MUSCULOSKELETAL SURGERY FLUOROSCOPIC FREE HAND AND ELECTROMAGNETIC-GUIDED TARGETING SYSTEM FOR DISTAL LOCKING SCREWS OF HUMERAL INTRAMEDULLARY NAIL.

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	reduction of both surgical time and risk factors related to the exposure to ionizing radiation for all the operating room staff and the patient.
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Compliance with Ethical Standards:

Conflict of Interest: Pietro Persiani declares that he has no conflict of interest. Michele Gurzi declares that he has no conflict of interest. Oreste Moreschini declares that he has no conflict of interest. Giorgio Di Giacomo declares that he has no conflict of interest. Ciro Villani declares that he has no conflict of interest.

Ethical approval: All procedures performed in studies involving human participants were in accordance with the ethical standards of the institutional and/or national research committee and with the 1964 Helsinki declaration and its later amendments or comparable ethical standards.

Informed consent: This is a retrospective study based on the analysis of the data present in the operating room records, there has been no contact with patients. Informed consent regarding the collection and analysis of data related to the surgery was obtained from all individual participants included in the study.

INTRODUCTION

Internal fixation with intramedullary nailing is one of the most used techniques in the treatment of diaphyseal fractures of the humerus and long bones in general; it offers great advantages, including indirect reduction and preservation of soft tissues and the fracture hematoma. The positioning of the distal locking screws remains, however, a procedure that has long surgical times and exposes the surgeon, and the patient, to high doses of ionizing rays [1-16], leading to numerous diseases, including thyroid cancer [4].

The traditional technique consists in the freehand insertion of the screws under fluoroscopic control [17-21]; this technique requires sufficient experience and skill from both the surgeon and the radiographer.

The Sureshot TM Distal Targeting System (Smith & Nephew, Inc., Memphis, TN, USA) is a new centring system for the distal locking of intramedullary nails, which uses computer technology based on electromagnetic fields. The advantages of this feature are: the reduced exposure to ionizing radiation for both patient and surgeon [22-27], the reduced potential of placement errors of the distal screws and the reduced surgical time [28-31].

The aim of our study is to analyze in a retrospective view the results obtained in humeral shaft fracture treated with The Sureshot TM Distal Targeting System compared to the same device but using the more traditional free hand technique for distal screw fixation, to assess the efficiency of this last device to reduce the exposition time to ionizing radiation.

MATERIALS AND METHODS

Our work is a non-randomized control group study analysed in a retrospective view, based on the study of medical and surgical records. Our study sample is composed of 59 non-consecutive patients (34 males and 25 females, average age 41, age range 34-47) with a simple humerus fracture diagnosis, types 1.2.A.1, 1.2.A.2 and 1.2.A.3 according to the AO classification. All these cases were these patients were treated between February 2013 and February 2016, at the -----. In all cases included in this study the ante-grade humeral intramedullary nail (Trigen Smith & Nephew, Inc., Memphis, TN, USA) was used. The sample involved in the study, although analysed retrospectively, was homogeneous and treated by two experienced operators (PP, OM) with a long experience in the repair of humeral fractures. Our sample was dived in two groups according to the used or not of the Sureshot TM Distal Targeting System. Additional inclusion criteria for our study sample were: absence of pathological fractures; diagnosis of a simple fracture according to the AO classification; absence of neurological deficits; absence of poly-traumas, use of the Sureshot TM

Distal Targeting System.

The chosen between freehand technique and distal targeting system was made according to the skill of surgeon with the new system, as result during the first part of the period considered most of the patients were treated with the freehand technique and are non-consecutive, on the opposite the patients treated in the last part of this period were all treated with the Sureshot TM Distal Targeting System.

Thus, the two groups compared in our study were composed as follow (Table 1):

Group 1 was the control group, it include 28 patients treated with a 16 cm intramedullary nail (TrigenTM nails, Smith & Nephew, Inc., Memphis, TN, USA) with distal locking screws inserted with a freehand technique: positioning the image intensifier perpendicularly to the arm supported by the aid, a centred incision is performed on the locking hole and the bone surface is reached in a blunt manner; the first cortex is drilled; the drill is then removed and the anteroposterior positioning of the cutter in correspondence of the locking hole is checked; if the position is correct one can proceed up to the second cortex; the length is measured and is controlled laterally, the nailing screw is then placed and its correct positioning and length are antero-posteriorly checked. The procedure is then repeated for the second screw.

Group 2 was the study group, it include 31 patients treated with a 16 cm ante-grade intramedullary nail (Trigen TM nails, Smith & Nephew, Inc., Memphis, TN, USA) using the Sureshot TM Distal Targeting System for the distal locking. All the locking procedures were done by two of the authors with an already acquired learning curve. When making a comparison with Group 1, there was no change in the arrangement and organization of the operating room.

The targeting system consists of three main parts: a computerized control unit (fig. 1), located within the display screen, a donut-shaped free hand pointer that produces a concentrated electromagnetic field and a sensor probe (fig. 2), inserted in the nail, which transmits the position information to the control unit.

The system then plays back a virtual image of the distal part of the nail in real time. A 12mm drill is positioned at the centre of the pointer. A trajectory line appears on the display in real time, connecting two coloured circles (Figure 2), which represent the tip of the drill and the centre of the pointer: the alignment of the circles provides the ideal direction for drilling and screw insertion. The skin is incised on the indicated site and a calibrated drill is connected through the guiding-sleeve. The correct position of the screws was evaluated intra-operatively with fluoroscopy after insertion.

