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1 **An integrated geophysical approach for investigating**
2 **hydro-geological characteristics of a debris landslide in the**
3 **Wenchuan Earthquake Area**

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35 **An integrated geophysical approach for investigating hydro-geological**
36 **characteristics of a debris landslide in the Wenchuan Earthquake Area**

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38 **ABSTRACT** Debris landslides are one of the most widely distributed types of landslides in the
39 Wenchuan earthquake area. The hydro-geological structure characteristics are the fundamental
40 basis for stability evaluation, performing protection and administration of a landslide. The rock
41 and soil mass of a debris landslide was highly non-uniform and preferential seepage paths were
42 normally developed in it. Therefore, in situ identification of the underground water seepage
43 system became particularly important. Recently, investigations on the seepage paths of
44 underground water in debris landslides were restricted to indoor model testing and site observation,
45 which were far from meeting the actual demand for landslide prevention and mitigation. To locate
46 the seepage paths, we conducted survey work on a debris landslide seated in the Xishan Village, Li
47 County, Sichuan Province, China, by combing four different geophysical methods. They were
48 multichannel analysis of surface wave (MASW), electrical resistivity tomography (ERT), ground
49 penetrating radar (GPR) and microtremor survey method (MSM). The geophysical interpretation
50 was verified with field engineering surveys and monitoring data. The results suggested that a
51 dendritic pipe-network seepage system usually developed in debris landslides. Varisized
52 infiltration pipes showed the characteristics of inhomogeneity and concentration of the seepage.
53 This work highlighted that geophysical parameters (shear wave velocity V_s , dielectric constant ϵ
54 and resistivity value ρ) could provide reliable qualitative and quantitative information about the
55 colluvial layer, bedrock interface, potential sliding surface and underground water seepage system
56 of a landslide. The optimum combination of geophysical methods was suitable to survey the
57 hydro-geological characteristics of debris landslides in the Wenchuan earthquake area.

58 **Keywords:** Hydro-geology; Pipe-network seepage system; Debris landslides; Geophysical
59 investigation; Wenchuan earthquake.

63 1. Introduction

64 The southeast edge of the Tibetan plateau was generated by the collision between the Indian
65 and the Eurasian plates, resulting in complex geological tectonics and a series of active large faults
66 (Kind et al., 2002). Since the self-Quaternary, especially the late Quaternary, these deep faults
67 have been very active where earthquakes had occurred frequently, such as the "5.12" Wenchuan
68 Ms 8.0 earthquake in 2008 and the "4.20" Lushan Ms 7.0 earthquake in 2013 on the Longmenshan
69 (LMS) fault belt (Wu et al., 2008; Liu et al., 2013) (Fig. 1 (a)). The destructive earthquakes
70 brought huge losses of lives and properties, and serious deformation and destruction of slopes
71 always accompanied the strong seismic inertia force. The potential safety problem in the
72 earthquake hit area will coexist with the local inhabitants for a long time.

73 Debris landslides are the most common landslide type in the Wenchuan earthquake area. A
74 soil can be named as gravel soil when the dry weight of particles over 2 mm exceeds 50% of the
75 total dry weight. In general, it is composed of a loose accumulation including artificial filled soil,
76 diluvium, collapsed soil, weathered rock material, etc. Shang et al. (2002) found by engineering
77 geological survey that underground water flow was a pipe-network discharge in a gravel clay
78 slope. Some spring water flowed out from the fissures among rubbles on the toe or back edge
79 scarp of a slope, particularly in the rainy season. The pipe-network drainage system was destroyed
80 or blocked when loading on the slope surface or excavation unloading at the foot of the slope. This
81 might lead to considerable increase in ground water level and pore water pressure in the slope
82 and cause instability of the slope, eventually (Xu et al., 2006; Yu et al., 2007; Sun et al., 2011).
83 Sensitive analysis of influence factors indicated that the main influence factors for the stability of
84 debris landslides were persistent rain, strong rainfall and surface runoff (He et al., 2005, Xu et al.,
85 2007a, 2008).

86 The pipe-network seepage system developed in debris landslides significantly influenced its
87 stability. The identification of seepage paths was very helpful for engineering mitigation of
88 landslides. Previous studies on pipe-network seepage systems were concentrated on indoor
89 physical and mechanical tests (Xu et al., 2006), model tests (Shang et al., 2005; Yu et al., 2007)
90 and numerical stimulation (Xu et al., 2007a, 2007b, 2008; Sun et al., 2011). However, literatures
91 about in situ identification of underground water seepage paths were very rare. Therefore, rapid

92 delineation of seepage paths in debris landslides was undoubtedly important for its stability
93 evaluation and selection of proper mitigation measures.

94 In the last two decades, geophysical methods were being increasingly applied to delineate
95 landslide structures, including internal geological structure, potential slip surface,
96 hydro-geological feature, movement characterisation, mechanical properties, etc. (Bogoslovsky
97 and Ogilvy, 1977; Bruno et al., 2000; Lapenna et al., 2005; Jongmans et al., 2009; Grandjean et al.,
98 2011; Torgoev et al., 2013). Compared with traditional techniques such as drilling, trenching and
99 tunnelling, geophysical techniques are flexible, relatively quick and deployable on landslides.
100 They are non-invasive to investigate a large volume. Jongmans et al. (2007) gave a detailed review
101 about recent applications of the main geophysical techniques on landslide characterization. They
102 presented the advantages and drawbacks of these techniques and explained the main reasons for
103 their relatively limited application to landslides. Even so, method-optimisation design, resolution
104 and penetration, and reliability of results on the landslide should still be discussed in our study.
105 Shear wave velocity (V_s) is sensitive to inhomogeneous media and interfaces. Therefore,
106 multichannel analysis of surface wave (MASW) is suitable to probe strata, weak intercalation,
107 structural planes and fracture zones in a shallow landslide (Meric et al., 2007; Jongmans et al.,
108 2009; Lima et al., 2012). Electrical resistivity (ρ) is a parameter used to provide information about
109 rupture surface, water content and conductivity, rock weathering and fracturing, as well as
110 water-saturated zones in a landslide (Lebourg et al., 2005; Marescot et al., 2008; Le Roux et al.,
111 2011). Ground penetrating radar (GPR) is a high resolution method, depending on the chosen
112 antennas, with a probing depth from a few centimetres to a few meters in resistive materials. It is
113 sensitive to dielectrics, magnetic contrast, fractures and especially water content, and was used
114 more in rock landslides (Bichler et al., 2004; Otto et al., 2006; Yamakawa et al., 2010). Moreover,
115 the microtremor survey method (MSM) developed in the last decade has no special requirement
116 for the environment because it acquires the structure of shear wave velocity from low frequency
117 vibration signals generated by human activities (Okada et al., 2003). The application of MSM was
118 then concentrated on the mapping of geothermal faults, collapsed columns in coal mines and
119 boulders along subway lines (Ling et al., 2006; Xu et al., 2009,2012). It was also expected to be
120 used in deep seated landslides (more than 50 m deep) investigations.

121 To delineate the in situ seepage paths in a debris landslide and build its hydro-geological
122 model for further research on numerical analysis and stability evaluation, this study attempted to
123 join four geophysical methods, MASW, ERT, GPR and MSM, to survey four profiles where
124 borehole data were available. The geophysical interpretation suggested that surface and
125 underground water drainage were major measures for the deformation control of a debris
126 landslide.

127 **2. Geological and geotechnical background**

128 **2.1 The study area**

129 The study area is located in Tonghua Town, Li County, Ngawa Tibetan and Qiang
130 Autonomous Prefecture, Sichuan Province, China. The Xishan village landslide (31°34'59.40",
131 103°25'30.99") is seated at the left bank of Zagunao River and nearby No.317 national highway.
132 The average altitude is about 2300 m with high mountains and deep valleys in the study area. Both
133 the Wenchuan Ms 8.0 earthquake in 2008 and the Lushan Ms 7.0 earthquake in 2013 occurred on
134 the Longmenshan fault system as shown in Fig. 1a. The landslide is 40 km away from the LMS
135 fault belt. Therefore, the structure of the slopes was strongly affected by the earthquakes, so that
136 there will be serious safety problems in this region for a few years to come.

137 The Xishan village landslide with thick overburden layers is a large retrogressive landslide
138 seated between the mountains as shown in Fig. 1b. The landslide is about 3800 m long with a
139 slope angle of 25°~45°. The minimum and maximum widths of it are 680 and 980 m,
140 respectively. The average thickness of the landslide mass is about 55 m. The difference in
141 altitude between the toe and the back edge of it is about 1790 m. The total volume of the
142 landslide is about $1.7 \times 10^8 \text{ m}^3$ (Luo 2015). The current local inhabitants living on the
143 landslide are about 724 from 211 households. The houses have been severely deformed and
144 damaged, and have even collapsed after the earthquakes. In addition, strong erosion to the toe
145 from the Zagunao River has increased the landslide deformation, and so many cracks, fallen trees
146 and collapses are being developed on the landslide, which indicates that persistent deformation of
147 the landslide is threatening to villager's lives and properties.

