

1 Brazilian savannah trees as bio-inspiration for hydraulic transient control in
2 a penstock of a small hydropower plant

3 **ABSTRACT**

4 This study proposes an innovation, which is to use a non-circular and bio-inspired forced conduit (a new
5 penstock with a cross section inspired by a tree trunk), to control the effects of hydraulic transients in
6 Brazilian Small Hydropower Plants (SHPs). The aim is to demonstrate that natural structures, adapted to
7 periodic environmental disturbances, are better at hydraulic transient control than traditional conduits.
8 The proposed methodology includes the following steps: (1) problem identification; (2) potential
9 biological model identification; (3) development of alternatives; (4) implementation and testing; and (5)
10 solution selection. This research was conducted at the São Tadeu I SHP, in the city of Santo Antônio de
11 Leverger/MT, Brazil. The following tree biological models from the Brazilian savannah (Cerrado) were
12 used: the *Handroanthus capitatus* and *Strychnos pseudoquina* species. The proposed innovation improves
13 the conduit of the traditional circular section and the relief valve solution of the criteria studied. The
14 reason for this improvement was the reduction of wave speed in the non-circular section (from 1,126 to
15 583 m s⁻¹).

16

17

18 *Keywords:* Biotechnology; Cerrado; pipeline; tree trunk; tube geometry; wave speed reduction

19

21 **1. Introduction**

22 In the global electricity matrix, hydroelectric power accounts for 16.1% of the total, while in the
23 case of Brazil, hydroelectric power contributes 56.8% (EPE, 2022). An analysis of the
24 hydroelectric generation potential of the Brazilian park estimates a potential of 176 GW (EPE,
25 2020). The estimate includes Large Hydropower Plants (LHPs) and Small Hydropower Plants
26 (SHPs, up to 30 MW), considering inventory studies completed and approved by the Brazilian
27 Electric Energy Agency (ANEEL). The estimated potential may be greater than the availability
28 of restricted water resources due to socio-environmental interference (e.g., national parks,
29 indigenous reserves, quilombo areas, environmental protection areas, and others). Most of the
30 Brazilian hydropower potential to explore is concentrated in the North and Central-West
31 regions, highlighting the fact that most of the major inventoried projects are concentrated in the
32 hydrographic regions of the Amazonia and Tocantins-Araguaia (EPE, 2020). In the Central-
33 West region, Mato Grosso (MT) State has presented an increasing consumption of electric
34 energy, by 5% per year, from 2007 to 2017. Over the specified period, the region witnessed a
35 notable surge in energy production, registering a remarkable 194% increase, equivalent to an
36 average annual growth rate of 6% (NIEPE, 2019). In alignment with this trajectory of growth, it
37 has been forecast that the expansion will encompass the addition of two more hydropower
38 plants and the establishment of 17 additional small hydropower plants. (AGER, 2021).

39 According to AGER (2021), concerning the generation units under construction, inspection
40 activities suggest efforts by entrepreneurs to comply with the works schedule approved by
41 ANEEL. These efforts include various aspects such as energy commercialisation, plant
42 integration into the distribution network, establishing transmission facilities, securing financing
43 for the enterprise, and other considerations. For operating power plants, different aspects can be
44 cited, namely: plant performance (technical and operational conditions), dam safety, and
45 significant incidents (safety conditions). Supervised actions have revealed instances of non-
46 compliance and inadequate maintenance of goods and installations, as well as obstruction of
47 hydraulic structures, such as the upper storage basin and pressure relief valve chamber in the
48 city of Brasnorte, MT, and the tunnel in the city of Santo Antônio de Leverger, MT, observed
49 during hydraulic transient performance tests (AGER, 2010; AGER, 2012; Guidicini et al.,
50 2022). The resulting revenue is also in agreement with these points, as EPE (2019) mentions
51 that over time, there have been many losses of hydroelectric plants that have affected the
52 generation performance. Consequently, reducing its efficiency and exacerbating unavailability
53 rates, until the point where deterioration reaches an irrecoverable stage, definitively interrupting

54 the energy supply. The reversal of this trend can be achieved by the actions of repowering and
55 modernising the generation units (EPE, 2019).

56 Requirements for modernisation and innovation in hydraulic transients is a topic that gives rise
57 to problems in hydroelectric plants in MT. Some advances in this research area include the
58 following: Anderson and Johnson (1990) studied the propagation speed of pressure waves and
59 their relationship with Young's modulus in blood vessel walls. The findings suggest that even
60 minor ovalisation in the tube can lead to significant decreases in both wave propagation speeds
61 and Young's modulus. Bending-induced changes in a cross-section shape with internal pressure
62 increased the apparent elasticity of the tube wall (Anderson and Johnson, 1990). Another study
63 focused on the research efforts of a new method to identify the presence of stiffness weakness
64 along a pipe (Hachem and Schleiss, 2012). Wave speed and wave attenuation factors during
65 transients are considered global indicators of local changes. The method was able to locate the
66 stiffness weakness along the test tube and the error in position estimation varied up to 23%
67 (Hachem and Schleiss, 2012). Aiming to achieve the ideal design of tunnels and compensation
68 tanks at the Marun hydroelectric plant (a large hydroelectric dam in operation located in
69 southwestern Iran), Fathi-Moghadam et al. (2013) developed hydraulic transient simulations
70 linked to an optimisation technique. The emergency operating condition (maximum oscillation
71 pressure) was studied. A genetic algorithm optimisation technique was used to select the
72 optimal diameter for the inlet tunnel, penstocks, and surge tanks. The results revealed
73 considerable savings in construction costs. Aiming to contribute to safety aspects of the
74 Montbovon hydroelectric plant installation (located in Fribourg, Switzerland), Alligné et al.
75 (2019) modeled hydraulic transient events in the interruption of discharge in the event of a pipe
76 rupture (gate protection valve equipped with downstream air valve). The results showed that the
77 pipe rupture simulation should consider: (1) the cavitation model in the gate protection valve;
78 (2) the separation of the water column in the gate; and (3) air intake through air valves located
79 downstream of the valve to obtain realistic results. In another study, the insertion of circular
80 tubes into a pipeline with water hammer occurrences was tested (Kubrak and Kodura, 2020). In
81 the research, three types of circular tubes — a thin-walled tube, a thick-walled tube, and a solid
82 cylindrical tube — were evaluated. According to Kubrak and Kodura (2020), the results showed
83 that by inserting a tube with a low modulus of elasticity can have a damping effect on the water
84 hammer phenomenon, that is, it reduces the speed of the pressure wave and the maximum
85 increase in water pressure.

86

87 In this context, there are opportunities for actions aimed at improving operation and
88 maintenance (O&M) processes, adaptive management, and innovation focusing on pressure
89 wave propagation speed. This study proposes an innovation, the use of a non-circular and bio-

90 inspired forced conduit section, to control the effects of hydraulic transients in a Brazilian Small
91 Hydropower Plant (SHP). The main aim is to show that natural fluid support and transport
92 structures, adapted to periodic environmental disturbances (burning and tipping) are better at
93 hydraulic transient control than traditional conduits.

94

96 **2. Theoretical background**

97 This study does not aim to delve deeply into the fundamental subject matter of this research
98 area. Instead, it provides concise presentations of the themes and suggests literature for those
99 interested in further exploration of this field.

100

101 2.1. Biomimetics and bio-inspiration

102 Natural selection serves as a mechanism through which nature has processed, refined, and
103 enhanced elements of the biological foundation over millions of years. Researchers can learn
104 from these evolutionary refinements and use them intending to create new improvements in
105 technology, thus this interdisciplinary synergy is the field of Biomimetics (Meyers et al., 2008).

