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DAKOTA, A Multilevel Parallel Object-Oriented Framework for Design Optimization, Parameter Estimation, Uncertainty Quantification, and Sensitivity Analysis

Version 4.0 Developers Manual

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for Design Optimization, Parameter Estimation, Uncertainty
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Abstract

The DAKOTA (Design Analysis Kit for Optimization and Terascale Applications) toolkit provides a flexible and extensible interface between simulation codes and iterative analysis methods. DAKOTA contains algorithms for optimization with gradient and nongradient-based methods; uncertainty quantification with sampling, reliability, and stochastic finite element methods; parameter estimation with nonlinear least squares methods; and sensitivity/variance analysis with design of experiments and parameter study methods. These capabilities may be used on their own or as components within advanced strategies such as surrogate-based optimization, mixed integer nonlinear programming, or optimization under uncertainty. By employing object-oriented design to implement abstractions of the key components required for iterative systems analyses, the DAKOTA toolkit provides a flexible and extensible problem-solving environment for design and performance analysis of computational models on high performance computers.

This report serves as a developers manual for the DAKOTA software and describes the DAKOTA class hierarchies and their interrelationships. It derives directly from annotation of the actual source code and provides detailed class documentation, including all member functions and attributes.

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Chapter 1

DAKOTA Developers Manual

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1.1 Introduction

The DAKOTA (Design Analysis Kit for Optimization and Terascale Applications) toolkit provides a flexible, extensible interface between analysis codes and iteration methods. DAKOTA contains algorithms for optimization with gradient and nongradient-based methods, uncertainty quantification with sampling, reliability, and stochastic finite element methods, parameter estimation with nonlinear least squares methods, and sensitivity/variance analysis with design of experiments and parameter study capabilities. These capabilities may be used on their own or as components within advanced strategies such as surrogate-based optimization, mixed integer nonlinear programming, or optimization under uncertainty. By employing object-oriented design to implement abstractions of the key components required for iterative systems analyses, the DAKOTA toolkit provides a flexible problem-solving environment as well as a platform for rapid prototyping of new solution approaches.

The Developers Manual focuses on documentation of the class structures used by the DAKOTA system. It derives directly from annotation of the actual source code. For information on input command syntax, refer to the [Reference Manual](#), and for a tour of DAKOTA features and capabilities, refer to the Users Manual.

1.2 Overview of DAKOTA

In the DAKOTA system, the *strategy* creates and manages *iterators* and *models*. In the simplest case, the strategy creates a single iterator and a single model and executes the iterator on the model to perform a single study. In a more advanced case, a hybrid optimization strategy might manage a global optimizer operating on a low-fidelity

model in coordination with a local optimizer operating on a high-fidelity model. And on the high end, a surrogate-based optimization under uncertainty strategy would employ an uncertainty quantification iterator nested within an optimization iterator and would employ truth models layered within surrogate models. Thus, iterators and models provide both stand-alone capabilities as well as building blocks for more sophisticated studies.

A model contains a set of *variables*, an *interface*, and a set of *responses*, and the iterator operates on the model to map the variables into responses using the interface. Each of these components is a flexible abstraction with a variety of specializations for supporting different types of iterative studies. In a DAKOTA input file, the user specifies these components through strategy, method, model, variables, interface, and responses keyword specifications.

The use of class hierarchies provides a mechanism for extensibility in DAKOTA components. In each of the various class hierarchies, adding a new capability typically involves deriving a new class and providing a small number of virtual function redefinitions. These redefinitions define the coding portions specific to the new derived class, with the common portions already defined at the base class. Thus, with a small amount of new code, the existing facilities can be extended, reused, and leveraged for new purposes.

The software components are presented in the following sections using a top-down order.

1.2.1 Strategies

Class hierarchy: [Strategy](#).

Strategies provide a control layer for creation and management of iterators and models. Specific strategies include:

- [SingleMethodStrategy](#): the simplest strategy. A single iterator is run on a single model to perform a single study.
- [MultilevelOptStrategy](#): hybrid optimization using a succession of iterators employing a succession of models of varying fidelity. The best results obtained are passed from one iterator to the next.
- [SurrBasedOptStrategy](#): surrogate-based optimization. Employs a single iterator with a [SurrogateModel](#) (either data fit or hierarchical). A sequence of approximate optimizations is performed, each of which involves build, optimize, and verify steps.
- [ConcurrentStrategy](#): two similar algorithms are available: (1) multi-start iteration from several different starting points, and (2) pareto set optimization for several different multiobjective weightings. Employs a single iterator with a single model, but runs multiple instances of the iterator concurrently for different settings within the model.

1.2.2 Iterators

Class hierarchy: [Iterator](#).

The iterator hierarchy contains a variety of iterative algorithms for optimization, uncertainty quantification, non-linear least squares, design of experiments, and parameter studies. The hierarchy is divided into [Minimizer](#) and [Analyzer](#) branches. The [Minimizer](#) classes include:

- Optimization: [Optimizer](#) provides a base class for the [DOTOptimizer](#), [CONMINOptimizer](#), [NPSOLOptimizer](#), [NLPQLPOptimizer](#), and [SNLLOptimizer](#) gradient-based optimization libraries and the [COLINOptimizer](#) and [JEGAOptimizer](#) nongradient-based optimization libraries.

- Parameter estimation: [LeastSq](#) provides a base class for [NL2SOLLeastSq](#), a least-squares solver based on NL2SOL, [SNLLLeastSq](#), a Gauss-Newton least-squares solver, and [NLSSOLLeastSq](#), an SQP-based least-squares solver.

and the [Analyzer](#) classes include:

- Uncertainty quantification: [NonD](#) provides a base class for [NonDReliability](#) (reliability analysis), [NonDEvidence](#) (Dempster-Shafer Theory of Evidence), and [NonDSampling](#). [NonDSampling](#) is further specialized with the [NonDLHSSampling](#) class for latin hypercube and Monte Carlo sampling and the [NonDPCESampling](#) class for polynomial chaos expansions.
- Parameter studies and design of experiments: [PStudyDACE](#) provides a base class for [ParamStudy](#), which provides capabilities for directed parameter space interrogation, and [DDACEDesignCompExp](#) and [FSUDesignCompExp](#), which provide for parameter space exploration through design and analysis of computer experiments. [NonDLHSSampling](#) from the uncertainty quantification branch also supports a design of experiments mode.

1.2.3 Models

Class hierarchy: [Model](#).

The model classes are responsible for mapping variables into responses when an iterator makes a function evaluation request. There are several types of models, some supporting sub-iterators and sub-models for enabling layered and nested relationships. When sub-models are used, they may be of arbitrary type so that a variety of recursions are supported.

- [SingleModel](#): variables are mapped into responses using a single [Interface](#) object. No sub-iterators or sub-models are used.
- [SurrogateModel](#): variables are mapped into responses using an approximation. The approximation is built and/or corrected using data from a sub-model (the truth model) and the data may be obtained using a sub-iterator (a design of experiments iterator). [SurrogateModel](#) has two derived classes: [DataFitSurrModel](#) for data fit surrogates and [HierarchSurrModel](#) for hierarchical models of varying fidelity. The relationship of the sub-iterators and sub-models is considered to be "layered" since they are not used as part of every response evaluation on the top level model, but rather used periodically in surrogate update and verification steps.
- [NestedModel](#): variables are mapped into responses using a combination of an optional [Interface](#) and a sub-iterator/sub-model pair. The relationship of the sub-iterators and sub-models is considered to be "nested" since they are used to perform a complete iterative study as part of every response evaluation on the top level model.

1.2.4 Variables

Class hierarchy: [Variables](#).

The [Variables](#) class hierarchy manages design, uncertain, and state variable types for continuous and discrete domain types. This hierarchy is specialized according to various views of the data.

- [DistinctVariables](#): both variable and domain type distinctions are retained, i.e. separate arrays for design, uncertain, and state variables types and for continuous and discrete domains.
- [AllVariables](#): variable types are combined and domain type distinction is retained, i.e. design, uncertain, and state variable types combined into a single continuous variables array and a single discrete variables array.
- [MergedVariables](#): variable type distinction is retained and domain types are combined, i.e. continuous and discrete variables merged into continuous arrays (integrality is relaxed) for design, uncertain, and state variable types.

The variables view that is chosen depends on the type of iterative study. For design optimization and uncertainty quantification, for example, variable and domain type distinctions are important and a [DistinctVariables](#) view is used. For parameter studies and design of experiments, however, the variable type distinctions can be ignored and an [AllVariables](#) view is used.

The [Constraints](#) hierarchy manages bound, linear, and nonlinear constraints and utilizes the same specializations for managing bounds on the variables (see [DistinctConstraints](#), [AllConstraints](#), and [MergedConstraints](#)).

1.2.5 Interfaces

Class hierarchy: [Interface](#).

Interfaces provide access to simulation codes or, conversely, approximations based on simulation code data. In the simulation case, an [ApplicationInterface](#) is used. [ApplicationInterface](#) is specialized according to the simulation invocation mechanism, for which the following nonintrusive approaches

- [SysCallApplicInterface](#): the simulation is invoked using a system call (the C function `system()`). Asynchronous invocation utilizes a background system call. Utilizes the [SysCallAnalysisCode](#) class to define syntax for input filter, analysis code, output filter, or combined spawning, which in turn utilize the [CommandShell](#) utility.
- [ForkApplicInterface](#): the simulation is invoked using a fork (the `fork/exec/wait` family of functions). Asynchronous invocation utilizes a nonblocking fork. Utilizes the [ForkAnalysisCode](#) class for lower level fork operations.
- [GridApplicInterface](#): the simulation is invoked using distributed resource facilities. This capability is experimental and still under development. The design is evolving into the use of Condor and/or Globus tools.

and the following semi-intrusive approach

- [DirectFnApplicInterface](#): the simulation is linked into the DAKOTA executable and is invoked using a procedure call. Asynchronous invocations will utilize nonblocking threads (capability not yet available).

are supported. Scheduling of jobs for asynchronous local, message passing, and hybrid parallelism approaches is performed in the [ApplicationInterface](#) class, with job initiation and job capture specifics implemented in the derived classes.

In the data fit approximation case, global, multipoint, or local approximations to simulation code response data can be built and used as surrogates for the actual, expensive simulation. The interface class providing this capability is

- [ApproximationInterface](#): builds an approximation using data from a truth model and then employs the approximation for mapping variables to responses. This class contains an array of [Approximation](#) objects, one per response function, which permits the mixing of approximation types (using the [Approximation](#) derived classes: [SurfpackApproximation](#) (provides kriging, neural network, MARS, polynomial regression, and radial basis functions), [GaussProcApproximation](#), [HermiteApproximation](#), [TANA3Approximation](#), and [TaylorApproximation](#)).

Note: in the data fit approximation case, [DataFitSurrModel](#) provides the bulk of the surrogate management logic. It contains an [ApproximationInterface](#) object which provides the approximate parameter to response mappings. In the hierarchical approximation case, an [ApproximationInterface](#) object is not used since [HierarchSurrModel](#) uses low and high fidelity models to manage surrogate construction/usage.

1.2.6 Responses

Class: [Response](#).

The [Response](#) class provides an abstract data representation of response functions and their first and second derivatives (gradient vectors and Hessian matrices). These response functions can be interpreted as an objective function and constraints (optimization data set), residual functions and constraints (least squares data set), or generic response functions (uncertainty quantification data set). This class is not currently part of a class hierarchy, since the abstraction has been sufficiently general and has not required specialization.

1.3 Services

A variety of services are provided in DAKOTA for parallel computing, failure capturing, restart, graphics, etc. An overview of the classes and member functions involved in performing these services is included below.

- Multilevel parallel computing: DAKOTA supports multiple levels of nested parallelism. A strategy can manage concurrent iterators, each of which manages concurrent function evaluations, each of which manages concurrent analyses executing on multiple processors. Partitioning of these levels with MPI communicators is managed in [ParallelLibrary](#) and scheduling routines for the levels are part of [ConcurrentStrategy](#), [ApplicationInterface](#), and [ForkApplicInterface](#).
- Parsing: DAKOTA employs the Input Deck Reader (IDR) parser to retrieve information from user input files. Parsing options are processed in [CommandLineHandler](#) and parsing occurs in [ProblemDescDB::manage_inputs\(\)](#) called from [main.C](#). IDR uses the keyword handlers in the [IDRProblemDescDB](#) derived class to populate data within the [ProblemDescDB](#) base class, which maintains a [DataStrategy](#) specification and lists of [DataMethod](#), [DataModel](#), [DataVariables](#), [DataInterface](#), and [DataResponses](#) specifications. Procedures for modifying the parsing subsystem are described in [Instructions for Modifying DAKOTA's Input Specification](#).
- Failure capturing: Simulation failures can be trapped and managed using exception handling in [ApplicationInterface](#) and its derived classes.

- Restart: DAKOTA maintains a record of all function evaluations both in memory (for capturing any duplication) and on the file system (for restarting runs). Restart options are processed in [CommandLineHandler](#) and retrieved in [ParallelLibrary::specify_outputs_restart\(\)](#), restart file management occurs in [ParallelLibrary::manage_outputs_restart\(\)](#), and restart file insertions occur in [ApplicationInterface](#). The `dakota_restart_util` executable, built from `restart_util.C`, provides a variety of services for interrogating, converting, repairing, concatenating, and post-processing restart files.
- Memory management: DAKOTA employs the techniques of reference counting and representation sharing through the use of letter-envelope and handle-body idioms (Coplien, "Advanced C++"). The former idiom provides for memory efficiency and enhanced polymorphism in the following class hierarchies: [Strategy](#), [Iterator](#), [Model](#), [Variables](#), [Constraints](#), [Interface](#), [ProblemDescDB](#), and [Approximation](#). The latter idiom provides for memory efficiency in data-intensive classes which do not involve a class hierarchy. Currently, only the [Response](#) class uses this idiom. When managing reference-counted data containers (e.g., [Variables](#) or [Response](#) objects), it is important to properly manage shallow and deep copies, to allow for both efficiency and data independence as needed in a particular context.
- Graphics: DAKOTA provides 2D iteration history graphics using Motif widgets and 3D surface plotting graphics from the PLPLOT package. Graphics data can also be catalogued in a tabular data file for post-processing with 3rd party tools such as Matlab, Tecplot, etc. All of these capabilities are encapsulated within the [Graphics](#) class.

1.4 Additional Resources

Additional development resources include:

- [Recommended Practices for DAKOTA Development](#)
- [Instructions for Modifying DAKOTA's Input Specification](#)
- In addition to its normal usage as a stand-alone application, DAKOTA may be interfaced as an algorithm library as described in [Interfacing with DAKOTA as a Library](#).
- The execution of function evaluations is a core component of DAKOTA involving several class hierarchies. An overview of the classes and member functions involved in performing these evaluations is provided in [Performing Function Evaluations](#).
- Project web pages are maintained at <http://endo.sandia.gov/DAKOTA> with software specifics and documentation pointers provided at <http://endo.sandia.gov/DAKOTA/software.html>, and a list of publications provided at <http://endo.sandia.gov/DAKOTA/references.html>

Chapter 2

DAKOTA Directory Hierarchy

2.1 DAKOTA Directories

This directory hierarchy is sorted roughly, but not completely, alphabetically:

src 29

Chapter 3

DAKOTA Namespace Index

3.1 DAKOTA Namespace List

Here is a list of all documented namespaces with brief descriptions:

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Chapter 4

DAKOTA Hierarchical Index

4.1 DAKOTA Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

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Iterator	257
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NonD	365
NonDEvidence	369
NonDReliability	379
NonDSampling	395
NonDLHSSampling	374
NonDPCESampling	377
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Chapter 5

DAKOTA Class Index

5.1 DAKOTA Class List

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CommandLineHandler (Utility class for managing command line inputs to DAKOTA)	125
CommandShell (Utility class which defines convenience operators for spawning processes with system calls)	127
ConcurrentStrategy (Strategy for multi-start iteration or pareto set optimization)	129
CONMINOptimizer (Wrapper class for the CONMIN optimization library)	132
Constraints (Base class for the variable constraints class hierarchy)	140
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DataFitSurrModel (Derived model class within the surrogate model branch for managing data fit surrogates (global and local))	149

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ForkApplicInterface (Derived application interface class which spawns simulation codes using forks)	215
FSUDesignCompExp (Wrapper class for the FSUDace QMC/CVT library)	218
FunctionCompare	222
GaussProcApproximation (Derived approximation class for Gaussian Process implementation)	223
GetLongOpt (<code>GetLongOpt</code> is a general command line utility from S. Manoharan (Advanced Computer Research Institute, Lyon, France))	228
Graphics (Single interface to 2D (motif) and 3D (PLPLOT) graphics as well as tabular cataloguing of data for post-processing with Matlab, Tecplot, etc)	232
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IDRProblemDescDB (The derived input file database utilizing the IDR parser)	245
Interface (Base class for the interface class hierarchy)	248
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JEGAEvaluator (This evaluator uses Sandia National Laboratories Dakota software)	267
JEGAOptimizer (Version of Optimizer for instantiation of John Eddy's Genetic Algorithms)	275
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LeastSq (Base class for the nonlinear least squares branch of the iterator hierarchy)	287
List (Template class for the Dakota bookkeeping list)	289
Matrix (Template class for the Dakota numerical matrix)	294
MergedConstraints (Derived class within the Constraints hierarchy which employs the merged data view)	297
MergedVariables (Derived class within the Variables hierarchy which employs the merged data view)	300
Minimizer (Base class for the optimizer and least squares branches of the iterator hierarchy)	304
Model (Base class for the model class hierarchy)	311
MPIPackBuffer (Class for packing MPI message buffers)	337
MPIUnpackBuffer (Class for unpacking MPI message buffers)	340

MultilevelOptStrategy (Strategy for hybrid optimization using multiple optimizers on multiple models of varying fidelity)	343
NestedModel (Derived model class which performs a complete sub-iterator execution within every evaluation of the model)	346
NI2Misc (Auxiliary information passed to calcr and calcj via ur)	352
NL2SOLLeastSq (Wrapper class for the NL2SOL nonlinear least squares library)	353
NLPQLPOptimizer (Wrapper class for the NLPQLP optimization library, Version 2.0)	356
NLSSOLLeastSq (Wrapper class for the NLSSOL nonlinear least squares library)	362
NoDBBaseConstructor (Dummy struct for overloading constructors used in on-the-fly instantiations)	364
NonD (Base class for all nondeterministic iterators (the DAKOTA/UQ branch))	365
NonDEvidence (Class for the Dempster-Shafer Evidence Theory methods within DAKOTA/UQ)	369
NonDLHSSampling (Performs LHS and Monte Carlo sampling for uncertainty quantification)	374
NonDPCESampling (Stochastic finite element approach to uncertainty quantification using polynomial chaos expansions)	377
NonDReliability (Class for the reliability methods within DAKOTA/UQ)	379
NonDSampling (Base class for common code between NonDLHSSampling and NonDPCESampling)	395
NPSOLOptimizer (Wrapper class for the NPSOL optimization library)	400
Optimizer (Base class for the optimizer branch of the iterator hierarchy)	403
ParallelConfiguration (Container class for a set of ParallelLevel list iterators that collectively identify a particular multilevel parallel configuration)	406
ParallelLevel (Container class for the data associated with a single level of communicator partitioning)	408
ParallelLibrary (Class for partitioning multiple levels of parallelism and managing message passing within these levels)	411
ParamResponsePair (Container class for a variables object, a response object, and an evaluation id)	422
ParamStudy (Class for vector, list, centered, and multidimensional parameter studies)	426
ProblemDescDB (The database containing information parsed from the DAKOTA input file)	429
PStudyDACE (Base class for managing common aspects of parameter studies and design of experiments methods)	437
Response (Container class for response functions and their derivatives. Response provides the handle class)	440
ResponseRep (Container class for response functions and their derivatives. ResponseRep provides the body class)	444
SingleMethodStrategy (Simple fall-through strategy for running a single iterator on a single model)	450
SingleModel (Derived model class which utilizes a single interface to map variables into responses)	452
SNLLBase (Base class for OPT++ optimization and least squares methods)	455
SNLLLeastSq (Wrapper class for the OPT++ optimization library)	458
SNLLOptimizer (Wrapper class for the OPT++ optimization library)	462
SOLBase (Base class for Stanford SOL software)	468
SortCompare	471
Strategy (Base class for the strategy class hierarchy)	472
String (Dakota::String class, used as main string class for Dakota)	477
SurfpackApproximation (Derived approximation class for Surfpack approximation classes. Interface between Surfpack and Dakota)	480
SurrBasedOptStrategy (Strategy for provably-convergent surrogate-based optimization)	484
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TANA3Approximation (Derived approximation class for TANA-3 two-point exponential approximation (a multipoint approximation))	509
TaylorApproximation (Derived approximation class for first- or second-order Taylor series (a local approximation))	512
Variables (Base class for the variables class hierarchy)	514
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Chapter 6

DAKOTA File Index

6.1 DAKOTA File List

Here is a list of all documented files with brief descriptions:

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keywordtable.C (File containing keywords for the strategy, method, model, variables, interface, and responses input specifications from dakota.input.spec)	533
main.C (File containing the main program for DAKOTA)	534
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Chapter 7

DAKOTA Page Index

7.1 DAKOTA Related Pages

Here is a list of all related documentation pages:

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Instructions for Modifying DAKOTA's Input Specification	545
Interfacing with DAKOTA as a Library	553
Performing Function Evaluations	561
Todo List	563

Chapter 8

DAKOTA Directory Documentation

8.1 /home/mseldre/dev/Dakota/src/ Directory Reference

Files

- file **AllConstraints.C**
- file **AllConstraints.H**
- file **AllVariables.C**
- file **AllVariables.H**
- file **AnalysisCode.C**
- file **AnalysisCode.H**
- file **ApplicationInterface.C**
- file **ApplicationInterface.H**
- file **ApproximationInterface.C**
- file **ApproximationInterface.H**
- file **COLINApplication.C**
- file **COLINApplication.H**
- file **COLINOptimizer.H**
- file **CommandLineHandler.C**
- file **CommandLineHandler.H**
- file **CommandShell.C**
- file **CommandShell.H**
- file **ConcurrentStrategy.C**
- file **ConcurrentStrategy.H**
- file **CONMINOptimizer.C**
- file **CONMINOptimizer.H**
- file **CtelRegExp.C**
- file **CtelRegExp.H**
- file **DakotaActiveSet.C**

- file **DakotaActiveSet.H**
- file **DakotaAnalyzer.C**
- file **DakotaAnalyzer.H**
- file **DakotaApproximation.C**
- file **DakotaApproximation.H**
- file **DakotaArray.H**
- file **DakotaBaseVector.H**
- file **DakotaBinStream.C**
- file **DakotaBinStream.H**
- file **DakotaConstraints.C**
- file **DakotaConstraints.H**
- file **DakotaGraphics.C**
- file **DakotaGraphics.H**
- file **DakotaInterface.C**
- file **DakotaInterface.H**
- file **DakotaIterator.C**
- file **DakotaIterator.H**
- file **DakotaLeastSq.C**
- file **DakotaLeastSq.H**
- file **DakotaList.H**
- file **DakotaMatrix.H**
- file **DakotaMinimizer.C**
- file **DakotaMinimizer.H**
- file **DakotaModel.C**
- file **DakotaModel.H**
- file **DakotaNonD.C**
- file **DakotaNonD.H**
- file **DakotaOptimizer.C**
- file **DakotaOptimizer.H**
- file **DakotaPStudyDACE.C**
- file **DakotaPStudyDACE.H**
- file **DakotaResponse.C**
- file **DakotaResponse.H**
- file **DakotaStrategy.C**
- file **DakotaStrategy.H**
- file **DakotaString.C**
- file **DakotaString.H**
- file **DakotaVariables.C**
- file **DakotaVariables.H**
- file **DakotaVector.H**
- file **data_types.C**
- file **data_types.h**
- file **DataFitSurrModel.C**
- file **DataFitSurrModel.H**
- file **DataInterface.C**
- file **DataInterface.H**

- file **DataMethod.C**
- file **DataMethod.H**
- file **DataModel.C**
- file **DataModel.H**
- file **DataResponses.C**
- file **DataResponses.H**
- file **DataStrategy.C**
- file **DataStrategy.H**
- file **DataVariables.C**
- file **DataVariables.H**
- file **DDACEDesignCompExp.C**
- file **DDACEDesignCompExp.H**
- file **DirectFnApplicInterface.C**
- file **DirectFnApplicInterface.H**
- file **DistinctConstraints.C**
- file **DistinctConstraints.H**
- file **DistinctVariables.C**
- file **DistinctVariables.H**
- file **DOTOptimizer.C**
- file **DOTOptimizer.H**
- file **ForkAnalysisCode.C**
- file **ForkAnalysisCode.H**
- file **ForkApplicInterface.C**
- file **ForkApplicInterface.H**
- file **FSUDesignCompExp.C**
- file **FSUDesignCompExp.H**
- file **GaussProcApproximation.C**
- file **GaussProcApproximation.H**
- file **global_defs.C**
- file **global_defs.h**
- file **GridApplicInterface.C**
- file **GridApplicInterface.H**
- file **HermiteApproximation.C**
- file **HermiteApproximation.H**
- file **HermiteChaos.C**
- file **HermiteChaos.H**
- file **HierarchSurrModel.C**
- file **HierarchSurrModel.H**
- file **IDRProblemDescDB.C**
- file **IDRProblemDescDB.H**
- file [JEGAEvaluator.C](#)
 - *Contains the implementation of the JEGAEvaluator class.*
- file [JEGAEvaluator.H](#)
 - *Contains the definition of the JEGAEvaluator class.*

- file [JEGAOptimizer.C](#)
Contains the implementation of the JEGAOptimizer class.
- file [JEGAOptimizer.H](#)
Contains the definition of the JEGAOptimizer class.
- file [keywordtable.C](#)
file containing keywords for the strategy, method, model, variables, interface, and responses input specifications from `dakota.input.spec`
- file **LatinHypercube.C**
- file **LatinHypercube.H**
- file **LHSInput.C**
- file **LHSInput.H**
- file [main.C](#)
file containing the main program for DAKOTA
- file **MergedConstraints.C**
- file **MergedConstraints.H**
- file **MergedVariables.C**
- file **MergedVariables.H**
- file **MPIPackBuffer.C**
- file **MPIPackBuffer.H**
- file **MultilevelOptStrategy.C**
- file **MultilevelOptStrategy.H**
- file **NestedModel.C**
- file **NestedModel.H**
- file **NL2SOLLeastSq.C**
- file **NL2SOLLeastSq.H**
- file **NLPQLPOptimizer.C**
- file **NLPQLPOptimizer.H**
- file **NLSSOLLeastSq.C**
- file **NLSSOLLeastSq.H**
- file **NonDEvidence.C**
- file **NonDEvidence.H**
- file **NonDLHSSampling.C**
- file **NonDLHSSampling.H**
- file **NonDPCESampling.C**
- file **NonDPCESampling.H**
- file **NonDReliability.C**
- file **NonDReliability.H**
- file **NonDSampling.C**
- file **NonDSampling.H**
- file **NPSOLOptimizer.C**
- file **NPSOLOptimizer.H**
- file **ParallelLibrary.C**

- file **ParallelLibrary.H**
- file **ParamResponsePair.C**
- file **ParamResponsePair.H**
- file **ParamStudy.C**
- file **ParamStudy.H**
- file **PluginDirectFnApplicInterface.C**
- file **PluginDirectFnApplicInterface.H**
- file **ProblemDescDB.C**
- file **ProblemDescDB.H**
- file **regexp.h**
- file **restart_util.C**
 - file containing the DAKOTA restart utility main program*

- file **SingleMethodStrategy.C**
- file **SingleMethodStrategy.H**
- file **SingleModel.C**
- file **SingleModel.H**
- file **SNLLBase.C**
- file **SNLLBase.H**
- file **SNLLLeastSq.C**
- file **SNLLLeastSq.H**
- file **SNLLOptimizer.C**
- file **SNLLOptimizer.H**
- file **SOLBase.C**
- file **SOLBase.H**
- file **SurfpackApproximation.C**
- file **SurfpackApproximation.H**
- file **SurrBasedOptStrategy.C**
- file **SurrBasedOptStrategy.H**
- file **SurrogateModel.C**
- file **SurrogateModel.H**
- file **SysCallAnalysisCode.C**
- file **SysCallAnalysisCode.H**
- file **SysCallApplicInterface.C**
- file **SysCallApplicInterface.H**
- file **system_defs.h**
- file **TANA3Approximation.C**
- file **TANA3Approximation.H**
- file **TaylorApproximation.C**
- file **TaylorApproximation.H**
- file **template_defs.h**
- file **VariablesUtil.H**

Chapter 9

DAKOTA Namespace Documentation

9.1 Dakota Namespace Reference

The primary namespace for DAKOTA.

Classes

- class [AllConstraints](#)
Derived class within the [Constraints](#) hierarchy which employs the all data view.
- class [AllVariables](#)
Derived class within the [Variables](#) hierarchy which employs the all data view.
- class [AnalysisCode](#)
Base class providing common functionality for derived classes ([SysCallAnalysisCode](#) and [ForkAnalysisCode](#)) which spawn separate processes for managing simulations.
- class [ApplicationInterface](#)
Derived class within the interface class hierarchy for supporting interfaces to simulation codes.
- class [ApproximationInterface](#)
Derived class within the interface class hierarchy for supporting approximations to simulation-based results.
- class [COLINApplication](#)
- class [COLINOptimizer](#)
Wrapper class for optimizers defined using COLIN.
- class [GetLongOpt](#)

GetLongOpt is a general command line utility from S. Manoharan (Advanced Computer Research Institute, Lyon, France).

- class [CommandLineHandler](#)
Utility class for managing command line inputs to DAKOTA.
- class [CommandShell](#)
Utility class which defines convenience operators for spawning processes with system calls.
- class [ConcurrentStrategy](#)
Strategy for multi-start iteration or pareto set optimization.
- class [CONMINOptimizer](#)
Wrapper class for the CONMIN optimization library.
- class [ActiveSet](#)
Container class for active set tracking information. Contains the active set request vector and the derivative variables vector.
- class [Analyzer](#)
Base class for [NonD](#), [DACE](#), and [ParamStudy](#) branches of the iterator hierarchy.
- class [SurrogateDataPoint](#)
Container class encapsulating basic parameter and response data for defining a "truth" data point.
- class [SurrogateDataPointRep](#)
The representation of a surrogate data point. This representation, or body, may be shared by multiple [SurrogateDataPoint](#) handle instances.
- class [Approximation](#)
Base class for the approximation class hierarchy.
- class [Array](#)
Template class for the [Dakota](#) bookkeeping array.
- class [BaseVector](#)
Base class for the [Dakota::Matrix](#) and [Dakota::Vector](#) classes.
- class [BiStream](#)
The binary input stream class. Overloads the >> operator for all data types.
- class [BoStream](#)
The binary output stream class. Overloads the << operator for all data types.
- class [Constraints](#)
Base class for the variable constraints class hierarchy.

- class [Graphics](#)
The [Graphics](#) class provides a single interface to 2D (motif) and 3D (PLPLOT) graphics as well as tabular cataloging of data for post-processing with Matlab, Tecplot, etc.
- class [Interface](#)
Base class for the interface class hierarchy.
- class [Iterator](#)
Base class for the iterator class hierarchy.
- class [LeastSq](#)
Base class for the nonlinear least squares branch of the iterator hierarchy.
- class [List](#)
Template class for the [Dakota](#) bookkeeping list.
- class [FunctionCompare](#)
- class [SortCompare](#)
- class [Matrix](#)
Template class for the [Dakota](#) numerical matrix.
- class [Minimizer](#)
Base class for the optimizer and least squares branches of the iterator hierarchy.
- class [Model](#)
Base class for the model class hierarchy.
- class [NonD](#)
Base class for all nondeterministic iterators (the DAKOTA/UQ branch).
- class [Optimizer](#)
Base class for the optimizer branch of the iterator hierarchy.
- class [PStudyDACE](#)
Base class for managing common aspects of parameter studies and design of experiments methods.
- class [Response](#)
Container class for response functions and their derivatives. [Response](#) provides the handle class.
- class [ResponseRep](#)
Container class for response functions and their derivatives. [ResponseRep](#) provides the body class.
- class [Strategy](#)
Base class for the strategy class hierarchy.
- class [String](#)

Dakota::String class, used as main string class for *Dakota*.

- class [Variables](#)
Base class for the variables class hierarchy.
- class [Vector](#)
*Template class for the *Dakota* numerical vector.*
- class [DataFitSurrModel](#)
Derived model class within the surrogate model branch for managing data fit surrogates (global and local).
- class [DataInterface](#)
Container class for interface specification data.
- class [DataMethod](#)
Container class for method specification data.
- class [DataModel](#)
Container class for model specification data.
- class [DataResponses](#)
Container class for responses specification data.
- class [DataStrategy](#)
Container class for strategy specification data.
- class [DataVariables](#)
Container class for variables specification data.
- class [DDACEDesignCompExp](#)
Wrapper class for the DDACE design of experiments library.
- class [DirectFnApplicInterface](#)
Derived application interface class which spawns simulation codes and testers using direct procedure calls.
- class [DistinctConstraints](#)
*Derived class within the *Constraints* hierarchy which employs the default data view (no variable or domain type array merging).*
- class [DistinctVariables](#)
*Derived class within the *Variables* hierarchy which employs the default data view (no variable or domain type array merging).*
- class [DOTOptimizer](#)
Wrapper class for the DOT optimization library.

- class [ForkAnalysisCode](#)
Derived class in the [AnalysisCode](#) class hierarchy which spawns simulations using forks.
- class [ForkApplicInterface](#)
Derived application interface class which spawns simulation codes using forks.
- class [FSUDesignCompExp](#)
Wrapper class for the FSUDace QMC/CVT library.
- class [GaussProcApproximation](#)
Derived approximation class for Gaussian Process implementation.
- struct [BaseConstructor](#)
Dummy struct for overloading letter-envelope constructors.
- struct [NoDBBaseConstructor](#)
Dummy struct for overloading constructors used in on-the-fly instantiations.
- class [GridApplicInterface](#)
Derived application interface class which spawns simulation codes using grid services such as Condor or Globus.
- class [HermiteApproximation](#)
Derived approximation class for Hermite polynomials (global approximation).
- class [HierarchSurrModel](#)
Derived model class within the surrogate model branch for managing hierarchical surrogates (models of varying fidelity).
- class [IDRProblemDescDB](#)
The derived input file database utilizing the IDR parser.
- class [JEGAEvaluator](#)
This evaluator uses Sandia National Laboratories [Dakota](#) software.
- class [JEGAOptimizer](#)
Version of [Optimizer](#) for instantiation of John Eddy's Genetic Algorithms.
- class [MergedConstraints](#)
Derived class within the [Constraints](#) hierarchy which employs the merged data view.
- class [MergedVariables](#)
Derived class within the [Variables](#) hierarchy which employs the merged data view.
- class [MPIPackBuffer](#)
Class for packing MPI message buffers.

- class [MPIUnpackBuffer](#)
Class for unpacking MPI message buffers.
- class [MultilevelOptStrategy](#)
Strategy for hybrid optimization using multiple optimizers on multiple models of varying fidelity.
- class [NestedModel](#)
Derived model class which performs a complete sub-iterator execution within every evaluation of the model.
- struct [NI2Misc](#)
Auxiliary information passed to `calcr` and `calcj` via `ur`.
- class [NL2SOLLeastSq](#)
Wrapper class for the NL2SOL nonlinear least squares library.
- class [NLPQLPOptimizer](#)
Wrapper class for the NLPQLP optimization library, Version 2.0.
- class [NLSSOLLeastSq](#)
Wrapper class for the NLSSOL nonlinear least squares library.
- class [NonDEvidence](#)
Class for the Dempster-Shafer Evidence Theory methods within DAKOTA/UQ.
- class [NonDLHSSampling](#)
Performs LHS and Monte Carlo sampling for uncertainty quantification.
- class [NonDPCESampling](#)
Stochastic finite element approach to uncertainty quantification using polynomial chaos expansions.
- class [NonDReliability](#)
Class for the reliability methods within DAKOTA/UQ.
- class [NonDSampling](#)
Base class for common code between [NonDLHSSampling](#) and [NonDPCESampling](#).
- class [NPSOLOptimizer](#)
Wrapper class for the NPSOL optimization library.
- class [ParallelLevel](#)
Container class for the data associated with a single level of communicator partitioning.
- class [ParallelConfiguration](#)
Container class for a set of [ParallelLevel](#) list iterators that collectively identify a particular multilevel parallel configuration.

- class [ParallelLibrary](#)
Class for partitioning multiple levels of parallelism and managing message passing within these levels.
- class [ParamResponsePair](#)
Container class for a variables object, a response object, and an evaluation id.
- class [ParamStudy](#)
Class for vector, list, centered, and multidimensional parameter studies.
- class [ProblemDescDB](#)
The database containing information parsed from the DAKOTA input file.
- class [SingleMethodStrategy](#)
Simple fall-through strategy for running a single iterator on a single model.
- class [SingleModel](#)
Derived model class which utilizes a single interface to map variables into responses.
- class [SNLLBase](#)
Base class for OPT++ optimization and least squares methods.
- class [SNLLLeastSq](#)
Wrapper class for the OPT++ optimization library.
- class [SNLLOptimizer](#)
Wrapper class for the OPT++ optimization library.
- class [SOLBase](#)
Base class for Stanford SOL software.
- class [SurfpackApproximation](#)
Derived approximation class for Surfpack approximation classes. [Interface](#) between Surfpack and [Dakota](#).
- class [SurrBasedOptStrategy](#)
[Strategy](#) for provably-convergent surrogate-based optimization.
- class [SurrogateModel](#)
Base class for surrogate models ([DataFitSurrModel](#) and [HierarchSurrModel](#)).
- class [SysCallAnalysisCode](#)
Derived class in the [AnalysisCode](#) class hierarchy which spawns simulations using system calls.
- class [SysCallApplicInterface](#)
Derived application interface class which spawns simulation codes using system calls.
- class [TANA3Approximation](#)

Derived approximation class for TANA-3 two-point exponential approximation (a multipoint approximation).

- class [TaylorApproximation](#)

Derived approximation class for first- or second-order Taylor series (a local approximation).

- class [VariablesUtil](#)

Utility class for the [Variables](#) and [Constraints](#) hierarchies which provides convenience functions for variable vectors and label arrays for combining design, uncertain, and state variable types and merging continuous and discrete variable domains.

Typedefs

- typedef [Vector](#)< Real > **RealVector**
- typedef [Vector](#)< int > **IntVector**
- typedef [BaseVector](#)< Real > **RealBaseVector**
- typedef [Matrix](#)< Real > **RealMatrix**
- typedef [Matrix](#)< int > **IntMatrix**
- typedef [Array](#)< Real > **RealArray**
- typedef [Array](#)< int > **IntArray**
- typedef [Array](#)< size_t > **SizetArray**
- typedef [Array](#)< String > **StringArray**
- typedef [Array](#)< [StringArray](#) > **String2DArray**
- typedef [Array](#)< [RealVector](#) > **RealVectorArray**
- typedef [Array](#)< [RealVectorArray](#) > **RealVector2DArray**
- typedef [Array](#)< [RealBaseVector](#) > **RealBaseVectorArray**
- typedef [Array](#)< [RealMatrix](#) > **RealMatrixArray**
- typedef [Array](#)< [Variables](#) > **VariablesArray**
- typedef [Array](#)< [Response](#) > **ResponseArray**
- typedef [Array](#)< [Model](#) > **ModelArray**
- typedef [Array](#)< [Iterator](#) > **IteratorArray**
- typedef [Array](#)< [ParamResponsePair](#) > **PRPArray**
- typedef [List](#)< bool > **BoolList**
- typedef [List](#)< int > **IntList**
- typedef [List](#)< size_t > **SizetList**
- typedef [List](#)< Real > **RealList**
- typedef [List](#)< String > **StringList**
- typedef [List](#)< [RealVector](#) > **RealVectorList**
- typedef [List](#)< [Variables](#) > **VariablesList**
- typedef [List](#)< [Interface](#) > **InterfaceList**
- typedef [List](#)< [Response](#) > **ResponseList**
- typedef [List](#)< [Model](#) > **ModelList**
- typedef [List](#)< [Iterator](#) > **IteratorList**
- typedef [List](#)< [ParamResponsePair](#) > **PRPList**
- typedef std::set< int > **IntSet**
- typedef std::map< int, short > **IntShortMap**

- typedef std::map< int, [RealVector](#) > **IntRealVectorMap**
- typedef std::map< int, [Response](#) > **IntResponseMap**
- typedef IntList::iterator **ILIter**
- typedef IntList::const_iterator **ILCIter**
- typedef SizerList::iterator **StLIter**
- typedef SizerList::const_iterator **StLCIter**
- typedef RealList::iterator **RLIter**
- typedef RealList::const_iterator **RLCIter**
- typedef StringList::iterator **StringLIter**
- typedef StringList::const_iterator **StringLCIter**
- typedef RealVectorList::iterator **RVLIter**
- typedef RealVectorList::const_iterator **RVLCIter**
- typedef VariablesList::iterator **VarsLIter**
- typedef InterfaceList::iterator **InterfLIter**
- typedef ResponseList::iterator **RespLIter**
- typedef ModelList::iterator **ModelLIter**
- typedef IteratorList::iterator **IterLIter**
- typedef PRPLList::iterator **PRPLIter**
- typedef [List](#)< [ParallelLevel](#) >::iterator **ParLevLIter**
- typedef [List](#)< [ParallelConfiguration](#) >::iterator **ParConfigLIter**
- typedef IntSet::iterator **ISIter**
- typedef IntShortMap::iterator **IntShMIter**
- typedef IntRealVectorMap::iterator **IntRVMIter**
- typedef IntResponseMap::iterator **IntRespMIter**
- typedef IntResponseMap::const_iterator **IntRespMCIter**
- typedef int(* **start_grid_computing_t**)(char *analysis_driver_script, char *params_file, char *results_file)
- typedef int(* **perform_analysis_t**)(char *iteration_num)
- typedef int>(* **get_jobs_completed_t**)()
- typedef int(* **stop_grid_computing_t**)()
- typedef unsigned char **u_char**
- typedef unsigned short **u_short**
- typedef unsigned int **u_int**
- typedef unsigned long **u_long**
- typedef long long **long_long**
- typedef void(* **Calcrj**)(int *n, int *p, Real *x, int *nf, Real *r, int *ui, void *ur, Vf vf)
- typedef void(* **Vf**)()

Enumerations

- enum **LHSNames** {
NORMAL, LOGNORMAL, UNIFORM, LOGUNIFORM,
WEIBULL, CONSTANT, USERDEFINED }

- enum {
N_MEAN, N_STD_DEV, N_LWR_BND, N_UPR_BND,
LN_MEAN, LN_STD_DEV, LN_ERR_FACT, LN_LWR_BND,
LN_UPR_BND, U_LWR_BND, U_UPR_BND, LU_LWR_BND,
LU_UPR_BND, T_MODE, T_LWR_BND, T_UPR_BND,
B_ALPHA, B_BETA, B_LWR_BND, B_UPR_BND,
GA_ALPHA, GA_BETA, GU_ALPHA, GU_BETA,
F_ALPHA, F_BETA, W_ALPHA, W_BETA }
- enum {
NORMAL, LOGNORMAL, UNIFORM, LOGUNIFORM,
TRIANGULAR, BETA, GAMMA, GUMBEL,
FRECHET, WEIBULL }
- enum {
MV, AMV_X, AMV_U, AMV_PLUS_X,
AMV_PLUS_U, TANA_X, TANA_U, NO_APPROX }
- enum **EvalType** { **NLFEvaluator, CONEvaluator** }
- enum { **NONE = 0, HOMOTOPY = 1, COMPOSITE_STEP = 2** }
- enum { **BASIC_PENALTY, ADAPTIVE_PENALTY, BASIC_LAGRANGIAN, AUGMENTED_-**
LAGRANGIAN }
- enum { **FILTER, TR_RATIO** }
- enum {
EMPTY, MERGED_ALL, MIXED_ALL, MERGED_DISTINCT_DESIGN,
MERGED_DISTINCT_UNCERTAIN, MERGED_DISTINCT_STATE, MIXED_DISTINCT_-
DESIGN, MIXED_DISTINCT_UNCERTAIN,
MIXED_DISTINCT_STATE }

Functions

- bool **operator==** (const [AllVariables](#) &vars1, const [AllVariables](#) &vars2)
equality operator
- template<> void [COLINOptimizer](#)< [coliny::DIRECT](#) >::**set_method_parameters** (void)

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- template<> void [COLINOptimizer](#)< [coliny::Cobyla](#) >::**set_method_parameters** (void)
- template<> void [COLINOptimizer](#)< [coliny::APPS](#) >::**set_method_parameters** (void)
- template<> void [COLINOptimizer](#)< [coliny::PatternSearch](#) >::**set_runtime_parameters** ()
- template<> void [COLINOptimizer](#)< [coliny::PatternSearch](#) >::**set_method_parameters** (void)
- template<> void [COLINOptimizer](#)< [coliny::SolisWets](#) >::**set_method_parameters** (void)
- template<> void [COLINOptimizer](#)< [coliny::EAminlp](#) >::**set_method_parameters** (void)
- [CommandShell](#) & **flush** ([CommandShell](#) &shell)

convenient shell manipulator function to "flush" the shell

- `bool operator==` (const [ActiveSet](#) &set1, const [ActiveSet](#) &set2)
equality operator
- `istream & operator>>` (istream &s, [ActiveSet](#) &set)
istream extraction operator for [ActiveSet](#). Calls read(istream&).
- `ostream & operator<<` (ostream &s, const [ActiveSet](#) &set)
ostream insertion operator for [ActiveSet](#). Calls write(ostream&).
- `BiStream & operator>>` ([BiStream](#) &s, [ActiveSet](#) &set)
[BiStream](#) extraction operator for [ActiveSet](#). Calls read(BiStream&).
- `BoStream & operator<<` ([BoStream](#) &s, const [ActiveSet](#) &set)
[BoStream](#) insertion operator for [ActiveSet](#). Calls write(BoStream&).
- `MPIUnpackBuffer & operator>>` ([MPIUnpackBuffer](#) &s, [ActiveSet](#) &set)
[MPIUnpackBuffer](#) extraction operator for [ActiveSet](#). Calls read(MPIUnpackBuffer&).
- `MPIPackBuffer & operator<<` ([MPIPackBuffer](#) &s, const [ActiveSet](#) &set)
[MPIPackBuffer](#) insertion operator for [ActiveSet](#). Calls write(MPIPackBuffer&).
- `bool operator!=` (const [ActiveSet](#) &set1, const [ActiveSet](#) &set2)
inequality operator
- `template<class T> istream & operator>>` (istream &s, [Array](#)< T > &data)
global istream extraction operator for [Vector](#)
- `template<class T> ostream & operator<<` (ostream &s, const [Array](#)< T > &data)
global ostream insertion operator for [Array](#)
- `template<class T> BiStream & operator>>` ([BiStream](#) &s, [Array](#)< T > &data)
global [BiStream](#) extraction operator for [Array](#)
- `template<class T> BoStream & operator<<` ([BoStream](#) &s, const [Array](#)< T > &data)
global [BoStream](#) insertion operator for [Array](#)
- `template<class T> MPIUnpackBuffer & operator>>` ([MPIUnpackBuffer](#) &s, [Array](#)< T > &data)
global [MPIUnpackBuffer](#) extraction operator for [Array](#)
- `template<class T> MPIPackBuffer & operator<<` ([MPIPackBuffer](#) &s, const [Array](#)< T > &data)
global [MPIPackBuffer](#) insertion operator for [Array](#)
- `istream & operator>>` (istream &s, [Constraints](#) &con)
istream extraction operator for [Constraints](#)

- ostream & operator<< (ostream &s, const [Constraints](#) &con)
ostream insertion operator for [Constraints](#)
- bool [interface_id_compare](#) (const [Interface](#) &interface, const void *id)
global comparison function for [Interface](#)
- bool [method_id_compare](#) (const [Iterator](#) &iterator, const void *id)
global comparison function for [Iterator](#)
- template<class T> ostream & operator<< (ostream &s, const [List](#)< T > &data)
global ostream insertion operator for [List](#)
- template<class T> [MPIUnpackBuffer](#) & operator>> ([MPIUnpackBuffer](#) &s, [List](#)< T > &data)
global [MPIUnpackBuffer](#) extraction operator for [List](#)
- template<class T> [MPIPackBuffer](#) & operator<< ([MPIPackBuffer](#) &s, const [List](#)< T > &data)
global [MPIPackBuffer](#) insertion operator for [List](#)
- template<class T> istream & operator>> (istream &s, [Matrix](#)< T > &data)
global istream extraction operator for [Matrix](#)
- template<class T> ostream & operator<< (ostream &s, const [Matrix](#)< T > &data)
global ostream insertion operator for [Matrix](#)
- template<class T> [MPIUnpackBuffer](#) & operator>> ([MPIUnpackBuffer](#) &s, [Matrix](#)< T > &data)
global [MPIUnpackBuffer](#) extraction operator for [Matrix](#)
- template<class T> [MPIPackBuffer](#) & operator<< ([MPIPackBuffer](#) &s, const [Matrix](#)< T > &data)
global [MPIPackBuffer](#) insertion operator for [Matrix](#)
- bool [model_id_compare](#) (const [Model](#) &model, const void *id)
global comparison function for [Model](#)
- bool operator== (const [ResponseRep](#) &rep1, const [ResponseRep](#) &rep2)
equality operator
- bool [responses_id_compare](#) (const [Response](#) &resp, const void *id)
global comparison function for [Response](#)
- istream & operator>> (istream &s, [Response](#) &response)
istream extraction operator for [Response](#). Calls read(istream&).
- ostream & operator<< (ostream &s, const [Response](#) &response)
ostream insertion operator for [Response](#). Calls write(istream&).

- **BiStream & operator>>** (BiStream &s, Response &response)
BiStream extraction operator for *Response*. Calls *read(BiStream&)*.
- **BoStream & operator<<** (BoStream &s, const Response &response)
BoStream insertion operator for *Response*. Calls *write(BoStream&)*.
- **MPIUnpackBuffer & operator>>** (MPIUnpackBuffer &s, Response &response)
MPIUnpackBuffer extraction operator for *Response*. Calls *read(MPIUnpackBuffer&)*.
- **MPIPackBuffer & operator<<** (MPIPackBuffer &s, const Response &response)
MPIPackBuffer insertion operator for *Response*. Calls *write(MPIPackBuffer&)*.
- **bool operator==** (const Response &resp1, const Response &resp2)
equality operator
- **bool operator!=** (const Response &resp1, const Response &resp2)
inequality operator
- **MPIPackBuffer & operator<<** (MPIPackBuffer &s, const String &data)
Reads String from buffer.
- **MPIUnpackBuffer & operator>>** (MPIUnpackBuffer &s, String &data)
Writes String to buffer.
- **String operator+** (const String &s1, const String &s2)
Concatenate two Strings and return the resulting *String*.
- **String operator+** (const char *s1, const String &s2)
Append a String to a *char** and return the resulting *String*.
- **String operator+** (const String &s1, const char *s2)
*Append a char** to a *String* and return the resulting *String*.
- **String operator+** (const DAKOTA_BASE_STRING &s1, const String &s2)
Append a String to a *DAKOTA_BASE_STRING* and return the resulting *String*.
- **String operator+** (const String &s1, const DAKOTA_BASE_STRING &s2)
Append a DAKOTA_BASE_STRING to a *String* and return the resulting *String*.
- **String toUpper** (const String &str)
Returns a String converted to upper case. Calls *String::upper()*.
- **String toLower** (const String &str)
Returns a String converted to lower case. Calls *String::lower()*.
- **bool operator==** (const Variables &vars1, const Variables &vars2)

equality operator

- bool `variables_id_compare` (const `Variables` &vars, const void *id)
global comparison function for `Variables`
- `istream` & `operator>>` (`istream` &s, `Variables` &vars)
istream extraction operator for `Variables`.
- `ostream` & `operator<<` (`ostream` &s, const `Variables` &vars)
ostream insertion operator for `Variables`.
- `BiStream` & `operator>>` (`BiStream` &s, `Variables` &vars)
`BiStream` extraction operator for `Variables`.
- `BoStream` & `operator<<` (`BoStream` &s, const `Variables` &vars)
`BoStream` insertion operator for `Variables`.
- `MPIUnpackBuffer` & `operator>>` (`MPIUnpackBuffer` &s, `Variables` &vars)
`MPIUnpackBuffer` extraction operator for `Variables`.
- `MPIPackBuffer` & `operator<<` (`MPIPackBuffer` &s, const `Variables` &vars)
`MPIPackBuffer` insertion operator for `Variables`.
- bool `operator!=` (const `Variables` &vars1, const `Variables` &vars2)
inequality operator
- template<class T> `istream` & `operator>>` (`istream` &s, `Vector`< T > &data)
global istream extraction operator for `Vector`
- template<class T> `ostream` & `operator<<` (`ostream` &s, const `Vector`< T > &data)
global ostream insertion operator for `Vector`
- template<class T> `MPIUnpackBuffer` & `operator>>` (`MPIUnpackBuffer` &s, `Vector`< T > &data)
global `MPIUnpackBuffer` extraction operator for `Vector`
- template<class T> `MPIPackBuffer` & `operator<<` (`MPIPackBuffer` &s, const `Vector`< T > &data)
global `MPIPackBuffer` insertion operator for `Vector`
- bool `operator==` (const `RealVector` &drv1, const `RealVector` &drv2)
equality operator for `RealVector`
- bool `operator==` (const `IntVector` &div1, const `IntVector` &div2)
equality operator for `IntVector`
- bool `operator==` (const `IntArray` &dia1, const `IntArray` &dia2)
equality operator for `IntArray`

- `bool operator==(const RealMatrix &drm1, const RealMatrix &drm2)`
equality operator for RealMatrix
- `bool operator==(const RealMatrixArray &drma1, const RealMatrixArray &drma2)`
equality operator for RealMatrixArray
- `bool operator==(const StringArray &dsa1, const StringArray &dsa2)`
equality operator for StringArray
- `void copy_data(const NEWMAT::ColumnVector &cv, RealBaseVector &drbv)`
copy NEWMAT::ColumnVector to RealBaseVector
- `void copy_data(const RealBaseVector &drbv, NEWMAT::ColumnVector &cv)`
copy RealBaseVector to NEWMAT::ColumnVector
- `void copy_data(const RealArray &dra, NEWMAT::ColumnVector &cv)`
copy RealArray to NEWMAT::ColumnVector
- `void copy_data(const RealMatrix &drm, NEWMAT::SymmetricMatrix &sm)`
copy RealMatrix to NEWMAT::SymmetricMatrix
- `void copy_data(const RealMatrix &drm, NEWMAT::Matrix &m)`
copy RealMatrix to NEWMAT::Matrix
- `void copy_data(const Epetra_SerialDenseVector &psdv, RealVector &drv)`
copy Epetra_SerialDenseVector to RealVector
- `void copy_data(const Epetra_SerialDenseVector &psdv, RealBaseVector &drbv)`
copy Epetra_SerialDenseVector to RealBaseVector
- `void copy_data(const Epetra_SerialDenseMatrix &psdm, RealMatrix &drm)`
copy Epetra_SerialDenseMatrix to RealMatrix
- `void copy_data(const Epetra_SerialSymDenseMatrix &ps sdm, RealMatrix &drm)`
copy Epetra_SerialSymDenseMatrix to RealMatrix
- `void copy_data(const RealVector &drv, Epetra_SerialDenseVector &psdv)`
copy RealVector to Epetra_SerialDenseVector
- `void copy_data(const RealArray &dra, Epetra_SerialDenseVector &psdv)`
copy RealArray to Epetra_SerialDenseVector
- `void copy_data(const RealBaseVector &drbv, Epetra_SerialDenseVector &psdv)`
copy RealBaseVector to Epetra_SerialDenseVector

- void `copy_data` (const `Real` *ptr, const int ptr_len, `Epetra_SerialDenseVector` &psdv)
copy Real to Epetra_SerialDenseVector*
- void `copy_data` (const `RealMatrix` &drm, `Epetra_SerialDenseMatrix` &psdm)
copy RealMatrix to Epetra_SerialDenseMatrix
- void `copy_data` (const `RealMatrix` &drm, `Epetra_SerialSymDenseMatrix` &psdm)
copy RealMatrix to Epetra_SerialSymDenseMatrix
- void `copy_data` (const `RealMatrixArray` &drma, `Array`< `Epetra_SerialSymDenseMatrix` > &psdma)
copy RealMatrixArray to Array<Epetra_SerialSymDenseMatrix>
- void `copy_data` (const `NEWMAT::ColumnVector` &cv, `Epetra_SerialDenseVector` &psdv)
copy NEWMAT::ColumnVector to Epetra_SerialDenseVector
- void `copy_data` (const std::vector< `DDaceSamplePoint` > &dspa, `RealVectorArray` &drva)
copy DDACE Array to RealVectorArray
- void `copy_data` (const std::vector< `DDaceSamplePoint` > &dspa, `Real` *ptr, const int ptr_len)
copy DDACE Array to RealVectorArray
- bool `operator!=` (const `RealVector` &drv1, const `RealVector` &drv2)
inequality operator for RealVector
- bool `operator!=` (const `IntVector` &div1, const `IntVector` &div2)
inequality operator for IntVector
- bool `operator!=` (const `IntArray` &dia1, const `IntArray` &dia2)
inequality operator for IntArray
- bool `operator!=` (const `RealMatrix` &drm1, const `RealMatrix` &drm2)
inequality operator for RealMatrix
- bool `operator!=` (const `RealMatrixArray` &drma1, const `RealMatrixArray` &drma2)
inequality operator for RealMatrixArray
- bool `operator!=` (const `StringArray` &dsa1, const `StringArray` &dsa2)
inequality operator for StringArray
- void `build_label` (`String` &label, const `String` &root_label, size_t tag)
create a label by appending a numerical tag to the root_label
- void `build_labels` (`StringArray` &label_array, const `String` &root_label)
create an array of labels by tagging root_label for each entry in label_array. Uses build_label().

- void [build_labels_partial](#) ([StringArray](#) &label_array, const [String](#) &root_label, size_t start_index, size_t num_items)
create a partial array of labels by tagging root_label for a subset of entries in label_array. Uses [build_label\(\)](#).
- template<class T> void [copy_data](#) (const T *ptr, const int ptr_len, [Vector](#)< T > &dv)
copy T to Vector<T>*
- template<class T> void [copy_data](#) (const T *ptr, const int ptr_len, [BaseVector](#)< T > &dbv)
copy T to BaseVector<T>*
- template<class T> void [copy_data](#) (const T *ptr, const int ptr_len, const [String](#) &ptr_type, [Matrix](#)< T > &dm, size_t nr, size_t nc)
copy T to Matrix<T>*
- template<class T> void [copy_data](#) (const T *ptr, const int ptr_len, const [String](#) &ptr_type, [Array](#)< [Vector](#)< T > > &dva, size_t num_vec, size_t vec_len)
copy T to Array<Vector<T> >*
- template<class T> void [copy_data](#) (const [Vector](#)< T > &dv, T *ptr, const int ptr_len)
*copy Vector<T> to T**
- template<class T> void [copy_data](#) (const [Matrix](#)< T > &dm, T *ptr, const int ptr_len, const [String](#) &ptr_type)
*copy Matrix<T> to T**
- template<class T> void [copy_data](#) (const [Vector](#)< T > &dv, [Matrix](#)< T > &dm, size_t nr, size_t nc)
copy Vector<T> to Matrix<T>
- template<class T> void [copy_data](#) (const [Vector](#)< T > &dv, [Array](#)< [Vector](#)< T > > &dva, size_t num_vec, size_t vec_len)
copy Vector<T> to Array<Vector<T> >
- template<class T> void [copy_data](#) (const [Array](#)< T > &da, [Vector](#)< T > &dv)
copy Array<T> to Vector<T>
- template<class T> void [copy_data](#) (const [BaseVector](#)< T > &dbv, [Vector](#)< T > &dv)
copy BaseVector<T> to Vector<T>
- template<class T> void [copy_data](#) (const [List](#)< T > &dl, [Array](#)< T > &da)
copy List<T> to Array<T>
- template<class T> void [copy_data](#) (const [List](#)< T > &dl, [Array](#)< [Array](#)< T > > &d2a, size_t num_a, size_t a_len)
copy List<T> to Array<Array<T> >
- template<class T> void [copy_data](#) (const [Array](#)< [Array](#)< T > > &d2a, [Array](#)< T > &da)

copy [Array](#)<Array<T>> to Array<T> (unroll 2D array into 1D array)

- `template<class T> void copy_data (const utilib::NumArray< T > &na, Vector< T > &dv)`
copy [utilib::NumArray](#)<T> to [Vector](#)<T>
- `template<class T> void copy_data (const Vector< T > &dv, utilib::NumArray< T > &na)`
copy [Vector](#)<T> to [utilib::NumArray](#)<T>
- `template<class T> void copy_data (const utilib::NumArray< T > &na, Array< T > &da)`
copy [utilib::NumArray](#)<T> to [Array](#)<T>
- `template<class T> void copy_data (const List< T > &dl, utilib::NumArray< T > &na)`
copy [List](#)<T> to [utilib::NumArray](#)<T>
- `template<class T> void copy_data (const TNT::Vector< T > &tntv, Vector< T > &dv)`
copy [TNT::Vector](#)<T> to [Vector](#)<T>
- `template<class T> void copy_data (const Vector< T > &dv, TNT::Vector< T > &tntv)`
copy [Vector](#)<T> to [TNT::Vector](#)<T>
- `template<class T> void copy_data (const T *ptr, const int ptr_len, TNT::Vector< T > &tntv)`
copy T to [TNT::Vector](#)<T>*
- `template<class T> void copy_data (const Matrix< T > &dm, TNT::Matrix< T > &tntm)`
copy [Matrix](#)<T> to [TNT::Matrix](#)<T>
- `bool data_interface_id_compare (const DataInterface &di, const void *id)`
global comparison function for [DataInterface](#)
- `MPIPackBuffer & operator<< (MPIPackBuffer &s, const DataInterface &data)`
[MPIPackBuffer](#) insertion operator for [DataInterface](#).
- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &s, DataInterface &data)`
[MPIUnpackBuffer](#) extraction operator for [DataInterface](#).
- `ostream & operator<< (ostream &s, const DataInterface &data)`
ostream insertion operator for [DataInterface](#)
- `bool data_method_id_compare (const DataMethod &dm, const void *id)`
global comparison function for [DataMethod](#)
- `MPIPackBuffer & operator<< (MPIPackBuffer &s, const DataMethod &data)`
[MPIPackBuffer](#) insertion operator for [DataMethod](#).
- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &s, DataMethod &data)`
[MPIUnpackBuffer](#) extraction operator for [DataMethod](#).

- `ostream & operator<<` (`ostream &s`, `const DataMethod &data`)
ostream insertion operator for DataMethod
- `bool data_model_id_compare` (`const DataModel &dm`, `const void *id`)
global comparison function for DataModel
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &s`, `const DataModel &data`)
MPIPackBuffer insertion operator for DataModel.
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &s`, `DataModel &data`)
MPIUnpackBuffer extraction operator for DataModel.
- `ostream & operator<<` (`ostream &s`, `const DataModel &data`)
ostream insertion operator for DataModel
- `bool data_responses_id_compare` (`const DataResponses &dr`, `const void *id`)
global comparison function for DataResponses
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &s`, `const DataResponses &data`)
MPIPackBuffer insertion operator for DataResponses.
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &s`, `DataResponses &data`)
MPIUnpackBuffer extraction operator for DataResponses.
- `ostream & operator<<` (`ostream &s`, `const DataResponses &data`)
ostream insertion operator for DataResponses
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &s`, `const DataStrategy &data`)
MPIPackBuffer insertion operator for DataStrategy.
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &s`, `DataStrategy &data`)
MPIUnpackBuffer extraction operator for DataStrategy.
- `ostream & operator<<` (`ostream &s`, `const DataStrategy &data`)
ostream insertion operator for DataStrategy
- `bool data_variables_id_compare` (`const DataVariables &dv`, `const void *id`)
global comparison function for DataVariables
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &s`, `const DataVariables &data`)
MPIPackBuffer insertion operator for DataVariables.
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &s`, `DataVariables &data`)
MPIUnpackBuffer extraction operator for DataVariables.

- `ostream & operator<<` (`ostream &s`, `const DataVariables &data`)
ostream insertion operator for `DataVariables`
- `int salinas_main` (`int argc`, `char *argv[]`, `MPI_Comm *comm`)
subroutine interface to SALINAS simulation code
- `bool operator==` (`const DistinctVariables &vars1`, `const DistinctVariables &vars2`)
equality operator
- `ParallelLibrary dummy_lib` (0)
dummy `ParallelLibrary` object used for mandatory reference initialization when a real `ParallelLibrary` instance is unavailable
- `ProblemDescDB dummy_db` (`dummy_lib`)
dummy `ProblemDescDB` object used for mandatory reference initialization when a real `ProblemDescDB` instance is unavailable
- `void abort_handler` (`int code`)
global function which handles serial or parallel aborts
- `int start_grid_computing` (`char *analysis_driver_script`, `char *params_file`, `char *results_file`)
- `int stop_grid_computing` ()
- `int perform_analysis` (`char *iteration_num`)
- `template<typename T> string asstring` (`const T &val`)
Creates a string from the argument "val" using an ostream.
- `bool operator==` (`const MergedVariables &vars1`, `const MergedVariables &vars2`)
equality operator
- `PACKBUF` (`int`, `MPI_INT`)
- `UNPACKBUF` (`int`, `MPI_INT`)
- `PACKSIZE` (`int`, `MPI_INT`)
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const int &data`)
insert an int
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const u_int &data`)
insert a u_int
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const long &data`)
insert a long
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const u_long &data`)
insert a u_long
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const short &data`)
insert a short

- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const u_short &data`)
insert a u_short
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const char &data`)
insert a char
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const u_char &data`)
insert a u_char
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const double &data`)
insert a double
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const float &data`)
insert a float
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const bool &data`)
insert a bool
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &buff`, `int &data`)
extract an int
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &buff`, `u_int &data`)
extract a u_int
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &buff`, `long &data`)
extract a long
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &buff`, `u_long &data`)
extract a u_long
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &buff`, `short &data`)
extract a short
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &buff`, `u_short &data`)
extract a u_short
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &buff`, `char &data`)
extract a char
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &buff`, `u_char &data`)
extract a u_char
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &buff`, `double &data`)
extract a double

- `MPIUnpackBuffer` & `operator>>` (`MPIUnpackBuffer` &buff, float &data)
extract a float
- `MPIUnpackBuffer` & `operator>>` (`MPIUnpackBuffer` &buff, bool &data)
extract a bool
- int `MPIPackSize` (const int &data, const int num=1)
return packed size of an int
- int `MPIPackSize` (const u_int &data, const int num=1)
return packed size of a u_int
- int `MPIPackSize` (const long &data, const int num=1)
return packed size of a long
- int `MPIPackSize` (const u_long &data, const int num=1)
return packed size of a u_long
- int `MPIPackSize` (const short &data, const int num=1)
return packed size of a short
- int `MPIPackSize` (const u_short &data, const int num=1)
return packed size of a u_short
- int `MPIPackSize` (const char &data, const int num=1)
return packed size of a char
- int `MPIPackSize` (const u_char &data, const int num=1)
return packed size of a u_char
- int `MPIPackSize` (const double &data, const int num=1)
return packed size of a double
- int `MPIPackSize` (const float &data, const int num=1)
return packed size of a float
- int `MPIPackSize` (const bool &data, const int num=1)
return packed size of a bool
- void `dn2f_` (int *n, int *p, Real *x, CalcTj, int *iv, int *liv, int *lv, Real *v, int *ui, void *ur, Vf)
- void `dn2fb_` (int *n, int *p, Real *x, Real *b, CalcTj, int *iv, int *liv, int *lv, Real *v, int *ui, void *ur, Vf)
- void `dn2g_` (int *n, int *p, Real *x, CalcTj, CalcTj, int *iv, int *liv, int *lv, Real *v, int *ui, void *ur, Vf)
- void `dn2gb_` (int *n, int *p, Real *x, Real *b, CalcTj, CalcTj, int *iv, int *liv, int *lv, Real *v, int *ui, void *ur, Vf)
- void `divset_` (int *, int *, int *, int *, Real *)
- double `dr7mdc_` (int *)

- double **rnum1** (void)
- double **rnum2** (void)
- bool **operator==** (const [ParamResponsePair](#) &pair1, const [ParamResponsePair](#) &pair2)
equality operator
- bool **vars_set_compare** (const [ParamResponsePair](#) &database_pr, const void *search_pr)
search function for a particular [ParamResponsePair](#) within a [List](#)
- bool **eval_id_compare** (const [ParamResponsePair](#) &pair, const void *id)
search function for a particular [ParamResponsePair](#) within a [List](#)
- bool **eval_id_sort_fn** (const [ParamResponsePair](#) &pr1, const [ParamResponsePair](#) &pr2)
sort function for [ParamResponsePair](#)
- [istream](#) & **operator>>** ([istream](#) &s, [ParamResponsePair](#) &pair)
istream extraction operator for [ParamResponsePair](#)
- [ostream](#) & **operator<<** ([ostream](#) &s, const [ParamResponsePair](#) &pair)
ostream insertion operator for [ParamResponsePair](#)
- [BiStream](#) & **operator>>** ([BiStream](#) &s, [ParamResponsePair](#) &pair)
[BiStream](#) extraction operator for [ParamResponsePair](#).
- [BoStream](#) & **operator<<** ([BoStream](#) &s, const [ParamResponsePair](#) &pair)
[BoStream](#) insertion operator for [ParamResponsePair](#).
- [MPIUnpackBuffer](#) & **operator>>** ([MPIUnpackBuffer](#) &s, [ParamResponsePair](#) &pair)
[MPIUnpackBuffer](#) extraction operator for [ParamResponsePair](#).
- [MPIPackBuffer](#) & **operator<<** ([MPIPackBuffer](#) &s, const [ParamResponsePair](#) &pair)
[MPIPackBuffer](#) insertion operator for [ParamResponsePair](#).
- bool **operator!=** (const [ParamResponsePair](#) &pair1, const [ParamResponsePair](#) &pair2)
inequality operator
- void **print_restart** (int argc, char **argv, [String](#) print_dest)
print a restart file
- void **print_restart_tabular** (int argc, char **argv, [String](#) print_dest)
print a restart file (tabular format)
- void **read_neutral** (int argc, char **argv)
read a restart file (neutral file format)
- void **repair_restart** (int argc, char **argv, [String](#) identifier_type)
repair a restart file by removing corrupted evaluations

- void `concatenate_restart` (int argc, char **argv)
concatenate multiple restart files

Variables

- `ProblemDescDB dummy_db`
dummy `ProblemDescDB` object used for mandatory reference initialization when a real `ProblemDescDB` instance is unavailable
- `Model dummy_model`
dummy `Model` object used for mandatory reference initialization or default virtual function return by reference when a real `Model` instance is unavailable
- `ParallelLibrary dummy_lib`
dummy `ParallelLibrary` object used for mandatory reference initialization when a real `ParallelLibrary` instance is unavailable
- `Graphics dakota_graphics`
the global `Dakota::Graphics` object used by strategies, models, and approximations
- `Interface dummy_interface`
dummy `Interface` object used for mandatory reference initialization or default virtual function return by reference when a real `Interface` instance is unavailable
- `Iterator dummy_iterator`
dummy `Iterator` object used for mandatory reference initialization or default virtual function return by reference when a real `Iterator` instance is unavailable
- `class class class class class class class class typedef double Real`
- `ostream * dakota_cout = &cout`
DAKOTA stdout initially points to cout, but may be redirected to a tagged ofstream if there are concurrent iterators.
- `ostream * dakota_cerr = &cerr`
DAKOTA stderr initially points to cerr, but may be redirected to a tagged ofstream if there are concurrent iterators.
- `PRPList data_pairs`
list of all parameter/response pairs.
- `BoStream write_restart`
the restart binary output stream (doesn't really need to be global anymore except for `abort_handler()`).
- `int write_precision = 10`
used in ostream data output functions (`restart_util.C` overrides this default value)

- int `mc_ptr_int` = 0
global pointer for ModelCenter API
- FILE * `yyin`
- const int `MAXPOSDEF` = 10
- const int `NONRANDOM` = 0
- const int `RANDOM` = 1
- Dakota::GSL_Singleton `GSL_RNG`
- const int `LARGE_SCALE` = 100
- const size_t `_NPOS` = ~(size_t)0
special value returned by index() when entry not found

9.1.1 Detailed Description

The primary namespace for DAKOTA.

The Dakota namespace encapsulates the core classes of the DAKOTA framework and prevents name clashes with third-party libraries from VendorOptimizers and VendorPackages. The C++ source files defining these core classes reside in Dakota/src as *. [CH].

9.1.2 Function Documentation

9.1.2.1 void `COLINOptimizer`< coliny::DIRECT >::set_method_parameters (void)

Section 3

specialization of set_method_parameters() for DIRECT

9.1.2.2 void `COLINOptimizer`< coliny::Cobyla >::set_method_parameters (void)

specialization of set_method_parameters() for Cobyla

9.1.2.3 void `COLINOptimizer`< coliny::APPS >::set_method_parameters (void)

specialization of set_method_parameters() for APPS

9.1.2.4 void `COLINOptimizer`< coliny::PatternSearch >::set_runtime_parameters ()

specialization of set_runtime_parameters() for PatternSearch

9.1.2.5 void COLINOptimizer< coliny::PatternSearch >::set_method_parameters (void)

specialization of set_method_parameters() for PatternSearch

9.1.2.6 void COLINOptimizer< coliny::SolisWets >::set_method_parameters (void)

specialization of set_method_parameters() for SolisWets

9.1.2.7 void COLINOptimizer< coliny::EAminlp >::set_method_parameters (void)

specialization of set_method_parameters() for EAminlp

9.1.2.8 CommandShell & flush (CommandShell & shell)

convenient shell manipulator function to "flush" the shell

global convenience function for manipulating the shell; invokes the class member flush function.

9.1.2.9 bool operator== (const DistinctVariables & vars1, const DistinctVariables & vars2)

equality operator

Checks each array using operator== from [data_types.C](#). Labels are ignored.

**9.1.2.10 bool vars_set_compare (const ParamResponsePair & database_pr, const void * search_pr)
[inline]**

search function for a particular [ParamResponsePair](#) within a [List](#)

a global function to compare the parameter values, ASV, & interface id of a particular database_pr (presumed to be in the global history list) with a passed in set of parameters, ASV, & interface id provided by search_pr.

9.1.2.11 bool eval_id_compare (const ParamResponsePair & pair, const void * id) [inline]

search function for a particular [ParamResponsePair](#) within a [List](#)

a global function to compare the evalId of a particular [ParamResponsePair](#) (from a [List](#)) with a passed in evaluation id. *((int*)id) construct casts void* to int* and then dereferences.

**9.1.2.12 bool eval_id_sort_fn (const ParamResponsePair & pr1, const ParamResponsePair & pr2)
[inline]**

sort function for [ParamResponsePair](#)

a global function used to sort a PRPList by evalId's.

9.1.2.13 void print_restart (int argc, char ** argv, String print_dest)

print a restart file

Usage: "dakota_restart_util print dakota.rst"

"dakota_restart_util to_neutral dakota.rst dakota.neu"

Prints all evals. in full precision to either stdout or a neutral file. The former is useful for ensuring that duplicate detection is successful in a restarted run (e.g., starting a new method from the previous best), and the latter is used for translating binary files between platforms.

9.1.2.14 void print_restart_tabular (int argc, char ** argv, String print_dest)

print a restart file (tabular format)

Usage: "dakota_restart_util to_pdb dakota.rst dakota.pdb"

"dakota_restart_util to_tabular dakota.rst dakota.txt"

Unrolls all data associated with a particular tag for all evaluations and then writes this data in a tabular format (e.g., to a PDB database or MATLAB/TECPLOT data file).

9.1.2.15 void read_neutral (int argc, char ** argv)

read a restart file (neutral file format)

Usage: "dakota_restart_util from_neutral dakota.neu dakota.rst"

Reads evaluations from a neutral file. This is used for translating binary files between platforms.

9.1.2.16 void repair_restart (int argc, char ** argv, String identifier_type)

repair a restart file by removing corrupted evaluations

Usage: "dakota_restart_util remove 0.0 dakota_old.rst dakota_new.rst"

"dakota_restart_util remove_ids 2 7 13 dakota_old.rst dakota_new.rst"

Repairs a restart file by removing corrupted evaluations. The identifier for evaluation removal can be either a double precision number (all evaluations having a matching response function value are removed) or a list of integers (all evaluations with matching evaluation ids are removed).

9.1.2.17 void concatenate_restart (int argc, char ** argv)

concatenate multiple restart files

Usage: "dakota_restart_util cat dakota_1.rst ... dakota_n.rst dakota_new.rst"

Combines multiple restart files into a single restart database.

9.2 SIM Namespace Reference

A sample namespace for derived classes that use `assign_rep()` to plug facilities into DAKOTA.

Classes

- class [DirectFnApplicInterface](#)

Sample derived interface class for testing plug-ins using `assign_rep()`.

9.2.1 Detailed Description

A sample namespace for derived classes that use `assign_rep()` to plug facilities into DAKOTA.

A typical use of plug-ins with `assign_rep()` is to publish a simulation interface for use in library mode. See [Interfacing with DAKOTA as a Library](#) for more information.

Chapter 10

DAKOTA Class Documentation

10.1 ActiveSet Class Reference

Container class for active set tracking information. Contains the active set request vector and the derivative variables vector.

Public Member Functions

- [ActiveSet](#) ()
default constructor
- [ActiveSet](#) (size_t num_fns, size_t num_deriv_vars)
standard constructor
- [ActiveSet](#) (const [ActiveSet](#) &set)
copy constructor
- [~ActiveSet](#) ()
destructor
- [ActiveSet](#) & [operator=](#) (const [ActiveSet](#) &set)
assignment operator
- void [reshape](#) (size_t num_fns, size_t num_deriv_vars)
reshape requestVector and derivVarsVector
- const [IntArray](#) & [request_vector](#) () const
return the request vector

- void `request_vector` (const `IntArray` &rv)
set the request vector
- void `request_values` (const int rv_val)
set all request vector values
- void `request_value` (const size_t index, const int rv_val)
set the value of an entry in the request vector
- const `IntArray` & `derivative_vector` () const
return the derivative variables vector
- void `derivative_vector` (const `IntArray` &dvv)
set the derivative variables vector
- void `derivative_start_value` (const int dvv_start_val)
set the derivative variables vector values
- void `read` (istream &s)
read an active set object from an istream
- void `write` (ostream &s) const
write an active set object to an ostream
- void `write_annotated` (ostream &s) const
write an active set object to an ostream in annotated format
- void `read` (BiStream &s)
read an active set object from the binary restart stream
- void `write` (BoStream &s) const
write an active set object to the binary restart stream
- void `read` (MPIUnpackBuffer &s)
read an active set object from a packed MPI buffer
- void `write` (MPIPackBuffer &s) const
write an active set object to a packed MPI buffer

Private Attributes

- `IntArray` `requestVector`
the vector of response requests

- [IntArray derivVarsVector](#)

the vector of variable ids used for computing derivatives

Friends

- `bool operator==(const ActiveSet &set1, const ActiveSet &set2)`
equality operator
- `bool operator!=(const ActiveSet &set1, const ActiveSet &set2)`
inequality operator

10.1.1 Detailed Description

Container class for active set tracking information. Contains the active set request vector and the derivative variables vector.

The [ActiveSet](#) class is a small class whose initial design function is to avoid having to pass the ASV and DVV separately. It is not part of a class hierarchy and does not employ reference-counting/ representation-sharing idioms (e.g., handle-body).

10.1.2 Member Data Documentation

10.1.2.1 [IntArray requestVector](#) [private]

the vector of response requests

It uses a 0 value for inactive functions and sums 1 (value), 2 (gradient), and 4 (Hessian) for active functions.

10.1.2.2 [IntArray derivVarsVector](#) [private]

the vector of variable ids used for computing derivatives

These ids will generally identify either the active continuous variables or the inactive continuous variables.

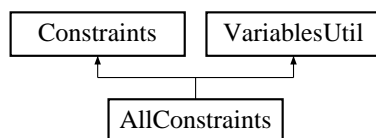
The documentation for this class was generated from the following files:

- DakotaActiveSet.H
- DakotaActiveSet.C

10.2 AllConstraints Class Reference

Derived class within the [Constraints](#) hierarchy which employs the all data view.

Inheritance diagram for AllConstraints::



Public Member Functions

- [AllConstraints](#) ()
default constructor
- [AllConstraints](#) (const [ProblemDescDB](#) &problem_db, const pair< short, short > &view)
standard constructor
- [~AllConstraints](#) ()
destructor
- const [RealVector](#) & [continuous_lower_bounds](#) () const
return the active continuous variable lower bounds
- void [continuous_lower_bounds](#) (const [RealVector](#) &c_l_bnds)
set the active continuous variable lower bounds
- const [RealVector](#) & [continuous_upper_bounds](#) () const
return the active continuous variable upper bounds
- void [continuous_upper_bounds](#) (const [RealVector](#) &c_u_bnds)
set the active continuous variable upper bounds
- const [IntVector](#) & [discrete_lower_bounds](#) () const
return the active discrete variable lower bounds
- void [discrete_lower_bounds](#) (const [IntVector](#) &d_l_bnds)
set the active discrete variable lower bounds
- const [IntVector](#) & [discrete_upper_bounds](#) () const
return the active discrete variable upper bounds

- void `discrete_upper_bounds` (const `IntVector` &d_u_bnds)
set the active discrete variable upper bounds
- `RealVector` `all_continuous_lower_bounds` () const
returns a single array with all continuous lower bounds
- `RealVector` `all_continuous_upper_bounds` () const
returns a single array with all continuous upper bounds
- `IntVector` `all_discrete_lower_bounds` () const
returns a single array with all discrete lower bounds
- `IntVector` `all_discrete_upper_bounds` () const
returns a single array with all discrete upper bounds
- void `write` (ostream &s) const
write a variable constraints object to an ostream
- void `read` (istream &s)
read a variable constraints object from an istream

Private Attributes

- `RealVector` `allContinuousLowerBnds`
a continuous lower bounds array combining continuous design, uncertain, and continuous state variable types (all view).
- `RealVector` `allContinuousUpperBnds`
a continuous upper bounds array combining continuous design, uncertain, and continuous state variable types (all view).
- `IntVector` `allDiscreteLowerBnds`
a discrete lower bounds array combining discrete design and discrete state variable types (all view).
- `IntVector` `allDiscreteUpperBnds`
a discrete upper bounds array combining discrete design and discrete state variable types (all view).
- size_t `numCDV`
number of continuous design variables
- size_t `numDDV`
number of discrete design variables
- size_t `numUV`

number of uncertain variables

- size_t [numCSV](#)

number of continuous state variables

- size_t [numDSV](#)

number of discrete state variables

10.2.1 Detailed Description

Derived class within the [Constraints](#) hierarchy which employs the all data view.

Derived variable constraints classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [AllConstraints](#) derived class combines design, uncertain, and state variable types but separates continuous and discrete domain types. The result is combined continuous bounds arrays ([allContinuousLowerBnds](#), [allContinuousUpperBnds](#)) and combined discrete bounds arrays ([allDiscreteLowerBnds](#), [allDiscreteUpperBnds](#)). Parameter and DACE studies currently use this approach (see [Variables::get_variables\(problem_db\)](#) for variables view selection; variables view is passed to the [Constraints](#) constructor in [Model](#)).

10.2.2 Constructor & Destructor Documentation

10.2.2.1 [AllConstraints](#) (const [ProblemDescDB](#) & *problem_db*, const pair< short, short > & *view*)

standard constructor

In this class, the all data approach (design, uncertain, and state types are combined) is used. Iterators/strategies which use this class include: parameter studies, dace, and nond_sampling in all_variables mode. Extract fundamental lower and upper bounds and combine them into [allContinuousLowerBnds](#), [allContinuousUpperBnds](#), [allDiscreteLowerBnds](#), and [allDiscreteUpperBnds](#) using utilities from [VariablesUtil](#).

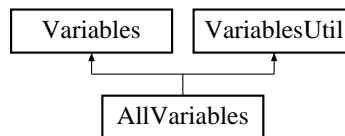
The documentation for this class was generated from the following files:

- [AllConstraints.H](#)
- [AllConstraints.C](#)

10.3 AllVariables Class Reference

Derived class within the [Variables](#) hierarchy which employs the all data view.

Inheritance diagram for AllVariables::



Public Member Functions

- [AllVariables](#) ()
default constructor
- [AllVariables](#) (const [ProblemDescDB](#) &problem_db, const pair< short, short > &view)
standard constructor
- [~AllVariables](#) ()
destructor
- size_t tv () const
Returns total number of vars.
- const [RealVector](#) & [continuous_variables](#) () const
return the active continuous variables
- void [continuous_variables](#) (const [RealVector](#) &c_vars)
set the active continuous variables
- const [IntVector](#) & [discrete_variables](#) () const
return the active discrete variables
- void [discrete_variables](#) (const [IntVector](#) &d_vars)
set the active discrete variables
- const [StringArray](#) & [continuous_variable_labels](#) () const
return the active continuous variable labels
- void [continuous_variable_labels](#) (const [StringArray](#) &cv_labels)
set the active continuous variable labels

- `const StringArray & discrete_variable_labels () const`
return the active discrete variable labels
- `void discrete_variable_labels (const StringArray &dv_labels)`
set the active discrete variable labels
- `size_t acv () const`
returns total number of continuous vars
- `size_t adv () const`
returns total number of discrete vars
- `RealVector all_continuous_variables () const`
returns a single array with all continuous variables
- `void all_continuous_variables (const RealVector &a_c_vars)`
sets all continuous variables using a single array
- `IntVector all_discrete_variables () const`
returns a single array with all discrete variables
- `void all_discrete_variables (const IntVector &a_d_vars)`
sets all discrete variables using a single array
- `StringArray all_continuous_variable_labels () const`
returns a single array with all continuous variable labels
- `StringArray all_discrete_variable_labels () const`
returns a single array with all discrete variable labels
- `StringArray all_variable_labels () const`
returns a single array with all variable labels
- `void read (istream &s)`
read a variables object from an istream
- `void write (ostream &s) const`
write a variables object to an ostream
- `void write_aprepro (ostream &s) const`
write a variables object to an ostream in aprepro format
- `void read_annotated (istream &s)`
read a variables object in annotated format from an istream

- void [write_annotated](#) (ostream &s) const
write a variables object in annotated format to an ostream
- void [write_tabular](#) (ostream &s) const
write a variables object in tabular format to an ostream
- void [read](#) (BiStream &s)
read a variables object from the binary restart stream
- void [write](#) (BoStream &s) const
write a variables object to the binary restart stream
- void [read](#) (MPIUnpackBuffer &s)
read a variables object from a packed MPI buffer
- void [write](#) (MPIPackBuffer &s) const
write a variables object to a packed MPI buffer

Private Member Functions

- void [copy_rep](#) (const Variables *vars_rep)
Used by [copy\(\)](#) to copy the contents of a letter class.

Private Attributes

- [RealVector](#) [allContinuousVars](#)
a continuous array combining all of the continuous variables (design, uncertain, and state).
- [IntVector](#) [allDiscreteVars](#)
a discrete array combining all of the discrete variables (design and state).
- [StringArray](#) [allContinuousLabels](#)
a label array combining all of the continuous variable labels (design, uncertain, and state).
- [StringArray](#) [allDiscreteLabels](#)
a label array combining all of the discrete variable labels (design and state).
- size_t [numCDV](#)
number of continuous design variables
- size_t [numDDV](#)
number of discrete design variables

- `size_t numUV`
number of uncertain variables
- `size_t numCSV`
number of continuous state variables
- `size_t numDSV`
number of discrete state variables

Friends

- `bool operator==(const AllVariables &vars1, const AllVariables &vars2)`
equality operator

10.3.1 Detailed Description

Derived class within the [Variables](#) hierarchy which employs the all data view.

Derived variables classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [AllVariables](#) derived class combines design, uncertain, and state variable types but separates continuous and discrete domain types. The result is a single array of continuous variables (`allContinuousVars`) and a single array of discrete variables (`allDiscreteVars`). Parameter and DACE studies currently use this approach (see `Variables::get_variables(problem_db)`).

10.3.2 Constructor & Destructor Documentation

10.3.2.1 [AllVariables](#) (`const ProblemDescDB & problem_db, const pair< short, short > & view`)

standard constructor

In this class, the all data approach (design, uncertain, and state types are combined) is used. Iterators/strategies which use this class include: parameter studies, DACE, and the `all_variables` mode of `nond_sampling`. Extract fundamental variable types and labels and combine them into `allContinuousVars`, `allDiscreteVars`, `allContinuousLabels`, and `allDiscreteLabels` using utilities from [VariablesUtil](#).

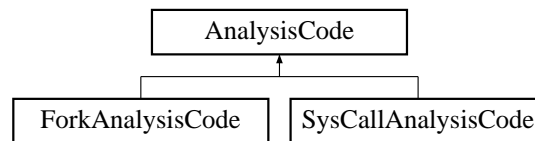
The documentation for this class was generated from the following files:

- `AllVariables.H`
- `AllVariables.C`

10.4 AnalysisCode Class Reference

Base class providing common functionality for derived classes ([SysCallAnalysisCode](#) and [ForkAnalysisCode](#)) which spawn separate processes for managing simulations.

Inheritance diagram for AnalysisCode::



Public Member Functions

- void [define_filenames](#) (const int id)
define modified filenames from user input by handling Unix temp file and tagging options
- void [write_parameters_files](#) (const [Variables](#) &vars, const [ActiveSet](#) &set, const int id)
write the parameters data and response request data to one or more parameters files (using one or more invocations of [write_parameters_file\(\)](#)) in either standard or aprepro format
- void [read_results_files](#) ([Response](#) &response, const int id)
read the response object from one or more results files
- const [StringArray](#) & [program_names](#) () const
return programNames
- const [String](#) & [input_filter_name](#) () const
return iFilterName
- const [String](#) & [output_filter_name](#) () const
return oFilterName
- const [String](#) & [parameters_filename](#) () const
return paramsFileName
- const [String](#) & [results_filename](#) () const
return resultsFileName
- const [String](#) & [results_filename](#) (const int id)
return the results filename entry in fileNameMap corresponding to id

- void [suppress_output_flag](#) (const bool flag)
set suppressOutputFlag
- bool [suppress_output_flag](#) () const
return suppressOutputFlag
- bool [multiple_parameters_filenames](#) () const
return multipleParamsFiles

Protected Member Functions

- [AnalysisCode](#) (const [ProblemDescDB](#) &problem_db)
constructor
- virtual [~AnalysisCode](#) ()
destructor

Protected Attributes

- bool [suppressOutputFlag](#)
flag set by master processor to suppress output from slave processors
- bool [verboseFlag](#)
flag for additional analysis code output if method verbosity is set
- bool [fileTagFlag](#)
flags tagging of parameter/results files
- bool [fileSaveFlag](#)
flags retention of parameter/results files
- bool [apreproFlag](#)
flags use of the APREPRO (the Sandia "A PRE PROCESSOR" utility) format for parameter files
- bool [multipleParamsFiles](#)
flag indicating the need for separate parameters files for multiple analysis drivers
- [String iFilterName](#)
the name of the input filter (input_filter user specification)
- [String oFilterName](#)
the name of the output filter (output_filter user specification)

- [StringArray programNames](#)
the names of the analysis code programs (analysis_drivers user specification)
- `size_t numPrograms`
the number of analysis code programs (length of programNames)
- [String specifiedParamsFileName](#)
the name of the parameters file from user specification
- [String paramsFileName](#)
the parameters file name actually used (modified with tagging or temp files)
- [String specifiedResultsFileName](#)
the name of the results file from user specification
- [String resultsFileName](#)
the results file name actually used (modified with tagging or temp files)
- `map< int, pair< String, String > > fileNameMap`
stores parameters and results file names used in spawning function evaluations. Map key is the function evaluation identifier.

Private Member Functions

- `void write_parameters_file (const Variables &vars, const ActiveSet &set, const StringArray &an_comps, const String ¶ms_fname)`
write the variables, active set vector, derivative variables vector, and analysis components to the specified parameters file in either standard or aprepro format

Private Attributes

- [ParallelLibrary](#) & [paralleLib](#)
reference to the [ParallelLibrary](#) object. Used in [define_filenames\(\)](#).
- [String2DArray analysisComponents](#)
the set of optional analysis components used by the analysis drivers (from the [analysis_components](#) interface specification)

10.4.1 Detailed Description

Base class providing common functionality for derived classes ([SysCallAnalysisCode](#) and [ForkAnalysisCode](#)) which spawn separate processes for managing simulations.

The [AnalysisCode](#) class hierarchy provides simulation spawning services for [ApplicationInterface](#) derived classes and alleviates these classes of some of the specifics of simulation code management. The hierarchy does not employ the letter-envelope technique since the [ApplicationInterface](#) derived classes instantiate the appropriate derived [AnalysisCode](#) class directly.

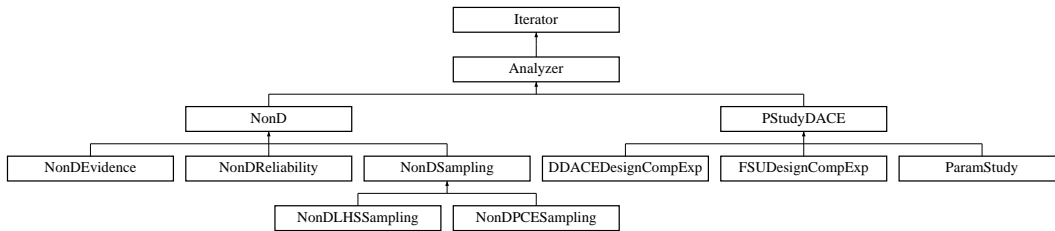
The documentation for this class was generated from the following files:

- [AnalysisCode.H](#)
- [AnalysisCode.C](#)

10.5 Analyzer Class Reference

Base class for [NonD](#), [DACE](#), and [ParamStudy](#) branches of the iterator hierarchy.

