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Preface

Assalamu'alaikum, Wr. Wb.

The International Conference on Theoretical and Applied Physics (ICTAP) is a conference organized by Physical Society of Indonesia (PSI) and hosted by Universitas Mataram, Universitas Hamzanwadi, Universitas Pendidikan Mandalika, Universitas Muhammadiyah Mataram, Universitas Islam Negeri Mataram, Sekolah Tinggi Keguruan dan Ilmu Pendidikan Taman Siswa Bima, Sekolah Tinggi Keguruan dan Ilmu Pendidikan Bima, and Universitas Samawa. It is an annual conference of the Society and moves from one major city to another, started ten years back in Bandung (Capital city of West Java province), then consecutively moved to Palangkaraya (Central Kalimantan, 2012), Malang (East Java, 2013), Denpasar (Bali, 2014), Kendari (South-East Sulawesi, 2015), Makassar (South Sulawesi, 2016), Yogyakarta (2017), Medan (2018), and Bandar Lampung (2019). The 10th ICTAP held by virtual conference from Lombok, which is one of the Beautiful Island in Indonesia, on 20-22 November 2020.

International Conference on Theoretical and Applied Physics (ICTAP) has offered a platform for bringing together students, postdocs, academics, and industrial experts to exchange their ideas and contributing an integrative approach to research in theoretical and applied physics. The program of the conference consisted of oral invited lectures of the leading experts on selected topics. The international seminar with the theme "Physics Science Research and Learning Facing Challenges in the Industrial Revolution 4.0 Era" is expected to provide great benefits for developing physics research in the future's challenging 4.0 era. It is aimed at promoting, developing, and disseminating interdisciplinary research from many different fields of physics.

Every submitted paper was reviewed using a single-blind-reviewed process. Note that their authors' articles presented in these Proceedings have been considerably modified after discussion during presentations or in the review process. Furthermore, let me express my appreciation and gratitude to the committee and the entire international conference committee on theoretical and applied physics (ICTAP), who have prepared this conference. ICTAP 2020 was attended by 10 Keynote Speakers, 115 participants, and 10 invited speakers, representing 40 institutions or higher education institutions.

Finally, I would like to thank all presenters and participants in the 10th ICTAP 2020 with the hope that it will provide great motivation for us, especially those who are always involved in theoretical and applied physics research, physics education research, and learning and the application of physics in our lives.

Wassalamu'alaikum, Wr. Wb.

Thank you,
The 10th ICTAP 2020 Chairman
Assoc. Prof. Drs. Aris Doyan, M.Si., Ph.D.



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Cervical single cell of *squamous intraepithelial lesion* classification using shape features and extreme learning machine

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Abstract. Cervical cancer is an abnormal growth of cells found on the cervix. In general, cervical cancer is identified early by doing a pap smear test. However, this examination is still manually performed by doctors and the results are still subjective. Therefore, this study aims to determine the classification of Squamous Intraepithelial Lesion automatically from cervical single cells. The classification of those Squamous Intraepithelial Lesion includes normal cervical cells, Low-Grade Squamous Intraepithelial Lesion (LSIL), and High-Grade Squamous Intraepithelial Lesion (HSIL). We used Extreme Learning Machine (ELM) as a classifier and tried to compare the ELM's performances with Backpropagation Neural Network method. We used 225 data and 3 classes include normal, LSIL, and HSIL. The classification was carried out by manual cropping and segmentation as the image pre-processing and the feature extraction was based on shape features consisting of Circularity, Semi Major and Minor Axis Length, Equivalent Diameter, Average Radius, and Compactness. This study concluded that Squamous Intraepithelial Lesion classification by using ELM had better performances than Backpropagation Neural Network. The highest accuracy result of 96.67% was obtained in Backpropagation training, while the highest accuracy in ELM's training was 100% when both methods were tried by using 225 data.

1. Introduction

Cancer is a disease that arises from the abnormal growth of body tissue cells that turn into cancer cells. From several types of cancer, cervical cancer ranks fourth in incidence after breast cancer in developing countries [1]. Cervical cancer is generally caused by the Human Papilloma Virus (HPV) where this virus causes changes in cell DNA. This causes cell growth to occur continuously so that early detection is necessary. In addition, the cause of delay in the diagnosis of cervical cancer is a symptom that is not visible and only obvious when it is in its final stage. To detect cervical cancer,



generally, an early examination or pap smear can be done. Pap smear is very important in reducing the incidence of cervical cancer [2]. This examination requires medical personnel to get an accurate diagnosis. However, medical personnel still analyse the result visually, so the results are subjective. Therefore it is necessary to have an automatic analysis in carrying out the process of diagnosing cervical cancer as a second opinion for doctors, so that it is expected that an accurate diagnosis of cervical cancer cells can be established.

