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On idiosyncratic stochasticity of financial leverage effects



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ABSTRACT

We model leverage as stochastic but independent of return shocks and of volatility and perform likelihood-based inference via the recently developed iterated filtering algorithm using S&P500 data, contributing new evidence to the still slim empirical support for random leverage variation.

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1. Introduction

Statistical modeling of financial markets has become a key tool in the field of finance. In this literature, many statistical models focus on the dynamics of random volatilities of financial returns. These volatilities have been found to be correlated with shocks to returns and such correlations have been often referred to as leverage effects. Leverage effects have been considered by numerous studies, almost all of which assume that leverage is constant over time and which have provided ample evidence of its empirical relevance. Part of this empirical evidence has nevertheless suggested that leverage could vary randomly over time, as particularly supported by some recent data analyses. However, these analyses are very few so far, making empirical evidence regarding randomness (or lack thereof) of leverage still scant. This scantness is likely to discourage serious consideration of random leverage as an alternative to the widely accepted fixed leverage and failing to account for such randomness could distort inference (if leverage is indeed random) resulting, among other things, in poorer hedging and risk management. To help prevent such poorer financial inferences by casting light on the question of leverage randomness, this paper provides new empirical evidence supporting random leverage. This evidence is the central result of the paper and is obtained by considering a model in which leverage randomness is idiosyncratic, i.e., independent of shocks to returns and of volatility. Moreover, this empirical support for idiosyncrasy complements existing work on it that only addressed theoretical aspects.

Leverage effects have been historically modeled as correlations that are constant over time, although recent studies have considered and supported the hypothesis of random variation in this correlation, which is also the focus of this paper. The study of correlation between volatility and shocks to returns is often traced back to Black (1976) and has gained popularity since then (e.g., Harvey and Shephard, 1996; Yu, 2005; Francq and Zakoian, 2010; Asai and McAleer, 2011). More recently, some studies have formally considered the possibility that this correlation be random and have found evidence in favor of

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it: [Bandi and Renò \(2012\)](#) considered both discrete- and continuous-time models but focused on jump-diffusion stochastic volatility models with leverage dynamics driven by spot volatility through a general function that was estimated non-parametrically relying on high-frequency S&P500 data; and [Yu \(2012\)](#) proposed a discrete-time stochastic volatility model with white noise leverage driven by the sign and magnitude of shocks to returns and estimated it semi-parametrically based on multiple US return series (including S&P500) relying on Markov chain Monte Carlo Bayesian methods. Also in this line of work, [Veraart and Veraart \(2012\)](#) focused on the theoretical properties of continuous-time stochastic volatility models with leverage dynamics driven by parametric Jacobi processes independent of both shocks to returns and of volatility, but left for future work contributing further empirical evidence either supporting or failing to support both random leverage in general and idiosyncratic random leverage in particular, which is our main concern in this paper.

The problem that this paper aims to lighten is the limited current empirical evidence regarding randomness of leverage, which is aggravated both by a limited theoretical exploration of such randomness and by its complications in inference and which can steer researchers away from considering the recent support for random leverage. On one hand, much theoretical work characterizing fixed-leverage models exists and provides a haven for empirical analyses based on them (for a review of GARCH-type fixed-leverage models, see for example [Francq and Zakoian, 2010](#); for a review of stochastic volatility fixed-leverage models, see for example [Asai and McAleer, 2011](#)). On the other hand, theoretical work addressing random-leverage models seems to be rare and to consist mainly of the three references mentioned above ([Bandi and Renò, 2012](#); [Veraart and Veraart, 2012](#); and [Yu, 2012](#)). Random-leverage models may also imply a more complex inference, for example because of treating leverage as an unobserved variable (in a state-space framework, as in [Yu, 2012](#)) or because of requiring high-frequency data (as in [Bandi and Renò, 2012](#); and [Veraart and Veraart, 2012](#)). These considerations about inference and theory are likely to complicate the flourishing of new studies addressing the empirical relevance of randomness in leverage, hence deterring its consideration as an alternative to the widely adopted fixed leverage.

