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# Sub-monthly prediction of harmful algal blooms based on automated cell imaging

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## Sub-monthly prediction of harmful algal blooms based on automated cell imaging

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#### 1 Sub-monthly prediction of harmful algal blooms based on automated cell

#### 2 imaging

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- 17 All authors helped prepare the manuscript and approved the final version. The authors declare no
- 18 competing interests.
- 19

#### 20 Data availability statement

All data and code required for the analysis will be made publicly available upon publication.

#### 23 Abstract

Harmful algal blooms (HABs) are an increasing threat to global fisheries and human health. The 24 25 mitigation of HABs requires management strategies to successfully forecast the abundance and distribution of harmful algal taxa. In this study, we attempt to characterize the dynamics of 2 26 phytoplankton genera (Pseudo-nitzschia spp. and Dinophysis spp.) in Narragansett Bay, Rhode 27 28 Island, using empirical dynamic modeling. We utilize a high-resolution Imaging FlowCytobot dataset to generate a daily-resolution time series of phytoplankton images and then characterize 29 the sub-monthly (1-30 days) timescales of univariate and multivariate prediction skill for each 30 taxon. Our results suggest that univariate predictability is low overall, different for each taxon and 31 does not significantly vary over sub-monthly timescales. For all univariate predictions, models can 32 rely on the inherent autocorrelation within each time series. When we incorporated multivariate 33 34 data based on quantifiable image features, we found that predictability increased for both taxa and that this increase was apparent on timescales >7 days. Pseudo-nitzschia spp. has distinctive 35 36 predictive dynamics that occur on timescales of around 16 and 25 days. Similarly, Dinophysis spp. is most predictable on timescales of 25 days. The timescales of prediction for Pseudo-nitzschia 37 spp. and Dinophysis spp. could be tied to environmental drivers such as tidal cycles, water 38 temperature, wind speed, community biomass, salinity, and pH in Narragansett Bay. For most 39 drivers, there were consistent effects between the environmental variables and the phytoplankton 40 taxon. Our analysis displays the potential of utilizing data from automated cell imagers to forecast 41 and monitor harmful algal blooms. 42

43

Keywords: Imaging FlowCytobot (IFCB); empirical dynamic modeling (EDM); Narragansett
Bay; phytoplankton population dynamics; ecological forecasting; Pseudo-nitzschia; Dinophysis

#### 46 Introduction

Harmful algal blooms (HABs) are anomalous increases in phytoplankton abundance, 47 biomass, or distribution that can negatively affect marine ecosystems and public health (Fleming 48 et al. 2011; Berdalet et al. 2016; Karlson et al. 2021). The rising frequency of such events in the 49 past few decades is of increasing global concern (Xiao et al. 2019; Gobler 2020). Some estimates 50 51 of economic damage due to HABs exceed hundreds of millions of dollars (Anderson et al. 2000), often due to fisheries closures (Brown et al. 2020; Sakamoto et al. 2021), disruption to tourism 52 (Smith et al. 2019; Béchard 2020) and damage to human health (Grattan et al. 2016; Kouakou and 53 Poder 2019). Consequently, the successful prediction and mitigation of HABs is a research priority 54 for state and national governments worldwide (Park et al. 2013; Brooks et al. 2016). 55

HAB predictions often require large amounts of data from various sources and 56 sophisticated modeling techniques (Franks 2018; Ralston and Moore 2020), as well as detailed 57 58 information on local and regional oceanographic features (Anderson et al. 2010; Dippner et al. 2011; Lapucci et al. 2022). Due to the requirement of high resolution and consistent data, 59 monitoring programs are implementing automated systems (Babin et al. 2005; Jochens et al. 2010) 60 61 with extensively trained algorithms (Sosik and Olson 2007; Ellen et al. 2019; Orenstein et al. 2020) that can identify and alert local officials of the presence, abundance and risk of HAB development. 62 The rapid deployment of such systems has greatly expanded the ability to detect HABs; however, 63 64 less is known about the utility of imaging data for HAB prediction models.

In this study, we explored the use of phytoplankton imaging data for HAB predictions in Narragansett Bay, Rhode Island (NBay). Narragansett Bay is a shallow coastal marine estuary of great cultural, historical, and economic importance to local communities (Herndon and Sekatau 1997; Dalton et al. 2010; Nixon and Fulweiler 2012). Coastal marine estuaries are highly dynamic

environments that are subject to seasonality (Carstensen et al. 2015), the influence of both 69 freshwater and seawater sources (Pilson 1985), large-scale climate phenomena (Scavia et al. 2002), 70 and anthropogenic inputs of nutrients (Cundell 1973; Goldberg et al. 1977). Within the past 71 decade, toxic harmful algal blooms have led to fisheries closures in Narragansett Bay (Bates et al. 72 2018) and motivated extensive research into the potential environmental drivers and species 73 74 composition (Sterling et al. 2022) of the relevant bloom-causing phytoplankton genera. Of particular importance in this area are Pseudo-nitzschia spp. and Dinophysis spp. due to their 75 potential toxicity and relevance for local fishery disruption. 76

Natural phytoplankton populations are variable from daily, seasonal to decadal timescales 77 (Chavez et al. 2003; Barton et al. 2016; Blauw et al. 2018). High variability in natural 78 79 phytoplankton populations is characteristic of non-linear and chaotic dynamics (Ascioti et al. 1993; Smayda 1998). In this paper, we used empirical dynamic modeling (EDM) to predict the 80 abundance of Pseudo-nitzschia spp. and Dinophysis spp. in Narragansett Bay, Rhode Island. These 81 82 genera were selected for a couple of reasons: their role in local harmful algal blooms and the availability of a dynamic, regular time series that would allow for the use of data-driven analyses. 83 EDM is a non-parametric framework that can avoid the pitfalls of typical statistical modeling by 84 relying on data-driven attractor reconstruction (Perretti et al. 2013; Chang et al. 2017). 85

