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### An approach to explore the eddy currents of the new type divertor for EAST device using ANSYS code

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An effective method for eddy current calculation has been developed for EAST's new divertor by using ANSYS. A 3D model of a double null divertor for the EAST device was built to evaluate eddy currents and electromagnetic (EM) forces on these components. The main input to the model is the plasma current and poloidal field coil currents, which are loaded into the model using experimental data measured from the EAST discharges. These currents generate magnetic fields that match those producing an EAST discharge, and the time variation of these fields produces the eddy currents in the divertors, along with from the resulting EM forces. In addition, the first 10 time steps were discussed for the eddy current generation and changing trend. It indicates that a static analysis before a transient mode start can solve the eddy current origination in the initial time steps. With this method, the EM transient response of EAST's new divertor can be predicted based on ANSYS simulations. Furthermore, the method is also an effective approach to estimate the EM results for the in-vessel components of a fusion reactor during a disruption.

**eddy current, divertor, plasma disruption, EAST (Experimental Advanced Superconducting Tokamak) device, ANSYS**

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## 1 Introduction

Experimental Advanced Superconducting Tokamak (EAST) would achieve long pulse operations over 1000 s at plasma current  $I_p \sim 1$  MA and toroidal field  $B_T \sim 3.5$  T with ITER-like dominant Radio Frequency (RF) heating schemes [1, 2]. It has recently undertaken an extensive upgrade during the shutdown to adopt an ITER-like divertor and other in-vessel components [3, 4]. However, the eddy currents induced in the divertor components by changing plasma currents are concerned, especially in the event of plasma disruption. Therefore, to investigate the electromagnetic (EM) forces in

the divertor components, the eddy currents must be explored in detail before an engineering design, because it is related to the structure safety due to the material property issues [5–7].

To estimate eddy currents, the calculation methods are diverse. Some examples are taken including the classical method by using the EM theory, the simulation based on ANSYS with the preprocessing results from the DINA code, the calculation using the TYPHOON code with magnetic field, etc. [8–11].

In this paper, a method using the ANSYS code to define the eddy current results of the EAST divertor was introduced. All the plasma and coil current data were loaded via the ANSYS load step, extension  $Si$  ( $i$ , the time step) files, with data coming from the EAST discharge experiments.

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The key technical issues were focused on the description of the plasma currents and the coil currents. To demonstrate the simulation, a finite element model of  $4.5^\circ$  sector would be used to address the detailed process in the eddy current simulations.

## 2 Eddy current issues of EAST new divertor

### 2.1 Upgrade design on EAST divertor

The EAST new divertor will match the operations in different phases [12]. In the previous design, the EAST divertor just used a separated structure with the cooling system [13]. According to the new physics targets in the next steps, EAST needs to enhance the core parameters, which leads to a higher heat flux on the divertor components. Notably, it was reported that the ITER divertor had the requirement not only of heat removal capability, but also to provide sufficient mechanical strength to withstand the EM loads [14]. In view of this, a cassette structure similar to the ITER divertor should be adopted for EAST to meet the higher heat flux target in this phase, as shown in Figure 1. However, since the EM loads of the EAST divertor are different from ITER, the EM loads on the new EAST divertor design need to be defined and investigated.

### 2.2 Eddy currents in the divertor components

Since the EM load parameters are the input data for the mechanics analysis, the EM transient analysis is ongoing now in line with the design activities of the EAST divertor. In particular, the main focus is the induced EM forces on the divertor components due to the eddy currents.

For the EAST device, the divertor components will be influenced by the fields generated by the plasma currents and the outer coils due to the induced current effects. The effects of the induced eddy current are up to the fast current changing of the relative coils [15]. For in-vessel compo-

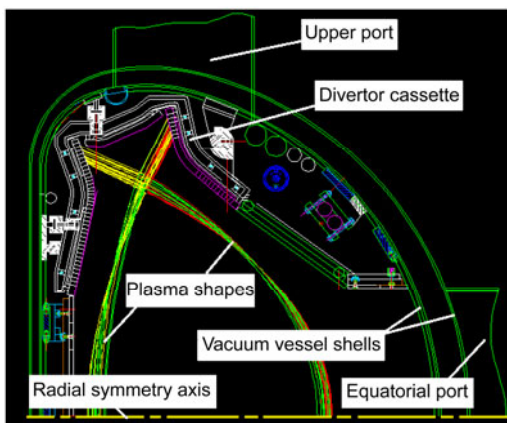


Figure 1 Half cross section of EAST vacuum vessel.