148 The geological stratum outcropping in the study area is the Maerkang sectional stratum
149 including Devonian system and Quaternary Holocene slope sediments. The underlying bedrock is

150 Devonian system composed of limestone, dolomite, phyllite, and even metamorphic quartz
151 sandstone and quartzite at the bottom (Fig. 2). The cover stratum consists mainly of Quaternary
152 colluvial deposit, gravel clay soil and gravel soil. The river terrace is Quaternary diluvium layer in
153 the front of the landslide. Exposed bedrock that appeared at the back edge and side wall of the
154 landslide was severely eroded with crushed rocks. Joint fissures and small developed faults were
155 obvious on the artificial excavation profiles.

156 **2.2 Engineering geological contexts**

157 The study selected a small landslide as a research object on the Xishan village landslide to
158 show the pipe-network seepage system in the debris landslide (Fig. 3a). The aim was to verify the
159 effect of the application of joint geophysical techniques on the landslide and discuss the optimum
160 combinations. On the other hand, we attempted to conduct a typical exemplary experiment using
161 multi-geophysical methods on this small landslide for further large scale investigation of the
162 Xishan village landslide. The back edge scarps, inclined trees, tensile cracks on the sidewalls (LF4
163 – LF7) and at the toe (LF8 – LF9) of the landslide were evident along with the landslide
164 deformation (Fig. 3b and 3c). The elevation difference of the small landslide was about 126 m
165 with a slope angle of 45° (Fig. 3a). Vegetation coverage in the front of the landslide was high due
166 to the numerous groundwater outcrops (Fig. 3d). Groundwater in the landslide mainly included
167 Quaternary loose deposits pore water and bedrock fissure water from alpine seasonal snowmelt,
168 domestic water and farmland irrigation water. Moreover, the maintenance of the drinking water
169 system in the village was so poor that a huge amount of water was flowing along the landslide
170 surface all year long to produce some water-rich zones in the landslide.

171 Human engineering activities, such as old house renovations and new house constructions,
172 posed great influences on the stability of the landslide after the earthquakes. Meanwhile, the
173 landslide was seriously excavated to build rural roads and drinking water system, which actually
174 increased the stability of the landslide with unloading (Fig. 4). On the other hand, the
175 pipe-network drainage system in the debris landslide was also damaged by the construction works.
176 Poor drainage enabled rise in the underground water level and decrease in shear strength of the
177 soil, which increased deformation of the landslide and threatened safety of the village. Therefore,
178 groundwater drainage became the main factor affecting the stability of this landslide.

179 According to the borehole data, shallow strata of the landslide from top to bottom are
180 Quaternary diluvium, gravel clay soil, gravel soil, strongly weathered phyllite, weathered phyllite
181 and phyllite bedrock. Bedrock outcrops on the surface were consistent with the previous
182 geological survey (Fig. 2). As shown in Fig. 5, average thickness of the Quaternary diluvium was
183 about 3.5 m, and thickness of the gravel soil was about 50 m on the longitudinal profile ZZ'.
184 Potential failure surface of the landslide was about 52 m in depth bounded by a 5.0 m thick strong
185 weathered phyllite layer with low shear strength, which facilitated further development of a deep
186 seated landslide.

187 In this study, we selected 4 geophysical surveying lines on the landslide to further learn about
188 the hydro-geological structure based on the previous site investigation. The shallow stratum
189 structure of the colluvial layer was surveyed using MASW and GPR. ERT was used to delineate
190 shallow water saturated zones and seepage paths in the landslide. Surveying lines for the GPR
191 method were P2 and P3, for the MASW method were P1, P2 and P3, and for the ERT method
192 were P1, P2, P3 and P4 (Fig. 3). MASW and GPR could not detect features at greater depth of the
193 debris landslide due to great attenuation of seismic and electromagnetic signals because of the
194 broken characteristics of gravel soil. However, MSM could be used to detect the degree of
195 weathering of bedrock and the rugged shape of the potential sliding surface with low frequency
196 microtremor (Ling et al., 2006; Xu et al., 2012).

197 Permeability of the shallow loose colluvial layer and gravel soil layer with large porosity was
198 high, so that the pipe-network drainage system played an important role in keeping its stability
199 (Shang et al., 2002; Xu et al., 2006; Yu et al., 2007). The interaction between the overburden layer
200 (Quaternary diluvium and gravel soil) and the weathered phyllite bedrock with high permeability
201 directly determined the stability of the longitudinal profile ZZ' in Fig. 5. Therefore, the evolution
202 of pipe-network seepage paths along depth in the landslide was extremely important for stability
203 evaluation of it.

204 **3. Methodology**

205 **3.1 MASW**

206 The MASW method was efficient at probing shallow subsurface structures with high
207 resolution using active sources. MASW was being increasingly applied to survey geological

208 structure, seismic microzonation, site response studies and geotechnical characterisation of near
209 surface materials (Park et al., 1999; Jongmans et al., 2009; Anbazhagan et al., 2011). Rayleigh
210 wave signals were collected using the layout of a single-ended excitation source and a receiving
211 system with geophones at equal spacing. Inversion dispersion curves were calculated using the
212 frequency-wavenumber (F-K) method to determine how shear wave velocity profiles varied with
213 depth. The investigation depth of MASW roughly corresponded to $V_s/3f$, and shear wave velocity
214 was sensitive to landslide deformation (Jongmans et al., 2009). This method was increasingly
215 applied in detecting 2D or 3D structures of landslides in recent years (Grandjean et al., 2011; Lima
216 et al., 2012).

217 The experimental device is an SE2404EI type engineering investigation instrument. The main
218 technical specifications are as follows: 24 data acquisition channels, sampling rate of 25 μ s – 10
219 ms, dynamic range over 131 dB, frequency band of 0.1 Hz – 5000 Hz, which meet the demand of
220 Rayleigh surface wave collection. The source is an artificial hammering source created by a 1.5 kg
221 sledge hammer on a steel plate with a diameter of 20 cm. The natural frequency of the geophone is
222 4.5 Hz. To effectively identify the Rayleigh surface wave record, we compared 2.0 m, 4.0 m and
223 6.0 m offsets, and ultimately selected the 6.0 m offset. According to the site condition, the
224 parameters used in our tests are as follows: sampling rate of 0.25 ms, 1024 sampling points, 24
225 channel detectors and 1.0 m track interval.

226 **3.2 ERT**

227 The resistivity value mainly depends on the mineral components, ground water and
228 electrolytes in the underground media. ERT applied direct current to shallow underground media,
229 and then the current flowing in conductive media was received by electrodes arranged along the
230 profile. The resistivity value was calculated to understand conductive properties of the subsurface
231 media (Reynolds, 1997). Resistivity data processing was accomplished using the programing code
232 and algorithms of a software RES2DINV. The 2D profile of resistivity was obtained by
233 performing elimination of bad data points, topographic correction, RMS convergence restraint,
234 least-squares inversion and a robust smoothness constraint (Loke and Barker, 1996). Inversion of
235 resistivity was realized with suppression of the smoothness using the least square method, which
236 adjusted the damping factor and the flatness filter ratio to adapt to different kinds of geological

237 structures according to the quality of records (Loke, 2001).

238 As far as landslide investigation is concerned, ERT was applied in detecting high saturated
239 and clay rich zones showing low resistivity ($10 - 40 \Omega \cdot m$) in the landslide (Lebourg et al., 2005;
240 Naudet et al., 2008; Göktürkler et al., 2008). Electrical resistivity tomography was conducted on
241 the profiles using the high density resistivity method. The device used in this study was a WGMD
242 multifunction digital direct current (DC) system. All of the resistivity profiles were obtained after
243 8 iterations, and the RMS error in percentage at the last iteration was controlled to below 5%. Two
244 dimensional resistivity profiles along the survey lines were produced using the Wenner
245 configuration with 60 electrodes, 1.5 m apart, to derive a detailed distribution of shallow
246 groundwater in the debris landslide.

247 **3.3 GPR**

248 Ground penetrating radar emits an electromagnetic pulse into the ground by chosen antennas.
249 The wave propagation, time-frequency and amplitude characteristics of electromagnetic signals
250 could then be analysed in order to understand the structure of the near-surface medium (Neal,
251 2004). The vertical resolution of GPR is a quarter to a half of the electromagnetic wavelength,
252 which depends on the frequency and propagation velocity of radar wave calculated from the
253 dielectric constants of soil (Sheriff, 1991; Otto et al., 2006). A higher frequency antenna
254 corresponds to higher resolution and shallower penetrating depth and vice versa. Therefore, the
255 selection of antennas and layout parameters is very important in radar data collection based on the
256 actual site conditions.

257 We carried out the electromagnetic surveys with ground penetrating radar SIR-20 from
258 Geophysical Survey Systems, Inc. (GSSI) Co., Ltd. In order to assure the probing depth and
259 resolution at the same time, a 100 MHz antenna corresponding to a theoretical penetrating depth
260 of 15 m was selected. The sampling rate used in the tests was 250 scans/m. Generally speaking,
261 there are three kinds of observation layout system, namely reflection profile (RP), wide angle
262 reflection (WAR) and common midpoint (CMP). RP was used in this study to obtain radar images
263 by moving the ground penetration radar along the above mentioned profiles with a fixed distance
264 between the transmitting antenna and the receiving antenna. The depths in the radargram
265 transformed from travel times were calculated based on an estimated wave velocity of

266 1.06×10^8 m/s with the equation $v = c / \sqrt{\varepsilon_r}$, where v was radar wave velocity, c was its
267 corresponding propagation velocity in vacuum (m/s), ε_r was relative dielectric constants with a
268 reference value of $\varepsilon_r = 8.0$ given by Davis and Annan (1989). Radar data processing was
269 accomplished using RADAN (version 6.0, Geophysical Survey Systems Inc., USA), including
270 distance norm, range gain, finite impulse response (FIR) filter, deconvolution, Kirchhoff migration
271 and time-depth conversion.

