Int. J. of Mathematical Sciences and Applications, Vol. 1, No. 3, September 2011 Copyright © Mind Reader Publications <u>www.journalshub.com</u>

# RADIUS-VITAL EDGES IN A GRAPH

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## Abstract:

The graph resulting from contracting edge "e" is denoted as G/e and the graph resulting from deleting edge "e" is denoted as G-e. An edge "e" is radius-essential if rad(G/e) < rad(G), radius-increasing if rad(G-e)>rad(G), and radius-vital if it is both radius-essential and radius-increasing. We partition the edges that are not radius-vital into three categories. In this paper, we study realizability questions relating to the number of edges that are not radius-vital in the three defined categories. A graph is radius-vital if all its edges are radius-vital. We give a structural characterization of radius-vital graphs.

Keywords: Radius-vital edges, radius-increasing edges, radius-essential edges

## AMS Classification 2010: 05C12

## **1.Introduction:**

The terminology used throughout this paper is based on Buckley and Harary [1], Harary[3].

Let G be a connected graph with vertex set V(G) and edge set E(G) with p and q representing order and size of G. The distance d(u,v) between vertices u and v is the length of a shortest path joining u and v. The eccentricity e(v) of v is the distance to a farthest vertex from v. The radius rad(G) and diameter diam(G) are minimum and maximum eccentricities, respectively. The center C(G) and P(G), periphery of a graph G consists of the sets of vertices of minimum and maximum eccentricity, respectively. Vertices in C(G) are called central vertices and those in P(G) are called the peripheral vertices. An elementary contraction of an edge e=uv in G is obtained by removing u and v, inserting a new vertex w and inserting an edge between w and any vertex to which either u or v (or both) were adjacent and G/e denotes the resulting graph. The graph resulting from deleting edge e is denoted by G-e.

As in [1], the sequential join  $G_1+G_2+G_3+....+G_k$  of graphs  $G_1, G_2, ..., G_k$  is the graph formed by taking one copy of each of the graphs  $G_1, G_2, ..., G_k$  and adding in additional edges from each vertex of  $G_i$  to each vertex in  $G_{i+1}$ , for  $1 \le i \le k-1$ .

An edge *e* is *radius-essential* if rad(G/e) < rad(G) and *radius-increasing* if

rad(G-e) > rad(G). We studied *radius-essential edges* in [9]. If every edge in a graph G is *radius-increasing*, then G is a *radius-minimal graph*. Gliviak [2] established various existence results for radius-minimal graphs. **Definition 1.1:** An *edge e* is *radius-vital* if it is both *radius-essential* and *radius-increasing*; otherwise, it is *radius-non-vital*.

Thus, a radius-vital edge e has the property that contracting e decreases the radius and deleting e increases the radius.

An edge *e* is *deletable* if its deletion does not alter the radius, that is, rad(G-e) = rad(G). (Gliviak [2] refers such edges *superflous*). An edge *e* is *contractible* if its contraction does not alter the radius, that is, rad(G/e) = rad(G). In view of these definitions, we can partition E(G) into four sets:

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 $\begin{array}{ll} \textit{radius-vital edges:} & E_v(G) = \{e: \ \textit{rad}(G/e) < \textit{rad}(G) \ \textit{and} \ \textit{rad}(G-e) > \textit{rad}(G)\}, \\ \textit{contracible, radius-increasing edges:} & E_c(G) = \{e: \ \textit{rad}(G/e) = \textit{rad}(G) \ \textit{and} \ \textit{rad}(G-e) > \textit{rad}(G)\}, \\ \textit{deletable, radius-essential edges:} & E_d(G) = \{e: \ \textit{rad}(G-e) = \textit{rad}(G) \ \textit{and} \ \textit{rad}(G/e) < \textit{rad}(G)\}, \\ \end{array}$ 

and

*contractible and deletable edges:*  $E_{cd}(G) = \{e: rad(G-e) = rad(G) and rad(G/e) = rad(G)\}$ .

An edge *e* is radius-non-vital(non-vital), if  $e \in E_c(G) \cup E_d(G) \cup E_{cd}(G)$ .

In this paper, we shall study the vital and non-vital edges of graphs. After characterizing graphs for which every edge is vital, we examine realizability questions relating to the sizes of the sets  $E_c(G)$ ,  $E_d(G)$  and  $E_{cd}(G)$  and study which triples (*x*, *y*, *z*) of integers are realizable for ( $|E_c(G)|, |E_d(G)|, |E_{cd}(G)|$ ).