106

107 According to Iouguina et al. (2014), the fields of biomimetics and bio-inspiration encompass a
108 broad range of objectives and contexts. However, they are differentiated by their focus:
109 biomimetics emphasises mechanical capacities, while bio-inspiration serves as an inclusive term
110 encompassing bionics and biomimicry fields. Definitions of biomimetics include Schmitt, who
111 officially coined the term biomimetics, a derivative of the Greek words bios (life) and mimesis
112 (imitate). Another definition was given by Bar-Cohen which mentions that it represents the
113 study and the imitation of the methods of the nature, projects and processes (Iouguina et al.,
114 2014). These fields have shown promising results regarding energy systems. A study, which
115 was inspired by insect wings to develop aeolian turbine archetypes, initiated turbine designs
116 35% more efficient than the conventional turbines (Cognet et al., 2017). In another study, the
117 characteristics of the existing wave energy converters were analysed using biomimetics ideas in
118 order to obtain hidden rules for improved designs (Zhang and Aggidis, 2018). More recently,
119 efforts have been made to identify valuable biological entities, or cases of bionic design, which
120 can inspire new wave energy converters (Zhang et al., 2022).

121

122 In general, the practical aspects of biomimetics can be accomplished by two approaches,
123 solution-based and problem-driven (Fayemi et al., 2017). The solution-based approach describes
124 the process of the biomimetic development for which the knowledge about biological systems
125 are the kick-starters to a new technical project. On the other hand, the problem-driven approach
126 is a biomimetic development process that determines a practical problem, in which an identified
127 problem is the starting point for the process (Fayemi et al., 2017). The approaches can be further

128 explored by interested researchers consulting the works of Vincent et al. (2006), Meyers et al.
129 (2008), Iouguina et al. (2014), Fayemi et al. (2017), Ulhøi (2021), Wommer and Wanieck
130 (2022) and Gebeshuber (2022).

131

132 2.2. Natural structures of support and transport of fluids

133 Plant stems naturally serve as structures for sustaining and fluid conduits. The stems establish
134 the connection between the roots and leaves, responsible for supporting the plant and carrying
135 water and mineral salt from the roots to the leaves, as well as carrying the sugars (produced in
136 the photo syntheses) from leaves to the roots (Meyers et al., 2008). Considering the basic idea of
137 this research and the fact that the biome of interest is the Brazilian tropical savannah (Cerrado),
138 it is essential to present some main characteristics. The Cerrado is characterised by having two
139 well-defined seasons: dry and rainy. The severe climatic conditions of the Brazilian Savannah
140 (Cerrado), which has frequent wildfires and water stress (periods of waterlogged soils and dry
141 periods), have directed the evolution of its flora (Sartorelli and Campos Filho, 2017). The
142 twisted appearance of its trees and bushes is a consequence of the occurrence of fire, and the
143 thick bark of the trunks acts as a defence mechanism for the trees against fire (MMA, 2007;
144 Simon and Pennington, 2012). Regarding this, plants have improved the ability to store water,
145 nutrients and sprout after fire and collapse, which gives the biome high resilience (Sartorelli and
146 Campos Filho, 2017). Tree species included low heights varying from 6 m to 8 m, thick corky
147 bark, mostly blackened by fire, and root sprouting (Borges et al., 2014; Simon and Pennington,
148 2012). Covering more than 20% of Brazilian territory, the Brazilian savannah (Cerrado) is not
149 as famous as the Amazon Forest, but it is also rich in biodiversity (Alencar et al., 2020). For
150 example, photographic registers of Brazilian savanna biome samples (before and after the forest
151 fire) are shown in Fig. 1.

152 Given the harsh environmental conditions of the Brazilian savannah, there is an expectation that
153 its improvement could inspire the development of technologies capable of meeting similarly
154 challenging requirements. There remains ample room for exploration regarding the Brazilian
155 savannah, and those interested are encouraged to consult the works of MMA (2007), Simon and
156 Pennington (2012), Borges et al. (2014), IBRAM (2016), Sartorelli and Campos Filho (2017),
157 Sano et al. (2019), Alencar et al. (2020), Gomes et al., (2020), Silva et al., (2021).

158

159 2.3. Basic transient equation

160 The equation that relates the increase in pressure caused by disturbances (a sudden change of
161 speed) in the flow of forced conduits can be derived by the movement's equation in a volume of
162 a pipe section where the outflow change occurs (Tullis, 1989). Equation 1 presents the relation

163 between the pressure increase and speed disturbance, often referred to as Joukowsky's law
164 (Stephenson, 1989).

$$165 \quad \Delta H = \frac{-a\Delta V}{g} \quad (1)$$

166 Where: ΔH is the head rise; a is the wave speed; ΔV is the reduction in flow velocity; and $g =$
167 9.81 m s^{-2} is the acceleration due to gravity.

168

169 The a is a parameter that must be precisely evaluated for each system. This value depends on
170 the density and the volumetric module of the liquid, elasticity, diameter and the thickness of the
171 pipe is the wall and the presence of air or free gas (Tullis, 1989). The calculation of a is derived
172 from the application of (1) the equation of continuity, (2) Joukowsky's law, (3) relation between
173 ΔH and liquid's bulk modulus (4) expansion of the pipe due to its tension-deformation
174 properties (Tullis, 1989). Taking into account the expansion of the pipeline's length and
175 diameter, as well as the fluid compression and its mathematical treatment, results in Eq 2.

$$176 \quad \frac{g\Delta H}{a^2} = \frac{\Delta A}{A} + \frac{\Delta\rho}{\rho} \quad (2)$$

177 Where: ΔA is the increase of the pipe cross-section area; A is the pipe cross-section area; $\Delta\rho$ is
178 the increase of mass density; and ρ is the fluid's mass density.

179

180 According to Tullis (1989), the aim is to express the wave speed as a function of fluid and pipe
181 properties which are readily obtainable. Then, inserting the bulk modulus of the liquid and the
182 static pressure into Eq. 2 leads to Eq. 3. The term $(CK\Delta A)/(A\Delta p)$ is derived by the tension
183 deformation pipe properties.

$$184 \quad a^2 = \frac{K/\rho}{1 + (CK\Delta A)/(A\Delta p)} \quad (3)$$

185 Where: K is the bulk modulus of the liquid; C is the effect of pipe constraint; and Δp is the
186 pressure increase.

187

188 To solve hydraulic transient problems, the Method of Characteristics is the most commonly
189 used (Larock et al., 2000). The transient flow analysis is based on the equations of the amount
190 of movement and continuity, as expressed by the derived partial Eqs 4 and 5. Eqs 4 and 5 were
191 simplified by comparing the relative magnitudes of the various terms and eliminating those of
192 lesser importance. More details are available in Tullis (1989).

193
$$g \frac{\partial H}{\partial x} + \frac{\partial V}{\partial t} + \frac{fV|V|}{2D} = 0 \quad (4)$$

194
$$\frac{\partial H}{\partial t} + \frac{a^2}{g} \frac{\partial V}{\partial x} = 0 \quad (5)$$

195 Where: x is the longitudinal coordinate; f is the friction coefficient; V is the average fluid speed;
196 D is the internal pipe diameter; and t is the time.

197

198 The mathematical treatment of Eqs 4 and 5 considering simplifications is solved by the Finite
199 Difference Method that results in Eqs 6, 7, ..., 11.