Our goal was to characterize the sub-monthly univariate and multivariate prediction timescales of *Pseudo-nitzschia spp.* and *Dinophysis spp.* utilizing a high temporal resolution dataset generated with an Imaging FlowCytobot (Olson and Sosik 2007). Automated instruments such as the Imaging FlowCytobot generate datasets of phytoplankton images and many associated features (i.e. image texture, contrast, object size etc.). Specifically, we aim to answer (1) How predictable are the harmful algal target species? (2) How does this predictability vary with time?

and (3) Which image features best describe the dynamics of the taxa? Once we identified the 92 important timescales, we also linked specific environmental drivers to the dynamics of the 93 phytoplankton populations. Our study did not attempt to offer detailed mechanistic explanations 94 of observed phenomena, nor develop tools that might model the growth and termination of harmful 95 algal blooms, but instead, it focused on identifying the potential of imaging data in prediction 96 models. By identifying the relevant dynamical timescales of harmful algal blooms, we also hoped 97 to provide local and regional management with a critical timeframe of action for the development 98 of environmental policy. Our underlying assumption was that the predictability of Pseudo-99 nitzschia spp. and Dinophysis spp. in Narragansett Bay had distinct timescales that varied in 100 response to environmental drivers and intrinsic population dynamics. 101

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#### **103** Materials and Methods

#### 104 *Automated cell imaging*

105 All the time series used in this study were collected by deploying an Imaging FlowCytobot 106 (IFCB) in Narragansett Bay, Rhode Island. The IFCB is an automated, flow-through imaging 107 system that captures images of the extant phytoplankton community in seawater. The system has 108 a maximum size limit of 150µm and works by drawing water at approximately 1m under the 109 surface at low tide. As our IFCB was deployed at the end of a pier (41.492°N, 71.419°W), the 110 actual sampling depth varied with the tidal cycle. Images can be observed in real-time using the 111 IFCB dashboard (http://ifcb-dashboard.gso.uri.edu/).

The IFCB samples approximately every 20 minutes depending on the number of cells
within a given sample. We used daily aggregated IFCB data from 14<sup>th</sup> June 2017 to 20<sup>th</sup> October

114 2021, barring gaps in the time series due to equipment malfunction or maintenance. Our data span 115 1590 days of observation with 518 days of missing data. For prediction tasks, all missing data 116 points were approximated using 30-day exponential moving averages (EMA) computed by the R 117 package "imputeTS" (Moritz and Bartz-Beielstein 2017). We used daily aggregated data, instead 118 of other shorter timescales (such as 1-hr or 12-hr) for three broad reasons: the influence of high 119 time series autocorrelation, irregular gaps in data collection, and, to strike a balance between 120 computational costs and expected analytical benefit.

A machine-learning approach was used to identify and classify the phytoplankton taxa 121 from a subset of annotated images (Sosik and Olson 2007). All obtained images classified as 122 Pseudo-nitzschia spp. and Dinophysis spp. were counted and reported as a concentration based on 123 the average sampling volume for each day (*images*  $mL^{-1}$ ). Higher concentrations of images act 124 as a proxy of higher abundance in the natural environment and lower concentrations of images 125 show that the taxon is rare/absent. To test the general ability to use image concentration as a proxy 126 for phytoplankton abundance, we visually compared our image concentration time series to a long-127 term weekly monitoring site located approximately 12km north of our IFCB location 128 129 (https://web.uri.edu/gso/research/plankton/). Figure S1 highlights that our IFCB image concentration agreed with the general pattern of *Pseudo-nitzschia spp.* abundance in Narragansett 130 Bay (as determined by microscopy counts) over the duration of our time series. 131

We evaluated the classifier's performance for sensitivity and precision with a manually annotated library of images. Table 1 reports the performance of the classifier for *Pseudo-nitzschia spp.* and *Dinophysis spp.* 

135 
$$Sensitivity = \frac{TP}{TP + FN}$$

136 
$$Precision = \frac{TP}{TP + FP}$$

137 where TP, FP and FN were the number of true positive, false positive, and false negative images.

**Table 1:** Sensitivity and precision of the automatic classifier for each of the phytoplankton classes.

	Sensitivity	Precision
Pseudo-nitzschia spp. (N=626)	0.85	0.94
Dinophysis spp. (N=412)	0.95	0.96

236 image features are automatically estimated for each IFCB image (Sosik and Olson 2007, https://github.com/hsosik/ifcb-analysis/wiki). We selected 20 features for further analysis based on their relevance to phytoplankton morphology and ecology (Sonnet et al. 2022). The average daily values for the image features, scaled by the average sampling volume for each day, formed a multi-dimensional time series for each taxon. Table 2 lists all the features and their units. 

Feature	Units
area	pixels <sup>2</sup>
biovolume	pixels <sup>3</sup>
major axis	pixels
minor axis	pixels
perimeter	pixels
orientation	degrees
eccentricity	-
solidity	-
texture uniformity	-
texture smoothness	-
texture gray	-
texture entropy	-
texture contrast	-
h90	pixels
h180	pixels
hflip	pixels
extent	pixels
equivalent diameter	pixels
convex area	pixels <sup>2</sup>
convex perimeter	pixels

**Table 2:** List of all image features used in this study and their units.

#### Environmental data

We compiled data from various monitoring programs located in and around Narragansett 160 Bay. Daily averages of water temperature (°C), salinity (*ppt*), chlorophyll ( $\mu g L^{-1}$ ), and pH were 161 requested from the Narragansett Bay Fixed Site Monitoring Network (NBFSMN, personal 162 communication: Heather Stoffel). These measurements were co-located with the Imaging 163 FlowCytobot. Daily averages of wind speed  $(m s^{-1})$  were drawn from the Kingston weather 164 station (41.49°N 71.54°W; U.S. Climate Reference Network; 165 https://www1.ncdc.noaa.gov/pub/data/uscrn/products/subhourly01/). Daily averages of tidal 166 height (Mean Sea Level; m) were calculated from measurements at the NOAA Quonset Point 167 Buoy (41° 35.2 N, 71° 24.6 W; #8454049; https://tidesandcurrents.noaa.gov/). Additional 168 environmental data, such as ambient nutrient concentrations, were not available at the same 169 temporal scale as the imaging data used in the study. 170

