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# EQUIVALENCE BETWEEN K-FUNCTIONALS BASED ON CONTINUOUS LINEAR TRANSFORMS 

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Dedicated to Academician Blagovest Sendov on occasion of his 75th birthday
Abstract. The paper presents a method of relating two $K$-functionals by means of a continuous linear transform of the function. In particular, a characterization of various weighted $K$-functionals by unweighted fixed-step moduli of smoothness is derived. This is applied in estimating the rate of convergence of several approximation processes.

## 1. $\boldsymbol{K}$-functionals in measuring the approximation error. Fin-

 ding a good estimate of the error of a given approximation process is a basic problem in approximation theory. The so called $K$-functional turned out to be[^0]very useful in this respect. It has been introduced by Lions and by Peetre and in its present form by Peetre [28], as a basis of the theory of interpolation of operators (e.g. [2, Ch. 5]). Later Butzer and Berens [4] clarified its importance in approximation theory.

Let $X$ be a Banach space with norm $\|\cdot\|_{X}$ and $Y$ be another space with a semi-norm $|\cdot|_{Y}$. For $f \in X$ and $t>0$ we define the $K$-functional between the spaces $X$ and $Y$ by

$$
\begin{equation*}
K(f, t ; X, Y)=\inf \left\{\|f-g\|_{X}+t|g|_{Y}: g \in Y \cap X\right\} . \tag{1.1}
\end{equation*}
$$

Usually $Y$ is a dense subspace of $X$ and consists of elements that possess certain additional properties as, for example, high smoothness. As it is seen from its definition the $K$-functional measures how well a given function $f \in X$ can be approximated by elements $g \in Y$ with control of their semi-norm $|g|_{Y}$. For given $f \in X$ the $K$-functional is a non-negative and non-decreasing function of $t$. Thus, $\lim _{t \rightarrow 0+} K(f, t ; X, Y)$ always exists. Moreover, this limit is 0 for every $f \in X$ iff $Y$ is dense in $X$.

For many applications in approximation theory $X$ is a weighted $L_{p}$-space $L_{p}(w)(I)=\left\{f \in L_{1, l o c}(I): w f \in L_{p}(I)\right\}, 1 \leq p \leq \infty$, with a norm $\|f\|_{X}=$ $\|w f\|_{p(I)}$ and $Y$ is a weighted Sobolev space $W_{p}^{r}(\phi)(I)=\left\{g \in A C_{l o c}^{r-1}(I): \phi g^{(r)} \in\right.$ $\left.L_{p}(I)\right\}$ with a semi-norm $|g|_{Y}=\left\|\phi g^{(r)}\right\|_{p(I)}$, where $I$ is an interval on the real line and $w, \phi$ are measurable on it with singularities only at its ends.

A standard application of the $K$-functional is the direct theorem for the error of an approximation process. If $\left\{\mathcal{L}_{\alpha}\right\}_{\alpha \in A}$ is a family of linear operators that maps the Banach space $X$ into itself such that
a) $\left\|\mathcal{L}_{\alpha} f\right\|_{X} \leq c\|f\|_{X}$ for every $f \in X$ and $\alpha \in A$,
b) $\left\|g-\mathcal{L}_{\alpha} g\right\|_{X} \leq c \theta(\alpha)|g|_{Y}$ for every $g \in Y$ and $\alpha \in A$ with $\theta: A \rightarrow \mathcal{R}_{+}$, then for every $f \in X$ and $\alpha \in A$ there holds the estimate

$$
\begin{equation*}
\left\|f-\mathcal{L}_{\alpha} f\right\|_{X} \leq c K(f, \theta(\alpha) ; X, Y) \tag{1.2}
\end{equation*}
$$

Above and in what follows we denote by $c$ positive constants not necessarily the same on each occurrence that do not depend on the function $f$ and the parameter $t$ in the $K$-functional.

Usually the estimates converse to (1.2) are of weak type but in a number of cases connected with saturated approximation processes strong type inverse inequalities can be established. Let $\mathcal{D}$ be a differential operator, $Y=\{g \in X$ :
$\mathcal{D} g \in X\}$ and $|g|_{Y}=\|\mathcal{D} g\|_{X}$. Ditzian and Ivanov proved in [9] that the inverse inequality to (1.2)

$$
\begin{equation*}
K(f, \theta(\alpha) ; X, Y) \leq c\left\|f-\mathcal{L}_{\alpha} f\right\|_{X} \tag{1.3}
\end{equation*}
$$

follows from a) and the inequalities:
c) $\left\|g-\mathcal{L}_{\alpha} g-\theta(\alpha) \mathcal{D} g\right\|_{X} \leq \psi(\alpha)|g|_{Z}$ for every $g \in Z$,
d) $\left\|\mathcal{D} \mathcal{L}_{\alpha}^{k} f\right\|_{X} \leq \frac{c}{\theta(\alpha)}\|f\|_{X}$ for every $f \in X$,
e) $\left|\mathcal{L}_{\alpha}^{\ell} g\right|_{Z} \leq M \frac{\theta(\alpha)}{\psi(\alpha)}\left\|\mathcal{D} \mathcal{L}_{\alpha}^{k} g\right\|_{X}$ for every $g \in X$,
where $Z \subset X, \theta: A \rightarrow \mathcal{R}_{+}$is bounded, $\psi: A \rightarrow \mathcal{R}_{+}, k, \ell \in \mathcal{N}, k \leq \ell$, and $M<1$ is a constant.

Thus, inequalities (1.2) and (1.3) imply that the approximation error and the $K$-functional are equivalent, which we denote by

$$
\begin{equation*}
\left\|f-\mathcal{L}_{\alpha} f\right\|_{X} \sim K(f, \theta(\alpha) ; X, Y) \tag{1.4}
\end{equation*}
$$

So, using $K$-functionals we can derive an estimate of the approximation error from several inequalities. However, let us note that in general it is difficult to establish some of inequalities c)-e), especially e) with a small constant on the right-hand side. The error estimates through $K$-functionals are of high importance in approximation theory but they solely are of little effectiveness because it is difficult to evaluate for a given $f$ and every $t \in\left(0, t_{0}\right.$ ] the infimum on the wide space $Y$. This shortcoming can be overcome by defining a new functional characteristic $\Omega(f, t)$, called modulus of smoothness, which is equivalent to the $K$-functional. The modulus of smoothness depends on $f$ more directly and can be more easily estimated being a supremum or an average on a neighbourhood of the origin in a finite dimensional space.
2. Moduli of smoothness. Let $X=L_{p}(I), I \subseteq \mathcal{R}$ is an interval, $1 \leq p \leq \infty$, with the usual $L_{p}$-norm on the interval $I$, and $Y=W_{p}^{r}(I)=\{g \in$ $\left.A C_{l o c}^{r-1}(I): g^{(r)} \in L_{p}(I)\right\}$ - the Sobolev space with the semi-norm $|g|_{W_{p}^{r}(I)}=$ $\left\|g^{(r)}\right\|_{p(I)}$. It is well known (see $[24,25]$ ) that for every $f \in L_{p}(I)$ and $0<t \leq t_{0}$ we have

$$
\begin{equation*}
K\left(f, t^{r} ; L_{p}(I), W_{p}^{r}(I)\right) \sim \omega_{r}(f, t)_{p(I)} \tag{2.1}
\end{equation*}
$$

where $\omega_{r}(f, t)_{p(I)}$ is the classical unweighted fixed-step modulus of smoothness of order $r$ of the function $f$, namely,

$$
\omega_{r}(f, t)_{p(I)}=\sup _{0<h \leq t}\left\|\Delta_{h}^{r} f\right\|_{p(I)}
$$

and $\Delta_{h}^{r} f(x)$ is the finite difference of the function $f$ of order $r$ and step $h$. We assume that $\Delta_{h}^{r} f(x)=0$ if the argument of any of the summands of the finite differences $\Delta_{h}^{r} f(x)$ is outside $I$. Thus, if we consider, for example, symmetric finite differences:

$$
\begin{equation*}
\Delta_{h}^{r} f(x)=\sum_{k=0}^{r}(-1)^{k}\binom{r}{k} f(x+(r / 2-k) h) \tag{2.2}
\end{equation*}
$$

of functions $f \in L_{p}[a, b]$, where $[a, b]$ is a finite interval, we have

$$
\omega_{r}(f, t)_{p[a, b]}=\sup _{0<h \leq t}\left\|\Delta_{h}^{r} f\right\|_{p[a+r h / 2, b-r h / 2]}
$$

We also set $\omega_{0}(f, t)_{p(I)}=\|f\|_{p(I)}$. Let us note that for $2 \pi$-periodic functions the $r$-th modulus $\omega_{r}(f, t)_{p, 2 \pi}$ is defined in a slightly different way - the norm is taken on an arbitrary period but the convention for vanishing of the finite difference is not applied.

