

# Effect of Horizontal Alternating Current Electric Field on the Stability of Natural Convection in a Dielectric Fluid Saturated Vertical Porous Layer

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*The stability of natural convection in a dielectric fluid-saturated vertical porous layer in the presence of a uniform horizontal AC electric field is investigated. The flow in the porous medium is governed by Brinkman–Wooding-extended-Darcy equation with fluid viscosity different from effective viscosity. The resulting generalized eigenvalue problem is solved numerically using the Chebyshev collocation method. The critical Grashof number  $G_c$ , the critical wave number  $a_c$ , and the critical wave speed  $c_c$  are computed for a wide range of Prandtl number  $Pr$ , Darcy number  $Da$ , the ratio of effective viscosity to the fluid viscosity  $\Lambda$ , and AC electric Rayleigh number  $Re_a$ . Interestingly, the value of Prandtl number at which the transition from stationary to traveling-wave mode takes place is found to be independent of  $Re_a$ . The interconnectedness of the Darcy number and the Prandtl number on the nature of modes of instability is clearly delineated and found that increasing in  $Da$  and  $Re_a$  is to destabilize the system. The ratio of viscosities  $\Lambda$  shows stabilizing effect on the system at the stationary mode, but to the contrary, it exhibits a dual behavior once the instability is via traveling-wave mode. Besides, the value of  $Pr$  at which transition occurs from stationary to traveling-wave mode increases with decreasing  $\Lambda$ . The behavior of secondary flows is discussed in detail for values of physical parameters at which transition from stationary to traveling-wave mode takes place. [DOI: 10.1115/1.4029348]*

*Keywords: natural convection, heat transfer, porous layer, AC electric field, stability, Chebyshev collocation method*

## 1 Introduction

In the recent past, several studies have addressed the stability of fluid flows in a fluid saturated porous medium. All these contributions, for instance, Makinde [1], Hill and Straughan [2], and Straughan and Harfash [3] are, however, limited to the case of a horizontal layer of porous medium. Nonetheless, the stability of natural convection in a vertical fluid saturated porous layer is important in analysis of natural convection flow arising from a heated impermeable surface, embedded in fluid saturated porous media, and has been used to model the heating of groundwater in an aquifer by a dike, which is idealized as a vertical impermeable surface. Besides, the study is of importance in many engineering and technological areas. These includes high performance insulation for building and cold storage, cooling of nuclear fuel in shipping flasks and water filled storage bays, insulation of high temperature gas cooled reactor vessels, burying of drums containing heat generating chemicals in the earth, regenerative heat exchangers containing porous materials, and so on. The instability of buoyancy opposed mixed convection in a vertical channel filled with a fluid-saturated porous medium is studied by Bera and Khalili [4].

Moreover, the influence of magnetic field or electric field becomes important as many fluid dynamical systems occurring in nature and engineering applications often involve electrically conducting fluids. In particular, the effects of magnetic field become dominant on convective instability when the fluid is either finitely

or highly electrically conducting. Thermal convective instability in a horizontal electrically conducting fluid layer in the presence of a uniform vertical magnetic field has been studied in detail by Chandrasekhar [5]. Its counterpart in a porous medium has also been investigated in the past (Ref. [6] and references therein). The effect of temperature modulation on the onset of thermal convection in an electrically conducting fluid-saturated porous medium subjected to a vertical magnetic field is discussed by Bhadauria [7]. Bhatta et al. [8] studied steady magnetoconvection in a horizontal mushy layer, which is considered as a porous medium. To the contrary, if the fluid is dielectric then the electric forces play a major role rather than magnetic forces in driving the motion.

The effect of AC as well as DC electric fields on convective instability in a dielectric horizontal fluid layer has been studied extensively in the past [9–12]. In dielectric fluids, an applied temperature gradient produces nonuniformities in the dielectric constant. The variation in dielectric constant and the electric field intense the polarization force causing fluid motion. In this case, convection can occur in a dielectric fluid layer even if the temperature gradient is stabilizing (i.e., cooling from below and heating from above) and such an instability produced by an electric field is called electroconvection, which is analogous to Rayleigh–Bénard instability. In addition, if the applied temperature gradient is also destabilizing (that is, heating from below and cooling from above) then such an instability problem is called electrothermal convection.

The drying process in porous media is a rather complicated process and new techniques are on anvil to make the drying processes more efficient and one of the effective ways to improve the overall drying kinetics is to apply an electric field [13,14]. Besides, it is observed that imposing AC currents facilitate transport-related

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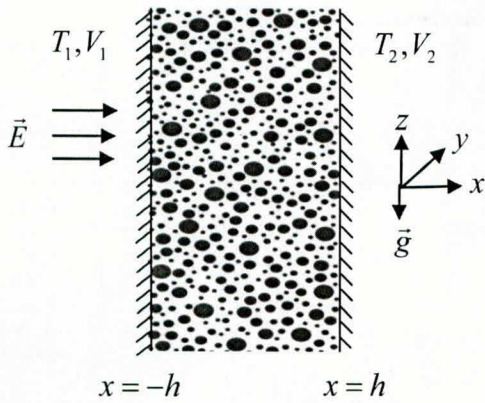


Fig. 1 Physical configuration

effects of two-phase flows, oil and water, in porous rocks [15]. It is thus imperative to study the stability of natural convection in a dielectric layer of porous medium in the presence of an electric field. The works which have been carried out in this direction are mainly concerned with buoyancy driven convection in a horizontal dielectric fluid saturated porous layer [15–17].

In this paper, the effect of a uniform AC electric field on the stability of natural convection in a vertical layer of dielectric fluid saturated sparsely packed porous medium is investigated because of its relevance and importance in many practical problems cited above. The resulting eigenvalue problem is solved numerically using Chebyshev collocation method and the results are presented graphically.

## 2 Mathematical Formulation

The physical configuration is as shown in Fig. 1. It consists of a Boussinesq dielectric fluid-saturated sparsely packed vertical layer of porous medium subject to a uniform AC electric field applied across the porous layer. A Cartesian coordinate system  $(x, y, z)$  is chosen with the origin at the middle of the vertical porous layer, where the  $x$ -axis is taken perpendicular to the plates and the  $z$ -axis is vertically upward, opposite in the direction of gravity. The plate at  $x = -h$  is maintained at fixed temperature  $T_1$  and fixed electric potential  $V_1 (= 0)$ , while the plate at  $x = h$  is

maintained at fixed temperature  $T_2 (> T_1)$  and at an alternating (60Hz) potential whose root-mean-square value is  $V_2$ . The equation of state is assumed to be linear

$$\rho(T) = \rho_0 \{1 - \alpha(T - T_0)\} \quad (1)$$

where  $\rho_0$  is the density at reference temperature  $T = T_0$  (at the middle of the channel) and  $\alpha$  is the thermal expansion coefficient. The dielectric constant is assumed to be linearly dependent on temperature

$$\varepsilon(T) = \varepsilon_0 \{1 - \gamma(T - T_0)\} \quad (2)$$

where  $\gamma (> 0)$  is the thermal expansion coefficient of dielectric constant and is assumed to be small. For example, for 10 cs silicone oil,  $\gamma = 2.86 \times 10^{-3} \text{ K}^{-1}$  and  $\varepsilon = 2.6 \times 10^{-11} \text{ Fm}^{-1}$ .

