# COMMUTANTS OF THE DUNKL OPERATORS IN $C(\mathbb{R})$ 

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#### Abstract

The Dunkl operators $D_{k} f(x)=\frac{d f(x)}{d x}+k \frac{f(x)-f(-x)}{x}, k \geq 0$, are considered in the space $C^{1}=C^{1}(\mathbb{R})$ of the smooth functions on $\mathbb{R}=(-\infty, \infty)$, and the operators $M: C(\mathbb{R}) \rightarrow C(\mathbb{R})$ with $M: C^{1}(\mathbb{R}) \rightarrow C^{1}(\mathbb{R})$ such that $M D_{k}=D_{k} M$ in $C^{1}(\mathbb{R})$ are characterized $(C(\mathbb{R})$ being the space of continuous functions on $\mathbb{R}$ ). Next, for a non-zero linear functional $\Phi: C(\mathbb{R}) \rightarrow \mathbb{C}$ the continuous linear operators $M$ with the invariant hyperplane $\Phi\{f\}=0$ and commuting with $D_{k}$ in it are also characterized. Further, mean-periodic functions for $D_{k}$ with respect to the functional $\Phi$ are introduced and it is proved that they form an ideal in a corresponding convolutional algebra $(C(\mathbb{R}), *)$. As an application the mean-periodic solutions of differentialdifference equations of the form $P\left(D_{k}\right) y=f$ with a polynomial $P$ are considered.

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## 1. Introduction

In the last two decades the differential-difference operators

$$
\begin{equation*}
D_{k} f(x)=\frac{d f(x)}{d x}+k \frac{f(x)-f(-x)}{x}, \quad k \geq 0 \tag{1}
\end{equation*}
$$

introduced by C. F. Dunkl [12] had been the item of numerous studies. For a survey of most of them see e.g. M. Rösler [15].

Nevertheless, some basic problems, connected with the Dunkl operators (1), still remain out of the attention of the researchers. We will mention here for example the spectral theory of $D_{k}$. Compared with the differentiation operator, there is no systematic study of it.

Here we attempt to solve some problems connected with $D_{k}$ which in a sense belongs to its spectral theory. For other operators their analogues are treated as application of their spectral theory. Here we prefer a direct approach, since till now no spectral theory of $D_{k}$ is available.

In the Introduction we consider some auxiliary results for the Dunkl operators to be used later. Most of them are found by other authors, and maybe only the general Taylor expansion for the Dunkl operators and a convolution product $f * g$ in $C(\mathbb{R})$ are new.

### 1.1. A family of operators commuting with $D_{k}$ : the translation operators $T_{k}^{y}$

The Dunkl translation (or shift) operators (see Trimeche [18] and M. Rösler [15]), are a class of operators $M: C(\mathbb{R}) \rightarrow C(\mathbb{R})$ commuting with $D_{k}$ in $C^{1}(\mathbb{R})$, and in a sence, they are the simplest such operators. Let us remind their definition.

Definition 1. Let $f \in C(\mathbb{R})$ and $y \in \mathbb{R}$. Then $\left(T_{k}^{y} f\right)(x)=u(x, y)$ is the solution of the initial value problem

$$
\begin{equation*}
D_{k, x} u(x, y)=D_{k, y} u(x, y), \quad u(x, 0)=f(x) . \tag{2}
\end{equation*}
$$

$T_{k}^{y}$ is said to be a translation operator for the Dunkl operator $D_{k}$.
Such solution $u(x, y)$ exists for arbitrary $f \in C(\mathbb{R})$ and it has the following explicit form (see e.g. [1] and [15]):
$T_{k}^{y} f(x)=\frac{\Gamma\left(k+\frac{1}{2}\right)}{\Gamma(k) \Gamma\left(\frac{1}{2}\right)}\left[\int_{0}^{\pi} f_{e}\left(\sqrt{x^{2}+y^{2}-2|x y| \cos t}\right) h^{e}(x, y, t) \sin ^{2 k-1} t d t\right.$

$$
\left.+\int_{0}^{\pi} f_{o}\left(\sqrt{x^{2}+y^{2}-2|x y| \cos t}\right) h^{o}(x, y, t) \sin ^{2 k-1} t d t\right]
$$

As usually, the subscripts " $e$ " and " $o$ " denote correspondingly the even and the odd part of a function $g: g_{e}(x)=\frac{g(x)+g(-x)}{2}, g_{o}(x)=\frac{g(x)-g(-x)}{2}$. If $h \in C(\mathbb{R})$, then

$$
\begin{aligned}
& h^{e}(x, y, t)=1-\operatorname{sign}(x y) \cos t \\
& h^{o}(x, y, t)= \begin{cases}\frac{(x+y)(1-\operatorname{sign}(x y) \cos t)}{\sqrt{x^{2}+y^{2}-2|x y| \cos t}} & \text { for }(x, y) \neq(0,0), \\
0 & \text { otherwise. }\end{cases}
\end{aligned}
$$

Lemma 1. The translation operators satisfy:
(i) $T_{k}^{y} f(x)=T_{k}^{x} f(y) \quad$ and
(ii) $T_{k}^{y} T_{k}^{z} f(x)=T_{k}^{z} T_{k}^{y} f(x)$.

Proof. (i) It follows by interchanging $x$ and $y$ in the definition (2). Then the solution is the same, but it has to be denoted by $T_{k}^{x} f(y)$, while the initial notation is $T_{k}^{y} f(x)$.

