

1 **Supplementary Information**

2 **Title: Optimal search patterns in honeybee orientation flights are** 3 **robust against emerging infectious diseases**

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7 **Supplementary Method: Harmonic Radar Tracking**

8 The tracking of a bee's flight relies on a 16 mm long dipole aerial with a Schottky diode, forming a
9 transponder that is vertically attached to the thorax of the bee¹ (Fig. S1a). At ca. 12–15 mg, the
10 weight of the transponder is considerably lighter than a typical nectar or pollen load carried by a bee
11 ². The transponder is excited by microwaves emitted from a stationary, horizontally scanning radar
12 system (Fig S1b)(9.41 GHz-transmitter, 3 kHz pulse repetitive frequency) and returns a microwave of
13 a harmonic frequency of the original wave for which the experimental arena is specifically scanned.
14 With the radar system turning at 20 rpm, this provides a positional record of a bee flying within a
15 range of 900 m every 3 seconds^{1,3}. The transponder signals are not uniquely identified and only one
16 individual can be tracked at a time. Radar tracking relies on a clear line-of-sight between the radar
17 and the tracked object. Obscuring landscape features like high vegetation, buildings or high terrain
18 may prevent the continuous recording of positional information^{4,5}. Based on the recorded radar
19 signals, tracks were manually digitalized using a custom-made TAS - Track Analysis Software V1.0 (by
20 Shane Hatty, Rothamsted Research, 2008) providing range (metres), bearing (radians) and a time
21 stamp for the transponder signal received with each radar revolution (3 sec). From these datasets
22 we directly inferred track duration and pauses (s), track length (m), mean flight speed (ms^{-1}) and
23 maximum displacement distance (i.e. furthest position of a bee from the colony, m). Based on the
24 smallest polygon enclosing the entire track (hull) we inferred track area A (m^2), track perimeter C (m)
25 and calculated isoperimetry I, i.e. overall track circularity:

$$I = 4\pi \frac{A}{C^2}$$

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28 **References**

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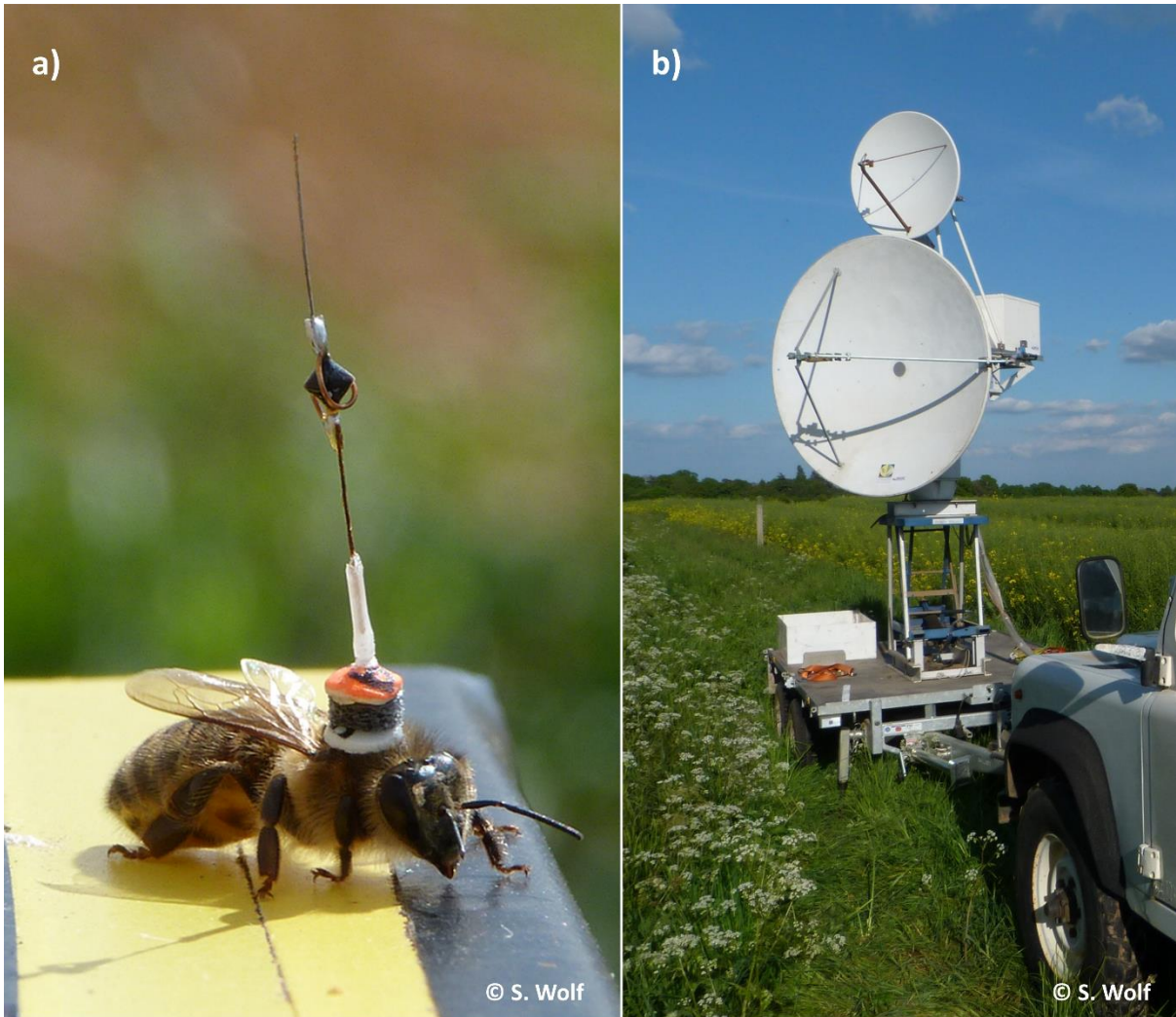
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42 **Supplementary Tables and Figures**