Let $w$ and $\varphi$ be power-type weights with singularities only at the ends of the interval $I \subseteq \mathcal{R}$. Ditzian and Totik [10, pp. 56, 218] introduced the varyingstep moduli of smoothness, which for a finite interval $I=[a, b]$ are defined by

$$
\begin{align*}
\omega_{\varphi}^{r}(f, t)_{w, p[a, b]}= & \sup _{0<h \leq t}\left\|w \Delta_{h \varphi}^{r} f\right\|_{p\left[a+t_{a}^{*}, b-t_{b}^{*}\right]}  \tag{2.3}\\
& +\sup _{0<h \leq t_{a}^{*}}\left\|w \vec{\Delta}_{h}^{r} f\right\|_{p\left[a, a+12 t_{a}^{*}\right]}+\sup _{0<h \leq t_{b}^{*}}\left\|w \overleftarrow{\Delta}_{h}^{r} f\right\|_{p\left[b-12 t_{b}^{*}, b\right]}
\end{align*}
$$

where $\vec{\Delta}_{h}^{r}$ and $\overleftarrow{\Delta}_{h}^{r}$ denote forward and backward $r$-th finite differences respectively and $t_{a}^{*}, t_{b}^{*}$ are functions of $t$ and $r$ depending on the behavior of $\varphi$ at the respective end-points.

Under certain conditions, the most important of which are the "finite overlapping condition" on $\varphi$ and the boundness of $w$ at a finite end-point of $I$, Ditzian and Totik proved in [10, Ch. 2 and Ch. 6] the equivalence

$$
K\left(f, t^{r} ; L_{p}(w)(I), W_{p}^{r}\left(w \varphi^{r}\right)(I)\right) \sim \omega_{\varphi}^{r}(f, t)_{w, p(I)}
$$

where the $K$-functional is defined for $X=L_{p}(w)(I), 1 \leq p \leq \infty$, and $Y=$ $W_{p}^{r}\left(w \varphi^{r}\right)(I)$ with the semi-norm $|g|_{W_{p}^{r}\left(w \varphi^{r}\right)(I)}=\left\|w \varphi^{r} g^{(r)}\right\|_{p(I)}$.

On the other hand, the second author introduced the following moduli of smoothness

$$
\begin{equation*}
\tau_{r}(f ; \psi(t))_{q, p(I)}=\left\|\omega_{r}(f, \cdot ; \psi(t, \cdot))_{q}\right\|_{p(I)} \tag{2.4}
\end{equation*}
$$

where the local moduli are given by

$$
\begin{aligned}
\omega_{r}(f, x ; \psi(t, x))_{q} & =\left((2 \psi(t, x))^{-1} \int_{-\psi(t, x)}^{\psi(t, x)}\left|\Delta_{h}^{r} f(x)\right|^{q} d h\right)^{1 / q}, 1 \leq q<\infty \\
\omega_{r}(f, x ; \psi(t, x))_{\infty} & =\sup \left\{\left|\Delta_{h}^{r} f(x)\right|:|h| \leq \psi(t, x)\right\}
\end{aligned}
$$

and $\psi$ is a continuous function connected with $\varphi$ in a certain way (see [21, 22]). Under certain conditions on $\varphi$ (see [22]), Ivanov proved the relation

$$
K\left(f, t^{r} ; L_{p}(I), W_{p}^{r}\left(\varphi^{r}\right)(I)\right) \sim \tau_{r}(f ; \psi(t))_{p, p(I)}
$$

The power and logarithmic-type weights $\varphi$ are covered. The first characterization, based on the standard translation operator, of the best approximations in $L_{p}[a, b]$, $1 \leq p \leq \infty$, by algebraic polynomials was established in the terms of $\tau$-moduli [21].

Let us also mention that Ky [27] defined moduli through which he characterized $K$-functionals of the type (1.1) with $X=L_{p}(w)(I), I \subseteq \mathcal{R}$ is an interval, $1 \leq p \leq \infty$, and $Y=W_{p}^{r}(w)(I)$, where the weight $w$ is bounded and satisfies certain monotonicity requirements near the end-points of the interval.
M. K. Potapov (see [29] and the references cited there) characterized the $K$-functional (1.1) with $X=L_{p}(w)[-1,1]$ with Jacobean weight $w$, and $Y=\{g \in$ $\left.A C_{l o c}^{2 r-1}[-1,1]: D_{\nu, \mu}^{r} g \in L_{p}[-1,1]\right\}$ with the semi-norm $|g|_{Y}=\left\|D_{\nu, \mu}^{r} g\right\|_{p[-1,1]}$, where

$$
D_{\nu, \mu}=(1-x)^{-\nu}(1+x)^{-\mu} \frac{d}{d x}(1-x)^{\nu+1}(1+x)^{\mu+1} \frac{d}{d x}
$$

is the Jacobean differential operator. The moduli introduced by Potapov are based on generalized translation operators.

Also Butzer, Stens and Wehrens [3, 5, 6] defined moduli of smoothness by means of multipliers and generalized translations to characterize the best weighted algebraic approximation with Jacobean weights.
3. Equivalence between $\boldsymbol{K}$-functionals. The main purpose of this paper is to present a general approach to establishing equivalence between two $K$-functionals of the type:

$$
K\left(f, t ; X_{1}, Y_{1}\right) \sim K\left(\mathcal{A} f, t ; X_{2}, Y_{2}\right)
$$

where $\mathcal{A}: X_{1} \rightarrow X_{2}$ is a bounded linear operator. Hence, in view of (2.1) for $X_{2}=L_{p}(I), Y_{2}=W_{p}^{r}(I),|G|_{W_{p}^{r}(I)}=\left\|G^{(r)}\right\|_{p(I)}, I \subseteq \mathcal{R}$ is an interval, we get the following characterization of the $K$-functional $K\left(f, t ; X_{1}, Y_{1}\right)$ by means of the unweighted fixed step-modulus of smoothness:

$$
K\left(f, t^{r} ; X_{1}, Y_{1}\right) \sim \omega_{r}(\mathcal{A} f, t)_{p(I)}
$$

We have (cf. [16, Definition 2.1 and Proposition 2.1] and [13, Definition 1.1 and Proposition 2.1])

Theorem 3.1. If there exists a linear operator $\mathcal{B}: X_{2} \rightarrow X_{1}$, related to $\mathcal{A}: X_{1} \rightarrow X_{2}$, and both operators satisfy the conditions:
a) $\|\mathcal{A} f\|_{X_{2}} \leq c\|f\|_{X_{1}}$ for every $f \in X_{1}$;
b) $\mathcal{A} g \in Y_{2} \cap X_{2}$ and $|\mathcal{A} g|_{Y_{2}} \leq c|g|_{Y_{1}}$ for every $g \in Y_{1} \cap X_{1}$;
c) $\|\mathcal{B} F\|_{X_{1}} \leq c\|F\|_{X_{2}}$ for every $F \in X_{2}$;
d) $\mathcal{B} G \in Y_{1} \cap X_{1}$ and $|\mathcal{B} G|_{Y_{1}} \leq c|G|_{Y_{2}}$ for any $G \in Y_{2} \cap X_{2}$;
e) $|f-\mathcal{B} \mathcal{A} f|_{Y_{1}}=0$ for every $f \in X_{1}$;
f) $|F-\mathcal{A B} F|_{Y_{2}}=0$ for every $F \in X_{2}$.

