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AN INVESTIGATION INTO THE LIKELIHOOD BASED PROCEDURES FOR THE CONSTRUCTION OF CONFIDENCE INTERVALS FOR THE COMMON ODDS RATIO IN K 2X2 CONTINGENCY TABLES

BY

SUNDARESWARY THEDCHANAMOORTHY

A Thesis

Submitted to the Faculty of Graduate Studies and Research through the Department of Mathematics and Statistics in Partial Fulfillment of the Requirements for the Degree of Master of Science at the University of Windsor

1994

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Dr. J.M. Morrissey Department of Computer Science

Dedicated to my Family

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ABSTRACT

This study was undertaken to construct confidence intervals of the common odds ratio using several likelihood based procedures. The likelihood based procedures for the construction of confidence intervals of common odds ratio in K 2X2 contingency tables axe derived. Simulations are performed to study the properties of these procedures in terms of the tail and coverage probabilities and average lengths of the confidence intervals and the results are presented. Based on the simulation results obtained in this study, it is concluded that the Baxtlett method (B) is most suitable for constructing confidence interval for the common odds ratio in large sample design.

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CHAPTER 1

INTRODUCTION

The comparison of two proportions in statistics has been actively studied by researchers for many years. One approach used for comparision of two proportions is inference regarding the corresponding odds ratio, a commonly used measure of association. The inference for the odds ratio is widely used in biostatistics, such as case-control and follow-up (restrospective and prospective) studies in cancer epidemiology. In a case-control study, odds ratio is the ratio of odds of disease occurrence among the exposd group and the corresponding odds for the unexposed group. In a follow-up study, odds ratio is the ratio of odds of exposure for the disease group and the corresponding odds for the non-disease group.

The key parameter for the case-control study or for the follow-up study is the odds ratio (ψ) , because it takes the same value whether it is calculated from the exposure or from the disease probabilities. In the above situation, we deal with only $a 2 \times 2$ table. However, nuisance or confounding factors are involved in many studies. Confounding is defined as the distortion of a disease/exposure brought about by the association of other factors with both disease and exposure. For example, age is a confounding factor in the case of alcohol consumption and cancer. One of the most important methods known for a long time used to control the confounding factor, is to divide the sample into series of strata which are internally homogeneous with respect to the confounding factors. In such situations, the summary measure will be the common odds ratio. A full analysis of such series of 2×2 tables would be: (1) to test the homogeneity of the odds ratios in all tables; (**²**) once such a hypothesis is not rejected, to test the common odds ratio $\psi = 1$, that is, to test that there is

no interaction between the exposure and disease and (3) if such a test fails (that is, when $\psi = 1$ is not acceptable) then to obtain the confidence interval for the common odds ratio.

Considerable amount of work has been done in this area. For example, Mantel, Brown and Byar (1977), Tarone (1985) and Paul and Donner (1989,1992) studied procedures for testing homogenity of odds ratio when the number of strata is fixed and sample size in each stratum can take any value up to infinity. Liang and Self (1985) studied procedure for testing homogenity of odds ratios in a large number of tables with sparse data in each table. Procedures for testing $\psi = 1$ were developed by Cochran (1954), Mantel and Haenzel (1959) and Mantel and Fleiss (1980).

Several point estimators for the common odds ratio exist in the literature. Woolf (1955) proposed the emprical logit estimator that behaves well for the large data but not for the sparse data. Gart (1962,1971) developed unconditional and conditional maximum likelihood estmators. Mantel and Haenzel (1954) developed the Mantel-Haenzel (M-H) estimator. Breslow and Liang (1982) recommended a modification of the M-H estimator based on the jacknife principle. A number of simulation studies have been conducted to compare the properties (bias and precision) of various estimators of the common odds ratio (McKinlay, 1975, 1978; Lubin, 1981; Hauck, Andersen and Leahy, 19S2, 1984; Jewell, 1984)

Relatively less attention has been given to confidence interval procedures for the common odds ratio. Gart (1970) gave an exact and an approximate method to construct the confidence interval for the common odds ratio. Brown (1981) studied the validity of three approximate methods developed by Cornfield (1956), Miettinen and Woolf (1955) for constructing confidence interval for the common odds ratio in a single 2×2 table. Hauck and Wallemark (1983) studied seven methods to construct the confidence interval in multiple tables. From the above study, the authors have concluded that the method using M-H estimator with Breslow's variance estimator provides coverage close to nominal. Robins, Brcslow and Grecndland (19S6) have compared six procedures based on various estimators of the variance of the M-H estimator to construct confidence interval for the common odds ratio. Sato (1990) developed a new confidence interval procedure using the M-H estimator and its asymptotic variance.

Several likelihood based procedures for constructing the confidence interval for a parameter in the presence of nuisance parameters are available in the literature (Bartlett, 1953; Levin and Kong, 19S0; Diciccio, 1990; Fraser, 1991). However, these procedures have not been used to construct the confidence interval for the common odds ratio. In this thesis, we apply several likelihood based procedures to construct confidence interval for the common odds ratio. Properties of these confidence intervals, in terms of coverage, are investigated by simulation.

In chapter 2, we review five likelihood based procedures to construct confidence interval for a parameter of interest. In chapter 3, we review maximum likelihood estimation of the common odds ratio. In chapter 4, we derive the likelihood based procedures to construct confidence interval for the common odds ratio. In chapter 5, we conduct a simulation study to investigate the properties of the various interval estimation procedures derived in chapter 4.

CHAPTER 2

A REVIEW OF LIKELIHOOD BASED PROCEDURES FOR THE CONSTRUCTION OF CONFIDENCE INTERVAL

Let $f(X; \gamma, \rho)$ be a density of a random variable X indexed by γ and ρ , where γ is the parameter of interest and $\rho = (\rho_1, \dots, \rho_K)'$ is a vector of K nuisance parameters. Given the sample X_1, \dots, X_n denote the log-likelihood by $l(\gamma, \rho)$. Now, define the likelihood scores $\frac{\partial l}{\partial \gamma}$ and $\frac{\partial l}{\partial \rho}$. Then the maximum likelihood estimates (MLEs) of the parameters γ and $\rho = (\rho_1, \dots, \rho_K)'$ are obtained by solving

$$
\frac{\partial l}{\partial \gamma} = 0
$$

and

$$
\frac{\partial l}{\partial \rho_k} = 0, \qquad \qquad k = 1, \cdots, K
$$

simultaneously.

2.1 Procedure based on the asymptotic properties of MLE

Denote the MLEs of the given parameters γ and $\rho = (\rho_1, \dots, \rho_K)'$ by $\hat{\gamma}$ and $\hat{\rho}$ = ($\hat{\rho}_1, \dots, \hat{\rho}_K$)' respectively. The asymptotic $100(1 - \alpha)\%$ confidence interval for **⁷** is given by

$$
\hat{\gamma} - \zeta \sqrt{var\hat{\gamma}} < \gamma < \hat{\gamma} + \zeta \sqrt{var\hat{\gamma}}
$$

where ζ is an appropriate quantile of a standard normal random variable. The quantity $var(\hat{\gamma})$ is obtained by inverting the Fisher information matrix of $(\hat{\gamma}, \hat{\rho})$. The elements of the Fisher information matrix are the negative of the expected values of the second order mixed partial derivatives of the log-likelihood function with respect to the parameters γ and ρ . Thus, $l(X, \gamma, \rho)$ is the log-likelihood function. Then the asymptotic variance-covariance of $(\hat{\gamma}, \hat{\rho})$ is given by

$$
I^{-1} = \begin{pmatrix} I_{\gamma\gamma} & I_{\gamma\rho} \\ I_{\rho\gamma} & I_{\rho\rho} \end{pmatrix}^{-1}
$$

where

$$
I_{\gamma\gamma} = -E(\frac{\partial^2 l}{\partial \gamma^2}),
$$

$$
I_{\gamma\rho} = -E(\frac{\partial^2 l}{\partial \gamma \partial \rho}),
$$

$$
I_{\rho\gamma} = -E(\frac{\partial^2 l}{\partial \rho \partial \gamma}),
$$

and

$$
I_{\rho\rho}=-E(\frac{\partial^2l}{\partial\rho\partial\rho^{'}}).
$$

The unknown parameters in $var(\hat{\gamma})$ are then replaced by their corresponding maximum likelihood estimators. Note that $I_{\gamma\gamma}$ is a scalar, $I_{\gamma\rho}$ is a $1 \times K$ matrix, $I_{\rho\gamma}$ is a K \times 1 matrix and $I_{\rho\rho}$ is a K \times K matrix.

2.2 Procedure based on Likelihood Ratio

Denote the unconstrained maximum log likelihood by $l(\hat{\gamma}, \hat{\rho})$ and the constrained maximum likelihood by $l(\gamma, \bar{\rho})$, where $\bar{\rho} = (\bar{\rho}_1, \dots, \bar{\rho}_K)'$ which maximize the loglikelihood function $l(\gamma, \rho)$ for given value of γ . Then the likelihood ratio is given by

$$
LR=2(l(\hat{\gamma},\hat{\rho})-l(\gamma,\tilde{\rho}))
$$

has a distribution which is approximately chi-square with one degree of freedom. Thus, the γ values that satisfy

$$
LR=2(l(\hat{\gamma},\hat{\rho})-l(\gamma,\tilde{\rho}))\leq \chi^2_{(1-\alpha)}(1)
$$

are the approximate $100(1 - \alpha)\%$ confidence limits for γ , where $\chi^2_{(1-\alpha)}(1)$ is the $(1 - \alpha)$ th quantile of a chi-squared distribution with one degree of freedom.

2.3 Procedure based on adjusted likelihood ratio

Diciccio (1988) and Diciccio, Fraser and Field (1990) developed a confidence interval procedure for the parameters of a location-scale family of distributions, where the location may be a function of several regression variables X_1, \cdots, X_K . Thus, if $k = 1$ we deal with the confidence interval procedure for the parameters of a two parameter distribution. Let $\rho = (\rho_1, \dots, \rho_K)'$ be the regression parameters and γ be the scalar parameter. In many situations, inference for a scalar parameter in the presence of nuisance parameters requires pivotal quantities. From Diciccio (1988) the pivotal statistics are,

$$
P_k = \frac{\rho_k - \hat{\rho}_k}{\hat{\gamma}}, \qquad k = 1, \cdots, K
$$

and

$$
P_{K+1} = log(\frac{\gamma}{\hat{\gamma}}).
$$

where $\hat{\rho}$ and $\hat{\gamma}$ are the MLE's of $\rho = (\rho_1, \dots, \rho_K)$ ' and γ . Therefore, the loglikelihood $l(\gamma, \rho)$ can be written in terms of a vector of pivotals $P = (P_1, \dots, P_{K+1})'$. We denote this as $l(P)$. It is obvious that the likelihood $l(P)$ attains its maximum value $l(0)$ at $P_k = 0$, $k = 1, \dots, K + 1$. Suppose the kth parameter is of interest, then the associated pivotal is P_k and the corresponding likelihood ratio (LR_k) is

$$
LR_k = 2\left[l(0) - l(\tilde{P}(P_k))\right]
$$

where $l(\tilde{P}(P_k))$ is the maximized log-likelihood function for a given value of P_k . The statistic *LRk* is approximately distributed as chi-square with one degree of freedom. Now define the signed root of the likelihood ratio by

$$
SR_k = -\sqrt{LR_k}, \qquad P_k < 0
$$

and

$$
SR_k = +\sqrt{LR_k}, \qquad P_k > 0.
$$

The distribution of SR_k can be approximated by the standard normal distribution, which has an error of order $n^{-\frac{1}{2}}$. That is

$$
Pr(P_k \leq p_k) = \Phi(SR_k) + 0(n^{\frac{-1}{2}}),
$$

where Φ is the distribution function of a standard normal random variable. Many researchers including Brandorff-Nielsen (19S6), Diciccio (1984,1988), Efron (1985) and McCullagh (19S4; 19S7) studied on further reduction of error and concluded that mean and variance adjustment to the approximate standard normal distribution of the signed root likelihood ratio statistics reduces the error to the order $n^{-\frac{3}{2}}$. Thus,

$$
Pr(P_k \leq p_k) = \Phi(\frac{SR_k - \mu_k}{\sigma_k}) + 0(n^{-\frac{3}{2}})
$$

where μ_k and σ_k^2 are the mean and variance of SR_k , respectively. The above equation can not be used as the exact values of mean and variance are not available. However, in principle, they can be sufficiently well approximated such that the above equation remains valid. Diciccio, Field and Fraser (1990) presented a procedure whereby the mean and variance adjustments in the above equation can be achieved using a simple formula that involves only first and second order partial derivatives.

The general form of the approximation is

$$
Pr(P_k \leq p_k) = \Phi(SR_k) + \phi(SR_k) \left[\frac{1}{SR_k} + \frac{|I|^{\frac{1}{2}}}{l_1(\tilde{P}(P_k)) \times |I^*|^{\frac{1}{2}}} \right] + 0(n^{-\frac{3}{2}})
$$

where I is the observed information matrix of order $(K + 1) \times (K + 1)$ with P_k , $k = 1, ..., K, K+1$ being replaced by zero. I^* is the submatrix of *I* corresponding to $(P_1,\cdots,P_{k-1},P_{k+1},\cdots,P_{K+1})$ with P_j , $j=1,...K,K+1,$ $j\neq k$ being replaced by its maximum likelihood estimate for given value of P_k . $|I|^{1 \over 2}$ and $|I^*|^{1 \over 2}$ are the square roots of the determinants of the matrices I and I^* respectively for $k =$ $1, \cdots, K+1 \text{ and } I_1(P(P_k) = \frac{a_k}{\partial P_k} \Big|_{\infty} \quad , \ P_j = P_j \;, j=1,...K, K+1, j\neq k.$ *Pk—Pk*

When $k = 1$, the above approximation reduces to

$$
Pr(P \leq p) = \Phi(SR) + \phi(SR) \left[\frac{1}{SR} + \frac{(-l_2(0))^{\frac{1}{2}}}{l_1(p)} \right] + 0(n^{\frac{-3}{2}})
$$

where

$$
l_1(x) = \frac{\partial^{(i)}l(x)}{\partial x^i}
$$

and ϕ is the density function of N(0,1). Thus, $100(1-\alpha)\%$ approximate lower and upper confidence limits for the given pivotal (kth) axe obtained by solving

$$
Pr(P_k \leq p_k) = \frac{\alpha}{2}
$$

and

$$
Pr(P_k \leq p_k) = 1 - \frac{\alpha}{2}.
$$

Hence, the confidence limits for the kth parameter of interest can be obtained from the pivoted limits.

