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# Learning in ultrametric committee machines 

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#### Abstract

The problem of learning by examples in ultrametric committee machines (UCMs) is studied within the framework of statistical mechanics. Using the replica formalism we calculate the average generalization error in UCMs with $L$ hidden layers and for a large enough number of units. In most of the regimes studied we find that the generalization error, as a function of the number of examples presented, develops a discontinuous drop at a critical value of the load parameter. We also find that when $L>1$ a number of teacher networks with the same number of hidden layers and different overlaps induce learning processes with the same critical points.


Keywords Multilayer-Networks, Learning-by-Examples

## 1 Introduction

From a theoretical perspective, neural networks are the archetype of disordered systems whose study has motivated researchers to develop new statistical mechanics techniques. Being idealizations used to model some aspects of the brain's behavior, they represent a new approach to the problem of computation, based on a paralleled processing of information. As a consequence, neural networks research is multidisciplinary; models inspired in biologic observations have been used to better understand emergent phenomena [1], pattern recognition and task reproduction [2], associative memory capacity [3] and neural developing [4]; several aspect of the learning process have been investigated by using recurrent [5] and spiking networks [6]; applications using neural networks have been recently developed for credit assignment [7] and Bayesian inference [8]. These research has also played a complementary role to studies in vivo [9-11]. The work described here is motivated by the need to better understand the learning by examples process in artificial networks to help the development of more efficient automatic systems.

One of the most well-studied and better understood feed-forward networks is the perceptron [12-14] which, because of its simplicity, has very limited computational capabilities. Ultrametric Committee Machines (UCMs), as presented in [15], represent one step forward in architectural complexity and, as a consequence, they are potentially better suited for real world applications. UCMs are fully connected committee machines with $K$ units in the first of its $L$ hidden layers, a tree like structure linking hidden-to-hidden layers and non-zero synaptic overlaps at the hidden-to-input level only. These overlaps, i.e. the inner products between synaptic vectors belonging to different units, form an ordered set $\left\{\tilde{\zeta}_{j}, j=1,2, \ldots, L\right\}$, where $\tilde{\zeta}_{j} \gg \tilde{\zeta}_{i}$ for all $j>i$. The overlap's subindex indicates the number of layers we have to go forward to find the common root to both units thus indicating the ultrametric distance between them (see figure 1). Although more sophisticated than the perceptron, some of the UCM's computational properties can be analytically obtained. Indeed, we show in this article that

[^0]by the application of the replica trick, it is possible to study the learning by examples process when, considering students and teachers of the same architecture, the number of examples presented to the student is proportional to the number of units in one of the $L$ hidden layers of the teacher. This scaling emerges naturally from the expression of the free energy of the system (see below).

Most of the studies found in the literature, in the area of learning process in networks, consider only the case where the teacher's synaptic overlaps are set to zero. Recently, [15], we found that there is a clear relationship between the magnitude of these overlaps and how difficult is to reproduce the teacher's classification. In this respect our results give support to the definition of network complexity presented in [17]. Understanding the link between task difficulty and network complexity is fundamental for the development of tools for practical applications.

A more complete description of UCM's is presented as follows. UCMs are fully connected committee machines with $L$ hidden layers organized in such a way that the number of units in the $L$-th layer (last hidden) is $K_{L}$, each one of them linked to $K_{L-1}$ units in the $(L-1)$-th layer through unit weights. This tree-like structure is repeated until reaching the first hidden layer, thus the total number of units populating the $\ell$-th hidden layer is $K_{L} K_{L-1} \ldots K_{\ell}$. The $K_{L} \ldots K_{1}=K$ units in the first hidden layer are connected to the inputs through synaptic vectors $\mathbf{w}_{\mathbf{k}_{1}} \in \mathbb{R}^{N}$ whose overlap matrix $[\boldsymbol{\Omega}]_{\mathbf{k}_{1}, \mathbf{k}_{1}^{\prime}} \equiv \mathbf{w}_{\mathbf{k}_{1}}^{\top} \mathbf{w}_{\mathbf{k}_{1}^{\prime}} / N$ satisfies the following relationship:

$$
\begin{equation*}
[\boldsymbol{\Omega}]_{\mathbf{k}_{1}, \mathbf{k}_{1}^{\prime}}=\delta_{\mathbf{k}_{1}, \mathbf{k}_{1}^{\prime}}\left(1-\tilde{\zeta}_{1}\right)+\ldots+\delta_{k_{L}, k_{L}^{\prime}}\left(\tilde{\zeta}_{L-1}-\tilde{\zeta}_{L}\right)+\tilde{\zeta}_{L} \tag{1}
\end{equation*}
$$

where $\mathbf{w}^{\top}$ is the transpose of the vector $\mathbf{w}$, the indexes $\mathbf{k}_{\ell} \equiv\left[k_{L}, k_{L-1}, \ldots, k_{\ell}\right]$ run over all hidden units of the $\ell$-th layer, $\delta_{\mathbf{k}_{\ell} \mathbf{k}_{\ell}^{\prime}} \equiv \prod_{m=\ell}^{L} \delta_{k_{m} k_{m}^{\prime}}$ and $\delta_{i j}=1$ if and only if $i=j$ and 0 otherwise and the overlaps $\tilde{\zeta}_{j}$ satisfy the relationship:

$$
\begin{equation*}
\tilde{\zeta}_{\ell}=\frac{\zeta_{\ell}}{\prod_{j=1}^{\ell} K_{j}} \tag{2}
\end{equation*}
$$

