1 <u>Title:</u> Sensorimotor Impairment from a New Analog of Spaceflight-altered Neurovestibular Cues

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- 3 <u>Running Title:</u> A New Spaceflight Analog for Sensorimotor Impairment
- 4 5 <u>Authors:</u>
- 6 Jordan B. Dixon<sup>1</sup>
- 7 Torin K. Clark<sup>1</sup>
- 8
- 9 <u>Affiliations:</u>
- <sup>1</sup>Smead Aerospace Engineering Sciences, University of Colorado Boulder, Boulder, Colorado,
- 11 USA
- 12
- 13 Address for correspondence:
- 14 Torin K. Clark
- 15 Bioastronautics Laboratory
- 16 University of Colorado-Boulder
- 17 1111 Engineering Dr. ECAE 100
- 18 Boulder, CO, 80309
- 19 Torin.clark@colorado.edu
- 20 Phone +1 (303)392-4015
- 21
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## 25 ABSTRACT

Exposure to microgravity during spaceflight causes central reinterpretations of orientation sensory 26 27 cues in astronauts, leading to sensorimotor impairment upon return to Earth. Currently there is no 28 ground-based analog for the neurovestibular system relevant to spaceflight. Here we propose such 29 an analog, which we term the "wheelchair head immobilization paradigm" (WHIP). The subject 30 lays on their side on a bed fixed to a modified electric wheelchair, with their head restrained by a 31 custom facemask. WHIP prevents any head tilt relative to gravity which normally produces 32 coupled stimulation to the otoliths and semicircular canals, but does not occur in microgravity. 33 Decoupled stimulation is produced through translation and rotation on the wheelchair by the 34 subject using a joystick. Following 12 hours of WHIP exposure, subjects systematically felt 35 illusory sensations of self-motion when making head tilts and had significant decrements in 36 balance and locomotion function using tasks similar to those assessed in astronauts post-37 spaceflight. These effects were not observed in our control groups without head-restraint, 38 suggesting the altered neurovestibular stimulation patterns experienced in WHIP lead to relevant 39 central reinterpretations. We conclude by discussing the findings in light of post-spaceflight 40 sensorimotor impairment, WHIP's uses beyond a spaceflight analog, limitations, and future work.

#### 41 NEW AND NOTEWORTHY

We propose, implement, and demonstrate the feasibility of a new analog for spaceflight-altered neurovestibular stimulation. Following extended exposure to the analog, we found subjects reported illusory self-motion perception. Further, they demonstrated decrements in balance and locomotion, using similar tasks as have been used to assess astronaut sensorimotor performance post-spaceflight.

47

## 48 **INTRODUCTION**

49 Humans must interpret sensory information, such as visual, vestibular, and proprioceptive cues, to produce appropriate motor control responses for everyday sensorimotor tasks like balance 50 51 and locomotion. However, sensorimotor impairment may occur either i) in individuals that have 52 experienced trauma (Minor, 1998), aging (Bermúdez Rey et al., 2016) or other dysfunction 53 (sensory, cognitive, and/or motor) (Merfeld et al., 2010), or ii) healthy individuals that are exposed 54 to an altered environment such as spaceflight (Paloski et al., 2008; Shelhamer, 2015). In the latter 55 case (Clark et al., 2015b) individuals have fully functioning sensory and motor capabilities, but 56 inappropriately interpret sensory cues yielding impaired motor responses. This interpretation of 57 sensory cues is closely associated to the concept of *internal models* – neural systems that replicate 58 the behavior/dynamics of physical systems, see (Tin & Poon, 2005) for a review – which appear 59 to be involved with spatial orientation perception (Angelaki et al., 1999, 2004; Merfeld et al., 60 1999). Presumably the central nervous system (CNS) has developed internal models appropriate 61 for the sensory motion stimulation experienced here on Earth (Cullen, 2012; Merfeld et al., 1993). 62 The continual reinforcement of our Earth environment helps maintain these internal models 63 (Wolpert et al., 1998), yielding typically excellent perception of orientation (Bortolami et al., 64 2006) and associated sensorimotor performance. However, when the environment changes 65 dramatically, such as for an astronaut in microgravity, these internal models become inappropriate. 66 This may cause the internal models to degrade (Merfeld, 2003), be adjusted for the new 67 environment (Parker et al., 1985; Young et al., 1984), and/or drive the creation of entirely new internal models (Imamizu et al., 2000; Wolpert et al., 1998). To better understand the dynamics of 68 69 sensorimotor internal models and the associated performance decrements, here we develop and 70 assess a novel ground-based analog of spaceflight-altered processing of neurovestibular cues.

71 The neurovestibular/sensorimotor response to spaceflight is thoroughly reviewed 72 elsewhere (Clark, 2019; Paloski et al., 2008; Wood et al., 2011). To summarize, upon entering 73 microgravity, the majority of astronauts experience space motion sickness (Lackner & DiZio, 74 2006) and disorientation (Paloski et al., 2008), presumably due to the altered and unexpected 75 graviceptor stimulation. Fortunately, all astronauts to date have suitably adapted to the 76 microgravity environment. This adaptation process appears to begin immediately and, at least 77 overtly, be completed within a few days (Shelhamer, 2015). However, the vestibular adaptations 78 while in microgravity produce impairment upon return to Earth (or presumably another gravity-79 rich environment, such as the moon or Mars). This includes postural (Wood et al., 2015) and 80 locomotion deficits (Mulavara et al., 2018), misperceptions of spatial orientation (Clément & 81 Wood, 2014), altered eye movements (Clément, 1998), manual control decrements (Merfeld, 82 1996), motion sickness (Lackner & DiZio, 2006), and ataxia (Paloski et al., 1993).

83 When returning to Earth, a ground support team is typically able to prevent astronaut 84 sensorimotor impairment having an operational impact on mission success. However, 85 sensorimotor impairment may have catastrophic impacts on future moon or Mars landings where 86 astronauts may have a more active piloting role and will not have a ground support team to assist 87 after landing, at least initially (Clark, 2019; Paloski et al., 2008). To date, numerous potential 88 countermeasures have been proposed, including artificial gravity (Bretl et al., 2019; Clément, 89 2015; Clément et al., 2015; Clément & Bukley, 2007; Young, 1999), sensorimotor training or 90 rehabilitation (Bloomberg et al., 2015; Clark et al., 2015a; Harm & Parker, 1993), or using 91 mechanical or electric orientation-reference devices (Galvan-Garza, 2016; Mulavara et al., 2015; 92 Rupert, 2000). Yet, to date none have been systematically evaluated in astronauts exposed to 93 microgravity, and thus have not transitioned to operational use.

94 Here on Earth, gravito-inertial acceleration (GIA) stimulation is the combination of gravity 95 and linear acceleration. GIA, which is transduced by the otolith organs of the vestibular system 96 (Fernandez & Goldberg, 1976), must be disambiguated by the CNS to distinguish between head 97 tilts (gravity) and translation (linear acceleration) (Merfeld et al., 1999). This motivated the otolith 98 tilt-translation reinterpretation (OTTR) hypothesis (Parker et al., 1985; Young et al., 1984), which 99 suggests that because "stimulation from gravity is absent during orbital flight, interpretation of 100 otolith responses as tilt is meaningless" (Young et al., 1984). Instead "[otolith signals] are centrally reinterpreted, for example, to represent linear acceleration rather than tilt" (Parker et al., 1985). 101 102 This is supported by astronauts reporting illusory perceptions of translation when making head 103 tilts post-spaceflight (Clément & Wood, 2014; Parker et al., 1985; Reschke & Parker, 1987). An 104 alternate (though potentially complementary) hypothesis, the rotation otolith tilt-translation 105 reinterpretation (ROTTR) hypothesis (Merfeld, 2003), emphasizes the importance of rotational 106 cues, such as those transduced by the semicircular canals of the vestibular system (Fernandez & 107 Goldberg, 1971). When making head tilts, the normally tightly coupled stimulation of graviceptors 108 (e.g., otoliths) and rotation sensors (e.g., semicircular canals) becomes uncoupled in microgravity. 109 This is suggested to cause "deterioration in the ability of the [CNS] to use rotational cues to help 110 accurately estimate the relative orientation of gravity ('tilt'). Changes in the ability to estimate 111 gravity then influence the ability...to estimate linear acceleration ('translation')" (Merfeld, 2003). 112 ROTTR would explain illusory translation perceptions, but also altered tilt perception, post-113 spaceflight (Clément, 1998; Clément & Wood, 2014). While the evidence is reviewed elsewhere 114 (Clark, 2019), there is currently not a well-accepted conceptual understanding of the 115 neurovestibular reinterpretation that occurs in microgravity.