272 **3.4 MSM**

273 MSM assumes that a microtremor is a stationary random process in space and time. The shear
274 wave velocity structure is estimated by the inversion of dispersion curves extracted from the
275 vertical component of microtremor records by the spatial autocorrelation (SPAC) method (Aki,
276 1957; Okada, 2003; Xu et al., 2009). We fitted the spatial autocorrelation coefficient to obtain
277 Rayleigh wave dispersion curves for the inversion of shear wave velocity structure (Xu et al.,
278 2012).

279 The microtremor survey instrument comprised a broadband seismometer CMG-3ESPC and a
280 data acquisition device REFTEK 72-08A from the Chinese seismic probe array center (CSPAC),
281 mainly including a broadband seismometer, battery, GPS clock, data collector and wires, etc. The
282 single-point circular array observation system comprised seven sets of microtremor instruments to
283 observe digital signals simultaneously, and the synchronization was controlled by an inner GPS
284 clock in the collector. As shown in Fig. 6a, here S_1 is the center point (survey point), and the other
285 six points (S_2 — S_7) are station points. A total of six microtremor observation points (S_2 — S_7) are
286 equally spaced on the circumference of two circles with radius of r_1 and r_2 , respectively. The
287 detection depth of the SPAC method was 3 to 5 times more than the observation radius (Okada,
288 2003). Preliminary geological survey showed that the maximum thickness of the landslide was
289 about 60 m. Therefore, we selected an inner radius of 5 m and an outer radius of 10 m to achieve
290 the SPAC detection depth (Fig. 6b). Finally, observation was conducted for two hours at each
291 survey point after the instrument was stable.

292 **4. Results and discussion**

293 **4.1 Shallow colluvial layer of the landslide**

294 To obtain the thickness of the shallow colluvial layer (SCL) of the debris landslide,
295 geophysical methods of MASW and GPR were jointly used to derive shear wave velocity profiles
296 (P1, P2, and P3) and reflection profiles of the radar wave (P2, P3). The interval of surveying
297 points was 6.0 m on all Vs profiles (Fig. 7). Location of the transverse profiles P2 and P3 were
298 marked with thick black dashed lines on the longitudinal profile P1 as shown in Fig. 7a. Boreholes
299 ZK02 and ZK03 were located at the bottom of the landslide. The reliable investigation depth of
300 MASW was 15 m, which was limited by the broken characteristics of gravel soil.

301 According to the Vs profile of P1, the landslide geological structure was divided into 4 layers
302 from surface to the depth of 12 m, including diluvial layer (<150 m/s), diluvial gravel layer
303 (150–250m/s), gravel layer (250–350m/s) and gravel clay layer (350–500m/s), which was verified
304 by the exposed geological profile in Fig. 4c. Average thickness of the shallow colluvial layer of
305 the landslide was about 5.0 m. The thickness of upper part of the landslide was greater, about 5-13
306 m, than that at the toe, about 3-5m. The maximum and minimum thickness were located next to P2
307 and P3, respectively, in accordance with the results from the boreholes ZK02 and ZK03. High
308 velocity body ($V_s > 550$ m/s) existed in the range of 40-50 m on Profile P1 at a depth of about 7.0
309 m. Average thickness of the SCL on Profile P2 (Fig. 7b) was over 4.0 m. However, there was a
310 collapsed low velocity zone (200-300 m/s) with a width of about 10.0 m at the location of about
311 30 m, of which the maximum thickness was about 13.0 m. By contrast, variation in thickness of
312 the SCL on Profile P3 was relatively flat with an average thickness of about 3.0 m. Three high
313 velocity blocks (>550 m/s) existed in the left part of P3. Meanwhile, there were two large low
314 velocity zones (300–350 m/s) on Profile P3 at the locations of 30.0 m and 80.0 m with thickness
315 of 8.0 m.

316 In order to verify the SCL results evaluated from MASW, we carried out GPR survey on
317 Profiles P2 and P3. Strong attenuation zones delimited by thick dashed lines in Fig. 8 were in
318 accordance with the low velocity zones (LVZ) in Fig. 7b and Fig. 7c, which showed a good
319 consistency with each other in detecting shallow structure of the landslide. The elastic properties
320 and conductivity of rock and soil in the landslide could be described with shear wave velocity and
321 electromagnetic wave attenuation, respectively. MASW was relatively accurate for probing
322 shallow subsurface with high resolution in the range of 15 m depth, and the critical shear wave

323 velocity of the SCL in the debris landslide was 350 m/s. GPR was faster than MASW in obtaining
324 the radar image of landslide structure based on the dielectric constants of underground materials.
325 Moreover, collapsed zones in Fig. 7 and Fig. 8 were consistent with each other which could be
326 interpreted with the drill core samples of ZK02 in Fig. 7. Positive amplitudes and negative
327 amplitudes represented stiff soil and loose soil, namely, high density soil and low density soil,
328 respectively.

329 However, the probing depth of both MASW and GPR was limited as a result of strong
330 attenuation of Rayleigh surface waves and radar waves by the loose or broken gravel soil. The
331 SCL undulation and geological anomalous bodies (large boulders or stones) revealed the
332 limitations of drilling technology. The thickness of the SCL could be regarded as the estimation
333 basis of slope debris flow volume (Le Roux et al., 2011), and it was closely related to the accurate
334 location of groundwater seepage paths.

335 **4.2 Hydrologic conditions**

336 ERT was suitable to identify the internal structure, water rich zone, clay zone and saturated
337 faults in landslides (Lebourg et al., 2005, 2010; Marescot et al., 2008). For the Xishan village
338 landslide, Xu et al. (2016) investigated the preferential flow pathways in it via time-lapse
339 electrical resistivity tomography (TLERT). To locate the groundwater flow channels in the
340 landslide, we conducted ERT survey along four resistivity profiles (P1, P2, P3 and P4) on it. The
341 short vertical line segments on top of each profile were electrode positions of a Wenner
342 configuration, 1.5 m apart (Fig. 9a). The credible investigation depth of ERT was about 12.0 m.
343 The resistivity value of landslide material was in the range of 0–300 $\Omega\cdot\text{m}$, out of which it was not
344 reliable due to the interpolation in resistivity inversion (Fig. 9a). In Fig. 9a, thin black dashed lines
345 were used to indicate the thickness of the SCL, and thick black dashed lines delineated the
346 saturated zones or clay rich zones. White arrows showed the drainage direction of groundwater,
347 and seepage field was visible too in the landslide.

348 Comparing with the profiles in Fig. 7, the resistivity value in Fig. 9 was consistent with the
349 shear wave velocity. On Profile P1, there was a low-conductivity, high-velocity block ($V_s > 550$
350 m/s, $\rho > 300 \Omega\cdot\text{m}$) and a high-conductivity, low-velocity block ($V_s < 350$ m/s, $\rho < 40 \Omega\cdot\text{m}$) at 45 m
351 and 60 m away from the toe (left end) of the landslide, respectively. Similar results appeared on

352 Profiles P2 and P3, such as a visible high-conductivity, low-velocity block at 6.0 m depth on
353 Profiles P2 and P3 at locations of 30 m 80 m from the left end, respectively. Figs. 7, 8 and 9 from
354 different methods gave similar variation results of the geological structure at the same locations of
355 the Profiles P2 and P3.

356 The resistivity value of the high saturated zone in the debris landslide was in the range of
357 0–50 Ω -m. The range with resistivity over 50 Ω -m could be interpreted as a low water content
358 zone, or a high density zone with large boulders or stones (Fig. 4b). Some different size
359 groundwater outcrop points and drill core samples shown in Fig. 9 could provide some evidence
360 for the above discussion. For instance, groundwater outflow in Fig. 3d was located on Profile P4
361 (Fig. 9) at the location of 40 m at depth of 6.0 m. The groundwater drainage system in the debris
362 landslide was a dendritic pipe-network system showing the characteristics of great inhomogeneity
363 and concentration.

364 **4.3 Potential sliding surface of the landslide**

365 The overburden thickness of the deep seated Xishan village landslide was about 50 m. An
366 initiative source MASW and passive source MSM were used to obtain the internal structure and
367 potential sliding surface of this landslide in view of probing depth and resolution at the same time.
368 Investigation depth of MASW was limited in depth range of 20 m, controlled by a high frequency
369 component (20–100 Hz) from the hammer source. Investigation depth of MSM was up to
370 hundreds of meters for low frequency component (1–20 Hz) from microtremor (Xu et al., 2009;
371 2012). As shown in Fig. 10, inverse black solid triangles represent the survey points of MASW
372 arranged at an equal spacing of 6.0 m. Gray rectangles were the survey center points O_i of the
373 microtremor observation array in Fig. 6a. The geological structure included 4 layers, including a
374 shallow colluvial layer (90–250 m/s), gravel soil layer (250–400m/s), weathered phyllite
375 (400–500m/s) and phyllite bedrock (>500m/s).

