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Factorization method for solving nonlocal boundary value problems in Banach space

This article deals with the factorization and solution of nonlocal boundary value problems in a Banach space of the abstract form

$$B_1 u = \mathcal{A}u - S\Phi(u) - G\Psi(A_0 u) = f, \quad u \in D(B_1),$$

where \mathcal{A}, A_0 are linear abstract operators, S, G are vectors of functions, Φ, Ψ are vectors of linear bounded functionals, and u, f are functions. It is shown that the operator B_1 under certain conditions can be factorized into a product of two simpler lower order operators as $B_1 = BB_0$. Then the solvability and the unique solution of the equation $B_1 u = f$ easily follow from the solvability conditions and the unique solutions of the equations $Bv = f$ and $B_0 u = v$. The universal technique proposed here is essentially different from other factorization methods in the respect that it involves decomposition of both the equation and boundary conditions and delivers the solution in closed form. The method is implemented to solve ordinary and partial Fredholm integro-differential equations.

Keywords: boundary value problems, nonlocal conditions, factorization, linear operators, integro-differential equations, closed-form solutions.

Introduction

Let X be a complex Banach space and X^* the adjoint space of X , i.e., the set of all complex-valued linear bounded functionals ϕ on X . Let $\mathcal{A}, A_0 : X \rightarrow X$ be linear operators with boundary conditions incorporated, $\Phi = \text{col}(\phi_1, \phi_2, \dots, \phi_m)$, $\Psi = \text{col}(\psi_1, \psi_2, \dots, \psi_m)$ vectors of linear bounded functionals $\phi_i, \psi_i, i = 1, 2, \dots, m$, and $S(s_1, s_2, \dots, s_m), G = (g_1, g_2, \dots, g_m)$ vectors of functions $s_i, g_i \in X, i = 1, 2, \dots, m$. Let the operator $B_1 : X \rightarrow X$ be defined by

$$B_1 = \mathcal{A} - S\Phi - G\Psi(A_0),$$

and consider the boundary value problem

$$B_1 u = \mathcal{A}u - S\Phi(u) - G\Psi(A_0 u) = f, \quad u \in D(B_1),$$

where $f \in X$ is a given forcing function and u is the unknown function.

The primary objective of the paper is to establish factorization conditions under which this problem can be decomposed into two simpler lower order boundary value problems and derive the unique solution in closed form. The second goal is to implement this procedure to solve boundary value problems for ordinary and partial Fredholm integro-differential equations with nonlocal boundary conditions. In this case B_1 is an integro-differential operator, \mathcal{A} is a differential operator of order n with nonlocal boundary conditions incorporated, and the functionals $\phi_i, \psi_i, i = 1, \dots, m$ are integrals with constant limits.

Integro-differential equations model many situations in biology, physics, economics, engineering and applied mathematics. Boundary value problems involving an integro-differential equation and nonlocal boundary conditions are very difficult to solve analytically and therefore very often numerical methods are employed. Factorization methods, where they can be applied, can reduce the problem to simpler lower order problems which can be solved and thus construct the solution of the initial complex problem [1–20].

The novelty of the factorization method presented here differs from other factorization methods in the literature in the respect that it involves decomposition of both the equation and boundary conditions and

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delivers the solution in closed form. The technique is new development in Banach spaces and an extension of a procedure used successfully by the authors to solve various other boundary value problems [21–24] and [25–27].

The method is simple to program to any Computer Algebra System.

The rest of the paper is organized as follows. In Section 1 some preliminary results are quoted. In Section 2 the solvability, uniqueness and decomposition conditions are established and the factorization solution method is explicated. In Section 3 two example problems are solved to show the implementation and efficiency of the method.

Preliminaries

Let X, Y be complex Banach space and $A : X \rightarrow Y$ a linear operator with $D(A)$ and $R(A)$ denoting its domain and range, respectively. We recall that A is said to be *injective* (or *uniquely solvable*) if for all $u_1, u_2 \in D(A)$ such that $Au_1 = Au_2$, follows that $u_1 = u_2$; alternatively, A is injective if and only if $\ker A = \{0\}$. The operator A is called *surjective* (or *everywhere solvable*) if $R(A) = Y$. The operator A is called *bijective* if A is both injective and surjective. Lastly, A is said to be *correct* if A is bijective and its inverse A^{-1} is bounded on Y . The problem $Au = f$ is called *correct* if the operator A is correct.

An operator $B_1 : X \rightarrow X$ is said to be factorable if there exist two operators $B_0, B : X \rightarrow X$ such that B_1 can be written as a product $B_1 = BB_0$. In this case, BB_0 is a *factorization* (*decomposition*) of B_1 .

Throughout the paper, we will use the notation $\Phi(g)$ to denote the $m \times m$ matrix whose i, j -th entry $\phi_i(g_j)$ is the value of the functional ϕ_i on element g_j , where $i, j = 1, \dots, m$. Note that $\Phi(gC) = \Phi(g)C$, where C is a $m \times k$ constant matrix. We will also denote by \mathbf{c} the column vector $\mathbf{c} = \text{col}(c_1, \dots, c_m)$ and by $0_m, I_m$ the zero and identity $m \times m$ matrices, respectively.

