

博士論文

Isometric immersions of $\text{RCD}(K, N)$
spaces via heat kernels

「 $\text{RCD}(K, N)$ 空間の熱核による等長はめ込み」

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Abstract

This thesis deals with metric measure spaces satisfying an $\text{RCD}(K, N)$ condition, which means that the space has a lower Ricci curvature bound $K \in \mathbb{R}$ and an upper dimension bound $N \in [1, \infty)$ in a synthetic sense. Such a space $(X, \mathbf{d}, \mathbf{m})$ always admits a canonical locally Lipschitz continuous heat kernel ρ , which gives the following heat kernel embedding for any $t > 0$:

$$\begin{aligned}\Phi_t : X &\longrightarrow L^2(\mathbf{m}) \\ x &\longmapsto (y \mapsto \rho(x, y, t)).\end{aligned}$$

The space $(X, \mathbf{d}, \mathbf{m})$ is said to be an isometrically heat kernel immersing space, if there exists a real-valued function $c(t)$ such that for any $t > 0$, $\sqrt{c(t)}\Phi_t$ is an isometric immersion. A main result states that any compact isometrically heat kernel immersing $\text{RCD}(K, N)$ space is isometric to an unweighted closed smooth Riemannian manifold. This is justified by a more general result: if a compact non-collapsed $\text{RCD}(K, N)$ space has an isometrically immersing eigenmap, then the space is isometric to an unweighted closed Riemannian manifold.

As an application, we first prove that the smoothness of strongly harmonic $\text{RCD}(K, N)$ spaces, which is defined as $\text{RCD}(K, N)$ spaces $(X, \mathbf{d}, \mathbf{m})$ such that its ρ is a function depends only on t and the distance $\mathbf{d}(x, y)$.

Another application is that, we give a C^∞ -compactness theorem for $\mathcal{M}(K, n, D, \tau)$. Here $\mathcal{M}(K, n, D, \tau)$ is the set of isometry classes of smooth closed n -dimensional Riemannian manifolds (M^n, g) with Ricci curvature bounded below by K , diameter not more than D , bearing an isometric immersing eigenmap $F : M^n \rightarrow \mathbb{R}^m$ with coordinates having L^2 norm not less than τ . This is even new in the submanifold theory.

These results are based on [H23] and [H unpublished].

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1 Introduction

1.1 Ricci curvature and Ricci limit spaces

Suppose (M^n, g) is an n -dimensional Riemannian manifold. Let us indicate by ∇ the corresponding Levi-Civita connection of (M^n, g) . The Riemannian curvature of (M^n, g) is a map which takes smooth vector fields X, Y, Z and T and returns the smooth function

$$\text{Rm}_g(X, Y, Z, T) := g(\nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z, T).$$

For each point $p \in M$, Rm_g induces a multilinear map $(\text{Rm}_g)_p : T_p M^n \times T_p M^n \times T_p M^n \times T_p M^n \rightarrow \mathbb{R}$. Given any unit vector $v = v_n \in T_p M^n$, we take an orthonormal basis $\{v_1, \dots, v_{n-1}\}$ of the hyperplane in $T_p M^n$ orthogonal to v . The Ricci curvature in the direction v at $p \in M^n$ is defined as

$$(\text{Ric}_g)_p(v) = \frac{1}{n-1} \sum_{i=1}^{n-1} (\text{Rm}_g)_p(v, v_i, v, v_i),$$

and the scalar curvature at $p \in M^n$ is defined as

$$(\text{Scal}_g)_p = \frac{1}{n} \sum_{i=1}^n (\text{Ric}_g)_p(v_i).$$

The manifold (M^n, g) is said to have a lower Ricci curvature bound $K \in \mathbb{R}$ if for any $p \in M^n$ it holds that

$$(\text{Ric}_g)_p(v) \geq K g(v, v), \quad \forall v \in T_p M^n.$$

When the space is provided with a lower Ricci curvature bound and an upper dimension bound, one may get plenty of information about the topology and geometry of it. For example we have Bonnet-Myers estimate on the diameter, Bishop-Gromov inequality on volume monotonicity [G81], Li-Yau heat kernel bounds [LY86], and the Cheeger-Gromoll splitting principle [CG71].

Using the Bishop-Gromov volume comparison theorem, in [G81] Gromov also gave a precompactness result for the set of metric spaces $\mathcal{J}(K, n, D)$ under the Gromov-Hausdorff topology, where $\mathcal{J}(K, n, D)$ is the family of isometry classes of n -dimensional Riemannian manifolds bearing a lower Ricci curvature bound $K \in \mathbb{R}$ and an upper diameter bound $D > 0$.

The Gromov-Hausdorff limit spaces of sequences in $\mathcal{J}(K, n, D)$ are known as Ricci limit spaces, which are not Riemannian manifolds in general. With the help of a significant research program carried out by Cheeger-Colding [ChCo96, ChCo1,

ChCo2, ChCo3] in 90's on Ricci limit spaces, it is now known to us that Ricci limit spaces enjoy some analytical and structural properties of smooth Riemannian manifolds with a lower Ricci curvature bound.

This motivates us to study a more general class of metric measure spaces, namely $\text{RCD}(K, N)$ metric measure spaces, explained in the next section.

1.2 Metric measure spaces satisfying the $\text{RCD}(K, N)$ condition

In this thesis, a triple $(X, \mathbf{d}, \mathbf{m})$ is said to be a metric measure space if (X, \mathbf{d}) is a complete separable metric space and \mathbf{m} is a nonnegative Borel measure with full support on X and being finite on any bounded subset of X .

In the first decade of this century, Sturm [St06a, St06b] and Lott-Villani [LV09] independently defined a notion of a lower Ricci curvature bound $K \in \mathbb{R}$ and an upper dimension bound $N \in [1, \infty]$ for metric measure spaces in a synthetic sense, which is named as the $\text{CD}(K, N)$ condition. A metric measure space is said to be an $\text{RCD}(K, N)$ space if it satisfies the $\text{CD}(K, N)$ condition, and its associated $H^{1,2}$ -Sobolev space is a Hilbert space. The precise definition of $\text{RCD}(K, N)$ spaces (and the equivalent ones) can be found in [AGS14b, AMS19, G13, G15, EKS15].

As an example, any weighted Riemannian manifold $(M^n, \mathbf{d}_g, e^{-f} \text{vol}_g)$ such that $f \in C^\infty(M^n)$ and that $\text{Ric}_N \geq Kg$, is an $\text{RCD}(K, N)$ space, where Ric_N is the Bakry-Émery N -Ricci curvature tensor defined by

$$\text{Ric}_N := \begin{cases} \text{Ric}_g + \text{Hess}_g(f) - \frac{df \otimes df}{N-n} & \text{if } N > n, \\ \text{Ric}_g & \text{if } N = n \text{ and } f \text{ is a constant,} \\ -\infty & \text{otherwise.} \end{cases}$$

In the sequel, we always assume that N is finite.

Given an $\text{RCD}(K, N)$ space $(X, \mathbf{d}, \mathbf{m})$, with the aid of a work by Bruè-Semola [BS20], there exists a unique $n \in [1, N] \cap \mathbb{N}$, which is called the essential dimension of $(X, \mathbf{d}, \mathbf{m})$ and is denoted by $n := \dim_{\mathbf{d}, \mathbf{m}}(X)$, such that the n -dimensional regular set \mathcal{R}_n (see Definition 2.24) satisfies that $\mathbf{m} = \theta \mathcal{H}^n \llcorner \mathcal{R}_n$ for some Borel function θ (see [AHT18]), where \mathcal{H}^n is the n -dimensional Hausdorff measure. It is remarkable that the canonical Riemannian metric g on $(X, \mathbf{d}, \mathbf{m})$ is also well-defined due to a work by Gigli-Pasqualetto [GP16] (see also [AHPT21, Proposition 3.2] and Definition 2.28). Then its \mathbf{m} -a.e. pointwise Hilbert-Schmidt norm $|g|_{\text{HS}}$ is equal to \sqrt{n} .

Let us introduce a special restricted class of $\text{RCD}(K, N)$ spaces introduced in [DG18] by De Philippis-Gigli as a synthetic counterpart of volume non-collapsed Gromov-Hausdorff limit spaces of Riemannian manifolds with a constant dimension and a lower Ricci curvature bound. The definition is simple: an $\text{RCD}(K, N)$

space is said to be non-collapsed if the reference measure \mathbf{m} is \mathcal{H}^N . It can be easily shown that in this case N must be an integer. Non-collapsed $\text{RCD}(K, N)$ spaces have nicer properties than general $\text{RCD}(K, N)$ spaces. See also for instance [ABS19, KM21].

Note that for any $\text{RCD}(K, N)$ space $(X, \mathbf{d}, \mathbf{m})$, it also admits the heat flow semigroup $\{h_t\}_{t>0}$, which gives the solution to the following equation.

$$\frac{d}{dt}h_t(f) = \Delta h_t f \quad \text{in } L^2(\mathbf{m}), \quad \forall f \in L^2(\mathbf{m}).$$

Thanks to works by Sturm [St95, St96] and by Jiang-Li-Zhang [JLZ16], the heat kernel on $(X, \mathbf{d}, \mathbf{m})$ has a locally Lipschitz representative ρ with Gaussian estimates (see Theorem 2.8). This allows us to construct Φ_t analogously as

$$\begin{aligned} \Phi_t : X &\longrightarrow L^2(\mathbf{m}) \\ x &\longmapsto (y \longmapsto \rho(x, y, t)), \end{aligned}$$

which also naturally induces the pull back metric $g_t := \Phi_t^*(g_{L^2(\mathbf{m})})$.

One can also generalize formula (1.2) to this setting with the L_{loc}^p convergence as follows, which plays a key role in proving equivalence between weakly non-collapsed $\text{RCD}(K, N)$ spaces and non-collapsed $\text{RCD}(K, N)$ spaces. See [AHPT21, Theorem 5.10] and [BGHZ23, Theorem 3.11] for the proof.

Theorem 1.1. *Let $(X, \mathbf{d}, \mathbf{m})$ be an $\text{RCD}(K, N)$ space with $\dim_{\mathbf{d}, \mathbf{m}}(X) = n$, then for any $p \in [1, \infty)$ and any bounded Borel set $A \subset X$, we have the following convergence in $L^p(A, \mathbf{m})$:*

$$|\text{tm}(B_{\sqrt{t}}(\cdot))g_t - c(n)g|_{\text{HS}} \rightarrow 0, \quad \text{as } t \downarrow 0,$$

where $c(n)$ is a constant depending only on n .

1.3 Isometric immersions on Riemannian manifolds

Let (M^n, g) be an n -dimensional closed, that is, compact without boundary, Riemannian manifold. A map

$$\begin{aligned} F : M^n &\longrightarrow \mathbb{R}^m \\ p &\longmapsto (\phi_1(p), \dots, \phi_m(p)) \end{aligned}$$

is said to be an *isometrically immersing eigenmap* if each ϕ_i is a non-constant eigenfunction of $-\Delta$ and F is an isometric immersion in the following sense:

$$F^*g_{\mathbb{R}^m} = \sum_{i=1}^m d\phi_i \otimes d\phi_i = g. \quad (1.1)$$

Let us recall a theorem of Takahashi in [Ta66] as follows: if (M^n, g) is additionally homogeneous and irreducible, then for any eigenspace V corresponding to some non-zero eigenvalue of $-\Delta$, there exists an $L^2(\text{vol}_g)$ -orthogonal basis $\{\phi_i\}_{i=1}^m$ ($m = \dim(V)$) of V realizing (1.1).

Besides, (M^n, g) can be also smoothly embedded into an infinite dimensional Hilbert space by using its heat kernel $\rho : M^n \times M^n \times (0, \infty) \rightarrow (0, \infty)$. More precisely, Bérard and Bérard-Besson-Gallot [B85, BBG94] proved that the following map, which is called *the t -time heat kernel mapping* in this thesis,

$$\begin{aligned} \Phi_t : M^n &\longrightarrow L^2(\text{vol}_g) \\ x &\longmapsto (y \longmapsto \rho(x, y, t)), \end{aligned}$$

is a smooth embedding. Moreover, one can use Φ_t to pull-back the flat Riemannian metric g_{L^2} on $L^2(\text{vol}_g)$ to get a metric tensor $g_t := \Phi_t^*(g_{L^2})$ with the following asymptotic formula (compare Theorem 1.1):

$$4(8\pi)^{\frac{n}{2}} t^{\frac{n+2}{2}} g_t = g - \frac{2t}{3} \left(\text{Ric}_g - \frac{1}{2} \text{Scal}_g g \right) + O(t^2), \quad t \downarrow 0. \quad (1.2)$$

Again when (M^n, g) is additionally homogeneous and irreducible, it again follows from Takahashi's theorem that there exists a non-negative function $c(t)$ such that for all $t > 0$, $\sqrt{c(t)}\Phi_t$ is an isometric immersion.

The observations above lead us to ask the following two questions.

Question 1.2. *How to characterize a manifold admitting an isometrically immersing eigenmap?*

Question 1.3. *How to characterize a manifold such that each t -time heat kernel mapping is an isometric immersion after a normalization?*

Note that if each t -time heat kernel mapping of a closed Riemannian manifold (M^n, g) is an isometric immersion after a normalization, then (M^n, g) admits an isometrically immersing eigenmap. Standard spectral theory of elliptic operators implies that there exists an orthonormal basis $\{\varphi_i\}_{i=1}^\infty$ in $L^2(\text{vol}_g)$ such that each φ_i is an eigenfunction of $-\Delta$ with corresponding eigenvalue λ_i , and that $\{\lambda_i\}_{i=1}^\infty$ satisfies

$$0 = \lambda_0 < \lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_i \rightarrow \infty.$$

Then the classical estimates for eigenvalues λ_i show that

$$g = c(t)g_t = c(t) \sum_{i=1}^{\infty} e^{-2\lambda_i t} d\varphi_i \otimes d\varphi_i, \quad \forall t > 0. \quad (1.3)$$

These estimates also allow us to let $t \rightarrow \infty$ in (1.3) to get (1.1) with $\phi_i = \lim_{t \rightarrow \infty} c(t)e^{-\lambda_1 t} \varphi_i$ ($i = 1, \dots, m$), where m is the dimension of the eigenspace corresponding to λ_1 .

The main purposes of the thesis are to give positive answers to the both questions above in the setting of $\text{RCD}(K, N)$ metric measure spaces.

1.4 Harmonic manifolds

In n -dimensional Euclidean space \mathbb{R}^n , there exist harmonic functions which only depend on the geodesic distance. For instance when $n > 2$, the function $f(x_1, \dots, x_n) = (x_1^2 + \dots + x_n^2)^{1-n/2}$ is harmonic on $\mathbb{R}^n \setminus \{0\}$. In regard to this fact, Ruse attempted to find harmonic functions on Riemannian manifolds with the same property and introduced the notion of harmonic manifold in 1930. His consideration gave the first historical definition of harmonic manifold as follows.

Definition 1.4. A Riemannian manifold (M^n, g) is said to be harmonic if its volume density function $\theta_p := \sqrt{|\det g_{ij}|}$ at each point p is a radial function.

Nowadays many equivalent definitions exist. See [B78, DR92, W50] as follows.

Theorem 1.5. *A complete n -dimensional Riemannian manifold (M^n, g) is harmonic if and only if either of the following condition holds.*

- (1) *For any point $p \in M^n$ and the distance function $d_p := \mathbf{d}_g(p, \cdot)$, Δd_p^2 is radial for any small $r > 0$.*
- (2) *For any $p \in M^n$ there exists a nonconstant radial harmonic function in a punctured neighborhood of p .*
- (3) *Every small geodesic sphere in M^n has constant mean curvature.*
- (4) *Every harmonic function satisfies the mean value property.*

When the space is connected and simply connected, there are many interesting characterizations about harmonic manifolds.

Theorem 1.6 ([CH11, Theorem 3], [CH12, Theorem 1]). *A connected, simply connected and complete Riemannian manifold is harmonic if and only if the volume of the intersection of two geodesic balls depends only on the distance between the centers and the radii of the balls.*

Theorem 1.7 ([S90, Theorem 1.1]). *A connected, simply connected and complete Riemannian manifold (M^n, g) is harmonic if and only if the heat kernel $\rho(x, y, t)$ is a function only of t and the distance $\mathbf{d}_g(x, y)$, i.e., it is of the form $\rho(x, y, t) = \rho(\mathbf{d}_g(x, y), t)$.*

Given a Riemannian manifold (M^n, g) , if H_i ($i = 1, 2$) are two functions on $M^n \times M^n$ such that for any $x \in M^n$ the functions $H_i^x(\cdot) := H_i(x, \cdot)$ ($i = 1, 2$) are L^2 -integrable functions, then their convolution $H_1 * H_2 : M^n \times M^n \rightarrow \mathbb{R}$ is defined by

$$H_1 * H_2(x, y) = \int_{M^n} H_1(x, z)H_2(y, z)d\text{vol}_g(z).$$

A function $H : M^n \times M^n \rightarrow \mathbb{R}$ is called radial kernel if $H(x, y)$ depends only on the geodesic distance between x and y , that is, if $H = h \circ d_g$, where $h : \mathbb{R}^+ \rightarrow \mathbb{R}$ is an arbitrary function.

Theorem 1.8 ([S90, Proposition 2.1]). *A connected, simply connected and complete Riemannian manifold is harmonic if and only if the convolution of the radial kernel functions $H_1 = h_1 \circ d_g$ and $H_2 = h_2 \circ d_g$ is a radial kernel function whenever h_1, h_2 are smooth functions on \mathbb{R}_+ with compact support.*

It should be emphasized that compact connected, simply connected harmonic manifolds are also good examples of IHKI spaces due to Remark 5.2.

As in the previous section, it is also natural to ask the following question.

Question 1.9. *How to characterize an $\text{RCD}(K, N)$ space satisfying the conditions in Theorem 1.6-1.8?*

1.5 Contributions

1.5.1 Isometrically heat kernel immersing $\text{RCD}(K, N)$ spaces

In connection with Question 1.3 in this setting, let us provide the following definition.

Definition 1.10 (Isometrically heat kernel immersing $\text{RCD}(K, N)$ spaces). An $\text{RCD}(K, N)$ space (X, d, \mathbf{m}) is said to be an *isometrically heat kernel immersing* space, or briefly an IHKI space if there exists a non-negative function $c(t)$, such that $\sqrt{c(t)}\Phi_t$ is an isometric immersion for all $t > 0$, namely

$$c(t)g_t = \left(\sqrt{c(t)}\Phi_t \right)^* (g_{L^2(\mathbf{m})}) = g, \quad \forall t > 0.$$

The simplest example of IHKI spaces are Euclidean spaces. On \mathbb{R}^n , it is obvious that

$$g_t^{\mathbb{R}^n} = \frac{c_1^{\mathbb{R}^n}}{t^{\frac{n+2}{2}}} g_{\mathbb{R}^n}, \quad \text{with } c_1^{\mathbb{R}^n} = \int_{\mathbb{R}^n} \left(\frac{\partial}{\partial x_1} \rho^{\mathbb{R}^n}(x, y, t) \right)^2 d\mathcal{L}^n(y). \quad (1.4)$$

Let us introduce the first main result of this thesis.

Theorem 1.11. *Let $(X, \mathbf{d}, \mathbf{m})$ be an $\text{RCD}(K, N)$ space. Then the following two conditions are equivalent.*

- (1) *There exist sequences $\{t_i\} \subset \mathbb{R}$ and $\{s_i\} \subset \mathbb{R}$ such that $t_i \rightarrow t_0$ for some $t_0 > 0$ and that $s_i \Phi_{t_i}$ is an isometric immersion for any i .*
- (2) *$(X, \mathbf{d}, \mathbf{m})$ is an IHKI $\text{RCD}(K, N)$ space.*

Remark 1.12. Theorem 1.11 is sharp in the following sense: there exists a closed Riemannian manifold (M^n, g) such that it is not IHKI and that $c\Phi_{t_0}$ is an isometric immersion for some $c > 0$ and some $t_0 > 0$. See Example 7.3.

Recalling that g_t plays a role of a “regularization” of an $\text{RCD}(K, N)$ space as discussed in [BGHZ23], it is expected that IHKI $\text{RCD}(K, N)$ spaces have nice regularity properties. Along this, we end this subsection by collecting such regularity results as follows.

