

Proposed TFTR Electrical System

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Paul Smith!
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G. Bronner
J. Murray

Abstract

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The development of controlled thermo-nuclear fusion has progressed to the stage where the present facilities and energy available for future devices are not sufficient and must be increased by about a factor of ten.

This report describes the proposed TFTR AC utility power distribution system, an energy storage motor generator flywheel facility, and the rectifier conversion equipment for the Toroidal Field Confining System (TF), Ohmic Heating System (OH), Equilibrium Field System (EF) and the Neutral Beam Heating System (NB).

The general requirements are described and the special design considerations identified.

AC Power Distribution System

The pulse rate and energy require approximately 20 MVA average input to the experimental device for the 4 major loads. Thus, a transformer with a rating of 30/40/50 MVA was selected for connection to the PPPL existing 138 KV power system. A major consideration was to connect up to the existing system so that PPPL has only one billing meter. This connection also takes advantage of the diversity in load and hence, lower demand charges. The transformer will have two secondary windings with mutual impedances arranged so that the loading and unloading on the 13.8 KV pulsed lines will not produce voltage fluctuations on the 4.16 KV or 13.8 KV general building loads. (Fig 1)

Motor Generator Flywheel Sets

Providing the 4500 megajoules of pulsed energy to the loads once every 300 seconds requires approximately 32,000 HP motors and 950 KVA generators. To provide for the contingency of allowing operation (at low pulses) when there is a repair or shut down of an MG set and to keep the cost to a minimum, it was determined that two identical

fatigue failure be carefully considered

The flywheels will each be capable of delivering 2250 megajoules of energy a safety involved with the dissipation of energy must be considered. For example, if the AC power fails and can't supply load, a DC pump will be required and, if it loses power, a mechanical shaft-driven pump or sufficient cooling supplied from a standby feed fire water system, will be needed to prevent bearing damage. In the event of a mechanical difficulty, such as a bearing heating up, the system shall be forced to a stop within fifteen minutes by a motor dynamic-brake system or by applying a load on the generator. When both systems are used, the stopping time will be less than 8 minutes. In addition, a mechanical break on the flywheel may also be provided.

The drive-motors will each be approximately 16,000 horse-power wound-rotor motors with normal variable rotor resistors for starting. To control the pulsing every few seconds, cycloconvertors will be employed. These will provide control over the load on the AC distribution system, keeping the pulse magnitude to a value equal to or less than the steady state rating of the motor. The cycloconverter will also have the capability to take over the variable resistor in the event of a failure, will not result in high rotor circuit temperatures and will provide for higher pulse power capability on the AC power system. The TFTR Tokamak facility is not pulsing.

The generator must provide the peak loads, as shown on Fig 2, with a peak of 475 MVA per generator. The steady state rating will be left to the recommendation of the machine designers. It is expected that the steady state rating will be lower than the peak pulse rating by a factor of a

Because of the phase controlled rectifiers supplying the loads, there will be unbalanced currents flowing in the generator circuits. Due to the variable frequency harmonic filters, if employed, will have impedances varied with the frequency. Hence, it is expected that simple resistive damped capacitors will be employed to

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The large number of pulses which will occur in the 25 years' life (approximately 2 million pulses) will require that the

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The flywheels will each be capable of delivering 2250 megajoules of energy and safety involved with the dissipation of the energy must be considered. For example, if the AC power fails and can't supply lubrication, a DC pump will be required and, if it loses power, a mechanical shaft-driven pump or sufficient cooling supplied from a gray feed fire water system, will be needed to prevent bearing damage. In the event of mechanical difficulty, such as a bearing heating up, the system shall be forced to a stop in fifteen minutes by a motor dynamic-breaking system or by applying a load on the generator. When both systems are used, the stopping will be less than 8 minutes. In addition, mechanical break on the flywheel may also be provided.

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Because of the phase controlled rectifiers supplying the loads, there will be harmonic currents flowing in the generator circuits. Due to the variable frequency harmonic filters, if employed, will have impedances varied with the frequency. Hence, it is expected that simple resistive damped capacitors will be employed to keep harmonic content down to a moderate value (approximately equal to that which would be in a non-phase-back 6 pulse system. Fig

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Toroidal Field Rectifiers

The rectifiers for supplying the 600 volts 73,200 amperes DC current to the Toroidal Field are shown on Fig. 4. They will

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Toroidal Field Rectifiers

The rectifiers for supplying the 6000
volts 73,200 amperes DC current to the Toroi-
dal Field are shown on Fig. 4. They will be

12-pulse phase-controlled units. Because of the high inductive load and its experimental nature, the rectifiers will be subjected to a high probability of faults. The units must, therefore, be designed to not only handle normal fault conditions, but also the energy stored in the load coils. The prime protection for load faults will be provided by fault suppression techniques, where the thyristors shall be designed to withstand fault currents and turn off the rectifiers under load faults. The AC breaker between the generator and the rectifier will provide protection for a fault in the transformer or rectifier itself and be only a back up on a DC circuit fault.

