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Highlights

- A numerical analysis framework has been developed that captures the experimentally observed dynamic response of micro-lattices
- The framework has been demonstrated to be accurate and robust across two lattice geometries and two loading rates, with responses monitored at both the impact face and the distal face of the sample
- The results suggest that simple MDoF models can be developed to capture the response of such geometries under fast loading regimes

Energy absorption in lattice structures in dynamics: Nonlinear FE simulations

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1 Abstract

2 An experimental study of the stress-strain behaviour of titanium alloy
3 (Ti6Al4V) lattice structures across a range of loading rates has been reported
4 in a previous paper (Ozdemir et al., 2016). The present work develops sim-
5 ple numerical models of re-entrant and diamond lattice structures, for the
6 first time, to accurately reproduce quasi-static and Hopkinson Pressure Bar
7 (HPB) test results presented in the previous paper. Following the develop-
8 ment of lattice models using implicit and explicit non-linear finite element
9 (FE) codes, the numerical models are first validated against the experimental
10 results and then utilised to explore further the phenomena associated with
11 impact, the failure modes and strain-rate sensitivity of these materials. We
12 have found that experimental results can be captured with good accuracy
13 by using relatively simple numerical models with beam elements. Numer-
14 ical HPB simulations demonstrate that intrinsic strain rate dependence of
15 Ti6Al4V is not sufficient to explain the emergent rate dependence of the
16 re-entrant cube samples. There is also evidence that, whilst re-entrant cube
17 specimens made up of multiple layers of unit cells are load rate sensitive, the
18 mechanical properties of individual lattice structure cell layers are relatively

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19 insensitive to load rate. These results imply that a rate-independent load-
20 deflection model of the unit cell layers could be used in a simple multi degree
21 of freedom (MDoF) model to represent the impact behaviour of a multi-layer
22 specimen and capture the microscopic rate dependence.

Keywords: lattice structures, impact and blast protection, finite element
method (FEM), emergent rate-dependence

23 1. Introduction

24 Over the previous few decades, research into the quasi-static and dy-
25 namic behaviour and energy absorbing characteristics of cellular solids has
26 been assessed using costly experiments, because of the extreme complexities
27 associated with their collapse mechanisms. With the current advances in
28 numerical methods, we can predict the response of cellular solids even under
29 very highly nonlinear loading regimes with a reasonable accuracy. Thus, in
30 recent years, numerical methods have been widely used for the characteri-
31 sation of mechanical behaviour and energy absorption properties of cellular
32 solids.

33 Numerical studies carried out on cellular solids are of both quasi-static
34 and dynamic nature and have been performed on a wide range of materi-
35 als including both stochastic (such as metallic foams) and periodic cellular
36 solids (such as lattice structures, hollow rings). Aktay et al. (2008) stud-
37 ied the quasi-static crushing behaviour of honeycombs using detailed micro-
38 mechanical models, homogenised modelling approach and a finite element-
39 discrete particle model with semi-adaptive coupling (SAC) technique and
40 compared the results of these models with experiments. The progressive

41 folding behaviour of square aluminium tubes subjected to quasi-static axial
42 crushing was numerically investigated using FEM by El-Hage et al. (2005).
43 Karagiozova et al. (2005) studied the dynamic response of circular and square
44 aluminium alloy tubes subjected to an axial explosive load using experimen-
45 tal and numerical techniques. Particular attention was paid to the influence
46 of the impulse and material properties on the energy absorption capacity of
47 tubes. Compressive response of a multi-layered steel pyramidal lattice, which
48 was investigated by underwater explosive tests, was simulated using a fully
49 coupled Euler-Lagrange FE hydro code by (Wadley et al., 2008). Energy
50 absorption, wave filtering and wave variation characteristics of ring systems
51 after collapse were studied both experimentally and numerically by Wang
52 et al. (2010). In the majority of the numerical studies, cellular structures are
53 assumed to have perfect geometries. However, the extent of imperfections
54 can be more easily considered and controlled in a numerical model than a
55 physical test. The effects of cell shape and cell wall thickness imperfections
56 on the dynamic crushing behaviour of honeycomb structures were studied
57 using the FEM by Li et al. (2007). Ajdari et al. (2011) carried out a nu-
58 merical study on 2D honeycomb structures in order to clarify the effect of
59 deformation rate, defects and irregularity on the behaviour of cellular struc-
60 tures. However, validation of the numerical model was not presented in their
61 paper.

62 Although there are several disadvantages associated with experiments
63 (for instance cost, time and collection of limited information during a fast
64 dynamic phenomenon), experimental works conducted on a range of cel-
65 lular materials have highlighted important issues associated with energy

66 absorption mechanisms of such materials when subjected to high loading
67 rates. For instance, Reid and Peng (1997) and Vural and Ravichandran
68 (2003) carried out Hopkinson Pressure Bar (HPB) and Split Hopkinson
69 Pressure Bar (SHPB) tests on wood samples, respectively. Reid and Peng
70 (1997) reported localised deformation mechanism and enhancement of crush-
71 ing strength of wood under dynamic loading conditions. Vural and Ravichan-
72 dran (2003) computed specific energy dissipation capacity of balsa wood and
73 they found that it was comparable with those of fiber-reinforced polymer
74 composites. Quasi-static and dynamic response of rectangular arrays of thin-
75 walled metal cylindrical tubes were examined experimentally by Shim and
76 Stronge (1986) and Stronge and Shim (1987), respectively. It was observed
77 that the response of a tightly-packed array of ductile, thin-walled tubes un-
78 der quasi-static and dynamic conditions is governed by the packing arrange-
79 ment. Similarly, experiments carried out on diamond and re-entrant cube
80 lattices (Ozdemir et al., 2016) demonstrated that unit cell geometry controls
81 the force-deformation response of such structures. Goldsmith and Sackman
82 (1992) determined the energy dissipation characteristics of bare honeycombs
83 and sandwich plates with honeycomb cores using a ballistic pendulum. Al-
84 ghamdi (2001) presented a review on mechanical properties of materials and
85 devices including tubes, sandwich plates and honeycomb cells for dissipating
86 kinetic energy.

87 A thorough understanding of the dynamic behaviour of cellular solids is
88 crucial for maximising the performance of such materials particularly under
89 high loading rates. The response of cellular solids may show quite distinctive
90 differences under quasi-static and dynamic loads, because of rate sensitiv-

ity. The mechanisms of rate sensitivity of cellular materials consist of the strain rate dependence of the parent material, the microinertia effects, the compression and flow of air trapped in cells, the shock wave generation, the effect of micro-structural geometry and the influence of intrinsic length scale of the material. Several experimental and numerical studies have been undertaken on cellular materials to highlight mechanisms causing rate sensitivity. Lee et al. (2006a) carried out a series of quasi-static compression, Kolsky bar (SHPB) and gas gun experiments (HPB) on a type of open-cell aluminium alloy foam and stainless steel woven textile core materials. While the peak stress of open-cell foams was deformation insensitive, the rate-sensitivity of the peak stress was observed in the textile cores. Differences in local strain fields were observed in both materials at intermediate strain rates ($230 - 330 \text{ s}^{-1}$), when compared with quasi-static loading conditions. This was attributed to the microinertia effects for the case of foam materials. At very high strain rates, the shock wave propagation was observed in both materials. In a following study, Lee et al. (2006b) undertook similar physical tests on pyramidal truss cores made of 304 stainless steel to investigate deformation modes of such materials. In addition, non-linear FE simulations were performed to understand the roles of material strain rate hardening and microinertia on the quasi-static and dynamic response of sandwich panels with pyramidal truss cores. At intermediate strain rates, microinertia effects caused differences in force-deformation response and deformation mode of such materials when compared with quasi-static loading conditions. At larger deformations, in addition to micro-inertia, the material strain rate hardening contributed to changes in deformation mode and stress-

116 strain response. Liu et al. (2009) studied the dynamic crushing behaviour
117 of 2D Voronoi honeycomb using FE method. Three different deformation
118 modes were observed at different loading ranges. These are: (1) quasi-static
119 homogeneous modes where crush bands are located randomly and the defor-
120 mation is macroscopically uniform; (2) transition mode in which crush bands
121 are mainly concentrated at the impact end rather than the support end; and
122 (3) shock mode where crush bands sequentially propagate from impact end
123 to the distal end. The changes in deformation mechanisms and stress-strain
124 response of Voronoi honeycomb observed under high loading rates were at-
125 tributed to inertia effects. Zhao and Gary (1998) performed quasi-static
126 and SHPB tests on aluminium honeycombs in the in-plane and out-of-plane
127 directions. While the in-plane crushing behaviour of the aluminium honey-
128 comb was rate insensitive, significant differences between static and dynamic
129 out-of-plane crushing behaviour of the honeycombs were observed due to
130 structural effects. Barnes et al. (2014) used direct impact tests to evaluated
131 shock-like response of an open cell aluminium foam by developing shock-
132 impact speed Hugoniot relations. As an extension of this work, Gaitanaros
133 and Kyriakides (2014) used FE analysis to replicate the experimentally ob-
134 served dynamic crushing behaviour of the open cell aluminium foam by form-
135 ing planar shocks. Zheng et al. (2014) examined the dynamic stress-strain
136 states in a closed-cell foam under direct impact conditions by creating FE
137 models of the foam using 3D Voronoi technique. Sun et al. (2016) obtained
138 a linear relation between shock speed and impact speed and established a
139 unique linear Hugoniot relation to characterise shock constitutive relation
140 for a 2D virtual foam.

141 In this study, we aim to develop simple FE models of titanium alloy
142 (Ti6Al4V) lattice structures to reproduce quasi-static and Hopkinson Pres-
143 sure Bar (HPB) test results reported in a previous study (Ozdemir et al.,
144 2016) with a reasonable accuracy. In the literature, existing numerical and
145 experimental studies on lattice structures focus mainly on two geometries:
146 body-centred cubic (BCC) and a similar structure with vertical pillars (BCC-
147 Z) (McKown et al., 2008; Mines et al., 2013; Smith et al., 2013). To the
148 best of our knowledge, this is the first research to numerically investigate
149 the dynamic response of re-entrant and diamond lattices. Imperfections of
150 the lattice structures have not been accounted for in the numerical mod-
151 els and perfect models of re-entrant cube and diamond lattices have been
152 built. In addition, there are very limited studies in the literature, which
153 validate numerical results against experiments for the dynamic response of
154 cellular solids over all duration of impact event (Lee et al., 2006b) and exist-
155 ing studies mainly focus on a maximum value of a response parameter (such
156 as maximum displacement). Following the development of numerical lattice
157 models using implicit and explicit non-linear finite element (FE) codes, in
158 this work, these models are validated against experimental results during all
159 time history of the impact event. Finally, the numerical models are utilised
160 to explore further the phenomena associated with impact, the failure modes
161 and strain-rate sensitivity of these materials.