2.4 Bartlett's procedure based on the likelihood score

Bartlett (1953) showed that, in the case of "nuisance parameter" there is an alternative to maximum likelihood estimator $\hat{\gamma}$ and is given by

$$
T(\gamma) = \left(\frac{\partial l}{\partial \gamma} - I_{\gamma \rho} I_{\rho \rho}^{-1} \frac{\partial l}{\partial \rho}\right)
$$

with variance

$$
I_{\gamma\gamma,\rho}=I_{\gamma\gamma}-I_{\gamma\rho}.I_{\rho\rho}^{-1}.I_{\rho\gamma}.
$$

Also, he showed that $\frac{T(\gamma)}{\sqrt{I_{\gamma\gamma,\rho}}}$ is a standardized normal variable. That is,

$$
\frac{T(\gamma)}{\sqrt{I_{\gamma\gamma,\rho}}} \sim N(0,1).
$$

An approximate $100(1 - \alpha)$ % confidence interval for γ can then be obtained by solving

8

$$
\frac{T(\gamma)}{\sqrt{I_{\gamma\gamma,\rho}}} = \pm Z_{\frac{\alpha}{2}}
$$

where $Z_{\frac{\alpha}{2}}$ is the appropriate quantile of the standard normal random variate.

2.5 Bartlett's procedure corrected for bias and skewness

When the nuisance parameters ρ in $T(\gamma)$ are replaced by their corresponding maximum likelihod estimates, the statistic $T(\gamma)$ involves a bias of $O(n^{-\frac{1}{2}})$ and is given by

$$
Bias = B(T(\gamma)) = -\frac{1}{2}trace\left(I_{\rho\rho}^{-1}\left(E(\frac{\partial^3 l}{\partial \gamma \partial \rho \partial \rho'}) + 2\frac{\partial I_{\gamma\rho}}{\partial \rho}\right)\right) + \frac{1}{2}trace\left(I_{\rho\rho}^{-1}M\right),
$$

where

$$
M_j = \left(E(\frac{\partial^3 l}{\partial \rho_j \partial \rho \partial \rho'}) + 2 \frac{\partial I_{\rho \rho}}{\partial \rho_j} \right) I_{\rho \rho}^{-1} I_{\rho \gamma}, \qquad j = 1, \cdots, K.
$$

See, Bartlett (1953), Levin and Kong (1990).

Skewness or the third cumulant of $T(\gamma)$ to the order of $n^{-\frac{3}{2}}$ is obtained for $s = t = q = 1, ..., K$, as

$$
K_3(\gamma) = 2E(\frac{\partial^3 l}{\partial \gamma^3}) + 3\frac{\partial I_{\gamma\gamma}}{\partial \gamma}
$$

$$
-3\sum_{s=1}^{K} f_s \left(2E(\frac{\partial^3 l}{\partial \gamma^2 \partial \rho_s}) + 2E(\frac{\partial I_{\gamma \rho_s}}{\partial \gamma}) + \frac{\partial I_{\gamma \gamma}}{\partial \rho_s} \right)
$$

+3
$$
\sum_{s} \sum_{t} f_s f_t \left(2E(\frac{\partial^3 l}{\partial \gamma \partial \rho_s \partial \rho_t}) + \frac{\partial I_{\rho_s \rho_t}}{\partial \gamma} + \frac{\partial I_{\gamma \rho_t}}{\partial \rho_s} + \frac{\partial I_{\gamma \rho_s}}{\partial \rho_t} \right)
$$

$$
\sum_{s} \sum_{t} \sum_{q} f_s f_t f_q \left(2E(\frac{\partial^3 l}{\partial \rho_s \partial \rho_t \partial \rho_q}) + \frac{\partial I_{\rho_s \rho_t}}{\partial \rho_q} + \frac{\partial I_{\rho_q \rho_t}}{\partial \rho_s} + \frac{\partial I_{\rho_q \rho_s}}{\partial \rho_t} \right)
$$

where $f = (f_1, \dots, f_K)' = I_{\gamma \rho} I_{\rho \rho}^{-1}$.

The statistic $T(\gamma)$ corrected for skewness and bias are a better approximation for the normal distribution. Therefore, a more accurate $100(1 - \alpha)$ % confidence interval for γ can be obtained by solving

$$
\frac{T(\gamma)}{\sqrt{I_{\gamma\gamma,\rho}}} - \frac{B(T(\gamma))}{\sqrt{I_{\gamma\gamma,\rho}}} - \frac{K_3(\gamma)(Z_{\frac{\alpha}{2}}^2 - 1)}{6I_{\gamma\gamma,\rho}^{\frac{3}{2}}} = \pm Z_{\frac{\alpha}{2}}.
$$

 $\boldsymbol{\zeta}$

 $\hat{\mathcal{A}}$

CHAPTER 3

NOTATIONS AND ESTIMATIONS OF COMMON ODDS RATIO

3.1 Notations

Consider K pairs of mutually independent binomial variates X_{1k}, X_{2k} with corresponding parameters p_{1k}, p_{2k} and sample sizes N_{1k}, N_{2k} , where $k = 1, \dots, K$.

$$
X_{1k} \sim B(N_{1k}, p_{1k})
$$

and

 $X_{2k} \sim B(N_{2k}, p_{2k}).$

Thus the data for the kth table or for the kth pair or the kth stratum are

group

and the corresponding table of probabilities for the kth stratum are

group

2 *p***_{2k} ?**2*k* **?**2*k*

where $p_{1k} + q_{1k} = 1$ and $p_{2k} + q_{2k} = 1$. Thus, $q_{1k} = 1 - p_{1k}$ and $q_{2k} = 1 - p_{2k}$. The odds ratio for the kth table (stratum) is

$$
\psi_k = \frac{p_{1k}q_{2k}}{p_{2k}q_{1k}}.\tag{3.1}
$$

The alternative name cross product ratio is used for odds ratio as it is equal to the ratio of the products $p_{1k}q_{2k}$ and $p_{2k}q_{1k}$; the probabilities from diagonally opposite cells. The odds ratio can be any nonnegative number. In other words

$$
0<\psi_k<\infty.
$$

The odds ratio does not change values when the orientation of the table is reversed or when the rows become the columns and vice versa. Therefore, it is not necessary to identify the clssification as the response in order to calculate odds ratio. It is sometimes more convenient to use $log(\psi_k)$, the natural logarithm of ψ_k . Because the odds ratio is symmetric about this value, reversal of rows or columns changes only the sign. In this study, we consider only the case where the odds ratio is the same in all strata (tables). That is,

$$
\psi_k = \psi, \qquad 0 < \psi < \infty
$$

for all $k = 1, ..., K$.

3.2 Unconditional maximum likelihood estimator

The distributions of X_{1k} and X_{2k} are binomials with indices N_{1k} and N_{2k} and probabilities p_{1k} and p_{2k} respectively. The likelihood L , dropping the combinatorial terms, is

$$
L \propto \prod_{k=1}^K (p_{1k})^{X_{1k}} (q_{1k})^{N_{1k}-X_{1k}} (p_{2k})^{X_{2k}} (q_{2k})^{N_{2k}-X_{2k}}.
$$

Using equation 3.1 with $\psi_k = \psi$, we have

$$
p_{2k}=\frac{p_{1k}}{\psi q_{1k}+p_{1k}}
$$

and

$$
q_{2k}=1-p_{2k}.
$$

So the likelihood

$$
L \propto \prod_{k=1}^{K} (p_{1k})^{X_{1k}} (q_{1k})^{N_{1k}-X_{1k}} \left(\frac{p_{1k}}{\psi q_{1k}+p_{1k}}\right)^{X_{2k}} \left(\frac{\psi q_{1k}}{\psi q_{1k}+p_{1k}}\right)^{N_{2k}-X_{2k}}
$$

and the log-Hkelihood *1* is

$$
l = C + \sum_{k=1}^{K} \left(X_{1k} log(\frac{p_{1k}}{q_{1k}}) + N_{1k} logq_{1k} + X_{2k} log \frac{p_{1k}}{\psi q_{1k}} + N_{2k} log \frac{\psi q_{1k}}{\psi q_{1k} + p_{1k}} \right),
$$

= $C + \sum_{k=1}^{K} \left((X_{1k} + X_{2k}) log(\frac{p_{1k}}{q_{1k}}) + N_{1k} logq_{1k} + N_{2k} log \frac{\psi}{\psi + \frac{p_{1k}}{q_{1k}}} - X_{2k} log \psi \right),$
where, C is a constant independent of the parameters ψ , p_{1k} , q_{1k} , Now, $T_k =$

where, C $X_{1k} + X_{2k}$. Define $\rho_k = log_{q_{1k}}^{\frac{p_{1k}}{q_{1k}}}, \gamma = log\psi$. Then $\frac{p_{1k}}{q_{1k}} = e^{\rho_k}, p_{1k} = \frac{e^{\rho_k}}{1 + e^{\rho_k}} \Rightarrow$ $q_{1k} = \frac{1}{1 + e^{\rho_k}}$. The log-likelihood *l* can be written as

$$
l = C + \sum_{k=1}^{K} (T_k \rho_k + (N_{2k} - X_{2k})\gamma - N_{1k} log(1 + e^{\rho_k}) - N_{2k} log(e^{\gamma} + e^{\rho_k})).
$$
\n(3.2)

The log-likelihood involves the $K + 1$ parameters γ and ρ_k , $k = 1, \dots, K$. The maximum log-likelihood estimators of γ and ρ_k ($k = 1, ..., K$) are obtained by maximizing the log-likelihood (3.2) directly by using IMSL subroutine DUMINF (IMSL.LIB 1989). Denote the MLEs of ρ_k and γ be $\hat{\rho}_k$ and $\hat{\gamma}_u$. These are the unconditional maximum likelihood estimators.

3.3 Conditional maximum likelihood

When working with the increasing strata case, the principal distribution of interest will be that of X_{1k} , given T_k , N_{1k} and N_{2k} . As originally noted by Fisher (1935), this distribution is the extended (or noncentral) hypergeometric distribution (Harkness, 1965) which is given by

$$
f(X_{1k}|T_k, N_{1k}, N_{2k}) = \frac{\binom{N_{1k}}{X_{1k}}\binom{N_{2k}}{T_k - X_{1k}}\psi^{X_{1k}}}{\sum_{u=a_k}^{b_k} \binom{N_{1k}}{u}\binom{N_{2k}}{T_k - u}\psi^u}
$$

where $a_k = \max (0, T_k - N_{2k}), b_k = \min (T_k, N_{1k}).$

Then the joint likelihood is

$$
L = \prod_{k=1}^K \frac{\binom{N_{1k}}{X_{1k}} \binom{N_{2k}}{T_k - X_{1k}} \psi^{X_{1k}}}{\sum_{u=a_k}^{b_k} \binom{N_{1k}}{u} \binom{N_{2k}}{T_k - u} \psi^u}.
$$

By reparametrization of $\psi = e^{\gamma}$, we have

$$
L = \prod_{k=1}^{K} \frac{\binom{N_{1k}}{X_{1k}} \binom{N_{2k}}{T_k - X_{1k}} e^{\gamma X_{1k}}}{\sum_{u=a_k}^{b_k} \binom{N_{1k}}{u} \binom{N_{2k}}{T_k - u} e^{\gamma u}}
$$

Prom this, the log-likelihood can be written as

$$
l=\sum_{k=1}^K (X_{1k}\gamma+C_k-log f_k(\gamma))
$$

where

$$
f_k(\gamma) = \sum_{X_{1k} = a_k}^{b_k} {N_{1k} \choose X_{1k}} {N_{2k} \choose T_k - X_{1k}} e^{\gamma X_{1k}}
$$

and C_k is a constant independent of the parameter γ .

The partial derivative of *I* with respect to the parameter γ is

 $\ddot{}$

$$
\frac{\partial l}{\partial \gamma} = \sum_{k=1}^K \left(X_{1k} - \frac{1}{f_k(\gamma)} \frac{\partial f_k(\gamma)}{\partial \gamma} \right).
$$

Now,

$$
E(X_{1k};\gamma)=\sum_{X_{1k}=b_{1k}}^{b_k}X_{1k}\frac{\binom{N_{1k}}{X_{1k}}\binom{N_{2k}}{T_k-X_{1k}}e^{\gamma X_{1k}}}{f_k(\gamma)}.
$$

Further,

$$
\frac{\partial f_k(\gamma)}{\partial \gamma} = \sum_{X_{1k}=a_k}^{b_k} X_{1k} \binom{N_{1k}}{X_{1k}} \binom{N_{2k}}{T_k-X_{1k}} e^{\gamma X_{1k}}.
$$

Thus,

$$
E(X_{1k};\gamma) = \frac{1}{f_k(\gamma)} \frac{\partial f_k(\gamma)}{\partial \gamma}
$$

and

$$
\frac{\partial l}{\partial \gamma} = \sum_{k=1}^K X_{1k} - \sum_{k=1}^K E(X_{1k}; \gamma).
$$

But, for the maximum likelihood estimator of $\gamma,$

$$
\frac{\partial l}{\partial \gamma}=0.
$$

Hence, the maximum likelihood estimator of γ is obtained by solving the equation

$$
\sum_{k=1}^{K} X_{1k} = \sum_{k=1}^{K} E(X_{1k}; \gamma).
$$

This equation can be solved by IMSL subroutine ZBREN. Denote the maximum likelihood estimator of γ by $\hat{\gamma}_c$. This is a conditional maximum likelihood estimator.