where the $\zeta_{j}$ are independent on the size of the system. The matrix of overlaps $\boldsymbol{\Omega}$ is ultrametric [18], hence UCMs. All the units that compose the network are binary, and process their inputs according to the following rules: the output unit $\sigma_{\mathbb{W}}(\mathbf{S}) \equiv \operatorname{sgn}\left(\sum_{k_{L}=1}^{K_{L}} \sigma_{k_{L}}(\mathbf{S}) / \sqrt{K_{L}}\right)$, the $\ell$-th hidden layer unit $\sigma_{\mathbf{k}_{\ell}}(\mathbf{S}) \equiv \operatorname{sgn}\left(\sum_{k_{\ell-1}=1}^{K_{\ell-1}} \sigma_{\left[\mathbf{k}_{\ell-1}\right]}(\mathbf{S}) / \sqrt{K_{\ell-1}}\right)$ and the first hidden layer unit $\sigma_{\mathbf{k}_{1}}(\mathbf{S}) \equiv \operatorname{sgn}\left(\mathbf{w}_{\mathbf{k}_{1}}^{\top} \mathbf{S} / \sqrt{N}\right)$, where $\mathbb{W}=\left\{\mathbf{w}_{\mathbf{k}_{1}} \in \mathbb{R}^{N}\right.$ and $\left.\mathbf{w}_{\mathbf{k}_{1}}^{\top} \mathbf{w}_{\mathbf{k}_{1}}=N\right\}$ is the set of synaptic vectors associated to the first hidden layer's units and $\mathbf{S} \in\{1,-1\}^{N}$. In figure 1 we present an UCM with $L=3$ hidden layers and $K_{3}$, $K_{2} K_{3}$ and $K_{1} K_{2} K_{3}=K$ units in each layer.

We present as follows an investigation on the learning by examples process in UCMs, which is based upon [19-21] and generalizes the results found in [22]. In section 2 we present the problem in the language of statistical mechanics, in section 3 we present our results for the general case and a study on the particular cases where $L=1$ and 2 . Section 4 synthesizes our conclusions and final considerations.

## 2 Replica symmetric analysis

Given a set of examples $\mathcal{S}_{P}=\left\{\left(\boldsymbol{\xi}_{\mu}, \sigma_{\mathbb{W} 0}\left(\boldsymbol{\xi}_{\mu}\right)\right)\right\}_{\mu=1}^{P}$, where the patterns $\boldsymbol{\xi}_{\mu} \in\{1,-1\}^{N}$ have been classified by an UCM teacher $\mathbb{W}^{0}$ with labels $\sigma_{\mathbb{W}^{0}}\left(\boldsymbol{\xi}_{\mu}\right) \in\{1,-1\}$, we can define the Hamiltonian of the student $\mathbb{W}$ by $H_{N}\left(\mathbb{W} ; \mathcal{S}_{P}\right) \equiv \sum_{\mu=1}^{P} \Theta\left(-\sigma_{\mathbb{W} 0}\left(\boldsymbol{\xi}_{\mu}\right) \sigma_{\mathbb{W}}\left(\boldsymbol{\xi}_{\mu}\right)\right)$, where $\sigma_{\mathbb{W}}\left(\boldsymbol{\xi}_{\mu}\right) \in\{1,-1\}$ is the classification given by the student to the $\mu$-th pattern and $\Theta(x>0)=1$ and 0 otherwise. We are interested on computing the system's statistical properties at zero temperature in the thermodynamic limit $(N \uparrow \infty)$, and in the large network regime $(1 \ll K<\infty)$, through the calculation of the partition function:

$$
\begin{equation*}
Z_{N}\left(\mathcal{S}_{P}\right)=\int \mathrm{d} \rho(\mathbb{W}) \prod_{\mu=1}^{P} \Theta\left(\sigma_{\mathbb{W} 0}\left(\boldsymbol{\xi}_{\mu}\right) \sigma_{\mathbb{W}}\left(\boldsymbol{\xi}_{\mu}\right)\right) \tag{3}
\end{equation*}
$$

where $\mathrm{d} \rho(\mathbb{W})$ is a measure of the synaptic vectors compatible with the UCM character of the student. $Z_{N}\left(\mathcal{S}_{P}\right)$ can be interpreted as the fraction of vectors in $\mathbb{R}^{N K}$ satisfying the constraints imposed by the


Fig. 1 Typical feed-forward network architecture studied in this article. This committee has $L=3$ hidden layers with synaptic overlaps in the hidden-to-input layer. All the synaptic weights linking hidden-to-hidden and hidden-to-output units are set to one. Observe that the highlighted synaptic vector $\mathbf{w}_{2,2,1}$ corresponds to the unit with index $\mathbf{k}_{1}=[2,2,1]$, i.e. the unit linked to the output through the path $2,2,1$. The network is composed by $K_{3}, K_{2} K_{3}$ and $K_{1} K_{2} K_{3}$ units in each layer and the boxes illustrate the meaning of the numbers $K_{1}, K_{2}$ and $K_{3}$.
$\Theta$ function. The zero temperature free energy of the system is defined as $f_{N}\left(\mathcal{S}_{P}\right) \equiv-\frac{1}{N K} \ln Z_{N}\left(\mathcal{S}_{P}\right)$, which is of order one and self averaging in the $N \uparrow \infty$ limit. Thus, we have that the statistical properties of the system are conveyed by the quenched average of the free energy, that can be computed by the replica trick:

$$
\begin{equation*}
f=-\lim _{N \rightarrow \infty} \frac{1}{N K} \lim _{n \rightarrow 0} \frac{\left\langle\left\langle Z_{N}^{n}\left(\mathcal{S}_{P}\right)\right\rangle_{\mathbb{W} 0}\right\rangle_{\xi}-1}{n} \tag{4}
\end{equation*}
$$