116 Spaceflight investigations of sensorimotor/neurovestibular impairment are limited by a 117 relatively small number of astronauts flying and returning infrequently. The small N makes it 118 difficult to systematically assess countermeasures, capture inter-individual differences, and 119 validate a conceptual understanding of CNS reinterpretations. Further, it is difficult to perform 120 assessments *immediately* post-landing due to operational constraints (e.g., landing in remote 121 locations). This has focused scientific measures to a Field Test occurring approximately one hour 122 following landing (Reschke et al., 2019; Tomilovskaya et al., 2014), while systematic laboratory 123 measures are often delayed a day or more post-landing (Reschke & Clément, 2018b). As 124 readaptation to Earth gravity begins immediately and occurs rapidly (Carriot et al., 2015), these 125 delays likely prevent quantifying the most severe sensorimotor impairments (Paloski et al., 2008) 126 that occur during operationally demanding periods such as piloted landing or emergency vehicle 127 egress. Alternatively, a ground-based analog for spaceflight-altered central processing of 128 neurovestibular cues would overcome these constraints and limitations by enabling testing 129 numerous subjects immediately after simulated microgravity exposure.

130 Deconditioning of other physiological systems (e.g., musculoskeletal or cardiovascular) is 131 often studied using long duration exposure to head down tilt bed rest as a ground-based analog 132 (Hargens & Vico, 2016). While bed rest has been used to investigate sensorimotor changes 133 (Clément et al., 2015; Mulavara et al., 2018), it is important to note that gravity stimulation to the 134 vestibular system (and other graviceptors) is not removed in bed rest. Bed rest instead could be 135 considered a lower extremity motor coordination disuse analog for the sensorimotor system, 136 specifically not replicating the neurovestibular alterations of spaceflight. Parabolic flight can 137 replicate the neurovestibular stimulation of microgravity, but only for very short durations (20-30 138 seconds) (Karmali & Shelhamer, 2008) that are too brief to induce central reinterpretations.

139 Here, we propose a novel ground-based approach to produce sustained replication of the 140 neurovestibular cues experienced in microgravity, in a single plane by restraining the head to keep 141 gravity out of the plane of interest (Figure 1). Translation and rotation stimulation, typically 142 experienced in microgravity, is produced through the base of a motorized wheelchair attached to 143 a recumbent bed that persons lie on during exposure. To demonstrate feasibility and perform 144 preliminary validation, we assess sensorimotor functional performance (spatial orientation 145 perception, balance, and locomotion) before and immediately following extended exposure to what 146 we term the "wheelchair head immobilization paradigm" (WHIP). Additionally, we assess a 147 control condition in which the subject has similar experiences, but the head is left unrestrained to 148 avoid controlled manipulation of neurovestibular cues. Finally, we assess an additional control 149 group called the "Baseline" condition for quantifying general population performance on our 150 specific sensorimotor test battery, without any exposure to the WHIP device. While here we focus 151 on WHIP as an analog for spaceflight-altered central processing of neurovestibular cues, the 152 paradigm may be relevant to better understanding neurovestibular/sensorimotor adaptations to 153 other altered environments or individuals with pathology-based balance impairments (Wood et al., 2011). 154

155 **METHODS** 

## 156 *Neurovestibular Cues*

157 On Earth and in microgravity, as depicted in Figure 1, the otolith organs experience a shear 158 force (*sf*) in response to head linear acceleration (*a*) (panels A, C). However, only on Earth (or 159 another planetary body) in the presence of gravity (*g*) can a head tilt also elicit an afferent response 160 from the otolith organs (panel B). This highlights the importance of semicircular canal stimulation 161 in response to angular rotations/tilts ( $\omega$ ) for disambiguating cues from the otolith organs in a 162 gravity environment (panel B). In a microgravity environment (panels C, D) these two sensory 163 pathways become uncoupled such that astronaut head tilts do not have the typical combination of 164 canal and otolith stimulation. Rather, they are not subjected to the tilt-translation ambiguity as all 165 otolith stimulation is due to head translation (linear acceleration, a).

166

FIGURE 1 PLACEMENT (Neurovestibular Cues & WHIP Device)

167 Although we cannot remove the vestibular sensation of gravity here on the ground, it is 168 possible to decouple tilt and rotational cues similar to microgravity, in a single plane. By having 169 subjects lie on their sides (lateral-recumbent) on a bed capable of Earth-vertical rotation and 170 fore-aft translation, as seen in Figure 1, they can experience normal accelerations (panel E) and 171 rotation stimulation in the sagittal plane without concurrent tilt stimulation (panel F). Specifically, 172 subject's heads are fixed relative to the device to prevent out-of-plane head tilts that would elicit 173 coupled vestibular stimulation, and their interaural axis is aligned with the rotational axis of the 174 bed (panels G-I). Desired motion inputs are provided through a joystick allowing for "active" (i.e., 175 subject controlling their own motion) rotations and translations, which may be essential to induce 176 adaptation (Carriot et al., 2013; Roy & Cullen, 2001). The WHIP paradigm has the following 177 critical similarities to microgravity: 1) Most notably, WHIP prevents the vestibular organs from 178 experiencing normal, coupled rotation and tilt stimulation relative to gravity for an extended period 179 of time; 2) through active wheelchair motion, WHIP allows for normal x-axis (naso-osccipital) 180 translation, and 3) normal rotation stimulation without concurrent tilt stimulation (i.e., otolith) in 181 the sagittal plane (i.e., pitch; nodding head 'yes'). 4) Finally, WHIP removes the tonic loading of 182 gravity on the otoliths in the z-axis (rostrocaudal) as is normally experienced on Earth during erect 183 posture.

184 *Device Hardware* 

Our prototype WHIP device (Figure 1, Panel I) consisted of a steel cart mounted to the base of a commercial-off-the-shelf electric wheelchair device and a Tempur-Pedic© memory foam mattress. WHIP subjects had their head fixed in the facemask to a countered foam block supported by an aluminum and steel frame that could be adjusted to align each subject's inter-aural axis with the center of rotation of the wheelchair. The height of the frame (y-axis) could also be adjusted throughout the test for subject comfort.

191 Not pictured in Figure 1 were bed extensions that could be added during idle periods for 192 lower leg comfort, and an inertial measurement unit (IMU) fixed to the facemask either directly 193 above the right ear on the facemask (for WHIP subjects) or mounted on the underside of the table 194 (for Control subjects). The IMU was used to quantify the motions - linear accelerations and 195 angular velocities – experienced as well as inadvertent out-of-plane head tilts made by WHIP-196 subjects due to slight flexibility of the facemask. Approximately 95% of WHIP accelerations experienced at the head fell under 0.18 G's (1.8 m/s<sup>2</sup>) in the x-axis (naso-osccipital, fore-aft 197 wheelchair translation), 0.12 G's (1.2 m/s<sup>2</sup>) in the z-axis (rostrocaudal, produced via combined 198 199 wheelchair rotation and translation yielding centripetal acceleration at the head location), but were 200 as high as 0.5 G's. Similarly, 95% of y-axis rotation (pitch, sagittal plane) angular velocities were 201 less than 81 °/s, but peaked near 100 °/s. The peak forward linear velocity was 1.76 m/s. Even 202 when the subject attempted, only small out-of-plane head tilt angles were feasible within the WHIP 203 facemask ( $<3^{\circ}$ ).

204 Experimental Protocol

Subjects were pre-screened, and excluded from the study if they had a self-reported history of vestibular dysfunction, or scored in the 0<sup>th</sup> or above the 90<sup>th</sup> percentile on the Motion Sickness Susceptibility Questionnaire (Reason, 1968; Reason & Brand, 1975) as this may indicate an

208 undiagnosed vestibular dysfunction. Subjects were assigned to one of three groups: WHIP subjects 209 (head restrained with a facemask during exposure), Control subjects (head unrestrained during 210 exposure) and Baseline subjects (no exposure; general population task performance). Assignments 211 were made based upon the needs of the study prior to subject recruitment. The Control group 212 performed an identical experimental protocol, but did not have their heads restrained in a facemask 213 during the exposure phase of the protocol (details below). This allowed for subjects to perform 214 coupled head tilts relative to gravity, as desired, and experience the tonic loading of gravity in each 215 axis, while controlling for laying down for an extended duration and using the wheelchair device 216 to navigate in a novel body orientation. As some of the functional metrics adopted from previous 217 spaceflight studies were modified for the needs of the paradigm, or experiment, we tested the 218 Baseline group that does not perform any exposure phase (unmonitored daily activity) to quantify 219 variability in the general population.

220 The experimental protocol consisted of four phases: training, pre-tests, exposure (for WHIP 221 and Control groups), and post-tests. Training occurred at least 24-hours prior to the start of the 222 exposure to allow the thermoplastic facemasks to fully cure, but no more than 5 days in advance 223 to avoid receding of task-learning. The break between training and pre-test also ensured pre-test 224 performance was not artificially inflated from having recently practiced the tasks, as compared to 225 post-tests in which tasks were not just recently practiced due to the exposure. During training 226 subjects were required to practice all functional tasks, with at least as many repetitions as trials of 227 the task, and until both the experimenters and subjects subjectively determined they had adopted 228 and honed their personal sensorimotor strategy for completing the task. WHIP subjects then had a 229 custom facemask molded (Civco Medical Solutions, MTAPU standard MRI uni-frame mask). The 230 pre- and post-test were performed identically, and were used to evaluate neurovestibular adaptation

to the exposure protocol by means of functional sensorimotor performance. The pre-test was conducted within 12 hours of the start of the exposure window (i.e., evening prior to when posttests would occur, or morning of exposure day) depending on subject availability. The exposure window was nominally 12 hours due to laboratory and staff constraints. Post-tests began immediately following the conclusion of the exposure (i.e., within 15 seconds). In the case of Baseline subjects, post-tests were performed approximately 12 or 24 hours following pre-tests based upon subject availability.