To prove (ii), use (i) as follows

$$
\begin{aligned}
& \left(T_{k}^{y} T_{k}^{z} f\right)(x)=T_{k}^{y}\left(T_{k}^{z} f(x)\right)=T_{k}^{y}\left(T_{k}^{x} f(z)\right)=T_{k}^{y}\left(T_{k}^{x} f\right)(z) \\
& =T_{k}^{z}\left(T_{k}^{x} f\right)(y)=T_{k}^{z}\left(T_{k}^{x} f(y)\right)=T_{k}^{z}\left(T_{k}^{y} f(x)\right)=\left(T_{k}^{z} T_{k}^{y} f\right)(x),
\end{aligned}
$$

which gives the result.
Lemma 2. Each of the operators $T_{k}^{y}$ commutes with $D_{k}$ in $C^{1}(\mathbb{R})$, i.e.

$$
\begin{equation*}
D_{k, x} T_{k}^{y} f(x)=T_{k}^{y} D_{k, x} f(x) . \tag{3}
\end{equation*}
$$

Proof. Applying $D_{k}$ to the defining equations (2) of the translation operator, it follows that

$$
\begin{aligned}
& D_{k, x}\left(D_{k, x} u(x, y)\right)= D_{k, x}\left(D_{k, y} u(x, y)\right)=\left(D_{k, x} D_{k, y}\right) u(x, y) \\
&=\left(D_{k, y} D_{k, x}\right) u(x, y)=D_{k, y}\left(D_{k, x} u(x, y)\right), \\
& D_{k, x} u(x, 0)=D_{k, x} f(x) .
\end{aligned}
$$

Here the commutation $D_{k, y} D_{k, x} g(x, y)=D_{k, x} D_{k, y} g(x, y)$ for any function $g(x, y) \in C^{1}(\mathbb{R} \times \mathbb{R})$ was used. Its validity is a straightforward check. Denote $v(x, y)=D_{k, x} u(x, y)=D_{k, x} T_{k}^{y} f(x)$ and $w(x)=D_{k, x} f(x)$. Then the above equalities are in fact the definition of the translation $v(x, y)=T_{k}^{y} w(x)$. Hence, substituting $v$ and $w$ yields the desired equality (3).

### 1.2. The right inverse operators of $D_{k}$ in $C(\mathbb{R})$ and their Taylor expansions

Let $L_{k}$ denote an arbitrary right inverse operator of $D_{k}$ in $C^{1}(\mathbb{R})$. Then, if $f \in C^{1}(\mathbb{R}), L_{k} f(x)=y(x)$ is the solution of the equation $D_{k} y(x)=f(x)$. Each such solution is determined up to an additive constant $C$.

First, let $y=L_{k} f$ be the solution of $D_{k} y(x)=f(x)$ with zero initial value condition, i.e. $y(0)=0$. It is easy to find that

$$
\begin{equation*}
L_{k} f(x)=\int_{0}^{x}\left[f_{o}(t)+\left(\frac{t}{x}\right)^{2 k} f_{e}(t)\right] d t \tag{4}
\end{equation*}
$$

where $f_{e}$ and $f_{o}$ are the even and the odd part of $f$, respectively.
Indeed, let $y(x)=L_{k} f(x)$ be represented as the sum of its even and odd parts, i.e. $y=y_{e}+y_{o}$. Then, in $D_{k} y(x)=f(x)$, which can be written as

$$
y_{e}^{\prime}+y_{o}^{\prime}+\frac{2 k}{x} y_{o}=f_{e}+f_{o},
$$

we separate the even and the odd part:

$$
y_{o}^{\prime}+\frac{2 k}{x} y_{o}=f_{e}, \quad y_{e}^{\prime}=f_{o} .
$$

Solving these two simultaneous equations and taking into account the initial condition $y(0)=0$ yields

$$
y_{e}(x)=\int_{0}^{x} f_{o}(t) d t \quad \text { and } \quad y_{o}(x)=\int_{0}^{x}\left(\frac{t}{x}\right)^{2 k} f_{e}(t) d t
$$

which gives the desired representation.
In the general case the representation of an arbitrary right inverse operator $L_{k}$ of $D_{k}$ is

$$
L_{k} f(x)=\int_{0}^{x}\left[f_{e}(t)+\left(\frac{t}{x}\right)^{2 k} f_{o}(t)\right] d t+C
$$

In order $L_{k}$ to be a linear operator, the additive constant $C$ should depend on $f$, i.e. it has to be a linear functional $\Psi\{f\}$. Hence, an arbitrary linear right inverse operator of $D_{k}$ in $C^{1}(\mathbb{R})$ has the form

$$
L_{k} f(x)=\int_{0}^{x}\left[f_{e}(t)+\left(\frac{t}{x}\right)^{2 k} f_{o}(t)\right] d t+\Psi\{f\}
$$

with a linear functional $\Psi$.
According to the general theory of right invertible operators (Bittner [2], Przeworska-Rolewicz [14]) an important characteristic of $L_{k}$ is its "initial projector"

$$
\begin{equation*}
F f(x)=f(x)-L_{k} D_{k} f(x)=\Phi\{f\} . \tag{5}
\end{equation*}
$$

It maps $C^{1}(\mathbb{R})$ onto $\operatorname{ker} D_{k}=\mathbb{R}$, i.e. it is a linear functional $\Phi$ on $C^{1}(\mathbb{R})$. Expressing $\Phi$ by $\Psi$, we obtain

$$
\Phi\{f\}=f(0)-\Psi\left\{D_{k} f\right\} .
$$

Let us note that $\Phi\{1\}=1$ which expresses the projector property of $F$.
Considering the right inverse operator $L_{k}$ of $D_{k}$, it is more convenient to obtain $L_{k} f$ as the solution of an elementary boundary value problem of the form

$$
\begin{equation*}
D_{k} y=f, \quad \Phi\{y\}=0, \tag{6}
\end{equation*}
$$

where $\Phi$ is a given linear functional on $C^{1}(\mathbb{R})$ with $\Phi\{1\}=1$.
The simplest case of such an operator is when $\Phi$ is the Dirac functional $\Phi\{f\}=f(0)$. Then $L_{k}$ is the operator (4). The general solution of (6) is
$L_{k} f(x)=\int_{0}^{x}\left[f_{e}(y)+\left(\frac{y}{x}\right)^{2 k} f_{o}(y)\right] d y-\Phi_{t}\left\{\int_{0}^{t}\left[f_{e}(y)+\left(\frac{y}{t}\right)^{2 k} f_{o}(y)\right] d y\right\}$.
Definition 2. The Dunkl-Appell polynomials $\left\{A_{k, n}(x)\right\}_{n=0}^{\infty}$ are introduced by the recurrences

$$
A_{k, 0}(x) \equiv 1, \quad \text { and } \quad D_{k} A_{k, n+1}(x)=A_{k, n}(x), \quad \Phi\left\{A_{k, n+1}\right\}=0, \quad n \geq 0
$$

Lemma 3. The Dunkl-Appell polynomials have the representation

$$
A_{k, n}(x)=L_{k}^{n}\{1\}(x),
$$

where $L_{k}$ is the right inverse (7) of the Dunkl operator $D_{k}$.
Proof. By induction: If $n=1$, then $D_{k} A_{k, 1}(x)=A_{k, 0}(x) \equiv 1 \equiv$ $L_{k}^{0}\{1\}(x)$ and therefore $A_{k, 1}(x)=L_{k}\{1\}(x)$. Now, suppose that the assertion is true for arbitrary $n \geq 0$. Then

$$
D_{k} A_{k, n+1}(x)=A_{k, n}(x)=L_{k}^{n}\{1\}(x), \Phi\left\{A_{k, n+1}\right\}=0,
$$

hence $A_{k, n+1}(x)=L_{k} A_{k, n}(x)=L_{k} L_{k}^{n}\{1\}(x)=L_{k}^{n+1}\{1\}(x)$, which proves the lemma.