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#### 172 Univariate predictions

We used empirical dynamic modeling (EDM) to make univariate predictions for the time 173 series of each harmful algae. Every time series was normalized (i.e. subtracting the mean value of 174 175 the time series and dividing by the standard deviation of the time series) before the application of EDM. Specifically, we relied on simplex projection (Sugihara and May 1990) with a consistent 176 embedding dimension of 4 and leave-one-out cross validation. This means that the univariate 177 attractor of a time series was embedded in a 4-dimensional space using the original times series 178 and successive lags of the same time series. Each point is described by  $(x_t, x_{t-1}, x_{t-2}, x_{t-3})$  where 179  $x_t$  is the value of x at time point t,  $x_{t-1}$  is its value at time t-1, and so on. The embedding 180

dimension was set at 4 to prevent overfitting and maximize the utilization of our daily-scale time 181 series data. Figure S2 shows how varying the embedding dimension affects the predictability of 182 each taxon with fixed prediction intervals of 1, 7, 14 and 28 days. An embedding dimension of 4 183 allowed for reasonable descriptions across all timescales for both taxa, with a lower risk of 184 overfitting our models to potentially noisy dynamics. The model creation and prediction sets were 185 randomly selected from the entire time series in intervals of 250 days. After bootstrapping 200 186 samples for each taxon, we generated a mean prediction and 95% confidence intervals 187  $(1.96 \times SE)$ . By randomizing the selection of model and prediction libraries, we tried to account 188 for the effects of imputed data into the time series, as well as avoid the effects of possible non-189 stationarity over the 1590 days of data. 190

We tested the predictability of each taxon for timescales of 1 to 30 days. Predictability was 191 described by  $\rho_{model}$ , the Pearson correlation coefficient, between the observed and the predicted 192 193 values after attractor reconstruction. To account for inherent autocorrelation within each time series, we subtracted the absolute value of the autocorrelation coefficient at each timescale of 194 prediction. The effective value of predictability was reported as  $\Delta \rho$ , which is the arithmetic 195 difference of the univariate predictability  $\rho_{model}$  and the autocorrelation coefficient  $\rho_{auto}$ . 196 Therefore,  $\Delta \rho$  quantifies the ability of our model to predict dynamics beyond autocorrelation 197 across a range of sub-monthly timescales. Due to the short timescales of prediction in this study 198 (<30 days), our dataset of 1590 days provided reasonable coverage of all possible sub-monthly 199 200 dynamics for these harmful algal taxa.

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Multiview embeddings are an effective technique for increasing predictability and drawing out information from multiple related time series (Ye and Sugihara 2016). We used MVE to utilize the associated dataset of image features collected by the IFCB. Once more, the embedding dimension was set to 4 for all taxa and the entire time series was used for model and prediction libraries. We relied on leave-one-out cross-validation instead of separate model and prediction libraries.

Each multivariate attractor was created by randomly selecting 3 normalized time series of features and the original time series of image concentration (*images mL*<sup>-1</sup>). Our goal was to predict the proxy abundance of each taxon by leveraging information stored in the image features. Predictability was evaluated for timescales of 1-30 days and reported as  $\Delta \rho$  (model predictability beyond autocorrelation), RMSE (root-mean-square error) and MAE (mean absolute error). We considered 500 trials of image feature combinations and reported predictability as the arithmetic mean with 95% confidence intervals (1.96 × *SE*).

For the best multivariate models (top 5% in terms of  $\rho_{model}$ ), we reported the frequency of appearance for each image feature as a proportion. A proportion of 0 implies that the feature did not show up in the best multivariate models while a proportion of 1 implies that it was always present. Based on the frequency of appearance, we could deduce the contribution of each feature in improving the overall predictability of the phytoplankton species.

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Once we identified any relevant timescales of prediction, we wanted to understand whether 226 227 there was a link between the abundance of harmful algal taxa and relevant environmental drivers. We used convergent cross mapping (CCM; Sugihara et al. 2012) to infer causation between the 228 environmental dataset and image concentration (*images*  $mL^{-1}$ ). Embedding dimensions were 229 optimized (i.e. selecting the embedding dimension that provides the highest prediction skill  $\rho$ ) to 230 each environmental variable (up to a maximum of 7 to prevent overfitting) and library sizes ranged 231 from 100 - 1400 in intervals of 100 days. There were 20 samples each for every library size and 232 the time to prediction ranged from 1-30 days. We tested whether we could infer causation by 233 234 predicting the values of past environmental variables from the abundance of the harmful algal taxa. Predictability was quantified by the cross-map prediction skill ( $\rho$ ), where higher values indicate 235 better predictions. Convergence was estimated using three tests -(1) Mann-Kendall trend test for 236  $\rho$  with increasing library size, (2) a Student's t-test for the  $\rho$  distributions at the maximum and 237 minimum library size and (3) by validating that the prediction skill  $\rho$  at the maximum library size 238 was greater than the Pearson correlation coefficient between image concentration and the 239 environmental time series. Only the predictions which satisfied all conditions and were significant 240 241 for both the Mann-Kendall and the Student's t-test (p-value < 0.05) were deemed convergent. If 242 any of the tests failed, then the causal effect of the environmental variable on the phytoplankton 243 taxa was deemed to be unresolved at those specific timescales. Cross-map prediction skill ( $\rho$ ) was 244 normalized to the embedding dimension by averaging  $\rho$  across prediction horizons (Saberski et al. 2021). 245

Software

All the analyses were conducted in R (R Core Team 2021). For plotting and data visualization, we used the R packages "ggplot2" (Wickham 2016) and "cowplot" (Wilke 2020). EDM was applied using pre-built functions in the R package "rEDM" (Park et al. 2022). Additionally, the R package "Kendall" (McLeod 2022) was used to conduct some statistical tests.