238 During the exposure, WHIP and Control subjects were required to periodically drive the 239 WHIP device around a large space to stimulate the vestibular system; for the WHIP subjects this 240 stimulated uncoupled otolith and SCC cues. Subjects were required to drive for at least 25% of the 241 total exposure time with at least three distinct driving sessions defined by a continuous period of 242 activity greater than 15 minutes, but were not limited to how much they could drive. While driving, 243 subjects were instructed to explore all possible motions (i.e., left and right rotations, fore and aft 244 translations, and combinations of rotations and translations) at varying magnitudes based on 245 joystick deflection and the wheelchair power setting. We encouraged multiple styles of driving 246 that was supported by the layout of the rooms, and temporary placement of cones as a form of 247 obstacle around which they would need to maneuver. Other activities (watching movies, using a 248 smartphone or iPad, or sleeping) were unmonitored, however, additional attention during resting 249 periods was given to Control subjects to ensure they maintained a fully recumbent head position. 250 *Pre- and Post-Test Metrics* 

Four well-established balance and locomotion tests – that mimic those used to assess astronauts – were used to quantify sensorimotor performance. The presentation of the tasks was ordered from those that required the least head and body movement to the most (detailed in

254 sequence below), in effort to minimize the impact of readaptation during post-testing. Further, 255 the spatial layout of task equipment was constructed such that there was little-to-no movement required to transition between tasks. Tests began with subjects laying on their sides, and with 256 257 WHIP subjects in the facemask. The experimenter reiterated to the subject to "Please keep your 258 eyes closed, and make as little head movement as possible unless instructed otherwise for the 259 *task.*" Immediately upon conclusion of the exposure window (for WHIP and Control groups), 260 subjects were assisted to a seated position, making a slow transition to upright to minimize 261 effects from fluid shifts or cardiovascular loading.

262 Spatial Orientation Perception during Static and Dynamic (Active) Head Tilts

263 In the first task, we had WHIP and Control subjects verbally report their spatial 264 orientation perceptions in response to first static and then dynamic head tilts (Baseline subjects 265 only performed the subsequent functional performance tasks). While keeping their eyes closed, 266 they were asked to make a static head tilt forward (pitch, nose down  $\sim 20^{\circ}$ ) and maintain the head 267 tilt while answering a series of questions (details below). They were then asked to make dynamic 268 head tilts,  $\pm 20^{\circ}$  at 0.33 Hz with the aid of a metronome, while the same questions were asked. 269 The subject was instructed to stop making head tilts, and continue answering the questions once 270 4-6 head tilt cycles were made, based on their ability to clearly describe sensations. The number 271 of head tilts was kept to as few as needed to describe the sensation while limiting stimuli that 272 might induce readaptation.

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Before the task was performed, the subject was instructed to: "*describe any sensations* you might have to the best of your ability, in any verbiage you can and/or feel is most

275 appropriate. Feel free to provide as much detail as you'd like." For each series of questions, a

276	prompt question was asked first that determines whether subsequent questions followed. The							
277	structure of the series was as follows:							
278	• "Did you have any unusual perceptions of motion?"							
279	• If answered "yes":							
280	1. "Please describe it to the best of your ability."							
281	2. "Did the sense of moving oscillate?"							
282	3. "Was the sensation sustained or transient?"							
283	4. "What direction was the sensation?"							
284	5. "Do you have any additional comments?"							
285	• If answered "no":							
286	<ul> <li>Do not ask further questions to avoid biasing later subject responses</li> </ul>							
287	After the subject finished responding to the questions, they were asked to open their eyes							
288	and were assisted off the wheelchair bed into a standing position to immediately begin the next							
289	task. However, a follow-up question session occurred at the conclusion of post-testing, which we							
290	describe here. Follow-up questions did not have a rigid structure, as it was tuned to individual							
291	subject reports, but broadly were aimed to: 1) disambiguate previous verbal reports that were							
292	unclear; 2) discover distinct differences of possible sensations or conscious motor control							
293	employed pre- versus post-test; 3) determine if illusory sensations were analogous in any way to							
294	past experiences; and; 4) attempt to chart the timeline of readaptation via decay of illusory							
295	perceptions (e.g., if/when during the post-test protocol were illusory sensations unperceivable).							
296	Audio from subject reports was recorded, transcribed, and analyzed after testing. To							
297	capture patterns in subjects' motion perception reports, we recorded the number of subjects (in							
298	WHIP vs. Control) that reported any illusory sensation, whether they were sustained, the							

directions of those sensations (e.g., coronal/roll tilt, and only clockwise), and whether the
sensations were static perceptions of a rotation angle/translation distance or dynamic perception
of constant spin/translation (see Tables 1 and 2).

302

## Modified Romberg Standing Balance Test

303 The Modified Romberg Standing Balance test (Agrawal et al., 2011; Bermúdez Rey et 304 al., 2016) involves standing both on the ground and on a medium density foam pad (to make 305 kinesthetic cues unreliable), with eyes open and closed (conditions 1-4). As is standard, each 306 condition 1-4 was performed for 30 seconds or until failure. If failed, the subject was given a 307 second opportunity. Tests were presented in the typical order of increasing difficulty (1: eyes 308 open, on ground; 2: eyes closed, on ground; 3: eyes open, on foam; 4: eyes closed, on foam). 309 Following these tests, we added a fifth condition called "4 Modified", or "4M", involving  $\pm 20^{\circ}$ 310 head tilts at 0.33Hz while standing on the foam pad (16"x18"x3" with slip covers, Sunmate from 311 Dynamic Systems Inc.) with eyes closed. This condition was inspired by condition 5M added to 312 the Sensory Organization Test (SOT) for computerized dynamic posturography previously used 313 as a sensitive measure of balance function in returning astronauts (Jain et al., 2010; Wood et al., 314 2015), and is also similar to Trial 3 of the sharpened Clinical Test of Sensory Interaction on 315 Balance (Cohen et al., 2019). The experimental setup used for those spaceflight experiments, 316 however, had hardware to measure body sway which was used to calculate an equilibrium score 317 metric. Without the ability to measure body sway and calculate the same metric, we introduced a 318 new failure criteria for our condition 4M associated with the secondary task of performing head 319 tilts. In addition to the standard failure criteria of the Modified Romberg test – the subject 320 moving their feet, uncrossing their arms, opening their eyes, or falling (caught by the 321 experimenters) – a trial was considered a failure if the subject could not maintain performing

head tilts for more than 3 seconds. This new condition 4M was repeated for eight trials, each lasting up to 15 seconds or until a failure, as it was anticipated to be a relatively sensitive metric based on post-spaceflight tests (Wood et al., 2015). All eight trials of Condition 4M are performed by the subject regardless of their performance on Conditions 1-4 or previous trials of Condition 4M. This and the following two performance tasks were initially graded in real-time, but were also video recorded for detailed review and validation.

### 328

## Tandem Walk (Heel-to-Toe Walking) Task

329 Next, a standard Tandem Walk task was assessed (Cohen et al., 2012b) that had subjects 330 walk forward with arms crossed for 10 steps, with the heel touching the toe of the other foot on 331 each step. Subjects did this in two conditions, first with eyes open and then with eyes closed. An 332 error in a step included having a space between the heel and toe (small gaps,  $\sim 1$  inch, were 333 allowable), the foot touching the ground while bringing it forward (side stepping), not taking a 334 step for more than 3 seconds, or opening eyes when they were supposed to be closed (Mulavara 335 et al., 2018). This procedure and failure criteria were selected to match those used to assess 336 returning astronauts in the laboratory setting (Mulavara et al., 2018), as well as in the Field Test 337 (Tomilovskaya et al., 2014) with our addition of the eyes open condition. By reviewing video 338 recordings, a naïve judge graded each step and represents the data presented in the Results 339 section. For WHIP subjects, three additional blinded judges scored the videos, and the results were highly correlated ( $r^2 = 0.833$ ; 0.884; 0.868). 340

#### 341

#### Modified Functional Mobility Test

The final task had WHIP and Control subjects perform eight trials of a complex obstacle course (Figure 2), at a self-selected pace (based on laboratory constraints, Baseline subjects did not perform this task). The course is set up on a base of medium-density foam. This task is modeled after the Functional Mobility Test (FMT) used at NASA Johnson Space Center to
assess functional mobility of ISS crewmembers returning from spaceflight (Cohen et al., 2012a;
Mulavara et al., 2010). Our course included identical or analogous obstacles tuned to require
movement primarily in the relevant, sagittal (pitch) plane, which we term the modified FMT
(mFMT).

