# Voltage-Probe-Position Dependence and Magnetic-Flux Contribution to the Measured Voltage in ac Transport Measurements: <br> Which Measuring Circuit Determines the Real Losses? 

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#### Abstract

The voltage $V_{\mathrm{s} b}$ measured between two voltage taps $a$ and $b$ during magnetic flux transport in a type-II superconductor carrying current $I$ is the sum of two contributions, the line integral from $a$ to $b$ of the electric field along an arlitrary path $C_{s}^{\prime}$ through the superconductior and a term proportional to the time rate of change of magnetic flux through the area bounded by the path $C_{8}$ and the measuring circuit leads. When the current $I(t)$ is oscillating with time $t$, the apparent ac loss (the time average of the product $I V_{a b}$ ) depends upon the measuring circuit used. Only when the measuring-circuit leads are brought out far from the surface does the apparent power dissipation approach the real (or true) ac loss associated with the lengith of sample probed. Calculations showing comparisons between the apparent and real ac losses in a flat strip of rectangular cross section will be presented, showing the behavior as a function of the measuring-circuit dimensions. Corresponding calculations also are presented for a sample of elliptical cross section.


## 1 Introduction

As high-temperature superconducting materials move closer to large-scale e-lectric-power applications, it is increasingly important to understand the magnitude and origin of the ac losses in these materials. Ideally, measurements of such losses should be carried out under experimental conditions close to those of the proposed applications. For example, for testing materials intended for use in ac power transmission cables, it is preferable that the ac losses be measured while the conductor is carrying an applied ac transport current.

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In measuring the low-frequency ac losses of normal metals, it is safe to use the simple procedure of (a) applying an ac current $I(t)=I_{0} \cos \omega t$, (b) using a high-impedance voltmeter to measure the corresponding voltage $V(t)$ between a pair of voltage taps across a representative segment of the conductor, and (c) obtaining the average rate of power dissipation from $P=\left\langle I(t) \mathrm{F}^{\mathrm{F}}(t)\right\rangle$, where the brackets denote the time average. It is at first surprising to learn that when the sample is a type-II superconducting tape or strip, this simple method runs into serious difficulties: The apparent rate of power dissipation $P_{\text {app }}$ so obtained depends on where the voltage taps are placed on the tape (along an edge or along the centerline) and on how far away from the tape the voltage leads are extended before they are brought together, twisted, and led out to the volimeter ([1].[2],[3]).

As emphasized by Camplell ([4]), to explain these results it is important to account for the fact that when low-resistance leads are atiached at contact. points $a$ and $b$ on the conductor, the time-clependent voltage $V_{a b}$ measured by a high-impedance voltmeter is the sum of an electric-field inlegral term and a magnetic-flux term. As shown in Refs. ([5][6][ 7$]$ ), this voltage is

$$
\begin{equation*}
\mathrm{r}_{\mathrm{ab}}=\int_{a}^{b} E \cdot d l-\frac{d}{d t} \Phi_{\mathrm{sm}} \tag{1}
\end{equation*}
$$

where the line integral is to be carried out from $a$ to $b$ along a path $C_{\text {s }}$ through the conductor, and $\Phi_{\mathrm{sm}}$ is the magnetic flux up through the loop bounded by the path $C_{s}$ and the measuring circuit leads (which define the contour $C_{\mathrm{m}}$ ). It can be shown with the help of Faraday's law that the voltage $V_{\text {ab }}$ is independent. of the contour $C_{s}$, because any change in the first term on the right-hand side of Eq. (1) is compensated by a canceling change in the second term. It often is convenient to chose the contour $C$;s so that the first term is zero.

Because of magnetic hysteresis, the flux term, i.e., the second term on the right-hand side of Eq. (1), has terms in strip geometry that are both in phase and out of phase with the current $I(t)$. Only for normal-metal wires in which the current density is uniform and for superconducting wires that have circular cross section does the contribution to the flux term from magnetic fields outside the sample have a vanishing in-phase component. As pointed out by Camplell ([4]), in general only when the leads are brought out to a large distance before bringing them together does the measurement give the true loss, i.e., the dissipated power delivered by the power supply to the segment between $a$ and $b$. Since the true loss involves the voltage measured across the terminals of the power supply, the flux $\Phi_{\text {sm }}$ involved in Eq. (1) is the t.otal flux through the area bounded by the contour $C_{\text {s }}$ along the the sample of interest and the contour $C_{\mathrm{m}}$ along the leads that connect the sample to the power supply.