Lemma 4. If $f \in C^{n}(\mathbb{R})$, then

$$
\begin{array}{r}
f(x)=\sum_{j=0}^{n-1} \Phi\left\{D_{k}^{j} f\right\} A_{k, j}(x)+L_{k}^{n}\left(D_{k}^{n} f\right)(x) \quad \text { and } \\
T_{k}^{y} f(x)=T_{k}^{x} f(y)=\sum_{j=0}^{n-1} \Phi\left\{T_{k}^{x} D_{k}^{j} f\right\} A_{k, j}(y)+L_{k}^{n}\left(T_{k}^{x} D_{k}^{n} f\right)(y), \tag{9}
\end{array}
$$

where $A_{k, j}(y)=L_{k}^{j}\{1\}(y)$ are the Dunkl-Appell polynomials, related to the functional $\Phi$.

Proof. Delsarte [5], Bittner [2], and Przeworska-Rolewicz [14] proposed variants of the Taylor formula for right invertible operators in linear spaces. In our case the general Taylor formula is the obvious operator identity

$$
I=\sum_{j=0}^{n-1} L_{k}^{j} F D_{k}^{j}+L_{k}^{n} D_{k}^{n},
$$

where $I$ is the identity operator and $F=I-L_{k} D_{k}$. In functional form the above identity takes the form

$$
f(x)=\sum_{j=0}^{n-1} L_{k}^{j} F D_{k}^{j} f(x)+L_{k}^{n} D_{k}^{n} f(x),
$$

where the initial projector $F$ of $L_{k}(5)$ is a linear functional $\Phi$ :

$$
F f(x)=f(x)-L_{k} D_{k} f(x)=\Phi\{f\} .
$$

$F$ projects the space $C(\mathbb{R})$ into the space $\mathbb{R}$ of the constants. Hence the Taylor formula with remainder term for the Dunkl operator $D_{k}$ is

$$
\begin{equation*}
f(x)=\sum_{j=0}^{n-1} \Phi\left\{D_{k}^{j} f\right\} L_{k}^{j}\{1\}(x)+L_{k}^{n} D_{k}^{n} f(x), \tag{10}
\end{equation*}
$$

which gives the result. (9) follows from (8) if we substitute $f(x)$ by $T_{k}^{y} f(x)$.
Corollary 1. If $f$ is a polynomial, then

$$
\begin{array}{r}
f(x)=\sum_{j=0}^{\infty} \Phi\left\{D_{k}^{j} f\right\} A_{k, j}(x) \quad \text { and } \\
T_{k}^{y} f(x)=T_{k}^{x} f(y)=\sum_{j=0}^{\infty} \Phi\left\{T_{k}^{x} D_{k}^{j} f\right\} A_{k, j}(y), \tag{12}
\end{array}
$$

where $A_{k, j}=L_{k}^{j}\{1\}$ are the Dunkl-Appell polynomials.
Further, we will use only the special case of the last formula, when $\Phi\{f\}=f(0)$. Then it takes the form

$$
\begin{equation*}
T_{k}^{y} f(x)=T_{k}^{x} f(y)=\sum_{j=0}^{\infty} D_{k}^{j} f(x) a_{k, j} y^{j} \tag{13}
\end{equation*}
$$

where $a_{k, j}$ are the constants
$a_{k, j}=\left\{\begin{array}{ll}\frac{1}{(2 k+1)(2 k+3) \ldots(2 k+2 m-1) \cdot 2 \cdot 4 \ldots(2 m-2)} & \text { if } j=2 m-1 \\ \frac{1}{(2 k+1)(2 k+3) \ldots(2 k+2 m-1) \cdot 2 \cdot 4 \ldots 2 m} & \text { if } j=2 m\end{array}\right.$.
The values of the constants are not important for our purposes, but let us mention that they can be found using the representation (4), which implies for odd and even powers

$$
L_{k} y^{2 m-1}=\frac{y^{2 m}}{2 m} \quad \text { and } \quad L_{k} y^{2 m}=\frac{y^{2 m+1}}{2 k+2 m+1} .
$$

Then, calculating consequently $L_{k}\{1\}, L_{k}^{2}\{1\}, \ldots, L_{k}^{j}\{1\}, \ldots$, the formula for $a_{k, j}$ follows by induction.

### 1.3. The intertwining operator $V_{k}$ for the Dunkl operator $D_{k}$

In Dunkl [12], Theorem 5.1, the similarity operator

$$
\begin{equation*}
V_{k} f(x)=b_{k} \int_{-1}^{1} f(x y)(1-y)^{k-1}(1+y)^{k} d y, \quad b_{k}=\frac{\Gamma(2 k+1)}{2^{2 k} \Gamma(k) \Gamma(k+1)} \tag{14}
\end{equation*}
$$

is found, which transforms the differentiation operator $D=\frac{d}{d x}$ into $D_{k}$ :

$$
V_{k} D=D_{k} V_{k}
$$

Some properties of this operator and its adjoint operator are studied by K. Trimeche [17].

