

Article

COMPARISON OF A NOVEL ORGANIC-FLUID THERMOFLUIDIC HEAT CONVERTER AND AN ORGANIC RANKINE CYCLE HEAT ENGINE[§]

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- Abstract: The Up-THERM heat converter is an unsteady, two-phase thermofluidic oscillator that
- ² employs an organic working-fluid, which is currently being considered as a prime-mover in small-
- to medium-scale combined heat and power (CHP) applications. In this paper, the Up-THERM heat
- 4 converter is compared to a basic (sub-critical, non-regenerative) equivalent organic Rankine cycle
- 5 (ORC) heat engine with respect to power output, thermal efficiency and exergy efficiency, but also
- 6 capital cost and specific cost. The study focuses on a pre-specified Up-THERM design in a selected
- 7 application, a heat-source temperature range from 210 °C to 500 °C and five different working
- ⁸ fluids (three *n*-alkanes and two refrigerants). A modelling methodology is developed that allows
- the above technoeconomic performance indicators to be estimated for the two thermodynamic
- ¹⁰ power-generation systems. It is found that the power output of the ORC engine is generally higher
- than that of the Up-THERM heat converter, at least as envisioned and in the chosen application,
- as expected. On the other hand, the capital costs of the Up-THERM heat converter are also lower
- compared to those of the ORC engine. Although the specific costs (\pounds/kW) of the ORC engine are lower than those of the Up-THERM converter at low heat-source temperatures, the two systems
- lower than those of the Up-THERM converter at low heat-source temperatures, the two systems
 become progressively comparable at higher temperatures, with the Up-THERM heat converter
- attaining a considerably lower specific cost at the highest heat-source temperatures considered.

17 Keywords: thermofluidic oscillator; two-phase; unsteady; non-linear; organic Rankine cycle;

- combined heat and power; performance analysis; economic comparison; low-grade heat; off-grid
- ¹⁹ power generation

20 Nomenclature

Α	$[m^2]$	Cross-sectional area
B_i	[-]	Constants
С	$[m^4 s^2/kg]$	Capacitance
С	[£]	Costs
С	[-]	Geometrical constant
c _p	[J/kgK]	Heat capacity at constant pressure
d	[m]	Diameter
F	[-]	Factor

f_0	[-]	Friction factor
8	$[m/s^2]$	Gravitational acceleration
h	$[W/m^2 K]$	Heat transfer coefficient
K_i	[-]	Constants
k	[N/m]	Spring constant
L	$[kg/m^4]$	Inductance
1	[m]	Length
т	[kg]	Mass
Р	[Pa]	Pressure
Ò	[W]	Heat flow-rate
R	$[kg/m^4 s]$	Resistance
Ś	[W/K]	Rate of entropy generation
S	[kI/kgK]	Specific entropy
Т	[K]	Temperature
t	[s]	Time
U	$[m^{3}/s]$	Flow rate
V	$[m^3]$	Volume
Ŵ	[W]	Power
1/	[-]	Spatial coordinate
y Greek let	L J ters	oputar coordinate
N	[K]	Temperature amplitude
к В	[1] [1/m]	Parameter that depends on the spatial gradient of the
Ρ	[1/ 111]	heat exchanger wall temperature at equilibrium
γ	[-]	Heat capacity ratio
δ	[m]	Gan between piston and slide bearing
u n	[%]	Efficiency
' 1/	$[m^2/s]$	Dynamic (absolute) viscosity
μ O	$\left[\frac{1}{ka}/m^{3}\right]$	Density
P Subscrip	[Kg/III]	Density
5005CTIP	15	Equilibrium
0 (1)		OPC condensor outlet / nump inlet
1 ()'		OPC nump outlet / grangerator inlet
∠ (2)		ORC pump outlet/evaporator inlet
3 (1)		ORC evaporator outlet/explander inlet
4		Underselie e e e e e e e e e e e e e e e e e e
a (1./		Click have been been been been been been been be
		Silde bearing
BM		Bare module
Ca		Carnot
°C'		Connection tube
CS'		Heat sink
'cv'		Check valve
'd'		Displacer cylinder
'ex'		Exergy
'exp'		Expander
'fg'		Phase change

'gen'	Power generating
'hm'	Hydraulic motor
'hot'	Hot heat exchanger
'htf'	Heat transfer fluid
'hx'	Heat exchanger
'in'	Into the cycle
'is'	Isentropic
'LM'	Log mean
'l'	Liquid volume
ʻlub'	Lubricant
'M'	Material
'max'	Maximum
'min'	Minimum
'motor'	Motor
'ms'	Mechanical spring
'net'	Net power
ʻnl'	Non-linear
'out'	Out of the cycle
ʻp'	Piston
'p*'	Reduced pressure
'pc'	Purchased costs of equipment
'pump'	Pump
'pv'	Piston valve
'q'	Heat flux
'ref'	Reference
'sat'	Saturation
'sh'	Shaft
'ss'	Stainless steel
'th'	Thermal domain
'v'	Vapour volume
'w'	Wall
'wf'	Working fluid
'wm'	Wall material
'wr'	Wall surface roughness
Superscripts	
'0'	Base condition

21 1. Introduction

²² Ensuring long-term energy and environmental security by reducing the current rates of consumption²³ of finite fossil-fuel reserves and the release of related emissions to the environment have been

²⁴ increasingly desirable goals in recent years. Specifically, the interest in the utilization of sustainable

²⁵ energy resources such as geothermal and solar heat, which are abundantly available, is attracting

²⁶ increasing attention, as is the recovery and utilization of low- and medium-grade (*i.e.*, temperature)

27 waste heat, significant quantities of which are being rejected in the industrial, transport and

²⁸ residential sectors [1]. These goals can be met to an extent by collecting or recovering thermal energy

from these sources and converting this to useful work such as electricity, shaft work, or pumping
(hydraulic) work. Because of the lower heat-source temperatures involved (relative to conventional
power generation), the thermal efficiency of any system used for this purpose is expected to be

³² inherently low, therefore cost is also of primary importance in the deployment of relevant solutions.

Thermofluidic oscillators are one particular class of thermodynamic heat converters that can utilize lower-grade external heat sources cost-effectively, as mentioned. This class of systems includes single-phase thermofluidic oscillators such as Sondhauss tubes [2,3], standing-wave thermoacoustic engines [4], and the Fluidyne engine [5]. Alternatively, two-phase thermofluidic oscillators are also being considered, such as the 'Non-Inertive-Feedback Thermofluidic Engine' (NIFTE) [6–8] and the

³⁸ Up-THERM heat converter, which comprises a single reciprocating solid-piston. In particular, the ³⁹ NIFTE has been shown to be capable of operating across temperature differences between a heat ⁴⁰ source and sink as low as 30 °C [9]. One important characteristic of thermofluidic oscillators is their ⁴¹ reliance (by-design) on far fewer moving parts and dynamic seals during operation, and their more ⁴² simple construction featuring more basic components. This allows more affordable materials and ⁴³ manufacturing techniques to be used, leading to lower capital costs but also longer maintenance

⁴⁴ cycles and lower operating costs than conventional power-generation systems.

The Up-THERM heat converter was proposed by Encontech B.V. [10,11] and further developed 45 under the EU FP7 project Up-THERM [12]. The device is described in detail in Kirmse et al. [13–15] 46 and Oyewunmi et al. [16]. Briefly, a constant temperature difference applied and maintained, by an external heat source and sink, between the hot and cold parts of the Up-THERM heat converter gives 48 rise to periodic alternating evaporation and condensation of the working fluid as this oscillates within 49 the device thereby undergoing an unsteady thermodynamic cycle. This leads to unsteady oscillations 50 of pressure, temperature, and volume within the engine and, consequently, the reciprocating motion 51 of liquid within the device and the reciprocating vertical motion of a solid piston. By transforming 52 the oscillatory movement of the liquid into unidirectional flow through the use of check valves and 53

⁵⁴ hydraulic accumulators, power can be extracted by a hydraulic motor.