We recall Corollary 3.11 from [25] which will need to prove the theorems below.

Corollary 1. Let A be a correct operator on a Banach space X and the components of the vectors $G = (g_1, \dots, g_m)$ and $F = \text{col}(F_1, \dots, F_m)$ are arbitrary elements of X and X^* , respectively. Then the operator $B : X \rightarrow X$ defined by

$$Bu = Au - GF(Au) = f, \quad D(B) = D(A), \quad f \in X \quad (1)$$

is correct if and only if

$$\det L = \det[I_m - F(G)] \neq 0. \quad (2)$$

If B is correct, then the unique solution of (1) for every $f \in X$ is given by

$$u = B^{-1}f = A^{-1}f + A^{-1}G[I_m - F(G)]^{-1}F(f). \quad (3)$$

The following theorem is the generalization of Theorem 1 in [28] and here we prove it without requiring the correctness of the operator A and the linear independence of the components of the functional vector $\Psi = \text{col}(\psi_1, \dots, \psi_m)$.

Theorem 2. Let X, Y and Z be Banach spaces and $A : X \rightarrow Y$ be a linear injective operator with $D(A) \subset Z \subseteq X$. Further let the vector $G = (g_1, \dots, g_m) \in Y^m$ and the column vector $\Psi = \text{col}(\psi_1, \dots, \psi_m)$, where $\psi_1, \dots, \psi_m \in Z^*$. Then:

(i) The operator $B : X \rightarrow Y$ defined by

$$Bu = Au - G\Psi(u) = f, \quad D(B) = D(A), \quad f \in X, \quad (4)$$

is injective if and only if

$$\det W = \det[I_m - \Psi(A^{-1}G)] \neq 0. \quad (5)$$

(ii) If B is injective and A is bijective, then B is bijective and for any $f \in Y$, the unique solution of (4) is given by

$$u = B^{-1}f = A^{-1}f + A^{-1}GW^{-1}\Psi(A^{-1}f). \quad (6)$$

(iii) If B is injective and A is correct, then B is correct.

Proof. (i) The sufficient injectiveness condition of the operator B is proved as in [28].

Now, we prove the converse statement “if the operator B is injective, then $\det W \neq 0$ ” or equivalently “if $\det W = 0$, then the operator B is not injective”. Suppose $\det W = 0$. Then there exists a nonzero vector $\mathbf{c} = \text{col}(c_1, \dots, c_m)$ such that $W\mathbf{c} = \mathbf{0}$. Consider the element $u_0 = A^{-1}G\mathbf{c}$. This element is nonzero, because otherwise we would have

$$W\mathbf{c} = [I_m - \Psi(A^{-1}G)]\mathbf{c} = \mathbf{c} - \Psi(A^{-1}G\mathbf{c}) = \mathbf{c} \neq \mathbf{0},$$

which is a contradiction. Further,

$$Bu_0 = Au_0 - G\Psi(u_0) = G\mathbf{c} - G\Psi(A^{-1}G)\mathbf{c} = G[I_m - G\Psi(A^{-1}G)]\mathbf{c} = GW\mathbf{c} = 0,$$

which means that $u_0 \in \ker B$ and thus B is not injective.

(ii) Let B is injective and A is bijective. Then (5) holds ($\det W \neq 0$) and for any $f \in Y$ from (4) follows that

$$u = A^{-1}G\Psi(u) + A^{-1}f, \tag{7}$$

and

$$\begin{aligned} \Psi(u) &= \Psi(A^{-1}G)\Psi(u) + \Psi(A^{-1}f), \\ [I_m - \Psi(A^{-1}G)]\Psi(u) &= \Psi(A^{-1}f), \\ \Psi(u) &= [I_m - \Psi(A^{-1}G)]^{-1}\Psi(A^{-1}f). \end{aligned} \tag{8}$$

Substituting (8) into (7), we obtain the unique solution (6). Since this solution is given for arbitrary $f \in Y$, then $R(B) = Y$, i.e., B is surjective. Hence B is a bijective operator.

(iii) If B is injective and A is correct, then from (6) follows that B^{-1} is bounded since A^{-1} and Ψ are bounded. Hence B is correct. \square

Main results

Theorem 3. Let X and Z_0, Z be Banach spaces, $Z_0, Z \subseteq X$, the vectors $G_0 = (g_{10}, \dots, g_{m0})$, $G = (g_1, \dots, g_m)$, $S = (s_1, \dots, s_m) \in X^m$, the components of the column vectors $\Phi = \text{col}(\phi_1, \dots, \phi_m)$ and $\Psi = \text{col}(\psi_1, \dots, \psi_m)$ belong to Z_0^* and Z^* , respectively, and the operators $B_0, B, B_1 : X \rightarrow X$ be defined by

$$B_0u = A_0u - G_0\Phi(u) = f, \quad D(B_0) = D(A_0) \subset Z_0, \tag{9}$$

$$Bu = Au - G\Psi(u) = f, \quad D(B) = D(A) \subset Z, \tag{10}$$

$$B_1u = AA_0u - S\Phi(u) - G\Psi(A_0u) = f, \quad D(B_1) = D(AA_0), \tag{11}$$

where A_0 and A are linear correct operators on X and $G_0 \in D(A)^m$. Then the following statements are satisfied:

(i) If

$$S \in R(B)^m \quad \text{and} \quad S = BG_0 = AG_0 - G\Psi(G_0), \tag{12}$$

then the operator B_1 can be factorized as $B_1 = BB_0$.