In Ben Salem and Kallel [1] the inverse operator $V_{k}^{-1}$ of $V_{k}$ is given. Using the denotation $S f(x)=\frac{1}{2 x} \frac{d f(x)}{d x}$, it has the form:
(i) If $k=n+r$ with $n \in \mathbb{N}$ and $r \in(0,1)$, then for $x \neq 0$

$$
\begin{align*}
V_{k}^{-1} f(x)=c_{k} & {\left[|x| S^{n+1} \int_{0}^{|x|}\left(x^{2}-y^{2}\right)^{-r} f_{e}(y) y^{2 k} d y\right.} \\
& \left.+\operatorname{sign} x \cdot S^{n+1} \int_{0}^{|x|}\left(x^{2}-y^{2}\right)^{-r} f_{o}(y) y^{2 k+1} d y\right], \tag{15}
\end{align*}
$$

where

$$
c_{k}=\frac{2 \sqrt{\pi}}{\Gamma\left(n+r+\frac{1}{2}\right) \Gamma(1-r)} .
$$

(ii) If $k \in \mathbb{N}_{0}=\mathbb{N} \cup\{0\}$, then

$$
\begin{equation*}
V_{k}^{-1} f(x)=\frac{\sqrt{\pi}}{\Gamma\left(k+\frac{1}{2}\right)}\left[x S^{k}\left(x^{2 k-1} f_{e}(x)\right)+S^{k}\left(x^{2 k} f_{o}(x)\right)\right], \quad x \neq 0 . \tag{16}
\end{equation*}
$$

$V_{k}$ transforms $C(\mathbb{R})$ into a proper subspace $\widetilde{C_{k}}$ of it. We may expect that $V_{k}$ is a similarity from a right inverse operator $\Lambda$ of $D=\frac{d}{d x}$ to $L_{k}$. In order to specify the operator $\Lambda$ let us define the linear functional

$$
\begin{equation*}
\widetilde{\Phi}\{f\}=\left(\Phi \circ V_{k}\right)\{f\} \tag{17}
\end{equation*}
$$

in $\widetilde{C_{k}}$. Then define $\Lambda: \widetilde{C_{k}} \rightarrow \widetilde{C_{k}}$ to be the solution $y=\Lambda \widetilde{f}$ of the boundary value problem

$$
D y(x)=y^{\prime}(x)=\widetilde{f}(x), \quad \widetilde{\Phi}\{y\}=0 .
$$

Thus we obtain

$$
\begin{equation*}
\Lambda \widetilde{f}(x)=\int_{0}^{x} \widetilde{f}(y) d y-\widetilde{\Phi_{t}}\left\{\int_{0}^{t} \widetilde{f}(\tau) d \tau\right\} . \tag{18}
\end{equation*}
$$

Lemma 5. The following similarity relation holds:

$$
\begin{equation*}
V_{k} \Lambda=L_{k} V_{k} . \tag{19}
\end{equation*}
$$

Proof. Applying $V_{k}$ to the defining equation $D(\Lambda \widetilde{f})=\widetilde{f}$, one obtains

$$
V_{k} D(\Lambda \widetilde{f})=V_{k} \tilde{f}=f
$$

or

$$
D_{k}\left(V_{k} \Lambda \widetilde{f}\right)=V_{k} \tilde{f}=f .
$$

In fact, the boundary value condition $\widetilde{\Phi}\{\Lambda \widetilde{f}\}=0$ can be written as $\Phi\left\{V_{k} \Lambda \widetilde{f}\right\}=0$. Hence $u=V_{k} \Lambda \widetilde{f}$ is the solution of the boundary value problem $D_{k} u=f, \Phi\{u\}=0$, i.e. $u=L_{k} f$. Therefore

$$
V_{k} \Lambda V_{k}^{-1} f=L_{k} f \quad \text { or } \quad V_{k} \Lambda=L_{k} V_{k} .
$$

The similarity relation (19) allows to introduce a convolution structure *: $C(\mathbb{R}) \times C(\mathbb{R}) \rightarrow C(\mathbb{R})$, such that $L_{k}$ to be the convolution operator $L_{k}=\{1\} *$ in $C(\mathbb{R})$.

The operator $\Lambda$ is defined not only in $\widetilde{C}$, but in the whole space $C(\mathbb{R})$. This allows to introduce a convolution structure $\widetilde{*}: C(\mathbb{R}) \rightarrow C(\mathbb{R})$.

Lemma 6. (Dimovski [8], Theorem 2.1.1, p.52) The operation

$$
\begin{equation*}
(f \widetilde{* g})(x)=\widetilde{\Phi}_{t}\left\{\int_{t}^{x} f(x+t-\tau) g(\tau) d \tau\right\} \tag{20}
\end{equation*}
$$

is a bilinear, commutative and associative operation in $C(\mathbb{R})$, such that

$$
\begin{equation*}
\Lambda f=\{1\} \widetilde{*} f . \tag{21}
\end{equation*}
$$

Lemma 7. If $f, g \in C(\mathbb{R})$, then $f \widetilde{*} g \in C^{n}(\mathbb{R})$ where $n=k$ for integer $k$ and $n=[k]+1$ for noninteger $k$.

The proof follows from the results on the smoothness of convolution (20) in Bozhinov [3], Theorem 2.1.13, Corollary 4, since the linear functional $\widetilde{\Phi}=\Phi \circ V_{k}$ is a "smoothing" one.

Theorem 1. The operation

$$
\begin{equation*}
f * g=D_{k}^{2 n} V_{k}\left[\left(V_{k}^{-1} L_{k}^{n} f\right) \widetilde{*}\left(V_{k}^{-1} L_{k}^{n} g\right)\right] \tag{22}
\end{equation*}
$$

is a convolution of $L_{k}$ in $C(\mathbb{R})$ such that

$$
\begin{equation*}
L_{k} f=\{1\} * f \tag{23}
\end{equation*}
$$

Proof. First of all, the operation $f * g$ is well defined in $C(\mathbb{R})$. Indeed, from the inversion formulae (15) and (16) for $V_{k}$ it follows that $L_{k}^{n} f$ and $L_{k}^{n} g$ belong to the range of $V_{k}$, and hence $V_{k}^{-1} L_{k}^{n} f$ and $V_{k}^{-1} L_{k}^{n} g$ are functions from $C(\mathbb{R})$. From Lemma 7 it follows that $\left(V_{k}^{-1} L_{k}^{n} f\right)^{*}\left(V_{k}^{-1} L_{k}^{n} g\right) \in C^{n}(\mathbb{R})$.

The intertwining operator $V_{k}$ increases the order of smoothness by $n$ and hence $(22)$ is well defined in $C(\mathbb{R})$.

The operator $T=V_{k}^{-1} L_{k}^{n}$ is a transmutation operator of $L_{k}$ into $\Lambda$, i.e.

$$
\begin{equation*}
T L_{k}=\Lambda T \tag{24}
\end{equation*}
$$

Indeed, (24) is equivalent to (19). According to Dimovski [8], Theorem 1.3.6, p.26, the operation

$$
f \widehat{*} g=T^{-1}[T f \widetilde{*} T g]
$$

is a convolution of the operator $L_{k}=T^{-1} \Lambda T$ in $C(\mathbb{R})$, such that $f \widehat{*} g$ is in $C^{n}(\mathbb{R})$. Then $f * g=D_{k}^{n}(f \widehat{*} g)$ is well defined in $C(\mathbb{R})$ and (23) holds.