376 The potential sliding surface estimated by MSM was a weathered phyllite boundary in the
377 range of 45-55 m at depth, and the average depth was 50 m. The location of the weathered phyllite
378 layer determined by MSM was close to the borehole results, and the geometric shape of it was also
379 visible on the V_s profile in Fig. 10. As far as delineation of weathered bedrock is concerned, the
380 thickness of the weathered layer from borehole ZK03 was about 7.6 m. The strong weathered

381 layer and intermediary weathered layer estimated from ZK03 in Fig.5 were in the range of
382 53.2-55.2 m and 55.2-60.8 m in depth, respectively. Meanwhile, the weathered layer estimated by
383 MSM was in the range of 30-57 m, and the average depth was about 51.5 m corresponding to a
384 shear wave velocity of 400–500 m/s. However, MSM failed to distinguish the strong weathered
385 layer and intermediary weathered layer, owing to insufficient survey points on the cross profile.
386 Ellipses represented the positions of large boulders or stones, which indicated that geophysical
387 survey with high covering density could provide a reference for drilling site selection. Dual-source
388 type surface wave (DDSW) could simultaneously assure both the exploration depth and resolution
389 for the structure detection of landslides. This technology was more effective than drilling in terms
390 of delineating depth, survey range and expenditure, and more suitable for large scale and high
391 density survey of a debris landslide.

392 **4.4 Hydrogeological model of the landslide**

393 A hydrogeological model of the debris landslide shown in Fig. 11 was built based on the above
394 joint analysis on the geological structure, hydrological conditions and potential failure surface
395 through integrated geophysical methods. The shallow colluvial layer was surveyed with MASW
396 and GPR. In situ hydrological information and pipe-network seepage system were extracted with
397 ERT. The geometric shape of the deep seated weathered bedrock and potential sliding surface was
398 delineated with MSM. Strong infiltration was visible, and potential failure surface was finally
399 estimated by both engineering survey and MSM in this model.

400 The internal structure of this landslide from MASW and MSM shown in Fig. 10 could
401 provide a reliable geological structure background for the delineation of seepage system. The gray
402 areas in Fig. 11 represented high-velocity and low-conductivity bodies from MASW and GPR,
403 respectively, which could be interpreted as large stones or hard blocks. The potential sliding
404 surface estimated by MSM was more visible and accurate than that from boreholes. A collapsed
405 low-velocity and high-conductivity block was formed by the confluence of shallow underground
406 water in the loose colluvial layer. The development of a pipe-network seepage system in a gravel
407 soil layer beneath the catchment area was a key factor for the stability estimation of a landslide.

408 At depths up to 15 m, underground water continued to infiltrate down to a deeper gravel soil
409 layer. ERT revealed the infiltration paths marked by black solid lines with arrows, which showed

410 the detour flow around geological abnormal zones. At depths greater than 15 m, infiltration paths
411 marked by black dashed lines with arrows in a gravel soil layer were speculated due to the limited
412 amount of electrodes. Therefore, longer survey lines were necessary to learn about deeper
413 hydrological information. It was known that the pipe-network seepage system in landslides could
414 drain underground water away in time to maintain the stability of them. Our study attempted to
415 discover the developing characteristics of seepage paths in a shallow debris landslide, but deeper
416 vertical infiltrability was unknown.

417 To verify the geophysical results, some geotechnical techniques and corresponding
418 parameters were recently used in geophysical interpretation, such as the combined
419 penetrometer moisture probe (CPMP), resistivity cone (RCPTU), penetration resistance,
420 remoulded shear strength, and so on (Yamakawa et al. 2010; Hibert et al. 2012; Solberg et al.,2016).
421 Continuous pore water pressure monitoring via borehole ZK03 using BGK-4500SR osmometers
422 showed that pore water pressure at depth of 25.92 m was high and increased with time, which
423 meant that this location was on the pipe-network seepage paths. By contrast, the pore water
424 pressure was about 7~17 kPa at depths of 8.00 m and 48.12 m and the variation with time was not
425 obvious. These verified the pipe-network seepage system revealed by integrated geophysical
426 investigation.

427 Fig. 13 gives the relationship between shear wave velocity and pore water pressure and
428 displacement. The observed displacements using borehole inclinometers in Fig.13 gradually
429 decreased with increase in depth from 5.39 m to 48.32 m. It also illustrated that the infiltration of
430 groundwater had induced the landslide deformation. The depth of potential infiltration interface
431 might be in the depth range of 25~30 m as indicated by Figs. 11 and 13. The corresponding shear
432 wave velocity was about 400 m/s. The depth of potential sliding surface estimated from the
433 displacement observation was about 38.48 m, which was consistent with the boundary for the
434 weathered phyllite in Fig. 11. There was an obvious negative correlation between shear wave
435 velocity and displacement along depth in Fig. 13, which indicated that the activities of landslide
436 could be inferred by geophysical methods. The shear strength of the potential sliding surface
437 would decrease if groundwater infiltrated into the weathered phyllite layer. Further survey work
438 should be conducted to confirm this. More complimentary in situ and laboratory tests were

439 necessary to evaluate mechanical and hydrogeological parameters of the landslide subsoil from
440 geophysical investigation. The comprehensive application of geophysical and geotechnical
441 techniques will be able to determine the quantitative hydro-geological characteristics of debris
442 landslides in the future.

443 **5. Conclusion**

444 In this study, surveys with multi-geophysical methods were carried out on a debris landslide
445 in Xishan Village, Li County, Sichuan Province, China. Shear wave velocity (V_s) could provide
446 some information about stratum structure, geological abnormal body (large boulders or blocks),
447 fissures and deformation of the landslide, etc. Resistivity value (ρ) was used to detect variation in
448 water content, high saturated and clay rich zones. Electromagnetic wave attenuation was very
449 helpful for the tomography of shallow structures with high resolution, especially for saturated or
450 clay rich zones. The depth and geometry of shallow colluvial layers was revealed by the combined
451 application of MASW and GPR. ERT was an effective tool to probe hydrographic information and
452 seepage paths in the debris landslide. The combination of MASW and MSM was the most suitable
453 to delineate the internal structure, bedrock, weathered bedrock layer and potential sliding surface
454 of the deep seated landslide.

455 Varisized boulders and stones in the debris landslide have significant influence on the
456 location selection of boreholes, so that preliminary geophysical surveys are particularly important.
457 Geophysical investigation showed that dendritic pipe-network seepage paths with different
458 dimensions developed in the slope. Groundwater seepage was highly inhomogeneous and
459 concentrated in the debris landslide. Water infiltration in landslides directly affects their stability,
460 so that surface and underground water drainage is an important measure for debris landslide
461 mitigation. The combined application of geophysical technologies were very useful for in situ
462 identification of groundwater infiltration paths in the debris landslide. It could provide a reference
463 for the location selection of drainage ditches or flumes.

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474 acquisition.

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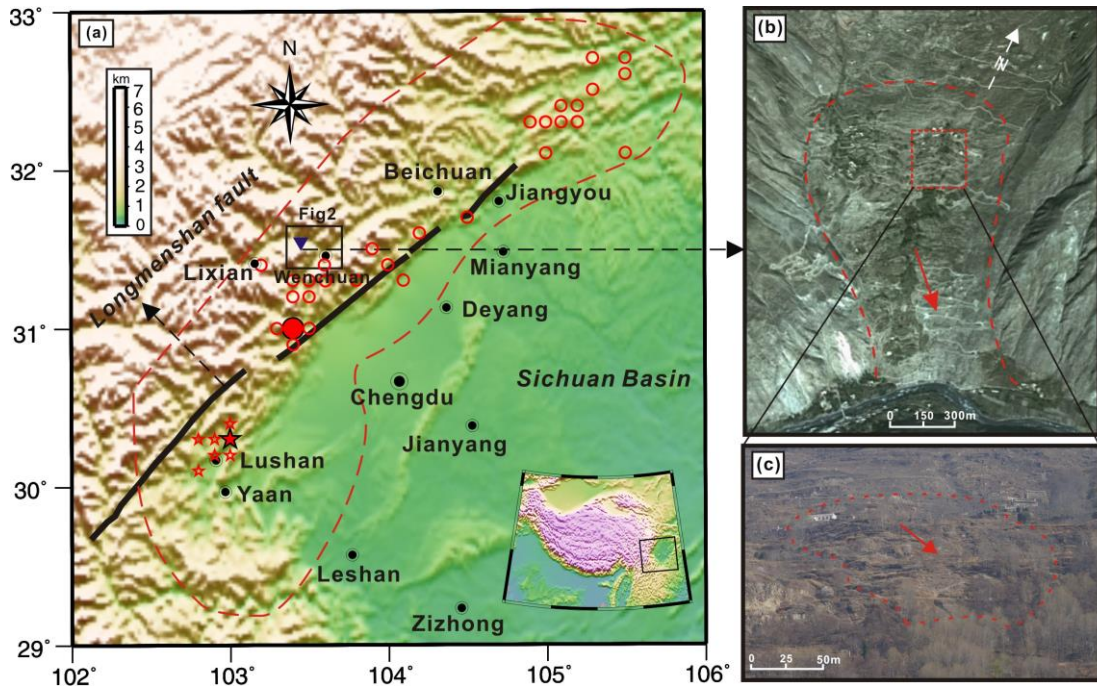
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592 **Figures**

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596 Fig. 1. (a) Location of the study area. The red circles and stars represent locations of the Wenchuan earthquake and

597 the Lushan earthquake, respectively. The red dashed line is the seismic intensity distribution range of both

598 earthquakes. (b) The Xishan village landslide. The red arrows indicate the main sliding direction of the landslide.

