# Common fixed points for two pairs of selfmaps satisfying certain contraction condition in $b$-metric spaces 

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#### Abstract

This study introduces generalized contraction for two pairs of selfmaps in complete $b$-metric spaces, and it then establishes the existence of common fixed points under the presumptions that these two pairs of maps are weakly compatible and satisfy the condition for generalized contraction. A sequence of selfmaps is added as an extension of the same. Additionally, we demonstrate the same using various hypotheses on two pairs of selfmaps that satisfy the $b$-(E.A)-property. Some of the conclusions in the literature are extended /generalized to two pairs of self maps by our theorems.


Keywords: common fixed points; $b$-metric space; weakly compatible; $b$-(E.A)-property. 2020 AMS subject classifications: 47H10, $54 \mathrm{H} 25 .{ }^{1}$

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## 1 Introduction

Czerwik (10) introduced the notion of $b$-metric space which is a generalization of metric space. Following that, numerous authors looked into fixed point theorems for single-valued and multi-valued mappings in $b$-metric spaces, we refer $(3 ; 8 ; 9 ; 11 ; 15 ; 16 ; 17 ; 22 ; 23 ; 24)$.

The concept of property (E.A) was introduced by Aamari and Moutawakil (1). Several authors then used this idea to demonstrate the presence of common fixed points, we refer ( $2 ; 4 ; 5 ; 6 ; 19 ; 20 ; 21$ ).

Definition 1.1. (10) Let $X_{b}$ be a non-empty set and $s \geq 1$ be a given real number. A function $d_{b}: X_{b} \times X_{b} \rightarrow[0, \infty)$ is said to be a $b$-metric if the following conditions are satisfied: for any $x_{b}, y_{b}, z_{b} \in X_{b}$
(i) $0 \leq d_{b}\left(x_{b}, y_{b}\right)$ and $d_{b}\left(x_{b}, y_{b}\right)=0$ iff $x_{b}=y_{b}$,
(ii) $d_{b}\left(x_{b}, y_{b}\right)=d_{b}\left(y_{b}, x_{b}\right)$,
(iii) $d_{b}\left(x_{b}, z_{b}\right) \leq s\left[d_{b}\left(x_{b}, y_{b}\right)+d_{b}\left(y_{b}, z_{b}\right)\right]$.

The pair $\left(X_{b}, d_{b}\right)$ is called a b-metric space with coefficient s.
Every metric space is a $b$-metric space with $s=1$, but converse is need not be true.

Definition 1.2. (9) Let $\left(X_{b}, d_{b}\right)$ be a $b$-metric space. Then a sequence $\left\{x_{b_{n}}\right\}$ in $X_{b}$ is said to be
(i) $b$-convergent if there exists $x_{b} \in X_{b}$ such that $d_{b}\left(x_{b_{n}}, x_{b}\right) \rightarrow 0$ as $n \rightarrow \infty$.

In this case, we write $\lim _{n \rightarrow \infty} x_{b_{n}}=x_{b}$.
(ii) b-Cauchy if $d_{b}\left(x_{b_{n}}, x_{b_{m}}\right) \rightarrow 0$ as $n, m \rightarrow \infty$.

In general, a $b$-metric is not necessarily continuous (12).
Definition 1.3. (13) Let $A$ and $B$ be selfmaps of a metric space $(X, d)$. The pair $(A, B)$ is said to be a compatible pair on $X$, if $\lim _{n \rightarrow \infty} d\left(A B x_{n}, B A x_{n}\right)=0$ whenever $\left\{x_{n}\right\}$ is a sequence in $X$ such that $\lim _{n \rightarrow \infty} A x_{n}=\lim _{n \rightarrow \infty} B x_{n}=t$, for some $t \in X$.

Definition 1.4. (14) Let $X$ be a nonempty set. Let $A: X \rightarrow X$ and $B: X \rightarrow X$ be two selfmaps. If $A x=B x$ implies that $A B x=B A x$ for $x$ in $X$, then we say that the pair $(A, B)$ is weakly compatible.

Definition 1.5. (19) Two selfmappings $A_{b}$ and $B_{b}$ of a $b$-metric space ( $X_{b}, d_{b}$ ) are said to satisfy $b$-(E.A)-property if there exists a sequence $\left\{x_{b_{n}}\right\}$ in $X_{b} \ni$ $\lim _{n \rightarrow \infty} A_{b} x_{b_{n}}=\lim _{n \rightarrow \infty} B_{b} x_{b_{n}}=z_{b}$ for some $z_{b} \in X_{b}$.

Lemma 1.1. (2) Let $\left(X_{b}, d_{b}\right)$ be a $b$-metric space with coefficient $s \geq 1$. Suppose that $\left\{x_{b_{n}}\right\}$ and $\left\{y_{b_{n}}\right\}$ are $b$-convergent to $x_{b}$ and $y_{b}$ respectively, then we have

$$
\frac{1}{s^{2}} d_{b}\left(x_{b}, y_{b}\right) \leq \liminf _{n \rightarrow \infty} d_{b}\left(x_{b_{n}}, y_{b_{n}}\right) \leq \limsup _{n \rightarrow \infty} d_{b}\left(x_{b_{n}}, y_{b_{n}}\right) \leq s^{2} d_{b}\left(x_{b}, y_{b}\right)
$$

In particular, if $x_{b}=y_{b}$, then we have $\lim _{n \rightarrow \infty} d_{b}\left(x_{b_{n}}, y_{b_{n}}\right)=0$. Moreover for each $z_{b} \in X_{b}$ we have

$$
\frac{1}{s} d_{b}\left(x_{b}, z_{b}\right) \leq \liminf _{n \rightarrow \infty} d_{b}\left(x_{b_{n}}, z_{b}\right) \leq \limsup _{n \rightarrow \infty} d_{b}\left(x_{b_{n}}, z_{b}\right) \leq s d_{b}\left(x_{b}, z_{b}\right) .
$$

Lemma 1.2. (7) Let $\left(X_{b}, d_{b}\right)$ be a $b$-metric space with coefficient $s \geq 1$ and $T_{b}: X_{b} \rightarrow X_{b}$ be a self map. Suppose that $\left\{x_{b_{n}}\right\}$ is a sequence in $X_{b}$ induced by $x_{b_{n+1}}=T_{b} x_{b_{n}}$ such that $d_{b}\left(x_{b_{n}}, x_{b_{n+1}}\right) \leq \lambda d_{b}\left(x_{b_{n-1}}, x_{b_{n}}\right)$ foralln $\in N$,where $\lambda \in(0,1)$ is a constant.Then $x_{b_{n}}$ is a $b$-cauchy sequence in $X_{b}$.

Recently, Nagaraju, Raju and Thirupathi (18) proved a theorem in metric spaces as follows:

Theorem 1.1. (18) Let $E, F, G$ and $H$ be self-mappings of a metric space $(X, d)$ satisfying the following conditions:
(i) $E(X) \subseteq H(X)$ and $F(X) \subseteq G(X)$,
(ii) $(E, G)$ and $(F, H)$ are weakly compatible and
(iii) $[d(E y, F z)]^{2} \leq \alpha \max \left\{[d(G y, E y)]^{2},[d(H z, F z)]^{2},[G y, H z]^{2}\right\}$ $\left.\left.\left.+\beta \max \left\{d_{( } G y, E y\right) d_{( } G y, F z\right), d_{( } E y, H z\right) d(F z, H z)\right\}$ $+\delta d(G y, F z) d(H z, E y)$
for all $y, z \in X$, where $\alpha, \beta, \delta \geq 0, \alpha+2 \beta<1$ and $\alpha+\delta<1$.
(iv) Further, if the pair $(E, G)$ satisfies (CLR_G)-property or the pair $(F, H)$ satisfies (CLR_H)-property, then the self-maps $E, F, G$ and $H$ have a unique common fixed point.

We introduce generalized contraction for two pairs of selfmaps in $b$-metric spaces and prove the existence of common fixed points under the assumptions that these two pairs of maps are weakly compatible and satisfying a generalized

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contraction condition in complete $b$-metric spaces. Our work is inspired by works of Nagaraju, Raju and Thirupathi (18). A series of selfmaps is added as an extension of the same. Additionally, we demonstrate the same using various hypotheses on two pairs of selfmaps that satisfy the $b$-(E.A)-property. Some of the conclusions in the literature are extended or generalized to two pairs of self maps by our theorems. We present examples to corroborate our findings and draw some conclusions from them.

## 2 Main Results

We introduce generalized contraction maps in $b$-metric spaces as follows.
Definition 2.1. Let $\left(X_{b}, d_{b}\right)$ be a b-metric space with coefficient $s \geq 1$ and $A_{b}, B_{b}, S_{b}, T_{b}$ : $X_{b} \rightarrow X_{b}$ be selfmaps. If there exist $\lambda_{1}, \lambda_{2}, \lambda_{3} \geq 0$ with $\lambda_{1}+s \lambda_{2}+s^{2} \lambda_{3} \leq 1$ such that

$$
\begin{align*}
s^{4}\left[d_{b}\left(A_{b} x_{b}, B_{b} y_{b}\right)\right]^{2} \leq & \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} x_{b}, T_{b} y_{b}\right)\right]^{2},\left[d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right)\right]^{2},\left[d_{b}\left(T_{b} y_{b}, B_{b} y_{b}\right)\right]^{2}\right\} \\
& +\lambda_{2} \max \left\{\frac{d_{b}\left(S_{b} x_{b} A_{b} A_{b}\right)_{b} d_{b}\left(S_{b} x_{b}, B_{b} y_{b}\right)}{2}, \frac{d_{b}\left(T_{b} y_{b}, B_{b} y_{b}\right) d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right)}{2}\right\} \\
& +\lambda_{3} \frac{d_{b}\left(S_{b} x_{b}, B_{b} y_{b}\right) d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right)}{2} . \tag{1}
\end{align*}
$$

Then we call $A_{b}, B_{b}, S_{b}$ and $T_{b}$ are generalized contraction maps.
Example 2.1. Let $X_{b}=[0,1]$ and let $d_{b}: X_{b} \times X_{b} \rightarrow[0, \infty)$ defined by

$$
d_{b}\left(x_{b}, y_{b}\right)=\left\{\begin{array}{cl}
0 & \text { if } x_{b}=y_{b} \\
\left(x_{b}+y_{b}\right)^{2} & \text { if } x_{b} \neq y_{b}
\end{array}\right.
$$