200
$$C^+ : H_{P,I} = C_P - BQ_{P,I} \quad (6)$$

201
$$C^- : H_{P,I} = C_M + BQ_{P,I} \quad (7)$$

202
$$C_P = H_{I-1} + BQ_{I-1} - RQ_{I-1}|Q_{I-1}| \quad (8)$$

203
$$C_M = H_{I+1} - BQ_{I+1} + RQ_{I+1}|Q_{I+1}| \quad (9)$$

204
$$B = \frac{a}{gA} \quad (10)$$

205
$$R = \frac{f\Delta x}{2gDA^2} \quad (11)$$

206 Where: $H_{P,I}$ and H_I are piezometric heads in node I, in the present and past time, respectively;
207 $Q_{P,I}$ and Q_I are the flow on node I, in the present and past time, respectively; and Δx is the
208 distance between nodes.

209

210 Complementary information about the basic equations of the hydraulic transient can be found in
211 Wylie and Streeter (1978), Watters (1979), Tullis (1989), Stephenson (1989), and Larock et al.,
212 (2000).

213

214 2.4. Boundary conditions

215 Afterwards, some boundary conditions of common small hydropower plants are briefly
216 presented, such as reservoir, surge tank, sudden cross-section changes, turbine, butterfly valve
217 and relief valve (Pejovic et al., 1987; Brekke, 2014).

218

219 In the boundary condition of the reservoir (node 1), which is considered to have a large storage
 220 capacity, the water level does not change during the transient and the head will remain constant
 221 $H_{P,I} = H_{R,I}$ = piezometric head at reservoir. Flow $Q_{P,I}$ will be calculated by Eq. 7 (Tullis, 1989).

222

223 Some reduction of costs can be obtained when the surge tank has a diameter smaller than the
 224 main pipe and some discharge is allowed. In these cases, Eqs 12, 13, ..., 20 represent the
 225 boundary conditions (Tullis, 1989).

$$226 \quad H_{P,NT} = 0.5 \left(-C_7 \pm \sqrt{C_7^2 - 4C_8} \right) \quad (12)$$

$$227 \quad C_1 = X_{LT} + \frac{\Delta t}{2A_t} \left[\frac{(C_P + C_M)}{B} + Q_T \right] \quad (13)$$

$$228 \quad C_2 = \frac{\Delta t}{(BA_t)} \quad (14)$$

$$229 \quad C_3 = g\Delta t A_{TA} \quad (15)$$

$$230 \quad C_4 = \frac{(C_P + C_M)}{B} - Q_T \quad (16)$$

$$231 \quad C_5 = \frac{C_1}{C_3} \quad (17)$$

$$232 \quad C_6 = \frac{C_2}{C_3} \quad (18)$$

$$233 \quad C_7 = \frac{-B \left(C_4 C_6 + 2 \frac{C_5}{B} + C_2 + 1 \right)}{(2C_6)} \quad (19)$$

$$234 \quad C_8 = \frac{B(C_4 C_5 + Z_{NT} + C_1)}{2C_6} \quad (20)$$

235 Where: $H_{P,NT}$ is the piezometric head on the surge tank; X_{LPT} and X_{LT} represent the water level on
 236 the surge tank, in the present and past time; Δt is the time step; A_{TA} is the cross-section area of
 237 the surge tank; Q_T is the flow on the surge tank; Z_{NT} is the topographic elevation of the surge
 238 tank. The term $Q_{P,NT}$ can be determined by Eq. 6. Complementary equations are necessary and
 239 more details are available in Tullis (1989).

240

241 The cross-section changes in a hydraulic system might cause a located head loss. In this case,
 242 one variable is known, the located head loss coefficient (K_l); three variables are unknown flow
 243 ($Q_{P,NL}$), piezometric head loss upstream ($H_{P,NL}$); piezometric head loss downstream (H_{PD}). The
 244 Eqs are 21, 22, ..., 25. Complementary material can be found in the work of Tullis (1989).

$$245 \quad H_{P,NL} - H_{PD} = C_8 Q_{P,NL}^2 \quad (21)$$

$$246 \quad C_8 = \pm \frac{K_l}{(2gA^2)} \quad (22)$$

$$247 \quad Q_{P,NL} = 0.5 \left(-C_9 \pm \sqrt{C_9^2 - 4C_{10}} \right) \quad (23)$$

$$248 \quad C_9 = \frac{2B}{C_8} \quad (24)$$

$$249 \quad C_{10} = \frac{(C_M - C_P)}{C_8} \quad (25)$$

250 For the turbine, there is a speed increase in the rotor as rotation and pressure are caused by the
 251 disturbance in the flow and there is a direct relation with the performance curves of the turbine
 252 (hill chart) and the controlling equipment of flow to the turbines (servomotor pistons). In this
 253 paper, the hydraulic condition studied is power failure during turbine operation with the rapid
 254 closure of the control valve. In this condition, the unit suddenly rejects the load during start-up
 255 (failure to start) or during steady-state operation (e.g. a short circuit of the transmission line).
 256 This is a normal operating condition, expected and executed as planned (Pejovic et al., 1987).
 257 The servomotor has its function guided by parameters as servomotor dead time, T_q ; minimum
 258 closure time from the fully open position, T_f ; cushioning time, T_h ; and, total closure time, T_z
 259 (Fig. 2). According to Pejovic et al. (1987) and Brekke (2014), usual values of these parameters
 260 include:

- 261 • T_q : 0.3 until 0.7 s;
- 262 • T_f : 4 until 6 s;
- 263 • T_h : 4 until 6 s;
- 264 • Position of transition of the piston of the servomotor (y_h) : 0.1 until 0.2.

265

266 Brekke (2014), presents a procedure to calculate the increase pressure, when the turbine
 267 characteristics are known and the boundary condition can be resumed: (1) activation of the
 268 servomotor; (2) variation in the angular speed of the rotor; (3) change of outflow in the turbine;
 269 (4) pressure rise, as shown in Eq. 6. Representing these boundary conditions results in Eqs 26,

270 27, ..., 30. More details about turbine boundary conditions can be found in Wylie and Streeter
 271 (1978), Pejovic et al. (1987) and Brekke (2014).

$$272 \quad H_{P,TU} = C_P - BQ_{P,TU} \quad (26)$$

$$273 \quad H_{P,TU} = H_{TU} (\alpha^2 + \upsilon^2) (A_0 + A_1 x) \quad (27)$$

$$274 \quad T = T_R (\alpha^2 + \upsilon^2) (A_0 + A_1 x) \quad (28)$$

$$275 \quad \frac{T}{T_R} - \frac{P_G}{\alpha} \frac{C_{SI}}{T_R \omega_R} = \frac{\omega_R}{T_R} \frac{WR^2}{g} \frac{d\alpha}{dt} \quad (29)$$

$$276 \quad T_f T_\alpha \frac{d^2 y}{dt^2} + T_\alpha' \frac{dy}{dt} + \sigma(y-1) + \alpha - 1 + T_d \frac{d\alpha}{dt} = 0 \quad (30)$$

277 Where: $H_{P,TU}$ is the piezometric head on the turbine, in present time; $Q_{P,TU}$ is the flow on the
 278 turbine, in present time; HP_{TU} is the piezometric head on the turbine, in present time; H_{TU} is the
 279 piezometric head on the turbine, in past time; α is the speed ratio, dimensionless; υ is the
 280 velocity ratio, dimensionless; A_0 , A_1 , B_0 and B_1 are coefficients that depend upon the zone of
 281 operation; $x = \tan^{-1}(\upsilon/\alpha)$; T is the instantaneous torque on the turbine; T_R is the rated torque on
 282 the turbine; P_G is the power absorbed by the generator; C_{SI} is a conversion constant used in SI;
 283 ω_R is the velocity angular of the turbine; WR^2/g is the polar moment of inertia of the rotating
 284 parts; T_α is the ratio of the change in speed deviation to the change in relative servo velocity,
 285 dimensionless; y is the piston servomotor position, dimensionless; σ is the real part of complex
 286 valued frequency, dimensionless.