599 (c) Testing landslide site. The red dashed line is the boundary of a small landslide on the Xishan village landslide.

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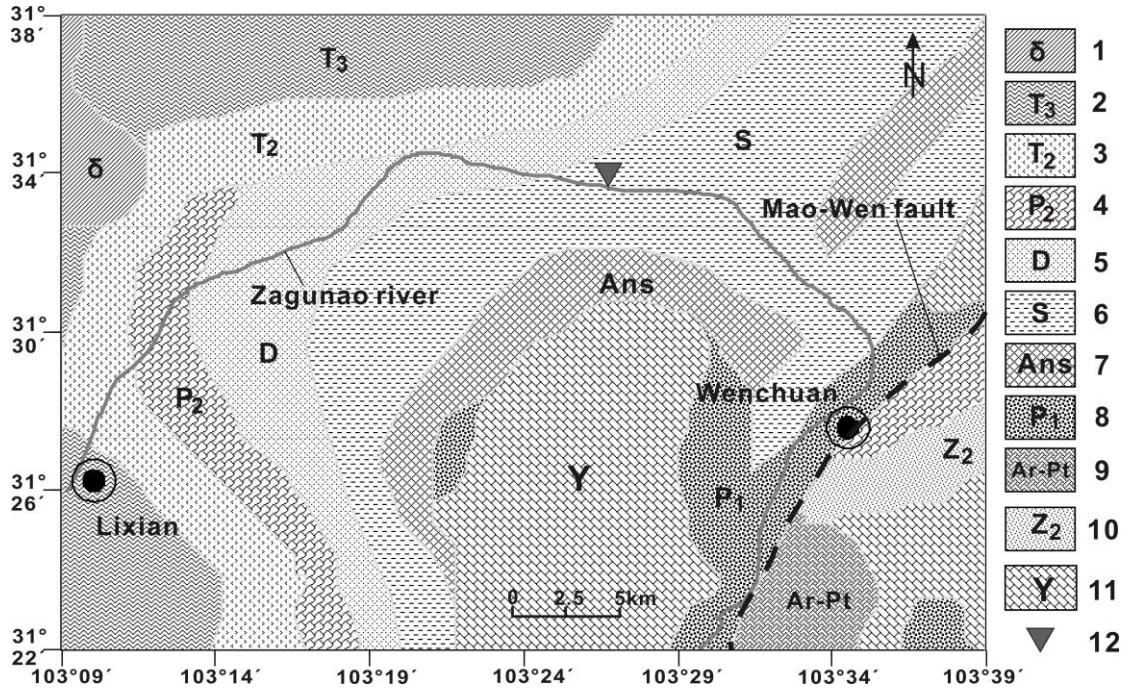
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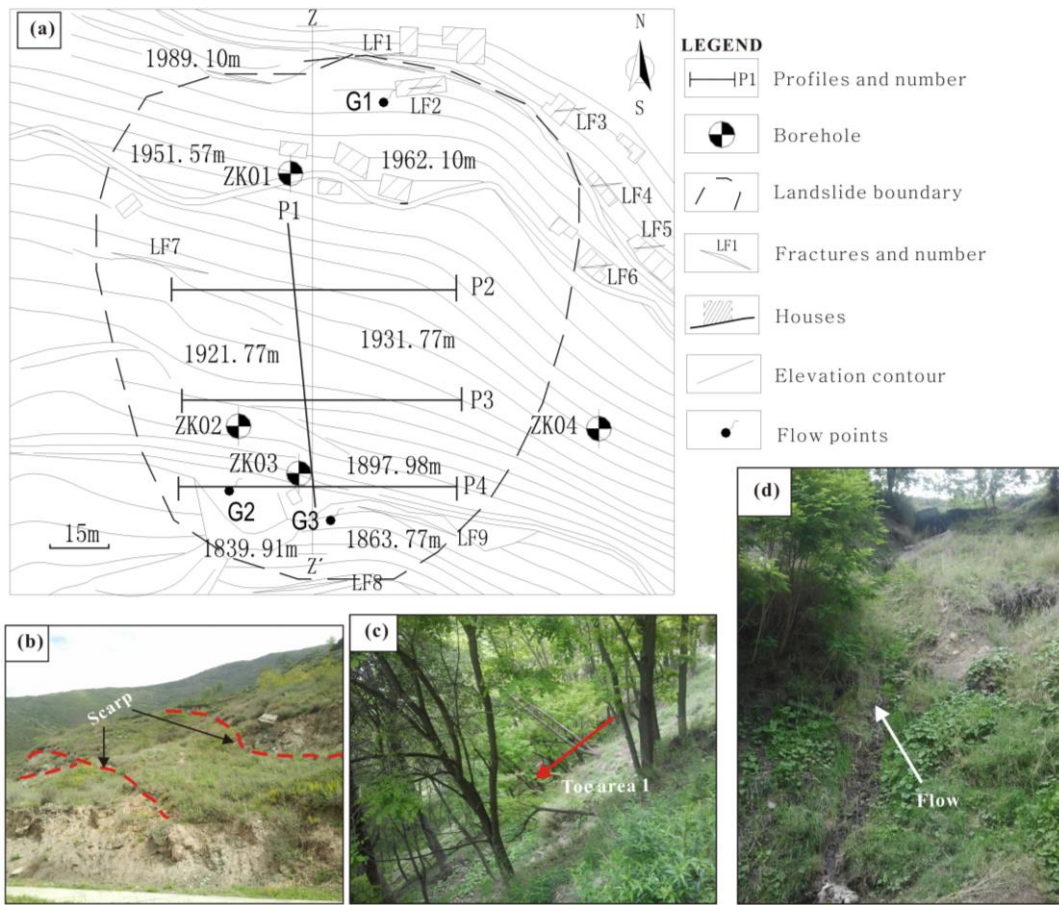
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Fig. 2. Regional geological map of the study area.

618 (1) Quartz syenite rock; (2) Clasolite and carbonate ; (3) Fine clasolite and carbonate; (4) Sandstone and limestone;
619 (5) Limestone and mudstone; (6) Slate and phyllite; (7) Silurian System ; (8) Siltstone, limestone and extrusive
620 rock; (9) Kangding Gr; (10) Dolomite and sand shale; (11) Plagioclase granite ; (12) Xishan village landslide.

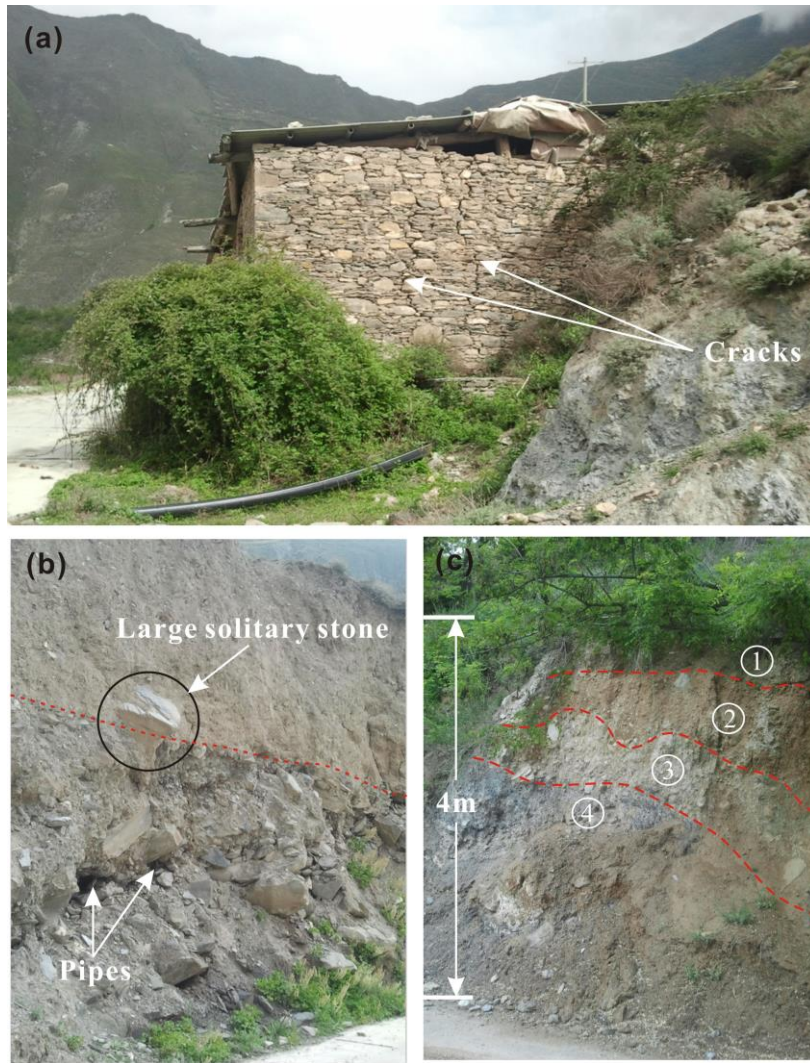
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Fig. 3. (a) Map of the engineering geological plane; (b) Scarps at the back edge of the landslide; (c, d) Vegetation coverage and water outflow at the toe of the landslide (G3).