CHAPTER 4

LIKELIHOOD BASED CONFIDENCE INTERVAL PROCEDURE FOR THE COMMON ODDS RATIO

4.1 Confidence interval estimation based on the conditional maximum likelihood estimator of the common odds ratio.

4.1.1 Procedure based on the asymptotic properties of MLE From the definition of variance,

$$
Var(X_{1k};\gamma) = E(X_{1k}^2;\gamma) - (E(X_{1k};\gamma))^2,
$$

where

$$
E(X_{1k};\gamma) = \sum_{X_{1k}=a_k}^{b_k} X_{1k} \frac{\binom{N_{1k}}{X_{1k}} \binom{N_{2k}}{T_K - X_{1k}} e^{\gamma X_{1k}}}{f_k(\gamma)}
$$

and

$$
E(X_{1k}^2; \gamma) = \sum_{X_{1k}=a_k}^{b_k} X_{1k}^2 \frac{\binom{N_{1k}}{X_{1k}} \binom{N_{2k}}{T_K - X_{1k}} e^{\gamma X_{1k}}}{f_k(\gamma)}.
$$

From chapter 3 we have

$$
\frac{\partial l}{\partial \gamma} = \sum_{k=1}^{K} X_{1k} - \sum_{k=1}^{K} \frac{1}{f_k(\gamma)} \frac{\partial f_k(\gamma)}{\partial \gamma}
$$
(4.1)

so the second derivative with respect to γ is

$$
\frac{\partial^2 l}{\partial \gamma^2} = -\left(\sum_{k=1}^K \frac{1}{f_k(\gamma)} \frac{\partial^2 f_k(\gamma)}{\partial \gamma^2} - \sum_{k=1}^K \frac{1}{f_k^2(\gamma)} (\frac{\partial f_k(\gamma)}{\partial \gamma})^2\right).
$$

From $f_k(\gamma)$, we have

$$
\frac{\partial f_k(\gamma)}{\partial \gamma} = \sum_{X_{1k}=a_k}^{b_k} X_{1k} \binom{N_{1k}}{X_{1k}} \binom{N_{2k}}{T_k - X_{1k}} e^{\gamma X_{1k}}
$$

and

$$
\frac{\partial^2 f_k(\gamma)}{\partial \gamma^2} = \sum_{X_{1k}=a_k}^{b_k} X_{1k}^2 {N_{1k} \choose X_{1k}} {N_{2k} \choose T_k - X_{1k}} e^{\gamma X_{1k}}.
$$

So

$$
E(X_{1k};\gamma) = \frac{1}{f_k(\gamma)} \frac{\partial f_k(\gamma)}{\partial \gamma}
$$

and

$$
E(X_{1k}^2;\gamma)=\frac{1}{f_k(\gamma)}\frac{\partial^2 f_k(\gamma)}{\partial \gamma^2}.
$$

Thus,

$$
\frac{\partial^2 l}{\partial \gamma^2} = -\left(\sum_{k=1}^K E(X_{1k}^2; \gamma) - \sum_{k=1}^K (E(X_{1k}; \gamma))^2\right)
$$

$$
= -\sum_{k=1}^K Var(X_{1k}; \gamma).
$$

Now, the asymptotic variance of the conditional maximum likelihood estimator $\hat{\gamma}_c$ is

$$
Var(\hat{\gamma}_c)=-\frac{1}{E(\frac{\partial^2 l}{\partial \gamma^2})}.
$$

Therefore,

$$
Var(\hat{\gamma}_c) = \frac{1}{\sum_{k=1}^K Var(X_{1k}; \gamma)}.
$$

Thus, an approximate confidence interval estimation for $\hat{\gamma}_c$ is obtained as

$$
\hat{\gamma}_c \pm Z_{\frac{\alpha}{2}} \sqrt{Var\hat{\gamma}_c}
$$

which can be written as

$$
\hat{\gamma}_{\rm c} \pm Z_{\frac{\rm c}{2}} \sqrt{\frac{1}{\sum_{k=1}^{k} var(X_{1k}; \gamma)}}
$$
(4.2)

Denote the estimates of the lower and upper limits of the confidence interval for γ obtained from (4.2) by $\hat{\gamma}_{McL}$ and $\hat{\gamma}_{McU}$. Then an approximate confidence interval for ψ , by using the conditional maximum likelihood estimator of γ , is

$$
e^{\hat{\gamma}_{M\epsilon L}}
$$

and

 $e^{\gamma_{McU}}$.

Denote these by $\hat{\psi}_{McL}$ and $\hat{\psi}_{McU}$.

4.1.2 Procedure based on likelihood ratio

From chapter 3, the conditional log-likeihood is

$$
l(\gamma) = \sum_{k=1}^{K} (X_{1k}\gamma + C_k - log f_k(\gamma))
$$

and the maximized log-likelihood, using the maximum likelihood estimator $\hat{\gamma}_c$ is

$$
l(\hat{\gamma}_c) = \sum_{k=1}^K (X_{1k}\hat{\gamma}_c + C_k - log f_k(\hat{\gamma}_c)).
$$

Thus,

$$
LR = 2\left[l(\hat{\gamma}_c) - l(\gamma)\right]
$$

$$
= 2\sum_{k=1}^{K} X_{1k}(\hat{\gamma}_c - \gamma) + \log \frac{f_k(\gamma)}{f_k(\hat{\gamma}_c)}
$$

The confidence limit for γ using the likelihood ratio procedure is obtained by solving

$$
2\sum_{k=1}^{K}\left[X_{1k}(\hat{\gamma}_c-\gamma)+\log\frac{f_k(\gamma)}{f_k(\hat{\gamma}_c)}\right]=\chi^2_{1-\alpha}(1) \tag{4.3}
$$

This equation can be solved by using IMSL subroutine ZREAL. Denote the lower and upper limits of the confidence interval for γ , obtained from (4.3) by $\hat{\gamma}_{LcL}$ and $\hat{\gamma}_{LeU}$. Then the estimators for the lower and the upper limit of the confidence interval for ψ , using the likelihood ratio procedure, are

$$
\hat{\psi}_{LcL}=e^{\hat{\gamma}_{LcL}}
$$

and

$$
\hat{\psi}_{LcU}=e^{\hat{\gamma}_{LcU}}.
$$

4.1.3 Procedure based on adjusted likelihood ratio

According to the procedure developed by Diciccio, Field and Fraser (1990), as discussed in chapter **²** , odds ratio is the only parameter of interest in the conditional approach. Therefore, the pivotal statistic is

$$
P = log \frac{\psi}{\hat{\psi}}.
$$

By reparametrization of $log \psi = \gamma$, we have

$$
P=\gamma-\hat{\gamma}.
$$

Therefore,

 \mathbf{r}_{m} .

$$
\gamma=P+\hat{\gamma},
$$

where $\hat{\gamma} = \hat{\gamma}_c$ =conditional maximum likelihood estimator of γ . From chapter 3, the conditional log-likelihood is

$$
l(\gamma)=\sum_{k=1}^K\left(X_{1k}\gamma+C_k-log f_k(\gamma)\right).
$$

Then, the corresponding log-likelihood,using the pivotal P, is

$$
l(P) = \sum_{k=1}^K (X_{1k}(P+\hat{\gamma}) + C_k - log f_k(P+\hat{\gamma})).
$$

When $P = 0$, the corresponding log-likelihood is

$$
l(0)=\sum_{k=1}^K (X_{1k}\hat{\gamma}+C_k-logf_k(\hat{\gamma}))\,.
$$

Hence, the likelihood ratio statistic is

$$
LR = 2 [l(0) - l(P)]
$$

$$
= 2 \sum_{k=1}^{K} \left(X_{1k}(-P) + \log \frac{f_k(\hat{\gamma} + P)}{f_k(\hat{\gamma})} \right)
$$

From chapter 2, the signed root likelihood ratio is

$$
SR = -\sqrt{LR}, \qquad if \quad P < 0
$$

and

$$
SR = \sqrt{LR}, \quad if \quad P > 0.
$$

Now, from the log-likelihood, involving the pivotal, we have

$$
l_1(P) = \frac{\partial l(P)}{\partial P}
$$

$$
= \sum_{k=1}^K X_{1k} - \sum_{k=1}^K E(X_{1k}; \hat{\gamma} + P)
$$

and

$$
l_2(0)=-\sum_{k=1}^K Var(X_{1k};\hat{\gamma}).
$$

Follwing the procedure in section 2.3, the marginal tail probability for the pivotal P can be given as

$$
Pr(P \leq p) = \Phi(SR) + \phi(SR) \left(\frac{1}{SR} + \frac{\sqrt{-l_2(0)}}{l_1(p)} \right) + O(n^{\frac{-3}{2}}).
$$

Hence, the $100(1-\alpha)$ % approximate lower and upper confidence limits are obtained by solving

$$
Pr(P \le p) = \Phi(SR) + \phi(SR) \left(\frac{1}{SR} + \frac{\sqrt{-l_2(0)}}{l_1(p)} \right) = \frac{\alpha}{2}
$$

and

$$
Pr(P \le p) = \Phi(SR) + \phi(SR) \left(\frac{1}{SR} + \frac{\sqrt{-l_2(0)}}{l_1(p)} \right) = 1 - \frac{\alpha}{2}
$$

respectively. Denote these as P_L and P_U . Therefore, the corresponding lower and upper limits of γ using Diciccio's procedure are $\hat{\gamma} + P_L$ and $\hat{\gamma} + P_U$ respectively. Then the lower and the upper limits of the confidence interval for ψ are

$$
\hat{\psi}_{DcL}=e^{\hat{\gamma}+P_L}
$$

and

$$
\hat{\psi}_{DcU}=e^{\hat{\gamma}+P_U}.
$$

4.1.4 Bartlett's procedure based on likelihood score

In this approach (conditional), we have determined the likelihood, using only the parameter of interest γ (or ψ). From chapter 2, the alternative to the maximum likelihood estimate $\hat{\gamma}_c$, is

$$
T(\gamma)=\frac{\partial l}{\partial \gamma}
$$

with variance $I_{\gamma\gamma}$. Thus, an approximate confidence interval for γ can be obtained by solving

$$
\frac{T(\gamma)}{\sqrt{I_{\gamma\gamma}}}=\pm Z_{\frac{\alpha}{2}}
$$

where $Z_{\frac{\alpha}{2}}$ is the appropriate quantile of the standard normal distribution. From Fisher information matrix

$$
I_{\gamma\gamma} = -E(\frac{\partial^2 l}{\partial \gamma^2})
$$

and also from section 4.1.1 we have

$$
\frac{\partial l}{\partial \gamma} = \sum_{k=1}^K (X_{1k} - E(X_{1k}; \gamma))
$$

and

$$
\frac{\partial^2 l}{\partial \gamma^2} = -\sum_{k=1}^K Var(X_{1k}; \gamma).
$$

Therefore, an approximate confidence interval for γ can be obtained by solving

$$
\frac{\sum_{k=1}^K (X_{1k} - E(X_{1k}; \gamma))}{\sqrt{\sum_{k=1}^K Var(X_{1k}; \gamma)}} = \pm Z_{\frac{\alpha}{2}}.
$$

This equation can be solved by using IMSL subroutine ZBREN. Denote the lower limit and the upper limit of γ obtained by Bartlett's procedure by $\hat{\gamma}_{BcL}$ and $\hat{\gamma}_{BcU}$. Then the corresponding lower and upper limits for the confidence interval of the odds ratio ψ are

$$
\hat{\psi}_{BcL}=e^{\hat{\gamma}_{BcL}}
$$

and

$$
\hat{\psi}_{BcU}=e^{\hat{\gamma}_{BcU}}.
$$

4.1.5 Bartlett's procedure corrected for bias and skewness

Since the conditional likelihood involves only one parameter γ , from chapter 2,

$$
B(T(\gamma))=0.
$$

The third cumulant for the alternative to the maximum lkelihood estimate for a single parameter $\hat{\gamma}_c$, is

$$
K_3(T(\gamma))=2E(\frac{\partial^3 l}{\partial \gamma^3})+3\frac{\partial I_{\gamma\gamma}}{\partial \gamma}.
$$

Therefore, the $100(1 - \alpha)$ % approximate confidence interval for γ is obtained by solving

$$
T(\gamma)-\frac{K_3(\gamma)(Z_{\frac{\alpha}{2}}^2-1)}{6I_{\gamma\gamma}^{\frac{3}{2}}}=\pm Z_{\frac{\alpha}{2}}.
$$

Applying

$$
I_{\gamma\gamma}=-E(\frac{\partial^2l}{\partial\gamma^2}),
$$

the partial derivative of $I_{\gamma\gamma}$ with respect to γ is

$$
\frac{\partial I_{\gamma\gamma}}{\partial\gamma}=-E(\frac{\partial^2l}{\partial\gamma^2}\frac{\partial l}{\partial\gamma})-E(\frac{\partial^3l}{\partial\gamma^3}).
$$

From section 4.1.1

$$
\frac{\partial^2 l}{\partial \gamma^2} = -\sum_{k=1}^K Var(X_{1k}; \gamma).
$$

Therefore,

$$
-E\left(\frac{\partial^2 l}{\partial \gamma^2} \frac{\partial l}{\partial \gamma}\right) = \left(\sum_{k=1}^K Var(X_{1k}; \gamma)\right) E\left(\frac{\partial l}{\partial \gamma}\right).
$$

But under regularity conditions

$$
E(\frac{\partial l}{\partial \gamma})=0.
$$

Therefore,

$$
-E\left(\frac{\partial^2 l}{\partial \gamma^2}\frac{\partial l}{\partial \gamma}\right)=0.
$$

Thus,

$$
\frac{\partial I_{\gamma\gamma}}{\partial\gamma}=-E(\frac{\partial^3l}{\partial\gamma^3}).
$$

and

$$
K_3(T(\gamma))=-E(\frac{\partial^3 l}{\partial \gamma^3}).
$$

But from section 4.1.1

$$
\frac{\partial^2 l}{\partial \gamma^2} = -\left(\sum_{k=1}^K \frac{1}{f_k(\gamma)} \frac{\partial^2 f_k(\gamma)}{\partial \gamma^2} - \sum_{k=1}^K \frac{1}{f_k^2(\gamma)} \left(\frac{\partial f_k(\gamma)}{\partial \gamma}\right)^2\right).
$$
(4.4)

