

1 **Process and Outcome-based Evaluation between Virtual Really-driven and Traditional** 2 **Construction Safety Training**

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18

19 **Abstract**

20 The emerging digital technologies such as virtual reality (VR) provide an alternative platform
21 for construction safety training. In order to explore how digital-driven technologies affect the
22 effectiveness of safety training, there is a need to empirically test the differences in
23 performance between digital 3D/VR safety training and traditional 2D/paper approach. This
24 research conducted a performance evaluation that emphasises both the training process and
25 learning outcomes of trainees based on researchers' self-developed immersive construction
26 safety training platform. Data related to physiological indicators such as skin resistance were
27 collected to measure safety performance before and after the training. The detailed
28 measurement indicators included nine categories (e.g., immersion, inspiration) to form a
29 holistic list of evaluation dimensions. The findings revealed that VR-driven immersive safety
30 training outperformed the traditional way for trainees in terms of both process and outcome-
31 based indicators. Results confirmed that safety training was no longer constrained by
32 understanding or memorizing 2D information (texts and images). Instead, trainees experienced

33 a stronger sense of embodied cognition through the immersive experience and multi-sensory
34 engagement by interacting with the VR-driven system. By engaging the theory of embodied
35 cognition, this research provides both the empirical evidence and in-depth analysis of how
36 immersive virtual safety training outperforms traditional training in terms of both training
37 process and outcomes.

38 **Keywords:** construction safety; embodied cognition; safety training; virtual reality;
39 immersive technology; hazard recognition

40 **1. Introduction**

41 Construction industry faces significant challenges including safety issues, in terms that
42 construction has the highest number of injuries crossing all industries (Adami et al., 2021).
43 Safety training can enhance workers' safety awareness and capability of handling danger
44 (Williams et al., 2010), and is considered a key approach to reduce safety risks. Existing safety
45 training mainly relies on traditional techniques such as lecturing, toolbox meeting, and video
46 or textbook learning. One of the significant limitations is that it is difficult to fully engage
47 workers in the learning environments created by these traditional techniques. Trainees could
48 have limited engagement in a passive learning mode. The information capturing for further
49 processing and forming longer-term memory of safety scenarios could be hampered due to lack
50 of interaction and insufficient site experience. Learning by doing does have pedagogical values.
51 However, educating workers by placing them into hazardous real-life jobsites is expensive and
52 unethical.

53 The technological evolvement in the era of Industry 4.0 has enabled a highly immersive and
54 interactive experience for learners. Construction safety training has also been involved with the
55 adoption of emerging digital technologies such as virtual reality (VR). Existing studies (Eiris
56 et al.,2018; Nykänen et al.,2020) adopting virtual or immersive technologies for construction
57 safety training were largely limited to training outcomes or trainees' subjective evaluation of

58 these technologies, but lack the comprehensive or empirical evidences to evaluate the
59 effectiveness of immersive technology as compared to the traditional training mode. The other
60 limitation from existing VR-driven studies (e.g., Tao et al., 2019) is that they had been limited
61 to a single feature of VR, such as immersion, but without a more comprehensive evaluation of
62 other features, for instance, first-person experience, degree of fun, and interaction, etc, all of
63 which are essential components of gamification (Mouaheb, et al. 2012) and can increase
64 player/user participation and engagement during learning (Landers, 2014). There has been
65 insufficient investigation based on a multi-criteria framework to evaluate the effects of VR for
66 safety training. Furthermore, the mechanism of learners' cognitive process in the VR-driven
67 training, especially how it differs from the traditional training, has been underdeveloped.

68 Several prior studies (e.g., Li et al., 2021; Zhang et al., 2021a) applying VR for safety-
69 related training crossing industries. It was believed by Adami et al. (2021) that previous studies
70 adopting VRs for training purposed had not sufficiently engaged learning theories but simply
71 technical aspects of the prototypes. VR could more effectively engage learners with bodily
72 experience, which is widely lacking in traditional learning environments. It is theoretically
73 hypothesized that adopting VR in safety training could enhance the training effectiveness by
74 increasing learners' embodied engagement. Embodied learning is viewed as educationally
75 significant based on facts that the individual should be treated as a whole being to be permitted
76 to experience themselves as a holistic, synthesized, acting, feeling, thinking being-in-the-world,
77 instead of being separated between physical and mental activities (Stolz, 2015). It was
78 confirmed that the heuristic role of immersion in VR is linked to educational affordances such
79 as empathy and embodied cognition (Shin, 2017). There is a need to explore how embodied
80 cognition plays a role in VR-driven construction safety training.

81 This study investigates the mechanism that causes the differences between VR-driven and
82 traditional training for construction safety. Both objective and subject data are collected in the

83 empirical study. Objective data are based on: physiological reactions of learners or trainees
84 during the training process; and the task performance following training by recognising safety
85 hazards. Subjective data are collected using a questionnaire following each individual's VR-
86 driven experiment to measure the effectiveness of the training process and the follow-up
87 impacts in a multi-criteria indicator system. This study echoes Adami et al. (2021) that
88 theoretical background should be engaged in applying VR rather than technical aspects alone.
89 The novelty of this study lies in that: (a) it deploys both objective and subjective data collection
90 approaches; (b) it engages both process and outcome of safety training in evaluating the
91 effectiveness of VR-based training of safety hazard recognition; and finally (c) it further
92 employs the theory of embodied cognition to conduct an in-depth qualitative analysis of how
93 VR-driven training differs from the traditional training of construction safety in terms of
94 effectiveness. By addressing the question of how VR as the alternative platform affects training
95 process and outcomes, the findings of this study provide both empirical and theoretical guides
96 for construction industry in adopting VR or other immersive technologies for safety training.

97 **2. Literature Review**

98 **2.1. Individuals' recognition of construction safety hazard**

99 Safety perception is considered a key proactive indicator in construction safety management
100 (Chen and Jin, 2013). It consists of perception towards site hazards (Han et al., 2019a). Hazard
101 recognition of individuals engages mental activities and cognitive load (Han et al., 2021).
102 Understanding the mental representations used for hazard recognition helps developing
103 inspection strategies for effective safety management (Chong et al., 2021). Early-stage
104 intervention is one method to improve the hazard recognition performance of construction
105 employees (Albert et al., 2014). The training of hazard detection or recognition is widely
106 adopted as the early-stage intervention aiming to improve workers' safety performance (Albert
107 and Routh, 2021). Traditional training of hazard recognition in construction includes observing

108 images. These images could be static, partially animated, or fully animated (i.e., video) as
109 studied by Eiris et al. (2021). The experimental comparisons of the effects of three different
110 image types on hazard recognition revealed no significant differences in training effectiveness
111 in terms of individuals' positive attitudes, engagement, and sense of being transported to the
112 scenario location (Eiris et al., 2021). Albert and Routh (2021) proposed specific training
113 intervention elements that could result in superior safety performance and outcomes, including
114 integration of visual cues to guide hazard recognition, immersive experiences in virtual
115 environments, personalization of training experiences, and testing and feedback, etc.

116 Prior studies (e.g., Chen and Jin, 2013; Han et al., 2019a) had widely adopted a questionnaire
117 survey approach to ask construction employees to self-evaluate safety hazard-related
118 perception. The questionnaire survey approach alone suffers from the drawback that
119 participants may lack situational engagement through site-based scenarios when filling the
120 questionnaire (Han et al., 2021) with potential consequences of relying on their memory.
121 Emerging digital and visualisation technologies with an experimental approach such as eye-
122 tracking wearable devices (Chong et al., 2021) can fulfil this limitation. Combining the
123 traditional questionnaire survey with digitisation-driven experiments can be found in several
124 studies from recent years studying influence factors on hazard recognition performance, such
125 as Han et al. (2021) and Kim et al. (2021). These influence factors on hazard recognition
126 include personal traits (e.g., prior site experience) as found by Hasanzadeh et al. (2016), site
127 conditions such as lighting (Han et al., 2020), and task mode of employees (Han et al., 2021).
128 These aforementioned studies (e.g., Bhoir et al., 2015; Hasanzadeh et al., 2016) recruited
129 students with similar academic and practical experience as participants in experimental
130 research adopting digital devices for safety performance measurements. The rationale of
131 recruiting university students instead of site employees was justified in Han et al. (2020) and

132 Comu et al. (2021), i.e., to exclude the effects of personal traits and to focus on the studied
133 variable or influence factors.

134 **2.2.Digitalisation-driven immersion training**

135 VR allows users to create, explore, and interact within environments that are perceived to
136 be nearly reality (Repetto et al., 2016). VR-based safety training provides a promising
137 alternative to the traditional passive training approach (Nykänen et al., 2020). Izatt et al. (2014)
138 described the visualisation technology with an interactive VR-based platform and stated that
139 the user interface was suitable for physics education. Using a virtual platform for training
140 firefighters' on wayfinding in search of victims in a burning building, Shi et al. (2021) found
141 that the virtual platform added value by allowing firefighters to experience disorientation and
142 use their existing knowledge to find victims in an unfamiliar building. Also applying VR for
143 emergency evacuation such as under fire, Zhang et al. (2021b) discussed the value of VR in
144 complex building path planning in terms of evacuation simulation. Applying VR platform for
145 construction pipeline operation training, Shi et al. (2020b) found that compared to trainees
146 recalling information from 2D drawing, those trained through 3D and VR outperformed in
147 operation tasks. By adopting a 360-degree panorama virtual training environment for fall
148 hazard recognition, Eiris et al. (2020) found that safety immersive storytelling provided an
149 analogous outcome compared to the traditional training, with reduced time required and a
150 stronger sense of presence for trainees. So far, there has been limited amount of empirically in-
151 depth research on adopting immersive and interactive VR platform in construction safety
152 training, specifically, on how the visualisation technology affects the training effectiveness of
153 recognising site hazards. The training effectiveness could be measured by both process (e.g.,
154 cognitive mechanism), and outcomes such as task performance as measured by Shi et al. (2020)
155 in construction operational training.

156 **2.3.Embodied cognition**

157 Embodied cognition is a cross-disciplinary (e.g., neuroscience, psychology) terminology
158 following the assumption that the body functions as a constituent of the mind rather than a
159 passive perceiver and actor serving the mind (Leitan and Chaffey, 2014). Bodily states and
160 modality-specific systems for perception and action underlie information processing, and the
161 embodiment contributes to multiple aspects and effects of mental activities (Foglia and Wilson,
162 2013). It is a proposed theory in cognitive science that cognition is embodied (Wilson and
163 Golonka, 2013). Prior experimental studies claimed that cognition is influenced by the body
164 states (Eerland et al., 2011), and the environment (Adam and Galinsky, 2012). It is stated that
165 the abstract cognitive states are grounded in the states of the body (Miles et al., 2010). Kilteni
166 et al. (2012) proposed that the sense of embodiment consisted of three subcomponents, namely
167 sense of self-location, sense of agency, and sense of body ownership. Consequently, VR was
168 suggested as a means to enhance the sense of embodiment through the three subcomponents
169 by Kilteni et al. (2012). In this regard, the immersive environment created by VR works as the
170 self-location; VR-based user platform or interface serves as the agency; and users'
171 physiological reactions reflects the body engagement.

