

OSCILLATORY MIXED DIFFERENCE SYSTEMS

JOSÉ M. FERREIRA AND SANDRA PINELAS

Received 2 November 2005; Accepted 21 February 2006

The aim of this paper is to discuss the oscillatory behavior of difference systems of mixed type. Several criteria for oscillations are obtained. Particular results are included in regard to scalar equations.

Copyright © 2006 J. M. Ferreira and S. Pinelas. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

1. Introduction

The aim of this work is to study the oscillatory behavior of the difference system

$$\Delta x(n) = \sum_{i=1}^{\ell} P_i x(n-i) + \sum_{j=1}^m Q_j x(n+j), \quad n = 0, 1, 2, \dots, \quad (1.1)$$

where $x(n) \in \mathbb{R}^d$, $\Delta x(n) = x(n+1) - x(n)$ is the usual difference operator, $\ell, m \in \mathbb{N}$, and for $i = 1, \dots, \ell$ and $j = 1, \dots, m$ P_i and Q_j are given $d \times d$ real matrices. For a particular form of the scalar case of (1.1), the same question is studied in [1] (see also [2, Section 1.16]).

The system (1.1) is introduced in [9]. In this paper the authors show that the existence of oscillatory or nonoscillatory solutions of that system determines an identical behavior to the differential system with piecewise constant arguments,

$$\dot{x}(t) = \sum_{i=1}^{\ell} P_i x([t-i]) + \sum_{j=1}^m Q_j x([t+j]), \quad (1.2)$$

where for $t \in \mathbb{R}$, $x(t) \in \mathbb{R}^d$ and $[\cdot]$ means the greatest integer function (see also [8, Chapter 8]).

By a solution of (1.1) we mean any sequence $x(n)$, of points in \mathbb{R}^d , with $n = -\ell, \dots, 0, 1, \dots$, which satisfy (1.1). In order to guarantee its existence and uniqueness for given

2 Oscillatory mixed difference systems

initial values $x_{-\ell}, \dots, x_0, \dots, x_{m-1}$, denoting by I the $d \times d$ identity matrix, we will assume throughout this paper that the matrices $P_1, \dots, P_\ell, Q_1, \dots, Q_m$, are such that

$$\begin{aligned} \det(I - Q_1) &\neq 0, & \text{if } m = 1, \\ \det Q_m &\neq 0, & \text{if } m \geq 2, \\ P_i &= 0, & \text{for every } i = 1, \dots, \ell, \end{aligned} \tag{1.3}$$

with no restrictions in other cases (see [8, Chapter 7] and [9]).

We will say that a sequence $y(n)$ satisfies *frequently* or *persistently* a given condition, (C), whenever for every $\nu \in \mathbb{N}$ there exists a $n > \nu$ such that $y(n)$ verifies (C). When there is a $\nu \in \mathbb{N}$ such that $y(n)$ verifies (C) for every $n > \nu$, (C) is said to be satisfied *eventually* or *ultimately*.

Upon the basis of this terminology, a solution of (1.1), $x(n) = [x_1(n), \dots, x_d(n)]^T$, is said to be *oscillatory* if each real sequence $x_k(n)$ ($k = 1, \dots, d$) is frequently nonnegative and frequently nonpositive. If for some $k \in \{1, \dots, d\}$ the real sequence $x_k(n)$ is either eventually positive or eventually negative, $x(n)$ is said to be a *nonoscillatory* solution of (1.1). Whenever all solutions of (1.1) are oscillatory we will say that (1.1) is an *oscillatory system*. Otherwise, (1.1) will be said *nonoscillatory*.

Systems of mixed-type like (1.1) can be looked as a discretization of the continuous difference system

$$x(t+1) - x(t) = \sum_{i=1}^{\ell} P_i x(t-i) + \sum_{j=1}^m Q_j x(t+j). \tag{1.4}$$

When $Q_m = I$, one easily can see that, through a suitable change of variable, this system is a particular case of the delay difference system

$$x(t) = \sum_{i=1}^p A_i x(t-r_i), \tag{1.5}$$

where the A_j are $d \times d$ real matrices and the r_j are real positive numbers.

As is proposed in [8, Section 7.11], we will investigate, here, conditions on the matrices P_i and Q_j ($i = 1, \dots, \ell$, and $j = 1, \dots, m$) which make the system (1.1) oscillatory. For that purpose we will develop the approach made in [3], motivated by analogues methods used in [6, 7] for obtaining oscillation criteria regarding the continuous delay difference system (1.5).

We notice that for mixed-type differential difference equations and the differential analog of (1.4), those methods seem not to work in general. In fact, for such equations the situation is essentially different since one cannot ensure, as for (1.5), that the corresponding Cauchy problem will be well posed, or guarantee an exponential boundness for all its solutions (see [11]).

According to [9] (or [8, Chapter 7]) the analysis of the oscillatory behavior of the system (1.1) can be based upon the existence or absence of real positive zeros of the characteristic equation

$$\det \left((\lambda - 1)I - \sum_{i=1}^{\ell} \lambda^{-i} P_i - \sum_{j=1}^m \lambda^j Q_j \right) = 0. \tag{1.6}$$

That is, letting

$$M(\lambda) = \sum_{i=1}^{\ell} \lambda^{-i} P_i + \sum_{j=1}^m \lambda^j Q_j, \tag{1.7}$$

one can say that (1.1) is oscillatory if and only if, for every $\lambda \in \mathbb{R}^+ =]0, +\infty[$,

$$\lambda - 1 \notin \sigma(M(\lambda)), \tag{1.8}$$

where for any matrix $C \in \mathbb{M}_d(\mathbb{R})$, the space of all $d \times d$ real matrices, by $\sigma(C)$ we mean its spectral set.

