## LAGRANGIAN FORMULATION OF

NEOCLASSICAL TRANSPORT THEORY:
general principals and application to lorentz gas
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#### Abstract

Neoclassical transport theory is developed in a Lagrangian formulation, in contrast to the usual Eulerian development. The Lagrangian formulation is constructed from the three actions: magnetic moment, parallel invariant, and bounce averaged poloidal flux. By averaging over the fast orbital time scales an equation in the actions alone of the Fokker-Planck type is obtained. The cocfficients give the rates of the elementary neoclassical scattering processes. This action space form of the kinctic equation contains in explicit form processes like banana diffusion and the kinematic Ware pinch. The associated fluxes can be computed by simple moments without having deviations from the local Maxwellian. All the trapped particle contributions are of this explicit type. Another class of fluxes arise from perturbations to the Maxwellian and are termed implicit. The decomposition of the fluxes into explicit and implicit parts is a key feature of the Lagrangian formulation. These contributions correspond to distinct physical processes and have separate Onsager symmetry theorems (explicit and implicit) for their respective transport matrices. The theory does not depend on the details of the FokkerPlanck coefficients but only on some very general properties and is thus applicable-without modification of the formalism-to non-axisymmetric and turbulent systems. This general formulation is the primary purpose of the work. To benchmark the theory, in the present paper, the tokamak transport coefficients (for the Lorentz


gas) are computed and compared to the known Eulerian results, demonstrating the equivalence of the two formulations. The elementary processes responsible for the neoclassicial pinch and bootstrap effects (somewhat obscured in the Eulerian picture) are identified and the physical basis for their Onsager symmetry relationship is clarified.

## I. Introduction

Particles in magnetic confinement devices travel macroscopic distances between collisions. As a result in curved magnetic geometries small velocity scatterings can lead to large radial steps and a consequent increase of transport over that prevailing when the mean free path between collisions is small. The theory of such enhanced classical transport has been extensively developed $(1,2)$ and is referred to as Necolassical transport theory. It is based on the Fokker-Planck equation for the one particle distribution function,

$$
\begin{equation*}
\frac{\partial f_{j}}{\partial t}+v \cdot \nabla f_{j}+\frac{q_{j}}{m_{j}}\left(E+\frac{1}{c} v \times B\right) \cdot \nabla_{v} f_{j}=C_{j}^{L}(f) \tag{1.1}
\end{equation*}
$$

where $C_{j}^{L}$ is the Landau collision operator, representing velocity space scattering at a fixed spatial position. For systems where the collision operator dominates in Eq. (1.1), one gets the standard classical, Chapman-Enskog, transport theory. Neoclassical theory is concerned with systems where certain of the streaming terms on the left hand side of (1.1) dominate (or at least compete with) the collision operator. These orbital streaming terms then dominate in a perturbation expansion. The conventional theory is essentially Eulerian in nature, working with $f=f(x, v)$, but the independent variables $x, v$ are not constants of the orbital motion in the equilibrium fields.

In contrast to the Eulerian description, many of the concepts in the neoclassical theory involve orbital properties and are essentially Lagrangian in nature. Thus to describe the elemental transport process (in the regime of weakest collisionality in axisymmetric devices), one thinks of banana orbits with some representative width, $\rho_{p}$, and a banana center which is a constant characteristic of an orbit. In the basic scattering event, two particles "exchange" banana orbits resulting in a diffusive step of the banana center of order $\rho_{p}$.

The present paper develops a transport theory for the low collisionality, banana, regime using what amounts to a Lagrangian picture. It is couched in terms of the actions, $J_{1}, J_{2}, J_{3}$, which are constants of motion in the equilibrium fields. We choose the actions in an axisymmetric toroidal system to be

$$
\begin{align*}
& J_{1} \equiv \pi m(b \times v)^{2} / \Omega=\text { M } \Lambda \text { GNEIIC MOMENT } \\
& J_{2} \equiv m \oint d s u=\text { PARALLEL INVARIANT }  \tag{1.2}\\
& J_{3} \equiv 2 \pi \frac{q}{c}\langle\psi\rangle=\text { DRIFI CENTER FLUX COORDINATE }
\end{align*}
$$

The reduced kinetic equation can be shown to be,

$$
\begin{equation*}
\frac{\partial f_{j}}{\partial t}+\frac{\partial}{\partial J} \cdot \frac{q_{j}}{2 \pi} V_{T u} u(\lambda) f_{j}=C_{j}^{\prime}(f)=\frac{\partial}{\partial J} \cdot \Gamma_{j}(f) \tag{1.3}
\end{equation*}
$$

where $C_{j}^{J}$ is a collision operator describing action scattering due to collisions, and $V_{T}$ is the inductive toroidal voltage. The distribution, $f_{j}$, is a function of the actions only. The orbital streaming terms in Eq. (1.1) of the Eulerian formulation do not appear explicitly, but have been incorporated into the collision operator. Thus, $C_{j}^{J}$ contains terms of the form $\partial / \partial J_{3} D_{33} \partial / \partial J_{3} f_{j}$, which give directly, radial diffusion due to action exchange under collisions.

The general form of the kinetic Eq. (1.3) would hold with any choice of the actions. If a compact transport theory is to be developed from (1.3), however, the choice is considerably narrowed. Specifically, one of the action variables must be identified as essentially spatial (radial), with the remaining two being velocity like. Since all the actions are intrinsically mixed (space-velocity) variables this distinction requires some explanation. Suppose the equilibrium Hamiltonian, $H_{0}=H_{0}\left(J_{1}, J_{2}, J_{3}\right)$ depends weakly on the action $J_{3}$ such that $\omega_{3} \equiv \partial H_{0} / \partial J_{3} \ll \omega_{1}, \omega_{2}$. Then the energy depends principally on the "velocity" variables $J_{1}$ and $J_{2}$, and $J_{3}$ can be regarded as a "radial" parameter. For the actions given in Eq. (1.2) and derived in Sec. II the conjugate angles $\theta_{1}, \theta_{2}, \theta_{3}$ are, respectively, bounce average gyrophase, bounce phase, and drift phase. The associated frequencies are then the bounce averaged gyrofrequency, bounce (or transit) frequency, and bounce averaged drift frequency. The frequencies are well ordered such that $\omega_{1} \gg \omega_{2} \gg \omega_{3}$ and $J_{3}$ is a good radial variable. Previous work.(3) in applying action-angle variables to a tokamak used the angular momentum invariant associated with axisymmetry, $J_{\phi}=\partial L / \partial \phi=\frac{q}{c} \psi+m R u B_{T} / B$, for the third action. Although $J_{\phi}$ can be used to calculate the radial shape of a banana orbit, the third frequency is large because of the kinetic piece, $m R u B_{T} / B$ of the angular momentum ( $\omega_{3} \sim \omega_{2} \sim$ transit frequency for untrapped particles), and this renders $J_{\phi}$ an inconvenient choice for constructing a transport theory.

The physical basis for the Lagrangian formulation is that in the lowest collisionality (banana) regime, the distribution function relaxes in a sequence of well-ordered time scales. On the fastest, orbital, time scale $f$ relaxes to a function of the constants of motion, or actions, alone. (Strictly speaking, the orbital motion docs not relax $f$,but rather produces very fine scale angle dependence, e.g. $f(\theta, t)=f\left(\theta-\omega_{i} t, 0\right)$, which is then destroyed by collision at a rate $\left(\nu \omega_{i}^{2}\right)^{1 / 3} \gg \nu$, the collision frequency.) The actions scatter under the influence of collisions to relax $f$ to a local Maxwcllian on the collisional time scale. Relaxation of the radial action gradients produces the transport on the (longer) diffusion time scale. The Lagrangian theory follows this hicrarchy of relaxation processes, first averaging over the orbital time scales (or equivalently, the angle variables) to give an equation of the form (1.3). The idea of expressing the collision operator in a constant of
motion space to eliminate the fast orbital time scale was first suggested by Hively, Miley and Rome (4), who applied such a theory to the very non-local problem of alpha particle transport. The velocity scattering part of the operator $C_{J}$, obtained by bounce averaging at fixed $\psi$ and thus ignoring the radial scattering, have been previously derived by Connor and Cordey (5).

The collision operator, $C_{j}^{J}$ of Eq. (1.3), can be written in a generalized Landau form as shown in Sec. III. It implies global conservation laws for particle number and energy, as well as a generalized global, $H$-theorem. This means that the Maxwell distribution $f \sim \exp \left(-H_{0}(J) / T\right)$ is absolutely stationary and unchanged by collisions. In practice, however, the absolute equilibrium distribution does not represent a magnetically confined plasma (owing to the weak dependence of $H_{0}(J)$ on $J_{3}$ or $\psi$ ). Non-equilibrium dependence on $J_{3}$ must be introduced to obtain spatial localization, thus one has a local Maxwellian,

$$
\begin{equation*}
f_{0}(J)=n\left(J_{3}\right) \frac{\exp \left[-H_{0}\left(J / T\left(J_{3}\right)\right]\right.}{\sqrt{2 \pi\left(m T\left(J_{3}\right)\right)^{3}}} \tag{1.4}
\end{equation*}
$$

Since the collision operator docs not annihilate a distribution like Eq. (1.4), transport will arise duc to collisions in Eq. (1.3).

The transport equations result simply by taking reduced moments of Eq. (1.3). Thus integration over $J_{1}$ and $J_{2}$ gives the particle transport equation in the form

$$
\begin{equation*}
\frac{\partial}{\partial t} n_{3}+\frac{\partial}{\partial J_{3}} \Gamma=0 \tag{1.5}
\end{equation*}
$$

where $n_{3}$ is particle number per unit $J_{3}$. Similarly, multiplication by $H_{0}$ and integration over $J_{1}, J_{2}$ gives the energy equation,

$$
\begin{equation*}
\frac{\partial}{\partial t} \frac{3}{2} n_{3} T+\frac{\partial}{\partial J_{3}}\left(\frac{3}{2} \Gamma T+q\right)=I_{T}^{i} V_{T} \tag{1.6}
\end{equation*}
$$

where $I_{T}^{i} V_{T}$ is Ohmic dissipation (per unit $J_{3}$ ), $V_{T}$ is the toroidal voltage, and $q$ is the heat flux. The transport equations are closed when the fluxes, $\Gamma, q$, and $I_{T}$ can be expressed in terms of $n, T$, and $V_{T}$. This is achieved by a very simple expansion of $f_{j}$ in Eq. (1.3) in powers of $\rho_{p} / a$ (poloidal gyroradius over minor radius), as described in Sec. IV. One then obtains a transport matrix, $T_{i j}$, relating the fuxes, $\Gamma, q / T, I_{T}$ to the forces, $A_{1}=d \ln n / d J_{3} ; A_{2}=d \ln T / d J_{3} ; A_{3}=V_{T} / T$,

$$
\begin{align*}
\Gamma & =T_{1 j} A_{j} \\
q / T & =T_{2 j} A_{j}  \tag{1.7}\\
I_{T} & =T_{3 j} A_{j} .
\end{align*}
$$

Note that the transport equations result directly from moments. It is not necessary to perform flux surface averages as required in the familiar Eulerian theory to obtain local transport relations. The two formulations are, of course, equivalent, although the connection between them is somewhat subtle, and there are differences in the theoretical structure which have physical implications. The Lagrangian formulation gives a much clearer picture of the physical processes responsible for the various neoclassical effects.

In the Eulerian version, the transport coefficients are written as inner products in the form, $T_{i j}=\left(a_{i}, g_{j}\right)$, .where $g_{i}$ is the perturbation from Maxwellian of the distribution function, driven by $a_{j}$. All fluxes are thus associated with deviations from the local Maxwellian, $f_{0}$. In the Lagrangian picture some fluxes exist, even without perturbations to $f_{0}$. We refer to these as explicit fluxes and denote their contribution to the transport coefficient by $T_{i j}^{e}$. In addition there are implicit fluxes of the form ( $\alpha_{i}, g_{j}$ ), not the same $\alpha_{i}$ and $g_{i}$ one has in the Eulerian theory, which are a result of perturbations $g_{j}$ on $f_{0}$ and depend for their existence on collisions (even though the final transport coefficient may not depend on collision frequency). Denoting these implicit contributions by $T_{i j}^{i}=-\left(a_{i}, g_{j}\right)$, the total transport coefficient is then $T_{i j}=T_{i j}^{e}+T_{i j}^{i}$. Thus, for example, from the term $\partial / \partial J_{3} D_{33} \partial / \partial J_{3} f_{0}$, of the collision operator one obtains a contribution to $T_{11}$ of the form $T_{11}^{e}=\int d J_{1} d J_{2} D_{33} f_{0}$, which corresponds to the physically appealing Lagrangian picture of diffusion of the banana centers. Similarly in the pinch cocfficient $T_{13}$, there is a contribution coming directly from the electric field term on the left hand side of Eq. (1.3), $T_{13}^{e}=\int d J_{1} d J_{2} q_{j} / 2 \pi T a_{3}(J) f_{0}$. This corresponds to a radial flow of particles, independent of the presence of collisions, and, for the trapped particles, is precisely the effect originally described by Ware (6). Finally, there are explicit contributions to the toroidal current, essentially diamagnetic in nature, which must be added to $I_{T}^{i}$ in computing the full spatial current density. Thus one has diamagnetic, $T_{31}^{e}$, as well as collisional, $T_{31}^{i}$, contributions to the bootstrap current. Note that the diamagnetic currents do not appear in the Ohmic dissipation term of Eq. (1.6), since no work is done by the external voltage $V_{T}$ in producing this current.

The implicit contributions to the transport matrix are symmetric, $T_{i j}^{i}=T_{j i}^{i}$, and have an associated positive definite form for antropy production due to collisions. It is for this implicit part that one can apply Onsager's theorem (7). There is no general thermodynamic argument, however, requiring symmetry of the explicit fluxes. In spite of this, for the axisymmetric tokamak, one finds. difectly, that $T_{i j}^{e}=T_{j i}$ and symmetry wbtains for the nevrall transport coefficients.

Now, the Eulerian theory does not naturally lend itself to this decomposition of the fluxes into explicit and implicit pieces. As a result, the clementary processes underlying certain effects, like the pinch effect and bootstrap current, have been obscured. The simple physical pictures have born little relation to the detailed mathematical expressions for the fluxes in the Eulerian representation. One could not be sure how much the pinch effect depended on collisions, to what extent the bootstrap current was diamagnetic, or why these processes were Onsager conjugate. The pinch effect has been interpreted as predominantly Ware's collisionless inward flow of trapped particles. The bootstrap current, on the other hand, required collisions, and was carried by circulating particles. A questions that has never been satisfactorily resolved is why such different effects, involving different classes of particles, should be Onsager conjugate processes? In the present, Lagrangian formulation, these issues can be clarified. We find that the pinch effect has two interpretations; one, the conventional Ware effect, or alternatively, a collisional process, affecting circulating particles, exclulsively. It is the alternate explanation that accounts for Onsager symmetry. The basic elementary process has an inverse process that generates the bootstrap current.

As a practical matter, the trapped particle contributions, which dominate most of the transport coefficients, are all explicit. They may be computed simply from moments without ever solving for the $g_{j}$ 's.

Probably the most useful aspect of the Lagrangian formulation is its generalizability. Equation (1.3) can be viewed as a Fokker-Planck equation in the actions with coefficients akin to the familiar stochastic average, $<\Delta J \Delta J / \Delta t>$, which, in the present paper, are due to collisions. These coefficients give the rates of the elementary scattering processes. However, the transport theory which follows does not depend on the precise form of these coefficients, but only some very general properties. Thus it can be extended in several directions. The neoclassical theory of non-symmetric systems, specifically treating like-particle transport, is considered in a companion paper (8). Further, the Lagrangian formulation provides a scheme for unifying collisional and turbulent transport. The necessity of a unifying framework is evident from the nature of neoclas- sical transport: collisional scattering from one global collisionless orbit to another. In a turbulent medium the collisionless orbits are quite different. Thus, in addition to the purely turbulent (primarily radial) transport, one has modifications to the neoclassical transport. The coefficients are not necessarily additive and a unifying framework is required for a proper evaluation of the transport. In the I.agrangian formulation this unification can be carried out by gencralizing the underlying Fokker-Planck coefficients. These points are emphasized by recent Monte Carlo work on stellarator transport (9) which naturally adopted what amounts to a Fokker-Planck
or Lagrangian approach. These studies cvaluted the test particle diffusion coefficient, $\Delta J_{3} \Delta J_{3} / \Delta t$, and the contributios to transport that it implies. Such a calculation does not give the full transport coefficient as there are several other processes that in general, contribute to the net particle diffusion and thermal conductivity coefficients. In addition, there are off diagonal coefficients, such as those giving the bootstrap current, which are important. These refinements to the theory can be carried out by using the Monte Carlo codes to compute the remaining Fokker-Planck coefficients. The formalism developed herein provides the procedures for obtaining the transport matrix from these Fokker-Planck coefficients.

It is to be emphasized that the novel feature of this work is the general formulation which allows the treatment of turbulence and non-axisymmetric systems. In the present paper the theory is benchmarked by displaying that it reproduces, identically, the tokamak transport coefficients for the Lorentz gas. The extension of the theory to heretofor unexplored problems is currently underway.

## II. Guiding Center Theory for an Axisyınmetric Torus: Action-Angle Variables

The formal theory to be developed here assumes the existence of action-angle variables, either exact or approximate to some requisite order of accuracy. We shall now present a derivation of those action-angle variables appropriate to an axisymmetric situation, correct to lowest significant order, within the guiding center approximation. The program starts from the equations of motion for the guiding center and uses the associated Lagrangian, first to derive the canonical angular momentum associated with the axisymmetry, and then to expeditiously transform the equations into flux coordinates. The parallel action $J_{2}$ is then derived, as well as its associated angle variable $\theta_{2}$. The action $J_{1}$ corresponding to the magnetic moment $\mu$ is demonstrated to be given by $J_{1}=2 \pi m c \mu / q$, and the associated angle variable $\theta_{1}$ to be $1 / 2 \pi$ times the gyration phase averaged over $\theta_{2}$. The third action $J_{3}$ is shown to be proportional to the poloidal flux coordinate $\psi$ averaged over $\theta_{2}$, and its associated angle variable to be $1 / 2 \pi$ times the average over $\theta_{2}$ of the other flux coordinate $\beta$. The energy $E=H(J, t)$ is then seen to be the Hamiltonian for the reduced problem. The reader is assumed to be familiar with the rudiments of guiding center theory, for example as developed by Bernstein (10) in a paper hereafter denoted by $I$, the notation of which is herein employed.

Consider the motion in a strong but slowly varying magnetic field $B(r, t)$, and a weak and slowly varying electric ficld $E(r, t)$ of a charge of mass $m$ and charge $q$. To lowest significant order in guiding center theory one can write the position vector of a particle charge $q$ and mass $m$ in the form

$$
\begin{equation*}
r=R+p \tag{2.1}
\end{equation*}
$$

where in a right-handed orthonormal set of basis vectors $e_{1}(R, t), e_{2}(R, t), e_{3}(R, t)=b(R, t)=B(R, t) / B(R, t)$ the guiding center $R$ obeys

$$
\begin{align*}
\dot{R} & =u b+\frac{b}{m \Omega} \times\left[\mu \nabla B+m u^{2} b \cdot \nabla b+m u \frac{\partial b}{\partial t}-q E\right]  \tag{2.2}\\
m \dot{u} & =-\mu b \cdot \nabla B+q b \cdot E+m u b \cdot(\nabla b) \cdot \dot{R} \tag{2.3}
\end{align*}
$$

and the gyration vector is given by

$$
\begin{align*}
& \rho=\rho\left[e_{1} \sin \varpi+e_{2} \cos \varpi\right]  \tag{2.4}\\
& \rho=\left[2 \mu B / m \Omega^{2}\right]^{1 / 2}  \tag{2.5}\\
& \varpi=\int_{0}^{t} d t^{\prime} \Omega\left[R\left(t^{\prime}\right), t^{\prime}\right]  \tag{2.6}\\
& \Omega=q B / m c \tag{2.7}
\end{align*}
$$

In Eqs. (2.2) - (2.7) the quantities $b, B, \Omega, E, e_{j}$, are evaluated at $R$, and are assumed not to change much in a time $2 \pi / \Omega$ or distance $\rho$, and the magnetic moment $\mu$ is a constant of the motion.

