

1-D P- and S-wave velocity models for the collision zone between the northern Tianshan mountain and the Junggar basin based on local earthquake data*

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Abstract We have developed crustal minimum 1-D P- and S-wave velocity models of the collision zone between the northern Tianshan mountain and the Junggar basin (86°E–89°E, 43°N–44.5°N). These two models were created through inversion of 1 370 P- and 1 396 S-wave travel times from 173 well-constrained local earthquakes recorded by the Ürümqi sparse local seismic network and temporary seismic arrays. In contrast to previous models, our results indicate relatively low velocity at both shallow (<10 km) and deep (30–45 km) depths. The shallow zone is interpreted to be the result of thick surficial sedimentary deposits, whereas the deeper anomaly is interpreted to result from ductile shearing and lower crustal flow. Additionally, we detected several transition layers under the lower crust, which may imply structural complexity of the uppermost mantle in this region. The improved models reduce the RMS residual of earthquake locations by 41.7% from 1.2 to 0.5 seconds. The more accurately located hypocenters appear to correlate with prominent local over-thrusts, which underlie an anticlinal fold belt and several blind faults. Positive station corrections are observed near the Junggar basin, which likely reflects low wave velocity; negative corrections near the Tianshan mountain and Bogda mountain suggest high wave velocity.

Key words: orogenic crust; Tianshan mountain-Junggar basin; 1-D seismic structure; earthquake relocation

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1 Introduction

The Tianshan mountain range is one of the most tectonically active intra-continental orogenic belts in the world. The boundary fault zone of the northern Tianshan piedmont delineates the collision zone between the northern part of the range and the

southern edge of the Junggar basin and is characterized by valley and ridge topography (Figure 1). The Global Geosciences Transects (GGTs) indicate that the northern Tianshan mountain and the Junggar basin have similar crustal structure (Liu, 2005). The 1965 *M*6.6 Bogda earthquake and the 1906 *M*7.7 Manas earthquake (solid red stars, Figure 1) are the largest recorded earthquakes in the Tianshan orogenic belt, and occurred within the collision zone. Active deformation has continued through the Holocene in response to the Indian-Eurasian collision, which may have begun 55 million years ago (Tapponnier et al., 2001), and as a result of regional subduction of the Tarim sub-plate and orogeny (Xiao

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et al., 1990). Deformation of the northern piedmont of the Tianshan is manifested by three sub-parallel sets of reverse faults and fold belts that are developed in the Cenozoic strata within the Ürümqi depression (Wang et al., 2004; Qi et al., 2008). This special tectonic structure, consisting of shovel-shaped faults zones and gentle

decollement slopes, is widely distributed in the study area (Deng et al., 1999), and has the potential to accumulate strain energy. A quick release of the accumulated energy then reaches the surface to generate large-scale destruction (e.g., $M_S8.0$ Wenchuan earthquake; Tao et al., 2011).