Based upon this characterization we will use, as in [3], the so-called logarithmic norms of matrices. For that purpose, we recall that to each induced norm, $\| \cdot \|$, in $\mathbb{M}_d(\mathbb{R})$, we can associate a logarithmic norm $\mu : \mathbb{M}_d(\mathbb{R}) \rightarrow \mathbb{R}$, which is defined through the following derivative:

$$\mu(C) = (\|I + tC\|)' |_{t=0}, \tag{1.9}$$

where $C \in \mathbb{M}_d(\mathbb{R})$. As is well known, the logarithmic norm of any matrix $C \in \mathbb{M}_d(\mathbb{R})$ provides real bounds of the set $\text{Re } \sigma(C) = \{\text{Re } z : z \in \sigma(C)\}$, which enables us to handle condition (1.8) in a more suitable way. Those bounds are given in the first of the following elementary properties of any logarithmic norm (see [4, 5]):

- (i) $\text{Re } \sigma(C) \subset [-\mu(-C), \mu(C)]$ ($C \in \mathbb{M}_d(\mathbb{R})$);
- (ii) $\mu(C_1) - \mu(-C_2) \leq \mu(C_1 + C_2) \leq \mu(C_1) + \mu(C_2)$ ($C_1, C_2 \in \mathbb{M}_d(\mathbb{R})$);
- (iii) $\mu(\gamma C) = \gamma \mu(C)$, for every $\gamma \geq 0$ ($C \in \mathbb{M}_d(\mathbb{R})$).

In regard to a given finite sequence of matrices, C_1, \dots, C_ν , in $\mathbb{M}_d(\mathbb{R})$, and on the basis of a logarithmic norm, μ , we can define other matrix measures with some relevance in the sequel such as

$$a(C_k) = \mu \left(\sum_{i=1}^k C_i \right), \quad b(C_k) = \mu \left(\sum_{i=k}^{\nu} C_i \right), \quad \text{for } k = 1, \dots, \nu. \tag{1.10}$$

In the same context, these measures give rise to the matrix measures α and β considered in [10] as follows:

$$\begin{aligned} \alpha(C_1) = a(C_1) = \mu(C_1), & \quad \alpha(C_k) = a(C_k) - a(C_{k-1}), \quad \text{for } k = 2, \dots, \nu; \\ \beta(C_\nu) = b(C_\nu) = \mu(C_\nu), & \quad \beta(C_k) = b(C_k) - b(C_{k+1}), \quad \text{for } k = 1, \dots, \nu - 1. \end{aligned} \tag{1.11}$$

4 Oscillatory mixed difference systems

In the sequel whenever the values $a(-C_k)$, $b(-C_k)$, $\alpha(-C_k)$, and $\beta(-C_k)$ are considered, we are implicitly referring to the values above with respect to the finite sequence $-C_1, \dots, -C_\nu$.

Notice that by the property (ii) above, these measures are related with the corresponding logarithmic norm μ in the following way:

$$a(C_k) \leq \sum_{i=1}^k \mu(C_i), \quad b(C_k) \leq \sum_{i=k}^{\nu} \mu(C_i), \quad (1.12)$$

$$\alpha(C_k) \leq \mu(C_k), \quad \beta(C_k) \leq \mu(C_k), \quad (1.13)$$

for every $k = 1, \dots, \nu$.

With respect to the measures α and β the following lemma holds.

LEMMA 1.1. *Let C_1, \dots, C_ν , be a finite sequence of $d \times d$ real matrices.*

(a) *If $\gamma_1 \geq \dots \geq \gamma_\nu \geq 0$ is a nonincreasing finite sequence of nonnegative real numbers, then*

$$\mu\left(\sum_{i=1}^{\nu} \gamma_i C_i\right) \leq \sum_{i=1}^{\nu} \gamma_i \alpha(C_i). \quad (1.14)$$

(b) *If $0 \leq \gamma_1 \leq \dots \leq \gamma_\nu$ is a nondecreasing finite sequence of nonnegative real numbers, then*

$$\mu\left(\sum_{i=1}^{\nu} \gamma_i C_i\right) \leq \sum_{i=1}^{\nu} \gamma_i \beta(C_i). \quad (1.15)$$

Proof. We will prove only inequality (1.14). Analogously one can obtain (1.15).

Applying the property (ii) of the logarithmic norms, one has

$$\mu\left(\sum_{i=1}^{\nu} \gamma_i C_i\right) = \mu\left(\gamma_\nu \sum_{i=1}^{\nu} C_i + \sum_{i=1}^{\nu-1} (\gamma_i - \gamma_\nu) C_i\right) \leq \gamma_\nu \mu\left(\sum_{i=1}^{\nu} C_i\right) + \mu\left(\sum_{i=1}^{\nu-1} (\gamma_i - \gamma_\nu) C_i\right). \quad (1.16)$$

On the other hand, since

$$\begin{aligned} \sum_{i=1}^{\nu-1} (\gamma_i - \gamma_\nu) C_i &= (\gamma_1 - \gamma_2) C_1 + (\gamma_2 - \gamma_3) C_1 + (\gamma_3 - \gamma_4) C_1 + \dots + (\gamma_{\nu-1} - \gamma_\nu) C_1 \\ &\quad + (\gamma_2 - \gamma_3) C_2 + (\gamma_3 - \gamma_4) C_2 + \dots + (\gamma_{\nu-1} - \gamma_\nu) C_2 + \dots \\ &\quad + (\gamma_{\nu-2} - \gamma_{\nu-1}) C_{\nu-2} + (\gamma_{\nu-1} - \gamma_\nu) C_{\nu-2} + (\gamma_{\nu-1} - \gamma_\nu) C_{\nu-1}, \end{aligned} \quad (1.17)$$

and $\gamma_{i+1} \leq \gamma_i$, for every $i = 1, \dots, \nu - 1$, we have by the properties (ii) and (iii) of the logarithmic norms,

$$\begin{aligned} \mu\left(\sum_{i=1}^{\nu} \gamma_i C_i\right) &\leq \gamma_{\nu} \mu\left(\sum_{i=1}^{\nu} C_i\right) + (\gamma_{\nu-1} - \gamma_{\nu}) \mu\left(\sum_{i=1}^{\nu-1} C_i\right) \\ &\quad + (\gamma_{\nu-2} - \gamma_{\nu-1}) \mu\left(\sum_{i=1}^{\nu-2} C_i\right) + \dots + (\gamma_2 - \gamma_3) \mu\left(\sum_{i=1}^2 C_i\right) + (\gamma_1 - \gamma_2) \mu(C_1). \end{aligned} \tag{1.18}$$

