# **Current Challenges (and Solutions)** in Satellite Navigation

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#### Institute of Communication and Navigation



# Knowledge for Tomorrow

# **Satellite Navigation – Application Fields**

- Navigation: automotive, aircrafts, shipping, space
- **Geodesy:** surveying, mapping, geology, archaeology, civil engineering, topography
- Time keeping: mobile communication
- systems, internet traffic
- Search and Rescue (SAR)
- Fleet management
- Traffic control
- Geolocation based games
- Marketing
- Social Networks





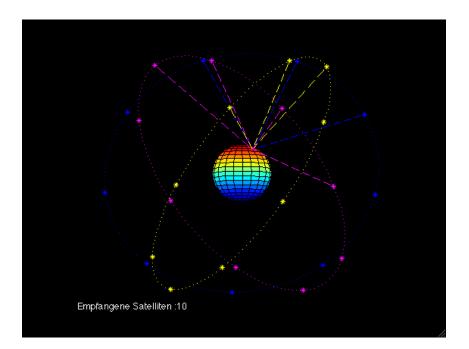
### **Satellite Navigation – General Principles**

#### Satellite broadcasts :

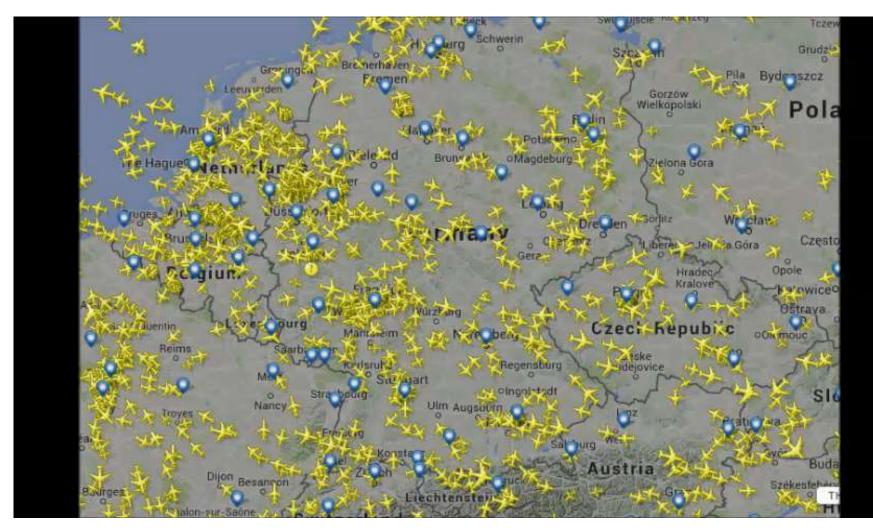
- · orbital data and ephemeris
- precise time stamp (atomic clocks)

#### Receiver measurements:

- compares transmission and reception time (flight time)
- distance between satellite and receiver.
- Receiver placed in a spherical shell:
  - trilateration
  - Position + time