(ii) If (12) holds, then the operator $B_1 = BB_0$ is correct if and only if the operators B_0 and B are correct which means that

$$\det L_0 = \det[I_m - \Phi(A_0^{-1}G_0)] \neq 0 \quad \text{and} \quad \det L = \det[I_m - \Psi(A^{-1}G)] \neq 0, \tag{13}$$

and the unique solution of (11) is

$$\begin{aligned} u = B_1^{-1}f &= A_0^{-1}A^{-1}f + [A_0^{-1}A^{-1}G + A_0^{-1}G_0L_0^{-1}\Phi(A_0^{-1}A^{-1}G)]L^{-1}\Psi(A^{-1}f) \\ &\quad + A_0^{-1}G_0L_0^{-1}\Phi(A_0^{-1}A^{-1}f). \end{aligned} \tag{14}$$

Proof. (i) Taking into account that $G_0 \in D(A)^m$ and (9)-(11) we get

$$\begin{aligned} D(BB_0) &= \{u \in D(B_0) : B_0u \in D(B)\} \\ &= \{u \in D(A_0) : A_0u - G_0\Phi(u) \in D(A)\} \\ &= \{u \in D(A_0) : A_0u \in D(A)\} = D(AA_0) = D(B_1). \end{aligned}$$

So $D(B_1) = D(BB_0)$. Let $y = B_0u$. Then for each $u \in D(AA_0)$ since (10) and (9) we have

$$\begin{aligned} BB_0u &= By = Ay - G\Psi(y) \\ &= A[A_0u - G_0\Phi(u)] - G\Psi(A_0u - G_0\Phi(u)) \\ &= AA_0u - AG_0\Phi(u) - G\Psi(A_0u) + G\Psi(G_0)\Phi(u) \end{aligned}$$

$$\begin{aligned}
 &= AA_0u - [AG_0 - G\Psi(G_0)]\Phi(u) - G\Psi(A_0u) \\
 &= AA_0u - BG_0\Phi(u) - G\Psi(A_0u),
 \end{aligned} \tag{15}$$

where the relation $BG_0 = AG_0 - G\Psi(G_0)$ follows from (10) if instead of u we take G_0 . By comparing (15) with (11) it is easy to verify that $B_1u = BB_0u$ for each $u \in D(AA_0)$ if a vector S satisfies (12).

(ii) Let the operator B_1 be defined by (11), where $S = BG_0$. Then Equation (11) can be equivalently presented in the matrix form:

$$B_1u = AA_0u - (BG_0, G) \begin{pmatrix} \Phi(A_0^{-1}A^{-1}AA_0u) \\ \Psi(A^{-1}AA_0u) \end{pmatrix} = f$$

or

$$B_1u = \mathcal{A}u - \mathcal{G}\mathcal{F}(\mathcal{A}u) = f, \quad D(B_1) = D(\mathcal{A}),$$

where $\mathcal{A} = AA_0$, $\mathcal{G} = (BG_0, G)$, $\mathcal{F} = \text{col}(\hat{\Phi}, \hat{\Psi})$, and

$$\mathcal{F}(v) = \begin{pmatrix} \hat{\Phi}(v) \\ \hat{\Psi}(v) \end{pmatrix} = \begin{pmatrix} \Phi(A_0^{-1}A^{-1}v) \\ \Psi(A^{-1}v) \end{pmatrix}.$$

Notice that the operator $\mathcal{A} = AA_0$ is correct, because of A and A_0 are correct, and that the vector \mathcal{F} is bounded, since the vector $\hat{\Phi}$ (resp. $\hat{\Psi}$) is bounded as a superposition of a bounded functional Φ (resp. Ψ) and a bounded operator $A_0^{-1}A^{-1}$ (resp. A^{-1}). Then we apply Corollary 1. In accordance to (2), (3), the operator B_1 is correct if and only if