Inheritance diagram for Analyzer::



Public Member Functions

- `const VariablesArray & all_variables () const`
return the complete set of evaluated variables
- `const RealVectorArray & all_c_variables () const`
return the complete set of evaluated continuous variables
- `const ResponseArray & all_responses () const`
return the complete set of computed responses
- `const RealVectorArray & all_fn_responses () const`
return the complete set of computed function responses

Protected Member Functions

- `Analyzer ()`
default constructor
- `Analyzer (Model &model)`
standard constructor
- `Analyzer (NoDBBaseConstructor, Model &model)`
alternate constructor for instantiations "on the fly"
- `~Analyzer ()`
destructor

- virtual void `update_best` (const `RealVector` &vars, const `Response` &response, const int eval_num)
compares current evaluation to best evaluation and updates best
- virtual void `vary_pattern` (bool pattern_flag)
sets varyPattern in derived classes that support it
- virtual void `get_parameter_sets` ()
*Returns one block of samples (ndim * num_samples).*
- void `evaluate_parameter_sets` (bool vars_flag, bool resp_flag, bool fns_flag, bool best_flag)
perform function evaluations to map parameter sets (allVariables/allCVariables/allDVariables) into response sets (allResponses/allFnResponses/allGradResponses)
- void `var_based_decomp` (const int ndim, const int num_samples)
- void `volumetric_quality` (int ndim, int num_samples, double *sample_points)
Calculation of volumetric quality measures.
- void `print_vbd` (ostream &s, const `RealVector` &S, const `RealVector` &T) const
Printing of VBD results.

Protected Attributes

- `VariablesArray` allVariables
array of all variables evaluated
- `RealVectorArray` allCVariables
array of all continuous variables evaluated (subset of allVariables)
- `ResponseArray` allResponses
array of all responses computed
- `RealVectorArray` allFnResponses
array of all function responses computed (subset of allResponses)
- `StringArray` allHeaders
array of headers to insert into output while evaluating allCVariables
- bool qualityFlag
flag to indicated if quality metrics were calculated
- double chiMeas
quality measures
- double dMeas

quality measures

- double [hMeas](#)
quality measures
- double [tauMeas](#)
quality measures

10.5.1 Detailed Description

Base class for [NonD](#), [DACE](#), and [ParamStudy](#) branches of the iterator hierarchy.

The [Analyzer](#) class provides common data and functionality for various types of systems analysis, including nondeterministic analysis, design of experiments, and parameter studies.

10.5.2 Member Function Documentation

10.5.2.1 void evaluate_parameter_sets (bool vars_flag, bool resp_flag, bool fns_flag, bool best_flag) [protected]

perform function evaluations to map parameter sets (allVariables/allCVariables/allDVariables) into response sets (allResponses/allFnResponses/allGradResponses)

Convenience function for derived classes with sets of function evaluations to perform (e.g., [NonDSampling](#), [DDACEDesignCompExp](#), [FSUDesignCompExp](#), [ParamStudy](#)).

10.5.2.2 void var_based_decomp (const int ndim, const int num_samples) [protected]

Calculation of sensitivity indices obtained by variance based decomposition. These indices are obtained by the Saltelli version of the Sobol' VBD which uses $(K+2)*N$ function evaluations, where K is the number of dimensions (uncertain vars) and N is the number of samples.

10.5.2.3 void volumetric_quality (int ndim, int num_samples, double * sample_points) [protected]

Calculation of volumetric quality measures.

Calculation of volumetric quality measures developed by FSU.

10.5.2.4 void print_vbd (ostream & s, const RealVector & S, const RealVector & T) const [protected]

Printing of VBD results.

printing of variance based decomposition indices.

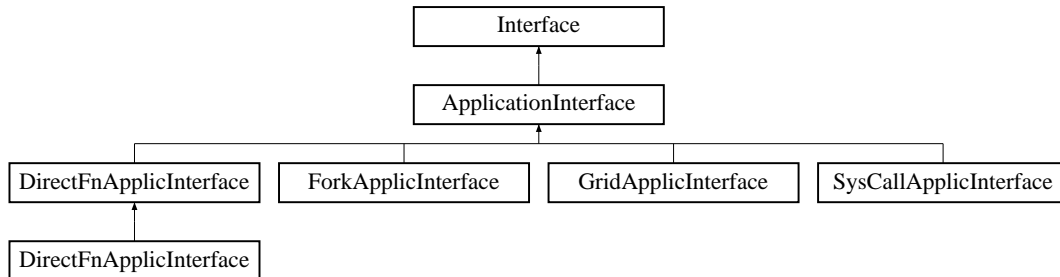
The documentation for this class was generated from the following files:

- DakotaAnalyzer.H
- DakotaAnalyzer.C

10.6 ApplicationInterface Class Reference

Derived class within the interface class hierarchy for supporting interfaces to simulation codes.

Inheritance diagram for ApplicationInterface::



Public Member Functions

- [ApplicationInterface](#) (const [ProblemDescDB](#) &problem_db)
constructor
- [~ApplicationInterface](#) ()
destructor

Protected Member Functions

- void [init_communicators](#) (const [IntArray](#) &message_lengths, const int &max_iterator_concurrency)
allocate communicator partitions for concurrent evaluations within an iterator and concurrent multiprocessor analyses within an evaluation.
- void [reset_communicators](#) (const [IntArray](#) &message_lengths)
reset the local parallel partition data for an interface (the partitions are already allocated in [ParallelLibrary](#)).
- void [free_communicators](#) ()
deallocate communicator partitions for concurrent evaluations within an iterator and concurrent multiprocessor analyses within an evaluation.
- void [init_serial](#) ()
- int [asynch_local_evaluation_concurrency](#) () const
return asynchLocalEvalConcurrency
- [String interface_synchronization](#) () const

return interface.Synchronization

- void `map` (const `Variables` &vars, const `ActiveSet` &set, `Response` &response, const bool asynch_flag=false)

Provides a "mapping" of variables to responses using a simulation. Protected due to [Interface](#) letter-envelope idiom.
- void `manage_failure` (const `Variables` &vars, const `ActiveSet` &set, `Response` &response, int failed_eval_id)

manages a simulation failure using abort/retry/recover/continuation
- const `ResponseArray` & `synch` ()

executes a blocking schedule for asynchronous evaluations in the beforeSynchCorePRPList queue and returns all jobs
- const `IntResponseMap` & `synch_nowait` ()

executes a nonblocking schedule for asynchronous evaluations in the beforeSynchCorePRPList queue and returns a partial list of completed jobs
- void `serve_evaluations` ()

run on evaluation servers to serve the iterator master
- void `stop_evaluation_servers` ()

used by the iterator master to terminate evaluation servers
- virtual void `derived_map` (const `Variables` &vars, const `ActiveSet` &set, `Response` &response, int fn_eval_id)

Called by `map()` and other functions to execute the simulation in synchronous mode. The portion of performing an evaluation that is specific to a derived class.
- virtual void `derived_map_asynch` (const `ParamResponsePair` &pair)

Called by `map()` and other functions to execute the simulation in asynchronous mode. The portion of performing an asynchronous evaluation that is specific to a derived class.
- virtual void `derived_synch` (`PRPList` &prp_list)

For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version waits for at least one completion.
- virtual void `derived_synch_nowait` (`PRPList` &prp_list)

For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version is nonblocking and will return without any completions if none are immediately available.
- void `self_schedule_analyses` ()

blocking self-schedule of all analyses within a function evaluation using message passing
- void `serve_analyses_synch` ()

serve the master analysis scheduler and manage one synchronous analysis job at a time

- virtual int `derived_synchronous_local_analysis` (const int &analysis_id)
Execute a particular analysis (identified by analysis_id) synchronously on the local processor. Used for the derived class specifics within `ApplicationInterface::serve_analyses_synch()`.

Protected Attributes

- `ParallelLibrary` & `paralleLib`
reference to the `ParallelLibrary` object used to manage MPI partitions for the concurrent evaluations and concurrent analyses parallelism levels
- bool `suppressOutput`
flag for suppressing output on slave processors
- int `evalCommSize`
size of evalComm
- int `evalCommRank`
processor rank within evalComm
- int `evalServerId`
evaluation server identifier
- bool `eaDedMasterFlag`
flag for dedicated master partitioning at ea level
- int `analysisCommSize`
size of analysisComm
- int `analysisCommRank`
processor rank within analysisComm
- int `analysisServerId`
analysis server identifier
- int `numAnalysisServers`
number of analysis servers
- bool `multiProcAnalysisFlag`
flag for multiprocessor analysis partitions
- bool `asynchLocalAnalysisFlag`
flag for asynchronous local parallelism of analyses
- int `asynchLocalAnalysisConcurrency`

limits the number of concurrent analyses in asynchronous local scheduling and specifies hybrid concurrency when message passing

- int [numAnalysisDrivers](#)
the number of analysis drivers used for each function evaluation (from the `analysis_drivers` interface specification)
- IntSet [completionSet](#)
the set of completed `fn_eval_id`'s populated by `derived_synch()` and `derived_synch_nowait()`

Private Member Functions

- bool [duplication_detect](#) (const [Variables](#) &vars, [Response](#) &response, const bool asynch_flag)
checks `data_pairs` and `beforeSynchCorePRPList` to see if the current evaluation request has already been performed or queued
- void [self_schedule_evaluations](#) ()
blocking self-schedule of all evaluations in `beforeSynchCorePRPList` using message passing; executes on `iteratorComm` master
- void [static_schedule_evaluations](#) ()
blocking static schedule of all evaluations in `beforeSynchCorePRPList` using message passing; executes on `iteratorComm` master
- void [asynchronous_local_evaluations](#) ([PRPList](#) &prp_list)
perform all jobs in `prp_list` using asynchronous approaches on the local processor
- void [synchronous_local_evaluations](#) ([PRPList](#) &prp_list)
perform all jobs in `prp_list` using synchronous approaches on the local processor
- void [asynchronous_local_evaluations_nowait](#) ([PRPList](#) &prp_list)
launch new jobs in `prp_list` asynchronously (if capacity is available), perform nonblocking query of all running jobs, and process any completed jobs
- void [serve_evaluations_synch](#) ()
serve the evaluation message passing schedulers and perform one synchronous evaluation at a time
- void [serve_evaluations_asynch](#) ()
serve the evaluation message passing schedulers and manage multiple asynchronous evaluations
- void [serve_evaluations_peer](#) ()
serve the evaluation message passing schedulers and perform one synchronous evaluation at a time as part of the 1st peer
- void [reset_evaluation_communicators](#) (const [IntArray](#) &message_lengths)
convenience function for updating the local evaluation partition data following `ParallelLibrary::init_evaluation_communicators()`.

- void `reset_analysis_communicators` ()
convenience function for updating the local analysis partition data following `ParallelLibrary::init_analysis_communicators()`.
- const `ParamResponsePair` & `get_source_pair` (const `Variables` &target_vars)
convenience function for the continuation approach in `manage_failure()` for finding the nearest successful "source" evaluation to the failed "target"
- void `continuation` (const `Variables` &target_vars, const `ActiveSet` &set, `Response` &response, const `ParamResponsePair` &source_pair, int failed_eval_id)
performs a 0th order continuation method to step from a successful "source" evaluation to the failed "target". Invoked by `manage_failure()` for failAction == "continuation".
- void `common_input_filtering` (const `Variables` &vars)
common input filtering operations, e.g. mesh movement with DDRIV
- void `common_output_filtering` (`Response` &response)
common output filtering operations, e.g. data filtering

Private Attributes

- int `worldSize`
size of `MPI_COMM_WORLD`
- int `worldRank`
processor rank within `MPI_COMM_WORLD`
- int `iteratorCommSize`
size of `iteratorComm`
- int `iteratorCommRank`
processor rank within `iteratorComm`
- bool `ieMessagePass`
flag for message passing at ie scheduling level
- int `numEvalServers`
number of evaluation servers
- bool `eaMessagePass`
flag for message passing at ea scheduling level
- int `procsPerAnalysis`
processors per analysis servers

- **int lenVarsMessage**
length of a `MPIPackBuffer` containing a `Variables` object; computed in `Model::init_communicators()`
- **int lenVarsActSetMessage**
length of a `MPIPackBuffer` containing a `Variables` object and an `ActiveSet` object; computed in `Model::init_communicators()`
- **int lenResponseMessage**
length of a `MPIPackBuffer` containing a `Response` object; computed in `Model::init_communicators()`
- **int lenPRPairMessage**
length of a `MPIPackBuffer` containing a `ParamResponsePair` object; computed in `Model::init_communicators()`
- **String evalScheduling**
user specification of evaluation scheduling algorithm (self, static, or no spec). Used for manual overrides of the auto-configure logic in `ParallelLibrary::resolve_inputs()`.
- **String analysisScheduling**
user specification of analysis scheduling algorithm (self, static, or no spec). Used for manual overrides of the auto-configure logic in `ParallelLibrary::resolve_inputs()`.
- **int asynchLocalEvalConcurrency**
limits the number of concurrent evaluations in asynchronous local scheduling and specifies hybrid concurrency when message passing
- **String interfaceSynchronization**
interface synchronization specification: synchronous (default) or asynchronous
- **bool headerFlag**
used by `synch_nowait` to manage output frequency (since this function may be called many times prior to any completions)
- **bool asvControlFlag**
used to manage a user request to deactivate the active set vector control. true = modify the ASV each evaluation as appropriate (default); false = ASV values are static so that the user need not check them on each evaluation.
- **bool evalCacheFlag**
used to manage a user request to deactivate the function evaluation cache (i.e., queries and insertions using the `data_pairs` list).
- **bool restartFileFlag**
used to manage a user request to deactivate the restart file (i.e., insertions into `write_restart`).
- **IntArray defaultASV**
the static ASV values used when the user has selected `asvControl = off`

- [String failAction](#)
mitigation action for captured simulation failures: abort, retry, recover, or continuation
- [int failRetryLimit](#)
limit on the number of retries for the retry failAction
- [RealVector failRecoveryFnVals](#)
the dummy function values used for the recover failAction
- [IntList beforeSynchIdList](#)
bookkeeps fnEvalId's of _all_ asynchronous evaluations (new & duplicate)
- [IntResponseMap historyDuplicateMap](#)
used to bookkeep asynchronous evaluations which duplicate data_pairs evaluations. Map key is fnEvalId, mad data is corresponding response.
- [std::map< int, pair< size_t, Response > > beforeSynchDuplicateMap](#)
used to bookkeep fnEvalId, beforeSynchCorePRPList index, and response of asynchronous evaluations which duplicate queued beforeSynchCorePRPList evaluations
- [PRPList beforeSynchCorePRPList](#)
used to bookkeep vars/set/response of nonduplicate asynchronous core evaluations. This is the queue of jobs populated by asynchronous map() that is later scheduled in synch() or synch_nowait().
- [PRPList beforeSynchAlgPRPList](#)
used to bookkeep vars/set/response of asynchronous algebraic evaluations. This is the queue of algebraic jobs populated by asynchronous map() that is later evaluated in synch() or synch_nowait().
- [ResponseList beforeSynchTotalRespList](#)
used to bookkeep total response of asynchronous evaluations with algebraic components but no core mapping components. This is populated by asynchronous map() and later used in synch() or synch_nowait().
- [IntSet runningSet](#)
used by asynchronous_local_nowait to bookkeep which jobs are running

10.6.1 Detailed Description

Derived class within the interface class hierarchy for supporting interfaces to simulation codes.

[ApplicationInterface](#) provides an interface class for performing parameter to response mappings using simulation code(s). It provides common functionality for a number of derived classes and contains the majority of all of the scheduling algorithms in DAKOTA. The derived classes provide the specifics for managing code invocations using system calls, forks, direct procedure calls, or distributed resource facilities.

10.6.2 Member Function Documentation

10.6.2.1 void init_serial () [inline, protected, virtual]

[DataInterface.C](#) defaults of 0 servers are needed to distinguish an explicit user request for 1 server (serialization of a parallelism level) from no user request (use parallel auto-config). This default causes problems when `init_communicators()` is not called for an interface object (e.g., static scheduling fails in `DirectFnApplicInterface::derived_map()` for `NestedModel::optionalInterface`). This is the reason for this function: to reset certain defaults for interface objects that are used serially.

Reimplemented from [Interface](#).

10.6.2.2 void map (const Variables & vars, const ActiveSet & set, Response & response, const bool asynch_flag = false) [protected, virtual]

Provides a "mapping" of variables to responses using a simulation. Protected due to [Interface](#) letter-envelope idiom.

The function evaluator for application interfaces. Called from `derived_compute_response()` and `derived_asynch_compute_response()` in derived [Model](#) classes. If `asynch_flag` is not set, perform a blocking evaluation (using `derived_map()`). If `asynch_flag` is set, add the job to the `beforeSynchCorePRPList` queue for execution by one of the scheduler routines in `synch()` or `synch_nowait()`. Duplicate function evaluations are detected with `duplication_detect()`.

Reimplemented from [Interface](#).

10.6.2.3 const ResponseArray & synch () [protected, virtual]

executes a blocking schedule for asynchronous evaluations in the `beforeSynchCorePRPList` queue and returns all jobs

This function provides blocking synchronization for all cases of asynchronous evaluations, including the local asynchronous case (background system call, nonblocking fork, & multithreads), the message passing case, and the hybrid case. Called from `derived_synchronize()` in derived [Model](#) classes.

Reimplemented from [Interface](#).

10.6.2.4 const IntResponseMap & synch_nowait () [protected, virtual]

executes a nonblocking schedule for asynchronous evaluations in the `beforeSynchCorePRPList` queue and returns a partial list of completed jobs

This function will eventually provide nonblocking synchronization for all cases of asynchronous evaluations, however it currently supports only the local asynchronous case since nonblocking message passing schedulers have not yet been implemented. Called from `derived_synchronize_nowait()` in derived [Model](#) classes.

Reimplemented from [Interface](#).

10.6.2.5 void serve_evaluations () [protected, virtual]

run on evaluation servers to serve the iterator master

Invoked by the `serve()` function in derived [Model](#) classes. Passes control to [serve_evaluations_async\(\)](#), [serve_evaluations_peer\(\)](#), or [serve_evaluations_synch\(\)](#) according to specified concurrency and self/static scheduler configuration.

Reimplemented from [Interface](#).

10.6.2.6 void stop_evaluation_servers () [protected, virtual]

used by the iterator master to terminate evaluation servers

This code is executed on the `iteratorComm` rank 0 processor when iteration on a particular model is complete. It sends a termination signal (`tag = 0` instead of a valid `fn_eval_id`) to each of the slave analysis servers. NOTE: This function is called from the [Strategy](#) layer even when in serial mode. Therefore, use `iteratorCommSize` to provide appropriate fall through behavior.

Reimplemented from [Interface](#).

10.6.2.7 void self_schedule_analyses () [protected]

blocking self-schedule of all analyses within a function evaluation using message passing

This code is called from derived classes to provide the master portion of a master-slave algorithm for the dynamic self-scheduling of analyses among slave servers. It is patterned after [self_schedule_evaluations\(\)](#). It performs no analyses locally and matches either [serve_analyses_synch\(\)](#) or [serve_analyses_async\(\)](#) on the slave servers, depending on the value of `asynchLocalAnalysisConcurrency`. Self-scheduling approach assigns jobs in 2 passes. The 1st pass gives each server the same number of jobs (equal to `asynchLocalAnalysisConcurrency`). The 2nd pass assigns the remaining jobs to slave servers as previous jobs are completed. Single- and multilevel parallel use intra- and inter-communicators, respectively, for send/receive. Specific syntax is encapsulated within [ParallelLibrary](#).

10.6.2.8 void serve_analyses_synch () [protected]

serve the master analysis scheduler and manage one synchronous analysis job at a time

This code is called from derived classes to run synchronous analyses on slave processors. The slaves receive requests (blocking receive), do local derived_map_ac's, and return codes. This is done continuously until a termination signal is received from the master. It is patterned after [serve_evaluations_synch\(\)](#).

10.6.2.9 bool duplication_detect (const Variables & vars, Response & response, const bool asynch_flag) [private]

checks `data_pairs` and `beforeSynchCorePRPList` to see if the current evaluation request has already been performed or queued

Called from [map\(\)](#) to check incoming evaluation request for duplication with content of `data_pairs` and `beforeSynchCorePRPList`. If duplication is detected, return true, else return false. Manage bookkeeping with `history-DuplicateMap` and `beforeSynchDuplicateMap`. Note that the list searches can get very expensive if a long list is searched on every new function evaluation (either from a large number of previous jobs, a large number of pending jobs, or both). For this reason, a user request for deactivation of the evaluation cache results in a complete bypass

of [duplication_detect\(\)](#), even though a `beforeSynchCorePRPList` search would still be meaningful. Since the intent of this request is to streamline operations, both list searches are bypassed.

10.6.2.10 `void self_schedule_evaluations () [private]`

blocking self-schedule of all evaluations in `beforeSynchCorePRPList` using message passing; executes on iteratorComm master

This code is called from [synch\(\)](#) to provide the master portion of a master-slave algorithm for the dynamic self-scheduling of evaluations among slave servers. It performs no evaluations locally and matches either [serve_evaluations_synch\(\)](#) or [serve_evaluations_asynch\(\)](#) on the slave servers, depending on the value of `asynchLocalEvalConcurrency`. Self-scheduling approach assigns jobs in 2 passes. The 1st pass gives each server the same number of jobs (equal to `asynchLocalEvalConcurrency`). The 2nd pass assigns the remaining jobs to slave servers as previous jobs are completed. Single- and multilevel parallel use intra- and inter-communicators, respectively, for send/receive. Specific syntax is encapsulated within [ParallelLibrary](#).

10.6.2.11 `void static_schedule_evaluations () [private]`

blocking static schedule of all evaluations in `beforeSynchCorePRPList` using message passing; executes on iteratorComm master

This code runs on the `iteratorCommRank 0` processor (the iterator) and is called from [synch\(\)](#) in order to assign a static schedule. It matches [serve_evaluations_peer\(\)](#) for any other processors within the 1st evaluation partition and [serve_evaluations_synch\(\)/serve_evaluations_asynch\(\)](#) for all other evaluation partitions (depending on `asynchLocalEvalConcurrency`). It performs function evaluations locally for its portion of the static schedule using either [asynchronous_local_evaluations\(\)](#) or [synchronous_local_evaluations\(\)](#). Single-level and multilevel parallel use intra- and inter-communicators, respectively, for send/receive. Specific syntax is encapsulated within [ParallelLibrary](#). The `iteratorCommRank 0` processor assigns the static schedule since it is the only processor with access to `beforeSynchCorePRPList` (it runs the iterator and calls `synchronize`). The alternate design of each peer selecting its own jobs using the modulus operator would be applicable if execution of this function (and therefore the job list) were distributed.

10.6.2.12 `void asynchronous_local_evaluations (PRPList & prp_list) [private]`

perform all jobs in `prp_list` using asynchronous approaches on the local processor

This function provides blocking synchronization for the local asynch case (background system call, non-blocking fork, or threads). It can be called from [synch\(\)](#) for a complete local scheduling of all asynchronous jobs or from [static_schedule_evaluations\(\)](#) to perform a local portion of the total job set. It uses the [derived_map_asynch\(\)](#) to initiate asynchronous evaluations and [derived_synch\(\)](#) to capture completed jobs, and mirrors the [self_schedule_evaluations\(\)](#) message passing scheduler as much as possible ([derived_synch\(\)](#) is modeled after `MPI_Waitsome()`).

10.6.2.13 `void synchronous_local_evaluations (PRPList & prp_list) [private]`

perform all jobs in `prp_list` using synchronous approaches on the local processor

This function provides blocking synchronization for the local synchronous case (foreground system call, blocking fork, or procedure call from [derived_map\(\)](#)). It is called from [static_schedule_evaluations\(\)](#) to perform a local

portion of the total job set.

10.6.2.14 void asynchronous_local_evaluations_nowait (PRPList & prp_list) [private]

launch new jobs in prp_list asynchronously (if capacity is available), perform nonblocking query of all running jobs, and process any completed jobs

This function provides nonblocking synchronization for the local asynch case (background system call, non-blocking fork, or threads). It is called from [synch_nowait\(\)](#) and passed the complete set of all asynchronous jobs (beforeSynchCorePRPList). It uses [derived_map_asynch\(\)](#) to initiate asynchronous evaluations and [derived_synch_nowait\(\)](#) to capture completed jobs in nonblocking mode. It mirrors a nonblocking message passing scheduler as much as possible ([derived_synch_nowait\(\)](#) modeled after `MPI_Testsome()`). The result of this function is `rawResponseMap`, which uses `fn_eval_id` as a key. It is assumed that the incoming prp_list contains only active and new jobs - i.e., all completed jobs are cleared by [synch_nowait\(\)](#).

10.6.2.15 void serve_evaluations_synch () [private]

serve the evaluation message passing schedulers and perform one synchronous evaluation at a time

This code is invoked by [serve_evaluations\(\)](#) to perform one synchronous job at a time on each slave/peer server. The servers receive requests (blocking receive), do local synchronous maps, and return results. This is done continuously until a termination signal is received from the master (sent via [stop_evaluation_servers\(\)](#)).

10.6.2.16 void serve_evaluations_asynch () [private]

serve the evaluation message passing schedulers and manage multiple asynchronous evaluations

This code is invoked by [serve_evaluations\(\)](#) to perform multiple asynchronous jobs on each slave/peer server. The servers test for any incoming jobs, launch any new jobs, process any completed jobs, and return any results. Each of these components is nonblocking, although the server loop continues until a termination signal is received from the master (sent via [stop_evaluation_servers\(\)](#)). In the master-slave case, the master maintains the correct number of jobs on each slave. In the static scheduling case, each server is responsible for limiting concurrency (since the entire static schedule is sent to the peers at start up).

10.6.2.17 void serve_evaluations_peer () [private]

serve the evaluation message passing schedulers and perform one synchronous evaluation at a time as part of the 1st peer

This code is invoked by [serve_evaluations\(\)](#) to perform a synchronous evaluation in coordination with the iteratorCommRank 0 processor (the iterator) for static schedules. The `bcast()` matches either the `bcast()` in [synchronous_local_evaluations\(\)](#), which is invoked by [static_schedule_evaluations\(\)](#), or the `bcast()` in [map\(\)](#).

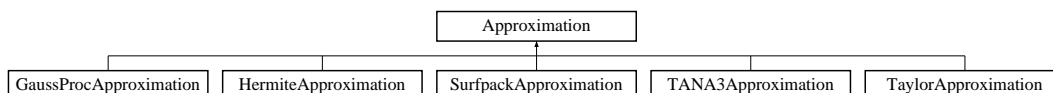
The documentation for this class was generated from the following files:

- ApplicationInterface.H
- ApplicationInterface.C

10.7 Approximation Class Reference

Base class for the approximation class hierarchy.

Inheritance diagram for Approximation::



Public Member Functions

- [Approximation](#) ()
default constructor
- [Approximation](#) ([ProblemDescDB](#) &problem_db, const size_t &num_acv)
standard constructor for envelope
- [Approximation](#) (const [String](#) &approx_type, const size_t &num_acv)
alternate constructor
- [Approximation](#) (const [Approximation](#) &approx)
copy constructor
- virtual [~Approximation](#) ()
destructor
- [Approximation operator=](#) (const [Approximation](#) &approx)
assignment operator
- virtual const [Real](#) & [get_value](#) (const [RealVector](#) &x)
retrieve the approximate function value for a given parameter vector
- virtual const [RealBaseVector](#) & [get_gradient](#) (const [RealVector](#) &x)
retrieve the approximate function gradient for a given parameter vector
- virtual const [RealMatrix](#) & [get_hessian](#) (const [RealVector](#) &x)
retrieve the approximate function Hessian for a given parameter vector
- virtual const [RealVector](#) & [approximation_coefficients](#) ()
return the coefficient array computed by [find_coefficients\(\)](#)

- virtual int `num_coefficients` () const
return the minimum number of samples required to build the derived class approximation type in numVars dimensions
- virtual int `num_constraints` () const
return the number of constraints to be enforced via anchorPoint
- virtual void `clear_current` ()
clear current build data in preparation for next build
- virtual void `second_order_flag` (bool flag)
set the Approximation's secondOrderFlag, if present
- int `required_samples` (bool constraint_flag) const
return the minimum number of samples required to build the approximation type in numVars dimensions. Uses `num_coefficients()` and `num_constraints()`.
- int `num_variables` () const
return the number of variables used in the approximation
- void `update` (const `RealVectorArray` &c_vars_samples, const `ResponseArray` &resp_samples, const int &fn_index)
populates currentPoints
- void `update` (const `RealVector` &c_vars, const `Response` &response, const int &fn_index)
populates anchorPoint
- void `update` (const `RealVector` &c_vars, const Real &fn_val, const `RealBaseVector` &fn_grad, const `RealMatrix` &fn_hess)
populates anchorPoint
- void `append` (const `RealVector` &c_vars, const `Response` &response, const int &fn_index)
appends one additional entry to currentPoints
- void `append` (const `RealVector` &c_vars, const Real &fn_val, const `RealBaseVector` &fn_grad, const `RealMatrix` &fn_hess)
appends one additional entry to currentPoints
- void `build` ()
builds the approximation by invoking `find_coefficients()`.
- bool `anchor` () const
queries the status of anchorPoint
- void `clear_all` ()
clear all build data (current and history) to restore original state.

- void `set_bounds` (const [RealVector](#) &lower, const [RealVector](#) &upper)
set approximation lower and upper bounds (currently only used by graphics)
- void `draw_surface` ()
render the approximate surface using the 3D graphics (2 variable problems only).

Protected Member Functions

- [Approximation](#) ([BaseConstructor](#), [ProblemDescDB](#) &problem_db, const size_t &num_acv)
constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)
- virtual void `find_coefficients` ()
calculate the data fit coefficients using `currentPoints` and `anchorPoint`

Protected Attributes

- bool `useGradsFlag`
flag signaling the use of gradient data in global approximation builds as indicated by the user's `use_gradients` specification. This setting cannot be inferred from the `responses spec.`, since we may need gradient support for evaluating gradients at a single point (e.g., the center of a trust region), but not require gradient evaluations at every point.
- bool `verboseFlag`
flag for verbose approximation output
- int `numVars`
number of variables in the approximation
- String `approxType`
approximation type identifier
- Real `approxValue`
value of the approximation returned by `get_value()`
- [RealBaseVector](#) `approxGradient`
gradient of the approximation returned by `get_gradient()`
- [RealMatrix](#) `approxHessian`
Hessian of the approximation returned by `get_hessian()`.
- List< [SurrogateDataPoint](#) > `currentPoints`

list of samples used to build the approximation. These sample points may be fit approximately (based on a least squares regression).

- **SurrogateDataPoint anchorPoint**

a special sample (often at the center of the approximation region) for which exact matching is enforced (e.g., using equality-constrained least squares)

Private Member Functions

- **Approximation * get_approx (ProblemDescDB &problem_db, const size_t &num_acv)**

Used only by the standard envelope constructor to initialize approxRep to the appropriate derived type.

- **Approximation * get_approx (const String &approx_type, const size_t &num_acv)**

Used only by the alternate envelope constructor to initialize approxRep to the appropriate derived type.

- **void add (const RealVector &c_vars, const Response &response, const int &fn_index, bool anchor_flag)**

add a new data point by either appending to currentPoints or assigning to anchorPoint, as dictated by anchor_flag. Uses add_point() and add_anchor().

- **void add_point (const RealVector &x, const Real &fn_val, const RealBaseVector &fn_grad, const RealMatrix &fn_hess)**

add a new data point by appending to currentPoints

- **void add_anchor (const RealVector &x, const Real &fn_val, const RealBaseVector &fn_grad, const RealMatrix &fn_hess)**

add a new data point by assigning to anchorPoint

Private Attributes

- **RealVector approxLowerBounds**

approximation lower bounds (used only by 3D graphics)

- **RealVector approxUpperBounds**

approximation upper bounds (used only by 3D graphics)

- **Approximation * approxRep**

pointer to the letter (initialized only for the envelope)

- **int referenceCount**

number of objects sharing approxRep

10.7.1 Detailed Description

Base class for the approximation class hierarchy.

The [Approximation](#) class is the base class for the data fit surrogate class hierarchy in DAKOTA. One instance of an [Approximation](#) must be created for each function to be approximated (a vector of Approximations is contained in [ApproximationInterface](#)). For memory efficiency and enhanced polymorphism, the approximation hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Approximation](#)) serves as the envelope and one of the derived classes (selected in `Approximation::get_approximation()`) serves as the letter.

10.7.2 Constructor & Destructor Documentation

10.7.2.1 [Approximation](#) ()

default constructor

The default constructor is used in `List<Approximation>` instantiations and by the alternate envelope constructor. `approxRep` is NULL in this case (`problem_db` is needed to build a meaningful [Model](#) object). This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

10.7.2.2 [Approximation](#) ([ProblemDescDB](#) & *problem_db*, *const size_t* & *num_acv*)

standard constructor for envelope

Envelope constructor only needs to extract enough data to properly execute `get_approx`, since `Approximation(BaseConstructor, problem_db)` builds the actual base class data for the derived approximations.

10.7.2.3 [Approximation](#) (*const String* & *approx_type*, *const size_t* & *num_acv*)

alternate constructor

This is the alternate envelope constructor for instantiations on the fly. Since it does not have access to `problem_db`, the letter class is not fully populated. This constructor executes `get_approx(type)`, which invokes the default constructor of the derived letter class, which in turn invokes the default constructor of the base class.

10.7.2.4 [Approximation](#) (*const Approximation* & *approx*)

copy constructor

Copy constructor manages sharing of `approxRep` and incrementing of `referenceCount`.

10.7.2.5 `~Approximation` () [virtual]

destructor

Destructor decrements referenceCount and only deletes approxRep when referenceCount reaches zero.

10.7.2.6 **Approximation** (**BaseConstructor**, **ProblemDescDB** & *problem_db*, **const size_t** & *num_acv*) [protected]

constructor initializes the base class part of letter classes (**BaseConstructor** overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all derived classes. [get_approx\(\)](#) instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list (to avoid recursion in the base class constructor calling [get_approx\(\)](#) again). Since the letter IS the representation, its rep pointer is set to NULL (an uninitialized pointer causes problems in `~Approximation`).

10.7.3 Member Function Documentation

10.7.3.1 **Approximation** operator= (**const Approximation** & *approx*)

assignment operator

Assignment operator decrements referenceCount for old approxRep, assigns new approxRep, and increments referenceCount for new approxRep.

10.7.3.2 **void clear_current** () [virtual]

clear current build data in preparation for next build

Redefined by [TANA3Approximation](#) to clear current data but preserve history.

Reimplemented in [TANA3Approximation](#).

10.7.3.3 **void second_order_flag** (**bool flag**) [virtual]

set the Approximation's secondOrderFlag, if present

Redefined by [TaylorApproximation](#) to set secondOrderFlag.

Reimplemented in [TaylorApproximation](#).

10.7.3.4 **void clear_all** ()

clear all build data (current and history) to restore original state.

Clears out any history (e.g., [TANA3Approximation](#) use for a different response function in [NonDReliability](#)).

10.7.3.5 **Approximation** * **get_approx** (**ProblemDescDB** & *problem_db*, const **size_t** & *num_acv*)
[private]

Used only by the standard envelope constructor to initialize approxRep to the appropriate derived type.

Used only by the envelope constructor to initialize approxRep to the appropriate derived type.

10.7.3.6 **Approximation** * **get_approx** (const **String** & *approx_type*, const **size_t** & *num_acv*)
[private]

Used only by the alternate envelope constructor to initialize approxRep to the appropriate derived type.

Used only by the envelope constructor to initialize approxRep to the appropriate derived type.

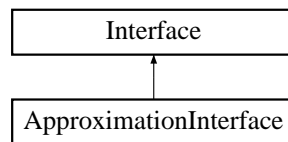
The documentation for this class was generated from the following files:

- DakotaApproximation.H
- DakotaApproximation.C

10.8 ApproximationInterface Class Reference

Derived class within the interface class hierarchy for supporting approximations to simulation-based results.

Inheritance diagram for ApproximationInterface::



Public Member Functions

- [ApproximationInterface](#) ([ProblemDescDB](#) &problem_db, const size_t &num_acv, const size_t &num_fns)

constructor

- [~ApproximationInterface](#) ()

destructor

Protected Member Functions

- void [map](#) (const [Variables](#) &vars, const [ActiveSet](#) &set, [Response](#) &response, const bool asynch_flag=false)

the function evaluator: provides an approximate "mapping" from the variables to the responses using functionSurfaces

- int [minimum_samples](#) (bool constraint_flag) const

returns the minimum number of samples required to build the functionSurfaces

- void [update_approximation](#) (const [RealVectorArray](#) &all_variables, const [ResponseArray](#) &all_responses)

passes multiple points to an approximation for building a surrogate

- void [update_approximation](#) (const [RealVector](#) &c_variables, const [Response](#) &response)
- void [build_approximation](#) (const [RealVector](#) &lower_bnds, const [RealVector](#) &upper_bnds)
- void [append_approximation](#) (const [RealVector](#) &c_variables, const [Response](#) &response)

updates an existing global approximation with new data

- void [clear](#) ()

clears all data from an approximation interface

- bool [anchor](#) () const
queries the presence of an `anchorPoint` within an approximation interface
- const [RealVectorArray](#) & [approximation_coefficients](#) ()
retrieve the approximation coefficients from each `Approximation` within an `ApproximationInterface`
- const [ResponseArray](#) & [synch](#) ()
recovers data from a series of asynchronous evaluations (blocking)
- const [IntResponseMap](#) & [synch_nowait](#) ()
recovers data from a series of asynchronous evaluations (nonblocking)

Private Attributes

- bool [completeApproxSet](#)
flag for complete approximation set (no mixture of truth/approx responses at `Model` level)
- [IntArray](#) [approxFnIds](#)
for incomplete approximation sets, this array specifies the response function subset that is approximated
- [Array](#)< [Approximation](#) > [functionSurfaces](#)
list of approximations, one per response function
- [RealVectorArray](#) [functionSurfaceCoeffs](#)
array of approximation coefficient vectors, one vector per response function
- bool [graphicsFlag](#)
controls 3D graphics of approximation surfaces
- [IntResponseMap](#) [beforeSynchResponseMap](#)
bookkeeping map to catalogue responses generated in `map()` for use in `synch()` and `synch_nowait()`. This supports pseudo-asynchronous operations (approximate responses are always computed synchronously, but asynchronous virtual functions are supported through bookkeeping).

10.8.1 Detailed Description

Derived class within the interface class hierarchy for supporting approximations to simulation-based results.

[ApproximationInterface](#) provides an interface class for building a set of global/local/multipoint approximations and performing approximate function evaluations using them. It contains a list of [Approximation](#) objects, one for each response function.

10.8.2 Member Function Documentation

10.8.2.1 `void update_approximation (const RealVector & c_variables, const Response & response)`
[protected, virtual]

Evaluate values, gradients, and possibly Hessians at the current point for building a local approximation.

Reimplemented from [Interface](#).

10.8.2.2 `void build_approximation (const RealVector & lower_bnds, const RealVector & upper_bnds)`
[protected, virtual]

Evaluate values, gradients, and possibly Hessians at the current point for building a local approximation.

Reimplemented from [Interface](#).

10.8.3 Member Data Documentation

10.8.3.1 `Array<Approximation> functionSurfaces` [private]

list of approximations, one per response function

This formulation allows the use of mixed approximations (i.e., different approximations used for different response functions), although the input specification is not currently general enough to support it.

The documentation for this class was generated from the following files:

- ApproximationInterface.H
- ApproximationInterface.C

10.9 Array Class Template Reference

Template class for the [Dakota](#) bookkeeping array.

Public Member Functions

- [Array](#) ()
Default constructor.
- [Array](#) (size_t size)
Constructor which takes an initial size.
- [Array](#) (size_t size, const T &initial_val)
Constructor which takes an initial size and an initial value.
- [Array](#) (const [Array](#)< T > &a)
Copy constructor.
- [Array](#) (const T *p, size_t size)
Constructor which copies size entries from T.*
- [~Array](#) ()
Destructor.
- [Array](#)< T > & [operator=](#) (const [Array](#)< T > &a)
Normal const assignment operator.
- [Array](#)< T > & [operator=](#) ([Array](#)< T > &a)
Normal assignment operator.
- [Array](#)< T > & [operator=](#) (const T &ival)
Sets all elements in self to the value ival.
- [operator T *](#) () const
Converts the [Array](#) to a standard C-style array. Use with care!
- T & [operator](#)[] (int i)
alternate bounds-checked indexing operator for int indices
- const T & [operator](#)[] (int i) const
alternate bounds-checked const indexing operator for int indices

- `T & operator[] (size_t i)`
*Index operator, returns the *i*th value of the array.*
- `const T & operator[] (size_t i) const`
*Index operator const, returns the *i*th value of the array.*
- `T & operator() (size_t i)`
Index operator, not bounds checked.
- `const T & operator() (size_t i) const`
Index operator const, not bounds checked.
- `void read (istream &s)`
*Reads an *Array* from an *istream*.*
- `void write (ostream &s) const`
*Writes an *Array* to an output stream.*
- `void write (ostream &s, const Array< String > &label_array) const`
*Writes an *Array* and associated label array to an output stream.*
- `void write_aprepro (ostream &s, const Array< String > &label_array) const`
*Writes an *Array* and associated label array to an output stream in *aprepro* format.*
- `void write_annotated (ostream &s, bool write_len) const`
*Writes an *Array* to an output stream in annotated format.*
- `void read (BiStream &s)`
*Reads an *Array* from a binary input stream.*
- `void write (BoStream &s) const`
*Writes an *Array* to a binary output stream.*
- `void read (MPIUnpackBuffer &s)`
*Reads an *Array* from a buffer after an *MPI* receive.*
- `void write (MPIPackBuffer &s) const`
*Writes an *Array* to a buffer prior to an *MPI* send.*
- `size_t length () const`
Returns size of array.
- `void reshape (size_t sz)`
*Resizes array to size *sz*.*
- `size_t index (const T &a) const`

Returns the index of the first array item which matches the object *a*.

- bool `contains` (const T &a) const

Checks if the array contains an object which matches the object *a*.

- size_t `count` (const T &a) const

Returns the number of items in the array matching the object *a*.

- const T * `data` () const

Returns pointer T* to continuous data.

10.9.1 Detailed Description

```
template<class T> class Dakota::Array< T >
```

Template class for the [Dakota](#) bookkeeping array.

An array class template that provides additional functionality that is specific to Dakota's needs. The [Array](#) class adds additional functionality needed by [Dakota](#) to the inherited base array class. The [Array](#) class can inherit from either the STL or RW vector classes.

10.9.2 Constructor & Destructor Documentation

10.9.2.1 `Array` (const T * *p*, size_t *size*) [inline]

Constructor which copies size entries from T*.

Assigns size values from p into array.

10.9.3 Member Function Documentation

10.9.3.1 `Array`< T > & `operator=` (const T & *ival*) [inline]

Sets all elements in self to the value *ival*.

Assigns all values of array to the value passed in as *ival*. For the Rogue Wave case, utilizes base class `operator=(ival)`, while for the ANSI case, uses the STL `assign()` method.

10.9.3.2 operator T * () const [inline]

Converts the [Array](#) to a standard C-style array. Use with care!

The operator() returns a c style pointer to the data within the array. Calls the [data\(\)](#) method. USE WITH CARE.

10.9.3.3]

T & operator[] (size_t i) [inline]

Index operator, returns the ith value of the array.

Index operator; calls the STL method at() which is bounds checked. Mimics the RW vector class. Note: the at() method is not supported by the __GNUC__ STL implementation or by builds omitting exceptions (e.g., SIERRA).

10.9.3.4]

const T & operator[] (size_t i) const [inline]

Index operator const, returns the ith value of the array.

A const version of the index operator; calls the STL method at() which is bounds checked. Mimics the RW vector class. Note: the at() method is not supported by the __GNUC__ STL implementation or by builds omitting exceptions (e.g., SIERRA).

10.9.3.5 T & operator() (size_t i) [inline]

Index operator, not bounds checked.

Non bounds check index operator, calls the STL operator[] which is not bounds checked. Needed to mimic the RW vector class

10.9.3.6 const T & operator() (size_t i) const [inline]

Index operator const, not bounds checked.

A const version of the non-bounds check index operator, calls the STL operator[] which is not bounds checked. Needed to mimic the RW vector class

10.9.3.7 const T * data () const [inline]

Returns pointer T* to continuous data.

Returns a C style pointer to the data within the array. USE WITH CARE. Needed to mimic RW vector class, is used in the operator(). Uses the STL front method.

The documentation for this class was generated from the following file:

- DakotaArray.H

10.10 BaseConstructor Struct Reference

Dummy struct for overloading letter-envelope constructors.

Public Member Functions

- [BaseConstructor](#) (int=0)

C++ structs can have constructors.

10.10.1 Detailed Description

Dummy struct for overloading letter-envelope constructors.

[BaseConstructor](#) is used to overload the constructor for the base class portion of letter objects. It avoids infinite recursion (Coplien p.139) in the letter-envelope idiom by preventing the letter from instantiating another envelope. Putting this struct here avoids circular dependencies.

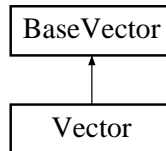
The documentation for this struct was generated from the following file:

- `global_defs.h`

10.11 BaseVector Class Template Reference

Base class for the [Dakota::Matrix](#) and [Dakota::Vector](#) classes.

Inheritance diagram for BaseVector::



Public Member Functions

- [BaseVector](#) ()
Default constructor.
- [BaseVector](#) (size_t size)
Constructor, creates vector of size.
- [BaseVector](#) (size_t size, const T &initial_val)
Constructor, creates vector of size with initial value of initial_val.
- [~BaseVector](#) ()
Destructor.
- [BaseVector](#) (const [BaseVector](#)< T > &a)
Copy constructor.
- [BaseVector](#)< T > & [operator=](#) (const [BaseVector](#)< T > &a)
Normal assignment operator.
- [BaseVector](#)< T > & [operator=](#) (const T &ival)
Assigns all values of vector to ival.
- T & [operator](#)[] (int i)
alternate bounds-checked indexing operator for int indices
- const T & [operator](#)[] (int i) const
alternate bounds-checked const indexing operator for int indices
- T & [operator](#)[] (size_t i)
Returns the object at index i, (can use as lvalue).

- `const T & operator[] (size_t i) const`
Returns the object at index i, const (can't use as lvalue).
- `T & operator() (size_t i)`
Index operator, not bounds checked.
- `const T & operator() (size_t i) const`
Index operator const , not bounds checked.
- `size_t length () const`
Returns size of vector.
- `void reshape (size_t sz)`
Resizes vector to size sz.
- `const T * data () const`
Returns const pointer to standard C array. Use with care.

Protected Member Functions

- `T * array () const`
Returns pointer to standard C array. Use with care.

10.11.1 Detailed Description

`template<class T> class Dakota::BaseVector< T >`

Base class for the [Dakota::Matrix](#) and [Dakota::Vector](#) classes.

The `Dakota::BaseVector` class is the base class for the [Dakota::Matrix](#) class. It is used to define a common vector interface for both the STL and RW vector classes. If the STL version is based on the `valarray` class then some basic vector operations such as `+`, `*` are available.

10.11.2 Constructor & Destructor Documentation

10.11.2.1 [BaseVector](#) (size_t size, const T & initial_val) [inline]

Constructor, creates vector of size with initial value of `initial_val`.

Constructor which takes an initial size and an initial value, allocates an area of initial size and initializes it with input value. Calls base class constructor

10.11.3 Member Function Documentation

10.11.3.1]

`T & operator[] (size_t i) [inline]`

Returns the object at index `i`, (can use as lvalue).

Index operator, calls the STL method `at()` which is bounds checked. Mimics the RW vector class. Note: the `at()` method is not supported by the `__GNUC__` STL implementation or by builds omitting exceptions (e.g., SIERRA).

10.11.3.2]

`const T & operator[] (size_t i) const [inline]`

Returns the object at index `i`, `const` (can't use as lvalue).

Const versions of the index operator calls the STL method `at()` which is bounds checked. Mimics the RW vector class. Note: the `at()` method is not supported by the `__GNUC__` STL implementation or by builds omitting exceptions (e.g., SIERRA).

10.11.3.3 `T & operator() (size_t i) [inline]`

Index operator, not bounds checked.

Non bounds check index operator, calls the STL `operator[]` which is not bounds checked. Needed to mimic the RW vector class

10.11.3.4 `const T & operator() (size_t i) const [inline]`

Index operator `const`, not bounds checked.

Const version of the non-bounds check index operator, calls the STL `operator[]` which is not bounds checked. Needed to mimic the RW vector class

10.11.3.5 `size_t length () const [inline]`

Returns size of vector.

Returns the length of the array by calling the STL `size` method. Needed to mimic the RW vector class

10.11.3.6 `void reshape (size_t sz) [inline]`

Resizes vector to size `sz`.

Resizes the array to size `sz` by calling the STL `resize` method. Needed to mimic the RW vector class

10.11.3.7 `const T * data () const` [inline]

Returns const pointer to standard C array. Use with care.

Returns a const pointer to the data within the array. USE WITH CARE. Needed to mimic RW vector class.

10.11.3.8 `T * array () const` [inline, protected]

Returns pointer to standard C array. Use with care.

Returns a non-const pointer to the data within the array. Non-const version of [data\(\)](#) used by derived classes.

The documentation for this class was generated from the following file:

- DakotaBaseVector.H

10.12 BiStream Class Reference

The binary input stream class. Overloads the >> operator for all data types.

Public Member Functions

- [BiStream \(\)](#)
Default constructor, need to open.
- [BiStream \(const char *s\)](#)
Constructor takes name of input file.
- [BiStream \(const char *s, std::ios_base::openmode mode\)](#)
Constructor takes name of input file, mode.
- [BiStream \(const char *s, int mode\)](#)
Constructor takes name of input file, mode.
- [~BiStream \(\)](#)
Destructor, calls `xdr_destroy` to delete `xdr` stream.
- [BiStream & operator>> \(String &ds\)](#)
Binary Input stream operator>>.
- [BiStream & operator>> \(char *s\)](#)
Input operator, reads `char` from binary stream [BiStream](#).*
- [BiStream & operator>> \(char &c\)](#)
Input operator, reads `char` from binary stream [BiStream](#).
- [BiStream & operator>> \(int &i\)](#)
Input operator, reads `int` from binary stream [BiStream](#).*
- [BiStream & operator>> \(long &l\)](#)
Input operator, reads `long` from binary stream [BiStream](#).
- [BiStream & operator>> \(short &s\)](#)
Input operator, reads `short` from binary stream [BiStream](#).
- [BiStream & operator>> \(bool &b\)](#)
Input operator, reads `bool` from binary stream [BiStream](#).

- [BiStream](#) & [operator>>](#) (double &d)
Input operator, reads double from binary stream [BiStream](#).
- [BiStream](#) & [operator>>](#) (float &f)
Input operator, reads float from binary stream [BiStream](#).
- [BiStream](#) & [operator>>](#) (unsigned char &c)
Input operator, reads unsigned char from binary stream [BiStream](#).*
- [BiStream](#) & [operator>>](#) (unsigned int &i)
Input operator, reads unsigned int from binary stream [BiStream](#).
- [BiStream](#) & [operator>>](#) (unsigned long &l)
Input operator, reads unsigned long from binary stream [BiStream](#).
- [BiStream](#) & [operator>>](#) (unsigned short &s)
Input operator, reads unsigned short from binary stream [BiStream](#).

Private Attributes

- XDR [xdrInBuf](#)
XDR input stream buffer.
- char [inBuf](#) [MAX_NETOBJ_SZ]
Buffer to hold data as it is read in.

10.12.1 Detailed Description

The binary input stream class. Overloads the >> operator for all data types.

The Dakota::BiStream class is a binary input class which overloads the >> operator for all standard data types (int, char, float, etc). The class relies on the methods within the ifstream base class. The Dakota::BiStream class inherits from the ifstream class. If available, the class utilize rpc/xdr to construct machine independent binary files. These [Dakota](#) restart files can be moved from host to host. The motivation to develop these classes was to replace the Rogue wave classes which [Dakota](#) historically used for binary I/O.

10.12.2 Constructor & Destructor Documentation

10.12.2.1 **BiStream** ()

Default constructor, need to open.

Default constructor, allocates xdr stream , but does not call the open method. The open method must be called before stream can be read.

10.12.2.2 **BiStream** (const char * s)

Constructor takes name of input file.

Constructor which takes a char* filename. Calls the base class open method with the filename and no other arguments. Also allocates the xdr stream.

10.12.2.3 **BiStream** (const char * s, std::ios_base::openmode mode)

Constructor takes name of input file, mode.

Constructor which takes a char* filename and int flags. Calls the base class open method with the filename and flags as arguments. Also allocates xdr stream.

10.12.2.4 **~BiStream** ()

Destructor, calls xdr_destroy to delete xdr stream.

Destructor, destroys the xdr stream allocated in constructor

10.12.3 Member Function Documentation

10.12.3.1 **BiStream** & operator>> (String & ds)

Binary Input stream operator>>.

The **String** input operator must first read both the xdr buffer size and the size of the string written. Once these are read it can then read and convert the **String** correctly.

10.12.3.2 **BiStream** & operator>> (char * s)

Input operator, reads char* from binary stream **BiStream**.

Reading char array is a special case. The method has no way of knowing if the length to the input array is large enough, it assumes it is one char longer than actual string, (Null terminator added). As with the **String** the size of the xdr buffer as well as the char array size written must be read from the stream prior to reading and converting the char array.

The documentation for this class was generated from the following files:

- [DakotaBinStream.H](#)
- [DakotaBinStream.C](#)

10.13 BoStream Class Reference

The binary output stream class. Overloads the << operator for all data types.

Public Member Functions

- [BoStream \(\)](#)
Default constructor, need to open.
- [BoStream \(const char *s\)](#)
Constructor takes name of input file.
- [BoStream \(const char *s, std::ios_base::openmode mode\)](#)
Constructor takes name of input file, mode.
- [BoStream \(const char *s, int mode\)](#)
Constructor takes name of input file, mode.
- [~BoStream \(\)](#)
Destructor, calls `xdr_destroy` to delete xdr stream.
- [BoStream & operator<< \(const String &ds\)](#)
Binary Output stream operator<<.
- [BoStream & operator<< \(const char *s\)](#)
Output operator, writes char TO binary stream [BoStream](#).*
- [BoStream & operator<< \(const char &c\)](#)
Output operator, writes char to binary stream [BoStream](#).
- [BoStream & operator<< \(const int &i\)](#)
Output operator, writes int to binary stream [BoStream](#).
- [BoStream & operator<< \(const long &l\)](#)
Output operator, writes long to binary stream [BoStream](#).
- [BoStream & operator<< \(const short &s\)](#)
Output operator, writes short to binary stream [BoStream](#).
- [BoStream & operator<< \(const bool &b\)](#)
Output operator, writes bool to binary stream [BoStream](#).

- [BoStream](#) & `operator<<` (const double &d)
Output operator, writes double to binary stream [BoStream](#).
- [BoStream](#) & `operator<<` (const float &f)
Output operator, writes float to binary stream [BoStream](#).
- [BoStream](#) & `operator<<` (const unsigned char &c)
Output operator, writes unsigned char to binary stream [BoStream](#).
- [BoStream](#) & `operator<<` (const unsigned int &i)
Output operator, writes unsigned int to binary stream [BoStream](#).
- [BoStream](#) & `operator<<` (const unsigned long &l)
Output operator, writes unsigned long to binary stream [BoStream](#).
- [BoStream](#) & `operator<<` (const unsigned short &s)
Output operator, writes unsigned short to binary stream [BoStream](#).

Private Attributes

- XDR [xdrOutBuf](#)
XDR output stream buffer.
- char [outBuf](#) [MAX_NETOBJ_SZ]
Buffer to hold converted data before it is written.

10.13.1 Detailed Description

The binary output stream class. Overloads the << operator for all data types.

The `Dakota::BoStream` class is a binary output classes which overloads the << operator for all standard data types (int, char, float, etc). The class relies on the built in write methods within the ostream base classes. `Dakota::BoStream` inherits from the ostream class. The motivation to develop this class was to replace the Rogue wave class which [Dakota](#) historically used for binary I/O. If available, the class utilize rpc/xdr to construct machine independent binary files. These [Dakota](#) restart files can be moved between hosts.

10.13.2 Constructor & Destructor Documentation

10.13.2.1 **BoStream** ()

Default constructor, need to open.

Default constructor allocates the xdr stream but does not call the open() method. The open() method must be called before stream can be written to.

10.13.2.2 **BoStream** (const char * s)

Constructor takes name of input file.

Constructor, takes char * filename as argument. Calls base class open method with filename and no other arguments. Also allocates xdr stream

10.13.2.3 **BoStream** (const char * s, std::ios_base::openmode mode)

Constructor takes name of input file, mode.

Constructor, takes char * filename and int flags as arguments. Calls base class open method with filename and flags as arguments. Also allocates xdr stream. Note : If no rpc/xdr support xdr calls are #ifdef'd out.

10.13.3 Member Function Documentation

10.13.3.1 **BoStream** & operator<< (const **String** & ds)

Binary Output stream operator<<.

The **String** operator<< must first write the xdr buffer size and the original string size to the stream. The input operator needs this information to be able to correctly read and convert the **String**.

10.13.3.2 **BoStream** & operator<< (const char * s)

Output operator, writes char* TO binary stream **BoStream**.

The output of char* is the same as the output of the **String**. The size of the xdr buffer and the size of the string must be written first, then the string itself.

The documentation for this class was generated from the following files:

- DakotaBinStream.H
- DakotaBinStream.C

10.14 COLINApplication Class Reference

Public Member Functions

- [COLINApplication](#) ([Model](#) &model, [Optimizer](#) *opt_)
constructor
- [~COLINApplication](#) ()
destructor
- void [DoEval](#) ([ColinPoint](#) &point, int &priority, [ColinResponse](#) *response, bool synch_flag)
launch a function evaluation either synchronously or asynchronously
- unsigned int [num_evaluation_servers](#) ()
The number of 'slave' processors that can perform evaluations. The value '0' indicates that this is a sequential application.
- void [synchronize](#) ()
blocking retrieval of all pending jobs
- int [next_eval](#) ()
nonblocking query and retrieval of a job if completed
- void [dakota_asynch_flag](#) (const bool &asynch_flag)
This function publishes the iterator's asynchFlag at run time (asynchFlag not initialized properly at construction).

Private Member Functions

- void [map_response](#) ([ColinResponse](#) &colin_response, const [Response](#) &dakota_response)
utility function for mapping a DAKOTA response to a COLIN response

Private Attributes

- [Model](#) & [userDefinedModel](#)
reference to the COLINOptimizer's model passed in the constructor
- [ActiveSet](#) [activeSet](#)
copy/conversion of the COLIN request vector
- bool [dakotaModelAsynchFlag](#)

a flag for asynchronous DAKOTA evaluations

- bool `blockingSynch`
flag for user specification of "synchronization blocking"
- IntResponseMap `dakotaResponseMap`
map of DAKOTA responses returned by `synchronize_nowait()`
- size_t `numObjFns`
number of objective functions
- size_t `numNonlinCons`
number of nonlinear constraints
- Optimizer * `opt`
pointer to the DAKOTA Optimizer hierarchy passed through the COLINApplication constructor. This is needed for accessing Optimizer functions (e.g., `multi_objective_modify()`) needed by COLINApplication.
- int `num_real_params`
number of continuous design variables
- int `num_integer_params`
number of discrete design variables
- int `synchronization_state`
tracks the state of asynchronous evaluations
- std::list< int > `requested_async_id`
tracks COLIN response ids from `DoEval()` to `next_eval()`

10.14.1 Detailed Description

`COLINApplication` is a DAKOTA class that is derived from COLIN's `OptApplication` hierarchy. It redefines a variety of virtual COLIN functions to use the corresponding DAKOTA functions. This is a more flexible algorithm library interfacing approach than can be obtained with the function pointer approaches used by `NPSOLOptimizer` and `SNLLOptimizer`.

10.14.2 Member Function Documentation

10.14.2.1 void DoEval (ColinPoint & pt, int & priority, ColinResponse * prob_response, bool synch_flag)

launch a function evaluation either synchronously or asynchronously

Converts the [ColinPoint](#) variables and request vector to DAKOTA variables and active set vector, performs a DAKOTA function evaluation with synchronization governed by `synch_flag`, and then copies the [Response](#) data to the `ColinResponse` response (synchronous) or bookkeeps the response object (asynchronous).

10.14.2.2 void synchronize ()

blocking retrieval of all pending jobs

Blocking synchronize of asynchronous DAKOTA jobs followed by conversion of the [Response](#) objects to `ColinResponse` response objects.

10.14.2.3 int next_eval ()

nonblocking query and retrieval of a job if completed

Nonblocking job retrieval. Finds a completion (if available), populates the COLIN response, and sets `id` to the completed job's `id`. Else set `id = -1`.

**10.14.2.4 void map_response (ColinResponse & colin_response, const Response & dakota_response)
[private]**

utility function for mapping a DAKOTA response to a COLIN response

`map_response` Maps a [Response](#) object into a `ColinResponse` class that is compatible with COLIN.

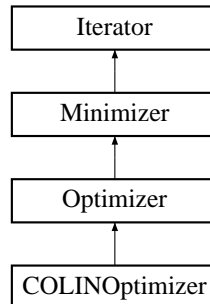
The documentation for this class was generated from the following files:

- COLINApplication.H
- COLINApplication.C

10.15 COLINOptimizer Class Template Reference

Wrapper class for optimizers defined using COLIN.

Inheritance diagram for COLINOptimizer::



Public Member Functions

- [COLINOptimizer](#) ([Model](#) &model)

Section 2

- [~COLINOptimizer](#) ()

destructor

- void [find_optimum](#) (void)

Performs the iterations to determine the optimal solution.

Protected Member Functions

- virtual void [set_rng](#) (void)

sets up the random number generator for stochastic methods

- virtual void [set_initial_point](#) ([ColinPoint](#) &pt)

sets the iteration starting point prior to minimization

- virtual void [get_min_point](#) ([ColinPoint](#) &pt)

retrieves the final solution after minimization

- virtual void [set_method_parameters](#) (void)

sets options for specific methods based on user specifications (called at construction time)

- void [set_standard_method_parameters](#) (void)
sets the standard method parameters shared by all methods
- virtual void [set_runtime_parameters](#) (void)
sets method parameters for specific methods using data that is not available until run time

Protected Attributes

- `OptimizerT * optimizer`
Pointer to COLIN base optimizer object.
- `COLINApplication * application`
Pointer to the COLINApplication object.
- `OptProblem< ColinPoint > problem`
the COLIN problem object
- `utilib::RNG * rng`
RNG ptr.
- `String evalSynch`
the synchronization setting (blocking or nonblocking)

10.15.1 Detailed Description

template<class OptimizerT> class Dakota::COLINOptimizer< OptimizerT >

Wrapper class for optimizers defined using COLIN.

The [COLINOptimizer](#) class provides a templated wrapper for COLIN, a Sandia-developed C++ optimization interface library. A variety of COLIN optimizers are defined in the COLINY optimization library, which contains the optimization components from the old SGOPT library. COLINY contains optimizers such as genetic algorithms, pattern search methods, and other nongradient-based techniques. [COLINOptimizer](#) uses a [COLINApplication](#) object to perform the function evaluations.

The user input mappings are as follows: `max_iterations`, `max_function_evaluations`, `convergence_tolerance`, `solution_accuracy` and `max_cpu_time` are mapped into COLIN's `max_iters`, `max_neval`, `ftol`, `accuracy`, and `max_time_data` attributes. An output setting of `verbose` is passed to COLIN's `set_output()` function and a setting of `debug` activates output of method initialization and sets the COLIN `debug` attribute to 10000. COLIN methods assume asynchronous operations whenever the algorithm has independent evaluations which can be performed simultaneously (implicit parallelism). Therefore, parallel configuration is not mapped into the method, rather it is used in [COLINApplication](#) to control whether or not an asynchronous evaluation request from the method is honored by the model (exception: pattern search exploratory moves is set to `best_all` for parallel function evaluations). Refer to [Hart, W.E., 1997] for additional information on COLIN objects and controls.

10.15.2 Member Function Documentation

10.15.2.1 void find_optimum (void) [virtual]

Performs the iterations to determine the optimal solution.

find_optimum redefines the [Optimizer](#) virtual function to perform the optimization using COLIN. It first sets up the problem data, then executes minimize() on the COLIN optimizer, and finally catalogues the results.

Implements [Optimizer](#).

10.15.2.2 void set_standard_method_parameters (void) [protected]

sets the standard method parameters shared by all methods

set_standard_method_parameters propagates standard DAKOTA user input to the optimizer.

The documentation for this class was generated from the following file:

- COLINOptimizer.H

10.16 ColinPoint Class Reference

Public Attributes

- `vector< double > rvec`
continuous parameter values
- `vector< int > ivec`
discrete parameter values

10.16.1 Detailed Description

A class containing a vector of doubles and integers.

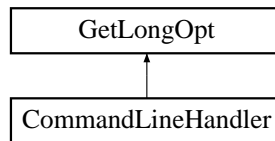
The documentation for this class was generated from the following file:

- COLINApplication.H

10.17 CommandLineHandler Class Reference

Utility class for managing command line inputs to DAKOTA.

Inheritance diagram for CommandLineHandler::



Public Member Functions

- [CommandLineHandler](#) ()
default constructor, requires [check_usage\(\)](#) call for parsing
- [CommandLineHandler](#) (int argc, char **argv)
constructor with parsing
- [~CommandLineHandler](#) ()
destructor
- void [check_usage](#) (int argc, char **argv)
Verifies that DAKOTA is called with the correct command usage. Prints a descriptive message and exits the program if incorrect.
- int [read_restart_evals](#) () const
Returns the number of evaluations to be read from the restart file (as specified on the DAKOTA command line) as an integer instead of a const char.*

Private Member Functions

- void [initialize_options](#) ()
enrolls the supported command line inputs.
- void [output_version](#) (ostream &s) const
outputs the DAKOTA version

10.17.1 Detailed Description

Utility class for managing command line inputs to DAKOTA.

[CommandLineHandler](#) provides additional functionality that is specific to DAKOTA's needs for the definition and parsing of command line options. Inheritance is used to allow the class to have all the functionality of the base class, [GetLongOpt](#).

The documentation for this class was generated from the following files:

- [CommandLineHandler.H](#)
- [CommandLineHandler.C](#)

10.18 CommandShell Class Reference

Utility class which defines convenience operators for spawning processes with system calls.

Public Member Functions

- [CommandShell \(\)](#)
constructor
- [~CommandShell \(\)](#)
destructor
- [CommandShell & operator<< \(const char *string\)](#)
adds string to unixCommand
- [CommandShell & operator<< \(CommandShell &\(*f\)\(CommandShell &\)\)](#)
allows passing of the flush function to the shell using <<
- [CommandShell & flush \(\)](#)
"flushes" the shell; i.e. executes the unixCommand
- void [asynch_flag](#) (const bool flag)
set the asynchFlag
- bool [asynch_flag](#) () const
get the asynchFlag
- void [suppress_output_flag](#) (const bool flag)
set the suppressOutputFlag
- bool [suppress_output_flag](#) () const
get the suppressOutputFlag

Private Attributes

- [String unixCommand](#)
the command string that is constructed through one or more << insertions and then executed by flush
- bool [asynchFlag](#)
flags nonblocking operation (background system calls)

- bool [suppressOutputFlag](#)
flags suppression of shell output (no command echo)

10.18.1 Detailed Description

Utility class which defines convenience operators for spawning processes with system calls.

The [CommandShell](#) class wraps the C `system()` utility and defines convenience operators for building a command string and then passing it to the shell.

10.18.2 Member Function Documentation

10.18.2.1 [CommandShell](#) & `flush ()`

"flushes" the shell; i.e. executes the `unixCommand`

Executes the `unixCommand` by passing it to `system()`. Appends an "&" if `asynchFlag` is set (background system call) and echos the `unixCommand` to `Cout` if `suppressOutputFlag` is not set.

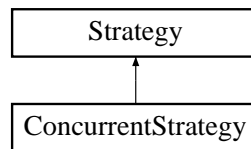
The documentation for this class was generated from the following files:

- `CommandShell.H`
- `CommandShell.C`

10.19 ConcurrentStrategy Class Reference

[Strategy](#) for multi-start iteration or pareto set optimization.

Inheritance diagram for ConcurrentStrategy::



Public Member Functions

- [ConcurrentStrategy](#) ([ProblemDescDB](#) &problem_db)

constructor

- [~ConcurrentStrategy](#) ()

destructor

- void [run_strategy](#) ()

Performs the concurrent strategy by executing selectedIterator on userDefinedModel multiple times in parallel for different settings within the iterator or model.

Private Member Functions

- void [self_schedule_iterators](#) ()

executed by the strategy master to self-schedule iterator jobs among slave iterator servers (called by [run_strategy\(\)](#))

- void [serve_iterators](#) ()

executed on the slave iterator servers to perform iterator jobs assigned by the strategy master (called by [run_strategy\(\)](#))

- void [static_schedule_iterators](#) ()

executed on iterator peers to statically schedule iterator jobs (called by [run_strategy\(\)](#))

- void [print_results](#) ()

prints the concurrent iteration results summary (called by [run_strategy\(\)](#))

Private Attributes

- [Model userDefinedModel](#)
the model used by the iterator
- [Iterator selectedIterator](#)
the iterator used by the concurrent strategy
- int [numIteratorServers](#)
number of concurrent iterator partitions
- int [numIteratorJobs](#)
total number of iterator executions to schedule over the servers
- [RealVectorArray parameterSets](#)
an array of parameter set vectors (either multistart variable sets or pareto multiobjective weighting sets) to be performed.
- [PRPArray prpResults](#)
an array of results corresponding to the parameter set vectors.
- bool [multiStartFlag](#)
distinguishes multi-start from Pareto-set
- bool [strategyDedicatedMasterFlag](#)
signals ded. master partitioning
- int [iteratorServerId](#)
identifier for an iterator server
- int [drvMsgLen](#)
length of an MPI buffer containing a RealVector from parameterSets

10.19.1 Detailed Description

[Strategy](#) for multi-start iteration or pareto set optimization.

This strategy maintains two concurrent iterator capabilities. First, a general capability for running an iterator multiple times from different starting points is provided (often used for multi-start optimization, but not restricted to optimization). Second, a simple capability for mapping the "pareto frontier" (the set of optimal solutions in mutiobjective formulations) is provided. This pareto set is mapped through running an optimizer multiple times for different sets of multiobjective weightings.

10.19.2 Member Function Documentation

10.19.2.1 void self_schedule_iterators () [private]

executed by the strategy master to self-schedule iterator jobs among slave iterator servers (called by [run_strategy\(\)](#))

This function is adapted from [ApplicationInterface::self_schedule_evaluations\(\)](#).

10.19.2.2 void serve_iterators () [private]

executed on the slave iterator servers to perform iterator jobs assigned by the strategy master (called by [run_strategy\(\)](#))

This function is similar in structure to [ApplicationInterface::serve_evaluations_synch\(\)](#).

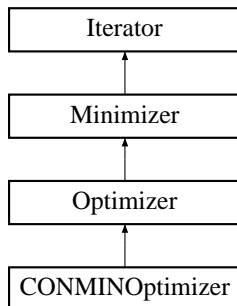
The documentation for this class was generated from the following files:

- ConcurrentStrategy.H
- ConcurrentStrategy.C

10.20 CONMINOptimizer Class Reference

Wrapper class for the CONMIN optimization library.

Inheritance diagram for CONMINOptimizer::



Public Member Functions

- [CONMINOptimizer \(Model &model\)](#)
constructor
- [~CONMINOptimizer \(\)](#)
destructor
- void [find_optimum \(\)](#)
Used within the optimizer branch for computing the optimal solution. Redefines the run_iterator virtual function for the optimizer branch.

Protected Member Functions

- virtual void [derived_pre_run \(\)](#)
performs run-time set up
- virtual void [derived_post_run \(\)](#)
performs final solution processing

Private Member Functions

- void [allocate_workspace \(\)](#)
Allocates workspace for the optimizer.

- void [deallocate_workspace \(\)](#)
Releases workspace memory.
- void [allocate_constraints \(\)](#)
Allocates constraint mappings.

Private Attributes

- int [conminInfo](#)
INFO from CONMIN manual.
- int [printControl](#)
IPRINT from CONMIN manual (controls output verbosity).
- int [optimizationType](#)
MINMAX from DOT manual (minimize or maximize).
- Real [objFnValue](#)
value of the objective function passed to CONMIN
- [RealVector](#) [constraintValues](#)
array of nonlinear constraint values passed to CONMIN
- [SizetList](#) [constraintMappingIndices](#)
a list of indices for referencing the corresponding [Response](#) constraints used in computing the CONMIN constraints.
- [RealList](#) [constraintMappingMultipliers](#)
a list of multipliers for mapping the [Response](#) constraints to the CONMIN constraints.
- [RealList](#) [constraintMappingOffsets](#)
a list of offsets for mapping the [Response](#) constraints to the CONMIN constraints.
- int [N1](#)
Size variable for CONMIN arrays. See CONMIN manual.
- int [N2](#)
Size variable for CONMIN arrays. See CONMIN manual.
- int [N3](#)
Size variable for CONMIN arrays. See CONMIN manual.
- int [N4](#)
Size variable for CONMIN arrays. See CONMIN manual.

- int [N5](#)
Size variable for CONMIN arrays. See CONMIN manual.
- int [NFDG](#)
Finite difference flag.
- int [IPRINT](#)
Flag to control amount of output data.
- int [ITMAX](#)
Flag to specify the maximum number of iterations.
- double [FDCH](#)
Relative finite difference step size.
- double [FDCHM](#)
Absolute finite difference step size.
- double [CT](#)
Constraint thickness parameter.
- double [CTMIN](#)
Minimum absolute value of CT used during optimization.
- double [CTL](#)
Constraint thickness parameter for linear and side constraints.
- double [CTLMIN](#)
Minimum value of CTL used during optimization.
- double [DELFUN](#)
Relative convergence criterion threshold.
- double [DABFUN](#)
Absolute convergence criterion threshold.
- double * [conminDesVars](#)
Array of design variables used by CONMIN (length NI = numdv+2).
- double * [conminLowerBnds](#)
Array of lower bounds used by CONMIN (length NI = numdv+2).
- double * [conminUpperBnds](#)
Array of upper bounds used by CONMIN (length NI = numdv+2).
- double * [S](#)

Internal CONMIN array.

- double * [G1](#)

Internal CONMIN array.

- double * [G2](#)

Internal CONMIN array.

- double * [B](#)

Internal CONMIN array.

- double * [C](#)

Internal CONMIN array.

- int * [MS1](#)

Internal CONMIN array.

- double * [SCAL](#)

Internal CONMIN array.

- double * [DF](#)

Internal CONMIN array.

- double * [A](#)

Internal CONMIN array.

- int * [ISC](#)

Internal CONMIN array.

- int * [IC](#)

Internal CONMIN array.

10.20.1 Detailed Description

Wrapper class for the CONMIN optimization library.

The [CONMINOptimizer](#) class provides a wrapper for CONMIN, a Public-domain Fortran 77 optimization library written by Gary Vanderplaats under contract to NASA Ames Research Center. The CONMIN User's Manual is contained in NASA Technical Memorandum X-62282, 1978. CONMIN uses a reverse communication mode, which avoids the static member function issues that arise with function pointer designs (see [NPSOLOptimizer](#) and [SNLLOptimizer](#)).

The user input mappings are as follows: `max_iterations` is mapped into CONMIN's `ITMAX` parameter, `max_function_evaluations` is implemented directly in the `find_optimum()` loop since there is no CONMIN parameter equivalent, `convergence_tolerance` is mapped into CONMIN's `DELFUN` and `DABFUN` parameters, output verbosity is mapped into CONMIN's `IPRINT` parameter (verbose: `IPRINT = 4`; quiet:

IPRINT = 2), gradient mode is mapped into CONMIN's NFDG parameter, and finite difference step size is mapped into CONMIN's FDCH and FDCHM parameters. Refer to [Vanderplaats, 1978] for additional information on CONMIN parameters.

10.20.2 Member Data Documentation

10.20.2.1 int [conminInfo](#) [private]

INFO from CONMIN manual.

Information requested by CONMIN: 1 = evaluate objective and constraints, 2 = evaluate gradients of objective and constraints.

10.20.2.2 int [printControl](#) [private]

IPRINT from CONMIN manual (controls output verbosity).

Values range from 0 (nothing) to 4 (most output). 0 = nothing, 1 = initial and final function information, 2 = all of #1 plus function value and design vars at each iteration, 3 = all of #2 plus constraint values and direction vectors, 4 = all of #3 plus gradients of the objective function and constraints, 5 = all of #4 plus proposed design vector, plus objective and constraint functions from the 1-D search

10.20.2.3 int [optimizationType](#) [private]

MINMAX from DOT manual (minimize or maximize).

Values of 0 or -1 (minimize) or 1 (maximize).

10.20.2.4 [RealVector constraintValues](#) [private]

array of nonlinear constraint values passed to CONMIN

This array must be of nonzero length and must contain only one-sided inequality constraints which are ≤ 0 (which requires a transformation from 2-sided inequalities and equalities).

10.20.2.5 [SizetList constraintMappingIndices](#) [private]

a list of indices for referencing the corresponding [Response](#) constraints used in computing the CONMIN constraints.

The length of the list corresponds to the number of CONMIN constraints, and each entry in the list points to the corresponding DAKOTA constraint.

10.20.2.6 RealList constraintMappingMultipliers [private]

a list of multipliers for mapping the [Response](#) constraints to the CONMIN constraints.

The length of the list corresponds to the number of CONMIN constraints, and each entry in the list contains a multiplier for the DAKOTA constraint identified with constraintMappingIndices. These multipliers are currently +1 or -1.

10.20.2.7 RealList constraintMappingOffsets [private]

a list of offsets for mapping the [Response](#) constraints to the CONMIN constraints.

The length of the list corresponds to the number of CONMIN constraints, and each entry in the list contains an offset for the DAKOTA constraint identified with constraintMappingIndices. These offsets involve inequality bounds or equality targets, since CONMIN assumes constraint allowables = 0.

10.20.2.8 int N1 [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N1 = \text{number of variables} + 2$

10.20.2.9 int N2 [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N2 = \text{number of constraints} + 2 * (\text{number of variables})$

10.20.2.10 int N3 [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N3 = \text{Maximum possible number of active constraints.}$

10.20.2.11 int N4 [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N4 = \text{Maximum}(N3, \text{number of variables})$

10.20.2.12 int N5 [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N5 = 2 * (N4)$

10.20.2.13 `double CT` [private]

Constraint thickness parameter.

The value of CT decreases in magnitude during optimization.

10.20.2.14 `double* S` [private]

Internal CONMIN array.

Move direction in N-dimensional space.

10.20.2.15 `double* G1` [private]

Internal CONMIN array.

Temporary storage of constraint values.

10.20.2.16 `double* G2` [private]

Internal CONMIN array.

Temporary storage of constraint values.

10.20.2.17 `double* B` [private]

Internal CONMIN array.

Temporary storage for computations involving array S.

10.20.2.18 `double* C` [private]

Internal CONMIN array.

Temporary storage for use with arrays B and S.

10.20.2.19 `int* MS1` [private]

Internal CONMIN array.

Temporary storage for use with arrays B and S.

10.20.2.20 `double* SCAL` [private]

Internal CONMIN array.

[Vector](#) of scaling parameters for design parameter values.

10.20.2.21 `double* DF` [private]

Internal CONMIN array.

Temporary storage for analytic gradient data.

10.20.2.22 `double* A` [private]

Internal CONMIN array.

Temporary 2-D array for storage of constraint gradients.

10.20.2.23 `int* ISC` [private]

Internal CONMIN array.

[Array](#) of flags to identify linear constraints. (not used in this implementation of CONMIN)

10.20.2.24 `int* IC` [private]

Internal CONMIN array.

[Array](#) of flags to identify active and violated constraints

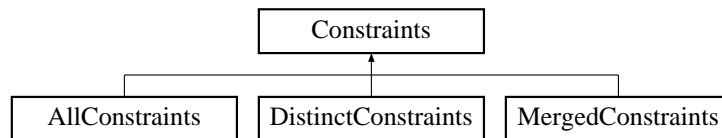
The documentation for this class was generated from the following files:

- CONMINOptimizer.H
- CONMINOptimizer.C

10.21 Constraints Class Reference

Base class for the variable constraints class hierarchy.

Inheritance diagram for Constraints::



Public Member Functions

- [Constraints](#) ()
default constructor
- [Constraints](#) (const [ProblemDescDB](#) &problem_db, const pair< short, short > &view)
standard constructor
- [Constraints](#) (const [Constraints](#) &con)
copy constructor
- virtual [~Constraints](#) ()
destructor
- [Constraints operator=](#) (const [Constraints](#) &con)
assignment operator
- virtual const [RealVector](#) & [continuous_lower_bounds](#) () const
return the active continuous variable lower bounds
- virtual void [continuous_lower_bounds](#) (const [RealVector](#) &c_l_bnds)
set the active continuous variable lower bounds
- virtual const [RealVector](#) & [continuous_upper_bounds](#) () const
return the active continuous variable upper bounds
- virtual void [continuous_upper_bounds](#) (const [RealVector](#) &c_u_bnds)
set the active continuous variable upper bounds
- virtual const [IntVector](#) & [discrete_lower_bounds](#) () const
return the active discrete variable lower bounds

- virtual void `discrete_lower_bounds` (const `IntVector` &d_l_bnds)
set the active discrete variable lower bounds
- virtual const `IntVector` & `discrete_upper_bounds` () const
return the active discrete variable upper bounds
- virtual void `discrete_upper_bounds` (const `IntVector` &d_u_bnds)
set the active discrete variable upper bounds
- virtual const `RealVector` & `inactive_continuous_lower_bounds` () const
return the inactive continuous lower bounds
- virtual void `inactive_continuous_lower_bounds` (const `RealVector` &i_c_l_bnds)
set the inactive continuous lower bounds
- virtual const `RealVector` & `inactive_continuous_upper_bounds` () const
return the inactive continuous upper bounds
- virtual void `inactive_continuous_upper_bounds` (const `RealVector` &i_c_u_bnds)
set the inactive continuous upper bounds
- virtual const `IntVector` & `inactive_discrete_lower_bounds` () const
return the inactive discrete lower bounds
- virtual void `inactive_discrete_lower_bounds` (const `IntVector` &i_d_l_bnds)
set the inactive discrete lower bounds
- virtual const `IntVector` & `inactive_discrete_upper_bounds` () const
return the inactive discrete upper bounds
- virtual void `inactive_discrete_upper_bounds` (const `IntVector` &i_d_u_bnds)
set the inactive discrete upper bounds
- virtual `RealVector` `all_continuous_lower_bounds` () const
returns a single array with all continuous lower bounds
- virtual `RealVector` `all_continuous_upper_bounds` () const
returns a single array with all continuous upper bounds
- virtual `IntVector` `all_discrete_lower_bounds` () const
returns a single array with all discrete lower bounds
- virtual `IntVector` `all_discrete_upper_bounds` () const
returns a single array with all discrete upper bounds

- virtual void [write](#) (ostream &s) const
write a variable constraints object to an ostream
- virtual void [read](#) (istream &s)
read a variable constraints object from an istream
- size_t [num_linear_ineq_constraints](#) () const
return the number of linear inequality constraints
- size_t [num_linear_eq_constraints](#) () const
return the number of linear equality constraints
- const [RealMatrix](#) & [linear_ineq_constraint_coeffs](#) () const
return the linear inequality constraint coefficients
- void [linear_ineq_constraint_coeffs](#) (const [RealMatrix](#) &lin_ineq_coeffs)
set the linear inequality constraint coefficients
- const [RealVector](#) & [linear_ineq_constraint_lower_bounds](#) () const
return the linear inequality constraint lower bounds
- void [linear_ineq_constraint_lower_bounds](#) (const [RealVector](#) &lin_ineq_l_bnds)
set the linear inequality constraint lower bounds
- const [RealVector](#) & [linear_ineq_constraint_upper_bounds](#) () const
return the linear inequality constraint upper bounds
- void [linear_ineq_constraint_upper_bounds](#) (const [RealVector](#) &lin_ineq_u_bnds)
set the linear inequality constraint upper bounds
- const [RealMatrix](#) & [linear_eq_constraint_coeffs](#) () const
return the linear equality constraint coefficients
- void [linear_eq_constraint_coeffs](#) (const [RealMatrix](#) &lin_eq_coeffs)
set the linear equality constraint coefficients
- const [RealVector](#) & [linear_eq_constraint_targets](#) () const
return the linear equality constraint targets
- void [linear_eq_constraint_targets](#) (const [RealVector](#) &lin_eq_targets)
set the linear equality constraint targets
- size_t [num_nonlinear_ineq_constraints](#) () const
return the number of nonlinear inequality constraints
- size_t [num_nonlinear_eq_constraints](#) () const

return the number of nonlinear equality constraints

- `const RealVector & nonlinear_ineq_constraint_lower_bounds () const`
return the nonlinear inequality constraint lower bounds
- `void nonlinear_ineq_constraint_lower_bounds (const RealVector &nln_ineq_l_bnds)`
set the nonlinear inequality constraint lower bounds
- `const RealVector & nonlinear_ineq_constraint_upper_bounds () const`
return the nonlinear inequality constraint upper bounds
- `void nonlinear_ineq_constraint_upper_bounds (const RealVector &nln_ineq_u_bnds)`
set the nonlinear inequality constraint upper bounds
- `const RealVector & nonlinear_eq_constraint_targets () const`
return the nonlinear equality constraint targets
- `void nonlinear_eq_constraint_targets (const RealVector &nln_eq_targets)`
set the nonlinear equality constraint targets

Protected Member Functions

- `Constraints (BaseConstructor, const ProblemDescDB &problem_db, const pair< short, short > &view)`
constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)
- `void manage_linear_constraints (const ProblemDescDB &problem_db)`
perform checks on user input, convert linear constraint coefficient input to matrices, and assign defaults

Protected Attributes

- `pair< short, short > variablesView`
the variables view pair containing active (first) and inactive (second) view enumerations
- `size_t numNonlinearIneqCons`
number of nonlinear inequality constraints
- `size_t numNonlinearEqCons`
number of nonlinear equality constraints
- `RealVector nonlinearIneqConLowerBnds`
nonlinear inequality constraint lower bounds

- [RealVector nonlinearIneqConUpperBnds](#)
nonlinear inequality constraint upper bounds
- [RealVector nonlinearEqConTargets](#)
nonlinear equality constraint targets
- `size_t numLinearIneqCons`
number of linear inequality constraints
- `size_t numLinearEqCons`
number of linear equality constraints
- [RealMatrix linearIneqConCoeffs](#)
linear inequality constraint coefficients
- [RealMatrix linearEqConCoeffs](#)
linear equality constraint coefficients
- [RealVector linearIneqConLowerBnds](#)
linear inequality constraint lower bounds
- [RealVector linearIneqConUpperBnds](#)
linear inequality constraint upper bounds
- [RealVector linearEqConTargets](#)
linear equality constraint targets
- [RealVector emptyRealVector](#)
an empty real vector returned in get functions when there are no variable constraints corresponding to the request
- [IntVector emptyIntVector](#)
an empty int vector returned in get functions when there are no variable constraints corresponding to the request

Private Member Functions

- `Constraints * get_constraints` (const [ProblemDescDB](#) &problem_db, const pair< short, short > &view)
Used only by the constructor to initialize constraintsRep to the appropriate derived type.

Private Attributes

- `Constraints * constraintsRep`
pointer to the letter (initialized only for the envelope)

- int [referenceCount](#)
number of objects sharing constraintsRep

10.21.1 Detailed Description

Base class for the variable constraints class hierarchy.

The [Constraints](#) class is the base class for the class hierarchy managing bound, linear, and nonlinear constraints. Using the variable lower and upper bounds arrays from the input specification, different derived classes define different views of this data. The linear and nonlinear constraint data is consistent in all views and is managed at the base class level. For memory efficiency and enhanced polymorphism, the variable constraints hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Constraints](#)) serves as the envelope and one of the derived classes (selected in [Constraints::get_constraints\(\)](#)) serves as the letter.

10.21.2 Constructor & Destructor Documentation

10.21.2.1 [Constraints](#) ()

default constructor

The default constructor: `constraintsRep` is NULL in this case (a populated `problem_db` is needed to build a meaningful [Constraints](#) object). This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

10.21.2.2 [Constraints](#) (const [ProblemDescDB](#) & *problem_db*, const pair< short, short > & *view*)

standard constructor

The envelope constructor only needs to extract enough data to properly execute `get_constraints`, since the constructor overloaded with [BaseConstructor](#) builds the actual base class data inherited by the derived classes.

10.21.2.3 [Constraints](#) (const [Constraints](#) & *con*)

copy constructor

Copy constructor manages sharing of `constraintsRep` and incrementing of `referenceCount`.

10.21.2.4 [~Constraints](#) () [virtual]

destructor

Destructor decrements `referenceCount` and only deletes `constraintsRep` when `referenceCount` reaches zero.

10.21.2.5 **Constraints** (**BaseConstructor**, **const ProblemDescDB & problem_db**, **const pair< short, short > & view**) [`protected`]

constructor initializes the base class part of letter classes (**BaseConstructor** overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all derived classes. `get_constraints()` instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list (to avoid recursion in the base class constructor calling `get_constraints()` again). Since the letter IS the representation, its rep pointer is set to NULL (an uninitialized pointer causes problems in `~Constraints`).

10.21.3 Member Function Documentation

10.21.3.1 **Constraints** `operator=` (**const Constraints & con**)

assignment operator

Assignment operator decrements referenceCount for old constraintsRep, assigns new constraintsRep, and increments referenceCount for new constraintsRep.

10.21.3.2 **void manage_linear_constraints** (**const ProblemDescDB & problem_db**) [`protected`]

perform checks on user input, convert linear constraint coefficient input to matrices, and assign defaults

Convenience function called from derived class constructors. The number of variables active for applying linear constraints is currently defined to be the number of active continuous variables plus the number of active discrete variables (the most general case), even though very few optimizers can currently support mixed variable linear constraints.

10.21.3.3 **Constraints** * `get_constraints` (**const ProblemDescDB & problem_db**, **const pair< short, short > & view**) [`private`]

Used only by the constructor to initialize constraintsRep to the appropriate derived type.

Initializes constraintsRep to the appropriate derived type, as given by the variables view.

The documentation for this class was generated from the following files:

- DakotaConstraints.H
- DakotaConstraints.C

10.22 CtelRegexp Class Reference

Public Types

- enum [RStatus](#) {
GOOD = 0, EXP_TOO_BIG, OUT_OF_MEM, TOO_MANY_PAR,
UNMATCH_PAR, STARPLUS_EMPTY, STARPLUS_NESTED, INDEX_RANGE,
INDEX_MATCH, STARPLUS_NOTHING, TRAILING, INT_ERROR,
BAD_PARAM, BAD_OPCODE }

Error codes reported by the engine - Most of these codes never really occurs with this implementation.

Public Member Functions

- [CtelRegexp](#) (const std::string &pattern)
Constructor - compile a regular expression.
- [~CtelRegexp](#) ()
Destructor.
- bool [compile](#) (const std::string &pattern)
Compile a new regular expression.
- std::string [match](#) (const std::string &str)
matches a particular string; this method returns a string that is a sub-string matching with the regular expression
- bool [match](#) (const std::string &str, size_t *start, size_t *size)
another form of matching; returns the indexes of the matching
- [RStatus](#) [getStatus](#) ()
Get status.
- const std::string & [getStatusMsg](#) ()
Get status message.
- void [clearErrors](#) ()
Clear all errors.
- const std::string & [getRe](#) ()
Return regular expression pattern.
- bool [split](#) (const std::string &str, std::vector< std::string > &all_matches)

Split.

Private Member Functions

- [CtelRegexp](#) (const [CtelRegexp](#) &)
Private copy constructor.
- [CtelRegexp](#) & [operator=](#) (const [CtelRegexp](#) &)
Private assignment operator.

Private Attributes

- `std::string` [strPattern](#)
STL string to hold pattern.
- `regexp * r`
Pointer to regexp.
- [RStatus](#) [status](#)
Return status, enumerated type.
- `std::string` [statusMsg](#)
STL string to hold status message.

10.22.1 Detailed Description

DESCRIPTION: Wrapper for the Regular Expression engine(`regexp`) released by Henry Spencer of the University of Toronto.

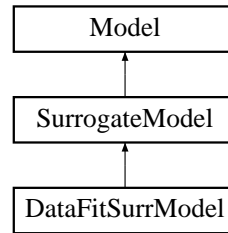
The documentation for this class was generated from the following files:

- `CtelRegExp.H`
- `CtelRegExp.C`

10.23 DataFitSurrModel Class Reference

Derived model class within the surrogate model branch for managing data fit surrogates (global and local).

Inheritance diagram for DataFitSurrModel::



Public Member Functions

- [DataFitSurrModel \(ProblemDescDB &problem_db\)](#)
constructor
- [~DataFitSurrModel \(\)](#)
destructor

Protected Member Functions

- void [derived_compute_response](#) (const [ActiveSet](#) &set)
portion of [compute_response\(\)](#) specific to [DataFitSurrModel](#)
- void [derived_async_compute_response](#) (const [ActiveSet](#) &set)
portion of [async_compute_response\(\)](#) specific to [DataFitSurrModel](#)
- const [ResponseArray](#) & [derived_synchronize](#) ()
portion of [synchronize\(\)](#) specific to [DataFitSurrModel](#)
- const [IntResponseMap](#) & [derived_synchronize_nowait](#) ()
portion of [synchronize_nowait\(\)](#) specific to [DataFitSurrModel](#)
- [Iterator](#) & [subordinate_iterator](#) ()
return [daceIterator](#)
- [Model](#) & [surrogate_model](#) ()
return this model instance

- [Model](#) & [truth_model](#) ()
return actualModel
- void [derived_subordinate_models](#) ([ModelList](#) &ml, bool recurse_flag)
return actualModel (and optionally its sub-models)
- [Interface](#) & [interface](#) ()
return approxInterface
- void [surrogate_bypass](#) (bool bypass_flag)
set surrogateBypass flag and pass request on to actualModel for any lower-level surrogates.
- void [build_approximation](#) ()
Builds the local/multipoint/global approximation using daceIterator/actualModel.
- bool [build_approximation](#) (const [RealVector](#) &c_vars, const [Response](#) &response)
Builds the local/multipoint/global approximation using daceIterator/actualModel to generate new data that augments the c_vars/response anchor point.
- void [update_approximation](#) (const [RealVector](#) &c_vars, const [Response](#) &response)
Adds a point to a global approximation and rebuilds it (requests forwarded to approxInterface).
- const [RealVectorArray](#) & [approximation_coefficients](#) ()
return the approximation coefficients from each [Approximation](#) (request forwarded to approxInterface)
- void [component_parallel_mode](#) (int mode)
update component parallel mode for supporting parallelism in actualModel
- void [derived_init_communicators](#) (const int &max_iterator_concurrency)
set up actualModel for parallel operations
- void [derived_init_serial](#) ()
set up actualModel for serial operations.
- void [derived_set_communicators](#) (const int &max_iterator_concurrency)
set active parallel configuration within actualModel
- void [reset_communicators](#) ()
reset communicator partitions for the [DataFitSurrModel](#) (request forwarded to actualModel)
- void [derived_free_communicators](#) (const int &max_iterator_concurrency)
deallocate communicator partitions for the [DataFitSurrModel](#) (request forwarded to actualModel)
- void [serve](#) ()

Service *actualModel* job requests received from the master. Completes when a termination message is received from *stop_servers()*.

