

1 **Buzz Off! An Evaluation of Ultrasonic**  
2 **Acoustic Vibration for the Disruption of**  
3 **Marine Microorganisms on Sensor**  
4 **Housing Materials**

5 **Abbreviated Headline: Ultrasonic Bio-fouling for Sensors**

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13 **Significance and Impact of the Study**

14 In this study, ultrasonic acoustic vibration is presented as a chemical-free,  
15 ecologically friendly alternative to conventional methods for the perturbation of microbial  
16 attachment to submerged surfaces. The results indicate the potential of an ultrasonic anti-bio-  
17 fouling method for the disruption of microbial bio-films on marine sensor housings, which is  
18 typically a principle limiting factor in their long-term operation in the oceans. With  
19 increasing deployment of scientific apparatus in aquatic environments, including further off-  
20 shore and for longer duration, the identification and evaluation of novel anti-fouling  
21 strategies that don't employ hazardous chemicals are widely sought.

22

23 **Abstract**

24 Bio-fouling is a process of ecological succession which begins with the attachment  
25 and colonisation of microorganisms to a submerged surface. For marine sensors and their  
26 housings, bio-fouling can be one of the principle limitations to long-term deployment and  
27 reliability. Conventional anti-bio-fouling strategies using biocides can be hazardous to the  
28 environment, and therefore alternative chemical-free methods are preferred. In this study,  
29 custom made testing assemblies were used to evaluate ultrasonic vibration as an anti-bio-  
30 fouling process for marine sensor housing materials over a 28-day time course. Microbial  
31 bio-fouling was measured based on (1) surface coverage, using fluorescence microscopy, and  
32 (2) bacterial 16S rDNA gene copies, using Quantitative PCR. Ultrasonic vibrations (20 KHz,  
33 200 ms pulses at 2 s intervals; total power 16.08 W) significantly reduced the surface  
34 coverage on two plastics, PMMA and PVC for up to 28 days. Bacterial gene copy number  
35 was similarly reduced, but the results were only statistically significant for PVC, which  
36 displayed the greatest overall resistance to bio-fouling, regardless of whether ultrasonic  
37 vibration was applied. Copper sheet, which has intrinsic biocidal properties was resistant to  
38 bio-fouling during the early stages of the experiment, but inhibited measurements made by  
39 PCR and generated inconsistent results later on.

40	<b>Keywords</b>
41	Bio-fouling
42	Anti-fouling
43	Ultrasonic
44	Sensor
45	Propidium Monoazide

## 46 **Introduction**

47 Environmental monitoring networks increasingly rely upon the long-term deployment  
48 of sensor equipment in the ocean (Hart and Martinez, 2006). However, the accuracy and  
49 reliability of these systems are rapidly impaired by bio-fouling. This is a process of  
50 ecological succession, which begins with the formation of a conditioning film containing  
51 dissolved organic compounds (proteins and polysaccharides) leading to the establishment of a  
52 bacterial biofilm. This paves the way for the recruitment and settlement of single-celled  
53 eukaryotes and, later, marine invertebrates (Callow and Callow, 2002). The gradual build-up  
54 of bio-material on sensors and their housings can obstruct water movement, modify the  
55 microenvironment around the sensor head, obscure optical windows and electrodes, and  
56 increase the rate of corrosion (Videla and Characklis, 1992). At the end of the deployment  
57 lifetime the apparatus must be removed to dry dock and cleaned, often requiring hazardous  
58 chemicals, and leading to increased maintenance costs and “down-time”. Sensitive equipment  
59 such as sensor electrode arrays require specialist cleaning or must be replaced after each  
60 deployment.

61 Current methods to reduce bio-fouling on sensors include, but are not limited to, the  
62 use of biocidal materials and coatings, the controlled release or generation of biocidal  
63 chemicals, and physical removal using wipers, scrapers or water jets (Manov et al., 2004;  
64 Whelan and Regan, 2006; Delauney et al., 2010). Each method has unique advantages and  
65 limitations; for example biocides contaminate the environment being monitored (Terlizzi et  
66 al., 2001), coatings can erode or become damaged and wipers require complicated moving  
67 parts, which must remain water-tight. Acoustic vibration, either within the audible (20 Hz – ≤  
68 20 KHz) or ultrasonic ( $\geq$  20 KHz) frequency range, has been demonstrated as a promising,  
69 ecologically friendly alternative to conventional methods for the removal of organic and in-  
70 organic material attached to submerged surfaces (Gittens et al., 2013; Legg et al., 2015). For