$$\begin{aligned}
 \det L_1 &= \det[I_{2m} - \mathcal{F}(\mathcal{G})] = \det \left[\begin{pmatrix} I_m & 0_m \\ 0_m & I_m \end{pmatrix} - \begin{pmatrix} \hat{\Phi}(BG_0) & \hat{\Phi}(G) \\ \hat{\Psi}(BG_0) & \hat{\Psi}(G) \end{pmatrix} \right] \\
 &= \det \begin{pmatrix} I_m - \hat{\Phi}(AG_0 - G\Psi(G_0)) & -\hat{\Phi}(G) \\ -\hat{\Psi}(AG_0 - G\Psi(G_0)) & I_m - \hat{\Psi}(G) \end{pmatrix} \\
 &= \det \begin{pmatrix} I_m - \Phi(A_0^{-1}G_0 - A_0^{-1}A^{-1}G\Psi(G_0)) & -\Phi(A_0^{-1}A^{-1}G) \\ -\Psi(G_0 - A^{-1}G\Psi(G_0)) & I_m - \Psi(A^{-1}G) \end{pmatrix} \\
 &= \det \begin{pmatrix} I_m - \Phi(A_0^{-1}G_0) + \Phi(A_0^{-1}A^{-1}G)\Psi(G_0) & -\Phi(A_0^{-1}A^{-1}G) \\ -\Psi(G_0) + \Psi(A^{-1}G)\Psi(G_0) & I_m - \Psi(A^{-1}G) \end{pmatrix} \neq 0.
 \end{aligned} \tag{16}$$

Multiplying by $\Psi(G_0)$ from the left the second column of the matrix in (16) and then adding to the first column, we get

$$\begin{aligned}
 \det L_1 &= \det \begin{pmatrix} I_m - \Phi(A_0^{-1}G_0) & -\Phi(A_0^{-1}A^{-1}G) \\ 0_m & I_m - \Psi(A^{-1}G) \end{pmatrix} \\
 &= \det[I_m - \Phi(A_0^{-1}G_0)] \det[I_m - \Psi(A^{-1}G)] = \det L_0 \det L \neq 0.
 \end{aligned}$$

So we proved that the operator B_1 is correct if and only if (13) is fulfilled. From (13), by Theorem 2, follows that the operators B and B_0 are correct.

Let now $u \in D(AA_0)$ and $B_1u = BB_0u = f$. Then, by Theorem 2 (ii), since B, B_0 are correct operators, we obtain

$$\begin{aligned}
 B_0u &= B^{-1}f = A^{-1}f + A^{-1}GL^{-1}\Psi(A^{-1}f), \\
 u &= B_0^{-1}(A^{-1}f + A^{-1}GL^{-1}\Psi(A^{-1}f)).
 \end{aligned}$$

Denote $g = A^{-1}f + A^{-1}GL^{-1}\Psi(A^{-1}f)$. By using Theorem 2 (ii) again, with A_0, G_0, Φ, L_0, g in place of A, G, Ψ, L, f respectively, we get

$$\begin{aligned}
 u &= B_0^{-1}g = A_0^{-1}g + A_0^{-1}G_0L_0^{-1}\Phi(A_0^{-1}g) = A_0^{-1}(A^{-1}f + A^{-1}GL^{-1}\Psi(A^{-1}f)) \\
 &+ A_0^{-1}G_0L_0^{-1}\Phi(A_0^{-1}(A^{-1}f + A^{-1}GL^{-1}\Psi(A^{-1}f))) = A_0^{-1}A^{-1}f + A_0^{-1}A^{-1}GL^{-1}\Psi(A^{-1}f) \\
 &+ A_0^{-1}G_0L_0^{-1}[\Phi(A_0^{-1}A^{-1}f) + \Phi(A_0^{-1}A^{-1}G)L^{-1}\Psi(A^{-1}f)],
 \end{aligned}$$

which implies (14). The theorem is proved. □

The next theorem is useful for applications and is proved by using Theorem 3.

Theorem 4. Let the spaces X, Z_0, Z , the vectors S, G, Φ, Ψ be defined as in Theorem 3 and the operator $B_1 : X \rightarrow X$ by

$$B_1 u = \mathcal{A}u - S\Phi(u) - G\Psi(A_0 u) = f, \quad u \in D(B_1), \quad (17)$$

where A_0 is a correct m -order differential operator with $D(A_0) \subset Z_0$ and \mathcal{A} is a n -order differential operator, $m < n$. Then the next statements are fulfilled:

(i) If there exists an $n - m$ order differential bijective operator $A : X \rightarrow X$ such that

$$\mathcal{A} = AA_0, \quad D(B_1) = D(AA_0), \quad D(A) \subset Z \subseteq X, \quad (18)$$

$$\det L = \det[I_m - \Psi(A^{-1}G)] \neq 0, \quad (19)$$

then the operator B_1 is factorized as $B_1 = BB_0$, where B_0, B are defined by (9), (10),

$$G_0 = A^{-1}S + A^{-1}GL^{-1}\Psi(A^{-1}S), \quad (20)$$

the operator A and vectors G, Ψ are determined from (18) and (17), respectively, and the operator A_0 and a vector Φ from (17).