350

## FIGURE 2 PLACEMENT (modified FMT)

351 The subjects began and ended each trial seated in a chair (left side of Figure 2). Floor 352 obstacles (requiring subjects to 'hurdle/step-over') were 0.5 meters tall, and hanging obstacles 353 (requiring subjects to 'duck') were adjusted to the subject's shoulder height at the start of 354 training. At their discretion, they began each trial by standing up out of the chair and were timed 355 for how long it took to complete the out-and-back course, and sit back down. To encourage 356 subjects to avoid the obstacles, they were told each contact counted as a five second penalty. 357 Pre- and post-tests were streamlined, such that one of the sessions was completed within 358 15-20 minutes: ~1-2 minutes for orientation perception reports, 4-5 minutes for modified 359 Romberg tests including eight trials of condition 4M, 2-3 minutes for Tandem Walk tests with 360 eyes open and then closed, 4-6 minutes for eight trials of the mFMT, with  $\sim$ 1 minute between 361 tasks to refresh instructions (though subjects could request a brief rest, typically only used during 362 the more fatiguing mFMT trials).

363 Subject Pool

The protocol was approved by the University of Colorado Institutional Review Board, and all subjects signed a written informed consent form. Ten subjects were assigned to the WHIP exposure group, one of whom voluntarily dropped out of the study and is not further considered (8M/1F; ages 19-26 years). Eight of nine subjects were exposed to the full 12-hour duration and 368 one subject was exposed for 10 hours. This subject is shown as an orange square in the WHIP 369 panels of the figures below, but did not have noticeably different responses and was pooled with 370 the other WHIP subjects for analysis. We also enrolled and tested 6 Control subjects (6M; ages 371 21-26), all of whom completed the full 12-hour exposure window. All subjects performed at least 372 3 hours of wheelchair driving and completed the post-tests.

373 Subjects were aware of the high-level project goal from the informed consent (i.e., 374 development of a new analog for spaceflight deconditioning), but were left naïve to the general 375 purpose of the protocol and study, potential effects of WHIP-exposure, and the different subject 376 groups (e.g., Control subjects were unaware of the head-restrained WHIP group).

377 Statistical Tests

To analyze the effects on sensorimotor performance of the Exposure group (WHIP, Control, or Baseline) at pre-test and post-test time points (PrePost), we fit a linear mixed model (Equation 1). This model was fit twice, first with the Performance metric as the number of successful trials on Romberg balance condition 4M, and then again with the number of correct tandem walk steps with eyes closed. We acknowledge that these data are not strictly ratio data (i.e., successful balance trials and correct steps can only be integers between zero and eight or ten, respectively).

385 
$$Performance = \beta_0 + \rho_i + Exposure + PrePost + PrePost * Exposure + \varepsilon_{ij}$$
 (1)

The model included an intercept  $(\beta_0)$  and random effects for each subject  $(\rho_i)$ . The Exposure and Pre vs. Post time points were applied as dummy variables. The base condition in which all dummy variables were null was set as the pre-test in the Baseline group. This approach was taken as it causes 1) the Exposure coefficients to represent a difference in pre-test performance for the Baseline group vs. the Control (or Baseline vs. WHIP), 2) the PrePost coefficient to be a difference from pre- to post-test performance in the Baseline group, and 3) the PrePost\*Exposure cross-effects to represent differences in pre vs. post-test performance in Baseline vs. Control (or Baseline vs. WHIP). As will be seen in the Results, the Exposure effects and the PrePost effect were not significant, as expected. However, the PrePost\*Exposure cross-effect was significant for the WHIP group, corresponding to the pre-test vs. post-test performance differing for the WHIP group compared to that for the Baseline group.

To further investigate this cross-effect, we performed paired comparison tests between pretest and post-test performance for the WHIP group. In each comparison, Shapiro-Wilks and Anderson-Darling tests were used to verify the assumption of normality prior to performing paired t-tests. We used one-tailed tests as we *a priori* hypothesized that the WHIP-subjects with headrestrained exposure would have significant sensorimotor decrements as compared to their pre-test baseline performance. All statistical tests were performed using MATLAB (v.2019a) and R/RStudio (v.1.0.153, 2017).

404 **RESULTS** 

Before presenting the results for each task, in summary, WHIP subjects systematically reported illusory orientation perceptions and had substantial functional performance decrements post WHIP-exposure. Control subjects tended to not have sensorimotor decrements, nor reported similar illusory perceptions of motion post-test. Particularly, on the locomotion and balance tasks that involved having eyes closed and/or active head tilts, WHIP subjects showed substantial sensorimotor impairment, as well as perceived increased difficulty in these tasks post-test.

411 Spatial Orientation Perception during Static and Dynamic (Active) Head Tilts

412 As expected, no subjects reported illusory perceptions of motion pre-test, so Table 1 only 413 presents post-test sensations. As subjects tended to report similar sensations during the initial static 414 head tilt as during the subsequent dynamic head tilts, no distinction was made based upon this.

415 7

 TABLE 1 PLACEMENT (Orientation perception)

416 All 9 WHIP subjects experienced illusory perceptions of tilt and/or rotation post-exposure. 417 These illusory perceptions were always sustained, but spanned all three directionalities (Table 2) with some subjects reporting static and others reporting dynamic perceptions (specified in brackets 418 419 in Table 1). In contrast, only 2 of 6 control subjects experienced sensations of tilt and/or translation. 420 These two both only had transient, static perceptions of left-ear-down tilt, which was also 421 commonly reported by WHIP subjects (though WHIP subjects reported this sensation to be 422 sustained). This may be an artifact of the exposure orientation, in which we had subjects always 423 laying and driving on their left sides (see Discussion for elaboration on potential underlying 424 mechanisms). Three of 9 WHIP subjects also experienced sustained translation perception, 425 predominately in the coronal plane (left-right) with one subject not able to articulate a 426 directionality. Only 1 of 6 Control subjects reported any illusory translation, noting a "slight heave, 427 up and down".

428

## TABLE 2 PLACEMENT

In the follow-up question session, some subjects provided colorful analogies to specific past experiences which are detailed elsewhere (Dixon & Clark, 2018). When asked whether the illusory sensations were similar to a "head rush", 7 of 9 of WHIP subjects reported it did not (i.e., that it was something more than just a head rush), one said it did, and the last reported "*I don't know*". In contrast, only 1 of 6 Control subjects reported their sensation did not feel similar to "head rush" noting that it was "*definitely more than that*" without further elaboration. Additionally,

435 all 9 WHIP subjects reported that they perceived performing eyes-closed tasks notably more 436 difficult post-test, particularly recovering from body sway using common phrases such as: "there's 437 kind of a lag", "overcompensated", and "recognized too late". Six of 9 WHIP subjects also 438 explicitly addressed the increased difficulty in performing and maintaining head tilts, calling them 439 "sluggish" and that they "couldn't feel [their] accelerations" with respect to starting and stopping 440 head tilts on the metronome beat, "as if there [was] noise over it". No Control subjects reported 441 perceived differences with respect to difficulty or motor strategy from pre- to post-test. Finally, all 442 subjects reported that illusory perceptions decayed fairly quickly throughout the post-tests, but 6 443 of 9 WHIP subjects reported their noticeable perceptions persisted at least through the modified 444 Romberg test (> 8-10 minutes).

445 FIGURE 3 PLACEMENT (Romberg condition 4M)

#### 446 Functional Balance and Locomotion Tests

447 As previously noted, tasks requiring eyes to be closed and/or those involving head tilts 448 resulted in substantial performance decrements for the WHIP group post-exposure. WHIP subjects 449 decreased from a mean of 7.0/8 successful trials pre-test to 4.6/8 post-test on Romberg condition 450 4M that involved both eyes closed and head tilts while standing on the foam pad (Figure 3). 451 Additionally, a performance decrement was seen on the eyes-closed condition of the Tandem Walk 452 task for WHIP subjects (Figure 4) who made an average of 7.7/10 correct steps pre-test, but only 453 5.9/10 correct steps post-test. These performance decrements were not observed in the Control 454 (head unrestrained) or Baseline (unmonitored activity) groups (Figures 3 and 4 B, C).

To statistically assess these effects, we fit the linear mixed model in Equation 1, first to the number of successfully completed trials in the modified Romberg balance test condition 4M (3). With 9 subjects in the WHIP group, 6 in Control, and 8 in Baseline, each performing pre and posttests (46 observations), and six fixed-effects (shown in Table 3), there remained 40 degrees offreedom in the model.

