



## Positive solutions of second-order three-point boundary value problems with sign-changing coefficients

Ye Xue and Guowei Zhang 

Department of Mathematics, Northeastern University, Shenyang 110819, China

Received 17 July 2016, appeared 22 October 2016

Communicated by Jeff R. L. Webb

**Abstract.** In this article, we investigate the boundary-value problem

$$\begin{cases} x''(t) + h(t)f(x(t)) = 0, & t \in [0, 1], \\ x(0) = \beta x'(0), & x(1) = x(\eta), \end{cases}$$

where  $\beta \geq 0$ ,  $\eta \in (0, 1)$ ,  $f \in C([0, \infty), [0, \infty))$  is nondecreasing, and importantly  $h$  changes sign on  $[0, 1]$ . By the Guo–Krasnosel'skiĭ fixed-point theorem in a cone, the existence of positive solutions is obtained via a special cone in terms of superlinear or sublinear behavior of  $f$ .

**Keywords:** positive solution, fixed point theorem, cone, sign-changing coefficient.

**2010 Mathematics Subject Classification:** 34B18, 34B10, 34B15.

### 1 Introduction


For the first time Liu [7] considered the existence of positive solutions to the following second-order three-point boundary value problems

$$\begin{cases} x''(t) + \lambda h(t)f(x(t)) = 0, & t \in [0, 1], \\ x(0) = 0, & x(1) = \delta x(\eta), \end{cases} \quad (1.1)$$

where  $\lambda$  is a positive parameter,  $\eta \in (0, 1)$ ,  $f \in C([0, \infty), [0, \infty))$  is nondecreasing,  $\delta \in (0, 1)$  and  $h(t)$  is continuous and especially changes sign on  $[0, 1]$  which is different from the non-negative assumption in most of these studies.

Karaca [4] studied the problems with more general boundary conditions

$$\begin{cases} x''(t) + h(t)f(x(t)) = 0, & t \in [0, 1], \\ \alpha x(0) = \beta x'(0), & x(1) = \delta x(\eta), \end{cases} \quad (1.2)$$

 Corresponding author. Email: gwzhang@mail.neu.edu.cn, gwzhangneum@sina.com

where  $\alpha \geq 0$ ,  $\beta \geq 0$ ,  $\alpha + \beta > 0$  with  $0 < \delta < 1$ ,  $f, h$  as in (1.1).

The authors of [4,7] showed the existence of at least one positive solution by applying the fixed-point theorem in a cone. Similar methods for a different problem are in [9]. Let  $E$  be a Banach space, the nonempty subset  $P$  is called a cone in  $E$  if it is a closed convex set and satisfies the properties that  $\lambda x \in P$  for any  $\lambda > 0$ ,  $x \in P$  and that  $\pm x \in P$  implies  $x = 0$  (the zero element in  $E$ ) (see [3]).

In [4] the author denoted

$$C_0^+[0,1] = \left\{ x \in C[0,1] : \min_{t \in [0,1]} x(t) \geq 0, \text{ and } \alpha x(0) = \beta x'(\eta), x(1) = \delta x(\eta) \right\}$$

and defined

$$\mathcal{P} = \{x \in C_0^+[0,1] : x(t) \text{ is concave on } [0,\eta] \text{ and convex on } [\eta,1]\}.$$

In fact,  $\mathcal{P}$  is not a cone since it is not a closed set in  $C[0,1]$ . For example, for  $n > 3$  let

$$x_n(t) = \begin{cases} t+1, & 0 \leq t \leq \frac{1}{n}, \\ \frac{1}{n}+1, & \frac{1}{n} < t \leq \frac{1}{3}, \\ 6\left(\frac{1}{2} + \frac{1}{n}\right)\left(\frac{1}{2} - t\right) + \frac{1}{2}, & \frac{1}{3} < t \leq \frac{1}{2}, \\ \frac{3}{4} - \frac{t}{2}, & \frac{1}{2} < t \leq 1, \end{cases}$$

$$x_0(t) = \begin{cases} 1, & 0 \leq t \leq \frac{1}{3}, \\ 3\left(\frac{1}{2} - t\right) + \frac{1}{2}, & \frac{1}{3} < t \leq \frac{1}{2}, \\ \frac{3}{4} - \frac{t}{2}, & \frac{1}{2} < t \leq 1. \end{cases}$$

Obviously,  $x_n \in \mathcal{P}$  for  $\alpha = \beta = 1$ ,  $\delta = 1/2$  and  $x_n \rightarrow x_0$  in  $C[0,1]$  since  $\{x_n(t)\}$  uniformly converges to  $x_0(t)$  on  $[0,1]$ . But  $x_0 \notin \mathcal{P}$  because  $x_0(0) = 1 \neq 0 = x_0'(0)$ . However the conclusions in [4] are actually true only if  $\alpha x(0) = \beta x'(\eta)$  is removed in  $C_0^+[0,1]$  which is not needed in the proof of [4, Lemma 2.2] by using of the concavity.

