified correctly. The producer's accuracy refers to the probability that a certain surface type of an area is correctly classified as such, while the user's accuracy refers to the probability that a sample labeled as a surface type class is correctly classified as this class. Overall accuracy can be derived from dividing the number of samples that were correctly classified by the total number of samples. The kappa coefficient, another criterion used for the assessment of classification results, measures the degree of agreement between classification and reference data considering change agreement occurring by chance. The overall accuracy and the kappa coefficient have been widely used for accuracy assessment of the classification of remote sensing data [69–71]. The statistics for melt ponds were calculated from the results of the machine learning models and compared to those from the airborne SAR images, evaluating the feasibility of obtaining reliable pond statistics from the high-resolution dual-polarization SAR data. Quantitative accuracy assessment was performed on the classification of 2011 SAR data, and only visual assessment based on the SAR amplitude image was conducted for the classification of 2010 SAR data due to the lack of reference data. The melt pond statistics for the swath of the 2011 SAR data were obtained from a melt pond map generated by the machine learning model resulting in the best performance in order to analyze sea ice characteristics in the area.

4. Results and Discussion

4.1. Polarimetric Signatures

The boxplots in Figure 3 show the characteristics of the polarimetric parameters in the samples of open water, sea ice and melt pond. The *F*-statistic and *p*-value in each boxplot were derived from the

one-way analysis of variance (ANOVA) at the 95% confidence level. The *p*-values below 0.05 mean that at least one surface type can be distinguished from the other surface types by the polarimetric parameters. Tukey's *post hoc* test at the 95% confidence level was carried out to identify which surface types can be discriminated from other surface types by a specific polarimetric parameter. The results of the *post hoc* tests are presented in each boxplot. Two surface types that cannot be discriminated from each other by the *post hoc* tests are denoted by the same lower case letter. The group names of the *results of the post hoc* tests are ordered according to the mean value of the samples. The ANOVA with *post hoc* tests was carried out using 300 randomly-selected samples (100 samples for each surface type) from a total of 37,152 samples (12,384 samples for each surface type), because the large sample size can overestimate the *F*-statistic, flagging the minute differences between the surface types as statistically significant. The sample size of 300 was determined by power analysis for one-way ANOVA with three groups conducted in G*Power [72] using an effect size of 0.25, an alpha of 0.05 and a power of 0.95.

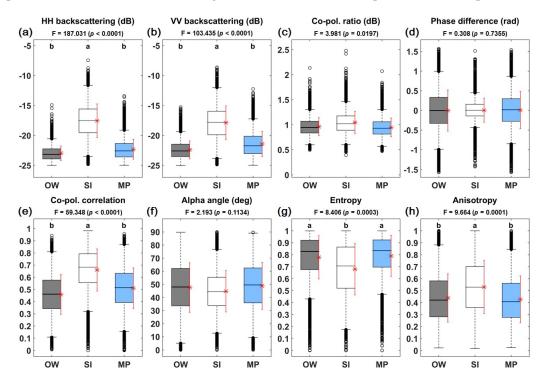


Figure 3. Boxplots of the polarimetric parameters used for the melt pond retrieval: (**a**) backscattering coefficient at HH polarization; (**b**) backscattering coefficient at VV polarization; (**c**) co-polarization ratio; (**d**) co-polarization phase difference; (**e**) copolarization correlation coefficient; (**f**) alpha angle, (**g**) entropy; and (**h**) anisotropy. Colored boxes represent the interquartile range of the samples, while a line inside the box means the median value of the samples. The vertical lines above and below the box represent 1.5-times the interquartile range beyond the lower and upper quartiles, and the dots represent the outliers. The red asterisks on the right side of boxes represent the mean value of the samples, while the red vertical lines above and below the asterisk mean the standard deviation of the samples. Co-pol, OW, SI, and MP indicate co-polarization, open water, sea ice, and melt pond, respectively.