Thus

$$\begin{aligned} \mu\left(\sum_{i=1}^{\nu} \gamma_i C_i\right) &\leq \gamma_{\nu} \left[\mu\left(\sum_{i=1}^{\nu} C_i\right) - \mu\left(\sum_{i=1}^{\nu-1} C_i\right) \right] + \gamma_{\nu-1} \left[\mu\left(\sum_{i=1}^{\nu-1} C_i\right) - \mu\left(\sum_{i=1}^{\nu-2} C_i\right) \right] \\ &\quad + \dots + \gamma_2 \left[\mu\left(\sum_{i=1}^2 C_i\right) - \mu(C_1) \right] + \gamma_1 \mu(C_1), \end{aligned} \tag{1.19}$$

which is equivalent to (1.14). □

In view of the examples which will be given in the sections below we recall the following well-known logarithmic norms of a matrix $C = [c_{jk}] \in \mathbb{M}_d(\mathbb{R})$:

$$\mu_1(C) = \max_{1 \leq k \leq d} \left\{ c_{kk} + \sum_{j \neq k} |c_{jk}| \right\}, \quad \mu_{\infty}(C) = \max_{1 \leq j \leq d} \left\{ c_{jj} + \sum_{k \neq j} |c_{jk}| \right\}, \tag{1.20}$$

which correspond, respectively, to the induced norms in $\mathbb{M}_d(\mathbb{R})$ given by

$$\|C\|_1 = \max_{1 \leq k \leq d} \left\{ \sum_{j=1}^d |c_{jk}| \right\}, \quad \|C\|_{\infty} = \max_{1 \leq j \leq d} \left\{ \sum_{k=1}^d |c_{jk}| \right\}. \tag{1.21}$$

With respect to the norm $\|C\|_2$ induced by the Hilbert norm in \mathbb{R}^d , the corresponding logarithmic norm is given by $\mu_2(C) = \max \sigma((B + B^T)/2)$. For this specific logarithmic norm, some oscillation criteria are obtained in [3].

2. Criteria involving the measures α and β

By (1.8) and the property (i) of the logarithmic norms, we have that (1.1) is oscillatory whenever, for every real positive λ ,

$$\lambda - 1 \notin [-\mu(-M(\lambda)), \mu(M(\lambda))]. \tag{2.1}$$

This means that (1.1) is oscillatory if either

$$\mu(M(\lambda)) < \lambda - 1, \quad \forall \lambda \in \mathbb{R}^+, \tag{2.2}$$

or

$$\mu(-M(\lambda)) < 1 - \lambda, \quad \forall \lambda \in \mathbb{R}^+. \tag{2.3}$$

6 Oscillatory mixed difference systems

Depending upon the choice of the matrix measures proposed, one can obtain several different conditions regarding the oscillatory behavior of (1.1).

THEOREM 2.1. *If for every $i = 1, \dots, \ell$, and $j = 1, \dots, m$,*

$$\alpha(P_i) \leq 0, \quad \beta(Q_j) \leq 0, \quad (2.4)$$

$$\beta(P_i) \leq 0, \quad \alpha(Q_j) \leq 0, \quad (2.5)$$

$$\sum_{i=1}^{\ell} \frac{(i+1)^{i+1}}{i^i} \beta(P_i) < -1, \quad (2.6)$$

then (1.1) is oscillatory.

Proof. By the property (ii) of the logarithmic norms, one has

$$\mu(M(\lambda)) \leq \mu\left(\sum_{i=1}^{\ell} \lambda^{-i} P_i\right) + \mu\left(\sum_{j=1}^m \lambda^j Q_j\right). \quad (2.7)$$

For every real $\lambda \in]1, +\infty[$, inequalities (1.14) and (1.15) and assumption (2.4) imply that

$$\mu(M(\lambda)) \leq \sum_{i=1}^{\ell} \lambda^{-i} \alpha(P_i) + \sum_{j=1}^m \lambda^j \beta(Q_j) \leq 0. \quad (2.8)$$

Then, for every real $\lambda > 1$, we conclude that

$$\mu(M(\lambda)) < \lambda - 1, \quad (2.9)$$

since in that case $\lambda - 1 > 0$.

Let now $0 < \lambda \leq 1$. From (2.7) and inequalities (1.14) and (1.15), we obtain

$$\mu(M(\lambda)) \leq \sum_{i=1}^{\ell} \lambda^{-i} \beta(P_i) + \sum_{j=1}^m \lambda^j \alpha(Q_j), \quad (2.10)$$

and by assumption (2.5) we have

$$\mu(M(\lambda)) \leq \sum_{i=1}^{\ell} \lambda^{-i} \beta(P_i). \quad (2.11)$$

But as

$$\max_{\lambda > 1} \left(\frac{\lambda^{-i}}{\lambda - 1} \right) = -\frac{(i+1)^{i+1}}{i^i}, \quad (2.12)$$

we conclude that, for every real $0 < \lambda \leq 1$,

$$\sum_{i=1}^{\ell} \lambda^{-i} \beta(P_i) \leq -(\lambda - 1) \sum_{i=1}^{\ell} \frac{(i+1)^{i+1}}{i^i} \beta(P_i). \quad (2.13)$$

Thus by (2.6),

$$\mu(M(\lambda)) \leq -(\lambda - 1) \sum_{i=1}^{\ell} \frac{(i+1)^{i+1}}{i^i} \beta(P_i) < \lambda - 1, \quad (2.14)$$

also for every real $0 < \lambda \leq 1$. □

As a corollary of Theorem 2.1, we obtain the following statement.

COROLLARY 2.2. *Under (2.4) and (2.5), if*

$$\sum_{i=1}^{\ell} \beta(P_i) < -\frac{1}{4}, \quad (2.15)$$

then (1.1) is oscillatory.

Proof. Since $(i+1)^{i+1}/i^i \geq 4$ for every positive integer, the condition (2.15) implies (2.6). □

The condition (2.15) is a result of (2.6) through a substitution involving the lower index of the family of matrices P_i . A condition involving the largest index, m , of the family of matrices Q_j is stated in the following theorem.

THEOREM 2.3. *Under (2.4) and (2.5), if $\beta(P_i) \neq 0$, for some $i = 1, \dots, \ell$, and*

$$\left(m \frac{\sum_{j=1}^m \alpha(Q_j)}{\sum_{i=1}^{\ell} \beta(P_i)} \right)^{1/(m+1)} \left(\sum_{i=1}^{\ell} \beta(P_i) \right) \left(\frac{1}{m} + 1 \right) \leq -1, \quad (2.16)$$

then (1.1) is oscillatory.

Proof. As in the proof of Theorem 2.1, we have

$$\mu(M(\lambda)) < \lambda - 1, \quad (2.17)$$

for every real $\lambda > 1$.