The organic Rankine cycle (ORC) is also a technology that is capable of converting lower-grade (external) heat into useful work. It is a more commercially mature technology compared to the novel concept of the Up-THERM heat converter, and a significant effort has been placed in the technical development and improvement of this technology, especially in the field of waste heat recovery [17– 24]. In particular, ORC engines promise relatively high efficiencies at low temperatures and power outputs and form a natural benchmark for the technical and economic assessment of the Up-THERM heat converter.

In this paper we compare the concept of the Up-THERM heat converter, based on a pre-specified Up-THERM (geometric) design in a selected application, to ORC engine technology with a view towards employing the Up-THERM heat converter as a combined heat and power (CHP), or cogeneration, prime-mover. To this end, we perform a thermodynamic and economic comparison of the two technologies, recovering heat from heat-sources in the temperature range from 210 °C to 500 °C. Three *n*-alkanes (*n*-pentane, *n*-hexane, and *n*-heptane) and two refrigerants (R134a and R227ea) are investigated as working fluids over the heat-source temperature range of interest.

The methods used for the modelling of the Up-THERM heat converter and the equivalent 69 sub-critical, non-regenerative ORC engine are described in Section 2. Moreover, in Section 2 we give 70 a brief explanation of the calculation of the capital costs of both systems. This is followed by an 71 examination of the following thermodynamic performance indicators of both engines: power output; 72 exergy efficiency; and thermal efficiency. It may be expected that the ORC engine will outperform the 73 74 Up-THERM heat converter purely in terms of these thermodynamic performance indicators. We proceed to investigate the economic performance of the two engines. In particular, we consider 75 the capital costs and specific costs per unit power. Due to its simple design, fewer and more basic 76 components, it can also be expected that the Up-THERM heat converter will have lower capital costs 77 than its ORC counterpart, which has a technically more complex construction, as mentioned above. 78

On the other hand, the specific costs of the two systems and how these compare are of particular
interest here, in the context of the future uptake and implementation of these technologies.

81 2. Materials and Methods

82 2.1. Up-THERM engine configuration and operation

A schematic of the Up-THERM engine is shown in Figure 1. The engine is completely filled with 83 liquid working fluid, except above the piston, where vapour working fluid fills a gas spring. The 84 engine comprises two parts, the displacer cylinder and the load arrangement. These two parts are 85 connected via the connection tube. The displacer cylinder represents the thermofluidic oscillator part 86 of the engine. It consists of the hot (HHX) and cold heat exchangers (CHX), the solid piston that 87 forms together with the inner wall of the displacer cylinder the piston valve, a slide bearing where 88 piston and liquid working fluid are separated, and two mechanical springs that are fixed to the top 89 and bottom of the lower part of the displacer cylinder and loosely attached to the piston. The load 90 arrangement contains two check valves, two hydraulic accumulators and the hydraulic motor. 91



Figure 1. Schematic of the Up-THERM heat engine with hot and cold heat exchangers, piston, valve, mechanical spring and hydraulic motor with piston at TDC and BDC (inset).

Assuming a cycle to start with the piston in the top dead centre the vapour-liquid interface is in 92 contact with the HHX, the piston valve is open and the top mechanical spring is fully compressed. 93 Liquid working fluid evaporates, thereby increasing the pressure in the gas spring above the piston. This, together with the mechanical spring, forces the piston downwards and the piston valve closes 95 preventing fluid from flowing from the chamber above the valve into the one below. Thus the 96 pressure in the upper chamber increases while the pressure in the lower chamber stays almost 97 constant. Due to inertia the piston moves beyond its equilibrium position and the lower mechanical spring is compressed while the upper mechanical spring is fully extended. When the piston moves further down, the piston valve opens. The pressure difference between the upper and lower chambers 100 is suddenly equalized and liquid working fluid flows downwards through the piston valve. The 1 01 vapour-liquid interface is now in contact with the CHX. Working-fluid vapour condenses and reduces 102 the pressure in the gas spring. The piston and vapour-liquid interface start moving upward until 103 the piston valve closes again. Now only the piston moves upwards and a pressure difference is 1 04 established between the upper and lower chamber, where the pressure in the upper chamber is lower 105 than the pressure in the lower chamber. When the piston valve opens again this pressure difference 1 06 gets suddenly equalized and working fluid flows from the lower into the upper chamber. 107

2.2. Up-THERM model development 108

The modelling methodology taken for the Up-THERM is an extension of previous approaches 1 0 9 employed for the modelling of thermoacoustic and thermofluidic devices, starting from the earlier 110 work of Ceperley [4], Huang and Chuang [25] and Backhaus and Swift [26,27]. In particular, 111 due to its reliance on the phase change of the working fluid, the Up-THERM engine has some 112 similarities to the NIFTE, models for which were first proposed by Smith [6,7,8] and later extended 113 and improved by Markides and Smith [9] and Solanki et al. [28,29,30]. Furthermore, the work of 114 Markides et al. [31] represented the first attempt to introduce a non-linear characteristic into the 115 model of the NIFTE (specifically, a static temperature profile in the device's heat exchangers); this 116 approach is also undertaken in the model of the Up-THERM used in the present paper. Since the 117 NIFTE modelling methodology has been validated against experimental data generated by a device 118 prototype, it is regarded as an appropriate starting point for the modelling of the Up-THERM engine. 119 The Up-THERM engine model is described in detail in Kirmse et al. [15]. Oyewunmi et al. [16] 120 investigated the influence of different (especially organic) working fluids on the engine performance. 121 The Up-THERM model is split into thermal and fluid domains, with a model derived for 122 each component in these domains. The dominant thermal or fluid processes in each component is 123 described by first-order spatially lumped, ordinary differential equations (ODEs). Electrical analogies 1 24 are drawn such that thermal resistance and fluid drag are represented by resistors, liquid inertia 125 by an inductor, and hydrostatic pressure difference and vapour compressibility by capacitors. The 126 passive electrical components are interconnected in an electric circuit network in the same way as 127 they are connected in the physical device. For the following components small fluctuations around 128 the respective time-mean value are assumed, allowing for linearization: the piston including the fluid around it and the slide bearing; the liquid column in the displacer cylinder; the connection 130 tube; the hydraulic accumulators; and the hydraulic motor. The piston valve in the displacer cylinder 1 31 and the two check valves exhibit inherently non-linear behaviour. The temperature profile in the 1 32 heat exchanger walls is assumed to follow a hyperbolic tangent function, which has been validated 133 experimentally in Kirmse *et al.* [15]. Hence, these three components are modelled non-linearly.

2.2.1. Thermal domain 1 35

1 34

In the thermal domain heat that is added to the cycle and converted into mechanical (pV) work, 136 giving rise to an increase in pressure and inducing flow. The useful flow quantity of the added heat 1 37

is its associated entropy flow. The entropy flow rate associated with the heat is: 1 38

$$\dot{S} = \frac{\dot{Q}_{\rm in}}{T_0} = \frac{h A_{\rm hx}}{T_0} \left[T_{\rm hx}(y(t)) - T_{\rm wf} \right], \tag{1}$$

where \hat{S} is the rate of change of entropy, T_0 the constant equilibrium temperature, \hat{Q}_{in} the rate, at which heat is added to the cycle, h is the constant heat transfer coefficient, A_{hx} the constant area over which phase-change heat transfer occurs, $T_{hx}(y(t))$ the temperature of the heat exchanger wall, which is in contact with the vapour-liquid interface and dependent on its position, and T_{wf} the temperature of the working fluid. A detailed explanation of the heat transfer process can be found in Solanki *et al.* [29] and Markides *et al.* [9]. The heat transfer coefficient h can be calculated using the following correlation [32]:

$$h = h_{\rm ref} F_p * F_{\rm W} F_{\rm q} \,. \tag{2}$$

In Equation 2 $h_{\rm ref}$ is a reference heat transfer coefficient for a specific fluid, which is determined 146 experimentally, and F_i non-dimensional functions that are independent of the fluid. The reference 147 heat transfer coefficient for *n*-pentane is $3300 \text{ W/m}^2 \text{ K}$, that for *n*-hexane is $3200 \text{ W/m}^2 \text{ K}$, and that for 148 *n*-heptane is 2900 W/m² K. The pressure factor F_p* takes the dependence of h on the reduced pressure 149 of the fluid into account. For the three *n*-alkanes used in this work the value of F_p * varies between 150 1.6 and 14. The wall factor $F_{\rm w} = F_{\rm wm}F_{\rm wr}$ is dependent on the properties of the heat-exchanger wall 151 material and surface roughness of the heat-exchanger wall. For steel as the heat-exchanger material 152 a wall material factor $F_{\rm wm}$ of 0.61 is used. As no information relating to the surface roughness is 153 available the surface roughness factor F_{wr} is set to 1, as recommended in reference [32]. The heat 154 input factor F_q takes the dependence of the heat transfer coefficient on the heat input Q_{in} into the 155 cycle into account, and its value varies in the range between 3.5 and 7.2. Thus, the value of the heat 156 transfer coefficient varies between $12600 \text{ W/m}^2 \text{ K}$ and $170000 \text{ W/m}^2 \text{ K}$. 157