Theorem 1.13. *Let $(X, \mathbf{d}, \mathbf{m})$ be an IHKI $\text{RCD}(K, N)$ space with $\dim_{\mathbf{d}, \mathbf{m}}(X) = n \geq 1$, then there exists $c > 0$ such that $\mathbf{m} = c\mathcal{H}^n$ and that $(X, \mathbf{d}, \mathbf{m})$ is an $\text{RCD}(K, n)$ space. In particular, $(X, \mathbf{d}, \mathcal{H}^n)$ is a non-collapsed $\text{RCD}(K, n)$ space.*

Theorem 1.14. *Assume that $(X, \mathbf{d}, \mathbf{m})$ is a non-compact IHKI $\text{RCD}(0, N)$ space with $\dim_{\mathbf{d}, \mathbf{m}}(X) = n \geq 2$, then $(X, \mathbf{d}, \mathbf{m})$ is isometric to $(\mathbb{R}^n, \mathbf{d}_{\mathbb{R}^n}, c\mathcal{H}^n)$ for some $c > 0$.*

Let us emphasize that in the compact setting we will be able to provide the best regularity result, namely the smoothness result (see Theorem 1.16 and Corollary 1.18).

1.5.2 Isometrically immersing eigenmaps on $\text{RCD}(K, N)$ spaces

In order to discuss a finite dimensional analogue of the IHKI condition, let us recall the following definition.

Definition 1.15 (Isometric immersion [H21, Definition 3.1]). Let $m \in \mathbb{N}_+$ and let $(X, \mathbf{d}, \mathbf{m})$ be an $\text{RCD}(K, N)$ space. A map

$$\begin{aligned} \Phi : X &\longrightarrow \mathbb{R}^m \\ x &\longmapsto (\phi_1(x), \dots, \phi_m(x)) \end{aligned}$$

is said to be an *isometric immersion* if it is locally Lipschitz and

$$\Phi^* g_{\mathbb{R}^m} := \sum_{i=1}^m d\phi_i \otimes d\phi_i = g \tag{1.5}$$

We are now ready to give an answer to Question 1.2 in the nonsmooth setting.

Theorem 1.16. *Let $(X, \mathbf{d}, \mathcal{H}^n)$ be a compact non-collapsed $\text{RCD}(K, n)$ space. If there exists an isometric immersion*

$$\begin{aligned}\Phi : X &\longrightarrow \mathbb{R}^m \\ x &\longmapsto (\phi_1(x), \dots, \phi_m(x))\end{aligned}$$

such that each ϕ_i is an eigenfunction of $-\Delta$ ($i = 1, \dots, m$), then (X, \mathbf{d}) is isometric to an n -dimensional smooth closed Riemannian manifold (M^n, g) .

It is emphasized again that the theorem above greatly improves a bi-Lipschitz regularity result proved in [H21] and seems to provide the smoothness for a much wider class of RCD spaces than existing results as far as the author knows (see for instance [K15b, GR18, MW19] for the special cases).

Remark 1.17. An isometrically immersing eigenmap may not be an embedding in general. See for instance [L81, Theorem 5].

As a corollary of Theorem 1.16, we obtain the following result, meaning that any compact IHKI $\text{RCD}(K, N)$ space must be smooth.

Corollary 1.18. *Let $(X, \mathbf{d}, \mathcal{H}^n)$ be a compact non-collapsed IHKI $\text{RCD}(K, n)$ space. Let E be the eigenspace with some non-zero corresponding eigenvalue λ of $-\Delta$. Then by taking $\{\phi_i\}_{i=1}^m$ ($m = \dim(E)$) as an $L^2(\mathbf{m})$ -orthonormal basis of E , the map*

$$\begin{aligned}\Phi : X &\longrightarrow \mathbb{R}^m \\ x &\longmapsto \sqrt{\frac{\mathcal{H}^n(X)}{m}}(\phi_1, \dots, \phi_m),\end{aligned}$$

satisfies that

$$\Phi(X) \subset \mathbb{S}^{m-1} \quad \text{and} \quad n\Phi^*g_{\mathbb{R}^m} = \lambda g.$$

In particular, (X, \mathbf{d}) is isometric to an n -dimensional smooth closed Riemannian manifold (M^n, g) .

1.5.3 Harmonic $\text{RCD}(K, N)$ spaces

In order to answer Question 1.9, we consider the following special class of $\text{RCD}(K, N)$ spaces.

Definition 1.19 (Strongly harmonic $\text{RCD}(K, N)$ space). A metric measure space $(X, \mathbf{d}, \mathbf{m})$ is said to be a *strongly harmonic* $\text{RCD}(K, N)$ space if it satisfies the following two conditions.

1. It is an $\text{RCD}(K, N)$ space.

2. There exists a real valued function $H : [0, \infty) \times [0, \infty) \rightarrow \mathbb{R}$ such that the heat kernel ρ of $(X, \mathbf{d}, \mathbf{m})$ satisfies

$$\rho(x, y, t) = H(\mathbf{d}(x, y), t), \quad \forall x, y \in X, \quad \forall t > 0. \quad (1.6)$$

Similar to IHKI $\text{RCD}(K, N)$ spaces, the condition of strong harmonicity also carries nice regularity and rigidity properties. Firstly we have

Theorem 1.20. *Let $(X, \mathbf{d}, \mathbf{m})$ be a strongly harmonic $\text{RCD}(K, N)$ space with $\dim_{\mathbf{d}, \mathbf{m}}(X) = n$. Then $\mathbf{m} = c\mathcal{H}^n$ for some constant $c > 0$ and $(X, \mathbf{d}, \mathcal{H}^n)$ is a non-collapsed $\text{RCD}(K, n)$ space.*

In order to get the smoothness of a strongly harmonic $\text{RCD}(K, N)$ space, a weaker condition is stated as follows.

Definition 1.21 (Radically symmetric $\text{RCD}(K, N)$ space). A metric measure space $(X, \mathbf{d}, \mathbf{m})$ is said to be a *radically symmetric* $\text{RCD}(K, N)$ space if it satisfies the following conditions.

1. It is an $\text{RCD}(K, N)$ space.
2. There exists a real valued function $F : [0, \infty) \times [0, \infty) \rightarrow \mathbb{R}$ and non-constant eigenfunctions $\{\phi_i\}_{i=1}^m$ such that

$$\sum_{i=1}^m \phi_i(x)\phi_i(y) = F(\mathbf{d}(x, y)), \quad \forall x, y \in X. \quad (1.7)$$

Theorem 1.22. *Let $(X, \mathbf{d}, \mathcal{H}^n)$ be a compact non-collapsed radically symmetric $\text{RCD}(K, n)$ space. Then (X, \mathbf{d}) is isometric to an n -dimensional smooth closed Riemannian manifold (M^n, g) .*

Corollary 1.23. *Assume $(X, \mathbf{d}, \mathbf{m})$ is a compact strongly harmonic $\text{RCD}(K, n)$ space with $\dim_{\mathbf{d}, \mathbf{m}}(X) = n$. Then (X, \mathbf{d}) is isometric to an n -dimensional smooth closed Riemannian manifold (M^n, g) .*

Finally, we also obtain a similar result for strongly harmonic $\text{RCD}(0, N)$ spaces to Theorem 1.13 as follows.

Theorem 1.24. *Let $(X, \mathbf{d}, \mathbf{m})$ be a non-compact harmonic $\text{RCD}(0, N)$ space with $\dim_{\mathbf{d}, \mathbf{m}}(X) = n$, then (X, \mathbf{d}) is isometric to $(\mathbb{R}^n, \mathbf{d}_{\mathbb{R}^n})$.*

1.5.4 Diffeomorphic finiteness theorems

As an application of Theorem 1.16, in Section 6 we first study some special isometry classes of closed Riemannian manifolds admitting isometrically immersing τ -eigenmaps.

Definition 1.25 (Isometrically immersing τ -eigenmap on Riemannian manifolds). Let (M^n, g) be an n -dimensional closed Riemannian manifold and let $\tau > 0$. A map

$$F : M^n \longrightarrow \mathbb{R}^m \\ p \longmapsto (\phi_1(p), \dots, \phi_m(p)),$$

is said to be a τ -eigenmap into \mathbb{R}^m if each ϕ_i is a non-constant eigenfunction of $-\Delta$ and

$$\min_{1 \leq i \leq m} \|\phi_i\|_{L^2(\text{vol}_g)} \geq \tau.$$

If in addition F is an isometric immersion, then it is said to be an *isometrically immersing τ -eigenmap into \mathbb{R}^m* .

Definition 1.26 (Isometric immersion via τ -eigenmaps). For all $K \in \mathbb{R}$, $D, \tau > 0$, denote by $\mathcal{M}(K, n, D, \tau)$ the set of isometry classes of n -dimensional closed Riemannian manifolds (M^n, g) such that the Ricci curvature is bounded below by K , that the diameter is bounded above by D and that there exists an isometrically immersing τ -eigenmap into \mathbb{R}^m for some $m \in \mathbb{N}$.

Our main result about $\mathcal{M}(K, n, D, \tau)$ is stated as follows.

Theorem 1.27. $\mathcal{M}(K, n, D, \tau)$ is compact in C^∞ -topology. That is, for any sequence of Riemannian manifolds $\{(M_i^n, g_i)\} \subset \mathcal{M}(K, n, D, \tau)$, after passing to a subsequence, there exists a Riemannian manifold $(M^n, g) \in \mathcal{M}(K, n, D, \tau)$ and diffeomorphisms $\psi_i : M^n \rightarrow M_i^n$, such that $\{\psi_i^* g_i\}$ C^k -converges to g on (M^n, g) for any $k \in \mathbb{N}$.

Finally in order to introduce an improved finiteness result from [H21], let us introduce the following definition.

Definition 1.28 (Almost isometric immersion via τ -eigenmap). For all $K \in \mathbb{R}$, $D, \tau > 0$, $\epsilon \geq 0$, denote by $\mathcal{N}(K, n, D, \tau, \epsilon)$ the set of isometry classes of n -dimensional closed Riemannian manifolds (M^n, g) such that the Ricci curvature is bounded below by K , that the diameter is bounded above by D and that there exists a τ -eigenmap F_{M^n} into \mathbb{R}^m for some $m \in \mathbb{N}$ with

$$\frac{1}{\text{vol}_g(M^n)} \int_{M^n} |F_{M^n}^* g_{\mathbb{R}^m} - g| \, \text{dvol}_g \leq \epsilon.$$

Note that $\mathcal{N}(K, n, D, \tau, 0) = \mathcal{M}(K, n, D, \tau)$. Combining the intrinsic Reifenberg method established in [ChCo1, Appendix A] by Cheeger-Colding, with Theorem 1.16 gives us the following diffeomorphic finiteness theorem.

Theorem 1.29. *There exists $\epsilon = \epsilon(K, n, D, \tau) > 0$ such that $\mathcal{N}(K, n, D, \tau, \epsilon)$ has finitely many members up to diffeomorphism.*

1.6 Outline of the proofs

The proofs of Theorems 1.13, 1.14, 1.20 and 1.24 are based on blow up and blow down arguments. See also the proofs of [AHPT21, Theorem 2.19] and [BGHZ23, Theorem 3.11] for related arguments.

The most delicate part of this thesis is in the proofs of Theorems 1.16 and 1.22, which make the full use of the equations for eigenfunctions, i.e. $\Delta\phi_i = -\mu_i\phi_i$ ($i = 1, \dots, m$). Note that one can easily obtain L^∞ -bounds of the Laplacian and of the gradient of each ϕ_i from the estimates in [J14, JLZ16, ZZ19, AHPT21] (see also Proposition 2.10).

In order to explain it more precisely, let us start with the following key equation:

$$\sum_{i=1}^m |\nabla\phi_i|^2 = n. \quad (1.8)$$

Since the lower bound of each $\Delta|\nabla\phi_i|^2$ comes directly from Bochner inequality (see (2.1)), (1.8) then guarantees the upper bound of each $\Delta|\nabla\phi_i|^2$ due to the following equality:

$$\Delta|\nabla\phi_i|^2 = \sum_{j \neq i}^m -\Delta|\nabla\phi_j|^2.$$

Therefore we have a uniform L^∞ -bound of all $|\nabla\langle\nabla\phi_i, \nabla\phi_j\rangle|$, which implies the $C^{1,1}$ differentiable structure of the space. Indeed, locally one can pick $\{u_i\}_{i=1}^m$ consisting of linear combinations of eigenfunctions ϕ_i and construct a bi-Lipschitz map $x \mapsto (u_1(x), \dots, u_n(x))$ which satisfies the following PDE:

$$\sum_{j,k=1}^m \langle \nabla u_j, \nabla u_k \rangle \frac{\partial^2 \phi_i}{\partial u_j \partial u_k} + \sum_{j=1}^n \Delta u_j \frac{\partial \phi_i}{\partial u_j} + \mu_i \phi_i = 0.$$

Then the smoothness of the space is justified by applying the elliptic regularity theory.

Finally, a similar technique as in the proof of Theorem 1.16 allows us to control each higher order covariant derivative of the Riemannian metric g of $(M^n, g) \in \mathcal{M}$ quantitatively. Thus we can then apply a theorem of Hebey-Herzlish proved in [HH97] to get the desired smooth compactness result, Theorem 1.27.

2 Notation and preliminary results

Throughout this thesis we will use standard notation in this topic. For example

- Denote by $C(K_1, \dots, K_n)$ a positive constant depending on K_1, \dots, K_n , and $\Psi = \Psi(\epsilon_1, \dots, \epsilon_k | c_1, \dots, c_j)$ some nonnegative function determined by $\epsilon_1, \dots, \epsilon_k, c_1, \dots, c_j$ such that

$$\lim_{\epsilon_1, \dots, \epsilon_k \rightarrow 0} \Psi = 0, \text{ for any fixed } c_1, \dots, c_j.$$

- Denote by ω_n the n -dimensional Hausdorff measure of the unit ball in \mathbb{R}^n which coincides with the usual volume of a unit ball in \mathbb{R}^n , and by \mathcal{L}^n the standard Lebesgue measure on \mathbb{R}^n .

We may use superscripts or subscripts when it is necessary to distinguish objects (for example, the Riemannian metrics, the gradients, etc.) on different spaces in this thesis.

2.1 Metric spaces

We fix some basic definitions and notation about metric spaces in this subsection. Let (X, \mathbf{d}) be a complete separable metric space.

Denote by $\text{Lip}(X, \mathbf{d})$ (resp. $\text{Lip}_b(X, \mathbf{d})$, $\text{Lip}_c(X, \mathbf{d})$, $C(X)$, $C_c(X)$) the set of all Lipschitz functions (resp. bounded Lipschitz functions, compactly supported Lipschitz functions, continuous functions, compactly supported continuous functions) on (X, \mathbf{d}) .

For any $f \in \text{Lip}(X, \mathbf{d})$, the local Lipschitz constant of f at a point $x \in X$ is defined by

$$\text{lip } f(x) = \begin{cases} \limsup_{y \rightarrow x} \frac{|f(y) - f(x)|}{\mathbf{d}(y, x)} & \text{if } x \in X \text{ is not isolated,} \\ 0 & \text{otherwise.} \end{cases}$$

If (X, \mathbf{d}) is compact, then the diameter of X is defined by

$$\text{diam}(X, \mathbf{d}) := \sup_{x, y \in X} \mathbf{d}(x, y).$$

For a map $f : X \rightarrow Y$ from (X, \mathbf{d}) to another complete metric space (Y, \mathbf{d}_Y) , f is said to be C -bi-Lipschitz from X to $f(X)$ for some $C \geq 1$ if

$$C^{-1} \mathbf{d}(x_1, x_2) \leq \mathbf{d}_Y(f(x_1), f(x_2)) \leq C \mathbf{d}(x_1, x_2), \quad \forall x_1, x_2 \in X.$$

We also denote by $B_R(x)$ the set $\{y \in X : \mathbf{d}(x, y) < R\}$, and by $B_\epsilon(A)$ the set $\{x \in X : \mathbf{d}(x, A) < \epsilon\}$ for any $A \subset X$, $\epsilon > 0$. In particular, denote by $B_r(0_n) := \{x \in \mathbb{R}^n : |x| < r\}$ for any $r > 0$.

2.2 RCD(K, N) spaces: definition and basic properties

Let $(X, \mathbf{d}, \mathbf{m})$ be a metric measure space.

Definition 2.1 (Cheeger energy). The Cheeger energy $\text{Ch}: L^2(\mathbf{m}) \rightarrow [0, \infty]$ is defined by

$$\text{Ch}(f) := \inf_{\{f_i\}} \left\{ \liminf_{i \rightarrow \infty} \int_X |\text{lip } f_i|^2 \, \mathbf{d}\mathbf{m} \right\},$$

where the infimum is taken among all sequences $\{f_i\}$ satisfying $f_i \in \text{Lip}_b(X, \mathbf{d}) \cap L^2(\mathbf{m})$ and $\|f_i - f\|_{L^2(\mathbf{m})} \rightarrow 0$.

The domain of the Cheeger energy, denoted by $D(\text{Ch})$, is the set of all $f \in L^2(\mathbf{m})$ with $\text{Ch}(f) < \infty$. It is dense in $L^2(\mathbf{m})$, and is a Banach space when equipped with the norm $\sqrt{\text{Ch}(\cdot) + \|\cdot\|_{L^2(\mathbf{m})}^2}$. This Banach space is the Sobolev space $H^{1,2}(X, \mathbf{d}, \mathbf{m})$. In addition, for any $f \in H^{1,2}(X, \mathbf{d}, \mathbf{m})$, by taking a minimizing sequence $\{f_i\}$ and using Mazur's lemma, one can identify a unique $|Df| \in L^2(\mathbf{m})$ such that

$$\text{Ch}(f) = \int_X |Df|^2 \, \mathbf{d}\mathbf{m}.$$

This $|Df|$ is called the minimal relaxed slope of f and satisfies the locality property, that is, for any other $h \in H^{1,2}(X, \mathbf{d}, \mathbf{m})$, we have $|Df| = |Dh|$ \mathbf{m} -a.e. on $\{x \in X : f = h\}$.

In particular, $(X, \mathbf{d}, \mathbf{m})$ is said to be infinitesimally Hilbertian if $H^{1,2}(X, \mathbf{d}, \mathbf{m})$ is a Hilbert space. In this case, for any $f, h \in H^{1,2}(X, \mathbf{d}, \mathbf{m})$, the following $L^1(\mathbf{m})$ integrable function is well-defined [AGS14b]:

$$\langle \nabla f, \nabla h \rangle := \lim_{\epsilon \rightarrow 0} \frac{|D(f + \epsilon h)|^2 - |Df|^2}{2\epsilon}.$$

Remark 2.2. For any $f \in H^{1,2}(X, \mathbf{d}, \mathbf{m})$, it is clear that

$$|\nabla f|^2 := \langle \nabla f, \nabla f \rangle = |Df|^2, \quad \mathbf{m}\text{-a.e.}$$

Definition 2.3 (The Laplacian [G15]). Assume that $(X, \mathbf{d}, \mathbf{m})$ is infinitesimally Hilbertian. The domain of Laplacian, namely $D(\Delta)$, is defined as the set of all $f \in H^{1,2}(X, \mathbf{d}, \mathbf{m})$ such that

$$\int_X \langle \nabla f, \nabla \varphi \rangle \, \mathbf{d}\mathbf{m} = - \int_X h \varphi \, \mathbf{d}\mathbf{m}, \quad \forall \varphi \in H^{1,2}(X, \mathbf{d}, \mathbf{m}),$$

for some $h \in L^2(\mathbf{m})$. In particular, denote by $\Delta f := h$ for any $f \in D(\Delta)$ because h is unique if it exists.

We are now ready to introduce the definition of $\text{RCD}(K, N)$ spaces. The following is an equivalent definition with the one proposed in [G15], and the equivalence is proved in [AGS15, EKS15]. See also [AMS19].

Definition 2.4. Let $K \in \mathbb{R}$ and $N \in [1, \infty)$. $(X, \mathbf{d}, \mathbf{m})$ is said to be an $\text{RCD}(K, N)$ space if and only if it satisfies the following conditions.

1. $(X, \mathbf{d}, \mathbf{m})$ is infinitesimally Hilbertian.
2. There exists $x \in X$ and $C > 0$, such that for any $r > 0$, $\mathbf{m}(B_r(x)) \leq Ce^{Cr^2}$.
3. (Sobolev to Lipschitz property) If $f \in H^{1,2}(X, \mathbf{d}, \mathbf{m})$ with $|\mathbf{D}f| \leq 1$ \mathbf{m} -a.e., then f has a 1-Lipschitz representative, that is, there exists a 1-Lipschitz function h such that $h = f$ \mathbf{m} -a.e.
4. (Bochner inequality) For any $f \in D(\Delta)$ with $\Delta f \in H^{1,2}(X, \mathbf{d}, \mathbf{m})$, the following holds for any $\varphi \in \text{Test}^F(X, \mathbf{d}, \mathbf{m})$ with $\varphi \geq 0$,

$$\frac{1}{2} \int_X |\nabla f|^2 \Delta \varphi \, \mathbf{d}\mathbf{m} \geq \int_X \varphi \left(\langle \nabla f, \nabla \Delta f \rangle + K |\nabla f|^2 + \frac{(\Delta f)^2}{N} \right) \, \mathbf{d}\mathbf{m}, \quad (2.1)$$

where $\text{Test}^F(X, \mathbf{d}, \mathbf{m})$ is the class of test functions defined by

$$\text{Test}^F(X, \mathbf{d}, \mathbf{m}) := \{f \in \text{Lip}(X, \mathbf{d}) \cap D(\Delta) \cap L^\infty(\mathbf{m}) : \Delta f \in H^{1,2}(X, \mathbf{d}, \mathbf{m}) \cap L^\infty(\mathbf{m})\}.$$

If in addition $\mathbf{m} = \mathcal{H}^N$, then $(X, \mathbf{d}, \mathbf{m})$ is said to be a non-collapsed $\text{RCD}(K, N)$ space.