If one introduces a vector potential $A$ and scalar potential $U$ such that

$$
\begin{align*}
& B=\nabla \times A  \tag{2.8}\\
& E=-\nabla U-\frac{1}{c} \frac{\partial A}{\partial t} \tag{2.9}
\end{align*}
$$

then (2.1) and (2.2) are the equations of motion (to lowest significant order in the small parameter underlying guiding center theory) associated with the Lagrangian, a generalization of that given by Taylor (11) for the case of a vacuum magnetic field,

$$
\begin{equation*}
L=\frac{1}{2} m(b \cdot \dot{R})^{2}+\frac{q}{c} \dot{R} \cdot A-\mu B-q U \tag{2.10}
\end{equation*}
$$

This reduced Lagrangian is readily obtained from the exact particle Lagrangian by using (2.1), introducing two time scales in $\rho$, and averaging over the rapidly varying gyro-phase keeping the slow variation fixed. The term $\mu B$ there is seen to represent the kinetic energy of the motion perpendicular to the line of force through the guiding center in question.

Consider an axisymmetric magnetic field and write in cylindrical coordinates $R, \varsigma, Z$

$$
\begin{equation*}
B^{\prime}=B_{R}(R, Z, t) e_{R}+B_{s}(R, Z, t) e_{s}+B_{Z}(R, Z, t) e_{Z} \tag{2.11}
\end{equation*}
$$

Then $B$ can be derived from the vector potential

$$
\begin{equation*}
A=\psi(R, Z, t) \nabla_{\zeta}+e_{Z} A_{Z}(R, Z, t) \tag{2.12}
\end{equation*}
$$

where

$$
\begin{equation*}
A_{Z}=\int^{R} d R^{\prime} B_{5}\left(R^{\prime}, Z, t\right) \tag{2.13}
\end{equation*}
$$

Correspondingly

$$
\begin{equation*}
L=\frac{1}{2} m\left(\dot{R} b \cdot e_{l l}+R \dot{\zeta} \dot{b} \cdot e_{\varsigma}+Z b \cdot e_{Z}\right)^{2}+\frac{q}{c}\left(\psi \dot{\zeta}+A_{Z} Z\right)-\mu B-q U \tag{2.14}
\end{equation*}
$$

Since $L$ is independent of $\varsigma$ it follows that

$$
\begin{equation*}
P_{5}=\frac{\partial L}{\partial \dot{\zeta}}=m R u b \cdot e_{\zeta}+\frac{q}{c} \psi \tag{2.15}
\end{equation*}
$$

where

$$
u=b \cdot \dot{R}
$$

is a constant of the motion.
An alternate choice of vector potential, more convenient for what is to come, is generated as follows. Let the curves $\chi(R, Z, t)=$ const be the orthognal trajectories in the $R, Z$ plane of the curves $\psi(R, Z, t)=$ const. That is $(\nabla \psi) \cdot \nabla \chi=0$. Define

$$
\begin{gather*}
G(\psi, \chi, t)=\frac{B_{\varsigma}}{e_{\varsigma} \cdot(\nabla \chi) \times(\nabla \psi)}  \tag{2.16}\\
\beta=\varsigma-\int_{0}^{\chi} d \chi^{\prime} G\left(\psi, \chi^{\prime}, t\right) \tag{2.17}
\end{gather*}
$$

Then

$$
\begin{align*}
\nabla \times(\psi \nabla \beta) & =(\nabla \psi) \times\left[\nabla \zeta-G \nabla \chi-(\nabla \psi) \int_{0}^{\chi} d \chi^{\prime} \partial G\left(\psi, \chi^{\prime}, t\right) / \partial \psi\right] \\
& =(\nabla \psi) \times \nabla \zeta+G(\nabla \chi) \times \nabla \psi  \tag{2.18}\\
& =B
\end{align*}
$$

since $(\nabla \chi) \times(\nabla \psi)$ is parallel to $e_{\zeta}$. Note that if the lines $\psi=$ const are topologically a set of nested circles, then $\chi$ may be chosen so that it behaves like an angle which changes by $2 \pi$ as one moves once around a closed curve $\psi=$ const, the so-called poloidal angle. Note too that since $B=(\nabla \psi) \times \nabla \beta$ it follows that $\boldsymbol{B} \cdot \nabla \psi=0$ and $B \cdot \nabla \beta=0$ whence one can use the values of $\psi$ and $\beta$ to label a line of force. Let $s$ be a coordinate which measures are length along a line of force; see Fig. [1]. If we use as coordinates $\psi, \beta$, and $s$, then the position vector $R=R(\psi, \beta, s, t)$, and if we denote a partial derivative by a subscript it follows from its definition as arc length that

$$
\begin{equation*}
R_{s}=b \tag{2.19}
\end{equation*}
$$

whence

$$
\begin{equation*}
u=b \cdot \dot{R}=b \cdot\left(\dot{s} R_{s}+\dot{\beta} R_{i}+\dot{\psi} R_{v}+R_{t}\right)=\dot{s}+\dot{\beta} b \cdot R_{i}+\dot{\psi} R_{\psi}+b \cdot R_{l} . \tag{2.20}
\end{equation*}
$$

Moreover, with $A=\psi \nabla \beta$

$$
\begin{equation*}
\dot{R} \cdot A=\psi \dot{R} \cdot \nabla \beta=\psi\left(\dot{\beta}-\frac{\partial \beta}{\partial t}\right) \tag{2.21}
\end{equation*}
$$

Thus if one defines
then following (2.10)

$$
\begin{equation*}
V=\mu \Omega+q\left(V+\frac{\psi}{c} \frac{\partial \beta}{\partial t}\right) \tag{2.22}
\end{equation*}
$$

$$
\begin{equation*}
L=\frac{1}{2} \mu^{2}+\frac{q}{c} \psi \dot{\beta}-V \tag{2.23}
\end{equation*}
$$

-The equations of motion for $\psi$ and $\beta$ which follow from (2.23) are readily seen to be, on cmploying (2.20),

$$
\begin{align*}
& \left(\frac{q}{c} \beta-m u b \cdot R_{\psi}\right)^{\cdot}=V_{\psi}  \tag{2.24}\\
& \left(\frac{q}{c} \psi+m u b \cdot R_{\beta}\right)^{\cdot}=-V_{\beta} \tag{2.25}
\end{align*}
$$

One can derive alternate expressions for $\dot{\psi}$ and $\dot{\beta}$ which are easier to understand, though not as useful for solving the equations of motion, as follows. Define the drift velocity

$$
\begin{equation*}
v_{d}=\frac{b}{m \Omega} \times\left[\nabla V+m u^{2} b \cdot \nabla b\right] \tag{2.26}
\end{equation*}
$$

and introduce

$$
\begin{equation*}
v_{B}=\frac{b}{B} \times\left[\frac{\partial \psi}{\partial t} \nabla \beta-\frac{\partial \beta}{\partial t} \nabla \psi\right] \tag{2.27}
\end{equation*}
$$

Then it is seen directly that

$$
\begin{equation*}
\frac{\partial \psi}{\partial t}+v_{B} \cdot \nabla \psi=0 \quad \frac{\partial \beta}{\partial t}+v_{B} \cdot \nabla \beta=0 \tag{2.28}
\end{equation*}
$$

and $v_{B}$ can be interpreted as the velocity of the line of force labeled by $\psi$ and $\beta$, and $\boldsymbol{v}_{d}$ measures the drifting of the particle from that line. Moreover one can readily show that

$$
\begin{equation*}
\dot{R}=u b+v_{d}+v_{B} \tag{2.29}
\end{equation*}
$$

when the coordinates $\psi$ and $\beta$ of a guiding eenter obey the equations of motion

$$
\begin{align*}
& \dot{\psi}=\frac{\partial \psi}{\partial t}+\dot{R} \cdot \nabla \psi=v_{d} \cdot \nabla \psi  \tag{2.30}\\
& \dot{\beta}=\frac{\partial \beta}{\partial t}+\dot{R} \cdot \nabla \beta=v_{d} \cdot \nabla \beta \tag{2.31}
\end{align*}
$$

where in order of magnitude $v_{d} \approx u^{2} / \Omega R \approx u \rho / R \ll u$.

The equation of motion for $s$ which follows from (2.23) is
$m\left(\dot{s}+\dot{\psi} b \cdot R_{\psi}+\dot{\beta} b \cdot R_{\beta}+b \cdot R_{t}\right)=-V_{s}+m u\left[\dot{\psi}\left(b \cdot R_{\psi}\right)_{s}+\dot{\beta}\left(b \cdot R_{\beta}\right)_{s}+\left(b \cdot R_{t}\right)_{s}\right]$

But since we are considering situations where for a representative case $s^{2} \sim u^{2} \gg(\dot{R}-u b)^{2}$, in its action on $b \cdot R_{\psi}, b \cdot R_{; 3}$, and $b \cdot R_{t}$ the convective time derivative an be approximated by $u b \cdot \nabla \approx u \delta / \partial s$. Moreover, since on average $\left(\ddot{\psi} b \cdot R_{\psi}\right)^{2} \ll\left[u \dot{\psi}\left(b \cdot R_{\dot{\psi}}\right)_{s}\right]^{2}$ and $\left(\dot{\psi} b \cdot R_{\psi}\right)^{2} \gg\left(b \cdot R_{t}\right)^{2}$, to the requisite accuracy Eq. (2.32) becomes

$$
\begin{equation*}
m \ddot{s}+V_{s}=0 \tag{2.33}
\end{equation*}
$$

Usually the motion along the lines of force is very rapid compared with the drift from a given line, which suggests solving (2.33) approximately holding $\psi, \beta$, and the explicit time dependence in $V$ constant. For reasonable magnetic field configurations there are two usual circumstances. Either the particle is magnetic mirror reflected by the spatially varying magnetic field strength, in which case the motion projected in the $R, Z$ plane consequent to (2.15) has the well known banana character, or it continues to circulate around the torus. In the latter case at fixed $\psi, \beta$, and $t$ the field strength $B$ is periodic in $s$ since when $\chi$ increases by $2 \pi$ one has the same values of $R$ and $Z$. This corresponds to a shift in $\zeta$ given by (2.17), viz.

$$
\begin{equation*}
\Delta(\psi)=\oint d \chi G \tag{2.34}
\end{equation*}
$$

But if one writes $R=R(\psi, \beta-\zeta, t), Z=Z(\psi, \beta-\varsigma, t)$, along the line of force

$$
\begin{equation*}
(d s)^{2}=(d R)^{2}+R^{2}(d \varsigma)^{2}+(d Z)^{2}=\left(R_{\varsigma}^{2}+R^{2}+Z_{\varsigma}^{2}\right)(d \varsigma)^{2} \tag{2.35}
\end{equation*}
$$

and the associated change in $s$ is

$$
\begin{equation*}
\delta=\int_{\varsigma}^{\varsigma+\Delta \varsigma} d \varsigma s_{5}(\psi, \beta, \varsigma, t) \tag{2.36}
\end{equation*}
$$

where following (2.35)

$$
\begin{equation*}
s_{\varsigma}=\left[R_{\varsigma}^{2}+R^{2}+Z_{\varsigma}^{2}\right]^{1 / 2} \tag{2.37}
\end{equation*}
$$

The desired approximate solution is obtained by introducing an angle variable $\theta_{2}(t)$ to account for the rapid motion along the lines of force, and writing $s=s\left(\theta_{2}, t\right)$. Then, as shown in $I$, it follows that if

$$
\begin{equation*}
\frac{1}{2} m w^{2}=E-V(\psi, \beta, s, \mu, t) \tag{2.38}
\end{equation*}
$$

then $E$ which is independent of $s$ is determined via

$$
\begin{equation*}
J_{2}=\oint d s m w \tag{2.39}
\end{equation*}
$$

where $J_{2}$ is an adiabatic invariant. The integral in (2.39) is executed holding $\psi, \beta, t$ fixed. Defining

$$
\begin{equation*}
\frac{1}{w_{2}}=\oint \frac{d s}{w} \tag{2.40}
\end{equation*}
$$

one has

$$
\begin{equation*}
\theta_{2}=\int d t \omega_{2} \tag{2.41}
\end{equation*}
$$

and $s$ is given implicitly by

$$
\begin{equation*}
\theta_{2}=\omega_{2} \int^{t} \frac{d s}{w} \tag{2.42}
\end{equation*}
$$

We will now show that $E$ can be viewed as a Hamiltonian. To this end we define

$$
\begin{equation*}
J_{1}=2 \pi \frac{m c}{q} \mu \tag{2.43}
\end{equation*}
$$

and note that following (2.39) $E=E\left(J_{1}, J_{2}, \psi, \beta, t\right)$. Then if one differentiates (2.39) with respect to $J_{2}$ there results

$$
\begin{align*}
1 & =\oint \frac{d s}{w} \frac{\partial}{\partial J_{2}} \frac{1}{2} m w^{2} \\
& =\oint \frac{d s}{w} \frac{\partial E}{\partial J_{2}} \tag{2.44}
\end{align*}
$$

whence on using (2.40)

$$
\begin{equation*}
\omega_{2}=\frac{\partial E}{\partial J_{2}} . \tag{2.45}
\end{equation*}
$$

Also on differentiating (2.39) with respect to $J_{1}$, one obtains using (2.38)

$$
\begin{align*}
0 & =\oint \frac{d s}{w} \frac{\partial}{\partial J_{1}} \frac{1}{2} m w^{2} \\
& =\oint \frac{d s}{w}\left[\frac{\partial E}{\partial J_{1}}-\frac{\Omega}{2 \pi}\right] \tag{2.46}
\end{align*}
$$

whence if we define

$$
\begin{equation*}
\omega_{1}=\omega_{2} \oint \frac{d s}{w} \frac{\Omega}{2 \pi}=\oint d 0_{2} \frac{\Omega}{2 \pi}, \tag{2.47}
\end{equation*}
$$

then

$$
\begin{equation*}
\omega_{1}=\frac{\partial E}{\partial J_{1}} . \tag{2.48}
\end{equation*}
$$

Thus if

$$
\begin{equation*}
\theta_{1}=\int d t \omega_{1} \tag{2.49}
\end{equation*}
$$

it follows that if we treat $J_{1}$ and $\theta_{1}$ and $J_{2}$ and $\theta_{2}$ as action and angle variables, then

$$
\begin{array}{ll}
\dot{J}_{1}=-\frac{\partial E}{\partial \theta_{1}}=0 & \dot{\theta}_{1}=\frac{\partial E}{\partial J_{1}}=\omega_{1} \\
\dot{J}_{2}=-\frac{\partial E}{\partial \theta_{2}}=0 & \dot{\theta}_{2}=\frac{\partial E}{\partial J_{2}}=\omega_{2} \tag{2.51}
\end{array}
$$

Clearly (2.50) and (2.51) are Hamiltonian equations of motion.
We shall now demonstrate that $\omega_{2}$ and $E$ are independent of $\beta$. To this end employ $\varsigma$ instead of $s$ as the variable of integration and observe that it follows from $\psi=\psi(R, Z, t)$ and $\chi=\chi(R, Z, t)$ that (2.17) can be written

$$
\begin{equation*}
\varsigma-\beta=\int_{0}^{\chi} d \chi^{\prime} G\left(\psi, \chi^{\prime}, t\right) \equiv F(R, Z, t) \tag{2.52}
\end{equation*}
$$

Clearly, stipulating $\psi$ and $\varsigma-\beta$ yields $R=R(\psi, \varsigma-\beta, t)$ and $Z=Z(\psi, \varsigma-\beta, t)$. Thus (2.39) can be written

$$
\begin{equation*}
J_{2}=\oint d \zeta s_{5}(\psi, \zeta-\beta, t) m w \tag{2.53}
\end{equation*}
$$

where now

$$
\begin{equation*}
\frac{1}{2} m w^{2}=E-V\left(\psi, \varsigma-\beta, J_{1}, t\right) \tag{2.54}
\end{equation*}
$$

Consider the case where there is reflection and $w$ vanishes. Let $\varsigma-\beta=\varsigma_{ \pm}$be the roots of $w=0$ as given by (2.54). Then (2.53) becomes,

$$
\begin{align*}
J_{2} & =2 \int_{\varsigma_{-}+\beta}^{\varsigma_{+}+\beta} d \zeta s_{\varsigma}(\psi, \zeta-\beta, t)\left\{2 m\left[E-V\left(\psi, \zeta-\beta, J_{1}, t\right)\right]\right\}^{1 / 2} \\
& =2 \int_{\varsigma_{-}}^{\varsigma+} d \zeta^{\prime} s_{\varsigma}\left(\psi, \zeta^{\prime}, t\right)\left\{2 m\left[E-V\left(\psi, \zeta^{\prime}, J_{1}, t\right)\right]\right\}^{1 / 2} \tag{2.55}
\end{align*}
$$

where we have introduced $\varsigma^{\prime}=\varsigma-\beta$. Clearly the final integral in (2.55) is independent of $\beta$, and hence so
tnust be $E$. For the case of a circulating paricle orbit one can write

$$
\begin{align*}
J_{2} & =\int_{\varsigma}^{s+\Delta} d \zeta s_{5}(\psi, \zeta-\beta, t)\left\{2 m\left[E-V\left(\psi, \zeta-\beta, J_{1}, t\right)\right]\right\}^{1 / 2} \\
& =\int_{\varsigma-\beta}^{s-\beta+\Delta} d \zeta s_{5}(\psi, \zeta-\beta, t)\left\{2 m\left[E-V\left(\psi, \zeta-\beta, J_{1}, t\right)\right]\right\}^{1 / 2}  \tag{2.56}\\
& =\int_{\varsigma}^{s^{\prime}+\Delta} d \zeta^{\prime} s_{\varsigma}\left(\psi, \zeta^{\prime}, t\right)\left\{2 m\left[E-V\left(\psi, \zeta^{\varsigma}, J_{1}, t\right)\right]\right\}^{1 / 2}
\end{align*}
$$

since the value of the integral over one period of a periodic function does not depend on where one begins the integration. Clearly again $E$ is independent of $\beta$.