287

288 For a butterfly valve at the end of the pipe, the boundary condition is the equation for head loss
 289 across the valve (Tullis, 1989). After the butterfly valve is completely closed, its boundary
 290 condition is similar to that of a dead-end pipe. For the valve fully close its boundary condition is
 291 similar to dead-end pipe. At the closed position ($Q_{P,BV} = 0$), the piezometric head ($H_{P,BV}$) is
 292 found from Eq. 6 or 7 (Tullis, 1989).

293

294 The relief valve acts to control the limiting pressure values, preventing the exceeding of a
 295 pressure value of interest (set point pressure). The boundary includes Eqs 23, 31, 32 and 33,
 296 according to Tullis (1989). Complementary equations and relief valve technical data (e.g.,
 297 discard coefficients, opening time, closing time) are necessary to fully understand this boundary
 298 condition. More information can be found in Wylie and Streeter (1978) and Tullis (1989).

$$299 \quad H_{P,NV} = C_P - BQ_{P,NV} \quad (31)$$

300
$$H_{P,NV} = C_M + BQ_{PD} \quad (32)$$

301
$$Q_{P,NV} = Q_{PV} + Q_{PD} \quad (33)$$

302 Where: HP_{NV} is the piezometric head on the relief valve; $Q_{P,NV}$ is the upstream flow of the relief
303 valve; Q_{PD} is the downstream flow of the relief valve; and Q_{PV} is the flow on the relief valve
304 discharge. The term Q_{PV} can be found according to the characteristics of its relief valve
305 (engineering data) and the piezometric head upstream and downstream of the valve.

306

307 2.5. Choosing a protection device

308 The hydraulic transient effects and the choice of the protection device will depend on the
309 physical and hydraulic characteristics of the hydropower plant layout. A table showing a
310 summary for choosing the protection device was proposed by Stephenson (1989). In any case
311 regarding choosing the protection device, the main objective is to prevent serious damage to the
312 installations. In general, it is desirable that the permissible maximum pressure is not exceeded in
313 order to prevent damage or rupture; and, that the minimum pressure does not reach levels of
314 cavitation, separation of the water column, as well as the potential event of buckling (Ramos,
315 2000). In agreement, Pejovic et al. (1987) mentions that there should be no vacuum in the tunnel
316 or in the forced conduit in any period of time. If necessary, a protection condition can include
317 one or several of the devices: (1) surge tanks; (2) relief valves; (3) governors; (4) deceleration of
318 wicket gate closure; (5) air chambers; (6) bleeding in air; (7) non-circular conduit; (8) flexible
319 hose; (9) check valves; (10) flow-control valves; (11) surge suppressors (Wylie and Streeter,
320 1978; Pejovic et al., 1987). In this case, the protection device alternative that ensures the
321 minimum pressure load amplitude and the minimum occurrence of vacuum can be considered as
322 the best option.

323

324

325 3. Study area

326 In this paper, the São Tadeu I Small Hydropower Plant (SHP), located in the municipality of
327 Santo Antônio de Leverger, Mato Grosso State (MT), Brazil was adopted as a research case
328 study. Figure 3 shows the location and the general layout of São Tadeu I SHP. Technical
329 information can be found below according to (ANEEL, 2009):

- 330 • Nominal Power: 9.278 MW
- 331 • Number of turbines, type: 2, Horizontal Francis
- 332 • Nominal head: 200 m
- 333 • Nominal discharge: $5.47 \text{ m}^3 \text{ s}^{-1}$
- 334 • Nominal speed: 900 rpm
- 335 • Tunnel - length, base, arch: 2,460 m, 4.5 m, 5.0 m
- 336 • Penstock - length, diameter: 128 m, 1.75 m
- 337 • Surge tank - high, diameter: 162 m, 2.6 m.

338

339 As a justification for choosing the area, the following points can be considered: lack of
340 information to help further studies and development of hydropower plant projects in MT,
341 Brazil; the presence of typical SHP elements, which can be considered a valid representative of
342 the SHP resource of MT, Brazil (ANEEL, 2009); occurrence of a structural problem related to
343 the hydraulic transient, hydraulic rupture of the adduction tunnel during the pressurisation test
344 (Assis, 2009; Guidicini et al., 2022).

345

346 The occurrence of hydraulic disruption in the adduction tunnel (that is, the load of chamber
347 pressure of the tunnel that exceeded the resistance of the surrounding rocky bulk) during the
348 pressurisation test generated ousting, in few hours, of all the volume of water that filled the
349 tunnel (Assis, 2009; Guidicini et al., 2022). This caused serious damage to civil works and the
350 equipment itself, delaying the start-up of the project by more than a year (Guidicini et al., 2022).
351 Among the recovery measures implemented are: determining the extent of the new shielding;
352 developing structural designs of the support bases and anchoring blocks of the new conduit; the
353 hydraulic analysis of the forced conduit; and others (Guidicini et al., 2022). Moreover, the
354 recurrence of leakage in the forced conduit expansion joint, observed during technical
355 inspections, may be related to difficulties of the adductor system in dealing with hydraulic

356 transients (AGER, 2013; AGER, 2017). Naturally, there is a need for studies to evaluate this
357 relationship.

358

359 The hydraulic rupture of the adduction tunnel and the presence of leakage in the expansion joint
360 associated with the desire to improve operation and maintenance (O&M) processes were
361 motivating factors for this research.

362

363

364 **4. Methodology**

365 Based on the idea of solving a practical problem (effects of hydraulic transient in a hydropower
366 plant adduction system), the problem-driven approach was adopted, according to Fayemi et al.
367 (2017). The proposed methodology includes the following steps: (1) problem identification; (2)
368 potential biological model identification; (3) development of alternatives; (4) implementation
369 and testing; and (5) solution selection.

370

371 4.1. Problem identification

372 To identify the problem, bibliographic research on technical information was carried out and
373 difficulties in operation and maintenance (O&M) processes in the study area were detected.
374 Special attention was given to the hydraulic transient subject and conditions of extreme
375 requirements of the adductor system. Furthermore, hydraulic simulations were used, such as the
376 Visual Basic for Applications (VBA) programming environment, hosted in MS Excel software.
377 The Method of Characteristics and the studies conducted by Wylie and Streeter (1978), Pejovic
378 et al. (1987), Tullis (1989), Larock et al., (2000) and Brekke (2014) were used.

379

380 4.2. Potential biological model identification

381 According to Fayemi et al. (2017), to identify the potential biological model, a question about
382 nature must be formulated to explore its progress in a given function. To formulate the question
383 two points are important, the first is nature and the second is function. Considering nature and
384 the biome in which the study area is inserted, nature can be represented by the Brazilian
385 savannah (Cerrado). Considering the function, the history of O&M difficulties in the study area,
386 and the routine of hydraulic transients wear down the tunnel, the penstock, and connections,
387 leading them to work inefficiently (AGER, 2013; AGER, 2017; Guidicini et al., 2022). Thus,
388 the function of interest is the adaptation to recurrent physical disturbance in fluid conductors.
389 Therefore, a question was formulated: in open pastures, which fluid conductor would be better
390 adapted to this recurrent physical disturbance? A simple answer to the question would be a
391 Brazilian savannah tree trunk, known to be adapted to extreme environmental conditions such
392 as felling, fire and water stress (Sartorelli and Campos Filho, 2017). To provide a precise
393 answer to the question, significant effort in research is essential. Activities such as defining
394 performance criteria to identifying the most effective conductor and conducting tests using a
395 representative sample of plants are crucial. Two tree species were studied: *Handroanthus*

396 *capitatus* (popular name is Ipê Amarelo) and *Strychnos pseudoquina* (popular name is Quina do
397 Cerrado), as shown in Figs 1c and 1d. They were chosen due to the frequent occurrence in the
398 Brazilian savannah and because these trunk trees are the potential biological model (Borges et
399 al., 2014; Sartorelli and Campos Filho, 2017).