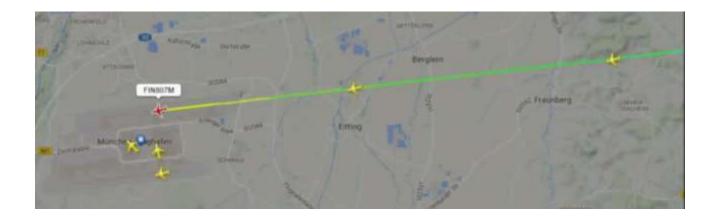


#### Safety of life applications (e.g. Civil aviation)



DLR

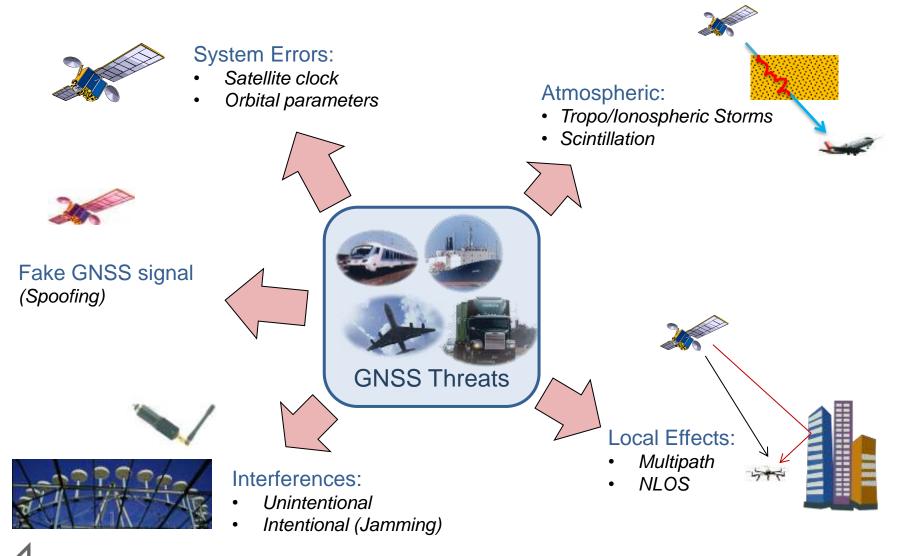
#### Safety of life applications



- Rely more on GNSS in the future (SESAR and NextGen)
- Allow for new type of approaches (e.g. curve)
- Increment of air traffic density  $\rightarrow$  Reduce distance between aircrafts
- Not only accuracy is therefore important → Integrity and availability

#### **GNSS Vulnerabilities**

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#### **System Error Monitoring**

Characterization of Satellite Orbit and Clock Errors

#### SIS Verification with High Gain Antenna



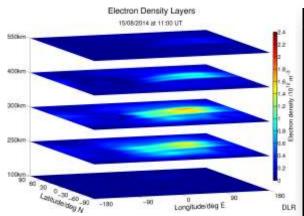
#### Experimentation and Verification Network (EV-NET)

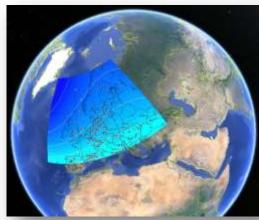


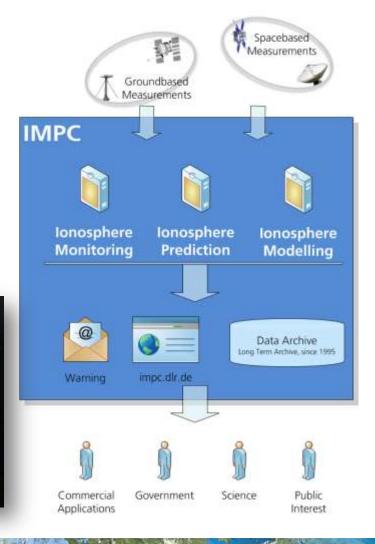
# **Ionosphere Monitoring Prediction Center (IMPC)**

# Detection, Analysis and alert of Ionospheric Events

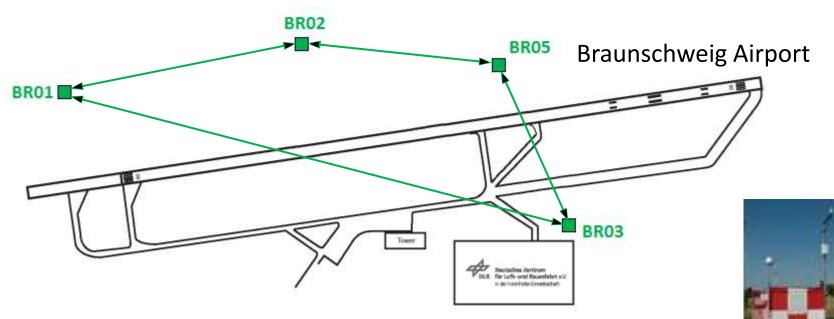
- Modeling of the lonosphere through the determination of the TEC (Total Electron Content)
- Detection of the amplitude and phase of scintillation for multifrequency GNSS measurements







#### **DLR GBAS Ground Facility**



	L1	L2	L5
BR01	>	>	<ul> <li>Image: A second s</li></ul>
BR02	>	>	<
BR03	>	>	<
BR05	>	~	$\checkmark$

Since 6<sup>th</sup> May 2014:

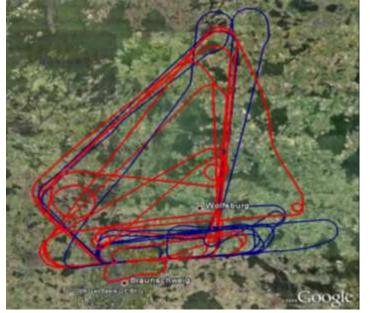
Javad Delta Receivers with GPS (L1 / L2 / L5) + Galileo (E1 / E5a) + Glonass Connected to Leica AR25 choke ring antennas





### **DLR Research Aircraft**

Evaluation of measurements and system performance through flight trials





D-CODE (Dornier 228) ATTAS (VFW 614) ATRA (Airbus 320)

#### **RF Interferences**

- GNSS signals are deeply buried in the noise and can be easily disturbed by interference from other signals
- Received power at Earth surface:
   ~ -160 dBW =
   0.000 000 000 000 000 1 Watt
- Can be disturbed by:
  - Accumulated noise (e.g. UWB)
  - High power pulses (DME, TACAN)

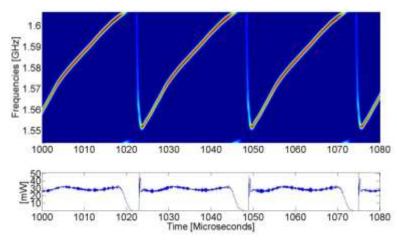


- High Power Continuous Wave (Harmonics from TV stations etc.)
- Personal Privacy Devices Jammers



# Interference by GPS Jammers (PPD) at Newark Airport

- Intentional jamming is reality!
- Personal Privacy Devices (jammers) disturb GPS and GBAS reference stations
- Operation illegal
- Price: \$ 30 \$ 200 in Internet
- Interference mitigation required

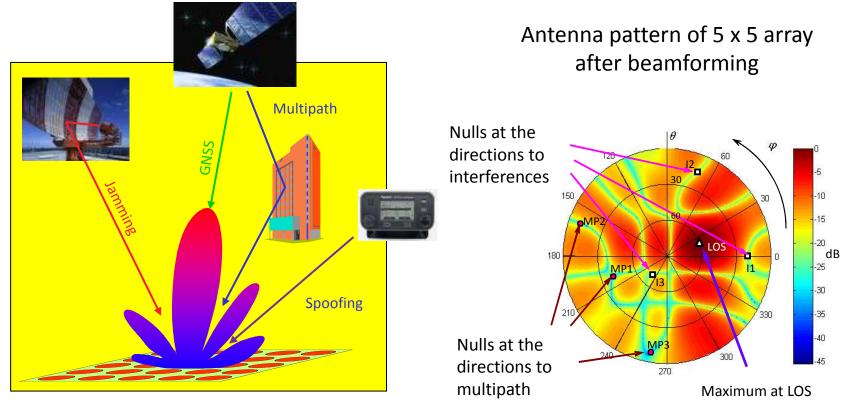


Source: R.H. Mitch et al., Signal Characteristics of Civil GPS Jammers, ION GNSS 2011



Airport Newark Liberty International, Motorway close to airport

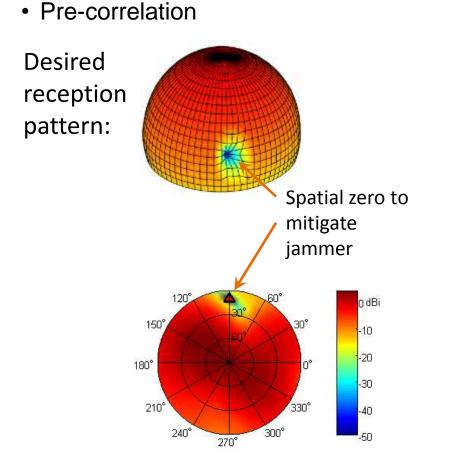
#### Adaptive Antennas Interference and multipath mitigation



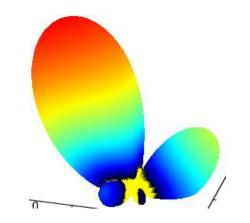
Antenna size approx. 95 x 95 cm<sup>2</sup>