Let us now turn to (2.25). To the order of approximation we require it can be written, since $u \approx w$,

$$
\begin{equation*}
\frac{q}{c} \dot{\psi}=-V_{\beta}-w\left(m w b \cdot R_{\beta}\right)_{s} \tag{2.57}
\end{equation*}
$$

and on the right hand side $\psi$ and $\beta$ can be evaluated at the same effective value employed in (2.39) and (2.40). We shall write $\psi=\psi\left(\theta_{2}, t\right), \beta=\beta\left(\theta_{2}, t\right)$ and identify the desired mean values with

$$
\begin{equation*}
\bar{\psi}=\oint d \theta_{2} \psi=\omega_{2} \oint \frac{d s}{w} \psi, \quad \bar{\beta}=\oint d \theta_{2} \beta=\omega_{2} \oint \frac{d s}{w} \beta . \tag{2.58}
\end{equation*}
$$

Recall that the values of $\psi$ and $\beta$ in the integrands in (2.58) are the particle coordinates evaluated on the exact trajectory which includes the effect of drifts. Thus $\bar{\psi}$ and $\bar{\beta}$ are to be interpreted as drift center coordinates. Then (2.57) can be written

$$
\begin{equation*}
\frac{q}{c}\left[\psi_{t}+w_{2} \psi_{O_{2}}\right]=-V_{\bar{\beta}}-w\left(m w b \cdot R_{\bar{\beta}}\right)_{s} \tag{2.59}
\end{equation*}
$$

But $d \theta_{2}=\omega_{2} d s / w$, whence if we average over one period of $\theta_{2}$, since $\omega_{2}$ is independent of $\theta_{2},(2.59)$ yields on using (2.56)

$$
\begin{equation*}
\frac{q}{c} \bar{\psi}_{t}=-\omega_{2} \oint \frac{d s}{w} \frac{\partial V}{\partial \beta}=\omega_{2} \frac{\partial}{\partial \beta} \oint d s m w=0 . \tag{5.60}
\end{equation*}
$$

Hence $\bar{\psi}$ is a particle constant of the motion. We can use (2.15) to express it in terms of $R, Z$ and $v$. To this end note that the average over one period of $\theta_{2}$ of (2.15) yiclds, on setting $u=w$,

$$
\begin{equation*}
P_{5}=\omega_{2} \oint d s m R b \cdot e_{\varsigma}+\frac{q}{c} \bar{\psi} \tag{2.62}
\end{equation*}
$$

on using (2.15) to eliminate $P_{\varsigma}$ onc obtains, since $e_{\varsigma} \cdot v \approx u b \cdot e_{\varsigma}$,

$$
\begin{equation*}
\bar{\psi}=\psi+\frac{m c}{q} R e_{s} \cdot v-\frac{m c}{q} \omega_{2} \oint d s m R b \cdot e_{s} . \tag{2.63}
\end{equation*}
$$

Note that the integral in (2.63) vanishes for the case of a banana orbit, while it tends to cancel the term involving $\boldsymbol{b}$ - $\boldsymbol{o}$ for the circulating particle orbit.

In a parallel fashion (2.24) can be written

$$
\begin{equation*}
\frac{q}{c}\left[\beta_{t}+\omega_{2} \beta_{\theta_{2}}\right]=V_{\psi}+w\left(m w b \cdot R_{\bar{\psi}}\right)_{s} \tag{2.64}
\end{equation*}
$$

which on averaging over $\theta_{2}$ yields

$$
\begin{equation*}
\underline{q}_{c}^{\bar{\beta}_{t}}=\omega_{2} \oint \frac{d s}{w} V_{\bar{\psi}} \tag{2.65}
\end{equation*}
$$

But on differentiating (2.39), the arguments of which are the mean values of $\bar{\psi}$ and $\bar{\beta}$, one gets

$$
\begin{align*}
0 & =\oint \frac{d s}{w} \frac{\partial}{\partial \bar{\psi}} \frac{1}{2} m w^{2} \\
& =\oint \frac{d s}{w}\left[\frac{\partial E}{\partial \bar{\psi}}-\frac{\partial V}{\partial \bar{\psi}}\right] \tag{2.66}
\end{align*}
$$

which in conjunction with (2.40) can be used to write

$$
\begin{equation*}
\frac{q_{\bar{\beta}}^{c}}{}=E_{\bar{\psi}} . \tag{2.67}
\end{equation*}
$$

Define

$$
\begin{align*}
J_{3} & =2 \pi \frac{q}{c} \bar{\psi}  \tag{2.68}\\
\omega_{3} & =\frac{c}{q} \frac{1}{2 \pi} E_{\bar{\psi}} \tag{2.69}
\end{align*}
$$

Then if

$$
\begin{equation*}
H\left(J_{1}, J_{2}, J_{3}, t\right) \equiv E\left(\bar{\psi}, J_{1}, J_{2}, t\right) \tag{2.70}
\end{equation*}
$$

Eq. (2.67) can be written

$$
\begin{equation*}
\frac{\partial H}{\partial J_{3}}=\omega_{3}, \tag{2.71}
\end{equation*}
$$

while (2.69) can be expressed as

$$
\begin{equation*}
\bar{\beta}=2 \pi \theta_{3} \tag{2.72}
\end{equation*}
$$

where

$$
\begin{equation*}
0_{3}=\int d t \omega_{3} . \tag{2.73}
\end{equation*}
$$

Thus if we treat $H$ as a Hamiltonian one has

$$
\begin{equation*}
\dot{J}_{i}=-\frac{\partial H}{\partial \theta_{i}}=0 \quad \dot{\theta}_{i}=\frac{\partial H}{\partial J_{i}} \equiv \omega_{i}\left(J_{1}, J_{2}, J_{3}, t\right) \tag{2.74}
\end{equation*}
$$

where $i=1$ and 2 correspond to (2.50) and (2.51). The high frequency part of $\beta$ can be gotten from (2.64) by neglecting the small term $\beta_{t}$, namely

$$
\begin{align*}
\beta & =\bar{\beta}+\frac{1}{\omega_{2}} \frac{c}{q} \int d \theta_{2}\left[V_{\bar{\psi}}+w\left(m w b \cdot R_{\bar{\psi}}\right)_{s}\right] \\
& =\bar{\beta}+\frac{1}{\omega_{2}} \frac{c}{q} \int \frac{d s}{w}\left[V_{\bar{\psi}}+w\left(m w b \cdot R_{\bar{\psi}}\right)_{s}\right]  \tag{2.75}\\
& =\bar{\beta}+\frac{c}{q} \frac{\partial}{\partial \bar{\psi}} \int^{s} d s m w+\frac{m c}{q} w b \cdot R_{\bar{\psi}}
\end{align*}
$$

Note that to the accuracy required for calculating $\nabla_{v} J_{1}$, following (2.1), (2.4), (2.5), (2.6) and (2.7)

$$
\begin{equation*}
\dot{r}=u b-\Omega \times \rho \tag{2.76}
\end{equation*}
$$

whence one can write

$$
\begin{equation*}
m(b \times \dot{r})^{2}=m \Omega^{2} \rho^{2}=J_{1} \frac{\Omega}{2 \pi} \tag{2.77}
\end{equation*}
$$

Thus on letting $\dot{r}=0$

$$
\begin{equation*}
J_{1}=\frac{2 \pi}{\Omega} \frac{m(b \times v)^{2}}{2} \tag{2.78}
\end{equation*}
$$

and

$$
\begin{equation*}
\nabla_{v} J_{1}=\frac{2 \pi m}{\Omega} b \times(v \times b) \tag{2.79}
\end{equation*}
$$

Also observe that following (2.39)

$$
\begin{align*}
\nabla_{v} J_{2} & =\oint \frac{d s}{w}\left[\nabla_{v} E-\frac{\Omega}{2 \pi} \nabla_{v} J_{1}\right] \\
& =\frac{m}{\omega_{2}}\left[v-\frac{2 \pi \omega_{1}}{\Omega} b \times(v \times b)\right] \tag{2.80}
\end{align*}
$$

since

$$
\begin{equation*}
E=\frac{1}{2} m v^{2}+q\left[U(R, t)+\frac{\psi(R, t)}{c} \frac{\partial \beta(R, t)}{\partial t}\right] \tag{2.81}
\end{equation*}
$$

whence to the required accuracy

$$
\begin{equation*}
\nabla_{\mathrm{t}} E=m v \tag{2.82}
\end{equation*}
$$

For the case of banana orbits it follows from (2.63) and (2.68) that

$$
\begin{equation*}
\nabla_{U} J_{3}=2 \pi m R e_{\varsigma} \tag{2.83}
\end{equation*}
$$

## III. The Collision Term

The conventional neoclassiccal theory is based on Eq. (1.1), as has been remarked. Ultimately, however, one is interested in transport arising from fluctuations of all types, not only that associated with discreteness, but that arising from, for example, low frequency drift wave-type turbulence. This requires a re-examination of the non-equilibrium statistical mechanics underlying the derivation of the collision term which will be considered in a future paper. Here we shall derive an expression for the collision term in action-angle variables by a direct .transformation of variables in the familiar Landau-Fokker-Planck term.

Recall that the collision term can be written

$$
\begin{equation*}
C_{i}^{L}(f)=-\nabla_{v} \cdot \Gamma \tag{3.1}
\end{equation*}
$$

where the current density in velocity space associated with small angle collisions is

$$
\begin{equation*}
\Gamma=-\sum_{\substack{\text { primed } \\ \text { species }}} \frac{2 \pi z^{2} z^{\prime 2} e^{4} l n \Lambda}{m^{2}} \int d^{3} v^{\prime}\left[f^{\prime}\left(r, \gamma^{\prime}, t\right) \nabla_{v} f(r, v, t)-\frac{m}{m^{\prime}} f(r, v, t) \nabla_{v f^{\prime}}\left(r, \gamma^{\prime}, t\right)\right] \cdot \nabla_{v} \nabla_{v}|v-\gamma| \tag{3.2}
\end{equation*}
$$

In (3.2) $f$ bears an implied subscript $i$ and $f^{\prime}$ an implied subscript $i^{\prime}$. On using the chain rule for differentiation

$$
\begin{align*}
\nabla_{v} \cdot \Gamma & =\left(\nabla_{v} J\right): \nabla_{J} \Gamma+\left(\nabla_{v} \theta\right): \nabla_{\theta} \Gamma  \tag{3.3}\\
& =\nabla_{J} \cdot\left[\Gamma \cdot \nabla_{v} J\right]+\nabla_{\theta} \cdot\left[\Gamma \cdot \nabla_{v} \theta\right]-\left[\nabla_{J} \cdot\left(\nabla_{v} J\right)^{T}+\nabla_{\theta} \cdot\left(\nabla_{v} \theta\right)^{T}\right] \cdot \Gamma
\end{align*}
$$

Recall that since the transformation from $r, v$ to $J, \theta$ is canonical the Jacobian of the transformation is unity. But for any non-singular transformation of variables, say from the set $x_{1}, x_{2}, \ldots, x_{N}$ to $y_{1}, y_{2}, \ldots, y_{N}$ one has the identity

$$
\begin{equation*}
\sum_{i=1}^{N} \frac{\partial}{\partial y_{i}}\left[\frac{\partial y_{i}}{\partial x_{j}} \frac{\partial\left(x_{1}, x_{2}, \ldots, x_{v}\right)}{\partial\left(y_{1}, y_{2}, \ldots, y_{v}\right)}\right]=0 \tag{3.4}
\end{equation*}
$$

whence the coefficient of $\Gamma$ on the right-hand side of (3.3) vanishes, and the collision term is of conservation form in action-angle variables.

Now if

$$
\begin{equation*}
\dot{f} \equiv \frac{\partial f}{\partial t}+\dot{v} \cdot \nabla f+\frac{q}{m}\left(E+\frac{v \times B}{c}\right) \cdot \nabla_{v} f \tag{3.5}
\end{equation*}
$$

Eq. (1.1) can be written

$$
\begin{equation*}
\dot{f}+\nabla_{v} \cdot \Gamma=0 \tag{3.6}
\end{equation*}
$$

But on using the chain rule, on transforming to action-angle variables,

$$
\begin{equation*}
\dot{f}=\frac{\partial f}{\partial t}+\dot{J} \cdot \nabla_{J} f+\dot{\theta} \cdot \nabla_{\theta} f \tag{3.7}
\end{equation*}
$$

or since $J$ and $\theta$ evolve according to the Hamiltonian equations

$$
\begin{equation*}
\dot{J}=-\frac{\partial H}{\partial \theta} \quad \dot{\theta}=\frac{\partial H}{\partial J} \tag{3.8}
\end{equation*}
$$

one has

$$
\begin{equation*}
\nabla_{J} \cdot \dot{\boldsymbol{j}}+\nabla_{\theta} \cdot \dot{\theta}=0 \tag{3.9}
\end{equation*}
$$

Thus one can write (3.6) in the two versions

$$
\begin{align*}
0 & =\frac{\partial f}{\partial t}+\dot{J} \cdot \nabla_{J} f+\dot{\theta} \cdot \nabla_{\theta} f+\nabla_{J} \cdot\left[\Gamma \cdot \nabla_{v} J\right]+\nabla_{\theta} \cdot\left[\Gamma \cdot \nabla_{v} \theta\right]  \tag{3.10}\\
& =\frac{\partial f}{\partial t}+\nabla_{J} \cdot\left[-\frac{\partial H}{\partial \theta} f+\Gamma \cdot \nabla_{v} J\right]+\nabla_{\theta} \cdot\left[\frac{\partial H}{\partial J} f+\Gamma \cdot \nabla_{v} \theta\right]
\end{align*}
$$

which latter too is in conservation form.
Suppose

$$
\begin{equation*}
I I(J, \theta, t)=H_{o}(J, t)+H_{1}(J, \theta, t) \tag{3.11}
\end{equation*}
$$

and define

$$
\begin{equation*}
\omega(J, t)=\frac{\partial H_{o}(J, t)}{\partial J} \tag{3.12}
\end{equation*}
$$

Then (3.10) can be expressed as

$$
\begin{equation*}
0=\frac{\partial f}{\partial t}+\omega \cdot \nabla_{\theta} f+\nabla_{J} \cdot\left[-\frac{\partial H_{1}}{\partial \theta} f+\Gamma \cdot \nabla_{v} J\right]+\nabla_{\theta} \cdot\left[\frac{\partial H_{1}}{\partial J} f+\Gamma \cdot \nabla_{v} \theta\right] \tag{3.13}
\end{equation*}
$$

Assume that $\omega_{1}$ is much larger in order of magnitude than any other frequency characterizing the coefficients in (3.13), viz. $\omega_{2}, \omega_{3}$ the collision frequency $\nu=C_{i}^{L}(f) / f, \partial H / \partial J_{2}$,etc. Then one can seek a solution of the form

$$
\begin{equation*}
f=\dot{f}_{0}+f_{1}+f_{2}+\ldots \tag{3.14}
\end{equation*}
$$

where succeeding terms are ordered in inverse powers of $\omega_{1}$. When (3.14) is inserted in (3.13) and one equates terms of like order in $1 / \omega_{1}$ there results

$$
\begin{gather*}
\omega_{1} \frac{\partial f_{0}}{\partial \theta_{1}}=0  \tag{3.15}\\
0=\frac{\partial f_{0}}{\partial t}+\omega_{1} \frac{\partial f_{1}}{\partial \theta_{1}}+\omega_{2} \frac{\partial f_{0}}{\partial \theta_{2}}+\omega_{3} \frac{\partial f_{0}}{\partial \theta_{3}}+\nabla_{J} \cdot\left[-\frac{\partial H_{1}}{\partial 0} f_{0}+\Gamma_{0} \cdot \nabla_{v J}\right]+\nabla_{0} \cdot\left[\frac{\partial H_{1}}{\partial J} f_{0}+\Gamma_{0} \cdot \nabla_{v} \theta\right] \tag{3.16}
\end{gather*}
$$

In (3.16), the subscript zero on $\Gamma$ indicates that one is to use $f_{0}$ in the collision integrals. An equation for $f_{o}$ alone can be obtained from (3.16) by integrating with respect to $\theta_{1}$, from zero to one and invoking the requirement that $f_{1}$ is periodic in $\theta_{1}$ with unit period. Note that the term in the last divergence on the right in (3.16) which involves $\partial / \partial O_{1}$ also vanishes, as docs the term involving $\partial H_{1} / \partial \theta_{1}$, assuming as is usually the case that $H_{1}$ is periodic in $\theta_{1}$ which is effectively the gyration phase.

Let us further assume that $\omega_{2}$ is much greater than the other frequencies and repeat the perturbation theory, and then that either $w_{3}$ is greater than the remaining frequencies or that the system is axisymmetric (in which case the distribution function is independent of $O_{3}$ ) and then repeat the perturbation theory. The final result to lowest significant order in all the several small parameters is

$$
\begin{gather*}
\nabla_{\theta} f=0  \tag{3.17}\\
0=\frac{\partial f}{\partial t}+\nabla_{J} \cdot \oint d^{3} \theta\left[-\frac{\partial H_{1}}{\partial \theta} f+\Gamma \cdot \nabla_{v} J\right] \tag{3.18}
\end{gather*}
$$

where, as will be done henceforth, we have suppressed the subscripts on $f$ indicating the order of approximation. In the axisymmetric case the most important pertrubation is that due to an electric field parallel to $b$ associated with induction by an outside transformer.. Rather than write directly the perturbed Hamiltonian $H_{l}$ it is convenient to note that such an electric field $E_{1}$ enters the original Fokker-Planck equation (1.1) in the form $\nabla \cdot \Gamma_{E}$ where $\Gamma_{E}=q / m E f$ and can be treated in the same fashion as the collisional current $\Gamma$, whence

$$
\begin{align*}
\nabla_{J} \cdot \oint d^{3} \theta\left[-f_{0} \frac{\partial H_{1}}{\partial \theta}\right] & =\nabla_{J} \cdot \oint d^{3} \theta \Gamma_{E} \cdot \nabla_{v} J  \tag{3.19}\\
& \approx \nabla_{J} \cdot\left[\omega_{2} \oint \frac{d s}{u} \frac{q}{m} E_{1} b \cdot \nabla_{v} J\right]
\end{align*}
$$

In order to establish the orders of magnitude of the terms in (3.18) we consider for simplicity an electron proton plasma where correct to lowest order in the ratio of the electron-to-ion mass, one has for the electrons

$$
\begin{align*}
-\Gamma= & \frac{2 \pi e^{4} l n \Lambda}{m^{2}} \int d^{3} v^{\prime}\left(f_{e}^{\prime} \nabla_{v} f_{e}-f_{e} \nabla_{v} f_{e}^{\prime}\right) \cdot \nabla_{v} \nabla_{v}|v-v|  \tag{3.20}\\
& +\frac{2 \pi n e^{-4} \ln \Lambda}{m^{2}}\left\{\left(\nabla_{v} f_{e}\right) \cdot \nabla_{v} \nabla_{v}\left|v-v_{i}\right|+\frac{m}{M} \frac{v-v_{i}}{\left|v-v_{i}\right|^{3}}\left[f_{e}+\frac{T_{i}}{m} \frac{v-v_{i}}{\left|v-v_{i}\right|^{3}} \cdot \nabla_{v} f_{e}\right]\right\}
\end{align*}
$$

and for the protons

$$
\begin{align*}
-\Gamma= & \frac{2 \pi n e^{4} \ln \Lambda}{M^{2}} \int d^{3} v^{\prime}\left(f_{i}^{\prime} \nabla_{v} f_{i}-f_{i} \nabla_{v}, f_{i}^{\prime}\right) \cdot \nabla_{v} \nabla_{v}|v-v|  \tag{3.21}\\
& \quad+\frac{2 \pi n e^{4} \ln \Lambda}{M^{2}}\left\{\frac{2}{3}<\frac{1}{\left|v-v_{\epsilon}\right|}>\nabla_{v} f_{i}+\frac{8 \pi}{3} \frac{M}{m} \frac{f_{\epsilon}\left(v_{i}\right)}{n}\left(v-v_{i}\right) f_{i}\right\}
\end{align*}
$$

where $n$ is the electron density, taken to be cqual to that of the protons $\boldsymbol{v}_{c}$ is the electron mean velocity, $\boldsymbol{v}_{i}$ is the ion mean velocity, and

$$
\begin{equation*}
<\frac{1}{\left|v-v_{e}\right|}>=\frac{1}{n} \int d^{3} v \frac{f_{e}}{\left|v-v_{e}\right|} \quad n T_{i}=\int d^{3} v \frac{m}{2}\left(v-v_{i}\right)^{2} f_{i} \tag{3.22}
\end{equation*}
$$