Hence, the third derivatives of f_k (γ) with respect to γ is

$$
\frac{\partial^3 l}{\partial \gamma^3} = \sum_{k=1}^K \left[\left(\frac{1}{f_k^2(\gamma)} (\frac{\partial f_k(\gamma)}{\partial \gamma}) (\frac{\partial^2 f_k(\gamma)}{\partial \gamma^2}) - \left(\frac{2}{f_k^3(\gamma)} (\frac{\partial f_k(\gamma)}{\partial \gamma}) (\frac{\partial f_k(\gamma)}{\partial \gamma})^2 \right) \right] - \sum_{k=1}^K \left[\left(\frac{1}{f_k(\gamma)} (\frac{\partial^3 f_k(\gamma)}{\partial \gamma^3}) \right) - \left((2) \frac{1}{f_k(\gamma)^2} (\frac{\partial f_k(\gamma)}{\partial \gamma}) (\frac{\partial^2 f_k(\gamma)}{\partial \gamma^2}) \right) \right].
$$

But from section 4.1.1, we have

$$
E(X_{1k};\gamma)=\frac{1}{f_k(\gamma)}\frac{\partial f_k(\gamma)}{\partial \gamma}
$$

and

$$
E(X_{1k}^2;\gamma)=\frac{1}{f_k(\gamma)}\frac{\partial^2 f_k(\gamma)}{\partial \gamma^2}.
$$

Furthermore,

$$
E(X_{1k}^3;\gamma)=\frac{1}{f_k(\gamma)}\frac{\partial^3 f_k(\gamma)}{\partial \gamma^3}.
$$

Hence,

$$
\frac{\partial^3 l}{\partial \gamma^3} = \sum_{k=1}^K 3E(X_{1k}; \gamma)E(X_{1k}^2; \gamma) - \sum_{k=1}^K 2\left(E(X_{1k}; \gamma)\right)^3 - \sum_{k=1}^K E(X_{1k}^3; \gamma)
$$

and

$$
E(\frac{\partial^3 l}{\partial \gamma^3}) = \sum_{k=1}^K 3E(X_{1k}; \gamma)E(X_{1k}^2; \gamma) - \sum_{k=1}^K 2(E(X_{1k}; \gamma))^3 - \sum_{k=1}^K E(X_{1k}^3; \gamma).
$$

Therefore, the third cumulant of $T(\gamma)$ is

$$
K_3(T(\gamma)) = -\sum_{k=1}^K 3E(X_{1k}, \gamma)E(X_{1k}^2, \gamma) + \sum_{k=1}^K 2(E(X_{1k}, \gamma))^3 + \sum_{k=1}^K E(X_{1k}^3, \gamma)
$$
\n(4.5)

By using the the values for $T(\gamma)$ and $I_{\gamma\gamma}$ and $K_3(T(\gamma))$ from equations (4.1), (4.4) and (4.5) the confidence interval for γ is obtained as

$$
T(\gamma)-\frac{K_3(T(\gamma))}{6I_{\gamma\gamma}^{\frac{3}{2}}} (Z_{\frac{\alpha}{2}}^2-1)=\pm Z_{\frac{\alpha}{2}}.
$$

Thus, the lower confidence limit for γ is obtained by solving

$$
T(\gamma) - \frac{K_3(T(\gamma))}{6I_{\gamma\gamma}^{\frac{3}{2}}} (Z_{\frac{\alpha}{2}}^2 - 1) = +Z_{\frac{\alpha}{2}}
$$

and the upper confidence limit is obtained by solving

$$
T(\gamma)-\frac{K_3(T(\gamma))}{6I_{\gamma\gamma}^\frac{3}{2}}(Z_{\frac{\alpha}{2}}^2-1)=-Z_{\frac{\alpha}{2}}.
$$

These equations can be solved by using IMSL subroutine ZBREN. Denote the lower limit and upper limit of γ obtained by Bartlett's corrected procedure by $\hat{\gamma}_{BCcL}$ and $\hat{\gamma}_{BCcU}$. The corresponding lower limit and upper limit of the odds ratio are

$$
\hat{\psi}_{BCcL}=e^{\hat{\gamma}_{BCcL}}
$$

and

$$
\hat{\psi}_{BCcU}=e^{\hat{\gamma}_{BCcU}}.
$$

4.2 Confidence interval estimation based on the unconditional maximum likelihood estimator of common odds ratio.

4.2.1 Procedure based on the asymptotic properties of MLE

Gart(1962) showed that the asymptotic variance of the unconditional estimator $\hat{\psi}_u$ is

$$
Var(\hat{\psi}_u) = \frac{\hat{\psi}^2}{V},
$$

Where

$$
V = \sum_{k=1}^K \hat{V}_k
$$

and

$$
(\hat{V}_k)^{-1} = (N_{1k}\hat{p}_{1k}\hat{q}_{1k})^{-1} + (N_{2k}\hat{p}_{2k}\hat{q}_{2k})^{-1}.
$$

Also, from section 3.1,

$$
p_{1k} = \frac{e^{\rho_k}}{1 + e^{\rho_k}}, \qquad q_{1k} = \frac{1}{1 + e^{\rho_k}}
$$

and

$$
p_{2k}=\frac{e^{\rho_k}}{e^{\gamma}+e^{\rho_k}},\qquad q_{2k}=\frac{e^{\gamma}}{e^{\gamma}+e^{\rho_k}}.
$$

Therefore,

$$
(\hat{V}_k)^{-1} = \frac{N_{1k}(e^{\hat{\gamma}} + e^{\hat{\rho}_k})^2 + N_{2k}e^{\hat{\gamma}}(1 + e^{\hat{\rho}_k})^2}{N_{1k}N_{2k}\hat{\gamma}e^{\hat{\rho}_k}}.
$$

An approximate $100(1-\alpha)$ % confidence interval using the unconditional maximum likelihood estimator of the common odds ratio is given by

$$
\hat{\psi}_u \pm Z_{\frac{\alpha}{2}} \sqrt{\frac{\hat{\psi}^2}{\hat{V}}}.
$$

Denote the lower limit and the upper limit of the unconditional odds ratio using asymptotic property of the mle by $\hat{\psi}_{M u L}$ and $\hat{\psi}_{M u U}$.
4.2.2 Procedure based on likelihood ratio

Let $\hat{p} = (\hat{p}_{11},...,\hat{p}_{1K})'$ and $\hat{\psi}$ be the maximum likelihood estimator of $p =$ $(p_{11},...,p_{1K})'$ and ψ respectively and the corresponding maximized log-likelihood be $l(\hat{\psi}, \hat{p})$. Further, for a given ψ , let $\tilde{p} = (\tilde{p}_{11}, ..., \tilde{p}_{1K})'$ be the maximum likelihood estimator of $p = (p_{11}, \dots, p_{1K})'$ and the corresponding log-likelihood by $l(\psi, \tilde{p})$. Then following the procedure discussed in chapter **²** , the confidence interval using the likelihood procedure is obtained by solving

$$
2\left[l(\hat{\psi},\hat{p})-l(\psi,\tilde{p})\right] \leq \chi^2_{(1-\alpha)}(1).
$$

From chapter 3, the maximized log-likelihood $l(\hat{\psi}, \hat{p})$, using the parametrization of γ and ρ_k is

$$
l = C + \sum_{k=1}^{K} (T_k \hat{\rho}_k + (N_{2k} - X_{2k})\hat{\gamma} - N_{1k} log(1 + e^{\hat{\rho}_k}) - N_{2k} log(e^{\hat{\gamma}} + e^{\hat{\rho}_k}))
$$

We still need to find $l(\psi, \tilde{p})$. Again from section 3.2, we have

$$
l(\psi,p) = C + \sum_{k=1}^K \left(X_{1k} log(\frac{p_{1k}}{q_{1k}}) + N_{1k} logq_{1k} + X_{2k} log \frac{p_{1k}}{\psi q_{1k}} + N_{2k} log \frac{\psi q_{1k}}{\psi q_{1k} + p_{1k}} \right).
$$

For a given ψ , the maximum likelihood estimator for p_{1k} , $k = 1, \dots, K$ is obtained by solving $\frac{\partial l}{\partial p_{1k}} = 0$. Now, the partial derivative of *l* with respect to p_{1k} is

$$
\frac{\partial l}{\partial p_{1k}} = \frac{X_{1k}}{p_{1k}} - \frac{(N_{1k} - X_{1k})}{q_{1k}} + \frac{X_{2k}}{p_{1k}} - \frac{(N_{2k} - X_{2k})}{q_{1k}} - \frac{(N_{2k})(1 - \psi)}{\psi q_{1k} + p_{1k}}
$$

$$
= \frac{X_{1k} + X_{2k}}{p_{1k}} - \frac{(N_{1k} + N_{2k} - X_{1k} - X_{2k})}{q_{1k}} - \frac{N_{2k}(1 - \psi)}{\psi q_{1k} + p_{1k}} = 0.
$$

From this and using the reparametrization of $\rho_k = log(\frac{p_{1k}}{1-p_{1k}})$ and $\gamma = log\psi$ we obtain

$$
T_k\frac{(1+e^{\rho_k})}{e^{\rho_k}}-\frac{(N_k-T_k)(1+e^{\rho_k})}{1}-\frac{N_{2k}(1+e^{\rho_k})(1-e^{\gamma})}{e^{\gamma}+e^{\rho_k}}=0,
$$

which can be written as

$$
A_k X_k^2 + B_k X_k + C_k = 0
$$

where

$$
B_k = -T_k(1 + e^{\gamma}) + N_{1k}e^{\gamma} + N_{2k},
$$

$$
A_k = (N_k - T_k),
$$

$$
C_k = -T_k e^{\gamma}
$$

and

$$
X_k=e^{\rho_k}.
$$

Now, $p_{1k}\epsilon(0,1)$, $\rho_k\epsilon(-\infty,\infty)$ and $e^{\rho_k}\epsilon(0,\infty)$. The solution of the quadratic equation is

$$
X_k = \frac{-B_k \pm \sqrt{B_k^2 - 4A_kC_k}}{2A_k}.
$$

We have to show that, it has two real roots and only one root is admissible. That is, only one solution is in the range $(0, \infty)$. Now $A_k = N_k - T_k$ is positive, $-C_k = T_k e^{\gamma}$ is positive therefore, $-A_K C_k$ is positive.

$$
-A_kC_k > 0 \Rightarrow B_k^2 - 4A_kC_k > 0. \tag{4.6}
$$

Therefore, the quadratic equation has two real roots. Now,

$$
-4A_kC_k > 0 \Rightarrow B_k^2 - 4A_kC_k > B_k^2,
$$

$$
\sqrt{B_k^2 - 4A_kC_k} > B_k.
$$
 (4.7)

From this it is clear that $-B_k + \sqrt{B_k^2 - 4A_KC_k} > 0$ and $-B_k - \sqrt{B_k^2 - 4A_kC_k}$ < 0. Therefore, we have only one admissible solution. Using this, the maximum likelihood estimate of e^{p_k} for a given e^{γ} is

$$
e^{\tilde{\rho}_k} = \frac{-B_k + \sqrt{B_k^2 - 4A_k C_k}}{2A_k} \tag{4.8}
$$

Putting this in $l(\gamma, \rho)$ we obtain

$$
l(\gamma,\tilde{\rho})=C+\sum_{k=1}^K \left(T_k\tilde{\rho}_k+(N_{2k}-X_{2k})\gamma-N_{1k}log(1+e^{\tilde{\rho}_k})-N_{2k}log(e^{\gamma}+e^{\tilde{\rho}_k})\right).
$$

From section 2.2, an approximate $100(1-\alpha)\%$ confidence interval for γ is obtained by solving

$$
LR = 2(l(\hat{\gamma}, \hat{\rho}) - l(\gamma, \tilde{\rho})) \leq \chi^2_{1-\alpha}(1)
$$

The above equation can be solved by using IMSL subroutine ZREAL. Denote the lower limit and upper limit of γ obtained by the likelihood procedure by $\hat{\gamma}_{LuL}$ and $\hat{\gamma}_{LuU}$. The corresponding lower limit and upper limit of the odds ratio are

$$
\hat{\psi}_{LuL} = e^{\hat{\gamma}_{LuL}}
$$

and

$$
\psi_{LuU}=e^{\hat{\gamma}_{LuU}}.
$$

4.2.3 Procedure based on adjusted likelihood ratio

In this approach (unconditional), γ is a scalar parameter and $\rho = (\rho_1, \dots, \rho_K)'$ is the vector of nuisance parameters. As discussed in chapter 2, according to the procedure developed by Diciccio, Field and Fraser (1990), the pivotal statistics are

$$
P_k = \frac{(\rho_k - \hat{\rho}_k)}{\hat{\psi}}, \qquad k = 1, \cdots, K
$$

and

$$
P_{K+1} = \log \frac{\psi}{\hat{\psi}}.
$$

Thus,

$$
\rho_k = \hat{\rho}_k + P_k \hat{\psi}
$$

and

$$
\gamma = \tilde{\gamma} + P_{K+1}.
$$

From chapter 3, the log-likelihood can be written as

$$
l = C + \sum_{k=1}^{K} (T_k \rho_k + (N_{2k} - X_{2k})\gamma - N_{1k} log(1 + e^{\rho_k}) - N_{2k} log(e^{\gamma} + e^{\rho_k})).
$$

Therefore, in terms of the pivotals, the log-likelihood is

$$
l(P) = C + \sum_{k=1}^{K} \left(T_k(\hat{\rho}_k + P_k \hat{\psi}) + (N_{2k} - X_{2k})(\hat{\gamma} + P_{K+1}) \right) -
$$

$$
\sum_{k=1}^{K} \left(N_{1k} log(1 + e^{\hat{\rho}_k + P_k \hat{\psi}}) + N_{2k} log(e^{\hat{\gamma} + P_{K+1}} + e^{\hat{\rho}_k + P_k \hat{\psi}}) \right)
$$
(4.9)

Hence,

$$
l(0) = C + \sum_{k=1}^K (T_k \hat{\rho}_k + (N_{2k} - X_{2k})\hat{\gamma} - N_{1k} log(1 + e^{\hat{\rho}_k}) - N_{2k} log(e^{\hat{\gamma}} + e^{\hat{\rho}_k})) .
$$