## 2. General commutant

The main result in this section is the following theorem.
ThEOREM 2. Let $M: C(\mathbb{R}) \rightarrow C(\mathbb{R})$ be a continuous linear operator with $M: C^{1}(\mathbb{R}) \rightarrow C^{1}(\mathbb{R})$. Then the following assertions are equivalent:
(i) $M$ commutes with the Dunkl operator

$$
D_{k} f(x)=\frac{d f(x)}{d x}+k \frac{f(x)-f(-x)}{x} \text { in } C^{1}(\mathbb{R})
$$

(ii) $M T_{k}^{y}=T_{k}^{y} M$ for every $y \in \mathbb{R}$;
(iii) $M$ admits a representation of the form

$$
\begin{equation*}
(M f)(x)=\Phi_{t}\left\{T_{k}^{t} f(x)\right\} \tag{25}
\end{equation*}
$$

with a continuous linear functional $\Phi: C(\mathbb{R}) \rightarrow \mathbb{C}$.
Proof. (i) $\Rightarrow$ (ii)
Suppose that $M$ commutes with the Dunkl operator $D_{k}$ in $C^{1}(\mathbb{R})$, i.e. $M D_{k} f=D_{k} M f$ for $f \in C^{1}(\mathbb{R})$. Then, for arbitrary $y \in \mathbb{R}$ and any polynomial $f(x)$, Taylor formula (13) implies

$$
\begin{gathered}
\left(M T_{k}^{y} f\right)(x)=\left(M T_{k}^{x} f\right)(y)=M_{x} \sum_{n=0}^{\infty}\left(D_{k}^{n} f\right)(x) a_{k, n} y^{n} \\
=\sum_{n=0}^{\infty}\left(M D_{k}^{n} f\right)(x) a_{k, n} y^{n}=\sum_{n=0}^{\infty}\left(D_{k}^{n} M f\right)(x) a_{k, n} y^{n} \\
=\sum_{n=0}^{\infty}\left(D_{k}^{n}(M f)\right)(x) a_{k, n} y^{n}=\left(T_{k}^{x} M f\right)(y)=\left(T_{k}^{y} M f\right)(x) .
\end{gathered}
$$

Since $M T_{k}^{y}=T_{k}^{y} M$ is true for polynomials, then this is true for arbitrary $f \in C^{1}(\mathbb{R})$. One should simply use approximation by polynomials.
(ii) $\Rightarrow$ (i)

Suppose $M T_{k}^{t}=T_{k}^{t} M$ for every $t \in \mathbb{R}$. For arbitrary polynomial $f(x)$ reverse the order in the above chain of equalities as follows:

$$
\begin{aligned}
& \sum_{n=0}^{\infty}\left(M D_{k}^{n} f\right)(x) a_{k, n} y^{n}=\left(M\left(T_{k}^{t} f\right)\right)(x) \\
= & \left(T_{k}^{t}(M f)\right)(x)=\sum_{n=0}^{\infty}\left(D_{k}^{n} M f\right)(x) a_{k, n} y^{n}
\end{aligned}
$$

The sums have to coincide for every $x$ and hence the coefficients of $y^{n}$ are equal for arbitrary $n$. For $n=1$ it follows that

$$
\begin{equation*}
\left(M\left(D_{k} f\right)\right)(x)=\left(D_{k}(M f)\right)(x) . \tag{26}
\end{equation*}
$$

Assuming that (26) is true for polynomials, it follows that it is true for arbitrary $f \in C^{1}(\mathbb{R})$ since $f$ could be approximated by polynomials.
(ii) $\Rightarrow$ (iii)

Let

$$
\begin{equation*}
M T_{k}^{y} f(x)=T_{k}^{y} M f(x), \quad \forall y \in \mathbb{R} \tag{27}
\end{equation*}
$$

The property $T_{k}^{y} f(x)=T_{k}^{x} f(y)$ applied to the right hand side of (27) gives

$$
\begin{equation*}
\left(M\left(T_{k}^{y} f\right)\right)(x)=\left(T_{k}^{x}(M f)\right)(y) \tag{28}
\end{equation*}
$$

Define the linear functional $\Phi$ as

$$
\Phi\{f\}:=(M f)(0) .
$$

Then, substituting $y=0$ in (28) and taking into account that $T_{k}^{0}$ is the identity operator, one has

$$
\begin{equation*}
\left(M\left(T_{k}^{y} f\right)\right)(0)=\left(T_{k}^{0}(M f)\right)(y)=(M f)(y) \tag{29}
\end{equation*}
$$

The left hand side is the value of the functional $\Phi$ for the function $g(x)=\left(T_{k}^{y} f\right)(x)$, and hence

$$
(M f)(y)=\Phi_{t}\left\{\left(T_{k}^{y} f\right)(t)\right\}=\Phi_{t}\left\{\left(T_{k}^{t} f\right)(y)\right\}
$$

using (28) and property (i) from Lemma 1 . This in fact is the desired representation (25) of the commutant of $D_{k}$ with $y$ for $x$, and with the dumb variable $t$ instead of $y$.
(iii) $\Rightarrow$ (ii)

It is a matter of a direct check to show that the operators of the form (25) commute with $T_{k}^{y}$ for every $y \in \mathbb{R}$ :

$$
\begin{gathered}
M T_{k}^{y} f(x)=\Phi_{t}\left\{\left(T_{k}^{t} T_{k}^{y} f\right)(x)\right\}=\Phi_{t}\left\{\left(T_{k}^{y} T_{k}^{t} f\right)(x)\right\} \\
\left.=T_{k}^{y} \Phi_{t}\left\{T_{k}^{t} f\right)(x)\right\}=T_{k}^{y} M f(x)
\end{gathered}
$$

This completes the proof.
Remark 1. From Kahane [13] it follows that the commutant of the differentiation operator $D_{0}$ in $C^{1}([-a, a])$ consists only of the trivial operators $M f(x)=c f(x)$, where $c=$ const. The same is true for $D_{k}, k>0$, too. For the proof, the intertwining operator $V_{k}$ has to be used.