Eqs. (3.20) and (3.21) conserve both energy and momentum, and vanish when $f_{t}$ and $f_{i}$ are Maxwellian at the same temperature. The terms in $m / M$ in (3.20) and the last terms on the right in (3.21) while necessary for energy and momentum conservation are smaller in order of magnitude than the others in their respective equations and will be neglected for the pupose of order of magnitude estimates. Note that

$$
\begin{align*}
\int d^{3} v^{\prime}\left(\nabla_{v^{\prime}} f^{\prime}\right) \cdot \nabla_{v} \nabla_{v}|v-v| & =\int d^{3} v^{\prime}\left\{f^{\prime} \nabla_{v^{\prime}} \nabla_{v^{\prime}}|v-v|-f^{\prime} \nabla_{v^{\prime}} \nabla_{v^{\prime}}^{2}|v-v|\right\} \\
& =-\int d^{3} v^{\prime} f^{\prime} \nabla_{v^{\prime}} \frac{2}{|v-v|}  \tag{3.23}\\
& =\nabla_{v} \int d^{3} v^{\prime} \frac{f^{\prime}}{\left|v-v^{\prime}\right|}
\end{align*}
$$

and define the symmetric tensors $\boldsymbol{D}$ and vector $\boldsymbol{d}$ via

$$
\begin{align*}
D_{e} & =\oint d^{3} \theta \frac{2 \pi e^{4} l n \Lambda}{m^{2}}\left(\nabla_{v} J\right)^{T} \cdot\left[\nabla_{v} \nabla_{v} \int d^{3} v^{\prime} f_{e}^{\prime}|v-v|+n \nabla_{v} \nabla_{v}\left|v-v_{i}\right|\right] \cdot\left(\nabla_{v} J\right)  \tag{3.24}\\
d_{e} & =-\oint d^{3} \theta \frac{2 \pi e^{4} l n \Lambda}{m^{2}}\left(\nabla_{v} J\right)^{T} \cdot 2 \nabla_{v} \int \frac{d^{3} v^{\prime} f_{e}^{\prime}}{|v-v|}  \tag{3.25}\\
D_{i} & =\oint d^{3} \theta \frac{2 \pi e^{4} l n \Lambda}{M^{2}}\left(\nabla_{v} J\right)^{T} \cdot\left[\nabla_{v} \nabla_{v} \int d^{3} v^{\prime} f_{i}^{\prime}|v-v|\right] \cdot\left(\nabla_{v} J\right)  \tag{3.26}\\
d_{i} & =-\oint d^{3} \theta \frac{2 \pi e^{4} l n \Lambda}{M^{2}}\left(\nabla_{v} J\right)^{T} \cdot 2 \nabla_{v} \int \frac{d^{3} v^{\prime} f_{i}^{\prime}}{|v-v|} \tag{3.27}
\end{align*}
$$

Then for both ions and electrons (3.18) assumes the form

$$
\begin{equation*}
\frac{\partial f}{\partial t}+\nabla_{J} \cdot \oint d^{3} \theta \frac{z e}{m} E \cdot\left(J_{v} J\right) f=\nabla_{J} \cdot\left[D \cdot \nabla_{J} f+d f\right] \tag{3.28}
\end{equation*}
$$

Note that in order of magnitude, or using (2.78) at any seq.

$$
\begin{array}{cc}
J_{1} \approx \frac{m v_{T}^{2}}{\omega_{1}} & \left|\nabla_{v} J_{1}\right| \approx \frac{m v_{T}}{\omega_{1}}
\end{array} \omega_{1} \approx \frac{\Omega}{2 \pi}
$$

$$
J_{3}=2 \pi a m R \Omega_{p} \quad\left|\nabla_{v} J_{3}\right| \approx 2 \pi m R \quad \omega_{3} \approx \frac{v_{T}^{2}}{2 \pi a R \Omega_{p}}
$$

where $R$ is the major radius of the torus, $a$ is the minor radius, $v_{T}$ is a representative thermal speed, and $\Omega_{0}$ is the gyration frequency computed using the poloidal magnetic field. Thus if we write roughly

$$
\begin{equation*}
D \approx\left(\nabla_{v} J\right)^{T} \cdot v_{T}^{2} \nu \cdot\left(\nabla_{v} J\right) \tag{3.30}
\end{equation*}
$$

where for electrons

$$
\begin{equation*}
\nu \approx \frac{2 \pi n e^{4} \ln \Lambda}{m^{2} v_{e T}^{3}} \tag{3.31}
\end{equation*}
$$

and for ions

$$
\begin{equation*}
\nu \approx \frac{2 \pi n e^{4} l n \Lambda}{M^{2} v_{i T}^{3}} \tag{3.32}
\end{equation*}
$$

it is readily seen that

$$
\begin{aligned}
& \frac{\partial}{\partial J_{1}}\left(D_{11} \frac{\partial f}{\partial J_{1}}\right): \frac{\partial}{\partial J_{2}}\left(D_{12} \frac{\partial f}{\partial J_{2}}\right): \frac{\partial}{\partial J_{1}}\left(D_{13} \frac{\partial f}{\partial J_{3}}\right): \frac{\partial}{\partial J_{2}}\left(D_{22} \frac{\partial f}{\partial J_{2}}\right): \frac{\partial}{\partial J_{2}}\left(D_{23} \frac{\partial f}{\partial J_{3}}\right): \frac{\partial}{\partial J_{3}}\left(D_{33} \frac{\partial f}{\partial J_{3}}\right) \\
& \approx 1: 1: \frac{\rho_{p}}{a}: 1: \frac{\rho_{p}}{a}:\left(\frac{\rho_{p}}{a}\right)^{2}
\end{aligned}
$$

where $\rho_{p}=v_{r} / \Omega_{p}$ is the mean gyration radius in the poloidal magnetic field. Similary, in order of magnitude

$$
\begin{equation*}
d=\left(\nabla_{v} \eta^{T} \cdot \boldsymbol{v}_{T} \nu_{e}\right. \tag{3.33}
\end{equation*}
$$

whence

$$
\begin{equation*}
\frac{\partial\left(d_{1} f\right)}{\partial J_{1}}: \frac{\partial\left(d_{2} f\right)}{\partial J_{2}}: \frac{\partial\left(d_{3} f\right)}{\partial J_{3}}=1: 1: \frac{\rho_{p}}{a} \tag{3.34}
\end{equation*}
$$

For the purpose of a transport theory one requires a cero-order distribution function for which the dominant part of the collision term vanishes, namely that part zero order in $\rho_{p} / a$, and also in $m / M$. To illustrate this determination it is convenient to consider the ions and write

$$
\begin{equation*}
a=\frac{2 \pi e^{4} \ln \Lambda}{M^{2}} \int d^{3} v^{\prime}\left(f^{\prime} \nabla_{v} f-f \nabla_{v} f^{\prime}\right) \cdot \nabla_{v} \nabla_{v}|v-\vartheta| \tag{3.35}
\end{equation*}
$$

in terms of which the collisional current density in $J$ space, including for this purpose only the self-collision contributions, is $-\nabla \cdot \Gamma$ with

$$
\begin{equation*}
-\Gamma=\int d^{3} \theta\left(\nabla_{v} d\right) \cdot a \tag{3.36}
\end{equation*}
$$

and with $f=f(J, t)$. Note too that to the order of accuracy we require the components of $J$ viewed as functions of $v$ depend on $u=b \cdot v$ and $w=|b \times v|$ but not on the gyro-phase $\phi$. Moreover, on using the chain rule

$$
\begin{align*}
\nabla_{v} f= & \left(\nabla_{v} J_{1}\right) \frac{\partial f}{\partial J_{1}}+\left(\nabla_{v} J_{2}\right) \frac{\partial f}{\partial J_{2}}+\left(\nabla_{v} J_{3}\right) \frac{\partial f}{\partial J_{3}} \\
= & \frac{2 \pi m b \times(v \times b) \frac{\partial f}{\partial J_{1}}+m \omega_{2}\left[v-\frac{2 \pi \omega_{1}}{\Omega} b \times(v \times b)\right] \frac{\partial f}{\partial J_{2}}}{\Omega}  \tag{3.37}\\
& +\left[m R e_{5}+\ldots\right] \frac{\partial f}{\partial J_{3}}
\end{align*}
$$

Using the estimates of (3.29) it is evident that to lowest order in $\rho_{p} / a$ one can neglect the last term on the right in (3.37) whence on using $J_{1}^{\prime}, J_{2}^{\prime}$, and $\phi^{\prime}$ as variables in (3.35) one can write

$$
\begin{align*}
a== & \frac{2 \pi e^{4} \ln \Lambda}{M^{2}} \int d J_{1}^{\prime} d J_{2}^{\prime} d \phi^{\prime} \frac{\partial(u, w)}{\partial\left(J_{1}^{\prime}, J_{2}^{\prime}\right)}\left[\nabla_{v} \nabla_{v}|v-\vartheta|\right] \\
& \cdot\left[\left(\nabla_{v} J_{1}\right) \frac{\partial}{\partial J_{1}} f f^{\prime}+\left(\nabla_{v} J_{2}\right) \frac{\partial}{\partial J_{2}} f f^{\prime}\right.  \tag{3.38}\\
& \left.-\left(\nabla_{v^{\prime}} J_{1}^{\prime}\right) \frac{\partial}{\partial J_{1}^{\prime}} f f^{\prime}-\left(\nabla_{v} J_{2}^{\prime}\right) \frac{\partial}{\partial J_{2}^{\prime}} f f^{\prime}\right]
\end{align*}
$$

If we require that to lowest order in $\rho_{p} / a$ that the collision term vanish, viz

$$
\begin{equation*}
0=\frac{\partial}{\partial J_{1}} \oint d^{3} \theta a \cdot \nabla_{v} J_{1}+\frac{\partial}{\partial J_{2}} \oint d^{3} \theta a \cdot \nabla_{v} J_{2} \tag{3.39}
\end{equation*}
$$

then on multiplication by inf integration over $J_{1}$ and $J_{2}$. and an obvious integration by parts, one obtains

$$
\begin{align*}
0=\int & d^{3} \theta d J_{1} d J_{2} d J_{1}^{\prime} d J_{2}^{\prime} d \phi^{\prime} f^{\prime} f^{\prime}\left\{\left[\frac{\partial \ln f}{\partial J_{1}}\left(\nabla_{v} J_{1}\right)+\frac{\partial \ln f}{\partial J_{2}}\left(\nabla_{v} J_{2}\right)\right] \cdot\left[\nabla_{v} \nabla_{v}|v-v|\right]\right. \\
\cdot & {\left[\left(\nabla_{v} J_{1}\right) \frac{\partial \ln f}{\partial J_{1}}+\left(\nabla_{v} J_{2}\right) \frac{\partial \ln f}{\partial J_{2}}-\left(\nabla_{v} J_{1}^{\prime}\right) \frac{\partial \ln f^{\prime}}{\partial J_{1}^{\prime}}-\left(\nabla_{v^{\prime}} J_{2}^{\prime}\right) \frac{\partial \ln f^{\prime}}{\partial J_{2}^{\prime}}\right] } \tag{3.40}
\end{align*}
$$

where it is assumed that the boundary conditions are such that all surface terms arising from the integration by parts vanish. Note that

$$
\begin{equation*}
\nabla_{v} \nabla_{v}|v-v|=\frac{(v-v)^{2} I-(v-v)(v-v)}{|v-v|^{3}} \tag{3.41}
\end{equation*}
$$

and define

$$
\begin{align*}
C & =\left(\nabla_{v} J_{1}\right) \frac{\partial \ln f}{\partial J_{1}}+\left(\nabla_{v} J_{2}\right) \frac{\partial \operatorname{lnf}}{\partial J_{2}}-\left(\nabla_{v} J_{1}^{\prime}\right) \frac{\partial \ln f^{\prime}}{\partial J_{1}}-\left(\nabla_{v^{\prime}} J_{2}^{\prime}\right) \frac{\partial \ln f^{\prime}}{\partial J_{2}^{\prime}} \\
& =\left(\nabla_{v} \ln f-\nabla_{v^{\prime}} \ln f^{\prime}\right)_{J_{3}}=\mathrm{const} \tag{3.42}
\end{align*}
$$

Then if in (3.40) we interchange $J_{1}$ and $J_{2}$ with $J_{1}^{\prime}$ and $J_{2}^{\prime}$, etc., and add half the result to (3.40), there emerges

$$
\begin{equation*}
0=\int d^{3} \theta d J_{1} d J_{2} d J_{1}^{\prime} d J_{2}^{\prime}[(v-v) \times c]^{2}|v-v|^{-3} \tag{3.43}
\end{equation*}
$$

Now it follows from (2.78) and (2.80) that

$$
\begin{equation*}
v=\frac{\omega_{2}}{M} \nabla_{v} J_{2}+\frac{\omega_{1}}{M} \nabla_{v} J_{1} \tag{3.44}
\end{equation*}
$$

Thus the requirement that

$$
\begin{equation*}
(v-v) \times C=0, \tag{3.45}
\end{equation*}
$$

which follows from (3.43), implics that

$$
\begin{align*}
0= & \left(\omega_{2} \nabla_{v} J_{2}+\omega_{1} \nabla_{v} J_{1}-\omega_{2}^{\prime} \nabla_{v^{\prime}} J_{2}^{\prime}-\omega_{1}^{\prime} \nabla_{v} J_{1}^{\prime}\right) \\
& \times\left[\left(\nabla_{\imath} J_{1}\right) \frac{\partial \ln f}{\partial J_{1}}+\left(\nabla_{\imath} J_{2}\right) \frac{\partial \ln f}{\partial J_{2}}-\left(\nabla_{v^{\prime}} J_{1}^{\prime}\right) \frac{\partial l n f^{\prime}}{\partial J_{1}^{\prime}}-\left(\nabla_{\imath} J_{2}^{\prime}\right) \frac{\partial \ln f^{\prime}}{\partial J_{2}^{\prime}}\right] \tag{3.46}
\end{align*}
$$

In (3.45) set $J_{1}^{\prime}$ and $J_{2}^{\prime}$ to zero which implies that $\nabla_{v} J_{1}^{\prime}$ and $\nabla_{v} J_{2}^{\prime}$ also vanish. Then (3.45) reduces to

$$
\begin{equation*}
\left(\nabla_{v} J_{1}\right) \times\left(\nabla_{v} J_{2}\right)\left(\omega_{1} \frac{\partial \ln f}{\partial J_{2}}-\omega_{2} \frac{\partial \ln f}{\partial J_{1}}\right)=0 \tag{3.47}
\end{equation*}
$$

Since in general the cross produce in (3.47) does not vanish one must have since $\omega_{1}=\partial H_{0} / \partial J_{1}, \omega_{2}=\partial H_{0} / \partial J_{2}$

$$
\begin{equation*}
\frac{\partial H_{o}}{\partial J_{1}} \frac{\partial f}{\partial J_{2}}-\frac{\partial H_{o}}{\partial J_{2}} \frac{\partial f}{\partial J_{1}}=0 \tag{3.48}
\end{equation*}
$$

whence

$$
\begin{equation*}
f=f\left(H_{0}, J_{3}\right) \tag{3.49}
\end{equation*}
$$

The $J_{3}$ dependence arises from the fact that all the manipulations leading to (3.48) were carried out at fixed $J_{3}$. If we return to (3.45), since $\nabla_{v} H_{0}=m v$ we can write

$$
\begin{align*}
0 & =(v-v) \cdot\left(\nabla_{v} \ln f-\nabla_{v} l n f^{\prime}\right)_{J_{3}=\text { const }} \\
& =(v-v) \cdot\left(m v \frac{\partial \ln f}{\partial H_{o}}-m v \frac{\partial \operatorname{lnf^{\prime }}}{\partial H_{o}^{\prime}}\right)  \tag{3.50}\\
& =m(v-v)\left(\frac{\partial \operatorname{lnf}}{\partial H_{o}}-\frac{\partial \ln f^{\prime}}{\partial J_{o}^{\prime}}\right)
\end{align*}
$$

whence

$$
\begin{equation*}
\frac{\partial \operatorname{lnf}}{\partial H_{o}}=\frac{\partial \operatorname{lnf}}{\partial H_{o}}=\text { const }=\frac{1}{T\left(J_{3}\right)} \tag{3.51}
\end{equation*}
$$

and

$$
\begin{equation*}
f=N\left(J_{3}\right) e^{-H_{0} / T\left(J_{3}\right)} \tag{3.52}
\end{equation*}
$$

This is, effectively, the reduced $H$-theorcom (at constant $J_{3}$ ) needed to begin a transport theory.

## IV. Formal Structure of the Transport Theory

We consider now the approximate solution of Eq. (1.3) to obtain the transport $\pi \pi$ relations. For simplicity, we take one species (electrons), and employ the Lorentz approximation collision operator, where $C_{e e}$ is neglected, and the $m_{i} \rightarrow \infty$ limit of $C_{e i}$ is used. The generalizations required to remove these approximations are involved and important, but the formal structure of the theory is identical in the more general case. The limit considered is thus

$$
\begin{equation*}
\frac{\partial f}{\partial t}+\frac{\partial}{\partial J} \cdot\left[\frac{q}{2 \pi} a\left(\partial V_{T} f\right]=C(f)\right. \tag{4.1}
\end{equation*}
$$

where,

$$
\begin{equation*}
C(f)=\frac{\partial}{\partial J} \cdot\left[D(J) \cdot \frac{\partial}{\partial J} f\right], \tag{4.2}
\end{equation*}
$$

and $D(J)$ is the symmetric, positive definite tensor, obtained by letting $m_{i} \rightarrow \infty$ in equation (3.20).
The approximation scheme is based on the smallness of the $J_{3}$ derivatives, and this, in turn requires that $J_{3}$ be radial in the sense discussed in Sec. I. Velocity scattering, involving $J_{1}$ and $J_{2}$, dominates and forces $f$ to be a local Maxwellian in leading order. The slower scatterings in radius produce the transport. For example, since
 the derivatives with respect to $J_{3}$ to scale like $\rho_{p} / a$. In fact, we have shown explicitly (Sec. III) that the collision operator orders in $\rho_{p} / a$ according to the number of $J_{3}$ derivatives. To achieve a maximal ordering, $V_{T}$ is treated as $O\left(\rho_{p} / a\right)$ and $\partial f / \partial t$ as $O\left(\left(\rho_{p} / a\right)^{2}\right)$. Then the. Ohmic dissipation and thermal conductivity appear together at second order along with the transport equations. The basic expansion is identical to that used previously [12] to assess the effect of finite beta drift wave turbulence [13] on the electron distribution function.