The boxplots in Figure 3 show that the values of the polarimetric parameters for sea ice (*i.e.*, multiyear ice) are distinct from those for open water and melt ponds, except for the co-polarization ratio, the phase difference and the alpha angle, which showed a similar median value and interquartile range for all surface types. The values of HH and VV backscattering coefficients of sea ice were ~8 dB stronger than those of open water and melt ponds. This is because a sea ice surface is typically rougher than a calm open water surface [73,74]. The co-polarization correlation coefficient is close to one for an isotropic scattering medium (e.g., multiyear ice or snow), while it decreases when the scattering medium is anisotropic (e.g., new ice and first-year ice) or the backscattering coefficients are close to

the noise level [35]. Sea ice in the study area was composed of multiyear ice floes and snow-covered first-year ice [28], which show larger values of the co-polarization correlation coefficient than open water and melt ponds, which show very low backscattering signals. The sea ice showed lower entropy values and larger anisotropy values than open water and melt ponds. This is possibly caused by the multiple scattering from the isotropic layer of multiyear ice floes and snow on the surface of first-year ice [75,76]. While multiyear ice can be identified from the polarimetric parameters, open water and melt ponds cannot be clearly distinguished from each other by the *post hoc* tests (Figure 3).

4.2. Performance of Melt Pond Detection Model Using Polarimetric Parameters

The test dataset was used to produce confusion matrices in order to assess the performance of the machine learning models developed using the polarimetric parameters. Both the DT and RF models showed relatively low overall accuracies of 66.56% and 69.88%, respectively, and low kappa coefficients of 49.89% and 54.82%, respectively (Tables 1 and 2). The user's and producer's accuracies of sea ice were higher than 80% for both models, because multiyear ice floes showed distinctive polarimetric characteristics from open water and melt ponds. However, the user's and producer's accuracies of open water and melt ponds. However, the user's and producer's accuracies of open water and melt pond on multiyear ice were very low for both models (Tables 1 and 2) due to the similarity in the polarimetric characteristics between the two classes. This means that the polarimetric parameters might not be effective for the detection of melt ponds on multiyear ice and suggests the need for supplemental variables for discriminating melt ponds from open water.

Table 1. Accuracy assessment results for the DT model that was developed using the polarimetric parameters.

Reference Classified as	Open Water	Sea Ice	Melt Pond	Sum	User's Accuracy
Open water	1865	79	1197	3141	59.38%
Sea ice	54	2152	349	2555	84.23%
Melt pond	558	246	931	1735	53.66%
Sum	2477	2477	2477	7431	
Producer's accuracy	75.29%	86.88%	37.59%		
Overall accuracy			66.59%		
Kappa coefficient			49.88%		

Table 2. Accuracy assessment results for the RF model that was developed using the polarimetric parameters.

Reference Classified as	Open Water	Sea Ice	Melt Pond	Sum	User's Accuracy
Open water	1955	50	1175	3180	61.48%
Sea ice	27	2222	286	2535	87.65%
Melt pond	495	205	1016	1716	59.21%
Sum	2477	2477	2477	7431	
Producer's accuracy	78.93%	89.71%	41.02%		
Overall accuracy			69.88%		
Kappa coefficient			54.82%		

The melt ponds on multiyear ice and open water showed similar polarimetric characteristics, which resulted in the low performance of the machine learning models evaluated above. In order to discriminate the melt ponds from open water by the polarimetric characteristics, texture features of the polarimetric parameters can be used. Melt ponds on multiyear ice were typically less than 100 m² [28], while open water formed in much larger areas than the melt ponds and contained few ice fragments. Therefore, within a pixel window larger than melt pond areas, the texture features of a polarimetric parameter computed for the window of which the center is a melt pond can be distinct from those of open water due to the difference of the spatial homogeneity. The average values of the polarimetric parameters within a pixel window for melt ponds would be different from those for sea ice and open

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water. The standard deviation values of the polarimetric parameters for melt ponds are expected to be larger than those for sea ice and open water. The texture features of the polarimetric parameters can be supplementary to the variables of the machine learning models, which might improve the performance of the retrieval of melt ponds on multiyear ice floes.

