

An automatic classification and robust segmentation procedure of spatial objects

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On page 332 there is a mistake in the formula in the middle of the page.
The wrong version is:

$$F = \langle x_u, x_v \rangle = 1 + \left(\frac{\partial z}{\partial E_i} \right) \left(\frac{\partial z}{\partial N_i} \right)$$

The correct version is:

$$F = \langle x_u, x_v \rangle = \left(\frac{\partial z}{\partial E_i} \right) \left(\frac{\partial z}{\partial N_i} \right)$$

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<http://dx.doi.org/10.1007/s10260-006-0033-5>.

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