In Sec. 2, we present the details of how to calculate the measured timedependent voltage $F^{-}(t)$ generated by hysteretic losses in a flat strip of rectangular cross section carrying an alternating current $I(t)$. We show how the apparent. loss depends upon the measuring circuit geometry and examine the conditions under which the apparent loss is a good approximation to the true loss. We also
present the corresponding results for a sample of elliptical cross section. In Sec. 3, we briefly summarize our results.

## 2 Theoretical Approach and Results

Consider a type-II superconducting strip of width $2 W$ and thickness $d \ll 2 \mid V$ in the $x y$ plane, centered on the $y$ axis, as shown in Fig. 1, such that the elges are at $x= \pm I V$. Assume that the London penetration depth $\lambda$ is less than the sample thickness. Suppose that an alternating current $I_{y}(t)=I_{0} \cos \omega t$ is applied. A corresponding self-field, which wraps around the sample, will be produced. If the current amplitude is very tiny, the magnitude of the field at the sample edges will be less than the lower critical field $H_{c 1}$ and thus will be too small to cause any vortices to penetrate into the sample. However, we are most interested in the case for which the current amplitude $J_{0}$ is substamial, such that vortices or antivortices are nucleated at the edges and driven into the sample during each half cycle.


Fig. 1. Sketch of slip geometry considered in this paper. The properties of long current-carrying type-1I superconductors of width 2IF and thickness $d<215$ are examined.

To calculate the hysteretic losses under such circumstances, we use the critical state model, which is characterized by a critical depinning current density $J_{c}$.

We assume for simplicity in this paper that $J_{c}$ is independent of the flux density $\boldsymbol{B}$. We also assume that over most of the vortex-filled region, the local field is sufficiently large by comparison with $H_{c 1}$ that we may take $B=\mu_{0} H$ to good approximation. At each value of the current $I_{y}(t)$ (assuming that the current amplitude $I_{0}$ is less than the critical current $\left.I_{c}=21 W d J_{c}\right)$, the quasistatic profiles of the current density $J_{y}(x, t)$ (averaged across the sample thichness) and the magnetic flux density $B(x, z, t)$ may be calculated using the Norris method [8] as described in detail in Refs. [9] and [10].

When the current $I_{y}(t)$ is equal to $I_{0}$, magnetic flux penetrates from both edges to the coordinates $x= \pm a_{0}$, where $a_{0}=W \sqrt{1-\left(I_{0} / I_{c}\right)^{2}}$, but $B_{z}(x, 0,1)$ remains zero in the umpenetrated region $|x|<a_{0}$. The current density $J_{y}$ in the strip is given by

$$
J_{y}\left(x ; a_{0}\right)= \begin{cases}\frac{2}{\pi} J_{c} \arctan \sqrt{\frac{w^{2} \cdot 2}{} a_{0}^{2}-x_{0}^{2}}, & |x|<a_{0}  \tag{2}\\ J_{c}, & a_{0}<|x|<I^{r}\end{cases}
$$

As $I_{y}(t)$ decreases, however, new flux fronts move in from both edges. The current density in each of these new regions has magnitude $J_{c}$, but it is reversed in direction. Let $x= \pm a(t)$ denote the time-dependent coordinates of these incoming flux fronts. As shown in Refs. [9] and [10], the current density in the strip can be expressed as the superposition of two distributions,

$$
\begin{equation*}
J_{y}(x, t)=J_{y}\left(2 ; a_{0}\right)-2 J_{y}(2 ; a) \tag{3}
\end{equation*}
$$

where the function $J_{y}(x: a)$ is defined in Eq. (2), $a(t)=W \sqrt{1-\left(I_{\mathrm{a}} / I_{c}\right)^{2}}$, and $I_{3}=\left[I_{0}-I_{y}(t)\right] / 2$. Note that $a(t)=W$ when $I_{y}(t)=I_{0}$, and $a(t)=a_{0}$ when $I_{5}(t)=-I_{0}$.