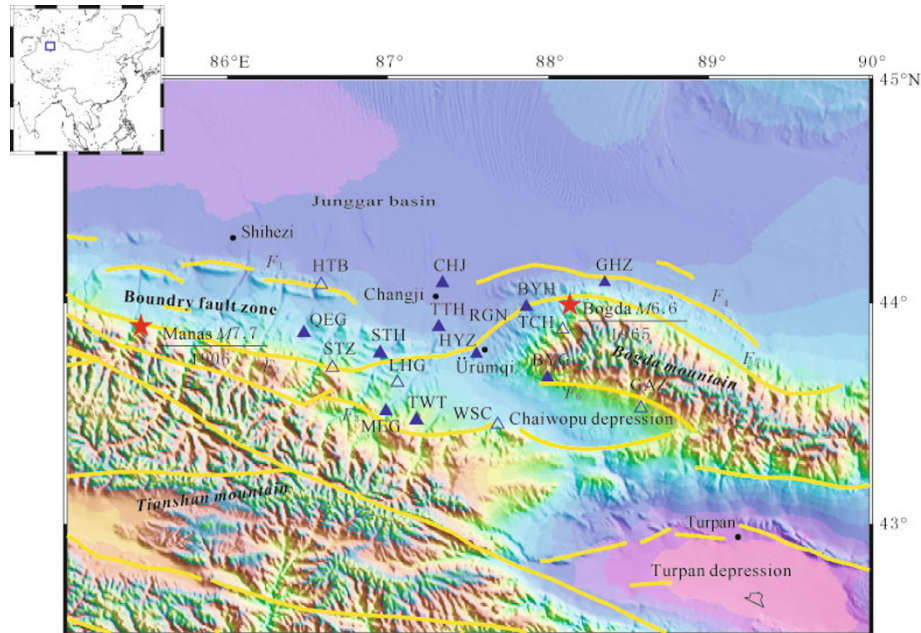


Figure 1 Tectonic map of the study region in Northwest China showing the location of seismic stations. The hollow blue triangles indicate the locations of the stations from the local seismic network and the solid blue triangles from the temporary array. Yellow lines delineate fault surface traces. F_1 . Manas-Tugulu anticline; F_2 . Qigu-Tuositai anticline; F_3 . Tianshan northern piedmont fault; F_4 . Fukan-Santai fault; F_5 . Bogda northern piedmont fault; F_6 . Bogda southern piedmont fault.

Investigations of the seismotectonic structure of the crust require high quality databases including reliable 1-D reference velocity models and accurate earthquake locations. Unfortunately, research of the study area has typically been focused on field-based geologic studies, and 3-D crustal structure tomography (Xu et al., 2000b; Qian et al., 2011) is of fairly low resolution due to technological limitations and limited data. Moreover, the obtained solutions and the reliability estimates depend on the initial 1-D reference model (Kissling et al., 1994). Several previous 1-D models referring to a single 2-D profile of deep seismic sounding (DSS) (Shao et al., 1996; Wang et al., 2004) cannot satisfy the whole target area, nor is the global crustal model CRUST 2.0 (Bassin et al., 2000) suitable for investigations of local seismology in this study, because the dataset is too sparsely sampled.

In this paper, we make use of recently obtained

data from the established local seismic network and temporary seismic arrays to develop an overall average 1-D velocity model for the crust and uppermost mantle of the Tianshan-Junggar collision zone. Inversion of P- and S-wave travel times is performed using the program VELEST (Kissling et al., 1994) to obtain the “minimum 1-D velocity model”. In addition, we relocated earthquake events that occurred from 1988 to August 2005 by using our newly updated 1-D reference model, which greatly reduced the RMS residual of their locations. Because high precision seismicity can be used to detect crustal shear zones (Shearer, 2002) and to identify hidden active faults (Courboux et al., 2003), we used the structures obtained by deep seismic reflection profile experiments (Liu et al., 2007) and our accurate relocation of hypocenters to delineate faults zones. These results illuminate the possible deep crustal geodynamic evolution of this seismotectonic block.

2 Data and methods

We deployed 10 broadband temporary seismic stations in the Tianshan-Junggar collision zone from July 2004 to August 2005, which was supported by the Ürümqi Active Faults Detection Project. The observation system consisted of a Guralp CMG-3ESP seismometer and a REF TEK 130 digitizer with a sampling rate of 50 sps, with a GPS working in continuous mode. The temporary stations, combined with the 17 seismic stations of the Ürümqi network, yielded a higher density seismic network with a station spacing of 20–40 km in the target area (Figure 1). We have hand-picked arrival times from the waveforms recorded by our temporary stations for more than one year. In addition, we have selected events from the Xinjiang monthly catalog and collected a total of 6 665 P- and 6 371 S-wave travel times to jointly invert for hypocenters and a layered crustal model.

For a 1-D model inversion, we measured the total travel time misfit (or residuals) often by using the RMS (root-mean-squared) misfit of the solution, and the target for most inversions is to address a global minimum for this RMS misfit. In the case of the coupled hypocenter-velocity problem, however, the solution depends on the initial model and initial hypocenter parameter, thereby most likely yielding several local minima, but not a global minimum. Calculating the 1-D minimum model avoids this situation through varying initial models and hypocenters performed by the program VELEST. The 1-D minimum models including a 1-D model and the station corrections are the result of a combined, simultaneous inversion of a large number of selected high-quality earthquakes. The attributed “minimum” denotes the fact that this 1-D model and the station corrections lead to a minimum average (RMS) value for all events used in the inversion.