Then

$$
\begin{equation*}
K\left(f, t ; X_{1}, Y_{1}\right) \sim K\left(\mathcal{A} f, t ; X_{2}, Y_{2}\right) \tag{3.1}
\end{equation*}
$$

and

$$
K\left(F, t ; X_{2}, Y_{2}\right) \sim K\left(\mathcal{B} F, t ; X_{1}, Y_{1}\right)
$$

Remark 3.1. Let us note that to get only (3.1) it is sufficient condition f) to be fulfilled only for $F \in \mathcal{A}\left(X_{1}\right)$.

In some cases in order to apply Theorem 3.1 more effectively in establishing a characterization of $K$-functionals $K\left(f, t^{r} ; L_{p}(w)(I), W_{p}^{r}\left(w \varphi^{r}\right)(I)\right)$ by the unweighted fixed-step moduli we shall split the singularities of the weights. More precisely, let $-\infty \leq \bar{a}<a_{1}<b_{1}<\bar{b} \leq \infty, I=(\bar{a}, \bar{b}), I_{1}=\left(\bar{a}, b_{1}\right)$ and $I_{2}=\left(a_{1}, \bar{b}\right)$. Let $w$ and $\varphi$ be non-negative measurable on $I$ weights such that $w \sim 1$ and $\varphi \sim 1$
on $\left[a_{1}, b_{1}\right]$. Then for $r \in \mathcal{N}, 1 \leq p \leq \infty, 0<t \leq b_{1}-a_{1}$ and $f \in L_{p}(w)(I)$ we have (cf. [8, p. 176, Lemma 2.3] and [16, Lemma 7.1]):

$$
\begin{align*}
K\left(f, t ; L_{p}(w)(I), W_{p}^{r}\left(w \varphi^{r}\right)(I)\right) & \sim K\left(f, t ; L_{p}(w)\left(I_{1}\right), W_{p}^{r}\left(w \varphi^{r}\right)\left(I_{1}\right)\right) \\
& +K\left(f, t ; L_{p}(w)\left(I_{2}\right), W_{p}^{r}\left(w \varphi^{r}\right)\left(I_{2}\right)\right) \tag{3.2}
\end{align*}
$$

Above we have used one and the same notation for the function $f$ and for its restrictions on subdomains.

Let us note that in the applications we require operator $\mathcal{A}$ from Theorem 3.1 to be constructed explicitly and the computations of $\omega_{r}(\mathcal{A} f, t)_{p}$ and $\omega_{r}(f, t)_{p}$ to be equally difficult. The latter means that the operations in constructing $\mathcal{A}$ are addition and multiplication by elementary functions, change of the variable by elementary functions and integration.
4. Application. Now, we give several applications of Theorem 3.1 in establishing characterizations of $K$-functionals in terms of the unweighted fixedstep moduli of smoothness.

Let us consider the $K$-functional

$$
\begin{align*}
& K\left(f, t ; L_{p}(w)(I), W_{p}^{r}\left(w \varphi^{r}\right)(I)\right)  \tag{4.1}\\
& \quad=\inf \left\{\|w(f-g)\|_{p(I)}+t\left\|w \varphi^{r} g^{(r)}\right\|_{p(I)}: g \in A C_{l o c}^{r-1}(I)\right\}
\end{align*}
$$

The domain $I$ may be finite, semi-infinite or infinite, represented respectively by $I=[a, b], I=[a, \infty)$ and $I=(-\infty, \infty)$. To define the weights $w$ and $\varphi$ we set $\chi_{\xi}(x)=|x-\xi|$ for a real number $\xi$. For a finite domain $I=[a, b]$ we consider the weights $w=\chi_{a}^{\gamma_{a}} \chi_{b}^{\gamma_{b}}$ and $\varphi=\chi_{a}^{\lambda_{a}} \chi_{b}^{\lambda_{b}}$ with $\gamma_{a}, \gamma_{b}, \lambda_{a}, \lambda_{b} \in \mathcal{R}$. For a semiinfinite domain $I=[a, \infty)$ we consider the weights $w=\chi_{a}^{\gamma_{a}} \chi_{a-1}^{\gamma_{\infty}-\gamma_{a}}$ (note that $w(x) / x^{\gamma_{\infty}} \rightarrow 1$ for $\left.x \rightarrow \infty\right)$ and $\varphi=\chi_{a}^{\lambda_{a}} \chi_{a-1}^{\lambda_{\infty}-\lambda_{a}}$ with $\gamma_{a}, \gamma_{\infty}, \lambda_{a}, \lambda_{\infty} \in \mathcal{R}$. For the infinite domain $I=(-\infty, \infty)$ we apply (3.2) to reduce the case to semi-infinite domain.

It is demonstrated in [16] that the case $\lambda_{a}>1$ with a finite end-point $a$ of the domain $I$ is equivalent to the case $\lambda_{\infty}<1$ (transfer to infinite endpoint), as well as the case $\lambda_{\infty}>1$ is equivalent to the case $\lambda_{a}<1$. So the two main cases in characterization of the $K$-functional (4.1) are i) $\lambda_{a}<1$ and $\lambda_{\infty}<1$ (see Subsection 4.1) and ii) $\lambda_{a}=1$ and $\lambda_{\infty}=1$ (see Subsection 4.2). In order to solve the first case we apply power change of the variable and for the second case - exponential change of the variable. In the remaining subsections
we consider applications in which the differential operator $\varphi^{r} D^{r}$ determining the second term of the $K$-functional is replaced by a linear differential operator of the form $P(D)$, where $P$ is a polynomial with constant coefficients in Subsection 4.3 or with varying coefficients in Subsection 4.4.

Also to describe the restrictions on the powers $\gamma_{a}, \gamma_{b}$ or $\gamma_{\infty}$ of the weight $w$ we set for $r \in \mathcal{N}$ and $1 \leq p \leq \infty$

$$
\begin{aligned}
& \Gamma_{+}(p)=(-1 / p, \infty), p<\infty, \text { and } \Gamma_{+}(\infty)=[0, \infty) \\
& \Gamma_{0}(p)=(-1 / p, \infty) ; \\
& \Gamma_{i}(p)=(-i-1 / p, 1-i-1 / p), \quad i=1, \ldots, r-1 \\
& \Gamma_{r}(p)=(-\infty, 1-r-1 / p) \\
& \Gamma_{e x c}(p)=\{1-r-1 / p, 2-r-1 / p, \ldots,-1 / p\}
\end{aligned}
$$

4.1. Power change of the variable. $K$-functionals with $\lambda_{a}<1$ and/or $\lambda_{\infty}<1$ are related to the best approximation by algebraic polynomials on a finite interval, to the approximation error of the Bernstein, Szasz-Mirakian and Baskakov operators, etc. [10, 21, 26, 31].

Let $r \in \mathcal{N}$ and $\xi \in(a, b)$. Let $s$ be one of the ends of the finite interval $[a, b]$ and $e-$ the other.

For $\rho \in \mathcal{R}, i \in \mathcal{N}_{0}, i \leq r, x \in(a, b)$ and $f \in L_{1, l o c}[a, b]$, satisfying the additional requirement $\chi_{s}^{-i+\rho} f \in L_{1}[s,(s+e) / 2]$ if $i>0$, we set

$$
\begin{aligned}
\left(A_{i}(\rho ; s, e ; \xi) f\right)(x)= & \left(\frac{x-s}{e-s}\right)^{\rho} f(x) \\
& +\frac{1}{e-s} \sum_{k=1}^{i} \alpha_{r, k}(\rho)\left(\frac{x-s}{e-s}\right)^{k-1} \int_{s}^{x}\left(\frac{y-s}{e-s}\right)^{-k+\rho} f(y) d y \\
& +\frac{1}{e-s} \sum_{k=i+1}^{r} \alpha_{r, k}(\rho)\left(\frac{x-s}{e-s}\right)^{k-1} \int_{\xi}^{x}\left(\frac{y-s}{e-s}\right)^{-k+\rho} f(y) d y
\end{aligned}
$$

where

$$
\alpha_{r, k}(\rho)=\frac{(-1)^{k}}{(r-1)!}\binom{r-1}{k-1} \prod_{\nu=0}^{r-1}(\rho+r-k-\nu), \quad k=1,2, \ldots, r .
$$

As usual, above and in what follows we assume that the sum is 0 if the upper bound is smaller than the lower.