460

#### TABLE 3 PLACEMENT (Linear model for Romberg 4M)

461 As the null condition for the dummy variables was set to be the Baseline subject's pre-test 462 performance, the value of  $\beta_0$  (7.34) corresponds to the number of successful balance trials out of 463 eight in that condition (i.e., while challenging, subjects were nominally successful in completing 464 the Romberg balance condition 4M trials). The main effects for Exposure were not significant for 465 either Control (p = 0.29) or WHIP (p = 0.70), corresponding to the pre-test performance not 466 differing between groups, as expected. Also as expected, the main effect of PrePost was not 467 significant (p = 0.58) as the Baseline subjects performance did not differ between pre-test and post-468 test. However, the PrePost\*Exposure cross-effect was significant for the WHIP group (coeff = -469 3.07, t(40) = -3.80, p < 0.0005). This corresponds to the pre-test vs. post-test performance differing 470 between the WHIP vs. Baseline groups. As the Baseline group did not have a significant difference 471 between pre and post-tests, the difference in WHIP corresponds to a performance decrement 472 (negative coefficient). To further investigate this, in WHIP subjects we performed a paired t-test 473 between pre-test vs. post-test number of successful balance trials (condition 4M) and found a 474 significant decrement (difference = -2.6 trials of 8, t(8) = -2.98, p = 0.0087). In addition, to 475 investigate the pre- vs. post-test changes in performance between groups, we performed a 476 one-tailed t-test, hypothesizing larger decrements in the WHIP group than the Control group. 477 Indeed, we found the WHIP group successfully completed fewer Romberg 4M balance trials post 478 vs. pre, as compared to the Control group (t-test, t(13) = 2.1, p = 0.03).

We also fit the linear mixed model in Equation 1 with the Performance dependent variableas the number of correct steps in the tandem walk test with eyes closed (Table 4).

#### TABLE 4 PLACEMENT (Linear model for Tandem Gait eyes closed)

482 The model fit to the tandem walk with eyes closed performance reached identical 483 conclusions as that for the modified Romberg 4M data. Neither of the Exposure or PrePost main 484 effects were significant, as expected. The PrePost\*Exposure cross-effect was significant for the 485 WHIP group (p = 0.025). This corresponds to the change in performance from pre to post-test 486 being different in the WHIP group as compared to the Baseline subjects (in which there was not a 487 significant difference between pre and post-tests). To further evaluate this, we performed a paired 488 t-test on the WHIP subjects' pre vs. post-test performance. We found the number of corrects steps 489 in tandem walk with eyes closed to significantly decrease (difference = -1.8 steps out of 10, t(8) = 490 -2.10, p = 0.034).

491 In contrast with WHIP subjects, Control subjects did not have comparable performance 492 decrements, in either the Modified Romberg Standing Balance test condition 4M (Figure 3B) or 493 the Tandem Walk test with eyes closed (Figure 4B). We also hypothesized the pre- vs. post-test 494 decrement in performance to be greater in the WHIP group than the Control group for the tandem 495 walk with eyes closed. However, this did not reach statistical significance (t-test, t(13) = 0.9, p =496 0.19). Thus, while the WHIP group had a significant decrement and the Control group did not, the 497 difference in the two groups' decrements was not significantly different. Similarly the Baseline 498 subjects who did not have any exposure, but instead just unmonitored daily activities between pre-499 and post-test, did not tend to have any change in performance (Figures 3B and 4B).

500

#### FIGURE 4 PLACEMENT (Tandem Walk)

501 During tasks where subjects had their eyes open or were not making dynamic head tilts, 502 however, there was no evidence of performance decrements following WHIP as compared to the 503 pre-test baselines. All subjects in all conditions completed conditions 1 through 4 on the Modified 504 Romberg Standing Balance test (thus pre- vs. post-: p>0.05). Similarly, all subjects scored 505 perfectly on the eyes open condition of the Tandem Walk task both pre- and post-test, except for 506 six subjects (3 WHIP, 2 Control and 1 Baseline) that scored 9/10 correct steps on either pre- or 507 post-test (p>0.05). The average time to complete the mFMT across eight repetitions was not 508 significantly different for pre- vs. post-test, for WHIP subjects (pre-test mean  $\pm$  SD: 11.3 $\pm$ 4.0 509 seconds, post-test:  $11.1\pm3.0$ , p>0.05) and Controls (pre-test:  $10.6\pm2.3$ , post-test:  $11.9\pm4.8$ , 510 p>0.05). These conclusions were the same if time penalties for contacting obstacles mentioned in 511 the instructions were integrated into the scores. We also explored pre- vs. post- differences only 512 considering the first mFMT trial or the first four trials (hypothesizing a decrement might decay in 513 later trials), but did not find any significant differences. Figure 5 shows the results of the mFMT 514 for the WHIP and Control subjects, not including time penalties to be consistent with previous 515 published FMT data (Cohen et al., 2012a; Mulavara et al., 2010)

516 FIGURE 5 PLACEMENT (modified Functional Mobility Test)

517 Finally, we note one interesting observation; one WHIP subject reported feeling motion 518 sickness part way through post-tests (during mFMT trials, the final performance test). This 519 included moderate nausea (no vomiting) and after a brief break (~1 minute) did not prevent the 520 subject from completing the remaining mFMT trials. Motion sickness symptoms subsided shortly 521 following the post-tests (~30 minutes after the end of WHIP exposure). No other subjects, WHIP, 522 Control, or Baseline, reported motion sickness during exposure, while performing post-tests, or in 523 debrief, though it was not explicitly questioned.

524 **DISCUSSION** 

Here we propose a novel ground-based analog aimed at replicating the neurovestibular cues
experienced by astronauts in microgravity. We demonstrated its feasibility for up to 12 hours (9/10

527 subjects completed the head-restrained testing, 8 for the full 12 hours, 1 for 10 hours). As our 528 primary finding, this duration of WHIP exposure (head-restrained exposure) led to systematically 529 altered orientation perception and significant decrements in sensorimotor functional tasks that are 530 most sensitive to vestibular function (e.g., eyes closed and/or making head tilts).

531 While sensorimotor decrements were significant across the WHIP group for both Romberg 532 4M and Tandem Gait with eyes closed tasks, it is worth noting some subjects did not appear to 533 have much or any change in performance. However, all 9 subjects had substantial impairment in 534 at least one of these two tasks (Figure 3A & 4A): The WHIP subject (blue triangle) that had slightly 535 improved performance pre- to post-test from 3/8 to 4/8 successful Romberg 4M trials decreased 536 from 8/10 to 5/10 correct steps in Tandem Walk with eyes closed. Similarly, the two subjects with 537 slightly better performance post-WHIP (blue circle and orange square) and the one that was 538 unaffected (green diamond) on Tandem Walk with eves closed, all had decrements in Romberg 539 4M post-WHIP (decreases of 4, 3, and 1 of 8 correct steps, respectively). Thus while there was 540 substantial inter-individual variability (as might be expected), all 9 WHIP subjects demonstrated 541 sensorimotor impairment on at least one of our two most sensitive functional tests.

542 These effects appear to be specifically due to the altered neurovestibular cues experienced 543 in WHIP, as they were not observed in the Control condition, which replicated aspects of the 544 exposure other than the head-restraint, or the Baseline condition in which there was unmonitored 545 activity. This is highlighted by the linear mixed model results in Equation 1 and Tables 3 and 4. 546 In each case there was not a significant main effect of Exposure, indicating WHIP, Control, and 547 Baseline subjects all had similar performance pre-test, as expected. Further, there was a not a 548 significant main effect of PrePost, which corresponds to no difference pre to post-test in the 549 Baseline subjects, again as expected. Finally, there was not a significant cross-effect of PrePost\*Exposure: Control, indicating the difference pre vs. post-test in Control subjects was similar to the insignificant effect of the Baseline subjects. It is briefly worth mentioning that while not significant, there were slight trends of performance decrements in the Control subjects (<1 fewer successful balance trial (Table 3); ~1 fewer correct tandem walk steps (Table 4)). Additional control conditions with alternative WHIP-exposures will likely help differentiate the specific effects of altered neurovestibular cues (WHIP subjects) versus sustained recumbent posture with unnatural motion (Control subjects), in the context of sensorimotor performance.

## 557

#### Comparison to post-spaceflight perceptual reports

558 In a recent study (Reschke & Clément, 2018a), 10 of 13 Space Shuttle crewmembers 559 reported that head movements made during reentry and immediately after return resulted in 560 increased sensations of self-motion as well as a lag in motion perception after the movement 561 stopped. This mirrors the verbal reports from WHIP subjects, all of whom reported illusory 562 sensations of rotation/tilt, with specific descriptions of "there's kind of a lag", "recognized too 563 late", and head tilts feeling "sluggish". During passive, whole-body tilts in the dark, post-564 spaceflight astronauts overestimate the amount of tilt (Clément, 1998; Clément & Wood, 2013, 565 2014) and often feel an illusory sensation of translation (Clément & Wood, 2014; Parker et al., 566 1985; Reschke & Parker, 1987; Young et al., 1984). Following WHIP, pitch head tilts might be 567 expected to yield an overestimation of pitch (ROTTR hypothesis) or translation in the sagittal 568 plane (OTTR and ROTTR hypotheses). While some WHIP subjects did experience illusory fore-569 aft translation and/or pitch tilt (Table 2), this was not pervasive. Instead, an illusory roll tilt or 570 coronal (y-axis) translation sensation were more common reports post-WHIP. Among other 571 explanations (see Limitations section for potential mechanisms), we note the methodological 572 difference of active, head tilts vs. passive, whole-body tilts (Carriot et al., 2013). Nonetheless,

573 WHIP subjects systematically reported sustained illusory orientation perceptions that either did 574 not occur or were not sustained for our Control subjects, suggesting WHIP head-restrained motion 575 drives a relevant central reinterpretation of neurovestibular stimuli.