From the Biot-Savart law, it follows that the magnetic flux density $B(x,=, t)$ in the vicinity of the strip also can be written as the superposition of two fields,

$$
\begin{equation*}
B(x, z, t)=B\left(x, z ; a_{0}\right)-2 B(x, z ; a) \tag{4}
\end{equation*}
$$

where $B\left(x, z ; a_{0}\right)$ is the magnetic flux density generated by the current density given in Eq. (2). Of the two terms on the right-hand side of Eq. (4), the first is independent of $t$, while the second one depends upon $t$ via the coordinate $a(t)$.

Having briefly discussed how to calculate the time-dependent magnetic flux density in the strip, we now turn to the problem of calculating the apparent and real rates of power dissipation. It is well known that the rate of power dissipation for hysteretic losses is linear in frequency, since there is a fixed amount. of energy dissipated each cycle. We thus calculate the apparent and real loss per cycle per unit. length of the strip. For simplicity, we consider two special circuit. configurations:
Perpeidicular case (Fig. 2). Here the voltage taps are placed along the centerline of the strip ( $x=0, z=d / 2$ ), and the leads extend perpendicular to the surface to a height $=$ before they are brought together, twisted, and led out to the voltmeter.

Parallel case (Fig. 3). Here the voltage taps are placed along the edge of the strip $(z=W, z=0)$, and the leads lie in the plane of the strip but extend perpendicular to the edge to the coordinate $x>W$ before they are brought. together, twisted, and led out to the voltmeter.
The measured voltage for both cases is determined by Eq. (1), where the contours $C_{\mathrm{s}}^{\prime}$ extend along the line $x=z=0$ except for segments that extend perpendicular to this line out to the voltage taps, as shown by the dotted lines in Figs. 2 and 3. It can be shown that the line integrals of the electric field [the first t.erm of Eq. (1)] vanish for these choices of $C_{s}$. To calculate the voltage $V_{\mathrm{ab}}(t)$ for these cases, we therefore need only to calculate the time derivative of the magnetic flux through the shaded areas in the measuring circuits sketched in Figs. 2 and 3. The time derivative of the magnetic flux is obtained by first using the BiotSavart law to express the magnetic field in terms of $J_{y}(x, t)$, as sketched in Eq. (4), and by taking the time derivative of the resulting expression using Eq. (3) and the comection between $a(t)$ and $I_{y}(t)$. The apparent loss per cycle per unit. leng(h is then obtained by evaluating $\int I_{y}(t) V_{\mathrm{ab}}(t) d t$ over one period $(2 \pi / \omega)$, where $V_{\mathrm{ab}}(t)$ is the voltage across unit leng(th of the sample.

The apparent loss per cycle per unit length for the strip in the perpendicular case is

$$
\begin{aligned}
& L_{\perp}(F)=\left(\frac{\mu_{0} I_{c}^{2}}{\pi}\right) \times \\
& {\left[2 ( \frac { z } { W } ) \left(\sqrt{\left(\frac{z}{W}\right)^{2}+1}-\sqrt{\left(\frac{z}{W}\right)^{2}+1-F^{2}}{ }^{\prime}\right.\right.} \\
& \left.-F \arctan \left(\frac{F}{\sqrt{\left(\frac{\dot{W}}{W}\right)^{2}+1-F^{2}}}\right)\right) \\
& -\frac{F^{2}}{2} \log \left(\frac{\sqrt{1-F^{2}}\left(\left(\frac{\dot{\rightharpoonup}}{\bar{W}}\right)+\sqrt{\left(\frac{\dot{\rightharpoonup}}{\bar{W}}\right)^{2}+1}\right)}{\left(\frac{\dot{\rightharpoonup}}{\bar{W}^{2}}\right)+\sqrt{\left(\frac{\dot{W}}{W}\right)^{2}+1-F^{2}}}\right)
\end{aligned}
$$

where $F=I_{0} / I_{c}, I_{c}=2 W d J_{c}$, and the thickness $d$ of the strip is ignored relative to the widtly 2 V . Note that the apparent loss is zero when the leads are brought together at the height $==0$. The reason for this is that both terms on the righthand side of Eq. (1) are then zero.


Fig. 2. The perpendicular case: Measuring-circuit leads extend to a height $=$ above the sample.


Fig. 3. The parallel case: Measuring-circuit. leads extend to the coordinate $x>W$.

