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A REVERSE FLOW, BOILING
—THERMOSIPHON LOOP
(Design and Feasibility Study)

A Thesis
Submitted to the Faculty of Graduate
Studies through the Department
of Mechanical Engineering in
Partial Fulfilment of the
Requirements for the Degree of
Master of Applied Science
at the
University of Windsor

by

Robert Gaspar

Windsor, Ontario

1973

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ABSTRACT

An experimental study was undertaken to investigate some of the factors affecting the operation of a fixed geometry, two phase thermosiphon loop after first determining that such a system is capable of operation, if initiated, when there is no external pumping and the flow direction is opposite to that generated by natural convection. The loop was constructed of glass with an internally heated annular heat input section, using Freon 113 as the working fluid and having an overall fluid depth of 13.1 feet. The effect of additional pressure drops of various magnitudes created by orifice plates which could be inserted at several locations in the riser section and the effect of the heater length and its location on the limiting values of the system output quality, heat input and flow rate were studied. In addition photographic and visual observations were made of the boiling phenomena and flow regimes including the behaviour of the system before and during flow reversal.

The information gathered indicates that there are both maximum and minimum performance limits for this type of system, that it is a functional method of utilizing buoyancy forces to maintain an unnatural flow direction once it is generated and that it is possible to predict the loop performance using a simple mathematical model.

ACKNOWLEDGEMENTS

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NOMENCLATURE

A	flow area, ft ²
C _p	specific heat, Btu/lbm °R
D	diameter, ft
D _e	equivalent diameter, ft
f _F	Fanning friction factor
g	acceleration due to gravity, ft/sec ²
g _c	gravitational constant, lbm.ft/lbf.sec ²
G	mass flux density, lbm/ft ² .hr
Gr	Grashoff Number, $D^3 \rho^2 \beta \Delta t / \mu^2$
h	heat transfer coefficient, Btu/ft ² .hr.°F
h _{fg}	enthalpy, Btu/lbm
k	thermal conductivity, Btu.ft/ft ² .hr.°F
K	friction loss coefficient
Ka	Von Karman Number, $f f_F (Re)^2$
L	length, ft
L _T	depth of working fluid in the system, ft
L _H	heater length, ft
m̄	mass flow rate, lbm/sec
N	weighting factor
N _{Fr}	Froude Number, $V/\sqrt{g D}$
N _{NU} _D	Nusselt Number based on diameter, $h D/k$
N _t	number of tubes
P	static pressure, lbf/ft ²

P_{BR}	static pressure at the bottom of the riser section, lbf/ft ²
P_{HI}	static pressure at the bottom of the heat input section, lbf/ft ²
P_r	reservoir static pressure in the reservoir-condenser section, lbf/ft ²
q	rate of heat transfer, Btu/hr
Q	Volume flow rate, ft ³ /sec
Q_{in}	rate of heat transfer to the working fluid, Btu/hr
Re	Reynolds Number, $\rho V D/\mu$
s	flow area, ft ²
t	temperature, °F
t_m	mean temperature, °F
T	temperature, °F
V	specific volume, ft ³ /lbm
\hat{V}	velocity, ft/sec
w_c	critical mass flow rate, lbm/sec
X	system output quality
y	length of flashing column, ft
z	elevation, ft
a	void fraction
β	coefficient of bulk expansion, 1/°F
Δ	difference in quantity
λ	latent heat of vapourization, Btu/lbm
μ	viscosity, lbm/ft.sec

π 3.1416

p density, lbm/ft³

Subscripts

g gaseous phase

in quantity entering heat input section

L liquid phase

out quantity leaving heat input section

sat saturated condition

Units

Btu British Thermal Unit

°F degrees Fahrenheit

ft feet

hr hour

lbf pound force

lbm pound mass

°R degrees Rankin

sec second

I INTRODUCTION

One of the major reasons for interest in the mechanism of reversed flow thermosiphoning is the number of Canadian nuclear reactors built with vertical fuel channels. The coolant flow in most of these reactors is upward. With this type of reactor, fueling is accomplished from above; i.e. the fueling machine sits on top of the reactor. This configuration introduces a number of design factors, such as:

1. Additional reinforcement of the reactor to support the weight of the fueling machine.
2. Design of the valve on the fueling port.
3. Fuel handling equipment.
4. Anchorage of the fuel string in the channel.
5. Necessity of coupling the fuel bundles with a common tie rod.
6. Coolant pumping.

In the case of a reactor operated with the coolant flowing downwards and the fueling done from below, the factors listed previously may either be simplified or eliminated, e.g. a tie-rod would be unnecessary which would permit the use of an additional fuel rod in each

fuel bundle. Another factor worthy of consideration is the case of a pump failure and subsequent reactor shut down.

In this case the coolant pumping must not be discontinued once the reactor is shut down. This is due to the physics of the reactor which will continue to generate heat in the reactor for quite some time after shut down. Although this heat generation is only a small percentage of the maximum possible output of the reactor and it does diminish slowly with time, it still must be removed from the reactor by a flowing coolant.

In the summer of 1968 the author became involved with the problem of downward flow while working as a summer student for Atomic Energy of Canada Limited. At that time the problem posed was a simple one; will a closed loop thermosiphon continue to operate with downward flow over the heater section without providing some external driving force.

Several experiments, which terminated in failure, were conducted with a test loop built for a different testing program. Finally a small test loop designated as the Freon Micro-Loop was constructed and testing was carried out as reported in a short paper (1). The results of the testing showed that the loop would operate with reverse flow over the heater section with or without

boiling although there was a good deal of flow instability for the case of boiling.

Upon entering graduate school the author submitted a research proposal to study the region of stability and operating characteristics of a reverse flow, boiling thermosiphon having previously obtained written permission from A.E.C.L. to continue the study initiated there.

The ultimate goal of the project was to investigate those factors which control the flow stability and evaporative efficiency of a reverse flow, boiling thermosiphon loop.

There are many factors which may influence the stability limits of operation of a reverse flow thermosiphon, such as:

1. Fluid properties
2. Loop geometry (height, component sizes, shape, etc.)
3. Heater length
4. Heater location
5. Heat flux variation (profile)
6. Inlet subcooling
7. Flow restrictions

From the experience gained at A.E.C.L. it was decided that to provide a versatile flow loop, the thermosiphon should be constructed from interchangeable components. Further, it was decided that the loop should be

primarily constructed with glass to allow visual observations of flow within the thermosiphon loop and because of the glass that a non toxic, low latent heat of evaporation liquid with a saturation temperature slightly higher than ambient room temperature at atmospheric pressure be chosen as the working fluid. Refrigerant 113 was thus chosen since its fluid properties were quite suited to the design requirements and an economical supply was available.

The choice of a glass system did impose some restriction such as insertion of monitoring systems for temperature, pressure and flow rate; maximum operating pressure and available component sizes but it was deemed essential for flow visualization. In fact the experimenter's ability to see the flow provided the insight for design changes that made stable, boiling, reverse flow in the system possible. The glass construction also made photographic recording of the visual characteristics of the modes of flow available for study by other investigators.

This thesis deals with the design and construction of the thermosiphon loop and the effects of varying the heater length, heater position and the effect of insertion of orifice plates of various sizes in various locations in the riser section of the flow loop on the maximum and minimum power dissipation and system output quality for

stable operation of the reverse flow, boiling thermosiphon loop shown in Figure 1. For these tests the orifice plates can be considered to represent valves, obstructions and other devices causing frictional pressure losses and the heater length and location tests can be considered as similar to the length and location of the nuclear fuel bundles in the reactor system.

These tests were conducted with one fluid, one fixed geometry and two constant inlet subcooling values, one for maximum performance and one for minimum performance.

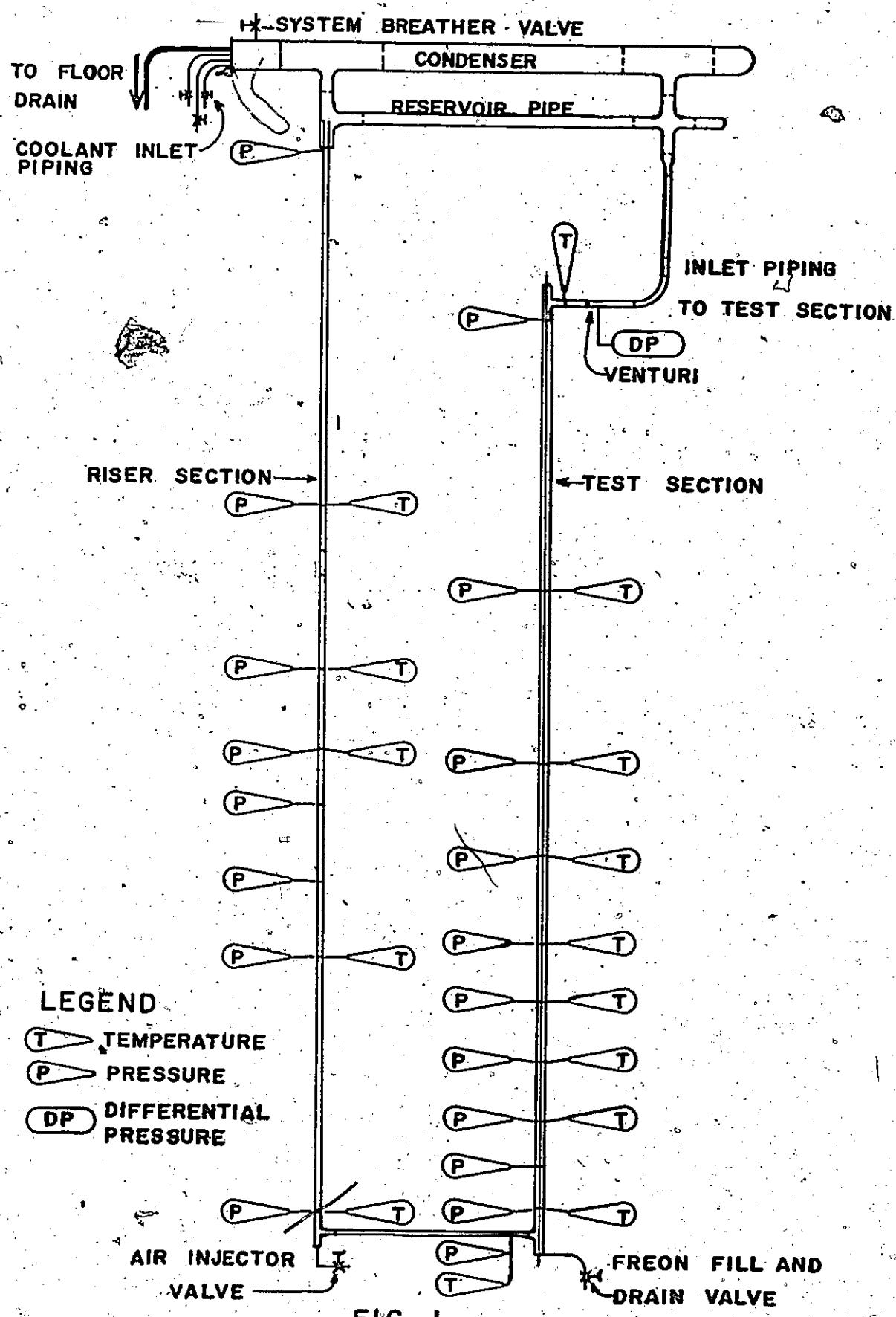


FIG. I
DIAGRAM OF TEST APPARATUS

II LITERATURE SURVEY

The material in this chapter is included to provide information relevant to this problem and the references used in the analysis of the results obtained.

The idea of a boiling thermosiphon operating with the flow direction being opposite to the normal direction of natural convective flows cannot be attributed to any individual reference. Consequently and unfortunately there are few previous publications dealing with this problem. From information gathered at Atomic Energy of Canada Limited, from M.B. Carver, D.F. D'Arcy, G.A. Wikhammer and D.C. Groeneveld (2,3,4,5) and later from J.T. Rogers (6) indications were that reverse flow boiling thermosiphoning was being considered as a coolant flow mode for nuclear reactors in the case of cooling system pump failure when the nuclear chain heat reaction is interrupted and the reactor output diminishes to a small percentage of its maximum heat generation. The sources at AECL indicated that J.T. Rogers and G.M. Barns had completed some preliminary calculations indicating the feasibility of this particular form of thermosiphoning. This work was followed up by R.G. Gaspar (author) who with the aid of D.C. Groeneveld constructed and tested a small thermosiphon loop (1). The report submitted by Gaspar indicated that reverse flow thermosiphoning was possible.

to achieve for both boiling and non-boiling cases.

A full report on the subject of reverse flow thermosiphoning was produced by G.M. Barns (see reference 7) which gave a literature survey and discussion of the problem as it pertains to nuclear reactors.

D.F. D'Arcy (8) suggested a 3:1 scaled down reactor loop that would be similar to one of the flow loops, U-1, in AECL's nuclear reactor NRU.

Other design ideas such as the use of glass piping for flow visualization and type of heating elements to provide power input were the result of experience gained by the author from another experimental study (9) conducted at AECL. The specific details (10) of a typical nineteen rod fuel bundle were used to determine a comparable hydraulic diameter for the annular flow passage heat input section of the test loop.

A venturi flow meter was designed employing design information outlined in an AECL Engineering manual (11) on that subject.

The condenser unit was designed according to established criteria outlined by both A.J. Chapman (12) and F. Kreith (13).

A Mechanical Engineering Laboratory manual (14) was the source of the procedure outline for calibrating the standard thermocouple used for the basic temperature measurements in the flow loop.

Data reduction and analysis were carried out by statistical methods outlined by A.M. Neville and J.B. Kennedy (15) with necessary supplementary information on the working fluid being provided by the ASHRAE Handbook of Fundamentals (16) and the Handbook of Tables for Applied Engineering Science (17).

From the references investigated several criteria for analysing the stability of the reverse flow direction were established. The first of these was found during the author's work at AECL.

An article on Sizing Piping for Process Plants (18) mentions a design problem encountered with two-phase vertical downward flow which may be applied to the analysis of stability for this problem. The author quotes several sources and establishes a value of Froude number modified for two phase flow as defined:

$$(N_{Fr})_L = \frac{\hat{V}_L}{\sqrt{gD}} \sqrt{\frac{\rho_L}{\rho_L - \rho_g}} \quad \text{Eqn. 1}$$

where the lower limit of this number is given as 0.31 below which bubbles will not be swept downward by a downward flowing liquid.

Bonilla (19) states four criteria which may be used in flow loop design for downward flowing fluids and which may be helpful in establishing lower stability limits for the flow loop under investigation.

The first two criteria are based on pulsing which may develop in the flow if the flow rate is such that the flow switches from laminar to turbulent. This problem may be avoided if the Reynolds number and Von Karman number for the flow are outside the ranges indicated

$$2,100 < Re < 3,500$$

$$70,000 < Ka < 270,000$$

It is also noted that in annuli turbulence initiates less abruptly and pulsing is less likely to be encountered within this range.

One of the two other criteria given is the requirement that the ratio of the Grashoff number to Von Karman number be always much much less than unity ($Gr/Ka \ll 1$), see eqn. 2; where the Δt term in the Grashoff number is the temperature rise, not the wall to fluid temperature difference. Bonilla indicates that the reason for this limit is that an instability may develop under certain conditions so that a slight decrease in flow increases the buoyancy opposing flow and eventually leading to a flow reversal. The final criterion given is a critical flow value (see eqn. 3) below which flow reversal may be anticipated.

$$\frac{Gr}{Ka} = \frac{\rho^2 \beta g(t_2 - t_1) De}{4 f_F G^2}$$
Eqn. 2

$$w_c = \left[\frac{\beta_1 g(t_2 - t_1) De}{8 f_F L} \frac{\Delta z}{\rho S} \right]^{1/2} \text{ lbm/sec Eqn. 3}$$

Information given by Pao (20) and Van Wijlen and Sonntag (21) was used to evaluate the test data in light of the ideas presented in the two sources cited.

Other sources of information pertaining to this thesis may be found in the references listing (22,23).

III EXPERIMENTAL DETAILS

Introduction

In order to observe and measure the operating characteristics of a boiling reverse flow thermosiphon it was decided that the construction material of the system be glass. With this in mind it was therefore necessary to operate the system close to room temperatures to minimize heat losses so that insulation would not be required. This choice dictated that a working fluid be chosen which has a low saturation temperature at atmospheric pressure since low pressure operation was considered essential for reasons of operator safety.

A. Selection of Working Fluid

As indicated, the choice of the working fluid was influenced by the desire to be able to observe the fluid flow in the glass system and, because of this choice, the loop should operate at atmospheric pressure and near room temperature.

Originally Refrigerant 11 was considered as the working fluid primarily because of its common use as a working fluid at A.E.C.L. and because there is information available for comparison of R-11 and water. However, at the time when the project was initiated there was no temperature control for the laboratory room temperature during the summer months and on very hot days outside, the room temperature sometimes reached 85°F. Consequently R-11 was

not used since its boiling point at atmospheric pressure is 74.7°F and under the room conditions mentioned the working fluid would require cooling to keep it in its liquid form. Also under the mentioned conditions it was envisioned that problems would be encountered with maintenance of liquid temperatures in the reservoir section which would increase the problem of controlling heat input during start up. In addition, even considering favourable room temperatures below the saturation temperature of R-11 there would be very little heat input needed to produce boiling in the heat input section.

Consequently, Refrigerant 113. (Trichlorotrifluoroethane) was chosen, based on its low saturation temperature of 117.6°F at atmospheric pressure, the fact that it remains a liquid even at elevated room temperatures, its low latent heat of vapourization, its low toxicity and its relatively low cost per pound.

B. Equipment and Design

1. Condenser Design

An arbitrary decision was made to build rather than purchase a condenser for the thermosiphon loop. The major factor influencing this decision was the consideration of problems arising from interfacing glass and metal parts such as allowing for different coefficients of thermal expansion, sealing of joints and problems of locating a suitable condensing heat exchanger. The selection of a glass

encased condensing unit conquered most of these difficulties and left only the selection of a large enough size of glass pipe to contain the condenser tube arrangement designed.

The condenser capacity was determined by the electrical energy available at the test site which was 25 kilowatts. This figure was arrived at from the 240 volt, 100 ampere service available plus an anticipated use of a 1000 watt heating tape for auxiliary heating.

The estimated maximum cooling water inlet temperature selected was 80°F for mid-summer operation. The maximum operating pressure of 7.5 psig was determined to be a safe pressure limit assuming that the system might be pressurised for some test runs much later in the testing program. For the maximum pressure assumed, the maximum vapour temperature in the condenser would be 140°F. The maximum temperature rise of the cooling water was arbitrarily assumed to be 15°F.

With a general idea of what the final condenser unit would look like, several design requirements were determined. The first parameter was condenser tube diameter. From the three readily available sizes, 3/8 inch O.D. soft copper tubing was selected since the coolant flow area in a 1/4 inch O.D. tube is quite small and 1/2 inch O.D. tubing would be hard to work compared to 3/8 inch O.D. soft copper.