- void [stop_servers](#) ()
Executed by the master to terminate actualModel server operations when DataFitSurrModel iteration is complete.
- int [evaluation_id](#) () const
return the current evaluation id for the DataFitSurrModel
- void [set_evaluation_reference](#) ()
set the evaluation counter reference points for the DataFitSurrModel (request forwarded to approxInterface and actualModel)
- void [print_evaluation_summary](#) (ostream &s, bool minimal_header=false, bool relative_count=true) const
print the evaluation summary for the DataFitSurrModel (request forwarded to approxInterface and actualModel)

Private Member Functions

- void [update_actual_model](#) ()
update actualModel with current variable values/bounds/labels
- void [update_global](#) ()
Updates fit arrays for global approximations.
- void [update_local_multipoint](#) ()
Updates fit arrays for local or multipoint approximations.
- void [build_global](#) ()
Builds a global approximation using daceIterator.
- void [build_local_multipoint](#) ()
Builds a local or multipoint approximation using actualModel.
- void [asv_mapping](#) (const [IntArray](#) &orig_asv, [IntArray](#) &actual_asv, [IntArray](#) &approx_asv, bool build_flag)
distributes the incoming orig_asv among actual_asv and approx_asv

Private Attributes

- int [surrModelEvals](#)
number of calls to [derived_compute_response\(\)](#)/[derived_asynch_compute_response\(\)](#)
- [String](#) [sampleReuse](#)

user selection of type of sample reuse for approximation builds: all, region, file, or none (default)

- [String sampleReuseFile](#)
file name for sampleReuse == "file"
- [Interface approxInterface](#)
manages the building and subsequent evaluation of the approximations (required for both global and local)
- [String actualModelPointer](#)
string identifier for the actual model from the local/multipoint approximation specification; used to build actual-Model.
- [Model actualModel](#)
the truth model which provides evaluations for building the surrogate (optional for global, required for local)
- [String daceMethodPointer](#)
string identifier for the dace method from the global approximation specification; used in building daceIterator and actualModel for global approximations (optional for global since restart data may also be used)
- [Iterator daceIterator](#)
selects parameter sets on which to evaluate actualModel in order to generate the necessary data for building global approximations (optional for global since restart data may also be used)

10.23.1 Detailed Description

Derived model class within the surrogate model branch for managing data fit surrogates (global and local).

The [DataFitSurrModel](#) class manages global or local approximations (surrogates that involve data fits) that are used in place of an expensive model. The class contains an [approxInterface](#) (required for both global and local) which manages the approximate function evaluations, an [actualModel](#) (optional for global, required for local) which provides truth evaluations for building the surrogate, and a [daceIterator](#) (optional for global, not used for local) which selects parameter sets on which to evaluate [actualModel](#) in order to generate the necessary data for building global approximations.

10.23.2 Member Function Documentation

10.23.2.1 `void derived_compute_response (const ActiveSet & set)` [protected, virtual]

portion of `compute_response()` specific to [DataFitSurrModel](#)

Build the approximation (if needed), evaluate the approximate response using [approxInterface](#), and, if correction is active, correct the results.

Reimplemented from [Model](#).

10.23.2.2 void derived_asynch_compute_response (const [ActiveSet](#) & set) [protected, virtual]

portion of [asynch_compute_response\(\)](#) specific to [DataFitSurrModel](#)

Build the approximation (if needed) and evaluate the approximate response using [approxInterface](#) in a quasi-asynchronous approach ([ApproximationInterface::map\(\)](#) performs the map synchronously and bookkeeps the results for return in [derived_synchronize\(\)](#) below).

Reimplemented from [Model](#).

10.23.2.3 const [ResponseArray](#) & derived_synchronize () [protected, virtual]

portion of [synchronize\(\)](#) specific to [DataFitSurrModel](#)

Retrieve quasi-asynchronous evaluations from [approxInterface](#) and, if correction is active, apply correction to each response in the array.

Reimplemented from [Model](#).

10.23.2.4 const [IntResponseMap](#) & derived_synchronize_nowait () [protected, virtual]

portion of [synchronize_nowait\(\)](#) specific to [DataFitSurrModel](#)

Retrieve quasi-asynchronous evaluations from [approxInterface](#) and, if correction is active, apply correction to each response in the map.

Reimplemented from [Model](#).

10.23.2.5 void derived_init_communicators (const int & max_iterator_concurrency) [inline, protected, virtual]

set up [actualModel](#) for parallel operations

asynchronous flags need to be initialized for the sub-models. In addition, [max_iterator_concurrency](#) is the outer level iterator concurrency, not the DACE concurrency that [actualModel](#) will see, and recomputing the [message_lengths](#) on the sub-model is probably not a bad idea either. Therefore, recompute everything on [actualModel](#) using [init_communicators](#).

Reimplemented from [Model](#).

10.23.2.6 int evaluation_id () const [inline, protected, virtual]

return the current evaluation id for the [DataFitSurrModel](#)

return the [DataFitSurrModel](#) evaluation count. Due to possibly intermittent use of surrogate bypass, this is not the same as either the [approxInterface](#) or [actualModel](#) model evaluation counts. It also does not distinguish duplicate evals.

Reimplemented from [Model](#).

10.23.2.7 `void update_actual_model () [private]`

update actualModel with current variable values/bounds/labels

Update variables and constraints data within actualModel using values and labels from currentVariables and bound/linear/nonlinear constraints from userDefinedConstraints.

10.23.2.8 `void build_global () [private]`

Builds a global approximation using daceIterator.

Determine sample points to use in building the approximation and then evaluate them on actualModel using daceIterator. Any changes to the bounds should be performed by setting them at a higher level (e.g., [SurrBasedOptStrategy](#)).

10.23.2.9 `void build_local_multipoint () [private]`

Builds a local or multipoint approximation using actualModel.

Evaluate the value, gradient, and possibly Hessian needed for a local or multipoint approximation using actualModel.

10.23.3 Member Data Documentation

10.23.3.1 `String actualModelPointer [private]`

string identifier for the actual model from the local/multipoint approximation specification; used to build actualModel.

Specification is used only for local/multipoint approximations, since the dace_method_pointer in the global approximation specification is responsible for identifying all actualModel components.

10.23.3.2 `Model actualModel [private]`

the truth model which provides evaluations for building the surrogate (optional for global, required for local)

actualModel is unrestricted in type; arbitrary nestings are possible.

The documentation for this class was generated from the following files:

- DataFitSurrModel.H
- DataFitSurrModel.C

10.24 DataInterface Class Reference

Container class for interface specification data.

Public Member Functions

- [DataInterface \(\)](#)
constructor
- [DataInterface \(const DataInterface &\)](#)
copy constructor
- [~DataInterface \(\)](#)
destructor
- [DataInterface & operator= \(const DataInterface &\)](#)
assignment operator
- [bool operator== \(const DataInterface &\)](#)
equality operator
- [void write \(ostream &s\) const](#)
write a [DataInterface](#) object to an ostream
- [void read \(MPIUnpackBuffer &s\)](#)
read a [DataInterface](#) object from a packed MPI buffer
- [void write \(MPIPackBuffer &s\) const](#)
write a [DataInterface](#) object to a packed MPI buffer

Public Attributes

- [String idInterface](#)
*string identifier for an interface specification data set (from the `id_interface` specification in **InterfIndControl**)*
- [String interfaceType](#)
the interface selection: system, fork, direct, or grid
- [String algebraicMappings](#)
defines the subset of the parameter to response mapping that is explicit and algebraic. This is typically a `stub.nl` filename (AMPL format) from JAGUAR.

- [StringArray analysisDrivers](#)
*the set of analysis drivers for a simulation-based interface (from the `analysis_drivers` specification in **InterfIndControl**)*
- [String2DArray analysisComponents](#)
*the set of analysis components for a simulation-based interface (from the `analysis_components` specification in **InterfIndControl**)*
- [String inputFilter](#)
*the input filter for a simulation-based interface (from the `input_filter` specification in **InterfIndControl**)*
- [String outputFilter](#)
*the output filter for a simulation-based interface (from the `output_filter` specification in **InterfIndControl**)*
- [String parametersFile](#)
*the parameters file for system call and fork interfaces (from the `parameters_file` specification in **InterfApplicSC** and **InterfApplicF**)*
- [String resultsFile](#)
*the results file for system call and fork interfaces (from the `results_file` specification in **InterfApplicSC** and **InterfApplicF**)*
- [String analysisUsage](#)
*the analysis command usage string for a system call interface (from the `analysis_usage` specification in **InterfApplicSC**)*
- [bool apreproFormatFlag](#)
*the flag for aprepro format usage in the parameters file for system call and fork interfaces (from the `aprepro` specification in **InterfApplicSC** and **InterfApplicF**)*
- [bool fileTagFlag](#)
*the flag for file tagging of parameters and results files for system call and fork interfaces (from the `file_tag` specification in **InterfApplicSC** and **InterfApplicF**)*
- [bool fileSaveFlag](#)
*the flag for saving of parameters and results files for system call and fork interfaces (from the `file_save` specification in **InterfApplicSC** and **InterfApplicF**)*
- [int procsPerAnalysis](#)
*processors per parallel analysis for a direct interface (from the `processors_per_analysis` specification in **InterfApplicDF**)*
- [StringArray gridHostNames](#)
*WEH - not currently used for grid computing names of host machines for a grid interface (from the `hostnames` specification in **InterfApplicG**).*

- [IntArray gridProcsPerHost](#)
*processors per host machine for a grid interface (from the processors_per_host specification in **Interf-ApplicG**)*
- [String interfaceSynchronization](#)
*parallel mode for a simulation-based interface: synchronous or asynchronous (from the asynchronous specification in **InterfIndControl**)*
- [int asynchLocalEvalConcurrency](#)
*evaluation concurrency for asynchronous simulation-based interfaces (from the evaluation_concurrency specification in **InterfIndControl**)*
- [int asynchLocalAnalysisConcurrency](#)
*analysis concurrency for asynchronous simulation-based interfaces (from the analysis_concurrency specification in **InterfIndControl**)*
- [int evalServers](#)
*number of evaluation servers to be used in the parallel configuration (from the evaluation_servers specification in **InterfIndControl**)*
- [String evalScheduling](#)
*the scheduling approach to be used for concurrent evaluations within an iterator (from the evaluation_self_scheduling and evaluation_static_scheduling specifications in **InterfIndControl**)*
- [int analysisServers](#)
*number of analysis servers to be used in the parallel configuration (from the analysis_servers specification in **InterfIndControl**)*
- [String analysisScheduling](#)
*the scheduling approach to be used for concurrent analyses within a function evaluation (from the analysis_self_scheduling and analysis_static_scheduling specifications in **InterfIndControl**)*
- [String failAction](#)
*the selected action upon capture of a simulation failure: abort, retry, recover, or continuation (from the failure_capture specification in **InterfIndControl**)*
- [int retryLimit](#)
*the limit on retries for captured simulation failures (from the retry specification in **InterfIndControl**)*
- [RealVector recoveryFnVals](#)
*the function values to be returned in a recovery operation for captured simulation failures (from the recover specification in **InterfIndControl**)*
- [bool activeSetVectorFlag](#)
*active set vector: 1=active (ASV control on), 0=inactive (ASV control off) (from the deactivate active_set_vector specification in **InterfIndControl**)*
- [bool evalCacheFlag](#)

*function evaluation cache: 1=active (all new evaluations checked against existing cache and then added to cache), 0=inactive (cache neither queried nor augmented) (from the deactivate evaluation_cache specification in **InterfIndControl**)*

- bool [restartFileFlag](#)

*function evaluation cache: 1=active (all new evaluations written to restart), 0=inactive (no records written to restart) (from the deactivate restart_file specification in **InterfIndControl**)*

Private Member Functions

- void [assign](#) (const [DataInterface](#) &data_interface)

convenience function for setting this objects attributes equal to the attributes of the incoming data_interface object (used by copy constructor and assignment operator)

10.24.1 Detailed Description

Container class for interface specification data.

The [DataInterface](#) class is used to contain the data from an interface keyword specification. It is populated by `ProblemDescDB::interface_kwhandler()` and is queried by the `ProblemDescDB::get_<datatype>()` functions. A list of [DataInterface](#) objects is maintained in `ProblemDescDB::interfaceList`, one for each interface specification in an input file. Default values are managed in the [DataInterface](#) constructor. Data is public to avoid maintaining set/get functions, but is still encapsulated within `ProblemDescDB` since `ProblemDescDB::interfaceList` is private (a similar model is used with [SurrogateDataPoint](#) objects contained in `Dakota::Approximation`).

The documentation for this class was generated from the following files:

- [DataInterface.H](#)
- [DataInterface.C](#)

10.25 DataMethod Class Reference

Container class for method specification data.

Public Member Functions

- [DataMethod \(\)](#)
constructor
- [DataMethod \(const DataMethod &\)](#)
copy constructor
- [~DataMethod \(\)](#)
destructor
- [DataMethod & operator= \(const DataMethod &\)](#)
assignment operator
- [bool operator== \(const DataMethod &\)](#)
equality operator
- [void write \(ostream &s\) const](#)
write a [DataMethod](#) object to an ostream
- [void read \(MPIUnpackBuffer &s\)](#)
read a [DataMethod](#) object from a packed MPI buffer
- [void write \(MPIPackBuffer &s\) const](#)
write a [DataMethod](#) object to a packed MPI buffer

Public Attributes

- [String idMethod](#)
*string identifier for the method specification data set (from the `id_method` specification in **MethodIndControl**)*
- [String modelPointer](#)
*string pointer to the model specification to be used by this method (from the `model_pointer` specification in **MethodIndControl**)*
- [String methodOutput](#)

*method verbosity control: quiet, verbose, debug, or normal (default) (from the output specification in **MethodIndControl**)*

- int [maxIterations](#)
*maximum number of iterations allowed for the method (from the max_iterations specification in **MethodIndControl**)*
- int [maxFunctionEvaluations](#)
*maximum number of function evaluations allowed for the method (from the max_function_evaluations specification in **MethodIndControl**)*
- bool [speculativeFlag](#)
*flag for use of speculative gradient approaches for maintaining parallel load balance during the line search portion of optimization algorithms (from the speculative specification in **MethodIndControl**)*
- Real [convergenceTolerance](#)
*iteration convergence tolerance for the method (from the convergence_tolerance specification in **MethodIndControl**)*
- Real [constraintTolerance](#)
*tolerance for controlling the amount of infeasibility that is allowed before an active constraint is considered to be violated (from the constraint_tolerance specification in **MethodIndControl**)*
- bool [methodScaling](#)
*flag indicating scaling status (from the scaling specification in **MethodIndControl**)*
- [RealVector linearIneqConstraintCoeffs](#)
*coefficient matrix for the linear inequality constraints (from the linear_inequality_constraint_matrix specification in **MethodIndControl**)*
- [RealVector linearIneqLowerBnds](#)
*lower bounds for the linear inequality constraints (from the linear_inequality_lower_bounds specification in **MethodIndControl**)*
- [RealVector linearIneqUpperBnds](#)
*upper bounds for the linear inequality constraints (from the linear_inequality_upper_bounds specification in **MethodIndControl**)*
- [RealVector linearIneqScales](#)
*scaling factors for the linear inequality constraints (from the linear_inequality_scales specification in **MethodIndControl**)*
- [RealVector linearEqConstraintCoeffs](#)
*coefficient matrix for the linear equality constraints (from the linear_equality_constraint_matrix specification in **MethodIndControl**)*
- [RealVector linearEqTargets](#)

*targets for the linear equality constraints (from the linear_equality_targets specification in **MethodIndControl**)*

- **RealVector linearEqScales**

*scaling factors for the linear equality constraints (from the linear_equality_scales specification in **MethodIndControl**)*

- **String methodName**

the method selection: one of the optimizer, least squares, nond, dace, or parameter study methods

- **String minMaxType**

*the optimization_type specification in **MethodDOTDC***

- **int verifyLevel**

*the verify_level specification in **MethodNPSOLDC***

- **Real functionPrecision**

*the function_precision specification in **MethodNPSOLDC***

- **Real lineSearchTolerance**

*the linesearch_tolerance specification in **MethodNPSOLDC***

- **Real absConvTol**

absolute function convergence tolerance

- **Real xConvTol**

x-convergence tolerance

- **Real singConvTol**

singular convergence tolerance

- **Real singRadius**

radius for singular convergence test

- **Real falseConvTol**

false-convergence tolerance

- **Real initTRRadius**

initial trust radius

- **int covarianceType**

kind of covariance required

- **bool regressDiag**

whether to print the regression diagnostic vector

- [String searchMethod](#)
*the search_method specification for Newton and nonlinear interior-point methods in **MethodOPTPPDC***
- [Real gradientTolerance](#)
*the gradient_tolerance specification in **MethodOPTPPDC***
- [Real maxStep](#)
*the max_step specification in **MethodOPTPPDC***
- [String meritFn](#)
*the merit_function specification for nonlinear interior-point methods in **MethodOPTPPDC***
- [String centralPath](#)
*the central_path specification for nonlinear interior-point methods in **MethodOPTPPDC***
- [Real stepLenToBoundary](#)
*the steplength_to_boundary specification for nonlinear interior-point methods in **MethodOPTPPDC***
- [Real centeringParam](#)
*the centering_parameter specification for nonlinear interior-point methods in **MethodOPTPPDC***
- [int searchSchemeSize](#)
*the search_scheme_size specification for PDS methods in **MethodOPTPPDC***
- [String evalSynchronization](#)
*the synchronization setting for parallel pattern search methods in **MethodCOLINYPS** and **MethodCOLINYAPPS***
- [Real constraintPenalty](#)
*the initial constraint_penalty for COLINY methods in **MethodCOLINYAPPS**, **MethodCOLINYDIR**, **MethodCOLINYPS**, **MethodCOLINYSW** and **MethodCOLINYE***
- [bool constantPenalty](#)
*the constant_penalty flag for COLINY methods in **MethodCOLINYPS** and **MethodCOLINYSW***
- [Real globalBalanceParam](#)
*the global_balance_parameter for the DIRECT method in **MethodCOLINYDIR***
- [Real localBalanceParam](#)
*the local_balance_parameter for the DIRECT method in **MethodCOLINYDIR***
- [Real maxBoxSize](#)
*the max_boxsize_limit for the DIRECT method in **MethodCOLINYDIR***
- [Real minBoxSize](#)
*the min_boxsize_limit for the DIRECT method in **MethodCOLINYDIR***

- [String boxDivision](#)
*the division setting (major_dimension or all_dimensions) for the DIRECT method in **MethodCOLINYDIR***
- [bool mutationAdaptive](#)
*the non_adaptive specification for the coliny_ea method in **MethodCOLINYEA***
- [bool showMiscOptions](#)
*the show_misc_options specification in **MethodCOLINYDC***
- [StringArray miscOptions](#)
*the misc_options specification in **MethodCOLINYDC***
- [Real solnAccuracy](#)
*the solution_accuracy specification in **MethodCOLINYDC***
- [Real crossoverRate](#)
*the crossover_rate specification for EA methods in **MethodCOLINYEA***
- [Real mutationRate](#)
*the mutation_rate specification for EA methods in **MethodCOLINYEA***
- [Real mutationScale](#)
*the mutation_scale specification for EA methods in **MethodCOLINYEA***
- [Real mutationMinScale](#)
*the min_scale specification for mutation in EA methods in **MethodCOLINYEA***
- [Real initDelta](#)
*the initial_delta specification for APPS/COBYLA/PS/SW methods in **MethodCOLINYAPPS**, **MethodCOLINYCOB**, **MethodCOLINYPS**, and **MethodCOLINYSW***
- [Real threshDelta](#)
*the threshold_delta specification for APPS/COBYLA/PS/SW methods in **MethodCOLINYAPPS**, **MethodCOLINYCOB**, **MethodCOLINYPS**, and **MethodCOLINYSW***
- [Real contractFactor](#)
*the contraction_factor specification for APPS/PS/SW methods in **MethodCOLINYAPPS**, **MethodCOLINYPS**, and **MethodCOLINYSW***
- [int newSolnsGenerated](#)
*the new_solutions_generated specification for GA/EPSSA methods in **MethodCOLINYEA***
- [int numberRetained](#)
*the integer assignment to random, chc, or elitist in the replacement_type specification for GA/EPSSA methods in **MethodCOLINYEA***

- bool `expansionFlag`
*the no_expansion specification for APPS/PS/SW methods in **MethodCOLINYAPPS**, **MethodCOLINYPS**, and **MethodCOLINYSW***
- int `expandAfterSuccess`
*the expand_after_success specification for PS/SW methods in **MethodCOLINYPS** and **MethodCOLINYSW***
- int `contractAfterFail`
*the contract_after_failure specification for the SW method in **MethodCOLINYSW***
- int `mutationRange`
*the mutation_range specification for the pga_int method in **MethodCOLINYEAA***
- int `totalPatternSize`
*the total_pattern_size specification for PS methods in **MethodCOLINYPS***
- bool `randomizeOrderFlag`
*the stochastic specification for the PS method in **MethodCOLINYPS***
- String `selectionPressure`
*the fitness_type specification for EA methods in **MethodCOLINYEAA***
- String `replacementType`
*the replacement_type specification for EA methods in **MethodCOLINYEAA***
- String `crossoverType`
*the crossover_type specification for EA methods in **MethodCOLINYEAA***
- String `mutationType`
*the mutation_type specification for EA methods in **MethodCOLINYEAA***
- String `exploratoryMoves`
*the exploratory_moves specification for the PS method in **MethodCOLINYPS***
- String `patternBasis`
*the pattern_basis specification for APPS/PS methods in **MethodCOLINYAPPS** and **MethodCOLINYPS***
- size_t `numCrossPoints`
The number of crossover points or multi-point schemes.
- size_t `numParents`
The number of parents to use in a crossover operation.
- size_t `numOffspring`

The number of children to produce in a crossover operation.

- **String fitnessType**

the fitness assessment operator to use.

- **String convergenceType**

The means by which this JEGA should converge.

- **Real percentChange**

The minimum percent change before convergence for a fitness tracker converger.

- **size_t numGenerations**

The number of generations over which a fitness tracker converger should track.

- **Real fitnessLimit**

The cutoff value for survival in fitness limiting selectors (e.g., below_limit selector).

- **Real shrinkagePercent**

The minimum percentage of the requested number of selections that must take place on each call to the selector (0, 1).

- **String nichingType**

The niching type.

- **RealVector nicheVector**

The discretization percentage along each objective.

- **String initializationType**

The means by which the JEGA should initialize the population.

- **String flatFile**

The filename to use for initialization.

- **String logFile**

The filename to use for logging.

- **int populationSize**

*the population_size specification for GA methods in **MethodCOLINYEA***

- **bool printPopFlag**

The print_each_pop flag to set the printing of the population at each generation.

- **String daceMethod**

*the dace method selection: grid, random, oas, lhs, oa_lhs, box_behnken, or central_composite (from the dace specification in **MethodDDACE**)*

- int `numSymbols`
the `numSymbols` specification for DACE methods
- bool `mainEffectsFlag`
*the `main_effects` specification for sampling methods in **MethodDDACE**)*
- bool `latinizeFlag`
*the `latinize` specification for FSU QMC and CVT methods in **MethodFSUDACE***
- bool `volQualityFlag`
*the `quality_metrics` specification for sampling methods (FSU QMC and CVT methods in **MethodFSUDACE**)*
- bool `varBasedDecompFlag`
*the `var_based_decomp` specification for sampling methods (FSU QMC and CVT methods in **MethodFSUDACE**)*
- `IntVector` `sequenceStart`
*the `sequenceStart` specification in **MethodFSUDACE***
- `IntVector` `sequenceLeap`
*the `sequenceLeap` specification in **MethodFSUDACE***
- `IntVector` `primeBase`
*the `primeBase` specification in **MethodFSUDACE***
- int `numTrials`
*the `numTrials` specification in **MethodFSUDACE***
- String `trialType`
*the `trial_type` specification in **MethodFSUDACE***
- int `randomSeed`
*the `seed` specification for COLINY, *NonD*, & DACE methods*
- int `numSamples`
*the `samples` specification for *NonD* & DACE methods*
- bool `fixedSeedFlag`
*flag for fixing the value of the seed among different *NonD*/DACE sample sets. This results in the use of the same sampling stencil/pattern throughout a strategy with repeated sampling.*
- bool `fixedSequenceFlag`
flag for fixing the sequence for Halton or Hammersley QMC sample sets. This results in the use of the same sampling stencil/pattern throughout a strategy with repeated sampling.
- int `expansionTerms`

*the expansion_terms specification in **MethodNonDPCE***

- **int expansionOrder**
*the expansion_order specification in **MethodNonDPCE***
- **String sampleType**
*the sample_type specification in **MethodNonDMC** and **MethodNonDPCE***
- **String reliabilitySearchType**
*the type of MPP search as specified by x_taylor_mean, x_taylor_mpp, u_taylor_mean, u_taylor_mpp, or no_approx in **MethodNonDRel***
- **String reliabilitySearchAlgorithm**
*the algorithm selection used for computing the MPP as specified by sqp or nip in **MethodNonDRel***
- **String reliabilityIntegration**
*the first_order/second_order integration selection in **MethodNonDRel***
- **String distributionType**
*the distribution cumulative or complementary specification in **MethodNonDMC**, **MethodNonDPCE**, and **MethodNonDRel***
- **String responseLevelMappingType**
*the compute probabilities or reliabilities specification in **MethodNonDMC**, **MethodNonDPCE**, and **MethodNonDRel***
- **RealVectorArray responseLevels**
*the response_levels specification in **MethodNonDMC**, **MethodNonDPCE**, and **MethodNonDRel***
- **RealVectorArray probabilityLevels**
*the probability_levels specification in **MethodNonDMC**, **MethodNonDPCE**, and **MethodNonDRel***
- **RealVectorArray reliabilityLevels**
*the reliability_levels specification in **MethodNonDMC**, **MethodNonDPCE**, and **MethodNonDRel***
- **bool allVarsFlag**
*the all_variables specification in **MethodNonDMC***
- **int paramStudyType**
the type of parameter study: list(-1), vector(1, 2, or 3), centered(4), or multidim(5)
- **RealVector finalPoint**
*the final_point specification in **MethodPSVPS***
- **RealVector stepVector**
*the step_vector specification in **MethodPSVPS***

- Real [stepLength](#)
*the step_length specification in **MethodPSVPS***
- int [numSteps](#)
*the num_steps specification in **MethodPSVPS***
- [RealVector](#) [listOfPoints](#)
*the list_of_points specification in **MethodPSLPS***
- Real [percentDelta](#)
*the percent_delta specification in **MethodPSCPS***
- int [deltasPerVariable](#)
*the deltas_per_variable specification in **MethodPSCPS***
- [IntArray](#) [varPartitions](#)
*the partitions specification for PStudy method in **MethodPSMPS***

Private Member Functions

- void [assign](#) (const [DataMethod](#) &data_method)
convenience function for setting this objects attributes equal to the attributes of the incoming data_method object (used by copy constructor and assignment operator)

10.25.1 Detailed Description

Container class for method specification data.

The [DataMethod](#) class is used to contain the data from a method keyword specification. It is populated by `ProblemDescDB::method_kwhandler()` and is queried by the `ProblemDescDB::get_<datatype>()` functions. A list of [DataMethod](#) objects is maintained in `ProblemDescDB::methodList`, one for each method specification in an input file. Default values are managed in the [DataMethod](#) constructor. Data is public to avoid maintaining set/get functions, but is still encapsulated within [ProblemDescDB](#) since `ProblemDescDB::methodList` is private (a similar model is used with [SurrogateDataPoint](#) objects contained in [Dakota::Approximation](#)).

The documentation for this class was generated from the following files:

- [DataMethod.H](#)
- [DataMethod.C](#)

10.26 DataModel Class Reference

Container class for model specification data.

Public Member Functions

- [DataModel \(\)](#)
constructor
- [DataModel \(const DataModel &\)](#)
copy constructor
- [~DataModel \(\)](#)
destructor
- [DataModel & operator= \(const DataModel &\)](#)
assignment operator
- [bool operator== \(const DataModel &\)](#)
equality operator
- [void write \(ostream &s\) const](#)
write a DataModel object to an ostream
- [void read \(MPIUnpackBuffer &s\)](#)
read a DataModel object from a packed MPI buffer
- [void write \(MPIPackBuffer &s\) const](#)
write a DataModel object to a packed MPI buffer

Public Attributes

- [String idModel](#)
string identifier for the model specification data set (from the id_model specification in ModelIndControl)
- [String modelType](#)
model type selection: single, surrogate, or nested (from the model type specification in ModelIndControl)
- [String variablesPointer](#)
string pointer to the variables specification to be used by this model (from the variables_pointer specification in ModelIndControl)

- **String interfacePointer**
*string pointer to the interface specification to be used by this model (from the `interface_pointer` specification in **ModelSingle** and the `optional_interface_pointer` specification in **ModelNested**)*
- **String responsesPointer**
*string pointer to the responses specification to be used by this model (from the `responses_pointer` specification in **ModelIndControl**)*
- **IntArray surrogateFnIds**
array specifying the response function set that is approximated
- **String approxType**
the selected approximation type: `local_taylor`, `multipoint_tana`, `global_(neural_network,mars,hermite,gaussian,polynomial,kriging)`, or hierarchical
- **String actualModelPtr**
*pointer to the interface specification for constructing the truth model used in building local and multipoint approximations (from the `actual_model_pointer` specification in **ModelSurrL** and **ModelSurrMP**)*
- **String lowFidelityModelPtr**
*pointer to the low fidelity model specification used in hierarchical approximations (from the `low_fidelity_model_pointer` specification in **ModelSurrH**)*
- **String highFidelityModelPtr**
*pointer to the high fidelity model specification used in hierarchical approximations (from the `high_fidelity_model_pointer` specification in **ModelSurrH**)*
- **String approxDaceMethodPtr**
*pointer to the design of experiments method used in building global approximations (from the `dace_method_pointer` specification in **ModelSurrG**)*
- **String approxSampleReuse**
*sample reuse selection for building global approximations: `none`, `all`, `region`, or `file` (from the `reuse_samples` specification in **ModelSurrG**)*
- **String approxSampleReuseFile**
*the file name for the "file" setting for the `reuse_samples` specification in **ModelSurrG***
- **String approxCorrectionType**
*correction type for global and hierarchical approximations: `additive` or `multiplicative` (from the `correction` specification in **ModelSurrG** and **ModelSurrH**)*
- short **approxCorrectionOrder**
*correction order for global and hierarchical approximations: `0`, `1`, or `2` (from the `correction` specification in **ModelSurrG** and **ModelSurrH**)*

- bool [approxGradUsageFlag](#)
*flags the use of gradients in building global approximations (from the `use_gradients` specification in **ModelSurrG**)*
- [RealVector krigingCorrelations](#)
*vector of correlations used in building a kriging approximation (from the `correlations` specification in **ModelSurrG**)*
- short [polynomialOrder](#)
*scalar integer indicating the order of the polynomial approximation (1=linear, 2=quadratic, 3=cubic; from the `polynomial` specification in **ModelSurrG**)*
- [String optionalInterfRespPointer](#)
*string pointer to the responses specification used by the optional interface in nested models (from the `optional_interface_responses_pointer` specification in **ModelNested**)*
- [String subMethodPointer](#)
*string pointer to the sub-iterator used by nested models (from the `sub_method_pointer` specification in **ModelNested**)*
- [StringArray primaryVarMaps](#)
*the primary variable mappings used in nested models for identifying the lower level variable targets for inserting top level variable values (from the `primary_variable_mapping` specification in **ModelNested**)*
- [StringArray secondaryVarMaps](#)
*the secondary variable mappings used in nested models for identifying the (distribution) parameter targets within the lower level variables for inserting top level variable values (from the `secondary_variable_mapping` specification in **ModelNested**)*
- [RealVector primaryRespCoeffs](#)
*the primary response mapping matrix used in nested models for weighting contributions from the sub-iterator responses in the top level (objective) functions (from the `primary_response_mapping` specification in **ModelNested**)*
- [RealVector secondaryRespCoeffs](#)
*the secondary response mapping matrix used in nested models for weighting contributions from the sub-iterator responses in the top level (constraint) functions (from the `secondary_response_mapping` specification in **ModelNested**)*

Private Member Functions

- void [assign](#) (const [DataModel](#) &data_model)
convenience function for setting this objects attributes equal to the attributes of the incoming data_model object (used by copy constructor and assignment operator)

10.26.1 Detailed Description

Container class for model specification data.

The [DataModel](#) class is used to contain the data from a model keyword specification. It is populated by `ProblemDescDB::model_kwhandler()` and is queried by the `ProblemDescDB::get_<datatype>()` functions. A list of [DataModel](#) objects is maintained in [ProblemDescDB::modelList](#), one for each model specification in an input file. Default values are managed in the [DataModel](#) constructor. Data is public to avoid maintaining set/get functions, but is still encapsulated within [ProblemDescDB](#) since [ProblemDescDB::modelList](#) is private (a similar model is used with [SurrogateDataPoint](#) objects contained in [Dakota::Approximation](#)).

The documentation for this class was generated from the following files:

- [DataModel.H](#)
- [DataModel.C](#)

10.27 DataResponses Class Reference

Container class for responses specification data.

Public Member Functions

- [DataResponses](#) ()
constructor
- [DataResponses](#) (const [DataResponses](#) &)
copy constructor
- [~DataResponses](#) ()
destructor
- [DataResponses](#) & [operator=](#) (const [DataResponses](#) &)
assignment operator
- bool [operator==](#) (const [DataResponses](#) &)
equality operator
- void [write](#) (ostream &s) const
write a [DataResponses](#) object to an ostream
- void [read](#) (MPIUnpackBuffer &s)
read a [DataResponses](#) object from a packed MPI buffer
- void [write](#) (MPIPackBuffer &s) const
write a [DataResponses](#) object to a packed MPI buffer

Public Attributes

- size_t [numObjectiveFunctions](#)
*number of objective functions (from the num_objective_functions specification in **RespFnOpt**)*
- size_t [numNonlinearIneqConstraints](#)
*number of nonlinear inequality constraints (from the num_nonlinear_inequality_constraints specification in **RespFnOpt**)*
- size_t [numNonlinearEqConstraints](#)

*number of nonlinear equality constraints (from the `num_nonlinear_equality_constraints` specification in **RespFnOpt**)*

- `size_t numLeastSqTerms`
*number of least squares terms (from the `num_least_squares_terms` specification in **RespFnLS**)*
- `size_t numResponseFunctions`
*number of generic response functions (from the `num_response_functions` specification in **RespFnGen**)*
- `RealVector objectiveFunctionScales`
*vector of objective function scaling factors (from the `objective_function_scales` specification in **RespFnOpt**)*
- `RealVector multiObjectiveWeights`
*vector of multiobjective weightings (from the `multi_objective_weights` specification in **RespFnOpt**)*
- `RealVector leastSqTermScales`
*vector of least squares term scaling factors (from the `least_squares_term_scales` specification in **RespFnOpt**)*
- `RealVector nonlinearIneqLowerBnds`
*vector of nonlinear inequality constraint lower bounds (from the `nonlinear_inequality_lower_bounds` specification in **RespFnOpt**)*
- `RealVector nonlinearIneqUpperBnds`
*vector of nonlinear inequality constraint upper bounds (from the `nonlinear_inequality_upper_bounds` specification in **RespFnOpt**)*
- `RealVector nonlinearIneqScales`
*vector of nonlinear inequality constraint scaling factors (from the `nonlinear_inequality_scales` specification in **RespFnOpt**)*
- `RealVector nonlinearEqTargets`
*vector of nonlinear equality constraint targets (from the `nonlinear_equality_targets` specification in **RespFnOpt**)*
- `RealVector nonlinearEqScales`
*vector of nonlinear equality constraint scaling factors (from the `nonlinear_equality_scales` specification in **RespFnOpt**)*
- `String gradientType`
*gradient type: none, numerical, analytic, or mixed (from the `no_gradients`, `numerical_gradients`, `analytic_gradients`, and `mixed_gradients` specifications in **RespGrad**)*
- `String hessianType`
*Hessian type: none, numerical, quasi, analytic, or mixed (from the `no_hessians`, `numerical_hessians`, `quasi_hessians`, `analytic_hessians`, and `mixed_hessians` specifications in **RespHess**).*

- [String quasiHessianType](#)
*quasi-Hessian type: bfgs, damped_bfgs, or srl (from the bfgs and srl specifications in **RespHess**)*
- [String methodSource](#)
*numerical gradient method source: dakota or vendor (from the method_source specification in **RespGradNum** and **RespGradMixed**)*
- [String intervalType](#)
*numerical gradient interval type: forward or central (from the interval_type specification in **RespGradNum** and **RespGradMixed**)*
- [RealVector fdGradStepSize](#)
*vector of finite difference step sizes for numerical gradients, one step size per active continuous variable, used in computing 1st-order forward or central differences (from the fd_gradient_step_size specification in **RespGradNum** and **RespGradMixed**)*
- [RealVector fdHessStepSize](#)
*vector of finite difference step sizes for numerical Hessians, one step size per active continuous variable, used in computing 1st-order gradient-based differences and 2nd-order function-based differences (from the fd_hessian_step_size specification in **RespHessNum** and **RespHessMixed**)*
- [IntList idNumericalGrads](#)
*mixed gradient numerical identifiers (from the id_numerical_gradients specification in **RespGradMixed**)*
- [IntList idAnalyticGrads](#)
*mixed gradient analytic identifiers (from the id_analytic_gradients specification in **RespGradMixed**)*
- [IntList idNumericalHessians](#)
*mixed Hessian numerical identifiers (from the id_numerical_hessians specification in **RespHessMixed**)*
- [IntList idQuasiHessians](#)
*mixed Hessian quasi identifiers (from the id_quasi_hessians specification in **RespHessMixed**)*
- [IntList idAnalyticHessians](#)
*mixed Hessian analytic identifiers (from the id_analytic_hessians specification in **RespHessMixed**)*
- [String idResponses](#)
*string identifier for the responses specification data set (from the id_responses specification in **RespSetId**)*
- [StringArray responseLabels](#)
*the response labels array (from the response_descriptors specification in **RespLabels**)*

Private Member Functions

- void `assign` (const [DataResponses](#) &data_responses)

convenience function for setting this objects attributes equal to the attributes of the incoming data_responses object (used by copy constructor and assignment operator)

10.27.1 Detailed Description

Container class for responses specification data.

The [DataResponses](#) class is used to contain the data from a responses keyword specification. It is populated by `ProblemDescDB::responses_kwhandler()` and is queried by the `ProblemDescDB::get_<datatype>()` functions. A list of [DataResponses](#) objects is maintained in `ProblemDescDB::responsesList`, one for each responses specification in an input file. Default values are managed in the [DataResponses](#) constructor. Data is public to avoid maintaining set/get functions, but is still encapsulated within [ProblemDescDB](#) since `ProblemDescDB::responsesList` is private (a similar model is used with [SurrogateDataPoint](#) objects contained in [Dakota::Approximation](#)).

The documentation for this class was generated from the following files:

- [DataResponses.H](#)
- [DataResponses.C](#)

10.28 DataStrategy Class Reference

Container class for strategy specification data.

Public Member Functions

- [DataStrategy \(\)](#)
constructor
- [DataStrategy \(const DataStrategy &\)](#)
copy constructor
- [~DataStrategy \(\)](#)
destructor
- [DataStrategy & operator= \(const DataStrategy &\)](#)
assignment operator
- void [write](#) (ostream &s) const
write a DataStrategy object to an ostream
- void [read](#) (MPIUnpackBuffer &s)
read a DataStrategy object from a packed MPI buffer
- void [write](#) (MPIPackBuffer &s) const
write a DataStrategy object to a packed MPI buffer

Public Attributes

- [String strategyType](#)
the strategy selection: multi_level, surrogate_based_opt, branch_and_bound, multi_start, pareto_set, or single_method
- bool [graphicsFlag](#)
*flags use of graphics by the strategy (from the graphics specification in **StratIndControl**)*
- bool [tabularDataFlag](#)
*flags tabular data collection by the strategy (from the tabular_graphics_data specification in **StratIndControl**)*
- [String tabularDataFile](#)

*the filename used for tabular data collection by the strategy (from the `tabular_graphics_file` specification in **StratIndControl**)*

- **int `iteratorServers`**
*number of servers for concurrent iterator parallelism (from the `iterator_servers` specification in **StratIndControl**)*
- **String `iteratorScheduling`**
*type of scheduling (self or static) used in concurrent iterator parallelism (from the `iterator_self_scheduling` and `iterator_static_scheduling` specifications in **StratIndControl**)*
- **String `methodPointer`**
*method identifier for the strategy (from the `opt_method_pointer` specifications in **StratSBO** and **StratParetoSet** and `method_pointer` specifications in **StratSingle** and **StratMultiStart**)*
- **StringArray `multilevelMethodList`**
*array of methods for the multilevel hybrid optimization strategy (from the `method_list` specification in **StratML**)*
- **String `multilevelType`**
*the type of multilevel hybrid optimization strategy: `uncoupled`, `uncoupled_adaptive`, or `coupled` (from the `uncoupled`, `adaptive`, and `coupled` specifications in **StratML**)*
- **Real `multilevelProgThresh`**
*progress threshold for `uncoupled_adaptive` multilevel hybrids (from the `progress_threshold` specification in **StratML**)*
- **String `multilevelGlobalMethodPointer`**
*global method pointer for coupled multilevel hybrids (from the `global_method_pointer` specification in **StratML**)*
- **String `multilevelLocalMethodPointer`**
*local method pointer for coupled multilevel hybrids (from the `local_method_pointer` specification in **StratML**)*
- **Real `multilevelLSProb`**
*local search probability for coupled multilevel hybrids (from the `local_search_probability` specification in **StratML**)*
- **int `surrBasedOptMaxIterations`**
*maximum number of iterations in the surrogate-based optimization strategy (from the `max_iterations` specification in **StratSBO**)*
- **Real `surrBasedOptConvTol`**
*convergence tolerance in the surrogate-based optimization strategy (from the `convergence_tolerance` specification in **StratSBO**)*
- **int `surrBasedOptSoftConvLimit`**
*number of consecutive iterations with change less than `surrBasedOptConvTol` required to trigger convergence within the surrogate-based optimization strategy (from the `soft_convergence_limit` specification in **StratSBO**)*

- bool `surrBasedOptLayerBypass`
flag to indicate user-specification of a bypass of any/all layerings in evaluating truth response values in SBO.
- Real `surrBasedOptTRInitSize`
*initial trust region size in the surrogate-based optimization strategy (from the `initial_size` specification in **StratSBO**) note: this is a relative value, e.g., 0.1 = 10% of global bounds distance (upper bound - lower bound) for each variable*
- Real `surrBasedOptTRMinSize`
*minimum trust region size in the surrogate-based optimization strategy (from the `minimum_size` specification in **StratSBO**), if the trust region size falls below this threshold the SBO iterations are terminated (note: if kriging is used with SBO, the min trust region size is set to 1.0e-3 in attempt to avoid ill-conditioned matrixes that arise in kriging over small trust regions)*
- Real `surrBasedOptTRContractTrigger`
*trust region minimum improvement level (ratio of actual to predicted decrease in objective fcn) in the surrogate-based optimization strategy (from the `contract_threshold` specification in **StratSBO**), the trust region shrinks or is rejected if the ratio is below this value ("`eta_1`" in the Conn-Gould-Toint trust region book)*
- Real `surrBasedOptTRExpandTrigger`
*trust region sufficient improvement level (ratio of actual to predicted decrease in objective fn) in the surrogate-based optimization strategy (from the `expand_threshold` specification in **StratSBO**), the trust region expands if the ratio is above this value ("`eta_2`" in the Conn-Gould-Toint trust region book)*
- Real `surrBasedOptTRContract`
*trust region contraction factor in the surrogate-based optimization strategy (from the `contraction_factor` specification in **StratSBO**)*
- Real `surrBasedOptTRExpand`
*trust region expansion factor in the surrogate-based optimization strategy (from the `expansion_factor` specification in **StratSBO**)*
- bool `surrBasedOptTRConstraintRelax`
flag to use trust region constraint relaxation for infeasible points
- int `surrBasedOptTRConstraintRelaxMethod`
trust region constraint relaxation method (currently implements: homotopy)
- int `concurrentRandomJobs`
*number of random jobs to perform in the concurrent strategy (from the `random_starts` and `random_weight_sets` specifications in **StratMultiStart** and **StratParetoSet**)*
- int `concurrentSeed`
*seed for the selected random jobs within the concurrent strategy (from the `seed` specification in **StratMultiStart** and **StratParetoSet**)*
- RealVector `concurrentParameterSets`
*user-specified (i.e., nonrandom) parameter sets to evaluate in the concurrent strategy (from the `starting_points` and `multi_objective_weight_sets` specifications in **StratMultiStart** and **StratParetoSet**)*

Private Member Functions

- void `assign` (const [DataStrategy](#) &data_strategy)
convenience function for setting this objects attributes equal to the attributes of the incoming data_strategy object (used by copy constructor and assignment operator)

10.28.1 Detailed Description

Container class for strategy specification data.

The [DataStrategy](#) class is used to contain the data from a strategy keyword specification. It is populated by `ProblemDescDB::strategy_kwhandler()` and is queried by the `ProblemDescDB::get_<datatype>()` functions. Default values are managed in the [DataStrategy](#) constructor. Data is public to avoid maintaining set/get functions, but is still encapsulated within [ProblemDescDB](#) since `ProblemDescDB::strategySpec` is private (a similar model is used with [SurrogateDataPoint](#) objects contained in [Dakota::Approximation](#)).

The documentation for this class was generated from the following files:

- [DataStrategy.H](#)
- [DataStrategy.C](#)

10.29 DataVariables Class Reference

Container class for variables specification data.

Public Member Functions

- [DataVariables](#) ()
constructor
- [DataVariables](#) (const [DataVariables](#) &)
copy constructor
- [~DataVariables](#) ()
destructor
- [DataVariables](#) & [operator=](#) (const [DataVariables](#) &)
assignment operator
- bool [operator==](#) (const [DataVariables](#) &)
equality operator
- void [write](#) (ostream &s) const
write a [DataVariables](#) object to an ostream
- void [read](#) (MPIUnpackBuffer &s)
read a [DataVariables](#) object from a packed MPI buffer
- void [write](#) (MPIPackBuffer &s) const
write a [DataVariables](#) object to a packed MPI buffer
- size_t [design](#) ()
return total number of design variables
- size_t [uncertain](#) ()
return total number of uncertain variables
- size_t [state](#) ()
return total number of state variables
- size_t [num_continuous_variables](#) ()
return total number of continuous variables

- `size_t num_discrete_variables ()`
return total number of discrete variables
- `size_t num_variables ()`
return total number of variables

Public Attributes

- `String idVariables`
*string identifier for the variables specification data set (from the `id_variables` specification in **VarSetId**)*
- `size_t numContinuousDesVars`
*number of continuous design variables (from the `continuous_design` specification in **VarDV**)*
- `size_t numDiscreteDesVars`
*number of discrete design variables (from the `discrete_design` specification in **VarDV**)*
- `size_t numNormalUncVars`
*number of normal uncertain variables (from the `normal_uncertain` specification in **VarUV**)*
- `size_t numLognormalUncVars`
*number of lognormal uncertain variables (from the `lognormal_uncertain` specification in **VarUV**)*
- `size_t numUniformUncVars`
*number of uniform uncertain variables (from the `uniform_uncertain` specification in **VarUV**)*
- `size_t numLoguniformUncVars`
*number of loguniform uncertain variables (from the `loguniform_uncertain` specification in **VarUV**)*
- `size_t numTriangularUncVars`
*number of triangular uncertain variables (from the `triangular_uncertain` specification in **VarUV**)*
- `size_t numWeibullUncVars`
*number of weibull uncertain variables (from the `weibull_uncertain` specification in **VarUV**)*
- `size_t numBetaUncVars`
*number of beta uncertain variables (from the `beta_uncertain` specification in **VarUV**)*
- `size_t numGammaUncVars`
*number of gamma uncertain variables (from the `gamma_uncertain` specification in **VarUV**)*
- `size_t numFrechetUncVars`
*number of frechet uncertain variables (from the `frechet_uncertain` specification in **VarUV**)*
- `size_t numGumbelUncVars`

- number of gumbel uncertain variables (from the `gumbel_uncertain` specification in **VarUV**)*
- `size_t numHistogramUncVars`
*number of histogram uncertain variables (from the `histogram_uncertain` specification in **VarUV**)*
- `size_t numIntervalUncVars`
*number of interval uncertain variables (from the `interval_uncertain` specification in **VarUV**)*
- `size_t numContinuousStateVars`
*number of continuous state variables (from the `continuous_state` specification in **VarSV**)*
- `size_t numDiscreteStateVars`
*number of discrete state variables (from the `discrete_state` specification in **VarSV**)*
- `RealVector continuousDesignVars`
*initial values for the continuous design variables array (from the `cdv_initial_point` specification in **VarDV**)*
- `RealVector continuousDesignLowerBnds`
*the continuous design lower bounds array (from the `cdv_lower_bounds` specification in **VarDV**)*
- `RealVector continuousDesignUpperBnds`
*the continuous design upper bounds array (from the `cdv_upper_bounds` specification in **VarDV**)*
- `RealVector continuousDesignScales`
*the continuous design scales array (from the `cdv_scales` specification in **VarDV**)*
- `IntVector discreteDesignVars`
*initial values for the discrete design variables array (from the `ddv_initial_point` specification in **VarDV**)*
- `IntVector discreteDesignLowerBnds`
*the discrete design lower bounds array (from the `ddv_lower_bounds` specification in **VarDV**)*
- `IntVector discreteDesignUpperBnds`
*the discrete design upper bounds array (from the `ddv_upper_bounds` specification in **VarDV**)*
- `StringArray continuousDesignLabels`
*the continuous design labels array (from the `cdv_descriptors` specification in **VarDV**)*
- `StringArray discreteDesignLabels`
*the discrete design labels array (from the `ddv_descriptors` specification in **VarDV**)*
- `RealVector normalUncMeans`
*means of the normal uncertain variables (from the `nuv_means` specification in **VarUV**)*
- `RealVector normalUncStdDevs`
*standard deviations of the normal uncertain variables (from the `nuv_std_deviations` specification in **VarUV**)*

- [RealVector normalUncLowerBnds](#)
*distribution lower bounds for the normal uncertain variables (from the nuv_lower_bounds specification in **VarUV**)*
- [RealVector normalUncUpperBnds](#)
*distribution upper bounds for the normal uncertain variables (from the nuv_upper_bounds specification in **VarUV**)*
- [RealVector lognormalUncMeans](#)
*means of the lognormal uncertain variables (from the lnuv_means specification in **VarUV**)*
- [RealVector lognormalUncStdDevs](#)
*standard deviations of the lognormal uncertain variables (from the lnuv_std_deviations specification in **VarUV**)*
- [RealVector lognormalUncErrFacts](#)
*error factors for the lognormal uncertain variables (from the lnuv_error_factors specification in **VarUV**)*
- [RealVector lognormalUncLowerBnds](#)
*distribution lower bounds for the lognormal uncertain variables (from the lnuv_lower_bounds specification in **VarUV**)*
- [RealVector lognormalUncUpperBnds](#)
*distribution upper bounds for the lognormal uncertain variables (from the lnuv_upper_bounds specification in **VarUV**)*
- [RealVector uniformUncLowerBnds](#)
*distribution lower bounds for the uniform uncertain variables (from the uuv_lower_bounds specification in **VarUV**)*
- [RealVector uniformUncUpperBnds](#)
*distribution upper bounds for the uniform uncertain variables (from the uuv_upper_bounds specification in **VarUV**)*
- [RealVector loguniformUncLowerBnds](#)
*distribution lower bounds for the loguniform uncertain variables (from the luuv_lower_bounds specification in **VarUV**)*
- [RealVector loguniformUncUpperBnds](#)
*distribution upper bounds for the loguniform uncertain variables (from the luuv_upper_bounds specification in **VarUV**)*
- [RealVector triangularUncModes](#)
*modes of the triangular uncertain variables (from the tuv_modes specification in **VarUV**)*
- [RealVector triangularUncLowerBnds](#)

*distribution lower bounds for the triangular uncertain variables (from the `tuv_lower_bounds` specification in **VarUV**)*

- [RealVector triangularUncUpperBnds](#)

*distribution upper bounds for the triangular uncertain variables (from the `tuv_upper_bounds` specification in **VarUV**)*

- [RealVector betaUncAlphas](#)

*alpha factors for the beta uncertain variables (from the `buv_means` specification in **VarUV**)*

- [RealVector betaUncBetas](#)

*beta factors for the beta uncertain variables (from the `buv_std_deviations` specification in **VarUV**)*

- [RealVector betaUncLowerBnds](#)

*distribution lower bounds for the beta uncertain variables (from the `buv_lower_bounds` specification in **VarUV**)*

- [RealVector betaUncUpperBnds](#)

*distribution upper bounds for the beta uncertain variables (from the `buv_upper_bounds` specification in **VarUV**)*

- [RealVector gammaUncAlphas](#)

*alpha factors for the gamma uncertain variables (from the `gauv_alphas` specification in **VarUV**)*

- [RealVector gammaUncBetas](#)

*beta factors for the gamma uncertain variables (from the `gauv_betas` specification in **VarUV**)*

- [RealVector gumbelUncAlphas](#)

*alpha factors for the gumbel uncertain variables (from the `guuv_alphas` specification in **VarUV**)*

- [RealVector gumbelUncBetas](#)

*beta factors for of the gumbel uncertain variables (from the `guuv_betas` specification in **VarUV**)*

- [RealVector frechetUncAlphas](#)

*alpha factors for the frechet uncertain variables (from the `fuv_alphas` specification in **VarUV**)*

- [RealVector frechetUncBetas](#)

*beta factors for the frechet uncertain variables (from the `fuv_betas` specification in **VarUV**)*

- [RealVector weibullUncAlphas](#)

*alpha factors for the weibull uncertain variables (from the `wuv_alphas` specification in **VarUV**)*

- [RealVector weibullUncBetas](#)

*beta factors for the weibull uncertain variables (from the `wuv_betas` specification in **VarUV**)*

- [RealVectorArray histogramUncBinPairs](#)

*an array containing a vector of (x,y) pairs for each bin-based histogram uncertain variable (see continuous linear histogram in LHS manual; from the `huv_num_bin_pairs` and `huv_bin_pairs` specifications in **VarUV**)*

- **RealVectorArray histogramUncPointPairs**
*an array containing a vector of (x,y) pairs for each point-based histogram uncertain variable (see discrete histogram in LHS manual; from the `huv_num_point_pairs` and `huv_point_pairs` specifications in **VarUV**)*
- **IntVector intervalUncNumIntervals**
*number of intervals per interval uncertain variables (from the `iuv_num_intervals` specification in **VarUV**)*
- **RealVector intervalUncProbValues**
*Probability values per interval uncertain variables (from the `iuv_interval_probs` specification in **VarUV**).*
- **RealVector intervalUncIntervalBounds**
*Interval Bounds per interval uncertain variables (from the `iuv_interval_bounds` specification in **VarUV**).*
- **RealMatrix uncertainCorrelations**
*correlation matrix for all uncertain variables (from the `uncertain_correlation_matrix` specification in **VarUV**). This matrix specifies rank correlations for sampling methods (i.e., LHS) and correlation coefficients (ρ_{ij} = normalized covariance matrix) for analytic reliability methods.*
- **RealVector uncertainVars**
array of values for all uncertain variables (built and initialized in `ProblemDescDB::variables_kwhandler()`)
- **RealVector uncertainLowerBnds**
*distribution lower bounds for all uncertain variables (collected from `nuv_lower_bounds`, `lnuv_lower_bounds`, `uuv_lower_bounds`, `luuv_lower_bounds`, `tuv_lower_bounds`, and `buv_lower_bounds` specifications in **VarUV**, and derived for gamma, gumbel, frechet, weibull and histogram specifications)*
- **RealVector uncertainUpperBnds**
*distribution upper bounds for all uncertain variables (collected from `nuv_upper_bounds`, `lnuv_upper_bounds`, `uuv_upper_bounds`, `luuv_upper_bounds`, `tuv_lower_bounds`, and `buv_upper_bounds` specifications in **VarUV**, and derived for gamma, gumbel, frechet, weibull and histogram specifications)*
- **StringArray uncertainLabels**
*labels for all uncertain variables (collected from `nuv_descriptors`, `lnuv_descriptors`, `uuv_descriptors`, `luuv_descriptors`, `tuv_descriptors`, `buv_descriptors`, `gauv_descriptors`, `guuv_descriptors`, `fuv_descriptors`, `wuv_descriptors`, and `huv_descriptors` specifications in **VarUV**)*
- **RealVector continuousStateVars**
*initial values for the continuous state variables array (from the `csv_initial_state` specification in **VarSV**)*
- **RealVector continuousStateLowerBnds**
*the continuous state lower bounds array (from the `csv_lower_bounds` specification in **VarSV**)*
- **RealVector continuousStateUpperBnds**
*the continuous state upper bounds array (from the `csv_upper_bounds` specification in **VarSV**)*

- [IntVector discreteStateVars](#)
initial values for the discrete state variables array (from the dsv_initial_state specification in VarSV)
- [IntVector discreteStateLowerBnds](#)
the discrete state lower bounds array (from the dsv_lower_bounds specification in VarSV)
- [IntVector discreteStateUpperBnds](#)
the discrete state upper bounds array (from the dsv_upper_bounds specification in VarSV)
- [StringArray continuousStateLabels](#)
the continuous state labels array (from the csv_descriptors specification in VarSV)
- [StringArray discreteStateLabels](#)
the discrete state labels array (from the dsv_descriptors specification in VarSV)

Private Member Functions

- void [assign](#) (const [DataVariables](#) &data_variables)
convenience function for setting this objects attributes equal to the attributes of the incoming data_variables object (used by copy constructor and assignment operator)

10.29.1 Detailed Description

Container class for variables specification data.

The [DataVariables](#) class is used to contain the data from a variables keyword specification. It is populated by [ProblemDescDB::variables_kwhandler\(\)](#) and is queried by the [ProblemDescDB::get_<datatype>\(\)](#) functions. A list of [DataVariables](#) objects is maintained in [ProblemDescDB::variablesList](#), one for each variables specification in an input file. Default values are managed in the [DataVariables](#) constructor. Data is public to avoid maintaining set/get functions, but is still encapsulated within [ProblemDescDB](#) since [ProblemDescDB::variablesList](#) is private (a similar model is used with [SurrogateDataPoint](#) objects contained in [Dakota::Approximation](#)).

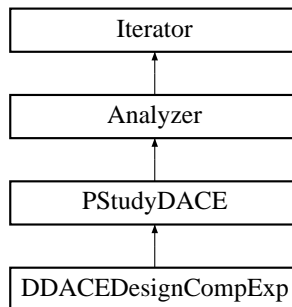
The documentation for this class was generated from the following files:

- [DataVariables.H](#)
- [DataVariables.C](#)

10.30 DDACEDesignCompExp Class Reference

Wrapper class for the DDACE design of experiments library.

Inheritance diagram for DDACEDesignCompExp::



Public Member Functions

- [DDACEDesignCompExp](#) ([Model](#) &model)
 - primary constructor for building a standard DACE iterator*
- [~DDACEDesignCompExp](#) ()
 - destructor*
- void [extract_trends](#) ()
 - Redefines the run_iterator virtual function for the PStudy/DACE branch.*
- void [sampling_reset](#) (int min_samples, bool all_data_flag, bool stats_flag)
 - reset sampling iterator*
- const [String](#) & [sampling_scheme](#) () const
 - return sampling name*
- void [vary_pattern](#) (bool pattern_flag)
 - sets varyPattern in derived classes that support it*
- void [get_parameter_sets](#) ()
 - Returns one block of samples (ndim * num_samples).*

Private Member Functions

- void `compute_main_effects()`
builds a `DDaceMainEffects::OneWayANOVA` if `mainEffectsFlag` is set
- void `resolve_samples_symbols()`
convenience function for resolving number of samples and number of symbols from input.

Private Attributes

- String `daceMethod`
oas, lhs, oa_lhs, random, box_behnken, central_composite, or grid
- int `samplesSpec`
user specification of number of samples
- int `numSamples`
number of samples to be evaluated
- int `numSymbols`
number of symbols to be used in generating the sample set (inversely related to number of replications)
- const int `originalSeed`
the user seed specification for the random number generator (allows repeatable results)
- int `randomSeed`
current seed for the random number generator
- bool `allDataFlag`
flag which triggers the update of `allVars/allResponses` for use by `Iterator::all_variables()` and `Iterator::all_responses()`
- size_t `numDACERuns`
counter for number of `run()` executions for this object
- bool `varyPattern`
flag for continuing the random number sequence from a previous `run()` execution (e.g., for surrogate-based optimization) so that multiple executions are repeatable but not correlated.
- bool `volQualityFlag`
flag which specifies evaluating the volumetric quality measures
- bool `varBasedDecompFlag`
flag which specifies variance based decomposition

- bool [mainEffectsFlag](#)
flag which specifies main effects
- `std::vector< std::vector< int > >` [symbolMapping](#)
mapping of symbols for main effects calculations

10.30.1 Detailed Description

Wrapper class for the DDACE design of experiments library.

The [DDACEDesignCompExp](#) class provides a wrapper for DDACE, a C++ design of experiments library from the Computational Sciences and Mathematics Research (CSMR) department at Sandia's Livermore CA site. This class uses design and analysis of computer experiments (DACE) methods to sample the design space spanned by the bounds of a [Model](#). It returns all generated samples and their corresponding responses as well as the best sample found.

10.30.2 Constructor & Destructor Documentation

10.30.2.1 [DDACEDesignCompExp](#) ([Model](#) & *model*)

primary constructor for building a standard DACE iterator

This constructor is called for a standard iterator built with data from probDescDB.

10.30.3 Member Function Documentation

10.30.3.1 `void resolve_samples_symbols () [private]`

convenience function for resolving number of samples and number of symbols from input.

This function must define a combination of samples and symbols that is acceptable for a particular sampling algorithm. Users provide requests for these quantities, but this function must enforce any restrictions imposed by the sampling algorithms.

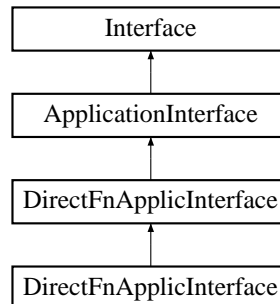
The documentation for this class was generated from the following files:

- [DDACEDesignCompExp.H](#)
- [DDACEDesignCompExp.C](#)

10.31 DirectFnApplicInterface Class Reference

Derived application interface class which spawns simulation codes and testers using direct procedure calls.

Inheritance diagram for DirectFnApplicInterface::



Public Member Functions

- **DirectFnApplicInterface** (const **ProblemDescDB** &problem_db)
constructor
- **~DirectFnApplicInterface** ()
destructor
- void **derived_map** (const **Variables** &vars, const **ActiveSet** &set, **Response** &response, int fn_eval_id)
Called by map() and other functions to execute the simulation in synchronous mode. The portion of performing an evaluation that is specific to a derived class.
- void **derived_map_asynch** (const **ParamResponsePair** &pair)
Called by map() and other functions to execute the simulation in asynchronous mode. The portion of performing an asynchronous evaluation that is specific to a derived class.
- void **derived_synch** (**PRPLList** &prp_list)
For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version waits for at least one completion.
- void **derived_synch_nowait** (**PRPLList** &prp_list)
For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version is nonblocking and will return without any completions if none are immediately available.
- int **derived_synchronous_local_analysis** (const int &analysis_id)
- const **StringArray** & **analysis_drivers** () const

retrieve the analysis drivers specification for application interfaces

Protected Member Functions

- virtual int `derived_map_if` (const `String` &if_name)
execute the input filter portion of a direct evaluation invocation
- virtual int `derived_map_ac` (const `String` &ac_name)
execute an analysis code portion of a direct evaluation invocation
- virtual int `derived_map_of` (const `String` &of_name)
execute the output filter portion of a direct evaluation invocation
- void `set_local_data` (const `Variables` &vars, const `ActiveSet` &set, const `Response` &response)
convenience function for local test simulators which sets variable attributes and zeros response data
- void `overlay_response` (`Response` &response)
convenience function for local test simulators which overlays response contributions from multiple analyses using `MPI_Reduce`

Protected Attributes

- `String` `iFilterName`
name of the direct function input filter
- `String` `oFilterName`
name of the direct function output filter
- bool `gradFlag`
signals use of `fnGrads` in direct simulator functions
- bool `hessFlag`
signals use of `fnHessians` in direct simulator functions
- size_t `numFns`
number of functions in `fnVals`
- size_t `numVars`
total number of continuous and discrete variables
- size_t `numACV`
total number of continuous variables

- `size_t numADV`
total number of discrete variables
- `size_t numDerivVars`
number of active derivative variables
- `RealVector xC`
continuous variables used within direct simulator fns
- `IntVector xD`
discrete variables used within direct simulator fns
- `StringArray xCLabels`
continuous variable labels
- `StringArray xDLabels`
discrete variable labels
- `IntArray directFnASV`
class scope active set vector
- `IntArray directFnDVV`
class scope derivative variables vector
- `RealVector fnVals`
response fn values within direct simulator fns
- `RealMatrix fnGrads`
response fn gradients w/i direct simulator fns
- `RealMatrixArray fnHessians`
response fn Hessians w/i direct simulator fns
- `StringArray fnLabels`
response function labels
- `StringArray analysisDrivers`
the set of analyses within each function evaluation (from the analysis_drivers interface specification)
- `size_t analysisDriverIndex`
the index of the active analysis driver within analysisDrivers
- `String2DArray analysisComponents`
the set of optional analysis components used by the analysis drivers (from the analysis_components interface specification)

- engine * [matlabEngine](#)
pointer to the MATLAB engine used for direct evaluations

Private Member Functions

- int [cantilever](#) ()
the cantilever UQ/OUU test function
- int [cyl_head](#) ()
the cylinder head constrained optimization test fn
- int [rosenbrock](#) ()
the rosenbrock optimization and least squares test fn
- int [text_book](#) ()
the text_book constrained optimization test function
- int [text_book1](#) ()
portion of [text_book\(\)](#) evaluating the objective fn
- int [text_book2](#) ()
portion of [text_book\(\)](#) evaluating constraint 1
- int [text_book3](#) ()
portion of [text_book\(\)](#) evaluating constraint 2
- int [text_book_ouu](#) ()
the text_book_ouu OUU test function
- int [log_ratio](#) ()
the log_ratio UQ test function
- int [short_column](#) ()
the short_column UQ/OUU test function
- int [salinas](#) ()
direct interface to the SALINAS structural dynamics code
- int [mc_api_run](#) ()
direct interface to ModelCenter via API, HKIM 4/3/03
- int [matlab_engine_run](#) ()
direct interface to Matlab via API, BMA 11/28/05

10.31.1 Detailed Description

Derived application interface class which spawns simulation codes and testers using direct procedure calls.

[DirectFnApplicInterface](#) uses a few linkable simulation codes and several internal member functions to perform parameter to response mappings.

10.31.2 Member Function Documentation

10.31.2.1 `int derived_synchronous_local_analysis (const int & analysis_id)` [inline, virtual]

This code provides the derived function used by [ApplicationInterface::serve_analyses_synch\(\)](#).

Reimplemented from [ApplicationInterface](#).

10.31.2.2 `int derived_map_ac (const String & ac_name)` [protected, virtual]

execute an analysis code portion of a direct evaluation invocation

When a direct analysis/filter is a member function, the (vars,set,response) data does not need to be passed through the API. If, however, non-member analysis/filter functions are added, then pass (vars,set,response) through to the non-member fns:

```
// API declaration
int sim(const Variables& vars, const ActiveSet& set, Response& response);
// use of API within derived_map_ac()
if (ac_name == "sim")
    fail_code = sim(directFnVars, directFnActSet, directFnResponse);
```

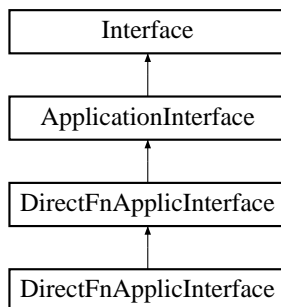
The documentation for this class was generated from the following files:

- [DirectFnApplicInterface.H](#)
- [DirectFnApplicInterface.C](#)

10.32 DirectFnApplicInterface Class Reference

Sample derived interface class for testing plug-ins using [assign_rep\(\)](#).

Inheritance diagram for DirectFnApplicInterface::



Public Member Functions

- [DirectFnApplicInterface](#) (const [Dakota::ProblemDescDB](#) &problem_db)
constructor
- [~DirectFnApplicInterface](#) ()
destructor

Protected Member Functions

- int [derived_map_ac](#) (const [Dakota::String](#) &ac_name)
execute an analysis code portion of a direct evaluation invocation

10.32.1 Detailed Description

Sample derived interface class for testing plug-ins using [assign_rep\(\)](#).

The plug-in [DirectFnApplicInterface](#) resides in namespace [SIM](#) and uses a copy of [rosenbrock\(\)](#) to perform parameter to response mappings. It may be activated by uncommenting the `LIBRARY_MODE_DEBUG` define in [main.C](#) (which activates the plug-in code block within that file) and uncommenting the `PLUGIN_S/PLUGIN_O` declarations at the top of the Dakota/src Makefile (which add this class to the build). Test input files should then use an `analysis_driver` of "plugin_rosenbrock".

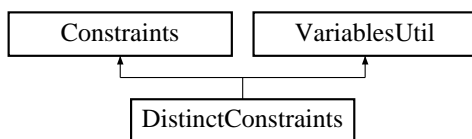
The documentation for this class was generated from the following files:

- [PluginDirectFnApplicInterface.H](#)
- [PluginDirectFnApplicInterface.C](#)

10.33 DistinctConstraints Class Reference

Derived class within the [Constraints](#) hierarchy which employs the default data view (no variable or domain type array merging).

Inheritance diagram for DistinctConstraints::



Public Member Functions

- [DistinctConstraints](#) ()
default constructor
- [DistinctConstraints](#) (const [ProblemDescDB](#) &problem_db, const pair< short, short > &view)
standard constructor
- [~DistinctConstraints](#) ()
destructor
- const [RealVector](#) & [continuous_lower_bounds](#) () const
return the active continuous variable lower bounds
- void [continuous_lower_bounds](#) (const [RealVector](#) &c_l_bnds)
set the active continuous variable lower bounds
- const [RealVector](#) & [continuous_upper_bounds](#) () const
return the active continuous variable upper bounds
- void [continuous_upper_bounds](#) (const [RealVector](#) &c_u_bnds)
set the active continuous variable upper bounds
- const [IntVector](#) & [discrete_lower_bounds](#) () const
return the active discrete variable lower bounds
- void [discrete_lower_bounds](#) (const [IntVector](#) &d_l_bnds)
set the active discrete variable lower bounds
- const [IntVector](#) & [discrete_upper_bounds](#) () const

return the active discrete variable upper bounds

- void `discrete_upper_bounds` (const `IntVector` &d_u_bnds)
set the active discrete variable upper bounds
- const `RealVector` & `inactive_continuous_lower_bounds` () const
return the inactive continuous lower bounds
- void `inactive_continuous_lower_bounds` (const `RealVector` &i_c_l_bnds)
set the inactive continuous lower bounds
- const `RealVector` & `inactive_continuous_upper_bounds` () const
return the inactive continuous upper bounds
- void `inactive_continuous_upper_bounds` (const `RealVector` &i_c_u_bnds)
set the inactive continuous upper bounds
- const `IntVector` & `inactive_discrete_lower_bounds` () const
return the inactive discrete lower bounds
- void `inactive_discrete_lower_bounds` (const `IntVector` &i_d_l_bnds)
set the inactive discrete lower bounds
- const `IntVector` & `inactive_discrete_upper_bounds` () const
return the inactive discrete upper bounds
- void `inactive_discrete_upper_bounds` (const `IntVector` &i_d_u_bnds)
set the inactive discrete upper bounds
- `RealVector` `all_continuous_lower_bounds` () const
returns a single array with all continuous lower bounds
- `RealVector` `all_continuous_upper_bounds` () const
returns a single array with all continuous upper bounds
- `IntVector` `all_discrete_lower_bounds` () const
returns a single array with all discrete lower bounds
- `IntVector` `all_discrete_upper_bounds` () const
returns a single array with all discrete upper bounds
- void `write` (ostream &s) const
write a variable constraints object to an ostream
- void `read` (istream &s)
read a variable constraints object from an istream

Private Attributes

- [RealVector continuousDesignLowerBnds](#)
the continuous design lower bounds array
- [RealVector continuousDesignUpperBnds](#)
the continuous design upper bounds array
- [IntVector discreteDesignLowerBnds](#)
the discrete design lower bounds array
- [IntVector discreteDesignUpperBnds](#)
the discrete design upper bounds array
- [RealVector uncertainLowerBnds](#)
the uncertain distribution lower bounds array
- [RealVector uncertainUpperBnds](#)
the uncertain distribution upper bounds array
- [RealVector continuousStateLowerBnds](#)
the continuous state lower bounds array
- [RealVector continuousStateUpperBnds](#)
the continuous state upper bounds array
- [IntVector discreteStateLowerBnds](#)
the discrete state lower bounds array
- [IntVector discreteStateUpperBnds](#)
the discrete state upper bounds array

10.33.1 Detailed Description

Derived class within the [Constraints](#) hierarchy which employs the default data view (no variable or domain type array merging).

Derived variable constraints classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [DistinctConstraints](#) derived class separates the design, uncertain, and state variable types as well as the continuous and discrete domain types. The result is separate lower and upper bounds arrays for continuous design, discrete design, uncertain, continuous state, and discrete state variables. This is the default approach, so all iterators and strategies not specifically utilizing the All or Merged views use this approach (see `Variables::get_variables(problem_db)` for variables type selection; variables type is passed to the [Constraints](#) constructor in [Model](#)).

10.33.2 Constructor & Destructor Documentation

10.33.2.1 `DistinctConstraints` (`const ProblemDescDB & problem_db, const pair< short, short > & view`)

standard constructor

In this class, the distinct approach (design, uncertain, and state types are distinct) is used. Most iterators/strategies use this approach, which is the default in `Constraints::get_constraints()`. Extract distinct lower and upper bounds (`VariablesUtil` is not used).

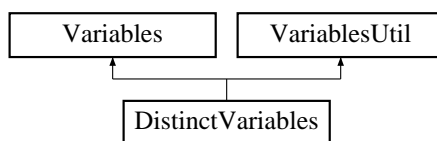
The documentation for this class was generated from the following files:

- `DistinctConstraints.H`
- `DistinctConstraints.C`

10.34 DistinctVariables Class Reference

Derived class within the [Variables](#) hierarchy which employs the default data view (no variable or domain type array merging).

Inheritance diagram for DistinctVariables::



Public Member Functions

- [DistinctVariables](#) ()
default constructor
- [DistinctVariables](#) (const [ProblemDescDB](#) &problem_db, const pair< short, short > &view)
standard constructor
- [~DistinctVariables](#) ()
destructor
- size_t tv () const
Returns total number of vars.
- const [RealVector](#) & [continuous_variables](#) () const
return the active continuous variables
- void [continuous_variables](#) (const [RealVector](#) &c_vars)
set the active continuous variables
- const [IntVector](#) & [discrete_variables](#) () const
return the active discrete variables
- void [discrete_variables](#) (const [IntVector](#) &d_vars)
set the active discrete variables
- const [StringArray](#) & [continuous_variable_labels](#) () const
return the active continuous variable labels
- void [continuous_variable_labels](#) (const [StringArray](#) &c_v_labels)

set the active continuous variable labels

- const [StringArray](#) & [discrete_variable_labels](#) () const
return the active discrete variable labels
- void [discrete_variable_labels](#) (const [StringArray](#) &d_v_labels)
set the active discrete variable labels
- const [RealVector](#) & [inactive_continuous_variables](#) () const
return the inactive continuous variables
- void [inactive_continuous_variables](#) (const [RealVector](#) &i_c_vars)
set the inactive continuous variables
- const [IntVector](#) & [inactive_discrete_variables](#) () const
return the inactive discrete variables
- void [inactive_discrete_variables](#) (const [IntVector](#) &i_d_vars)
set the inactive discrete variables
- const [StringArray](#) & [inactive_continuous_variable_labels](#) () const
return the inactive continuous variable labels
- void [inactive_continuous_variable_labels](#) (const [StringArray](#) &i_c_v_labels)
set the inactive continuous variable labels
- const [StringArray](#) & [inactive_discrete_variable_labels](#) () const
return the inactive discrete variable labels
- void [inactive_discrete_variable_labels](#) (const [StringArray](#) &i_d_v_labels)
set the inactive discrete variable labels
- size_t [acv](#) () const
returns total number of continuous vars
- size_t [adv](#) () const
returns total number of discrete vars
- [RealVector](#) [all_continuous_variables](#) () const
returns a single array with all continuous variables
- void [all_continuous_variables](#) (const [RealVector](#) &a_c_vars)
sets all continuous variables using a single array
- [IntVector](#) [all_discrete_variables](#) () const
returns a single array with all discrete variables

- void `all_discrete_variables` (const `IntVector` &a_d_vars)
sets all discrete variables using a single array
- `StringArray all_continuous_variable_labels` () const
returns a single array with all continuous variable labels
- `StringArray all_discrete_variable_labels` () const
returns a single array with all discrete variable labels
- `StringArray all_variable_labels` () const
returns a single array with all variable labels
- void `read` (istream &s)
read a variables object from an istream
- void `write` (ostream &s) const
write a variables object to an ostream
- void `write_aprepro` (ostream &s) const
write a variables object to an ostream in aprepro format
- void `read_annotated` (istream &s)
read a variables object in annotated format from an istream
- void `write_annotated` (ostream &s) const
write a variables object in annotated format to an ostream
- void `write_tabular` (ostream &s) const
write a variables object in tabular format to an ostream
- void `read` (`BiStream` &s)
read a variables object from the binary restart stream
- void `write` (`BoStream` &s) const
write a variables object to the binary restart stream
- void `read` (`MPIUnpackBuffer` &s)
read a variables object from a packed MPI buffer
- void `write` (`MPIPackBuffer` &s) const
write a variables object to a packed MPI buffer

Private Member Functions

- void `copy_rep` (const `Variables` *vars_rep)
Used by `copy()` to copy the contents of a letter class.

Private Attributes

- `RealVector` `continuousDesignVars`
the continuous design variables array
- `IntVector` `discreteDesignVars`
the discrete design variables array
- `RealVector` `uncertainVars`
the uncertain variables array
- `RealVector` `continuousStateVars`
the continuous state variables array
- `IntVector` `discreteStateVars`
the discrete state variables array
- `StringArray` `continuousDesignLabels`
the continuous design variables label array
- `StringArray` `discreteDesignLabels`
the discrete design variables label array
- `StringArray` `uncertainLabels`
the uncertain variables label array
- `StringArray` `continuousStateLabels`
the continuous state variables label array
- `StringArray` `discreteStateLabels`
the discrete state variables label array

Friends

- bool `operator==` (const `DistinctVariables` &vars1, const `DistinctVariables` &vars2)
equality operator

10.34.1 Detailed Description

Derived class within the [Variables](#) hierarchy which employs the default data view (no variable or domain type array merging).

Derived variables classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [DistinctVariables](#) derived class separates the design, uncertain, and state variable types as well as the continuous and discrete domain types. The result is separate arrays for continuous design, discrete design, uncertain, continuous state, and discrete state variables. This is the default approach, so all iterators and strategies not specifically utilizing the All or Merged views use this approach (see `Variables::get_variables(problem_db)`).

10.34.2 Constructor & Destructor Documentation

10.34.2.1 [DistinctVariables](#) (`const ProblemDescDB & problem_db, const pair< short, short > & view`)

standard constructor

In this class, the distinct approach is used (design, uncertain, and state variable types and continuous and discrete domain types are distinct). Most iterators/strategies use this approach. Extract distinct variable types and labels ([VariablesUtil](#) is not used).

10.34.3 Friends And Related Function Documentation

10.34.3.1 `bool operator==(const DistinctVariables & vars1, const DistinctVariables & vars2)` [friend]

equality operator

Checks each array using `operator==` from [data_types.C](#). Labels are ignored.

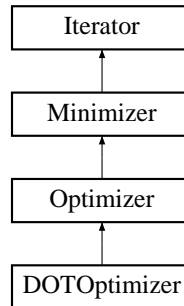
The documentation for this class was generated from the following files:

- [DistinctVariables.H](#)
- [DistinctVariables.C](#)

10.35 DOTOptimizer Class Reference

Wrapper class for the DOT optimization library.

Inheritance diagram for DOTOptimizer::



Public Member Functions

- [DOTOptimizer \(Model &model\)](#)
constructor
- [~DOTOptimizer \(\)](#)
destructor
- void [find_optimum \(\)](#)
Used within the optimizer branch for computing the optimal solution. Redefines the run_iterator virtual function for the optimizer branch.

Protected Member Functions

- virtual void [derived_pre_run \(\)](#)
performs run-time set up
- virtual void [derived_post_run \(\)](#)
performs final solution processing

Private Member Functions

- void [allocate_workspace \(\)](#)
Allocates workspace for the optimizer.

- void `allocate_constraints ()`
Allocates constraint mappings.

Private Attributes

- int `dotInfo`
INFO from DOT manual.
- int `dotFDSinfo`
internal DOT parameter NGOTOZ
- int `dotMethod`
METHOD from DOT manual.
- int `printControl`
IPRINT from DOT manual (controls output verbosity).
- int `optimizationType`
MINMAX from DOT manual (minimize or maximize).
- `RealArray realCntlParmArray`
RPRM from DOT manual.
- `IntArray intCntlParmArray`
IPRM from DOT manual.
- `RealVector designVars`
array of design variable values passed to DOT
- `Real objFnValue`
value of the objective function passed to DOT
- `RealVector constraintValues`
array of nonlinear constraint values passed to DOT
- int `realWorkSpaceSize`
size of realWorkSpace
- int `intWorkSpaceSize`
size of intWorkSpace
- `RealArray realWorkSpace`
real work space for DOT

- [IntArray intWorkSpace](#)
int work space for DOT
- [SizetList constraintMappingIndices](#)
a list of indices for referencing the corresponding [Response](#) constraints used in computing the DOT constraints.
- [RealList constraintMappingMultipliers](#)
a list of multipliers for mapping the [Response](#) constraints to the DOT constraints.
- [RealList constraintMappingOffsets](#)
a list of offsets for mapping the [Response](#) constraints to the DOT constraints.

10.35.1 Detailed Description

Wrapper class for the DOT optimization library.

The [DOTOptimizer](#) class provides a wrapper for DOT, a commercial Fortran 77 optimization library from Vanderplaats Research and Development. It uses a reverse communication mode, which avoids the static member function issues that arise with function pointer designs (see [NPSOLOptimizer](#) and [SNLLOptimizer](#)).

The user input mappings are as follows: `max_iterations` is mapped into DOT's `ITMAX` parameter within its `Iprm` array, `max_function_evaluations` is implemented directly in the `find_optimum()` loop since there is no DOT parameter equivalent, `convergence_tolerance` is mapped into DOT's `DELOBJ` parameter (the relative convergence tolerance) within its `Rprm` array, `output_verbosity` is mapped into DOT's `Iprint` parameter within its function call parameter list (verbose: `Iprint = 7`; quiet: `Iprint = 3`), and `optimization_type` is mapped into DOT's `MINMAX` parameter within its function call parameter list. Refer to [Vanderplaats Research and Development, 1995] for information on `Iprm`, `Rprm`, and the DOT function call parameter list.

10.35.2 Member Data Documentation

10.35.2.1 `int dotInfo` [private]

INFO from DOT manual.

Information requested by DOT: 0=optimization complete, 1=get values, 2=get gradients

10.35.2.2 `int dotFDSinfo` [private]

internal DOT parameter `NGOTOZ`

the DOT parameter list has been modified to pass `NGOTOZ`, which signals whether DOT is finite-differencing (nonzero value) or performing the line search (zero value).

10.35.2.3 int dotMethod [private]

METHOD from DOT manual.

For nonlinear constraints: 0/1 = dot_mmfd, 2 = dot_slp, 3 = dot_sqp. For unconstrained: 0/1 = dot_bfgs, 2 = dot_frcg.

10.35.2.4 int printControl [private]

IPRINT from DOT manual (controls output verbosity).

Values range from 0 (least output) to 7 (most output).

10.35.2.5 int optimizationType [private]

MINMAX from DOT manual (minimize or maximize).

Values of 0 or -1 (minimize) or 1 (maximize).

10.35.2.6 RealArray realCntlParmArray [private]

RPRM from DOT manual.

Array of real control parameters.

10.35.2.7 IntArray intCntlParmArray [private]

IPRM from DOT manual.

Array of integer control parameters.

10.35.2.8 RealVector constraintValues [private]

array of nonlinear constraint values passed to DOT

This array must be of nonzero length and must contain only one-sided inequality constraints which are ≤ 0 (which requires a transformation from 2-sided inequalities and equalities).

10.35.2.9 SizerList constraintMappingIndices [private]

a list of indices for referencing the corresponding [Response](#) constraints used in computing the DOT constraints.

The length of the list corresponds to the number of DOT constraints, and each entry in the list points to the corresponding DAKOTA constraint.

10.35.2.10 RealList constraintMappingMultipliers [private]

a list of multipliers for mapping the [Response](#) constraints to the DOT constraints.

The length of the list corresponds to the number of DOT constraints, and each entry in the list contains a multiplier for the DAKOTA constraint identified with `constraintMappingIndices`. These multipliers are currently +1 or -1.

10.35.2.11 `RealList constraintMappingOffsets` [private]

a list of offsets for mapping the `Response` constraints to the DOT constraints.

The length of the list corresponds to the number of DOT constraints, and each entry in the list contains an offset for the DAKOTA constraint identified with `constraintMappingIndices`. These offsets involve inequality bounds or equality targets, since DOT assumes constraint allowables = 0.

The documentation for this class was generated from the following files:

- `DOTOptimizer.H`
- `DOTOptimizer.C`

10.36 ErrorTable Struct Reference

Data structure to hold errors.

Public Attributes

- [CtelRegexp::RStatus rc](#)
Enumerated type to hold status codes.
- `const char * msg`
Holds character string error message.

10.36.1 Detailed Description

Data structure to hold errors.

This module implements a C++ wrapper for Regular Expressions based on the public domain engine for regular expressions released by: Copyright (c) 1986 by University of Toronto. Written by Henry Spencer. Not derived from licensed software.

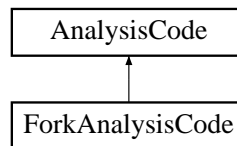
The documentation for this struct was generated from the following file:

- CtelRegExp.C

10.37 ForkAnalysisCode Class Reference

Derived class in the [AnalysisCode](#) class hierarchy which spawns simulations using forks.

Inheritance diagram for ForkAnalysisCode::



Public Member Functions

- [ForkAnalysisCode](#) (const [ProblemDescDB](#) &problem_db)
constructor
- [~ForkAnalysisCode](#) ()
destructor
- pid_t [fork_program](#) (const bool block_flag)
spawn a child process using fork()/vfork()/execvp() and wait for completion using waitpid() if block_flag is true
- void [check_status](#) (const int status)
check the exit status of a forked process and abort if an error code was returned
- void [ifilter_argument_list](#) ()
set argList for execution of the input filter
- void [ofilter_argument_list](#) ()
set argList for execution of the output filter
- void [driver_argument_list](#) (const int analysis_id)
set argList for execution of the specified analysis driver

Private Attributes

- [StringArray](#) argList
*an array of strings for use with execvp(const char *, char * const *). These are converted to an array of const char*'s in fork_program().*

10.37.1 Detailed Description

Derived class in the [AnalysisCode](#) class hierarchy which spawns simulations using forks.

[ForkAnalysisCode](#) creates a copy of the parent DAKOTA process using `fork()/vfork()` and then replaces the copy with a simulation process using `execvp()`. The parent process can then use `waitpid()` to wait on completion of the simulation process.

10.37.2 Member Function Documentation

10.37.2.1 `void check_status (const int status)`

check the exit status of a forked process and abort if an error code was returned

Check to see if the process terminated abnormally (`WIFEXITED(status)==0`) or if either `execvp` or the application returned a status code of -1 (`WIFEXITED(status)!=0 && (signed char)WEXITSTATUS(status)==-1`). If one of these conditions is detected, output a failure message and abort. Note: the application code should not return a status code of -1 unless an immediate abort of dakota is wanted. If for instance, failure capturing is to be used, the application code should write the word "FAIL" to the appropriate results file and return a status code of 0 through `exit()`.

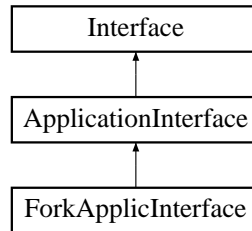
The documentation for this class was generated from the following files:

- `ForkAnalysisCode.H`
- `ForkAnalysisCode.C`

10.38 ForkApplicInterface Class Reference

Derived application interface class which spawns simulation codes using forks.

Inheritance diagram for ForkApplicInterface::



Public Member Functions

- [ForkApplicInterface](#) (const [ProblemDescDB](#) &problem_db)
constructor
- [~ForkApplicInterface](#) ()
destructor
- void [derived_map](#) (const [Variables](#) &vars, const [ActiveSet](#) &set, [Response](#) &response, int fn_eval_id)
Called by [map\(\)](#) and other functions to execute the simulation in synchronous mode. The portion of performing an evaluation that is specific to a derived class.
- void [derived_map_async](#) (const [ParamResponsePair](#) &pair)
Called by [map\(\)](#) and other functions to execute the simulation in asynchronous mode. The portion of performing an asynchronous evaluation that is specific to a derived class.
- void [derived_synch](#) ([PRPLList](#) &prp_list)
For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version waits for at least one completion.
- void [derived_synch_nowait](#) ([PRPLList](#) &prp_list)
For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version is nonblocking and will return without any completions if none are immediately available.
- int [derived_synchronous_local_analysis](#) (const int &analysis_id)
- const [StringArray](#) & [analysis_drivers](#) () const
retrieve the analysis drivers specification for application interfaces

Private Member Functions

- void [derived_synch_kernel](#) ([PRPList](#) &prp_list, const [pid_t](#) pid)
Convenience function for common code between [derived_synch\(\)](#) & [derived_synch_nowait\(\)](#).
- [pid_t](#) [fork_application](#) (const bool block_flag)
perform the complete function evaluation by managing the input filter, analysis programs, and output filter
- void [asynchronous_local_analyses](#) (const int &start, const int &end, const int &step)
execute analyses asynchronously on the local processor
- void [synchronous_local_analyses](#) (const int &start, const int &end, const int &step)
execute analyses synchronously on the local processor
- void [serve_analyses_asynch](#) ()
serve the analysis scheduler and execute analysis jobs asynchronously

Private Attributes

- [ForkAnalysisCode](#) [forkSimulator](#)
[ForkAnalysisCode](#) provides convenience functions for forking individual programs and checking fork exit status.
- `std::map< pid_t, int >` [processIdMap](#)
map of fork process id's to function evaluation id's for asynchronous evaluations

10.38.1 Detailed Description

Derived application interface class which spawns simulation codes using forks.

[ForkApplicInterface](#) uses a [ForkAnalysisCode](#) object for performing simulation invocations.

10.38.2 Member Function Documentation

10.38.2.1 `int derived_synchronous_local_analysis (const int & analysis_id) [inline, virtual]`

This code provides the derived function used by [ApplicationInterface::serve_analyses_synch\(\)](#) as well as a convenience function for [ForkApplicInterface::synchronous_local_analyses\(\)](#) below.

Reimplemented from [ApplicationInterface](#).

10.38.2.2 `pid_t fork_application (const bool block_flag)` [private]

perform the complete function evaluation by managing the input filter, analysis programs, and output filter

Manage the input filter, 1 or more analysis programs, and the output filter in blocking or nonblocking mode as governed by `block_flag`. In the case of a single analysis and no filters, a single fork is performed, while in other cases, an initial fork is reforked multiple times. Called from `derived_map()` with `block_flag == BLOCK` and from `derived_map_asynch()` with `block_flag == FALL_THROUGH`. Uses `ForkAnalysisCode::fork_program()` to spawn individual program components within the function evaluation.

10.38.2.3 `void asynchronous_local_analyses (const int & start, const int & end, const int & step)`
[private]

execute analyses asynchronously on the local processor

Schedule analyses asynchronously on the local processor using a self-scheduling approach (start to end in step increments). Concurrency is limited by `asynchLocalAnalysisConcurrency`. Modeled after `ApplicationInterface::asynchronous_local_evaluations()`. NOTE: This function should be elevated to `ApplicationInterface` if and when another derived interface class supports asynchronous local analyses.

10.38.2.4 `void synchronous_local_analyses (const int & start, const int & end, const int & step)`
[inline, private]

execute analyses synchronously on the local processor

Execute analyses synchronously in succession on the local processor (start to end in step increments). Modeled after `ApplicationInterface::synchronous_local_evaluations()`.

10.38.2.5 `void serve_analyses_asynch ()` [private]

serve the analysis scheduler and execute analysis jobs asynchronously

This code runs multiple `asynch` analyses on each server. It is modeled after `ApplicationInterface::serve_evaluations_asynch()`. NOTE: This fn should be elevated to `ApplicationInterface` if and when another derived interface class supports hybrid analysis parallelism.

