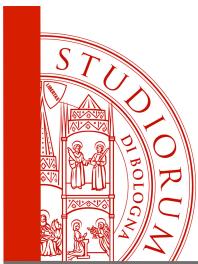


STEADY-STATE

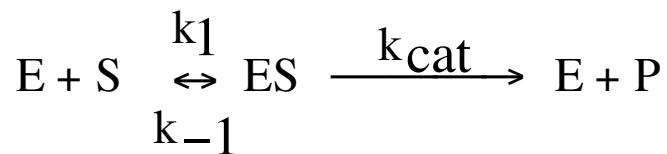
Prof. Alejandro Hochkoeppel

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STEADY-STATE



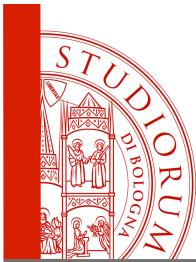
$$\frac{d[ES]}{dt} = 0$$

Briggs and Haldane:

- k_{cat} not necessarily $\ll k_1$ and k_{-1}
- when reaction velocity is constant, $[ES]$ is constant or the variation of $[ES]$ is $\ll [S]$

$$\begin{aligned}\frac{d[ES]}{dt} &= k_1[E][S] - k_{-1}[ES] - k_{cat}[ES] = k_1[S](E_t - [ES]) - k_{-1}[ES] - k_{cat}[ES] = \\ &= k_1[S]E_t - [ES](k_1[S] + k_{-1} + k_{cat})\end{aligned}$$

$$\frac{d[ES]}{dt} = 0 \Rightarrow k_1[S]E_t = [ES](k_1[S] + k_{-1} + k_{cat}) \quad \frac{E_t}{[ES]} = 1 + \frac{k_{-1} + k_{cat}}{k_1[S]}$$



STEADY-STATE

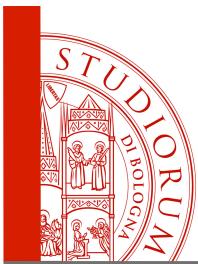
$$\frac{[E_t]}{[ES]} = 1 + \frac{k_{-1} + k_{cat}}{k_1[S]} \quad [ES] = \frac{[E_t]k_1[S]}{k_1[S] + k_{-1} + k_{cat}} = \frac{[E_t][S]}{[S] + \frac{k_{-1} + k_{cat}}{k_1}}$$

$$[ES] = \frac{[E_t][S]}{\frac{k_{-1} + k_{cat}}{k_1} + [S]} \quad v = \frac{k_{cat}[E_t][S]}{\frac{k_{-1} + k_{cat}}{k_1} + [S]} = \frac{k_{cat}[E_t][S]}{K_m + [S]}$$

$$K_m = \frac{k_{-1} + k_{cat}}{k_1}$$

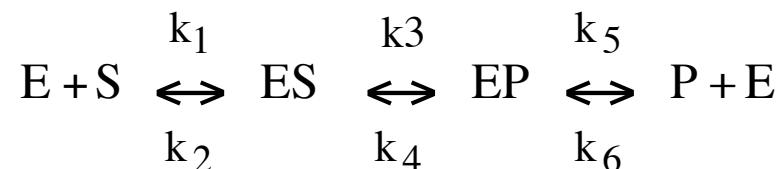
When $k_{cat} \ll k_1$ and $k_{-1} K_m = K_s$

Carbonic anhydrase features Briggs-Haldane kinetics



STEADY-STATE

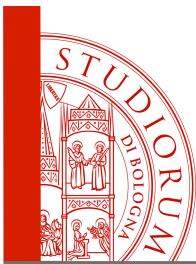
John Burdon Sanderson Haldane: Enzymes, Longmans Green & Co. London, 1930
Reversible Reactions: pp.80-83



$$\frac{d[\text{ES}]}{dt} = k_1[\text{S}]([\text{Et}] - [\text{ES}] - [\text{EP}]) + k_4[\text{EP}] - (k_2 + k_3)[\text{ES}]$$

$$\frac{d[\text{EP}]}{dt} = k_6[\text{P}]([\text{Et}] - [\text{ES}] - [\text{EP}]) + k_3[\text{ES}] - (k_4 + k_5)[\text{EP}]$$