172 VR offers immersion, embodiment, and presence through gaming (Evans and Rzeszewski,
173 2020). It has been found that immersion in a VR-based game setup increased users'
174 psychological arousal (Yao and Kim, 2019). Awada et al. (2021), by applying VR experiments
175 in shooting studies, found out that VR induced emotional arousal and increased users' heart
176 rate. The study of Steidl et al. (2011) on cognitive skill learning suggested that emotional
177 arousal could in parallel, enhance the neural systems that support procedural learning and its
178 declarative context. Shim (2018) investigated the user experience in VR by exploring the
179 immersive storytelling context in a VR model that integrated presence, flow, empathy, and
180 embodiment. It was suggested that the cognitive processes were significantly correlated to
181 users' empathy and embodiment. In the VR-driven learning environment, Shin (2017) found

182 out that embodied cognition process is shaped by learners' perception and context. The study
183 of Shin (2017) laid the foundation for VR technologies as a heuristic assessment tool for a user
184 embodied cognitive process.

185 **3. Methodology**

186 This research was based on the comparative studies of safety training performance adopting
187 two different approaches, namely the VR-driven immersive training and the traditional
188 textbook learning. The training performance was measured by learners / trainees' recognition
189 of safety hazards in given construction site scenarios. The research team self-developed the
190 whole VR-based immersive training system that underwent trials and tests as seen in the
191 workflow of the study described in Figure 1. According to Figure 1, this study was divided into
192 three major phases. In the first phase defined as pre-experimental preparation, the safety hazard
193 scenarios were obtained by the research team from real-world construction sites. The research
194 started from establishing safety hazard scenarios, which would be assigned to both groups of
195 trainees, i.e., traditional textbook learning in a classroom, and the VR-based immersive safety
196 training; in the second phase defined as comparative training, the two groups of trainees were
197 arranged in a parallel way to receive their safety training, but underwent consistent monitoring
198 before, during and after the training. Three major measurements were taken for each trainee,
199 namely physiological reaction during training in terms of skin resistance, learning performance
200 measured by hazard identification, and self-reflection by filling a post-training questionnaire;
201 in the third phase defined as post-experiment analyses, the three major measurements enabled
202 comprehensive comparisons of the two different safety training approaches, and further
203 exploration by embedding the Embodied Cognition Theory defined in Foglia and Wilson
204 (2013).

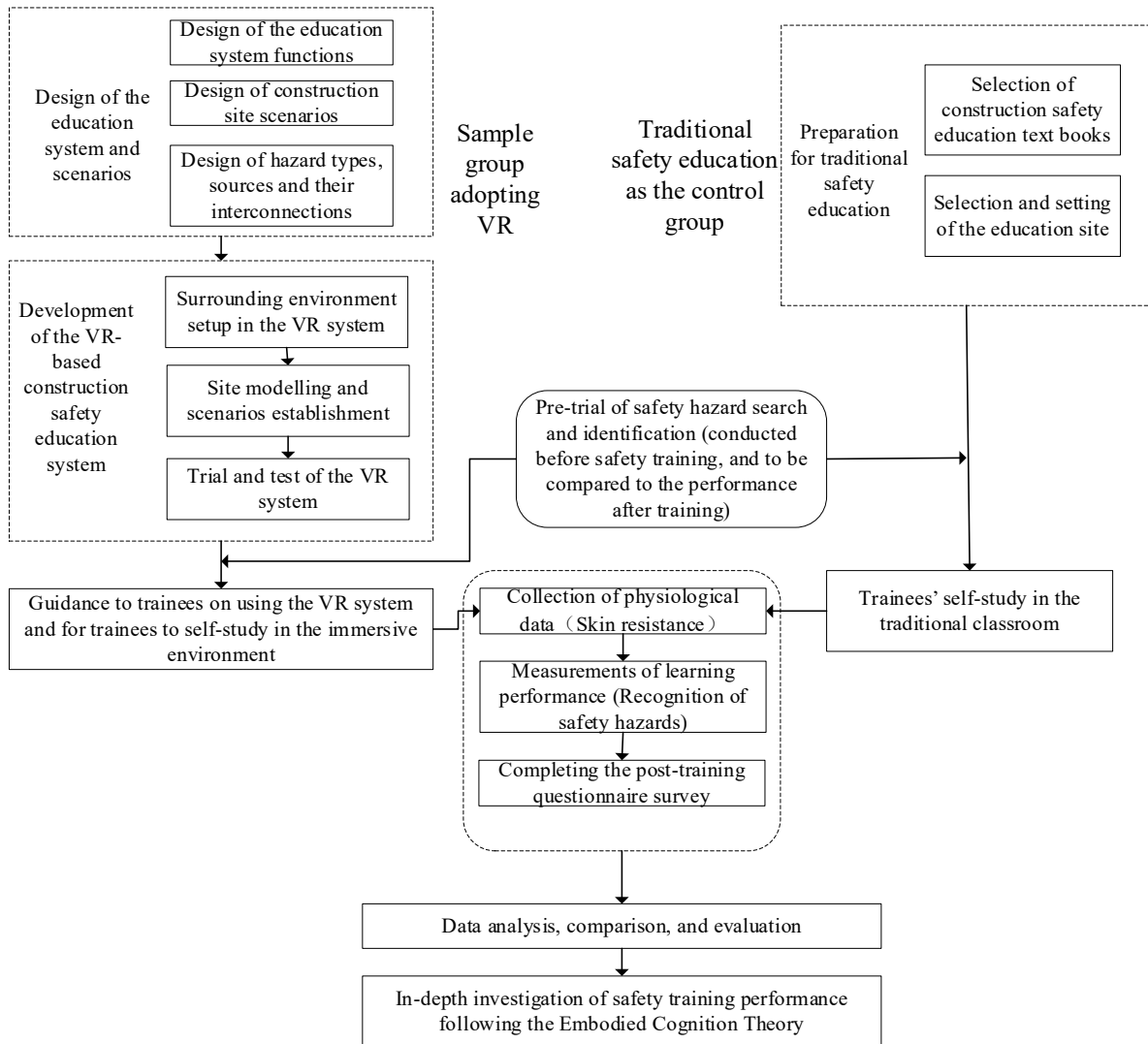


Figure 1. Workflow of the research

3.1. Experimental measurements

This experimental study measured the safety training effectiveness based on both the training procedure and endpoint performance by comparing the two aforementioned approaches. Four major dimensions were defined to compare the training effectiveness between VR-based immersive training and traditional training, namely self-evaluation of learning process, endpoint evaluation of learning impacts, physiological reaction, and learning performance.

The learning process and learners' endpoint evaluation were measured through a post-training questionnaire, involving a total of nine indicators. The learning process was measured

216 by seven indicators, namely openness, flexibility, immersion, ease of learning, comfort,
217 interactive engagement, and degree of fun. These indicators were generated from emotional
218 dimension related theories (Schmid K et al., 2011; Steidl et al., 2011; Jhean-Larose et al., 2014),
219 which describe that highly fluctuating emotions can keep the human brain at a high level of
220 arousal and that the high arousal could enhance the learning effects. These seven indicators
221 were used to measure individual trainees' evaluation of the learning environment and manners.
222 Endpoint evaluation of learning effects was defined by the proactiveness and degree of
223 inspiration, which was defined to measure the effectiveness of the training approach on driving
224 the learning desire.

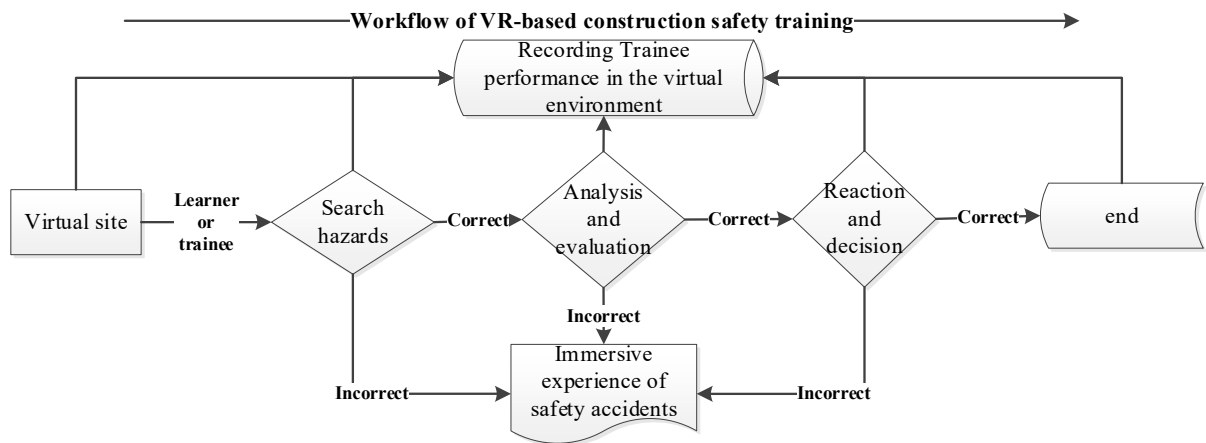
225 Existing studies (e.g., Deng et al., 2012; Zhao et al., 2021) indicated that several
226 physiological indicators such as skin resistance, respiratory data, heart rate, pulse rate, and
227 body temperature could reflect human beings' mental status. Among these indicators, heart
228 rate, pulse data, and respiratory value are consistently related to the individual's nerves and
229 significantly affected by the individual's ability to tolerate mental stress (Yang, 2021). Skin
230 resistance is a physiological indicator to expressly evaluate an individual trainee's mental status.
231 According to Ye (2021), skin resistance changes are caused by: 1) variation of human body's
232 sweat secretion rate due to external environmental and physical emotional stimulus, and 2)
233 changes of contraction and relaxation of blood vessels caused by nervous system activity.
234 Compared to other physiological indicators such as blood pressure, heart rate and body
235 temperature, skin resistance is more sensible to individuals' mental status variation
236 (Steinberger et al., 2017). It is significantly affected by emotional status and linearly related to
237 the level of emotional arousal (Shi, 2017). Emotional arousal would result in noticeable skin
238 resistance change (Bradley and Lang, 2000). Therefore, skin resistance is often adopted as a
239 physiological indicator in emotional arousal experiments (Reimer & Mehler, 2011). This
240 research adopted skin resistance as the measurement for trainees' emotional arousal.

241 Finally, the learning performance was measured by the performance changes of recognising
 242 safety hazards before and after the safety training. The two indicators in terms of accuracy and
 243 time spent in detecting safety hazards were adopted for measuring the learning performance.

244 **3.2.Experimental setup**

245 Two approaches to safety training were provided for the comparative study as shown in
 246 Figure 1. The VR-based immersive training was designed as the alternative to traditional
 247 textbook-based learning. The procedure of the VR-based training system developed by the
 248 research team as illustrated in Figure 2, was comprised of multiple aspects of the immersive
 249 engagement process, including virtual construction site tour to search hazards, identifying
 250 hazards, hazard analysis and evaluation, reaction and decision-making in response to hazards,
 251 and individual performance being recorded. As seen in Figure 2, any of the steps related to
 252 hazard detection, analysis, or reaction would cause virtual safety accidents.