Then clearly $\left(X_{b}, d_{b}\right)$ is a complete b-metric space with $s=2$.
We define $A_{b}, B_{b}, S_{b}, T_{b}: X_{b} \rightarrow X_{b}$ by $A_{b}\left(x_{b}\right)=\frac{1-x_{b}}{5}, B_{b}\left(x_{b}\right)=\frac{\log _{10}\left(1+x_{b}\right)}{5}$,
$S_{b}\left(x_{b}\right)=x_{b}^{2}, T_{b}\left(x_{b}\right)=x_{b}$ for all $x_{b} \in X_{b}$.
Take $\lambda_{1}=\frac{1}{7}, \lambda_{2}=\frac{1}{8}, \lambda_{3}=\frac{1}{10}$.
Clearly, $\lambda_{1}+s \lambda_{2}+s^{2} \lambda_{3} \leq 1$.
Then we have

$$
\begin{aligned}
& s^{4}\left[d_{b}\left(A_{b} x_{b}, B_{b} y_{b}\right)\right]^{2}=16\left(\frac{1-e^{x_{b}}}{5}+\frac{\log _{10}\left(1+y_{b}\right)}{5}\right)^{4} \\
& \leq \frac{1}{7} \max \left\{\left(x_{b}^{2}+y_{b}\right)^{4},\left(x_{b}^{2}+\frac{1-e^{x_{b}}}{5}\right)^{4},\left(y_{b}+\frac{\log _{10}\left(1+y_{b}\right)}{5}\right)^{4}\right\} \\
&+\frac{1}{8} \max \left\{\frac{\left.\left(x_{b}^{2}+\frac{1-e^{2}}{5}\right)^{2}\right)^{2}\left(x_{b}^{2}+\frac{\log _{10}\left(1+y_{b}\right)}{2}\right)^{2}}{2}, \frac{\left(y_{b}+\frac{\log _{10}\left(1+y_{b}\right)}{5}\right)^{2}\left(y_{b}+\frac{1-e^{x_{b}}}{5}\right)^{2}}{2}\right\} \\
&+\frac{1}{10}\left(x_{b}^{2}+\frac{+\log _{10}\left(1+y_{b}\right)}{5}\right)^{2}\left(y_{b}+\frac{1-e^{x} b_{b}}{5}\right)^{2} \\
& \leq \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} x_{b}, T_{b} y_{b}\right)\right]^{2},\left[d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right)\right]^{2},\left[d_{b}\left(T_{b} y_{b}, B_{b} y_{b}\right)\right]^{2}\right\} \\
&+\lambda_{2} \max \left\{\frac{d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right)_{b}\left(S_{b} x_{b}, B_{b} y_{b}\right)}{}, \frac{d_{b}\left(T_{b} y_{b}, B_{b} y_{b}\right)_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right)}{2}\right\} \\
&+\lambda_{3} \frac{d_{b}\left(S_{b} x_{b}, B_{b} y_{b}\right) d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right)}{2} .
\end{aligned}
$$

Therefore $A_{b}, B_{b}, S_{b}$ and $T_{b}$ are generalized contraction maps.

Let $A_{b}, B_{b}, S_{b}$ and $T_{b}$ be mappings from a $b$-metric space ( $X_{b}, d_{b}$ ) into itself and satisfying

$$
\begin{equation*}
A_{b}\left(X_{b}\right) \subseteq T_{b}\left(X_{b}\right) \text { and } B_{b}\left(X_{b}\right) \subseteq S_{b}\left(X_{b}\right) \tag{2}
\end{equation*}
$$

Now, by (2), for any $x_{b_{0}} \in X_{b}$, there exists $x_{b_{1}} \in X_{b}$ such that $y_{b_{0}}=A_{b} x_{b_{0}}=T_{b} x_{b_{1}}$.
In the same way for this $x_{b_{1}}$, we can choose a point $x_{b_{2}} \in X_{b}$ such that $y_{b_{1}}=B_{b} x_{b_{1}}=S_{b} x_{b_{2}}$ and so on.
In general, we can define a sequence $\left\{y_{b_{n}}\right\} \in X_{b}$ such that

$$
\begin{equation*}
y_{b_{2 n}}=A_{b} x_{b_{2 n}}=T_{b} x_{b_{2 n+1}} \text { and } y_{b_{2 n+1}}=B_{b} x_{b_{2 n+1}}=S_{b} x_{b_{2 n+2}} \text { for } n=0,1,2, \ldots \tag{3}
\end{equation*}
$$

Proposition 2.1. Let $\left(X_{b}, d_{b}\right)$ be a $b$-metric space with coefficient $s \geq 1$. Suppose that $A_{b}, B_{b}, S_{b}$ and $T_{b}$ are generalized contraction maps. Then we have the following:
(i) If $A_{b}\left(X_{b}\right) \subseteq T_{b}\left(X_{b}\right)$ and the pair $\left(B_{b}, T_{b}\right)$ is weakly compatible, and if $x_{b}$ is a common fixed point of $A_{b}$ and $S_{b}$ then $x_{b}$ is a common fixed point of $A_{b}, B_{b}, S_{b}$ and $T_{b}$ and it is unique.
(ii) If $B_{b}\left(X_{b}\right) \subseteq S_{b}\left(X_{b}\right)$ and the pair $\left(A_{b}, S_{b}\right)$ is weakly compatible, and if $x_{b}$ is a common fixed point of $B_{b}$ and $T_{b}$ then $x_{b}$ is a common fixed point of $A_{b}, B_{b}, S_{b}$ and $T_{b}$ and it is unique.

Proof. First, we assume that (i) holds. Let $x_{b}$ be a common fixed point of $A_{b}$ and $S_{b}$.
Then $A_{b} x_{b}=S_{b} x_{b}=x_{b}$.
Since $A_{b}\left(X_{b}\right) \subseteq T_{b}\left(X_{b}\right)$, there exists $y \in X_{b}$ such that $T_{b} y_{b}=x_{b}$.
Therefore $A_{b} x_{b}=S_{b} x_{b}=T_{b} y_{b}=x_{b}$. If $A_{b} x_{b} \neq B_{b} y_{b}$, then
$s^{4}\left[d_{b}\left(A_{b} x_{b}, B_{b} y_{b}\right)\right]^{2} \leq \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} x_{b}, T_{b} y_{b}\right)\right]^{2},\left[d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right)\right]^{2},\left[d_{b}\left(T_{b} y_{b}, B_{b} y_{b}\right)\right]^{2}\right\}$

$$
\begin{aligned}
&+\lambda_{2} \max \left\{d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right) d_{b}\left(S_{b} x_{b}, B_{b} y_{b}\right)\right. \\
&\left.+\lambda_{3} \frac{d_{b}\left(T_{b} y_{b}, B_{b} y_{b}\right) d_{b}\left(T_{b} x_{b} y_{b}, B_{b}, A_{b} x_{b}\right)}{2}\right\} \\
&=\lambda_{1}\left[d_{b}\left(A_{b} x_{b}, B_{b} y_{b} y_{b}\right)\right]^{2}
\end{aligned}
$$

which implies that $\left(s^{4}-\lambda_{1}\right)\left[d_{b}\left(A_{b} x_{b}, B_{b} y_{b}\right)\right]^{2} \leq 0$.
Since $\left(s^{4}-\lambda_{1}\right) \geq 0$, we have $d_{b}\left(A_{b} x_{b}, B_{b} y_{b}\right) \leq 0$ which implies that $A_{b} x_{b}=B_{b} y_{b}$.
Therefore $A_{b} x_{b}=B_{b} y_{b}=S_{b} x_{b}=T_{b} y_{b}=x_{b}$.
As $\left(B_{b}, T_{b}\right)$ is weakly compatible and $T_{b} y_{b}=B_{b} y_{b}$, we have
$B_{b} T_{b} y_{b}=T_{b} B_{b} y_{b}$. i.e., $B_{b} x_{b}=T_{b} x_{b}$.
Now, we prove that $B_{b} x_{b}=x_{b}$. If $B_{b} x_{b} \neq x_{b}$, then

$$
\begin{aligned}
s^{4}\left[d_{b}\left(x_{b}, B_{b} x_{b}\right)\right]^{2}= & s^{4}\left[d_{b}\left(A_{b} x_{b}, B_{b} x_{b}\right)\right]^{2} \\
\leq & \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} x_{b}, T_{b} x_{b}\right)\right]^{2},\left[d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right)\right]^{2},\left[d_{b}\left(T_{b} x_{b}, B_{b} x_{b}\right)\right]^{2}\right\} \\
& +\lambda_{2} \max \left\{d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right) d_{b}\left(S_{b} x_{b}, B_{b} x_{b}\right)\right. \\
& \left.+\lambda_{3} \frac{\left.d_{b}\left(S_{b} x_{b} x_{b}, B_{b} x_{b}, x_{b}\right) d_{b}\left(B_{b} x_{b}\right) d_{b} d_{b}, A_{b} x_{b} x_{b} x_{b}, A_{b} x_{b}\right)}{2}\right\} \\
= & \lambda_{1}\left[d_{b}\left(x_{b}, B_{b} x_{b}\right)\right]^{2}+\lambda_{3} \frac{\left[d_{b}\left(x_{b}, B_{b} x_{b}\right)\right]^{2}}{2}
\end{aligned}
$$

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$$
=\left(\lambda_{1}+\frac{\lambda_{3}}{2}\right)\left[d_{b}\left(x_{b}, B_{b} x_{b}\right)\right]^{2}
$$

which implies that $\left[s^{4}-\left(\lambda_{1}+\frac{\lambda_{3}}{2}\right)\right]\left[d_{b}\left(x_{b}, B_{b} x_{b}\right)\right]^{2} \leq 0$.
Since $\left[s^{4}-\left(\lambda_{1}+\frac{\lambda_{3}}{2}\right)\right] \geq 0$, we have $d_{b}\left(x_{b}, B_{b} x_{b}\right) \leq 0$.
Hence, $B_{b} x_{b}=x_{b}$.
Therefore $A_{b} x_{b}=B_{b} x_{b}=S_{b} x_{b}=T_{b} x_{b}=x_{b}$.
Therefore, $x_{b}$ is a common fixed point of $A_{b}, B_{b}, S_{b}$ and $T_{b}$.
If $x_{b}^{\prime}$ is also a common fixed point of $A_{b}, B_{b}, S_{b}$ and $T_{b}$ with $x_{b} \neq x_{b}^{\prime}$, then

$$
\begin{aligned}
s^{4}\left[d_{b}\left(x_{b}, x_{b}^{\prime}\right)\right]^{2}= & s^{4}\left[d_{b}\left(A_{b} x_{b}, B_{b} x_{b}^{\prime}\right)\right]^{2} \\
\leq & \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} x_{b}, T_{b} x_{b}^{\prime}\right)\right]^{2},\left[d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right)\right]^{2},\left[d_{b}\left(T_{b} x_{b}^{\prime}, B_{b} x_{b}^{\prime}\right)\right]^{2}\right\} \\
& \left.+\lambda_{2} \max \max _{b}\left(S_{b} x_{b}, A_{b} x_{b}\right) d_{b}\left(S_{b} x_{b}, B_{b} x_{b}^{\prime}\right), \frac{d_{b}\left(T_{b} x_{b}^{\prime}, B_{b} x_{b}^{\prime}\right) d_{b}\left(T_{b} x_{b}^{\prime}, A_{b} x_{b}\right)}{2}\right\} \\
& +\lambda_{3} d_{b}\left(S_{b} x_{b}, B_{b} x_{b}^{\prime}\right) d_{b}\left(T_{b} x_{b}^{\prime}, A_{b} x_{b}\right) \\
= & \lambda_{1}\left[d_{b}\left(x_{b}, x_{b}^{\prime}\right)\right]^{2}+\lambda_{3} \frac{\left[d_{b}\left(x_{b}, x_{b}^{\prime}\right)\right]^{2}}{2} \\
= & \left(\lambda_{1}+\frac{\lambda_{3}}{2}\right)\left[d_{b}\left(x_{b}, x_{b}^{\prime}\right)\right]^{2}
\end{aligned}
$$

which implies that $\left[s^{4}-\left(\lambda_{1}+\frac{\lambda_{3}}{2}\right)\right]\left[d_{b}\left(x_{b}, x_{b}^{\prime}\right)\right]^{2} \leq 0$.
Since $\left[s^{4}-\left(\lambda_{1}+\frac{\lambda_{3}}{2}\right)\right] \geq 0$, we have $d_{b}\left(x_{b}, x_{b}^{\prime}\right) \leq 0$.
Hence, $x_{b}^{\prime}=x_{b}$.
Therefore $x_{b}$ is the unique common fixed point of $A_{b}, B_{b}, S_{b}$ and $T_{b}$.
The proof of $(i i)$ is similar to $(i)$ and hence is omitted.
Lemma 2.1. Let $A_{b}, B_{b}, S_{b}$ and $T_{b}$ be selfmaps of a $b$-metric space ( $X_{b}, d_{b}$ ) and satisfy (2) and are generalized contraction maps. Then for any $x_{b_{0}} \in X_{b}$, the sequence $\left\{y_{b_{n}}\right\}$ defined by (3) is $b$-Cauchy in $X_{b}$.