## 3. The commutant of $D_{k}$ in an invariant hyperplane

A hyperplane in $C(\mathbb{R})$ can be defined by an arbitrary nonzero linear functional $\Phi$ in $C(\mathbb{R})$. Such a functional has an explicit Riesz-Markov representation

$$
\Phi\{f\}=\int_{\alpha}^{\beta} f(t) d \mu(t)
$$

with $-\infty<\alpha \leq \beta<+\infty$ and with a Radon measure $\mu$ on $[\alpha, \beta]$. This measure $\mu$ is generated by a complex valued function of bounded variation and we will denote it also by $\mu$. It is convenient to assume that $\mu(t)$ is normalized in such a way that the representation to be unique. To this end we may assume that $\mu(t)$ is right-continuous and $\mu(\alpha)=0$. The case $\alpha=\beta$ is a special case of the Dirac functional $\Phi\{f\}=A f(\alpha)$. Here we do not consider this case separately (which it deserves on its own right) since it is embraced in the general case with the only assumption that $\Phi\{1\}=$ $\mu([\alpha, \beta]) \neq 0$.

Definition 3. A hyperplane in $C(\mathbb{R})$ defined by a nonzero linear functional $\Phi$ is said to be the subset of $C(\mathbb{R})$

$$
C_{\Phi}=\{f: f \in C(\mathbb{R}), \Phi\{f\}=0\} .
$$

Our main task in this section is to characterize the linear operators $M: C(\mathbb{R}) \rightarrow C(\mathbb{R})$ for which $C_{\Phi}$ is an invariant hyperplane, i.e. with $M\left(C_{\Phi}\right) \subset C_{\Phi}$, and which commute with a Dunkl operator $D_{k}$ in $C_{\Phi}^{1}$. As
usual, by $C_{\Phi}^{1}$ we denote the subspace of $C_{\Phi}$, consisting of smooth functions. The set of all such operators will be denoted by $\operatorname{Comm}_{\Phi}\left\{D_{k}\right\}$.

Since the commutation relation $M D_{k}=D_{k} M$ should be satisfied in $C_{\Phi}^{1}$, we will consider only operators $M: C(\mathbb{R}) \rightarrow C(\mathbb{R})$, for which $M$ : $C^{1}(\mathbb{R}) \rightarrow C^{1}(\mathbb{R})$. This restriction allows to give a complete constructive characterization of the commutant $\operatorname{Comm}_{\Phi}\left\{D_{k}\right\}$. Such restriction is not assumed in the next theorem.

Theorem 3. A linear operator $M: C(\mathbb{R}) \rightarrow C(\mathbb{R})$ belongs to $\operatorname{Comm}_{\Phi}$ $\left\{D_{k}\right\}$ iff it commutes with a right inverse operator $R_{\lambda_{0}}$ of $D_{k}^{\left(\lambda_{0}\right)}=D_{k}-\lambda_{0}$, defined by the boundary value condition $\Phi\left\{R_{\lambda_{0}} f\right\}=0$ provided $\lambda_{0} \in \mathbb{C}$ is such that $R_{\lambda_{0}}$ exists.

Proof. a) Let $\lambda_{0} \in \mathbb{C}$ be such that $R_{\lambda_{0}}$ exists. This means that the boundary value problem

$$
\left(D_{k}-\lambda_{0}\right) y=f, \quad \Phi\{y\}=0
$$

has a unique solution $y=R_{\lambda_{0}} f$ for arbitrary $f \in C(\mathbb{R})$. The operator $R_{\lambda_{0}}$ is such that $R_{\lambda_{0}}: C(\mathbb{R}) \rightarrow C_{\Phi}^{1}$. We are to prove that if for an operator $M: C(\mathbb{R}) \rightarrow C(\mathbb{R})$ one has $M R_{\lambda_{0}}=R_{\lambda_{0}} M$ and $M\left(C_{\Phi}\right) \subset C_{\Phi}$, then $M D_{k}=D_{k} M$ in $C_{\Phi}^{1}$.

Consider the function $h=\left(M D_{k}^{\left(\lambda_{0}\right)}-D_{k}^{\left(\lambda_{0}\right)} M\right) f$ for $f \in C_{\Phi}^{1}$. We will show that $R_{\lambda_{0}} h=0$. Indeed,

$$
\begin{aligned}
R_{\lambda_{0}} h & =R_{\lambda_{0}} M D_{k}^{\left(\lambda_{0}\right)} f-R_{\lambda_{0}} D_{k}^{\left(\lambda_{0}\right)} M f \\
& =M\left(R_{\lambda_{0}} D_{k}^{\left(\lambda_{0}\right)}\right) f-R_{\lambda_{0}} D_{k}^{\left(\lambda_{0}\right)} M f .
\end{aligned}
$$

According to Przeworska-Rolewicz [14] we have $R_{\lambda_{0}} D_{k}^{\left(\lambda_{0}\right)} f=f$ on $C_{\Phi}^{1}$. Then by the assumption $f \in C_{\Phi}^{1} \Rightarrow M f \in C_{\Phi}^{1}$ and hence $R_{\lambda_{0}} D_{k}^{\left(\lambda_{0}\right)} M f=M f$. Thus we obtain $R_{\lambda_{0}} h=M f-M f=0$, which implies $h=0$.
b) Conversely, let $M: C_{\Phi}(\mathbb{R}) \rightarrow C_{\Phi}(\mathbb{R})$ and $M D_{k}^{\left(\lambda_{0}\right)}=D_{k}^{\left(\lambda_{0}\right)} M$ in $C_{\Phi}^{1}$. If $f \in C(\mathbb{R})$, consider the function $g=\left(M R_{\lambda_{0}}-R_{\lambda_{0}} M\right) f$. It is easy to verify that $D_{k}^{\left(\lambda_{0}\right)} g=0$ and $\Phi\{g\}=0$. Indeed,

$$
\begin{aligned}
D_{k}^{\left(\lambda_{0}\right)} g & =D_{k}^{\left(\lambda_{0}\right)} M R_{\lambda_{0}} f-\left(D_{k}^{\left(\lambda_{0}\right)} R_{\lambda_{0}}\right) M f \\
& =M\left(D_{k}^{\left(\lambda_{0}\right)} R_{\lambda_{0}}\right) f-M f=M f-M f=0
\end{aligned}
$$