576 In the same recent study (Reschke & Clément, 2018a), 11 of 14 crewmembers also reported 577 difficulties standing or walking immediately after Shuttle wheel-stop. Subjective reports from our 578 WHIP subjects were similar to these provided by returning astronauts. In particular our WHIP 579 subjects tended to notice or perceive effects of the illusory sensations primarily in the presence of 580 multisensory deprivation (e.g., eyes closed, standing on foam pad).

# 581 *Comparison to post-spaceflight functional performance*

582 Wood et al. (2015, 2011) assessed balance performance in crewmembers returning from 583 the International Space Station (ISS) using the SOT, finding the added condition 5M (eyes closed, 584 unstable support, dynamic pitch head tilts  $\pm 20^{\circ}$  at 0.33 Hz) was the most sensitive. Pre-flight, 585 condition 5M was challenging, but feasible, resulting in an average 'continuous Equilibrium 586 Score' (cEQ) of 62.3 (Wood et al., 2015), on a 0 to 100 scale (100 being perfect balance with no 587 sway). However, post-spaceflight, the task was essentially infeasible, either not being attempted 588 or leading to a fall, corresponding to a score of zero. Another study performing the identical task 589 (Mulavara et al., 2018), also with crewmembers from long-duration ISS flights, showed the cEQ 590 significantly decreased from a median of approximately 75 to 45. Additionally, SOT data collected 591 from short-duration returning Shuttle crewmembers and matched controls (Jain et al., 2010; 592 Ozdemir et al., 2018), showed astronauts post-spaceflight had 20/22 falls during condition 5M 593 while controls only had 2/22 falls. Similarly, condition 4M of the modified Romberg test which is 594 analogous to condition 5M of the SOT – but using a foam pad rather than sway referenced platform 595 – was the most sensitive functional performance metric collected in WHIP subjects, with the
596 proportion of completed trials decreasing by an average of 34%.

597 To date, results from the post-spaceflight Field Test including the Tandem Walk task have 598 not been formally published. In a presentation given at the 2016 NASA HRP Investigator's 599 Workshop (Rosenberg et al., 2016), however, preliminary results from 18 crewmembers showed 600 significantly worse performance on the Tandem Walk task (eyes closed) for at least 24 hours after 601 flight (subsequent HRP presentations reached similar conclusions (Reschke et al., 2017a, 2017b, 602 2019; Rosenberg et al., 2018)). In fact, the Tandem Walk was the most challenging of 12 tasks 603 assessed in the Field Test (computerized dynamic posturography for the SOT is not feasible in the 604 field). One day after returning from the ISS, the median percent correct steps was significantly 605 reduced to 45% from 75% pre-flight (Mulavara et al., 2018). In the identical test, WHIP subjects 606 show a similar tendency of having significantly worse performance post-test (based on mean 607 proportion of correct steps reducing from 7.7/10 to 5.9/10). This was further supported through 608 our informal review of the video recordings (i.e., decreased ground contact stability, increased 609 number of falls leading to missteps, time to correct after misstep). Future tests will aim to quantify 610 these additional metrics by incorporating an IMU system to measure body sway, and pressure plate 611 insoles to measure mediolateral center of pressure.

Returning astronauts often experience motion sickness ("Earth sickness"), presumably due to the unexpected graviceptor cues after having adapted to the microgravity environment (Lackner & DiZio, 2006; Paloski et al., 2008). It is worth noting that one of our WHIP subjects reported motion sickness during post-tests (this was 1 of the 8 WHIP subjects that completed the full 12 hours of exposure). This could have been due to extraneous causes, such as feeling light headed from returning to an upright posture after being lateral-recumbent during exposure or the subject

618 choosing to not eat as much during exposure. However, we speculate the motion sickness was due 619 to WHIP-induced neurovestibular reinterpretations, since: i) the WHIP subject reported motion 620 sickness between performing mFMT trials (the most active task) after having completed head tilts, 621 the modified Romberg balance task, and the heel-to-toe walking task, and; ii) no Control subjects 622 reported motion sickness. This one WHIP subject may have been particularly susceptible to 623 neurovestibular reinterpretations within the 12 hour time period, to motion sickness when exposed 624 to unexpected sensory cues, or simply more willing to offer unsolicited comments during testing. 625 As we did not initially anticipate motion sickness to occur following only 12 hours of WHIP 626 exposure (based upon pilot testing), we did not specifically ask subjects to report symptoms. 627 Longer duration exposures should include measures of motion sickness.

#### 628

# Eyes-open tasks and readaptation during post-tests

629 WHIP subjects had no significant or observable differences pre- to post-test in task 630 conditions that allowed eyes to be open (modified Romberg balance conditions 1 and 3, Tandem 631 Walk with eyes open, and the mFMT). Visual cues provide a strong orientation reference to 632 estimate vertical (Karmali et al., 2014) and can dominate over vestibular influence. One 633 interpretation is that tasks which did not isolate vestibular cues were less sensitive to capturing 634 post-WHIP decrements as visual and other cues could still be used effectively. This is subjectively 635 supported by the fact that some WHIP subjects reported their illusory sensations were still present 636 during eyes-open tasks, but that they were not "noticeably distracting".

We also found time to complete the mFMT post-WHIP was not significantly different from
baseline values (11.3 seconds pre-WHIP vs. 11.1 post-WHIP). Following long duration spaceflight
(average of 185 days on the ISS), a substantial increase in time to complete the traditional FMT
was observed (Mulavara et al., 2010). The lack of a performance decrement following WHIP on

641 our mFMT could be attributed to a number of factors: it was an eyes-open task following a 642 relatively short exposure duration (12 hours vs. 185 days), readaptation may be occurring during 643 the post-tests prior to performing mFMT, since head movements tend to drive readaptation to a 644 gravity environment (Reschke & Clément, 2018a), and subjects often adopted a strategy where the 645 head was maintained level, which may make the mFMT less sensitive to quantifying post-WHIP 646 performance decrements. Future work should aim to assess the impact of WHIP on an alternate 647 complex, functional task that may be more sensitive. We suggest a task that includes required pitch 648 head tilts (e.g, bending over or reaching up high to grab a small item that cannot be accomplished 649 while keeping the head level) and/or limited visual cues to emphasize dependence upon vestibular 650 alterations (e.g., a reduced field of view similar to a space suit helmet or reduced/altered lighting 651 like the challenging lighting conditions on the moon (Oravetz et al., 2009)). Finally, this task might 652 be performed first, immediately post-WHIP to minimize the influence of readaptation, but at the 653 risk of impacting the sensitivity of other functional performance metrics.

#### 654

#### Sensorimotor Analogs of Spaceflight

655 As a primary objective, we aimed to assess WHIP as an analog for spaceflight-induced 656 neurovestibular adaptations. However, other analogs have been proposed and used to investigate 657 sensorimotor changes, such as head down tilt bed rest (Koppelmans et al., 2013; Lee et al., 2019; 658 Mulavara et al., 2018). Bed rest prevents subjects from performing balance and locomotion tasks 659 otherwise experienced in Earth-bound ambulatory life, which mimics the reduction in these 660 activities experienced by astronauts on orbit (though treadmill and exercise with elastic resistance 661 allow for some activity). Extended bed rest (weeks to months) also induces muscle weakening 662 (Akima et al., 2005) and elevated heart rates to maintain blood pressure (Mulavara et al., 2018), 663 which may at least partially contribute to performance decrements in balance and locomotion tasks

664 following long duration (70 day) bed rest (Mulavara et al., 2018). However, in bedrest paradigms 665 subjects' heads are unrestrained such that the vestibular sensory stimulation patterns are generally 666 unaltered compared to normal ambulatory life. The consistent supine orientation and lack of 667 ambulation obviously differs from typical experiences, which may lead to the neuroplasticity 668 observed in previous studies (Yuan et al., 2018), but the coupling of graviceptor (otolith) and 669 rotational (semicircular canal) cues is maintained during bed rest, such as when rolling to one's 670 side or pitching the head up. With the unaltered vestibular stimulation, shorter duration bed rest (5 671 days) does not induce balance and locomotion decrements, including in a task with head tilts, eyes 672 closed, on a foam pad (Clément et al., 2015). Yet Shuttle flights of comparable microgravity 673 exposure duration (11-13 days) do significantly impair balance, particularly when head tilts are 674 performed (Jain et al., 2010; Ozdemir et al., 2018; Paloski et al., 2006). Taken together these results 675 suggest the sensorimotor functional impairments observed after long-duration bed rest are 676 impacted by motor disuse and atrophy, rather than neurovestibular adaptations which occur over 677 the shorter timescale in microgravity degrading post-spaceflight sensorimotor performance.

