Southern Illinois University Carbondale **OpenSIUC**

Miscellaneous (presentations, translations, interviews, etc)

Department of Mathematics

12-1997

The Stable Manifold Theorem for SDE's (Stochastic Analysis Seminar, MSRI)

Salah-Eldin A. Mohammed Southern Illinois University Carbondale, salah@sfde.math.siu.edu

Follow this and additional works at: http://opensiuc.lib.siu.edu/math misc



Part of the Mathematics Commons

Stochastic Analysis Seminar; December 3-5, 1997; Mathematical Sciences Research Institute; Berkeley, California

Recommended Citation

Mohammed, Salah-Eldin A., "The Stable Manifold Theorem for SDE's (Stochastic Analysis Seminar, MSRI)" (1997). Miscellaneous (presentations, translations, interviews, etc). Paper 27.

http://opensiuc.lib.siu.edu/math misc/27

This Article is brought to you for free and open access by the Department of Mathematics at OpenSIUC. It has been accepted for inclusion in Miscellaneous (presentations, translations, interviews, etc) by an authorized administrator of OpenSIUC. For more information, please contact opensiuc@lib.siu.edu.

THE STABLE MANIFOLD THEOREM FOR SDE'S

MSRI, Berkeley: December 3 & 5, 1997

Salah-Eldin A. Mohammed

Southern Illinois University
Carbondale, IL 62901–4408 USA

and

MSRI, Berkeley

Web site: http://salah.math.siu.edu

Outline

- Formulate a Local Stable Manifold Theorem for stochastic differential equations (SDE's).
- Theorem holds for Stratonovich and Itô SDE's driven by spatial Kunita-type semimartingales with stationary ergodic increments.
- Start with the existence of a stochastic flow for SDE.
- Concept of a hyperbolic stationary trajectory. The stationary trajectory is a solution of the forward /backward anticipating SDE for all time (Stratonovich case).
- Existence of a stationary random family of asymptotically invariant stable and unstable manifolds within a stationary neighborhood of the hyperbolic stationary solution.
- The stable and unstable manifolds are dynamically characterized using forward and backward solutions of anticipating versions of the (Stratonovich) SDE.
- Proof based on Ruelle-Oseledec (non-linear) multiplicative ergodic theory and anticipating stochastic calculus.

Formulation of The Theorem

Stratonovich SDE

$$dx(t) = h(x(t)) dt + \sum_{i=1}^{m} g_i(x(t)) \circ dW_i(t),$$
 (I)

on \mathbf{R}^d driven by *m*-dimensional Brownian motion $W:=(W_1,\cdots,W_m).$

 $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \in \mathbf{R}}, P) := \text{canonical filtered Wiener space.}$

 $\Omega := \text{space of all continuous paths } \omega : \mathbf{R} \to \mathbf{R}^m, \, \omega(0) = 0,$ in Euclidean space \mathbf{R}^m , with compact open topology;

 $\mathcal{F} := \text{Borel } \sigma\text{-field of } \Omega;$

 $\mathcal{F}_t := \text{sub-}\sigma\text{-field of }\mathcal{F} \text{ generated by the evaluations}$ $\omega \to \omega(u), \ u \le t, \quad t \in \mathbf{R}.$

P :=Wiener measure on Ω .

 $h, g_i : \mathbf{R}^d \to \mathbf{R}^d, 1 \le i \le m$, vector fields on \mathbf{R}^d . For some $k \ge 1, \delta \in (0,1)$, h is $C_b^{k,\delta}$, viz. h has all derivatives $D^j h, 1 \le j \le k$, continuous and globally bounded, $D^k h$ Hölder continuous with exponent δ .

 g_i , $1 \le i \le m$, globally bounded and in $C_b^{k+1,\delta}$.

 $\theta: \mathbf{R} \times \Omega \to \Omega$ is the (ergodic) Brownian shift

$$\theta(t,\omega)(s) := \omega(t+s) - \omega(t), \quad t,s \in \mathbf{R}, \, \omega \in \Omega.$$

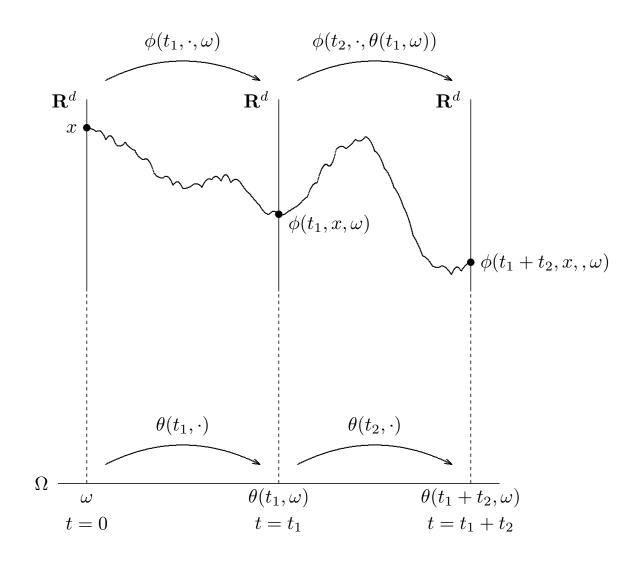
Let $\phi: \mathbf{R} \times \mathbf{R}^d \times \Omega \to \mathbf{R}^d$ be the stochastic flow generated by (I) $(\phi(t,\cdot,\omega) = [\phi(-t,\cdot,\theta(t,\omega))]^{-1}, t < 0)$. Then ϕ is a perfect cocycle:

$$\phi(t+s,\cdot,\omega) = \phi(t,\cdot,\theta(s,\omega)) \circ \phi(s,\cdot,\omega),$$

for all $s, t \in \mathbf{R}$ and all $\omega \in \Omega$ ([I-W], [A-S], [A]).

Figure illustrates the cocycle property. Vertical solid lines represent random fibers consisting of copies of \mathbf{R}^d . (ϕ, θ) is a "random vector-bundle morphism" over the "base" probability space Ω .

The Cocycle



Definition

The SDE (I) has a stationary trajectory if there exists an \mathcal{F} -measurable random variable $Y: \Omega \to \mathbf{R}^d$ such that

$$\phi(t, Y(\omega), \omega) = Y(\theta(t, \omega)) \tag{1}$$

for all $t \in \mathbf{R}$ and every $\omega \in \Omega$. Denote stationary trajectory (1) by $\phi(t, Y) = Y((\theta(t)))$.

If (1) holds on a sure event Ω_t that may depend on t, then there are "perfect" versions of the stationary random variable Y and of the flow ϕ such that (1) and the cocycle property hold for all $\omega \in \Omega$ ([Sc]).

Let $\phi(t,Y)$ be a stationary solution of (I). Cocycle property of ϕ implies that the linearization

$$(D_2\phi(t,Y(\omega),\omega),\theta(t,\omega))$$

along the stationary solution is also a $d \times d$ -matrix-valued cocycle. Using Kolmogorov's theorem, the random variables

$$\sup_{x \in \mathbf{R}^d} \frac{|D_2 \phi(t, x)|}{(1 + |x|^{\gamma})}, \ \gamma > 0,$$

have moments of all orders. If $E \log^+ |Y| < \infty$, then $E \log^+ |D_2\phi(1,Y)| < \infty$. Apply Oseledec's Theorem to get a non-random finite Lyapunov spectrum:

$$\lim_{n\to\infty} \frac{1}{n} \log |D_2\phi(n, Y(\omega), \omega)(v(\omega))|, \quad v \in L^0(\Omega, \mathbf{R}^d).$$

Spectrum takes finitely many values $\{\lambda_i\}_{i=1}^p$ with non-random multiplicities q_i , $1 \le i \le p$, and $\sum_{i=1}^p q_i = d$ ([Ru.1], Theorem I.6).

Definition

Stationary trajectory $\phi(t,Y)$ of (I) is hyperbolic if $E \log^+ |Y(\cdot)| < \infty$, and if the linearized cocycle $(D_2\phi(n,Y(\omega),\omega),\theta(n,\omega))$ has a non-vanishing Lyapunov spectrum

$$\{\lambda_p < \dots < \lambda_{i_0+1} < \lambda_{i_0} < 0 < \lambda_{i_0-1} < \dots < \lambda_2 < \lambda_1\}$$

i.e. $\lambda_i \neq 0$ for all $1 \leq i \leq p$.