Similarly, the apparent loss per cycle per unit length for the strip in the parallel case is

$$
\begin{align*}
& L_{\|}(F)=\left(\frac{\mu_{0} I_{c}^{2}}{\pi}\right) \times \\
& {\left[2 ( \frac { x } { W } ) \left(\sqrt{\left(\frac{x}{W}\right)^{2}-1+F^{2}}-\sqrt{\left(\frac{x}{W V}\right)^{2}-1}\right.\right.} \\
& \left.-F \log \left(\frac{\sqrt{\left(\frac{x}{W^{W}}\right)^{2}-1}}{\sqrt{\left(\frac{x}{(W)}\right)^{2}-1+F^{2}}-F}\right)\right) \\
& -\frac{F^{2}}{2} \log \left(\frac{\sqrt{1-F^{2}}\left(\left(\frac{x}{W}\right)+\sqrt{\left(\frac{x}{W^{W}}\right)^{2}-1}\right)}{\left(\frac{x}{W^{2}}\right)+\sqrt{\left(\frac{x}{W}\right)^{2}-1+F^{2}}}\right) \\
& -\left(1-\frac{F}{2}\right)^{2} \log \left(\frac{\left(\frac{x}{W^{*}}\right)^{2}-1+\left(\frac{x}{W^{2}}\right) \sqrt{\left(\frac{x}{W^{\prime}}\right)^{2}-1+F^{2}}+F}{(1-F) \sqrt{\left(\frac{x}{W}\right)^{2}-1}\left(\left(\frac{x}{W^{W}}\right)+\sqrt{\left(\frac{x}{W}\right)^{2}-1}\right)}\right) \\
& \left.-\left(1+\frac{F}{2}\right)^{2} \log \left(\frac{\left(\frac{x}{W}\right)^{2}-1+\left(\frac{x}{W^{W}}\right) \sqrt{\left(\frac{\dot{H}}{W}\right)^{2}-1+F^{2}}-F}{(1+F) \sqrt{\left(\frac{x}{W}\right)^{2}-1}\left(\left(\frac{x}{W}\right)+\sqrt{\left(\frac{x}{W}\right)^{2}-1}\right)}\right)\right] \text {. } \tag{6}
\end{align*}
$$

Figure 4 shows plots of the apparent loss per cycle per unit lenglh in both the perpendicular and parallel cases for strip geometry versus $F=I_{0} / I_{c}$ on a semilogarithmic scale. Shown for comparison is the real (or true loss) per cycle per unit lenglh for strip geometry (solid curve) [ 8$]$,

$$
\begin{equation*}
L_{0}(F)=\left(\frac{\mu_{0} I_{\mathrm{c}}^{2}}{\pi}\right)\left[(1-F) \log (1-F)+(1+F) \log (1+F)-F^{2}\right] . \tag{i}
\end{equation*}
$$

Note that $L_{0} \propto F^{4}$ for small $F \ll 1$. We see that the apparent losses $L_{\perp}$ and $L_{\|}$ agree with $L_{0}$ within about $1 \%$ when $z / W>3$ or $x / W>3$. For large values of $=/ W$ and $x / W$, the following expansions are useful:

$$
\begin{align*}
L_{\perp}(F)= & L_{0}(F)+ \\
& \left(\frac{\mu_{0} I_{c}^{2}}{\pi}\right)\left[-\frac{F^{4}}{12\left(\frac{\frac{\varepsilon}{W}}{W}\right)^{2}}+\frac{F^{4}\left(\frac{1}{2}-\frac{F^{2}}{5}\right)}{8\left(\frac{\frac{\varepsilon}{W}}{4}\right)^{4}}+O\left(\frac{1}{\left(\frac{\frac{\varepsilon}{W}}{W}\right)^{6}}\right)\right], \\
L_{\|}(F)= & L_{0}(F)+ \\
& \left(\frac{\mu_{0} I_{c}^{2}}{\pi}\right)\left[\frac{F^{4}}{12\left(\frac{x}{W}\right)^{2}}+\frac{F^{4}\left(\frac{1}{2}-\frac{F^{2}}{5}\right)}{8\left(\frac{x}{W}\right)^{4}}+O\left(\frac{1}{\left(\frac{T}{W}\right)^{6}}\right)\right] . \tag{9}
\end{align*}
$$



Fig. 4. Apparent loss per cycle per unit lengih (in units of $\mu_{0} I_{c}^{2} / \pi$ ) for a strip of width $21 \%$ and thickness $d$, calculated as described in the text for parallel (dot-dashed curves) and perpendicular geometry (dashed curves). The real loss, representing the actual power dissipation made up by the power supply is shown by the solid curve [8].