For $\sigma>0, i \in \mathcal{N}, i \leq r, x \in(a, b)$ and $f \in L_{1, l o c}[a, b]$, satisfying the additional requirement $\chi_{s}^{(1-i) / \sigma-1} f \in L_{1}[s,(s+e) / 2]$ if $i>1$, we set

$$
\begin{aligned}
& \left(B_{i}(\sigma ; s, e ; \xi) f\right)(x)=f\left(s+(e-s)\left(\frac{x-s}{e-s}\right)^{\sigma}\right) \\
& +\frac{1}{e-s} \sum_{k=2}^{i} \beta_{r, k}(\sigma)\left(\frac{x-s}{e-s}\right)^{k-1} \int_{s}^{x}\left(\frac{y-s}{e-s}\right)^{-k} f\left(s+(e-s)\left(\frac{y-s}{e-s}\right)^{\sigma}\right) d y \\
& +\frac{1}{e-s} \sum_{k=i+1}^{r} \beta_{r, k}(\sigma)\left(\frac{x-s}{e-s}\right)^{k-1} \int_{\xi}^{x}\left(\frac{y-s}{e-s}\right)^{-k} f\left(s+(e-s)\left(\frac{y-s}{e-s}\right)^{\sigma}\right) d y
\end{aligned}
$$

where

$$
\beta_{r, k}(\sigma)=\frac{(-1)^{r-k}}{(r-2)!}\binom{r-2}{k-2} \prod_{i=1}^{r-1}(k-1-i \sigma), \quad k=2,3, \ldots, r
$$

By means of these operators and their modifications we can construct operators that satisfy Theorem 3.1 above for $K$-functionals $K\left(f, t ; L_{p}\left(\chi_{a}^{\gamma_{a}} \chi_{b}^{\gamma_{b}}\right)[a, b]\right.$, $\left.W_{p}^{r}\left(\chi_{a}^{\gamma_{a}+r \lambda_{a}} \chi_{b}^{\gamma_{b}+r \lambda_{b}}\right)[a, b]\right)$ with $\lambda_{a}, \lambda_{b} \neq 1$. For example, by Propositions 3.9 and 6.2 in [16] (cf. Theorem 6.1 there) we establish

Theorem 4.1. Let $r \in \mathcal{N}$ and $1 \leq p \leq \infty,\left(1-\lambda_{a}\right)\left(1-\nu_{a}\right)>0$, $\left(1-\lambda_{b}\right)\left(1-\nu_{b}\right)>0$. Let also $\kappa_{a}, \mu_{a}, \mu_{b} \notin \Gamma_{\text {exc }}(p)$ and $\kappa_{b} \in \Gamma_{0}(p)$. We set $w=\chi_{a}^{\kappa_{a}} \chi_{b}^{\kappa_{b}}, \varphi=\chi_{a}^{\lambda_{a}} \chi_{b}^{\lambda_{b}}, \tilde{w}=\chi_{a}^{\mu_{a}} \chi_{b}^{\mu_{b}}, \tilde{\varphi}=\chi_{a}^{\nu_{a}} \chi_{b}^{\nu_{b}}$ and

$$
\begin{aligned}
& \mathcal{A}=A_{i_{1}}(-\rho ; a, b ; \xi) A_{i_{2}}\left(-\rho_{b} ; b, a ; \xi\right) B_{1}\left(\sigma_{b}^{-1} ; b, a ; \xi\right) B_{1}\left(\sigma_{a} ; a, b ; \xi\right) A_{0}\left(\rho_{a} ; a, b ; \xi\right) \\
& \mathcal{B}=A_{i^{\prime}}\left(-\rho_{a} ; a, b ; \eta\right) B_{1}\left(\sigma_{a}^{-1} ; a, b ; \eta\right) B_{1}\left(\sigma_{b} ; b, a ; \eta\right) A_{0}\left(\rho_{b} ; b, a ; \eta\right) A_{0}(\rho ; a, b ; \eta)
\end{aligned}
$$

where $\xi, \eta \in(a, b), \rho<\mu_{a}+1 / p$, the integers $i_{1}, i_{2}, i^{\prime}$ are such that $\Gamma_{i_{1}}(p) \ni \mu_{a}$, $\Gamma_{i_{2}}(p) \ni \mu_{b}, \Gamma_{i^{\prime}}(p) \ni \kappa_{a}$, and

$$
\begin{aligned}
\sigma_{a} & =\frac{1-\nu_{a}}{1-\lambda_{a}}, \quad \sigma_{b}=\frac{1-\lambda_{b}}{1-\nu_{b}} \\
\rho_{a} & =\kappa_{a}+\frac{1}{p}-\frac{\mu_{a}-\rho+1 / p}{\sigma_{a}}, \quad \rho_{b}=\mu_{b}+\frac{1}{p}-\frac{\kappa_{b}+1 / p}{\sigma_{b}} .
\end{aligned}
$$

Then for $f \in L_{p}(w)[a, b]$ and $t>0$ we have

$$
K\left(f, t ; L_{p}(w)[a, b], W_{p}^{r}\left(w \varphi^{r}\right)[a, b]\right) \sim K\left(\mathcal{A} f, t ; L_{p}(\tilde{w})[a, b], W_{p}^{r}\left(\tilde{w} \tilde{\varphi}^{r}\right)[a, b]\right)
$$

and for $F \in L_{p}(\tilde{w})[a, b]$ and $t>0$ we have

$$
K\left(F, t ; L_{p}(\tilde{w})[a, b], W_{p}^{r}\left(\tilde{w} \tilde{\varphi}^{r}\right)[a, b]\right) \sim K\left(\mathcal{B} F, t ; L_{p}(w)[a, b], W_{p}^{r}\left(w \varphi^{r}\right)[a, b]\right)
$$

Remark 4.1. Interchanging $a$ and $b$ in the definition of $\mathcal{A}$ and $\mathcal{B}$ in the theorem above we get a similar relation between the $K$-functionals under the hypothesis that $\kappa_{a} \in \Gamma_{0}(p)$ and $\kappa_{b}, \mu_{a}, \mu_{b} \notin \Gamma_{e x c}(p)$.

Theorem 4.1 and (2.1) imply directly a characterization of the considered $K$-functional by the ordinary modulus of smoothness but here we present another one given in [16, Theorem 6.2], which is simpler to state.

Theorem 4.2. Let $r \in \mathcal{N}, 1 \leq p \leq \infty$ and $\lambda_{a}, \lambda_{b} \in(-\infty, 1)$. For $p<\infty$ we assume that $\kappa_{a}, \kappa_{b} \notin \Gamma_{e x c}(p)$ as at least one of them is in $\Gamma_{0}(p)$, and for $p=\infty$ we assume that $\kappa_{a}=\kappa_{b}=0$. We set $w=\chi_{a}^{\kappa_{a}} \chi_{b}^{\kappa_{b}}, \varphi=\chi_{a}^{\lambda_{a}} \chi_{b}^{\lambda_{b}}$ and

$$
\mathcal{A}=B_{1}\left(\sigma_{b} ; b, a ; \xi\right) B_{1}\left(\sigma_{a} ; a, b ; \xi\right) A_{0}\left(\rho_{b} ; b, a ; \xi\right) A_{0}\left(\rho_{a} ; a, b ; \xi\right)
$$

where $\xi \in(a, b)$ and

$$
\sigma_{a}=\frac{1}{1-\lambda_{a}}, \quad \sigma_{b}=\frac{1}{1-\lambda_{b}}, \quad \rho_{a}=\kappa_{a}+\frac{\lambda_{a}}{p}, \quad \rho_{b}=\kappa_{b}+\frac{\lambda_{b}}{p}
$$

Then for $f \in L_{p}(w)[a, b]$ and $t>0$ we have

$$
K\left(f, t^{r} ; L_{p}(w)[a, b], W_{p}^{r}\left(w \varphi^{r}\right)[a, b]\right) \sim \omega_{r}(\mathcal{A} f, t)_{p[a, b]}
$$

The operators $A$ and $B$ defined in the beginning of this subsection can also be used when the weight exponent at the end $s$ takes an exceptional value from $\Gamma_{e x c}(p)$ but then they change the exponent into one that belongs to $\Gamma_{e x c}(p)$ again. More precisely, the following assertion holds for the $A$-operators.