Having selected the condenser tube diameter and visualizing horizontal array of condenser tubes it was then necessary to determine the number of tubes per bank. This

value was chosen to be 6 tubes per bank after considering the proposed geometry of the headers and since no great deviation from that number was considered likely and any deviation about it would not significantly affect other calculations.

The properties and conditions necessary for the condenser design are listed as follows:

$$\Delta t = 140 - 95 = 45 \text{ (assuming a maximum coolant temperature of } 95^{\circ}\text{F})$$

$$t_m = (140 + 95)/2 = 117.5^{\circ}\text{F}$$

$$D = 3/8 \text{ inch} = 1/32 \text{ ft}$$

$$N_t = 6$$

$$g = 32.2 \text{ ft/sec}^2$$

Evaluating the properties of saturated R-113 liquid at the mean film temperature

$$\rho = 94.3 \text{ lb/ft}^3$$

$$\mu = 1.219 \text{ lb/ft-hr}$$

$$k = 0.034 \text{ Btu/hr-ft-}^{\circ}\text{F}$$

$$\lambda = 61.3 \text{ Btu/lb}$$

Substituting into eqn. 10.22 of Chapman (Eqn. 4)

$$N_{NU_D} = .725 \frac{(g \rho^2 \lambda D^3)^{1/4}}{N_t \mu k \Delta t} \quad \text{Eqn. 4}$$

Then

$$N_{NU_D} = 114.5$$

Thus

$$hD = k N_{NU_D} = 3.89 \text{ Btu/hr-ft-}^{\circ}\text{F}$$

$$\text{Since } q = \pi L h D \Delta t \quad \text{Eqn. 5}$$

then the required length of tubing is

$$L = \frac{q}{\pi h D \Delta t} \quad \text{Eqn. 6}$$

$$L = 155 \text{ ft}$$

The condenser unit was visualized as having a U-type tube arrangement and no more than three banks of tubes. Also since the space available in the lab was about 8 feet long, it was decided that the length of each "U" condenser tube be 5 feet which allows 3 feet for support members and cooling water facilities.

This indicated a final choice of 180 ft of tubing, since the total number of tubes was selected as 18. This allowed the condenser design to be on the conservative side and seemed to be a convenient arrangement of condenser tubes.

The decision regarding the physical layout of the condenser unit dictated that the condenser glass shroud must accommodate 36 condenser tubes with at least an equal area of free space surrounding them. This resulted in the selection of a 4 inch inside diameter glass pipe for the condenser shroud. The final overall length of the condenser as it was built was 7 feet with the additional length being used for the inlet and outlet headers and the connections to the condenser tubes.

The general construction of the condenser tube bank was quite simple. A 3.75 in diameter template was used during assembly to ensure sufficient space for the tubes when they

were finally inserted in the glass shroud. The tubes were separated from each other by 1/8 inch diameter copper wires which were soldered to individual tubes at 1 foot intervals to maintain horizontal spacing of tubes at the same elevation and to keep the tube layers separated vertically.

The header system consisted of three controlled flow inlet headers, one for each tube bank; and one main outlet header collecting the coolant return and directing it to the floor drain. Each end of each U-shaped condenser tube is connected to its appropriate header by an accommodating length (2 to 12 inches) of soft polyvinyl chloride tubing which is clamped over the end of the copper tubing. This plastic tubing was selected on the basis of information that polyvinyl chloride is unaffected by contact with R-113.

A leakage problem encountered when preliminary testing was started. The problem arose from an unanticipated effect of the Refrigerant on the tubing used for connecting the condenser tubes to the headers. As was noted polyvinyl chloride is one of three plastics which is unaffected by contact with R-113, the other two being nylon and polytetrafluoroethylene.

It was concluded therefore that the connecting tubing supplied was certainly not one of these three listed because the shrinkage was at least 20% and there was no flexibility compared to another piece of tubing not used in the R-113 atmosphere. The tubing shrank and hardened sufficiently to loosen at the clamped ends enough so that it eventually pulled

free. This required replacing the original tubing with new polyvinyl chloride tubing. To help prevent any further leakage, Lepage's Plastic Rubber was applied at the joints on the water side of each clamped joint. The solution improved the situation but problems of leaks still occurred which were possibly because of the variations in the length of the connecting plastic tubing. Finally it was decided to pressurize the condenser with a continuous flow of cooling water and this has proven successful since no further leakage was observed.

2. Selection of Flow Loop Design

The limitations which governed the selection of the glass piping and other hardware for the flow loop are: the hydraulic radius of the heat input section, the flow area of the venturi in the inlet to the heat input section, the flow area of the heat input section and the flow area of the riser be approximately the same. An added requirement was that all of the glass piping, the copper heating tube of the heat input section and the heater cartridges be stock items which would require little or no alterations before installation.

The hydraulic radius of the heat input section which was used to help make the component selections is similar to that of a typical working nuclear reactor which is approximately 0.0659 inches. This criterion was used because several small test loop facilities have hydraulic radii in the same range and this would seem to be a useful reference for comparison of different flow loops in use. The venturi used to measure

the mass flow rate was also a governing factor since small sizes are difficult to manufacture. In this case it was determined that the bore diameter be no smaller than 0.50 inches.

The method planned for circulation of the working fluid was the use of air injection at the base of the riser section which would create a flow of the working fluid in the required direction.

The maximum thermosiphon height was dictated by the maximum floor to ceiling height of 18 feet 4 inches available in the Mechanical Engineering laboratory. With these basic requirements set it was then necessary to design the component sections of the thermosiphon loop with dimensions as given in the following sections.

3. Heat Input Section

The selection of an annular flow passage heat input section was determined by the general size of the test loop and the type of studies to be made. In larger models an attempt would have been made to provide a heat input section similar to that of a typical working nuclear reactor, i.e. separate heating elements for simulation of individual fuel rods.

Because of the nature of the investigation it was not deemed advisable since flow visualization was a requirement of the testing so that flow reversals could be observed. Therefore to provide a similar condition and to allow flow

visualization an annular flow passage with a hydraulic radius of approximately 0.0659 inches was designed. With consideration of other component sizes and the intended use of stock items an outer wall inside diameter of one inch was selected which allowed the use of Q.V.F. (Quick Visible Flow) nominal one inch inside diameter glass pipe.

This selection would require the inner wall of the annulus to be 0.736 inches. A copper tube of the required outside diameter is not commercially available. Therefore there were essentially three possible options to choose from.

A commercial 0.750 inch O.D. copper tube could be turned down on a lathe to the required diameter, the heating elements could be inserted in the same copper tube and it could be passed through a draw die to bring it down to size or the 0.750 inch O.D. copper tube could be used and the system would have a hydraulic radius of 0.0625 inches for the annular flow passage. Eventually the third possibility was chosen because, of the other two possibilities, the first would be difficult to achieve because of the cumbersome nature of working with a twelve foot length of copper tube in a lathe and the second choice would mean that special heating elements would be required to slip inside the tube or else the test section would have to be disassembled to insert a multitude of separate heating tubes (practically one for each test conducted).

The inner surface of the heat input section was

therefore chosen to be a twelve foot length of precision drawn seamless copper tubing with an outside diameter of 0.75 ± 0.001 inches and an inside diameter of 0.526 ± 0.001 inches. This type of tube was used for all testing of the thermosiphon loop.

The first attempts at achieving reverse flow were conducted with a thermocouple instrumented heating tube of precision drawn seamless copper tubing with four 0.11 inch wide slots cut into the outer heating surface and running the full length of the tube. These slots were located at equally spaced circumferential positions to carry surface temperature measuring thermocouple lead wires. The lead wires were embedded in an epoxy resin cement which filled the slots.

Unfortunately during the first attempts at achieving reverse flow, many flow reversals were encountered because of the short heaters and lack of nucleation sites in the riser. These reversals occurred while air was still being pumped into the system and the pressure of air in the fluid allowed the heater sheath temperatures to rise high enough to cause a breakdown of the bond between the epoxy and the copper tube thereby allowing the thermocouple lead wires to pop out of their slots. Therefore a non-instrumented precision drawn copper tube was used for the majority of the testing program until the damage to the instrument tube could be corrected and until such a time when the operating range of the thermosiphon

loop could be located so that the problems of damaging reversals in flow direction could be avoided.

As was noted previously the outer glass pipe used in the heat input section had an inside diameter of one inch +0.01, -0.02 inches so that the equivalent diameter of the heat input section was $0.25 + 0.01, -0.02$ inches. These glass pipe sections are made with flared ends which are joined by a three bolt iron clamping ring with a graphite impregnated asbestos insert used for cushioning the glass against high stresses caused by unequal bolt tension.

Nylon spacer rings (see Figure 2) were machined to fit the inside glass flare (see Figure 3) in order to provide a means of securing fluid temperatures and pressures in the heat input section.

Besides allowing insertion of thermocouple probes and static pressure taps some of the nylon rings were fitted with three screw holes which could be used for centering the heating tube by means of three alignment screws.

A glass to nylon seal was achieved by inserting deformable teflon sealing rings between the two materials thus reducing the bolt tension and stress on the glass pipe required to attain a dry seal.

The heat input section length from inlet to outlet centreline is 129.5 inches and is made up of the glass pipe section lengths listed in order from top to bottom in Table 1.

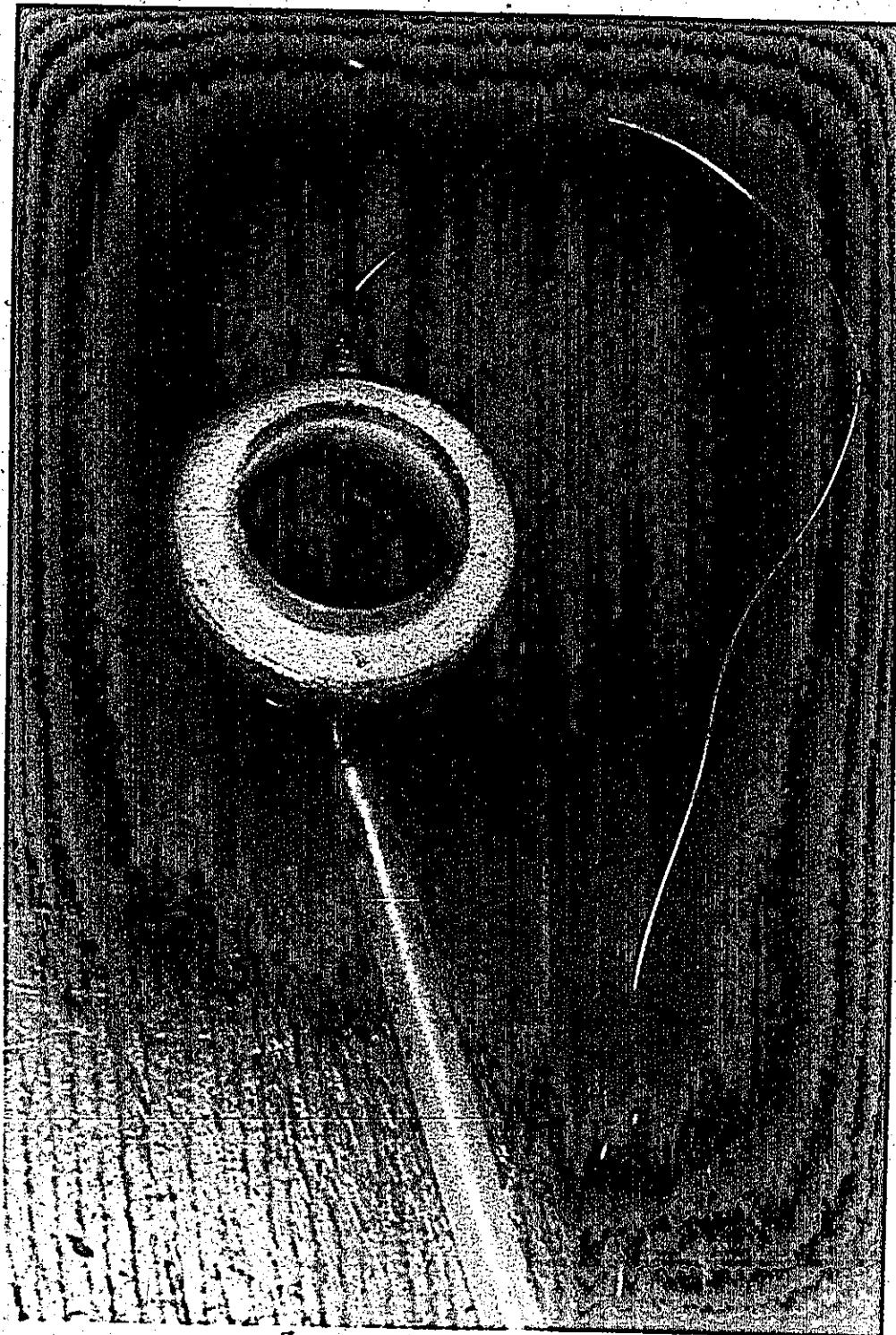


FIG. 2

NYLON INSERT RING OF HEAT INPUT SECTION

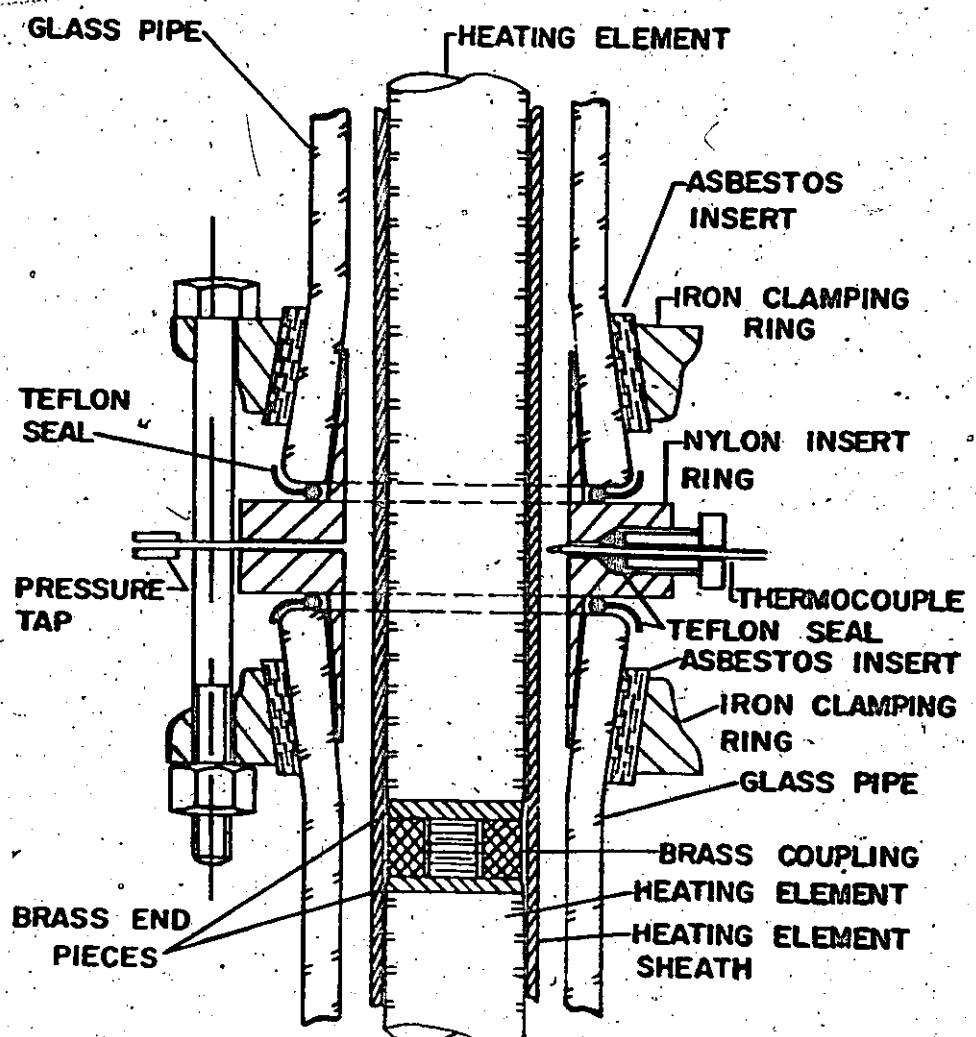


FIG. 3
DIAGRAM OF TEST SECTION JOINT

TABLE 1

List of Heat Input Section Glass Piping (Top to Bottom)

1. 5.5 inch glass tee piece (inlet)
2. 36 inch long glass pipe
3. 24 inch long glass pipe
4. 12 inch long glass pipe
5. 12 inch long glass pipe
6. 8 inch long glass pipe
7. 8 inch long glass pipe
8. 8 inch long glass pipe
9. 6 inch long glass pipe
10. 6 inch long glass pipe
11. 5.5. inch glass tee piece (outlet)

The end caps used to seal each end of the test section and to align the heating tube are shown in Figure 4. They were constructed from free machining brass plate 0.375 inches thick. Each end plate was bolted to its adjacent glass tee utilizing a teflon gasket ring to provide the glass to brass seal. The seal between the heating tube and the end plate was made with a neoprene 'O'-ring which seated in a sealing groove cut into the brass end plate. The sealing ring is compressed against the end plate and the heating tube by a sealing plate which encircled the heating tube and is bolted to the end plate with three brass machine screws.

