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Risk Aggregation in the presence of Discrete Causally Connected Random Variables

Peng Lin[†], Martin Neil[†] and Norman Fenton[†]

ABSTRACT

Risk aggregation is a popular method used to estimate the sum of a collection of financial assets or events, where each asset or event is modelled as a random variable. Applications include insurance, operational risk, stress testing, and sensitivity analysis. In practice the sum of a set of random variables involves the use of two well-known mathematical operations: n -fold convolution (for a fixed number n) and N -fold convolution, defined as the compound sum of a frequency distribution N and a severity distribution, where the number of constant n -fold convolutions is determined by N . Where the severity and frequency variables are independent, and continuous, currently numerical solutions such as, Panjer's recursion, Fast Fourier transforms and Monte Carlo simulation produce acceptable results. However, they have not been designed to cope with new modelling challenges that require hybrid models containing discrete explanatory (regime switching) variables or where discrete and continuous variables are inter-dependent and may influence the severity and frequency in complex, non-linear, ways. This paper describes a *Bayesian Factorization and Elimination* (BFE) algorithm that performs convolution on the hybrid models required to aggregate risk in the presence of causal dependencies. This algorithm exploits a number of advances from the field of Bayesian Networks, covering methods to approximate statistical and conditionally deterministic functions to factorize multivariate distributions for efficient computation. Experiments show that BFE is as accurate on conventional problems as competing methods. For more difficult hybrid problems BFE can provide a more general solution that the others cannot offer. Additionally, the BFE approach can be easily extended to perform deconvolution for

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the purposes of stress testing and sensitivity analysis in a way that competing methods do not.

Keywords: Risk aggregation; Bayesian Factorization and Elimination; Convolution; Deconvolution; Causal dependency modelling; Bayesian networks; Dynamic Discretization.

1. MOTIVATION AND INTRODUCTION

Risk aggregation is a popular method used to estimate the sum of a collection of financial assets or events, where each asset or event is modelled as a random variable. Existing techniques make a number of assumptions about these random variables. Firstly, they are almost always continuous. Secondly, if they are independent then they are identically distributed. Thirdly, should they be dependent, these dependencies are best represented by correlation functions, such as copulas (Embrechts, 2009) (Nelsen, 2007), where marginal distribution functions are linked by some dependence structure. These statistical methods have tended to model associations between variables as a purely phenomenological artefact extant in historical statistical data. Recent experience, at least since the beginning of the financial crisis in 2007, has amply demonstrated the inability of these assumptions to handle non-linear effects or “shocks” on financial assets and events, resulting in models that are inadequate for prediction, stress testing and model comprehension (IMF, 2009), (Laeven & Valencia, 2008).

It has been extensively argued that modelling dependence as correlation is insufficient, since it ignores any views that the analyst may, quite properly, hold about those causal influences that help generate and explain the statistical data observed (Meucci, 2008), (Rebonato, 2010). Such causal influences are commonplace and permeate all levels of economic and financial discourse. For example, does a dramatic fall in equity prices cause an increase in equity implied volatilities or is it an increase in implied volatility that causes a fall in equity prices? The answer is trivial in this case, since a fall in equity prices is well known to affect implied volatility, but correlation alone contains no information about the direction of causation. To incorporate causation we need to involve the analyst or expert and “fold into” the model views of how discrete events interact and the

effects of this interaction on the aggregation of risk. This approach extends the methodological boundaries last pushed back by the celebrated Black–Litterman model (Black & Litterman, 1991). In that approach a risk manager’s role is as an active participant in the risk modelling, and the role of the model is to accommodate their subjective “views”, expressed as Bayesian priors of expectations and variances of asset returns. In this paper we aim to represent these Bayesian “views” in an explicit causal structure, whilst providing the computational framework for solutions. Such causal models would involve discrete explanatory (regime switching) variables and hybrid mixtures of inter-dependent discrete and continuous variables. A causal risk aggregation model might incorporate expert derived views about macro-economic, behavioural, operational or strategic factors that might influence the assets or events under “normal” or “abnormal” conditions. Applications of the approach include insurance, stress testing, operational risk and sensitivity analysis.

At its heart risk aggregation requires the sum of n random variables. In practice this involves the use of two well-known mathematical operations: n -fold convolution (for a fixed value of n) and N -fold convolution (Heckman & Meyers, 1983), defined as the compound sum of a frequency distribution, N , and a severity distribution, S , where the number of constant n -fold convolutions is determined by N , stochastically. Currently popular methods such as Panjer’s recursion (Panjer 1981), Fast Fourier transforms (Heckman and Meyers 1983) and Monte Carlo simulation (Meyers 1980) perform risk aggregation numerically using parameters derived from historical data to estimate the distributions for both S and N . Where S and N are independent, and continuous, these approaches produce acceptable results. However, they have not been designed to cope with the new modelling challenges outlined above. In the context of modelling general dependencies among severity variables, a popular approach is to use copulas, both to model the dependent variables and to perform risk aggregation.

Our aim then is to show how we can carry out a stochastic risk aggregation (N -fold convolution) in a causal Bayesian framework, in such a way that subjective views about inter-dependencies can be explicitly modelled and numerically evaluated i.e. where discrete and continuous variables are inter-dependent and may influence N and S in com-

plex, non-linear ways. We see this as the first of many financial modelling problems that are amenable to this new approach.

This paper describes a *Bayesian Factorization and Elimination* (BFE) algorithm that performs convolution on the hybrid models required to aggregate risk in the presence of causal dependencies. This algorithm exploits a number of advances from the field of Bayesian Networks (BNs), covering methods to approximate statistical and conditionally deterministic functions and to factorize multivariate distributions for efficient computation.

Section 2 provides an overview of popular methods for risk aggregation. Section 3 describes BN technology with a view to explaining some of the core foundational algorithms used in this paper. The BFE convolution algorithm is described in Section 4, showing how it builds and extends on the standard BN algorithms presented in Section 3. Section 5 presents a version of BFE that performs deconvolution and Section 6 presents experimental results showing the performance of BFE. Section 7 concludes the paper.

2. RISK AGGREGATION

An encyclopaedic overview of the current state of the art in risk aggregation is presented in , (McNeil, Frey, & Embrechts, 2010). The general aggregation formula for fixed, n , assets, is:

$$T = S_0 + S_1 + \dots + S_n \tag{2.1}$$

where T is the sum of n asset valuations and each S_i is from the same common continuous distribution f_x , which can be thought of as a return (severity) distribution S . This is called an *n-fold* convolution. If $S \sim f_x$ and if we have a variable number of assets, N , then (2.1) can be rewritten as an *N-fold* convolution:

$$f_T(x) = \sum_{j=0}^{\infty} f^{*j}(x)P(N = j) \tag{2.2}$$

where $f^{*j}(x) = \int_0^{\infty} f^{*(j-1)}(x-y)f(dy)$ is a recursive n -fold convolution on S . We

can therefore rewrite (2.2) in a discrete form: $P(N = j) = a_j$, for $j = 0, 1, \dots, L$, where L is the length of discretized frequency N . The following expressions hold:

$$P(T) = a_0P(T_0) + a_1P(T_1) + \dots + a_LP(T_L) \quad (2.3)$$

$$T_0 = S_0, T_1 = S_0 + S_1, \dots, T_L = S_0 + S_1 + \dots + S_L \quad (2.4)$$

where each T_j is a constant n -fold convolution. The formula (2.3) represents a mixture distribution where the mixture components consist of mutually exclusive variables, themselves composed using the conditionally deterministic functions stated in (2.4).

For the sake of clarity in insurance, and similar, applications N is interpreted as a frequency distribution, and S is defined as a severity (loss) distribution.

