

1 Quantitative assessment of head movement dynamics in
2 dystonia using visual perceptive deep learning: a multi-centre
3 retrospective longitudinal cohort study

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6
7 **Abstract**

8 **Background** Dystonia is a neurological movement disorder characterised by abnormal in-
9 voluntary movements and postures, particularly affecting the head and neck. However, current
10 clinical assessment methods for dystonia rely on simplified rating scales which lack the ability to
11 capture the intricate spatiotemporal features of dystonic phenomena, hindering clinical manage-
12 ment and limiting understanding of the underlying neurobiology. To address this, we developed
13 a visual perceptive deep learning framework that utilizes standard clinical videos to comprehen-
14 sively evaluate and quantify disease states and the impact of therapeutic interventions, specifically
15 deep brain stimulation. This framework overcomes the limitations of traditional rating scales and
16 offers an efficient and accurate method that is rater-independent for evaluating and monitoring
17 dystonia patients.

18 **NOTE: This preprint reports new research that has not been certified by peer review and should not be used to guide clinical practice.**

19 **Methods** To evaluate the framework, we leveraged semi-standardized clinical video data
20 collected in three retrospective, longitudinal cohort studies across seven academic centres in Ger-
21 many. We extracted static head angle excursions for clinical validation and derived kinematic
22 variables reflecting naturalistic head dynamics to predict dystonia severity, subtype, and neuro-
23 modulation effects. The framework was validated in a fully independent cohort of generalised
24 dystonia patients.

25
26 **Findings** Computer vision-derived measurements of head angle excursions showed a strong
27 correlation with clinically assigned scores, outperforming previous approaches employing spe-
28 cialised camera equipment. Across comparisons, we discovered a consistent set of kinematic fea-
29 tures derived from full video assessments, which encoded information relevant to disease severity,
30 subtype, and effects of neural circuit intervention more strongly and independently of static head
31 angle deviations predominantly used for scoring.

32
33 **Interpretation** The proposed visual perceptive machine learning framework reveals kine-
34 matic pathosignatures of dystonia which may be utilized to augment clinical management, facil-
35 itate scientific translation and inform personalised and precision approaches in Neurology.
36

37 Research in context

38 **Evidence before this study** Clinical assessment of dystonia, a neurological movement disorder,
39 has traditionally relied on rating scales that aim to simplify complex phenomenology into lower-
40 dimensional rating items. However, these score-based assessments have significant clinimetric limita-
41 tions and do not fully capture the rich spatiotemporal dynamics of dystonic phenomena, which are
42 crucial for clinical judgment and pathophysiological understanding. In contrast, recent investigations
43 in animal models of dystonia have already demonstrated the utility and relevance of quantitative
44 methods for phenotyping, which gradually supersedes previous observer-dependent behavioural anal-
45 yses. Taken together, this has led to a need for more objective and detailed clinical evaluation methods
46 of dystonia.

47 We performed a PubMed search up to July 2023 combining the terms "dystonia" AND ("deep
48 learning" OR "machine learning" or "computer vision" OR "vision-based" OR "video-based") AND
49 ("angle" OR "kinematic" OR "rating" OR "scoring" OR "movement analysis") including abstracts
50 in English or German. The search yielded three studies that validated vision-based frameworks for
51 automating the assessment of cervical dystonia severity compared to clinician-annotated ratings. Two
52 of these studies focused on deriving head angle deviations from specialised camera setups, while the
53 third study utilised computer vision in a retrospective video dataset recorded using conventional
54 equipment. These studies reported fair to moderately strong correlations between vision-based head
55 angle measurements and clinical scores. Additionally, two studies investigated computer vision for
56 assessing head tremor in the context of cervical dystonia: one single case report demonstrated the
57 clinical validity of computer vision-derived head angle and head tremor metrics, while a retrospective
58 cross-sectional study reported moderately strong clinical agreement of computer vision-derived head
59 oscillation metrics across different dystonia subgroups. Two additional studies used computer vision-
60 based kinematics to quantify dystonia-like phenomena in rodent models of monogenetic dystonia,
61 demonstrating utility in both phenotype and genotype predictions.

62 However, most of the clinical studies were limited to static task conditions, where patients at-
63 tempted to hold a neutral position of the head, thus not providing a naturalistic account of dysto-
64 nia. Moreover, beyond head angular deviations and oscillation metrics, no study explored a broader
65 kinematic feature space that reflects the true spatiotemporal complexity of dystonic movements. Ad-
66 ditionally, the studies assessed patients at single time points without considering different therapy
67 conditions, particularly the effects of deep brain stimulation, which is a highly effective intervention
68 targeting brain circuits. Nor did they compare dystonia sub-types, such as cervical and generalised
69 systemia.

70 **Added value of this study** In this study, we present a comprehensive visual perceptive deep learn-
71 ing framework that addresses the gaps in current dystonia assessments. We use this framework to
72 retrospectively analyse a unique dataset from three multi-centric, studies encompassing video exami-
73 nations of patients along the dystonic severity continuum, including different deep brain stimulation

74 states. Our framework goes beyond the automation of suboptimal symptom severity assessments by
75 reverse engineering a set of clinically inspired kinematic features. The resulting high dimensional, yet
76 intuitively interpretable kinematic feature space enabled us to explore disease states and effects of
77 brain circuit therapies in a level of detail comparable to experimental neuroscientific investigations.
78 Through a data-driven approach, we have identified a consistent set of only four dynamic param-
79 eters that encode dystonia severity, subtype, and the efficacy of brain circuit interventions. Notably,
80 these features are independent of static head angle deviations, which play a central role in dystonia
81 severity scores, pointing to the involvement of partially distinct neurobiological processes not cap-
82 tured by these scores. Our findings align with emerging concepts of symptom-specific brain circuits
83 and findings in rodent models of dystonia, thereby exemplifying the visual perceptive framework’s
84 potential to augment clinical management and bridge translational gaps in movement disorders re-
85 search. By providing a more comprehensive and precise assessment of the disorder, our study offers
86 valuable insights for improved treatment strategies and further understanding of dystonia’s complex
87 neurobiology.

88 **Implications of all the available evidence** The available evidence collectively underscores the
89 limitations of traditional rating scales in capturing the informative spatiotemporal dynamics of dys-
90 tonic movements, emphasizing the need for more objective and granular evaluation methods. In line
91 with recent animal studies using computer vision for dystonia quantification, recent clinical stud-
92 ies have shown the potential of computer vision-based frameworks in automating cervical dystonia
93 severity assessment and capturing head tremor metrics. However, their underlying study designs may
94 inadvertently reinforce limitations associated with the clinical scoring process.

95 In this study, we introduce a comprehensive visual perceptive deep learning framework that serves
96 as a powerful platform to augment clinical judgement and generate valuable pathophysiological in-
97 sights by extracting a set of clinically inspired, interpretable kinematic features. Our findings have
98 implications beyond dystonia, showcasing the utility of visual perceptive frameworks in enhancing
99 clinical management and fostering integration with advanced neuroimaging and neurotechnological
100 methods. This study opens doors for future translational research to explore the broader application
101 of computer vision and deep learning techniques to derive kinematic signatures of movement disorders
102 across species and experimental conditions, promising more precise and personalised assessments that
103 can significantly improve therapeutic strategies and patient outcomes.

104 Introduction

105 Dystonia is a neurological disorder characterised by abnormal movements and postures caused by
106 involuntary muscle contractions[1]. It is recognised as the third most prevalent movement disorder,
107 with recent estimates as high as 732 per 100,000 individuals [2]. Despite advancements in under-
108 standing the epidemiological, neurogenetic, and neurobiological factors associated with dystonia, the
109 identification of objective biomarkers remains challenging. Consequently, the diagnosis, monitoring
110 of treatment outcomes, and classification of dystonia heavily rely on clinical phenomenology. This
111 entails considering various factors, such as the distribution of affected body regions, which allows for
112 categorising dystonia along a severity spectrum of focal, segmental and generalised manifestations[2].
113 However, dystonic movements exhibit highly complex spatiotemporal characteristics, involving a com-
114 bination of tonic and phasic elements, such as twisting, tremulous oscillations, and overflow to other
115 body regions, occurring on variable time scales and exacerbated or alleviated by certain movements
116 [1, 3–5]. Achieving precise clinical phenotyping of dystonia poses a significant challenge, demanding
117 expert visual perception skills[6].

118 To accurately assess disease progression and therapeutic outcomes in dystonia, it is essential to
119 employ reliable and well-defined operational measures that can be consistently measured and inter-
120 preted across diverse clinical settings and practitioners. This is of particular relevance for assessing
121 outcomes of available therapies, ranging from oral medication to Botulinum neurotoxin injections
122 for selective muscle weakening and deep brain stimulation (DBS)[7]. To date, clinical rating scales
123 such as the Toronto Western Spasmodic Torticollis Rating Scale (TWSTRS) for cervical dystonia
124 and the Burke-Fahn-Marsden Dystonia Rating Scale (BFMDRS) for generalized dystonia have been
125 extensively utilised for this purpose [8–10]. These scales aim to condense complex clinical observa-
126 tions into simplified representations, relying on a limited set of categorical items, such as head-angle

127 deviations in attempted neutral head position, encoded by a few ordinal values. Although this simpli-
128 fication offers advantages in time-sensitive clinical settings, it is accompanied by significant clinimetric
129 limitations, including substantial inter-rater variability[11–13]. Furthermore, the original versions of
130 these scales fail to quantify important information regarding abnormal movement trajectories, action-
131 induced changes of dystonia, dystonic overflow (i.e., the spread of dystonic posturing/movement to
132 adjacent body parts), and tremor, which has recently been recognised as affecting a majority of dys-
133 tonia patients [14]. Yet, emerging evidence from animal models highlights the critical role played by
134 the rich spatiotemporal structure of motor behavior in understanding the pathocircuitry of dystonia,
135 thereby shaping our approach to investigation and treatment [15–17]. The lack of standardised op-
136 erational and shared measures hampers translational efforts, thus necessitating the development of
137 objective outcome measures[3, 18].

