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- Combined uncertainty estimation for the determination of the dissolved iron
- 6 amount content in seawater using flow injection with chemiluminescence
- 7 detection.
- 8
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#### 25 Abstract

26 This work assesses the components contributing to the combined uncertainty budget associated with the 27 measurement of the Fe amount content by flow injection chemiluminescence (FI-CL) in <0.2 µm filtered 28 and acidified seawater samples. Amounts of loaded standard solutions and samples were determined 29 gravimetrically by differential weighing. Up to 5% variations in the loaded masses were observed during 30 measurements, in contradiction to the usual assumptions made when operating under constant loading 31 time conditions. Hence signal intensities (V) were normalised to the loaded mass and plots of average 32 normalized intensities (in V kg<sup>-1</sup>) versus values of the Fe amount content (in nmol kg<sup>-1</sup>) added to a 'low 33 level' iron seawater matrix were used to produce the calibration graphs. The measurement procedure 34 implemented and the uncertainty estimation process developed were validated from the agreement 35 obtained with consensus values for three SAFe and GEOTRACES reference materials (D2, GS and GD). 36 Relative expanded uncertainties for peak height and peak area based results were estimated to be 37 around 12% and 10% (k=2) respectively. The most important contributory factors were the uncertainty 38 on the sensitivity coefficient (i.e. calibration slope) and within-sequence-stability (i.e. the signal stability 39 measured over several hours of operation; in this case 32 h). Therefore, an uncertainty estimation based 40 on the intensity repeatability alone, as is often done in FI-CL studies, is not a realistic estimation of the 41 overall uncertainty of the procedure.

42

#### 44 Introduction

45 The ocean acts as both a sink and a source for carbon dioxide and plays an important role in regulating the global climate system (Boyd and Elwood, 2010). The dynamics of the ocean and its interaction with 46 47 the atmosphere are strongly linked to the properties of seawater. Elements such as Fe limit marine 48 primary production in approximately one third of the world's oceans (Ussher et al., 2013) and thus may 49 have a profound effect on plankton communities and the global carbon cycle (Martin and Fitzwater, 1988; 50 Mills et al., 2004). More reliable determinations of micronutrient elements in marine waters are thus 51 essential to enhance our understanding of their impact on ocean productivity and processes (e.g. ocean 52 acidification). Therefore, robust and fully validated measurement procedures are necessary, accompanied 53 by an estimation of the overall uncertainty budget.

54 The international standard ISO/IEC 17025 (2005) states that the performance of a measurement 55 procedure should be evaluated based on one or a combination of the following approaches: a) the use of 56 reference materials, b) the comparison of results achieved with other methods, c) inter-laboratory 57 comparison, d) systematic assessments of the factors influencing the result and e) the assessment of the 58 uncertainty of the results. The Fe content of commercially available certified reference materials is at 59 least one order of magnitude higher than most open ocean waters and are thus of limited use for 60 method development. Therefore, test materials from inter-laboratory comparison exercises are often used 61 instead, e.g. those collected as part of the IRONAGES, SAFe and GEOTRACES studies. However, Bowie et 62 al. (2006) observed that discrepancies between results obtained in different laboratories during the 63 IRONAGES comparison remained too large (e.g. up to 59% variability when using the same procedure) 64 and differed significantly at the 95 % confidence level. Factors thought to explain these results included: 65 (1) variations in the efficiency of the extraction of iron from the matrix during pre-concentration 66 (resulting in different procedures measuring different fractions of iron), (2) errors in the quantification of the analytical blank, (3) inaccuracies in the system calibration and (4) underestimation of the stated 67 68 uncertainty (Bowie et al, 2003; Petrov et al. 2007). Hence iron data from these exercises for the same 69 water mass were distinctly inconsistent. Points (1) and (2) have been addressed by the SAFe (Johnson et 70 al., 2007) and GEOTRACES (GEOTRACES, 2013) exercises but not points (3) and (4). It is thus useful to 71 revisit these two factors and determine how realistic uncertainties can be estimated for the most 72 commonly applied measurement procedures (particularly shipboard procedures) (see also Ussher et al., 73 2010b). In this respect flow injection with chemiluminescence detection (FI-CL) was chosen for this study 74 as it is a technique that allows high temporal and spatial resolution measurements at sea without the 75 need for sample storage and transport. 76 According to the international nomenclature, the measurement uncertainty is a "non-negative parameter

characterizing the dispersion of the quantity values being attributed to a measurand, based on the

78 *information used*" (JCGM 200, 2008). The basic purpose of an uncertainty statement is to propose a Geerke L&O methods 2016 PEARL 17-Aug-16 3

79 range of possible 'true' values. There are various ways of estimating uncertainties. For instance, 80 combined uncertainty estimates can be based on data obtained by inter-laboratory or intra-laboratory 81 studies (see e.g. Analytical Methods Committee, 1995; Nordic Committee on Food Analysis, 1997). The 82 uncertainty estimation proposed in the Guide for Uncertainty in Measurements (GUM) is based on 83 combining the contributions of all known sources of uncertainty (JCGM 100, 2008). In this approach, the 84 measurement procedure is described by a mathematical model and the values and associated standard 85 uncertainties of the different components (the input quantities) in the model must be established. The model and input data are then used to calculate the measurement result including its associated 86 87 combined uncertainty.

88 The aim of this work was to study the application of the 'GUM approach' to the FI-CL measurement 89 procedure. The specific objectives were to; (1) propose a set of mathematical equations (a model) 90 describing this measurement process and allowing the estimation of a measurement uncertainty, (2) 91 discuss the best way to assess the uncertainties of the different components in the model, (3) apply this 92 uncertainty model to present the measurement results with their estimated combined uncertainties 93 obtained for seawater samples from the SAFe and GEOTRACES campaigns (Lohan et al., 2006; Johnson 94 et al., 2007) and, from the above, (4) propose a simplified equation to estimate the measurement 95 uncertainty.