The generators supplying the rectifiers will have relatively high inductance. Thus, there will be large variations of voltage at the AC input terminals of the rectifier. The rectifiers will not only be subject to the no-load to full-load regulation, but the pulsed generators will have overexcited fields. (So, in the cases where the generator voltages will be abnormally high.) The 13.8 KV voltage will go to the saturation voltage of the generator without resulting in a voltage breaking down the thyristors.

The high source impedance has the advantage that the fault currents will be low and thus, the coil and lead support mechanical requirements will be low. In addition, the volume and costs of thyristors needed to provide fault protection will be low.

The TF coils will need a forcing voltage to reach full current in the prescribed rise time, yet only need the IR drop during the flat top experimental time. The rectifiers will be phased back to provide the lower voltage, but this is accomplished only by producing a lower power factor. When the voltage required drops below the module voltage 4 series modules of 25%, one module will be allowed to free-wheel and only pass current but not provide input power or voltage. In this way the generator will operate at a higher power factor and it will be able to supply the 25% extra to other loads, such as the neutral beam system.

Ohmic Heating Rectifier

The OH system, consisting of a 12-pulsed 1.5 KV, 40 KA rectifier, provides the power for the plasma current and is also fed from the generators (ref. Fig. 5). It is envisaged to have the same features as described above for TF rectifier, except that the "free wheeling" may not be employed, but it will

This interruption of current requires 62 KV, 34 KA DC. This voltage is interrupting the current in the OH coil by high voltage DC breakers are not available as a production

The current in the coil is swinging in the negative direction and interrupted by the breakers. The rectifier output leads must be reversed to reverse the rectifier power again used to control the coil current. It is contemplated that thyristors and/or mechanical switches will be utilized to reverse the rectifier

After the reversal, the reverse voltage may be varied, as desired for the plasma control for the experiment (one second maximum at full current periods at lower currents).

Filters that may be connected to the circuit will be needed to provide reduction of ripple, particularly when the circuit is and disconnected when fast response is required of the system.

Both a positive and a negative crowbar or shorting switch will be required across the load coil to be used when plasma instabilities occur to prevent the dissipation of plasma energy into the vacuum tube wall. By shorting the circuit the energy can be dissipated in the crowbar circuit instead of the vacuum chamber. It is noted that this requirement will be met by frequent short circuits applied to the rectifier.

If the plasma current fails because the breakdown oscillator is not effective, then the OH coil energy will be fed into the commutating capacitors and result in an over voltage of the capacitors. To prevent damage to the capacitors a voltage protective crowbar will be used.

The rectifier bridge shall be such that AC and load transient plasma transients, will not result in thyristor damage.

EF Rectifier Circuit

The EF rectifier will be a thyristor-controlled rectifier with a current of 80 KA (Fig.6). This unit will provide the necessary vertical field required to keep the plasma current loop, at the center of the vacuum tube. When the current changes, the loop structure of the EF system must change to control

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To provide for the 150 to 300 volts around the major diameter of the TFTR Tokamak, required to start the build up of plasma current, the OH coil current is interrupted and the current commutated into a capacitor-resistor circuit which controls the maximum coil di/dt (maximum induced voltage) as well as the rise of plasma current.

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After the reversal, the rectifier voltage may be varied, as desired, to the plasma control for the experiment (one second maximum at full current a periods at lower currents).

Filters that may be connected in circuit will be needed to provide the reduction of ripple, particularly when opened and disconnected when fast response is required of the system.

Both a positive and a negative opening crowbar or shorting switch will be required across the load coil to be opened when plasma instabilities occur and prevent the dissipation of plasma energy into the vacuum tube wall. By shorting the OH circuit the energy can be dissipated in the OH circuit instead of the vacuum chamber. It is noted that this requirement will require frequent short circuits applied to the rectifier.

If the plasma current falls to zero because the breakdown oscillator is not effective, then the OH coil energy will be dissipated into the commutating capacitors and result in an over voltage of the capacitors. To prevent damage to the capacitors a voltage protective crowbar will be required.

The rectifier bridge shall be designed such that AC and load transients, as well as plasma transients, will not result in thyristor damage.

EF Rectifier Circuit

The EF rectifier will be a 12-pulsed thyristor-controlled rectifier rated at 12 KV and 80 KA (Fig.6). This unit will supply the necessary vertical field required to keep the plasma current loop, or ring, at the center of the vacuum tube. As the current changes, the loop stress changes and the EF system must change to create a confining force. For example, as the plasma current increases from some small value to the maximum value, the plasma loop will enlarge. The EF current must rise in proportion to the plasma current to maintain the plasma major diameter within the vacuum tube.

The EF rectifier will have the same requirements as explained in the OH circuit above, except it will not have interlocking and reversing switches.

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In the cases where full operation is required and the

controlled units. Because of load and its experimental conditions, the units will be subjected to a variety of faults. The units are designed to not only withstand these conditions, but also the high currents on the load coils. The prime concern is that faults will be provided on techniques, where the units are designed to withstand the high currents. The AC breaker between the rectifier will provide a back up in the transformer and be only a back up on

supplying the rectifiers with high inductance. Thus, the variations of voltage terminals of the rectifier will not only be subject to load regulation, but the units will have overexcited cases where the generated voltage is abnormally high. The units will go to the saturation region without resulting in a drop in the thyristors.