138 To address the challenges of dystonia assessment, researchers have explored various instrumented
139 solutions, such as electromyography[7] or body-worn sensors[19]. However, the successful integration
140 of these approaches into clinical practice has proven elusive[20]. Contactless, vision-based methods
141 utilising multiple and/or special depth cameras have shown promise in extracting head angles in
142 cervical dystonia. Nevertheless, their clinical validity has been limited, especially when operating
143 under monocular conditions [21, 22]. In this context, computer vision, a branch of contemporary
144 artificial intelligence, has emerged as a disruptive and promising technology in clinical neuroscience
145 and broader medical applications [23–26]. By leveraging convolutional neural networks (CNNs),
146 visual perceptive frameworks offer several advantages, including real-time 3D human pose tracking
147 derived from monocular 2D videos captured by consumer-grade camera hardware [27, 28]. These
148 advancements have significantly improved head pose estimation [29–31], some of which have been
149 employed to semi-automate TWSTRS ratings [20]. However, these studies have primarily focused
150 on reproducing the rating score by quantifying static head angular deviations in a single fixed head
151 position, thereby reinforcing the aforementioned limitations and biases associated with the rating
152 scale. Our hypothesis is that a naturalistic approach, which incorporates both gestalt aspects and
153 the dynamics of head movement, will lead to a more accurate and ecologically valid assessment of
154 dystonia. This approach will enable us to capture subtle variations and intricate patterns that may
155 have been overlooked by previous constrained methods. Furthermore, we propose that including
156 healthy controls and different dystonia subgroups, with repeated recordings at various therapeutic
157 states (e.g., different DBS settings), will allow us to explore multiple facets of specificity in these
158 digital physiometers.

159 In this study, we have developed a visual perceptive deep learning framework that utilises com-
160 puter vision to analyze the dynamics of natural head movement. The goal was to identify distinct
161 patterns, or pathosignatures, that have diagnostic and therapeutic implications. By doing so, we
162 aimed to enhance our understanding of the underlying pathophysiology of dystonia and effects of
163 therapeutic neuromodulation. Specifically, we trained a novel convolutional neural network to pre-
164 dict movement states, and we combined the outputs with head angles obtained from a benchmark
165 algorithm, MediaPipe, to extract both static and kinematic features from patients undergoing clinical
166 dystonia examinations. To demonstrate the feasibility of our approach, we conducted a retrospective
167 cohort study to assess the agreement between predicted severity and clinical ratings, establishing how
168 both static and dynamic variables change in response to DBS. Subsequently, we validated the predic-
169 tive accuracy of dynamic variables using an additional cohort of patients with generalised dystonia.
170 Lastly, we provide insights into the added value of the dynamic variables in differentiating between
171 patients with cervical dystonia and those with generalised dystonia.

172 **Methods**

173 **Study design and participants**

174 We sourced clinical video data documenting the severity of cervical and generalised/segmental dys-
175 tonia from two prospective, longitudinal, multi-centre cohort studies investigating the therapeutical
176 effect of pallidal DBS on dystonia [32–34] and a third, multi-centre retrospective investigation ana-
177 lyzing clinical outcomes using advanced neuroimaging techniques [35]. The sourced data was split
178 into two data sets, based on dystonia subtype: (i) cervical and (ii) generalised dystonia. The cervical
179 dystonia cohort comprised 86 cervical dystonia patients from Rostock, Heidelberg, Dusseldorf, Berlin,
180 Innsbruck, Oslo, Hannover, Kiel, Würzburg. The generalised dystonia cohort, used for independent

181 validation, comprised 30 patients from the same centres. Individual datasets were included if (i) they
182 contained at least one pre-operative clinical rating video showing the full dystonic phenotype and
183 a video from the chronic postoperative phase (3-15 months post surgery) documenting the effects
184 of clinically programmed DBS and (ii) both videos fulfilled minimal criteria ensuring video quality,
185 which were chosen to reflect the current best practice in clinical computer vision approaches [20, 23,
186 24]. These were: (i) front view perspective of a single individual sitting on a chair, (ii) no significantly
187 obscuring items on patients (e. g. excessive head dressings with externalised DBS device), (ii) no
188 excessive camera movements, variable zoom depths or lighting insufficient to identify typical body
189 landmarks (e.g., eyes), (iii) continuous presence of head and neck in the camera frame. A final set
190 of 232 videos, comprising a total of 116 individual patients, was analysed in this study. All videos
191 were recorded with standard consumer grade camera hardware, in most instances mounted on a tri-
192 pod. The minimal spatiotemporal resolution was 540×540 pixels and 24 frames per second. An
193 additional cohort of 22 healthy controls underwent a structured TWSTRS examination and a head
194 position matching task. This task was precisely timed to map ground truths of head movement range
195 along each of the three principal rotational axes (pitch, yaw, tilt; see supplementary Figure S1 for
196 the detailed protocol).

197 **Ethics approval.** This study was approved by the Julius-Maximilians University ethics committee
198 (AZ 301/20). The original studies had been approved by the responsible ethics committees.

199 **Clinical scoring.** Respective dystonia severity rating scales, i.e., Burke-Fahn-Marsden dystonia
200 rating scale (BFMDRS) for generalised dystonia and the Toronto Western Spasmodic Torticollis
201 severity part (TWSTRS) for cervical dystonia, had originally been administered in an open-label
202 approach or by one expert rater. In order to eliminate potential scoring biases and to extend the
203 clinical rating to include head tremor[9], all videos were re-scored. To this end, video segments in
204 which patients were asked to let their head drift to its natural null position were annotated. These
205 segments partly reflect the individual dystonic phenotype and its severity (corresponding to TWSTRS
206 severity element I). Three raters, two blinded senior movement disorders experts (DZ, CWI) and
207 one junior investigator (LF) specifically trained using the TWSTRS teaching tape[8], applied the
208 TWSTRS severity part. Three raters, two blinded senior movement disorders experts (DZ, SRS) and
209 one junior investigator (LF), also applied an additional head tremor subscore from TWSTRS-2[9].
210 For subsequent analyses, we mainly focused on TWSTRS severity item assessing the time-weighted
211 deviation of head posture from neutral straight ahead along three main rotational axes, namely pitch
212 for antero-/retrocollis, yaw for torticollis and tilt for laterocollis. The original TWSTRS contains
213 further items, which however failed to meet criteria for utility in subsequent investigations[9]. Each
214 item is scored on an ordinal scale from 0 – 3 (laterocollis, anterocollis, retrocollis) or 0 – 4 (torticollis,
215 head tremor), corresponding to increasing angle deviations of the head from the midline or in case of
216 tremor, its amplitude, duration and dominant direction. Assessors' ratings were collapsed into one
217 'mean score' for subsequent model evaluations.

218 Visual perceptive deep learning framework

219 We built a comprehensive framework for assessing dystonia phenotype and severity, enabling auto-
220 mated kinematic evaluation directly from video. Our approach involved combining the outputs of two
221 convolutional neural networks: one tracking facial landmarks and the other one for extracting gestalt
222 information, represented as movement states. From each video, utilizing the deep learning outputs,
223 we derived static variables during periods when patients were instructed to allow their heads to drift
224 to a neutral position (referred to as the null position). In addition, dynamic variables capturing the
225 patients' natural movement patterns were extracted using the entire duration of the TWSTRS video
226 examination. We should note that these clinical examinations often didn't follow the full TWSTRS
227 protocol, nor did they necessarily follow the prescribed ordering of movements.

228 To achieve face and head tracking, we utilized a pre-trained model from MediaPipe [30]. We
229 opted for MediaPipe due to its real-time applicability and compatibility with mobile devices, which
230 holds potential for point-of-care applications. The default tracking values of MediaPipe's video mode
231 (detection confidence: 0.5; tracking confidence: 0.5) were employed. Head angles were calculated
232 relative to a neutral face-forward position along three axes of movement (torticollis, laterocollis,
233 and antero-/retrocollis) using the face mask. We employed the orthogonal Procrustes technique to

234 compute the rotation necessary to minimize the discrepancy between the rotated 3D face mask and
235 a face-forward face mask, thus obtaining accurate head angles [36].

236 To track gestalt patterns throughout the videotaped examinations, which lacked a fixed protocol
237 and order, we aimed to classify the head movement states on a frame-by-frame basis along the three
238 principal axes. For this purpose, we developed a custom model trained on videos of healthy controls.
239 We fine-tuned a pre-trained resnet50 convolutional neural network model in PyTorch for 30 epochs to
240 achieve loss convergence. The training and validation data sets consisted of images from 22 healthy
241 controls and 23 cervical dystonia patients, with participants exclusively assigned to one data split. 15
242 healthy controls and 15 patients were used for training, and the remainder for validation. Movement
243 states (e.g., ‘face forward’ or ‘tilt left’) were labeled by a junior movement disorders expert (MF). The
244 custom model demonstrated training and validation accuracies of 83.8% and 84.6%, respectively. We
245 employed multilabel classification with a binary cross-entropy loss function during model training,
246 and additional details are provided in the appendix.

247 Using the outputs of the two convolutional neural network models, we engineered several kinematic
248 features that capture the temporal evolution of patients’ head trajectories beyond simple angular de-
249 viations. These kinematic features aimed to quantify clinically relevant observations in dystonia that
250 are commonly noted but seldom quantified in clinical settings, such as movement overflow to other
251 bodyparts as well as action-induced changes of dystonia, both resulting in asymmetrical or abnormal
252 movement trajectories, dystonic tremor[14] and the complexity of dystonia characterised by the
253 involvement of multiple axes in phasic or tonic movements and movement predictability over time.
254 The features were partially harmonised with kinematic features recently reported to be relevant to
255 dystonia phenotype and genetics in rodent models of dystonia [15, 16] as well as the characterisation
256 of brain dynamics more broadly [37, 38]. The derived features primarily included correlations, sym-
257 metries, oscillatory and entropy-related characteristics, which are further described below.

