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# Profile Likelihood in Directed Graphical Models from BUGS Output

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## Introduction

Approximate profile likelihood of parameters/functions of parameters in directed graphical models with incomplete data from posterior samples from software BUGS (Bayesian inference Using Gibbs Sampling).

## Directed Graphical Model

Directed graphical model defined by

- directed acyclic graph,  $\mathcal{G} = (V, E)$
- joint probability distribution of  $\mathbf{v} = (v_v)_{v \in V}$  that is directed Markov w.r.t. to  $\mathcal{G}$

i.e. admit *recursive factorization property*

$$p(\mathbf{v}) = \prod_{v \in V} p(v_v | \mathbf{v}_{\text{pa}(v)})$$

Assume

$$V = X \cup Y \cup \Theta \cup C$$

|                                | random<br>(single-edged)                                               | constant<br>(double-edged)                                                 |
|--------------------------------|------------------------------------------------------------------------|----------------------------------------------------------------------------|
| <b>observed</b><br>(rectangle) | X: observed data<br>$\mathbf{x} = (x_v)_{v \in X}$                     | C: covariates<br>$\mathbf{c} = (c_v)_{v \in C}$                            |
| <b>unobserved</b><br>(circle)  | Y: missing data/<br>latent variables<br>$\mathbf{y} = (y_v)_{v \in Y}$ | $\Theta$ : parameters<br>$\boldsymbol{\theta} = (\theta_v)_{v \in \Theta}$ |

As Spiegelhalter (1998) consider constants as random variables with priors on, but condition on them.

Let

$$z_v = \begin{cases} x_v & \text{for } v \in X \\ y_v & \text{for } v \in Y \end{cases}$$

$$\mathbf{z}_{\text{pa}(v)} = (\mathbf{x}_{\text{pa}(v)}, \mathbf{y}_{\text{pa}(v)})$$

Then

$$p(\mathbf{x}, \mathbf{y}, \boldsymbol{\theta}, \mathbf{c}) = \prod_{v \in X \cup Y} p(z_v | \mathbf{z}_{\text{pa}(v)}, \boldsymbol{\theta}_{\text{pa}(v)}, \mathbf{c}_{\text{pa}(v)}) \times \prod_{v \in \Theta} p(\theta_v) \prod_{v \in C} p(c_v)$$

Since  $\boldsymbol{\theta}$  and  $\mathbf{c}$  mutually independent

$$p(\mathbf{x}, \mathbf{y} | \boldsymbol{\theta}, \mathbf{c}) = \prod_{v \in X \cup Y} p(z_v | \mathbf{z}_{\text{pa}(v)}, \boldsymbol{\theta}_{\text{pa}(v)}, \mathbf{c}_{\text{pa}(v)})$$

Likelihood of  $\boldsymbol{\theta}$

$$L(\boldsymbol{\theta} | \mathbf{x}, \mathbf{c}) = \int p(\mathbf{x}, \mathbf{y} | \boldsymbol{\theta}, \mathbf{c}) d\mathbf{y}$$

Profile likelihood of  $\theta_i$ ,  $i \in \Theta$ ,

$$\hat{L}(\theta_i | \mathbf{x}, \mathbf{c}) = \sup_{\boldsymbol{\theta}_{\setminus i}} L(\boldsymbol{\theta} | \mathbf{x}, \mathbf{c})$$

where  $\boldsymbol{\theta}_{\setminus i} = \boldsymbol{\theta}_{\Theta \setminus \{i\}}$ .

Profile likelihood of  $\phi = g(\boldsymbol{\theta})$

$$\hat{L}(\phi | \mathbf{x}, \mathbf{c}) = \sup_{\boldsymbol{\theta} \in g^{-1}(\phi)} L(\boldsymbol{\theta} | \mathbf{x}, \mathbf{c}), \quad \phi \in \Phi$$

where  $\Phi$  image of parameter space of  $\boldsymbol{\theta}$  under  $g$ .

Integrated likelihood of  $\theta_i$ ,  $i \in \Theta$ ,

$$\begin{aligned} \bar{L}(\theta_i | \mathbf{x}, \mathbf{c}) &= \int L(\theta_i, \boldsymbol{\theta}_{\setminus i} | \mathbf{x}, \mathbf{c}) p(\boldsymbol{\theta}_{\setminus i} | \theta_i) d\boldsymbol{\theta}_{\setminus i} \\ &= \int p(\mathbf{x}, \mathbf{w} | \theta_i, \mathbf{c}) d\mathbf{w} \end{aligned}$$

where  $\mathbf{w} = (\mathbf{y}, \boldsymbol{\theta}_{\setminus i})$ .

