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ALMOST-UNIFORM SAMPLING OF POINTS ON HIGH-DIMENSIONAL ALGEBRAIC VARIETIES

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ABSTRACT. We consider the problem of uniform sampling of points on an algebraic variety. Specifically, we develop a randomized algorithm that, given a small set of multivariate polynomials over a sufficiently large finite field, produces a common zero of the polynomials almost uniformly at random. The statistical distance between the output distribution of the algorithm and the uniform distribution on the set of common zeros is polynomially small in the field size, and the running time of the algorithm is polynomial in the description of the polynomials and their degrees provided that the number of the polynomials is a constant.

1. Introduction

A natural and important class of problems in computer science deals with random generation of objects satisfying certain properties. More precisely, one is interested in an efficient algorithm that, given a *compact* description of a set of objects, outputs an element in the set uniformly at random, where the exact meaning of "compact" depends on the specific problem in question.

Uniform sampling typically arises for problems in NP. Namely, given an instance belonging to a language in NP, one aims to produce a witness uniformly at random. Here, the requirement is stronger than that of decision and search problems. In a seminal paper, Jerrum, Valiant and Vazirani [8] gave a unified framework for this problem and showed that, for polynomial-time verifiable relations xRy, uniform sampling of a witness y for a given instance x is reducible to approximate counting of the witnesses, and hence, can be efficiently accomplished using a Σ_2^P oracle. It is natural to ask whether the requirement for an Σ_2^P oracle can be lifted. In fact, this is the case; a result of Bellare, Goldreich, and Petrank [3] shows that an NP oracle is sufficient and also necessary for uniform sampling of NP witnesses.

The NP sampling problem can be equivalently stated as follows: Given a boolean circuit of polynomially bounded size, sample an input that produces the output 1 (if possible), uniformly at random among all possibilities. This problem can be naturally generalized to

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models of computation other than small boolean circuits, and an interesting question to ask is the following: For what restricted models, the uniform (or almost-uniform) sampling problem is efficiently solvable (e.g., by polynomial-time algorithms or polynomial-sized circuits) without the need for an additional oracle? Of course if the role of the NP oracle in [3] can be replaced by a weaker oracle that can be efficiently implemented, that would immediately imply an efficient uniform sampler. While for general NP relations the full power of an NP oracle is necessary, this might not be the case for more restricted models.

In this work, we study the sampling problem for the restricted model of polynomial functions. A polynomial function of degree d over a field \mathbb{F} (that we assume to be finite) is a mapping $f: \mathbb{F}^n \to \mathbb{F}^m$ such that every coordinate of the output can be computed by an n-variate polynomial of total degree at most d over \mathbb{F} . The corresponding sampling problem (that we call $variety\ sampling$) is defined as follows: Given a polynomial function, find a pre-image of a given output (that can be considered the zero vector without loss of generality) uniformly at random. Hence, in this problem one seeks to sample a uniformly random point on a given algebraic variety. It is not difficult to show that this problem is, in general, NP-hard. Hence, it is inevitable to relax the generality of the problem if one hopes to obtain an efficient solution without the need for an NP oracle. Accordingly, we restrict ourselves to the case where

- (1) The co-dimension of the variety (or, the number of the polynomials that define the variety) is *small*,
- (2) The underlying field is *sufficiently large*,
- (3) The output distribution is only required to be *statistically close* to the uniform distribution on the variety.

It is shown in [8] that almost uniform generation of NP witnesses (with respect to the statistical distance) is possible without using an NP oracle for self-reducible relations for which the size of the solution space can be efficiently approximated. The relation underlying the variety sampling problem consists of a set of n-variate polynomials over \mathbb{F} and a point $x \in \mathbb{F}^n$, and it holds if and only if x is a common zero of the polynomials. Obviously, assuming that field operations can be implemented in polynomial time, this is a polynomial-time verifiable relation. Moreover, the relation is self reducible, as any fixing of one of the coordinates of the witness x leads to a smaller instance of the problem itself, defined over n-1 variables. Approximate counting of the witnesses amounts to giving a sharp estimate on the number of common zeros of the set of polynomials. Several such estimates are available. In particular, a result of Lang and Weil¹ (Theorem 2.2) that we will later use in the paper gives general lower and upper bounds on the number of rational points on varieties. Moreover, there are algorithmic results (see [1, 2, 7, 12, 14] and the references therein) that consider the problem of counting rational points on a given variety that belongs to a certain restricted class of varieties over finite fields.

Thus, it appears that the result of [8] already covers the variety sampling problem. However, this is not the case because of the following subtleties:

(1) Our relation is not necessarily self-reducible in the strong sense required by the construction of [8]. What required by this result is that partial fixings of the witness can be done in steps of at most logarithmic length (to allow for an efficient enumeration of all possible fixings). Namely, in our case, a partial fixing of x amounts to choosing

¹This result can be seen as a consequence of the Weil theorem (initially conjectured in [18]) which is an analog of the Riemann hypothesis for curves over finite fields.