A question is whether one can have boundary condition  $x(1) = \delta x(\eta)$  with  $\delta < (\beta + 1)/(\beta + \eta)$  in problem (1.2) with  $\alpha = 1$ , which is the necessary condition when  $f \geq 0$ . We only consider one (less complicated) special case  $\delta = 1$ . If  $\alpha = 0$ , the corresponding linear problem for  $g \in C[0,1]$  will be

$$\begin{cases} x''(t) + g(t) = 0, & t \in [0,1], \\ x'(0) = 0, & x(1) = x(\eta), \end{cases} \quad (1.3)$$

which is a resonance problem. So it is acceptable that  $\alpha > 0$  and may be supposed to be  $\alpha = 1$ . For that reason, we investigate the existence of positive solutions to the three-point boundary-value problem

$$\begin{cases} x''(t) + h(t)f(x(t)) = 0, & t \in [0,1], \\ x(0) = \beta x'(\eta), & x(1) = x(\eta), \end{cases} \quad (1.4)$$

where  $\beta \geq 0$ ,  $\eta \in (0,1)$ ,  $f \in C([0,\infty), [0,\infty))$ ,  $h(t)$  is continuous and is sign changing on  $[0,1]$ . The existence of positive solutions is obtained via a special cone (see (2.5)) in terms of superlinear or sublinear behavior of  $f$  by the Guo–Krasnosel'skiĭ fixed-point theorem in a cone. The ideas here are similar to the papers [4,7] and [9], but note that the signs on  $h$  are opposite to those in [4,7]. Other relevant research can be seen in [1,2,5,8,10].

## 2 Preliminaries

We will use the following assumptions.

(H<sub>1</sub>)  $h : [0, 1] \rightarrow \mathbb{R}$  is continuous and such that  $h(t) \leq 0$ ,  $t \in [0, \eta]$ ;  $h(t) \geq 0$ ,  $t \in [\eta, 1]$ .  
Moreover,  $h(t)$  does not vanish identically on any subinterval of  $[0, 1]$ .

(H<sub>2</sub>)  $f \in C([0, \infty), [0, \infty))$  is continuous and nondecreasing.

(H<sub>3</sub>) There exists a constant  $\tau \in (\frac{1+\eta}{2}, 1)$  such that  $A\rho h(\tau - \rho t) + h(t) \geq 0$  for  $t \in [0, \eta]$  and  $\rho = \frac{\tau - \eta}{\eta}$ , where

$$A = \begin{cases} \frac{\beta(1-\tau)(1-\eta)}{2+\beta-\eta}, & \beta \neq 0, \\ \frac{(1-\tau)\eta^2}{1+\eta}, & \beta = 0. \end{cases} \quad (2.1)$$

**Remark 2.1.** The following example indicates that (H<sub>3</sub>) is reasonable. If we take  $\eta = 1/5$ ,  $\tau = 4/5 \in (3/5, 1)$ ,  $\rho = 3$  and

$$h(t) = \begin{cases} t - 1/5, & t \in [0, 1/5], \\ (125/2)(t - 1/5), & t \in (1/5, 1], \end{cases}$$

then

$$A = \begin{cases} 2/125, & \beta = 1/5, \\ 1/150, & \beta = 0. \end{cases}$$

It is easy to see for  $t \in [0, 1/5]$  that  $A\rho h(\tau - \rho t) + h(t) = 8(1/5 - t) \geq 0$  when  $\beta = 1/5$  and  $A\rho h(\tau - \rho t) + h(t) = (11/4)(1/5 - t) \geq 0$  when  $\beta = 0$ .