For the class of test functions on an $\text{RCD}(K, N)$ space $(X, \mathbf{d}, \mathbf{m})$, by [S14],

1. $|\nabla f|^2 \in H^{1,2}(X, \mathbf{d}, \mathbf{m})$ for any $f \in \text{Test}^F(X, \mathbf{d}, \mathbf{m})$.
2. Define $\text{Test}^F_+(X, \mathbf{d}, \mathbf{m}) := \{f \in \text{Test}^F(X, \mathbf{d}, \mathbf{m}) : f \geq 0\}$ and $H_+^{1,2}(X, \mathbf{d}, \mathbf{m}) := \{f \in H^{1,2}(X, \mathbf{d}, \mathbf{m}) : f \geq 0 \text{ } \mathbf{m}\text{-a.e.}\}$. Then $\text{Test}^F_+(X, \mathbf{d}, \mathbf{m})$ (resp. $\text{Test}^F(X, \mathbf{d}, \mathbf{m})$) is dense in $H_+^{1,2}(X, \mathbf{d}, \mathbf{m})$ (resp. $H^{1,2}(X, \mathbf{d}, \mathbf{m})$).

The following inequality is a generalization of the Bishop-Gromov inequality in Riemannian geometry.

Theorem 2.5 (Bishop-Gromov inequality [LV09, St06b]). *Assume that $(X, \mathbf{d}, \mathbf{m})$ is an $\text{RCD}(K, N)$ space. Then the following holds for any $x \in X$.*

1. If $N > 1$, $K \neq 0$, $r < R \leq \pi \sqrt{\frac{N-1}{K \vee 0}}$, then $\frac{\mathbf{m}(B_R(x))}{\mathbf{m}(B_r(x))} \leq \frac{\int_0^R V_{K,N} dt}{\int_0^r V_{K,N} dt}$, where

$$V_{K,N}(t) := \begin{cases} \sin \left(t \sqrt{K/(N-1)} \right)^{N-1}, & \text{if } K > 0, \\ \sinh \left(t \sqrt{-K/(N-1)} \right)^{N-1}, & \text{if } K < 0. \end{cases}$$

2. If $N = 1$ and $K \leq 0$, or $N \in (1, \infty)$ and $K = 0$, then $\frac{\mathbf{m}(B_R(x))}{\mathbf{m}(B_r(x))} \leq \left(\frac{R}{r}\right)^N$.

Remark 2.6. (2.2) and (2.3) are direct consequences of Theorem 2.5, where (2.3) is a combination of (2.2) and the fact that $B_r(x) \subset B_{r+d(x,y)}(y)$.

$$\frac{\mathbf{m}(B_R(x))}{\mathbf{m}(B_r(x))} \leq C(K, N) \exp\left(C(K, N) \frac{R}{r}\right), \quad \forall x \in X, \forall r < R. \quad (2.2)$$

$$\frac{\mathbf{m}(B_r(x))}{\mathbf{m}(B_r(y))} \leq C(K, N) \exp\left(C(K, N) \frac{r + d(x, y)}{r}\right), \quad \forall x, y \in X, \forall r > 0. \quad (2.3)$$

For an $\text{RCD}(K, N)$ space $(X, \mathbf{d}, \mathbf{m})$, the heat flow $\{\mathbf{h}_t : L^2(\mathbf{m}) \rightarrow L^2(\mathbf{m})\}_{t>0}$ associated with its Cheeger energy is defined by: for any $f \in L^2(\mathbf{m})$, $\{\mathbf{h}_t f\}_{t>0}$ satisfies the following properties.

1. (Solution to the heat equation) For any $t > 0$, $\mathbf{h}_t f \in D(\Delta)$ and $\frac{d}{dt} \mathbf{h}_t(f) = \Delta \mathbf{h}_t f$ in $L^2(\mathbf{m})$.
2. (Semigroup property) For any $s, t > 0$, $\mathbf{h}_{t+s} f = \mathbf{h}_t(\mathbf{h}_s f)$.
3. (Contraction on $L^2(\mathbf{m})$) $\|\mathbf{h}_t f\|_{L^2(\mathbf{m})} \leq \|f\|_{L^2(\mathbf{m})}$, $\forall t > 0$.
4. (Commutative with Δ) If $f \in D(\Delta)$, then for any $t > 0$, $\mathbf{h}_t(\Delta f) = \Delta(\mathbf{h}_t f)$.

For any $p \in [1, \infty]$, $\{\mathbf{h}_t\}_{t>0}$ also acts on $L^p(\mathbf{m})$ as a linear family of contractions, namely

$$\|\mathbf{h}_t \varphi\|_{L^p(\mathbf{m})} \leq \|\varphi\|_{L^p(\mathbf{m})}, \quad \forall t > 0, \quad \forall \varphi \in L^p(\mathbf{m}). \quad (2.4)$$

Set $\hat{1} \in L^\infty(\mathbf{m})$ as (the equivalence class in \mathbf{m} -a.e. sense of) the function on X identically equal to 1. It is now worth pointing out the following stochastic completeness of $\text{RCD}(K, N)$ spaces:

$$\mathbf{h}_t(\hat{1}) \equiv \hat{1}, \quad \forall t > 0.$$

Sturm's works [St95, St96] guarantee the existence of a locally Hölder continuous representative ρ on $X \times X \times (0, \infty)$ of the heat kernel for $(X, \mathbf{d}, \mathbf{m})$. More precisely, the solution to the heat equation can be expressed by using ρ as follows:

$$\mathbf{h}_t(f) = \int_X \rho(x, y, t) f(y) d\mathbf{m}(y), \quad \forall f \in L^2(\mathbf{m}).$$

Remark 2.7 (Rescaled RCD space). For any $\text{RCD}(K, N)$ space $(X, \mathbf{d}, \mathbf{m})$ and any $a, b \in (0, \infty)$, the rescaled space $(X, a\mathbf{d}, b\mathbf{m})$ is an $\text{RCD}(a^{-1}K, N)$ space whose heat kernel $\tilde{\rho}$ can be written as $\tilde{\rho}(x, y, t) = b^{-1} \rho(x, y, a^{-2}t)$.

The locally Hölder continuity of the heat kernel on $\text{RCD}(K, N)$ spaces is improved to be locally Lipschitz due to the following Jiang-Li-Zhang's [JLZ16] estimates.

Theorem 2.8. *Let $(X, \mathbf{d}, \mathbf{m})$ be an $\text{RCD}(K, N)$ space. Given any $\epsilon > 0$, there exist positive constants $C_i = C_i(K, N, \epsilon), i = 1, 2, 3, 4$ such that the heat kernel ρ satisfies the following estimates.*

$$\frac{1}{C_1} \exp\left(-\frac{\mathbf{d}^2(x, y)}{(4 - \epsilon)t} - C_2 t\right) \leq \mathbf{m}(B_{\sqrt{t}}(y)) \rho(x, y, t) \leq C_1 \exp\left(-\frac{\mathbf{d}^2(x, y)}{(4 + \epsilon)t} + C_2 t\right)$$

holds for all $t > 0$, and all $x, y \in X$ and

$$|\nabla_x \rho(x, y, t)| \leq \frac{C_3}{\sqrt{t} \mathbf{m}(B_{\sqrt{t}}(x))} \exp\left(-\frac{\mathbf{d}^2(x, y)}{(4 + \epsilon)t} + C_4 t\right)$$

holds for all $t > 0$ and \mathbf{m} -a.e. $x, y \in X$.

Remark 2.9. The results of [D97] are also applicable to $\text{RCD}(K, N)$ spaces. In particular, under the assumption of Theorem 2.8, for any $x, y \in X$, the function $t \mapsto \rho(x, y, t)$ is analytic. Moreover, for any $n \geq 1, t \in (0, 1)$, and $x, y \in X$, the Bishop-Gromov inequality (2.2), Theorem 2.8 and [D97, Theorem 4] give that,

$$\left| \frac{\partial^n}{\partial t^n} \rho(x, y, t) \right| \leq \frac{C(K, N)n!}{t^n} (\mathbf{m}(B_{\sqrt{t}}(x))\mathbf{m}(B_{\sqrt{t}}(y)))^{-\frac{1}{2}} \exp\left(-\frac{\mathbf{d}^2(x, y)}{100t}\right). \quad (2.5)$$

For a compact $\text{RCD}(K, N)$ space $(X, \mathbf{d}, \mathbf{m})$, by [J14, JLZ16], its heat kernel ρ can be expressed as follows, (see also [AHPT21, Appendix]).

$$\rho(x, y, t) = \sum_{i=0}^{\infty} e^{-\mu_i t} \phi_i(x) \phi_i(y), \quad (2.6)$$

where eigenvalues of $-\Delta$ counted with multiplicities and the corresponding eigenfunctions are denoted as follows.

$$\begin{cases} 0 = \mu_0 < \mu_1 \leq \mu_2 \leq \dots \rightarrow +\infty, \\ -\Delta \phi_i = \mu_i \phi_i, \\ \{\phi_i\}_{i \in \mathbb{N}} : \text{an orthonormal basis of } L^2(\mathbf{m}). \end{cases} \quad (2.7)$$

We may use the notation (2.7) in Proposition 2.10, Proposition 2.13 without any attention.

The following estimates can be obtained by the Gaussian estimates (Theorem 2.8) and are useful in this thesis. See [AHPT21, Appendix] and [ZZ19].

Proposition 2.10. *Let $(X, \mathbf{d}, \mathbf{m})$ be a compact $\text{RCD}(K, N)$ space with $\mathbf{m}(X) = 1$, then there exist $C_j = C_j(K, N, \text{diam}(X, \mathbf{d}))$ ($j = 5, 6$), such that for all $i \geq 1$,*

$$\|\phi_i\|_{L^\infty(\mathbf{m})} \leq C_5 \mu_i^{N/4}, \quad \|\|\nabla \phi_i\|\|_{L^\infty(\mathbf{m})} \leq C_5 \mu_i^{(N+2)/4}, \quad C_6 i^{2/N} \leq \mu_i \leq C_5 i^2.$$

The rest of this subsection is based on [GH18, GR20]. We first introduce some basic knowledges of the Euclidean cone over metric measure spaces. Then the background of the product space of metric measure spaces follows.

Definition 2.11 (Euclidean cone as a metric measure space). Let $(X, \mathbf{d}, \mathbf{m})$ be an $\text{RCD}(N-2, N-1)$ space with $N \geq 2$. We define the Euclidean cone over $(X, \mathbf{d}, \mathbf{m})$ as the metric measure space $(\mathbf{C}(X), \mathbf{d}_{\mathbf{C}(X)}, \mathbf{m}_{\mathbf{C}(X)})$ as follows.

1. The space $\mathbf{C}(X)$ is defined as $\mathbf{C}(X) := [0, \infty) \times X / (\{0\} \times X)$. The origin is denoted by o^* .
2. For any two points (r, x) and (s, y) , the distance between them is defined as

$$\mathbf{d}_{\mathbf{C}(X)}((r, x), (s, y)) := \sqrt{r^2 + s^2 - 2rs \cos(\mathbf{d}(x, y))}.$$

3. The measure of $\mathbf{C}(X)$ is defined as $\mathbf{d}\mathbf{m}_{\mathbf{C}(X)}(r, x) = r^{N-1} dr \otimes \mathbf{d}\mathbf{m}(x)$.

Remark 2.12. If $(X, \mathbf{d}, \mathbf{m})$ is an $\text{RCD}(N-2, N-1)$ space, then it has an upper diameter bound π due to [St06b, Corollary 2.6] and [O07, Theorem 4.3]. In addition, by [K15a, Theorem 1.1], $(\mathbf{C}(X), \mathbf{d}_{\mathbf{C}(X)}, \mathbf{m}_{\mathbf{C}(X)})$ is an $\text{RCD}(0, N)$ space if and only if $(X, \mathbf{d}, \mathbf{m})$ is an $\text{RCD}(N-2, N-1)$ space.

By [GH18, Definition 3.8, Proposition 3.12], for any $f \in H^{1,2}(\mathbf{C}(X), \mathbf{d}_{\mathbf{C}(X)}, \mathbf{m}_{\mathbf{C}(X)})$, it holds that

$$(f^{(x)} : r \mapsto f(r, x)) \in H^{1,2}(\mathbb{R}, \mathbf{d}_{\mathbb{R}}, r^{N-1} \mathcal{L}^1), \quad \mathbf{m}\text{-a.e. } x \in X,$$

$$(f^{(r)} : x \mapsto f(r, x)) \in H^{1,2}(X, \mathbf{d}, \mathbf{m}), \quad r^{N-1} \mathcal{L}^1\text{-a.e. } r \in \mathbb{R},$$

and that $|\nabla f|_{\mathbf{C}(X)}^2$ can be written as

$$|\nabla f|_{\mathbf{C}(X)}^2(r, x) = |\nabla f^{(x)}|_{\mathbb{R}}^2(r) + \frac{1}{r^2} |\nabla f^{(r)}|_X^2(x) \quad \mathbf{m}_{\mathbf{C}(X)}\text{-a.e. } (r, x) \in \mathbf{C}(X).$$

Thus for any $f_1, f_2 \in H^{1,2}(\mathbf{C}(X), \mathbf{d}_{\mathbf{C}(X)}, \mathbf{m}_{\mathbf{C}(X)})$, it can be readily checked that for $\mathbf{m}_{\mathbf{C}(X)}\text{-a.e. } (r, x) \in \mathbf{C}(X)$,

$$\langle \nabla f_1, \nabla f_2 \rangle_{\mathbf{C}(X)}(r, x) = \left\langle \nabla f_1^{(x)}, \nabla f_2^{(x)} \right\rangle_{\mathbb{R}}(r) + \frac{1}{r^2} \left\langle \nabla f_1^{(r)}, \nabla f_2^{(r)} \right\rangle_X(x). \quad (2.8)$$

In addition, the heat kernel $\rho^{\mathbf{C}(X)}$ on $(\mathbf{C}(X), \mathbf{d}_{\mathbf{C}(X)}, \mathbf{m}_{\mathbf{C}(X)})$ has the following explicit expression as [D02, Theorem 6.20].

Proposition 2.13. *Let $(X, \mathbf{d}, \mathbf{m})$ be a compact $\text{RCD}(N - 2, N - 1)$ space with $N \geq 3$. Let $\alpha = (2 - N)/2$, $\nu_j = \sqrt{\alpha^2 + \mu_j}$ for $j \in \mathbb{N}$. Then $\rho^{C(X)}$ can be written as follows:*

$$\rho^{C(X)}((r_1, x_1), (r_2, x_2), t) = (r_1 r_2)^\alpha \sum_{j=0}^{\infty} \frac{1}{2t} \exp\left(-\frac{r_1^2 + r_2^2}{4t}\right) I_{\nu_j}\left(\frac{r_1 r_2}{2t}\right) \phi_j(x_1) \phi_j(x_2). \quad (2.9)$$

Here I_ν is a modified Bessel function defined by

$$I_\nu(z) = \sum_{k=0}^{\infty} \frac{1}{k! \Gamma(\nu + k + 1)} \left(\frac{z}{2}\right)^{2k + \nu}. \quad (2.10)$$

Proof. We claim that for any $f \in C_c(C(X))$, by using $\rho^{C(X)}$ defined in (2.9), $\text{h}_t f$ can be expressed as follows.

$$\text{h}_t f(r_1, x_1) = \int_{C(X)} \rho^{C(X)}((r_1, x_1), (r_2, x_2), t) f(r_2, x_2) \mathbf{d}\mathbf{m}_{C(X)}(r_2, x_2). \quad (2.11)$$

Then we are done by combining (2.4) and the fact that $C_c(C(X))$ is dense in $L^2(\mathbf{m}_{C(X)})$.

To show (2.11), we first set $u_i(r) = \int_X f(r, x) \phi_i(x) \mathbf{d}\mathbf{m}(x)$ ($i = 0, 1, \dots$). For any $r \in (0, \infty)$, since $f^{(r)}$ is continuous, by Parseval's identity we have

$$\sum_{i=0}^{\infty} u_i^2(r) = \int_X \sum_{i=0}^{\infty} u_i^2(r) \phi_i^2(x) \mathbf{d}\mathbf{m}(x) = \int_X f^2(r, x) \mathbf{d}\mathbf{m}(x).$$

Letting $f_k(r) := \sum_{i=0}^k r^{N-1} u_i^2(r)$, and using the dominated convergence theorem, we get

$$\lim_{k \rightarrow \infty} \int_{(0, \infty)} f_k(r) \mathbf{d}r = \int_{(0, \infty)} \int_X r^{N-1} f^2(r, x) \mathbf{d}\mathbf{m}(x) \mathbf{d}r.$$

This yields

$$\begin{aligned} & \lim_{k \rightarrow \infty} \int_{C(X)} \left(f(r, x) - \sum_{i=0}^k u_i(r) \phi_i(x) \right)^2 \mathbf{d}\mathbf{m}_{C(X)}(r, x) \\ &= \lim_{k \rightarrow \infty} \left(\int_{(0, \infty)} \int_X r^{N-1} f^2(r, x) \mathbf{d}\mathbf{m}(x) \mathbf{d}r - \int_{(0, \infty)} f_k(r) \mathbf{d}r \right) = 0. \end{aligned}$$

Therefore $f(r, x) = \sum_{i=0}^{\infty} u_i(r) \phi_i(x)$ for $\mathbf{m}_{C(X)}$ -a.e. $(r, x) \in C(X)$. Applying the separation of variables in classical ways like [Ta96, Chapter 8], we complete the proof of (2.11). □

Definition 2.14 (Cartesian product as a metric measure space). Let $(X, \mathbf{d}_X, \mathbf{m}_X)$, $(Y, \mathbf{d}_Y, \mathbf{m}_Y)$ be two metric measure spaces. The product metric measure space $(X \times Y, \mathbf{d}_{X \times Y}, \mathbf{m}_{X \times Y})$ is defined as the product space $X \times Y$ equipped with the distance

$$\mathbf{d}_{X \times Y}((x_1, y_1), (x_2, y_2)) = \sqrt{\mathbf{d}_X^2(x_1, x_2) + \mathbf{d}_Y^2(y_1, y_2)}, \quad \forall (x_1, y_1), (x_2, y_2) \in X \times Y,$$

and the measure $\mathbf{d}\mathbf{m}_{X \times Y} := \mathbf{d}\mathbf{m}_X \otimes \mathbf{d}\mathbf{m}_Y$.

Since [GR20, Proposition 4.1] applies for $\text{RCD}(K, \infty)$ spaces, for any $f \in H^{1,2}(X \times Y, \mathbf{d}_{X \times Y}, \mathbf{m}_{X \times Y})$, it holds that

$$(f^{(x)} : y \mapsto f(x, y)) \in H^{1,2}(Y, \mathbf{d}_Y, \mathbf{m}_Y), \quad \mathbf{m}_X\text{-a.e. } x \in X,$$

$$(f^{(y)} : x \mapsto f(x, y)) \in H^{1,2}(X, \mathbf{d}_X, \mathbf{m}_X), \quad \mathbf{m}_Y\text{-a.e. } y \in Y,$$

and $|\nabla f|_{X \times Y}^2$ can be expressed as

$$|\nabla f|_{X \times Y}^2(x, y) = |\nabla f^{(y)}|_X^2(x) + |\nabla f^{(x)}|_Y^2(y), \quad \mathbf{m}_{X \times Y}\text{-a.e. } (x, y) \in X \times Y. \quad (2.12)$$

Thus for any $f_1, f_2 \in H^{1,2}(X \times Y, \mathbf{d}_{X \times Y}, \mathbf{m}_{X \times Y})$, we have the following for $\mathbf{m}_{X \times Y}$ -a.e. $(x, y) \in X \times Y$:

$$\langle \nabla f_1, \nabla f_2 \rangle_{X \times Y}(x, y) = \langle \nabla f_1^{(y)}, \nabla f_2^{(y)} \rangle_X(x) + \langle \nabla f_1^{(x)}, \nabla f_2^{(x)} \rangle_Y(y). \quad (2.13)$$

It also follows from [GR20, Corollary 4.2] that for any $f \in L^2(\mathbf{m}_{X \times Y})$,

$$\mathbf{h}_t^{X \times Y} f = \mathbf{h}_t^X (\mathbf{h}_t^Y f^{(x)}) = \mathbf{h}_t^Y (\mathbf{h}_t^X f^{(y)}).$$

As a result, $\rho^{X \times Y}$ has an explicit expression as follows.

$$\rho^{X \times Y}((x_1, y_1), (x_2, y_2), t) = \rho^X(x_1, x_2, t) \rho^Y(y_1, y_2, t). \quad (2.14)$$

2.3 First and second order calculus on $\text{RCD}(K, N)$ spaces

This subsection is based on [G18]. We assume that $(X, \mathbf{d}, \mathbf{m})$ is an $\text{RCD}(K, N)$ space in this subsection.

