# ON THE UNIFORM STRONG CONSISTENCY OF LOCAL POLYNOMIAL REGRESSION UNDER DEPENDENCE CONDITIONS 

Francisco-Fernández, M., Vilar-Fernández J.M. and Vilar-Fernández, J.A.

Departamento de Matemáticas, Facultad de Informática
Universidad de A Coruña 15071, SPAIN
mariofr@udc.es, eijvilar@udc.es and eijoseba@udc.es

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#### Abstract

In this paper, nonparametric estimators of the regression function, and its derivatives, obtained by means of weighted local polynomial fitting are studied. Consider the fixed regression model where the error random variables are coming from a stationary stochastic process satisfying a mixing condition. Uniform strong consistency, along with rates, are established for these estimators.

Furthermore, when the errors follow an $\mathrm{AR}(1)$ correlation structure, strong consistency


properties are also derived for a modified version of the local polynomial estimators proposed by Vilar-Fernández and Francisco-Fernández in (1).

## 1. INTRODUCTION AND DEFINITIONS

Let us consider the fixed regression model where the functional relationship between the design points, $x_{t, n}$, and the responses, $Y_{t, n}$, can be expressed as

$$
\begin{equation*}
Y_{t, n}=m\left(x_{t, n}\right)+\varepsilon_{t, n}, \quad 1 \leq t \leq n \tag{1.1}
\end{equation*}
$$

where $m(x)$ is a regression function and $\varepsilon_{t, n}, 1 \leq t \leq n$, is a sequence of unobserved random variables with zero mean and finite variance $\sigma^{2}$. For each $n$, it is assumed that $\varepsilon_{1, n}, \varepsilon_{2, n}, \ldots, \varepsilon_{n, n}$ have the same joint distribution as $\epsilon_{1}, \epsilon_{2}, \ldots, \epsilon_{n}$, where $\left\{\epsilon_{t}, t \in Z\right\}$ is a strictly stationary stochastic process. Finally, it is considered that the design points, $x_{t, n}$, $1 \leq t \leq n$, follow a regular design generated by a design density $f$; that is, for each $n$, the design points are defined by

$$
\begin{equation*}
\int_{0}^{x, n} f(x) d(x)=\frac{t-1}{n-1}, \quad 1 \leq t \leq n \tag{1.2}
\end{equation*}
$$

$f$ being a positive function (see (2)).
In this setting, the goal is to estimate the regression function, $m(x)=E(Y \mid X=x)$, and its derivatives when the errors are dependent, satisfying the strong mixing condition. To do this, the local polynomial regression (LPR) estimator will be considered in the present study. Assuming that the $(p+1)$ th derivative of the regression function at point $x$ exists,
then $\vec{\beta}(x)=\left(\beta_{0}(x), \beta_{1}(x), \cdots, \beta_{p}(x)\right)^{t}$, where $\beta_{j}(x)=m^{(j)}(x) /(j!)$, with $j=0,1, \ldots, p$, can be estimated by minimizing the function

$$
\begin{equation*}
\Psi(\vec{\beta}(x))=\sum_{t=1}^{n}\left(Y_{t, n}-\sum_{j=0}^{p} \beta_{j}(x)\left(x_{t, n}-x\right)^{j}\right)^{2} \omega_{t, n}, \tag{1.3}
\end{equation*}
$$

where $\omega_{t, n}=n^{-1} K_{n}\left(x_{t, n}-x\right)$ are the weights and $K_{n}(u)=h_{n}^{-1} K\left(h_{n}^{-1} u\right), K$ being a kernel function and $h_{n}$ the bandwidth or smoothing parameter that controls the size of the local neighborhood and so the amount of smoothing.

Now, commonly used matrix notation is introduced for concise presentation of results.
Denote

$$
\vec{Y}_{(n)}=\left(\begin{array}{c}
Y_{1, n} \\
\vdots \\
Y_{n, n}
\end{array}\right), \quad X_{(n)}=\left(\begin{array}{cccc}
1 & \left(x_{1, n}-x\right) & \cdots & \left(x_{1, n}-x\right)^{p} \\
\vdots & \vdots & \vdots & \vdots \\
1 & \left(x_{n, n}-x\right) & \cdots & \left(x_{n, n}-x\right)^{p}
\end{array}\right)
$$

and let $W_{(n)}=\operatorname{diag}\left(\omega_{1, n}, \ldots, \omega_{n, n}\right)$ be the diagonal array of weights. Then, by assuming the invertibility of $X_{(n)}^{t} W_{(n)} X_{(n)}$, the LPR estimator of $\vec{\beta}(x)$ is given by

$$
\begin{equation*}
\hat{\vec{\beta}}_{(n)}(x)=\left(X_{(n)}^{t} W_{(n)} X_{(n)}\right)^{-1} X_{(n)}^{t} W_{(n)} \vec{Y}_{(n)}=S_{(n)}^{-1}(x) \vec{T}_{(n)}(x) \tag{1.4}
\end{equation*}
$$

where $S_{(n)}(x)$ is the $(p+1) \times(p+1)$ array whose $(i+1, j+1)$ th element is $s_{i, j, n}(x)=$ $s_{i+j, n}(x), i, j=0,1, \ldots, p$, with

$$
\begin{equation*}
s_{j, n}(x)=\frac{1}{n} \sum_{t=1}^{n}\left(x_{t, n}-x\right)^{j} K_{n}\left(x_{t, n}-x\right), \quad 0 \leq j \leq 2 p \tag{1.5}
\end{equation*}
$$

and $\vec{T}_{(n)}(x)=\left(t_{0, n}(x), t_{1, n}(x), \ldots, t_{p, n}(x)\right)^{t}$, being

$$
\begin{equation*}
t_{j, n}(x)=\frac{1}{n} \sum_{t=1}^{n}\left(x_{t, n}-x\right)^{j} K_{n}\left(x_{t, n}-x\right) Y_{t, n}, \quad 0 \leq j \leq p \tag{1.6}
\end{equation*}
$$

So, the LPR estimator of $m^{(j)}(x)$ is given by $\hat{m}_{n}^{(j)}(x)=j!\hat{\beta}_{j}(x), \hat{\beta}_{j}(x)$ being the $j$ th component of $\hat{\vec{\beta}}_{(n)}(x), j=0,1, \ldots, p$.

Since early papers on LPR, (3) and (4), many other relevant papers on this smoothing method have appeared, showing that the LPR estimator presents several good properties. See, for example, (5), (6), (7), (8), (9), and the references within. In these papers the independence of the observations is assumed. The statistical properties of LPR estimator with dependent data have been studied in recent works ((10), (11), (12), (13), (14), (15) and (16)). In these works the regression model with random design is considered and the assumption of the data satisfying some mixing condition is used. In the present context of fixed design, the asymptotic normality of the LPR estimator was studied in (17) when the random error, $\varepsilon_{t}$, has absolutely summable autocovariances. A complete study of this smoothing method can also be found in monograph (18).

The present paper is devoted to establishing strong uniform consistency and obtaining sharp rates of almost sure convergence over a compact set of $\mathbf{R}$ of two estimators of $m(x)$ and its derivatives. The first of these estimators is the LPR estimator given in (1.4), considering that the random errors satisfy an $\alpha$-mixing condition. The second estimator considered is a modified version of the LPR estimator, which has been proposed by Vilar-Fernández and Francisco-Fernández in (1). This last estimator is studied in the particular case where the stochastic process $\epsilon_{t}$ follows an $\operatorname{AR}(1)$ type correlation structure

$$
\begin{equation*}
\epsilon_{t}=\rho \epsilon_{t-1}+e_{t}, t \in \mathbf{Z} \tag{1.7}
\end{equation*}
$$

with $|\rho|<1$ and $\left\{e_{t}\right\}_{t \in \mathcal{Z}}$, a noise process with mean zero and finite variance $\sigma_{e}^{2}$. The proposed
estimator is obtained in two steps. In the first step, a matrix $P_{(n)}$, defined by

$$
P_{(n)}=\left(\begin{array}{ccccc}
\sqrt{1-\rho^{2}} & 0 & 0 & \ldots & 0 \\
-\rho & 1 & 0 & \ldots & 0 \\
0 & -\rho & 1 & \ldots & 0 \\
\vdots & \ddots & \ddots & \ddots & \vdots \\
0 & \ldots & 0 & -\rho & 1
\end{array}\right),
$$

in the case of $\operatorname{AR}(1)$ errors, is used to transform the regression model and to get a new model where the errors are uncorrelated.

