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# Tool Support for Inspecting the Code Quality of HPC Applications

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## Abstract

*The nature of HPC application development encourages ad hoc design and implementation, rather than formal requirements analysis and design specification as is typical in software engineering. However, we cannot simply expect HPC developers to adopt formal software engineering processes wholesale, even while there is a need to improve software structure and quality to ensure future maintainability. Therefore, we propose tools that HPC developers can use at their discretion to obtain feedback on the structure and quality of their codes. This feedback would come in the form of code quality metrics and analyses, presented when necessary in intuitive and interactive visualizations. This paper summarizes our implementation of just such a tool, which we apply to a standard HPC benchmark as “proof-of-concept.”*

## 1. Introduction

Software engineering processes are not commonly applied to high-performance computing (HPC) application development for several reasons [4, 9, 11]. First, developers may focus on performance over other aspects of the code, such as those that would ease future maintenance. Secondly, the developer could be the application’s sole customer, at least initially; thus, there may be little motivation to think about how to use, maintain, adapt, or extend an application beyond its initial use. Thirdly, many HPC developers are not formally trained in software engineering processes; development proceeds in an *ad hoc* manner, possibly without requirements engineering, design plans, or documentation. Collectively, these aspects of HPC software imply high development and maintenance costs during a software system’s lifetime.

However, it is unrealistic to expect sudden widespread changes in the HPC applications development process [4].

Instead, we envision the creation of tools to help communicate software maintainability, component reusability, and code quality aspects of HPC software to developers during code development. These tools would provide such feedback *unobtrusively*, *i.e.*, in a way that allows the developer to decide how best to make trade-offs between the performance and maintainability of their software. Moreover, by providing the right kinds of analyses and visualizations, these tools could even aid in restructuring and improving code during forward-engineering.

This paper summarizes our on-going implementation of just such a tool for large-scale C and C++ applications. Our code quality feedback tool, which we implemented by combining a number of other tools as described in Section 3, does not enforce particular design or development formalisms or processes [5]; rather, it provides information and guidance in the form of specific code quality metrics. Moreover, our tool can provide this information in the form of interactive visualizations when appropriate, *e.g.*, when trying to understand whether the overall software architecture matches the developer’s mental model, or whether a subset of files or functions could be easily extracted as a reusable component.

We provide concrete examples of the analyses our tool produces in Section 2. These examples come from applying our tool to an actual HPC benchmark, SMG2000 [1]. Section 3 describes our tool’s implementation. We hope this paper will stimulate discussion on the role of interactive feedback about code quality during HPC application development, with our tool serving as a constructive example of what is possible.

## 2. Code Quality Metrics and Analyses

Our tool presents the user with a variety of code quality metrics and analyses, of which this section provides concrete examples. Except where noted, we generated these

Property	Value	Remark
#LOC (estimate)	46,000	based on AST size
#LOC (wc)	28,301	w/o external libs
#Files	71	source and header
#Files (Source)	53	
#Files (Header)	18	
#AST NODES	515,030	
#AST NODES	858,660	(with ext lib)
#CLASSES	0	
#STRUCTS	33	
#UNIONS	1	
#FUNCTIONS	394	SMG2000 only
#FUNCTION CALLS	1,268	

**Table 1. Simple global statistics**

Property	Value	Remark
#VAR_LOCAL	3726	
#VAR_MEMBER	0	
#VAR_MEMBER_PUBLIC	0	
#VAR_MEMBER_STATIC	0	
#VAR_MEMBER_STRUCT	245	
#VAR_MEMBER_UNION	2	
#VAR_NON_MEMBER	2	globals
#VAR_NON_MEMBER_STATIC	5	file access

**Table 2. Variable statistics**

examples by applying our tool to SMG2000, an 50k lines-of-code parallel HPC benchmark implementing the semi-coarsening multigrid method [1].

We organize these examples into three categories (Sections 2.1–2.3), in increasing order of “context” about the code that each requires. Roughly speaking, the more context needed to understand a metric or analysis, the better suited it is to either static or even interactive visualization.

## 2.1. Simple statistics

Our tool provides many metrics and analyses that can be represented simply as a single number or short textual list, such as the lines of code, the number of global variables, or the number of function calls (measured statically), among others. Tables 1–3 show several examples.