Proof. Let $x_{b_{0}} \in X_{b}$ and let $\left\{y_{b_{n}}\right\}$ be a sequence defined by (3).
Assume that $y_{b_{n}}=y_{b_{n+1}}$ for some $n$.
Case (i): $n$ even.
We write $n=2 m, m \in \mathbb{N}$.
Now, we consider

$$
\begin{aligned}
& s^{4}\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right)\right]^{2}=s^{4}\left[d_{b}\left(y_{b_{2 m+1}}, y_{b_{2 m+2}}\right)\right]^{2} \\
& =s^{4}\left[d_{b}\left(y_{b_{2 m+2}}, y_{b_{2 m+1}}\right)\right]^{2} \\
& =s^{4}\left[d_{b}\left(A_{b} x_{b_{2 m+2}}, B_{b} x_{b_{2 m+1}}\right)\right]^{2} \\
& \leq \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} x_{b_{2 m+2}}, T_{b} x_{b_{2 m+1}}\right)\right]^{2},\left[d_{b}\left(S_{b} x_{b_{2 m+2}}, A_{b} x_{b_{2 m+2}}\right)\right]^{2},\right. \\
& \left.\left[d_{b}\left(T_{b} x_{b_{2 m+1}}, B_{b} x_{b_{2 m+1}}\right)\right]^{2}\right\} \\
& +\lambda_{2} \max \left\{\frac{d_{b}\left(S_{b} x_{b_{2 m+}}, A_{b} x_{b_{2 m+2}}\right) d_{b}\left(S_{b} x_{b_{2 m+}}, B_{b} x_{b_{2 m+1}}\right)}{2},\right. \\
& \left.\frac{d_{b}\left(T_{b} x_{b_{2 m+1}}, B_{b} x_{b_{2 m+1}}\right) d_{b}\left(T_{b} x_{b_{2 m+1}}, A_{b} x_{b_{2 m+2}}\right)}{2}\right\} \\
& +\lambda_{3} \frac{d_{b}\left(S_{b} x_{b_{2 m+2}}, B_{b} x_{b_{2 m+1}}\right) d_{b}\left(T_{b} x_{b_{2 m+1}}, A_{b} x_{b_{2 m+2}}\right)}{2} \\
& =\lambda_{1} \max \left\{\left[d_{b}\left(y_{b_{2 m+1}}, y_{b_{2_{m}}}\right)\right]^{2},\left[d_{b}\left(y_{b_{2 m+1}}, y_{b_{2 m+2}}\right)\right]^{2},\left[d_{b}\left(y_{b_{2 m}}, y_{b_{2 m+1}}\right)\right]^{2}\right\} \\
& +\lambda_{2} \max \left\{\frac{d_{b}\left(y_{b_{2 m+}}, y_{b_{2 m+}}\right) d_{b}\left(y_{b_{2 m+}}, y_{b_{2 m+1}}\right)}{2}, \frac{d_{b}\left(y_{b_{2 m}}, y_{b_{2 m+1}}\right) d_{b}\left(y_{b_{2 m}}, y_{b_{2 m+2}}\right)}{2}\right\}
\end{aligned}
$$

$$
\begin{aligned}
& +\lambda_{3} \frac{d_{b}\left(y_{b_{2 m+1}}, y_{b_{2 m+1}}\right) d_{b}\left(y_{b_{2 m}}, y_{b_{2 m+2}}\right)}{2} \\
= & \lambda_{1} \max \left\{\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n}}\right)\right]^{2},\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right)\right]^{2},\left[d_{b}\left(y_{b_{n}}, y_{b_{n+1}}\right)\right]^{2}\right\} \\
& \quad+\lambda_{2} \max \left\{\frac{d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right) d_{b}\left(y_{b_{n+1}}, y_{b_{n+1}}\right)}{2}, \frac{d_{b}\left(y_{b_{n}}, y_{b_{n+1}}\right) d_{b}\left(y_{b_{n}}, y_{b_{n+2}}\right)}{2}\right\} \\
& \quad+\lambda_{3} \frac{d_{b}\left(y_{b_{n+1}}, y_{b_{n+1}}\right) d_{b}\left(y_{b_{n}}, y_{b_{n+2}}\right)}{2} \\
= & \lambda_{1}\left[d_{b}\left(y_{b_{n}}, y_{b_{n+1}}\right)\right]^{2}
\end{aligned}
$$

which implies that $\left(s^{4}-\lambda_{1}\right)\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right)\right]^{2} \leq 0$.
Since $\left(s^{4}-\lambda_{1}\right) \geq 0$, we have $d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right) \leq 0$
which implies that $y_{b_{n+2}}=y_{b_{n+1}}=y_{b_{n}}$.
In general, we have $y_{b_{n+k}}=y_{b_{n}}$ for $k=0,1,2, \ldots$.
Case (ii): $n$ odd.
We write $n=2 m+1$ for some $m \in \mathbb{N}$.
Now we consider

$$
\begin{aligned}
& s^{4}\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right)\right]^{2}=s^{4}\left[d_{b}\left(y_{b_{2 m+2}}, y_{b_{2 m+3}}\right)\right]^{2} \\
& =s^{4}\left[d_{b}\left(A_{b} x_{b_{2 m+2}}, B_{b} x_{b_{2 m+3}}\right)\right]^{2} \\
& \leq \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} x_{b_{2 m+2}}, T_{b} x_{b_{2 m+3}}\right)\right]^{2},\left[d_{b}\left(S_{b} x_{b_{2 m+2}}, A_{b} x_{b_{2 m+2}}\right)\right]^{2},\right. \\
& \left.\left[d_{b}\left(T_{b} x_{b_{2 m+3}}, B_{b} x_{b_{2 m+3}}\right)\right]^{2}\right\} \\
& +\lambda_{2} \max \left\{\frac{d_{b}\left(S_{b} x_{b_{2 m+2}}, A_{b} x_{b_{2 m+2}}\right) d_{b}\left(S_{b} x_{b_{2 m+2}}, B_{b} x_{b_{2 m+3}}\right)}{2},\right. \\
& \left.\frac{d_{b}\left(T_{b} x_{b_{2 m+3}}, B_{b} x_{b_{2 m+3}}\right) d_{b}\left(T_{b} x_{b_{2 m+3}}, A_{b} x_{b_{2 m+2}}\right)}{2}\right\} \\
& +\lambda_{3} \frac{d_{b}\left(S_{b} x_{b_{2 m+2}}, B_{b} x_{b_{2 m+3}}\right) d_{b}\left(T_{b} x_{b_{2 m+3}}, A_{b} x_{b_{2 m+2}}\right)}{2} \\
& =\lambda_{1} \max \left\{\left[d_{b}\left(y_{b_{2 m+1}}, y_{b_{2 m+2}}\right)\right]^{2},\left[d_{b}\left(y_{b_{2 m+1}}, y_{b_{2 m+2}}\right)\right]^{2},\left[d_{b}\left(y_{b_{2 m+2}}, y_{b_{2 m+3}}\right)\right]^{2}\right\} \\
& +\lambda_{2} \max \left\{\frac{d_{b}\left(y_{b_{2 m+1}}, y_{b_{2 m+2}}\right) d_{b}\left(y_{b_{2 m+1}}, y_{b_{2 m+3}}\right)}{2},\right. \\
& \left.\frac{d_{b}\left(y_{b_{2 m+2}}, y_{b_{2 m+3}}\right) d_{b}\left(y_{b_{2 m+2}}, y_{b_{2 m+2}}\right)}{2}\right\}+\lambda_{3} \frac{d_{b}\left(y_{b_{2 m+1}}, y_{b_{2 m+3}}\right) d_{b}\left(y_{b_{2 m+2}}, y_{b_{2 m+2}}\right)}{2} \\
& =\lambda_{1} \max \left\{\left[d_{b}\left(y_{b_{n}}, y_{b_{n+1}}\right)\right]^{2},\left[d_{b}\left(y_{b_{n}}, y_{b_{n+1}}\right)\right]^{2},\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right)\right]^{2}\right\} \\
& +\lambda_{2} \max \left\{\frac{d_{b}\left(y_{b_{n}}, y_{b_{n+1}}\right) d_{b}\left(y_{b_{n}}, y_{b_{n+2}}\right)}{2}, \frac{d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right) d_{b}\left(y_{b_{n+1}}, y_{b_{n+1}}\right)}{2}\right\} \\
& +\lambda_{3} \frac{d_{b}\left(y_{b_{n}}, y_{b_{n+2}}\right) d_{b}\left(y_{b_{n+1}}, y_{b_{n+1}}\right)}{2} \\
& =\lambda_{1}\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right)\right]^{2}
\end{aligned}
$$

which implies that $\left(s^{4}-\lambda_{1}\right)\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right)\right]^{2} \leq 0$.
Since $\left(s^{4}-\lambda_{1}\right) \geq 0$, we have $d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right) \leq 0$
which implies that $y_{b_{n+2}}=y_{b_{n+1}}=y_{b_{n}}$.
In general, we have $y_{b_{n+k}}=y_{b_{n}}$ for $k=1,2,3, \ldots$.
From Case ( $i$ ) and Case (ii), we have $y_{b_{n+k}}=y_{b_{n}}$ for $k=0,1,2, \ldots$.
Therefore, $\left\{y_{b_{n+k}}\right\}$ is a constant sequence and hence $\left\{y_{b_{n}}\right\}$ is $b$ - Cauchy.
Now we assume that $y_{b_{n}} \neq y_{b_{n+1}}$ for all $n \in \mathbb{N}$.
If $n$ is odd then $n=2 m+1$ for some $m \in \mathbb{N}$.