For this purpose, performing a Taylor series expansion, the regression model (1.1) can be approximated by

$$
\begin{equation*}
\vec{Y}_{(n)} \approx X_{(n)} \vec{\beta}(x)+\vec{\varepsilon}_{(n)} \tag{1.8}
\end{equation*}
$$

where $\vec{\varepsilon}_{(n)}=\left(\varepsilon_{1, n}, \varepsilon_{2, n}, \ldots, \varepsilon_{n, n}\right)$.
Then, the errors of the following regression model

$$
\begin{equation*}
P_{(n)} \vec{Y}_{(n)}=P_{(n)} X_{(n)} \vec{\beta}(x)+P_{(n)} \vec{\varepsilon}_{(n)} \tag{1.9}
\end{equation*}
$$

are uncorrelated.
Now, in the second step, assuming that $X_{(n)}^{t} P_{(n)}^{t} W_{(n)} P_{(n)} X_{(n)}$ is nonsingular, an estimator of $\vec{\beta}(x)$, generalized least squares estimator (GLPR), is obtained by using weighted least squares

$$
\begin{equation*}
\tilde{\vec{\beta}}_{G, n}(x)=\left(X_{(n)}^{t} P_{(n)}^{t} W_{(n)} P_{(n)} X_{(n)}\right)^{-1} X_{(n)}^{t} P_{(n)}^{t} W_{(n)} P_{(n)} \vec{Y}_{(n)}=\tilde{C}_{(n)}^{-1}(x) \tilde{\vec{G}}_{(n)}(x) \tag{1.10}
\end{equation*}
$$

where $\tilde{C}_{(n)}(x)=X_{(n)}^{t} P_{(n)}^{t} W_{(n)} P_{(n)} X_{(n)}$ and $\tilde{\vec{G}}_{(n)}(x)=X_{(n)}^{t} P_{(n)}^{t} W_{(n)} P_{(n)} \vec{Y}_{(n)}$.

As matrix $P_{(n)}$ is unknown, the new estimator of $\vec{\beta}(x)$ is obtained by changing $P_{(n)}$ to an estimator of it, $\hat{P}_{(n)}$. This new estimator is called feasible least squares estimator (FLPR) and it is given by

$$
\begin{equation*}
\hat{\vec{\beta}}_{F, n}(x)=\left(X_{(n)}^{t} \hat{P}_{(n)}^{t} W_{(n)} \hat{P}_{(n)} X_{(n)}\right)^{-1} X_{(n)}^{t} \hat{P}_{(n)}^{t} W_{(n)} \hat{P}_{(n)} \vec{Y}_{(n)}=\hat{C}_{(n)}^{-1}(x) \hat{\vec{G}}_{(n)}(x) \tag{1.11}
\end{equation*}
$$

where $\hat{C}_{(n)}^{-1}(x)$ is assumed to exist.
In the case of $\operatorname{AR}(1)$ errors considered here, the matrix $P_{(n)}$ is estimated on the basis of a previous consistent estimation of $\rho$. In (1), $\rho$ was estimated by

$$
\begin{equation*}
\hat{\rho}_{n}=\frac{\sum_{t=1}^{n-1} \hat{\varepsilon}_{t, n} \hat{\varepsilon}_{t+1, n}}{\sum_{t=1}^{n} \hat{\varepsilon}_{t, n}^{2}} \tag{1.12}
\end{equation*}
$$

where $\hat{\varepsilon}_{t, n}=Y_{t, n}-\hat{m}_{n}\left(x_{t, n}\right), 1 \leq t \leq n$, are nonparametric residuals and $\hat{m}_{n}(x)$ is a consistent estimator of $m(x)$, for example, the LPR estimator. A natural estimator for $P_{(n)}$ is then obtained by replacing $\rho$ with $\hat{\rho}_{n}$.

Vilar-Fernández and Francisco-Fernández in (1) proved that the estimators $\hat{\vec{\beta}}_{(n)}(x)$ and $\hat{\vec{\beta}}_{F, n}(x)$ have the same asymptotic distribution. However, in a simulation study a better behavior was observed for the mean integrated squared error of estimator $\hat{\vec{\beta}}_{F, n}(x)$ with respect to $\hat{\vec{\beta}}_{(n)}(x)$ when correlation of the observations was large.

Before continuing, it is worth mentioning some works concerned with the study of strong consistency properties for kernel nonparametric estimators of the regression function under dependence conditions. For the regression model with random design, Collomb and Härdle in (19) obtained the strong uniform convergence of a robust nonparametric estimator under $\phi$-mixing conditions, Gyorfi et al. in (20) and Roussas in (21) proved strong consistency of the Nadaraya-Watson kernel estimator under several mixing conditions, Troung
and Stone in (22) obtained weak convergence rates under $\alpha$-mixing assumption and Masry and $\mathrm{Tj} ø$ stheim in (23) established strong convergence rates and asymptotic normality under $\alpha$-mixing conditions. Recently, Lu and Cheng in (24) proved the distribution-free strong consistency under $\alpha$-mixing and quite mild conditions, Ango Nze and Douckan in (25) considered delta-sequence estimators and established uniform convergence in the mean and almost surely under $\alpha$-mixing conditions and absolute regularity. In (26), Masry employed the local polynomial fitting for the estimation of the multivariate regression function and obtained uniform strong consistency with rates for strong mixing processes. Vilar-Fernández and Vilar-Fernández in (16) studied a recursive local polynomial smoother under $\alpha$-mixing dependence and established properties of strong consistency.

In the case of nonparametric regression with fixed design, Roussas in (27) studied a general linear smoother of the regression function and obtained consistency in quadratic mean and strong consistency under several mixing conditions of the errors. Roussas et al. in (28) established the asymptotic normality of this estimator when the errors are $\alpha$-mixing and in (29), Tran et al. generalized this result dispensing of mixing assumptions and encompassing models with discrete noise.

The organization of this paper is as follows: in Section 2, the uniform strong convergence of the estimator $\hat{\vec{\beta}}_{(n)}(x)$ over compact subsets of $\mathbf{R}$ is proven and the rates of convergence are established. In Section 3, the uniform strong convergence for the new estimator $\hat{\vec{\beta}}_{F, n}(x)$ is obtained. Finally, Section 4 is devoted to the proofs of the results.

## 2. UNIFORM STRONG CONSISTENCY OF THE LPR ESTIMATOR

To establish the uniform strong convergence of the LPR estimator, $\hat{\vec{\beta}}_{(n)}(x)$, defined in (1.4), a standard proof technique based on using a Berstein's type inequality for strongly mixing sequences joint to a coupling argument due to Rio (30) is considered. First of all, it is necessary to split the error estimation. For this purpose, assuming the continuity of the first $(p+1)$ derivatives of $m(x)$, a Taylor series expansion around $x$ with an integral remainder is performed, so that

$$
\begin{equation*}
m\left(x_{t, n}\right)=\sum_{j=0}^{p} \frac{m^{(j)}(x)}{j!}\left(x_{t, n}-x\right)^{j}+\frac{m^{(p+1)}(x)}{(p+1)!}\left(x_{t, n}-x\right)^{p+1}+R_{t, n}(x), t=1, \ldots, n \tag{2.1}
\end{equation*}
$$

where

$$
\begin{equation*}
R_{t, n}(x)=\frac{\left(x_{t, n}-x\right)^{p+1}}{p!} \int_{0}^{1}(1-w)^{p}\left[m^{(p+1)}\left(x+w\left(x_{t, n}-x\right)\right)-m^{(p+1)}(x)\right] d w . \tag{2.2}
\end{equation*}
$$

In matrix form,

$$
\vec{M}_{(n)}=X_{(n)} \vec{\beta}(x)+\frac{m^{(p+1)}(x)}{(p+1)!}\left(\begin{array}{c}
\left(x_{1, n}-x\right)^{p+1}  \tag{2.3}\\
\vdots \\
\left(x_{n, n}-x\right)^{p+1}
\end{array}\right)+\vec{R}_{(n)}(x)
$$

with $\vec{M}_{(n)}=\left(m\left(x_{1, n}\right), \ldots, m\left(x_{n, n}\right)\right)^{t}$ and $\vec{R}_{(n)}(x)=\left(R_{1, n}(x), \ldots, R_{n, n}(x)\right)^{t}$.
Using (1.4) and (2.3), the following is obtained:

$$
\begin{equation*}
E\left(\hat{\vec{\beta}}_{(n)}(x)\right)=\vec{\beta}(x)+\frac{m^{(p+1)}(x)}{(p+1)!} S_{(n)}^{-1}(x) \vec{U}_{(n)}(x)+S_{(n)}^{-1}(x) \vec{V}_{(n)}(x), \tag{2.4}
\end{equation*}
$$

where $\vec{U}_{(n)}(x)$ and $\vec{V}_{(n)}(x)$ are $(p+1)$-dimensional vectors whose $(j+1)$ th components $U_{j, n}(x)$ and $V_{j, n}(x), j=0,1, \ldots, p$, are given by

$$
\begin{gathered}
U_{j, n}(x)=s_{j+p+1, n}(x) \\
V_{j, n}(x)=\frac{s_{j+p+1, n}(x)}{p!} \int_{0}^{1}(1-w)^{p}\left[m^{(p+1)}\left(x+w\left(x_{t, n}-x\right)\right)-m^{(p+1)}(x)\right] d w .
\end{gathered}
$$

From (2.4), the following decomposition for the error

$$
\begin{gather*}
\hat{\vec{\beta}}_{(n)}(x)-\vec{\beta}(x)=S_{(n)}^{-1}(x) \vec{T}_{(n)}^{\star}(x)+\frac{m^{(p+1)}(x)}{(p+1)!} S_{(n)}^{-1}(x) \vec{U}_{(n)}(x)+S_{(n)}^{-1}(x) \vec{V}_{(n)}(x) \\
=\vec{\Delta}_{1, n}(x)+\vec{\Delta}_{2, n}(x)+\vec{\Delta}_{3, n}(x) \tag{2.5}
\end{gather*}
$$

is directly derived, where it has been denoted that

$$
\vec{T}_{(n)}^{\star}(x)=\vec{T}_{(n)}(x)-E\left(\vec{T}_{(n)}(x)\right) .
$$

The vector $\vec{\Delta}_{1, n}(x)$ is random and the vectors $\vec{\Delta}_{2, n}(x)$ and $\vec{\Delta}_{3, n}(x)$ are deterministic. Now, to obtain the strong consistency of the LPR estimator, the convergence of these three vectors is studied next.