Definition 2.15 (L^p -normed L^∞ -module). For any $p \in [1, \infty]$, a quadruplet $(\mathcal{M}, \|\cdot\|_{\mathcal{M}}, \cdot, |\cdot|)$ is said to be an L^p -normed L^∞ -module if it satisfies the following conditions.

1. The normed vector space $(\mathcal{M}, \|\cdot\|_{\mathcal{M}})$ is a Banach space.

2. The multiplication by L^∞ -functions $\cdot : L^\infty(\mathbf{m}) \times \mathcal{M} \rightarrow \mathcal{M}$ is a bilinear map such that for every $f, h \in L^\infty(\mathbf{m})$ and every $v \in \mathcal{M}$, it holds that

$$f \cdot (h \cdot v) = (fh) \cdot v, \quad \hat{1} \cdot v = v.$$

3. The pointwise norm $|\cdot| : \mathcal{M} \rightarrow L^p(\mathbf{m})$ satisfies that for every $f \in L^\infty(\mathbf{m})$ and every $v \in \mathcal{M}$, it holds that

$$|v| \geq 0, \quad |f \cdot v| = |f||v| \quad \mathbf{m}\text{-a.e.}, \quad \text{and} \quad \|v\|_{\mathcal{M}} = \| |v| \|_{L^p(\mathbf{m})}.$$

In particular, $(\mathcal{M}, \|\cdot\|_{\mathcal{M}}, \cdot, |\cdot|)$ is said briefly to be a module when $p = 2$.

Remark 2.16. The homogeneity and subadditivity of $|\cdot|$ follows directly from Definition 2.15. Write fv instead of $f \cdot v$ later on for simplicity.

To construct the cotangent module, the first step is to define a pre-cotangent module Pcm . Elements of Pcm are of the form $\{(E_i, f_i)\}_{i=1}^n$ where $\{E_i\}_{i=1}^n$ is some Borel partition of X and $\{f_i\}_{i=1}^n \subset H^{1,2}(X, \mathbf{d}, \mathbf{m})$. Secondly, define an equivalence relation on Pcm as follows.

$\{(E_i, f_i)\}_{i=1}^n \sim \{(F_i, h_i)\}_{i=1}^m$ if and only if for any i, j , $|Df_i| = |Dh_j|$ holds \mathbf{m} -a.e. on $E_i \cap F_j$.

Denote by $[E_i, f_i]_i$ the equivalence class of $\{(E_i, f_i)\}_{i=1}^n$ and by χ_E the characteristic function of E for any Borel set $E \subset X$.

With the help of the locality of minimal relaxed slopes, the following operations on the quotient Pcm/\sim are well-defined:

$$\begin{aligned} [E_i, f_i]_i + [F_j, g_j]_j &:= [E_i \cap F_j, f_i + g_j]_{i,j}, \\ \alpha [E_i, f_i]_i &:= [E_i, \alpha f_i]_i, \\ \left(\sum_j \alpha_j \chi_{F_j} \right) \cdot [E_i, f_i]_i &:= [E_i \cap F_j, \alpha_j f_i]_{i,j}, \\ |[E_i, f_i]_i| &:= \sum_i \chi_{E_i} |Df_i| \quad \mathbf{m}\text{-a.e. in } X, \\ \|[E_i, f_i]_i\| &:= \| |[E_i, f_i]_i| \|_{L^2(\mathbf{m})} = \left(\sum_i \int_{E_i} |Df_i|^2 d\mathbf{m} \right)^{\frac{1}{2}}. \end{aligned}$$

Let $(L^2(T^*(X, \mathbf{d}, \mathbf{m})), \|\cdot\|_{L^2(T^*(X, \mathbf{d}, \mathbf{m}))})$ be the completion of $(\text{Pcm}/\sim, \|\cdot\|)$. The multiplication \cdot and the pointwise norm $|\cdot|$ in Definition 2.15 can be continuously extended to

$$\begin{aligned} \cdot : L^\infty(\mathbf{m}) \times L^2(T^*(X, \mathbf{d}, \mathbf{m})) &\rightarrow L^2(T^*(X, \mathbf{d}, \mathbf{m})), \\ |\cdot| : L^2(T^*(X, \mathbf{d}, \mathbf{m})) &\rightarrow L^2(\mathbf{m}). \end{aligned}$$

Then the construction of the module $\left(L^2(T^*(X, \mathbf{d}, \mathbf{m})), \|\cdot\|_{L^2(T^*(X, \mathbf{d}, \mathbf{m}))}, \cdot, |\cdot|\right)$ is completed. We write $L^2(T^*(X, \mathbf{d}, \mathbf{m}))$ for short if no ambiguity is caused.

Theorem 2.17 (Uniqueness of cotangent module). *There is a unique couple $(L^2(T^*(X, \mathbf{d}, \mathbf{m})), d)$, where $L^2(T^*(X, \mathbf{d}, \mathbf{m}))$ is a module and $d : H^{1,2}(X, \mathbf{d}, \mathbf{m}) \rightarrow L^2(T^*(X, \mathbf{d}, \mathbf{m}))$ is a linear operator such that $|df| = |Df|$ holds \mathbf{m} -a.e. for every $f \in H^{1,2}(X, \mathbf{d}, \mathbf{m})$. Uniqueness is intended up to unique isomorphism: if another couple (\mathcal{M}, d') satisfies the same properties, then there exists a unique module isomorphism $\zeta : L^2(T^*(X, \mathbf{d}, \mathbf{m})) \rightarrow \mathcal{M}$ such that $\zeta \circ d = d'$.*

In this thesis, $L^2(T^*(X, \mathbf{d}, \mathbf{m}))$ and d are called the cotangent module and the differential respectively. Elements of $L^2(T^*(X, \mathbf{d}, \mathbf{m}))$ are called 1-forms.

Likewise, the tangent module $L^2(T(X, \mathbf{d}, \mathbf{m}))$ can be defined as a module generated by $\{\nabla f : f \in H^{1,2}(X, \mathbf{d}, \mathbf{m})\}$, where ∇f satisfies that

$$dh(\nabla f) = \langle \nabla h, \nabla f \rangle \quad \mathbf{m}\text{-a.e.}, \quad \forall h \in H^{1,2}(X, \mathbf{d}, \mathbf{m}).$$

$L^2(T(X, \mathbf{d}, \mathbf{m}))$ is the dual module of $L^2(T^*(X, \mathbf{d}, \mathbf{m}))$, and its elements are called vector fields.

Let us recall the construction of the tensor product of $L^2(T^*(X, \mathbf{d}, \mathbf{m}))$ with itself in [G18].

For any $f \in L^\infty(\mathbf{m})$, $f_1, f_2 \in \text{Test}F(X, \mathbf{d}, \mathbf{m})$, the tensor $f df_1 \otimes df_2$ is defined as

$$f df_1 \otimes df_2(\eta_1, \eta_2) := f df_1(\eta_1) df_2(\eta_2), \quad \forall \eta_1, \eta_2 \in L^2(T(X, \mathbf{d}, \mathbf{m})).$$

Set

$$\text{Test}(T^*)^{\otimes 2}(X, \mathbf{d}, \mathbf{m}) := \left\{ \sum_{i=1}^k f_{1,i} df_{2,i} \otimes df_{3,i} : k \in \mathbb{N}, f_{j,i} \in \text{Test}F(X, \mathbf{d}, \mathbf{m}) \right\}.$$

and define the $L^\infty(\mathbf{m})$ -bilinear norm

$$\langle \cdot, \cdot \rangle : \text{Test}(T^*)^{\otimes 2}(X, \mathbf{d}, \mathbf{m}) \times \text{Test}(T^*)^{\otimes 2}(X, \mathbf{d}, \mathbf{m}) \rightarrow L^2(\mathbf{m})$$

as

$$\langle df_1 \otimes df_2, df_3 \otimes df_4 \rangle := \langle \nabla f_1, \nabla f_3 \rangle \langle \nabla f_2, \nabla f_4 \rangle, \quad \forall f_i \in \text{Test}F(X, \mathbf{d}, \mathbf{m}) \quad (i = 1, 2, 3, 4).$$

The pointwise Hilbert-Schmidt norm is then defined as

$$\begin{aligned} |\cdot|_{\text{HS}} : \text{Test}(T^*)^{\otimes 2}(X, \mathbf{d}, \mathbf{m}) &\longrightarrow L^2(\mathbf{m}) \\ A &\longmapsto |A|_{\text{HS}} := \sqrt{\langle A, A \rangle}. \end{aligned}$$

For any $p \in [1, \infty]$, adapting a similar continuous extension procedure of $\text{Test}(T^*)^{\otimes 2}(X, \mathbf{d}, \mathbf{m})$ with respect to the norm $\|\cdot\|_{\text{HS}}\|_{L^p(\mathbf{m})}$ gives a construction of the L^p -normed L^∞ -module $L^p((T^*)^{\otimes 2}(X, \mathbf{d}, \mathbf{m}))$.

In addition, denote by $L^p_{\text{loc}}(T^*(X, \mathbf{d}, \mathbf{m}))$ the collection of 1-forms ω with $|\omega| \in L^p_{\text{loc}}(\mathbf{m})$. Here $L^p_{\text{loc}}(\mathbf{m})$ is the set of all functions f such that $f \in L^p(B_R(x), \mathbf{m})$ for any $B_R(x) \subset X$. Similarly for other vector fields and other tensors.

The end of this subsection is aimed at recalling definitions of two kinds of tensor fields.

Theorem 2.18 (The Hessian [G18]). *For any $f \in \text{Test}F(X, \mathbf{d}, \mathbf{m})$, there exists a unique $T \in L^2((T^*)^{\otimes 2}(X, \mathbf{d}, \mathbf{m}))$, called the Hessian of f , denoted by $\text{Hess } f$, such that for all $f_i \in \text{Test}F(X, \mathbf{d}, \mathbf{m})$ ($i = 1, 2$),*

$$2T(\nabla f_1, \nabla f_2) = \langle \nabla f_1, \nabla \langle \nabla f_2, \nabla f \rangle \rangle + \langle \nabla f_2, \nabla \langle \nabla f_1, \nabla f \rangle \rangle - \langle \nabla f, \nabla \langle \nabla f_1, \nabla f_2 \rangle \rangle \quad (2.15)$$

holds for \mathbf{m} -a.e. $x \in X$. Moreover, the following holds for any $f \in \text{Test}F(X, \mathbf{d}, \mathbf{m})$, $\varphi \in \text{Test}F_+(X, \mathbf{d}, \mathbf{m})$.

$$\frac{1}{2} \int_X \Delta \varphi \cdot |\nabla f|^2 \text{d}\mathbf{m} \geq \int_X \varphi (|\text{Hess } f|_{\text{HS}}^2 + \langle \nabla \Delta f, \nabla f \rangle + K|\nabla f|^2) \text{d}\mathbf{m}. \quad (2.16)$$

Since $\text{Test}F(X, \mathbf{d}, \mathbf{m})$ is dense in $D(\Delta)$, $\text{Hess } f \in L^2((T^*)^{\otimes 2}(X, \mathbf{d}, \mathbf{m}))$ is well-defined for any $f \in D(\Delta)$. In addition, if $f_i \in \text{Test}F(X, \mathbf{d}, \mathbf{m})$ ($i = 1, 2$), then $\langle \nabla f_1, \nabla f_2 \rangle \in H^{1,2}(X, \mathbf{d}, \mathbf{m})$, and the following holds for any $\varphi \in H^{1,2}(X, \mathbf{d}, \mathbf{m})$.

$$\langle \nabla \varphi, \nabla \langle \nabla f_1, \nabla f_2 \rangle \rangle = \text{Hess } f_1(\nabla f_2, \nabla \varphi) + \text{Hess } f_2(\nabla f_1, \nabla \varphi) \quad \mathbf{m}\text{-a.e.} \quad (2.17)$$

Definition 2.19 (The Riemannian metric). A tensor field $\bar{g} \in L^\infty_{\text{loc}}((T^*)^{\otimes 2}(X, \mathbf{d}, \mathbf{m}))$ is said to be a (resp. semi) Riemannian metric on $(X, \mathbf{d}, \mathbf{m})$ if it satisfies the following properties.

1. (Symmetry) $\bar{g}(V, W) = \bar{g}(W, V)$ \mathbf{m} -a.e. for any $V, W \in L^2(T(X, \mathbf{d}, \mathbf{m}))$.
2. (Non (resp. Non semi-) degeneracy) For any $V \in L^2(T(X, \mathbf{d}, \mathbf{m}))$, it holds that

$$\bar{g}(V, V) > 0 \quad (\text{resp. } \bar{g}(V, V) \geq 0) \quad \mathbf{m}\text{-a.e. on } \{|V| > 0\}.$$

2.4 Convergence of $\text{RCD}(K, N)$ spaces

For a sequence of pointed $\text{RCD}(K, N)$ spaces $(X_i, \mathbf{d}_i, \mathbf{m}_i, x_i)$, the equivalence between pointed measured Gromov Hausdorff (pmGH) convergence and pointed measured Gromov (pmG) convergence is established in [GMS13]. We only introduce the definition of pmGH convergence and a precompactness theorem of a

sequence of pointed $\text{RCD}(K, N)$ spaces. It is remarkable that for compact metric measure spaces there is a more convenient convergence named measured Gromov-Hausdorff (mGH) convergence (see [F87]).

Definition 2.20 (Pointed measured Gromov-Hausdorff (pmGH) convergence). A sequence of pointed metric measure spaces $\{(X_i, \mathbf{d}_i, \mathbf{m}_i, x_i)\}$ is said to be convergent to a pointed metric measure space $(X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty, x_\infty)$ in the pointed measured Gromov-Hausdorff (pmGH) sense, if there exists a complete separable metric space (Y, \mathbf{d}_Y) and a sequence of isometric embeddings $\{\iota_i : X_i \rightarrow Y\}_{i \in \mathbb{N} \cup \{\infty\}}$, such that

1. $\mathbf{d}_Y(\iota_i(x_i), \iota_\infty(x_\infty)) \rightarrow 0$,
2. for any $R, \epsilon > 0$, there exists $N > 0$, such that for any $i > N$, we have $\iota_\infty(B_R^{X_\infty}(x_\infty)) \subset B_\epsilon^Y(\iota_i(B_R^{X_i}(x_i)))$ and $\iota_i(B_R^{X_i}(x_i)) \subset B_\epsilon^Y(\iota_\infty(B_R^{X_\infty}(x_\infty)))$,
3. for every $f \in C_c(Y)$, $\lim_{i \rightarrow \infty} \int_Y f d(\iota_i)_\# \mathbf{m}_i = \int_Y f d(\iota_\infty)_\# \mathbf{m}_\infty$.

In particular, we say that $X_i \ni x'_i \rightarrow x'_\infty \in X_\infty$ if $\mathbf{d}_Y(\iota_i(x'_i), \iota_\infty(x'_\infty)) \rightarrow 0$.

Definition 2.21 (Measured Gromov-Hausdorff convergence). Let $\{(X_i, \mathbf{d}_i, \mathbf{m}_i)\}$ be a sequence of compact metric measure spaces with $\sup_i \text{diam}(X_i, \mathbf{d}_i) < \infty$. Then $\{(X_i, \mathbf{d}_i, \mathbf{m}_i)\}$ is said to be convergent to a metric measure space $(X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty)$ in the measured Gromov-Hausdorff (mGH) sense if there exists a sequence of points $\{x_i \in X_i\}_{i \in \mathbb{N} \cup \{\infty\}}$, such that

$$(X_i, \mathbf{d}_i, \mathbf{m}_i, x_i) \xrightarrow{\text{pmGH}} (X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty, x_\infty).$$

Theorem 2.22 (Precompactness of pointed $\text{RCD}(K, N)$ spaces under pmGH convergence [GMS13]). *Let $\{(X_i, \mathbf{d}_i, \mathbf{m}_i, x_i)\}$ be a sequence of pointed $\text{RCD}(K, N)$ spaces such that*

$$0 < \liminf_{i \rightarrow \infty} \mathbf{m}_i(B_1^{X_i}(x_i)) \leq \limsup_{i \rightarrow \infty} \mathbf{m}_i(B_1^{X_i}(x_i)) < \infty.$$

Then there exists a subsequence $\{(X_{i(j)}, \mathbf{d}_{i(j)}, \mathbf{m}_{i(j)}, x_{i(j)})\}$, such that it pmGH converges to a pointed $\text{RCD}(K, N)$ space $(X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty, x_\infty)$.

Especially, non-collapsed pmGH convergent sequences of non-collapsed $\text{RCD}(K, N)$ spaces preserve the Hausdorff measure.

Theorem 2.23 (Continuity of Hausdorff measure [DG18, Theorem 1.3]). *If a sequence of pointed non-collapsed $\text{RCD}(K, N)$ spaces $\{(X_i, \mathbf{d}_i, \mathcal{H}^N, x_i)\}$ pmGH converges to a pointed $\text{RCD}(K, N)$ space $(X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty, x_\infty)$ and satisfies $\inf_i \mathcal{H}^N(B_1^{X_i}(x_i)) > 0$, then $\mathbf{m}_\infty = \mathcal{H}^N$.*

It is also worth recalling the following definition.

Definition 2.24 (Regular set). Let $(X, \mathbf{d}, \mathbf{m})$ be an $\text{RCD}(K, N)$ space. Given any integer $k \in [1, N]$, the k -dimensional regular set $\mathcal{R}_k := \mathcal{R}_k(X)$ of X is defined as the set of all points of x such that

$$\left(X, \frac{1}{r_i} \mathbf{d}, \frac{\mathbf{m}}{\mathbf{m}(B_{r_i}(x))}, x \right) \xrightarrow{\text{pmGH}} \left(\mathbb{R}^k, \mathbf{d}_{\mathbb{R}^k}, \frac{1}{\omega_k} \mathcal{L}^k, 0_k \right) \quad \forall \{r_i\} \subset (0, \infty) \text{ with } r_i \rightarrow 0.$$

It is time to introduce the definition of the essential dimension of RCD spaces. Compare [CN12].

Theorem 2.25 (Essential dimension [BS20]). *Let $(X, \mathbf{d}, \mathbf{m})$ be an $\text{RCD}(K, N)$ space which is not a single point. Then there exists a unique $n \in \mathbb{N} \cap [1, N]$ such that $\mathbf{m}(X \setminus \mathcal{R}_n) = 0$. The essential dimension $\dim_{\mathbf{d}, \mathbf{m}}(X)$ of $(X, \mathbf{d}, \mathbf{m})$ is defined as this n .*

Remark 2.26. Under the assumption of Theorem 2.25, for any $m \in \mathbb{N}_+$, define the Bishop-Gromov density of $(X, \mathbf{d}, \mathbf{m})$ as

$$\begin{aligned} \vartheta_m(X, \mathbf{d}, \mathbf{m}) : X &\longrightarrow [0, \infty] \\ x &\longmapsto \begin{cases} \lim_{r \rightarrow 0} \frac{\mathbf{m}(B_r(x))}{\omega_m r^m}, & \text{if it exists,} \\ \infty, & \text{otherwise.} \end{cases} \end{aligned}$$

The measure \mathbf{m} then can be represented as $\vartheta_n(X, \mathbf{d}, \mathbf{m})(x) \mathcal{H}^n \llcorner \mathcal{R}_n$. Moreover, $\mathbf{m}(\mathcal{R}_n \setminus \mathcal{R}_n^*) = 0$, where $\mathcal{R}_n^* := \{x \in \mathcal{R}_n : \vartheta_n(X, \mathbf{d}, \mathbf{m}) \in (0, \infty)\}$. See [AHT18].

In particular, for non-collapsed $\text{RCD}(K, N)$ spaces, the following statement holds.