- a particular value for one of the n variables. The portion of x corresponding to the variable being fixed would have length $\log q$, and in general, this can be much larger than $O(\log |x|)$.
- (2) The general Lang-Weil estimate gives interesting bounds only when the underlying field is fairly large.
- (3) The algorithmic results mentioned above, being mostly motivated by cryptographic or number-theoretic applications such as primality testing, focus on very restricted classes of varieties, for instance, elliptic [14] or hyperelliptic [1] curves (or general plane curves [7] that are only defined over a constant number of variables), or low-dimensional Abelian varieties [2]. Moreover, they are efficient in terms of the running time with respect to the logarithm of the field size and the dependence on the number of variables or the degree (whenever they are not restricted to constants) can be exponential.

Hence, over large fields, fine granularity of the self-reduction cannot be fulfilled and over small fields, no reliable and efficient implementation of a counting oracle is available for our problem, and we cannot directly apply the general sampler of [8]. In this work, we construct an efficient sampler that directly utilizes the algebraic structure of the problem. The main theorem that we prove is the following:

Though we present the above result for affine varieties, our techniques can be readily applied to the same problem for projective varieties as well. At a high level, the algorithm is simple and intuitive, and can be roughly described as follows: To sample a point on a variety V of co-dimension k, we first sample a k-dimensional affine subspace A uniformly at random and then a random point on $V \cap A$. To make the analysis clear, we show (in Section 3) that the problem can be viewed as a sampling problem on almost regular bipartite graphs, where one can sample a left vertex almost uniformly by picking the left neighbor of a random edge. The main part of the analysis (Section 4) is to show why this reduction holds, and requires basic tools from Algebraic Geometry, in particular the Lang-Weil estimate on the number of points on varieties (Theorem 2.2), and details on how to deal with problems such as varying dimension and size of the intersection $V \cap A$. The reduction combined with the graph sampling algorithm constitutes the sampling algorithm claimed in the main theorem.

Connection with Randomness Extractors

Trevisan and Vadhan [17] introduced the notion of *samplable sources* as probability distributions that can be sampled using small, e.g., polynomial-sized, boolean circuits. An *extractor* for samplable sources is a deterministic function whose output, when the input is

²We consider an explicit description of polynomials given by a list of their nonzero monomials.

randomly chosen according to any samplable distribution, has a distribution that is statistically close to uniform. Assuming the existence of certain hard functions, they constructed such extractors.

As a natural class of samplable distributions, Dvir, Gabizon and Wigderson [6] considered the class of distributions that are samplable by low-degree multivariate polynomials. They gave a construction of extractors for such sources over sufficiently large finite fields that does not rely on any hardness assumption and achieves much better parameters. Moreover, they introduced the dual notion of algebraic sources that are defined as distributions that are uniform on rational points of low-degree affine varieties, and asked whether efficient extractors exist for such sources. Our main theorem shows that algebraic sources (for a wide range of parameters) are close to samplable distributions, and hence, any extractor for samplable distributions is also an extractor for such algebraic sources. Very recently, Dvir [5] gave a direct and unconditional construction of an extractor for algebraic sources when the field size is sufficiently large.

2. Preliminaries and Basic Facts

We will use a simple form of the well known Schwartz-Zippel lemma and a theorem by Lang and Weil for bounding the number of the points on a variety:

Lemma 2.1. (Schwartz-Zippel) [15, 19] Let f be a nonzero n-variate polynomial of degree d defined over a finite field \mathbb{F}_q . Then the number of zeros of f is at most dq^{n-1} .

Theorem 2.2. (Lang-Weil) [10] Let n, d, r be positive integers. There exists a constant A(n,d,r) depending only on n,d,r such that for any irreducible r-dimensional variety V of degree d defined in a projective space \mathbb{P}^n over a finite field \mathbb{F}_q , we have $|N-q^r| \leq (d-1)(d-2)q^{r-\frac{1}{2}} + A(n,d,r)q^{r-1}$, where N is the number of rational points of V over \mathbb{F}_q .

This theorem can be generalized to the case of reducible varieties as follows:

Corollary 2.3. Let n, d, r be positive integers. There exists a constant A'(n, d, r) depending only on n, d, r and a constant $\delta(d)$ depending only on d and integer $s, 1 \leq s \leq d$, such that for any r-dimensional variety V of degree d defined in a projective space \mathbb{P}^n over a finite field \mathbb{F}_q we have $|N - sq^r| \leq \delta(d)q^{r-\frac{1}{2}} + A'(n, d, r)q^{r-1}$, where N is the number of rational points of V over \mathbb{F}_q .