General numerical solutions to computing the aggregate distribution include Panjer's recursion (Panjer, 1981), Fast Fourier transform (Heckman & Meyers, 1983). and Monte Carlo (MC) simulation (Meyers, 1980).

In this paper severity variables can depend on discrete explanatory variables with dependencies expressed via conditioning in Bayesian networks. This contrasts with the classic approach for dependency modelling among severity variables using copulas. Rather than use dependency and conditioning the copula approach models the dependency structure independently with marginal functions, which supports the construction of high dimensional models.

In the context of copula based risk aggregation Bruneton (Bruneton, 2011) proposes the use of hierarchical aggregation using copulas. Also, Arbenz (Arbenz & Canestraro, 2012) proposes hierarchical risk aggregation based on tree dependence modelling using step-wise low dimensional copulas, and also gives a sample reordering algorithm for numerical approximation. Brechmann (Brechmann, 2014) suggests hierarchical Kendall copulas to achieve flexible building blocks, where risk aggregation is supported by the Kendall function. These approaches capture the joint dependencies from a hierarchical structure and exploit use of small building blocks. In contrast to correlation modelling,

our work assumes causality and dependency, where joint dependency is decomposed by conditional dependencies using the Bayesian network framework.

3. BAYESIAN NETWORKS

3.1. Background

A Bayesian Network (BN)(Jensen & Nielsen, 2009), (Pearl, 1993), (Lauritzen 1996) consists of two main elements:

1. *Qualitative*: This is given by a directed acyclic graph (DAG), with nodes representing random variables, which can be discrete or continuous, and may or may not be observable, and directed arcs (from parent to child) representing causal or influential relationships between variables.
2. *Quantitative*: A probability distribution associated with each node X . For a node with parents this is a Conditional Probability Distribution (CPD), $P(X | pa(X))$ that defines the probabilistic relationship of node given its respective parents $pa(X)$. For each node X without parents, called root nodes, this is their marginal probability distribution $P(X)$. If X is discrete, the CPD can be represented as a Node Probability Table (NPT), $P(X | pa(X))$, which lists the probability that X takes, on each of its different values, for each combination of values of its parents $pa(X)$. For continuous variables, the CPDs represent conditional probability density functions.

Together, the qualitative and quantitative parts of the BN encode all relevant information contained in a full joint probability model. The conditional independence assertions about the variables, represented by the absence of arcs, allow decomposition of the underlying joint probability distribution as a product of CPDs. Specifically:

$$P(X_1, \dots, X_n) = \prod P(X_i | pa(X_i))$$

This significantly reduces the complexity of inference tasks on the BN (Spiegelhalter and Lauritzen 1990) (Fenton and Neil 2012)(Fenton & Neil, 2012).

BNs have already been employed to address financial problems. For example, in (Cowell, Verrall, & Yoon, 2007) BNs were used for overall loss distribution and making predictions for insurance; in (Martin Neil & Fenton, 2008) BNs were used for modeling operational risk in financial institutes, while the work in (Politou & Giudici, 2009) combines Monte Carlo simulation, graphic models and copula functions to build operational risk models for a bank. Likewise, (Rebonato, 2010) discusses a coherent stress testing approach using BNs.

We have chosen to use BNs because the latest algorithms can model causal dependencies between hybrid variables during inference, to produce approximate posterior marginal distributions for the variables of interest. Also, by virtue of Bayes' Theorem they are agnostic about causal direction and can perform inference from cause to effect and vice versa (or convolution to de-convolution, as is the case here). Until very recently BN tools were unable to properly handle non-Gaussian continuous variables, and so such variables had to be discretized manually, with inevitable loss of accuracy. A solution to this problem was described in (Neil, Tailor and Marquez 2007) based on an extension of the Junction Tree (JT) inference algorithm and is described below in Section 3.2. The result of inference is a set of queries on the BN in the form of univariate or multivariate posterior marginal distributions. This allows the approximate solution of classical Bayesian statistical problems, involving continuous variables, as well as hybrid problems involving both discrete and continuous variables, without any restriction on distribution family or any requirement for conjugacy. This scheme iteratively converges on the posterior solution and has provided highly efficient solutions in a number of domains (Neil, Marquez and Fenton 2010) (Fenton & Neil, 2012).

Both exact and approximate inference in BNs is NP-hard (Cooper & Herskovits, 1992) and the efficiency of the JT architecture depends on the size of the clusters in the associated tree. To help reduce conditional probability table (CPT) size we employ a factorization scheme called binary factorization (described below in Section 3.3) to re-

duce the size, and associated computation time required, for continuous variables in the model (Neil, Chen, & Fenton, 2012).

We have used AgenaRisk (AgenaRisk 2014), a commercial BN package and extended it to incorporate the new BFE algorithm to carry out the experiments described in Section 4.

3.2. Dynamic Discretization (DD) on hybrid BNs

Static discretization has historically been used to approximate the domain of the continuous variables in a BN using predefined, fixed piecewise constant partitions. This approximation will be accurate so long as the posterior high density region remains in the specified domain during inference. However the analyst will not know, in advance, which areas of the domain require the greater number of intervals, ultimately resulting in an inaccurate posterior estimate. Dynamic Discretization (DD) is an alternative discretization approach that searches for the high density region during inference and adds more intervals where they are needed whilst removing intervals where they are not (by merging or deletion). The algorithm iteratively discretizes the target variables by the convergence of relative entropy error threshold .

Formally, let X be a continuous node in the BN. The range of X is denoted by Ω_x , and the probability density function of X , is denoted by f_x . The idea of discretization is to approximate f_x as follows:

1. Partition Ω_x into a set of interval $\Psi_x = \{w_j\}$,
2. Define a locally constant function f_x on the partitioning intervals.

As in , we estimate the relative entropy error induced by the discretized function using an upper bound of the Kullback-Leibler (KL) metric between two density functions f and g :

$$D(f \parallel g) = \int f(x) \log \frac{f(x)}{g(x)} dx \quad (3.1)$$

Under the KL metric the optimal value for the discretized function \tilde{f}_x is given by the mean of the function in each of the intervals of the discretized domain. The discretization task reduces then to finding an optimal partition set $\hat{\Psi}_x$.

DD searches Ω_x for the most accurate specification of the high-density regions given the model and the evidence, calculating a sequence of discretization intervals in Ω_x iteratively. At each stage in the iterative process, a candidate discretization, $\Psi_x = \{w_j\}$, is tested to determine whether the relative entropy error of the resulting discretized probability density \tilde{f}_x is below a given threshold, defined according to some stopping rule. After each variable in the model is discretized the inference algorithm, such as Junction Tree, calculates the joint posterior distributions for all variables in the model. This gives a new posterior probability density for all variables and these are then re-discretized. This process continues until the stopping rule is triggered.

3.3. Binary Factorization (BF)

The cost of using off-the-shelf BN algorithms to calculate *N-fold* convolution can be computationally expensive. The conditional probability density expression of node T is defined by all of its parent nodes by Equation (2.1):

$$T_n = S_0 + S_1 + \dots + S_n$$

If each node has a node state of size m and the total number of parents is n , then the CPT for T has a total size of m^{n+1} given the intervals computed under DD. To help reduce the CPT size we employ binary factorization to factorize the BN graph according to the statistical and deterministic functions declared in it.

To illustrate the BF process, we consider constant *n-fold* convolution models for both the independent and common cause case, as represented by BNs $G1$ and $G2$ respectively in Figure 2. This is just Equation 2.1.

