Dynamic in-situ sensing of fluid-dispersed 2D 1 materials integrated on microfluidic Si chip 2

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In this work, we propose a novel approach for wafer-scale integration of 2D materials on CMOS 17 photonics chip utilising methods of synthetic chemistry and microfluidics technology. We have 18 successfully demonstrated that this approach can be used for integration of any fluid-dispersed 19 2D nano-objects on silicon-on-insulator photonics platform. We demonstrate for the first time 20 that the design of an optofluidic waveguide system can be optimised to enable simultaneous in-21 situ Raman spectroscopy monitoring of 2D dispersed flakes during the device operation. 22 Moreover, for the first time, we have successfully demonstrated the possibility of label-free 2D 23 flake detection via selective enhancement of the Stokes Raman signal at specific wavelengths. 24 We discovered an ultra-high signal sensitivity to the xyz alignment of 2D flakes within the 25 optofluidic waveguide, which in turn enables precise in-situ alignment detection for the first 26 practicable realisation of 3D photonic microstructure shaping based on 2D-fluid composites and 27 CMOS photonics platform while also representing a useful technological tool for the control of 28 29 liquid phase deposition of 2D materials.

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The recent development of nanocomposites consisting of fluid-dispersed atomically thin two-31 dimensional (2D) materials has sparked a great level of interest as a highly promising in-situ 32 33 tailored meta-material device platform for the next generation of multi-functional optoelectronic systems¹⁻¹³. Dynamically controlled three-dimensional (3D) self-assembly of fluid-suspended 34 2D materials not only provides a new breakthrough route for technological applications of 2D 35 material based 3D device architectures¹⁴⁻¹⁶, but also their fluidic nature allows CMOS-36 compatible wafer-scale back-end integration on chip using microfluidic technology¹⁷⁻¹⁹. The 37 practical realisation of dynamically reconfigurable 3D material fluid metastructures integrated 38 into a microfluidic system and coupled with a CMOS photonic circuit (as illustrated in Fig. 1) 39 opens up limitless possibilities in the fabrication of compact and low-power systems for 40 commercially viable, miniaturised, multi-functional light-management devices such as light 41 emitting sources²⁰, tuneable optical filters²¹ and nanoantenna phased arrays²². For example, 1D 42 photonic crystals of graphene which could act as optical filters have been theoretically explored²³ 43 but as yet no method exists for the precise reconfigurable control of such structures. 44 Additionally, self-assembly of fluid dispersed 2D materials represents a remarkable precursor 45 state for liquid phase deposition of ordered lamellae, stacks and other structures in the solid 46 phase²⁴⁻²⁶. Reconfigurability of the metastructures can be achieved by exploiting liquid crystal 47 technology^{6,15} with in-situ monitoring used to characterise the metastructure formation. 48

However, the primary challenge for the first realisation of on-chip controlled assembly of 2D 49 flakes into functional metastructures is the lack of a reliable and sensitive method for *in-situ* 50 characterisation. Such a method is pivotal to the confirmation of the integration of composites in 51 the device and to enable determination of parameters, such as spatial alignment of incorporated 52 2D materials, dynamically during device operation. Conventional characterisation methods such 53 as Raman spectroscopy^{5,27,28}, coherent anti-Stokes Raman spectroscopy (CARS)²⁹ and Fourier 54 Transform Infrared Spectroscopy (FTIR)³⁰ are not suitable for studies of fluid nanocomposites 55 with relatively low concentrations of nanoparticles dispersed. In this case, the significantly 56 greater scattering volume of the host fluid compared to that of the dispersed nanoparticles always 57 dominates the vibrational signal intensity, rendering the monitoring of the considerably weaker 58 bands of dispersed nanoparticles impossible. 59

Here we demonstrate, for the first time, the wafer-scale integration of fluid-dispersed 2D 60 materials on Si photonics chip utilising microfluidic technology, and their subsequent electrical 61 and optical manipulation. We also propose and subsequently demonstrate a novel approach for 62