Failure to consider random leverage could induce both an undue confidence in conclusions and biases and would hence work against prevention of poor hedging and risk management, to which this paper seeks to contribute. Misleading inference can result from models that fix features that in fact vary. Examples of this include heteroskedastic disturbances in otherwise properly specified linear models ([White, 1980](#)) and over-dispersed data in the context of generalized linear models ([McCullagh and Nelder, 1989](#)), both of which result in downward biased standard errors (which lead to faulty inference). In general, similar biases are also likely to occur in any parameter of non-linear models (as investigated for example in [He et al., 2010](#)), as a result of the model with the fixed parameter attempting to replicate the effects of the ignored parameter variation. Ignoring variation in leverage could affect, among others, hedging, due to the role of leverage in this operation (as emphasized for example in [Lai and Sheu, 2011](#)), and risk management, through inaccurate inferences about (for example) value-at-risk. Contributing to prevent such poorer financial inferences is the ultimate goal of this paper.

The main contribution of this paper is to provide new empirical evidence supporting random leverage based on a stochastic idiosyncratic model for it, in which likelihood-based inference is performed using S&P500 data. The evidence comes from comparing two stochastic volatility models: the well-established, fixed-leverage, asymmetric autoregressive model of [Harvey and Shephard \(1996\)](#) and one where the leverage parameter is assumed to follow a random walk (as defined in Section 2). Random walks are one of the simplest possible idiosyncratic dynamic models (since they only introduce one parameter: the noise variance), making them an interesting candidate for our goal, and can point to more complex models to be explored in future research, e.g., models where unobserved state variables also play a role in leverage dynamics, along the lines of the specification in [Bandi and Renò \(2012\)](#) or of some continuous-time stochastic volatility models with multiple volatility factors ([Christoffersen et al., 2009](#)). In addition, random walks have proved useful in similar contexts considered in the macroeconomics and the financial time-varying parameter literature for several reasons (see for example references in [Müller and Petalas, 2010](#)). These reasons include the ability to approximate breaks and that they can facilitate inference. Inference in this paper is implemented via the recently developed algorithm of iterated filtering for likelihood-based inference in general state-space models (as detailed in Section 3) to analyze S&P500 daily return data. When analyzing these data (in Section 4), the maximized likelihood for the fixed-leverage model is found to be lower than that for the random-walk model. This finding is consistent with interval estimates of the unobserved leverage process, which also suggest time variation. Both these results constitute the desired valuable evidence and (as discussed in Section 5) not only strengthen the still slim empirical support for random leverage (reported so far only for the non-idiosyncratic models of [Yu, 2012](#) and of [Bandi and Renò, 2012](#)) but also complement the theoretical considerations about idiosyncratic stochastic leverage of [Veraart and Veraart \(2012\)](#).

2. Stochastic volatility with random-walk leverage

Let y_t be a financial rate of return in time period t and σ_t^2 the volatility of y_t , both related by the discrete-time stochastic volatility model with the following state-space representation:

$$\begin{aligned} y_t &= \sigma_t^2 \epsilon_t = \exp\left\{h_t/2\right\} \epsilon_t \\ h_t &= \mu_h(1 - \phi) + \phi h_{t-1} + \eta_t \sigma_\eta \sqrt{1 - \phi^2} \\ \text{Corr}[\eta_t, \epsilon_{t-1}] &= \rho, \end{aligned} \quad (1)$$

where $\{\epsilon_t\}$ and $\{\eta_t\}$ are Gaussian unit-variance white noise processes. In this model, both y_t and h_t are covariance stationary for $|\phi| < 1$. If we let $\eta_t = \rho \epsilon_{t-1} + \omega_t \sqrt{1 - \rho^2}$ with $\{\omega_t\}$ also being a Gaussian unit-variance white noise process that

is independent of $\{\epsilon_t\}$, then $\{\eta_t\}$ remains a Gaussian unit-variance white noise process with η_t satisfying the required correlation with ϵ_{t-1} . Hence, the set of Eqs. (1) defines the same model as the set of equations

