

Presentation of AC Processor **ATCOR**

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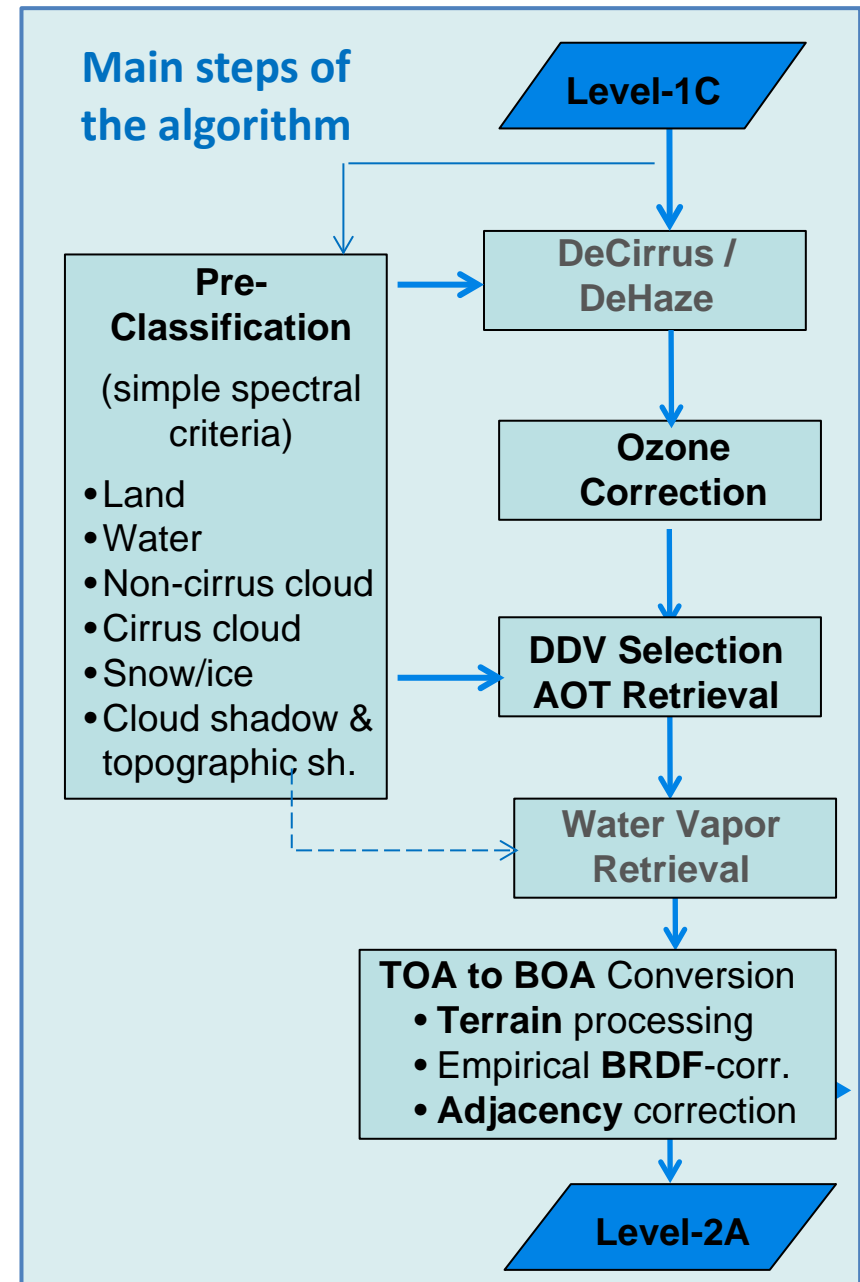
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Knowledge for Tomorrow

ATCOR Overview

- Processor developed by DLR, first version 1990, continually updated
- Multi-Mission tool, MS and HS satellite and airplane imagery, spectral region 400 – 2500 nm
- Atmospheric correction over land
- Processing on granule level for a single-time dataset
- IDL application
 - Interactive mode
 - Batch mode: configuration by *.inn text file



ATCOR: Inputs

- Level-1C ortho-image Top-Of-Atmosphere (TOA) radiance products
 - Sentinel-2: Reflectance to radiance conversion
- Pre-compiled database of atmospheric Look-up tables
 - Sentinel-2 and Landsat-8 aerosol models:
 - rural/continental & maritime & urban & desert
- Radiative Transfer code:
MODTRAN5.4 with HITRAN2013
- Optional DEM provided by user