The following assumptions are required:
A.1. The kernel function $K(\cdot)$ is symmetric, positive, Lipschitz continuous and with a bounded support.
A.2. The sequence of bandwidths $\left\{h_{n}\right\}$ is such that $h_{n}>0, \forall n$, and $h_{n} \downarrow 0$ and $n h_{n} \uparrow \infty$ as $n \uparrow \infty$.
A.3. The matrix $S_{(n)}^{-1}(x)$ exists for $x \in A$, with $A$ a compact subset of R , and the design density function $f$ satisfies $0<C \leq f(x) \leq C^{\prime}<\infty$, with $C$ and $C^{\prime}$ real numbers.
A.4. The function $m^{(p+1)}(x)$ is uniformly continuous on $A$.
A.5. $E\left(\left|\varepsilon_{t}\right|^{\delta}\right)<\infty$, for some $\delta>2$.
A.6. The stationary process $\varepsilon_{t}$ is $\alpha$-mixing, with mixing coefficients $\alpha(k)$ such that

$$
\sum_{k=1}^{\infty} k \alpha(k)^{1-2 / \delta}<\infty
$$

A.7. Define the sequence $M_{n}=\left(n \ln n(\ln \ln n)^{1+\gamma}\right)^{1 / \delta}$, for some $0<\gamma<1$. Then $h_{n}$ is chosen in such a way that

$$
\gamma_{n}=\left(\frac{n M_{n}^{2}}{h_{n}^{3} \ln n}\right)^{1 / 2} \rightarrow \infty \quad \text { and } \quad b_{n}=\left(\frac{n h_{n}}{M_{n}^{2} \ln n}\right)^{1 / 2} \rightarrow \infty \quad \text { as } n \rightarrow \infty
$$

In addition, the $\alpha$-mixing sequence $\alpha(k)$ satisfies

$$
\sum_{n=1}^{\infty} \frac{n \gamma_{n}}{b_{n}}\left(\frac{n M_{n}^{2}}{h_{n} \ln n}\right)^{1 / 2} \alpha\left(b_{n}\right)<\infty
$$

Assumptions A.1, A.2, A.3, A. 4 and A. 5 are not very restrictive regularity conditions and are quite usual in the context of local polynomial regression. While assumption A. 6 is also a usual summability requirement on the mixing coefficients, assumption A. 7 is a more complex condition involving both the bandwidth and the $\alpha$-mixing sequence. It is imposed to determine an appropriate truncation sequence to obtain a precise block size when the Bernstein's block technique is employed. It has also been required by Masry in (26). It is quite usual to find complex conditions on the $\alpha$-mixing coefficients in the literature
concerning strong consistency. Interesting comments about this topic can be seen in Lu and Cheng in (24) (Remark 2.3).

In particular, it can be easily seen that if

$$
h_{n}=O\left(\frac{\ln n}{n}\right)^{\phi}, \text { with } \phi<1-2 / \delta
$$

then the conditions $\gamma_{n} \rightarrow \infty$ and $b_{n} \rightarrow \infty$ in assumption A. 7 are satisfied. If, in addition, the mixing coefficients are assumed to decay exponentially fast, that is, $\alpha(k)=O(\exp \{-\theta k\})$, then both assumption A. 6 and the summability restriction in assumption A. 7 are also satisfied for all $\theta>0$.

Another mixing case of interest is $\alpha(k)=O\left(k^{-\theta}\right)$. In such a case, straightforward calculations allow us to conclude that the summability restriction in assumption A. 7 is satisfied provided that

$$
\theta>\frac{(1+\phi) 5 / 2+3 / \delta}{(1-\phi) 1 / 2-1 / \delta}=L(\phi, \delta)
$$

Note that for fixed $\phi$, the function $L(\phi, \delta)$ is monotonically decreasing in $\delta$. Therefore, assumption A. 5 and the summability condition in assumption A. 7 move in opposite directions since the larger $\delta$ is chosen, the smaller $\theta$ can be selected.

In what follows $H_{(n)}$ denotes the diagonal array $\operatorname{diag}\left(1, h_{n}, h_{n}^{2}, \cdots, h_{n}^{p}\right)$ and $S$ is the $(p+1) \times(p+1)$ array whose $(i+1, j+1)$ th element is $s_{i, j}=\mu_{i+j}, i, j=0,1, \ldots, p$, where $\mu_{j}=\int u^{j} K(u) d u$ and $\vec{\mu}=\left(\mu_{p+1}, \ldots, \mu_{2 p+1}\right)^{t}$.

The following result of Francisco-Fernández and Vilar-Fernández given in (17) will be used.

PROPOSITION 1. If assumptions A. 1 and A. 2 hold, then

$$
\begin{equation*}
\lim _{n \rightarrow \infty} h_{n}^{-j} s_{j, n}(x)=f(x) \mu_{j}, \quad 0 \leq j \leq 2 p+1 \tag{2.6}
\end{equation*}
$$

Result (2.6) can be written in matrix form as

$$
\begin{equation*}
\lim _{n \rightarrow \infty} H_{(n)}^{-1} S_{(n)}(x) H_{(n)}^{-1}=f(x) S \tag{2.7}
\end{equation*}
$$

Proposition 1 is then used to obtain the uniform convergence for the deterministic terms $\vec{\Delta}_{2, n}(x)$ and $\vec{\Delta}_{3, n}(x)$.

PROPOSITION 2. If assumptions A.1-A. 4 hold, then

$$
\begin{equation*}
\sup _{x \in A} H_{(n)} \vec{\Delta}_{2, n}(x)=h_{n}^{p+1}\left(\sup _{x \in A} m^{(p+1)}(x)\right) \frac{1}{(p+1)!} S^{-1} \vec{\mu}(1+o(1))=O\left(h_{n}^{p+1}\right) \tag{2.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\sup _{x \in A} H_{(n)} \vec{\Delta}_{3, n}(x)=O\left(h_{n}^{p+2}\right) . \tag{2.9}
\end{equation*}
$$

Next, the strong consistency for the random term $\vec{\Delta}_{1, n}(x)$ is established.

PROPOSITION 3. If assumptions A.1-A. 7 are fulfilled, then

$$
\begin{equation*}
\sup _{x \in A} H_{(n)} \vec{\Delta}_{1, n}(x)=O\left(\frac{\ln n}{n h_{n}}\right)^{1 / 2} \text { almost sure. } \tag{2.10}
\end{equation*}
$$

The proof of Proposition 3 is the most complex step. The basic tool is the Bernstein's blocks technique which consists in approximating mixing sequences by independent sequences, so that a Bernstein-type exponential inequality can be applied. After the blocks are determined, an independence approximation argument must be used. In this paper a coupling theorem due to Rio in (30) is adopted, which has also been used by others (see for example Carbon, Tran and and Wu in (31)). Alternatively, other authors have considered a weaker argument from Bradley (32).

The following theorem follows from equation (2.5) and Propositions 2 and 3.

THEOREM 1. If assumptions A.1-A. 7 are fulfilled, then

$$
\begin{equation*}
\sup _{x \in A} H_{(n)}\left(\hat{\vec{\beta}}_{(n)}(x)-\vec{\beta}(x)\right)=O\left(h_{n}^{p+1}\right)+O\left(\frac{\ln n}{n h_{n}}\right)^{1 / 2} \text { almost sure. } \tag{2.11}
\end{equation*}
$$

In the next result, derived directly from Theorem 1, the uniform strong convergence and rates for the local polynomial estimator of the regression function and its derivatives are established.

COR OLLARY 1. Under the hypothesis of Theorem 1 , we have, for $j=0,1, \ldots, p$, that

$$
\begin{equation*}
\sup _{x \in A}\left(\hat{m}_{n}^{(j)}(x)-m^{(j)}(x)\right)=O\left(h_{n}^{p+1-j}\right)+O\left(\frac{\ln n}{n h_{n}^{1+2 j}}\right)^{1 / 2} \text { almost sure. } \tag{2.12}
\end{equation*}
$$

## 3. UNIFORM STRONG CONSISTENCY OF THE FLPR ESTIMATOR

This section is devoted to establishing the uniform strong convergence of the FLPR estimator, $\hat{\vec{\beta}}_{F, n}(x)$, defined in (1.11). Therefore, throughout this section it will be assumed that the stochastic process $\epsilon_{t}$ follows an $\mathrm{AR}(1)$ model with $|\rho|<1$.

Our attention will first focus on $\tilde{\vec{\beta}}_{G, n}(x)$, the estimator defined in (1.10). In particular, conditions to ensure the uniform strong convergence of $\tilde{\vec{\beta}}_{G, n}(x)$ will be established.

