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# Large eddy simulation of a turbulent flow in a 5 x 5 rod bundle with a mixing vane spacer grid

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In fuel assemblies of pressurized water reactors (PWRs), mixing-vane spacer grids are extensively employed to array fuel rods and enhance inter- and intra-subchannel mixing. The turbulent flow downstream of spacer grids is essential knowledge to support the design of spacer grids and mixing vanes. As a high-fidelity approach for turbulence simulation, large eddy simulation (LES) results are assessed with the high-resolution flow field measured with particle image velocimetry (PIV). The LES results reveal a mixing vane effect on vortex structures and Reynolds stresses. The mechanism of vortex generation at the mixing vanes and the development downstream of the spacer grid are visualized by the Q-criterion. The distributions of the root mean square fluctuating velocity and Reynolds stresses decay rapidly downstream of the spacer grid. The secondary flow intensity downstream of the spacer grid predicted by LES is evaluated and follows an exponentially decaying law with distance from the spacer grid.

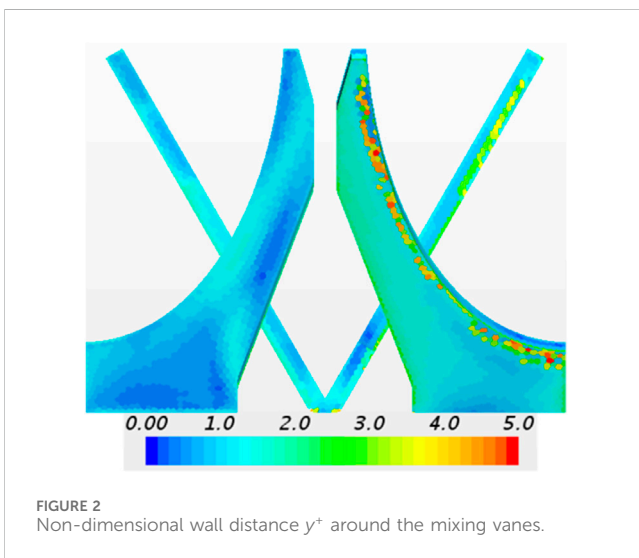
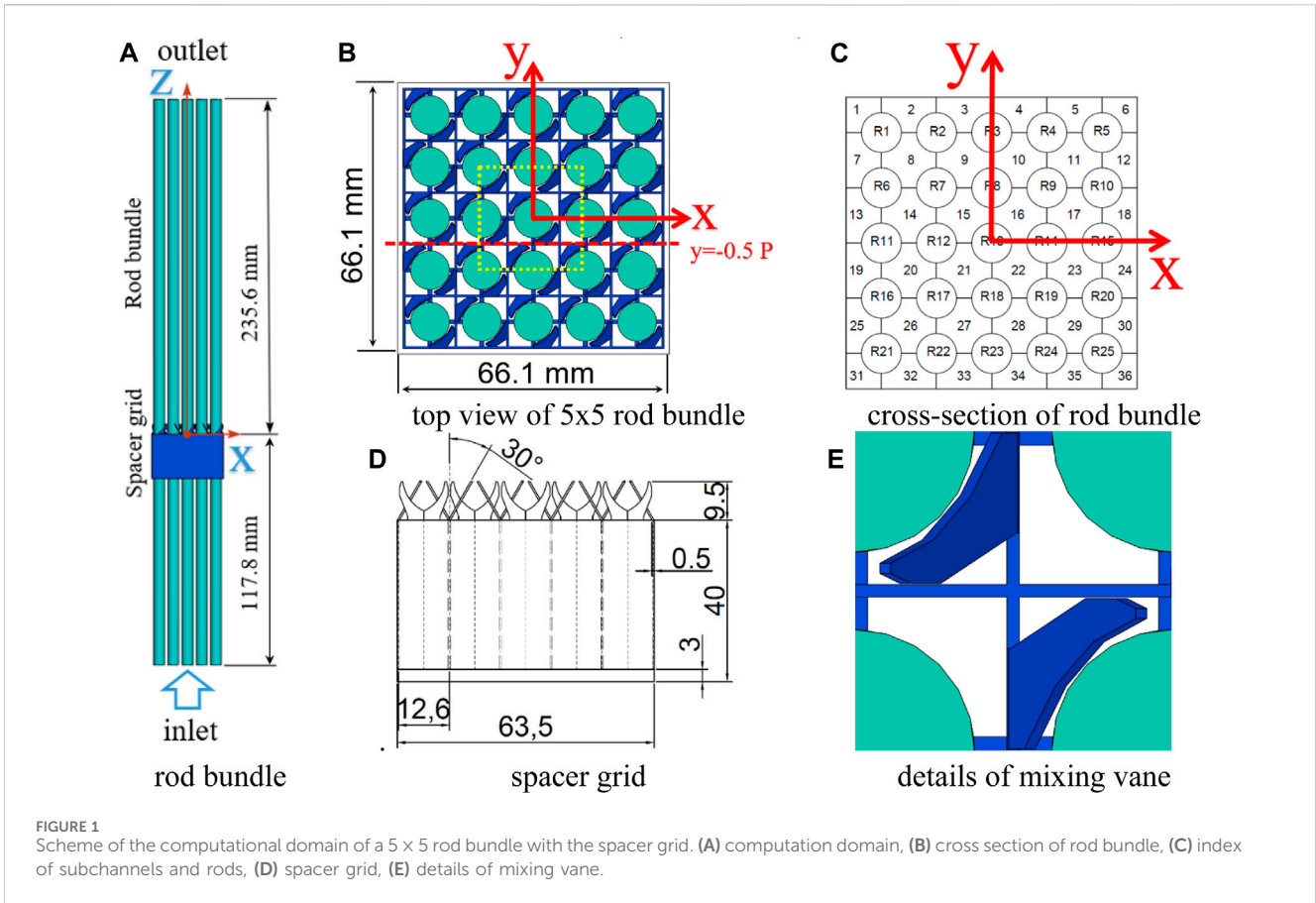
## KEYWORDS

spacer grid, validation, large eddy simulation, lateral turbulence and subchannel mixing, rod bundle assembly

## 1 Introduction

In pressurized water reactors (PWRs), fuel rod bundles are assembled into spacer grids in the core. In order to increase heat transfer, mixing vanes are fabricated on the spacer grid to produce an inter-subchannel crossflow and secondary flow within the subchannel. Furthermore, the disturbance of momentum and the thermal boundary layer on fuel rods enhances heat transfer from fuel rods to the coolant.