Define $\lambda_{i_0} := \max\{\lambda_i : \lambda_i < 0\}$ if at least one $\lambda_i < 0$. If all $\lambda_i > 0$, set $\lambda_{i_0} = -\infty$. (This implies that λ_{i_0-1} is the smallest positive Lyapunov exponent of the linearized flow, if at least one $\lambda_i > 0$; in case all λ_i are negative, set $\lambda_{i_0-1} = \infty$.) Let $\rho \in \mathbf{R}^+$, $x \in \mathbf{R}^d$.

 $B(x,\rho) := \text{open ball in } \mathbf{R}^d, \text{ center } x \text{ and radius } \rho;$

 $\bar{B}(x,\rho) :=$ corresponding closed ball;

 $C(\mathbf{R}^d)$:= the class of all non-empty compact subsets of \mathbf{R}^d with Hausdorff metric d^* :

 $d^*(A_1, A_2) := \sup\{d(x, A_1) : x \in A_2\} \vee \sup\{d(y, A_2) : y \in A_1\}$ where $A_1, A_2 \in \mathcal{C}(\mathbf{R}^d)$;

 $d(x, A_i) := \inf\{|x - y| : y \in A_i\}, x \in \mathbf{R}^d, i = 1, 2;$

 $\mathcal{B}(\mathcal{C}(\mathbf{R}^d)) := \text{Borel } \sigma\text{-algebra on } \mathcal{C}(\mathbf{R}^d) \text{ with respect to the metric } d^*.$

Theorem 1 (The Stable Manifold Theorem) (M.+ Scheutzow, 1997)

Assume that the coefficients of SDE (I) satisfy the given hypotheses. Suppose $\phi(t,Y)$ is a hyperbolic stationary trajectory of (I) with $E\log^+|Y| < \infty$.

Fix $\epsilon_1 \in (0, -\lambda_{i_0})$ and $\epsilon_2 \in (0, \lambda_{i_0-1})$. Then there exist

- (i) a sure event $\Omega^* \in \mathcal{F}$ with $\theta(t, \cdot)(\Omega^*) = \Omega^*$ for all $t \in \mathbf{R}$,
- (ii) \mathcal{F} -measurable random variables $\rho_i, \beta_i : \Omega^* \to [0, \infty), \beta_i > \rho_i > 0$, i = 1, 2, such that for each $\omega \in \Omega^*$, the following is true:

There are $C^{k,\epsilon}$ ($\epsilon \in (0,\delta)$) submanifolds $\tilde{\mathcal{S}}(\omega)$, $\tilde{\mathcal{U}}(\omega)$ of $\bar{B}(Y(\omega), \rho_1(\omega))$ and $\bar{B}(Y(\omega), \rho_2(\omega))$ (resp.) with the following properties:

(a) $\tilde{S}(\omega)$ is the set of all $x \in \bar{B}(Y(\omega), \rho_1(\omega))$ such that

$$|\phi(n, x, \omega) - Y(\theta(n, \omega))| \le \beta_1(\omega) e^{(\lambda_{i_0} + \epsilon_1)n}$$

for all integers $n \geq 0$. Furthermore,

$$\limsup_{t \to \infty} \frac{1}{t} \log |\phi(t, x, \omega) - Y(\theta(t, \omega))| \le \lambda_{i_0}$$
 (2)

for all $x \in \tilde{\mathcal{S}}(\omega)$. Each stable subspace $\mathcal{S}(\omega)$ of the linearized flow $D_2\phi$ is tangent at $Y(\omega)$ to the submanifold $\tilde{\mathcal{S}}(\omega)$, viz. $T_{Y(\omega)}\tilde{\mathcal{S}}(\omega) = \mathcal{S}(\omega)$. In particular, dim $\tilde{\mathcal{S}}(\omega) = \dim \mathcal{S}(\omega)$ and is non-random.

(b)
$$\limsup_{t \to \infty} \frac{1}{t} \log \left[\sup_{\substack{x_1 \neq x_2 \\ x_1, x_2 \in \tilde{\mathcal{S}}(\omega)}} \left\{ \frac{|\phi(t, x_1, \omega) - \phi(t, x_2, \omega)|}{|x_1 - x_2|} \right\} \right] \leq \lambda_{i_0}.$$

(c) (Cocycle-invariance of the stable manifolds):

There exists $\tau_1(\omega) \geq 0$ such that

$$\phi(t,\cdot,\omega)(\tilde{\mathcal{S}}(\omega)) \subseteq \tilde{\mathcal{S}}(\theta(t,\omega)), \quad t \ge \tau_1(\omega). \tag{3}$$

Also

$$D_2\phi(t, Y(\omega), \omega)(\mathcal{S}(\omega)) = \mathcal{S}(\theta(t, \omega)), \quad t \ge 0.$$
 (4)

(d) $\tilde{\mathcal{U}}(\omega)$ is the set of all $x \in \bar{B}(Y(\omega), \rho_2(\omega))$ with the property that

$$|\phi(-n, x, \omega) - Y(\theta(-n, \omega))| \le \beta_2(\omega) e^{(-\lambda_{i_0-1} + \epsilon_2)n}$$
 (5)

for all integers $n \geq 0$. Also

$$\limsup_{t \to \infty} \frac{1}{t} \log |\phi(-t, x, \omega) - Y(\theta(-t, \omega))| \le -\lambda_{i_0 - 1}.$$
 (6)

for all $x \in \tilde{\mathcal{U}}(\omega)$. Furthermore, the unstable subspace $\mathcal{U}(\omega)$ of $D_2\phi$ is the tangent space to $\tilde{\mathcal{U}}(\omega)$ at $Y(\omega)$, viz. $T_{Y(\omega)}\tilde{\mathcal{U}}(\omega) = \mathcal{U}(\omega)$. In particular, dim $\tilde{\mathcal{U}}(\omega) = \dim \mathcal{U}(\omega)$ and is non-random.

(e)
$$\limsup_{t \to \infty} \frac{1}{t} \log \left[\sup_{\substack{x_1 \neq x_2 \\ x_1, x_2 \in \tilde{\mathcal{U}}(\omega)}} \left\{ \frac{|\phi(-t, x_1, \omega) - \phi(-t, x_2, \omega)|}{|x_1 - x_2|} \right\} \right] \leq -\lambda_{i_0 - 1}.$$

(f) (Cocycle-invariance of the unstable manifolds):

There exists $\tau_2(\omega) \geq 0$ such that

$$\phi(-t,\cdot,\omega)(\tilde{\mathcal{U}}(\omega)) \subseteq \tilde{\mathcal{U}}(\theta(-t,\omega)), \quad t \ge \tau_2(\omega). \tag{7}$$

Also

$$D_2\phi(-t, Y(\omega), \omega)(\mathcal{U}(\omega)) = \mathcal{U}(\theta(-t, \omega)), \quad t \ge 0.$$
 (8)

(g) The submanifolds $\tilde{\mathcal{U}}(\omega)$ and $\tilde{\mathcal{S}}(\omega)$ are transversal, viz.

$$\mathbf{R}^d = T_{Y(\omega)} \tilde{\mathcal{U}}(\omega) \oplus T_{Y(\omega)} \tilde{\mathcal{S}}(\omega). \tag{9}$$

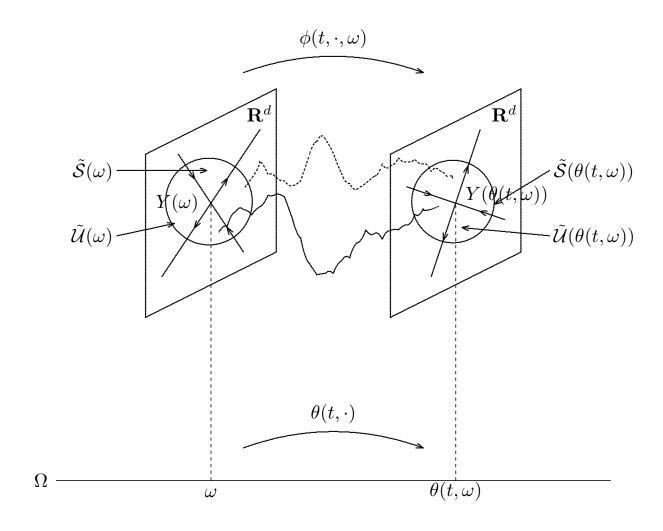
(h) The mappings

$$\Omega \to \mathcal{C}(\mathbf{R}^d), \qquad \Omega \to \mathcal{C}(\mathbf{R}^d),$$

$$\omega \mapsto \tilde{\mathcal{S}}(\omega) \qquad \omega \mapsto \tilde{\mathcal{U}}(\omega)$$