## Method

### Version 1

$\theta_0$ : fixed value of  $\boldsymbol{\theta}$ . As Geyer & Thompson (1992) consider

$$\frac{p(\mathbf{x} | \boldsymbol{\theta}, \mathbf{c})}{p(\mathbf{x} | \boldsymbol{\theta}_0, \mathbf{c})} = \frac{1}{\alpha} L(\boldsymbol{\theta} | \mathbf{x}, \mathbf{c})$$

Rewrite likelihood function

$$L(\boldsymbol{\theta} | \mathbf{x}, \mathbf{c})$$

$$\propto \int \prod_{v \in \text{ch}(\Theta)} \frac{p(z_v | \mathbf{z}_{\text{pa}(v)}, \boldsymbol{\theta}_{\text{pa}(v)}, \mathbf{c}_{\text{pa}(v)})}{p(z_v | \mathbf{z}_{\text{pa}(v)}, \boldsymbol{\theta}_{0\text{pa}(v)}, \mathbf{c}_{\text{pa}(v)})} p(\mathbf{y} | \boldsymbol{\theta}, \mathbf{c}) d\mathbf{y}$$

Draw  $\mathbf{y}^{(1)}, \mathbf{y}^{(2)}, \dots, \mathbf{y}^{(N)}$  from  $p(\mathbf{y} | \boldsymbol{\theta}, \mathbf{c})$ .

Approximate likelihood function

$$\bar{L}(\boldsymbol{\theta} | \mathbf{x}, \mathbf{c}) \propto \sum_{j=1}^N \prod_{v \in \text{ch}(\Theta)} \frac{p(z_v^{(j)} | \mathbf{z}_{\text{pa}(v)}^{(j)}, \boldsymbol{\theta}_{\text{pa}(v)}^{(j)}, \mathbf{c}_{\text{pa}(v)}^{(j)})}{p(z_v^{(j)} | \mathbf{z}_{\text{pa}(v)}^{(j)}, \boldsymbol{\theta}_{0\text{pa}(v)}^{(j)}, \mathbf{c}_{\text{pa}(v)}^{(j)})}$$

where  $z_v^{(j)} = x_v$ , for  $v \in X$ ,  $z_v^{(j)} = y_v^{(j)}$ , for  $v \in Y$ , and  $\boldsymbol{\theta}_{\text{pa}(v)}^{(j)} = (\mathbf{x}_{\text{pa}(v)}, \mathbf{y}_{\text{pa}(v)}^{(j)})$ .

Sampling from  $p(\mathbf{y} | \boldsymbol{\theta}, \mathbf{c})$ : in BUGS with  $\boldsymbol{\theta}$  fixed as  $\boldsymbol{\theta}_0$ .

$\boldsymbol{\theta}_0$ : posterior mean of initial Gibbs sampler with priors on  $\boldsymbol{\theta}$ .

Compute  $\log \bar{L}(\boldsymbol{\theta} | \mathbf{x}, \mathbf{c})$  in grid formed by quantiles of initial Gibbs sampler.

Maximize over grid to approximate profile log-likelihood.

### Version 2

$\boldsymbol{\psi}$ : another generic symbol of  $\boldsymbol{\theta}$ . Rewrite likelihood function

$$L(\boldsymbol{\theta} | \mathbf{x}, \mathbf{c})$$

$$\propto \iint \prod_{v \in \text{ch}(\Theta)} \frac{p(z_v | \mathbf{z}_{\text{pa}(v)}, \boldsymbol{\theta}_{\text{pa}(v)}, \mathbf{c}_{\text{pa}(v)})}{p(z_v | \mathbf{z}_{\text{pa}(v)}, \boldsymbol{\psi}_{\text{pa}(v)}, \mathbf{c}_{\text{pa}(v)})} p(\mathbf{y}, \boldsymbol{\psi} | \mathbf{x}, \mathbf{c}) d\mathbf{y} d\boldsymbol{\psi}$$

Draw  $(\mathbf{y}^{(1)}, \boldsymbol{\psi}^{(1)}), (\mathbf{y}^{(2)}, \boldsymbol{\psi}^{(2)}), \dots, (\mathbf{y}^{(N)}, \boldsymbol{\psi}^{(N)})$  from  $p(\mathbf{y}, \boldsymbol{\psi} | \mathbf{x}, \mathbf{c})$ .

Approximate likelihood function

$$\bar{L}(\boldsymbol{\theta} | \mathbf{x}, \mathbf{c}) \propto \sum_{j=1}^N \prod_{v \in \text{ch}(\Theta)} \frac{p(z_v^{(j)} | \mathbf{z}_{\text{pa}(v)}^{(j)}, \boldsymbol{\theta}_{\text{pa}(v)}^{(j)}, \mathbf{c}_{\text{pa}(v)}^{(j)})}{p(z_v^{(j)} | \mathbf{z}_{\text{pa}(v)}^{(j)}, \boldsymbol{\psi}_{\text{pa}(v)}^{(j)}, \mathbf{c}_{\text{pa}(v)}^{(j)})}$$

Sampling from  $p(\mathbf{y}, \boldsymbol{\psi} | \mathbf{x}, \mathbf{c})$ : in BUGS with priors on  $\boldsymbol{\theta}$ .