Several experimental investigations have been carried out by laser Doppler anemometry (LDA). [Chang et al. \(2008\)](#), [Chang et al. \(2014\)](#), and [Han et al. \(2009\)](#) employed LDA to measure the lateral flow downstream of the split-type mixing vane spacer grid and the swirl-type mixing vane spacer grid. They found that the secondary flow intensity downstream of the split-type mixing vane spacer grid was much larger than that downstream of the swirl-type mixing vane spacer grid. Thus, the split-type mixing vane spacer grid was chosen for an advanced fuel assembly. To study the mechanism of lateral turbulence generated by the spacer grid, particle image velocimetry (PIV) was applied in the measurement of the turbulent flow in a 5 × 5 rod bundle. [Dominguez-Ontiveros et al. \(2012\)](#) and [Conner et al. \(2013\)](#) applied PIV to measure the longitudinal flow in a 5 × 5 rod bundle using a spacer grid, and they used FEP tubes as rod bundles to match the refractive index of water. [Nguyen and Hassan \(2017\)](#) and [Matozinhos et al.](#)



(2021) studied the turbulent length scales in the axial velocity field in a 5 × 5 rod bundle using a spacer grid. Qu et al. (2019a), Qu et al. (2019b), Qu et al. (2019c), Qu et al. (2021), Xiong et al. (2020b), and Qu et al. (2023) applied PIV to obtain the lateral flow in a 5 × 5 rod bundle using a spacer grid, and they investigated subchannel mixing models based on the experimental data.

However, experimental work is limited to specific measured locations. The computational fluid dynamics (CFD) methodology is

powerful for capturing detailed flow fields in rod bundles. There have been several benchmark exercises to establish best practice guidelines and validate the CFD codes (Lee et al., 2014; Kang and Hassan, 2016; Mikuž and Tiselj, 2016). They suggested the Reynolds stress model (RSM) and large eddy simulation (LES) to simulate the turbulent flow in the rod bundle for time-averaged flow qualities and instantaneous characteristics. Busco and Hassan (2018) and Busco et al. (2019) employed LES to study the length scales and anisotropic turbulence in the rod bundle downstream of the spacer grid. Xiong et al. (2020a) and Wiltshcko et al. (2021) concluded that LES is superior to RSM in the prediction of the flow field in a 5 × 5 rod bundle with split-type mixing vanes. Only one paper studied the mechanism of cross-flow generated by mixing vanes by hybrid simulation based on the LES and RNG k-epsilon models (Chang and Tavoularis, 2015).

Addad et al. (2015) applied direct numerical simulation to study the buoyancy-driven turbulent flow in a horizontal annular cavity at a Rayleigh number of  $1.18 \times 10^9$ . Their predictions of temperature profiles were validated by experimental data. Kim et al. (2019) employed the LES results as a baseline to validate the RANS model to predict the temperature and heat transfer coefficient in randomly packed pebbles. Ali et al. (2022) used LES to simulate the heat transfer during baffle jetting in the rod bundle. With the validation of experimental data, the LES gives good predictions of flow and heat transfer results.

In this study, the turbulent flow in the rod bundle is simulated by LES and discussed in this paper. The mixing vane-induced vortex structures and their development downstream of the spacer grid are

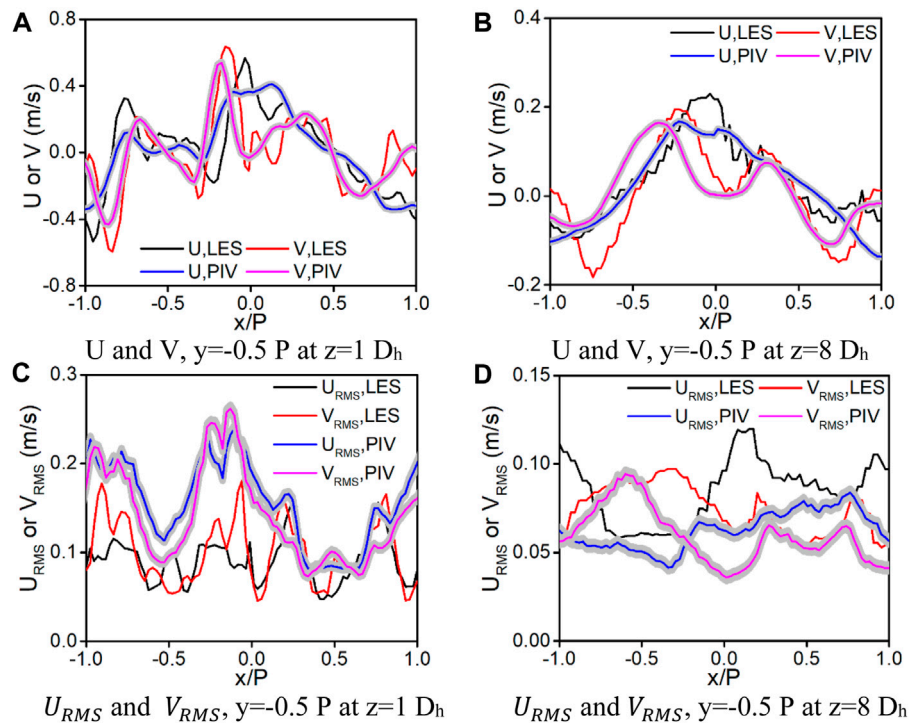


FIGURE 3  
LES validations along  $y = -0.5 P$  at  $z = 1 D_h$  and  $8 D_h$ .

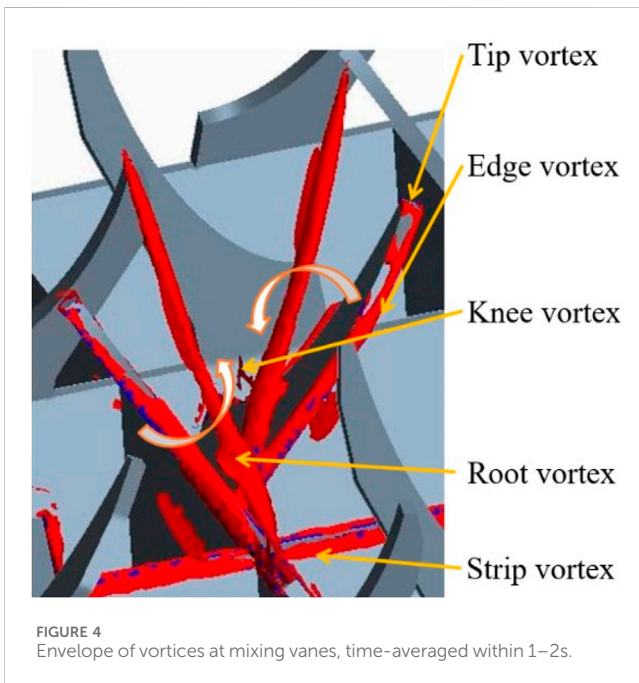


FIGURE 4  
Envelope of vortices at mixing vanes, time-averaged within 1–2s.

studied. The developments of the turbulent fluctuating velocity and Reynolds stress are discussed downstream of the space grid. The secondary flow intensity is evaluated and shows an exponential decaying trend after the spacer grid.