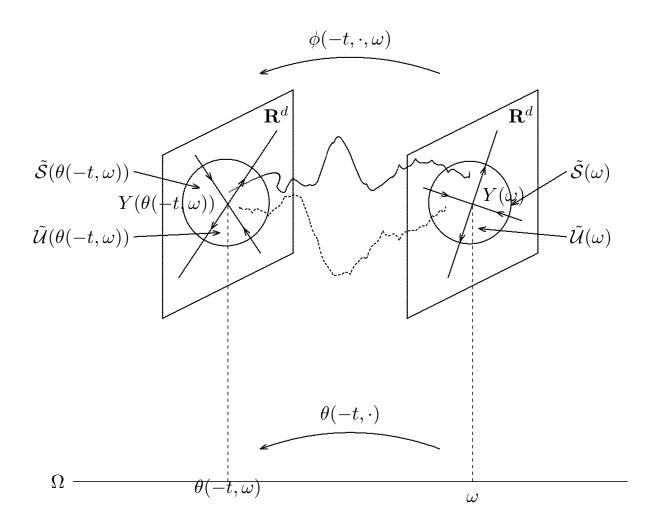
are $(\mathcal{F}, \mathcal{B}(\mathcal{C}(\mathbf{R}^d)))$ -measurable.

Assume, further, that $h, g_i, 1 \leq i \leq m$, are C_b^{∞} Then the local stable and unstable manifolds $\tilde{\mathcal{S}}(\omega), \tilde{\mathcal{U}}(\omega)$ are C^{∞} .



 $t > \tau_1(\omega)$

A picture is worth a 1000 words!



$$t > \tau_2(\omega)$$

Remarks

(i) In Stratonovich SDE (I), replace global boundedness on $g'_i s$ by requiring

$$\mathbf{R}^d \ni x \mapsto \sum_{l=1}^m \frac{\partial g_l^i(x)}{\partial x_j} g_l^j(x) \in \mathbf{R}, \ 1 \le i, j \le d$$

to be in $C_b^{k,\delta}$.

- (ii) Conjecture: The the global boundedness condition is not needed. This conjecture is not hard to check if the vector fields g_i , $1 \le i \le m$ are C_b^{∞} and generate a finite-dimensional solvable Lie algebra. See [Ku], Theorem 4.9.10, p. 212.
- (iii) Theorem holds for the Itô SDE

$$dx(t) = h(x(t)) dt + \sum_{i=1}^{m} g_i(x(t)) dW_i(t),$$
 (II)

with $h, g_i : \mathbf{R}^d \to \mathbf{R}^d, 1 \le i \le m$, in $C_b^{k,\delta}$.

(iv) Replace the stationary random variable Y by its invariant distribution μ , then formulate result with respect to the product measure $\mu \otimes P$ and the underlying skew-product flow. This would give stable and unstable manifolds that are defined a.e. $(\mu \otimes P)$; cf. [C] for

the globally asymptotically stable case on a compact manifold.

(v) Replace the SDE (I) with Kunita-type SDE

$$d\phi(t) = \overset{\circ}{F}(\circ dt, \phi(t)), \quad t > s$$
$$\phi(s) = x$$

where $\overset{\circ}{F}$ is a spatial semimartingale helix (i.e. with stationary ergodic increments) and with local characteristics of class $(B_{ub}^{k+1,\delta},B_{ub}^{k,\delta})$ and the function

$$[0,\infty) \times \mathbf{R}^d \ni (t,x) \mapsto \sum_{j=1}^d \frac{\partial a^{\cdot,j}(t,x,y)}{\partial x_j} \bigg|_{y=x} \in \mathbf{R}^d$$

belongs to $B_{ub}^{k,\delta}$. In the Itô case, last condition is not needed.

$$\begin{split} \overset{\circ}{F}(t,x) &= V(t,x) + M(t,x) \\ a^{i,j}(t,x,y) &:= \frac{d}{dt} < M^i(\cdot,x), M^j(\cdot,y) > (t) \\ b^i(t,x) &:= \frac{d}{dt} V^i(t,x), \quad x,y \in \mathbf{R}^d, 1 \leq i,j \leq d \end{split}$$

Sketch of Proof

Linearization and Substitution

Assume regularity conditions on the coefficients h, g_i . By the Substitution Rule, $\phi(t, Y(\omega), \omega)$ is a stationary solution of the anticipating Stratonovich SDE

$$d\phi(t,Y) = h(\phi(t,Y)) dt + \sum_{i=1}^{m} g_i(\phi(t,Y)) \circ dW_i(t), \quad t > 0$$

$$\phi(0,Y) = Y.$$
(II)

([N-P]).

Linearize the SDE (I) along the stationary trajectory. By substitution, match the solution of the linearized equation with the linearized cocycle $D_2\phi(t,Y(\omega),\omega)$. Hence $D_2\phi(t,Y(\omega),\omega)$, $t \geq 0$, solves the SDE:

$$dD_{2}\phi(t,Y) = Dh(\phi(t,Y))D_{2}\phi(t,Y) dt + \sum_{i=1}^{m} Dg_{i}(\phi(t,Y))D_{2}\phi(t,Y) \circ dW_{i}(t), \quad t > 0$$

$$D_{2}\phi(0,Y) = I.$$
(III)

 D_2, D denotes spatial (Fréchet) derivatives.

Similarly, the backward trajectories

$$\phi(t,Y), D_2\phi(t,Y), t<0,$$

solve the corresponding backward Stratonovich SDE's:

$$d\phi(t,Y) = -h(\phi(t,Y)) dt - \sum_{i=1}^{m} g_i(\phi(t,Y)) \circ \hat{d}W_i(t), \quad t < 0$$

$$\phi(0,Y) = Y.$$

$$dD_2\phi(t,Y) = -Dh(\phi(t,Y))D_2\phi(t,Y) dt$$

$$-\sum_{i=1}^{m} Dg_i(\phi(t,Y))D_2\phi(t,Y) \circ \hat{d}W_i(t), \quad t < 0$$

$$D_2\phi(0,Y) = I.$$
(III-)

Above SDE's (II)-(III)⁻ give dynamic characterizations of the stable and unstable manifolds.

The following lemma is used to construct the shift-invariant sure event appearing in the statement of the local stable manifold theorem. Gives "perfect versions" of the ergodic theorem and Kingman's subadditive ergodic theorem.

Lemma 1

(i) Let $h: \Omega \to \mathbf{R}^+$ be \mathcal{F} -measurable and such that

$$\int_{\Omega} \sup_{0 \le u \le 1} h(\theta(u, \omega)) dP(\omega) < \infty.$$

Then there is a sure event $\Omega_1 \in \mathcal{F}$ such that $\theta(t,\cdot)(\Omega_1) = \Omega_1$ for all $t \in \mathbf{R}$, and

$$\lim_{t \to \infty} \frac{1}{t} h(\theta(t, \omega)) = 0$$

for all $\omega \in \Omega_1$.

- (ii) Suppose $f: \mathbf{R}^+ \times \Omega \to \mathbf{R} \cup \{-\infty\}$ is a measurable process on (Ω, \mathcal{F}, P) satisfying the following conditions
- (a) $E \sup_{0 \le u \le 1} f^+(u) < \infty$, $E \sup_{0 \le u \le 1} f^+(1 u, \theta(u)) < \infty$
- (b) $f(t_1 + t_2, \omega) \leq f(t_1, \omega) + f(t_2, \theta(t_1, \omega))$ for all $t_1, t_2 \geq 0$ and all $\omega \in \Omega$.

Then there is sure event $\Omega_2 \in \mathcal{F}$ such that $\theta(t,\cdot)(\Omega_2) = \Omega_2$ for all $t \in \mathbf{R}$, and a fixed number $f^* \in \mathbf{R} \cup \{-\infty\}$ such that

$$\lim_{t \to \infty} \frac{1}{t} f(t, \omega) = f^*$$

for all $\omega \in \Omega_2$.