The dielectric fluid in the presence of electric field experiences a body force  $\mathbf{f}_e$ , which can be expressed as [18]

$$\mathbf{f}_e = \rho_e \mathbf{E} - \frac{1}{2} (\mathbf{E} \cdot \mathbf{E}) \nabla \varepsilon + \frac{1}{2} \nabla \left( \rho \frac{\partial \varepsilon}{\partial \rho} \mathbf{E} \cdot \mathbf{E} \right) \quad (3)$$

Here,  $\mathbf{E}$  is the root-mean-square value of the electric field,  $\rho_e$  is the free charge density, and  $\varepsilon$  is the dielectric constant. In Eq. (3), the Coulomb force term  $\rho_e \mathbf{E}$  is neglected and only the dielectrophoretic force term  $(\mathbf{E} \cdot \mathbf{E}) \nabla \varepsilon / 2$  is retained [10]. It is seen that the dielectrophoretic force term depends on  $(\mathbf{E} \cdot \mathbf{E})$  rather than  $\mathbf{E}$ . We scale lengths with  $h$ , time with  $\varphi_p h^2 / \nu$ , velocity with  $\kappa / h$ , temperature with  $\beta h$ , electric field with  $\gamma \beta h E_0$ , and pressure with  $\rho_0 \kappa \nu / h^2$  and arrive at the following nondimensional equations, respectively, for the conservation of mass, momentum, and energy [17,19]

$$\nabla \cdot \mathbf{q} = 0 \quad (4)$$

$$\frac{\partial \mathbf{q}}{\partial t} + \frac{1}{\text{Pr}} (\mathbf{q} \cdot \nabla) \mathbf{q} = -\varphi_p^2 \nabla P + G \text{Pr} \theta \hat{k} - \frac{1}{\text{Da}} \mathbf{q} + \Lambda \nabla^2 \mathbf{q} - \frac{R_{ea}}{2} (\mathbf{E} \cdot \mathbf{E}) \nabla \varepsilon \quad (5)$$

$$M \text{Pr} \frac{\partial \theta}{\partial t} + (\mathbf{q} \cdot \nabla) \theta = \nabla^2 \theta \quad (6)$$

with

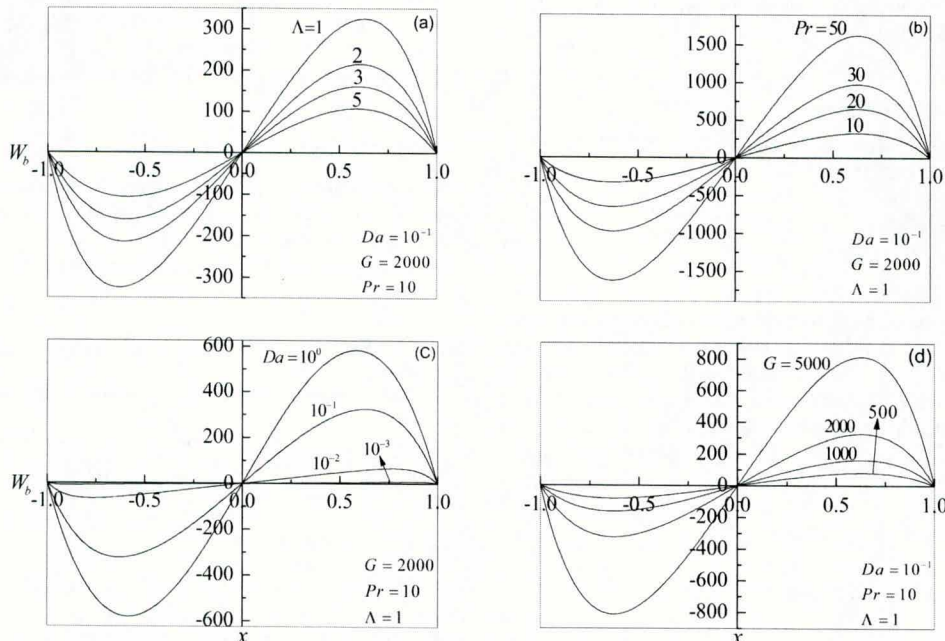


Fig. 2 Basic velocity profiles

**Table 1 Order of base polynomial independency**

N	$\Lambda = 1, G = 1000, Pr = 10, Re_a = 500,$ $a = 1.3, Da = 10^0$		$\Lambda = 1, G = 5000, Pr = 5, Re_a = 500,$ $a = 1.0, Da = 10^{-1}$	
	$c_r$	$c_i$	$c_r$	$c_i$
1	-1.06347688	18.55040886	-1.63863768	-50.04448946
5	-0.34802857	23.65207688	-0.65803884	-19.84774664
10	-0.23948191	25.00002772	-2.51750973	-0.00003551
15	-1.11422137	26.74831987	-2.38597731	-0.00014765
20	-1.11470659	26.74380337	-1.62687643	-0.00011241
25	-1.11471709	26.74385713	-1.62682867	-0.00014189
30	-1.11471985	26.74385061	-1.62682941	-0.00013953
35	-1.11471985	26.74385059	-1.62682943	-0.00013964
40	-1.11471986	26.74385059	-1.62682944	-0.00013964
50	-1.11471986	26.74385058	-1.62682944	-0.00013964
60	-1.11471986	26.74385059	-1.62682944	-0.00013963
70	-1.11471986	26.74385059	-1.62682944	-0.00013964
80	-1.11471986	26.74385059	-1.62682944	-0.00013964

$$\nabla \times \mathbf{E} = 0 \text{ or } \mathbf{E} = -\nabla V, \nabla \cdot (\varepsilon \mathbf{E}) = 0 \quad (7)$$

Here,  $\mathbf{q} = (u, v, w)$  is the velocity vector,  $P$  is the modified pressure,  $\theta (= T - T_0)$  is the temperature,  $V$  is the electric potential,  $Re_a$  is the AC electric Rayleigh number,  $Pr$  is the Prandtl number,  $G$  is the Grashof number,  $\Lambda$  is the ratio of effective viscosity to the fluid viscosity,  $Da$  is the Darcy number,  $M$  is a nondimensional group, and  $\phi_p$  is the porosity of the porous medium.

### 3 Basic State

The basic state solution is found to be

$$\begin{aligned} W_b &= \frac{G Pr Da}{2} \left[ x - \operatorname{cosech} \left( \frac{1}{\sqrt{Da\Lambda}} \right) \sinh \left( \frac{x}{\sqrt{Da\Lambda}} \right) \right], \\ \theta_b &= \frac{x}{2}, \quad \varepsilon_b = 1 - \frac{\Gamma x}{2}, \quad \mathbf{E}_b = \frac{1}{\Gamma} \left[ \frac{1}{1 - \Gamma x/2} \right] \hat{i}, \\ V_b &= \frac{2}{\Gamma^2} \log \left( \frac{1 - \Gamma x/2}{1 + \Gamma/2} \right), \quad (\Gamma = \gamma \beta h) \end{aligned} \quad (8)$$

The pressure is of no consequence as we are eliminating the same. It should be noted that in the initial steady state the electric field does not affect the flow field.