For the investigated refrigerants the heat values of h_{ref} are 4200 W/m² K (R134a) and 4100 W/m² K (R227ea). Thus, thes heat transfer coefficients range between 71000 and 87000 W/m² K.

As the heat transfer coefficient is an input to the model, but the heat input an output of the model, an iterative approach is chosen to calculate h. Therein the heat input of the previous step is taken to calculate the heat transfer process of the current step. Iterations are stopped when convergence is achieved. A detailed description of the calculation for the heat transfer coefficient can be found in Kirmse *et al.* [15] and Oyewunmi *et al.* [16].

¹⁶⁵ The non-linear profile of the heat-exchanger wall temperature can be described by [31]:

$$T_{\rm hx}(y) = \alpha \tanh\left(\beta y\right) \,,\tag{3}$$

where α is the amplitude of the temperature in the heat-exchanger wall. The parameter β is related to the height of the heat exchanger where the temperature profile saturates, which is assumed to be at the maximum length of the heat exchanger. This temperature profile has been validated experimentally in Kirmse *et al.* [15] and thus is deemed suitable for the present paper. As can be seen in Equation 3, the temperature of the heat-exchanger wall is dependent on the position *y* of the vapour-liquid interface. A graphical representation of the temperature profile is shown in Figure 2.

As the remainder of the engine is described in the fluid domain, the thermal and fluid domain must be coupled. This can be achieved by using the following three coupling equations [9]:

$$S = \rho_{\rm v} \, s_{\rm fg} \, U_{\rm th} \,, \tag{4}$$

$$T_{\rm hx}\left(y\left(t\right)\right) = \left(\frac{\mathrm{d}T}{\mathrm{d}P}\right)_{\rm sat} P_{\rm th}; \quad T_{\rm wf} = \left(\frac{\mathrm{d}T}{\mathrm{d}P}\right)_{\rm sat} P_{\rm v}, \tag{5}$$

where ρ_v is the density of the vapour working fluid, s_{fg} the phase-change specific entropy and U_{th} the volumetric flow rate. The rate of change of working-fluid temperature with pressure in the saturation



Figure 2. Non-linear temperature profile in the heat exchangers. At length l_{hx} of the heat exchanger the temperature saturates.

region is denoted by $\left(\frac{dT}{dP}\right)_{sat}$, the thermal pressure by P_{th} and the pressure in the displacer cylinder gas spring by P_v .

178 2.2.2. Fluid domain

In the fluid domain quasi-steady, laminar and fully developed flow is assumed, as the Reynolds and
 Wormersley numbers are sufficiently low. Viscous drag in the displacer cylinder, connection tube,
 and load arrangement are represented by a resistance:

$$R = \frac{128\mu l}{\pi d^4} \,,\tag{6}$$

where μ is the dynamic (absolute) viscosity of the working fluid, *l* the length of the liquid column and *d* its diameter. Liquid inertia is represented by an inductance:

$$L = \frac{4\rho_l l}{\pi d^2} \,, \tag{7}$$

where ρ_1 is the density of the liquid working fluid. The hydrostatic pressure of the liquid column in the displacer cylinder and the vapour compressibility in the hydraulic accumulators and displacer cylinder gas spring are represented by capacitances:

$$C_{\rm d} = \frac{\pi d^2}{4\rho_1 g}; \quad C_{\rm a} = \frac{V_0}{\gamma P_0}; \quad C_{\rm v} = \frac{V_0 + V_{\rm v}}{\gamma (P_0 + P_{\rm v})},$$
 (8)

with *g* the gravitational acceleration, γ the heat capacity ratio, V_0 and P_0 the equilibrium volume and pressure, and V_v and P_v the time-varying volume and pressure. For a detailed description of the resistances, inductances and capacitances see Kirmse *et al.* [15].

To model the piston and the surrounding fluid flow, a force balance is applied to the piston and the surrounding fluid (simplified Navier-Stokes). In the slide bearing underneath the piston valve, the piston and liquid are separated. While the piston slides through one channel, lubricated by a small amount of liquid, the fluid flows through two separate channels. As the channels have a constant height, the hydrostatic pressure difference is constant and hence, is neglected. Thus, the electrical analogies for the piston, fluid, and slide bearing are:

$$R_{l,1} = \frac{128c_2l_p\mu}{\pi c_1c_3}; \quad R_{l,2} = \frac{128c_2l_p\mu}{\pi c_1\left(c_1 - 2c_2d_p^2\right)}; \quad C_l = \frac{\pi^2 c_1\left(c_1 - c_2d_p^2\right)}{64c_2^2k_{\rm ms}}; \quad L_l = \frac{64c_2^2m_p}{\pi^2 c_1\left(c_1 - 2c_2d_p^2\right)};$$

$$R_{\rm p} = \frac{64l_{\rm p}\mu}{\pi d_{\rm p}^2 c_1}; \quad C_{\rm p} = \frac{\pi^2 d_{\rm p}^2 c_1}{32k_{\rm ms} c_2}; \quad L_{\rm p} = \frac{32m_{\rm p} c_2}{\pi^2 d_{\rm p}^2 c_1}; \quad R_{\rm b,p} = \frac{16\mu l_{\rm b}}{\pi^2 d_{\rm p}^3 \delta}; \quad L_{\rm b,p} = \frac{4\rho_{\rm ss} l_{\rm b}}{\pi d_{\rm p}^2}$$
(9)
$$L_{\rm b,l} = \frac{4\rho_{\rm l} l_{\rm b}}{\pi d_{\rm p}^2}; \quad R_{\rm b,l} = \frac{128\mu l_{\rm b}}{\pi d_{\rm b}^4}.$$

In Equation 9 l_p is the length of the piston, d_p its diameter, m_p its mass, δ the size of the gap between the piston and the walls of the slide bearing, and ρ_{ss} the density of stainless steel, the material the piston is made of. The slide bearing has the length l_b and $d_{b,l}$ denotes the diameter of the channels through which the fluid flows, k_{ms} is the spring constant of the mechanical spring; c_1 , c_2 and c_3 are geometric constants, with $c_1 = d_c^2 - d_p^2$, $c_2 = \ln (d_c/d_p)$, and $c_3 = c_2 (d_c^2 + d_p^2) - c_1$.