Proof. Let $V_1 \cup V_2 \cup \ldots \cup V_t$, where $1 \leq t \leq d$, be a decomposition of V into distinct irreducible components and denote the set of r-dimensional components in this decomposition by S. Let s := |S|. Note that each component $V_i \notin S$ has dimension at most r-1 and by Theorem 2.2, the number of points on the union of the components outside S is negligible, namely, at most $A''q^{r-\frac{3}{2}}$ where A'' is a parameter depending only on n, d, r. Hence to prove the corollary, it suffices to bound the number of points on the union of the components in S.

For each component $V_i \in S$ we can apply Theorem 2.2, which implies that the number of points of V_i in \mathbb{P}^n , assuming that its degree is d_i , is bounded from q^r by at most $(d_i - 1)(d_i - 2)q^{r-\frac{1}{2}} + \alpha_i q^{r-1}$, for some α_i that depends only on n, d_i, r . This upper bounds the number of points of V by

$$\sum_{i=1}^{s} |V_i| \le sq^r + \delta_1 q^{r - \frac{1}{2}} + A_1 q^{r - 1},$$

where $\delta_1 \stackrel{\text{def}}{=} \sum_{i=1}^s (d_i - 1)(d_i - 2) \leq d^2$ (from the fact that $\sum_{i=1}^s d_i \leq d$) and $A_1 \stackrel{\text{def}}{=} \sum_{i=1}^s \alpha_i$. Note that A_1 and δ_1 can be upper bounded by quantities depending only on n, d, r and d, respectively. This proves one side of the inequality.

For the lower bound on |V|, we note that the summation above counts the points at the intersection of two irreducible components multiple times, and it will be sufficient to discard all such points and lower bound the number of points that lie on exactly one of the components. Take a distinct pair of the irreducible components, V_i and V_j . The intersection of these varieties defines an (r-1)-dimensional variety, which by the upper bound we just obtained can have at most $s_{ij}q^{r-1} + \delta_2q^{r-1.5} + A_2q^{r-2}$) points, for some $s_{ij} \leq d^2$, and parameters δ_2 depending only on d and A_2 depending on n, k, r. Hence, considering all the pairs, the number of points that lie on more than one of the irreducible components is no more than $\binom{d}{2}(d^2q^{r-1} + \delta_2q^{r-1.5} + A_2q^{r-2})$, which means that the number of distinct points of V is at least $\sum_{i=1}^{s} |V_i| - d^4q^{r-1} - d^2\delta_2q^{r-\frac{3}{2}} - d^2A_2q^{r-2}$, which is itself at least $sq^r - \delta_1q^{r-\frac{1}{2}} - (A_1 + d^4)q^{r-1} - d^2\delta_2q^{r-\frac{3}{2}} - d^2A_2q^{r-2}$. Taking (crudely) $A'(n,d,r) \stackrel{\text{def}}{=} A_1 + d^2A_2 + d^4 + d^2\delta_2 + A''$ and $\delta \stackrel{\text{def}}{=} \delta_1$ proves the corollary.

Remark 2.4. Corollary 2.3 also holds for affine varieties. An affine variety V can be seen as the restriction of a projective variety \bar{V} to the affine space, where no irreducible component of \bar{V} is fully contained in the hyperplane at infinity. Then the affine dimension of V will be the (top) dimension of \bar{V} , and the bound in Corollary 2.3 holds for V if the affine dimension of the variety is taken as the parameter r in the bound. This is because each irreducible component of \bar{V} intersects the hyperplane at infinity at a variety of dimension less than r, and by Theorem 2.2, adding those points to the estimate will have a negligible effect of order $q^{r-\frac{3}{2}}$.

Finally, we review some basic notions that we use from probability theory. The statistical distance (or total variation distance) of two distributions \mathcal{X} and \mathcal{Y} defined on the same finite space S is defined as $\frac{1}{2} \sum_{s \in S} |\Pr_{\mathcal{X}}(s) - \Pr_{\mathcal{Y}}(s)|$, where $\Pr_{\mathcal{X}}$ and $\Pr_{\mathcal{Y}}$ denote the probability measures on S defined by the distributions \mathcal{X} and \mathcal{Y} , respectively. Note that this is half the ℓ_1 distance of the two distributions when regarded as vectors of probabilities over S. It can be shown that the statistical distance of the two distributions is at most ϵ if and only if for every $T \subseteq S$, we have $|\Pr_{\mathcal{X}}[T] - \Pr_{\mathcal{Y}}[T]| \le \epsilon$. When the statistical distance of \mathcal{X} and \mathcal{Y} is at most ϵ , we say that \mathcal{X} and \mathcal{Y} are ϵ -close. We will also use the notion of a convex combination of distributions, defined as follows:

Definition 2.5. Let $\mathcal{X}_1, \mathcal{X}_2, \ldots, \mathcal{X}_k$ be probability distributions on a finite set S and $\alpha_1, \alpha_2, \ldots, \alpha_k$ be nonnegative real values that sum up to 1. Then the *convex combination* $\alpha_1 \mathcal{X}_1 + \alpha_2 \mathcal{X}_2 + \cdots + \alpha_n \mathcal{X}_n$ is a distribution \mathcal{X} on S given by the probability measure $\Pr_{\mathcal{X}}(x) \stackrel{\text{def}}{=} \sum_{i=1}^k \alpha_i \Pr_{\mathcal{X}_i}(x)$, for $x \in S$.

There is a simple connection between convex combinations and distance of distributions:

Proposition 2.6. Let \mathcal{X}, \mathcal{Y} , and \mathcal{E} be probability distributions on a finite set S such that for some $0 \le \epsilon \le 1$, $\mathcal{X} = (1 - \epsilon)\mathcal{Y} + \epsilon \mathcal{E}$. Then \mathcal{X} is ϵ -close to \mathcal{Y} .

3. A Vertex Sampling Problem

In this section we introduce a sampling problem on graphs, and develop an algorithm to solve it. We will later use this algorithm as a basic component in our construction of samplers for varieties. The problem is as follows:

Problem 3.1. Let G be a bipartite graph defined on a set \mathcal{L} of left vertices and \mathcal{R} of right vertices. Suppose that the degree of every vertex on the right is between 1 and d, for some d>1, and the degree of every vertex on the left differs from an integer ℓ by at most $\delta\ell$. We are given an oracle $\mathsf{RSamp}(G)$ that returns an element of \mathcal{R} chosen uniformly at random (and independently at each call), and an oracle $\mathsf{RNei}(v)$ that returns the neighbor list of a given vertex $v \in \mathcal{R}$. Construct an algorithm that outputs a random vertex in \mathcal{L} almost uniformly.

Intuitively, for a bipartite graph which is regular from left and right, sampling a vertex on the left amounts to picking a random edge in the graph, which is in turn possible by choosing a random edge connected to a random vertex on the right side. Here of course, the graph is not regular, however the concentration of the left degrees around ℓ allows us to treat the graph as if it were regular and get an almost uniform distribution on $\mathcal L$ by picking a random edge. We will compensate the irregularity from right by using a "trial and error" strategy. The pseudocode given in Algorithm 1 implements this idea. The algorithm in fact handles a more general situation, in which a call to RSamp can fail (and return a special failure symbol \perp) with some probability upper bounded by a given parameter p.

Algorithm 1 BipartiteSample

Require: G, RSamp, RNei given as in Problem 3.1, and p denoting the failure probability of RSamp.

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1: Let \delta, d be as in Problem 3.1.

2: t_0 \leftarrow \lceil \frac{d}{1-p} \ln(\frac{1-\delta}{\delta}) \rceil; t \leftarrow t_0

3: while t \geq 0 do

4: t \leftarrow t-1; R \leftarrow \mathsf{RSamp}(G)

5: if R \neq \perp then

6: V \leftarrow \mathsf{RNei}(R)

7: With probability |V|/d, output an element of V uniformly at random and return.

8: end if

9: end while

10: Output an arbitrary element of \mathcal{L}.
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Lemma 3.2. The output distribution of Algorithm 1 is supported on \mathcal{L} and is $3\delta/(1-\delta)$ -close to the uniform distribution on \mathcal{L} .

Proof. First we focus on one iteration of the **while** loop in which the call to RSamp has not failed, and analyze the output distribution of the algorithm conditioned on the event that Line 7 returns a left vertex. In this case, one can see the algorithm as follows: Add a special vertex v_0 to the set of left vertices \mathcal{L} . Bring the degree of each right vertex up to d by connecting it to v_0 as many times as necessary. Hence, the graph G now becomes d-regular from right. Now the algorithm picks a random element $R \in \mathcal{R}$ and a random neighbor of R and independently repeats the process if v_0 is picked as a neighbor.