Research on the identification of cervical cancer cells has been carried out in previous studies using SVM, k-NN and ANN to identify normal and abnormal cells. The feature extraction method used is the Gray Level Cooccurrence Matrix (GLCM). The accuracy results of this study are 86% with SVM, 70% with KNN, and 65% with ANN. Subsequent research used morphological feature extraction and image classification using the k-nearest neighbor (kNN) method, this study generated the accuracy of 82.9% with 5 Fold Cross validation [3]. Another research employed the random forest method and resulted in 81.71% of accuracy. To identify cells and feature extraction, the study used the Gray Level Cooccurrence Matrix, local binary pattern and tamura [4]. Subsequent research used the multilayer perceptron method to identify normal and abnormal cells. This study uses the extraction method of morphological features such as size, shape and texture with an accuracy of 85.05% [5]. Another research employed the fuzzy min-max neural network classification method to classify normal cells, low-grade squamous intra-epithelial lesions (LSIL) and high-grade squamous intra-epithelial lesions (HSIL) while the feature extraction method used is adaptive fuzzy. moving k-means (AFMKM). The level of accuracy obtained in this study is 75% [6].

We used the Extreme Learning Machine (ELM) method and compared the result with the *Backpropagation*, that is the commonly used image classification method. The ELM has the advantage of being able to work optimally even on complex functions with linear and non-linear data [7]. ELM has a good learning ability in generating image classification with accurate results. In this study, the ELM method was used for image classification of Squamous Intraepithelial Lesions automatically from cervical single cells.

2. Method

2.1 Datasets

Cervical cancer Pap smear image data were obtained from Dr. Soetomo General Hospital. The data taken is an image of Squamous Intraepithelial Lesion consisting of Normal class, LSIL (Low-Grade SIL), HSIL (High-Grade SIL) with jpg format. A total of 225 cervical cancer Pap smear image data were used. Training process used 180 data and 45 data for the testing process.

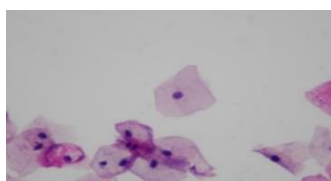


Figure 1. Normal Pap Smear Image

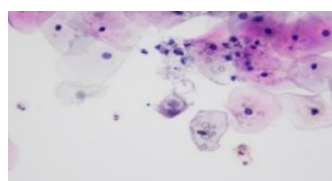


Figure 2. LSIL (Low Grade Squamous Intraepithelial Lesion) Pap Smear Image

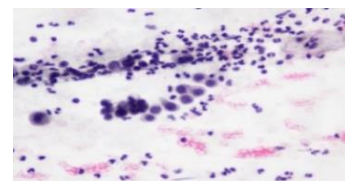


Figure 3. HSIL (High-Grade Squamous Intraepithelial Lesion) Pap Smear Image

2.2 Feature Extraction

The shape features to be extracted are: Circularity, Semi Major and Minor Axis Length, Equivalent Diameter, Average Radius, Compactness. Cervical cancer cells have a similar shape. However, abnormal cervical cancer cells have a shape that is larger and more irregular than normal cells. At the feature extraction stage, there are 8 parameter calculations in the nucleus and cytoplasm shown in Table 1:

Table 1. Feature Shape [8]

Feature Shape	
<i>Semi minor-Axis length</i>	$b =$ shortest distance between nuclei centroid and boundary
<i>Semi major-Axis length</i>	$a =$ longest distance between nuclei centroid and boundary
<i>Average Radius</i>	$Avr =$ average distance between nuclei centroid and boundary
<i>Eccentricity</i>	$c = \sqrt{a^2 - b^2}$; $e = c / a$
<i>Equivalent Diameter</i>	$ED = \frac{4 \times Area}{\pi}$
<i>Perimeter</i>	$P =$ sum of pixels in nuclei boundary
<i>Circularity</i>	$C = \frac{4 \times Area}{P^2}$
<i>Compactness</i>	$Cp = P^2 / Area$

2.3 ELM Classification

Extreme Learning Machine (ELM) is a supervised algorithm in the Artificial Neural Network group which is a type of single hidden layer feedforward network (SFLN). The ELM algorithm was introduced by Huang et al. in 2006. ELM can perform the process of generalizing data in a relatively short time compared to the Support Vector Machine algorithm and the Backpropagation algorithm [9].