and

$$
\Phi\{g\}=\Phi\left\{M R_{\lambda_{0}} f\right\}-\Phi\left\{R_{\lambda_{0}} M f\right\}=0
$$

since $R_{\lambda_{0}}: C(\mathbb{R}) \rightarrow C_{\Phi}^{1}(\mathbb{R})$, i.e. $\Phi\left\{R_{\lambda_{0}} f\right\}=0$. Since $M: C_{\Phi} \rightarrow C_{\Phi}$, then $\Phi\left\{M R_{\lambda_{0}} f\right\}=0$. We proved that $g$ is the solution of the boundary value problem

$$
D_{\lambda_{0}} g=0, \quad \Phi\{g\}=0,
$$

and hence $g=0$.
Further, we may choose a $\lambda_{0} \in \mathbb{C}$ for which there exists $R_{\lambda_{0}}$ and look for the commutant of $R_{\lambda_{0}}$ in $C(\mathbb{R})$. For the sake of simplicity we assume that $\lambda_{0}=0$.

Let us find the operator $R_{0}=L_{k}$. It is the right inverse of $D_{k}$ defined by the solution of the boundary value problem

$$
\begin{equation*}
D_{k} y=f, \quad \Phi\{y\}=0 . \tag{30}
\end{equation*}
$$

The solution was given in (7) in the second part of the introduction and it is
$L_{k} f(x)=\int_{0}^{x}\left[f_{o}(y)+\left(\frac{y}{x}\right)^{2 k} f_{e}(y)\right] d y-\Phi_{t}\left\{\int_{0}^{t}\left[f_{o}(y)+\left(\frac{y}{t}\right)^{2 k} f_{e}(y)\right] d y\right\}$,
where it is assumed that $\Phi\{1\}=1$ and $f_{e}$ and $f_{o}$ are the even and the odd part of $f$ correspondingly.

According to Theorem 3 the problem of characterization of the commutant of $D_{k}$ in the invariant hyperplane $C_{\Phi}$ reduces to the problem of characterization of the the commutant of $L_{k}$ in $C(\mathbb{R})$. This is a more or less standard problem in the frames of the convolutional calculus (see Dimovski [8] and Bozhinov [3]). The general scheme is the following:

1. Find a separately continuous convolution of $L_{k}$ in $C(\mathbb{R})$, i.e. a bilinear, commutative and associative operation $f * g$, such that $L_{k}$ to be a convolutional operator $L_{k}=\{\varphi\} *$ for some $\varphi \in C(\mathbb{R})$.
2. Show that the commutant of $L_{k}$ in $C(\mathbb{R})$ coincides with the ring of the multipliers of the convolutional algebra $(C(\mathbb{R}), *)$. A sufficient condition is $L_{k}$ to have a cyclic element in $C(\mathbb{R})$ (see Dimovski [8], p.32, Theorem 1.3.10).
3. Then an operator $M: C(\mathbb{R}) \rightarrow C(\mathbb{R})$ commutes with $L_{k}$ in $C(\mathbb{R})$ iff it has the form

$$
M f=D_{k}(\varphi * f)
$$

In our case under the additional restriction $M: C^{1}(\mathbb{R}) \rightarrow C^{1}(\mathbb{R})$ we obtain the following complete characterization of the commutant:

$$
M \in \operatorname{Comm}_{C(\mathbb{R})}\left\{L_{k}\right\} \Longleftrightarrow M f=m * f+\mu f
$$

with $m \in C(\mathbb{R})$ and $\mu \in \mathbb{C}$.

Now we are ready to characterize the operators $M: C(\mathbb{R}) \rightarrow C(\mathbb{R})$ with $M: C^{1}(\mathbb{R}) \rightarrow C^{1}(\mathbb{R})$ commuting with $L_{k}$ in $C^{1}(\mathbb{R})$.

Theorem 4. A continuous linear operator $M: C(\mathbb{R}) \rightarrow C(\mathbb{R})$ with $M: C^{1}(\mathbb{R}) \rightarrow C^{1}(\mathbb{R})$ commutes with $L_{k}$ iff it admits a representation of the form

$$
\begin{equation*}
M f=m * f+\mu f \tag{31}
\end{equation*}
$$

with $m \in C(\mathbb{R})$ and $\mu \in \mathbb{C}$. This representation is uniquely determined.
Proof. The operator $L_{k}$ has the constant function $e(x) \equiv 1$ as a cyclic element in $C(\mathbb{R})$. Indeed, from the representation (23) it is seen that $L_{k}^{n}\{1\}$ is a polynomial of degree exactly $n$. Due to Weierstrass' approximation theorem, each $f \in C(\mathbb{R})$ can be approximated almost uniformly by linear combinations of $\left\{L_{k}^{n}\{1\}\right\}_{n=0}^{\infty}$, i.e. $\overline{\operatorname{span}}\left\{L_{k}^{n}\{1\}\right\}_{n=0}^{\infty}=C(\mathbb{R})$.

Hence the commutant of $L_{k}$ in $C(\mathbb{R})$ coincides with the ring of multipliers of the convolutional algebra $(C(\mathbb{R}), *)$ (see Dimovski $[8]$, Theorem 1.3.11, p. 33).

It remains to characterize the multipliers $M: C(\mathbb{R}) \rightarrow C(\mathbb{R})$ of the convolutional algebra $(C(\mathbb{R}), *)$. Apply $M$ to $L_{k} f=\{1\} * f$ to obtain

$$
M L_{k} f=(M\{1\}) * f
$$

Since $M L_{k}=L_{k} M$, then

$$
L_{k}(M f)=(M\{1\}) * f .
$$

Hence, applying $D_{k}$

$$
M f=D_{k}(M\{1\} * f) .
$$

Continue by using the formula

$$
D_{k}(M\{1\} * f)=\left(D_{k} M\{1\}\right) * f+\Phi\{M\{1\}\} f
$$

(see Dimovski [8], Theorem 1.3.8, p. 31). Thus the desired representation (31) is established with $m=D_{k} M\{1\}$ and $\mu=\Phi\{M\{1\}\}$.