To develop a reasonable reference model with evenly distributed recorded data, we only used data from earthquakes that occurred from July 2004 to August 2005, such that the temporary station data could have equal weight to the seismic network data in the inversion process. Following the VELEST protocol, we prepared three different earthquake event groups. One group contains 501 events from the Xinjiang monthly routine catalog (C65), with more than four-station recordings for each event. The other groups consist of 727 relocated results of adopted earthquakes determined with Hypoinverse (Klein, 2002), and 417

relocated earthquakes determined through application of hypoDD (Waldhauser and Ellsworth, 2000), respectively. To further reduce the systematic errors in the dataset, and to further improve the stability of inversion, we chose events according to the following criteria: from a minimum number of six stations, with $2.3 \leq v_P \leq 8$ km/s, between the estimated minimum value of P-wave velocity near surface and the P-wave velocity near uppermost mantle around the study area from previous research (Xiao et al., 2004), and $GAP \leq 180$. GAP refers to the largest azimuthal gap (degrees) between azimuthally adjacent stations. Then, we selected 321 earthquakes from the Hypoinverse relocated results, and 173 earthquakes from the hypoDD relocated results as two additional event groups for inversion.

We utilized three 1-D prior models with v_P/v_S ratio of 1.73 from previous studies (Shao et al., 1996; Wang et al., 2004; Sun et al., 2011) as our initial 1-D velocity models (dashed lines in Figures 2a–2b), in which we (Sun et al., 2011) revised the velocity of very shallow depth according to the DSS result (Xiao et al., 2004), and verified that the shallow part of the 1-D model is important for location. Kissling et al. (1994) pointed out that the coupled hypocenter-velocity inversion solution obtained by any iterative algorithm strongly depends on the initial model and initial hypocenter locations. As described above, we assigned three groups of earthquake events and selected three initial models, from which we obtained nine combinations of event groups and initial models by pairwise bonding. For each combination, we first applied VELEST algorithms to obtain its 1-D velocity models with minimal misfit (RMS residual), so that each event groups can create three VELEST output models based on three different initial models. After comparing the RMS residuals of these three event groups, we selected one event group with the smallest RMS residual on the whole, and then merged its three output models by taking an average to obtain a new 1-D model, named VM1. Because VELEST does not automatically adjust the thickness of model layers, we linearly interpolated several layers for three initial models by following the approach of Kissling et al. (1994), where we put the trial layer thickness at 2 km for shallow crustal levels and increased layer thickness with increasing depth to approximately 4 to 5 km near Moho depths. Following the same derivation process for the model VM1, we created the VM2 model from these three new modified initial models with three event groups. Finally, with the two newly created models VM1