Further to the linear descriptions of the piston, liquid column in the displacer cylinder, and connection tube, the inherently non-linear behaviour of the piston valve, formed by the piston and the displacer cylinder wall, is described as a non-linear resistance using a Heaviside step function H{.}:

$$R_{\rm pv} = R_{\rm min, pv} + \frac{1}{2} R_{\rm max, pv} \left(-H \left\{ P_{\rm l,d} - \rho_{\rm l} g l_{\rm pv} \right\} + H \left\{ P_{\rm l,d} + \rho_{\rm l} g l_{\rm pv} \right\} \right) , \tag{10}$$

where $R_{\min,pv}$ and $R_{\max,pv}$ are the minimum and maximum value of the resistance, respectively; $P_{l,d}$ the hydrostatic pressure difference across the liquid in the displacer cylinder, which represents the position of the piston; and l_{pv} the height at which the valve opens or closes. Furthermore, a non-linear resistance is introduced that prevents the amplitudes of oscillation in the displacer cylinder from becoming longer than the displacer cylinder length:

$$R_{\rm nl} = R_{\rm max,nl} \left(H \left\{ P_{\rm l,d} - \rho_{\rm wf} g l_{\rm nl} \right\} + H \left\{ -P_{\rm l,d} - \rho_{\rm wf} g l_{\rm nl} \right\} \right) \,. \tag{11}$$

Due to the design of the engine this resistance is used for all heat source temperatures and working fluids. It is desirable that the piston and the vapour-liquid interface oscillates along the entire length of the heat exchanger to use the maximum available area of the heat exchanger. When the piston hits the top or bottom of the displacer cylinder, it can be ensured that the amplitudes of oscillations are sufficiently large. This behaviour has also been observed in the prototype testing.

In Equation 11 $R_{\text{max,nl}}$ is the maximum value of the resistance and h_{nl} the maximum amplitude.

216 2.2.3. Load

In the load arrangement a hydraulic motor is chosen to convert the energy of the fluid into shaft work.
The hydraulic motor needs to be supplied with an (almost) constant unidirectional flow. Therefore,
two check valves convert the oscillating fluid flow into a unidirectional flow. The Check valves are
described as a non-linear resistance:

$$R_{\rm cv} = R_{\rm max, cv} \mathbf{H}\{U\}, \tag{12}$$

where $R_{\max,cv}$ is the maximum resistance when the valve is closed. The two hydraulic accumulators dampen the amplitudes of pressure and volumetric displacement. They are described linearly using Equation 8. The losses and inertia of the hydraulic motor are calculated using a torque balance on the motor. To calculate the power that can be extracted from the engine Ohm's law is used. Thus, the resistance, inductance and power of the engine are:



Figure 3. Circuit diagram of the Up-THERM engine. The colours represent the same domains (thermal, fluid, and load) of the engine as shown in Figure 1.

$$R_{\rm hm} = \frac{16\mu_{\rm hub}d_{\rm sh}^3 l_{\rm sh}}{\pi\epsilon d^4 d_{\rm hm}^2}; \quad L_{\rm hm} = \frac{8m_{\rm hm}}{\pi d^4}; \quad \dot{W}_{\rm hm} = R_{\rm gen} U_{\rm hm}^2.$$
(13)

In the above equation the dynamic viscosity of the lubricant is described by μ_{lub} ; the diameter and length of the shaft by d_{sh} and l_{sh} respectively; the gap between the shaft and motor by ϵ ; the diameters of the tube and motor by d and d_{hm} respectively; the mass of the motor by m_{hm} ; and the flow rate through the motor by U_{hm} . The load resistance R_{gen} is determined empirically to achieve the maximum power output of the engine.

231 2.3. Up-THERM engine model

The models of each component in the three domains are combined to form the dynamic Up-THERM 232 engine model. As electrical analogies are used to represent the dominant thermal and fluid effects in 233 each component, an electronic circuit diagram can be drawn to represent the entire device. This circuit 2 34 is shown in Figure 3. The values for the resistances, inductances, and capacitances (or collectively, 235 RLC parameters) from Fig. 3 are summarized in Table 1. Based on a given specification for the 236 employment of an Up-THERM heat converter as a CHP prime-mover (suggested in the testing 237 procedure of a prototype Up-THERM engine), the proposed physical dimensions of the Up-THERM 238 heat converter along with the working-fluid properties are used to define all RLC model parameters. 239 Since the values of some of the electrical components are dependent on the fluid properties, the values 240 given in Table 1 are for *n*-pentane at a heat source temperature of 210 °C. 241

The external heat source to the device is a stream of heat transfer fluid (thermal oil), whose mass flow rate is set to 1 kg/s in accordance with the recommended flow rate proposed for the Up-THERM prototype testing. It is assumed that no phase change of the heat transfer fluid takes place. The given heat source temperatures correspond to the inlet temperature of the hot side into the hot heat exchanger. The heat sink is a water stream with an inlet temperature of 10 °C.

247 2.4. Calculation of thermodynamic performance indicators

²⁴⁸ Three performance indicators are used in the comparison. The first is the power output of the ²⁴⁹ hydraulic motor:

Thermal-fluid effect	Component	Nominal values	Unit
Connection tube resistance	R _c	1.32×10^{3}	$kg m^{-4} s^{-1}$
Hydraulic motor resistance	<i>R</i> _{hm}	$4.31 imes 10^5$	${ m kg}{ m m}^{-4}{ m s}^{-1}$
Displacer cylinder resistance	R _d	3.21×10^3	$\mathrm{kg}\mathrm{m}^{-4}\mathrm{s}^{-1}$
Leakage flow resistance 1	$R_{1,1}$	$3.39 imes 10^7$	$\mathrm{kg}\mathrm{m}^{-4}\mathrm{s}^{-1}$
Leakage flow resistance 2	$R_{1,2}$	$6.45 imes 10^5$	$\mathrm{kg}\mathrm{m}^{-4}\mathrm{s}^{-1}$
Fluid flow in load pipes	$R_{t,1/2}$	$2.09 imes10^4$	$\mathrm{kg}\mathrm{m}^{-4}\mathrm{s}^{-1}$
Piston resistance	R _p	$4.29 imes10^4$	$\mathrm{kg}\mathrm{m}^{-4}\mathrm{s}^{-1}$
Fluid flow resistance in slide bearing	$R_{b,l}$	$2.19 imes10^7$	$\mathrm{kg}\mathrm{m}^{-4}\mathrm{s}^{-1}$
Piston resistance in slide bearing	R _{b,p}	$3.19 imes10^5$	${ m kg}{ m m}^{-4}{ m s}^{-1}$
Thermal resistance	R _{th}	$2.41 imes10^7$	$kg m^{-4} s^{-1}$
Connection tube inductance	L _c	$3.12 imes 10^5$	$\mathrm{kg}\mathrm{m}^{-4}$
Hydraulic motor inductance	$L_{\rm hm}$	$3.09 imes 10^5$	kgm^{-4}
Displacer cylinder inductance	L_{d}	$1.88 imes 10^5$	$\mathrm{kg}\mathrm{m}^{-4}$
Leakage flow inductance	L_1	$6.45 imes 10^7$	$\mathrm{kg}\mathrm{m}^{-4}$
Fluid flow in load pipes	$L_{t,1/2}$	$1.42 imes 10^6$	$\mathrm{kg}\mathrm{m}^{-4}$
Piston inductance	Lp	$5.96 imes 10^6$	$\mathrm{kg}\mathrm{m}^{-4}$
Fluid flow inductance in slide bearing	$L_{b,l}$	$8.28 imes 10^6$	$\mathrm{kg}\mathrm{m}^{-4}$
Piston inductance in slide bearing	$L_{b,p}$	$4.42 imes 10^6$	$\mathrm{kg}\mathrm{m}^{-4}$
Displacer cylinder capacitance	$C_{\rm d}$	$8.18 imes10^{-8}$	$\mathrm{m}^4\mathrm{s}^4\mathrm{kg}^{-1}$
Leakage flow capacitance	C_{l}	$1.78 imes10^{-10}$	${ m m}^4{ m s}^4{ m kg}^{-1}$
Piston capacitance	Cp	$6.02 imes 10^{-10}$	${ m m}^4{ m s}^4{ m kg}^{-1}$
Hydraulic accumulator capacitance	$C_{a,1/2}$	$1.25 imes 10^{-9}$	${ m m}^4{ m s}^4{ m kg}^{-1}$

Table 1. Electrical analogy for linear components shown in Fig.3.