Proposition 4.1. Let $i, i^{\prime} \in \mathcal{N}_{0}, r \in \mathcal{N}$, as $i, i^{\prime}<r, 1 \leq p \leq \infty$, $\gamma \in \Gamma_{+}(p), \xi, \eta \in(a, b)$, and $s$ be one of the points $a$ or $b$ and $e$ be the other one. We set $w=\chi_{s}^{-i-1 / p} \chi_{e}^{\gamma}$ and $\tilde{w}=\chi_{s}^{-i^{\prime}-1 / p} \chi_{e}^{\gamma}$. Finally, let $\phi$ be measurable and non-negative on $(a, b)$. Then we have

$$
\begin{aligned}
K\left(f, t ; L_{p}(w)[a, b], W_{p}^{r}(w \phi)\right. & {[a, b]) } \\
& \sim K\left(A_{i^{\prime}}\left(i^{\prime}-i ; s, e ; \xi\right) f, t ; L_{p}(\tilde{w})[a, b], W_{p}^{r}(\tilde{w} \phi)[a, b]\right)
\end{aligned}
$$

and

$$
\begin{aligned}
K\left(F, t ; L_{p}(\tilde{w})[a, b], W_{p}^{r}(\tilde{w} \phi)\right. & {[a, b]) } \\
& \sim K\left(A_{i}\left(i-i^{\prime} ; s, e ; \eta\right) F, t ; L_{p}(w)[a, b], W_{p}^{r}(w \phi)[a, b]\right)
\end{aligned}
$$

Proof. Just similarly as in the proof of [16, Proposition 3.2] we verify that the operators $\mathcal{A}=A_{i^{\prime}}\left(i^{\prime}-i ; s, e ; \xi\right)$ and $\mathcal{B}=A_{i}\left(i-i^{\prime} ; s, e ; \eta\right)$ satisfy the hypotheses of Theorem 3.1 with $X_{1}=L_{p}(w)[a, b], X_{2}=L_{p}(\tilde{w})[a, b], Y_{1}=$ $W_{p}^{r}(w \phi)[a, b]$ and $Y_{2}=W_{p}^{r}(\tilde{w} \phi)[a, b]$. In establishing properties a) and b) we also take into consideration that $\alpha_{r, i^{\prime}+1}\left(i^{\prime}-i\right)=0, \alpha_{r, i+1}\left(i-i^{\prime}\right)=0$ and hence Hardy's inequalities are applicable.

If we separate the singularities of the weights $w$ and $\varphi$ beforehand, using (3.2), we can get a similar characterization of the $K$-functional with simpler transforms of the function but by a sum of two moduli $\omega_{r}$. Moreover, the requirement that the exponent of the weight $w$ on at least one of the ends of the interval is greater than $-1 / p$ for $p<\infty$ is trivially satisfied and hence relaxed. In addition, Proposition 4.1 allows us to characterize the $K$-functional in the case $p=\infty$ not only for $\kappa_{a}, \kappa_{b}=0$ but for all $\kappa_{a}, \kappa_{b} \in \Gamma_{e x c}(\infty)=\{1-r, \ldots,-1,0\}$. Thus, (3.2), Theorem 4.2 (in the case $p<\infty$ ), and Proposition 4.1, [13, Theorem 5.4] (in the case $p=\infty$ ) yield the following relation (cf. [16, Theorem 7.1]).

Theorem 4.3. Let $r \in \mathcal{N}, 1 \leq p \leq \infty$ and $\lambda_{a}, \lambda_{b} \in(-\infty, 1)$. For $p<\infty$ we assume that $\kappa_{a}, \kappa_{b} \notin \Gamma_{e x c}(p)$, and for $p=\infty$ we assume that $\kappa_{a}, \kappa_{b} \in \Gamma_{e x c}(\infty)$. We set $w=\chi_{a}^{\kappa_{a}} \chi_{b}^{\kappa_{b}}, \varphi=\chi_{a}^{\lambda_{a}} \chi_{b}^{\lambda_{b}}$ and

$$
\begin{aligned}
\mathcal{A}_{1} & =B_{1}\left(\sigma_{a} ; a, b_{1} ; \xi_{1}\right) A_{0}\left(\rho_{a} ; a, b_{1} ; \xi_{1}\right) \\
\mathcal{A}_{2} & =B_{1}\left(\sigma_{b} ; b, a_{1} ; \xi_{2}\right) A_{0}\left(\rho_{b} ; b, a_{1} ; \xi_{2}\right)
\end{aligned}
$$

where $a<a_{1}<b_{1}<b, \xi_{1} \in\left(a, b_{1}\right), \xi_{2} \in\left(a_{1}, b\right)$ and

$$
\sigma_{a}=\frac{1}{1-\lambda_{a}}, \quad \sigma_{b}=\frac{1}{1-\lambda_{b}}, \quad \rho_{a}=\kappa_{a}+\frac{\lambda_{a}}{p}, \quad \rho_{b}=\kappa_{b}+\frac{\lambda_{b}}{p} .
$$

Then for $f \in L_{p}(w)[a, b]$ and $t>0$ we have

$$
K\left(f, t^{r} ; L_{p}(w)[a, b], W_{p}^{r}\left(w \varphi^{r}\right)[a, b]\right) \sim \omega_{r}\left(\mathcal{A}_{1} f, t\right)_{p\left[a, b_{1}\right]}+\omega_{r}\left(\mathcal{A}_{2} f, t\right)_{p\left[a_{1}, b\right]}
$$

Remark 4.2. The $K$-functional $K\left(f, t^{r} ; L_{p}(w)[a, b], W_{p}^{r}\left(w \varphi^{r}\right)[a, b]\right)$ for $\kappa_{a}, \kappa_{b} \in \Gamma_{e x c}(p), p<\infty$, and $\kappa_{a}, \kappa_{b} \notin \Gamma_{e x c}(\infty), p=\infty$, can also be characterized in a similar way but that involves new elements. Some initial comments on that are given in $[15$, Sections 3 and 4$]$.

Results similar to those given in Theorems 4.1-4.3 are valid in the cases when one or both of the expressions $\left(1-\lambda_{a}\right)\left(1-\nu_{a}\right),\left(1-\lambda_{b}\right)\left(1-\nu_{b}\right)$ is negative and/or the interval is (semi-)infinite (see [16]).
4.2. Exponential change of the variable. $K$-functionals with $\lambda_{a}=$ 1 and/or $\lambda_{\infty}=1$ are related to the approximation error of the Post-Widder, Gamma and Baskakov operators (see [17] and the references cited there, and also [31]). In [18] we show that

$$
\begin{aligned}
\left\|w\left(f-P_{1 / t} f\right)\right\|_{p[0, \infty)} \sim \| w\left(f-G_{1 / t} f\right) & \|_{p[0, \infty)} \\
& \sim K\left(f, t ; L_{p}(w)[0, \infty), W_{p}^{2}\left(w \chi_{0}^{2}\right)[0, \infty)\right)
\end{aligned}
$$

where $P_{1 / t}$ and $G_{1 / t}$ denote respectively the Post-Widder and the Gamma operators, $f \in L_{p}(w)[0, \infty), w(x)=x^{\gamma_{0}}(1+x)^{\gamma_{\infty}-\gamma_{0}}$ with arbitrary $\gamma_{0}, \gamma_{\infty} \in \mathcal{R}$, and $1 \leq p \leq \infty$ (the case $\gamma_{0}=\gamma_{\infty}$ was considered in [17]).