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Fig. 4. (a) House cracks induced by landslide deformation; (b) Excavation profile near the rural road; (c) Shallow stratum on the landslide located near the flow point G2 and G3 in Fig. 3a.

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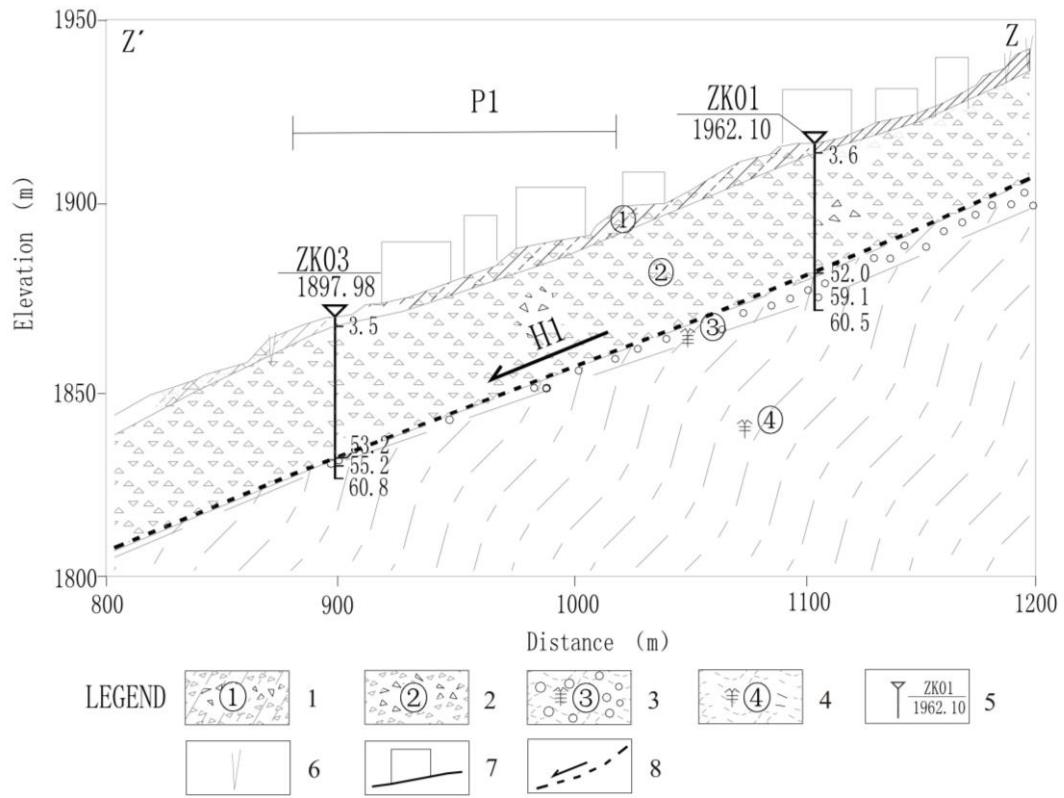
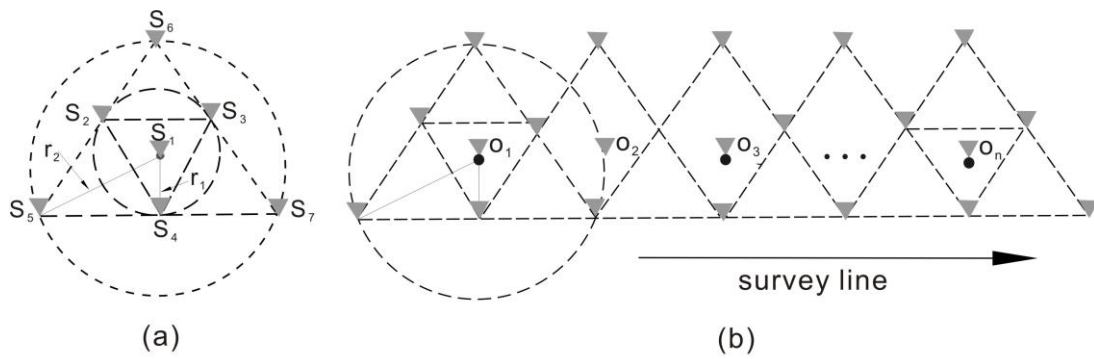


Fig. 5. Cross-section (ZZ') showing the structure of landslide in Fig. 3a.

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(1) Quaternary diluvium; (2) Gravel soil; (3) Weathered phyllite; (4) Phyllite bedrock; (5) Borehole and number; (6) Fissure; (7) House; (8) Potential failure surface.

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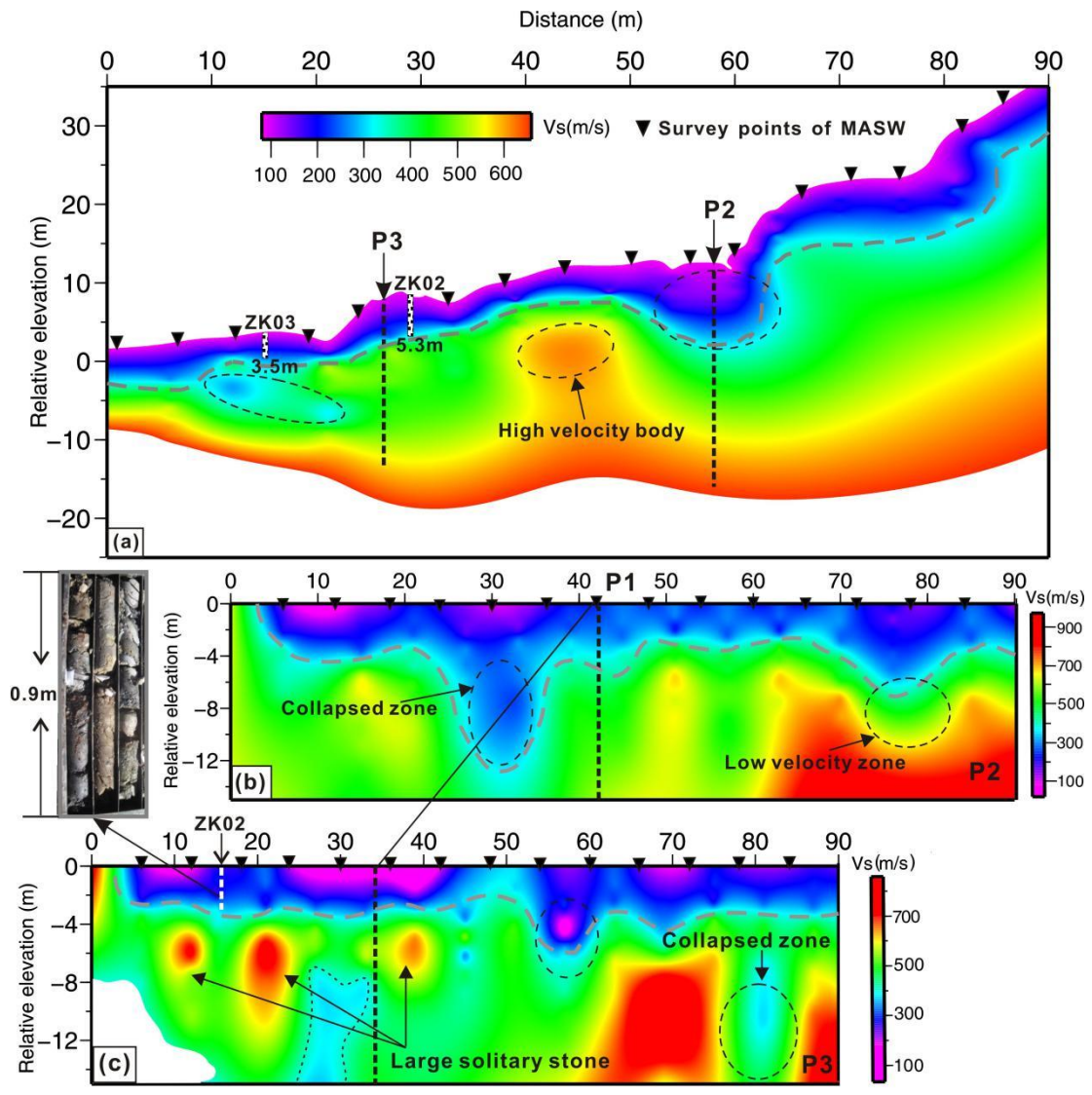


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Fig. 6. Layout of microtremor observation array.