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254

255 Figure 2. Procedure of the VR-based construction safety training

256 Extending from the previously developed virtual safety training platform (Han et al., 2021)
 257 by the researchers, the three hazard-related activities causing immersive accidents illustrated
 258 in Figure 2 can be further demonstrated by using the fall from uncovered hole as an example.
 259 In the VR-based training platform, trainee must first click “Yes” to correctly identify the hazard
 260 when the uncovered hole is seen. Then the trainee is asked to answer two questions at the

261 analysis and evaluation stage towards the identified hazard, i.e., what is the danger level of the
262 hazard, and what types of accidents could result from the hazard. Finally, the trainee is required
263 to make a decision to handle the hazard, such as “remind myself on this hazard”, “wait around
264 the hole and inform others passing by”, and “report it to the site safety staff”, etc. These
265 questions and decisions are provided in the VR platform in the form of multi-choice options.
266 The responses or answers selected by the trainee are then recorded as task performance. The
267 VR system automatically evaluates and scores the individual trainee’s task performance, so the
268 trainee is provided with the feedback afterwards. The VR-based immersive training system
269 described in Figures 1 and 2 and shown in Figure 3 was supported by these hardware sets,
270 including: Dell G7 laptop; HTC Vive VR headset developed (HTC Corporation, 2020); VIVE
271 EYE PRO; and Avatars. Additionally, HKR-11C+ sensor shown in Figure 4 was adopted for
272 measuring the skin resistance signal change. The sensor, with a range from 100K to 2.5M,
273 measurement accuracy at 2.5K, and error at +/-2%, met the technical requirements for this
274 study.



Figure 3. VR experimental system



Figure 4. Skin resistance sensor

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276 **3.3.Experimental participants**

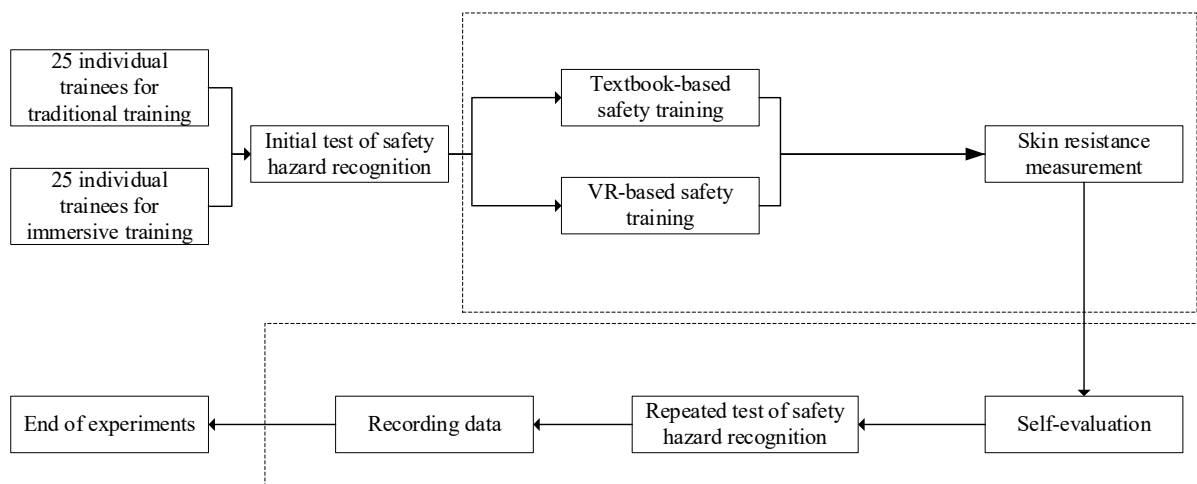
277 Experimental participants were recruited from Jiangsu University students in the disciplines
278 of construction management or civil engineering but with little site experience. Random
279 sampling procedure and methods were adopted as consistent in the earlier studies conducting

280 immersive-based safety hazard recognition tests (Han et al., 2020b; Han et al., 2021), which
281 also recruited students from the same disciplines. This rationale of recruiting students only
282 instead of other participants from different backgrounds could be justified by Comu et al. (2021)
283 that different participants, as affected by their field experience, education and site role, would
284 perform significantly different in safety training. In this study, participants were divided into
285 two groups, namely traditional safety training and VR-based immersive training. Recruiting
286 university students instead of construction professionals for this study could also be justified
287 by another earlier study of Kalyuga (2013), who revealed that learners' prior knowledge
288 significantly affected learning effects. It was indicated that experienced site professionals, with
289 more prior knowledge in construction site, would experience varied learning effects from VR-
290 based training, because of the differed working memory and cognitive load caused by the
291 multimedia learning defined by Kalyuga (2013). Several personal traits such as prior
292 knowledge, age, and computer skills as identified in different studies (e.g., Lim and Morris,
293 2009; Kintu et al, 2016; Alk and Temizel, 2018) could cause the varied learning performance.
294 Therefore, in order to minimise the effects of personal traits on trainees' learning performance,
295 university students with a similar experience and knowledge level of construction activities
296 were selected as experimental participants instead of construction professionals. Conducting
297 the experimental studies engaging human participants for this study gained the approval from
298 the University's Research Ethics approval beforehand. Before starting the safety training, each
299 participant was asked to sign the consent form. A total of 52 students agreed to participate, and
300 50 of them participated with valid skin resistance data collected. That was because out of the
301 52 students initially recruited, two students had high ranges of bodily movement during safety
302 training, causing their skin resistance measurements abnormally fluctuating. Therefore, these
303 two participants' data recorded had to be abandoned. The 50 valid participants were divided
304 evenly into the two training groups (i.e., traditional and VR-based training approaches). The

305 sample size of this study was considered reasonable both statistically and practically. Similar
 306 sample sizes for immersive-based experimental studies can be found in Leder et al. (2018),
 307 Han et al. (2020b), and Nie et al. (2021), where the sample sizes ranged from 40 to 53.

308 3.4. Experimental procedure

309 The experimental procedure is illustrated in Figure 5, following the five steps described
 310 from Sections 3.4.1 to 3.4.5.



311

312 Figure 5. Description of the safety training process

313 A pilot study was conducted before formal experiments. Three pilot participants were
 314 recruited for the trials of the VR experimental system shown in Figure 3. Research assistants
 315 guided each participant in wearing VR hardware and the correct operation of avatars. The
 316 virtual site tasks completed by each participant was recorded, including the time consumed and
 317 the participant self-movement during the immersive site walkthrough. These recorded data
 318 during the pilot study provided feedback on the practicality of the VR system for the later
 319 formal experimental studies. Figure 6 demonstrates examples of the pilot study during
 320 participants' virtual site work.



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Figure 6. Examples of immersive site activities during the pilot study

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The pilot study showed the average time of completion for trainees was 5 minutes and 36 seconds. Researchers decided that 10 minutes were suitable as the time allowed for each trainee in completing the site tasks. It was also found that participants' large range of body movements would affect the data collection of skin resistance. It was hence decided that when conducting immersive site work (i.e., detecting and evaluating site safety hazards), participants' hand, which was wearing skin resistance sensor during the experiment, should be placed on the desk stably.

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Following the pilot study of the whole immersive system trial and user feedback, the formal experimental workflow was standardised. Before each trainee started the formal immersive task, the laboratory staff would explain the experimental steps to ensure that the whole process was clear. It was also pre-planned by the researchers that any individual trainee's data would not be included in case of any interruptions occurring during the experiment or if the trainee's any personal reasons to discontinue the immersive task. The whole experiment process for each trainee consisted of the following five sequential steps: experimental preparation; tests of

337 identifying safety hazards; measurements of physiological indicators during safety training;
338 post-training test of safety hazard identification; post-experiment survey.

339 3.4.1. Experimental preparation

340 Two different safety training rooms were set corresponding to the two different training
341 approaches. One room was prepared with the traditional safety training materials, and the other
342 was set with VR-related immersive system. All other settings of the room, for instance, room
343 environment, size, and safety training contents, were kept the same. Only one trainee would be
344 allowed into the room at one time. Each trainee or participant would enter one of the two rooms
345 depending on the education approach that had been priorly decided randomly by draws.
346 Subsequently, each participant would be guided to sit quietly, with the left hand's index and
347 middle fingers wearing the skin resistance sensors.

348 3.4.2. Tests of identifying safety hazards

349 Before the formal safety training, each trainee was arranged with the pre-test of identifying
350 hazards from given site scenarios. Laboratory staff recorded the time taken to complete
351 searching hazards in 16 site photos and calculated the accuracy of hazard detection for each
352 trainee. These site photos, part of which are shown in Figure 7, were collected from real
353 construction sites. These photos underwent peer safety experts validation following the
354 consistent procedure described in Han et al. (2020b). Basically, the scenes shown in selected
355 photos were all related to typical safety hazards (e.g., lack of fall protection, improperly
356 extended scaffolding) which did not conform to safety regulations and easily cause accidents.
357 The hazards contained in these photos were validated and consistent with the follow-up
358 construction safety training textbook and VR-based safety training.

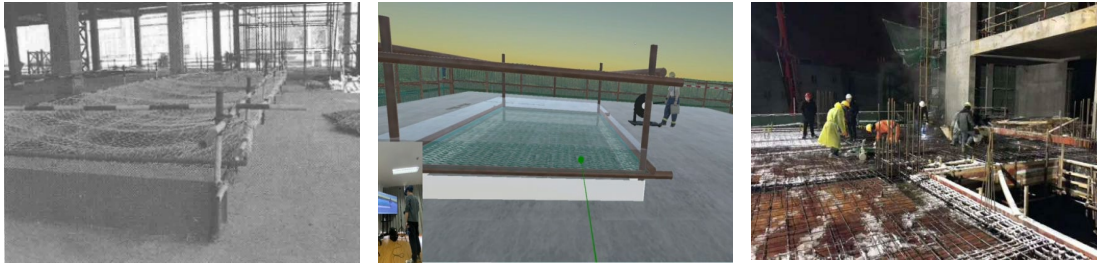


359
 360 Figure 7. Site photos for safety training in this study (note: only four out of the 16 photos are
 361 displayed in Figure 7 as examples)
 362

363 A total of seven major hazard categories were included in both the VR-based and textbook
 364 safety training. The seven major categories included fall from height, collapse, electrocution,
 365 insufficient protective equipment, hit by heavy equipment, struck by objects, and hazards by
 366 lifting. These hazards were displayed in specific scenes or scenarios, such as: 1) no covering
 367 or protection around holes, causing the danger of fall at holes; 2) site employees not wearing
 368 hard hat; 3) obstacles existing within the turning radius zones of heavy equipment; 4) danger
 369 of electrocution for not wearing gloves to operate electricity distribution boxes; 5) non-
 370 existence of the other peer worker or supervisor when required; 6) electricity distribution box
 371 placed randomly, the box door not closed, or wires dropped at the floor; 7) broken safety net;
 372 8) pile connection operation messed, or lack of easily seen accident evacuation channel; 9)
 373 workers not wearing seat belts; 10) no isolation net on the edge of the protection zones; 11)
 374 operators not wearing puncture-proof safety shoes with steel toe; 12) single point of lashing for
 375 tower crane lifting; 13) non-regulated maintenance edge; 14) materials not placed stably when
 376 working at height; 15) pedestrians passing under heavy objects during the lifting operation;

377 and 16) other hazards belonging to one of the seven major categories. Each of these 16 scenes
378 was separately displayed for safety hazard tests. The same hazard scenes were adopted for both
379 training groups.