The impedance has the advantage that the currents will be low and the lead support mechanical stress will be low. In addition, the number of thyristors needed to handle the current will be low.

The units will need a forcing voltage to maintain the prescribed rise time in the IR drop during the initial time. The rectifiers are designed to provide the lower voltage drop is accomplished only by a high power factor. When the voltage drops below the module voltage, one module will be free-wheel and only pass the input power or the way the generator will operate at a power factor and it will require the 25% extra to other parts of the neutral beam system.

Operating Rectifier

The rectifier, consisting of a 12-pulsed thyristor-rectifier, provides the power to the load and is also fed from the AC source (Fig. 5). It is envisioned to have the same features as described for the other rectifier, except that the "free

This interruption of current requires a 31 to 62 KV, 34 KA DC. This voltage is produced by interrupting the current in the primary of the OH coil by high voltage DC breakers which are not available as a production item.

The current in the coil is allowed to swing in the negative direction after it is interrupted by the breakers. Then the rectifier output leads must be reversed and the rectifier power again used to control the coil current. It is contemplated that ignitrons and/or mechanical switches will be utilized to reverse the rectifier leads.

After the reversal, the rectifier voltage may be varied, as desired, to provide the plasma control for the experimental time (one second maximum at full current and longer periods at lower currents).

Filters that may be connected in the circuit will be needed to provide the reduction of ripple, particularly when operated and disconnected when fast response is required of the system.

Both a positive and a negative conducting crowbar or shorting switch will be required across the load coil to be operated when plasma instabilities occur and prevent the dissipation of plasma energy into the vacuum tube wall. By shorting the OH coil, the energy can be dissipated in the OH coil circuit instead of the vacuum chamber. It is noted that this requirement will result in frequent short circuits applied to the OH rectifier.

If the plasma current fails to build up because the breakdown oscillator is not effective, then the OH coil energy will dump into the commutating capacitors and could result in an over voltage of the capacitors. To prevent damage to the capacitors an over voltage protective crowbar will be required.

The rectifier bridge shall be protected such that AC and load transients, as well as plasma transients, will not result in thyristor damage.

EF Rectifier Circuit

The EF rectifier will be a 12-pulse thyristor-controlled rectifier rated 3.KV and 80 KA (Fig.6). This unit will supply the necessary vertical field required to keep the plasma current loop, or ring, in the center of the vacuum tube. As the plasma current changes, the loop stress changes and

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There will be bias, or correction fields, required to assure that the initial plasma current occurs at the desired location within the vacuum chamber. There may be separate supplies for both vertical and horizontal fields, but the SF system may be utilized to provide the vertical bias.

To provide plasma compression, where the major diameter of the plasmas loop is decreased, the EF field is increased by adding a pulsed current into the EF coils. This is supplied by switching in a 7.5 megajoule capacitor bank in series with the EF rectifier.

As previously noted, the rectifier must be designed for repeated crowbars or shorts with fault suppression protection and it must be self-protected against damage due to any transient voltage, including positive and negative plasma induced voltages.

Neutral Beam Supply

This system is the one which has the greatest number of unknowns. At the present time the design calls for 4 diode rectifier units feeding 12 sources, with a maximum voltage of 120 KV and supplying 90 amperes for each source. It is envisioned that each source will be supplied through 120 KV series modulators to provide the voltage regulation at $\pm 1\%$. Consideration is also being given to provide phase-controlled ignitron rectifiers with crowbars as the primary protective feature, and shunt regulators.

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The sources will all need conditioning, or rapid pulsing, before being used as injectors into TFTR and, hence, they shall be operable either from the MG sets or directly off the 60 Hz AC distribution system, independent of the other 3 major loads on the generator.

The regulation on fault protection for this equipment has not been clearly established. If the modulator tube is developed to provide primary protection for the load (neutral beam injectors), then crowbars will provide the back up protection for the load