After employing binary factorization, the BNs $G1$ and $G2$ are transformed into $G1'$ and $G2'$ respectively as shown in Figure 3. In Figure 2 $G1$ shows the *N-fold* convo-

lution when severities are independent and identically distributed. $G2$ denotes the N -fold convolution when severities are dependent on a discrete common cause random vector, C .

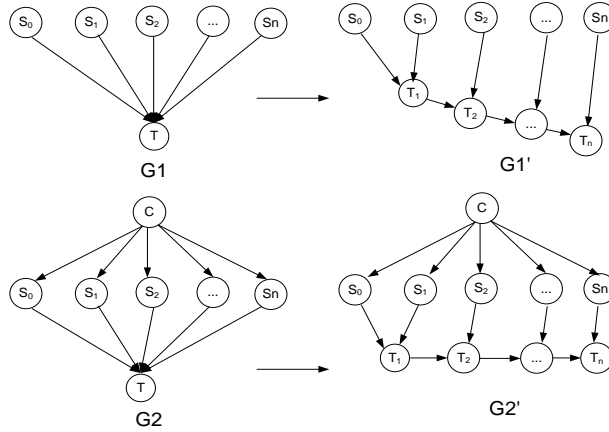


Figure 3 BN models of N -fold convolution of i.i.d. severity variables ($G1$) and of common cause version ($G2$) with accompanying binary factorized versions ($G1'$ and $G2'$)

BF ensures that, in the transformed BN, each variable's NPT expression involves a maximum of two continuous parent variables in the transformed BN. This produces a maximal discretized NPT of size m^3 .

Theoretical equivalence of $G1$ and $G1'$ with the resulting BN models $G2$ and $G2'$ is demonstrated in (Neil et al., 2012).

4. BAYESIAN FACTORIZATION AND ELIMINATION (BFE)

To solve the N -fold convolution problem using off-the-shelf BN technology is not possible because we cannot compute $G1$ and $G2$ effectively from the conditional dependency structures defined in Figure 3. This is because, even with binary factorization, either the model size is prohibitively large (in the case of $G1$) or the junction tree cluster sizes would be exponential in size (as with $G2$). Therefore, the original contribution of this paper is to produce an iterative factorized approach to the computation that scales up to arbitrary sized models. This approach is called *Bayesian Factorization and Elimination* (BFE). This algorithm performs convolution on the hybrid models required to ag-

gregate risk in the presence (or absence) of causal dependencies. This algorithm exploits a number of advances from the field of BNs already described in Section 3. We refer to these advances as the BN engine and they are shown in the overall algorithm architecture in Figure 4.

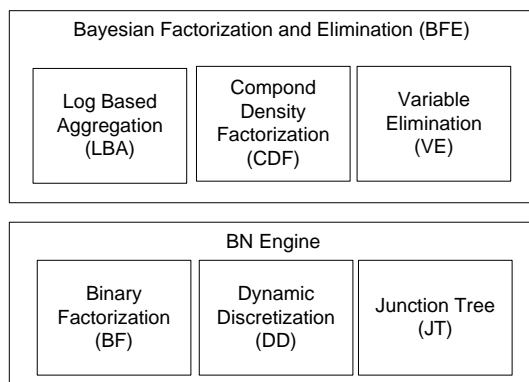


Figure 4 Architecture of BN algorithms

The BFE algorithm contains three separate steps, each performing specific optimizations:

1. **Log Based Aggregation (LBA):** this algorithm computes equation (2.4), the n -fold convolution, in a log based pattern that can be more efficient than aggregation by straight summation.
2. **Variable Elimination (VE):** variables are iteratively eliminated during LBA process, by which we can achieve greater computation efficiency for calculating arbitrary constant n -fold convolutions.
3. **Compound Density Factorization (CDF):** the compound sum equation (2.3) can be factorized by this algorithm in order to reduce large node probability tables into smaller ones. CDF is similar to binary factorization except that in CDF we introduce one more intermediate variable (a Boolean node) for weighting the compound density combination at each step in the aggregation process.

4.1. Log Based Aggregation (LBA)

In equation (2.3) each $T_i, i = 1, \dots, n$ is the sum of its parent variables T_{i-1} and S_i , and the aggregation process simply involves repeated summations of the same variable S_i .

As binary factorization proceeds intermediate variables F_j are created to aggregate every two parents, creating a hierarchy until the total aggregate, T , is computed. An example, in the presence and absence of common cause vector is shown in Figure 5.

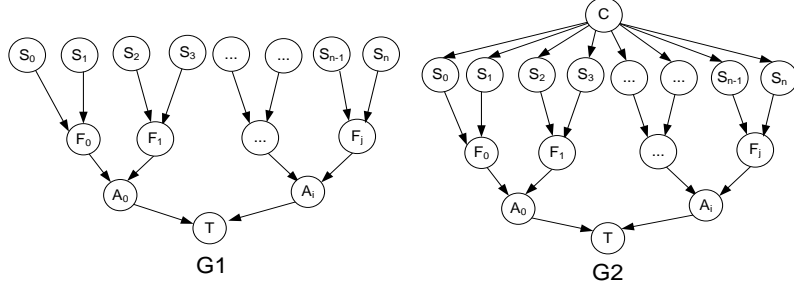


Figure 5 G1 and G2 BNs binary factorized for aggregation

This approach to aggregation is computationally expensive since all the variables are entered and computed in the BN explicitly. Log based aggregation simply computes and subsequently reuses prior computed results recursively, so that in each subsequent step we can reuse results from previous steps, without having to create the whole BN. The resulting process is $O(\log_2 n)$.

4.2. Variable Elimination (VE)

The aim of Variable Elimination (VE) is to remove nodes from a BN, G , that do not belong to a query set, Q , containing only the variables of interest, by a process of marginalization. Here we use variable elimination to reduce the number of variables we handle but add additional steps to exploit repeated structure in the binary factorized model. We do not need, therefore, to explicitly manipulate the whole BN, because we are not interested in setting arbitrary query variables or conditioning evidence. Instead we iterate through the binary factored model, progressively creating subsets of the aggregation hierarchy that can be reused recursively, eliminating nodes and reusing parts as we go.

We first consider a full binary factorized BN and use this to identify variables that can be eliminated and query sets necessary during VE. In the simple case for an n -fold convolution for independent i.i.d. severity variables, the graph $G1'$ in Figure 3 denotes

the binary factorized form of the computation of $T_n = \sum_{j=0}^n S_j$ after introducing the intermediate binary factored variables $\{T_1, T_2, \dots, T_{n-1}\}$. The marginal distribution for T_n has the form:

$$\begin{aligned}
P(T_n) &= \sum_{(S_0, \dots, S_n, T_1, \dots, T_{n-1})} P(S_0, S_1, \dots, S_n, T_1, T_2, \dots, T_{n-1}, T_n) \\
&= \sum_{(S_0, \dots, S_n, T_1, \dots, T_{n-1})} P(T_n | T_{n-1}, S_n) P(T_{n-1} | T_{n-2}, S_{n-1}) \dots P(T_1 | S_0, S_1) P(S_0) P(S_1) \dots P(S_n)
\end{aligned} \tag{4.1}$$

(Exploiting the conditional independence relations in Figure 3)

Notice that every pair of parent variables T_i and S_{i+1} is independent in this model and we can marginalize out each pair of T_i and S_{i+1} from the model separately. Equation (4.1) can be alternatively expressed as predefined ‘query blocks’:

$$P(T_n) = \sum_{T_{n-1}, S_n} P(T_n | T_{n-1}, S_n) \left\{ \dots \left\{ \sum_{T_1, S_2} P(T_2 | T_1, S_2) \left\{ \sum_{S_0, S_1} P(T_1 | S_0, S_1) P(S_0) P(S_1) \right\} P(S_2) \right\} \dots \right\} P(S_n) \tag{4.2}$$

So, using (4.2) we can recursively marginalize out, i.e. eliminate or prune, each pair of parents T_i and S_{i+1} from the model. For example, the elimination order in (4.2) could be: $\{S_0, S_1\}, \{T_1, S_2\} \dots \{T_{n-1}, S_n\}$. The marginal distribution of T_n , i.e. the final query set, is then yielded at the last elimination step.