678 As an alternative, WHIP specifically aims to partially replicate the vestibular sensory cues 679 experienced in microgravity and capture the neurovestibular-induced functional impairment. 680 While 12-hours of WHIP exposure and 70-days of bed rest both impair balance and locomotion 681 function analogous to post-spaceflight, WHIP more meaningfully replicates the neurovestibular 682 contribution to sensorimotor impairment. To our knowledge, illusory perceptions of self-motion 683 are not reported post-bed rest, such as those reported by all 9 of our WHIP subjects. We note that 684 the lateral recumbent posture of WHIP also replicates the motor disuse of bed rest (if not the 685 precise 6° head down configuration for fluid shifts). If it were feasible to sustain for long enough durations (e.g., weeks to months), extended exposure to WHIP could serve as a comprehensiveanalog for spaceflight neurovestibular/sensorimotor alterations.

688 While WHIP was initially conceived as a potential ground-based analog for spaceflight-689 induced sensorimotor impairment, it may have other uses from a basic science and clinical 690 perspective. While other paradigms (e.g., prism reversing glasses (Welch, 1974), altered gravity 691 on a centrifuge (Galvan-Garza et al., 2018), galvanic vestibular stimulation (Dilda et al., 2014)) 692 may be used to explore how the brain reinterprets sensory information when exposed to a novel 693 environment, WHIP allows us to explore changes when reinforcing sensory information (i.e., 694 coupling of otolith and canal cues during head tilts) is systematically removed. Specifically, WHIP 695 may be used to investigate how internal models for orientation perception degrade without sensory 696 reinforcement and how that impacts sensorimotor performance, such as has been explored in motor 697 learning (Cohen et al., 2004) for alterations to the vestibulo-ocular reflex gain once reinforcement 698 has been removed. Further, by studying the degradation of internal models, it may be possible to 699 better understand how internal models are developed, maintained, and optimized. In addition to 700 the basic science implications, this may be important for clinical populations where acute damage 701 (e.g., unilateral dysfunction) or gradual changes (e.g., hair cell loss with aging (Karmali et al., 702 2018)) require maintenance of internal models for orientation perception.

703 *Limitations and Future Work* 

As an analog for replicating the neurovestibular stimulation patterns of spaceflight, WHIP has some limitations. First, WHIP does not remove gravity; it simply fixes the direction of gravity out of the pitch/sagittal plane. (Of course, microgravity on orbit also does not "remove" gravity either, but effectively counters it by continual free fall around the Earth.) If the CNS processes sensory cues holistically, it may continue to track the direction of gravity during WHIP, despite it being fixed in the y-axis (inter-aural). Nonetheless, this paradigm prevents normal, coupled rotation and tilt stimulation and removes the typical tonic loading of gravity in the z-axis (rostrocaudal) for an extended period of time, similar to microgravity exposure.

712 As the altered stimulation patterns were in the pitch plane, we anticipated altered responses 713 primarily within this plane. Unexpectedly, several WHIP subjects reported illusory perceptions in 714 roll tilt and/or y-axis translation. One explanation is that the precisely 1G sustained stimulation in 715 the +y-axis when laying on their left side led to an unexpected sensory response as the fixed GIA 716 was removed when sitting upright post-WHIP. This aspect of reinterpretation is not relevant for 717 microgravity where there is no fixed GIA stimulation, but may contribute to post-WHIP functional 718 impairment as subjects could fall/misstep in any direction. A potential control condition is to 719 configure WHIP subjects with right side down, instead of on their left. If the fixed GIA stimulation 720 from gravity was critical, one might hypothesize the direction of illusory y-axis motion and 721 falls/missteps post-WHIP would differ between groups with right versus left-side down.

722 Second, while the inertial orientation cues mimicked those in microgravity, other 723 orientation cues were largely unchanged during WHIP. For example, visual verticality cues 724 (doorways and the ceiling and floor in our testing room) still aligned with gravitational vertical. 725 Similarly, while the memory foam mattress comfortably distributed tactile cues, the subject's 726 weight was still felt on their left side in the gravitational direction. As WHIP was proposed as a 727 neurovestibular-specific analog, these non-vestibular cues failing to mimic microgravity may be 728 acceptable. However, if desired, future work could aim to provide altered visual cues using virtual 729 reality (VR). A VR headset worn throughout WHIP exposure could provide visual motion cues 730 without vertical indicators, for example consisting of a dot pattern that provides visual flow of 731 angular rotation and linear translation. To mimic microgravity space stations, where visual vertical r32 cues may exist, but are not consistent (e.g. working with a piece of hardware on the "ceiling"), the r33 VR environment could have virtual tunnels (no verticality cues) that connect to virtual rooms with r34 specific, but differing verticality cues. We hypothesize combining WHIP with VR-altered visual r35 orientation cues would accelerate the adaptation process by reinforcing the ambiguity of vestibular r36 information.

737 Third, in our initial WHIP assessment, angular rotation and linear translation were actuated 738 actively (Figure 1), which we hoped would more effectively induce neurovestibular 739 reinterpretations (Carriot et al., 2015; Welch et al., 1998), even if produced indirectly using a 740 joystick. While it may not be feasible to enable natural active control (e.g., walking) with WHIP 741 head-restraint, future work could explore the criticality of joystick active control. We envision 742 control groups with either i) no motion at all (wheelchair turned off) or ii) passive control 743 (wheelchair drives itself without the subject using the joystick). We note simply actively driving 744 the wheelchair with the joystick head-unrestrained is unlikely to account for the post-WHIP 745 sensorimotor decrements, as Control subjects had this experience but were not impaired.

746 Further, the wheelchair-produced translation and rotation were likely different in character 747 than those typically experienced in spaceflight. The precise magnitudes, frequencies, and 748 characteristics of astronaut motions likely depend upon the activity being performed (e.g., EVA 749 vs. floating down a hallway vs. pushing off a wall). However, our prototype WHIP device was 750 likely unable to produce large enough stimuli. For example, quickly shaking one's head "no" 751 reaches peak angular velocities of at least 360 °/s (Grossman et al., 1988), while the wheelchair 752 peaked at ~100 °/s. Similarly, pushing off a wall could briefly yield >1G of acceleration, but the 753 wheelchair was more limited. The frequency content of motions also likely differed. Finally, very 754 slight head tilts ( $<3^{\circ}$ ) were feasible within the custom-modeled facemask. Nonetheless, the

wheelchair reproduced decoupled translations and rotations, without substantial head tilts, similarto microgravity.

757 Finally, WHIP exposure was limited to 12 hours in our initial validation effort. This 758 duration was selected as a compromise between what we anticipated would be tolerable for most 759 subjects (based upon pilot tests) versus being long enough to expect quantifiable sensorimotor 760 changes post-WHIP (loosely based upon most astronauts "adapting" to microgravity within 0-3 761 days (Shelhamer, 2015)). While early spaceflight missions were fairly short (e.g., Mercury: 15 762 minutes, hours, and then a day+), in the last 40 years most missions have been approximately 1-2 763 weeks (Shuttle, now termed "short duration") or 3-6 months (ISS, termed "long duration") and 764 future missions may be even longer (Mars: 1-2 years). Yet, neurovestibular reinterpretations 765 appear to occur in response to gravity *transitions*, not necessarily extended exposure within an 766 altered gravity environment. Thus WHIP may be leveraged to better understand the underlying 767 mechanisms and temporal dynamics of central reinterpretation occurring in astronauts during 768 gravity transitions, even if longer durations may cause altered internal models to be more engrained 769 and lead to motor/balance disuse and musculoskeletal deconditioning.

770 Based upon our first-hand experience, WHIP exposure could likely be extended for more 771 than 12 hours. First, of the 10 subjects that enrolled in the WHIP group, eight completed all 12 772 hours, one went for 10 hours, and one asked to stop after approximately 5 hours. While most 773 subjects eventually noted slight discomfort from the facemask, none reported high levels of pain. 774 A more supportive, structural custom facemask design could alleviate discomfort (with an added 775 benefit of further limiting the magnitude of out-of-plane head tilts possible within the mask). 776 Second, biological activities required beyond 12 hours are feasible within WHIP, including sleep 777 (subjects often took brief naps during the 12 hours), eating/drinking (with a straw), and urination

(ONEDONE unisex bottle system). In a hospital setting, WHIP exposure on the order of several days could be feasible, but it is unlikely to be tolerable for weeks or months. However, as noted above, neurovestibular reinterpretations may be completed within a few days. If post-WHIP decrements stabilize after a few days of exposure, it would be unnecessary to extend beyond this as further decrements would likely be associated with motor/balance disuse and muscle atrophy.