400

401 4.3. Development of alternatives

402 To develop alternatives, two approaches were adopted: the innovative approach and the
403 traditional approach. For the innovative approach, the method used was the non-circular conduit
404 to control the hydraulic transient and reduce the propagation speed of a pressure wave (Wylie
405 and Streeter, 1978). Integrating this method with the natural fluid conduit (tree trunk), adapted
406 to recurrent physical disturbances (fluctuating flood and drought conditions, occurrence of
407 wildfires), leads to the alternative of replacing the traditional circular cross-section with a non-
408 circular tree trunk cross-section. These trees have highly irregular trunks and can withstand
409 significant changes in water flow. When in hydraulic transient, penstocks in hydroelectric plants
410 also face extreme conditions (changes in water flow and pressure). This similarity is the main
411 reason for choosing the highly irregular section alternative. The choice of quadrant prioritised
412 the irregularity of the quadrant. For the sake of illustration, the development of alternatives is
413 shown in Fig. 4.

414

415 For the traditional approach, the alternative relief valve was chosen, aligning with
416 recommendations in the literature for the study area (Wylie and Streeter, 1978; Pejovic et al.,
417 1987; Tullis, 1989; and Stephenson, 1989). The relief valve simulation was based on the
418 following points: in the installation at the midpoint between the tunnel forced conduction
419 transition and the butterfly valve; presence of a central adjustment device with control functions,
420 function 1 (reaction time, $t_R = 0$ s), function 2 (opening time, $t_O = 2$ s), function 3 (closing time,
421 $t_C = 15$ s); maximum allowable pressure equal to the pressure in the permanent flow plus 5%;
422 and the globe valve discharge coefficient presented by Tullis (1989). The values of t_R , t_a and t_C
423 were defined with an iterative trial and error process. Information techniques on the relief valve
424 used for the simulation can be found in Bermad (2020).

425

426 4.4. Implementation and testing

427 Regarding implementation and testing, it was based on the understanding that the
428 implementation is the simulation of replacing the traditional circular cross-section forced
429 conduit with another non-circular cross-section conduit of equal area. Pressure propagation

430 velocity (a) estimates were performed considering Eq. 3 and the calculation of ΔA for the non-
 431 circular section, according to research by Jenkner (1971), Wylie and Streeter (1978), Watters
 432 (1979) and Tullis (1989). The term ΔA was defined as the sum of the increase in the
 433 infinitesimal areas, as shown in Fig. 5 and Eqs 34, 35, 36 and 37.

$$434 \quad \frac{\Delta A}{A\Delta p} = \frac{1}{eEA} \left(2 \sum_{i=1}^n \sum_{j=1}^2 d_{i,j}^2 D_{i,j} + \frac{1}{60e^2} \sum_{i=1}^n \sum_{j=1}^2 D_{i,j}^5 \right) \quad (34)$$

$$435 \quad \Delta D_{i,j} = \frac{\Delta p}{eE} d_{i,j} D_{i,j} \quad (35)$$

$$436 \quad d_{i,j} = 0.5(b_{i,j} + B_{i,j}) \quad (36)$$

$$437 \quad \Delta d_{i,j} = d_{i,j}^2 \frac{\Delta p}{eE} \quad (37)$$

438 Where: i is a subscript that represents the infinitesimal element, $i = 1, 2, \dots, n$; j is a subscript
 439 that represents the part of a non-circular section, $j = 1$ if quadrant is 1 or 2, $j = 2$ if quadrant is 3
 440 or 4; $D_{i,j}$ is the infinitesimal length of wall pipe; $\Delta D_{i,j}$ is the increase in the infinitesimal length of
 441 wall pipe; $d_{i,j}$ is the average height of the infinitesimal element; $\Delta d_{i,j}$ is the increase in the
 442 average height of the element infinitesimal; e is the thickness of the pipe wall; E is the elasticity
 443 modulus; $b_{i,j}$ is the minimum height of infinitesimal element; and $B_{i,j}$ is the maximum height of
 444 the infinitesimal element. Details of the set of equations are available in Appendices A and B.

445

446 To carry out the tests, the estimated value of a was used to simulate the condition of power
 447 failure during turbine operation with the rapid closure of the control valve (load rejection). The
 448 following parameters were adopted for hydraulic simulation: time of minimum closing, $T_f = 5$ s;
 449 time of damping, $T_h = 0$ s; position of transition of the piston of the servomotor, $y_h = 0.16$;
 450 characteristic hill chart curves for the Francis turbine of Brekke (2014) adapted to the ANEEL
 451 (2009). The parameters used as references were from Pejovic et al. (1987), STE (2013) and
 452 Brekke (2014). The hydraulic simulations followed the same procedures used to identify the
 453 problem.

454

455 4.5. Solution selection

456 To choose the solution, the criteria of pressure amplitude (C_{R1}), vacuum incidence (C_{R2}) and
 457 graphical pressure analysis (temporal evolution at points of interest and adductor system
 458 envelope) were used, in alignment with Pejovic et al. (1987) and Cassano et al. (2020). The
 459 selected solution was the alternative that presented minor values of C_{R1} and C_{R2} , as Eqs 38, 39,

460 ..., 41. The interest points are the tunnel near the reservoir (P1); the surge tank (P2); the tunnel-
461 power transition, in the forced conduit (P3); and the butterfly valve (P4).

$$462 \quad C_{R1} = N^{-1} \sum_{I=1}^N (P_{I,t,max} - P_{I,t,min}) \quad (38)$$

$$463 \quad C_{11,I,t} = \begin{cases} 0, & \text{if } H_{P,I,t} \geq Z(i) \\ 1, & \text{if } H_{P,I,t} < Z(i) \end{cases} \quad (39)$$

$$464 \quad C_{12} = \sum_{I=1}^N \sum_{t=0}^{t_{max}} C_{11,I,t} \quad (40)$$

$$465 \quad C_{R2} = 100 \frac{C_{12}}{L} \quad (41)$$

466 Where: C_{R1} is the average pressure amplitude (kPa); I is the node identifier, $I = 1, 2, \dots, N$; $P_{I,t,max}$
467 is the maximum pressure on node I , in time t_S ; $P_{I,t,min}$ is the minimum pressure on node I , in time
468 t_S ; $H_{P,I,t}$ is the piezometric head on node I , in time t ; $C_{11,I,t}$ is the identifier of the incident of the
469 vacuum event on node I , in time t_S ; t_S is the simulation time, $t_S = 0, \Delta t, 2\Delta t, \dots, t_{max}$; C_{12} is the
470 total number of incidences of the vacuum event, in time t_S ; L is the length of the section; C_{R2} is
471 the incident rate of the vacuum event. The t_{max} was defined using the period of oscillation of the
472 chimney balance (T) and in condition $t_{max} \geq T$, according to Eq. 42.

$$473 \quad T = 2\pi \sqrt{L_T A_{TN} / g A_{TN}} \quad (42)$$

474 Where: L_T is the length of the water column (tunnel and tank length); A_{TN} is the tunnel area.

475

476 For criterion C_{R1} , it is required to smooth variations, thus achieving smaller pressure transients
477 and reduced levels of mechanical stress. Therefore, the lowest average pressure amplitude is
478 desired, according to Eq. 38. To evaluate the performance according to criterion C_{R2} , a
479 simplified model of equations that identifies, quantifies, and distributes the occurrence of
480 vacuum events over time was proposed (Eqs 39, 40, and 41). Basically, it was considered that
481 every time the piezometric line cuts the conduit, there is a vacuum event. The number of events
482 was added up and distributed longitudinally and temporally. Naturally, there is room for further
483 development, and more robust models can be created.