For samples of elliptical cross section, the apparent loss per cycle per unit length can be calculated by a procedure very similar to that described above, except that the current density and magnetic fields are those found in Ref. [ 8$]$. We consider the elliptical cross section to be characterized by a semimajor axis IF and semiminor axis $d / 2$, such that the widh of the sample is $2 W$ and the thickness at the thickest point is $d$. The critical current is thus $I_{\mathrm{c}}=(\pi / 2) \| d J_{\mathrm{c}}$,
and the ratio of the semiminor axis to the semimajor axis is $a=d / 2 W$. The results are, for the perpendicular case,

$$
\begin{aligned}
& L_{\perp}(F)=\left(\frac{\mu_{0} I_{c}^{2}}{\pi}\right) \times \\
& {\left[\frac { 2 ( \frac { \tilde { \partial } } { a } ) } { 3 ( 1 - a ^ { 2 } ) ^ { 2 } } \left(\left(2\left(\frac{\tilde{F}}{W}\right)^{2}-(3 F-5)\left(1-a^{2}\right)\right) \sqrt{\left(\frac{\tilde{F}}{W}\right)^{2}+\left(1-a^{2}\right)}\right.\right.} \\
& \left.-\left(2\left(\frac{\tilde{W}}{\mathbb{W}}\right)^{2}-(2 F-5)\left(1-\alpha^{2}\right)\right) \sqrt{\left(\frac{\tilde{W}}{W}\right)^{2}+(1-F)\left(1-a^{2}\right)}\right)
\end{aligned}
$$

and, for the parallel case,

$$
\begin{align*}
& L_{\|}(F)=\left(\frac{\mu_{0} I_{c}^{2}}{\pi}\right) \times \\
& {\left[\frac { 2 ( \frac { x } { W } ) } { 3 ( 1 - a ^ { 2 } ) ^ { 2 } } \left(\left(2\left(\frac{x}{W}\right)^{2}+(3 F-5)\left(1-\alpha^{2}\right)\right) \sqrt{\left(\frac{x}{W}\right)^{2}-\left(1-a^{2}\right)}\right.\right.} \\
& \left.-\left(2\left(\frac{x}{W}\right)^{2}+(2 F-5)\left(1-a^{2}\right)\right) \sqrt{\left(\frac{x}{W^{7}}\right)^{2}-(1-F)\left(1-a^{2}\right)}\right) \\
& -\frac{F^{2}}{2} \log \left(\frac{\sqrt{1-F}\left(\left(\frac{x}{\left(\frac{x}{W}\right)}+\sqrt{\left(\frac{\frac{2}{W}}{W}\right)^{2}-\left(1-a^{2}\right)}\right)\right.}{\left(\frac{x}{W}\right)+\sqrt{\left(\frac{x}{W}\right)^{2}-(1-F)\left(1-a^{2}\right)}}\right) \\
& -\left(1-\frac{F}{2}\right)^{2} \log \left(\frac{\left(\frac{x}{W^{W}}\right)-\sqrt{\left(\frac{x}{W}\right)^{2}-\left(1-\alpha^{2}\right)}}{\left(\frac{x}{W^{\prime}}\right)+\sqrt{\left(\frac{x}{W}\right)^{2}-\left(1-\alpha^{2}\right)}}\right) \\
& \left.-\left(1-\frac{F}{2}\right)^{2} \log \left(\frac{\left(\frac{x}{W}\right)+\sqrt{\left(\frac{x}{W^{2}}\right)^{2}-(1-F)\left(1-a^{2}\right)}}{\left(\frac{x}{W}\right)-\sqrt{\left(\frac{x}{W}\right)^{2}-(1-F)\left(1-a^{2}\right)}}\right)\right] . \tag{11}
\end{align*}
$$

Figure 5 shows plots of the apparent loss per cycle per unit length in both the perpendicular and parallel cases for elliptical cross sections versus $F=I_{0} / I_{c}$ on a semilogarithmic scale. Shown for comparison is the real (or true loss) per cycle per unit leng(h) for elliptical cross sections (solid curve) [8],

$$
\begin{equation*}
L_{0}(F)=\left(\frac{\mu_{0} I_{c}^{2}}{\pi}\right)\left[(1-F) \log (1-F)+(2-F) \frac{F}{2}\right] . \tag{12}
\end{equation*}
$$