**Lemma 2.2.** For  $g \in C[0, 1]$ ,

$$\begin{cases} x''(t) + g(t) = 0, & t \in [0, 1], \\ x(0) = \beta x'(0), & x(1) = x(\eta) \end{cases} \quad (2.2)$$

has the unique solution

$$x(t) = \int_0^1 G_1(t, s)g(s)ds + \frac{\beta}{1-\eta} \int_0^1 G_2(\eta, s)g(s)ds + \frac{t}{1-\eta} \int_0^1 G_1(\eta, s)g(s)ds,$$

where

$$G_1(t, s) = \begin{cases} (1-t)s, & 0 \leq s \leq t \leq 1, \\ (1-s)t, & 0 \leq t < s \leq 1, \end{cases} \quad G_2(\eta, s) = \begin{cases} 1-\eta, & 0 \leq s \leq \eta, \\ 1-s, & \eta < s \leq 1. \end{cases}$$

*Proof.* By Taylor expansion we have

$$x(t) = a_0 + a_1 t + \int_0^t (t-s)x''(s)ds = a_0 + a_1 t - \int_0^t (t-s)g(s)ds \quad (2.3)$$

and

$$\begin{aligned} x(0) &= a_0, \quad x(1) = a_0 + a_1 - \int_0^1 (1-s)g(s)ds, \\ x(\eta) &= a_0 + a_1 \eta - \int_0^\eta (\eta-s)g(s)ds, \quad x'(0) = a_1. \end{aligned}$$

The boundary conditions imply that  $a_0 = \beta a_1$  and

$$a_0 + a_1 - \int_0^1 (1-s)g(s)ds = a_0 + a_1\eta - \int_0^\eta (\eta-s)g(s)ds,$$

thus

$$\begin{aligned} a_1 &= \frac{1}{1-\eta} \int_0^1 (1-s)g(s)ds - \frac{1}{1-\eta} \int_0^\eta (\eta-s)g(s)ds, \\ a_0 &= \frac{\beta}{1-\eta} \int_0^1 (1-s)g(s)ds - \frac{\beta}{1-\eta} \int_0^\eta (\eta-s)g(s)ds. \end{aligned}$$

It follows from (2.3) that

$$\begin{aligned} x(t) &= \frac{\beta+t}{1-\eta} \int_0^1 (1-s)g(s)ds - \frac{\beta+t}{1-\eta} \int_0^\eta (\eta-s)g(s)ds - \int_0^t (t-s)g(s)ds \\ &= \left( t + \frac{\beta+\eta t}{1-\eta} \right) \int_0^1 (1-s)g(s)ds + (\beta+st) \int_0^\eta g(s)ds - \frac{\beta+\eta t}{1-\eta} \int_0^\eta (1-s)g(s)ds \\ &\quad + \int_0^t (1-t)sg(s)ds - \int_0^t (1-s)tg(s)ds \\ &= \int_t^1 (1-s)tg(s)ds + \int_\eta^1 \frac{\beta+\eta t}{1-\eta} (1-s)g(s)ds \\ &\quad + \int_0^\eta (\beta+st)g(s)ds + \int_0^t (1-t)sg(s)ds \\ &= \int_0^1 G_1(t,s)g(s)ds + \frac{\beta}{1-\eta} \left( \int_0^\eta (1-\eta)g(s)ds + \int_\eta^1 (1-s)g(s)ds \right) \\ &\quad + \frac{t}{1-\eta} \left( \int_0^\eta (1-\eta)sg(s)ds + \int_\eta^1 (1-s)\eta g(s)ds \right) \\ &= \int_0^1 G_1(t,s)g(s)ds + \frac{\beta}{1-\eta} \int_0^1 G_2(\eta,s)g(s)ds + \frac{t}{1-\eta} \int_0^1 G_1(\eta,s)g(s)ds, \end{aligned}$$

and hence the proof is complete. □

For  $t, s \in [0, 1]$  let

$$G(t, s) = G_1(t, s) + \frac{\beta}{1-\eta} G_2(\eta, s) + \frac{t}{1-\eta} G_1(\eta, s). \quad (2.4)$$

**Lemma 2.3.** *If  $s_1 \in [0, \eta]$  and  $s_2 \in [\eta, \tau]$ , then*

$$G_1(\eta, s_2) \geq AG_1(\eta, s_1), \quad G(t, s_2) \geq AG(t, s_1), \quad \forall t \in [0, 1],$$

where  $\tau$  and  $A$  are as in (H<sub>3</sub>).