43 **Figure S1**

44 a) Honeybee worker marked on its thorax with a white number tag upon which a transponder is
45 attached. b) Harmonic Radar Unit with large transmitting dish and smaller receiving dish mounted
46 on a turntable for horizontal scanning at 20 revolutions per minute. The vehicle contains the
47 operating and recording unit. Note that this picture was taken before the experiment and no oilseed
48 rape was available as foraging resource during the data collection.



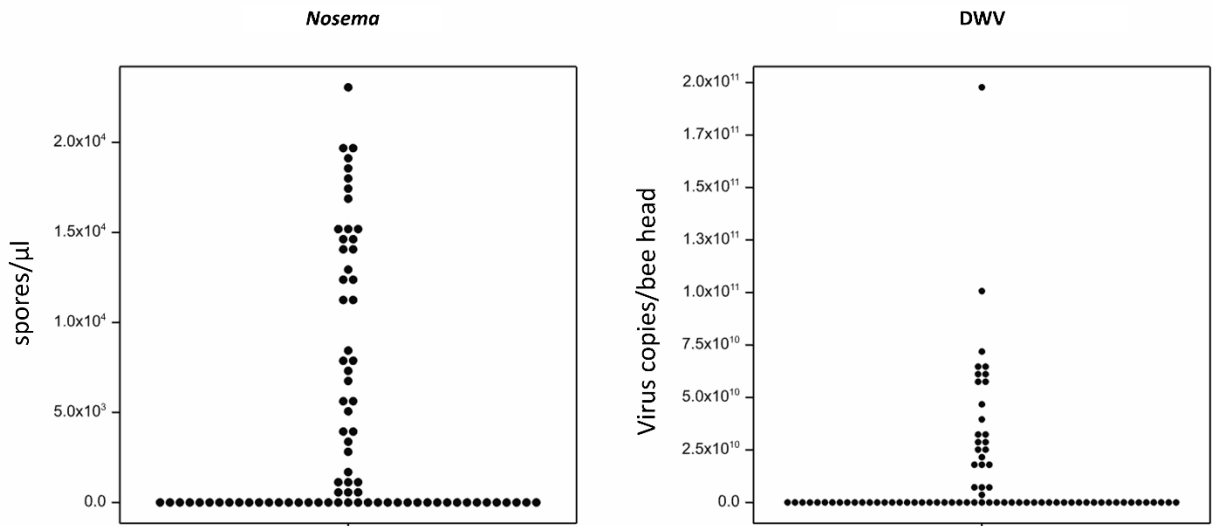
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52 **Figure S2**

53 Disease load pyramid for DWV load and *Nosema* spore load in the radar tracked bees. For both
54 pathogens there is a distinct group of non-infected bees, as compared to a group of bees with
55 varying degrees of infections and including highly infected individuals.