The ELM method has a different mathematical model from the feedforward neural network. The mathematical model of ELM is simpler and more effective. For N different number of input pairs and output targets (x_i, t_i) , with $x_i = [x_{i1}, x_{i2}, \dots, x_{in}]^T \in \mathbf{R}^n$ and $t_i = [t_{i1}, t_{i2}, \dots, t_{im}]^T \in \mathbf{R}^m$, SLFNs standard with the number of hidden nodes as much as \tilde{N} and the activation function $g(x)$ can be modelled mathematically as follows [10]:

$$\sum_{i=1}^{\tilde{N}} \beta_i g_i(x_j) = \sum_{i=1}^{\tilde{N}} \beta_i g_i(w_i \cdot x_j + b_i) = o_j, j = 1, 2, \dots, N \quad (2.5)$$

with

$w_i = [w_{i1}, w_{i2}, \dots]^T$ is a weight vector connecting the i th hidden node and the input nodes.

$\beta_i = [\beta_{i1}, \beta_{i2}, \dots]^T$ is a weight vector connecting the i th hidden node and the output nodes.

b_i is *threshold* from *hidden node* to- i .

$w_i \cdot x_j$ is *inner product* from w_i and x_j

Standard SLFNs with \tilde{N} hidden nodes and the activation function $g(x)$ are assumed to be able to estimate N of this sample with an error rate of 0 which means $\sum_{j=1}^N \|o_j - t_j\| = 0$, so there is β_i, w_i , dan b_i such that:

$$\sum_{i=1}^{\tilde{N}} \beta_i g_i(w_i \cdot x_j + b_i) = t_j, j = 1, 2, \dots, N \quad (2.6)$$

The equation above can be written simply as:

$$H\beta = T \quad (2.7)$$

with

$$H = \begin{bmatrix} g(w_1 \cdot x_1 + b_1) & \dots & g(w_{\tilde{N}} \cdot x_1 + b_{\tilde{N}}) \\ \vdots & \vdots & \vdots \\ g(w_1 \cdot x_N + b_1) & \dots & g(w_{\tilde{N}} \cdot x_N + b_{\tilde{N}}) \end{bmatrix} \quad (2.8)$$

$$\beta = \begin{bmatrix} \beta_1^T \\ \vdots \\ \beta_N^T \end{bmatrix} \tag{2.9}$$

$$T = \begin{bmatrix} t_1^T \\ \vdots \\ t_N^T \end{bmatrix} \tag{2.10}$$

H in the equation (2.8) is the hidden layer output matrix of the neural network. $g(wi. xj + bi)$ shows the output of hidden neurons related to the input xj . β is the matrix of the output weight and T the matrix of the target. In ELM, the input weight and hidden bias are determined randomly, so that the output weight associated with the hidden layer can be determined from the equation:

$$\beta = H^\dagger T \tag{2.11}$$

The structure of the ELM that can be observed is as shown in Figure 4:

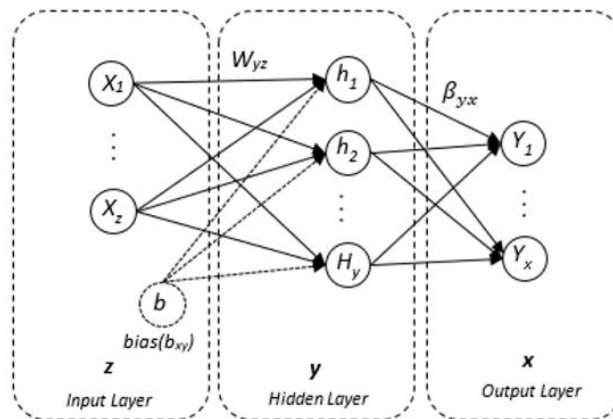


Figure 4. Extreme Learning Machine Structure [11]

Data normalization is carried out so that the range between data is not too far away so that when the data is processed, accurate results will be obtained.

3. Result and Discussion

3.1 Segmentation

Prior to the extraction of shape features, manual segmentation was carried out through cropping. In one field of view there are several cells, so cropping is done to make some data where there are several cells that are indicated of the same type. The dimensions of the cropping result are 431 x 432 pixels shown in Figure 5.