$$\begin{aligned} y_t &= \sigma_t^2 \epsilon_t = \exp\{h_t/2\} \epsilon_t \\ h_t &= \mu_h(1 - \phi) + \phi h_{t-1} + \sigma_\eta \sqrt{1 - \phi^2} \left(\rho \epsilon_{t-1} + \nu_t \sqrt{1 - \rho^2} \right) \\ &= \mu_h(1 - \phi) + \phi h_{t-1} + \beta \rho \exp\{-h_{t-1}/2\} + \sigma_\omega \omega_t, \end{aligned} \quad (2)$$

with $\beta = y_{t-1} \sigma_\eta \sqrt{1 - \phi^2}$ and $\sigma_\omega = \sigma_\eta \sqrt{1 - \phi^2} \sqrt{1 - \rho^2}$. That sets of Eqs. (1) and (2) are equivalent has often been pointed out (see for example, [Harvey and Shephard, 1996](#); [Malik and Pitt, 2011](#); [Yu, 2012](#)). The stochastic volatility model defined by the set of Eqs. (2) is a re-parameterization of the asymmetric stochastic volatility model of [Harvey and Shephard \(1996\)](#) (so that neither the mean nor the variance of h_t depends on ϕ) and this will be the model that we will allude to when in the rest of the paper we refer to the fixed-leverage model.

As an alternative to the fixed-leverage model, we consider letting an appropriate transformation of leverage follow a random walk. If such transformation is the Fisher transformation, leverage is allowed to vary over its natural range $[-1, 1]$, whereas a logit transformation might be preferred if negativity is to be imposed (which we avoid given the existing evidence pointing to the possibility of positive correlations, as in [Yu, 2012](#)). The Fisher-transformed leverage $\{\rho_t\}$ process driven by the random-walk leverage factor process $\{f_t\}$ is defined by equations

$$\begin{aligned} \rho_t &= \frac{e^{2f_t} - 1}{e^{2f_t} + 1} \\ f_t &= f_{t-1} + \sigma_v \nu_t, \end{aligned} \quad (3)$$

where $\{\nu_t\}$ is a Gaussian white noise process again independent of $\{\epsilon_t\}$ and of $\{\eta_t\}$. Replacing ρ by (3) in Eqs. (2) gives the following state-space model equations:

$$\begin{aligned} y_t &= \sigma_t^2 \epsilon_t = \exp\{h_t/2\} \epsilon_t \\ h_t &= \mu_h(1 - \phi) + \phi h_{t-1} + \beta \frac{e^{2(f_{t-1} + \sigma_v \nu_t)} - 1}{e^{2(f_{t-1} + \sigma_v \nu_t)} + 1} \exp\{-h_{t-1}/2\} + \sigma_\omega \omega_t \\ f_t &= f_{t-1} + \sigma_v \nu_t, \end{aligned} \quad (4)$$

which define a model that we refer to as the random-walk leverage model. In spite of the random walk, both $E[\rho_t]$ and $V[\rho_t]$ are bounded, even if $\{\rho_t\}$ is not covariance stationary. The covariance stationarity of both y_t and h_t for $|\phi| < 1$ of the fixed-leverage model is retained by the random-walk leverage model, both of which belong to the family of non-linear, non-Gaussian state-space models.

3. Likelihood-based inference

Non-linear, non-Gaussian state-space models have been studied extensively (see for example [Durbin and Koopman, 2001](#)). In these models, it is not straightforward to check that the appealing, usual properties of maximum likelihood estimates hold, in part due to the likelihood being in general analytically intractable. These difficulties did not prevent early developments of simulation-based methods to perform likelihood-based inference in such models ([Shephard and Pitt, 1997](#); [Durbin and Koopman, 1997](#)), which is on its own a challenge that has been taken on more recently ([Liesenfeld and Richard, 2003](#); [Richard and Zhang, 2007](#); [Jungbacker and Koopman, 2007](#)). Another recent contribution, which we favor in this paper, is the iterated filtering algorithm.