71 clarity, the term “ultrasonic” is used herein to describe the acoustic vibration used in this  
72 study, 20 kHz, which lies on the border between the audible and ultrasonic frequencies. The  
73 cavitation induced by ultrasonic pulses propagating through water can inhibit bio-fouling on  
74 solid sub-strata, including the removal or destruction of bacterial biofilms (Qian et al., 1997;  
75 Mermillod-Blondin et al., 2001), and reduction in the settlement rate of barnacle larvae  
76 (Branscomb and Rittschof, 1984; Kitamura et al., 1995; Guo et al., 2011a; Guo et al., 2011b).  
77 The latter is most pronounced at a frequency of approximately 20 KHz (Kitamura et al.,  
78 1995; Guo et al., 2011b). Not surprisingly, there are numerous patents relating to the use of  
79 acoustics for the removal of bio-fouling, and ultrasonic cleaning systems are already  
80 underdevelopment (Mazue et al., 2011) or commercially available for “in the water”  
81 maintenance of ship / boat hulls (e.g. SonicShield by CMS Marine Ltd, SHIPSONIC by  
82 Globus Benelux, Sonihull by NRG Marine Ltd, UltraSystem by Ultrasonic Antifouling Ltd  
83 and ClearHull by Ultrasonic Works Ltd). Recently, a multi-national European collaboration,  
84 the “Cleanship” project, undertook field trials of an ultrasound-based method for the  
85 detection and prevention of bio-fouling on submerged steel plates (De Carellan et al., 2014),  
86 and there have been reports of successful long-term sea trials of acoustic anti-biofouling  
87 systems fitted to commercial and military vessels, although these references are not readily  
88 available.

89         Despite the clear potential, and increasing popularity of ultrasonic anti-fouling  
90 methods, there is a paucity of data relating to the potential application for the protection of  
91 marine sensing. In this study, ultrasonic acoustic vibration is evaluated as an anti-bio-fouling  
92 method on three types of material used for the fabrication of marine sensor housings;  
93 Poly(methyl methacrylate) (PMMA), Polyvinyl chloride (PVC) and Copper (Cu). The tests  
94 were carried out on small pieces of each material, the size of a microscope slide, which were  
95 fixed to stainless steel plates via nylon spacers. The plates were submerged at 1.5 m depth, in

96 baffled housings, in a busy industrial dock for 28 days during the summer of 2015. One plate  
97 was fitted with a commercially available ultrasonic transducer, the ClearHull 110 system,  
98 which produced ultrasonic acoustic vibrations (20 KHz 200 ms pulses at 2 s intervals; total  
99 power 16.08 W) over the duration of the experiment; another was deployed without  
100 ultrasonic acoustic vibration as a control. The extent of micro-fouling on each material was  
101 quantified after 1, 3, 14, 21 and 28 days during the deployment using two principle methods;  
102 (1) surface coverage using DAPI staining with fluorescence microscopy, and (2) bacterial  
103 16S rDNA gene copy number using Quantitative Polymerase Chain Reaction (qPCR). The  
104 demonstration of ultrasonic anti-fouling is timely considering the increasing use of sensor and  
105 measurement apparatus in the ocean, and the increasing preference for environmentally  
106 friendly, biocide-free anti-fouling methods that don't contaminate the environment. To the  
107 best of our knowledge this is the first quantitative, time course evaluation of ultrasonic anti-  
108 fouling for the protection of marine sensor housings.

## 109 **Results and Discussion**

110 The effects of ultrasonic vibration on the bio-fouling of marine sensor housing  
111 materials were evaluated using custom made testing assemblies, as shown in Figure 1. The  
112 extent of bio-fouling was measured over a 28 day deployment using two parameters; surface  
113 coverage and bacterial 16S rDNA gene copy number. From the determination of the surface  
114 coverage using the DAPI staining and fluorescence microscopy, shown in Figure 2, the  
115 application of ultrasonic vibrations to the materials led to a significant (t-test,  $P = <0.05$ )  
116 reduction in DAPI staining, particularly during the later stages of the experiment (from day  
117 14). These effects were also apparent on the steel plates to which the materials were mounted,  
118 and the assembly fitted with ultrasonic anti-fouling remained mostly clear throughout the  
119 deployment, whilst the control became colonised extensively by barnacles (not shown). Cu  
120 had the lowest levels of DAPI staining during the early stages of the deployment (day 1 and  
121 3), in line with its intrinsic anti-fouling properties, but had high levels of DAPI staining from  
122 day 14. This coincided with the formation of a blue / green patina over the Cu surface which  
123 prevented proper examination, and therefore the results for Cu from day 14 onwards were  
124 inconclusive. PVC displayed the greatest resistance to bio-fouling, and had significantly  
125 lower surface coverage than PMMA, both on the control and with ultrasonic disruption.