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253 **Results** 

Both *Pseudo-nitzschia spp.* and *Dinophysis spp.* in Narragansett Bay showed intermittent periods of high and low abundance in Narragansett Bay. The IFCB captured such bloom dynamics using the concentration of identified images of both taxa (Figure 1; left column). When evaluated for the autocorrelation inherent within each time series, both *Pseudo-nitzschia spp.* and *Dinophysis spp.* had decreasing autocorrelation with time (Figure 1; right column). The decrease was more rapid for *Pseudo-nitzschia spp.* (ACF < 0.25 within 7 days), whereas *Dinophysis spp.* showed a more gradual decrease over the entire 30 days.

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Figure 1: Time series of 2 harmful algal bloom-forming taxa in Narragansett Bay, Rhode Island (left column) and their associated autocorrelation functions (ACF; right column). Relative abundance is estimated from the number of unique images taken by the IFCB and classified as (a) *Pseudo-nitzschia spp.* and (c) *Dinophysis spp.* Autocorrelation decreases with time and varies depending on the dynamics of each specific taxon.

- 270 271
- The univariate predictability of both time series ( $\Delta \rho$ ) was low overall and did not greatly change over a prediction horizon of 30 days. The univariate predictability of *Dinophysis spp.* indicated some promise of the model over autocorrelation on horizons of >28 days, whereas the results for *Pseudo-nitzschia spp.* indicated that there is little to no predictability inherent within the time series beyond autocorrelation across all sub-monthly timescales.



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Figure 2: Univariate prediction skill ( $\Delta \rho$ ) of the time series of (a) *Pseudo-nitzschia spp.* and (b) *Dinophysis spp.* over a prediction horizon of 1-30 days. Model predictions ( $\rho_{model}$ ) were calculated from 200 random libraries of 250 days each and the results were reported as an arithmetic mean with 95% confidence intervals ( $\pm 1.96 \times S.E.$ ).  $\Delta \rho$  was calculated by subtracting the autocorrelation coefficient at each prediction horizon.

Multivariate prediction skill ( $\Delta \rho$ ), calculated using the time series of image abundance and 3 associated image features, was much higher than the univariate prediction skill for both *Pseudonitzschia spp.* and *Dinophysis spp.* Using the original time series with only 3 image features at a time (multivariate embedding dimension = 4) allowed for direct comparisons to the univariate prediction skill. The predictability of *Pseudo-nitzschia spp*. had distinctive cycles with peaks every 16 and 25 days. An increase in model predictability over autocorrelation was most prominent after a 3-day prediction horizon. The predictability of *Dinophysis spp*. was also higher than inherent autocorrelation after a 6-day prediction horizon. *Dinophysis spp*. had multiple peaks in  $\Delta \rho$  at prediction horizons of 10-20 days, with a distinct peak at 25 days. The RMSE of the predictions also showed a distinct drop around the 25-day mark.



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**Figure 3:** Multivariate prediction skill of the time series of *Pseudo-nitzschia spp.* (left column) and *Dinophysis spp.* (right column) over a prediction horizon of 1-30 days. (a) and (c) report prediction skill ( $\Delta \rho$ ) calculated by subtracting the autocorrelation coefficient at each prediction horizon, (b) and (d) report prediction error as the root-mean-squared-error (RMSE), (e) and (f) report prediction error as the mean-absolute-error (MAE). Model results were calculated from 500 embeddings of phytoplankton abundance and 3 unique image features. The results were reported as an arithmetic mean with 95% confidence intervals ( $\pm 1.96 \times S.E.$ ).

304 Without accounting for autocorrelation, some multivariate models for both Pseudonitzschia spp. and Dinophysis spp. reached prediction skills of 0.70 and greater (Figure 4&5; left). 305 The top 5% of these multivariate models had a fairly uniform distribution of image features, with 306 some clear exceptions. The time series of biovolume and orientation prominently appeared in the 307 top multivariate models for Pseudo-nitzschia spp., whereas the time series of solidity and hflip 308 were present but in a distinctly lower frequency compared to the other features. For Dinophysis 309 *spp.*, the time series of biovolume, texture gray and orientation were prominently present in the 310 top multivariate models. 311

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**Figure 4:** Multivariate prediction skill of the time series of *Pseudo-nitzschia spp.* ( $\rho$ ; left) over a prediction horizon of 1-30 days. Prediction skill ( $\rho$ ) refers to the Pearson correlation coefficient between model predictions and actual observations. Model results were calculated from 1000 embeddings of phytoplankton abundance and 3 unique image features. Each point is the outcome of a single model run. Frequency of image features (right) summarizes the top 5% of model outcomes and the image features included in these models.



Figure 5: Multivariate prediction skill of the time series of *Dinophysis spp.* ( $\rho$ ; left) over a prediction horizon of 1-30 days. Prediction skill ( $\rho$ ) refers to the Pearson correlation coefficient between model predictions and actual observations. Model results were calculated from 1000 embeddings of phytoplankton abundance and 3 unique image features. Each point is the outcome of a single model run. Frequency of image features (right) summarizes the top 5% of model outcomes and the image features included in these models.

Environmental influence on the populations of *Pseudo-nitzschia spp.* and *Dinophysis spp.*, as measured by the cross-map prediction skill ( $\rho$ ), showed variable effects across different prediction horizons. For *Pseudo-nitzschia spp.*, the prediction skill of all the environmental parameters converged with increasing library size. The strength and timescales of inferred causal influence differed across the variables. The influence of chlorophyll on *Pseudo-nitzschia spp.* had a peak at timescales around 28 days, whereas the influence of tidal height was strongest around 2

- 337 weeks. The time series of water temperature, pH, wind speed, and salinity showed significant and
- 338 consistent effects on the *Pseudo-nitzschia spp*. time series across most sub-monthly timescales.



Figure 6: Influence of environmental drivers on *Pseudo-nitzschia spp.* in Narragansett Bay quantified by the cross-map prediction skill ( $\rho$  based on convergent cross mapping; see Methods). The influence was measured over a prediction horizon of 1-30 days (black line). Red points indicate which models showed convergence. The dashed line refers to the Pearson correlation coefficient between the time series of *Pseudo-nitzschia spp.* abundance and the environmental variable.