Two intra-operative temporal parameters were timed in both groups: the time, measured in seconds, for the correct positioning of the distal locking screws (from the time when the nail is positioned to the last antero-posterior check-up

for the evaluation on the correct placement of the screws); the time, measured in seconds, of exposure to ionizing radiation during this procedure (automatically calculated by the Siemens model fluoroscopic image intensifier).

The evaluation of the data was performed by running the Student's t-test for normal continuous data for two independent samples by means of the SPSS 20 statistical software (IBM statistics).

RESULTS

In group 1 (free hand), the average time for the distal locking was 28.96 seconds (range of 16-39, S.D: 8,401), and the average time of exposure was 1023.57 seconds (range of seconds 510-1400, S.D: 429,317).

In group 2, the average time for the distal locking was 4.35 seconds (range of 2-8 S.D: 1,799), and the average time of exposure was 645.48 seconds (range of seconds 310-1110, S.D 210,093).

For both the parameters assessed within the two groups there was a significant statistical difference *p*-value <0.001 (Table 2).

There were no immediate complications in the two groups; since our study focuses on the analysis of surgery times and radiation exposure, there is no value, at this stage, in assessing the long-term complications.

DISCUSSION

Both the *free hand* distal locking and the Targeting System techniques achieved a correct positioning of the implant at the end of the surgery.

In group 2, the exposure to ionizing radiation was significantly lower, reducing the risky and occupational exposure that surgeons are subject to [30-33]. Amongst the orthopedic procedures with fluoroscopy, intramedullary nailing of long bones is considered the one with the highest exposure to radiation [8]. During these surgeries, the distal locking of the intramedullary nail is the phase with the higher percentage of exposure to radiation, reaching as much as 50% [1]. Recent studies have revealed an increased risk of cancer, mostly due to radiation exposure, among orthopedic surgeons [14-15].

Literature data on the Sureshot TM system report an accuracy of between 96% and 100%, with a decrease of the average irradiation time from 36 to 13 seconds and from 49 to 25 seconds for the locking of the tibia and femur, respectively [34].

In a comparative study with the *free hand* technique on a cadaver, the new technique was equally effective (100% vs. 94% for the tibial nail; 96% for both techniques for the femoral nail) and faster (+ 32% for the femoral nail and + 47.5% for the tibial nail) compared to traditional distal locking [34]. The use of the SureshotTM technique is currently not able to completely eliminate the use of fluoroscopy, however, it does limit its use to the confirmation of the correct final position of the screws or in case of particular difficulty.

There are many works present in literature regarding distal locking in the nailing of femoral and tibial fractures, and they all are based on the *free hand* method; contrarily, there are few studies that compare the distal locking techniques in progress with intramedullary humeral nailing [35-46].

The main disadvantages are the added cost (the probe used is single-use only) and the fact that the pointer is used "free hand" by the surgeon, without the aid of a support, thus making it unstable and prone to little trajectory changes due to involuntary movements of the surgeon. However, the continuous real time display of the procedure allows for immediate corrections and, consequently, an accurate positioning of the screw on the first attempt (whereas the *free hand* technique usually requires 1-6 attempts), therefore reducing also the surgical and operating room occupancy times, in a statistically significant way.

In any case, larger studies are still needed to evaluate the cost (of the device)/benefit (statistically significant reduction of the surgical time and exposure to ionizing rays).

CONCLUSION

The SureshotTM Distal Targeting System has proven to be equally effective when compared to the traditional techniques in 1.2.A.1, 1.2.A.2 and 1.2.A.3 distal humeral fractures (AO classification).

Furthermore, it adds with the benefits of a significant reduction of both surgical time and risk factors related to the exposure to ionizing radiation for all the operating room staff and the patient, thus reducing the incidence of related diseases.

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Fig. 1 Computerized control unit



Fig. 2 Donut-shaped free hand pointer and sensor probe

	Overall x-ray exsposure (sec)		Distal screw x-ray exsposure (sec)		
	Group1	Group2	Group1	Group2	
1	510	310	16	2	
2	550	360	16	2	
3	550	400	18	2	
4	590	440	17	2	
5	610	460	18	3	
6	650	480	21	3	
7	660	480	20	3	
8	690	500	22	3	
9	700	500	22	3	
1 0	720	510	25	3	
1 1	720	510	26	3	
1 2	730	530	28	3	
1 3	800	550	30	4	
1 4	790	550	30	3	
1 5	910	570	31	4	
1 6	1020	570	36	4	
1 7	1100	600	35	4	
1 8	1110	620	35	4	
1 9	1200	650	34	5	
2 0	1230	700	35	5	
2 1	1340	710	35	5	

Table 1 – Partition of the 2 groups

2 2	1400	740	36	5
2 3	1510	770	36	6
2 4	1550	810	37	6
2 5	1600	840	37	6
2 6	1730	840	38	6
2 7	1790	870	38	6
2 8	1900	920	39	6
2 9	-	1020	16	8
3 0	- 1090		16	8
3 1	-	1110	18	8

Groups		N	Average	Deviation std.	Average std. errors	Sig. (2- code)
Overall x-ray exsposure	1	28	1023,57	429,317	81,133	,000
(sec)	2	31	645,48	210,093	37,734	
Distal screw x-ray	1	28	28,96	7,946	1,502	,000
exsposure (sec)	2	31	4,35	1,799	,323	



group



group