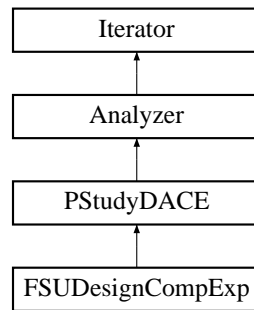
The documentation for this class was generated from the following files:

- ForkApplicInterface.H
- ForkApplicInterface.C

10.39 FSUDesignCompExp Class Reference

Wrapper class for the FSUDace QMC/CVT library.

Inheritance diagram for FSUDesignCompExp::



Public Member Functions

- [FSUDesignCompExp \(Model &model\)](#)
primary constructor for building a standard DACE iterator
- [~FSUDesignCompExp \(\)](#)
destructor
- void [extract_trends \(\)](#)
Redefines the run_iterator virtual function for the PStudy/DACE branch.
- void [sampling_reset](#) (int min_samples, bool all_data_flag, bool stats_flag)
reset sampling iterator
- const [String & sampling_scheme \(\)](#) const
return sampling name
- void [vary_pattern](#) (bool pattern_flag)
sets varyPattern in derived classes that support it
- void [get_parameter_sets \(\)](#)
*Returns one block of samples (ndim * num_samples).*

Private Member Functions

- void [enforce_input_rules\(\)](#)
enforce sanity checks/modifications for the user input specification

Private Attributes

- int [samplesSpec](#)
user specification of number of samples
- int [numSamples](#)
number of samples to be evaluated
- bool [allDataFlag](#)
flag which triggers the update of allVars/allResponses for use by [Iterator::all_variables\(\)](#) and [Iterator::all_responses\(\)](#)
- size_t [numDACERuns](#)
counter for number of [run\(\)](#) executions for this object
- bool [latinizeFlag](#)
flag which specifies latinization of QMC or CVT sample sets
- bool [volQualityFlag](#)
flag which specifies evaluating the volumetric quality measures
- bool [varBasedDecompFlag](#)
flag which specifies calculating variance based decomposition sensitivity analysis metrics
- [IntVector](#) [sequenceStart](#)
Integer vector defining a starting index into the sequence for random variable sampled. Default is 0 0 0 (e.g. for three random variables).
- [IntVector](#) [sequenceLeap](#)
Integer vector defining the leap number for each sequence being generated. Default is 1 1 1 (e.g. for three random vars.).
- [IntVector](#) [primeBase](#)
Integer vector defining the prime base for each sequence being generated. Default is 2 3 5 (e.g., for three random vars.).
- int [originalSeed](#)
the user seed specification for the random number generator (allows repeatable results)
- int [randomSeed](#)

current seed for the random number generator

- bool `varyPattern`
flag for continuing the random number or QMC sequence from a previous `run()` execution (e.g., for surrogate-based optimization) so that multiple executions are repeatable but not identical.
- int `numCVTTrials`
specifies the number of sample points taken at internal CVT iteration
- int `trialType`
Trial type in CVT. Specifies where the points are placed for consideration relative to the centroids. Choices are grid (2), halton (1), uniform (0), or random (-1). Default is random.

10.39.1 Detailed Description

Wrapper class for the FSUDace QMC/CVT library.

The `FSUDesignCompExp` class provides a wrapper for FSUDace, a C++ design of experiments library from Florida State University. This class uses quasi Monte Carlo (QMC) and Centroidal Voronoi Tessellation (CVT) methods to uniformly sample the parameter space spanned by the active bounds of the current `Model`. It returns all generated samples and their corresponding responses as well as the best sample found.

10.39.2 Constructor & Destructor Documentation

10.39.2.1 `FSUDesignCompExp` (`Model` & `model`)

primary constructor for building a standard DACE iterator

This constructor is called for a standard iterator built with data from `probDescDB`.

10.39.3 Member Function Documentation

10.39.3.1 `void enforce_input_rules () [private]`

enforce sanity checks/modifications for the user input specification

Users may input a variety of quantities, but this function must enforce any restrictions imposed by the sampling algorithms.

The documentation for this class was generated from the following files:

- `FSUDesignCompExp.H`

- FSUDesignCompExp.C

10.40 FunctionCompare Class Template Reference

Public Member Functions

- [FunctionCompare](#) (bool(*func)(const T &, void *), void *v)
Constructor that defines the pointer to function and search value.
- bool [operator\(\)](#) (T t) const
The operator() must be defined. Calls the function test_fn.

Private Attributes

- bool(* [test_fn](#))(const T &, void *)
Pointer to test function.
- void * [search_val](#)
Holds the value to search for.

10.40.1 Detailed Description

template<class T> class Dakota::FunctionCompare< T >

Internal functor to mimic the RW find and index functions using the STL find_if() method. The class holds a pointer to the test function and the search value.

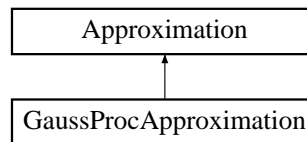
The documentation for this class was generated from the following file:

- DakotaList.H

10.41 GaussProcApproximation Class Reference

Derived approximation class for Gaussian Process implementation.

Inheritance diagram for GaussProcApproximation::



Public Member Functions

- [GaussProcApproximation \(\)](#)
default constructor
- [GaussProcApproximation \(ProblemDescDB &problem_db, const size_t &num_acv\)](#)
standard constructor
- [~GaussProcApproximation \(\)](#)
destructor

Protected Member Functions

- `int num_coefficients () const`
return the minimum number of samples required to build the derived class approximation type in numVars dimensions
- `int num_constraints () const`
return the number of constraints to be enforced via anchorPoint
- `void find_coefficients ()`
find the covariance parameters governing the Gaussian process response
- `const Real & get_value (const RealVector &x)`
retrieve the function value for a given parameter set x

Private Member Functions

- void `GPmodel_build` ()
Function to compute hyperparameters governing the GP.
- Real `GPmodel_apply` (const `RealVector` &new_x)
Function returns a response value using the GP surface.
- void `predict` ()
Calculates the predicted new response value for x in normalized space.
- void `normalize` ()
Normalizes the initial inputs upon which the GP surface is based.
- void `unnormalize` ()
Takes the value from the GP normalized prediction and unnormalizes it.
- Real `calc_nll` ()
calculates the negative log likelihood function (based on covariance matrix)
- void `covmatrix` ()
calculates the covariance matrix for a given set of input points
- void `covvector` ()
calculates the covariance vector between a new point x and the set of inputs upon which the GP is based
- void `optimize_nll` ()
function which sets up and performs the optimization of the negative log likelihood to determine the optimal values of the covariance oaraneters

Static Private Member Functions

- static void `negloglik` (int mode, int n, const `NEWMAT::ColumnVector` &X, `NEWMAT::Real` &fx, `NEWMAT::ColumnVector` &grad_x, int &result_mode)
static function used by OPT++ as the objective function to optimize the hyperparameters in the covariance of the GP by minimizing the negative log likelihood
- static void `constraint_eval` (int mode, int n, const `NEWMAT::ColumnVector` &X, `NEWMAT::ColumnVector` &g, `NEWMAT::Matrix` &gradC, int &result_mode)
static function used by OPT++ as the constraint function in the optimization of the negative log likelihood. Currently this function is empty: it is an unconstrained optimization.

Private Attributes

- Epetra_SerialDenseMatrix [x_matrix](#)
A 2-D array (num sample sites = rows, num vars = columns) used to create the Gaussian process.
- Epetra_SerialDenseMatrix [f_of_x_array](#)
An array of response values; one response value per sample site.
- Epetra_SerialDenseMatrix [initX](#)
Initial set of sample values of X upon which the GP is based.
- Epetra_SerialDenseMatrix [newX](#)
New value of x at which one wants a point prediction. This is currently a single point, but it may be a vector of X values, where each X can be multi-dimensional.
- Epetra_SerialDenseMatrix [outY](#)
output Y corresponding to initX
- Epetra_SerialDenseMatrix [covmatrixX](#)
The covariance matrix where each element (i,j) is the covariance between points Xi and Xj in the initial set of samples.
- Epetra_SerialDenseMatrix [covvectorX](#)
The covariance vector where each element (j,0) is the covariance between a new point X and point Xj from the initial set of samples.
- Epetra_SerialDenseMatrix [newY](#)
The Gaussian process prediction for point newX.
- Epetra_SerialDenseMatrix [tempholder](#)
A temporary placeholder matrix to allow for Epetra matrix multiplication.
- Epetra_SerialDenseMatrix [cov_mult](#)
Another temporary placeholder matrix to allow for Epetra matrix multiplication.
- Epetra_SerialDenseVector [mean_column](#)
The mean of the input columns of initX.
- Epetra_SerialDenseVector [sqterms](#)
The standard deviation of the input columns of initX.
- Real [meanY](#)
The mean of the output Y.
- Real [stdY](#)
The standard deviation of the output Y.

- size_t [num_obs](#)

The number of observations on which the GP surface is built.

- size_t [num_vars](#)

The number of variables in each X variable (number of dimensions of the problem).

- size_t [num_new](#)

The number of new X values for which one wants a prediction. In this implementation, num_new = 1.

- Real [sige](#)

The GP error term.

- RealVector [theta](#)

*Theta is the vector of covariance parameters for the GP. We determine the values of theta by optimization. Currently, the covariance function is $\theta[0] \cdot \exp(-0.5 \cdot \text{sume}) + \text{delta} \cdot \text{pow}(\text{sige}, 2)$. *sume* is the sum squared of weighted distances; it involves a sum of $\theta[1](X_i(1) - X_j(1))^2 + \theta[2](X_i(2) - X_j(2))^2 + \dots$ where $X_i(1)$ is the first dimension value of multi-dimensional variable X_i . $\text{delta} \cdot \text{pow}(\text{sige}, 2)$ is a jitter term used to improve matrix computations. *delta* is zero for the covariance between different points and 1 for the covariance between the same point. *sige* is the underlying process error.*

- Real [nll](#)

The negative log likelihood value for a particular matrix.

- Real [approx Value](#)

A placeholder to return the Gaussian process prediction.

Static Private Attributes

- static [GaussProcApproximation * GPInstance](#)

pointer to the active object instance used within the static evaluator

10.41.1 Detailed Description

Derived approximation class for Gaussian Process implementation.

The [GaussProcApproximation](#) class provides a global approximation (surrogate) based on a Gaussian process. The Gaussian process is built after normalizing the function values, with zero mean. Opt++ is used to determine the optimal values of the covariance parameters, those which minimize the negative log likelihood function.

10.41.2 Member Function Documentation

10.41.2.1 Real GPmodel_apply (const RealVector & new_x) [private]

Function returns a response value using the GP surface.

The response value is computed at the design point specified by the RealVector function argument.

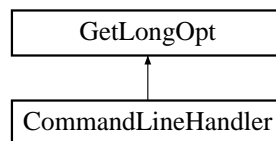
The documentation for this class was generated from the following files:

- GaussProcApproximation.H
- GaussProcApproximation.C

10.42 GetLongOpt Class Reference

[GetLongOpt](#) is a general command line utility from S. Manoharan (Advanced Computer Research Institute, Lyon, France).

Inheritance diagram for GetLongOpt::



Public Types

- enum [OptType](#) { **Valueless**, **OptionalValue**, **MandatoryValue** }
enum for different types of values associated with command line options.

Public Member Functions

- [GetLongOpt](#) (const char optmark= '-')
Constructor.
- [~GetLongOpt](#) ()
Destructor.
- int [parse](#) (int argc, char *const *argv)
parse the command line args (argc, argv).
- int [parse](#) (char *const str, char *const p)
parse a string of options (typically given from the environment).
- int [enroll](#) (const char *const opt, const [OptType](#) t, const char *const desc, const char *const val)
Add an option to the list of valid command options.
- const char * [retrieve](#) (const char *const opt) const
Retrieve value of option.
- void [usage](#) (ostream &outfile=cout) const
Print usage information to outfile.

- void [usage](#) (const char *str)
Change header of usage output to str.

Private Member Functions

- char * [basename](#) (char *const p) const
extract the base name from a string as delimited by '/'
- int [setcell](#) (Cell *c, char *valtoken, char *nexttoken, const char *p)
internal convenience function for setting Cell::value

Private Attributes

- Cell * [table](#)
option table
- const char * [ustring](#)
usage message
- char * [pname](#)
program basename
- char [optmarker](#)
option marker
- int [enroll_done](#)
finished enrolling
- Cell * [last](#)
last entry in option table

10.42.1 Detailed Description

[GetLongOpt](#) is a general command line utility from S. Manoharan (Advanced Computer Research Institute, Lyon, France).

[GetLongOpt](#) manages the definition and parsing of "long options." Command line options can be abbreviated as long as there is no ambiguity. If an option requires a value, the value should be separated from the option either by whitespace or an "=".

10.42.2 Constructor & Destructor Documentation

10.42.2.1 `GetLongOpt` (`const char optmark = '-'`)

Constructor.

Constructor for `GetLongOpt` takes an optional argument: the option marker. If unspecified, this defaults to '-', the standard (?) Unix option marker.

10.42.3 Member Function Documentation

10.42.3.1 `int parse` (`int argc`, `char *const * argv`)

parse the command line args (`argc`, `argv`).

A return value < 1 represents a parse error. Appropriate error messages are printed when errors are seen. `parse` returns the the optind (see `getopt(3)`) if parsing is successful.

10.42.3.2 `int parse` (`char *const str`, `char *const p`)

parse a string of options (typically given from the environment).

A return value < 1 represents a parse error. Appropriate error messages are printed when errors are seen. `parse` takes two strings: the first one is the string to be parsed and the second one is a string to be prefixed to the parse errors.

10.42.3.3 `int enroll` (`const char *const opt`, `const OptType t`, `const char *const desc`, `const char *const val`)

Add an option to the list of valid command options.

`enroll` adds option specifications to its internal database. The first argument is the option sting. The second is an enum saying if the option is a flag (`Valueless`), if it requires a mandatory value (`MandatoryValue`) or if it takes an optional value (`OptionalValue`). The third argument is a string giving a brief description of the option. This description will be used by `GetLongOpt::usage`. `GetLongOpt`, for usage-printing, uses `{ $val }` to represent values needed by the options. `< $val >` is a mandatory value and `{ [$val] }` is an optional value. The final argument to `enroll` is the default string to be returned if the option is not specified. For flags (options with `Valueless`), use "" (empty string, or in fact any arbitrary string) for specifying `TRUE` and `0` (null pointer) to specify `FALSE`.

10.42.3.4 `const char * retrieve` (`const char *const opt`) `const`

Retrieve value of option.

The values of the options that are enrolled in the database can be retrieved using `retrieve`. This returns a string and this string should be converted to whatever type you want. See `atoi`, `atof`, `atol`, etc. If a "parse" is not done before retrieving all you will get are the default values you gave while enrolling! Ambiguities while retrieving (may happen when options are abbreviated) are resolved by taking the matching option that was enrolled last. For example, `-{v}` will expand to `{-verify}`. If you try to retrieve something you didn't enroll, you will get a warning message.

10.42.3.5 void usage (const char * *str*) [inline]

Change header of usage output to *str*.

[GetLongOpt::usage](#) is overloaded. If passed a string "*str*", it sets the internal usage string to "*str*". Otherwise it simply prints the command usage.

The documentation for this class was generated from the following files:

- CommandLineHandler.H
- CommandLineHandler.C

10.43 Graphics Class Reference

The [Graphics](#) class provides a single interface to 2D (motif) and 3D (PLPLOT) graphics as well as tabular cataloging of data for post-processing with Matlab, Tecplot, etc.

Public Member Functions

- [Graphics](#) ()
constructor
- [~Graphics](#) ()
destructor
- void [create_plots_2d](#) (const [Variables](#) &vars, const [Response](#) &response)
creates the 2d graphics window and initializes the plots
- void [create_tabular_datastream](#) (const [Variables](#) &vars, const [Response](#) &response, const [String](#) &tabular_data_file)
opens the tabular data file stream and prints the headings
- void [add_datapoint](#) (const [Variables](#) &vars, const [Response](#) &response)
adds data to each window in the 2d graphics and adds a row to the tabular data file based on the results of a model evaluation
- void [add_datapoint](#) (int i, double x, double y)
adds data to a single window in the 2d graphics
- void [new_dataset](#) (int i)
creates a separate line graphic for subsequent data points for a single window in the 2d graphics
- void [show_data_3d](#) (const [RealVector](#) &X, const [RealVector](#) &Y, const [RealMatrix](#) &F)
generate a new 3d plot for F(X,Y)
- void [close](#) ()
close graphics windows and tabular datastream
- void [set_x_labels2d](#) (const char *x_label)
set x label for each plot equal to x_label
- void [set_y_labels2d](#) (const char *y_label)
set y label for each plot equal to y_label
- void [set_x_label2d](#) (int i, const char *x_label)

set x label for ith plot equal to x_label

- void [set_y_label2d](#) (int i, const char *y_label)
set y label for ith plot equal to y_label
- void [graphics_counter](#) (int cntr)
set graphicsCntr equal to cntr
- int [graphics_counter](#) () const
return graphicsCntr
- void [tabular_counter_label](#) (const [String](#) &label)
set tabularCntrLabel equal to label

Private Attributes

- Graphics2D * [graphics2D](#)
pointer to the 2D graphics object
- bool [win2dOn](#)
flag to indicate if 2D graphics window is active
- bool [win3dOn](#)
flag to indicate if 3D graphics window is active
- bool [tabularDataFlag](#)
flag to indicate if tabular data stream is active
- int [graphicsCntr](#)
used for x axis values in 2D graphics and for 1st column in tabular data
- [String](#) [tabularCntrLabel](#)
label for counter used in first line comment w/i the tabular data file
- ofstream [tabularDataFStream](#)
file stream for tabulation of graphics data within compute_response

10.43.1 Detailed Description

The [Graphics](#) class provides a single interface to 2D (motif) and 3D (PLPLOT) graphics as well as tabular cataloging of data for post-processing with Matlab, Tecplot, etc.

There is only one [Graphics](#) object (dakotaGraphics) and it is global (for convenient access from strategies, models, and approximations).

10.43.2 Member Function Documentation

10.43.2.1 void create_plots_2d (const Variables & vars, const Response & response)

creates the 2d graphics window and initializes the plots

Sets up a single event loop for duration of the dakotaGraphics object, continuously adding data to a single window. There is no reset. To start over with a new data set, you need a new object (delete old and instantiate new).

10.43.2.2 void create_tabular_datastream (const Variables & vars, const Response & response, const String & tabular_data_file)

opens the tabular data file stream and prints the headings

Opens the tabular data file stream and prints headings, one for each continuous and discrete variable and one for each response function, using the variable and response function labels. This tabular data is used for post-processing of DAKOTA results in Matlab, Tecplot, etc.

10.43.2.3 void add_datapoint (const Variables & vars, const Response & response)

adds data to each window in the 2d graphics and adds a row to the tabular data file based on the results of a model evaluation

Adds data to each 2d plot and each tabular data column (one for each active variable and for each response function). graphicsCntr is used for the x axis in the graphics and the first column in the tabular data.

10.43.2.4 void add_datapoint (int i, double x, double y)

adds data to a single window in the 2d graphics

Adds data to a single 2d plot. Allows complete flexibility in defining other kinds of x-y plotting in the 2D graphics.

10.43.2.5 void new_dataset (int i)

creates a separate line graphic for subsequent data points for a single window in the 2d graphics

Used for displaying multiple data sets within the same plot.

10.43.2.6 void show_data_3d (const RealVector & X, const RealVector & Y, const RealMatrix & F)

generate a new 3d plot for F(X,Y)

3D plotting clears data set and builds from scratch each time show_data3d is called. This still involves an event loop waiting for a mouse click (right button) to continue. X = 1-D x grid values only and Y = 1-D Y grid values only [X and Y are _not_ (X,Y) pairs]. F = 2-d grid of values for a single function for all (X,Y) combinations.

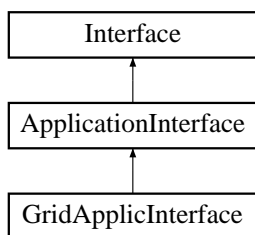
The documentation for this class was generated from the following files:

- DakotaGraphics.H
- DakotaGraphics.C

10.44 GridApplicInterface Class Reference

Derived application interface class which spawns simulation codes using grid services such as Condor or Globus.

Inheritance diagram for GridApplicInterface::



Public Member Functions

- [GridApplicInterface](#) (const [ProblemDescDB](#) &problem_db)
constructor
- [~GridApplicInterface](#) ()
destructor
- void [derived_map](#) (const [Variables](#) &vars, const [ActiveSet](#) &set, [Response](#) &response, int fn_eval_id)
Called by [map\(\)](#) and other functions to execute the simulation in synchronous mode. The portion of performing an evaluation that is specific to a derived class.
- void [derived_map_asynch](#) (const [ParamResponsePair](#) &pair)
Called by [map\(\)](#) and other functions to execute the simulation in asynchronous mode. The portion of performing an asynchronous evaluation that is specific to a derived class.
- void [derived_synch](#) ([PRPLList](#) &prp_list)
For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version waits for at least one completion.
- void [derived_synch_nowait](#) ([PRPLList](#) &prp_list)
For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version is nonblocking and will return without any completions if none are immediately available.
- int [derived_synchronous_local_analysis](#) (const int &analysis_id)

Public Attributes

- [SysCallAnalysisCode](#) `code`
Used to read/write parameter files and responses.

Protected Member Functions

- void [derived_synch_kernel](#) ([PRPList](#) &prp_list)
Convenience function for common code between wait and nowait case.
- bool [grid_file_test](#) (const [String](#) &root_file)
test file(s) for existence based on root_file name

Protected Attributes

- [IntSet](#) `idSet`
Set of function evaluation id's for active asynchronous system call evaluations.
- [IntShortMap](#) `failCountMap`
map linking function evaluation id's to number of response read failures
- [start_grid_computing_t](#) `start_grid_computing`
handle to dynamically linked start_grid_computing function
- [perform_analysis_t](#) `perform_analysis`
handle to dynamically linked perform_analysis grid function
- [get_jobs_completed_t](#) `get_jobs_completed`
handle to dynamically linked get_jobs_completed grid function
- [stop_grid_computing_t](#) `stop_grid_computing`
handle to dynamically linked stop_grid_computing function

10.44.1 Detailed Description

Derived application interface class which spawns simulation codes using grid services such as Condor or Globus.

This class is currently a modified copy of [SysCallApplicInterface](#) adapted for use with an external grid services library which was dynamically linked using `dlopen()` services.

10.44.2 Member Function Documentation

10.44.2.1 `int derived_synchronous_local_analysis (const int & analysis_id)` [inline, virtual]

This code provides the derived function used by [ApplicationInterface::serve_analyses_synch\(\)](#).

TODO - allow local analyses????

Reimplemented from [ApplicationInterface](#).

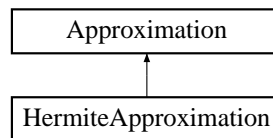
The documentation for this class was generated from the following files:

- GridApplicInterface.H
- GridApplicInterface.C

10.45 HermiteApproximation Class Reference

Derived approximation class for Hermite polynomials (global approximation).

Inheritance diagram for HermiteApproximation::



Public Member Functions

- [HermiteApproximation \(\)](#)
default constructor
- [HermiteApproximation \(ProblemDescDB &problem_db, const size_t &num_acv\)](#)
standard constructor
- [~HermiteApproximation \(\)](#)
destructor

Protected Member Functions

- `int num_coefficients () const`
return the minimum number of samples required to build the derived class approximation type in numVars dimensions
- `int num_constraints () const`
return the number of constraints to be enforced via anchorPoint
- `const RealVector & approximation_coefficients ()`
return the coefficient array computed by find_coefficients()
- `void find_coefficients ()`
find the Polynomial Chaos coefficients for the response surface
- `const Real & get_value (const RealVector &x)`
retrieve the function value for a given parameter set x

Private Member Functions

- void [get_num_chaos](#) ()
calculate number of Chaos according to the highest order of Chaos
- [RealVector](#) [get_chaos](#) (const [RealVector](#) &x, int order)
calculate the Polynomial Chaos from variables

Private Attributes

- [RealVector](#) [chaosCoeffs](#)
numChaos entries
- [RealVectorArray](#) [chaosSamples](#)
*numChaos*num_pts entries*
- int [numChaos](#)
Number of terms in Polynomial Chaos Expansion.
- int [highestOrder](#)
Highest order of Hermite Polynomials in Expansion.

10.45.1 Detailed Description

Derived approximation class for Hermite polynomials (global approximation).

The [HermiteApproximation](#) class provides a global approximation based on Hermite polynomials. It is used primarily for polynomial chaos expansions (for stochastic finite element approaches to uncertainty quantification).

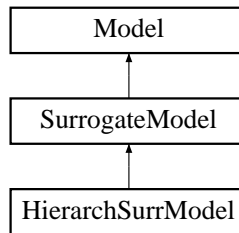
The documentation for this class was generated from the following files:

- HermiteApproximation.H
- HermiteApproximation.C

10.46 HierarchSurrModel Class Reference

Derived model class within the surrogate model branch for managing hierarchical surrogates (models of varying fidelity).

Inheritance diagram for HierarchSurrModel::



Public Member Functions

- [HierarchSurrModel \(ProblemDescDB &problem_db\)](#)
constructor
- [~HierarchSurrModel \(\)](#)
destructor

Protected Member Functions

- void [derived_compute_response](#) (const [ActiveSet](#) &set)
portion of [compute_response\(\)](#) specific to [HierarchSurrModel](#)
- void [derived_async_compute_response](#) (const [ActiveSet](#) &set)
portion of [async_compute_response\(\)](#) specific to [HierarchSurrModel](#)
- const [ResponseArray](#) & [derived_synchronize](#) ()
portion of [synchronize\(\)](#) specific to [HierarchSurrModel](#)
- const [IntResponseMap](#) & [derived_synchronize_nowait](#) ()
portion of [synchronize_nowait\(\)](#) specific to [HierarchSurrModel](#)
- [Model](#) & [surrogate_model](#) ()
return [lowFidelityModel](#)
- [Model](#) & [truth_model](#) ()

return highFidelityModel

- void [derived_subordinate_models](#) (ModelList &ml, bool recurse_flag)
return lowFidelityModel and highFidelityModel
- void [surrogate_bypass](#) (bool bypass_flag)
set surrogateBypass flag and pass request on to highFidelityModel for any lower-level surrogates.
- void [build_approximation](#) ()
use highFidelityModel to compute the truth values needed for correction of lowFidelityModel results
- void [component_parallel_mode](#) (int mode)
update component parallel mode for supporting parallelism in lowFidelityModel and highFidelityModel
- void [derived_init_communicators](#) (const int &max_iterator_concurrency)
set up lowFidelityModel and highFidelityModel for parallel operations
- void [derived_init_serial](#) ()
set up lowFidelityModel and highFidelityModel for serial operations.
- void [derived_set_communicators](#) (const int &max_iterator_concurrency)
set active parallel configuration within lowFidelityModel and highFidelityModel
- void [reset_communicators](#) ()
reset communicator partition data for the [HierarchSurrModel](#) (request forwarded to lowFidelityModel and high-FidelityModel)
- void [derived_free_communicators](#) (const int &max_iterator_concurrency)
deallocate communicator partitions for the [HierarchSurrModel](#) (request forwarded to lowFidelityModel and high-FidelityModel)
- void [serve](#) ()
Service lowFidelityModel and highFidelityModel job requests received from the master. Completes when a termination message is received from [stop_servers\(\)](#).
- void [stop_servers](#) ()
Executed by the master to terminate lowFidelityModel and highFidelityModel server operations when iteration on the [HierarchSurrModel](#) is complete.
- int [evaluation_id](#) () const
Return the current evaluation id for the [HierarchSurrModel](#).
- void [set_evaluation_reference](#) ()
set the evaluation counter reference points for the [HierarchSurrModel](#) (request forwarded to lowFidelityModel and highFidelityModel)

- void `print_evaluation_summary` (ostream &s, bool minimal_header=false, bool relative_count=true) const

print the evaluation summary for the [HierarchSurrModel](#) (request forwarded to [lowFidelityModel](#) and [highFidelityModel](#))

Private Member Functions

- void `update_model` (Model &model)

update the incoming model ([lowFidelityModel](#) or [highFidelityModel](#)) with current variable values/bounds/labels

Private Attributes

- int `hierModelEvals`

number of calls to [derived_compute_response\(\)](#)/[derived_asynch_compute_response\(\)](#)

- Model `lowFidelityModel`

provides approximate low fidelity function evaluations. [Model](#) is of arbitrary type and supports recursions (e.g., [lowFidelityModel](#) can be a data fit surrogate on a low fidelity model).

- Model `highFidelityModel`

provides truth evaluations for computing corrections to the low fidelity results. [Model](#) is of arbitrary type and supports recursions.

- Response `highFidResponse`

the high fidelity response is computed in [build_approximation\(\)](#) and needs class scope for use in automatic surrogate construction in [derived compute_response](#) functions.

10.46.1 Detailed Description

Derived model class within the surrogate model branch for managing hierarchical surrogates (models of varying fidelity).

The [HierarchSurrModel](#) class manages hierarchical models of varying fidelity. In particular, it uses a low fidelity model as a surrogate for a high fidelity model. The class contains a [lowFidelityModel](#) which performs the approximate low fidelity function evaluations and a [highFidelityModel](#) which provides truth evaluations for computing corrections to the low fidelity results.

10.46.2 Member Function Documentation

10.46.2.1 void derived_compute_response (const [ActiveSet](#) & set) [protected, virtual]

portion of [compute_response\(\)](#) specific to [HierarchSurrModel](#)

Evaluate the approximate response using [lowFidelityModel](#), compute the high fidelity response if needed with [build_approximation\(\)](#), and, if correction is active, correct the low fidelity results.

Reimplemented from [Model](#).

10.46.2.2 void derived_asynch_compute_response (const [ActiveSet](#) & set) [protected, virtual]

portion of [asynch_compute_response\(\)](#) specific to [HierarchSurrModel](#)

Evaluate the approximate response using an asynchronous [lowFidelityModel](#) evaluation and compute the high fidelity response with [build_approximation\(\)](#) (for correcting the low fidelity results in [derived_synchronize\(\)](#) and [derived_synchronize_nowait\(\)](#)) if not performed previously.

Reimplemented from [Model](#).

10.46.2.3 const [ResponseArray](#) & derived_synchronize () [protected, virtual]

portion of [synchronize\(\)](#) specific to [HierarchSurrModel](#)

Perform a blocking retrieval of all asynchronous evaluations from [lowFidelityModel](#) and, if automatic correction is on, apply correction to each response in the array.

Reimplemented from [Model](#).

10.46.2.4 const [IntResponseMap](#) & derived_synchronize_nowait () [protected, virtual]

portion of [synchronize_nowait\(\)](#) specific to [HierarchSurrModel](#)

Perform a nonblocking retrieval of currently available asynchronous evaluations from [lowFidelityModel](#) and, if automatic correction is on, apply correction to each response in the list.

Reimplemented from [Model](#).

10.46.2.5 int evaluation_id () const [inline, protected, virtual]

Return the current evaluation id for the [HierarchSurrModel](#).

return the hierarchical model evaluation count. Due to possibly intermittent use of surrogate bypass, this is not the same as either the loFi or hiFi model evaluation counts. It also does not distinguish duplicate evals.

Reimplemented from [Model](#).

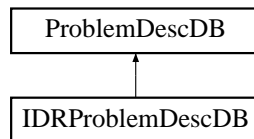
The documentation for this class was generated from the following files:

- [HierarchSurrModel.H](#)
- [HierarchSurrModel.C](#)

10.47 IDRProblemDescDB Class Reference

The derived input file database utilizing the IDR parser.

Inheritance diagram for IDRProblemDescDB::



Public Member Functions

- [IDRProblemDescDB](#) ([ParallelLibrary](#) ¶llel_lib)
constructor
- [~IDRProblemDescDB](#) ()
destructor
- void [derived_manage_inputs](#) (const char *dakota_input_file)
parses the input file and populates the problem description database using IDR.

Static Public Member Functions

- static void [strategy_kwhandler](#) (const struct FunctionData *parsed_data)
strategy keyword handler called by IDR when a complete strategy specification is parsed
- static void [method_kwhandler](#) (const struct FunctionData *parsed_data)
method keyword handler called by IDR when a complete method specification is parsed
- static void [model_kwhandler](#) (const struct FunctionData *parsed_data)
model keyword handler called by IDR when a complete model specification is parsed
- static void [variables_kwhandler](#) (const struct FunctionData *parsed_data)
variables keyword handler called by IDR when a complete variables specification is parsed
- static void [interface_kwhandler](#) (const struct FunctionData *parsed_data)
interface keyword handler called by IDR when a complete interface specification is parsed
- static void [responses_kwhandler](#) (const struct FunctionData *parsed_data)
responses keyword handler called by IDR when a complete responses specification is parsed

Static Private Member Functions

- static void [idr_kw_id_error](#) (const char *kw)
Error handler for missing required IDR keyword.
- static Int [idr_find_id](#) (Int *id_pos, const Int cntr, const char *id, const char **id_list, const char *kw)
Function used by the keyword handlers to return the number of parsed instances of a particular keyword.
- static Int ** [idr_get_int_table](#) (const struct FunctionData *parsed_data, Int identifier, Int &table_len, Int num_lists, Int list_entry_len)
Function for creating an IDR table of Ints.
- static Real ** [idr_get_real_table](#) (const struct FunctionData *parsed_data, Int identifier, Int &table_len, Int num_lists, Int list_entry_len)
Function for creating an IDR table of Reals.
- static char *** [idr_get_string_table](#) (const struct FunctionData *parsed_data, Int identifier, Int &table_len, Int num_lists, Int list_entry_len)
Function for creating an IDR table of strings.

Static Private Attributes

- static [IDRProblemDescDB](#) * [pDDBInstance](#)
pointer to the active object instance used within the static kwhandler functions in order to avoid the need for static data
- static Int ** [intTable](#)
integer table populated in [idr_get_int_table\(\)](#)
- static Real ** [realTable](#)
real table populated in [idr_get_real_table\(\)](#)
- static char *** [stringTable](#)
string table populated in [idr_get_string_table\(\)](#)

10.47.1 Detailed Description

The derived input file database utilizing the IDR parser.

The [IDRProblemDescDB](#) class is a database for DAKOTA input file data that is populated by the Input Deck Reader (IDR) parser. When the parser reads a complete keyword (delimited by a newline), it calls the corresponding kwhandler function from this class which populates the corresponding Data object from the base class. For information on modifying the IDR input parsing procedures, refer to [Dakota/docs/Dev_Spec_Change.dox](#)

10.47.2 Member Function Documentation

10.47.2.1 void derived_manage_inputs (const char * *dakota_input_file*) [virtual]

parses the input file and populates the problem description database using IDR.

Parse the input file using the Input Deck Reader (IDR) parsing system. IDR populates the [IDRProblemDescDB](#) object with the input file data.

Reimplemented from [ProblemDescDB](#).

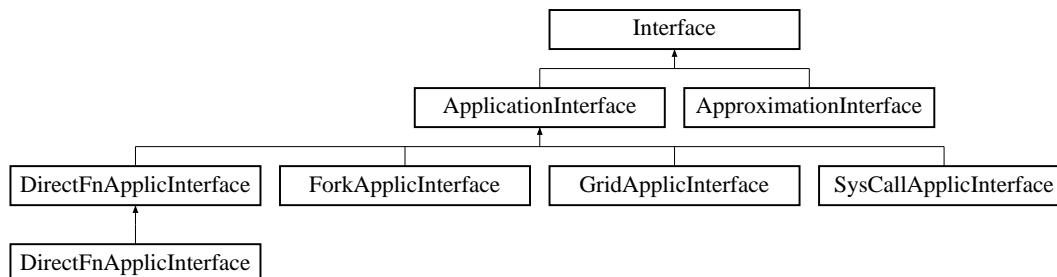
The documentation for this class was generated from the following files:

- IDRProblemDescDB.H
- IDRProblemDescDB.C

10.48 Interface Class Reference

Base class for the interface class hierarchy.

Inheritance diagram for Interface::



Public Member Functions

- [Interface](#) ()
default constructor
- [Interface](#) ([ProblemDescDB](#) &problem_db)
standard constructor for envelope
- [Interface](#) (const [Interface](#) &interface)
copy constructor
- virtual [~Interface](#) ()
destructor
- [Interface](#) operator= (const [Interface](#) &interface)
assignment operator
- virtual void [map](#) (const [Variables](#) &vars, const [ActiveSet](#) &set, [Response](#) &response, const bool asynch_
flag=false)
the function evaluator: provides a "mapping" from the variables to the responses.
- virtual const [ResponseArray](#) & [synch](#) ()
recovers data from a series of asynchronous evaluations (blocking)
- virtual const [IntResponseMap](#) & [synch_nowait](#) ()
recovers data from a series of asynchronous evaluations (nonblocking)

- virtual void [serve_evaluations](#) ()
evaluation server function for multiprocessor executions
- virtual void [stop_evaluation_servers](#) ()
send messages from iterator rank 0 to terminate evaluation servers
- virtual void [init_communicators](#) (const [IntArray](#) &message_lengths, const int &max_iterator_concurrency)

allocate communicator partitions for concurrent evaluations within an iterator and concurrent multiprocessor analyses within an evaluation.
- virtual void [reset_communicators](#) (const [IntArray](#) &message_lengths)
reset the local parallel partition data for an interface (the partitions are already allocated in [ParallelLibrary](#)).
- virtual void [free_communicators](#) ()
deallocate communicator partitions for concurrent evaluations within an iterator and concurrent multiprocessor analyses within an evaluation.
- virtual void [init_serial](#) ()
reset certain defaults for serial interface objects.
- virtual int [asynch_local_evaluation_concurrency](#) () const
return the user-specified concurrency for asynch local evaluations
- virtual [String](#) [interface_synchronization](#) () const
return the user-specified interface synchronization
- virtual int [minimum_samples](#) (bool constraint_flag) const
returns the minimum number of samples required to build a particular [ApproximationInterface](#) (used by [DataFitSurrModels](#)).
- virtual void [update_approximation](#) (const [RealVectorArray](#) &all_variables, const [ResponseArray](#) &all_responses)
passes multiple points to an approximation for building a surrogate
- virtual void [update_approximation](#) (const [RealVector](#) &c_variables, const [Response](#) &response)
passes a single point to an approximation for building a surrogate
- virtual void [build_approximation](#) (const [RealVector](#) &lower_bnds, const [RealVector](#) &upper_bnds)
builds the surrogate
- virtual void [append_approximation](#) (const [RealVector](#) &c_variables, const [Response](#) &response)
updates an existing global approximation with new data
- virtual void [clear](#) ()
clears all data from an approximation interface

- virtual bool [anchor](#) () const
queries the presence of an anchorPoint within an approximation interface
- virtual const [RealVectorArray](#) & [approximation_coefficients](#) ()
retrieve the approximation coefficients from each [Approximation](#) within an [ApproximationInterface](#)
- virtual const [StringArray](#) & [analysis_drivers](#) () const
retrieve the analysis drivers specification for application interfaces
- void [assign_rep](#) ([Interface](#) *interface_rep, bool ref_count_incr=true)
replaces existing letter with a new one
- const [String](#) & [interface_type](#) () const
returns the interface type
- const [String](#) & [interface_id](#) () const
returns the interface identifier
- int [evaluation_id](#) () const
returns the current function evaluation id for the interface
- void [set_eval_reference](#) ()
set evaluation count reference points for the interface
- void [print_eval_summary](#) (ostream &s, bool minimal_header, bool relative_count) const
print an evaluation summary for the interface
- bool [multi_proc_eval_flag](#) () const
returns a flag signaling the use of multiprocessor evaluation partitions
- bool [iterator_eval_dedicated_master_flag](#) () const
returns a flag signaling the use of a dedicated master processor at the iterator-evaluation scheduling level
- bool [is_null](#) () const
function to check interfaceRep (does this envelope contain a letter?)

Protected Member Functions

- [Interface](#) ([BaseConstructor](#), const [ProblemDescDB](#) &problem_db)
constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)
- void [asv_mapping](#) (const [ActiveSet](#) &total_set, [ActiveSet](#) &algebraic_set, [ActiveSet](#) &core_set, const [Variables](#) &vars, const [Response](#) &response)

define the evaluation requirements for *algebraic_mappings()* (*algebraic_set*) and the core Application/Approximation mapping (*core_set*) from the total *Interface* evaluation requirements (*total_set*). Also

- void *algebraic_mappings* (const *Variables* &vars, const *ActiveSet* &*algebraic_set*, *Response* &*algebraic_response*)
evaluate the algebraic_response using the AMPL solver library and the data extracted from the algebraic_mappings file
- void *response_mapping* (const *Response* &*algebraic_response*, const *Response* &*core_response*, *Response* &*total_response*)
combine the response from algebraic_mappings() with the response from derived_map() to create the total response

Protected Attributes

- *String* *interfaceType*
the interface type: system, fork, direct, grid, or approximation
- *String* *idInterface*
the interface specification identifier string from the DAKOTA input file (used in print_eval_summary())
- bool *algebraicMappings*
flag for the presence of algebraic_mappings that define the subset of an Interface's parameter to response mapping that is explicit and algebraic.
- bool *coreMappings*
flag for the presence of non-algebraic mappings that define the core of an Interface's parameter to response mapping (using analysis_drivers for ApplicationInterface or functionSurfaces for ApproximationInterface).
- int *fnEvalId*
total interface evaluation counter
- int *newFnEvalId*
new (non-duplicate) interface evaluation counter
- int *fnEvalIdRefPt*
iteration reference point for fnEvalId
- int *newFnEvalIdRefPt*
iteration reference point for newFnEvalId
- *IntArray* *fnValCounter*
number of value evaluations by resp fn
- *IntArray* *fnGradCounter*
number of gradient evaluations by resp fn

- [IntArray fnHessCounter](#)
number of Hessian evaluations by resp fn
- [IntArray newFnValCounter](#)
number of new value evaluations by resp fn
- [IntArray newFnGradCounter](#)
number of new gradient evaluations by resp fn
- [IntArray newFnHessCounter](#)
number of new Hessian evaluations by resp fn
- [IntArray fnValRefPt](#)
iteration reference point for fnValCounter
- [IntArray fnGradRefPt](#)
iteration reference point for fnGradCounter
- [IntArray fnHessRefPt](#)
iteration reference point for fnHessCounter
- [IntArray newFnValRefPt](#)
iteration reference point for newFnValCounter
- [IntArray newFnGradRefPt](#)
iteration reference point for newFnGradCounter
- [IntArray newFnHessRefPt](#)
iteration reference point for newFnHessCounter
- [ResponseArray rawResponseArray](#)
The complete array of responses returned after a blocking schedule of asynchronous evaluations.
- [IntResponseMap rawResponseMap](#)
The partial map of responses returned after a nonblocking schedule of asynchronous evaluations.
- [StringArray responseTags](#)
response function identifier tags from the DAKOTA input file (used in [print_eval_summary\(\)](#) and derived direct interface classes)
- [bool multiProcEvalFlag](#)
flag for multiprocessor evaluation partitions (evalComm)
- [bool ieDedMasterFlag](#)
flag for dedicated master partitioning at the iterator level

- bool [silentFlag](#)
flag for really quiet (silent) interface output
- bool [quietFlag](#)
flag for quiet interface output
- bool [verboseFlag](#)
flag for verbose interface output
- bool [debugFlag](#)
flag for really verbose (debug) interface output

Private Member Functions

- [Interface](#) * [get_interface](#) ([ProblemDescDB](#) &problem_db)
Used by the envelope to instantiate the correct letter class.

Private Attributes

- [StringArray](#) [algebraicVarTags](#)
set of variable tags from AMPL stub.col
- [SizetArray](#) [algebraicACVIndices](#)
set of indices mapping AMPL algebraic variables to DAKOTA all continuous variables
- [SizetArray](#) [algebraicDerivIndices](#)
set of indices mapping AMPL algebraic variables to DAKOTA derivative variables
- [StringArray](#) [algebraicFnTags](#)
set of function tags from AMPL stub.row
- [SizetArray](#) [algebraicFnIndices](#)
set of indices mapping AMPL algebraic objective functions to DAKOTA response functions
- [Interface](#) * [interfaceRep](#)
pointer to the letter (initialized only for the envelope)
- int [referenceCount](#)
number of objects sharing interfaceRep

10.48.1 Detailed Description

Base class for the interface class hierarchy.

The [Interface](#) class hierarchy provides the part of a [Model](#) that is responsible for mapping a set of [Variables](#) into a set of Responses. The mapping is performed using either a simulation-based application interface or a surrogate-based approximation interface. For memory efficiency and enhanced polymorphism, the interface hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Interface](#)) serves as the envelope and one of the derived classes (selected in [Interface::get_interface\(\)](#)) serves as the letter.

10.48.2 Constructor & Destructor Documentation

10.48.2.1 [Interface](#) ()

default constructor

used in [Model](#) envelope class instantiations

10.48.2.2 [Interface](#) ([ProblemDescDB](#) & *problem_db*)

standard constructor for envelope

Used in [Model](#) instantiation to build the envelope. This constructor only needs to extract enough data to properly execute [get_interface](#), since [Interface::Interface\(BaseConstructor, problem_db\)](#) builds the actual base class data inherited by the derived interfaces.

10.48.2.3 [Interface](#) (const [Interface](#) & *interface*)

copy constructor

Copy constructor manages sharing of [interfaceRep](#) and incrementing of [referenceCount](#).

10.48.2.4 [~Interface](#) () [virtual]

destructor

Destructor decrements [referenceCount](#) and only deletes [interfaceRep](#) if [referenceCount](#) is zero.

10.48.2.5 [Interface](#) ([BaseConstructor](#), const [ProblemDescDB](#) & *problem_db*) [protected]

constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all inherited interfaces. [get_interface\(\)](#) instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list

(to avoid the recursion of the base class constructor calling `get_interface()` again). Since this is the letter and the letter IS the representation, `interfaceRep` is set to NULL (an uninitialized pointer causes problems in `~Interface`).

10.48.3 Member Function Documentation

10.48.3.1 `Interface` `operator=` (`const Interface & interface`)

assignment operator

Assignment operator decrements `referenceCount` for old `interfaceRep`, assigns new `interfaceRep`, and increments `referenceCount` for new `interfaceRep`.

10.48.3.2 `void assign_rep` (`Interface * interface_rep`, `bool ref_count_incr = true`)

replaces existing letter with a new one

Similar to the assignment operator, the `assign_rep()` function decrements `referenceCount` for the old `interfaceRep` and assigns the new `interfaceRep`. It is different in that it is used for publishing derived class letters to existing envelopes, as opposed to sharing representations among multiple envelopes (in particular, `assign_rep` is passed a letter object and `operator=` is passed an envelope object). Letter assignment supports two models as governed by `ref_count_incr`:

- `ref_count_incr = true` (default): the incoming letter belongs to another envelope. In this case, increment the reference count in the normal manner so that deallocation of the letter is handled properly.
- `ref_count_incr = false`: the incoming letter is instantiated on the fly and has no envelope. This case is modeled after `get_interface()`: a letter is dynamically allocated using `new` and passed into `assign_rep`, the letter's reference count is not incremented, and the letter is not remotely deleted (its memory management is passed over to the envelope).

10.48.3.3 `Interface * get_interface` (`ProblemDescDB & problem_db`) [`private`]

Used by the envelope to instantiate the correct letter class.

used only by the envelope constructor to initialize `interfaceRep` to the appropriate derived type.

10.48.4 Member Data Documentation

10.48.4.1 ResponseArray rawResponseArray [protected]

The complete array of responses returned after a blocking schedule of asynchronous evaluations.

The array is the raw set of responses corresponding to all asynchronous map calls. This raw array is postprocessed (i.e., finite difference gradients merged) in [Model::synchronize\(\)](#) where it becomes responseArray.

10.48.4.2 IntResponseMap rawResponseMap [protected]

The partial map of responses returned after a nonblocking schedule of asynchronous evaluations.

The map is a partial set of completions which are identified through their `fn_eval_id` key. Postprocessing from raw to combined form (i.e., finite difference gradient merging) is not currently supported in [Model::synchronize_nowait\(\)](#).

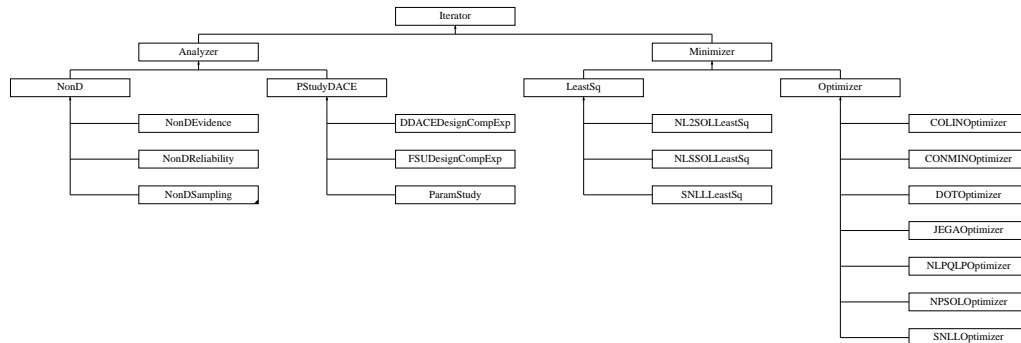
The documentation for this class was generated from the following files:

- DakotaInterface.H
- DakotaInterface.C

10.49 Iterator Class Reference

Base class for the iterator class hierarchy.

Inheritance diagram for Iterator::



Public Member Functions

- [Iterator](#) ()
default constructor
- [Iterator](#) ([Model](#) &model)
standard constructor for envelope
- [Iterator](#) (const [Iterator](#) &iterator)
copy constructor
- virtual [~Iterator](#) ()
destructor
- [Iterator](#) operator= (const [Iterator](#) &iterator)
assignment operator
- virtual void [run](#) ()
run the iterator; portion of [run_iterator\(\)](#)
- virtual const [Variables](#) & [variable_results](#) () const
return the final iterator solution (variables)
- virtual const [Response](#) & [response_results](#) () const
return the final iterator solution (response)

- virtual void [response_results_active_set](#) (const [ActiveSet](#) &set)
set the requested data for the final iterator response results
- virtual void [print_results](#) (ostream &s) const
print the final iterator results
- virtual void [multi_objective_weights](#) (const [RealVector](#) &multi_obj_wts)
set the relative weightings for multiple objective functions. Used by [ConcurrentStrategy](#) for Pareto set optimization.
- virtual void [sampling_reset](#) (int min_samples, bool all_data_flag, bool stats_flag)
reset sampling iterator
- virtual const [String](#) & [sampling_scheme](#) () const
return sampling name
- virtual [String](#) [uses_method](#) () const
return name of any enabling iterator used by this iterator
- virtual void [method_recourse](#) ()
perform a method switch, if possible, due to a detected conflict
- virtual const [VariablesArray](#) & [all_variables](#) () const
return the complete set of evaluated variables
- virtual const [RealVectorArray](#) & [all_c_variables](#) () const
return the complete set of evaluated continuous variables
- virtual const [ResponseArray](#) & [all_responses](#) () const
return the complete set of computed responses
- virtual const [RealVectorArray](#) & [all_fn_responses](#) () const
return the complete set of computed function responses
- void [pre_run](#) ()
utility function to perform common operations prior to [run\(\)](#)
- void [run_iterator](#) (ostream &s)
utility function to automate [pre_run\(\)/run\(\)/post_run\(\)](#) verbosely
- void [run_iterator](#) ()
utility function to automate [pre_run\(\)/run\(\)/post_run\(\)](#) quietly
- void [post_run](#) (ostream &s)
utility function to perform common operations following [run\(\)](#) verbosely

- void `post_run ()`
utility function to perform common operations following `run()` quietly
- void `assign_rep (Iterator *iterator_rep, bool ref_count_incr=true)`
replaces existing letter with a new one
- void `user_defined_model (const Model &the_model)`
set the model
- `Model & user_defined_model () const`
return the model
- const `String & method_name () const`
return the method name
- const `String & method_id () const`
return the method identifier (idMethod)
- const int & `maximum_concurrency () const`
return the maximum concurrency supported by the iterator
- void `maximum_concurrency (const int &max_conc)`
set the maximum concurrency supported by the iterator
- void `active_set (const ActiveSet &set)`
set the default active set vector (for use with iterators that employ `evaluate_parameter_sets()`)
- const `ActiveSet & active_set () const`
return the default active set vector (used by iterators that employ `evaluate_parameter_sets()`)
- void `sub_iterator_flag (bool si_flag)`
set subIteratorFlag
- void `variable_mappings (const SisetArray &c_index1, const SisetArray &d_index1, const SisetArray &index2)`
set primaryCVarMapIndices, primaryDVarMapIndices, secondaryVarMapIndices
- bool `is_null () const`
function to check iteratorRep (does this envelope contain a letter?)

Protected Member Functions

- `Iterator (BaseConstructor, Model &model)`
constructor initializes the base class part of letter classes (`BaseConstructor` overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

- [Iterator](#) ([NoDBBaseConstructor](#), [Model](#) &model)
base class for iterator classes constructed on the fly (no DB queries)
- virtual void [derived_pre_run](#) ()
portions of pre_run specific to derived iterators
- virtual void [derived_post_run](#) ()
portions of post_run specific to derived iterators

Protected Attributes

- [Model](#) & [userDefinedModel](#)
class member reference for the model passed into the constructor
- const [ProblemDescDB](#) & [probDescDB](#)
class member reference to the problem description database
- [String](#) [methodName](#)
name of the iterator (the user's method spec)
- Real [convergenceTol](#)
iteration convergence tolerance
- int [maxIterations](#)
maximum number of iterations for the iterator
- int [maxFunctionEvals](#)
maximum number of fn evaluations for the iterator
- int [maxConcurrency](#)
maximum coarse-grained concurrency
- size_t [numFunctions](#)
number of response functions
- size_t [numContinuousVars](#)
number of active continuous vars.
- size_t [numDiscreteVars](#)
number of active discrete vars.
- [ActiveSet](#) [activeSet](#)
tracks the response data requirements on each function evaluation

- **bool subIteratorFlag**
flag indicating if this `Iterator` is a sub-iterator (`NestedModel::subIterator` or `DataFitSurrModel::daceIterator`)
- **SizeTArray primaryCVarMapIndices**
"primary" continuous variable mappings flowed down from higher level iteration
- **SizeTArray primaryDVarMapIndices**
"primary" discrete variable mappings flowed down from higher level iteration
- **SizeTArray secondaryVarMapIndices**
"secondary" variable mappings flowed down from higher level iteration
- **String gradientType**
type of gradient data: analytic, numerical, mixed, or none
- **String intervalType**
type of numerical gradient interval: central or forward
- **String methodSource**
source of numerical gradient routine: dakota or vendor
- **String hessianType**
type of Hessian data: analytic, numerical, quasi, mixed, or none
- **Real fdGradStepSize**
relative finite difference step size for numerical gradients
- **Real fdHessByGradStepSize**
relative finite difference step size for numerical Hessians estimated using first-order differences of gradients
- **Real fdHessByFnStepSize**
relative finite difference step size for numerical Hessians estimated using second-order differences of function values
- **bool silentOutput**
flag for really quiet (silent) algorithm output
- **bool quietOutput**
flag for quiet algorithm output
- **bool verboseOutput**
flag for verbose algorithm output
- **bool debugOutput**
flag for really verbose (debug) algorithm output
- **bool asynchFlag**
copy of the model's asynchronous evaluation flag

Private Member Functions

- [Iterator](#) * [get_iterator](#) ([Model](#) &model)

Used by the envelope to instantiate the correct letter class.

Private Attributes

- [String](#) [idMethod](#)

method identifier string from the input file

- [Iterator](#) * [iteratorRep](#)

pointer to the letter (initialized only for the envelope)

- [int](#) [referenceCount](#)

number of objects sharing iteratorRep

10.49.1 Detailed Description

Base class for the iterator class hierarchy.

The [Iterator](#) class is the base class for one of the primary class hierarchies in DAKOTA. The iterator hierarchy contains all of the iterative algorithms which use repeated execution of simulations as function evaluations. For memory efficiency and enhanced polymorphism, the iterator hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Iterator](#)) serves as the envelope and one of the derived classes (selected in [Iterator::get_iterator\(\)](#)) serves as the letter.

10.49.2 Constructor & Destructor Documentation

10.49.2.1 [Iterator](#) ()

default constructor

The default constructor is used in `Vector<Iterator>` instantiations and for initialization of [Iterator](#) objects contained in [Strategy](#) derived classes (see derived class header files). `iteratorRep` is `NULL` in this case (a populated `problem_db` is needed to build a meaningful [Iterator](#) object). This makes it necessary to check for `NULL` pointers in the copy constructor, assignment operator, and destructor.

10.49.2.2 [Iterator](#) ([Model](#) & *model*)

standard constructor for envelope

Used in iterator instantiations within strategy constructors. Envelope constructor only needs to extract enough data to properly execute `get_iterator`, since `Iterator(BaseConstructor, model)` builds the actual base class data inherited by the derived iterators.

10.49.2.3 `Iterator` (`const Iterator & iterator`)

copy constructor

Copy constructor manages sharing of `iteratorRep` and incrementing of `referenceCount`.

10.49.2.4 `~Iterator` () [virtual]

destructor

Destructor decrements `referenceCount` and only deletes `iteratorRep` when `referenceCount` reaches zero.

10.49.2.5 `Iterator` (`BaseConstructor, Model & model`) [protected]

constructor initializes the base class part of letter classes (`BaseConstructor` overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

This constructor builds the base class data for all inherited iterators. `get_iterator()` instantiates a derived class and the derived class selects this base class constructor in its initialization list (to avoid the recursion of the base class constructor calling `get_iterator()` again). Since the letter IS the representation, its representation pointer is set to NULL (an uninitialized pointer causes problems in `~Iterator`).

10.49.2.6 `Iterator` (`NoDBBaseConstructor, Model & model`) [protected]

base class for iterator classes constructed on the fly (no DB queries)

This constructor also builds base class data for inherited iterators. However, it is used for on-the-fly instantiations for which DB queries cannot be used. Therefore it only sets attributes taken from the incoming model.

10.49.3 Member Function Documentation

10.49.3.1 `Iterator` `operator=` (`const Iterator & iterator`)

assignment operator

Assignment operator decrements `referenceCount` for old `iteratorRep`, assigns new `iteratorRep`, and increments `referenceCount` for new `iteratorRep`.

10.49.3.2 `void run` () [virtual]

run the iterator; portion of `run_iterator()`

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This function is the virtual run function for the iterator class hierarchy. All derived classes need to redefine it.

Reimplemented in [LeastSq](#), [NonD](#), [Optimizer](#), and [PStudyDACE](#).

10.49.3.3 void print_results (ostream & s) const [virtual]

print the final iterator results

This virtual function provides additional iterator-specific final results outputs beyond the function evaluation summary printed in [post_run\(\)](#).

Reimplemented in [LeastSq](#), [Optimizer](#), [PStudyDACE](#), [NonDEvidence](#), [NonDLHSSampling](#), [NonDPCESSampling](#), and [NonDReliability](#).

10.49.3.4 void pre_run ()

utility function to perform common operations prior to [run\(\)](#)

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This function is the pre-run function. This function is not virtual: derived portions are defined in [derived_pre_run\(\)](#).

10.49.3.5 void run_iterator (ostream & s)

utility function to automate [pre_run\(\)](#)/[run\(\)](#)/[post_run\(\)](#) verbosely

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This non-virtual function is one form of the overloaded [run_iterator](#) function which automates the pre-run/run/post-run portions of the progression. This form accepts an ostream and executes verbosely.

10.49.3.6 void run_iterator ()

utility function to automate [pre_run\(\)](#)/[run\(\)](#)/[post_run\(\)](#) quietly

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This non-virtual function is one form of the overloaded [run_iterator](#) function which automates the pre-run/run/post-run portions of the progression. This form does not accept an ostream and executes quietly.

10.49.3.7 void post_run (ostream & s)

utility function to perform common operations following [run\(\)](#) verbosely

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This function is one form of the overloaded post-run function. This form accepts an ostream and executes verbosely. This function is not virtual: derived portions are defined in [derived_post_run\(\)](#).

10.49.3.8 void post_run ()

utility function to perform common operations following [run\(\)](#) quietly

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This function is one form of the overloaded post-run function. This form does not accept an ostream and executes quietly. This function is not virtual: derived portions are defined in [derived_post_run\(\)](#).

10.49.3.9 void assign_rep (Iterator * iterator_rep, bool ref_count_incr = true)

replaces existing letter with a new one

Similar to the assignment operator, the [assign_rep\(\)](#) function decrements referenceCount for the old iteratorRep and assigns the new iteratorRep. It is different in that it is used for publishing derived class letters to existing envelopes, as opposed to sharing representations among multiple envelopes (in particular, assign_rep is passed a letter object and operator= is passed an envelope object). Letter assignment supports two models as governed by ref_count_incr:

- ref_count_incr = true (default): the incoming letter belongs to another envelope. In this case, increment the reference count in the normal manner so that deallocation of the letter is handled properly.
- ref_count_incr = false: the incoming letter is instantiated on the fly and has no envelope. This case is modeled after [get_iterator\(\)](#): a letter is dynamically allocated using new and passed into assign_rep, the letter's reference count is not incremented, and the letter is not remotely deleted (its memory management is passed over to the envelope).

10.49.3.10 void derived_pre_run () [protected, virtual]

portions of pre_run specific to derived iterators

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This function is the virtual derived class portion of [pre_run\(\)](#). Redefinition by derived classes is optional.

Reimplemented in [CONMINOptimizer](#), [DOTOptimizer](#), [NLPQLPOptimizer](#), [SNLLLeastSq](#), and [SNLLOptimizer](#).

10.49.3.11 void derived_post_run () [protected, virtual]

portions of post_run specific to derived iterators

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This function is the virtual derived class portion of [post_run\(\)](#). Redefinition by derived classes is optional.

Reimplemented in [CONMINOptimizer](#), [DOTOptimizer](#), [NLPQLPOptimizer](#), [SNLLLeastSq](#), and [SNLLOptimizer](#).

10.49.3.12 Iterator * get_iterator (Model & model) [private]

Used by the envelope to instantiate the correct letter class.

Used only by the envelope constructor to initialize iteratorRep to the appropriate derived type, as given by the methodName attribute.

10.49.4 Member Data Documentation

10.49.4.1 Real `fdGradStepSize` [protected]

relative finite difference step size for numerical gradients

A scalar value (instead of the vector `fd_gradient_step_size spec`) is used within the iterator hierarchy since this attribute is only used to publish a step size to vendor numerical gradient algorithms.

10.49.4.2 Real `fdHessByGradStepSize` [protected]

relative finite difference step size for numerical Hessians estimated using first-order differences of gradients

A scalar value (instead of the vector `fd_hessian_step_size spec`) is used within the iterator hierarchy since this attribute is only used to publish a step size to vendor numerical Hessian algorithms.

10.49.4.3 Real `fdHessByFnStepSize` [protected]

relative finite difference step size for numerical Hessians estimated using second-order differences of function values

A scalar value (instead of the vector `fd_hessian_step_size spec`) is used within the iterator hierarchy since this attribute is only used to publish a step size to vendor numerical Hessian algorithms.

The documentation for this class was generated from the following files:

- `DakotaIterator.H`
- `DakotaIterator.C`

10.50 JEGAEvaluator Class Reference

This evaluator uses Sandia National Laboratories [Dakota](#) software.

Public Member Functions

- virtual bool [Evaluate](#) (JEGA::Utilities::DesignGroup &group)
Does evaluation of each design in "group".
- virtual bool [Evaluate](#) (JEGA::Utilities::Design &des)
This method cannot be used!!
- virtual std::string [GetName](#) () const
Returns the proper name of this operator.
- virtual std::string [GetDescription](#) () const
Returns a full description of what this operator does and how.
- virtual GeneticAlgorithmOperator * [Clone](#) (JEGA::Algorithms::GeneticAlgorithm &algorithm) const
Creates and returns a pointer to an exact duplicate of this operator.
- [JEGAEvaluator](#) (JEGA::Algorithms::GeneticAlgorithm &algorithm, [Model](#) &model, [JEGAOptimizer](#) &theOptimizer)
Constructs a [JEGAEvaluator](#) for use by algorithm.
- [JEGAEvaluator](#) (const [JEGAEvaluator](#) ©)
Copy constructs a [JEGAEvaluator](#).
- [JEGAEvaluator](#) (const [JEGAEvaluator](#) ©, JEGA::Algorithms::GeneticAlgorithm &algorithm, [Model](#) &model, [JEGAOptimizer](#) &theOptimizer)
Copy constructs a [JEGAEvaluator](#) for use by algorithm.

Static Public Member Functions

- static const std::string & [Name](#) ()
Returns the proper name of this operator.
- static const std::string & [Description](#) ()
Returns a full description of what this operator does and how.

Protected Member Functions

- [RealVector GetContinuumVariableValues](#) (const JEGA::Utilities::Design &from) const
Returns the continuous Design variable values held in Design from.
- [IntVector GetDiscreteVariableValues](#) (const JEGA::Utilities::Design &from) const
Returns the discrete Design variable values held in Design from.
- void [GetContinuumVariableValues](#) (const JEGA::Utilities::Design &from, [RealVector](#) &into) const
Places the continuous Design variable values from Design from into RealVector into.
- void [GetDiscreteVariableValues](#) (const JEGA::Utilities::Design &from, [IntVector](#) &into) const
Places the discrete Design variable values from Design from into IntVector into.
- void [SeparateVariables](#) (const JEGA::Utilities::Design &from, [IntVector](#) &intoDisc, [RealVector](#) &intoCont) const
This method fills intoDisc and intoCont appropriately using the values of from.
- void [RecordResponses](#) (const [RealVector](#) &from, JEGA::Utilities::Design &into) const
Records the computed objective and constraint function values into into.
- std::size_t [GetNumberNonLinearConstraints](#) () const
Returns the number of non-linear constraints for the problem.
- std::size_t [GetNumberLinearConstraints](#) () const
Returns the number of linear constraints for the problem.

Private Member Functions

- [JEGAEvaluator](#) (JEGA::Algorithms::GeneticAlgorithm &algorithm)
This constructor has no implementation and cannot be used.

Private Attributes

- [Model](#) & [_model](#)
The Model known by this evaluator.
- [JEGAOptimizer](#) & [_theOptimizer](#)
The JEGAOptimizer that created this evaluator.

10.50.1 Detailed Description

This evaluator uses Sandia National Laboratories [Dakota](#) software.

Evaluations are carried out using a [Model](#) which is known by reference to this class. This provides the advantage of execution on massively parallel computing architectures.

10.50.2 Constructor & Destructor Documentation

10.50.2.1 [JEGAEvaluator](#) ([JEGA::Algorithms::GeneticAlgorithm](#) & *algorithm*, [Model](#) & *model*, [JEGAOptimizer](#) & *theOptimizer*)

Constructs a [JEGAEvaluator](#) for use by *algorithm*.

The optimizer is needed for purposes of variable scaling.

Parameters:

algorithm The GA for which the new evaluator is to be used.

model The model through which evaluations will be done.

theOptimizer The optimizer that created and is using this evaluator.

10.50.2.2 [JEGAEvaluator](#) (const [JEGAEvaluator](#) & *copy*)

Copy constructs a [JEGAEvaluator](#).

Parameters:

copy The evaluator from which properties are to be duplicated into this.

10.50.2.3 [JEGAEvaluator](#) (const [JEGAEvaluator](#) & *copy*, [JEGA::Algorithms::GeneticAlgorithm](#) & *algorithm*, [Model](#) & *model*, [JEGAOptimizer](#) & *theOptimizer*)

Copy constructs a [JEGAEvaluator](#) for use by *algorithm*.

The optimizer is needed for purposes of variable scaling.

Parameters:

copy The existing [JEGAEvaluator](#) from which to retrieve properties.

algorithm The GA for which the new evaluator is to be used.

model The model through which evaluations will be done.

theOptimizer The optimizer that created and is using this evaluator.

10.50.2.4 **JEGAEvaluator** (JEGA::Algorithms::GeneticAlgorithm & *algorithm*) [private]

This constructor has no implementation and cannot be used.

This constructor can never be used. It is provided so that this operator can still be registered in an operator registry even though it can never be instantiated from there.

Parameters:

algorithm The GA for which the new evaluator is to be used.

10.50.3 Member Function Documentation

10.50.3.1 **const string & Name ()** [static]

Returns the proper name of this operator.

Returns:

The string "JEGA Evaluator".

10.50.3.2 **const string & Description ()** [static]

Returns a full description of what this operator does and how.

The returned text is:

```
This evaluator uses Sandia's DAKOTA optimization software to evaluate the passed in Designs. This makes it possible to take advantage of the fact that DAKOTA is designed to run on massively parallel machines.
```

Returns:

A description of the operation of this operator.

10.50.3.3 **RealVector GetContinuumVariableValues (const JEGA::Utilities::Design & *from*) const** [protected]

Returns the continuous Design variable values held in Design *from*.

It returns them as a RealVector for use in the [Dakota](#) interface. The values in the returned vector will be the actual values intended for use in the evaluation functions.

Parameters:

from The Design class object from which to extract the continuous design variable values.

Returns:

A vector of the continuous design variable values associated with *from*.

10.50.3.4 IntVector GetDiscreteVariableValues (const JEGA::Utilities::Design & *from*) const
[protected]

Returns the discrete Design variable values held in Design *from*.

It returns them as a IntVector for use in the [Dakota](#) interface. The values in the returned vector will be the values for the design variables as far as JEGA knows. However, in actuality, the values are the representations due to the way that [Dakota](#) manages discrete variables.

Parameters:

from The Design class object from which to extract the discrete design variable values.

Returns:

A vector of the discrete design variable values associated with *from*.

10.50.3.5 void GetContinuumVariableValues (const JEGA::Utilities::Design & *from*, RealVector & *into*) const
[protected]

Places the continuous Design variable values from Design *from* into RealVector *into*.

The values in the returned vector will be the actual values intended for use in the evaluation functions.

Parameters:

from The Design class object from which to extract the continuous design variable values.

into The vector into which to place the extracted values.

10.50.3.6 void GetDiscreteVariableValues (const JEGA::Utilities::Design & *from*, IntVector & *into*) const
[protected]

Places the discrete Design variable values from Design *from* into IntVector *into*.

The values placed in the vector will be the values for the design variables as far as JEGA knows. However, in actuality, the values are the representations due to the way that [Dakota](#) manages discrete variables.

Parameters:

from The Design class object from which to extract the discrete design variable values.

into The vector into which to place the extracted values.

10.50.3.7 void SeparateVariables (const JEGA::Utilities::Design & *from*, IntVector & *intoDisc*, RealVector & *intoCont*) const [protected]

This method fills *intoDisc* and *intoCont* appropriately using the values of *from*.

The discrete design variable values are placed in *intoDisc* and the continuum are placed into *intoCont*.

It is more efficient to use this method than to use GetDiscreteVariableValues and GetContinuumVariableValues separately if you want both.

Parameters:

from The Design class object from which to extract the discrete design variable values.

intoDisc The vector into which to place the extracted discrete values.

intoCont The vector into which to place the extracted continuous values.

10.50.3.8 void RecordResponses (const RealVector & *from*, JEGA::Utilities::Design & *into*) const [protected]

Records the computed objective and constraint function values into *into*.

This method takes the response values stored in *from* and properly transfers them into the *into* design.

The response vector *from* is expected to contain values for each objective function followed by values for each non-linear constraint in the order in which the info objects were loaded into the target by the optimizer class.

Parameters:

from The vector of responses to install into *into*.

into The Design to which the responses belong and into which they must be written.

10.50.3.9 size_t GetNumberNonLinearConstraints () const [protected]

Returns the number of non-linear constraints for the problem.

This is computed by adding the number of non-linear equality constraints to the number of non-linear inequality constraints. These values are obtained from the model.

Returns:

The total number of non-linear constraints.

10.50.3.10 size_t GetNumberLinearConstraints () const [protected]

Returns the number of linear constraints for the problem.

This is computed by adding the number of linear equality constraints to the number of linear inequality constraints. These values are obtained from the model.

Returns:

The total number of linear constraints.

10.50.3.11 virtual bool Evaluate (JEGA::Utilities::DesignGroup & group) [virtual]

Does evaluation of each design in "group".

This method uses the [Model](#) known by this class to get Designs evaluated. It properly formats the Design class information in a way that [Dakota](#) will understand and then interprets the [Dakota](#) results and puts them back into the Design class object. It respects the asynchronous flag in the [Model](#) so evaluations may occur synchronously or asynchronously.

Prior to evaluating a Design, this class checks to see if it is marked as already evaluated. If it is, then the evaluation of that Design is not carried out. This is not strictly necessary because [Dakota](#) keeps track of evaluated designs and does not re-evaluate. An exception is the case of a population read in from a file complete with responses where [Dakota](#) is unaware of the evaluations.

Parameters:

group The group of Design class objects to be evaluated.

Returns:

true if all evaluations completed and false otherwise.

10.50.3.12 virtual bool Evaluate (JEGA::Utilities::Design & des) [virtual]

This method cannot be used!!

This method does nothing and cannot be called. This is because in the case of asynchronous evaluation, this method would be unable to conform. It would require that each evaluation be done in a synchronous fashion.

Parameters:

des A Design that would be evaluated if this method worked.

Returns:

Would return true if the Design were evaluated and false otherwise.

10.50.3.13 string GetName () const [virtual]

Returns the proper name of this operator.

Returns:

See [Name\(\)](#).

10.50.3.14 `string GetDescription () const [virtual]`

Returns a full description of what this operator does and how.

Returns:

See [Description\(\)](#).

10.50.3.15 `virtual GeneticAlgorithmOperator* Clone (JEGA::Algorithms::GeneticAlgorithm & algorithm) const [virtual]`

Creates and returns a pointer to an exact duplicate of this operator.

Parameters:

algorithm The GA for which the clone is being created.

Returns:

A clone of this operator.

10.50.4 Member Data Documentation**10.50.4.1** `Model& _model [private]`

The [Model](#) known by this evaluator.

It is through this model that evaluations will take place.

10.50.4.2 `JEGAOptimizer& _theOptimizer [private]`

The [JEGAOptimizer](#) that created this evaluator.

This instance is used to access certain needed functions from the optimizer class such as those methods that do variable scaling.

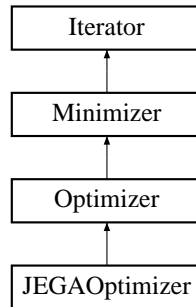
The documentation for this class was generated from the following files:

- [JEGAEvaluator.H](#)
- [JEGAEvaluator.C](#)

10.51 JEGAOptimizer Class Reference

Version of [Optimizer](#) for instantiation of John Eddy's Genetic Algorithms.

Inheritance diagram for JEGAOptimizer::



Public Member Functions

- virtual void [find_optimum](#) ()
Performs the iterations to determine the optimal set of solutions.
- [JEGAOptimizer](#) ([Model](#) &model)
Constructs a [JEGAOptimizer](#) class object.
- [~JEGAOptimizer](#) ()
Destructs a [JEGAOptimizer](#).

Protected Member Functions

- void [ReCreateTheAlgorithmConfig](#) ()
Destroys the existing algorithm configuration and creates a new one.
- void [ReCreateTheProblemConfig](#) ()
Destroys the existing problem configuration and creates a new one.
- void [LoadTheAlgorithmConfig](#) ()
Completely initializes or re-initializes the algorithm configuration.
- void [LoadTheProblemConfig](#) ()
Completely initializes or re-initializes the problem configuration.

- void [LoadTheDesignVariables](#) ()
Adds DesignVariableInfo objects into the problem configuration object.
- void [LoadTheObjectiveFunctions](#) ()
Adds ObjectiveFunctionInfo objects into the problem configuration object.
- void [LoadTheConstraints](#) ()
Adds ConstraintInfo objects into the problem configuration object.
- const JEGA::Utilities::Design * [GetBestSolution](#) (const JEGA::Utilities::DesignOFSortSet &from)
Chooses the best Design from a set of solutions taking into account the algorithm type.
- const JEGA::Utilities::Design * [GetBestMOSolution](#) (const JEGA::Utilities::DesignOFSortSet &from)
Chooses the best Design from a set of solutions assuming that they are generated by a multi objective algorithm.
- const JEGA::Utilities::Design * [GetBestSOSolution](#) (const JEGA::Utilities::DesignOFSortSet &from)
Chooses the best Design from a set of solutions assuming that they are generated by a single objective algorithm.

Private Attributes

- [EvalCreator](#) * [_theEvalCreator](#)
A pointer to an EvaluatorCreator used to create the evaluator used by JEGA in [Dakota](#) (a [JEGAEvaluator](#)).
- JEGA::FrontEnd::ProblemConfig * [_theProbConfig](#)
A pointer to the problem configuration loaded by this optimizer at each call to [find_optimum](#) and passed to the JEGA Driver.
- JEGA::FrontEnd::AlgorithmConfig * [_theAlgConfig](#)
A pointer to the algorithm configuration loaded by this optimizer at each call to [find_optimum](#) and passed to the JEGA Driver.
- [JEGAProbDescDB](#) * [_theProbDB](#)
A pointer to the [JEGAProbDescDB](#) that wraps the [Dakota::ProblemDescDB](#) and from which all parameters are retrieved by the created algorithms.

Static Private Attributes

- static const std::string [_sogaMethodText](#)
The text that indicates the SOGA method.
- static const std::string [_mogaMethodText](#)
The text that indicates the MOGA method.

Friends

- class [JEGAEvaluator](#)

The [JEGAEvaluator](#) is a friend so that it can access the methods of the [Minimizer](#) base class of the [JEGAOptimizer](#) necessary to do variable scaling.

Classes

- class [EvalCreator](#)

A specialization of the [JEGA::FrontEnd::EvaluatorCreator](#) that creates a new instance of a [JEGAEvaluator](#).

- class [JEGAProbDescDB](#)

A specialization of the [JEGA::Utilities::ParameterDatabase](#) that wraps and retrieves data from a [Dakota::ProblemDescDB](#).

10.51.1 Detailed Description

Version of [Optimizer](#) for instantiation of John Eddy's Genetic Algorithms.

This class encapsulates the necessary functionality for creating and properly initializing a GeneticAlgorithm.

10.51.2 Constructor & Destructor Documentation

10.51.2.1 [JEGAOptimizer](#) (**Model** & *model*)

Constructs a [JEGAOptimizer](#) class object.

This method does some of the initialization work for the algorithm. In particular, it initialized the JEGA core.

Parameters:

model The [Dakota::Model](#) that will be used by this optimizer for problem information, etc.

10.51.3 Member Function Documentation

10.51.3.1 `void ReCreateTheAlgorithmConfig ()` [protected]

Destroys the existing algorithm configuration and creates a new one.

A usable evaluator creator must already exist prior to calling this method. The parameter database will be destroyed and re-created in order to implement this method. As a result, the parameter data in the underlying [ProblemDescDB](#) will remain unchanged but any additional data will be gone.

10.51.3.2 void ReCreateTheProblemConfig () [protected]

Destroys the existing problem configuration and creates a new one.
The newly created problem configuration will be completely empty.

10.51.3.3 void LoadTheAlgorithmConfig () [protected]

Completely initializes or re-initializes the algorithm configuration.
This first uses the ReCreateTheAlgorithmConfig method and then loads the fresh configuration object with appropriate data retrieved from the parameter database.

10.51.3.4 void LoadTheProblemConfig () [protected]

Completely initializes or re-initializes the problem configuration.
This first uses the ReCreateTheProblemConfig method and then loads the fresh configuration object using the LoadTheDesignVariables, LoadTheObjectiveFunctions, and LoadTheConstraints methods.

10.51.3.5 void LoadTheDesignVariables () [protected]

Adds DesignVariableInfo objects into the problem configuration object.
This retrieves design variable information from the ParameterDatabase and creates DesignVariableInfo's from it.

10.51.3.6 void LoadTheObjectiveFunctions () [protected]

Adds ObjectiveFunctionInfo objects into the problem configuration object.
This retrieves objective function information from the ParameterDatabase and creates ObjectiveFunctionInfo's from it.

10.51.3.7 void LoadTheConstraints () [protected]

Adds ConstraintInfo objects into the problem configuration object.
This retrieves constraint function information from the ParameterDatabase and creates ConstraintInfo's from it.

10.51.3.8 const JEGA::Utilities::Design* GetBestSolution (const JEGA::Utilities::DesignOFSortSet & *from*) [protected]

Chooses the best Design from a set of solutions taking into account the algorithm type.
eventually this functionality must be moved into a separate post-processing application for MO datasets.

10.51.3.9 `const JEGA::Utilities::Design* GetBestMOSolution (const JEGA::Utilities::DesignOFSortSet & from)` [protected]

Chooses the best Design from a set of solutions assuming that they are generated by a multi objective algorithm. eventually this functionality must be moved into a separate post-processing application for MO datasets.

10.51.3.10 `const JEGA::Utilities::Design* GetBestSOSolution (const JEGA::Utilities::DesignOFSortSet & from)` [protected]

Chooses the best Design from a set of solutions assuming that they are generated by a single objective algorithm. eventually this functionality must be moved into a separate post-processing application for MO datasets.

10.51.3.11 `void find_optimum ()` [virtual]

Performs the iterations to determine the optimal set of solutions.

Override of pure virtual method in [Optimizer](#) base class.

Implements [Optimizer](#).

The documentation for this class was generated from the following files:

- [JEGAOptimizer.H](#)
- [JEGAOptimizer.C](#)

10.52 JEGAOptimizer::EvalCreator Class Reference

A specialization of the JEGA::FrontEnd::EvaluatorCreator that creates a new instance of a [JEGAEvaluator](#).

Public Member Functions

- virtual JEGA::Algorithms::GeneticAlgorithmEvaluator * [CreateEvaluator](#) (JEGA::Algorithms::GeneticAlgorithm &alg)
Overriden to return a newly created [JEGAEvaluator](#).
- [EvalCreator](#) (Model &theModel, JEGAOptimizer &theOptimizer)
Constructs an [EvalCreator](#) using the supplied model and optimizer.

Private Attributes

- [JEGAOptimizer](#) & [_theOptimizer](#)
The optimizer instance to be passed to the constructor of the [JEGAEvaluator](#).
- [Model](#) & [_theModel](#)
The user defined model to be passed to the constructor of the [JEGAEvaluator](#).

10.52.1 Detailed Description

A specialization of the JEGA::FrontEnd::EvaluatorCreator that creates a new instance of a [JEGAEvaluator](#).

10.52.2 Constructor & Destructor Documentation

10.52.2.1 [EvalCreator](#) (Model & theModel, JEGAOptimizer & theOptimizer)

Constructs an [EvalCreator](#) using the supplied model and optimizer.

Parameters:

theModel The [Dakota::Model](#) this creator will pass to the created evaluator.

theOptimizer The [JEGAOptimizer](#) this creator will pass to the created evaluator.

10.52.3 Member Function Documentation

10.52.3.1 virtual JEGA::Algorithms::GeneticAlgorithmEvaluator* CreateEvaluator (JEGA::Algorithms::GeneticAlgorithm & *alg*) [virtual]

Overriden to return a newly created [JEGAEvaluator](#).

The GA will assume ownership of the evaluator so we needn't worry about keeping track of it for destruction. The additional parameters needed by the [JEGAEvaluator](#) are stored as members of this class at construction time.

Parameters:

alg The GA for which the evaluator is to be created.

Returns:

A pointer to a newly created Evaluator.

The documentation for this class was generated from the following file:

- [JEGAOptimizer.C](#)

10.53 JEGAOptimizer::JEGAProbDescDB Class Reference

A specialization of the JEGA::Utilities::ParameterDatabase that wraps and retrieves data from a [Dakota::ProblemDescDB](#).

Public Member Functions

- virtual int [GetIntegral](#) (const std::string &tag) const
Overridden to supply the requested parameter as an integer from this DB.
- virtual double [GetDouble](#) (const std::string &tag) const
Overridden to supply the requested parameter as a double from this DB.
- virtual std::size_t [GetSizeType](#) (const std::string &tag) const
Overridden to supply the requested parameter as a size_t from this DB.
- virtual bool [GetBoolean](#) (const std::string &tag) const
Overridden to supply the requested parameter as a bool from this DB.
- virtual std::string [GetString](#) (const std::string &tag) const
Overridden to supply the requested parameter as a string from this DB.
- virtual JEGA::DoubleVector [GetDoubleVector](#) (const std::string &tag) const
Overridden to supply the requested parameter as a DoubleVector from this DB.
- virtual JEGA::IntVector [GetIntVector](#) (const std::string &tag) const
Overridden to supply the requested parameter as an IntVector from this DB.
- virtual JEGA::DoubleMatrix [GetDoubleMatrix](#) (const std::string &tag) const
Overridden to supply the requested parameter as a DoubleMatrix from this DB.
- virtual JEGA::IntList [GetIntList](#) (const std::string &tag) const
Overridden to supply the requested parameter as an IntList from this DB.
- virtual JEGA::StringVector [GetStringVector](#) (const std::string &tag) const
Overridden to supply the requested parameter as a StringVector from this DB.
- virtual JEGA::StringList [GetStringList](#) (const std::string &tag) const
Overridden to supply the requested parameter as a StringList from this DB.
- virtual std::string [Dump](#) () const
Prints the contents of the entire database into a string and return it.

- virtual void [Dump](#) (std::ostream &stream) const
Prints the contents of the entire database into the supplied output stream.
- [JEGAProbDescDB](#) (const [ProblemDescDB](#) &wrapped)
Constructs a [JEGAProbDescDB](#) to wrap wrapped.

Private Attributes

- const [ProblemDescDB](#) & [_wrapped](#)
The Dakota::ProblemDescription database from which the actual data is obtained.

10.53.1 Detailed Description

A specialization of the [JEGA::Utilities::ParameterDatabase](#) that wraps and retrieves data from a [Dakota::ProblemDescDB](#).

10.53.2 Constructor & Destructor Documentation

10.53.2.1 [JEGAProbDescDB](#) (const [ProblemDescDB](#) & *wrapped*)

Constructs a [JEGAProbDescDB](#) to wrap *wrapped*.

Parameters:

wrapped The existing [ProblemDescDB](#) from which otherwise unknown parameter values are retrieved.

10.53.3 Member Function Documentation

10.53.3.1 `int GetIntegral (const std::string & tag) const` [virtual]

Overridden to supply the requested parameter as an integer from this DB.

Parameters:

tag The key by which the requested value is to be retrieved.

10.53.3.2 double GetDouble (const std::string & tag) const [virtual]

Overridden to supply the requested parameter as a double from this DB.

Parameters:

tag The key by which the requested value is to be retrieved.

10.53.3.3 size_t GetSizeType (const std::string & tag) const [virtual]

Overridden to supply the requested parameter as a size_t from this DB.

Parameters:

tag The key by which the requested value is to be retrieved.

10.53.3.4 bool GetBoolean (const std::string & tag) const [virtual]

Overridden to supply the requested parameter as a bool from this DB.

Parameters:

tag The key by which the requested value is to be retrieved.

10.53.3.5 string GetString (const std::string & tag) const [virtual]

Overridden to supply the requested parameter as a string from this DB.

Parameters:

tag The key by which the requested value is to be retrieved.

10.53.3.6 JEGA::DoubleVector GetDoubleVector (const std::string & tag) const [virtual]

Overridden to supply the requested parameter as a DoubleVector from this DB.

Parameters:

tag The key by which the requested value is to be retrieved.

10.53.3.7 JEGA::IntVector GetIntVector (const std::string & tag) const [virtual]

Overridden to supply the requested parameter as an IntVector from this DB.

Parameters:

tag The key by which the requested value is to be retrieved.

10.53.3.8 JEGA::DoubleMatrix GetDoubleMatrix (const std::string & tag) const [virtual]

Overridden to supply the requested parameter as a DoubleMatrix from this DB.

Parameters:

tag The key by which the requested value is to be retrieved.

10.53.3.9 JEGA::IntList GetIntList (const std::string & tag) const [virtual]

Overridden to supply the requested parameter as an IntList from this DB.

Parameters:

tag The key by which the requested value is to be retrieved.

10.53.3.10 JEGA::StringVector GetStringVector (const std::string & tag) const [virtual]

Overridden to supply the requested parameter as a StringVector from this DB.

Parameters:

tag The key by which the requested value is to be retrieved.

10.53.3.11 JEGA::StringList GetStringList (const std::string & tag) const [virtual]

Overridden to supply the requested parameter as a StringList from this DB.

Parameters:

tag The key by which the requested value is to be retrieved.

10.53.3.12 `string Dump () const` [virtual]

Prints the contents of the entire database into a string and return it.

This method cannot be implemented by this class and thus does nothing.

Returns:

The entire contents of the database in a string.

10.53.3.13 `void Dump (std::ostream & stream) const` [virtual]

Prints the contents of the entire database into the supplied output stream.

This method cannot be implemented by this class and thus does nothing.

Parameters:

stream The stream into which to write the contents of this database.

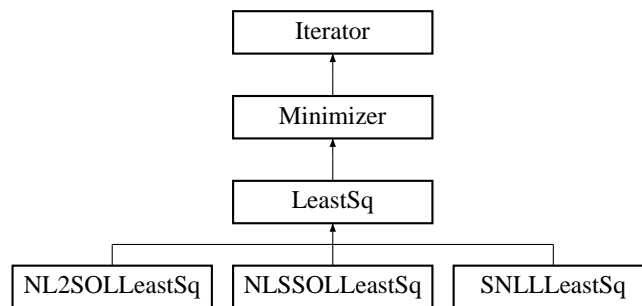
The documentation for this class was generated from the following file:

- [JEGAOptimizer.C](#)

10.54 LeastSq Class Reference

Base class for the nonlinear least squares branch of the iterator hierarchy.

Inheritance diagram for LeastSq:



Protected Member Functions

- [LeastSq \(\)](#)
default constructor
- [LeastSq \(Model &model\)](#)
standard constructor
- [~LeastSq \(\)](#)
destructor
- void [run \(\)](#)
run the iterator; portion of [run_iterator\(\)](#)
- void [print_results](#) (ostream &s) const
- void [derived_initialize_scaling](#) ()
provides derived class-specific portions of scaling initialization since [Optimizer](#) and [LeastSq](#) iterators have obj fn. and residual scales, respectively
- virtual void [minimize_residuals](#) ()=0
Used within the least squares branch for minimizing the sum of squares residuals. Redefines the [run_iterator](#) virtual function for the least squares branch.

Protected Attributes

- int `numLeastSqTerms`
number of least squares terms

10.54.1 Detailed Description

Base class for the nonlinear least squares branch of the iterator hierarchy.

The `LeastSq` class provides common data and functionality for `NLSSOLLeastSq` and `SNLLLeastSq`.

10.54.2 Constructor & Destructor Documentation

10.54.2.1 `LeastSq (Model & model)` [protected]

standard constructor

This constructor extracts the inherited data for the least squares branch and performs sanity checking on gradient and constraint settings.

10.54.3 Member Function Documentation

10.54.3.1 `void run ()` [inline, protected, virtual]

run the iterator; portion of `run_iterator()`

`Iterator` supports a construct/pre-run/run/post-run/destroy progression. This function is the virtual run function for the iterator class hierarchy. All derived classes need to redefine it.

Reimplemented from `Iterator`.

10.54.3.2 `void print_results (ostream & s) const` [protected, virtual]

Redefines default iterator results printing to include nonlinear least squares results (residual terms and constraints).

Reimplemented from `Iterator`.

The documentation for this class was generated from the following files:

- `DakotaLeastSq.H`
- `DakotaLeastSq.C`

10.55 List Class Template Reference

Template class for the [Dakota](#) bookkeeping list.

Public Member Functions

- [List](#) ()
Default constructor.
- [List](#) (const [List](#)< T > &a)
Copy constructor.
- [~List](#) ()
Destructor.
- [template](#)<class InputIter> [List](#) (InputIter first, InputIter last)
Range constructor (member template).
- [List](#)< T > & [operator=](#) (const [List](#)< T > &a)
assignment operator
- void [write](#) (ostream &s) const
Writes a [List](#) to an output stream.
- void [read](#) ([MPIUnpackBuffer](#) &s)
Reads a [List](#) from an [MPIUnpackBuffer](#) after an MPI receive.
- void [write](#) ([MPIPackBuffer](#) &s) const
Writes a [List](#) to a [MPIPackBuffer](#) prior to an MPI send.
- size_t [entries](#) () const
Returns the number of items that are currently in the list.
- T [get](#) ()
Removes and returns the first item in the list.
- T [removeAt](#) (size_t index)
Removes and returns the item at the specified index.
- bool [remove](#) (const T &a)
Removes the specified item from the list.

- void `insert` (const T &a)
Adds the item a to the end of the list.
- bool `contains` (const T &a) const
Returns TRUE if list contains object a, returns FALSE otherwise.
- bool `find` (bool(*test_fn)(const T &, const void *), const void *test_fn_data, T &found_item) const
Returns TRUE if the list contains an object that the user defined function finds and sets k to this object.
- `List< T >::iterator find` (bool(*test_fn)(const T &, const void *), const void *test_fn_data)
Returns an iterator pointing to an object that the user defined function finds.
- size_t `index` (bool(*test_fn)(const T &, const void *), const void *test_fn_data) const
Returns the index of object that the user defined test function finds.
- void `sort` (bool(*sort_fn)(const T &, const T &))
Sorts the list into an order based on the predefined sort function.
- size_t `index` (const T &a) const
Returns the index of the object.
- size_t `count` (const T &a) const
Returns the number of items in the list equal to object.
- T & `operator[]` (size_t i)
Returns the object at index i (can use as lvalue).
- const T & `operator[]` (size_t i) const
Returns the object at index i, const (can't use as lvalue).

10.55.1 Detailed Description

template<class T> class Dakota::List< T >

Template class for the [Dakota](#) bookkeeping list.

The `List` is the common list class for [Dakota](#). It inherits from either the RW list class or the STL list class. Extends the base list class to add [Dakota](#) specific methods Builds upon the previously existing `DakotaValList` class

10.55.2 Member Function Documentation

10.55.2.1 T get ()

Removes and returns the first item in the list.