Under steady-state conditions: both $d[\text{ES}]/dt$ and $d[\text{EP}]/dt = 0$



STEADY-STATE

Under steady-state conditions:

$$k_1[S](E_t - [ES] - [EP]) + k_4[EP] - (k_2 + k_3)[ES] = 0$$

$$k_6[P](E_t - [ES] - [EP]) + k_3[ES] - (k_4 + k_5)[EP] = 0$$

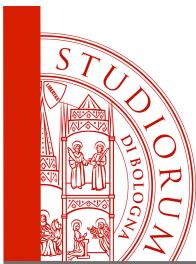
Let us consider [ES] and [EP]:

$$[ES] = \frac{k_1[S][E_t] + [EP](k_4 - k_1[S])}{k_1[S] + k_2 + k_3}$$

$$[EP] = \frac{k_6[P][E_t] + [ES](k_3 - k_6[P])}{k_6[P] + k_4 + k_5}$$

$$\frac{[ES]}{[E_t]} = \frac{k_1[S] + [EP]/[E_t](k_4 - k_1[S])}{k_1[S] + k_2 + k_3}$$

$$\frac{[EP]}{[E_t]} = \frac{k_6[P] + [ES]/[E_t](k_3 - k_6[P])}{k_6[P] + k_4 + k_5}$$



STEADY-STATE

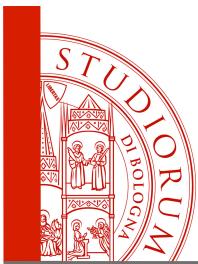
$$\frac{[ES]}{[E_t]} = \frac{k_1[S] + [EP]/[E_t](k_4 - k_1[S])}{k_1[S] + k_2 + k_3} \quad \frac{[EP]}{[E_t]} = \frac{k_6[P] + [ES]/[E_t](k_3 - k_6[P])}{k_6[P] + k_4 + k_5}$$

$$\frac{[ES]}{[E_t]} = \frac{k_1[S] + (k_4 - k_1[S]) \left(\frac{k_6[P] + [ES]/[E_t](k_3 - k_6[P])}{k_6[P] + k_4 + k_5} \right)}{k_1[S] + k_2 + k_3} =$$

$$\frac{k_1[S](k_4 + k_5 + k_6[P]) + k_4k_6[P] - k_1k_6[S][P] + [ES]/[E_t](k_4k_3 + k_1k_6[S][P] - k_4k_6[P] - k_1k_3[S])}{(k_4 + k_5 + k_6[P])(k_1[S] + k_2 + k_3)}$$

$$\frac{[ES]}{[E_t]} [(k_4 + k_5 + k_6[P])(k_1[S] + k_2 + k_3) - k_4k_3 - k_1k_6[S][P] + k_4k_6[P] + k_1k_3[S]] =$$

$$k_1k_4[S] + k_1k_5[S] + k_1k_6[S][P] + k_4k_6[P] - k_1k_6[S][P]$$



STEADY-STATE

$$\frac{[ES]}{[E_t]} [(k_4 + k_5 + k_6[P])(k_1[S] + k_2 + k_3) - k_4 k_3 - k_1 k_6[S][P] + k_4 k_6[P] + k_1 k_3[S]] =$$

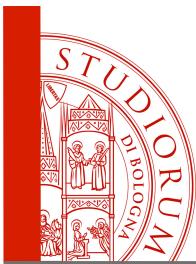
$$k_1 k_4 [S] + k_1 k_5 [S] + k_1 k_6 [S][P] + k_4 k_6 [P] - k_1 k_6 [S][P]$$

$$\frac{[ES]}{[E_t]} [k_1[S](k_3 + k_4 + k_5) + k_6[P](k_2 + k_3 + k_4) + k_2 k_5 + k_3 k_5 + k_2 k_4] = k_1[S](k_4 + k_5) + k_4 k_6[P]$$

$$\frac{[ES]}{[E_t]} = \frac{k_1[S](k_4 + k_5) + k_4 k_6[P]}{k_1[S](k_3 + k_4 + k_5) + k_6[P](k_2 + k_3 + k_4) + k_2 k_5 + k_3 k_5 + k_2 k_4}$$