Recalling inequality (2.10), we obtain by (2.5), for every real $0 < \lambda \leq 1$,

$$\mu(M(\lambda)) \leq \lambda^{-1} \sum_{i=1}^{\ell} \beta(P_i) + \lambda^m \sum_{j=1}^m \alpha(Q_j), \quad (2.18)$$

since $\lambda^{-i} \geq \lambda^{-1}$ and $\lambda^j \geq \lambda^m$. The function

$$f(\lambda) = \lambda^{-1} \sum_{i=1}^{\ell} \beta(P_i) + \lambda^m \sum_{j=1}^m \alpha(Q_j) \quad (2.19)$$

is strictly concave and

$$f(\lambda) \leq \left(m \frac{\sum_{j=1}^m \alpha(Q_j)}{\sum_{i=1}^{\ell} \beta(P_i)} \right)^{1/(m+1)} \left(\sum_{i=1}^{\ell} \beta(P_i) \right) \left(\frac{1}{m} + 1 \right). \quad (2.20)$$

8 Oscillatory mixed difference systems

By (2.16) we have then, for every real $0 < \lambda \leq 1$, $\mu(M(\lambda)) \leq -1 < \lambda - 1$, and consequently condition (2.2) is fulfilled and system (1.1) is oscillatory. \square

By use of (2.3), the following theorem is stated.

THEOREM 2.4. *If for every $i = 1, \dots, \ell$ and $j = 1, \dots, m$,*

$$\alpha(-P_i) \leq 0, \quad \beta(-Q_j) \leq 0, \quad (2.21)$$

$$\alpha(-Q_j) \leq 0, \quad \beta(-P_i) \leq 0, \quad (2.22)$$

$$\sum_{j=1}^m \frac{j^j}{(j-1)^{j-1}} \beta(-Q_j) < -1, \quad (2.23)$$

then (1.1) is oscillatory.

Proof. For every $\lambda \geq 1$, as in (2.8), we have

$$\mu(-M(\lambda)) \leq \sum_{i=1}^{\ell} \lambda^{-i} \alpha(-P_i) + \sum_{j=1}^m \lambda^j \beta(-Q_j), \quad (2.24)$$

and by (2.21)

$$\mu(-M(\lambda)) \leq \sum_{j=1}^m \lambda^j \beta(-Q_j). \quad (2.25)$$

Since for $j > 1$,

$$\max_{\lambda > 1} \left(\frac{\lambda^j}{1-\lambda} \right) = -\frac{j^j}{(j-1)^{j-1}}, \quad (2.26)$$

and for $j = 1$,

$$\sup_{\lambda > 1} \left(\frac{\lambda}{1-\lambda} \right) = -1, \quad (2.27)$$

we can conclude (under the convention $0^0 = 1$) that

$$\sum_{j=1}^m \lambda^j \beta(-Q_j) < (\lambda - 1) \sum_{j=1}^m \frac{j^j}{(j-1)^{j-1}} \beta(-Q_j), \quad (2.28)$$

for every real $\lambda \geq 1$. So by (2.23), we obtain

$$\mu(-M(\lambda)) < (\lambda - 1) \sum_{j=1}^m \frac{j^j}{(j-1)^{j-1}} \beta(-Q_j) \leq 1 - \lambda, \quad (2.29)$$

for every real $\lambda \geq 1$.

On the other hand, for every $0 < \lambda < 1$, as in (2.10), by (2.22), we have

$$\mu(-M(\lambda)) \leq \sum_{i=1}^{\ell} \lambda^{-i} \beta(-P_i) + \sum_{j=1}^m \lambda^j \alpha(-Q_j) \leq 0 < 1 - \lambda, \quad (2.30)$$

and consequently system (1.1) is oscillatory. □

COROLLARY 2.5. *Under (2.21) and (2.22), if*

$$\sum_{j=1}^m \beta(-Q_j) < -1 \quad (2.31)$$

then (1.1) is oscillatory.

Proof. Clearly (2.31) implies (2.23). □

Remark 2.6. In case of having $m > 1$, (2.31) can be replaced by $\sum_{j=1}^m \beta(-Q_j) \leq -1$.

We illustrate these results with the following example.

Example 2.7. Consider system (1.1) with $d = \ell = m = 2$, and

$$\begin{aligned} P_1 &= \begin{bmatrix} -1 & 1 \\ -1 & -4 \end{bmatrix}, & P_2 &= \begin{bmatrix} -\frac{1}{10} & -1 \\ 0 & -1 \end{bmatrix}, \\ Q_1 &= \begin{bmatrix} -9 & -2 \\ 3 & -10 \end{bmatrix}, & Q_2 &= \begin{bmatrix} -8 & 1 \\ -2 & -10 \end{bmatrix}. \end{aligned} \quad (2.32)$$

Through the logarithmic norm μ_1 , we have

$$\begin{aligned} a(P_1) &= \mu_1(P_1) = 0 = \mu_1(P_2) = b(P_2), \\ a(P_2) &= \mu_1(P_1 + P_2) = b(P_1) = -\frac{1}{10}, \\ a(Q_1) &= \mu_1(Q_1) = -6 = \mu_1(Q_2) = b(Q_2), \\ a(Q_2) &= \mu_1(Q_1 + Q_2) = b(Q_1) = -16, \end{aligned} \quad (2.33)$$

and consequently

$$\begin{aligned} \alpha(P_1) &= 0, & \alpha(P_2) &= -\frac{1}{10}, & \beta(Q_1) &= -10, & \beta(Q_2) &= -6, \\ \beta(P_1) &= -\frac{1}{10}, & \beta(P_2) &= 0, & \alpha(Q_1) &= -6, & \alpha(Q_2) &= -10. \end{aligned} \quad (2.34)$$

Since

$$\sqrt[3]{2 \times 160} \left(-\frac{1}{10} \right) \left(\frac{1}{2} + 1 \right) \approx -1.0260 < -1, \quad (2.35)$$

we can conclude, by Theorem 2.3, that the correspondent system (1.1) is oscillatory.

Notice that, as

$$\sum_{i=1}^2 \frac{(i+1)^{i+1}}{i^i} \beta(P_i) = 2^2 \times \left(-\frac{1}{10} \right) - \frac{3^3}{2^2} \times 0 = -\frac{2}{5},$$

$$\sum_{i=1}^2 \beta(P_i) = -\frac{1}{10},$$
(2.36)

Theorem 2.1 and Corollary 2.2 cannot be applied to this system. The same holds to Theorem 2.4 and Corollary 2.5 since the respective conditions (2.21) and (2.22) are not fulfilled.