380 Figure 8 displays an example of how the site photo was embedded in both the traditional
381 and VR-based training.



382

383 a) Picture from safety textbook b) VR-based scenario c) Real site scene

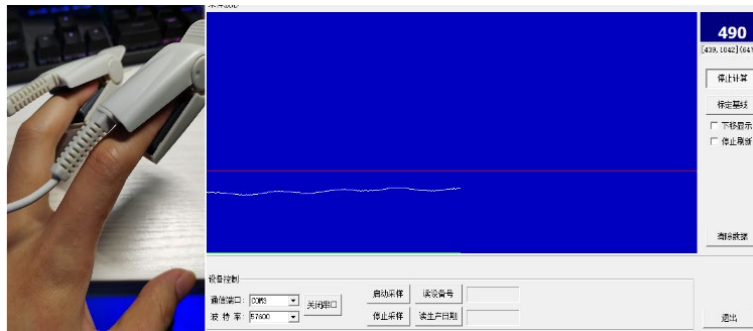
384 Figure 8. An example of uncovered hole applied to both textbook and VR-based training

385 Each trainee was displayed with the site scenes. The trainee was asked to respond to
386 questions regarding the existence of hazards in each site scene.

387 3.4.3. Measurements of physiological indicators during safety training

388 Each trainee, either in the traditional safety training or the VR-based group, was scheduled
389 for safety training lasting about 10 minutes. During the training period, each individual was
390 wearing the sensor and maintaining the two fingers of the left hand unmoved. Figure 9 shows
391 an example of a trainee wearing sensors during safety training and the real-time display of skin
392 resistance. At the beginning of each training, each trainee was guided by the researcher to
393 ensure their skin resistance was stable as seen in Figure 9. **Only after the flat and stable skin**
394 **resistance data were confirmed for each trainee, the safety training process would start with**
395 **continuing data recording of skin resistance. Therefore, the follow-up data collection and**
396 **analyses of skin resistance recorded were based on the fact that each trainee started from the**
397 **initially stable physiological status. The variation of skin resistance during the training would**
398 **then reflect each individual trainee's emotional or mental status by eliminating the effects of**
399 **each individual's initial status. Skin conductance level (SCL), is the tonic level of electrical**

400 conductivity of skin and reflects the general changes in autonomic arousal (Braithwaite et al.,
401 2015). The overall degree of arousal (Malmo, 1959) of trainees as measured in Figure 13 in
402 terms of lowest value, peak value, average value during the training process, and fluctuation
403 value, reflects the principles of SCL. It was found from previous studies (e.g., Choi et al., 2011)
404 that SCL was significantly correlated to individual's mental or physiological status.



405
406 Figure 9. Display of skin resistance during the safety training

407 Trainees recruited in the group of traditional safety training read picture-based construction
408 site safety textbooks. The training room was set with a sound-resistant screen to prevent any
409 external noise. Laboratory staff equipped the trainee with skin resistance sensors and asked the
410 trainee to leave the left hand unmoving on the table whilst self-studying the textbook.
411 Laboratory staff then stood out of the view of the trainee until training was completed. Figure
412 10 displays examples of participants during the traditional safety training.



413
414 Figure 10. Trainees studying safety hazards in the textbook-based safety training

415 The other group of trainees receiving the VR-based training was guided to operate the
416 immersive safety training platform shown in Figure 3 with the right hand. The training contents
417 of safety hazards (e.g., site scenarios and hazard types) were kept consistent between the two

418 groups. The VR-based immersive platform adopted the same site scenarios, including hazards
419 from the textbook used in the traditional training group. The immersive training room was also
420 set with consistent sound-resistant devices. Each trainee followed the instructions and guide
421 within the immersive system to complete a virtual site tour, hazard learning, experiencing
422 safety accidents virtually, and handling safety hazards. Figures 11 and 12 display the training
423 devices and the room setup for each participant in the VR-based immersive safety training
424 group.



Figure 11. VR headset for immersive construction safety training and other measurement devices



Figure 12. VR-based immersive safety training room

425

426 3.4.4. Post-training test of safety hazard identification

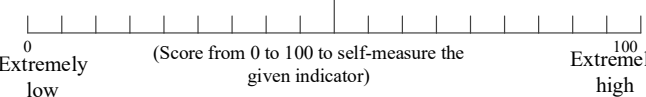
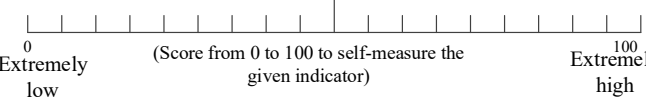
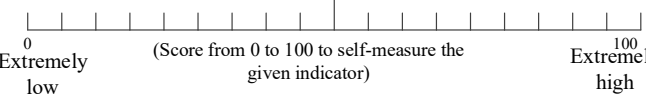
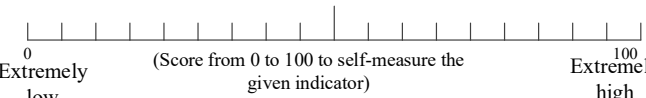
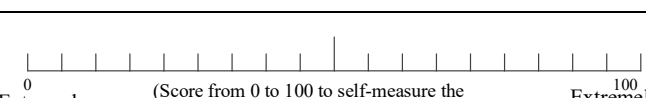
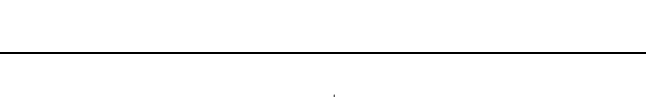
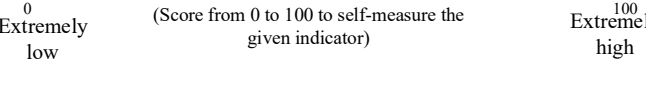
427 Following the safety training described in 3.4.3, the individual trainee would have a 5-
428 minute break, and repeat the hazard recognition task in 3.4.2. The task performance of each
429 trainee in terms of time of completion and accuracy rate was measured again to enable the
430 follow-up evaluation of the effects of safety training.

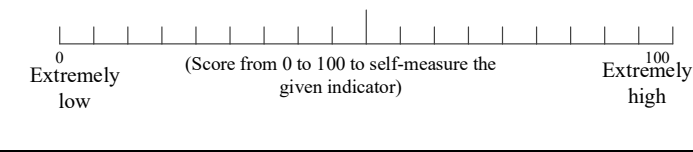
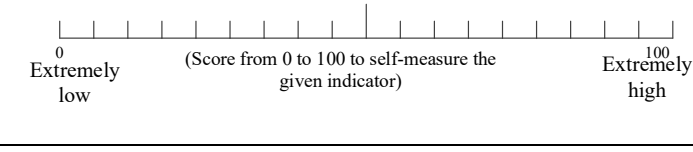
431 3.4.5. Post-experiment survey

432 Each trainee was provided with a questionnaire upon the completion of their safety training
433 and task. The nine indicators introduced in Section 3.1 is defined in Table 1, which is the post-
434 training self-evaluation questionnaire to score the training system. Each indicator was scored
435 by every trainee on a scale from 0 to 100. A higher score would indicate a more positive

436 evaluation of the trainee towards the given indicator. The measurement scales from 0 to 100
 437 were adapted from NASA-TLX principles (Hart, 1986), which evaluated individuals' mental
 438 status and effort in a multi-dimensional approach. In this scale system, measurement score for
 439 each indicator was equally divided into 20 ranges as seen in Table 1. The rationale for selecting
 440 a 100 point-based scale rather than the 1-5 Likert scale was also based on the fact that
 441 participants might hesitate to score between 3 and 4 and be more unlikely to choose 1 or 5 in a
 442 traditional Likert scale measurement. Further, the NSSA-TLX scale allows more varying
 443 scores among participants.

444 Table 1. Post-training self-evaluation of construction safety training

Self-evaluation measurement system		
Gender:		Group: VR group or Traditional training group
Openness	A1: The training room was with sufficient space and not making me feel suppressed.	
Flexibility	A2: The safety training received was with flexible training methods and low restrictions.	
Immersion	A3: The training received was immersive with little interruption from what had been occurring externally.	
Ease of learning	A4: The training steps and instruction was easy to understand, with easy-to-follow guides.	
Comfort	A5: The training process was comfortable both physically and mentally.	
Interactive engagement	A6: The training process was vivid and interactive by actively engaging personal senses.	
Degree of fun	A7: Training process was pleasurable and interesting.	

Proactive-ness	B1: The training approach made me more motivated and proactive in studying construction safety.	
Degree of inspiration	B2: The training approach made me excited and inspired me to continue studying safety related issues.	

445

446 **4. Results**

447 **4.1.Data validation**

448 Data through all trainees' participation were collected according to the two groups, namely
 449 immersive training and traditional safety training. Descriptive statistics are summarised for the
 450 two groups as shown in Tables 2 and 3.

451 **Table 2. Descriptive statistics of physiological data between the two training groups (kΩ)**

Training group	VR group (N=25)		Traditional training group (N=25)	
	Mean	Standard deviation	Mean	Standard deviation
Lowest value of individual skin resistance	259.52	96.78	318.80	84.26
Highest value of individual skin resistance	593.20	172.49	433.04	94.83
Average value of individual skin resistance	388.80	127.05	374.76	87.55
Variation of individual skin resistance	328.56	132.28	114.24	38.83

452

453 **Table 3. Descriptive statistics of self-evaluation scores between the two training groups**

Training group	VR group (N=25)		Traditional training group (N=25)	
	Mean	Standard deviation	Mean	Standard deviation
Openness	91.80	8.28	74.56	12.43
Flexibility	86.44	12.92	70.72	19.04
Immersion	88.68	8.75	65.20	16.10
Ease of learning	95.12	5.07	71.44	17.80
Comfort	93.84	6.47	75.12	15.82
Interactive engagement	90.84	7.78	64.88	20.73
Degree of fun	93.88	7.62	62.80	16.21

454

455 Data from both groups were found not meeting normal distribution following normal test
 456 described in Mishra et al. (2021). Mann–Whitney U test, as the non-parametric statistical
 457 analysis and accompanied with Kolmogorov-Smirnov statistic (KS Statistic) method, was
 458 adopted to test the level of significance for differences between the two groups. According to
 459 GraphPad (2022), Mann–Whitney U test ranks all values from low to high with a *p* value to

460 measure the discrepancy between mean ranks between two studied groups; KS test compares
 461 the cumulative distribution between two groups also using a p value; KS method is more
 462 sensitive to any differences in the two data distributions while Mann–Whitney U test is most
 463 sensitive to changes in the median. As the two methods are adopted in comparing two different
 464 data distributions or groups, this study adopts both tests to have more comprehensive
 465 comparisons. The four defined dimensions in Section 3.1 for comparative analysis were
 466 analysed, including self-evaluation of learning process, endpoint evaluation of learning
 467 outcome, physiological reaction, and learning performance. Non-parametric method such as
 468 Mann-Whitney test is more suitable for data that are skewed distributions or have a discrete or
 469 ordinal scale (Krzywinski and Altman, 2014). Following Krzywinski and Altman (2014), it
 470 can be assumed at 5% level of significance, and the null hypothesis that the two groups had
 471 consistent median values in the given dimension. A p value lower than 0.05 would decline the
 472 null hypothesis and indicate a significant difference between the two groups in terms of the
 473 given dimension shown in Tables 4-7. A lower p value would suggest a more significant
 474 difference between the two groups.

475 *4.1.1. Analysis of physiological reaction during training*

476 The statistical tests based on two different non-parametric methods for the skin resistance
 477 values between the two studied groups are summarised in Table 4.