ultra-sensitive, label-free, *in-situ* detection and monitoring of integrated 2D-fluid composite 63 materials on-chip. Specifically, an *in-situ* micro-Raman characterisation approach, whereby the 64 Raman signal of 2D dispersed nanoparticles is selectively enhanced through the design of 65 optofluidic waveguide geometry on silicon-on-insulator (SOI) platform. It has previously been 66 shown that the Raman signal from micro-structured silicon cavities can be enhanced due to 67 Fabry-Pérot type resonances³¹⁻³³. Here, the structure is designed to simultaneously enhance 68 different resonant modes relating to different parameters of the optofluidic waveguides, 69 balancing the required enhancement of the signal from multiple vibrational bands with the desire 70 for the greatest achievable intensity for the individual bands. The developed approach 71 demonstrates ultra-high sensitivity to the xyz alignment of 2D nanoparticles within optofluidic 72 waveguides. Hence, for the first time, our findings demonstrate the possibility of monitoring the 73 74 dynamics of fluid-dispersed 2D nanoparticles on chip. Our work paves the way for the practical realisation of dynamically reconfigurable photonic metastructures based on 2D-fluid 75 composites integrated on CMOS photonics platform with a range of important applications, such 76 as renewable energy, optical communications, bio-chemical sensing, and security and 77 defence technologies^{4,8,34} or as a precursor to controlled deposition of solid state structures^{24–26}. 78

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Typically, large-scale CMOS photonics builds on a SOI platform; a high index-contrast 80 waveguide platform which prevents interference between the photonic integrated circuit 81 components and the substrate. Therefore, we use an SOI based Fabry-Pérot type optofluidic 82 waveguide channel, with an open top cladding (Fig. 1 inset) to allow *in-situ* micro-Raman 83 detection and monitoring of the integrated 2D fluid nanocomposite system during device 84 operation. To optimise the optofluidic waveguide design for facilitating strong confinement of 85

light on chip and to significantly enhance the Raman back-scattered signal of the individual 86 incorporated 2D nanoplatelets, we model the variation in the intensity of the Raman bands of 87 dispersed nanoparticles while varying parameters that can be experimentally controlled, such as: 88 the waveguide width, w, and the buffer oxide (BOX) layer thickness, h_{BOX} . We consider the 89 specific case of the D and G bands of 2D carbon-based materials (Fig. 2)- such as graphene and 90 graphene oxide (GO)- dispersed in a nematic liquid crystal (LC) host, however the proposed 91 methodology can be utilised for any fluid-dispersed material. The backscattered Raman signal 92 intensity is numerically determined for wavelengths corresponding to the Raman active bands 93 using the scattering matrix method [See Supplementary Methods]. The complex variation of the 94 Raman signal as a result of modifying the optofluidic waveguide parameters can be rationalised 95 as the superposition of Fabry-Pérot resonance effects in different parts of the geometry. 96 97 Enhancement of up to 100x can be observed between maximising and minimising combinations of the optofluidic waveguide parameters. 98

99 In order to experimentally demonstrate the enhancement of the Raman intensity, 2D materialfluid nanocomposites- consisting of graphene and GO nanoplatelets dispersed in LCs- were 100 prepared by a liquid phase dispersion method [See Supplementary Methods]. The optimal 101 parameters for the microfluidic structures were determined from the calculated Raman signal 102 intensity maps shown in Figure 2. Resonator devices consisting of optofluidic waveguide 103 channels of different widths were fabricated on SOI wafer with a thick buffer oxide ($h_{BOX}=2 \mu m$) 104 layer and with a silicon device layer of 15 µm. The prepared nanocomposites were integrated 105 into optofluidic waveguide channels via infiltration reservoirs on the chip (Fig. 3). The selected 106 microfluidic channels had widths in the ranges $3.7\pm0.2 \ \mu m$ (narrow channels, strong 107 108 enhancement) and $10.5\pm1.5 \ \mu m$ (wide channels, weaker enhancement). Optical microscopy (Fig.

3b) and scanning electron microscopy (Fig. 3c-e) both confirmed the successful integration of109the nanocomposite into all channels.110

Raman spectra are presented for the GO-LC nanocomposites- with MLC-6608 (Fig. 4a) and 111 with E7 (Fig. 4b) as the fluid host- at three points in-situ on the chip; more specifically: in a wide 112 channel (Fig. 4c), in a narrow channel (Fig. 4d) and in an infiltration reservoir (Fig. 4e). Liquid 113 crystal MLC-6608 exhibits weak Raman bands (see Supplementary Results) that have no strong 114 overlap with the D and G bands, allowing for clear determination of the GO bands in gathered 115 spectra. Raman spectra were recorded for individual monolayer flakes of area $1.0\pm0.1 \ \mu m^2$ in all 116 cases. For GO dispersed in MLC-6608, the D band Raman intensities were observed in the 117 approximate ratio 5:8:16 for an infiltration reservoir, 11.6 µm channel and 3.6 µm channel 118 respectively. For the G band, intensities were observed in the ratio 5:7:16. E7, however, has a 119 strong Raman active vibrational band at around 1605 cm^{-1} (see Supplementary Results), 120 overlapping with the G band. Nevertheless, utilising the proposed signal enhancing design, the 121 122 observation of the G band as a broad shoulder on this band is feasible (Fig. 4b). In addition, similar results were obtained for nanocomposites with graphene instead of GO. 123