## 2 LES setup and validation

The commercial software package STAR CCM+ is used for the numerical simulations that are presented in this work. The LES is used for the numerical investigation of the flow field in the  $5 \times 5$  rod bundle with a split-type mixing vane spacer grid. The LES calculates large-scale energy-containing eddies directly from the filtered Navier–Stokes equation, while small-scale eddies containing less kinetic energy are modeled using the sub-grid-scale (SGS) model. The filtered Navier–Stokes equations for mass and momentum are developed from the incompressible Navier–Stokes equations and are given as follows (Selvam et al., 2015):

$$\frac{\partial(\bar{u}_i)}{\partial x_i} = 0, \tag{1}$$

$$\frac{\partial(\bar{u}_i)}{\partial t} + \frac{\partial}{\partial x_j}(\bar{u}_i \bar{u}_j) = -\frac{\partial \bar{p}}{\rho \partial x_i} + \frac{\partial \sigma_{ij}}{\rho \partial x_j} - \frac{\partial \tau_{ij}}{\rho \partial x_j}. \tag{2}$$

The wall-adapting local eddy-viscosity (WALE) model is used as the SGS model [21].

$$\nu_r = (C_w \Delta)^2 \frac{(S_{ij}^d S_{ij}^d)^{3/2}}{(\bar{S}_{ij} \bar{S}_{ij})^{5/2} + (S_{ij}^d S_{ij}^d)^{5/4}}, \tag{3}$$

where the model constant  $C_w$  is set to  $C_w = 0.544$ , and  $S_{ij}^d$  is calculated as follows [21]:

$$S_{ij}^d = \bar{S}_{ik} \bar{S}_{kj} + \bar{\Omega}_{ik} \bar{\Omega}_{kj} - \frac{1}{3} \delta_{ij} (\bar{S}_{mn} \bar{S}_{mn} - \bar{\Omega}_{mn} \bar{\Omega}_{mn}). \tag{4}$$

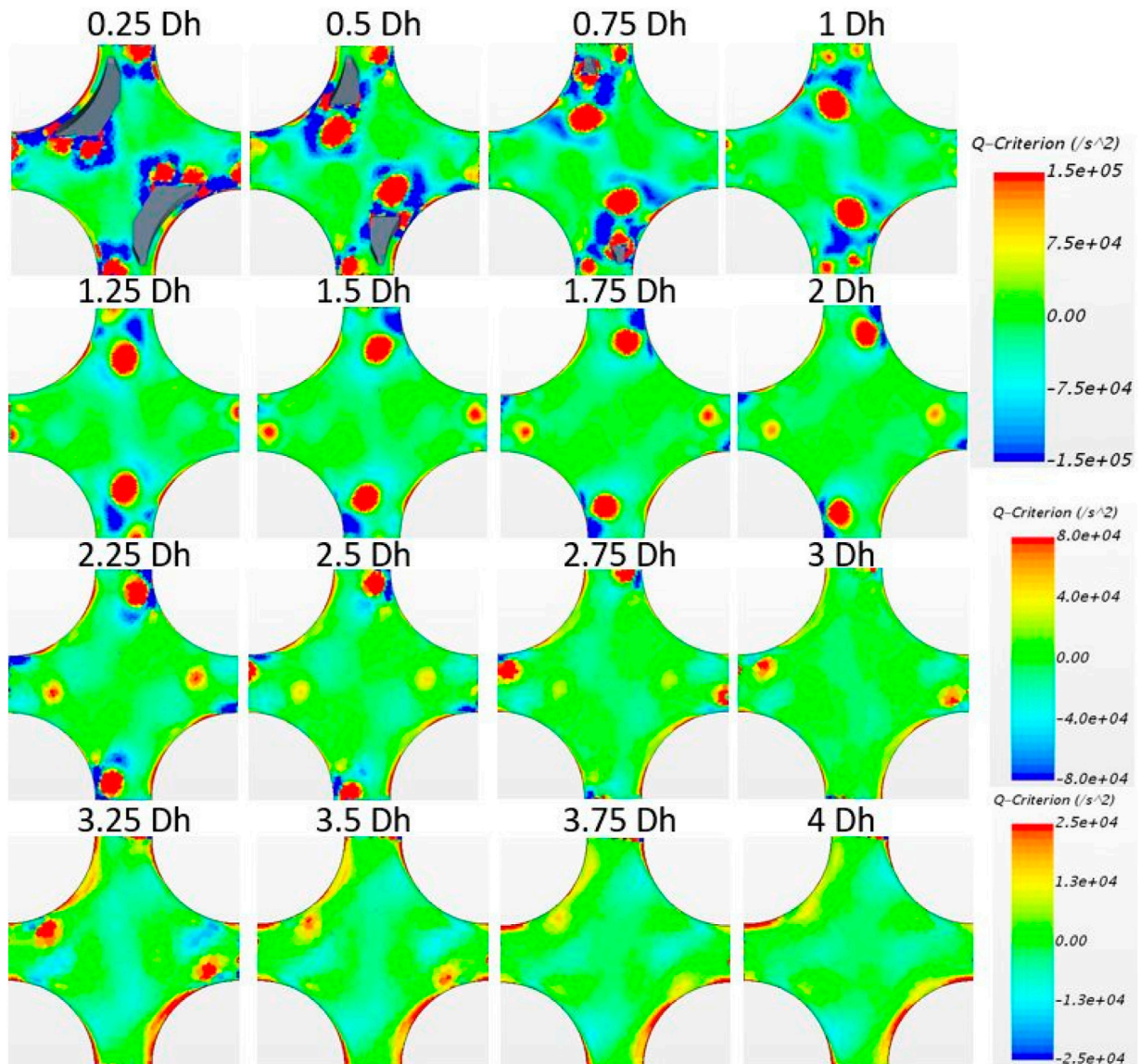


FIGURE 5  
Q-criterion in subchannel No. 11, time-averaged within 1–2s.

The experimental data on PIV measurements in a  $5 \times 5$  rod bundle (Qu et al., 2019a) with a bulk velocity of 1 m/s are used to validate numerical predictions.