126 The number of bacterial 16S rDNA gene copies on each material was quantified as an  
127 additional measure of bio-fouling during the later stages of the deployment, from day 14.  
128 This analysis included the biological material that accumulated outward from the surface of  
129 each sample, and which could not be measured in 2-dimensions as surface coverage. In these  
130 experiments the bio-fouling on each material was removed into sterile dock water with a  
131 sterile swab and divided into two representative samples. One of these was left untreated,  
132 whilst another was exposed to PMA, a photo-reactive compound, which diffuses across  
133 broken cell membranes and intercalates with the genome. Subsequent photo-activation of



134 PMA-DNA complexes leads to irreversible covalent modification of DNA, preventing its  
135 amplification by PCR. Thus, using membrane integrity as a proxy for cell viability, only  
136 viable cells are included in subsequent amplification of genomic DNA by PCR. The number  
137 of 16S rDNA gene copies detected on PMMA and PVC, with or without ultrasonic anti-  
138 fouling is shown in Figure 3, along with the estimated bacterial viability calculated by  
139 comparing the gene copy number with and without PMA pre-treatment. The results for Cu  
140 are not shown; the presence of labile copper in the samples inhibited PCR amplification,  
141 requiring additional DNA purification leading to loss of sample and making quantification  
142 unreliable.

143         On both plastics, the ultrasonic vibration led to a reduction in the number of bacterial  
144 gene copies. This indicates a reduction in bio-fouling in support of the results from DAPI  
145 staining, shown in Figure 2. However, the difference was only statistically significant (t-test,  
146  $P = > 0.05$ ) for PVC. PMMA presented with more DAPI staining than PVC throughout the  
147 experiment (with or without anti-fouling), but conversely the material recovered from the  
148 surface contained significantly fewer bacterial gene copies. Bacterial colonisation typically  
149 occurs during the primary stages of bio-fouling followed by the settlement of other  
150 microorganisms and small invertebrates, which may influence the bacterial component of the  
151 biofilm, for example through competition for nutrients and predation. These processes may  
152 contribute to the discrepancy between total bio-fouling estimated using DAPI staining, and  
153 bacterial bio-fouling estimated using qPCR.

154         Two principle mechanisms of action for ultrasonic disruption to biofilms  
155 include (1) detachment / dislodging of biological material from the surface and (2) damage /  
156 death of living cells from sheer stress induced by cavitation. PMA is a state of the art method  
157 for differentiating between total and viable bacterial populations on the basis of cell wall /  
158 plasma membrane integrity. On PMMA, ultrasonic anti-fouling had no significant effect on

159 bacterial viability over the experimental time course. In contrast, on the PVC there was an  
160 increase in the proportion of viable bacteria over time; specifically at day 28 the bacteria  
161 remaining on the surfaces had a greater than 90 % viability. This implies the formation of a  
162 sparse, but healthy community of organisms, with mechanism (1) predominating.

163         This preliminary investigation indicates that ultrasonic anti-fouling can significantly  
164 inhibit bio-fouling on PMMA or PVC marine sensor housings for up to 28 days, which may  
165 enhance the deployment lifetime and accuracy of the sensors contained within them. PVC  
166 showed the greatest resistance to biofouling indicating that it may be preferred for sensor  
167 housing fabrication. Although the results for Cu were inconclusive, it is likely that, due to the  
168 intrinsic biocidal properties of this material, it would have displayed the greatest overall  
169 resistance to bio-fouling, regardless of ultrasonic vibration. However, it is also relatively  
170 expensive and cannot be readily moulded into complicated designs, unlike the thermoplastics  
171 PMMA and PVC. Furthermore, there is an increasing preference for environmentally  
172 friendly, biocide-free anti-fouling methods that don't contaminate the environment or  
173 interfere with measurements; as in, for example, the inhibition of the PCR analysis in this  
174 particular study from Cu-exposed samples.