### 4 Linear Stability Analysis

To study the stability of the basic state, we superimpose an infinitesimal disturbance on the base flow in the form

$$\begin{aligned} \mathbf{q} &= \mathbf{q}_b + \mathbf{q}', \quad P = P_b + P', \quad V = V_b + V', \\ \theta &= \theta_b + \theta', \quad \varepsilon = \varepsilon_b + \varepsilon' \end{aligned} \quad (9)$$

Equation (9) is substituted back in to Eqs. (4)–(7) and usual steps of linear stability theory is followed [19]. Since Squire’s theorem is valid, we consider only two-dimensional flows, and hence, a stream function  $\psi(x, z, t)$  is introduced through  $u = \partial\psi/\partial z$  and  $w = -\partial\psi/\partial x$ . Then, the normal mode analysis procedure is applied in the form  $\{\psi, \theta, V\} = \{\Psi, \Theta, \Phi\}(x)e^{ia(z-ct)}$ , where  $c = c_r + ic_i$  and  $a$  is the wave number, to arrive at the following stability equations:

$$\begin{aligned} \left( \frac{W_b}{Pr} - c \right) (D^2 - a^2) \Psi - \frac{1}{Pr} D^2 W_b \Psi + \frac{Re_a}{2} (D\Phi + \Theta) \\ = \frac{1}{ia} \left[ \Lambda (D^2 - a^2)^2 \Psi - \frac{1}{Da} (D^2 - a^2) \Psi - G Pr D\Theta \right] \end{aligned} \quad (10)$$

$$\left( \frac{W_b}{Pr} - Mc \right) \Theta + \frac{1}{2Pr} \Psi = \frac{1}{iaPr} (D^2 - a^2) \Theta \quad (11)$$

$$D\Theta + (D^2 - a^2) \Phi = 0 \quad (12)$$

Equations (10)–(12) are to be solved subject to appropriate boundary conditions. It is considered that on the rigid and isothermal vertical plates the tangential electric field vanishes. Thus the associated boundary conditions are

$$\Psi = D\Psi = \Theta = \Phi = 0 \text{ at } x = \pm 1 \quad (13)$$

Equations (10)–(12) together with the boundary conditions (13) constitute an eigenvalue problem which has to be solved numerically. The resulting eigenvalue problem is solved using the Chebyshev collocation method. The numerical results reported are based on the leading eigenvalue of the said system. By this, we mean that when one employs the time representation in  $\psi$ ,  $\theta$ , and  $V$  of form  $e^{-iac t}$  with  $c = c_r + ic_i$  then this results in  $\psi$ ,  $\theta$ , and  $V$  having terms of form  $e^{-iac_r t} \cdot e^{ac_i t}$ . The eigenvalues are found such that the largest value of  $c_i$  is  $c_i = 0$  and then the result is minimized over the wave number  $a$ . The resulting  $G$  value is then the critical Grashof number with corresponding wave number. The value  $c_i = 0$  is chosen because this is the threshold at which the solution becomes unstable according to linearized theory. For, if  $c_i > 0$  then  $\psi$ ,  $\theta$ , and  $V$  grow rapidly like  $e^{ac_i t}$  and the solution is unstable.

### 5 Results and Discussion

A numerical study has been carried to analyze the effect of uniform horizontal AC electric field on the stability of natural convection in a dielectric fluid saturated vertical porous layer whose walls are maintained at constant but different temperatures. The Brinkman–Wooding-extended Darcy model is adopted to describe

**Table 2 Variation of  $G_c$ ,  $a_c$ , and  $c_c$  as a function of  $Pr$  for  $Re_a = 0 = 1/Da, M = 1$**

Pr	$G_c$	$a_c$	$c_c$
1.0	992.52946472	1.404	0
5.0	982.99195862	1.384	0
10.0	983.55348200	1.383	0
12.6	984.09135449	1.383	0
12.7	984.09135447	1.383	0
12.8	831.82237442	0.400	$\pm 24.83007796$
13.0	769.99223337	0.420	$\pm 23.04185671$
15.0	487.16752634	0.608	$\pm 14.72510713$
20.0	301.71983348	0.820	$\pm 9.29210134$

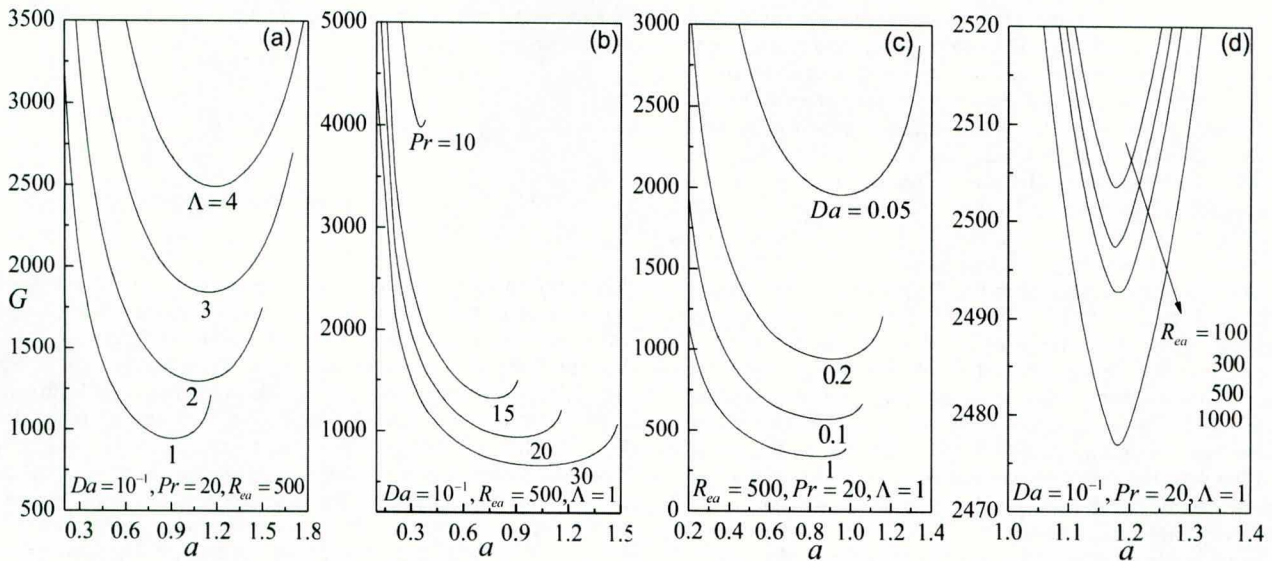


Fig. 3 Neutral stability curves

the flow in a porous medium. The solution obtained for the basic flow reveals that  $Re_a$  has no influence on the basic flow but the other parameters  $\Lambda$ ,  $Pr$ ,  $Da$ , and  $G$  alters the same significantly. Figures 2(a)–2(d), respectively, show the influence of  $\Lambda$ ,  $Pr$ ,  $Da$ , and  $G$  on the basic velocity  $W_b$ . These figures indicate that decrease in the value of  $Pr$ ,  $Da$ , and  $G$  (Figs. 2(b)–2(d)) is to suppress the fluid flow but a similar trend is noticed with increasing  $\Lambda$  (Fig. 2(a)). These figures indicate that the velocity profiles are antisymmetric about the vertical line at  $x = 0$ . However, they are not precisely centrosymmetric about  $x = \pm 1/2$ . Further inspection of the figures reveals that increase in  $Pr$ ,  $Da$ , and  $G$  while decrease in  $\Lambda$  lead to the formation of thin boundary layers near the two vertical walls.

To know the accuracy of the numerical method employed, the number of terms in the collocation method was increased. It is observed that the results remain consistent with an improved accuracy for all the parametric values considered by taking 61 terms in the Chebyshev collocation method (Table 1). In order to validate our numerical results, test computations were performed considering 61 terms under the limiting case of  $Re_a = 0 = 1/Da$  for different values of  $Pr$  and for  $M = 1$ . The critical Grashof number  $G_c$ , the critical wave number  $a_c$ , and the critical wave speed  $c_c$  computed numerically are tabulated in Table 2. From the table, it is observed that the transition from stationary to traveling-wave mode occurs when the Prandtl number  $Pr$  exceeds the value 12.7 which is in agreement with the well established results in Refs. [19–21].