*Proof.* In the case whether  $\beta = 0$  or  $\beta \neq 0$ ,

$$\frac{G_1(\eta, s_2)}{G_1(\eta, s_1)} = \frac{(1-s_2)\eta}{(1-\eta)s_1} \geq \frac{(1-\tau)\eta}{(1-\eta)\eta} = \frac{1-\tau}{1-\eta} \geq A.$$

When  $\beta \neq 0$ ,

$$\begin{aligned} \frac{G(t, s_2)}{G(t, s_1)} &= \frac{G_1(t, s_2) + \frac{\beta}{1-\eta} G_2(\eta, s_2) + \frac{t}{1-\eta} G_1(\eta, s_2)}{G_1(t, s_1) + \frac{\beta}{1-\eta} G_2(\eta, s_1) + \frac{t}{1-\eta} G_1(\eta, s_1)} \\ &\geq \frac{\frac{\beta}{1-\eta} G_2(\eta, s_2)}{G_1(t, s_1) + \frac{\beta}{1-\eta} G_2(\eta, s_1) + \frac{t}{1-\eta} G_1(\eta, s_1)} \\ &\geq \frac{\frac{\beta}{1-\eta} (1-s_2)(1-\eta)}{(1-s_1) + \frac{\beta}{1-\eta} (1-s_1) + \frac{1}{1-\eta} (1-s_1)} \\ &= \frac{\beta(1-s_2)}{(1 + \frac{\beta+1}{1-\eta})(1-s_1)} \geq \frac{\beta(1-\tau)}{1 + \frac{\beta+1}{1-\eta}} = \frac{\beta(1-\tau)(1-\eta)}{2 + \beta - \eta}, \end{aligned}$$

when  $\beta = 0$ ,

$$\begin{aligned} \frac{G(t, s_2)}{G(t, s_1)} &= \frac{G_1(t, s_2) + \frac{t}{1-\eta} G_1(\eta, s_2)}{G_1(t, s_1) + \frac{t}{1-\eta} G_1(\eta, s_1)} \geq \frac{\frac{t}{1-\eta} G_1(\eta, s_2)}{G_1(t, s_1) + \frac{t}{1-\eta} G_1(\eta, s_1)} \\ &\geq \frac{\frac{t}{1-\eta} G_1(\eta, s_2)}{(1-s_1)t + \frac{t}{1-\eta} G_1(\eta, s_1)} = \frac{\frac{1}{1-\eta} G_1(\eta, s_2)}{(1-s_1) + \frac{1}{1-\eta} G_1(\eta, s_1)} \\ &\geq \frac{\frac{1}{1-\eta} s_2 \eta (1-\eta)(1-s_2)}{1 + \frac{1}{1-\eta} s_1 (1-\eta)} \geq \frac{(1-\tau)\eta^2}{1+\eta}. \end{aligned}$$

Thus the proof is finished. □

In  $C[0, 1]$  with the norm  $\|x\| = \max_{t \in [0,1]} |x(t)|$  for  $x \in C[0, 1]$ , denote

$$X = \left\{ x \in C[0, 1] : \min_{t \in [0,1]} x(t) \geq 0, \text{ and } x(0) \leq x(\eta), x(1) = x(\eta) \right\},$$

$$P = \{x \in X : x(t) \text{ is convex on } [0, \eta] \text{ and is concave on } [\eta, 1]\}. \quad (2.5)$$

Obviously,  $P$  is a cone in  $C[0, 1]$ .

**Lemma 2.4.** *If  $x \in P$ , then  $x(t) \leq x(\eta) = \min_{t \in [\eta, 1]} x(t)$  for  $t \in [0, \eta]$ .*

**Lemma 2.5.** *If  $x \in P$ , then*

$$x(t) \geq \frac{1-\tau}{2(1-\eta)} \|x\| \quad \text{for } t \in \left[ \tau, \frac{1+\tau}{2} \right],$$

where  $\tau$  is as in  $(H_3)$ .