$$\dot{W}_{\rm hm} = \int R_{\rm gen} U_{\rm hm} dV_{\rm hm} \,, \tag{14}$$

where $V_{\rm hm} = \int U_{\rm hm} dt$ is the volume displaced in the hydraulic motor during one cycle. The second performance indicator is the exergy (second law) efficiency, which can be calculated as the ratio between the power output and the exergy input into the system:

$$\eta_{\rm ex} = \frac{\dot{W}_{\rm hm}}{\int P_{\rm th} dV_{\rm th}} \,. \tag{15}$$

In the above equation $\dot{W}_{\rm hm}$ is the power output and $\int P_{\rm th} dV_{\rm th}$ the exergy input into the cycle. The thermal pressure $P_{\rm th}$ is the equivalent of the heat-source temperature in the fluid domain and the thermal volume equivalent to the entropy that is generated during heat addition in one cycle, see Eqs. 4 and 5. Hence, it can be regarded as $\int T dS$, which corresponds to an exergy. $V_{\rm th} = \int U_{\rm th} dt$ is the entropy flow into the working fluid expressed in the fluid domain. The thermal efficiency as a third performance indicator relates the power output of the cycle to the heat input:

$$\eta_{\rm th} = \frac{\dot{W}_{\rm hm}}{\dot{Q}_{\rm in}}\,,\tag{16}$$

with \dot{W}_{hm} from Equation 14 and \dot{Q}_{in} from Equation 1.

The oscillation frequency as a fourth performance indicator is unique to the Up-THERM engine in this comparison. It is calculated with the period T of one cycle:

$$F = \frac{1}{T}.$$
 (17)



Figure 4. Schematic of the sub-critical ORC engine.

262 2.5. Organic Rankine cycle model development

In Fig. 4 we provide a schematic of the sub-critical organic Rankine (ORC) cycle that is modelled in this paper. As the Up-THERM heat converter has a simple design with no super-heating and no regeneration, this simple layout is chosen for the ORC engine used in the comparison in this work; a recuperator/regenerator would increase the cost and complexity of the ORC engine in comparison to the Up-THERM engine. Furthermore, it has been shown that super-heating of the working fluid is in some cases detrimental to the ORC performance [20,33].

²⁶⁹ The liquid working fluid is pumped from State 1 to State 2, requiring the pump work:

$$\dot{W}_{\text{pump}} = \dot{m}_{\text{wf}} (h_2 - h_1) = \dot{m}_{\text{wf}} \frac{(h_{2,\text{is}} - h_1)}{\eta_{\text{is,pump}}},$$
 (18)

where the isentropic efficiency of the pump $\eta_{is,pump}$ is set to 0.75. Heat is added to the cycle from the heat source. The heat transfer process is assumed to be isobaric, has no heat losses and a minimum pinch temperature difference in the evaporator of 10 °C:

$$\dot{Q}_{\rm in} = \dot{m}_{\rm wf} \left(h_3 - h_2 \right) \,.$$
 (19)

²⁷³ In the expander power is extracted from the cycle:

$$\dot{W}_{\text{exp}} = \dot{m}_{\text{wf}} (h_3 - h_4) = \eta_{\text{is,exp}} \, \dot{m}_{\text{wf}} (h_3 - h_{4,\text{is}}) \,.$$
 (20)

The isentropic efficiency $\eta_{is,exp}$ is set to 0.7 for the economic comparison and assumes the three values 0.65, 0.70 and 0.75 for the thermodynamic comparison. Finally, in the condenser heat is removed isobarically from the cycle, leaving the working fluid as saturated liquid:

$$\dot{Q}_{\text{out}} = \dot{m}_{\text{wf}} \left(h_4 - h_1 \right) = \dot{m}_{\text{cs}} c_{p,\text{cs}} \left(T_{\text{cs,out}} - T_{\text{cs,in}} \right).$$
 (21)

The net power output, which is considered as one performance indicator in this work, is the power of the expander minus the power required by the pump:

$$\dot{W}_{\text{net}} = \dot{W}_{\text{exp}} - \dot{W}_{\text{pump}} \,. \tag{22}$$

The thermal and the exergy efficiency are two further performance indicators that are considered in this work:

$$\eta_{\rm th} = \frac{W_{\rm net}}{\dot{Q}_{\rm in}} = 1 - \frac{h_4 - h_1}{h_3 - h_2}; \quad \eta_{\rm ex} = \frac{\eta_{\rm th}}{\eta_{\rm Ca}}, \tag{23}$$

where η_{Ca} is the Carnot efficiency.

280 2.6. Economic analysis of cycle components

Next to the thermodynamic performance indicators mentioned in the previous section an economic comparison is performed between the Up-THERM heat converter and the ORC engine. A Factored Estimate is carried out for both engines, which estimates the major equipment costs. Hence, the bare module costs C_{BM} of each component are determined and summed up to give the capital costs of each engine.

The costs of the heat exchangers are calculated by using the following equation [34]:

$$C_{\rm BM,hx} = C_{\rm pc}^0 F_{\rm BM} \,, \tag{24}$$

with C_{pc}^{0} the purchased cost of equipment for base conditions and F_{BM} the bare module factor, which takes into account the different material and operating pressure. The base condition considers carbon steel at atmospheric pressure and the purchased costs of equipment for base conditions is then:

$$\log(C_{\rm pc}^0) = K_1 + K_2 \log(A) + K_3 \log(A)^2,$$
(25)

where *A* is the area of the heat exchangers and K_1 , K_2 and K_3 are constants. In this work a double-pipe heat exchanger is used, which has the following values for the constants [34]: $K_1 = 3.3444$, $K_2 = 0.2745$, and $K_3 = 0.0472$. To account for the different material of the heat exchanger and pressures above atmospheric, the bare module factor is used:

$$F_{\rm BM} = B_1 + B_2 F_{\rm M} F_p \,, \tag{26}$$

with the constants $B_1 = 1.74$ and $B_2 = 1.55$ that depend on the equipment type. For the case of stainless steel heat exchangers the material factor F_M is set to 2.75. For pressures under 40 bar no adjustment is necessary so that the pressure factor F_p is set to unity. The area of the heat exchangers is calculated using a correlation by Hewitt *et al.* [35]:

$$A = \frac{\dot{Q}_{\rm in}}{h_{\rm t} \Delta T_{\rm LM}} \,, \tag{27}$$

with the heat input into the cycle Q_{in} , the total heat transfer coefficient h_t and the log mean 298 temperature difference between the heat source and the working fluid ΔT_{LM} . For the Up-THERM 299 heat converter the heat input is calculated according to Eq. 1 and for the ORC engine the heat input 300 is calculated using Eq. 19. The total heat transfer coefficient h_t considers convection from the heat 301 source to the heat-exchanger wall, conduction within the heat-exchanger wall, and convection from 302 the heat-exchanger wall to the working fluid. The heat exchanger is designed that the pressure drop 303 $\Delta P_{\rm hx}$ in the hot side of the heat exchangers does not exceed 1 bar, which corresponds to 100 W of 304 required hydraulic work to pump the hydraulic oil through the heat exchanger. The pressure drop in 305 the heat exchanger can be calculated with [35]: 306

$$\Delta P_{\rm hx} = 4 f_0 \frac{l_{\rm hx}}{d_{\rm e}} \rho_{\rm htf} \mu_{\rm htf} \,, \tag{28}$$

where d_e is the equivalent diameter including fins and the friction factor f_0 that is dependent on the Reynolds number [35]:

$$f_0 = 0.079 Re_{\rm htf}^{(-1/4)} \text{ for } Re < 2e4 ; f_0 = 0.046 Re_{\rm htf}^{(-1/5)} \text{ for } Re > 2e4 .$$
⁽²⁹⁾

The ORC engine requires a pump. In this paper we choose a positive-displacement pump due to the low power rating required. The pump cost can be calculated by the following equation [34]:

$$\log(C_{\rm BM,pump}) = 3.4771 + 0.315 \, \log(\dot{W}_{\rm pump}) + 0.1438 \, \log(\dot{W}_{\rm pump})^2, \tag{30}$$

The pump is powered by an electric motor that has the following costing equation [36]:

$$C_{BM,pump,motor} = \exp\{5.8259 + 0.13141 \ln(W_{pump}) + 0.053255 \ln(\dot{W}_{pump})^2 + 0.028628 \ln(\dot{W}_{pump})^3 - 0.0035549 \ln(\dot{W}_{pump})^4\},$$
(31)

that takes into account the power of the pump W_{pump} .