The close agreement, in Figure 4f, between the relative intensities of the D and G bands found 124 experimentally for all nanocomposites (points) and those determined numerically (solid lines) 125 verifies the method for predicting the Raman signal enhancement. For both the D and G bands, 126 the numerically determined enhancement ratio was within the error of the experimental 127 measurements; slight differences occur due to the flake not being positioned precisely at the 128 centre of the channel. Therefore, this technique presents an effective tool for maximising the 129 enhancement of the Raman signal.

Understanding the dynamics of 2D nanoplatelet spatial alignment is essential for the 131 realisation of three-dimensional metastructure formation. External stimuli, such as applied 132 electric field and light coupling^{6,15} [See Supplementary Results and Supplementary Videos 1-4], 133 induce dynamic re-ordering of suspended 2D nanoparticles. Here, a Raman laser was exploited 134 to move a GO flake within a channel (Fig. 5a), while simultaneously being used to monitor the 135 xyz alignment over time. The variation in the experimental Raman spectra for different flake 136 positions within the channel is illustrated in Fig 5b.

The effect of the flake position on the Raman signal intensity was modelled by varying the 138 position of the oscillating dipoles within the optofluidic waveguide channel both laterally and 139 vertically. The ratio of the D and G band intensities is not constant as the position is varied (Fig. 140 5c-d). For lateral displacements (Fig. 5c), there are ratios of 11 and 32 between the minimal and 141 maximal intensities determined numerically for the D and G bands respectively. For vertical 142 displacements (Fig. 5d), the maximum and minimum values of the average intensity differ by 143 factors of around four and five times for the D and G bands respectively. 144

For the lateral displacement of the flake, the ratios of the intensities of the GO D and G bands 145 were extracted from experimental spectra when a flake was next to the wall and when moved 146 further towards the centre of the channel. These ratios were then used as a multiplier on the 147 numerically determined intensity for the flake next to the wall (position 2 in Fig. 5a) to 148 determine an approximate displacement. Positions approximated using experimental data in 149 tandem with the numerically determined results are closely matched to the values observed using 150 optical microscopy techniques (See Supplementary Results), falling within the experimental 151 error. The lateral position can therefore be determined with similar precision to optical 152 microscopy (approx. $\pm 5\%$) currently, but with scope for the error to be reduced significantly by 153 improving the signal-to-noise ratio. 154

For the vertical displacement of the flake, again the ratios of the intensities of the GO D and G 155 bands were extracted, this time from data with the flake at the bottom of the channel and further 156 towards the surface. The ratios were then used to multiply the numerically determined intensity 157 with the flake at the bottom of the channel to determine an approximate displacement. The 158 numerical analysis covering the effect of vertical flake position shows close agreement with the 159 experimental data. The vertical position of the flake cannot be determined from optical 160 microscopy but the close agreement of the positions determined separately from the D and G 161 bands confirms that the method is accurate. Therefore, the predictions made from the Raman 162 spectra are the most accurate method of determining the vertical position currently available. 163 While we propose this technique as a method for monitoring self-assembly of 3D metastructures 164 comprised of 2D materials, this approach may also find applications in a wide range of other 165 areas such as controlling flake alignment for liquid phase deposition of 2D materials^{24,26} or for 166 spatial monitoring of nanoparticle distributions³⁵. 167