Figures 3(a)–3(d) demonstrate the neutral curves on the  $(G, a)$ -plane for various values of  $\Lambda$ ,  $Pr$ ,  $Da$ , and  $Re_a$ , respectively. In the calculation, the value of  $M$  is fixed at 1. In these figures, the portion below each neutral stability curve corresponds to stable region and the region above corresponds to instability. It is seen that the neutral stability curves exhibit single but different minimum with respect to the wave number for various values of  $\Lambda$ ,  $Pr$ ,  $Da$ , and  $Re_a$ . From Fig. 3(a), it is observed that the effect of increasing  $\Lambda$  is to increase the region of stability, while an opposite trend is noticed with increasing  $Pr$  (Fig. 3(b)). Figure 3(c) exhibits that increasing  $Da$  is to decrease the region of stability and a similar effect could be seen with increasing  $Re_a$  and the same is evident from Fig. 3(d).

The critical stability parameters  $G_c$ ,  $c_c$ , and  $a_c$  are computed for different values of physical parameters to know their impact on the stability characteristics of the system. Figure 4(a) shows the variation of  $G_c$  with  $Pr$  for different values of  $Da$  when  $\Lambda = 1$  and  $Re_a = 500$ . It is important to note that the mode of instability changes with increasing  $Pr$ . There is a general reduction in the origin of the curves as the reference  $Da$  value increases. For

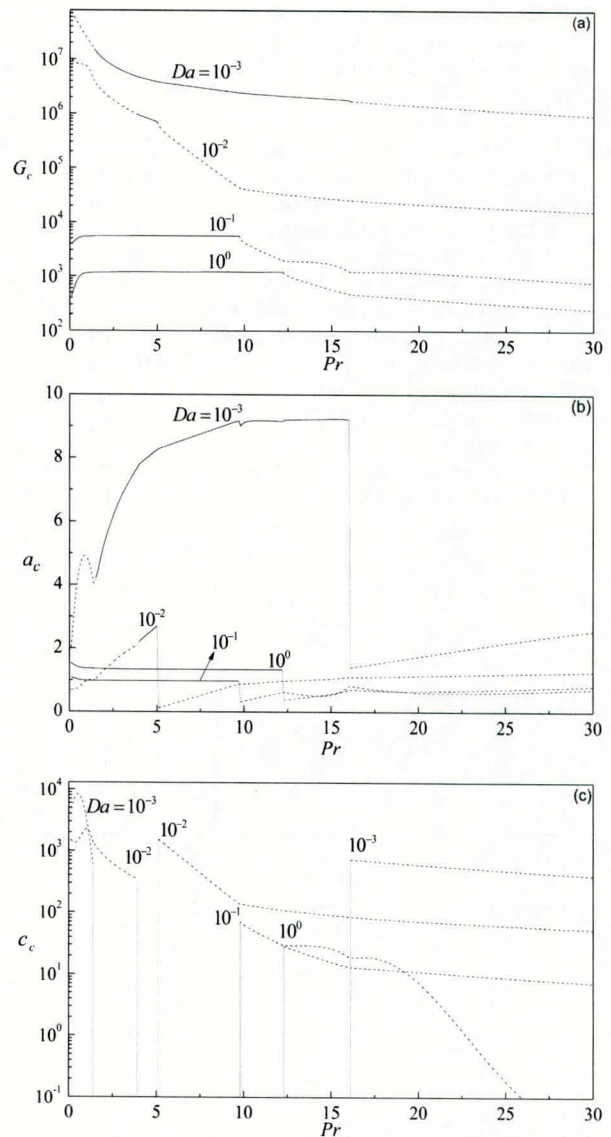


Fig. 4 Variation of (a)  $G_c$ , (b)  $a_c$ , and (c)  $c_c$  with  $Pr$  for a fixed value of  $Re_a (=500)$ ,  $\Lambda (=1)$  and for various values of  $Da$ . (—) Stationary modes, (.....) traveling-wave modes.

$Da = 10^{-3}$ , there is a sheer drop in the curve and as the curve progresses there is a reduction in its slope. The same can be seen for  $Da = 10^{-2}$ , except for the initial drop to be steeper when compared to the previous curve. Further, it is seen that the instability is via traveling-wave mode for low values of Pr when  $Da = 10^{-3}$  and switches over to stationary up to  $Pr = 16$ . With further increase in Pr, the instability transits back to the traveling-wave mode. Similar pattern (traveling-wave to stationary and again to traveling-wave mode) is observed for  $Da = 10^{-2}$ . Interestingly, the flow is predominantly traveling-wave mode, while it is stationary for a very short interval at low Pr values. As Da approaches larger multiples of 10 (i.e.,  $Da = 10^{-1}$  and  $10^0$ ), there is perceptible difference in the behavior of the curves. For both the values of Da, the curves are fairly constant and the instability switches over from stationary to traveling-wave mode at some threshold value of Pr. Such a weak influence of Pr on  $G_c$  at stationary mode is another indication that buoyancy forces are the dominant source of instability. But they experience a drop in  $G_c$  with increasing Pr. In other words, the Prandtl number shows no significant effect if the disturbances are stationary, while its effect is significant if the disturbances are via traveling-wave modes. From Fig. 4(a), it is also noticed that decrease in the value of Da is to increase the value of  $G_c$  and thus it has a stabilizing effect on the system. This may be attributed to the fact that decreasing Da amounts to decrease in the permeability of the porous medium, which in turn retards the fluid flow.

Figure 4(b) illustrates the variation of  $a_c$  as a function of Pr for different values of Da when  $\Lambda = 1$  and  $R_{ea} = 500$ . These graphs show irregular behavior for different referable Da values. With  $Da = 10^{-3}$ , there is a sharp rise in the graph, for lower values of Pr. As Pr approaches the value 16, a vertical drop followed by a gradual rise in the curve is observed. For values of Pr lesser than 10 and at  $Da = 10^{-2}$ , the curve rises and falls in a triangular fashion and increases gradually to almost a horizontal curve thereafter. Curves for  $Da = 10^{-1}$  and  $10^0$  show similar behavior. The curves are of constant  $a_c$  values in the stationary mode, and after undergoing a mild drop, continue to move as horizontal curves. Corresponding  $c_c$  summarized in Fig. 4(c), indeed confirm the above observed behavior more evidently. The vertical lines represent the discontinuous changes in  $c_c$  due to the transition from stationary to traveling-wave mode.

Furthermore, streamlines and isotherms at the critical state for both stationary and traveling-wave modes are analyzed. The

stream lines and isotherms are drawn, respectively from the following expressions:

$$\Psi = \sum_{j=0}^N (\text{Re}(\Psi_j) \cos az - \text{Im}(\Psi_j) \sin az) \zeta_j(x), \quad (14)$$

$$\Theta = \sum_{j=0}^N (\text{Re}(\Theta_j) \cos az - \text{Im}(\Theta_j) \sin az) \zeta_j(x)$$

where  $\Psi_j$ 's and  $\Theta_j$ 's are the eigenvectors and  $\zeta_j(x)$  is a Chebyshev polynomial of order  $j$ . In all contour plots, dashed lines denote negative values whereas solid lines stand for positive values. Figures 5 and 6 show the results for different values of Pr when  $\Lambda = 1$ ,  $R_{ea} = 500$ , and  $Da = 10^{-1}$ . The streamlines and isotherms are shown in Figs. 5(a)–5(d) and 6(a)–6(d), respectively, for  $Pr = 3.8, 4.0, 4.9$ , and  $5.1$ . The pattern appears to be stationary bicellular convection in streamlines, whereas in isotherms similar to bicellular oblate triangles are observed. It is also observed that the magnitude of secondary flow is very weak. Nonetheless, it is seen that the flow strength suddenly changes only qualitatively but not quantitatively in both streamlines and isotherms once the value of Pr increases from 9.6 (Figs. 5(e) and 6(e)) to 9.8 (Figs. 5(f) and 6(f)). Also, there is a sudden increase in wavelength and this confirms that transition mode occurs at that point.