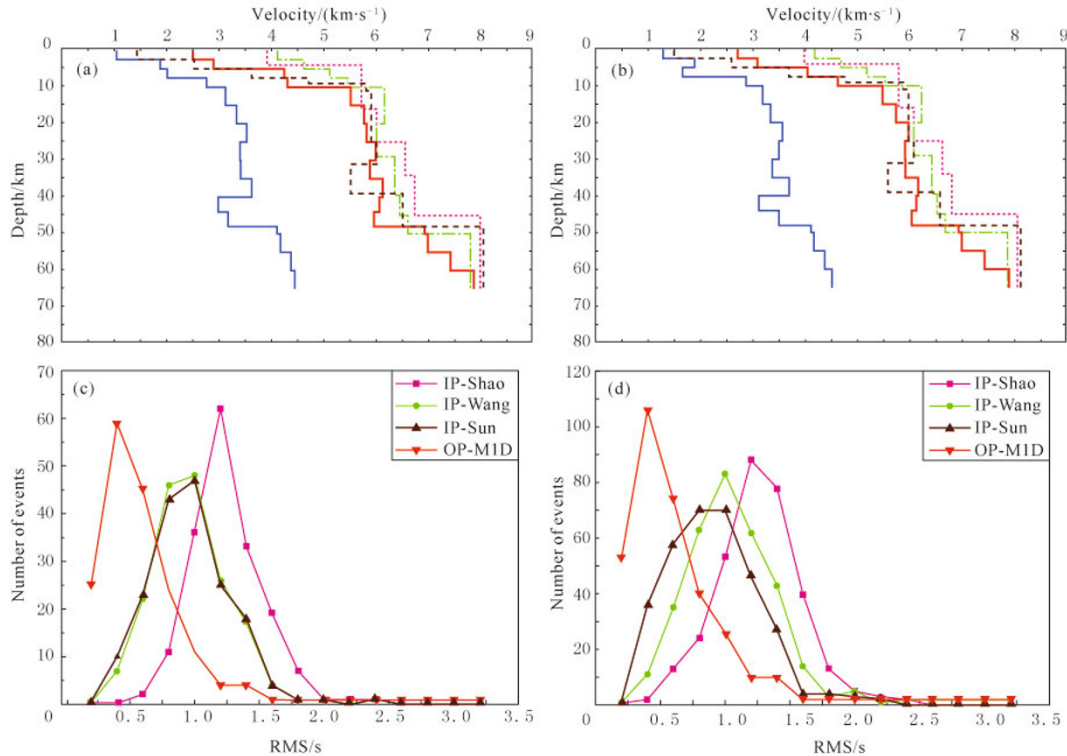


Figure 2 Three initial models and estimated 1-D velocity models for two event groups by hypoDD (a) and Hypoinverse (b), and the corresponding difference between the RMS residuals of hypocenters located by them (c, d). For (a) and (b), the solid red line shows the improved 1-D P velocity model, the solid blue line shows the improved 1-D S velocity model, the pink line shows the initial model from Shao et al. (1996), the green line shows the initial model from Wang et al. (2004), and the brown line shows the initial model from Sun et al. (2011). For (c) and (d), “IP” means input model and “OP” means output model.

and VM2, we re-ran VELEST for three event groups. The inversion iteration stopped when earthquake location and velocity of model layers became stable. The output models with close minimum RMS residuals based on the models VM1 and VM2 are similar (solid lines in Figures 2a–2b), indicating that our inversion is stable and reliable.

3 Results

Due to the fact that some events in the C65 event group are the outliers with large location errors, the resulting output RMS residuals of the group are significantly larger than those of the other two event groups (Table 1), which indicates the need to improve the quality of earthquake locations through preliminary relocation. In the following we will discuss the computation only for hypoDD and Hypoinverse event groups. We preferred to choose the model iterated from VM1 and the hypoDD event group as our minimum 1-D velocity

model because of smaller RMS values for the three event groups (solid red lines, Figure 2a). Consequently, we can achieve the smallest RMS residuals of earthquake locations. Finally, our dataset contained 1 370 P- and 1 396 S-waves, including 1 473 direct waves and 1 293 refracted waves, which covers the crustal depth range well. As compared to the three initial models, our estimated 1-D velocity model shows a reduction of total RMS values of all events for either event groups (Figures 2c, 2d), and can thus be used to relocate earthquakes more accurately.

Table 1 The calculated RMS residual of hypocenters after inversion for different initial date combination

| Events group | RMS residual | |
|--------------|--------------|------|
| | VM1 | VM2 |
| C65 | 2.02 | 2.1 |
| hypoDD | 0.53 | 0.54 |
| Hypoinverse | 0.58 | 0.59 |

In constructing the minimum 1-D velocity model, two sets of station corrections were iteratively inverted along i -th layer velocities by VELEST with positive and negative values corresponding to relatively slow (later arrivals) and fast (early arrivals) wave velocities, respectively. These corrections reveal discrepancies between the 1-D minimum velocity model and the true velocity structure below stations, and can reduce the effect of

crustal inhomogeneity. The obtained station corrections were considered to be related to subsurface geology and the depth of the Moho, but not to elevation. Our results suggest that most stations at the Junggar basin are located in a local slow velocity area, and that most stations near the northern Tianshan mountain are located in a local high velocity area with respect to the reference station LHG (white solid circle, Figure 3a).