Theorem 2.27 (Bishop inequality [DG18, Corollary 1.7]). *Let $(X, \mathbf{d}, \mathcal{H}^N)$ be a non-collapsed $\text{RCD}(K, N)$ space. Then $\dim_{\mathbf{d}, \mathcal{H}^N}(X) = N \in \mathbb{N}$, and $\vartheta_N(X, \mathbf{d}, \mathcal{H}^N) \leq 1$ holds for any $x \in X$. Moreover, the equality holds if and only if $x \in \mathcal{R}_N$.*

Given an $\text{RCD}(K, N)$ space $(X, \mathbf{d}, \mathbf{m})$, there is a canonical Riemannian metric g in the following sense.

Theorem 2.28 (The canonical Riemannian metric [GP16, AHPT21]). *There exists a unique Riemannian metric g such that for any $f_1, f_2 \in H^{1,2}(X, \mathbf{d}, \mathbf{m})$, it holds that*

$$g(\nabla f_1, \nabla f_2) = \langle \nabla f_1, \nabla f_2 \rangle \quad \mathbf{m}\text{-a.e. in } X.$$

Moreover, $|g|_{\text{HS}} = \sqrt{\dim_{\mathbf{d}, \mathbf{m}}(X)}$ \mathbf{m} -a.e. in X .

Let us use this canonical Riemannian metric to define the trace as

$$\begin{aligned} \text{Tr} : L_{\text{loc}}^2((T^*)^{\otimes 2}(X, \mathbf{d}, \mathbf{m})) &\longrightarrow L_{\text{loc}}^2((T^*)^{\otimes 2}(X, \mathbf{d}, \mathbf{m})) \\ T &\longmapsto \langle T, g \rangle. \end{aligned}$$

The convergence of functions and tensor fields on pmGH convergent pointed $\text{RCD}(K, N)$ spaces are also well-defined as in [GMS13], [H15, Definition 1.1] and [AH17, AST16]. In the rest of this subsection, we fix a pmGH convergence of $\text{RCD}(K, N)$ spaces

$$(X_i, \mathbf{d}_i, \mathbf{m}_i, x_i) \xrightarrow{\text{pmGH}} (X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty, x_\infty),$$

and use the notation in Definition 2.20.

Theorem 2.29 (Arzelà-Ascoli theorem). *Suppose $f_i \in C(X_i)$ ($i \in \mathbb{N}$) such that $\{f_i\}$ satisfies the following two conditions.*

1. (Locally uniformly bounded) *For any $R > 0$ it holds that*

$$\sup_i \sup_{y_i \in B_R(x_i)} |h_i(y_i)| < \infty.$$

2. (Locally equicontinuous) *For any $\epsilon, R \in (0, \infty)$, there exists $\delta \in (0, 1)$ such that for any $i \in \mathbb{N}$ it holds that*

$$|f_i(y_i) - f_i(z_i)| < \epsilon, \quad \forall y_i, z_i \in B_R(x_i) \text{ such that } \mathbf{d}_i(x_i, y_i) < \delta.$$

Then after passing to a subsequence, there exists $f_\infty \in C(X_\infty)$ such that $\{f_i\}$ pointwisely converges to f_∞ in the following sense:

$$f_i(y_i) \rightarrow f_\infty(y) \text{ whenever } X_i \ni y_i \rightarrow y \in X_\infty.$$

Definition 2.30 (L^2 -convergence of functions defined on varying spaces). A sequence $\{f_i : X_i \rightarrow \mathbb{R}\}$ is said to be L^2 -weakly convergent to $f_\infty \in L^2(\mathbf{m}_\infty)$ if

$$\begin{cases} \sup_i \|f_i\|_{L^2(\mathbf{m}_i)} < \infty, \\ \lim_{i \rightarrow \infty} \int_Y h f_i d(\iota_i)_\# \mathbf{m}_i = \int_Y h f_\infty d(\iota_\infty)_\# \mathbf{m}_\infty, \quad \forall h \in C_c(Y). \end{cases}$$

If moreover $\{f_i\}$ satisfies $\limsup_{i \rightarrow \infty} \|f_i\|_{L^2(\mathbf{m}_i)} \leq \|f\|_{L^2(\mathbf{m}_\infty)}$, then $\{f_i\}$ is said to be L^2 -strongly convergent to f .

Definition 2.31 ($H^{1,2}$ -convergence of functions defined on varying spaces). A sequence $\{f_i : X_i \rightarrow \mathbb{R}\}$ is said to be $H^{1,2}$ -weakly convergent to $f_\infty \in H^{1,2}(X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty)$ if

$$f_i \xrightarrow{L^2\text{-weakly}} f \text{ and } \sup_i \text{Ch}^{X_i}(f_i) < \infty.$$

If moreover, $\{f_i\}$ satisfies

$$\limsup_{i \rightarrow \infty} \|f_i\|_{L^2(\mathbf{m}_i)} \leq \|f\|_{L^2(\mathbf{m}_\infty)} \text{ and } \limsup_{i \rightarrow \infty} \text{Ch}^{X_i}(f_i) = \text{Ch}^{X_\infty}(f_\infty),$$

then $\{f_i\}$ is said to be $H^{1,2}$ -strongly convergent to f .

Definition 2.32 (Convergence of tensor fields defined on varying spaces). Let $T_i \in L^2_{\text{loc}}((T^*)^{\otimes 2}(X_i, \mathbf{d}_i, \mathbf{m}_i))$, ($i \in \mathbb{N}$). For any $R > 0$, $\{T_i\}$ is said to be L^2 -weakly convergent to $T_\infty \in L^2((T^*)^{\otimes 2}(B_R^{X_\infty}(x_\infty), \mathbf{d}_\infty, \mathbf{m}_\infty))$ on $B_R^{X_\infty}(x_\infty)$ if it satisfies the following conditions.

1. (Uniform upper L^2 bound) $\sup_i \| |T_i|_{\text{HS}} \|_{L^2(B_R^{X_i}(x_i), \mathbf{m}_i)} < \infty$.
2. For any $f_{j,i} \in \text{Test}F(X_i, \mathbf{d}_i, \mathbf{m}_i)$ ($i \in \mathbb{N}$, $j = 1, 2$) such that $\{f_{j,i}\}$ L^2 -strongly converges to $f_{j,\infty} \in \text{Test}F(X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty)$ ($j = 1, 2$) and that

$$\sup_{i,j} \left(\|f_{j,i}\|_{L^\infty(\mathbf{m}_i)} + \| |\nabla^{X_i} f_{j,i}| \|_{L^\infty(\mathbf{m}_i)} + \| \Delta^{X_i} f_{j,i} \|_{L^\infty(\mathbf{m}_i)} \right) < \infty,$$

we have $\{\chi_{B_R^{X_i}(x_i)} \langle T_i, df_{1,i} \otimes df_{2,i} \rangle\}$ L^2 -weakly converges to $\chi_{B_R^{X_\infty}(x_\infty)} \langle T_\infty, df_{1,\infty} \otimes df_{2,\infty} \rangle$.

If moreover, $\limsup_{i \rightarrow \infty} \| |T_i|_{\text{HS}} \|_{L^2(B_R^{X_i}(x_i), \mathbf{m}_i)} \leq \| |T_\infty|_{\text{HS}} \|_{L^2(B_R^{X_\infty}(x_\infty), \mathbf{m}_\infty)}$, then $\{T_i\}$ is said to be L^2 -strongly convergent to T_∞ on $B_R^{X_\infty}(x_\infty)$.

The following two theorems are based on [AH18, GMS13, AST16].

Theorem 2.33 (Compactness of Sobolev functions). *If moreover*

$$\sup_i \text{diam}(X_i, \mathbf{d}_i) < \infty,$$

then for any $f_i \in H^{1,2}(X_i, \mathbf{d}_i, \mathbf{m}_i)$ $i \in \mathbb{N}$ with $\sup_i \|f_i\|_{H^{1,2}(X_i, \mathbf{d}_i, \mathbf{m}_i)} < \infty$, there exists $f_\infty \in H^{1,2}(X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty)$, and a subsequence of $\{f_i\}$ which is still denoted as $\{f_i\}$ such that $\{f_i\}$ L^2 -strongly converges to f_∞ and

$$\liminf_{i \rightarrow \infty} \int_{X_i} |\nabla^{X_i} f_i|^2 d\mathbf{m}_i \geq \int_{X_\infty} |\nabla^{X_\infty} f_\infty|^2 d\mathbf{m}_\infty.$$

Theorem 2.34 (Stability of Laplacian). *Let $\{(X_i, \mathbf{d}_i, \mathbf{m}_i)\}$, $(X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty)$ be taken as in Theorem 2.33. Let $f_i \in D(\Delta^{X_i})$ with*

$$\sup_i \left(\|f_i\|_{H^{1,2}(X_i, \mathbf{d}_i, \mathbf{m}_i)} + \|\Delta^{X_i} f_i\|_{L^2(\mathbf{m}_i)} \right) < \infty.$$

If $\{f_i\}$ L^2 -strongly converges to f (by Theorem 2.33 $f_\infty \in H^{1,2}(X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty)$), then the following statements hold.

1. $f_\infty \in D(\Delta^{X_\infty})$.
2. $\{\Delta^{X_i} f_i\}$ L^2 -weakly converges to $\Delta^{X_\infty} f_\infty$.
3. $\{|\nabla^{X_i} f_i|\}$ L^2 -strongly converges to $|\nabla^{X_\infty} f_\infty|$.

Let us recall three convergences to end this section.

Theorem 2.35 (Pointwise convergence of heat kernels [AHT18, Theorem 3.3]). *The heat kernels ρ_i of $(X_i, \mathbf{d}_i, \mathbf{m}_i)$ satisfy*

$$\lim_{i \rightarrow \infty} \rho_i(x_i, y_i, t_i) = \rho_\infty(x_\infty, y_\infty, t)$$

whenever $X_i \times X_i \times (0, \infty) \ni (x_i, y_i, t_i) \rightarrow (x_\infty, y_\infty, t) \in X_\infty \times X_\infty \times (0, \infty)$.

Theorem 2.36 ($H^{1,2}$ -strong convergence of heat kernels [AHPT21, Theorem 2.19]). *For any $\{t_i\} \subset (0, \infty)$ with $t_i \rightarrow t_0 \in (0, \infty)$ and any $\{y_i\}$ with $X_i \ni y_i \rightarrow y_\infty \in X_\infty$, $\{\rho_i(\cdot, y_i, t_i)\}$ $H^{1,2}$ -strongly converges to $\rho_\infty(\cdot, y_\infty, t) \in H^{1,2}(X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty)$.*

Theorem 2.37 (Lower semicontinuity of essential dimension [K19, Theorem 1.5]).

$$\liminf_{i \rightarrow \infty} \dim_{\mathbf{d}_i, \mathbf{m}_i}(X_i) \leq \dim_{\mathbf{d}_\infty, \mathbf{m}_\infty}(X_\infty).$$

3 The isometric immersion into L^2 space via heat kernel

Recently the equivalence between weakly non-collapsed RCD spaces and non-collapsed RCD spaces is proved in [BGHZ23, Theorem 1.3], which states as follows.

Theorem 3.1. *Assume that $(X, \mathbf{d}, \mathbf{m})$ is an $\text{RCD}(K, N)$ space. If*

$$\mathbf{m} \left(\left\{ x \in X : \limsup_{r \rightarrow 0^+} \frac{\mathbf{m}(B_r(x))}{r^N} < \infty \right\} \right) > 0,$$

then $\mathbf{m} = c\mathcal{H}^N$ for some $c > 0$. Therefore, $(X, \mathbf{d}, c^{-1}\mathbf{m})$ is a non-collapsed $\text{RCD}(K, N)$ space.

The key to prove Theorem 3.1 is Theorem 3.2, and the asymptotic formula (Theorem 1.1) of g_t plays an important role in the proof of Theorem 3.2. The precise definition of g_t shall be given in Theorem 3.3.

Theorem 3.2 ([BGHZ23, Theorem 1.5, Theorem 2.22]). *Assume that $(X, \mathbf{d}, \mathcal{H}^n)$ is an $\text{RCD}(K, N)$ space with $\dim_{\mathbf{d}, \mathbf{m}}(X) = n$ and U is a connected open subset of X such that for any compact subset $A \subset U$,*

$$\inf_{r \in (0,1), x \in A} \frac{\mathcal{H}^n(B_r(x))}{r^n} > 0. \quad (3.1)$$

Then for any $f \in \text{Test}F(X, \mathbf{d}, \mathcal{H}^n)$, any $\varphi \in D(\Delta)$ with $\varphi \geq 0$, $\text{supp}(\varphi) \subset U$ and $\Delta\varphi \in L^\infty(\mathcal{H}^n)$, it holds that

$$\frac{1}{2} \int_U |\nabla f|^2 \Delta\varphi \, d\mathcal{H}^n \geq \int_U \varphi \left(\langle \nabla f, \nabla \Delta f \rangle + K|\nabla f|^2 + \frac{(\Delta f)^2}{n} \right) d\mathcal{H}^n.$$

In addition, for a weakly non-collapsed (and is now non-collapsed) $\text{RCD}(K, n)$ space $(X, \mathbf{d}, \mathcal{H}^n)$, it follows from [DG18, Theorem 1.12] that

$$\Delta f = \langle \text{Hess } f, g \rangle \quad \mathbf{m}\text{-a.e.}, \quad \forall f \in D(\Delta).$$

3.1 The pullback metric g_t

In [Ta66], Takahashi proves that any compact homogeneous irreducible Riemannian manifold (M^n, g) is IHKI, which is even true provided that (M^n, g) is a non-compact homogeneous irreducible Riemannian manifold.

To generalize such isometric immersions to $\text{RCD}(K, N)$ spaces, let us first introduce the following locally Lipschitz t -time heat kernel mapping on an $\text{RCD}(K, N)$ space $(X, \mathbf{d}, \mathbf{m})$ by using its heat kernel ρ analogously :

$$\begin{aligned}\Phi_t : X &\longrightarrow L^2(\mathbf{m}) \\ x &\longmapsto (y \mapsto \rho(x, y, t)),\end{aligned}$$

which is well-defined due to the estimates in Theorem 2.8.

The natural pull-back semi-Riemannian metric of the flat metric of $L^2(\mathbf{m})$, namely $g_t := (\Phi_t)^*(g_{L^2(\mathbf{m})})$, is defined as follows, see [AHPT21, Proposition 4.7] and [BGHZ23, Proposition 3.7].

Theorem 3.3 (The pull-back semi-Riemannian metrics). *For all $t > 0$, there is a unique semi-Riemannian metric $g_t \in L_{\text{loc}}^\infty((T^*)^{\otimes 2}(X, \mathbf{d}, \mathbf{m}))$ such that*

1. For any $\eta_i \in L^2(T^*(X, \mathbf{d}, \mathbf{m}))$ with bounded support ($i = 1, 2$),

$$\int_X \langle g_t, \eta_1 \otimes \eta_2 \rangle \, \mathbf{d}\mathbf{m} = \int_X \int_X \langle d_x \rho(x, y, t), \eta_1 \rangle \langle d_x \rho(x, y, t), \eta_2 \rangle \, \mathbf{d}\mathbf{m}(x) \mathbf{d}\mathbf{m}(y).$$

In particular, if $(X, \mathbf{d}, \mathbf{m})$ is compact, then $g_t = \sum_{i=1}^{\infty} e^{-2\mu_i t} d\phi_i \otimes d\phi_i$.

2. For any $t \in (0, 1)$, the rescaled semi-Riemannian metric $t\mathbf{m}(B_{\sqrt{t}}(\cdot))g_t$ satisfies

$$t\mathbf{m}(B_{\sqrt{t}}(\cdot))g_t \leq C(K, N)g, \quad (3.2)$$

which means that for any $\eta \in L^2(T^*(X, \mathbf{d}, \mathbf{m}))$, it holds that

$$t\mathbf{m}(B_{\sqrt{t}}(x))\langle g_t, \eta \otimes \eta \rangle(x) \leq C(K, N)|\eta|^2(x) \quad \mathbf{m}\text{-a.e. } x \in X.$$

The rest part of this subsection proves Theorem 1.11. The following inequality is needed. See for instance [AHPT21, Lemma 2.3] and [BGHZ23, Lemma 2.7].

Lemma 3.4. *Let $(X, \mathbf{d}, \mathbf{m})$ be an $\text{RCD}(K, N)$ space. Then for any $\alpha \in \mathbb{R}$, $\beta > 0$ and any $x \in X$, it holds that*

$$\int_X \mathbf{m}(B_{\sqrt{t}}(y))^\alpha \exp\left(-\frac{\beta \mathbf{d}^2(x, y)}{t}\right) \, \mathbf{d}\mathbf{m}(y) \leq C(K, N, \alpha, \beta) \mathbf{m}(B_{\sqrt{t}}(x))^{\alpha+1}. \quad (3.3)$$

Remark 3.5. When $(X, \mathbf{d}, \mathbf{m})$ is an $\text{RCD}(0, N)$ space, by [JLZ16, Corollary 1.1] and Lemma 3.4, (3.2) becomes

$$t\mathbf{m}(B_{\sqrt{t}}(\cdot))g_t \leq C(N)g, \quad \forall t > 0. \quad (3.4)$$

Jiang's gradient estimate [J14, Theorem 3.1] is also important in this thesis, which states as follows.

Theorem 3.6. *Let $(X, \mathbf{d}, \mathbf{m})$ be an $\text{RCD}(K, N)$ space and Ω be an open subset. If for some $u \in D(\Delta) \cap L^\infty(\Omega, \mathbf{m})$, $\Delta u \in L^\infty(\Omega, \mathbf{m})$, then for every $B_R(x)$ with $R \leq 1$ and $B_{8R}(x) \Subset \Omega$, it holds that*

$$\|\nabla u\|_{L^\infty(B_R(x), \mathbf{m})} \leq C(K, N) \left(\frac{1}{R} \|u\|_{L^\infty(B_{8R}(x), \mathbf{m})} + R \|\Delta u\|_{L^\infty(B_{8R}(x), \mathbf{m})} \right). \quad (3.5)$$

Finally, we need the following proposition.

Proposition 3.7. *Suppose that $(X, \mathbf{d}, \mathbf{m})$ is an $\text{RCD}(K, N)$ space which is not a single point. Then for any $t > 0$,*

$$\mathbf{m}(\{x \in X : |g_t|_{\text{HS}} > 0\}) > 0.$$

Proof. Assume by contradiction the existence of $t_0 > 0$ such that $\mathbf{m}(\{x \in X : |g_{t_0}|_{\text{HS}} > 0\}) = 0$. Clearly this implies $|\nabla_x \rho(x, y, t_0)| = 0$, \mathbf{m} -a.e. $x, y \in X$. For any fixed $x \in X$, the locally Lipschitz continuity of $y \mapsto \rho(x, y, t_0)$ as well as the Sobolev to Lipschitz property then yields that $\Phi_{t_0} \equiv c\hat{1}$ for some constant c . Therefore, it follows from the stochastic completeness of $\text{RCD}(K, N)$ spaces that $\mathbf{m}(X) < \infty$. Without loss of generality, assume that $\mathbf{m}(X) = 1$. Notice that $\Phi_{2t_0}(x) = h_{t_0}(\Phi_{t_0}(x)) \equiv \hat{1}$, which implies $\rho(x, y, t) \equiv 1$ on $X \times X \times [t_0, 2t_0]$ by (2.4). Then applying Remark 2.9 shows that

$$\rho(x, y, t) = 1, \quad \forall (x, y, t) \in X \times X \times (0, \infty).$$

As a consequence, for any $f \in L^2(\mathbf{m})$, we have

$$h_t f = \int_X \rho(x, y, t) f \, d\mathbf{m} = \int_X f \, d\mathbf{m}, \quad \forall t > 0.$$

Since $h_t f$ converges to f in $L^2(\mathbf{m})$ as $t \rightarrow 0$, f is nothing but a constant function, which is enough to conclude that X is a single point. A contradiction. \square

Proof of Theorem 1.11. Let $n = \dim_{\mathbf{d}, \mathbf{m}}(X)$. For any fixed $B_R(x_0) \subset X$, set

$$f : (0, \infty) \longrightarrow [0, \infty)$$

$$t \longmapsto n\mathbf{m}(B_R(x_0)) \int_{B_R(x_0)} \langle g_t, g_t \rangle \, d\mathbf{m} - \left(\int_{B_R(x_0)} \langle g, g_t \rangle \, d\mathbf{m} \right)^2.$$

Since we can rescale the space, it suffices to show that f is analytic at any $t \in (0, 1)$. Because then by applying Proposition 3.7 we are done.