(ii) If in addition to (i) A is correct, then the operator $B_1 = BB_0$ is correct if and only if

$$\det L_0 = \det[I_m - \Phi(A_0^{-1}G_0)] \neq 0 \quad (21)$$

and the unique solution of (17), (18) is given by

$$u = B_0^{-1}B^{-1}f = B_0^{-1}v = A_0^{-1}v + A_0^{-1}G_0L_0^{-1}\Phi(A_0^{-1}v), \quad (22)$$

where

$$v = A^{-1}f + A^{-1}GL^{-1}\Psi(A^{-1}f). \quad (23)$$

Proof. (i) Suppose that there exist the operators A, B, B_0 , defined in (i). Acting by the operator B on the vector G_0 , defined by (20), we get.

$$\begin{aligned} BG_0 &= AG_0 - G\Psi(G_0) \\ &= A(A^{-1}S + A^{-1}GL^{-1}\Psi(A^{-1}S)) - G\Psi(A^{-1}S + A^{-1}GL^{-1}\Psi(A^{-1}S)) \\ &= S + GL^{-1}\Psi(A^{-1}S) - G\Psi(A^{-1}S) - G\Psi(A^{-1}G)L^{-1}\Psi(A^{-1}S) \\ &= S + G[I_m - \Psi(A^{-1}G)]L^{-1}\Psi(A^{-1}S) - G\Psi(A^{-1}S) = S. \end{aligned}$$

So $BG_0 = S$. From (17) for $\mathcal{A} = AA_0$ and $BG_0 = S$ we get

$$B_1 u = AA_0 u - BG_0\Phi(u) - G\Psi(A_0 u) = f, \quad u \in D(AA_0). \quad (24)$$

Denote $y = A_0 u$. Then from (24) for any $u \in D(AA_0)$ follows that

$$B_1 u = Ay - G\Psi(y) - BG_0\Phi(u) = By - BG_0\Phi(u) = B(A_0 u - G_0\Phi(u)) = BB_0 u.$$

In Theorem 3 (i) we proved that $D(BB_0) = D(AA_0) = D(B_1)$. Consequently, B_1 is factorized in $B_1 = BB_0$.

(ii) Let A be a correct operator. Then by Theorem 2, since (19), (21), the operators B, B_0 are correct too. Remind that for G_0 , defined by (20), we proved in (i) that $BG_0 = S$. Then by Theorem 3 (i), (iii), we have the factorization $B_1 = BB_0$ and B_1 is correct if and only if $\det L \neq 0$ and $\det L_0 \neq 0$. But by assumption $\det L \neq 0$. Thus B_1 is correct if and only if (21) holds. Let $BB_0 u = f$ for any $f \in X$. Then because of the operators B, B_0 are correct, we obtain

$$B_0 u = B^{-1}f = A^{-1}f + A^{-1}GL^{-1}\Psi(A^{-1}f).$$

From the above, denoting $v = A^{-1}f + A^{-1}GL^{-1}\Psi(A^{-1}f)$, follows that

$$B_0 u = v, \quad u = B_0^{-1}v = A_0^{-1}v + A_0^{-1}G_0L_0^{-1}\Phi(A_0^{-1}v),$$

which give (23) and (22). So the theorem is proved. \square

Remark 5. Usually in applications X is the space $C[a, b]$ or $L_p(a, b)$, $p = 1, 2, \dots$, and Z_0, Z are the spaces $C^k[a, b]$ or $W_p^k(a, b)$, $k = 1, \dots, n$, respectively. Problem (17) can be solved by factorization method if it is possible to determine from (17) the vectors S, G, Φ, Ψ and the operators A_0, A such that

$$\mathcal{A} = AA_0, \quad D(B_1) = D(AA_0), \quad D(A) \subset Z, \quad D(A_0) \subset Z_0, \quad \det L \neq 0, \quad \det L_0 \neq 0.$$

If the above conditions are fulfilled, then a unique solution to (17) can be found by (22), (23), where G_0 is given by (20).

Illustrative Examples

To explain the implementation of the factorization method and to show its efficiency, we solve two example problems.

Example 1. Let us find the solution of the nonlocal boundary value problem

$$\begin{aligned} u''(t) - (t+1) \int_0^1 (t-1)u(t)dt - t^2 \int_0^1 t^3 u'(t)dt &= 2 - 3t, \quad 0 < t < 1, \\ u(0) + u(1) &= 0, \quad u'(0) - 4u'(1) = 0. \end{aligned} \quad (25)$$

The operator $B_1 : C[0, 1] \rightarrow C[0, 1]$ corresponding to the problem is correct. The unique solution to problem (25) is given by the formula

$$u(t) = -\frac{5(1204t^4 + 402256t^3 - 811850t^2 + 549488t - 70549)}{4037236}. \quad (26)$$

Proof. First we need to find the operators A, A_0 and check the condition $D(B_1) = D(AA_0)$. If we compare equation (25) with Problem (17), (18), it is natural to take $X = C[0, 1]$, $m = 1$, $I_m = 1$,

$$Au = AA_0u = u''(t), \quad (27)$$

$$\begin{aligned} D(B_1) &= \{u(t) \in C^2[0, 1] : u(0) + u(1) = 0, \quad u'(0) - 4u'(1) = 0\}, \\ A_0u(t) &= u'(t), \quad D(A_0) = \{u(t) \in C^1[0, 1] : u(0) = -u(1)\}, \\ \Phi(u) &= \int_0^1 (t-1)u(t)dt, \quad \Psi(A_0u) = \int_0^1 t^3 u'(t)dt, \end{aligned} \quad (28)$$