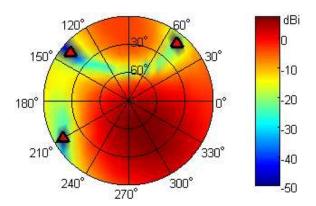


### Pre and post correlation techniques: Beamforming



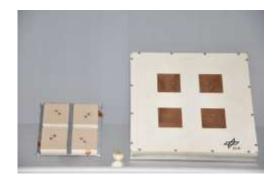
• Post-correlation



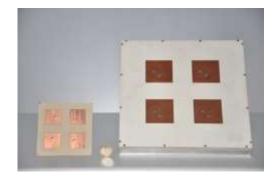




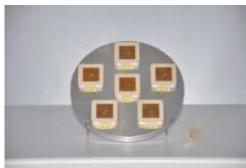
### Some DLR GNSS Antenna Arrays



Galileo E1/E6 standard and miniaturized



Galileo E1/E5 standard and miniaturized



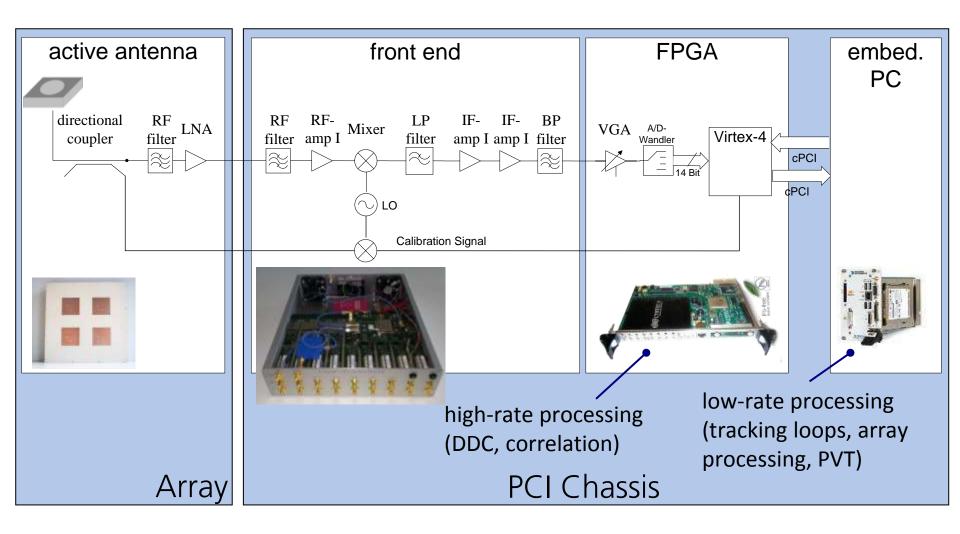