4.3. Performance of the Melt Pond Detection Model Considering the Texture Features of the Polarimetric Parameters

The texture features of the polarimetric parameters were calculated based on a pixel window in a square with a side length ranging from 5–35 pixels of the TerraSAR-X data obtained in a mid-incidence angle (32.7°) and used as the additional input variables for the machine learning models. The overall accuracies and kappa coefficients for the machine learning models were derived from confusion matrices using the test samples (Figure 4) and then assessed in order to find an optimum pixel window for calculating the texture features. The overall performance of the machine learning models was improved, compared to the previously-developed models that used only the polarimetric parameters (Tables 1 and 2). The DT and RF models showed the highest overall performance when adopting the texture features of the polarimetric parameters based on 13×13 and 15×15 pixel windows, respectively. The RF models showed higher overall accuracies (85.7%–89.9%) and kappa coefficients (78.6%–84.9%) than the DT models (79.7%–85.7% and 69.6%–78.6%, respectively). The overall accuracy and kappa coefficient produced from the DT model adopting the texture features based on a 15×15 pixel window were only 0.7% lower than the best DT model that uses the texture features based on a 13×13 pixel window. Therefore, a 15×15 pixel window was selected as the optimum window for computing the texture features of the polarimetric parameters.

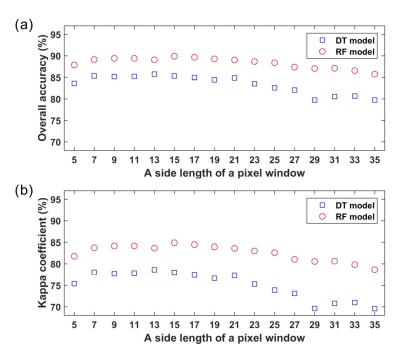


Figure 4. The variations of the overall accuracy and the kappa coefficient for the DT and RF model that were developed using the polarimetric parameters and their texture features based on a pixel window, ranging from 5–35: (**a**) the variations of the overall accuracies; and (**b**) the variations of the kappa coefficients.

Figure 5 shows the boxplots of the texture features of the polarimetric parameters based on a 15×15 pixel window using the samples of open water, sea ice and melt pond. The ANOVA with Tukey's *post hoc* test at the 95% confidence level was performed for each variable. The melt ponds on multiyear ice were statistically discriminated from the open water and sea ice using the average

of the HH and VV backscattering coefficients, the co-polarization correlation, the co-polarization phase difference, the alpha angle, the entropy, the anisotropy and the standard deviation of the phase difference. The other variables of the texture features for melt ponds and open water showed similar mean values.

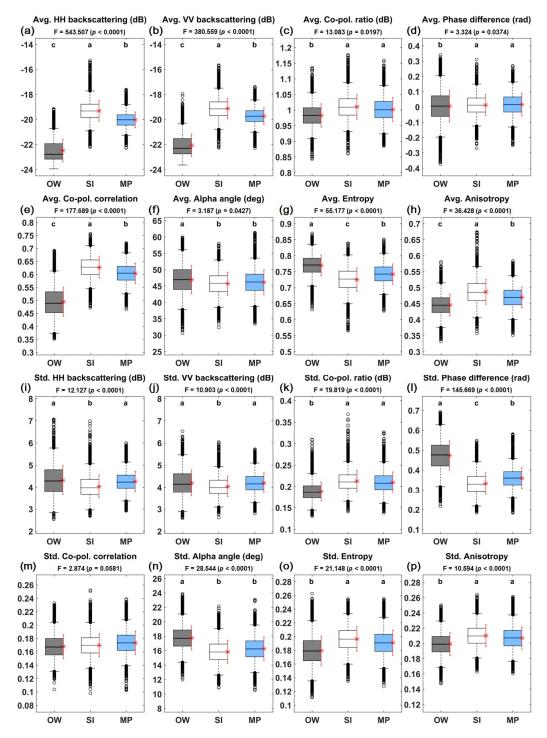


Figure 5. Boxplots of the texture features of the polarimetric parameters used as the supplementary variables for melt pond retrieval: (**a**–**h**) the average of the polarimetric parameters based on a 15×15 pixel window; and (**i**–**p**) the standard deviation of the polarimetric parameters based on a 15×15 pixel window. Co-pol, Avg, and Std indicate co-polarization, average, and standard deviation, respectively.

The confusion matrices of the DT and RF models developed using the polarimetric parameters and their texture features based on a 15×15 pixel window are presented in Tables 3 and 4 respectively. Both models showed a much improved classification performance, especially for melt ponds and open water, compared to the models developed using only the polarimetric parameters. The overall accuracy and the kappa coefficient of the RF model (90.05% and 85.12%) were higher than the DT model (85.33% and 78.0%). The user's and producer's accuracies for the open water, sea ice and melt pond were also higher in the RF model than the DT model, which is possibly due to a superior categorization strategy of RF [48,63].