*Proof.* By Lemma 2.4 we have  $\|x\| = \max_{t \in [\eta, 1]} x(t)$  and denote

$$\mu = \sup \{ \xi \in [\eta, 1] : x(\xi) = \|x\| \}.$$

Notice that  $x(t)$  is concave on  $[\eta, 1]$ . For  $t \in [\eta, \mu]$ ,

$$\frac{x(\mu) - x(\eta)}{\mu - \eta} \geq \frac{x(\mu) - x(t)}{\mu - t}$$

and

$$x(t) \geq \frac{(t-\eta)x(\mu) + (\mu-t)x(\eta)}{\mu-\eta} \geq \frac{t-\eta}{\mu-\eta} \|x\| \geq \frac{t-\eta}{1-\eta} \|x\|;$$

for  $t \in (\mu, 1]$ ,

$$\frac{x(t) - x(\mu)}{t - \mu} \geq \frac{x(1) - x(\mu)}{1 - \mu}$$

and

$$x(t) \geq \frac{(t-\mu)x(1) + (1-t)x(\mu)}{1-\mu} \geq \frac{1-t}{1-\eta} \|x\| = \left(1 - \frac{t-\eta}{1-\eta}\right) \|x\|.$$

Therefore,

$$x(t) \geq \min \left\{ \frac{t-\eta}{1-\eta}, 1 - \frac{t-\eta}{1-\eta} \right\} \|x\|, \quad \forall t \in [\eta, 1]$$

and hence

$$x(t) \geq \min \left\{ \frac{\tau-\eta}{1-\eta}, \frac{1-\tau}{2(1-\eta)} \right\} \|x\| = \frac{1-\tau}{2(1-\eta)} \|x\|, \quad \forall t \in \left[\tau, \frac{1+\tau}{2}\right]$$

since  $\left[\tau, \frac{1+\tau}{2}\right] \subset [\eta, 1]$ . □

**Lemma 2.6.** *Suppose that  $(H_1)$ – $(H_3)$  are satisfied. If  $x \in P$ , then*

$$\int_0^\tau G(t,s)h(s)f(x(s))ds \geq 0 \quad (\forall t \in [0,1]) \quad \text{and} \quad \int_0^\tau G_1(\eta,s)h(s)f(x(s))ds \geq 0,$$

where  $\tau$  is as in  $(H_3)$ .

*Proof.* For  $s \in [\eta, \tau]$  let  $s = \tau - \rho z$ , here  $\rho = (\tau - \eta)/\eta$ , then  $z \in [0, \eta]$ . By Lemma 2.3, Lemma 2.4,  $(H_1)$  and  $(H_3)$ , we have

$$\begin{aligned} \int_\eta^\tau G(t,s)h(s)f(x(s))ds &= \rho \int_0^\eta G(t, \tau - \rho z)h(\tau - \rho z)f(x(\tau - \rho z))dz \\ &\geq A\rho \int_0^\eta G(t,z)h(\tau - \rho z)f(x(\tau - \rho z))dz \\ &\geq A\rho \int_0^\eta G(t,z)h(\tau - \rho z)f(x(z))dz \\ &\geq - \int_0^\eta G(t,z)h(z)f(x(z))dz = - \int_0^\eta G(t,s)h(s)f(x(s))ds \end{aligned}$$

and hence

$$\int_0^\tau G(t,s)h(s)f(x(s))ds \geq 0.$$

By the same way, the other inequality holds. □

### 3 Main results

For  $x \in P$  define the operator  $T$  as the following:

$$(Tx)(t) = \int_0^1 G(t,s)h(s)f(x(s))ds, \quad (3.1)$$

where  $G(t,s)$  is in (2.4).

**Lemma 3.1.** *If  $(H_1)$ – $(H_3)$  are satisfied, then  $T : P \rightarrow P$  is completely continuous, where  $P$  is the cone defined by (2.5) in  $C[0, 1]$ .*

*Proof.* If  $x \in P$ , it is clear that  $(Tx)(t)$  is continuous on  $[0, 1]$  and for  $t \in [0, 1]$ ,

$$(Tx)(t) = \int_0^\tau G(t, s)h(s)f(x(s))ds + \int_\tau^1 G(t, s)h(s)f(x(s))ds \geq 0$$

by Lemma 2.6. Moreover, direct calculations by virtue of (2.4), (3.1) and Lemma 2.6 yield

$$(Tx)(\eta) = \frac{1}{1-\eta} \int_0^1 G_1(\eta, s)h(s)f(x(s))ds + \frac{\beta}{1-\eta} \int_0^1 G_2(\eta, s)g(s)f(x(s))ds = (Tx)(1),$$

$$\begin{aligned} (Tx)(\eta) - (Tx)(0) &= \frac{1}{1-\eta} \int_0^1 G_1(\eta, s)h(s)f(x(s))ds \\ &= \frac{1}{1-\eta} \left( \int_0^\tau G_1(\eta, s)h(s)f(x(s))ds + \int_\tau^1 G_1(\eta, s)g(s)f(x(s))ds \right) \geq 0. \end{aligned}$$