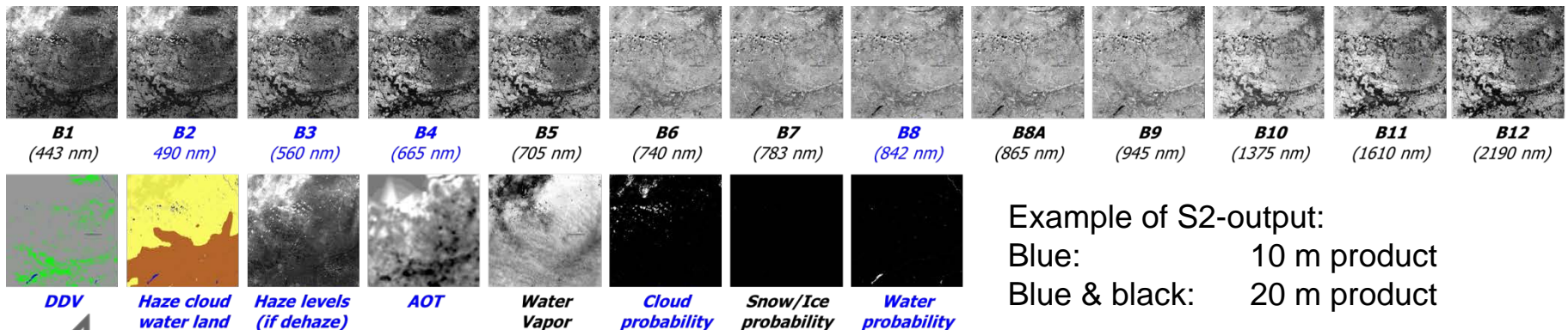
Look-up-table selection	Default
Aerosol type	Rural
Atm. profile	Set by date (summer, winter)

cfg. parameter	Default
surface elevation	set if no DEM



ATCOR: Outputs

- Sentinel-2 (13-band cube 20m; 4-band cube 10m)
- Landsat (30m)
- Bottom-Of-Atmosphere (BOA) corrected reflectance
- Aerosol Optical Thickness@550 nm (AOT) map
- Sentinel-2: Water Vapour (WV) map (resampled 20 m)
- Dense Dark Vegetation (DDV) map
- Haze-Cloud-Water map
- Quality Indicators for cloud, snow and water probabilities



ATCOR: Processing steps and parameters

- Ozone correction:
 - Applied to bands in 450 – 800 nm with precalculated MODTRAN LUTs
 - Ref: Richter et al., Int. J. Remote Sensing, Vol. 35, 8044-8056 (2014)
- Optional cirrus and haze removal:
 - Cirrus removal: uses bands 1.38 μm and 0.66 μm , correction is applied to all bands
 - Haze removal: uses blue/green bands correction for bands 0.4 – 2.5 μm
 - Makarau et al., IEEE TGRS, Vol. 52, 5895-5905 (2014)
 - Makarau et al., IEEE GRSL, Vol. 13, 379-383 (2016)

cfg. parameter	Default
ozone column	
Sentinel-2	from meta data file (ECMWF product TCO3)
Landsat-8	user input, else: 331 DU
Cirrus correction	on
Haze removal	off



AOT(550nm) Retrieval, Part 1: DDV Selection

- S2: uses B12(2.2 μm) & B8a(865 nm)
L8: uses B7(2.2 μm) & B5(865 nm)

cfg. parameter	Default
Default/Start VIS	23 km

- compute surface $\rho(2.2\mu\text{m})$ for VIS=23km excluding water.
(Min. distance of DDV-pixels to clouds = 500 m) Then
 - $0.01 < \rho(2.2\mu\text{m}) < 0.05$ If less than 5% of scene pixels DDV, then
 - $0.01 < \rho(2.2\mu\text{m}) < 0.10$ If less than 5% of scene pixels DDV, then
 - $0.01 < \rho(2.2\mu\text{m}) < 0.12$
 - If $< 2\%$ DDV pixels, then set VIS to default value
(VIS=23 km corresponds to AOT=0.32)
 - Check water bodies: if $\rho(\text{water}, 865 \text{ nm}) < 0$ for more than 1% of pixels, then
 - decrease AOT550 until $\rho(\text{water}, 865 \text{ nm}) \geq 0$



AOT(550nm) Retrieval, Part 2: spectral correlation

Spectral correlation for DDV:

S2: B2(490 nm), B4(665 nm) & B12(2.2 μm)

L8: B2(490 nm), B4(665 nm) & B7(2.2 μm)

- $\rho(0.665\mu\text{m}) = 0.5 \rho(2.2\mu\text{m})$
- $\rho(0.490\mu\text{m}) = 0.5 \rho(0.665\mu\text{m}) + 0.005$
- $\rho(0.443\mu\text{m}) = 0.8 \rho(0.490\mu\text{m})$
- calculate VIS [AOT] from $\rho(0.665\mu\text{m})$
- Non-reference pixels are assigned the average AOT550 of the DDV pixels (default) or spatial triangulation
- Smoothing of AOT550 map to suppress noise (3 km box)
- Rescale path radiance to match $\rho(0.443\mu\text{m},\text{DDV})$ & $\rho(0.490\mu\text{m},\text{DDV})$

cfg. parameter	Default
Visibility	Average over VIS of DDV
Ratio red / _swir	0.5
Ratio blue / _red	0.5