For *Dinophysis spp.*, there were more models that showed convergence across all prediction horizons. The time series of *Dinophysis spp.* was consistently affected by tide height, water temperature, and pH across all timescales. Total biomass (chlorophyll) appeared as a significant driver of *Dinophysis spp.* with peaks around 5, 14 and 27 days. The effects of salinity were consistent and stronger in the short-term (1-3 days). Predictability was higher than the Pearson correlation coefficient for most environmental variables and showed consistency, which might suggest specific mechanisms of causal influence.



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Figure 7: Influence of environmental drivers on *Dinophysis spp.* in Narragansett Bay quantified by the cross-map prediction skill ( $\rho$  based on convergent cross mapping; see Methods). The influence was measured over a prediction horizon of 1-30 days (black line). Red points indicate which models showed convergence. The dashed line refers to the Pearson correlation coefficient between the time series of *Dinophysis spp.* abundance and the environmental variable.

#### 362 Discussion

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#### Predictability of Pseudo-nitzschia spp. and Dinophysis spp.

Perturbations in phytoplankton population dynamics typically decorrelate within 364 timescales of a month (Kuhn et al. 2019). When we tested for the inherent autocorrelation within 365 366 the time series of both Pseudo-nitzschia spp. and Dinophysis spp., we found that the autocorrelation decreased significantly within the first 10 days for Pseudo-nitzschia spp., but 367 *Dinophysis spp.* had higher autocorrelation for up to 30 days. After accounting for autocorrelation, 368 369 the univariate predictability of both Pseudo-nitzschia spp. and Dinophysis spp. was low overall; however, the univariate predictability of *Pseudo-nitzschia spp.* showed some cyclical behavior. 370 Our univariate models likely picked up on repetitive population-level mechanisms that increased 371 or decreased abundance on sub-monthly timescales. Some examples of such mechanisms could 372 include regular switching between periods of growth and sexual reproduction (D'Alelio et al. 373 374 2009; Annunziata et al. 2022), density-dependent interactions with parasitic protists (Berdjeb et al. 2018), or the tidal transport of productive populations from nearby sites (Shanks et al. 2014). 375 Part of the lack of univariate predictability could be due to the presence of measurement error and 376 377 stochasticity in the time series of both taxa, as well as a general lack of natural predictability for larger diatoms and dinoflagellates (Agarwal et al. 2021). 378

In the multivariate case, we found the predictability of both *Pseudo-nitzschia spp.* and *Dinophysis spp.* improved on timescales of greater than 1 week. Multiview embeddings have been previously shown to improve the univariate predictability of short time series (Ye and Sugihara 2016). By leveraging information stored across multiple related image features, our approach of randomly creating non-lagged embeddings could have allowed us to create better and more reliable estimates of predictive dynamics (Ma et al. 2018). The cyclical predictability of *Pseudo-nitzschia*  *spp.* was more prominent in the multivariate models, implicating predictable behavior on 16-day and 25-day timescales. *Dinophysis spp.* was most predictable on timescales of 25 days. Due to the presence of distinct timescales of predictability for both taxa, our results suggest that future development of HAB models would benefit by resolving dynamics on daily and weekly timescales. The identification of relevant ecological and environmental drivers of population dynamics on these timescales might also aid in the development of automated monitoring and early-warning systems.

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#### Relative contribution of IFCB image features

When we evaluated the relative proportions of image features among the top multivariate 394 models, the time series of biovolume was prominently present for Pseudo-nitzschia spp. and 395 Dinophysis spp. This implies that the time series of biovolume adds considerable information to 396 397 the future predictability of harmful algal taxa. Biovolume estimates from IFCB images (Moberg and Sosik 2012) are often used as an important marker of phytoplankton community structure and 398 function (Brosnahan et al. 2015; Oliver et al. 2021). Although image-derived biovolume estimates 399 400 might differ from microscopy-derived estimates (Kraft et al. 2021), cell biovolume typically varies linearly with other phytoplankton functional traits (Edwards et al. 2012). Our results suggest that 401 including biovolume estimates and other high-performing image descriptors into models for 402 403 harmful algal taxa improves predictability beyond autocorrelation.

Image descriptors derived from flow cytometers have found utility in studies of phytoplankton morphology (Sonnet et al. 2022), as well as for the training of different image classifiers (Mosleh et al. 2012; Zheng et al. 2017). In general, "features" from an IFCB image are

all calculated from the pixels of the image and the relationships between them (see Table 2). As 407 most features share the fundamental quantity underlying their calculations (i.e. the image itself), 408 409 we expect all time series to be nonlinear approximations of one another. The relatively consistent proportions of most features in the top multivariate models indicate that the use of features 410 themselves, and not necessarily their "character", increases the predictability of harmful algal taxa. 411 412 Unless there is a particular reason to prefer one feature for another (such as biovolume for its relationship to other traits), prediction models relying on automated imaging systems would 413 benefit from using any associated image data. Detailed information on the causal relationships 414 between image features for *Pseudo-nitzschia spp.*, as well as the partial correlations between each 415 image feature and our time series of image concentration, can be found in the Supplemental 416 417 material.