$S = t + 1$, $G = t^2$. Let us denote $A_0u(t) = u'(t) = y(t) = y$. Then from (27) we have $y \in D(A)$, $AA_0u = (u'(t))' = y'(t) = Ay(t)$, $y(0) - 4y(1) = 0$. So we proved that

$$Ay = y'(t), \quad D(A) = \{y(t) \in C^1[0, 1] : y(0) - 4y(1) = 0\}.$$

Further by definition we find

$$\begin{aligned} D(AA_0) &= \{u(t) \in D(A_0) : A_0u(t) \in D(A)\} \\ &= \{u(t) \in C^1[0, 1] : u(0) = -u(1), \quad u'(t) \in C^1[0, 1], \quad u'(0) - 4u'(1) = 0\} \\ &= \{u(t) \in C^2[0, 1] : u(0) + u(1) = 0, \quad u'(0) - 4u'(1) = 0\} = D(B_1). \end{aligned}$$

So $D(B_1) = D(AA_0)$. It is easy to verify that the operators A, A_0 are correct on $C[0, 1]$ and that for every $f(t) \in C[0, 1]$ the following formulae hold true

$$A^{-1}f(t) = \int_0^t f(x)dx - \frac{4}{3} \int_0^1 f(x)dx, \quad (29)$$

$$A_0^{-1}f(t) = \int_0^t f(x)dx - \frac{1}{2} \int_0^1 f(x)dx. \quad (30)$$

From (28) we have

$$\Phi(f) = \int_0^1 (x-1)f(x)dx, \quad \Psi(f) = \int_0^1 x^3 f(x)dx. \quad (31)$$

Then $|\Phi(f)| \leq \frac{1}{2}\|f(x)\|_C$, $|\Psi(f)| \leq \frac{1}{4}\|f(x)\|_C$, that is $\Phi, \Psi \in C^*[0, 1]$ and $Z_0 = Z = C[0, 1]$. Using (29), (31) and (19), we obtain

$$A^{-1}G = \int_0^t x^2 dx - \frac{4}{3} \int_0^1 x^2 dx = \frac{t^3}{3} - \frac{4}{9},$$

$$\Psi(A^{-1}G) = \int_0^1 x^3 \left(\frac{x^3}{3} - \frac{4}{9} \right) dx = -\frac{4}{63},$$

$$\det L = \det[I_m - \Psi(A^{-1}G)] = 1 + 4/63 = 67/63, \quad L^{-1} = 63/67.$$

So (19) is fulfilled. Further using (20), (23), (29), (31) for $S = t + 1, G = t^2$ and $f(t) = 2 - 3t$ we find

$$\begin{aligned} A^{-1}f &= -\frac{3t^2}{2} + 2t - \frac{2}{3}, \quad \Psi(A^{-1}f) = -\frac{1}{60}, \\ v &= A^{-1}f + A^{-1}GL^{-1}\Psi(A^{-1}f) = -\frac{7t^3 + 2010t^2 - 2680t + 884}{1340}, \\ A^{-1}S &= \int_0^t (x+1)dx - \frac{4}{3} \int_0^1 (x+1)dx = \frac{t^2}{2} + t - 2, \\ \Psi(A^{-1}S) &= \int_0^1 x^3 \left(\frac{x^2}{2} + x - 2 \right) dx = -\frac{13}{63}, \\ G_0 &= A^{-1}S + A^{-1}GL^{-1}\Psi(A^{-1}S) = -\frac{273t^3 - 2010t^2 - 4020t + 7676}{4020}. \end{aligned} \tag{32}$$

Taking into account (30), (31), we obtain

$$A_0^{-1}G_0 = -\frac{546t^4 - 5360t^3 - 16080t^2 + 61408t - 20257}{32160}, \quad \Phi(A_0^{-1}G_0) = -\frac{44509}{964800}.$$

Since

$$\det L_0 = \det[I_m - \Phi(A_0^{-1}G_0)] = \frac{1009309}{964800} \neq 0, \quad \text{then } L_0^{-1} = \frac{964800}{1009309},$$

and by Theorem 4 (ii), Problem (25) is correct. By (30)-(32) we calculate

$$A_0^{-1}v = -\frac{14t^4 + 5360t^3 - 10720t^2 + 7072t - 863}{10720}, \quad \Phi(A_0^{-1}v) = \frac{1223}{107200}.$$

Substituting these values into (22), i.e.,

$$u = A_0^{-1}v + A_0^{-1}G_0L_0^{-1}\Phi(A_0^{-1}v),$$

we obtain the unique solution to (25), which is given by (26).