484

485 For graphical analysis, the selected solution was the alternative with the highest stationarity
486 (unstable behaviour over time around a constant average) and the lowest amplitude, the option

487 aimed to attenuate the effects of pressure pulses and fatigue, according to Pejovic et al. (1987)
488 and Cassano et al. (2020).
489

490

491 **5. Results**

492 The results of this research are presented below. As the main problems were identified,
493 following bibliographic research and hydraulic simulations, there are important pressure values
494 in the tunnel forced conduction transition, incidence of vacuum events in the tunnel and in the
495 forced conduit. The recurrence of leakage in the expansion joint, which was observed in AGER
496 (2013) and AGER (2017), suggests fatigue due to high pressures and possibly hydraulic
497 transients. The non-zero performance of criterion C_{R2} also suggests possible problems. Both
498 indications need further investigation and adjustment with field data.

499

500 As a result of identifying the potential biological model, the trunk sections of the Ipê Amarelo
501 and Quina do Cerrado tree species are shown in Fig. 6. The visual analysis in Fig. 6 indicates
502 the Third and the Second quadrant as the ones with the highest irregularity, therefore they were
503 selected to develop the alternatives. The current situation of the study area (Reference) and the
504 set of alternatives developed (A1, A2, ..., A7) can be observed in Fig. 7. As an alternative of the
505 innovative approach, they have A1 alternatives, A2, ..., A6. Alternative A7 was chosen from
506 the traditional relief valve approach. In Table 1, descriptive information of the generated
507 alternatives is presented, in Fig. 5. More information about infinitesimal elements of alternatives
508 A1, A2, ..., A6 is available in Appendices A and B.

509

510 As results of the implementation and tests, we have the estimates of a and the performance of
511 criteria (C_{R1} and C_{R2}), according to Table 2. Graphs with information on pressure envelopes and
512 temporal evolution at the points of interest are presented in Figs 8 and 9.

513

514 The non-circular sections generated desirably important gains in the reduction of a , the
515 reduction rate of a that ranged from 36.0 to 38.2%. This reduction was higher than the values
516 found by Anderson and Johnson (1990), a reduction rate from 6.9 to 8.4%. A possible
517 justification is related to the severe non-regularity of the proposed cross-section as opposed to
518 the mild non-regularity tested by Anderson and Johnson (1990). The values of a were estimated,
519 thus there is a requirement for experimental research for proper validation. The observation of
520 C_{R1} for the tunnel indicates A1 (the lowest pressure amplitude, $C_{R1} = 751.9$ kPa) as the best
521 alternative and A7 (the second largest pressure amplitude, $C_{R1} = 795.5$ kPa) showed an
522 improvement compared to the Reference. On the other hand, the observation of C_{R1} for the

523 forced conduit indicated A2 and A4 (lower pressure amplitude, $C_{R1} = 2,016.1$ kPa) as the best
524 alternatives. A7 showed gain in relation to the Reference (pressure amplitude changed, from C_{R1}
525 $= 2,772.6$ to $2,073.2$ kPa). Therefore, the innovative approach overcame the traditional approach
526 to C_{R1} .

527

528 For C_{R2} , in the tunnel, the best alternative was A7 ($C_{R2} = 0.8$ event $100 \text{ m}^{-1} \text{ s}^{-1}$), alternatives A3
529 and A6 presented the worst performances ($C_{R2} = 1.8$ event $100 \text{ m}^{-1} \text{ s}^{-1}$). Moreover, for C_{R2} , the
530 observation of the forced conduit did not indicate vacuum occurrence for alternatives A1, A2,
531 ..., A6. The A7 alternative intensified the vacuum occurrence (of $C_{R2} = 0.04$ for 0.1 event 100
532 $\text{m}^{-1} \text{ s}^{-1}$). Therefore, for the C_{R2} , the innovative and traditional approaches were equivalent. A
533 traditional approach surpassed the innovative approach in the tunnel, but it was inferior in the
534 penstock.

535

536 Regarding the graphical analysis, it can be observed that the innovative approach resulted in the
537 reduction of maximum values and increase in minimum values in the tunnel and in the forced
538 conduit (see Fig. 8: Reference; A1; A2; ...; A6) eliminating the occurrence of vacuum in the
539 forced conduit. The stationarity was noted in the Hmax and Hmin lines, in the tunnel and in the
540 forced conduit (see Fig. 8: A1; A2; ...; A6). In the traditional approach, a reduction in the
541 maximum and minimum values in the tunnel and in the forced conduit was observed (see Fig. 8:
542 A7). The advantage was the reduction of the requirements of maximum pressure of the forced
543 conduit, the disadvantage was the increase in the occurrence of the vacuum also in the forced
544 conduit (see Fig. 8: Reference and A7). In the traditional approach, there is no stationarity in the
545 Hmax and Hmin lines (see Fig. 8: A7).

546

547 The graphical analysis of the temporal evolution of points of interest showed the occurrence of
548 vacuum in P1 in all the alternatives developed. Alternative A7 was the one with the lowest
549 number of vacuum events (see Fig. 9: A1, P1; A2, P1; ...; A7, P1). The observation of the point
550 of interest P2 indicated no influence of alternatives A1, A2, ..., A6 on the pressure. In contrast,
551 alternative A7 influenced the pressure (see Fig. 9: A1, P2; A2, P2; ...; A7, P2). For the point of
552 P3 interest, the A4 alternative indicated minor amplitude of pressure and the A7 alternative the
553 largest amplitude of pressure (see Fig. 9: A1, P3; A2, P3; ...; A7, P3). In none of the alternatives
554 was the occurrence of vacuum in P3 observed. Thus, with regards protecting P3, alternative A4
555 was the best. In a similar way, for the point of P4 interest, alternatives A2 and A4 presented a
556 minimum amplitude of pressure and the A7 alternative maximum amplitude of pressure (see
557 Fig. 9: A1, P4; A2, P4; ...; A7, P4). Only in alternative A7 vacuum was the point of interest P4

558 observed. Alternatives A2 and A4 were selected because they consider protection of the point of
559 interest P4.

560

561 Naturally, the innovative approach prevailed over the Reference, which was the expected result,
562 because reducing a is one of the hydraulic transient control methods. Overall, the innovative
563 approach outperformed the traditional approach in most criteria. The exception was observed
564 when the tunnel protection was desired for the occurrence of vacuum and the protection of the
565 forced conduit for maximum pressure requirements. The alternatives with better performances
566 were A4, A2 and A1, two of these are the cross-section of the unmodified tree trunk. This
567 suggests that the unmodified tree trunk section may overcome modified tree trunk sections and
568 traditional pipe sections, although more studies are required for further proof.

569

570 Despite obtaining good results, some concerns are important for sustaining and continuing
571 efforts in this research area. Currently, ways to reduce a include incorporating plastic tubes in
572 the penstock and inserting circular tubes, according to works by Kubrak and Kodura (2020) and
573 Kubrak et al. (2021). Evaluating the advantages and disadvantages of this innovation compared
574 to existing alternatives is a concern and must be considered. Another aspect concerns the
575 possible loss of additional energy inherent to the innovation when in permanent operation (as it
576 is a non-circular pipe, greater turbulence, greater energy consumption, and greater unit head loss
577 are expected). In other words, there is an expectation of less energy available for generating
578 electrical energy. How important this loss of available energy will be and whether it can be
579 economically sustained over time is relevant and deserves further investigation. At this point,
580 acknowledging the manufacturing and installation costs is mandatory. Thus, is the cost of
581 innovation (manufacturing, installation, and loss of available energy) lower than the O&M cost
582 of conventional piping systems? These are key questions that require definite answers.
583 Biomimetics and bio-inspiration researchers observe that nature, with its continuous evolution,
584 has overcome greater obstacles than these at times. However, a reliable answer can only be
585 derived from robust scientific evidence.

