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**THE VARIETY OF LEIBNIZ ALGEBRAS  
DEFINED BY THE IDENTITY  $x(y(zt)) \equiv 0^*$**

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ABSTRACT. Let  $F$  be a field of characteristic zero. In this paper we study the variety of Leibniz algebras  ${}_3\mathbf{N}$  determined by the identity  $x(y(zt)) \equiv 0$ . The algebras of this variety are left nilpotent of class not more than 3. We give a complete description of the vector space of multilinear identities in the language of representation theory of the symmetric group  $S_n$  and Young diagrams. We also show that the variety  ${}_3\mathbf{N}$  is generated by an abelian extension of the Heisenberg Lie algebra. It has turned out that  ${}_3\mathbf{N}$  has many properties which are similar to the properties of the variety of the abelian-by-nilpotent of class 2 Lie algebras. It has overexponential growth of the codimension sequence and subexponential growth of the colength sequence.

**1. Introduction.** We study varieties of Leibniz algebras over a field  $F$  of zero characteristic. It is well known that in characteristic zero all polynomial identities are completely determined by the multilinear ones. One of the most

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important numerical characteristics of polynomial identities of a variety of algebras are the codimension, the cocharacter and the colength sequences. There are a lot of papers about the codimension growth of associative and Lie algebras. Recently the systematic study of polynomial identities of Leibniz algebras has been also started (see for example [3]).

A *Leibniz algebra*  $L$  over a field  $F$  is a nonassociative algebra with multiplication

$$(-, -) : L \times L \longrightarrow L$$

satisfying the Leibniz identity

$$(1) \quad (x, (y, z)) = ((x, y), z) - ((x, z), y).$$

In other words, the operator of right multiplication  $(-, z)$  is a derivation of the algebra. Notice that this identity is equivalent to the classical Jacobi identity when  $(-, -)$  is skew-symmetric. The Leibniz identity allows us to express any product as a linear combination of left-normed products. We will omit the Leibniz parentheses and use the left-normed notation  $a_1 a_2 \cdots a_n = ((a_1, \dots, a_{n-1}), a_n)$ . Identities of Leibniz algebras are very close to the defining identities of Lie algebras. In particular, the following relations follow from (1):

$$x(yz) \equiv xyz - xzy, x(yy) \equiv 0, x(yz) \equiv -x(zy),$$

$$x(yzt) + x(zty) + x(tyz) \equiv 0.$$

In this paper we study the variety of Leibniz algebras determined by the identity

$$(2) \quad x(y(zt)) \equiv 0.$$

Denote this variety by  ${}_3\mathbf{N}$ . Our main purpose is to give a complete description of the space of multilinear identities of  ${}_3\mathbf{N}$  in the language of representation theory of the symmetric group  $S_n$  and Young diagrams.

We recall all essential notions. Their definitions are similar to those for varieties of associative and Lie algebras.

Let  $\mathbf{V}$  be a variety of Leibniz algebras over a field  $F$ . Denote by  $F(X, \mathbf{V})$  the relatively free algebra of the variety  $\mathbf{V}$  with a countable set of generators  $X = \{x_1, x_2, \dots\}$ . Denote also by  $P_n = P_n(\mathbf{V})$  the set of all multilinear Leibniz polynomials in  $x_1, \dots, x_n$  in  $F(X, \mathbf{V})$ . The left action of the symmetric group  $S_n$  defined by  $\sigma(x_i) = x_{\sigma(i)}$ ,  $\sigma \in S_n$ , can be naturally extended to the vector space  $P_n$ . The structure of  $P_n$  as an  $S_n$ -module,  $n = 1, 2, \dots$ , is an important characterization of  $\mathbf{V}$  and gives very useful information about  $\mathbf{V}$ .

Denote by  $\chi_\lambda$  the irreducible character of the symmetric group  $S_n$  corresponding to the partition  $\lambda$  of  $n$  and, for a variety  $\mathbf{V}$ , consider the decomposition of the  $S_n$ -character  $\chi(P_n(\mathbf{V}))$  as a sum of irreducible components

$$(3) \quad \chi_n(\mathbf{V}) = \chi(P_n(\mathbf{V})) = \sum_{\lambda \vdash n} m_\lambda \chi_\lambda.$$

The character  $\chi_n(\mathbf{V})$  is called the  $n$ -th cocharacter of  $\mathbf{V}$  and the integer  $c_n(\mathbf{V}) = \dim P_n(\mathbf{V})$  is the  $n$ -th codimension of  $\mathbf{V}$ . Important numerical characteristics of  $\mathbf{V}$  are also the multiplicities  $m_\lambda$  in (3). The total number of summands

$$l_n(\mathbf{V}) = \sum_{\lambda \vdash n} m_\lambda$$

in the sum (3) is called the  $n$ -th colength of the variety  $\mathbf{V}$ .