Table 3. Accuracy assessment results for the DT model that was developed using the polarimetric parameters and their texture features.

Reference Classified as	Open Water	Sea Ice	Melt Pond	Sum	User's Accuracy
Open water	2333	14	210	2557	91.24%
Sea ice	15	2175	434	2624	82.89%
Melt pond	129	288	1833	2250	81.47%
Sum	2477	2477	2477	7431	
Producer's accuracy	94.19%	87.81%	74.0%		
Overall accuracy			85.33%		
Kappa coefficient			78.0%		

Table 4. Accuracy assessment results for the RF model that was developed using the polarimetric parameters and their texture features.

Reference Classified as	Open Water	Sea Ice	Melt Pond	Sum	User's Accuracy
Open water	2366	7	125	2498	94.72%
Sea ice	5	2280	304	2589	88.06%
Melt pond	106	190	2048	2344	87.37%
Sum	2477	2477	2477	7431	
Producer's accuracy	95.52%	92.04%	82.68%		
Overall accuracy			90.08%		
Kappa coefficient			85.12%		

The relative importance of the variables ranked in the top 10 most important variables for the DT and RF models is shown in Figures 6 and 7 respectively. The HH backscattering coefficient was used as the most important variable in both models. The HH backscattering coefficient would be used for the discrimination of sea ice from open water and melt ponds based on the difference of surface roughness under low wind speed conditions [73,74]. In the DT model, the average of the VV backscattering coefficients was also used as the most important variable, and the average of the HH backscattering coefficients was the next important one (Figure 6). The melt pond samples of the average of the backscattering coefficients showed much higher values than the open water samples due to the strong backscattering signals from the surrounding sea ice, but smaller values than sea ice samples (Figure 5). Therefore, the average of the backscattering coefficients in a mid-incidence angle would contribute to the distinction between melt ponds on multiyear ice and open water. The standard deviation of the HH backscattering coefficients in a mid-incidence angle was identified as the second important variable in the RF model (Figure 7), which would contribute to separation of sea ice from open water and melt ponds. The average of the co-polarization phase difference and the alpha angle in a mid-incidence angle were also identified as the important variables in the RF model, which was possibly used in order to distinguish melt ponds on multiyear ice from open water. The average of the co-polarization correlation, entropy and anisotropy and the standard deviation of the phase difference in a mid-incidence angle showed a significant difference between melt ponds and other surface types, but their contributions to the machine learning models were relatively low. This would be because the melt pond samples showed much more distinct characteristics from open water for the texture

features of the HH and VV backscattering coefficients compared to other input variables derived in a mid-incidence angle (Figure 5).

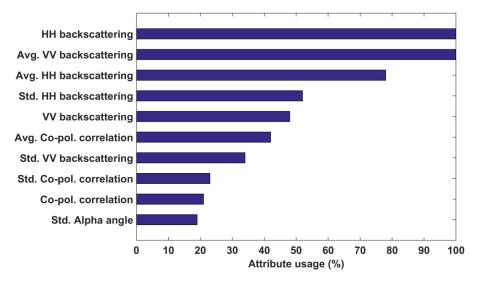


Figure 6. Attribute usage of the DT model that was developed using the polarimetric parameters and their texture features based on a 15×15 pixel window.

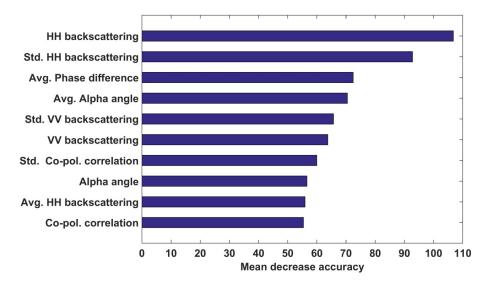


Figure 7. Mean decrease accuracy of the RF model that was developed using the polarimetric parameters and their texture features based on a 15×15 pixel window.