For any $m \geq 1$, the commutativity of $\frac{\partial}{\partial t}$ and Δ allows us to fix an arbitrary $y \in X$ and apply Theorem 3.6 on $B_{8\sqrt{t}}(x)$ for $u : z \mapsto \frac{\partial^m}{\partial t^m} \rho(z, y, t)$. (2.5) then implies

$$\|\|\nabla u\|\|_{L^\infty(B_{\sqrt{t}}(x), \mathbf{m})} \leq \frac{C(K, N)m!}{t^{m+\frac{1}{2}}} \sup_{z \in B_{8\sqrt{t}}(x)} (\mathbf{m}(B_{\sqrt{t}}(z))\mathbf{m}(B_{\sqrt{t}}(y)))^{-\frac{1}{2}} \exp\left(-\frac{\mathbf{d}^2(z, y)}{100t}\right).$$

Using (2.3), for any $z \in B_{8\sqrt{t}}(x)$, we know

$$\frac{\mathbf{m}(B_{\sqrt{t}}(x))}{\mathbf{m}(B_{\sqrt{t}}(z))} \leq C(K, N) \exp\left(\frac{\sqrt{t} + \mathbf{d}(x, z)}{\sqrt{t}}\right) \leq C(K, N).$$

This as well as the inequality $-\mathbf{d}^2(z, y) \leq \mathbf{d}^2(z, x) - \frac{\mathbf{d}^2(x, y)}{2}$ implies that for \mathbf{m} -a.e. $x \in X$,

$$\left| \nabla_x \frac{\partial^m}{\partial t^m} \rho(x, y, t) \right| \leq \frac{C(K, N)m!}{t^{m+\frac{1}{2}}} (\mathbf{m}(B_{\sqrt{t}}(x))\mathbf{m}(B_{\sqrt{t}}(y)))^{-\frac{1}{2}} \exp\left(-\frac{\mathbf{d}^2(x, y)}{200t}\right). \quad (3.6)$$

Let $f = n\mathbf{m}(B_R(x_0))f_1 - f_2$, with $f_2(t) = \int_{B_R(x_0)} \langle g, g_t \rangle d\mathbf{m}$. We only give a proof of the analyticity of f_1 , since the analyticity of f_2 will follow from similar arguments.

Rewrite f_1 as

$$f_1(t) = \int_{B_R(x_0)} \int_X \int_X \langle \nabla_x \rho(x, y, t), \nabla_x \rho(x, z, t) \rangle^2 d\mathbf{m}(z)d\mathbf{m}(y)d\mathbf{m}(x).$$

It is enough to estimate derivatives of each order of f_1 at any fixed $t \in (0, 1)$. We first show that f_1 is differentiable.

For any sufficiently small s , $\frac{f_1(t+s) - f_1(t)}{s}$ can be written as the sum of the integrals of functions like

$$\left\langle \nabla_x \frac{\rho(x, y, t+s) - \rho(x, y, t)}{s}, \nabla_x \rho(x, z, t) \right\rangle \langle \nabla_x \rho(x, y, t+s), \nabla_x \rho(x, z, t+s) \rangle \quad (3.7)$$

on $B_R(x_0) \times X \times X$.

In order to use the dominated convergence theorem, we need estimates of $\left| \nabla_x \frac{\rho(x, y, t+s) - \rho(x, y, t)}{s} \right|$ and $|\nabla_x \rho(x, y, t+s)|$ for any sufficiently small s . By

Theorem 2.8 and the Bishop-Gromov inequality, for \mathbf{m} -a.e. $x \in X$,

$$\begin{aligned}
|\nabla_x \rho(x, y, t+s)| &\leq \frac{C(K, N)}{\sqrt{t+s} \mathbf{m}(B_{\sqrt{t+s}}(x))} \exp\left(-\frac{\mathbf{d}^2(x, y)}{100(t+s)}\right) \\
&\leq \frac{C(K, N)}{\sqrt{t} \mathbf{m}(B_{\sqrt{t}}(x)) \mathbf{m}(B_{\sqrt{t+s}}(x))} \exp\left(-\frac{\mathbf{d}^2(x, y)}{200t}\right) \\
&\leq \frac{C(K, N)}{\sqrt{t} \mathbf{m}(B_{\sqrt{t}}(x))} \exp\left(-\frac{\mathbf{d}^2(x, y)}{200t}\right).
\end{aligned} \tag{3.8}$$

The last inequality of (3.8) is obvious when $s > 0$, and is guaranteed by the Bishop-Gromov inequality when $s < 0$.

Applying (3.6), Theorem 3.6 and the Lagrange mean value theorem, the following estimate can also be obtained as in (3.8):

$$\begin{aligned}
&\left| \nabla_x \left(\frac{\rho(x, y, t+s) - \rho(x, y, t)}{s} - \frac{\partial}{\partial t} \rho(x, y, t) \right) \right| \\
&\leq \frac{C(K, N)2!|s|}{t^{\frac{5}{2}}} (\mathbf{m}(B_{\sqrt{t}}(x)) \mathbf{m}(B_{\sqrt{t}}(y)))^{-\frac{1}{2}} \exp\left(-\frac{\mathbf{d}^2(x, y)}{300t}\right).
\end{aligned} \tag{3.9}$$

Therefore the $L^1(\mathbf{m} \otimes \mathbf{m} \otimes \mathbf{m})$ convergence of (3.7) as $s \rightarrow 0$ can be verified by (3.8), (3.9) and Lemma 3.4. The limit of (3.7) as $s \rightarrow 0$ is actually

$$\int_{B_R(x_0) \times X \times X} \left\langle \nabla_x \frac{\partial}{\partial t} \rho(x, y, t), \nabla_x \rho(x, z, t) \right\rangle \langle \nabla_x \rho(x, y, t), \nabla_x \rho(x, z, t) \rangle \mathbf{d}\mathbf{m}(z) \mathbf{d}\mathbf{m}(y) \mathbf{d}\mathbf{m}(x).$$

The proof of any higher order differentiability of f_1 can follow from similar arguments as above.

On the other hand, the higher order derivatives of f_1 shall be written as

$$f_1^{(m)}(t) = \sum_{k=0}^m \sum_{i=0}^k \sum_{j=0}^{m-k} \int_{B_R(x_0)} \int_X \int_X I_{k,i} I_{m-k,j} \mathbf{d}\mathbf{m}(z) \mathbf{d}\mathbf{m}(y) \mathbf{d}\mathbf{m}(x),$$

where

$$I_{k,i} = \left\langle \nabla_x \frac{\partial^i}{\partial t^i} \rho(x, y, t), \nabla_x \frac{\partial^{k-i}}{\partial t^{k-i}} \rho(x, z, t) \right\rangle.$$

Letting

$$I_i = \left| \nabla_x \frac{\partial^i}{\partial t^i} \rho(x, y, t) \right|, \quad J_i = \left| \nabla_x \frac{\partial^i}{\partial t^i} \rho(x, z, t) \right|,$$

we obtain

$$|I_{k,i} I_{m-k,j}| \leq I_i J_i J_{k-i} J_{m-k-j}, \quad \mathbf{m}\text{-a.e.}$$

Finally Theorem 2.8, Lemma 3.4 and (3.6) yield that

$$\left| \int_X I_i I_j d\mathbf{m}(y) \right| \leq C(K, N) \frac{i!j!}{t^{i+j+1}},$$

$$\left| \int_X J_{k-i} J_{m-k-j} d\mathbf{m}(z) \right| \leq C(K, N) \frac{(k-i)!(m-k-j)!}{t^{m-i-j+1}}.$$

Thus $|f_1^{(m)}(t)| \leq \mathbf{m}(B_R(x_0))C(K, N)m!t^{-(m+2)}$. This completes the proof. \square

3.2 A regularity result about IHKI RCD(K, N) spaces

This subsection is aimed at proving Theorem 1.13. The following statement is trivial for the pmGH convergence of geodesic spaces, which is frequently used in the proof of Theorem 1.13. We shall call no extra attention to this well-known fact in this thesis.

Fact 3.8. Assume that $(X, \mathbf{d}, \mathbf{m})$ is an RCD(K, N) space and is not a single point. Then for any sequence of points $\{x_i\} \subset X$, and any $\{r_i\}$ with $r_i \rightarrow 0$, after passing to a subsequence, the pmGH limit of $\left\{ \left(X_i, \frac{1}{r_i} \mathbf{d}_i, \frac{\mathbf{m}}{\mathbf{m}(B_{r_i}(x_i))}, x_i \right) \right\}$ is not a single point.

Let us fix an IHKI RCD(K, N) space $(X, \mathbf{d}, \mathbf{m})$ which is not a single point. According to Proposition 3.7, we make a convention that there exists a function $c(t)$ such that

$$c(t)g_t = g, \quad \forall t > 0,$$

in the rest of this subsection.

Proof of Theorem 1.13. The proof consists of three steps.

Step 1 There exists $\tilde{c} > 0$, such that

$$\lim_{r \rightarrow 0} \frac{\mathbf{m}(B_r(x))}{r^n} = \tilde{c}, \quad \forall x \in \mathcal{R}_n^*, \quad (3.10)$$

and the function c satisfies

$$\lim_{t \rightarrow 0} \frac{t^{n+2}}{c(t^2)} = \tilde{c}^{-1} \omega_n c_1^{\mathbb{R}^n}. \quad (3.11)$$

Fix $x \in \mathcal{R}_n^*$. From the very definition of \mathcal{R}_n^* , $\lim_{r \rightarrow 0} r^{-n} \mathbf{m}(B_r(x)) = \tilde{c}$ for some $\tilde{c} = \tilde{c}(x) > 0$. For any $\{r_i\}$ with $r_i \rightarrow 0$, we have

$$(X_i, \mathbf{d}_i, \mathbf{m}_i, x) := \left(X, \frac{1}{r_i} \mathbf{d}, \frac{\mathbf{m}}{\mathbf{m}(B_{r_i}(x))}, x \right) \xrightarrow{\text{pmGH}} \left(\mathbb{R}^n, \mathbf{d}_{\mathbb{R}^n}, \frac{1}{\omega_n} \mathcal{L}^n, 0_n \right). \quad (3.12)$$

On each X_i , $c(r_i^2 t)g_t^{X_i} = r_i^2 \mathbf{m}(B_{r_i}(x))g_{X_i}$. By [BGHZ23, Theorem 3.11], $\{g_t^{X_i}\}$ L^2 -strongly converges to $\omega_n g_t^{\mathbb{R}^n}$ on any $B_R(0_n) \subset \mathbb{R}^n$, from which we know

$$\lim_{i \rightarrow \infty} r_i^2 \frac{\mathbf{m}(B_{r_i}(x))}{c(r_i^2 t)} = \omega_n c_t^{\mathbb{R}^n}.$$

Since the above limit does not depend on the choice of the sequence $\{r_i\}$, we have

$$\lim_{r \rightarrow 0} r^2 \frac{\mathbf{m}(B_r(x))}{c(r^2 t)} = \lim_{r \rightarrow 0} \frac{\mathbf{m}(B_r(x))}{r^n} \frac{r^{n+2}}{c(r^2 t)} = \omega_n c_t^{\mathbb{R}^n}. \quad (3.13)$$

As a result, we get (3.11). Observe that the limit in (3.13) also does not depend on the choice of $x \in \mathcal{R}_n^*$, which suffices to show (3.10).

Step 2 $\mathbf{m} = \tilde{c}\mathcal{H}^n$, for the constant \tilde{c} obtained in Step 1.

Reprising the same arguments as in Step 1, we know that $\mathcal{R}_n = \mathcal{R}_n^*$ (In fact, L^2 -strong convergence of $\{g_t^{X_i}\}$ on any $B_R(0_n) \subset \mathbb{R}^n$ is also valid when $x \in \mathcal{R}_n$ by [BGHZ23, Theorem 3.11]). This implies $\mathbf{m} = \tilde{c}\mathcal{H}^n \llcorner \mathcal{R}_n$. To complete the proof of Step 2, we need nothing but $\mathcal{H}^n \ll \mathbf{m}$, which, together with Theorem 2.25 would give $\mathcal{H}^n(X \setminus \mathcal{R}_n) = 0$. This is sufficient to conclude.

For any $x \in X \setminus \mathcal{R}_n$, and any sequence $\{r_i\}$ with $r_i \rightarrow 0$, after passing to a subsequence, there exists a pointed RCD(0, N) space $(X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty, x_\infty)$ such that

$$(X_i, \mathbf{d}_i, \mathbf{m}_i, x) := \left(X, \frac{1}{r_i} \mathbf{d}, \frac{\mathbf{m}}{\mathbf{m}(B_{r_i}(x))}, x \right) \xrightarrow{\text{pmGH}} (X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty, x_\infty).$$

When i is sufficiently large, recall again on each X_i , $c(r_i^2 t)g_t^{X_i} = r_i^2 \mathbf{m}(B_{r_i}(x))g_{X_i}$. In particular, we know from Theorem 3.3 that $r_i^2 \mathbf{m}(B_{r_i}(x)) \leq C(K, N)c(r_i^2 t)$. Since $(X_\infty, \mathbf{d}_\infty)$ is not a single point, using Theorems 2.36 and 2.37, and (3.11), we see

$$\lim_{i \rightarrow \infty} \frac{\mathbf{m}(B_{r_i}(x))}{r_i^n} \in (0, C(K, N)).$$

In particular,

$$C(K, N) \geq \limsup_{r \rightarrow 0} \frac{\mathbf{m}(B_r(x))}{r^n} \geq \liminf_{r \rightarrow 0} \frac{\mathbf{m}(B_r(x))}{r^n} > 0. \quad (3.14)$$

Set

$$X_\tau := \left\{ x \in X : \liminf_{r \rightarrow 0} \frac{\mathbf{m}(B_r(x))}{r^n} \geq \tau \right\},$$

and notice that $X = \bigcup_{\tau > 0} X_\tau$ by (3.14). Applying [AT04, Theorem 2.4.3] then implies

$$\mathcal{H}^n \llcorner X_\tau \ll \mathbf{m} \llcorner X_\tau, \quad \forall \tau > 0,$$

from which we conclude.

Step 3 $(X, \mathbf{d}, \mathcal{H}^n)$ is an $\text{RCD}(K, n)$ space.

Without loss of generality, assume $\mathbf{m} = \mathcal{H}^n$. We first treat the case that $(X, \mathbf{d}, \mathcal{H}^n)$ is compact. By Theorem 3.2, it suffices to show

$$\inf_{x \in X} \inf_{s \in (0,1)} \frac{\mathcal{H}^n(B_s(x))}{s^n} > 0. \quad (3.15)$$

Assume on the contrary that (3.15) does not hold, then for any $\epsilon > 0$, there exists $x_\epsilon \in X$, such that $\inf_{s \in (0,1)} s^{-n} \mathcal{H}^n(B_s(x_\epsilon)) < \epsilon$. By (2.2),

$$\frac{\mathcal{H}^n(B_r(x_\epsilon))}{r^n} < \epsilon, \quad \text{for some } r = r(\epsilon) \leq \Psi(\epsilon | K, N, \text{diam}(X, \mathbf{d}), \mathcal{H}^n(X)).$$

As a consequence, there exists a sequence $\{x_i\} \subset X$, a sequence $\{r_i\} \subset (0, \infty)$ with $r_i \rightarrow 0$ and a pointed $\text{RCD}(0, N)$ space $(X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty, x_\infty)$, such that

$$\lim_{i \rightarrow \infty} \frac{\mathcal{H}^n(B_{r_i}(x_i))}{r_i^n} = 0, \quad (3.16)$$

and

$$(X_i, \mathbf{d}_i, \mathbf{m}_i, x_i) := \left(X_i, \frac{1}{r_i} \mathbf{d}, \frac{\mathbf{m}}{\mathbf{m}(B_{r_i}(x_i))}, x_i \right) \xrightarrow{\text{pmGH}} (X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty, x_\infty).$$

Again $c(r_i^2 t) g_t^{X_i} = r_i^2 \mathbf{m}(B_{r_i}(x_i)) g_{X_i}$ on each X_i , and $\{g_t^{X_i}\}$ L^2 -strongly converges to 0 on $B_R(x_\infty)$ for any $R > 0$ by (3.16), which contradicts Proposition 3.7.

As for the non-compact case, it suffices to repeat Step 1-3 and apply Theorem 3.2 again on any $B_R(x) \subset X$. □

3.3 Non-compact IHKI $\text{RCD}(0, n)$ spaces

We start by proving the following theorem in this subsection.

Theorem 3.9. *Suppose $(X, \mathbf{d}, \mathcal{H}^{n-1})$ is a non-collapsed $\text{RCD}(n-2, n-1)$ space with $n \geq 2$. If $g_1^{C(X)} \geq c g_{C(X)}$ for some $c > 0$, then (X, \mathbf{d}) is isometric to $(\mathbb{S}^{n-1}, \mathbf{d}_{\mathbb{S}^{n-1}})$.*

We need some preparations. According to Remark 2.12, $(C(X), \mathbf{d}_{C(X)}, \mathbf{m}_{C(X)})$ is an $\text{RCD}(0, n)$ space. In addition, by applying Theorem 2.27, Theorem 3.1

and the splitting theorem for $\text{RCD}(0, n)$ spaces (see [G13, Theorem 1.4], [G14]), $(C(X), \mathbf{d}_{C(X)}, \mathbf{m}_{C(X)})$ is also non-collapsed, which means that $\mathbf{m}_{C(X)} = \mathcal{H}^n$.

To fix the notation, we use (2.7), and set $\alpha = (2 - n)/2$, $\nu_j = \sqrt{\alpha^2 + \mu_j}$ for every $j \in \mathbb{N}$. It is notable that $\mu_1 \geq n$ by [K15b, Corollary 1.3]. For any $\text{RCD}(K, N)$ space $(Y, \mathbf{d}_Y, \mathbf{m}_Y)$, we define

$$\begin{aligned} \rho_t^Y : Y &\longrightarrow (0, \infty) \\ y &\longmapsto \rho^Y(y, y, t). \end{aligned}$$

The validity of limit processes in the proof of Theorem 3.9 can be verified by the following estimates. We check one of them for reader's convenience.

Lemma 3.10. *There exists $C = C(n, \text{diam}(X, \mathbf{d}))$, such that the following estimates hold.*

1. $\sup_{x \in X} \sum_{j=k}^{\infty} I_{\nu_j}(r) \phi_j^2(x) \leq C \left(\frac{r}{2}\right)^{k \frac{1}{2(n-1)}}$, $\forall r \in (0, 1)$, $\forall k \in \mathbb{N}_+$.
2. $I_{\nu_j}(r) \mu_j \leq C j^2 \left(\frac{r}{2}\right)^{\nu_j} \leq C j^2 \left(\frac{r}{2}\right)^{j \frac{1}{n-1}}$, $\forall r \in (0, 1)$, $\forall j \in \mathbb{N}$.
3. $\sum_{j=k}^{\infty} I_{\nu_j}(r) \mu_j \leq C \left(\frac{r}{2}\right)^{k \frac{1}{2(n-1)}}$, $\forall r \in (0, 1)$, $\forall k \in \mathbb{N}_+$.

Proof of 1. According to Proposition 2.10, there exists $C = C(n, \text{diam}(X, \mathbf{d}))$, such that for any $x \in X$,

$$\begin{aligned} \sum_{j=k}^{\infty} I_{\nu_j}(r) \phi_j^2(x) &\leq C \sum_{j=k}^{\infty} I_{\nu_j}(r) j^{n-1} \\ &= C \sum_{j=k}^{\infty} j^{n-1} \sum_{l=0}^{\infty} \frac{1}{l! \Gamma(\nu_j + l + 1)} \left(\frac{r}{2}\right)^{2l + \nu_j} \\ &\leq C \sum_{j=k}^{\infty} j^{n-1} \left(\frac{r}{2}\right)^{\nu_j} \exp\left(\frac{r^2}{4}\right) \\ &\leq C \sum_{j=k}^{\infty} j^{n-1} \left(\frac{r}{2}\right)^{j \frac{1}{n-1}} \\ &\leq C \left(\frac{r}{2}\right)^{k \frac{1}{2(n-1)}} \sum_{j=k}^{\infty} j^{n-1} \left(\frac{r}{2}\right)^{j \frac{1}{2(n-1)}} \leq C \left(\frac{r}{2}\right)^{k \frac{1}{2(n-1)}}. \end{aligned}$$

□

Notice that $(C(X), \mathbf{d}_{C(X)}, \mathcal{H}^n)$ has maximal volume growth, and its blow down is itself. Applying the large time behavior of the heat kernel [JLZ16, Theorem 1.3] shows

$$\rho_t^{C(X)} \equiv \frac{n\omega_n}{\mathcal{H}^{n-1}(X)} (4\pi t)^{-\frac{n}{2}}, \quad \forall t > 0. \quad (3.17)$$

Lemma 3.11 and Lemma 3.12 are also useful in the proof of Theorem 3.9.