Denote by  $d_\lambda$  the dimension of the irreducible  $S_n$ -module corresponding to  $\lambda$ . The following relation

$$c_n(\mathbf{V}) = \dim P_n(\mathbf{V}) = \sum_{\lambda \vdash n} m_\lambda d_\lambda$$

holds for the above introduced numerical characteristics. It is well known that for any nontrivial variety of associative algebras  $\mathbf{V}$ , the sequence of codimensions is exponentially bounded [7] and the colength function  $l_n(\mathbf{V})$  is polynomially bounded [2].

The variety  $3\mathbf{N}$  is similar to the variety  $\mathbf{AN}_2$  of all abelian-by-nilpotent of class 2 Lie algebras determined by the Lie identity  $(x_1x_2x_3)(x_4x_5x_6) \equiv 0$ . The Lie variety  $\mathbf{AN}_2$  was investigated in many papers (see for example [8], [4], [9], [6]). Both varieties  $3\mathbf{N}$  and  $\mathbf{AN}_2$  have overexponential growth of their codimension sequences and non-polynomial but subexponential growth of the colength sequences.

As by-products of the proofs of our main results we give an explicit basis of  $P_n(3\mathbf{N})$  indexed with the involutions of the symmetric group  $S_{n-1}$ . We also establish that the variety  $3\mathbf{N}$  is generated by a Leibniz algebra which is an abelian extension of the infinitely dimensional Heisenberg Lie algebra.

**2. Main results.** First we give examples of Leibniz algebras from the variety  $3\mathbf{N}$ . We need these algebras in the proof of our main theorem. We will show that they generate the variety  $3\mathbf{N}$ .

Let  $T_k = F[t_1, \dots, t_k]$  be the algebra of polynomials in  $k$  commuting variables  $t_1, \dots, t_k$  and let  $H_k$  be the Lie algebra with basis  $\{a_1, \dots, a_k, b_1, \dots, b_k, c\}$  and multiplication table

$$a_i b_j = \delta_{ij} c, \quad a_i a_j = b_i b_j = a_i c = b_j c = 0,$$

where  $\delta_{ij}$  is the Kronecker delta. The algebra  $H_k$  is called the Heisenberg algebra and satisfies the Lie identity  $x_1x_2x_3 \equiv 0$ . The vector space  $T_k$  becomes a right  $H_k$ -module if we define the action of the basis elements of  $H_k$  on the polynomial  $f \in T_k$  by

$$fc = f, fa_s = f'_s, fb_s = t_s f,$$

where  $f'_s$  is the partial derivative of  $f$  with respect to  $t_s$ . We also define the trivial left action of  $H_k$  on  $T_k$  by  $a_s f = b_s f = c f = 0, f \in T_k$ .

The algebra we need is a direct sum of the vector spaces  $T_k$  and  $H_k$  with multiplication determined by the rule

$$(f + x)(g + y) = fg + xy,$$

where  $f, g$  are polynomials from  $T_k$  and  $x, y$  are elements from  $H_k$ . Let us denote this algebra by  $H^k$ . It is easy to see that for any  $k$  the algebra  $H^k$  is a Leibniz algebra.

**Lemma 1.** *The algebra  $H^k$  satisfies the identity (2), i.e.  $H^k \in {}_3\mathbf{N}$  for any  $k = 1, 2, \dots$*

Proof. If  $f_i \in T_k$  and  $x_i \in H_k, i = 1, 2, 3, 4$ , then

$$\begin{aligned} (f_1 + x_1)((f_2 + x_2)((f_3 + x_3)(f_4 + x_4))) \\ = (f_1 + x_1)((f_2 + x_2)(f_3x_4 + x_3x_4)) \\ = (f_1 + x_1)(f_2(x_3x_4) + x_2(x_3x_4)) = 0. \end{aligned} \quad \square$$

**Lemma 2.** *The vector space  $P_n({}_3\mathbf{N})$  is spanned by the multilinear products*

$$(4) \quad \Theta_{(i_1, i_1, \dots, i_m, j_1, \dots, j_m)} = x_i(x_{i_1}x_{j_1})(x_{i_2}x_{j_2}) \cdots (x_{i_m}x_{j_m})x_{k_1} \cdots x_{k_{n-2m-1}},$$

with  $i_s < j_s, s = 1, \dots, m, i_1 < i_2 < \dots < i_m, k_1 < k_2 < \dots < k_{n-2m-1}$ .