Iterated filtering has been successfully implemented to do inference not only in highly non-Gaussian, non-linear state-space models, mostly in a context of biological applications ([Bhadra et al., 2011](#); [Bretó et al., 2009](#); [He et al., 2010](#); [King et al., 2008](#); [Laneri et al., 2010](#); [Shrestha et al., 2011](#)) but also in the continuous-time Lévy-driven stochastic volatility model of [Bandorff-Nielsen and Shephard \(2001\)](#) (see the discussion on [Andrieu et al., 2010](#)). The iterated filtering algorithm is based on a sequence of filtering operations which has been shown to converge to the maximum likelihood estimate ([Ionides et al., 2006, 2011](#)). The algorithm boils down to extending the model of interest by letting the model parameters that are to be estimated become artificially random. Then, starting at an initial guess for the estimate $\hat{\theta}_0$ and successively diminishing the artificial random perturbations to the parameters, the algorithm generates a sequence of updated parameter estimates $\hat{\theta}_1, \hat{\theta}_2, \dots$ that converges to the maximum likelihood estimate. Iterated filtering has been implemented in this paper using the software package POMP (Partially Observed Markov Processes, [King et al., 2010](#)) written for the R statistical computing environment ([R Development Core Team, 2010](#)). Iterated filtering can be implemented as long as the state-space model satisfies the usual conditions of state Markovianity and of measurement independence conditional on current states (which are met by our models, in spite of y_{t-1} entering the equations for h_t through β). Nevertheless, these two conditions are necessary but not sufficient to converge to a maximum.

Table 1

Parameter and log-likelihood (ℓ) estimates and standard errors (in parenthesis) for the fixed- and random-walk leverage models and S&P500 data. These data were analyzed with the following algorithmic parameters: 150 iterations, an exponential decay of perturbations of $\alpha = 0.978$ and 8000 particles. 70,000 particles were used to obtain the estimates of ℓ , which result from taking the average of two likelihood evaluations from which we calculate the Monte Carlo standard error. Parameter standard errors were derived via a numerical approximation to the Hessian (see Ionides et al., 2006). They are computationally affordable and give a reasonable idea of the scale of uncertainty and can hence be used to construct approximate confidence intervals. More rigorous confidence intervals can be obtained via profile likelihoods.

Model	μ_h	ϕ	σ_η	ρ	σ_v	ℓ
Fixed leverage	-0.2506 (0.0710)	0.9805 (0.0017)	0.9003 (0.0375)	-0.6579 (0.0599)	-	-8416.44 (0.0410)
Random-walk leverage	-0.2610 (0.0776)	0.9818 (0.0015)	0.9222 (0.0406)	-	0.0086 (0.0013)	-8409.06 (0.1333)