Following the ideas of the previous subsection for $r \in \mathcal{N}, \gamma \in \mathcal{R}, F \in$ $L_{1, l o c}(\mathcal{R}), f \in L_{1, l o c}[a, \infty)$ and $x \in \mathcal{R}$ we define the operators

$$
\begin{aligned}
& \left(A_{\gamma} F\right)(x)=e^{(\gamma+1 / p) x} F(x) \\
& \quad+\sum_{k=1}^{r}(-1)^{k}\binom{r}{k} \frac{(\gamma+1 / p)^{k}}{(k-1)!} \int_{0}^{x}(x-y)^{k-1} e^{(\gamma+1 / p) y} F(y) d y \\
& (B f)(x)=f\left(a+e^{x}\right)+\sum_{i=1}^{r-1} \frac{s(r, r-i)}{(i-1)!} \int_{0}^{x}(x-y)^{i-1} f\left(a+e^{y}\right) d y
\end{aligned}
$$

where $s(r, k)$ are the Stirling numbers of the first kind defined by

$$
x(x-1) \ldots(x-r+1)=\sum_{k=0}^{r} s(r, k) x^{k}
$$

for $k=0,1, \ldots, r$ and $s(r, k)=0$ for $k>r$. Then the following one-term characterization is valid $[14,19]$.

Theorem 4.4. Let $r \in \mathcal{N}, 1 \leq p \leq \infty, 0<t \leq t_{0}, \gamma \in \mathcal{R}$ and $f \in L_{p}\left(\chi_{a}^{\gamma}\right)[a, \infty)$.
a) If $\gamma \notin \Gamma_{e x c}(p)$, then

$$
K\left(f, t^{r} ; L_{p}\left(\chi_{a}^{\gamma}\right)[a, \infty), W_{p}^{r}\left(\chi_{a}^{\gamma+r}\right)[a, \infty)\right) \sim \omega_{r}\left(A_{\gamma} B f, t\right)_{p(\mathcal{R})} .
$$

b) If $\gamma \in \Gamma_{e x c}(p)$, then

$$
K\left(f, t^{r} ; L_{p}\left(\chi_{a}^{\gamma}\right)[a, \infty), W_{p}^{r}\left(\chi_{a}^{\gamma+r}\right)[a, \infty)\right) \sim \omega_{r}\left(B\left(\chi_{a}^{\gamma+1 / p} f\right), t\right)_{p(\mathcal{R})}
$$

By means of the method of 3.1 the operators $A_{\gamma}$ and $B$ in the above theorem can be further simplified if we use two fixed step moduli of different order. To treat the more general weight $w(x)=\chi_{a}^{\gamma_{a}} \chi_{a-1}^{\gamma_{\infty}-\gamma_{a}}$ with $\gamma_{a}, \gamma_{\infty} \in \mathcal{R}$ in some cases we shall also apply (3.2), which increases the number of fixed step moduli to four. For $r \in \mathcal{N}, i, j \in \mathcal{N}_{0}, j \leq r$, distinct points $x_{0}, \ldots, x_{r} \in(a, \infty)$ and a weight $\bar{w}$ we define the linear operator $\mathcal{A}_{i, j-1}(\bar{w}): L_{1, l o c}[a, \infty) \rightarrow L_{1, l o c}(\mathcal{R})$ by

$$
\mathcal{A}_{i, j-1}(\bar{w}) f=\left(\bar{w}\left(f-\mathcal{L}_{i, j-1} f\right)\right) \circ \mathcal{E}
$$

where $\mathcal{E}(x)=e^{x}$ and

$$
\begin{gathered}
\left(\mathcal{L}_{i, j-1} f\right)(x)=\sum_{n=i}^{j-1} \frac{1}{n!}\left(\sum_{\ell=1}^{r} \frac{\Phi_{\ell}^{(n+1)}(a)}{\Phi_{\ell}\left(x_{\ell}\right)} \int_{x_{0}}^{x_{\ell}} f(y) d y\right)(x-a)^{n} \\
\Phi_{\ell}(x)=\prod_{\substack{m=0 \\
m \neq \ell}}^{r}\left(x-x_{m}\right), \quad \ell=1, \ldots, r
\end{gathered}
$$

We have the following characterization [18, Theorem 1.2].
Theorem 4.5. Let $r \in \mathcal{N}, i, j \in \mathcal{N}_{0}, i, j \leq r, 1 \leq p \leq \infty$ and $t_{0}>0$. Let also $w=\chi_{a}^{\gamma_{a}} \chi_{a-1}^{\gamma_{\infty}-\gamma_{a}}$ with $\gamma_{a} \in \Gamma_{i}(p), \gamma_{\infty} \in \Gamma_{j}(p)$. Then for every $f \in$ $L_{p}(w)[a, \infty)$ and $0<t \leq t_{0}$ there holds

$$
\begin{aligned}
K\left(f, t^{r} ; L_{p}(w)[a, \infty),\right. & \left.W_{p}^{r}\left(w \chi_{a}^{r}\right)[a, \infty)\right) \\
& \sim \omega_{r}\left(\mathcal{A}_{i, j-1}\left(\chi_{a}^{1 / p} w\right) f, t\right)_{p(\mathcal{R})}+t^{r}\left\|\mathcal{A}_{i, j-1}\left(\chi_{a}^{1 / p} w\right) f\right\|_{p(\mathcal{R})}
\end{aligned}
$$

Proof. We shall show that the operator $\mathcal{A}=\mathcal{A}_{i, j-1}\left(\chi_{a}^{1 / p} w\right)$ satisfies the hypotheses of Theorem 3.1 with $X_{1}=L_{p}(w)[a, \infty), Y_{1}=W_{p}^{r}\left(w \chi_{a}^{r}\right)[a, \infty)$ as $|g|_{Y_{1}}=\left\|w \chi_{a}^{r} g^{(r)}\right\|_{p[a, \infty)}, X_{2}=L_{p}(\mathcal{R}), Y_{2}=W_{p}^{r}(\mathcal{R})$ as $|G|_{Y_{2}}=\|G\|_{p(\mathcal{R})}+$ $\left\|G^{(r)}\right\|_{p(\mathcal{R})}$ and $\mathcal{B}: X_{2} \rightarrow X_{1}$, defined by $\mathcal{B} F=\chi_{a}^{-1 / p} w^{-1}(F \circ \log )$. Since $\mathcal{L}_{i, j-1}$ :
$X_{1} \rightarrow X_{2}$ is bounded we verify that $\mathcal{A}$ and $\mathcal{B}$ satisfy respectively conditions a) and c) of Theorem 3.1 just by a change of the variable. In [18, Proposition 4.3 and 4.4.e] we establish the inequalities

$$
\left\|w \chi_{a}^{k}\left(g-\mathcal{L}_{i, j-1} g\right)^{(k)}\right\|_{p[a, \infty)} \leq c\left\|w \chi_{a}^{r} g^{(r)}\right\|_{p[a, \infty)}, \quad k=0, \ldots, r
$$

provided that $g \in W_{p}^{r}\left(w \chi_{a}^{r}\right)[a, \infty), \gamma_{0} \in \Gamma_{i}(p), \gamma_{\infty} \in \Gamma_{j}(p)$. Hence condition b) of Theorem 3.1 follows. Similarly, by the well-known inequalities

$$
\left\|G^{(k)}\right\|_{p(\mathcal{R})} \leq c\left(\|G\|_{p(\mathcal{R})}+\left\|G^{(r)}\right\|_{p(\mathcal{R})}\right), \quad k=0, \ldots, r
$$

we get d). Finally, we directly verify that $f-\mathcal{B} \mathcal{A} f=\mathcal{L}_{i, j-1} f \in \pi_{r-1} \cap Y_{1}$ for any $f \in X_{1}$, which implies e), and since $\mathcal{L}_{i, j-1}$ preserves the polynomials of the form $c_{i} \chi_{a}^{i}+\cdots+c_{j-1} \chi_{a}^{j-1}$ we have $\mathcal{A B} F=F$ for any $F \in \mathcal{A}\left(X_{1}\right)$, which implies f) for $F \in \mathcal{A}\left(X_{1}\right)$.