Proof. Note that the identities (1) and (2) allow us to transform the polynomial elements from  $P_n({}_3\mathbf{N})$  as follows. First,

$$(5) \quad xy_2y_1 = xy_1y_2 + x(y_2y_1)$$

and we can rearrange the positions of the generators in the left-normed products adding summands with products in parentheses. Second,

$$(6) \quad xy(zt) = x(zt)y$$

and we can move any product  $(x_{i_s}x_{j_s})$  if it does not stand at the most left position. Third, we can permute two generators inside brackets, namely

$$(7) \quad x(y_2y_1) = -x(y_1y_2).$$

Hence we can change the position of any pair of generators  $y_k$  and  $y_{k+1}$  using the identity (5):

$$y_1 \cdots y_k y_{k+1} = y_1 \cdots y_{k+1} y_k + y_1 \cdots y_{k-1} (y_k y_{k+1}), \quad k > 1.$$

Then by (7) we can rearrange the order of  $y_k$  and  $y_{k+1}$  in the product  $(y_k y_{k+1})$  if necessary and move it to the appropriate position using the identity (6)

$$y_1 \cdots y_{k-1} (y_k y_{k+1}) = y_1 \cdots (y_k y_{k+1}) y_{k-1} = \cdots = y_1 (y_k y_{k+1}) \cdots y_{k-1}$$

and (6) again allows to change the places of the products  $(y_i y_j)$ :

$$x(y_{\sigma(1)} z_{\sigma(1)}) \cdots (y_{\sigma(k)} z_{\sigma(k)}) = x(y_1 z_1) \cdots (y_k z_k), \quad \sigma \in S_k. \quad \square$$

The following proposition gives a set of algebras which generates the variety  ${}_3\mathbf{N}$  as well as a basis for the vector space  $P_n({}_3\mathbf{N})$ .

**Proposition 3.** (i) *The algebras  $H^k = T_k + H_k$ ,  $k = 1, 2, \dots$ , generate the variety  ${}_3\mathbf{N}$ .*

(ii) *The set of all elements (4) is a linear basis of  $P_n({}_3\mathbf{N})$ .*

**Proof.** By Lemma 2 every element of  $P_n({}_3\mathbf{N})$  is a linear combination of the elements of the type (4). Suppose that (4) enjoy the equality in  $P_n({}_3\mathbf{N})$

$$(8) \quad \sum_{(i, i_1, \dots, i_m, j_1, \dots, j_m)} \alpha_{(i, i_1, \dots, i_m, j_1, \dots, j_m)} \Theta_{(i, i_1, \dots, i_m, j_1, \dots, j_m)} = 0$$

for some  $\alpha_{(i, i_1, \dots, i_m, j_1, \dots, j_m)} \in F$ . Hence (8) is a polynomial identity for  ${}_3\mathbf{N}$  and vanishes on the algebras  $H^k$ . We will prove both parts of the proposition if we find a  $k > 0$  such that (8) is different from 0 for some elements in  $H^k$ . Each element  $\Theta_{(i, i_1, \dots, i_m, j_1, \dots, j_m)}$  is defined by the number  $m$  of products  $(x_{i_s} x_{j_s})$ , a fixed generator  $x_i$  and the  $2m$ -tuple  $(i_1, \dots, i_m, j_1, \dots, j_m)$  (satisfying  $i_1 < i_2 < \dots < i_m, i_1 < j_1, \dots, i_m < j_m$ ). Pick the element  $\Theta_I, I = (i, i_1, \dots, i_m, j_1, \dots, j_m)$  with nonzero coefficient  $\alpha_I$  which contains the least number  $m$  of products. Replace the variables  $x_s, s = 1, 2, \dots, n$ , with the following elements of the algebra  $H^m$ :  $x_i = f, x_{i_s} = a_s, x_{j_s} = b_s, s = 1, \dots, m$ , (the rest of the elements  $x_\alpha$  are replaced by  $c$ ). Let us check that the value of all other  $\Theta_J, J \neq I$ , of the type (4) after this substitution is zero. Recall that  $xf = 0$  for any  $x$  from  $H_k$ . Hence any element  $\Theta_J$  will be zero, if its left factor is not equal to  $x_i$ . If  $\Theta_J$  has more than  $m$  products of degree 2 then it will be 0 since the element  $c$  from the center of algebra  $H_m$  will be placed into some  $(x_{i_s} x_{j_s})$ . The multiplication rules imply that  $\Theta_J$  takes zero value as soon as  $J \neq I$ .