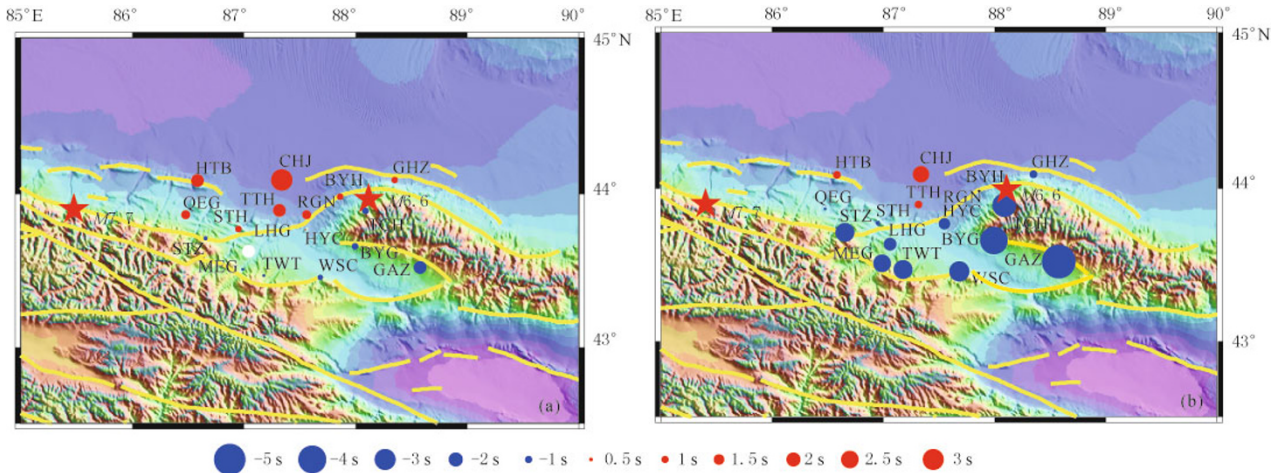


Figure 3 P-wave (a) and S-wave (b) station corrections obtained in this study. Solid circles indicate station corrections with size proportional to magnitude. Red stars denote 1965 $M6.6$ Bogda and 1966 $M7.7$ Manas earthquakes.

The Tianshan mountain northern piedmont fault continuously extend northward, through a deep blind-thrust fault slope, to a complex multi-level decollement of thrust faults that developed in Cenozoic strata. The depth of the main decollement is 8–9 km, and the upper decollement is 3–4 km (Deng et al., 1999). For our 1-D minimum velocity model, the average P-wave velocity in the shallow upper crust (<10 km) is 3.57 km/s, which is also consistent with the thick section of sedimentary strata within the Ürümqi depression (Liu et al., 2007). In contrast to previous 1-D models (Shao et al., 1996; Wang et al., 2004; Sun et al., 2011), our work has revealed relatively low velocity zones at two different depth ranges. The upper zone, at ~30 km depth, is a possible ductile shear zone between the upper and lower crusts, which has distinct physical properties. This putative shear zone is interpreted to be a zone of detachment faulting beneath thin-skinned folding and faulting that resulted from compressional stress (Xu et al., 2000a). The second low velocity zone is at a depth of ~45 km and is marked by especially low S-wave velocity (solid blue lines, Figures 2a, 2b), which were evident in 3-D imaging (Wang et al., 2008). This may be the result of a zone of partial melting at the bottom

of the lower crust, potentially influenced by small-scale convective flow from the uppermost mantle (Xu et al., 1998). This interpretation is in contrast to that of Zhao et al. (2004), in which lower crust material beneath the Junggar basin is thought to have been brought to the uppermost mantle of Tianshan orogenic belt during the north to south subduction of the Junggar tectonic block under the Tianshan orogenic belt.

There are several different depths reported as the location of the Moho discontinuity around the study area, including about 50 km depth from gravity research (Zhang et al., 2011), and 60 km depth from deep sounding profiles (Xiao et al., 2004). We detected several slightly increased velocity layers at depths greater than 48 km, similar to what has been seen in the Tianshan mountain of Kyrgyzstan (Xu et al., 2000b). Deep seismic sounding and seismic tomographic profiles across the Tianshan orogenic belt similarly indicated that gradual velocity changes occur in the crust-mantle transition zone with layer thickness of approximately 10 to 20 km (Shao et al., 1996; Zhao et al., 2001; Liu et al., 2007). Since nearly half of our dataset were refracted rays, our obtained models could reveal complexities of the crust-mantle transition zone. However, im-

proved resolution could be obtained if we conducted 3-D tomography by introducing more crossed rays of distant earthquakes based on our average 1-D structure.