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419

#### Potential environmental drivers

To further investigate the timescales of prediction for both *Pseudo-nitzschia spp.* and 420 Dinophysis spp., we evaluated any inferred causal relationships between environmental drivers 421 422 and the proxy abundance of each taxon. Consistent causal influence on either taxon would show variable but significant, effects across sub-monthly timescales. We found that both Pseudo-423 nitzschia spp. and Dinophysis spp. are affected by water temperatures, wind speed, tidal height, 424 425 salinity, pH, and total biomass (chlorophyll). Previous studies across various regions, have hypothesized correlative relationships between harmful algal blooms and these environmental 426 drivers (Almandoz et al. 2007; Sildever et al. 2019; Zhang et al. 2020; Lima et al. 2022). In our 427 study, convergent model predictions with increasing library size and prediction skills that greatly 428 exceeded the Pearson correlation coefficients between the individual time series indicate that there 429

are causal relationships beyond simple covariance. None of the environmental drivers we tested 430 overlapped with the previously quantified multivariate timescales. This implies that the dynamics 431 432 of both taxa in Narragansett Bay are subject to multiple context-dependent forces that interact with each other. Successful prediction models for Pseudo-nitzschia spp. and Dinophysis spp. would 433 need to incorporate the specific local conditions under which the harmful algal blooms develop. 434 435 An ideal prediction model would attempt to combine data from relevant image properties and environmental drivers for particular timescales of prediction. Different model combinations could 436 be optimized for forecasting at certain points during the 30-day prediction horizon. Table S3 437 explores the outcomes of some illustrative combined models for both *Pseudo-nitzschia spp.* and 438 Dinophysis spp. with a prediction horizon of 5, 10 and 15 days. Our results also indicate that there 439 440 can be lags between an environmental driver and the driven harmful algal taxa. Future studies that attempt to predict the dynamics of *Pseudo-nitzschia spp.* and *Dinophysis spp.* might need to 441 characterize the causal timescales of their predictors. 442

443 As there has been rapid deployment of automated imaging systems for the early detection of harmful algal bloom events (Campbell et al. 2010, 2013), our results suggest that there is 444 potential to use such data sources in advanced prediction models. Monitoring programs that 445 concurrently deploy other environmental and biogeochemical sensors might be able characterize 446 the relevant timescales of dynamics, and consequently, predict the magnitude and spatial 447 distribution of harmful algal events across broader regions. Although this study focuses on the 448 population dynamics of the harmful algal bloom-causing taxa, our prediction models could also 449 be coupled with other broad-scale ecosystem models to potentially include the impacts on higher 450 451 trophic levels and human health.

#### Study limitations and future directions

Although we have demonstrated the potential of using automated cell imaging data in 454 prediction models, there are several considerations involved that merit further discussion. First, as 455 our sampling location is fixed, the influence of different water masses and a lack of spatial 456 information can limit real-time projections of HAB abundance across entire regions. Future studies 457 should consider the concurrent deployment of multiple different systems to accurately map and 458 forecast spatial population patterns. Second, as *Pseudo-nitzschia spp.* is a chain-forming diatom, 459 the use of image concentration is not a measure of the actual abundance of the taxon within the 460 water column - there can be a variable number of cells within an image. Instead, image 461 concentration is a measure of our ability to detect and identify the taxa. Although detection 462 numbers are high when abundance is typically high (Figure S1), future studies might need to 463 accurately quantify the relationship between the in-situ abundance of chain-forming organisms 464 and their image detection. Third, the deployment and maintenance of IFCB systems may lead to 465 466 some irregularities and gaps within a long-term time series. Despite multiple years of data collection, a large proportion of our daily-scale time series had to be approximated from existing 467 observations. Our approach requires sufficient long-term coverage for the development of 468 prediction models and future studies could evaluate alternative methods of data processing and 469 interpolation of missing observations. Fourth, the development of harmful algal blooms likely 470 depends on a suite of unknown environmental triggers (such as the nutrient regime, ambient light 471 levels, etc.). The identification of specific causal mechanisms would depend on careful 472 experimentation in laboratory studies, where confounding factors can be controlled, and additive 473 474 influence can be disentangled.

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695	Figure Captions

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Figure 1: Time series of 2 harmful algal bloom-forming taxa in Narragansett Bay, Rhode Island 697 (left column) and their associated autocorrelation functions (ACF; right column). Relative 698 abundance is estimated from the number of unique images taken by the IFCB and classified as (a) 699 Pseudo-nitzschia spp. and (c) Dinophysis spp. Autocorrelation decreases with time and varies 700 701 depending on the dynamics of each specific taxon.

702 **Figure 2:** Univariate prediction skill ( $\Delta \rho$ ) of the time series of (a) *Pseudo-nitzschia spp.* and (b) Dinophysis spp. over a prediction horizon of 1-30 days. Model predictions ( $\rho_{model}$ ) were 703 calculated from 200 random libraries of 250 days each and the results were reported as an 704 arithmetic mean with 95% confidence intervals ( $\pm 1.96 \times S.E.$ ).  $\Delta \rho$  was calculated by subtracting 705 706 the autocorrelation coefficient at each prediction horizon.

**Figure 3:** Multivariate prediction skill of the time series of *Pseudo-nitzschia spp.* (left column) and *Dinophysis spp.* (right column) over a prediction horizon of 1-30 days. (a) and (c) report prediction skill ( $\Delta \rho$ ) calculated by subtracting the autocorrelation coefficient at each prediction horizon, (b) and (d) report prediction error as the root-mean-squared-error (RMSE), (e) and (f) report prediction error as the mean-absolute-error (MAE). Model results were calculated from 500 embeddings of phytoplankton abundance and 3 unique image features. The results were reported as an arithmetic mean with 95% confidence intervals (±1.96 × *S.E.*).

Figure 4: Multivariate prediction skill of the time series of *Pseudo-nitzschia spp.* ( $\rho$ ; left) over a prediction horizon of 1-30 days. Prediction skill ( $\rho$ ) refers to the Pearson correlation coefficient between model predictions and actual observations. Model results were calculated from 1000 embeddings of phytoplankton abundance and 3 unique image features. Each point is the outcome of a single model run. Frequency of image features (right) summarizes the top 5% of model outcomes and the image features included in these models.

Figure 5: Multivariate prediction skill of the time series of *Dinophysis spp.* ( $\rho$ ; left) over a prediction horizon of 1-30 days. Prediction skill ( $\rho$ ) refers to the Pearson correlation coefficient between model predictions and actual observations. Model results were calculated from 1000 embeddings of phytoplankton abundance and 3 unique image features. Each point is the outcome of a single model run. Frequency of image features (right) summarizes the top 5% of model outcomes and the image features included in these models.