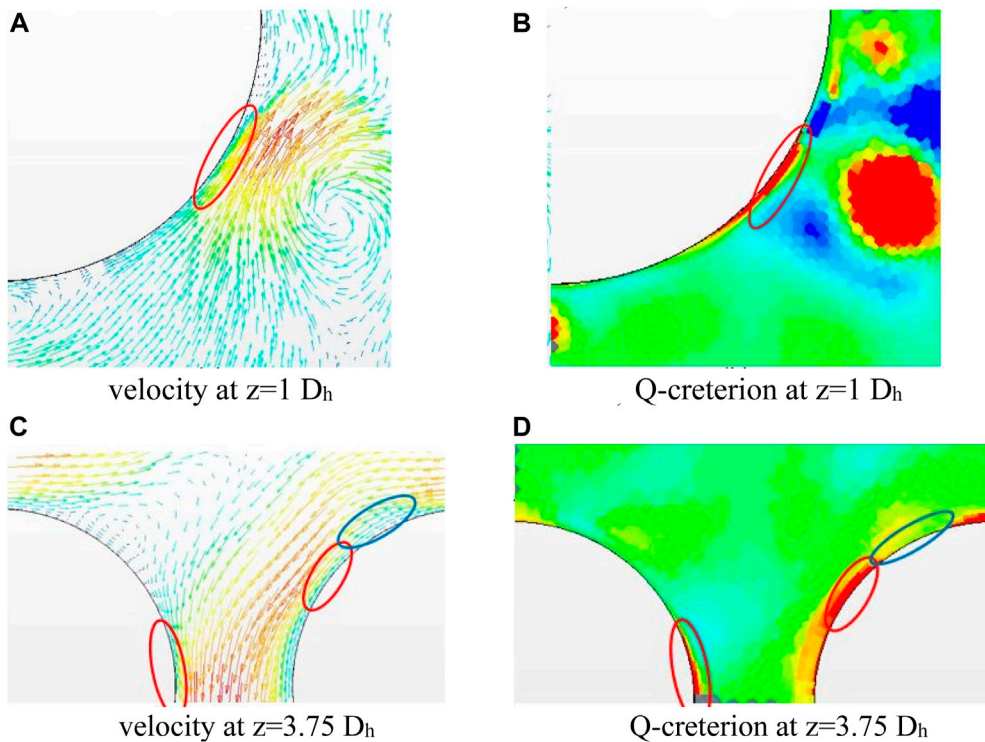
Figure 1 shows the computational domain of the numerical investigation; the indices of the subchannel can be seen in the cross-sectional view (in Figure 1B). Upstream of the spacer grid, a length of  $10 D_h$  (subchannel hydraulic diameter) is discretized, while downstream of the spacer grid, a length of  $20 D_h$  is discretized (see Figure 1A).

A fully developed velocity profile of a bare rod bundle was set as the inlet boundary, so the relatively short length of  $10 D_h$  is long enough. The wall boundaries are set to no slip walls, and the outlet boundary is a pressure outlet. The properties of the simulated coolant flow, including density  $\rho$  and kinematic viscosity  $\nu$ , are set corresponding to a temperature of 25°C. The polyhedral mesh

with a base size of 0.175 mm is generated from the spacer grid to  $z = 5 D_h$  downstream of the spacer grid. To resolve the boundary layers at the wall, five prism layers are generated near the wall. The mesh is extruded before the spacer grid and after  $z = 5 D_h$ , with the base size of 0.35 mm for each cell. The details of mesh size sensitivity can be found in Wiltchko et al. (2021). The simulation quality of the LES is strongly dependent on mesh quality. The important mesh parameters of the non-dimensional wall distance  $y^+$  and turbulence length scales were carefully evaluated. The non-dimensional wall distance  $y^+$  is calculated by

$$y^+ = \frac{y u_\tau}{\nu}, \quad (5)$$

where  $y$  is the thickness of the first mesh near the wall, with the friction velocity  $u_\tau$ , which is calculated as follows:



**FIGURE 6** Velocity vectors and Q-criterion in subchannel No. 11, time-averaged within 1–2s. **(A)** velocity at  $z=1D_h$ , **(B)** Q-criterion at  $z=1D_h$ , **(C)** velocity at  $z=3.75D_h$ , **(D)** Q-criterion at  $z=3.75D_h$ .

$$u_\tau = \sqrt{\frac{\tau_w}{\rho}}, \tag{6}$$

where  $\tau_w$  is the wall shear stress,  $\rho$  is the density, and  $\nu$  is the kinematic viscosity. The non-dimensional wall distance  $y^+$  of the first cell should be smaller than 1, which is satisfied almost in the whole investigated domain in this work. Only around the mixing vanes, the non-dimensional wall distance  $y^+$  is greater than 1 in several cells at the edges of the mixing vanes, as shown in Figure 2, with a maximum  $y^+$  value of approximately 5.

The energy-containing length scale  $L_R$  is written as (Addad et al., 2008)

$$L_R = \frac{k^{3/4}}{\varepsilon}, \tag{7}$$

where  $k$  is the turbulent kinetic energy and  $\varepsilon$  is the turbulent dissipation rate. The Taylor microscale is

$$\lambda = \sqrt{10 \frac{k\nu}{\varepsilon}}, \tag{8}$$

with the kinematic viscosity  $\nu$ . The mesh size was refined until the following conditions were satisfied:

$$\Delta = \sqrt[3]{\frac{V_{total}}{N_{total}}}, \tag{9}$$

$$\Delta \leq \min\left(\lambda, \frac{L_R}{10}\right). \tag{10}$$

In the present study, with  $L_R = 2.43 \text{ mm}$ ,  $\lambda = 0.48 \text{ mm}$ , and  $\Delta = 0.23 \text{ mm}$ , the mesh size fulfills the recommendation by Addad et al. (2008), and these length scales are less than the Taylor length scale with 32.9 million cells. In order to achieve numerical stability in the transient LES, the timestep was estimated using the Courant–Friedrichs–Lewy (CFL) number.

$$CFL = \frac{u\Delta t}{\Delta x} < 1. \tag{11}$$

The simulated physical time is 2 s, which corresponds to 5.66 flow-through times. The LES was initialized with the velocity, pressure, and turbulence intensity fields generated by RSM. To validate LES, the time-averaged crossflow velocity and the root mean square of the fluctuating velocity are defined and compared with the experimental results (Qu et al., 2019a).

$$U = \frac{1}{N} \sum_{i=1}^N (u_i), \tag{12}$$

$$U_{RMS} = \sqrt{\frac{1}{N-1} \sum_{i=1}^N (u_i - \bar{u})^2}. \tag{13}$$

The simulated data within 1–2 s are investigated. As shown in Figure 3A, B, the time-averaged velocity  $U$  and  $V$  along  $y = -0.5 P$  at  $z = 1 D_h$  and  $8 D_h$  are in reasonable agreement with the experimental data, exhibiting the same trends with an over-predicted magnitude. As shown in Figure 3C, D,  $U_{RMS}$  and  $V_{RMS}$  along  $y = -0.5 P$  at  $z = 1$  and  $8 D_h$  are reproduced reasonably well against the experimental

