# Diameter of Polyhedra: Limits of Abstraction 

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#### Abstract

We investigate the diameter of a natural abstraction of the 1 -skeleton of polyhedra. Even if this abstraction is more general than other abstractions previously studied in the literature, known upper bounds on the diameter of polyhedra continue to hold here. On the other hand, we show that this abstraction has its limits by providing an almost quadratic lower bound.


One of the most prominent mysteries in convex geometry is the question whether the diameter of polyhedra is polynomial in the number of its facets or not. If the largest diameter of a $d$-dimensional polyhedron with $n$ facets is denoted by $\triangle_{u}(d, n)$, then the best known lower and upper bounds are $n-d+\lfloor d / 5\rfloor \leq \triangle_{u}(d, n) \leq n^{1+\log d}$, shown by Klee and Walkup [15] and Kalai and Kleitman [13] respectively. The gap which is left open here is huge, even after decades of intensive research on this problem.

Interestingly, the above upper bound holds also for simple combinatorial abstractions of polyhedra by which term we (loosely) mean a rigorously defined set of purely combinatorial properties of the polyhedra in question that are strong enough to allow non-trivial conclusions about its geometry.

[^0]In the quest of bounding $\triangle_{u}$ one can restrict attention to non-degenerate polyhedra (we call a polyhedron non-degenerate if each vertex is contained in exactly $d$ facets) since, by perturbation, any polyhedron can be turned into a non-degenerate polyhedron whose diameter is at least as large as the one of the original polyhedron. For this reason we also allow ourselves this simplifying assumption of non-degeneracy (all our results, though, perfectly hold without it).

Combinatorial abstractions have been studied in the literature for a long time $[11,2,1]$. The subject of this paper is a simple base abstraction which is defined by one single feature, common to all previously studied abstractions from which lower and upper bounds have been previously derived. As an extra evidence (besides simplicity) that our framework is quite natural, we give for it three different descriptions that all turn out to be pairwise equivalent.

Even if our abstraction is more general than previously considered ones, we nonetheless show that all known upper bounds do hold here with natural and simple proofs. On the other hand, we prove an almost quadratic lower bound on the diameter in this abstraction, and this constitutes the main concrete result of this paper.

While only one feature of the previously studied abstractions suffices to derive the best known upper bounds, our lower bound also shows the limits of this natural base abstraction for the purpose of proving linear upper bounds on the diameter. To prove such a bound, more features of the geometry of polyhedra will have to be understood and used than the single one that we identify here. Let us, however, note that a polynomial (or even quadratic!) upper bound in this framework still remains a possibility.

In the first description, our base abstraction is given by a connected graph $G=(V, E)$. Here ${ }^{1} V \subseteq[n]^{d}$ and the edges $E$ of $G$ are such that the following connectivity condition holds:
i) For each $u, v \in V$ there exists a path connecting $u$ and $v$ whose intermediate vertices all contain $u \cap v$.

Let $\mathcal{B}_{d, n}$ be the set of all graphs $G$ with the above property; the largest diameter of a graph in $\mathcal{B}_{d, n}$ will be denoted by $D(d, n)$. We call $d$ the dimension and $n$ the number of facets of the abstraction.

Before we proceed, let us understand why this class contains the 1skeletons of non-degenerate polyhedra in dimension $d$ having $n$ facets. In

[^1]this setting, each vertex is uniquely determined by the $d$ facets in which it is contained. If the facets are named $\{1, \ldots, n\}$, then a vertex is uniquely determined by a $d$-element subset of $\{1, \ldots, n\}$. Furthermore, for every pair of vertices $u, v$ there exists a path which does not leave the minimal face in which both $u$ and $v$ are contained. This is reflected in condition i ). Thus if $\triangle_{u}(d, n)$ is the maximum diameter of a non-degenerate polyhedron with $n$ facets in dimension $d$, then $\triangle_{u}(d, n) \leq D(d, n)$ holds.
Our main result is a super-linear lower bound on $D(d, n)$, namely $D(n / 4, n)=$ $\Omega\left(n^{2} / \log n\right)$. The non-trivial construction relies on the notion of disjoint covering designs and in order to prove the existence of such designs with desired parameters we use Lovász Local Lemma.

At the same time the bound of Kalai and Kleitman [13], $\Delta_{u}(d, n) \leq$ $n^{1+\log d}$, as well as the upper bound of Larman [16], $\Delta_{u}(d, n) \leq 2^{d-1} \cdot n$, which is linear when the dimension is fixed, continue to hold in the base abstraction. While the first bound is merely an adaption of the proof in [13], our proof of the second bound is much simpler than the one which was proved for polyhedra in [16].

We strongly believe that the study of abstractions, asymptotic lower and upper bounds for those and the development of algorithms to compute bounds for fixed parameters $d$ and $n$ should receive more attention since they can help to understand the important features of the geometry of polyhedra that may help to improve the state-of-the art of the diameter question.

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[^1]:    ${ }^{1}[n]^{d}$ is the family of all $d$-element subsets of $[n]=\{1, \ldots, n\}$