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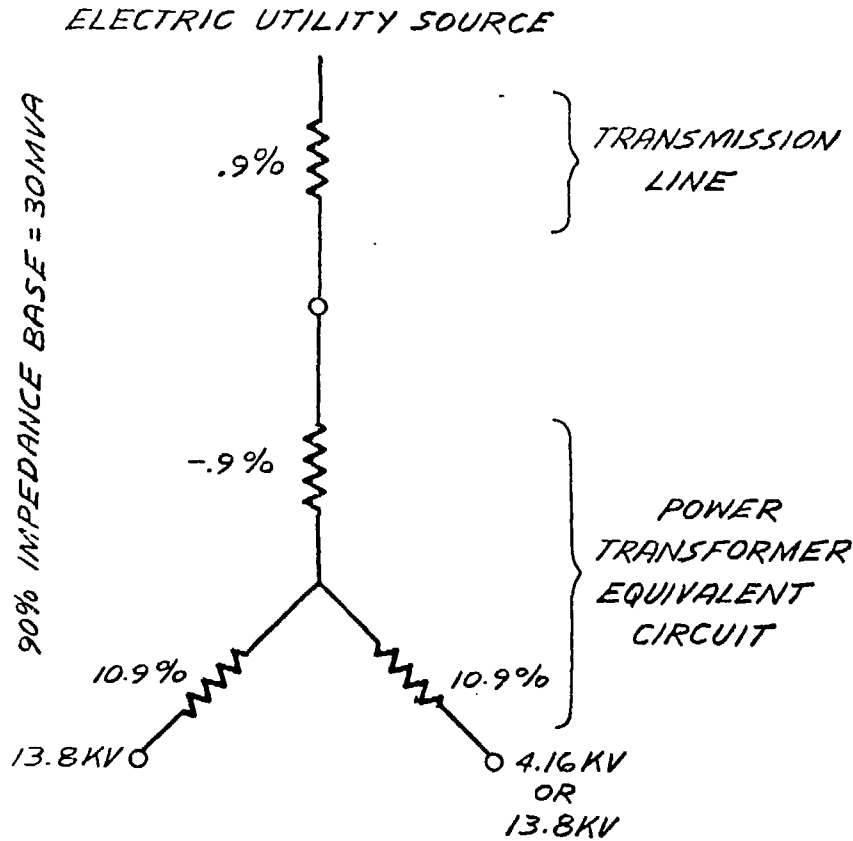
The regulation on fault protection for this equipment has not been clearly established. If the modulator tube is developed to provide primary protection for the load (neutral beam injectors), then crowbars will provide the back up protection for the load and primary protection for the modulators. In any event, the rectifier will have to be designed to withstand frequent short circuits

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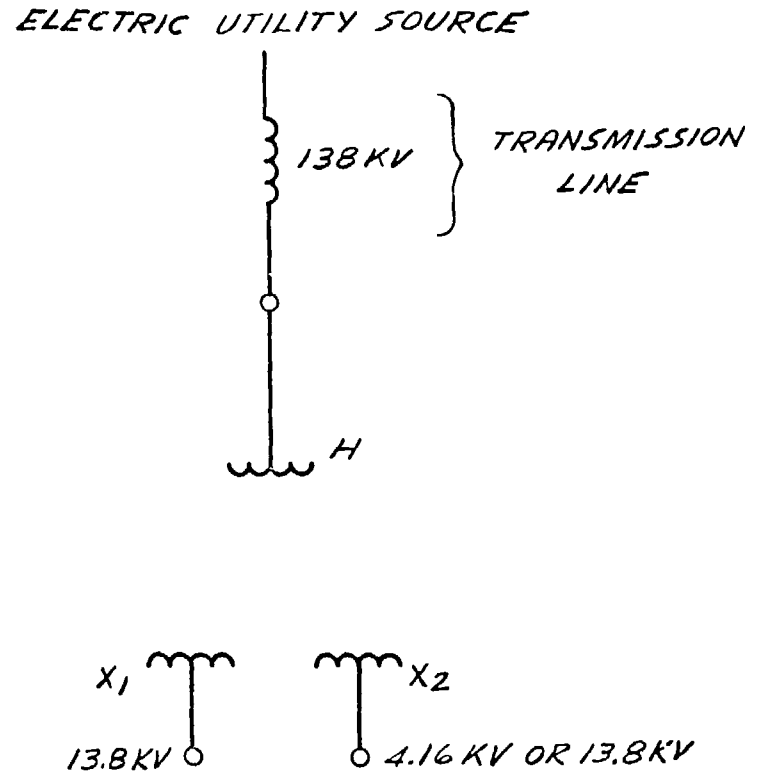
If phase-controlled rectifiers are not employed, then high speed interrupters (breakers) will be necessary.

CAPTIONS:

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|--------|-----------------------|
| Fig. 1 | Impedance Diagram |
| Fig. 2 | Load Diagram |
| Fig. 3 | Harmonic Content |
| Fig. 4 | Symbolic TF Rectifier |
| Fig. 5 | Symbolic OH Circuit |
| Fig. 6 | Symbolic EF Circuit |