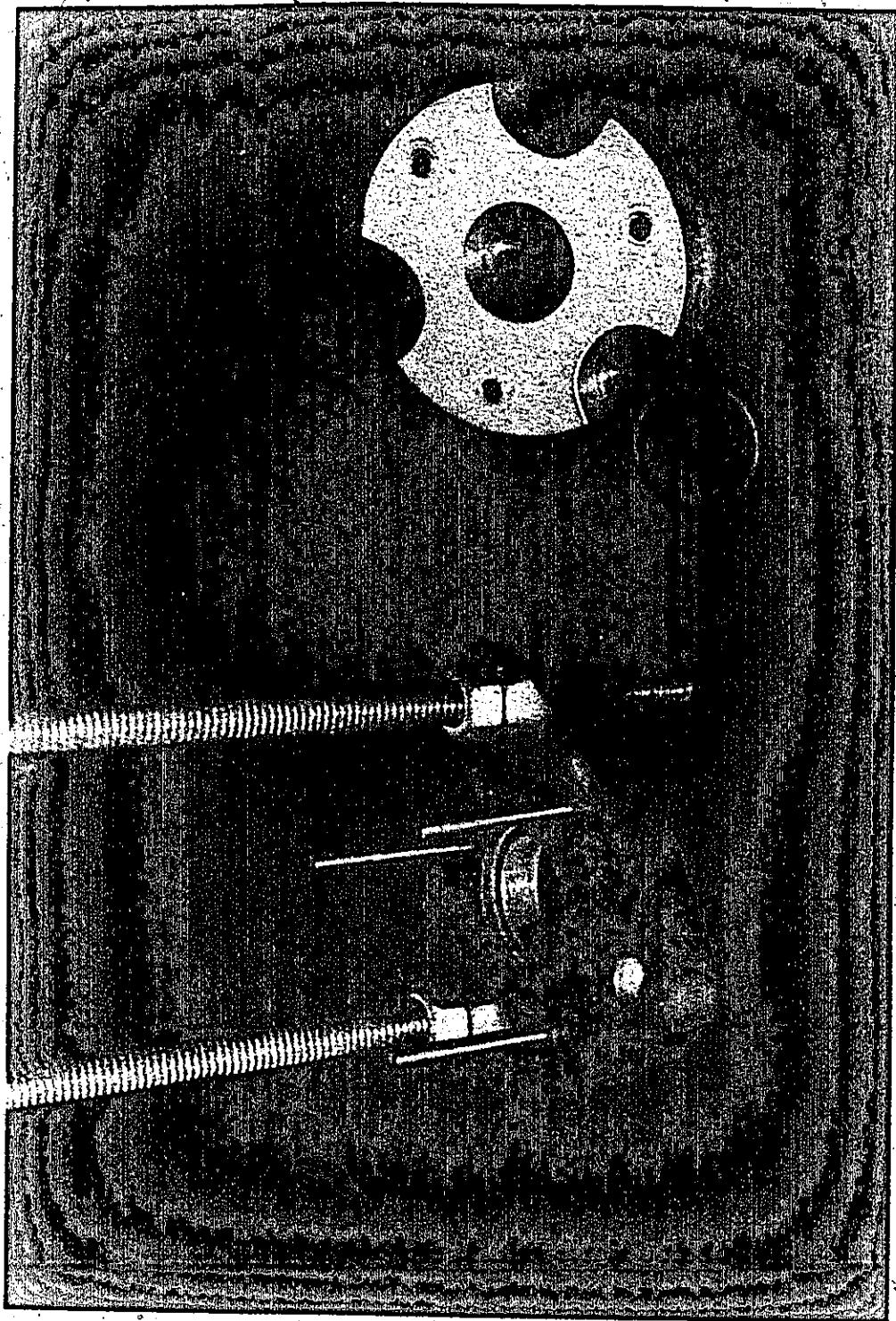


FIG. 4
HEAT INPUT SECTION END SEAL

4. Heaters

Various lengths of heating elements were used singly and in pairs to provide the overall heating lengths tested. These heating elements all have nominal outside diameters of 0.625 inches. To allow these heating elements to slip inside the copper heating tube of the heat input section each heater was ground down on an abrasive wheel such that they would just slip inside the heating tube. The four heaters used consisted of two Cl-406R Chromalox "Redhead" Electric Cartridge Heaters with a nominal length of 10.75 inches and rated at 1700 watts in air, one Cl-446R Chromalox Cartridge Heater with a nominal length of 36 inches and rated at 3500 watts in air and one Cl-458R Chromalox Cartridge Heater with a nominal length of 48 inches and rated at 3800 watts in air. Male and female brass bolt type fittings were machined and brazed on the ends of the heating elements to allow them to be used in paired combinations. Table 2 lists the cartridge heaters and gives the specifications of each heater.

Each heater was powered by a variable autotransformer rated at six kilowatts. The power being dissipated through each heater was obtained by an ammeter-voltmeter circuit which measured the current through the heater and the voltage drop across both heater and ammeter. Each voltmeter has an internal resistance of 5000 ohms/volt and a measuring

TABLE 2
HEATING ELEMENT SPECIFICATIONS

CARTRIDGE ELEMENT	LEAD WIRE	ALL DIMENSIONS IN INCHES				MALE AND FEMALE END FITTINGS			
		A OVERALL LENGTH	B LEAD END UNHEATED LENGTH	C FITTED END UNHEATED LENGTH	D ₁ DIAMETER	M MALE LENGTH	D _m DIAMETER	F FEMALE LENGTH	D _f DIAMETER
C1-406R (M)		10.62	0.50	0.25	.622 .002	.067	.600	.285	.600
C1-406R (F)		10.60	0.67	0.25	as above				
C1-446R(M)		35.75	1.00	1.75	as above	.067	.600		
C1-458R(F)		47.95	1.00	0.75	as above			.375	.600

accuracy of $\pm 0.5\%$ full scale with a reading accuracy of $\pm .25V$, while each ammeter has a measuring accuracy of $\pm 1\%$ full scale with a reading accuracy of ± 0.025 Amperes.

5. Horizontal Connecting Pipe and Riser

In order that the flow area of the connecting tube and riser be approximately equal to the nominal flow area of 0.344 in^2 of the heat input section, $5/8$ inch I.D. glass pipe with a flow area of 0.307 in^2 was selected. This selection required the use of a reducing glass section to connect the one inch I.D. outlet of the heat input section to the 24 inch horizontal connecting pipe. The connecting pipe and riser are also Q.V.F. glass pipe to allow visual observations of the single or two phase flow after it leaves the heat input section. The pipe sections are of convenient length to allow temperature and, if necessary, static pressure readings to be made at the joints. Table 3 lists the glass piping used to construct the connecting pipe and riser in order from the reducer section to the top of the riser where it enters the reservoir section. It should be noted that the final 4 inch length of glass pipe is inside the riser such that when the reservoir section is half full, the working fluid just covers the outlet of the riser.

This design was selected since it was felt that it would reduce the flow resistance and improve the chances of operation of the thermosiphon. Further investigation has since revealed that this design choice was not necessary.

TABLE 3.

List of Connecting and Riser Section Glass Piping

1. 3 inch long one inch to five-eighths inch reducer
2. 24 inch long five-eighths inch glass pipe
3. 2 inch long (each leg) five-eighths inch glass tee piece
4. 36 inch long five-eighths inch glass pipe
5. 8 inch long five-eighths inch glass pipe
6. 6 inch long five-eighths inch glass pipe
7. 6 inch long five-eighths inch glass pipe
8. 10 inch long five-eighths inch glass pipe
9. 12 inch long five-eighths inch glass pipe
10. 3 inch long five-eighths inch glass pipe
11. 6 inch long five-eighths inch glass pipe
12. 60 inch long five-eighths inch glass pipe
13. 4 inch long five-eighths inch glass pipe

as there is no noticeable difference if the thermosiphon is operated without the 4 inch pipe in place.

Two types of nylon inserts were used to provide instrumentation access to the flow inside the pipe. One of the nylon inserts as shown in Fig. 5A was used during the first set of tests to determine the effect of an additional pressure drop in the flow loop. As shown in the diagram there were two halves to each insert, one for each side of the orifice plate. Each half of the insert is identical and is constructed in two parts.

One part of the insert is a tapered section machined to fit its individual glass end flare. This part of the insert was drilled out to 5/8 inch I.D. and was machined to have a shoulder which snapped into a retaining groove machined into the second part of the insert. The second portion of the insert is an inch and an eighth O.D. ring with a static pressure tap at the inside edge of the orifice plate side mating surface. All dimensions are as given in Figures 5A and 5B.

The orifice plates used were cut from .007 inch sheet steel. The orifice holes were drilled in this thin stock by clamping each plate between two pieces of 1/4 inch thick perspex and slowly drilling through the sandwiched material. Each plate used had 6 orifice diameters one of which was always 0.625 in. The five other diameters were arbitrarily chosen for each plate from a range of diameter ratios in increments of 0.05 from 0.5 to 0.9; where the diameter ratio

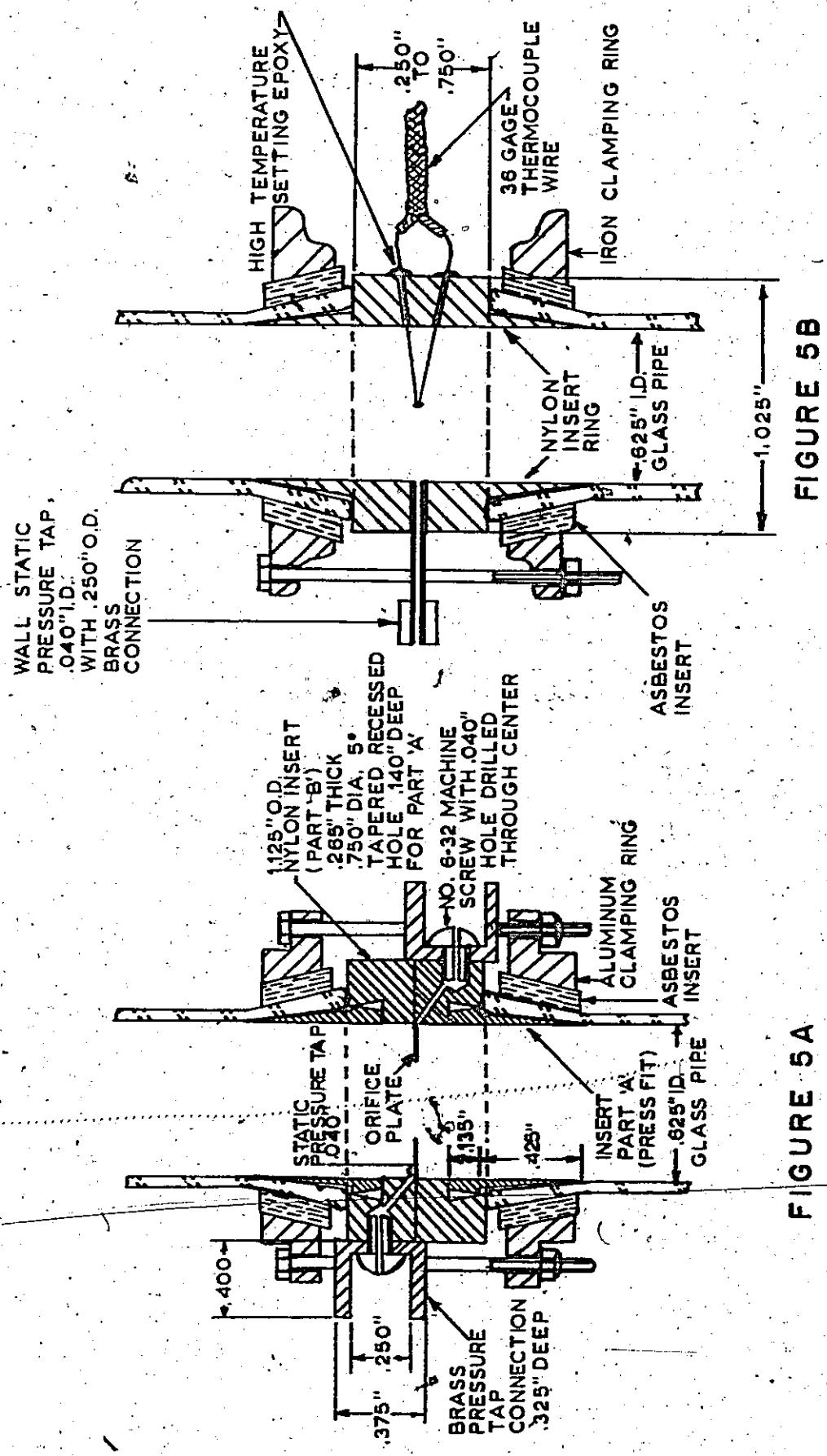


FIGURE 5B

FIGURE 5A

is defined as the ratio of the orifice diameter to adjoining inside pipe diameter.

The number of orifice plates were arbitrarily chosen to be six. The six locations for inserting these plates, as measured from the riser inlet centerline were 2 inches, 46 inches, 67.5 inches, 74 inches, 81 inches, and 92 inches respectively.

The other set of nylon inserts were used whenever the orifice plates were not in use. These inserts, shown in Figure 5B and Figure 5C, were used to allow measurements of centre core fluid temperatures and wall static pressures in the horizontal connecting pipe and riser to be made.

The bottom leg of the riser tee joint contained a nylon insert as shown in Figure 6. This insert was fabricated to reduce the flow losses through the tee and to provide a means of injecting air into the riser to initiate circulation. The insert has a 0.04 inch hole drilled through its longitudinal centre line and it was clamped into the tee piece with an end plate containing an air hose adapter and valve.

6. Thermocouples

Two types of thermocouples were used in the testing program. To measure the bulk fluid temperature at the centre of the annular gap in the heat input section, 0.040 inch O.D. inconel sheathed iron-constantan thermocouples were employed. These thermocouples were calibrated against a copper-constantan

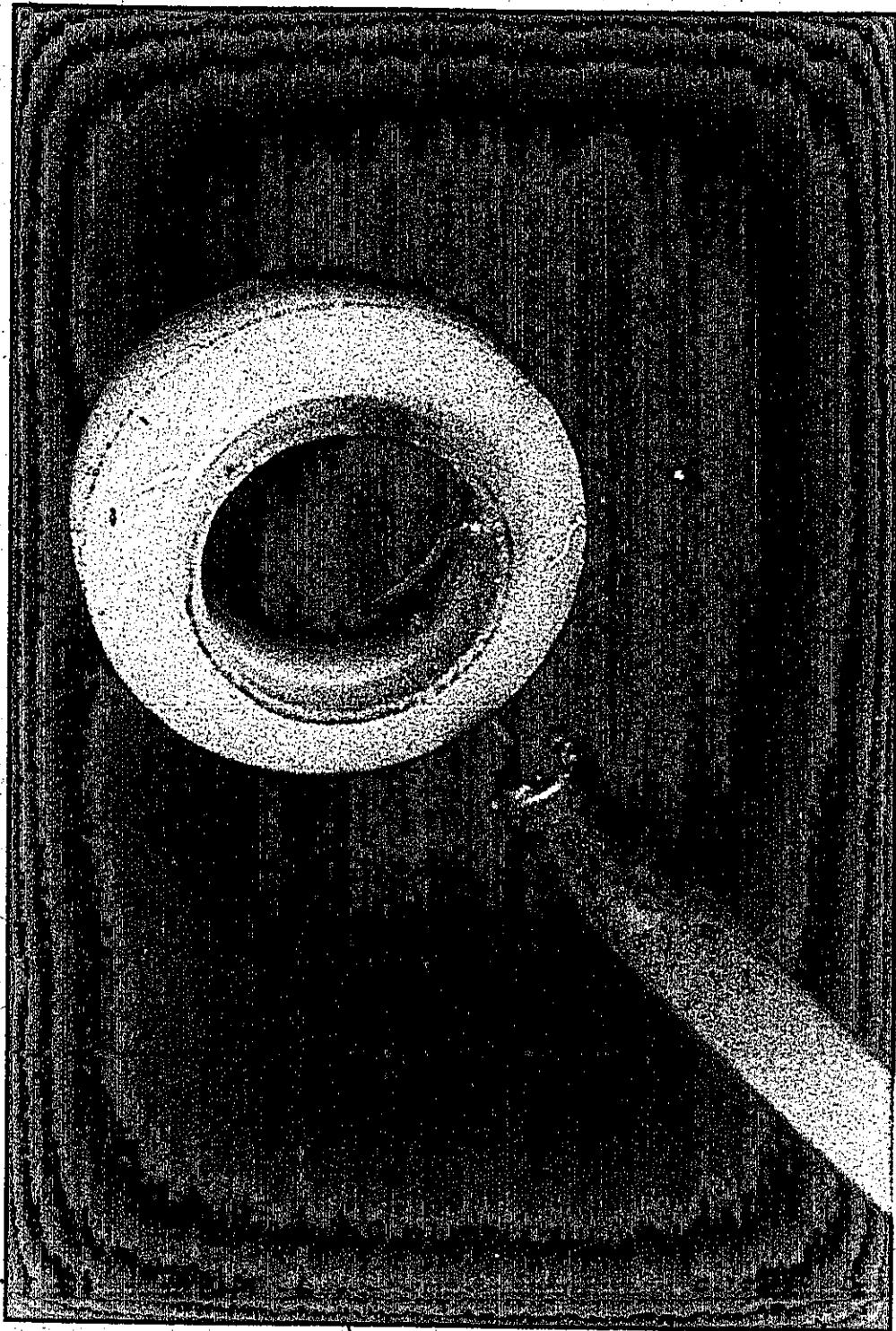


FIG. 5C
NYLON INSERT RING OF RISER

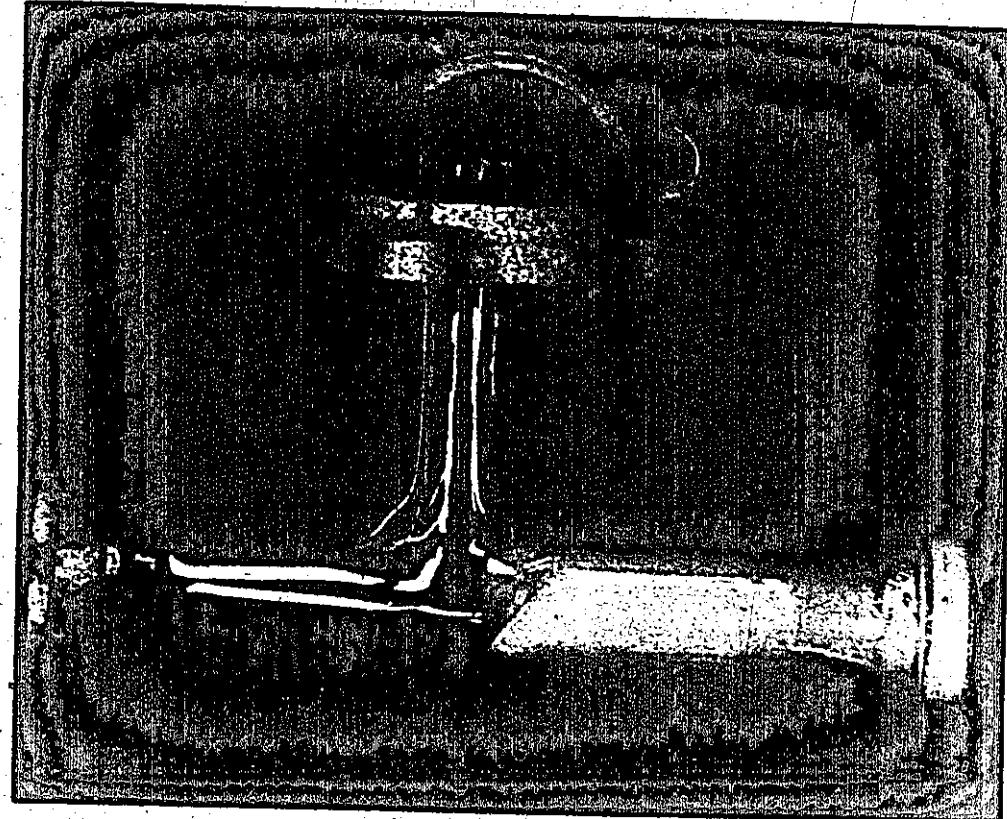


FIG. 6
NYLON INSERT OF RISER INLET "TEE"

thermocouple which was used as the standard reference for all temperature readings. Since the iron-constantan thermocouples were delicate i.e. an estimated head size of 0.010 inches, they were periodically checked for accurate temperature reading by comparing the measured temperature of the circulating working fluid without heat addition against the standard reference thermocouple. Based on the calibration the accuracy of the iron constantan thermocouples is $\pm 0.2 F^\circ$ with a measured reading repeatability of $\pm 0.1 F^\circ$.