Now, we need to find $l(\tilde{P}(P_{K+1}))$. From equation (4.9) we obtain

$$
\frac{\partial l}{\partial P_k} = T_k \hat{\psi} - \frac{N_{1k} e^{\hat{\rho}_k + P_k \psi} (\hat{\psi})}{(1 + e^{\hat{\rho}_k + P_k \hat{\psi}})} - \frac{N_{2k} e^{\hat{\rho}_k + P_k \psi} (\hat{\psi})}{e^{\hat{\gamma} + P_{K+1}} + e^{\hat{\rho}_k + P_k \hat{\psi}}} = 0
$$

$$
\Rightarrow T_k - \frac{N_{1k} e^{\hat{\rho}_k + P_k \hat{\psi}}}{(1 + e^{\hat{\rho}_k + P_k \hat{\psi}})} - \frac{N_{2k} e^{\hat{\rho}_k + P_k \hat{\psi}}}{e^{\hat{\gamma} + P_{K+1}} + e^{\hat{\rho}_k + P_k \hat{\psi}}} = 0
$$

$$
\Rightarrow T_k (1 + e^{\hat{\rho}_k + P_k \hat{\psi}}) (e^{\hat{\gamma} + P_{K+1}} + e^{\hat{\rho}_k + P_k \hat{\psi}}) - N_{1k} e^{\hat{\rho}_k + P_k \hat{\psi}} (e^{\hat{\gamma} + P_{K+1}} + e^{\hat{\rho}_k + P_k \hat{\psi}})
$$

$$
- N_{2k} e^{\hat{\rho}_k + P_k \hat{\psi}} (1 + e^{\hat{\rho}_k + P_k \hat{\psi}}) = 0
$$
(4.10)

Let $X_k = e^{\hat{\psi}P_k}$. Then equation (4.10) can be written as

$$
A_k X_k^2 + B_k X_k + C_k = 0
$$

where

$$
A_k = (N_k - T_k)e^{2\hat{\rho}_k},
$$

$$
B_k = -\left(T_k(1 + e^{\hat{\gamma} + P_{K+1}}) - N_{1k}e^{\hat{\gamma} + P_{K+1}} - N_{2k}\right)e^{\hat{\rho}_k}
$$

and

$$
C_k = -T_k e^{\gamma + P_{K+1}}
$$

Now, using the same argument as in the derivation in section 4.2.1, we have the values for P_k ($k = 1, \dots, K$) that maximize $l(P)$ for a given value of P_{K+1} as

$$
\tilde{P}_k = \frac{1}{\hat{\psi}}log\left(\frac{-B_k + \sqrt{B_k^2 - 4A_kC_k}}{2A_k}\right).
$$

Substituting this value in equation (4.9), we obtain the maximized log-likelihood for a given value of ${\cal P}_{K+1}$ as

$$
l(\tilde{P}(P_{K+1})) = C + \sum_{k=1}^{K} \left(T_k(\hat{\rho}_k + \tilde{P}_k \hat{\psi}) + (N_{2k} - X_{2k})(\hat{\gamma} + P_{K+1}) \right) -
$$

$$
\sum_{k=1}^{K} \left(N_{1k} log(1 + e^{\hat{\rho}_k + \tilde{P}_k \hat{\psi}}) + N_{2k} log(e^{\hat{\gamma} + P_{K+1}} + e^{\hat{\rho}_k + \tilde{P}_k \hat{\psi}}) \right) \tag{4.11}
$$

Therefore, the likelihood ratio statistic for the pivotal P_{K+1} is

$$
LR_{K+1} = 2 \left[l(0) - l(\tilde{P}(P_{K+1})) \right]
$$

= $2 \sum_{k=1}^{K} \left(-T_k \tilde{P}_k \hat{\psi} + (N_{2k} - X_{2k})(-P_{K+1}) \right)$
 $-2 \sum_{k=1}^{K} \left(N_{1k} log \frac{1 + e^{\rho_k}}{1 + e^{\rho_k + \tilde{P}_k \hat{\psi}}} + N_{2k} log \frac{e^{\hat{\gamma}} + e^{\hat{\rho}_k}}{e^{\hat{\gamma} + P_{K+1}} + e^{\rho_k + \tilde{P}_k \hat{\psi}}} \right).$

From chapter 2, the signed root statistic is

$$
SR_{K+1} = -\sqrt{LR_{K+1}}, \qquad if \quad \gamma < \hat{\gamma}
$$

and

$$
SR_{K+1} = +\sqrt{LR_{K+1}}, \quad \text{if } \gamma > \hat{\gamma}.
$$

From equation (4.9), we have

$$
\frac{\partial l(P)}{\partial P_k} = T_k \hat{\psi} - \frac{N_{1k} \hat{\psi} e^{P_k \hat{\psi} + \hat{\rho}_k}}{1 + e^{\hat{\rho}_k + P_k \hat{\psi}}} - \frac{N_{2k} e^{\hat{\rho}_k + P_k \hat{\psi}} (\hat{\psi})}{e^{\hat{\gamma} + P_{K+1}} + e^{\hat{\rho}_k + P_k \hat{\psi}}}
$$

and

$$
\frac{\partial l(P)}{\partial P_{K+1}} = \sum_{k=1}^{K} (N_{2k} - X_{2k}) - \sum_{k=1}^{K} \frac{N_{2k} e^{\hat{\gamma} + P_{K+1}}}{e^{\hat{\gamma} + P_{K+1}} + e^{\rho_{k} + P_{k}\hat{\psi}}}.
$$

Hence,

$$
-\frac{\partial^2 l(P)}{\partial P_k^2} = \frac{N_{1k}\hat{\psi}^2 e^{\hat{\rho}_k + P_k \hat{\psi}}}{(1 + e^{\hat{\rho}_k + P_k \hat{\psi}})^2} + \frac{N_{2k}e^{\hat{\rho}_k + P_k \hat{\psi}} e^{\hat{\gamma} + P_{K+1}} (\hat{\psi}^2)}{(e^{\hat{\gamma} + P_{K+1}} + e^{\rho_k + P_k \hat{\psi}})^2},
$$

$$
-\frac{\partial^2 l(P)}{\partial P_k \partial P_{K+1}} = -\frac{N_{2k} \hat{\psi} e^{\hat{\gamma} + P_{K+1}} e^{\hat{\rho}_k + P_k \hat{\psi}}}{(e^{\hat{\gamma} + P_{K+1}} + e^{\rho_k + P_k \hat{\psi}})^2}
$$

and

$$
-\frac{\partial^2 l(P)}{\partial P_{K+1}^2} = \sum_{k=1}^K \frac{N_{2k} \hat{\psi} e^{\hat{\gamma} + P_{K+1}} e^{\hat{\rho}_k + P_k \hat{\psi}}}{(e^{\hat{\gamma} + P_{K+1}} + e^{\hat{\rho}_k + P_k \hat{\psi}})^2}
$$

Therefore, $\frac{\partial^2 l(P)}{\partial P_k^2}$ for a given $P_k = 0, k = 1, \dots, K + 1$ is

$$
-\frac{\partial^2 l(0)}{\partial P_k^2} = \frac{N_{1k} \hat{\psi}^2 e^{\hat{\rho}_k}}{(1 + e^{\hat{\rho}_k})^2} + \frac{N_{2k} e^{\hat{\rho}_k} e^{\hat{\gamma}} (\hat{\psi}^2)}{(e^{\hat{\gamma}} + e^{\hat{\rho}_k})^2} = a_k
$$

$$
-\frac{\partial^2 l(0)}{\partial P_k \partial P_{K+1}} = -\frac{N_{2k} e^{\hat{\gamma}} e^{\hat{\rho}_k} (\hat{\psi})}{(e^{\hat{\gamma}} + e^{\hat{\rho}_k})^2} = b_k
$$

and

$$
-\frac{\partial^2 l(0)}{\partial P_{K+1}} = \sum_{k=1}^K \frac{N_{2k} e^{\gamma} e^{\beta_k} (\hat{\psi})}{(e^{\gamma} + e^{\beta_k})^2} = d.
$$

The information matrix I can be written as

$$
I = \begin{pmatrix} I_{11} & I_{12} \\ I_{21} & I_{22} \\ \end{pmatrix}, \quad |I| = |I_{11}| \cdot |I_{22} - I_{21} I_{11}^{-1} I_{12}|
$$

where I_{11} is a diagonal matrix with kth diagonal element a_k , I_{12} is a $K \times 1$ matrix with kth element b_k , $I_{12} = I_{21}$ and $I_{22} = d$ is a scalar.

Therefore, the determinant of the information matrix I (given $P_k = 0$ and $P_{K+1} =$ $0)$ is

$$
|I| = \left(\prod_{k=1}^K a_k\right) \left(d - \sum_{k=1}^K \frac{(b_k)^2}{a_k}\right)
$$

and the determinant of the submatrix I^* for given \bar{P}_k $(k = 1, \dots, K)$ is

$$
|I^*| = \left(\prod_{k=1}^K -\frac{\partial^2 l \tilde{P}(P_{K+1})}{\partial P_k^2}\right).
$$

=
$$
\prod_{k=1}^K \left[\frac{N_{1k} \hat{\psi}^2 e^{\rho_k + \tilde{P}_k \hat{\psi}}}{(1 + e^{\rho_k + \tilde{P}_k \hat{\psi}})^2} + \frac{N_{2k} e^{\rho_k + \tilde{P}_k \hat{\psi}} e^{\gamma + P_{K+1} \hat{\psi}^2}}{(e^{\gamma + P_{K+1}} + e^{\rho_k + \tilde{P}_k \hat{\psi}})^2}\right].
$$

From the equation (4.9), we have,

$$
l_1\left(\tilde{P}(P_{K+1})\right) = \left. \frac{\partial l(P)}{\partial P_{K+1}} \right|_{P_k = \tilde{P}_k} = \sum_{k=1}^K \left((N_{2k} - X_{2k}) - \frac{N_{2k}e^{\tilde{\gamma} + P_{K+1}}}{e^{\tilde{\gamma} + P_{K+1}} + e^{\tilde{\rho}_k + \tilde{P}_k \tilde{\psi}}} \right).
$$

Following the procedure in section 2.3, the marginal tail probability for the pivotal P_{K+1} can be written as

$$
Pr(P_{K+1} \leq p_{K+1}) = \Phi(SR_{K+1}) + \phi(SR_{K+1}) \left(\frac{1}{SR_{K+1}} + \frac{|I|^{\frac{1}{2}}}{l_1(\tilde{P}(P_{K+1})|I^*|^{\frac{1}{2}})} \right)
$$

Hence, the $100(1 - \alpha)\%$ approximate lower and upper confidence limits can be obtained by solving

$$
\Phi(SR_{K+1}) + \phi(SR_{K+1}) \left(\frac{1}{S R_{K+1}} + \frac{|I|^{\frac{1}{2}}}{l_1(\tilde{P}(P_{K+1}))|I^*|^{\frac{1}{2}}} \right) = \frac{\alpha}{2}
$$

and

$$
\Phi(SR_{K+1}) + \phi(SR_{K+1}) \left(\frac{1}{S R_{K+1}} + \frac{|I|^{\frac{1}{2}}}{l_1(\tilde{P}(P_{K+1}))|I^*|^{\frac{1}{2}}} \right) = 1 - \frac{\alpha}{2}
$$

respectively. Denote these as P_L and P_U . Therefore, the corresponding lower and upper limits of γ using Diciccio's procedure are $\hat{\gamma}e^{P_L}$ and $\hat{\gamma}e^{P_U}$ respectively. Then the estimators for the lower and the upper limits of the confidence interval for ψ are

$$
\hat{\psi}_{D u L} = e^{\hat{\gamma} e^{P_L}}
$$

and

$$
\hat{\psi}_{DuU}=e^{\hat{\gamma}e^{P_U}}.
$$

4.2.4 Bartlett's procedure based on the likelihood score

In this approach, we are interested to construct confidence interval for the parameter ψ , in the presence of nuisance parameters $\phi = (p_{11},...,p_{1K})'$. From section 2.3 (chapter 2), Bartlett's alternative to the maximum likelihood estimate $\hat{\psi}$,

$$
T(\psi) = \frac{\partial l}{\partial \psi} - I_{\psi\phi} I_{\phi\phi}^{-1} \left(\frac{\partial l}{\partial \phi} \right)
$$

with variance $I_{\psi\psi,\phi}$ has asymptotically normal distribution. As reviewed in section 2.3, the 100(1 – α)% confidence interval for ψ is obtained by solving

$$
\frac{T(\psi)}{\sqrt{I_{\psi\psi,\phi}}}=\pm Z_{\frac{\alpha}{2}}
$$

where $Z_{\frac{\alpha}{2}}$ is an approximate quantile of a standard normal distribution. From the unconditional log-likelihood discussed in chapter 3, the partial derivative of *I* with respect to ψ is

$$
\frac{\partial l}{\partial \psi} = \sum_{k=1}^{K} \frac{-N_{2k}q_{1k}}{\psi q_{1k} + p_{1k}} + \sum_{k=1}^{K} \frac{(N_{2k} - X_{2k})}{\psi}.
$$

The second partial derivative of *l* with respect to ψ is

$$
\frac{\partial^2 l}{\partial \psi^2} = \sum_{k=1}^K \frac{N_{2k}q_{1k}^2}{(\psi q_{1k} + p_{1k})^2} - \sum_{k=1}^K \frac{(N_{2k} - X_{2k})}{\psi^2}.
$$

Furthermore,

$$
E(X_{2k})=N_{2k}p_{2k}.
$$

Therefore,

$$
-E(\frac{\partial^2 l}{\partial \psi^2}) = -\sum_{k=1}^K \frac{N_{2k}q_{1k}^2}{(\psi q_{1k} + p_{1k})^2} + \sum_{k=1}^K \frac{N_{2k}q_{2k}}{\psi^2}.
$$

Reparametrization of the above equation in terms of γ and ρ_k leads to

$$
-E\left(\frac{\partial^2 l}{\partial \psi^2}\right)=\sum_{k=1}^K \frac{N_{2k}e^{\rho_k}}{(e^{\rho_k}+e^{\gamma})^2e^{\gamma}}.
$$

But from Fisher information matrix

$$
I_{\psi\psi} = -E(\frac{\partial^2 l}{\partial \psi^2}).
$$

Therefore,

$$
I_{\psi\psi} = \sum_{k=1}^{K} \frac{N_{2k}e^{\rho_k}}{(e^{\rho_k} + e^{\gamma})^2 e^{\gamma}} = S(say).
$$
 (4.12)