96

#### 97 Materials and procedures

#### 98 *Reagents, materials and samples*

99 Concentrated hydrochloric acid (HCl), ammonia (NH<sub>3</sub> 20 - 22%) and glacial acetic acid (CH<sub>3</sub>CO<sub>2</sub>H), all 100 SpA grade, were purchased from Romil (Cambridge, UK). Hydrogen peroxide, Merck Suprapur grade was 101 obtained from VWR (Lutterworth UK), Luminol (5-amino-2,3-dihydro-1,4-phthalazinedione), sodium 102 carbonate and triethylenetetramine (TETA) were purchased from Sigma Aldrich (Gillingham, Dorset, UK). 103 All high purity water (HPW), 18.2 MΩ·cm, was drawn from an ElgaStat Maxima system (Marlow, UK). All 104 weighing was performed using an analytical balance (OH1602/C, Ohaus, Thetford, UK). The accuracy of 105 the balance was checked daily before use using F1 Class certified weights (KERN, Albstadt, Germany). All 106 facilities were managed under ISO 9001:2008 certification. 107

To ensure low blank Fe amount content all sample and reagent handling was undertaken in an ISO 14644-1 Class 5 laminar flow hood (Bassaire, Southampton, UK) situated within an ISO 14644-1 Class 5 clean room. Reagent and sample containers were made of low density polyethylene (LDPE; Nalgene, Fisher Scientific, UK) and were cleaned using established cleaning protocols for trace metals. Containers were immersed in ~ 1.1 M trace metal grade HCl (Fisher Scientific) for at least seven days. Subsequently, the containers were rinsed in copious amounts of HPW, filled with 0.01 M HCl and stored in double resealable plastic bags until use.

114 The main characteristics of the seawater samples used for this project are described in Table 1. Briefly, 115 all samples were filtered at sea and then acidified either at sea or at Plymouth University (PU). Seawater samples, referred to as SWA, SWB, and SWC, containing  $\leq 0.5$  nmol kg<sup>-1</sup> Fe were selected to prepare 116 117 three different sets of calibration standards, by addition of controlled amounts of iron from a CPI 118 International (Amsterdam, Netherlands) ICP-MS standard containing 0.17 mol kg<sup>-1</sup> Fe. Experiments in this work were carried out with 0.5 L reference samples from large volumes of homogenised, bulk seawater 119 120 samples (SAFe D2 and GEOTRACES GS and GD consensus mean reference materials). More details 121 regarding the sampling, pre-treatment and bottling procedures for these materials can be found 122 elsewhere (Jonhson et al., 2007; GEOTRACES 2013).

123

#### 124 The FI-CL based measurement procedure

125 Figure 1 describes the FI-CL manifold used for these experiments. It consists of three peristaltic pumps 126 (Minipuls 3, Gilson, Luton, UK), one PTFE manually operated three port valve (Valve 1; Omnifit), one 127 three port solenoid valve (Valve 2), one two-way six port electronically actuated valve (Valve 3; VICI, 128 Valco Instruments, Schenkon, Switzerland), a thermostatic water bath (Gran, Cambridge, UK) and a 129 photomultiplier tube (PMT; Hamamatsu H 6240-01, Hamamatsu Photonics, Welwyn Garden City, UK) 130 containing a coiled, transparent PVC flow cell (volume 40 µL). The peristaltic pump tubing used was two 131 stop accu-rated<sup>™</sup> PVC (Elkay, Basingstoke, UK) and all other manifold tubing was 0.8 mm i.d. PTFE. The 132 system used two poly(methyl methacrylate) columns (1 cm long, 1.5 mm i.d., volume 70 µL), loaded with 133 Toyopearl AF Chelate 650 resin (Tosoh Bioscience, Stuttgart, Germany) retained with HDPE frits (BioVion 134 F, 0.75 mm thick, 22-57 µm pore size), to clean up the buffer and column rinse solutions. The analytical 135 column, also loaded with Toyopearl AF Chelate 650 resin, was made of polyethylene with LDPE frits with 136 an internal volume of 200 µL (Global FIA, Fox Island, USA).

137 Peristaltic pump and valve control and data acquisition were performed using custom built hardware and software (Ruthern Instruments, Bodmin, UK) run under Labview v 7.1 (National Instruments, Newbury, 138 139 UK). The measurement procedure, based on Obata et al. (1993), was as follows. A working solution of 140 approximately 0.35 µmol kg<sup>-1</sup> Fe was prepared gravimetrically by serial dilution of the CPI International stock solution. This working solution was then used to gravimetrically prepare calibration standards and 141 142 achieve added levels ranging from 0.15 to 0.9 nmol kg<sup>-1</sup> Fe in 0.15 nmol kg<sup>-1</sup> increments. All calibration 143 standards were prepared at least 12 h before use to allow for complete equilibration of the added Fe with 144 that present in the calibration seawater. A 20 µL aliquot of a 10 mM H<sub>2</sub>O<sub>2</sub> solution was added to all 145 calibration standards at least 2 h before use, to ensure that all Fe present was as Fe(III) (Lohan et al., 146 2006). The following solutions were also prepared at least 12 h before use. A 48 mM stock solution of

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147 luminol was obtained by dissolving 0.177 g of luminol and 0.25 g of  $Na_2CO_3$  in 20 mL of HPW. This stock 148 was then diluted to give a 0.24 mM working solution. The post column reagents for the 149 chemiluminescence reaction was a mixture of 0.23 M HCl, 0.44 M NH<sub>3</sub>, 0.24 mM luminol / 0.46 mM TETA 150 and 0.31 M H<sub>2</sub>O<sub>2</sub>. The acidified reference samples and standards of seawater were buffered to pH 3.5 151 with 0.35 M CH<sub>3</sub>CO<sub>2</sub>H and 0.11 M NH<sub>3</sub>. To precondition and wash the column, 0.011 M HCl was used.

152 To operate the FI-CL instrument, the LabVIEW software was opened and the baseline signal from the 153 PMT monitored to check for stability. The pump controlling the eluent and post-column reagents was 154 then activated and the baseline chemiluminescence signal recorded after the signal had stabilised. Each 155 analytical session started with the measurement of a procedural blank (by application of the "closed 156 sample valve" method). For this, the sample flow was stopped, by closing one port on valve 1, so that 157 only the wash solution and ammonium acetate buffer passed over the column. The FI-CL system was 158 then operated by loading and injecting SWA for at least 30 min to monitor stability. Subsequently, 159 calibration seawater standards and samples were analysed. The FI-Cl manifold was fully automated and 160 one replicate measurement consisted of the following analytical cycle. The column was conditioned for 10 161 s with 0.011 M HCl. Then the sample and buffer were loaded simultaneously for 60 s. The column was 162 washed with 0.011 M HCl for 20 s. The Fe was then eluted with 0.23 M HCl for 120 s. The mass of loaded 163 sample or standard solution was gravimetrically determined for each replicate by differential weighing. 164 Between each sample the sample flow path was washed with HPW for 30 s followed by uptake of the 165 fresh sample for 180 s. After each analytical session all fluid paths were flushed with 0.01 M HCl for 10 166 min and then with HPW for 15 min and HPW was left in the lines.