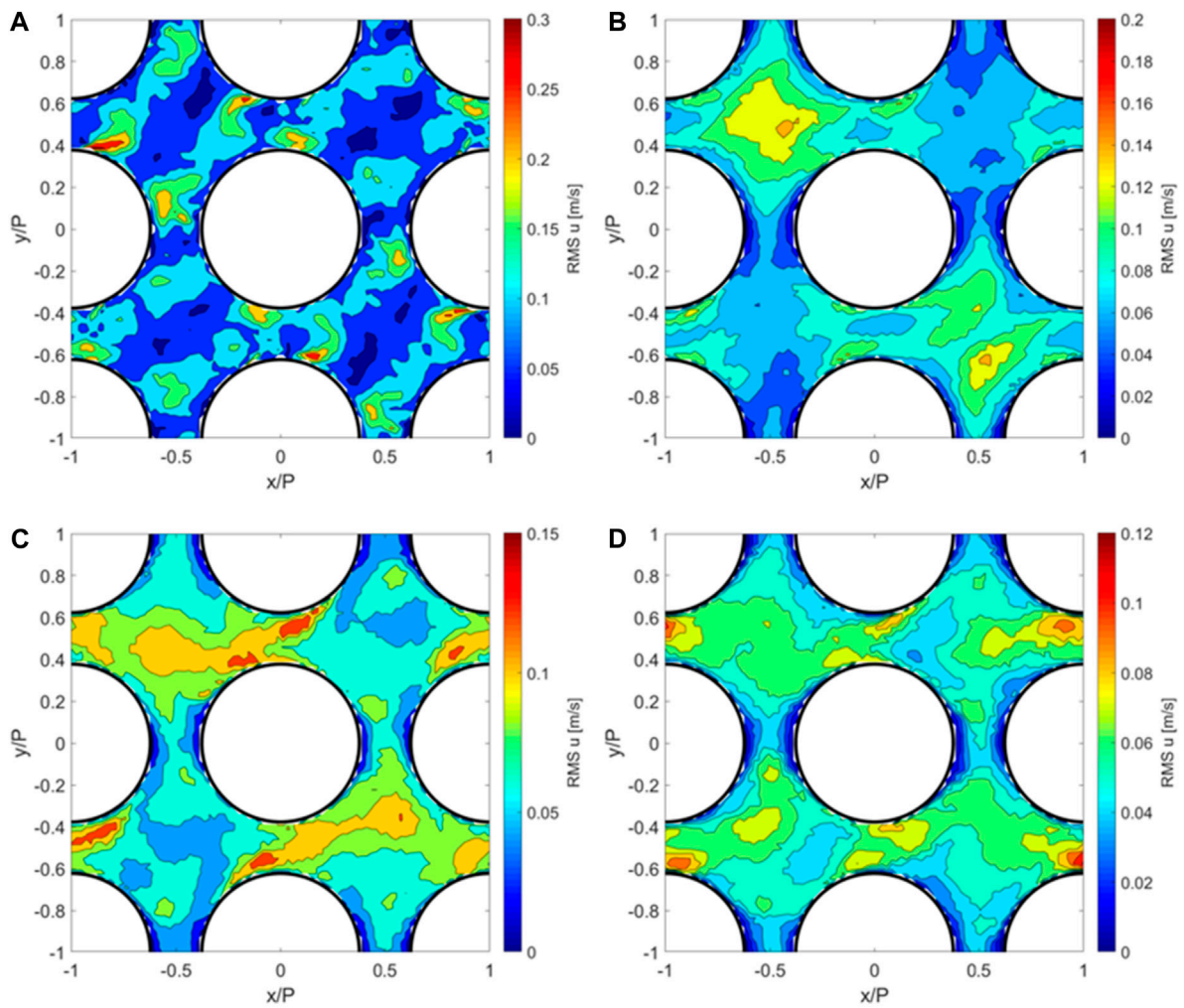


FIGURE 7  $U_{RMS}$  at  $z = 1 D_h$  (A),  $z = 4 D_h$  (B),  $z = 8 D_h$  (C), and  $z = 16 D_h$  (D), time-averaged within 1–2s.

data, with a slight under-prediction at  $z = 1 D_h$  and over-prediction at  $z = 8 D_h$ .

### 3 Lateral turbulence analysis

#### 3.1 Vortex formation and development

The mixing vanes generate vortices, which are a key factor driving the subchannel crossflow. Therefore, the formation of the vortices, as well as their path through the rod bundle, is investigated. First, the formation of the vortices at the mixing vanes is illustrated. To identify a vortex in the flow, the Q-criterion can be used. The Q-criterion estimates the regions in the flow field that are dominated by rotation, as well as the regions dominated by strain and shear, and is calculated by (Chang and Tavoularis, 2015)

$$Q = -\frac{1}{2}(S_{ij}S_{ij} - \Omega_{ij}\Omega_{ij}), \tag{14}$$

$$S_{ij} = \frac{1}{2}\left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i}\right), \tag{15}$$

$$\Omega_{ij} = \frac{1}{2}\left(\frac{\partial u_i}{\partial x_j} - \frac{\partial u_j}{\partial x_i}\right). \tag{16}$$

A positive Q-value indicates a region that is dominated by rotation, while a negative Q-value indicates a region that is dominated by strain and shear. By drawing iso-value surfaces with a certain positive value, vortex envelopes can be made visible. Figure 4 shows the iso-surface of  $Q = 8.5 \times 10^5 s^{-2}$  near mixing vanes. The two main vortices in each subchannel are formed at the root of the mixing vanes. For clarity, the iso-surface with a high value of Q is chosen to show the two strong vortices. On the tips, edges, and knees of mixing vanes and strips of the space grid, weak shedding vortices are formed.