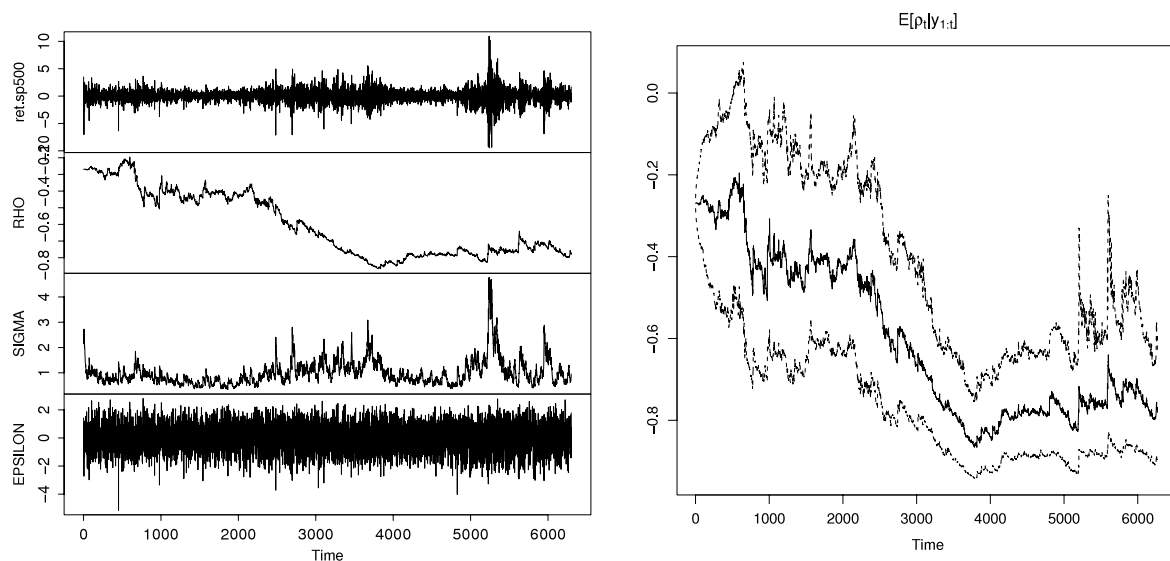


Fig. 1. Left panel: data and filtering means of some unobserved variables for the random-walk leverage model (top to bottom): S&P500 daily returns, leverage correlation ρ_t , volatility factor h_t and return shock ϵ_t . Right panel: mean (solid line), the first quartile and the third quartile (dashed lines) of the filtering distributions of the unobserved leverage correlation ρ_t (conditional on the contemporaneously available data y_1, \dots, y_t). All results were obtained using a particle filter with 5000 particles.

Convergence of iterated filtering to the maximum likelihood estimate has been shown under some regularity conditions on the likelihood surface and on the algorithmic parameters (see Ionides et al., 2006, 2011, for details). The algorithmic parameters include the number of iterations, the initial levels of artificial randomness and the speed at which this randomness diminishes from one iteration to the next (and also the number of particles if iterated filtering is implemented via particle filters, as in this paper). The conditions on the likelihood surface are rather technical so, in practice, convergence is assessed via convergence diagnostic plots (included in Appendix). These plots suggest an appropriate choice of algorithmic parameters and represent evidence that the likelihood has in fact been maximized in our analysis of S&P500 data.

4. Empirical results

A sample of S&P500 daily returns is analyzed in Table 1 and in Fig. 1, which report estimates and results that broadly agree with the related results provided by Bandi and Renò (2012) and by Yu (2012) and that seem to support random and idiosyncratic leverage variation. The returns were demeaned prior to the analysis and correspond to the 25-year period from January 4, 1988 to December 31, 2012. In this period, there are 6302 observations, which are comparable to the sample size used in Bandi and Renò (2012), almost six times that used in Yu (2012), and crucial to obtain the high estimate precision reported in Table 1. All the estimates in Table 1 seem to be statistically significant and they correspond to either parameters that are common to both models or specific to each model. On one hand, the estimates for common parameters μ_h , ϕ and σ_η are almost identical for both models (and do not appear to be statistically different). They are also in the usual range reported in the literature (after accounting for the fact that some analysis may not use our parameterization to remove ϕ from the marginal mean and variance of h_t , e.g., Yu, 2012). On the other hand, the estimated correlation ρ specific to the fixed-leverage model lies in the interval $(-0.7399, -0.5759)$. This interval is in the upper end of correlation strength usually reported but seems to agree with the results in Yu (2012) and in Bandi and Renò (2012). On one hand, Bandi and Renò (2012) also find evidence of leverage being “more negative than those generally found in the literature” (Bandi and Renò, 2012, page 105, in light of their Fig. 4) based on results for the 1990–2009 period (which is a large subset of the period we consider). On the

other hand, Yu (2012) does not find such a strong correlation for the period 1985–1989 (which is a much shorter period ending one year after ours begin) and in which the interval estimate for ρ is approximately $(-0.5431, -0.1951)$. This interval is nevertheless very similar to our filtering interval for ρ_t of about $(-0.55, -0.10)$ reported around the period 1988–1999 in Fig. 1. Fig. 1 also supports a relatively stable leverage around -0.4 for the decade 1988–1997 (roughly, the first 2500 observations) followed by a progressive drop to about -0.8 for the last decade 2003–2012 (roughly, the last 2500 observations). This strong correlation in the last decade agrees with the findings reported in Bandi and Renò (2012), as explained in the lines above. The smooth progression from around -0.4 to around -0.8 and the stability around these values for about a decade each are also consistent with the fixed-leverage correlation being estimated around -0.6 . A final finding consistent with previous analysis that we point out is positive leverage. Positive leverage was found in Yu (2012) and, although very timidly, it also appears in Fig. 1 within the filtering intervals of ρ_t for only a few months in one of the early years in our 25-year sample. Providing a sound, deeper financial interpretation of these empirical findings is beyond the goal of this paper of throwing light on the issue of leverage randomness.