167

#### 168 Data treatment

169 Data integration was also performed with the custom build software run in LabVIEW. The baseline, and 170 the start and end points of the peak were set manually for each transient signal. The main calculations in 171 this study were carried out on the basis of peak height data, as this is the commonly used practice for FI-172 CL measurements in the oceanographic community (and the wider FI community). Peak area 173 measurements were also made and some of the differences observed when using peak areas are 174 discussed below. Further data treatment, including calculations for the estimation of standard 175 uncertainties, was carried out in Excel<sup>®</sup>. The combined uncertainties were obtained by propagating 176 together individual uncertainty components according to the GUM (JCGM 100, 2008). In practice, a 177 dedicated software program was used (Metrodata GmbH, 2003). The reported combined uncertainties 178 are expanded uncertainties and reported as  $U = ku_c$  where  $u_c$  is the combined standard uncertainty and k 179 is a coverage factor equal to 2. If "the probability distribution characterized by y and  $u_{c}(y)$  is 180 approximately normal and the effective degrees of freedom of  $u_c(y)$  is of significant size" ("greater than 10"), "taking k=2 produces an interval having a level of confidence of approximately 95 %" (JCGM 100,
2008).

183

#### 184 Assessment

#### 185 *Definition of the measurand*

186 The GUM states that a measurement begins with an appropriate specification of the measurand, the 187 particular quantity intended to be measured (JCGM 100, 2008). Iron exists in different physico-chemical 188 forms in seawater. Traditionally, filtration is performed to differentiate between the different physical size 189 fractions (Ussher et al., 2004, 2010a, Wu et al., 2001). Additionally, iron occurs in two oxidation states; 190 Fe(II) and Fe(III). Generally, Fe(III) predominates in oxygenated waters, of which most (80–99%) is 191 strongly complexed by organic ligands (Achterberg et al., 2001; Mawji et all, 2008; Gledhill and Buck, 192 2012). In this study the measurand is the amount content of Fe present in  $<0.2 \ \mu m$  filtered and acidified 193 samples and is regarded as the dissolved fraction of the Fe present in the seawaters. The aim was to 194 obtain the Fe amount content in specific samples and therefore the uncertainties associated with the 195 sampling process and/or the sample conditioning phase have not been considered.

196

#### 197 Experimental design

198 Three different types of experiment were performed. Firstly, the stability of the analytical procedure was 199 checked with 5 measurements (6 replicates of each) performed over a period of 32 h for SWC (with and 200 without  $H_2O_2$  addition) and a procedural blank (this was termed the "stability experiment"). Secondly, the 201 effect of small variations in the matrix was investigated by comparing the sensitivity achieved for the 202 three different seawaters (Table 1). On the first day, SWA was compared with SWB while on the second 203 day SWA was compared with SWC ("matrix experiment"). Thirdly, the FI-CL based procedure was applied 204 to the determination of iron in samples of three filtered and acidified seawater reference materials using 205 SWA for calibration ("sample experiment").

206

# Calculating the dissolved Fe amount content in the samples and mathematical description of the measurement procedure

209 Implicit in the GUM "is the assumption that a measurement can be modelled mathematically to the 210 degree imposed by the required accuracy of the measurement" (JCGM 100, 2008). A measurand Y is 211 determined from various input quantities  $X_i$  through a functional relationship. These input quantities "may 212 themselves be viewed as measurands and may themselves depend on other quantities, including 213 corrections and correction factors" "that can contribute a significant component of uncertainty to the 214 result of the measurement" (JCGM 100, 2008). A mathematical description of the FI-CL measurement 215 procedure is given through equations 1 to 5 described in Table 2. The main equation in this procedure is Geerke L&O methods 2016 PEARL 17-Aug-16 7

the calculation of the dissolved Fe amount content in a sample by dividing the blank corrected sample intensity by the sensitivity of the system (Equation 1 in Table 2). The way the equations controlling these

- 218 three input parameters were established is discussed below.
- 219

#### 220 Mass normalisation of the measurement signal

221 In most flow analysis methods incorporating a pre-concentration column, the amount of sample loaded is 222 assumed to remain the same for constant loading times and the resulting peak height signals (expressed 223 in V) are used for the calculations. Variations in the loaded mass are thus not corrected for. However, this 224 was found to be an issue as variations in sample mass were observed to be significant during the 225 "stability experiment", with about 5% decrease in the sample loaded from the first to the last 226 measurement (data not shown). During the "sample experiment" the average loaded mass for samples 227 was lower than for the standards, probably due to the fact that the samples were all run at the end of 228 the sequence and were therefore more likely to be affected by wear on the pump tubing, increased back 229 pressure on the analytical column and / or changes in the relative flow rates of the sample and buffer 230 lines (Figure 2). These results show the importance of weighing the amount of seawater loaded each 231 time and of normalising the peak signal (symbol I, in V) to the loaded mass (in kg). In addition, 232 gravimetric measurement, coupled with calibration of the analytical balance, provides tighter traceability 233 to SI (the kg) of the amounts of loaded samples than loading by volumetric means.

As a result of this finding, mass normalised signals (symbol J, in V kg<sup>-1</sup>) were used throughout this study for the calculations (Equation 2b, Table 2). Following the example given in Quétel et al. (2001), in equations 2a, 3a and 4a unity multiplicative factors were introduced to carry standard uncertainties associated with signal stability, data integration and matrix effects. Since these unity factors do not influence the final results, but enable the propagation of sources of uncertainty, they are discussed in more detail below.

240

#### 241 Blank corrections

Assessment of overall blank levels that reflect the reality of sample contamination during the 242 243 measurement procedure is necessary. In the international inter-laboratory comparison exercise 244 IRONAGES, blanks were reported to range between 6 and 290% of the Fe content in the seawater 245 sample (Petrov et al., 2007). Moreover, participants had diverse ways of defining and assessing their 246 blanks (Bowie et al., 2006) and were, therefore, possibly overlooking different aspects of the 247 contamination process. Sources of contamination during FI-CL measurements include the Fe present in 248 reagents (i.e. the added  $H_2O_2$  the buffer and wash solutions and the chemiluminescence reagents) and 249 Fe leaching from laboratory ware and parts of the experimental set-up. Sample manipulations could also 250 be a major contributor to the analytical blank as was shown to be the case by Petrov et al. (2007) during

251 isotope dilution inductively coupled plasma mass spectrometry measurements using co-precipitation with 252 magnesium hydroxide for sample preparation. The Fe from the reagents of the chemiluminescence 253 reaction is normally included in the baseline. Baseline subtraction for the determination of net peak 254 height or peak area signals should therefore remove this possible bias. The influence of additions of 255 chemical reagents for the purpose of preserving and/or conditioning the samples (e.g. acid,  $H_2O_2$ ) can be 256 assessed using double spiking of the reagents. Previous studies using FI-CL have shown their contribution 257 to be low / negligible if care is taken to select high purity reagents (Bowie et al., 2003: Bowie et al., 258 2004; Klunder et al. 2010).