Figure 5 shows the Q-criterion in subchannel No. 11. The regions with a high Q-value are indications of vortices. At  $z = 0.25 D_h$ , the two main vortices can be seen, located at the root edges of mixing vanes close to the subchannel center. The secondary vortices generated by the edges of mixing vanes in gaps can be seen. From  $z = 0.25 D_h$  to  $1 D_h$ , the two main vortices rotate around the subchannel center in a clockwise direction. In addition, the rotating vortices are instantaneously temporal. Within  $1 D_h$ , the secondary vortices formed at the sharp edges of the adjacent subchannels move

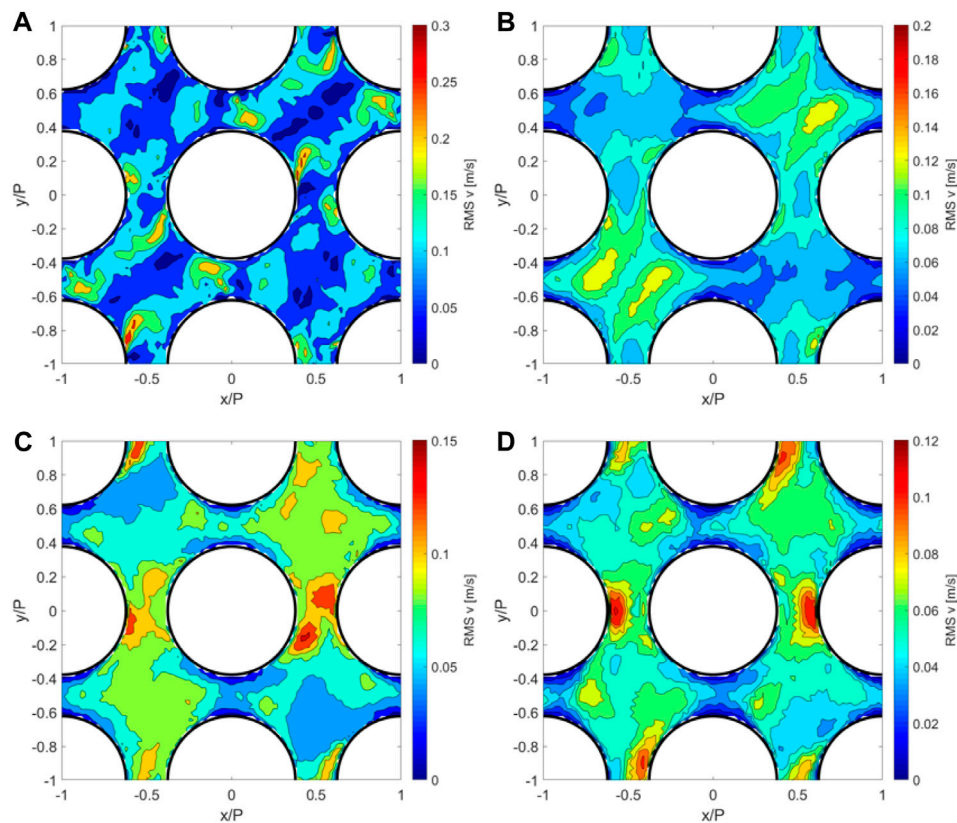


FIGURE 8  
 $V_{RMS}$  at  $z = 1 D_h$  (A),  $z = 4 D_h$  (B),  $z = 8 D_h$  (C), and  $z = 16 D_h$  (D), time-averaged within 1–2s.

into subchannel 11. At  $z = 0.75 D_h$ , the generation of the secondary vortices at the tips of the mixing vanes can be seen. On the way upstream, these secondary vortices move to the adjacent subchannel at the top and bottom. At  $z = 1.25 D_h$ , the secondary vortices induced by the top edges of the mixing vanes in subchannels 10 and 12 (refer to Figure 1B) enter subchannel 11. Furthermore, these vortices move toward the subchannel center, while the main vortices move toward the adjacent subchannels. There is still a little clockwise spinning in the path of the main vortices. The secondary vortices generated by the sharp edges move into the adjacent subchannels. At  $z = 2.75 D_h$ , the down main vortex has already moved into subchannel 15 and the top main vortex moves into subchannel 7. Moreover, the main vortices from subchannels 10 and 12 enter subchannel 11. The secondary vortices of the top edges of the mixing vanes in the adjacent subchannels decompose, while the main vortices from the adjacent subchannels move toward the subchannel center along a clockwise path close to the rods. Another important effect of heat transfer from the fuel rods to the coolant flow is the breaking up of the boundary layer around the fuel rods. Generally, in a pipe flow, the friction of the wall leads to a shear-dominated boundary layer near the walls. However, in Figure 5, the Q-criterion indicates regions with a high rotation close to rods. These are the regions where the boundary layer is broken up by flowing vortices.

Figure 6A shows the vector field of the crossflow velocity near the rod at the cross section at  $z = 1 D_h$  downstream of the spacer grid. Figure 6B shows the Q-criterion at the same location. Figure 6B shows a

region of high Q-value in the boundary layer close to the rod (marked red). Figure 6A shows the reason for this effect. The vortex induces crossflow velocity in such a way that the boundary layer is very thin at this position. The wall-normal velocity gradient is very high at this location. Therefore, the heat transfer from the fuel rod into the coolant flow is enhanced at this location. The rest of the section of the rod wall is surrounded by a normal boundary layer, and there is no high wall-normal velocity gradient. In this part of the section of the wall, the Q-value is low, and therefore, the flow is shear-dominated. The crossflow velocity and Q-criterion at  $z = 3.75 D_h$  are shown in Figure 6C, D, respectively. The regions of high Q-value in Figure 6D are marked in red, and the corresponding regions with a thin boundary layer are marked in red in Figure 6C. A region with a relatively thick boundary layer is marked in blue. Here, the Q-criterion has a small value.

### 3.2 Turbulent fluctuating velocity

Figure 7 shows  $U_{RMS}$  at  $z = 1 D_h$ ,  $4 D_h$ ,  $8 D_h$ , and  $16 D_h$  in the central four subchannels. The mixing vanes induce a strong shear flow through gaps at  $z = 1 D_h$ . When the shear flow sweeps rods, high  $U_{RMS}$  is generated near the rods. Generally, high  $U_{RMS}$  is always located in a vortex or near the rods. At  $z = 4 D_h$ , the maxima  $U_{RMS}$  is stronger in the subchannel center, resulting in a chessboard pattern in the cross section. The new vortices merge with vortices from adjacent subchannels, while some vortices decompose and transfer their kinetic energy into the