Figure 6: Influence of environmental drivers on *Pseudo-nitzschia spp.* in Narragansett Bay quantified by the cross-map prediction skill ( $\rho$  based on convergent cross mapping; see Methods). The influence was measured over a prediction horizon of 1-30 days (black line). Red points indicate which models showed convergence. The dashed line refers to the Pearson correlation
coefficient between the time series of *Pseudo-nitzschia spp*. abundance and the environmental
variable.

732	Figure 7: Influence of environmental drivers on <i>Dinophysis spp</i> . in Narragansett Bay quantified
733	by the cross-map prediction skill ( $\rho$ based on convergent cross mapping; see Methods). The
734	influence was measured over a prediction horizon of 1-30 days (black line). Red points indicate
735	which models showed convergence. The dashed line refers to the Pearson correlation coefficient
736	between the time series of <i>Dinophysis spp</i> . abundance and the environmental variable.
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Figure S1: Time series of *Pseudo-nitzschia spp.* in Narragansett Bay, Rhode Island. Top panel: 752 Relative abundance as estimated from the average number of unique images taken by the IFCB 753 and reported as an image concentration. Bottom panel: Weekly cell counts of Pseudo-nitzschia 754 Long-Term conducted at the Narragansett Bay Plankton Time Series 755 spp. (https://web.uri.edu/gso/research/plankton/). 756

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Figure S2: Univariate prediction skill ( $\rho$ ) varies with the choice of embedding dimension and the prediction horizon. Red points indicate the actual model and grey points indicate the autocorrelation coefficient (i.e. constant predictor). The left column shows the results for *Pseudonitzschia spp*. models run with prediction horizons of (a) 1 day (b) 7 days (c) 14 days and (d) 28 days. The right column similarly reports results for *Dinophysis spp*. models run with prediction horizons of (e) 1 day (f) 7 days (g) 14 days and (h) 28 days.

An advanced test for causality is given in [1], where they provide a generalized correlation coefficient, GMC(Y|X), via the Nadaraya-Watson nonparametric Kernel regression

769  $Y = g(X) = \mathbb{E}[Y|X] + \epsilon$ 

770 where g(X) is a non-parametric, unspecified (non-linear) function. Some of the salient features of 771 this methodology are

• It allows us to measure how differences or changes in *X* affect the differences or changes in *Y* in a non-linear way. Nonetheless, this measurement is normalized to be a number between -1 and 1, allowing us to make a comparison between the generalized correlation coefficients of two pairs of time series. Keeping the notation in the original paper, we will write that  $R^*(i, j) = r^*(X_i | X_j)$  is the generalized correlation coefficient of the factor  $X_i$ given the factor  $X_i$ .

- It is not a symmetric measurement. This is obvious from the definition as the conditional 778 expectations satisfy that  $E[Y|X] \neq E[X|Y]$ . Moreover, precisely because of this definition, 779 *GMC* establishes a framework where causality can be analyzed. This becomes particularly 780 important because it allow us to see whether any of the features of our dataset has a direct 781 causality relation to the feature that we want to forecast, which is "number". Furthermore, 782 the author establishes a generalization of Granger-Causality where if  $|R^*(i, j)| < |R^*(j, i)|$ 783 then the data suggests that  $X_i \rightarrow X_j$ . In other words, the factor  $X_i$  is the cause and the factor 784  $X_i$  becomes the effect. 785
- It is a nonlinear, nonparametric method. This means that, contrary to the common Pearson correlation coefficient, two quantities X, Y are independent if and only if GMC(Y|X) =GMC(X|Y) = 0. Also, as with any nonparametric method, we get the advantage of not biasing our estimates by stipulating the form of the relationship between the variables but this comes at a great computational expense, where even in a modest data set as ours it can take a lot of time to compute it.

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To compute the *GMC*, we used the library "generalCorr" in R for all the pairs of factors. The obtained results can be found in Table 1 in the Appendix. It is also important to point out that in this table, the row variable  $x_i$  is the "effect" while the column variable  $x_j$  is the predictor or the "cause." Thus, if we want to see if a variable is a good predictor or "cause" (individually) for the variable "number" then we need to look at the first row.

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Notice that all the factors have a generalized partial correlation between 0.26 and 0.39, in absolute
value, with "number", meaning that they are not good individual predictors for this variable and
there is a very weak causal relationship. To make sure we also computed the (normal) linear partial
correlation coefficients, described in Table 2.

This analysis shows that no individual factor can help us in increasing our predictability and, moreover, since uniformly across the table  $|R^*(number|factor)| < |R^*(factor|number)|$  for any factor, the data suggests that the variable we want to predict is the driver of the whole data set, as expected. However, based on the results of our methodology, we can conclude that there are different subsets of factors which, as a cluster, can actually help us understand better the behavior of the algae.

Finally, let us point out that as expected, almost all of the features are considered to be a function of another factor. This make sense as all the features are measured through a transformation of the information provided from the same picture. The only feature where we do not have a clear

813 dependance or causality is our main response variable "number", making our methodology become

814 more relevant as any improvement in the predictability of the algae becomes of critical importance.

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- 816 References:
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- 818 [1] Vinod, H. D. (2017). Generalized correlation and kernel causality with applications in
- 819 development economics. Communications in Statistics-Simulation and Computation,
- 820 46(6):4513-4534.
- 821