Figures 7(a)–7(f) exhibit the evolution of streamline patterns for various values of Pr when  $\Lambda = 1$ ,  $R_{ea} = 500$ , and  $Da = 10^{-2}$ . For  $Pr = 3.8$ , the streamlines are concentrated at the geometrical center of the fluid cross section and mild ripples are observed toward the left (Fig. 7(a)). The streamlines shown in Fig. 7(b) for  $Pr = 4.0$ , the value at which transition from traveling-wave to stationary mode takes place, are more or less mirror image of streamlines presented in Fig. 7(a) for  $Pr = 2$  but the strength of the secondary flow is found to increase marginally. The streamlines shown in Fig. 7(c) for an increased value of  $Pr = 4.9$  reveals that the undulations observed in Figs. 7(a) and 7(b) seem distributed on either sides of the origin. The flow pattern and flow strength changes qualitatively as well as quantitatively as the instability changes from stationary to traveling-wave mode with further increase in the value of Pr. In other words, the instability switches over from stationary to traveling-wave mode once the value of Pr exceeds the value 5.0. When  $Pr = 5.1$ , it is observed that the convective motion is constructed by two parts, one is the vigorous cell in the right half of

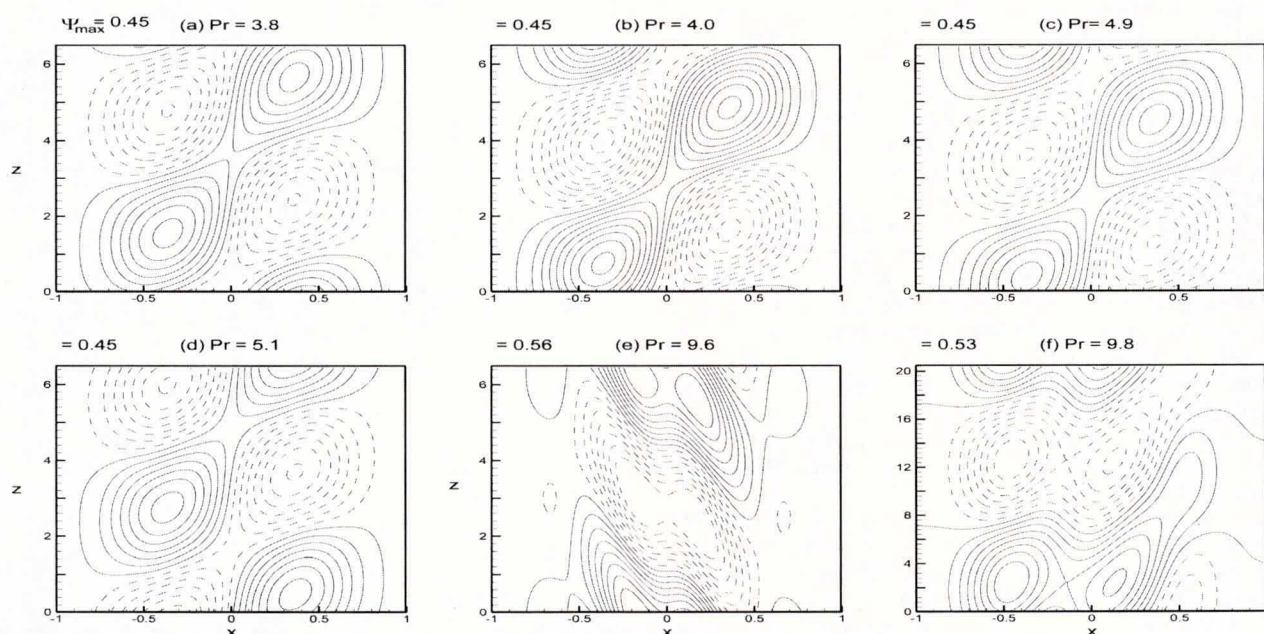


Fig. 5 The disturbance streamlines for different values of Pr when  $\Lambda = 1$ ,  $R_{ea} = 500$ , and  $Da = 10^{-1}$

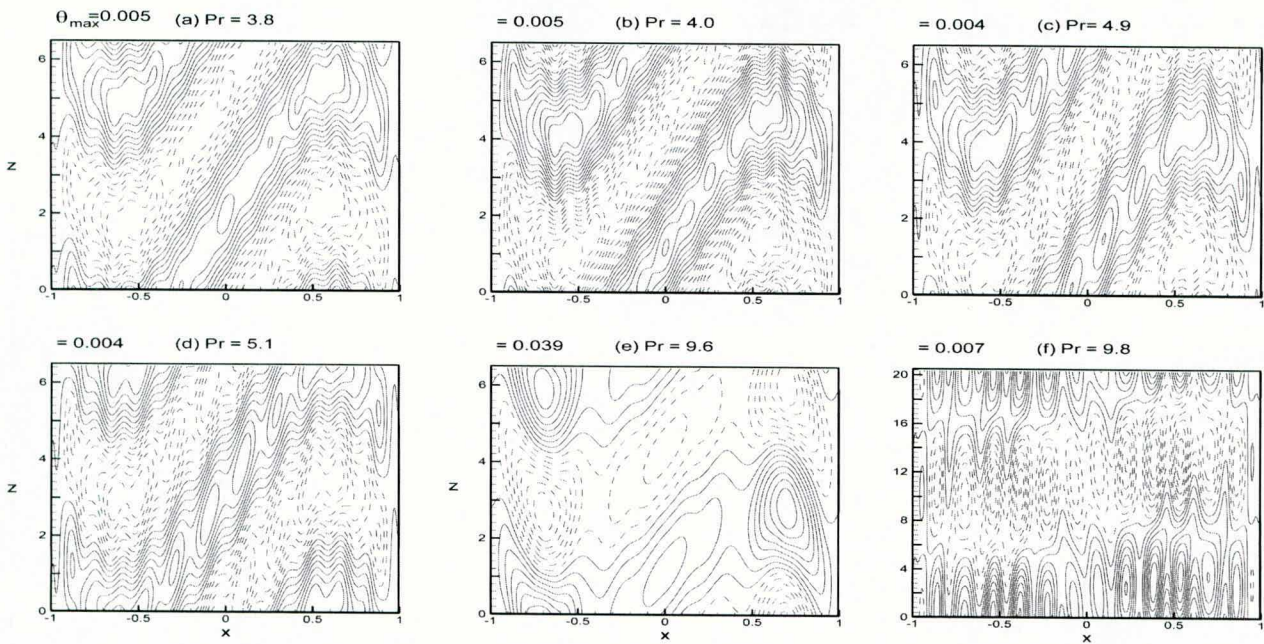


Fig. 6 The disturbance isotherms for different values of  $Pr$  when  $\Lambda = 1$ ,  $Re_a = 500$ , and  $Da = 10^{-1}$

the porous layer adjacent to the right surface, the other is the weak circulation which is exterior to the vigorous convection cell. This is evident from Fig. 7(d). It is further seen that the actual wavelengths are substantially larger in streamlines and at this stage  $\Psi_{max}$  increases from 0.41 to 0.69. Further increase in  $Pr$  is to decrease the wavelength and increase in flow strength (Figs. 7(e) and 7(f)).