175         The results presented in this study were generated using ultrasonic acoustic vibration  
176 with a frequency of 20 kHz, which has also been demonstrated to be effective at perturbing  
177 the settlement of barnacle larvae (Kitamura et al., 1995; Guo et al., 2011b), with short 200 ms  
178 pulses every 2 s. Comprehensive optimisation of these ultrasonic acoustic parameters, made  
179 according to the material type and architecture, may achieve greater reductions in  
180 colonisation rate. Crucially, the use of short, intermittent pulses may alleviate interference to  
181 sensor measurements caused by structural vibrations, where these measurements are made in  
182 between pulses. Another, important consideration is the power consumption of ultrasonic  
183 anti-fouling over a long deployment, which is a potential limitation of this method compared

184 to, for example, the use of biocidal coatings. The Clear Hull 110 system configuration used  
185 for this study operated with a total power of 16.08 W from a 12 V transformer, connected to  
186 the mains supply (240 V). This generated a consumption of 134 mAh (based on 200 ms  
187 pulses every 2 s), which could be sustained for a period of 30 days using a battery pack  
188 containing 24 D-cell batteries (assuming 3.6 V / 17 Ah cells working with 4 batteries in  
189 series, with 6 series in parallel), or equivalent. This is within reasonable specifications,  
190 however significant reductions in power consumption could be achieved by further  
191 optimisation of the electronics and the ultrasonic acoustic parameters. The findings of this  
192 investigation show considerable promise for the development and commercialisation of  
193 ultrasonic anti-fouling systems for sensor housings and support structures, in addition to the  
194 systems already available for the protection of marine vessels.

195 **Materials and Methods**

196 **Testing Equipment.** The effect of ultrasonic acoustic vibration on the adhesion of  
197 microorganisms to three sensor housing materials, Poly(methyl methacrylate) (PMMA),  
198 Polyvinyl chloride (PVC) and Copper (Cu), was evaluated using submersible assemblies,  
199 shown in Figure 1. Each assembly was fabricated from a 3 mm thick stainless steel plate  
200 (Marine Grade 316), onto which were mounted an array of removable “Packets” supporting a  
201 sample of each material, cut to the equivalent size of a conventional glass microscope slide  
202 (25 mm by 75 mm). The packets were constructed from rigid, glass-filled Nylon blocks (100  
203 mm by 95 mm) secured to the steel plate at each corner using 20 mm A4 grade M4 hex head  
204 machine screws (Din 933) with A4 grade M4 Nylock nuts. The materials were secured within  
205 a recessed portion of the Nylon surface by two lateral stainless steel bars, screwed into the  
206 Nylon using 12 mm A4 stainless steel M4 machine screws. Each slide was cleaned with  
207 detergent and 70 % (v/v) ethanol solution to remove any residual grease and debris prior to  
208 deployment. The entire assembly was housed within an opaque polypropylene box featuring  
209 baffled openings to allow water movement and prevent large marine life from entering, and  
210 secured to the back plate using a 12 mm A4 stainless steel M4 machine screw at each corner.  
211 Two testing assemblies were deployed simultaneously, either with or without the application  
212 of ultrasonic vibration provided by a Clear Hull 110 ultrasonic anti-fouling system  
213 (Ultrasonic Works Ltd, UK). The Clear Hull 110 features an aluminium transducer attached  
214 to a control unit by a water-proof cable, and powered from a 12 V transformer connected to a  
215 240 V (mains) electrical supply. The transducer was fixed to the stainless steel back plate  
216 through a central 11 mm hole. It was set to emit 200 ms pulses at 2 s intervals, tuned to a  
217 frequency of 20 kHz with a total power of 16.08 W. A sacrificial Zn anode was attached to  
218 the back plate containing the aluminium transducer to prevent corrosion. The equipment was  
219 hung at a depth of 1.5 meters from a pontoon within the Empress Dock, Southampton (UK)

220 between the 8<sup>th</sup> of July and the 5<sup>th</sup> of August 2015. During this time the Empress Dock water  
221 had a temperature of between 18.6 and 19.1 °C, and a mean salinity of 31 ± PSU.