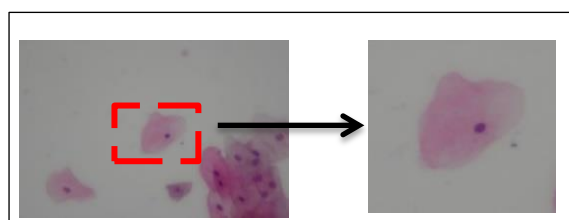


Figure 5. Before and after cropping

The resulting image from manual segmentation in the form of RGB is converted into a ycbcr image. This is done to differentiate between the nucleus and cytoplasmic images so that they can be selected and circled in the nucleus and cytoplasm by using the regionprops toolbox. After that the program can calculate 8 parameters from the shape of the cytoplasmic cells and the shape of the nucleus cells. Then the results of the average value for calculation of parameter calculations can be seen in Figure 6 and Figure 7.

3.2 Future Extraction

Feature extraction is the stage of taking important characters (features) in cells after the image segmentation process. In this study, using shape features consisting of 8 parameters of the shape features. Among others, namely: Circularity, Semi Major and Minor Axis Length, Equivalent Diameter, Average Radius, Compactness.

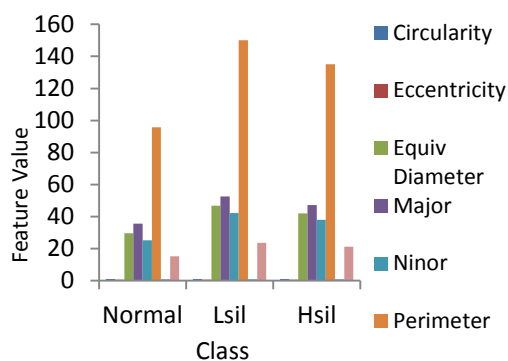


Figure 6. Shape feature extraction average in nuclei

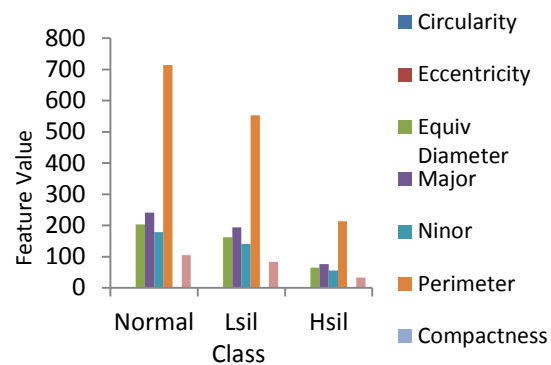


Figure 7. Shape feature extraction average in cytoplasm

The results of segmentation and feature extraction on the image show the difference between normal epithelial cells and abnormal epithelial cells in size and shape. Figure 7 depicted in the graph shows that the average value of normal epithelial cells (nuclei) and abnormal epithelial cells has a similar shape. Nor in the regularity of its form. The graph of each parameter increases, this proves that in normal nucleus cells the size and shape is smaller than the size and shape of abnormal nucleus cells. So, it can be concluded from the extraction results that the higher the abnormal class the nucleus, the bigger the shape and size of the nucleus. Abnormal epithelial cells have a more irregular shape than normal epithelial cells. On the other hand, in cytoplasmic cells, the more abnormal cervical cells are, the smaller their shape and size, or even until they are not visible as shown in Figure 8, the graph of each parameter shows a decrease, this proves that the size and shape of the cytoplasm is getting smaller than that. normal cells to hsil class.

3.3 Training and Testing Process

In this study, k-fold cross validation was used as a method of dividing data into k sub-data, namely 5-fold cross validation It can be seen that the results shown in Table 2 of ELM have an accuracy of 100% on fold 1 with a training time of 6 seconds. Backpropagation has accuracy of 96.67% with 12 seconds of Training Time.

As for the results of the ELM testing process, it is known that the accuracy of ELM is done by doing 5-Fold Cross Validation in order to get a pretty good validation accuracy and the validation results are obtained at 95%. Meanwhile, based on Table 2, the backpropagation training stage is the result of program testing for normal images, LSIL, and HSIL. The highest accuracy at the testing stage is in the 4th fold, which is 93.89%. It can be seen that ELM and backpropagation neural networks are

able to distinguish pap smear images in normal, LSIL, and HSIL classes by using shape feature extraction.

Table 2. ELM and Backpropagation Training Process Result

Fold-n	ELM			Backpropagation		
	Accuracy of Training (%)	Training Time(s)	Accuracy of Testing (%)	Accuracy of Training (%)	Training Time(s)	Accuracy of Testing (%)
1	100	6	95	92.22	9	92.22
2	90	0	84	93.89	9	93.33
3	88	0	88	95.56	9	93.33
4	87	1	77	95.56	9	93.89
5	91.6	0	80	96.67	12	86.67

4. Conclusion

The classification of Squamous Intraepithelial Lesions using ELM has a better performance than Backpropagation Neural Network. The result of ELM training time is 6 seconds and Backpropagation for 12 seconds. It can be seen that the ELM computation is faster so that the running time of the program during training and testing does not last long. It is also known that the highest accuracy results of 96.67% were obtained in Backpropagation training, while the highest accuracy in ELM training was 100% when both methods were tried using 225 data.