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We now consider

$$
\begin{align*}
& s^{4}\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right)\right]^{2}=s^{4}\left[d_{b}\left(y_{b_{2 m+2}}, y_{b_{2 m+3}}\right)\right]^{2} \\
& =s^{4}\left[d_{b}\left(A_{b} x_{b_{2 m+2}}, B_{b} x_{b_{2 m+3}}\right)\right]^{2} \\
& \leq \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} x_{b_{2 m+2}}, T_{b} x_{b_{2 m+3}}\right)\right]^{2},\left[d_{b}\left(S_{b} x_{b_{2 m+2}}, A_{b} x_{b_{2 m+2}}\right)\right]^{2},\right. \\
& \left.\left[d_{b}\left(T_{b} x_{b_{2 m+3}}, B_{b} x_{b_{2 m+3}}\right)\right]^{2}\right\} \\
& +\lambda_{2} \max \left\{\frac{d_{b}\left(S_{b} x_{b_{2 m+2}}, A_{b} x_{b_{2 m+2}}\right) d_{b}\left(S_{b} x_{b_{2 m+2}}, B_{b} x_{b_{2 m+3}}\right)}{2},\right. \\
& \left.\frac{d_{b}\left(T_{b} x_{b_{2 m+3}}, B_{b} x_{b_{2 m+3}}\right) d_{b}\left(T_{b} x_{b_{2 m+3}}, A_{b} x_{b_{2 m+2}}\right)}{2}\right\} \\
& +\lambda_{3} \frac{d_{b}\left(S_{b} x_{b_{2 m+2}}, B_{b} x_{b_{2 m+3}}\right) d_{b}\left(T_{b} x_{b_{2 m+3}}, A_{b} x_{b_{2 m+2}}\right)}{2} \\
& =\lambda_{1} \max \left\{\left[d_{b}\left(y_{b_{2 m+1}}, y_{b_{2 m+2}}\right)\right]^{2},\left[d_{b}\left(y_{b_{2 m+1}}, y_{b_{2 m+2}}\right)\right]^{2},\left[d_{b}\left(y_{b_{2 m+2}}, y_{b_{2 m+3}}\right)\right]^{2}\right\} \\
& +\lambda_{2} \max \left\{\frac{d_{b}\left(y_{b_{2 m+1}}, y_{b_{2 m+2}}\right) d_{b}\left(y_{b_{2 m+1}}, y_{b_{2 m+3}}\right)}{2}, \frac{d_{b}\left(y_{b_{2 m+2}}, y_{b_{2 m+3}}\right) d_{b}\left(y_{b_{2 m+2}}, y_{b_{2 m+2}}\right)}{2}\right\} \\
& +\lambda_{3} \frac{d_{b}\left(y_{b_{2 m+1}}, y_{b_{2 m+3}}\right) d_{b}\left(y_{b_{2 m+2}}, y_{b_{2 m+2}}\right)}{2} \\
& =\lambda_{1} \max \left\{\left[d_{b}\left(y_{b_{n}}, y_{b_{n+1}}\right)\right]^{2},\left[d_{b}\left(y_{b_{n}}, y_{b_{n+1}}\right)\right]^{2},\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right)\right]^{2}\right\} \\
& +\lambda_{2} \max \left\{\frac{d_{b}\left(y_{b_{n}}, y_{b_{n+1}}\right) d_{b}\left(y_{b_{n}}, y_{b_{n+2}}\right)}{2}, \frac{d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right) d_{b}\left(y_{b_{n+1}}, y_{b_{n+1}}\right)}{2}\right\} \\
& +\lambda_{3} \frac{d_{b}\left(y_{b_{n}}, y_{b_{n+2}}\right) d_{b}\left(y_{b_{n+1}}, y_{b_{n+1}}\right)}{2} \tag{4}
\end{align*}
$$

If $\left[d_{b}\left(y_{b_{n}}, y_{b_{n+1}}\right)\right]^{2}<\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right)\right]^{2}$ then from (4), we have
$s^{4}\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right)\right]^{2} \leq \lambda_{1}\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right)\right]^{2}+s \lambda_{2}\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right)\right]^{2}$
which implies that $\left(s^{4}-\lambda_{1}-s \lambda_{2}\right)\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right)\right]^{2} \leq 0$.
Since $\left(s^{4}-\lambda_{1}-s \lambda_{2}\right) \geq 0$, we have $\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right)\right]^{2} \leq 0$
which implies that $y_{b_{n+1}}=y_{b_{n+2}}$,
which is a contradiction.
Therefore $\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right)\right]^{2} \leq\left[d_{b}\left(y_{b_{n}}, y_{b_{n+1}}\right)\right]^{2}$.
From the inequality (4), we have $s^{4}\left[\left[d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right)\right]^{2}\right] \leq\left(\lambda_{1}+s \lambda_{2}\right)\left[d_{b}\left(y_{b_{n}}, y_{b_{n+1}}\right)\right]^{2}$
which implies that $d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right) \leq k d_{b}\left(y_{b_{n}}, y_{b_{n+1}}\right)$, where $k=\frac{\sqrt{\left(\lambda_{1}+s \lambda_{2}\right)}}{s^{2}}<1$. Similarly, we can prove that $d_{b}\left(y_{b_{n+1}}, y_{b_{n+2}}\right) \leq k d_{b}\left(y_{b_{n}}, y_{b_{n+1}}\right)$ whenever $n$ is even. By Lemma 1.2, we have $\left\{y_{b_{n}}\right\}$ is a $b$-Cauchy sequence in $X_{b}$.

The following is the main result of this paper.
Theorem 2.1. Let $A_{b}, B_{b}, S_{b}$ and $T_{b}$ be selfmaps on a complete b-metric space $\left(X_{b}, d_{b}\right)$ and satisfy (2) and the maps are generalized contraction maps. If the pairs $\left(A_{b}, S_{b}\right)$ and $\left(B_{b}, T_{b}\right)$ are weakly compatible and one of the range sets $S_{b}\left(X_{b}\right), T_{b}\left(X_{b}\right), A_{b}\left(X_{b}\right)$ and $B_{b}\left(X_{b}\right)$ is closed, then for any $x_{b_{0}} \in X_{b}$, the sequence $\left\{y_{b_{n}}\right\}$ defined by (3) is Cauchy in $X_{b}$ and $\lim _{n \rightarrow \infty} y_{b_{n}}=z_{b}($ say $), z_{b} \in$ $X_{b}$ and $z_{b}$ is the unique common fixed point of $A_{b}, B_{b}, S_{b}$ and $T_{b}$.

Proof. By Lemma 2.1, the sequence $\left\{y_{b_{n}}\right\}$ is $b$-Cauchy in $X_{b}$.
Since $X_{b}$ is $b$-complete, $\exists z_{b} \in X_{b} \ni \lim _{n \rightarrow \infty} y_{b_{n}}=z_{b}$.

Then

$$
\left\{\begin{array}{l}
\lim _{n \rightarrow \infty} y_{b_{2 n}}=\lim _{n \rightarrow \infty} A_{b} x_{b_{2 n}}=\lim _{n \rightarrow \infty} T_{b} x_{b_{2 n+1}}=z_{b} \text { and }  \tag{5}\\
\lim _{n \rightarrow \infty} y_{b_{2 n+1}}=\lim _{n \rightarrow \infty} B_{b} x_{b_{2 n+1}}=\lim _{n \rightarrow \infty} S_{b} x_{b_{2 n+2}}=z_{b} .
\end{array}\right.
$$

We consider the below cases.
Case ( $i$ ). $S_{b}\left(X_{b}\right)$ is closed.
In this case $z_{b} \in S_{b}\left(X_{b}\right)$ and there exists $t_{b} \in X_{b}$ such that $z_{b}=S_{b} t_{b}$.
If $A_{b} t_{b} \neq z_{b}$, then

$$
\begin{align*}
& s^{4}\left[d_{b}\left(A_{b} t_{b}, B_{b} x_{b_{2 n+1}}\right)\right]^{2} \leq \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} t_{b}, T_{b} x_{b_{2 n+1}}\right)\right]^{2},\left[d_{b}\left(S_{b} t_{b}, A_{b} t_{b}\right)\right]^{2},\right. \\
& \left.\left[d_{b}\left(T_{b} x_{b_{2 n+1}}, B_{b} x_{b_{2 n+1}}\right)\right]^{2}\right\} \\
& +\lambda_{2} \max \left\{\frac{d_{b}\left(S_{b} t_{b}, A_{b} t_{b}\right) d_{b}\left(S_{b} t_{b}, B_{b} x_{b_{2 n+1}}\right)}{d_{b}\left(T_{b} x_{b} x_{2}\right.},\right.  \tag{6}\\
& \left.\frac{d_{b}\left(T_{b} x_{b_{2 n+1}}, B_{b} x_{b_{2 n+1}}\right) d_{b}\left(T_{b} x_{b_{2 n+1}}, A_{b} t_{b}\right)}{d_{b}\left(S_{b} t_{b}, B_{b} x_{b_{2 n+1}}\right) d_{b}\left(T_{b} x_{b_{2 n+1}}, A_{b} t_{b}\right)}\right\} \\
& +\lambda_{3} \frac{d_{b}\left(S_{b} t_{b}, B_{b} x_{b_{2 n+1}}\right) d_{b}\left(\stackrel{2}{T_{b}} x_{b_{2 n+1}}, A_{b} t_{b}\right)}{2}
\end{align*}
$$

On letting limit superior as $n \rightarrow \infty$ in the inequality (6), using Lemma 1.1 and (5), we get
$\frac{1}{s^{2}}\left(s^{4}\left[d_{b}\left(A_{b} t_{b}, z_{b}\right)\right]^{2}\right) \leq \lambda_{1}\left[d_{b}\left(A_{b} t_{b}, z_{b}\right)\right]^{2}$
which implies that $\left(s^{2}-\lambda_{1}\right)\left[d_{b}\left(A_{b} t_{b}, z_{b}\right)\right]^{2} \leq 0$.
Since $\left(s^{2}-\lambda_{1}\right) \geq 0$, we have $A_{b} t_{b}=z_{b}$.
Therefore, $A_{b} t_{b}=z_{b}=S_{b} t_{b}$.
Since $\left(A_{b}, S_{b}\right)$ is weakly compatible and $A_{b} t_{b}=S_{b} t_{b}$, we have
$A_{b} S_{b} t_{b}=S_{b} A_{b} t_{b}$. i.e., $A_{b} z_{b}=S_{b} z_{b}$.
Suppose $A_{b} z_{b} \neq z_{b}$. We now consider

$$
\begin{align*}
& s^{4}\left[d_{b}\left(A_{b} z_{b}, B_{b} x_{b_{2 n+1}}\right)\right]^{2} \\
& \leq \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} z_{b}, T_{b} x_{b_{2 n+}}\right)\right]^{2},\left[d_{b}\left(S_{b} z_{b}, A_{b} z_{b}\right)\right]^{2},\left[d_{b}\left(T_{b} x_{b_{2 n+1}}, B_{b} x_{b_{2 n+1}}\right)\right]^{2}\right\} \\
& \quad+\lambda_{2} \max \left\{\frac{d_{b}\left(S_{b} z_{b}, A_{b} z_{b}\right) d_{b}\left(S_{b} z_{b}, B_{b} x_{b_{2 n+1}}\right)}{2}, \frac{d_{b}\left(T_{b} x_{b_{2 n+1}}, B_{b} x_{b_{2 n+1}}\right) d_{b}\left(T_{b} x_{b_{2 n+1}}, A_{b} z_{b}\right)}{2}\right\} \\
& \quad+\lambda_{3} \frac{d_{b}\left(S_{b} z_{b}, B_{b} x_{b_{2 n+1}}\right) d_{b}\left(T_{b} x_{b_{2 n+1}}, A_{b} z_{b}\right)}{2} \tag{7}
\end{align*}
$$

On letting limit superior as $n \rightarrow \infty$ in the inequality (7) , using Lemma 1.1 and (5), we get
$\frac{1}{s^{2}}\left(s^{4}\left[d_{b}\left(A_{b} z_{b}, z_{b}\right)\right]^{2}\right) \leq\left(\lambda_{1}+\frac{s^{2} \lambda_{3}}{2}\right)\left[d_{b}\left(A_{b} z_{b}, z_{b}\right)\right]^{2}$
which implies that $\left(s^{2}-\lambda_{1}-\frac{s^{2} \lambda_{3}}{2}\right)\left[d_{b}\left(A_{b} z_{b}, z_{b}\right)\right]^{2} \leq 0$.
Since $\left(s^{2}-\lambda_{1}-\frac{s^{2} \lambda_{3}}{2}\right) \geq 0$, we have $A_{b} z_{b}=z_{b}$.
Therefore $A_{b} z_{b}=S_{b} z_{b}=z_{b}$.
Hence, $z_{b}$ is a common fixed point of $A_{b}$ and $S_{b}$.
By Proposition 2.1, we get that $z_{b}$ is a unique common fixed point of $A_{b}, B_{b}, S_{b}$ and $T_{b}$. Case (ii). $T_{b}\left(X_{b}\right)$ is closed.
In this case $z_{b} \in T_{b}\left(X_{b}\right)$ and there exists $u_{b} \in X_{b} \ni z_{b}=T_{b} u_{b}$.