Lemma 3.11. *Let $(Y_i, \mathbf{d}_i, \mathbf{m}_i)$ be two $\text{RCD}(K, N)$ spaces such that $\rho_{2t}^{Y_i}$ are constant functions for some $t > 0$ ($i = 1, 2$). Then on $Y_1 \times Y_2$,*

$$g_t^{Y_1 \times Y_2}(y_1, y_2) = \rho_{2t}^{Y_1}(y_1)g_t^{Y_2}(y_2) + \rho_{2t}^{Y_2}(y_2)g_t^{Y_1}(y_1).$$

That is, for any $f \in \text{Lip}_c(Y_1 \times Y_2, \mathbf{d}_{Y_1 \times Y_2})$, denote by $f^{(y_1)} : y_2 \mapsto f(y_1, y_2)$ for any fixed y_1 , and $f^{(y_2)} : y_1 \mapsto f(y_1, y_2)$ for any fixed y_2 , it holds that

$$\begin{aligned} & g_t^{Y_1 \times Y_2}(\nabla^{Y_1 \times Y_2} f, \nabla^{Y_1 \times Y_2} f)(y_1, y_2) \\ &= \rho_{2t}^{Y_1}(y_1)g_t^{Y_2}(\nabla^{Y_2} f^{(y_1)}, \nabla^{Y_2} f^{(y_1)})(y_2) + \rho_{2t}^{Y_2}(y_2)g_t^{Y_1}(\nabla^{Y_1} f^{(y_2)}, \nabla^{Y_1} f^{(y_2)})(y_1), \end{aligned}$$

for $\mathbf{m}_{Y_1 \times Y_2}$ -a.e. (y_1, y_2) in $Y_1 \times Y_2$.

Proof. Recalling (2.13), (2.14) and the definition of $g_t^{Y_1 \times Y_2}$ in Theorem 3.3, we have

$$\begin{aligned} & g_t^{Y_1 \times Y_2}(y_1, y_2) \\ &= \int_{Y_1 \times Y_2} \sum_{i=0}^1 \rho^{Y_{i+1}}(y_{i+1}, y'_{i+1}, t) d_{y_{2-i}} \rho^{Y_{2-i}}(y_{2-i}, y'_{2-i}, t) \\ & \quad \otimes \sum_{i=0}^1 \rho^{Y_{i+1}}(y_{i+1}, y'_{i+1}, t) d_{y_{2-i}} \rho^{Y_{2-i}}(y_{2-i}, y'_{2-i}, t) d\mathbf{m}_1(y'_1) d\mathbf{m}_2(y'_2) \\ &= \rho_{2t}^{Y_1}(y_1)g_t^{Y_2}(y_2) + \rho_{2t}^{Y_2}(y_2)g_t^{Y_1}(y_1) + I_1(y_1, y_2) + I_2(y_1, y_2), \end{aligned}$$

where

$$I_1(y_1, y_2) = \frac{1}{4} \int_{Y_1 \times Y_2} d_{y_1} (\rho^{Y_1}(y_1, y'_1, t))^2 \otimes d_{y_2} (\rho^{Y_2}(y_2, y'_2, t))^2 d\mathbf{m}_1(y'_1) d\mathbf{m}_2(y'_2),$$

$$I_2(y_1, y_2) = \frac{1}{4} \int_{Y_1 \times Y_2} d_{y_2} (\rho^{Y_2}(y_2, y'_2, t))^2 \otimes d_{y_1} (\rho^{Y_1}(y_1, y'_1, t))^2 d\mathbf{m}_1(y'_1) d\mathbf{m}_2(y'_2),$$

By our assumption, for $i = 1, 2$, we have

$$\left(y_i \mapsto d_{y_i} \int_{Y_i} (\rho^{Y_i}(y_i, y'_i, t))^2 d\mathbf{m}_i(y'_i) \right) = 0 \quad \text{in } L^2(T^*(Y_i, \mathbf{d}_i, \mathbf{m}_i)).$$

Therefore $I_1(y_1, y_2) = 0$ and $I_2(y_1, y_2) = 0$ follow from the local Hille's theorem (see for example [BGHZ23, Proposition 3.4]). \square

Lemma 3.12. *Under the assumption of Lemma 3.11, if moreover there exist $c_1, c_2, t > 0$, such that $g_t^{Y_1} = c_1 g_{Y_1}$ and*

$$g_t^{Y_1 \times Y_2} \geq c_2 g_{Y_1 \times Y_2} \quad (\text{resp. } g_t^{Y_1 \times Y_2} = c_2 g_{Y_1 \times Y_2}),$$

then there exists $c_3 > 0$, such that

$$g_t^{Y_2} \geq c_3 g_{Y_2} \quad (\text{resp. } g_t^{Y_2} = c_3 g_{Y_2}).$$

Proof. Since the proofs of both cases are almost the same, we only give the proof of in the case that $g_t^{Y_1 \times Y_2} \geq c_2 g_{Y_1 \times Y_2}$.

Fix a ball $B_R^{Y_1}(\tilde{y}_1) \subset Y_1$, by [MN19, Lemma 3.1], there exists a cut-off function $\phi \in \text{Lip}_c(Y_1, \mathbf{d}_1)$ such that

$$\phi|_{B_R^{Y_1}(\tilde{y}_1)} \equiv 1, \quad \phi|_{Y_1 \setminus B_{2R}^{Y_1}(\tilde{y}_1)} \equiv 0.$$

Now for any $\varphi \in H^{1,2}(Y_2, \mathbf{d}_2, \mathbf{m}_2)$, set $f : (y_1, y_2) \mapsto \phi(y_1)\varphi(y_2)$. Then it follows from (2.12) and Lemma 3.11 that for $\mathbf{m}_{Y_1 \times Y_2}$ -a.e. (x, y) in $B_R^{Y_1}(\tilde{y}_1) \times Y_2$,

$$\begin{aligned} & \rho_{2t}^{Y_1}(y_1) g_t^{Y_2} (\nabla^{Y_2} \varphi, \nabla^{Y_2} \varphi) (y_2) \\ &= \phi^2(y_1) \rho_{2t}^{Y_1}(y_1) g_t^{Y_2} (\nabla^{Y_2} \varphi, \nabla^{Y_2} \varphi) (y_2) + c_1 \varphi^2(y_2) \rho_{2t}^{Y_2}(y_2) |\nabla \phi|^2(y_1) \\ &= \rho_{2t}^{Y_1}(y_1) g_t^{Y_2} (\nabla^{Y_2} f^{(y_1)}, \nabla^{Y_2} f^{(y_1)}) (y_2) + \rho_{2t}^{Y_2}(y_2) g_t^{Y_1} (\nabla^{Y_1} f^{(y_2)}, \nabla^{Y_1} f^{(y_2)}) (y_1) \\ &= g_t^{Y_1 \times Y_2} (\nabla^{Y_1 \times Y_2} f, \nabla^{Y_1 \times Y_2} f) (y_1, y_2) \\ &\geq c_2 g_{Y_1 \times Y_2} (\nabla^{Y_1 \times Y_2} f, \nabla^{Y_1 \times Y_2} f) (y_1, y_2) = c_2 |\nabla^{Y_2} \varphi|^2(y_2). \end{aligned}$$

In particular,

$$\rho_{2t}^{Y_1}(y_1) g_t^{Y_2} (\nabla^{Y_2} \varphi, \nabla^{Y_2} \varphi) (y_2) \geq c_2 |\nabla^{Y_2} \varphi|^2(y_2), \quad \mathbf{m}_2\text{-a.e. } y_2 \in Y_2.$$

Since $\varphi \in H^{1,2}(Y_2, \mathbf{d}_2, \mathbf{m}_2)$ is taken to be arbitrary, we complete the proof by setting $c_3 := c_2 (\rho_{2t}^{Y_1})^{-1}$. \square

Proof of Theorem 3.9. We start by considering the case that $n \geq 4$.

For any fixed $(r_0, x_0) \in C(X)$ and any $\varphi \in \text{Lip}(X, \mathbf{d})$, take $f \in C^\infty((0, \infty))$ such that $\text{supp } f \in (r_0/4, 3r_0)$ and $f \equiv 1$ on $(r_0/2, 2r_0)$. Then Proposition 2.13 and (2.8) yield that for \mathcal{H}^n -a.e. $(r, x) \in B_{r_0/2}^{C(X)}(r_0, x_0)$,

$$\begin{aligned}
cr^{-2} |\nabla\varphi|^2(x) &= c |\nabla(f\varphi)|_{C(X)}^2(r, x) \\
&\leq g_1^{C(X)}(\nabla(f\varphi), \nabla(f\varphi))(r, x) \\
&= \frac{1}{4} r^{2\alpha} \sum_{j=1}^{\infty} \int_0^{\infty} s \exp\left(-\frac{r^2 + s^2}{2}\right) I_{\nu_j}\left(\frac{rs}{2}\right)^2 ds \langle \nabla(f\varphi), \nabla\phi_j \rangle_{C(X)}^2(r, x) \\
&= \frac{1}{4} r^{2\alpha-4} \sum_{j=1}^{\infty} \int_0^{\infty} s \exp\left(-\frac{r^2 + s^2}{2}\right) I_{\nu_j}\left(\frac{rs}{2}\right)^2 ds \langle \nabla\varphi, \nabla\phi_j \rangle^2(x) \\
&= \frac{1}{2} r^{2\alpha-4} \sum_{j=1}^{\infty} \exp\left(-\frac{r^2}{2}\right) I_{\nu_j}\left(\frac{r^2}{2}\right) \langle \nabla\varphi, \nabla\phi_j \rangle^2(x),
\end{aligned} \tag{3.18}$$

where the last equality follows from the semigroup property of $\{h_t^{C(X)}\}_{t>0}$.

In the remaining part of the proof, we just denote by $|\cdot|$ the pointwise norm on $L^2(T^*(X, \mathbf{d}, \mathcal{H}^{n-1}))$ for notation convenience.

Combining the fact that $|\langle \nabla\varphi, \nabla\phi_j \rangle| \leq |\nabla\varphi| |\nabla\phi_j|$, \mathcal{H}^{n-1} -a.e. in X , with last equality of (3.18) implies

$$c |\nabla\varphi|^2 \leq \frac{1}{2} r^{-n} \sum_{j=1}^{\infty} \exp\left(-\frac{r^2}{2}\right) I_{\nu_j}\left(\frac{r^2}{2}\right) |\nabla\varphi|^2 |\nabla\phi_j|^2 \quad \mathcal{H}^n\text{-a.e. } (r, x) \in B_{r_0/2}^{C(X)}(r_0, x_0).$$

In particular, taking $\varphi = \mathbf{d}(x_0, \cdot)$ which satisfies that $|\nabla\varphi| \equiv 1$, we have

$$c \leq \frac{1}{2} r^{-n} \exp\left(-\frac{r^2}{2}\right) \sum_{j=1}^{\infty} I_{\nu_j}\left(\frac{r^2}{2}\right) |\nabla\phi_j|^2 \quad \mathcal{H}^n\text{-a.e. } (r, x) \in B_{r_0/2}^{C(X)}(r_0, x_0). \tag{3.19}$$

Integration of (3.19) on X then gives

$$c \mathcal{H}^{n-1}(X) \leq \frac{1}{2} r^{-n} \exp\left(-\frac{r^2}{2}\right) \sum_{j=1}^{\infty} I_{\nu_j}\left(\frac{r^2}{2}\right) \mu_j \quad \mathcal{L}^1\text{-a.e. } r \in (r_0/2, 2r_0). \tag{3.20}$$

In fact, (3.20) holds for any $r > 0$ due to the arbitrariness of $r_0 > 0$, which is still denoted as (3.20).

If $n \geq 4$ and $\mu_1 > n - 1$, then $\nu_j \geq \nu_1 > n/2$, for all $j \in \mathbb{N}_+$. However, Lemma 3.10 implies that the right hand side of (3.20) vanishes as $r \rightarrow 0$. Thus a contradiction occurs. Therefore $\mu_1 = n - 1$ when $n \geq 4$.

By Theorem 3.1 and Obata's first eigenvalue rigidity theorem [K15b, Theorem 1.2], there exists a non-collapsed RCD($n - 3, n - 2$) space $(X', \mathbf{d}_{X'}, \mathcal{H}^{n-2})$, such that $(C(X), \mathbf{d}_{C(X)})$ is isometric to $(\mathbb{R} \times C(X'), \sqrt{\mathbf{d}_{\mathbb{R}}^2 + \mathbf{d}_{C(X')}^2})$.

From (2.14) and (3.17), we know

$$\rho_t^{C(X)} \equiv \frac{n\omega_n}{\mathcal{H}^{n-1}(X)}(4\pi t)^{\frac{n-1}{2}}.$$

Using Lemmas 3.11 and 3.12, we see that $g_1^{C(X')} \geq c'g_{C(X')}$ for some $c' > 0$. It is now sufficient to deal with the case that $n = 3$.

Repeating the previous arguments, we have $\mu_1 = 2$. We claim that $\mu_2 = 2$. If $\mu_2 > 2$, then the integration of (3.19) on any measurable set $\Omega \subset X$ yields

$$\begin{aligned} c\mathcal{H}^2(\Omega) &\leq Cr^{-2} \sum_{j=1}^{\infty} I_{\nu_j} \left(\frac{r^2}{2t} \right) \int_{\Omega} |\nabla \phi_j|^2 d\mathcal{H}^2 \\ &\leq Cr^{-2} I_{\nu_1} \left(\frac{r^2}{2t} \right) \int_{\Omega} |\nabla \phi_1|^2 d\mathcal{H}^2 + r^{-2} \sum_{j=2}^{\infty} I_{\nu_j} \left(\frac{r^2}{2t} \right) \int_X |\nabla \phi_j|^2 d\mathcal{H}^2 \\ &\rightarrow C \int_{\Omega} |\nabla \phi_1|^2 d\mathcal{H}^2 \text{ as } r \rightarrow 0. \end{aligned}$$

for some $C = C(n, \text{diam}(X, \mathbf{d}))$. The arbitrariness of Ω , together with the Lebesgue differentiation theorem shows that $|\nabla \phi_1|^2 \geq c_0 := c^{-1}C > 0$, \mathcal{H}^2 -a.e.

Consider the Laplacian of ϕ_1^α for any even integer α , and calculate as follows:

$$\begin{aligned} \Delta \phi_1^\alpha &= \alpha(\alpha - 1)|\nabla \phi_1|^2 \phi_1^{\alpha-2} + \alpha \phi_1^{\alpha-1} \Delta \phi_1 \\ &= \alpha(\alpha - 1)|\nabla \phi_1|^2 \phi_1^{\alpha-2} - \alpha \phi_1^{\alpha-1} (n - 1) \phi_1 \\ &= \alpha \phi_1^{\alpha-2} ((\alpha - 1)|\nabla \phi_1|^2 - (n - 1)\phi_1^2) \\ &\geq \alpha \phi_1^{\alpha-2} ((\alpha - 1)c_0 - C(n, \text{diam}(X, \mathbf{d}))), \quad \mathcal{H}^2\text{-a.e.} \end{aligned}$$

As a result, the integer α can be chosen to be sufficiently large such that ϕ_1^α is superharmonic. However, any superharmonic function on a compact RCD space must be a constant function (see for instance [GR19, Theorem 2.3]). A contradiction. Therefore $\mu_2 = 2$.

According to [K15b, Theorem 1.4], (X, \mathbf{d}) must be isometric to either $(\mathbb{S}^2, \mathbf{d}_{\mathbb{S}^2})$ or $(\mathbb{S}_+^2, \mathbf{d}_{\mathbb{S}_+^2})$. Thus $(C(X), \mathbf{d}_{C(X)})$ must be isometric to either $(\mathbb{R}^3, \mathbf{d}_{\mathbb{R}^3})$ or $(\mathbb{R}_+^3, \mathbf{d}_{\mathbb{R}_+^3})$.

Notice that on $\mathbb{R}_+^n := \{(x_1, \dots, x_n) \in \mathbb{R}^n : x_n > 0\}$,

$$g_t^{\mathbb{R}_+^n} \left(\frac{\partial}{\partial x_n}, \frac{\partial}{\partial x_n} \right) (x_1, \dots, x_n) = c_n t^{-\frac{n+2}{2}} \left(\frac{1 - \exp\left(-\frac{x_n^2}{2t}\right)}{2} + \frac{x_n^2}{4t} \exp\left(-\frac{x_n^2}{2t}\right) \right).$$

It is clear that

$$\lim_{x_3 \rightarrow 0^+} g_t^{\mathbb{R}_+^3} \left(\frac{\partial}{\partial x_3}, \frac{\partial}{\partial x_3} \right) (x_1, x_2, x_3) = 0,$$

which contradicts our assumption.

When $n = 2$, set $Y = C(X) \times \mathbb{R}$, and notice that $g_1^Y \geq c' g_Y$ for some $c' > 0$ by (3.17), Lemma 3.11 and Lemma 3.12, which shall be verified in the same way as previous arguments. Thus (Y, \mathbf{d}_Y) must be isometric to $(\mathbb{R}^3, \mathbf{d}_{\mathbb{R}^3})$ and $(C(X), \mathbf{d}_{C(X)})$ must be isometric to $(\mathbb{R}^2, \mathbf{d}_{\mathbb{R}^2})$. \square

As an application of Theorem 3.9, we prove Theorem 1.14.

Proof of Theorem 1.14. It follows from Theorem 1.13 that $\mathbf{m} = c\mathcal{H}^n$ for some $c > 0$, and $(X, \mathbf{d}, \mathcal{H}^n)$ is an $\text{RCD}(0, n)$ space. Without loss of generality, we may assume that $\mathbf{m} = \mathcal{H}^n$.

The subsequent blow-down arguments in this proof are almost the same as that in the proof of Theorem 1.13, and we omit the details.

Take $\{r_i\}$ with $r_i \rightarrow \infty$, and a pointed $\text{RCD}(0, n)$ space $(X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty, x_\infty)$ such that

$$(X_i, \mathbf{d}_i, \mathbf{m}_i, x) := \left(X, \frac{1}{r_i} \mathbf{d}, \frac{\mathbf{m}}{\mathbf{m}(B_{r_i}(x))}, x \right) \xrightarrow{\text{pmGH}} (X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty, x_\infty).$$

Again on each X_i , $c(r_i^2 t) g_t^{X_i} = r_i^2 \mathbf{m}(B_{r_i}(x)) g_{X_i}$. Applying (3.4) and Proposition 3.7 implies that

$$e(t) g_t^{X_\infty} = g_{X_\infty}, \quad \forall t > 0, \quad (3.21)$$

where the function $e = e(t)$ is defined as

$$e(t) := \lim_{i \rightarrow \infty} \frac{c(r_i^2 t)}{r_i^2 \mathbf{m}(B_{r_i}(x))}.$$

Therefore, Theorem 1.13 implies that $\mathbf{m}_\infty = \tilde{c}\mathcal{H}^n$ for some $\tilde{c} > 0$. In particular, it follows from [BGHZ23, Theorem 1.6] that

$$\mathbf{m}_i = \frac{\mathbf{m}}{\mathbf{m}(B_{r_i}(x))} = c_i \mathcal{H}_{\mathbf{d}_i}^n$$

for some $\tilde{c}_i > 0$ whenever i is sufficiently large. It is clear that $\lim_{i \rightarrow \infty} \tilde{c}_i = \tilde{c}$.

Since now

$$\frac{\mathbf{m}(B_{2r_i}(x))}{\mathbf{m}(B_{r_i}(x))} = \mathbf{m}_i(B_2^{X_i}(x)) = c_i \mathcal{H}_{\mathbf{d}_i}^n(B_2^{X_i}(x)) = c_i \frac{1}{r_i^n} \mathbf{m}(B_{2r_i}(x)),$$

which yields that

$$\lim_{i \rightarrow \infty} \frac{\mathbf{m}(B_{r_i}(x))}{r_i^n} = \tilde{c}^{-1}. \quad (3.22)$$

As a result, combining [DG16, Theorem 1.1] with (3.21) and (3.22) yields that $(X_\infty, \mathbf{d}_\infty, \mathcal{H}^n)$ is an IHKI RCD(0, n) space, and is an Euclidean cone. Hence it follows directly from Theorem 3.9 that $(X_\infty, \mathbf{d}_\infty)$ is isometric to $(\mathbb{R}^n, \mathbf{d}_{\mathbb{R}^n})$. Finally, it remains to use the volume rigidity theorem for non-collapsed almost RCD(0, n) spaces [DG18, Theorem 1.6] to conclude. \square

The following corollary can be proved by using similar arguments as in the proof of Theorem 1.14.