In summary, we propose a novel approach for integration of 2D materials on CMOS photonics 168 chip utilising microfluidics technology. We have successfully demonstrated that this approach 169 can be used for integration of any fluid-dispersed 2D nanoparticles on SOI photonics platform. 170 The optofluidic system design can be optimised to enable in-situ Raman spectroscopy 171 monitoring of 2D dispersed flakes during device operation. In-situ label-free 2D flake sensing 172 via selective enhancement of the Stokes Raman signal at given wavelengths has been determined 173 numerically and confirmed experimentally. This approach has been applied to monitor the 174 individual 2D nanoplatelet dynamic within an optofluidic waveguide with high sensitivity, 175 enabling precise *in-situ* alignment monitoring for controlling liquid phase deposition of 2D 176 materials as well as he first practical realisation of 3D photonic metastructure shaping based on 177 2D-fluid composites and CMOS photonics platform. 178 ASSOCIATED CONTENT 179 **Supporting Information** 180 Supporting Information Available: Supplementary Methods- Numerical Calculations, Synthesis 181 of GO-LC nanocomposites, Instrumentation. (PDF). Supplementary Results- Raman Intensity 182 Maps, Liquid crystal spectra, Nanoparticle alignment by external stimuli, *In-situ* determination 183 of nanoparticle positions (PDF). Video- Orientation switching of a graphene flake dispersed in 184 E7, Electrically induced motion of GO flakes, Electrically induced motion of a single GO flake, 185 Optically induced motion of GO flakes (AVI). 186 **ACKNOWLEDGMENTS** 187 We acknowledge financial support from: The Engineering and Physical Sciences Research 188 Council (EPSRC) of the United Kingdom via the EPSRC Centre for Doctoral Training in 189 190 Electromagnetic Metamaterials (Grant No. EP/L015331/1) and also via Grant Nos. EP/N035569/1, EP/G036101/1, EP/M002438/1, and EP/M001024/1, Science Foundation Ireland 191 Grant No. 12/IA/1300, the Ministry of Education and Science of the Russian Federation (Grant 192 No. 14.B25.31.0002) and the Royal Society International Exchange Grant 2015/R3. The 193 microfluidic structures were fabricated at Tyndall National Institute under the Science 194 Foundation Ireland NAP368 and NAP94 programs. 195 AUTHOR INFORMATION 196 197 **Corresponding Author**

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input	from M.C., T.P., Y.G., A.B., T.P., B.H. and S.Y. conducted the experiments; S.D. wrote	201
the c	ode used for numerical analysis; L.B. synthesised the nanocomposites; A.B. and M.C.	202
supe	rvised and directed the research. All authors read and approved the final manuscript.	203
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Figure 1. A CMOS photonic circuit coupled to a microfluidic layer integrating dynamically reconfigurable 2D material metastructures by exploiting liquid crystal technology. *In-situ* micro-spectroscopy detection and monitoring gives information on the formation of the metastructures.

Figure 2. a) Map showing regions where both the D and G bands of 2D carbon-based materials are determined numerically to be strongly enhanced in Raman spectroscopy measurements. b) Expanded view of the region of interest highlighted in a. The range of parameters for which strong enhancement is observed are shown with the white lines including fabrication deviation Δh_{BOX} and Δw .

Figure 3. a) SEM image of the chip used for Raman measurements, before infiltration with the nanocomposite. **b)** Polarised microscopy image of the structure infiltrated with a composite of MLC 6608 and graphene oxide. Integration of the composite, including GO flakes, into all microfluidic structures on the chip can be seen. **c)** SEM of GO flakes infiltrated with a host LC into a 3.6 μm channel. **d)** SEM of GO flakes infiltrated with a host LC into an 11.6 μm channel. **e)** SEM of an 11.6 μm channel, with the LC removed, showing the integration of large numbers of GO flakes.

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Figure 4. a-b) Normalized Raman spectra showing the enhancement of the D and G bands for graphene oxide dispersed in (**a**) liquid crystal MLC 6608 and (**b**) liquid crystal E7. Spectra are shown for three microfluidic geometries: in (**c**) an infiltration reservoir of width 100μm (magenta), in (**d**) a microfluidic cavity of width 11.6μm (green) and in (**e**) a microfluidic cavity of width 3.6μm (black). Approximate laser spot sizes are shown in (**c-e**). **f**) Comparison of numerically determined (solid lines) and experimentally measured (points) Raman intensities of the graphene oxide D (blue) and G (red) bands. All data is normalized to the case where the walls are separated by a distance great enough for Fabry-Pérot resonances to have no effect.

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Figure 5. a) GO flake movement induced by the Raman laser. Each image represents the change after 10 *s* exposure time in the order in which they were observed. **b)** Raman spectra of a GO flake dispersed in liquid crystal E7 within a narrow channel (approx. $3.6 \ \mu m$) at positions 1 (cyan), 2 (violet) and 5 (grey) as seen in **a. c-d**) The variation of the Raman intensity of the GO D (blue) and G (red) bands for lateral (**c**) and vertical (**d**) displacements of a GO flake within the microfluidic channel. Solid lines give the numerically determined Raman intensities. Flake positions determined from normalized experimental spectra are shown as points. For lateral displacements, the error in the experimental measurement is given by the size of the symbols.