Now, Theorem 3.1 in view of Remark 3.1 yields

$$
\begin{aligned}
K\left(f, t^{r} ;\right. & \left.L_{p}(w)[a, \infty), W_{p}^{r}\left(w \chi_{a}^{r}\right)[a, \infty)\right) \\
& \sim \inf \left\{\|\mathcal{A} f-G\|_{p(\mathcal{R})}+t^{r}\left(\|G\|_{p(\mathcal{R})}+\left\|G^{(r)}\right\|_{p(\mathcal{R})}\right): G \in W_{p}^{r}(\mathcal{R})\right\}
\end{aligned}
$$

To complete the proof we just need to observe that for $F \in L_{p}(\mathcal{R}), 1 \leq$ $p \leq \infty$, and $0<t \leq t_{0}$ there holds (cf. [17, Lemma 5.2])

$$
\begin{aligned}
& \inf \left\{\|F-G\|_{p(\mathcal{R})}+t^{r}\left(\left\|G^{(\ell)}\right\|_{p(\mathcal{R})}+\left\|G^{(r)}\right\|_{p(\mathcal{R})}\right): G \in W_{p}^{r}(\mathcal{R})\right\} \\
& \sim \omega_{r}(F, t)_{p(\mathcal{R})}+t^{r-\ell} \omega_{\ell}(F, t)_{p(\mathcal{R})}, \quad \ell=0, \ldots, r-1
\end{aligned}
$$

Let us explicitly note that for $j \leq i$ we have $\mathcal{A}_{i, j-1}\left(\chi_{a}^{1 / p} w\right) f=$ $\left(\chi_{a}^{1 / p} w f\right) \circ \mathcal{E}$.

Similarly, the following assertion can be established
Theorem 4.6 [18, Theorem 1.3]. Let $r \in \mathcal{N}, 1 \leq p \leq \infty$ and $b, t_{0}>0$. Let also $w=\chi_{a}^{\gamma_{a}} \chi_{a-1}^{\gamma_{\infty}-\gamma_{a}}$ with $\gamma_{a}, \gamma_{\infty} \in \mathcal{R}$ and the integers $i, j$ be determined by $\Gamma_{i}(p) \cup\{1-i-1 / p\} \ni \gamma_{a}, \Gamma_{j}(p) \cup\{-j-1 / p\} \ni \gamma_{\infty}$. We set $\ell_{a}=1$ if $\gamma_{a} \in \Gamma_{e x c}(p)$, and $\ell_{a}=0$ otherwise. We set $\ell_{\infty}=1$ if $\gamma_{\infty} \in \Gamma_{e x c}(p)$, and $\ell_{\infty}=0$ otherwise. Let the integers $i^{\prime}, j^{\prime}$ be such that $0 \leq i^{\prime} \leq i-\ell_{0}$ and $j+\ell_{\infty} \leq j^{\prime} \leq r$. Then for
every $f \in L_{p}(w)[a, \infty)$ and $0<t \leq t_{0}$ there holds

$$
\begin{aligned}
& K\left(f, t^{r} ; L_{p}(w)[a, \infty), W_{p}^{r}\left(w \chi_{a}^{r}\right)[a, \infty)\right) \\
& \quad \sim \omega_{r}\left(\mathcal{A}_{i, j^{\prime}-1}\left(\chi_{a}^{\gamma_{a}+1 / p}\right) f, t\right)_{p(-\infty, b]}+t^{r-\ell_{a}} \omega_{\ell_{a}}\left(\mathcal{A}_{i, j^{\prime}-1}\left(\chi_{a}^{\gamma_{a}+1 / p}\right) f, t\right)_{p(-\infty, b]} \\
& \quad+\omega_{r}\left(\mathcal{A}_{i^{\prime}, j-1}\left(\chi_{a}^{\gamma_{\infty}+1 / p}\right) f, t\right)_{p[-b, \infty)}+t^{r-\ell_{\infty}} \omega_{\ell_{\infty}}\left(\mathcal{A}_{i^{\prime}, j-1}\left(\chi_{a}^{\gamma_{\infty}+1 / p}\right) f, t\right)_{p[-b, \infty)} .
\end{aligned}
$$

Similar characterizations hold for the $K$-functionals $K\left(f, t ; L_{p}\left(\chi_{a}^{\gamma_{a}}\right)[a, b]\right.$, $\left.W_{p}^{r}\left(\chi_{a}^{\gamma_{a}+r}\right)[a, b]\right)$ and $K\left(f, t ; L_{p}\left(\chi_{a}^{\gamma_{\infty}}\right)[a+1, \infty), W_{p}^{r}\left(\chi_{a}^{\gamma_{\infty}+r}\right)[a+1, \infty)\right)$.
4.3. A $K$-functional associated with the best approximation by trigonometric polynomials. Let $L_{p, 2 \pi}$ denote the set of the $2 \pi$-periodic functions in $L_{p}$. The best trigonometric approximation of a function $f \in L_{p, 2 \pi}$ is given by

$$
E_{n}^{T}(f)_{p}=\inf _{g \in T_{n}}\|f-g\|_{p[-\pi, \pi]}
$$

where $T_{n}$ is the set of trigonometric polynomials of degree at most $n \in \mathcal{N}_{0}$. As it is known the rate of best approximation by trigonometric polynomials can be estimated by the periodic modulus of smoothness as follows (see e.g. [8, Ch. 7]):

$$
\begin{align*}
E_{n}^{T}(f)_{p} & \leq c \omega_{r}\left(f, n^{-1}\right)_{p, 2 \pi}, \quad n \in \mathcal{N}  \tag{4.2}\\
\omega_{r}(f, t)_{p, 2 \pi} & \leq c t^{r} \sum_{0 \leq k \leq 1 / t}(k+1)^{r-1} E_{k}^{T}(f)_{p}, \quad 0<t \leq t_{0}
\end{align*}
$$

However, $\omega_{r}(f, t)_{p, 2 \pi} \equiv 0$ iff $f \in T_{0}$, whereas $E_{n}^{T}(f)_{p}=0$ for any $f \in T_{n}$ and thus the direct estimate (4.2) contains a gap. This discrepancy can be overcome by defining another periodic modulus which is zero iff $f$ is trigonometric polynomial of a given degree.

Let $\Pi_{n}$ denote the set of the algebraic polynomials of degree $n \in \mathcal{N}_{0}$. For $r \in \mathcal{N}$ let us define the linear operator $\mathcal{A}_{r-1}: L_{p, 2 \pi} \rightarrow L_{p, 2 \pi}+\Pi_{2 r-2}$ by

$$
\mathcal{A}_{r-1}(f, x)=f(x)+\sum_{j=1}^{r-1} \frac{a_{r-1, j}}{(2 j-1)!} \int_{0}^{x}(x-t)^{2 j-1} f(t) d t
$$

where $a_{r-1, j}$ are given by the Stirling numbers of the first kind with

$$
a_{r-1, j}=\sum_{k=1}^{2 r-2 j-1}(-1)^{r-j-k} s(r, k) s(r, 2 r-2 j-k)
$$

The first author introduced in [12] the following periodic modulus of smoothness:

$$
\begin{equation*}
\omega_{r}^{T}(f, t)_{p, 2 \pi}=\sup _{0<h \leq t}\left\|\Delta_{h}^{2 r-1} \mathcal{A}_{r-1} f\right\|_{p[-\pi, \pi]} \tag{4.3}
\end{equation*}
$$

Let us note that although $\mathcal{A}_{r-1} f$ is not generally a $2 \pi$-periodic function for $f \in$ $L_{p, 2 \pi}$, its finite difference $\Delta_{h}^{2 r-1} \mathcal{A}_{r-1} f$ is. It was established in [12] that

$$
\begin{align*}
E_{n}^{T}(f)_{p} & \leq c \omega_{r}^{T}(f, 1 / n)_{p, 2 \pi}, \quad n \geq r-1  \tag{4.4}\\
\omega_{r}^{T}(f, t)_{p, 2 \pi} & \leq c t^{2 r-1} \sum_{r-1 \leq k \leq 1 / t}(k+1)^{2 r-2} E_{k}^{T}(f)_{p}, \quad 0<t \leq 1 / r
\end{align*}
$$

as $\omega_{r}^{T}(f, t)_{p, 2 \pi} \equiv 0$ iff $f \in T_{r-1}$. Let us note that (4.4) for $n=r-1$ is a trigonometric analogue of Whitney's theorem.