783 Each of these limitations would be expected to reduce the efficacy of WHIP to induce 784 neurovestibular reinterpretations. Yet, post-WHIP we found systematically altered orientation 785 perception and significant decrements in sensorimotor tasks, not observed for Control or Baseline 786 subjects. This suggests the impact of these limitations was sufficiently small, although we note the 787 persistence of impairment post-WHIP was relatively brief (subjects typically reported feeling 788 normal within 30 minutes) as compared to that observed post-spaceflight. This may have been a 789 result of WHIP-induced central reinterpretations not being fully engrained due to a combination 790 of the limitations listed above. We suggest the effects of WHIP not be quantitatively compared to 791 those in astronauts post-spaceflight, even if the duration is matched (e.g., 4 days of WHIP 792 compared to a 4 day Shuttle mission). Instead, WHIP might be seen as an analog that partially 793 replicates the neurovestibular stimulation patterns of microgravity, inducing *qualitatively* similar 794 sensorimotor impairment.

The most exciting area of future work is utilizing WHIP as an analog to investigate questions of scientific and operational interest that may be difficult in a spaceflight study. For example, WHIP could be used to assess impairment *immediately* post-exposure to better quantify readaptation and/or in response to varied exposure durations. The ability to assess effects immediately post-WHIP in a laboratory environment enables carefully controlled experiments using sophisticated equipment (in contrast to the Field Test where tasks are limited by the 801 environment). For example, fundamental scientific questions like testing the ROTTR and OTTR
802 hypotheses could be done using passive, whole-body motions on a computer-controlled motion
803 device.

804 Experiments with WHIP exposure are difficult, but not nearly to the extent of spaceflight 805 experiments. Thus WHIP could be used to investigate topics that require a large number of 806 subjects, such as better quantifying, understanding, and predicting individual differences in 807 neurovestibular adaptation. WHIP could also be used as a first step for countermeasure 808 development. There are currently too few NASA astronauts flying (a few per year) to quickly 809 assess and iterate countermeasure approaches as it will take years to produce a single group sample 810 of sufficient statistical power (during which many confounding factors may be varied). Instead 811 WHIP could be used, as head down tilt bed rest is for the musculoskeletal system, to quickly assess 812 the efficacy of neurovestibular-specific countermeasures, and varying aspects such as intensity, 813 personalization, etc. to optimize approaches. The most promising countermeasure prescriptions 814 identified during WHIP testing could then move forward to full validation during operational 815 spaceflight studies.

## 816 CONCLUSION

We propose a novel neurovestibular analog for spaceflight, termed the wheelchair head immobilization paradigm (WHIP), which aims to replicate the spatial orientation sensory cues experienced by astronauts in microgravity. Specifically, coupled head tilt stimulation is eliminated using a facemask, while decoupled linear translation and angular velocity are actuated via a joystick-controlled motorized wheelchair. A prototype WHIP device was constructed and tested in nine subjects (plus six head-unrestrained Controls) for up to 12 hours and found to be tolerable. Using similar or identical tasks as assessed with astronauts post-spaceflight, post-WHIP we found 824 systematically altered orientation perception when making head tilts and significant decrements in 825 balance and locomotion performance not observed in control groups. Future work should aim to 826 use WHIP to address scientific and operational topics not easily investigated with a spaceflight 827 study.

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## 1046 TABLES AND FIGURES

Table 1. Post-test illusory tilt/rotation and translation perception counts, sustainment, and directionalities based on subjective reports during static and dynamic head tilts (task #1) for WHIP vs. control subjects. Values in shaded sections include counts only from subjects that responded 'Yes' to experiencing 'Any Illusory Sensation(s)'. Subjects' illusory sensations could be categorized into more than one *Directionality*, but it is only possible to have one *Distinction* per colored section, per subject. If *Distinction* was unable to be extracted from verbal reports it was considered as 'No clear direction'. Values outside of brackets indicate a static rotation/tilt angle 1054 perception, while values inside of brackets indicate a perception of constant spin. Oscillatory 1055 sensations are inherently perceptions of constant spin, but that change direction.

	Tilt and Rotation				Translation			
Characterization	Distinction		WHIP	Control	Distinction		WHIP	Control
Any Illusory	Yes		9/9	2/6	Yes		3/9	1/6
Sensation(s)	No		0/9	4/6	No		6/9	5/6
Sustained	Yes		9	0	Yes		3	1
Sensation(s)	No		0	2	No		0	0
	Coronal / Roll Tilt [constant spin]	Clockwise (RED)	1 [1]	0	Coronal	Stationary (Left)	[1]	0
		Counterclockwise (LED)	4	2		Stationary (Right)	[1]	0
		Oscillatory	[2]	0		Oscillatory	0	0
	Sagittal / Pitch Tilt	Stationary (Fore)	0	0	Saggital	Stationary (Fore)	0	0
Directionality		Stationary (Aft)	0	0		Stationary (Aft)	0	0
		Oscillatory	[1]	0		Oscillatory	0	0
	Transverse / Yaw RotationCloc Cour Cour [constant spin]Osci	Clockwise (Left)	[2]	0	Transverse	Stationary (Up)	0	0
		Counterclockwise (Right)	[1]	0		Stationary (Down)	0	0
		Oscillatory	0	0		Oscillatory	0	[1]
	No	clear direction	0	0	No cl	ear direction	1	0

1056



Control

Baseline



1057





Figure 1. WHIP paradigm and device. We define a standard, right-handed, head-fixed coordinate 1060 1061 system denoted in *purple* (x+ out nose, y+ out left ear, z+ out top of head). Otolith (sf, red) and 1062 semicircular canal stimuli ( $\omega$ , *blue*) are shown for: translation/acceleration (*a*, *green*) in the 1063 leftmost column (panels A, C and E) and rotation/tilt ( $\omega$ , blue) in the middle column (panels B, D 1064 and F) compared across 1G (panels A and B), 0G (panels C and D), and WHIP (panels E and F) 1065 environments. Gravity (g, yellow) present in 1G and WHIP environments is shown to elicit coupled 1066 otolith stimulation during pitch head rotations in 1G (panel B) while the same motion in WHIP 1067 does not elicit otolith stimulation (panel F). The right column and picture (panels G, H and I) 1068 shows WHIP with a subject lying on their side (lateral recumbent) with head support and the wheelchair device. The selection was arbitrary to fix gravity in the +y-axis with left-side down 1069 1070 (panels G, H and I) to enable decoupled stimulation in the pitch plane (e.g., the subject could be 1071 supine, gravity fixed in the -x-axis, isolating the roll plane). However, the selection of pitch plane 1072 enabled the subject to navigate the wheelchair while looking out in the direction of travel. The first 1073 manufactured iteration of the WHIP device is shown on the right (panel I).





1076 Figure 2. Modified Functional Mobility Test (mFMT) spatial layout. (A) Top-down view; (B)

1077 isometric view. Dotted *red* arrows indicate course path for each trial that starts and ends seated in

1078 the chair with each obstacle being encountered twice. *Blue* obstacles are required to be ducked

1079 under, and *orange* obstacles are required to by hurdled/stepped over.





Figure 3. Proportion of successfully completed trials out of 8 for Condition '4M' of the Modified
Romberg Standing Balance Test for WHIP-subjects (panel A), Control-subjects (panel B) and
Baseline-subjects (panel C). *Blue* error bars represent 95% confidence intervals of the mean.
Data are slightly shifted horizontally to minimize overlap of symbols. Statistically significant
differences were found for the WHIP group.

1087

1088 Table 2. Linear Mixed Model (Equation 1) for Modified Romberg Balance Test Condition 4M.

Fixed Effect Parameters	Estimate	Standard Error	t Statistic	p-value
$\beta_0$	7.34	0.49		
Exposure: Control	0.63	0.59	1.07	0.29
Exposure: WHIP	0.29	0.74	0.39	0.70
PrePost	-0.38	0.67	-0.56	0.58
PrePost*Exposure: Control	-0.96	0.90	-1.07	0.29
PrePost*Exposure: WHIP	-3.07	0.81	-3.80	<0.0005

1089

1090 Table 3. Linear Mixed Model (Equation 1) for Tandem Walk with Eyes Closed.

Fixed Effect Parameters	Estimate	Standard Error	t Statistic	p-value
$\beta_0$	8.25	0.62		
Exposure: Control	0.50	0.71	0.70	0.49
Exposure: WHIP	-0.25	0.94	-0.27	0.79
PrePost	-0.58	0.85	-0.69	0.49

PrePost*Exposure: Control	-1.17	1.09	-1.07	0.29
PrePost*Exposure: WHIP	-2.28	0.98	-2.33	0.025

1092



1093 Figure 4. Number of correct steps out of ten for the Eyes-Closed condition of the Tandem Walk

1094 task for WHIP-subjects (panel Å), Control-subjects (panel B) and Baseline-subjects (panel C).

1095 Blue error bars represent 95% confidence intervals of the mean. Data are slightly shifted

1096 horizontally to minimize overlap of symbols. Statistically significant differences were found for

1097 the WHIP group.



1099 Figure 5. Mean trial times on the modified Functional Mobility Test for WHIP-subjects (panel

A) and Control-subjects (panel B). Blue error bars represent 95% confidence intervals of the

1101 mean. Data are slightly shifted horizontally to minimize overlap of symbols. No significant

1102 differences were found.