And :

$$\frac{[EP]}{[E_t]} = \frac{k_6[P](k_2 + k_3) + k_1 k_3[S]}{k_1[S](k_3 + k_4 + k_5) + k_6[P](k_2 + k_3 + k_4) + k_2 k_5 + k_3 k_5 + k_2 k_4}$$



STEADY-STATE

$$\frac{[ES]}{[E_t]} = \frac{k_1[S](k_4 + k_5) + k_4 k_6 [P]}{k_1[S](k_3 + k_4 + k_5) + k_6 [P](k_2 + k_3 + k_4) + k_2 k_5 + k_3 k_5 + k_2 k_4}$$

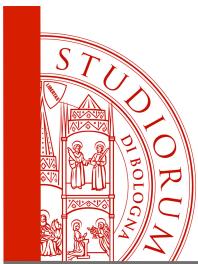
$$\frac{[EP]}{[E_t]} = \frac{k_6[P](k_2 + k_3) + k_1 k_3 [S]}{k_1[S](k_3 + k_4 + k_5) + k_6 [P](k_2 + k_3 + k_4) + k_2 k_5 + k_3 k_5 + k_2 k_4}$$

$$v = k_3[ES] - k_4[EP] = \frac{(k_1 k_3 k_5 [S] - k_2 k_4 k_6 [P]) [E_t]}{k_1[S](k_3 + k_4 + k_5) + k_6 [P](k_2 + k_3 + k_4) + k_2 k_5 + k_3 k_5 + k_2 k_4}$$

$$v = \frac{(k_1 k_3 k_5 [S] - k_2 k_4 k_6 [P]) [E_t]}{k_1[S](k_3 + k_4 + k_5) + k_6 [P](k_2 + k_3 + k_4) + k_2 k_5 + k_3 k_5 + k_2 k_4} = \frac{V K' [S] - V' K [P]}{K K' + K' [S] + K [P]}$$

With :

$$V = \frac{k_3 k_5 [E_t]}{k_3 + k_4 + k_5} \quad V' = \frac{k_2 k_4 [E_t]}{k_2 + k_3 + k_4} \quad K = \frac{k_2 k_4 + k_2 k_5 + k_3 k_5}{k_1(k_3 + k_4 + k_5)} \quad K' = \frac{k_2 k_4 + k_2 k_5 + k_3 k_5}{k_6(k_2 + k_3 + k_4)}$$



STEADY-STATE

$$v = \frac{VK'[S] - V'K[P]}{KK' + K'[S] + K[P]}$$

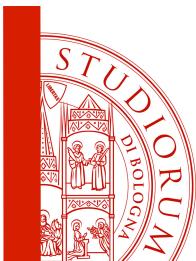
$$V = \frac{k_3 k_5 [E_t]}{k_3 + k_4 + k_5} \quad V' = \frac{k_2 k_4 [E_t]}{k_2 + k_3 + k_4} \quad K = \frac{k_2 k_4 + k_2 k_5 + k_3 k_5}{k_1(k_3 + k_4 + k_5)} \quad K' = \frac{k_2 k_4 + k_2 k_5 + k_3 k_5}{k_6(k_2 + k_3 + k_4)}$$

If $[P] = 0$:

$$v = \frac{VK'[S]}{KK' + K'[S]} = \frac{V[S]}{K + [S]} \quad \text{with } V = V_{\max} \quad \text{and } K = K_m$$

At equilibrium:

$$v = \frac{VK'[S] - V'K[P]}{KK' + K'[S] + K[P]} = 0 \quad VK'[S] = V'K[P] \quad \frac{[S]}{[P]} = \frac{V'K}{VK'} = \frac{k_2 k_4 k_6}{k_1 k_3 k_5} \quad \text{Haldane relationship}$$