The statistics computed in Table 3 are among the most interesting of the simple statistics. For instance, our tool can check for certain kinds of security violations related to API misuse<sup>1</sup> and reports McCabe’s cyclomatic complexity (“CC”) [6]. Where appropriate, the user may select particular thresholds on these statistics, and the tool will report violations accordingly.

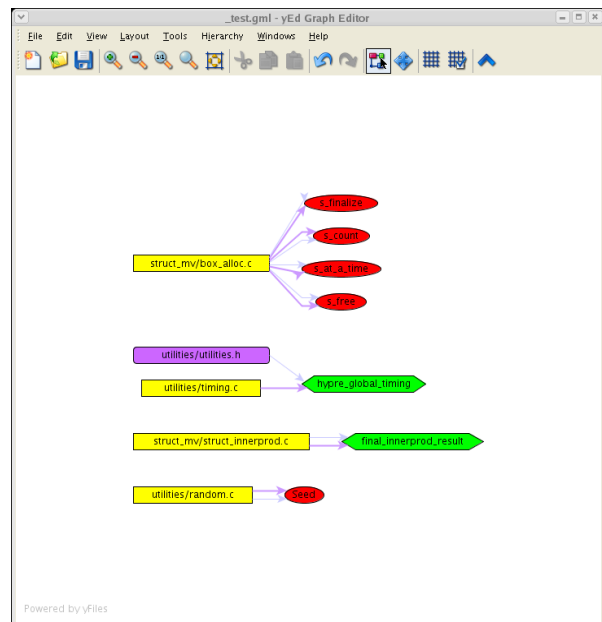
<sup>1</sup>E.g., using the C function `sprintf` rather than the safer `snprintf`.

Analysis	Threshold	#Violations
Security	0	4
CC per function	< 20	20
CC per file	< 100	4
Global Variable	0	2
LOC (per function)	< 200	19
Cyclic dependency (funcs)	0	3
Cyclic dependency(files)	0	1
Naming	>3 char	53
TOTAL		106

**Table 3. Simple analysis results**

## 2.2. Coherence reporting

In addition to the simple statistics of Section 2.1, our tool can report coherences. Our tool presents this category of information in the form of static pictures, to help illustrate interesting context.



**Figure 1. Variable access graph.**

For example, consider the variable access graph in Figure 1, which shows coherences between global variables (ovals and hexagons) and the source files which reference them (boxes) as edges. Figure 1 reveals the existence of two global variables (hexagons), and five file-scoped variables (*i.e.*, variables declared as `static` in a file’s global scope). The two true global variables are each used only within a single source file,<sup>2</sup> and therefore could be eliminated by

<sup>2</sup>One of the variables, `hyper_global_timing`, appears in a header file as well, but only when conditionally compiled for inclusion within the corresponding source file shown.

converting them to be, for instance, file-scoped variables instead. However, whether or not to do this is up to the developer; our tool only reveals this opportunity.

As another example, consider the file-include graph for SMG2000 shown in Figure 2, which shows coherences between source files (yellow boxes) and header files, where we distinguish between the program’s header files (green boxes) and system headers (grey boxes). A developer could use this image to determine, for instance, whether there is unwanted sharing of header files between logically distinct components. (No such cases are shown in this figure.)

### 2.3. Interactive visualizations

In some cases, text dumps and even static pictures might not illuminate issues to the developer. Our tool can provide interactive 3-D visualizations for such information, and we use familiar visual metaphors from the real-world to aid program comprehension and understanding in these visualizations.

For example, consider the image of the project file structure depicted in Figure 3, which is a snapshot taken of the tool while running on a sub-module of ROSE, the compiler infrastructure that constitutes the front-end of our tool (see Section 3.1). Such an image gives a developer a sense of the overall software architecture. The five directories of this sub-module appear as five “islands,” individual files as “cities” within the island, and individual function definitions as “buildings.” In addition, aggregate shaded edges between cities indicates that some function in one file (yellow end) calls some function in another file (dark end). Other user-selected metrics and static or dynamic analyses may be rendered as textures, colors, and icons in this view (not shown; these elements appear when zooming in to view structures more closely than shown in Figure 3).

From Figure 3, a developer can quickly see whether his logical concept of components in the system holds. For instance, the leftmost island has only incoming edges, implying that it is indeed a reusable component. If the developer decides to make changes to the system to improve the quality or component structure, he can compare old and new visualizations to make a quick judgement. Indeed, we used our tool in this interactive fashion to create new, reusable components for this sub-module of ROSE.