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If $B_{b} u_{b} \neq z_{b}$, then

$$
\begin{align*}
& s^{4}\left[d_{b}\left(A_{b} x_{b_{2 n+2}}, B_{b} u_{b}\right)\right]^{2} \\
& \leq \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} x_{b} x_{2_{n+2}}, T_{b} u_{b}\right)\right]^{2},\left[d_{b}\left(S_{b} x_{b_{2 n+2}}, A_{b} x_{\left.b_{2 n+2}\right)}\right)\right]^{2},\left[d_{b}\left(T_{b} u_{b}, B_{b} u_{b}\right)\right]^{2}\right\} \\
& \quad+\lambda_{2} \max \left\{\frac{d_{b}\left(S_{b} x_{b_{2 n+}}, A_{b} x_{b_{2 n+}}\right) d_{b}\left(S_{b} x_{b_{2 n+2}}, B_{b} u_{b}\right)}{2} \frac{d_{b}\left(T_{b} u_{b}, B_{b} u_{b}\right) d_{b}\left(T_{b} u_{b}, A_{b} x_{\left.b_{2 n+2}\right)}\right)}{2}\right\} \\
& \quad+\lambda_{3} \frac{d_{b}\left(S_{b} x_{b_{2 n+2},}, B_{b} u_{b}\right) d_{b}\left(T_{b} u_{b}, A_{b} x_{\left.b_{2 n+2}\right)}^{2}\right.}{2} \tag{8}
\end{align*}
$$

On letting limit superior as $n \rightarrow \infty$ in (8), using Lemma 1.1 and (5), we get $\frac{1}{s^{2}}\left(s^{4}\left[d_{b}\left(B_{b} u_{b}, z_{b}\right)\right]^{2}\right) \leq \lambda_{1}\left[d_{b}\left(B_{b} u_{b}, z_{b}\right)\right]^{2}$ which implies that $\left(s^{2}-\lambda_{1}\right)\left[d_{b}\left(B_{b} u_{b}, z_{b}\right)\right]^{2} \leq 0$.
Since $\left(s^{2}-\lambda_{1}\right) \geq 0$, we have $B_{b} u_{b}=z_{b}$.
Therefore, $B_{b} u_{b}=z_{b}=T_{b} u_{b}$.
Since the pair $\left(B_{b}, T_{b}\right)$ is weakly compatible and $B_{b} u_{b}=T_{b} u_{b}$, we have
$B_{b} T_{b} u_{b}=T_{b} B_{b} u_{b}$. i.e., $B_{b} z_{b}=T_{b} z_{b}$.
We now prove that $B_{b} z_{b}=z_{b}$. Suppose that $B_{b} z_{b} \neq z_{b}$. We now consider

$$
\begin{align*}
& s^{4}\left[d_{b}\left(A_{b} x_{b_{2 n+}}, B_{b} z_{b}\right)\right]^{2} \\
& \left.\leq \lambda_{1} \max \left\{d_{b}\left(S_{b} x_{b} b_{2 n+2}, T_{b} z_{b}\right)\right]^{2},\left[d_{b}\left(S_{b} x_{b_{2 n+2}}, A_{b} x_{b_{2 n+}}\right)\right]^{2},\left[d_{b}\left(T_{b} z_{b}, B_{b} z_{b}\right)\right]^{2}\right\} \\
& \quad+\lambda_{2} \max \left\{\frac{d_{b}\left(S_{b} x_{b 2 n+2}, A_{b} x_{b_{2 n+2}} d_{b}\left(d_{b} x_{b} x_{b_{2 n+}+2}, B_{b} z_{b}\right)\right.}{2}, \frac{d_{b}\left(T_{b} z_{b}, B_{b} z_{b}\right) d_{b}\left(T_{b} z_{b}, A_{b} x_{\left.b_{2 n+2}\right)}\right)}{2}\right\}  \tag{9}\\
& \quad+\lambda_{3} \frac{d_{b}\left(S_{b} x_{b_{2 n+2}}, B_{b} z_{b}\right) d_{b}\left(T_{b} z_{b}, A_{b} x_{\left.b_{2 n+2}\right)}\right)}{2}
\end{align*}
$$

On letting limit superior as $n \rightarrow \infty$ in (9), using Lemma 1.1 and (5), we get $\frac{1}{s^{2}}\left(s^{4}\left[d_{b}\left(B_{b} z_{b}, z_{b}\right)\right]^{2}\right) \leq\left(\lambda_{1}+\frac{s^{2} \lambda_{3}}{2}\right)\left[d_{b}\left(B_{b} z_{b}, z_{b}\right)\right]^{2}$ which implies that $\left(s^{2}-\lambda_{1}-\frac{s^{2} \lambda_{3}}{2}\right)\left[d_{b}\left(B_{b} z_{b}, z_{b}\right)\right]^{2} \leq 0$.
Since $\left(s^{2}-\lambda_{1}-\frac{s^{2} \lambda_{3}}{2}\right) \geq 0$, we have $B_{b} z_{b}=z_{b}$.
Therefore $B_{b} z_{b}=T_{b} z_{b}=z_{b}$.
Therefore, $z_{b}$ is a common fixed point of $B$ and $T$.
By Proposition 2.1, we get that $z_{b}$ is the unique common fixed point of $A_{b}, B_{b}, S_{b}$ and $T_{b}$.
Case (iii). $A_{b}\left(X_{b}\right)$ is closed.
From the inequality (2) and Case (ii), the conclusion follows.
Case (iv). $B_{b}\left(X_{b}\right)$ is closed.
From the inequality (2) and Case (i), the Proof follows.
Theorem 2.2. Let $\left(X_{b}, d_{b}\right)$ be a b-metric space with coefficient $s \geq 1$. Assume that $A_{b}, B_{b}, S_{b}, T_{b}: X_{b} \rightarrow X_{b}$ are generalized contraction maps and satisfy (2). Suppose that one of the pairs $\left(A_{b}, S_{b}\right)$ and $\left(B_{b}, T_{b}\right)$ satisfies the $b-(E . A)$-property and that one of the subspace $A_{b}\left(X_{b}\right), B_{b}\left(X_{b}\right), S_{b}\left(X_{b}\right)$ and $T_{b}\left(X_{b}\right)$ is b-closed in $X_{b}$. Then the pairs $\left(A_{b}, S_{b}\right)$ and $\left(B_{b}, T_{b}\right)$ have a point of coincidence in $X_{b}$. Moreover, if the pairs $\left(A_{b}, S_{b}\right)$ and $\left(B_{b}, T_{b}\right)$ are weakly compatible, then $A_{b}, B_{b}, S_{b}$ and $T_{b}$ have a unique common fixed point in $X_{b}$.

Proof. We first assume that the pair $\left(A_{b}, S_{b}\right)$ satisfies the $b$-(E.A)-property. So there exists a sequence $\left\{x_{b_{n}}\right\}$ in $X_{b}$ such that

$$
\begin{equation*}
\lim _{n \rightarrow \infty} A_{b} x_{b_{n}}=\lim _{n \rightarrow \infty} S_{b} x_{b_{n}}=q_{b} \text { for some } q_{b} \in X_{b} \tag{10}
\end{equation*}
$$

Since $A_{b}\left(X_{b}\right) \subseteq T_{b}\left(X_{b}\right)$, there exists a sequence $\left\{y_{b_{n}}\right\}$ in $X_{b}$ such that $A_{b} x_{b_{n}}=T_{b} y_{b_{n}}$, and hence

$$
\begin{equation*}
\lim _{n \rightarrow \infty} T_{b} y_{b_{n}}=q_{b} . \tag{11}
\end{equation*}
$$

We now show that $\lim _{n \rightarrow \infty} B_{b} y_{b_{n}}=q_{b}$. Suppose that $\lim _{n \rightarrow \infty} B_{b} y_{b_{n}} \neq q_{b}$.
From (1), we have

$$
\begin{align*}
s^{4}\left[d_{b}\left(A_{b} x_{b_{n}}, B_{b} y_{b_{n}}\right)\right]^{2} \leq & \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} x_{b_{n}}, T_{b} y_{b_{n}}\right)\right]^{2},\left[d_{b}\left(S_{b} x_{b_{n}}, A_{b} x_{b_{n}}\right)\right]^{2},\right. \\
& {\left.\left[d_{b}\left(T_{b} y_{b_{n}}, B_{b} y_{b_{n}}\right)\right]^{2}\right\} } \\
& +\lambda_{2} \max \left\{\frac{d_{b}\left(S_{b} x_{b_{n}}, A_{b} x_{\left.b_{n}\right)}\right) d_{b}\left(S_{b} x_{b_{n}}, B_{b} y_{b_{n}}\right)}{},\right. \\
& \left.+\lambda_{3} \frac{d_{b}\left(S_{b} x_{b} x_{b_{n}}, y_{b}, y_{b}, y_{b}\right) d_{b} y_{b}\left(T_{b} y_{b} y_{b}, A_{b}, A_{b} x_{b_{n}}\right)}{2}, y_{b_{n}}, A_{b} x_{b_{n}}\right) \tag{12}
\end{align*}
$$

By taking limit superior as $n \rightarrow \infty$ in (12), and using (10) and (11), we obtain $\frac{1}{s^{2}} s^{4} \liminf _{n \rightarrow \infty}\left[d_{b}\left(q_{b}, B_{b} y_{b_{n}}\right)\right]^{2} \leq s^{4} \limsup _{n \rightarrow \infty}\left[d_{b}\left(A_{b} x_{b_{n}}, B_{b} y_{b_{n}}\right)\right]^{2}$

$$
\begin{aligned}
& \leq \limsup _{n \rightarrow \infty}\left(\lambda _ { 1 } \operatorname { m a x } \left\{\left[d_{b}\left(S_{b} x_{b_{n}}, T_{b} y_{b_{n}}\right)\right]^{2},\left[d_{b}\left(S_{b} x_{b_{n}}, A_{b} x_{b_{n}}\right)\right]^{2},\right.\right. \\
& \quad\left[\begin{array}{ll}
\left.\left[d_{b}\left(T_{b} y_{b_{n}}, B_{b} y_{b_{n}}\right)\right]^{2}\right\}
\end{array}\right. \\
& \left.\quad+\lambda_{2} \max ^{\operatorname{mox}\left(d_{b} S_{b} b_{n}, A_{b} x_{b_{n}}\right) d_{b}\left(S_{b} x_{b_{n}}, B_{b} y_{b_{n}}\right)}, \frac{d_{b}\left(T_{b} y_{b_{n}}, B_{b} y_{b_{n}}\right) d_{b}\left(T_{b} y_{b_{n}}, A_{b} x_{b_{n}}\right)}{2}\right\} \\
& \left.\quad+\lambda_{3} \frac{d_{b}\left(S_{b} x_{b_{n}}, B_{b} y_{b_{n}}\right) d_{b}\left(T_{b} y_{b_{n}}, A_{b} x_{b_{n}}\right)}{2}\right) \\
& \leq s^{2} \lambda_{1} \limsup _{n \rightarrow \infty}\left[d_{b}\left(q_{b}, B_{b} y_{b_{n}}\right)\right]^{2} .
\end{aligned}
$$