Proof

[Mo.1], Lemma 7. \square

Theorem 2 ([O], 1968)

Let (Ω, \mathcal{F}, P) be a probability space and $\theta : \mathbf{R}^+ \times \Omega \to \Omega$ a measurable family of ergodic P-preserving transformations. Let $T : \mathbf{R}^+ \times \Omega \to L(\mathbf{R}^d)$ be measurable, such that (T, θ) is an $L(\mathbf{R}^d)$ valued cocycle. Suppose that

$$E \sup_{0 \le t \le 1} \log^+ ||T(t, \cdot)|| < \infty, \quad E \sup_{0 \le t \le 1} \log^+ ||T(1 - t, \theta(t, \cdot))|| < \infty.$$

Then there is a set $\Omega_0 \in \mathcal{F}$ of full P-measure such that $\theta(t,\cdot)(\Omega_0) \subseteq \Omega_0$ for all $t \in \mathbf{R}^+$, and for each $\omega \in \Omega_0$, the limit

$$\lim_{n\to\infty} [T(t,\omega)^* \circ T(t,\omega)]^{1/(2t)} := \Lambda(\omega)$$

exists in the uniform operator norm. Each $\Lambda(\omega)$ has a discrete non-random spectrum

$$e^{\lambda_1} > e^{\lambda_2} > e^{\lambda_3} > \dots > e^{\lambda_p}$$

where the λ_i 's are distinct. Each e^{λ_i} has a fixed non-random multiplicity m_i and eigen-space $F_i(\omega)$, with $m_i := \dim F_i(\omega)$. Define

$$E_1(\omega) := \mathbf{R}^d, \quad E_i(\omega) := \left[\bigoplus_{j=1}^{i-1} F_j(\omega) \right]^{\perp}, \ 1 < i \le p.$$

Then

$$E_p(\omega) \subset \cdots \subset E_{i+1}(\omega) \subset E_i(\omega) \cdots \subset E_2(\omega) \subset E_1(\omega) = \mathbf{R}^d$$

$$\lim_{t \to \infty} \frac{1}{t} \log ||T(t, \omega)x|| = \lambda_i(\omega), \quad \text{if} \quad x \in E_i(\omega) \setminus E_{i+1}(\omega),$$

and

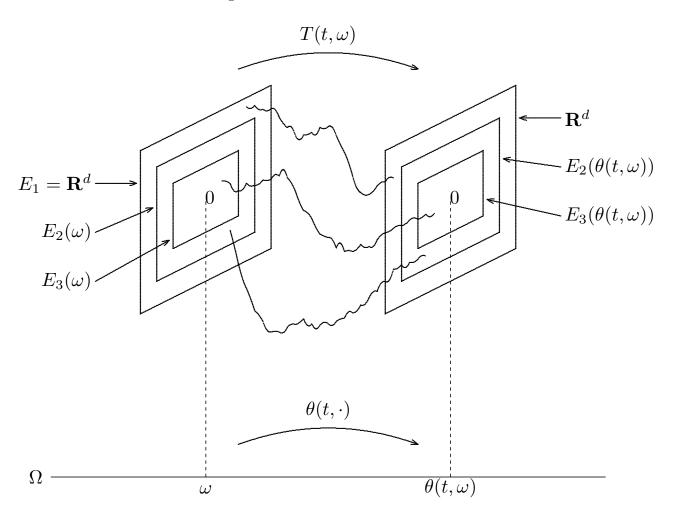
$$T(t,\omega)(E_i(\omega)) \subseteq E_i(\theta(t,\omega))$$

for all $t \ge 0$, $1 \le i \le p$.

Proof.

Based on the discrete version of Oseledec's multiplicative ergodic theorem and Lemma 1. ([Ru.1], I.H.E.S Publications, 1979, pp. 303-304; cf. Furstenberg & Kesten (1960), [Mo.1]), "perfect" infinite-dimensional version and application to SFDE's.

$Spectral\ Theorem$

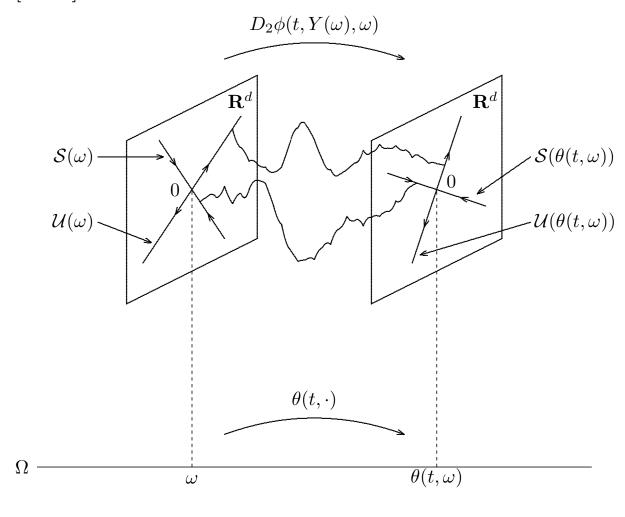


Apply Theorem 2 with $T(t,\omega) := D_2\phi(t,Y(\omega),\omega)$. Then linearized cocycle has random invariant stable and unstable subspaces $\{S(\omega),U(\omega):\omega\in\Omega\}$:

$$D_2\phi(t, Y(\omega), \omega)(\mathcal{S}(\omega)) = \mathcal{S}(\theta(t, \omega)),$$

$$D_2\phi(-t, Y(\omega), \omega)(\mathcal{U}(\omega)) = \mathcal{U}(\theta(-t, \omega)), \quad t \ge 0.$$

[Mo.1].



Estimates on the non-linear cocycle

Theorem 3 (M. + Scheutzow [M-S.2])

There exists a jointly measurable modification of the trajectory random field of (I), denoted by $\{\phi_{s,t}(x) : -\infty < s, t < \infty, x \in \mathbf{R}^d\}$, with the following properties:

Define $\phi: \mathbf{R} \times \mathbf{R}^d \times \Omega \to \mathbf{R}^d$ by

$$\phi(t, x, \omega) := \phi_{0,t}(x, \omega), \quad x \in \mathbf{R}^d, \omega \in \Omega, t \in \mathbf{R}.$$

Then the following is true for all $\omega \in \Omega$:

- (i) For each $x \in \mathbf{R}^d$, and $s, t \in \mathbf{R}$, $\phi_{s,t}(x,\omega) = \phi(t-s,x,\theta(s,\omega))$.
- (ii) (ϕ, θ) is a perfect cocycle:

$$\phi(t+s,\cdot,\omega) = \phi(t,\cdot,\theta(s,\omega)) \circ \phi(s,\cdot,\omega),$$

for all $s, t \in \mathbf{R}$.

- (iii) For each $t \in \mathbf{R}$, $\phi(t, \cdot, \omega) : \mathbf{R}^d \to \mathbf{R}^d$ is a C^k diffeomorphism.
- (iv) The mapping $\mathbf{R}^2 \ni (s,t) \mapsto \phi_{s,t}(\cdot,\omega) \in \operatorname{Diff}^k(\mathbf{R}^d)$ is continuous, where $\operatorname{Diff}^k(\mathbf{R}^d)$ denotes the group of all C^k diffeomorphisms of \mathbf{R}^d , given the C^k -topology.
- (v) For every $\epsilon \in (0, \delta), \gamma, \rho, T > 0$, and $1 \le |\alpha| \le k$, the quantities

$$\sup_{\substack{0 \le s, t \le T, \\ x \in \mathbf{R}^d}} \frac{|\phi_{s,t}(x,\omega)|}{[1+|x|(\log^+|x|)^{\gamma}]}, \quad \sup_{\substack{0 \le s, t \le T, \\ x \in \mathbf{R}^d}} \frac{|D_x^{\alpha}\phi_{s,t}(x,\omega)|}{(1+|x|^{\gamma})},$$

$$\sup_{x \in \mathbf{R}^d} \sup_{\substack{0 \le s, t \le T, \\ 0 < |x'-x| < \rho}} \frac{|D_x^{\alpha}\phi_{s,t}(x,\omega) - D_x^{\alpha}\phi_{s,t}(x',\omega)|}{|x-x'|^{\epsilon}(1+|x|)^{\gamma}},$$

are finite. The random variables defined by the above expressions have p-th moments for all $p \ge 1$.

Proof

Cocycle property (ii): approximate the flow using helix mollifiers of Brownian motion:

$$W^{k}(t) := k \int_{t-1/k}^{t} W(s) ds - k \int_{-1/k}^{0} W(s) ds.$$

$$W^{k}(t_{2}, \theta(t_{1}, \omega)) = W^{k}(t_{1} + t_{2}, \omega) - W^{k}(t_{1}, \omega), \quad k \ge 1$$

([I-W], cf. [Mo.1], [Mo.2] for linear infinite-dimensional case).