Water Vapor Retrieval

- Atmospheric Precorrected Differential Absorption (APDA) technique
- S2 Bands B8a (865 nm) and B9 (945 nm)

cfg. parameter	Default
WV correction	on
WV over water	Land average
Smooth WV map	100 m

$$R_{APDA} = \frac{L(\rho, 945) - L_p(945, W)}{L(\rho, 865) - L_p(865)}$$

$$R_{APDA}(W) = a_0 \exp(-a_1 W^{a_2})$$

Solving for W :
$$W = \left(\frac{\ln(R_{APDA} / a_0)}{-a_1} \right)^{1/a_2}$$

Equations are iterated using the precalculated LUTs with $W=0.4 - 5.0$ cm

Ref: Schläpfer et al. RSE, Vol. 65, 353-366 (1998)



Surface Reflectance Retrieval

cfg. parameter	Default
Adjacency range	1 km
BRDF correction	No

- All bands except cirrus band

- Flat terrain, 3 steps:

1. solve RT equation for ρ :

$$L = L_p + \frac{T E_g \rho^{(1)} / \pi}{1 - \rho^{(1)} s}$$

2. Calculate average (1 – 2 km box):

$$\bar{\rho} = \sum_{i,k=1}^N \rho^{(1)}(i,k)$$

3. Adjacency correction: $\rho(x,y) = \rho^{(1)}(x,y) + q \left\{ \rho^{(1)}(x,y) - \bar{\rho}(x,y) \right\}$

- Mountainous terrain: complex, see references for details, DEM required, includes empirical BRDF-correction



Processing time (Intel 3.5 GHz PC, Ubuntu 14.04)

- Landsat-8 OLI (7711 x 7861 pixels), flat terrain: 2 min
- Rugged terrain (with DEM) 8 min

- Sentinel-2: import of jp2 files 4 min
- conversion into layer-stacked radiance cubes: 13-bands at 20m
and 4 bands at 10m

- S2 surface reflectance:
 - 13-band cube (5490 x 5490, 20m) 3 / 6 min (flat/DEM)
 - 4-band cube (10980 x 1098, 10m) 2 / 4 min (flat/DEM)



Selected References ATCOR

- Richter, R., Int: J. Remote Sensing, Vol. 11, 159-166, 1990
- Richter, R., Applied Optics, Vol. 37, 4004-415, 1998
- Richter, R., et al., IEEE TGRS, Vol. 49, 1772-1780, 2011
- Richter, R., et al., IJRS, Vol. 32, 2931-2941, 2011
- <https://www.rese-apps.com>, ATCOR manual, 2016



MAJA - MACCS-ATCOR Joint Algorithm

- Motivation: combination of strengths of MACCS (CNES) and ATCOR (DLR) in a close cooperation of the related developer teams
- Enhancement of ATCOR and MACCS components for an optimized and efficient software solution
- Integration of ATCOR modules into MACCS framework of multi-temporal processing
- Preparation of operational MAJA environment at CNES and DLR in the context of the Sentinel-2 mission



Thank you! Bye Bye!



ATCOR: Empirical BRDF correction model for rugged terrain (DEM required)

- Empirical BRDF correction with factor (G) according to following equation:

$$G = \{ \cos(\beta_i) / \cos(\beta_T) \}^b \geq g$$

- where: β_i : local solar zenith angle (from metadata, section 0)
 β_T : threshold for surface reflectance (determined by program)
 b : exponent (set via options below)
 g : Lower boundary of BRDF correction, recommended between 0.2 and 0.25 (configuration parameter)
- Options to be selected: next slide



ATCOR: BRDF options

cfg. parameter	Default
BRDF model	21

- Options to be selected:

1: correction with cosine of local solar zenith angle ($b=1$)

2: correction with $\sqrt{\cos}$ of local solar zenith angle ($b=1/2$)

11: "weak" correction dependent on surface type

for soil/sand with $b=1$

for vegetation: $b=1/3$ ($\lambda < 720$ nm), and $b=3/4$ ($\lambda > 720$ nm)

12: "strong" correction dependent on surface type

for soil/sand $b=1$

for vegetation $b=1.0$ ($\lambda < 720$ nm), and $b=3/4$ ($\lambda > 720$ nm)

21: "weak" correction dependent on surface type

for soil/sand with $b=1/2$

for vegetation with $b=1/3$ ($\lambda < 720$ nm), and $b=3/4$ ($\lambda > 720$ nm)

This is the recommended standard yielding good results in most cases.

22: "strong" correction dependent on surface type

for soil/sand with $b=1/2$

for vegetation with $b=1.0$ ($\lambda < 720$ nm), and $b=3/4$ ($\lambda > 720$ nm),