In order to prove the uniqueness, assume that

$$
M=m_{1} * f+\mu_{1} f=m_{2} * f+\mu_{2} f \quad \text { or } \quad\left(m_{1}-m_{2}\right) * f=\left(\mu_{2}-\mu_{1}\right) f .
$$

Take $f(x) \equiv 1$ :

$$
L_{K}\left(m_{1}-m_{2}\right)=\mu_{2}-\mu_{1} .
$$

Apply $\Phi$ :

$$
0=\mu_{2}-\mu_{1},
$$

hence $\mu_{1}=\mu_{2}$.
From $\left(m_{1}-m_{2}\right) * f=0$ we obtain $m_{1}=m_{2}$, since the convolutional algebra $(C(\mathbb{R}), *)$ is annihilators-free. The proof is completed.

Combining Theorems 3 and 4 , we can state the following characterization result:

Theorem 5. Let $M: C(\mathbb{R}) \rightarrow C(\mathbb{R})$ be a linear operator with an invariant hyperplane $C_{\Phi}=\{f: f \in C(\mathbb{R}), \Phi\{f\}=0\}$ where $\Phi$ is a linear functional in $C(\mathbb{R})$ with $\Phi\{1\}=1$. If $M: C^{1}(\mathbb{R}) \rightarrow C^{1}(\mathbb{R})$, then the following assertions are equivalent:
(i) $M$ commutes with $D_{k}$ in $C_{\Phi}$;
(ii) $M$ admits a representation of the form

$$
\begin{equation*}
M f=m * f+\mu f, \tag{32}
\end{equation*}
$$

with $m \in C(\mathbb{R})$ and $\mu \in \mathbb{C}$.

## 4. Mean-periodic functions associated with the Dunkl operator

In Ben Salem and Kallel [1] the theory of the mean-periodic functions in $C(\mathbb{R})$, associated with the Dunkl operator $D_{k}$, is developed. This theory becomes more transparent if we use the explicit representations (25) and (32) of the commutants of $D_{k}$ and its right inverses.

Definition 4. A function $f \in C(\mathbb{R})$ is said to be mean-periodic for $D_{k}$ if it belongs to the kernel space (null-space) of a linear operator $M: C(\mathbb{R}) \rightarrow C(\mathbb{R})$ with $M: C^{1}(\mathbb{R}) \rightarrow C^{1}(\mathbb{R})$ commuting with $D_{k}$.

As we have seen in Section 2, Theorem 2, each operator $M: C(\mathbb{R}) \rightarrow$ $C(\mathbb{R})$ with $M D_{k}=D_{k} M$ in $C^{1}(\mathbb{R})$ has the form

$$
(M f)(x)=\Phi_{t}\left\{T_{k}^{t} f(x)\right\}
$$

with a linear functional $\Phi$ in $C(\mathbb{R})$, where $T_{k}^{t}$ is the generalized translation operator (2).

It is most natural to consider a class of mean-periodic functions depending on a fixed linear functional $\Phi$. Further we denote such a class by $M P_{\Phi}$.

To each class $M P_{\Phi}$ there corresponds the convolutional algebra $(C(\mathbb{R}), *)$, where $*$ is the operation (22).

Lemma 8. If $f \in M P_{\Phi}$, then $L_{k} f \in M P_{\Phi}$.
Proof. Denote

$$
\varphi(x)=\Phi_{t}\left\{T_{k}^{t} L_{k} f(x)\right\}
$$

We use the commutation relation $D_{k} T_{k}^{t}=T_{k}^{t} D_{k}$ (Lemma 2) to obtain

$$
D_{k} \varphi(x)=\Phi_{t}\left\{D_{k} T_{k}^{t} L_{k} f(x)\right\}=\Phi_{t}\left\{T_{k}^{t} D_{k} L_{k} f(x)\right\}=\Phi_{t}\left\{T_{k}^{t} f(x)\right\}=0 .
$$

Hence $\varphi(x)=C=$ const. But $\Phi\{\varphi\}=\Phi_{t}\left\{T_{k}^{t} \Phi_{x}\left\{L_{k} f(x)\right\}\right\}=0$ since $\Phi_{x}\left\{\left(L_{k} f(x)\right\}\right\}=0$. We proved that $C=0$.

Theorem 6. The class of mean-periodic functions $M P_{\Phi}$ is an ideal in the convolutional algebra $(C(\mathbb{R}), *)$.

Proof. Assume that $f \in M P_{\Phi}$, i.e.

$$
\Phi_{t}\left\{T_{k}^{t} f(x)\right\}=0
$$

From Lemma 7, it follows that $L_{k}^{n+1} f \in M P_{\Phi}$ for $n=0,1,2, \ldots$, i.e.

$$
\Phi_{t}\left\{T_{k}^{t} L_{k}^{n+1} f(x)\right\}=0
$$

Since $L_{k} f=\{1\} * f$, then $L_{k}^{n+1} f=A_{k, n} * f$, where the Dunkl-Appell polynomial $A_{k, n}$ is of degree exactly $n$. We have

$$
\Phi_{t}\left\{T_{k}^{t}\left(A_{k, n} * f\right)(x)\right\}=0
$$

and then we can assert that

$$
\Phi_{t}\left\{T_{k}^{t}(P * f)(x)\right\}=0
$$

for any polynomial $P$. By an approximation argument it follows that

$$
\Phi_{t}\left\{T_{k}^{t}(g * f)(x)\right\}=0
$$

for an arbitrary function $g \in C(\mathbb{R})$, i.e. that $g * f \in M P_{\Phi}$. This completes the proof.

This theorem could be used to study the problem for solving differentialdifference equations of the form

$$
\begin{equation*}
P\left(D_{k}\right) y=f, \tag{33}
\end{equation*}
$$

with a polynomial $P$ in a space $M P_{\Phi}$ of mean-periodic functions.
Here we will state only a typical result, leaving the complete study for a next publication.

THEOREM 7. In order a linear differential-difference equation of the form (33) to have a unique solution in $M P_{\Phi}$, it is necessary and sufficient no one of the eigenvalues of the problem $D_{k} u-\lambda u=0, \Phi(u)=0$, to be a root of the polynomial $P$.

Remark 2. Throughout of this paper (with the exception of Theorem 3) we assume that $\lambda=0$ is not an eigenvalue of the problem $D_{k} u-\lambda u=0$, $\Phi(u)=0$, and this allows some technical simplifications. Nevertheless, the main results remain valid without such assumption. How should be settled the singular case, when $\lambda=0$ is an eigenvalue, is shown in Dimovski and Hristov [9]. Representations (25) and (32) and the convolution (22) remain without any changes but one should use Theorem 3 .

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