Let $T \subseteq \mathcal{L}$ be a non-empty subset of the left vertices (excluding v_0) in the graph. We want to estimate the probability of the event T. We can write this probability as follows:

$$\Pr[T] = \sum_{r \in \mathcal{R}} \Pr[T \mid R = r] \Pr[R = r] = \frac{1}{|\mathcal{R}|} \sum_{r \in \mathcal{R}} \Pr[T \mid R = r] = \frac{1}{d|\mathcal{R}|} \sum_{r \in \mathcal{R}} |T \cap \Gamma(r)|,$$

where in the last equation $\Gamma(r)$ is the set of neighbors of r in the graph. Hence the summation can be simplified as the number of edges connected to T. This quantity is in the range $|T|\ell(1\pm\delta)$, because the left degrees are all concentrated around ℓ , ignoring v_0 which is by assumption not in T. That is,

$$\Pr[T] = \Pr[T, \neg v_0] = \frac{|T|\ell}{d|\mathcal{R}|} (1 \pm \delta), \tag{3.1}$$

where we use the shorthand $(1 \pm \delta)$ to denote a quantity in the range $[1 - \delta, 1 + \delta]$.

Hence the probabilities of all events that exclude v_0 are close to one another, which implies that the distribution of the outcome of a single iteration of the algorithm, conditioned on a non-failure, is close to uniform. We will now make this statement more rigorous.

The degree of v_0 can be estimated as

$$\deg(v_0) = d|\mathcal{R}| - |\mathcal{L}|\ell(1 \pm \delta)$$

by equating the number of edges on the left and right side of the graph. Similar to what we did for computing the probability of T we can compute the probability of picking v_0 as

$$\Pr(v_0) = \frac{1}{d|\mathcal{R}|} \deg(v_0) = 1 - \frac{|\mathcal{L}|}{d|\mathcal{R}|} \ell(1 \pm \delta).$$

Combining this with (3.1) we get that

$$\Pr[T \mid \neg v_0] = \frac{\Pr[T, \neg v_0]}{1 - \Pr(v_0)} = \frac{|T|}{|\mathcal{L}|} \left(1 \pm \frac{2\delta}{1 - \delta} \right).$$

Hence, the output distribution of a single iteration of the **while** loop, conditioned on a non-failure (i.e., the event that the iteration reaches Line 7 and outputs an element of \mathcal{L}) is $2\delta/(1-\delta)$ -close to the uniform distribution on \mathcal{L} . Now denote by φ the failure probability. To obtain an upper bound on φ , note that the probability of sampling v_0 at Line 7 of the algorithm is at most (d-1)/d since each vertex on the right has at least one neighbor different from v_0 . Hence,

$$\varphi \le 1 - (1 - p)/d \tag{3.2}$$

Now we get back to the whole algorithm, and notice that if the **while** loop iterates for up to t_0 times, the output distribution of the algorithm can be written as a convex combination

$$\mathcal{O} = (1 - \varphi)\mathcal{D} + (1 - \varphi)\varphi\mathcal{D} + \dots + (1 - \varphi)\varphi^{t_0 - 1}\mathcal{D} + \varphi^{t_0}\mathcal{E} = (1 - \varphi^{t_0})\mathcal{D} + \varphi^{t_0}\mathcal{E},$$

where \mathcal{D} is the output distribution of a single iteration conditioned on a non-failure and \mathcal{E} is an arbitrary *error distribution* corresponding to the event that the algorithm reaches the last line. The coefficient of \mathcal{E} , for $t_0 \geq \frac{d}{1-p} \ln(\frac{1-\delta}{\delta})$, can be upper bounded using (3.2) by

$$\varphi^{t_0} \le \left(1 - \frac{1-p}{d}\right)^{\frac{d}{1-p}\ln(\frac{1-\delta}{\delta})} \le \frac{\delta}{1-\delta}.$$

This combined with the fact that \mathcal{D} is $2\delta/(1-\delta)$ -close to uniform and Proposition 2.6 implies that \mathcal{O} is $3\delta/(1-\delta)$ -close to the uniform distribution on \mathcal{L} .

4. Sampling Rational Points on Varieties

Now we are ready to describe and analyze our algorithm for sampling rational points on varieties. For the sake of brevity, we will present the results in this section for affine varieties. However, they can also be shown to hold for projective varieties using similar arguments.

We reduce the problem to the vertex sampling problem described in the preceding section. The basic idea is to intersect the variety with randomly chosen affine spaces in \mathbb{F}_a^n and narrowing-down the problem to the points within the intersection. Accordingly, the graph G in the bipartite sampling problem will be defined as the incidence graph of the points on the variety with affine spaces. This is captured in the following definition:

Definition 4.1. Let V be an affine variety of co-dimension k in \mathbb{F}_q^n . Then the affine incidence graph of the variety is a bipartite graph $G = (L \cup R, E)$ defined as follows:

- The left vertex set is V,
- For a k-dimensional affine space A, we say that A properly intersects V if the intersection $V \cap A$ is non-empty and has dimension zero. Then the right vertex set of G is defined as the set of k-dimensional affine spaces in \mathbb{F}_q^n that properly intersect
- There is an edge between $u \in L$ and $v \in R$ if and only if the affine space v contains the point u.