258

259 **Correlation features:** The movement state predictions, represented by softmax outputs from the
260 convolutional neural network, and the head-angle measurements (in degrees) are continuous values
261 assigned to each frame of the video. To investigate the relationship between movement states, we
262 calculated the Pearson correlation between them. By calculating the Pearson correlation between
263 movement states, we are exploring the interdependence of different movement patterns. For instance,
264 a high correlation between the prediction probabilities of rotation left and tilt left would indicate
265 that the movement vectors blend or exhibit a certain degree of overlap when the patient rotates left.
266 This suggests that the movement states become ‘entangled’ or ‘intermixed’ during specific actions,
267 as recently suggested in experimental studies [15]. Healthy controls are expected to show minimal
268 correlations between movement states and head angles, indicating precise and distinct control of head
269 movements. These features aim to capture phenomena such as overflow and complexity, as well as
270 abnormal movement trajectories.

271 **Head oscillations:** The primary frequency and amplitude of head-angle oscillations along each
272 axis of motion were assessed using a Fourier spectrogram. To isolate the relevant oscillatory signals
273 and remove intended head movements dictated by examination protocol, a bandpass filter with an
274 order 6 Butterworth filter was applied, limiting the frequencies to the range of 2 – 10 Hz. These
275 features aim to capture phasic characteristics, such as dystonic jerks and tremors. It is expected that
276 healthy controls will exhibit minimal or no head oscillations in these frequency ranges.

277 **Symmetry features:** Each axis of head motion can exhibit movement in opposite directions from
278 a neutral face-forward position. To quantify the symmetry of each motion axis, we calculated the
279 proportion of time the head was oriented in one direction compared to the opposite direction. For
280 instance, if a patient spent 7 seconds in rotation left and only 3 seconds in rotation right, the symmetry
281 value would be calculated as $(7 - 3)/10 = 4/10 = 0.4$. Values closer to zero indicate a stronger
282 symmetry, while large positive or negative values indicate a significant asymmetry. These features
283 aim to capture fixed, tonically abnormal head deviations and asymmetrical movement trajectories.
284 Healthy controls are expected to demonstrate a high degree of symmetry in their head movements.

285 **Multi-scale entropy (MSE):** Entropy measures provide a quantitative way to assess the irreg-
286 ularity or complexity of time series data, making them well-suited for capturing the intricate and
287 nonlinear dynamics often observed in dystonic movements [37, 38]. Abnormal movements in dystonia
288 often exhibit both short-term irregularities (e.g., tremor) and long-term temporal patterns (e.g., sus-
289 tained postures) that are not easily captured by traditional measures. MSE quantifies the complexity
290 and regularity of dystonic movements at different temporal scales. By applying MSE to kinematic
291 time series data, a scale-dependent measure of complexity can be obtained, potentially revealing
292 specific temporal patterns or fluctuations associated with disease states or treatment effects. We
293 hypothesize that DBS will increase the regularity and predictability of their movements, indicative of
294 improved motor control.

295 Evaluation of the visual perceptive framework

296 Performance in evaluating predominant direction and severity of dystonic head deviation was mea-
297 sured by Pearson correlation between the clinically annotated TWSTRS and the head angle excursion
298 along each axis of motion respectively. Performance in evaluating the tremor component of patients
299 was measured by Pearson correlation between the clinically annotated tremor score and the head
300 angle oscillation amplitude along each axis of motion respectively. To measure the robustness of our
301 approach, a validation dataset comprising generalised dystonia patients without clinical annotations
302 was used. The same kinematic variables were extracted from the full videos and a statistical analysis
303 comparing DBS conditions (preoperative off, postoperative on).

304 Statistical analysis

305 **Univariate analysis** Univariate variable analysis was performed to discover kinematic features
306 that differed (i) between stimulation conditions in cervical dystonia, and between cervical and gen-
307 eralised dystonia. To establish significance, we used either Wilcoxon (when paired between pre- and
308 postoperatively) or Mann-Whitney U-tests, and report p-values adjusted for multiple comparisons
309 (Benjamini Hochberg false discovery rate correction, FDR). Effect sizes were computed using rank-
310 biserial correlation. To aid interpretation, we ranked variables by their effect sizes. Statistical analyses
311 were done in Python with the statmodels package (0.15.0). Correlation analysis was performed to
312 identify relationships between head angle excursions and annotated scores. Pearson correlations were
313 calculated in Python with the scipy package (1.4.1).

314 **Harmonic analysis** The strength of the fundamental tremor frequency and its first harmonic
315 (double the fundamental frequency) were calculated using the distance correlation between their
316 instantaneous phases. The harmonic strengths were determined using the head angles for each axis
317 of motion respectively. Distance correlations were calculated in Python with the dcor package (0.6)

318 Results

319 A total of 88 patients were retrospectively rated in both treatment conditions by three independent
320 raters using the TWSTRS severity rating scale, as well as the TWSTRS-2 tremor item. We ensured
321 that the raters were blinded to the disease and treatment status of the patients. For severity ratings,
322 we focused on the attempted neutral, 'null' head position captured in each video, aiming to capture
323 dystonic head deviations in three principal axes: yaw for torticollis, tilt for laterocollis, and pitch
324 for antero-/retrocollis. We observed considerable variation in the annotated scores among the raters,
325 which differed between axes: while clinical raters strongly agreed (mean Cohen-kappa score: 0.86) on
326 torticollis severity, they only moderately agreed on laterocollis and antero-/retrocollis scores (mean
327 Cohen-kappa scores: 0.65, 0.67 respectively) (Figure S2). Across all axes, DBS treatment led to
328 a significant reduction in clinical ratings, i.e., severity (Figure S3A). However, effect sizes differed
329 considerably within each axis: 0.71 for torticollis, 0.49 for laterocollis and 0.85 for anteroretrocollis.
330 Moreover, individual clinical scores exhibited a strong correlation between the pre- and post-operative
331 DBS conditions (Figure S4A). Longitudinally, post-operative clinical ratings in the torticollis and
332 laterocollis directions demonstrated a negative correlation with the duration between pre- and post-
333 operative evaluations, in line with the clinical observation of delayed effects (Figure S4B). However,

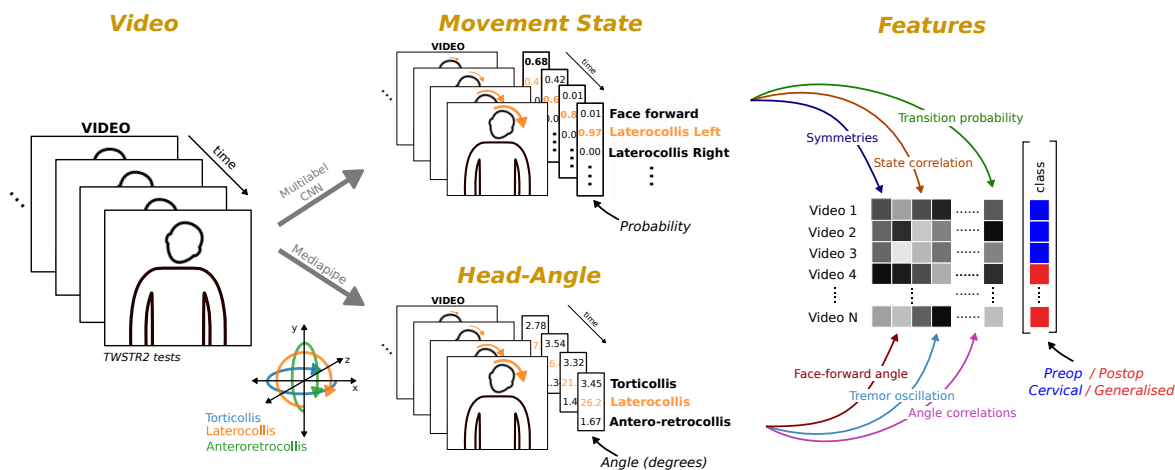


Figure 1: **Measurement of static and kinematic features using computer vision workflow.** Videos comprising individual frames are fed into convolutional neural network models that predict the movement state, i.e., the probability of the head direction of a patient, and track face-mesh coordinates to derive head angles for each frame. Head angle deviations can be extracted directly during periods of the video where a patient attempts a neutral face forward position. Using the full video, kinematic features can be constructed from the movement states predictions and angles, e.g., the correlation between axis of rotation or dystonic tremors. Features can be stored and compared across groups, such as operation status or disease.

334 there was no correlation between the difference in clinical rating from pre- to post-operation and the
 335 duration of time (Figure S4C).

336 We proceeded to assess the clinical relevance of the visual perceptive framework in accurately
 337 capturing angular deviations of the head. We extracted the excursion of head angles from attempted
 338 neutral head positions for each patient. The head angles strongly agreed with clinical scores for all
 339 principal axes of motion ($r \geq 0.66$, Figure 2A). We further observed a significant reduction of head
 340 angle deviations in each axis by DBS (Figure 2B) with largest effect sizes in torticollis (0.59), followed
 341 by laterocollis (0.46) and anteroretrocollis (0.38). To further investigate the relationship between head
 342 angle deviations and clinical characteristics, we divided the patients into three phenotypic groups
 343 based on their dominant axis of deviation. We discovered that each group of patients exhibited
 344 a significant change from pre- to post-operative evaluations only in their respective dominant axis
 345 of deviation (effect sizes: torticollis 0.76; laterocollis 0.93; anteroretrocollis 0.60; Figure 2C). For
 346 instance, patients with a dominant torticollis excursion only demonstrated a significant change in
 347 yaw but not in other axes. Furthermore, we found no systematic excursion in a particular direction
 348 for any axis of movement (Figure S5). The pre- and post-operative head angles exhibited a strong
 349 correlation (Figure 2D), indicating a reduction in angle excursion following treatment but not a
 350 complete elimination. However, we did not observe a systematic correlation between head angles in
 351 different axes of motion among both patients and controls (Figure 2E).