Assuming that the number of patterns $P$ presented to the student scales with the size of the synaptic vectors as $P=\alpha N$, where $\alpha$ is the load parameter, the quenched average of the replicated system can be expressed as:

$$
\left\langle\left\langle Z_{N}^{n}\left(\mathcal{S}_{P}\right)\right\rangle_{\mathbb{W} 0}\right\rangle_{\boldsymbol{\xi}}=\int \prod_{a=0}^{n} \mathrm{~d} \rho\left(\mathbb{W}^{a}\right) \exp \left(\alpha N G_{E, N}^{(n)}\left(\left\{\mathbb{W}^{a}\right\}\right)\right),
$$

where the pattern distribution $\mathcal{P}\left(\boldsymbol{\xi}_{\mu}\right)=\prod_{j=1}^{N} \mathcal{P}\left(\xi_{j, \mu}\right)=2^{-N}$ is independent of $\mu$ and

$$
G_{E, N}^{(n)}\left(\left\{\mathbb{W}^{a}\right\}\right) \equiv-\ln \left\langle\prod_{a=1}^{n} \Theta\left(\sigma_{\mathbb{W}^{0}}(\boldsymbol{\xi}) \sigma_{\mathbb{W}^{a}}(\boldsymbol{\xi})\right)\right\rangle_{\boldsymbol{\xi}}
$$

By means of delta functions we can introduce the parameters $N q_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a, b} \equiv \mathbf{w}_{\mathbf{k}_{1}}^{a \top} \mathbf{w}_{\mathbf{m}_{1}}^{b}$ for all $0<a<b \leq n$, $N t_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a} \equiv \mathbf{w}_{\mathbf{k}_{1}}^{a \top} \mathbf{w}_{\mathbf{m}_{1}}^{a}$ for all $\mathbf{k}_{1} \neq \mathbf{m}_{1}$ and $N r_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a} \equiv \mathbf{w}_{\mathbf{k}_{1}}^{a \top} \mathbf{w}_{\mathbf{m}_{1}}^{0}$, and considering that the student and teacher committees satisfy $N=\mathbf{w}_{\mathbf{k}_{1}}^{a \mathrm{~T}} \mathbf{w}_{\mathbf{k}_{1}}^{a}$ for all $0<a \leq n$ and $N[\boldsymbol{\Omega}]_{\mathbf{k}_{1}, \mathbf{m}_{1}}=\mathbf{w}_{\mathbf{k}_{1}}^{0 \top} \mathbf{w}_{\mathbf{m}_{1}}^{0}$, where $\boldsymbol{\Omega}$ is as defined in (1), we can express the zero temperature, replicated partition function as:

$$
\begin{aligned}
& \left\langle\left\langle Z_{N}^{n}\left(\mathcal{S}_{P}\right)\right\rangle_{\mathbb{W} 0}\right\rangle_{\boldsymbol{\xi}}=\int \prod_{\mathbf{k}_{1} \mathbf{m}_{1}}\left(\prod_{a<b} \frac{\mathrm{~d} q_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a, b} \mathrm{~d} \hat{q}_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a, b}}{2 \pi / N} \prod_{a} \frac{\mathrm{~d} r_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a} \mathrm{~d} \hat{r}_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a}}{2 \pi / N}\right) \\
& \int \prod_{a}\left(\prod_{\mathbf{k}_{1}<\mathbf{m}_{1}} \frac{\mathrm{~d} t_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a} \mathrm{~d} \hat{t}_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a}}{2 \pi / N} \prod_{\mathbf{k}_{1}} \frac{\mathrm{~d} \hat{\kappa}_{\mathbf{k}_{1}}^{a}}{4 \pi}\right) \exp \left[-\alpha N G_{E, N}^{(n)}(\mathscr{P})-\frac{1}{2} N G_{S, N}^{(n)}(\mathscr{P} ; \hat{P})\right],
\end{aligned}
$$

where $\mathscr{P} \equiv\left\{t_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a}\right\} \cup\left\{r_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a}\right\} \cup\left\{q_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a, b}\right\}$ and $\hat{\mathscr{P}} \equiv\left\{\hat{\kappa}_{\mathbf{k}_{1}}^{a}\right\} \cup\left\{\hat{r}_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a}\right\} \cup\left\{\hat{t}_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a}\right\} \cup\left\{\hat{q}_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a, b}\right\}$ and:

$$
\begin{aligned}
N G_{S, N}^{(n)}(\mathscr{P} ; \hat{\mathscr{P}}) \equiv & -2 \ln \left\langle\operatorname { e x p } \left[\sum_{(a, b)} \sum_{\left(\mathbf{k}_{1}, \mathbf{m}_{1}\right)} \hat{q}_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a, b}\left(N q_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a, b}-\mathbf{w}_{\mathbf{k}_{1}}^{a \top} \mathbf{w}_{\mathbf{m}_{1}}^{b}\right)+\right.\right. \\
& +\sum_{a} \sum_{\left(\mathbf{k}_{1}, \mathbf{m}_{1}\right)} \hat{t}_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a}\left(N t_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a}-\mathbf{w}_{\mathbf{k}_{1}}^{a \top} \mathbf{w}_{\mathbf{m}_{1}}^{a}\right)+ \\
& \left.\left.+\sum_{a} \sum_{\mathbf{k}_{1}}\left(\sum_{\mathbf{m}_{1}} \hat{r}_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a}\left(N r_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a}-\mathbf{w}_{\mathbf{k}_{1}}^{0 \top} \mathbf{w}_{\mathbf{m}_{1}}^{a}\right)+\frac{1}{2} \hat{\kappa}_{\mathbf{k}_{1}}^{a}\left(N-\mathbf{w}_{\mathbf{k}_{1}}^{a \top} \mathbf{w}_{\mathbf{k}_{1}}^{a}\right)\right)\right]\right\rangle_{\mathbb{W}^{n+1}}
\end{aligned}
$$