Before utilizing the vertex sampling algorithm of the preceding section, we need to develop the tools needed for showing that the affine incidence graph satisfies the properties needed by the algorithm. We begin with an estimate on the number of linear and affine subspaces of a given dimension. The estimate is straightforward to obtain, yet we include a proof for completeness.

Proposition 4.2. Let \mathbb{F} be a finite field of size $q \geq \sqrt{2k}$, and let N_1 and N_2 be the number of distinct k-dimensional linear and affine subspaces of \mathbb{F}^n , respectively. Then we have

- (1) $|N_1/q^{k(n-k)} 1| \le 2k/q^2$, (2) $|N_2/q^{(k+1)(n-k)} 1| \le 2k/q^2$.

Proof. If k = n, then $N_1 = N_2 = 1$, and the claim is obvious. Hence, assume that k < n. Denote by $N_{k,n}$ the number of ways to choose k linearly independent vectors in \mathbb{F}^n . That is, $N_{k,n}=(q^n-1)(q^n-q)\cdots(q^n-q^{k-1})$. This quantity is upper bounded by q^{nk} , and lower bounded by $(q^n-q^{k-1})^k\geq q^{nk}(1-kq^{k-1-n})\geq q^{nk}(1-k/q^2)$. Hence, the reciprocal of $N_{k,n}$ can be upper bounded as follows:

$$\frac{1}{N_{k,n}} \le \frac{q^{-nk}}{1 - k/q^2} = q^{-nk} \left(1 + \frac{k}{q^2} \cdot \frac{1}{1 - k/q^2} \right) \le q^{-nk} \left(1 + \frac{2k}{q^2} \right),$$

where the last inequality follows from the assumption that $q^2 \geq 2k$.

The number of k-dimensional subspaces of \mathbb{F}^n is the number of ways one can choose k linearly independent vectors in \mathbb{F}^n , divided by the number of bases a k-dimensional vector space can assume. That is, $N_1 = N_{k,n}/N_{k,k}$. By the bounds above, we obtain

$$N_1 \le q^{nk} \cdot q^{-k^2} (1 + 2k/q^2)$$
 and $N_1 \ge q^{nk} (1 - k/q^2) \cdot q^{-k^2}$,

which implies $|N_1/q^{k(n-k)}-1| \leq 2k/q^2$. The second part of the claim follows from the observation that two translations of a k-dimensional subspace A defined by vectors u and v coincide if and only if $u - v \in A$. Hence, the number of affine k-dimensional subspaces of \mathbb{F}^n is the number of k-dimensional subspaces of \mathbb{F}^n multiplied by the number of cosets of A, i.e., $N_2 = N_1 q^{n-k}$.

The following two propositions show that a good fraction of all k-dimensional affine spaces properly intersect any affine variety of co-dimension k.

Proposition 4.3. Let n, d, k be positive integers, and $V \subset \mathbb{F}_q^n$ be an affine variety of codimension k defined by the zero-set of k polynomials $f_1, \ldots, f_k \in \mathbb{F}_q[x_1, \ldots, x_n]$, each of degree at most d. Suppose that $v \in V$ is a fixed point of V. Then the fraction of k-dimensional affine spaces passing through v that properly intersect V is at least 1 - B(k, n, d)/q, where B(n, d, k) is independent of q and polynomially large in n, d, k.

Proof. Without loss of generality, assume that v is the origin, and that $q \ge \sqrt{2k}$. Denote by L the set of k-dimensional linear subspaces that can be parametrized as

$$\begin{pmatrix} x_{k+1} \\ x_{k+2} \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} \alpha_{11} & \dots & \alpha_{1k} \\ \alpha_{21} & \dots & \alpha_{2k} \\ \vdots & \ddots & \vdots \\ \alpha_{(n-k)1} & \dots & \alpha_{(n-k)k} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_k \end{pmatrix},$$

where $\alpha \stackrel{\text{def}}{=} \{\alpha_{11}, \ldots, \alpha_{(n-k)k}\}$ is a set of indeterminates in \mathbb{F}_q . Note that $|L| = q^{|\alpha|} = q^{k(n-k)}$, and define the polynomial ring $\mathcal{R} \stackrel{\text{def}}{=} \mathbb{F}_q[\alpha_{11}, \ldots, \alpha_{(n-k)k}]$. We first upper bound the number of bad subspaces in L whose intersections with V have nonzero dimensions. Substituting the linear forms defining x_{k+1}, \ldots, x_n in f_1, \ldots, f_k we see that the intersection of V and the elements of L is defined by the common zero-set of polynomials $g_1, \ldots, g_k \in \mathcal{R}[x_1, \ldots, x_k]$, where for each $i \in [k]$,

$$g_i(x_1, \dots, x_k) \stackrel{\text{def}}{=} f_i(x_1, \dots, x_k, \alpha_{11}x_1 + \dots + \alpha_{1k}x_k, \dots, \alpha_{(n-k)1}x_1 + \dots + \alpha_{(n-k)k}x_k).$$