352 Next, we hypothesized that relying solely on the measurement of static head angular deviations
 353 is inadequate for providing a comprehensive description of the diverse range of dystonic movement
 354 abnormalities observed in real-world clinical assessments. An example of the head-angle kinematics
 355 from a full clinical examination both pre- and post-operation is shown in Figure 3A. Therefore, we
 356 conducted an explorative analysis of videos encompassing the entire TWSTRS severity assessment,
 357 utilising a comprehensive set of clinically inspired kinematic variables (Figure 3C left). First, we find
 358 that several kinematic variables are significantly larger pre-operatively. The top five differentiating
 359 features included oscillatory characteristics in each axis (ranging from 2-10 Hz) and correlations of
 360 movement states. Notably, the effect sizes of these kinematic features were generally larger than those
 361 of angle deviations during attempted neutral face-forward positioning, suggesting that they are more
 362 responsive to DBS intervention. To identify kinematic features that are predominantly associated with
 363 a favourable treatment response, we further divided the sample into responder and non-responder
 364 groups based on the degree of improvement in overall clinical rater scores (i.e., patients with \geq or
 365 $<$ 30% improvement, Figure 3B). After repeating statistical tests between DBS conditions for the

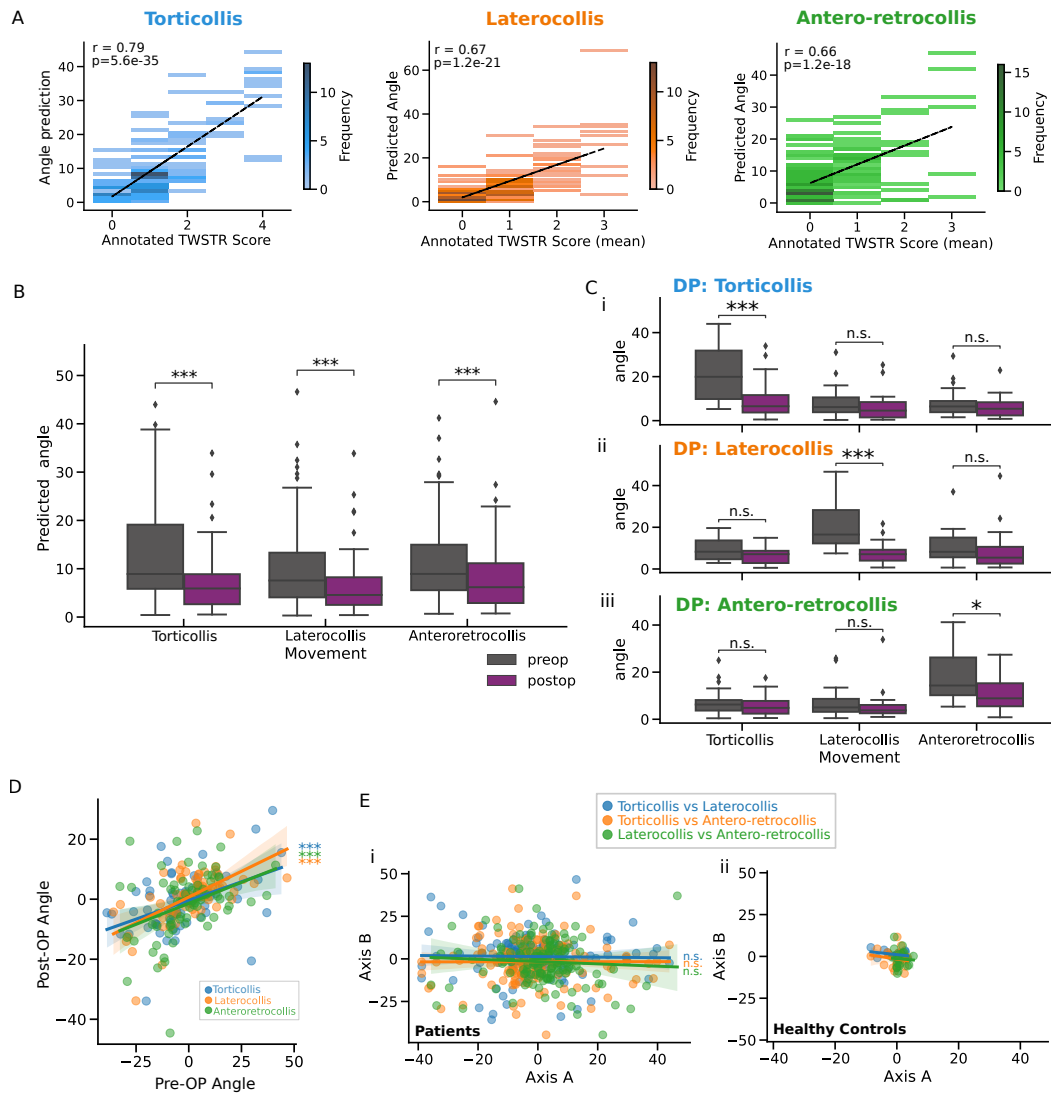


Figure 2: Computer vision analysis of head angle during periods of face-forward. **A** 2-D histograms for comparing video derived head-angle (absolute angle) and clinically assigned TWSTRS scores for each axis of motion. **B** Box plots showing (absolute) pre- (grey) and post- (purple) operative angles, for each axes of movement. Median and interquartile ranges are displayed in each plot. **C** Like (B) but patients are separated into their dominant phenotypes, i.e., their dominant axis of deviation from face-forward. **D** Scatter plot showing correlation of predicted pre- and post-operative head angles for each movement axis. **E** Scatter plots correlating each pair of axes of motion for (i) patients and (ii) healthy controls, for pre- and post-op combined. Correlations were Pearson r tests. Group tests were Mann-Whitney U-tests: * $p < 0.05$; ** $p < 0.01$; *** $p < 0.001$.

366 responder and non-responder groups respectively, we found that the top five kinematic features were
 367 also more strongly modulated in the responder group (calculated as effect size of responders minus
 368 the effect size of non-responders, Figure 3C right). To understand the time-scales at which dystonic
 369 movements were modulated by DBS, we applied multiscale entropy analysis to the head-angle time-
 370 series. At DBS ON, patients displayed less complex head movements at shorter timescales (i.e., $< 1s$)
 371 (Figure S6), but no significant differences were observed at longer scales (i.e., $> 1s$), indicating that
 372 neural circuit interventions restore movement regularity on subsecond time scales.

373 Despite the original purpose of the scores to capture head-angle deviations from the natural face-
 374 forward position, we hypothesized a significant influence of a broader clinical impression beyond
 375 pure angular deviations. Hence, we investigated whether the kinematic variables also correlated with
 376 the clinically annotated scores. We found that various kinematic features positively and negatively

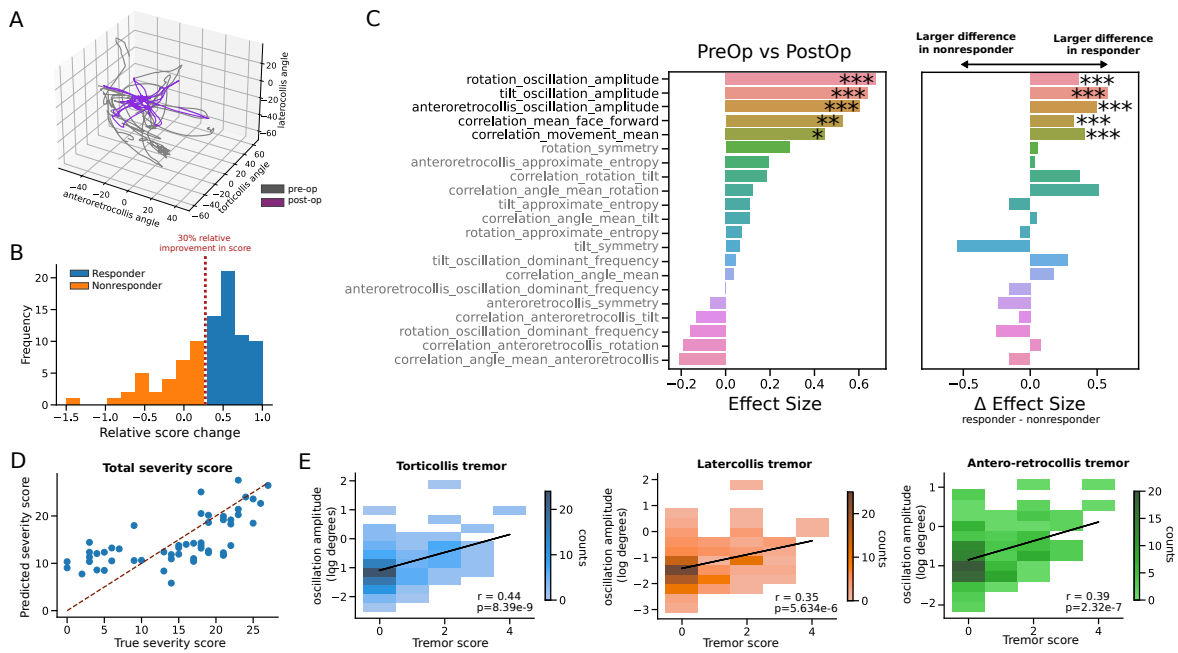


Figure 3: Statistical analysis of kinematic variables from full-videos. Kinematic variables (e.g., head tremor amplitude and frequency, correlations of movement states) were derived from the full-video as patients performed a series of clinically assigned movements. **A** Example of the head-angle kinematics for a randomly chosen patient pre- and post-operation reveals a more structured movement with DBS. **B** Responders are patients who observed a 30% relative improvement in their clinically rated score from pre-operative DBS off to post-operative DBS on. **C** Summary of statistical analysis, showing (i) effect size of Wilcoxon tests between pre- and post-operation (rank-biserial correlation, positive effect indicating variable is larger during pre-operation period) and (ii) the difference in effect sizes of the responder group and non-responder group (all tests Benjamini Hochberg FDR corrected). **D** A scatter plot showing the relationship between predicted values of total severity scores using additive sequential feature selection on a linear model with a combination of kinematic and static features (mean absolute error 4.79). The dotted red line corresponds to line of perfect agreement between predicted and true holistic scores. **E** 2-D histograms for comparing video derived oscillations for each axis of motion and a clinically assigned tremor severity score (not defined by axis of motion). Fitted linear model in black. Significance levels: * $p < 0.05$; ** $p < 0.01$; *** $p < 0.001$.