Through the application of inequalities (1.13), from Theorem 2.1, Corollary 2.2, Theorem 2.4, and Corollary 2.5, the corollaries below extend results contained in [3, Theorem 2].

COROLLARY 2.8. *Let $\mu(P_i) \leq 0$, $\mu(Q_j) \leq 0$, for every $i = 1, \dots, \ell$, and $j = 1, \dots, m$. If one of the inequalities*

$$\sum_{i=1}^{\ell} \frac{(i+1)^{i+1}}{i^i} \mu(P_i) < -1, \quad \sum_{i=1}^{\ell} \mu(P_i) < -\frac{1}{4},$$
(2.37)

is satisfied, then system (1.1) is oscillatory.

COROLLARY 2.9. *Let for every $i = 1, \dots, \ell$, and $j = 1, \dots, m$, $\mu(-P_i) \leq 0$, $\mu(-Q_j) \leq 0$. If one of the inequalities*

$$\sum_{j=1}^m \frac{j^j}{(j-1)^{j-1}} \mu(-Q_j) < -1, \quad \sum_{j=1}^m \mu(-Q_j) < -1,$$
(2.38)

is verified, then system (1.1) is oscillatory.

Example 2.10. Consider system (1.1) with $d = 2$, $\ell = 3$, $m = 2$,

$$P_1 = \begin{bmatrix} -2 & -1 \\ 1 & -7 \end{bmatrix}, \quad P_2 = \begin{bmatrix} -1 & 2 \\ 1 & -4 \end{bmatrix}, \quad P_3 = \begin{bmatrix} -5 & 0 \\ -2 & -1 \end{bmatrix},$$

$$Q_1 = \begin{bmatrix} -1 & 1 \\ 0 & -5 \end{bmatrix}, \quad Q_2 = \begin{bmatrix} -2 & 0 \\ -1 & -1 \end{bmatrix}.$$
(2.39)

With respect to the logarithmic norm μ_1 , we have

$$\mu_1(P_1) = -1, \quad \mu_1(P_2) = 0, \quad \mu_1(P_3) = \mu_1(Q_1) = -1, \quad \mu_1(Q_2) = -1,$$

$$\mu_1(P_1) + \mu_1(P_2) + \mu_1(P_3) = -2.$$
(2.40)

Then the corresponding system (1.1) is oscillatory by Corollary 2.8. Remark that Corollary 2.9 cannot be used in this case.

When $d = 1$, one has $\mu(c) = c$, for every logarithmic norm, μ , and any real number, c . As a consequence also $\alpha(c) = \beta(c) = c$. So, all the results involving logarithmic norms and the matrix measures α and β can easily be adapted to the scalar case of (1.1), that is, to the equation

$$\Delta x(n) = \sum_{i=1}^{\ell} p_i x(n-i) + \sum_{j=1}^m q_j x(n+j), \tag{2.41}$$

where p_i and q_j are real numbers, for $i = 1, \dots, \ell$, and $j = 1, \dots, m$.

Remark 2.11. The scalar case correspondent to Corollary 2.9 is in certain a sense an extension of [1, Theorem 6] (or [2, Theorem 1.16.7]).

3. The measures a and b

Through the use of the matrix measures a and b , different criteria are obtained through the following theorems.

THEOREM 3.1. *If for every $i = 1, \dots, \ell$, and $j = 1, \dots, m$,*

$$a(P_i) \leq 0, \quad b(Q_j) \leq 0, \tag{3.1}$$

$$a(Q_j) \leq 0, \quad b(P_i) \leq 0, \tag{3.2}$$

$$b(P_1) < 0, \quad \sum_{i=1}^{\ell} b(P_i) \leq -1, \tag{3.3}$$

then (1.1) is oscillatory.

Proof. Recall inequality (2.8) and notice that for every real λ ,

$$\begin{aligned} \sum_{i=1}^{\ell} \lambda^{-i} \alpha(P_i) &= \lambda^{-1} a(P_1) + \sum_{i=2}^{\ell} \lambda^{-i} [a(P_i) - a(P_{i-1})] \\ &= \sum_{i=1}^{\ell} \lambda^{-i} a(P_i) - \sum_{i=1}^{\ell-1} \lambda^{-(i+1)} a(P_i) \end{aligned} \tag{3.4}$$

$$= \sum_{i=1}^{\ell-1} \lambda^{-i} (1 - \lambda^{-1}) a(P_i) + \lambda^{-\ell} a(P_{\ell}),$$

$$\begin{aligned} \sum_{j=1}^m \lambda^j \beta(Q_j) &= \sum_{j=1}^{m-1} \lambda^j [b(Q_j) - b(Q_{j+1})] + \lambda^m b(Q_m) \\ &= \sum_{j=1}^m \lambda^j b(Q_j) - \sum_{j=2}^m \lambda^{(j-1)} b(Q_j) \end{aligned} \tag{3.5}$$

$$= \lambda b(Q_1) + \sum_{j=2}^m \lambda^j (1 - \lambda^{-1}) b(Q_j).$$

12 Oscillatory mixed difference systems

Therefore, for every $\lambda > 1$, we have by (3.1)

$$\sum_{i=1}^{\ell} \lambda^{-i} \alpha(P_i) \leq 0, \quad \sum_{j=1}^m \lambda^j \beta(Q_j) \leq 0, \quad (3.6)$$

taking into account that $\lambda^{-i}(1 - \lambda^{-1}) > 0$, for $i = 1, \dots, \ell - 1$, and $\lambda^j(1 - \lambda^{-1}) > 0$, for $j = 2, \dots, m$. Thus, for every $\lambda > 1$, we obtain $\mu(M(\lambda)) \leq 0$ and in consequence

$$\mu(M(\lambda)) < \lambda - 1. \quad (3.7)$$

Recalling now inequality (2.10), first observe that, analogously,

$$\begin{aligned} \sum_{i=1}^{\ell} \lambda^{-i} \beta(P_i) &= \sum_{i=1}^{\ell} \lambda^{-i} b(P_i) - \sum_{i=2}^{\ell} \lambda^{-(i-1)} b(P_i) \\ &= \lambda^{-1} b(P_1) + \sum_{i=2}^{\ell} \lambda^{-i} (1 - \lambda) b(P_i), \end{aligned} \quad (3.8)$$

$$\begin{aligned} \sum_{j=1}^m \lambda^j \alpha(Q_j) &= \sum_{j=1}^m \lambda^j a(Q_j) - \sum_{j=1}^{m-1} \lambda^{(j+1)} a(Q_j) \\ &= \lambda^m a(Q_m) + \sum_{j=1}^{m-1} \lambda^j (1 - \lambda) a(Q_j). \end{aligned} \quad (3.9)$$