Figures 8(a) and 8(b) illustrate the variation of  $G_c$  and  $a_c$  as a function of  $Pr$  for different values of  $Re_a$  when  $\Lambda = 1$  and  $Da = 10^{-1}$ . Figure 8(a) reveals that the magnitude of the basis of the curve and the peaks increase as  $Re_a$  increases at lower values of  $Pr (< 1)$ . Further increase in  $Pr$ , the peak disappears and the curves for all values of  $Re_a$  come together up to  $Pr = 9.7$ . Thereafter, there is a vertical followed by a parabolic drop in the  $G_c$  value for all the values of  $Re_a$ . In other words,  $Pr$  shows no significant effect if the disturbances are stationary. This may be due to the fact that the energy for stationary instability at low to moderate  $Pr$  is derived mainly from the base flow velocity field

through the action of disturbance Reynolds stresses at the mid-plane between the upward and the downward flowing convective streams. Whereas the effect of  $Pr$  becomes significant if the disturbances are traveling-wave mode. Although the effect of increasing  $Re_a$  is to instill instability on the system but its influence is found to be not so significant. That is, higher the electric field strength the less stable the system due to an increase in the destabilizing electrostatic energy to the system. Figure 8(b) demonstrates that the origin of the curve is lower for lower values of  $Re_a$  and increases with the latter for  $Pr < 1$ . Further, the curves of different  $Pr$  and  $Re_a$  coalesce until  $Pr = 9.7$  and then there is a sudden massive drop in its value and it then increases almost logarithmically. This indicates two different physical mechanisms of instability. As  $Pr$  increases, there is a tendency for more of the disturbance energy to originate from the potential energy associated with the buoyancy effect than as transfer from the kinetic energy of the base flow by the action of Reynolds stresses.

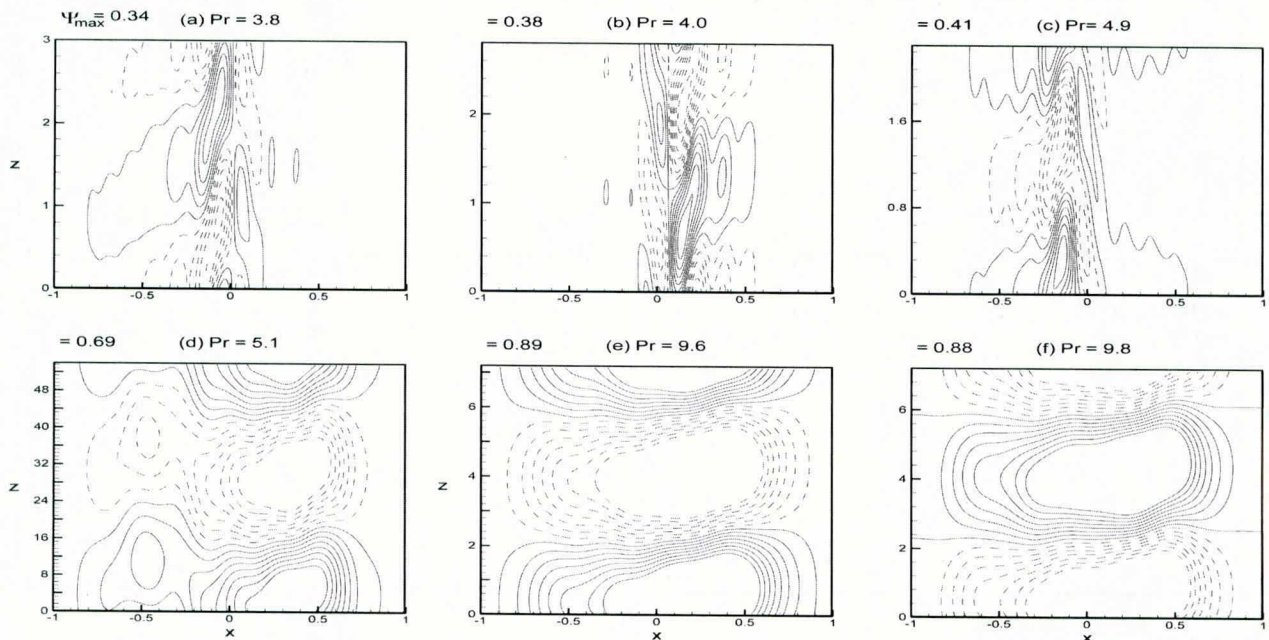
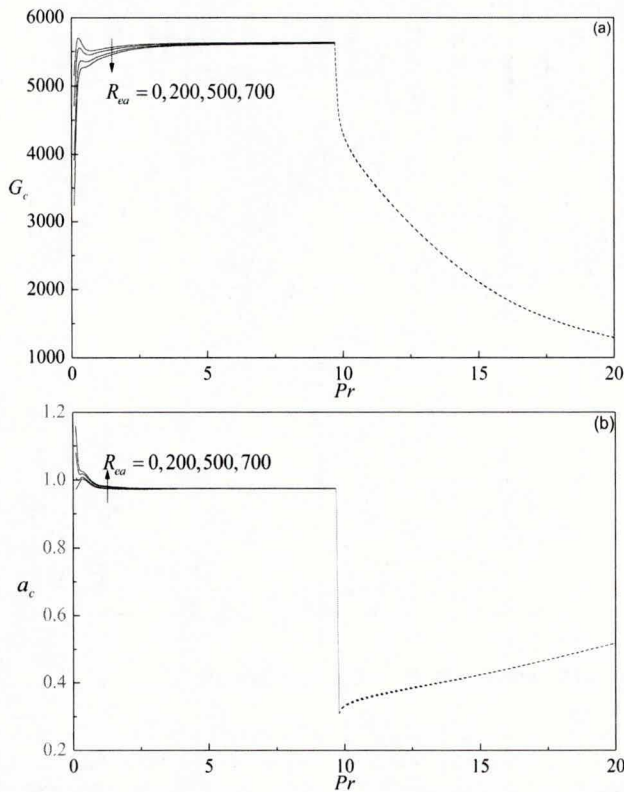
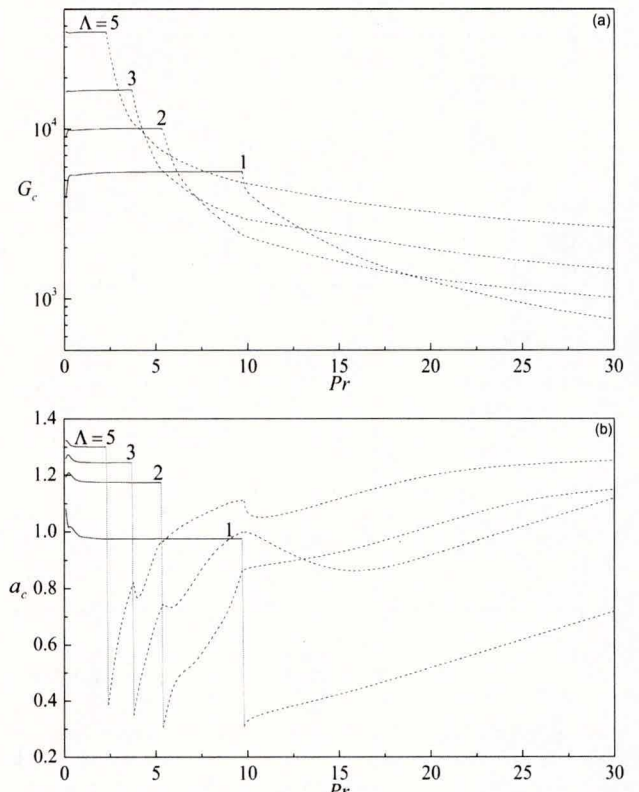


Fig. 7 The disturbance streamlines for different values of  $Pr$  when  $\Lambda = 1$ ,  $Re_a = 500$ , and  $Da = 10^{-2}$