377 correlated with the scores of each axis of head motion (FDR corrected p-values, Figure S7). These
 378 kinematic features included symmetries of movement, correlations of movement states, and oscillation
 379 amplitudes and frequencies. By collapsing the TWSTRS sub-item scores into an average, we further
 380 defined a holistic, clinical dystonia severity measure. Notably, the correlation strength of kinematic
 381 features to the holistic score increased when compared to the scores of each independent axis of
 382 motion, in some cases surpassing the correlation strength of the head-angle deviations (Figure S7).
 383 To independently verify the holistic score, we collected the original total TWSTRS severity score for
 384 a sub-cohort of patients (scores ranging from 0-27). Using a linear model with additive sequential
 385 feature selection, we found the optimal model to predict the total TWSTR severity score included a
 386 combination of static head-angle deviations and kinematic features (mean absolute error 4.79, Figure
 387 3D). Repeating sequential feature selection with only head-angle deviations produced inferior
 388 predictions (mean absolute error 5.63), suggesting that head-angle deviations must be accompanied
 389 by kinematic features for the automated assessment of overall dystonic severity. We further exam-
 390 ined the oscillatory kinematic features along each axis and found that they correlated with clinically
 391 assigned tremor scores (Figure 3E). However, we found no significant correlation between the oscilla-
 392 tion amplitudes and face-forward angle deviations (Figure S8), suggesting that they capture distinct
 393 dimensions of dystonic movements independent of the angle deviations in static head position.

394 To assess the robustness and validity of the extended kinematic feature set, we used an independ-
 395 ent, out-of-sample data set comprising pre- and post-operative videos of 30 patients with generalised

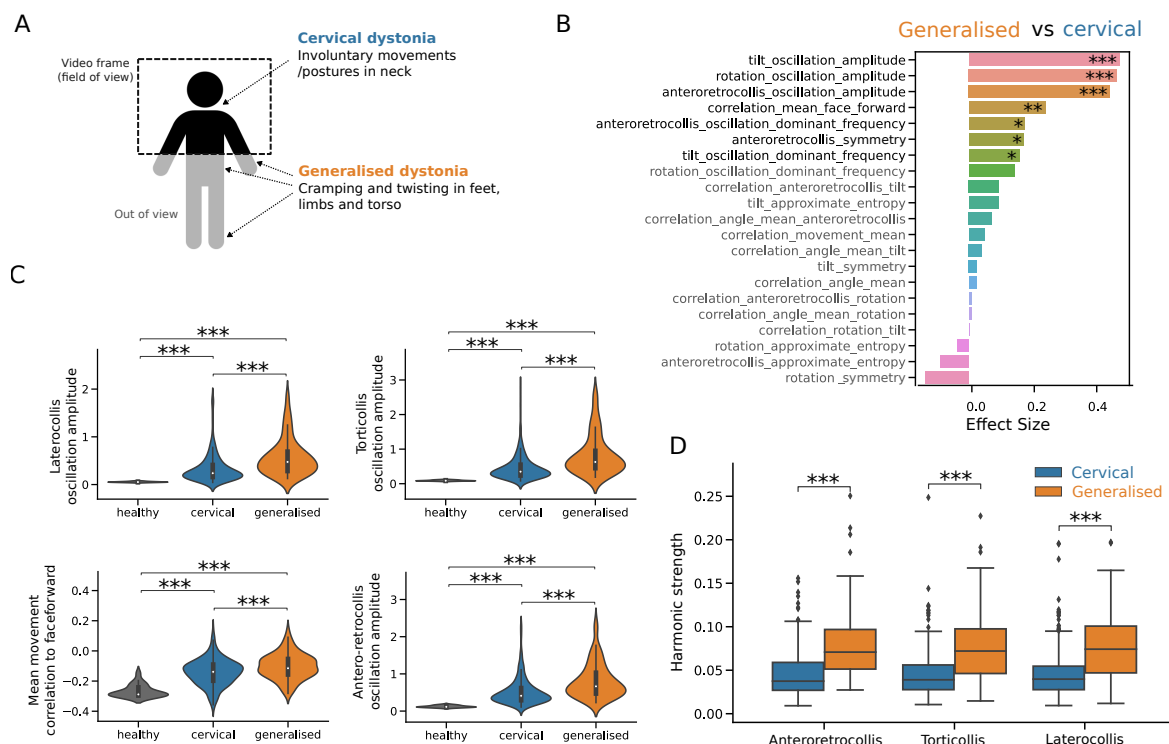


Figure 4: Comparison of generalised and cervical dystonia patients using kinematics variables. Annotations of face-forward periods were unavailable and thus only kinematic variables from the full-videos were extracted. **A** Schematic describing the typical visibility of patient pose captured by videos. Markers indicate common symptoms in cervical and generalised dystonia. **B** Effect sizes (rank-biserial correlation) of Mann-Whitney U-tests (Benjamini-Hochberg FDR corrected) between generalised and cervical dystonia patients (positive effective indicating variable is larger in generalised dystonia patients). **C** Violin plots of variables that are significantly larger in generalised dystonia patients relative to cervical dystonia patients (none were found as statistically significant vice-versa). Healthy controls shown for reference. **D** Comparison of oscillation harmonic strengths between cervical and generalised dystonia patients along each axis of motion. Harmonic strength is measured per patient as the distance correlation between the phases of the dominant tremor frequency and its harmonic (twice the dominant frequency). Mann-Whitney U-tests: * $p < 0.05$; ** $p < 0.01$; *** $p < 0.001$.

396 dystonia collected between 2002 and 2008. It should be noted that patients with generalised dysto-
 397 nia tend to also have craniocervical disease manifestations [13]. Due to the video framing, only the
 398 upper-half poses of patients were captured, thereby excluding additional signs of generalised dystonia
 399 such as twisting in limbs from the analysis (Figure 4A). As clinical ratings and periods of static
 400 face-forward were unavailable for the generalised dystonia dataset, only kinematic variables (and not
 401 head angle excursions) were extracted. We repeated the statistical analysis of kinematic variables as
 402 modulated by DBS in generalised dystonia patients (Figure S9). Remarkably, we observed that the
 403 same five dynamic variables that exhibited the strongest response to DBS in cervical dystonia were
 404 also significantly modulated in the generalised dystonia patients (Figure S9A).

405 Finally, we asked whether kinematic features could differentiate between cervical and generalised
 406 dystonia. Analysis within the kinematic feature space revealed seven features that displayed a clear
 407 differentiation between cervical and generalised patients (Figure 4B). These features were consistently
 408 larger in generalised dystonia patients. Among the significant features, four corresponded to the previ-
 409 ously identified five kinematic features that were preferentially modulated by DBS: oscillatory features
 410 in all three axes and a mean movement correlation with the face-forward position. Additionally, two
 411 frequency-related variables capturing the frequency of head oscillations in the laterocollis and an-
 412 teroretrocollis axes were also significantly larger in generalised dystonia patients. Notably, all the
 413 identified features exhibited pronounced differences compared to healthy controls (Figure 4C), indi-

414 cating their sensitivity to dystonic movements. Considering the prominent involvement of oscillatory
415 kinematic features, which are associated with tremor, we further examined the strength of harmonics
416 in cervical and generalised dystonia patients. Our analysis revealed that generalised dystonia patients
417 exhibited stronger harmonics in head tremor oscillations across all axes of motion, in comparison to
418 cervical dystonia patients (Figure 4D). Moreover, multiscale entropy analysis showed that generalised
419 dystonia patients displayed maximal entropy at much earlier timescales relative to cervical dystonia
420 patients (Figure S10). This suggests that longer-scale movement patterns hold valuable information
421 to distinguish between different stages of dystonia.

422 Discussion

423 In this study, we developed a visual perceptive framework using convolutional neural networks to
424 comprehensively evaluate dystonia based on clinical video recordings. Our unique dataset comprised
425 longitudinal video documentation of cervical and generalised dystonia patients' full clinical assess-
426 ments at multiple medical centers, including those with and without DBS. This enabled us to compre-
427 hensively evaluate head movements in both task-constrained, static conditions and quasi-naturalistic,
428 dynamic conditions, providing a holistic assessment of dystonia. Beyond technical validation, we
429 demonstrate the framework's utility to augment clinical judgement and facilitate insights pertinent
430 to disease states and the readout of neural circuit intervention effects.

431 Clinical scales, commonly used to assess dystonia and other neurological disorders, have inherent
432 limitations due to clinimetric issues, likely stemming from the oversimplification of complex disease
433 phenomenology into low-dimensional ordinal parameters [9, 11–13]. While necessary in time-sensitive
434 clinical settings, this oversimplification comes at the expense of precision, granularity, and ultimately,
435 ecological validity. An illustration of this is evident when comparing the relatively simple contempo-
436 rary scoring approaches with Oppenheim's detailed phenotypical account of dystonia from 1911 [39]
437 . For example, TWSTRS omits some key clinical features of dystonia which only become evident
438 with dynamic, voluntary movements and undoubtedly influence overall clinical judgement. Whilst
439 adaptations to TWSTRS have incorporated tremor related features [40, 41], there is still a growing
440 demand for more objective and granular disease metrics [3, 18]. Already widely used for quantitative
441 phenotyping in experimental neuroscience, computer vision approaches have recently emerged as a
442 promising new tool for clinical assessments [20, 23, 24, 42].