Melt pond mapping results from the DT and RF models were compared to the melt pond maps derived from the airborne SAR images. Figure 8 shows a comparison between a reference melt pond map and machine learning results. The open water areas detected by both models were well matched to those from the airborne SAR image. However, the DT model overestimated melt pond areas and underestimated sea ice areas compared to the melt pond map from the airborne SAR image. The RF model detected the areas of melt ponds and sea ice better than the DT model, which may be because the bootstrapping and ensemble strategies of the RF model overcome the problems of overfitting that is the limitation of the DT model [66,67,77].

Since the RF-based melt pond retrieval model using the polarimetric parameters and their texture features based on a 15×15 pixel window performed better than the other machine learning models, it was applied to the TerraSAR-X dual polarization data obtained on 21 July 2010. As there was no

reference data of melt ponds available over the area of the 2010 TerraSAR-X swath, the melt pond mapping result of the RF model was visually assessed in comparison to the amplitude image. Figure 9 shows comparisons between the amplitude images and melt pond mapping results. The melt ponds and open water detected from the RF model showed close agreement with dark areas observed in the amplitude images. The RF model detected most of the dark and small areas as melt ponds, with discrimination of large and dark areas as open water. Some melt ponds were identified by the model in dark areas of a large size, which appeared as open water (yellow circles in Figure 9). Although it is not clear whether the large and dark areas of the amplitude images are actual open water, it might be possible to say that the RF model did not produce as high performance for melt pond retrievals from the 2010 TerraSAR-X data as that from the 2011 ones, because it would be biased to the 2011 TerraSAR-X data and might not work well for the different sea ice and weather conditions.

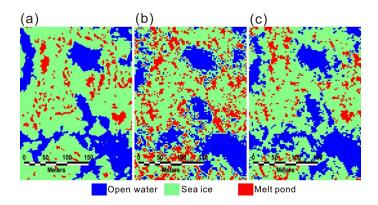


Figure 8. The comparison between (**a**) the airborne SAR- and machine learning results-based melt pond maps: (**b**) the DT model and (**c**) the RF model.

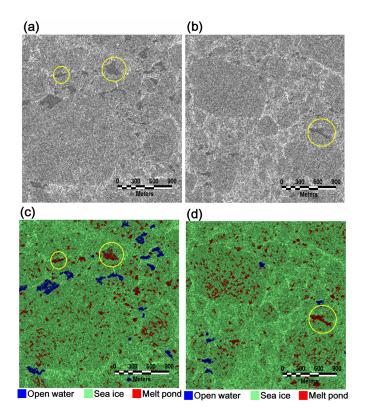


Figure 9. Visual comparisons between the 2010 TerraSAR-X HH-polarized amplitude images (**a**,**b**) and the RF model-based melt pond maps (**c**,**d**).

As the RF model produced better classification results than the DT model, the RF-derived melt pond map was used to obtain the statistics for melt ponds. The root mean square deviation (RMSD) between the sea ice concentration produced from the airborne SAR-derived maps and the RF-derived map was only 4.9% (a normalized RMSD (NRMSD) of 7.7%) (Figure 10a), which resulted from the high performance of the RF model for discriminating sea ice from open water and melt ponds. The melt pond fractions estimated from the RF-derived map were similar to those from the airborne SAR images (Figure 10b), with an RMSD of 2.4% (an NRMSD of 15.8%). The number density of melt ponds retrieved from the RF-derived map and the airborne SAR images showed an NRMSD of 17.4% (Figure 10c), which is similar to the NRMSD for the melt pond fraction (Figure 10b). However, the range of the number density retrieved from the RF-derived map $(1500-2867 \text{ km}^{-2})$ was much smaller than that from the airborne SAR images ($1061-3808 \text{ km}^{-2}$), which was clearly attributed to the lower spatial resolution of the TerraSAR-X dual-polarimetric data (3 m) than the airborne SAR data (0.3 m). The melt ponds with a narrow width could not be detected in the RF model, even though the pond areas are larger than 9 m² due to the spatial resolution of the TerraSAR-X data. The mean pond area retrieved from the RF-derived map showed a relatively large NRMSD (23.9%) compared to that from the airborne SAR-derived melt pond maps (Figure 10d). Such a large deviation can be attributed to the difference of the spatial resolutions between the TerraSAR-X and airborne SAR data.