The solution of the saddle point equation on the variables in $\hat{\mathscr{P}}$ can be expressed in terms of the variables in $\mathscr{P}$ and, by considering the replica symmetric ansatz and the UCM character of the student, we can express these parameters as:

$$
\begin{aligned}
& t_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a} \equiv \delta_{\mathbf{k}_{1} \mathbf{m}_{1}}\left(1-\tilde{t}_{1}\right)+\delta_{\mathbf{k}_{2} \mathbf{m}_{2}}\left(\tilde{t}_{1}-\tilde{t}_{2}\right)+\ldots+\delta_{k_{L} m_{L}}\left(\tilde{t}_{L-1}-\tilde{t}_{L}\right)+\tilde{t}_{L} \\
& q_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a, b} \equiv \delta_{\mathbf{k}_{1} \mathbf{m}_{1}}\left(1-\tilde{q}_{1}\right)+\delta_{\mathbf{k}_{2} \mathbf{m}_{2}}\left(\tilde{q}_{1}-\tilde{q}_{2}\right)+\ldots+\delta_{k_{L} m_{L}}\left(\tilde{q}_{L-1}-\tilde{q}_{L}\right)+\tilde{q}_{L} \\
& r_{\mathbf{k}_{1}, \mathbf{m}_{1}}^{a}=\delta_{\mathbf{k}_{1} \mathbf{m}_{1}}\left(1-\tilde{r}_{1}\right)+\delta_{\mathbf{k}_{2} \mathbf{m}_{2}}\left(\tilde{r}_{1}-\tilde{r}_{2}\right)+\ldots+\delta_{k_{L} m_{L}}\left(\tilde{r}_{L-1}-\tilde{r}_{L}\right)+\tilde{r}_{L},
\end{aligned}
$$

where $\tilde{q}_{j}, \tilde{r}_{j}$ and $\tilde{t}_{j}$ obey the scaling law (2). We find that:

$$
G_{E, N}^{(n)}(\mathscr{P}) \simeq-2 n \int \mathcal{D} z \mathcal{H}\left(\sqrt{\frac{\mathscr{R}_{L}}{1-\mathscr{R}_{L}}} z\right) \ln \mathcal{H}\left(\sqrt{\frac{\mathscr{Q}_{L}}{1-\mathscr{Q}_{L}}} z\right)+O\left(n^{2}, N^{-1}\right)
$$

where:

$$
\begin{aligned}
& \mathscr{Q}_{\ell} \equiv \frac{\gamma_{\ell-1}}{\gamma_{\ell}}\left[\frac{2}{\pi} \arcsin \left(\mathscr{Q}_{\ell-1}\right)+\left(\frac{2}{\pi}\right)^{\ell} \frac{q_{\ell}}{\gamma_{\ell-1}}\right] \\
& \mathscr{R}_{\ell} \equiv \frac{\rho_{\ell-1}}{\rho_{\ell}}\left[\frac{2}{\pi} \arcsin \left(\sqrt{\frac{\gamma_{\ell-2}}{\gamma_{\ell-1}} \frac{\rho_{\ell-1}}{\rho_{\ell-2}}} \mathscr{R}_{\ell-1}\right)+\left(\frac{2}{\pi}\right)^{\ell} \frac{r_{\ell}}{\sqrt{\gamma_{\ell-1} \rho_{\ell-1}}}\right],
\end{aligned}
$$

with $\mathscr{Q}_{0} \equiv q_{0}, \mathscr{R}_{0} \equiv r_{0}, \gamma_{\ell} \equiv 1+\sum_{j=1}^{\ell}\left(\frac{2}{\pi}\right)^{j} t_{j}$ and $\rho_{\ell} \equiv 1+\sum_{j=1}^{\ell}\left(\frac{2}{\pi}\right)^{j} \zeta_{j}$, for all $\ell=0, \ldots, L$. We have also use the definitions $\mathcal{D} z \equiv \mathrm{~d} z \mathrm{e}^{-z^{2} / 2} / \sqrt{2 \pi}$ and $\mathcal{H}(z) \equiv \int_{z}^{\infty} \mathcal{D} x$.

Assuming that the number of units per layer in the committees respect the relations $K_{1} \ldots K_{\ell-1} K_{\ell}^{2}>$ $K$ for all $\ell=1, \ldots, L$, which simply indicates that the closer to the input the more densely populated the layer, the dominant contribution to the configurational term can be expressed as:

$$
G_{S, N}^{(n)}(\mathscr{P}) \simeq n K\left[g_{0}(\mathscr{P})+\frac{1}{K_{1}} g_{1}(\mathscr{P})+\frac{1}{K_{1} K_{2}} g_{2}(\mathscr{P})+\ldots+\frac{1}{K} g_{L}(\mathscr{P})\right]
$$