Therefore, letting $0 < \lambda \leq 1$, (3.2) implies that

$$\sum_{i=1}^{\ell} \lambda^{-i} \beta(P_i) \leq \sum_{i=1}^{\ell} b(P_i) - \lambda \sum_{i=2}^{\ell} b(P_i), \quad (3.10)$$

since $\lambda^{-i} \geq 1$ for every $i = 1, \dots, \ell$. On the other hand, as $\lambda^j(1 - \lambda) \geq 0$ for every $j = 1, \dots, m - 1$, we have again by (3.2)

$$\sum_{j=1}^m \lambda^j \alpha(Q_j) \leq 0. \quad (3.11)$$

Thus

$$\mu(M(\lambda)) \leq \sum_{i=1}^{\ell} b(P_i) - \lambda \sum_{i=2}^{\ell} b(P_i), \quad (3.12)$$

for every $0 < \lambda \leq 1$. If the sum $\sum_{i=2}^{\ell} b(P_i) = 0$, then we obtain by (3.3)

$$\mu(M(\lambda)) \leq \sum_{i=1}^{\ell} b(P_i) \leq -1 < \lambda - 1 \quad (3.13)$$

for every $0 < \lambda \leq 1$. Otherwise the right-hand term of (3.12) is the straight line determined by the points $(0, \sum_{i=1}^{\ell} b(P_i))$ and $((\sum_{i=1}^{\ell} b(P_i))/(\sum_{i=2}^{\ell} b(P_i)), 0)$, which stays under the straight line $\lambda - 1$ when λ runs the interval $]0, 1]$, taking into account (3.3) and that $(\sum_{i=1}^{\ell} b(P_i))/(\sum_{i=2}^{\ell} b(P_i)) > 1$. Hence, for every $0 < \lambda \leq 1$,

$$\mu(M(\lambda)) < \lambda - 1. \tag{3.14}$$

Thus (1.1) is oscillatory and the proof is complete. □

THEOREM 3.2. *Under (3.1) and (3.2), with $b(P_1) < 0$, if*

$$\left(m \frac{a(Q_m)}{b(P_1)} \right)^{1/(m+1)} b(P_1) \left(\frac{1}{m} + 1 \right) \leq -1, \tag{3.15}$$

then (1.1) is oscillatory.

Proof. For $\lambda > 1$, one can follow the proof of Theorem 3.1.

Let now $0 < \lambda \leq 1$. The equalities

$$\begin{aligned} \sum_{i=1}^{\ell} \lambda^{-i} \beta(P_i) &= \lambda^{-1} b(P_1) + \sum_{i=2}^{\ell} \lambda^{-i} (1 - \lambda) b(P_i), \\ \sum_{j=1}^m \lambda^j \alpha(Q_j) &= \lambda^m a(Q_m) + \sum_{j=1}^{m-1} \lambda^j (1 - \lambda) a(Q_j) \end{aligned} \tag{3.16}$$

imply

$$\mu(M(\lambda)) \leq \lambda^{-1} b(P_1) + \lambda^m a(Q_m), \tag{3.17}$$

for every real $0 < \lambda \leq 1$. The function

$$g(\lambda) = \lambda^{-1} b(P_1) + \lambda^m a(Q_m) \tag{3.18}$$

is strictly concave and

$$g(\lambda) \leq \left(m \frac{a(Q_m)}{b(P_1)} \right)^{1/(m+1)} b(P_1) \left(\frac{1}{m} + 1 \right) \tag{3.19}$$

for every real λ . Then by (3.15),

$$\mu(M(\lambda)) \leq -1 < \lambda - 1, \tag{3.20}$$

for every $0 < \lambda \leq 1$, and (1.1) is oscillatory. □

14 Oscillatory mixed difference systems

THEOREM 3.3. *If for every $i = 1, \dots, \ell$ and $j = 1, \dots, m$,*

$$a(-P_i) \leq 0, \quad b(-Q_j) \leq 0, \quad (3.21)$$

$$a(-Q_j) \leq 0, \quad b(-P_i) \leq 0, \quad (3.22)$$

$$b(-Q_1) < 0, \quad \sum_{j=1}^m b(-Q_j) \leq -1, \quad (3.23)$$

then (1.1) is oscillatory.

Proof. By (3.4) and (3.5), one has, for every real λ ,

$$\begin{aligned} \mu(-M(\lambda)) &\leq \sum_{i=1}^{\ell-1} \lambda^{-i} (1 - \lambda^{-1}) a(-P_i) + \lambda^{-\ell} a(-P_\ell) \\ &\quad + \lambda b(-Q_1) + \sum_{j=2}^m \lambda^j (1 - \lambda^{-1}) b(-Q_j). \end{aligned} \quad (3.24)$$

If $\lambda \geq 1$, we have by (3.21)

$$\mu(-M(\lambda)) \leq \lambda \sum_{j=1}^m b(-Q_j) - \sum_{j=2}^m b(-Q_j), \quad (3.25)$$

since $\lambda^j \geq \lambda$ for every $\lambda \geq 1$. If $\sum_{j=2}^m b(-Q_j) = 0$, then

$$\mu(-M(\lambda)) \leq \lambda \sum_{j=1}^m b(-Q_j) \leq -\lambda < 1 - \lambda. \quad (3.26)$$

Otherwise, for $\lambda \geq 1$, the right-hand term of (3.25) is a half line passing through the point $((\sum_{j=2}^m b(-Q_j))/(\sum_{j=1}^m b(-Q_i)), 0)$, with a slope not larger than the slope of $1 - \lambda$. Then taking into account (3.23), one has

$$\frac{(\sum_{j=2}^m b(-Q_j))}{(\sum_{j=1}^m b(-Q_i))} < 1, \quad (3.27)$$

and consequently $\mu(-M(\lambda)) < 1 - \lambda$, for every $\lambda \geq 1$.