EQUIVALENT WYE REACTANCE
FOR 3 WINDING TRANSFORMER



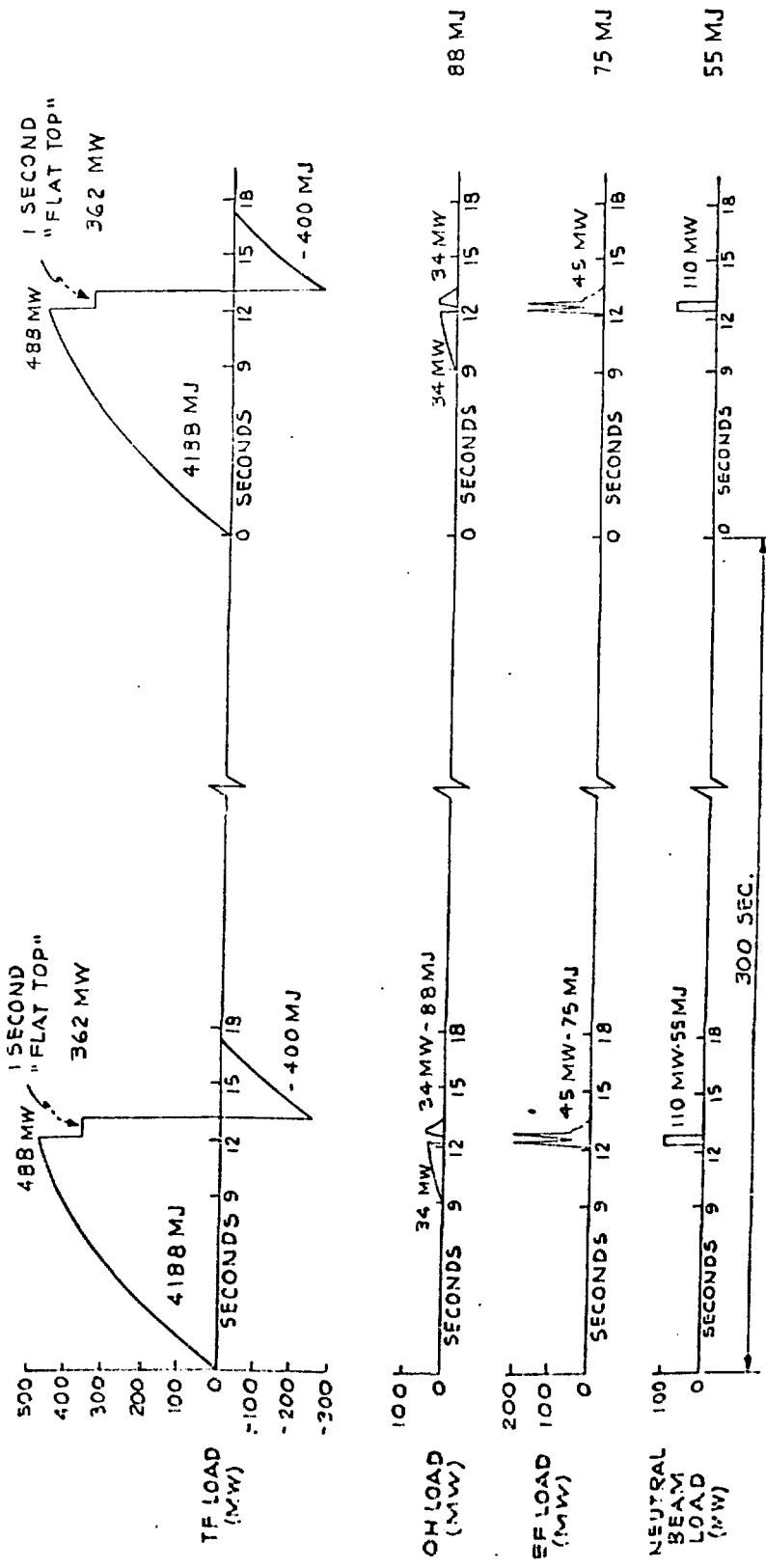
$$X_H - X_1 = +10\%$$

$$X_H - X_2 = +10\%$$