- 259 Descriptions of what a blank may represent are available from the International Union of Pure and 260 Applied Chemistry (IUPAC). A "procedural blank" is "where the analytical procedure is executed in all 261 respects apart from the addition of the test portion" (McNaught and Wilkinson, 1997; Inczedy et al., 262 1998). Alternative measurement procedures for blank determination, such as the field blank approach or 263 varying sample loading times and extrapolating back to time zero (Bowie et al. 2004), were not suitable 264 as the former requires a matrix containing no analyte and the latter only accounts for reagents that are 265 loaded for a constant time e.g. the wash solution, but not those for which the amount loaded is variable 266 e.g. the pH adjustment solution.
- 267 In FI-CL, the signal obtained with the "closed sample valve" method as described above, i.e. loading only 268 buffer (Bowie et al., 2004; Ussher et al., 2010a), can be considered as a procedural blank. This method 269 was applied as no better alternatives could be found for estimating the level of contamination. The risk 270 that matrix effects and pH changes could influence final results due to fluctuations in the blank values 271 determined in this way is discussed below. Normalised signal intensities were calculated by division by 272 the average loaded sample mass (equation 3b). These blank values were 50-100 times lower than the 273 signals for the seawater samples. Unity multiplicative correction factors were used to propagate 274 uncertainties on stability and matrix effects (equation 3a) and are discussed in more detail below.
- 275

#### 276 <u>Calculation of the calibration slope</u>

277 The FI-CL method has a different sensitivity for seawater than for ultra-pure water because of matrix 278 related effects (Bucciarelli et al., 2001). Thus, a common approach for the calibration under matrix-279 matching conditions is to use a low level Fe seawater and fortify it with increasing amounts of Fe 280 (Bucciarelli et al., 2001; Bowie et al., 2004; Ussher et al., 2010a; Klunder et al., 2011). In this work, in 281 addition to the low level seawater alone (termed the 'zero' standard), six calibration standards were prepared with Fe amount content ranging from 0.15 to 0.9 nmol kg<sup>-1</sup>. Since measurements were 282 283 repeated 6 times for each calibration point, a total of 7 x 6 = 42 results were obtained. A linear 284 regression was plotted, with the masses of Fe loaded (in kg, obtained by multiplication of the standard Fe 285 mass fraction by the loaded mass of the replicate) on the x axis and the corresponding measured signal

286 intensities (in V) on the y axis. The 'behaviour' of the data was nearly the same irrespective of the scale 287 of observation, with replicate results spread randomly around the regression graph in more or less the 288 same way for all 6 standards prepared and tested. Common practice is to produce 3-4 replicates per Fe 289 level and work with average values. Thus, a more practical way of establishing the calibration curve 290 consists of plotting a linear regression between the group of 6+1 Fe amount content (C, in nmol kg<sup>-1</sup>) on 291 the x axis and the corresponding average normalized intensities (J, in V kg<sup>-1</sup>) on the y axis. The sensitivity coefficient (F, in V nmol<sup>-1</sup>), i.e. the slope, is obtained using equation 4b from Table 2 (see Figure 3). 292 293 Weighted regression can also be performed but the calculations are more complex. In a weighted 294 regression the higher the uncertainty on a y value the smaller the contribution of the y value to the 295 regression slope. This is especially important if the increase of values on the x axis can be related to an 296 increase of the standard uncertainty on corresponding values on the y axis. There was no difference with 297 this dataset at the 95% confidence level between weighted and unweighted regressions. This is probably 298 because the increase in the standard uncertainty with increased normalised intensity is limited. The 299 comparison between these two approaches is further discussed in the next section.

300

#### 301 Assessing the standard uncertainties

302 Individual uncertainty components and the factors influencing their standard uncertainties were 303 evaluated. This is necessary to enable a combined uncertainty estimation of the Fe amount content 304 results.

305

## 306 <u>Uncertainty on mass normalised measurement signals</u>

307 During the "sample experiment", the repeatability (short term signal stability) of mass-normalised 308 intensities (peak height based signals) for one measurement varied between 1.9 and 4.0% RSD (relative 309 standard deviation, n=6) while for the "stability experiment" repeatabilities varied between 2.4 and 4.9 310 %. These variations in RSD cannot be explained by variations in the specific characteristics of the sample 311 replicates since the same solution was measured throughout the "stability experiment". Moreover, as 312 illustrated in Figure 4, there was also a longer term variability component involved (within-sequence-313 stability), and thus two sources of instability influencing the intensity values. Over the 32 h long analytical 314 sequence there was no clear trend, and as a result correction for drift was not possible. Therefore, the 315 approach proposed is to estimate typical values for both components from the outcome of an ANOVA 316 analysis and multiply the sample average mass normalised intensities by unity correction factors carrying 317 the uncertainty for these two components ( $\delta_{rep S}$  and  $\delta_{stab S}$ ). Repeated intensity values per sample and 318 average intensity values from replicate samples were approximately normally distributed. The intensity 319 repeatability and the within-sequence-stability, determined using data from the "stability experiment", 320 were 4.1% and 6.3% respectively. Assuming independence between the intensity values used to

calculate both types of standard deviation, uncertainty estimations were carried out using these standard
 deviations divided by square root 6, i.e. the number of replicates and square root 5, i.e. the number of
 repeat measurements analysed in each case, to give values of 1.7% and 2.8% respectively.