We mention that a similar study was done for 3-connectedness in graphs. Reid and Wu[6] studied edges "e" in 3-connected graphs for which either deletion of "e" or the contraction of "e", but not both, alters the 3-connectedness of the graph.

Definition 1.2: A graph G is radius-vital if all its edges are radius-vital.

We recall some results from Walikar, Buckley and Itagi[9]. Let  $\sigma_r(G)$  be the number of essential edges in G. That is,

 $\sigma_r(G) = |\{e \in E(G): rad(G/e) < rad(G)\}|.$ 

Since an essential edge is not contractible,  $\sigma_r(G) = |E_v(G)| + |E_d(G)|$ .

Let p and q denote the number of vertices and edges, respectively, in G. We shall need the following.

**Proposition 1.3[2]:** A non-trivial graph is radius minimal if and only if G is a tree.

**Proposition 1.4[9]** : For a tree T,  $\sigma_r(G) = q$ , if and only if T is a path on even number of vertices.

#### 2.Results:

The following result characterizes radius-vital graphs.

**<u>Proposition 2.1:</u>** Let G be a graph with rad(G)=r. Then G is radius-vital if and only if G is a path on even number of vertices.

**Proof:** A non-trivial graph G is radius-minimal if and only if G is a tree, by Proposition 1.1[2]. By Proposition 1.2[9],  $\sigma_r(T) = q$  if and only if T is a path on even number of vertices. Combining the two results the proof follows.

We now focus on the non-vital edges of a graph. We begin with a definition and several preliminary observations.

**Definition 2.2:** For any three non-negative integers x, y, z, a graph G is said to be an (x, y, z)-graph, if  $|E_c(G)| = x$ ,  $|E_d(G)| = y$  and  $|E_{cd}(G)| = z$ , and the triple (x, y, z) is realizable if there exists an (x, y, z)-graph G.

By Proposition 2.1, it is clear that only (0, 0, 0) graphs are paths on even number of vertices.

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**<u>Remark 2.3</u>**: If  $\sigma_r(G)=0$ , then all edges are contractible no matter whether they are deletable or not. Hence G contains no vital edges. Therefore, if G is an (x, y, z)- graph with  $\sigma_r(G)=0$ , we have y = 0 and x + z = q.

A graph G is a radius-edge-invariant graph (r.e.i. graph) if for each  $e \in E(G)$ , rad(G-e) = rad(G), that is, every

edge of G is deletable. Refer Walikar, Buckley and Itagi [8] for detailed study of these graphs.

**<u>Remark 2.4</u>**: If  $\sigma_r(G) = q$ , then no edge of G is contractible. Hence x = z = 0 and  $y \le q$ . If y = q, then G is radiusedge-invariant, otherwise, there exists at least one vital edge in G.

**<u>Remark 2.5:</u>** If G is radius-edge-invariant graph then every edge is deletable, so there are no vital edges in G. Thus, for a r.e.i. graph, x = 0 and y + z = q.

**<u>Remark 2.6</u>**: If G is radius-minimal then no edge is deletable. Hence y = z = 0 and  $x \le q$ . Thus for a diameter minimal graph G, if  $\sigma_r(G) = 0$ , then x = q and if  $\sigma_r(G) > 0$ , there exists at least one vital edge.

Next we consider realizability of triple of integers.

**Lemma 2.7:** *The triple* (0,1,0) *is not realizable.* 

**Proof:** On the contrary assume that (0, 1, 0) is realizabe. Then there exists a graph G, containing only one edge, say  $e \in$ 

 $E_d(G)$ . Then (i) rad(G-e) = rad(G) and (ii) rad(G/e) < rad(G) hold. And all other edges e' in G are vital, hence (i') rad(G-e') > rad(G) and (ii') rad(G/e') < rad(G). From (ii) and (ii') it follows that  $\sigma_r(G) = q$ . Hence, for e, there exists a radius-preserving spanning tree which avoids e. But this edge can be contracted too without altering the radius of G, a contradiction to the fact that  $\sigma_r(G) = q$ .

**Lemma 2.8:** The triple (x, 0, 0) is realizable, for all  $x \ge 0$ .

**Proof:** If x = 0, then by *Proposition 2.1*, *G* is a path on even number of vertices. For  $x \ge 1$ , consider a graph *G*, obtained by joining *x* pendent edges to any one of the central vertices of path  $P_{2n}$ ,  $n \ge 3$ . Clearly, this graph has *x* edges belonging to  $E_c(G)$  and rest all vital. Hence the result.