162 The outline of the present paper can be summarised as follows: In Section
163 2, a nonlinear FE procedure for the analysis of quasi-static and impact re-
164 sponse of diamond and re-entrant cube lattice structures is discussed briefly.
165 Next, stress-strain response and associated failure modes of lattices, which

166 were captured by quasi-static compression tests, are simulated using the non-
167 linear FEM in Section 3. The energy absorption characteristics of lattices
168 under high deformation rates are examined numerically in Section 4 by tak-
169 ing into account the effect of unit-cell geometric configuration. Finally, the
170 influence of strain rate sensitivity of Ti6Al4V and radial confinement on the
171 impact response lattice samples is assessed in Sections 5 and 6, respectively.

172 2. Nonlinear FE modelling

173 In this work, two unit cell geometries are chosen to carry out numerical
174 HPB impact simulations. The geometries are diamond (Figure 1(a)), where
175 the struts are arranged similar to the interatomic bonds in the atomic lattice
176 of diamond, and re-entrant cube (Figure 1(b)), a cube shape with all edges
177 and diagonal struts across the faces bent towards the centre; were it not for
178 the fact that the unit cells of the lattice are connected at the corners, this
179 last structure would resemble the auxetic structure of Lakes and Park (1998).
180 The repeating unit cell is kept as a 5 mm side length cube for both lattices.
181 Square strut cross-section was chosen for the diamond lattices with diagonal
182 length of 1.0 mm, whereas the strut diameter of the re-entrant cube is 0.48
183 mm.

184 For HPB impact tests, a steel bar projectile and a Nylon 66 impactor are
185 used for low and high velocity loadings, respectively. The steel projectile has
186 a diameter of 25 mm, a length of 250 mm and a mass of 963 g. The Nylon
187 66 projectiles have a diameter of 27 mm, a length of 31 mm and a mass of
188 19.3 g. Two testing configurations were considered for the HPB tests: In
189 the first case, the specimen was placed on the impact face of the HPB and

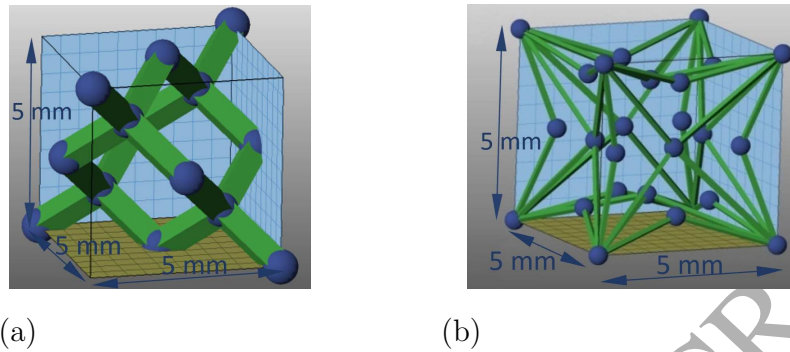


Figure 1: Representative unit cells of (a) diamond and (b) re-entrant cube lattice structures.

190 the projectile was fired onto the specimen (Figure 2(a)). In the other case,
 191 the test specimens were fixed to the impact face of the projectile (Figure
 192 2(b)). In these tests, 3D FE models of the impactor and HPB are built along
 193 with the full 3D models of lattices therefore, boundary conditions are taken
 194 care of by contact algorithms defined between the impactor and sample and
 195 between the HPB and sample. The HPB has a free boundary condition at
 196 its far end.

197 The multi-purpose nonlinear FE analysis program LS-DYNA is used to
 198 simulate the response mechanisms of lattice samples. Due to the fact that
 199 continuum elements are computationally expensive, 3D Timoshenko beam
 200 elements with plasticity and large deformation capabilities are used for the
 201 modelling of lattices. The main failure mechanisms of the lattices such as
 202 plasticity, buckling, and brittle shear failure are considered in the numerical
 203 model. In order to take into account plasticity, a material model pertaining
 204 to Von Mises yield condition with isotropic strain hardening is introduced in

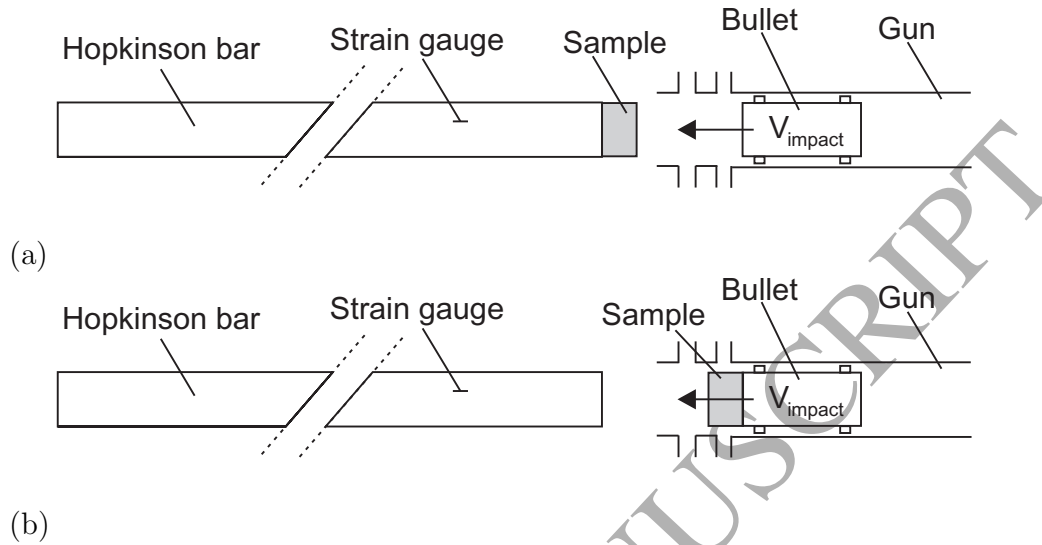


Figure 2: Two testing configurations for the HPB tests: (a) the distal face test and (b) impact face test.

205 the FE model. A plastic strain-based failure criteria, where the element is
 206 deleted when all the through thickness integration points reach the defined
 207 failure strain, is used in the model. Buckling is considered by activating
 208 geometric nonlinearity in the numerical simulations. In addition, struts are
 209 discretised by several beam elements in order to capture the micro-buckling
 210 of struts correctly. Tensile tests were performed on as-built round samples
 211 with a cross-sectional area of 24 mm^2 by following ASTM E8M-13a guide-
 212 lines (E8M-13a (2013)) to determine mechanical properties of Ti6Al4V. In
 213 the material model, Ti6Al4V alloy is assumed to have a Young's modulus of
 214 114 GPa , Poisson's ratio of 0.3 , mass density of $4.43 \times 10^3 \text{ kg/m}^3$ and yield
 215 stress of 880 MPa . The values of these properties are also consistent with

216 the values obtained from the literature (Al-Bermani et al., 2010; Rafi et al.,
217 2012). Numerical analysis results also indicated that the global response was
218 not very sensitive to these particular values. Effective plastic strain to fail-
219 ure is set to be 0.3. Strain rate dependency of Ti6Al4V is ignored in the
220 numerical simulations, unless otherwise stated. For the numerical quasi-
221 static simulations, rigid material is assumed for the steel test rig. For the
222 numerical HPB test simulations, a linear elastic material with Young's
223 modulus of 210 GPa, Poisson's ratio 0.3, mass density $7.80 \times 10^3 \text{ kg/m}^3$ is as-
224 sumed for the steel impactor. The Nylon 66 impactor is considered to exhibit
225 elastic-perfect plastic behaviour with Young's modulus of 1.7 GPa, Poisson's
226 ratio of 0.4, mass density of $1.088 \times 10^3 \text{ kg/m}^3$, yield stress of 160 MPa and
227 tangent modulus of 1.00 MPa. All the input data for the material models
228 used in the quasi-static and impact tests are given in Table 1 along with the
229 LS-DYNA material number and name.

230 In the FE simulations, the interaction forces between parts are trans-
231 ferred with contact algorithms. The so-called one-way contact algorithm
232 (*CONTACT_AUTOMATIC_NODES_TO_SURFACE), in which only slave
233 nodes (lattice nodes) are checked for penetration of the master segments (test
234 rig), is used to model the interaction between lattices and test rig in the nu-
235 merical quasi-static simulations. The friction forces between the test rig and
236 lattice sample are taken into account with static and dynamic friction coef-
237 ficients of 0.1. For the numerical HPB test simulations, two separate one-way
238 contact types (*CONTACT_AUTOMATIC_NODES_TO_SURFACE) are used
239 to model the force transfer between the impactor and lattice sample and
240 the interaction between the lattice sample and HPB. Self-contact of the

241 lattices is modelled using a beam-to-beam contact algorithm (*CONTACT
242 _AUTOMATIC_GENERAL). Static and dynamic friction coefficients are de-
243 fined as 0.30 for all contact cases. Following the development of the finite
244 element model of lattices, a mesh sensitivity analysis was carried out to en-
245 sure that the results are not sensitive to the mesh size; it was found that five
246 beam elements per strut resulted in effective convergence of the results. The
247 finite element models of 5-layer auxetic and diamond samples consist of 24320
248 and 8320 beam elements respectively. The length of each beam element is
249 0.543 mm and 0.433 mm for auxetic and diamond lattices, respectively. The
250 rigid quasi-static test rig was modelled using 5408 four-node shell elements.

251 The experimental load-time signals from the impact loading events were
252 recorded by means of a single HPB, 25 mm diameter, 3.4 m length, with a
253 perimeter-mounted axial strain gauge station set 250 mm from the impact
254 face of the bar. The strain gauge station thus recorded a distorted ver-
255 sion of the impact load, due to well-known dispersion effects. As discussed in
256 (Ozdemir et al., 2016), the impact load-time signals typically included signifi-
257 cant energy at frequencies above that which can currently be accommodated
258 by standard frequency domain dispersion correction techniques (Tyas and
259 Watson 2001). Therefore, in order to compare like with like, the numerical
260 models of the impact events included explicit modelling of the full HPB in
261 addition to the impactor and lattice specimen. In the model, the load signal
262 dispersed as it travelled along the model of the HPB, before being recorded
263 on the bar perimeter at the location of the strain gauge in the experimental
264 work, 250 mm from the impact face of the bar (Figure 3). In all subse-
265 quent comparisons of the experimental and numerical stress-time histories in

Part	LS-DYNA Material number [-]	LS-DYNA Material name [-]	ρ [kg/m ³]	E [GPa]	ν [-]	σ_y [MPa]	E_{tan} [MPa]
Compression test rig	*MAT_020	*MAT_RIGID	7850	210	0.3	–	–
Steel impactor & HPB	*MAT_001	*MAT_ELASTIC	7850	210	0.3	–	–
Nylon impactor	*MAT_003	*MAT_PLASTIC_KINEMATIC	1088	1.5	0.4	160	1
Ti6Al4V	*MAT_024	*MAT_PIECEWISE_LINEAR_PLASTICITY	4456.4	113.76	0.3	895.6	–

Table 1: Input data for all materials used in the numerical analyses.