222 **Sample Recovery.** Three “Packets” were recovered from each assembly after 1, 3,  
223 14, 21 or 28 days post deployment. At each time point, the assemblies were removed from  
224 the water and the back plates were released from their housings. The packets were unbolted  
225 and immersed in 0.2 µm filtered dock water for later analysis. The equipment was re-  
226 assembled and submerged within five minutes to minimise disruption to the remaining  
227 samples.

228 **Fluorescence Microscopy.** Each sample of material was washed three times by  
229 immersion in Phosphate Buffered Saline (PBS) (pH 7.4). Then, the materials were immersed  
230 in 5 mL of PBS containing 100 µL of 4',6-diamidino-2-phenylindole (DAPI; Sigma-Aldrich,  
231 UK) in darkness for 5 minutes. These were removed to air, and kept in darkness, at room  
232 temperature for 20 minutes prior to observation using an EVOS™ FL cell imaging  
233 microscope (Thermo Fisher Scientific) with a DAPI filter set (344-357 nm Excitation; 447-  
234 460 nm Emission). Images were captured using a 10x objective from ten locations on each  
235 slide, which were selected at random by deriving coordinates using a random number  
236 generator. Images were collected from each material sample, at each time point over the  
237 course of the deployment. Each image was analysed using the thresholding function of  
238 ImageJ Image Analysis Software (Schneider et al., 2012) to estimate the percentage  
239 coverage. Equivalent thresholding limits were applied to each image in order to make a fair  
240 comparison.

241 **Propidium Monoazide (PMA) Pre-treatment and DNA Extraction.** PMA pre-  
242 treatment was carried out according to published methods (Magiopoulos et al., 2016). Each  
243 sample of material was immersed in 10 mL of a sterile PBS (pH 7.4) and the surface bio-  
244 fouling was removed using a sterile Buccal swab (IsoHelix, UK). The PBS and swab head

245 were transferred to a sterile, tube, vortexed, and divided into two samples. One sample was  
246 mixed with 2.5  $\mu$ L of a 50  $\mu$ M solution of PMA, and the other was mixed with 2.5  $\mu$ L of  
247 sterile water. The samples were left in darkness for 5 minutes and then, on ice, irradiated with  
248 white light from two 650 W lamps (FLASH 2000 L, DTS, Italy) placed approximately 20 cm  
249 from the samples for 3 min. Each sample was washed three times in sterile PBS prior to DNA  
250 extraction using the PowerWater DNA isolation kit (MoBio Inc., USA) according to the  
251 manufacturer's recommended protocol.

252           **Quantitative Polymerase Chain Reaction (qPCR).** The DNA recovered from each  
253 sample of material, with or without PMA pre-treatment, was used to quantify the number of  
254 16S rRNA gene copies using qPCR. PCR was carried out using universal bacterial primers,  
255 341F and 785R and 5 PRIME HotMaster Taq DNA Polymerase (5 PRIME GmbH, Germany)  
256 according to the manufacturer's recommendations. Each reaction was spiked with EvaGreen  
257 DNA binding dye (Biotium, USA) and 5  $\mu$ L of template DNA; the total volume was 20  $\mu$ L.  
258 The thermal cycling parameters were 94  $^{\circ}$ C for 2 minutes, followed by 40 cycles of 94  $^{\circ}$ C for  
259 20 seconds, 46  $^{\circ}$ C for 10 seconds and 65  $^{\circ}$ C for 50 seconds with a final elongation step of 65  
260  $^{\circ}$ C for 10 minutes. The reactions were carried out in triplicate, and measured in real-time  
261 using an Mx3005P real-time thermalcycler (Agilent Technologies, USA). A post-  
262 amplification, high-resolution melting curve was plotted to ensure product specificity. The  
263 efficiency of the PCR amplification was determined according to the method of Pfaffl (Pfaffl,  
264 2001), and was found to be 97 %. Quantification of 16S rRNA gene fragments was achieved  
265 by comparing the threshold cycle (Ct) values obtained from the samples with those from a  
266 dilution series of custom made 16S rRNA gene DNA standards with concentrations ranging  
267 from 2,000,000 to 200 copies per reaction, as described by Magiopoulos *et al* (Magiopoulos  
268 *et al.*, 2016).

269           **Statistical Analysis.** The results of the DAPI-fluorescence analysis, and qPCR  
270 analysis were tested, where appropriate, for statistical significance using the Paired T-test  
271 with a 95 % confidence. Statistical tests were carried out using Minitab (Minitab Ltd, UK;  
272 version 17).