In order to illustrate the recursive BN graph operations, required during VE, consider Figure 3 and BN G_1 . The first few steps involved are shown in Figure 6. At each stage we reuse the same graph structures and expressions for graphs $\{K_1, K_2, K_3\}$ and $\{L_1, L_2, L_3\}$. We can proceed through the binary factorized BN, computing the marginal distributions for the query set, removing elimination sets and repeating the process until we exhaust the variable list.

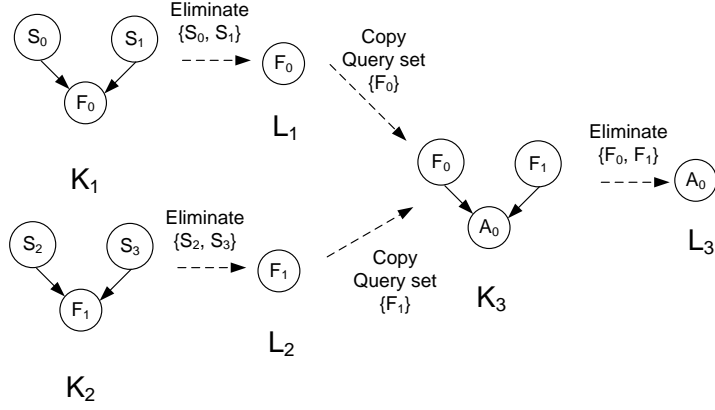


Figure 6 VE process applied to part of BN G_1

However, in the case where common cause dependencies are present in the BN, as illustrated by G_2 in Figure 3, additional care is needed during VE. Here the elimination set does not simply consist of leaf nodes that can be eliminated directly since we have a common parent node, C , that we want to preserve in the query set at each step. To help highlight how the VE process operates in the presence of common cause variables consider BN G_2' in Figure 3 and compute the posterior marginal distribution for T_2 . The marginal distribution for T_2 has the form (4.3):

$$\begin{aligned}
 P(T_2) &= \sum_{C, S_0, S_1, S_2, T_1} P(T_2 | T_1, S_2) P(T_1 | S_0, S_1) P(S_0 | C) P(S_1 | C) P(S_2 | C) P(C) \\
 &= \sum_{C, S_2, T_1} P(T_2 | T_1, S_2) P(S_2 | C) P(C) \left\{ \sum_{S_0, S_1} P(T_1 | S_0, S_1) P(S_0 | C) P(S_1 | C) \right\}
 \end{aligned} \tag{4.3}$$

We first want to eliminate S_0 and S_1 by marginalizing them:

$$P(T_1 | C) = \sum_{S_0, S_1} P(T_1 | S_0, S_1) P(S_0 | C) P(S_1 | C) \tag{4.4}$$

The marginal of T_2 can now be expressed along with C , T_1 and S_3 alone:

$$P(T_2) = \sum_{C, S_2, T_1} P(T_2 | T_1, S_2) P(S_2 | C) P(T_1 | C) P(C)$$

Next we eliminate S_2 and T_1 :

$$P(T_2 | C) = \sum_{T_1, S_2} P(T_2 | T_1, S_2) P(S_2 | C) P(T_1 | C) \quad (4.5)$$

In general, by variable elimination, we obtain the conditional distribution for each variable T_{n-1} (the sum of n severity variables) with the form:

$$P(T_{n-1} | C) = \sum_{T_{n-2}, S_{n-1}} P(T_{n-1} | T_{n-2}, S_{n-1}) P(T_{n-2} | C) P(S_{n-1} | C) \quad (4.6)$$

Since (4.6) specifies the conditional distribution for variable $T_{n-1} | C$, and therefore the posterior marginal distribution for the target n -fold convolution T_{n-1} , the aggregate total, is obtained by marginalizing out C .

In order to explain the VE algorithm, in terms of graph manipulation, in the common cause case we step through a 3 -fold convolution. Figure 7 (a) depicts a 3 -fold convolution model, binary factorized (from G to G') and then subject to VE, resulting in reduced the BN V . The VE steps are shown in Figure 7 (b), which, although operating on subsets of G , result in the same graph i.e. $L_2 = V$.

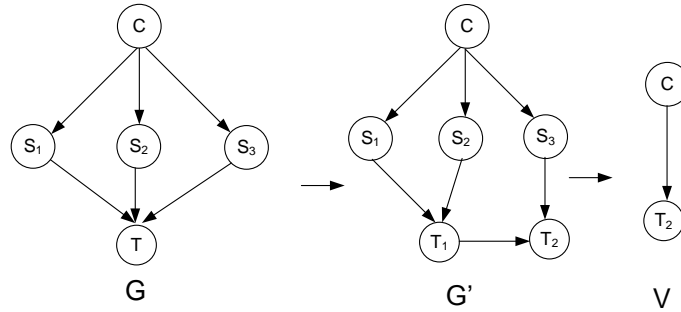


Figure 7 (a) Simple common cause model binary factorization and VE process

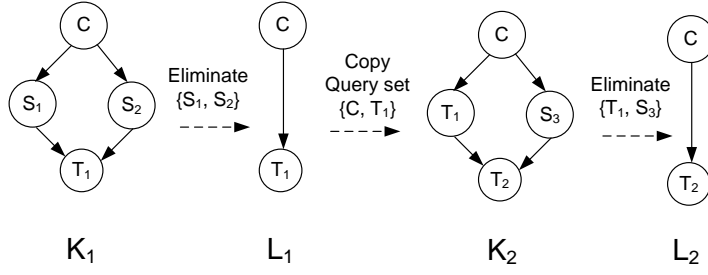


Figure 7 (b) VE process applied to part of BN G

To calculate the arbitrary n -fold convolution in the multiple common cause case it is essential to maintain the structure connecting the common causes in G' in every elimination step so that when variables are eliminated any dependencies on common cause variables are correctly maintained. Consequently, the elimination task involves generating the marginal for variable T_j conditional on the set $\mathbf{C} = C_0, C_1, \dots, C_m$. This more general case is shown in Figure 8, with multiple common cause variables C_0, C_1, \dots, C_m , and dependent severity variables, S_i . The scheme can be generalised to any configuration of common causes.

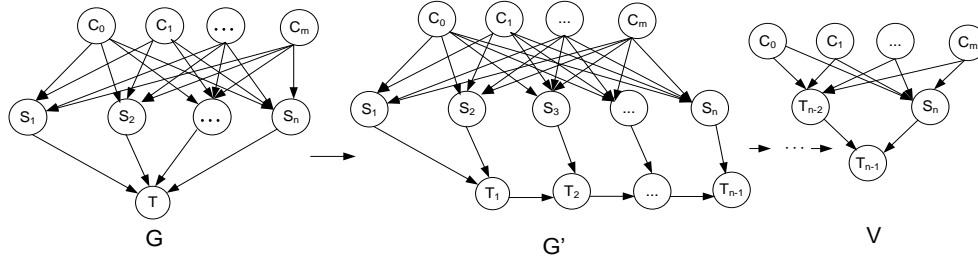


Figure 8 Multiple common cause model binary factorization and VE process (transformed graph name shown below each graph)

4.3. Compound Density Factorization (CDF)

Recall the compound density expression for an N -fold convolution, as given in equation

(2.3), where $T_j = \sum_{i=0}^j S_i$, $j = 0 \dots L$ (length of N) is an i -fold convolution with S itself and

$a_j = P(N = j)$ is the weighting assigned to the corresponding T_j . Unfortunately, the

compound density expression for $P(T)$ is very space inefficient and to address this we need to factorize it. Given each component in the mixture is mutually exclusive, i.e. for a given value of N the aggregate total is equal to one, and only one T_i , variable, this factorization is straightforward. However, we cannot use a binary factorization for (2.3), therefore we factorize the compound density expression into pairs of “block nodes” and combine each pair incrementally as shown below.