For the costs of the expander the following equation, generated from scroll expander manufacturers' data, is used:

$$\log(C_{\rm BM}) = 3.819 + 0.5422 \, \log(\dot{W}_{\rm exp}) \,. \tag{32}$$

The coefficients for the calculations of the component costs are from different years. To account for inflation the Chemical Engineering Plant Cost Index (CEPCI) [37] is used, which scales every components' cost to the same reference year. In this paper the reference year is 2014:

$$C_{\rm BM,2014} = C_{\rm BM,i} \frac{CEPCI_{2014}}{CEPCI_i} \,, \tag{33}$$

where *i* is the year for which the correlation is valid. Finally, some of the components are costed in \pounds , while others are costed in \$. The currency of choice in this paper is \pounds , however, a conversion factor of 1.42\$/ \pounds can be used readily to convert \$ into \pounds .

The Up-THERM heat converter requires two hydraulic accumulators, a hydraulic motor and one displacer cylinder. As there are no correlations for the bare module costs available, standard off-the-shelf products are selected. For the displacer cylinder a piston-accumulator is chosen, while for the hydraulic accumulators bladder accumulators are selected. The hydraulic motor is selected according to the flow rate through the hydraulic load.

324 2.7. Working fluids

In the present work we consider the use of the three *n*-alkanes (*n*-pentane, *n*-hexane and *n*-heptane) for heat-source temperatures between 210 °C and 500 °C. In the lower part of this range (*i.e.*, 210 °C to 360 °C) *n*-pentane is used as the working fluid, due to its lower critical point compared to *n*-hexane and *n*-heptane. *n*-hexane is considered in the mid part of the temperature range (*i.e.*, 260 °C to 440 °C), while *n*-heptane is used in the upper part (*i.e.*, 320 °C to 500 °C). The heat sink is for all cases constant at 10 °C.

A further thermo-economic comparison is carried out by considering the two refrigerants R134a and R227ea for low heat-source temperatures of 100 °C (R134a and R227ea) and 120 °C (R227ea). As the normal boiling point (*i.e.*, at a pressure of 1 atmosphere) of these two refrigerants is much lower than the boiling point at atmospheric pressure of the aforementioned *n*-alkanes they can be used at lower temperatures.

It should be noted that the *n*-alkanes cannot be used at these low temperatures, as the Up-THERM equilibrium pressure would be below 1 bar. Pressures below 1 bar should be avoided to avoid contamination of the heat converter from the outside. Likewise, the critical temperatures of R134a and R227ea are approximately 100 °C, which allows for maximum heat-source temperatures of 190 °C.

309 310

341 2.8. Simulation procedure

The heat-source and heat-sink temperatures, and the factors α and β that determine the shape of the 342 temperature profile along the heat-exchanger walls of the Up-THERM engine are used as inputs to 343 the Up-THERM model. Based on these boundary conditions, and the RLC parameters defined by the 344 design of the proposed Up-THERM prototype and the working fluid(s), simulations are performed 345 from which the heat input into the Up-THERM cycle is determined, as described in Section 2.2.1. 346 Furthermore, the work output, exergy efficiency and thermal efficiency can be evaluated from the 347 results of the simulation. The same heat inputs and heat-source temperatures are used in the ORC 348 engine simulations for the respective working fluid to provide a common basis for comparison of the 349 two engines. In the simulations of the ORC engine the net power output is maximized subject to the 350 pinch conditions in the heat exchangers and the heat input and heat source temperature. Moreover, 351 the maximum pressure of the working fluid in the ORC engine is set to 90% of the critical pressure 352 and the minimum pressure to 1 bar. The results of the simulations are the net power output, the 353 exergy efficiency, and the thermal efficiency. 354

355 3. Results and Discussion

In Figure 5 the power outputs of the Up-THERM heat converter and the ORC engine for the three 356 *n*-alkanes at different heat-source temperatures are shown. The marker of the ORC power output 357 shows the cycle with an isentropic efficiency of the expander of 70%, while the error bars indicate the 358 results for 65% and 75% isentropic efficiency respectively. It can be seen that for low heat-source 359 temperatures the power output of the ORC engine is generally higher than the power output of 360 the Up-THERM heat converter. Furthermore, the power output generally increases with increasing 361 heat-source temperature in both engines. In particular, for *n*-pentane the power output of the 362 Up-THERM heat converter increases from 0.5 kW at 210 °C to 7.0 kW at 360 °C. For *n*-hexane the power output of the Up-THERM heat converter increases from 0.4 kW at 260 °C to 7.9 kW at 440 °C 364 and for *n*-heptane from 0.4 kW at 320 °C to 5.4 kW at 500 °C. 365

In the same temperature ranges the net power output of the ORC engine rises from 4.0 kW 366 (*n*-pentane), 2.0 kW (*n*-hexane) and 2.4 kW (*n*-heptane) to 6.6 kW (*n*-pentane), 5.6 kW (*n*-hexane) 367 and 4.1 kW (*n*-heptane). Especially for *n*-hexane and *n*-heptane it can be observed that at increasing 368 heat-source temperatures the difference in the power output of the two engines becomes less 369 pronounced until, at the highest heat-source temperatures the Up-THERM heat converter surpasses 370 the ORC engine in terms of power output. This is due to the heat input into both engines, which levels 371 off at high heat-source temperatures for each working fluid. While for the Up-THERM heat converter 372 the exergy input into the cycle, which is always increasing with increasing heat-source temperatures, is more relevant to create useful power, for the ORC engine the heat input is considered to create 374 useful power. As the heat input is levelling off for high heat-source temperatures of each working 375 fluid and the thermal efficiency is constant (see Fig. 7), the power output levels off as well. 376

For the Up-THERM heat converter the increasing power output is due to the increasing 377 temperature difference between the heat source and heat sink and the increasing equilibrium pressure 378 for increasing heat-source temperatures. A higher equilibrium pressure allows for higher amplitudes 379 of pressure and volumetric displacement, which in turn leads to higher power outputs. Moreover, 380 the heat input into the Up-THERM cycle increases with increasing heat-source temperature, due to 381 the increasing temperature difference between heat source and working fluid and the increasing heat 382 transfer coefficient h. From Eq. 2 it can be seen that h is dependent on the reduced pressure of the 383 fluid. When the pressure increases, h increases and hence, the heat input into the Up-THERM cycle 384 increases. As the heat input is equal for the same heat-source temperature and working fluid for the 385 Up-THERM heat converter and the ORC engine, the heat input into the ORC engine also increases 386 with increasing heat-source temperature. This leads to higher power outputs in the Up-THERM heat 387 converter and the ORC engine. 388



Figure 5. Power output from the Up-THERM heat converter and the ORC engine for different working fluids at different heat-source temperatures. For the ORC engine the circles indicate an expander isentropic efficiency of 0.70 and the error bars isentropic efficiencies of 0.65 and 0.75, respectively.