443 We first demonstrate the robustness and clinical applicability of our deep learning framework in
444 accurately inferring head-angle deviations during attempted 'null' head positions from diverse clinical
445 videos captured using consumer-grade hardware. Our visual perceptive approach surpasses various
446 vision-based frameworks that relied on multiple or specialized depth cameras to automate ratings
447 [21, 22], and achieves comparable performance to a recent study by Zhang et al. [20]. However,
448 a distinguishing feature of our approach is the ability to estimate head angles in real-time using a
449 portable device such as smartphones or tablets. This capability enables its practical implementation
450 in clinical point-of-care settings and at-home monitoring, enhancing accessibility and convenience.
451 Moreover, we have applied our framework to diverse clinical videos from multiple centres with slightly
452 differing protocols, showing the effects of neuromodulation in both focal and generalised dystonia,
453 highlighting the generalisability of our tool and specificity of our findings.

454 The key advantage of our framework lies in its capability to analyse full video examinations of
455 patients. To showcase this, we reverse-engineered complex clinical observations such as dystonic
456 overflow, tremor and the action-dependent dynamics of dystonic movements into objectively mea-
457 surable kinematic features. Albeit highly informative and clinically indispensable, these dimensions
458 are not explicitly part of the TWSTRS. To this end, we first tuned a convolutional neural network
459 to parse naturalistically occurring 3D head positions into discrete, geometrically defined states. By
460 projecting each sample into a high-dimensional space comprising clinically inspired and interpretable
461 kinematic features, we successfully identified a set of five kinematic variables that exhibited maximal
462 differentiation across therapy states. These were in addition to expected improvements in head-angle
463 deviations, which have been shown in prior studies [7]. In other words, these features demonstrated
464 the most pronounced response to neuromodulation, rendering them highly specific to the behavioral
465 downstream effects of the neural circuit intervention. Furthermore, our analysis revealed that these
466 same features were closely associated with a favorable treatment response to DBS, as defined clini-
467 cally by a relative score reduction of more than 30% [32, 33, 35]. This finding not only underscores

468 the relevance of these features but also highlights their potential as reliable indicators of effect and
469 efficacy of neural circuit interventions.

470 Our analysis revealed that three of the kinematic features associated with DBS effect were related
471 to head oscillations. Additionally, multi-scale entropy analysis highlighted that neuromodulation ex-
472 erts the most profound effects on movement regularity on a subsecond time scale, pointing rather to
473 high frequency phasic than low frequency, tonic aspects of dystonic movements. This finding aligns
474 with recent evidence indicating that head tremor is a prevalent manifestation in the majority of pa-
475 tients with cervical dystonia [14, 43, 44]. The recognition of tremor as a core clinical characteristic
476 only recently led to the inclusion of a quantifiable tremor item in the revised version of the TWSTRS
477 [9]. Tremor-related features emerged most consistently across contrasts, strongly highlighting the
478 previously less well documented role of oscillatory aspects in dystonia pathophysiology and therapy.
479 Notably, tremor has been associated with impaired physical functioning and pain, which are crucial
480 dimensions of quality of life in dystonia [45, 46]. Therefore, the linkage between kinematic features
481 and patient-centered outcomes provides an avenue for further investigations into ‘disease architec-
482 tures’ comprised by multiple phenotyping axes. The remaining correlational features we identified in
483 our analysis provide further insights into potential manifestations of dystonic overflow and multiaxial
484 involvement, as expressed in an abnormal covariance of head movement trajectories. These features
485 were evaluated throughout dynamic movement trajectories, capturing a key characteristic of dystonia,
486 namely the provocation of involuntary, dystonic movements through voluntary action. In an inde-
487 pendent validation dataset comprising 30 generalised dystonia patients, we found the same kinematic
488 features reflected pallidal DBS effects, confirming aforementioned results in cervical dystonia patients.
489 This demonstrates the generalisability of our findings to different states of disease progression and
490 further reinforces their disease-specific nature. Furthermore, experimental investigations in rodent
491 models of dystonia suggest that similar correlational features are independent predictors of genetic
492 susceptibility factors in rodent models of dystonia, establishing a first hint for their neurobiological
493 and translational relevance [15].

494 To gain further insights into the discriminatory potential of these kinematic features, we at-
495 tempted to distinguish different disease states, namely focal-cervical and generalised dystonia, within
496 the kinematic feature space. A total of seven features exhibited significant differences, with four of
497 the previously identified kinematic features among them. Notably, control patients exhibited the low-
498 est values, followed by cervical and then generalised dystonia patients. Multi-scale entropy analysis
499 further highlighted that focal and generalised dystonias show a pronounced difference of regularity
500 in both subsecond and longer time scales > 1 second, pointing to a more profound dysfunction of
501 motor control in generalised dystonia. Overall, these observations align well with the concept of
502 a dystonic phenotypical continuum wherein severity progressively increases [13], and suggests that
503 these kinematic features sensitively capture disease state and progression, which is of critical rele-
504 vance for interventional studies. Moreover, the emergence of a unified feature set specific to both
505 cervical and generalised dystonia aligns with recent findings demonstrating the convergence of a mul-
506 tisynaptic neural network underlying both dystonia subgroups [47]. The observed motor behavioural
507 disorganisation is mirrored on the neurobiological level by pathologically irregular neuronal firing
508 patterns associated with the dystonic state [15, 48], overall suggesting that kinematic features can be
509 a powerful readout of brain circuit function.

510 To better understand what information the kinematic features captured, we next correlated them
511 with clinically annotated scores and measured angular head deviations. Despite the clinically an-
512 notated scores purposed to capture natural head-angle deviations from attempted null position, we
513 found various dynamic features that were correlated with clinical, but not head-angle deviations.
514 This included clinical scores along each axis but also a holistic severity score. These results imply
515 that the kinematic features are, at least partially, encoded by different neurobiological substrates.
516 In terms of oscillatory features, this finding aligns with recent work on diverging symptom-specific
517 circuit components for tremor versus dystonia [49]. Moreover, it suggests that clinicians may unin-
518 tentionally incorporate more complex kinematic aspects from a patient’s dystonic symptomatology
519 into their clinical scores to more accurately reflect the global clinical impression. This could explain
520 some of the discussed limitations of current scoring approaches, which may be confounding factors
521 for score-based therapeutic or brain-behaviour association studies. Within the context of rapidly
522 emerging adaptive neurotechnologies [50] and connectomic neuroimaging techniques [47], intriguing
523 use cases for our deep learning approach come to mind, such as pathophysiologically motivated circuit
524 interrogation or guidance of adaptive and personalized neuromodulatory treatment regimes[50, 51].

525 Our study has several limitations that should be considered. Firstly, our assessments were limited
526 to videos focusing on the upper body, thereby neglecting dystonic phenomena occurring in other
527 regions. However, it is important to note that cervical dystonia is one of the most common forms
528 of dystonia, and studying head kinematics provides a valuable entry point for investigating digital
529 pathosignatures of dystonia, given the relative simplicity of head movements compared to whole-body
530 movements. Secondly, although our measurements of oscillation amplitudes demonstrated substantial
531 clinical validity, it is important to note that the degree of validity was slightly lower compared to
532 previous investigations that exclusively focused on oscillations occurring in the head's null position
533 [52]. We deliberately opted to derive tremor amplitudes from the full videos, considering that tremor
534 in cervical dystonia exhibits variation in relation to head position [43, 53]. This approach allowed
535 for a more ecologically valid estimation of tremor but also introduced natural variability into the
536 measurements. Thirdly, we did not incorporate information on DBS parametrization. The location
537 of the implanted lead and the electrical stimulation fields are known to be important predictors of
538 therapy response in dystonia [35, 47, 54]. This omission may have influenced the performance of our
539 kinematic features in capturing therapy state contrasts, as suboptimal responses could reduce the
540 overall distance between therapy states in the feature space. To partially address this limitation, we
541 conducted a subgroup analysis specifically focusing on clinically determined good responders.

542 Overall, these findings highlight the potential of our visual perceptive framework to enhance and
543 augment dystonia diagnosis, monitoring and therapy by uncovering consistent latent pathosigna-
544 tures. The proposed modern vision-based approach expands upon traditional principles of 'medical
545 cinematography' in movement science. Video-derived kinematic pathosignatures may not only inform
546 neural circuit therapeutics but also address the critical need for objective and standardized evalua-
547 tion methods in the form of digital biomarkers. Their high sensitivity has recently been shown to
548 facilitate clinical trials, genotype predictions and continuous monitoring in neurological disorders [24,
549 42, 55]. Moreover, our framework may bridge methodological gaps between clinical and experimental
550 neuroscience, which has already widely adapted computer vision for phenotyping animal models of
551 dystonia [15–17]. We envisage the proposed tool to strengthen translational and precision medicine
552 approaches in modern neurology.

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564 CS, JK, AS, MW, AKH, SP, AK, IMS, WE, JM, CM, MR Analysis: RLP, MF, CWI, DZ, LF, MM,
565 SRS; Writing - Original Draft: RLP, MF; Writing - Review: RLP, MF, SRS, CWI; & Editing: RLP,
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567 Competing interests

568 The authors declare no competing interests.

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Supplementary Material

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S1 Model variable interpretation

Below we provide more details on the interpretation of the derived variables from the deep learning framework:

Head angles:

- Angle torticollis: Head-angle deviation from face-forward in yaw axis when a patient is sitting in a neutral position. Positive angle = right, Negative angle = left.
- Angle laterocollis: Head-angle deviation from face-forward in tilt axis when a patient is sitting in a neutral position. Positive angle = right tilt, Negative angle = left tilt.
- Angle antero/retrocollis: Head-angle deviation from face-forward in antero/retrocollis axis when a patient is sitting in a neutral position. Positive angle = anterocollis, Negative angle = retrocollis.

738 **Correlation features:**

- 739 • Correlation movement mean: Mean correlation coefficient between all predicted movement
740 states.
- 741 • Correlation mean face forward: Mean correlation coefficient of each movement state to face-
742 forward movement state.

743 **Head oscillations:**

- 744 • Oscillation amplitude: The amplitude of the largest peak in a Fourier transform of the angles.
745 For each axis respectively.
- 746 • Oscillation frequency: The frequency of the largest peak in a Fourier transform of the angles.
747 For each axis respectively.