Meanwhile  $(Tx)''(t) = -h(t)f(x(t)) \geq 0$  for  $t \in [0, \eta]$  and  $(Tx)''(t) \leq 0$  for  $t \in [\eta, 1]$ , i.e.,  $(Tx)(t)$  is convex on  $[0, \eta]$  and is concave on  $[\eta, 1]$  respectively. These mean that  $T : P \rightarrow P$ . At last, we know that  $T$  is completely continuous from the Arzelà–Ascoli theorem.  $\square$

It follows from Lemma 2.2 that there exists a positive solution to (1.4) if and only if  $T$  has a fixed point in  $P$ . In order to prove the existence of positive solution we need the following Guo-Krasnosel'skiĭ fixed point theorem in the cone [3, 6].

**Lemma 3.2.** *Let  $E$  be a Banach space and  $P$  be a cone in  $E$ . Suppose that  $\Omega_1$  and  $\Omega_2$  are bounded open sets in  $E$  with  $0 \in \Omega_1$  and  $\overline{\Omega_1} \subset \Omega_2$ . If  $T : P \cap (\overline{\Omega_2} \setminus \Omega_1) \rightarrow P$  is a completely continuous operator and satisfies either*

- (i)  $\|Tx\| \leq \|x\|$  for  $x \in P \cap \partial\Omega_1$  and  $\|Tx\| \geq \|x\|$  for  $x \in P \cap \partial\Omega_2$ ; or
- (ii)  $\|Tx\| \geq \|x\|$  for  $x \in P \cap \partial\Omega_1$  and  $\|Tx\| \leq \|x\|$  for  $x \in P \cap \partial\Omega_2$ ,

then  $T$  has a fixed point in  $P \cap (\overline{\Omega_2} \setminus \Omega_1)$ .

**Theorem 3.3.** *Suppose that  $(H_1)$ – $(H_3)$  are satisfied. If*

$$\lim_{u \rightarrow 0^+} f(u)/u = 0, \tag{3.2}$$

$$\lim_{u \rightarrow \infty} f(u)/u = \infty, \tag{3.3}$$

then (1.4) has at least one positive solution.

*Proof.* Let  $P$  and  $T$  be respectively as (2.5) and (3.1).

By (3.2) there exists  $r_1 > 0$  such that  $f(u) \leq \varepsilon_1 u$  for  $u \in [0, r_1]$ , where  $\varepsilon_1 > 0$  satisfies

$$\varepsilon_1 \max_{t \in [0, 1]} \int_\eta^1 G(t, s)h(s)ds \leq 1. \tag{3.4}$$

Denote  $\Omega_1 = \{x \in C[0,1] : \|x\| < r_1\}$  and hence from (H<sub>1</sub>) and (3.4) we have that  $\forall x \in P \cap \partial\Omega_1$ ,

$$\begin{aligned} (Tx)(t) &= \int_0^\eta G(t,s)h(s)f(x(s)) + \int_\eta^1 G(t,s)h(s)f(x(s))ds \\ &\leq \int_\eta^1 G(t,s)h(s)f(x(s))ds \leq \varepsilon_1 \int_\eta^1 G(t,s)h(s)x(s)ds \\ &\leq \varepsilon_1 \|x\| \int_\eta^1 G(t,s)h(s)ds \leq r_1, \quad t \in [0,1], \end{aligned}$$

that is,  $\|Tx\| \leq \|x\|$ .