(a) Single-point array survey system; (b) Layout of microtremor profile observation.

The black solid circles represent survey points; gray solid inverse triangles indicate the locations of observation equipment.



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Fig. 7. The profiles of shear wave velocity in landslide.

(a) Profile P1; (b) Profile P2; (c) Profile P3.

The black inverse triangles represent survey points, black dashed lines represent the location of profiles and gray dashed lines indicate the depth distribution of the shallow colluvial layer (SCL)

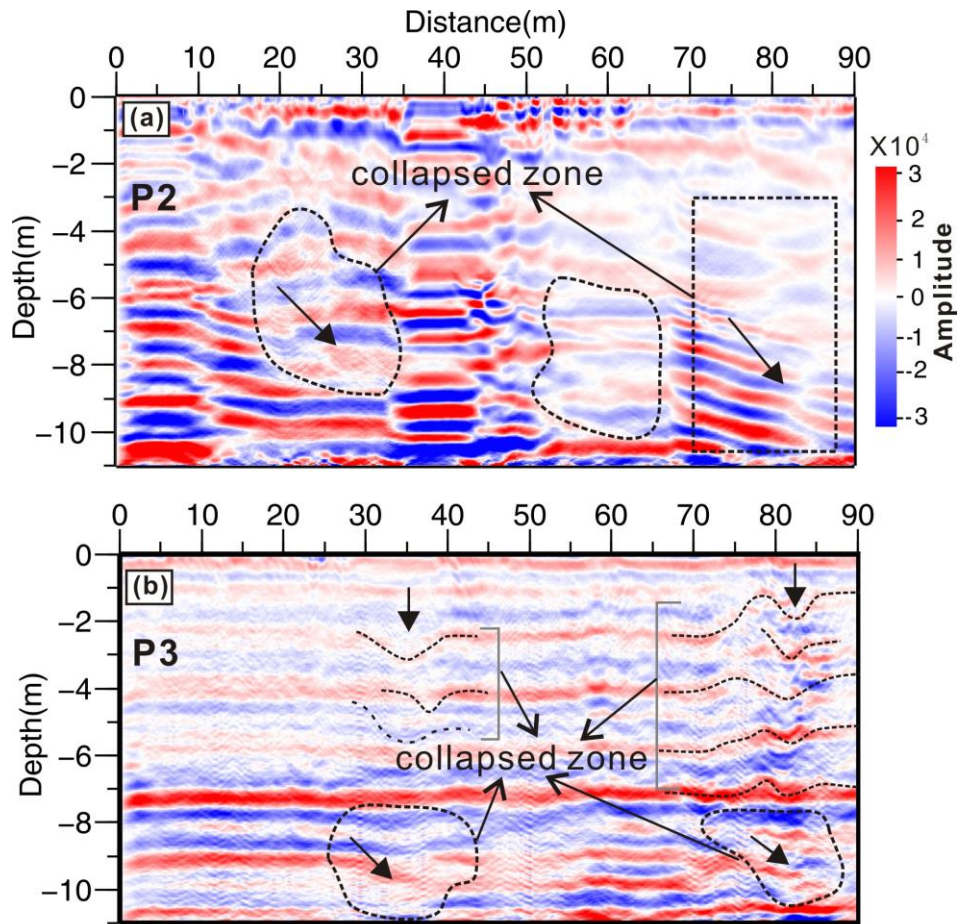


Fig. 8. GPR image profiles of P2 and P3.

The arrows indicate the extension direction of collapsed zones; radar wave attenuation zones were delimited by thick dashed lines which corresponded well to the location of collapsed zones or low velocity zones (LVZ) of the

Vs profiles on P2 and P3 in Fig. 3.

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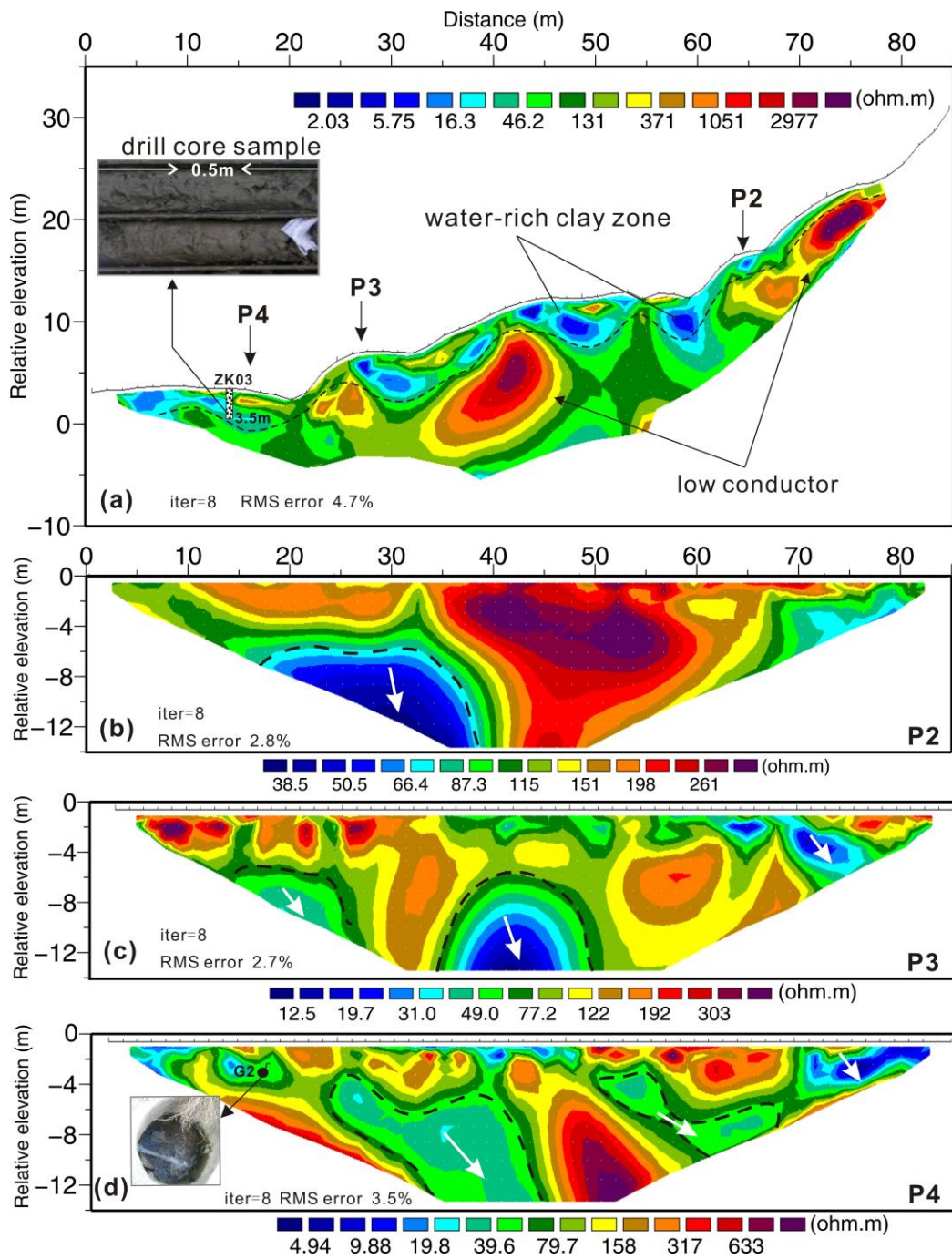
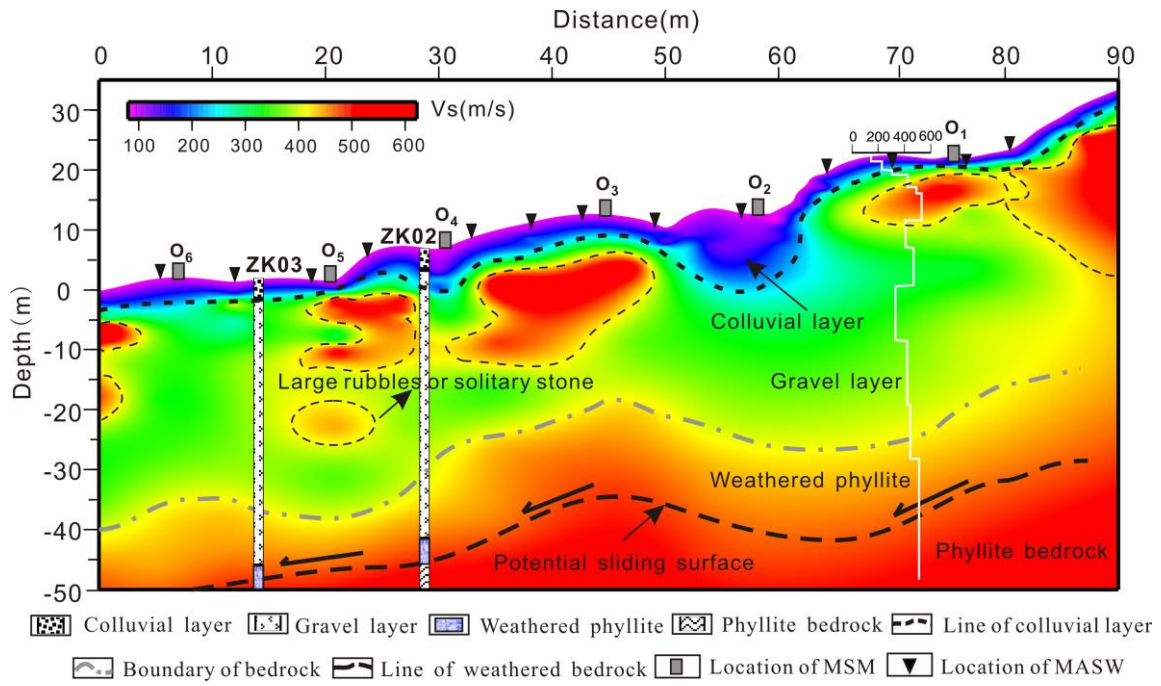


Fig. 9. Electrical resistivity tomography (ERT) profiles.

