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## 3 SIMULATION OF AUTOMATIC CONTROL OF AN IRRIGATION CANAL

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## 8 Abstract

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Improved water management and efficient investment in the modernization of irrigation schemes 10 are essential measures in many countries to satisfy the increasing demand for water. Automatic 11 control of the main canals is one method for increasing the efficiency and flexibility of irrigation 12 systems. In 2005, one canal in the irrigation scheme 'Sector BXII del Bajo Guadalquivir' was 13 monitored. This canal is representative of irrigation schemes in Southern Spain; it is divided into 14 four pools and supplies an area of 5,154 ha. Ultrasonic sensors and pressure transducers were 15 used to record the opening of gates and water levels at the upstream and downstream ends of 16 each canal pool. Using the recorded data and the SIC (Simulation of Irrigation Canals) hydraulic 17 model, two canal control options (local upstream control and distant downstream control) were 18 evaluated using a Proportional-Integral control algorithm. First, the SIC model was calibrated 19 and validated under steady-state conditions. Then the proportional and integral gains of the PI 20 algorithm were calibrated. The controllers were tested using theoretical demand changes 21 (constant outflow followed by a sudden demand increase or decrease) and real demand changes 22 generated on the basis of a spatially distributed crop water balance that included a number of 23 sources of variability (random and not random) in the determination of field irrigation timing and 24 depth. The results obtained show that only the distant downstream controller was able, quickly 25 and automatically, to adjust the canal dynamics to the varying water demands; it achieved this 26 efficiently and with few spills at the canal tail, even when there were sudden and significant flow 27 variations. 28

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31 downstream control, proportional-integral controller

<sup>30</sup> Keywords: flexibility of water delivery, on-demand operation, local upstream control, distant