Each g_i , as a polynomial in x_1, \ldots, x_k , has total degree at most d and each of its coefficients is a polynomial in $\alpha_{11}, \ldots, \alpha_{(n-k)k}$ of total degree at most d. Denote by $I \subseteq \mathcal{R}[x_1, \ldots, x_k]$ the ideal generated by $g_1, \ldots g_k$. For every $j \in [n]$, the ideal $I \cap \mathcal{R}[x_j]$ is generated by a polynomial h_j . Each coefficient of h_j can be written as a polynomial in \mathcal{R} with total degree at most D, where for a fixed k, D is polynomially large in d. This can be shown using an elimination method, e.g., generalized resultants or Gröbner bases (cf. [4, 11, 9]). Take any coefficient of h_j which is a nonzero polynomial in \mathcal{R} . The number of the choices of α which makes this coefficient zero is, by Lemma 2.1, at most $Dq^{k(n-k)-1}$. This also upper bounds the number of the choices of α that make h_j identically zero.

A union bound shows that for all but at most $nDq^{k(n-k)-1}$ choices of α none of the polynomial h_j is identically zero, and hence the solution space of g_1, \ldots, g_k is zero dimensional (and obviously non-empty, as we already know that it contains v). This gives an upper bound of nD/q on the fraction of bad subspaces in L.

By Proposition 4.2, the set L contains at least a $1-2k/q^2$ fraction of all k-dimensional subspaces of \mathbb{F}_q^n . Hence, the fraction of k-dimensional subspaces of \mathbb{F}_q^n that properly intersect V is at least

$$\left(1 - \frac{2k}{q^2}\right)\left(1 - \frac{nD}{q}\right) \ge \left(1 - \frac{2k + nD}{q}\right).$$

The claim follows by taking $B \stackrel{\text{def}}{=} 2k + nD$.

Proposition 4.4. Let k, n, d be positive integers, and $V \subset \mathbb{F}_q^n$ be an affine variety of codimension k defined by the zero-set of k polynomials $f_1, \ldots, f_k \in \mathbb{F}_q[x_1, \ldots, x_n]$, each of degree at most d. The fraction of k-dimensional affine subspaces that properly intersect V is at least

 $d^{-k}\left(1 - \frac{\delta(d)}{\sqrt{q}} - \frac{A'(n,d,n-k) + B(n,d,k)}{q}\right),\,$

where $\delta(\cdot), A'(\cdot), B(\cdot)$ are as in Corollary 2.3 and Proposition 4.3.

Proof. We use a counting argument to obtain the desired bound. Denote by N, N_1 , and N_2 the number of points of V, the number of k-dimensional subspaces and k-dimensional affine subspaces in \mathbb{F}_q^n , respectively. Then Corollary 2.3 (followed by Remark 2.4) implies that

$$N \ge sq^{n-k} - \delta(d)q^{n-k-\frac{1}{2}} - A'(n,d,n-k)q^{n-k-1},$$

for some $s \in [d^k]$ (as the degree of V is at most d^k).

By Proposition 4.3, for every $v \in V$, at least $N_1(1 - B(n, d, k)/q)$ affine subspace pass through v and properly intersect V. Hence in total $N \cdot N_1(1 - B(n, d, k)/q)$ affine spaces properly intersect V, where we have counted every such affine space at most d^k times (This is because the intersection of V and an affine space A that properly intersects it is of size at most d^k , and A is counted once for each point at the intersection). Thus, the fraction of distinct affine subspaces that properly intersect V is at least

$$\frac{NN_1(1-B(n,d,k)/q)}{d^kN_2}.$$

By the fact that $N_2 = N_1 q^{n-k}$ and the lower bound on N, we conclude that this fraction is at least

$$d^{-k}\left(s - \frac{\delta(d)}{\sqrt{q}} - \frac{A'(n,d,n-k)}{q}\right)\left(1 - \frac{B(n,d,k)}{q}\right).$$

As $s \geq 1$, this proves the claim.

Now having the above tools available, we are ready to give the reduction from variety sampling to the vertex sampling problem introduced in the preceding section and prove our main theorem:

Proof of Theorem 1.1. Let $G = (L \cup R, E)$ be the affine incidence graph of V. We will use Algorithm 1 on G. To show that the algorithm works, first we need to implement the oracles RSamp and RNei that are needed by the algorithm.