266 this paper, the results are those measured at the gauge position. The HPB
 267 was modelled using 491904 and 724680 eight-node hexahedral elements in
 268 low and high velocity impact simulations, respectively. The steel and ny-
 269 lon impactors were represented with 39424 and 13200 eight-node hexahedral
 270 elements, respectively.

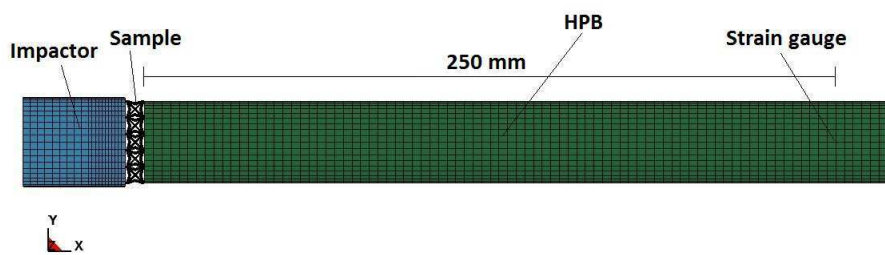


Figure 3: Schematic description of the 3D FE model of the HPB test setup

271 The average computation time for analysing low velocity impact tests of
 272 single and five-layer lattice samples was approximately 6 hours and 20 hours,
 273 respectively, on a quad core 64 bit PC with 2 GB memory. The finite element
 274 analysis of high velocity impact tests of single- and five-layer samples took
 275 around 40 minutes and 5 hours, respectively, on the same computer.

276 It is worth noting that stress measurements, whether experimental or
 277 numerical, may be influenced by edge (or size) effects in case of a low number
 278 cells in the height direction. Therefore, the findings of the experimental and
 279 numerical investigations regarding dynamic properties of lattices reported
 280 here are indicative only.

281 3. Nonlinear quasi-static behaviour of lattices

282 Single layer square samples of diamond and re-entrant cube lattices with
283 an edge length of 25 mm and a height of 5 mm were compressed at a crosshead
284 speed of 0.2 mm/min using a Hounsfield TX0038 universal test rig (Ozdemir
285 et al., 2016). For each sample type, three quasi-static tests were carried out.
286 The average stress-strain curves of the diamond and re-entrant cube samples
287 following quasi-static compression tests are shown in Figures 4(a) and (b),
288 respectively. As one can observe from these figures, the quasi-static stress-
289 strain response of the re-entrant and diamond lattice structure show a typical
290 of Type II (stretch dominated) response as defined by Ashby (2006), where
291 a relatively constant initial stiffness is followed by post-peak softening, and
292 later by final densification of the material.

293 Relative density $\bar{\rho}$, elastic modulus E , yield stress σ_y and absorbed energy
294 (up to densification) of the single-layer samples obtained following the quasi-
295 static tests are summarized in Table 2. Strain limits up to 30 % and 60 %
296 are chosen to compute absorbed energy for the re-entrant cube and diamond
297 lattices, respectively. Stress-strain plots indicate that diamond lattices are
298 more efficient than re-entrant cube trusses for energy absorption under quasi-
299 static conditions, although the relative density of the re-entrant cube samples
300 is higher than that of diamond lattices.

301 Numerical quasi-static stress-strain response of diamond and re-entrant
302 cube lattices is also superimposed in Figures 4(a) and (b), respectively. An
303 increase in initial stiffness of experimental stress-strain curves of re-entrant
304 and diamond lattices at around of 80% and 180% is observed due to the
305 initial crushing of diamond and re-entrant cube samples, respectively. Both

Lattice structure	N. of layers	$\bar{\rho}$	E	σ_y	Absorbed energy
		[—]	[MPa]	[MPa]	[MJ/m ³]
Diamond	1	0.137	132.2	11.8	2.32
Re-entrant cube	1	0.166	126.6	10.8	1.65

Table 2: Averaged material properties obtained following the quasi-static tests.

306 experimental and numerical stress-strain curves of diamond and re-entrant
 307 cube lattices show a clear peak load which coincides with the onset of frac-
 308 ture occurring in the struts near the nodes. After the peak load, post-yield
 309 softening behaviour is followed by a steep stress rise due to densification of
 310 the lattice layer.

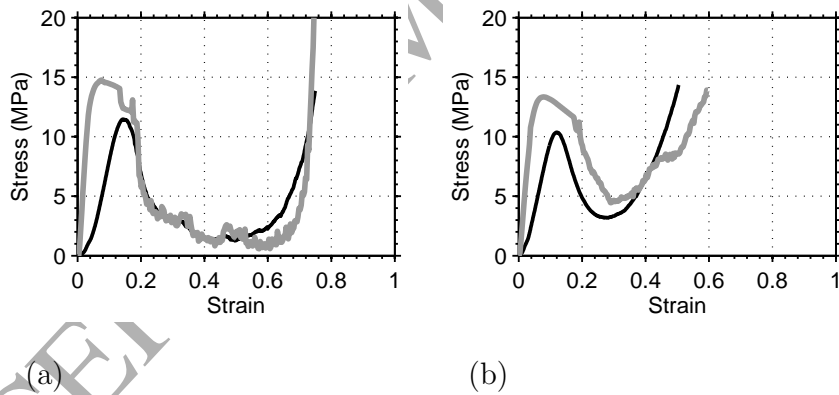


Figure 4: The average experimental (black line) and numerical (grey line) stress-strain curves of single-layer (a) diamond and (b) re-entrant cube samples obtained following the quasi-static compression tests.

311 An implicit time integration technique is employed to obtain economic

312 solutions for the quasi-static response of lattice structures. However, the im-
313 plicit FEM encountered numerical difficulties when solving non-linear prob-
314 lem after the samples are compressed around 1 mm. Therefore, switching
315 from the quasi-static implicit scheme to the dynamic explicit scheme with
316 mass scaling is employed for both diamond and re-entrant cube lattice sam-
317 ples. The time step size is kept large enough to ensure that kinetic energy
318 is less than 5% of the peak internal energy. The numerical method predicts
319 a higher initial stiffness than experiments for both re-entrant cube and dia-
320 mond samples. In the numerical simulations, the geometry of the struts is
321 assumed to be perfectly circular without any imperfection along their length.
322 On the other hand, lattice struts manufactured by the Electron Beam Melt-
323 ing (EBM) technique include irregularities both in cross-section and along
324 the length of the strut (Ozdemir et al., 2016) which act as weakeners. There-
325 fore, the numerical method predicts somewhat higher strength and stiffness
326 for the quasi-static response of diamond and re-entrant cube samples than
327 is observed experimentally. Since the diameter of the struts in the diamond
328 samples is larger than that of re-entrant cube samples, imperfections, which
329 are independent of strut size, arising from the resolution limitations of the
330 processing method, play a more important role in the quasi-static response
331 of the re-entrant cube samples. A remarkable consistency of experimental
332 and numerical deformed shapes of the re-entrant cube and diamond samples
333 is observed following the quasi-static compression tests (Figure 5).

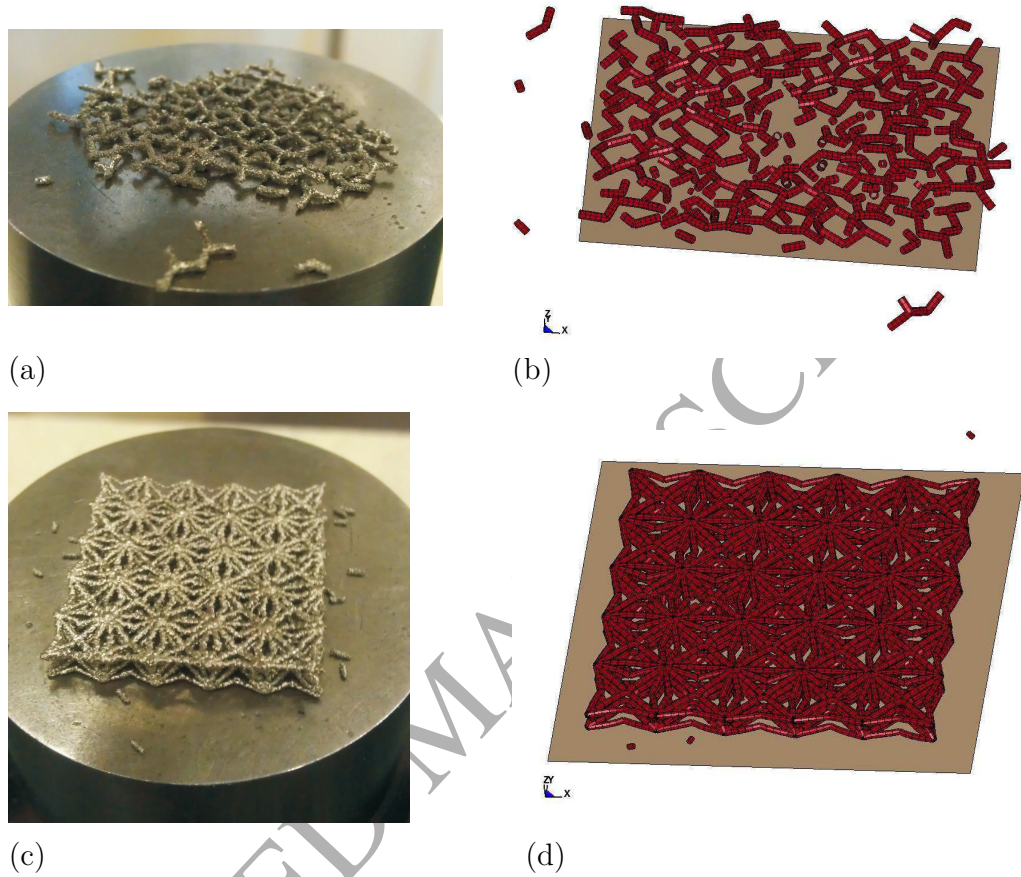


Figure 5: Deformed shape of diamond sample during quasi-static (a) experiment and (b) numerical simulation. Deformed shape of re-entrant cube sample during quasi-static (c) experiment and (d) numerical simulation. The pre-test sample sizes were 25 x 25 x 5 mm.

334 4. Nonlinear impact response of lattices

335 The HPB tests carried out with bare impactor and on single and multi-
 336 layer lattice samples are described in detail in (Ozdemir et al., 2016). In the
 337 present work, these test results are utilized to develop an effective modelling

338 tool using the FEM for the prediction of the mechanical behaviour, progres-
339 sive damage and failure modes of the lattices. The same material models
340 and material parameters defined in Section 3 are utilized in the numerical
341 impact models as validated with quasi-static tests.