478 Table 4. Level of significance in difference of skin resistance value between the two groups
 479 (N=50)

Variable	Mann–Whitney U test		KS Statistic	
	Z value	p value	Z value	p value
Skin resistance value (k Ω)	-5.850	0.000**	3.111	0.000**

480 Note: ** denotes p value lower than 0.01, indicating a significant difference between the two experimental groups.

481
 482 The p values from both Mann–Whitney U test and KS Statistic methods indicate that
 483 different safety training approaches resulted in significant variation in terms of skin resistance

484 between the two groups. A further evaluation could be conducted to analyse how the two
 485 different training approaches cause varied physiological reactions during safety training.

486 4.1.2. Self-evaluation of the training process

487 The two statistical methods applied to analyse trainees' evaluation of the training process
 488 also reveal significant differences between the two groups, as seen in Table 5. It can be found
 489 that the two studied groups differed significantly in each of the seven self-evaluation indicators
 490 related to the safety training process.

491 Table 5. Statistical analyses from self-evaluation of training process between the two studied
 492 groups

Variable	Mann–Whitney U test		KS Statistic	
	Z value	p value	Z Value	p value
Openness	-4.807	0.000**	2.404	0.000**
Flexibility	-3.259	0.001**	1.697	0.006**
Immersion	-5.096	0.000**	2.828	0.000**
Ease of learning	-5.248	0.000**	2.828	0.000**
Comfort	-4.456	0.000**	2.404	0.000**
Interactive engagement	-5.083	0.000**	2.546	0.000**
Degree of fun	-5.848	0.000**	3.111	0.000**

493 Note: ** denotes *p* value lower than 0.01, indicating a significant difference between the two experimental groups.

494 4.1.3. Evaluation of learning performance

496 For each trainee within the group of either immersive training or textbook-based training,
 497 the improvements in terms of time taken to complete and the accuracy rate of detecting site
 498 hazards were recorded or calculated by comparing the outcomes of the two tests introduced in
 499 Sections 3.4.2 and 3.4.4. The *p* values lower than 0.01 in Table 6 indicate significant
 500 differences regarding the improvements caused by the two different training approaches.

501 Table 6. Statistical analyses of learning performance between the two studied groups
 502 (N=50)

Variable	Mann–Whitney U test		KS Statistic	
	Z value	p value	Z Value	p value
Improvement in time of completion	-2.670	0.008**	1.697	0.006**
Improvement of hazard recognition accuracy	-5.524	0.000**	2.828	0.000**

503

504 4.1.4. Self-evaluation of learning outcome

505 The two indicators in light of trainees' evaluation on the training approach's impacts are
506 statistically analysed in Table 7. The lower *p* values from the analyses of both indicators
507 indicate the significant differences between the two training groups.

508 Table 7. Statistical analyses of learning outcome between the two studied groups (N=50)

Variable	Mann–Whitney U test		KS Statistic	
	Z value	<i>p</i> value	Z Value	<i>p</i> value
Proactiveness	-2.670	0.008**	1.697	0.006**
Degree of inspiration	-5.524	0.000**	2.828	0.000**

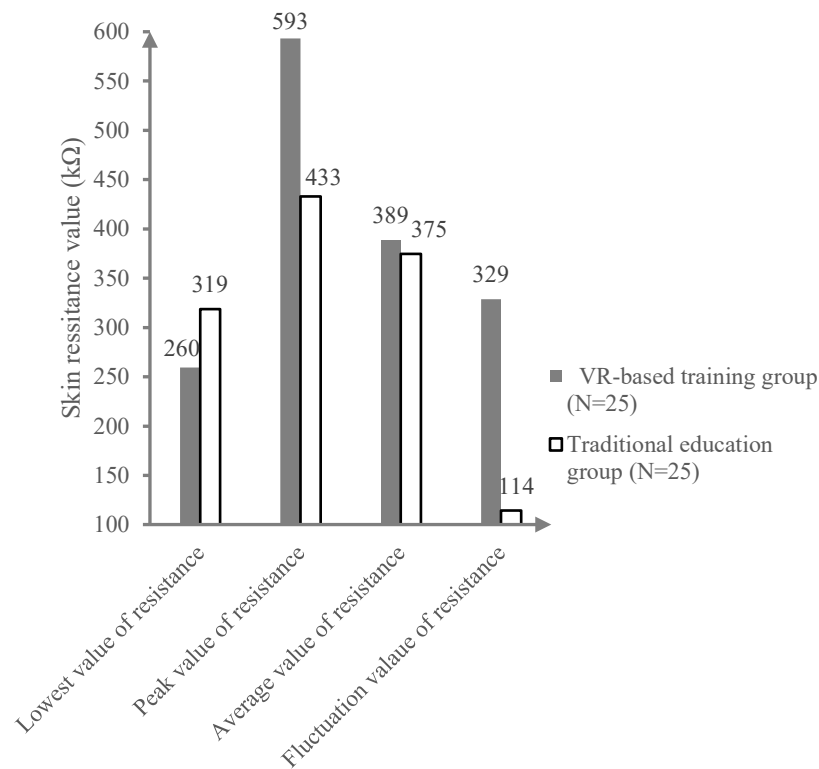
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510 **4.2. Further analyses of experimental data**

511 The whole data sample was based on the 50 experimental participants (i.e., trainees), defined
512 by the four different dimensions of measurements on the effectiveness of the allocated safety
513 training approach. These dimensions included both subjective (e.g., self-evaluation of learning
514 process and outcome) and objective measurements such as skin resistance, time of completion
515 and hazard recognition accuracy.

516 4.2.1. Differences in trainees' physiological reactions caused by the training approach

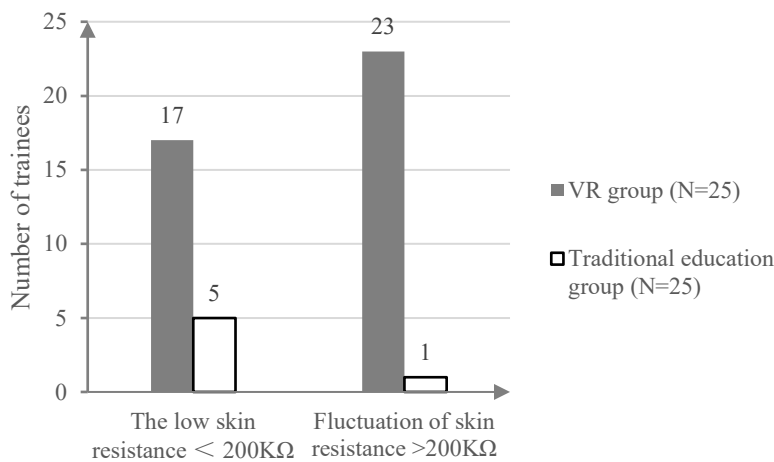
517 Trainees' physiological reaction during safety training was measured by skin resistance in
518 this study. Figure 13 shows the comparisons of skin resistance in terms of lowest value, peak
519 value, average value during the training process, and fluctuation value. The peak value of the
520 VR group was 593 kΩ, higher than that in the traditional training group based on textbook
521 training. It is seen in Figure 13 that the two groups had a close average value during their
522 training process, i.e., 389 kΩ compared to 375 kΩ. However, the fluctuation value, which is
523 the difference between the peak and lowest values of skin resistance, indicates that VR group
524 underwent significantly higher variations (i.e., 329 kΩ versus 114 kΩ) of physiological
525 reactions during training.



526 Figure 13. Comparison of skin resistance (kΩ) between the two training groups

528 A further analysis shown in Figure 14 found that the VR group had 23 individual trainees
 529 with a fluctuation value higher than 200 kΩ. In contrast, the traditional training group had only
 530 one trainee. It is inferred that a high fluctuation of skin resistance is a common phenomenon
 531 for VR-based trainees. When the body is in a state of emotional arousal, sweat secretion
 532 increases, skin conductivity rises, and skin resistance decreases (Khalifa et al., 2022; Vrana and
 533 Rollock, 2002). As counted in Figure 14, among the totally 22 individual trainees with the
 534 lowest resistance value below 200 kΩ, VR group contributed to 17 of them. It is hence indicated
 535 that VR-based training brings a higher degree of emotional experience during safety training.
 536 For example, during the VR-based immersive site tour, the trainee would experience falling
 537 from height as “punishment” if failing to identify the hazard for uncovered opening. The
 538 intense scenario changes bring strong emotional experiences to trainees in the immersive
 539 environment, making the trainees nervous or excited. The real-time collected physiological
 540 data showed the large change of skin resistance value during the time period when a trainee
 541 failed to detect safety hazards. Therefore, the newly developed VR system had created virtual
 542

543 scenarios that to some degree, represented the real site environment to spark the immersive
544 experience for trainees.



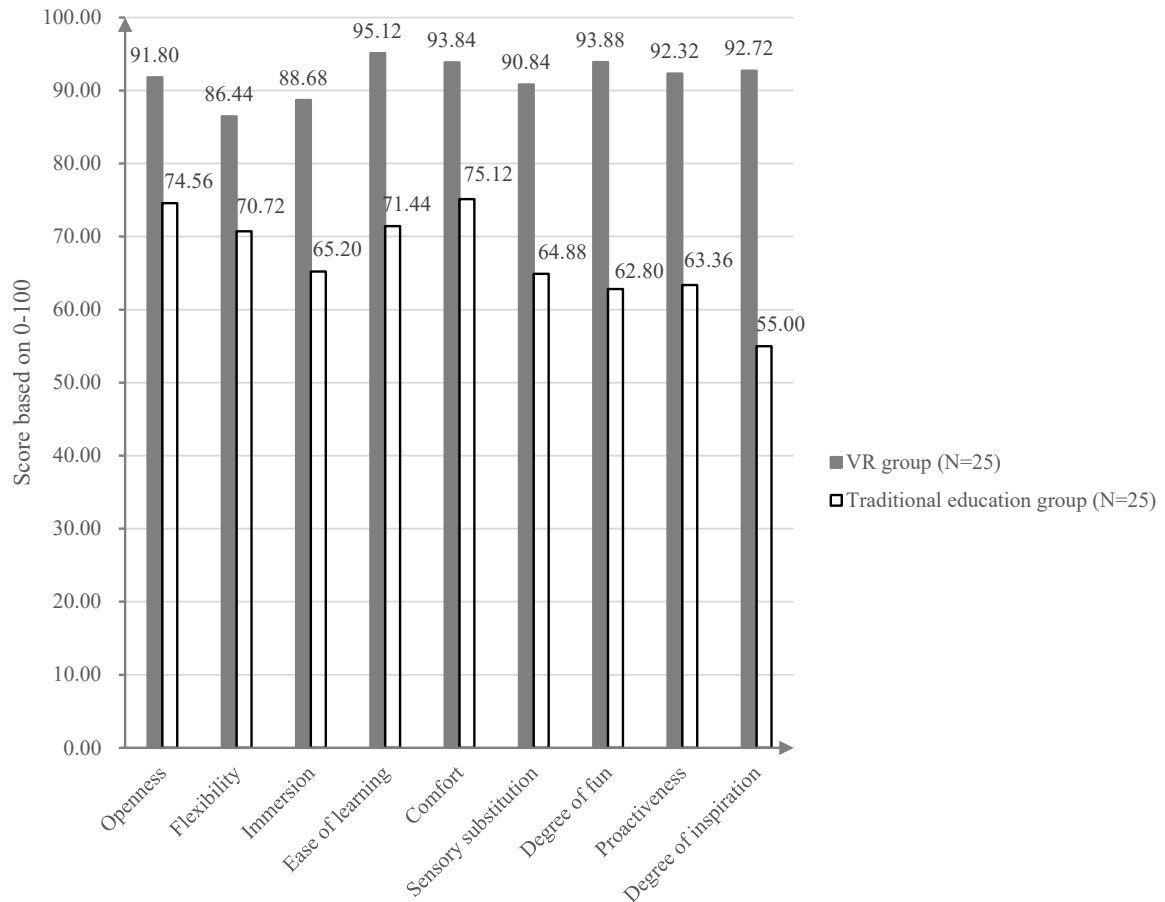
545
546 Figure 14. Numbers of trainees falling into the defined skin resistance ranges
547

548 In the virtual environment, trainees would be more likely to be excited by multi-sensory
549 stimulations, resulting in higher physiological reactions in terms of skin resistance, which could
550 be adopted as the measurement for emotional fluctuation, brain arousal, and alertness
551 (Boucsein, 2012). The significant differences in skin resistance value variations between the
552 two training approaches indicated the stimulating effects of VR-based training on individuals'
553 sensory reactions. The close average values of skin resistance during the training process
554 between the two groups, as shown in Figure 13, indicated that the VR-based training has
555 maintained the overall emotional reaction of trainees at a normal range.