nents of fusion device, it was reported that the large eddy current would be induced on the heat sink with high conductivity during the disruption of plasma [16]. Therefore, the eddy currents in the divertor are mainly a concern during the disruption of the core plasma. In addition, in view of the changing of the currents in the superconductor coils, the PF (poloidal field) and TF (toroidal field) coils should be included. However, comparing to the currents in the PF coils, the currents in the TF coils almost keep constant, thus, the concern can be focused on the currents in the PF coils. In the EAST device, the currents exist in the superconductor coils provided by the outer powers from the discharges start to the end. The significant changes in the currents of the PF coils can be measured with 14 sets of data during one discharge shot. In the same case, the plasma currents can also be measured along with a shot time by using Rogowski coils. The plasma and coil current data are applied to the input data of the EM analysis in the simulations.

## 3 Eddy current calculation

To explore the eddy currents in the new divertor components, a 3D finite element (FE) model was established. It included the double-null divertors, 14 PF coils, the plasma filaments, and the vacuum zones, as shown in Figure 2. The element for the EM calculations was chosen as solid 97, which has AX, AY, AZ degrees of freedom.

### 3.1 Plasma current discretization

It was reported that the plasma current can be considered as a rigid current ring, and the plasma current can be shown as an exponential function [17]:

$$I = I_0 \exp(-t/\tau),$$

where  $I_0 = 1.0$  MA,  $t$ , time (s), = 3 ms. Thus, an equivalent method for plasma currents was taken into account using a linear or a thin rectangular solid body. Namely, the plasma currents are represented by a number of currents carrying filaments, and they are located in the center of the core

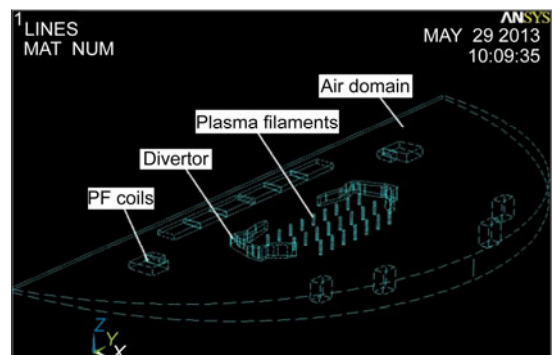


Figure 2 A 3D FE model for eddy current calculation.

plasma area. The currents of the plasma filaments vary rapidly in the plasma disruption. According to the core domain area, the filament number can be chosen as 24, and the currents in these filaments are calculated to generate the same field as the plasma during a shot [18]. The current in each filament varies with time throughout the discharge, and as a result, there is a data file of time varying currents for the filaments. It can be applied to the filament bodies by the ANSYS commands.

### 3.2 Load files

Using the ANSYS code for eddy current simulation, the key step is the load files, which load the input data of the plasma filament currents and the PF coil currents. These files define the current parameters at each time step. Each step has only one set of the measured data of currents for all plasma filaments and the PF coils in the discharge. In this study, the discharge was broken up into 79 time steps.

In addition, one load file was combined with the current information by algorithmic processor description language (APDL) of the ANSYS code. It is called the  $S_i$  ( $i=1-79$ ) files. Finally, all the  $S_i$  files were edited into one folder with the same dictionary path, which can be read and loaded in the ANSYS code successively while the simulation was run.

### 3.3 Boundary conditions

In the 3D FE model, a key point of the zero voltage was set in one corner of the model, which served for the high voltage discharge. Otherwise, there was overflow on the high voltage in the model. A "D" shape domain was set as the air zone, enclosing the divertors and the PF coils. A  $4.5^\circ$  sector of the vessel and divertor were modeled using cyclic symmetry, so symmetry boundary conditions need to be set on the two side surfaces of the "D" shape model. Figure 3 shows the boundary conditions applied to the model.