Calibrated copper-constantan thermocouples were used throughout the rest of the thermosiphon loop to monitor temperatures at particular reference points. These 36 gage fiber-glass insulated thermocouples were all taken from the same roll and were calibrated against a calibration thermometer in a constant temperature bath according to standard procedures. The accuracy measured for these thermocouples was $\pm 0.2 F^\circ$ with a measured reading repeatability of $\pm 0.1 F^\circ$. The calibration relationship used to determine the actual temperature from the temperature measured is:

$$T_a = 1.0008 T_r - 0.0651$$

This relationship was determined by the least squares method of curve fitting and was found to have a correlation coefficient of 1.000.

The temperature readings were taken using two Honeywell millivolt nulling potentiometers each with a limit of error of 0.01 millivolts for a range of 0-16.1 millivolts. Each poten-

tiometer was used for one type of thermocouple wire and was connected to a Thermo-Electric thermocouple switch. Since nulling potentiometers were used and the thermocouples were calibrated through the switch connection it is assumed that there are no reading errors due to any contact resistances between the switch contacts. A Zeref 32°F reference junction unit was used to provide an external reference junction for each circuit and manufactures specifications indicate a maximum reference source error of -0.0, +0.9 F° about 32°F, although the actual errors from measurement are -0.0, +0.1 F°. Temperature conversion calculations were carried out by employing a set of Leed and Northrup Company conversion tables.

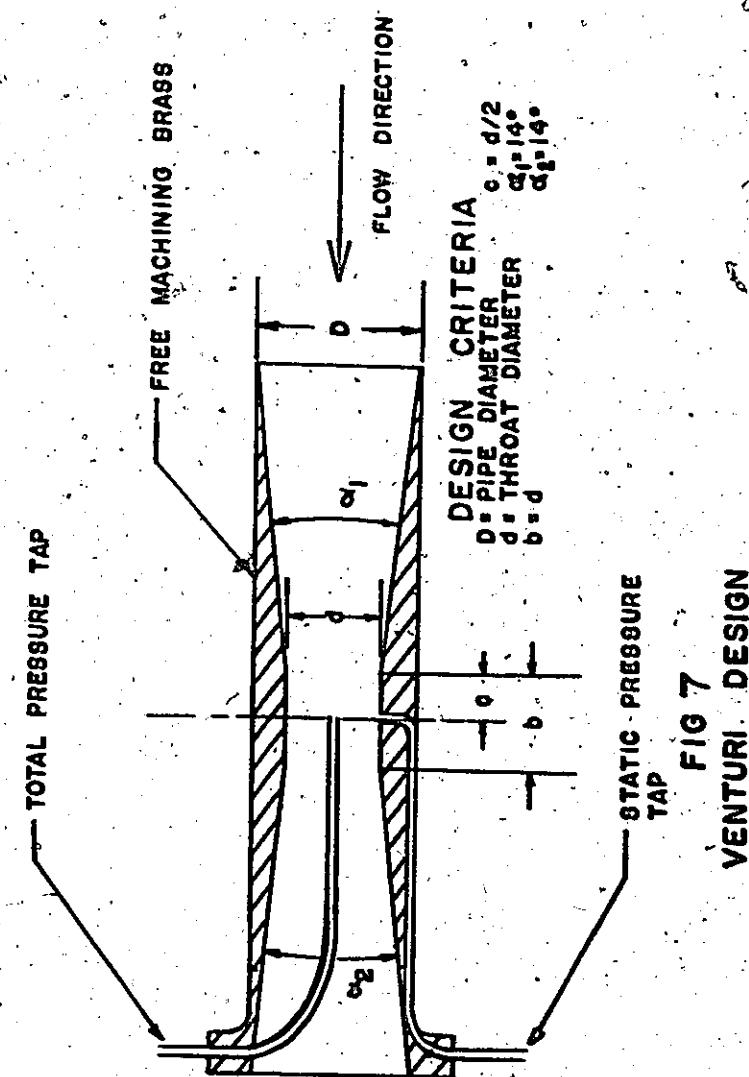
7. Venturi

A venturi (see Fig. 7 and Fig. 8) type flow meter was designed to measure the inlet test section flow rate. The venturi design considerations that were considered important were; that the venturi have a very good pressure recovery characteristic and, because of the possibility of saturated liquid being present in the reservoir section, that the venturi be located at some point in the thermosiphon loop where the chances of fluid flashing due to the venturi's pressure drop would be minimal.

From a design handbook of flow metering devices used by A.E.C.L. the following design details were chosen:

Diameter Ratio 0.527

Inlet Contraction Angle 7°



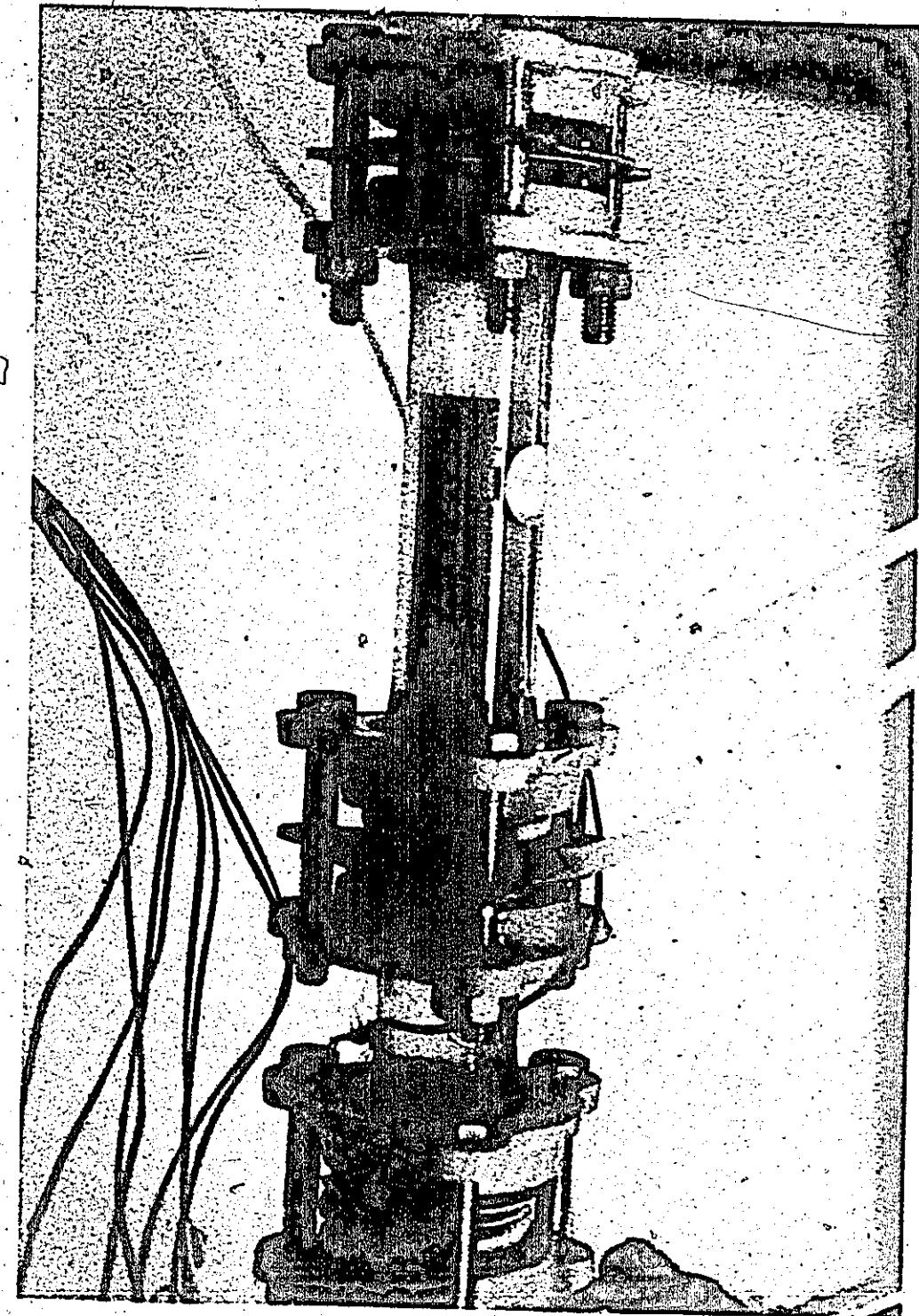


FIG. 8
VENTURI IN PLACE

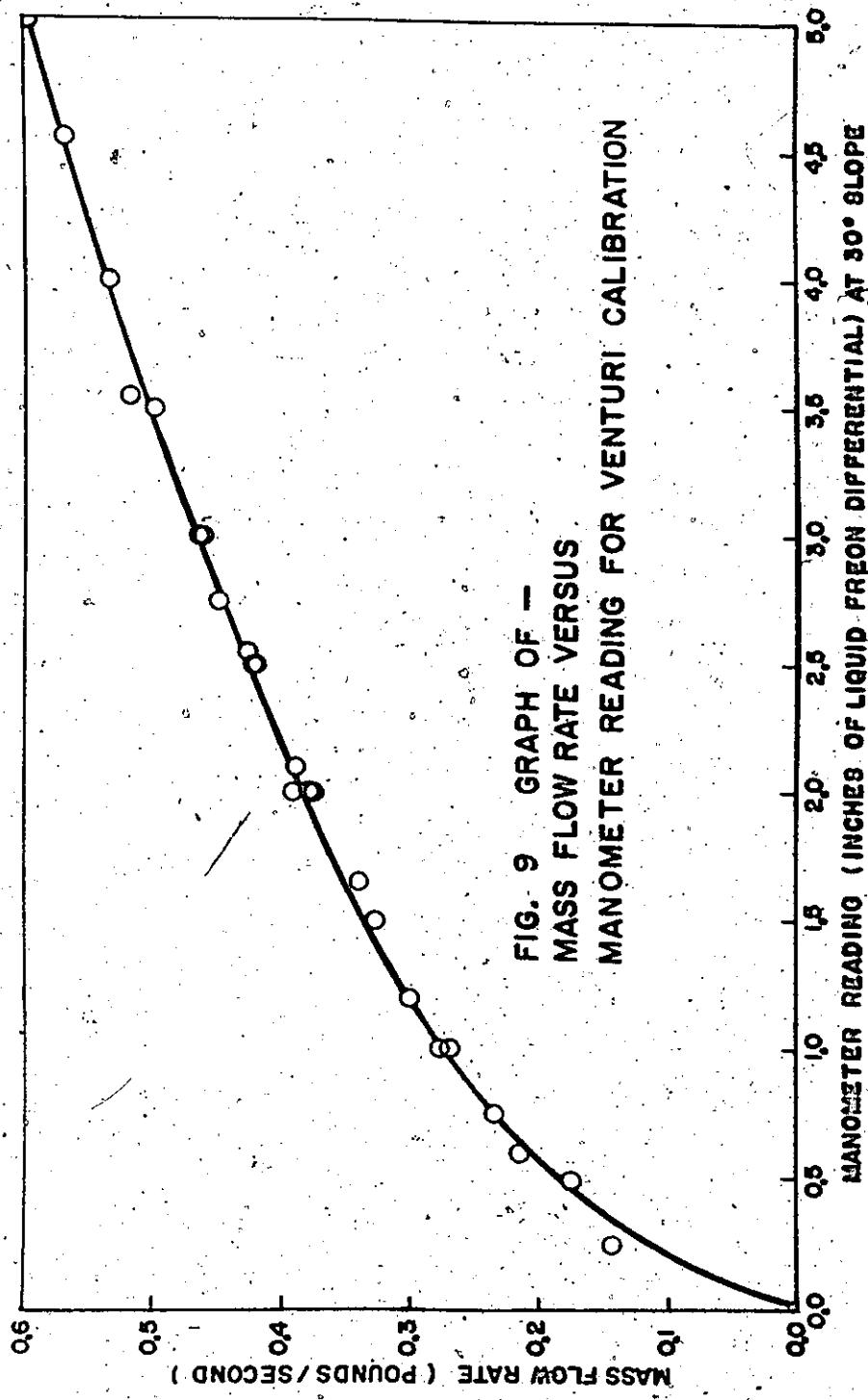


FIGURE 9

Outlet Contraction Angle 7°

Predicted Pressure Loss

in Percentage of Actual

Differential 11%

Location 24 inches below

liquid/vapour interface.

The last detail was chosen after assuming that the pressure differential across the venturi would never be greater than 1.3 psi which corresponded to a flow rate of 1.6 pounds per second.

The venturi was calibrated (see Figure 9) in situ using a constant head of Refrigerant 113 as the calibrating liquid. A weighing tank and timer were used to calculate the mass flow rate through the system. The mass flow reading accuracy for calibration was 0.1 lbm with a possible error of .2% with a starting and stopping error estimated as one second for minimum time intervals giving an error of $\pm 2\%$ with an overall accuracy of $\pm 2.2\%$. The venturi was installed three inches upstream of the heat input section in a six inch long section of glass pipe. Table 4 lists the glass piping in order from the reservoir cross tee-piece to the heat input section inlet tee-piece.

TABLE 4
List of Inlet Glass Piping

1. 4 inch long 2 inch to 1 inch reducing glass piece
2. 12 inch long glass pipe
3. 3 inch long glass pipe
4. 4 3/4 inch equal 90° bend pipe
5. 6 inch long glass pipe (venturi section)
6. 3 inch long glass pipe

8. Reservoir Section

The reservoir section pipe inside diameter was 2 inches. It is constructed from 4 components: a 2 inch I.D. glass tee piece, each leg being 4 inches long; a 42 inch long section of glass pipe; a 2 inch I.D. glass cross-piece, each leg being 4 inches long and one blank buttress end piece 3 7/8 inches long.

9. Pressure Taps

All pressure taps throughout the system were 0.040 inch I.D. holes drilled into the nylon inserts. After drilling each hole was inspected and any burrs at the edges of the tap holes were removed. Provision for connections to pressure tap lines was made by undersize drilling of the pressure tap outlet such that 0.040 inch I.D. steel hypodermic tubing could be press fitted into the expanded pressure tap hole. The means of connection of the larger bore pressure lines to the hypodermic

tubing was a brass reducer ferrule silver soldered to the free end of the hypodermic tubing. The ferrule size was such that the connecting tubing of the pressure lines slip tightly over the ferrule.

The only exception to the above were the fittings on the nylon inserts for the orifice plates. In this case a hollow no. 6-32 screw was used to connect a 1/4 inch O.D. brass connecting piece to the nylon insert as shown in Figure 5A.

10. Manometers

Two types of manometers were used for measuring pressures in the system. One type was a mercury-in-glass U-tube manometer open to the atmosphere used to indicate static pressures. The tubing used was 0.075 inch I.D., 0.187 inch O.D., 30 inch long standard manometer glass tubing mounted vertically in front of 1/20th inch per division graph paper and a reading accuracy of 0.05 inches. The connection between the system and manometer was 0.185 inch I.D. flexible hard polyvinyl tubing. Measurements were made of the damping of the system as calculated from experimental data and it was found that the damping factor was 0.59 at a natural frequency of 0.6 Hz with the system fully charged with the working fluid.

To indicate differential pressures, inverted, 22 inch long, sloping U-tube glass manometers were used. Each manometer was constructed from 0.060 inch I.D., 0.250 inch O.D. precision

bore glass tubing with a branch at the top of the U to provide a port for injection or withdrawal of the manometer working fluid. Sealing of the bleed branch was by means of a standard automotive, brass tire valve connected to the manometer by a short length of neoprene tubing. The connecting lines from the manometer tubes to the 0.040 inch I.D. hypodermic tubing pressure taps were 0.185 inch I.D. flexible hard polyvinyl tubing connected to the manometer by short lengths of neoprene tubing.

Some problems were encountered with the design of the sloping tube manometers. The differential pressure manometers used for measuring pressure losses between pipe joints, differential pressure across orifice plates and venturi differential pressure were originally designed for using mercury as the measuring fluid. From preliminary testing it was found that mercury was not satisfactory for several reasons; these being that the manometers would require only a 2 1/2 to 3 degree tilt from horizontal, introducing a large possible reading error and that because of the low surface tension of R-113 the mercury would trap globules of the refrigerant against the manometer tube wall resulting in changes in actual cross-sectional tube area.

A fluid that was immiscible in R-113 and that would allow a slope sufficiently large so as to reduce the probable reading errors was diligently sought for without a satisfactory solution. Water was ruled out because of similar surface

tension problems as the mercury-R113 situation. Other standard manometer fluids were also tried but they had other drawbacks such as the fluid colouring being bleached out or absorbed by the working fluid so that it was impossible to locate the interface between the two liquids.

Finally it was decided to use an inverted manometer with a 30° slope using air as the displacing medium although this meant putting up with time consuming checks for leaks and extra care taken in purging the tubes and lines of extraneous air bubbles. This decision cleared all problems of differential pressure measurement except for large overall system pressure drops and these were simply solved by using similar manometer tubes with an overall length of 30 inches mounted vertically. The measurement scale for all of these manometers was 1/10 inch per division graph paper with a reading accuracy of 0.1 inches.

C. Experimental Procedure to Run a Test

The procedure for a testing sequence is:

1. a previous determination of the type of testing to be conducted will dictate whether:
 - a. An orifice plate of a particular diameter ratio is inserted in the riser section at some elevation above the bottom glass tee-piece inlet centerline or:
 - b. A chosen combination of heating elements is inserted in the heating tube of the heat

- input section and located at a particular position relative to the outlet centerline of the heat input section.
2. Turn on the thermocouple reference junction.
 3. Make all necessary connections to the power supplies being used.
 4. Charge the system with the working fluid by pressurising its storage container and forcing the working fluid into the system through a valve located at the bottom of the heat input section.
 5. Check for any leaks in the thermosiphon loop as the working fluid slowly rises to the fill line.
 6. Purge any trapped air from the manometer lines by squeezing the neoprene connecting tubes at the bottom of the manometers.
 7. Check level of working fluid in reservoir section and top off to desired fill line.
 8. Check for zero reading on manometers.
 9. Initiate circulation by injecting air at the bottom of the riser section.
 10. Switch on thermocouple potentiometers and check settings of reference junction and standard cell compensation circuits.
 11. Compare temperature readings of the thermocouples in the system.
 12. Record barometric pressure.