Let now $0 < \lambda < 1$. By (3.8) and (3.9), one obtains

$$\begin{aligned} \mu(-M(\lambda)) &\leq \lambda^{-1} b(-P_1) + \sum_{i=2}^{\ell} \lambda^{-i} (1 - \lambda) b(-P_i) \\ &\quad + \lambda^m a(-Q_m) + \sum_{j=1}^{m-1} \lambda^j (1 - \lambda) a(-Q_j), \end{aligned} \quad (3.28)$$

and by assumption (3.22), we have

$$\mu(-M(\lambda)) \leq 0 < 1 - \lambda \tag{3.29}$$

for every $0 < \lambda < 1$.

Thus (1.1) is oscillatory, which achieves the proof. □

The following example illustrates the use of these results.

Example 3.4. Consider now system (1.1) with $d = 2, \ell = m = 3$,

$$\begin{aligned} P_1 &= \begin{bmatrix} -\frac{2}{15} & -\frac{1}{15} \\ 1 & -5 \end{bmatrix}, & P_2 &= \begin{bmatrix} \frac{1}{15} & 0 \\ -1 & 2 \end{bmatrix}, & P_3 &= \begin{bmatrix} -\frac{1}{5} & 0 \\ -2 & -6 \end{bmatrix}, \\ Q_1 &= \begin{bmatrix} -15 & 0 \\ 1 & -11 \end{bmatrix}, & Q_2 &= \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix}, & Q_3 &= \begin{bmatrix} -6 & -1 \\ -1 & -10 \end{bmatrix}. \end{aligned} \tag{3.30}$$

By use of the logarithmic norm μ_∞ , we obtain

$$\begin{aligned} a(P_2) = a(Q_2) = 0, & \quad a(P_3) = b(P_3) = b(P_1) = -\frac{1}{5}, & \quad a(Q_3) = b(Q_1) = -19, \\ b(Q_2) = -4, b(Q_3) = -5, & \quad a(Q_1) = -3, & \quad b(P_2) = -\frac{2}{15}, & \quad a(P_1) = -\frac{1}{15}. \end{aligned} \tag{3.31}$$

The condition (3.15) is satisfied, since its left-hand term is equal to

$$\left(3\frac{19}{-1/5}\right)^{1/4} \left(-\frac{1}{5}\right) \left(\frac{1}{3} + 1\right) = -\frac{4}{15} \sqrt[4]{285} \approx -1.0957. \tag{3.32}$$

Then the correspondent system (1.1) is oscillatory.

Notice that for this system, Theorem 2.1, Corollary 2.2, and Theorems 2.3 and 3.1 cannot be used since

$$\begin{aligned} \alpha(P_3) &= a(P_3) - a(P_2) = \frac{1}{5}, \\ b(P_1) + b(P_2) + b(P_3) &= -\frac{1}{5} - \frac{2}{15} - \frac{1}{5} = -\frac{8}{15}. \end{aligned} \tag{3.33}$$

By use of inequalities (1.12), from Theorems 3.1 and 3.3, one can state results involving only the logarithmic norm μ . However, such results are less general than those already described in Section 2. Nevertheless, for the scalar equation (2.41), the correspondent results involving the measures a and b are more general than those obtained with the measures α and β . In fact, notice that for any given finite sequence of real numbers, c_1, \dots, c_r ,

we have

$$\begin{aligned}
 a(c_k) &= \sum_{i=1}^k c_i, & b(c_k) &= \sum_{i=k}^{\nu} c_i, \\
 \sum_{k=1}^{\nu} a(c_k) &= \nu c_1 + (\nu-1)c_2 + \cdots + 2c_{\nu-1} + c_{\nu} = \sum_{k=1}^{\nu} (\nu-k+1)c_k, & (3.34) \\
 \sum_{k=1}^{\nu} b(c_k) &= \nu c_{\nu} + (\nu-1)c_{\nu-1} + \cdots + 2c_2 + c_1 = \sum_{k=1}^{\nu} kc_k.
 \end{aligned}$$

Moreover, for the finite sequence, $-c_1, \dots, -c_{\nu}$, one has

$$a(-c_k) = -a(c_k), \quad b(-c_k) = -b(c_k), \quad (3.35)$$

and consequently

$$\sum_{k=1}^{\nu} a(-c_k) = -\sum_{k=1}^{\nu} (\nu-k+1)c_k, \quad \sum_{k=1}^{\nu} b(-c_k) = -\sum_{k=1}^{\nu} kc_k. \quad (3.36)$$

Therefore Theorems 3.1, 3.2, and 3.3 can be, respectively, rewritten, as the following corollaries.

COROLLARY 3.5. *If*

$$\begin{aligned}
 a(p_i) &= \sum_{k=1}^i p_k \leq 0, & b(p_i) &= \sum_{k=i}^{\ell} p_k \leq 0, & \text{for every } i &= 1, \dots, \ell, \\
 a(q_j) &= \sum_{k=1}^j q_k \leq 0, & b(q_j) &= \sum_{k=j}^m q_k \leq 0, & \text{for every } j &= 1, \dots, m, \\
 & & \sum_{i=1}^{\ell} p_i &< 0,
 \end{aligned} \quad (3.37)$$

and either

$$\sum_{i=1}^{\ell} ip_i \leq -1, \quad (3.38)$$

or

$$\left(m \frac{\sum_{j=1}^m q_j}{\sum_{i=1}^{\ell} p_i} \right)^{1/(m+1)} \left(\sum_{i=1}^{\ell} p_i \right) \left(\frac{1}{m} + 1 \right) \leq -1, \quad (3.39)$$

then (2.41) is oscillatory.

COROLLARY 3.6. *If for every $i = 1, \dots, \ell$ and $j = 1, \dots, m$,*

$$a(p_i) = \sum_{k=1}^i p_k \geq 0, \quad b(p_i) = \sum_{k=i}^{\ell} p_k \geq 0, \quad \text{for every } i = 1, \dots, \ell, \quad (3.40)$$

$$a(q_j) = \sum_{k=1}^j q_k \geq 0, \quad b(q_j) = \sum_{k=j}^m q_k \geq 0, \quad \text{for every } j = 1, \dots, m, \quad (3.41)$$

$$\sum_{j=1}^m q_j > 0, \quad \sum_{j=1}^m j q_j \geq 1, \quad (3.42)$$

then (2.41) is oscillatory.