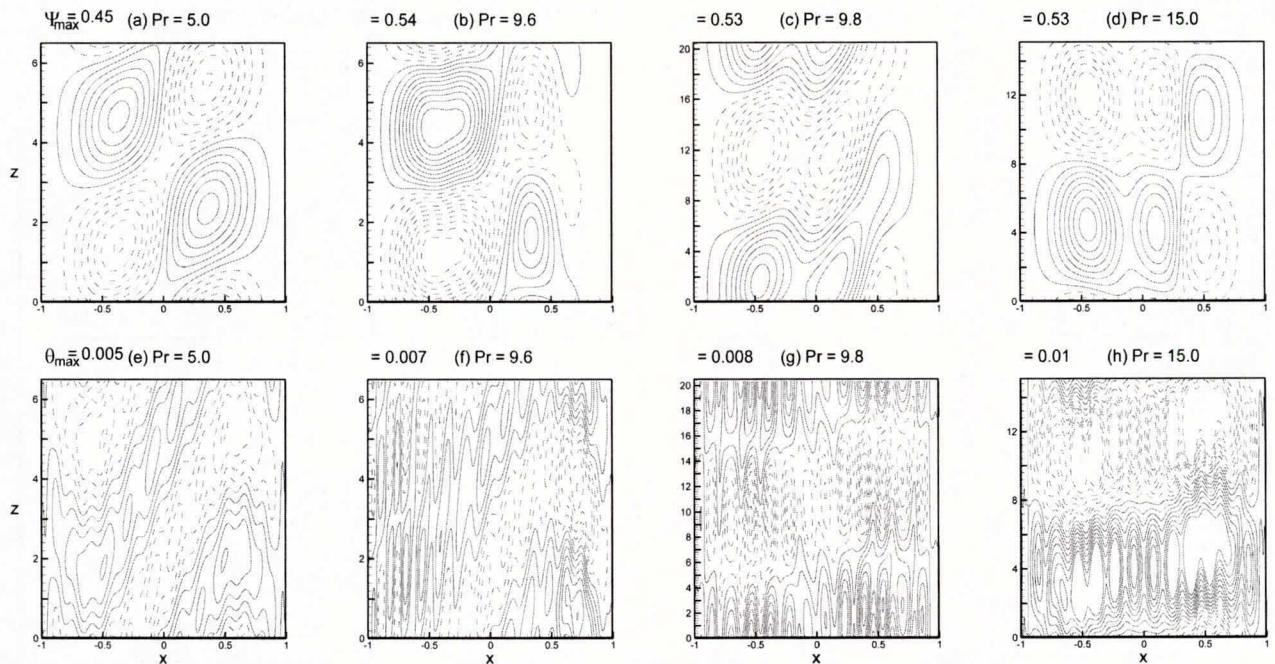
**Fig. 8** Variation of (a)  $G_c$  and (b)  $a_c$  with  $Pr$  for a fixed value of  $Da (= 10^{-1})$ ,  $\Lambda (= 1)$  and for various values of  $Re_a$ . (—) Stationary modes and (.....) traveling-wave modes.

To know the influence of  $Pr$  and  $Re_a$  on the disturbance flow and temperature, the corresponding streamlines and isotherms at the critical state for both stationary and traveling-wave modes are displayed in Fig. 9 for different values of  $Pr$  when  $\Lambda = 1$ ,  $Re_a = 200$ , and  $Da = 10^{-1}$ . For  $Pr = 5$  and  $9.6$ , the flow pattern appears to be stationary bicellular in both streamlines and isotherms as shown in Figs. 9(a), 9(b) and 9(e), 9(f), respectively. An abrupt change could



**Fig. 10** Variation of (a)  $G_c$  and (b)  $a_c$  with  $Pr$  for a fixed value of  $Re_a (= 500)$ ,  $Da (= 10^{-1})$  and for various values of  $\Lambda$ . (—) Stationary modes and (.....) traveling-wave modes.

be seen in stability profile as the instability mode changes from stationary to traveling-wave mode. Here, the flow pattern changes qualitatively but not quantitatively as the mode changes from stationary to traveling-wave mode. In other words, the instability switches over from stationary to traveling-wave mode once the value of  $Pr$  exceeds  $9.6$ . When  $Pr = 9.8$ , convective cells transform into unicellular from bicellular in streamlines (Fig. 9(c)). In



**Fig. 9** The disturbance streamlines (a)–(d) and isotherms (e)–(h) for different values of  $Pr$  when  $\Lambda = 1$ ,  $Da = 10^{-1}$ , and  $Re_a = 200$

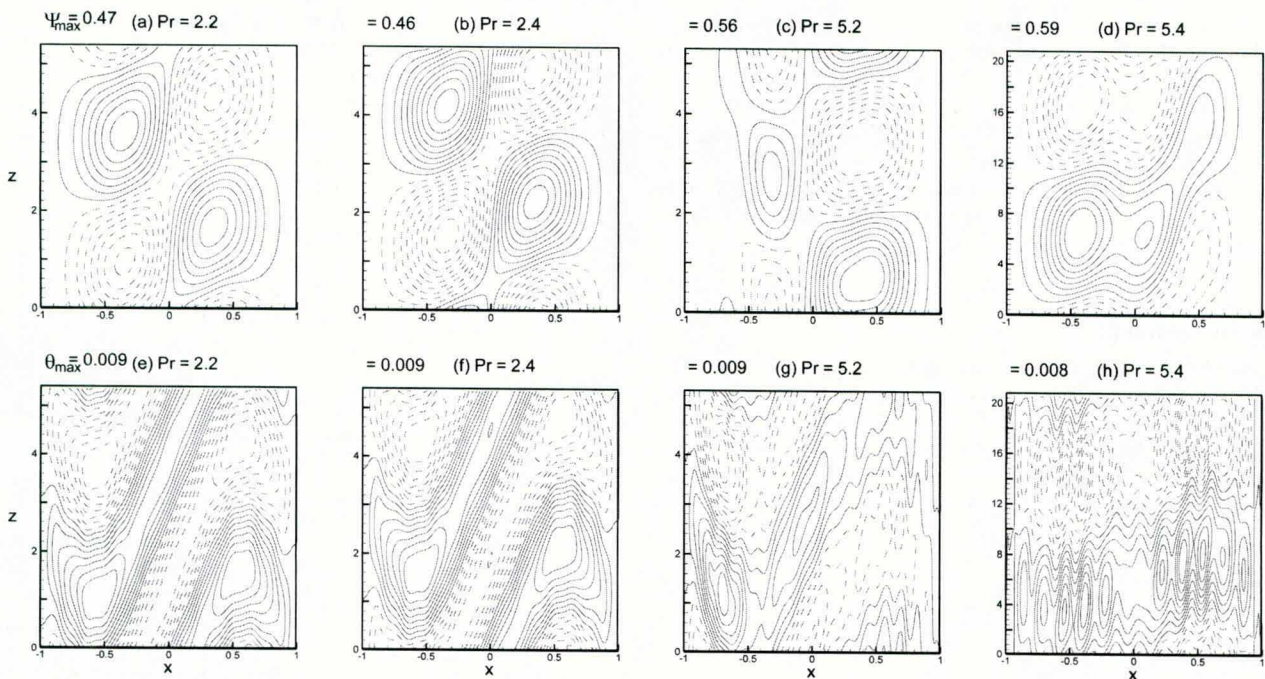


Fig. 11 The disturbance streamlines (a)–(d) and isotherms (e)–(h) for different values of Pr when  $\Lambda = 2$ ,  $Da = 10^{-1}$ ,  $Re_a = 500$

isotherms, a flurry of activity is noticed as observed in Fig. 9(g). Cells of various patterns and shapes are seen throughout the spread of the porous layer. Similar behavior is observed in both streamlines and isotherms when  $Pr = 15$  (Figs. 9(d) and 9(h)). It is also observed that the change in streamline and isotherm patterns remains unaltered with increasing values of  $Re_a$ .