So, the result of the substitution is equal to  $\alpha_I \cdot f c^{n-m-1} = \alpha_I \cdot f \neq 0$  and all elements (4) are linearly independent. This completes the proof of the proposition.  $\square$

The following theorem describes the codimension sequence of  ${}_3\mathbf{N}$ .

**Theorem 4.** *The codimension sequence of  ${}_3\mathbf{N}$  satisfies*

$$c_n({}_3\mathbf{N}) = n \cdot \text{inv}(n - 1) = n \cdot \sum_{\lambda \vdash (n-1)} d_\lambda,$$

where  $\text{inv}(m)$  is the number of involutions (permutations of order two) in  $S_m$ .

*Proof.* There exists an obvious one-to-one correspondence between the elements (4) and the ordered pairs

$$(i, \{(i_1, j_1), (i_2, j_2), \dots, (i_m, j_m)\})$$

involving  $2m + 1$  pairwise different elements  $i, i_1, \dots, i_m, j_1, \dots, j_m$  such that  $i_1 < j_1, i_2 < j_2, \dots, i_m < j_m$ . We may identify the sets  $\{(i_1, j_1), (i_2, j_2), \dots, (i_m, j_m)\}$  with the involutions of the symmetric group  $S_{n-1}$  acting on  $\{1, \dots, i - 1, i + 1, \dots, n\}$  because any permutation  $\sigma \in S_{n-1}$  of order two can be written as a product of independent transpositions  $\sigma = \tau_1 \cdots \tau_m$ , where any transposition  $\tau_s$  has the form  $(i_s, j_s)$ ,  $s = 1, \dots, m$ .

Hence by Proposition 3 we conclude that

$$c_n({}_3\mathbf{N}) = \dim P_n({}_3\mathbf{N}) = n \cdot \text{inv}(n - 1),$$

where  $\text{inv}(n - 1)$  is the number of involutions in the symmetric group  $S_{n-1}$ . The second equality

$$n \cdot \text{inv}(n - 1) = n \cdot \sum_{\lambda \vdash (n-1)} d_\lambda$$

follows from the well known equality  $\text{inv}(m) = \sum_{\lambda \vdash m} d_\lambda$  (which can be found e.g. as Proposition 2 from [8]).  $\square$

Now we will show that the equality  $c_n({}_3\mathbf{N}) = n \cdot \sum_{\lambda \vdash (n-1)} d_\lambda$  reflects the structure of some  $S_{n-1}$ -submodules of  $P_n({}_3\mathbf{N})$ . We consider the subspace  $Q_n^{(i)}$  of  $P_n({}_3\mathbf{N})$  spanned by all monomials starting with  $x_i$ :

$$Q_n^{(i)} = \text{span}\{x_i x_{j_1} \dots x_{j_{n-1}} \mid \{j_1, \dots, j_{n-1}\} = \mathbf{N}_n \setminus \{i\}\},$$

where  $i = 1, \dots, n$  and  $\mathbf{N}_n = \{1, 2, \dots, n\}$ .

All subspaces  $Q_n^{(i)}$ ,  $i = 1, \dots, n$ , have the same  $S_{n-1}$ -module structure, where  $S_{n-1}$  acts on  $\mathbf{N}_n \setminus \{i\}$ . For convenience we will investigate the  $S_{n-1}$ -module  $Q_n^{(n)}$ .