The function RSamp simply samples a k-dimensional affine space of \mathbb{F}_q^n uniformly at random, and checks whether the outcome A properly intersects V. To do so, one can parametrize the affine subspace as in the proof of Proposition 4.3 and substitute the parametrization in f_1, \ldots, f_k to obtain a system of k polynomial equations in k unknowns, each of degree at most D which is polynomially large in d. As k is an absolute constant, it is possible to solve this system in polynomial time using multipolynomial resultants or the Gröbner bases method combined with backward substitutions. If at any point, the elimination of all but any of the variables gives the zero polynomial, it turns out that the system does not define a zero-dimensional variety and hence, A does not properly intersect V. Also, if the elimination results in a univariate polynomial that does not have a solution in \mathbb{F}_q , the intersection becomes empty, again implying that A does not properly intersect V. In both cases RSamp fails, and otherwise, it outputs A. Furthermore, if the intersection is proper,

the elimination method gives the list of up to D^k points at the intersection, which one can use to construct the oracle RNei.

Now we need to show that the graph G satisfies the conditions required by Lemma 3.2. By the argument above, the degree of every right vertex in G is at least 1 and at most D^k , which is polynomially large in d. Let p denote the failure probability of RSamp. Then Proposition 4.4 implies that $p \leq d^{-k}/2$ when $q \geq \max\{16\delta^2(d), 4(A'(n, d, n - k) + B(n, d, k))\}$.

To bound the left degrees of the graph, note that each left node, which is a point on V, is connected to all k-dimensional affine subspaces that properly intersect V and pass through the point. The number of such spaces is, by Proposition 4.2, at most $q^{k(n-k)}(1+2k/q^2)$ (assuming $q \ge \sqrt{2k}$), and by combination of Proposition 4.2 and Proposition 4.3, at least

$$q^{k(n-k)}\left(1 - \frac{2k}{q^2}\right)\left(1 - \frac{B(k, n, d)}{q}\right) \ge q^{k(n-k)}\left(1 - \frac{2k + B(k, n, d)}{q}\right).$$

Now if we choose $q \ge (2k + B(k, n, d))^{1/\epsilon}$, the left degrees become concentrated in the range $q^{k(n-k)}(1 \pm 1/q^{1-\epsilon})$.

Putting everything together, now we can apply Lemma 3.2 to conclude that the output distribution of the algorithm is $(6/q^{1-\epsilon})$ -close to the uniform distribution on V.

To show the efficiency of the algorithm, first note that Algorithm 1 calls each of the oracles RSamp and RNei at most

$$\frac{D^k}{1-p}\ln\left(\frac{1-q^{\epsilon-1}}{q^{\epsilon-1}}\right) \le 2D^k(1-\epsilon)\ln q$$

times, which is upper bounded by a polynomial in d, $\ln q$. Hence it remains to show that the implementation of the two oracles are efficient. The main computational cost of these functions is related to the problem of deciding whether a system of k polynomial equations of bounded degree in k unknowns has a zero dimensional solution space, and if so, computing the list of at most D^k solutions of the system. As in our case k is a fixed constant, elimination methods can be efficiently applied to reduce the problem to that of finding the zero-set of a single uni-variate polynomial of bounded degree. A randomized algorithm is given in [13] for this problem that runs in expected polynomial time. Thus, we can use this algorithm as a sub-routine in RSamp and RNei to get a sampling algorithm that runs in expected polynomial time. Then it is possible to get a worst-case polynomial time algorithm by using a time-out trick, i.e., if the running time of the sampler exceeds a (polynomially large) threshold, it is forced to terminate and output an arbitrary point in \mathbb{F}_q^n . The error caused by this can increase the distance between the output distribution of the sampler and the uniform distribution on V by a negligible amount that can be made arbitrarily small (and in particular, smaller than $1/q^{1-\epsilon}$), and hence, is of little importance.

Finally, we need an efficient implementation of the field operations over \mathbb{F}_q . This is again possible using the algorithm given in [13]. Moreover, when the characteristic of the field is small, deterministic polynomial time algorithms are known for this problem [16].

5. Concluding Remarks

We showed the correctness and the efficiency of our sampling algorithm for varieties of constant co-dimension over large fields. Though our result covers important special cases such as sampling random roots of multivariate polynomials, relaxing either of these requirements is an interesting problem. In particular, it remains an interesting problem

to design samplers that work for super-constant (and even more ambitiously, linear in n) co-dimensions (in our result, the dependence of the running time on the co-dimension is exponential and thus, we require constant co-dimensions). Moreover, in this work we did not attempt to optimize or obtain concrete bounds on the required field size, which is another interesting problem. Finally, the error of our sampler (i.e., the distance of the output distribution from the uniform distribution on the variety) depends on the field size, and it would be interesting to bring down the error to an arbitrary parameter that is given to the algorithm.

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