Remove and return item from front of list. Returns the object pointed to by the `list::begin()` iterator. It also deletes the first node by calling the `list::pop_front()` method. Note: `get()` is not the same as `list::front()` since the latter would return the 1st item but would not delete it.

10.55.2.2 T removeAt (size_t index)

Removes and returns the item at the specified index.

Removes the item at the index specified. Uses the STL `advance()` function to step to the appropriate position in the list and then calls the `list::erase()` method.

10.55.2.3 bool remove (const T & a)

Removes the specified item from the list.

Removes the first instance matching object `a` from the list (and therefore differs from the STL `list::remove()` which removes all instances). Uses the STL `find()` algorithm to find the object and the `list::erase()` method to perform the remove.

10.55.2.4 void insert (const T & a) [inline]

Adds the item `a` to the end of the list.

Insert item at end of list, calls `list::push_back()` method.

10.55.2.5 bool contains (const T & a) const [inline]

Returns TRUE if list contains object `a`, returns FALSE otherwise.

Uses the STL `find()` algorithm to locate the first instance of object `a`. Returns true if an instance is found.

10.55.2.6 bool find (bool(*)(const T &, const void *) test_fn, const void * test_fn_data, T & found_item) const

Returns TRUE if the list contains an object that the user defined function finds and sets `k` to this object.

Find the first item in the list which satisfies the test function. Sets `k` if the object is found.

10.55.2.7 List< T >::iterator find (bool(*)(const T &, const void *) test_fn, const void * test_fn_data)

Returns an iterator pointing to an object that the user defined function finds.

Find the first item in the list which satisfies the test function and return an iterator pointing to it.

10.55.2.8 `size_t` `index (bool (*)(const T &, const void *) test_fn, const void * test_fn_data) const`

Returns the index of object that the user defined test function finds.

Returns the index of the first item in the list which satisfies the test function. Uses a single list traversal to both locate the object and return its index (generic algorithms would require two loop traversals).

10.55.2.9 `void` `sort (bool (*)(const T &, const T &) sort_fn) [inline]`

Sorts the list into an order based on the predefined sort function.

The sort method utilizes the [SortCompare](#) functor and the base class `list::sort` algorithm to sort a list based on the incoming sorting function `sort_fn`. Note that the functor-based sorting method of `std::list` is not supported by all compilers (e.g., SOLARIS, TFLOP) due to use of member templates, but a function pointer-based interface is available in some cases.

10.55.2.10 `size_t` `index (const T & a) const`

Returns the index of the object.

Returns the index of the first item in the list which matches the object `a`. Uses a single list traversal to both locate the object and return its index (generic algorithms would require two loop traversals).

10.55.2.11 `size_t` `count (const T & a) const [inline]`

Returns the number of items in the list equal to object.

Uses the STL `count()` algorithm to return the number of occurrences of the specified object.

10.55.2.12 `]`

`T & operator[] (size_t i)`

Returns the object at index `i` (can use as lvalue).

Returns item at position `i` of the list by stepping through the list using forward or reverse STL iterators (depending on which end of the list is closer to the desired item). Once the object is found, it returns the value pointed to by the iterator.

This functionality is inefficient in `0->len` loop-based list traversals and is being replaced by iterator-based list traversals in the main DAKOTA code. For isolated look-ups of a particular index, however, this approach is acceptable.

10.55.2.13 `]`

`const T & operator[] (size_t i) const`

Returns the object at index `i`, `const` (can't use as lvalue).

Returns const item at position *i* of the list by stepping through the list using forward or reverse STL iterators (depending on which end of the list is closer to the desired item). Once the object is found it returns the value pointed to by the iterator.

This functionality is inefficient in 0->len loop-based list traversals and is being replaced by iterator-based list traversals in the main DAKOTA code. For isolated look-ups of a particular index, however, this approach is acceptable.

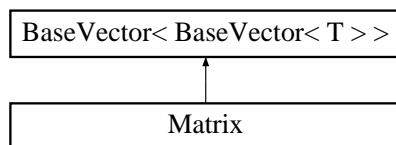
The documentation for this class was generated from the following file:

- DakotaList.H

10.56 Matrix Class Template Reference

Template class for the [Dakota](#) numerical matrix.

Inheritance diagram for Matrix::



Public Member Functions

- [Matrix](#) (size_t num_rows=0, size_t num_cols=0)
Constructor, takes number of rows, and number of columns as arguments.
- [~Matrix](#) ()
Destructor.
- [Matrix< T > & operator=](#) (const T &ival)
Sets all elements in the matrix to ival.
- size_t [num_rows](#) () const
Returns the number of rows for the matrix.
- size_t [num_columns](#) () const
Returns the number of columns for the matrix.
- void [reshape_2d](#) (size_t num_rows, size_t num_cols)
Resizes the matrix to num_rows by num_cols.
- void [read](#) (istream &s, size_t nr, size_t nc)
Reads a portion of the [Matrix](#) from an input stream.
- void [read](#) (istream &s)
Reads the complete [Matrix](#) from an input stream.
- void [read_row_vector](#) (istream &s, size_t i, size_t nc)
*Reads a portion of the *ith* [Matrix](#) row vector from an input stream.*
- void [read_row_vector](#) (istream &s, size_t i)
*Reads the *ith* [Matrix](#) row vector from an input stream.*

- void `write` (ostream &s, size_t nr, size_t nc, bool brackets, bool row_rtn, bool final_rtn) const
Writes a portion of the `Matrix` to an output stream.
- void `write` (ostream &s, bool brackets, bool row_rtn, bool final_rtn) const
Writes the complete `Matrix` to an output stream.
- void `write_row_vector` (ostream &s, size_t i, size_t nc, bool brackets, bool break_line, bool final_rtn) const
Writes a portion of the `i`th `Matrix` row vector to an output stream.
- void `write_row_vector` (ostream &s, size_t i, bool brackets, bool break_line, bool final_rtn) const
Writes the `i`th `Matrix` row vector to an output stream.
- void `read` (BiStream &s, size_t nr, size_t nc)
Reads a portion of the `Matrix` from a binary input stream.
- void `read` (BiStream &s)
Reads the complete `Matrix` from a binary input stream.
- void `read_row_vector` (BiStream &s, size_t i, size_t nc)
Reads a portion of the `i`th `Matrix` row vector from a binary input stream.
- void `read_row_vector` (BiStream &s, size_t i)
Reads the `i`th `Matrix` row vector from a binary input stream.
- void `write` (BoStream &s, size_t nr, size_t nc) const
Writes a portion of the `Matrix` to a binary output stream.
- void `write` (BoStream &s) const
Writes the complete `Matrix` to a binary output stream.
- void `write_row_vector` (BoStream &s, size_t i, size_t nc) const
Writes a portion of the `i`th `Matrix` row vector to a binary output stream.
- void `write_row_vector` (BoStream &s, size_t i) const
Writes the `i`th `Matrix` row vector to a binary output stream.
- void `read` (MPIUnpackBuffer &s)
Reads a `Matrix` from an `MPIUnpackBuffer` after an MPI receive.
- void `read_annotated` (MPIUnpackBuffer &s)
Reads an annotated `Matrix` from an `MPIUnpackBuffer` after an MPI receive.
- void `read_row_vector` (MPIUnpackBuffer &s, size_t i)
Reads the `i`th `Matrix` row vector from an `MPIUnpackBuffer` after an MPI recv.

- void `write (MPIPackBuffer &s) const`
Writes a [Matrix](#) to a [MPIPackBuffer](#) prior to an MPI send.
- void `write_annotated (MPIPackBuffer &s) const`
Writes an annotated [Matrix](#) to a [MPIPackBuffer](#) prior to an MPI send.
- void `write_row_vector (MPIPackBuffer &s, size_t i) const`
*Writes the *i*th [Matrix](#) row vector to a [MPIPackBuffer](#) prior to an MPI send.*

10.56.1 Detailed Description

`template<class T> class Dakota::Matrix< T >`

Template class for the [Dakota](#) numerical matrix.

A matrix class template to provide 2D arrays of objects. The matrix is zero-based, rows: 0 to (numRows-1) and cols: 0 to (numColumns-1). The class supports overloading of the subscript operator allowing it to emulate a normal built-in 2D array type. [Matrix](#) relies on the [BaseVector](#) template class to manage any differences between underlying DAKOTA_BASE_VECTOR implementations (RW, STL, etc.).

10.56.2 Member Function Documentation

10.56.2.1 `Matrix< T > & operator=(const T & val) [inline]`

Sets all elements in the matrix to ival.

calls base class operator=(ival)

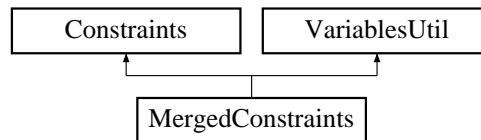
The documentation for this class was generated from the following file:

- `DakotaMatrix.H`

10.57 MergedConstraints Class Reference

Derived class within the [Constraints](#) hierarchy which employs the merged data view.

Inheritance diagram for MergedConstraints::



Public Member Functions

- [MergedConstraints](#) ()
default constructor
- [MergedConstraints](#) (const [ProblemDescDB](#) &problem_db, const pair< short, short > &view)
standard constructor
- [~MergedConstraints](#) ()
destructor
- const [RealVector](#) & [continuous_lower_bounds](#) () const
return the active continuous variable lower bounds
- void [continuous_lower_bounds](#) (const [RealVector](#) &c_l_bnds)
set the active continuous variable lower bounds
- const [RealVector](#) & [continuous_upper_bounds](#) () const
return the active continuous variable upper bounds
- void [continuous_upper_bounds](#) (const [RealVector](#) &c_u_bnds)
set the active continuous variable upper bounds
- const [RealVector](#) & [inactive_continuous_lower_bounds](#) () const
return the inactive continuous lower bounds
- void [inactive_continuous_lower_bounds](#) (const [RealVector](#) &i_c_l_bnds)
set the inactive continuous lower bounds
- const [RealVector](#) & [inactive_continuous_upper_bounds](#) () const
return the inactive continuous upper bounds

- void [inactive_continuous_upper_bounds](#) (const [RealVector](#) &i_c_u_bnds)
set the inactive continuous upper bounds
- [RealVector](#) [all_continuous_lower_bounds](#) () const
returns a single array with all continuous lower bounds
- [RealVector](#) [all_continuous_upper_bounds](#) () const
returns a single array with all continuous upper bounds
- void [write](#) (ostream &s) const
write a variable constraints object to an ostream
- void [read](#) (istream &s)
read a variable constraints object from an istream

Private Attributes

- [RealVector](#) [mergedDesignLowerBnds](#)
a design lower bounds array merging continuous and discrete domains (integer values promoted to reals)
- [RealVector](#) [mergedDesignUpperBnds](#)
a design upper bounds array merging continuous and discrete domains (integer values promoted to reals)
- [RealVector](#) [uncertainLowerBnds](#)
the uncertain distribution lower bounds array (no discrete uncertain to merge)
- [RealVector](#) [uncertainUpperBnds](#)
the uncertain distribution upper bounds array (no discrete uncertain to merge)
- [RealVector](#) [mergedStateLowerBnds](#)
a state lower bounds array merging continuous and discrete domains (integer values promoted to reals)
- [RealVector](#) [mergedStateUpperBnds](#)
a state upper bounds array merging continuous and discrete domains (integer values promoted to reals)

10.57.1 Detailed Description

Derived class within the [Constraints](#) hierarchy which employs the merged data view.

Derived variable constraints classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [MergedConstraints](#) derived class combines continuous and discrete domain types but separates design, uncertain, and state variable types. The result is merged design bounds

arrays (`mergedDesignLowerBnds`, `mergedDesignUpperBnds`), uncertain distribution bounds arrays (`uncertainLowerBnds`, `uncertainUpperBnds`), and merged state bounds arrays (`mergedStateLowerBnds`, `mergedStateUpperBnds`). The branch and bound strategy uses this approach (see `Variables::get_variables(problem_db)` for variables type selection; variables type is passed to the `Constraints` constructor in `Model`).

10.57.2 Constructor & Destructor Documentation

10.57.2.1 `MergedConstraints` (const `ProblemDescDB` & `problem_db`, const `pair< short, short >` & `view`)

standard constructor

In this class, a merged data approach is used in which continuous and discrete arrays are combined into a single continuous array (integrality is relaxed; the converse of truncating reals is not currently supported but could be in the future if needed). Iterators/strategies which use this class include: `BranchBndStrategy`. Extract fundamental lower and upper bounds and merge continuous and discrete domains to create `mergedDesignLowerBnds`, `mergedDesignUpperBnds`, `mergedStateLowerBnds`, and `mergedStateUpperBnds` using utilities from `VariablesUtil` (uncertain distribution bounds do not require any merging).

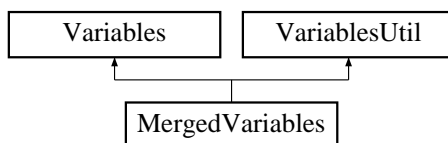
The documentation for this class was generated from the following files:

- `MergedConstraints.H`
- `MergedConstraints.C`

10.58 MergedVariables Class Reference

Derived class within the [Variables](#) hierarchy which employs the merged data view.

Inheritance diagram for MergedVariables::



Public Member Functions

- [MergedVariables](#) ()
default constructor
- [MergedVariables](#) (const [ProblemDescDB](#) &problem_db, const pair< short, short > &view)
standard constructor
- [~MergedVariables](#) ()
destructor
- size_t tv () const
Returns total number of vars.
- const [RealVector](#) & [continuous_variables](#) () const
return the active continuous variables
- void [continuous_variables](#) (const [RealVector](#) &c_vars)
set the active continuous variables
- const [StringArray](#) & [continuous_variable_labels](#) () const
return the active continuous variable labels
- void [continuous_variable_labels](#) (const [StringArray](#) &c_v_labels)
set the active continuous variable labels
- const [RealVector](#) & [inactive_continuous_variables](#) () const
return the inactive continuous variables
- void [inactive_continuous_variables](#) (const [RealVector](#) &i_c_vars)
set the inactive continuous variables

- const [StringArray](#) & [inactive_continuous_variable_labels](#) () const
return the inactive continuous variable labels
- void [inactive_continuous_variable_labels](#) (const [StringArray](#) &i_c_v_labels)
set the inactive continuous variable labels
- size_t [acv](#) () const
returns total number of continuous vars
- [RealVector](#) [all_continuous_variables](#) () const
returns a single array with all continuous variables
- void [all_continuous_variables](#) (const [RealVector](#) &a_c_vars)
sets all continuous variables using a single array
- [StringArray](#) [all_continuous_variable_labels](#) () const
returns a single array with all continuous variable labels
- [StringArray](#) [all_variable_labels](#) () const
returns a single array with all variable labels
- void [read](#) (istream &s)
read a variables object from an istream
- void [write](#) (ostream &s) const
write a variables object to an ostream
- void [write_aprepro](#) (ostream &s) const
write a variables object to an ostream in aprepro format
- void [read_annotated](#) (istream &s)
read a variables object in annotated format from an istream
- void [write_annotated](#) (ostream &s) const
write a variables object in annotated format to an ostream
- void [write_tabular](#) (ostream &s) const
write a variables object in tabular format to an ostream
- void [read](#) ([BiStream](#) &s)
read a variables object from the binary restart stream
- void [write](#) ([BoStream](#) &s) const
write a variables object to the binary restart stream

- void [read](#) ([MPIUnpackBuffer](#) &s)
read a variables object from a packed MPI buffer
- void [write](#) ([MPIPackBuffer](#) &s) const
write a variables object to a packed MPI buffer

Private Member Functions

- void [copy_rep](#) (const [Variables](#) *vars_rep)
Used by [copy\(\)](#) to copy the contents of a letter class.

Private Attributes

- [RealVector](#) [mergedDesignVars](#)
a design variables array merging continuous and discrete domains (integer values promoted to reals)
- [RealVector](#) [uncertainVars](#)
the uncertain variables array (no discrete uncertain to merge)
- [RealVector](#) [mergedStateVars](#)
a state variables array merging continuous and discrete domains (integer values promoted to reals)
- [StringArray](#) [mergedDesignLabels](#)
a label array combining continuous design and discrete design labels
- [StringArray](#) [uncertainLabels](#)
the uncertain variables label array (no discrete uncertain to combine)
- [StringArray](#) [mergedStateLabels](#)
a label array combining continuous state and discrete state labels

Friends

- bool [operator==](#) (const [MergedVariables](#) &vars1, const [MergedVariables](#) &vars2)
equality operator

10.58.1 Detailed Description

Derived class within the [Variables](#) hierarchy which employs the merged data view.

Derived variables classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [MergedVariables](#) derived class combines continuous and discrete domain types but separates design, uncertain, and state variable types. The result is a single continuous array of design variables (`mergedDesignVars`), a single continuous array of uncertain variables (`uncertainVars`), and a single continuous array of state variables (`mergedStateVars`). The branch and bound strategy uses this approach (see `Variables::get_variables(problem_db)`).

10.58.2 Constructor & Destructor Documentation

10.58.2.1 [MergedVariables](#) (`const ProblemDescDB & problem_db, const pair< short, short > & view)`

standard constructor

In this class, a merged data approach is used in which continuous and discrete arrays are combined into a single continuous array (integrality is relaxed; the converse of truncating reals is not currently supported but could be in the future if needed). Iterators/strategies which use this class include: `BranchBndStrategy`. Extract fundamental variable types and labels and merge continuous and discrete domains to create `mergedDesignVars`, `mergedStateVars`, `mergedDesignLabels`, and `mergedStateLabels` using utilities from [VariablesUtil](#) (uncertain variables and labels do not require any merging).

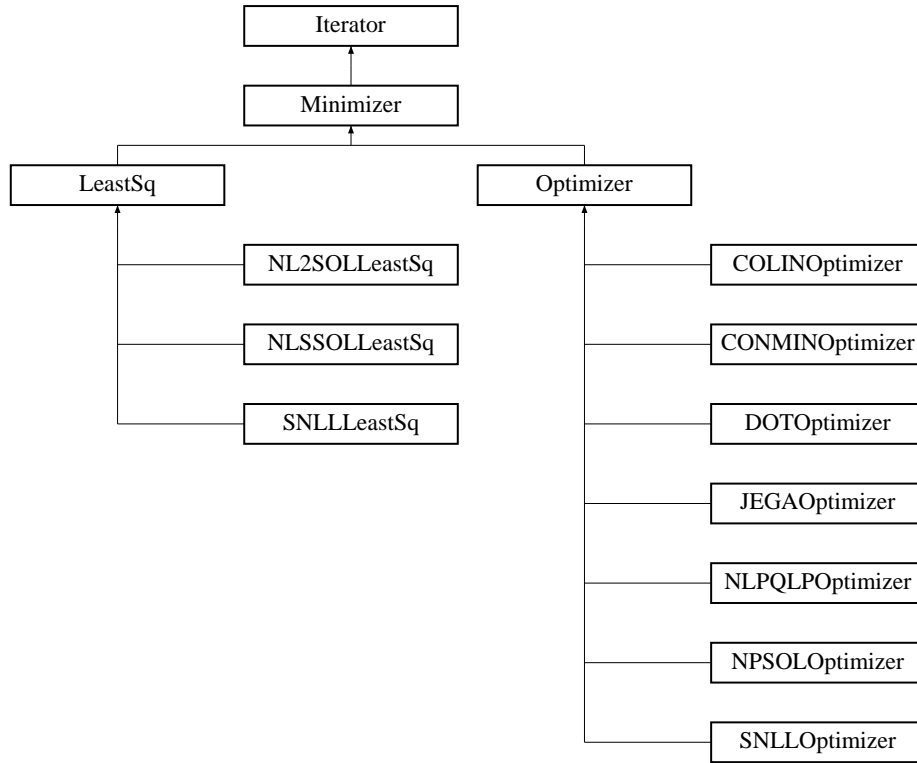
The documentation for this class was generated from the following files:

- `MergedVariables.H`
- `MergedVariables.C`

10.59 Minimizer Class Reference

Base class for the optimizer and least squares branches of the iterator hierarchy.

Inheritance diagram for Minimizer::



Public Member Functions

- `const Variables & variable_results () const`
return the final iterator solution (variables)
- `const Response & response_results () const`
return the final iterator solution (response)

Protected Member Functions

- `Minimizer ()`
default constructor

- [Minimizer](#) ([Model](#) &model)
standard constructor
- [Minimizer](#) ([NoDBBaseConstructor](#), size_t num_lin_ineq, size_t num_lin_eq, size_t num_nln_ineq, size_t num_nln_eq)
alternate constructor for "on the fly" instantiations
- [~Minimizer](#) ()
destructor
- void [response_results_active_set](#) (const [ActiveSet](#) &set)
set the requested data for the final iterator response results
- virtual void [derived_initialize_scaling](#) ()=0
provides derived class-specific portions of scaling initialization since [Optimizer](#) and [LeastSq](#) iterators have obj fn. and residual scales, respectively
- void [initialize_scaling](#) ()
helper function to initialize scaling multipliers and offsets
- [RealVector](#) [modify_n2s](#) (const [RealVector](#) &native_vars, const [RealVector](#) &multipliers, const [RealVector](#) &offsets) const
general mapping from native to scaled variables vectors: $scaled_vars = (native_vars - offsets)/multipliers$
- [RealVector](#) [cv_modify_n2s](#) (const [RealVector](#) &native_vars) const
map continuous variables from native to scaled
- [RealVector](#) [nln_ineq_modify_n2s](#) (const [RealVector](#) &native_vars) const
map nonlinear inequalities from native to scaled
- [RealVector](#) [nln_eq_modify_n2s](#) (const [RealVector](#) &native_vars) const
map nonlinear equalities from native to scaled
- [RealVector](#) [lin_ineq_modify_n2s](#) (const [RealVector](#) &native_vars) const
map linear inequalities from native to scaled
- [RealVector](#) [lin_eq_modify_n2s](#) (const [RealVector](#) &native_vars) const
map linear equalities from native to scaled
- [RealVector](#) [fns_modify_n2s](#) (const [RealVector](#) &native_fns) const
map functions (reponse vector) from native to scaled
- [RealMatrix](#) [lin_coeffs_modify_n2s](#) (const [RealMatrix](#) &native_coeffs, const [RealVector](#) &cv_multipliers, const [RealVector](#) &lin_multipliers) const
general linear coefficients mapping from native to scaled space

- [RealMatrix lin_ineq_coeffs_modify_n2s](#) (const [RealMatrix](#) &native_coeffs) const
map linear inequality constraint matrix from native to scaled
- [RealMatrix lin_eq_coeffs_modify_n2s](#) (const [RealMatrix](#) &native_coeffs) const
map linear equality constraint matrix from native to scaled
- [Response response_modify_n2s](#) (const [Response](#) &response_source) const
map responses from native to scaled variable space
- [RealVector modify_s2n](#) (const [RealVector](#) &scaled_vars, const [RealVector](#) &multipliers, const [RealVector](#) &offsets) const
*general RealVector mapping from native to scaled variables: native_vars = scaled_vars * multipliers + offsets*
- [RealVector cv_modify_s2n](#) (const [RealVector](#) &scaled_vars) const
map continuous variables from scaled to native
- [RealVector fns_modify_s2n](#) (const [RealVector](#) &scaled_fns) const
map functions (responses) from scaled to native
- void [adjust_user_scales](#) ([RealVector](#) &scales, const int length, const Real default_scale_factor)
expand and error check user-supplied scaling vectors before use in scaling framework
- void [compute_scale_factor](#) (const Real lower_bound, const Real upper_bound, Real *multiplier, Real *offset)
automatically compute scaling factor – bounds case
- void [compute_scale_factor](#) (const Real target, Real *multiplier)
automatically compute scaling factor – target case

Protected Attributes

- Real [constraintTol](#)
optimizer/least squares constraint tolerance
- Real [bigRealBoundSize](#)
cutoff value for inequality constraint and continuous variable bounds
- int [bigIntBoundSize](#)
cutoff value for discrete variable bounds
- size_t [numNonlinearIneqConstraints](#)
number of nonlinear inequality constraints
- size_t [numNonlinearEqConstraints](#)

- number of nonlinear equality constraints*
- `size_t numLinearIneqConstraints`
number of linear inequality constraints
- `size_t numLinearEqConstraints`
number of linear equality constraints
- `int numNonlinearConstraints`
total number of nonlinear constraints
- `int numLinearConstraints`
total number of linear constraints
- `int numConstraints`
total number of linear and nonlinear constraints
- `bool boundConstraintFlag`
convenience flag for denoting the presence of user-specified bound constraints. Used for method selection and error checking.
- `bool speculativeFlag`
flag for speculative gradient evaluations
- `bool scaleFlag`
flag indicating scaling status
- `RealVector cvScaleMultipliers`
scales for continuous variables
- `RealVector cvScaleOffsets`
offsets for continuous variables
- `RealVector fnScaleMultipliers`
scales for obj. fns. or LSQ terms
- `RealVector nonlinearIneqScaleMultipliers`
scales for nonlin. ineq.
- `RealVector nonlinearIneqScaleOffsets`
offsets for nonlin. ineq.
- `RealVector nonlinearEqScaleMultipliers`
scales for nonlin. eq.
- `RealVector nonlinearEqScaleOffsets`

offsets for nonlin. eq.

- [RealVector responseScaleMultipliers](#)
scales for ALL responses
- [RealVector responseScaleOffsets](#)
offsets for ALL responses (zero for functions, not for nonlin con)
- [RealVector linearIneqScaleMultipliers](#)
scales for linear ineq constrs.
- [RealVector linearIneqScaleOffsets](#)
offsets for linear ineq constrs.
- [RealVector linearEqScaleMultipliers](#)
scales for linear constraints
- [RealVector linearEqScaleOffsets](#)
offsets for linear constraints
- [bool vendorNumericalGradFlag](#)
convenience flag for gradType == numerical && methodSource == vendor
- [Variables bestVariables](#)
best variables found in solution
- [Response bestResponses](#)
best responses found in solution

Friends

- [class SOLBase](#)
the [SOLBase](#) class is not derived the iterator hierarchy but still needs access to iterator hierarchy data (to avoid attribute replication)
- [class SNLLBase](#)
the [SNLLBase](#) class is not derived the iterator hierarchy but still needs access to iterator hierarchy data (to avoid attribute replication)

10.59.1 Detailed Description

Base class for the optimizer and least squares branches of the iterator hierarchy.

The [Minimizer](#) class provides common data and functionality for [Optimizer](#) and [LeastSq](#).

10.59.2 Constructor & Destructor Documentation

10.59.2.1 **Minimizer** (*Model & model*) [protected]

standard constructor

This constructor extracts inherited data for the optimizer and least squares branches and performs sanity checking on constraint settings.

10.59.3 Member Function Documentation

10.59.3.1 **void initialize_scaling ()** [protected]

helper function to initialize scaling multipliers and offsets

helper function used in constructors of derived classes to set up scaling multipliers and offsets when input scaling flag is enabled includes call to the derived class' `derived_initialize_scaling()`

10.59.3.2 **RealMatrix lin_coeffs_modify_n2s (const RealMatrix & src_coeffs, const RealVector & cv_multipliers, const RealVector & lin_multipliers) const** [protected]

general linear coefficients mapping from native to scaled space

compute scaled linear constraint matrix given design variable multipliers and linear scaling multipliers. Only scales components corresponding to continuous variables so for `src_coeffs` of size $M \times N$, `lin_multipliers.size() <= M`, `cv_multipliers.size() <= N`

10.59.3.3 **Response response_modify_n2s (const Response & src_response) const** [protected]

map responses from native to scaled variable space

scaling forward mapping: modifies response from a model (native) for use in iterators (scaled) with scaling and `multi_objective` or building least squares terms – not including `multi_objective_modify`, since least squares methods do not use

10.59.3.4 **void adjust_user_scales (RealVector & scales, const int length, const Real default_scale_factor)** [protected]

expand and error check user-supplied scaling vectors before use in scaling framework

expand and error check user-specified scales vector if no scales: populate with `default_scale_factor` if only one scale factor: replicate to appropriate length

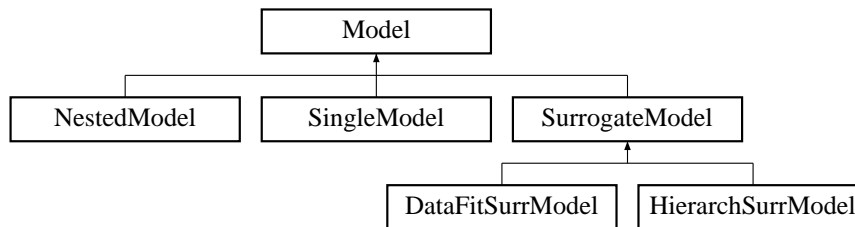
The documentation for this class was generated from the following files:

- `DakotaMinimizer.H`
- `DakotaMinimizer.C`

10.60 Model Class Reference

Base class for the model class hierarchy.

Inheritance diagram for Model::



Public Member Functions

- [Model](#) ()
default constructor
- [Model](#) ([ProblemDescDB](#) &problem_db)
standard constructor for envelope
- [Model](#) (const [Model](#) &model)
copy constructor
- virtual [~Model](#) ()
destructor
- [Model operator=](#) (const [Model](#) &model)
assignment operator
- virtual [Iterator](#) & [subordinate_iterator](#) ()
return the sub-iterator in nested and surrogate models
- virtual [Model](#) & [surrogate_model](#) ()
return the approximation sub-model in surrogate models
- virtual [Model](#) & [truth_model](#) ()
return the truth sub-model in surrogate models
- virtual void [derived_subordinate_models](#) ([ModelList](#) &ml, bool recurse_flag)
portion of [subordinate_models](#)() specific to derived model classes

- virtual `Interface & interface ()`
return the interface employed by the derived model class, if present: `SingleModel::userDefinedInterface`, `DataFitSurrModel::approxInterface`, or `NestedModel::optionalInterface`
- virtual void `surrogate_bypass (bool bypass_flag)`
deactivate/reactivate the approximations for any/all surrogate models contained within this model
- virtual void `build_approximation ()`
build a new approximation in `SurrogateModels`
- virtual bool `build_approximation (const RealVector &c_vars, const Response &response)`
build a new approximation in `SurrogateModels` using/enforcing response at `c_vars`
- virtual void `update_approximation (const RealVector &c_vars, const Response &response)`
update an existing approximation in `DataFitSurrModels` with new data
- virtual const `RealVectorArray & approximation_coefficients ()`
retrieve the approximation coefficients from each `Approximation` within a `DataFitSurrModel`
- virtual void `compute_correction (const Response &truth_response, const Response &approx_response, const RealVector &c_vars)`
compute correction factors for use in `SurrogateModels`
- virtual void `auto_correction (bool correction_flag)`
manages automatic application of correction factors in `SurrogateModels`
- virtual bool `auto_correction ()`
return flag indicating use of automatic correction within this model's responses
- virtual void `apply_correction (Response &approx_response, const RealVector &c_vars, bool quiet_flag=false)`
apply correction factors to `approx_response` (for use in `SurrogateModels`)
- virtual void `component_parallel_mode (int mode)`
update component parallel mode for supporting parallelism in a model's interface component, sub-model component, or neither component [`componentParallelMode = 0 (none)`, `1 (INTERFACE/LF_MODEL)`, or `2 (SUB_MODEL/HF_MODEL/TRUTH_MODEL)`].
- virtual `String local_eval_synchronization ()`
return derived model synchronization setting
- virtual int `local_eval_concurrency ()`
return derived model asynchronous evaluation concurrency
- virtual void `reset_communicators ()`

reset communicator partition data for a model

- virtual void `serve ()`
Service job requests received from the master. Completes when a termination message is received from `stop_servers()`.
- virtual void `stop_servers ()`
Executed by the master to terminate all server operations for a particular model when iteration on the model is complete.
- virtual bool `derived_master_overload () const`
Return a flag indicating the combination of multiprocessor evaluations and a dedicated master iterator scheduling. Used in synchronous `compute_response` functions to prevent the error of trying to run a multiprocessor job on the master.
- virtual int `evaluation_id () const`
Return the current function evaluation id for the `Model`.
- virtual void `set_evaluation_reference ()`
Set the reference points for the evaluation counters within the `Model`.
- virtual void `print_evaluation_summary (ostream &s, bool minimal_header=false, bool relative_count=true) const`
Print an evaluation summary for the `Model`.
- `ModelList & subordinate_models (bool recurse_flag=true)`
return the sub-models in nested and surrogate models
- void `compute_response ()`
Compute the `Response` at `currentVariables` (default `ActiveSet`).
- void `compute_response (const ActiveSet &set)`
Compute the `Response` at `currentVariables` (specified `ActiveSet`).
- void `asynch_compute_response ()`
Spawn an asynchronous job (or jobs) that computes the value of the `Response` at `currentVariables` (default `ActiveSet`).
- void `asynch_compute_response (const ActiveSet &set)`
Spawn an asynchronous job (or jobs) that computes the value of the `Response` at `currentVariables` (specified `ActiveSet`).
- const `ResponseArray & synchronize ()`
Execute a blocking scheduling algorithm to collect the complete set of results from a group of asynchronous evaluations.
- const `IntResponseMap & synchronize_nowait ()`

Execute a nonblocking scheduling algorithm to collect all available results from a group of asynchronous evaluations.

- void `init_communicators` (const int &max_iterator_concurrency)
allocate communicator partitions for a model and store configuration in modelPCIterMap
- void `init_serial` ()
for cases where `init_communicators()` will not be called, modify some default settings to behave properly in serial.
- void `set_communicators` (const int &max_iterator_concurrency)
set active parallel configuration for the model (set modelPCIter from modelPCIterMap)
- void `free_communicators` (const int &max_iterator_concurrency)
deallocate communicator partitions for a model
- void `estimate_message_lengths` ()
estimate messageLengths for a model
- void `assign_rep` (Model *model_rep, bool ref_count_incr=true)
replaces existing letter with a new one
- size_t `num_functions` () const
return number of functions in currentResponse
- size_t `tv` () const
return total number of vars
- size_t `cv` () const
return number of active continuous variables
- size_t `dv` () const
return number of active discrete variables
- void `active_variables` (const Variables &vars)
set the active variables in currentVariables
- const RealVector & `continuous_variables` () const
return the active continuous variables from currentVariables
- void `continuous_variables` (const RealVector &c_vars)
set the active continuous variables in currentVariables
- const IntVector & `discrete_variables` () const
return the active discrete variables from currentVariables
- void `discrete_variables` (const IntVector &d_vars)

set the active discrete variables in currentVariables

- `size_t icv () const`
return number of inactive continuous variables
- `size_t idv () const`
return number of inactive discrete variables
- `const RealVector & inactive_continuous_variables () const`
return the inactive continuous variables in currentVariables
- `void inactive_continuous_variables (const RealVector &i_c_vars)`
set the inactive continuous variables in currentVariables
- `const IntVector & inactive_discrete_variables () const`
return the inactive discrete variables in currentVariables
- `void inactive_discrete_variables (const IntVector &i_d_vars)`
set the inactive discrete variables in currentVariables
- `const RealVector & normal_means () const`
return the normal uncertain variable means
- `void normal_means (const RealVector &n_means)`
set the normal uncertain variable means
- `const RealVector & normal_std_deviations () const`
return the normal uncertain variable standard deviations
- `void normal_std_deviations (const RealVector &n_std_devs)`
set the normal uncertain variable standard deviations
- `const RealVector & normal_lower_bounds () const`
return the normal uncertain variable lower bounds
- `void normal_lower_bounds (const RealVector &n_lower_bnds)`
set the normal uncertain variable lower bounds
- `const RealVector & normal_upper_bounds () const`
return the normal uncertain variable upper bounds
- `void normal_upper_bounds (const RealVector &n_upper_bnds)`
set the normal uncertain variable upper bounds
- `const RealVector & lognormal_means () const`
return the lognormal uncertain variable means

- void `lognormal_means` (const `RealVector` &ln_means)
set the lognormal uncertain variable means
- const `RealVector` & `lognormal_std_deviations` () const
return the lognormal uncertain variable standard deviations
- void `lognormal_std_deviations` (const `RealVector` &ln_std_devs)
set the lognormal uncertain variable standard deviations
- const `RealVector` & `lognormal_error_factors` () const
return the lognormal uncertain variable error factors
- void `lognormal_error_factors` (const `RealVector` &ln_err_facts)
set the lognormal uncertain variable error factors
- const `RealVector` & `lognormal_lower_bounds` () const
return the lognormal uncertain variable lower bounds
- void `lognormal_lower_bounds` (const `RealVector` &ln_lower_bnds)
set the lognormal uncertain variable lower bounds
- const `RealVector` & `lognormal_upper_bounds` () const
return the lognormal uncertain variable upper bounds
- void `lognormal_upper_bounds` (const `RealVector` &ln_upper_bnds)
set the lognormal uncertain variable upper bounds
- const `RealVector` & `uniform_lower_bounds` () const
return the uniform uncertain variable lower bounds
- void `uniform_lower_bounds` (const `RealVector` &u_lower_bnds)
set the uniform uncertain variable lower bounds
- const `RealVector` & `uniform_upper_bounds` () const
return the uniform uncertain variable upper bounds
- void `uniform_upper_bounds` (const `RealVector` &u_upper_bnds)
set the uniform uncertain variable upper bounds
- const `RealVector` & `loguniform_lower_bounds` () const
return the loguniform uncertain variable lower bounds
- void `loguniform_lower_bounds` (const `RealVector` &lu_lower_bnds)
set the loguniform uncertain variable lower bounds

- `const RealVector & loguniform_upper_bounds () const`
return the loguniform uncertain variable upper bounds
- `void loguniform_upper_bounds (const RealVector &lu_upper_bnds)`
set the loguniform uncertain variable upper bounds
- `const RealVector & triangular_modes () const`
return the triangular uncertain variable modes
- `void triangular_modes (const RealVector &t_modes)`
set the triangular uncertain variable modes
- `const RealVector & triangular_lower_bounds () const`
return the triangular uncertain variable lower bounds
- `void triangular_lower_bounds (const RealVector &t_lower_bnds)`
set the triangular uncertain variable lower bounds
- `const RealVector & triangular_upper_bounds () const`
return the triangular uncertain variable upper bounds
- `void triangular_upper_bounds (const RealVector &t_upper_bnds)`
set the triangular uncertain variable upper bounds
- `const RealVector & beta_alphas () const`
return the beta uncertain variable alphas
- `void beta_alphas (const RealVector &b_alphas)`
set the beta uncertain variable alphas
- `const RealVector & beta_betas () const`
return the beta uncertain variable betas
- `void beta_betas (const RealVector &b_betas)`
set the beta uncertain variable betas
- `const RealVector & beta_lower_bounds () const`
return the beta uncertain variable lower bounds
- `void beta_lower_bounds (const RealVector &b_lower_bnds)`
set the beta uncertain variable lower bounds
- `const RealVector & beta_upper_bounds () const`
return the beta uncertain variable upper bounds
- `void beta_upper_bounds (const RealVector &b_upper_bnds)`

set the beta uncertain variable upper bounds

- `const RealVector & gamma_alphas () const`
return the gamma uncertain variable alpha parameters
- `void gamma_alphas (const RealVector &ga_alphas)`
set the gamma uncertain variable alpha parameters
- `const RealVector & gamma_betas () const`
return the gamma uncertain variable beta parameters
- `void gamma_betas (const RealVector &ga_betas)`
set the gamma uncertain variable beta parameters
- `const RealVector & gumbel_alphas () const`
return the gumbel uncertain variable alphas
- `void gumbel_alphas (const RealVector &gu_alphas)`
set the gumbel uncertain variable alphas
- `const RealVector & gumbel_betas () const`
return the gumbel uncertain variable betas
- `void gumbel_betas (const RealVector &gu_betas)`
set the gumbel uncertain variable betas
- `const RealVector & frechet_alphas () const`
return the frechet uncertain variable alpha parameters
- `void frechet_alphas (const RealVector &f_alphas)`
set the frechet uncertain variable alpha parameters
- `const RealVector & frechet_betas () const`
return the frechet uncertain variable beta parameters
- `void frechet_betas (const RealVector &f_betas)`
set the frechet uncertain variable beta parameters
- `const RealVector & weibull_alphas () const`
return the weibull uncertain variable alpha parameters
- `void weibull_alphas (const RealVector &w_alphas)`
set the weibull uncertain variable alpha parameters
- `const RealVector & weibull_betas () const`
return the weibull uncertain variable beta parameters

- void `weibull_betas` (const `RealVector` &w_betas)
set the weibull uncertain variable beta parameters
- const `RealVectorArray` & `histogram_bin_pairs` () const
return the histogram uncertain bin pairs
- void `histogram_bin_pairs` (const `RealVectorArray` &h_bin_pairs)
set the histogram uncertain bin pairs
- const `RealVectorArray` & `histogram_point_pairs` () const
return the histogram uncertain point pairs
- void `histogram_point_pairs` (const `RealVectorArray` &h_pt_pairs)
set the histogram uncertain point pairs
- const `IntVector` & `interval_num_intervals` () const
return the interval number of intervals per variable
- void `interval_num_intervals` (const `IntVector` &int_num_intvls)
set the interval number of intervals per variable
- const `RealVector` & `interval_probs` () const
return the interval probability values
- void `interval_probs` (const `RealVector` &int_probs)
set the interval probability values
- const `RealVector` & `interval_bounds` () const
return the interval bounds
- void `interval_bounds` (const `RealVector` &int_bounds)
set the interval probability values
- const `StringArray` & `continuous_variable_types` () const
return the active continuous variable types from currentVariables
- const `StringArray` & `discrete_variable_types` () const
return the active discrete variable types from currentVariables
- const `StringArray` & `continuous_variable_labels` () const
return the active continuous variable labels from currentVariables
- void `continuous_variable_labels` (const `StringArray` &c_v_labels)
set the active continuous variable labels in currentVariables

- const [StringArray](#) & [discrete_variable_labels](#) () const
return the active discrete variable labels from currentVariables
- void [discrete_variable_labels](#) (const [StringArray](#) &d_v_labels)
set the active discrete variable labels in currentVariables
- const [StringArray](#) & [inactive_continuous_variable_labels](#) () const
return the inactive continuous variable labels in currentVariables
- void [inactive_continuous_variable_labels](#) (const [StringArray](#) &i_c_v_labels)
set the inactive continuous variable labels in currentVariables
- const [StringArray](#) & [inactive_discrete_variable_labels](#) () const
return the inactive discrete variable labels in currentVariables
- void [inactive_discrete_variable_labels](#) (const [StringArray](#) &i_d_v_labels)
set the inactive discrete variable labels in currentVariables
- const [RealVector](#) & [continuous_lower_bounds](#) () const
return the active continuous variable lower bounds from userDefinedConstraints
- void [continuous_lower_bounds](#) (const [RealVector](#) &c_l_bnds)
set the active continuous variable lower bounds in userDefinedConstraints
- const [RealVector](#) & [continuous_upper_bounds](#) () const
return the active continuous variable upper bounds from userDefinedConstraints
- void [continuous_upper_bounds](#) (const [RealVector](#) &c_u_bnds)
set the active continuous variable upper bounds in userDefinedConstraints
- const [IntVector](#) & [discrete_lower_bounds](#) () const
return the active discrete variable lower bounds from userDefinedConstraints
- void [discrete_lower_bounds](#) (const [IntVector](#) &d_l_bnds)
set the active discrete variable lower bounds in userDefinedConstraints
- const [IntVector](#) & [discrete_upper_bounds](#) () const
return the active discrete variable upper bounds from userDefinedConstraints
- void [discrete_upper_bounds](#) (const [IntVector](#) &d_u_bnds)
set the active discrete variable upper bounds in userDefinedConstraints
- const [RealVector](#) & [inactive_continuous_lower_bounds](#) () const
return the inactive continuous lower bounds in userDefinedConstraints
- void [inactive_continuous_lower_bounds](#) (const [RealVector](#) &i_c_l_bnds)

set the inactive continuous lower bounds in userDefinedConstraints

- `const RealVector & inactive_continuous_upper_bounds () const`
return the inactive continuous upper bounds in userDefinedConstraints
- `void inactive_continuous_upper_bounds (const RealVector &i_c_u_bnds)`
set the inactive continuous upper bounds in userDefinedConstraints
- `const IntVector & inactive_discrete_lower_bounds () const`
return the inactive discrete lower bounds in userDefinedConstraints
- `void inactive_discrete_lower_bounds (const IntVector &i_d_l_bnds)`
set the inactive discrete lower bounds in userDefinedConstraints
- `const IntVector & inactive_discrete_upper_bounds () const`
return the inactive discrete upper bounds in userDefinedConstraints
- `void inactive_discrete_upper_bounds (const IntVector &i_d_u_bnds)`
set the inactive discrete upper bounds in userDefinedConstraints
- `size_t num_linear_ineq_constraints () const`
return the number of linear inequality constraints
- `size_t num_linear_eq_constraints () const`
return the number of linear equality constraints
- `const RealMatrix & linear_ineq_constraint_coeffs () const`
return the linear inequality constraint coefficients
- `void linear_ineq_constraint_coeffs (const RealMatrix &lin_ineq_coeffs)`
set the linear inequality constraint coefficients
- `const RealVector & linear_ineq_constraint_lower_bounds () const`
return the linear inequality constraint lower bounds
- `void linear_ineq_constraint_lower_bounds (const RealVector &lin_ineq_l_bnds)`
set the linear inequality constraint lower bounds
- `const RealVector & linear_ineq_constraint_upper_bounds () const`
return the linear inequality constraint upper bounds
- `void linear_ineq_constraint_upper_bounds (const RealVector &lin_ineq_u_bnds)`
set the linear inequality constraint upper bounds
- `const RealMatrix & linear_eq_constraint_coeffs () const`
return the linear equality constraint coefficients

- void `linear_eq_constraint_coeffs` (const `RealMatrix` &lin_eq_coeffs)
set the linear equality constraint coefficients
- const `RealVector` & `linear_eq_constraint_targets` () const
return the linear equality constraint targets
- void `linear_eq_constraint_targets` (const `RealVector` &lin_eq_targets)
set the linear equality constraint targets
- size_t `num_nonlinear_ineq_constraints` () const
return the number of nonlinear inequality constraints
- size_t `num_nonlinear_eq_constraints` () const
return the number of nonlinear equality constraints
- const `RealVector` & `nonlinear_ineq_constraint_lower_bounds` () const
return the nonlinear inequality constraint lower bounds
- void `nonlinear_ineq_constraint_lower_bounds` (const `RealVector` &nln_ineq_l_bnds)
set the nonlinear inequality constraint lower bounds
- const `RealVector` & `nonlinear_ineq_constraint_upper_bounds` () const
return the nonlinear inequality constraint upper bounds
- void `nonlinear_ineq_constraint_upper_bounds` (const `RealVector` &nln_ineq_u_bnds)
set the nonlinear inequality constraint upper bounds
- const `RealVector` & `nonlinear_eq_constraint_targets` () const
return the nonlinear equality constraint targets
- void `nonlinear_eq_constraint_targets` (const `RealVector` &nln_eq_targets)
set the nonlinear equality constraint targets
- const `IntList` & `merged_integer_list` () const
return the list of discrete variables merged into a continuous array in currentVariables
- const `IntArray` & `message_lengths` () const
return the array of MPI packed message buffer lengths (messageLengths)
- const `Variables` & `current_variables` () const
return the current variables (currentVariables)
- const `Response` & `current_response` () const
return the current response (currentResponse)

- const `ProblemDescDB` & `prob_desc_db` () const
return the problem description database (probDescDB)
- const `String` & `model_type` () const
return the model type (modelType)
- const `String` & `model_id` () const
return the model identifier (idModel)
- const `String` & `interface_id` ()
return the interface identifier (interface().interface_id())
- bool `asynch_flag` () const
return the asynchronous evaluation flag (asynchEvalFlag)
- void `asynch_flag` (const bool flag)
set the asynchronous evaluation flag (asynchEvalFlag)
- void `auto_graphics` (const bool flag)
set modelAutoGraphicsFlag to activate posting of graphics data within compute_response/synchronize functions (automatic graphics posting in the model as opposed to graphics posting at the strategy level).
- const `String` & `gradient_method` () const
return the gradient evaluation method (gradType)
- const `String` & `hessian_method` () const
return the Hessian evaluation method (hessType)
- const int & `evaluation_capacity` () const
return the evaluation capacity for use in iterator logic
- int `derivative_concurrency` () const
return the gradient concurrency for use in parallel configuration logic
- void `parallel_configuration_iterator` (const ParConfigLIter &pc_iter)
set modelPCIter
- const ParConfigLIter & `parallel_configuration_iterator` () const
return modelPCIter
- bool `is_null` () const
function to check modelRep (does this envelope contain a letter)

Protected Member Functions

- [Model](#) ([BaseConstructor](#), [ProblemDescDB](#) &[problem_db](#))
constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)
- virtual void [derived_compute_response](#) (const [ActiveSet](#) &set)
portion of [compute_response\(\)](#) specific to derived model classes
- virtual void [derived_asynch_compute_response](#) (const [ActiveSet](#) &set)
portion of [asynch_compute_response\(\)](#) specific to derived model classes
- virtual const [ResponseArray](#) & [derived_synchronize](#) ()
portion of [synchronize\(\)](#) specific to derived model classes
- virtual const [IntResponseMap](#) & [derived_synchronize_nowait](#) ()
portion of [synchronize_nowait\(\)](#) specific to derived model classes
- virtual void [derived_init_communicators](#) (const int &max_iterator_concurrency)
portion of [init_communicators\(\)](#) specific to derived model classes
- virtual void [derived_init_serial](#) ()
portion of [init_serial\(\)](#) specific to derived model classes
- virtual void [derived_set_communicators](#) (const int &max_iterator_concurrency)
portion of [set_communicators\(\)](#) specific to derived model classes
- virtual void [derived_free_communicators](#) (const int &max_iterator_concurrency)
portion of [free_communicators\(\)](#) specific to derived model classes

Protected Attributes

- [Variables](#) [currentVariables](#)
the set of current variables used by the model for performing function evaluations
- [size_t](#) [numDerivVars](#)
the number of active continuous variables used in computing most response derivatives (i.e., in places such as quasi-Hessians and response corrections where only the active continuous variables are supported)
- [Response](#) [currentResponse](#)
the set of current responses that holds the results of model function evaluations
- [size_t](#) [numFns](#)
the number of functions in [currentResponse](#)

- [Constraints userDefinedConstraints](#)

Explicit constraints on variables are maintained in the [Constraints](#) class hierarchy. Currently, this includes linear constraints and bounds, but could be extended in the future to include other explicit constraints which (1) have their form specified by the user; and (2) are not catalogued in [Response](#) since their form and coefficients are published to an iterator at startup.

- [IntArray messageLengths](#)

length of packed MPI buffers containing vars, vars/set, response, and PRPair

- const [ProblemDescDB](#) & [probDescDB](#)

class member reference to the problem description database. This reference is a const copy of the incoming `problem_db` non-const reference and is only used in `Model::prob_desc_db()` (it is not inherited).

- [ParallelLibrary](#) & [parallelLib](#)

class member reference to the parallel library

- [ParConfigLIter modelPCIter](#)

the [ParallelConfiguration](#) node used by this model instance

- int [componentParallelMode](#)

the component parallelism mode: 0 (none), 1 (INTERFACE/LF_MODEL), or 2 (SUB_MODEL/HF_MODEL/TRUTH_MODEL)

Private Member Functions

- `Model * get_model (ProblemDescDB &problem_db)`

Used by the envelope to instantiate the correct letter class.

- int `estimate_derivatives (const IntArray &map_asv, const IntArray &fd_grad_asv, const IntArray &fd_hess_asv, const IntArray &quasi_hess_asv, const ActiveSet &original_set, const bool asynch_flag)`

evaluate numerical gradients using finite differences. This routine is selected with "method_source dakota" (the default method_source) in the numerical gradient specification.

- void `synchronize_derivatives (const Variables &vars, const ResponseArray &fd_responses, Response &new_response, const IntArray &fd_grad_asv, const IntArray &fd_hess_asv, const IntArray &quasi_hess_asv, const ActiveSet &original_set)`

combine results from an array of finite difference response objects (fd_grad_responses) into a single response (new_response)

- void `update_response (const Variables &vars, Response &new_response, const IntArray &fd_grad_asv, const IntArray &fd_hess_asv, const IntArray &quasi_hess_asv, const ActiveSet &original_set, Response &initial_map_response, const RealMatrix &new_fn_grads, const RealMatrixArray &new_fn_hessians)`

overlay results to update a response object

- void `update_quasi_hessians (const Variables &vars, Response &new_response, const ActiveSet &original_set)`

perform quasi-Newton Hessian updates

- bool `manage_asv` (const `IntArray` &asv_in, `IntArray` &map_asv_out, `IntArray` &fd_grad_asv_out, `IntArray` &fd_hess_asv_out, `IntArray` &quasi_hess_asv_out)

Coordinates usage of `estimate_derivatives()` calls based on asv_in.

Private Attributes

- `Model * modelRep`
pointer to the letter (initialized only for the envelope)
- int `referenceCount`
number of objects sharing modelRep
- `String modelType`
type of model: single, nested, or surrogate
- bool `hierarchicalModel`
flag for identifying a `HierarchSurrModel`
- `String idModel`
model identifier string from the input file
- bool `estDerivsFlag`
flags presence of estimated derivatives within a set of calls to `asynch_compute_response()`
- bool `asynchEvalFlag`
flags asynch evaluations (local or distributed)
- int `evaluationCapacity`
capacity for concurrent evaluations supported by the `Model`
- `std::map< int, ParConfigLIter > modelPCIterMap`
map<> used for tracking `modelPCIter` instances using concurrency level as the lookup key
- bool `modelAutoGraphicsFlag`
flag for posting of graphics data within `compute_response` (automatic graphics posting in the model as opposed to graphics posting at the strategy level)
- bool `silentFlag`
flag for really quiet (silent) model output
- bool `quietFlag`
flag for quiet model output

- **ModelList** `modelList`
used to collect sub-models for `subordinate_models()`
- **VariablesList** `varsList`
history of vars populated in `async_compute_response()` and used in `synchronize()`.
- **List< IntArray >** `asvList`
if `estimate_derivatives()` is used, transfers ASVs from `async_compute_response()` to `synchronize()`
- **List< ActiveSet >** `setList`
if `estimate_derivatives()` is used, transfers ActiveSets from `async_compute_response()` to `synchronize()`
- **BoolList** `initialMapList`
transfers `initial_map` flag values from `estimate_derivatives()` to `synchronize_derivatives()`
- **BoolList** `dbCaptureList`
transfers `db_capture` flag values from `estimate_derivatives()` to `synchronize_derivatives()`
- **ResponseList** `dbResponseList`
transfers database captures from `estimate_derivatives()` to `synchronize_derivatives()`
- **RealList** `deltaList`
transfers deltas from `estimate_derivatives()` to `synchronize_derivatives()`
- **IntList** `numMapsList`
tracks the number of maps used in `estimate_derivatives()`. Used in `synchronize()` as a key for combining finite difference responses into numerical gradients.
- **RealMatrix** `xPrev`
previous parameter vectors used in computing `s` for quasi-Newton updates
- **RealMatrix** `fnGradsPrev`
previous gradient vectors used in computing `y` for quasi-Newton updates
- **RealMatrixArray** `quasiHessians`
quasi-Newton Hessian approximations
- **SizeTArray** `numQuasiUpdates`
number of quasi-Newton Hessian updates applied
- **ResponseArray** `responseArray`
used to return an array of responses for asynchronous evaluations. This array has the responses in final concatenated form. The similar array in `Interface` contains the raw responses.
- **IntResponseMap** `graphicsRespMap`
used to cache the data returned from `derived_synchronize_nowait()` prior to sequential input into the graphics

- [String gradType](#)
grad type: none,numerical,analytic,mixed
- [String methodSrc](#)
method source: dakota,vendor
- [String intervalType](#)
interval type: forward,central
- [RealVector fdGradSS](#)
relative step sizes for numerical gradients
- [IntList gradIdAnalytic](#)
analytic id's for mixed gradients
- [IntList gradIdNumerical](#)
numerical id's for mixed gradients
- [String hessType](#)
Hess type: none,numerical,quasi,analytic,mixed.
- [String quasiHessType](#)
quasi-Hessian type: bfgs, damped_bfgs, srl
- [RealVector fdHessByGradSS](#)
relative step sizes for numerical Hessians estimated with 1st-order grad differences
- [RealVector fdHessByFnSS](#)
relative step sizes for numerical Hessians estimated with 2nd-order fn differences
- [IntList hessIdAnalytic](#)
analytic id's for mixed Hessians
- [IntList hessIdNumerical](#)
numerical id's for mixed Hessians
- [IntList hessIdQuasi](#)
quasi id's for mixed Hessians
- [RealVector normalMeans](#)
normal uncertain variable means
- [RealVector normalStdDevs](#)
normal uncertain variable standard deviations

- [RealVector normalLowerBnds](#)
normal uncertain variable lower bounds
- [RealVector normalUpperBnds](#)
normal uncertain variable upper bounds
- [RealVector lognormalMeans](#)
lognormal uncertain variable means
- [RealVector lognormalStdDevs](#)
lognormal uncertain variable standard deviations
- [RealVector lognormalErrFacts](#)
lognormal uncertain variable error factors
- [RealVector lognormalLowerBnds](#)
lognormal uncertain variable lower bounds
- [RealVector lognormalUpperBnds](#)
lognormal uncertain variable upper bounds
- [RealVector uniformLowerBnds](#)
uniform uncertain variable lower bounds
- [RealVector uniformUpperBnds](#)
uniform uncertain variable upper bounds
- [RealVector loguniformLowerBnds](#)
loguniform uncertain variable lower bounds
- [RealVector loguniformUpperBnds](#)
loguniform uncertain variable upper bounds
- [RealVector triangularModes](#)
triangular uncertain variable modes
- [RealVector triangularLowerBnds](#)
triangular uncertain variable lower bounds
- [RealVector triangularUpperBnds](#)
triangular uncertain variable upper bounds
- [RealVector betaAlphas](#)
beta uncertain variable alphas
- [RealVector betaBetas](#)

beta uncertain variable betas

- [RealVector betaLowerBnds](#)
beta uncertain variable lower bounds
- [RealVector betaUpperBnds](#)
beta uncertain variable upper bounds
- [RealVector gammaAlphas](#)
gamma uncertain variable alphas
- [RealVector gammaBetas](#)
gamma uncertain variable betas
- [RealVector gumbelAlphas](#)
gumbel uncertain variable alphas
- [RealVector gumbelBetas](#)
gumbel uncertain variable betas
- [RealVector frechetAlphas](#)
frechet uncertain variable alphas
- [RealVector frechetBetas](#)
frechet uncertain variable betas
- [RealVector weibullAlphas](#)
weibull uncertain variable alphas
- [RealVector weibullBetas](#)
weibull uncertain variable betas
- [RealVectorArray histogramBinPairs](#)
histogram uncertain (x,y) bin pairs (continuous linear histogram)
- [RealVectorArray histogramPointPairs](#)
histogram uncertain (x,y) point pairs (discrete histogram)
- [IntVector intervalNumIntervals](#)
interval uncertain variable number of intervals per variable
- [RealVector intervalProbValues](#)
interval uncertain variable probability values
- [RealVector intervalBounds](#)
interval uncertain variable interval bounds

10.60.1 Detailed Description

Base class for the model class hierarchy.

The [Model](#) class is the base class for one of the primary class hierarchies in DAKOTA. The model hierarchy contains a set of variables, an interface, and a set of responses, and an iterator operates on the model to map the variables into responses using the interface. For memory efficiency and enhanced polymorphism, the model hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Model](#)) serves as the envelope and one of the derived classes (selected in [Model::get_model\(\)](#)) serves as the letter.

10.60.2 Constructor & Destructor Documentation

10.60.2.1 [Model](#) ()

default constructor

The default constructor is used in `vector<Model>` instantiations and for initialization of [Model](#) objects contained in [Iterator](#) and derived [Strategy](#) classes. `modelRep` is NULL in this case (a populated `problem_db` is needed to build a meaningful [Model](#) object). This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

10.60.2.2 [Model](#) ([ProblemDescDB](#) & *problem_db*)

standard constructor for envelope

Used in model instantiations within strategy constructors. Envelope constructor only needs to extract enough data to properly execute `get_model`, since `Model(BaseConstructor, problem_db)` builds the actual base class data for the derived models.

10.60.2.3 [Model](#) (const [Model](#) & *model*)

copy constructor

Copy constructor manages sharing of `modelRep` and incrementing of `referenceCount`.

10.60.2.4 `~Model` () [virtual]

destructor

Destructor decrements `referenceCount` and only deletes `modelRep` when `referenceCount` reaches zero.

10.60.2.5 [Model](#) ([BaseConstructor](#), [ProblemDescDB](#) & *problem_db*) [protected]

constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

This constructor builds the base class data for all inherited models. `get_model()` instantiates a derived class and the derived class selects this base class constructor in its initialization list (to avoid the recursion of the base class constructor calling `get_model()` again). Since the letter IS the representation, its representation pointer is set to NULL (an uninitialized pointer causes problems in `~Model`).

10.60.3 Member Function Documentation

10.60.3.1 `Model` operator= (const `Model` & *model*)

assignment operator

Assignment operator decrements referenceCount for old modelRep, assigns new modelRep, and increments referenceCount for new modelRep.

10.60.3.2 `Iterator` & `subordinate_iterator` () [virtual]

return the sub-iterator in nested and surrogate models

return by reference requires use of dummy objects, but is important to allow use of `assign_rep()` since this operation must be performed on the original envelope object.

Reimplemented in [DataFitSurrModel](#), and [NestedModel](#).

10.60.3.3 `Model` & `surrogate_model` () [virtual]

return the approximation sub-model in surrogate models

return by reference requires use of dummy objects, but is important to allow use of `assign_rep()` since this operation must be performed on the original envelope object.

Reimplemented in [DataFitSurrModel](#), and [HierarchSurrModel](#).

10.60.3.4 `Model` & `truth_model` () [virtual]

return the truth sub-model in surrogate models

return by reference requires use of dummy objects, but is important to allow use of `assign_rep()` since this operation must be performed on the original envelope object.

Reimplemented in [DataFitSurrModel](#), and [HierarchSurrModel](#).

10.60.3.5 `Interface` & `interface` () [virtual]

return the interface employed by the derived model class, if present: [SingleModel::userDefinedInterface](#), [DataFitSurrModel::approxInterface](#), or [NestedModel::optionalInterface](#)

return by reference requires use of dummy objects, but is important to allow use of [assign_rep\(\)](#) since this operation must be performed on the original envelope object.

Reimplemented in [DataFitSurrModel](#), [NestedModel](#), and [SingleModel](#).

10.60.3.6 [String](#) `local_eval_synchronization()` [virtual]

return derived model synchronization setting

[SingleModels](#) and [HierarchSurrModels](#) redefine this virtual function. A default value of "synchronous" prevents asynch local operations for:

- [NestedModels](#): a subIterator can support message passing parallelism, but not asynch local.
- [DataFitSurrModels](#): while asynch evals on approximations will work due to some added bookkeeping, avoiding them is preferable.

Reimplemented in [SingleModel](#).

10.60.3.7 `int` `local_eval_concurrency()` [virtual]

return derived model asynchronous evaluation concurrency

[SingleModels](#) and [HierarchSurrModels](#) redefine this virtual function.

Reimplemented in [SingleModel](#).

10.60.3.8 [ModelList](#) & `subordinate_models` (`bool recurse_flag = true`)

return the sub-models in nested and surrogate models

since `modelList` is built with list insertions (using envelope copies), these models may not be used for `model.assign_rep()` since this operation must be performed on the original envelope object. They may, however, be used for letter-based operations (including [assign_rep\(\)](#) on letter contents such as an interface).

10.60.3.9 `void` `init_communicators` (`const int & max_iterator_concurrency`)

allocate communicator partitions for a model and store configuration in `modelPCIterMap`

The `init_communicators()` and `derived_init_communicators()` functions are structured to avoid performing the `messageLengths` estimation more than once. `init_communicators()` (not virtual) performs the estimation and then forwards the results to `derived_init_communicators` (virtual) which uses the data in different contexts.

10.60.3.10 `void` `init_serial()`

for cases where `init_communicators()` will not be called, modify some default settings to behave properly in serial.

The `init_serial()` and `derived_init_serial()` functions are structured to separate base class (common) operations from derived class (specialized) operations.

10.60.3.11 void estimate_message_lengths ()

estimate messageLengths for a model

This functionality has been pulled out of `init_communicators()` and defined separately so that it may be used in those cases when messageLengths is needed but `model.init_communicators()` is not called, e.g., for the master processor in the self-scheduling of a concurrent iterator strategy.

10.60.3.12 void assign_rep (Model * model_rep, bool ref_count_incr = true)

replaces existing letter with a new one

Similar to the assignment operator, the `assign_rep()` function decrements referenceCount for the old modelRep and assigns the new modelRep. It is different in that it is used for publishing derived class letters to existing envelopes, as opposed to sharing representations among multiple envelopes (in particular, `assign_rep` is passed a letter object and `operator=` is passed an envelope object). Letter assignment supports two models as governed by `ref_count_incr`:

- `ref_count_incr = true` (default): the incoming letter belongs to another envelope. In this case, increment the reference count in the normal manner so that deallocation of the letter is handled properly.
- `ref_count_incr = false`: the incoming letter is instantiated on the fly and has no envelope. This case is modeled after `get_model()`: a letter is dynamically allocated using `new` and passed into `assign_rep`, the letter's reference count is not incremented, and the letter is not remotely deleted (its memory management is passed over to the envelope).

10.60.3.13 int derivative_concurrency () const

return the gradient concurrency for use in parallel configuration logic

This function assumes derivatives with respect to the active continuous variables. Therefore, concurrency with respect to the inactive continuous variables is not captured.

10.60.3.14 Model * get_model (ProblemDescDB & problem_db) [private]

Used by the envelope to instantiate the correct letter class.

Used only by the envelope constructor to initialize modelRep to the appropriate derived type, as given by the modelType attribute.

10.60.3.15 int estimate_derivatives (const IntArray & map_asv, const IntArray & fd_grad_asv, const IntArray & fd_hess_asv, const IntArray & quasi_hess_asv, const ActiveSet & original_set, const bool asynch_flag) [private]

evaluate numerical gradients using finite differences. This routine is selected with "method_source dakota" (the default method_source) in the numerical gradient specification.

Estimate derivatives by computing finite difference gradients, finite difference Hessians, and/or quasi-Newton Hessians. The total number of finite difference evaluations is returned for use by [synchronize\(\)](#) to track response arrays, and it could be used to improve management of `max_function_evaluations` within the iterators.

10.60.3.16 `void synchronize_derivatives (const Variables & vars, const ResponseArray & fd_responses, Response & new_response, const IntArray & fd_grad_asv, const IntArray & fd_hess_asv, const IntArray & quasi_hess_asv, const ActiveSet & original_set) [private]`

combine results from an array of finite difference response objects (`fd_grad_responses`) into a single response (`new_response`)

Merge an array of `fd_responses` into a single `new_response`. This function is used both by synchronous [compute_response\(\)](#) for the case of asynchronous [estimate_derivatives\(\)](#) and by [synchronize\(\)](#) for the case where one or more [asynch_compute_response\(\)](#) calls has employed asynchronous [estimate_derivatives\(\)](#).

10.60.3.17 `void update_response (const Variables & vars, Response & new_response, const IntArray & fd_grad_asv, const IntArray & fd_hess_asv, const IntArray & quasi_hess_asv, const ActiveSet & original_set, Response & initial_map_response, const RealMatrix & new_fn_grads, const RealMatrixArray & new_fn_hessians) [private]`

overlay results to update a response object

Overlay the `initial_map_response` with numerically estimated `new_fn_grads` and `new_fn_hessians` to populate `new_response` as governed by `asv` vectors. Quasi-Newton secant Hessian updates are also performed here, since this is where the gradient data needed for the updates is first consolidated. Convenience function used by [estimate_derivatives\(\)](#) for the synchronous case and by [synchronize_derivatives\(\)](#) for the asynchronous case.

10.60.3.18 `void update_quasi_hessians (const Variables & vars, Response & new_response, const ActiveSet & original_set) [private]`

perform quasi-Newton Hessian updates

quasi-Newton updates are performed for approximating response function Hessians using BFGS or SR1 formulations. These Hessians are supported only for the active continuous variables, and a check is performed on the DVV prior to invoking the function.

10.60.3.19 `bool manage_asv (const IntArray & asv_in, IntArray & map_asv_out, IntArray & fd_grad_asv_out, IntArray & fd_hess_asv_out, IntArray & quasi_hess_asv_out) [private]`

Coordinates usage of [estimate_derivatives\(\)](#) calls based on `asv_in`.

Splits `asv_in` total request into `map_asv_out`, `fd_grad_asv_out`, `fd_hess_asv_out`, and `quasi_hess_asv_out` as governed by the responses specification. If the returned `use_est_deriv` is true, then these `asv` outputs are used by [estimate_derivatives\(\)](#) for the initial map, finite difference gradient evals, finite difference Hessian evals, and quasi-Hessian updates, respectively. If the returned `use_est_deriv` is false, then only `map_asv_out` is used.

The documentation for this class was generated from the following files:

- DakotaModel.H

- DakotaModel.C

10.61 MPIPackBuffer Class Reference

Class for packing MPI message buffers.

Public Member Functions

- [MPIPackBuffer](#) (int size_=1024)
Constructor, which allows the default buffer size to be set.
- [~MPIPackBuffer](#) ()
Destructor.
- const char * [buf](#) ()
Returns a pointer to the internal buffer that has been packed.
- int [size](#) ()
The number of bytes of packed data.
- int [capacity](#) ()
the allocated size of Buffer.
- void [reset](#) ()
Resets the buffer index in order to reuse the internal buffer.
- void [pack](#) (const int *data, const int num=1)
*Pack one or more **int**'s.*
- void [pack](#) (const u_int *data, const int num=1)
*Pack one or more **unsigned int**'s.*
- void [pack](#) (const long *data, const int num=1)
*Pack one or more **long**'s.*
- void [pack](#) (const u_long *data, const int num=1)
*Pack one or more **unsigned long**'s.*
- void [pack](#) (const short *data, const int num=1)
*Pack one or more **short**'s.*
- void [pack](#) (const u_short *data, const int num=1)
*Pack one or more **unsigned short**'s.*

- void `pack` (const char *data, const int num=1)
*Pack one or more **char**'s.*
- void `pack` (const u_char *data, const int num=1)
*Pack one or more **unsigned char**'s.*
- void `pack` (const double *data, const int num=1)
*Pack one or more **double**'s.*
- void `pack` (const float *data, const int num=1)
*Pack one or more **fbat**'s.*
- void `pack` (const bool *data, const int num=1)
*Pack one or more **bool**'s.*
- void `pack` (const int &data)
*Pack a **int**.*
- void `pack` (const u_int &data)
*Pack a **unsigned int**.*
- void `pack` (const long &data)
*Pack a **long**.*
- void `pack` (const u_long &data)
*Pack a **unsigned long**.*
- void `pack` (const short &data)
*Pack a **short**.*
- void `pack` (const u_short &data)
*Pack a **unsigned short**.*
- void `pack` (const char &data)
*Pack a **char**.*
- void `pack` (const u_char &data)
*Pack a **unsigned char**.*
- void `pack` (const double &data)
*Pack a **double**.*
- void `pack` (const float &data)
*Pack a **fbat**.*
- void `pack` (const bool &data)
*Pack a **bool**.*

Protected Member Functions

- void [resize](#) (const int newsize)
Resizes the internal buffer.

Protected Attributes

- char * [Buffer](#)
The internal buffer for packing.
- int [Index](#)
The index into the current buffer.
- int [Size](#)
The total size that has been allocated for the buffer.

10.61.1 Detailed Description

Class for packing MPI message buffers.

A class that provides a facility for packing message buffers using the MPI_Pack facility. The [MPIPackBuffer](#) class dynamically resizes the internal buffer to contain enough memory to pack the entire object. When deleted, the [MPIPackBuffer](#) object deletes this internal buffer. This class is based on the Dakota_Version_3_0 version of `utilib::PackBuffer` from `utilib/src/io/PackBuf.[cpp,h]`

The documentation for this class was generated from the following files:

- [MPIPackBuffer.H](#)
- [MPIPackBuffer.C](#)

10.62 MPIUnpackBuffer Class Reference

Class for unpacking MPI message buffers.

Public Member Functions

- void **setup** (char *buf_, int size_, bool flag_=false)
Method that does the setup for the constructors.
- **MPIUnpackBuffer** ()
Default constructor.
- **MPIUnpackBuffer** (int size_)
Constructor that specifies the size of the buffer.
- **MPIUnpackBuffer** (char *buf_, int size_, bool flag_=false)
Constructor that sets the internal buffer to the given array.
- **~MPIUnpackBuffer** ()
Destructor.
- void **resize** (const int newsize)
Resizes the internal buffer.
- const char * **buf** ()
Returns a pointer to the internal buffer.
- int **size** ()
Returns the length of the buffer.
- int **curr** ()
Returns the number of bytes that have been unpacked from the buffer.
- void **reset** ()
Resets the index of the internal buffer.
- void **unpack** (int *data, const int num=1)
*Unpack one or more **int**'s.*
- void **unpack** (u_int *data, const int num=1)
*Unpack one or more **unsigned int**'s.*

- void `unpack` (long *data, const int num=1)
*Unpack one or more **long**'s.*
- void `unpack` (u_long *data, const int num=1)
*Unpack one or more **unsigned long**'s.*
- void `unpack` (short *data, const int num=1)
*Unpack one or more **short**'s.*
- void `unpack` (u_short *data, const int num=1)
*Unpack one or more **unsigned short**'s.*
- void `unpack` (char *data, const int num=1)
*Unpack one or more **char**'s.*
- void `unpack` (u_char *data, const int num=1)
*Unpack one or more **unsigned char**'s.*
- void `unpack` (double *data, const int num=1)
*Unpack one or more **double**'s.*
- void `unpack` (float *data, const int num=1)
*Unpack one or more **float**'s.*
- void `unpack` (bool *data, const int num=1)
*Unpack one or more **bool**'s.*
- void `unpack` (int &data)
*Unpack a **int**.*
- void `unpack` (u_int &data)
*Unpack a **unsigned int**.*
- void `unpack` (long &data)
*Unpack a **long**.*
- void `unpack` (u_long &data)
*Unpack a **unsigned long**.*
- void `unpack` (short &data)
*Unpack a **short**.*
- void `unpack` (u_short &data)
*Unpack a **unsigned short**.*
- void `unpack` (char &data)

*Unpack a **char**.*

- void `unpack` (u_char &data)
*Unpack a **unsigned char**.*
- void `unpack` (double &data)
*Unpack a **double**.*
- void `unpack` (float &data)
*Unpack a **fbat**.*
- void `unpack` (bool &data)
*Unpack a **bool**.*

Protected Attributes

- char * `Buffer`
The internal buffer for unpacking.
- int `Index`
The index into the current buffer.
- int `Size`
The total size that has been allocated for the buffer.
- bool `ownFlag`
If `TRUE`, then this class owns the internal buffer.

10.62.1 Detailed Description

Class for unpacking MPI message buffers.

A class that provides a facility for unpacking message buffers using the `MPI_Unpack` facility. This class is based on the `Dakota_Version_3_0` version of `utilib::UnPackBuffer` from `utilib/src/io/PackBuf.[cpp,h]`

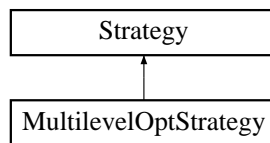
The documentation for this class was generated from the following files:

- `MPIPackBuffer.H`
- `MPIPackBuffer.C`

10.63 MultilevelOptStrategy Class Reference

[Strategy](#) for hybrid optimization using multiple optimizers on multiple models of varying fidelity.

Inheritance diagram for MultilevelOptStrategy::



Public Member Functions

- [MultilevelOptStrategy](#) ([ProblemDescDB](#) &problem_db)
constructor
- [~MultilevelOptStrategy](#) ()
destructor
- void [run_strategy](#) ()
Performs the hybrid optimization strategy by executing multiple iterators on different models of varying fidelity.
- const [Variables](#) & [variable_results](#) () const
return the final solution from selectedIterators (variables)
- const [Response](#) & [response_results](#) () const
return the final solution from selectedIterators (response)

Private Member Functions

- void [run_coupled](#) ()
run a tightly coupled hybrid
- void [run_uncoupled](#) ()
run an uncoupled hybrid
- void [run_uncoupled_adaptive](#) ()
run an uncoupled adaptive hybrid

Private Attributes

- [String multiLevelType](#)
coupled, uncoupled, or uncoupled_adaptive
- [StringArray methodList](#)
the list of method identifiers
- [int numIterators](#)
number of methods in methodList
- [Real localSearchProb](#)
the probability of running a local search refinement within phases of the global optimization for coupled hybrids
- [Real progressMetric](#)
the amount of progress made in a single iterator++ cycle within an uncoupled adaptive hybrid
- [Real progressThreshold](#)
when the progress metric falls below this threshold, the uncoupled adaptive hybrid switches to the next method
- [IteratorArray selectedIterators](#)
the set of iterators, one for each entry in methodList
- [ModelArray userDefinedModels](#)
the set of models, one for each iterator

10.63.1 Detailed Description

[Strategy](#) for hybrid optimization using multiple optimizers on multiple models of varying fidelity.

This strategy has three approaches to hybrid optimization: (1) the uncoupled hybrid runs one method to completion, passes its best results as the starting point for a subsequent method, and continues this succession until all methods have been executed; (2) the uncoupled adaptive hybrid is similar to the uncoupled hybrid, except that the stopping rules for the optimizers are controlled adaptively by the strategy instead of internally by each optimizer; and (3) the coupled hybrid uses multiple methods in close coordination, generally using a local search optimizer repeatedly within a global optimizer (the local search optimizer refines candidate optima which are fed back to the global optimizer). The uncoupled strategies only pass information forward, whereas the coupled strategy allows both feed forward and feedback. Note that while the strategy is targeted at optimizers, any iterator may be used so long as it defines the notion of a final solution which can be passed as the starting point for subsequent iterators.

10.63.2 Member Function Documentation

10.63.2.1 void run_coupled () [private]

run a tightly coupled hybrid

In the coupled case, use is made of external hybridization capabilities, such as those available in the global/local hybrids from SGOPT. This function is responsible only for publishing the local optimizer selection to the global optimizer and then invoking the global optimizer; the logic of method switching is handled entirely within the global optimizer. Status: incomplete.

10.63.2.2 void run_uncoupled () [private]

run an uncoupled hybrid

In the uncoupled nonadaptive case, there is no interference with the iterators. Each runs until its own convergence criteria is satisfied. Status: fully operational.

10.63.2.3 void run_uncoupled_adaptive () [private]

run an uncoupled adaptive hybrid

In the uncoupled adaptive case, there is interference with the iterators through the use of the ++ overloaded operator. iterator++ runs the iterator for one cycle, after which a progress_metric is computed. This progress metric is used to dictate method switching instead of each iterator's internal convergence criteria. Status: incomplete.

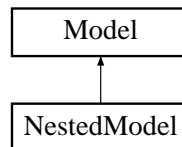
The documentation for this class was generated from the following files:

- MultilevelOptStrategy.H
- MultilevelOptStrategy.C

10.64 NestedModel Class Reference

Derived model class which performs a complete sub-iterator execution within every evaluation of the model.

Inheritance diagram for NestedModel::



Public Member Functions

- [NestedModel \(ProblemDescDB &problem_db\)](#)
constructor
- [~NestedModel \(\)](#)
destructor

Protected Member Functions

- void [derived_compute_response](#) (const [ActiveSet](#) &set)
portion of [compute_response\(\)](#) specific to [NestedModel](#)
- void [derived_async_compute_response](#) (const [ActiveSet](#) &set)
portion of [async_compute_response\(\)](#) specific to [NestedModel](#)
- void [derived_subordinate_models](#) ([ModelList](#) &ml, bool recurse_flag)
return subModel
- [Iterator](#) & [subordinate_iterator](#) ()
return subIterator
- [Interface](#) & [interface](#) ()
return optionalInterface
- void [surrogate_bypass](#) (bool bypass_flag)
NestedModels have nothing to bypass, but must pass request on to the subModel for any lower-level surrogates.
- void [component_parallel_mode](#) (int mode)

update component parallel mode for supporting parallelism in optionalInterface and subModel

- bool [derived_master_overload](#) () const
flag which prevents overloading the master with a multiprocessor evaluation (forwarded to optionalInterface)
- void [derived_init_communicators](#) (const int &max_iterator_concurrency)
set up optionalInterface and subModel for parallel operations
- void [derived_init_serial](#) ()
set up optionalInterface and subModel for serial operations.
- void [derived_set_communicators](#) (const int &max_iterator_concurrency)
set active parallel configuration within subModel
- void [reset_communicators](#) ()
reset communicator partitions for the [NestedModel](#) (forwarded to optionalInterface and subModel)
- void [derived_free_communicators](#) (const int &max_iterator_concurrency)
deallocate communicator partitions for the [NestedModel](#) (forwarded to optionalInterface and subModel)
- void [serve](#) ()
Service optionalInterface and subModel job requests received from the master. Completes when a termination message is received from [stop_servers](#)().
- void [stop_servers](#) ()
Executed by the master to terminate server operations for subModel and optionalInterface when iteration on the [NestedModel](#) is complete.
- int [evaluation_id](#) () const
Return the current evaluation id for the [NestedModel](#).
- void [set_evaluation_reference](#) ()
set the evaluation counter reference points for the [NestedModel](#) (request forwarded to optionalInterface and sub-Model)
- void [print_evaluation_summary](#) (ostream &s, bool minimal_header=false, bool relative_count=true) const
print the evaluation summary for the [NestedModel](#) (request forwarded to optionalInterface and subModel)

Private Member Functions

- void [asv_mapping](#) (const [IntArray](#) &mapped_asv, [IntArray](#) &interface_asv, [IntArray](#) &sub_iterator_asv)
define the evaluation requirements for the optionalInterface (interface_asv) and the subIterator (sub_iterator_asv) from the total model evaluation requirements (mapped_asv)

- void `response_mapping` (const `Response` &interface_response, const `Response` &sub_iterator_response, `Response` &mapped_response)
combine the response from the optional interface evaluation with the response from the sub-iteration using the primaryCoeffs/secondaryCoeffs mappings to create the total response for the model
- void `update_sub_model` ()
update subModel with current variable values/bounds/labels

Private Attributes

- int `nestedModelEvals`
number of calls to `derived_compute_response()`/ `derived_asynch_compute_response()`
- `Iterator` `subIterator`
the sub-iterator that is executed on every evaluation of this model
- `Model` `subModel`
the sub-model used in sub-iterator evaluations
- size_t `numSubIterFns`
number of sub-iterator response functions prior to mapping
- size_t `numSubIterMappedIneqCon`
number of top-level inequality constraints mapped from the sub-iteration results
- size_t `numSubIterMappedEqCon`
number of top-level equality constraints mapped from the sub-iteration results
- `Interface` `optionalInterface`
the optional interface contributes nonnested response data to the total model response
- `String` `optInterfacePointer`
the optional interface pointer from the nested model specification
- `Response` `optInterfaceResponse`
the response object resulting from optional interface evaluations
- size_t `numOptInterfPrimary`
number of primary response functions (objective/least squares/generic functions) resulting from optional interface evaluations
- size_t `numOptInterfIneqCon`
number of inequality constraints resulting from optional interface evaluations
- size_t `numOptInterfEqCon`

number of equality constraints resulting from the optional interface evaluations

- [SizetArray primaryCVarMapIndices](#)

"primary" variable mappings for inserting active continuous currentVariables into active continuous subModel variables. If there are no secondary mappings defined, then the insertions replace the subModel variable values.

- [SizetArray primaryDVarMapIndices](#)

"primary" variable mappings for inserting active discrete currentVariables into active discrete subModel variables. No secondary mappings are defined for discrete variables, so the insertions replace the subModel variable values.

- [SizetArray secondaryVarMapIndices](#)

"secondary" variable mappings for inserting active continuous currentVariables into sub-parameters (e.g., distribution parameters for uncertain variables) of the active continuous subModel variables.

- [RealMatrix primaryRespCoeffs](#)

"primary" response_mapping matrix applied to the sub-iterator response functions. For OUU, the matrix is applied to UQ statistics to create contributions to the top-level objective functions/least squares/ generic response terms.

- [RealMatrix secondaryRespCoeffs](#)

"secondary" response_mapping matrix applied to the sub-iterator response functions. For OUU, the matrix is applied to UQ statistics to create contributions to the top-level inequality and equality constraints.

10.64.1 Detailed Description

Derived model class which performs a complete sub-iterator execution within every evaluation of the model.

The [NestedModel](#) class nests a sub-iterator execution within every model evaluation. This capability is most commonly used for optimization under uncertainty, in which a nondeterministic iterator is executed on every optimization function evaluation. The [NestedModel](#) also contains an optional interface, for portions of the model evaluation which are independent from the sub-iterator, and a set of mappings for combining sub-iterator and optional interface data into a top level response for the model.

10.64.2 Member Function Documentation

10.64.2.1 void derived_compute_response (const [ActiveSet](#) & set) [protected, virtual]

portion of [compute_response\(\)](#) specific to [NestedModel](#)

Update subModel's inactive variables with active variables from currentVariables, compute the optional interface and sub-iterator responses, and map these to the total model response.

Reimplemented from [Model](#).

10.64.2.2 void derived_asynch_compute_response (const [ActiveSet](#) & set) [protected, virtual]

portion of [asynch_compute_response\(\)](#) specific to [NestedModel](#)

Not currently supported by NestedModels (need to add concurrent iterator support). As a result, [derived_synchronize\(\)](#) and [derived_synchronize_nowait\(\)](#) are inactive as well).

Reimplemented from [Model](#).

10.64.2.3 bool derived_master_overload () const [inline, protected, virtual]

flag which prevents overloading the master with a multiprocessor evaluation (forwarded to optionalInterface)

Derived master overload for subModel is handled separately in subModel.compute_response() within subIterator.run().

Reimplemented from [Model](#).

10.64.2.4 void derived_init_communicators (const int & max_iterator_concurrency) [inline, protected, virtual]

set up optionalInterface and subModel for parallel operations

Asynchronous flags need to be initialized for the subModel. In addition, max_iterator_concurrency is the outer level iterator concurrency, not the subIterator concurrency that subModel will see, and recomputing the message_lengths on the subModel is probably not a bad idea either. Therefore, recompute everything on subModel using [init_communicators\(\)](#).

Reimplemented from [Model](#).

10.64.2.5 int evaluation_id () const [inline, protected, virtual]

Return the current evaluation id for the [NestedModel](#).

return the top level nested evaluation count. To get the lower level eval count, the subModel must be explicitly queried. This is consistent with the eval counter definitions in surrogate models.

Reimplemented from [Model](#).

10.64.2.6 void response_mapping (const [Response](#) & opt_interface_response, const [Response](#) & sub_iterator_response, [Response](#) & mapped_response) [private]

combine the response from the optional interface evaluation with the response from the sub-iteration using the primaryCoeffs/secondaryCoeffs mappings to create the total response for the model

In the OUU case,

```
optionalInterface fns = {f}, {g} (deterministic primary functions, constraints)
subIterator fns      = {S}      (UQ response statistics)
```

```
Problem formulation for mapped functions:
      minimize    {f} + [W]{S}
```

```

subject to  {g_l} <= {g}      <= {g_u}
            {a_l} <= [A]{S} <= {a_u}
            {g}   == {g_t}
            [A]{S} == {a_t}

```

where [W] is the primary_mapping_matrix user input (primaryRespCoeffs class attribute), [A] is the secondary_mapping_matrix user input (secondaryRespCoeffs class attribute), {{g_l},{a_l}} are the top level inequality constraint lower bounds, {{g_u},{a_u}} are the top level inequality constraint upper bounds, and {{g_t},{a_t}} are the top level equality constraint targets.

NOTE: optionalInterface/subIterator primary fns (obj/lsq/generic fns) overlap but optionalInterface/subIterator secondary fns (ineq/eq constraints) do not. The [W] matrix can be specified so as to allow

- some purely deterministic primary functions and some combined: [W] filled and [W].num_rows() < {f}.length() [combined first] *or* [W].num_rows() == {f}.length() and [W] contains rows of zeros [combined last]
- some combined and some purely stochastic primary functions: [W] filled and [W].num_rows() > {f}.length()
- separate deterministic and stochastic primary functions: [W].num_rows() > {f}.length() and [W] contains {f}.length() rows of zeros.

If the need arises, could change constraint definition to allow overlap as well: {g_l} <= {g} + [A]{S} <= {g_u} with [A] usage the same as for [W] above.

In the UOO case, things are simpler, just compute statistics of each optimization response function: [W] = [I], {f}/{g}/[A] are empty.

10.64.3 Member Data Documentation

10.64.3.1 Model subModel [private]

the sub-model used in sub-iterator evaluations

There are no restrictions on subModel, so arbitrary nestings are possible. This is commonly used to support surrogate-based optimization under uncertainty by having NestedModels contain SurrogateModels and vice versa.

The documentation for this class was generated from the following files:

- NestedModel.H
- NestedModel.C

10.65 NI2Misc Struct Reference

Auxiliary information passed to `calcr` and `calcj` via `ur`.

Public Attributes

- Real * `J` [2]
cache the two most recent Jacobian values in speculative-evaluation mode
- int `nf` [2]
function-evaluation counts corresponding to cached Jacobian values (used to tell which J value to use)
- int `specgrad`
whether to cache J values (0 == no, 1 == yes)

10.65.1 Detailed Description

Auxiliary information passed to `calcr` and `calcj` via `ur`.

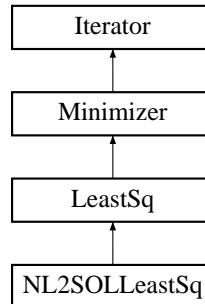
The documentation for this struct was generated from the following file:

- `NL2SOLLeastSq.C`

10.66 NL2SOLLeastSq Class Reference

Wrapper class for the NL2SOL nonlinear least squares library.

Inheritance diagram for NL2SOLLeastSq::



Public Member Functions

- [NL2SOLLeastSq \(Model &model\)](#)
standard constructor
- [~NL2SOLLeastSq \(\)](#)
destructor
- void [minimize_residuals \(\)](#)

Static Private Member Functions

- static void [calcr](#) (int *np, int *pp, Real *x, int *nfp, Real *r, int *ui, void *ur, Vf vf)
evaluator function for residual vector
- static void [calcj](#) (int *np, int *pp, Real *x, int *nfp, Real *J, int *ui, void *ur, Vf vf)
evaluator function for residual Jacobian

Private Attributes

- int [auxprt](#)
auxiliary printing bits (see [Dakota Ref Manual](#)): sum of 1 = x0prt (print initial guess) 2 = solprt (print final solution) 4 = statpr (print solution statistics) 8 = parprt (print nondefault parameters) 16 = dradpr (print bound constraint drops/adds) debug/verbose/normal use default = 31 (everything), quiet uses 3, silent uses 0.

- int **outlev**
frequency of output summary lines in number of iterations (debug/verbose/normal/quiet use default = 1, silent uses 0)
- Real **dltfdj**
finite-diff step size for computing Jacobian approximation (fd_gradient_step_size)
- Real **delta0**
finite-diff step size for gradient differences for H (a component of some covariance approximations, if desired) (fd_hessian_step_size)
- Real **dltfdc**
finite-diff step size for function differences for H (fd_hessian_step_size)
- int **mxfcsl**
function-evaluation limit (max_function_evaluations)
- int **mxiter**
iteration limit (max_iterations)
- Real **rfctol**
relative fn convergence tolerance (convergence_tolerance)
- Real **afctol**
absolute fn convergence tolerance (absolute_conv_tol)
- Real **xctol**
x-convergence tolerance (x_conv_tol)
- Real **sctol**
singular convergence tolerance (singular_conv_tol)
- Real **lmaxs**
radius for singular-convergence test (singular_radius)
- Real **xftol**
false-convergence tolerance (false_conv_tol)
- int **covreq**
kind of covariance required (covariance): 1 or -1 ==> $\sigma^2 H^{-1} J^T J H^{-1}$ 2 or -2 ==> $\sigma^2 H^{-1}$ 3 or -3 ==> $\sigma^2 (J^T J)^{-1}$ 1 or 2 ==> use gradient diffs to estimate H -1 or -2 ==> use function diffs to estimate H default = 0 (no covariance)
- int **rdreq**
whether to compute the regression diagnostic vector (regression_diagnostics)
- Real **fprec**

expected response function precision (`function_precision`)

- Real `lmax0`

initial trust-region radius (`initial_trust_radius`)

Static Private Attributes

- static `NL2SOLLeastSq * nl2solInstance`

pointer to the active object instance used within the static evaluator functions

10.66.1 Detailed Description

Wrapper class for the NL2SOL nonlinear least squares library.

The `NL2SOLLeastSq` class provides a wrapper for NL2SOL, a C library from Bell Labs. It uses a function pointer approach for which passed functions must be either global functions or static member functions.

10.66.2 Member Function Documentation

10.66.2.1 `void minimize_residuals ()` [virtual]

Details on the following subscript values appear in "Usage Summary for Selected Optimization Routines" by David M. Gay, Computing Science Technical Report No. 153, AT&T Bell Laboratories, 1990. <http://netlib.bell-labs.com/cm/cs/cstr/153.ps.gz>

Implements `LeastSq`.

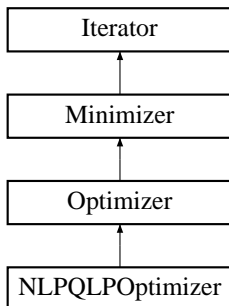
The documentation for this class was generated from the following files:

- `NL2SOLLeastSq.H`
- `NL2SOLLeastSq.C`

10.67 NLPQLPOptimizer Class Reference

Wrapper class for the NLPQLP optimization library, Version 2.0.

Inheritance diagram for NLPQLPOptimizer::



Public Member Functions

- [NLPQLPOptimizer \(Model &model\)](#)
constructor
- [~NLPQLPOptimizer \(\)](#)
destructor
- void [find_optimum \(\)](#)
Used within the optimizer branch for computing the optimal solution. Redefines the run_iterator virtual function for the optimizer branch.

Protected Member Functions

- virtual void [derived_pre_run \(\)](#)
performs run-time set up
- virtual void [derived_post_run \(\)](#)
performs final solution processing

Private Member Functions

- void [allocate_workspace \(\)](#)
Allocates workspace for the optimizer.