The collision operator is therefore expanded in powers of $\rho_{p} / a$, namely

$$
\begin{align*}
C(f)= & \frac{\partial}{\partial J} \cdot\left[D \cdot \frac{\partial}{\partial J} f\right]=C_{0}(f)+C_{1}(f)+C_{2}(f)=\frac{\partial}{\partial J} \cdot\left[D_{0} \cdot \frac{\partial}{\partial J} f\right] \\
& +\frac{\partial}{\partial J} \cdot\left[D_{1} \cdot \frac{\partial}{\partial J} f\right]+\frac{\partial}{\partial J} \cdot\left[D_{2} \cdot \frac{\partial}{\partial J} f\right] \tag{4.3}
\end{align*}
$$

where,

$$
\begin{align*}
& D_{1}=D_{11} e_{1} e_{1}+D_{12}\left(e_{1} e_{2}+e_{2} e_{1}\right)+D_{22} e_{2} e_{2} \\
& D_{1}=D_{13}\left(e_{1} e_{3}+e_{3} e_{1}\right)+D_{23}\left(e_{2} e_{3}+e_{3} e_{2}\right) \\
& D_{2}=D_{33} e_{3} e_{33} \tag{4.4}
\end{align*}
$$

and $e_{1}, e_{2}, e_{3}$ are an orthonormal set of cartesian unit vectors such that $J=J_{1} e_{1},+J_{2} e_{2}+J_{3} e_{3}$. We will also use the conventions

$$
\begin{equation*}
e_{\perp}=e_{1}+e_{2} ; \quad \partial / \partial J_{\perp}=e_{1} \partial / \partial J_{1}+e_{2} \frac{\partial}{\partial J_{2}} \tag{4.5}
\end{equation*}
$$

so that $C_{0}$ can be written $C_{0}=\partial / \partial J_{\perp} \cdot D_{0} \cdot \partial / \partial J_{\perp}$. In a similar way the electric field operator separates into a first order part, $\partial / \partial J_{\perp} \cdot \frac{q}{2 \pi} a(\eta) V_{T} f$, and second order part, $\partial / \partial J_{3} \frac{q}{2 \pi} a_{3} V_{T} f$. The latter describes an explicit radial flow driven by the electric field and independent of the existence of collisions. This is Ware's original effect [4]. It appears directly in the action-angle (Lagrangian) formulation. In the first order part we assume (and later show) that $a_{\perp}(J)=a_{2}(J) e_{2}$, and $\partial / \partial J_{\perp} \cdot a_{2}=\partial / \partial J_{2} a_{2}=0$. Thus, the energy moment becomes

$$
\int d^{2} J_{\perp} H_{0}(J) \frac{\partial}{\partial J_{\perp}} \cdot \frac{q}{2 \pi} a_{\perp} V_{T} f=-V_{T} \int d^{2} J_{\perp} \frac{q}{2 \pi} a_{2} \omega_{2} f
$$

Since the energy moment of the electric field term must, in general, give the Ohmic power input, we may infer that this last integral gives toroidal current per unit $J_{3}$, and thus define,

$$
\begin{equation*}
I_{T}^{i}=\int d^{2} J_{\perp} \frac{q}{2 \pi} a_{2}\left(J \omega_{2}(J) f\right. \tag{4.6}
\end{equation*}
$$

A direct calculation of the bounce averaged toroidal current, when expressed in terms of the actions, yields the same expression (Sec. V).

Following this ordering of the kinctic equation, we expand $f$ in powers of $\rho_{p} / a$. The zero order equation is,

$$
\begin{equation*}
0=C_{o}\left(f_{o}\right) \tag{4.7}
\end{equation*}
$$

It is at this point that a judicious choice of the actions (i.e., $J_{3}$ radial such that $\omega_{3}=\partial H_{o} / \partial J_{3}$ is small) becomes necessary to solve Eq. (4.7). Then the reduced H-theorem of the previous section applies and we conclude that $f_{o}$ must be a local Maxwellian $f_{o}=f_{m} \equiv N\left(J_{3}\right) \exp \left(-H_{o}(J) / T\left(J_{3}\right)\right)$.

For reasons that will be clear shortly, we normalize $f_{n}$ as follows:

$$
\begin{equation*}
f_{0}=f_{m} \equiv n(2 \pi m T)^{-3 / 2} \exp \left(-H_{o} / T\right) \tag{4.8}
\end{equation*}
$$

where $n$, a density per unit spatial volume, is related to $n_{3}$ by

$$
\begin{equation*}
n=n_{3} \partial J_{3} / \partial V=n_{3} 2 \pi \frac{q}{c} \partial \psi / \partial V \tag{4.9}
\end{equation*}
$$

where $V$ is the volume interior to a flux surface $\psi=$ const. . The relation between $\boldsymbol{n}$ and the observed density is detailed in Sec. V.

Having solved Eq. (4.8), we proceed to the first order equation

$$
\begin{equation*}
\frac{\partial}{\partial J_{\perp}} \cdot\left[\frac{q}{2 \pi} V_{T} a_{\perp}(J) f_{0}\right]-\frac{\partial}{\partial J} \cdot\left[D_{1} \cdot \frac{\partial}{\partial J} f_{0}\right]=C_{o}\left(f_{1}\right) \tag{4.10}
\end{equation*}
$$

Noting that $D_{1}$ can be written as a scalar times the tensor [see Eq. (5.31)],

$$
\begin{equation*}
\left(-\frac{1}{\omega_{1}} e_{1}+\frac{1}{\omega_{2}} e_{2}\right) e_{3}+e_{3}\left(-\frac{1}{\omega_{1}} e_{1}+\frac{1}{\omega_{2}} e_{2}\right), \tag{4.11}
\end{equation*}
$$

the second term on the left side of Eq. (4.11) becomes,

$$
\begin{align*}
\frac{\partial}{\partial J} \cdot D_{1} \cdot \frac{\partial}{\partial J} f_{0} & =-\frac{\partial}{\partial J} \cdot D_{1} \cdot \omega_{\perp} \frac{f_{0}}{T} \\
& +\frac{\partial}{\partial J_{\perp}} \cdot\left(D_{1} \cdot e_{3} \frac{\partial f_{0}}{\partial J_{3}}\right)=\left(\frac{\partial}{\partial J_{\perp}} \cdot D_{1} \cdot e_{3}\right) \frac{\partial f_{0}}{\partial J_{3}}, \tag{4.12}
\end{align*}
$$

The electric field term, using the properties of the function $a(J)$ can be expressed in the alternate form,

$$
\begin{equation*}
\frac{\partial}{\partial J_{\perp}} \cdot \frac{q}{2 \pi} V_{T} \cdot a_{\perp} f_{0}=\frac{q}{2 \pi} V_{T} a_{2} \frac{\partial f_{0}}{\partial J_{2}}=-\frac{V_{T}}{T} \frac{q}{2 \pi} a_{2} \omega_{2} f_{0} . \tag{4.13}
\end{equation*}
$$

Using these propertics, the first order equation can be written as either

$$
\begin{equation*}
C_{0}\left(f_{1}\right)=\frac{\partial}{\partial J_{\perp}} \cdot \frac{q}{2 \pi} a_{\perp} V_{T} f_{0}-\frac{\partial}{\partial J_{\perp}} \cdot\left(D_{1} \cdot e_{3} \frac{\partial f_{0}}{\partial J_{3}}\right), \tag{4.14}
\end{equation*}
$$

or

$$
\begin{equation*}
\left.C_{0}\left(f_{1}\right)=-\frac{q}{2 \pi} a_{2} \omega_{2} f_{0} \frac{V_{T}}{T}-\left(\frac{\partial}{\partial J_{\perp}} \cdot D_{1} \cdot e_{3}\right) \frac{\partial f_{0}}{\partial J_{3}}\right) . \tag{4.15}
\end{equation*}
$$

Inversion of the collision operator, $C_{0}$, is now required to determine $f_{1}$, subject to certain integrability conditions. In the present formulation these conditions are trivially satisficd, as we now show.

The integrability conditions are determined by the annihilators of $C_{0}$, in this case the particle and energy moments. It is evident that the particle moment. $\int d^{2} J_{\perp}$, also annihilates the source terms from I:q. (4.14). For the energy moment, we compute $\int d^{2} J_{\perp} H_{0}(J)$, from Eq. (4.14), and integrate the right side by parts. There
results the condition,

$$
0=-\int d^{2} J_{\perp} \frac{q}{2 \pi} a_{2} \omega_{2} f_{0} V_{T}+\int d^{2} J_{\perp} \omega_{\perp} \cdot D_{1} \cdot e_{3} \frac{\partial f_{0}}{\partial J_{3}} .
$$

The first term vanishes since the equilibrium distribution, $f_{0}$, carries no current in the sense of Eq. (4.6). Using form (4.11) for $D_{1}$, the second term is zero.

For use in the ensuing transport equations, it is convenient to express the driving terms for $f_{1}$ in terms of thermodynamic forces $A_{i}$,

$$
\begin{align*}
& A_{1}=d \ln n / d J_{3} \\
& A_{2}=d \ln T / d J_{3}  \tag{4.16}\\
& A_{3}=V_{T} / T .
\end{align*}
$$

Using form (4.8) for $f_{0}$, the first order Eq.. (4.15) becomes $C_{0}\left(f_{1}\right)=a_{1} f_{0} A_{1}+a_{2} f_{0} A_{2}+a_{3} f_{0} A_{3}$, where the coefficients $a_{i}$, are given by

$$
\begin{align*}
& \alpha_{1}=-\frac{\partial}{\partial J_{\perp}} \cdot\left[D_{1} \cdot e_{3}\right] \\
& \alpha_{2}=-\frac{\partial}{\partial J_{\perp}} \cdot\left[D_{1} \cdot e_{3}\left(\frac{H_{0}}{T}-\frac{3}{2}\right)\right]  \tag{4.18}\\
& a_{3}=-\frac{q}{2 \pi} a_{2} \omega_{2} .
\end{align*}
$$

Finally, defining the individual responses, $g_{i}$, according to,

$$
\begin{equation*}
C_{0}\left(g_{i}\right)=a_{i} f_{0} \tag{4.19}
\end{equation*}
$$

$f_{1}$ can be expressed as a sum over the thermodynamic forces,

$$
\begin{equation*}
f_{1}=\sum_{i} g_{i} A_{i} . \tag{4.20}
\end{equation*}
$$

These relations are useful for writing the transport equations in a compact form and for proving Onsager symmetry of the transport coefficients.

To second order in $\rho_{p} / a$, Eq. (4.1) becomes,

$$
\begin{equation*}
\frac{\partial f_{0}}{\partial t}+\frac{\partial}{\partial J_{3}} \frac{q}{2 \pi} a_{3}(J) f_{0} V_{T}+\frac{\partial}{\partial J_{\perp}} \cdot \frac{q}{2 \pi} a_{\perp}\left(J_{)} f_{1} V_{T}-C_{1}\left(f_{1}\right)-C_{2}\left(f_{0}\right)=C_{0}\left(f_{2}\right) .\right. \tag{4.21}
\end{equation*}
$$

The integrability conditions for the solution of $f_{2}$ now provide the transport equations. Accordingly, although the transport equations themselves are second order, they require knowledge of $f$ only through first order.

The particle moment of (4.21) is,

$$
\begin{aligned}
\frac{\partial}{\partial t} n_{3} & +\frac{\partial}{\partial J_{3}}\left[\int d^{2} J_{\perp} \frac{q}{2 \pi} a_{3} f_{0} V_{T}-\int d^{2} J_{\perp} e_{3} \cdot D_{1} \cdot \frac{\partial}{\partial J_{\perp}} f_{1}\right. \\
& \left.-\int d^{2} J_{\perp} D_{33} \frac{\partial f_{0}}{\partial J_{3}}\right]=0
\end{aligned}
$$

The second term in brackets can be integrated by parts,

$$
\begin{aligned}
-\int d^{2} J_{\perp} e_{3} \cdot D_{1} \cdot \frac{\partial}{\partial J_{\perp}} f_{1} & =\int d^{2} J_{\perp} f_{1} \frac{\partial}{\partial J_{\perp}} \cdot\left(e_{3} \cdot D_{1}\right)^{t} \\
& =\int d^{2} J_{\perp} f_{1} \frac{\partial}{\partial J_{\perp}} \cdot D_{1} \cdot e_{3}=-\int d^{2} J_{\perp} a_{1} f_{1}
\end{aligned}
$$

using the symmetry of $D_{1}$ and the definition (4.18), to give,

$$
\begin{equation*}
\frac{\partial n_{3}}{\partial t}+\frac{\partial}{\partial J_{3}}\left[\int d^{2} J_{\perp} \frac{q}{2 \pi} a_{3} f_{0} V_{T}-\int d^{2} J_{\perp} a_{1} f_{1}-\int d^{2} J_{\perp} D_{33} \frac{\partial f_{0}}{\partial J_{3}}\right]=0 \tag{4.22}
\end{equation*}
$$

This is in the form of transport Eq. (1.5), with the flux, $\Gamma$, being proportional to the thermodynamic forces, $A_{i}$. Note that the thermodynamic force, $A_{1}$, is defined in terms of the spatial number density, $n$, while the transport equation itself is expressed per unit $J_{3}$. The reason for this and its relation to the flux surface average of the conventional Eulerian theory, will be given in Sec. V. We then define transport coefficients, $T_{1 i}$, as in Eq. (1.7), as follows,

$$
\begin{equation*}
\Gamma=T_{11} \frac{d \ln n}{d J_{3}}+T_{12} \frac{d \ln T}{d J_{3}}+T_{13} \frac{V_{T}}{T} \tag{4.23}
\end{equation*}
$$

We use an inner product notation, $(g, h) \equiv \int d^{2} J_{\perp} g h$, to write the coefficients. The second term in (4.22), by virtue of Eqs. (4.19) and (4.20), yields implicit contributions of the form $T_{1 j}^{i}=-\left(\alpha_{1}, g_{j}\right)$. In addition, there are explicit contributions to the flow that do not require the calculation of $f_{1}$. We denote these by $T_{1 j}^{e}$. Collecting terms, the particle transport coefficients, $T_{1}$, become,

$$
\begin{align*}
& T_{11}=\left(-D_{33}, f_{0}\right)-\left(a_{1}, g_{1}\right)=T_{11}^{e}+T_{11}^{i} \\
& T_{12}=\left(-D_{33}, f_{0}\left(\frac{H_{0}}{T}-\frac{3}{2}\right)\right)-\left(a_{1}, g_{2}\right)=T_{12}^{e}+T_{12}^{i}  \tag{4.24}\\
& T_{13}=\left(\frac{q T}{2 \pi} a_{3}, f_{0}\right)-\left(a_{1}, g_{3}\right)=T_{13}^{e}+T_{13}^{i}
\end{align*}
$$

The cocfficient, $T_{11}$, is the particle diffusion cocfficient, appropriately normalized, and contains both explicit and implicit parts. Coefficient $T_{13}$ implies a radial flow driven by the toroidal voltage, the pinch effect. The
explicit.part of $T_{13}$ arises from the second term in Eq. (4.21) and is entirely independent of the existence of collisions.

The procedure for obtaining the energy transport equation from the energy moment of Eq. (4.21) is similar. The first order term in the electric field now contributes to give Ohmic heating. The energy transport equation is in the form (1.6), with the heat flux,

$$
\begin{equation*}
q / T=T_{21} \frac{d \ln n}{d J_{3}}+T_{22} \frac{d \ln n}{d J_{3}}+T_{32} V_{T} / T \tag{4.25}
\end{equation*}
$$

The transport coefficients are again decomposed into implicit and explicit parts, as

$$
\begin{align*}
& T_{21}=\left(-D_{33}, f_{0}\left(\frac{H_{0}}{T}-\frac{3}{2}\right)\right)-\left(a_{2}, g_{1}\right)=T_{21}^{e}+T_{21}^{i} \\
& T_{22}=\left(-D_{33}, f_{0}\left(\frac{H_{0}}{T}-\frac{3}{2}\right)^{2}\right)-\left(a_{2}, g_{2}\right)=T_{22}^{e}+T_{22}^{i}  \tag{4.26}\\
& T_{23}=\left(\frac{q T}{2 \pi} a_{3}, f_{0}\left(\frac{H_{0}}{T}-\frac{3}{2}\right)\right)-\left(a_{2}, g_{3}\right)=T_{23}^{e}+T_{23}^{i}
\end{align*}
$$

Finally the toroidal current, $I_{T}^{i}$, appearing in the Ohmic heating term $I_{T}^{i} V_{T}$, of Eq. (1.6), can also be expressed as a flux driven by the thermodynamic forces

$$
\begin{equation*}
I_{T}^{i}=T_{31}^{i} \frac{d \ln n}{d J_{3}}+T_{32}^{i} \frac{d \ln T}{d J_{3}}+T_{33}^{i} V_{T} / T \tag{4.26}
\end{equation*}
$$

where the transport coefficients in Eq. (4.26) are only of the implicit type,

$$
\begin{align*}
& T_{31}^{i}=-\left(a_{3}, g_{1}\right) \\
& T_{32}^{i}=-\left(a_{3}, g_{2}\right)  \tag{4.27}\\
& T_{33}^{i}=-\left(a_{3}, g_{3}\right) .
\end{align*}
$$

When the equilibrium Hamiltonian, $H_{0}(J)$, is known, transport equations (1.5) and (1.6), together with the coefficients (4.24), (4.26), and (4.28) are a closed system evolving the density and temperature. The particle density and toroidal current are expressed naturally per unit $J_{3}$ in this representation. However, the Hamiltonian, . $H_{0}(\eta)$, depends implicitly on the magnetic ficld. This requires knowledge of the toroidal current density in real space and includes a diamagnetic contribution in addition to $I_{T}^{i}$. Were it not for this circumstance the real space densities would never be needed in the transport theory. The appearance of $n$ in the thermodynamic force, $A_{1}$, is a consequence of the normalization (4.8) and not fundamental.

The term, $I_{7}^{i}$, defined by Eq. (4.6), was not derived as an electric current but was interpreted as such from the form of the Ohmic heating term in the energy equation. In addition to this dissipative current, there are
diamagnetic currents, $I_{T}^{e}$, for which no work is done by the external voltage. This is shown in Sec. V, where the spatial toroidal current density is computed. The flux surface averaged current, to first order in the gyroradius has an implicit piece, as given by Eq. (4.26) and an explicit piece in the form

$$
\begin{equation*}
I_{T}^{e}=T_{31}^{e} \frac{d \ln n}{d J_{3}}+T_{32}^{e} \frac{d \ln T}{d J_{3}} \tag{4.28}
\end{equation*}
$$

Onsager symmetry is immediately apparent for the implicit coefficients, $T_{i j}^{i}$, using their inner product form and the self-adjointness of $C_{0}$. Thus, noting that,

$$
\begin{equation*}
-T_{i j}^{i}=\left(\alpha_{i}, g_{j}\right)=\left(C_{0}\left(g_{i}\right), g_{j}\right)=\left(g_{i}, C_{0}\left(g_{i}\right)\right)=\left(\alpha_{j}, g_{i}\right)=-T_{j i}^{i} \tag{4.30}
\end{equation*}
$$

proves the symmetry. This property is a direct result of the symmetry of the full diffusion tensor, $\boldsymbol{D}$. The symmetry of $D_{1}$ leads to the inner product form for the implicit fluxes and the symmetry of $D_{0}$ makes $C_{0}$ selfadjoint.

The symmetry of the explicit fluxes $T_{12}^{e}$ and $T_{21}^{e}$ is evident by inspection of Eqs. (4.24) and (4.26). The explicit symmetry between the pinch coefficients $T_{13}^{e}$ and $T_{23}^{e}$, and the (diamagnetic) bootstrap current coefficients $T_{31}^{e}$ and $T_{32}^{e}$ will be shown and interpreted in detail in Sec. $V$.

## V. Transport Theory for the Lorentz Model Axisymmetric Torus

In this section we illustrate the formal theory developed in Secs. I - IV by evaluating the transport coefficients and by comparing the Lagrangian and conventional Eulerian representations.

The kinetic equation then, in the $x, v$ variables, is just Eq. (1.1). The form (1.3) used in the Lagrangian formulation can be obtained from Eq. (1.1) by simply changing variables to $J, \theta$ and averaging over the angles as shown in Sec. III. Since they commence from the same equation, the two representations must then be equivalent. Demonstrating this equivalence, however, is not straightforward, because of the basic differences in theoretical structure. Moreover, these formal structural differences have some interesting physical interpretations with evident implications for future developments.