(iii) and (iv) are well-known to hold for a.a. $\omega \in \Omega$ ([Ku], Theorem 4.6.5).

A perfect version of $\phi_{s,t}$ satisfying (i)-(iv) for all $\omega \in \Omega$, is obtained in [A-S] by perfection techniques and the diffeomorphism theorem for flows ([Ku], Theorem 4.6.5; cf. also [M-S.1]).

By known estimates (or GRR) ([M-S.2]), the random variables

$$X_{1} := \sup_{\substack{0 \le s \le t \le T, \\ x \in \mathbf{R}^{d}}} \frac{|\phi_{s,t}(x,\cdot)|}{[1 + |x|(\log^{+}|x|)^{\gamma}]},$$

$$X_{2} := \sup_{\substack{0 \le s \le t \le T, \\ x \in \mathbf{R}^{d}}} \frac{|x|}{[1 + |\phi_{s,t}(x,\cdot)|(\log^{+}|x|)^{\gamma}]}$$

have p-th moments for all $p \ge 1$. It is sufficient to show that the random variable

$$\hat{X}_1 := \sup_{\substack{0 \le s \le t \le T, \\ x \in \mathbf{R}^d}} \frac{|\phi_{t,s}(x,\cdot)|}{[1 + |x|(\log^+|x|)^\gamma]}$$

has p-th moments for all $p \ge 1$. Assume (without loss of generality) that $\gamma \in (0,1)$. From the definition of X_2 ,

$$|y| \le X_2[1 + |\phi_{s,t}(y,\cdot)|(\log^+ |y|)^{\gamma}]$$

for all $0 \le s \le t \le T, y \in \mathbf{R}^d$. Use the substitution

$$y = \phi_{t,s}(x,\omega) = \phi_{s,t}^{-1}(x,\omega), \ \phi_{s,t}(y,\omega) = x, 0 \le s \le t \le T, \omega \in \Omega, x \in \mathbf{R}^d,$$

to rewrite above inequality as

$$|y| \le X_2[1 + |x|(\log^+ |y|)^{\gamma}].$$

Solve above inequality (by taking \log^+) for $\log^+|y|$. Therefore, there exists a non-random constant $K_1 := K_1(\gamma) > 0$ such that

$$|y| \le K_1 X_2 [1 + |x| \{1 + (\log^+ |X_2|)^{\gamma} + (\log^+ |x|)^{\gamma} \}].$$

Since X_2 has moments of all orders, the above inequality implies that \hat{X}_1 also has p-th moments for all $p \ge 1$.

Complete proof by [Ku], [M-S.2] and GRR.

 $\|\cdot\|_{k,\epsilon} := C^{k,\epsilon}$ -norm on $C^{k,\epsilon}$ mappings $\bar{B}(0,\rho) \to \mathbf{R}^d$.

Lemma 2

Assume that $\log^+|Y(\cdot)|$ is integrable. Then the cocycle ϕ satisfies

$$\int_{\Omega} \log^{+} \sup_{-T \le t_1, t_2 \le T} \|\phi(t_2, Y(\theta(t_1, \omega)) + (\cdot), \theta(t_1, \omega))\|_{k,\epsilon} dP(\omega) < \infty$$
(10)

for any fixed $0 < T, \rho < \infty$ and any $\epsilon \in (0, \delta)$. Furthermore, the linearized flow $(D_2\phi(t, Y(\omega), \omega), \theta(t, \omega)), t \geq 0$, is an $L(\mathbf{R}^d)$ -valued perfect cocycle and

$$\int_{\Omega} \log^{+} \sup_{-T \le t_1, t_2 \le T} \|D_2 \phi(t_2, Y(\theta(t_1, \omega)), \theta(t_1, \omega))\|_{L(\mathbf{R}^d)} dP(\omega) < \infty$$
(11)

for any fixed $0 < T < \infty$. The forward cocycle $(D_2\phi(t,Y(\omega),\omega),\theta(t,\omega),t>0)$ has a non-random finite Lyapunov spectrum $\{\lambda_m < \cdots < \lambda_{i+1} < \lambda_i < \cdots < \lambda_2 < \lambda_1\}$. Each Lyapunov exponent λ_i has a non-random multiplicity q_i , $1 \le i \le m$, and $\sum_{i=1}^m q_i = \sum_{i=1}^m q_i = \sum_{i=$

d. The backward linearized cocycle $(D_2\phi(t,Y(\omega),\omega),\theta(t,\omega),t<0)$, admits a "backward" non-random finite Lyapunov spectrum:

$$\lim_{t \to -\infty} \frac{1}{t} \log |D_2 \phi(t, Y(\omega), \omega)(v(\omega))|, \quad v \in L^0(\Omega, \mathbf{R}^d),$$

taking values in $\{-\lambda_i\}_{i=1}^m$ with non-random multiplicities q_i , $1 \le i \le m$, and $\sum_{i=1}^m q_i = d$.

Proof of Lemma 2

We first prove (11). Start with the perfect cocycle property for (ϕ, θ) :

$$\phi(t_1 + t_2, \cdot, \omega) = \phi(t_2, \cdot, \theta(t_1, \omega)) \circ \phi(t_1, \cdot, \omega)$$
(12)

for all $t_1, t_2 \in \mathbf{R}$ and all $\omega \in \Omega$. Cocycle property for $(D_2\phi(t, Y(\omega), \omega), \theta(t, \omega))$ follows directly by taking Fréchet derivatives at $Y(\omega)$ on both sides of (12); viz.

$$D_{2}\phi(t_{1}+t_{2},Y(\omega),\omega)$$

$$=D_{2}\phi(t_{2},\phi(t_{1},Y(\omega),\omega),\theta(t_{1},\omega))\circ D_{2}\phi(t_{1},Y(\omega),\omega)$$

$$=D_{2}\phi(t_{2},Y(\theta(t_{1},\omega)),\theta(t_{1},\omega))\circ D_{2}\phi(t_{1},Y(\omega),\omega)$$
(13)

for all $\omega \in \Omega_0, t_1, t_2 \in \mathbf{R}$. Existence of a fixed discrete spectrum for $D_2\phi(t,Y)$ follows from [Mo.1] and [M-S.1], using the integrability property (11) and the ergodicity of θ . ((11) follows from (13) and Theorem 3 (v)). But (10) implies (11)! Therefore it is sufficient to prove (10).

In view of (1) and the identity

$$\phi_{t_1,t_1+t_2}(x,\omega) = \phi(t_2, x, \theta(t_1,\omega)), \quad x \in \mathbf{R}^d, t_1, t_2 \in \mathbf{R},$$

(Theorem 3(i)), (10) (for $\epsilon = 0$) will follow from

$$\int_{\Omega} \log^{+} \sup_{\substack{0 \le s, t \le T, \\ |x'| \le \rho}} |D_{x}^{\alpha} \phi_{s,t}(\phi_{0,s}(Y(\omega), \omega) + x', \omega)| dP(\omega) < \infty, \quad 0 \le |\alpha| \le k.$$
(14)

Denote random "constants" by K_i , i = 1, 2, 3, 4. Each $K_i := K_i(\rho, T)$, i = 1, 2, 3, 4, has p-th moments for all $p \ge 1$. The following inequalities follow easily from Theorem 3 (v).

$$\log^{+} \sup_{\substack{s,t \in [0,T], \\ |x'| \leq \rho}} |D_{x}^{\alpha} \phi_{s,t}(\phi_{0,s}(Y(\omega),\omega) + x',\omega)|$$

$$\leq \log^{+} \sup_{s \in [0,T]} \{K_{1}(\omega)[1 + (\rho + |\phi_{0,s}(Y(\omega),\omega)|)^{2}]\}$$

$$\leq \log^{+} K_{2}(\omega) + \log^{+}[1 + 2\rho^{2} + K_{3}(\omega)(1 + |Y(\omega)|^{4})]$$

$$\leq \log^{+} K_{4}(\omega) + \log[1 + 2\rho^{2}] + 4\log^{+}|Y(\omega)| \tag{15}$$

for all $\omega \in \Omega$. (15)+ integrability hypothesis on Y imply (14). \square

The Auxiliary Cocycle

To apply Ruelle's discrete non-linear ergodic theorem ([Ru.1], Theorem 5.1, p. 292), introduce the following auxiliary cocycle $Z: \mathbf{R} \times \mathbf{R}^d \times \Omega \to \mathbf{R}^d$. This a "centering" of the flow ϕ about the stationary solution:

$$Z(t, x, \omega) := \phi(t, x + Y(\omega), \omega) - Y(\theta(t, \omega)) \tag{16}$$

for $t \in \mathbf{R}, x \in \mathbf{R}^d, \omega \in \Omega$.