Finally, we determined 781 earthquake hypocenters by applying the method hypoDD to relocate 2 370 earthquakes that occurred from 1988 to 2005 on the newly obtained 1-D crustal P-wave velocity model. The average depth of the hypocenters is 16.8 km with 75.8% being located between 5 km and 25 km depth. We reduce the average horizontal error ellipse calculated by LSQR (Paige and Saunders, 1982) from 664.6 m to 125.6 m in the east-west direction, 664.6 m to 149.3 m in the north-south direction, and errors in depth are reduced from 669.7 m to 155.7 m. When the same method and parameters were used with the model of Shao et al. (1996), the horizontal error ellipse was reduced to 191.3 m in EW, 210.4 m in NS, and the depth error to 274.5 m. Thus, our minimum 1-D velocity model further improves earthquake location precision.

In plan view (Figure 4a), the Tianshan northern piedmont fault (F_3), the dividing line between the Jung-

gar tectonic block and the active continental margin of North Tianshan (Deng et al., 1999), is a thrust deep fault. The orogenic process of collision between the Indian plate and the Eurasian plate caused the Tianshan mountain and the Bogda mountain to uplift abruptly (Tapponnier et al., 2001), and the thrust Tianshan-Junggar transition zone is generally deflected in the regional compression strain environment. The relocation results show that the earthquake events selected are mainly distributed around the Tianshan-Junggar deflection belt area, dominantly consisting of the fault F_3 , and clustering at some thrust faults and anticline area. For example, the Hutubi anticline, a latest active anticline located at northeast of Tugulu anticline, is suggested as the result of the Manas reverse fault expanding eastward and grows a minor uplift at surface (Deng et al., 1999). The selected events are also distinctly aligned south of the surface trace of the Manas-Tugulu anticline and fold deflection belts of the Bogda northern piedmont, where there are several parallel anticlines and thrust faults.

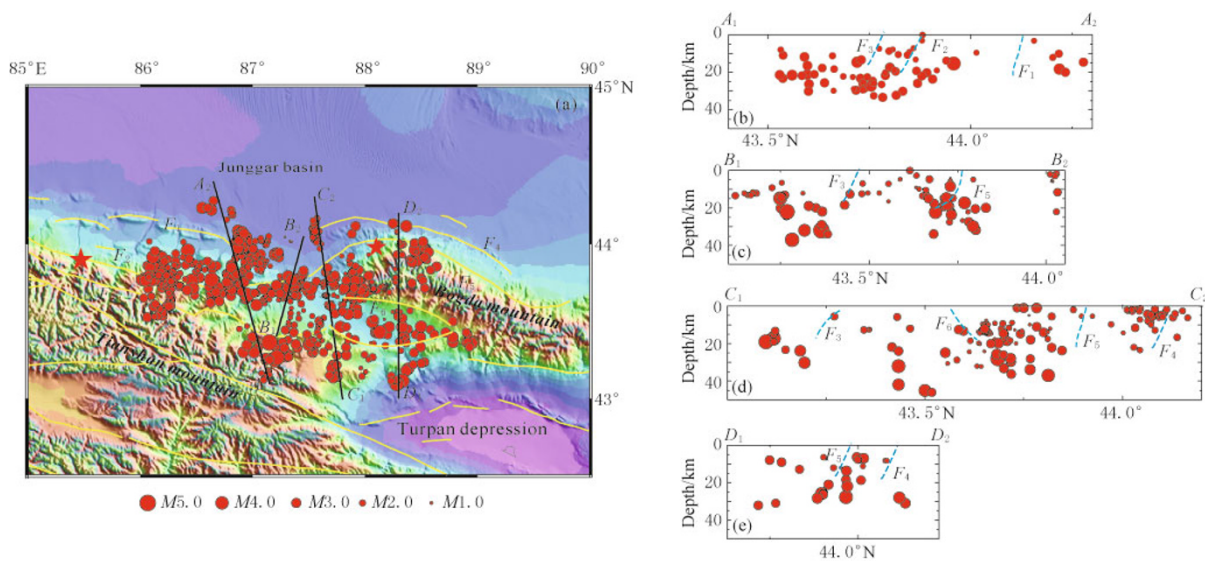


Figure 4 Distribution of relocated earthquakes within 10 km on both sides of the four profiles A_1A_2 , B_1B_2 , C_1C_2 , and D_1D_2 (a) and plan views of the four profiles (b–e) where the faults F_1 – F_6 (blue dashed lines) refer to deep seismic reflection profiles (Liu et al., 1994; Liu et al., 2007; Qi et al., 2008), and their meanings are the same as those in Figure 1.