where

$$
\begin{aligned}
& g_{0}(\mathscr{P}) \equiv \ln \left(1-q_{0}\right)+\frac{q_{0}-r_{0}^{2}}{1-q_{0}} \\
& g_{\ell}(\mathscr{P}) \equiv \ln \left(\frac{1-q_{0}+\sum_{j=1}^{\ell}\left(t_{j}-q_{j}\right)}{1-q_{0}+\sum_{j=1}^{\ell-1}\left(t_{j}-q_{j}\right)}\right)+\frac{\sum_{j=0}^{\ell} q_{j}-\frac{\left(\sum_{j=0}^{\ell} r_{j}\right)^{2}}{1+\sum_{j=1}^{\ell} \zeta_{j}}}{1-q_{0}+\sum_{j=1}^{\ell}\left(t_{j}-q_{j}\right)}-\frac{\sum_{j=0}^{\ell-1} q_{j}-\frac{\left(\sum_{j=0}^{\ell-1} r_{j}\right)^{2}}{1+\sum_{j=1}^{\ell-1} \zeta_{j}}}{1-\sum_{j=1}^{\ell-1}\left(t_{j}-q_{j}\right)}+ \\
& +\left[\frac{\sum_{j=0}^{\ell-1} q_{j}-\frac{\left(\sum_{j=0}^{\ell-1} r_{j}\right)^{2}}{1+\sum_{j=1}^{\ell-1} \zeta_{j}}}{1-q_{0}+\sum_{j=1}^{\ell-1}\left(t_{j}-q_{j}\right)}-1\right] \frac{q_{\ell}+\frac{\zeta_{\ell}}{1+\sum_{j=1}^{\ell-1} \zeta_{j}} \frac{\left(\sum_{j=0}^{\ell-1} r_{j}\right)^{2}}{1+\sum_{j=1}^{\ell-1} \zeta_{j}}-2 r_{\ell} \frac{\sum_{j=0}^{\ell-1} r_{j}}{1+\sum_{j=1}^{\ell-1} \zeta_{j}}}{1-q_{0}+\sum_{j=1}^{\ell-1}\left(t_{j}-q_{j}\right)} .
\end{aligned}
$$

According to (4) and assuming that we can interchange the limits in $N$ and $n$, we have that:

$$
\begin{align*}
f(\alpha, \mathscr{P})= & -2 \frac{\alpha}{K} \int \mathcal{D} z \mathcal{H}\left(\sqrt{\frac{\mathscr{R}_{L}}{1-\mathscr{R}_{L}}} z\right) \ln \mathcal{H}\left(\sqrt{\frac{\mathscr{Q}_{L}}{1-\mathscr{Q}_{L}}} z\right)-  \tag{5}\\
& -\frac{1}{2}\left[g_{0}(\mathscr{P})+\frac{1}{K_{1}} g_{1}(\mathscr{P})+\frac{1}{K_{1} K_{2}} g_{2}(\mathscr{P})+\ldots+\frac{1}{K} g_{L}(\mathscr{P})\right],
\end{align*}
$$

is the free energy of the system.
The generalization error is defined by

$$
\varepsilon_{G}(\mathscr{P}) \equiv\left\langle\left\langle\Theta\left(-\sigma_{\mathbb{W} 0}(\mathbf{S}) \sigma_{\mathbb{W}}(\mathbf{S})\right)\right\rangle_{\mathbb{W} 0}\right\rangle_{\mathbf{S}}=\frac{1}{\pi} \arccos \left(\sqrt{\frac{\gamma_{L-1}}{\gamma_{L}} \frac{\rho_{L}}{\rho_{L-1}}} \mathscr{R}_{L}\right),
$$

which is computed in a similar way as the average sensitivity [15] and should be evaluated in the parameters obtained from the optimization of (5).

## 3 Results

It is clear from the structure of (5) that there are different regimes corresponding to values of the load parameter $\alpha$ proportional to the number of units in a given layer, i.e. $\alpha \sim O(1), O\left(K_{L}\right), O\left(K_{L} K_{L-1}\right)$, $\ldots, O(K)$ respectively. If $\alpha \sim O(1)$ the optimization of the first $L$ leading terms in the free energy produces $q_{\ell}=r_{\ell}=0$ for $0 \leq \ell<L$ and $t_{\ell}=0$ for $0<\ell<L$. The optimal values of the remaining parameters are obtained by solving the set of equations:

$$
\begin{equation*}
0=\frac{\partial}{\partial \eta}\left[-2 \alpha \int \mathcal{D} z \mathcal{H}\left(\sqrt{\frac{\mathscr{R}_{L}}{1-\mathscr{R}_{L}}} z\right) \ln \mathcal{H}\left(\sqrt{\frac{\mathscr{Q}_{L}}{1-\mathscr{Q}_{L}}} z\right)-\frac{1}{2} g_{L}\left(q_{L}, r_{L}, t_{L}\right)\right] \tag{6}
\end{equation*}
$$

where $\eta=q_{L}, r_{L}$ and $t_{L}$. In the particular case where $\zeta_{\ell}=0$ for all $0<\ell<L$ we can propose $t_{L}=\zeta_{L}$ and $r_{L}=q_{L}$ leaving only one equation (in $q_{L}$ ) to be solved. This particularly symmetric case is characterized by the equation $\mathscr{R}_{L}=\mathscr{Q}_{L}$ and, although descriptively simpler, presents the same qualitative behavior as the case with all non-zero overlaps. By defining the integral

$$
\begin{equation*}
\mathcal{I}(x) \equiv \frac{1}{2 \pi} \frac{1}{\sqrt{1-x^{2}}} \int \mathcal{D} z \mathcal{H}^{-1}\left(\sqrt{\frac{x}{1+x}} z\right) \tag{7}
\end{equation*}
$$

the saddle point equation in $q_{L}$ is:

$$
\begin{equation*}
0=\alpha\left(\frac{2}{\pi}\right)^{L} \frac{\mathcal{I}\left(\mathscr{Q}_{L}\right)}{1+\left(\frac{2}{\pi}\right)^{L} \zeta_{L}}-\frac{1}{2} \frac{q_{L}}{\left(1+\zeta_{L}\right)\left(1+\zeta_{L}-q_{L}\right)} \tag{8}
\end{equation*}
$$

where $\mathscr{Q}_{L}=\left(\frac{2}{\pi}\right)^{L}\left[1+\left(\frac{2}{\pi}\right)^{L} \zeta_{L}\right]^{-1} q_{L}$. For large values of $\alpha$ the generalization error asymptotically approaches the value:

$$
\begin{equation*}
\varepsilon_{G}(\alpha) \simeq \frac{1}{\pi} \arccos \left(\mathscr{Q}_{L}^{(\infty)}\right)+\left[\int \mathcal{D} z \mathcal{H}^{-1}\left(\sqrt{\frac{\mathscr{Q}_{L}^{(\infty)}}{1+\mathscr{Q}_{L}^{(\infty)}}} z\right)\right]^{-1} \frac{1}{\alpha}+O\left(\alpha^{-2}\right) \tag{9}
\end{equation*}
$$

where

$$
\begin{equation*}
\mathscr{Q}_{L}^{(\infty)} \equiv\left(\frac{2}{\pi}\right)^{L} \frac{1+\zeta_{L}}{1+\left(\frac{2}{\pi}\right)^{L} \zeta_{L}} \tag{10}
\end{equation*}
$$

which implies that total generalization can not be achieved for finite values of $\zeta_{L}$.
Let us consider the case where the load parameter is proportional to the number of units in the $\ell$-th hidden layer, i.e. $\alpha=\hat{\alpha} K_{L} K_{L-1} \ldots K_{\ell+1}$ with $0<\ell<L$ and $\hat{\alpha}$ independent on $K_{1}, \ldots, K_{L}$. In this regime we found that the optimization of the first $\ell$ terms of the free energy is achieved by $q_{j}=r_{j}=0$
for all $0 \leq j<\ell$ and $t_{j}=0$ for all $0<j<\ell$. The optimization of the term of $O\left(K_{1}^{-1} \ldots K_{\ell}^{-1}\right)$ is achieved through

$$
\begin{equation*}
0=\frac{\partial}{\partial \eta}\left[-2 \hat{\alpha} \int \mathcal{D} z \mathcal{H}\left(\sqrt{\frac{\mathscr{R}_{L}}{1-\mathscr{R}_{L}}} z\right) \ln \mathcal{H}\left(\sqrt{\frac{\mathscr{Q}_{L}}{1-\mathscr{Q}_{L}}} z\right)-\frac{1}{2} g_{\ell}(\mathscr{P})\right] \tag{11}
\end{equation*}
$$

where $\eta=q_{\ell}, r_{\ell}, t_{\ell}$ and $t_{\ell-1}$, in the cases where $\ell>0$. The optimization of the remaining terms (order $K_{1}^{-1} \ldots K_{\ell+1}^{-1}$ and higher) produces the relationships

$$
0=1+\sum_{j=\ell}^{m}\left(t_{j}-q_{j}\right) \quad \text { and } \quad 0=\left(1+\sum_{j=\ell}^{m} t_{j}\right)\left(1+\sum_{j=1}^{m} \zeta_{j}\right)-\left(\sum_{j=\ell}^{m} r_{j}\right)^{2}
$$

for all $\ell<m \leq L$. This system of equations gets a simpler form for a teacher with overlaps $\zeta_{j}=0$ for all $0<j<\ell$. In this case we can chose $t_{j}=\zeta_{j}$ for all $0<j \leq L, r_{j}=q_{j}$ for all $0 \leq j \leq L$ and $q_{j}=\zeta_{j}$ for all $\ell+2 \leq j \leq L$ and the set of equations gets reduced to the relationship $q_{\ell+1}=1+\zeta_{\ell}+\zeta_{\ell+1}-q_{\ell}$ and the equation:

$$
\begin{equation*}
0=\hat{\alpha}\left(\frac{2}{\pi}\right)^{L} \prod_{j=\ell+1}^{L-1} \frac{1}{\sqrt{1-\mathscr{Q}_{j}^{2}}}\left[\frac{1}{\sqrt{1-\mathscr{Q}_{\ell}^{2}}}-1\right] \frac{\mathcal{I}\left(\mathscr{Q}_{L}\right)}{1+\sum_{j=\ell}^{L}\left(\frac{2}{\pi}\right)^{j} \zeta_{j}}-\frac{1}{2} \frac{q_{\ell}}{\left(1+\zeta_{\ell}\right)\left(1+\zeta_{\ell}-q_{\ell}\right)} \tag{12}
\end{equation*}
$$

The learning processes induced by these teachers are characterized by the equation $\mathscr{Q}_{L}=\mathscr{R}_{L}$. Although apparently simpler, these processes present a behavior qualitative similar to the processes induced by teachers with a full set of non-zero overlaps.

Observe that (12) always admits the solution $q_{\ell}=0$, which is the global minimum of the free energy for small values of $\hat{\alpha}$. In this phase there is no specialization of the units and all the overlaps associated to the $\ell$-th layer are zero. For values of the load parameter $\hat{\alpha}>\hat{\alpha}_{s}$ the free energy develops a second minimum at $q_{\ell}^{\star}>0$. This minimum becomes global for $\hat{\alpha}>\hat{\alpha}_{c}>\hat{\alpha}_{s}$. For large values of $\hat{\alpha}$ the asymptotic expression for the generalization error matches (9) with:

$$
\begin{align*}
\mathscr{Q}_{\ell}^{(\infty)} & \equiv\left(\frac{2}{\pi}\right)^{\ell} \frac{1+\zeta_{\ell}}{1+\left(\frac{2}{\pi}\right)^{\ell} \zeta_{\ell}}  \tag{13}\\
\mathscr{Q}_{m}^{(\infty)} & \equiv \frac{1+\sum_{j=\ell}^{m-1}\left(\frac{2}{\pi}\right)^{j} \zeta_{j}}{1+\sum_{j=\ell}^{m}\left(\frac{2}{\pi}\right)^{j} \zeta_{j}}\left[\frac{2}{\pi} \arcsin \left(\mathscr{Q}_{m-1}^{(\infty)}\right)+\left(\frac{2}{\pi}\right)^{m} \frac{\zeta_{m}}{1+\sum_{j=\ell}^{m-1}\left(\frac{2}{\pi}\right)^{j} \zeta_{j}}\right] \tag{14}
\end{align*}
$$

where $\ell<m \leq L$. In this way the generalization error asymptotically converges to a non-zero value if and only if $\ell>0$ and $\zeta_{j}<\infty$ for all $j=1, \ldots, L$.