The exergy efficiencies of the Up-THERM heat converter and the ORC engine are shown in Fig. 6 389 for the investigated *n*-alkanes and heat-source temperatures. As in Fig. 5 for the ORC exergy efficiency 390 the markers show results for 70% isentropic expander efficiency, while the error bars indicate the 391 results for 65% and 75% respectively. The exergy efficiency of the ORC engine decreases from 34.3% at 392 210 °C to 25.7% at 360 °C for *n*-pentane, from 28.5% at 260 °C to 22.1% at 440 °C for *n*-hexane and from 393 22.7% at 320 °C to 18.7% at 500 °C for *n*-heptane. This is due to the constant thermal efficiency (14.2% 394 for *n*-pentane, 13.3% for *n*-hexane and 11.9% for *n*-heptane) for the *n*-alkanes in the ORC engine, see 395 Fig. 7. This constant thermal efficiency is a result of the sub-critical constraint on the ORCs engines 396 (*i.e.*, evaporating the working fluid at sub-critical pressures) employed to maintain a phase-change 397 similarity with the Up-THERM converter. Since the heat-source temperatures are higher than the 398 critical temperatures of the working fluids, each working fluid is evaporated at the set sub-critical 399 pressure limit (95% of the critical pressure), whereby the optimal cycles have similar profiles on a 4 00 T-s or P-h diagram, and hence the resulting ORC engines have similar thermal efficiencies (see also 4 01 Eq. 23). As the heat-source temperature increases, the Carnot (*i.e.*, maximum possible) efficiency 4 0 2 increases, leading to a decreasing exergy efficiency, which is consistent with its definition in Eq. 23. 403

For the Up-THERM heat converter the exergy efficiencies of all three *n*-alkanes rise first with 4 04 increasing heat-source temperature and, after having reached a maximum, decrease for further 4 05 increasing heat-source temperatures. When the heat-source temperature increases, the heat input 4 06 and exergy input into the cycle increase. However for temperatures above 310 °C (n-pentane), 400 °C 407 (*n*-hexane) and 450 °C (*n*-heptane) the heat input levels off. This can be seen as the maximum heat 408 input into the cycle for each working fluid. However, due to the increasing heat-source temperature, 4 0 9 the exergy input into the cycle does not level off but increases further. This leads to a decreasing 410 41 exergy efficiency. The maximum η_{ex} for *n*-pentane is 41.6%, for *n*-hexane 42.7% and for *n*-heptane 43.7%. Thus, with increasing chain lengths of the *n*-alkanes, the maximum exergy efficiency increases. 412 This is in contrast with the ORC engine, where with increasing chain length of the *n*-alkanes the 413 maximum exergy efficiency decreases. 414

Next to the exergy efficiency the thermal efficiency is shown in Fig. 7. The thermal efficiency
 of the Up-THERM engine increases for increasing heat-source temperatures. As the heat input and
 power output first increase with increasing heat-source temperatures, the thermal efficiency increases



Figure 6. Exergy efficiency the Up-THERM heat converter and the ORC engine for different working fluids at different heat-source temperatures. For the ORC engine the circles indicate an expander isentropic efficiency of 0.70 and the error bars isentropic efficiencies of 0.65 and 0.75, respectively.

slowly. When the heat input levels off at the aforementioned temperatures, the increase of thermal efficiency becomes steeper. A higher heat-source temperature leads to higher equilibrium pressures and higher oscillation amplitudes of pressure and volumetric displacement. Thus, a higher pressure drop across the hydraulic motor can be observed, leading to higher power outputs. The power output is defined as $\dot{W}_{\rm hm} = (R_{\rm gen}U_{\rm hm}) U_{\rm hm}$ in Eq. 13, with $\Delta P_{\rm load} = R_{\rm gen}U_{\rm hm}$ the pressure drop across the load. As the load resistance $R_{\rm load}$ is determined empirically for maximum power output, its value grows for increasing heat-source temperatures.

The thermal efficiency of the ORC engine stays constant for every working fluid over the 425 investigated temperature range as the working fluid is expanded from the saturated vapour curve. 426 For increasing chain-lengths of the *n*-alkanes, the thermal efficiency of the Up-THERM heat converter 427 and the ORC engine decrease (at the same heat-source temperature). For the ORC engine this is due 428 to the lower evaporation pressure, which is constant over the investigated temperature ranges for 429 each respective working fluid. For the Up-THERM heat converter the equilibrium pressure decreases 4 30 with increasing chain-lengths of the *n*-alkanes, leading to a decreased power output (see Fig. 5) and 4 31 decreasing thermal efficiency. 4 3 2

After having looked at the thermodynamic performance of the two engines, the economic 433 performance is investigated in more detail. Therefore, in Figs. 8a and 8b the bare module costs of the 4 34 Up-THERM heat converter and the ORC engine for *n*-pentane at different heat-source temperatures 4 35 are shown, which can be considered as capital costs of the two engines. The Up-THERM heat 4 36 converter has lower capital costs than the ORC engine for all investigated heat-source temperatures. 4 37 The biggest costs are associated with the heat exchangers in the Up-THERM heat converter and the 4 38 ORC engine. In this paper it is implicit that the hot and cold heat exchangers of the Up-THERM 4 3 9 440 heat converter are the same size, as it is assumed that the equilibrium temperature lies half-way between the hot and cold heat exchanger and thus, the length of both heat exchangers is identical. 441 The piston accumulator and hydraulic motor have the smallest contribution to the capital costs of the 442 Up-THERM heat converter, as these are commercially available off-the-shelf products. The hydraulic 443 accumulators have slightly higher cost, due to the relatively high pressures they have to endure. 444 The costs of the hydraulic motor decrease with increasing heat-source temperatures as the flow 445



Figure 7. Thermal efficiency for the Up-THERM heat converter and the ORC engine for different working fluids at different heat-source temperatures. For the ORC engine the circles indicate an expander isentropic efficiency of 0.70 and the error bars isentropic efficiencies of 0.65 and 0.75, respectively.

rate through it decreases, while the pressure drop across the hydraulic motor increases. Due to thedecreasing flow rates smaller hydraulic motors can be utilized for higher temperatures.

The evaporator and condenser of the ORC engine contribute the most to its costs. The costs of the evaporator decrease for increasing heat-source temperatures, while the costs of the condenser stay almost constant over the investigated temperature range. As for higher heat-source temperatures the working fluid mass flow rate increases and hence more pump power is required, the pump costs increase for increasing heat source temperatures. Similarly, as the power output increases for increasing heat-source temperatures, the cost of the expander rises.

The simple design of the Up-THERM heat converter together with the utilization of commercially available products leads to the economic advantage over the ORC engine, which uses a pump and expander. Due to the increasing heat input into the cycle, which corresponds to increasing areas of the heat exchangers, and the dominating costs of the heat exchangers in the Up-THERM heat converter, the lowest capital costs are observed for low temperatures. The costs of the ORC heat exchangers are higher than the costs of the Up-THERM heat exchangers, as a larger area is required to evaporate/condense the working fluid.

In Figs. 9a and 9b the bare module costs of both engines are shown for *n*-hexane at heat-source 4 61 temperatures between 260 °C and 440 °C. Similar to the previous figure for *n*-pentane the Up-THERM 462 heat converter has lower capital costs than the ORC engine. In general the capital costs of the 463 Up-THERM heat converter are about £6000 lower for *n*-hexane than for *n*-pentane. This is due to the 4 64 lower heat input into the cycle and consequently a smaller area of the heat exchanger, which leads to 4 65 significantly lower overall costs, as the heat exchangers contribute the most to the Up-THERM costs. 466 The costs of the ORC engine are approximately £10000 lower for *n*-hexane than for *n*-pentane, due to 467 smaller, and hence cheaper, heat exchangers. 468

Finally, in Figs. 10a and 10b the capital cots of the Up-THERM heat converter and the ORC engine
 for *n*-heptane are shown. The capital costs of both engines are approximately equal for *n*-heptane and
 n-hexane, due to similar-sized heat exchangers.

⁴⁷² Next to applications in the aforementioned temperature range, a further thermo-economic ⁴⁷³ comparison at temperatures of 100 °C and 120 °C is performed. For these temperatures the two



(b) Bare module costs for ORC engine.

Figure 8. Bare module costs for the Up-THERM heat converter and the ORC engine for *n*-pentane at different heat-source temperatures.



(b) Bare module costs for the ORC engine.

Figure 9. Bare module costs for the Up-THERM heat converter and the ORC engine for *n*-hexane at different heat-source temperatures.



(b) Bare module costs for the ORC engine.

Figure 10. Bare module costs for the Up-THERM heat converter and the ORC engine for *n*-heptane at different heat-source temperatures.