556 4.2.2. Comparisons of trainees' self-evaluation on the learning approach

557 Self-evaluation of the training received is another important measurement dimension of the
558 training effectiveness through learners' reflections. Experimental participants from the two
559 different training approaches are compared based on their self-evaluation scores towards the
560 nine indicators defined in Table 1. Figure 15 compares the scores of each indicator between
561 the two groups. It is seen that VR group scores significantly higher at all the indicators
562 compared to their counterparts from the traditional training group. Figure 15, together with

563 Tables 5 and 7, indicate that the VR-based training results in more positive evaluations from
 564 trainees in terms of both the training process and the post-training impacts (i.e., motivating the
 565 continuous learning and the inspiration).



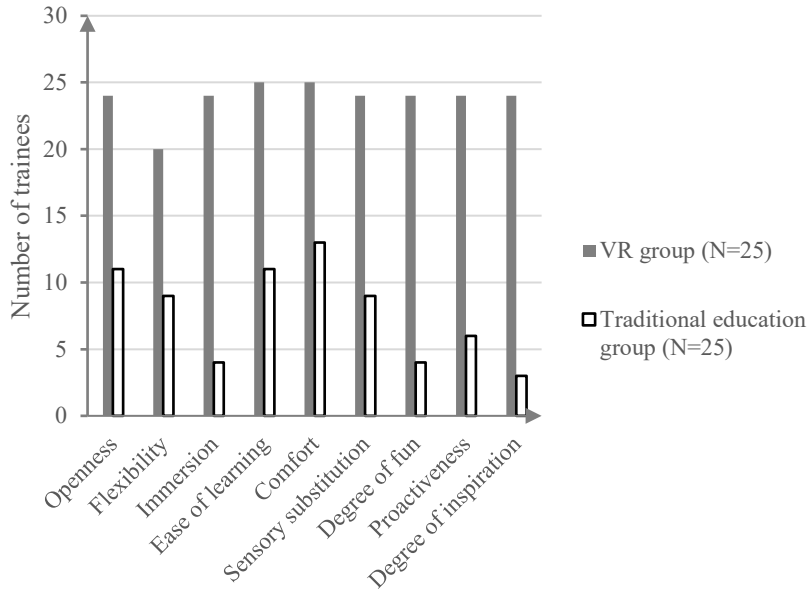
566
 567 Figure 15. Trainees’ self-reflection of the safety training process

568 Among the seven training process-related indicators, the highest differences between the
 569 two groups are found in the indicators of immersion, ease of learning, interactive engagement,
 570 and degree of fun. Trainees found the VR-based training with a significantly higher degree of
 571 fun, which could be related to the immersive experience and interactive engagement brought
 572 by the VR-driven platform. The immersive environment and multi-sensory engagement can
 573 more easily make the trainee concentrate on the learning tasks. In contrast, the traditional
 574 training needs learners to convert the 2D information from the textbook into real site safety
 575 scenarios. Learners or trainees in the traditional group tend to spend more effort in studying
 576 and memorising the text or static information from the textbook. Differing from the textbook-

577 based training, learners in the VR-based training can experience more interactions with the
578 dynamic and immersive site scenarios.

579 The two indicators related to the post-training outcome demonstrate even more significant
580 differences between the two groups as seen in Figure 15. The highest difference comes from
581 the degree of inspiration. The VR-based training significantly differs from the traditional safety
582 training in terms of motivating trainees' relational thinking, which is highly connected to
583 inspirational learning. The virtual environment provides an immersive site experience to
584 trainees, engages multiple bodily sensing (e.g., visual and vocal), and enables relational
585 thinking through human-immersion interactions. In the VR-based training approach, trainees
586 could more easily capture the safety knowledge through virtual site exploration and interaction.
587 Trainees could even further develop their own safety awareness with relational thinking
588 towards other potential site safety hazards not covered in prior learnings. The traditional
589 textbook learning would need trainees in a less active manner to link static images and texts
590 into the real site scenarios. In comparison, VR-based safety training more actively drives
591 learners to relate the virtual scenarios to real site safety hazards. Through this actively relational
592 thinking, trainees would be more likely to make instant and proper decisions onsite when
593 handling safety hazards.

594 Researchers counted the number of individual trainees from each group scoring over 80 out
595 of 100 for each given indicator. Figure 16 shows that more than 80% of trainees from the VR
596 group assigned the evaluation score over 80 for each of the nine indicators. This number from
597 the traditional training group is significantly lower for each indicator. Figure 16 shows that
598 trainees from the VR group held significantly higher positive perceptions in terms of the
599 learning process and post-learning impacts from the training approach that they received.

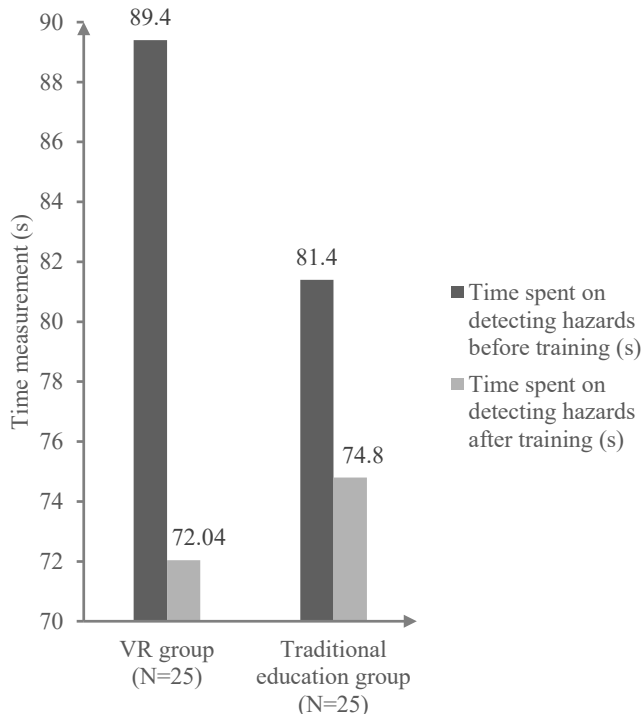


600

601 Figure 16. Counts on number of trainees scoring over 80 out of 100 for the nine indicators in
 602 the studied group

603 4.2.3. Comparisons of learning performance

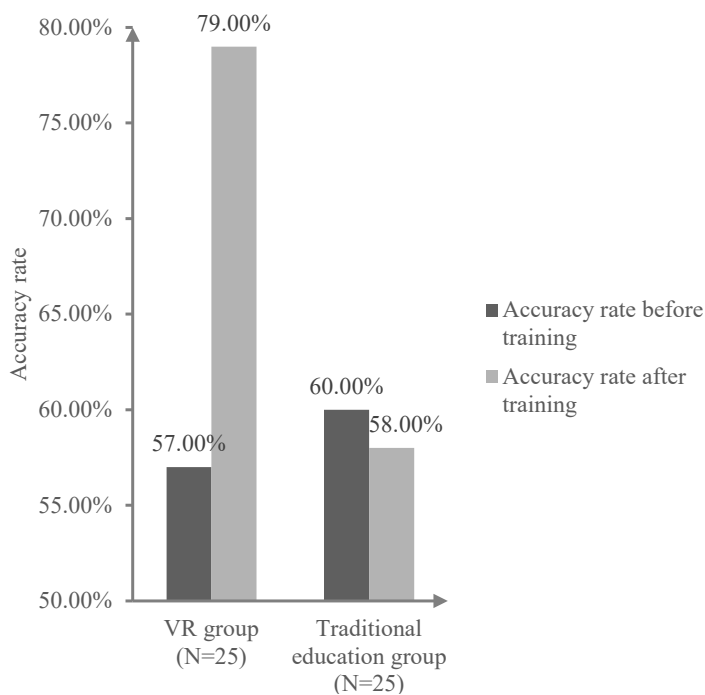
604 The site scenarios selected for the task of safety hazard recognition all came from real-word
 605 construction projects. A total of the same 16 scenarios were tested for each trainee. For each
 606 trainee, the accuracy rate and time spent on detecting hazards from all the given scenarios
 607 before and after the training were compared for both groups, as illustrated in Figures 17 and
 608 18. It is seen in Figure 17 that the VR-based training reduced the time spent on detecting
 609 hazards by 17.36 seconds, compared to the reduction by 7.72 seconds in the traditional training
 610 group. In terms of detection accuracy rate, the VR group, on average, had their hazard
 611 recognition performance improved by 22%. In contrast, the traditional group had not improved
 612 the accuracy rate, but with a minor reduction. Both indicators showed that VR-based training
 613 outperformed the traditional safety training by improving learning performance.



614

615

Figure 17. Comparisons of time spent to detect safety hazards before and after training



616

617

Figure 18. Changes in safety hazard recognition accuracy rates following training

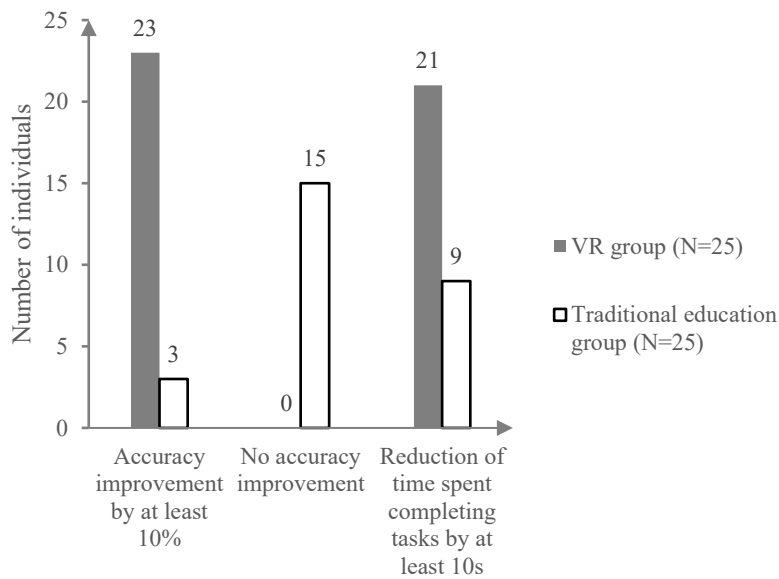
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620

Further data analysis showed that 92% of individuals in the VR group achieved their accuracy improvement by at least 10%. Instead, only 12% of individuals from the traditional training group achieved the same level of accuracy improvement. In terms of time spent on

621 recognising hazards, individuals from the VR group also outperformed their peers from the
622 traditional training group, as indicated in Figure 19.