**GPS** miniaturized



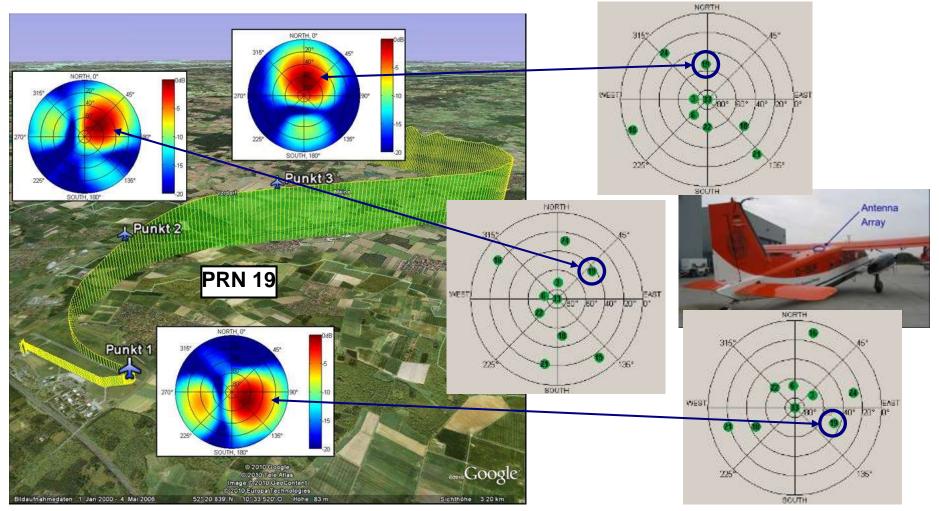
**GPS** conformal



#### **Practical Realization: Complete System**

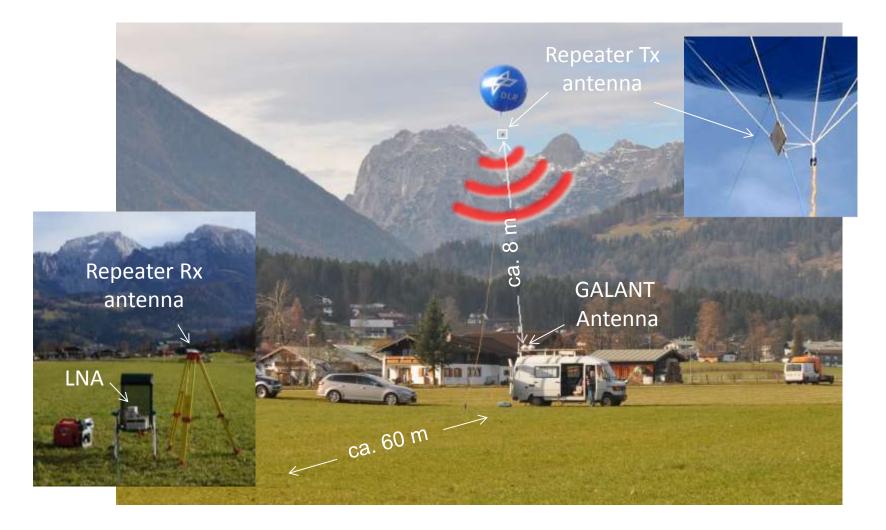


#### **Beamforming and DOA-estimation in Flight Tests**

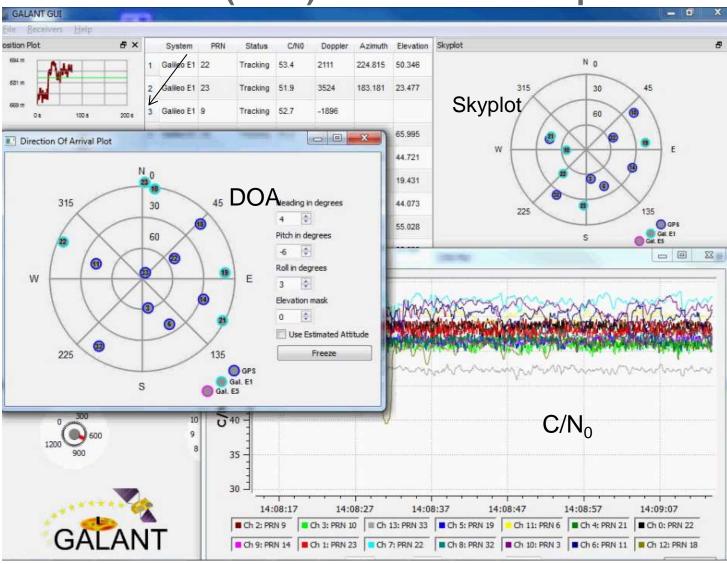


DLR

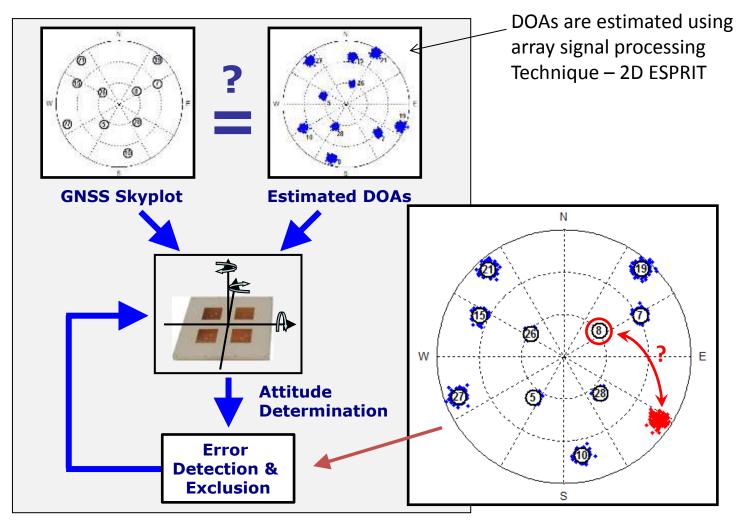
#### **Repeater Test Set-Up**



# **Direction of Arrival (DOA) Estimation in Repeater Scenario**



# **Concept of Joint Attitude Determination