Sample loading and standard preparation cannot be performed gravimetrically on board ship and therefore this is done volumetrically, which may cause additional sources of uncertainty. In this case, the set of equations described in Table 2 will change slightly and result in equation 6 as described below:

327 
$$C_{s} = \frac{\overline{I}_{R\_S} \cdot \delta_{rep\_S} \cdot \delta_{stab\_S} \cdot \delta_{WtoV\_S} - \overline{I}_{R\_B} \cdot \delta_{stab\_B} \cdot \delta_{rep\_B} \cdot \delta_{matrix\_B}}{F_{reg} \cdot \delta_{matrix\_std}}$$
 equation 6

328 As a consequence of not using mass normalization, the sensitivity factor is determined by regression of the intensity (expressed in V) with the concentration (nmol  $L^{-1}$ ) and has the units V/nmol  $L^{-1}$ . Secondly, 329 330 an extra unity multiplicative correction factor ( $\delta_{WtoV,S}$ ) was introduced to take account of the difference in 331 the mass loading between samples and standards (Figure 2). Using this data set and assuming constant 332 loading (i.e. without mass normalisation) its contribution to the final uncertainty budget was a few 333 percent. Lastly, although the same approach can be used to quantify the uncertainty on the unity 334 multiplicative factors of the intensity repeatability and within-sequence-stability, the values will be higher 335 than in the case of mass normalization. It must be noted that the within-sequence-stability during on-336 board measurements might be different than in controlled laboratory conditions, but a specific 337 assessment was not possible within the time frame of this study.

#### 338 Uncertainty on blank corrections

339 The evaluation of the uncertainty on blank measurement signals was approached in a similar way as for 340 the sample measurement signals. ANOVA analysis of the "stability experiment" results indicated 6.9% 341 and 10% respectively for the intensity repeatability (n=5) and the within-sequence-stability. A unity 342 multiplicative factor  $\delta_{matrix B}$  with a value of 1±0.2 was conservatively applied in equation 3a to account for the matrix differences between the blank samples and the standards used for calibration purposes. 343 344 However, since the signal intensity for the analytical blank was about 50-100 lower than the intensity for 345 the seawater samples in this project, this source of uncertainty on the blank correction had no influence 346 on the combined uncertainties estimated for the Fe amount content in the samples investigated.

347

#### 348 <u>Uncertainty on the calibration slope</u>

As discussed above, there are different statistical approaches that can be used to calculate the slope of the regression line (Miller, 1991: Press et al., 2012). Values obtained using different regression approaches are not significantly different at the 95% confident interval, but associated standard

352 uncertainties do vary (Table 3). The standard uncertainty on the slope when using average normalised 353 intensity values is the same whether the regression is weighted or unweighted. It is lower when using all 354 individual data in the unweighted regression because there are more data points that follow a normal 355 distribution. The importance of the number of standards and replicates on the size of the estimated 356 standard uncertainty of the slope was studied. In Table 4 it can be seen that the number of standards 357 used is a more important criterion than the number of replicates, but nevertheless the uncertainty on the 358 sensitivity factor also improves using 6 rather than 3 replicates. Small matrix differences between the 359 three seawaters tested in the "matrix experiment" did not lead to significant differences between the 360 slopes obtained for SWA, SWB and SWC. Therefore, no uncertainty factor for differences in the calibrant 361 matrix was applied.

362

#### 363 Discussion

#### 364 *Application to seawater samples from the SAFe and GEOTRACES campaigns*

365 Since consensus values are available for the Fe amount content in samples from the SAFe and 366 GEOTRACES campaigns (GEOTRACES, 2013), these data were compared with results obtained by 367 application of the model for combined uncertainty estimation and the calculations described above. 368 Samples D2, GS and GD were analyzed using 6 replicates each time, the "closed sample valve" approach 369 for blank assessment and a least square regression calibration line with 7 levels (no Fe added + 6 levels 370 of added Fe) in SWA. This was the "sample experiment", and results obtained are reported in Table 5. 371 Estimated expanded (coverage factor k=2) relative combined uncertainties were around 12% on a peak 372 height basis, and around 10% on a peak area basis. Using this dataset, the combined uncertainty was 373 slightly higher using volumetric loading compared with gravimetric loading. For example, for sample GD 374 the combined expanded uncertainty increased from 12 to 13% for peak height integration. It can be seen 375 that both peak height and peak area based results are systematically lower than the consensus values. 376 Results obtained for GS and GD (peak height and peak area basis) and peak area results for D2 were in 377 agreement with consensus values within uncertainty statements. These conclusions were reached from 378 the observation that the expanded combined uncertainty (k=2) on the difference between a measured 379 and the corresponding consensus value was greater than the difference itself in all cases (calculations 380 according to a methodology reported in Linsinger, 2010). For the peak height results for the D2 sample, 381 the expanded uncertainty on the difference was smaller than the difference itself but only by less than 382 3%. These results validate the measurement procedure implemented and the uncertainty estimation 383 process developed. They nevertheless point to the presence of a systematic effect not yet (sufficiently) 384 corrected for.

386 An overview of the values of the input parameters and their associated standard uncertainties for these 387 experiments is given in supplementary Table S1. The relative contributions of the different input 388 parameters to the uncertainty budget are given for sample GD in Table 6 as an example. The normalised 389 signal intensity repeatability accounts for only 7.9% of the total uncertainty. The within-sequence-stability 390 (assessed over 32 h) and the uncertainty on the sensitivity coefficient (calibration slope) are the most 391 important contributors to the combined uncertainty with relative contributions of 21.6 and 69.7%. 392 Therefore, it is beneficial to have a low uncertainty on the calibration slope. For this reason, it is 393 favourable to use sufficient replicates (6) and number of standards (at least the non-spiked standards 394 and 5 spiked levels). Moreover, correctly estimating the within-sequence-stability is key and should be 395 done under the same measurement conditions as for the samples.

396

Results obtained indicate that an uncertainty estimation based on the signal repeatability alone, as is often done in FI-CL studies, is not a realistic estimation of the overall uncertainty of the procedure. However, taking into account only the major contributions, the combined expanded uncertainty could be approximated using equation 7:

401

402 
$$U_{C_{s}} \approx 2 \cdot C_{s} \sqrt{\frac{\overline{J}_{s}^{2} \cdot \left[\left(\frac{u_{\delta_{rep_{s}}}}{\overline{\delta_{rep_{s}}}}\right)^{2} + \left(\frac{u_{\delta_{stab_{s}}}}{\overline{\delta_{stab_{s}}}}\right)^{2}\right]}{\left(\overline{J}_{s} - \overline{J}_{B}\right)^{2}} + \left(\frac{u_{F}}{\overline{F}}\right)^{2}}$$
equation 7

403

404 In this, the standard uncertainty on the intensity repeatability and within-sequence-stability can be 405 assessed using ANOVA analyses of repeat measurements of the same solution. The uncertainty on the 406 calibration slope can be obtained using statistical tools. This simplified approach assumes that the blank 407 does not significantly contribute to the uncertainty and should therefore have a much lower intensity 408 compared with the sample (as was the case in this study). When using data from this project the 409 uncertainty obtained with equation 7 was nearly identical to the uncertainty calculated above (for 410 example the difference was less than 0.2% for GD using peak height data). Therefore, if the assumptions 411 are valid this simplified approach provides a realistic uncertainty estimate.