Lemma 3

 (Z, θ) is a perfect cocycle on \mathbf{R}^d and $Z(t, 0, \omega) = 0$ for all $t \in \mathbf{R}$, and all $\omega \in \Omega$.

Proof of Lemma 3

Let $t_1, t_2 \in \mathbf{R}, \omega \in \Omega, x \in \mathbf{R}^d$.

$$Z(t_{2}, Z(t_{1}, x, \omega), \theta(t_{1}, \omega))$$

$$= \phi(t_{2}, Z(t_{1}, x, \omega) + Y(\theta(t_{1}, \omega)), \theta(t_{1}, \omega)) - Y(\theta(t_{2}, \theta(t_{1}, \omega)))$$

$$= \phi(t_{2}, \phi(t_{1}, x + Y(\omega), \omega), \theta(t_{1}, \omega)) - Y(\theta(t_{2} + t_{1}, \omega))$$

$$= Z(t_{1} + t_{2}, x, \omega), t_{1}, t_{2} \in \mathbf{R}, \omega \in \Omega, x \in \mathbf{R}^{d}.$$

 $Z(t,0,\omega) \equiv 0$ by definition of Z and stationary solution. \square

The proof of the local stable-manifold theorem (Theorem 1) uses a discretization argument that requires the following lemma.

Lemma 4

Suppose that $\log^+ |Y(\cdot)|$ is integrable. Then there is a sure event $\Omega_3 \in \mathcal{F}$ with the following properties:

- (i) $\theta(t,\cdot)(\Omega_3) = \Omega_3$ for all $t \in \mathbf{R}$,
- (ii) For every $\omega \in \Omega_3$ and any $x \in \mathbf{R}^d$, the statement

$$\limsup_{n \to \infty} \frac{1}{n} \log |Z(n, x, \omega)| < 0 \tag{17}$$

implies

$$\limsup_{t \to \infty} \frac{1}{t} \log |Z(t, x, \omega)| = \limsup_{n \to \infty} \frac{1}{n} \log |Z(n, x, \omega)|.$$
 (18)

Proof

The integrability condition (10) of Lemma 2 implies that

$$\int_{\Omega} \log^{+} \sup_{\substack{0 \le t_{1}, t_{2} \le 1, \\ x^{*} \in \bar{B}(0,1)}} \|D_{2}Z(t_{1}, x^{*}, \theta(t_{2}, \omega))\|_{L(\mathbf{R}^{d})} dP(\omega) < \infty.$$
 (19)

Therefore by (the perfect version of) the ergodic theorem (Lemma 1(i)), there is a sure event $\Omega_3 \in \mathcal{F}$ such that $\theta(t,\cdot)(\Omega_3) = \Omega_3$ for all $t \in \mathbf{R}$, and

$$\lim_{t \to \infty} \frac{1}{t} \log^{+} \sup_{\substack{0 \le u \le 1, \\ x^* \in \bar{B}(0,1)}} ||D_2 Z(u, x^*, \theta(t, \omega))||_{L(\mathbf{R}^d)} = 0$$
 (20)

for all $\omega \in \Omega_3$.

Let $\omega \in \Omega_3$ and suppose $x \in \mathbf{R}^d$ satisfies (17). Then (17) implies that there exists a positive integer $N_0(x,\omega)$ such that $Z(n,x,\omega) \in \bar{B}(0,1)$ for all $n \geq N_0$. Let $n \leq t < n+1$, $n \geq N_0$. Then by the cocycle property for (Z,θ) and the Mean Value Theorem:

$$\sup_{n \le t \le n+1} \frac{1}{t} \log |Z(t, x, \omega)|$$

$$\le \frac{1}{n} \log^{+} \sup_{\substack{0 \le u \le 1, \\ x^* \in \overline{B}(0,1)}} ||D_2 Z(u, x^*, \theta(n, \omega))||_{L(\mathbf{R}^d)} + \frac{n}{(n+1)} \frac{1}{n} \log |Z(n, x, \omega)|.$$

Take $\limsup_{n\to\infty}$ in the above relation and use (20) to get

$$\limsup_{t \to \infty} \frac{1}{t} \log |Z(t, x, \omega)| \le \limsup_{n \to \infty} \frac{1}{n} \log |Z(n, x, \omega)|.$$

The inequality

$$\limsup_{n\to\infty}\frac{1}{n}\log|Z(n,x,\omega)|\leq \limsup_{t\to\infty}\frac{1}{t}\log|Z(t,x,\omega)|,$$

is obvious. Hence (18) holds. \Box

Ruelle's Non-linear Ergodic Theorem

Theorem 4 ([Ru.1], 1979)

Let $\Omega \ni \mapsto F_{\omega} \in C^{k,\delta}(\mathbf{R}^d, 0; \mathbf{R}^d, 0)$ be measurable such that $E \log^+ \|F_{\cdot}| \bar{B}(0,1) \| < \infty$. Set $F^n(\omega) := F_{\theta(n-1,\omega)} \circ \cdots \circ F_{\theta(1,\omega)} \circ F_{\omega}$. Suppose $\lambda < 0$ is not in the spectrum of the cocycle $(DF_{\omega}^n(0), \theta(n,\omega))$. Then there is a sure event $\Omega_0 \in \mathcal{F}$ such that $\theta(1,\cdot)(\Omega_0) \subseteq \Omega_0$, and measurable functions $\beta(\omega) > \alpha(\omega) > 0, \gamma(\omega) > 1$ with the following properties:

(a) If $\omega \in \Omega_0$, the set

$$V_{\omega}^{\lambda} := \{ x \in \bar{B}(0, \alpha(\omega)) : ||F_{\omega}^{n}(x)|| \le \beta(\omega)e^{n\lambda} \text{ for all } n \ge 0 \}$$

is a $C^{k,\delta}$ submanifold of $\bar{B}(0,\alpha(\omega))$.

(b) If $x_1, x_2 \in V_{\omega}^{\lambda}$, then

$$||F_{\omega}^{n}(x_{1}) - F_{\omega}^{n}(x_{2})|| \le \gamma(\omega)||x_{1} - x_{2}||e^{n\lambda}||$$

for all integers $n \geq 0$. If $\lambda' < \lambda$ and $[\lambda', \lambda]$ is disjoint from the spectrum of $(DF_{\omega}^{n}(0), \theta(n, \omega))$, then there exists a measurable $\gamma'(\omega) > 1$ such that

$$||F_{\omega}^{n}(x_{1}) - F_{\omega}^{n}(x_{2})|| \le \gamma'(\omega)||x_{1} - x_{2}||e^{n\lambda'}||$$

for all $x_1, x_2 \in V_{\omega}^{\lambda}$ and all integers $n \geq 0$.

Proof

[Ru.1], Theorem 5.1, p. 292.

Construction of the Stable/Unstable Manifolds

Assume the hypotheses of Theorem 1.

Consider the auxiliary cocycle (Z,θ) . Define the family of maps $F_{\omega}: \mathbf{R}^d \to \mathbf{R}^d$ by $F_{\omega}(x):=Z(1,x,\omega)$ for all $\omega \in \Omega$ and $x \in \mathbf{R}^d$. Let $\tau:=\theta(1,\cdot):\Omega \to \Omega$. Define $F_{\omega}^n:=F_{\tau^{n-1}(\omega)}\circ \cdots \circ F_{\tau(\omega)}\circ F_{\omega}$. Then cocycle property for Z gives $F_{\omega}^n=Z(n,\cdot,\omega)$ for each $n\geq 1$. F_{ω} is $C^{k,\epsilon}$ ($\epsilon\in(0,\delta)$) and $(DF_{\omega})(0)=D_2\phi(1,Y(\omega),\omega)$. By measurability of the flow ϕ , the map $\omega\mapsto (DF_{\omega})(0)$ is \mathcal{F} -measurable. By (11) of Lemma 2, the map $\omega\mapsto \log^+\|D_2\phi(1,Y(\omega),\omega)\|_{L(\mathbf{R}^d)}$ is integrable. The discrete cocycle $((DF_{\omega}^n)(0),\theta(n,\omega),n\geq 0)$ has a non-random Lyapunov spectrum which coincides with that of the linearized continuous cocycle $(D_2\phi(t,Y(\omega),\omega),\theta(t,\omega),t\geq 0)$, viz. $\{\lambda_m<\cdots<\lambda_{i+1}<\lambda_i<\cdots<\lambda_2<\lambda_1\}$, where each λ_i has fixed multiplicity $q_i,1\leq i\leq m$ (Lemma 2). If $\lambda_i>0$ for all $1\leq i\leq m$, then take $\tilde{\mathcal{S}}(\omega):=\{Y(\omega)\}$ for all $\omega\in\Omega$. Theorem is trivial in this case. Suppose that at least one $\lambda_i<0$.