342 *4.1. Impact tests with bare impactor*

343 Numerical simulations of low and high velocity impact tests were first
344 carried out in the absence of the lattice specimen at the impact face of the
345 HPB in order to verify the numerical models of the impactors. The steel and
346 Nylon 66 impactors were fired at velocities of 7.6 m/s and 178 m/s during
347 experiments, respectively, to transmit the same order of magnitude of impulse
348 (around 6 Ns).

349 The experimental and numerical stress-time histories observed at the
350 gauge station positioned 250 mm from the impact face of the HPB along
351 with cumulative impulse-time histories are given in Figures 6 and 7. Al-
352 though the numerical model predicts a higher peak stress than experiments
353 for both low-velocity and high-velocity impacts, durations of the experimen-
354 tal and numerical main impact pulses are virtually the same. In experimental
355 work, it is inevitable that a less-than-perfect alignment will be achieved be-
356 tween the impactor and the HPB. As a result, not all of the momentum of
357 the impactor is transferred to the HPB in the first cycle of the stress wave
358 through the length of the impactor. This results in an initial load plateau
359 which is lower than would be assumed from 1-D theory and a subsequent
360 low-magnitude coda to the main pulse which accounts for the majority of
361 the residual impulse. These features are clearly seen on the experimental

362 stress-time history shown in Figure 6(a). On the other hand, the numerical
 363 model assumes that the impact surfaces of the impactor and the HPB are
 364 perfectly parallel, and as a result the coda is not observed in the numerical
 365 stress-time history. Impulse starts to increase when the impactor comes into
 366 contact with the HPB and remains unchanged following the rebound of the
 367 impactor (Figure 6(b)). Cumulative impulse-time histories suggest that re-
 368 bound velocity of the impactors in the numerical simulation is higher than
 369 that observed in experiments.

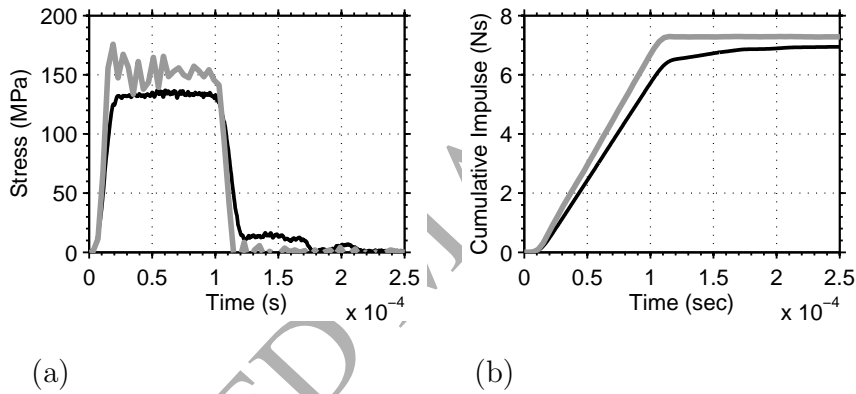


Figure 6: Experimental (black line) and numerical (grey line) (a) stress and (b) cumulative impulse-time histories in the absence of lattice specimen generated by the steel impactor fired at a velocity of 7.6 m/s.

370 4.2. Impact response of single layer specimens

371 Examples of experimental and numerical impact stress, cumulative im-
 372 pulse and strain time histories as well as stress-strain curves developed on
 373 the distal and impact face of single-layer re-entrant cube specimens induced

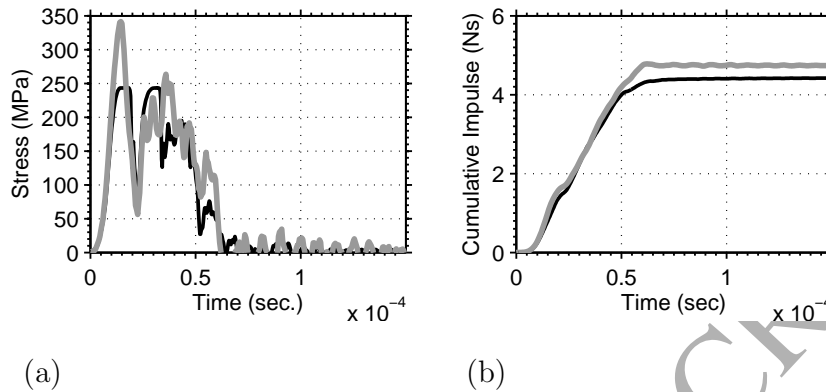


Figure 7: Experimental (black line) and numerical (grey line) (a) stress and (b) cumulative impulse-time histories in the absence of lattice specimen generated by the Nylon 66 impactor fired at a velocity of 178 m/s.

374 by the steel impactor are shown in Figures 8 and 9, respectively. In these
 375 tests, the average strain rate is around 3700 s^{-1} and 3600 s^{-1} , respectively.
 376 Figures 8(a) and 9(a) show examples of a good agreement between simulated
 377 and measured stress-time histories. Strain developed in the samples was not
 378 measured directly during the experiments. Therefore, the high speed video
 379 footage was used to estimate the displacement vs time record of the impacted
 380 face, from which the axial strain-time history was calculated. Subsequently,
 381 a stress-strain curve was derived for each test.

382 Numerical distal and impact face stress, cumulative impulse and strain
 383 time histories as well as stress-strain curves induced by the Nylon 66 im-
 384 pactor fired at velocities of 200 m/s and 187 m/s are shown in Figures 10 and
 385 11, respectively. The average strain rate is around 42400 s^{-1} and 26000 s^{-1} ,
 386 respectively, in these tests. Experimental stress and cumulative impulse-time

387 histories are also superimposed in Figures 10(a), 10(b), 11(a) and 11(b). The
388 resolution of the high speed video footage of high speed impact tests was not
389 sufficient to estimate the displacement time histories of samples under high
390 strain rates; strain vs time and stress vs strain curves for these samples could
391 not be predicted. As one can observe from Figures 10(a), 10(b), 11(a) and
392 11(b), the stress and cumulative impulse-time histories obtained from ex-
393 perimental and numerical methods show a very good agreement for the first
394 $5.5 \cdot 10^{-5}$ s. After $5.5 \cdot 10^{-5}$ s, the numerical results deviate from the exper-
395 imental results. Comparison of the experimental and numerical cumulative
396 impulse graphs given in Figures 10(b) and 11(b) shows that the numerical
397 method predicts a higher rebound velocity for the Nylon 66 impactor than
398 occurred in the experiment. This suggests that the difference between ex-
399 perimental and numerical stress-time histories for the high velocity impact
400 tests (Figures 10(a) and 11(a)) is caused by the non-linear deformations of
401 the Nylon 66 impactor, since an elastic-perfectly plastic material model for
402 the impactor is used in the numerical simulations. Therefore, in reality, some
403 part of the energy remaining in the system is dissipated by the fracture of
404 the impactor, whereas, in the numerical models, this energy remains in the
405 impactor and it rebounds with a higher velocity. This shows that we have
406 captured the essentials in the stress-time lattice behaviour; late time differ-
407 ences caused by the fracture of the experimental impactor are of secondary
408 importance and the lattice behaviour is modelled correctly.

409 The impact stress, cumulative impulse and strain time histories of two
410 distal face impact tests (steel impactor at low speed, Nylon 66 impactor at
411 high speed) differ significantly (Figures 12(a) - (c)). On the other hand, the

412 stress-strain curves of single-layer samples under low and high velocity loads
413 strongly suggest that there is little difference in the distal face stress vs overall
414 specimen strain at loading rates differing by an order of magnitude (Figure
415 12(d)). Therefore, we can conclude that distal face stress-strain response
416 of single-layer re-entrant cube samples exhibits rate insensitive behaviour.
417 Similar observations can be made for the impact stress, cumulative impulse
418 and strain time histories of two impact face impact tests under low and
419 high velocity loads (Figures 13(a) - (c)). However, the discrepancy between
420 numerical stress vs strain curves under low and high velocity loads increases
421 for impact face tests (Figure 13(d)).

422 *4.3. Impact response of five-layer specimens*

423 Impact tests on five-layer lattice samples of the same diameter as the
424 impactor were conducted to establish the ability of the lattices to extend the
425 duration of the impact load and to reduce peak response (Ozdemir et al.,
426 2016).

427 *4.3.1. Diamond lattices*

428 Examples of experimental and numerical distal face stress and cumulative
429 impulse-time histories developed on the five-layer diamond lattices during low
430 and high velocity impact tests are shown in Figures 14 and 15. In the case
431 of the lower velocity impact, there is excellent correlation between the ex-
432 perimental and numerical results. The stress-time correlation is less good for
433 the higher velocity impact, with the early time experimental stress being 10-
434 15% higher than that predicted by the model, and the final peak associated

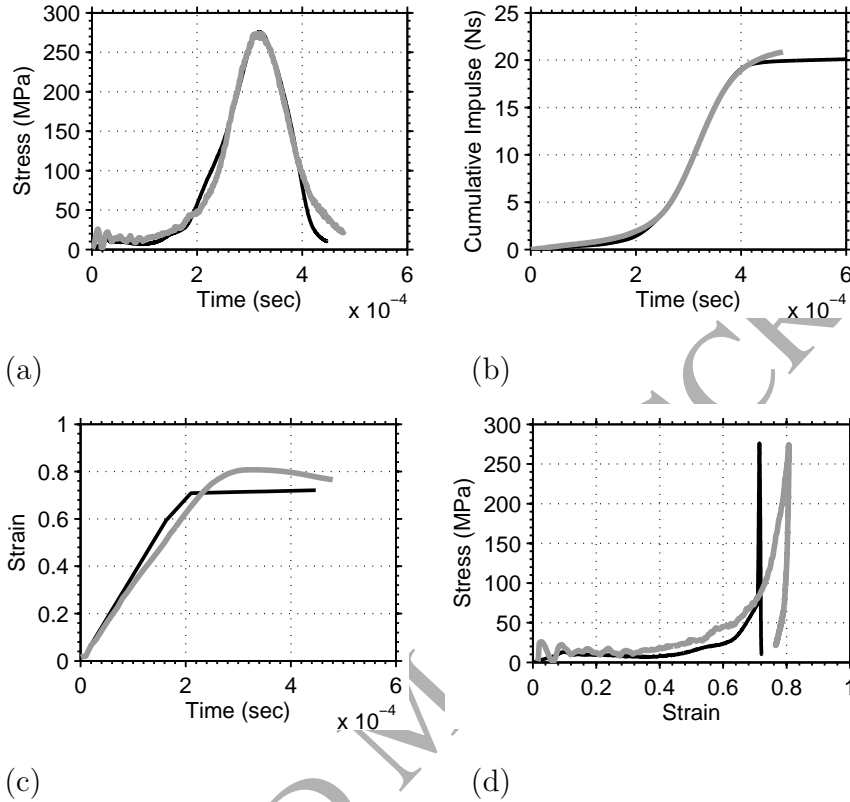


Figure 8: Experimental (black line) and numerical (grey line) distal face (a) stress, (b) cumulative impulse and (c) strain time histories, and (d) stress-strain curve of the single layer re-entrant cube lattice specimen induced by the steel impactor fired at a velocity of 18.8 m/s.