## 3. Tool Implementation

We built our visualization system by combining the tools shown in Figure 4. We use ROSE [10] as the C++ front-end. ROSEVA extends the ROSE API for use within the VizzAnalyzer framework [8, 12]. ROSEVA has two main interfaces, one for the parsing of C/C++ code (source retrieval and AST construction) and one for high level anal-

yses. Since ROSE and ROSEVA are developed in C/C++ and VizzAnalyzer in Java, we use Babel [3] to connect these worlds. Finally, we use Vizz3D [7] to visualize the results.

### 3.1. ROSE

ROSE is an open infrastructure for building compiler-based source-to-source analysis and transformation tools. For C and C++, ROSE fully supports all language features, preserves all source information for use in analysis, and permits arbitrarily complex source-level translation via its rewrite system. Although research in the ROSE project emphasizes performance optimization, ROSE contains many of the components common to any compiler infrastructure, and thus supports the development of general source-based analysis and transformation tools.

### 3.2. ROSEVA

ROSEVA has been designed as a library using the ROSE API. ROSEVA has two interfaces that VizzAnalyzer accesses via Babel: *retrieval* and *analysis*. The retrieval takes the files to be parsed by ROSE as input and constructs internally an AST representation of the C/C++ source files. For user interaction, selected graphs are returned to VizzAnalyzer. These results can be visualized directly or further inspected with additional analyses.

Therefore, ROSEVA provides a second interface allowing VizzAnalyzer to access a variety of analyses on any graph produced by the frontend. Analyses results, such as CC or LOC, are fed back directly as properties to the VizzAnalyzer. These properties are used by the VizzAnalyzer to flexibly visualize any kind of program information.

### 3.3. Babel

Babel is a tool for mixing C, C++, Fortran77, Fortran90, Python, and Java in a single application. Babel is the foundation for a multi-language scientific component framework. Babel addresses the language interoperability problem using Interface Definition Language (IDL) techniques. In particular, Babel uses a Scientific Interface Definition Language (SIDL) that addresses the unique needs of parallel scientific computing.

### 3.4. VizzAnalyzer

The VizzAnalyzer framework is our composition system for reverse engineering, supporting the rapid composition of individual software reverse engineering tools by reusing arbitrary reverse engineering components. VizzAnalyzer distinguishes two domains: Program retrieval and analysis are



part of the *software analysis domain* and program visualization is part of the *information visualization domain* [8]. Each domain operates on its own program model. For instance, a model for software analysis may contain information about a program's clusters, metrics, cycles, *etc.*, while a model for information visualization contains information about the visualization of a program, such as the position or color of entities. VizzAnalyzer allows the merging of tools from both domains.

### 3.5. Vizz3D

Vizz3D is a 3D information visualization system. It presents system structure and quality information to a user in a comprehensible way and leverages the understanding of that system. Vizz3D is highly flexible and allows users to define and re-assign layout algorithms and metaphors at run-time. Hence, visualizations can be online-configured. This also enables an interactive and iterative software analysis, where appropriate views are created on demand.

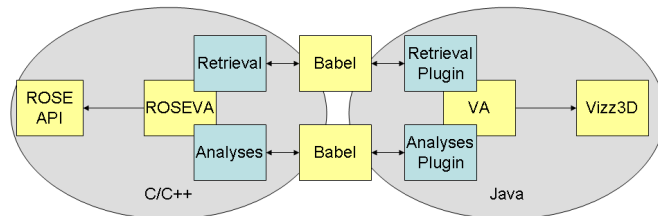


Figure 4. Visualization Tool Architecture

## 4. Summary and Future Work

In our on-going research, we are continuing to extend and to evaluate our code quality feedback tool by working with development teams. Work in the latter area is of course critical to determining just how useful our approach could be, particularly for the common development practices of HPC applications [4].

The current version of our tool reports on a broad collection of metrics and analyses. Moreover, these reports (textual, static image, and interactive visualization) can include a variety of metrics of specific interest to HPC developers. For instance, we can report static counts of floating point operations within each function, or any hardware processor counts collected at run-time *via* an interface in ROSE to the HPCToolkit [2], though we did not show these in our examples. We are also implementing analyses to extract repository information, *e.g.*, from CVS. We are actively extending the metrics and analyses.

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