By (3.3) there exists  $\tilde{R}_1 > 0$  such that  $f(u) \geq \Lambda_1 u$  for  $u \geq \tilde{R}_1$ , where  $\Lambda_1 > 0$  satisfies

$$\Lambda_1 \frac{1-\tau}{2(1-\eta)} \max_{t \in [0,1]} \int_\tau^{(1+\tau)/2} G(t,s)h(s)ds \geq 1. \quad (3.5)$$

Denote  $\Omega_2 = \{x \in C[0,1] : \|x\| < R_1\}$ , where

$$R_1 = \max \left\{ 2r_1, \tilde{R}_1 \frac{2(1-\eta)}{1-\tau} \right\}, \quad (3.6)$$

and hence by Lemma 2.5 and (3.6) we have that  $\forall x \in P \cap \partial\Omega_2$ ,

$$x(t) \geq \frac{1-\tau}{2(1-\eta)} \|x\| = \frac{1-\tau}{2(1-\eta)} R_1 \geq \tilde{R}_1 \quad \text{for } t \in \left[ \tau, \frac{1+\tau}{2} \right]. \quad (3.7)$$

Consequently, it follows from Lemma 2.6, (3.7) and (3.5) that  $\forall x \in P \cap \partial\Omega_2$ ,

$$\begin{aligned} \|Tx\| &= \max_{t \in [0,1]} \left( \int_0^\tau G(t,s)h(s)f(x(s)) + \int_\tau^1 G(t,s)h(s)f(x(s))ds \right) \\ &\geq \max_{t \in [0,1]} \int_\tau^1 G(t,s)h(s)f(x(s))ds \geq \max_{t \in [0,1]} \int_\tau^{(1+\tau)/2} G(t,s)h(s)f(x(s))ds \\ &\geq \max_{t \in [0,1]} \int_\tau^{(1+\tau)/2} G(t,s)h(s)\Lambda_1 x(s)ds \\ &\geq \Lambda_1 \frac{1-\tau}{2(1-\eta)} \|x\| \max_{t \in [0,1]} \int_\tau^{(1+\tau)/2} G(t,s)h(s)ds \geq \|x\|. \end{aligned}$$

By Lemma 3.1 and Lemma 3.2  $T$  has at least one fixed point in  $P \cap (\bar{\Omega}_2 \setminus \Omega_1)$  which is the positive solution to (1.4).  $\square$

**Theorem 3.4.** *Suppose that (H<sub>1</sub>)–(H<sub>3</sub>) are satisfied. If*

$$\lim_{u \rightarrow 0^+} f(u)/u = \infty, \quad (3.8)$$

$$\lim_{u \rightarrow \infty} f(u)/u = 0, \quad (3.9)$$

then (1.4) has at least one positive solution.

*Proof.* Let  $P$  and  $T$  be respectively as (2.5) and (3.1).

By (3.8) there exists  $r_2 > 0$  such that  $f(u) \geq \Lambda_2 u$  for  $u \in [0, r_2]$ , where  $\Lambda_2 > 0$  satisfies

$$\Lambda_2 \frac{1-\tau}{2(1-\eta)} \max_{t \in [0,1]} \int_\tau^{(1+\tau)/2} G(t,s)h(s)ds \geq 1. \quad (3.10)$$



Denote  $\Omega_1 = \{x \in C[0, 1] : \|x\| < r_2\}$  and hence from Lemma 2.6 and Lemma 2.5 we have that  $\forall x \in P \cap \partial\Omega_1$ ,

$$\begin{aligned} \|Tx\| &= \max_{t \in [0, 1]} \left( \int_0^\tau G(t, s)h(s)f(x(s)) + \int_\tau^1 G(t, s)h(s)f(x(s))ds \right) \\ &\geq \max_{t \in [0, 1]} \int_\tau^1 G(t, s)h(s)f(x(s))ds \geq \max_{t \in [0, 1]} \int_\tau^{(1+\tau)/2} G(t, s)h(s)f(x(s))ds \\ &\geq \max_{t \in [0, 1]} \int_\tau^{(1+\tau)/2} G(t, s)h(s)\Lambda_2 x(s)ds \\ &\geq \Lambda_2 \frac{1-\tau}{2(1-\eta)} \|x\| \max_{t \in [0, 1]} \int_\tau^{(1+\tau)/2} G(t, s)h(s)ds \geq \|x\|. \end{aligned}$$

By (3.9) there exists  $\tilde{R}_2 > 0$  such that  $f(u) \leq \varepsilon_2 u$  for  $u \geq \tilde{R}_2$ , where  $\varepsilon_2 > 0$  satisfies

$$\varepsilon_2 \max_{t \in [0, 1]} \int_\eta^1 G(t, s)h(s)ds \leq 1. \quad (3.11)$$