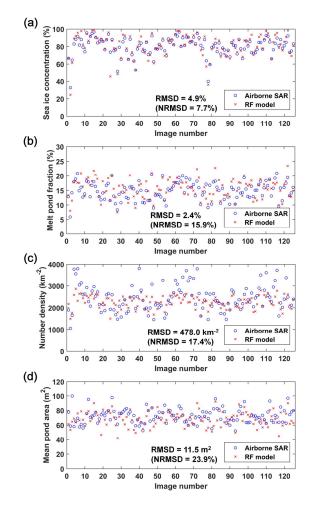


Figure 10. The comparison between the airborne SAR- and the RF model-derived statistics for melt pond and sea ice: (**a**) sea ice concentration; (**b**) melt pond fraction; (**c**) number density of ponds and (**d**) mean pond area. NRMSD, normalized RMSD.

The comparison results indicate that the high-resolution dual-polarimetric parameters and their texture features have potential to provide the reliable estimation of melt pond fraction and sea ice concentration in the summer melting peak season of the Arctic sea ice based on the RF approach. However, the RF-derived melt pond map could not estimate the number density or mean pond area accurately due to the existence of small and narrow melt ponds.

The statistics for melt ponds were computed for a 50 by 50 pixel window of the 2011 TerraSAR-X data using the RF-derived melt pond map and gridded at a 150-m grid size (Figure 11). The values of sea ice concentration were close to 100% in the areas of the multiyear ice floes, while less than 90% in the areas of the heavily-melted ice fragments (Figure 11a). The melt pond fractions on the heavily-melted ice fragments were less than 10%, while those on the multiyear ice floes varied from 10%–28% (Figure 11b). The higher melt pond fractions on the multiyear ice floes were attributed to a larger fraction of ice [28]. The number density and the mean area of melt ponds were estimated as ~3800 km⁻² (Figure 11c) and ~120 m² (Figure 11d), respectively, in the areas of both the multiyear ice floes and heavily-melted ice fragments. However, again, note that the number density and mean pond area obtained by the RF model would be inaccurate, because the narrow and small melt ponds (less than 9 m² in size) would not be detected due to the spatial resolution of the TerraSAR-X data.

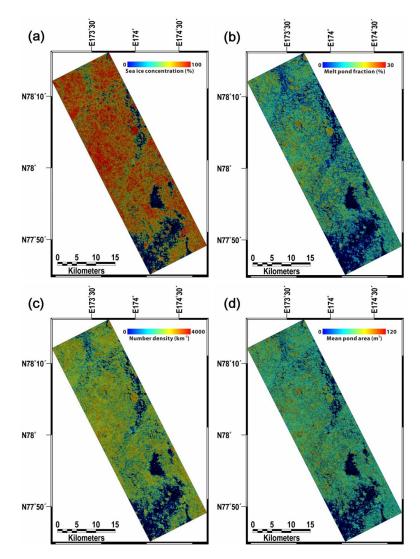


Figure 11. Maps of the statistics for melt pond and sea ice generated from the RF model-derived melt pond map: (**a**) sea ice concentration; (**b**) melt pond fraction; (**c**) number density of ponds; and (**d**) mean pond area.

Kim *et al.* [28] estimated melt pond fraction by mapping ponds from the same TerraSAR-X data based on the combination of multiscale segmentation and aggregation of the amplitude image. They reported that the melt pond fraction derived by their methodology was significantly underestimated compared to the airborne SAR survey. This implies that the use of the single-polarized backscattering amplitude only might not be sufficient for retrieval of the ponds. Since the RF model in the present study was developed using various polarimetric parameters and their texture features, which provided more abundant information to discriminate melt ponds from sea ice and open water, it was able to provide a more accurate melt pond fraction.