586

587 In an endeavor to facilitate this quest for answers, a comparative analysis was conducted
588 between the load capacity of conventional circular piping and bioinspired non-circular piping.
589 For the load available with the circular piping, São Tadeu I SHP project data were consulted,
590 available in ANEEL (2009). For the load available with the bioinspired non-circular piping, data
591 obtained from the first step (permanent regime, butterfly valve upstream of the turbine
592 completely open) of the simulation of alternative A4 were used. These data were selected

593 because it was the alternative with the best overall performance. The results were as follows: (1)
594 for the circular pipe, the reference liquid head was 200.0 m; (2) for the bioinspired non-circular
595 pipe, the reference liquid head was 198.1 m; (3) 0.95% available energy loss. These results were
596 obtained through simulations and computational modelling, thus there is a requirement for
597 ongoing research in this area and validation through experimental test data and modelling.
598

600 **6. Summary and conclusions**

601 An innovation aimed at improving operation and maintenance (O&M) processes in hydropower
602 plants has been proposed. A set of alternatives utilising non-circular and bio-inspired sections
603 for forced conduit was developed. The biological models used include Brazilian savannah tree
604 species such as *Handroanthus capitatus* (popular name Ipê Amarelo) and *Strychnos*
605 *pseudoquina* (popular name Quina do Cerrado). Simulated hydraulic transient tests in a small
606 hydropower plant indicated that the bio-inspired non-circular section conduit surpasses the
607 traditional circular section conduit and the relief valve solution in most of the studied criteria
608 (pressure amplitude, vacuum occurrence, graphical analysis). The aim was to show that natural
609 fluid support and transport structures, adapted to periodic environmental disturbances (burning
610 and tipping) are better at hydraulic transient control than traditional conduits, confirmed using
611 simulated tests (wave speed reduction ranged from 36.0 to 38.2%).

612

613 For the specific case study, the use of field data for the validation of the simulations would be of
614 great value. In the case of confirming the reference simulation, it is suggested to investigate
615 solutions that will ensure the non-occurrence of vacuum with respect to system pressure
616 variations. Optimising the functions of the central relief valve adjustment device can be a viable
617 way, while another way would be to combine hydraulic transient control methods.

618

619 The recommendations of this research include:

- 620 • A study of reliable ways to estimate wave speed (a) and alignment with experimental
621 results.
- 622 • A study of methods to cancel external supports (anchoring) in pipes with a cross-section
623 of unmodified tree trunks as internal pressures do not cancel out in all directions and
624 senses.
- 625 • Accomplishment of experimental tests in order to contribute to the practical validation
626 of the results found.
- 627 • Tests with other Cerrado species, using other combinations of quadrants, with
628 combinations of conventional solutions, and with combinations between conventional
629 and innovative solutions (for example, relief valves and bioinspired non-circular
630 piping).

- 631
- Using economic criteria (including implementation costs) and multi-criteria methods to
- 632
- select the optimum solution.

633

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637 University Renewable Energy Group and Fluid Machinery Group.

638

639

640 **Appendix A. Calculation of ΔA for the non-circular section**

641

642 Figure A1a shows a unit long non-circular section of pipe of wall thickness e subject to an
 643 increased pressure Δp , the quadrants ($j = 1$ and $j = 2$), infinitesimal element ($i = 1, 2, \dots, n$) and
 644 cross-section length $d_{i,j}$. Due to the axial and diagonal asymmetry, it was assumed that the
 645 deformation could be obtained from an infinitesimal element of rectangular shape under internal
 646 pressure, as shown in Fig. A1b. This rectangular section, when subjected to internal pressure, is
 647 deformed on its smallest side ($D_{i,j}$) according to the approach described in Jenkner (1971). The
 648 smallest side of the infinitesimal element, top for $j = 1$ and bottom for $j = 2$, borders the pipe
 649 wall; the other sides border neighbouring elements. Therefore, it was assumed that surface
 650 deformation occurs basically due to normal forces, as shown in Fig. A1c. The deformation
 651 caused by the normal force and stress, see Fig. A1d, can be estimated based on Jenkner (1971),
 652 Wylie and Streeter (1978) and Tullis (1989), according to Eqs A.1, A.2, ..., A.14.

653
$$\Delta D_{i,j} = \frac{\sigma_N}{E} D_{i,j} \quad (\text{A.1})$$

654
$$\sigma_N = \frac{N}{ed_U} \quad (\text{A.2})$$

655
$$\Delta p = \frac{F}{A_{i,j}} = \frac{F}{d_{i,j}d_U} \quad (\text{A.3})$$

656
$$N - F = 0 \quad (\text{A.4})$$

657
$$N = \Delta p d_{i,j} d_U \quad (\text{A.5})$$

658
$$\sigma_N = \frac{\Delta p d_{i,j}}{e} \quad (\text{A.6})$$

659
$$\Delta D_{i,j} = \frac{\Delta p}{eE} d_{i,j} D_{i,j} \quad (\text{A.7})$$

660
$$\Delta d_{i,j} = d_{i,j} \frac{\Delta D_{i,j}}{D_{i,j}} = d_{i,j}^2 \frac{\Delta p}{eE} \quad (\text{A.8})$$

661
$$\Delta A_N = \sum_{i=1}^n \sum_{j=1}^2 d_{i,j} \Delta D_{i,j} + (D_{i,j} + \Delta D_{i,j}) \Delta d_{i,j} = 2 \frac{\Delta p}{eE} \sum_{i=1}^n \sum_{j=1}^2 d_{i,j}^2 D_{i,j} \quad (\text{A.9})$$

662
$$\frac{\Delta A_N}{A\Delta p} = \frac{2}{eEA} \sum_{i=1}^n \sum_{j=1}^2 d_{i,j}^2 D_{i,j} \quad (\text{A.10})$$

663
$$\Delta A_B = \frac{\Delta p}{60e^3 E} \sum_{i=1}^n \sum_{j=1}^2 D_{i,j}^5 \quad (\text{A.11})$$

664
$$\frac{\Delta A_B}{A\Delta p} = \frac{1}{60e^3 EA} \sum_{i=1}^n \sum_{j=1}^2 D_{i,j}^5 \quad (\text{A.12})$$

665
$$\frac{\Delta A}{A\Delta p} = \frac{\Delta A_N}{A\Delta p} + \frac{\Delta A_B}{A\Delta p} \quad (\text{A.13})$$

666
$$\frac{\Delta A}{A\Delta p} = \frac{1}{eEA} \left(2 \sum_{i=1}^n \sum_{j=1}^2 d_{i,j}^2 D_{i,j} + \frac{1}{60e^2} \sum_{i=1}^n \sum_{j=1}^2 D_{i,j}^5 \right) \quad (\text{A.14})$$

667 Where: i is a subscript that represents the infinitesimal element, $i = 1, 2, \dots, n$; j is a subscript
 668 that represents the part of a non-circular section, $j = 1$ if quadrant is 1 or 2, $j = 2$ if quadrant is 3
 669 or 4; $D_{i,j}$ is the infinitesimal length of wall pipe; $\Delta D_{i,j}$ is the increase in the infinitesimal length of
 670 wall pipe; $d_{i,j}$ is the average height of the element infinitesimal; $\Delta d_{i,j}$ is the increase in the
 671 average height of the element infinitesimal; $A_{i,j}$ is the area of pipe in the infinitesimal element;
 672 ΔA_N is the increase in the transverse pipe cross-section due to normal forces; σ_N is the lateral
 673 unit stress; e is the thickness of pipe wall; E is the elasticity modulus; N is the Normal force; d_U
 674 is the longitudinal length of pipe (1 m); F is the force due to internal pressure; ΔA_B is the
 675 increase in the transverse pipe cross-section due to bending stress.