13. Supply sufficient power to heating element(s) to provide a uniform heat flux capable of sustaining circulation after air injection in the riser section ceases.
14. Decrease rate of air injection gradually as the temperature of the working fluid increases and boiling commences in the riser.
15. Stop air injection and allow the system to stabilize.
16. Vary heat flux slowly to achieve either minimum heat input test or maximum heat input test.
17. Allow system parameters to reach steady state before taking readings.
18. After system start up, changes in heating element position were carried out at reduced power input while the system is operating. If the change in heater location is done slowly the system will have sufficient time to adjust to the change but if the change is too rapid it will usually cause a reversal.
19. During a flow reversal the heating element(s) were powered down. This was done since it was found that several changes in flow direction would usually take place and it is often quite possible to reacquire the desired flow direction by repowering the heating element(s) at the proper moment.

If this is not done it is necessary to return to step 9, jump to step 14 and continue from that point to run another test.

20. For orifice plate testing it is necessary to drain the system and start at step 1, jump to step 5 and run through the rest of the test sequence omitting steps 10, 11 and 12.
21. Because of Refrigerant 113's ability to dissolve oils it was necessary to periodically change the working fluid used in the system. The contaminated fluid was run through a distillation apparatus to remove the contaminants and then re-used in the system.

IV RESULTS

1. Introduction

All the information gathered from the tests conducted with the thermosiphon loop have been collected and collated for presentation in this chapter. The information presented covers the Preliminary Operating Tests, the Orifice Plate Experiments, the Heater Experiments and a presentation of notable photographically recorded observations.

1.1 Preliminary Operating Tests

When construction of the system was completed the initial attempts to achieve sustained downflow operation using the 22 inch heating unit were unsuccessful. Visual observation of the flow indicated that as the rate of air injection at the bottom of the riser was decreased, to enable the buoyancy forces created by the flashing liquid to take over, the flash point in the riser would start to vary periodically with time. This fluctuation caused periodic changes in flow rate and in the amount of vapour on the heating surface. These fluctuations increased in amplitude ultimately causing a reversal of flow.

Because of the large amount of vapour being generated on the 22 inch heating surface it was decided that longer heaters with a reduced heat flux would likely be more successful. In addition, it was decided to insert a flow restriction in the riser to act as a flash initiator by causing an abrupt

drop in the fluid pressure across the device. The use of a flow restriction in the form of an orifice plate in fact made sustained reversed flow possible with the 22 inch heating unit.

This success lead to an investigation of the operating limits imposed on the heat input to the system when the size and location of the orifice plate was varied in the riser. The use of longer heaters in the heat input section was also found to improve the operating range of the system and lead to an investigation of the effect of various heater lengths and positions on the system performance.

The results of these investigations are presented in the following sections along with the pertinent photographic or visual observations.

Although the raw and subsequent reduced data has not been included in this thesis, it has been collected in a single volume and is available in the Mechanical Engineering Office Library as Report HT-73-I entitled "Data Summary of the Reversed Flow, Boiling Thermosiphon Loop Tests for Master's Thesis" by R. Gaspar. Sample data however has been included in Appendix II.

1.2 Orifice Plate Experiments

Experiments to determine the effect of various sizes and locations of orifices were conducted in the riser. The orifices tested had a range of (orifice diameter/riser diameter) ratios from 0.5 to 1.0 in increments of 0.05 and could be positioned 2 inches, 46 inches, 67.5 inches, 74 inches,

81 inches or 92 inches above the inlet "Tee" centerline.

The effect of the orifice plate diameter ratio on the heat input limits is shown in Figure 10 which indicates that there is little variation in the maximum heat input until the diameter ratio drops below approximately 0.6. It also indicates that there is little variation in the minimum power input with the exception of a diameter ratio of 1.0, at which point the minimum heat input required to maintain reversed flow is significantly higher. This demonstrates that an orifice plate can be used to further lower the minimum power requirements of a reversed flow system if the situation requires such a reduction. It should be pointed out that such a system operating with an orifice plate in the riser and with minimum heat flux is susceptible to premature reversal if the change in heat input is too large.

The reason for this instability is readily apparent from an inspection of Figure 10 which shows two operating modes, the smaller of these being a range of minimum heat flux where flow oscillations occur but do not lead to reversal. This range of oscillating reversed flow does not exist for diameter ratios approaching unity. Also to be noted is that the changeover point from stable reversed flow to oscillating reversed flow is not a function of diameter ratio except when no orifice is present.

The stable operating range indicated in Figure 10 is much larger, the flow rate is steady and the system is

**GRAPH OF TOTAL HEAT INPUT
VERSUS ORIFICE DIAMETER RATIO**

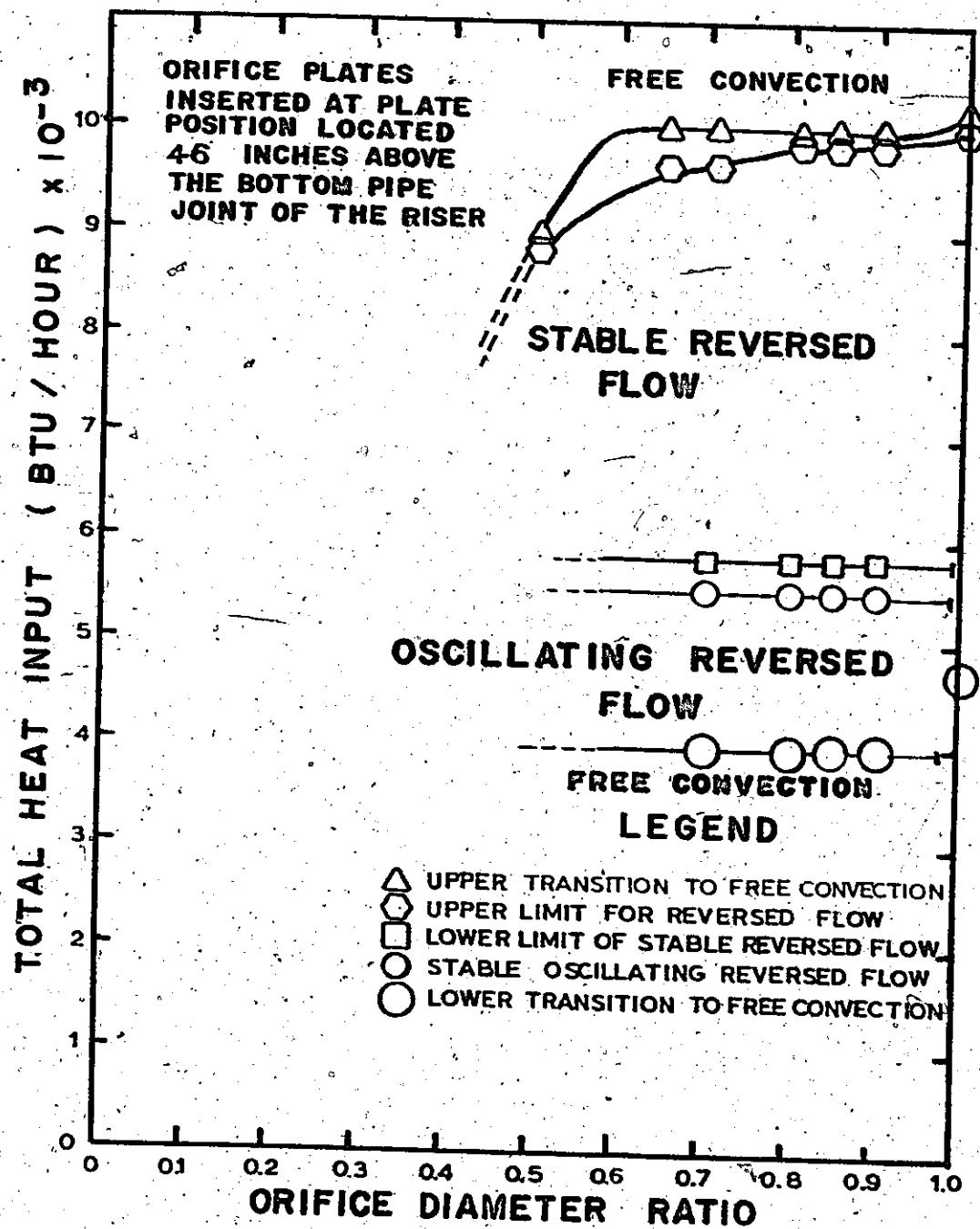


FIGURE 10

not as sensitive to sudden or large changes in heat flux.

Figure 11 indicates that there is no significant variation in maximum heat input when an orifice plate with a fixed diameter ratio is used and its position in the riser is changed.

The following visual observations of the thermosiphon loop were noted:

1. The presence of an orifice plate at any location in the riser caused a periodic fluctuation in flow rate evidenced by a change in flash point position for heat input values near either the maximum or minimum values required to maintain reversed flow.
2. Flow separation from the riser wall was noted to occur on the downstream side of the orifice plate for diameter ratios of 0.7 or less at locations 45 inches or higher above the riser inlet centerline and did not necessarily indicate the starting point for flashing. Also the flow separation disappeared or diminished in extent when flashing commenced upstream of the orifice plate.
3. Perturbations of the order of 300 Btu/hour of either increase or decrease in heat input could initiate cyclical changes in the location of the flashing point in the riser when the system was operating in the stable operating range. These

GRAPH OF TOTAL HEAT INPUT VERSUS
ORIFICE PLATE POSITION IN THE RISER

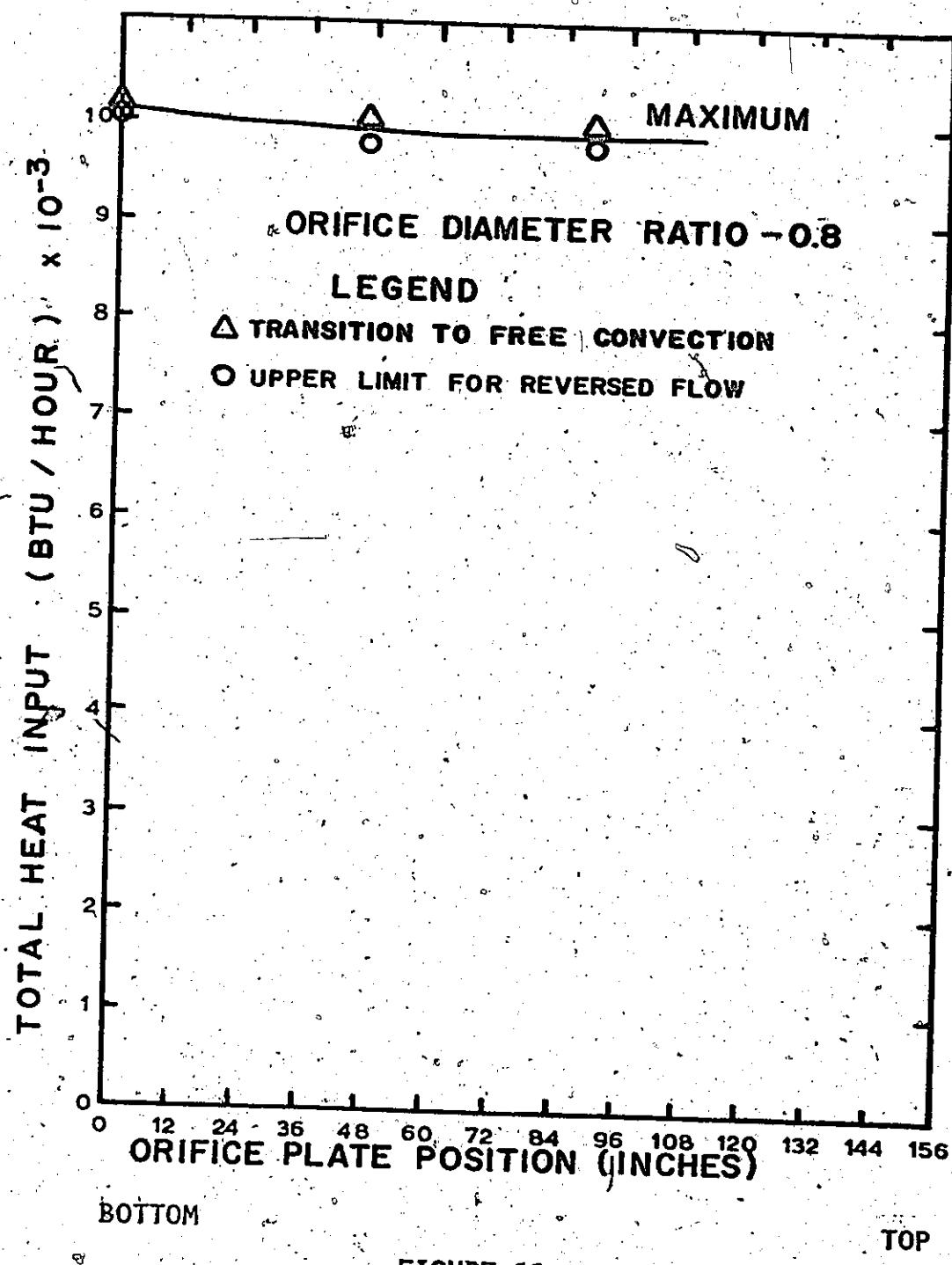


FIGURE 11.

cyclical changes affected both the flow rate and the heater section outlet temperature such that the system would continue to hunt for a stable flash point location. Generally the system was capable of attenuating the oscillations allowing a stable flash point to be reached. However if the heat input was near the maximum, reversal in flow direction would accompany the oscillations.

4. After a number of shorter lengths of piping were used to construct the riser to allow for insertion of orifice plates and instrumentation it became evident that, with no vapour carryover, the piping joints were producing nucleation sites for flashing even when the orifice plates were not used. With vapour carryover from the heat input section the location of the flash point was seen to be independent of the pipe joints. The bubbles of vapour appeared to provide all the necessary nucleation sites in the riser.

6. The length of time required for the system to reach steady state was sometimes as long as 15 minutes for step changes in heat input of 150 Btu/hour when the system was operating near the maximum heat input value. In fact on several occasions with orifice plates in place flow reversals took

place after steady state had apparently been reached and data was being recorded.

7. Static electricity charges were noted to exist on the outer surface of the glass riser.

1.3 Heater Length-Position Experiments.

Tests were conducted to determine the effect of varying the length and position of the heat input units on the operating characteristics of the thermosiphon loop. The experiments conducted were carried out for the following range of variables:

Heating Lengths. 11, 22, 36, 48, 60 and 84 inches

Position of the Lower End of Heater Relative to Heater Section Outlet Centerline. 0 to 50 inches

For the variables listed it was determined that overall these tests the rate of heat input varied from a minimum of 3,500 Btu/hour to a maximum of 12,000 Btu/hour.

The corresponding flow rates measured varied from a minimum of 0.383 lb/sec to a maximum of 0.485 lb/sec.

Before going further it should be noted that all graphs which refer to the heaters are based on the true heated length of each unit, not on the nominal physical length by which they are designated in this thesis.

1.3.1 System Output Quality

In order to compare the overall evaporation performance of the various configurations tested a term Output Quality "X" was defined as follows:

X = Heat added per pound to raise the enthalpy above the saturation enthalpy at the condenser pressure/Heat required to completely vaporize one pound of fluid at the condenser pressure.

Symbolically this expression may be written as

$$X = \frac{h_{out} - h_{sat}}{h_{fg}} \quad \text{Eqn. 7}$$

or, to more clearly indicate its origin, as:

$$X = \frac{(h_{out} - h_{in}) - (h_{sat} - h_{in})}{h_{fg}} \quad \text{Eqn. 8}$$

where the first term in the numerator of Equation 8 is the enthalpy rise in the heat input section and the second term is the enthalpy rise necessary to bring the fluid at inlet up to the saturation enthalpy in the condenser.

To further simplify the calculation of the quality, Equation 7 can be rewritten in terms of temperatures. This method of calculation was selected rather than finding a correlating equation for h_{out} versus T_{out} because the numerator of Equation 7 can be replaced by $C_p(T_{out} - T_{sat})$ since the specific heat at constant pressure is commonly given in a table of properties of most liquids. Thus we have

$$X = C_p \frac{(T_{out} - T_{sat})}{h_{fg}} \quad \text{Eqn. 9}$$

As the calculations which were carried out for this thesis were in the form of a program for a Hewlett Packard 9100B calculator, an expression for h_{fg} in terms of T_{sat} was determined. This was done to allow the operator to input only two variables, T_{out} and T_{sat} . Thus the efficiency calculation is based on two measurements; the condenser operating pressure which can be converted to a corresponding saturation temperature and the heat input section outlet temperature. Thus the final equation used for computational purposes with appropriate numerical values is:

$$X = \frac{0.277 (T_{out} - T_{sat})}{72.179 - 0.077 T_{sat}} \quad \text{Eqn. 10}$$

1.3.2. Comparison of Heater Performance

Figure 12, a graph of system output quality versus length of heating element for the lower end of the heating element located at the outlet centerline of the heat input section, indicates the minimum and maximum qualities achieved by the thermosiphon.

Note that the minimum operating quality is not a function of the heater length except for a lower limit on the length of a heater which would be capable of sustained operation. This limit is indicated by the intersection of the extrapolated curves. The curve for the upper limit output quality increases asymptotically with the length of the heater.