Approximating the vector $\vec{M}_{(n)}$ with a Taylor series in a neighborhood of $x$ and employing similar arguments as those used in the previous section, the following decomposition of the error is obtained:

$$
\begin{gather*}
\tilde{\vec{\beta}}_{G, n}(x)-\vec{\beta}(x)=\tilde{C}_{(n)}^{-1}(x) \tilde{\vec{G}}_{(n)}^{*}(x)+\frac{m^{(p+1)}(x)}{(p+1)!} \tilde{C}_{(n)}^{-1}(x) \tilde{\vec{U}}_{(n)}(x)+\tilde{C}_{(n)}^{-1}(x) \tilde{\vec{V}}_{(n)}(x) \\
=\tilde{\vec{\Delta}}_{1, n}(x)+\tilde{\vec{\Delta}}_{2, n}(x)+\tilde{\vec{\Delta}}_{3, n}(x), \tag{3.1}
\end{gather*}
$$

where

$$
\tilde{\vec{G}}_{(n)}^{*}(x)=\tilde{\vec{G}}_{(n)}(x)-E\left(\tilde{\vec{G}}_{(n)}(x)\right),
$$

and $\tilde{\vec{U}}_{(n)}(x)$ and $\tilde{\vec{V}}_{(n)}(x)$ are $(p+1)$-dimensional vectors analogous to $\vec{U}_{(n)}(x)$ and $\vec{V}_{(n)}(x)$ in (2.4), respectively. Here, they are given by

$$
\begin{equation*}
\tilde{\vec{U}}_{(n)}(x)=X_{(n)}^{t} P_{(n)}^{t} W_{(n)} P_{(n)}\left(\left(x_{1, n}-x\right)^{p+1}, \ldots,\left(x_{n, n}-x\right)^{p+1}\right)^{t} \tag{3.2}
\end{equation*}
$$

and

$$
\begin{equation*}
\tilde{\vec{V}}_{(n)}(x)=X_{(n)}^{t} P_{(n)}^{t} W_{(n)} P_{(n)} \vec{R}_{(n)}(x), \tag{3.3}
\end{equation*}
$$

with $\vec{R}_{(n)}(x)$ given in (2.3).

Using basic algebra allows to derive the particular form for the $(j+1)$ th component of $\tilde{\vec{U}}_{(n)}(x)$, for $j=0,1, \ldots, p$ :

$$
\begin{aligned}
\tilde{U}_{j, n}(x)= & \tilde{c}_{j, p+1, n}(x) \\
= & \frac{1}{n} \sum_{t=1}^{n}\left(x_{t, n}-x\right)^{j+p+1} K_{n}\left(x_{t, n}-x\right)-\frac{\rho^{2}}{n}\left(x_{1, n}-x\right)^{j+p+1} K_{n}\left(x_{1, n}-x\right) \\
& -\frac{\rho}{n} \sum_{t=2}^{n}\left(x_{t, n}-x\right)^{j}\left(x_{t-1, n}-x\right)^{p+1} K_{n}\left(x_{t, n}-x\right) \\
& -\frac{\rho}{n} \sum_{t=2}^{n}\left(x_{t, n}-x\right)^{p+1}\left(x_{t-1, n}-x\right)^{j} K_{n}\left(x_{t, n}-x\right) \\
& +\frac{\rho^{2}}{n} \sum_{t=2}^{n}\left(x_{t-1, n}-x\right)^{j+p+1} K_{h}\left(x_{t, n}-x\right) .
\end{aligned}
$$

To show the convergence to zero of terms $\tilde{\vec{\Delta}}_{i, n}(x), i=1,2,3$, assumptions A.3, A. 4 and A. 7 are modified as follows:
A. $3^{\prime}$. The matrix $\tilde{C}_{(n)}^{-1}(x)$ exists for $x \in A$, with $A$ a compact subset of R , and the design density $f$ verifies $0<C \leq f(x)<C^{\prime}$, with $C$ and $C^{\prime}$ real numbers.
A. $4^{\prime}$. The functions $f^{\prime}$ and $m^{(p+1)}$ are continuous on $A$.
A. $7^{\prime}$. Denote $M_{n}=\left(n \ln n(\ln \ln n)^{1+\gamma}\right)^{1 / \delta}$ for some $0<\gamma<1$. The bandwidth $h_{n}$ is such that the sequences

$$
\gamma_{n}=\left(\frac{n M_{n}^{2}}{h_{n}^{3} \ln n}\right)^{1 / 2} \rightarrow \infty \quad \text { and } \quad b_{n}=\left(\frac{n h_{n}}{M_{n}^{2} \ln n}\right)^{1 / 2} \rightarrow \infty \quad \text { as } n \rightarrow \infty
$$

The next result, obtained by Vilar-Fernández and Francisco-Fernández in (1), is here used to show the convergence to zero of the deterministic terms $\tilde{\vec{\Delta}}_{2, n}(x)$ and $\tilde{\vec{\Delta}}_{3, n}(x)$.

PROPOSITION 4. If assumptions A.1, A.2, A. $3^{\prime}$ and A. $4^{\prime}$ hold, then

$$
\begin{equation*}
\lim _{n \rightarrow \infty} h_{n}^{-(i+j)} \tilde{c}_{i, j, n}(x)=(1-\rho)^{2} f(x) \mu_{i+j}, \quad 0 \leq i, j \leq p+1 \tag{3.4}
\end{equation*}
$$

Expression (3.4) can be rewritten in matrix form as follows:

$$
\begin{equation*}
\lim _{n \rightarrow \infty} H_{(n)}^{-1} \tilde{C}_{(n)}(x) H_{(n)}^{-1}=(1-\rho)^{2} f(x) S \tag{3.5}
\end{equation*}
$$

The strong consistency of both $\tilde{\vec{\Delta}}_{2, n}(x)$ and $\tilde{\vec{\Delta}}_{3, n}(x)$ is now a direct consequence of Proposition 4 and is established in the following result.

PROPOSITION 5. If assumptions A.1, A.2, A. $3^{\prime}$ and A. $4^{\prime}$ hold, then

$$
\begin{equation*}
\sup _{x \in A} H_{(n)} \tilde{\vec{\Delta}}_{2, n}(x)=O\left(h_{n}^{p+1}\right) \tag{3.6}
\end{equation*}
$$

and

$$
\begin{equation*}
\sup _{x \in A} H_{(n)} \tilde{\vec{\Delta}}_{3, n}(x)=O\left(h_{n}^{p+2}\right) . \tag{3.7}
\end{equation*}
$$

The strong convergence of the random term $\tilde{\vec{\Delta}}_{1, n}(x)$ is established in the following Proposition.

PROPOSITION 6. If assumptions A.1, A.2, A. $3^{\prime}$, A. $4^{\prime}$, A. 5 and A. $7^{\prime}$ are fulfilled, then

$$
\begin{equation*}
\sup _{x \in A} H_{(n)} \tilde{\vec{\Delta}}_{1, n}(x)=O\left(\frac{\ln n}{n h_{n}}\right)^{1 / 2} \text { almost sure. } \tag{3.8}
\end{equation*}
$$

In accordance with (3.1), the uniform strong convergence of the estimator $\tilde{\vec{\beta}}_{G, n}(x)$ follows from Propositions 5 and 6.

THEOREM 2. Under assumptions of Proposition 6, it is verified that

$$
\begin{equation*}
\sup _{x \in A} H_{(n)}\left(\tilde{\vec{\beta}}_{G, n}(x)-\vec{\beta}(x)\right)=O\left(h_{n}^{p+1}\right)+O\left(\frac{\ln n}{n h_{n}}\right)^{1 / 2} \quad \text { almost sure. } \tag{3.9}
\end{equation*}
$$

On the other hand, on the basis of the convergence in probability of the estimator $\hat{\rho}_{n}$, defined in (1.12), to the autoregressive coefficient $\rho$, the uniform strong convergence to zero of the term $H_{(n)}\left(\hat{\vec{\beta}}_{F, n}(x)-\tilde{\vec{\beta}}_{G, n}(x)\right)$ is obtained in the next result.

THEOREM 3. If assumptions A.1, A.2, A. $3^{\prime}$ and A. $4^{\prime}$ hold, then

$$
\begin{equation*}
\sup _{x \in A} H_{(n)}\left(\hat{\vec{\beta}}_{F, n}(x)-\tilde{\vec{\beta}}_{G, n}(x)\right)=o\left(h_{n}^{p+1}\right)+o\left(\frac{\ln n}{n h_{n}}\right)^{1 / 2} \text { almost sure. } \tag{3.10}
\end{equation*}
$$

From both, Theorems 2 and 3, the uniform strong convergence of the FLPR estimator $\hat{\beta}_{F, n}(x)$ is deduced.

THEOREM 4. Under assumptions of Theorem 2 it is verified that

$$
\begin{equation*}
\sup _{x \in A} H_{(n)}\left(\hat{\vec{\beta}}_{F, n}(x)-\vec{\beta}(x)\right)=O\left(h_{n}^{p+1}\right)+O\left(\frac{\ln n}{n h_{n}}\right)^{1 / 2} \text { almost sure. } \tag{3.11}
\end{equation*}
$$

If $\hat{m}_{F, n}^{(j)}(x)$ denotes the nonparametric feasible least squares estimator of $m^{(j)}(x)$, for $j=0,1, \ldots, p$, then $\hat{m}_{F, n}^{(j)}(x)=(j!) \hat{\beta}_{j, F, n}(x)$, being

$$
\hat{\vec{\beta}}_{F, n}(x)=\left(\hat{\beta}_{0, F, n}(x), \hat{\beta}_{1, F, n}(x), \ldots, \hat{\beta}_{p, F, n}(x)\right)^{t}
$$

Result (3.11) can be then reformulated in terms of $\hat{m}_{F, n}^{(j)}(x)$, as shown in Corollary 2.