Example 2. Let $\bar{\Pi} = \{(t, s) \in \mathbb{R}^2 : 0 \leq t, s \leq 1\}$, $u = u(t, s), u'_t, u''_{ts} \in C(\bar{\Pi})$. The operator $B_1 : C(\bar{\Pi}) \rightarrow C(\bar{\Pi})$ corresponding to the problem:

$$\begin{aligned} u''_{ts}(t, s) - (2t - s) \int_0^1 \int_0^1 u(t, s) dt ds - (t + s) \int_0^1 \int_0^1 tsu'_t(t, s) dt ds \\ = -\frac{213s + 149t - 600}{220}, \end{aligned} \tag{33}$$

$$u(0, s) = s \int_0^1 \int_0^1 t^2 u(t, s) dt ds,$$

$$u'_t(t, 0) = (2t - 1) \int_0^1 \int_0^1 (s + 3)u'_t(t, s) dt ds$$

is correct. The unique solution to Problem (33) is given by the formula

$$u(t, s) = \frac{6s(25t + 1) + 275t(t - 1)}{55}. \tag{34}$$

Proof. First we need to find the operators A, A_0 and check the condition $D(B_1) = D(AA_0)$. If we compare (33) with Problem (17), (18), it is natural to take $X = C(\bar{\Pi}), m = 1, I_m = 1,$

$$AA_0x = u''_{ts}(t, s), \tag{35}$$

$$D(B_1) = \{u(t, s) \in C(\bar{\Pi}), u'_t, u''_{ts} \in C(\bar{\Pi}), u(0, s) = s \int_0^1 \int_0^1 t^2 u(t, s) dt ds,$$

$$u'_t(t, 0) = (2t - 1) \int_0^1 \int_0^1 (s + 3)u'_t(t, s)dt ds, \tag{36}$$

$$A_0u(t, s) = u'_t(t, s), \tag{37}$$

$$D(A_0) = \{u(t, s) \in C(\overline{\Pi}) : u'_t(t, s) \in C(\overline{\Pi}), \quad u(0, s) = s \int_0^1 \int_0^1 t^2u(t, s)dt ds\},$$

$$\Phi(u) = \int_0^1 \int_0^1 u(t, s)dt ds, \quad \Psi(A_0u) = \int_0^1 \int_0^1 tsu'_t(t, s)dt ds, \tag{38}$$

$S = 2t - s, G = t + s, f = -(213s + 149t - 600)/220$. In (37), denote $A_0u(t, s) = u'_t(t, s) = y(t, s) = y$. Then from (35), (36) we have $y \in D(A), AA_0u = (u'_t(t, s))'_s = y'_s(t, s) = Ay(t, s)$ and $y(t, 0) = (2t - 1) \int_0^1 \int_0^1 (s + 3)y(t, s)dt ds$. So we proved that

$$Ay = y'_s(t, s), \quad D(A) = \{y(t, s) \in C(\overline{\Pi}) : y'_s \in C(\overline{\Pi}), y(t, 0) = (2t - 1) \int_0^1 \int_0^1 (s + 3)y(t, s)dt ds\}.$$

Then by definition

$$D(AA_0) = \{u(t, s) \in D(A_0) : A_0u(t, s) \in D(A)\}$$

$$= \{u(t, s) \in C(\overline{\Pi}) : u'_t \in C(\overline{\Pi}), \quad u(0, s) = s \int_0^1 \int_0^1 t^2u(t, s)dt ds,$$

$$u'_t(t, 0) = (2t - 1) \int_0^1 \int_0^1 (s + 3)u'_t(t, s)dt ds, \quad u''_{ts}(t, s) \in C(\overline{\Pi})\}$$

$$= \{u(t, s) \in C(\overline{\Pi}), u'_t, u''_{ts} \in C(\overline{\Pi}), \quad u(0, s) = s \int_0^1 \int_0^1 t^2u(t, s)dt ds,$$

$$u'_t(t, 0) = (2t - 1) \int_0^1 \int_0^1 (s + 3)u'_t(t, s)dt ds\} = D(B_1).$$

Thus $D(B_1) = D(AA_0)$. It is easy to verify that the operators A, A_0 are correct on $C(\overline{\Pi})$ and for every $f(t, s) \in C(\overline{\Pi})$ hold true

$$A^{-1}f(t, s) = \int_0^s f(t, x)dx + (2t - 1) \int_0^1 \int_0^1 \int_0^s (s + 3)f(t, x)dx dt ds, \tag{39}$$

$$A_0^{-1}f(t, s) = \int_0^t f(z, s)dz + \frac{6s}{5} \int_0^1 \int_0^1 \int_0^t t^2f(z, s)dz dt ds. \tag{40}$$

From (38) we get

$$\Phi(f) = \int_0^1 \int_0^1 f(t, s)dt ds, \quad \Psi(f) = \int_0^1 \int_0^1 tsf(t, s)dt ds. \tag{41}$$

Then $\Phi, \Psi \in C^*(\overline{\Pi})$ and $Z_0 = Z = C(\overline{\Pi})$. Using (39), (41) and (19) we obtain

$$A^{-1}G = \frac{s^2}{2} + st + \frac{37(2t - 1)}{24}, \quad \Psi(A^{-1}G) = \frac{29}{96}, \quad L = 1 - \Psi(A^{-1}G) = 67/96, \quad L^{-1} = 96/67.$$