623

624 Figure 19. Counts on number of individuals on measured improvements before and after
625 training from both groups

626 The number of individuals that achieved the two measured improvements in terms of
627 accuracy and reduction of time spent completing hazard detection are compared between the
628 two groups. Compared to 0% of VR group individuals who did not improve their accuracy in
629 hazard detection, still 15% of trainees from the traditional training did not achieve any
630 improvement. A total of 21 out of 25 individuals from the VR group were able to reduce the
631 time spent on tasks by at least 10 seconds. This proportion was only 9 out of 25 in the traditional
632 group.

633 4.2.4. Correlational analyses between measurement dimensions of training effectiveness

634 The training effectiveness could be affected by multiple factors such as learning
635 environment and training approach. The differences identified between VR and tradition
636 training of safety hazards can be further analysed by investigating the correlations between
637 these pre-defined dimensions, for example, the relationship between physiological reaction and
638 learning performance shown in Table 8, as well as the correlations between learning

639 performance and self-evaluations as seen in Table 9. Following the guide from Bishara and
 640 Hittner (2012) on conducting correlation analyses for non-normally distributed data, the
 641 Spearman’s correlations analyses were conducted as shown in Tables 8 and 9.

642 Table 8. Correlational analysis between physiological reaction and learning performance

Variable		Time improvement	Accuracy improvement
Skin resistance	Spearman’s correlation	0.198	0.640**
	<i>p</i>	0.167	0.000
	N	50	50

643 ** denotes *p* value lower than 0.01; *denotes *p* value lower than 0.05

644
 645 Table 9. Correlational analysis between self-evaluation of learning process and learning
 646 performance

Variable		Openness	Flexibility	Immersion	Ease of learning	Comfort	interactive engagement	Degree of fun	Proactiveness	Degree of inspiration
Accuracy improvement	Spearman’s correlation	.609*	.430*	.689**	.587**	.487**	.666**	.774**	.607*	.736**
	<i>p</i>	0.000	0.002	0.000	0.000	0.000	0.000	0.000	0.000	0.000
	N	50	50	50	50	50	50	50	50	50
Time improvement	Spearman’s correlation	0.247	0.11	0.197	0.092	.300*	0.2	.294*	.332*	.399**
	<i>p</i>	0.084	0.449	0.171	0.525	0.034	0.163	0.038	0.018	0.004
	N	50	50	50	50	50	50	50	50	50

647 ** denotes *p* value lower than 0.01; *denotes *p* value lower than 0.05

648 The correlational coefficient and corresponding *p* values in Tables 8 and 9 indicate that
 649 physiological reaction and self-evaluation had significant correlations with the accuracy
 650 improvement in detecting safety hazards, but not with time reduction in detecting hazards. VR-
 651 based training typically caused a more intense engagement of trainees measured by skin
 652 resistance, with more positive feedback towards the training, and hence resulting in better
 653 learning performance.

654 4.2.5. Further analysis

655 Traditional safety training mainly engages learners through reading and listening. Learners
 656 are largely engaged in a passive way by being fed with the information. If not further digested

657 or processed by the individual trainee, the learning content or information could soon disappear
658 or become ineffective in the knowledge storage of individuals. This ineffectiveness could be
659 indicated by the lack of improvement in hazard recognition after the training in the traditional
660 training group. The traditional safety training approach was largely based on 2-dimensional
661 text and images, requiring trainees to further memorize and process the information. Different
662 from the traditional training, VR-based immersive approach integrates active and passive
663 learning manners, and enables trainees to experience hazards in the immersive environment.
664 The virtual site tour provides a context in the safety hazard scenario. Interactive learning
665 enables trainees' embodied cognitive processing of hazard information. Learners' multiple
666 sensory participation in the immersive environment, such as experiencing accidents in VR, can
667 more effectively store hazard-related knowledge through cognitive learning to form a more in-
668 depth memory of safety hazards. As tested by the earlier study of Han et al. (2021), a lower
669 cognitive load typically resulted in better task performance, such as hazard recognition. The
670 reduced time to complete tasks, besides the accuracy improvement, also suggested the
671 effectiveness of VR-based training approach.

672 **5. Discussion**

673 **5.1. Learning environment in the VR-based safety training**

674 Embodied cognition is based on the theory that cognition, thinking, memory, emotion and
675 attitude are all shaped by the interaction between human body and the environment (Ye, 2015).
676 Individuals' capturing and development of knowledge highly depends on the environment
677 where the body is placed (Robbins and Aydede, 2009). VR-based safety training provides a
678 new learning environment and experience. The post-experiment evaluation revealed that
679 trainees from the VR group held significantly more positive views on the immersion. It was
680 indicated that the embodied learning environment created by the VR-driven immersion enabled
681 learners to have the direct feeling and emotional engagement in experiencing site hazards. This

682 immersive experience can highly arouse different brain parts, including the thalamus for visual,
683 auditory, and somatosensory engagement, cerebellum for regulating balance and body
684 movement, as well as cerebral cortex. As a result, learners had a stronger immersive experience
685 as if they were working on sites viewing the hazards.

686 The theory of situated cognition describes that the rich information contained in the
687 environment helps cognitive processing (Wilson, 2002; Olson and Olson, 2003; Chrisly, 2004),
688 and enhances learning performance in understanding concepts and seeking solutions (Glaser,
689 2001; Kirsh, 2009). As demonstrated in this comparative experimental research of safety
690 training, the environment is created by the different information channels (i.e., traditional
691 textbook or the VR-based immersion). In the traditional safety training, information is mainly
692 in the form of 2D text, static images, or videos. In the VR environment, such as the VR platform
693 developed by researchers in this study, information is presented in the immersive 3D through
694 the virtual site tour. Individual trainees have their virtual site walkthrough, searching site
695 hazards, handling the hazard, experiencing the safety accidents, and also studying safety
696 operational regulations. For those with limited education background, such as workforce, and
697 those with little site experience, the virtual site information presented with multiple sensory
698 engagements (e.g., visual, virtual site noises) can be more effective than traditional 2D based
699 information during safety training. The VR environment can reduce the cognitive load needed
700 for processing the information, decrease the learning difficulty, and hence improve the learning
701 outcomes. The post-experiment survey also showed that trainees from the VR group generally
702 perceived the ease of learning safety hazards. As indicated by Sternberg et al. (2012), learners
703 tend to encode the content of learning and the environment, and store it in their long-term
704 memory. The environment features or contexts will serve as effective clues for information
705 retrieval in future recalls (Sternberg et al., 2012). This theory can be verified in the VR-based

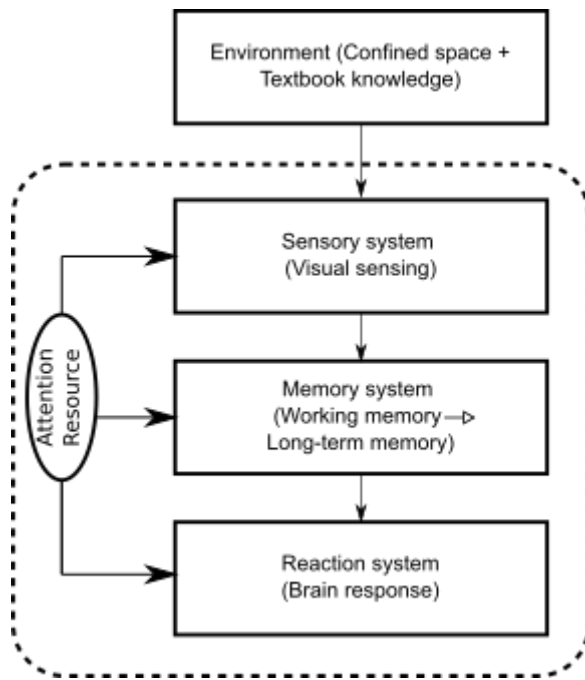
706 safety training, where learners significantly improved their accuracy and reduced time spent
707 for completing the hazard detection tasks after the training.

708 The multi-sensory engagement, as forementioned, reduces the distraction as trainees may
709 experience during the learning process. For example, noise occurring during training can affect
710 learners' allocation of attention resource, and further disturbing the information processing for
711 knowledge storage. Sudden or unexpected noise could inevitably happen in the traditional
712 safety training environment. In the VR environment, learners wearing headsets in this study
713 were listening to the site background sound during virtual site tour to help them better
714 immersed. Learners were more engaged both visually and vocally on searching safety hazards,
715 and hence less likely to be affected by other non-relevant distractions in the training room.

716 **5.2. Embodied cognition enhancing the learning process**

717 Human beings' cognitive learning process can be divided into sensory, information
718 processing, and reaction stages. The information processing stage involves memorizing and
719 storing the knowledge. Safety training aims to form the proper safety cognition and to further
720 develop appropriate safety behaviors of trainees. The traditional textbook-based training is
721 limited to two-dimensional text or image information. Trainees are likely to have a single-
722 sensory engagement in viewing and processing information. Following the principles of
723 psychology and human performance described by Wickens et al. (2021), Figure 20 models the
724 process of knowledge storage and reaction within the traditional textbook-based learning
725 environment.

726



727

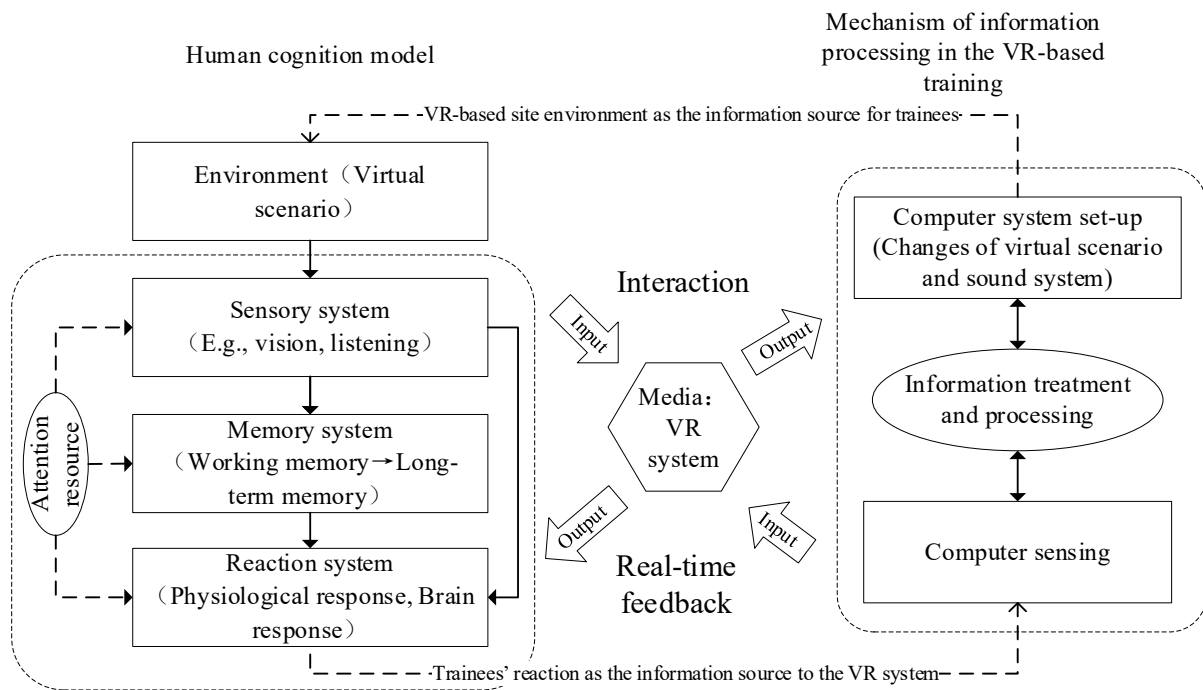
728

729 Figure 20. Mechanism of traditional learning and information processing

730 In this study, researchers proposed that VR-based training could embed embodied cognition
 731 to enhance interactive learning in the immersive environment. In the immersive site tour,
 732 trainees do not only observe hazard-related information, but also the surrounding context in a
 733 more holistic scenario. For example, the building's different elements, site equipment, and
 734 layout are all context information where the hazards could be. VR-based immersion can
 735 provide the whole picture, rather than only presenting the hazard in an isolated manner as in
 736 traditional textbook training. Post-experiment reflection from participants indicated that from
 737 the VR-based site tours that they would more frequently pay attention on higher locations on
 738 site after experiencing the virtual falls from height due to ignorance of hazard. Trainees stated
 739 that they would hence more likely to search the relevant hazards such as fall in the given site
 740 scenario.