COROLLARY 2. Under assumptions of Theorem 4, it is verified that

$$
\begin{equation*}
\sup _{x \in A}\left(\hat{m}_{F, n}^{(j)}(x)-m^{(j)}(x)\right)=O\left(h_{n}^{p+1-j}\right)+O\left(\frac{\ln n}{n h_{n}^{1+2 j}}\right)^{1 / 2} \text { almost sure. } \tag{3.12}
\end{equation*}
$$

The extension of these results to regression models with more general correlation structures, for example, $A R M A(p, q)$ models, is conceptually straightforward but with the drawback that the $P_{(n)}$ matrix depends on more parameters and these need to be estimated.

## 4. PROOFS

Throughout this section, the proofs of the results presented in sections 2 and 3 are outlined.

## PROOF OF PROPOSITION 2.

According to (2.5),

$$
\begin{aligned}
\vec{\Delta}_{2, n}(x) & =\frac{m^{(p+1)}(x)}{(p+1)!} S_{(n)}^{-1}(x) \vec{U}_{(n)}(x) \\
& =\frac{m^{(p+1)}(x)}{(p+1)!} h_{n}^{p+1} H_{(n)}^{-1}\left(H_{(n)}^{-1} S_{(n)}(x) H_{(n)}^{-1}\right)^{-1}\left(\frac{1}{h_{n}^{p+1}} H_{(n)}^{-1} \vec{U}_{(n)}(x)\right) .
\end{aligned}
$$

Then, using Proposition 1 it is obtained that

$$
\vec{\Delta}_{2, n}(x)=h_{n}^{p+1} \frac{m^{(p+1)}(x)}{(p+1)!} H_{(n)}^{-1} S^{-1} \vec{\mu}(1+o(1))
$$

and thus (2.8) is derived from the boundedness of $m^{(p+1)}(x)$.
The proof of (2.9) follows for similar arguments and it has been omitted.

## PROOF OF PROPOSITION 3.

From (2.5)

$$
H_{(n)} \vec{\Delta}_{1, n}(x)=\left(H_{(n)}^{-1} S_{(n)}(x) H_{(n)}^{-1}\right)^{-1} H_{(n)}^{-1} \vec{T}_{(n)}^{\star}(x) .
$$

The limit of $H_{(n)}^{-1} S_{(n)}(x) H_{(n)}^{-1}$ is given in (2.7), so that, it is sufficient to establish the almost sure convergence of $H_{(n)}^{-1} \vec{T}_{(n)}^{\star}(x)$, that is, of its components $h_{n}^{-j} t_{j, n}^{\star}(x)$, for $j=0,1, \ldots, p$.

Let $\left\{M_{n}\right\}$ be the sequence of positive numbers defined in A. 7 and let

$$
\begin{equation*}
\varepsilon_{t, M_{\mathrm{n}}}=\varepsilon_{t, n} I\left(\left|\varepsilon_{t, n}\right| \leq M_{n}\right) . \tag{4.1}
\end{equation*}
$$

Replacing $\varepsilon_{t}$ with $\varepsilon_{t, M_{\mathrm{n}}}$, new terms $t_{j, n}^{\star B}(x)$ are defined by

$$
\begin{equation*}
t_{j, n}^{\star B}(x)=\frac{1}{n} \sum_{t=1}^{n}\left(x_{t, n}-x\right)^{j} K_{n}\left(x_{t, n}-x\right) \varepsilon_{t, M_{n}}, \quad 0 \leq j \leq p, \tag{4.2}
\end{equation*}
$$

so that, for $j=0,1, \ldots, p$,

$$
\sup _{x \in A} h_{n}^{-j} t_{j, n}^{\star}(x) \leq \sup _{x \in A} h_{n}^{-j}\left(t_{j, n}^{\star}(x)-t_{j, n}^{\star B}(x)\right)+\sup _{x \in A} h_{n}^{-j} t_{j, n}^{\star B}(x)=Q_{j, 1, n}+Q_{j, 2, n} .
$$

Now, each term on the right-hand side above is examined. As far as term $Q_{j, 1, n}$ is concerned, it is observed that

$$
h_{n}^{-j}\left(t_{j, n}^{\star}(x)-t_{j, n}^{\star B}(x)\right)=\frac{1}{n} \sum_{t=1}^{n} \varepsilon_{t, n} I\left(\left|\varepsilon_{t, n}\right|>M_{n}\right) h_{n}^{-j}\left(x_{t, n}-x\right)^{j} K_{n}\left(x_{t, n}-x\right) .
$$

Under A. 5 and using Markov's inequality, it is obtained that

$$
P\left(\left|\varepsilon_{n, n}\right|>M_{n}\right) \leq M_{n}^{-\delta} E\left(\left|\varepsilon_{n, n}\right|^{\delta}\right)<\infty
$$

for sufficiently large $n$. In addition, Proposition 1 ensures the summability of the factor on the right-hand side. Therefore, Borel-Cantelli Lemma gives that $\left|\varepsilon_{n, n}\right| \leq M_{n}$ almost surely for all sufficiently large $n$. On the other hand, since $M_{n}$ is increasing, there exists $n$ such that $\left|\varepsilon_{t, n}\right| \leq M_{n}$ almost surely for $t \leq n$. From the above conclusions follows the almost sure convergence to zero of $Q_{j, 1, n}$, for $j=0,1, \ldots, p$.

Attention is now concentrated on the term $Q_{j, 2, n}$. Since $A$ is compact, it can be covered with $\gamma_{n}$ intervals of length $2 l_{n}$ and center $x_{k, n}^{\prime}$. Denote $I_{k, n}=\left[x_{k, n}^{\prime}-l_{n, x_{k, n}^{\prime}}^{\prime}+l_{n}\right], 1 \leq k \leq \gamma_{n}$, with $\gamma_{n} \rightarrow \infty$ as $n \rightarrow \infty$. Note that necessarily $l_{n}=O\left(\gamma_{n}^{-1}\right)$. Then

$$
\begin{gather*}
Q_{j, 2, n}=\sup _{x \in A} h_{n}^{-j} t_{j, n}^{\star B}(x) \\
\leq \max _{1 \leq k \leq \gamma_{n}} \sup _{x \in A \cap I_{k, n}} h_{n}^{-j}\left|t_{j, n}^{\star B}(x)-t_{j, n}^{\star B}\left(x_{k, n}^{\prime}\right)\right|+\max _{1 \leq k \leq \gamma_{n}} h_{n}^{-j}\left|t_{j, n}^{\star B}\left(x_{k, n}^{\prime}\right)\right|=P_{j, 1, n}+P_{j, 2, n} \tag{4.3}
\end{gather*}
$$

Under assumption A.1, for each $x \in I_{k, n}$ one has

$$
\begin{equation*}
h_{n}^{-j}\left|t_{j, n}^{\star B}(x)-t_{j, n}^{\star B}\left(x_{k, n}^{\prime}\right)\right| \leq C_{j} \frac{l_{n} M_{n}}{h_{n}^{2}}=C \frac{M_{n}}{\gamma_{n} h_{n}^{2}}, \tag{4.4}
\end{equation*}
$$

where $C$ is a positive real number. Taking into account (4.3), (4.4) and the definitions of the sequences $M_{n}$ and $\gamma_{n}$ given in A.7, it is concluded that

$$
\begin{equation*}
P_{j, 1, n} \leq C\left(\frac{\ln n}{n h_{n}}\right)^{1 / 2} \rightarrow 0 \quad \text { as } n \rightarrow \infty \tag{4.5}
\end{equation*}
$$

Thus, only the following remains to be proven:

$$
\begin{equation*}
P_{j, 2, n}=O\left(\frac{\ln n}{n h_{n}}\right)^{1 / 2} \text { almost sure. } \tag{4.6}
\end{equation*}
$$

The two following lemmas are necessary to show (4.6). The first of these lemmas is a coupling theorem for strongly mixing real-valued random variables.

LEM M A 1. (Theorem 4 of (30)) Let $\mathcal{A}$ be a $\sigma$-field of $(\Omega, \mathbf{z}, P)$ and let $X$ be a real-valued random variable taking almost sure values in $[a, b]$. Suppose furthermore that there exists a random variable $\beta$ with uniform distribution over $[0,1]$, independent of $\mathcal{A} \vee \sigma(X)$. Then, there exists some random variable $X^{*}$ independent of $\mathcal{A}$ and with the same distribution as $X$ such that

$$
E\left(\left|X-X^{*}\right|\right) \leq 2(b-a) \alpha(\mathcal{A}, \sigma(X)) .
$$

Moreover, $X^{*}$ is a $\mathcal{A} \vee \sigma(X) \vee \sigma(\beta)$-measurable random variable.

The second lemma is the Bernstein inequality. The proof can be seen in (33).