Furthermore, reparametrization of $\frac{\partial l}{\partial \psi}$ in terms of ρ_k and γ gives

$$
\frac{\partial l}{\partial \psi} = \sum_{k=1}^{K} \frac{N_{2k} e^{\rho_k} - X_{2k} (e^{\gamma} + e^{\rho_k})}{e^{\gamma} (e^{\gamma} + e^{\rho_k})}.
$$
(4.13)

From the unconditional log-likelihood in chapter 3, we have

$$
\frac{\partial l}{\partial p_{1k}} = \frac{(X_{1k} + X_{2k})}{p_{1k}} - \frac{(N_{1k} + N_{2k} - X_{2k} - X_{1k})}{q_{1k}} - \frac{N_{2k}(1 - \psi)}{\psi q_{1k} + p_{1k}}.
$$

But

$$
\phi = (p_{11},...,p_{1K})'.
$$

Therefore,

$$
\frac{\partial^2 l}{\partial p_{1k}\partial p_{1k'}}=0, \qquad k \neq k'.
$$

Further, when $k=k$ $^\prime$

$$
\frac{\partial^2 l}{\partial p_{1k}^2} = -\frac{X_{1k} + X_{2k}}{p_{1k}^2} - \frac{N_{2k} + N_{1k} - X_{1k} - X_{2k}}{q_{1k}^2} + \frac{N_{2k}(1 - \psi)^2}{(\psi q_{1k} + p_{1k})^2}
$$

and

$$
-E(\frac{\partial^2 l}{\partial p_{1k}^2})=\frac{N_{1k}p_{1k}+N_{2k}p_{2k}}{p_{1k}^2}+\frac{N_{2k}q_{2k}+N_{1k}q_{1k}}{q_{1k}^2}-\frac{N_{2k}(1-\psi)^2}{(\psi q_{1k}+p_{1k})^2}.
$$

Using the reparametrization $p_{1k} = \frac{e^{\rho_k}}{1 + e^{\rho_k}}$, we have

$$
-E(\frac{\partial^2 l}{\partial p_{1k}^2}) = \frac{N_{1k}(1+e^{\rho_k})^2}{e^{\rho_k}} + \frac{N_{2k}(1+e^{\rho_k})^4}{e^{\rho_k}(e^{\gamma}+e^{\rho_k})^2}
$$

and

$$
-E(\frac{\partial^2 l}{\partial p_{1k}p_{1k'}})=0.
$$

Therefore, the matrix $I_{\phi\phi}$ is diagonal, and is given by

$$
I_{\phi\phi} = \begin{pmatrix} i_{11} & 0 & \cdots & 0 \\ 0 & i_{22} & \cdots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & 0 & \cdots & i_{KK} \end{pmatrix}
$$

where

$$
i_{kk} = \frac{N_{1k}(1+e^{\rho_k})^2}{e^{\rho_k}} + \frac{N_{2k}(1+e^{\rho_k})^4e^{\gamma}}{e^{\rho_k}(e^{\rho_k}+e^{\gamma})^2}.
$$

Now, from $\frac{\partial l}{\partial \psi}$, we have

$$
\frac{\partial^2 l}{\partial p_{1k}\partial \psi} = \frac{N_{2k}(1-\psi)q_{1k}}{(\psi q_{1k}+p_{1k})^2} + \frac{N_{2k}}{\psi q_{1k}+p_{1k}},
$$

$$
=\frac{N_{2k}(q_{1k}-\psi q_{1k}+\psi q_{1k}+p_{1k})}{(\psi q_{1k}+p_{1k})^2},
$$

$$
=\frac{N_{2k}}{(\psi q_{1k}+p_{1k})^2}.
$$

By reparametrization of $p_{1k} = \frac{e^{\rho_k}}{1 + e^{\rho_k}}$, we have

$$
\frac{\partial^2 l}{\partial p_{1k}\partial \psi}=\frac{N_{2k}(1+e^{\rho_k})^2}{(e^{\gamma}+e^{\rho_k})^2}.
$$

But from Fisher information matrix,

$$
I_{\phi\psi} = -E(\frac{\partial^2 l}{\partial \phi \partial \psi}).
$$

Therefore,

$$
I_{\phi\psi} = \begin{pmatrix} r_1 \\ \vdots \\ r_K \end{pmatrix}
$$

with kth row element $\boldsymbol{r}_k,$ where

$$
r_k = -\frac{N_{2k}(1+e^{\rho_k})^2}{(e^{\gamma}+e^{\rho_k})^2}.
$$

Similarly,

$$
I_{\psi\phi}=(r_1 \cdots r_K).
$$

As mentioned in chapter 2, we have

$$
I_{\psi\psi,\phi} = I_{\psi\psi} - I_{\psi\phi}I_{\phi\phi}^{-1}I_{\phi\psi}.
$$

But from the above derivations, $I_{\psi\phi}I_{\phi\phi}^{-1}I_{\phi\psi}$ is a scalar. Therefore,

$$
I_{\psi\psi,\phi} = \sum_{k=1}^{K} \frac{N_{2k}e^{\rho_k}}{(e^{\rho_k} + e^{\gamma})^2 e^{\gamma}} - \sum_{k=1}^{K} \frac{r_k^2}{i_{kk}}.
$$
 (4.14)

Reparametrization of $\frac{\partial l}{\partial p_{1k}}$ in terms of γ and ρ_k gives

$$
\frac{\partial l}{\partial p_{1k}} = \frac{T_k(1+e^{\rho_k})}{e^{\rho_k}} - (N_k - T_k)(1+e^{\rho_k}) - \frac{N_{2k}(1+e^{\rho_k})(1-e^{\gamma})}{(e^{\gamma}+e^{\rho_k})}
$$

Therefore, $(\frac{\partial l}{\partial \phi})$ is a $K \times 1$ matrix and given by

$$
\left(\frac{\partial l}{\partial \phi}\right) = \begin{pmatrix} u_1 \\ \vdots \\ u_K \end{pmatrix}
$$

with kth row element u_k , which is equal to $\frac{\partial l}{\partial p_{1k}}$. From the above discussions, $I_{\psi\phi}I_{\phi\phi}^{-1}(\frac{\partial l}{\partial\phi})'$ is a scalar and is given by

$$
I_{\psi\phi}I_{\phi\phi}^{-1}(\frac{\partial l}{\partial\phi})=\sum_{k=1}^{K}r_ku_k(i_{kk})^{-1}
$$
\n(4.15)

From equations (4.13), (4.14) and (4.15) the lower limit and the upper limit of γ are obtained by solving

$$
\frac{T(\psi)}{\sqrt{I_{\psi\psi,\phi}}} = \pm Z_{\frac{\alpha}{2}} \tag{4.16}
$$

that is by solving

$$
\frac{\sum_{k=1}^K ((D_k - r_k u_k (i_{kk})^{-1})}{S} = \pm Z_{\frac{\alpha}{2}},
$$

where

$$
D_k = \sum_{k=1}^{K} \frac{N_{2k}e^{\rho_k} - X_{2k}(e^{\gamma} + e^{\rho_k})}{e^{\gamma}(e^{\gamma} + e^{\rho_k})},
$$

$$
r_k = -\frac{N_{2k}(1 + e^{\rho_k})^2}{(e^{\gamma} + e^{\rho_k})^2},
$$

$$
u_k = \frac{T_k(1 + e^{\rho_k})}{e^{\rho_k}} - (N_k - T_k)(1 + e^{\rho_k}) - \frac{N_{2k}(1 + e^{\rho_k})(1 - e^{\gamma})}{(e^{\gamma} + e^{\rho_k})},
$$

$$
i_{kk} = \frac{N_{1k}(1 + e^{\rho_k})^2}{e^{\rho_k}} + \frac{N_{2k}(1 + e^{\rho_k})^4 e^{\gamma}}{e^{\rho_k}(e^{\rho_k} + e^{\gamma})^2},
$$

and

$$
S=\sum_{k=1}^K\frac{N_{2k}e^{\rho_k}}{(e^{\rho_k}+e^{\gamma})^2e^{\gamma}}.
$$

Note that the left hand side of the equation (4.16) involves e^{ρ_k} , which can be replaced from (4.8), by,

$$
e^{\tilde{\rho}_k} = \frac{-B_k + \sqrt{B_k^2 - 4A_kC_k}}{2A_k}
$$

where

$$
A_k = (N_k - T_k),
$$

$$
B_k = -T_k(1 + e^{\gamma}) + N_{1k}e^{\gamma} + N_{2k},
$$

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 $\mathcal{A}^{\text{max}}_{\text{max}}$

and

$$
C_k=-T_k e^{\gamma}.
$$

Denote the lower limit and the upper limit of γ obtained by Bartlett's procedure by $\hat{\gamma}_{BucL}$ and $\hat{\gamma}_{BucU}$. The corresponding lower limit and upper limit of the odds ratio are

$$
\hat{\psi}_{BucL}=e^{\hat{\gamma}_{BucL}}
$$

and

$$
\hat{\psi}_{BucU}=e^{\hat{\gamma}_{BucU}}.
$$

4.2.5 B artlett's procedure corrected for Bias and Skewness

In this procedure the nuisance parameters $\phi = (p_{11}, \dots, p_{1K})'$ in $T(\psi)$ are replaced by their corresponding maximum likelihood estimates $\hat{\phi} = (\hat{p}_{11}, \dots, \hat{p}_{1K})'$. This involves a bias of order $n^{\frac{-1}{2}}$. As reviewed in chapter 2, bias in $T(\psi)$ is given by

$$
Bias(T_{\psi}) = -\frac{1}{2}trace\left(I_{\phi\phi}^{-1}\left(E(\frac{\partial^3 l}{\partial \psi \partial \phi \partial \phi^T}) + 2\frac{\partial I_{\psi\phi}}{\partial \phi}\right)\right) + \frac{1}{2}trace\left(I_{\phi\phi}^{-1}M\right)
$$

where M is the $K \times K$ array (M_1, M_2, \ldots, M_K) with j th column given by

$$
M_j = \left(E(\frac{\partial^3 l}{\partial \phi_j \partial \phi \partial \phi^T}) + 2 \frac{\partial I_{\phi \phi}}{\partial \phi_j} \right) I_{\phi \phi}^{-1} I_{\phi \psi}.
$$

For convenience, we consider

$$
Bias(T_{\psi})=B_1+B_2,
$$

where

$$
B_1 = -\frac{1}{2}trace\left(I_{\phi\phi}^{-1}\left(E(\frac{\partial^3 l}{\partial \psi \partial \phi \partial \phi^T}) + 2\frac{\partial I_{\psi\phi}}{\partial \phi}\right)\right)
$$

and

$$
B_2 = +\frac{1}{2}trace\left(I_{\phi\phi}^{-1}M\right).
$$

Now, let

$$
\frac{\partial^2 l}{\partial p_{1k}\partial p_{1k}} = j_k.
$$

Then

$$
\frac{\partial^2 l}{\partial \phi \partial \phi^T} = \begin{pmatrix} j_1 & 0 & \cdots & 0 \\ 0 & j_2 & \cdots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & 0 & \cdots & j_K \end{pmatrix}
$$

with kth diagonal element $\frac{\partial^2 l}{\partial p_{1k}^2}$ and

$$
E\left(\frac{\partial^3 l}{\partial \psi \partial \phi \partial \phi^T}\right) = \begin{pmatrix} t_1 & 0 & \cdots & 0 \\ 0 & t_2 & \cdots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & 0 & \cdots & t_K \end{pmatrix}
$$

with kth row diagonal element E($\frac{\partial^3 l}{\partial \psi \partial p_{1k} \partial p_{1k}}$) = *t_k*. From section 4.2.3 (chapter 4), we have

$$
\frac{\partial l}{\partial \psi} = \sum_{k=1}^{K} -\frac{N_{2k}q_{1k}}{\psi q_{1k} + p_{1k}} + \frac{(N_{2k} - X_{2k})}{\psi}
$$

Hence

$$
\frac{\partial^2 l}{\partial p_{1k}\partial \psi} = \frac{N_{2k}}{(\psi q_{1k} + p_{1k})^2}
$$

and

$$
\frac{\partial^3 l}{\partial p_{1k}\partial p_{1k}\partial \psi}=-\frac{2N_{2k}(1-\psi)}{(\psi q_{1k}+p_{1k})^3}.
$$

By the parametrization of $p_{1k} = \frac{1}{1 + e^{\rho_k}}$, we have

$$
E\left(\frac{\partial^3 l}{\partial p_{1k}\partial p_{1k}\partial \psi}\right) = -\frac{2N_{2k}(1-e^{\gamma})(1+e^{\rho_k})^3}{(e^{\gamma}+e^{\rho_k})^3}.
$$
 (4.17)

That is

$$
t_k=-\frac{2N_{2k}(1-e^{\gamma})(1+e^{\rho_k})^3}{(e^{\gamma}+e^{\rho_k})^3}.
$$

From section 4.2.3, we have

$$
I_{\psi\phi} = (-E(\frac{\partial^2 l}{\partial \psi \partial p_{11}}), \cdots, -E(\frac{\partial^2 l}{\partial \psi \partial p_{1K}}))
$$

and

$$
-E(\frac{\partial^2 l}{\partial p_{1k}\partial \psi})=-\frac{N_{2k}}{(\psi q_{1k}+p_{1k})^2}
$$

Hence

$$
\frac{\partial}{\partial p_{1k}}(-E(\frac{\partial^2 l}{\partial p_{1k}\partial \psi}))=\frac{2N_{2k}(1-\psi)}{(\psi q_{1k}+p_{1k})^3}.
$$

By the parameterization of $p_{1k} = \frac{e^{\rho_k}}{1 + e^{\rho_k}}$, we have

$$
\frac{\partial}{\partial p_{1k}}(-E(\frac{\partial^2 l}{\partial p_{1k}\partial \psi}))=\frac{2N_{2k}(1-e^{\gamma})(1+e^{\rho_k})^3}{(e^{\gamma}+e^{\rho_k})^3}.
$$
\n(4.18)