435 with full densification of the sample and final transfer of the residual mo-
 436 mentum from the impactor being higher in the numerical model. However,
 437 the experimental and numerical final cumulative impulse results show good
 438 correspondence in both cases. This indicates that local fluctuations in the

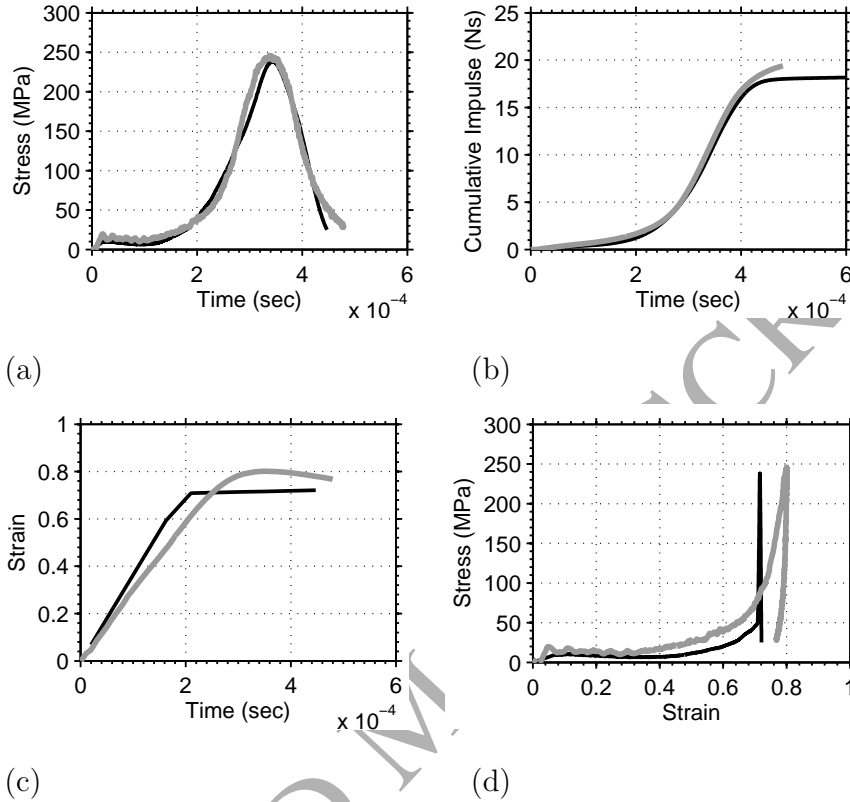


Figure 9: Experimental (black line) and numerical (grey line) impact face (a) stress, (b) cumulative impulse and (c) strain time histories, and (d) stress-strain curve of the single layer re-entrant cube lattice specimen induced by the steel impactor fired at a velocity of 17.7 m/s.

439 stress-time histories average themselves out.

440 Figure 16 shows numerical and experimental impact face stress vs time
 441 and cumulative impulse vs time plots of five-layer diamond lattice induced
 442 by the Nylon 66 projectile. The discrepancies between experimental and

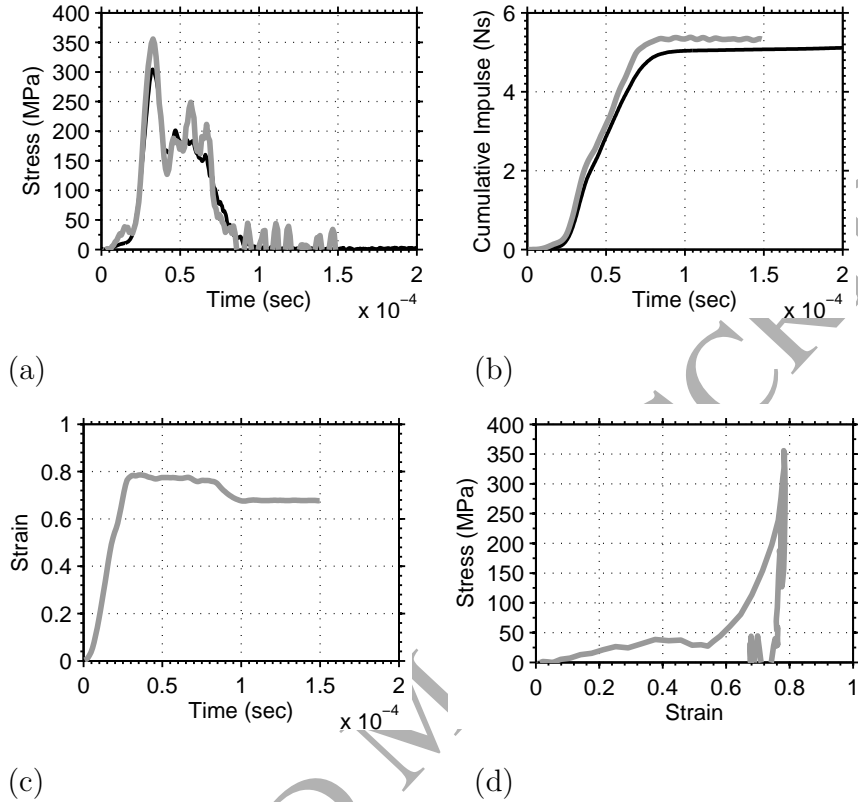


Figure 10: Experimental (black line) and numerical (grey line) distal face (a) stress, (b) cumulative impulse and (c) strain time histories, and (d) stress-strain curve of the single layer re-entrant cube lattice specimen induced by the Nylon 66 impactor fired at a velocity of 200 m/s.

443 numerical stress time histories can also be observed for impact face high
 444 velocity loads. However, the experimental and numerical cumulative impulse
 445 time histories show a good correlation for both cases.

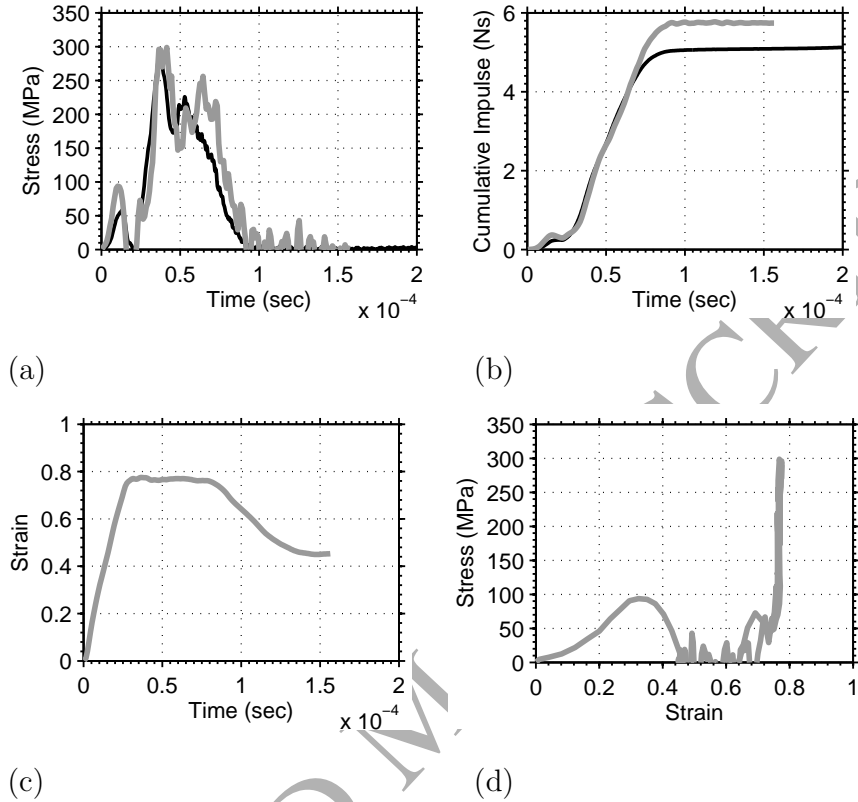


Figure 11: Experimental (black line) and numerical (grey line) impact face (a) stress, (b) cumulative impulse and (c) strain time histories, and (d) stress-strain curve of the single layer re-entrant cube lattice specimen induced by the Nylon 66 impactor fired at a velocity of 187 m/s.

446 4.3.2. Re-entrant cube lattices

447 Figures 17 -20 show numerical and experimental distal and impact face
 448 stress vs time and cumulative impulse vs time plots of five-layer re-entrant
 449 cube lattices induced by the steel and Nylon 66 projectiles. Numerical simu-

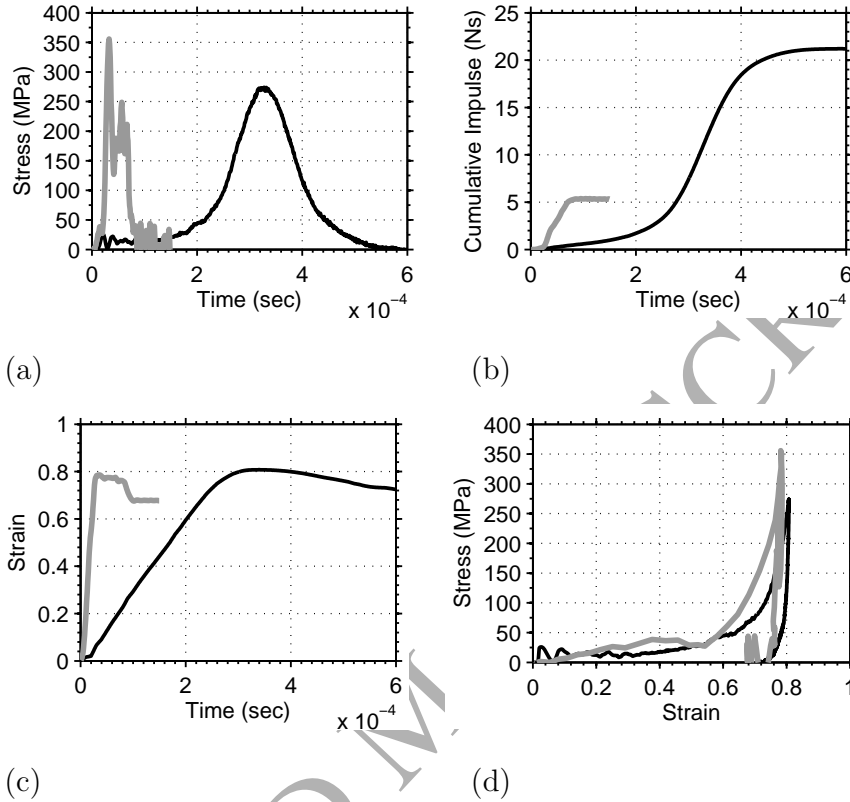


Figure 12: Numerical distal face (a) stress, (b) cumulative impulse and (c) strain time histories, and (d) stress-strain curves of the single layer re-entrant cube lattice specimens induced by the steel (black line) and Nylon 66 (grey line) impactors fired at velocities of 18.8 and 200 m/s, respectively.