LEMMA 2. Let $Y_{1}, Y_{2}, \ldots, Y_{n}$ be independent bounded random variables with zero mean and $\left|Y_{i}\right| \leq M$. Denoting $\sigma_{i}^{2}$ as the variance of $Y_{i}$, and supposing $\sum_{i=1}^{n} \sigma_{i}^{2} \leq V$. Then, for each $\eta>0$,

$$
P\left(\left|\sum_{i=1}^{n} Y_{i}\right| \geq \eta\right) \leq 2 \exp \left(-\frac{1}{2} \eta^{2} /\left(V+\frac{1}{3} M \eta\right)\right)
$$

From (4.2), $h_{n}^{-j} t_{j, n}^{\star B}(x)$ can be written in the form

$$
\begin{equation*}
h_{n}^{-j} t_{j, n}^{\star B}(x)=\frac{1}{n} \sum_{t=1}^{n} \xi_{t, n}(x)=\Gamma_{n}(x), \tag{4.7}
\end{equation*}
$$

where

$$
\begin{equation*}
\xi_{t, n}(x)=\left(\frac{x_{t, n}-x}{h_{n}}\right)^{j} K_{n}\left(x_{t, n}-x\right) \varepsilon_{t, M_{\mathrm{n}}} . \tag{4.8}
\end{equation*}
$$

The Bernstein's blocks technique is used next. Set $n=2 s_{n} b_{n}+v_{n}$, where $s_{n}, b_{n}$ and $v_{n}$ are integer numbers satisfying $s_{n} \rightarrow \infty, b_{n} \rightarrow \infty$ as $n \rightarrow \infty$ and $0 \leq v_{n}<b_{n}$. Then, $\Gamma_{n}(x)$ is split into $2 s_{n}$ blocks of size $b_{n}$ plus a residual block of size $v_{n}$ as follows:

Define the blocks

$$
\begin{equation*}
B_{k, n}(x)=\frac{1}{n} \sum_{t=(k-1) b_{\mathrm{n}}+1}^{k b_{\mathrm{n}}} \xi_{t, n}(x), \quad k=1,2, \ldots, 2 s_{n} . \tag{4.9}
\end{equation*}
$$

So the partition of $\Gamma_{n}(x)$ is given by

$$
\begin{equation*}
\Gamma_{n}(x)=\frac{1}{n} \sum_{t=1}^{n} \xi_{t, n}(x)=\Gamma_{1, n}(x)+\Gamma_{2, n}(x)+\Gamma_{3, n}(x), \tag{4.10}
\end{equation*}
$$

where

$$
\begin{equation*}
\Gamma_{1, n}(x)=\sum_{j=1}^{s_{n}} B_{2 j-1, n}(x), \Gamma_{2, n}(x)=\sum_{j=1}^{s_{n}} B_{2 j, n}(x) \text { and } \Gamma_{3, n}(x)=\sum_{t=2 s_{n} b_{n}+1}^{n} \xi_{t, n}(x) \tag{4.11}
\end{equation*}
$$

Since the contribution of the residual term $\Gamma_{3, n}(x)$ is negligible, we have for each $\varepsilon>0$

$$
\begin{align*}
& P\left(\left|P_{j, 2, n}\right|>\varepsilon\right) \leq P\left(\max _{1 \leq k \leq \gamma_{n}}\left|\Gamma_{1, n}\left(x_{k, n}^{\prime}\right)\right|>\varepsilon / 2\right)+P\left(\max _{1 \leq k \leq \gamma_{n}}\left|\Gamma_{2, n}\left(x_{k, n}^{\prime}\right)\right|>\varepsilon / 2\right) \\
& \quad \leq 2 P\left(\max _{1 \leq k \leq \gamma_{n}}\left|\Gamma_{1, n}\left(x_{k, n}^{\prime}\right)\right|>\frac{\varepsilon}{2}\right) \leq 2 \gamma_{n} \sup _{x \in A} P\left(\left|\Gamma_{1, n}(x)\right|>\frac{\varepsilon}{2}\right) . \tag{4.12}
\end{align*}
$$

To bound the last term in (4.12) the independence approximation argument given in Lemma 1 is used next.

Let $\left\{U_{j}\right\}_{j>0}$ be a sequence of independent random variables with uniform distribution over $[0,1]$, independent of $\left\{B_{2 j-1, n}(x)\right\}_{j=1}^{s_{n}}$. By Lemma 1 , for any positive $j$, there exists a measurable function $F_{j}$ such that $B_{2 j-1, n}^{*}(x)=F_{j}\left(B_{1, n}(x), B_{3, n}(x), \ldots, B_{2 j-1, n}(x), U_{j}\right)$ satisfies the conditions of Lemma 1 (here $\left.\mathcal{A}=\sigma\left(B_{2 k-1, n}(x), 1 \leq k<j\right)\right)$. Therefore, for each
$j, B_{2 j-1, n}^{*}(x)$ is independent of $B_{1, n}^{*}(x), B_{3, n}^{*}(x), \ldots, B_{2 j-3, n}^{*}(x)$, has the same distribution as $B_{2 j-1, n}(x)$ and satisfies

$$
\begin{equation*}
E\left(\left|B_{2 j-1, n}(x)-B_{2 j-1, n}^{*}(x)\right|\right) \leq 2\left\|B_{2 j-1, n}(x)\right\|_{\infty} \alpha\left(b_{n}\right) \tag{4.13}
\end{equation*}
$$

From (4.9) and (4.11), it can be written that

$$
\begin{gather*}
P\left(\left|\Gamma_{1, n}(x)\right|>\frac{\varepsilon}{2}\right) \leq P\left(\left|\sum_{j=1}^{s_{n}}\left(B_{2 j-1, n}(x)-B_{2 j-1, n}^{*}(x)\right)\right|>\frac{\varepsilon}{4}\right) \\
\quad+P\left(\left|\sum_{j=1}^{s_{n}} B_{2 j-1, n}^{*}(x)\right|>\frac{\varepsilon}{4}\right)=\Delta_{1, n}(x)+\Delta_{2, n}(x) . \tag{4.14}
\end{gather*}
$$

By assumption A.1,

$$
\begin{equation*}
\left\|B_{2 j-1, n}(x)\right\|_{\infty}=\left\|\frac{1}{n} \sum_{t=(2 j-2) b_{n}+1}^{(2 j-1) b_{n}}\left(\frac{x_{t, n}-x}{h_{n}}\right)^{j} \frac{1}{h_{n}} K\left(\frac{x_{t, n}-x}{h_{n}}\right) \varepsilon_{t, M_{\mathrm{n}}}\right\|_{\infty} \leq C_{1} \frac{b_{n} M_{n}}{n h_{n}} \tag{4.15}
\end{equation*}
$$

with $C_{1}$ a positive constant. Then, by using Markov's inequality, (4.13) and (4.15), one has

$$
\begin{equation*}
\Delta_{1, n}(x) \leq \sum_{j=1}^{s_{n}} P\left(\left|B_{2 j-1, n}(x)-B_{2 j-1, n}^{*}(x)\right|>\frac{\varepsilon}{4 s_{n}}\right) \leq \frac{8 s_{n}^{2}}{\varepsilon} C_{1} \frac{b_{n} M_{n}}{n h_{n}} \alpha\left(b_{n}\right) \tag{4.16}
\end{equation*}
$$

Concerning $\Delta_{2, n}(x)$, if $\sigma_{j}^{2}$ denotes $\operatorname{Var}\left(B_{2 j-1, n}^{*}(x)\right)=\operatorname{Var}\left(B_{2 j-1, n}(x)\right)$, then Davidov's Lemma (see (34)) and assumption A. 6 lead to $\sum_{k=1}^{\infty} k|c(k)|<\infty$, where $\operatorname{Cov}\left(\epsilon_{t}, \epsilon_{t+k}\right)=\sigma^{2} c(k)$. Therefore Proposition 2 in (17) can be applied to obtain that

$$
\begin{equation*}
\sum_{j=1}^{s_{n}} \sigma_{j}^{2} \leq E\left(h_{n}^{-j} t_{j, n}^{\star}(x)\right)^{2}=\frac{1}{n h_{n}} \nu_{2 j} f(x) c(\varepsilon) \leq \frac{1}{n h_{n}} \nu_{2 j} C_{2} c(\varepsilon)=\frac{C_{v}}{n h_{n}} \tag{4.17}
\end{equation*}
$$

where $\nu_{2 j}=\int u^{2 j} K^{2}(u) d u, c(\varepsilon)=\sigma^{2}\left(c(0)+2 \sum_{k=1}^{\infty}|c(k)|\right)$ and $C_{2}$ and $C_{v}$ are positive constants.

Now, Lemma 2, (4.15) and (4.17) lead to

$$
\begin{equation*}
\Delta_{2, n}(x) \leq 2 \exp \left(-\frac{1}{2} \frac{\varepsilon^{2}}{16} /\left(\frac{C_{v}}{n h_{n}}+\frac{\varepsilon}{12} C_{1} \frac{b_{n} M_{n}}{n h_{n}}\right)\right)=2 \exp \left(-\frac{1}{32} \frac{\varepsilon^{2} n h_{n}}{C_{v}+C_{1} \varepsilon b_{n} M_{n} \frac{1}{12}}\right) . \tag{4.18}
\end{equation*}
$$

It follows from (4.12), (4.14), (4.16) and (4.18) that

$$
\begin{equation*}
P\left(\left|P_{j, 2, n}\right|>\varepsilon\right) \leq 2 \gamma_{n}\left[\left(\frac{8 s_{n}^{2}}{\varepsilon} C_{1} \frac{b_{n} M_{n}}{n h_{n}} \alpha\left(b_{n}\right)\right)+2 \exp \left(-\frac{1}{32} \frac{\varepsilon^{2} n h_{n}}{C_{v}+C_{1} \varepsilon b_{n} M_{n} \frac{1}{12}}\right)\right] . \tag{4.19}
\end{equation*}
$$

By choosing $\varepsilon=\varepsilon_{n}=C_{\varepsilon}\left(\frac{\ln n}{n h_{n}}\right)^{1 / 2}$, expression (4.19) can be written in the form

$$
P\left(\left|P_{2, j, n}\right|>\varepsilon\right) \leq a_{n}+b_{n},
$$

where

$$
a_{n}=\frac{16 C_{1}}{C_{\varepsilon}} \gamma_{n} \frac{n}{b_{n}}\left(\frac{M_{n}^{2} n}{h_{n} \ln n}\right)^{1 / 2} \alpha\left(b_{n}\right)
$$

and

$$
b_{n}=4 \gamma_{n} n^{\frac{-c_{\varepsilon}^{2}}{32\left(C_{v}+\frac{C_{1}}{12} C_{\varepsilon}\right)}} .
$$

From assumption A.7, the sequence $a_{n}$ is summable and by selecting a large enough $C_{\varepsilon}$, one can obtain that $b_{n}$ is also summable. Then, the Borel-Cantelli Lemma leads to (4.6) and the proof of Proposition 3 is completed.