Example 3.7. The equation

$$\Delta x(n) = -x(n-3) + x(n-2) - x(n-1) - x(n+2) \quad (3.43)$$

is oscillatory, by Corollary 3.5 through condition (3.38).

Example 3.8. Still by Corollary 3.5, the equation

$$\Delta x(n) = -\frac{1}{10}x(n-3) - \frac{1}{5}x(n-1) - 3x(n+1) - 5x(n+2) \quad (3.44)$$

is oscillatory through condition (3.39) since

$$\left(2\frac{-8}{-3/10}\right)\left(-\frac{3}{10}\right)\left(\frac{1}{3}+1\right) \approx -1.5057. \quad (3.45)$$

(Notice that condition (3.38) is not fulfilled in this case.)

Example 3.9. The equation

$$\Delta x(n) = 3x(n-3) - x(n-2) + 2x(n-1) + x(n+1) - x(n+2) + x(n+3) \quad (3.46)$$

is oscillatory, by Corollary 3.6.

Acknowledgment

The research of the first author was supported in part by FCT (Portugal).

References

- [1] R. P. Agarwal and S. R. Grace, *The oscillation of certain difference equations*, Mathematical and Computer Modelling **30** (1999), no. 1-2, 53–66.
- [2] R. P. Agarwal, S. R. Grace, and D. O’Regan, *Oscillation Theory for Difference and Functional Differential Equations*, Kluwer Academic, Dordrecht, 2000.
- [3] Q. Chuanxi, S. A. Kuruklis, and G. Ladas, *Oscillations of linear autonomous systems of difference equations*, Applicable Analysis **36** (1990), no. 1-2, 51–63.

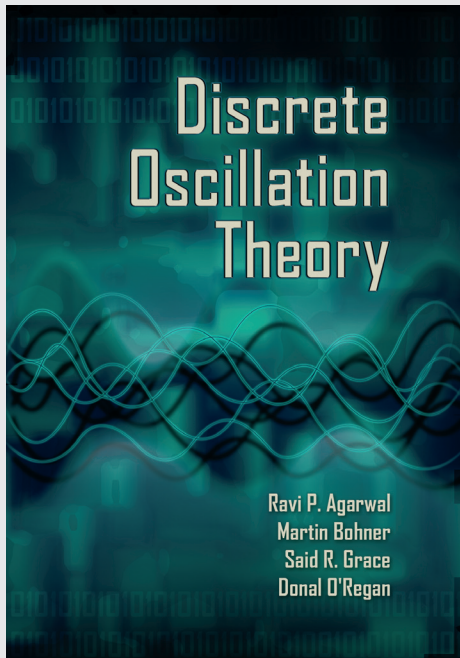
- [4] W. A. Coppel, *Stability and Asymptotic Behavior of Differential Equations*, D. C. Heath, Massachusetts, 1965.
- [5] C. A. Desoer and M. Vidyasagar, *Feedback Systems: Input-Output Properties*, Academic Press, New York, 1975.
- [6] J. M. Ferreira and A. M. Pedro, *Oscillations of delay difference systems*, Journal of Mathematical Analysis and Applications **221** (1998), no. 1, 364–383.
- [7] J. M. Ferreira and S. Pinelas, *Oscillatory retarded functional systems*, Journal of Mathematical Analysis and Applications **285** (2003), no. 2, 506–527.
- [8] I. Györi and G. Ladas, *Oscillation Theory of Delay Differential Equations*, Oxford Mathematical Monographs, Oxford University Press, New York, 1991.
- [9] I. Györi, G. Ladas, and L. Pakula, *Conditions for oscillation of difference equations with applications to equations with piecewise constant arguments*, SIAM Journal on Mathematical Analysis **22** (1991), no. 3, 769–773.
- [10] J. Kirchner and U. Stroinski, *Explicit oscillation criteria for systems of neutral differential equations with distributed delay*, Differential Equations and Dynamical Systems **3** (1995), no. 1, 101–120.
- [11] T. Krisztin, *Nonoscillation for functional differential equations of mixed type*, Journal of Mathematical Analysis and Applications **245** (2000), no. 2, 326–345.

José M. Ferreira: Departamento de Matemática, Instituto Superior Técnico, Avenida Rovisco Pais, 1049-001 Lisboa, Portugal
E-mail address: jferr@math.ist.utl.pt

Sandra Pinelas: Departamento de Matemática, Universidade dos Açores, Rua Mãe de Deus, 9500-321 Ponta Delgada, Portugal
E-mail address: spinelas@notes.uac.pt

DISCRETE OSCILLATION THEORY

Ravi P. Agarwal, Martin Bohner, Said R. Grace, and Donal O'Regan



This book is devoted to a rapidly developing branch of the qualitative theory of difference equations with or without delays. It presents the theory of oscillation of difference equations, exhibiting classical as well as very recent results in that area. While there are several books on difference equations and also on oscillation theory for ordinary differential equations, there is until now no book devoted solely to oscillation theory for difference equations. This book is filling the gap, and it can easily be used as an encyclopedia and reference tool for discrete oscillation theory.

In nine chapters, the book covers a wide range of subjects, including oscillation theory for second-order linear difference equations, systems of difference equations, half-linear difference equations, nonlinear difference equations, neutral difference equations, delay difference equations, and differential equations with piecewise constant arguments. This book summarizes almost 300 recent research papers and hence covers all aspects of discrete oscillation theory that have been discussed in recent journal articles. The presented

theory is illustrated with 121 examples throughout the book. Each chapter concludes with a section that is devoted to notes and bibliographical and historical remarks.

The book is addressed to a wide audience of specialists such as mathematicians, engineers, biologists, and physicists. Besides serving as a reference tool for researchers in difference equations, this book can also be easily used as a textbook for undergraduate or graduate classes. It is written at a level easy to understand for college students who have had courses in calculus.

For more information and online orders please visit <http://www.hindawi.com/books/cmia/volume-1>
For any inquires on how to order this title please contact books.orders@hindawi.com

"Contemporary Mathematics and Its Applications" is a book series of monographs, textbooks, and edited volumes in all areas of pure and applied mathematics. Authors and/or editors should send their proposals to the Series Editors directly. For general information about the series, please contact cmia.ed@hindawi.com.