## A. Normalization, Moments, Relation to Flux Surface Average.

In the formal theory of Sec. IV, quantities such as particle number and energy are naturally expressed as densities per unit of action, $J_{3}$, and arise as reduced moments such as, $n_{3}=\int d J_{1} d J_{2} f$. The conventional (Eulerian) representation uses spatial densities, such as $n$, and expresses the transport equations in terms of flux surface averages. This section develops the connection between $n_{3}, n$ and the flux surface average.

As spatial variables we will use the conventional magnetic flux coordinates, $(\psi, \beta, s)$, discussed in Sec. II. The volume clement is then,

$$
\begin{equation*}
\nabla s \cdot \nabla \beta \times \nabla \psi d^{3} x=d s d \beta d \psi=B d^{3} x \tag{5.1}
\end{equation*}
$$

and the specific volume, $d V / d \psi$, between flux surfaces is

$$
\begin{equation*}
d V / d \psi=\oint \frac{|d s| d \beta}{B}=2 \pi \oint \frac{|d s|}{B} \tag{5.2}
\end{equation*}
$$

where the line integral covers one circuit of the poloidal circumference. The path length, $|d s|$, in Eq. (5.2) is taken to be positive. The flux surface average of any function, $F$, can be written

$$
\begin{equation*}
\langle F\rangle_{\varphi} \equiv \frac{d \psi}{d V} \int d A F /|\nabla \psi|=\frac{d \psi}{d V} \int|d s| d \beta F / B \tag{5.3}
\end{equation*}
$$

The subscript, $\psi$, distinguishes this from the bounce average, natural to the Lagrangian representation, and denoted by

$$
\begin{equation*}
\langle F\rangle=\int d \theta_{2} F=\omega_{2} \oint d s F / w \tag{5.4}
\end{equation*}
$$

where the path element, $d s$, in Eq. (5.4) has the same sign as $w$.
Given any distribution $f(J, \theta)$ in the action-angle variables, the spatial density $n(x)$ can be obtained by projection, viz

$$
\begin{equation*}
n(x)=\int d^{3} J d^{3} \theta \delta(x-x(J, \theta)) f(J, \theta) \tag{5.5}
\end{equation*}
$$

with $x(J, 0)$ determined by the transformation, $x, v \mapsto J, 0$. In magnetic flux coordinates this becomes, using (5.1),

$$
\begin{equation*}
n(x)=\int d^{3} J d^{3} \theta B \delta(s-s(J, \theta)) \delta(\beta-\beta(J, \theta)) \delta(\psi-\psi(J, \theta)) f(J, \theta) . \tag{5.6}
\end{equation*}
$$

The flux surface average density takes a particularly simple form. We apply Eq. (5.3) to Eq. (5.6). Neglecting toroidal gyroradius corrections (classical transport) and using axisymmetry eliminates $\theta_{1}$ and $\theta_{3}$ dependences of $f$. There results,

$$
\begin{equation*}
\langle n(x)\rangle_{\psi}=\frac{d \psi}{d V} \int d^{3} J \oint d \theta_{2} \delta\left(\psi-\psi\left(I, \theta_{2}\right)\right) f\left(J, \theta_{2}\right) \tag{5.7}
\end{equation*}
$$

or, using path length, $s^{\prime}$, in place of $\boldsymbol{\theta}_{2}$,

$$
\begin{equation*}
\langle n(x)\rangle_{\psi}=\frac{d \psi}{d V} \int d^{3} J \omega_{2} \oint \frac{d s^{\prime}}{w} \delta\left(\psi-\psi\left(J, s^{\prime}\right)\right) f\left(J, s^{\prime}\right) \tag{5.8}
\end{equation*}
$$

The function $\psi\left(J, s^{\prime}\right)$ can be inferred from Eqs. (2.63) and (2.68). For present purposes, we write the third action as

$$
\begin{align*}
J_{3} & =\frac{2 \pi q}{c} \psi+2 \pi\left(\frac{m u I}{B}-\left(\frac{m u I}{B}\right\rangle\right) \\
& \equiv \frac{2 \pi q}{c} \psi+\Delta J_{3} \tag{5.9}
\end{align*}
$$

where $I$ is conventionally defined as $R B_{T}$. Thus, to order $\rho_{p} / a, J_{3}=\frac{2 \pi q}{c} \psi$ and to second order in $\rho_{p} / a$, for $f$ independent of $s^{\prime}$, the flux surface average density becomes

$$
\begin{equation*}
\langle n(x)\rangle_{\psi}=\frac{2 \pi q}{c} \frac{d \psi}{d V} \int d^{2} J_{\perp} f\left(J_{\perp}, \frac{2 \pi q}{c} \psi\right)=\frac{d J_{3}}{d V} n_{3} \tag{5.10}
\end{equation*}
$$

so that $\langle n\rangle_{\mathrm{v}} / n_{3}$ is just the specific volume between surfaces $J_{3}=$ const.

Actually the local density $n(x)$, not flux surface averaged, and $n_{3}$ have the same relationship although only to first order in $\rho_{p} / a$. To show this, we first compute the normalization constant for $f_{0}$, written as,

$$
\begin{equation*}
f_{0}(J)=n_{3}\left(J_{3}\right) c_{3}\left(J_{3}\right) \exp \left(-H_{0}(J) / T\left(J_{3}\right)\right), \tag{5.11}
\end{equation*}
$$

with $c_{3}$ determined by

$$
\begin{equation*}
1=c_{3} \sum_{\sigma} \int d J_{1} d J_{2} \exp \left(-H_{0}(J) / T\right) \tag{5.12}
\end{equation*}
$$

The sum $\sigma$ runs over plus and minus parallel velocities. It is convenient to use the variables

$$
\begin{align*}
& \lambda=J_{1} / H_{0}\left(J_{1}, J_{2}\right)  \tag{5.13}\\
& H=H_{0}\left(J_{1}, J_{2}\right),
\end{align*}
$$

with volume element,

$$
\begin{equation*}
d J_{1} d J_{2}=\frac{H}{\omega_{2}} d \lambda d H \tag{5.14}
\end{equation*}
$$

The variable $\lambda$ is the bounce averaged pitch angle divided by $\omega_{1}$. Using Eq. (2.40) for $\omega_{2}$, Eq. (5.12) becomes,

$$
\begin{equation*}
1=c_{3} \sum_{\sigma} \oint d s^{\prime} \int d \lambda d H \frac{\sigma H}{\sqrt{\frac{2}{m} H(1-\lambda \Omega / 2 \pi)}} e^{-H / T} \tag{5.15}
\end{equation*}
$$

In the integration over $\lambda$, it is understood that the maximum value of $\lambda$ at fixed $s^{\prime}$ is $2 \pi / \Omega$. Doing the $\lambda$ and $H$ integrals and summing over $\sigma$ yields,

$$
\begin{equation*}
1=c_{3}(2 \pi m T)^{3 / 2} \frac{c}{q} \oint \frac{|d s|}{B}=c_{3}(2 \pi m T)^{3 / 2} \frac{d V}{d J_{3}} \tag{5.16}
\end{equation*}
$$

Upon solving for $c_{3}$, and inserting in Eq. (5.11), the specific volume factor combines with $n_{3}$ to give $n \equiv$ $n_{3} d J_{3} / d V$, which acocunts for the normalization used in Eq. (4.9).

Finally, to demonstrate that the $n$, so defined, is the leading order spatial density, we evaluate Eq. (5.6) with $f=f_{0}$. The $\beta$ integral is done by noting that $\beta(J, \theta)=2 \pi \theta_{3}+\delta \beta\left(J, \theta_{2}\right)$. Writing the $\theta_{2}$ integral in terms of arc length, as above then gives,

$$
\begin{align*}
n(x) & =\sum_{\sigma} \int d^{3} J \omega_{2} \oint \frac{d s^{\prime}}{|w|} \frac{B}{2 \pi} \delta\left(s-s^{\prime}\right) \delta\left(\psi-\frac{c}{2 \pi q}\left(J_{3}-\Delta J_{3}\right)\right) f_{0}(J)  \tag{5.17}\\
& =\sum_{\sigma} \int d^{2} J_{\perp} \frac{q B \omega_{2}}{c|w|} f_{0}\left(J_{\perp}, \frac{2 \pi q}{c} \psi+\Delta J_{3}\right) .
\end{align*}
$$

'To lowest order in $\rho_{p} / a$, the $\Delta J_{3}$ may be ncglected. Upon doing the indicated integrals, one finds, form (5.17); $n(x)=n$, as required.

## B. Collision Operator and Kinetic Equation

We now carry out an explicit evaluation of the coefficients in Eq. (3.28) for the Lorentz limit. Defining the velocity dependent collision frequency,

$$
\begin{equation*}
\nu(v)=2 \pi n q^{4} \ln \Lambda / m^{2} v^{3} \tag{5.18}
\end{equation*}
$$

eq. (3.28) can be written,

$$
\begin{align*}
& \frac{\partial f}{\partial t}+\frac{\partial}{\partial J} \cdot\left(\int d^{3} \theta \frac{q}{m} E \cdot \nabla_{v} J f\right)=  \tag{5.19}\\
& \quad \frac{\partial}{\partial J} \cdot \int d^{3} \theta \nu\left(\nabla_{v} J\right)^{T} \cdot\left(v^{2} I-v v\right) \cdot \nabla_{v} J \cdot \frac{\partial}{\partial J} f
\end{align*}
$$

which is of the form (1.3) To simplify things further, we assume axisymmetry, and evaluate only neoclassical fluxes, neglecting effects of order $\rho_{T} / a$. The integrands in Eq. (5.19) are then independent of both $\theta_{1}$ and $\theta_{3}$, leaving only the $\theta_{2}$, or bounce average, integral. Writing the induction field as, $E=e_{\zeta} V_{T} / 2 \pi R$, where $V_{T}$ is the (constant) toroidal voltage, puts Eq. (5.19) in th form of Eq. (4.1) and (4.2), with the coefficients given by

$$
\begin{align*}
& a(J)=\omega_{2} \oint \frac{d s}{w} \frac{1}{m R} e_{\rho} \cdot \nabla_{v} J  \tag{5.20}\\
& D(J)=\omega_{2} \oint \frac{d s}{w}\left(\nabla_{v} J\right)^{t} \cdot\left(v^{2} I-v v\right) \cdot \nabla_{v} J . \tag{5.21}
\end{align*}
$$

It remains to evaluate the partial velocity derivatives of the actions at fixed $x$, and carry out the bounce averages. This has an obvious physical interpretation since the effect of collisions is to scatter the velocity at a fixed spatial position. The derivatives, $\nabla_{\boldsymbol{v}} J$, measure the effectiveness by which such a process changes the actions, and Eq. (5.21) averages the resulting action scattering over a bounce. In particular $\nabla \boldsymbol{v} J_{3}$ measures the rate of radial scattering due to collisions. It is this sensitivity of the radial coordinate, $J_{3}$, to velocity parameters that leads to the enhanced (neoclassical) transport. The importance for grod confinement of the insensitivity of $J_{3}$ to velocity parameters, termed omnigenity, has been noted in conncetion with mirror confinement (14).

From Eqs. (2.79) and (2.80) we have,

$$
\begin{equation*}
\nabla{ }_{\nabla} I_{1}=\frac{2 \pi m}{\Omega}(v-u b) \tag{5.22}
\end{equation*}
$$

and

$$
\begin{equation*}
\nabla_{v} J_{2}=\frac{m}{\omega_{2}}\left(\imath\left(1-\frac{2 \pi \omega_{1}}{\Omega}\right)+\frac{2 \pi \omega_{1}}{\Omega} u b\right) . \tag{5.23}
\end{equation*}
$$

While from Eq. (5.9), it follows that

$$
\begin{align*}
\nabla_{v} J_{3}= & \nabla_{v}\left[2 \pi m u I / B-2 \pi\left(\frac{m u I}{B}\right)\right]  \tag{5.24}\\
= & b \frac{2 \pi m I}{B}-\nabla_{v} J_{1} \frac{\partial}{\partial J_{1}} 2 \pi\left(\frac{m u I}{B}\right\rangle \\
& -\nabla_{v} J_{2} \frac{\partial}{\partial J_{2}} 2 \pi\left(\frac{m u I}{B}\right)
\end{align*}
$$

plus terms of higher order, neglected, consistent with our $\omega_{3} \rightarrow 0$ limit, because of the weak dependence of equilibrium quantitites on $J_{3}$.

Note that for each action, $\nabla_{v} J_{i}$ can be written in the form $a v+\beta b$. Since $v \cdot\left(v^{2} I-v v\right) \cdot v=\left(v^{2} I-v v\right)$. $v=0$, the diffusion tensor depends only on the $b$ component. We can therefore write,

$$
\begin{equation*}
D=\omega_{2} \oint \frac{d s}{w} \nu\left(b \cdot \nabla_{v}\right)\left(b \cdot \nabla_{v}\right)\left(v^{2}-u^{2}\right), \tag{5.25}
\end{equation*}
$$

or in index notation,

$$
\begin{equation*}
\dot{D}_{i j}=\frac{J_{1}}{\pi m}\left\langle\nu \Omega \frac{\partial}{\partial u} J_{i} \frac{\partial}{\partial u} J_{j}\right\rangle . \tag{5.26}
\end{equation*}
$$

An abbreviated notation is employed in both (5.25) and (5.26), with $b \cdot \nabla_{v}=\partial / \partial u$ indicating the coefficient of $b$ in the decomposition of $\nabla_{\boldsymbol{v}} I_{i}$ into vectors along $\boldsymbol{v}$ and $b$. The indication $b \cdot \nabla_{\boldsymbol{v}}$ does not denote the usual dot product because $v$ and $b$ are not orthogonal in general. Using Eqs. (5.22), (5.23) and (5.24), the ordered diffusion tensor can be written as the sum of the terms, $D=D_{0}+D_{1}+D_{2}$, where

$$
\begin{align*}
D_{0}= & 4 \pi \nu J_{1} \omega_{1}^{2}\left\langle\frac{m u^{2}}{\Omega}\right\rangle\left(-\frac{1}{\omega_{1}} e_{1}+\frac{1}{\omega_{2}} e_{2}\right)\left(-\frac{1}{\omega_{1}} e_{1}+\frac{1}{\omega_{2}} e_{2}\right),  \tag{5.27}\\
D_{1}= & 4 \pi \nu J_{2} \omega_{2}\left\langle u \frac{\partial}{\partial u}\left(\frac{m u I}{B}-\left\langle\frac{m u I}{B}\right\rangle\right)\right\rangle  \tag{5.28}\\
& \times\left[\left(-\frac{1}{\omega_{1}} e_{1}+\frac{1}{\omega_{2}} e_{2}\right) e_{3}+e_{3}\left(-\frac{1}{\omega_{1}} e_{1}+\frac{1}{\omega_{2}} e_{2}\right)\right] \\
& =4 \pi \frac{\nu J_{1}}{m}\left\langle\Omega\left[\frac{\partial}{\partial u}\left(\frac{m u I}{B}-\left\langle-\frac{m u I}{B}\right\rangle\right)\right]^{2}\right\rangle e_{3} e_{3} . \tag{5.29}
\end{align*}
$$

The third action in Eq. (5.9) is predominantly a spatial variable, $2 \pi \frac{q}{c} \psi$, with a kinetic correction, $\Delta J_{3}$. It is the derivatives $\nabla_{v} J_{3}=\nabla_{0} \Delta J_{3}$ which appear in $D_{1}$ and $D_{2}$ and determine the radial transport. The magnitude of $\Delta J_{3}$ measures the deviation of the orbit from the average flux surface, $\langle\psi\rangle=\frac{c}{2 \pi q} J_{3}$. For circulating particles the local kinetic angular momentum, $m u I / B$, very nearly cquals the average, $(m u I / B\rangle, \Delta J_{3} \approx 0$, the displacement of the orbit from the average flux surface is small, and the neoclassical enhancement of transport is minimal (except near the boundary between the circulating and trapped regions). For trapped particles, the averaged angular momentum is identically zero. The omnigenity factor, $b \cdot \nabla_{v} J_{3}=2 \pi m I / B$, is then significant, indicating substantial neoclassical enhancement for the trapped particles. To denote this, we define the factor

$$
\begin{equation*}
\left.\Delta_{c}=\frac{B}{m I} b \cdot \nabla \mathfrak{Q} \frac{m u I}{B}\right\rangle, \tag{5.30}
\end{equation*}
$$

which is zero for trapped particles, unity for well circulating particles. Using Eq. (5.30) the coefficients $D_{1}$ and $D_{2}$ become,

$$
\begin{align*}
& D_{1}=4 \pi \nu J_{1} \omega_{1}\left\langle\frac{m u I}{B}\left(1-\Delta_{c}\right)\right\rangle\left[\left(-\frac{1}{\omega_{1}} e_{1}+\frac{1}{\omega_{2}} e_{2}\right) e_{3}+e_{3}\left(-\frac{1}{\omega_{1}} e_{1}+\frac{1}{\omega_{2}} e_{2}\right)\right]  \tag{5.31}\\
& D_{2}=4 \pi \nu J_{1}\left\langle m \Omega \frac{I^{2}}{B^{2}}\left(1-\Delta_{c}\right)^{2}\right\rangle e_{3} e_{3} \tag{5.32}
\end{align*}
$$

The electric field coefficient , $a$, is evaluated similarly. The term $a_{1}$ is of order $\rho_{T} / a$ and would vanish identically if the gyroaverage, $\int d \theta_{2}$, were retained in Eq. (5.20). For $a_{2}$ we need,

$$
\begin{align*}
e_{\varsigma} \cdot \nabla_{v} J_{2} & =\frac{m}{\omega_{2}} e_{\varsigma} \cdot v+\frac{2 \pi m \omega_{1}}{\Omega \omega_{2}}\left(-e_{\zeta} \cdot v+e_{\varsigma} \cdot b b \cdot v\right)  \tag{5.33}\\
& =\frac{m}{\omega_{2}} e_{\rho} \cdot v-\frac{2 \pi m \omega_{1}}{\Omega \omega_{2}} e_{\zeta} \cdot b \times e_{\psi} b \times e_{\psi} \cdot v \\
& =\frac{m}{\omega_{2}} e_{\varsigma} \cdot v-\frac{2 \pi m \omega_{1}}{\Omega \omega_{2}} \frac{B_{p} B_{T}}{B^{2}} e_{\psi} \cdot b \times 0 \\
& \rightarrow \frac{m}{\omega_{2}} \frac{u B_{T}}{B}
\end{align*}
$$

where the last step follows from averaging over $\theta_{1}$. To the order we require, $u=\omega$, so that

$$
\begin{equation*}
a_{\perp}=e_{2} a_{2}=e_{2} \frac{1}{\omega_{2}}\left\langle\frac{u I}{R^{2} B}\right\rangle=e_{2} I \oint \frac{d s}{B} \frac{1}{R^{2}} \tag{5.34}
\end{equation*}
$$

The integral in $s$ goes around a full orbital cycle and vanishes for trapped particies. The radial flow coefficient is

$$
\begin{equation*}
a_{3}=\left\langle\frac{2 \pi}{m R} c_{亏} \cdot \nabla_{2}\left(\frac{m u I}{B}-\left\langle\frac{m u I}{B}\right\rangle\right)\right\rangle \tag{5.35}
\end{equation*}
$$

or, for trapped particles, simply,

$$
\begin{equation*}
a_{3} \rightarrow 2 \pi I^{2}\left(\frac{1}{B^{2} R^{2}}\right)=2 \pi \omega_{2} \oint \frac{d s}{u} \frac{B_{T}^{2}}{B^{2}} . \tag{5.36}
\end{equation*}
$$

The orderings assumed in Scc. IV can now be verified. Since $J_{1} \sim m v_{\mathrm{th}} \rho_{T} \sim m v_{\mathrm{th}}^{2} / \omega_{1}$ and $J_{2} \sim$ $m v_{\mathrm{th}} R \sim m v_{\mathrm{th}}^{2} / \omega_{2}$, it follows from Eq. (5.27) that $\omega_{1} d J_{1} \sim \omega_{2} d J_{2}$, all the terms of $C_{0}$ are the same magnitude and of order $\nu$. In contrast, the dimensionless parameter characterizing $J_{3}$ derivatives in the collision operator is $m v_{\mathrm{th}} I / B J_{3} \sim \rho_{p} / a<1$. Similarly in the electric field term, since the coefficients $a_{2}$ and $a_{3}$ are of order unity and $\left|d \ln J_{2} / d \ln J_{3}\right| \sim \rho_{p} / a$, the assumed ordering is satisfied.