Figure 11. Bare module costs for the Up-THERM heat converter and the ORC engine for the refrigerants R134a and R227ea at different heat-source temperatures.



Figure 12. Specific costs for the Up-THERM heat converter and the ORC engine for *n*-pentane at different heat-source temperatures.

refrigerants R134a and R227ea are considered as working fluids. The bare module costs for the
Up-THERM heat converter and the ORC engine for R134a and R227ea are shown in Fig. 11. It can
be seen that the total costs of the Up-THERM heat converter are lower than the total costs of the
ORC engine for each working fluid at the respective heat-source temperature. However, compared
to *n*-pentane, *n*-hexane and *n*-heptane the capital costs are higher for those refrigerants in the
investigated temperature range. This is mainly due to the larger area of the heat exchangers, which
leads to higher bare module costs. In summary, it can be seen that the Up-THERM heat converter has
lower up-front costs than the ORC engine for applications in all investigated temperature ranges.

Next to the capital costs of the Up-THERM heat converter and ORC engine the specific capital 482 costs are evaluated in this paper. The specific costs are expressed in \pounds/kW and take the power output 483 into account. At first, the specific costs of the Up-THERM heat converter and the ORC engine are 4 84 compared for *n*-pentane as depicted in Fig. 12. The specific capital costs decrease with increasing 485 heat-source temperatures for both engines due to the rising power output and almost constant capital 486 costs. At 210 °C the specific capital costs of the Up-THERM heat converter are about five times higher 48 than those for the ORC engine. As the heat-source temperature increases the specific capital costs 4 88 of the Up-THERM heat converter decrease more rapidly than those of the ORC engine (mainly due 489 to the steeper increasing power output) so that at 310 °C the specific capital costs of the Up-THERM 490 engine and the ORC engine are approximately equal. For heat-source temperatures above 310 °C the 491 Up-THERM has lower specific costs, due to the further increasing power output of the Up-THERM 49 heat converter, while the power output of the ORC engine levels off. 493

The specific capital costs for *n*-hexane are shown in Fig. 13. For heat-source temperatures 4 94 between 260 °C and 360 °C the Up-THERM heat converter has higher costs than the ORC engine. 495 As the heat-source temperature increases the specific costs of both engines decrease. This is due to 496 the increase in power output of both engines with increasing heat-source temperature, see also Fig. 5. 49 The capital costs of both engines remain fairly constant with increasing heat-source temperature, see Figs. 9a and 9b. However, as the power output of the Up-THERM heat converter increases 499 faster than the power output of the ORC engine, the specific costs of the Up-THERM heat converter 500 decrease faster. In fact, at 370 °C heat-source temperature both engines have approximately the same 501 specific costs and at 380 °C and above, the Up-THERM heat converter is approximately 1000 £/kW 502 to 5000 £/kW cheaper than the ORC engine, which means that at 440 °C the specific costs of the 503 Up-THERM heat converter are half of those of the ORC engine. 5.04

In Fig. 14 the specific costs of the Up-THERM heat converter and the ORC engine are shown for *n*-heptane as the working fluid at different heat-source temperatures. Similarly to the cases for *n*-pentane and *n*-hexane, the specific costs for both engines decrease with increasing heat-source temperature due to the increasing power output and the constant capital costs. Also, the specific costs of the Up-THERM heat converter decrease faster than the specific costs of the ORC engine due to the steeper increase of the Up-THERM power output. For heat-source temperatures above 430 °C the ORC engine has higher specific costs than the Up-THERM heat converter.

In Fig. 15 we show the specific costs for the refrigerants R134a and R227ea for both the Up-THERM heat converter and the ORC engine. Although, the Up-THERM heat converter has lower capital costs for R134a than the ORC engine, the specific costs of the Up-THERM heat converter are much higher. In fact, the specific costs are the highest amongst all investigated fluids at all heat-source temperatures. These high specific costs are due to the low power output of the Up-THERM heat converter for R134a and R227ea, which range from 0.24 kW (R134a) to 0.65 kW (R227ea).

It should be noted that in this work only the capital costs of both engines are considered. The operating costs (such as maintenance) are not taken into account. Due to the simple design and lack of moving parts (*e.g.*, no pump) it is expected that the Up-THERM heat converter has much lower operating expenses than the ORC engine. The maintenance interval of the Up-THERM heat converter is expected to be 50000 hours, which corresponds to over five years. For ORC engines the operating



Figure 13. Specific costs for the Up-THERM heat converter and the ORC engine for *n*-hexane at different heat-source temperatures.



Figure 14. Specific costs for the Up-THERM heat converter and the ORC engine for *n*-heptane at different heat-source temperatures.



Figure 15. Specific costs for the Up-THERM heat converter and the ORC engine for R134a and R227ea at different heat-source temperatures.

and maintenance costs can contribute to the total costs per operating hour almost as much as the investment costs [38].

Lastly, we look at the capital and the specific costs of both engines using the three aforementioned 525 *n*-alkanes as working fluids at different power outputs. In Fig. 16 these costs are shown. For 526 low heat source temperatures (e.g., n-pentane and n-heptane in the Up-THERM heat converter) the 527 specific costs are high (over 80000 \pounds/kW). This is due to the low power output of the Up-THERM 528 heat converter for low temperatures when using *n*-pentane or *n*-heptane as working fluids. With 529 increasing heat source temperatures the specific costs first decrease rapidly, as the power output 530 increases. However, for power outputs over 2 kW this decrease of the specific costs is less pronounced 5 31 and appears to approach a lower limit. This indicates that there are minimum specific costs for both 5 3 2 engine types that are approached for higher power outputs. As seen in Figs. 8a–10b and the inset in 533 Fig. 16 the ORC capital costs are generally higher than the Up-THERM capital costs. 5 34

535 4. Conclusions

A pre-specified Up-THERM heat converter design in a selected prime-mover application has been 536 compared thermodynamically and economically to an equivalent ORC heat engine when using five 537 different working fluids over a range of heat-source temperatures between 210 °C and 500 °C. It 538 is noted that ORC systems are a mature technology with which we have decades of development, 539 operational and commercialization experience, whereas the Up-THERM is still in the early stages 540 of development and needs to prove its commercial potential. It is also noted that the present effort 541 only considers capital costs and does not account for operating/maintenance expenses which are 542 expected to move the balance further in favour of the Up-THERM converter. This is expected, 543 since the Up-THERM converter canbe constructed from more simple components using low-cost 544



Figure 16. Capital costs (inset) and specific costs of the Up-THERM heat converter and ORC engine plotted over the respective power output.

manufacturing techniques and materials, and has fewer moving parts and dynamic seals, whichallows longer maintenance cycles and lower operating costs than the ORC engine.

The power outputs of both engines increase at higher heat-source temperatures, while the capital costs do not change greatly with the heat-source temperature. Thus, the specific costs (in \pounds/kW) of both systems decrease significantly at progressively higher temperatures, and this is especially true for the Up-THERM converter whose net power output also increases strongly at high temperatures.

Generally, for all the working fluids considered, the ORC engine outperforms its Up-THERM counterpart purely in terms of power output, exergy efficiency and thermal efficiency. However, the capital costs are always lower for the Up-THERM heat converter. For example, with *n*-pentane as the working fluid, the Up-THERM's capital costs are only half those of the equivalent ORC engine. This leads to the possibility that at heat-source temperatures above 310 °C (for *n*-pentane), 380 °C (for *n*-hexane) and 430 °C (for *n*-heptane), the Up-THERM heat converter becomes the more affordable solution in terms of specific costs (relative to the equivalent ORC engine).

Thus, the Up-THERM heat converter can be regarded as an attractive alternative to the ORC engine at heat-source temperatures above 310 °C (*n*-pentane), above 380 °C (*n*-hexane) and above 430 °C (*n*-heptane), as the power output is comparable to or even higher than the power output of the equivalent ORC engine, while the specific costs are much lower. Since the capital costs of the Up-THERM converter are significantly lower than those of the ORC engine, the Up-THERM is an attractive solution over the entire investigated temperature range when up-front costs are crucial.

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