- void `deallocate_workspace ()`
Releases workspace memory.
- void `allocate_constraints ()`
Allocates constraint mappings.

Private Attributes

- int `L`
L : Number of parallel systems, i.e. function calls during line search at predetermined iterates. HINT: If only less than 10 parallel function evaluations are possible, it is recommended to apply the serial version by setting L=1.
- int `numEqConstraints`
numEqConstraints : Number of equality constraints.
- int `MMAX`
MMAX : Row dimension of array DG containing Jacobian of constraints. MMAX must be at least one and greater or equal to M.
- int `N`
N : Number of optimization variables.
- int `NMAX`
NMAX : Row dimension of C. NMAX must be at least two and greater than N.
- int `MNN2`
MNN2 : Must be equal to M+N+N+2.
- double * `X`
X(NMAX,L) : Initially, the first column of X has to contain starting values for the optimal solution. On return, X is replaced by the current iterate. In the driving program the row dimension of X has to be equal to NMAX. X is used internally to store L different arguments for which function values should be computed simultaneously.
- double * `F`
F(L) : On return, F(1) contains the final objective function value. F is used also to store L different objective function values to be computed from L iterates stored in X.
- double * `G`
G(MMAX,L) : On return, the first column of G contains the constraint function values at the final iterate X. In the driving program the row dimension of G has to be equal to MMAX. G is used internally to store L different set of constraint function values to be computed from L iterates stored in X.
- double * `DF`
DF(NMAX) : DF contains the current gradient of the objective function. In case of numerical differentiation and a distributed system (L>1), it is recommended to apply parallel evaluations of F to compute DF.

- double * **DG**
DG(MMAX,NMAX) : DG contains the gradients of the active constraints (ACTIVE(J)=.true.) at a current iterate X. The remaining rows are filled with previously computed gradients. In the driving program the row dimension of DG has to be equal to MMAX.
- double * **U**
U(MNN2) : U contains the multipliers with respect to the actual iterate stored in the first column of X. The first M locations contain the multipliers of the M nonlinear constraints, the subsequent N locations the multipliers of the lower bounds, and the final N locations the multipliers of the upper bounds. At an optimal solution, all multipliers with respect to inequality constraints should be nonnegative.
- double * **C**
C(NMAX,NMAX) : On return, C contains the last computed approximation of the Hessian matrix of the Lagrangian function stored in form of an LDL decomposition. C contains the lower triangular factor of an LDL factorization of the final quasi-Newton matrix (without diagonal elements, which are always one). In the driving program, the row dimension of C has to be equal to NMAX.
- double * **D**
D(NMAX) : The elements of the diagonal matrix of the LDL decomposition of the quasi-Newton matrix are stored in the one-dimensional array D.
- double **ACC**
ACC : The user has to specify the desired final accuracy (e.g. 1.0D-7). The termination accuracy should not be smaller than the accuracy by which gradients are computed.
- double **ACCQP**
ACCQP : The tolerance is needed for the QP solver to perform several tests, for example whether optimality conditions are satisfied or whether a number is considered as zero or not. If ACCQP is less or equal to zero, then the machine precision is computed by NLPQLP and subsequently multiplied by 1.0D+4.
- double **STPMIN**
*STPMIN : Minimum steplength in case of L>1. Recommended is any value in the order of the accuracy by which functions are computed. The value is needed to compute a steplength reduction factor by STPMIN**(1/L-1). If STPMIN<=0, then STPMIN=ACC is used.*
- int **MAXFUN**
MAXFUN : The integer variable defines an upper bound for the number of function calls during the line search (e.g. 20). MAXFUN is only needed in case of L=1, and must not be greater than 50.
- int **MAXIT**
MAXIT : Maximum number of outer iterations, where one iteration corresponds to one formulation and solution of the quadratic programming subproblem, or, alternatively, one evaluation of gradients (e.g. 100).
- int **MAX_NM**
MAX_NM : Stack size for storing merit function values at previous iterations for non-monotone line search (e.g. 10). In case of MAX_NM=0, monotone line search is performed.
- double **TOL_NM**

TOL_NM : Relative bound for increase of merit function value, if line search is not successful during the very first step. Must be non-negative (e.g. 0.1).

- int **IPRINT**

IPRINT : Specification of the desired output level. *IPRINT* = 0 : No output of the program. *IPRINT* = 1 : Only a final convergence analysis is given. *IPRINT* = 2 : One line of intermediate results is printed in each iteration. *IPRINT* = 3 : More detailed information is printed in each iteration step, e.g. variable, constraint and multiplier values. *IPRINT* = 4 : In addition to '*IPRINT*=3', merit function and steplength values are displayed during the line search.

- int **MODE**

MODE : The parameter specifies the desired version of NLPQLP. *MODE* = 0 : Normal execution (reverse communication!). *MODE* = 1 : The user wants to provide an initial guess for the multipliers in *U* and for the Hessian of the Lagrangian function in *C* and *D* in form of an LDL decomposition.

- int **IOUT**

IOUT : Integer indicating the desired output unit number, i.e. all write-statements start with 'WRITE(*IOUT*,...)'.

- int **IFAIL**

IFAIL : The parameter shows the reason for terminating a solution process. Initially *IFAIL* must be set to zero. On return *IFAIL* could contain the following values: *IFAIL* = -2 : Compute gradient values w.r.t. the variables stored in first column of *X*, and store them in *DF* and *DG*. Only derivatives for active constraints *ACTIVE*(*J*)=.TRUE. need to be computed. Then call NLPQLP again, see below. *IFAIL* = -1 : Compute objective fn and all constraint values subject the variables found in the first *L* columns of *X*, and store them in *F* and *G*. Then call NLPQLP again, see below. *IFAIL* = 0 : The optimality conditions are satisfied. *IFAIL* = 1 : The algorithm has been stopped after *MAXIT* iterations. *IFAIL* = 2 : The algorithm computed an uphill search direction. *IFAIL* = 3 : Underflow occurred when determining a new approximation matrix for the Hessian of the Lagrangian. *IFAIL* = 4 : The line search could not be terminated successfully. *IFAIL* = 5 : Length of a working array is too short. More detailed error information is obtained with '*IPRINT*>0'. *IFAIL* = 6 : There are false dimensions, for example *M*>*M*MAX, *N*>=*N*MAX, or *M*N2<>*M*+*N*+*N*+2. *IFAIL* = 7 : The search direction is close to zero, but the current iterate is still infeasible. *IFAIL* = 8 : The starting point violates a lower or upper bound. *IFAIL* = 9 : Wrong input parameter; i.e., *MODE*, LDL decomposition in *D* and *C* (in case of *MODE*=1), *IPRINT*, *IOUT* *IFAIL* = 10 : Internal inconsistency of the quadratic subproblem, division by zero. *IFAIL* > 100 : The solution of the quadratic programming subproblem has been terminated with an error message and *IFAIL* is set to *IFQL*+100, where *IFQL* denotes the index of an inconsistent constraint.

- double * **WA**

WA(*LWA*) : *WA* is a real working array of length *LWA*.

- int **LWA**

LWA : *LWA* value extracted from NLPQLP20.f.

- int * **KWA**

KWA(*LKWA*) : The user has to provide working space for an integer array.

- int **LKWA**

LKWA : *LKWA* should be at least *N*+10.

- int * **ACTIVE**

ACTIVE(LACTIV) : The logical array shows a user the constraints, which NLPQLP considers to be active at the last computed iterate, i.e. $G(J,X)$ is active, if and only if $ACTIVE(J)=.TRUE.$, $J=1,\dots,M$.

- int **LACTIVE**
*LACTIV : The length LACTIV of the logical array should be at least $2*M+10$.*
- int **LQL**
LQL : If $LQL = .TRUE.$, the quadratic programming subproblem is to be solved with a full positive definite quasi-Newton matrix. Otherwise, a Cholesky decomposition is performed and updated, so that the subproblem matrix contains only an upper triangular factor.
- **SizeList nonlinIneqConMappingIndices**
a list of indices for referencing the DAKOTA nonlinear inequality constraints used in computing the corresponding NLPQL constraints.
- **RealList nonlinIneqConMappingMultipliers**
a list of multipliers for mapping the DAKOTA nonlinear inequality constraints to the corresponding NLPQL constraints.
- **RealList nonlinIneqConMappingOffsets**
a list of offsets for mapping the DAKOTA nonlinear inequality constraints to the corresponding NLPQL constraints.
- **SizeList linIneqConMappingIndices**
a list of indices for referencing the DAKOTA linear inequality constraints used in computing the corresponding NLPQL constraints.
- **RealList linIneqConMappingMultipliers**
a list of multipliers for mapping the DAKOTA linear inequality constraints to the corresponding NLPQL constraints.
- **RealList linIneqConMappingOffsets**
a list of offsets for mapping the DAKOTA linear inequality constraints to the corresponding NLPQL constraints.

10.67.1 Detailed Description

Wrapper class for the NLPQLP optimization library, Version 2.0.

AN IMPLEMENTATION OF A SEQUENTIAL QUADRATIC PROGRAMMING METHOD FOR SOLVING
NONLINEAR OPTIMIZATION PROBLEMS BY DISTRIBUTED COMPUTING AND NON-MONOTONE
LINE SEARCH

This subroutine solves the general nonlinear programming problem

minimize $F(X)$ subject to $G(J,X) = 0$, $J=1,\dots,ME$ $G(J,X) \geq 0$, $J=ME+1,\dots,M$ $XL \leq X \leq XU$

and is an extension of the code NLPQLD. NLPQLP is specifically tuned to run under distributed systems. A new input parameter L is introduced for the number of parallel computers, that is the number of function calls to be executed simultaneously. In case of $L=1$, NLPQLP is identical to NLPQLD. Otherwise the line search is modified

to allow L parallel function calls in advance. Moreover the user has the opportunity to use distributed function calls for evaluating gradients.

The algorithm is a modification of the method of Wilson, Han, and Powell. In each iteration step, a linearly constrained quadratic programming problem is formulated by approximating the Lagrangian function quadratically and by linearizing the constraints. Subsequently, a one-dimensional line search is performed with respect to an augmented Lagrangian merit function to obtain a new iterate. Also the modified line search algorithm guarantees convergence under the same assumptions as before.

For the new version, a non-monotone line search is implemented which allows to increase the merit function in case of instabilities, for example caused by round-off errors, errors in gradient approximations, etc.

The subroutine contains the option to predetermine initial guesses for the multipliers or the Hessian of the Lagrangian function and is called by reverse communication.

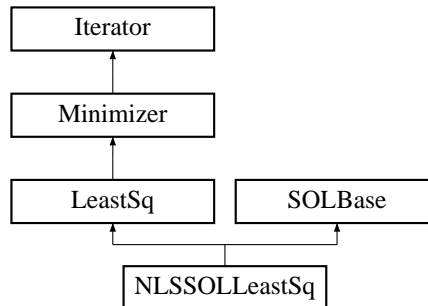
The documentation for this class was generated from the following files:

- NLPQLPOptimizer.H
- NLPQLPOptimizer.C

10.68 NLSSOLLeastSq Class Reference

Wrapper class for the NLSSOL nonlinear least squares library.

Inheritance diagram for NLSSOLLeastSq::



Public Member Functions

- [NLSSOLLeastSq \(Model &model\)](#)
standard constructor
- [~NLSSOLLeastSq \(\)](#)
destructor
- void [minimize_residuals \(\)](#)
Used within the least squares branch for minimizing the sum of squares residuals. Redefines the run_iterator virtual function for the least squares branch.

Static Private Member Functions

- static void [least_sq_eval](#) (int &mode, int &m, int &n, int &nrowfj, double *x, double *f, double *gradf, int &nstate)
Evaluator for NLSSOL: computes the values and first derivatives of the least squares terms (passed by function pointer to NLSSOL).

Static Private Attributes

- static [NLSSOLLeastSq * nlssolInstance](#)
pointer to the active object instance used within the static evaluator functions in order to avoid the need for static data

10.68.1 Detailed Description

Wrapper class for the NLSSOL nonlinear least squares library.

The `NLSSOLLeastSq` class provides a wrapper for NLSSOL, a Fortran 77 sequential quadratic programming library from Stanford University marketed by Stanford Business Associates. It uses a function pointer approach for which passed functions must be either global functions or static member functions. Any nonstatic attribute used within static member functions must be either local to that function or accessed through a static pointer.

The user input mappings are as follows: `max_function_evaluations` is implemented directly in `NLSSOLLeastSq`'s evaluator functions since there is no NLSSOL parameter equivalent, and `max_iterations`, `convergence_tolerance`, `output_verbosity`, `verify_level`, `function_precision`, and `linesearch_tolerance` are mapped into NLSSOL's "Major Iteration Limit", "Optimality Tolerance", "Major Print Level" (`verbose`: Major Print Level = 20; `quiet`: Major Print Level = 10), "Verify Level", "Function Precision", and "Linesearch Tolerance" parameters, respectively, using NLSSOL's `npoptn()` subroutine (as wrapped by `npoptn2()` from the `npoptn_wrapper.f` file). Refer to [Gill, P.E., Murray, W., Saunders, M.A., and Wright, M.H., 1986] for information on NLSSOL's optional input parameters and the `npoptn()` subroutine.

The documentation for this class was generated from the following files:

- `NLSSOLLeastSq.H`
- `NLSSOLLeastSq.C`

10.69 NoDBBaseConstructor Struct Reference

Dummy struct for overloading constructors used in on-the-fly instantiations.

Public Member Functions

- [NoDBBaseConstructor](#) (int=0)
C++ structs can have constructors.

10.69.1 Detailed Description

Dummy struct for overloading constructors used in on-the-fly instantiations.

[NoDBBaseConstructor](#) is used to overload the constructor used for on-the-fly iterator instantiations in which [ProblemDescDB](#) queries cannot be used. Putting this struct here avoids circular dependencies.

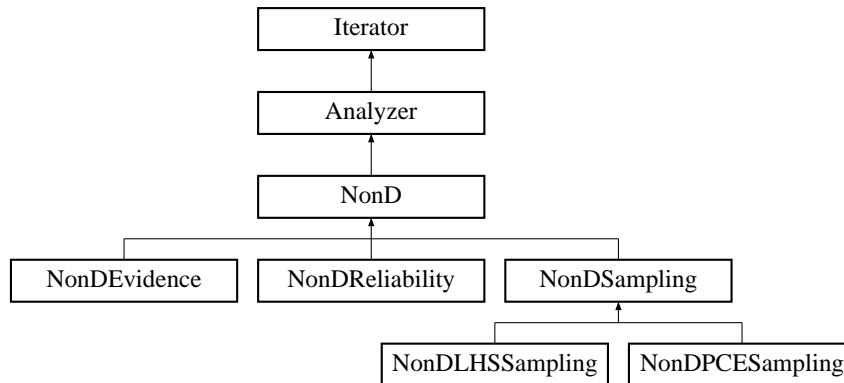
The documentation for this struct was generated from the following file:

- `global_defs.h`

10.70 NonD Class Reference

Base class for all nondeterministic iterators (the DAKOTA/UQ branch).

Inheritance diagram for NonD::



Protected Member Functions

- [NonD \(Model &model\)](#)
constructor
- [NonD \(NoDBBaseConstructor, Model &model\)](#)
alternate constructor for sample generation and evaluation "on the fly"
- [NonD \(NoDBBaseConstructor, const RealVector &lower_bnds, const RealVector &upper_bnds\)](#)
alternate constructor for sample generation "on the fly"
- [~NonD \(\)](#)
destructor
- `void run ()`
redefines the main iterator hierarchy virtual function to invoke quantify_uncertainty
- `const Response & response_results () const`
return the final statistics from the nondeterministic iteration
- `void response_results_active_set (const ActiveSet &set)`
set the active set within finalStatistics
- `virtual void quantify_uncertainty ()=0`

performs a forward uncertainty propagation of parameter distributions into response statistics

Protected Attributes

- [RealMatrix uncertainCorrelations](#)
uncertain variable correlation matrix (rank correlations for sampling and correlation coefficients for analytic reliability)
- size_t [numNormalVars](#)
number of normal uncertain variables
- size_t [numLognormalVars](#)
number of lognormal uncertain variables
- size_t [numUniformVars](#)
number of uniform uncertain variables
- size_t [numLoguniformVars](#)
number of loguniform uncertain variables
- size_t [numTriangularVars](#)
number of triangular uncertain variables
- size_t [numBetaVars](#)
number of beta uncertain variables
- size_t [numGammaVars](#)
number of gamma uncertain variables
- size_t [numGumbelVars](#)
number of gumbel uncertain variables
- size_t [numFrechetVars](#)
number of frechet uncertain variables
- size_t [numWeibullVars](#)
number of weibull uncertain variables
- size_t [numHistogramVars](#)
number of histogram uncertain variables
- size_t [numIntervalVars](#)
number of interval uncertain variables
- size_t [numUncertainVars](#)

total number of uncertain variables

- `size_t numResponseFunctions`
number of response functions
- `RealVector meanStats`
means of response functions calculated in `compute_statistics()`
- `RealVector stdDevStats`
std deviations of response functions (calculated in `compute_statistics()`)
- `RealVectorArray requestedRespLevels`
requested response levels for all response functions
- `RealVectorArray computedProbLevels`
output probability levels for all response functions resulting from `requestedRespLevels`
- `RealVectorArray computedRelLevels`
output reliability levels for all response functions resulting from `requestedRespLevels`
- `RealVectorArray requestedProbLevels`
requested probability levels for all response functions
- `RealVectorArray requestedRelLevels`
requested reliability (beta) levels for all response functions
- `RealVectorArray computedRespLevels`
output response levels for all response functions resulting from either `requestedProbLevels` or `requestedRelLevels`
- `size_t totalLevelRequests`
total number of levels specified within `requestedRespLevels`, `requestedProbLevels`, and `requestedRelLevels`
- `bool cdfFlag`
flag for type of probabilities/reliabilities used in mappings: cumulative/CDF (true) or complementary/CCDF (false)
- `bool respLevelProbFlag`
flag to indicate mapping of $z \rightarrow p$ (true) or $z \rightarrow \beta$ (false)
- `bool correlationFlag`
flag for indicating if correlation exists among the uncertain variables
- `bool strategyFlag`
flag indicating a strategy other than "single_method". Used to compute additional statistics for use at the strategy level or to deactivate additional output not needed for strategy executions.
- `Response finalStatistics`

final statistics from the uncertainty propagation used in strategies: response means, standard deviations, and probabilities of failure

Private Member Functions

- void `distribute_levels` (`RealVectorArray` &levels)

convenience function for distributing a vector of levels among multiple response functions if a short-hand specification is employed.

10.70.1 Detailed Description

Base class for all nondeterministic iterators (the DAKOTA/UQ branch).

The base class for nondeterministic iterators consolidates uncertain variable data and probabilistic utilities for inherited classes.

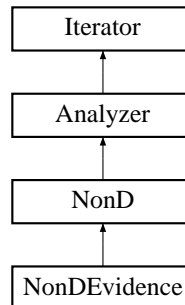
The documentation for this class was generated from the following files:

- DakotaNonD.H
- DakotaNonD.C

10.71 NonDEvidence Class Reference

Class for the Dempster-Shafer Evidence Theory methods within DAKOTA/UQ.

Inheritance diagram for NonDEvidence::



Public Member Functions

- [NonDEvidence](#) ([Model](#) &model)
constructor
- [~NonDEvidence](#) ()
destructor
- void [quantify_uncertainty](#) ()
performs an epistemic uncertainty propagation using Dempster-Shafer evidence theory methods which solve for cumulative distribution functions of belief and plausibility
- void [print_results](#) (ostream &s) const
print the cumulative distribution functions for belief and plausibility

Private Member Functions

- void [calculate_basic_prob_intervals](#) ()
convenience function for encapsulating the calculation of basic probability assignments for input interval combinations
- void [calculate_maxmin_per_interval](#) ()
convenience function for encapsulating the determination of maximum and minimum values within each input interval combination (cell).

- void `calculate_cum_belief_plaus ()`
convenience function for determining the cumulative distribution functions of belief and plausibility, based on the max and mins per interval cell

Private Attributes

- const int `originalSeed`
the user seed specification (default is 0)
- int `numSamples`
the number of samples used in the surrogate
- int `NV`
Size variable for DDS arrays.
- int `NCMB`
Size variable for DDS arrays.
- int `MAXINTVLS`
Size variable for DDS arrays.
- Real `Y`
Temporary output variable.
- Real * `BPA`
Internal DDS array.
- Real * `VMIN`
Internal DDS array.
- Real * `VMAX`
Internal DDS array.
- Real * `BPAC`
Internal DDS array.
- Real * `CMIN`
Internal DDS Array.
- Real * `CMAX`
Internal DDS Array.
- Real * `X`
Internal DDS Array.

- `int * NI`
Internal DDS array.
- `int * IP`
Internal DDS array.

10.71.1 Detailed Description

Class for the Dempster-Shafer Evidence Theory methods within DAKOTA/UQ.

The `NonDEvidence` class implements the propagation of epistemic uncertainty using Dempster-Shafer theory of evidence. In this approach, one assigns a set of basic probability assignments (BPA) to intervals defined for the uncertain variables. Input interval combinations are calculated, along with their BPA. Currently, the response function is evaluated at a set of sample points, then a response surface is constructed which is sampled extensively to find the minimum and maximum within each input interval cell, corresponding to the belief and plausibility within that cell, respectively. This data is then aggregated to calculate cumulative distribution functions for belief and plausibility.

10.71.2 Member Data Documentation

10.71.2.1 `int NV` [private]

Size variable for DDS arrays.

NV = number of interval variables

10.71.2.2 `int NCMB` [private]

Size variable for DDS arrays.

NCMB = number of cell combinations

10.71.2.3 `int MAXINTVLS` [private]

Size variable for DDS arrays.

MAXINTVLS = maximum number of intervals per individual interval var

10.71.2.4 `Real Y` [private]

Temporary output variable.

Y = current output to be placed in cell

10.71.2.5 Real* BPA [private]

Internal DDS array.

Basic Probability Assignments

10.71.2.6 Real* VMIN [private]

Internal DDS array.

Minimum ends of intervals.

10.71.2.7 Real* VMAX [private]

Internal DDS array.

Maximum ends of intervals.

10.71.2.8 Real* BPAC [private]

Internal DDS array.

Basic Probability Combinations.

10.71.2.9 Real* CMIN [private]

Internal DDS [Array](#).

Minimum per cell combination.

10.71.2.10 Real* CMAX [private]

Internal DDS [Array](#).

Maximum per cell combination.

10.71.2.11 Real* X [private]

Internal DDS [Array](#).

X per cell combination.

10.71.2.12 int* NI [private]

Internal DDS array.

Number of intervals per interval variable

10.71.2.13 `int* IP` [private]

Internal DDS array.

Sort order for combinations

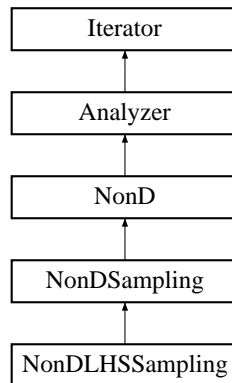
The documentation for this class was generated from the following files:

- NonDEvidence.H
- NonDEvidence.C

10.72 NonDLHSSampling Class Reference

Performs LHS and Monte Carlo sampling for uncertainty quantification.

Inheritance diagram for NonDLHSSampling::



Public Member Functions

- [NonDLHSSampling](#) ([Model](#) &model)
constructor
- [NonDLHSSampling](#) ([Model](#) &model, int samples, int seed)
alternate constructor for sample generation and evaluation "on the fly"
- [NonDLHSSampling](#) (int samples, int seed, const [RealVector](#) &lower_bnds, const [RealVector](#) &upper_bnds)
alternate constructor for sample generation "on the fly"
- [~NonDLHSSampling](#) ()
destructor
- void [quantify_uncertainty](#) ()
performs a forward uncertainty propagation by using LHS to generate a set of parameter samples, performing function evaluations on these parameter samples, and computing statistics on the ensemble of results.
- void [print_results](#) (ostream &s) const
print the final statistics

Private Attributes

- bool [allVarsFlag](#)
flags DACE mode using all variables
- bool [varBasedDecompFlag](#)
flags computation of VBD

10.72.1 Detailed Description

Performs LHS and Monte Carlo sampling for uncertainty quantification.

The Latin Hypercube Sampling (LHS) package from Sandia Albuquerque's Risk and Reliability organization provides comprehensive capabilities for Monte Carlo and Latin Hypercube sampling within a broad array of user-specified probabilistic parameter distributions. It enforces user-specified rank correlations through use of a mixing routine. The [NonDLHSSampling](#) class provides a C++ wrapper for the LHS library and is used for performing forward propagations of parameter uncertainties into response statistics.

10.72.2 Constructor & Destructor Documentation

10.72.2.1 [NonDLHSSampling](#) (*Model & model*)

constructor

This constructor is called for a standard letter-envelope iterator instantiation. In this case, `set_db_list_nodes` has been called and `probDescDB` can be queried for settings from the method specification.

10.72.2.2 [NonDLHSSampling](#) (*Model & model, int samples, int seed*)

alternate constructor for sample generation and evaluation "on the fly"

This alternate constructor is used by [NonDEvidence](#) for generation and evaluation of Model-based sample sets. It is `_not_` a letter-envelope instantiation and a `set_db_list_nodes` has not been performed. It is called with all needed data passed through the constructor. It's purpose is to avoid the need for a separate LHS specification within methods that use LHS sampling.

10.72.2.3 [NonDLHSSampling](#) (*int samples, int seed, const RealVector & lower_bnds, const RealVector & upper_bnds*)

alternate constructor for sample generation "on the fly"

This alternate constructor is used by [ConcurrentStrategy](#) for generation of uniform, uncorrelated sample sets. It is `_not_` a letter-envelope instantiation and a `set_db_list_nodes` has not been performed. It is called with all needed data passed through the constructor and is designed to allow more flexibility in variables set definition (i.e., relax

connection to a variables specification and allow sampling over parameter sets such as multiobjective weights). In this case, a [Model](#) is not used and the object must only be used for sample generation (no evaluation).

10.72.3 Member Function Documentation

10.72.3.1 void quantify_uncertainty() [virtual]

performs a forward uncertainty propagation by using LHS to generate a set of parameter samples, performing function evaluations on these parameter samples, and computing statistics on the ensemble of results.

Loop over the set of samples and compute responses. Compute statistics on the set of responses if statsFlag is set.

Implements [NonD](#).

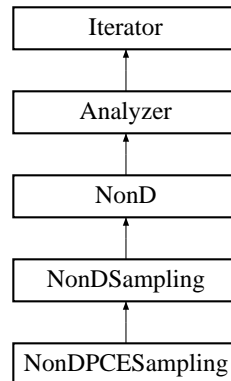
The documentation for this class was generated from the following files:

- NonDLHSSampling.H
- NonDLHSSampling.C

10.73 NonDPCESampling Class Reference

Stochastic finite element approach to uncertainty quantification using polynomial chaos expansions.

Inheritance diagram for NonDPCESampling::



Public Member Functions

- [NonDPCESampling \(Model &model\)](#)
constructor
- [~NonDPCESampling \(\)](#)
destructor
- void [quantify_uncertainty \(\)](#)
perform a forward uncertainty propagation using SFEM/PCE methods
- void [print_results \(ostream &s\) const](#)
print the final statistics and PCE coefficient array

Private Attributes

- [RealVectorArray coeffArray](#)
Array containing Polynomial Chaos coefficients, one real vector per response function.
- int [highestOrder](#)
Highest order of Hermite Polynomials in Expansion.
- int [numChaos](#)

Number of terms in Polynomial Chaos Expansion.

10.73.1 Detailed Description

Stochastic finite element approach to uncertainty quantification using polynomial chaos expansions.

The NonDPCE class uses a polynomial chaos expansion (PCE) approach to approximate the effect of parameter uncertainties on response functions of interest. It utilizes the HermiteSurf and HermiteChaos classes to perform the PCE.

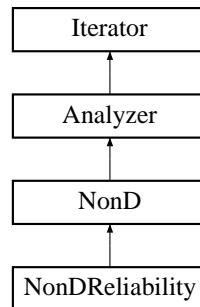
The documentation for this class was generated from the following files:

- NonDPCESampling.H
- NonDPCESampling.C

10.74 NonDReliability Class Reference

Class for the reliability methods within DAKOTA/UQ.

Inheritance diagram for NonDReliability::



Public Member Functions

- [NonDReliability \(Model &model\)](#)
constructor
- [~NonDReliability \(\)](#)
destructor
- void [quantify_uncertainty \(\)](#)
performs an uncertainty propagation using analytical reliability methods which solve constrained optimization problems to obtain approximations of the cumulative distribution function of response
- void [print_results \(ostream &s\) const](#)
print the approximate mean, standard deviation, and importance factors when using the mean value method or the CDF/CCDF information when using MPP-search-based reliability methods
- [String uses_method \(\) const](#)
return name of active MPP optimizer
- void [method_recourse \(\)](#)
perform an MPP optimizer method switch due to a detected conflict

Private Member Functions

- void [initialize_random_variables \(\)](#)

convenience fn for initializing ranVarType, ranVarMeansX, ranVarStdDevsX

- void [initial_taylor_series](#) ()
convenience function for performing the initial limit state Taylor-series approximation
- void [mean_value](#) ()
convenience function for encapsulating the simple Mean Value computation of approximate statistics and importance factors
- void [mpp_search](#) ()
convenience function for encapsulating the reliability methods that employ a search for the most probable point (AMV, AMV+, FORM, SORM)
- void [initialize_class_data](#) ()
convenience function for initializing class scope arrays
- void [initialize_level_data](#) ()
convenience function for initializing/warm starting MPP search data for each response function prior to level 0
- void [initialize_mpp_search_data](#) ()
convenience function for initializing/warm starting MPP search data for each z/p/beta level for each response function
- void [update_mpp_search_data](#) (const [Variables](#) &vars_star, const [Response](#) &resp_star)
convenience function for updating MPP search data for each z/p/beta level for each response function
- void [update_level_data](#) ([RealVector](#) &final_stats, [RealMatrix](#) &final_stat_grads)
convenience function for updating z/p/beta level data and final statistics following MPP convergence
- void [update_limit_state_surrogate](#) ()
convenience function for passing the latest variables/response data to limitStateSurrogate
- void [assign_mean_data](#) ()
update mostProbPointX/U, computedRespLevel, fnGradX/U, and fnHessX/U from ranVarMeansX/U, fnValsMeanX, fnGradsMeanX, and fnHessiansMeanX
- void [g_eval](#) (int &mode, const [Epetra_SerialDenseVector](#) &u)
convenience function for evaluating fnVal(u), fnGradU(u), and fnHessU(u) as required by [RIA_constraint_eval\(\)](#) and [PMA_objective_eval\(\)](#)
- void [dg_ds_eval](#) (const [Epetra_SerialDenseVector](#) &x_vars, const [Epetra_SerialDenseVector](#) &fn_grad_x, [RealMatrix](#) &final_stat_grads)
convenience function for evaluating dg/ds
- void [trans_U_to_X](#) (const [Epetra_SerialDenseVector](#) &u_vars, [Epetra_SerialDenseVector](#) &x_vars)
Transformation routine from u-space of uncorrelated standard normal variables to x-space of correlated random variables.

- void [trans_U_to_Z](#) (const Epetra_SerialDenseVector &u_vars, Epetra_SerialDenseVector &z_vars)
Transformation routine from u-space of uncorrelated standard normal variables to z-space of correlated standard normal variables.
- void [trans_Z_to_X](#) (const Epetra_SerialDenseVector &z_vars, Epetra_SerialDenseVector &x_vars)
Transformation routine from z-space of correlated standard normal variables to x-space of correlated random variables.
- void [trans_X_to_U](#) (const Epetra_SerialDenseVector &x_vars, Epetra_SerialDenseVector &u_vars)
Transformation routine from x-space of correlated random variables to u-space of uncorrelated standard normal variables.
- void [trans_X_to_Z](#) (const Epetra_SerialDenseVector &x_vars, Epetra_SerialDenseVector &z_vars)
Transformation routine from x-space of correlated random variables to z-space of correlated standard normal variables.
- void [trans_Z_to_U](#) (Epetra_SerialDenseVector &z_vars, Epetra_SerialDenseVector &u_vars)
Transformation routine from z-space of correlated standard normal variables to u-space of uncorrelated standard normal variables.
- void [trans_grad_X_to_U](#) (const Epetra_SerialDenseVector &fn_grad_x, Epetra_SerialDenseVector &fn_grad_u, const Epetra_SerialDenseVector &x_vars)
Transformation routine for gradient vector from x-space to u-space.
- void [trans_hess_X_to_U](#) (const Epetra_SerialSymDenseMatrix &fn_hess_x, Epetra_SerialSymDenseMatrix &fn_hess_u, const Epetra_SerialDenseVector &x_vars, const Epetra_SerialDenseVector &fn_grad_x)
Transformation routine for Hessian matrix from x-space to u-space.
- void [jacobian_dX_dU](#) (const Epetra_SerialDenseVector &x_vars, Epetra_SerialDenseMatrix &jacobian_xu)
Jacobian of $x(u)$ mapping obtained from $dX/dZ dZ/dU$.
- void [jacobian_dX_dZ](#) (const Epetra_SerialDenseVector &x_vars, Epetra_SerialDenseMatrix &jacobian_xz)
Jacobian of $x(z)$ mapping obtained from differentiation of [trans_Z_to_X\(\)](#).
- void [jacobian_dU_dX](#) (const Epetra_SerialDenseVector &x_vars, Epetra_SerialDenseMatrix &jacobian_ux)
Jacobian of $u(x)$ mapping obtained from $dU/dZ dZ/dX$.
- void [jacobian_dZ_dX](#) (const Epetra_SerialDenseVector &x_vars, Epetra_SerialDenseMatrix &jacobian_zx)
Jacobian of $z(x)$ mapping obtained from differentiation of [trans_X_to_Z\(\)](#).
- void [jacobian_dX_dS](#) (const Epetra_SerialDenseVector &x_vars, Epetra_SerialDenseMatrix &jacobian_xs)

Design Jacobian of $x(u,s)$ mapping obtained from differentiation of `trans_U_to_X()` with respect to distribution parameters S .

- void `numerical_design_jacobian` (const Epetra_SerialDenseVector &x_vars, bool xs, Epetra_SerialDenseMatrix &num_jacobian_xs, bool zs, Epetra_SerialDenseMatrix &num_jacobian_zs)

Computes numerical dx/ds and dz/ds Jacobians as requested by xs and zs booleans.
- void `hessian_d2X_dU2` (const Epetra_SerialDenseVector &x_vars, Array< Epetra_SerialSymDenseMatrix > &hessian_xu)

Hessian of $x(u)$ mapping obtained from $dZ/dU^T d^2X/dZ^2 dZ/dU$.
- void `hessian_d2X_dZ2` (const Epetra_SerialDenseVector &x_vars, Array< Epetra_SerialSymDenseMatrix > &hessian_xz)

Hessian of $x(z)$ mapping obtained from differentiation of `jacobian_dX_dZ()`.
- void `trans_correlations` ()

As part of the Nataf distribution model (Der Kiureghian & Liu, 1986), this procedure modifies the user-specified correlation matrix (`corrMatrix`) and decomposes it into its Cholesky factor (`corrCholeskyFactor`).
- void `verify_trans_jacobian_hessian` (const Epetra_SerialDenseVector &v0)

routine for verification of transformation Jacobian/Hessian terms
- void `verify_design_jacobian` (const Epetra_SerialDenseVector &u0)

routine for verification of design Jacobian terms
- const Real & `distribution_parameter` (const size_t &index)

return a particular random variable distribution parameter
- void `distribution_parameter` (const size_t &index, const Real ¶m)

set a particular random variable distribution parameter and update derived quantities
- Real `probability` (const Real &beta)

Convert beta to a probability using either a first-order or second-order integration.
- Real `reliability` (const Real &p)

Convert probability to beta using the inverse of a first-order or second-order integration.
- void `principal_curvatures` ()

Compute the κU vector of principal curvatures from `fnHessU`.
- Real `phi` (const Real &beta)

Standard normal density function.
- Real `Phi` (const Real &beta)

Standard normal cumulative distribution function.
- Real `Phi_inverse` (const Real &p)

Inverse of standard normal cumulative distribution function.

- Real `erf_inverse` (const Real &p)
Inverse of error function used in `Phi_inverse()`.
- Real `cdf_beta_Pinv` (const Real &normcdf, const Real &alpha, const Real &beta)
Inverse of standard beta CDF (not supported by GSL).

Static Private Member Functions

- static void `RIA_objective_eval` (int &mode, int &n, double *u, double &f, double *grad_f, int &)
static function used by NPSOL as the objective function in the Reliability Index Approach (RIA) problem formulation. This equality-constrained optimization problem performs the search for the most probable point (MPP) with the objective function of $(\text{norm } u)^2$.
- static void `RIA_constraint_eval` (int &mode, int &ncnln, int &n, int &nrowj, int *needc, double *u, double *c, double *cjac, int &nstate)
static function used by NPSOL as the constraint function in the Reliability Index Approach (RIA) problem formulation. This equality-constrained optimization problem performs the search for the most probable point (MPP) with the constraint of $G(u) = \text{response level}$.
- static void `PMA_objective_eval` (int &mode, int &n, double *u, double &f, double *grad_f, int &)
static function used by NPSOL as the objective function in the Performance Measure Approach (PMA) problem formulation. This equality-constrained optimization problem performs the search for the most probable point (MPP) with the objective function of $G(u)$.
- static void `PMA_constraint_eval` (int &mode, int &ncnln, int &n, int &nrowj, int *needc, double *u, double *c, double *cjac, int &nstate)
static function used by NPSOL as the constraint function in the Performance Measure Approach (PMA) problem formulation. This equality-constrained optimization problem performs the search for the most probable point (MPP) with the constraint of $(\text{norm } u)^2 = \text{beta}^2$.
- static void `RIA_objective_eval` (int mode, int n, const NEWMAT::ColumnVector &u, NEWMAT::Real &f, NEWMAT::ColumnVector &grad_f, int &result_mode)
static function used by OPT++ as the objective function in the Reliability Index Approach (RIA) problem formulation. This equality-constrained optimization problem performs the search for the most probable point (MPP) with the objective function of $(\text{norm } u)^2$.
- static void `RIA_constraint_eval` (int mode, int n, const NEWMAT::ColumnVector &u, NEWMAT::ColumnVector &g, NEWMAT::Matrix &grad_g, int &result_mode)
static function used by OPT++ as the constraint function in the Reliability Index Approach (RIA) problem formulation. This equality-constrained optimization problem performs the search for the most probable point (MPP) with the constraint of $G(u) = \text{response level}$.
- static void `PMA_objective_eval` (int mode, int n, const NEWMAT::ColumnVector &u, NEWMAT::Real &f, NEWMAT::ColumnVector &grad_f, int &result_mode)

static function used by OPT++ as the objective function in the Performance Measure Approach (PMA) problem formulation. This equality-constrained optimization problem performs the search for the most probable point (MPP) with the objective function of $G(u)$.

- static void [PMA_constraint_eval](#) (int mode, int n, const NEWMAT::ColumnVector &u, NEWMAT::ColumnVector &g, NEWMAT::Matrix &grad_g, int &result_mode)
static function used by OPT++ as the constraint function in the Performance Measure Approach (PMA) problem formulation. This equality-constrained optimization problem performs the search for the most probable point (MPP) with the constraint of $(\text{norm } u)^2 = \text{beta}^2$.

Private Attributes

- [Approximation limitStateSurrogate](#)
Approximation instance used for TANA-3 and Taylor series limit state approximations.
- size_t [numRelAnalyses](#)
number of invocations of [quantify_uncertainty\(\)](#)
- size_t [approxIters](#)
number of AMV+/TANA approximation cycles for the current respFnCount/levelCount
- bool [approxConverged](#)
indicates convergence of approximation-based iterations
- Epetra_SerialDenseVector [fnGradX](#)
actual x-space gradient for current function from most recent response evaluation
- Epetra_SerialDenseVector [fnGradU](#)
u-space gradient for current function updated from fnGradX and Jacobian dx/du
- Epetra_SerialSymDenseMatrix [fnHessX](#)
actual x-space Hessian for current function from most recent response evaluation
- Epetra_SerialSymDenseMatrix [fnHessU](#)
u-space Hessian for current function updated from fnHessX and Jacobian dx/du
- Epetra_SerialDenseVector [kappaU](#)
principal curvatures derived from eigenvalues of orthonormal transformation of fnHessU
- Real [modelFnVal](#)
x-space/u-space value for current function from (linearized) model used in RIA/PMA objective/constraint evaluators
- Epetra_SerialDenseVector [modelFnGradU](#)
u-space gradient for current function from (linearized) model used in RIA/PMA objective/constraint evaluators

- `Epetra_SerialSymDenseMatrix` [modelFnHessU](#)
u-space Hessian for current function from (linearized) model used in RIA/PMA objective/constraint evaluators
- `Epetra_SerialDenseVector` [fnValsMeanX](#)
response function values evaluated at mean x
- `Epetra_SerialDenseMatrix` [fnGradsMeanX](#)
response function gradients evaluated at mean x
- `Array< Epetra_SerialSymDenseMatrix >` [fnHessiansMeanX](#)
response function Hessians evaluated at mean x
- `RealVector` [medianFnVals](#)
response function values evaluated at $u=0$ (for first-order integration, $p=0.5$ -> median function values). Used to determine the sign of beta.
- `RealVector` [initialPtU](#)
initial guess for MPP search in u-space
- `Epetra_SerialDenseVector` [mostProbPointX](#)
location of MPP in x-space
- `Epetra_SerialDenseVector` [mostProbPointU](#)
location of MPP in u-space
- `RealVectorArray` [prevMPPUlev0](#)
array of converged MPP's in u-space for level 0. Used for warm-starting initialPtU within RBDO.
- `RealMatrix` [prevFnGradDLev0](#)
matrix of limit state sensitivities w.r.t. inactive/design variables for level 0. Used for warm-starting initialPtU within RBDO.
- `RealMatrix` [prevFnGradUlev0](#)
matrix of limit state sensitivities w.r.t. active/uncertain variables for level 0. Used for warm-starting initialPtU within RBDO.
- `RealVector` [prevICVars](#)
previous design vector. Used for warm-starting initialPtU within RBDO.
- `IntArray` [prevCumASVLev0](#)
accumulation (using $|=$) of all previous design ASV's from requested finalStatistics. Used to detect availability of prevFnGradDLev0 data for warm-starting initialPtU within RBDO.
- `IntArray` [ranVarType](#)
vector of indices indicating the type of each uncertain variable
- `Epetra_SerialDenseVector` [ranVarMeansX](#)

vector of means for all uncertain random variables in x-space

- Epetra_SerialDenseVector [ranVarMeansU](#)
vector of means for all uncertain random variables in u-space
- Epetra_SerialDenseVector [ranVarStdDevsX](#)
vector of standard deviations for all uncertain random variables in x-space
- Epetra_SerialSymDenseMatrix [corrMatrix](#)
Epetra copy of [uncertainCorrelations](#).
- Epetra_SerialDenseMatrix [corrCholeskyFactor](#)
cholesky factor of [corrMatrix](#)
- int [respFnCount](#)
counter for which response function is being analyzed
- size_t [levelCount](#)
counter for which response/probability level is being analyzed
- size_t [statCount](#)
counter for which final statistic is being computed
- Real [requestedRespLevel](#)
the response level target for the current response function
- Real [requestedCDFProbLevel](#)
the CDF probability level target for the current response function
- Real [requestedCDFRelLevel](#)
the CDF reliability level target for the current response function
- Real [computedRespLevel](#)
output response level calculated
- Real [computedRelLevel](#)
output reliability level calculated
- short [mppSearchType](#)
the MPP search type selection: MV, x/u-space AMV, x/u-space AMV+, or FORM
- bool [npsolFlag](#)
flag representing the optimization MPP search algorithm selection (SQP or NIP)
- bool [warmStartFlag](#)
flag indicating the use of warm starts

- bool [nipModeOverrideFlag](#)
flag indicating the use of move overrides within OPT++ NIP
- short [integrationOrder](#)
integration order (1 or 2) provided by integration specification
- short [taylorOrder](#)
order of Taylor series approximations (1 or 2) in MV/AMV/AMV+ derived from hessianType
- [RealMatrix impFactor](#)
importance factors predicted by MV
- int [npsolDerivLevel](#)
derivative level for NPSOL executions (1 = analytic grads of objective fn, 2 = analytic grads of constraints, 3 = analytic grads of both).
- const Real [Pi](#)
the value for Pi used in several numerical routines

Static Private Attributes

- static [NonDReliability * nondRelInstance](#)
pointer to the active object instance used within the static evaluator functions in order to avoid the need for static data

10.74.1 Detailed Description

Class for the reliability methods within DAKOTA/UQ.

The [NonDReliability](#) class implements the following reliability methods through the support of different limit state approximation and integration options: mean value (MV), advanced mean value method (AMV) in x- or u-space, iterated advanced mean value method (AMV+) in x- or u-space, first order reliability method (FORM), and second order reliability method (SORM). The AMV/AMV+/FORM/SORM variants employ an optimizer (currently NPSOL SQP or OPT++ NIP) to solve an equality-constrained optimization problem for the most probable point (MPP).

10.74.2 Member Function Documentation

10.74.2.1 void initialize_random_variables() [private]

convenience fn for initializing ranVarType, ranVarMeansX, ranVarStdDevsX

Build ranVar arrays containing the uncertain variable distribution types and their corresponding means/standard deviations.

10.74.2.2 void initial_taylor_series() [private]

convenience function for performing the initial limit state Taylor-series approximation

An initial first- or second-order Taylor-series approximation is required for MV/AMV/AMV+/TANA or for the case where meanStats or stdDevStats (from MV) are required within finalStatistics for subIterator usage of [NonDReliability](#).

10.74.2.3 void initialize_class_data() [private]

convenience function for initializing class scope arrays

Initialize class-scope arrays and perform other start-up activities, such as evaluating median limit state responses.

10.74.2.4 void initialize_level_data() [private]

convenience function for initializing/warm starting MPP search data for each response function prior to level 0

For a particular response function prior to the first z/p/beta level, initialize/warm-start optimizer initial guess (initialPtU), expansion point (mostProbPointX/U), and associated response data (computedRespLevel, fnGradX/U, and fnHessX/U).

10.74.2.5 void initialize_mpp_search_data() [private]

convenience function for initializing/warm starting MPP search data for each z/p/beta level for each response function

For a particular response function at a particular z/p/beta level, warm-start or reset the optimizer initial guess (initialPtU), expansion point (mostProbPointX/U), and associated response data (computedRespLevel, fnGradX/U, and fnHessX/U).

10.74.2.6 void update_mpp_search_data(const Variables & vars_star, const Response & resp_star) [private]

convenience function for updating MPP search data for each z/p/beta level for each response function

Includes case-specific logic for updating MPP search data for the AMV/AMV+/TANA/NO_APPROX methods.

10.74.2.7 `void update_level_data (RealVector & final_stats, RealMatrix & final_stat_grads)`
`[private]`

convenience function for updating z/p/beta level data and final statistics following MPP convergence

Updates computedRespLevels/computedProbLevels/computedRelLevels, final_stats/final_stat_grads, warm start, and graphics data.

10.74.2.8 `void g_eval (int & mode, const Epetra_SerialDenseVector & u)` `[private]`

convenience function for evaluating fnVal(u), fnGradU(u), and fnHessU(u) as required by [RIA_constraint_eval\(\)](#) and [PMA_objective_eval\(\)](#)

Convenience function for evaluating the value/gradient/Hessian of G(u). Attributes containing actual data from response evaluations:

- fnValsMeanX, computedRespLevel, fnGradX, fnHessX Attributes used in evaluator fns that may involve approximations:
- modelFnVal, modelFnGradU, modelFnHessU It is important to keep these separate, since fnGradU is used in a number of places (warm start projections, sensitivities, and SORM integrations at converged MPP's) and should not defined from approximations.

10.74.2.9 `void dg_ds_eval (const Epetra_SerialDenseVector & x_vars, const Epetra_SerialDenseVector & fn_grad_x, RealMatrix & final_stat_grads)` `[private]`

convenience function for evaluating dg/ds

Computes dg/ds where s = design variables. Supports potentially overlapping cases of design variable augmentation and insertion.

10.74.2.10 `void trans_U_to_X (const Epetra_SerialDenseVector & u_vars, Epetra_SerialDenseVector & x_vars)` `[private]`

Transformation routine from u-space of uncorrelated standard normal variables to x-space of correlated random variables.

This procedure performs the transformation from u to x space. u_vars is the vector of random variables in uncorrelated standard normal space (u-space). x_vars is the vector of random variables in the original user-defined x-space.

10.74.2.11 `void trans_U_to_Z (const Epetra_SerialDenseVector & u_vars, Epetra_SerialDenseVector & z_vars)` `[private]`

Transformation routine from u-space of uncorrelated standard normal variables to z-space of correlated standard normal variables.

This procedure computes the transformation from u to z space. `u_vars` is the vector of random variables in uncorrelated standard normal space (u-space). `z_vars` is the vector of random variables in normal space with proper correlations (z-space).

10.74.2.12 `void trans_Z_to_X (const Epetra_SerialDenseVector & z_vars, Epetra_SerialDenseVector & x_vars) [private]`

Transformation routine from z-space of correlated standard normal variables to x-space of correlated random variables.

This procedure computes the transformation from z to x space. `z_vars` is the vector of random variables in normal space with proper correlations (z-space). `x_vars` is the vector of random variables in the original user-defined x-space

10.74.2.13 `void trans_X_to_U (const Epetra_SerialDenseVector & x_vars, Epetra_SerialDenseVector & u_vars) [private]`

Transformation routine from x-space of correlated random variables to u-space of uncorrelated standard normal variables.

This procedure performs the transformation from x to u space `u_vars` is the vector of random variables in uncorrelated standard normal space (u-space). `x_vars` is the vector of random variables in the original user-defined x-space.

10.74.2.14 `void trans_X_to_Z (const Epetra_SerialDenseVector & x_vars, Epetra_SerialDenseVector & z_vars) [private]`

Transformation routine from x-space of correlated random variables to z-space of correlated standard normal variables.

This procedure performs the transformation from x to z space: `z_vars` is the vector of random variables in normal space with proper correlations (z-space). `x_vars` is the vector of random variables in the original user-defined x-space.

10.74.2.15 `void trans_Z_to_U (Epetra_SerialDenseVector & z_vars, Epetra_SerialDenseVector & u_vars) [private]`

Transformation routine from z-space of correlated standard normal variables to u-space of uncorrelated standard normal variables.

This procedure computes the transformation from z to u space. `u_vars` is the vector of random variables in uncorrelated standard normal space (u-space). `z_vars` is the vector of random variables in normal space with proper correlations (z-space).

10.74.2.16 `void trans_grad_X_to_U (const Epetra_SerialDenseVector & fn_grad_x,
Epetra_SerialDenseVector & fn_grad_u, const Epetra_SerialDenseVector & x_vars)
[private]`

Transformation routine for gradient vector from x-space to u-space.

This procedure transforms a gradient vector from the original user-defined x-space (where evaluations are performed) to uncorrelated standard normal space (u-space). `x_vars` is the vector of random variables in x-space.

10.74.2.17 `void trans_hess_X_to_U (const Epetra_SerialSymDenseMatrix & fn_hess_x,
Epetra_SerialSymDenseMatrix & fn_hess_u, const Epetra_SerialDenseVector & x_vars, const
Epetra_SerialDenseVector & fn_grad_x) [private]`

Transformation routine for Hessian matrix from x-space to u-space.

This procedure transforms a Hessian matrix from the original user-defined x-space (where evaluations are performed) to uncorrelated standard normal space (u-space). `x_vars` is the vector of the random variables in x-space.

10.74.2.18 `void jacobian_dX_dU (const Epetra_SerialDenseVector & x_vars, Epetra_SerialDenseMatrix
& jacobian_xu) [private]`

Jacobian of $x(u)$ mapping obtained from dX/dZ dZ/dU .

This procedure computes the Jacobian of the transformation $x(u)$. `x_vars` is the vector of random variables in the original user-defined x-space.

10.74.2.19 `void jacobian_dX_dZ (const Epetra_SerialDenseVector & x_vars, Epetra_SerialDenseMatrix
& jacobian_xz) [private]`

Jacobian of $x(z)$ mapping obtained from differentiation of [trans_Z_to_X\(\)](#).

This procedure computes the Jacobian of the transformation $x(z)$. `x_vars` is the vector of random variables in the original user-defined x-space.

10.74.2.20 `void jacobian_dU_dX (const Epetra_SerialDenseVector & x_vars, Epetra_SerialDenseMatrix
& jacobian_ux) [private]`

Jacobian of $u(x)$ mapping obtained from dU/dZ dZ/dX .

This procedure computes the Jacobian of the transformation $u(x)$. `x_vars` is the vector of random variables in the original user-defined x-space.

10.74.2.21 `void jacobian_dZ_dX (const Epetra_SerialDenseVector & x_vars, Epetra_SerialDenseMatrix
& jacobian_zx) [private]`

Jacobian of $z(x)$ mapping obtained from differentiation of [trans_X_to_Z\(\)](#).

This procedure computes the Jacobian of the transformation $z(x)$. x_vars is the vector of random variables in the original user-defined x -space.

10.74.2.22 `void jacobian_dX_dS (const Epetra_SerialDenseVector & x_vars , Epetra_SerialDenseMatrix & $jacobian_xs$) [private]`

Design Jacobian of $x(u,s)$ mapping obtained from differentiation of [trans_U_to_X\(\)](#) with respect to distribution parameters S .

This procedure computes the derivative of the original variables x with respect to the random variable distribution parameters s . This provides the design Jacobian of the transformation for use in computing RBDO design sensitivities.

10.74.2.23 `void numerical_design_jacobian (const Epetra_SerialDenseVector & x_vars , bool xs , Epetra_SerialDenseMatrix & $num_jacobian_xs$, bool zs , Epetra_SerialDenseMatrix & $num_jacobian_zs$) [private]`

Computes numerical dx/ds and dz/ds Jacobians as requested by xs and zs booleans.

This procedure computes numerical derivatives of x and/or z with respect to distribution parameters s , and is used by [jacobian_dX_dS\(\)](#) to provide data that is not available analytically. Numerical dz/ds involves dL/ds ($z(s) = L(s)u$ and $dz/ds = dL/ds u$) and is needed to evaluate dx/ds semi-analytically for correlated variables. Numerical dx/ds is needed for distributions lacking simple closed-form CDF expressions (beta and gamma distributions).

10.74.2.24 `void hessian_d2X_dU2 (const Epetra_SerialDenseVector & x_vars , Array< Epetra_SerialSymDenseMatrix > & $hessian_xu$) [private]`

Hessian of $x(u)$ mapping obtained from $dZ/dU^T d^2X/dZ^2 dZ/dU$.

This procedure computes the Hessian of the transformation $x(u)$. $hessian_xu$ is a 3D tensor modeled as an array of matrices, where the i -th matrix is d^2X_i/dU^2 . x_vars is the vector of random variables in the original user-defined x -space.

10.74.2.25 `void hessian_d2X_dZ2 (const Epetra_SerialDenseVector & x_vars , Array< Epetra_SerialSymDenseMatrix > & $hessian_xz$) [private]`

Hessian of $x(z)$ mapping obtained from differentiation of [jacobian_dX_dZ\(\)](#).

This procedure computes the Hessian of the transformation $x(z)$. $hessian_xz$ is a 3D tensor modeled as an array of matrices, where the i -th matrix is d^2X_i/dZ^2 . x_vars is the vector of random variables in the original user-defined x -space.

10.74.2.26 `void trans_correlations () [private]`

As part of the Nataf distribution model (Der Kiureghian & Liu, 1986), this procedure modifies the user-specified correlation matrix (`corrMatrix`) and decomposes it into its Cholesky factor (`corrCholeskyFactor`).

This procedure modifies the correlation matrix input by the user for use in the Nataf distribution model (Der Kiureghian and Liu, ASCE JEM 112:1, 1986). It uses empirical expressions derived from least-squares polynomial fits to numerical integration data.

- `corrMatrix`: the correlation coefficient matrix of the random variables provided by the user
- `mod_corr_matrix`: modified correlation matrix
- `corrCholeskyFactor`: Cholesky factor of the modified correlation matrix for use in `Z_to_U` and `U_to_Z` transformations.

Note: The modification is exact for normal-normal, lognormal-lognormal, and normal-lognormal transformations. All other cases are approximations with some error as noted below.

10.74.2.27 Real probability (const Real & beta) [private]

Convert beta to a probability using either a first-order or second-order integration.

Converts beta into a probability using either first-order (FORM) or second-order (SORM) integration. The SORM calculation first calculates the principal curvatures at the MPP (using the approach in Ch. 8 of Haldar & Mahadevan), and then applies correction formulations from the literature (Breitung, Hohenbichler/Rackwitz, Tvedt, Hong).

10.74.2.28 Real reliability (const Real & p) [private]

Convert probability to beta using the inverse of a first-order or second-order integration.

Converts a probability into a reliability using the inverse of the first-order or second-order integrations implemented in `NonDReliability::probability(beta)`.

10.74.2.29 Real Phi (const Real & beta) [inline, private]

Standard normal cumulative distribution function.

returns a probability < 0.5 for negative beta and a probability > 0.5 for positive beta.

10.74.2.30 Real Phi_inverse (const Real & p) [inline, private]

Inverse of standard normal cumulative distribution function.

returns a negative beta for probability < 0.5 and a positive beta for probability > 0.5 .

10.74.2.31 Real cdf_beta_Pinv (const Real & normcdf, const Real & alpha, const Real & beta) [private]

Inverse of standard beta CDF (not supported by GSL).

Solve is performed in scaled space (for the standard beta distribution).

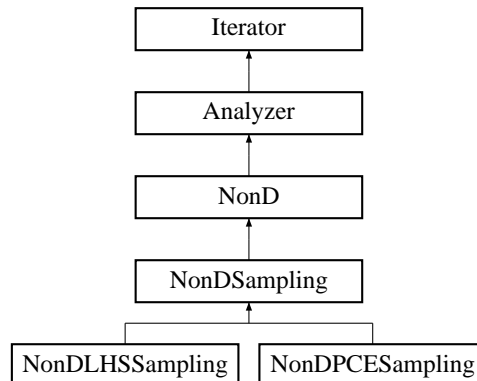
The documentation for this class was generated from the following files:

- NonDReliability.H
- NonDReliability.C

10.75 NonDSampling Class Reference

Base class for common code between [NonDLHSSampling](#) and [NonDPCESampling](#).

Inheritance diagram for NonDSampling::



Protected Member Functions

- [NonDSampling](#) ([Model](#) &model)
constructor
- [NonDSampling](#) ([NoDBBaseConstructor](#), [Model](#) &model, int samples, int seed)
alternate constructor for sample generation and evaluation "on the fly"
- [NonDSampling](#) ([NoDBBaseConstructor](#), int samples, int seed, const [RealVector](#) &lower_bnds, const [RealVector](#) &upper_bnds)
alternate constructor for sample generation "on the fly"
- [~NonDSampling](#) ()
destructor
- void [sampling_reset](#) (int min_samples, bool all_data_flag, bool stats_flag)
resets number of samples and sampling flags
- const [String](#) & [sampling_scheme](#) () const
return sampleType: "lhs" or "random"
- void [vary_pattern](#) (bool pattern_flag)
set varyPattern

- void `get_parameter_sets` ()

Uses `run_lhs()` to generate a set of samples from the distributions in `userDefinedModel`. In the usual mode, this will be called once. In variance-based decomposition or replicated LHS, it may be called several times.
- void `get_parameter_sets` (const `RealVector` &lower_bnds, const `RealVector` &upper_bnds)

Uses `run_lhs()` to generate a set of uniform samples over `lower_bnds/upper_bnds`.
- void `run_lhs` (const `RealVector` &all_l_bnds, const `RealVector` &all_u_bnds, const `RealVector` &n_means, const `RealVector` &n_std_devs, const `RealVector` &n_l_bnds, const `RealVector` &n_u_bnds, const `RealVector` &ln_means, const `RealVector` &ln_std_devs, const `RealVector` &ln_err_facts, const `RealVector` &ln_l_bnds, const `RealVector` &ln_u_bnds, const `RealVector` &u_l_bnds, const `RealVector` &u_u_bnds, const `RealVector` &lu_l_bnds, const `RealVector` &lu_u_bnds, const `RealVector` &t_modes, const `RealVector` &t_l_bnds, const `RealVector` &t_u_bnds, const `RealVector` &b_alphas, const `RealVector` &b_betas, const `RealVector` &b_l_bnds, const `RealVector` &b_u_bnds, const `RealVector` &ga_alphas, const `RealVector` &ga_betas, const `RealVector` &w_alphas, const `RealVector` &w_betas, const `RealVectorArray` &h_bin_prs, const `RealVectorArray` &h_pt_prs, const `IntVector` &num_intervals, const `RealVector` &interval_probs, const `RealVector` &interval_bounds)

generates the desired set of parameter samples from within user-specified probabilistic distributions. Supports both old and new LHS libraries. Used by `NonDLHSSampling` and `NonDPCESSampling`.
- void `compute_statistics` (const `RealVectorArray` &samples)

computes mean, standard deviation, and probability of failure for the samples input
- void `compute_correlations` (const `RealVectorArray` &all_c_vars, const `RealVectorArray` &all_fns)

computes four correlation matrices for input and output data simple, partial, simple rank, and partial rank
- void `simple_corr` (Epetra_SerialDenseMatrix &total_data, const int &num_obs, const int &num_corr, const bool &rank_on)

computes simple correlations
- void `partial_corr` (Epetra_SerialDenseMatrix &total_data, const int &num_obs, const int &num_corr, const bool &rank_on)

computes partial correlations
- void `print_statistics` (ostream &s) const

prints the mean, standard deviation, and probability of failure statistics computed in `compute_statistics()`

Static Protected Member Functions

- static bool `rank_sort` (const int &x, const int &y)

sort algorithm to compute ranks for rank correlations

Protected Attributes

- int `samplesSpec`
user specification of number of samples
- int `numSamples`
the number of samples to evaluate
- String `sampleType`
the sample type: "lhs" or "random"
- bool `statsFlag`
flags computation/output of statistics
- bool `allDataFlag`
flags update of allVariables/allResponses
- size_t `numActiveVars`
total number of variables published to LHS
- size_t `numDesignVars`
number of design variables (treated as uniform distribution within design variable bounds for DACE usage of NonDSampling)
- size_t `numStateVars`
number of state variables (treated as uniform distribution within state variable bounds for DACE usage of NonDSampling)
- bool `varyPattern`
flag for generating a sequence of seed values within multiple `run_lhs()` calls so that the `run_lhs()` executions (e.g., for surrogate-based optimization) are repeatable but not correlated.

Private Member Functions

- void `check_error`(const int &err_code, const char *err_source) const
checks the return codes from LHS routines and aborts if an error is returned

Private Attributes

- const int `originalSeed`
the user seed specification (default is 0)
- int `randomSeed`
the current random number seed

- `size_t numLHSRuns`
counter for number of executions of `run_lhs()` for this object
- `RealVector mean95CIDeltas`
Plus/minus deltas on response function means for 95% confidence intervals (calculated in `compute_statistics()`).
- `RealVector stdDev95CILowerBnds`
Lower bound for 95% confidence interval on std deviation (calculated in `compute_statistics()`).
- `RealVector stdDev95CIUpperBnds`
Upper bound for 95% confidence interval on std deviation (calculated in `compute_statistics()`).
- `Epetra_SerialDenseMatrix simpleCorr`
matrix to hold simple raw correlations
- `Epetra_SerialDenseMatrix simpleRankCorr`
matrix to hold simple rank correlations
- `Epetra_SerialDenseMatrix partialCorr`
matrix to hold partial raw correlations
- `Epetra_SerialDenseMatrix partialRankCorr`
matrix to hold partial rank correlations

Static Private Attributes

- static `RealArray rawData`
vector to hold raw data before rank sort
- static `int pgf90Initialized`
flag indicating whether `pgpf_init()` has been called.

10.75.1 Detailed Description

Base class for common code between `NonDLHSSampling` and `NonDPCESampling`.

This base class provides common code for sampling methods which employ the Latin Hypercube Sampling (LHS) package from Sandia Albuquerque's Risk and Reliability organization. `NonDSampling` manages two LHS versions within a `#ifdef` construct in `run_lhs()`: (1) the 1998 Fortran 90 LHS version as documented in SAND98-0210, which was converted to a UNIX link library in 2001, (2) the 1970's vintage LHS that had been f2c'd and converted to (incomplete) classes.

10.75.2 Constructor & Destructor Documentation

10.75.2.1 [NonDSampling](#) ([Model](#) & *model*) [protected]

constructor

This constructor is called for a standard letter-envelope iterator instantiation. In this case, `set_db_list_nodes` has been called and `probDescDB` can be queried for settings from the method specification.

10.75.2.2 [NonDSampling](#) ([NoDBBaseConstructor](#), [Model](#) & *model*, *int samples*, *int seed*) [protected]

alternate constructor for sample generation and evaluation "on the fly"

This alternate constructor is used by [NonDEvidence](#) for generation and evaluation of on-the-fly sample sets.

10.75.2.3 [NonDSampling](#) ([NoDBBaseConstructor](#), *int samples*, *int seed*, *const RealVector* & *lower_bnds*, *const RealVector* & *upper_bnds*) [protected]

alternate constructor for sample generation "on the fly"

This alternate constructor is used by [ConcurrentStrategy](#) for generation of uniform, uncorrelated sample sets.

10.75.3 Member Function Documentation

10.75.3.1 `void sampling_reset (int min_samples, bool all_data_flag, bool stats_flag)` [inline, protected, virtual]

resets number of samples and sampling flags

used by `ApproximationInterface::build_global_approximation()` to publish the minimum number of samples needed from the sampling routine (to build a particular global approximation) and to set `allDataFlag` and `statsFlag`. In this case, `allDataFlag` is set to true (vectors of variable and response sets must be returned to build the global approximation) and `statsFlag` is set to false (statistics computations are not needed).

Reimplemented from [Iterator](#).

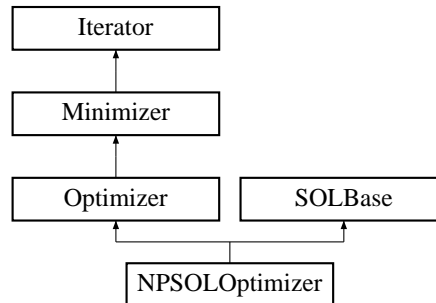
The documentation for this class was generated from the following files:

- `NonDSampling.H`
- `NonDSampling.C`

10.76 NPSOLOptimizer Class Reference

Wrapper class for the NPSOL optimization library.

Inheritance diagram for NPSOLOptimizer::



Public Member Functions

- [NPSOLOptimizer \(Model &model\)](#)
standard constructor
- [NPSOLOptimizer \(const RealVector &initial_point, const RealVector &var_lower_bnds, const RealVector &var_upper_bnds, const RealMatrix &lin_ineq_coeffs, const RealVector &lin_ineq_lower_bnds, const RealVector &lin_ineq_upper_bnds, const RealMatrix &lin_eq_coeffs, const RealVector &lin_eq_targets, const RealVector &nonlin_ineq_lower_bnds, const RealVector &nonlin_ineq_upper_bnds, const RealVector &nonlin_eq_targets, void\(*user_obj_eval\)\(int &, int &, double *, double &, double *, int &\), void\(*user_con_eval\)\(int &, int &, int &, int &, int *, double *, double *, double *, int &\), const int &derivative_level, const Real &conv_tol\)](#)
alternate constructor for instantiations "on the fly"
- [~NPSOLOptimizer \(\)](#)
destructor
- void [find_optimum \(\)](#)
Used within the optimizer branch for computing the optimal solution. Redefines the run_iterator virtual function for the optimizer branch.

Private Member Functions

- void [find_optimum_on_model \(\)](#)
called by find_optimum for setUpType == "model"

- void [find_optimum_on_user_functions](#) ()
called by find_optimum for setUpType == "user_functions"

Static Private Member Functions

- static void [objective_eval](#) (int &mode, int &n, double *x, double &f, double *gradf, int &nstate)
OBJFUN in NPSOL manual: computes the value and first derivatives of the objective function (passed by function pointer to NPSOL).

Private Attributes

- [String setUpType](#)
controls iteration mode: "model" (normal usage) or "user_functions" (user-supplied functions mode for "on the fly" instantiations). NonDReliability currently uses the user_functions mode.
- [RealVector initialPoint](#)
holds initial point passed in for "user_functions" mode.
- [RealVector lowerBounds](#)
holds variable lower bounds passed in for "user_functions" mode.
- [RealVector upperBounds](#)
holds variable upper bounds passed in for "user_functions" mode.
- void(* [userObjectiveEval](#))(int &, int &, double *, double &, double *, int &)
holds function pointer for objective function evaluator passed in for "user_functions" mode.
- void(* [userConstraintEval](#))(int &, int &, int &, int &, int *, double *, double *, double *, int &)
holds function pointer for constraint function evaluator passed in for "user_functions" mode.

Static Private Attributes

- static [NPSOLOptimizer * npsolInstance](#)
pointer to the active object instance used within the static evaluator functions in order to avoid the need for static data

10.76.1 Detailed Description

Wrapper class for the NPSOL optimization library.

The `NPSOLOptimizer` class provides a wrapper for NPSOL, a Fortran 77 sequential quadratic programming library from Stanford University marketed by Stanford Business Associates. It uses a function pointer approach for which passed functions must be either global functions or static member functions. Any attribute used within static member functions must be either local to that function or accessed through a static pointer.

The user input mappings are as follows: `max_function_evaluations` is implemented directly in `NPSOLOptimizer`'s evaluator functions since there is no NPSOL parameter equivalent, and `max_iterations`, `convergence_tolerance`, `output_verbosity`, `verify_level`, `function_precision`, and `linesearch_tolerance` are mapped into NPSOL's "Major Iteration Limit", "Optimality Tolerance", "Major Print Level" (`verbose`: Major Print Level = 20; `quiet`: Major Print Level = 10), "Verify Level", "Function Precision", and "Linesearch Tolerance" parameters, respectively, using NPSOL's `npoptn()` subroutine (as wrapped by `npoptn2()` from the `npoptn_wrapper.f` file). Refer to [Gill, P.E., Murray, W., Saunders, M.A., and Wright, M.H., 1986] for information on NPSOL's optional input parameters and the `npoptn()` subroutine.

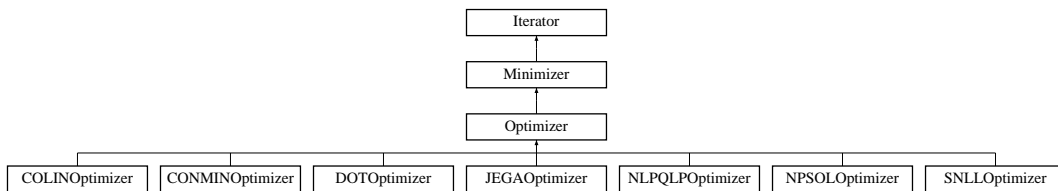
The documentation for this class was generated from the following files:

- `NPSOLOptimizer.H`
- `NPSOLOptimizer.C`

10.77 Optimizer Class Reference

Base class for the optimizer branch of the iterator hierarchy.

Inheritance diagram for Optimizer::



Public Member Functions

- void [run](#) ()
run the iterator; portion of [run_iterator\(\)](#)

Protected Member Functions

- [Optimizer](#) ()
default constructor
- [Optimizer](#) ([Model](#) &model)
standard constructor
- [Optimizer](#) ([NoDBBaseConstructor](#), size_t num_cv, size_t num_lin_ineq, size_t num_lin_eq, size_t num_nln_ineq, size_t num_nln_eq)
alternate constructor for "on the fly" instantiations
- [~Optimizer](#) ()
destructor
- void [print_results](#) (ostream &s) const
- void [multi_objective_weights](#) (const [RealVector](#) &multi_obj_wts)
set the relative weightings for multiple objective functions. Used by [ConcurrentStrategy](#) for Pareto set optimization.
- void [derived_initialize_scaling](#) ()
provides derived class-specific portions of scaling initialization since [Optimizer](#) and [LeastSq](#) iterators have obj fn. and residual scales, respectively

- virtual void [find_optimum](#) ()=0
Used within the optimizer branch for computing the optimal solution. Redefines the run_iterator virtual function for the optimizer branch.
- [Response](#) [multi_objective_modify](#) (const [Response](#) &raw_response) const
forward mapping: maps multiple objective functions to a single objective for single-objective optimizers
- const [RealVector](#) & [multi_objective_retrieve](#) (const [Variables](#) &vars, const [Response](#) &response) const
inverse mapping: retrieves values for multiple objective functions from the solution of a single-objective optimizer

Protected Attributes

- size_t [numObjectiveFunctions](#)
number of objective functions
- [RealVector](#) [multiObjWeights](#)
user-specified weights for multiple objective functions

Friends

- class [COLINApplication](#)
a [COLINOptimizer](#) uses a [COLINApplication](#) object to perform the function evaluations

10.77.1 Detailed Description

Base class for the optimizer branch of the iterator hierarchy.

The [Optimizer](#) class provides common data and functionality for [DOTOptimizer](#), [NPSOLOptimizer](#), [SNLLOptimizer](#), and [COLINOptimizer](#).

10.77.2 Constructor & Destructor Documentation

10.77.2.1 [Optimizer](#) ([Model](#) & *model*) [protected]

standard constructor

This constructor extracts the inherited data for the optimizer branch and performs sanity checking on gradient and constraint settings.

10.77.3 Member Function Documentation

10.77.3.1 void run () [inline, virtual]

run the iterator; portion of [run_iterator\(\)](#)

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This function is the virtual run function for the iterator class hierarchy. All derived classes need to redefine it.

Reimplemented from [Iterator](#).

10.77.3.2 void print_results (ostream & s) const [protected, virtual]

Redefines default iterator results printing to include optimization results (objective functions and constraints).

Reimplemented from [Iterator](#).

10.77.3.3 Response multi_objective_modify (const Response & raw_response) const [protected]

forward mapping: maps multiple objective functions to a single objective for single-objective optimizers

This function is responsible for the mapping of multiple objective functions into a single objective for publishing to single-objective optimizers. Used in [DOTOptimizer](#), [NPSOLOptimizer](#), [SNLLOptimizer](#), and [SGOPTApplication](#) on every function evaluation. The simple weighting approach (using [multiObjWeights](#)) is the only technique supported currently. The weightings are used to scale function values, gradients, and Hessians as needed.

10.77.3.4 const RealVector & multi_objective_retrieve (const Variables & vars, const Response & response) const [protected]

inverse mapping: retrieves values for multiple objective functions from the solution of a single-objective optimizer

Retrieve a full multiobjective response based on the data returned by a single objective optimizer by performing a `data_pairs` search.

The documentation for this class was generated from the following files:

- [DakotaOptimizer.H](#)
- [DakotaOptimizer.C](#)

10.78 ParallelConfiguration Class Reference

Container class for a set of [ParallelLevel](#) list iterators that collectively identify a particular multilevel parallel configuration.

Public Member Functions

- [ParallelConfiguration](#) ()
default constructor
- [ParallelConfiguration](#) (const [ParallelConfiguration](#) &pl)
copy constructor
- [~ParallelConfiguration](#) ()
destructor
- [ParallelConfiguration](#) & operator= (const [ParallelConfiguration](#) &pl)
assignment operator
- const [ParallelLevel](#) & w_parallel_level () const
return the [ParallelLevel](#) corresponding to wPLIter
- const [ParallelLevel](#) & si_parallel_level () const
return the [ParallelLevel](#) corresponding to siPLIter
- const [ParallelLevel](#) & ie_parallel_level () const
return the [ParallelLevel](#) corresponding to iePLIter
- const [ParallelLevel](#) & ea_parallel_level () const
return the [ParallelLevel](#) corresponding to eaPLIter

Private Member Functions

- void [assign](#) (const [ParallelConfiguration](#) &pl)
assign the attributes of the incoming pl to this object

Private Attributes

- short [numParallelLevels](#)
number of parallel levels
- ParLevLIter [wPLIter](#)
list iterator for MPI_COMM_WORLD (not strictly required, but improves modularity by avoiding explicit usage of MPI_COMM_WORLD)
- ParLevLIter [siPLIter](#)
list iterator for concurrent iterator partitions (there may be more than one per parallel configuration instance)
- ParLevLIter [iePLIter](#)
list iterator identifying the iterator-evaluation parallelLevel (there can only be one)
- ParLevLIter [eaPLIter](#)
list iterator identifying the evaluation-analysis parallelLevel (there can only be one)

Friends

- class [ParallelLibrary](#)
the [ParallelLibrary](#) class has special access priveleges in order to streamline implementation

10.78.1 Detailed Description

Container class for a set of [ParallelLevel](#) list iterators that collectively identify a particular multilevel parallel configuration.

Rather than containing the multilevel parallel configuration directly, [ParallelConfiguration](#) instead provides a set of list iterators which point into a combined list of [ParallelLevels](#). This approach allows different configurations to reuse [ParallelLevels](#) without copying them. A list of [ParallelConfigurations](#) is contained in [ParallelLibrary](#) ([ParallelLibrary::parallelConfigurations](#)).

The documentation for this class was generated from the following file:

- [ParallelLibrary.H](#)

10.79 ParallelLevel Class Reference

Container class for the data associated with a single level of communicator partitioning.

Public Member Functions

- [ParallelLevel \(\)](#)
default constructor
- [ParallelLevel \(const ParallelLevel &pl\)](#)
copy constructor
- [~ParallelLevel \(\)](#)
destructor
- [ParallelLevel & operator= \(const ParallelLevel &pl\)](#)
assignment operator
- [bool dedicated_master_flag \(\) const](#)
return dedicatedMasterFlag
- [bool communicator_split_flag \(\) const](#)
return commSplitFlag
- [bool server_master_flag \(\) const](#)
return serverMasterFlag
- [bool message_pass \(\) const](#)
return messagePass
- [const int & num_servers \(\) const](#)
return numServers
- [const int & processors_per_server \(\) const](#)
return procsPerServer
- [const MPI_Comm & server_intra_communicator \(\) const](#)
return serverIntraComm
- [const int & server_communicator_rank \(\) const](#)
return serverCommRank

- const int & [server_communicator_size](#) () const
return serverCommSize
- const MPI_Comm & [hub_server_intra_communicator](#) () const
return hubServerIntraComm
- const int & [hub_server_communicator_rank](#) () const
return hubServerCommRank
- const int & [hub_server_communicator_size](#) () const
return hubServerCommSize
- const MPI_Comm & [hub_server_inter_communicator](#) () const
return hubServerInterComm
- MPI_Comm * [hub_server_inter_communicators](#) () const
return hubServerInterComms
- const int & [server_id](#) () const
return serverId

Private Member Functions

- void [assign](#) (const [ParallelLevel](#) &pl)
assign the attributes of the incoming pl to this object

Private Attributes

- bool [dedicatedMasterFlag](#)
signals dedicated master partitioning
- bool [commSplitFlag](#)
signals a communicator split was used
- bool [serverMasterFlag](#)
identifies master server processors
- bool [messagePass](#)
flag for message passing at this level
- int [numServers](#)
number of servers

- int [procsPerServer](#)
processors per server
- MPI_Comm [serverIntraComm](#)
intracomm. for each server partition
- int [serverCommRank](#)
rank in serverIntraComm
- int [serverCommSize](#)
size of serverIntraComm
- MPI_Comm [hubServerIntraComm](#)
intracomm for all serverCommRank==0 w/i next higher level serverIntraComm
- int [hubServerCommRank](#)
rank in hubServerIntraComm
- int [hubServerCommSize](#)
size of hubServerIntraComm
- MPI_Comm [hubServerInterComm](#)
intercomm. between a server & the hub (on server partitions only)
- MPI_Comm * [hubServerInterComms](#)
intercomm. array on hub processor
- int [serverId](#)
server identifier

Friends

- class [ParallelLibrary](#)
the [ParallelLibrary](#) class has special access privileges in order to streamline implementation

10.79.1 Detailed Description

Container class for the data associated with a single level of communicator partitioning.

A list of these levels is contained in [ParallelLibrary](#) ([ParallelLibrary::parallelLevels](#)), which defines all of the parallelism levels across one or more multilevel parallelism configurations.

The documentation for this class was generated from the following file:

- [ParallelLibrary.H](#)

10.80 ParallelLibrary Class Reference

Class for partitioning multiple levels of parallelism and managing message passing within these levels.

Public Member Functions

- [ParallelLibrary](#) (int &argc, char **&argv)
stand-alone mode constructor
- [ParallelLibrary](#) ()
library mode constructor
- [ParallelLibrary](#) (int dummy)
dummy constructor (used for dummy_lib)
- [~ParallelLibrary](#) ()
destructor
- const [ParallelLevel](#) & [init_iterator_communicators](#) (const int &iterator_servers, const int &procs_per_iterator, const int &max_iterator_concurrency, const [String](#) &default_config, const [String](#) &iterator_scheduling)
split MPI_COMM_WORLD into iterator communicators
- const [ParallelLevel](#) & [init_evaluation_communicators](#) (const int &evaluation_servers, const int &procs_per_evaluation, const int &max_evaluation_concurrency, const int &asynch_local_evaluation_concurrency, const [String](#) &default_config, const [String](#) &evaluation_scheduling)
split an iterator communicator into evaluation communicators
- const [ParallelLevel](#) & [init_analysis_communicators](#) (const int &analysis_servers, const int &procs_per_analysis, const int &max_analysis_concurrency, const int &asynch_local_analysis_concurrency, const [String](#) &default_config, const [String](#) &analysis_scheduling)
split an evaluation communicator into analysis communicators
- void [free_iterator_communicators](#) ()
deallocate iterator communicators
- void [free_evaluation_communicators](#) ()
deallocate evaluation communicators
- void [free_analysis_communicators](#) ()
deallocate analysis communicators
- void [print_configuration](#) ()

print the parallel level settings for a particular parallel configuration

- void `specify_outputs_restart` (`CommandLineHandler &cmd_line_handler`)
specify output streams and restart file(s) using command line inputs (normal mode)
- void `specify_outputs_restart` (const char *clh_std_output_filename, const char *clh_std_error_filename, const char *clh_read_restart_filename, const char *clh_write_restart_filename, int restart_evals)
specify output streams and restart file(s) using external inputs (library mode).
- void `manage_outputs_restart` (const `ParallelLevel &pl`)
manage output streams and restart file(s) (both modes)
- void `close_streams` ()
close streams, files, and any other services
- void `send_si` (`MPIPackBuffer &send_buff`, int dest, int tag)
blocking send at the strategy-iterator communication level
- void `isend_si` (`MPIPackBuffer &send_buff`, int dest, int tag, `MPI_Request &send_req`)
nonblocking send at the strategy-iterator communication level
- void `recv_si` (`MPIUnpackBuffer &recv_buff`, int source, int tag, `MPI_Status &status`)
blocking receive at the strategy-iterator communication level
- void `irecv_si` (`MPIUnpackBuffer &recv_buff`, int source, int tag, `MPI_Request &recv_req`)
nonblocking receive at the strategy-iterator communication level
- void `send_ie` (`MPIPackBuffer &send_buff`, int dest, int tag)
blocking send at the iterator-evaluation communication level
- void `isend_ie` (`MPIPackBuffer &send_buff`, int dest, int tag, `MPI_Request &send_req`)
nonblocking send at the iterator-evaluation communication level
- void `recv_ie` (`MPIUnpackBuffer &recv_buff`, int source, int tag, `MPI_Status &status`)
blocking receive at the iterator-evaluation communication level
- void `irecv_ie` (`MPIUnpackBuffer &recv_buff`, int source, int tag, `MPI_Request &recv_req`)
nonblocking receive at the iterator-evaluation communication level
- void `send_ea` (int &send_int, int dest, int tag)
blocking send at the evaluation-analysis communication level
- void `isend_ea` (int &send_int, int dest, int tag, `MPI_Request &send_req`)
nonblocking send at the evaluation-analysis communication level
- void `recv_ea` (int &recv_int, int source, int tag, `MPI_Status &status`)

blocking receive at the evaluation-analysis communication level

- void `irecv_ea` (int &recv_int, int source, int tag, MPI_Request &recv_req)
nonblocking receive at the evaluation-analysis communication level
- void `bcast_w` (int &data)
broadcast an integer across MPI_COMM_WORLD
- void `bcast_i` (int &data)
broadcast an integer across an iterator communicator
- void `bcast_e` (int &data)
broadcast an integer across an evaluation communicator
- void `bcast_a` (int &data)
broadcast an integer across an analysis communicator
- void `bcast_si` (int &data)
broadcast an integer across a strategy-iterator intra communicator
- void `bcast_w` (MPIPackBuffer &send_buff)
broadcast a packed buffer across MPI_COMM_WORLD
- void `bcast_i` (MPIPackBuffer &send_buff)
broadcast a packed buffer across an iterator communicator
- void `bcast_e` (MPIPackBuffer &send_buff)
broadcast a packed buffer across an evaluation communicator
- void `bcast_a` (MPIPackBuffer &send_buff)
broadcast a packed buffer across an analysis communicator
- void `bcast_si` (MPIPackBuffer &send_buff)
broadcast a packed buffer across a strategy-iterator intra communicator
- void `bcast_w` (MPIUnpackBuffer &recv_buff)
matching receive for packed buffer broadcast across MPI_COMM_WORLD
- void `bcast_i` (MPIUnpackBuffer &recv_buff)
matching receive for packed buffer bcast across an iterator communicator
- void `bcast_e` (MPIUnpackBuffer &recv_buff)
matching receive for packed buffer bcast across an evaluation communicator
- void `bcast_a` (MPIUnpackBuffer &recv_buff)
matching receive for packed buffer bcast across an analysis communicator

- void `bcast_si` (`MPIUnpackBuffer` &recv_buff)
matching recv for packed buffer bcast across a strat-iterator intra comm
- void `barrier_w` ()
enforce MPI_Barrier on MPI_COMM_WORLD
- void `barrier_i` ()
enforce MPI_Barrier on an iterator communicator
- void `barrier_e` ()
enforce MPI_Barrier on an evaluation communicator
- void `barrier_a` ()
enforce MPI_Barrier on an analysis communicator
- void `reduce_sum_ea` (double *local_vals, double *sum_vals, const int &num_vals)
compute a sum over an eval-analysis intra-communicator using MPI_Reduce
- void `reduce_sum_a` (double *local_vals, double *sum_vals, const int &num_vals)
compute a sum over an analysis communicator using MPI_Reduce
- void `test` (`MPI_Request` &request, int &test_flag, `MPI_Status` &status)
test a nonblocking send/receive request for completion
- void `wait` (`MPI_Request` &request, `MPI_Status` &status)
wait for a nonblocking send/receive request to complete
- void `waitall` (const int &num_recvs, `MPI_Request` *&recv_reqs)
wait for all messages from a series of nonblocking receives
- void `waitsome` (const int &num_sends, `MPI_Request` *&recv_requests, int &num_recvs, int *&index_array, `MPI_Status` *&status_array)
wait for at least one message from a series of nonblocking receives but complete all that are available
- void `free` (`MPI_Request` &request)
free an MPI_Request
- const int & `world_size` () const
return worldSize
- const int & `world_rank` () const
return worldRank
- bool `mpirun_flag` () const
return mpirunFlag

- `bool is_null () const`
return dummyFlag
- `Real parallel_time () const`
returns current MPI wall clock time
- `void parallel_configuration_iterator (const ParConfigLIter &pc_iter)`
set the current ParallelConfiguration node
- `const ParConfigLIter & parallel_configuration_iterator () const`
return the current ParallelConfiguration node
- `const ParallelConfiguration & parallel_configuration () const`
return the current ParallelConfiguration instance
- `size_t num_parallel_configurations () const`
returns the number of entries in parallelConfigurations
- `bool parallel_configuration_is_complete ()`
identifies if the current ParallelConfiguration has been fully populated
- `void increment_parallel_configuration ()`
add a new node to parallelConfigurations and increment currPCIter
- `bool w_parallel_level_defined () const`
test current parallel configuration for definition of world parallel level
- `bool si_parallel_level_defined () const`
test current parallel configuration for definition of strategy-iterator parallel level
- `bool ie_parallel_level_defined () const`
test current parallel configuration for definition of iterator-evaluation parallel level
- `bool ea_parallel_level_defined () const`
test current parallel configuration for definition of evaluation-analysis parallel level
- `Array< MPI_Comm > analysis_intra_communicators ()`
return the set of analysis intra communicators for all parallel configurations (used for setting up direct simulation interfaces prior to execution time).

Private Member Functions

- void `init_communicators` (const `ParallelLevel` &parent_pl, const int &num_servers, const int &procs_per_server, const int &max_concurrency, const int &asynch_local_concurrency, const `String` &default_config, const `String` &scheduling_override)
 - split a parent communicator into child server communicators*
- void `free_communicators` (`ParallelLevel` &pl)
 - deallocate intra/inter communicators for a particular `ParallelLevel`*
- bool `split_communicator_dedicated_master` (const `ParallelLevel` &parent_pl, `ParallelLevel` &child_pl, const int &proc_remainder)
 - split a parent communicator into a dedicated master processor and num_servers child communicators*
- bool `split_communicator_peer_partition` (const `ParallelLevel` &parent_pl, `ParallelLevel` &child_pl, const int &proc_remainder)
 - split a parent communicator into num_servers peer child communicators (no dedicated master processor)*
- bool `resolve_inputs` (int &num_servers, int &procs_per_server, const int &avail_procs, int &proc_remainder, const int &max_concurrency, const int &capacity_multiplier, const `String` &default_config, const `String` &scheduling_override)
 - resolve user inputs into a sensible partitioning scheme*
- void `send` (`MPIPackBuffer` &send_buff, const int &dest, const int &tag, `ParallelLevel` &parent_pl, `ParallelLevel` &child_pl)
 - blocking buffer send at the current communication level*
- void `send` (int &send_int, const int &dest, const int &tag, `ParallelLevel` &parent_pl, `ParallelLevel` &child_pl)
 - blocking integer send at the current communication level*
- void `isend` (`MPIPackBuffer` &send_buff, const int &dest, const int &tag, `MPI_Request` &send_req, `ParallelLevel` &parent_pl, `ParallelLevel` &child_pl)
 - nonblocking buffer send at the current communication level*
- void `isend` (int &send_int, const int &dest, const int &tag, `MPI_Request` &send_req, `ParallelLevel` &parent_pl, `ParallelLevel` &child_pl)
 - nonblocking integer send at the current communication level*
- void `recv` (`MPIUnpackBuffer` &recv_buff, const int &source, const int &tag, `MPI_Status` &status, `ParallelLevel` &parent_pl, `ParallelLevel` &child_pl)
 - blocking buffer receive at the current communication level*
- void `recv` (int &recv_int, const int &source, const int &tag, `MPI_Status` &status, `ParallelLevel` &parent_pl, `ParallelLevel` &child_pl)
 - blocking integer receive at the current communication level*

- void `irecv` (`MPIUnpackBuffer` &recv_buff, const int &source, const int &tag, `MPI_Request` &recv_req, `ParallelLevel` &parent_pl, `ParallelLevel` &child_pl)
nonblocking buffer receive at the current communication level
- void `irecv` (int &recv_int, const int &source, const int &tag, `MPI_Request` &recv_req, `ParallelLevel` &parent_pl, `ParallelLevel` &child_pl)
nonblocking integer receive at the current communication level
- void `bcast` (int &data, const `MPI_Comm` &comm)
broadcast an integer across a communicator
- void `bcast` (`MPIPackBuffer` &send_buff, const `MPI_Comm` &comm)
send a packed buffer across a communicator using a broadcast
- void `bcast` (`MPIUnpackBuffer` &recv_buff, const `MPI_Comm` &comm)
matching receive for a packed buffer broadcast
- void `barrier` (const `MPI_Comm` &comm)
enforce MPI_Barrier on comm
- void `reduce_sum` (double *local_vals, double *sum_vals, const int &num_vals, const `MPI_Comm` &comm)
compute a sum over comm using MPI_Reduce
- void `check_error` (const `String` &err_source, const int &err_code)
check the MPI return code and abort if error

Private Attributes

- ofstream `output_ofstream`
tagged file redirection of stdout
- ofstream `error_ofstream`
tagged file redirection of stderr
- int `worldRank`
rank in MPI_COMM_WORLD
- int `worldSize`
size of MPI_COMM_WORLD
- bool `mpirunFlag`
flag for a parallel mpirun/yod launch
- bool `ownMPIFlag`

flag for ownership of MPI_Init/MPI_Finalize

- bool [dummyFlag](#)
prevents multiple MPI_Finalize calls due to dummy_lib
- bool [stdOutputFlag](#)
flags redirection of DAKOTA std output to a file
- bool [stdErrorFlag](#)
flags redirection of DAKOTA std error to a file
- Real [startCPUTime](#)
start reference for UTILIB CPU timer
- Real [startWCTime](#)
start reference for UTILIB wall clock timer
- Real [startMPITime](#)
start reference for MPI wall clock timer
- long [startClock](#)
start reference for local clock() timer measuring parent+child CPU
- const char * [stdOutputFilename](#)
filename for redirection of stdout
- const char * [stdErrorFilename](#)
filename for redirection of stderr
- const char * [readRestartFilename](#)
input filename for restart
- const char * [writeRestartFilename](#)
output filename for restart
- int [restartEvals](#)
number of restart evals to read
- [List< ParallelLevel > parallelLevels](#)
the complete set of parallelism levels for managing multilevel parallelism among one or more configurations
- [List< ParallelConfiguration > parallelConfigurations](#)
the set of parallel configurations which manage list iterators for indexing into parallelLevels
- [ParLevLIter currPLiter](#)
list iterator identifying the current node in parallelLevels

- `ParConfigLIter currPCIter`

list iterator identifying the current node in parallelConfigurations

10.80.1 Detailed Description

Class for partitioning multiple levels of parallelism and managing message passing within these levels.

The `ParallelLibrary` class encapsulates all of the details of performing message passing within multiple levels of parallelism. It provides functions for partitioning of levels according to user configuration input and functions for passing messages within and across MPI communicators for each of the parallelism levels. If support for other message-passing libraries beyond MPI becomes needed (PVM, ...), then `ParallelLibrary` would be promoted to a base class with virtual functions to encapsulate the library-specific syntax.