The effects on the output quality caused by changing

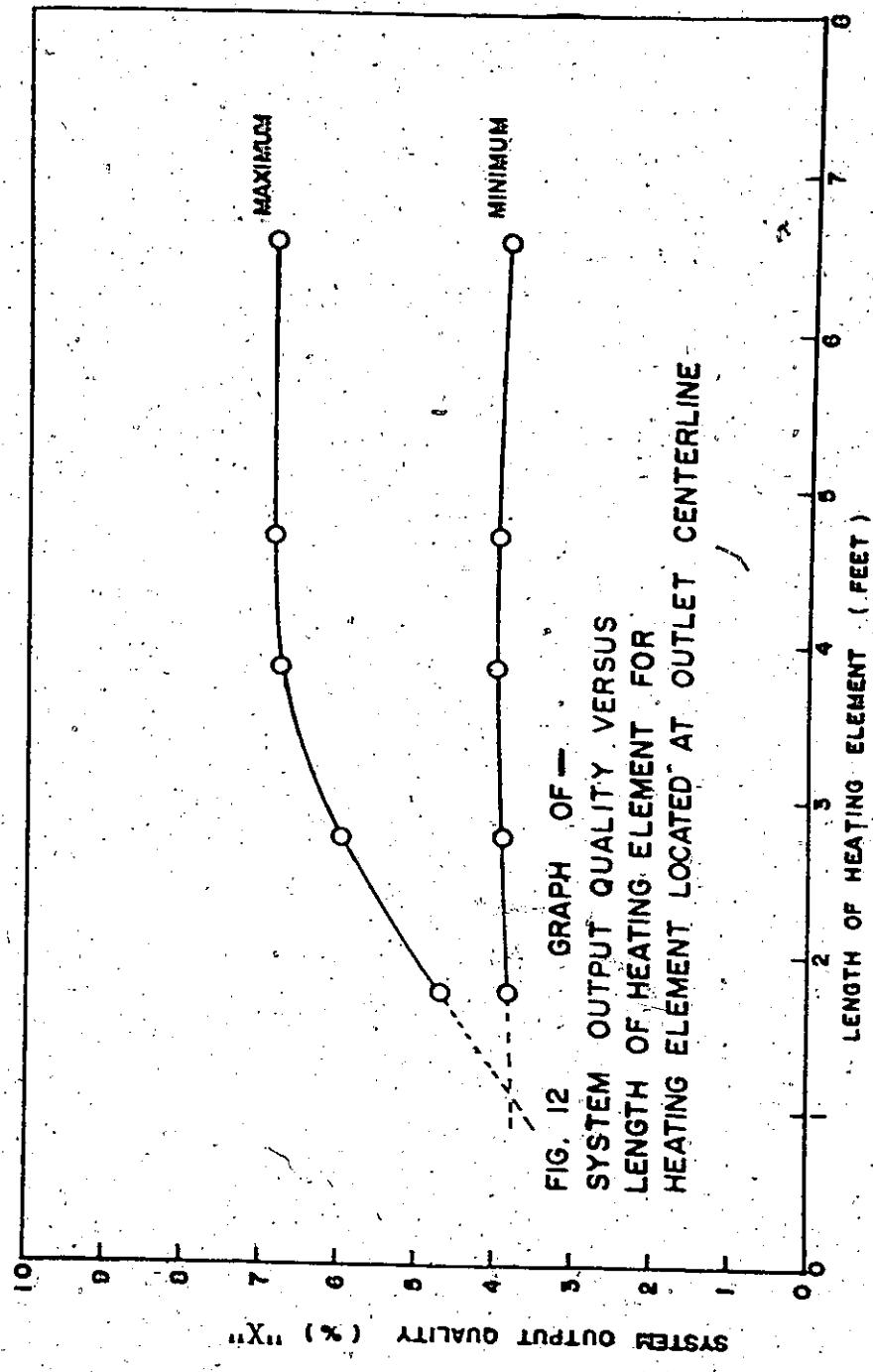


FIGURE 12

the vertical position of the heating elements in the heat input section are illustrated in Figure 13. This graph of system output quality versus position of the bottom end of the heating element above the outlet centerline compares the output qualities achieved by the five heaters listed.

The graph shows that in addition to the previously noted fact that the minimum output quality is not a function of heater length, the minimum is also not a function of heater position. The graph also indicates that there is a decrease in output quality as the heater is elevated above the outlet centerline, the longer heaters being more adversely affected.

A situation which is also evident is the intersection of efficiency values for the 36 inch heater with the values for the 48 inch and 60 inch heaters. In order to resolve this apparent discrepancy further testing of the 36 and 48 inch heaters was undertaken. Unfortunately a modification had already been made to the heat input section in the form of an instrumented heated surface as described in Chapter III, section 3. Figure 14, a graph of system output quality versus heating element position above outlet centerline illustrates the results of this additional testing. As can be seen in the graph the output qualities of the two heaters appear to converge but do not intersect.

It was observed that the output qualities of the 36 inch and 48 inch heaters are slightly lower than those for similar positions in Figure 13. In addition the slope

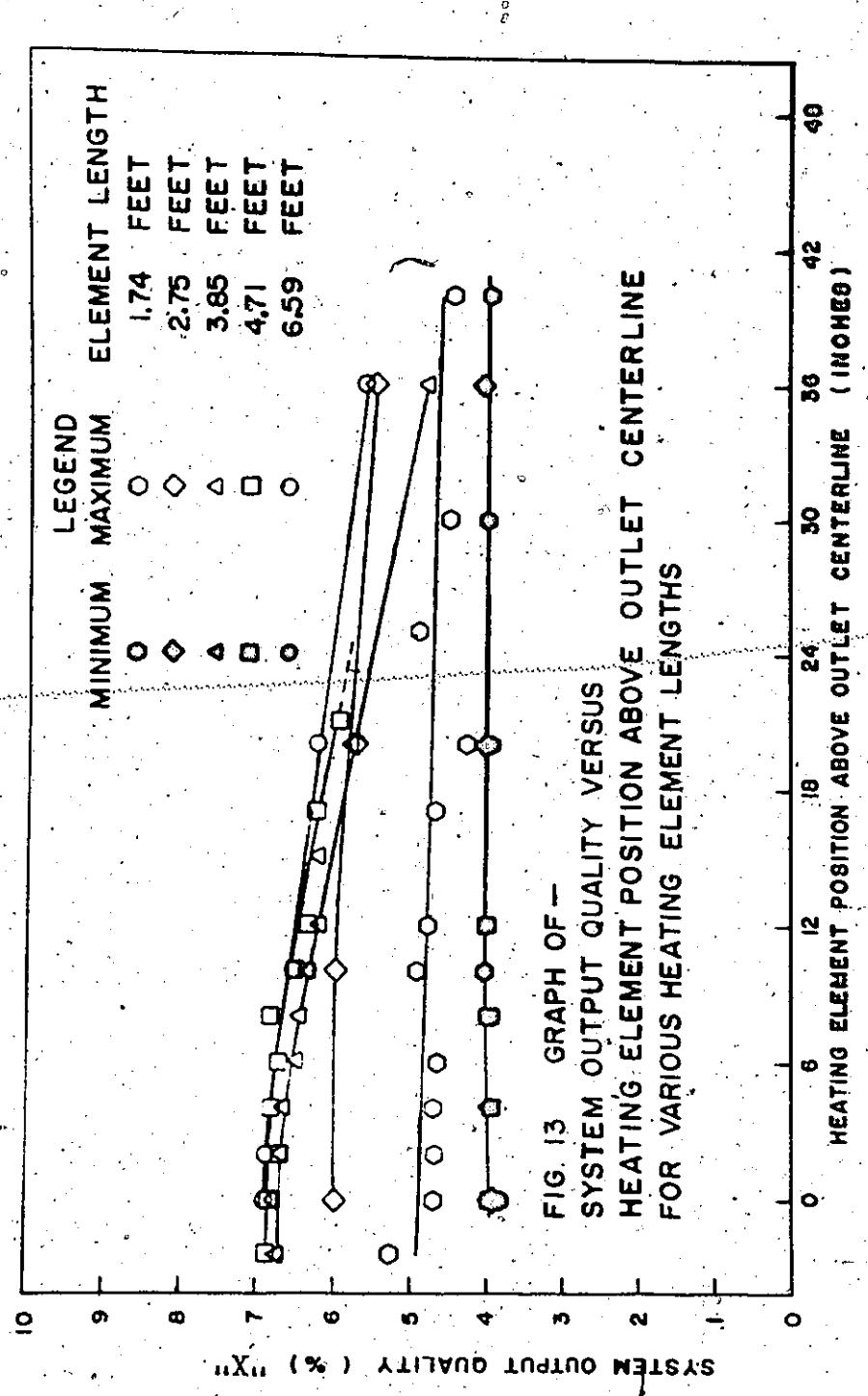


FIG. 13 GRAPH OF -
SYSTEM OUTPUT QUALITY VERSUS
HEATING ELEMENT POSITION ABOVE OUTLET CENTERLINE
FOR VARIOUS HEATING ELEMENT LENGTHS

FIGURE 13

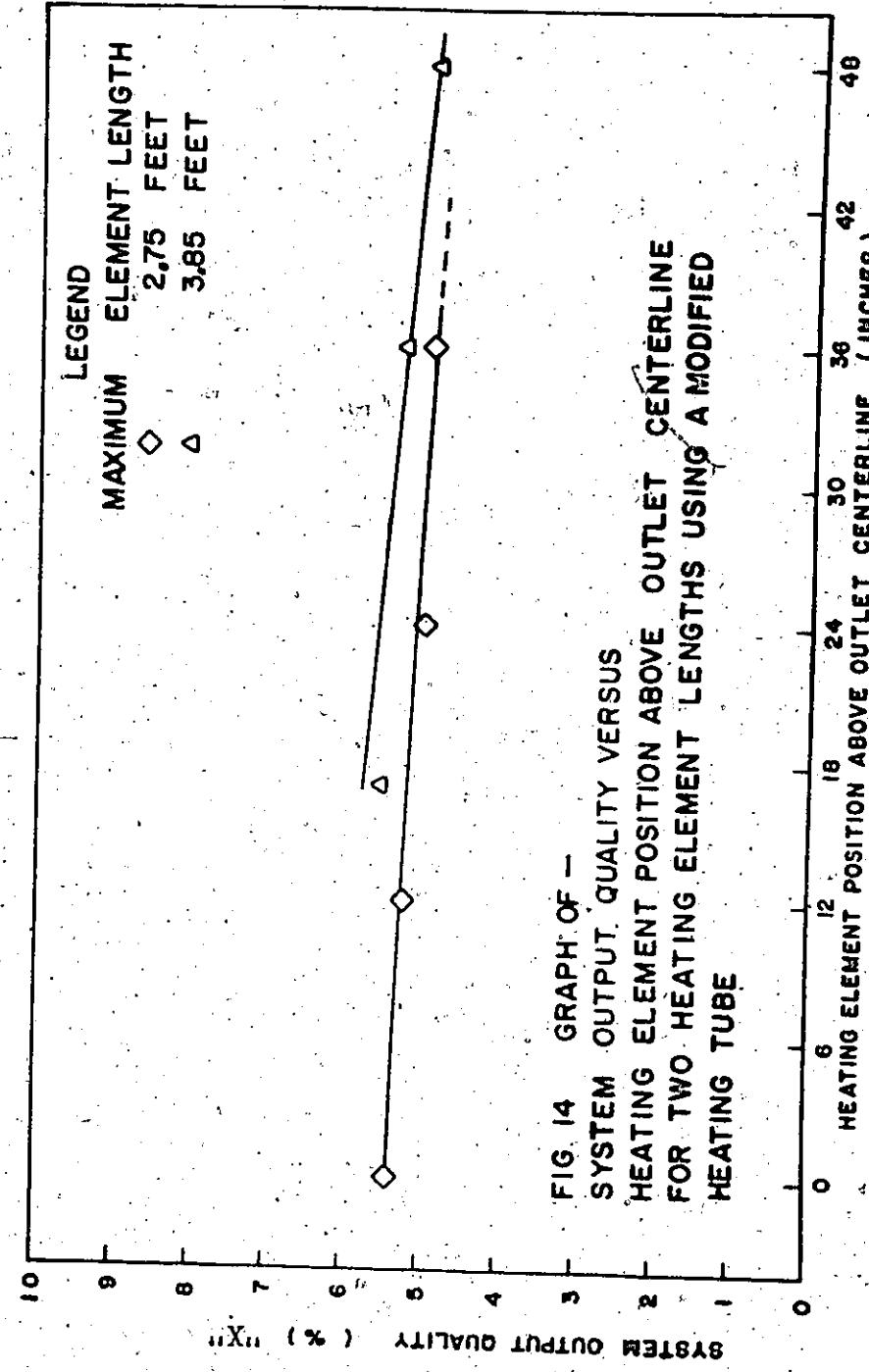


FIGURE 14

of the output quality curve for the 36 inch heater in each of the graphs was practically identical. It was felt that the 12.7% displacement of the output quality curve for the 36 inch heater was due to the replacement of approximately 18% of the copper heating surface with epoxy filler over the thermocouple leads. This increases the copper surface heat flux for a given power input since epoxy conducts heat to a lesser degree than copper. Thus the author believes that the multiplication of the values of Figure 14 by 1.127 to bring the two 36 inch long heater test results into line was warranted.

To arrive at a corrected graph of system efficiency versus heating element position, one final correction was made for all heaters and this was to take into account the unheated bottom end of each heater. This unheated portion is due to insulating end seals and allowances for internal connection of the lead wires. Thus Figure 15, a graph of system output quality versus corrected heating element position above outlet centerline, is the final outcome of combining the information of Figures 13 and 14 and also indicates a correct placement of the bottom end of each heater accurate to $\pm 1/8$ inch.

The graph shows that the trends in output quality are the same for the 48 inch, 60 inch and 84 inch heaters although each successively longer heater improves the output quality very slightly. What can also be noted is that the

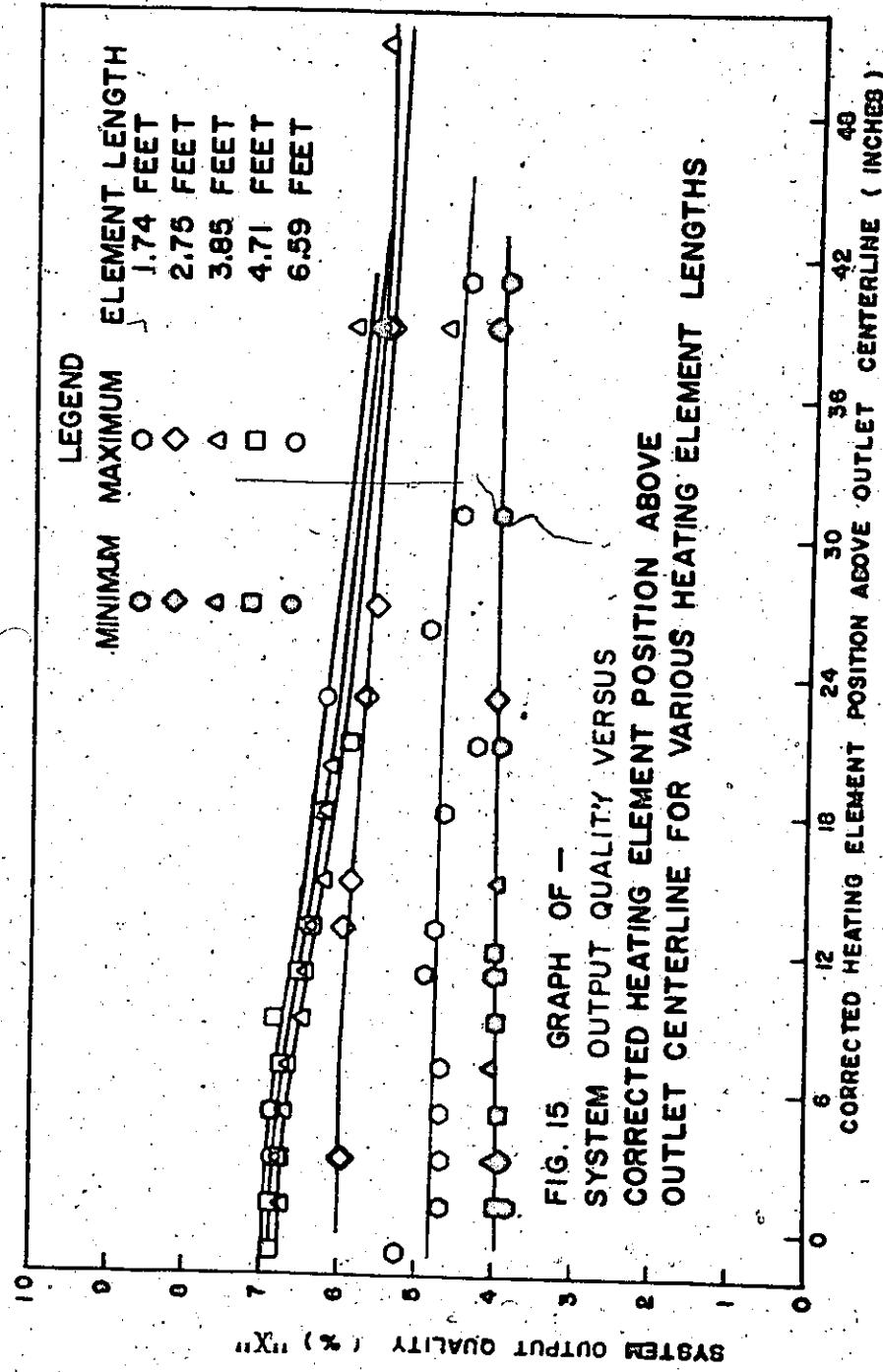


FIGURE 15

36 inch heater has an output quality line which approaches the operating curves of the three previously mentioned heaters at the 40 inch position and appears to then run parallel to them. The rest of the graph shows the same information previously discussed for the minimum output quality line of the system.

One piece of additional information relating to the 22 inch heater should be discussed and this concerns the scatter of data points in both Figures 13 and 15. The scatter was caused by minor flow instabilities in the heating section and the only time these appeared was during the testing of the 22 inch heater. These instabilities were characterized by a cyclical change in the amount of vapour being generated on the heating surface and these changes were observed to diminish as the heat flux increased or the heater was moved higher in the heat input section.

For low elevations of the heater the cyclical changes disappeared when the heat input reached such a level that areas of the heating surface were no longer in contact with the coolant flow. Indeed, the ability of the system to operate with dry patches on the heating surface, as shown in Figure 20, was another characteristic of this heater length which was not observed during testing of the rest of the heaters. Since it was felt that the system should not operate with dryout the maximum output quality of the 22 inch heater was determined by the value at which dryout appeared and because this limit is

determined by observation of dry patches rather than a flow reversal there is significantly more scatter in this data.

1.3.3. Additional Information and Photographic Observations

Figure 16, a graph of mass flux versus heating element length for the bottom end of the heating element located at outlet centerline, indicates the small variation in mass flux exhibited by the system as the heat input was increased from the minimum to the maximum value required for stable operation.

Figure 17 is an enlarged photo of the outlet tee of the heat input section and illustrates the bubble distribution as well as showing the relatively large voids which may become attached to the heat input section outer wall. This condition generally indicates that a flow reversal is imminent.

Figure 18 is a photo of the outlet tee taken when the system was near reversal. This picture shows a different characteristic of the system which can be used to help predict when the maximum heat input has been reached. This characteristic is the formation of a large, irregular bubble in the side branch of the heat input section outlet tee. This bubble may grow in size until it occupies one-half of the outlet flow area before a reversal occurs.