The machine learning models were developed and assessed using only two mid-incidence angle (32.7°) TerraSAR-X dual polarization images of very small swath widths for the summer multiyear ice floes in the Chukchi Sea. The characteristics of the polarimetric parameters for sea ice and melt ponds can change significantly with ice conditions, wind speed and incidence angles [32,34,78]. In particular, the texture features of polarimetric parameters used in the machine learning models are second order statistics, which would change significantly with the variation of incidence angles. Therefore, the melt pond retrieval models developed in this study can be applied to the X-band dual polarization SAR data of a small swath width with mid-incidence angle for detecting melt ponds on multiyear ice in the summer season, but cannot be directly used for other incidence angle data containing other sea ice types in wide areas. In order to develop a general-purpose melt pond retrieval model, it is required to use a number of polarimetric SAR data for various sea ice types with different incidence angles and to construct sufficient reference datasets corresponding to the SAR data. Furthermore, an artificial neural network approach using the texture features of polarimetric parameters is needed to be evaluated for melt pond retrievals, because it might be useful for texture-based classification [79].

The machine learning-based classification of high-resolution dual-polarization X-band SAR data with the mid-incidence angle (32.7°) shows potential to accurately estimate the melt pond fraction on the summer multiyear sea ice in the Chukchi Sea. The proposed models for melt pond detection are only applicable to situations where individual melt ponds are larger than the pixel size of SAR data, which is an important distinction from the previous studies that developed techniques for unmixing the melt pond fraction from mixed pixels [17,32]. The TerraSAR-X dual-polarization data can be effectively used for regular monitoring of the melt pond fraction on a local scale (typically less than 100 km²) based on the revisit time of the satellite, but not enough to observe melt ponds at a regional scale due to the limitation of the swath of the polarimetric SAR data. In order to study the relationship between sea ice ponding and climate change, the melt pond fractions at a much larger spatial scale should be monitored. Satellite optical data, such as MODIS and MERIS, can be used to retrieve the melt pond fraction over a regional scale [17,19,21,22]. However, the prevailing cloudy days in the summer season make it difficult to observe melt ponds using optical data. Passive microwave sensors can be used for monitoring melt ponds in the entire Arctic regardless of cloud conditions because the microwave emissivity of sea ice can vary by the fraction of melt ponds [5,11,80,81].

5. Conclusions

Melt ponds on summer multiyear sea ice in the Chukchi Sea in the Arctic were retrieved using the classification of two TerraSAR-X dual co-polarization data with the mid-incidence angle (32.7°) obtained in July 2010 and August 2011, respectively, based on two machine learning approaches—DT and RF. The reference dataset for the classification of melt ponds, sea ice and open water was constructed from the airborne SAR images obtained coincident with the TerraSAR-X data acquisition in 2011. The machine learning models using only the polarimetric parameters could not discriminate melt ponds on multiyear ice from open water due to their similar polarimetric signatures, while those using the polarimetric parameters and their spatial average and standard deviation based on a 15 × 15 pixel window showed much improved performance for the melt pond retrieval. The RF model produced better performance for retrieving melt ponds than the DT model based on the accuracy assessment. The HH backscattering coefficient, its spatial standard deviation and the average of the co-polarization phase differences and the alpha angles were defined as more contributing variables than the other ones by the RF model. The RF-derived melt pond mapping result from the TerraSAR-X data obtained in 2010 was compared to the dark areas observed in the amplitude image due to lack of reference data. The RF model identified most of the small and dark areas as melt ponds. Melt pond statistics for the 2011 TerraSAR-X data were calculated from the RF-derived melt pond map. The melt pond fraction and sea ice concentration estimated from the RF-derived melt pond map showed RMSDs of 2.4% and 4.9%, respectively, compared to the airborne SAR-derived maps. This means that there is potential to accurately retrieve melt pond fraction and sea ice concentration for multiyear ice in the Arctic summer season from high-resolution mid-incidence angle dual-polarization SAR data. However, the melt pond area because of the melt ponds being smaller than the pixel size of the TerraSAR-X data.

The melt pond retrieval models proposed in this study could not be validated for different ice types and incidence angles. The swath of the TerraSAR-X dual-polarization imaging mode is not enough to observe melt ponds on wide-area sea ice. Future research includes: (1) developing pond fraction retrieval models using multi-polarization SAR data in different incidence angles for various ice types and *in situ* observations of the ponds based on icebreakers; (2) studying the relationship between the polarimetric signatures and microwave emissivity of melt ponds; and (3) monitoring melt pond fractions over the entire Arctic using the ensemble of multi-polarization SAR data and passive microwave observations.

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Conflicts of Interest: The authors declare that there are no conflicts of interest.

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