273 **Acknowledgements**

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276 Clear Hull 110 ultrasonic anti-fouling system.

277 **Conflicts of Interest**

278 None declared.

279



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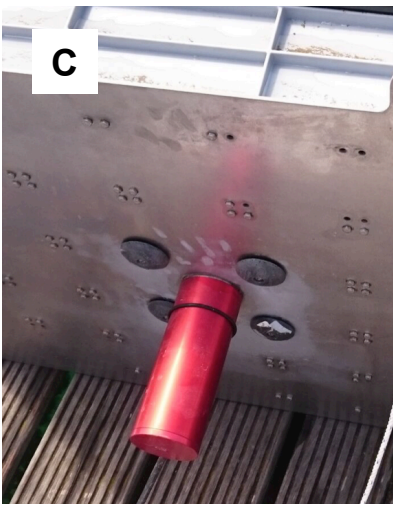
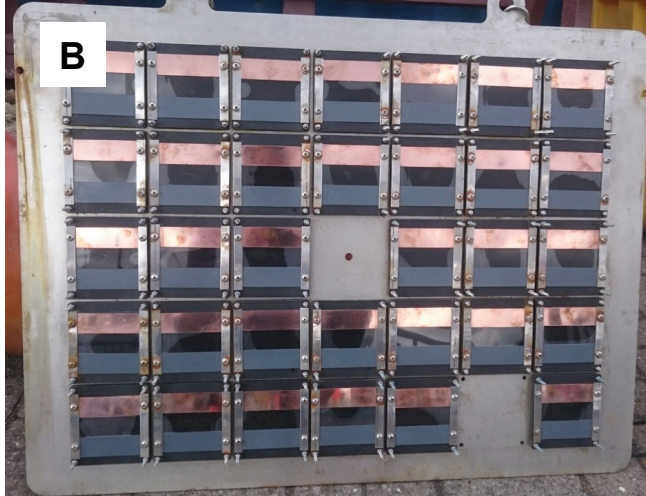
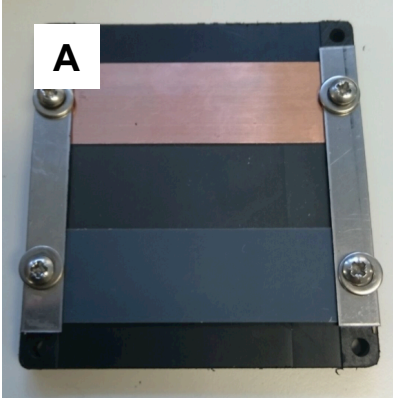
330 **Figure Legends.**