So (19) is fulfilled. Further, using (39), (41), (23), (20) for $S = 2t - s, G = t + s$ and $f(t) = -(213s + 149t - 600)/220$ we find

$$A^{-1}f = -\frac{2556s^2 + 24s(149t - 600) - 19927(2t - 1)}{5280}, \quad \Psi(A^{-1}f) = \frac{2675}{4224},$$

$$v = A^{-1}f + A^{-1}GL^{-1}\Psi(A^{-1}f) = -\frac{336s^2 - 6s(424t + 5025) - 57187(2t - 1)}{11055}, \tag{42}$$

$$A^{-1}S = -\frac{s^2}{2} + 2st + \frac{29(2t - 1)}{24}, \quad \Psi(A^{-1}S) = \frac{25}{96},$$

$$G_0 = A^{-1}S + A^{-1}GL^{-1}\Psi(A^{-1}S) = -\frac{42s^2 - 318st - 239(2t - 1)}{134}.$$

Taking into account (40), (41) we obtain

$$A_0^{-1}G_0 = -\frac{2100s^2t - 3s(2650t^2 + 9) - 11950t(t - 1)}{6700}, \quad \Phi(A_0^{-1}G_0) = -\frac{6019}{40200}.$$

Since

$$\det L_0 = \det[I_m - \Phi(A_0^{-1}G_0)] = \frac{46219}{40200} \neq 0,$$

then $L_0^{-1} = \frac{40200}{46219}$, and hence by Theorem 4 (ii), problem (33) is correct. By (40)-(42) we calculate

$$A_0^{-1}v = -\frac{8400s^2t - 6s(5300t^2 + 125625t + 5043) - 1429675t(t - 1)}{276375},$$

$$\Phi(A_0^{-1}v) = -\frac{92438}{829125}.$$

Substituting the above values into (22), we obtain, by Theorem 4 (ii), the unique solution of (33)

$$u = A_0^{-1}v + A_0^{-1}G_0L_0^{-1}\Phi(A_0^{-1}v) = \frac{6s(25t + 1) + 275t(t - 1)}{55},$$

which is (34).

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Банах кеңістігінде локальді емес шекаралық есептерді шешуге арналған факторизация әдісі

Мақала банах кеңістігінде абстракттілі операторлары бар

$$B_1 u = Au - S\Phi(u) - G\Psi(A_0 u) = f, \quad u \in D(B_1),$$

түріндегі локалды емес шектік есептерді факторизациялау және шешуге арналған, мұндағы A, A_0 сызықтық дерексіз операторлар, S, G функция векторлары, Φ, Ψ сызықтық шектеулі функционалды векторлар және u, f функциялар. B_1 операторы белгілі бір жағдайларда $B_1 = Bb_0$ кіші екі қарапайым оператордың көбейтіндісіне факторлануы мүмкін екендігі көрсетілген. Содан кейін $B_1 u = f$ теңдеуінің шешімі мен жалғыз шешімі $Bv = f$ және $b_0 u = v$ теңдеулер шешімдерінің шешімділігі мен бірегейлігі шарттарынан оңай туындайды. Ұсынылған әмбебап әдіс басқа факторизация әдістерінен айтарлықтай ерекшеленеді, өйткені оған теңдеу мен шекаралық шарттардың факторизациясы кіреді және шешімді жабық түрде ұсынады. Бұл әдіс Фредгольмның қарапайым және жартылай интеграл-дифференциалдық теңдеулерін шешуге арналған.

Клт сөздер: шекаралық есептер, жергілікті емес жағдайлар, факторизация, сызықтық операторлар, интеграл-дифференциалдық теңдеулер, жабық түрдегі шешімдер.

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Метод факторизации для решения нелокальных краевых задач в банаховом пространстве

Статья посвящена факторизации и решению нелокальных краевых задач с операторами абстрактного вида

$$B_1 u = Au - S\Phi(u) - G\Psi(A_0 u) = f, \quad u \in D(B_1),$$

в банаховом пространстве, где A, A_0 — линейные абстрактные операторы; S, G — векторы функций; Φ, Ψ — векторы линейных ограниченных функционалов; а u, f — функции. Показано, что оператор B_1 при определенных условиях может быть факторизован в произведение двух более простых операторов меньшего порядка $B_1 = BB_0$. Тогда разрешимость и единственное решение уравнения $B_1 u = f$ легко следует из условий разрешимости и единственности решений уравнений $Bv = f$ и $B_0 u = v$. Предлагаемый универсальный метод существенно отличается от других методов факторизации, поскольку он включает факторизацию уравнения и граничных условий и предоставляет решение в замкнутой форме. Метод разработан для решения обыкновенных и частных интеграл-дифференциальных уравнений Фредгольма.

Ключевые слова: краевые задачи, нелокальные условия, факторизация, линейные операторы, интеграл-дифференциальные уравнения, решения в замкнутой форме.