$$X_1 - X_2 = +21.8\%$$

REACTANCE
FOR 3 WINDING TRANSFORMER

FIG. 1



~~FOR BEAM POWER TO MW~~
 FLYWHEELS = 4500 MJ

FIG 2

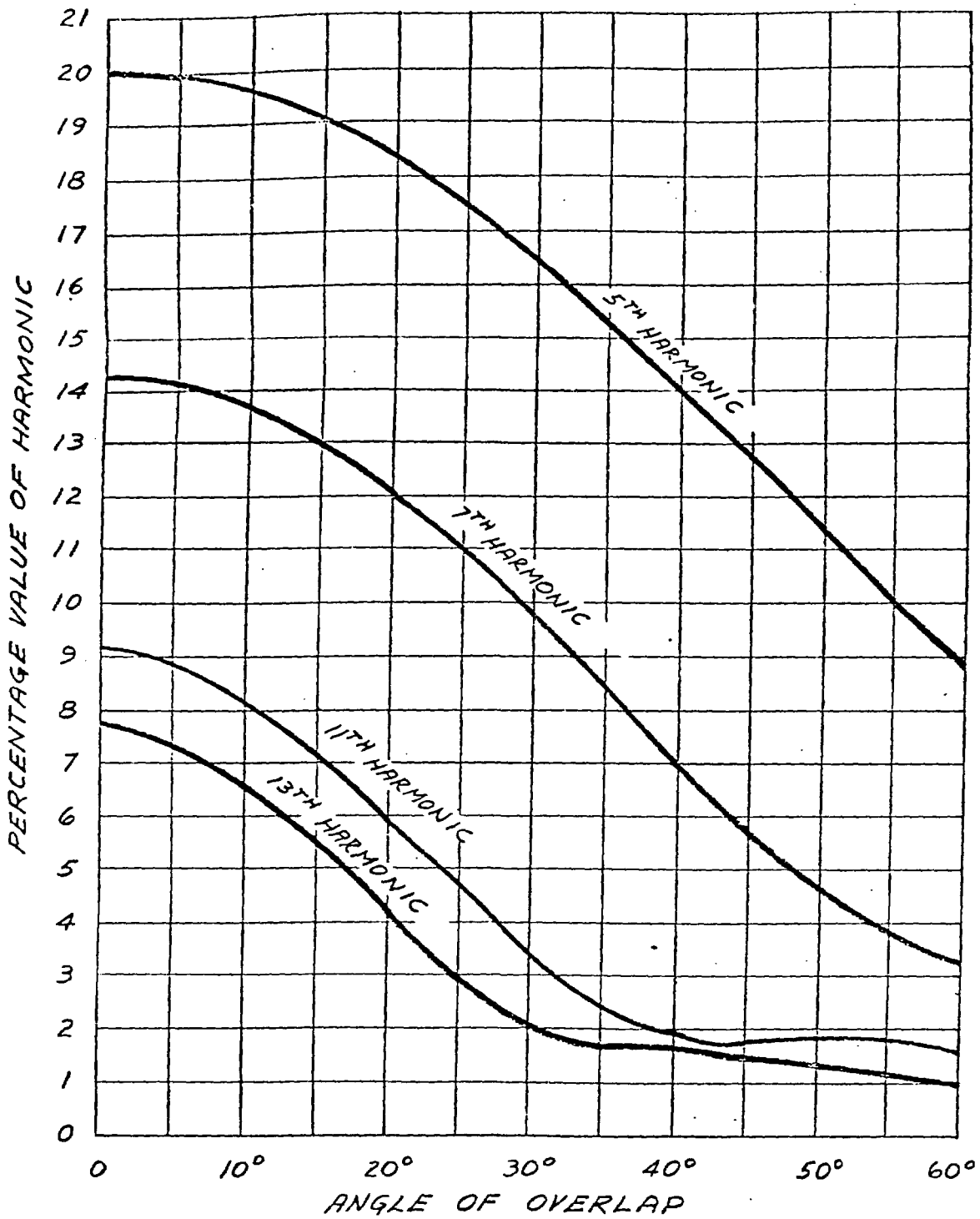


FIG. 3

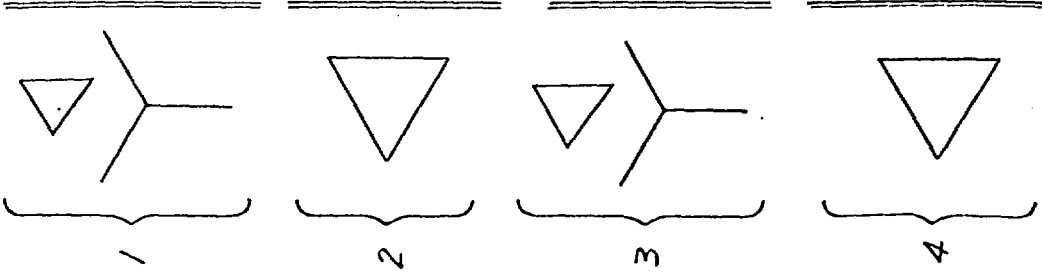
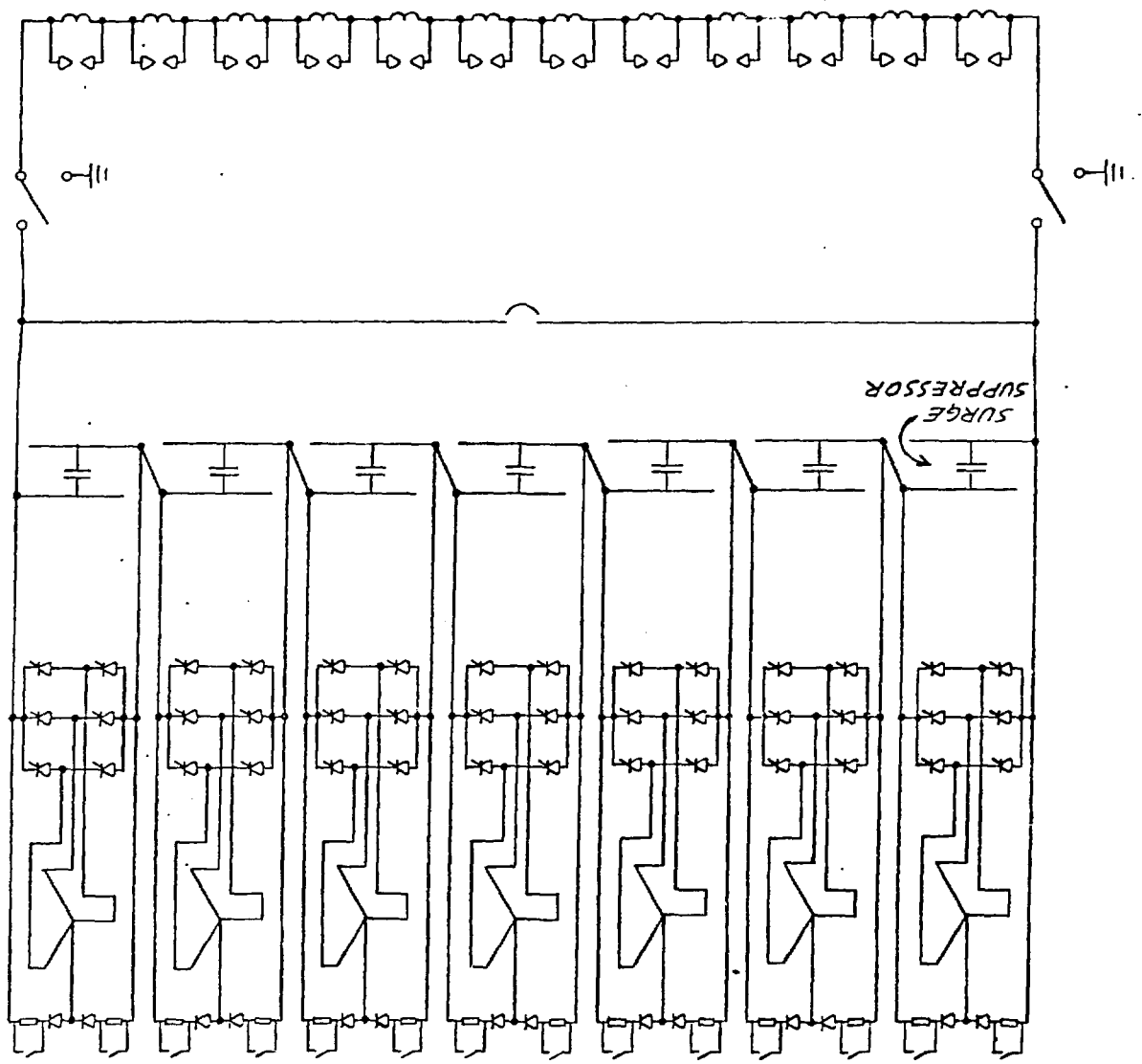