Compute  $\log \bar{L}(\boldsymbol{\theta} | \mathbf{x}, \mathbf{c})$  in grid formed by quantiles of Gibbs sampler in this version.

Maximize over grid to approximate profile log-likelihood.

## Profile likelihood of a function

$\tilde{\mathcal{V}}$ : grid points already considered. Form pairs

$$(g(\boldsymbol{\theta}), \bar{L}(\boldsymbol{\theta} | \mathbf{x}, \mathbf{c})), \quad \boldsymbol{\theta} \in \tilde{\mathcal{V}}$$

Need to calculate  $g(\boldsymbol{\theta})$ , already have  $\bar{L}(\boldsymbol{\theta} | \mathbf{x}, \mathbf{c})$ .

Order pairs in increasing order w.r.t.  $\phi = g(\boldsymbol{\theta})$ , partition into bins.

Find pair with maximum value of  $\bar{L}(\boldsymbol{\theta} | \mathbf{x}, \mathbf{c})$  for each bin.

Combine maximum pairs to approximate profile log-likelihood of  $g(\boldsymbol{\theta})$ .

## Integrated likelihood of $\theta_i$

Consider  $\Theta \setminus \{i\}$  as latent variables in method.

Get a 1-dimensional grid. Marginalisation done by summation instead of maximalisation.

## Comments

Priors: no significant impact, once Gibbs sampler converged.

Method: hybrid of Bayesian and likelihood - prior used to compute credible region, approximation done there.

Complementary tool to BUGS.

## Example

From Spiegelhalter, Thomas, Best & Gilks (1996b). Measure for ten power plant pumps

$c_i$ : operation time  
 $x_i$ : number of failures

Model:  $i = 1, 2, \dots, 10$

$$x_i | y_i, c_i \sim \text{Po}(y_i c_i)$$

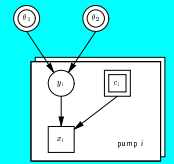
$$y_i | \theta_1, \theta_2 \sim \Gamma(\theta_1, \theta_2)$$

where

$y_i$ : failure rate of pump  $i$

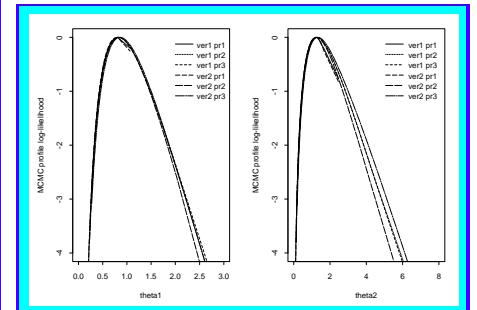
$\theta_1$ : shape parameter

$\theta_2$ : scale parameter

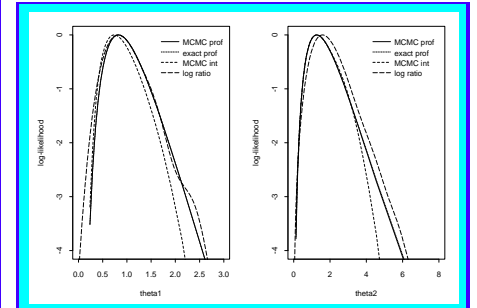


| PRIORS     | Prior 1            | Prior 2             | Prior 3                |
|------------|--------------------|---------------------|------------------------|
| $\theta_1$ | Exp(10)            | Exp(1.0)            | Exp(0.01)              |
| $\theta_2$ | $\Gamma(0.1, 1.0)$ | $\Gamma(0.01, 0.1)$ | $\Gamma(0.001, 0.001)$ |

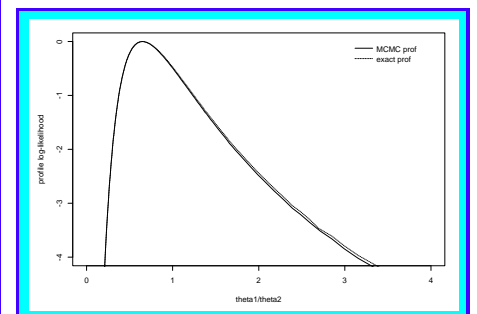
Sample size:  $N = 5.000$     Grid size:  $200 \times 200$



Priors no significant impact



Good approximation



Good approximation

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