**Proposition 5.** *The character  $\chi(Q_n^{(n)})$  of the  $S_{n-1}$ -module  $Q_n^{(n)}$  is*

$$\chi(Q_n^{(n)}) = \sum_{\lambda \vdash (n-1)} \chi_\lambda,$$

i.e. it is a sum of all irreducible  $S_{n-1}$ -characters, all participating with multiplicity 1.

PROOF. Denote by  $\lambda'_i$  the  $i$ -th column of the Young diagram corresponding to the partition  $\lambda = (\lambda_1, \lambda_2, \dots, \lambda_m)$ .

Consider the associative polynomial

$$S_{\lambda'_i} = S_{\lambda'_i}(X_1, \dots, X_{\lambda'_i}) = \sum_{\sigma \in S_{\lambda'_i}} (-1)^\sigma X_{\sigma(1)} \cdots X_{\sigma(\lambda'_i)}$$

where  $X_i$  is the operator of right multiplication by  $x_i$ ,  $i = 1, \dots, n$ , i.e.  $wX_i = wx_i$  and  $w(X_iX_j) = ((wx_i)x_j)$ . We relate with the partition  $\lambda$  the multihomogeneous element

$$(9) \quad x_n S_{\lambda'_1} S_{\lambda'_2} \cdots S_{\lambda'_m}.$$

If the polynomial (9) is a non-zero element of the free algebra of the variety  ${}_3\mathbf{N}$ , then its complete linearization generates an irreducible  $S_{n-1}$ -module of  $Q_n^{(n)}$  corresponding to  $\lambda$ . We will prove that for any partition  $\lambda \vdash (n-1)$  the polynomial (9) is not an identity for some algebra  $H^k$ .

We start with the case when the diagram of  $\lambda$  has only one column. Using the properties of our variety and the identity (1), we obtain

$$x_n S_{n-1}(X_1, \dots, X_{n-1}) = \frac{1}{2^k} \sum_{\sigma \in S_{n-1}} (-1)^\sigma x_n (x_{\sigma(1)} x_{\sigma(2)}) \cdots (x_{\sigma(2k-1)} x_{\sigma(2k)})$$

for odd  $n = 2k + 1$  and

$$x_n S_{n-1}(X_1, \dots, X_{n-1}) = \frac{1}{2^k} \sum_{\sigma \in S_{n-1}} (-1)^\sigma x_n (x_{\sigma(1)} x_{\sigma(2)}) \cdots (x_{\sigma(2k-1)} x_{\sigma(2k)}) x_{\sigma(n-1)}$$

for even  $n = 2k + 2$ .

Let us replace  $x_n$  with some  $f \in T_n$  and substitute  $a_1, b_1, a_2, b_2, \dots$  from  $H_n$  instead of  $x_1, x_2, x_3, x_4, \dots, x_{n-1}$  respectively. The result of the substitution is equal to  $\alpha \cdot (fc^k) = \alpha \cdot f$  when  $n = 2k + 1$  or  $\alpha \cdot (fc^k a_{k+1}) = \alpha \cdot f'_{k+1}$  where  $\alpha = \frac{k!}{2^k}$  and  $f'_{k+1}$  is the partial derivative with respect to  $t_{k+1}$ . All terms in the sum will equal zero except the case when for every  $s = 1, 2, \dots, k$  the pair  $a_s, b_s$  is within the same parentheses  $(a_s b_s)$ . Thus, for a suitable  $f$ , we have a non-zero result of the substitution.

Clearly, similar reasons work in the general situation.

So, for any partition  $\lambda \vdash (n-1)$  the element (9) is not equal to zero in  $P_n({}_3\mathbf{N})$ . In this way, the decomposition of the character  $\chi(Q_n^{(n)})$  as a sum of



irreducible characters of the symmetric group  $S_{n-1}$  has the form

$$\chi(Q_n^{(i)}) = \sum_{\lambda \vdash (n-1)} p_\lambda \chi_\lambda,$$

where  $p_\lambda \geq 1$  for all  $\lambda \vdash n - 1$ . This implies that

$$\dim Q_n^{(i)} = \sum_{\lambda \vdash (n-1)} p_\lambda d_\lambda \geq \sum_{\lambda \vdash (n-1)} d_\lambda, \quad i = 1, \dots, n.$$

Since the vector space  $P_n(3\mathbf{N})$  is the direct sum of the subspaces  $Q_n^{(i)}$  for  $i = 1, 2, \dots, n$ , we have

$$c_n(3\mathbf{N}) = \dim P_n(3\mathbf{N}) = \sum_{i=1}^n \dim Q_n^{(i)} \geq n \cdot \sum_{\lambda \vdash (n-1)} d_\lambda.$$

Hence, by Theorem 4,  $p_\lambda = 1$  for all  $\lambda \vdash n - 1$  and this completes the proof.  $\square$

Now we will investigate the multiplicities of the variety  $3\mathbf{N}$ .