5. Discussion

The new evidence reported here supporting random leverage lies in the likelihood difference and in the interval estimates for the unobserved leverage ρ_t and both strengthens the current, scant empirical support for general random leverage and complements existing theoretical work on idiosyncratic leverage. The reported likelihood of the random-walk leverage model is higher than that of the fixed-leverage one. A formal model comparison may be carried using a model selection criterion, like Akaike's information criterion. Any such criteria that penalize higher likelihoods according to some increasing function of the number of estimated parameters will favor the random-walk leverage model, since the number of parameters in both models is four. However, these models are not nested and cannot be compared with a likelihood-ratio test. Still, for such test to fail to deem significant at a 5% level the improvement of 6.78 log-likelihood units that Table 1 reports, it would take a model with at least seven more parameters than the fixed-leverage model. This number of additional allowed parameters gives an informal measure of how higher the ability to capture the dynamics in the data of the random-walk leverage model is compared to that of the fixed leverage model.

Although such comparison provides the sought evidence supporting the incipient literature on random leverage, it does not suffice to address the more intricate issue of whether the random-walk leverage model considered here is more appropriate than other possible models. In fact, it could even be the case that the current scant evidence that supports different random leverage models (including that of this paper) merely reflects that there is some other mechanism at work (different than random leverage) that fixed leverage models are missing, like for example multiple stochastic volatility factors (Chernov et al., 2003; Christoffersen et al., 2009). Both comparing different random leverage models and exploring alternative mechanisms to random leverage is beyond the scope of this paper, which focuses on comparing the random-walk and the fixed leverage models.

Other informal support in favor of the random-walk leverage model is given by the interval estimates for ρ_t reported in Fig. 1. The upper and lower bounds of these intervals evolve more or less monotonically from approximately $(-0.55, -0.1)$ down to approximately $(-0.6, -0.9)$. These intervals intersect during a large fraction of the period considered with the 95% confidence interval reported for the fixed-leverage model ρ of $(-0.7399, -0.5759)$. Nevertheless, this intersection does not occur (or is minimal) in some sub-periods, supporting time-variation even if uncertainty about ρ_t is taken into account. Ignoring this uncertainty and focusing on the filtering mean of ρ_t also provides information about leverage stationarity, which has been assumed in previous theoretical work regarding idiosyncratic random leverage.

The leverage stationarity assumption of Veraart and Veraart (2012) suggests that the filtered ρ_t should oscillate around a mean leverage value. Such oscillations would take longer times as parameters approached non-stationarity regions and hence (for a fixed sample size) ρ_t would return fewer times to its mean within the sample. Such mean-reverting behavior seems to be supported by the filtering means in Fig. 1 but only for some sub-periods of our sample (e.g., observations 500 to 2000, or 4500 to 6000) and not for the entire sample. This suggests the following two conjectures (left to be explored in future research): first, a stationary model might be more appropriate for certain sub-periods than for the entire period considered here; and second, if a stationary model were used (instead of a random walk) for the entire sample, parameters would likely be estimated to be near non-stationarity regions (in fact, this was observed at preliminary stages of our work when fitting a stationary AR(1) leverage model to the entire sample). Such closeness to non-stationarity regions would raise the question of testing for non-stationarity. The need for such tests has given rise to an abundant literature that extends the seminal work on unit root testing of Dickey and Fuller (1979). Unit roots have also been considered in the state-space framework, having produced so far a careful study of diffuse priors for Gaussian exact filtering and smoothing (see for example Durbin and Koopman, 2001) and of unit-root testing in Gaussian, linear state-space models (Chang et al., 2009), but no results seem to have been developed so far for the non-linear, non-Gaussian framework needed in this paper.