450 lations can reasonably well predict the response of lattices under low velocity
 451 impact loads, while high frequency oscillations are observed both in the nu-
 452 merical plateau and the densification regime during high velocity impact
 453 tests, especially on the distal face.

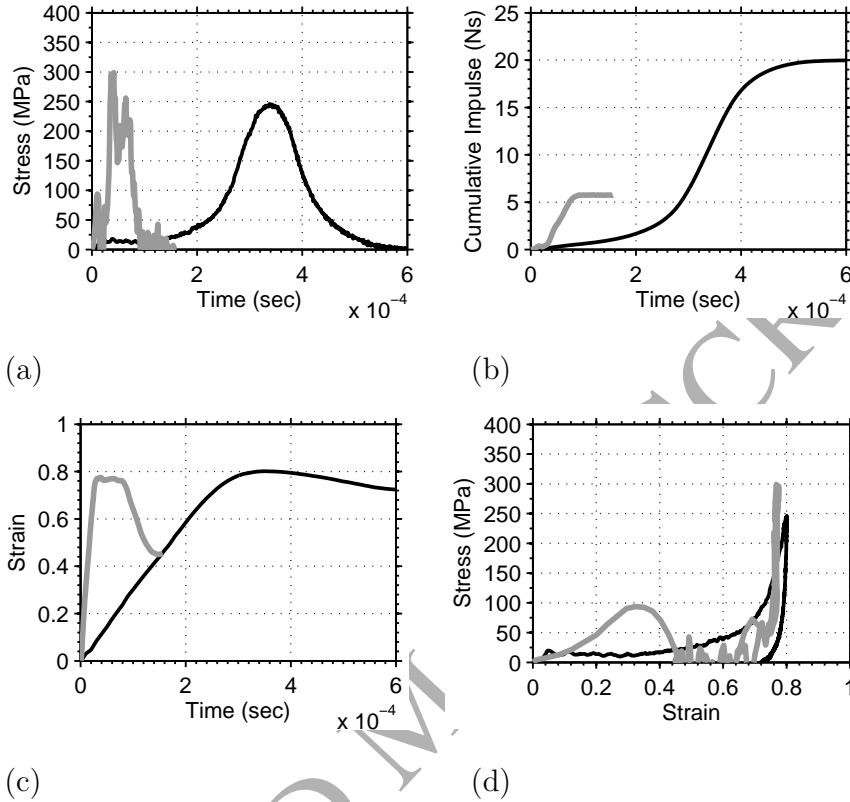


Figure 13: Numerical impact face (a) stress, (b) cumulative impulse and (c) strain time histories, and (d) stress-strain curves of the single layer re-entrant cube lattice specimens induced by the steel (black line) and Nylon 66 (grey line) impactors fired at velocities of 18.8 and 200 m/s, respectively.

454 As noted previously, the numerical model assumes perfectly co-axial and
 455 normal impact. This will inevitably lead to a faster rise time of the load,
 456 and hence, more significant high frequency content in the load-time signal.
 457 This may be the source of the high frequency oscillations in the early stages

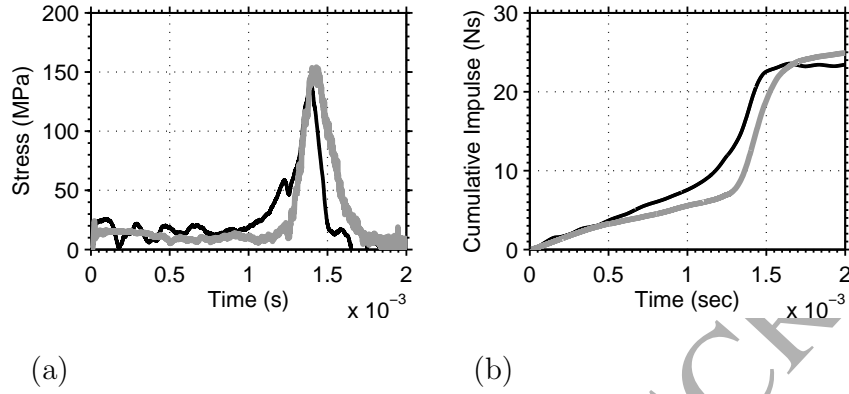


Figure 14: Experimental (black line) and numerical (grey line) distal face (a) stress and (b) cumulative impulse-time histories of the five-layer diamond lattice specimen induced by the steel impactor fired at a velocity of 19.4 m/s.

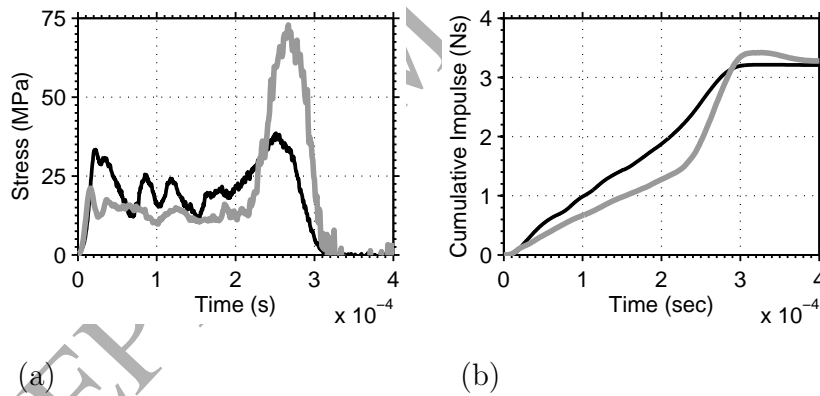


Figure 15: Experimental (black line) and numerical (grey line) distal face (a) stress and (b) cumulative impulse-time histories of the five-layer diamond lattice specimen induced by the Nylon 66 impactor fired at a velocity of 140 m/s.

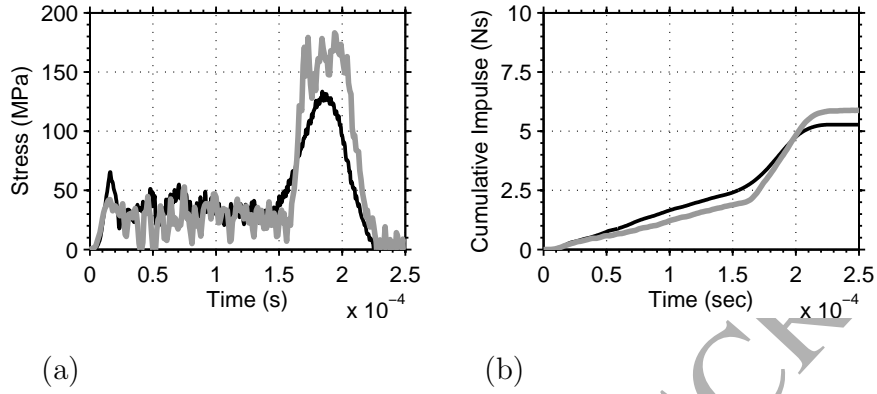


Figure 16: Experimental (black line) and numerical (grey line) impact face (a) stress and (b) cumulative impulse-time histories of the five-layer diamond lattice specimen induced by the Nylon 66 impactor fired at a velocity of 165 m/s.

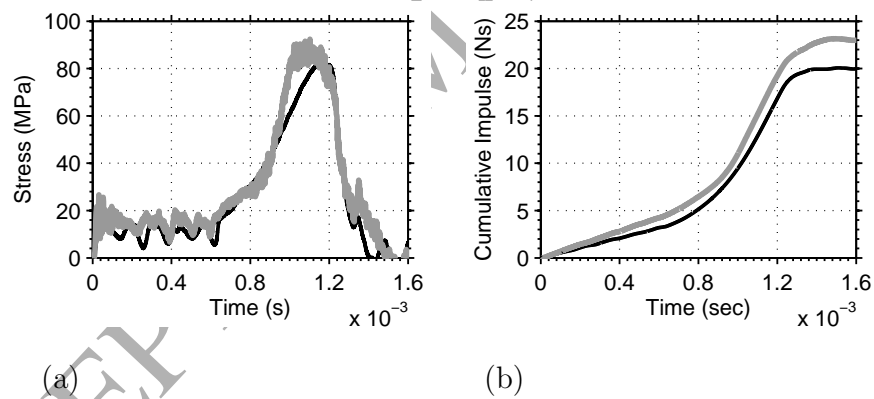


Figure 17: Experimental (black line) and numerical (grey line) distal face (a) stress and (b) cumulative impulse-time histories of the five-layer re-entrant cube lattice specimen induced by the steel impactor fired at a velocity of 16.8 m/s.

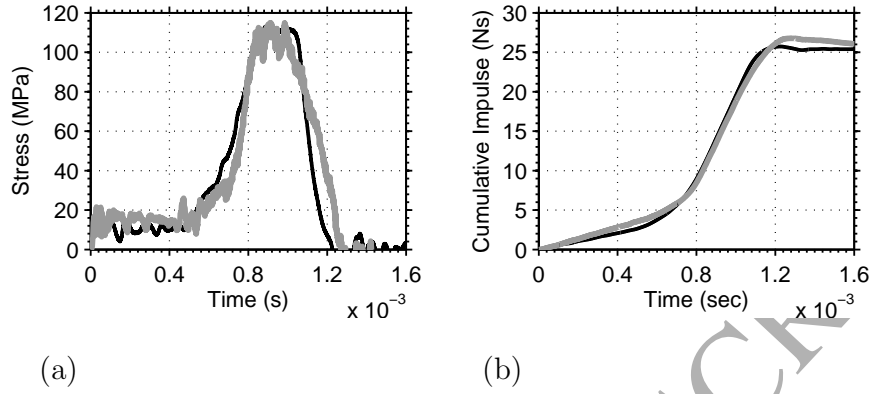


Figure 18: Experimental (black line) and numerical (grey line) impact face (a) stress and (b) cumulative impulse-time histories of the five-layer re-entrant cube lattice specimen induced by the steel impactor fired at a velocity of 20.3 m/s.