412

#### 413 Peak area versus peak height

The bias between results and consensus values was around -12% for D2 and GS and -20% for GD, on a peak height basis, and around -8% for D2 and GS and -16% for GD, on a peak area basis. This also means that peak height results were systematically lower than the peak area results by approximately 4-

417 5%. The cause for this trend is not well understood. It is unlikely to be related to an error in the 418 placement of the baseline for integration, as this affects height less than area (Dyson et al., 1998). In 419 contrast, the asymmetry of the FI-CL peaks could be a possible source of error during peak height 420 measurement, since peak area is less sensitive to peak asymmetry than peak height (Dyson et al., 1998). 421 It can also be observed in Table 5 that estimated combined uncertainties are larger for peak height than 422 for peak area based results. This is mainly related to a larger uncertainty associated with the sensitivity 423 coefficient for peak height compared with peak area (Table S1). The intensity repeatability and the 424 within-sequence-stability are also slightly better for peak area than for peak height data, which can be 425 related to count statistics. Area integration is considered the 'true' measure of the amount of solute 426 (Dyson et al., 1998) and possible problems specific to peak area data such as peak overlap and / or low 427 S/N ratios (Dyson et al., 1998) are not an issue with FI-CL measurements. These observations lead to the 428 conclusion that peak area data may be preferable to peak height data with FI-CL measurement results, 429 contrary to common practice. Additionally, users should routinely and systematically describe the way 430 peak data are processed.

431

#### 432 **Comments and recommendations**

The amount content of dissolved Fe in marine waters is measured to elucidate the biogeochemical cycling of this element and its role in the oceanic sequestration of atmospheric  $CO_2$ . However, quantifying the amount of Fe present in <0.2 µm filtered and acidified seawater samples remains a difficult analytical task, and achieving reliable results is a challenging objective. Moreover, the uncertainty as part of the measurement results is easily underestimated.

438 FI-CL is a technique commonly applied because of its portability and hence suitability for shipboard 439 deployment. This paper proposes that the relative expanded (k=2) combined uncertainty of the 440 measurement results using FI-CL in the described configuration cannot be better than about 10 to 15% for seawater samples containing 0.5 to 1 nmol kg<sup>-1</sup> of dissolved Fe. When applied on-board ship the 441 442 minimum achievable uncertainty is likely to be even larger owing to the more challenging working 443 conditions compared with shore-based laboratories. Moreover, this paper emphasises the fact that it will 444 be beneficial to researchers to refine measurement practices in order to improve the likelihood of 445 achieving lower uncertainty targets. For FI-CL, the uncertainty associated with the calibration slope and 446 the within-sequence-stability are shown to be much greater sources of uncertainty than the intensity 447 repeatability alone. Experimental planning must therefore systematically address the identification of 448 strategies aimed at quantifying and minimising the role of these uncertainty contributors. These 449 strategies include the use of as many calibration standards as possible (ideally 5 plus the 'zero' standard 450 measured with 6 replicates) and measurements repeated regularly for the same sample over the entire 451 analytical sequence. It is also shown that more attention needs to be paid to the way FI-CL peak data are Geerke L&O methods 2016 PEARL 17-Aug-16 14

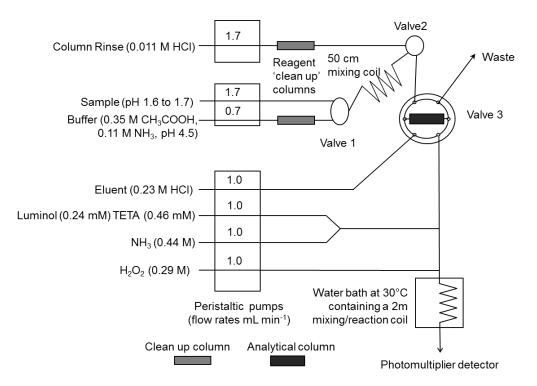
452 collected and processed, as this could lead to significant errors with respect to the size of the combined 453 uncertainties. To enhance the transparency of these aspects it is recommended that more comprehensive 454 descriptions of the methods used to validate the measurement procedures (including the way peak data 455 collection/processing is performed) are included in publications and reports. Moreover, a simple equation 456 to approximately estimate the uncertainty has been proposed, which is valid if the blank levels are 457 significantly lower than the levels of interest.

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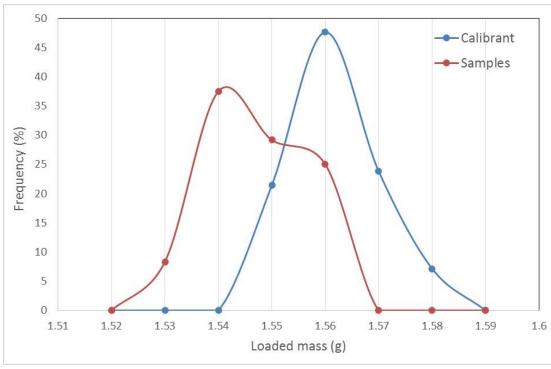
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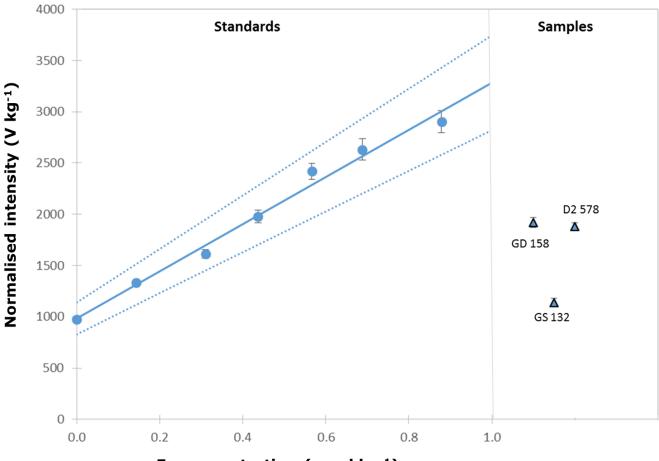
555 Figure 1: The FI-CL system used for the determination of dissolved Fe levels in seawater.