676

677 The effect of pipe constraint (C) considering the thick-walled pipes (if $D_{i,j}/e > 20$ then thin-
 678 walled pipe, otherwise thick-walled pipe). For pipes with functioning expansion joints along
 679 their length (Watters, 1979). The Eqs are A.15 and A.16.

680
$$\frac{D_{i,j}}{e} = \frac{0.01}{0.01575} = 0.63 \quad (\text{A.15})$$

681
$$C = \frac{1}{1 + \frac{e}{D_{i,j}}} \left[1 + 2 \frac{e}{D_{i,j}} (1 + \mu) \left(1 + \frac{e}{D_{i,j}} \right) \right] = 4.42 \quad (\text{A.16})$$

682 Where: μ is Poisson's ratio for pipe material ductile cast iron, $\mu \approx 0.28$ (Tullis, 1989).

683

684

685 **Appendix B. Non-circular section**

686

687 The infinitesimal elements of the non-circular sections obtained in the research are shown in
688 Fig. B1.

689

690

691 **Notation**

692

693 μ = Poisson's ratio for pipe material (–)

694 σ = real part of complex valued frequency (–)

695 α = speed ratio (–)

696 v = velocity ratio (–)

697 ΔA_B = increase in pipe cross-section area due to bending stress (m²)

698 ΔA_N = increase in pipe cross-section area due to normal forces (m²)

699 $\Delta d_{i,j}$ = increase in average height of the infinitesimal element (m)

700 $\Delta D_{i,j}$ = increase in infinitesimal length of wall pipe (m)

701 σ_N = lateral unit stress (Pa)

702 ω_R = velocity angular of turbine (rad s⁻¹)

703 A = pipe cross-section area (m²)

704 a = wave speed (m s⁻¹)

705 A_0, A_1, B_0 and B_1 = coefficients that depend on the zone of operation

706 $A_{i,j}$ = area of pipe in the infinitesimal element (m²)

707 A_{TA} = cross-section area of surge tank (m²)

708 A_{TN} = tunnel area (m²)

709 $B_{i,j}$ = maximum height of infinitesimal element (m)

710 $b_{i,j}$ = minimum height of infinitesimal element (m)

711 C = effect of pipe constraint (–)

712 $C_{11,I,t}$ = identifier of incident of vacuum event on node I , in time t_S (number of event)

713 C_{12} = total number of incidences of vacuum event, in time t_S (event s⁻¹)

714 C_{R1} = average pressure amplitude (kPa)

715 C_{R2} = incident rate of vacuum event (event 100 m⁻¹ s⁻¹)

716 C_{SI} = conversion constant used in SI (–)

717	D	= internal pipe diameter (m)
718	d_{ij}	= average height of the infinitesimal element (m)
719	D_{ij}	= infinitesimal length of wall pipe (m)
720	d_U	= longitudinal length of pipe (1 m)
721	E	= elasticity modulus (Pa)
722	e	= thickness of pipe wall (m)
723	F	= force due to internal pressure (N)
724	f	= friction coefficient (–)
725	g	= acceleration due to gravity (m s^{-2})
726	H_I	= piezometric heads in node I, in past time (m)
727	$H_{P,BV}$	= piezometric head on valve butterfly (m)
728	H_{PD}	= piezometric head loss downstream (m)
729	$H_{P,I}$	= piezometric heads in node I, in present time (m)
730	$H_{P,I,t}$	= piezometric head on node I, in time t_S (m)
731	$H_{P,NL}$	= piezometric head loss upstream (m)
732	$H_{P,NT}$	= piezometric head on surge tank (m)
733	$H_{P,NV}$	= piezometric head on relief valve (m)
734	$H_{P,TU}$	= piezometric head on turbine, in present time (m)
735	HP_{TU}	= piezometric head on turbine, in present time (m)
736	H_{TU}	= piezometric head on turbine, in past time (m)
737	I	= node identifier, $I = 1, 2, \dots, N$
738	i	= subscript that represents the infinitesimal element, $i = 1, 2, \dots, n$
739	j	= subscript that represents the part of a non-circular section
740	K	= bulk modulus of the liquid (Pa)
741	K_l	= located head loss coefficient (–)
742	L	= length of the section (m)
743	L_T	= length of the water column, tunnel and tank length (m)
744	P_G	= power absorbed by generator (W);

- 745 $P_{I,t,max}$ = maximum pressure on node I , in time t_S (kPa)
- 746 $P_{I,t,min}$ = minimum pressure on node I , in time t_S (kPa)
- 747 Q_I = flow on node I , in past time ($\text{m}^3 \text{s}^{-1}$)
- 748 $Q_{P,BV}$ = flow on valve butterfly ($\text{m}^3 \text{s}^{-1}$)
- 749 Q_{PD} = downstream flow of relief valve ($\text{m}^3 \text{s}^{-1}$)
- 750 $Q_{P,I}$ = flow on node I , in present time ($\text{m}^3 \text{s}^{-1}$)
- 751 $Q_{P,NL}$ = flow on located head ($\text{m}^3 \text{s}^{-1}$)
- 752 $Q_{P,NV}$ = upstream flow of relief valve ($\text{m}^3 \text{s}^{-1}$)
- 753 $Q_{P,NT}$ = upstream flow of surge tank ($\text{m}^3 \text{s}^{-1}$)
- 754 $Q_{P,TU}$ = flow on turbine, in present time ($\text{m}^3 \text{s}^{-1}$)
- 755 Q_{PV} = flow on relief valve discharge ($\text{m}^3 \text{s}^{-1}$)
- 756 Q_T = flow on surge tank ($\text{m}^3 \text{s}^{-1}$)
- 757 T = instantaneous torque on turbine (Nm);
- 758 t = time (s)
- 759 T_α = ratio of the change in speed deviation to the change in relative servo velocity (–)
- 760 t_C = closing time (s)
- 761 T_f = time of minimum closure from the total opened position (s)
- 762 T_h = time of damping (s)
- 763 t_{max} = is maximum simulation time (s)
- 764 t_O = opening time (s)
- 765 T_q = closure time of servomotor (s)
- 766 t_R = reaction time (s)
- 767 T_R = the rated torque on turbine (Nm);
- 768 t_S = simulation time, $t = 0, Dt, 2Dt, \dots, t_{max}$ (s)
- 769 T_z = time of total closing (s)
- 770 V = average fluid speed (m s^{-1})
- 771 WR^2/g = polar moment of inertia of rotating parts (kg m^2)
- 772 x = longitudinal coordinate (m)

- 773 X_{LPT} = water level on the surge tank, in present time (m)
- 774 X_{LT} = water level on the surge tank, in past time (m)
- 775 y = servomotor piston position (–)
- 776 y_h = position of transition of the servomotor piston (–)
- 777 Z_{NT} = topographic elevation of surge tank (m)
- 778 ΔA = increase in transverse pipe section (m²)
- 779 ΔH = head rise (m)
- 780 Δp = pressure increase (Pa)
- 781 Δt = time step (s)
- 782 ΔV = reduction in flow velocity (m s⁻¹)
- 783 Δx = distance between nodes (m)
- 784 $\Delta \rho$ = increase in mass density (kg m⁻³)
- 785 ρ = fluid mass density (kg m⁻³)
- 786

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