#### Table 1: The matrix of Generalized correlation (for *Pseudo-nitzschia spp.*).

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020	1			1	1	r			r		1	1		1	1	-	1	1	-		
	numbe	area	vol	c.are	c.per	ecc	eq.di	exte	h180	h90	hflip	maj.ax	min.ax	peri	solid	tx.co	tx.gr	tx.en	tx.sm	tx.un	orien
	r			а	im		am	nt						m		ntras	ау	tropy	ooth	if	t
																t					
numbe	1	0.322	0.3	0.312	0.339	0.344	0.351	0.375	0.278	0.277	0.267	0.332	0.38	0.331	0.372	0.381	0.368	0.392	0.355	0.32	-0.33
r																					
area	0.816	1	0.99	0.999	0.994	0.981	0.996	0.984	0.963	0.977	0.941	0.993	0.995	0.989	0.985	0.98	0.974	0.985	0.974	0.951	0.243
vol	0.786	0.99	1	0.986	0.972	0.948	0.976	0.953	0.933	0.948	0.909	0.969	0.975	0.964	0.955	0.949	0.942	0.955	0.942	0.92	0.139
c.area	0.817	0.999	0.985	1	0.996	0.982	0.996	0.984	0.967	0.977	0.949	0.994	0.995	0.993	0.985	0.983	0.976	0.986	0.977	0.954	0.283
c.perim	0.833	0.995	0.975	0.996	1	0.995	0.999	0.993	0.974	0.986	0.956	0.999	0.997	0.997	0.995	0.993	0.988	0.996	0.988	0.973	0.345
ecc	0.843	0.983	0.956	0.985	0.995	1	0.993	0.994	0.97	0.99	0.951	0.996	0.989	0.993	0.995	0.996	0.991	0.997	0.99	0.974	0.348
eq.dia	0.832	0.997	0.979	0.997	0.999	0.994	1	0.994	0.972	0.984	0.951	0.998	0.998	0.995	0.996	0.993	0.987	0.995	0.987	0.97	0.335
m																					
extent	0.84	0.986	0.965	0.985	0.993	0.994	0.994	1	0.965	0.981	0.943	0.993	0.992	0.987	0.997	0.992	0.987	0.995	0.985	0.97	0.243
h180	0.819	0.954	0.939	0.961	0.966	0.961	0.963	0.952	1	0.947	0.963	0.963	0.961	0.967	0.957	0.959	0.954	0.963	0.953	0.933	0.227
h90	0.837	0.973	0.948	0.974	0.982	0.988	0.979	0.978	0.952	1	0.929	0.988	0.971	0.978	0.977	0.976	0.97	0.977	0.97	0.96	0.311
hflip	0.769	0.933	0.914	0.942	0.945	0.94	0.94	0.93	0.961	0.922	1	0.941	0.939	0.949	0.93	0.945	0.937	0.944	0.942	0.929	0.347
maj.ax	0.836	0.994	0.973	0.995	0.999	0.996	0.998	0.994	0.972	0.991	0.952	1	0.995	0.996	0.995	0.993	0.987	0.995	0.987	0.972	0.344
min.ax	0.827	0.996	0.981	0.996	0.997	0.989	0.998	0.992	0.971	0.976	0.951	0.995	1	0.993	0.994	0.99	0.985	0.993	0.985	0.968	0.324
perim	0.83	0.989	0.964	0.993	0.997	0.992	0.994	0.988	0.971	0.981	0.957	0.995	0.991	1	0.988	0.991	0.985	0.992	0.985	0.973	0.391
solid	0.841	0.988	0.967	0.987	0.996	0.996	0.996	0.998	0.969	0.982	0.947	0.995	0.995	0.99	1	0.995	0.99	0.998	0.989	0.972	0.305
tx.cont	0.835	0.982	0.956	0.984	0.993	0.995	0.992	0.991	0.967	0.98	0.953	0.992	0.99	0.991	0.993	1	0.989	0.997	0.998	0.968	0.364
rast																					
tx.gray	0.811	0.978	0.956	0.979	0.988	0.989	0.987	0.987	0.967	0.974	0.951	0.987	0.985	0.986	0.989	0.99	1	0.989	0.985	0.972	0.348
tx.entr	0.841	0.986	0.961	0.987	0.996	0.997	0.995	0.995	0.971	0.981	0.951	0.995	0.993	0.992	0.997	0.997	0.989	1	0.993	0.964	0.333
ору																					
tx.smo	0.827	0.973	0.945	0.976	0.984	0.987	0.983	0.982	0.956	0.971	0.947	0.983	0.98	0.983	0.984	0.998	0.982	0.99	1	0.957	0.382
oth																					
tx.unif	0.77	0.96	0.944	0.961	0.969	0.97	0.969	0.969	0.951	0.963	0.94	0.968	0.967	0.968	0.97	0.964	0.971	0.963	0.955	1	0.175
orient	0	0.726	0.109	0.74	0.739	0.36	0.753	0.754	0.11	0.31	0.73	0.75	0.55	0.429	0.172	0.753	0.732	0.326	0.721	0.105	1

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829 Table 2: The vector of (linear) partial correlation between all the predictors and the variable "number".

number	area	vol	c.are	c.peri	ecc	eq.di	exten	h180	h90	hflip	maj.ax	min.ax	peri	solid	tx.co	tx.gra	tx.en	tx.sm	tx.uni	orien
			а	m		am	t						m		ntras	У	tropy	ooth	f	t
															t					
1	-0.05	0.09	0.09	0.04	-0.01	-0.22	0.03	0.07	0.07	-0.17	0.10	0.20	0.13	0.25	-0.33	0.08	0.07	0.33	0.05	0.22

Table 3: Outcomes of multivariate models where both image features and environmental variables are combined (i.e. E = 4 with 2 image-based and 2 environmental predictors). 100 random combinations were tested for each prediction horizon (5,10 and 15 days) and the models with the highest 

 $\Delta \rho$  are reported below. 

Taxa	Time to prediction (days)	Predictor 1	Predictor 2	Predictor 3	Predictor 4	ρ	$\Delta oldsymbol{ ho}$
Pseudo- nitzschia spp.	5	eq.diam	ecc	water temperature	salinity	0.74	0.32
Pseudo- nitzschia spp.	10	eq.diam	extent	chlorophyll	water temperature	0.80	0.67
Pseudo- nitzschia spp.	15	solidity	c.perim	pН	water temperature	0.74	0.66
Dinophysis spp.	5	h90	tx.unif	water temperature	salinity	0.76	0.15
Dinophysis spp.	10	area	tx.gray	pH	water temperature	0.80	0.37
Dinophysis spp.	15	tx.unif	extent	рН	water temperature	0.79	0.42