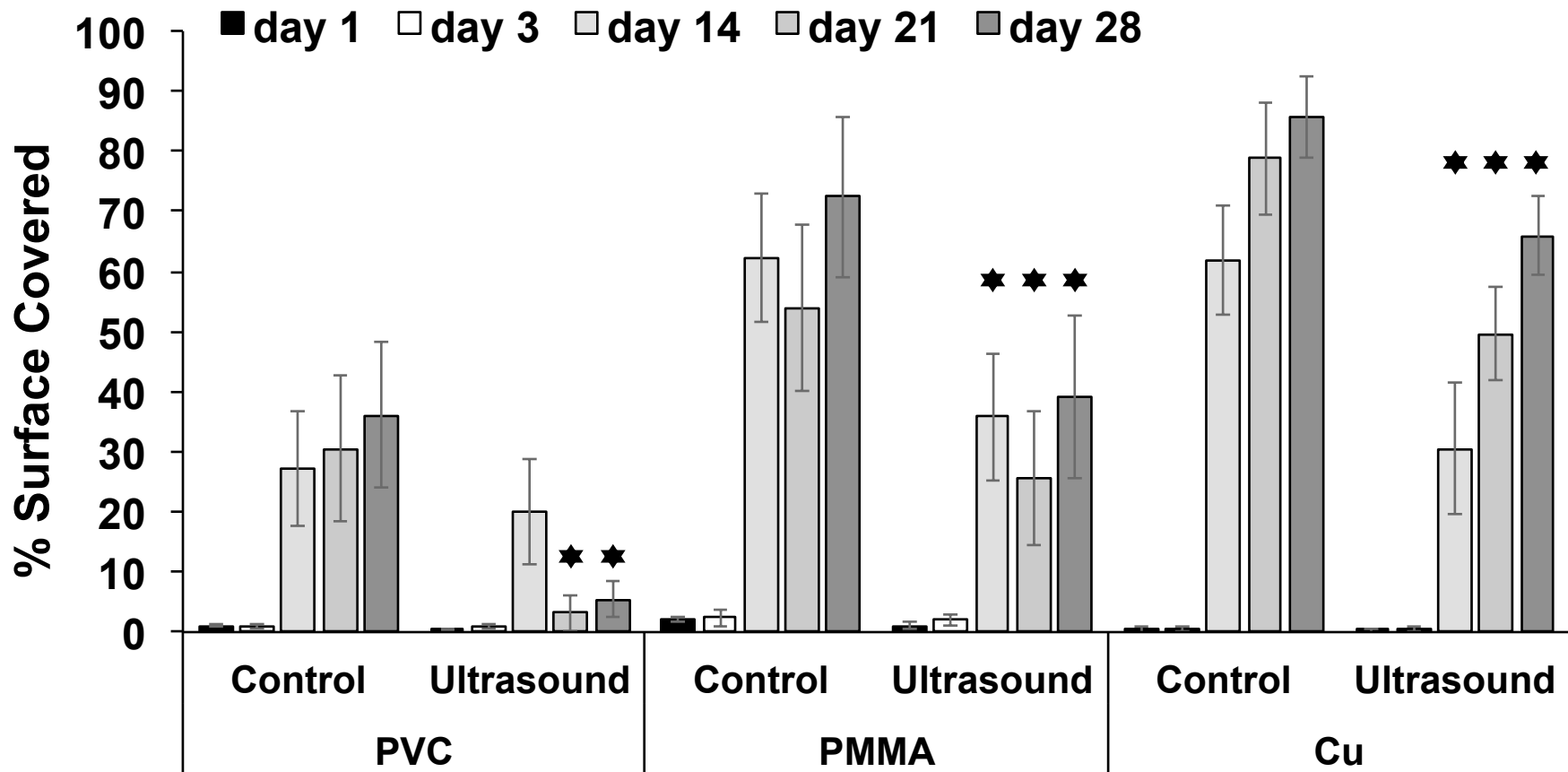
331 **Figure 1.** Photographs of the ultrasonic anti-fouling testing apparatus. The apparatus was  
332 carefully designed to enable the synchronous evaluation of bio-fouling on three materials,  
333 using a single ultrasonic transducer, and wherein a sample of each material could be  
334 recovered at regular intervals, and in a short period of time to minimise disruption to the  
335 experiment. “Packets” were prepared to contain small samples of marine sensor housing  
336 materials, Cu (top), PMMA (middle) and PVC (bottom), fixed to glass-filled Nylon blocks by  
337 stainless steel lateral support plates (Panel A). The packets were bolted to a stainless steel  
338 back-plate featuring a central hole (Panel B), used to affix a ClearHull 110 ultrasonic  
339 transducer (Panel C). This was connected to a control module on the pontoon, via a  
340 waterproof cable, and powered by a 12 V transformer connected to a mains (240 V) power  
341 supply (not shown). The assemblies were enclosed within a plastic housing featuring baffled  
342 openings to restrict the entry of large debris / marine life, whilst allowing water circulation  
343 over the surfaces (shown in Panel D with or without the steel plate attached). Two identical  
344 assemblies were deployed, with or without the ClearHull 110 ultrasonic transducer.