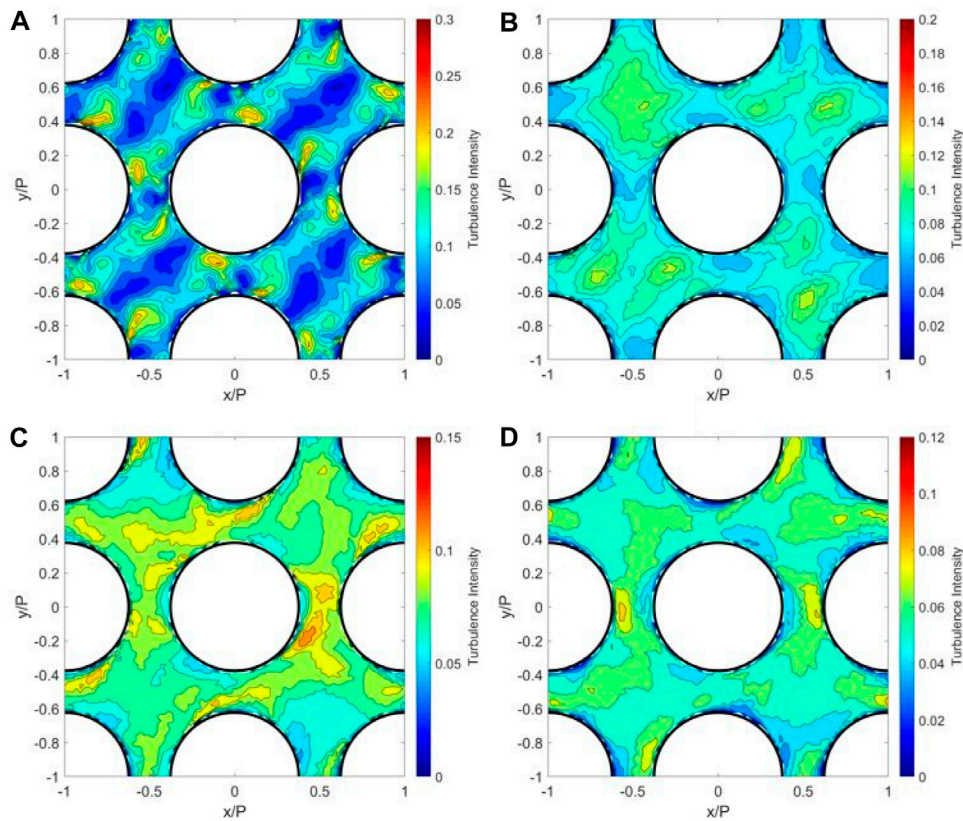


FIGURE 9  
TI at  $z = 1 D_h$  (A),  $z = 4 D_h$  (B),  $z = 8 D_h$  (C), and  $z = 16 D_h$  (D), time-averaged within 1–2s.

merging vortex. This process exists in subchannel centers, resulting in high  $U_{RMS}$  in subchannel centers. At  $z = 8 D_h$ , the chessboard pattern maintains, but strongest  $U_{RMS}$  is in gaps and near rods. At  $z = 16 D_h$ , the chessboard pattern is weak, while strongest  $U_{RMS}$  still locates in gaps.  $V_{RMS}$  is shown in Figure 8, at  $z = 1 D_h$ ,  $4 D_h$ ,  $8 D_h$ , and  $16 D_h$  downstream of the spacer grid. Generally, the appearance of the fluctuations of the velocity component  $v$  is like the appearance of the fluctuations of the velocity component  $u$ , but the distribution is *vice versa*. The maxima of the fluctuations can be found in the vertical gaps because the flow can pass through these gaps with the  $v$  component of the velocity. Moreover, the chessboard pattern is appearing from  $z = 4 D_h$  to  $z = 16 D_h$ , while the chessboard pattern and magnitude of  $V_{RMS}$  fade with the flow development downstream of the spacer grid. The decay rates of  $U_{RMS}$  and  $V_{RMS}$  are high in the near wake of the spacer grid within  $4 D_h$ , where the Reynolds shear stress is strong. After  $4 D_h$ , the decay rates of  $U_{RMS}$  and  $V_{RMS}$  become slow.

### 3.3 Lateral turbulence intensity and Reynolds shear stress

The lateral turbulence intensity can be calculated by

$$TI = \frac{1}{\bar{w}_b} \sqrt{\frac{1}{2} (U_{RMS}^2 + V_{RMS}^2)}, \quad (17)$$

$$\overline{u'v'} = \frac{1}{N-1} \sum_{i=1}^N (u_i - U)(v_i - V). \quad (18)$$

Figure 9 shows the lateral turbulence intensity at  $1 D_h$ ,  $4 D_h$ ,  $8 D_h$ , and  $16 D_h$  downstream of the spacer grid. At  $z = 1 D_h$ , the turbulence intensity has the maxima close to the rods, near the gaps of the subchannels. The high turbulence intensity is at the same locations where the velocity maxima are appearing due to the vortices. In the subchannel center, the turbulence intensity is very small. At  $z = 4 D_h$ , the maxima of the turbulence intensity are in the subchannel centers, while the magnitude of the maxima and the averaged turbulence intensity are smaller than those at the first cross section. The shape of the distribution of the turbulence intensity is very similar to the shape of the distribution of the vortices, as observed by the Q-criterion. It is obvious that the vortices are leading to a high turbulence intensity. At  $z = 8 D_h$ , the decay of the turbulence intensity becomes slower. The maxima are moving from the subchannel centers toward the rods, especially into the gaps between the adjacent subchannels. The high turbulence intensity close to the fuel rods is enhancing heat transfer at the locations in the gaps. At  $z = 16 D_h$ , the highest TI is located close to the rods in the vertical gaps, while next to the rods in the horizontal gaps, the smallest values of the turbulence intensity can be found. Therefore, the heat transfer is enhanced by the turbulence in the vertical gaps but not in the horizontal gaps. The turbulence intensity follows an exponential decay rate within  $20 D_h$  downstream of the spacer grid.