To illustrate our results let us consider a network with one hidden layer ( $L=1$ ). If $\alpha \sim O(1)$ we have that the learning process presents only a perceptron-like phase where its asymptotic generalization error is given by (9) and (10) and no transition is observed. If $\zeta_{1}$ is zero we recover the result obtained in [22]. Large values of the overlap $\zeta_{1}$ indicate that the hidden units of the teacher work almost like $K$ identical perceptrons. Only in this case $\mathscr{Q}_{1}^{(\infty)}$ becomes close to one and the generalization error approaches zero asymptotically.

When $\alpha=\hat{\alpha} K$ the free energy has the form:

$$
f(q ; \hat{\alpha})=-2 \hat{\alpha} \int \mathcal{D} z \mathcal{H}\left(\sqrt{\frac{\mathscr{Q}_{1}}{1-\mathscr{Q}_{1}}} z\right) \ln \mathcal{H}\left(\sqrt{\frac{\mathscr{Q}_{1}}{1-\mathscr{Q}_{1}} z}\right)-\frac{1}{2}[\ln (1-q)+q]
$$

where $\mathscr{Q}_{1}=\frac{2}{\pi}\left(1+\frac{2}{\pi} \zeta_{1}\right)^{-1}\left[\arcsin (q)+1+\zeta_{1}-q\right]$, that is precisely the expression found in [22] when $\zeta_{1}=0$. The free energy has a minimum at $q=0$ for all values of $\hat{\alpha}$ and develops a second minimum $0<q^{\star}<1$ at $\hat{\alpha}>\hat{\alpha}_{s}$. This minimum becomes global at $\hat{\alpha}>\hat{\alpha}_{c}>\hat{\alpha}_{s} . \hat{\alpha}_{c}$ can be obtained by solving the equations (12) simultaneously with $f_{0}\left(0, \hat{\alpha}_{c}\right)=f_{0}\left(q_{c} ; \hat{\alpha}_{c}\right)$ where $q_{c}=q^{\star}\left(\hat{\alpha}_{c}\right)$. In the region where the minimum $q=0$ is the dominant (small $\hat{\alpha}$ ), the generalization error is a constant. For $\hat{\alpha}>\hat{\alpha}_{c}$ the generalization error decays asymptotically to zero. The larger the parameter $\zeta_{1}$ the larger $\hat{\alpha}_{c}$ and the


Fig. 2 Critical parameters $\hat{\alpha}_{s}, \hat{\alpha}_{c}$ and $\varepsilon_{c}$ as functions of the overlap $\zeta_{1}$. In the left panel we observe the load parameters as a function of the teacher's overlap. The asymptotic behavior of both quantities is proportional to $\sqrt{\zeta_{1}}$. In the left panel we observe the asymptotic decay to zero of the generalization error at the transition $\hat{\alpha}_{c}$.
lower the generalization error at the critical point $\varepsilon_{c} \equiv \varepsilon_{G}\left(\hat{\alpha}_{c}\right)$. Thus, for large values of the overlap $\zeta_{1}$ we recover the perceptron like behavior where full generalization is achieved at very low values of $\hat{\alpha}$. For large values of the overlap $\zeta_{1}$ we have that the critical parameter obeys the following equation:

$$
\begin{equation*}
0=2 \lambda_{c} \sqrt{\frac{1+q_{c}}{1-q_{c}}} \frac{1+\sqrt{1-q_{c}^{2}}}{q_{c}}\left(\lambda_{c}-\sqrt{\frac{\pi}{2}-1}\right)-\ln \left(1-q_{c}\right)-q_{c}, \tag{15}
\end{equation*}
$$

where $\lambda_{c} \equiv \frac{\pi}{2}-1+q_{c}-\arcsin \left(q_{c}\right)$. The numerical solution of (15) is $q_{c} \simeq 0.931$ which implies that $\hat{\alpha}_{c} \simeq 5.94 \sqrt{\zeta_{1}}$ and the value of the generalization error at the criticality is $\varepsilon_{c} \simeq 0.248 / \sqrt{\zeta_{1}}$. Graphs of the critical parameters $\hat{\alpha}_{s}, \hat{\alpha}_{c}$ and $\varepsilon_{c}$ as functions of $\zeta_{1}$, are presented in figure 2 . The regression of these curves $\hat{\alpha}_{c}$ vs. $\zeta_{1}$ and $\varepsilon_{c}$ vs. $\zeta_{1}$ confirm within a $1 \%$ the results presented above.

Thus, for $L=1$ we have that the larger the overlap $\zeta_{1}$ the larger the volume of information must be presented to the network to enter the learning (decreasing generalization error) phase. Although the generalization error in the data acquisition phase $(q=0)$ gets smaller, this tradeoff relationship suggests that, if the overlap is large enough, maybe a perceptron that saturates to a non-zero generalization error and a $O(N)$ training set is more economical than a $L=1$ UCM with a large overlap and a $O(K N)$ training set.

For $L>1$ we have a new and interesting result regarding multilayer feed-forward networks. By proceeding in similar way as in the example before we can study the behavior of the critical parameters as functions of the teacher overlaps $\zeta_{1}, \ldots, \zeta_{L}$. As we do so, we can find different values of the teacher's overlaps that induce equivalent learning processes, i.e. produce the same critical parameters. This result, for $L=2$ is presented in figure 3 .