If  $f$  is bounded, then there exists a constant  $M > 0$  such that  $f(u) \leq M$  for  $u \geq 0$  and denote  $\Omega_2 = \{x \in C[0, 1] : \|x\| < R_2\}$  in this case, where

$$R_2 = \max \left\{ 2r_2, M \max_{t \in [0, 1]} \int_\eta^1 G(t, s)h(s)ds \right\}, \quad (3.12)$$

and hence from (H<sub>1</sub>) and (3.12) we have that  $\forall x \in P \cap \partial\Omega_2$ ,

$$\begin{aligned} (Tx)(t) &= \int_0^\eta G(t, s)h(s)f(x(s)) + \int_\eta^1 G(t, s)h(s)f(x(s))ds \\ &\leq \int_\eta^1 G(t, s)h(s)f(x(s))ds \leq M \max_{t \in [0, 1]} \int_\eta^1 G(t, s)h(s)ds \leq R_2, \quad t \in [0, 1], \end{aligned}$$

that is,  $\|Tx\| \leq \|x\|$ .

For the case when  $f$  is unbounded, take  $R_2 = \max\{2r_2, \tilde{R}_2\}$  and thus  $f(u) \leq f(R_2)$  for  $u \in [0, R_2]$  by the monotonicity of  $f$ . Therefore from (H<sub>1</sub>) and (3.11) we have that  $\forall x \in P \cap \partial\Omega_2$ ,

$$\begin{aligned} (Tx)(t) &= \int_0^\eta G(t, s)h(s)f(x(s)) + \int_\eta^1 G(t, s)h(s)f(x(s))ds \\ &\leq \int_\eta^1 G(t, s)h(s)f(x(s))ds \leq f(R_2) \max_{t \in [0, 1]} \int_\eta^1 G(t, s)h(s)ds \\ &\leq \varepsilon_2 R_2 \max_{t \in [0, 1]} \int_\eta^1 G(t, s)h(s)ds \leq R_2, \quad t \in [0, 1], \end{aligned}$$

which implies  $\|Tx\| \leq \|x\|$  also.

By Lemma 3.1 and Lemma 3.2  $T$  has at least one fixed point in  $P \cap (\overline{\Omega_2} \setminus \Omega_1)$  which is the positive solution to (1.4).  $\square$

## Acknowledgments

The authors express their gratitude to the referees for their valuable comments and suggestions. The authors are supported by National Natural Science Foundation of China (Grant number 61473065).

## References

- [1] C. BAI, D. XIE, Y. LIU, C. L. WANG, Positive solutions for second-order four-point boundary value problems with alternating coefficient, *Nonlinear Anal.* **70**(2009), 2014–2023. [MR2492138](#); [url](#)
- [2] Y. GUO, W. GE, S. DONG, Two positive solutions for second order three point boundary problems with sign changing nonlinearities, *Acta Math. Appl. Sin.* **27**(2004), 522–529. [MR2125526](#)
- [3] D. GUO, V. LAKSHMIKANTHAM, *Nonlinear problems in abstract cones*, Academic Press, Boston, 1988. [MR0959889](#)
- [4] I. Y. KARACA, On the existence of positive solutions for three-point boundary value problems with alternating coefficients, *Math. Comput. Modelling* **47**(2008) 1019–1034. [MR2413732](#); [url](#)
- [5] I. Y. KARACA, Nonlinear triple-point problems with change of sign, *Comput. Math. Appl.* **55**(2008) 691–703. [MR2387616](#); [url](#)
- [6] M. A. KRASNOSEL'SKIĬ, *Positive solutions of operator equations* (English translation), P. Noordhoff Ltd. Groningen, 1964. [MR0181881](#)
- [7] B. LIU, Positive solutions of second-order three-point boundary value problems with change of sign, *Comput. Math. Appl.* **47**(2004) 1351–1361. [MR2070989](#); [url](#)
- [8] B. LIU, Positive solutions of second-order three-point boundary value problems with change of sign in Banach spaces, *Nonlinear Anal.* **64**(2006) 1336–1355. [MR2200496](#); [url](#)
- [9] Y. WU, Z. ZHAO, Positive solutions for third-order boundary value problems with change of signs, *Appl. Math. Comput.* **218**(2011) 2744–2749. [MR2838180](#); [url](#)
- [10] D. XIE, Y. LIU, C. BAI, Triple positive solutions for second-order four-point boundary value problem with sign changing nonlinearities, *Electron. J. Qual. Theory Differ. Equ.* **2009**, No. 35, 1–14. [MR2511288](#); [url](#)