556



557

558 Figure 2: Frequency of variation (in %) of loaded masses for samples and calibration standards during the "sample experiment"



Fe concentration (nmol kg<sup>-1</sup>)

Figure 3: Unweighted calibration using average data for the regression. Blue dotted lines delimit a 95%
 confidence interval around the regression graph. Signal intensities observed for samples GD158, GS132 and

**D2578 are also reported.** 

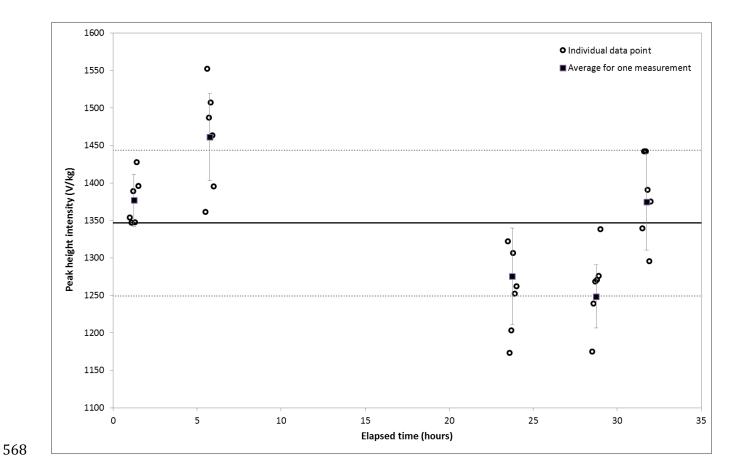


Figure 4: Stability over the 32 h "stability experiment" with seawater C using peak height based results. Vertical bars indicate the standard deviation of the average of the 6 replicates. Horizontal lines indicate the average and standard deviations for the groups of 5 repeat measurements.

## 570 Table 1: Description of the samples used.

Comula norte	014/4	614/D		SAFe campaign	GEOTRACES campaigns	
Sample name	SWA	SWB	SWC	D2-578	GS-132	GD-158
Collection Location	05°20.5′ S, 06°11.9′ W to 06°44.8′ S, 05°04.8 W	27° 47.195′ S, 007°1 2.949՝ W	40° S 48.46° W	30° N, 140° W 31°40′ N 64°10′ W		31°40′ N 64°10′ W
Depth	Surface	500 m	Surface	1000 m	Surface 2000 m	
Filtration	Sartorius Sartobran-P cartridge. Cellulose acetate 0.45 µm pre- filter then 0.2 µm filter	Whatman GD/X PTFE 0.2 µm filter	Pall Acropak Supor capsule. PES 0.8 pre- filter then 0.2 µm filter.	Polycarbonate track etched 0.45 µm pre- filter, then 0.2-µm filter. Homogenized in 1000 L fluorinated LDPE tanks	Pall Acropak Supor capsule. PES0.8 p filter then 0.2 µm filter.	
Acidification	Bulk sample acidified at sea with 700 mL of ~10 M Q-HCI. Homogenized in 1000 L fluorinated LDPE tanks	Acidified at Plymouth University (PU) with 2 mL of Romil UpA grade HCl per L seawater	Acidified at PU with 1 mL of Romil UpA grade HCl per L seawater	Acidified at sea with 2 mL of conc HCl per L seawater.	Homogenized in 500 L fluorinated LDPE tanks.Acidified at sea with 2 mL of cono HCl.	
Final pH	Final pH 2.0		1.7	1.8	1.8	1.8
Consensus dissolved Fe ± 2 s.d. (nmol kg <sup>-1</sup> )	issolved Fe $\pm$ 2 s.d. 0.53 $\pm$ 0.20		N/A	0.933 ± 0.046	0.546 ± 0.092	1.0 ± 0.2
Reference	Bowie et al., 2006	Ussher et al., 2013	Wyatt et al., 2014	Lohan et al., 2006	Johnson et	al, 2007

## Table 2: Mathematical equations for quantification of the Fe amount content using gravimetric loading and FI-CL based procedure.

## 1. Amount content in the sample $\ensuremath{C_{\text{S}}}$

Blank corrected sample signal intensity divided by the sensitivity (calibration slope) of the measurement procedure :

$$C_{S} = \frac{\overline{J}_{S} - \overline{J}_{B}}{F}$$

2. Normalised signal intensity for the sample  $\overline{J}_s$ 

a. Normalised signal intensity for the sample accounting for all sources of uncertainty:

$$J_{S} = J_{R_{S}} \cdot \delta_{rep_{S}} \cdot \delta_{stab_{S}}$$

b. Average normalised raw signal intensity for consecutive replicates:  $\overline{J}_{R_{-}S} = \frac{1}{n} \sum_{i} \frac{I_{S_{-}i}}{m_{S_{-}i}}$ 

## 3. Normalised signal intensity for the analytical blank $\bar{J}_{\scriptscriptstyle B}$

a. Normalised signal intensity for the analytical blank accounting for all sources of

uncertainty: 
$$\overline{J}_{B} = \overline{J}_{R_{B}} \cdot \delta_{stab_{B}} \cdot \delta_{rep_{B}} \cdot \delta_{matrix_{B}}$$

b. Average normalised raw signal intensity for consecutive replicates under closed sample

valve conditions: 
$$\overline{J}_{R_B} = \frac{1}{n} \sum_{i} \frac{I_{B_i}}{\overline{m}_S}$$

4. Calibration slope F

a. Slope accounting for all sources of uncertainty:  $F = F_{reg} \cdot \delta_{matrix\_std}$ 

b. Slope of least squares regression line of the normalised signal intensity versus the amount added Fe:

$$F_{reg} = \frac{r \sum C_{\text{std}\_j} \cdot \overline{J}_{\text{std}\_j} - \sum C_{\text{std}\_j} \cdot \sum \overline{J}_{\text{std}\_j}}{r \sum C_{\text{std}\_j}^2 - \left(\sum C_{\text{std}\_j}\right)^2}$$

## 5. Amount content of the added Fe in the calibration standards

a. Added Fe amount in the calibration standard:  $C_{\text{std_j}} = \frac{m_{\text{stock_j}}}{(m_{\text{stock_i}} + m_{\text{calSW_j}})} \cdot C_{\text{stock}}$ 

b. Amount in the stock solution:

$$C_{stock} = \frac{m_{mother\_aliquot}}{m_{stock} + m_{mother\_aliquot}} \cdot C_{mother}$$