Therefore,

$$
\frac{\partial I_{\psi\phi}}{\partial \phi} = \begin{pmatrix} l_1 & 0 & \cdots & 0 \\ 0 & l_2 & \cdots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & 0 & \cdots & l_K \end{pmatrix}
$$

with kth diagonal element l_k , where

$$
l_k=\frac{2N_{2k}(1-e^{\gamma})(1+e^{\rho_k})^3}{(e^{\gamma}+e^{\rho_k})^3}.
$$

Therefore, from the above discussions $E(\frac{\partial^3 l}{\partial p_{1k}\partial p_{2k}\partial \psi}) + 2 \frac{\partial I_{\psi\phi}}{\partial \phi}$ is a $K \times K$ matrix with

diagonal element $t_k + 2l_k$. Also the diagonal element of the matrix $I_{\phi\phi}^{-1}$ is $(i_{kk})^{-1}$. Therefore,

$$
B_1 = -\frac{1}{2} \sum_{k=1}^{K} \frac{(t_k + 2l_k)}{i_{kk}}.
$$
 (4.19)

Now, the jth array element of the matrix M is

$$
M_j = \left(E(\frac{\partial^3 l}{\partial \phi_j \partial \phi \partial \phi^T}) + 2 \frac{\partial I_{\phi \phi}}{\partial \phi_j} \right) I_{\phi \phi}^{-1} I_{\phi \psi}.
$$

We have shown that

$$
\frac{\partial^2 l}{\partial \phi \partial \phi^T} = \begin{pmatrix} j_1 & 0 & \cdots & 0 \\ 0 & j_2 & \cdots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & 0 & \cdots & j_K \end{pmatrix}.
$$

Therefore,

$$
\frac{\partial^3 l}{\partial \phi_k \partial \phi \partial \phi^T} = \begin{pmatrix} 0 & 0 & \cdots & 0 \\ 0 & s_k & \cdots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \end{pmatrix}
$$

where

$$
s_k = \frac{\partial^3 l}{\partial p_{1k}^3}.
$$

From section 4.2.3, we have

$$
\frac{\partial^2 l}{\partial p_{1k}^2} = -\frac{(X_{1k} + X_{2k})}{p_{1k}^2} - \frac{(N_{1k} + N_{2k} - X_{1k} - X_{2k})}{q_{1k}^2}
$$

$$
+\frac{N_{2k}(1-\psi)^2}{(\psi q_{1k}+p_{1k})^2}.
$$

Hence

$$
\frac{\partial^3 l}{\partial p_{1k}^3} = \frac{2(X_{1k} + X_{2k})}{p_{1k}3} - \frac{2(N_{1k} + N_{2k} - X_{1k} - X_{2k})}{q_{1k}^3}
$$

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$$
+\frac{N_{2k}(1-\psi)^3(-2)}{(\psi q_{1k}+p_{1k})^3}
$$

Therefore,

$$
E(\frac{\partial^3 l}{\partial p_{1k}^3}) = \frac{2N_{1k}(q_{1k} - p_{1k})}{p_{1k}^2 q_{1k}^2} + \frac{2N_{2k}}{p_{1k}^2(\psi q_{1k} + p_{1k})} - \frac{2N_{2k}(\psi)}{q_{1k}^2(\psi q_{1k} + p_{1k})} - \frac{2N_{2k}(1 - \psi)^3}{(\psi q_{1k} + p_{1k})^3}.
$$

By using the reparametrization of p_{1k} , q_{1k} and ψ , we have

$$
E\left(\frac{\partial^3 l}{\partial p_{1k}^3}\right) = \frac{2N_{1k}(1 - e^{\rho_k})(1 + e^{\rho_k})^3}{(e^{\rho_k})^2} + \frac{2N_{2k}(1 + e^{\rho_k})^3}{(e^{\rho_k})^2(e^{\gamma} + e^{\rho_k})}
$$

$$
-\frac{2N_{2k}(1 + e^{\rho_k})^3 e^{\gamma}}{(e^{\gamma} + e^{\rho_k})} - \frac{2N_{1k}(1 - e^{\gamma})^3(1 + e^{\rho_k})^3}{(e^{\rho_k} + e^{\gamma})^3} = s_k \tag{4.20}
$$

Let R.H.S of the above equation is equal to s_k .

We have already shown that $I_{\phi\phi}$ is a diagonal matrix with diagonal element i_{kk} . Therefore.

$$
\frac{\partial I_{\phi\phi}}{\partial \phi_k} = \begin{pmatrix} 0 & 0 & \cdots & 0 \\ 0 & v_k & \cdots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \end{pmatrix}
$$

where

$$
v_k = \frac{\partial}{\partial p_{1k}} E(-\frac{\partial^2 l}{\partial p_{1k}^2}).
$$

From section 4.2.4, we have

$$
-E\left(\frac{\partial^2 l}{\partial p_{1k}^2}\right)=\frac{N_{1k}p_{1k}+N_{2k}p_{2k}}{p_{1k}^2}+\frac{N_{2k}q_{2k}+N_{1k}q_{1k}}{q_{1k}^2}-\frac{N_{2k}(1-\psi)^2}{(\psi q_{1k}+p_{1k})^2}.
$$

Hence, using the reparametrization of p_{1k} , q_{1k} and ψ , we have

$$
\frac{\partial}{\partial p_{1k}}E(-\frac{\partial^2 l}{\partial p_{1k}^2})=\frac{N_{1k}(e^{\rho_k}-1)(1+e^{\rho_k})^3}{(e^{\rho_k})^2}-\frac{N_{2k}(e^{\gamma}(e^{\rho_k}-1)-2e^{\rho_k})(1+e^{\rho_k})^3}{(e^{\rho_k})^2(e^{\gamma}+e^{\rho_k})^2}
$$

$$
+\frac{N_{2k}e^{\gamma}(e^{\rho_k}-1+2e^{\gamma})(1+e^{\rho_k})^3}{(e^{\gamma}+e^{\rho_k})^2}+\frac{2N_{2k}(1-e^{\gamma})^3(1+e^{\rho_k})^3}{(e^{\gamma}+e^{\rho_k})^3}=v_k \qquad (4.21)
$$

Let the R.H.S of the above equation is equal to v_k But, kth array element of M is

$$
M_k = \left(E\left(\frac{\partial^3 l}{\partial \phi_k \partial \phi \partial \phi^T} \right) + 2 \frac{\partial I_{\phi\phi}}{\partial \phi_k} \right) I_{\phi\phi}^{-1} I_{\phi\psi}
$$

Therefore,

$$
M_k = \left(\begin{array}{c} 0 \\ 0 \\ m_k \\ \vdots \\ 0 \end{array}\right),
$$

with $m_k = (s_k + 2v_k)(r_k)(i_{kk})^{-1}$. Therefore, M is a K×K matrix with diagonal element m_k . Hence,

$$
I_{\phi\phi}^{-1}M = \begin{pmatrix} m_1 i_{11}^{-1} & 0 & \cdots & 0 \\ 0 & m_2 i_{22}^{-1} & \cdots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & 0 & \cdots & m_K i_{KK}^{-1} \end{pmatrix}
$$

Therefore,

$$
B_2 = \frac{1}{2} \sum_{k=1}^{K} \frac{(s_k + 2v_k)(r_k)}{(i_{kk})^2}.
$$
 (4.22)

From equations (4.19) and (4.22), we can find the bias in terms of γ and ρ_k . That is

$$
Bias(T_{\psi}) = B_1 + B_2 = -\frac{1}{2}\sum_{k=1}^{K} \frac{(m_k + 2l_k)}{i_{kk}} + \frac{1}{2}\sum_{k=1}^{K} \frac{(s_k + 2v_k)(r_k)}{(i_{kk})^2}.
$$

Bartlett's correction for Skewness

 -3 As reviewed in chapter 2, the third cumulant of T_{ψ} to the order $O(n^{-\frac{1}{2}})$ is obtained for $s, t, q = 1, \dots, K$ is given by

$$
K_3(\psi) = 2E\left(\frac{\partial^3 l}{\partial \psi^3}\right) + 3\left(\frac{\partial I_{\psi\psi}}{\partial \psi}\right)
$$

$$
-3\sum_{s=1}^{K} f_s \left(2E \left(\frac{\partial^3 l}{\partial \psi^2 \partial \phi_s} \right) + 2 \frac{\partial I_{\psi\phi_s}}{\partial \psi} + \frac{\partial I_{\psi\psi}}{\partial \phi_s} \right)
$$

+3
$$
\sum_{s} \sum_{t} f_s f_t \left(2E \left(\frac{\partial^3 l}{\partial \psi \partial \phi_s \partial \phi_t} \right) + \frac{\partial I_{\phi_s\phi_t}}{\partial \psi} + \frac{\partial I_{\psi\phi_t}}{\partial \phi_s} + \frac{\partial I_{\psi\phi_s}}{\partial \phi_t} \right)
$$

-
$$
\sum_{s} \sum_{t} f_s f_t f_q \left(2E \left(\frac{\partial^3 l}{\partial \phi_s \partial \phi_t \partial \phi_q} \right) + \frac{\partial I_{\phi_t} \phi_q}{\partial \phi_s} + \frac{\partial I_{\phi_s} \phi_q}{\partial \phi_t} + \frac{\partial I_{\phi_s} \phi_t}{\partial \phi_q} \right)
$$

From section 4.2.4, we have

$$
\frac{\partial^2 l}{\partial \psi^2} = \sum_{k=1}^K \frac{N_{2k}q_{1k}^2}{(\psi q_{1k} + p_{1k})^2} - \sum_{k=1}^K \frac{(N_{2k} - X_{2k})}{\psi^2}.
$$

Hence

$$
\frac{\partial^3 l}{\partial \psi^3} = \sum_{k=1}^K \frac{-2N_{2k}q_{1k}^2 q_{1k}}{(\psi q_{1k} + p_{1k})^3} + \sum_{k=1}^K \frac{2(N_{2k} - X_{2k})}{\psi^3}
$$

and

$$
E(\frac{\partial^3 l}{\partial \psi^3}) = \sum_{k=1}^K \frac{-2N_{2k}q_{1k}^3}{(\psi q_{1k} + p_{1k})^3} + \sum_{k=1}^K \frac{2N_{2k}q_{2k}}{\psi^3}.
$$
 (4.23)

Also from section 4.2.4, we have

$$
I_{\psi\psi} = \sum_{k=1}^{K} \frac{-N_{2k}q_{1k}^2}{(\psi q_{1k} + p_{1k})^2} + \sum_{k=1}^{K} \frac{N_{2k}q_{2k}}{\psi^2}
$$

Therefore,

$$
\frac{\partial I_{\psi\psi}}{\partial \psi} = \sum_{k=1}^{K} \frac{2N_{2k}q_{1k}^3}{(\psi q_{1k} + p_{1k})^3} - \sum_{k=1}^{K} \frac{N_{2k}q_{1k}(p_{1k} + 2\psi q_{1k})}{\psi^2(p_{1k} + \psi q_{1k})}.
$$
(4.24)

From equations (4.23) and (4.24), we have

 $\bar{\bar{z}}$

$$
2E(\frac{\partial^3l}{\partial\psi^3})+3\frac{\partial I_{\psi\psi}}{\partial\psi}=
$$

$$
\sum_{k=1}^{K} \frac{2N_{2k}q_{1k}^3}{(\psi q_{1k} + p_{1k})^3} + \sum_{k=1}^{K} \frac{N_{2k}q_{1k}(p_{1k} - 2\psi q_{1k})}{\psi^2(\psi q_{1k} + p_{1k})^2}.
$$
 (4.25)

Let the R.H.S of the above equation be A. From chapter 2 review, $f = I_{\phi\psi}I_{\phi\phi}^{-1}$, we have the sth element

$$
f_s = \frac{(r_s)}{i_{ss}}
$$

 $E(\frac{\partial^3 l}{\partial \psi^2 \partial \phi_s})$ is a $K \times 1$ matrix and it's sth element can be determined as follows:

$$
\frac{\partial^3 l}{\partial \psi^2 \partial p_{1s}} = \frac{\partial}{\partial \psi} \left(\frac{\partial^2 l}{\partial \psi \partial p_{1s}} \right)
$$

$$
= \frac{\partial}{\partial \psi} \left(\frac{N_{2s}}{(\psi q_{1s} + p_{1s})^2} \right)
$$

$$
= \frac{-2N_{2s}q_{1s}}{(\psi q_{1s} + p_{1s})^3}
$$

$$
E\left(\frac{\partial^3 l}{\partial \psi^2 \partial p_{1s}}\right) = \frac{-2N_{2s}q_{1s}}{(\psi q_{1s} + p_{1s})^3}.
$$

a *r* $\frac{\partial \phi}{\partial t}$ is a $K \times 1$ matrix and it's sth element can be determined as follows:

$$
\frac{\partial I_{\psi\phi_s}}{\partial \psi} = \frac{\partial}{\partial \psi} \left(\frac{-N_{2s}}{(\psi q_{1s} + p_{1s})^2} \right)
$$

$$
= \frac{2N_{2s}q_{1s}}{(\psi q_{1s} + p_{1s})^3}
$$

from the above equations, we have

$$
2E(\frac{\partial^3 l}{\partial \psi^2 \partial \phi_s}) + 2\frac{\partial I_{\psi\phi_s}}{\partial \psi} = 0.
$$

From section 4.2.4, $I_{\psi\psi}$ is known and it is a scalar. Therefore, $\frac{\partial I_{\psi\psi}}{\partial \phi_i}$ is a $K \times 1$ matrix. It's sth element is

$$
\frac{\partial I_{\psi\psi}}{\partial p_{1s}} = \frac{\partial}{\partial p_{1s}} \left(\sum_{s=1}^K \frac{-N_{2s}q_{1s}^2}{(\psi q_{1s} + p_{1s})^2} + \sum_{s=1}^K \frac{N_{2s}\psi q_{1s}}{\psi^2(\psi q_{1s} + p_{1s})} \right).
$$

Hence.

$$
\frac{\partial I_{\text{UU}}}{\partial p_{1s}} = \frac{2N_{2s}q_{1s}}{(\psi q_{1s} + p_{1s})^3} - \frac{N_{2s}}{\psi(\psi q_{1s} + p_{1s})^2}.
$$

By reparametrization of p_{1s} , q_{1s} and ψ , we have

$$
\frac{\partial I_{\psi\psi}}{\partial p_{1s}} = \frac{2N_{2s}(1+e^{\rho_s})^2}{(e^{\gamma}+e^{\rho_s})^3} - \frac{N_{2s}(1+e^{\rho_s})^2}{e^{\gamma}(e^{\gamma}+e^{\rho_s})^2}.
$$
(4.26)

Let the R.H.S of the above equation be *g..* Therefore,

$$
\sum_{s=1}^K f_s \left(2E(\frac{\partial^3 l}{\partial \psi^2 \partial \phi_s}) + 2 \frac{\partial I_{\psi \phi_s}}{\partial \psi} + \frac{\partial I_{\psi \psi}}{\partial \phi_s} \right) = \sum_{s=1}^K \frac{(r_s)(g_s)}{i_{ss}}.
$$

But from equation (4.17), the kth element of the matrix $E\left(\frac{\partial^3 l}{\partial \psi \partial \phi_4 \partial \phi_t}\right)$ is $\frac{-2N_{2k}(1-\epsilon^{\gamma})(1+\epsilon^{\rho_k})^3}{(\epsilon^{\gamma}+\epsilon^{\rho_k})^3}$ when $s = t = k$ and zero otherwise. We have already shown that the above value is t_k . From equation (4.18), the kth element of the matrix $\frac{\partial I_{\psi o_t}}{\partial \phi}$ is

$$
=\frac{2N_{2k}(1-e^{\rho_k})(1+e^{\rho_k})^3}{(e^{\gamma}+e^{\rho_k})^3}
$$

when $s = t = k$, otherwise zero and we have already shown that this value is equal to l_k .