**Lemma 2.9:** The triple (x, 1, 0) is not realizable for all values of  $x \ge 0$ .

**Proof:** On the contrary assume that the triple is realizable. Hence there exists a graph G containing one edge, say e, e

 $\in E_d(G)$  and "x" edges belonging to  $E_c(G)$ , that is,  $\sigma_r(G) = q$ -x. For e, there exists a radius-preserving spanning tree,

which does not contain e, as rad(G-e) = rad(G). By contraction of this edge radius remains unaltered contradicting the fact that the edge

 $e \in E_d(G)$ , proving the result.

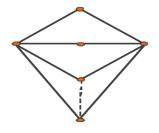
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**Lemma 2.10:** The triple (0,y,0) is realizable for y = 2m,  $m \ge 2$ , or y = 2k + mn,  $k \ge 2$ ,  $m \ge 2, n \ge 1$  or y = mn,  $m \ge 2, n \ge 1$ .

**Proof:** To show that (0, y, 0) is realizable, it is sufficient to show the existence of a graph for values given in the

hypothesis. For y = 0, the realizability follows from *Proposition 2.1*. It is clear that an edge  $e \in E_d(G)$  edge lies on a

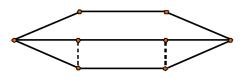
block of *G*. Since x = z = 0, all other edges of *G* must be vital. For different values of "y", we have different structure of blocks containing "y" edges. If y is even <u>i.e.</u>  $y \ge 2m$ ,  $m \ge 2$ , consider a graph  $G_1 = K_1 + \overline{K_m} + K_1$ ,  $m \ge 2$ , as in Figure 1.





For the graph of Figure 2, all 2m edges belong to  $E_d(G)$ . Hence  $G_1$  is a (0, y, 0) graph.

For y = mn,  $m \ge 2$ ,  $n \ge 1$ , consider a graph  $G_2 = K_1 + \overline{K_m} F \overline{K_m} + K_1$ , where F denotes the one factor between  $\overline{K_m}$  and  $\overline{K_m}$  as in Figure 2.





 $G_2$  is an (0, y, 0) graph as all 3m edges are deletable, radius-increasing.

Next consider a graph  $G_3 = K_1 + \overline{K_m} F \overline{K_m} F \overline{K_m} + K_1$ , where F denotes one factor between two consecutive  $\overline{K_m}$ 's, as in Figure 3.

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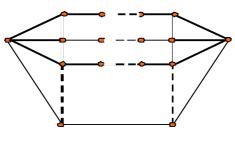
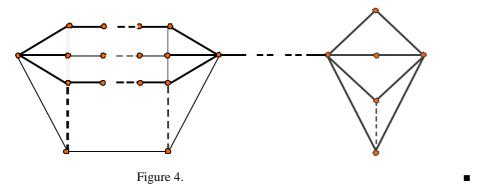


Figure 3

Clearly  $G_3$  is an (0, y, 0)-graph for y = mn,  $m \ge 2$ ,  $n \ge 2$ , as all mn edges of  $G_3$  belong to  $E_d(G)$ . Hence any combination of the above discussed values of "y" can be realized for (0, y, 0). So the realizing graph will be as shown in Figure 4.



**Lemma 2.11:** The triple (x, y, 0) is realizable for  $x \ge 0$ ; y = 2m, or y = 2k + mn,  $k \ge 2$ ,  $m \ge 2$ ,

 $n \ge 1$ , or y = mn,  $m \ge 2$ ,  $n \ge 1$ .

**Proof:** Consider the graph G of *Figure 1*. Join "x" pendent edges at any one of the vertices of degree m, to get an  $G_1'=(x, y, 0)$ - graph for  $y \ge 2m$ ,  $m \ge 2$ . Clearly, contraction of these pendent "x" edges does not alter radius of  $G_1'$ . Similarly, to each of  $G_2, G_3, G_4$  of above Lemma 2.10, we can join "x" pendent edges at any vertex whose degree is not equal to two, to get graphs  $G_2', G_3', G_4'$  which are (x, y, 0) graphs for different values of "y". We note that  $G_2'$  is (x, 3m, 0)-graph,  $G_3'$  is (x, mn, 0)-graph and  $G_4'$  is (x, 2k+mn, 0)- graph.

Lemma 2.12: The triple (0,0,1) is not realizable.