In the profiles of Figures 4b–4e (A_1A_2 , B_1B_2 , C_1C_2 , D_1D_2), we find that most earthquakes are distributed at a depth range above 30 km, reflecting the widespread thrustnappe character, and event distributions in closely proximity to the mountains dip more steeply, appearing to follow the bounding reverse fault that separates the rigid hanging wall of Tianshan moun-

tain block from the Junggar basin block. At the boundary area, this may indicate that the deep blind faults ruptured downward when they collided with the rigid tectonic block in the folding process. The rigid upper crust of the Tianshan could have detached along the ductile shear zone in the mid-crust, contemporaneously with horizontal N-S compression and deformation forces

due to the hot material upwelling from the upper mantle. Xu et al. (2005) suggested that uneven compression may have caused a decollement to develop at the bottom of the crust, and that the Tianshan block penetrated to the southern edge of the rigid Junggar basin block along faults in the deep crust at the collision boundary. This action led to the deformation of the lithosphere between the orogenic belt and adjacent basin.

Referring to the geometrical character of several of the faults and anticlines in profiles (Liu et al., 1994; Liu et al., 2007; Qi et al., 2008), earthquakes mostly occur in the hanging wall of these thrust faults, as shown in Figure 4b. In Figure 4c, the earthquakes occurred below the depression area between F_3 and F_5 dip more gently than those below mountainous area. These findings are consistent with the presence of a detachment found in deep seismic reflection profiles of Liu et al. (2007). The Chaiwopu depression, located between the Tianshan mountain and the Bogda mountain, is common footwall of Tianshan northern piedmont fault (F_3) and Bogda southern piedmont fault (F_6) (Qi et al., 2008). The profile C_1C_2 (Figure 4d) crosses over the Chaiwopu depression and the Bogda mountain from south to north, in which most events occurred between F_5 and F_6 , where the collision area of the Bogda mountain and Ürümqi depression was found. Some events between F_3 and F_6 are located deeper than 40 km depth below the Chaiwopu depression, similar to those below the central Tianshan mountain (Xu et al., 2005). Considering the universal knowledge about viscosity of middle-bottom crust, we re-audited these original hypocenter parameters, in which the depths are beyond 40 km as well. We need to further confirm it in depth by using reflection phases like pP and PmP of waveforms recorded by seismic stations in the future. In the northward thrusting and extension orogenic process of the Tianshan mountain, the tectonic activity of the deflection belt between Bogda northern piedmont fault (F_5) and Fukan-Santai fault (F_4) is complicated, which formed some small-scale thrust fault zones and fold structures. We find that many earthquakes occurred below deflection belt area in the profile D_1D_2 (Figure 4e). Furthermore, most events relocated with relatively larger magnitude are dominantly distributed at deeper depths than smaller ones, implying that the stress is not easy to accumulate in shallow depression regions to create a large earthquake. Qi et al. (2008) pointed out that the shallow tectonic deformation at the Tianshan-Junggar area was mainly controlled by the relatively weak strata of the Jurassic and Paleogene.

4 Discussion and conclusions

Our newly relocated hypocenters may aid in the discovery of blind and deep fault zones, delineating the boundaries of sub-plates (Figures 4b–4e), which is of potential use in oil and gas exploration. However, the 1-D crustal reference velocity model does not provide a full representation of the structural complexity of the study area; even the hypoDD method cannot eliminate uncertainties associated with the model. To further improve relocation precision, future work should focus on arrival time picking, seismic station coverage, and relocation using a 3-D model. In addition, the focal mechanism solutions of regional earthquakes also help to verify the distribution and features of the fault.

By inverting P- and S-wave travel times recorded by the local seismic network and a temporary seismic array, we have developed average 1-D P-wave and S-wave velocity crustal models for the collision zone between the northern Tianshan mountain and the Junggar basin. We then relocated the events that occurred in the previous decades with this new improved reference model. Our models have improved the accuracy of hypocenter determination by significantly reducing RMS residuals of earthquakes and locating errors. In accordance with previous studies of regional geological structure, the distribution of relocated earthquakes may reveal the coherence with the distinct local over-thrust anticline belt.

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