In addition, the FE model coordinate system should be changed to cylinder system if there was an original Carte-

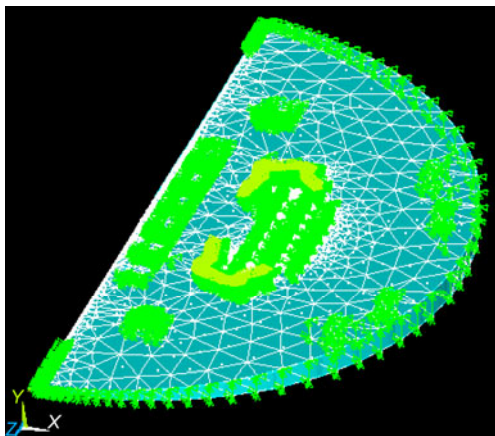


Figure 3 Boundary conditions.

sian system of the three-dimensional model. The mesh elements must be rotated into the cylindrical system for current and field calculations.

### 3.4 Calculation and discussion

The calculation results include the induced field, the induced current density, the EM force from the induced currents, etc. Since there were 79 time steps, the EM results will have 79 steps along the time variation. For example, Figure 4 just displays the induced magnetic field at time of 0.013393, and Figure 5 only shows the EM force distribution at time of 0.13776, the maximum value of the induced EM forces is located in the inner target area.

In fact, there are 79 steps of the induced fields which show the magnetic fields changing during the shot time, just the same as the eddy currents and their induced EM forces. In this case, there are 79 eddy current results and the corresponding induced EM forces for each step, which can be

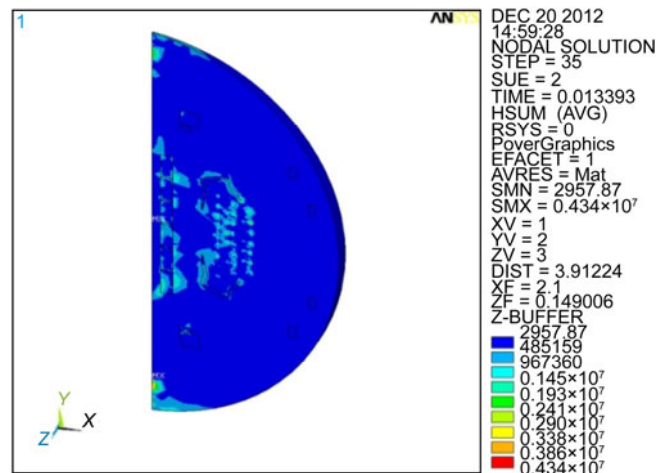


Figure 4 Induced EM field at time of 0.013393.

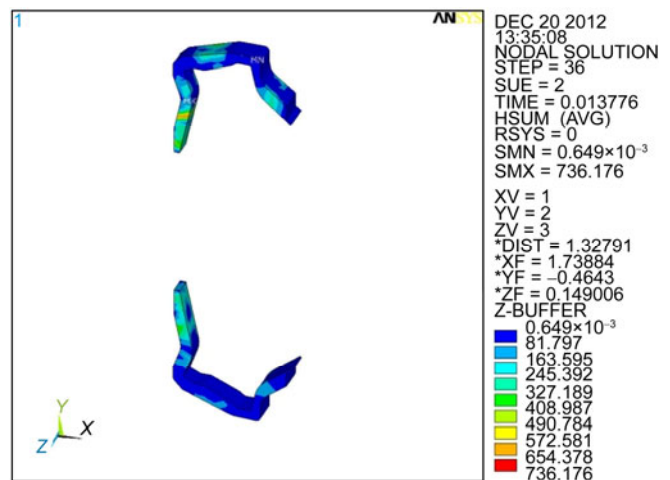


Figure 5 Induced EM force at time of 0.13776.

described as result-time step figures. The plots indicate that the induced currents and the EM forces change with the time. Figure 6 shows the change for the induced current density with two kinds of sub-time step.

It is noteworthy that the maximum value of the eddy current density is  $362 \text{ MA m}^{-2}$  at sub time step of two. It was located in the beginning of the plasma current changing where the values drop down rapidly along the first several time steps. However, we expect the eddy currents to be zero at the beginning time and then be induced from zero to a relatively high value due to the plasma current decay. The large current at the beginning is an artifact of the analysis processing. The problem is because of the choice of analysis type in the analysis processing. Therefore, the results of the first 10 steps should be abandoned since they do not reflect the real cases of the time steps. To eliminate this problem, the transient analysis must begin with the plasma at a steady state operation, instead of starting with no plasma current as has been done. Therefore, the results of the first 10 steps could be ignored since it could not reflect the real case of operation. To solve the problem, a static analysis was performed inside the first 10 time steps and used as an initial condition. The updated results are shown in Figure 7.