and Spoofing Detection Algorithm**

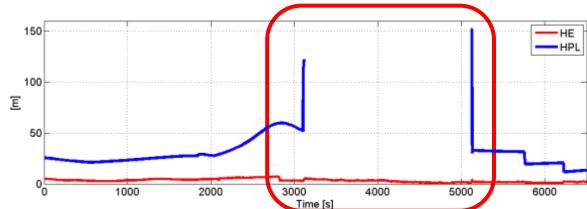


M. Appel, A. Konovaltsev, and M. Meurer, "Robust Spoofing Detection and Mitigation based on Direction of Arrival Estimation," in Proc. ION GNSS+ 2015, Tampa, FL, USA, 2015.

#### Loss of satellites due to maneuvers: Inertial Coasting

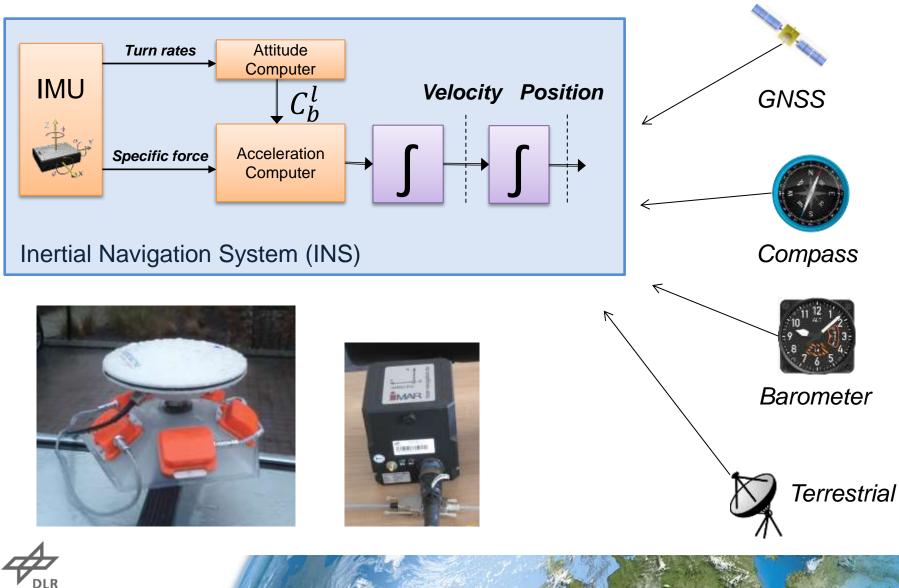


- Loss of satellites due to maneuvers
- Time gap due to restart of smoothing filters