## C. Transport Coefficients

To evaluate the transport coefficients; one must determine the perturbed distributions, $g_{i}$, required for the implicit fluxes. We illustrate the procedure for $g_{1}$ and show the equivalence of the transport coefficients, $T_{11}$, $T_{13}$ and $T_{31}$ with those obtained by Hinton and Hazeltine from the Eulerian formulation. This equivalence relies on a certain cancellation of parts of the implicit and explicit fluxes, which is demonstrated in detail in Appendix A. To determine the full flux surface averaged toroidal current, the diamagnetic contributions. $T_{13}^{e}$ and $T_{23}^{e}$, must be computed. This is done, and demonstration of the explicit symmetry, $T_{31}^{e}=T_{13}^{e}$, is given.

The computation of $g_{1}$, follows from Eq. (4.20), evaluated using the specific forms (5.27) and (5.28),

$$
\begin{equation*}
\frac{\partial}{\partial J} \cdot D_{0} \cdot \frac{\partial}{\partial J} g_{1}=-\left(\frac{\partial}{\partial J} \cdot D_{1} \cdot e_{3}\right) f_{o}=-\frac{\partial}{\partial J} \cdot\left[D_{1} \cdot e_{3} f_{o}\right] \tag{5.37}
\end{equation*}
$$

This equation is easily integrated using the variables $\lambda \equiv(\lambda, H)$ defined in Eq. (5.13). With the transformation matrix, $M$, such that $\frac{\partial}{\partial J}=M \cdot \frac{\partial}{\partial \lambda}$, given by

$$
\begin{aligned}
M= & \frac{1}{H}\left(1-\frac{\omega_{1} J_{1}}{H}\right) e_{1} e_{\lambda}+\omega_{1} e_{1} e_{H} \\
& -\frac{\omega_{2} J_{1}}{H^{2}} e_{2} e_{\lambda}+\omega_{2} e_{2} e_{H},
\end{aligned}
$$

Eq. (5.37) becomes,

$$
\begin{align*}
& \frac{\partial}{\partial J} \cdot\left\{( - \frac { e _ { 1 } } { \omega _ { 1 } } + \frac { e _ { 2 } } { \omega _ { 2 } } ) \left[-4 \pi \nu \lambda<B><\frac{m u^{2}}{B}>\frac{\partial}{\partial \lambda} g_{1}\right.\right.  \tag{5.39}\\
& \left.\left.\quad+4 \pi \nu \lambda \omega_{1} H<\frac{m u I}{B}\left(1-\Delta_{c}\right)>f_{0}\right]\right\}=0
\end{align*}
$$

The variable $\lambda$ is bounded by zero and $2 \pi / \Omega_{\text {MIN }}$ (the value $2 \pi / \Omega_{M A X}$ corresponds to the boundary between trapped and circulating particles). Eq. (5.39) is to be solved subject to a condition of zero flow across the boundaries $\lambda=0,2 \pi / \Omega_{M I N}$ (and continuity of flux across $\lambda=2 \pi / \Omega_{M A X}$ should be a discontinuity in the forcing function appear). Application of the boundary condition at $\lambda=2 \pi / \Omega_{\text {MIN }}$ requires that the terms in square brackets vanish identically, yielding,

$$
\begin{equation*}
<\frac{m u^{2}}{\Omega}>\frac{\partial g_{1}}{\partial \lambda}=H<\frac{m u I}{B}\left(1-\Delta_{c}\right)>f_{0} . \tag{5.40}
\end{equation*}
$$

This equation determines $g_{1}$, for both signs of transiting particles, up to a constant equal to the trapped particle density. If we require that $\sum_{\sigma} \int d J_{1} d J_{2} g_{1}=0$, so that $f_{o}$ contain all the particle density through second order, then the trapped particle perturbation is zero.

The implicit contribution to the diffusion cocfficient, $-T_{11}^{i}$, is now easily evaluated,

$$
\begin{align*}
-T_{11}^{i} \equiv\left(a_{1}, \dot{g}_{1}\right) & =\int d J_{1} d J_{2} \alpha_{1} g_{1} \\
& =\int d J_{1} d J_{2}\left(-\frac{\partial}{\partial J} \cdot D_{1} \cdot e_{3}\right) g_{1}=\int d J_{1} d J_{2}\left(D_{1} \cdot e_{3}\right)^{t} \cdot \frac{\partial}{\partial J} g_{1}  \tag{5.41}\\
& =\int d J_{1} d J_{2} e_{3} \cdot D_{1} \cdot \frac{\partial}{\partial J} g_{1}
\end{align*}
$$

Transforming variables, and using Eq. (5.31), this becomes

$$
\begin{equation*}
-T_{11}^{i}=\sum_{\sigma} \int d H d \lambda 4 \pi \nu \lambda \frac{H^{2}}{\omega_{2}} f_{o}<\frac{m u I}{B}\left(1-\Delta_{c}\right)>^{2} /<\frac{m u^{2}}{\Omega}> \tag{5.42}
\end{equation*}
$$

Adding the explicit piece, $T_{11}^{e}=\left(-D_{33}, f_{0}\right)$, gives the full transport cocfficient as,

$$
\begin{align*}
T_{11}= & \left.-\sum_{\sigma} \int d H d \lambda 4 \pi \nu \lambda \frac{H^{2}}{\omega_{2}} f_{o} \right\rvert\,<m \Omega \frac{I^{2}}{B^{2}}\left(1-\Delta_{c}\right)^{2}>  \tag{5.43}\\
& -<\frac{m u I}{B}\left(1-\Delta_{c}\right)>^{2} /<\frac{m u^{2}}{\Omega}>1
\end{align*}
$$

This expression, as we will shortly show, reduces to the well known results from the Eulerian representation if we set $\Delta_{c}=0$. In fact, $\Delta_{c}$ is zero only in trapped space and is nearly unity over most of circulating space. What actually happens is that the terms involving $\Delta_{c}$ from the explicit part exactly cancel those from the implicit part giving the same effect as putting $\Delta_{c}=0$. This cancelation and an analogous one in the other transport coefficients is demonstrated in Appendix A.

That the trapped particles make the dominant contribution to the diffusion coefficient, $-T_{11}$, is well known. To arrive at this conclusion in the Eulerian picture, one must actually evaluate the integrals in Eq. (5.43), (for $\Delta_{c}=0$ ), and show that they nearly cancel for circulating particles. The circulating and trapped particle contributions are formally the same order in $\rho_{p} / a$ and a great deal of effort is required to demonstrate the numerical smallness of the circulating particle contributions. In the Lagrangian formulation there is an additional small parameter, $1-\Delta_{c}$, appearing in both the explicit and implicit terms, which measures the relative insensitivity of the circulation particle action, $J_{3}$, to velocity scattering. Correct to order ( $\left.1-\Delta_{c}\right)^{2}$ the transport coefficient is due to trapped particles, is therefore explicit and can be obtained from simple moments of the collision operator without ever solving for the perturbed distribution function. This reduces the required computations significantly, an aspect of the Lagrangian formulation that has practical potential for evaluating transport in more complex systems.

To relate Eq. (5.43) to the familiar Eulerian expressions, we write out the bounce averages and do the integrals over $H$ and the $\sigma$ sum to give

$$
\begin{align*}
T_{11}= & -\frac{\nu_{o}}{\sqrt{\pi}} \frac{2 T}{m} \frac{q I^{2}}{c} n \int_{0}^{2 \pi / \Omega_{M I N}} d \lambda \lambda\left[\oint \frac{d s}{B} \frac{1}{\sqrt{1-\lambda \Omega / 2 \pi}}\right.  \tag{5.44}\\
& \left.-\mathcal{Y}\left(2 \pi / \Omega_{M A X}-\lambda\right) \frac{\left(\oint \frac{d s}{B}\right)^{2}}{\oint \frac{d s}{B} \sqrt{1-\lambda \Omega / 2 \pi}}\right]
\end{align*}
$$

In Eq. (5.44), $\nu_{o}$ is given by Eq. (5.18) cvaluated at $v=\sqrt{2 T / m}$, and J 3 is the heavy side step function. Note that the second (implicit) term vanishes for the trapped particles. Since the $s$ integrals have a weighting factor of $1 / B$, they can now be interpreted as flux surface averages even though they arose, in the present theory, from orbit averages. Thus, letting $\lambda=\lambda^{\prime} 2 \pi / \Omega_{0}$ and recalling that $d V / d J_{3}=c / q \int d s / B$. Eq. (5.44) becomes

$$
\begin{equation*}
T_{11}=-\frac{V_{0}}{\sqrt{\pi}} \frac{2 T}{m \Omega_{o}^{2}}\left(\frac{2 \pi q I}{c}\right)^{2} n_{3} I_{11} \tag{5.45}
\end{equation*}
$$

where $I_{11}$ is the dimensionless integral,

$$
\begin{equation*}
I_{11}=\int_{0}^{\Omega_{0} / \Omega_{M I N}} d \lambda^{\prime} \lambda^{\prime}\left[<\frac{1}{\sqrt{1-\lambda^{\prime} \Omega / \Omega_{0}}}>_{\psi}-\frac{{ }^{2}\left(\Omega_{0} / \Omega_{M A X}-\lambda^{\prime}\right)}{<\sqrt{1-\lambda^{\prime} \Omega / \Omega_{o}}>_{\psi}}\right] . \tag{5.46}
\end{equation*}
$$

Apart from the system of units, this is the same cocfficient derived by Hinton and Hazeltine. Their units are based on an effective minor radius coordinate $\rho$, defined by $B_{p o}(\rho)=1 / R_{0} \partial \psi / \partial \rho$, which replaces our $J_{3}$ as a radial variable. To convert Eq. (5.45), multiply by $\left(d \rho / d J_{3}\right)^{2}=\left(c / 2 \pi q B_{p o} R_{o}\right)^{2}$, and divide by the specific volume $d V / d J_{3}$.

The distribution function $g_{1}$ can also be used to compute the implicit bootstrap current, $T_{31}^{i}=-\left(\alpha_{3}, g_{1}\right)$ , and from the symmetry relation, $T_{13}^{i}=T_{31}^{i}$, the implicit Ware pinch coefficient as well. The explicit Ware coefficient follows from Eqs. (4.25) and (5.20) as

$$
\begin{align*}
T_{13}^{e} & =-\int d J_{1} d J_{2} \omega_{2} \oint \frac{d s}{u} \frac{q T}{2 \pi m R}\left(e_{\varsigma} \cdot \nabla_{v} J_{3}\right) f_{0},  \tag{5.47}\\
& =-\int d J_{1} d J_{2} \omega_{2} \oint \frac{d s}{u} \frac{q T}{2 \pi m R}\left(e_{\varsigma} \cdot \nabla_{v} \Delta J_{3}\right) f_{0},
\end{align*}
$$

where $\Delta J_{3}$, see Eq. (5.9), measures the displacement of the actual $\psi$ from the orbital average $\psi$ or $J_{3}$.

Now consider the calculation of the toroidal electric current density in the action-angle formalism. Following, the procedure for obtaining the spatial density, we begin from

$$
\begin{equation*}
J_{T}=\int d^{3} J d^{3} \theta \delta\left(x-x\left(J_{1} \theta\right) q e_{5} \cdot \theta\left(J_{1} \theta\right) f(\lambda) .\right. \tag{5.48}
\end{equation*}
$$

This, in general, is a function of $\psi$ and the poloidal angle and can be used in Ampere's law to determine the flux function $\psi$. It contains the Pfirsch-Schluter current in addition to the parts, constant on a flux surface, that are determined from transport theory. 'Thus to define $I_{T}$ for the present transport theory, we weight $J_{T}$ by $1 / 2 \pi R$ to give an angular current, flux surface average, and multiply by the specific volume $d V / d J_{3}$,

$$
\begin{align*}
& I_{T} \equiv \frac{c}{2 \pi q} \frac{d V}{d \psi}<J_{T} / 2 \pi R>_{\psi}  \tag{5.49}\\
&=\int d^{3} J \omega_{2} \oint \frac{d s}{u} \frac{c}{2 \pi q} \delta\left(\psi-\frac{c}{2 \pi q}\left(J_{3}-\Delta J_{3}\right)\right) \frac{q}{2 \pi R} e_{\zeta} \cdot \nabla f, \\
&=\int d^{2} J_{\perp} \omega_{2} \oint \frac{d s}{u} \frac{q}{2 \pi R} e_{\zeta} \cdot \nabla f\left(J_{\perp}, \frac{2 \pi q}{c} \psi+\Delta J_{3}\right) .
\end{align*}
$$

Expanding in powers of $\rho_{p} / a$, this becomes, to first order,

$$
\begin{equation*}
I_{T}=\int d^{2} J_{\perp} \omega_{2} \oint \frac{d s}{u} \frac{q}{2 \pi R} e_{\zeta} \cdot \sigma\left[f_{1}\left(J_{\perp}, \frac{2 \pi q}{c} \psi\right)+\Delta J_{3} \frac{\partial f_{0}}{\partial J_{3}}\right] \tag{5.50}
\end{equation*}
$$

The first term is just the implicit current density, $I_{T}^{i}$, of Eq. (4.6) as can be seen from Eq. (5.34) for $a_{2}$. The second term is a diamagnetic current associated with the departure of the orbits from their average flux surfaces. It gives the explicit fluxes,

$$
\begin{gather*}
T_{31}^{e}=\int d^{2} J_{\perp} \omega_{2} \oint \frac{d s}{u} \frac{q}{2 \pi R} e_{5} \cdot v \Delta J_{3} f_{0}  \tag{5.51}\\
T_{32}^{e}=\int d^{2} J_{\perp} \omega_{2} \oint \frac{d s}{u} \frac{q}{2 \pi R} e_{\zeta} \cdot v \Delta J_{3}\left(\frac{H}{T}-3 / 2\right) f_{0} . \tag{5.52}
\end{gather*}
$$

Note that the explicit current has been defined in a manner analogous to Eq. (4.27), so that the total current is given by

$$
\begin{equation*}
I_{T}=T_{31} \frac{d \ln n}{d J_{3}}+T_{32} \frac{d \ln T}{d J_{3}}+T_{33} V_{T} / T \tag{5.53}
\end{equation*}
$$

To prove the explicit conjugacy, we obscrve that upon change of variables $J_{1}, J_{2} \rightarrow v_{\perp}, u$, the volume element transforms such that $d J_{1} d J_{2 \omega_{2}} / u=m^{2} / \Omega d^{3} v$, and the integrals in Eqs. (5.47) and (5.51) can be expressed accordingly. If one then integrates the velocity integral in Eq. (5.47) by parts, Eq. (5.51), results.

We can now compute the full coefficient $T_{31}=T_{13}$, as

$$
\begin{align*}
& T_{31}=\int d J_{1} d J_{2}\left(-a_{3} g_{1}+\omega_{2} \oint \frac{d s}{u} \frac{q}{2 \pi R} e_{\varsigma} \cdot v \Delta J_{3} f_{o}\right),  \tag{5.54}\\
& \\
& =\int d J_{1} d I_{2}\left(\frac{q}{2 \pi} \omega_{2} \oint \frac{d s}{B} \frac{I}{R^{2}} g_{1}+\frac{q}{2 \pi}\left(\omega_{2} \oint \frac{d s}{B} \frac{I}{R^{2}} \Delta J_{3} f_{0}\right) .\right.
\end{align*}
$$

As shown in the Appendix the perturbed distrubution can be written $g_{1}=g_{1}^{\prime}+<2 \pi m I u / B>f_{0}$, where $g_{1}^{\prime}$ satisfies Eq. (5.39) with $\Delta_{c}=0$. Making this substitution cancels the average term, $<2 \pi m I u / B>$, in $\Delta J_{3}$ to give,

$$
\begin{equation*}
T_{31}=\frac{q}{2 \pi} \int d J_{1} d J_{2} \omega_{2} \oint \frac{d s}{B} \frac{I}{R^{2}}\left(g_{1}^{\prime}+\frac{2 \pi m I u}{B} f_{0}\right) \tag{5.55}
\end{equation*}
$$

Changing variables to $\lambda_{,} H$ and integrating both terms by parts, Eq. (5.40) with $\Delta_{c}=0$, can be used for $\partial g_{1}^{\prime} / \partial \lambda$. Doing the $H$ integrals the result can be expressed,

$$
\begin{equation*}
T_{31}=\frac{3}{4} q T n_{3} I_{31} \tag{5.56}
\end{equation*}
$$

where $I_{31}$ is the dimensionless integral,

$$
\begin{align*}
I_{31}= & \int_{0}^{\Omega_{0} / \Omega_{M I N}} d \lambda^{\prime} \lambda^{\prime}\left[<\frac{I^{2}}{R^{2} B_{0}^{2} \sqrt{1-\lambda^{\prime} \Omega / \Omega_{0}}}>_{\psi}\right.  \tag{5.57}\\
& \left..-H\left(\Omega_{0} / \Omega_{M A X}-\lambda^{\prime}\right) \frac{<I^{2} / R^{2} B_{0}^{2}>_{\psi}}{<\sqrt{1-\lambda^{\prime} \Omega / \Omega_{0}>_{\psi}}}\right] .
\end{align*}
$$

Again this is equivalent to the coefficient quoted by Hinton and Hazeltine. Their form of Eq. (5.56) is recovered by multiplying by factors of $d \rho / d J_{3}=c / 2 \pi q B_{p o} R_{0} d V / d J_{3}, 2 \pi R_{o} / T$, and -1 , to account, respectively, for the radial variable, density normalization, current normalization, and sign of radial variable ( $J_{3}$ is negative for electrons).

## D. Physical Mechanism of the Pinch Effect and the Bootstrap Current

We now evaluate the separate contributions to the transport coefficients in the limit of small inverse aspect ratio and interpret the results. The overall (dimensionless) cocfficient, obtained from the asymptotic evaluation of Eq. (5.57) is [1].

$$
\begin{equation*}
I_{13}=I_{31} \simeq 1.38 \sqrt{2 \epsilon}+O\left(\epsilon^{\frac{3}{2}}\right) \tag{5.58}
\end{equation*}
$$

where $\epsilon=r / R_{0}$, is the inverse aspect ratio. Recall that Eq. (5.57) was obtained by adding the explicit and implicit results, and that the average terms needed to separate these pieces had then cancelled. Since the interpretation requires this separation, we first identify the dimensionless integrals corresponding to the individual parts.