However, the second peak current density is in the time steps range of 35–36 and 41–56. These peaks covered the real cases of the induced currents with the time steps, the maximum value was  $124 \text{ MA m}^{-2}$ . The effective values ranged from 6.46 to  $67.1 \text{ MA m}^{-2}$ . They could be considered as the eddy current density induced by the changing currents of the plasma filaments and the PF coils, as shown

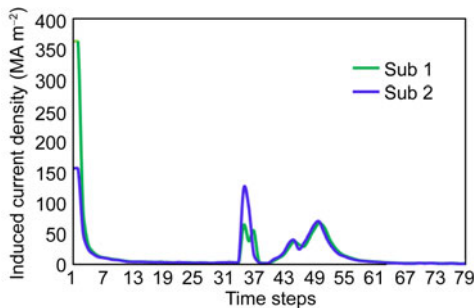


Figure 6 Induced current density with time steps.

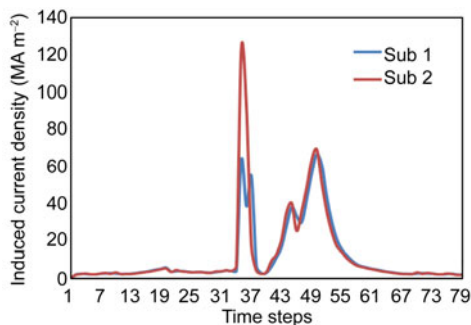


Figure 7 New results after adding a static analysis.

in Figures 5 and 6. Correspondingly, the peak EM force was  $841.622 \text{ N}$  at step of 35, and the effective EM force ranged from 86.74 to  $368.88 \text{ N}$ , as shown in Figure 8. Thus, the induced currents in the divertor components followed a trend from zero value to a peak value over the time of the disruption.

In addition to the measured data of the PF coil currents, the experimental data of the plasma currents also reflected the fast changing with the time steps from the initial change of the plasma to end in the disruption. Since the plasma currents can be discretized with the time steps based on the above exponential function, for the vessel components of other fusion devices, even for future reactors, their EM transient behavior could be predicted on the EM results once the current functions were obtained. The measured data in this study was really a set of discretized data from experimental discharges.

On the other hand, owing to the induced currents coming from the induced magnetic fields, once the changing fields of outer coils are obtained by some codes of magnetic analysis, like the PF coils, the EM calculations can also be predicted based on the magnetic field discretization.

#### 4 Summary

A method using 1D current filaments to recreate the fields generated by the plasma in the EAST tokamak is an effective way to simulate the rapid changing of magnetic fields due to changes in the plasma current during a disruption. The  $S_i$  load files ( $i$ =time step) used by APDL language can combine the filament current data along with data for the coil currents as the input data for the ANSYS code. This is the key step for the ANSYS calculations. This indicates that the ANSYS FE method can simulate the transient changing of the plasma currents and the coil currents and predict the magnetic fields, eddy currents and the relative EM forces with a set of continuous results.

In addition, it indicates that the measured current data from EAST discharge can be used to simulate the plasma disruption according to the time steps. However, the function of the current data could also be applied and loaded in the code for calculation as long as it can be discretized with

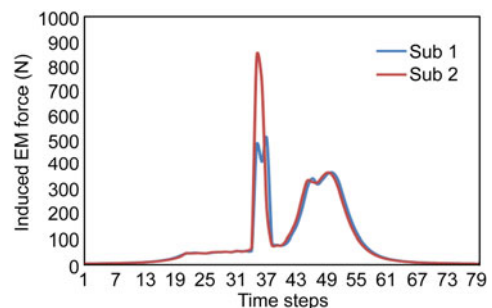


Figure 8 Induced EM forces with the time steps.

the time. Therefore, it is an effective approach to the EM analysis which can be not only applied for EAST divertor components with the measured data, but also can be served for the in-vessel components analysis of a future fusion reactor, as long as the current data can be described with a classic function or the discretized magnetic fields.

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