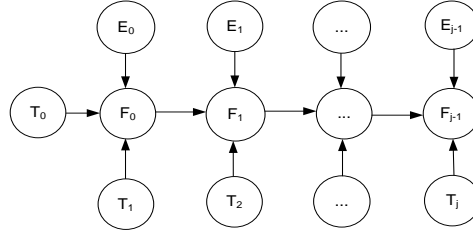


Figure 9 Compound density factorization

Equation (2.3) is factorized as shown in Figure 9, where additional Boolean variables, E_j (with only two states *True* and *False*)[†], are introduced to assign weightings proportional to a_j , to each pair of block nodes, i.e. $\{T_0, T_1\}, \{F_0, T_2\}, \dots, \{F_{j-2}, T_j\}$. Factor variables, F_j , are created to calculate the weighted aggregate for each step, up to the length of the N -fold convolution, L .

The node probability table for E_{j-1} is defined by the following:

$$P(E_{j-1} = True) = \frac{a_0 + a_1 + \dots + a_{j-1}}{a_0 + a_1 + \dots + a_j} \quad (4.7)$$

The conditionally deterministic expression for variable F_{j-1} (called a partitioned node in BN parlance) is defined by:

$$F_{j-1} = \begin{cases} F_{j-2} & \text{if } E_{j-1} = True \\ T_j & \text{if } E_{j-1} = False \end{cases} \quad (4.8)$$

Since T_0 and T_1 are mutually exclusive, the marginal distribution for variable F_0 is:

[†] “True” and “False” are used for convenience; any binary labelling would do equally well.

$$F_0 = P(E_0 = True)P(T_0) + P(E_0 = False)P(T_1) = a_0P(T_0) + a_1P(T_1)$$

which is identical to the first two terms in the original compound density expression, (2.3). Similarly, the marginal for variable F_j becomes:

$$F_{j-1} = P(E_{j-1} = True)P(F_{j-2}) + P(E_{j-1} = False)P(T_j) \quad (4.9)$$

After applying the CDF method to (2.3) we have the marginal for F_{j-1} as shown by (4.9), which yields the compound density, $P(T)$, for the N -fold convolution. Therefore by using the CDF method we can compute the compound density (2.3) more efficiently.

The CDF method is a general way of factorizing a compound density. It takes as input any n -fold convolution, regardless of the causal structure governing the severity variables. Note that the CDF method can be made more efficient by applying variable elimination (VE) to remove leaf nodes. Likewise we can execute the algorithm recursively reuse the same BN fragment $P(F | F, T, E)$.

4.4. The BFE Convolution Algorithm

The BFE convolution algorithm is formalised, as pseudo code, in Table 1

Table 1 BFE convolution algorithm

Input: S : Severity variable, N : Frequency variable, C : vector of common causes (optional)

Output: Compound density T

Main:

1. Compute the probability density function of N , with sample space Z by:

$$f_N(x) = P(N = x) = P(\{z_j \in Z : N(z) = x\}) = a_j, j = 0, 1, \dots, \text{length}(Z)$$

2. **for** $j = 0$ to (length of Z) **do**

3. **for** $i = 0$ to z_j **do**

4. Compute z_j -fold convolution $T_{z_j} = \sum_{i=0}^{z_j} S_i$ by **BF** and **LBA** algorithms

5. Eliminate nodes (out of query set) by **VE** algorithm
 6. **end for**
 7. **While** $j \geq 2$ **do**
 8. Apply **CDF** algorithm to factorize (2.3) by probability density of N
 Compute $F_{j-1} = P(E_{j-1} = True)P(F_{j-2}) + P(E_{j-1} = False)P(T_{z_j})$
 9. Eliminate nodes S_i , F_{j-2} and T_{z_j} by **VE** algorithm
 10. **end while**
 11. **end for**
 12. **return** $P(F_{j-1})$ {marginal distribution of T }
-

5. DECONVOLUTION USING THE BFE ALGORITHM

5.1. Deconvolution

Where we are interested in the posterior marginal distribution of the causal variables conditional on the convolution aggregated results we can perform deconvolution, in effect reversing the direction of inference involved in convolution. This is of interest in sensitivity analysis, where we might be interested in identifying which causal variables have the largest, differential, impact on some summary statistic of the aggregated total, such as the mean loss or the conditional Value At Risk (cVAR), derived from $P(C | T > t_0)$.

One established solution for deconvolution involves inverse filtering using Fourier Transforms, whereby the severity, S , is obtained by inverse transformation from its characteristic function. Alternative analytical estimation methods, i.e. maximum likelihood, and numerical evaluation involving Fourier transforms or simulation based sampling methods, can be attempted but none of them is known to have been applied to N -fold deconvolution in hybrid models containing discrete causal variables.

BN based inference offers an alternative, natural, way of solving deconvolution because it offers both predictive (cause to consequence) reasoning and diagnostic (consequence to cause) reasoning. This process of backwards inference is called “back propagation”, whereby evidence is entered into the BN on a consequence node and then the

model is updated to determine the posterior probabilities of all parent and antecedent variables in the model. A “backwards” version of the BFE algorithm offers a solution for answering deconvolution problems, in a general way without making any assumptions about the form of the density function of S . The approach again uses a discretized form for all continuous variables in the hybrid BN, thus ensuring that the frequency distribution, N , is identifiable.

EXAMPLE 1

Consider a simple BN with parent variable distributions $X \sim Normal(\mu = 5, \sigma^2 = 5)$, $Y \sim Normal(\mu = 10, \sigma^2 = 10)$ and likelihood function for a child variable $P(Z | X, Y) = P(Z = X + Y)$. Figure 12(a) show the prior convolution effects of the back propagation calculation, as marginal distributions superimposed on the BN graph. The exact posterior marginal for Z is $Z \sim Normal(\mu = 15, \sigma^2 = 15)$. Our approximation produces a mean of 14.99 and variance 16.28.

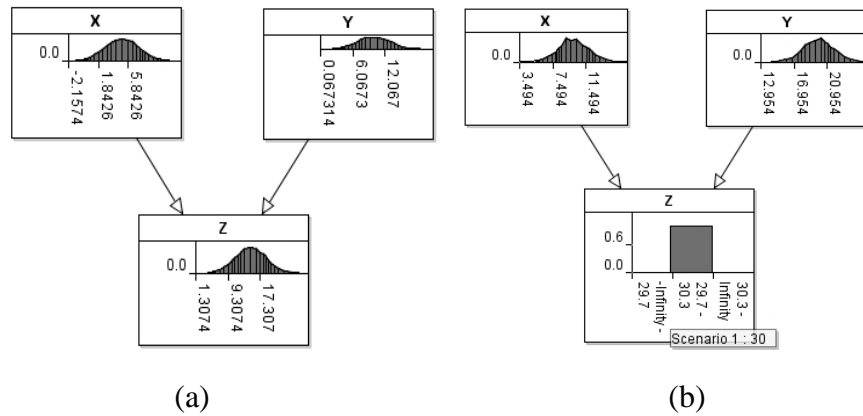


Figure 12 (a) Convolution and (b) Deconvolution

If we set an observation $Z = z_0$ and perform inference we obtain the posterior marginal of X by Bayes' rule:

$$P(X | Z = z_0) = \frac{P(X, Z = z_0)}{P(Z = z_0)} = \frac{\sum_Y P(Z = z_0 | X, Y)P(X)P(Y)}{\sum_{X, Y} P(Z = z_0 | X, Y)P(X)P(Y)} \quad (5.1)$$

Where our likelihood $P(Z|X,Y)$ is a convolution function, equation (5.1) defines the deconvolution and yields the posterior marginal distribution of X given observation $Z = z_0$. In Figure 12(b), the observation is $Z = 30$ (which is approximated as a discrete bin of given width), and the posterior for X has updated to a marginal distribution with mean 9.97 and variance 3.477.