748 **Symmetry features:**

- 749 • Symmetry rotation: Proportion of time head was oriented in one direction compared to the
750 opposite direction for the rotation states (left or right).
- 751 • Symmetry tilt: Proportion of time head was oriented in one direction compared to the opposite
752 direction for the tilt states (left or right).
- 753 • Symmetry anteroretrocollis: Proportion of time head was oriented in one direction compared
754 to the opposite direction for the antero/retrocollis states (forward or backward).

755 **S2 Supplementary figures**

Filming protocol healthy control group TWSTRS

Cluster	Time	Move
	5 sec	Head straight, transition phase
Rotation to the right 30 sec	10 sec	Turn head ¼ range to the right
	10 sec	Turn head ½ range to the right
	10 sec	Turn head full range to the right
	5 sec	Head straight, transition phase
Rotation to the left 30 sec	10 sec	Turn head ¼ range to the left
	10 sec	Turn head ½ range to the left
	10 sec	Turn head full range to the left
	5 sec	Head straight, transition phase
Tilt to the right 30 sec	10 sec	Tilt head ¼ range to the right shoulder
	10 sec	Tilt head ½ range to the right shoulder
	10 sec	Tilt head full range to the right shoulder
	5 sec	Head straight, transition phase
Tilt to the left 30 sec	10 sec	Tilt head ¼ range to the left shoulder
	10 sec	Tilt head ½ range to the left shoulder
	10 sec	Tilt head full range to the left shoulder
	5 sec	Head straight, transition phase
Head to chest 30 sec	10 sec	Head to chest ¼ range
	10 sec	Head to chest ½ range
	10 sec	Head to chest full range
	5 sec	Head straight, transition phase
Head backwards 30 sec	10 sec	Head backwards ¼ range
	10 sec	Head backwards ½ range
	10 sec	Head backwards full range
	5 sec	Head straight, transition phase
Looking straight forward	30 sec	Head straight
	5 sec	Head straight, transition phase
Eye movement 40 sec	10 sec	keep eyes closed
	10 sec	Open eyes
	10 sec	Keep eyes closed
	10 sec	Open eyes
	5 sec	Head straight, transition phase
Shoulder lift right	10 sec	Lift right shoulder
	5 sec	Head straight, transition phase
Shoulder lift left	10 sec	Lift left shoulder
	1-5 sec	Transition phase, end

Figure S1: Healthy controls filming protocol.

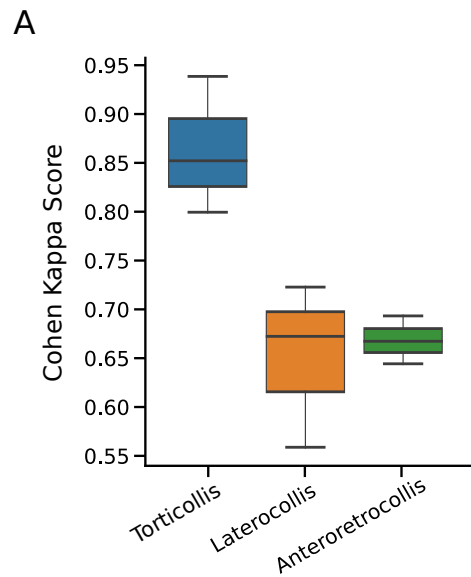


Figure S2: **Agreement of clinical raters.** Distribution of Cohen-Kappa-scores by axis (3-paired comparisons per axis).

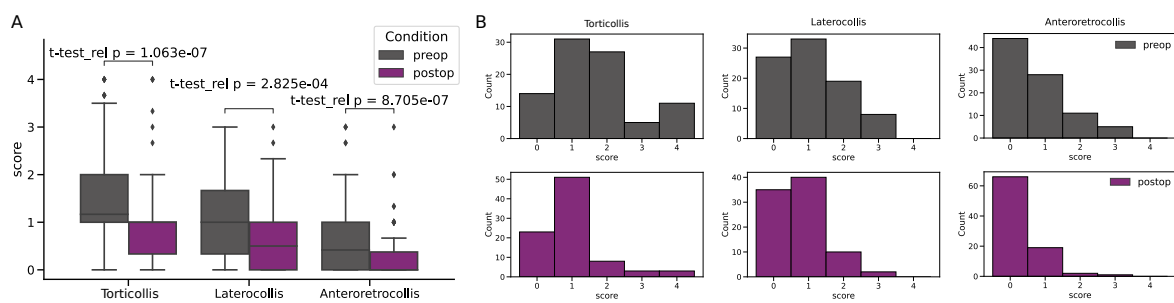


Figure S3: **Distribution of pre- and post-operative clinically annotated scores.** **A** Box plots showing clinically rated patient scores (mean across clinical raters) for pre- (grey) and post- (purple) operation, for each axes of movement. Median and interquartile ranges are displayed in each plot. **B** Pre- (top) and post- (bottom) operative distributions of scores. Maximum score is 4 for torticollis and 3 for laterocollis and anteroretrocollis.

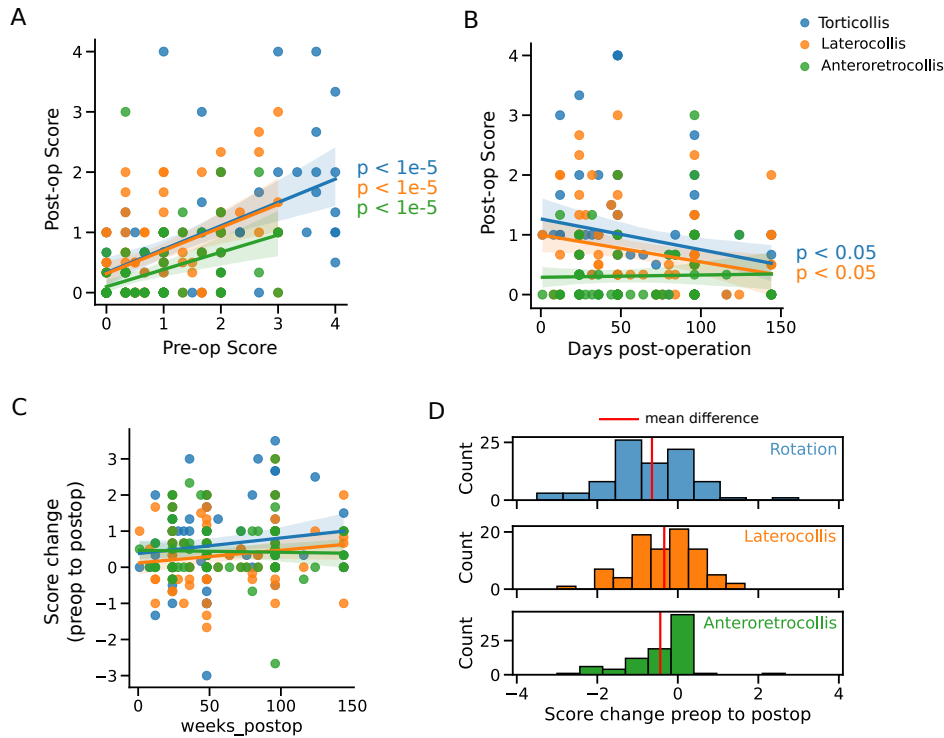


Figure S4: **Comparison of pre- and post-operation scores.** **A** Scatter plot showing correlations of pre- and post-operation scores. Fitted linear model. **B** Correlation between date of post-operative assessment and score. **C** A scatter plot of the relative change in clinically assigned scores between pre- and post-op (pre-op score subtracted from post-op score). **D** Histograms of relative changes in scores (pre-op score subtracted from post-op score). By colours: torticollis (blue), laterocollis (orange) and anteroretrocollis (green)

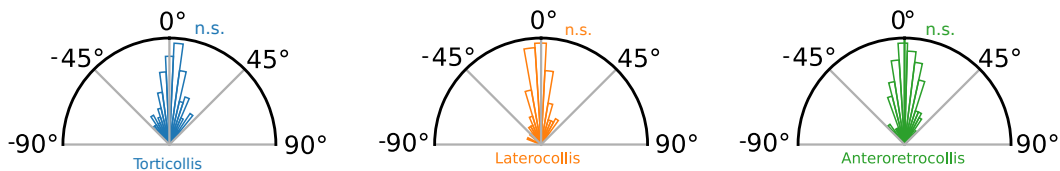


Figure S5: **Deviations from face-forward are centred at zero at the group-level.** Polar histograms showing that the average angle does not significantly deviate in any direction. One-sample t-tests were non-significant in each axis of motion.

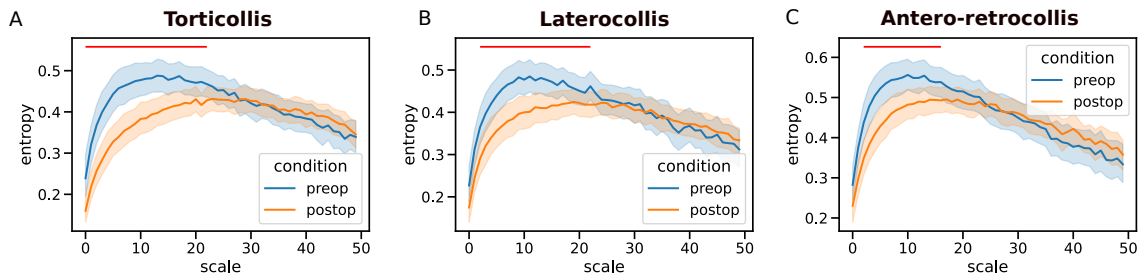


Figure S6: **Multiscale entropy reveals only short timescale differences pre- to post-operation.** Multiscale entropy analysis (approximate entropy) is applied to the each head-angle time-series for increasing scales (Python EntropyHub 0.2). Scale (x-axis) is defined in units of video frames (videos were standardised to a sampling rate of 25 frames per second). Maximal entropy is observed earlier for pre-operative recordings relative to post-operation. Red lines indicate scales with significant differences between pre and post-operation (paired t-test, $p < 0.05$).