Now, we need to calculate $\frac{\partial I_{\phi, \phi}}{\partial \psi}$. When $s = t = k$, it is

$$
\frac{\partial I_{o_k o_k}}{\partial \psi} = \frac{\partial}{\partial \psi} \left(\frac{N_{1k}}{p_{1k}q_{1k}} + \frac{N_{2k}p_{2k}}{p_{1k}^2} + \frac{N_{2k}q_{2k}}{q_{1k}^2} - \frac{N_{2k}(1-\psi)^2}{(\psi q_{1k} + p_{1k})^2} \right)
$$

$$
= \frac{N_{2k}(p_{1k} - q_{1k})}{p_{1k}q_{1k}(\psi q_{1k} + p_{1k})^2} + \frac{2N_{2k}(1-\psi)}{(\psi q_{1k} + p_{1k})^3}.
$$

By reparametrization of p_{1k} , q_{1k} and ψ , we have

$$
\frac{\partial I_{\phi,\phi_t}}{\partial \psi} = \frac{N_{2k}(e^{\rho_{k}} - 1)(1 + e^{\rho_{k}})^3}{e^{\rho_{k}}(e^{\gamma} + e^{\gamma})^2} + \frac{2N_{2k}(1 - e^{\gamma})(1 + e^{\rho_{k}})^3}{(e^{\gamma} + e^{\rho_{k}})^3}
$$
(4.27)

when $s = t = k$, otherwise zero. Let the R.H.S of the above equation be e_k from eq 4.24 we have

$$
2E\left(\frac{\partial^3 l}{\partial \psi^3}\right) + 3\frac{\partial I_{\psi\psi}}{\partial \psi} = A
$$

and from equation (4.26). we have

$$
-3\sum_{s=1}^{K} f_s \left(2E\left(\frac{\partial^3 l}{\partial \psi^2 \partial \phi_s}\right) + 2\frac{\partial I_{\psi\phi_s}}{\partial \psi} + \frac{\partial I_{\psi\psi}}{\partial \phi_s}\right) = -3\sum_{k=1}^{K} \frac{(r_k)(g_k)}{i_{kk}}.
$$

From equation (4.27). we have

$$
+3\sum_{\bullet}\sum_{t}f_{\bullet}f_{t}\left(2E\left(\frac{\partial^{3}l}{\partial\psi\partial\phi_{\bullet}\partial\phi_{t}}\right)+\frac{\partial I_{\phi_{\bullet}\phi_{t}}}{\partial\psi}+\frac{\partial I_{\psi\phi_{t}}}{\partial\phi_{\bullet}}+\frac{\partial I_{\psi\phi_{\bullet}}}{\partial\phi_{t}}\right)
$$

$$
= 3 \sum_{k=1}^K (\frac{r_k}{i_{kk}})^2 (e_k).
$$

From equation (4.20) and from equation (4.21). we have

$$
-\sum_{s}\sum_{t}\sum_{q}f_{s}f_{t}f_{q}\left(2E\left(\frac{\partial^{3}l}{\partial\phi_{s}\partial\phi_{t}\partial\phi_{q}}\right)+\frac{\partial I_{o_{t}}\phi_{q}}{\partial\phi_{s}}+\frac{\partial I_{o_{s}}\phi_{q}}{\partial\phi_{t}}+\frac{\partial I_{o_{s}}\phi_{t}}{\partial\phi_{q}}\right)
$$

$$
=-\sum_{k=1}^{K}(\frac{r_{k}}{i_{kk}})^{3}\left(2s_{k}+3v_{k}\right)
$$

Thus.

$$
K_3(\psi) = A - 3 \sum_{k=1}^K \frac{(r_k)(g_k)}{i_{kk}} + 3 \sum_{k=1}^K (\frac{r_k}{i_{kk}})^2(e_k) - \sum_{k=1}^K (\frac{r_k}{i_{kk}})^3 (2s_k + 3v_k).
$$

The lower and upper confidence limits of γ are obtained by solving

$$
\frac{T_{\psi}}{\sqrt{I_{\psi\psi,\phi}}} - \frac{B(T_{\psi})}{\sqrt{I_{\psi\psi,\phi}}} - \frac{K_3(\psi)(Z_{\frac{2}{3}}^2 - 1)}{6(I_{\psi\psi,\phi})} = \pm Z_{\frac{\phi}{2}}
$$
(4.28)

Note that the left hand side of the equation (4.28) involves e^{ρ_k} , which can be replaced from (4.8), by,

$$
e^{\tilde{\rho}_k}=\frac{-B_k+\sqrt{B_k^2-4A_kC_k}}{2A_k},
$$

where

 $A_k = (N_k - T_k),$ $B_k = -T_k(1 + e^{\gamma}) + N_{1k}e^{\gamma} + N_{2k}$

and

$$
C_k=-T_k e^{\gamma}.
$$

Denote the lower limit and the upper limit of γ obtained by Bartlett's corrected procedure by $\hat{\gamma}_{BCucL}$ and $\hat{\gamma}_{BCucU}$. The corresponding lower limit and upper limit of the odds ratio are

$$
\hat{\psi}_{BCucL}=e^{\hat{\gamma}_BCucL}
$$

and

$$
\hat{\psi}_{BCucU}=e^{\hat{\gamma}_{BCucU}}.
$$

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 ζ $\hat{\mathbb{R}}_t$

CHAPTER 5

SIMULATION STUDIES

In this chapter, the performance of the likelihood based procedures except the adjusted likelihood procedure based on the unconditional likelihood derived in chapter 4. are examined through simulations. The adjusted likelihood based procedure based on the unconditional likelihood is showing some convergence problems that could not be resolved by the author. IMSL random number generator RNBIN was used to generate binomial variables. The range of values for the parameters K, N_{1k} , N_{2k}, ψ and p_{1k} used in the simulation studies were chosen to be representative of situations which arise in epidemiologic practice. In the simulation study, for each of the *K* =5, 10 strata, the sample sizes chosen were $(N_{1k}, N_{2k}) = (5,5)$, (10,10), (20,20), (5,20). The values of probabilities p_{1k} chosen were $p_{1k} = 0.05 + 0.04k(\frac{20}{K})$ [Robins, Breslow and Greenland (1986)] and the values of ψ chosen were $\psi = 1, 3.5$ and 6.5. For all the likelihood procedures and for each combination of K, (N_{1k}, N_{2k}) , p_{1k} and ψ , we produced the tail and the coverage probabilities and the average lengths based on 1000 samples. The validity of the confidence interval is determined by the probability that the random interval covers the parameter value. This probability is called coverage probability. We have use 95% nominal confidence coefficient. The tail probabilities are the probabilities that the parameter value lies outside the random interval. Using the conventional rule, we added 0.5 to each observed frequency in any simulated table where a zero observed frequency occured. Tables 5.1a and 5.1b list the lower and upper tail probabilities, coverage probabilities and average length of the confidence intervals for the common odds ratio using the conditional likelihood. Tables 5.2a and 5.2b list the lower and upper tail probabilities, coverage probabilities and average length of the confidence intervals for the common odds ratio using the unconditional likelihood.

Results: The ML method (Procedure based on maximum likelihood estimate) provides adequate coverage ($p \geq 0.9$, where p is estimated coverage probability) for $\psi = 1.0$ and unacceptable coverage for other values of ψ for both conditional and unconditional likelihoods. The LR method (Procedure based on likelihood ratio) provides excellent coverage for $\psi = 1.0, 3.5$ and 6.5 for all designs used for conditional likelihood except for the design $N_{1k} = N_{2k} = 5$, $K = 10$ and $\psi =$ 6.5. The LR method based on the unconditional likelihood also provides excellent coverage for all designs used. The methods B and BC (Bartlett and Bartlett's corrected) provide excellent coverage for ψ =1.0, 3.5 and 6.5 for all designs used for both conditional and unconditional likelihood except for the design $N_{1k} = N_{2k} = 5$ $,K = 10$ and $\psi = 6.5$ for conditional likelihood. The SQ method (Signed square root of the likelihood ratio) provides excellent coverage ($p \ge 0.94$) for $\psi = 1,3.5$ and 6.5 for the design $N_{1k} = N_{2k} = 20$ and $K = 5$ and also for $\psi = 3.5$ and 6.5 for the design $N_{1k} = N_{2k} = 10$ and $K = 10$. For all other designs the coverage dropped below 94% for conditional likelihood. The SQ method provides excellent coverage for the unconditional likelihood for all the designs used. From Tables 5.1a and 5.1b, we note that the likelihood ratio intervals provide the upper tail probabilities which are larger than those of the lower tail probabilities for many of the designs used for conditional likelihood. The SQ method gives higher values for lower tail probabilities than LR method for all designs used for conditional likelihood and most of the designs used for unconditional likelihood. For $N_{1k} = N_{2k} = 20$ and $K = 5$, the methods LR, B, BC and SQ performed equally well in terms of coverage and tail probabilities for conditional likelihood. But for the same design, when $\psi = 6.5$ these methods provide excellent upper tail probabilities and an adequate lower tail probabilities. For $N_{1k} = N_{2k} = 10$ and $K = 5$, the methods B and BC performed well in terms of tail and coverage probabilities when $\psi = 1.0$, for conditional likelihood. For $N_{1k} = N_{2k} = 20$ and $K = 10$, the SQ method performed well in terms of tail and coverage probabilities, when $\psi = 1.0$ and 3.5 for conditional likelihood. For $N_{1k} = N_{2k} = 10$ and $K = 10$, the methods B and BC performed well in terms of tail and coverage probabilities when $\psi = 1.0$ for conditional likelihood. For unconditional likelihood the SQ method (Signed square root of likelihood ratio) performed well in terms of coverage and tail probabilities when $K = 5$ for all the designs used. For $N_{1k} = N_{2k} = 20$ and $K = 10$, the methods B and SQ performed equally well in terms of tail and coverage probabilities for unconditional likelihood. For $N_{1k} = N_{2k} = 10$ and $K = 10$, the methods LR, B, BC and SQ performed well in terms of tail and coverage probabilities when $\psi = 1.0$ for unconditional likelihood. But for other values of ψ the methods LR, B, and SQ provide excellent upper tail probabilities and unacceptable lower tail probabilities. For the design $N_{1k} = 5$ and $N_{2k} = 20$ and $K = 5$, the methods LR, B, and BC performed well in terms of tail and coverage probabilities for $\psi = 1$ and 3.5.

In summary, for conditional likelihood, in terms of coverage probabilities, the methods LR, B and BC provide excellent coverage for all the designs used. But in terms of tail probabilities Bartlett's method perfomed slightly better than other method. For unconditional likelihood, in terms of coverage probabilities, the methods LR, B, BC and SQ provide excellent coverage for all the designs used. But in terms of tail probabilities, the methods B and SQ peformed well. However, in terms of average length the method B gave the shortest average length. For the Bartlett method, the unconditional likelihood gave the coverage probability closed to 0.95 and the tail probabilities closed to 0.25 for most of the designs used. Based on the results of these likelihood based procedures, the Bartletts method B with

unconditional likelihood seems to be most suitable for constructing confidence limits for common odds ratio, atlcast for the kinds of designs that have been used in the simulations study in this thesis. However, most of these procedures fall short of producing adequate coverage probability when K (\geq 25) increases and the sample sizes (< 5) in each tables are small. The likelihood procedure corrected for appropriate tails in small samples developed following Deciccio, Field and Fraser (1990) is expected to perform well in these situations.

Table 5 -la: Lower and upper tail probabilities, coverage probabilities and average lengths of the confidence intervals for the common odds ratio using the conditional likelihood. $p_{1k} = 0.05+0.04k(20/K)$, K=5, alpha=0.05

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 $\gamma_{\rm{in}}$

 λ

 $\ddot{}$

Table 5.1b: Lower and upper tail probabilities, coverage probabilities and average lengths of the confidence intervals for the common odds ratio using the conditional likelihood. $p_{1k} = 0.05+0.04k(20/K)$, K=10, alpha=0.05

55

 \mathcal{L}

Table 5.2a: Lower and upper tail probabilities, coverage probabilities and average lengths of the confidence intervals for the common odds ratio using the unconditional likelihood. $p_{1k} = 0.05+0.04k(20/K)$, K=5, alpha=0.05

 $\ddot{}$

Table 5.2b: Lower and upper tail probabilities, coverage probabilities and average lengths of the confidence intervals for the common odds ratio using the unconditional likelihood. $p_{1k} = 0.05+0.04k (20/K)$, K=10, alpha=0.05

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 \bar{z}

 $\hat{\mathcal{A}}$

 $\sim 10^6$

 $\sim 10^{-10}$

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