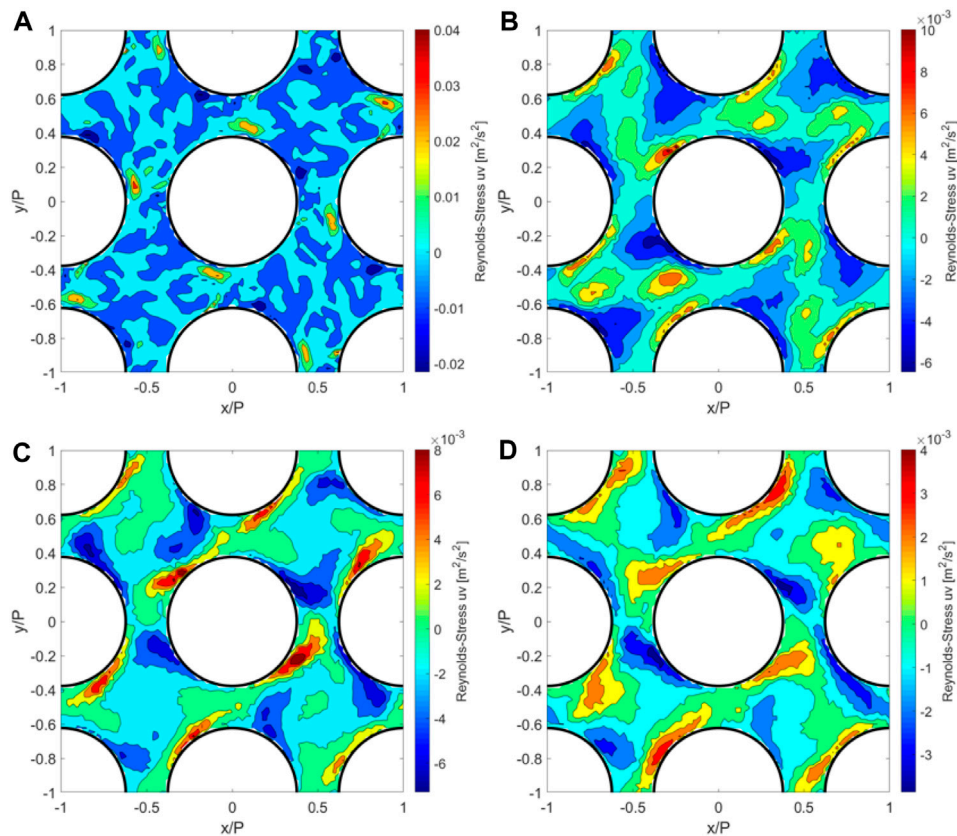


FIGURE 10  $u'v'$  at  $z = 1 D_h$  (A),  $z = 4 D_h$  (B),  $z = 8 D_h$  (C), and  $z = 16 D_h$  (D), time-averaged within 1–2s.

TABLE 1 Fitted exponential decay functions of SFI based on experimental and simulated data.

Model	SFIO	A	B
Experiment	0.03972	0.30214	-0.144
LES	0.03851	0.32	-0.1295
Relative error	-3.0%	5.9%	-10.1%

The lateral Reynolds shear stress  $\tau_{uv}$  at  $z = 1 D_h$  is shown in Figure 10A. The counter-current crossflow in the subchannels near the spacer grid produces a strong shear flow through gaps into adjacent subchannels. The maxima of Reynolds shear stress  $\tau_{uv}$  can be seen in the gaps close to the rods, which correspond with the locations of a strong shear flow.  $\tau_{uv}$  from  $z = 4 D_h$  to  $16 D_h$  can be seen in Figure 10B, D. In a streamwise direction, a strong decay of the magnitude of the shear flow is observed. At  $z = 4 D_h$ , the maximum  $\tau_{uv}$  is still in the gaps close to rods and vortices in the subchannel center. At  $z = 8 D_h$  and  $16 D_h$ , the highest Reynolds stress is near rod surfaces, facing subchannel centers.

### 3.4 Secondary flow intensity

One key parameter to evaluate the effect of the spacer grid on the fluid flow is the area-averaged secondary flow intensity (SFI). The

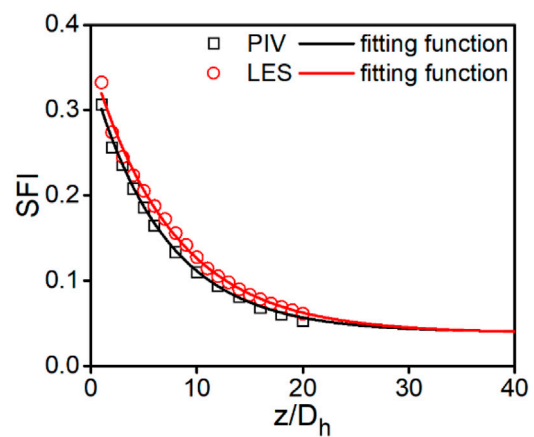


FIGURE 11 SFI downstream of the spacer grid.

SFI is the area-averaged ratio of the magnitude of the spanwise crossflow velocity components  $u$  and  $v$ , and the streamwise component  $w$ , and therefore gives some indication of the inter-subchannel mixing. A strong secondary flow in the rod bundle leads to inter-subchannel mixing. The inter-subchannel mixing increases the heat transfer from the fuel rods into the coolant flow and is therefore very important for the investigation. Hence, it is important

to validate the simulation for this parameter. The SFI can be calculated as (Busco and Hassan, 2018)

$$SFI = \frac{1}{A} \sum_i \frac{A_i \sqrt{\bar{u}^2 + \bar{v}^2}}{\bar{w}}. \quad (19)$$

In this equation,  $A$  represents the area of the cross section;  $A_i$  is the measurement resolution or grid resolution,  $A_i = \Delta x^* \Delta y$ ;  $u$  and  $v$  are the crossflow velocity components in the respective directions; and  $\bar{w}$  is the bulk flow velocity. The SFI follows an exponential function:

$$SFI = SFI_0 + Ae^{-\frac{x}{D_h}}, \quad (20)$$

which is evaluated from the measured data from  $1 D_h$  to  $20 D_h$  downstream of the spacer grid in the experiment and LES. The coefficients of fitted SFI correlations are listed in Table 1, and the fitted SFI correlations are listed in Figure 11.

In order to visualize the fully developed flow, far downstream of the spacer grid, the functions are plotted up to  $40 D_h$  downstream of the spacer grid. It is important to be aware that drawing conclusions from extrapolated data is a challenge. Nevertheless, it can be assumed that the fitting function of the experiment gives a good approximation to the fully developed  $SFI_0$ , as well as to the axial distance downstream of the spacer grid, where the flow is fully developed. The fully developed secondary flow intensity  $SFI_0$  is almost the same in the experiment and LES. Furthermore, the value of  $SFI_0$ , according to both fitting functions, almost reached approximately  $30 D_h$  downstream of the spacer grid. Hence, it can be concluded that the accuracy of the LES approach is satisfactory for the SFI.

## 4 Conclusion

The turbulent flow in a  $5 \times 5$  rod bundle with a spacer grid was studied using the LES. The simulation results for the crossflow velocity and lateral Reynolds stresses were well-validated against previous experimental data. The investigation has shown that the presented simulation shows high accuracy for the velocity distribution in the whole investigated domain. The results of the velocity fluctuations and the lateral Reynolds shear stress have been proven to be accurate near the spacer grid and reasonable far downstream of the spacer grid. Based on the simulation, the

vortices shed from mixing vanes and travel through subchannels and gaps within the first four hydraulic diameters downstream of the spacer grid. In addition, lateral velocity and Reynolds stresses decay in the exponential law with the distance from the spacer grid. LES can reach a high level of accuracy in the flow inside of a rod bundle with mixing vanes and can be used for future investigations.

## Data availability statement

The raw data supporting the conclusion of this article will be made available by the authors, without undue reservation.

## Author contributions

CL: visualization, writing—original draft, and writing—review and editing. ZD: supervision and writing—review and editing.

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## Conflict of interest

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