To illustrate the behavior of the student network with respect to the large overlap limit, we consider the case of a UCM learning from a teacher with $L=2$. We assume the symmetric regime, thus if $\alpha \sim O(1)$ we suppose that $\zeta_{1}=0$. The saddle point equation (8) can be written as:

$$
\begin{equation*}
0=\alpha \mathscr{Q}_{2}^{(\infty)} \mathcal{I}\left(\mathscr{Q}_{2}\right)-\frac{1}{2} \frac{\mathscr{Q}_{2}}{\mathscr{Q}_{2}^{(\infty)}-\mathscr{Q}_{2}} \tag{16}
\end{equation*}
$$

where $\mathscr{Q}_{2}^{(\infty)}$ is as presented in (13). Equation (16) is precisely the saddle point equation of the perceptron when $\mathscr{Q}_{2}^{(\infty)} \uparrow 1$, which is the limit value reached when $\zeta_{2} \uparrow \infty$. Observe that total generalization is achievable at this limit for large values of $\alpha$. In a very similar way, when $\alpha=\hat{\alpha} K_{2}$, we can write the saddle point equation as

$$
\begin{equation*}
0=\hat{\alpha} \frac{2}{\pi}\left[\frac{1}{\sqrt{1-\mathscr{Q}_{1}^{2}}}-1\right] \mathscr{Q}_{1}^{(\infty)} \mathcal{I}\left(\mathscr{Q}_{2}^{(\mathrm{eff})}\right)-\frac{1}{2} \frac{\mathscr{Q}_{1}}{\mathscr{Q}_{1}^{(\infty)}-\mathscr{Q}_{1}}+O(\varphi) \tag{17}
\end{equation*}
$$



Fig. 3 Critical value of $\hat{\alpha}_{c}$ against $\zeta_{1}$ and $\zeta_{2}$. The lines are drawn at constant $\hat{\alpha}$ and thus represent sets of points whose coordinates describe different teachers with identical $\hat{\alpha}_{c}$.
where $\varphi \equiv\left(\frac{2}{\pi}\right)^{2}\left(1+\frac{2}{\pi} \zeta_{1}\right)^{-1} \zeta_{2}$ and $\mathscr{Q}_{2}^{(\text {eff })} \equiv \frac{2}{\pi}\left[\arcsin \left(\mathscr{Q}_{1}\right)+\mathscr{Q}_{1}^{(\infty)}-\mathscr{Q}_{1}\right]$. Equation (17) is equivalent to the saddle point equation of a system with $L=1$ in the limit $\mathscr{Q}_{1}^{(\infty)} \uparrow 1$ and $\varphi \downarrow 0$. Such a behavior is achieved for large values of the overlap $\zeta_{1}$. Again, for the large overlap limit and for large values of $\hat{\alpha}$, total generalization is asymptotically obtained.

## 4 Conclusions

UCMs are feed-forward, binary neural networks that can be considered as the perceptron's next level of architectural complexity. They have only recently been study for the first time and, although they theoretically present more capabilities than the perceptron, they have not been used in real world applications yet.

Probably the most appealing feature UCMs have is the direct relationship between network complexity (as a function of the UCM's overlaps) and task difficulty. If a task difficulty can be assessed by measuring its sensitivity (as presented in [15] and [17]), then a suitable UCM may be constructed to cope with it. It is natural to continue this research by exploring the learning process in UCMs.

In this article we presented a study of the learning-by-examples process in UCMs. Our results were obtained by the application of statistical mechanics techniques, more precisely, by the application of the replica trick, with the imposition of replica symmetric ansatz. Our analysis is based on the study of regimes characterized by the number of examples presented to the student. The regimes of interest are those where the load parameter $\alpha$ is proportional to the number of units in the $\ell$-th hidden layer of the teacher. To simplify this analysis we considered teachers with the first $\ell-1$ overlaps equal to zero. Although apparently less complex, such systems present a qualitatively identical critical behavior to systems with a full set of non-vanishing teacher overlaps.

Our first result, equation (8), is the saddle point equation correspondent to the regime where $\alpha$ is of order 1 . This equation admits only one solution, which is the only minimum of the free energy, for all values of $\alpha$. Thus, this regime is characterized by a lack of transitions and a decay of the generalization error to a non-vanishing value.

The first regime that admits a phase transition occurs when the load parameter is proportional to the number of hidden units in the more external (closest to the output) hidden layer. This first order transition is from a symmetric phase with zero inter-replica overlap and constant value of the generalization error (data acquisition phase), to a specialized phase, with a non-zero inter-replica overlap and decaying (and non-negligible) generalization error (generalization phase). This behavior is repeated for regimes where $\alpha$ is proportional to the number of units in a given hidden layer, but the first. If $\alpha \sim O(K)$ then after the transition the generalization error asymptotically vanishes when $\hat{\alpha} \uparrow \infty$. In all the cases where the transition is observed, the drop in the generalization error is discontinuous. We also observed that teachers with large overlaps effectively appear to their students as less architecturally complex UCMs. This result appeals to the consideration of the tradeoff between architectural
complexity and network performance. It is probably due to this tradeoff that more economical (and simpler) networks could effectively perform equally good as a more complex (and training demanding) network.

Finally, we found that if $L>1$ we can find many teachers with different synaptic overlaps and identical critical parameters. This indicates that, although representing different Boolean functions and implementing different classification tasks, these teachers induce the same learning process in student networks. This motivates a classification of teachers in equivalence classes that may simplify the study of Boolean functions so implemented.

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