Note that $L_{0} \propto F^{3}$ for small $F \ll 1$. We find that the apparent losses $L_{\perp}$ and $L_{\|}$ agree with $L_{0}$ wilhin about. $1 \%$ when $=/ W>3$ or $x / W>3$. For large values of $=/ W$ and $x / W$, the following expansions for elliptical cross sections are useful:

$$
\begin{align*}
L_{\perp}(F)= & L_{0}(F)+ \\
& \left(\frac{\mu_{0} I_{c}^{2}}{\pi}\right)\left[-\frac{\left(1-\alpha^{2}\right) F^{3}}{12\left(\frac{\dot{W}}{W}\right)^{2}}+\frac{\left(1-\alpha^{2}\right)^{2}(2-F) F^{3}}{32\left(\frac{\dot{\hbar}}{W}\right)^{4}}+O\left(\frac{1}{\left(\frac{\hbar}{W}\right)^{6}}\right)\right], \tag{13}
\end{align*}
$$

$$
\begin{align*}
L_{\|}(F)= & L_{0}(F)+ \\
& \left(\frac{\mu_{0} I_{c}^{2}}{\pi}\right)\left[\frac{\left(1-\alpha^{2}\right) F^{3}}{12\left(\frac{x}{W^{W}}\right)^{2}}+\frac{\left(1-\alpha^{2}\right)^{2}(2-F) F^{3}}{32\left(\frac{x}{W^{6}}\right)^{4}}+O\left(\frac{1}{\left(\frac{x}{W^{6}}\right)^{5}}\right)\right] . \tag{14}
\end{align*}
$$

Note that for both the strip geometry and elliptical cross sections the apparent. loss in the parallel geometry is an overestimate of the true loss, but the apparent loss in the perpendicular geometry is an underestimate. The predicted behavior has been confirmed, at least qualitatively by Fleshler et al. [11][12].

The above calculations have been carried out for monolithic type-li superconducting strips of rectangular or elliptical cross section, in which the critical depinning current density is $J_{c}$. Our calculations also should apply, with minor modifications, to strip-like composite conductors contaiming a uniform density (volume fraction $f_{5}$ ) of untwisted superconducting filaments (each filament characterized by $J_{c}$ ) embedded in a normal-metal matrix. It can be shown that application of a current to such a composite conductor induces a current that flows initially with highest density in the filaments near the edge. Only when the current density in the outermost filaments exceeds $J_{c}$ does current transfer to filaments farther from the edge, thereby permiting magnetic flux to peneirate more deeply into the composite conductor. Under the application of an ac current, the penetration of magnetic flux into composites is thus very similar to that into monolithic superconductors. The maximum supercurrent density, averaged over the composite's total cross section, is the engineering critical current. density, $J_{e}=f_{s} J_{c}$. To describe losses of multifilamentary composite conductors using Eqs. (5)-(14), one must therefore replace $J_{c}$ by $J_{e}=f_{s} J_{c}$ and $I_{c}$ by $I_{\mathrm{c}}=2 W d J_{\mathrm{e}}$ for rectangular cross section or $\dot{I}_{\mathrm{c}}=(\pi / 2) W d J_{\mathrm{e}}$ for elliptical cross section.


Fig. 5. Apparent. Joss per cycle per unit. length (in units of $\mu_{0} I_{c}^{2} / \pi$ ) for a sample of elliptical cross section ( $\alpha-0$ ), calculated as described in the text for parallel (dotdashed curves) and perpendicular geometry (dashed curves). The real loss, representing the actual power dissipation made up by the power supply is shown by the solid curve [8].

## 3 Summary and Acknowledgments

In i.his paper we have theoretically studied the hysteretic ac transport losses of lype-lI superconclucting strips of rectangular and elliptical cross section carrying an ac current. Our theory shows that the apparent loss per cycle per unit length
depends both upon the placement of the voltage contacts on the surface of the superconductor and upon the arrangement of the measuring circuit leads as they are brought away from the sample before being twisted and led out too the volmeter. Our results show that the apparent loss per cycle is underestimatied in the perpendicular arrangement sketched in Fig. 2 but is overestimated in the parallel arrangement sketched in Fig. 3. We have presented several expressions that can be used to determine the amount by which the apparent loss per cycle for a given measuring circuit configuration differs from the true loss per cycle.

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