741 The subjective measurement through post-experiment survey complemented the task
 742 performance to measure the training effectiveness. Trainees from the VR group scored
 743 significantly higher than their peers from the traditional training group in evaluating the

744 training process and the longer-term impacts. It was inferred that VR-based training provided
 745 more inspiration and motivation for participants during safety training. VR-based training does
 746 not really change the learning process, as shown in Figure 20 for traditional training. However,
 747 VR provides richer information and context to stimulate trainees' sensing, such as the whole
 748 virtual site scenario to engage trainees. The virtual environment of construction sites hosts all
 749 information, including safety hazards. As illustrated in Figure 21, during the interactive training
 750 process, an individual trainee and the immersive environment work as the information source
 751 to each other. This interactive process enabled trainees' multi-sensory engagement i.e., the
 752 embodied cognition in the training process.



753
 754 Figure 21. Embodied cognition model of learner engagement in the VR-driven safety training
 755 system

756
 757 Figure 21 demonstrates a cognition model via a virtual environment. It is constructed based
 758 on the human-computer interaction model (Guo, 2020). Individuals develop cognition during
 759 their interaction with the VR system. The information provided by the VR scene through the
 760 visual and auditory channels is firstly perceived by an individual, and stored in the memory
 761 system. The individual then makes decision in responding to the information received. The VR

762 system presets its scenarios with sound system. Similar to the human cognitive process, after
763 information processing, the VR system reacts to the individual with updated scenes and sound
764 effects. Through this bespoke process of interaction, the individual and the VR system
765 continuously exchange information and feedback. This bodily engagement could cause
766 physiological and emotional arousal as indicated in Figure 13, and further influencing the
767 cognitive outcomes. The site environment is the carrier of safety knowledge related to hazards,
768 and presents the safety knowledge to trainees in a visualized and dynamic manner. On the other
769 hand, the individual trainee's behaviour during the virtual site tour also feeds back to the VR
770 system. For instance, ignoring safety hazards or improper reaction to identified site hazards
771 would cause a sudden (virtual) fall of the trainee. Therefore, the trainee and the VR-based site
772 environment are in a dynamic interaction, and continue feeding back to each other. This
773 interaction and real-time feedback between the trainee and the environment are not available
774 in the traditional safety training. VR provides succinct but vivid scenarios which enable a
775 longer term memory to be established (Hu, 2021). VR-based construction safety training
776 enhances building the safety knowledge through specific scenes (Liang and Huang, 2008). As
777 a result, the learning performance and trainee evaluation are improved. The embodied
778 cognition could also enhance the inspiration and motivation for continuous learning.

779 Knowledge acquiring, emotional experience, and behavioural reaction form the process
780 of embodied cognition (Ye, 2015). Cognitive activities are inseparable from body participation,
781 while physiological changes and emotional responses are the individual's reactions to the
782 stimulus events (Ye et al., 2021). Both positive and negative emotions during the cognitive
783 process will strengthen the memory coding for the future retrieving of the stimulus (Baddeley
784 et al., 2018). By measuring physiological data such as skin electrokinetics and heart rate
785 changes, Christianson and Nilsson (1984) found that there would be voluntary emotional
786 awakening during the memorizing process. Similarly, the skin resistance variation was

787 identified after safety training. This variation was more significant in the VR training group
788 than the traditional training group. The objective data captured from skin resistance could also
789 be validated by the subjective measurements through post-training questionnaire survey, which
790 also indicated that trainees had stronger emotional arousal in the VR-based training. Emotional
791 arousal could provide a facilitating effect on memory encoding of individuals, and create more
792 reflexive attention and thinking , as indicated by Heuer and Reisberg (1990).

793 Safety in construction work is highly related to preventive awareness and knowledge in a
794 dynamic and risky site environment. Safety training might be downplayed as it is often
795 considered with little contribution to the income generation of construction workforce.
796 Workers typically only pay attention to their site activities to complete tasks that directly matter
797 to their income, but with limited attention to safety knowledge or safety training. The
798 traditional safety training tends to be more towards passive learning and lacks the engagement
799 of individuals. The training effectiveness is not uncommonly in question. Instead, the
800 emotional arousal stimulated in the VR system, such as the virtual experience of fall from
801 height, collapse of scaffolding, and struck-by, etc., increases the interaction between the trainee
802 and the VR system. The immersive and multi-sensory engagement can transform the traditional
803 passive learning into a more active learning mode.

804 Safety accidents often cause serious injuries and even fatalities. However, trainees in a third-
805 person experience by reading texts, listening, or watching videos in the traditional safety
806 training may not be fully engaged in realising the seriousness of accidents and hazards. The
807 VR system allows learners to gain specific and profound experiences through engaging bodily
808 senses. At the same time, the first-person learning perspective provided by the VR system
809 strengthens the emotional participation of individuals, and enhances the sense of substitution
810 in the virtual environment (Chen, 2020). This first-person perspective of learners during safety
811 training also evaluates the scenario setup, interaction, and immersion of the designed VR

812 system. The empathy and emotional arousal in experiencing site accidents caused by hazards
813 integrate trainees' feeling, awareness of hazards, understanding, and reaction. The individual
814 trainee becomes part of the virtual site in the active learning, rather than being a bystander as
815 in the traditional training. The first-person experience is strengthened by virtually walking
816 through the site and by also observing other non-hazard-related information in a holistic picture.
817 Hence, the trainee builds his/her own safety knowledge through the virtual walkthrough in the
818 first-person perspective.

819 This first-person experience is enabled by the interaction between the learner and the VR
820 system, as well as the immersive environment created by the VR technology. VR, as the
821 technical media, bridges the learner and the actual world (e.g., construction site hazards in this
822 study). The physiological reaction together with emotional arousal were strengthened by this
823 first-person experience, as indicated by the post-experiment questionnaire survey and the skin
824 resistance analyses. The storyline or scenarios of safety hazards embedded in the virtual site
825 can be updated within the VR system to reflect the real world site hazards and training needs.

826 **6. Conclusion**

827 Although immersive technologies involving virtual reality (VR) have been applied in
828 construction safety training as an alternative to the traditional safety training, there has been a
829 lack of empirical data to test the effectiveness of VR-based training mode versus the traditional
830 approach. To address this need, this study adopted the self-developed VR-based construction
831 safety training system to compare the effectiveness between the traditional safety training and
832 the VR-based approach. Both objective and subjective data were collected involving the
833 training process and outcome. Objective data included the skin resistance measurements of
834 each individual during the training, and the task performance as outcomes. The subjective
835 measurements were based on the post-training questionnaire survey collecting individuals'
836 evaluation of the training process and post-training impacts. Both the subjective and objective

837 data collected based on the training process and task performance revealed the consistent
838 findings that VR-based training approach outperformed the traditional safety training in terms
839 of trainees' interactive engagement and learning outcomes.

840 The differences between the two safety training approaches can be summarised in the
841 following aspects:

842 a) VR-based training involving embodied cognition enables trainees' physiological
843 reaction and emotional engagement. Compared to the traditional training, VR-based
844 training caused a higher fluctuation of skin resistance, which reflects a higher level of
845 sympathy and emotional arousal;

846 b) Learners gain a better experience through virtual and immersive training. The post-
847 experiment questionnaire survey revealed that VR group learners had a significantly
848 more positive experience towards the training process (e.g., degree of fun). Learners
849 from the VR group also held more positive views regarding the inspiration and
850 motivation of continuing safety training following the training;

851 c) The bodily engagement through interactive learning in the immersive environment can
852 enhance the learning performance measured by accuracy and time spent on hazard
853 detection. VR-based training could decrease the cognitive load spent on learning safety
854 hazards through multi-sensory engagement and could further enhance the longer-term
855 memory of safety hazards.

856 Following the theory of embodied cognition, these findings were achieved:

857 1) By providing the immersive environment, interactive mode, and the first-person experience,
858 VR-based system could meet the training needs in construction safety with enhanced
859 learning experience and training outcomes. This enhancement could be explained by the
860 embodied cognition theories. Basically, trainees or learners could obtain the nearly-real-
861 world perception from the immersive environment, with stronger emotional arousal

862 through interaction with the VR system. Further, the trainees could form the embodied
863 cognition with the first-person experience in the virtual site, and transform it into longer-
864 term memory. Finally, safety awareness and knowledge can be improved through VR-
865 based training.

866 2) Differing from the traditional training, VR-based training motivates individual trainees
867 through multiple bodily sensory engagements. Trainees can better allocate their attention
868 resources with reduced distraction and lowered cognitive load. This multi-sensory
869 engagement strengthens both the physical and mental participation, and bridges the trainee
870 and the virtual environment. This information processing and memorizing of safety hazard
871 related knowledge, through embodied cognition, can further motivate trainees' reflective
872 thinking and active learning. Specifically, trainees have enhanced experience during the
873 training process through immersion, fun, ease of learning, first-person experience, and
874 inspiration, all of which boost the learning performance.

875 The current study has several limitations. Firstly, the potentially negative emotional
876 reactions during VR-based training, such as nervousness and uncertainty of trainees, were not
877 measured during the study. Therefore, it remains unknown how these negative reactions could
878 affect cognitive learning and performance. The future study can consider extending the
879 measurement dimensions in the post-experiment evaluation by including these negative
880 reactions. Secondly, the post-training test of safety hazard recognition was conducted on the
881 same day of the training. It only measured the short-term learning performance of trainees
882 following safety training. The longer-term learning performance of hazard recognition is yet to
883 be tested by comparing the VR-based and the traditional safety training. Future research could
884 be extended to test the longer-term performance of trainees, e.g., one week or one month after
885 the safety training. More research is needed to evaluate how long and how often VR-based
886 training could optimally enhance individuals' learning performance.

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