STEADY-STATE

$$v = \frac{k_{cat}[E_t][S]}{K_m + [S]}$$

$$v = \frac{V_{max}[S]}{K_m + [S]}$$

Lineweaver and Burk:
double-reciprocal plot

$$\frac{1}{v} = \frac{K_m + [S]}{V_{max}[S]} = \frac{1}{V_{max}} \left(\frac{K_m}{[S]} + 1 \right) \quad \frac{1}{v} = y \quad \frac{1}{[S]} = x$$

$$y = \frac{1}{V_{max}} + \frac{K_m}{V_{max}} \cdot x \quad y = a + b \cdot x$$

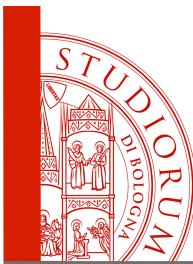
Linear plot, easier to handle!

Slope: K_m/V_{max}

Intercepts

x: $-1/K_m$

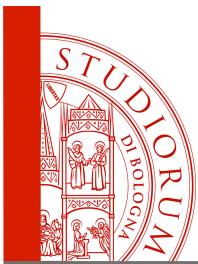
y: $1/V_{max}$



STEADY-STATE

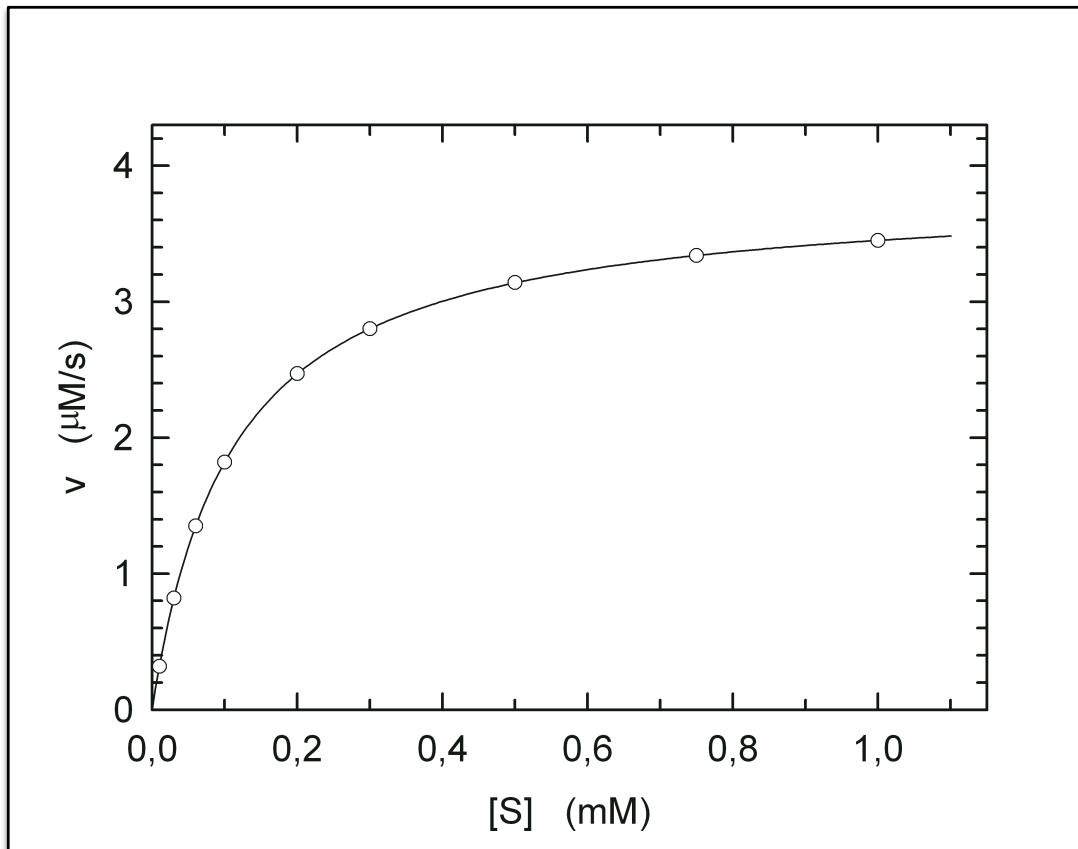
The reciprocal plot features crowded points