The porous materials used in many technological applications of practical importance possess high permeability values. For example, permeabilities of compressed foams as high as  $8 \times 10^{-6} \text{ m}^2$  and for a 1 mm thick foam layer the equivalent Darcy number is equal to 8 (see Ref. [22] and references therein). Moreover, for such a high porosity porous medium, Givler and Altobelli [23] determined experimentally that  $\mu_e = 7.5^{+3.4}_{-2.4} \mu$ , where  $\mu_e$  is the effective viscosity or the Brinkman viscosity and  $\mu$  is the fluid viscosity. Therefore, the ratio of these two viscosities is considered to be different from unity in analyzing the problem. The variation of  $G_c$ ,  $a_c$ , and  $c_c$  with Pr is shown in Fig. 10 for different values of  $\Lambda$  when  $Re_a = 500$  and  $Da = 10^{-1}$ . Depending on the value of  $\Lambda$ , there exists a threshold value of Pr at which the instability switches over from stationary to traveling-wave mode (Fig. 10(a)). Moreover, the threshold value of Pr increases noticeably with decreasing  $\Lambda$ . In the stationary mode, decreasing  $\Lambda$  will lead to the decrease in  $G_c$  and thus it has a destabilizing effect on the system. This is because, increasing  $\Lambda$  amounts to increase in the viscous effect, which in turn retards the fluid flow. However,  $\Lambda$  shows a dual behavior on  $G_c$  if the instability is via traveling-wave mode. It is also seen from the figure that the dependence of  $G_c$  upon Pr is very weak in the case of stationary mode, while  $G_c$  at traveling-wave mode is a strongly decreasing function of Pr. The vertical lines represent discontinuous changes in  $a_c$  due to the transition from stationary to traveling-wave mode (Fig. 10(b)). It is evident from the figure that the dependence of  $a_c$  at stationary mode upon Pr is weak, whereas  $a_c$  at traveling-wave mode depends strongly upon Pr. It is also seen from Fig. 10(b) that as  $\Lambda$  decreases  $a_c$  decreases at stationary mode, whereas it exhibits a twin behavior at traveling-wave mode.

The streamlines and isotherms are displayed for representative values of physical parameters considered in Fig. 10. Figures 11(a)–11(d) and 11(e)–11(h) exhibit streamlines and isotherms before and after the transition mode as a function of Pr for  $\Lambda = 2$ ,  $Da = 10^{-1}$ , and  $Re_a = 500$ . For  $Pr = 2.2, 2.4$ , and  $5.2$ , the flow pattern appears to be as stationary and bicellular. Further, the

streamlines move closer and appear to be parallel at the center of the vertical porous layer (Figs. 11(a)–11(c)). The corresponding isotherms are shown in Figs. 11(e)–11(g). It can be seen that bicellular oblate triangle cells occupy the whole thickness of vertical porous layer. The instability switches over from stationary to traveling-wave mode once the value of Pr exceeds the value 5.2. When  $Pr = 5.4$ , convective cells transform into unicellular from bicellular in streamlines (Fig. 11(d)) whereas in isotherms, it appears as though the cells move out in a ripple like manner from the center of the fluid cross section (Fig. 11(h)). It is further seen that the actual wavelengths are substantially larger in both streamlines and isotherms. Interestingly, change in  $\Psi_{\max}$  and  $\theta_{\max}$  is marginal at this stage. Same observations are noticed with increase in  $\Lambda$  at the critical state.

## 6 Conclusions

The following conclusions can be drawn from the foregoing study:

- (i) Although the basic flow is independent of  $Re_a$ , it is significantly influenced by  $\Lambda$ , Pr, Da, and  $G$ .
- (ii) The decrease in the value of Da is to reinforce stability on the system. A definite single threshold value of Pr exists denoting transition from stationary to traveling-wave mode for  $Da = 10^0$  and  $10^{-1}$  and this threshold value increases as Da decreases. Nonetheless, for  $Da = 10^{-2}$  and  $10^{-3}$ , there is an abrupt change in the flow pattern exists with increasing Pr (i.e., instability switches over from traveling-wave to stationary mode and again it transits back to traveling-wave mode). In other words, there is a range of Pr in which the instability is via stationary mode and this range of Pr increases with the decrease in the value of Da.
- (iii) The ratio of viscosities  $\Lambda$  shows stabilizing effect on the system at the stationary mode. To the contrary, it exhibits a dual behavior if the instability is via traveling-wave mode. Moreover, the value of Pr at which transition occurs from stationary to traveling-wave mode increases as the value of  $\Lambda$  decreases.
- (iv) Increase in the AC electric Rayleigh number  $Re_a$  is to destabilize the flow due to increasing destabilizing electrostatic energy but its effect is found to be not so significant. The



value of Pr at which transition from stationary to traveling-wave instability occurs and the critical wave number remain invariant for all values of AC electric Rayleigh number.

- (v) The magnitudes of secondary flows (streamlines and isotherms) confirm the behavior of stability curves observed before and after the change of mode of instability. For the range of parametric values considered, convective cells are found to appear in unicellular, bicellular as well as multicellular in nature.

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## Nomenclature

- $a$  = vertical wave number  
 $c$  = wave speed  
 $c_r$  = phase velocity  
 $c_i$  = growth rate  
 $D$  = differential operator  
 $Da = K\varphi_p^2/h^2$  = Darcy number  
 $E$  = root-mean-square value of the electric field  
 $E_0$  = root-mean-square value of the electric field at  $x = 0$   
 $\mathbf{f}_e$  = force of electrical origin  
 $\mathbf{g}$  = acceleration due to gravity  
 $G = \alpha g \varphi_p^2 \beta h^4 / \nu^2$  = Grashof number  
 $h$  = thickness of the dielectric porous layer  
 $\hat{k}$  = unit vector in z-direction  
 $K$  = permeability of the porous medium  
 $P$  = modified pressure  
 $Pr = \nu/\kappa$  = Prandtl number  
 $\mathbf{q} = (u, v, w)$  = velocity vector  
 $R_{ca} = \gamma^2 \varphi_p^2 \varepsilon_0 E_0^2 \beta^2 h^4 / \mu \kappa$  = AC electric Rayleigh number  
 $t$  = time  
 $T_1$  = temperature of the left boundary  
 $T_2$  = temperature of the right boundary  
 $V$  = root-mean-square value of the electric potential  
 $V_1$  = electric potential of the left boundary  
 $V_2$  = electric potential of the right boundary  
 $W_b$  = basic velocity  
 $(x, y, z)$  = Cartesian co-ordinates

## Greek Symbols

- $\alpha$  = volumetric thermal expansion coefficient  
 $\beta$  = temperature gradient  
 $\gamma$  = thermal expansion coefficient of dielectric constant  
 $\varepsilon$  = dielectric constant  
 $\varepsilon_0$  = reference dielectric constant at  $T_0$   
 $\theta$  = temperature  
 $\Theta$  = amplitude of perturbed temperature  
 $\kappa$  = thermal diffusivity  
 $\Lambda = \varphi_p^2 \mu_e / \mu$  = ratio of effective viscosity to the fluid viscosity  
 $\mu$  = fluid viscosity  
 $\mu_e$  = effective viscosity

- $\nu = \mu/\rho_0$  = kinematic viscosity  
 $\rho$  = fluid density  
 $\rho_e$  = free charge density  
 $\rho_0$  = reference density at  $T_0$   
 $\sigma$  = electrical conductivity of the fluid  
 $\Phi$  = amplitude of perturbed electric potential  
 $\varphi_p$  = porosity of the porous medium  
 $\chi$  = ratio of heat capacities  
 $\psi$  = stream function  
 $\Psi$  = amplitude of vertical component of perturbed velocity

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