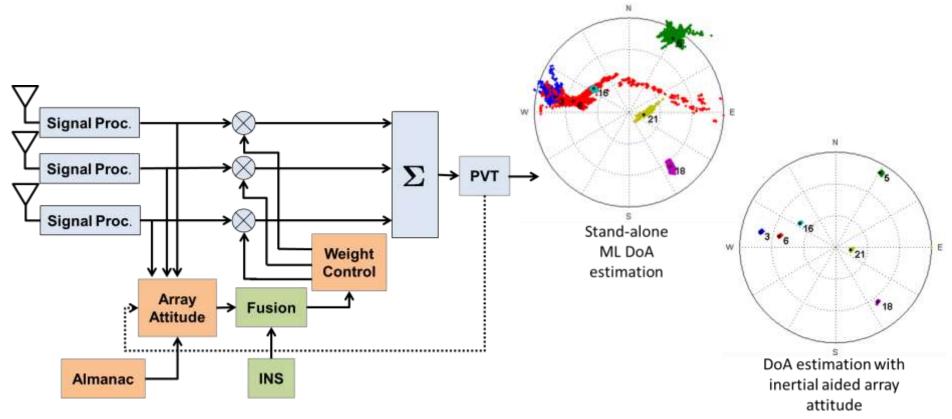


Continuity and availability requirements might not be fulfilled

# **Multisensor Fusion**



### Highlight: Inertial aided array antenna attitude



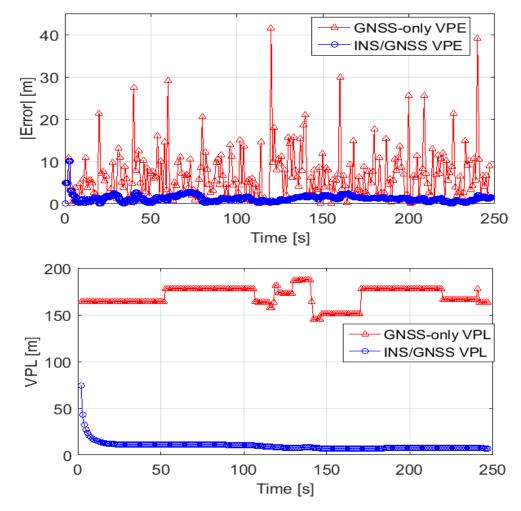
Improving the signal-to-noise ration (CN<sub>0</sub> improvements of 10 dB possible)

Reliable tracking the Line of Sight (LoS) satellite signal

### **Multisensor Fusion**

- Accuracy improvement
- Low sensitivity to faults/biases
- Local and global fault detectability improvement
- Availability improvement thanks to the reduction of Protection Levels



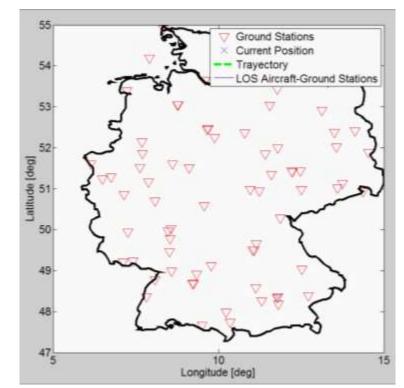




# **Alternative Position Navigation and Timing (APNT)**

GNSS denied area

It is meant to be a GNSS backup System



#### Signals under consideration:

- Distance Measurement Equipment (DME), eDME
- L-band Digital Aeronautical Communications System (LDACS)
- Universal Access Transceiver (UAT)
- Mode S transponder/1090 Mhz (ADS-B)



### **DLR Oberpfaffenhofen**

Employees: 1.590 Area: 245.000 m<sup>2</sup> Research institutes and facilities:

- Microwaves and Radar Institute
- Institute of Communications and Navigation
- Institute of Atmospheric Physics
- Remote Sensing Technology Institute
- Institute of Robotics and Mechatronics
- German Remote Sensing Data Centre
- Space Operations and Astronaut Training
- Galileo Control Centre
- Flight Experiments



# Institute of Communication and Navigation

#### **Employees**

- ~ 140 employees
- ~ 115 scientists/PhD candidates

#### **Facilities**

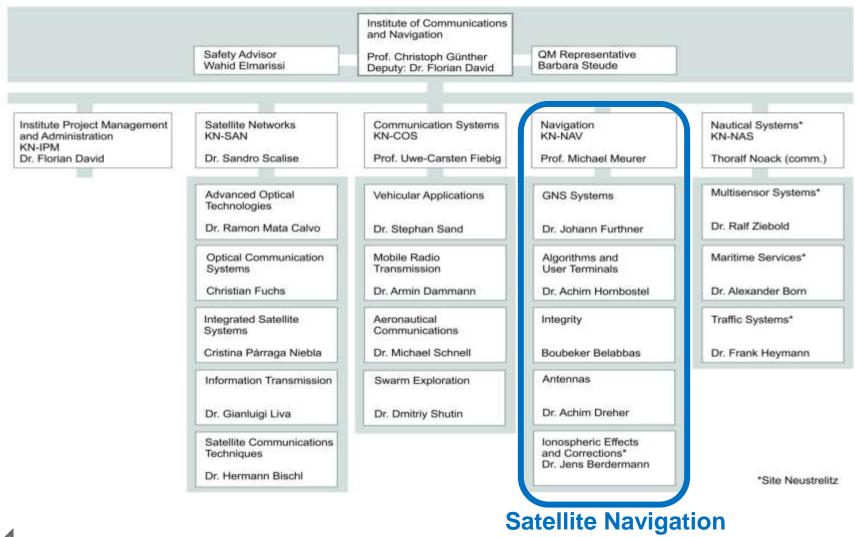
- Neustrelitz
- Oberpfaffenhofen





#### Organization Chart Institute of Communications and Navigation





OH8-KNI-Organigramm

Stand: 01.10.2014