[S] (μM)	v ($\mu\text{M}/\text{s}$)	1/[S] (μM^{-1})	1/v ($\text{s}/\mu\text{M}$)	v/[S] (s^{-1})
25	0.708	0.0400	1.4124	0.0283
50	1.195	0.0200	0.8368	0.0239
75	1.551	0.0133	0.6447	0.0207
100	1.821	0.0100	0.5491	0.0182
200	2.468	0.0050	0.4052	0.0123
300	2.799	0.0033	0.3573	0.0093
500	3.135	0.0020	0.3190	0.0063
750	3.336	0.0013	0.2998	0.0044
1000	3.446	0.0010	0.2902	0.0034



STEADY-STATE

v vs. [S] plot

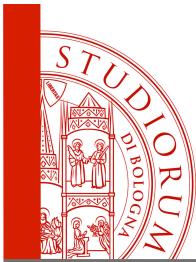


$$y = (a \cdot x) / (b + x)$$

$$a = V_{\max}$$

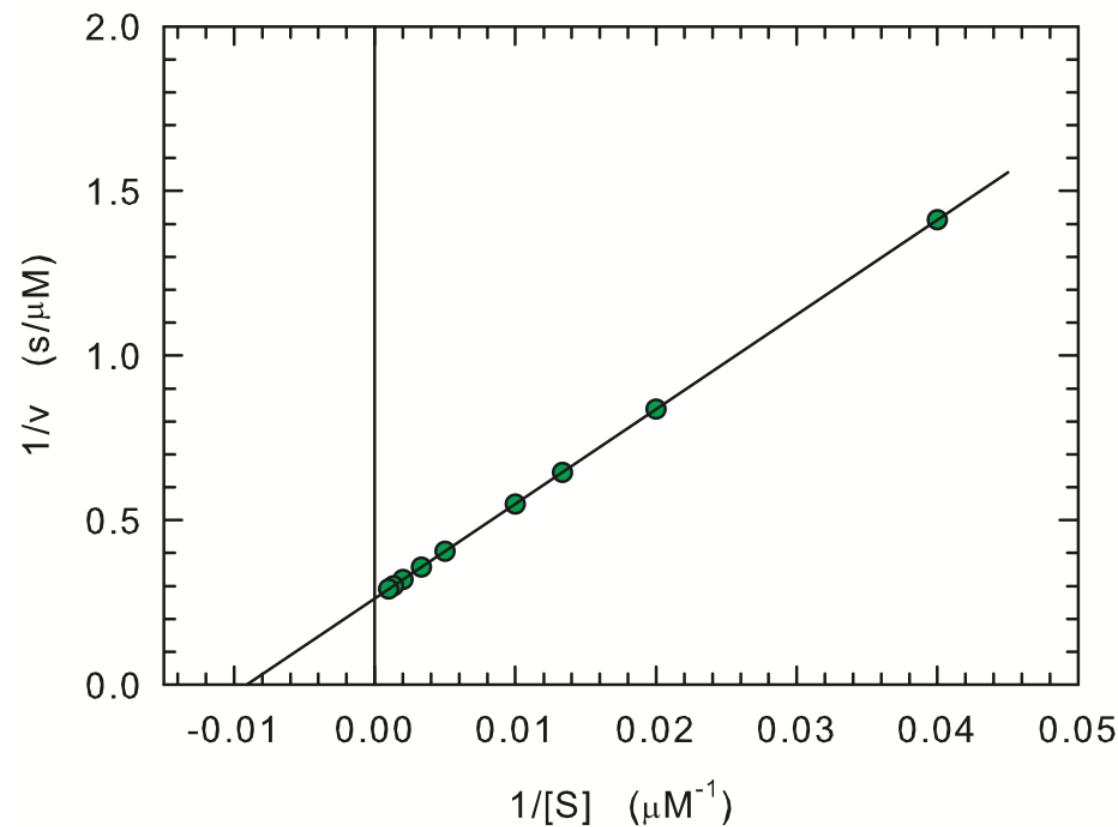
$$b = K_m$$

- Points well separated
- Fitting by computer



STEADY-STATE

Lineweaver-Burk plot

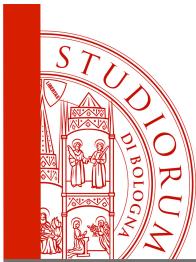