In the example shown in Figure 12 the parent variables X and Y are conditionally dependent given the observation $Z = z_0$. For n -fold convolution with or without common causes an observation on the T_i variables would also make each of the severity variables dependent and we can perform n -fold deconvolution using the DD and JT alone for small models containing non i.i.d severity variables with query block sizes of maximum cardinality four. For large models, containing i.i.d severity variables BFE provides a correct solution with minimal computational overhead.

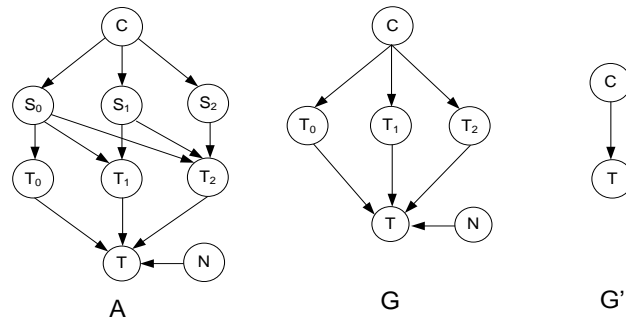


Figure 13 Binary factored common cause N -fold BN, A , reduced by applying the VE algorithm to G and then G'

We have already noted that during N -fold convolution the T_i variables are mutually exclusive, such that for a given $N = i$, if the variable T_i exists, then the other variables do not. This fact can be exploited during factorization during the deconvolution processes.

Consider the common cause BN model shown in Figure 13. The fully specified model is shown in BN graph A . The posterior distributions for all nodes can be computed by way of the BFE convolution algorithm and we can cache any distributions and parameters we might need during this process, for subsequent use during deconvolution. The BFE deconvolution algorithm then proceeds by eliminating all intermediate, fre-

quency and severity variables until we get the reduced BN graph containing the final query set of interest.

Let us assume the model structure in BN A of Figure 13. Here frequency, N , is discretized into three finite states $\{1, 2, 3\}$, so there are three n -fold convolution variables

$$T_i = \sum_{j=0}^i S_j, i = 0, 1, 2 \text{ each corresponding to the sum of one, two and three severity variables. } T \text{ is the compound distribution defined by:}$$

$$T = a_0P(T_0) + a_1P(T_1) + a_2P(T_2), a_i = P(N = i), i = 0, 1, 2$$

Given evidence $T = t_0$ the deconvolution of C is achieved by:

$$\begin{aligned} P(C | T = t_0) &= \frac{P(C, T = t_0)}{P(T = t_0)} \\ &= \sum_{S_i, T_i, N} P(T = t_0 | pa(T))P(N)P(T_i | pa(T_i))P(S_i | C)P(C) \end{aligned} \quad (5.2)$$

where $pa(T)$ denotes the parents of T . So, once the convolution model has eliminated all irrelevant variables, in this case S_i, T_{z_j}, E_j, F_j we would be left with the query set, which here is $Q = \{C, T\}$.

5.2. Reconstructing the frequency variables during deconvolution

If we are also interested in including the frequency variable, N , in our query set we must be careful to cache variables E_j, F_{j-2} and T_{z_j} during convolution. Recall that the prior distribution for N was decomposed into the E_j during compound density factorization, therefore we need some way of updating this prior using the new posterior probabilities generated on the Boolean variables, E_j , during deconvolution. To perform deconvolution on N it is first necessarily to reconstruct N from the E_j variables that together composed the original N .

Reconstruction involves composing all Boolean variables, E_j , into the frequency variable N , in a way that the updating of E_j can directly result in generating a new posterior distribution of N . The model is established by connecting all E_j nodes to N , where the new NPT for N has the form of combining all its parents. However, it turns out this NPT is exponential (2^{j+1}) in size. To avoid the drawback we use an alternative, factorized, approach that can reconstruct the NPT incrementally.

As before, we reconstruct N using binary factorization where the conditioning is conducted efficiently using incremental steps. Here the intermediate variables produced during binary factorization, $N_k, (k = 0, \dots, j-1)$, are created efficiently by ensuring their NPTs are of minimal size.

The routine for constructing the NPTs for $N_k, (k = 0, \dots, j-1)$ from the E_j 's is:

1. Order parents E_j and E_{j-1} from higher index to lower index for N_k 's NPT (since E_j is Boolean variable with only two states, one concatenating all E_{j-1} 's states and another state is single state that E_{j-1} does not contain. In this example E_1 should be placed on top of E_0 in the NPT table, as it is easier for comparing the common sets)
2. As we have already generated the NPT map of E_j, E_{j-1} and N_k . Next we specify the NPT entry with unit value ("1") at $N_k = \tau$, when E_j and E_{j-1} has common sets τ (In this example, E.g. E_1 and E_0 have common sets $\tau = "0"$ and $\tau = "1"$)
3. Specify NPT entry with value ("1") at $N_k = \tau$, when E_j and E_{j-1} has no common sets and $E_j = \tau$ (E_j has one state τ that E_{j-1} does not contain, so under this case N_k only needs to be consistent with E_j as the changes on E_{j-1} won't affect the probability $P(N_k = \tau)$, E.g. in this example it is when $E_1 = \tau = "2"$)
4. Specify NPT entry with value ("0") at all other entries.

We repeat this routine for all $N_k, (k = 0, \dots, j-1)$ until we have exhausted all E_j 's, producing a fully reconstructed N . Once we have built the reconstructed structure (N_k) for N , in fact the updates of E_j 's probabilities are directly mapped to N_k , and so deconvolution of N is retrieved.

5.3. The BFE Deconvolution Algorithm with examples

The BFE deconvolution algorithm, for N -fold deconvolution, is formalised, as pseudo code, in Table 2:

Table 2 BFE deconvolution algorithm

Input: S : Severity variable, N : Frequency variable, \mathbf{C} : vector of common causes and $T = t_0$

Output: posterior marginal of query set members i.e. $P(\mathbf{C} | T = t_0), P(N | T = t_0)$

Main:

1. **do** convolution BFE algorithm to produce final query set
 2. **if** N is in query set
 3. **reconstruct** N from E_j
 4. **end if**
 5. **set** evidence t_0 on T and perform inference
 6. **return** posterior marginal distributions for query set
-

EXAMPLE 2

Consider a simplified example for deconvoluting N , suppose frequency distribution N is discretized as $\{0.1, 0.2, 0.3, 0.4\}$ with discrete states $\{0, 1, 2, 3\}$ and $S \sim \text{Exponential}(1)$. Figure 14 (a) shows these incremental steps for example 4. In this example there are three parents (E_0, E_1, E_2) to N . The incremental composition steps of E_j have introduced two intermediate variables N_0 and N_1 , and we expect the frequency

N to be reconstructed at the end of the incremental step, which is variable N_1 . Key to this process is how to build the NPT for each N_k .