## PROOF OF PROPOSITION 5.

This proof follows in the same way as Proposition 2 but using Proposition 4 instead of Proposition 1 and, therefore, it has been omitted.

## PROOF OF PROPOSITION 6.

Similar arguments to those used in Proposition 3 are employed here and only the main differences are presented below.

According to (3.1), $H_{(n)} \tilde{\vec{\Delta}}_{1, n}(x)=\left(H_{(n)}^{-1} \tilde{C}_{(n)}(x) H_{(n)}^{-1}\right)^{-1} H_{(n)}^{-1} \tilde{\vec{G}}_{(n)}^{*}(x)$. Since Proposition 4 ensures the convergence of the first term, our attention is focused on the components of $H_{(n)}^{-1} \tilde{\vec{G}}_{(n)}^{*}(x)$, which are given by

$$
h_{n}^{-j} \tilde{g}_{j, n}^{*}(x)=\frac{1}{n} \sum_{t=1}^{n} \chi_{t, n}(x)
$$

with

$$
\chi_{1, n}(x)=\left(1-\rho^{2}\right)\left(\frac{x_{1, n}-x}{h_{n}}\right)^{j} K_{n}\left(x_{1, n}-x\right) \varepsilon_{1, n}
$$

and

$$
\chi_{t, n}(x)=\left[\left(\frac{x_{t, n}-x}{h_{n}}\right)^{j}-\rho\left(\frac{x_{t-1, n}-x}{h_{n}}\right)^{j}\right] K_{n}\left(x_{t, n}-x\right) e_{t, n}, t=2,3, \ldots, n
$$

Note that the random variables $\left\{\chi_{t, n}(x)\right\}_{t=1}^{n}$ are independent.
Next, a truncation argument is again used. Let $\varepsilon_{t, M_{\mathrm{n}}}$ be as in (4.1) and consider the error variables defined by $e_{t, M_{\mathrm{n}}}=\varepsilon_{t, M_{\mathrm{n}}}-\rho \varepsilon_{t-1, M_{\mathrm{n}}}$. Then terms $\tilde{g}_{j, n}^{* B}(x)$ are constructed as $\tilde{g}_{j, n}^{*}(x)$, but replacing $\varepsilon_{1, n}$ with $\varepsilon_{1, M_{n}}$ and $e_{t, n}$ with $e_{t, M_{n}}, t=2, \ldots, n$. Hence, for $j=0, \ldots, p$,

$$
\sup _{x \in A} h_{n}^{-j} \tilde{g}_{j, n}^{*}(x) \leq \sup _{x \in A} h_{n}^{-j}\left(\tilde{g}_{j, n}^{*}(x)-\tilde{g}_{j, n}^{* B}(x)\right)+\sup _{x \in A} h_{n}^{-j} \tilde{g}_{j, n}^{* B}(x)=\tilde{Q}_{j, 1, n}+\tilde{Q}_{j, 2, n}
$$

For $\eta>0$, the Tchebyshev and Cauchy-Schwartz inequalities lead to

$$
P\left(\tilde{Q}_{j, 1, n}>\eta\right) \leq \sup _{x \in A}\left[\frac{1}{n \eta}\left(1-\rho^{2}\right)\left(\frac{x_{1, n}-x}{h_{n}}\right)^{j} K_{n}\left(x_{1, n}-x\right)\left[P\left(\left|\varepsilon_{1, n}\right|>M_{n}\right)\right]^{1 / 2} \sigma_{e}\right.
$$

$$
\left.+\frac{1}{n \eta} \sum_{t=2}^{n}\left(\left(\frac{x_{t, n}-x}{h_{n}}\right)^{j}-\rho\left(\frac{x_{t-1, n}-x}{h_{n}}\right)^{j}\right) K_{n}\left(x_{t, n}-x\right)\left[P\left(\left|e_{t}\right|>2 M_{n}\right)\right]^{1 / 2} \sigma_{e}\right] .
$$

Since $M_{n}$ is increasing, $\left|\varepsilon_{1, n}\right|<M_{n}$ and $\left|e_{t, n}\right|<2 M_{n}$ almost surely. Hence, using the Borel-Cantelli Lemma, it is concluded that $\tilde{Q}_{j, 1, n} \rightarrow 0$ almost sure as $n \rightarrow \infty$.

With regard to the almost sure convergence of $\tilde{Q}_{j, 2, n}$ we proceed as in (4.3). Consider $\gamma_{n}$ intervals $I_{k, n}=\left[x_{k, n}^{\prime}-l_{n,} x_{k, n}^{\prime}+l_{n}\right]$ covering $A$. Then

$$
\tilde{Q}_{j, 2, n}=\max _{1 \leq k \leq \gamma_{n}} \sup _{x \in A \cap I_{\mathrm{k}, n}} h_{n}^{-j}\left|\tilde{g}_{j, n}^{* B}(x)-\tilde{g}_{j, n}^{* B}\left(x_{k, n}^{\prime}\right)\right|+\max _{1 \leq k \leq \gamma_{n}} h_{n}^{-j}\left|\tilde{g}_{j, n}^{* B}\left(x_{k, n}^{\prime}\right)\right|=\tilde{P}_{j, 1, n}+\tilde{P}_{j, 2, n} .
$$

From assumption A.1,

$$
\begin{gathered}
\tilde{P}_{j, 1, n} \leq \frac{M_{n}\left(1-\rho^{2}\right) C_{j}}{n h_{n}}\left|\frac{x_{k, n}^{\prime}-x}{h_{n}}\right|+\frac{2 M_{n} C_{j}}{n h_{n}} \sum_{t=2}^{n}\left(\left|\frac{x_{k, n}^{\prime}-x}{h_{n}}\right|(1-\rho)+O\left(\frac{1}{n h_{n}}\right)\right) \\
=O\left(\frac{M_{n}}{h_{n}}\left(\frac{l_{n}}{h_{n}}+\frac{1}{n h_{n}}\right)\right)=O\left(\frac{M_{n}}{\gamma_{n} h_{n}^{2}}\right),
\end{gathered}
$$

and definitions of $M_{n}$ and $\gamma_{n}$ in A. $7^{\prime}$ allow us to conclude that $\tilde{P}_{j, 1, n} \leq O\left(\frac{\ln n}{n h_{n}}\right)^{1 / 2}$.
Thus, only the convergence of $\tilde{P}_{j, 2, n}$ remains to be studied. For each $\varepsilon>0$,

$$
\begin{equation*}
P\left(\max _{1 \leq k \leq \gamma_{n}} h_{n}^{-j}\left|\tilde{g}_{j, n}^{* B}\left(x_{k, n}^{\prime}\right)\right|>\varepsilon\right)=\gamma_{n} \sup _{x \in A} P\left(\left|\sum_{t=1}^{n} \frac{1}{n} \chi_{t, n}^{B}(x)\right|>\varepsilon\right), \tag{4.20}
\end{equation*}
$$

where $\chi_{t, n}^{B}(x)$ denotes independent random variables defined as $\chi_{t, n}(x)$, but replacing $\varepsilon_{1, n}$ with $\varepsilon_{1, M_{\mathrm{n}}}$ and $e_{t, n}$ with $e_{t, M_{\mathrm{n}}}$.

From assumptions A. 1 and A. $7^{\prime}$, it is obtained that

$$
\begin{equation*}
\left|\frac{1}{n} \chi_{t, n}^{B}(x)\right| \leq C_{e} \frac{M_{n}}{n h_{n}}, \quad t=1,2, \ldots, n, \tag{4.21}
\end{equation*}
$$

with $C_{e}$ being a positive constant.

On the other hand, taking into account the independence of random variables $\chi_{t, n}(x)$ and using Proposition 3.2 of (1), one has that

$$
\begin{equation*}
\sum_{t=1}^{n} \operatorname{Var}\left(\frac{1}{n} \chi_{t, n}^{B}(x)\right)=\operatorname{Var}\left(h_{n}^{-j} \tilde{g}_{j, n}^{* B}(x)\right) \leq \frac{1}{n h_{n}} \nu_{2 j} f(x)(1-\rho)^{2} \sigma_{e}^{2}=\frac{C_{v}}{n h_{n}} \tag{4.22}
\end{equation*}
$$

where $\sigma_{e}^{2}$ is the variance of $e_{t, n}$.
Using (4.21), (4.22) and the Berstein inequality (Lemma 2), as in (4.18), it is concluded that

$$
\begin{equation*}
P\left(\left|\sum_{t=1}^{n} \frac{1}{n} \chi_{t, n}^{B}(x)\right|>\varepsilon\right) \leq 2 \exp \left(\frac{-3 n h_{n} \varepsilon^{2}}{6 C_{v}+2 C_{e} M_{n} \varepsilon}\right) \tag{4.23}
\end{equation*}
$$

If the bound in (4.23) is considered in (4.20) and $\varepsilon=\varepsilon_{n}=C_{\varepsilon}\left(\frac{\ln n}{n h_{n}}\right)^{1 / 2}$ is taken with a large enough $C_{\varepsilon}$, then Borel-Cantelli's Lemma leads to

$$
\tilde{P}_{j, 2, n}=O\left(\frac{\ln n}{n h_{n}}\right)^{1 / 2} \text { almost sure }
$$

and the proof of Proposition 6 is completed.