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Figure S3

Box plots (box: median (central line) 6 quartiles; whiskers: minimum – maximum values) of the behavioural effects of “high” (>1000 spores/ μ , white) and “low” (<1000 spores/ μ l, light grey) infection levels in honeybee orientation flight parameters in comparison to the absence of *Nosema* sp. (“no”, dark grey). See Table 2 for statistical information.

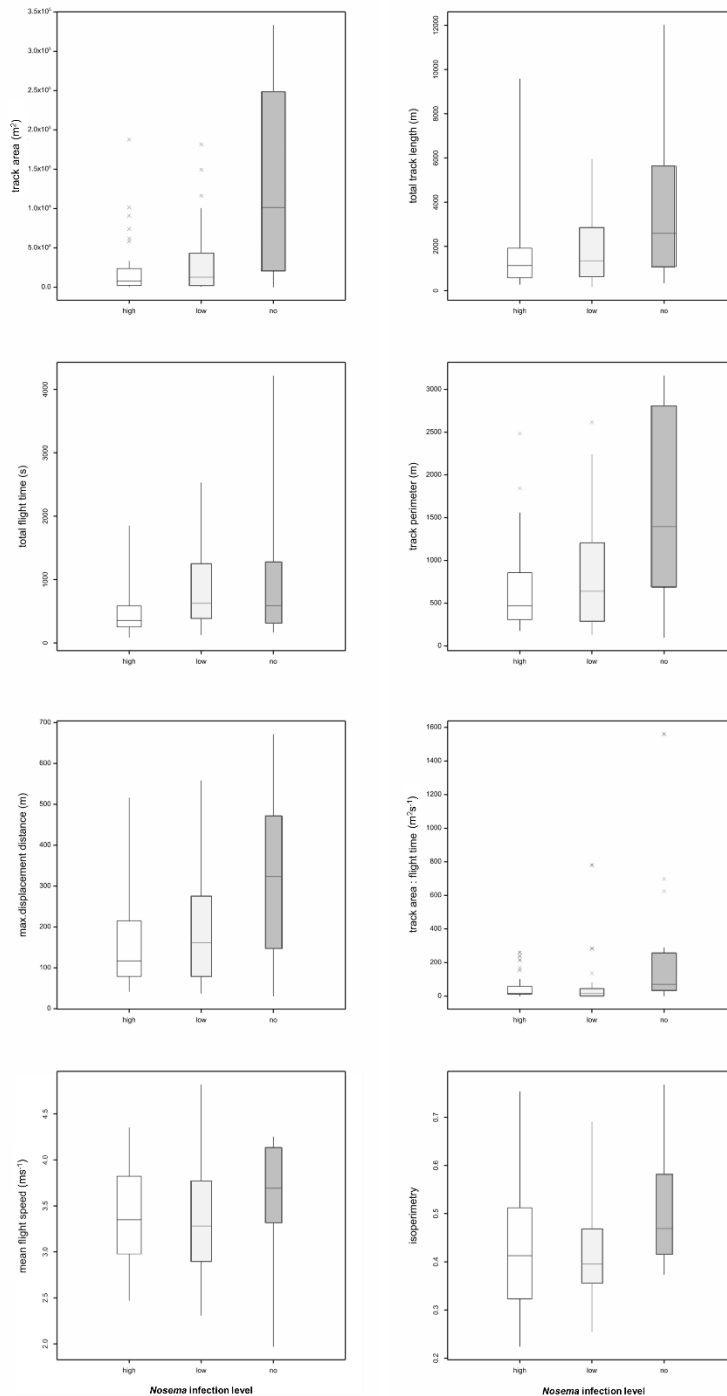


Figure S4

Frequency rank distributions (FRDs) of flight step lengths (l in meters) for all bees in each pathogen group (black solid lines) together with the group-level best-fit power-law distributions (black dashed-line) and the group-level best fit exponential distributions (black dotted lines). For each pathogen group the FRDs are better represented by power-laws which are indicative of Lévy flights.