Since $\left(1-\lambda_{1}\right)>0$, we have

$$
\begin{equation*}
\lim _{n \rightarrow \infty} B_{b} y_{b_{n}}=q_{b} . \tag{13}
\end{equation*}
$$

Case (i). Assume $T_{b}\left(X_{b}\right)$ is a $b$-closed subset of $X_{b}$.
In this case $q_{b} \in T_{b}\left(X_{b}\right)$, we can choose $r_{b} \in X_{b} \ni T_{b} r_{b}=q_{b}$.
Now, our claim is $B_{b} r_{b}=q_{b}$. Suppose $d_{b}\left(B_{b} r_{b}, q_{b}\right)>0$. From (1), we have

$$
\begin{align*}
& s^{4}\left[d_{b}\left(A_{b} x_{b_{2 n+}}, B_{b} r_{b}\right)\right]^{2} \\
& \leq \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} x_{b} b_{2 n+2}, T_{b} r_{b}\right)\right]^{2},\left[d_{b}\left(S_{b} x_{b_{2 n+2}}, A_{b} x_{\left.b_{2 n+2}\right)}\right)\right]^{2},\left[d_{b}\left(T_{b} r_{b}, B_{b} r_{b}\right)\right]^{2}\right\} \\
& \quad+\lambda_{2} \max \left\{\frac{d_{b}\left(S_{b} x_{b 2 n+2}, A_{b} x_{\left.b_{2 n+2}\right)} d_{b}\left(S_{b} x_{x_{2 n+}}, B_{b} r_{b}\right)\right.}{2} \frac{d_{b}\left(T_{b} r_{b}, B_{b} r_{b}\right) d_{b}\left(T_{b} r_{b}, A_{b} x_{\left.b_{2 n+2}\right)}\right)}{2}\right\} \tag{14}
\end{align*}
$$

On letting limit superior as $n \rightarrow \infty$ in (14), using (10), (11), (12) and Lemma 1.1, we have $\frac{1}{s^{2}} s^{4} d_{b}\left(q_{b}, B_{b} r_{b}\right) \leq \lambda_{1}\left[d_{b}\left(q_{b}, B_{b} r_{b}\right)\right]^{2}$ which implies that
$\left(s^{2}-\lambda_{1}\right)\left[d_{b}\left(q_{b}, B_{b} r_{b}\right)\right]^{2} \leq 0$.
Since $\left(s^{2}-\lambda_{1}\right) \geq 0$, we have $B_{b} r_{b}=q_{b}$.
Hence $B_{b} r_{b}=T_{b} r_{b}=q_{b}$, so that $q_{b}$ is a coincidence point of $B_{b}$ and $T_{b}$.
Since $B_{b}\left(X_{b}\right) \subseteq S_{b}\left(X_{b}\right)$, we have $q_{b} \in S_{b}\left(X_{b}\right)$, there exists $z_{b} \in X_{b}$ such that $S_{b} z_{b}=q_{b}=B_{b} r_{b}$.
Now we show that $A_{b} z_{b}=q_{b}$. Suppose $A_{b} z_{b} \neq q_{b}$. From the inequality (1), we have

$$
\begin{aligned}
& s^{4}\left[d_{b}\left(A_{b} z_{b}, q_{b}\right)\right]^{2}=s^{4}\left[d_{b}\left(A_{b} z_{b}, B_{b} r_{b}\right)\right]^{2} \\
& \leq \\
& \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} z_{b}, T_{b} r_{b}\right)\right]^{2},\left[d_{b}\left(S_{b} z_{b}, A_{b} z_{b}\right)\right]^{2},\left[d_{b}\left(T_{b} r_{b}, B_{b} r_{b}\right)\right]^{2}\right\} \\
& \quad+\lambda_{2} \max ^{2}\left\{\frac{d_{b}\left(S_{b} z_{b}, A_{b} z_{b}\right) d_{b}\left(S_{b} z_{b}, B_{b} r_{b}\right)}{}, \frac{d_{b}\left(T_{b} r_{b}, B_{b} r_{b} d_{b}\left(T_{b} r_{b}, A_{b} z_{b}\right)\right.}{2}\right\} \\
& \quad+\lambda_{3} \frac{d_{b}\left(S_{b} z_{b}, B_{b} r_{b} d_{b}\left(T_{b} r_{b}, A_{b} z_{b}\right)\right.}{2}
\end{aligned}
$$

which implies that $\left(s^{4}-\lambda_{1}\right)\left[d_{b}\left(q_{b}, A_{b} z_{b}\right)\right]^{2} \leq 0$.
Since $\left(s^{4}-\lambda_{1}\right) \geq 0$, we have $A_{b} z_{b}=q_{b}$.
Therefore $A_{b} z_{b}=S_{b} z_{b}=q_{b}$ so that $z_{b}$ is a coincidence point of $A_{b}$ and $S_{b}$.
Since the pairs $\left(A_{b}, S_{b}\right)$ and $\left(B_{b}, T_{b}\right)$ are weakly compatible, we have $A_{b} q_{b}=S_{b} q_{b}$ and $B_{b} q_{b}=T_{b} q_{b}$.
Therefore $q_{b}$ is also a coincidence point of the pairs $\left(A_{b}, S_{b}\right)$ and $\left(B_{b}, T_{b}\right)$.
We now show that $q_{b}$ is a common fixed point of $A_{b}, B_{b}, S_{b}$ and $T_{b}$.
Suppose $A_{b} q_{b} \neq q_{b}$.
From the inequality (1), we have

$$
\begin{aligned}
& s^{4}\left[d_{b}\left(A_{b} q_{b}, q_{b}\right)\right]^{2}=s^{4}\left[d_{b}\left(A_{b} q_{b}, B_{b} r_{b}\right)\right]^{2} \\
& \leq \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} q_{b}, T_{b} r_{b}\right)\right]^{2},\left[d_{b}\left(S_{b} q_{b}, A_{b} q_{b}\right)\right]^{2},\left[d_{b}\left(T_{b} r_{b}, B_{b} r_{b}\right)\right]^{2}\right\} \\
& +\lambda_{2} \max \left\{\frac{d_{b}\left(S_{b} q_{b}, A_{b} q_{b}\right)_{b}\left(S_{b} q_{b}, B_{b} r_{b}\right)}{2}, \frac{d_{b}\left(T_{b} r_{b}, B_{b} r_{b}\right) d_{b}\left(T_{b} r_{b}, A_{b} q_{b}\right)}{2}\right\} \\
& +\lambda_{3} \frac{d_{b}\left(S_{b} q_{b}, B_{b} r_{b}\right) d_{b}\left(T_{b} r_{b}, A_{b} q_{b}\right)}{2}
\end{aligned}
$$

which implies that $\left[s^{4}-\left(\lambda_{1}+\frac{\lambda_{3}}{2}\right)\right]\left[d_{b}\left(q_{b}, A_{b} q_{b}\right)\right]^{2} \leq 0$.
Since $\left(s^{4}-\left(\lambda_{1}+\frac{\lambda_{3}}{2}\right)\right) \geq 0$, we have $A_{b} q_{b}=q_{b}$.
Therefore $A_{b} q_{b}=S_{b} q_{b}=q_{b}$ so that $q_{b}$ is a common fixed point of $A_{b}$ and $S_{b}$.
By Proposition 2.1, $q_{b}$ is a unique common fixed point of $A_{b}, B_{b}, S_{b}$ and $T_{b}$.
Case (ii). Suppose $A_{b}\left(X_{b}\right)$ is $b$-closed.
In this case, we have $q_{b} \in A_{b}\left(X_{b}\right)$ and $A_{b}\left(X_{b}\right) \subseteq T_{b}\left(X_{b}\right)$,
we choose $r_{b} \in X_{b} \ni q_{b}=T_{b} r_{b}$.
Rest of the proof follows as in Case (i).
Case (iii). Suppose $S_{b}\left(X_{b}\right)$ is $b$-closed.
We follow the argument similar as Case (i) and we get conclusion.
Case (iv). Suppose $B_{b}\left(X_{b}\right)$ is $b$-closed. As in Case (ii), we get the conclusion.
For the case of $\left(B_{b}, T_{b}\right)$ satisfies the $b$-(E.A)-property, we follow the argument similar to the case $\left(A_{b}, S_{b}\right)$ satisfies the $b$-(E.A)-property.

## 3 Corollaries and Examples

The following is an example in support of Theorem 2.1.
Example 3.1. Let $X_{b}=[0, \infty)$ and let $d_{b}: X_{b} \times X_{b} \rightarrow \mathbb{R}^{+}$defined by

$$
d_{b}\left(x_{b}, y_{b}\right)=\left\{\begin{array}{cl}
0 & \text { if } x_{b}=y_{b} \\
4 & \text { if } x_{b}, y_{b} \in(0,1) \\
\frac{9}{2}+\frac{1}{x_{b}+y_{b}} & \text { if } x_{b}, y_{b} \in[1, \infty) \\
\frac{12}{5} & \text { otherwise }
\end{array}\right.
$$

Then clearly $\left(X_{b}, d_{b}\right)$ is a complete $b$-metric space with coefficient $s=\frac{25}{24}$.
We define $A_{b}, B_{b}, S_{b}, T_{b}: X_{b} \rightarrow X_{b}$ by
$A_{b}\left(x_{b}\right)=1$ if $x_{b} \in[0, \infty), B_{b}\left(x_{b}\right)=\left\{\begin{array}{cl}x_{b} & \text { if } x_{b} \in[0,1) \\ \frac{1}{x_{b}} & \text { if } \\ x_{b} \in[1, \infty),\end{array}\right.$
$S_{b}\left(x_{b}\right)=\left\{\begin{array}{cl}x_{b} & \text { if } x_{b} \in[0,1) \\ \frac{1+x_{b}}{2} & \text { if } x_{b} \in[1, \infty),\end{array}\right.$ and $T_{b}\left(x_{b}\right)=\left\{\begin{array}{cl}2 & \text { if } x_{b} \in[0,1) \\ 2 x_{b}^{2}-1 & \text { if } x_{b} \in[1, \infty) .\end{array}\right.$
Clearly $A_{b}\left(X_{b}\right) \subseteq T_{b}\left(X_{b}\right), B_{b}\left(X_{b}\right) \subseteq S_{b}\left(X_{b}\right)$ and $A_{b}\left(X_{b}\right)$ is closed.
Clearly the pairs $\left(A_{b}, S_{b}\right)$ and $\left(B_{b}, T_{b}\right)$ are weakly compatible.
We take $\lambda_{1}=\frac{10}{51}, \lambda_{2}=\frac{1}{4}, \lambda_{3}=\frac{1}{2}$.
Then clearly $\lambda_{1}+s \lambda_{2}+s^{2} \lambda_{3} \leq 1$.
With out loss generality, we assume that $x \geq y$.
Case (i). $x_{b}, y_{b} \in[0,1)$.
$d_{b}\left(A_{b} x_{b}, B_{b} y_{b}\right)=\frac{12}{5}, d_{b}\left(S_{b} x_{b}, T_{b} y_{b}\right)=\frac{12}{5}, d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right)=\frac{12}{5}$,
$d_{b}\left(T_{b} y_{b}, B_{b} y_{b}\right)=\frac{12}{5}, d_{b}\left(S_{b} x_{b}, B_{b} y_{b}\right)=4, d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right)=\frac{9}{2}+\frac{1}{x_{b}+y_{b}}$.
We now consider

$$
\begin{aligned}
& s^{4}\left[d_{b}\left(A_{b} x_{b}, B_{b} y_{b}\right)\right]^{2}=\left(\frac{25}{24}\right)^{4}\left(\frac{12}{5}\right)^{2} \\
& \leq \frac{10}{51}\left(\frac{12}{5}\right)^{2}+\frac{1}{8}\left(\left(\frac{12}{5}\right)\left(\frac{9}{2}+\frac{1}{x_{b}+y_{b}}\right)\right)+\frac{1}{4}\left((4)\left(\frac{9}{2}+\frac{1}{x_{b}+y_{b}}\right)\right) \\
& \leq \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} x_{b}, T_{b} y_{b}\right)\right]^{2},\left[d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right)\right]^{2},\left[d_{b}\left(T_{b} y_{b}, B_{b} y_{b}\right)\right]^{2}\right\} \\
&+\lambda_{2} \max \left\{\frac{d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right) d_{b}\left(S_{b} x_{b}, B_{b} y_{b}\right)}{2}, \frac{d_{b}\left(T_{b} y_{b}, B_{b} y_{b}\right) d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right)}{2}\right\} \\
&+\lambda_{3} \frac{d_{b}\left(S_{b} x_{b}, B_{b} y_{b}\right) d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right)}{2} .
\end{aligned}
$$