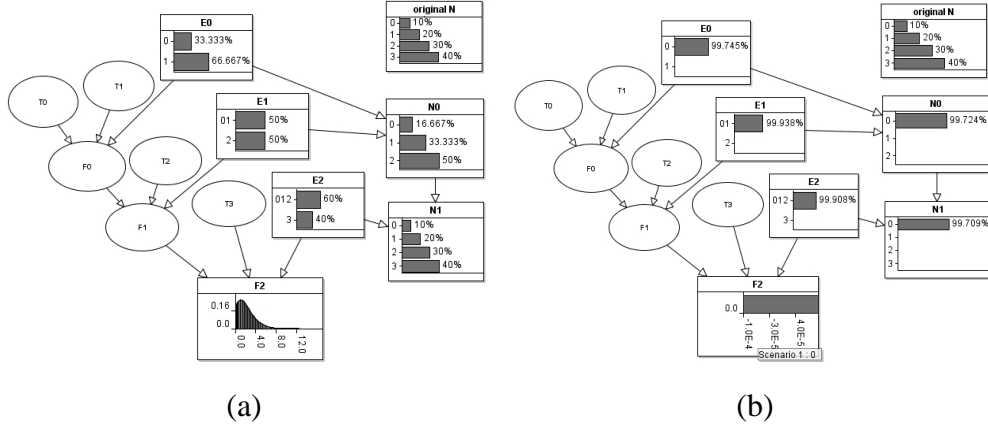


Figure 14 (a) Reconstruct N (b) Deconvoluting N

Table 3 The NPT of N_0

E_1	“01”		“2”	
E_0	“0”	“1”	“0”	“1”
$N_0 = 0$	1.0	0.0	0.0	0.0
$N_0 = 1$	0.0	1.0	0.0	0.0
$N_0 = 2$	0.0	0.0	1.0	1.0

Table 3 illustrates the NPT of N_0 , where it composes E_0 and E_1 successively, in such a way that each N_k contains all and only its parents’ discrete states. So N_0 has the discrete distribution on “0”, “1” and “2”.

Figure 14 (b) shows the deconvolution of N by our reconstruction process. The reconstructed prior distribution of N_1 is identical to node “original N ” (shown in Figure 14 (a)) as we expected. After setting an observation value “0” at the compound sum variable F_2 we have queried that the posterior of N is 99.7% probability at state “0”, since at state zero it has all possibility of generating a zero compound sum at F_2 .

The reconstruction theme is applicable to cases that N has discrete parent cause variables as well, where E_j ’s NPTs are generated directly from N ’s parents, and the

deconvolution is performed by BFE deconvolution algorithm. Experiment 3 in section 6 considers deconvoluting common cause variables where the model has this form.

6. EXPERIMENTS

We report on a number of experiments using the BFE algorithm in order to determine whether it can be applied to a spectrum of risk aggregation problem archetypes. Where possible the results are compared to analytical results, FFT, Panjer's approach and Monte Carlo simulation. The following experiments, with accompanying rationale, were carried out:

1. *Experiment 1: Convolution with multi-modal (mixtures of) severity distribution.* We believe this to be a particularly difficult case for those methods that are more reliant on particular analytical assumptions. Practically, multi-modal distributions are of interest in cases where we might have extreme outcomes, such as sharp regime shifts in asset valuations.
2. *Experiment 2: Convolution with discrete common causes variables.* This is the key experiment in the paper since these causes will be co-dependent and the severity distribution will depend on their values (and hence will be a conditional mixture).
3. *Experiment 3: Deconvolution with discrete common causes.* This is the inverse of experiment 2 where we seek to estimate the posterior marginal for the common causes conditioned on some observed total aggregated value.

The computing environment settings for the experiments are as follows. Operation system: Windows XP Professional, Intel i5 @ 3.30GHz, 4.0GB RAM. AgenaRisk was used to implement the BFE algorithm, which was written in java, where typically the DD settings were for 65 iterations for severity variables and 25 iterations for the frequency variable. A sample size of 2.0E+5 was used as the settings in R(R, 2013) for the Monte Carlo simulation.

6.1. Experiment 1: Convolution with multi-modal severity distribution

Here we set the event frequency as $N \sim \text{Poisson}(50)$ but the severity distribution is a mixture distribution, $S \sim f_S$:

$$f_S = (0.2)\text{Gamma}(5, 1.5) + (0.3)\text{Normal}(25, 2) + (0.4)\text{Normal}(50, 3) + (0.1)\text{Gamma}(100, 2)$$

In a hybrid BN a mixture distribution is modelled by conditioning the severity variable on one or more partitioning discrete variables, C . Assuming that that severity variables, S_j , are i.i.d. we can calculate the compound density using BFE.

The characteristic function of a mixture distribution is inconvenient to define (with continuous and discrete components). The analytical and programming effort needed to solve each multi-modal severity distribution for Panjer is high, so here we compare with MC only.

Table 6 Results of convolution with multi-modal severity distribution

Algorithm	Mean	Standard Deviation	95th Percentile	99th Percentile	Analysis Effort
MC	2444.8	516.7	3340.0	3787.7	Low
BFE	2441.1	523.3	3341.5	3783.1	Low

The corresponding marginal distribution for the query node set $\{T, N, S\}$ is shown in Figure 18.

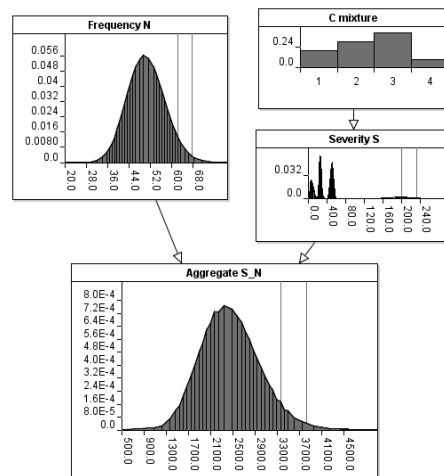


Figure 19 Marginal distributions for overlaid on BN graph containing query nodes for Experiment 1

6.2. Experiment 2: Convolution with discrete common causes variables

Loss distributions from operational risk can vary in different circumstances, e.g. exhibiting co-dependences among causes. Suppose in some cases that losses are caused by daily operations and these losses are drawn from a mixture of truncated Normal distributions, whereas extreme or some unexpected losses are distributed in a more severe distribution. We model this behaviour by a hierarchical common cause combination C_0, \dots, C_4 .

The severity variable S is conditioning on common cause variable, C_0, C_1, C_2 . And these common cause variables are conditioned on higher common causes C_3 and C_4 . Severity NPT is shown in Table 7. The frequency distribution of losses is modelled as $N \sim Poisson(50)$.