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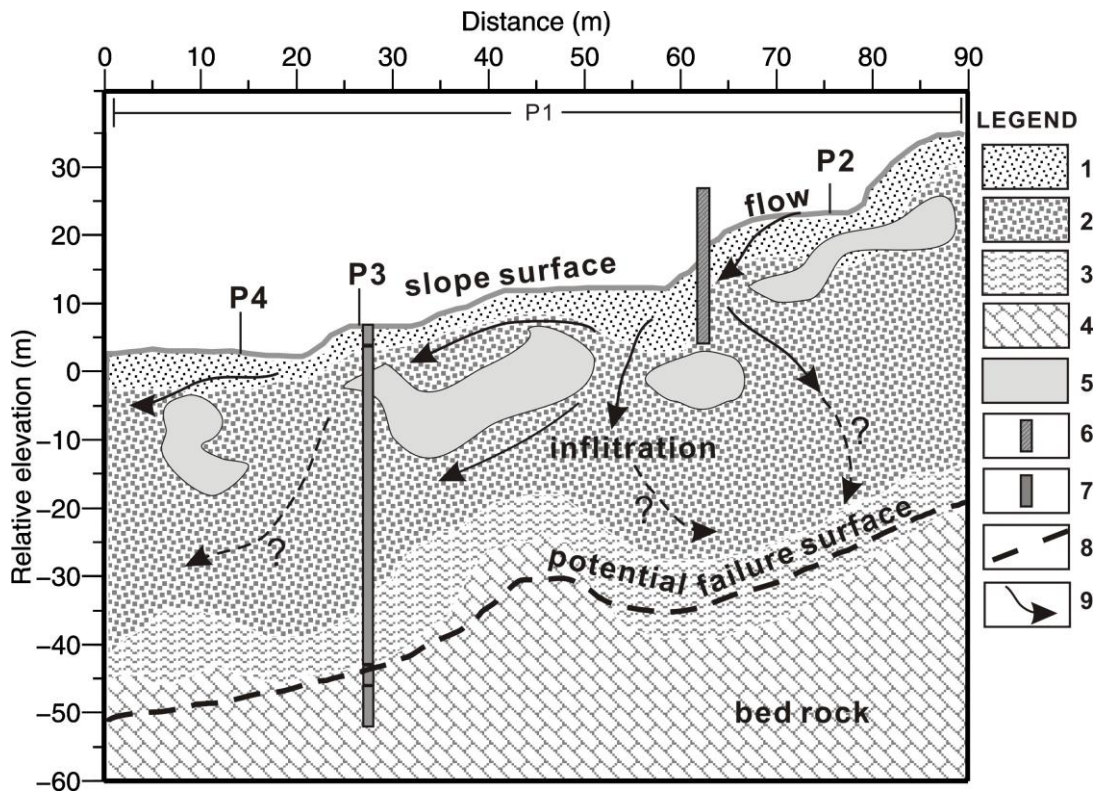


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Fig. 10. Shear velocity structure estimated by both the MASW and MSM

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Fig. 11. A Hydro-geology model of comprehensive interpretation in the debris landslide.

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(1) Diluvium layer; (2) Gravel layer; (3) Strong weathered phyllite; (4) Phyllite bedrock; (5) High velocity or low

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conductor zone; (6) Drainage channel ; (7) Borehole; (8) Potential failure surface comprehensive assessment from

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geophysical investigation and engineering survey ; (9) Infiltration paths of surface water.

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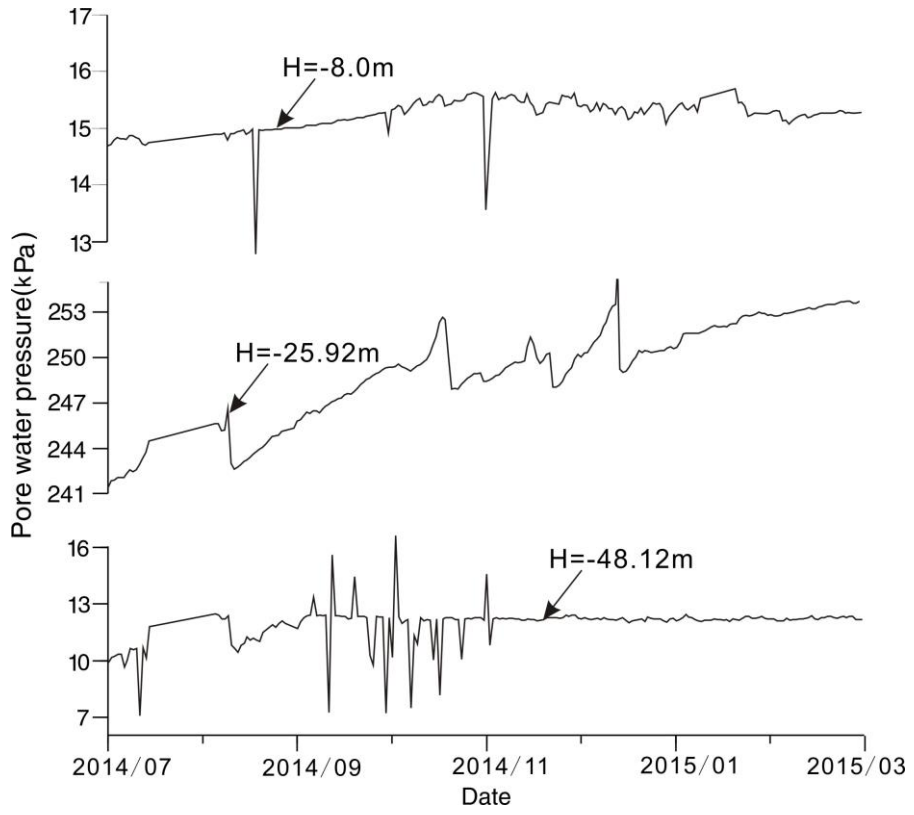
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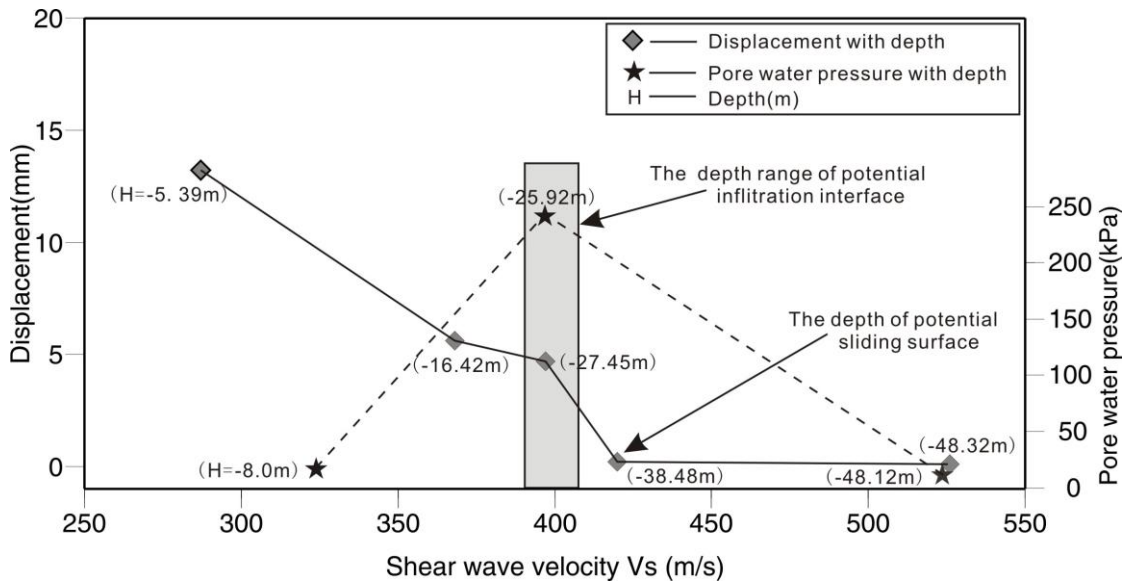
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Fig. 12. The monitored pore water pressure at 8.0 m, 25.92 m and 48.12 m depth of ZK03

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Fig. 13. The relationship between shear wave velocity and pore water pressure and displacements along the depth of ZK03 in the landslide