Case (ii). $x_{b}, y_{b} \in(1, \infty)$.
$d_{b}\left(A_{b} x_{b}, B_{b} y_{b}\right)=\frac{12}{5}, d_{b}\left(S_{b} x_{b}, T_{b} y_{b}\right)=\frac{9}{2}+\frac{1}{x_{b}+y_{b}}, d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right)=\frac{9}{2}+\frac{1}{x_{b}+y_{b}}$,
$d_{b}\left(T_{b} y_{b}, B_{b} y_{b}\right)=\frac{12}{5}, d_{b}\left(S_{b} x_{b}, B_{b} y_{b}\right)=\frac{12}{5}, d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right)=\frac{9}{2}+\frac{1}{x_{b}+y_{b}}$.
We now consider

$$
\begin{aligned}
& s^{4}\left[d_{b}\left(A_{b} x_{b}, B_{b} y_{b}\right)\right]^{2}=\left(\frac{25}{24}\right)^{4}\left(\frac{12}{5}\right)^{2} \\
& \leq \frac{10}{51}\left(\frac{9}{2}+\frac{1}{x_{b}+y_{b}}\right)^{2}+\frac{1}{8}\left(\left(\frac{9}{2}+\frac{1}{x_{b}+y_{b}}\right)\left(\frac{12}{5}\right)\right)+\frac{1}{4}\left(\left(\frac{12}{5}\right)\left(\frac{9}{2}+\frac{1}{x_{b}+y_{b}}\right)\right) \\
& \leq \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} x_{b}, T_{b} y_{b}\right)\right]^{2},\left[d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right)\right]^{2},\left[d_{b}\left(T_{b} y_{b}, B_{b} y_{b}\right)\right]^{2}\right\} \\
&+\lambda_{2} \max ^{2}\left\{\frac{d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right) d_{b}\left(S_{b} x_{b}, B_{b} y_{b}\right)}{}, \frac{d_{b}\left(T_{b} y_{b} B_{b} y_{b}\right) d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right)}{2}\right\} \\
&+\lambda_{3} d_{b}\left(S_{b} x_{b}, B_{b} y_{b}\right) d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right) .
\end{aligned}
$$

Case (iii). $x_{b} \in(1, \infty), y_{b} \in(0,1)$.
$d_{b}\left(A_{b} x_{b}, B_{b} y_{b}\right)=\frac{12}{5}, d_{b}\left(S_{b} x_{b}, T_{b} y_{b}\right)=\frac{9}{2}+\frac{1}{x_{b}+y_{b}}, d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right)=\frac{9}{2}+\frac{1}{x_{b}+y_{b}}$,

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$d_{b}\left(T_{b} y_{b}, B_{b} y_{b}\right)=\frac{12}{5}, d_{b}\left(S_{b} x_{b}, B_{b} y_{b}\right)=\frac{12}{5}, d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right)=\frac{9}{2}+\frac{1}{x_{b}+y_{b}}$,
We now consider

$$
\begin{aligned}
& s^{4}\left[d_{b}\left(A_{b} x_{b}, B_{b} y_{b}\right)\right]^{2}=\left(\frac{25}{24}\right)^{4}\left(\frac{12}{5}\right)^{2} \\
& \leq \frac{10}{51}\left(\frac{9}{2}+\frac{1}{x_{b}+y_{b}}\right)^{2}+\frac{1}{8}\left(\left(\frac{12}{5}\right)\left(\frac{9}{2}+\frac{1}{x_{b}+y_{b}}\right)\right)+\frac{1}{4}\left(\left(\frac{12}{5}\right)\left(\frac{9}{2}+\frac{1}{x_{b}+y_{b}}\right)\right) \\
& \leq \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} x_{b}, T_{b} y_{b}\right)\right]^{2},\left(d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right)\right]^{2},\left[d_{b}\left(d_{b} y_{b}, B_{b} y_{b}\right)\right]^{2}\right\} \\
&+\lambda_{2} \max \left\{\frac{\left.d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right)\right)_{b}\left(S_{b} x_{b} B_{b} B_{b}\right)}{2}, \frac{d_{b}\left(T_{b} y_{b}, B_{b} y_{b} d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right.\right.}{2}\right\} \\
& \quad+\lambda_{3} \frac{d_{b}\left(S_{b} x_{b}, B_{b} y_{b} b d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right)\right.}{2} .
\end{aligned}
$$

Therefore $A_{b}, B_{b}, S_{b}$ and $T_{b}$ satisfy all the hypotheses of Theorem 2.1 and 1 is the unique common fixed point in $X_{b}$.

The following is an example in support of Theorem 2.2.
Example 3.2. Let $X_{b}=[0,1]$ and let $d_{b}: X_{b} \times X_{b} \rightarrow \mathbb{R}^{+}$defined by

$$
d_{b}\left(x_{b}, y_{b}\right)=\left\{\begin{array}{cl}
0 & \text { if } x_{b}=y_{b}, \\
\frac{11}{15} & \text { if } x_{b}, y_{b} \in\left[0, \frac{2}{3}\right), \\
\frac{99}{100}+\frac{x_{b}+y_{b}}{200} & \text { if } x_{b}, y_{b} \in\left[\frac{2}{3}, 1\right], \\
\frac{12}{25} & \text { otherwise. }
\end{array}\right.
$$

Then clearly $\left(X_{b}, d_{b}\right)$ is a complete $b$-metric space with coefficient $s=\frac{25}{24}$.
We define $A_{b}, B_{b}, S_{b}, T_{b}: X_{b} \rightarrow X_{b}$ by
$A_{b}\left(x_{b}\right)=\frac{2}{3}$ if $x_{b} \in[0,1], B_{b}\left(x_{b}\right)= \begin{cases}\frac{1}{2} & \text { if } x_{b} \in\left[0, \frac{2}{3}\right) \\ \frac{2}{3} & \text { if } x_{b} \in\left[\frac{2}{3}, 1\right],\end{cases}$
$S_{b}\left(x_{b}\right)=\left\{\begin{array}{cl}\frac{1}{2} & \text { if } x_{b} \in\left[0, \frac{2}{3}\right) \\ \frac{2+5 x_{b}}{8} & \text { if } x_{b} \in\left[\frac{2}{3}, 1\right],\end{array}\right.$ and $T_{b}\left(x_{b}\right)=\left\{\begin{array}{cl}1 & \text { if } x_{b} \in\left[0, \frac{2}{3}\right) \\ \frac{4+x_{b}}{7} & \text { if } x_{b} \in\left[\frac{2}{3}, 1\right] .\end{array}\right.$
Clearly $A_{b}\left(X_{b}\right) \subseteq T_{b}\left(X_{b}\right)$ and $B_{b}\left(X_{b}\right) \subseteq S_{b}\left(X_{b}\right) . A_{b}\left(X_{b}\right)=\left\{\frac{2}{3}\right\}$ is b-closed.
We choose a sequence $\left\{x_{b_{n}}\right\}$ with $\left\{x_{b_{n}}\right\}=\frac{2}{3}+\frac{1}{n}, n \geq 4$ with $\lim _{n \rightarrow \infty} A_{b} x_{b_{n}}=\lim _{n \rightarrow \infty} S_{b} x_{b_{n}}=\frac{2}{3}$, hence the pair $\left(A_{b}, S_{b}\right)$ satisfies the $b$-(E.A)-property.
Clearly the pairs $\left(A_{b}, S_{b}\right)$ and $\left(B_{b}, T_{b}\right)$ are weakly compatible.
We take $\lambda_{1}=\frac{10}{51}, \lambda_{2}=\frac{1}{4}, \lambda_{3}=\frac{1}{2}$. Then clearly $\lambda_{1}+s \lambda_{2}+s^{2} \lambda_{3} \leq 1$.
With out loss generality, we assume that $x \geq y$.
Case (i). $x_{b}, y_{b} \in\left(0, \frac{2}{3}\right)$.
$d_{b}\left(A_{b} x_{b}, B_{b} y_{b}\right)=\frac{12}{25}, d_{b}\left(S_{b} x_{b}, T_{b} y_{b}\right)=\frac{12}{25}, d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right)=\frac{12}{25}$,
$d_{b}\left(T_{b} y_{b}, B_{b} y_{b}\right)=\frac{12}{25}, d_{b}\left(S_{b} x_{b}, B_{b} y_{b}\right)=\frac{11}{15}, d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right)=\frac{99}{100}+\frac{x_{b}+y_{b}}{200}$,
We now consider

$$
\begin{aligned}
& s^{4}\left[d_{b}\left(A_{b} x_{b}, B_{b} y_{b}\right)\right]^{2}=\left(\frac{25}{24}\right)^{4}\left(\frac{12}{25}\right)^{2} \\
& \leq \frac{10}{51}\left(\frac{12}{25}\right)^{2}+\frac{1}{8}\left(\left(\frac{12}{25}\right)\left(\frac{99}{100}+\frac{x_{b}+y_{b}}{200}\right)\right)+\frac{1}{4}\left(\left(\frac{11}{15}\right)\left(\frac{99}{100}+\frac{x_{b}+y_{b}}{200}\right)\right) \\
& \leq \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} x_{b}, T_{b} y_{b}\right)\right]^{2},\left(d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right)\right]^{\prime},\left[d_{b}\left(T_{b} T_{b}, B_{b} y_{b}\right)\right]^{2}\right\} \\
&+\lambda_{2} \max \left\{\frac{d_{b}\left(S_{b} x_{b} x_{b}, A_{b} x_{b}\right) d_{b}\left(S_{b} x_{b}, B_{b} y_{b}\right)}{2}, \frac{d_{b}\left(T_{b} y_{b}, B_{b} y_{b}\right) d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right)}{2}\right\} \\
&+\lambda_{3} \frac{d_{b}\left(S_{b} x_{b}, B_{b} y_{b} d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right)\right.}{2} .
\end{aligned}
$$

Case (ii). $x_{b}, y_{b} \in\left(\frac{2}{3}, 1\right]$.
$d_{b}\left(A_{b} x_{b}, B_{b} y_{b}\right)=0$. In this case the inequality (1) trivially holds.