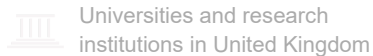
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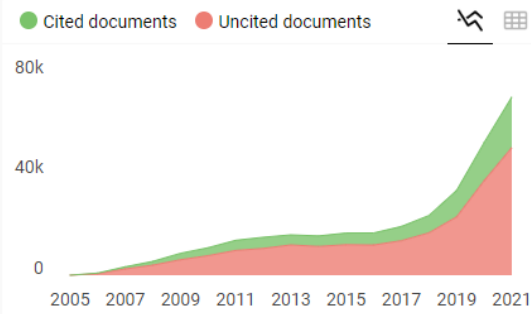
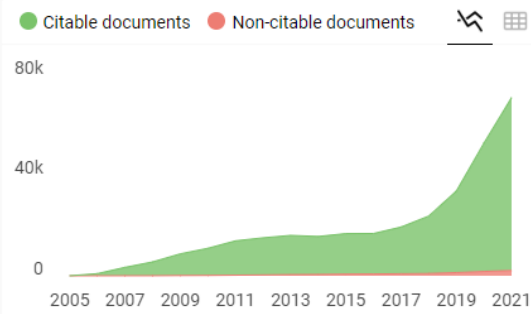
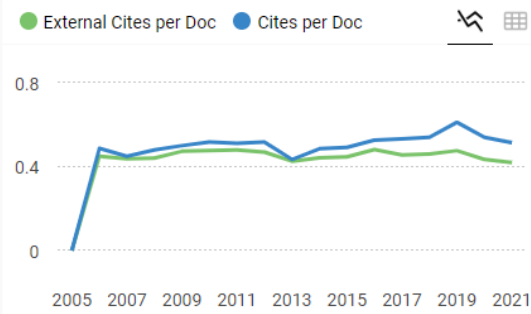
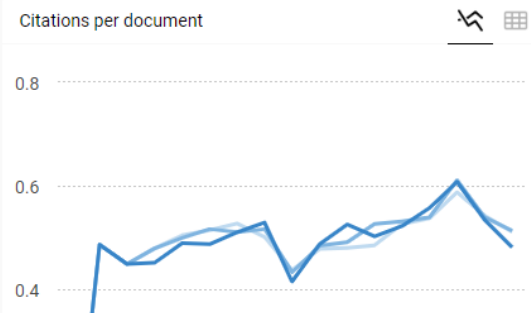
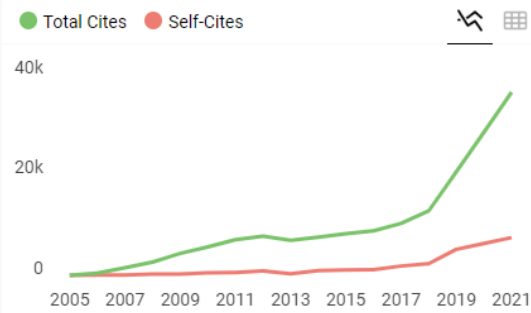
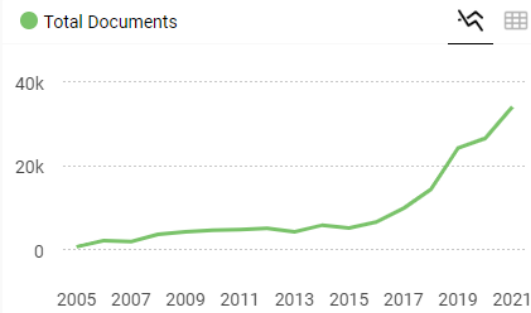
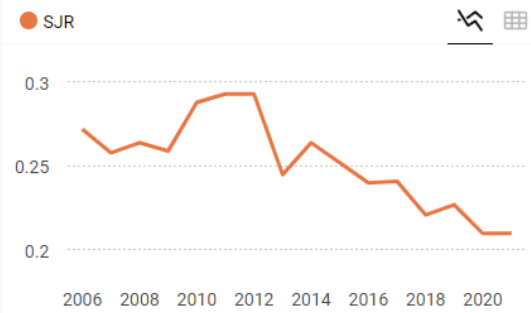
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