10.80.2 Constructor & Destructor Documentation

10.80.2.1 `ParallelLibrary (int & argc, char **& argv)`

stand-alone mode constructor

This constructor is the one used by `main.C`. It calls `MPI_Init` conditionally based on whether a parallel launch is detected.

10.80.2.2 `ParallelLibrary ()`

library mode constructor

This constructor provides a library mode and is used by the SIERRA Adak application. It does not call `MPI_Init`, but rather gathers data from `MPI_COMM_WORLD` if `MPI_Init` has been called elsewhere.

10.80.2.3 `ParallelLibrary (int dummy)`

dummy constructor (used for `dummy_lib`)

This constructor is used for creation of the global `dummy_lib` object, which is used to satisfy initialization requirements when the real `ParallelLibrary` object is not available.

10.80.3 Member Function Documentation

10.80.3.1 void specify_outputs_restart (CommandLineHandler & cmd_line_handler)

specify output streams and restart file(s) using command line inputs (normal mode)

Get the -output, -error, -read_restart, and -write_restart filenames and the -stop_restart limit from the command line. Defaults for the filenames from the command line handler are NULL for the filenames and 0 for restart_evals if no user specification. Only worldRank==0 has access to command line arguments and must Bcast this data to all iterator masters.

10.80.3.2 void manage_outputs_restart (const ParallelLevel & pl)

manage output streams and restart file(s) (both modes)

If the user has specified the use of files for DAKOTA standard output and/or standard error, then bind these filenames to the Cout/Cerr macros. In addition, if concurrent iterators are to be used, create and tag multiple output streams in order to prevent jumbled output. Manage restart file(s) by processing any incoming evaluations from an old restart file and by setting up the binary output stream for new evaluations. Only master iterator processor(s) read & write restart information. This function must follow init_iterator_communicators so that restart can be managed properly for concurrent iterator strategies. In the case of concurrent iterators, each iterator has its own restart file tagged with iterator number.

10.80.3.3 void close_streams ()

close streams, files, and any other services

Close streams associated with manage_outputs and manage_restart and terminate any additional services that may be active.

10.80.3.4 void increment_parallel_configuration () [inline]

add a new node to parallelConfigurations and increment currPCIter

Called from the [ParallelLibrary](#) ctor and from [Model::init_communicators\(\)](#). An increment is performed for each [Model](#) initialization except the first (which inherits the world and strategy-iterator parallel levels from the first partial configuration).

10.80.3.5 void init_communicators (const ParallelLevel & parent_pl, const int & num_servers, const int & procs_per_server, const int & max_concurrency, const int & asynch_local_concurrency, const String & default_config, const String & scheduling_override) [private]

split a parent communicator into child server communicators

Split parent communicator into concurrent child server partitions as specified by the passed parameters. This constructs new child intra-communicators and parent-child inter-communicators. This function is called from the [Strategy](#) constructor for the concurrent iterator level and from [ApplicationInterface::init_communicators\(\)](#) for the concurrent evaluation and concurrent analysis levels.

10.80.3.6 `bool resolve_inputs (int & num_servers, int & procs_per_server, const int & avail_procs, int & proc_remainder, const int & max_concurrency, const int & capacity_multiplier, const String & default_config, const String & scheduling_override) [private]`

resolve user inputs into a sensible partitioning scheme

This function is responsible for the "auto-configure" intelligence of DAKOTA. It resolves a variety of inputs and overrides into a sensible partitioning configuration for a particular parallelism level. It also handles the general case in which a user's specification request does not divide out evenly with the number of available processors for the level. If `num_servers` & `procs_per_server` are both nondefault, then the former takes precedence.

The documentation for this class was generated from the following files:

- ParallelLibrary.H
- ParallelLibrary.C

10.81 ParamResponsePair Class Reference

Container class for a variables object, a response object, and an evaluation id.

Public Member Functions

- [ParamResponsePair](#) ()
default constructor
- [ParamResponsePair](#) (const [Variables](#) &vars, const [String](#) &interface_id, const [Response](#) &response, bool deep_copy=false)
alternate constructor for temporaries
- [ParamResponsePair](#) (const [Variables](#) &vars, const [String](#) &interface_id, const [Response](#) &response, const int eval_id, bool deep_copy=true)
standard constructor for history uses
- [ParamResponsePair](#) (const [ParamResponsePair](#) &pair)
copy constructor
- [~ParamResponsePair](#) ()
destructor
- [ParamResponsePair](#) & operator= (const [ParamResponsePair](#) &pair)
assignment operator
- void [read](#) (istream &s)
read a [ParamResponsePair](#) object from an istream
- void [write](#) (ostream &s) const
write a [ParamResponsePair](#) object to an ostream
- void [read_annotated](#) (istream &s)
read a [ParamResponsePair](#) object in annotated format from an istream
- void [write_annotated](#) (ostream &s) const
write a [ParamResponsePair](#) object in annotated format to an ostream
- void [write_tabular](#) (ostream &s) const
write a [ParamResponsePair](#) object in tabular format to an ostream
- void [read](#) ([BiStream](#) &s)

read a *ParamResponsePair* object from the binary restart stream

- void `write (BoStream &s) const`
write a *ParamResponsePair* object to the binary restart stream
- void `read (MPIUnpackBuffer &s)`
read a *ParamResponsePair* object from a packed MPI buffer
- void `write (MPIPackBuffer &s) const`
write a *ParamResponsePair* object to a packed MPI buffer
- int `eval_id () const`
return the evaluation identifier
- const `Variables & prp_parameters () const`
return the parameters object
- const `Response & prp_response () const`
return the response object
- void `prp_response (const Response &response)`
set the response object
- const `ActiveSet & active_set () const`
return the active set object from the response object
- void `active_set (const ActiveSet &set)`
set the active set object within the response object
- const `String & interface_id () const`
return the interface identifier from the response object

Private Attributes

- `Variables prPairParameters`
the set of parameters for the function evaluation
- `Response prPairResponse`
the response set for the function evaluation
- `String idInterface`
the interface used to generate the response object. Used in `ParamResponsePair::vars_set_compare` to prevent duplicate detection on results from different interfaces.
- int `evalId`
the function evaluation identifier (assigned from `ApplicationInterface::fnEvalId`)

Friends

- `bool operator==(const ParamResponsePair &pair1, const ParamResponsePair &pair2)`
equality operator
- `bool operator!=(const ParamResponsePair &pair1, const ParamResponsePair &pair2)`
inequality operator

10.81.1 Detailed Description

Container class for a variables object, a response object, and an evaluation id.

`ParamResponsePair` provides a container class for association of the input for a particular function evaluation (a variables object) with the output from this function evaluation (a response object), along with an evaluation identifier. This container defines the basic unit used in the `data_pairs` list, in restart file operations, and in a variety of scheduling algorithm bookkeeping operations. With the advent of STL, replacement of arrays of this class with `map<>` and `pair<>` template constructs may be possible (using `map<int, pair<vars,response> >`, for example), assuming that deep copies, I/O, alternate constructors, etc., can be adequately addressed.

10.81.2 Constructor & Destructor Documentation

10.81.2.1 `ParamResponsePair` (const Variables & vars, const String & interface_id, const Response & response, bool deep_copy = false) [inline]

alternate constructor for temporaries

Uses of this constructor often employ the standard `Variables` and `Response` copy constructors to share representations since this constructor is commonly used for `search_pairs` (which are local instantiations that go out of scope prior to any changes to values; i.e., they are not used for history).

10.81.2.2 `ParamResponsePair` (const Variables & vars, const String & interface_id, const Response & response, const int eval_id, bool deep_copy = true) [inline]

standard constructor for history uses

Uses of this constructor often do not share representations since deep copies are used when history mechanisms (e.g., `beforeSynchCorePRPList`, `data_pairs`) are involved.

10.81.3 Member Function Documentation

10.81.3.1 void read (MPIUnpackBuffer & s) [inline]

read a [ParamResponsePair](#) object from a packed MPI buffer

idInterface is omitted since master processor retains interface ids and communicates asv and response data only with slaves.

10.81.3.2 void write (MPIPackBuffer & s) const [inline]

write a [ParamResponsePair](#) object to a packed MPI buffer

idInterface is omitted since master processor retains interface ids and communicates asv and response data only with slaves.

10.81.4 Member Data Documentation

10.81.4.1 String idInterface [private]

the interface used to generate the response object. Used in `ParamResponsePair::vars_set_compare` to prevent duplicate detection on results from different interfaces.

idInterface belongs here rather than in [Response](#) since some [Response](#) objects involve consolidation of several fn evals (e.g., `Model::synchronize_derivatives()`) that are not, in total, generated by a single interface. The `prPair`, on the other hand, is used for storage of all low level fn evals that get evaluated in `ApplicationInterface::map()`.

10.81.4.2 int evalId [private]

the function evaluation identifier (assigned from `ApplicationInterface::fnEvalId`)

evalId belongs here rather than in [Response](#) since some [Response](#) objects involve consolidation of several fn evals (e.g., `Model::synchronize_derivatives()`). The `prPair`, on the other hand, is used for storage of all low level fn evals that get evaluated in `ApplicationInterface::map()`.

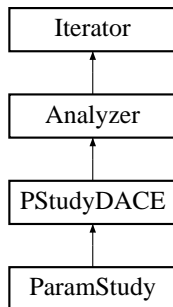
The documentation for this class was generated from the following files:

- `ParamResponsePair.H`
- `ParamResponsePair.C`

10.82 ParamStudy Class Reference

Class for vector, list, centered, and multidimensional parameter studies.

Inheritance diagram for ParamStudy::



Public Member Functions

- [ParamStudy](#) ([Model](#) &model)
constructor
- [~ParamStudy](#) ()
destructor
- void [extract_trends](#) ()
Redefines the run_iterator virtual function for the PStudy/DACE branch.

Private Member Functions

- void [compute_vector_steps](#) ()
computes stepVector and numSteps from initialPoint, finalPoint, and either numSteps or stepLength (pStudyType is 1 or 2)
- void [vector_loop](#) (const [RealVector](#) &start, const [RealVector](#) &step_vect, const int &num_steps)
performs the parameter study by looping from start in num_steps increments of step_vect. Total number of evaluations is num_steps + 1.
- void [sample](#) (const [RealVector](#) &list_of_points)
performs the parameter study by sampling from a list of points
- void [centered_loop](#) (const [RealVector](#) &start, const Real &percent_delta, const int &deltas_per_variable)

performs a number of plus and minus offsets for each parameter centered about start

- void `multidim_loop` (const `IntArray` &var_partitions)
performs vector_loops recursively in multiple dimensions
- void `recurse` (int nloop, int nindex, `IntArray` ¤t_index, const `IntArray` &max_index, const `RealVector` &start, const `RealVector` &step_vect)
used by multidim_loop to enable a variable number of nested loops

Private Attributes

- `RealVector` `listOfPoints`
list of evaluation points for the list_parameter_study
- `RealVector` `initialPoint`
the starting point for vector and centered parameter studies
- `RealVector` `finalPoint`
the ending point for vector_parameter_study (a specification option)
- `RealVector` `stepVector`
the n-dimensional increment in vector_parameter_study
- int `numSteps`
the number of times stepVector is applied in vector_parameter_study
- int `pStudyType`
internal code for parameter study type: -1 (list), 1,2,3 (different vector specifications), 4 (centered), or 5 (multidim)
- int `deltasPerVariable`
number of offsets in the plus and the minus direction for each variable in a centered_parameter_study
- bool `nestedFlag`
flag set by parameter studies which call other parameter studies in loops
- Real `stepLength`
the Cartesian length of multidimensional steps in vector_parameter_study (a specification option)
- Real `percentDelta`
size of relative offsets in percent for each variable in a centered_parameter_study
- `IntArray` `variablePartitions`
number of partitions for each variable in a multidim_parameter_study
- int `psCounter`
class-scope counter (needed for asynchronous multidim_loop)

10.82.1 Detailed Description

Class for vector, list, centered, and multidimensional parameter studies.

The [ParamStudy](#) class contains several algorithms for performing parameter studies of different types. It is not a wrapper for an external library, rather its algorithms are self-contained. The vector parameter study steps along an n-dimensional vector from an arbitrary initial point to an arbitrary final point in a specified number of steps. The centered parameter study performs a number of plus and minus offsets in each coordinate direction around a center point. A multidimensional parameter study fills an n-dimensional hypercube based on a specified number of intervals for each dimension. It is a nested study in that it utilizes the vector parameter study internally as it recurses through the variables. And the list parameter study provides for a user specification of a list of points to evaluate, which allows general parameter investigations not fitting the structure of vector, centered, or multidim parameter studies.

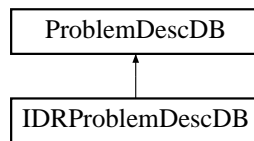
The documentation for this class was generated from the following files:

- ParamStudy.H
- ParamStudy.C

10.83 ProblemDescDB Class Reference

The database containing information parsed from the DAKOTA input file.

Inheritance diagram for ProblemDescDB::



Public Member Functions

- [ProblemDescDB \(\)](#)
default constructor
- [ProblemDescDB \(ParallelLibrary ¶llel_lib\)](#)
standard constructor
- [ProblemDescDB \(const ProblemDescDB &db\)](#)
copy constructor
- [~ProblemDescDB \(\)](#)
destructor
- [ProblemDescDB operator= \(const ProblemDescDB &db\)](#)
assignment operator
- void [manage_inputs \(CommandLineHandler &cmd_line_handler\)](#)
parses the input file and populates the problem description database. This version reads from the dakota input filename passed with the "-input" option on the DAKOTA command line.
- void [manage_inputs \(const char *dakota_input_file\)](#)
parses the input file and populates the problem description database. This version reads from the dakota input filename passed in.
- void [check_input \(\)](#)
verifies that there was at least one of each of the required keywords in the dakota input file. Used by [manage_inputs\(\)](#).
- void [set_db_list_nodes \(const String &method_tag\)](#)

set dataMethodIter based on a method identifier string to activate a particular method specification in dataMethodList and use pointers from this method specification to set all other list iterators.

- void `set_db_list_nodes` (const size_t &method_index)
set dataMethodIter based on an index within dataMethodList to activate a particular method specification and use pointers from this method specification to set all other list iterators.
- void `set_db_method_node` (const size_t &method_index)
set dataMethodIter based on an index within dataMethodList to activate a particular method specification (only).
- size_t `get_db_method_node` ()
return the index of the active node in dataMethodList
- void `set_db_model_nodes` (const String &model_tag)
set the model list iterators (dataModelIter, dataVariablesIter, dataInterfaceIter, and dataResponsesIter) based on the model identifier string
- void `set_db_model_nodes` (const size_t &model_index)
set the model list iterators (dataModelIter, dataVariablesIter, dataInterfaceIter, and dataResponsesIter) based on an index within dataModelList
- size_t `get_db_model_node` ()
return the index of the active node in dataModelList
- void `set_db_variables_node` (const String &variables_tag)
set dataVariablesIter based on the variables identifier string
- void `set_db_interface_node` (const String &interface_tag)
set dataInterfaceIter based on the interface identifier string
- void `set_db_responses_node` (const String &responses_tag)
set dataResponsesIter based on the responses identifier string
- `ParallelLibrary` & `parallel_library` () const
return the parallelLib reference
- `IteratorList` & `iterator_list` ()
return a list of all Iterator objects that have been instantiated
- `ModelList` & `model_list` ()
return a list of all Model objects that have been instantiated
- `VariablesList` & `variables_list` ()
return a list of all Variables objects that have been instantiated
- `InterfaceList` & `interface_list` ()
return a list of all Interface objects that have been instantiated

- [ResponseList](#) & [response_list](#) ()
return a list of all [Response](#) objects that have been instantiated
- const [Iterator](#) & [get_iterator](#) ([Model](#) &model)
retrieve an existing [Iterator](#), if it exists, or instantiate a new one
- const [Model](#) & [get_model](#) ()
retrieve an existing [Model](#), if it exists, or instantiate a new one
- const [Variables](#) & [get_variables](#) ()
retrieve an existing [Variables](#), if it exists, or instantiate a new one
- const [Interface](#) & [get_interface](#) ()
retrieve an existing [Interface](#), if it exists, or instantiate a new one
- const [Response](#) & [get_response](#) (const [Variables](#) &vars)
retrieve an existing [Response](#), if it exists, or instantiate a new one
- const [RealVector](#) & [get_drv](#) (const [String](#) &entry_name) const
get a [RealVector](#) out of the database based on an identifier string
- const [IntVector](#) & [get_div](#) (const [String](#) &entry_name) const
get a [IntVector](#) out of the database based on an identifier string
- const [IntArray](#) & [get_dia](#) (const [String](#) &entry_name) const
get a [IntArray](#) out of the database based on an identifier string
- const [RealMatrix](#) & [get_drm](#) (const [String](#) &entry_name) const
get a [RealMatrix](#) out of the database based on an identifier string
- const [RealVectorArray](#) & [get_drva](#) (const [String](#) &entry_name) const
get a [RealVectorArray](#) out of the database based on an identifier string
- const [IntList](#) & [get_dil](#) (const [String](#) &entry_name) const
get a [IntList](#) out of the database based on an identifier string
- const [StringArray](#) & [get_dsa](#) (const [String](#) &entry_name) const
get a [StringArray](#) out of the database based on an identifier string
- const [String2DArray](#) & [get_ds2a](#) (const [String](#) &entry_name) const
get a [String2DArray](#) out of the database based on an identifier string
- const [String](#) & [get_string](#) (const [String](#) &entry_name) const
get a [String](#) out of the database based on an identifier string

- `const Real & get_real (const String &entry_name) const`
get a Real out of the database based on an identifier string
- `const int & get_int (const String &entry_name) const`
get an int out of the database based on an identifier string
- `const short & get_short (const String &entry_name) const`
get a short int out of the database based on an identifier string
- `const size_t & get_sizet (const String &entry_name) const`
get a size_t out of the database based on an identifier string
- `const bool & get_bool (const String &entry_name) const`
get a bool out of the database based on an identifier string
- `void insert_node (const DataStrategy &data_strategy)`
set the DataStrategy object
- `void insert_node (const DataMethod &data_method)`
add a DataMethod object to the dataMethodList
- `void insert_node (const DataModel &data_model)`
add a DataModel object to the dataModelList
- `void insert_node (const DataVariables &data_variables)`
add a DataVariables object to the dataVariablesList
- `void insert_node (const DataInterface &data_interface)`
add a DataInterface object to the dataInterfaceList
- `void insert_node (const DataResponses &data_responses)`
add a DataResponses object to the dataResponsesList

Protected Member Functions

- `ProblemDescDB (BaseConstructor, ParallelLibrary ¶llel_lib)`
constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)
- `virtual void derived_manage_inputs (const char *dakota_input_file)`
parses the input file and populates the problem description database. This version reads from the dakota input filename passed in.

Protected Attributes

- [DataStrategy](#) `strategySpec`
the strategy specification (only one allowed) resulting from a call to `strategy_kwhandler()` or `insert_node()`
- [List< DataMethod >](#) `dataMethodList`
list of method specifications, one for each call to `method_kwhandler()` or `insert_node()`
- [List< DataModel >](#) `dataModelList`
list of model specifications, one for each call to `model_kwhandler()` or `insert_node()`
- [List< DataVariables >](#) `dataVariablesList`
list of variables specifications, one for each call to `variables_kwhandler()` or `insert_node()`
- [List< DataInterface >](#) `dataInterfaceList`
list of interface specifications, one for each call to `interface_kwhandler()` or `insert_node()`
- [List< DataResponses >](#) `dataResponsesList`
list of responses specifications, one for each call to `responses_kwhandler()` or `insert_node()`
- `size_t` `strategyCnt`
counter for strategy specifications used in `check_input`

Private Member Functions

- `ProblemDescDB * get_db (ParallelLibrary ¶llel_lib)`
Used by the standard envelope constructor to instantiate the correct letter class.
- `void send_db_buffer ()`
MPI send of a large buffer containing `strategySpec` and all objects in `dataMethodList`, `dataModelList`, `dataVariablesList`, `dataInterfaceList`, and `dataResponsesList`. Used by `manage_inputs()`.
- `void receive_db_buffer ()`
MPI receive of a large buffer containing `strategySpec` and all objects in `dataMethodList`, `dataModelList`, `dataVariablesList`, `dataInterfaceList`, and `dataResponsesList`. Used by `manage_inputs()`.

Private Attributes

- `ParallelLibrary & parallelLib`
reference to the `parallel_lib` object passed from main
- [List< DataMethod >::iterator](#) `dataMethodIter`
iterator identifying the active list node in `dataMethodList`

- [List< DataModel >::iterator dataModelIter](#)
iterator identifying the active list node in dataModelList
- [List< DataVariables >::iterator dataVariablesIter](#)
iterator identifying the active list node in dataVariablesList
- [List< DataInterface >::iterator dataInterfaceIter](#)
iterator identifying the active list node in dataInterfaceList
- [List< DataResponses >::iterator dataResponsesIter](#)
iterator identifying the active list node in dataResponsesList
- [IteratorList iteratorList](#)
list of iterator objects, one for each method specification
- [ModelList modelList](#)
list of model objects, one for each model specification
- [VariablesList variablesList](#)
list of variables objects, one for each variables specification
- [InterfaceList interfaceList](#)
list of interface objects, one for each interface specification
- [ResponseList responseList](#)
list of response objects, one for each responses specification
- [bool dbLocked](#)
prevents use of get_<type> data retrieval functions prior to a set_db_list_nodes invocation
- [ProblemDescDB * dbRep](#)
pointer to the letter (initialized only for the envelope)
- [int referenceCount](#)
number of objects sharing dbRep

10.83.1 Detailed Description

The database containing information parsed from the DAKOTA input file.

The [ProblemDescDB](#) class is a database for DAKOTA input file data that is populated by a parser defined in a derived class. When the parser reads a complete keyword (delimited by a newline), it populates a data class object ([DataStrategy](#), [DataMethod](#), [DataVariables](#), [DataInterface](#), or [DataResponses](#)) and, for all cases except strategy, appends the object to a linked list ([dataMethodList](#), [dataVariablesList](#), [dataInterfaceList](#), or [dataResponsesList](#)). No strategy linked list is used since only one strategy specification is allowed.

10.83.2 Constructor & Destructor Documentation

10.83.2.1 [ProblemDescDB \(\)](#)

default constructor

The default constructor: dbRep is NULL in this case. This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

10.83.2.2 [ProblemDescDB \(ParallelLibrary & parallel_lib\)](#)

standard constructor

This is the primary envelope constructor which uses problem_db to build a fully populated db object. It only needs to extract enough data to properly execute get_db(problem_db), since the constructor overloaded with [BaseConstructor](#) builds the actual base class data inherited by the derived classes.

10.83.2.3 [ProblemDescDB \(const ProblemDescDB & db\)](#)

copy constructor

Copy constructor manages sharing of dbRep and incrementing of referenceCount.

10.83.2.4 [~ProblemDescDB \(\)](#)

destructor

Destructor decrements referenceCount and only deletes dbRep when referenceCount reaches zero.

10.83.2.5 [ProblemDescDB \(BaseConstructor, ParallelLibrary & parallel_lib\)](#) [protected]

constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all derived classes. [get_db\(\)](#) instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list (to avoid the recursion of the base class constructor calling [get_db\(\)](#) again). Since the letter IS the representation, its representation pointer is set to NULL (an uninitialized pointer causes problems in [~ProblemDescDB](#)).

10.83.3 Member Function Documentation

10.83.3.1 ProblemDescDB operator= (const ProblemDescDB & db)

assignment operator

Assignment operator decrements referenceCount for old dbRep, assigns new dbRep, and increments referenceCount for new dbRep.

10.83.3.2 void manage_inputs (CommandLineHandler & cmd_line_handler)

parses the input file and populates the problem description database. This version reads from the dakota input filename passed with the "-input" option on the DAKOTA command line.

Manage command line inputs using the [CommandLineHandler](#) class and parse the input file.

10.83.3.3 void manage_inputs (const char * dakota_input_file)

parses the input file and populates the problem description database. This version reads from the dakota input filename passed in.

Parse the input file.

10.83.3.4 ProblemDescDB * get_db (ParallelLibrary & parallel_lib) [private]

Used by the standard envelope constructor to instantiate the correct letter class.

Initializes dbRep to the appropriate derived type. The standard derived class constructors are invoked.

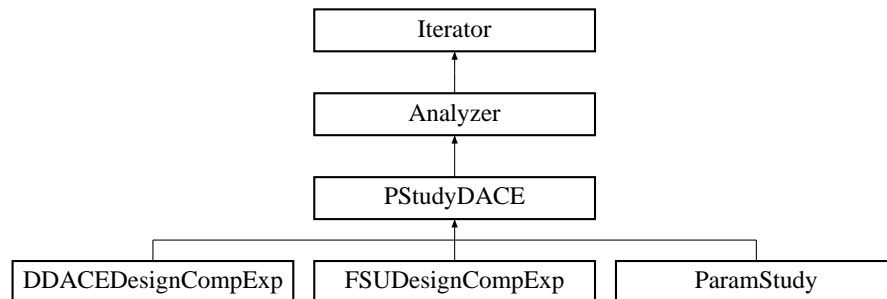
The documentation for this class was generated from the following files:

- ProblemDescDB.H
- ProblemDescDB.C

10.84 PStudyDACE Class Reference

Base class for managing common aspects of parameter studies and design of experiments methods.

Inheritance diagram for PStudyDACE::



Protected Member Functions

- [PStudyDACE](#) ([Model](#) &model)
constructor
- [~PStudyDACE](#) ()
destructor
- void [run](#) ()
run the iterator; portion of [run_iterator\(\)](#)
- const [Variables](#) & [variable_results](#) () const
return the final iterator solution (variables)
- const [Response](#) & [response_results](#) () const
return the final iterator solution (response)
- void [response_results_active_set](#) (const [ActiveSet](#) &set)
set the requested data for the final iterator response results
- void [print_results](#) (ostream &s) const
print the final iterator results
- virtual void [extract_trends](#) ()=0
Redefines the [run_iterator](#) virtual function for the PStudy/DACE branch.

- void `update_best` (const `RealVector` &vars, const `Response` &response, const int eval_num)
compares current evaluation to best evaluation and updates best

Protected Attributes

- Variables `bestVariables`
best variables found during the study
- Response `bestResponses`
best responses found during the study
- Real `bestObjFn`
best objective function found during the study
- Real `bestConViol`
best constraint violations found during the study. In the current approach, constraint violation reduction takes strict precedence over objective function reduction.
- size_t `numObjFns`
number of objective functions
- size_t `numLSqTerms`
number of least squares terms
- `RealVector` `multiObjWts`
vector of multiobjective weights

10.84.1 Detailed Description

Base class for managing common aspects of parameter studies and design of experiments methods.

The `PStudyDACE` base class manages common data and functions, such as those involving the best solutions located during the parameter set evaluations or the printing of final results.

10.84.2 Member Function Documentation

10.84.2.1 void run () [inline, protected, virtual]

run the iterator; portion of `run_iterator()`

`Iterator` supports a construct/pre-run/run/post-run/destroy progression. This function is the virtual run function for the iterator class hierarchy. All derived classes need to redefine it.

Reimplemented from [Iterator](#).

10.84.2.2 void print_results (ostream & s) const [protected, virtual]

print the final iterator results

This virtual function provides additional iterator-specific final results outputs beyond the function evaluation summary printed in [post_run\(\)](#).

Reimplemented from [Iterator](#).

The documentation for this class was generated from the following files:

- DakotaPStudyDACE.H
- DakotaPStudyDACE.C

10.85 Response Class Reference

Container class for response functions and their derivatives. [Response](#) provides the handle class.

Public Member Functions

- [Response](#) ()
default constructor
- [Response](#) (const [Variables](#) &vars, const [ProblemDescDB](#) &problem_db)
standard constructor built from problem description database
- [Response](#) (const [ActiveSet](#) &set)
alternate constructor using limited data
- [Response](#) (const [Response](#) &response)
copy constructor
- [~Response](#) ()
destructor
- [Response operator=](#) (const [Response](#) &response)
assignment operator
- [size_t num_functions](#) () const
return the number of response functions
- const [ActiveSet](#) & [active_set](#) () const
return the active set
- void [active_set](#) (const [ActiveSet](#) &set)
set the active set
- const [IntArray](#) & [active_set_request_vector](#) () const
return the active set request vector
- void [active_set_request_vector](#) (const [IntArray](#) &asrv)
set the active set request vector
- const [IntArray](#) & [active_set_derivative_vector](#) () const
return the active set derivative vector

- void `active_set_derivative_vector` (const `IntArray` &asdv)
set the active set derivative vector
- const `String` & `responses_id` () const
return the response identifier
- const `StringArray` & `fn_tags` () const
return the function identifier strings
- void `fn_tags` (const `StringArray` &tags)
set the function identifier strings
- const `RealVector` & `function_values` () const
return the function values
- void `function_values` (const `RealVector` &function_vals)
set the function values
- const `RealMatrix` & `function_gradients` () const
return the function gradients
- void `function_gradients` (const `RealMatrix` &function_grads)
set the function gradients
- const `RealMatrixArray` & `function_hessians` () const
return the function Hessians
- void `function_hessians` (const `RealMatrixArray` &function_hessians)
set the function Hessians
- void `read` (istream &s)
read a response object from an istream
- void `write` (ostream &s) const
write a response object to an ostream
- void `read_annotated` (istream &s)
read a response object in annotated format from an istream
- void `write_annotated` (ostream &s) const
write a response object in annotated format to an ostream
- void `read_tabular` (istream &s)
read responseRep::functionValues in tabular format from an istream
- void `write_tabular` (ostream &s) const

write responseRep::functionValues in tabular format to an ostream

- void [read](#) ([BiStream](#) &s)
read a response object from the binary restart stream
- void [write](#) ([BoStream](#) &s) const
write a response object to the binary restart stream
- void [read](#) ([MPIUnpackBuffer](#) &s)
read a response object from a packed MPI buffer
- void [write](#) ([MPIPackBuffer](#) &s) const
write a response object to a packed MPI buffer
- [Response copy](#) () const
a deep copy for use in history mechanisms
- int [data_size](#) ()
handle class forward to corresponding body class member function
- void [read_data](#) (double *response_data)
handle class forward to corresponding body class member function
- void [write_data](#) (double *response_data)
handle class forward to corresponding body class member function
- void [overlay](#) (const [Response](#) &response)
handle class forward to corresponding body class member function
- void [copy_results](#) (const [Response](#) &response)
Used in place of operator= when only results data updates are desired (functionValues/functionGradients/function-Hessians are updated, ASV/tags/id's/etc. are not). Care is taken to allow different derivative array sizing between the two response objects.
- void [copy_results](#) (const [RealVector](#) &source_fn_vals, const [RealMatrix](#) &source_fn_grads, const [RealMatrixArray](#) &source_fn_hessians, const [ActiveSet](#) &source_set)
Overloaded form which allows update from components of a response object. Care is taken to allow different derivative array sizing.
- void [reset](#) ()
handle class forward to corresponding body class member function
- void [reset_inactive](#) ()
handle class forward to corresponding body class member function
- bool [is_null](#) () const
function to check responseRep (does this handle contain a body)

Private Attributes

- [ResponseRep](#) * [responseRep](#)
pointer to the body (handle-body idiom)

Friends

- bool [operator==](#) (const [Response](#) &resp1, const [Response](#) &resp2)
equality operator
- bool [operator!=](#) (const [Response](#) &resp1, const [Response](#) &resp2)
inequality operator

10.85.1 Detailed Description

Container class for response functions and their derivatives. [Response](#) provides the handle class.

The [Response](#) class is a container class for an abstract set of functions (functionValues) and their first (functionGradients) and second (functionHessians) derivatives. The functions may involve objective and constraint functions (optimization data set), least squares terms (parameter estimation data set), or generic response functions (uncertainty quantification data set). It is not currently part of a class hierarchy, since the abstraction has been sufficiently general and has not required specialization. For memory efficiency, it employs the "handle-body idiom" approach to reference counting and representation sharing (see Coplien "Advanced C++", p. 58), for which [Response](#) serves as the handle and [ResponseRep](#) serves as the body.

10.85.2 Constructor & Destructor Documentation

10.85.2.1 [Response](#) ()

default constructor

Need a populated problem description database to build a meaningful [Response](#) object, so set the `responseRep=NULL` in default constructor for efficiency. This then requires a check on NULL in the copy constructor, assignment operator, and destructor.

The documentation for this class was generated from the following files:

- `DakotaResponse.H`
- `DakotaResponse.C`

10.86 ResponseRep Class Reference

Container class for response functions and their derivatives. [ResponseRep](#) provides the body class.

Private Member Functions

- [ResponseRep](#) ()
default constructor
- [ResponseRep](#) (const [Variables](#) &vars, const [ProblemDescDB](#) &problem_db)
standard constructor built from problem description database
- [ResponseRep](#) (const [ActiveSet](#) &set)
alternate constructor using limited data
- [~ResponseRep](#) ()
destructor
- void [read](#) (istream &s)
read a responseRep object from an istream
- void [write](#) (ostream &s) const
write a responseRep object to an ostream
- void [read_annotated](#) (istream &s)
read a responseRep object from an istream (annotated format)
- void [write_annotated](#) (ostream &s) const
write a responseRep object to an ostream (annotated format)
- void [read_tabular](#) (istream &s)
read functionValues from an istream (tabular format)
- void [write_tabular](#) (ostream &s) const
write functionValues to an ostream (tabular format)
- void [read](#) ([BiStream](#) &s)
read a responseRep object from a binary stream
- void [write](#) ([BoStream](#) &s) const
write a responseRep object to a binary stream

- void [read](#) ([MPIUnpackBuffer](#) &s)
read a responseRep object from a packed MPI buffer
- void [write](#) ([MPIPackBuffer](#) &s) const
write a responseRep object to a packed MPI buffer
- int [data_size](#) ()
return the number of doubles active in response. Used for sizing double response_data arrays passed into read_data and write_data.*
- void [read_data](#) (double *response_data)
read from an incoming double array*
- void [write_data](#) (double *response_data)
write to an incoming double array*
- void [overlay](#) (const [Response](#) &response)
add incoming response to functionValues/Gradients/Hessians
- void [copy_results](#) (const [RealVector](#) &source_fn_vals, const [RealMatrix](#) &source_fn_grads, const [RealMatrixArray](#) &source_fn_hessians, const [ActiveSet](#) &source_set)
update this response object from components of another response object
- void [reshape](#) (const size_t &num_fns, const size_t &num_params, bool grad_flag, bool hess_flag)
reshapes response data arrays
- void [reset](#) ()
resets all response data to zero
- void [reset_inactive](#) ()
resets all inactive response data to zero
- void [active_set_request_vector](#) (const [IntArray](#) &asrv)
set the active set request vector and verify consistent number of response functions
- void [active_set_derivative_vector](#) (const [IntArray](#) &asdv)
set the active set derivative vector and reshape functionGradients/functionHessians if needed

Private Attributes

- int [referenceCount](#)
number of handle objects sharing responseRep
- [RealVector](#) [functionValues](#)
abstract set of functions

- [RealMatrix functionGradients](#)
first derivatives
- [RealMatrixArray functionHessians](#)
second derivatives
- [ActiveSet responseActiveSet](#)
copy of the [ActiveSet](#) used by the [Model](#) to generate a [Response](#) instance
- [StringArray fnTags](#)
function identifiers used to improve output readability
- [String idResponses](#)
response identifier string from the input file

Friends

- class [Response](#)
the handle class can access attributes of the body class directly
- bool [operator==](#) (const [ResponseRep](#) &rep1, const [ResponseRep](#) &rep2)
equality operator

10.86.1 Detailed Description

Container class for response functions and their derivatives. [ResponseRep](#) provides the body class.

The [ResponseRep](#) class is the "representation" of the response container class. It is the "body" portion of the "handle-body idiom" (see Coplien "Advanced C++", p. 58). The handle class ([Response](#)) provides for memory efficiency in management of multiple response objects through reference counting and representation sharing. The body class ([ResponseRep](#)) actually contains the response data (functionValues, functionGradients, functionHessians, etc.). The representation is hidden in that an instance of [ResponseRep](#) may only be created by [Response](#). Therefore, programmers create instances of the [Response](#) handle class, and only need to be aware of the handle/body mechanisms when it comes to managing shallow copies (shared representation) versus deep copies (separate representation used for history mechanisms).

10.86.2 Constructor & Destructor Documentation

10.86.2.1 ResponseRep (const Variables & vars, const ProblemDescDB & problem_db) [private]

standard constructor built from problem description database

The standard constructor used by Dakota::ModelRep.

10.86.2.2 ResponseRep (const ActiveSet & set) [private]

alternate constructor using limited data

Used for building a response object of the correct size on the fly (e.g., by slave analysis servers performing `execute()` on a `local_response`). `fnTags` is not needed for this purpose since it's not passed in the MPI send/recv buffers. However, NPSOLOptimizer's user-defined functions option uses this constructor to build `bestResponses` and `bestResponses` needs `fnTags` for I/O, so construction of `fnTags` has been added.

10.86.3 Member Function Documentation**10.86.3.1 void read (istream & s) [private]**

read a responseRep object from an istream

ASCII version of `read` needs capabilities for capturing data omissions or formatting errors (resulting from user error or asynch race condition) and analysis failures (resulting from nonconvergence, instability, etc.).

10.86.3.2 void write (ostream & s) const [private]

write a responseRep object to an ostream

ASCII version of `write`.

10.86.3.3 void read_annotated (istream & s) [private]

read a responseRep object from an istream (annotated format)

`read_annotated()` is used for neutral file translation of restart files. Since objects are built solely from this data, annotations are used. This version closely mirrors the `BiStream` version.

10.86.3.4 void write_annotated (ostream & s) const [private]

write a responseRep object to an ostream (annotated format)

`write_annotated()` is used for neutral file translation of restart files. Since objects need to be build solely from this data, annotations are used. This version closely mirrors the `BoStream` version, with the exception of the use of white space between fields.

10.86.3.5 void read_tabular (istream & s) [private]

read functionValues from an istream (tabular format)

read_tabular is used to read functionValues in tabular format. It is currently only used by ApproximationInterfaces in reading samples from a file. There is insufficient data in a tabular file to build complete response objects; rather, the response object must be constructed a priori and then its functionValues can be set.

10.86.3.6 void write_tabular (ostream & s) const [private]

write functionValues to an ostream (tabular format)

write_tabular is used for output of functionValues in a tabular format for convenience in post-processing/plotting of DAKOTA results.

10.86.3.7 void read (BiStream & s) [private]

read a responseRep object from a binary stream

Binary version differs from ASCII version in 2 primary ways: (1) it lacks formatting. (2) the [Response](#) has not been sized a priori. In reading data from the binary restart file, a [ParamResponsePair](#) was constructed with its default constructor which called the [Response](#) default constructor. Therefore, we must first read sizing data and resize all of the arrays.

10.86.3.8 void write (BoStream & s) const [private]

write a responseRep object to a binary stream

Binary version differs from ASCII version in 2 primary ways: (1) It lacks formatting. (2) In reading data from the binary restart file, ParamResponsePairs are constructed with their default constructor which calls the [Response](#) default constructor. Therefore, we must first write sizing data so that ResponseRep::read(BoStream& s) can resize the arrays.

10.86.3.9 void read (MPIUnpackBuffer & s) [private]

read a responseRep object from a packed MPI buffer

UnpackBuffer version differs from [BiStream](#) version in the omission of fnTags. Master processor retains function tags and interface ids and communicates asv and response data only with slaves.

10.86.3.10 void write (MPIPackBuffer & s) const [private]

write a responseRep object to a packed MPI buffer

[MPIPackBuffer](#) version differs from [BoStream](#) version only in the omission of fnTags. The master processor retains tags and ids and communicates asv and response data only with slaves.

10.86.3.11 `void copy_results (const RealVector & source_fn_vals, const RealMatrix & source_fn_grads, const RealMatrixArray & source_fn_hessians, const ActiveSet & source_set) [private]`

update this response object from components of another response object

Copy function values/gradients/Hessians data `_only_`. Prevents unwanted overwriting of responseActiveSet, fnTags, etc. Also, care is taken to account for differences in derivative variable matrix sizing.

10.86.3.12 `void reshape (const size_t & num_fns, const size_t & num_params, bool grad_flag, bool hess_flag) [private]`

reshapes response data arrays

Reshape functionValues, functionGradients, and functionHessians according to num_fns, num_params, grad_flag, and hess_flag.

10.86.3.13 `void reset () [private]`

resets all response data to zero

Reset all numerical response data (not tags, ids, or active set) to zero.

10.86.3.14 `void reset_inactive () [private]`

resets all inactive response data to zero

Used to clear out any inactive data left over from previous evaluations.

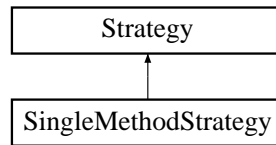
The documentation for this class was generated from the following files:

- DakotaResponse.H
- DakotaResponse.C

10.87 SingleMethodStrategy Class Reference

Simple fall-through strategy for running a single iterator on a single model.

Inheritance diagram for SingleMethodStrategy::



Public Member Functions

- [SingleMethodStrategy \(ProblemDescDB &problem_db\)](#)
constructor
- [~SingleMethodStrategy \(\)](#)
destructor
- void [run_strategy \(\)](#)
Perform the strategy by executing selectedIterator on userDefinedModel.
- const [Variables & variable_results \(\)](#) const
return the final solution from selectedIterator (variables)
- const [Response & response_results \(\)](#) const
return the final solution from selectedIterator (response)

Private Attributes

- [Model userDefinedModel](#)
the model to be iterated
- [Iterator selectedIterator](#)
the iterator

10.87.1 Detailed Description

Simple fall-through strategy for running a single iterator on a single model.

This strategy executes a single iterator on a single model. Since it does not provide coordination for multiple iterators and models, it can be considered to be a "fall-through" strategy in that it allows control to fall through immediately to the iterator.

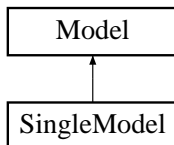
The documentation for this class was generated from the following files:

- SingleMethodStrategy.H
- SingleMethodStrategy.C

10.88 SingleModel Class Reference

Derived model class which utilizes a single interface to map variables into responses.

Inheritance diagram for SingleModel::



Public Member Functions

- [SingleModel](#) ([ProblemDescDB](#) &problem_db)
constructor
- [~SingleModel](#) ()
destructor

Protected Member Functions

- [Interface](#) & [interface](#) ()
return userDefinedInterface
- void [derived_compute_response](#) (const [ActiveSet](#) &set)
portion of [compute_response\(\)](#) specific to [SingleModel](#) (invokes a synchronous map() on userDefinedInterface)
- void [derived_asynch_compute_response](#) (const [ActiveSet](#) &set)
portion of [asynch_compute_response\(\)](#) specific to [SingleModel](#) (invokes an asynchronous map() on userDefinedInterface)
- const [ResponseArray](#) & [derived_synchronize](#) ()
portion of [synchronize\(\)](#) specific to [SingleModel](#) (invokes synch() on userDefinedInterface)
- const [IntResponseMap](#) & [derived_synchronize_nowait](#) ()
portion of [synchronize_nowait\(\)](#) specific to [SingleModel](#) (invokes synch_nowait() on userDefinedInterface)
- void [component_parallel_mode](#) (int mode)
[SingleModel](#) only supports parallelism in userDefinedInterface, so this virtual function redefinition is simply a sanity check.

- [String local_eval_synchronization \(\)](#)
return userDefinedInterface synchronization setting
- [int local_eval_concurrency \(\)](#)
return userDefinedInterface asynchronous evaluation concurrency
- [bool derived_master_overload \(\) const](#)
flag which prevents overloading the master with a multiprocessor evaluation (request forwarded to userDefinedInterface)
- [void derived_init_communicators \(const int &max_iterator_concurrency\)](#)
set up SingleModel for parallel operations (request forwarded to userDefinedInterface)
- [void derived_init_serial \(\)](#)
set up SingleModel for serial operations (request forwarded to userDefinedInterface).
- [void reset_communicators \(\)](#)
reset communicator partition data for the SingleModel (request forwarded to userDefinedInterface)
- [void derived_free_communicators \(const int &max_iterator_concurrency\)](#)
deallocate communicator partitions for the SingleModel (request forwarded to userDefinedInterface)
- [void serve \(\)](#)
Service userDefinedInterface job requests received from the master. Completes when a termination message is received from stop_servers().
- [void stop_servers \(\)](#)
executed by the master to terminate userDefinedInterface server operations when SingleModel iteration is complete.
- [int evaluation_id \(\) const](#)
return the current evaluation id for the SingleModel (request forwarded to userDefinedInterface)
- [void set_evaluation_reference \(\)](#)
set the evaluation counter reference points for the SingleModel (request forwarded to userDefinedInterface)
- [void print_evaluation_summary \(ostream &s, bool minimal_header=false, bool relative_count=true\) const](#)
print the evaluation summary for the SingleModel (request forwarded to userDefinedInterface)

Private Attributes

- [Interface userDefinedInterface](#)
the interface used for mapping variables to responses

10.88.1 Detailed Description

Derived model class which utilizes a single interface to map variables into responses.

The [SingleModel](#) class is the simplest of the derived model classes. It provides the capabilities the old [Model](#) class, prior to the development of surrogate and nested model extensions. The derived response computation and synchronization functions utilize a single interface to perform the function evaluations.

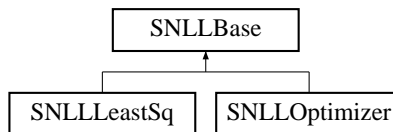
The documentation for this class was generated from the following files:

- [SingleModel.H](#)
- [SingleModel.C](#)

10.89 SNLLBase Class Reference

Base class for OPT++ optimization and least squares methods.

Inheritance diagram for SNLLBase::



Public Member Functions

- [SNLLBase \(\)](#)
default constructor
- [SNLLBase \(Model &model\)](#)
standard constructor
- [~SNLLBase \(\)](#)
destructor

Protected Member Functions

- void [copy_con_vals](#) (const [RealVector](#) &local_fn_vals, [NEWMAT::ColumnVector](#) &g, const size_t &offset)
convenience function for copying local_fn_vals to g; used by constraint evaluator functions
- void [copy_con_vals](#) (const [NEWMAT::ColumnVector](#) &g, [RealVector](#) &local_fn_vals, const size_t &offset)
convenience function for copying g to local_fn_vals; used in final solution logging
- void [copy_con_grad](#) (const [RealMatrix](#) &local_fn_grads, [NEWMAT::Matrix](#) &grad_g, const size_t &offset)
convenience function for copying local_fn_grads to grad_g; used by constraint evaluator functions
- void [copy_con_hess](#) (const [RealMatrixArray](#) &local_fn_hessians, [OPTPP::OptppArray](#)<[NEWMAT::SymmetricMatrix](#)> &hess_g, const size_t &offset)
convenience function for copying local_fn_hessians to hess_g; used by constraint evaluator functions
- void [snll_pre_instantiate](#) (const [String](#) &merit_fn, bool bound_constr_flag, const int &num_constr)

convenience function for setting OPT++ options prior to the method instantiation

- void `snll_post_instantiate` (const int &num_cv, bool vendor_num_grad_flag, const [String](#) &finite_diff_type, const Real &fdss, const int &max_iter, const int &max_fn_evals, const Real &conv_tol, const Real &grad_tol, const Real &max_step, bool bound_constr_flag, const int &num_constr, bool debug_output, OPTPP::OptimizeClass *the_optimizer, OPTPP::NLP0 *nlf_objective, OPTPP::FDNLF1 *fd_nlf1, OPTPP::FDNLF1 *fd_nlf1_con)

convenience function for setting OPT++ options after the method instantiation

- void `snll_pre_run` (OPTPP::NLP0 *nlf_objective, OPTPP::NLP *nlp_constraint, const [RealVector](#) &init_pt, bool bound_constr_flag, const [RealVector](#) &lower_bnds, const [RealVector](#) &upper_bnds, const [RealMatrix](#) &lin_ineq_coeffs, const [RealVector](#) &lin_ineq_l_bnds, const [RealVector](#) &lin_ineq_u_bnds, const [RealMatrix](#) &lin_eq_coeffs, const [RealVector](#) &lin_eq_targets, const [RealVector](#) &nln_ineq_l_bnds, const [RealVector](#) &nln_ineq_u_bnds, const [RealVector](#) &nln_eq_targets)

convenience function for OPT++ configuration prior to the method invocation

- void `snll_post_run` (OPTPP::NLP0 *nlf_objective)

convenience function for setting OPT++ options after the method instantiations

Static Protected Member Functions

- static void `init_fn` (int n, NEWMAT::ColumnVector &x)

An initialization mechanism provided by OPT++ (not currently used).

Protected Attributes

- [String](#) `searchMethod`

value_based_line_search, gradient_based_line_search, trust_region, or tr_pds

- OPTPP::SearchStrategy `searchStrat`

enum: LineSearch, TrustRegion, or TrustPDS

- OPTPP::MeritFcn `meritFn`

enum: NormFmu, ArgaezTapia, or VanShanno

- bool `constantASVFlag`

flags a user selection of active_set_vector == constant. By mapping this into mode override, reliance on duplicate detection can be avoided.

Static Protected Attributes

- static [Minimizer](#) * `optLSqInstance`

pointer to the active base class object instance used within the static evaluator functions in order to avoid the need for static data

- static bool [modeOverrideFlag](#)
flags OPT++ mode override (for combining value, gradient, and Hessian requests)
- static EvalType [lastFnEvalLocn](#)
an enum used to track whether an nlf evaluator or a constraint evaluator was the last location of a function evaluation
- static int [lastEvalMode](#)
copy of mode from constraint evaluators
- static [RealVector](#) [lastEvalVars](#)
copy of variables from constraint evaluators

10.89.1 Detailed Description

Base class for OPT++ optimization and least squares methods.

The [SNLLBase](#) class provides a common base class for [SNLLOptimizer](#) and [SNLLLeastSq](#), both of which are wrappers for OPT++, a C++ optimization library from the Computational Sciences and Mathematics Research (CSMR) department at Sandia's Livermore CA site.

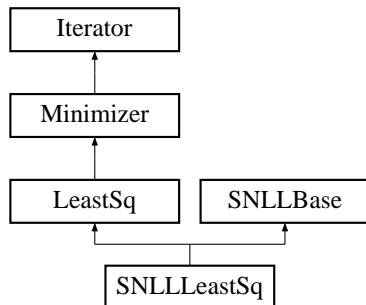
The documentation for this class was generated from the following files:

- [SNLLBase.H](#)
- [SNLLBase.C](#)

10.90 SNLLLeastSq Class Reference

Wrapper class for the OPT++ optimization library.

Inheritance diagram for SNLLLeastSq::



Public Member Functions

- [SNLLLeastSq \(Model &model\)](#)
constructor
- [~SNLLLeastSq \(\)](#)
destructor
- void [minimize_residuals \(\)](#)
Performs the iterations to determine the least squares solution.

Protected Member Functions

- virtual void [derived_pre_run \(\)](#)
invokes [SNLLBase::snll_pre_run\(\)](#) and performs other set-up
- virtual void [derived_post_run \(\)](#)
invokes [SNLLBase::snll_post_run\(\)](#) and performs other solution processing

Static Private Member Functions

- static void [nlf2_evaluator_gn](#) (int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::Real &f, NEWMAT::ColumnVector &grad_f, NEWMAT::SymmetricMatrix &hess_f, int &result_mode)

objective function evaluator function which obtains values and gradients for least square terms and computes objective function value, gradient, and Hessian using the Gauss-Newton approximation.

- static void [constraint1_evaluator_gn](#) (int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::ColumnVector &g, NEWMAT::Matrix &grad_g, int &result_mode)
constraint evaluator function which provides constraint values and gradients to OPT++ Gauss-Newton methods.
- static void [constraint2_evaluator_gn](#) (int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::ColumnVector &g, NEWMAT::Matrix &grad_g, OPTPP::OptppArray< NEWMAT::SymmetricMatrix > &hess_g, int &result_mode)
constraint evaluator function which provides constraint values, gradients, and Hessians to OPT++ Gauss-Newton methods.

Private Attributes

- OPTPP::NLP0 * [nlfObjective](#)
objective NLF base class pointer
- OPTPP::NLP0 * [nlfConstraint](#)
constraint NLF base class pointer
- OPTPP::NLP * [nlpConstraint](#)
constraint NLP pointer
- OPTPP::NLF2 * [nlf2](#)
pointer to objective NLF for full Newton optimizers
- OPTPP::NLF2 * [nlf2Con](#)
pointer to constraint NLF for full Newton optimizers
- OPTPP::NLF1 * [nlf1Con](#)
pointer to constraint NLF for Quasi Newton optimizers
- OPTPP::OptimizeClass * [theOptimizer](#)
optimizer base class pointer
- OPTPP::OptNewton * [optnewton](#)
Newton optimizer pointer.
- OPTPP::OptBCNewton * [optbcnewton](#)
Bound constrained Newton optimizer ptr.
- OPTPP::OptDHNIPS * [optdhnips](#)
Disaggregated Hessian NIPS optimizer ptr.

Static Private Attributes

- static [SNLLLeastSq](#) * [snllSqInstance](#)

pointer to the active object instance used within the static evaluator functions in order to avoid the need for static data

10.90.1 Detailed Description

Wrapper class for the OPT++ optimization library.

The [SNLLLeastSq](#) class provides a wrapper for OPT++, a C++ optimization library of nonlinear programming and pattern search techniques from the Computational Sciences and Mathematics Research (CSMR) department at Sandia's Livermore CA site. It uses a function pointer approach for which passed functions must be either global functions or static member functions. Any attribute used within static member functions must be either local to that function, a static member, or accessed by static pointer.

The user input mappings are as follows: `max_iterations`, `max_function_evaluations`, `convergence_tolerance`, `max_step`, `gradient_tolerance`, `search_method`, and `search_scheme_size` are set using OPT++'s `setMaxIter()`, `setMaxFeval()`, `setFcnTol()`, `setMaxStep()`, `setGradTol()`, `setSearchStrategy()`, and `setSSS()` member functions, respectively; `output_verbosity` is used to toggle OPT++'s debug mode using the `setDebug()` member function. Internal to OPT++, there are 3 search strategies, while the DAKOTA `search_method` specification supports 4 (`value_based_line_search`, `gradient_based_line_search`, `trust_region`, or `tr_pds`). The difference stems from the "is_expensive" flag in OPT++. If the search strategy is `LineSearch` and "is_expensive" is turned on, then the `value_based_line_search` is used. Otherwise (the "is_expensive" default is off), the algorithm will use the `gradient_based_line_search`. Refer to [Meza, J.C., 1994] and to the OPT++ source in the `Dakota/VendorOptimizers/opt++` directory for information on OPT++ class member functions.

10.90.2 Member Function Documentation

10.90.2.1 `void nlf2_evaluator_gn(int mode, int n, const NEWMAT::ColumnVector & x, NEWMAT::Real & f, NEWMAT::ColumnVector & grad_f, NEWMAT::SymmetricMatrix & hess_f, int & result_mode)` [static, private]

objective function evaluator function which obtains values and gradients for least square terms and computes objective function value, gradient, and Hessian using the Gauss-Newton approximation.

This nlf2 evaluator function is used for the Gauss-Newton method in order to exploit the special structure of the nonlinear least squares problem. Here, $fx = \sum (T_i - Tbar_i)^2$ and [Response](#) is made up of residual functions and their gradients along with any nonlinear constraints. The objective function and its gradient vector and Hessian matrix are computed directly from the residual functions and their derivatives (which are returned from the [Response](#) object).

10.90.2.2 `void constraint1_evaluator_gn (int mode, int n, const NEWMAT::ColumnVector & x, NEWMAT::ColumnVector & g, NEWMAT::Matrix & grad_g, int & result_mode) [static, private]`

constraint evaluator function which provides constraint values and gradients to OPT++ Gauss-Newton methods.

While it does not employ the Gauss-Newton approximation, it is distinct from `constraint1_evaluator()` due to its need to anticipate the required modes for the least squares terms. This constraint evaluator function is used with diagggregated Hessian NIPS and is currently active.

10.90.2.3 `void constraint2_evaluator_gn (int mode, int n, const NEWMAT::ColumnVector & x, NEWMAT::ColumnVector & g, NEWMAT::Matrix & grad_g, OPTPP::OptppArray< NEWMAT::SymmetricMatrix > & hess_g, int & result_mode) [static, private]`

constraint evaluator function which provides constraint values, gradients, and Hessians to OPT++ Gauss-Newton methods.

While it does not employ the Gauss-Newton approximation, it is distinct from `constraint2_evaluator()` due to its need to anticipate the required modes for the least squares terms. This constraint evaluator function is used with full Newton NIPS and is currently inactive.

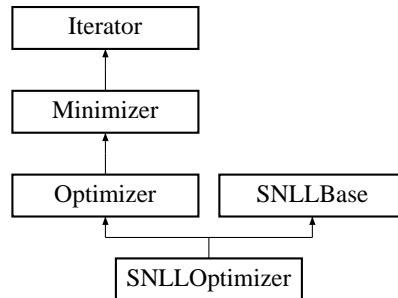
The documentation for this class was generated from the following files:

- SNLLLeastSq.H
- SNLLLeastSq.C

10.91 SNLLOptimizer Class Reference

Wrapper class for the OPT++ optimization library.

Inheritance diagram for SNLLOptimizer::



Public Member Functions

- [SNLLOptimizer \(Model &model\)](#)
standard constructor
- [SNLLOptimizer \(const RealVector &initial_point, const RealVector &var_lower_bnds, const RealVector &var_upper_bnds, const RealMatrix &lin_ineq_coeffs, const RealVector &lin_ineq_lower_bnds, const RealVector &lin_ineq_upper_bnds, const RealMatrix &lin_eq_coeffs, const RealVector &lin_eq_targets, const RealVector &nonlin_ineq_lower_bnds, const RealVector &nonlin_ineq_upper_bnds, const RealVector &nonlin_eq_targets, void\(*user_obj_eval\)\(int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::Real &f, NEWMAT::ColumnVector &grad_f, int &result_mode\), void\(*user_con_eval\)\(int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::ColumnVector &g, NEWMAT::Matrix &grad_g, int &result_mode\)\)](#)
alternate constructor for instantiations "on the fly"
- [~SNLLOptimizer \(\)](#)
destructor
- void [find_optimum \(\)](#)
Performs the iterations to determine the optimal solution.

Protected Member Functions

- virtual void [derived_pre_run \(\)](#)
invokes [SNLLBase::snll_pre_run\(\)](#) and performs other set-up

- virtual void `derived_post_run()`
invokes `SNLLBase::snll_post_run()` and performs other solution processing

Static Private Member Functions

- static void `nlf0_evaluator` (int n, const NEWMAT::ColumnVector &x, NEWMAT::Real &f, int &result_mode)
objective function evaluator function for OPT++ methods which require only function values.
- static void `nlf1_evaluator` (int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::Real &f, NEWMAT::ColumnVector &grad_f, int &result_mode)
objective function evaluator function which provides function values and gradients to OPT++ methods.
- static void `nlf2_evaluator` (int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::Real &f, NEWMAT::ColumnVector &grad_f, NEWMAT::SymmetricMatrix &hess_f, int &result_mode)
objective function evaluator function which provides function values, gradients, and Hessians to OPT++ methods.
- static void `constraint0_evaluator` (int n, const NEWMAT::ColumnVector &x, NEWMAT::ColumnVector &g, int &result_mode)
constraint evaluator function for OPT++ methods which require only constraint values.
- static void `constraint1_evaluator` (int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::ColumnVector &g, NEWMAT::Matrix &grad_g, int &result_mode)
constraint evaluator function which provides constraint values and gradients to OPT++ methods.
- static void `constraint2_evaluator` (int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::ColumnVector &g, NEWMAT::Matrix &grad_g, OPTPP::OptppArray<NEWMAT::SymmetricMatrix> &hess_g, int &result_mode)
constraint evaluator function which provides constraint values, gradients, and Hessians to OPT++ methods.

Private Attributes

- OPTPP::NLP0 * `nlfObjective`
objective NLF base class pointer
- OPTPP::NLP0 * `nlfConstraint`
constraint NLF base class pointer
- OPTPP::NLP * `nlpConstraint`
constraint NLP pointer
- OPTPP::NLF0 * `nlf0`
pointer to objective NLF for nongradient optimizers

- OPTPP::NLF1 * [nlf1](#)
pointer to objective NLF for (analytic) gradient-based optimizers
- OPTPP::NLF1 * [nlf1Con](#)
pointer to constraint NLF for (analytic) gradient-based optimizers
- OPTPP::FDNLF1 * [fdnlf1](#)
pointer to objective NLF for (finite diff) gradient-based optimizers
- OPTPP::FDNLF1 * [fdnlf1Con](#)
pointer to constraint NLF for (finite diff) gradient-based optimizers
- OPTPP::NLF2 * [nlf2](#)
pointer to objective NLF for full Newton optimizers
- OPTPP::NLF2 * [nlf2Con](#)
pointer to constraint NLF for full Newton optimizers
- OPTPP::OptimizeClass * [theOptimizer](#)
optimizer base class pointer
- OPTPP::OptPDS * [optpds](#)
PDS optimizer pointer.
- OPTPP::OptCG * [optcg](#)
CG optimizer pointer.
- OPTPP::OptLBFGS * [optlbfgs](#)
L-BFGS optimizer pointer.
- OPTPP::OptNewton * [optnewton](#)
Newton optimizer pointer.
- OPTPP::OptQNewton * [optqnewton](#)
Quasi-Newton optimizer pointer.
- OPTPP::OptFDNewton * [optfdnewton](#)
Finite Difference Newton opt pointer.
- OPTPP::OptBCNewton * [optbcnewton](#)
Bound constrained Newton opt pointer.
- OPTPP::OptBCQNewton * [optbcqnewton](#)
Bnd constrained Quasi-Newton opt ptr.

- [OPTPP::OptBCFDNewton](#) * [optbcfdnewton](#)
Bnd constrained FD-Newton opt ptr.
- [OPTPP::OptNIPS](#) * [optnips](#)
NIPS optimizer pointer.
- [OPTPP::OptQNIPS](#) * [optqnips](#)
Quasi-Newton NIPS optimizer pointer.
- [OPTPP::OptFDNIPS](#) * [optfdnips](#)
Finite Difference NIPS opt pointer.
- [String setUpType](#)
*flag for iteration mode: "model" (normal usage) or "user_functions" (user-supplied functions mode for "on the fly" instantiations). *NonDReliability* currently uses the user_functions mode.*
- [RealVector initialPoint](#)
holds initial point passed in for "user_functions" mode.
- [RealVector lowerBounds](#)
holds variable lower bounds passed in for "user_functions" mode.
- [RealVector upperBounds](#)
holds variable upper bounds passed in for "user_functions" mode.

Static Private Attributes

- [static SNLLOptimizer](#) * [snllOptInstance](#)
pointer to the active object instance used within the static evaluator functions in order to avoid the need for static data

10.91.1 Detailed Description

Wrapper class for the OPT++ optimization library.

The [SNLLOptimizer](#) class provides a wrapper for OPT++, a C++ optimization library of nonlinear programming and pattern search techniques from the Computational Sciences and Mathematics Research (CSMR) department at Sandia's Livermore CA site. It uses a function pointer approach for which passed functions must be either global functions or static member functions. Any attribute used within static member functions must be either local to that function, a static member, or accessed by static pointer.

The user input mappings are as follows: `max_iterations`, `max_function_evaluations`, `convergence_tolerance`, `max_step`, `gradient_tolerance`, `search_method`, and `search_scheme_size` are set using OPT++'s `setMaxIter()`, `setMaxFeval()`, `setFcnTol()`, `setMaxStep()`, `setGradTol()`, `setSearchStrategy()`, and `setSSS()` member functions, respectively; `output_verbosity` is used to toggle OPT++'s

debug mode using the `setDebug()` member function. Internal to OPT++, there are 3 search strategies, while the DAKOTA `search_method` specification supports 4 (`value_based_line_search`, `gradient_based_line_search`, `trust_region`, or `tr_pds`). The difference stems from the "is_expensive" flag in OPT++. If the search strategy is `LineSearch` and "is_expensive" is turned on, then the `value_based_line_search` is used. Otherwise (the "is_expensive" default is off), the algorithm will use the `gradient_based_line_search`. Refer to [Meza, J.C., 1994] and to the OPT++ source in the `Dakota/VendorOptimizers/opt++` directory for information on OPT++ class member functions.

10.91.2 Constructor & Destructor Documentation

10.91.2.1 `SNLLOptimizer` (Model & model)

standard constructor

This constructor is used for normal instantiations using data from the [ProblemDescDB](#).

10.91.2.2 `SNLLOptimizer` (const `RealVector` & *initial_point*, const `RealVector` & *var_lower_bnds*, const `RealVector` & *var_upper_bnds*, const `RealMatrix` & *lin_ineq_coeffs*, const `RealVector` & *lin_ineq_lower_bnds*, const `RealVector` & *lin_ineq_upper_bnds*, const `RealMatrix` & *lin_eq_coeffs*, const `RealVector` & *lin_eq_targets*, const `RealVector` & *nonlin_ineq_lower_bnds*, const `RealVector` & *nonlin_ineq_upper_bnds*, const `RealVector` & *nonlin_eq_targets*, void(*) (int mode, int n, const `NEWMAT::ColumnVector` &x, `NEWMAT::Real` &f, `NEWMAT::ColumnVector` &grad_f, int &result_mode) *user_obj_eval*, void(*) (int mode, int n, const `NEWMAT::ColumnVector` &x, `NEWMAT::ColumnVector` &g, `NEWMAT::Matrix` &grad_g, int &result_mode) *user_con_eval*)

alternate constructor for instantiations "on the fly"

This is an alternate constructor for performing an optimization using the passed in objective function and constraint function pointers.

10.91.3 Member Function Documentation

10.91.3.1 `void nlf0_evaluator` (int n, const `NEWMAT::ColumnVector` & x, `NEWMAT::Real` & f, int & result_mode) [*static, private*]

objective function evaluator function for OPT++ methods which require only function values.

For use when DAKOTA computes f and gradients are not directly available. This is used by nongradient-based optimizers such as PDS and by gradient-based optimizers in vendor numerical gradient mode (opt++'s internal finite difference routine is used).

10.91.3.2 `void nlf1_evaluator (int mode, int n, const NEWMAT::ColumnVector & x, NEWMAT::Real & f, NEWMAT::ColumnVector & grad_f, int & result_mode) [static, private]`

objective function evaluator function which provides function values and gradients to OPT++ methods.

For use when DAKOTA computes f and df/dX (regardless of gradientType). Vendor numerical gradient case is handled by nlf0_evaluator.

10.91.3.3 `void nlf2_evaluator (int mode, int n, const NEWMAT::ColumnVector & x, NEWMAT::Real & f, NEWMAT::ColumnVector & grad_f, NEWMAT::SymmetricMatrix & hess_f, int & result_mode) [static, private]`

objective function evaluator function which provides function values, gradients, and Hessians to OPT++ methods.

For use when DAKOTA receives f, df/dX, & d^2f/dx^2 from the [ApplicationInterface](#) (analytic only). Finite differencing does not make sense for a full Newton approach, since lack of analytic gradients & Hessian should dictate the use of quasi-newton or fd-newton. Thus, there is no fdnlf2_evaluator for use with full Newton approaches, since it is preferable to use quasi-newton or fd-newton with nlf1. Gauss-Newton does not fit this model; it uses nlf2_evaluator_gn instead of nlf2_evaluator.

10.91.3.4 `void constraint0_evaluator (int n, const NEWMAT::ColumnVector & x, NEWMAT::ColumnVector & g, int & result_mode) [static, private]`

constraint evaluator function for OPT++ methods which require only constraint values.

For use when DAKOTA computes g and gradients are not directly available. This is used by nongradient-based optimizers and by gradient-based optimizers in vendor numerical gradient mode (opt++'s internal finite difference routine is used).

10.91.3.5 `void constraint1_evaluator (int mode, int n, const NEWMAT::ColumnVector & x, NEWMAT::ColumnVector & g, NEWMAT::Matrix & grad_g, int & result_mode) [static, private]`

constraint evaluator function which provides constraint values and gradients to OPT++ methods.

For use when DAKOTA computes g and dg/dX (regardless of gradientType). Vendor numerical gradient case is handled by constraint0_evaluator.

10.91.3.6 `void constraint2_evaluator (int mode, int n, const NEWMAT::ColumnVector & x, NEWMAT::ColumnVector & g, NEWMAT::Matrix & grad_g, OPTPP::OptppArray< NEWMAT::SymmetricMatrix > & hess_g, int & result_mode) [static, private]`

constraint evaluator function which provides constraint values, gradients, and Hessians to OPT++ methods.

For use when DAKOTA computes g, dg/dX, & d^2g/dx^2 (analytic only).

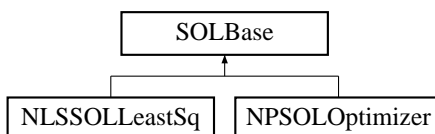
The documentation for this class was generated from the following files:

- SNLLOptimizer.H
- SNLLOptimizer.C

10.92 SOLBase Class Reference

Base class for Stanford SOL software.

Inheritance diagram for SOLBase::



Public Member Functions

- [SOLBase \(\)](#)
default constructor
- [SOLBase \(Model &model\)](#)
standard constructor
- [~SOLBase \(\)](#)
destructor

Protected Member Functions

- void [allocate_arrays](#) (const int &num_cv, const size_t &num_nln_con, const [RealMatrix](#) &lin_ineq_coeffs, const [RealMatrix](#) &lin_eq_coeffs)
Allocates miscellaneous arrays for the SOL algorithms.
- void [deallocate_arrays](#) ()
Deallocates memory previously allocated by [allocate_arrays](#)().
- void [allocate_workspace](#) (const int &num_cv, const int &num_nln_con, const int &num_lin_con, const int &num_lsq)
Allocates real and integer workspaces for the SOL algorithms.
- void [set_options](#) (bool speculative_flag, bool vendor_num_grad_flag, bool verbose_output, const int &verify_lev, const Real &fn_prec, const Real &linesrch_tol, const int &max_iter, const Real &constr_tol, const Real &conv_tol, const [String](#) &grad_type, const Real &fdss)
Sets SOL method options using calls to `npoptm2`.

- void `augment_bounds` (`RealVector` &augmented_l_bnds, `RealVector` &augmented_u_bnds, const `RealVector` &lin_ineq_l_bnds, const `RealVector` &lin_ineq_u_bnds, const `RealVector` &lin_eq_targets, const `RealVector` &nln_ineq_l_bnds, const `RealVector` &nln_ineq_u_bnds, const `RealVector` &nln_eq_targets)

augments variable bounds with linear and nonlinear constraint bounds.

Static Protected Member Functions

- static void `constraint_eval` (int &mode, int &ncnln, int &n, int &nrowj, int *needc, double *x, double *c, double *cjac, int &nstate)

CONFUN in NPSOL manual: computes the values and first derivatives of the nonlinear constraint functions.

Protected Attributes

- int `realWorkSpaceSize`
size of realWorkSpace
- int `intWorkSpaceSize`
size of intWorkSpace
- `RealArray` `realWorkSpace`
real work space for NPSOL/NLSSOL
- `IntArray` `intWorkSpace`
int work space for NPSOL/NLSSOL
- int `nlnConstraintArraySize`
used for non-zero array sizing (nonlinear constraints)
- int `linConstraintArraySize`
used for non-zero array sizing (linear constraints)
- `RealArray` `cLambda`
CLAMBDA from NPSOL manual: Langrange multipliers.
- `IntArray` `constraintState`
ISTATE from NPSOL manual: constraint status.
- int `informResult`
INFORM from NPSOL manual: optimization status on exit.
- int `numberIterations`
ITER from NPSOL manual: number of (major) iterations performed.

- int [boundsArraySize](#)
length of augmented bounds arrays (variable bounds plus linear and nonlinear constraint bounds)
- double * [linConstraintMatrixF77](#)
[A] matrix from NPSOL manual: linear constraint coefficients
- double * [upperFactorHessianF77](#)
[R] matrix from NPSOL manual: upper Cholesky factor of the Hessian of the Lagrangian.
- double * [constraintJacMatrixF77](#)
[CJAC] matrix from NPSOL manual: nonlinear constraint Jacobian
- int [fnEvalCntr](#)
counter for testing against maxFunctionEvals
- size_t [constrOffset](#)
used in [constraint_eval\(\)](#) to bridge [NLSSOLLeastSq::numLeastSqTerms](#) and [NPSOLOptimizer::numObjectiveFunctions](#)

Static Protected Attributes

- static [SOLBase](#) * [solInstance](#)
pointer to the active object instance used within the static evaluator functions in order to avoid the need for static data
- static [Minimizer](#) * [optLqInstance](#)
pointer to the active base class object instance used within the static evaluator functions in order to avoid the need for static data

10.92.1 Detailed Description

Base class for Stanford SOL software.

The [SOLBase](#) class provides a common base class for [NPSOLOptimizer](#) and [NLSSOLLeastSq](#), both of which are Fortran 77 sequential quadratic programming algorithms from Stanford University marketed by Stanford Business Associates.

The documentation for this class was generated from the following files:

- SOLBase.H
- SOLBase.C

10.93 SortCompare Class Template Reference

Public Member Functions

- `SortCompare` (`bool(*func)(const T &, const T &)`)
Constructor that defines the pointer to function.
- `bool operator()` (`const T &p1, const T &p2`) `const`
The operator() must be defined. Calls the defined sort_fn.

Private Attributes

- `bool(* sort_fn)` (`const T &, const T &`)
Pointer to test function.

10.93.1 Detailed Description

`template<class T> class Dakota::SortCompare< T >`

Internal functor used in the sort algorithm to sort using a specified compare method. The class holds a pointer to the sort function.

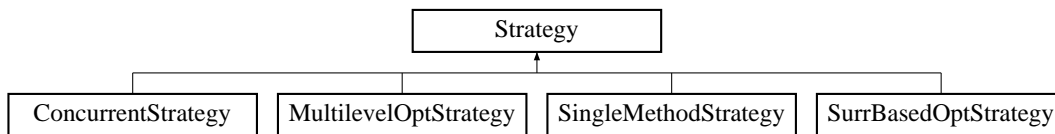
The documentation for this class was generated from the following file:

- `DakotaList.H`

10.94 Strategy Class Reference

Base class for the strategy class hierarchy.

Inheritance diagram for Strategy::



Public Member Functions

- [Strategy](#) ()
default constructor
- [Strategy](#) ([ProblemDescDB](#) &problem_db)
envelope constructor
- [Strategy](#) (const [Strategy](#) &strat)
copy constructor
- virtual [~Strategy](#) ()
destructor
- [Strategy operator=](#) (const [Strategy](#) &strat)
assignment operator
- virtual void [run_strategy](#) ()
the run function for the strategy: invoke the iterator(s) on the model(s). Called from [main.C](#).
- virtual const [Variables](#) & [variable_results](#) () const
return the final strategy solution (variables)
- virtual const [Response](#) & [response_results](#) () const
return the final strategy solution (response)
- void [run_iterator](#) ([Iterator](#) &the_iterator, [Model](#) &the_model)
Convenience function for invoking an iterator and managing parallelism. This version omits communicator repartitioning. Function must be public due to use by MINLPNode.
- [ProblemDescDB](#) & [prob_desc_db](#) () const

returns the problem description database (probDescDB)

- [ParallelLibrary](#) & [parallel_library](#) () const
returns the parallel library (parallelLib)

Protected Member Functions

- [Strategy](#) ([BaseConstructor](#), [ProblemDescDB](#) &problem_db)
constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)
- void [init_communicators](#) ([Iterator](#) &the_iterator, [Model](#) &the_model)
convenience function for allocating comms prior to running an iterator
- void [free_communicators](#) ([Iterator](#) &the_iterator, [Model](#) &the_model)
convenience function for deallocating comms after running an iterator
- void [initialize_graphics](#) (const [Model](#) &model)
convenience function for initialization of 2D graphics and data tabulation

Protected Attributes

- [ProblemDescDB](#) & [probDescDB](#)
class member reference to the problem description database
- [ParallelLibrary](#) & [parallelLib](#)
class member reference to the parallel library
- [String](#) [strategyName](#)
type of strategy: single_method, multi_level, surrogate_based_opt, opt_under_uncertainty, branch_and_bound, multi_start, or pareto_set.
- int [worldRank](#)
processor rank in MPI_COMM_WORLD
- int [worldSize](#)
size of MPI_COMM_WORLD
- int [iteratorCommRank](#)
processor rank in iteratorComm
- int [iteratorCommSize](#)
number of processors in iteratorComm

- bool [mpirunFlag](#)
flag for parallel MPI launch of DAKOTA
- bool [graphicsFlag](#)
flag for using graphics in a graphics executable
- bool [tabularDataFlag](#)
flag for file tabulation of graphics data
- String [tabularDataFile](#)
filename for tabulation of graphics data

Private Member Functions

- [Strategy](#) * [get_strategy](#) ()
Used by the envelope to instantiate the correct letter class.

Private Attributes

- [Strategy](#) * [strategyRep](#)
pointer to the letter (initialized only for the envelope)
- int [referenceCount](#)
number of objects sharing strategyRep

10.94.1 Detailed Description

Base class for the strategy class hierarchy.

The [Strategy](#) class is the base class for the class hierarchy providing the top level control in DAKOTA. The strategy is responsible for creating and managing iterators and models. For memory efficiency and enhanced polymorphism, the strategy hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Strategy](#)) serves as the envelope and one of the derived classes (selected in [Strategy::get_strategy\(\)](#)) serves as the letter.

10.94.2 Constructor & Destructor Documentation

10.94.2.1 [Strategy](#) ()

default constructor

Default constructor. `strategyRep` is NULL in this case (a populated `problem_db` is needed to build a meaningful [Strategy](#) object). This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

10.94.2.2 [Strategy](#) ([ProblemDescDB](#) & *problem_db*)

envelope constructor

Used in `main.C` instantiation to build the envelope. This constructor only needs to extract enough data to properly execute `get_strategy`, since `Strategy::Strategy(BaseConstructor, problem_db)` builds the actual base class data inherited by the derived strategies.

10.94.2.3 [Strategy](#) (const [Strategy](#) & *strat*)

copy constructor

Copy constructor manages sharing of `strategyRep` and incrementing of `referenceCount`.

10.94.2.4 [~Strategy](#) () [virtual]

destructor

Destructor decrements `referenceCount` and only deletes `strategyRep` when `referenceCount` reaches zero.

10.94.2.5 [Strategy](#) ([BaseConstructor](#), [ProblemDescDB](#) & *problem_db*) [protected]

constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all inherited strategies. `get_strategy()` instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list (to avoid the recursion of the base class constructor calling `get_strategy()` again). Since the letter IS the representation, its representation pointer is set to NULL (an uninitialized pointer causes problems in `~Strategy`).

10.94.3 Member Function Documentation

10.94.3.1 [Strategy](#) operator= (const [Strategy](#) & *strat*)

assignment operator

Assignment operator decrements `referenceCount` for old `strategyRep`, assigns new `strategyRep`, and increments `referenceCount` for new `strategyRep`.

10.94.3.2 void run_iterator (*Iterator & the_iterator, Model & the_model*)

Convenience function for invoking an iterator and managing parallelism. This version omits communicator repartitioning. Function must be public due to use by MINLPNode.

This is a convenience function for encapsulating the parallel features (run/serve) of running an iterator. This function omits allocation/deallocation of communicators to provide greater efficiency in those strategies which involve multiple iterator executions but only require communicator allocation/deallocation to be performed once.

It does not require a strategyRep forward since it is only used by letter objects. While it is currently a public function due to its use in MINLPNode, this usage still involves a strategy letter object.

10.94.3.3 void init_communicators (*Iterator & the_iterator, Model & the_model*) [protected]

convenience function for allocating comms prior to running an iterator

This is a convenience function for encapsulating the allocation of communicators prior to running an iterator. It does not require a strategyRep forward since it is only used by letter objects.

10.94.3.4 void free_communicators (*Iterator & the_iterator, Model & the_model*) [protected]

convenience function for deallocating comms after running an iterator

This is a convenience function for encapsulating the deallocation of communicators after running an iterator. It does not require a strategyRep forward since it is only used by letter objects.

10.94.3.5 void initialize_graphics (*const Model & model*) [protected]

convenience function for initialization of 2D graphics and data tabulation

This is a convenience function for encapsulating graphics initialization operations. It does not require a strategyRep forward since it is only used by letter objects.

10.94.3.6 Strategy * get_strategy () [private]

Used by the envelope to instantiate the correct letter class.

Used only by the envelope constructor to initialize strategyRep to the appropriate derived type, as given by the strategyName attribute.

The documentation for this class was generated from the following files:

- DakotaStrategy.H
- DakotaStrategy.C

10.95 String Class Reference

Dakota::String class, used as main string class for [Dakota](#).

Public Member Functions

- [String](#) ()
Default constructor.
- [String](#) (const [String](#) &a)
Copy constructor for incoming [String](#).
- [String](#) (const [String](#) &a, size_t start_index, size_t num_items)
Copy constructor for portion of incoming [String](#).
- [String](#) (const char *c_string)
Copy constructor for incoming char array.*
- [String](#) (const DAKOTA_BASE_STRING &a)
Copy constructor for incoming base string.
- [~String](#) ()
Destructor.
- [String](#) & operator= (const [String](#) &)
Assignment operator for incoming [String](#).
- [String](#) & operator= (const DAKOTA_BASE_STRING &)
Assignment operator for incoming base string.
- [String](#) & operator= (const char *)
Assignment operator for incoming char array.*
- operator const char * () const
The operator() returns pointer to standard C char array.
- [String](#) & toUpper ()
Convert to upper case string.
- void upper ()
- [String](#) & toLower ()
Convert to lower case string.

- void `lower ()`
- bool `contains (const char *sub_string) const`
Returns true if `String` contains `char` substring.*
- bool `begins (const char *sub_string) const`
Returns true if `String` starts with `char` substring.*
- bool `ends (const char *sub_string) const`
Returns true if `String` ends with `char` substring.*
- char * `data () const`
Returns pointer to standard C char array.

10.95.1 Detailed Description

Dakota::String class, used as main string class for [Dakota](#).

The Dakota::String class is the common string class for [Dakota](#). It provides a common interface for string operations whether inheriting from the STL `basic_string` or the Rogue Wave `RWCString` class

10.95.2 Member Function Documentation

10.95.2.1 operator const char * () const [inline]

The operator() returns pointer to standard C char array.

The operator () returns a pointer to a char string. Uses the STL `c_str()` method. This allows for the [String](#) to be used in method calls without having to call the `data()` or `c_str()` methods.

10.95.2.2 void upper ()

Private method which converts [String](#) to upper. Utilizes an STL iterator to step through the string and then calls the STL `toupper()` method. Needs to be done this way because STL only provides a single char `toupper` method.

10.95.2.3 void lower ()

Private method which converts [String](#) to lower. Utilizes an STL iterator to step through the string and then calls the STL `tolower()` method. Needs to be done this way because STL only provides a single char `tolower` method.

10.95.2.4 bool contains (const char * *sub_string*) const [inline]

Returns true if [String](#) contains char* substring.

Returns true if the [String](#) contains the char* sub_string. Uses the STL find() method.

10.95.2.5 bool begins (const char * *sub_string*) const [inline]

Returns true if [String](#) starts with char* substring.

Returns true if the [String](#) begins with the char* sub_string. Uses the STL compare() method.

10.95.2.6 bool ends (const char * *sub_string*) const [inline]

Returns true if [String](#) ends with char* substring.

Returns true if the [String](#) ends with the char* sub_string. Uses the STL compare() method.

10.95.2.7 char * data () const [inline]

Returns pointer to standard C char array.

Returns a pointer to C style char array. Needed to mimic the Rogue Wave string class. USE WITH CARE.

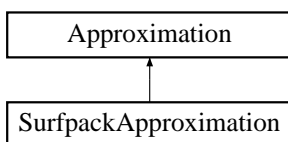
The documentation for this class was generated from the following files:

- DakotaString.H
- DakotaString.C

10.96 SurfpackApproximation Class Reference

Derived approximation class for Surfpack approximation classes. [Interface](#) between Surfpack and [Dakota](#).

Inheritance diagram for SurfpackApproximation::



Public Member Functions

- [SurfpackApproximation](#) ()
default constructor
- [SurfpackApproximation](#) ([ProblemDescDB](#) &problem_db, const size_t &num_acv)
and are passed as is to Surfpack methods and functions– which expect structures of type std::vector. This is legal as long as the types Surfpack expects really are superclasses of their [Dakota](#) counterparts. It will fail if a Real is #defined in [Dakota](#) to be a float, because then it will be a subclass of std::vector<float> being passed in as a std::vector<double>. The possible solutions, I think, are: 1. Have the same typedef feature in Surfpack so that everything can be configured to use floats or doubles 2. Explicitly cast each vector component as it passes over the [Dakota/Surfpack](#) boundary
- [~SurfpackApproximation](#) ()
destructor

Protected Member Functions

- int [num_coefficients](#) () const
- void [find_coefficients](#) ()
SurfData object will be created from Dakota's SurrogateDataPoints, and the appropriate Surfpack build method will be invoked.
- const [RealVector](#) & [approximation_coefficients](#) ()
Vector of values representing the identity of the Surfpack surface. Return value of this function is not yet meaningful. The format of such a vector of values is not yet defined for all Surfpack classes.
- const Real & [get_value](#) (const [RealVector](#) &x)
Return the value of the Surfpack surface for a given parameter vector x.

- const [RealBaseVector](#) & [get_gradient](#) (const [RealVector](#) &x)
retrieve the approximate function gradient for a given parameter vector x
- const [RealMatrix](#) & [get_hessian](#) (const [RealVector](#) &x)
retrieve the approximate function Hessian for a given parameter vector x

Private Member Functions

- void [checkForEqualityConstraints](#) ()
If anchor_point is present, create equality constraints from a particular point, gradient, and/or hessian.
- [SurfData](#) * [surrogates_to_surf_data](#) ()
copy from [SurrogateDataPoint](#) to [SurfPoint](#)/[SurfData](#)

Private Attributes

- [RealVector](#) [coefficients](#)
Vector representation of the [Approximation](#) (e.g., polynomial coefficients for linear regression or trained neural network weights). The format of such a vector has not been defined for all Surfpack classes.
- [Surface](#) * [surface](#)
The native Surfpack approximation.
- [SurfData](#) * [surfData](#)
The data used to build the approximation, in Surfpack format.
- short [polyOrder](#)
order (1, 2, or 3) of a polynomial regression surrogate

10.96.1 Detailed Description

Derived approximation class for Surfpack approximation classes. [Interface](#) between Surfpack and [Dakota](#).

The [SurfpackApproximation](#) class is the interface between [Dakota](#) and Surfpack. Based on the information in the [ProblemDescDB](#) that is passed in through the constructor, [SurfpackApproximation](#) builds a Surfpack Surface object that corresponds to one of the following data-fitting techniques: polynomial regression, kriging, artificial neural networks, radial basis function network, or multivariate adaptive regression splines (MARS).

10.96.2 Constructor & Destructor Documentation

10.96.2.1 [SurfpackApproximation](#) ([ProblemDescDB](#) & *problem_db*, `const size_t` & *num_acv*)

and are passed as is to Surfpack methods and functions– which expect structures of type `std::vector`. This is legal as long as the types Surfpack expects really are superclasses of their [Dakota](#) counterparts. It will fail if a `Real` is `#defined` in [Dakota](#) to be a float, because then it will be a subclass of `std::vector<float>` being passed in as a `std::vector<double>`. The possible solutions, I think, are: 1. Have the same typedef feature in Surfpack so that everything can be configured to use floats or doubles 2. Explicitly cast each vector component as it passes over the Dakota/Surfpack boundary

Initialize the embedded Surfpack surface object and configure it using the specifications from the input file. Data for the surface is created later.

Todo

Add RBFNet surface fit interface

10.96.3 Member Function Documentation

10.96.3.1 `int num_coefficients () const` [`protected`, `virtual`]

Todo

: Check to make sure that the number of points required does not

Todo

: The reported number of points required is computed in a rather

exceed the bounds for a signed integer ad hoc manner. Do something smarter.

Reimplemented from [Approximation](#).

10.96.3.2 `void find_coefficients ()` [`protected`, `virtual`]

`SurfData` object will be created from Dakota's `SurrogateDataPoints`, and the appropriate Surfpack build method will be invoked.

Todo

Right now, we're completely deleting the old data and then

`surfData` will be deleted in `dtor` recopying the current data into a `SurfData` object. This was just the easiest way to arrive at a solution that would build and run. This function is frequently called from `addPoint` `rebuild`, however, and it's not good to go through this whole process every time one more data point is added.

Reimplemented from [Approximation](#).

10.96.3.3 `const RealVector & approximation_coefficients ()` [`protected`, `virtual`]

[Vector](#) of values representing the identity of the Surfpack surface. Return value of this function is not yet meaningful. The format of such a vector of values is not yet defined for all Surfpack classes.

The value returned from this function is currently meaningless.

Todo

: Provide an appropriate list of coefficients for each surface type

Reimplemented from [Approximation](#).

10.96.3.4 const RealMatrix & get_hessian (const RealVector & x) [protected, virtual]

retrieve the approximate function Hessian for a given parameter vector x

Todo

Make this acceptably efficient

Reimplemented from [Approximation](#).

10.96.3.5 void checkForEqualityConstraints () [private]

If anchor_point is present, create equality constraints from a particular point, gradient, and/or hessian.

If there is an anchor point, add an equality constraint for its response value. Also add constraints for gradient and hessian, if applicable.

Todo

improve efficiency of conversion

10.96.3.6 SurfData * surrogates_to_surf_data () [private]

copy from [SurrogateDataPoint](#) to SurfPoint/SurfData

Copy the data stored in Dakota-style [SurrogateDataPoint](#) objects into Surfpack-style SurfPoint and SurfData objects.

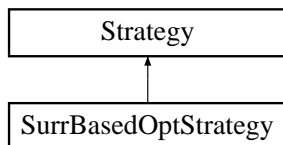
The documentation for this class was generated from the following files:

- SurfpackApproximation.H
- SurfpackApproximation.C

10.97 SurrBasedOptStrategy Class Reference

[Strategy](#) for provably-convergent surrogate-based optimization.

Inheritance diagram for SurrBasedOptStrategy::



Public Member Functions

- [SurrBasedOptStrategy](#) ([ProblemDescDB](#) &problem_db)
constructor
- [~SurrBasedOptStrategy](#) ()
destructor
- void [run_strategy](#) ()
Performs the surrogate-based optimization strategy by optimizing local, global, or hierarchical surrogates over a series of trust regions.
- const [Variables](#) & [variable_results](#) () const
return the SBO final solution (variables)
- const [Response](#) & [response_results](#) () const
return the SBO final solution (response)

Private Member Functions

- void [run_surrogate_based_optimization](#) ()
the core SBO algorithm, as called from [run_strategy](#)()
- bool [tr_bounds](#) ([RealVector](#) &c_vars_center, const [StringArray](#) &c_vars_labels, const [RealVector](#) &global_lower_bnds, const [RealVector](#) &global_upper_bnds, [RealVector](#) &tr_lower_bnds, [RealVector](#) &tr_upper_bnds)
compute current trust region bounds
- void [find_center_truth](#) ([Response](#) &response_center_truth, const [RealVector](#) &c_vars_center, const [Iterator](#) &dace_iterator, [Model](#) &truth_model)

retrieve response_center_truth if possible, evaluate it if not

- void `find_center_approx` (Response &response_center_approx, const Response &response_center_truth)
retrieve response_center_approx if possible, evaluate it if not
- void `hard_convergence_check` (const Response &response_truth, const RealVector &c_vars, const RealVector &lower_bnds, const RealVector &upper_bnds)
check for hard convergence (norm of projected gradient of merit function near zero)
- void `tr_ratio_check` (const RealVector &c_vars_center, const RealVector &c_vars_star, const RealVector &tr_lower_bounds, const RealVector &tr_upper_bounds, const Response &response_center_truth, const Response &response_center_approx, const Response &response_star_truth, const Response &response_star_approx)
compute trust region ratio for accepting/rejecting SBO iterate and sizing next trust region and check for soft convergence (diminishing returns)
- void `update_penalty` (const RealVector &fns_center_truth, const RealVector &fns_star_truth)
initialize and update the penaltyParameter
- void `update_lagrange_multipliers` (const RealVector &fn_vals, const RealMatrix &fn_grads)
initialize and update Lagrange multipliers for basic Lagrangian
- void `update_augmented_lagrange_multipliers` (const RealVector &fn_vals)
initialize and update the Lagrange multipliers for augmented Lagrangian
- bool `update_filter` (const RealVector &fn_vals)
update a filter from a set of function values
- Real `lagrangian_merit` (const RealVector &fn_vals)
compute a Lagrangian function from a set of function values
- void `lagrangian_gradient` (const RealMatrix &fn_grads, RealVector &lag_grad)
compute the gradient of the Lagrangian function
- Real `augmented_lagrangian_merit` (const RealVector &fn_vals)
compute an augmented Lagrangian function from a set of function values
- void `augmented_lagrangian_gradient` (const RealVector &fn_vals, const RealMatrix &fn_grads, RealVector &alag_grad)
compute the gradient of the augmented Lagrangian function
- Real `penalty_merit` (const RealVector &fn_vals)
compute a penalty function from a set of function values
- void `penalty_gradient` (const RealVector &fn_vals, const RealMatrix &fn_grads, RealVector &pen_grad)
compute the gradient of the penalty function

- Real [objective](#) (const [RealVector](#) &fn_vals)
compute a single objective value from one or more objective functions
- Real [constraint_violation](#) (const [RealVector](#) &fn_vals, const Real &constraint_tol)
compute the constraint violation from a set of function values
- void [relax_constraints](#) (const [Response](#) &response_truth, const [RealVector](#) &c_vars, const [RealVector](#) &lower_bnds, const [RealVector](#) &upper_bnds)
relax constraints by updating bounds when current iterate is infeasible

Static Private Member Functions

- static void [hom_objective_eval](#) (int &mode, int &n, double *u, double &f, double *grad_f, int &)
static function used by NPSOL as the objective function in the homotopy constraint relaxation formulation.
- static void [hom_constraint_eval](#) (int &mode, int &ncnln, int &n, int &nrowj, int *needc, double *u, double *c, double *cjac, int &nstate)
static function used by NPSOL as the constraint function in the homotopy constraint relaxation formulation.