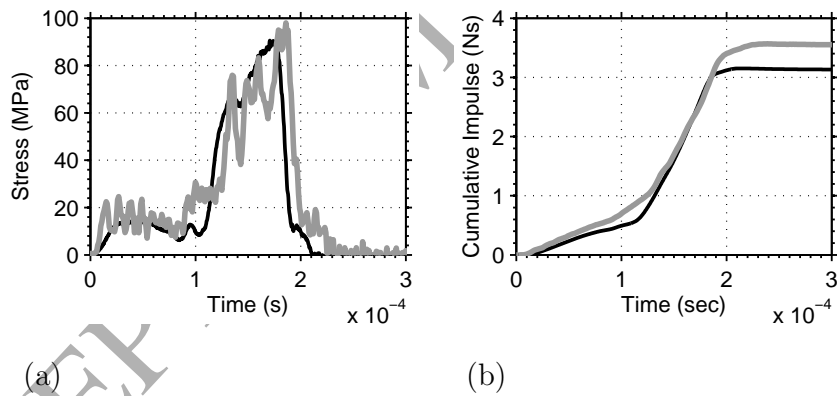


Figure 19: Experimental (black line) and numerical (grey line) distal face (a) stress and (b) cumulative impulse-time histories of the five-layer re-entrant cube lattice specimen induced by the Nylon 66 impactor fired at a velocity of 134 m/s.

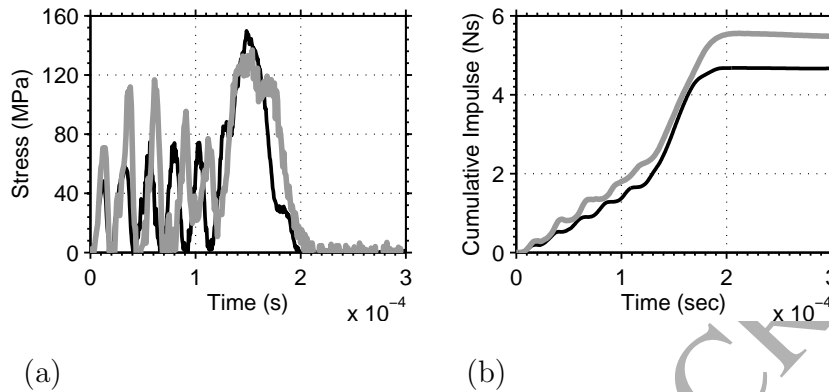


Figure 20: Experimental (black line) and numerical (grey line) impact face (a) stress and (b) cumulative impulse-time histories of the five-layer re-entrant cube lattice specimen induced by the Nylon 66 impactor fired at a velocity of 136 m/s.

458 of the numerical signal in Figure 19(a). To assess the correlation between
 459 the experimental and numerical loads without this high frequency content,
 460 filtering was applied to the signals. An example of filtered experimental and
 461 numerical results using a low-pass filter with a cut-off frequency of 60000
 462 Hz is shown in Figure 21, which is the filtered counterpart of Figure 19.
 463 The consistency of numerical and experimental results is improved by the
 464 elimination of very high frequency oscillations in the stress-time history. High
 465 frequency oscillations, which still exist in the numerical stress-time history
 466 after filtering, may be associated with the uncertainties in the material model
 467 of the Nylon 66 impactor.

468 In general, during impact tests, the specimen stress-time curve comprises
 469 a reasonably constant plateau load during cell collapse, followed by a much
 470 greater magnitude stress spike towards the end of the pulse (densification).

471 For low velocity impact tests, plateau load recorded during distal face and
472 impact face tests have very similar values. However, for higher velocity im-
473 pact tests, the impact face plateau stress is remarkably higher than distal
474 face plateau stress. Similar observation was made by Liu et al. (2009) who
475 reported the dynamic crushing behaviour of 2D Voronoi honeycombs at sup-
476 port and impact ends.

477 Both experiments and the FEM exhibit similar failure modes of re-entrant
478 cube lattices for low and high velocity HPB tests. In the lower velocity (steel
479 impactor) tests, the order of failure of the individual cell layers is random.
480 This implies a slowly applied impact load is equilibrated along the entire
481 length of the specimen and the order of cell layer collapse is governed by
482 the strength discrepancies between layers due to the imperfect geometry of
483 the struts along the length. Similar behaviour has been noted in the initial
484 crushing of hexagonally-packed rectangular arrays of thin-walled metal tubes
485 under quasi-static loads, which was localized in a narrow band (Shim and
486 Stronge, 1986). The random location of this band was attributed to the lo-
487 cal imperfections or weaknesses in the array. The higher velocity (Nylon 66
488 impactor) tests show that the failure of cell layers occurs sequentially from
489 impact face to distal face as the deformation is localised. This indicates that
490 equilibrium of load throughout the length of the specimen is not established
491 at these higher velocities. This response is very similar to dynamic crush-
492 ing behaviour of square-packed array in which propagates from the impact
493 surface into the undeformed array. In hexagonally-packed arrays, dynamic
494 crushing propagates from both the impact and distal ends (Stronge and Shim,
495 1987).

496 We have clear evidence of our layered system behaving as previous re-
 497 searchers have noted for other layered systems - layers failing in order of
 498 weakness at low impact velocities, layers failing in order of distance from
 499 impact face at high velocities as the deformation is localised (see for instance
 500 Figures 20 and 21 in (Ozdemir et al., 2016)).

501 Considering the difference in impact velocity from test to test, the im-
 502 pact and distal face stress-time histories from both the low-velocity and
 503 high-velocity impact tests demonstrate that diamond lattices appear to be
 504 marginally more efficient in temporally spreading the intensity of impact and
 505 reducing peak load than re-entrant cube lattices, even though re-entrant cube
 506 trusses have a higher relative density than diamond lattices.

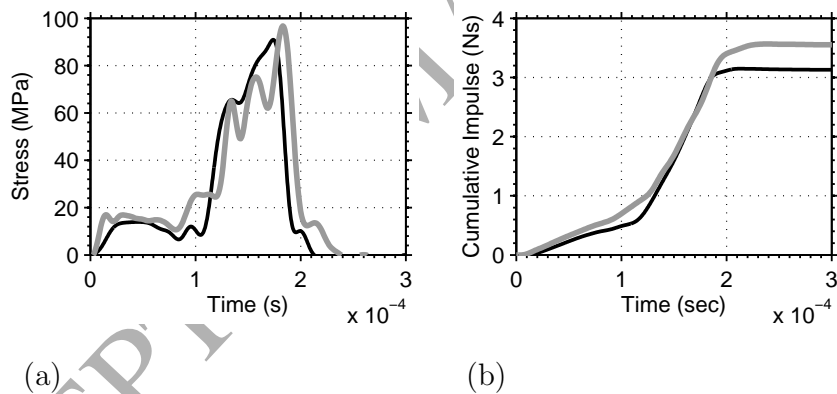


Figure 21: Experimental (black line) and numerical (grey line) filtered distal face (a) stress and (b) cumulative impulse-time histories of the five-layer re-entrant cube lattice specimen induced by the Nylon 66 impactor fired at a velocity of 134 m/s.

507 **5. Influence of intrinsic strain rate sensitivity of Ti6Al4V**

508 In the previous numerical analyses, the intrinsic strain rate dependence
 509 of Ti6Al4V is ignored in the constitutive model. The Johnson-Cook material
 510 model captures strain hardening and strain rate sensitivity of a material by
 511 expressing stress as a function of strain and strain rate:

$$\sigma = (A + B \varepsilon^n) \left(1 + C \ln \left(\frac{\dot{\varepsilon}}{\dot{\varepsilon}_0} \right) \right) \quad (1)$$

512 where σ is the stress, ε is the plastic strain, $\dot{\varepsilon}_0$ is a reference strain rate
 513 equal to 1 s^{-1} , $\dot{\varepsilon}$ is the effective plastic strain rate, A is the yield stress, the
 514 combination of B and n governs the hardening behaviour of the material, and
 515 C represents the strain rate sensitivity of the material. In this formulation
 516 temperature effects are ignored.

517 The influence of intrinsic rate dependency of Ti6Al4V on the impact re-
 518 sponse of single and multi-layer re-entrant cube lattice samples is assessed
 519 by using different C values in the numerical simulations. A realistic value
 520 of strain rate sensitivity parameter C for Ti6AL4V is reported to be on av-
 521 erage 0.022 (Shao et al. (2010) and US-DOT-FAA (2000)). In addition to
 522 this realistic value, an extremely (and unrealistically) high value of $C = 0.1$
 523 is also assumed and simulation results are compared with those of strain
 524 rate insensitive material model. Plots in Figure 22 show a comparison for
 525 distal face stress-time histories of the single and multi-layer re-entrant cube
 526 lattice specimens developed during low and high velocity impact tests. As
 527 can be seen from this figure, the realistic value of intrinsic strain rate sen-
 528 sitivity of the Ti6Al4V only very slightly affects the response of the single

529 and multi-layer re-entrant cube lattice samples. Even with such an unreal-
530 istically high value of $C = 0.1$, it is not possible to emulate the response
531 of five-layer samples with a one-layer sample. This suggests that the rate-
532 dependent behaviour that emerges at the macro-scopic level is *not* due to
533 the rate-dependence of the Ti6Al4V alloy, but rather due to the interaction
534 of stiffness and inertia at the unit cell level which can thus be adjusted and
535 optimised according to user-defined performance requirements. The hypoth-
536 esis regarding the source of rate-sensitivity of lattices needs further detailed
537 investigations on numerical models of lattices in a future work. Liu et al.
538 (2009) drawn similar conclusions in relation to the strain-rate sensitivity of
539 2D Voronoi honeycomb stating that the strain-rate sensitivity of cell wall
540 material has minor effect on the dynamic response of such materials; rate
541 effect is mainly caused by inertia. have also reached similar conclusions in
542 their numerical study

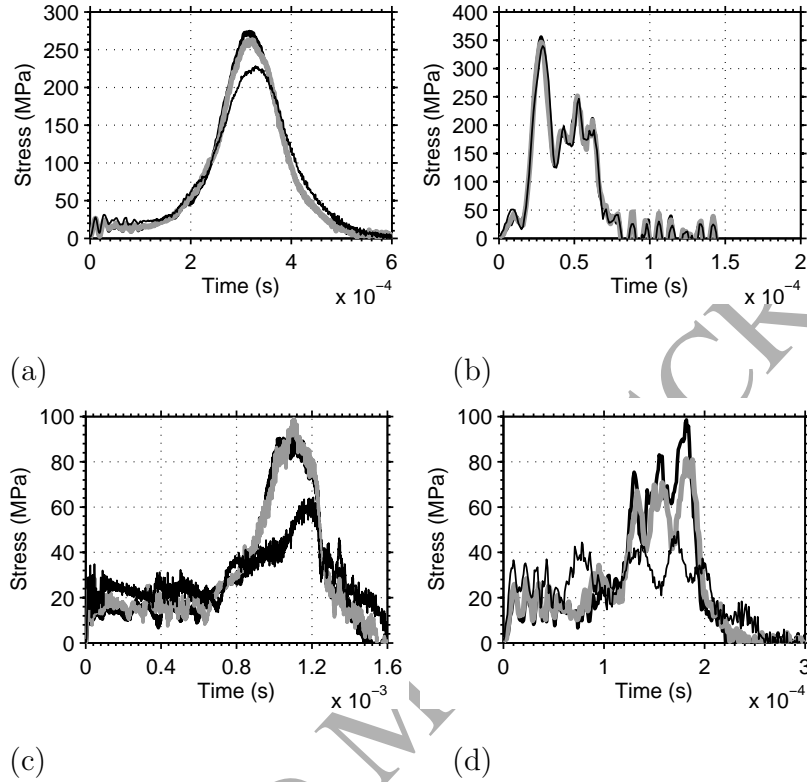


Figure 22: Distal face stress-time histories of (a) the single layer re-entrant cube lattice specimen induced by the steel impactor fired at a velocity of 18.8 m/s, (b) the single layer re-entrant cube lattice specimen induced by the Nylon 66 impactor fired at a velocity of 200 m/s, (c) the five-layer re-entrant cube lattice specimen induced by the steel impactor fired at a velocity of 16.8 m/s, and (d) the five-layer re-entrant cube lattice specimen induced by the Nylon 66 impactor fired at a velocity of 136 m/s for strain rate insensitive material model (thick black line), Johnson-Cook material model with $C=0.02$ (grey line) and $C=0.1$ (thin black line).