Case (iii). $x_{b} \in\left(\frac{2}{3}, 1\right], y_{b} \in\left(0, \frac{2}{3}\right)$.
$d_{b}\left(A_{b} x_{b}, B_{b} y_{b}\right)=\frac{12}{25}, d_{b}\left(S_{b} x_{b}, T_{b} y_{b}\right)=\frac{99}{1100}+\frac{x_{b}+y_{b}}{200}, d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right)=\frac{99+x_{b}}{100}$,
$d_{b}\left(T_{b} y_{b}, B_{b} y_{b}\right)=\frac{12}{25}, d_{b}\left(S_{b} x_{b}, B_{b} y_{b}\right)=\frac{12}{25}, d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right)=\frac{99}{100}+\frac{x_{b}+y_{b}}{200}$,
We now consider

$$
\begin{aligned}
& s^{4}\left[d_{b}\left(A_{b} x_{b}, B_{b} y_{b}\right)\right]^{2}=\left(\frac{25}{24}\right)^{4}\left(\frac{12}{25}\right)^{2} \\
& \leq\left.\frac{10}{51}\left(\frac{99+x_{b}}{100}\right)^{2}+\frac{1}{8}\left(\left(\frac{99+x_{b}}{100}\right)\left(\frac{12}{25}\right)\right)+\frac{1}{4}\left(\frac{12}{25}\right)\right)\left(\left(\frac{99}{100}+\frac{x_{b}+y_{b}}{200}\right)\right. \\
& \leq \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} x_{b}, T_{b} y_{b}\right)\right]^{2},\left[d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right)\right]^{2},\left[d_{b}\left(T_{b} y_{b}, B_{b} y_{b}\right)\right]^{2}\right\} \\
&+\lambda_{2} \max \left\{\frac{d_{b}\left(S_{b} x_{b}, A_{b} x_{b}\right) d_{b}\left(S_{b} x_{b}, B_{b} y_{b}\right)}{2}, \frac{d_{b}\left(T_{b} y_{b}, B_{b} y_{b}\right) d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right)}{2}\right\} \\
&+\lambda_{3} \frac{d_{b}\left(S_{b} x_{b}, B_{b} y_{b}\right) d_{b}\left(T_{b} y_{b}, A_{b} x_{b}\right)}{2} .
\end{aligned}
$$

Therefore $A_{b}, B_{b}, S_{b}$ and $T_{b}$ satisfy all the hypotheses of Theorem 2.2 and $\frac{2}{3}$ is the unique common fixed point in $X_{b}$.

Corolary 3.1. Let $\left\{A_{n}\right\}_{n=1}^{\infty}, S_{b}$ and $T_{b}$ be selfmaps on a complete b-metric space ( $X_{b}, d_{b}$ ) satisfying $A_{1} \subseteq S_{b}\left(X_{b}\right)$ and $A_{1} \subseteq T_{b}\left(X_{b}\right)$. Assume that there exist positive reals $\lambda_{1}, \lambda_{2}, \lambda_{3}$ with $\lambda_{1}+s \lambda_{2}+s^{2} \lambda_{3} \leq 1$ such that

$$
\begin{align*}
& s^{4}\left[d_{b}\left(A_{1} x_{b}, A_{j} y_{b}\right)\right]^{2} \leq \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} x_{b}, T_{b} y_{b}\right)\right]^{2},\left[d_{b}\left(S_{b} x_{b}, A_{1} x_{b}\right)\right]^{2},\left[d_{b}\left(T_{b} y_{b}, A_{j} y_{b}\right)\right]^{2}\right\} \\
& +\lambda_{2} \max \left\{\frac{d_{b}\left(S_{b} x_{b}, A_{1} x\right) d_{b}\left(S_{b} x_{b}, A_{j} y_{b}\right)}{2}, \frac{d_{b}\left(T_{b} y_{b}, A_{j} y\right) d_{b}\left(T_{b} y_{b}, A_{1} x_{b}\right)}{2}\right\} \\
& +\lambda_{3} \frac{d_{b}\left(S_{b} x_{b}, A_{j} y_{b}\right) d_{b}\left(T_{b} y_{b}, A_{1} x_{b}\right)}{2} . \tag{15}
\end{align*}
$$

for all $x_{b}, y_{b} \in X_{b}$ and $j=1,2,3, \ldots$.. If the pairs $\left(A_{1}, S_{b}\right)$ and $\left(A_{1}, T_{b}\right)$ are weakly compatible and one of the range sets $A_{1}\left(X_{b}\right), S_{b}\left(X_{b}\right)$ and $T_{b}\left(X_{b}\right)$ is closed, then $\left\{A_{n}\right\}_{n=1}^{\infty}, S_{b}$ and $T_{b}$ have a unique common fixed point in $X_{b}$.

Proof. Under the assumptions on $A_{1}, S_{b}$ and $T_{b}$, the existence of common fixed point $z_{b}$ of $A_{1}, S_{b}$ and $T_{b}$ follows by choosing $A_{b}=B_{b}=A_{1}$ in Theorem 2.1.
Therefore $A_{1} z_{b}=S_{b} z_{b}=T_{b} z_{b}=z_{b}$.
Now, let $j \in \mathbb{N}$ with $j \neq 1$.
We now consider

$$
\begin{align*}
s^{4}\left[d_{b}\left(z_{b}, A_{j} z_{b}\right)\right]^{2}= & s^{4}\left[d_{b}\left(A_{1} z_{b}, A_{j} z_{b}\right)\right]^{2} \\
\leq & \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} z_{b}, T_{b} z_{b}\right)\right)^{2},\left[d_{b}\left(S_{b} z_{b}, A_{1} z_{b}\right)\right]^{2},\left[d_{b}\left(T_{b} z_{b}, A_{j} z_{b}\right)\right]^{2}\right\} \\
& +\lambda_{2} \max ^{2}\left\{\frac{d_{b}\left(S_{b} z_{b} A_{1} A_{1} z_{b}\right) d_{b}\left(S_{b} z_{b}, A_{j} z_{b}\right)}{}, \frac{d_{b}\left(T_{b} z_{b}, A_{j} z_{b}\right) d_{b}\left(T_{b} z_{b}, A_{1} z_{b}\right)}{2}\right\} \\
& +\lambda_{3} \frac{d_{b}\left(S_{b} z_{b}, A_{j} z_{b}\right) d_{b}\left(T_{b} z_{b}, A_{1} z_{b}\right)}{2} . \tag{16}
\end{align*}
$$

From the inequality (16), we have
$s^{4}\left[d_{b}\left(z_{b}, A_{j} z_{b}\right)\right]^{2} \leq \lambda_{1}\left[d_{b}\left(z_{b}, A_{j} z_{b}\right)\right]^{2}$
which implies that $\left(s^{4}-\lambda_{1}\right)\left[d_{b}\left(z_{b}, A_{j} z_{b}\right)\right]^{2} \leq 0$.
Since $\left(s^{4}-\lambda_{1}\right) \geq 0$, we have $A_{j} z_{b}=z_{b}$ for $j=1,2,3, \ldots$ and uniqueness of common fixed point follows from the inequality (15).

Therefore $\left\{A_{n}\right\}_{n=1}^{\infty}, S_{b}$ and $T_{b}$ have a unique common fixed point in $X_{b}$.

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Corolary 3.2. Let $\left\{A_{n}\right\}_{n=1}^{\infty}, S_{b}$ and $T_{b}$ be selfmaps on a b-metric space ( $X_{b}, d_{b}$ ) satisfy the conditions $A_{1} \subseteq S_{b}\left(X_{b}\right), A_{1} \subseteq T_{b}\left(X_{b}\right)$ and (15). If one of the pairs $\left(A_{1}, S_{b}\right)$ and $\left(A_{1}, T_{b}\right)$ satisfies the $b$-(E.A)-property and that one of the subspace $A_{1}(X), S_{b}\left(X_{b}\right)$ or $T_{b}\left(X_{b}\right)$ is $b$-closed in $X_{b}$. Then the pairs $\left(A_{1}, S_{b}\right)$ and $\left(A_{1}, T_{b}\right)$ have a point of coincidence in $X_{b}$. Moreover, if the pairs $\left(A_{1}, S_{b}\right)$ and $\left(A_{1}, T_{b}\right)$ are weakly compatible, then $\left\{A_{n}\right\}_{n=1}^{\infty}, S_{b}$ and $T_{b}$ have a unique common fixed point in $X_{b}$.

Proof. Under the assumptions on $A_{1}, S_{b}$ and $T_{b}$, the existence of common fixed point $z_{b}$ of $A_{1}, S_{b}$ and $T_{b}$ follows by choosing $A_{b}=B_{b}=A_{1}$ in Theorem 2.2.
Therefore $A_{1} z_{b}=S_{b} z_{b}=T_{b} z_{b}=z_{b}$.
Now, let $j \in \mathbb{N}$ with $j \neq 1$.
We now consider

$$
\begin{align*}
& s^{4}\left[d_{b}\left(z_{b}, A_{j} z_{b}\right)\right]^{2}= \\
& \leq s^{4}\left[d_{b}\left(A_{1} z_{b}, A_{j} z_{b}\right)\right]^{2} \\
& \leq \lambda_{1} \max \left\{\left[d_{b}\left(S_{b} z_{b}, T_{b} z_{b}\right)\right]^{2},\left[d_{b}\left(S_{b} z_{b}, A_{1} z_{b}\right)\right]^{2},\left[d_{b}\left(T_{b} z_{b}, A_{j} z_{b}\right)\right]^{2}\right\} \\
& \quad+\lambda_{2} \max \left\{\frac{d_{b}\left(S_{b} z_{b}, A_{1} z_{b}\right) d_{b}\left(S_{b} z_{b}, A_{j} z_{b}\right)}{2}, \frac{d_{b}\left(T_{b} z_{b}, A_{j} z_{b}\right) d_{b}\left(T_{b} z_{b}, A_{1} z_{b}\right)}{2}\right\}  \tag{17}\\
& \\
& \quad+\lambda_{3} \frac{d_{b}\left(S_{b} z_{b}, A_{j} z_{b}\right) d_{b}\left(T_{b} z_{b}, A_{1} z_{b}\right)}{2}
\end{align*}
$$

From the inequality (17), we have
$s^{4}\left[d_{b}\left(z_{b}, A_{j} z_{b}\right)\right]^{2} \leq \lambda_{1}\left[d_{b}\left(z_{b}, A_{j} z_{b}\right)\right]^{2}$ which implies that $\left(s^{4}-\lambda_{1}\right)\left[d_{b}\left(z_{b}, A_{j} z_{b}\right)\right]^{2} \leq 0$.
Since $\left(s^{4}-\lambda_{1}\right) \geq 0$, we have $A_{j} z_{b}=z_{b}$ for $j=1,2,3, \ldots$ and uniqueness of common fixed point follows from the inequality (15).

Therefore $\left\{A_{n}\right\}_{n=1}^{\infty}, S_{b}$ and $T_{b}$ have a unique common fixed point in $X_{b}$.

## 4 Conclusion

In this paper, we introduced generalized contraction for two pairs of selfmaps in complete $b$-metric spaces and proved the existence and of common fixed points. Our results extend/generalize the known results that are available in the literature. A sequence of selfmaps is added as an extension of the same. We provided examples in support of our results and some corollaries to our results are presented.
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