Figure 19 is a view of part of the heat input and horizontal sections. The picture shows the void being produced on the heating surface as well as the helical vapour

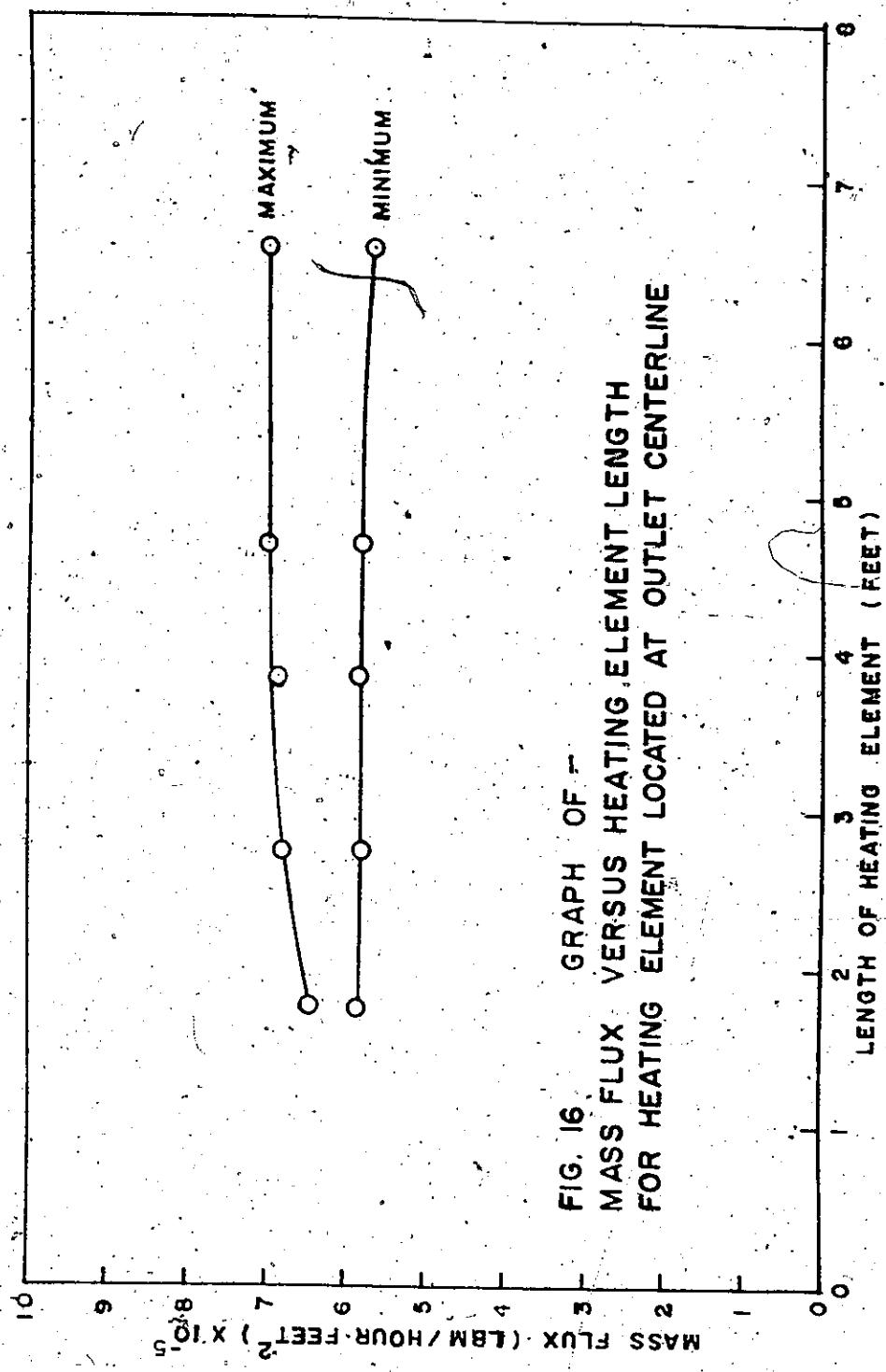


FIGURE 16

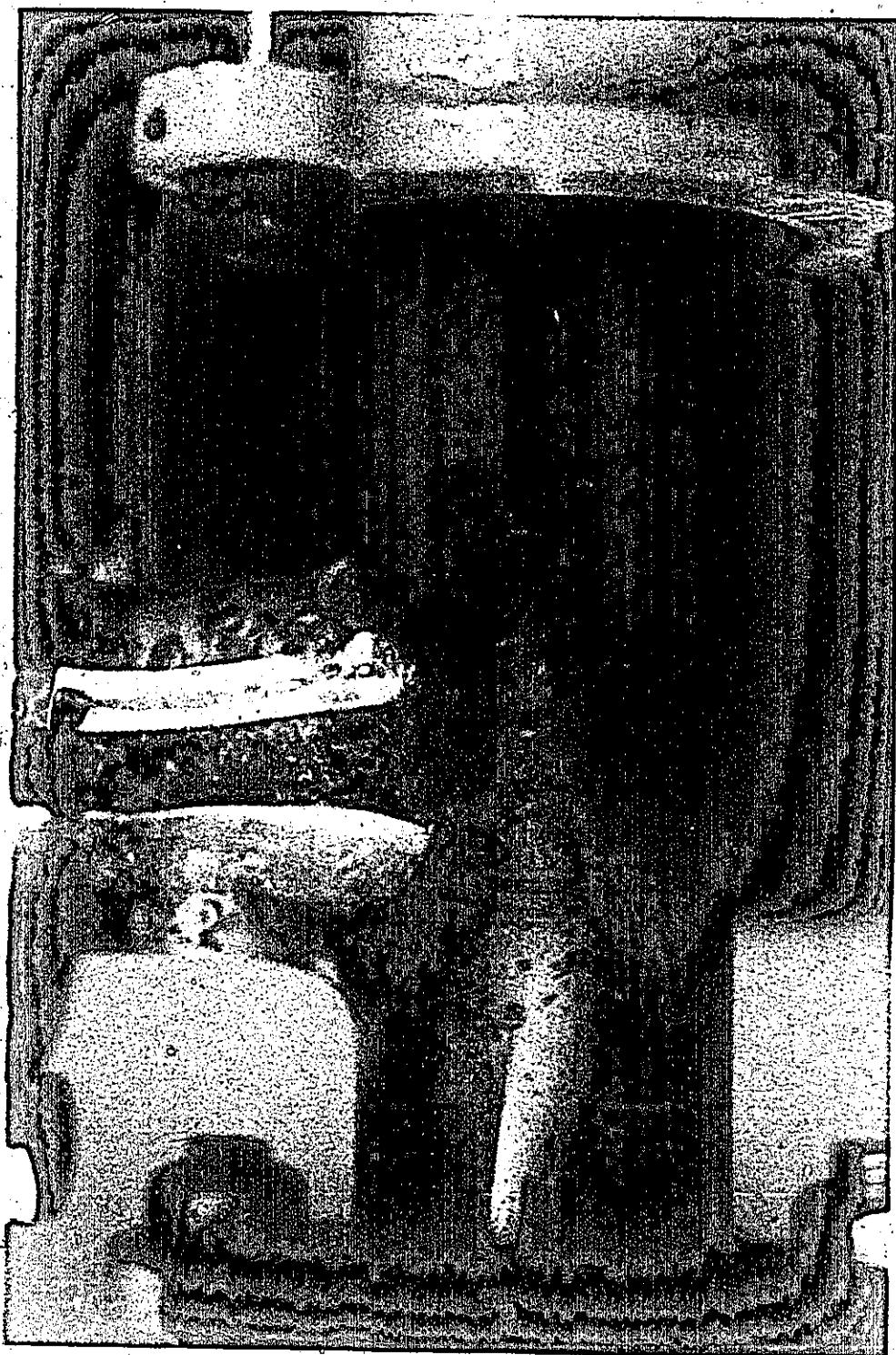


FIG. 17

PHOTOGRAPH OF VOID ATTACHMENT TO A
HEAT INPUT SECTION JOINT

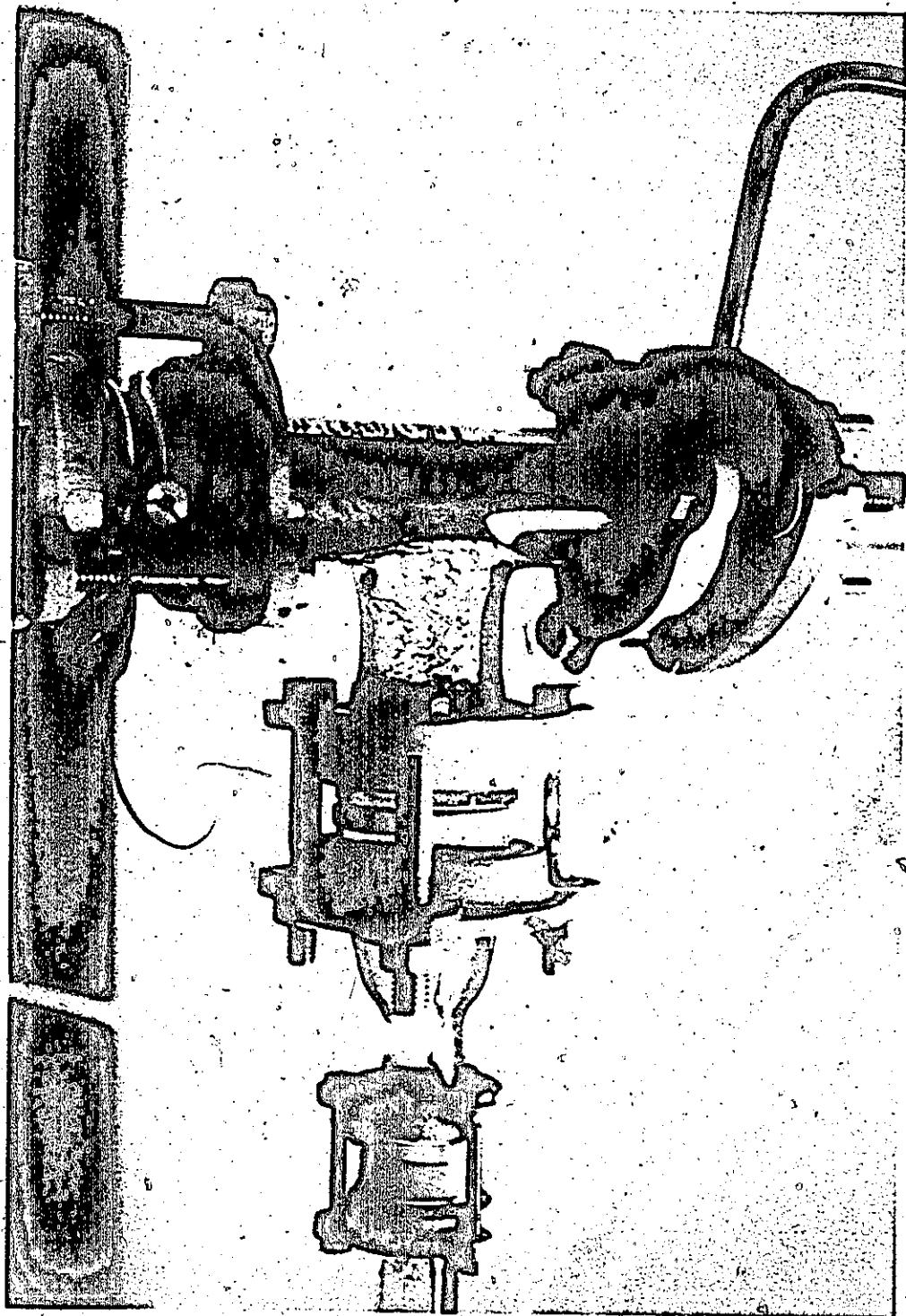


FIG. 18
PHOTOGRAPH OF LARGE VOID FORMATION IN
THE SIDE BRANCH OF THE HEAT INPUT SECTION
OUTLET "TEE"

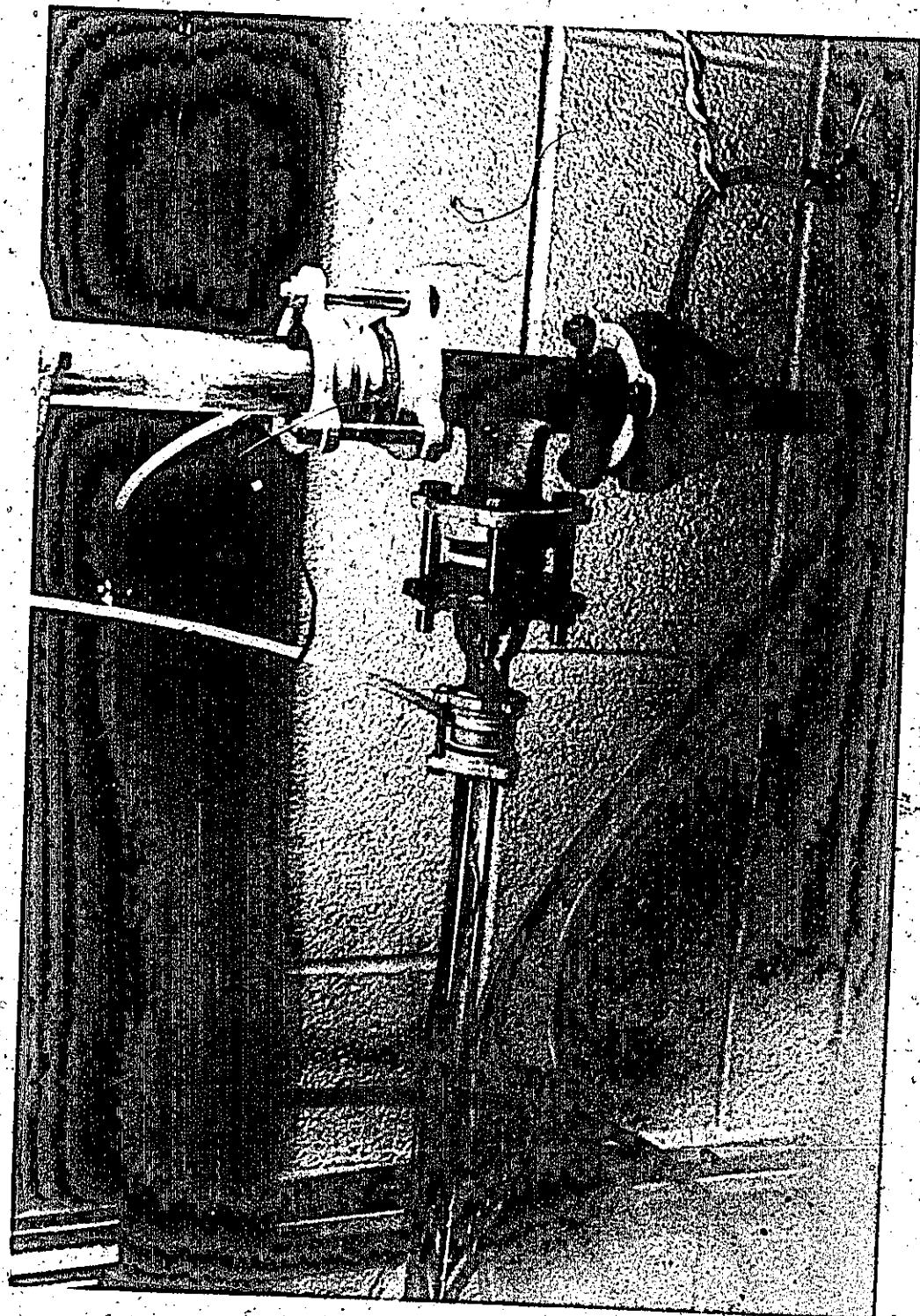


FIG. 19
PHOTOGRAPH OF SINGLE HELICAL VAPOUR TUBE IN
HORIZONTAL CONNECTING SECTION

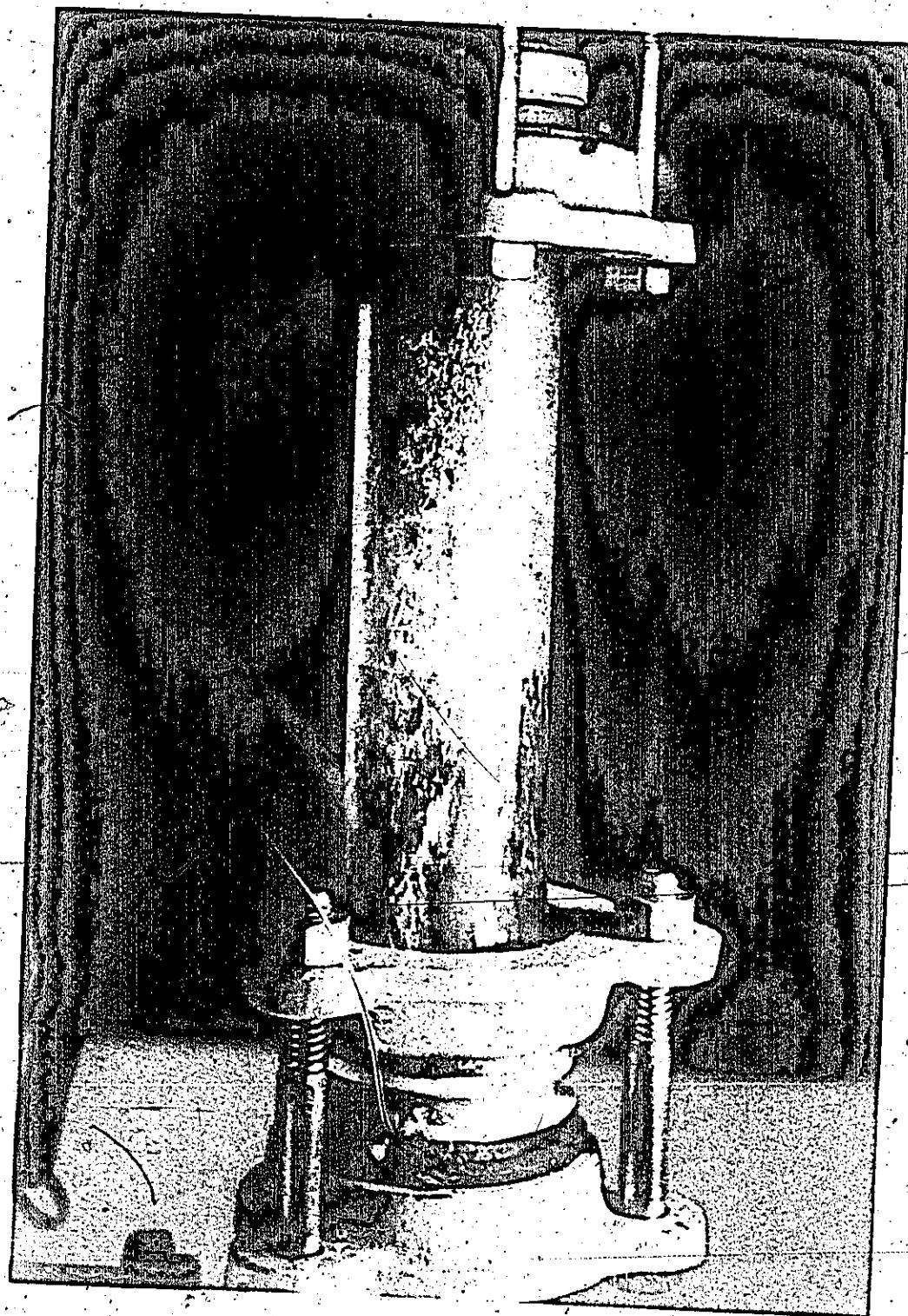


FIG. 20

PHOTOGRAPH OF DRYOUT OF HEATING TUBE SURFACE

tube which can be seen in the horizontal section. This too is another possible flow configuration indicating that maximum heat input has been reached. In fact, it is quite possible to observe twin helical vapour tubes which may exist side by side in the horizontal section but which may never join until they reach the inlet tee of the riser section.

One last piece of information remains to be discussed and that is the mode of flashing in the riser. During the orifice plate tests it was observed that the joints in the riser seemed to provide nucleation sites for flashing of the fluid. This same observation was made for all tests concerned with the heaters.