For the explicit pinch coefficient, we need $e_{5} \cdot \nabla_{v} \Delta J_{3}$, which is evaluated from Eq. (5.9) as follows,

$$
\begin{align*}
e_{5} \cdot \nabla_{v} \Delta J_{3}= & 2 \pi m e_{5} \cdot \nabla v\left(\frac{u I}{B}-\omega_{2} I \oint \frac{d s}{B}\right)  \tag{5.59}\\
= & 2 \pi m\left[\frac{I^{2}}{B^{2} R}-I \oint \frac{d s}{B} e_{5} \cdot \nabla_{v} J_{1} \frac{\partial \omega_{2}}{\partial J_{1}}\right. \\
& \left.\left.+e_{5} \cdot \nabla_{v} J_{2} \frac{\partial \omega_{2}}{\partial J_{2}}\right)\right]
\end{align*}
$$

where it is understood that $\oint \frac{d g}{B}$ is zcro for trapped particles. The term $e_{5} \cdot \nabla_{v} J_{1}$ is of order $\rho_{T} / a$ and therefore negligible. The derivative $\partial \omega_{2} / \partial J_{2}$ is expressed in terms of $\lambda$ and $H$ derivatives, and manipulated slightly to give the electric field coefficient, $a_{3}$, as

$$
\begin{align*}
a_{3} & =\omega_{2} \oint \frac{d s}{u} \frac{1}{m R} e_{5} \cdot \nabla_{v} \Delta J_{3}  \tag{5.60}\\
& =2 \pi \omega_{2} \oint \frac{d s}{u} \frac{I^{2}}{B^{2} R^{2}}\left[1-\frac{m u}{H} B\left(\oint \frac{d s}{B}\right)\left(\frac{\omega_{2}}{2}+\omega_{2}^{2} \lambda \frac{\partial}{\partial \lambda} \frac{1}{\omega_{2}}\right)\right] \\
& \simeq 2 \pi \omega_{2}\left[\frac{1}{\omega_{2}}-\frac{m}{2 H}(\oint d s)^{2}\left(\omega_{2}+2 \omega_{2}^{2} \lambda \frac{\partial}{\partial \lambda} \frac{1}{\omega_{2}}\right)\right]
\end{align*}
$$

where the last step assumes small $\epsilon=r / R$. We use the small $\epsilon$ limit for the frequencies, such that for trapped particles, $1-\epsilon<\lambda^{\prime}<1+\epsilon$,

$$
\begin{equation*}
\frac{1}{\omega_{2}}=\oint d s \sqrt{\frac{m}{2 H}} \frac{1}{\sqrt{2 \epsilon}} \frac{2}{\pi} K\left(\frac{1+\epsilon-\lambda^{\prime}}{2 \epsilon}\right) \tag{5.61}
\end{equation*}
$$

where $K$ is the elliptic integral of the first kind, and for ciculating particles, $0<\lambda^{\prime}<1-\epsilon$,

$$
\begin{equation*}
\frac{1}{\omega_{2}}=\oint d s \sqrt{\frac{m}{2 H}} \frac{1}{\sqrt{1+\epsilon-\lambda^{\prime}}} \frac{2}{\pi} K\left(\frac{2 \epsilon}{1+\epsilon-\lambda^{\prime}}\right) \tag{5.62}
\end{equation*}
$$

Note that the energy dependence is the same for all terms. The integrals can be carried out to give $T_{13}$ in the form of Fiq. (5.56). For trapped particles the result is

$$
\begin{equation*}
I_{13}^{e, t r}=\frac{2}{3} \frac{1}{\sqrt{2 \epsilon}} \int_{1-\epsilon}^{1+\epsilon} d \lambda^{\prime} \frac{2}{\pi} K\left(\frac{1+\epsilon-\lambda^{\prime}}{2 \epsilon}\right) \tag{5.63}
\end{equation*}
$$

and for circulating particles,

$$
\begin{align*}
I_{13}^{e . c i r}= & \frac{2}{3} \int_{0}^{1-\epsilon} d \lambda^{\prime}\left[\frac{2}{\pi} \frac{K\left(\frac{2 \epsilon}{1+\epsilon-\lambda^{\prime}}\right)}{\sqrt{1+\epsilon-\lambda^{\prime}}}\right.  \tag{5.64}\\
& -\frac{\pi}{2} \frac{\sqrt{1+\epsilon-\lambda^{\prime}}}{K\left(\frac{2 \epsilon}{1+\epsilon-\lambda^{\prime}}\right)} \\
& \left.-\pi \frac{1+\epsilon-\lambda^{\prime}}{K^{2}\left(\frac{2 \epsilon}{1+\epsilon-\lambda^{\prime}}\right)} \lambda^{\prime} \frac{d}{d \lambda^{\prime}}\left(\frac{K\left(\frac{2 \epsilon}{1+\epsilon^{\prime}-\lambda^{\prime}}\right)}{\sqrt{1+\epsilon-\lambda^{\prime}}}\right)\right]
\end{align*}
$$

The conventional explanation of the pinch effect is that it is predominantly $I_{13}^{e, t r}$ or the Ware effect [4] evaluating Eq. (5.63) in the limit of small $\epsilon$, one finds

$$
\begin{equation*}
I_{13}^{e, t r}=\frac{8}{3 \pi} \sqrt{2 \epsilon}+O\left(\epsilon^{\frac{3}{2}}\right) \tag{5.65}
\end{equation*}
$$

which is 62 percent of the full cocfficient. The circulating particle contributions $I_{13}^{e_{13}^{, c i r}}$ and $I_{13}^{i, c i r}$ are of opposite sign and cancel to a large degree.

The conjugate process to the Ware effect is the diamagnetic current of the trapped particles, $I_{31}^{\text {e,tr }}$. However, this is of order $\epsilon^{3 / 2}$, and cannot account for any of the bootstrap current in the small $\epsilon$ limit [1]. Furthermore, evaluating the diamagnetic contribution of the circulating particles, one finds,

$$
\begin{equation*}
I_{31}^{e, c i r}=2 \int_{0}^{1-\epsilon} d \lambda^{\prime} \sqrt{1+\epsilon-\lambda^{\prime}}\left(\frac{2}{\pi} E\left(\frac{2 \epsilon}{1+\epsilon-\lambda^{\prime}}\right)-\frac{\pi}{2 K\left(\frac{2 \epsilon}{1+\epsilon-\lambda^{\prime}}\right)}\right) \tag{5.66}
\end{equation*}
$$

where $E$ is the clliptic integral of the second kind. The contribution, $I_{31}^{e, c i r}$, from Eq. (5.66), is also of order $\epsilon^{3 / 2}$ although this comes about from a concellation of order unity terms. Physically, the circulating particles produce a toroidal diamagnetic current that changes sign as one moves from the outer to the inner half of the torus. This is the Pfirsch-Schlter current. The flux surface average, however, as reflected in Eq. (5.66) gives a net current of nearly $\not$ cro. Furthermore, the integrand in F:q. (5.66) is of order $\epsilon^{3 / 2}$ for all $\lambda$. so that all panticles, unifornly, make a small contribution to the net current.

The inference from this is that the bootstrap current is completely implicit. In physical terms it is basically a collisional process affecting the circulating particles. This contrast in physical mechanism, between the pinch and bootstrap effects creates a conceptual dilemma. Why should such disjoint processes, invoiving different classes of particles, be Onsager conjugate effects?

To resolve this dilemma, first note that the explicit symmetry, together with the above results for $T_{31}^{e}$, imply that to order $\epsilon^{3 / 2}, T_{13}^{e} \simeq 0$. But then, noting Eq. (5.64), it follows that the explicit circulating particle flow is actually radially out, and at a rate which cancels entirely (to order $\epsilon^{3 / 2}$ ) the Ware pinch! The same conclusion can be reached directly using Eq. (5.64). This is somewhat different than the explicit bootstrap current, in that the trapped and ciculating contributions are separately large and only cancel upon integration over phase space. Nonetheless the total explicit coefficient is zero and this leads to an alternate interpretation of $T_{13}$ : the pinch effect is a collisional process involving circulating particles. This interpretation provides the link with the bootstrap current. However, there is no connection, whatever, with the original Ware effect.

The question is now reduced to understanding the implicit flows. Recall that these arose from the first order (in $\rho_{p} / a$ ) parts of the collision operator, or cross processes of the form

$$
\begin{align*}
& \frac{\partial}{\partial J_{3}} e_{3} \cdot D \cdot \frac{\partial}{\partial J_{\perp}},  \tag{5.67}\\
& \frac{\partial}{\partial J_{\perp}} \cdot D \cdot e_{3} \frac{\partial}{\partial J_{3}}, \tag{5.68}
\end{align*}
$$

relfecting correlation in the scattering process between jumps in radius and jumps in velocity. This correlation occurs only for circulating particles. The operator (5.67) gives a radial flux when operating on a perturbed $f_{1}$, that carries a current. Operator (5.68), acting on $f_{0}$. drives a current carrying perturbation. The perturbed $f_{1}$ resulting from this process (5.68) is determined by an equation of the form (5.37). Since both the drive $C_{1}\left(f_{0}\right)$ and the restoring force operator, $C_{o}\left(f_{1}\right)$, are proportional to the collision frequency, $\nu_{e i}$, the resulting $f_{1}$ will be independent of $\nu_{e i}$. The resulting bootstrap cocfficients $T_{31}^{i}$ and $T_{32}^{i}$ are also independent of $\nu_{e i}$. This does not, of course, contradict the notion that the underlying process in Eq. (5.68) is collisional.

These processes and their consequent fluxes can be understood simply with the aid of Fig. (2), comparing representative orbits for different types of particles. Consider now, two particles, initially well-circulating, moring in opposite directions along the magnetic field. Both have orbits lying very nearly on the flux surface $\psi$.

As these particles scatter toward trapped space, under the influence of collisions, their orbits change as indicated in the figure. The $\sigma=-1$ particle scatters to an orbit whose average surface is shifted inward relative to $\psi$ while the $\sigma=+1$ particle scatters out. This is the origin of the correlation betwen parallel velocity sign and radial step. A radial flow will result whenver the perturbed distribution has unequal fractions of $\sigma=-1$ and $\sigma=+1$ particles, or in other words, when the pertrubed distribution of circulating particles carries a current. The current driven by the toroidal electric field has an excess of $\sigma=-1$ particles and drives an inward radial flow. This process, in the alternate interpretation, causes the pinch effect. It is due entrely to circuiating particles.

Now invert the process just described. that is, take two marginally circulating particles, oppositely directed along the magnetic field and scatter them back toward the well circulating state. The $\sigma=-1$ particle started on an inner average surface and ended up on $\psi$. The $\sigma=+1$ particle started on an outer average surface and also ended up on $\psi$. With a normal density gradient the result will be more $\sigma=-1$ than $\sigma=+1$ particles on the final $\psi$ surface, and thus an electric current. This is the mechanism behind the bootstrap current. It is the precise microscopic inverse to the process accounting for the pinch effect. One can then easily understand the Onsager symmetry, and there is no dilemma.

It might be noted that the bootstrap current, according to our explanation of the pinch effect, will also drive a radial flow. This is, in fact, the mechanism of the implicit diffusion flux $T_{11}^{i}$. Another relevant point is illustrated by the figure. Pitch angle scattering of trapped particles moves the bounce points around on the $\psi$ surface, but the average $\psi$,to first order in $\rho_{p} / a$, does not change. This is why the trapped particles do not contribute to the implicit fluxes.

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## FIGURECAPTIONS

Fig. 1. Schematic of the lines $\beta=$ const and the lines $s=$ const in a surface $\phi=$ const. The lines $s=$ const are generated by choosing an arbitrary surface $s=0$ nowhere tangent to a line of force and on each line of force $\phi=$ const, $\beta=$ const measuring off are length. It is evident from the figure that if the lines shear, then $J S$ is not parallel to $b$.

Fig. 2. Representative orbit projections for trapped and circulating particles. The dashed circle, $\psi$ surface, is the average surface for trapped particles and well circulating particles, $\lambda^{\prime} \ll \mathbf{1}$. In fact, the actual orbits for well circulating particles differ negligibly from $\psi$. Marginally circulating particle orbits are very distorted, resembling the inner half of a trapped particle banana orbit for the $\sigma=-1$ direction of parallel velocity, and the outer half of the banana for $\sigma=+1$. Average surfaces, $<\psi>$, for marginally circulating particles are displaced inward from $\psi$, for $\sigma=-1$, and outward for $\sigma+1$.

## APPENDIX A

## Identity of Transport Equations

We wish to relate the more conventional transport equations derived by Eulerian theories to the expressions obtained via the Lagrangian formulation. To this end note that on employing the Eulerian theory the flux surface average of the continuity equation can be expressed as

$$
\begin{equation*}
\frac{\partial}{\partial t} \int d^{3} r d^{3} v \delta\left(\psi-\psi^{\prime}\right) f+\frac{\partial}{\partial \psi^{1}} \int d^{3} r d^{3} v \delta\left(\psi-\psi^{\prime}\right) v_{d} \cdot(\nabla \psi) f=0 \tag{A-1}
\end{equation*}
$$

where $\boldsymbol{v}_{d}$ is given by the quasi-steady state limit of (2.26). It is readily shown that in this case

$$
\begin{equation*}
v_{d} \cdot \nabla \psi=-u \frac{\partial}{\partial s}\left(\frac{I}{\Omega}\right) \tag{A-2}
\end{equation*}
$$

where $I(\psi, t)=R B_{5}$. Clearly in the first term in (A-1) it is adequate to use $f_{0}$ and in the second term $f_{1}$. Let $V$ by the volume enclosed by a toroidal magnetic surface $\psi=\psi^{\prime}$, and let $V^{\prime}=d V / d \psi$ and $n(\psi, t)=\int d^{3} v f_{0}$. Then on introducing $E$ and $\mu$ Eq. (A-1) can be written

$$
\begin{equation*}
\frac{\partial}{\partial t}\left(V^{\prime} h\right)+\frac{\partial}{\partial \psi}\left(\frac{2 \pi}{m}\right)^{2} \int d E d \mu d s \frac{u I}{\Omega} \frac{\partial f_{1}}{\partial s}=0 \tag{A-3}
\end{equation*}
$$

Let an angular bracket be such that

$$
\begin{equation*}
<\frac{u I}{\Omega}>=\frac{\oint d s \frac{\hbar}{h}}{\oint \frac{d s}{u}}=\omega_{2} \oint d s \frac{I}{\Omega}=\oint d \theta_{2} \frac{u I}{\Omega} \tag{A-4}
\end{equation*}
$$

Then since $f_{1}$ is periodic in the basic periodicity in $s$ one can write (A-3) as

$$
\begin{equation*}
\frac{\partial}{\partial t}\left(V^{\prime} n\right)=\frac{\partial}{\partial \psi}\left(\frac{2 \pi}{m}\right)^{2} \int d E d \mu d s\left[\frac{u I}{\Omega}-\left\langle\frac{u I}{\Omega}\right\rangle\right] \frac{\partial f_{1}}{\partial s} \tag{A-5}
\end{equation*}
$$

But in the Eulerian theory $f_{l}$ obcys the kinctic equation

$$
\begin{equation*}
0=\frac{\partial}{\partial s}\left(\int_{1}-\frac{u I}{\Omega} \frac{\partial f_{o}}{\partial \psi}\right)+\frac{1}{u} \nabla_{v} \cdot \Gamma_{1}+\frac{\partial}{\partial E}\left(Z \epsilon b \cdot E f_{0}\right) \tag{A-6}
\end{equation*}
$$

where $\Gamma_{1}$ is the current density in velocity space correct to first order in the small parameter when (A-6) is inserted in (A-S) and use made of the relations $\partial f_{0} / \partial s=0$ and

$$
\begin{equation*}
\oint d s \frac{u I}{\Omega}\left[\frac{u I}{\Omega} \frac{\partial f_{0}}{\partial \psi}\right]=\oint d s\left[\frac{1}{2}\left(\frac{u I}{\Omega}\right)^{2} \frac{\partial f_{0}}{\partial \psi}\right]=0 \tag{A-7}
\end{equation*}
$$

on integrating out the perfect derivative with respect to $E$ there results

$$
\begin{equation*}
\frac{\dot{\partial}}{\partial t}\left(V^{\prime} n\right)=-\frac{\partial}{\partial \psi}\left(\frac{2 \pi}{m}\right)^{2} \int \frac{d E d \mu d s}{u}\left[\frac{u I}{\Omega}-\left\langle\frac{u I}{\Omega}\right\rangle\right] \nabla_{v} \cdot \Gamma_{1} \tag{A-8}
\end{equation*}
$$

which can be written as
$\frac{\partial}{\partial t} \int d^{3} r d^{3} v \delta\left(\psi-\psi^{\prime}\right) f_{0}=-\frac{\partial}{\partial \psi^{\prime}} \int d^{3} r d^{3} v \delta\left(\psi-\psi^{\prime}\right)\left[\frac{u I}{\Omega}-\left\langle\frac{u I}{\Omega}\right\rangle\right] \nabla_{v} \cdot \Gamma_{1}$
Consider now the result of integrating (3.1) with respect to $J_{1}$ and $J_{2}$ at fixed $J_{3}$. Since $\oint d^{3} \theta=1$ the result can be written

$$
\begin{equation*}
\frac{\partial}{\partial t} \int d^{3} \theta d^{3} J \delta\left(J_{3}-J_{3}^{\prime}\right) f_{o}=-\frac{\partial}{\partial J_{3}^{\prime}} \int d^{3} \theta d^{3} J \delta\left(J_{3}-J_{3}^{\prime}\right) \Gamma \cdot \nabla_{v} J_{3} \tag{A-10}
\end{equation*}
$$

But $d^{3} r d^{3} v=d^{3} \theta d^{3} J$ and one can write (2.68) as

$$
\begin{equation*}
J_{3}=2 \pi \frac{q}{c}\left[\psi+\frac{u I}{\Omega}-\left\langle\frac{u I}{\Omega}\right\rangle\right] \tag{A-11}
\end{equation*}
$$

Thus if we pick $J_{3}^{\prime}=2 \pi q / c \psi^{\prime}$, Eq. (A-10) can be written on expanding the $\delta$ function in a power series in the "small" quantity $u I / \Omega-\langle u I / \Omega\rangle$, cffectively in powers of the poloidal gyration radius,

$$
\begin{array}{r}
\frac{\partial}{\partial t} \int d^{3} r d^{3} v f_{0}\left\{\delta\left[2 \pi \frac{q}{c}\left(\psi-\psi^{\prime}\right)\right]+2 \pi \frac{q}{c}\left[\frac{u I}{\Omega}-\left\langle\frac{u I}{\Omega}\right\rangle\right] \delta^{\prime}\left[2 \pi \frac{q}{c}\left(\psi-\psi^{\prime}\right)\right]+\cdots\right\} \\
=\int d^{3} r d^{3} v\left(\nabla_{v} \cdot \Gamma_{1}\right)\left\{\delta\left[2 \pi \frac{q}{c}\left(\psi-\psi^{\prime}\right)\right]+2 \pi \frac{q}{c}\left[\frac{u I}{\Omega}-\left\langle\frac{u I}{\Omega}\right\rangle\right] \delta^{\prime}\left[2 \pi \frac{q}{c}\left(\psi-\psi^{\prime}\right)+\cdots\right]\right\} \tag{A-12}
\end{array}
$$

On using the properties $\delta(a x)=\frac{1}{u} \delta(x), \delta^{\prime}(a x)=\frac{1}{a^{2}} \delta^{\prime}(x)$ and $\int d^{3} v \nabla_{v} \cdot \Gamma_{1}=0$. and kecping only leading order non-vanishing terms, Eq. (A-12) yiclds (A-9), demonstrating the identity of the expressions
derived by the two formulations. Parallel derivations prevail for the other transport equations. The average terms involving $\langle u I / \Omega\rangle$, although important to the Lagrangian formulation and the dcomposition into explicit and implicit fluxes, nonetheless cancel out and do not appear in the net transport coefficients.



Figure 2