A substantial element of the proof of (4.4) is the following relation between $K$-functionals, which is established by the method given in Theorem 3.1:

$$
\begin{aligned}
& K_{r, \ell}^{T}(f, t)_{p}=\inf \left\{\|f-g\|_{p[-\pi, \pi]}+t\left\|\widetilde{D}_{r} D^{\ell} g\right\|_{p[-\pi, \pi]}: g \in W_{p, 2 \pi}^{2 r+\ell-1}\right\} \\
& \sim K\left(\mathcal{A}_{r-1} f, t ; L_{p, 2 \pi}+\Pi_{2 r-2}, W_{p, 2 \pi}^{2 r+\ell-1}\right), \quad \ell=0,1, \ldots
\end{aligned}
$$

with $D g=g^{\prime}, \widetilde{D}_{r} g=\left(D^{2}+(r-1)^{2}\right) \cdots\left(D^{2}+1\right) D g$ and $W_{p, 2 \pi}^{m}=\left\{g \in A C_{l o c}^{m}(\mathcal{R})\right.$ : $\left.D^{m} g \in L_{p, 2 \pi}\right\}$. Let us recall that $\widetilde{D}_{r} g=0$ iff $g \in T_{r-1}$ and hence $K_{r, 0}^{T}(f, t)_{p} \equiv 0$ iff $g \in T_{r-1}$.

Another modulus which is equivalent to zero for the trigonometric polynomials up to a given degree was considered by A.G. Babenko, N.I. Chernykh and V.T. Shevaldin. Through it they proved an upper estimate just like (4.2) for $p=2$ and $r \in \mathcal{N}$ in [1], and Shevaldin [30] proved it for $p=\infty$ and $r=2$.

### 4.4. The $K$-functional associated with the approximation error of the Kantorovich and the Durrmeyer operators.

Theorem 3.1 can be also applied for characterizing $K$-functionals with the second term generated by a linear differential operator of the form $P(D)$, where $P$ is a polynomial with varying coefficients. In such cases the application is more complicated but the arising problems can be overcome, for example, by a varying sets technique. In order to demonstrate the approach let us consider the $K$-functional associated with the approximation error of the Kantorovich and the Durrmeyer operators.

Consider the space $L_{p}[0,1], 1 \leq p \leq \infty$, as for $p=\infty$ we identify $L_{\infty}[0,1]$ in this subsection with $C[0,1]$. Let $\tilde{Y}_{p}$ be $C^{2}[0,1]$ equipped with the semi-norm
$|g|_{\tilde{Y}_{p}}=\left\|\left(\phi g^{\prime}\right)^{\prime}\right\|_{p[0,1]}$, where $\phi(x)=x(1-x)$. In this case the differential operator is $\phi D^{2}+\phi^{\prime} D$. As it was shown by Chen, Ditzian and Ivanov [7] for the Durrmeyer operator $M_{n}$ and by Gonska and Zhou [20] for the Kantorovich operator $K_{n}$, we have for $1 \leq p \leq \infty$ the equivalence

$$
\begin{equation*}
\left\|f-K_{n} f\right\|_{p[0,1]} \sim\left\|f-M_{n} f\right\|_{p[0,1]} \sim K\left(f, 1 / n ; L_{p}[0,1], \tilde{Y}_{p}\right) \tag{4.5}
\end{equation*}
$$

Further, Gonska and Zhou [20] proved for $f \in L_{p}[0,1], 1<p \leq \infty$ that

$$
K\left(f, t^{2} ; L_{p}[0,1], \tilde{Y}_{p}\right) \sim \omega_{\sqrt{\phi}}^{2}(f, t)_{p[0,1]}+\omega_{1}\left(f, t^{2}\right)_{p[0,1]}
$$

where $\omega_{\sqrt{\phi}}^{2}$ is given by (2.3) with $w \equiv 1$. The above equivalence is not valid in the case $p=1$. For the characterization of the $K$-functional in (4.5) for $p=1$ the second author [23] used the scheme

$$
\begin{align*}
K\left(f, t ; L_{1}[0,1], \tilde{Y}_{1}\right)=K & \left(f, t ; L_{1}[0,1], Z_{1}\right) \sim K\left(\mathcal{A} f, t ; L_{1}[0,1], Z_{2}\right)  \tag{4.6}\\
& \sim K\left(\mathcal{A} f, t ; L_{1}[0,1], W_{1}^{2}(\phi)[0,1]\right)+t \omega_{1}(f, 1)_{1[0,1]}
\end{align*}
$$

where the operator $\mathcal{A}$ is given by

$$
(\mathcal{A} f)(x)=f(x)+\int_{1 / 2}^{x}\left(\frac{x}{y^{2}}-\frac{1-x}{(1-y)^{2}}\right) f(y) d y
$$

Theorem 3.1 is applied in (4.6) with $X_{1}=X_{2}=L_{1}[0,1], Y_{1}=Z_{1}$ and $Y_{2}=Z_{2}$, where

$$
\begin{gathered}
Z_{1}=\left\{f \in C^{2}[0,1]: f^{\prime}(0)=0, f^{\prime}(1)=0\right\} \\
Z_{2}=\left\{f \in C^{2}[0,1]: f(0)=2 \int_{0}^{1 / 2} f(y) d y, f(1)=2 \int_{1 / 2}^{1} f(y) d y\right\}
\end{gathered}
$$

and the semi-norms in $Z_{1}$ and $Z_{2}$ are given by $\left\|\left(\phi g^{\prime}\right)^{\prime}\right\|_{1[0,1]}$ and $\left\|\phi g^{\prime \prime}\right\|_{1[0,1]}$ respectively. Note that Theorem 3.1 cannot be applied directly with $\mathcal{A}$ and the subspaces $Y_{1}=\tilde{Y}_{1}, Y_{2}=W_{1}^{2}(\phi)[0,1]$ because items b) and d) (with $\left.\mathcal{B}=\mathcal{A}^{-1}\right)$ are not fulfilled. Moreover, $\mathcal{A}\left(Z_{1}\right)=Z_{2}$ but $\mathcal{A}\left(\tilde{Y}_{1}\right) \neq W_{1}^{2}(\phi)[0,1]$. Using (4.5), (4.6) and Theorem 4.2 we get for every $n \in \mathbb{N}$ and every $f \in L_{1}[0,1]$

$$
\left\|f-P_{n} f\right\|_{1[0,1]} \sim\left\|f-M_{n} f\right\|_{1[0,1]} \sim \omega_{2}\left(\tilde{\mathcal{A}} \mathcal{A} f, n^{-1 / 2}\right)_{1[0,1]}+n^{-1} \omega_{1}(f, 1)_{1[0,1]}
$$

where $\tilde{\mathcal{A}}$ stays for the operator $\mathcal{A}$ from Theorem 4.2 with $r=2, p=1, a=0$, $b=1, \lambda_{0}=\lambda_{1}=1 / 2, \kappa_{0}=\kappa_{1}=0, \xi=1 / 2$.

Following the approach sketched in this subsection Zapryanova [32] characterized the $K$-functional related to the $L_{p}[0,1], 1 \leq p \leq 2$, error of the algebraic version of the integral Jackson operator.

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