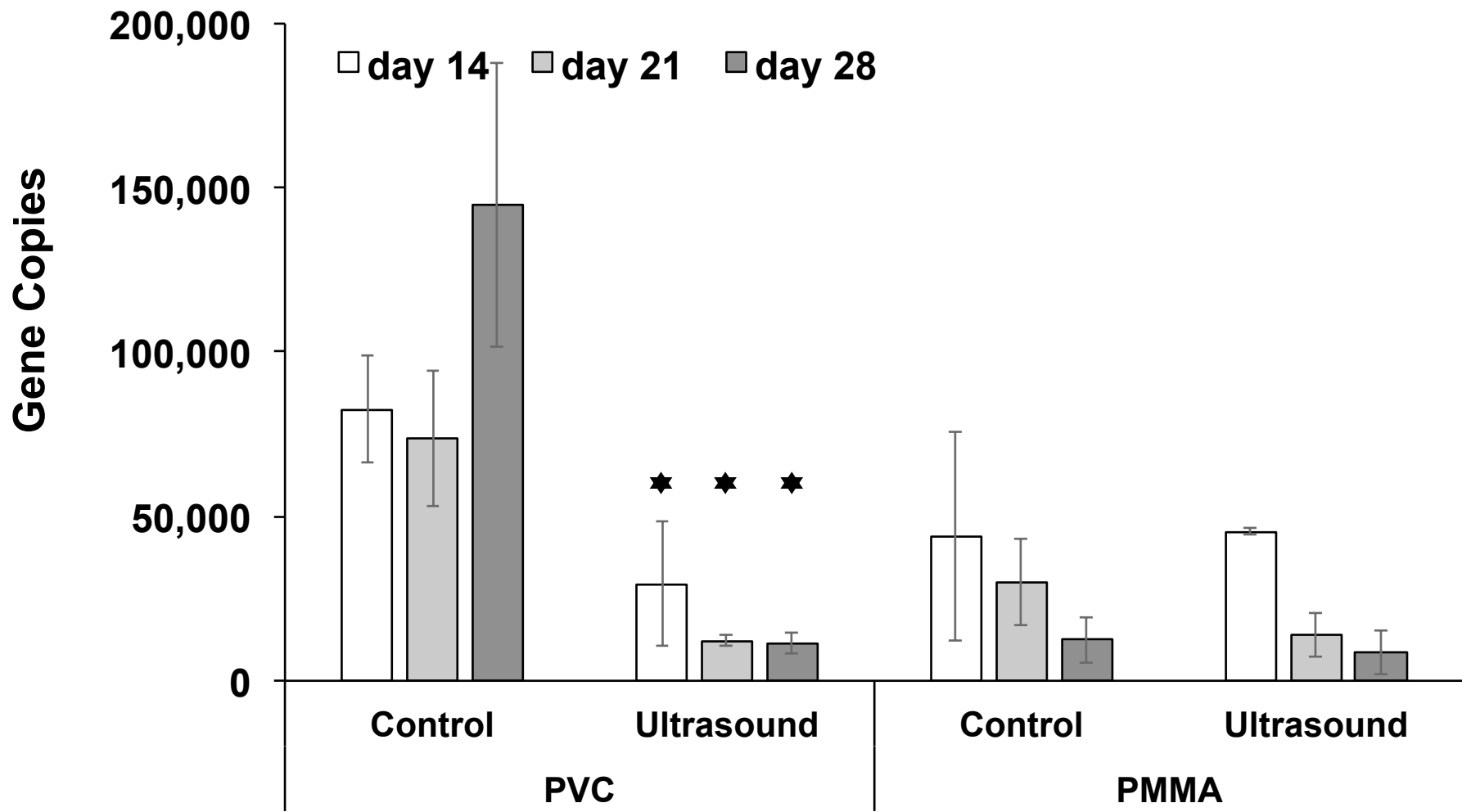
345 **Figure 2.** Percentage cover by DAPI-stained biological matter on the surfaces of sensor  
346 housing materials. The materials were deployed for up to 28 days, with or without ultrasonic  
347 anti-fouling. The results represent the mean from at least 3 replicate samples, recovered at  
348 each time point. The error bars show the standard deviation of the mean. Statistically  
349 significant differences (t-test,  $P > 0.05$ ) between control and ultrasound are denoted with an  
350 asterisk.

351 **Figure 3.** Top: bacterial 16S rDNA gene copy number measured on PMMA and PVC, after  
352 14, 21 or 28 days with or without ultrasonic anti-fouling. The results show the mean from at  
353 least 3 material samples, and the error bars show the standard deviation. Statistically  
354 significant differences (t-test,  $P > 0.05$ ) between control and ultrasound are denoted with an

355 asterisk. Bottom: the table shows the estimated percentage of viable bacteria on each material  
356 sample based on a comparison between PMA pre-treated and untreated samples.







Time Point	% Viability on PVC		% Viability on PMMA	
	Control	Ultrasound	Control	Ultrasound
Day 14	32.24	5.62	6.42	21.53
Day 21	44.98	34.20	10.71	9.63
Day 28	21.41	94.97	25.85	16.13