The box of a Young diagram is called an ‘‘inner corner’’ if after removing this box, we also get a Young diagram. For example, the number of inner corners for the diagram of the partition  $(3, 2, 2, 1)$  equals to 3 and the diagram of the partition  $(4, 2, 2)$  has two inner corners.

Denote by  $r(\lambda)$  the number of inner corners of the diagram of the partition  $\lambda \vdash n$ . Clearly,  $r(\lambda)$  is equal to the number of distinct lengths of the rows of the Young diagram. Hence we have the restriction  $1 + 2 + \dots + r(\lambda) \leq n$ .

The following observation is obvious.

**Remark 6.**  $r(\lambda) < \sqrt{2n}$ .

**Theorem 7.** *The  $n$ -th cocharacter of the variety  $3\mathbf{N}$  has the form*

$$\chi_n(3\mathbf{N}) = \chi(P_n(3\mathbf{N})) = \sum_{\lambda \vdash n} r(\lambda) \chi_\lambda,$$

*i.e. the multiplicity  $m_\lambda$  is equal to the number  $r(\lambda)$  of the inner corners of the diagram of  $\lambda$ .*

**Proof.** Fix some partition  $\lambda \vdash n$ . Recall (see for example [5]) that the  $G$ -module  $V$  is *induced* from the  $H$ -module  $W$ , where  $H$  is a subgroup  $G$ , (and the representation of  $G$  in  $V$  is induced by the representation of  $H$  in  $W$ ) if  $W$  is a subspace of  $V$  and the following conditions hold:

- 1)  $W$  is a submodule of  $V$  considered as an  $H$ -module;
- 2)  $V = \bigoplus_{s \in G/H} sW$ .

So, from the definition of induced module we have that, as an  $S_n$ -module,  $P_n(3\mathbf{N})$  is induced by the  $S_{n-1}$ -module  $Q_n^{(n)}$ . Since, by Proposition 5, the character of  $Q_n^{(n)}$  is the sum of all irreducible  $S_{n-1}$ -characters, by the branching rule for

representations of symmetric groups we have that the multiplicity  $m_\lambda$  in  $\chi_n(3\mathbf{N})$  equals the number of inner corners of the diagram of the partition  $\lambda \vdash n$ . The proof of Theorem 7 is completed.  $\square$

By Remark 6 and Theorem 7 the multiplicities  $m_\lambda$  of the variety  $3\mathbf{N}$ ,  $\lambda \vdash n$ , are bounded by  $\sqrt{2n}$ . On the other hand, by the well known result about the number of different partitions, the colength of the variety  $3\mathbf{N}$  cannot be restricted by any polynomial function and has intermediate growth. We will obtain more precise asymptotics of the colength of  $3\mathbf{N}$ . Recall the asymptotic formula for the number  $p(n)$  of partitions of  $n$  (see [1]):

$$p(n) \sim \frac{1}{4n\sqrt{3}} \cdot e^{\pi\sqrt{\frac{2n}{3}}}.$$

**Corollary 8.** *The colength  $l_n(3\mathbf{N})$  satisfies the following inequalities*

$$p(n) \leq l_n(3\mathbf{N}) < \sqrt{2n} \cdot p(n),$$

where  $p(n)$  is the number of partitions of  $n$ .

*Proof.* From Theorem 7 we have

$$l_n(3\mathbf{N}) = \sum_{\lambda \vdash n} m_\lambda = \sum_{\lambda \vdash n} r(\lambda).$$

Using Remark 6 we obtain  $1 \leq m_\lambda < \sqrt{2n}$ . Hence we have the inequalities

$$p(n) \leq l_n(3\mathbf{N}) < \sqrt{2n} \cdot p(n).$$

The equality  $p(n) = l_n(3\mathbf{N})$  holds if and only if  $r(\lambda) = 1$  for all  $\lambda \vdash n$ , i.e. for  $n = 1, 2$ .  $\square$

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