## PROOF OF THEOREM 3.

From definitions (1.10) and (1.11),

$$
\begin{gather*}
H_{(n)}\left|\hat{\vec{\beta}}_{F, n}(x)-\tilde{\vec{\beta}}_{G, n}(x)\right| \\
=H_{(n)}\left|\left(X_{(n)}^{t} \hat{\Omega}_{n}^{-1} X_{(n)}\right)^{-1} X_{(n)}^{t} \hat{\Omega}_{n}^{-1} \vec{Y}_{(n)}-\left(X_{(n)}^{t} \Omega_{n}^{-1} X_{(n)}\right)^{-1} X_{(n)}^{t} \Omega_{n}^{-1} \vec{Y}_{(n)}\right|, \tag{4.24}
\end{gather*}
$$

where the matrices $\hat{P}_{(n)}^{t} W_{(n)} \hat{P}_{(n)}$ and $P_{(n)}^{t} W_{(n)} P_{(n)}$ have been denoted by $\hat{\Omega}_{n}^{-1}$ and $\Omega_{n}^{-1}$, respectively. In addition, the dependence on $x$ of all the matrices in (4.24) has been omitted for simplicity in notation.

Replacing $\vec{Y}_{(n)}$ with $\vec{M}_{(n)}+\vec{\varepsilon}_{(n)}$ and using (2.3), one obtains that

$$
\begin{equation*}
\sup _{x \in A} H_{(n)}\left|\hat{\vec{\beta}}_{F, n}(x)-\tilde{\vec{\beta}}_{G, n}(x)\right| \leq \Phi_{1, n}+\Phi_{2, n}+\Phi_{3, n} \tag{4.25}
\end{equation*}
$$

where

$$
\begin{aligned}
\Phi_{1, n} & =\sup _{x \in A}\left\{\frac{1}{(p+1)!} m^{(p+1)}(x) H_{(n)}\left|\hat{C}_{(n)}^{-1} X_{(n)}^{t} \hat{\Omega}_{n}^{-1} \vec{U}_{x}-\tilde{C}_{(n)}^{-1} X_{(n)}^{t} \Omega_{n}^{-1} \vec{U}_{x}\right|\right\} \\
\Phi_{2, n} & =\sup _{x \in A}\left\{H_{(n)}\left|\hat{C}_{(n)}^{-1} X_{(n)}^{t} \hat{\Omega}_{n}^{-1} \vec{R}_{(n)}-\tilde{C}_{(n)}^{-1} X_{(n)}^{t} \Omega_{n}^{-1} \vec{R}_{(n)}\right|\right\} \\
\Phi_{3, n} & =\sup _{x \in A}\left\{H_{(n)}\left|\hat{C}_{(n)}^{-1} X_{(n)}^{t} \hat{\Omega}_{n}^{-1} \vec{\varepsilon}_{(n)}-\tilde{C}_{(n)}^{-1} X_{(n)}^{t} \Omega_{n}^{-1} \vec{\varepsilon}_{(n)}\right|\right\}
\end{aligned}
$$

with $\vec{U}_{x}$ denoting the vector $\left(\left(x_{1, n}-x\right)^{p+1}, \ldots,\left(x_{n, n}-x\right)^{p+1}\right)^{t}$.
The three terms on the right hand-side of (4.25) are studied next.
Let $X_{(n)}^{t} \hat{\Omega}_{n}^{-1} \vec{U}_{x}$ and $X_{(n)}^{t} \Omega_{n}^{-1} \vec{U}_{x}$ be denoted by $\hat{C}_{u, n}$ and $\tilde{C}_{u, n}$, respectively. From assumption A. $4^{\prime}$ follows that

$$
\begin{gathered}
\Phi_{1, n} \leq C_{M} H_{(n)} \sup _{x \in A}\left|\hat{C}_{(n)}^{-1} \hat{C}_{u, n}-\tilde{C}_{(n)}^{-1} \tilde{C}_{u, n}\right| \\
\leq C_{M} H_{(n)} \sup _{x \in A}\left|\hat{C}_{(n)}^{-1}\left(\hat{C}_{u, n}-\tilde{C}_{u, n}\right)\right|+C_{M} H_{(n)} \sup _{x \in A}\left|\left(\hat{C}_{(n)}^{-1}-\tilde{C}_{(n)}^{-1}\right) \tilde{C}_{u, n}\right|=\Phi_{1,1, n}+\Phi_{1,2, n},
\end{gathered}
$$

where $C_{M}$ is a positive real number.
Proposition 4 together with the almost sure convergence of the estimator $\hat{\rho}_{n}$ (Proposition 3.4 of (1)) lead to

$$
\begin{gather*}
\Phi_{1,1, n}=C_{M} \sup _{x \in A}\left|\left(H_{(n)}^{-1} \hat{C}_{(n)} H_{(n)}^{-1}\right)^{-1} H_{(n)}^{-1}\left(\hat{C}_{u, n}-\tilde{C}_{u, n}\right)\right| \\
=C_{M} \sup _{x \in A}\left(\left(\left(1-\hat{\rho}_{n}\right)^{2} f(x) S+o(1)\right)^{-1}\left((1-\rho)^{2} f(x) \vec{\mu}+o(1)\right) h_{n}^{p+1}\right) o(1)=o\left(h_{n}^{p+1}\right) . \tag{4.26}
\end{gather*}
$$

On the other hand, it can be written that

$$
\begin{aligned}
\Phi_{1,2, n}= & C_{M} \sup _{x \in A} \mid\left[\left(H_{(n)}^{-1} X_{(n)}^{t}\left(\hat{\Omega}_{n}^{-1}-\Omega_{n}^{-1}\right) X_{(n)} H_{(n)}^{-1}+H_{(n)}^{-1} X_{(n)}^{t} \Omega_{n}^{-1} X_{(n)} H_{(n)}^{-1}\right)^{-1}\right. \\
& \left.-\left(H_{(n)}^{-1} X_{(n)}^{t} \Omega_{n}^{-1} X_{(n)} H_{(n)}^{-1}\right)^{-1}\right] H_{(n)}^{-1} X_{(n)}^{t} \Omega_{n}^{-1} \vec{U}_{x} \mid
\end{aligned}
$$

Then, Proposition 4 and Lemma 1 of (1) allow us to deduce that $\Phi_{1,2, n} \leq o\left(h_{n}^{p+1}\right)$, which jointly with (4.26) lead to $\Phi_{1, n} \leq o\left(h_{n}^{p+1}\right)$.

Taking into account the expression of $\vec{R}_{(n)}$ given in (2.2) and using the same arguments employed previously, it is directly deduced that $\Phi_{2, n} \leq o\left(h_{n}^{p+1}\right)$.

Finally, the strong consistency of $\Phi_{3, n}$ is established as follows:

$$
\begin{gathered}
\Phi_{3, n} \leq \sup _{x \in A}\left(H_{(n)}\left|\hat{C}_{(n)}^{-1} X_{(n)}^{t}\left(\hat{\Omega}_{n}^{-1}-\Omega_{n}^{-1}\right) \vec{\varepsilon}_{(n)}\right|\right)+\sup _{x \in A} H_{(n)}\left(\left|\left(\hat{C}_{(n)}^{-1}-\tilde{C}_{(n)}^{-1}\right) X_{(n)}^{t} \Omega_{n}^{-1} \vec{\varepsilon}_{(n)}\right|\right) \\
\leq \sup _{x \in A}\left(\left|H_{(n)} \hat{C}_{(n)}^{-1} H_{(n)}\right|\left|H_{(n)}^{-1} X_{(n)}^{t}\left(\hat{\Omega}_{n}^{-1}-\Omega_{n}^{-1}\right) \vec{\varepsilon}_{(n)}\right|\right) \\
+\sup _{x \in A}\left(\left|H_{(n)}\left(\hat{C}_{(n)}^{-1}-\tilde{C}_{(n)}^{-1}\right) H_{(n)}\right|\left|H_{(n)}^{-1} X_{(n)}^{t} \Omega_{n}^{-1} \vec{\varepsilon}_{(n)}\right|\right)=\Phi_{3,1, n}+\Phi_{3,2, n} .
\end{gathered}
$$

Now, convergence of both $\Phi_{3,1, n}$ and $\Phi_{3,2, n}$ are derived by using Propositions 4 and 6 , the strong convergence of $\hat{\rho}_{n}$ and similar arguments to those employed to establish the consistency of $\Phi_{1,1, n}$ and $\Phi_{1,2, n}$. In particular, it is concluded that $\Phi_{3, n} \leq o\left(\frac{\ln n}{n h_{n}}\right)^{1 / 2}$ almost sure and the proof of (3.10) is stated.

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