**Proof:** Suppose, (0, 0, 1) is realizable, let *G* be the realizing graph. In *G*, let "*e*" be the only edge such that rad(G-e) = rad(G) = rad(G/e). *G* cannot contain only one edge as  $K_2$  is neither deletable nor contractible. Hence all other edges of *G* must be vital. Since, rad(G/e) = rad(G), for some central vertex, *say u*, there are at least two eccentric vertices say  $u_1$  and  $u_2$ , joined by disjoint paths. Hence if "*e*" lies on any one path, say  $u-u_1$  path, then any other edge of  $u-u_2$  path can also be contracted without altering the radius of *G*. This contradicts the fact that *G* contains only one radius-vital edge and hence the result.

**Lemma 2.13:** The triple (0, 0, z) is realizable except for z = 1.

**Proof:** From *Proposition 2.1, (0, 0, 0)* is realizable. From above lemma, *(0, 0, 1)* is not realizable. For  $z \ge 2$ , consider a graph *G* obtained by identification of each end vertex of a path  $P_n$  with each one central vertex of a path  $P_{2n-4}$ . The graph so obtained is as in Figure 5.

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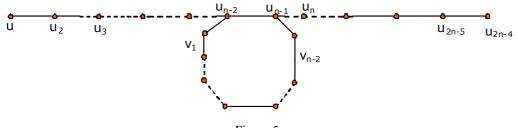


Figure 5

Label the vertices of *G* as in Figure 5. So rad(G) = n-2. Clearly, the edges of the form  $u_iu_{i+1}$ ,  $1 \le i \le 2n-4$ , are vital. Edges of the form  $v_iv_{i+1}$ ,  $v_1u_{n-2}$ ,  $v_{n-2}u_{n-1}$ , belong to  $E_{cd}(G)$  and there is no edge belonging to  $E_c(G)$  and  $E_d(G)$ . Hence by taking z=n-1, the triple (0, 0, z) is realizable, for  $z \ge 2$ .

**Lemma 2.14:** The triple (x, 0, z) is realizable for all  $x \ge 0$ ,  $z \ge 0$ .

**<u>Proof</u>**: For x = z = 0, the realizability of (x, 0, z)-graph is ensured by *Proposition 2.1*. For x = 0, the graph constructed in the above lemma serves the purpose for  $z \ge 2$ . For  $x \ge 1$ , consider a (0, 0, z)-graph constructed in above lemma. Join "x" pendent edges at either  $u_{n-2}$  or  $u_{n-1}$  of G of *Figure 5*. Clearly these "x" edges belong to  $E_c(G)$  and there is no edge belonging to  $E_d(G)$ . Hence, (x, 0, z) is realizable,  $x \ge 0$ ,  $z \ge 2$ . For z = 1, the graph of the Figure 6 is the realizer.

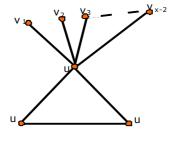


Figure 6.

Clearly, the edge  $u_1u_2$  is the only edge of  $E_{cd}(G)$  and rest all belong to  $E_c(G)$ . Hence this is (x, 0, 1)-graph.

<u>**Theorem 2.15:**</u> The triple (x, y, z) is realizable if  $x \ge 0$ ; y = 2m,  $m \ge 2$ , or y = 2k + mn,  $k \ge 2$ ,  $m \ge 2$ ,  $n \ge 1$ , or y = mn,  $m \ge 2$ ,  $n \ge 1$ ;  $z \ne 1$ .

**Proof:** Proof follows from *Lemma 2.1 to Lemma 2.14*. The realizing graph *G* is as in Figure 7.

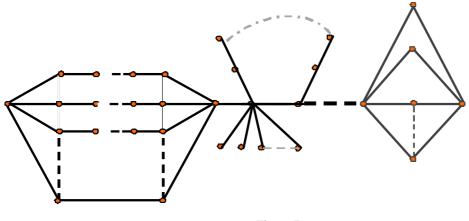


Figure 7.

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Clearly, edges of the form  $u u_i^{1}$ ,  $u_i^{j} u_{i+1}^{j}$ ,  $u_i^{n} v_1$ ,  $1 \le i \le m$ ,  $1 \le j \le n$ ;  $v_{2n-4}x_i$ ,  $xx_i$ ,  $1 \le i \le 1$  belong to  $E_d(G)$ . Edges of the form  $v_{n-2}y_i$ ,  $1 \le i \le x$ , belong to  $E_c(G)$  and edges of the form  $v_{n-2}w_1$ ,  $v_{n-1}w_{n-2}$ ,  $w_iw_{i+1}$ ;  $2 \le i \le n-3$ , belong to  $E_{cd}(G)$ , rest all edges are vital. Hence *G* is an (x, y, z)-graph for the values given in the hypothesis.

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