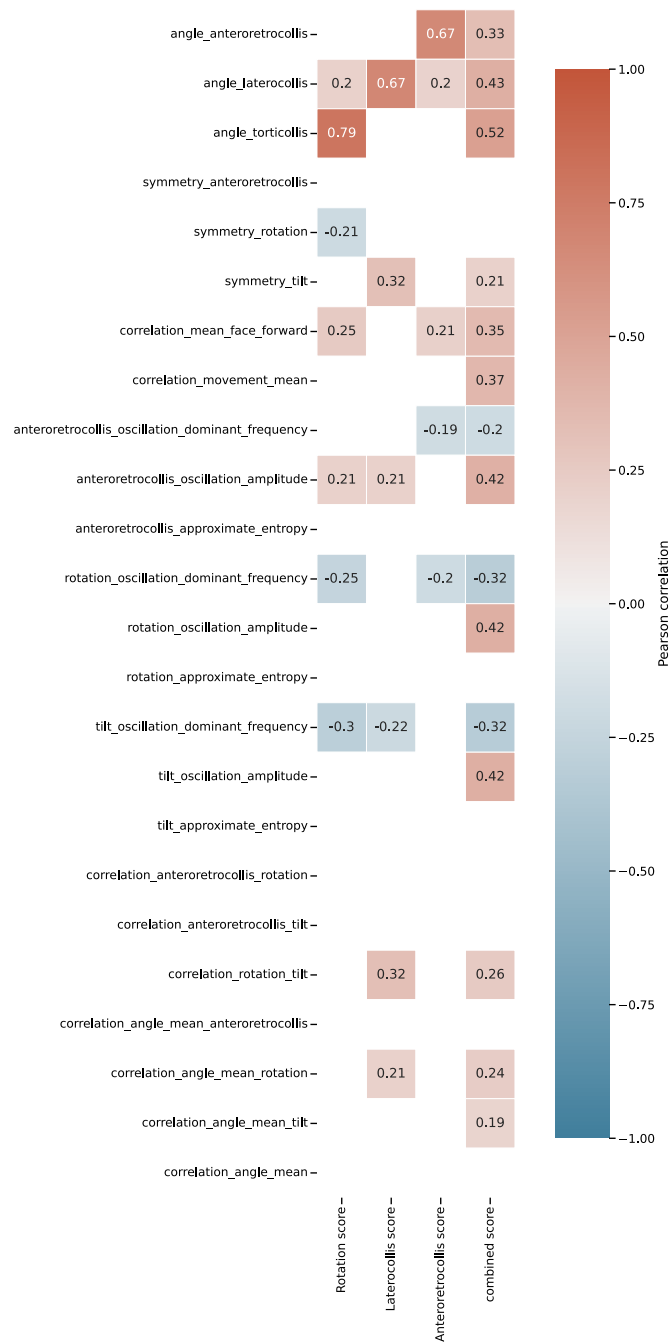


Figure S7: **Correlation of kinematic features with annotated scores.** Clinically annotated scores (mean across raters) for head-angle deviations from neutral face-forward along each axis are correlated with engineered kinematic features from full videos. A holistic score taken as the mean clinical rating across the three axes is also correlated with kinematic features. Only significant (FDR corrected, $p < 0.05$) correlations are shown.

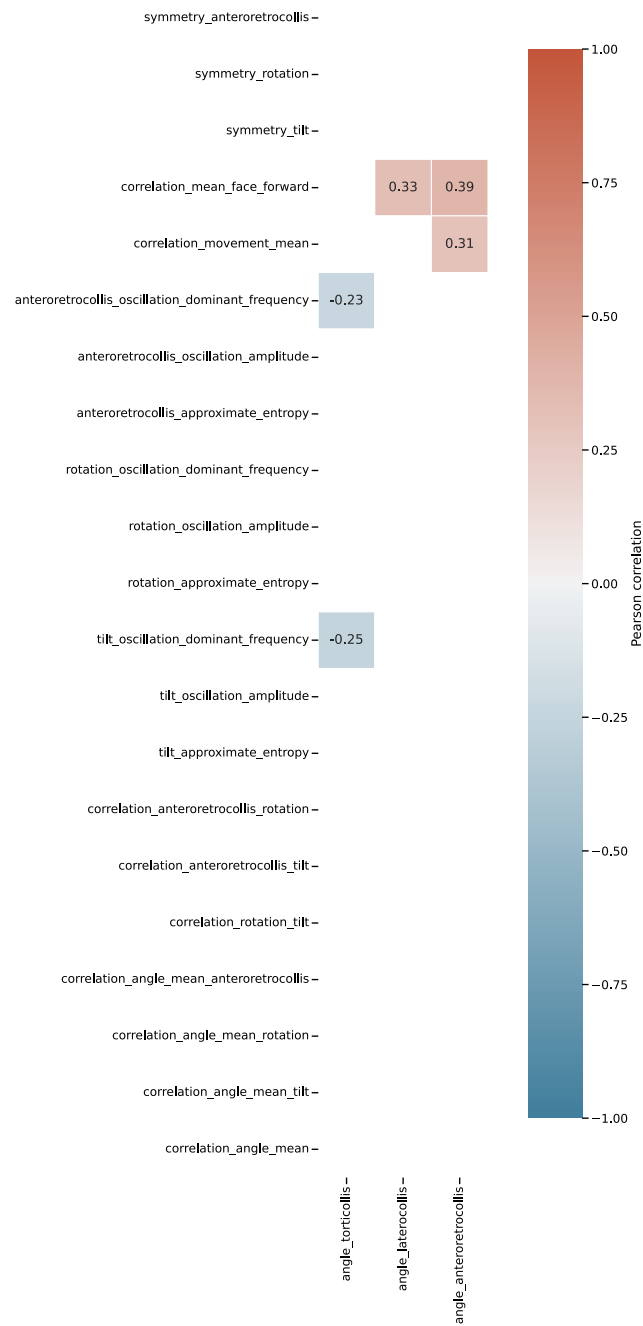


Figure S8: **Correlation of kinematic features with face-forward angles.** Head-angle deviations during attempted neutral face-forward are correlated with engineered kinematic features from full videos. Only significant (FDR multiple comparisons corrected, $p < 0.05$) correlations are shown.

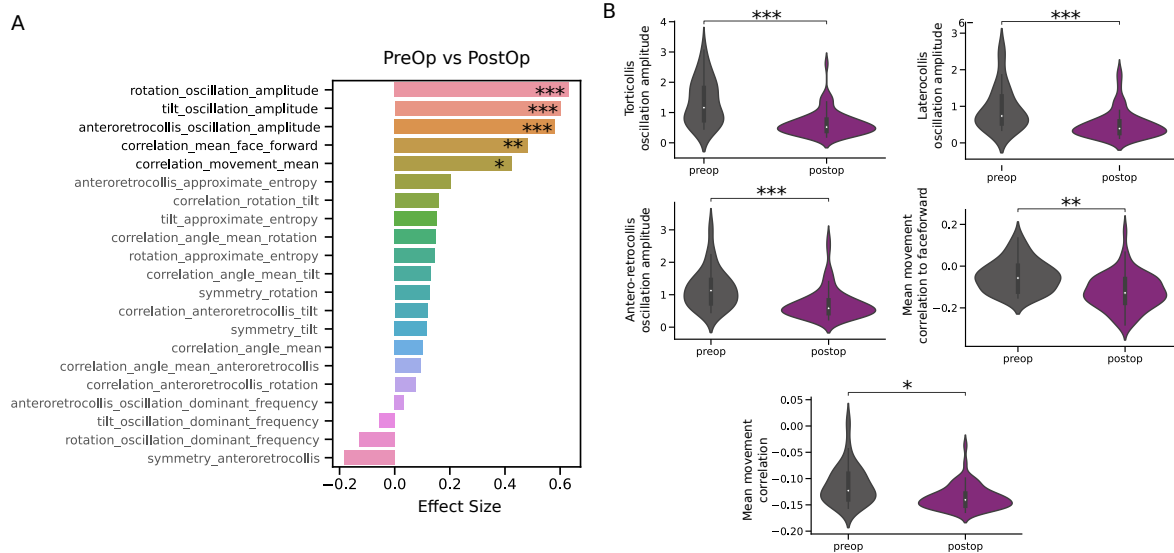


Figure S9: **Validation of full video kinematics in cohort of generalised dystonia patients.** **A** Effect size (rank-biserial correlation) of dynamical variables between pre- and post-operation with Wilcoxon tests. **B** Violin plots of variables that are significantly larger pre- (grey) relative to post- (purple) operation. Significance levels: * $p < 0.05$; ** $p < 0.01$; *** $p < 0.001$.

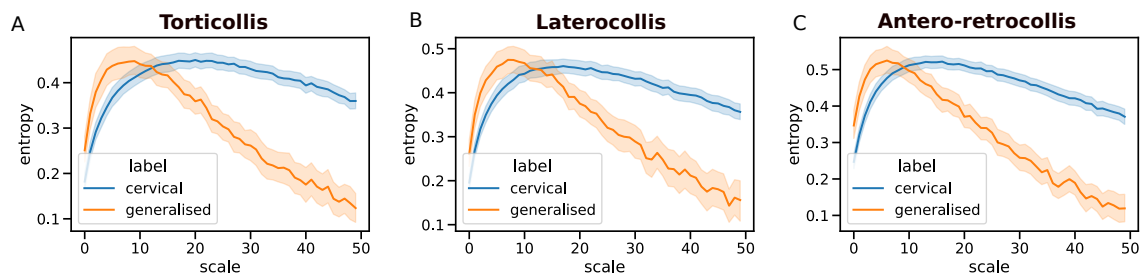


Figure S10: **Multiscale entropy reveals differences between generalised and cervical patients at all scales.** Multiscale entropy analysis (approximate entropy) is applied to the each head-angle time-series for increasing scales (Python EntropyHub 0.2). Maximal entropy is observed at earlier scales for generalised dystonia patients.