$$y = a + b \cdot x$$

$$a = 1/V_{\max}$$

$$b = -1/K_m$$

- Points at high [S] crowded
- Easy fitting



STEADY-STATE

$$v = \frac{k_{cat}[E_t][S]}{K_m + [S]}$$

$$v = \frac{V_{max}[S]}{K_m + [S]}$$

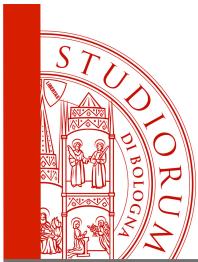
Eadie-Hofstee:

$$v(K_m + [S]) = V_{max}[S] \quad v = V_{max} - v \cdot K_m / [S]$$

$$y = v \quad x = v/[S] \quad y = V_{max} - K_m \cdot x$$

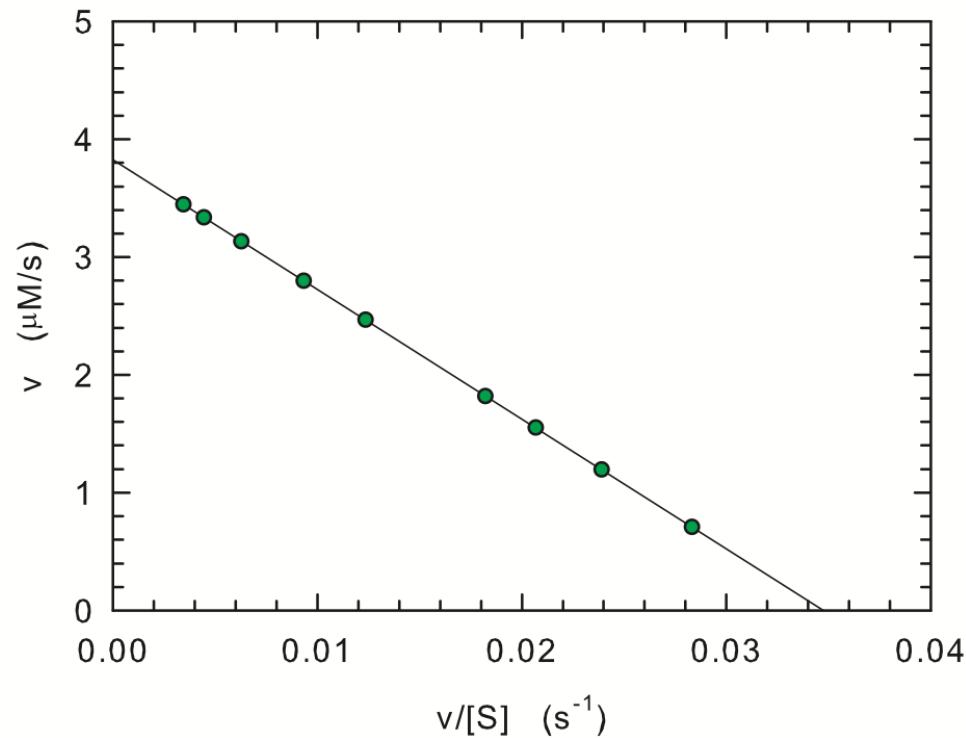
Slope: $-K_m$ Intercepts

$x: V_{max}/K_m$
 $y: V_{max}$



STEADY-STATE

Eadie-Hofstee plot

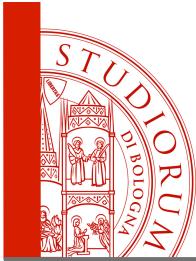


$$y = a - b \cdot x$$

$$a = V_{\max}$$

$$b = K_m \cdot x$$

- Points well separated
- Easy fitting



STEADY-STATE