FIG. 4

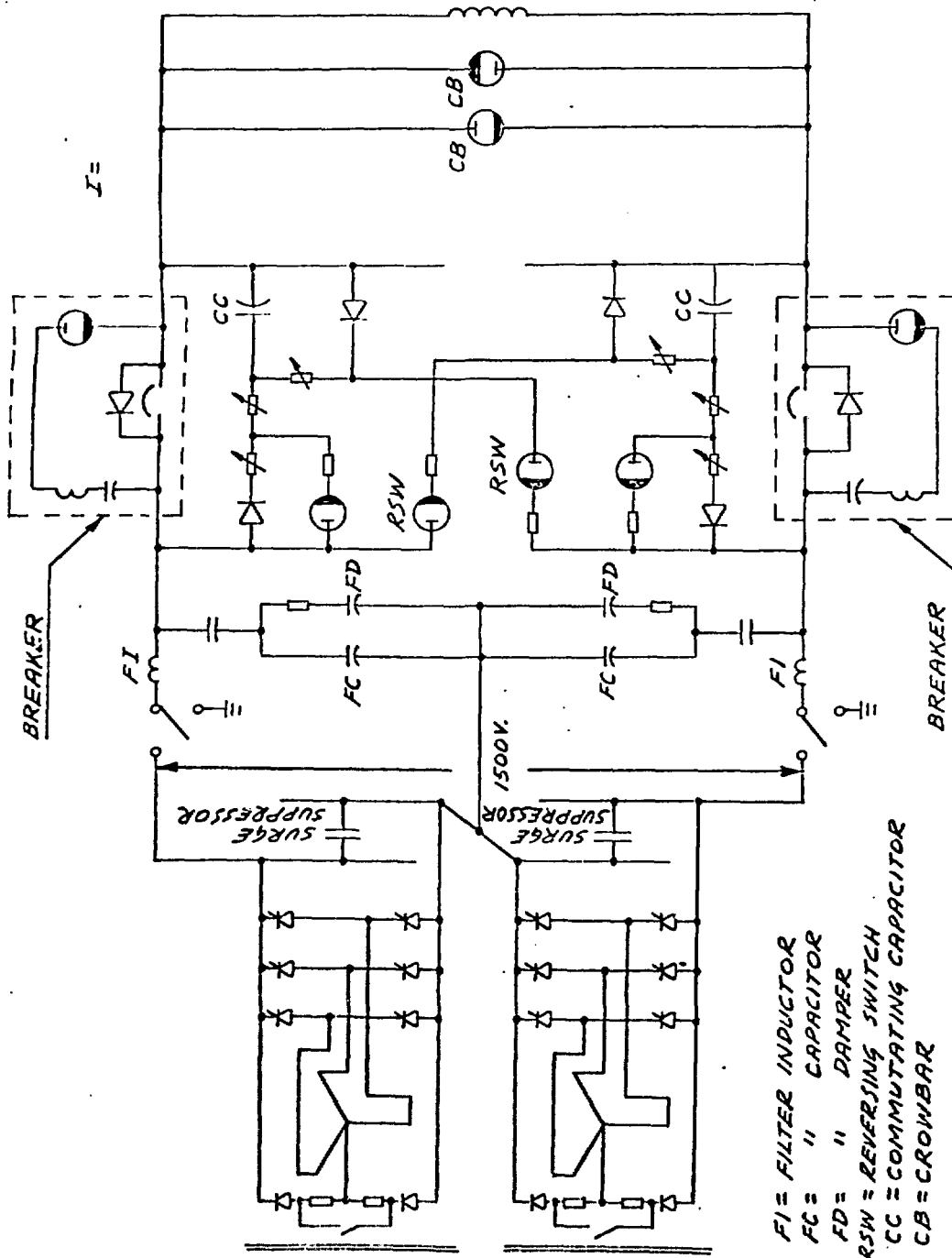
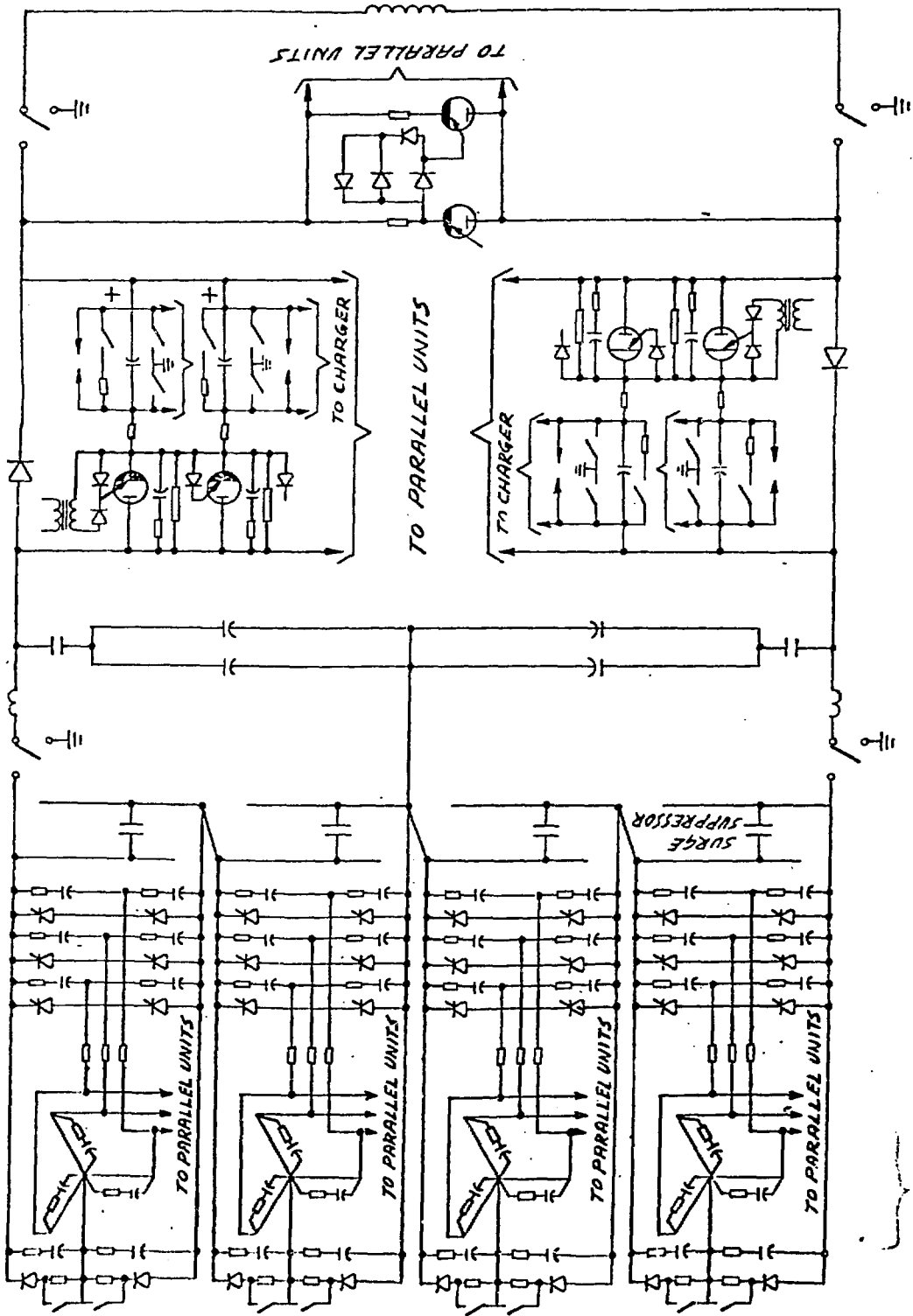


FIG. 5



E. F. CIRCUIT

TRANS. SECTION