Use discrete non-linear ergodic theorem of Ruelle (Theorem 4) and its proof to obtain a sure event $\Omega_1^* \in \mathcal{F}$ such that $\theta(t,\cdot)(\Omega_1^*) = \Omega_1^*$ for all $t \in \mathbf{R}$, \mathcal{F} -measurable positive random variables $\rho_1, \beta_1 : \Omega_1^* \to (0, \infty), \rho_1 < \beta_1$, and a random family of $C^{k,\epsilon}$ ($\epsilon \in (0,\delta)$) submanifolds of $\bar{B}(0,\rho_1(\omega))$ denoted by $\tilde{\mathcal{S}}_d(\omega), \omega \in \Omega_1^*$, and satisfying the following properties for each $\omega \in \Omega_1^*$:

$$\tilde{\mathcal{S}}_d(\omega) = \{ x \in \bar{B}(0, \rho_1(\omega)) : |Z(n, x, \omega)| \le \beta_1(\omega) e^{(\lambda_{i_0} + \epsilon_1)n} \text{ for all } n \in \mathbf{Z}^+ \}.$$
(21)

 $\tilde{\mathcal{S}}_d(\omega)$ is tangent at 0 to the stable subspace $\mathcal{S}(\omega)$ of the linearized flow $D_2\phi$, viz. $T_0\tilde{\mathcal{S}}_d(\omega) = \mathcal{S}(\omega)$. Therefore dim $\tilde{\mathcal{S}}_d(\omega)$ is non-random by ergodicity of θ . Also

$$\limsup_{n \to \infty} \frac{1}{n} \log \left[\sup_{\substack{x_1 \neq x_2, \\ x_1, x_2 \in \tilde{\mathcal{S}}_d(\omega)}} \frac{|Z(n, x_1, \omega) - Z(n, x_2, \omega)|}{|x_1 - x_2|} \right] \leq \lambda_{i_0}.$$
 (22)

The $\theta(t,\cdot)$ -invariant sure event $\Omega_1^* \in \mathcal{F}$ is constructed using the ideas in Ruelle's proof (of Theorem 5.1 in [Ru.1], p. 293), combined with the estimate (10) of Lemma 2 and the subadditive ergodic theorem (Lemma 1 (ii)).

For each $\omega \in \Omega_1^*$, let $\tilde{\mathcal{S}}(\omega)$ be the set defined in part (a) of the theorem. Then by definition of $\tilde{\mathcal{S}}_d(\omega)$ and Z:

$$\tilde{\mathcal{S}}(\omega) = \tilde{\mathcal{S}}_d(\omega) + Y(\omega). \tag{23}$$

Since $\tilde{\mathcal{S}}_d(\omega)$ is a $C^{k,\epsilon}$ ($\epsilon \in (0,\delta)$) submanifold of $\bar{B}(0,\rho_1(\omega))$, then $\tilde{\mathcal{S}}(\omega)$ is a $C^{k,\epsilon}$ ($\epsilon \in (0,\delta)$) submanifold of $\bar{B}(Y(\omega),\rho_1(\omega))$. Furthermore, $T_{Y(\omega)}\tilde{\mathcal{S}}(\omega) = T_0\tilde{\mathcal{S}}_d(\omega) = \mathcal{S}(\omega)$. Hence dim $\tilde{\mathcal{S}}(\omega) = \dim \mathcal{S}(\omega) = \lim_{i \to \infty} q_i$, and is non-random.

Now (22) implies that

$$\limsup_{n \to \infty} \frac{1}{n} \log |Z(n, x, \omega)| \le \lambda_{i_0} \tag{24}$$

for all ω in Ω_1^* and all $x \in \tilde{\mathcal{S}}_d(\omega)$. Therefore by Lemma 4, there is a sure event $\Omega_2^* \subseteq \Omega_1^*$ such that $\theta(t,\cdot)(\Omega_2^*) = \Omega_2^*$ for all $t \in \mathbf{R}$, and

$$\limsup_{t \to \infty} \frac{1}{t} \log |Z(t, x, \omega)| \le \lambda_{i_0}$$
 (25)

for all $\omega \in \Omega_2^*$ and all $x \in \tilde{\mathcal{S}}_d(\omega)$. Therefore (2) holds.

To prove (b), let $\omega \in \Omega_1^*$. By (22), there is a positive integer $N_0 := N_0(\omega)$ (independent of $x \in \tilde{\mathcal{S}}_d(\omega)$) such that $Z(n,x,\omega) \in \bar{B}(0,1)$ for all $n \geq N_0$. Let $\Omega_4^* := \Omega_2^* \cap \Omega_3$, where Ω_3 is the shift-invariant sure event defined in the proof of Lemma 4. Then Ω_4^* is a sure event and $\theta(t,\cdot)(\Omega_4^*) = \Omega_4^*$ for all $t \in \mathbf{R}$. By cocycle property, Mean-Value theorem and the ergodic theorem (Lemma 1(i)), we get (b).

To prove the invariance property (4), apply the Oseledec theorem to the linearized cocycle $(D_2\phi(t,Y(\omega),\omega),\theta(t,\omega))$ ([Mo.1], Theorem 4, Corollary 2). This gives a sure $\theta(t,\cdot)$ -invariant event, also denoted by Ω_1^* , such that $D_2\phi(t,Y(\omega),\omega)(\mathcal{S}(\omega))\subseteq \mathcal{S}(\theta(t,\omega))$ for all $t\geq 0$ and all $\omega\in\Omega_1^*$. Equality holds because $D_2\phi(t,Y(\omega),\omega)$ is injective and dim $\mathcal{S}(\omega)=\dim \mathcal{S}(\theta(t,\omega))$ for all $t\geq 0$ and all $\omega\in\Omega_1^*$.

To prove the asymptotic invariance property (3), use the ideas in the proofs of Theorems 5.1 and 4.1 in [Ru.1], pp. 285-297, to pick random variables ρ_1, β_1 and a sure event (also denoted by) Ω_1^* such that $\theta(t, \cdot)(\Omega_1^*) = \Omega_1^*$ for all $t \in \mathbf{R}$, and with the property that for any $\epsilon \in (0, \epsilon_1)$ and every $\omega \in \Omega_1^*$, there exists a positive $K_1^{\epsilon}(\omega)$ for which the inequalities

$$\rho_1(\theta(t,\omega)) \ge K_1^{\epsilon}(\omega)\rho_1(\omega)e^{(\lambda_{i_0}+\epsilon)t}, \quad \beta_1(\theta(t,\omega)) \ge K_1^{\epsilon}(\omega)\beta_1(\omega)e^{(\lambda_{i_0}+\epsilon)t}$$
(26)

hold for all $t \geq 0$. Use (b) to obtain a sure event $\Omega_5^* \subseteq \Omega_4^*$ such that $\theta(t,\cdot)(\Omega_5^*) = \Omega_5^*$ for all $t \in \mathbf{R}$, and for any $0 < \epsilon < \epsilon_1$ and $\omega \in \Omega_4^*$, there exists $\beta^{\epsilon}(\omega) > 0$ (independent of x) with

$$|\phi(t, x, \omega) - Y(\theta(t, \omega))| \le \beta^{\epsilon}(\omega) e^{(\lambda_{i_0} + \epsilon)t}$$
(27)

for all $x \in \tilde{\mathcal{S}}(\omega)$, $t \geq 0$. Fix $t \geq 0$, $\omega \in \Omega_5^*$ and $x \in \tilde{\mathcal{S}}(\omega)$. Let n be a non-negative integer. Then the cocycle property and (27) imply that

$$|\phi(n,\phi(t,x,\omega),\theta(t,\omega)) - Y(\theta(n,\theta(t,\omega)))|$$

$$= |\phi(n+t,x,\omega) - Y(\theta(n+t,\omega))|$$

$$\leq \beta^{\epsilon}(\omega)e^{(\lambda_{i_0}+\epsilon)(n+t)}$$

$$\leq \beta^{\epsilon}(\omega)e^{(\lambda_{i_0}+\epsilon)t}e^{(\lambda_{i_0}+\epsilon_1)n}.$$
(28)

If $\omega \in \Omega_5^*$, then it follows from (26),(27), (28) and the definition of $\tilde{\mathcal{S}}(\theta(t,\omega))$ that there exists $\tau_1(\omega) > 0$ such that $\phi(t,x,\omega) \in \tilde{\mathcal{S}}(\theta(t,\omega))$ for all $t \geq \tau_1(\omega)$. This proves asymptotic invariance.