Table 7 Severity NPT

C_0	High				Low			
C_1	High		Low		High		Low	
C_2	High	Low	High	Low	High	Low	High	Low
Expression	Normal (1,2)	Normal (2,3)	Normal (3,4)	Normal (4,5)	Normal (100,110)	Normal (110,120)	Normal (120,130)	Normal (130,140)

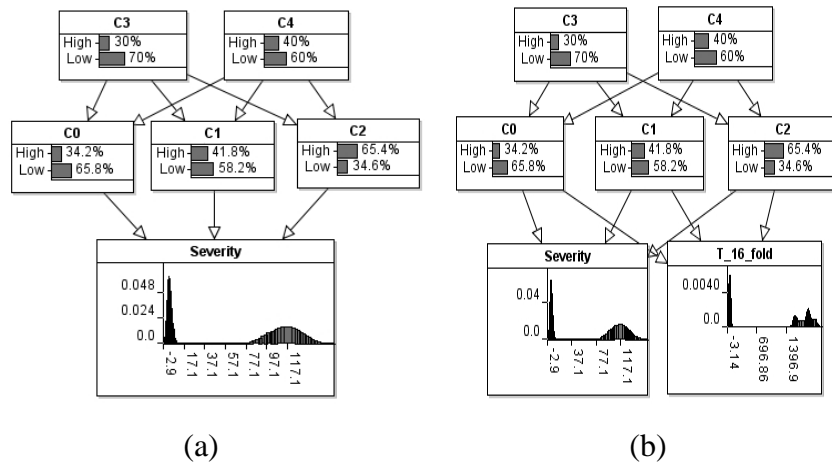


Figure 20 (a) Common cause dependent severity; (b) 16-fold convolution of dependent severity

In Figure 20 (a) the model severities with dependencies by common cause variables C_0, \dots, C_4 is introduced. Figure 20 (b) depicts a *16-fold* convolution of dependent severities using the variable elimination method. For any given frequency distribution, N , we can apply the BFE convolution algorithm to calculate the common cause N -fold convolution.

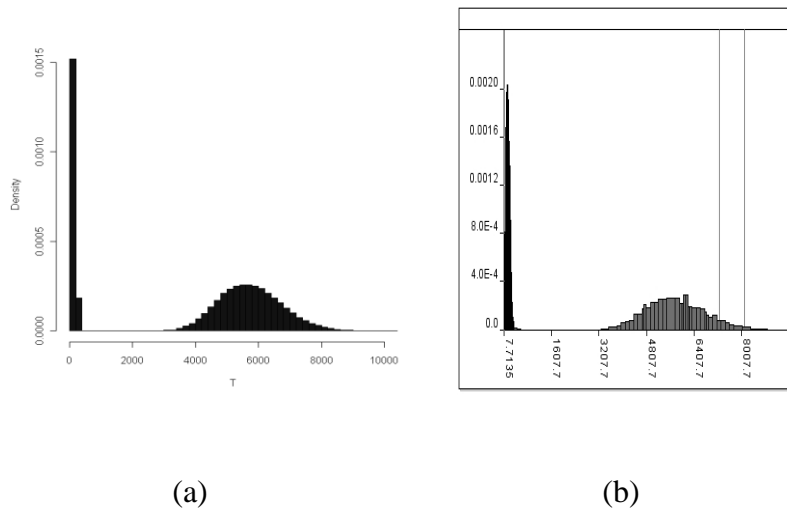


Figure 21 Compound densities (a) MC; (b) BFE

Table 8 Common cause N -fold convolution density

Algorithm	Mean	Median	Standard Deviation	95th Percentile	99th Percentile
MC	3831	5017	2784	7215	8023
BFE	3871	5052	3255	7267	8115

Figure 21 illustrates the output compound densities for the compared algorithms. Table 8 shows the results for the two approaches are almost identical on summary statistics except the small difference on standard deviation. BFE has offered a unified approach to construct and compute such a model conveniently.

6.3. Experiment 3: deconvolution with discrete common causes variables

We reuse the convolution model from Experiment 2 as the input model for deconvolution (Figure 22).

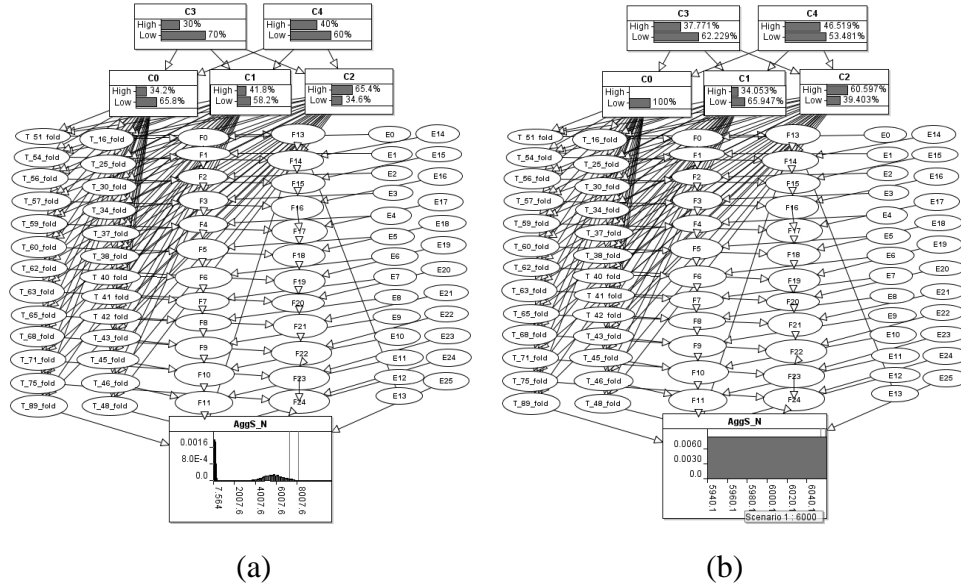


Figure 22 (a) Common Cause N -fold convolution using BFE algorithm; (b) N -fold model deconvolution using BFE algorithm (The intermediate variables in this example are shown for reference despite them being eliminated during the convolution process)

Figure 22 (b) sets an observation on total aggregation node $AggS_N$. After performing deconvolution we queried the posterior marginal of common causes and diagnose that the most likely common cause is C_0 , which is in its “Low” state with certainty. This is easily explained by the fact that from the severity NPT, shown in Table 7, it is only when state of C_0 is “Low” that a value of 6000 can be at all probable. This deconvolution is currently only supported by BEF since the information cannot be back retrieved by other approaches.

Deconvolution is obviously useful in carrying out a sensitivity of the model results, allowing the analyst to quickly check model assumptions and identify which causal factors have the largest consequential effect on the result. This is difficult to do manually or informally in the presence of non-linear interactions. Also, without “backwards” deconvolution we can only compute such sensitivities “forwards” one casual variable at a time and this is computationally much more expensive. For example, the forwards calculation

of T from ten Boolean common cause variables would require 2^{10} calculations versus 40 in the backwards case (assuming T was discretized into 40 states).

7. CONCLUSION AND FUTURE WORK

This paper has reviewed historical, popular, methods for performing risk aggregation and compared them with a new method called *Bayesian Factorization and Elimination* (BFE). The method exploits a number of advances from the field of Bayesian Networks, covering methods to approximate statistical and conditionally deterministic functions and to factorize multivariate distributions for efficient computation. Our objective for BFE was for it to perform aggregation for classes of problems that the existing methods cannot solve (namely hybrid situations involving common causes) while performing at least as well on conventional aggregation problems. Our experiments show that our objectives were achieved. For more difficult hybrid problems the experimental results show that BFE provides a more general solution that is not possible with the previous methods.

Additionally, the BFE approach can be easily extended to perform deconvolution for the purposes of stress testing and sensitivity analysis in a way that competing methods cannot currently offer. The BFE deconvolution method reported here provides a low resolution result, which is likely good enough for the purposes of model checking and sensitivity analysis. However, we are investigating an alternative high resolution approach whereby variables are discretized efficiently during the deconvolution process, thus providing more accurate posterior results.

On-going and future research is also focused on more complex situations involving both copulas and common cause variables. The challenge here is to decompose these models into lower dimensional joint distributions, where complexity can be further reduced by factorization. One final area of interest includes optimization of the results such that we might choose a set of actions in the model that maximize returns for minimum risk: we see deconvolution playing a strong role here.

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