543 6. Effect of confinement

544 In the previous analyses, the impact behaviour of the lattice samples are
545 numerically simulated under uniaxial loading conditions without radial con-
546 straint. Next, specimens are constrained against radial expansion by placing
547 them inside a frictionless circular steel tube with a clearance fit, therefore,
548 uniaxial straining of the samples is achieved. All other test parameters are
549 the same as in Section 4. It is clear from Figure 23 that lateral confinement
550 slightly affects the compressive response of re-entrant cube lattices for both
551 low and high velocity impact tests. This is also consistent with the Poisson
552 ratio of the re-entrant cube lattices which is near zero or negative (Almgren
553 (1985)). The failure of the re-entrant lattice occurs in a systematic, layer-by-
554 layer fashion, so confinement does not substantially affect the compressive
555 stress of such lattices. However, a lattice specimen with a different mode of
556 collapse should be assessed to quantify the influence of the confinement on
557 the response of the structure.

558 Similar conclusions have been reached for different foam types under
559 quasi-static conditions. Radford et al. (2005) evaluated the effect of lat-
560 eral confinement on Alporas foam and only a small effect on the compression
561 response was observed. This was attributed to the fact that the Alporas foam
562 has a plastic Poisson ratio close to zero. Tan et al. (2005) radially confined
563 Hydro/Cymat3 foam specimens and proposed that the radial confinement
564 had little effect in the pre-densification regime.

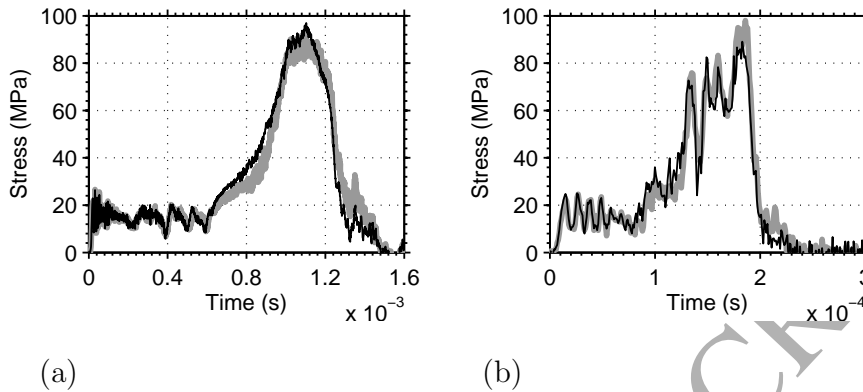


Figure 23: Numerical unconfined (grey line) and confined (black line) distal face stress-time histories of five-layer re-entrant cube lattice specimens induced by (a) the steel impactor fired at a velocity of 16.8 m/s and (b) the Nylon 66 impactor fired at a velocity of 134 m/s.

565 7. Discussion

566 Numerical simulations carried out in this work demonstrate that the FEM
 567 is an efficient analysis tool for the prediction of the mechanical behaviour,
 568 progressive damage and failure modes of lattice materials. Considering dis-
 569 advantages associated with continuum elements, 3D Timoshenko beam ele-
 570 ments with appropriate contact properties were preferred for the modelling
 571 of lattice materials. Comparison of experimental and numerical results reveal
 572 that quasi-static and impact response of lattices with 3D Timoshenko beam
 573 elements is represented with high accuracy including individual collapse of
 574 cell layers and densification. This led to a drastic reduction in the total
 575 number of elements and degrees of freedom and, in turn, CPU time. On the
 576 other hand, practical design tools are vital for early stage of design due to
 577 the computational expense of the numerical methods. It is highly beneficial

578 to have a simplified model of lattice structures for generic assessment/design
579 purposes in addition to a numerical tool.

580 A short review on the quasi-static deformation mechanisms of stretch
581 dominated and bending dominated structures may help to explore the rate-
582 sensitivity mechanism of lattices for future works . Most foams show a bend-
583 ing dominated behaviour, whereas lattice structures demonstrate a stretch
584 dominated behaviour. Stiffnesses and initial collapse strengths of stretch
585 dominated structures are higher than those of bending dominated structures
586 of the same relative density, since the deformation mechanisms of stretch
587 dominated structures are characterized by hard response modes like tension
588 and compression rather than soft failure modes like bending. In stretch dom-
589 inated response, initial yield of the material is followed by a post-yield soft-
590 ening stiffness caused by plastic buckling or brittle collapse of struts, whereas
591 bending dominated structures continue to collapse at a nearly constant stress.
592 Because of this, the energy absorption capacity of stretch dominated struc-
593 tures is less than that of bending dominated structures, although they are
594 lighter Ashby (2006). Under dynamic loading, the collapse mode of cellular
595 solids may change from a quasi-static failure mode to new mode involving
596 additional stretching which can dissipate more energy. This phenomenon is
597 called as micro-inertia which can cause an increase in the strength of cellu-
598 lar solids under dynamic loading conditions in addition to inertia and shock
599 wave propagation effects Deshpande and Fleck (2000). Bending dominated
600 structures are slightly affected by micro-inertia, strain-rate and inertia effects
601 under dynamic conditions Calladine and English (1984).

602 Impact tests on single-layer re-entrant cube samples explained in Section

603 4.2 strongly suggest that the distal face stress-strain curves of single-layer re-
 604 entrant cube samples exhibit little difference at loading rates even differing by
 605 an order of magnitude (Figure 12(d)), while five-layer samples under low and
 606 high velocity impact loads exhibit load rate sensitive behaviour (Figure 24).
 607 These results imply that a rate-independent load-deflection model of the unit
 608 cell re-entrant cube layers could be used in a simple multi degree of freedom
 609 (MDoF) model of a multi-layer specimen to represent its impact behaviour.
 610 A simple 1-D MDoF spring-mass model can therefore be developed, using
 611 lumped masses representing the inertia of each unit cell layer. The stiffness
 612 of each layer can be represented with a rate-independent stress-strain curve
 613 based on the data in Figure 12(d).

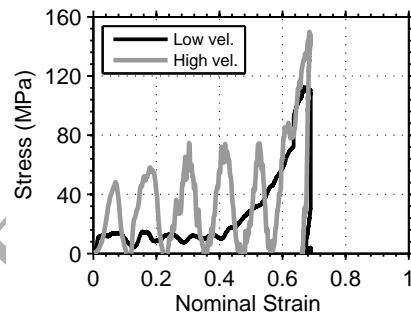


Figure 24: Numerical impact face stress-time histories of the five-layer re-entrant cube lattice specimen induced by the steel (black line) and Nylon 66 (grey line) impactors fired at velocities of 20.3 and 136 m/s, respectively

614 Regular periodic morphologies of lattice structures allow us to use such
 615 simple spring mass systems for representing their impact response. There-
 616 fore, we can specifically design 1-D layered systems for lattices to optimise

617 load spreading ability. However, the heterogeneous nature of foamed metals
618 complicates the development of such simplified models for representing dy-
619 namic behaviour of metallic foams under high-strain rates. **But, there will be**
620 **certain restrictions in adopting an MDoF model: a physical justification for**
621 **spring geometry can only follow from cell dimensions, and such a restrictive**
622 **choice of parameters may limit the MDoF model's capability to provide the**
623 **spatial resolution required for dynamic response capture.**

624 A MDoF spring-mass model for multi-layer re-entrant cube samples is also
625 consistent with the form of failure of such lattices. However, the efficiency of
626 a similar MDoF system of another lattice type with a different mode of col-
627 lapse should be elaborated carefully. In a future work, simplified design tools
628 for lattices for impact threats will be studied in more detail. The relative ac-
629 curacy by which multi-layer lattice structures can be modelled with a simple
630 MDOF model raises the question to what extent the dynamic behaviour of
631 lattice structures can be homogenised, and whether a homogenised model is
632 able to capture the essential characteristics of localisation.

633 8. Conclusions

634 This work focuses, for the first time, on the development of simple FE
635 models of diamond and re-entrant cube lattices for the characterisation of
636 dynamic response of such materials. The FE models of lattices are built
637 using 3D Timoshenko beam elements. The results of the previous extensive
638 experimental study (Ozdemir et al., 2016) are utilized to collect more data on
639 the quasi-static and impact behaviour of titanium alloy (Ti6Al4V) lattices.
640 Numerical analysis results show that 3D Timoshenko beam elements with

641 appropriate contact properties are able to represent quasi-static and impact
642 response of lattices with enough accuracy including individual collapse of cell
643 layers and densification. Therefore, the FEM can be used an efficient tool for
644 the prediction of the mechanical behaviour, progressive damage and failure
645 modes of the lattice structures. Numerical impact analysis also reveals that
646 intrinsic strain rate dependence of the Ti6Al4V cannot cause any emergent
647 rate dependence of the response of the re-entrant cube lattices.

648 There is also some evidence that, whilst re-entrant cube specimens made
649 up over multiple layers of unit cells are load rate sensitive, the mechanical
650 properties of individual lattice cell layers are relatively insensitive to load
651 rate. These results imply that a rate-independent load-deflection model of
652 the unit cell layers could be used in a simple MDoF model of a multi-layer
653 specimen to represent its impact behaviour. In a future contribution, we will
654 focus on development of a simplified design tool of the lattices for impact
655 threats. In addition, a more realistic material model will be used for Nylon
656 66 impactor and imperfections of lattices will be included in the numerical
657 models in a future numerical modelling work.

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