We prove (d), regarding the existence of the local unstable manifolds $\tilde{\mathcal{U}}(\omega)$, by running both the flow ϕ and the shift θ backward in time:

$$\tilde{\phi}(t, x, \omega) := \phi(-t, x, \omega), \ \tilde{Z}(t, x, \omega) := Z(-t, x, \omega), \ \tilde{\theta}(t, \omega) := \theta(-t, \omega)$$

for all $t \geq 0$ and all $\omega \in \Omega$. $(\tilde{Z}(t,\cdot,\omega),\tilde{\theta}(t,\omega),t \geq 0)$ is a smooth cocycle, with $\tilde{Z}(t,0,\omega)=0$ for all $t\geq 0$. The linearized flow $(D_2\tilde{\phi}(t,Y(\omega),\omega),\tilde{\theta}(t,\omega),t\geq 0)$ is an $L(\mathbf{R}^d)$ -valued perfect cocycle with a non-random finite Lyapunov spectrum $\{-\lambda_1<-\lambda_2<\dots<-\lambda_i<-\lambda_{i+1}<\dots<-\lambda_m\}$ where $\{\lambda_m<\dots<\lambda_{i+1}<\lambda_i<\dots<\lambda_2<\lambda_1\}$ is the Lyapunov spectrum of the forward linearized flow $(D_2\phi(t,Y(\omega),\omega),\theta(t,\omega),t\geq 0)$. Apply first part of the proof to get stable manifolds for the backward flow $\tilde{\phi}$ satisfying assertions (a), (b), (c). This translates into the existence of unstable manifolds for the original flow ϕ , and (d), (e), (f) automatically hold. Hence

there is a sure event $\Omega_6^* \in \mathcal{F}$ such that $\theta(-t, \cdot)(\Omega_6^*) = \Omega_6^*$ for all $t \in \mathbf{R}$, and (d), (e) and (f) hold for all $\omega \in \Omega_6^*$.

Define the sure event $\Omega^* := \Omega_6^* \cap \Omega_5^*$. Then $\theta(t, \cdot)(\Omega^*) = \Omega^*$ for all $t \in \mathbf{R}$. Assertions (a)-(f) hold for all $\omega \in \Omega^*$.

Measurability of the stable manifolds follows from

$$\tilde{\mathcal{S}}(\omega) = Y(\omega) + \tilde{\mathcal{S}}_d(\omega) \tag{29}$$

$$\tilde{\mathcal{S}}_d(\omega) = \lim_{m \to \infty} \bar{B}(0, \rho_1(\omega)) \cap \bigcap_{i=1}^m f_i(\cdot, \omega)^{-1}(\bar{B}(0, 1))$$
 (30)

$$f_n(x,\omega) := \beta_1(\omega)^{-1} e^{-(\lambda_{i_0} + \epsilon_1)n} Z(n, x, \omega), \quad x \in \mathbf{R}^d, \, \omega \in \Omega_1^*,$$

for all integers $n \geq 0$. (Above limit is taken in the metric d^* on $\mathcal{C}(\mathbf{R}^d)$.) Use joint continuity of translation and measurability of Y, f_i , ρ_1 , finite intersections and the continuity of the maps

$$\mathbf{R}^+ \ni r \mapsto \bar{B}(0,r) \in \mathcal{C}(\mathbf{R}^d).$$

$$\operatorname{Hom}(\mathbf{R}^d) \ni f \mapsto f^{-1}(\bar{B}(0,1)) \in \mathcal{C}(\mathbf{R}^d).$$

When h, g_i are in C_b^{∞} , adapt above argument to give a sure event in \mathcal{F} , also denoted by Ω^* such that $\tilde{\mathcal{S}}(\omega)$, $\tilde{\mathcal{U}}(\omega)$ are C^{∞} for all $\omega \in \Omega^*$. \square

References

- [A] Arnold, L., Random Dynamical Systems, Springer-Verlag (To appear).
- [A-S] Arnold, L., and Scheutzow, M. K. R., Perfect cocycles through stochastic differential equations, *Probab. Th. Rel. Fields*, 101, (1995), 65-88.
- [A-I] Arnold, L., and Imkeller, P., Stratonovich calculus with spatial parameters and anticipative problems in multiplicative ergodic theory, Stoch. Proc. Appl. 62 (1996), 19-54.
 - [C] Carverhill, A., Flows of stochastic dynamical systems: Ergodic theory, *Stochastics*, 14 (1985), 273-317.
- [I-W] Ikeda, N., and Watanabe, S., Stochastic Differential Equations and Diffusion Processes, Second Edition, North-Holland-Kodansha (1989).
 - [Ku] Kunita, H., Stochastic Flows and Stochastic Differential Equations, Cambridge University Press, Cambridge, New York, Melbourne, Sydney (1990).
- [Mo.1] Mohammed, S.-E. A., The Lyapunov spectrum and stable manifolds for stochastic linear delay equations, Stochastics and Stochastic Reports, Vol. 29 (1990), 89-131.
- [Mo.2] Mohammed, S.-E. A., Lyapunov exponents and stochastic flows of linear and affine hereditary Systems, Diffusion Processes and Related Problems in Analysis, Vol. II,

- edited by Mark Pinsky and Volker Wihstutz, Birkhauser (1992), 141-169.
- [M-N-S] Millet, A., Nualart, D., and Sanz, M., Large deviations for a class of anticipating stochastic differential equations, *The Annals of Probability*, 20 (1992), 1902-1931.
- [M-S.1] Mohammed, S.-E. A., and Scheutzow, M. K. R., Lyapunov exponents of linear stochastic functional differential equations driven by semimartingales, Part I: The multiplicative ergodic theory, Ann. Inst. Henri Poincaré, Probabilités et Statistiques, Vol. 32, 1, (1996), 69-105. pp. 43.
- [M-S.2] Mohammed, S.-E. A., and Scheutzow, M. K. R., Spatial estimates for stochastic flows in Euclidean space, to appear in *The Annals of Probability*.
 - [Nu] Nualart, D., Analysis on Wiener space and anticipating stochastic calculus (to appear in) St. Flour Notes.
 - [N-P] Nualart, D., and Pardoux, E., Stochastic calculus with anticipating integrands, Analysis on Wiener space and anticipating stochastic calculus, *Probab. Th. Rel. Fields*, 78 (1988), 535-581.
 - [O] Oseledec, V. I., A multiplicative ergodic theorem. Lyapunov characteristic numbers for dynamical systems, Trudy Moskov. Mat. Obšč. 19 (1968), 179-210. English transl. Trans. Moscow Math. Soc. 19 (1968), 197-221.

- [O-P] Ocone, D., and Pardoux, E., A generalized Itô-Ventzell formula. Application to a class of anticipating sto-chastic differential equations, Ann. Inst. Henri Poincaré, Probabilités et Statistiques, Vol. 25, no. 1 (1989), 39-71.
- [Ru.1] Ruelle, D., Ergodic theory of differentiable dynamical systems, *Publ. Math. Inst. Hautes Etud. Sci.* (1979), 275-306.
- [Ru.2] Ruelle, D., Characteristic exponents and invariant manifolds in Hilbert space, *Annals of Mathematics* 115 (1982), 243–290.
 - [Sc] Scheutzow, M. K. R., On the perfection of crude cocycles, Random and Computational Dynamics, 4, (1996), 235-255.
 - [Wa] Wanner, T., Linearization of random dynamical systems, in *Dynamics Reported*, vol. 4, edited by U. Kirchgraber and H.O. Walther, Springer (1995), 203-269.