Private Attributes

- [Model surrogateModel](#)
the surrogate model (a [SurrogateModel](#) object)
- [Iterator selectedIterator](#)
the optimizer used on surrogateModel
- Real [trustRegionFactor](#)
the trust region factor is used to compute the total size of the trust region – it is a percentage, e.g. for trustRegionFactor = 0.1, the actual size of the trust region will be 10% of the global bounds (upper bound - lower bound for each design variable).
- Real [minTrustRegionFactor](#)
a soft convergence control: stop SBO when the trust region factor is reduced below the value of minTrustRegionFactor
- Real [convergenceTol](#)
the optimizer convergence tolerance; used in several SBO hard and soft convergence checks
- Real [constraintTol](#)
a tolerance specifying the distance from a constraint boundary that is allowed before an active constraint is considered to be a violated constraint.
- Real [trRatioContractValue](#)

trust region ratio min value: contract tr if ratio below this value

- Real [trRatioExpandValue](#)

trust region ratio sufficient value: expand tr if ratio above this value

- Real [gammaContract](#)

trust region contraction factor

- Real [gammaExpand](#)

trust region expansion factor

- Real [gammaNoChange](#)

factor for maintaining the current trust region size (normally 1.0)

- bool [trConstraintRelax](#)

flag to use trust region constraint relaxation for infeasible starting points

- int [trConstraintRelaxMethod](#)

type of trust region constraint relaxation for infeasible starting points: NONE (default=0) or HOMOTOPY (1)

- int [meritFnType](#)

type of merit function used in trust region ratio logic: BASIC_PENALTY, ADAPTIVE_PENALTY, BASIC_LAGRANGIAN, or AUGMENTED_LAGRANGIAN

- int [acceptLogic](#)

type of iterate acceptance test logic: FILTER or TR_RATIO

- RealVectorList [sboFilter](#)

Set of response function vectors defining a filter (objective vs. constraint violation) for iterate selection/rejection.

- RealVector [lagrangeMult](#)

Lagrange multipliers for basic Lagrangian calculations.

- RealVector [augLagrangeMult](#)

Lagrange multipliers for augmented Lagrangian calculations.

- Real [penaltyParameter](#)

the penalization factor for violated constraints used in quadratic penalty calculations; increased in [update_penalty\(\)](#)

- int [penaltyIterOffset](#)

iteration offset used to update the scaling of the penalty parameter for [adaptive_penalty](#) merit functions

- int [sboIterNum](#)

SBO iteration number.

- int `sboIterMax`
maximum number of SBO iterations
- short `convergenceFlag`
code indicating satisfaction of hard or soft convergence conditions
- size_t `numFns`
number of response functions
- size_t `numVars`
number of active continuous variables
- short `softConvCount`
number of consecutive candidate point rejections. If the count reaches `softConvLimit`, stop SBO.
- short `softConvLimit`
the limit on consecutive candidate point rejections. If exceeded by `softConvCount`, stop SBO.
- bool `gradientFlag`
flags the use of gradients within the SBO process
- bool `hessianFlag`
flags the use of Hessians within the SBO process
- bool `correctionFlag`
flags the use of surrogate correction techniques at the center of each trust region
- bool `globalApproxFlag`
flags the use of a global data fit surrogate (rsm, ann, mars, kriging)
- bool `localApproxFlag`
flags the use of a local data fit surrogate (Taylor series)
- bool `hierarchApproxFlag`
flags the use of a hierarchical surrogate
- bool `newCenterFlag`
flags the acceptance of a candidate point and the existence of a new trust region center
- bool `daceCenterPtFlag`
flags the availability of the center point in the DACE evaluations for global approximations (CCD, Box-Behnken)
- bool `multiLayerBypassFlag`
flags the simultaneous presence of two conditions: (1) additional layerings w/i `actual_model` (e.g., `surrogateModel = layered/nested/layered` -> `actual_model = nested/layered`), and (2) a user-specification to bypass all layerings within `actual_model` for the evaluation of truth data (`response_center_truth` and `response_star_truth`).

- **bool useGradsFlag**
flags the "use_gradients" specification in which gradients are to be evaluated for each DACE point in global surrogate builds.
- **size_t numObjFns**
number of objective functions
- **size_t numNonlinIneqConstr**
number of nonlinear inequality constraints
- **size_t numNonlinEqConstr**
number of nonlinear equality constraints
- **size_t nonlinIneqOffset**
index offset to nonlinear constraint functions
- **size_t nonlinEqOffset**
index offset to nonlinear constraint functions
- **RealVector multiObjWts**
vector of multiobjective weights.
- **RealVector nonlinIneqLowerBnds**
vector of current nonlinear inequality constraint lower bounds
- **RealVector nonlinIneqUpperBnds**
vector of current nonlinear inequality constraint upper bounds
- **RealVector nonlinEqTargets**
vector of current nonlinear equality constraint targets
- **Real bigRealBoundSize**
cutoff value for continuous bounds
- **RealVector nonlinIneqLowerBndsSlack**
vector of true nonlinear inequality constraint lower bounds
- **RealVector nonlinIneqUpperBndsSlack**
vector of true nonlinear inequality constraint upper bounds
- **RealVector nonlinEqTargetsSlack**
vector of true nonlinear equality constraint targets
- **Real tau**
constraint relaxation parameter

- Real [alpha](#)
constraint relaxation parameter backoff parameter (multiplier)
- int [npsolDerivLevel](#)
derivative level for NPSOL executions (1 = analytic grads of objective fn, 2 = analytic grads of constraints, 3 = analytic grads of both).
- Variables [bestVariables](#)
best variables found in SBO
- Response [bestResponses](#)
best responses found in SBO

Static Private Attributes

- static [SurrBasedOptStrategy](#) * [sboOptInstance](#)
pointer to SBO strategy used in static member functions

10.97.1 Detailed Description

[Strategy](#) for provably-convergent surrogate-based optimization.

This strategy uses a [SurrogateModel](#) to perform optimization based on local, global, or hierarchical surrogates. It achieves provable convergence through the use of a sequence of trust regions and the application of surrogate corrections at the trust region centers.

10.97.2 Member Function Documentation

10.97.2.1 void run_strategy () [virtual]

Performs the surrogate-based optimization strategy by optimizing local, global, or hierarchical surrogates over a series of trust regions.

Trust region-based strategy to perform surrogate-based optimization in subregions (trust regions) of the parameter space. The optimizer operates on approximations in lieu of the more expensive simulation-based response functions. The size of the trust region is varied according to the goodness of the agreement between the approximations and the true response functions.

Reimplemented from [Strategy](#).

10.97.2.2 void `hard_convergence_check` (const [Response](#) & *response_truth*, const [RealVector](#) & *c_vars*, const [RealVector](#) & *lower_bnds*, const [RealVector](#) & *upper_bnds*) [private]

check for hard convergence (norm of projected gradient of merit function near zero)

The hard convergence check computes the gradient of the merit function at the trust region center, performs a projection for active bound constraints (removing any gradient component directed into an active bound), and signals convergence if the 2-norm of this projected gradient is less than `convergenceTol`.

10.97.2.3 void `tr_ratio_check` (const [RealVector](#) & *c_vars_center*, const [RealVector](#) & *c_vars_star*, const [RealVector](#) & *tr_lower_bounds*, const [RealVector](#) & *tr_upper_bounds*, const [Response](#) & *response_center_truth*, const [Response](#) & *response_center_approx*, const [Response](#) & *response_star_truth*, const [Response](#) & *response_star_approx*) [private]

compute trust region ratio for accepting/rejecting SBO iterate and sizing next trust region and check for soft convergence (diminishing returns)

Compute soft convergence metrics (trust region ratio, number of consecutive failures, min trust region size, etc.) and use them to assess whether the convergence rate has decreased to a point where the process should be terminated (diminishing returns).

10.97.2.4 void `update_penalty` (const [RealVector](#) & *fns_center_truth*, const [RealVector](#) & *fns_star_truth*) [private]

initialize and update the `penaltyParameter`

Scaling of the penalty value is important to avoid rejecting SBO iterates which must increase the objective to achieve a reduction in constraint violation. In the basic penalty case, the penalty is ramped exponentially based on the iteration counter. In the adaptive case, the ratio of relative change between center and star points for the objective and constraint violation values is used to rescale penalty values.

10.97.2.5 void `update_lagrange_multipliers` (const [RealVector](#) & *fn_vals*, const [RealMatrix](#) & *fn_grads*) [private]

initialize and update Lagrange multipliers for basic Lagrangian

For the Rockafellar augmented Lagrangian, simple Lagrange multiplier updates are available which do not require the active constraint gradients. For the basic Lagrangian, Lagrange multipliers are estimated through solution of a nonnegative linear least squares problem.

10.97.2.6 void `update_augmented_lagrange_multipliers` (const [RealVector](#) & *fn_vals*) [private]

initialize and update the Lagrange multipliers for augmented Lagrangian

For the Rockafellar augmented Lagrangian, simple Lagrange multiplier updates are available which do not require the active constraint gradients. For the basic Lagrangian, Lagrange multipliers are estimated through solution of a nonnegative linear least squares problem.

10.97.2.7 bool update_filter (const RealVector & fn_vals) [private]

update a filter from a set of function values

Update the sboFilter with fn_vals if new iterate is non-dominated.

10.97.2.8 Real lagrangian_merit (const RealVector & fn_vals) [private]

compute a Lagrangian function from a set of function values

The Lagrangian function computation sums the objective function and the Lagrange multiplier terms for inequality/equality constraints. This implementation follows the convention in Vanderplaats with $g \leq 0$ and $h = 0$.

10.97.2.9 Real augmented_lagrangian_merit (const RealVector & fn_vals) [private]

compute an augmented Lagrangian function from a set of function values

The Rockafellar augmented Lagrangian function sums the objective function, Lagrange multiplier terms for inequality/equality constraints, and quadratic penalty terms for inequality/equality constraints. This implementation follows the convention in Vanderplaats with $g \leq 0$ and $h = 0$.

10.97.2.10 Real penalty_merit (const RealVector & fn_vals) [private]

compute a penalty function from a set of function values

The penalty function computation applies a quadratic penalty to any constraint violations and adds this to the objective function(s) $p = f + r_p cv$.

10.97.2.11 Real objective (const RealVector & fn_vals) [private]

compute a single objective value from one or more objective functions

The objective computation sums up the contributions from one or more objective functions using the multiobjective weights.

10.97.2.12 Real constraint_violation (const RealVector & fn_vals, const Real & constraint_tol) [private]

compute the constraint violation from a set of function values

Compute the quadratic constraint violation defined as $cv = g + ^T g + h + ^T h$. This implementation supports equality constraints and 2-sided inequalities. The constraint_tol allows for a small constraint infeasibility (used for penalty methods, but not Lagrangian methods).

10.97.2.13 void hom_objective_eval (int & mode, int & n, double * u, double & f, double * grad_f, int &) [static, private]

static function used by NPSOL as the objective function in the homotopy constraint relaxation formulation.

NPSOL objective functions evaluator for solution of homotopy constraint relaxation parameter optimization. This constrained optimization problem performs the update of the tau parameter in the homotopy heuristic approach used to relax the constraints in the original problem .

10.97.2.14 `void hom_constraint_eval (int & mode, int & ncnln, int & n, int & nrowj, int * needc, double * u, double * c, double * cjac, int & nstate)` [static, private]

static function used by NPSOL as the constraint function in the homotopy constraint relaxation formulation.

NPSOL constraint functions evaluator for solution of homotopy constraint relaxation parameter optimization. This constrained optimization problem performs the update of the tau parameter in the homotopy heuristic approach used to relax the constraints in the original problem .

The documentation for this class was generated from the following files:

- SurrBasedOptStrategy.H
- SurrBasedOptStrategy.C

10.98 SurrogateDataPoint Class Reference

Container class encapsulating basic parameter and response data for defining a "truth" data point.

Public Member Functions

- [SurrogateDataPoint \(\)](#)
default constructor
- [SurrogateDataPoint \(const RealVector &x, const Real &fn_val, const RealBaseVector &fn_grad, const RealMatrix &fn_hess\)](#)
standard constructor
- [SurrogateDataPoint \(const SurrogateDataPoint &sdp\)](#)
copy constructor
- [~SurrogateDataPoint \(\)](#)
destructor
- [SurrogateDataPoint & operator= \(const SurrogateDataPoint &sdp\)](#)
assignment operator
- [bool operator== \(const SurrogateDataPoint &sdp\) const](#)
equality operator
- [const RealVector & continuous_variables \(\) const](#)
return continuousVars
- [const Real & response_function \(\) const](#)
return responseFn
- [const RealBaseVector & response_gradient \(\) const](#)
return responseGrad
- [const RealMatrix & response_hessian \(\) const](#)
return responseHess
- [bool is_null \(\) const](#)
function to check sdpRep (does this handle contain a body)

Private Attributes

- [SurrogateDataPointRep](#) * `sdpRep`
pointer to the body (handle-body idiom)

10.98.1 Detailed Description

Container class encapsulating basic parameter and response data for defining a "truth" data point.

A list of these data points is contained in each [Approximation](#) instance ([Approximation::currentPoints](#)) and provides the data to build the approximation. A handle-body idiom is used to avoid excessive data copying overhead.

The documentation for this class was generated from the following file:

- `DakotaApproximation.H`

10.99 SurrogateDataPointRep Class Reference

The representation of a surrogate data point. This representation, or body, may be shared by multiple [SurrogateDataPoint](#) handle instances.

Private Member Functions

- [SurrogateDataPointRep](#) (const [RealVector](#) &x, const Real &fn_val, const [RealBaseVector](#) &fn_grad, const [RealMatrix](#) &fn_hess)
constructor
- [~SurrogateDataPointRep](#) ()
destructor

Private Attributes

- [RealVector](#) `continuousVars`
continuous variables
- Real `responseFn`
truth response function value
- [RealBaseVector](#) `responseGrad`
truth response function gradient
- [RealMatrix](#) `responseHess`
truth response function Hessian
- int `referenceCount`
number of handle objects sharing `sdpRep`

Friends

- class [SurrogateDataPoint](#)
the handle class can access attributes of the body class directly

10.99.1 Detailed Description

The representation of a surrogate data point. This representation, or body, may be shared by multiple [SurrogateDataPoint](#) handle instances.

The SurrogateDataPoint/SurrogateDataPointRep pairs utilize a handle-body idiom (Coplien, Advanced C++).

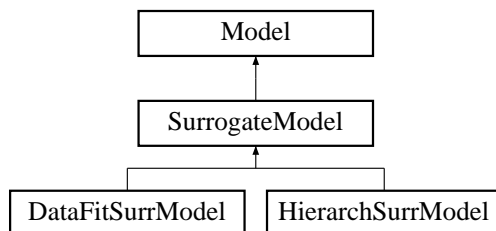
The documentation for this class was generated from the following file:

- DakotaApproximation.H

10.100 SurrogateModel Class Reference

Base class for surrogate models ([DataFitSurrModel](#) and [HierarchSurrModel](#)).

Inheritance diagram for SurrogateModel::



Protected Member Functions

- [SurrogateModel](#) ([ProblemDescDB](#) &problem_db)
constructor
- [~SurrogateModel](#) ()
destructor
- void [compute_correction](#) (const [Response](#) &truth_response, const [Response](#) &approx_response, const [RealVector](#) &c_vars)
compute the correction required to bring approx_response into agreement with truth_response
- void [apply_correction](#) ([Response](#) &approx_response, const [RealVector](#) &c_vars, bool quiet_flag=false)
apply the correction computed in [compute_correction\(\)](#) to approx_response
- void [check_submodel_compatibility](#) (const [Model](#) &sub_model)
verify compatibility between [SurrogateModel](#) attributes and attributes of the submodel ([DataFitSurrModel::actualModel](#) or [HierarchSurrModel::highFidelityModel](#))
- bool [force_rebuild](#) ()
evaluate whether a rebuild of the approximation should be forced based on changes in the inactive data
- void [auto_correction](#) (bool correction_flag)
sets autoCorrection to on (true) or off (false)
- bool [auto_correction](#) ()
returns autoCorrection setting

Protected Attributes

- bool `mixedResponseSet`
flag for mixed approximate/actual responses
- `IntArray` `surrogateFnIds`
for mixed response sets, this array specifies the response function subset that is approximated
- `ResponseArray` `correctedResponseArray`
array of corrected responses used in `derived_synchronize()` functions
- `IntResponseMap` `correctedResponseMap`
list of corrected responses used in `derived_synchronize_nowait()` functions
- `IntRealVectorMap` `rawCVarsMap`
map of raw continuous variables used by `apply_correction()`. `Model::varsList` cannot be used for this purpose since it does not contain lower level variables sets from finite differencing.
- `String` `correctionType`
approximation correction approach to be used: additive or multiplicative
- short `correctionOrder`
approximation correction order to be used: 0, 1, or 2
- bool `autoCorrection`
a flag which controls the use of `apply_correction()` in `DataFitSurrModel` and `HierarchSurrModel` approximate response computations
- bool `correctionComputed`
flag indicating whether or not a correction has been computed and is available for application
- `String` `approxType`
approximation type identifier string: global, local, or hierarchical
- `size_t` `approxBuilds`
number of calls to `build_approximation()`
- bool `surrogateBypass`
a flag which allows bypassing the approximation for evaluations on the underlying truth model.
- `String` `rebuildControl`
flag controlling the rebuild of approximations when changes occur to the active/inactive variable values/bounds.
- `RealVector` `fitCLBnds`
stores a copy of the active continuous lower bounds when the approximation is built; used to detect when a rebuild is required.

- [RealVector fitCUBnds](#)
stores a copy of the active continuous upper bounds when the approximation is built; used to detect when a rebuild is required.
- [IntVector fitDLBnds](#)
stores a copy of the active discrete lower bounds when the approximation is built; used to detect when a rebuild is required.
- [IntVector fitDUBnds](#)
stores a copy of the active discrete upper bounds when the approximation is built; used to detect when a rebuild is required.
- [RealVector fitInactCVars](#)
stores a copy of the inactive continuous variables when the approximation is built; used to detect when a rebuild is required.
- [IntVector fitInactDVars](#)
stores a copy of the inactive discrete variables when the approximation is built; used to detect when a rebuild is required.
- [RealVector fitInactCLBnds](#)
stores a copy of the inactive continuous lower bounds when the approximation is built; used to detect when a rebuild is required.
- [RealVector fitInactCUBnds](#)
stores a copy of the inactive continuous upper bounds when the approximation is built; used to detect when a rebuild is required.
- [IntVector fitInactDLBnds](#)
stores a copy of the inactive discrete lower bounds when the approximation is built; used to detect when a rebuild is required.
- [IntVector fitInactDUBnds](#)
stores a copy of the inactive discrete upper bounds when the approximation is built; used to detect when a rebuild is required.

Private Member Functions

- void [apply_additive_correction](#) ([RealVector](#) &alpha_corrected_fns, [RealMatrix](#) &alpha_corrected_grads, [RealMatrixArray](#) &alpha_corrected_hessians, const [RealVector](#) &c_vars, const [ActiveSet](#) &set)
internal convenience function for applying additive corrections
- void [apply_multiplicative_correction](#) ([RealVector](#) &beta_corrected_fns, [RealMatrix](#) &beta_corrected_grads, [RealMatrixArray](#) &beta_corrected_hessians, const [RealVector](#) &c_vars, const [ActiveSet](#) &set)
internal convenience function for applying multiplicative corrections

Private Attributes

- **bool badScalingFlag**
flag used to indicate function values near zero for multiplicative corrections; triggers an automatic switch to additive corrections
- **bool combinedFlag**
flag indicating the combination of additive/multiplicative corrections
- **bool computeAdditive**
flag indicating the need for additive correction calculations
- **bool computeMultiplicative**
flag indicating the need for multiplicative correction calculations
- **RealVector addCorrFns**
0th-order additive correction term: equals the difference between high and low fidelity model values at $x=x_center$.
- **RealMatrix addCorrGrads**
1st-order additive correction term: equals the gradient of the high/low function difference at $x=x_center$.
- **RealMatrixArray addCorrHessians**
2nd-order additive correction term: equals the Hessian of the high/low function difference at $x=x_center$.
- **RealVector multCorrFns**
0th-order multiplicative correction term: equals the ratio of high fidelity to low fidelity model values at $x=x_center$.
- **RealMatrix multCorrGrads**
1st-order multiplicative correction term: equals the gradient of the high/low function ratio at $x=x_center$.
- **RealMatrixArray multCorrHessians**
2nd-order multiplicative correction term: equals the Hessian of the high/low function ratio at $x=x_center$.
- **RealVector combineFactors**
factors for combining additive and multiplicative corrections. Each factor is the weighting applied to the additive correction and 1.-factor is the weighting applied to the multiplicative correction. The factor value is determined by an additional requirement to match the high fidelity function value at the previous correction point (e.g., previous trust region center). This results in a multipoint correction instead of a strictly local correction.
- **RealVector correctionCenterPt**
The point in parameter space where the current correction is calculated (often the center of the current trust region). Used in calculating $(x - x_c)$ terms in 1st-/2nd-order corrections.
- **RealVector correctionPrevCenterPt**
copy of correctionCenterPt from the previous correction cycle
- **RealVector approxFnsCenter**

Surrogate function values at the current correction point which are needed as a fall back if the current surrogate function values are unavailable when applying 1st-/2nd-order multiplicative corrections.

- [RealVector approxFnsPrevCenter](#)

copy of approxFnsCenter from the previous correction cycle

- [RealMatrix approxGradsCenter](#)

Surrogate gradient values at the current correction point which are needed as a fall back if the current surrogate function gradients are unavailable when applying 1st-/2nd-order multiplicative corrections.

- [RealVector truthFnsCenter](#)

Truth function values at the current correction point.

- [RealVector truthFnsPrevCenter](#)

copy of truthFnsCenter from the previous correction cycle

10.100.1 Detailed Description

Base class for surrogate models ([DataFitSurrModel](#) and [HierarchSurrModel](#)).

The [SurrogateModel](#) class provides common functions to derived classes for computing and applying corrections to approximations.

10.100.2 Member Function Documentation

10.100.2.1 `void compute_correction (const Response & truth_response, const Response & approx_response, const RealVector & c_vars)` [`protected`, `virtual`]

compute the correction required to bring approx_response into agreement with truth_response

Compute an additive or multiplicative correction that corrects the approx_response to have 0th-order consistency (matches values), 1st-order consistency (matches values and gradients), or 2nd-order consistency (matches values, gradients, and Hessians) with the truth_response at a single point (e.g., the center of a trust region). The 0th-order, 1st-order, and 2nd-order corrections use scalar values, linear scaling functions, and quadratic scaling functions, respectively, for each response function.

Reimplemented from [Model](#).

10.100.2.2 `bool force_rebuild ()` [`protected`]

evaluate whether a rebuild of the approximation should be forced based on changes in the inactive data

This function forces a rebuild of the approximation according to the approximation type, the rebuildControl setting, and which active/inactive data has changed since the last build.

10.100.3 Member Data Documentation

10.100.3.1 bool `autoCorrection` [protected]

a flag which controls the use of `apply_correction()` in `DataFitSurrModel` and `HierarchSurrModel` approximate response computations

`SurrBasedOptStrategy` must toggle this value since `compute_correction()` no longer automatically backs out an old correction.

10.100.3.2 size_t `approxBuilds` [protected]

number of calls to `build_approximation()`

used as a flag to automatically build the approximation if one of the derived `compute_response` functions is called prior to `build_approximation()`.

10.100.3.3 String `rebuildControl` [protected]

flag controlling the rebuild of approximations when changes occur to the active/inactive variable values/bounds.

A setting of "all" denotes that the approximation should be rebuilt every time the inactive variables change (e.g., for each instance of {d} in OUU). A setting of "region" denotes that the approximation should be rebuilt every time the bounded region for the inactive variables changes (e.g., for each new trust region on {d} in OUU).

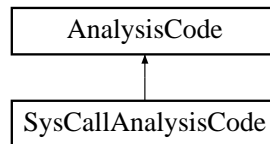
The documentation for this class was generated from the following files:

- SurrogateModel.H
- SurrogateModel.C

10.101 SysCallAnalysisCode Class Reference

Derived class in the [AnalysisCode](#) class hierarchy which spawns simulations using system calls.

Inheritance diagram for SysCallAnalysisCode::



Public Member Functions

- [SysCallAnalysisCode](#) (const [ProblemDescDB](#) &problem_db)
constructor
- [~SysCallAnalysisCode](#) ()
destructor
- void [spawn_evaluation](#) (const bool block_flag)
spawn a complete function evaluation
- void [spawn_input_filter](#) (const bool block_flag)
spawn the input filter portion of a function evaluation
- void [spawn_analysis](#) (const int &analysis_id, const bool block_flag)
spawn a single analysis as part of a function evaluation
- void [spawn_output_filter](#) (const bool block_flag)
spawn the output filter portion of a function evaluation
- const [String](#) & [command_usage](#) () const
return commandUsage

Private Attributes

- [String](#) [commandUsage](#)
optional command usage string for supporting nonstandard command syntax (supported only by SysCall analysis codes)

10.101.1 Detailed Description

Derived class in the [AnalysisCode](#) class hierarchy which spawns simulations using system calls.

[SysCallAnalysisCode](#) creates separate simulation processes using the C `system()` command. It utilizes [CommandShell](#) to manage shell syntax and asynchronous invocations.

10.101.2 Member Function Documentation

10.101.2.1 `void spawn_evaluation (const bool block_flag)`

spawn a complete function evaluation

Put the [SysCallAnalysisCode](#) to the shell using either the default syntax or specified `commandUsage` syntax. This function is used when all portions of the function evaluation (i.e., all analysis drivers) are executed on the local processor.

10.101.2.2 `void spawn_input_filter (const bool block_flag)`

spawn the input filter portion of a function evaluation

Put the input filter to the shell. This function is used when multiple analysis drivers are spread between processors. No need to check for a Null input filter, as this is checked externally. Use of nonblocking shells is supported in this fn, although its use is currently prevented externally.

10.101.2.3 `void spawn_analysis (const int & analysis_id, const bool block_flag)`

spawn a single analysis as part of a function evaluation

Put a single analysis to the shell using the default syntax (no `commandUsage` support for analyses). This function is used when multiple analysis drivers are spread between processors. Use of nonblocking shells is supported in this fn, although its use is currently prevented externally.

10.101.2.4 `void spawn_output_filter (const bool block_flag)`

spawn the output filter portion of a function evaluation

Put the output filter to the shell. This function is used when multiple analysis drivers are spread between processors. No need to check for a Null output filter, as this is checked externally. Use of nonblocking shells is supported in this fn, although its use is currently prevented externally.

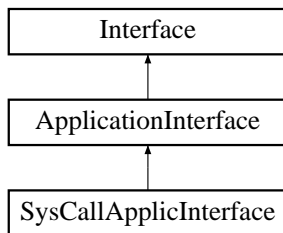
The documentation for this class was generated from the following files:

- `SysCallAnalysisCode.H`
- `SysCallAnalysisCode.C`

10.102 SysCallApplicInterface Class Reference

Derived application interface class which spawns simulation codes using system calls.

Inheritance diagram for SysCallApplicInterface::



Public Member Functions

- [SysCallApplicInterface](#) (const [ProblemDescDB](#) &problem_db)
constructor
- [~SysCallApplicInterface](#) ()
destructor
- void [derived_map](#) (const [Variables](#) &vars, const [ActiveSet](#) &set, [Response](#) &response, int fn_eval_id)
Called by [map\(\)](#) and other functions to execute the simulation in synchronous mode. The portion of performing an evaluation that is specific to a derived class.
- void [derived_map_async](#) (const [ParamResponsePair](#) &pair)
Called by [map\(\)](#) and other functions to execute the simulation in asynchronous mode. The portion of performing an asynchronous evaluation that is specific to a derived class.
- void [derived_synch](#) ([PRPList](#) &prp_list)
- void [derived_synch_nowait](#) ([PRPList](#) &prp_list)
- int [derived_synchronous_local_analysis](#) (const int &analysis_id)
- const [StringArray](#) & [analysis_drivers](#) () const
retrieve the analysis drivers specification for application interfaces

Private Member Functions

- void [spawn_application](#) (const bool block_flag)
Spawn the application by managing the input filter, analysis drivers, and output filter. Called from [derived_map\(\)](#) & [derived_map_async\(\)](#).

- void [derived_synch_kernel](#) ([PRPList](#) &prp_list)
Convenience function for common code between [derived_synch\(\)](#) & [derived_synch_nowait\(\)](#).
- bool [system_call_file_test](#) (const [String](#) &root_file)
detect completion of a function evaluation through existence of the necessary results file(s)

Private Attributes

- [SysCallAnalysisCode](#) [sysCallSimulator](#)
[SysCallAnalysisCode](#) provides convenience functions for passing the input filter, the analysis drivers, and the output filter to a [CommandShell](#) in various combinations.
- [IntSet](#) [sysCallSet](#)
set of function evaluation id's for active asynchronous system call evaluations
- [IntShortMap](#) [failCountMap](#)
map linking function evaluation id's to number of response read failures

10.102.1 Detailed Description

Derived application interface class which spawns simulation codes using system calls.

[SysCallApplicInterface](#) uses a [SysCallAnalysisCode](#) object for performing simulation invocations.

10.102.2 Member Function Documentation

10.102.2.1 void [derived_synch](#) ([PRPList](#) &prp_list) [inline, virtual]

Check for completion of active asynch jobs (tracked with [sysCallSet](#)). Wait for at least one completion and complete all jobs that have returned. This satisfies a "fairness" principle, in the sense that a completed job will `_always_` be processed (whereas accepting only a single completion could always accept the same completion - the case of very inexpensive fn. evals. - and starve some servers).

Reimplemented from [ApplicationInterface](#).

10.102.2.2 void [derived_synch_nowait](#) ([PRPList](#) &prp_list) [inline, virtual]

Check for completion of active asynch jobs (tracked with [sysCallSet](#)). Make one pass through [sysCallSet](#) & complete all jobs that have returned.

Reimplemented from [ApplicationInterface](#).

10.102.2.3 `int derived_synchronous_local_analysis(const int & analysis_id) [inline, virtual]`

This code provides the derived function used by [ApplicationInterface::serve_analyses_synch\(\)](#).

Reimplemented from [ApplicationInterface](#).

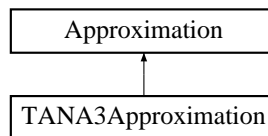
The documentation for this class was generated from the following files:

- SysCallApplicInterface.H
- SysCallApplicInterface.C

10.103 TANA3Approximation Class Reference

Derived approximation class for TANA-3 two-point exponential approximation (a multipoint approximation).

Inheritance diagram for TANA3Approximation::



Public Member Functions

- [TANA3Approximation \(\)](#)
default constructor
- [TANA3Approximation \(ProblemDescDB &problem_db, const size_t &num_acv\)](#)
standard constructor
- [~TANA3Approximation \(\)](#)
destructor

Protected Member Functions

- [int num_coefficients \(\) const](#)
return the minimum number of samples required to build the derived class approximation type in numVars dimensions
- [int num_constraints \(\) const](#)
return the number of constraints to be enforced via anchorPoint
- [void find_coefficients \(\)](#)
calculate the data fit coefficients using currentPoints and anchorPoint
- [const Real & get_value \(const RealVector &x\)](#)
retrieve the approximate function value for a given parameter vector
- [const RealBaseVector & get_gradient \(const RealVector &x\)](#)
retrieve the approximate function gradient for a given parameter vector
- [void clear_current \(\)](#)

Private Member Functions

- void [find_scaled_coefficients](#) ()
compute TANA coefficients based on scaled inputs
- void [offset](#) (const [RealVector](#) &x, [RealVector](#) &s)
based on minX, apply offset scaling to x to define s

Private Attributes

- [RealVector](#) pExp
the vector of exponent values
- [RealVector](#) minX
the vector of minimum parameter values used in scaling
- [RealVector](#) scX1
the vector of scaled x1 values
- [RealVector](#) scX2
the vector of scaled x2 values
- [Real](#) H
the scalar Hessian value in the TANA-3 approximation

10.103.1 Detailed Description

Derived approximation class for TANA-3 two-point exponential approximation (a multipoint approximation).

The [TANA3Approximation](#) class provides a multipoint approximation based on matching value and gradient data from two points (typically the current and previous iterates) in parameter space. It forms an exponential approximation in terms of intervening variables.

10.103.2 Member Function Documentation

10.103.2.1 void [clear_current](#) () [protected, virtual]

Redefine default implementation to support history mechanism.

Reimplemented from [Approximation](#).

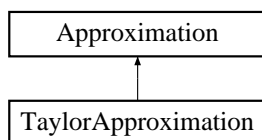
The documentation for this class was generated from the following files:

- TANA3Approximation.H
- TANA3Approximation.C

10.104 TaylorApproximation Class Reference

Derived approximation class for first- or second-order Taylor series (a local approximation).

Inheritance diagram for TaylorApproximation::



Public Member Functions

- [TaylorApproximation \(\)](#)
default constructor
- [TaylorApproximation \(ProblemDescDB &problem_db, const size_t &num_acv\)](#)
standard constructor
- [~TaylorApproximation \(\)](#)
destructor

Protected Member Functions

- int [num_coefficients \(\)](#) const
return the minimum number of samples required to build the derived class approximation type in numVars dimensions
- void [find_coefficients \(\)](#)
calculate the data fit coefficients using currentPoints and anchorPoint
- const Real & [get_value](#) (const [RealVector](#) &x)
retrieve the approximate function value for a given parameter vector
- const [RealBaseVector](#) & [get_gradient](#) (const [RealVector](#) &x)
retrieve the approximate function gradient for a given parameter vector
- const [RealMatrix](#) & [get_hessian](#) (const [RealVector](#) &x)
retrieve the approximate function Hessian for a given parameter vector

- void [second_order_flag](#) (bool flag)
set the Approximation's secondOrderFlag, if present

Private Attributes

- bool [secondOrderFlag](#)
flag to indicate a 2nd-order Taylor series with a Hessian term

10.104.1 Detailed Description

Derived approximation class for first- or second-order Taylor series (a local approximation).

The [TaylorApproximation](#) class provides a local approximation based on data from a single point in parameter space. It uses a first- or second-order Taylor series expansion: $f(x) = f(x_c) + \text{grad}(x_c)' (x - x_c) + (x - x_c)' \text{Hess}(x_c) (x - x_c) / 2$.

10.104.2 Member Function Documentation

10.104.2.1 void [second_order_flag](#) (bool *flag*) [inline, protected, virtual]

set the Approximation's secondOrderFlag, if present

Redefined by [TaylorApproximation](#) to set secondOrderFlag.

Reimplemented from [Approximation](#).

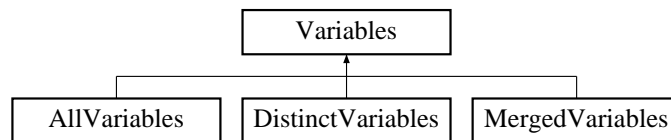
The documentation for this class was generated from the following files:

- TaylorApproximation.H
- TaylorApproximation.C

10.105 Variables Class Reference

Base class for the variables class hierarchy.

Inheritance diagram for Variables::



Public Member Functions

- [Variables \(\)](#)
default constructor
- [Variables \(const ProblemDescDB &problem_db\)](#)
standard constructor
- [Variables \(const pair< short, short > &view\)](#)
alternate constructor
- [Variables \(const Variables &vars\)](#)
copy constructor
- [virtual ~Variables \(\)](#)
destructor
- [Variables operator= \(const Variables &vars\)](#)
assignment operator
- [virtual size_t tv \(\) const](#)
Returns total number of vars.
- [virtual const RealVector & continuous_variables \(\) const](#)
return the active continuous variables
- [virtual void continuous_variables \(const RealVector &c_vars\)](#)
set the active continuous variables
- [virtual const IntVector & discrete_variables \(\) const](#)
return the active discrete variables

- virtual void `discrete_variables` (const `IntVector` &d_vars)
set the active discrete variables
- virtual const `StringArray` & `continuous_variable_labels` () const
return the active continuous variable labels
- virtual void `continuous_variable_labels` (const `StringArray` &cv_labels)
set the active continuous variable labels
- virtual const `StringArray` & `discrete_variable_labels` () const
return the active discrete variable labels
- virtual void `discrete_variable_labels` (const `StringArray` &dv_labels)
set the active discrete variable labels
- virtual const `RealVector` & `inactive_continuous_variables` () const
return the inactive continuous variables
- virtual void `inactive_continuous_variables` (const `RealVector` &i_c_vars)
set the inactive continuous variables
- virtual const `IntVector` & `inactive_discrete_variables` () const
return the inactive discrete variables
- virtual void `inactive_discrete_variables` (const `IntVector` &i_d_vars)
set the inactive discrete variables
- virtual const `StringArray` & `inactive_continuous_variable_labels` () const
return the inactive continuous variable labels
- virtual void `inactive_continuous_variable_labels` (const `StringArray` &i_c_vars)
set the inactive continuous variable labels
- virtual const `StringArray` & `inactive_discrete_variable_labels` () const
return the inactive discrete variable labels
- virtual void `inactive_discrete_variable_labels` (const `StringArray` &i_d_vars)
set the inactive discrete variable labels
- virtual size_t `acv` () const
returns total number of continuous vars
- virtual size_t `adv` () const
returns total number of discrete vars

- virtual [RealVector](#) [all_continuous_variables](#) () const
returns a single array with all continuous variables
- virtual void [all_continuous_variables](#) (const [RealVector](#) &a_c_vars)
sets all continuous variables using a single array
- virtual [IntVector](#) [all_discrete_variables](#) () const
returns a single array with all discrete variables
- virtual void [all_discrete_variables](#) (const [IntVector](#) &a_d_vars)
sets all discrete variables using a single array
- virtual [StringArray](#) [all_continuous_variable_labels](#) () const
returns a single array with all continuous variable labels
- virtual [StringArray](#) [all_discrete_variable_labels](#) () const
returns a single array with all discrete variable labels
- virtual [StringArray](#) [all_variable_labels](#) () const
returns a single array with all variable labels
- virtual void [read](#) (istream &s)
read a variables object from an istream
- virtual void [write](#) (ostream &s) const
write a variables object to an ostream
- virtual void [write_aprepro](#) (ostream &s) const
write a variables object to an ostream in aprepro format
- virtual void [read_annotated](#) (istream &s)
read a variables object in annotated format from an istream
- virtual void [write_annotated](#) (ostream &s) const
write a variables object in annotated format to an ostream
- virtual void [write_tabular](#) (ostream &s) const
write a variables object in tabular format to an ostream
- virtual void [read](#) ([BiStream](#) &s)
read a variables object from the binary restart stream
- virtual void [write](#) ([BoStream](#) &s) const
write a variables object to the binary restart stream
- virtual void [read](#) ([MPIUnpackBuffer](#) &s)

read a variables object from a packed MPI buffer

- virtual void [write](#) ([MPIPackBuffer](#) &s) const
write a variables object to a packed MPI buffer
- size_t [cv](#) () const
Returns number of active continuous vars.
- size_t [dv](#) () const
Returns number of active discrete vars.
- size_t [icv](#) () const
returns number of inactive continuous vars
- size_t [idv](#) () const
returns number of inactive discrete vars
- [Variables copy](#) () const
for use when a true copy is needed (the representation is `_not_shared`).
- const [IntList](#) & [merged_integer_list](#) () const
returns the list of discrete variables merged into a continuous array
- const pair< short, short > & [view](#) () const
returns variablesView
- pair< short, short > [get_view](#) (const [ProblemDescDB](#) &problem_db) const
defines variablesView from problem_db attributes
- const [String](#) & [variables_id](#) () const
returns the variables identifier string
- const [StringArray](#) & [continuous_variable_types](#) () const
return the active continuous variable types
- const [StringArray](#) & [discrete_variable_types](#) () const
return the active discrete variable types
- const [IntArray](#) & [continuous_variable_ids](#) () const
return the active continuous variable position identifiers
- const [IntArray](#) & [inactive_continuous_variable_ids](#) () const
return the inactive continuous variable position identifiers
- const [IntArray](#) & [all_continuous_variable_ids](#) () const
return the all continuous variable position identifiers

Protected Member Functions

- [Variables](#) ([BaseConstructor](#), const [ProblemDescDB](#) &problem_db, const pair< short, short > &view)
constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

Protected Attributes

- [IntList](#) [mergedIntegerList](#)
the list of discrete variables for which integrality is relaxed by merging them into a continuous array
- pair< short, short > [variablesView](#)
the variables view pair containing active (first) and inactive (second) view enumerations
- [StringArray](#) [continuousVarTypes](#)
array of variable types for the active continuous variables
- [StringArray](#) [discreteVarTypes](#)
array of variable types for the active discrete variables
- [IntArray](#) [continuousVarIds](#)
array of position identifiers for the active continuous variables
- [IntArray](#) [inactiveContinuousVarIds](#)
array of position identifiers for the inactive continuous variables
- [IntArray](#) [allContinuousVarIds](#)
array of position identifiers for the all continuous variables array
- [RealVector](#) [emptyRealVector](#)
an empty real vector returned in get functions when there are no variables corresponding to the request
- [IntVector](#) [emptyIntVector](#)
an empty int vector returned in get functions when there are no variables corresponding to the request
- [StringArray](#) [emptyStringArray](#)
an empty label array returned in get functions when there are no variables corresponding to the request

Private Member Functions

- virtual void [copy_rep](#) (const [Variables](#) *vars_rep)
Used by [copy\(\)](#) to copy the contents of a letter class.
- [Variables](#) * [get_variables](#) (const [ProblemDescDB](#) &problem_db)

Used by the standard envelope constructor to instantiate the correct letter class.

- [Variables](#) * [get_variables](#) (const pair< short, short > &view) const

Used by the alternate envelope constructor, by read functions, and by [copy\(\)](#) to instantiate a new letter class.

Private Attributes

- [String](#) [idVariables](#)

variables identifier string from the input file

- [Variables](#) * [variablesRep](#)

pointer to the letter (initialized only for the envelope)

- int [referenceCount](#)

number of objects sharing variablesRep

Friends

- bool [operator==](#) (const [Variables](#) &vars1, const [Variables](#) &vars2)

equality operator

- bool [operator!=](#) (const [Variables](#) &vars1, const [Variables](#) &vars2)

inequality operator

10.105.1 Detailed Description

Base class for the variables class hierarchy.

The [Variables](#) class is the base class for the class hierarchy providing design, uncertain, and state variables for continuous and discrete domains within a [Model](#). Using the fundamental arrays from the input specification, different derived classes define different views of the data. For memory efficiency and enhanced polymorphism, the variables hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Variables](#)) serves as the envelope and one of the derived classes (selected in [Variables::get_variables\(\)](#)) serves as the letter.

10.105.2 Constructor & Destructor Documentation

10.105.2.1 **Variables** ()

default constructor

The default constructor: `variablesRep` is NULL in this case (a populated `problem_db` is needed to build a meaningful **Variables** object). This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

10.105.2.2 **Variables** (const **ProblemDescDB** & *problem_db*)

standard constructor

This is the primary envelope constructor which uses `problem_db` to build a fully populated variables object. It only needs to extract enough data to properly execute `get_variables(problem_db)`, since the constructor overloaded with **BaseConstructor** builds the actual base class data inherited by the derived classes.

10.105.2.3 **Variables** (const pair< short, short > & *view*)

alternate constructor

This is the alternate envelope constructor for instantiations on the fly. Since it does not have access to `problem_db`, the letter class is not fully populated. This constructor executes `get_variables(view)`, which invokes the default constructor of the derived letter class, which in turn invokes the default constructor of the base class.

10.105.2.4 **Variables** (const **Variables** & *vars*)

copy constructor

Copy constructor manages sharing of `variablesRep` and incrementing of `referenceCount`.

10.105.2.5 **~Variables** () [virtual]

destructor

Destructor decrements `referenceCount` and only deletes `variablesRep` when `referenceCount` reaches zero.

10.105.2.6 **Variables** (**BaseConstructor**, const **ProblemDescDB** & *problem_db*, const pair< short, short > & *view*) [protected]

constructor initializes the base class part of letter classes (**BaseConstructor** overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all derived classes. `get_variables()` instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list (to avoid the recursion of the base class constructor calling `get_variables()` again). Since the letter IS the representation, its representation pointer is set to NULL (an uninitialized pointer causes problems in `~Variables`).

10.105.3 Member Function Documentation

10.105.3.1 `Variables` `operator=` (`const Variables & vars`)

assignment operator

Assignment operator decrements `referenceCount` for old `variablesRep`, assigns new `variablesRep`, and increments `referenceCount` for new `variablesRep`.

10.105.3.2 `Variables` `copy` () `const`

for use when a true copy is needed (the representation is `_not_shared`).

Deep copies are used for history mechanisms such as `bestVariables` and `data_pairs` since these must catalogue copies (and should not change as the representation within current `Variables` changes).

10.105.3.3 `Variables` * `get_variables` (`const ProblemDescDB & problem_db`) [`private`]

Used by the standard envelope constructor to instantiate the correct letter class.

Initializes `variablesRep` to the appropriate derived type, as given by `problem_db` attributes. The standard derived class constructors are invoked.

10.105.3.4 `Variables` * `get_variables` (`const pair< short, short > & view`) `const` [`private`]

Used by the alternate envelope constructor, by read functions, and by `copy()` to instantiate a new letter class.

Initializes `variablesRep` to the appropriate derived type, as given by `view`. The default derived class constructors are invoked.

10.105.4 Member Data Documentation

10.105.4.1 `IntArray` `continuousVarIds` [`protected`]

array of position identifiers for the active continuous variables

These identifiers define positions of the active continuous variables within the total variable sequence.

10.105.4.2 `IntArray` `inactiveContinuousVarIds` [`protected`]

array of position identifiers for the inactive continuous variables

These identifiers define positions of the inactive continuous variables within the total variable sequence.

10.105.4.3 `IntArray allContinuousVarIds` [protected]

array of position identifiers for the all continuous variables array

These identifiers define positions of the all continuous variables array within the total variable sequence.

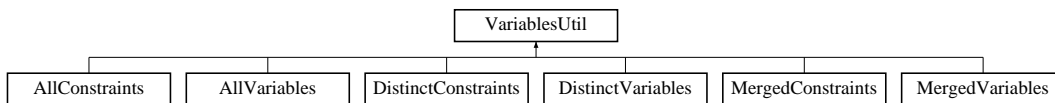
The documentation for this class was generated from the following files:

- DakotaVariables.H
- DakotaVariables.C

10.106 VariablesUtil Class Reference

Utility class for the [Variables](#) and [Constraints](#) hierarchies which provides convenience functions for variable vectors and label arrays for combining design, uncertain, and state variable types and merging continuous and discrete variable domains.

Inheritance diagram for VariablesUtil::



Public Member Functions

- [VariablesUtil](#) ()
constructor
- [~VariablesUtil](#) ()
destructor

Protected Member Functions

- void [update_merged](#) (const [RealVector](#) &c_array, const [IntVector](#) &d_array, [RealVector](#) &m_array) const
combine a continuous array and a discrete array into a single continuous array through promotion of integers to reals (merged view)
- void [update_all_continuous](#) (const [RealVector](#) &c1_array, const [RealVector](#) &c2_array, const [RealVector](#) &c3_array, [RealVector](#) &all_array) const
combine 3 continuous arrays (design, uncertain, state) into a single continuous array (all view)
- void [update_all_discrete](#) (const [IntVector](#) &d1_array, const [IntVector](#) &d2_array, [IntVector](#) &all_array) const
combine 2 discrete arrays (design, state) into a single discrete array (all view)
- void [update_from_merged](#) (const [RealVector](#) &m_array, [RealVector](#) &c_array, [IntVector](#) &d_array) const
extract a continuous array and a discrete array from a single continuous array through truncation of reals to integers (merged view)
- void [update_from_all_continuous](#) (const [RealVector](#) &all_array, [RealVector](#) &c1_array, [RealVector](#) &c2_array, [RealVector](#) &c3_array) const

extract 3 continuous arrays (design, uncertain, state) from a single continuous array (all view)

- void `update_from_all_discrete` (const `IntVector` &all_array, `IntVector` &d1_array, `IntVector` &d2_array) const

extract 2 discrete arrays (design, state) from a single discrete array (all view)

- void `update_labels` (const `StringArray` &l1_array, const `StringArray` &l2_array, `StringArray` &all_array) const

combine 2 label arrays into a single label array (merged or all views)

- void `update_labels` (const `StringArray` &l1_array, const `StringArray` &l2_array, const `StringArray` &l3_array, `StringArray` &all_array) const

combine 3 label arrays (design, uncertain, state) into a single label array (all view)

- void `update_labels_partial` (size_t num_items, const `StringArray` &src_array, size_t src_start_index, `StringArray` &tgt_array, size_t tgt_start_index) const

update a portion of one label array from a portion of another label array (all view)

10.106.1 Detailed Description

Utility class for the `Variables` and `Constraints` hierarchies which provides convenience functions for variable vectors and label arrays for combining design, uncertain, and state variable types and merging continuous and discrete variable domains.

Derived classes within the `Variables` and `Constraints` hierarchies use multiple inheritance to inherit these utilities.

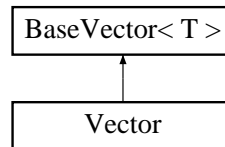
The documentation for this class was generated from the following file:

- `VariablesUtil.H`

10.107 Vector Class Template Reference

Template class for the [Dakota](#) numerical vector.

Inheritance diagram for Vector::



Public Member Functions

- [Vector](#) ()
Default constructor.
- [Vector](#) (size_t len)
Constructor which takes an initial length.
- [Vector](#) (size_t len, const T &initial_val)
Constructor which takes an initial length and an initial value.
- [Vector](#) (const [Vector](#)< T > &a)
Copy constructor.
- [Vector](#) (const T *p, size_t len)
Constructor which copies len entries from T.*
- [~Vector](#) ()
Destructor.
- [Vector](#)< T > & [operator=](#) (const [Vector](#)< T > &a)
Normal const assignment operator.
- [Vector](#)< T > & [operator=](#) (const T &ival)
Sets all elements in self to the value ival.
- [operator T *](#) () const
Converts the [Vector](#) to a standard C-style array. Use with care!
- void [read](#) (istream &s)
Reads a [Vector](#) from an input stream.

- void `read` (istream &s, Array< String > &label_array)
Reads a [Vector](#) and associated label array from an input stream.
- void `read_partial` (istream &s, size_t start_index, size_t num_items)
Reads part of a [Vector](#) from an input stream.
- void `read_partial` (istream &s, size_t start_index, size_t num_items, Array< String > &label_array)
Reads part of a [Vector](#) and the corresponding labels from an input stream.
- void `read_tabular` (istream &s)
Reads a [Vector](#) from a tabular text input file.
- void `read_annotated` (istream &s, Array< String > &label_array)
Reads a [Vector](#) and associated label array in annotated from an input stream.
- void `write` (ostream &s) const
Writes a [Vector](#) to an output stream.
- void `write` (ostream &s, const Array< String > &label_array) const
Writes a [Vector](#) and associated label array to an output stream.
- void `write_partial` (ostream &s, size_t start_index, size_t num_items) const
Writes part of a [Vector](#) to an output stream.
- void `write_partial` (ostream &s, size_t start_index, size_t num_items, const Array< String > &label_array) const
Writes part of a [Vector](#) and the corresponding labels to an output stream.
- void `write_aprepro` (ostream &s, const Array< String > &label_array) const
Writes a [Vector](#) and associated label array to an output stream in `aprepro` format.
- void `write_partial_aprepro` (ostream &s, size_t start_index, size_t num_items, const Array< String > &label_array) const
Writes part of a [Vector](#) and the corresponding labels to an output stream in `aprepro` format.
- void `write_annotated` (ostream &s, const Array< String > &label_array) const
Writes a [Vector](#) and associated label array in annotated form to an output stream.
- void `write_tabular` (ostream &s) const
Writes a [Vector](#) in tabular form to an output stream.
- void `write_partial_tabular` (ostream &s, size_t start_index, size_t num_items) const
Writes part of a [Vector](#) in tabular form to an output stream.
- void `read` (BiStream &s, Array< String > &label_array)

Reads a *Vector* and associated label array from a binary input stream.

- void `write (BoStream &s, const Array< String > &label_array) const`
Writes a *Vector* and associated label array to a binary output stream.
- void `read (MPIUnpackBuffer &s)`
Reads a *Vector* from a buffer after an MPI receive.
- void `read (MPIUnpackBuffer &s, Array< String > &label_array)`
Reads a *Vector* and associated label array from a buffer after an MPI receive.
- void `write (MPIPackBuffer &s) const`
Writes a *Vector* to a buffer prior to an MPI send.
- void `write (MPIPackBuffer &s, const Array< String > &label_array) const`
Writes a *Vector* and associated label array to a buffer prior to an MPI send.

10.107.1 Detailed Description

```
template<class T> class Dakota::Vector< T >
```

Template class for the *Dakota* numerical vector.

The *Dakota::Vector* class is the numeric vector class. It inherits from the common vector class *Dakota::BaseVector* which provides the same interface for both the STL and RW vector classes. If the STL version of *BaseVector* is based on the *valarray* class then some basic vector operations such as + , * are available. This class adds functionality to read/write vectors in a variety of ways

10.107.2 Constructor & Destructor Documentation

10.107.2.1 `Vector (const T * p, size_t len) [inline]`

Constructor which copies len entries from T*.

Assigns size values from p into array.

10.107.3 Member Function Documentation

10.107.3.1 `Vector< T > & operator= (const T & ival) [inline]`

Sets all elements in self to the value ival.

Assigns all values of array to ival. If STL, uses the vector assign method because there is no operator=(ival).

Reimplemented from [BaseVector](#).

The documentation for this class was generated from the following file:

- [DakotaVector.H](#)

Chapter 11

DAKOTA File Documentation

11.1 JEGAEvaluator.C File Reference

Contains the implementation of the JEGAEvaluator class.

Namespaces

- namespace [Dakota](#)
- namespace **JEGA::Logging**
- namespace **JEGA::Algorithms**

11.1.1 Detailed Description

Contains the implementation of the JEGAEvaluator class.

11.2 JEGAEvaluator.H File Reference

Contains the definition of the JEGAEvaluator class.

Namespaces

- namespace [Dakota](#)

11.2.1 Detailed Description

Contains the definition of the JEGAEvaluator class.

11.3 JEGAOptimizer.C File Reference

Contains the implementation of the JEGAOptimizer class.

Namespaces

- namespace [Dakota](#)
- namespace `eddy::utilities`

Functions

- `template<typename T> string asstring (const T &val)`
Creates a string from the argument "val" using an ostream.

11.3.1 Detailed Description

Contains the implementation of the JEGAOptimizer class.

11.4 JEGAOptimizer.H File Reference

Contains the definition of the JEGAOptimizer class.

Namespaces

- namespace **JEGA**
- namespace **JEGA::Utilities**
- namespace **JEGA::FrontEnd**
- namespace [Dakota](#)

11.4.1 Detailed Description

Contains the definition of the JEGAOptimizer class.

11.5 keywordtable.C File Reference

file containing keywords for the strategy, method, model, variables, interface, and responses input specifications from **dakota.input.spec**

Variables

- const struct KeywordHandler [idrKeywordTable](#) []

Initialize the keyword table as a vector of KeywordHandler structures (KeywordHandler declared in idr-keyword.h). A null KeywordHandler structure signifies the end of the keyword table.

11.5.1 Detailed Description

file containing keywords for the strategy, method, model, variables, interface, and responses input specifications from **dakota.input.spec**

11.6 main.C File Reference

file containing the main program for DAKOTA

Functions

- int `main` (int argc, char *argv[])
The main DAKOTA program.

11.6.1 Detailed Description

file containing the main program for DAKOTA

11.6.2 Function Documentation

11.6.2.1 int main (int argc, char * argv[])

The main DAKOTA program.

Manage command line inputs, input files, restart file(s), output streams, and top level parallel iterator communicators. Instantiate the Strategy and invoke its `run_strategy()` virtual function.

11.7 restart_util.C File Reference

file containing the DAKOTA restart utility main program

Namespaces

- namespace [Dakota](#)

Functions

- void [print_restart](#) (int argc, char **argv, [String](#) print_dest)
print a restart file
- void [print_restart_tabular](#) (int argc, char **argv, [String](#) print_dest)
print a restart file (tabular format)
- void [read_neutral](#) (int argc, char **argv)
read a restart file (neutral file format)
- void [repair_restart](#) (int argc, char **argv, [String](#) identifier_type)
repair a restart file by removing corrupted evaluations
- void [concatenate_restart](#) (int argc, char **argv)
concatenate multiple restart files
- int [main](#) (int argc, char *argv[])
The main program for the DAKOTA restart utility.

11.7.1 Detailed Description

file containing the DAKOTA restart utility main program

11.7.2 Function Documentation

11.7.2.1 void print_restart (int argc, char ** argv, String print_dest)

print a restart file

Usage: "dakota_restart_util print dakota.rst"

"dakota_restart_util to_neutral dakota.rst dakota.neu"

Prints all evals. in full precision to either stdout or a neutral file. The former is useful for ensuring that duplicate detection is successful in a restarted run (e.g., starting a new method from the previous best), and the latter is used for translating binary files between platforms.

11.7.2.2 void print_restart_tabular (int argc, char ** argv, String print_dest)

print a restart file (tabular format)

Usage: "dakota_restart_util to_pdb dakota.rst dakota.pdb"

"dakota_restart_util to_tabular dakota.rst dakota.txt"

Unrolls all data associated with a particular tag for all evaluations and then writes this data in a tabular format (e.g., to a PDB database or MATLAB/TECPLOT data file).

11.7.2.3 void read_neutral (int argc, char ** argv)

read a restart file (neutral file format)

Usage: "dakota_restart_util from_neutral dakota.neu dakota.rst"

Reads evaluations from a neutral file. This is used for translating binary files between platforms.

11.7.2.4 void repair_restart (int argc, char ** argv, String identifier_type)

repair a restart file by removing corrupted evaluations

Usage: "dakota_restart_util remove 0.0 dakota_old.rst dakota_new.rst"

"dakota_restart_util remove_ids 2 7 13 dakota_old.rst dakota_new.rst"

Repairs a restart file by removing corrupted evaluations. The identifier for evaluation removal can be either a double precision number (all evaluations having a matching response function value are removed) or a list of integers (all evaluations with matching evaluation ids are removed).

11.7.2.5 void concatenate_restart (int argc, char ** argv)

concatenate multiple restart files

Usage: "dakota_restart_util cat dakota_1.rst ... dakota_n.rst dakota_new.rst"

Combines multiple restart files into a single restart database.

11.7.2.6 int main (int argc, char * argv[])

The main program for the DAKOTA restart utility.

Parse command line inputs and invoke the appropriate utility function ([print_restart\(\)](#), [print_restart_tabular\(\)](#), [read_neutral\(\)](#), [repair_restart\(\)](#), or [concatenate_restart\(\)](#)).

Chapter 12

Recommended Practices for DAKOTA Development

12.1 Introduction

Common code development practices can be extremely useful in multiple developer environments. Particular styles for code components lead to improved readability of the code and can provide important visual cues to other developers.

Much of this recommended practices document is borrowed from the CUBIT mesh generation project, which in turn borrows its recommended practices from other projects. As a result, C++ coding styles are fairly standard across a variety of Sandia software projects in the engineering and computational sciences.

12.2 Style Guidelines

Style guidelines involve the ability to discern at a glance the type and scope of a variable or function.

12.2.1 Class and variable styles

Class names should be composed of two or more descriptive words, with the first character of each word capitalized, e.g.:

```
class ClassName;
```

Class member variables should be composed of two or more descriptive words, with the first character of the second and succeeding words capitalized, e.g.:

```
double classMemberVariable;
```

Temporary (i.e. local) variables are lower case, with underscores separating words in a multiple word temporary variable, e.g.:

```
int temporary_variable;
```

Constants (i.e. parameters) are upper case, with underscores separating words, e.g.:

```
const double CONSTANT_VALUE;
```

12.2.2 Function styles

Function names are lower case, with underscores separating words, e.g.:

```
int function_name();
```

There is no need to distinguish between member and non-member functions by style, as this distinction is usually clear by context. This style convention allows member function names which set and return the value of a similarly-named private member variable, e.g.:

```
int memberVariable;
void member_variable(int a) { // set
    memberVariable = a;
}
int member_variable() const { // get
    return memberVariable;
}
```

In cases where the data to be set or returned is more than a few bytes, it is highly desirable to employ const references to avoid unnecessary copying, e.g.:

```
void continuous_variables(const RealVector& c_vars) { // set
    continuousVariables = c_vars;
}
const RealVector& continuous_variables() const { // get
    return continuousVariables;
}
```

Note that it is not necessary to always accept the returned data as a const reference. If it is desired to be able change this data, then accepting the result as a new variable will generate a copy, e.g.:

```
const RealVector& c_vars = model.continuous_variables(); // reference to continuousVariables cannot be changed
RealVector c_vars = model.continuous_variables(); // local copy of continuousVariables can be changed
```


12.2.3 Miscellaneous

Appearance of typedefs to redefine or alias basic types is isolated to a few header files ([data_types.h](#), [template_defs.h](#)), so that issues like program precision can be changed by changing a few lines of typedefs rather than many lines of code, e.g.:

```
typedef double Real;
```

xemacs is the preferred source code editor, as it has C++ modes for enhancing readability through color (turn on "Syntax highlighting"). Other helpful features include "Paren highlighting" for matching parentheses and the "New Frame" utility to have more than one window operating on the same set of files (note that this is still the same edit session, so all windows are synchronized with each other). Window width should be set to 80 internal columns, which can be accomplished by manual resizing, or preferably, using the following alias in your shell resource file (e.g., .cshrc):

```
alias xemacs "xemacs -g 81x63"
```

where an external width of 81 gives 80 columns internal to the window and the desired height of the window will vary depending on monitor size. This window width imposes a coding standard since you should avoid line wrapping by continuing anything over 80 columns onto the next line.

Indenting increments are 2 spaces per indent and comments are aligned with the code they describe, e.g.:

```
void abort_handler(int code)
{
    int initialized = 0;
    MPI_Initialized(&initialized);
    if (initialized) {
        // comment aligned to block it describes
        int size;
        MPI_Comm_size(MPI_COMM_WORLD, &size);
        if (size>1)
            MPI_Abort(MPI_COMM_WORLD, code);
        else
            exit(code);
    }
    else
        exit(code);
}
```

Also, the continuation of a long command is indented 2 spaces, e.g.:

```
const String& iterator_scheduling
    = problem_db.get_string("strategy.iterator_scheduling");
```

and similar lines are aligned for readability, e.g.:

```
cout << "Numerical gradients using " << finiteDiffStepSize*100. << "% "
    << finiteDiffType << " differences\nto be calculated by the "
    << methodSource << " finite difference routine." << endl;
```

Lastly, #ifdef's are not indented (to make use of syntax highlighting in xemacs).

12.3 File Naming Conventions

In addition to the style outlined above, the following file naming conventions have been established for the DAKOTA project.

File names for C++ classes should, in general, use the same name as the class defined by the file. Exceptions include:

- with the introduction of the Dakota namespace, base classes which previously utilized prepended Dakota identifiers can now safely omit the identifiers. However, since file names do not have namespace protection from name collisions, they retain the prepended Dakota identifier. For example, a class previously named `DakotaModel` which resided in `DakotaModel.[CH]`, is now `Dakota::Model` (class `Model` in namespace `Dakota`) residing in the same filenames. The retention of the previous filenames reduces the possibility of multiple instances of a `Model.H` causing problems. Derived classes (e.g., `NestedModel`) do not require a prepended Dakota identifier for either the class or file names.
- in a few cases, it is convenient to maintain several closely related classes in a single file, in which case the file name may reflect the top level class or some generalization of the set of classes (e.g., `DakotaResponse.[CH]` files contain `Dakota::Response` and `Dakota::ResponseRep` classes, and `DakotaBinStream.[CH]` files contain the `Dakota::BiStream` and `Dakota::BoStream` classes).

The type of file is determined by one of the four file name extensions listed below:

- **.H** A class header file ends in the suffix `.H`. The header file provides the class declaration. This file does not contain code for implementing the methods, except for the case of inline functions. Inline functions are to be placed at the bottom of the file with the keyword `inline` preceding the function name.
- **.C** A class implementation file ends in the suffix `.C`. An implementation file contains the definitions of the members of the class.
- **.h** A header file ends in the suffix `.h`. The header file contains information usually associated with procedures. Defined constants, data structures and function prototypes are typical elements of this file.
- **.c** A procedure file ends in the suffix `.c`. The procedure file contains the actual procedures.

12.4 Class Documentation Conventions

Class documentation uses the doxygen tool available from <http://www.doxygen.org> and employs the JAVA-doc comment style. Brief comments appear in header files next to the attribute or function declaration. Detailed descriptions for functions should appear alongside their implementations (i.e., in the `.C` files for non-inlined, or in the headers next to the function definition for inlined). Detailed comments for a class or a class attribute must go in the header file as this is the only option.

NOTE: Previous class documentation utilities (`class2frame` and `class2html`) used the `/// comment style and comment blocks such as this:`

```
/// Class:      Model
/// Description: The model to be iterated by the Iterator.  Contains Variables, Interface, and Response objects.
/// Owner:      Mike Eldred
/// Version:    $Id: Dev_Recomm_Pract.dox 3615 2006-05-10 17:39:26Z mseldre $
```

These tools are no longer used, so remaining comment blocks of this type are informational only and will not appear in the documentation generated by doxygen.

Chapter 13

Instructions for Modifying DAKOTA's Input Specification

13.1 Modify `dakota.input.spec`

The master input specification resides in `dakota.input.spec` in `$DAKOTA/src`. As part of the Input Deck Reader (IDR) build process, a soft link to this file is created in `$DAKOTA/VendorPackages/idr`. The master input specification can be modified with the addition of new constructs using the following logical relationships:

- `{ }` for required individual specifications
- `()` for required group specifications
- `[]` for optional individual specifications
- `[][]` for optional group specifications
- `|` for "or" conditionals

These constructs can be used to define a variety of dependency relationships in the input specification. It is recommended that you review the existing specification and have an understanding of the constructs in use before attempting to add new constructs.

Warning:

- Do *not* skip this step. Attempts to modify the [keywordtable.C](#) and [ProblemDescDB.C](#) files in `$DAKOTA/src` without reference to the results of the code generator are very error-prone. Moreover, the input specification provides a reference to the allowable inputs of a particular executable and should be kept in synch with the parser files (modifying the parser files independent of the input specification creates, at a minimum, undocumented features).
- All keywords in `dakota.input.spec` are currently lower case by convention. All user inputs are converted to lower case by the parser prior to keyword match testing, resulting in case insensitive parsing. [To

allow keywords with capitalization and case sensitive parsing, `IDR_NO_CONVRSN` should be passed in `idr_init()` and uses of `idr_case_convert()` within `idr.c` should be reviewed.]

- Since the Input Deck Reader (IDR) parser allows abbreviation of keywords, you *must* avoid adding a keyword that could be misinterpreted as an abbreviation for a different keyword within the same keyword handler (the term "keyword handler" refers to the `strategy_kwhandler()`, `method_kwhandler()`, `variables_kwhandler()`, `interface_kwhandler()`, and `responses_kwhandler()` member functions in the [IDRProblemDescDB](#) class). For example, adding the keyword "expansion" within the method specification would be a mistake if the keyword "expansion_factor" already was being used in this specification.
- Since IDR input is order-independent, the same keyword may be reused multiple times in the specification if and only if the specification blocks are mutually exclusive. For example, method selections (e.g., `dot_frcg`, `dot_bfgs`) can reuse the same method setting keywords (e.g., `optimization_type`) since the method selection blocks are all separated by logical "or"s. If `dot_frcg` and `dot_bfgs` were not exclusive and could be specified at the same time, then association of the `optimization_type` setting with a particular method would be ambiguous. This is the reason why repeated specifications which are non-exclusive must be made unique, typically with a prepended identifier (e.g., `cdv_initial_point`, `ddv_initial_point`).

13.2 Rebuild IDR

```
cd $DAKOTA/VendorPackages/idr
make clean
make
```

These steps regenerate [keywordtable.C](#) and `idr-gen-code.C` in the `$DAKOTA/VendorPackages/idr/<canonical_build_directory>` directory for use in updating [keywordtable.C](#) and [IDRProblemDescDB.C](#) in `$DAKOTA/src`.

13.3 Update keywordtable.C in \$DAKOTA/src

Do *not* directly replace the [keywordtable.C](#) in `$DAKOTA/src` using the one from `idr`, as there are important differences in the `kwhandler` bindings. Rather, update the [keywordtable.C](#) in `$DAKOTA/src` using the one from `idr` as a reference. Once this step is completed, it is a good idea to verify the match by diff'ing the 2 files. The only differences should be in comments, includes, and `kwhandler` declarations.

13.4 Update IDRProblemDescDB.C in \$DAKOTA/src

Find the keyword handler functions (e.g., `variables_kwhandler()`) in `$DAKOTA/VendorPackages/idr/<canonical_build_directory>/idr-gen-code.C` and `$DAKOTA/src/IDRProblemDescDB.C` which correspond to your modifications to the input specification. The `idr-gen-code.C` file is the result of a code generator and contains skeleton constructs for extracting data from IDR. You will be copying over parts of this skeleton to [IDRProblemDescDB.C](#) and then adding code to populate attributes within `Data` class container objects.

13.4.1 Replace keyword handler declarations and counter loop

Rather than trying to update these line by line, it is recommended to delete the entire block starting with the keyword declarations and ending at the bottom of the keyword counter loop. The declarations assign -1 to keywords and look like this:

```
Int cdv_descriptor = -1;
Int cdv_initial_point = -1;
```

They start after the line "Int cntr;". The keyword counter loop looks like this:

```
for ( cntr=data_len; cntr--; ) {
  if ( idr_find_id( &cdv_descriptor, cntr,
                  "cdv_descriptor", id_str, kw_str ) ) continue;
  ...
  if ( idr_find_id( &wuv_dist_upper_bounds, cntr,
                  "wuv_dist_upper_bounds", id_str, kw_str ) ) continue;
}
```

Once the old keyword declarations and keyword counter loop have been deleted, replace them with the corresponding blocks from `idr-gen-code.C` containing the updated keyword declarations and counter loop.

13.4.2 Update keyword handler logic blocks

For the newly added or modified input specifications, copy the appropriate skeleton constructs from `idr-gen-code.C` and paste them into the corresponding location in `IDRProblemDescDB.C`.

The next step is to add code to these skeletons to set data attributes within the Data class object used by the keyword handler. At the top of the method, variables, interface, and responses keyword handlers, a Data class object is instantiated in order to store attributes, e.g.:

```
DataMethod data_method;
```

and within the strategy keyword handler, a reference to the [strategySpec](#) data class object is used to store attributes. Each of these data class objects is a simple container class which contains the data from a single keyword handler invocation. Within each skeleton construct, you will extract data from the IDR data structures and then use this data to set the corresponding attribute within the Data class.

Integer, real, and string data are extracted using the `idata`, `rdata`, and `cdata` arrays provided by IDR. These arrays are indexed using a bracket operator with the keyword as an index. Lists of integer, list of real, and list of string data are extracted using the `IDRProblemDescDB::idr_get_int_table()`, `IDRProblemDescDB::idr_get_real_table()`, and `IDRProblemDescDB::idr_get_string_table()` functions, respectively.

Example 1: if you added the specification:

```
[method_setting = <REAL>]
```

you would copy over

```
if ( method_setting >= 0 ) {
}
```

from `idr-gen-code.C` into `IDRProblemDescDB.C` and then populate the if block with a call to set the corresponding attribute within the `data_method` object using data extracted using the `rdata` array:

```
if ( method_setting >= 0 ) {
    data_method.methodSetting = rdata[method_setting];
}
```

Use of a set member function within `DataMethod` is not needed since the data is public. The data is public since `ProblemDescDB` already provides sufficient encapsulation (`ProblemDescDB::dataMethodList`, `ProblemDescDB::dataModelList`, `ProblemDescDB::dataVariablesList`, `ProblemDescDB::dataInterfaceList`, `ProblemDescDB::dataResponsesList`, and `ProblemDescDB::strategySpec` are private attributes), and public access reduces the amount of code to manage when performing input specification modifications by omitting the need to add/modify set/get functions.

Example 2: if you added the specification

```
[method_setting = <LISTof><REAL>]
```

you would copy over

```
if ( method_setting >= 0 ) {
    { Int idr_table_len;
      Real** idr_table = idr_get_real_table( parsed_data, method_setting,
                                           idr_table_len, 1, 1 );
    }
}
```

from `idr-gen-code.C` into `IDRProblemDescDB.C` and then populate it with a loop which extracts each entry of the table and populates the corresponding attribute within the `data_method` object. The `idr_table_len` attribute is used for the loop limit and to size the `data_method` object.

```
if ( method_setting >= 0 ) {
    { Int idr_table_len;
      Real** idr_table = idr_get_real_table( parsed_data, method_setting,
                                           idr_table_len, 1, 1 );

      data_method.methodSetting.reshape(idr_table_len);
      for (int i = 0; i<idr_table_len; i++)
          data_method.methodSetting[i] = idr_table[0][i];
    }
}
```

Attention:

If no new data attributes have been added, but instead there are only new settings for existing attributes, then you're done with the database augmentation at this point (you just need to add code to use these new settings in the places where the existing attributes are used).

13.5 Update `ProblemDescDB.C` in `$DAKOTA/src`

13.5.1 Augment/update get_<data_type>() functions

The next update step involves extending the database retrieval functions in [ProblemDescDB.C](#). These retrieval functions accept an identifier string and return a database attribute of a particular type, e.g. a `RealVector`:

```
const RealVector& get_drv(const String& entry_name);
```

The implementation of each of these functions has a simple series of if-else checks which return the appropriate attribute based on the identifier string. For example,

```
if (entry_name == "variables.continuous_design.initial_point")
    return (*dbRep->dataVariablesIter).continuousDesignVars;
```

appears at the top of [ProblemDescDB::get_drv\(\)](#). Based on the identifier string, it returns the `continuous-DesignVars` attribute from a [DataVariables](#) object. Since there may be multiple variables specifications, the `dataVariablesIter` list iterator identifies which node in the list of [DataVariables](#) objects is used. In particular, `dataVariablesList` contains a list of all of the `data_variables` objects, one for each time `variables_kwhandler()` has been called by the parser. The particular variables object used for the data retrieval is managed by `dataVariablesIter`, which is set in a `set_db_list_nodes()` operation that will not be described here.

There may be multiple [DataMethod](#), [DataModel](#), [DataVariables](#), [DataInterface](#), and/or [DataResponses](#) objects. However, only one strategy specification is currently allowed so a list of [DataStrategy](#) objects is not needed. Rather, [ProblemDescDB::strategySpec](#) is the lone [DataStrategy](#) object.

To augment the `get_<data_type>()` functions, add `else` blocks with new identifier strings which retrieve the appropriate data attributes from the Data class object. The style for the identifier strings is a top-down hierarchical description, with specification levels separated by periods and words separated with underscores, e.g. "keyword.group_specification.individual_specification". Use the `(*dbRep->listIter).attribute` syntax for variables, interface, responses, and method specifications. For example, the `method_setting` example attribute would be added to `get_drv()` as:

```
else if (entry_name == "method.method_name.method_setting")
    return (*dbRep->dataMethodIter).methodSetting;
```

A strategy specification addition would not use a `(*dbRep->listIter)` syntax, but would instead look like:

```
else if (entry_name == "strategy.strategy_name.strategy_setting")
    return dbRep->strategySpec.strategySetting;
```

13.6 Update Corresponding Data Classes

In this step, we extend the Data class definitions ([DataStrategy](#), [DataMethod](#), [DataModel](#), [DataVariables](#), [DataInterface](#), and/or [DataResponses](#)) to include the new attributes referenced in [Update keyword handler logic blocks](#) and [Augment/update get_<data_type>\(\) functions](#).

13.6.1 Update the Data class header file

Add a new attribute to the public data for each of the new specifications. Follow the style guide for class attribute naming conventions (or mimic the existing code).

13.6.2 Update the .C file

Define defaults for the new attributes in the constructor initialization list. Add the new attributes to the assign() function for use by the copy constructor and assignment operator. Add the new attributes to the write(MPIPackBuffer&), read(MPIUnpackBuffer&), and write(ostream&) functions, paying careful attention to the use of a consistent ordering.

13.7 Use get_<data_type>() Functions

At this point, the new specifications have been mapped through all of the database classes. The only remaining step is to retrieve the new data within the constructors of the classes that need it. This is done by invoking the get_<data_type>() function on the [ProblemDescDB](#) object using the identifier string you selected in [Augment/update get_<data_type>\(\) functions](#). For example:

```
const String& interface_type = problem_db.get_string("interface.type");
```

passes the "interface.type" identifier string to the [ProblemDescDB::get_string\(\)](#) retrieval function, which returns the desired attribute from the active [DataInterface](#) object.

Warning:

Use of the get_<data_type>() functions is restricted to class constructors, since only in class constructors are the data list iterators (i.e., [dataMethodIter](#), [dataModelIter](#), [dataVariablesIter](#), [dataInterfaceIter](#), and [dataResponsesIter](#)) guaranteed to be set correctly. Outside of the constructors, the database list nodes will correspond to the last set operation, and may not return data from the desired list node.

13.8 Update the Documentation

Doxygen comments should be added to the Data class headers for the new attributes, and the reference manual sections describing the portions of [dakota.input.spec](#) that have been modified should be updated.

Chapter 14

Interfacing with DAKOTA as a Library

14.1 Introduction

Some users may be interested in linking the DAKOTA toolkit into another application for use as an algorithm library. While this is not the primary usage model for DAKOTA, certain facilities are in place to allow this type of integration.

As part of the normal DAKOTA build process, where `Dakota/configure -prefix=`pwd`` has been run prior to `make && make install`, a `libdakota.a` is created and a copy of it is placed in `Dakota/lib`. This library contains all source files from `Dakota/src` excepting the `main.C` and `restart_util.C` main programs. This library may be linked with another application through inclusion of `-ldakota` on the link line. Library and header paths may also be specified using the `-L` and `-I` compiler options (using `Dakota/lib` and `Dakota/include`, respectively). Depending on the configuration used when building this library, other libraries for the vendor optimizers and vendor packages will also be needed to resolve DAKOTA symbols for DOT, NPSOL, OPT++, SGOPT, LHS, Epetra, etc. Copies of these libraries are also placed in `Dakota/lib`. An XML specification of library names and paths is also available in `Dakota/dependency`.

Warning:

While users are free to interface DAKOTA as a library within other software applications for their own internal use, the GNU GPL license stipulates that any application linked with DAKOTA in this way defines a "derivative work" and can only be distributed externally under the same GNU GPL open source license. Refer to <http://www.gnu.org/licenses/gpl.html> or contact the DAKOTA team for additional information.

Attention:

The use of DAKOTA as an algorithm library should be distinguished from the linking of simulations within DAKOTA using the direct application interface (see [DirectFnApplicInterface](#)). In the former, DAKOTA is providing algorithm services to another software application, and in the latter, a linked simulation is providing analysis services to DAKOTA. It is not uncommon for these two capabilities to be used in combination, resulting in a "sandwich" implementation.

The procedure for utilizing DAKOTA as a library within another application involves a number of steps that

are similar to those used in the stand-alone DAKOTA application. The stand-alone procedure can be viewed in the file `main.C`, and the differences for the library approach are most easily explained with reference to that file. The basic steps of executing DAKOTA include instantiating the `ParallelLibrary`, `CommandLineHandler`, and `ProblemDescDB` objects; managing the DAKOTA input file (`ProblemDescDB::manage_inputs()`); specifying restart files and output streams (`ParallelLibrary::specify_outputs_restart()`); and instantiating the `Strategy` and running it (`Strategy::run_strategy()`). When using DAKOTA as an algorithm library, the operations are quite similar, although command line information (`argc`, `argv`, and therefore `CommandLineHandler`) will not in general be accessible. In particular, `main.C` can pass `argc` and `argv` into the `ParallelLibrary` and `CommandLineHandler` constructors and then pass the `CommandLineHandler` object into `ProblemDescDB::manage_inputs()` and `ParallelLibrary::specify_outputs_restart()`. In an algorithm library approach, a `CommandLineHandler` object is not instantiated and overloaded forms of the `ParallelLibrary` constructor, `ProblemDescDB::manage_inputs()`, and `ParallelLibrary::specify_outputs_restart()` are used.

The overloaded forms of these functions are as follows. For instantiation of the `ParallelLibrary` object, the default constructor may be used. This constructor assumes that MPI is initialized elsewhere in the parent application. That is, the instantiation

```
ParallelLibrary parallel_lib(argc, argv);
```

is replaced with

```
ParallelLibrary parallel_lib;
```

In the case of specifying restart files and output streams, the call to

```
parallel_lib.specify_outputs_restart(cmd_line_handler);
```

should be replaced with its overloaded form in order to pass the required information through the parameter list

```
parallel_lib.specify_outputs_restart(std_output_filename, std_error_filename,
read_restart_filename, write_restart_filename, restart_evals);
```

where file names for standard output and error and restart read and write as well as the integer number of restart evaluations are passed through the parameter list rather than read from the command line of the main DAKOTA program. The definition of these attributes is performed elsewhere in the parent application (e.g., specified in the parent application input file or GUI).

With respect to alternate forms of `ProblemDescDB::manage_inputs()`, the two following sections describe different approaches to populating data within DAKOTA's problem description database. It is this database from which all DAKOTA objects draw data upon instantiation.

14.2 Problem database populated through input file parsing

The simplest approach to linking an application with the DAKOTA library is to rely on DAKOTA's normal parsing system to populate DAKOTA's problem database (`ProblemDescDB`) through the reading of an input file. The disadvantage to this approach is the requirement for an additional input file beyond those already required by the parent application.

In this approach, the call to

```
problem_db.manage_inputs(cmd_line_handler);
```

should be replaced with its overloaded form

```
problem_db.manage_inputs(dakota_input_file);
```

where the file name for the DAKOTA input is passed through the parameter list rather than read from the command line of the main DAKOTA program. Again, the definition of the DAKOTA input file name is performed elsewhere in the parent application (e.g., specified in the parent application input file or GUI).

14.3 Problem database populated through external means

This approach is more involved than the previous approach, but it allows the application to publish all needed data to DAKOTA's database directly, thereby eliminating the need for the parsing of a separate DAKOTA input file. In this case, `ProblemDescDB::manage_inputs()` is not called. Rather, `DataStrategy`, `DataMethod`, `DataModel`, `DataVariables`, `DataInterface`, and `DataResponses` objects must be instantiated and populated with the desired problem data. These objects are then published to the problem database using `ProblemDescDB::insert_node()`, e.g.:

```
// instantiate the data object
DataMethod data_method;

// set the attributes within the data object
data_method.methodName = "nond_sampling";
...

// publish the data object to the ProblemDescDB
problem_db.insert_node(data_method);
```

The data objects are populated with their default values upon instantiation, so only the non-default values need to be specified. Refer to the `DataStrategy`, `DataMethod`, `DataModel`, `DataVariables`, `DataInterface`, and `DataResponses` class documentation and source code for lists of attributes and their defaults.

The default strategy is `single_method`, which runs a single iterator on a single model, and the default model is `single`, so it is not necessary to instantiate and publish a `DataStrategy` or `DataModel` object if advanced multi-component capabilities are not required. Rather, instantiation and insertion of a single `DataMethod`, `DataVariables`, `DataInterface`, and `DataResponses` object is sufficient for basic DAKOTA capabilities.

Once the data objects have been published to the `ProblemDescDB` object, a call to

```
problem_db.check_input();
```

will perform basic database error checking.

14.4 Instantiating the strategy

With the `ProblemDescDB` object populated with problem data, we may now instantiate the strategy.

```
// instantiate the strategy
Strategy selected_strategy(problem_db);
```

Following strategy construction, all MPI communicator partitioning has been performed and the [ParallelLibrary](#) instance may be interrogated for parallel configuration data. For example, the lowest level communicators in DAKOTA's multilevel parallel partitioning are the analysis communicators, which can be retrieved using:

```
// retrieve the set of analysis communicators for simulation initialization:
// one analysis comm per ParallelConfiguration (PC), one PC per Model.
Array<MPI_Comm> analysis_comms = parallel_lib.analysis_intra_communicators();
```

These communicators can then be used for initializing parallel simulation instances, where the number of MPI communicators in the array corresponds to one communicator per [ParallelConfiguration](#) instance, where there is one [ParallelConfiguration](#) instance per [Model](#).

14.5 Defining the direct application interface

When employing a library interface to DAKOTA, it is frequently desirable to also use a direct interface between DAKOTA and the simulation. There are two approaches to defining this direct interface.

14.5.1 Extension

The first approach involves extending the existing [DirectFnApplicInterface](#) class to support additional direct simulation interfaces. In this case, a new simulation interface function can be added to `Dakota/src/DirectFnApplicInterface.[CH]` for the simulation of interest. If the new function will not be a member function, then the following prototype should be used in order to pass the required data:

```
int sim(const Dakota::Variables& vars, const Dakota::ActiveSet& set,
        Dakota::Response& response);
```

If the new function will be a member function, then this can be simplified to

```
int sim();
```

since the data access can be performed through the [DirectFnApplicInterface](#) class attributes.

This simulation can then be added to the logic blocks in [DirectFnApplicInterface::derived_map_ac\(\)](#). In addition, [DirectFnApplicInterface::derived_map_if\(\)](#) and [DirectFnApplicInterface::derived_map_of\(\)](#) can be extended to perform pre- and post-processing tasks if desired, but this is not required.

While this approach is the simplest, it has the disadvantage that the DAKOTA library may need to be recompiled when the simulation or its direct interface is modified. If it is desirable to maintain the independence of the DAKOTA library from the host application, then the following derivation approach should be employed.

14.5.2 Derivation

The second approach is to derive a new interface from [DirectFnApplicInterface](#) in order to redefine several virtual functions. A typical derived class declaration might be


```

namespace SIM {

class DirectFnApplicInterface: public Dakota::DirectFnApplicInterface
{
public:

    // Constructor and destructor

    DirectFnApplicInterface(const ProblemDescDB& problem_db, const size_t& num_fns);
    ~DirectFnApplicInterface();

protected:

    // Virtual function redefinitions

    int derived_map_if(const DakotaString& if_name);
    int derived_map_ac(const DakotaString& ac_name);
    int derived_map_of(const DakotaString& of_name);

private:

    // Data
}

} // namespace SIM

```

where the new derived class resides in the simulation's namespace. Similar to the case of [Extension](#), the `DirectFnApplicInterface::derived_map_ac()` function is the required redefinition, and `DirectFnApplicInterface::derived_map_if()` and `DirectFnApplicInterface::derived_map_of()` are optional.

The new derived interface object (from namespace `SIM`) must now be plugged into the strategy. In the simplest case of a single model and interface, one could use

```

// retrieve the interface of interest
ModelList& all_models = problem_db.model_list();
Model& first_model = *all_models.begin();
Interface& interface = first_model.interface();
// plug in the new direct interface instance (DB does not need to be set)
interface.assign_rep(new SIM::DirectFnApplicInterface(problem_db), false);
// repropagate parallel configuration data down to the new interface
first_model.reset_communicators();

```

In a more advanced case of multiple models and multiple interface plug-ins, one might use

```

// retrieve the list of Models from the Strategy
ModelList& models = problem_db.model_list();
// iterate over the Model list
for (ModelLIter ml_iter = models.begin(); ml_iter != models.end(); ml_iter++) {
    Interface& interface = ml_iter->interface();
    if (interface.interface_type() == "direct" &&
        interface.analysis_drivers().contains("SIM") ) {
        // set the correct list nodes within the DB prior to new instantiations
        problem_db.set_db_model_nodes(ml_iter->model_id());
        // plug in the new direct interface instance
        interface.assign_rep(new SIM::DirectFnApplicInterface(problem_db, num_fns), false);
        // repropagate parallel configuration data down to the new interface
        ml_iter->reset_communicators();
    }
}

```

New direct interface instances inherit various attributes of use in configuring the simulation. In particular, the [ApplicationInterface::parallelLib](#) reference provides access to MPI communicator data (e.g., the analysis communicators discussed in [Instantiating the strategy](#)), [DirectFnApplicInterface::analysisDrivers](#) provides the analysis driver names specified by the user in the input file, and [DirectFnApplicInterface::analysisComponents](#) provides additional analysis component identifiers (such as mesh file names) provided by the user which can be used to distinguish different instances of the same simulation interface.

14.6 Executing the strategy

Finally, with simulation configuration and plug-ins completed, we execute the strategy:

```
// run the strategy
selected_strategy.run_strategy();
```

14.7 Retrieving data after a run

After executing the strategy, final results can be obtained through the use of [Strategy::variable_results\(\)](#) and [Strategy::response_results\(\)](#), e.g.:

```
// retrieve the final parameter values
const Variables& vars = selected_strategy.variable_results();

// retrieve the final response values
const Response& resp = selected_strategy.response_results();
```

In the case of optimization, the final design is returned, and in the case of uncertainty quantification, the final statistics are returned.

14.8 Summary

To utilize the DAKOTA library within a parent software application, the basic steps of [main.C](#) and the order of invocation of these steps should be mimicked from within the parent application. Of these steps, [ParallelLibrary](#) instantiation, [ProblemDescDB::manage_inputs\(\)](#) and [ParallelLibrary::specify_outputs_restart\(\)](#) require the use of overloaded forms in order to function in an environment without direct command line access and, potentially, without file parsing. Additional optional steps not performed in [main.C](#) include the extension/derivation of the direct interface and the retrieval of strategy results after a run.

DAKOTA's library mode has stabilized and is now being used successfully by several Sandia and external simulation codes/frameworks.

Chapter 15

Performing Function Evaluations

Performing function evaluations is one of the most critical functions of the DAKOTA software. It can also be one of the most complicated, as a variety of scheduling approaches and parallelism levels are supported. This complexity manifests itself in the code through a series of cascaded member functions, from the top level model evaluation functions, through various scheduling routines, to the low level details of performing a system call, fork, or direct function invocation. This section provides an overview of the primary classes and member functions involved.

15.1 Synchronous function evaluations

For a synchronous (i.e., blocking) mapping of parameters to responses, an iterator invokes [Model::compute_response\(\)](#) to perform a function evaluation. This function is all that is seen from the iterator level, as underlying complexities are isolated. The binding of this top level function with lower level functions is as follows:

- [Model::compute_response\(\)](#) utilizes [Model::derived_compute_response\(\)](#) for portions of the response computation specific to derived model classes.
- [Model::derived_compute_response\(\)](#) directly or indirectly invokes [Interface::map\(\)](#).
- [Interface::map\(\)](#) utilizes [ApplicationInterface::derived_map\(\)](#) for portions of the mapping specific to derived application interface classes.

15.2 Asynchronous function evaluations

For an asynchronous (i.e., nonblocking) mapping of parameters to responses, an iterator invokes [Model::asynch_compute_response\(\)](#) multiple times to queue asynchronous jobs and then invokes either [Model::synchronize\(\)](#) or [Model::synchronize_nowait\(\)](#) to schedule the queued jobs in blocking or nonblocking fashion. Again, these functions are all that is seen from the iterator level, as underlying complexities are isolated. The binding of these top level functions with lower level functions is as follows:

- `Model::asynch_compute_response()` utilizes `Model::derived_asynch_compute_response()` for portions of the response computation specific to derived model classes.
- This derived model class function directly or indirectly invokes `Interface::map()` in asynchronous mode, which adds the job to a scheduling queue.
- `Model::synchronize()` or `Model::synchronize_nowait()` utilize `Model::derived_synchronize()` or `Model::derived_synchronize_nowait()` for portions of the scheduling process specific to derived model classes.
- These derived model class functions directly or indirectly invoke `Interface::synch()` or `Interface::synch_nowait()`.
- For application interfaces, these interface synchronization functions are responsible for performing evaluation scheduling in one of the following modes:
 - asynchronous local mode (using `ApplicationInterface::asynchronous_local_evaluations()` or `ApplicationInterface::asynchronous_local_evaluations_nowait()`)
 - message passing mode (using `ApplicationInterface::self_schedule_evaluations()` or `ApplicationInterface::static_schedule_evaluations()` on the iterator master and `ApplicationInterface::serve_evaluations_synch()` or `ApplicationInterface::serve_evaluations_peer()` on the servers)
 - hybrid mode (using `ApplicationInterface::self_schedule_evaluations()` or `ApplicationInterface::static_schedule_evaluations()` on the iterator master and `ApplicationInterface::serve_evaluations_asynch()` on the servers)
- These scheduling functions utilize `ApplicationInterface::derived_map()` and `ApplicationInterface::derived_map_asynch()` for portions of asynchronous job launching specific to derived application interface classes, as well as `ApplicationInterface::derived_synch()` and `ApplicationInterface::derived_synch_nowait()` for portions of job capturing specific to derived application interface classes.

15.3 Analyses within each function evaluation

The discussion above covers the parallelism level of concurrent function evaluations serving an iterator. For the parallelism level of concurrent analyses serving a function evaluation, similar schedulers are involved (`ForkApplicInterface::synchronous_local_analyses()`, `ForkApplicInterface::asynchronous_local_analyses()`, `ApplicationInterface::self_schedule_analyses()`, `ApplicationInterface::serve_analyses_synch()`, `ForkApplicInterface::serve_analyses_asynch()`) to support synchronous local, asynchronous local, message passing, and hybrid modes. Not all of the schedulers are elevated to the `ApplicationInterface` level since the system call and direct function interfaces do not yet support nonblocking local analyses (and therefore support synchronous local and message passing modes, but not asynchronous local or hybrid modes). Fork interfaces, however, support all modes of analysis parallelism.

15.4 Todo List

Member **SurfpackApproximation**(ProblemDescDB &problem_db, const size_t &num_acv) The dakota data structures like RealVector inherit from std::vector.

Member **SurfpackApproximation**(ProblemDescDB &problem_db, const size_t &num_acv) Add RBFNet surface fit interface

Member **num_coefficients**() const : Check to make sure that the number of points required does not

Member **num_coefficients**() const : The reported number of points required is computed in a rather

Member **find_coefficients**() Right now, we're completely deleting the old data and then

Member **approximation_coefficients**() : Provide an appropriate list of coefficients for each surface type

Member **get_hessian**(const RealVector &x) Make this acceptably efficient

Member **checkForEqualityConstraints**() improve efficiency of conversion

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