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Paran	neter	Index		
С	Fe amount content (nmol kg <sup>-1</sup> )	S	Sample	
I	Signal intensity (V)	В	Blank	
$\overline{J}$	Average mass normalised	R	Raw	
	intensity (V kg <sup>-1</sup> )	Std	Calibration Standard	
F	Sensitivity coefficient (slope, V	stock	Intermediate Fe standard stock solution	
	nmol <sup>-1</sup> )		(prepared dilution of the mother solution)	
n	Number of replicates	mother	Mother Fe standard solution (commercial	
			standard)	
r	Number of calibration	i	Index referring to the x <sup>th</sup> sample replicate	
	standards			
m &	Mass & average mass (kg)	j	Index referring to the x <sup>th</sup> standard	
$\overline{m}$		Reg	Sensitivity coefficient (calibration slope)	
			obtained by linear regression	
		calSW	a 'low iron' seawater substrate used to produ	
			the calibration curves	
δ	Unity multiplicative correction	Stab	Accounts for the uncertainty arising from the	
	factors carrying the relative		intensity stability over an analytical sequence	
	uncertainty associated to the	matrix	Accounts for the uncertainty arising from ma	
	parameter considered		effects on the sensitivity	
		rep	Accounts for the uncertainty arising from the	
		1		

WtoV

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Accounts for the uncertainty related to the

difference in loaded mass whether it is done by

575

## 577 Table 3: Slopes and their associated standard uncertainties depending on the regression calculations

578 considered. r is the number of standards and n the number of replicates per standard.

Regression approach		Data	Sensitivity coefficient (=slope) (F)		
		points	Value	Uncertainty (k=1)	
Weight	ted regression	7 (r)	2301	83	
Unweighted regression	average values		2297	118	
	all individual data	42 (r*n)	2297	56	

580 Table 4: Dependence of the relative standard uncertainty (rsu) on the calculated slope/sensitivity coefficient,

#### 581 rsu (F), in %, on the number of replicates or calibration standards used.

n	rsu (F), with n = number of replicates using 7 calibration standards (original + 6 Fe addition levels)	rsu (F), with n = number of calibration standards using 6 replicates for each standard
6	6.6	6.6
5	7.5	6.8
4	7.9	11.5
3	8.6	14.6

#### 

583Table 5: Amount content results with combined expanded uncertainty with a coverage factor (k) of 2 (i.e. 95%584confidence interval) for the three sea water samples from the SAFe and GEOTRACES campaigns using585gravimetric loading. Consensus values were downloaded from the GEOTRACES.org website and are from May5862013.

Commis	(	Obtained Fe am	Consensus Fe amount content			
	Peak height		Peak a	area	(nmol kg⁻¹)	
Sample	Value	Relative uncertainty	Value	Relative uncertainty	Value	Relative uncertainty
D2	$0.82 \pm 0.10$	12	$0.861 \pm 0.086$	10	0.933 ± 0.046	4.9
GS	0.478 ± 0.060	12	$0.500 \pm 0.051$	10	0.546 ± 0.092	16.8
GD	$0.800 \pm 0.099$	12	0.836 ± 0.084	10	$1.0 \pm 0.2$	20.0

Table 6: Relative contributions (%) to the combined uncertainty budget estimated for the dissolved Fe level

595 596 measured by FI-CL in the GD sample from the GEOTRACES campaign (symbols as in Table 2). The intermediate

result refers to the parameters used in equation 1 of Table 2, in which all associated uncertainties are included. 597

	Quantity	Gravimetric loading			
	Quantity	Peak height	Peak area		
$\overline{J}_{s}$	Intermediate result	29.5	44.4		
(V/kg)	$\overline{J}_{\scriptstyle R\_S}$ (treated as constant)	-	-		
	$\delta_{rep_S}$	7.9	9.4		
	$\delta_{stab_S}$	21.6	35.0		
$\overline{J}_{\scriptscriptstyle B}$	Intermediate result	0.6	1.4		
ه (V/kg)	$I_{B}$ (treated as constant)	-	-		
	$\overline{m}_{s}$	0.0	0.0		
	$\delta_{\mathrm{rep}_B}$	0.0	0.6		
	$\delta_{_{stab}\_B}$	0.1	0.0		
	$\delta_{matrix\_B}$	0.5	0.8		
F	Intermediate result	69.7	54.3		
(sensitivity coefficient or slope)	F <sub>reg</sub>	69.7	54.3		
(V/nanomol)	$\delta_{ mtmm{matrix\_std}}$	0.0	0.0		

598

## 600 Supplementary information

601 Table S1: details of the uncertainty budget associated to the result of the measurement by FI-CL (with gravimetric loading) of the dissolved Fe amount

602 content in the D2 reference material from SAFe. Symbols as in Table 2.

603

			Peak height			Peak area		
Quantity		Value	Stand Unc (k=1)		Value	Stand Unc (k=1)		
			Absolute	%		Absolute	%	
$\overline{J}_{S}$	Intermediate result	D2	1918	63	3.3	52179	1700	3.3
		GS	1140	37	3.3	30809	1000	3.3
(V/kg)		GD	1879	62	3.3	50711	1700	3.3
	$\overline{J}_{R_{-}S}$	D2	1918	0	0	52179	0	0
	K_3	GS	1140	0	0	30809	0	0
		GD	1879	0	0	50711	0	0
	$\delta_{rep_S}$		1	0.017	1.7	1	0.015	1.5
	$\delta_{stab_s}$		1	0.028	2.8	1	0.029	2.9
$\overline{J}_{\scriptscriptstyle B}$	Intermediate result		41.8	2.2	5.3	1115	190	17.0
	I <sub>B</sub>		0.0645	0	0	1.72	0	0.0
(V/kg)	$\overline{m}_{s}$		0.001542	0.000004	0.3	0.001542	0.000004	0.3
	$\delta_{\mathrm{rep}_B}$		1	0.069	6.9	1	0.17	17.0
	$\delta_{stab\_B}$		1	0.10	10	1	0	0
	$\delta_{matrix\_B}$		1	0.2	20	1	0.2	20
F (sensitivity coefficient or	Intermediate re	Intermediate result		118	5.1	59330	2190	3.7
	F <sub>reg</sub>		2297	118	5.1	59330	2190	3.7
slope) (V/nanomol)	$\delta_{matrix\_std}$		1	0	0	1	0	0