The flash point in the riser always jumped from one joint to the next. Subsequent tests of the system with larger riser diameters have proven that a completely smooth walled riser devoid of joints or projections has a detrimental effect on the operation of the thermosiphon. In fact a string of disks were suspended in the larger risers and these did allow flashing to take place and also lowered the minimum heat input limit. Consequently it is felt that the reason that the minimum thermosiphon operating limit is constant for all heaters regardless of their position is because of the particular geometry used which put the last joint which could act as a flash initiator 5.3 feet below the riser outlet.

V MODEL

A simple mathematical model for the two phase reversed flow thermosiphon was postulated for the prediction of the maximum and minimum performance of the loop.

The assumptions incorporated into the model are:

1. At all riser locations where vapour is present the flow is considered to be homogeneous with no slip between the liquid and vapour phases. Such mixtures have the kinematic viscosity of the non-flashing liquid and a density based on an empirical variation of void fraction between zero at the flash point to a maximum at the exit of the riser, the maximum void fraction being determined by the quality at the outlet of the riser. The flash point locations used for the prediction of maximum and minimum performance are those which have been recorded as observed during the experimentation.

2. A constant heat input per unit heater length was assumed.

3. No boiling occurs in the heat input annulus.

4. There is no heat transfer from the loop to the surrounding atmosphere.

The computation of the flow rate is accomplished by evaluating separately the static pressures around the loop and the frictional pressure losses due to the moving fluid. Thus the fluid will be treated as being inviscid for the calculations of the static pressure at the bottom of the heat

of the heat input section and the bottom of the riser section.

The calculation of the static pressure at the bottom of the heat input section is an iterative procedure consisting of the following steps:

1. Assuming the heater section outlet temperature is equal to the inlet temperature calculate the frictionless flow static pressure at the bottom of the heater section due to the head of liquid.

2. Assume that the temperature of the bottom of the heater section is the saturation temperature for the static pressure calculated.

3. Recalculate the inviscid flow static pressure rise through the downflow tube using the expression

$$P_{HI} - P_{reservoir} = \frac{g}{g_c} [(L_T - L_H) \rho_{tin} + L_H \rho [(t_{in} + t_{out})/2]] \text{ lbf/ft}^2$$

Eqn. 11

4. Repeat steps 2 and 3 until there is negligible change in the static pressure rise.

The next part of the calculation is concerned with determining the inviscid flow, static pressure drop through the riser. The pressure drop along the non-flashing portion of the riser is given by:

$$\Delta P_{NF} = \rho_{out} \frac{g}{g_c} (L_T - y) \quad \text{Eqn. 12}$$

where y is the length of the flashing column of liquid in the riser.

The static pressure drop along the flashing portion of the riser is determined as follows:

The riser exit quality, x_{exit} , is given by,

$$x_{exit} = \frac{h_{out} - h_{L\ sat\ exit}}{h_{fg\ exit}} \quad \text{Eqn. 13}$$

For no slip

$$\alpha_{exit} = \frac{V_g\ exit}{(1-x_{exit})V_L\ exit + V_g\ exit} \quad \text{Eqn. 14}$$

Let the mean void fraction over the flashing region be

$$\alpha_{mean} = N \alpha_{exit} \quad (0 \leq N \leq 1) \quad \text{Eqn. 15}$$

where N is an empirical weighting factor which is introduced to compensate for the fact that the void fraction varies from 0 to α_{exit} , there is slip between the two phases, and the fluid does not behave as a homogeneous liquid.

Then the static pressure drop over the flashing portion of the riser is

$$\Delta P_F = y \rho_{L\ sat\ exit} \frac{g}{g_c} (1 - N \alpha_{exit}) \quad \text{Eqn. 16}$$

and the static pressure drop over the entire riser section is given by,

$$P_{BR} - P_{reservoir} = \Delta P_{NF} + \Delta P_F = \frac{g}{g_c} [(L_T - y) \rho_{out} + y \rho_{L\ sat\ exit}] (1 - \alpha_{mean}) \quad \text{lb/ft}^2 \quad \text{Eqn. 17}$$

After determination of the static pressure rise and pressure drop, the difference between the two values or the frictional pressure drop is used to solve for the volume flow rate Q according to the expression

$$Q = \sqrt{\frac{P_{HI} - P_{BR}}{\rho_{in}} \cdot \frac{2g_c}{\sum K_i/A_i^2}} \text{ ft}^3/\text{sec} \quad \text{Eqn. 18}$$

where the $\sum K_i/A_i^2$ term takes into account the summation of all friction losses through the expansions, contractions, elbows, tees, and fluid friction in the tubing. The pipe loss coefficient K is equal to fL/D .

The mass flow rate is given by:

$$m = \rho Q \text{ lbm/sec} \quad \text{Eqn. 19}$$

The method used to obtain initial estimates of the friction factors was accomplished by using Eqn. 1 and the minimum Froude Number limit of 0.31 for determining an estimate of flow velocity and consequently Reynolds Number for the heat input section which then makes estimates for the rest of the flow loop possible.

By using the results of the flow rate calculation to determine new estimates of the friction factors around the loop an iterative process can be undertaken to refine the value of the flow rate. The flash point saturation temperature was then calculated from the static pressure at the flash point in the riser. This temperature was then used as the outlet temperature from the heat input section and all the preceding calculations

starting with Eqn. 11 were repeated until there were negligible changes in the values being determined.

In order to evaluate the capability of the model the following properties and geometric data were used to determine the maximum and minimum performance for the chosen heater length.

Working Fluid - Freon 113

Condenser Pressure - Atmospheric

Heater Length (L_H) - 4.0 feet

Total Head of fluid - 13.1 feet

(L_T)

T_{in} - 110.2°F (max); 115.3°F (min)

y - 10.0 feet (max); 5.3 feet (min)

The friction loss coefficients are given for the standard geometry used.

Thermosiphon Section	K_i/A_i^2	(1/ft ⁴)
	maximum value	minimum value
2 inch Tee	3782	3782
8 inches of 2 inch I.D. pipe	124	129
Sudden Contraction	11766	11766
13 inches of 1 inch I.D. pipe	5637	5812
1 inch Elbow	20169	20169
6 inches of 1 inch I.D. pipe	2602	2683
Sudden Contraction	92307	92307
Conical Enlargement	39978	39978
4 inches of 1 inch I.D. pipe	1735	1788
1 inch Tee	315414	315414
Sudden Contraction	175230	15463
11 feet Annular Pipe	1323055	1360064
1 inch Tee	315414	315414
Sudden Expansion	175230	175230
Sudden Contraction	59403	59403
28 inches 5/8 I.D. Pipe	117293	121236
5/8 inch T.	396023	396023
13 feet 5/8 inch pipe	658518	675457
Sudden Expansion	176010	176010
40 inches 2 inch I.D. pipe	618	643
2 inch Tee	3782	3782
$\Sigma K_i/A_i^2$	3878624	3952320

All friction factors were calculated from pipe flow data using experimentally determined Reynolds Numbers. The annulus was

treated as a round pipe with diameter equal to the equivalent diameter of the annulus. By matching the experimental data to the model predictions, it was determined that a value of $N = .185$ gave the best overall simulation.

A comparison of the limiting flow rates and power inputs predicted by the model with the corresponding observed values in the thermosiphon are shown in Table 5 which also includes a maximum flow rate prediction if the riser is completely full of two phase liquid and a comparison of the predictions of minimum flow rate by the model, Bonilla's method and the limiting Froude Number Method.

TABLE 5
Comparison of Results

Heater Length 48 inches

Length of Flashing Column y feet	Observed		Predicted $N = 0.185$		Value of N for agreement of \dot{m} Qin	Predicted Qin Btu/hr
	\dot{m}	Qin Btu/hr	\dot{m}	Qin Btu/hr		
5.3	.400	4,222	.373	3,712	.215	3,881 Btu/hr
10.0	.470	10,078	.512	10,480	.154	9,815 Btu/hr

Model Predicted Maximum Flow Rate .576 lbm/sec

Model Predicted Minimum Flow Rate .099 lbm/sec

Bonilla's Predicted Minimum Flow Rate .105 lbm/sec

Froude Number Predicted Minimum Flow Rate .207 lbm/sec

VI CONCLUSIONS

The following conclusions have been reached after studying the results of the experiments:

1. A flash initiator mechanism of some type must be present in the riser to ensure that stable flashing does occur. In the absence of suitable nucleation sites the liquid becomes superheated because no boiling takes place. This is an unstable condition which increases in severity as the superheat increases until a condition where spontaneous flashing is reached. This situation creates large fluctuations in the flash point position and hinders stable reversed flow operation.

2. As indicated by the reduced values of maximum performance for the short heaters; there exists a lower limit on heater length below which boiling reversed flow cannot be attained. The maximum performance is lower because of the high heat flow rate per unit of heating surface area. The working fluid is not capable of handling this high heat flux without large amounts of void being formed. The presence of void in the heat input section produces a buoyancy force which acts to retard the flow before more flashing generates a larger buoyancy force in the riser section. Thus the shorter the heater, the sooner it produces the large amounts of void which act to reverse the flow and consequently the lower the maximum performance of the system.

3. For long heaters, heater length and position have little effect on the maximum performance of the thermosiphon which indicates that the buoyancy forces in the heat input section are negligible when compared with those produced in the riser section due to flashing.

4. For long heaters the mechanism of reversal is slightly different from that of the short heaters. In this case the maximum buoyancy force and consequently flow rate has been generated by flashing in the riser section. Any increase in heat input does not increase the amount of flashing or the flow rate beyond this limit but it does increase the amount of void present in the heat input section. As this happens the buoyancy forces generated in the heat input section oppose the increase in flow rate and presently cause a reversal.

5. For heaters longer than the minimum length discussed in the results chapter; the minimum performance of the thermosiphon is not a function of heater length or position because the only factor governing it is the buoyancy force generated by the flashing in the riser section. As the flash point temperature approaches the saturation temperature corresponding to the pressure in the condenser the differences become so small that if the fluid for some reason superheats, it may be swept into the reservoir before it flashes. Once this has occurred the buoyancy force driving the flow is gone and because heating is continuous in the heat input section the buoyancy forces generated there will favour natural convection,

thus reversing the flow direction.

In addition several conclusions become evident from studying the information provided by the model. These are:

1. Since the friction losses are a function of pipe diameter it should be possible to increase the flow rate by increasing the flow areas of the riser and heat input sections.

2. The variation in weighting factor N necessary to match the observed flow rates to the predicted values indicates that the rate of increase in void fraction per unit length of riser is not the same for the two performance limits. If the model is correct it would seem that the amount of void per unit length increases faster for lower power inputs than it does for higher power inputs. This is indicated by the larger value of N for the minimum performance limit determined for the four foot heater.

Finally it may be stated that although the reversed flow, boiling thermosiphon is operating in a metastable condition so that by exceeding either of its operating limits or altering drastically one of its variables, a reversal in flow direction takes place; it is a functional system which can be used in situations where it is necessary to have only sub-cooled boiling and no continuous external pumping of the working fluid.

APPENDIX I

PROPERTIES OF REFRIGERANT

(FREON) 113

REFRIGERANT 113
TRICHLOROTRIFLUOROETHANE

Chemical Formula	CCl ₂ F-CClF ₂
Molecular Weight	187.39
Boiling Temperature at Atmospheric Pressure, F	117.6
Freezing Temperature at Atmospheric Pressure, F	-31
Critical Temperature, F	417.4
Critical Pressure, psia	498.9
Critical Density, lb per cu ft	36.0
Density of Liquid at 86 F, lb per cu ft	96.96
Specific Volume of Saturated Vapor at 5 F, cu ft per lb	27.04
Specific Heat of Liquid at 86 F, Btu per (lb) (F)	0.218
Specific Heat Ratio (c_p/c_v) of Vapor at 86 F and One Atmosphere Pressure	1.12
Thermal Conductivity, (Btu) (ft) per (sq ft) (hr) (F):	
Saturated Liquid at 5 F	0.044
Saturated Liquid at 86 F	0.037
Vapor at Saturation Pressure at 5 F	0.0035
Vapor at 1/2 Atmosphere Pressure at 86 F	0.0045
Viscosity, Centipoises:	
Saturated Liquid at 5 F	1.28
Saturated Liquid at 86 F	0.638
Vapor at Saturation Pressure at 5 F	0.0079
Vapor at 1/2 Atmosphere Pressure at 86 F	0.0096
Relative Dielectric Strength of Vapor at 77 F and 0.4 Atmosphere Pressure (Nitrogen = 1)	3.9
Color	Clear and colorless
Odor and Detection	Faint ethereal odor. Leaks readily located with a halide leak de- tector.
Flammability	Nonflammable.
Toxicity, Underwriters' Laboratories Classification	Much less than Group 4, but more than Group 5

APPENDIX II

SAMPLES OF DATA PAGES
AND SAMPLE DATA

Sample Data Sheet

Date: May 11/72

Run No. 4.

B_a PR 736 in Hg @ 76°F

Heater: 59

Room Temp: 83.5

Riser Size: 58

Data Listing Page 5 Column 2

Heater Elevation: 0

Heat Input Section			
Static Pressure Drop	15.5 - 0.9	15.0 - 0.8	
Correction for Zero (Inches of Freon)	+ .05	+ .05	
Mass Flow Reading	7.1 - 3.8	7.25 - 3.95	
Correction for Zero	- .05	- .05	
Heat Input Section			
Potentiometer Readings			
Bottom to Top (Millivolts)			
1 Iron-Constantan	2.907		
2	2.758		
3	2.7		
4	2.514		
5	2.425		
6	2.271		
7	2.231		
8	2.231		
Potentiometer Readings			
Copper Constantan (Millivolts)			
Heat Input Section Outlet	2.377		
Riser Section Inlet	2.367		
Three Feet Up Riser	2.362		
Heat Input Section Inlet	1.750		
Power			
Upper Heater Volts x amps	210 x 11.4	212.5 x 11.5	215 x 11.65
Lower Heater Volts x amps	70 x 7.85	70 x 7.85	70 x 7.85
Flow Situation		Very near reversal	Reversal

Raw Data Partially Reduced

Date	June 29/72	May 30	May 30	May 31
Heater Length	59 inches	59	59	59
Heater Position	0 inches	2	6	21
Barometric Pressure	756.0 mm @ 76°F	740.1 @ 73	740.1 @ 73	744.4 @ 67
Room Temperature	83.5°F	74.5	75	78.5
Test Section Pressure Drop	14.65 in Freon	14.6	14.9	14.50
Mass Flow Rate	.485 lbm/sec	.467	.467	.453
Inlet Temperature	110.0°F	109.2	109.4	108.8
Outlet Temperature	136.3°F	135.1	134.9	132.8
Total Power at Reversal	3054 watts	3044	2933	2497
Total Power Before Reversal	2943 watts	2923	2879	2447
HI Section Outlet Temperature	1350°F	135.1	134.9	132.8
Riser Section Inlet Temperature	134.6°F	134.8	134.5	132.5
Temperature 3 Feet Up Riser	134.1°F	134.1	133.9	132.1
Temperature In Heat Input Section Bottom to Top				
T1	132.2°F	133.2	131.7	129.8
T2	128.2°F	128.2	129.3	132.2
T3	125.8°F	126.2	127.8	132.7
T4	119.0°F	119.3	121.3	127.0
T5	116.3°F	116.5	118.3	124.3
T6	111.0°F	111.3	112.8	119.0
T7	108.8°F	108.7	108.3	113.5
T8	109.8°F	109.2	109.5	110.7
Page Number	5	5	6	7
Column Number	2	6	3	5

Sample of Final Data.

Heater Length	Position inches	Page	Column	Flow Rate lbm/hr	X %
48"	-1	1	1	1710	6.72
	1	1	2	1692	6.68
	1	1	3	1681	6.85
	3	1	4	1681	6.69
	5	1	5	1681	6.75
	5	1	6	1674	6.55
	7	2	1	1674	6.44
	7	2	2	1674	6.50
	9	2	3	1681	6.48
	9	2	4	1674	6.39
	11	2	6	1638	6.36
	11	2	7	1656	6.36
	13	3	1	1674	6.21
	16	3	2	1656	6.14
	16	3	3	1595	6.30
	21	3	4	1620	5.79
	37	3	5	1595	4.72
				END	MAXIMUM
48"	1	4	1	1440	4.02
	5	4	2	1404	4.02
	9	4	3	1378	3.88
	9	4	4	1404	3.98
	13	4	5	1422	3.98
				END	MINIMUM
59"	-1	5	1	1692	6.84
	1	5	2	1746	6.95
	3	5	4	1681	6.66
	5	5	7	1681	6.76
	5	6	1	1681	6.88
	7	6	2	1692	6.69
	7	6	3	1681	6.82
	7	6	4	1674	6.69

Heater Length	Position inches	Page	Column	Flow Rate lbm/hr	X %
59"	9	6	5	1681	6.70
	9	6	6	1674	6.96
	11	6	7	1674	6.43
	11	7	1	1656	6.59
	13	7	2	1656	6.36
	13	7	3	1674	6.31
	18	7	4	1656	6.21
			END	MAXIMUM	
	1	8	1	1422	3.98
59"	5	8	2	1422	3.93
	9	8	3	1422	3.98
	13	8	4	1422	4.01
			END	MINIMUM	
22"	-2	9	1	1638	5.26
	0	9	2	1530	4.43
	0	9	3	1620	4.94
	2	9	4	1548	4.68
	4	9	5	1595	4.70
	6	9	6	1584	4.69
	6	9	7	1523	4.63
	10	10	1	1548	4.92
	10	10	2	1595	4.90
	12	10	3	1537	4.78
	17	10	4	1523	4.68
	20	10	5	1512	4.26
	25	10	6	1523	4.90
	30	10	7	1512	4.41
	30	11	1	1523	4.59
	40	11	2	1512	4.44
			END	MAXIMUM	
22"	0	12	1	1440	3.82
	10	12	2	1422	4.02
	20	12	3	1440	3.95
	30	12	4	1440	4.01
	30	12	5	1422	3.96
	40	12	6	1422	3.96
			END	MINIMUM	

Heater Length	Position inches	Page	Column	Elev. Rate lbm/hr	X %
36"	1	13	1	1674	5.98
	11	13	2	1656	5.99
	21	13	3	1631	5.72
	37	13	4	1595	5.44
				END	MAXIMUM
36"	1	13	5	1422	3.91
	21	13	6	1386	4.02
	37	13	7	1440	4.09
				END.	MINIMUM
84"	1	14	1	1710	6.87
	5	14	2	1692	6.61
	5	14	3	1656	7.15
	5	14	4	1638	6.91
	5	14	5	1681	7.03
	11	14	6	1674	6.30
	11	14	7	1681	6.53
	21	15	1	1631	6.71
	37	15	2	1595	5.60
				END	MAXIMUM
	1	15	3	1386	3.87
	21	15	4	1386	4.01
	37	15	5	1404	4.05
				END	MINIMUM

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