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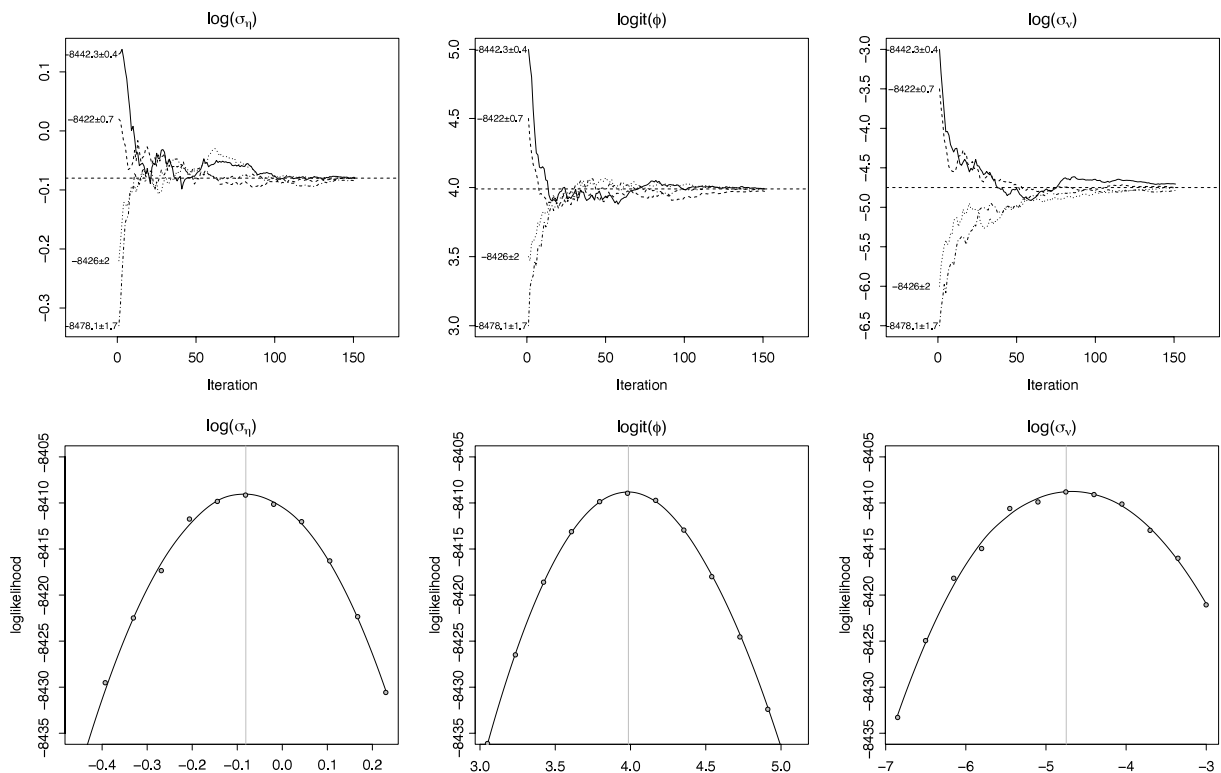


Fig. A.2. Sample of diagnostic plots for iterated filtering corresponding to transformations (to \mathbb{R}) of parameters of random-walk leverage model: $\log(\sigma_\eta)$ (left column), $\text{logit}(\phi)$ (center column), and $\log(\sigma_v)$ (right column). *Top panels:* trajectories of the algorithm updates showing $\hat{\theta}_1, \hat{\theta}_2, \dots, \hat{\theta}_{150}$ converge to the maximum likelihood estimate (horizontal line) starting from four different starting points $\hat{\theta}_0$. On the left margin, likelihood estimates at the starting point $\hat{\theta}_0$ and Monte Carlo interval half width, obtained by averaging four replicates with 10,000 particles each. *Bottom panel:* sliced likelihoods for the corresponding parameters, in which the likelihood surface is explored along one of the parameters, keeping the other parameters fixed at the point which iterated filtering converges to. Each filled circle shows the likelihood estimate obtained with 70,000 particles. The curve results from smoothing the likelihood evaluations with local quadratic regression.

Appendix

See Fig. A.2.

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