Corollary 3.13. *Let $(X, \mathbf{d}, \mathcal{H}^n)$ be a non-collapsed RCD(0, n) space. If there exists a function $c(t)$ such that*

1. $c(t)g_t \geq g, \forall t > 0,$
2. $\liminf_{t \rightarrow \infty} t^{-(n+2)}c(t^2) > 0.$

Then (X, \mathbf{d}) is isometric to $(\mathbb{R}^n, \mathbf{d}_{\mathbb{R}^n})$.

4 The isometric immersion into Euclidean space

The main purpose of this section is to prove Theorem 1.16. To begin with, let us recall a useful result (Theorem 4.3) in [H21], which plays an important role in this section.

Definition 4.1 (Regular map). Let $(X, \mathbf{d}, \mathbf{m})$ be an $\text{RCD}(K, N)$ space. Then a map $F := (\varphi_1, \dots, \varphi_k) : X \rightarrow \mathbb{R}^k$ is said to be regular if each φ_i is in $D(\Delta)$ with $\Delta\varphi_i \in L^\infty(\mathbf{m})$.

Definition 4.2 (Locally uniformly δ -isometric immersion). Let $(X, \mathbf{d}, \mathbf{m})$ be an $\text{RCD}(K, N)$ space and $F := (\varphi_1, \dots, \varphi_k) : X \rightarrow \mathbb{R}^k$ be a locally Lipschitz map. F is said to be a locally uniformly δ -isometric immersion on $B_r(x_0) \subset X$ if for any $x \in B_r(x_0)$ it holds that

$$\frac{1}{\mathbf{m}(B_s(x))} \int_{B_{\delta^{-1}s}(x)} |F^*g_{\mathbb{R}^k} - g_X| \, \mathbf{d}\mathbf{m} < \delta, \quad \forall s \in (0, r).$$

Theorem 4.3 ([H21, Theorem 3.4]). Let $(X, \mathbf{d}, \mathbf{m})$ be an $\text{RCD}(K, N)$ space with $\dim_{\mathbf{d}, \mathbf{m}}(X) = n$ and let $F := (\varphi_1, \dots, \varphi_k) : X \rightarrow \mathbb{R}^k$ be a regular map with

$$\sum_{i=1}^k \|\|\nabla\varphi_i\|\|_{L^\infty(\mathbf{m})} \leq C.$$

If F is a locally uniformly δ -isometric immersion on some ball $B_{4r}(x_0) \subset X$. Then the following statements hold.

1. For any $s \in (0, r)$, $\mathbf{d}_{\text{GH}}(B_s(x_0), B_s(0_n)) \leq \Psi(\delta|K, N, k, C)s$, where \mathbf{d}_{GH} is the Gromov-Hausdorff distance.
2. $F|_{B_r(x_0)}$ is $(1 + \Psi(\delta|K, N, k, C))$ -bi-Lipschitz from $B_r(x_0)$ to $F(B_r(x_0)) \subset \mathbb{R}^k$.

From now on, we let $(X, \mathbf{d}, \mathcal{H}^n)$ be a fixed compact non-collapsed $\text{RCD}(K, n)$ space, and we assume that

$$g = \sum_{i=1}^m d\phi_i \otimes d\phi_i, \tag{4.1}$$

where g is the canonical Riemannian metric of $(X, \mathbf{d}, \mathcal{H}^n)$ and each ϕ_i is an eigenfunction of $-\Delta$ with corresponding eigenvalue μ_i ($i = 1, \dots, m$). To fix the notation, denote by C a constant with

$$C = C \left(K, m, n, \text{diam}(X, \mathbf{d}), \mathcal{H}^n(X), \mu_1, \dots, \mu_m, \|\phi_1\|_{L^2(\mathcal{H}^n)}, \dots, \|\phi_m\|_{L^2(\mathcal{H}^n)} \right),$$

which may vary from line to line, and by $\mathbf{M}_{n \times n}(\mathbb{R})$ the set of all $n \times n$ real matrices equipped with the Euclidean metric on \mathbb{R}^{n^2} , and by I_n the $n \times n$ identity matrix.

Lemma 4.4. *Each $\langle \nabla \phi_i, \nabla \phi_j \rangle$ is a Lipschitz function ($i, j = 1, \dots, m$). In particular,*

$$\sum_{i,j=1}^m \|\nabla \langle \nabla \phi_i, \nabla \phi_j \rangle\|_{L^\infty(\mathcal{H}^n)} \leq C. \quad (4.2)$$

Proof. We first show that $|\nabla \phi_1|^2 \in \text{Lip}(X, \mathbf{d})$. Taking trace of (4.1) gives

$$\sum_{i=1}^m |\nabla \phi_i|^2 = \langle g, g \rangle = n. \quad (4.3)$$

Using the Bochner's inequality (2.1), for any $\varphi \in \text{Test}F_+(X, \mathbf{d}, \mathcal{H}^n)$, we get

$$\int_X |\nabla \phi_1|^2 \Delta \varphi d\mathcal{H}^n \geq 2 \int_X \varphi \left((K - \mu_1) |\nabla \phi_1|^2 + \frac{1}{n} \mu_1^2 \phi_1^2 \right) d\mathcal{H}^n \geq -C \int_X \varphi d\mathcal{H}^n, \quad (4.4)$$

where the last inequality comes from Proposition 2.10. Owing to (4.3) and (4.4),

$$\int_X |\nabla \phi_1|^2 \Delta \varphi d\mathcal{H}^n = - \sum_{j=2}^m \int_X |\nabla \phi_j|^2 \Delta \varphi d\mathcal{H}^n \leq C \int_X \varphi d\mathcal{H}^n. \quad (4.5)$$

Since $\text{Test}F_+(X, \mathbf{d}, \mathcal{H}^n)$ is dense in $H_+^{1,2}(X, \mathbf{d}, \mathcal{H}^n)$, and $\phi_1 \in \text{Test}F(X, \mathbf{d}, \mathcal{H}^n)$ with $|\nabla \phi_1|^2 \in H^{1,2}(X, \mathbf{d}, \mathcal{H}^n)$, the combination of these facts with (4.4) and (4.5) yields that for any $\varphi \in H_+^{1,2}(X, \mathbf{d}, \mathcal{H}^n)$,

$$\left| \int_X \langle \nabla |\nabla \phi_1|^2, \nabla \varphi \rangle d\mathcal{H}^n \right| = \left| \int_X |\nabla \phi_1|^2 \Delta \varphi d\mathcal{H}^n \right| \leq C \int_X |\varphi| d\mathcal{H}^n \leq C \|\varphi\|_{L^2(\mathcal{H}^n)}. \quad (4.6)$$

Note that (4.6) also holds for any $\varphi \in \text{Lip}(X, \mathbf{d})$ because $\varphi + |\varphi|, |\varphi| - \varphi \in \text{Lip}(X, \mathbf{d})$. Since $\text{Test}F(X, \mathbf{d}, \mathcal{H}^n)$ is dense in $H^{1,2}(X, \mathbf{d}, \mathcal{H}^n)$, we have

$$\left| \int_X \langle \nabla |\nabla \phi_1|^2, \nabla \varphi \rangle d\mathcal{H}^n \right| \leq C \|\varphi\|_{L^2(\mathcal{H}^n)}, \quad \forall \varphi \in H^{1,2}(X, \mathbf{d}, \mathcal{H}^n).$$

Consequently, the linear functional

$$\begin{aligned} T : H^{1,2}(X, \mathbf{d}, \mathcal{H}^n) &\longrightarrow \mathbb{R} \\ \varphi &\longmapsto \int_X \langle \nabla |\nabla \phi_1|^2, \nabla \varphi \rangle d\mathcal{H}^n \end{aligned}$$

can be continuously extended to a bounded linear functional on $L^2(\mathcal{H}^n)$. Applying the Riesz representation theorem, there exists a unique $h \in L^2(\mathcal{H}^n)$, such that

$$T(\varphi) = - \int_X \varphi h d\mathcal{H}^n, \quad \forall \varphi \in L^2(\mathcal{H}^n).$$

Therefore $|\nabla\phi_1|^2 \in D(\Delta)$ with $\|\Delta|\nabla\phi_1|^2\|_{L^2(\mathcal{H}^n)} \leq C$. Using (4.6) again, and repeating the previous arguments, we have

$$\left| \int_X \Delta |\nabla\phi_1|^2 \varphi d\mathcal{H}^n \right| \leq C \int_X |\varphi| d\mathcal{H}^n, \quad \forall \varphi \in L^1(\mathcal{H}^n),$$

because $\text{Test}F(X, \mathbf{d}, \mathcal{H}^n)$ is also dense in $L^1(\mathcal{H}^n)$. Thus $\|\Delta|\nabla\phi_1|^2\|_{L^\infty(\mathcal{H}^n)} \leq C$.

According to Theorem 3.6, $\|\nabla|\nabla\phi_1|^2\|_{L^\infty(\mathcal{H}^n)} \leq C$. For any other $|\nabla\phi_i|^2$, the estimates of $\|\Delta|\nabla\phi_i|^2\|_{L^\infty(\mathcal{H}^n)}$ and $\|\nabla|\nabla\phi_i|^2\|_{L^\infty(\mathcal{H}^n)}$ can be obtained along the same lines. Rewrite these estimates as

$$\sum_{i=1}^m \left(\|\Delta|\nabla\phi_i|^2\|_{L^\infty(\mathcal{H}^n)} + \|\nabla|\nabla\phi_i|^2\|_{L^\infty(\mathcal{H}^n)} \right) \leq C. \quad (4.7)$$

Applying (2.16), (4.7) and Proposition 2.10, we have

$$\int_X \varphi |\text{Hess } \phi_i|_{\text{HS}}^2 d\mathcal{H}^n \leq C \int_X \varphi d\mathcal{H}^n, \quad \forall \varphi \in \text{Test}F_+(X, \mathbf{d}, \mathcal{H}^n), \quad i = 1, \dots, m,$$

which implies that

$$\sum_{i=1}^m \|\text{Hess } \phi_i|_{\text{HS}}\|_{L^\infty(\mathcal{H}^n)} \leq C. \quad (4.8)$$

For each $\langle \nabla\phi_i, \nabla\phi_j \rangle$ ($i, j = 1, \dots, m$), from (2.17) we obtain that

$$\begin{aligned} |\langle \nabla\varphi, \nabla\langle \nabla\phi_i, \nabla\phi_j \rangle \rangle| &= |\text{Hess } \phi_i(\nabla\phi_j, \nabla\varphi) + \text{Hess } \phi_j(\nabla\phi_i, \nabla\varphi)| \\ &\leq (|\text{Hess } \phi_i|_{\text{HS}} |\nabla\phi_j| + |\text{Hess } \phi_j|_{\text{HS}} |\nabla\phi_i|) |\nabla\varphi| \\ &\leq C |\nabla\varphi| \quad \mathcal{H}^n\text{-a.e.}, \quad \forall \varphi \in H^{1,2}(X, \mathbf{d}, \mathcal{H}^n). \end{aligned} \quad (4.9)$$

As a result, $\langle \nabla\phi_i, \nabla\phi_j \rangle \in H^{1,2}(X, \mathbf{d}, \mathcal{H}^n)$. We complete the proof by letting $\varphi = \langle \nabla\phi_i, \nabla\phi_j \rangle$ in (4.9), which shows that

$$\|\nabla\langle \nabla\phi_i, \nabla\phi_j \rangle\|_{L^\infty(\mathcal{H}^n)} \leq C. \quad (4.10)$$

□

Lemma 4.5. *For any $\epsilon > 0$, there exists $0 < \delta \leq \Psi(\epsilon|C)$, such that for any $0 < r < \delta$ and any arbitrary but fixed $x_0 \in X$, the following holds.*

1. *The map*

$$\begin{aligned} \mathbf{x}_0 : B_r(x_0) &\longrightarrow \mathbb{R}^n \\ x &\longmapsto (u_1(x), \dots, u_n(x)) \end{aligned} \quad (4.11)$$

is $(1 + \epsilon)$ -bi-Lipschitz from $B_r(x_0)$ to $\mathbf{x}_0(B_r(x_0))$, where each u_i is a linear combination of ϕ_1, \dots, ϕ_m with coefficients only dependent on x_0 .

2. *The matrix-valued function*

$$\begin{aligned} U : B_r(x_0) &\longrightarrow \mathbf{M}_{n \times n}(\mathbb{R}) \\ x &\longmapsto (u^{ij}(x)) := (\langle \nabla u_i, \nabla u_j \rangle(x)), \end{aligned}$$

is Lipschitz continuous and satisfies $(1 - \epsilon)I_n \leq U \leq (1 + \epsilon)I_n$ on $B_r(x_0)$. Moreover, there exists a matrix-valued Lipschitz function

$$\begin{aligned} B : B_r(x_0) &\longrightarrow \mathbf{M}_{n \times n}(\mathbb{R}) \\ x &\longmapsto (b_{ij}(x)), \end{aligned}$$

such that

$$BUB^T(x) = I_n, \quad \forall x \in B_r(x_0).$$

Proof. Consider the matrix-valued function

$$\begin{aligned} E : X &\longrightarrow \mathbf{M}_{m \times m}(\mathbb{R}) \\ x &\longmapsto (\langle \nabla \phi_i, \nabla \phi_j \rangle(x)), \end{aligned}$$

which is Lipschitz continuous by Lemma 4.4. For any fixed $x_0 \in X$, since $E(x_0)$ is a symmetric matrix of trace n and satisfies $E(x_0)^2 = E(x_0)$, there exists an $m \times m$ orthogonal matrix $A = (a_{ij})$, such that

$$AE(x_0)A^T = \begin{pmatrix} I_n & 0 \\ 0 & 0 \end{pmatrix}.$$

Letting $u_i = \sum_{j=1}^m a_{ij}\phi_j$, g then can be written as $g = \sum_{i=1}^m du_i \otimes du_i$ with

$$\sum_{i,j=n+1}^m \langle \nabla u_i, \nabla u_j \rangle^2(x_0) = 0. \quad (4.12)$$

In order to use Theorem 4.3, we need

$$\sum_{i=1}^m \|\nabla u_i\|_{L^\infty(\mathcal{H}^n)}^2 + \sum_{i=1}^m \|\Delta u_i\|_{L^\infty(\mathcal{H}^n)} + \sum_{i,j=1}^m \|\nabla \langle \nabla u_i, \nabla u_j \rangle\|_{L^\infty(\mathcal{H}^n)} \leq C, \quad (4.13)$$

which follows directly from the Proposition 2.10 and Lemma 4.4. We claim that for any $\epsilon \in (0, 1)$, there exists $0 < \delta \leq \Psi(\epsilon|C)$, such that \mathbf{x}_0 is a locally uniformly ϵ -isometric immersion on $B_r(x_0)$ for any $0 < r < \delta$.

For any $y_0 \in B_r(x_0)$, $0 < s < r$, we have

$$\begin{aligned}
& \frac{1}{\mathcal{H}^n(B_s(y_0))} \int_{B_{\epsilon^{-1}s}(y_0)} \left| g - \sum_{i=1}^n du_i \otimes du_i \right|_{\text{HS}} d\mathcal{H}^n \\
& \leq \frac{\mathcal{H}^n(B_{\epsilon^{-1}s}(y_0))}{\mathcal{H}^n(B_s(y_0))} \left(\int_{B_{\epsilon^{-1}s}(y_0)} \left| g - \sum_{i=1}^n du_i \otimes du_i \right|_{\text{HS}}^2 d\mathcal{H}^n \right)^{\frac{1}{2}} \\
& = \frac{\mathcal{H}^n(B_{\epsilon^{-1}s}(y_0))}{\mathcal{H}^n(B_s(y_0))} \left(\int_{B_{\epsilon^{-1}s}(y_0)} \sum_{i,j=n+1}^m \langle \nabla u_i, \nabla u_j \rangle^2 d\mathcal{H}^n \right)^{\frac{1}{2}} \leq C\epsilon^{-1} \exp(C\epsilon^{-1})\delta^2,
\end{aligned} \tag{4.14}$$

where the last inequality comes from (2.2), (4.12) and (4.13).

Thus applying Theorem 4.3, there exists $0 < \delta \leq \Psi(\epsilon|C)$, such that for any $0 < r < \delta$, the function \mathbf{x}_0 defined in (4.11) is $(1 + \epsilon)$ -bi-Lipschitz from $B_r(x_0)$ to $\mathbf{x}_0(B_r(x_0))$. We may also require δ to satisfy condition 2, which is again due to (4.13). Finally, the choice of the matrix $B(x)$ follows from a standard congruent transformation of $U(x)$. □

Lemma 4.6. *X admits a $C^{1,1}$ differentiable structure.*

Proof. Since (X, \mathbf{d}) is compact, by taking $\epsilon = \frac{1}{2}$ in Lemma 4.5, there exists a finite index set Γ , such that the finite family of pairs $\{(B_r(x_\gamma), \mathbf{x}_\gamma)\}_{\gamma \in \Gamma}$ satisfies the following properties.

1. It is a covering of X , i.e. $X \subset \bigcup_{\gamma \in \Gamma} B_r(x_\gamma)$.
2. For every $\gamma \in \Gamma$, \mathbf{x}_γ is $\frac{3}{2}$ -bi-Lipschitz from $B_r(x_\gamma)$ to $\mathbf{x}_\gamma(B_r(x_\gamma)) \subset \mathbb{R}^n$, and each component of \mathbf{x}_γ is a linear combination of ϕ_1, \dots, ϕ_m with coefficients only dependent on x_γ .

We only prove the $C^{1,1}$ regularity of ϕ_1, \dots, ϕ_m on $(B_r(x_0), \mathbf{x}_0)$, since the $C^{1,1}$ regularity of ϕ_1, \dots, ϕ_m on any other $(B_r(x_\gamma), \mathbf{x}_\gamma)$ can be proved in a same way.

For any $y_0 \in B_r(x_0)$, without loss of generality, assume that $B_s(y_0) \subset B_r(x_0)$ for some $s > 0$ and $\mathbf{x}_0(y_0) = 0_n \in \mathbb{R}^n$. Since \mathbf{x}_0 is a $\frac{3}{2}$ -bi-Lipschitz map (thus also a homeomorphism) from $B_r(x_0)$ to $\mathbf{x}_0(B_r(x_0))$, for any sufficiently small $t > 0$, there exists a unique $y_t \in B_r(x_0)$ such that $\mathbf{x}_0(y_t) = (t, 0, \dots, 0)$.

For $i = 1, \dots, n$, set

$$\begin{aligned}
v_i : B_s(y_0) & \longrightarrow \mathbb{R} \\
x & \longmapsto \sum_{j=1}^n b_{ij}(y_0)u_j(x),
\end{aligned} \tag{4.15}$$

where $B = (b_{ij})$ is taken as in Lemma 4.5. It can be immediately checked that $\langle \nabla v_i, \nabla v_j \rangle(y_0) = \delta_{ij}$ ($i, j = 1, \dots, n$).

Notice that

$$\begin{aligned} & \int_{B_\tau(y_0)} \left| g - \sum_{i=1}^n dv_i \otimes dv_i \right|_{\text{HS}}^2 d\mathcal{H}^n \\ &= \int_{B_\tau(y_0)} \left(n + \sum_{i,j=1}^n \langle \nabla v_i, \nabla v_j \rangle - 2 \sum_{i=1}^n |\nabla v_i|^2 \right) d\mathcal{H}^n \rightarrow 0 \quad \text{as } \tau \rightarrow 0^+. \end{aligned} \quad (4.16)$$

Thus arguing as in the proof of Lemma 4.5 and applying Theorem 4.3 to $B_{2d(y_0, y_t)}(y_0)$ for any sufficiently small $t > 0$, we know

$$\sum_{i=1}^n \left(\frac{v_i(y_t) - v_i(y_0)}{d(y_t, y_0)} \right)^2 \rightarrow 1, \quad \text{as } t \rightarrow 0^+. \quad (4.17)$$

Recall $u_i(y_t) = u_i(y_0) = 0$ ($i = 2, \dots, n$). This together with (4.17) shows

$$\sum_{i=1}^n b_{i1}^2(y_0) \lim_{t \rightarrow 0^+} \frac{t^2}{d(y_t, y_0)^2} = 1. \quad (4.18)$$

Next is to calculate values of $\lim_{t \rightarrow 0^+} \frac{u_i(y_t) - u_i(y_0)}{t}$ for $i = n+1, \dots, m$.

For $i = n+1, \dots, m$, set

$$\begin{aligned} f_i &: B_s(y_0) \longrightarrow [0, \infty) \\ x &\longmapsto u_i(x) - \sum_{j=1}^n \langle \nabla u_i, \nabla v_j \rangle(y_0) v_j(x). \end{aligned}$$

Observe that

$$\lim_{x \rightarrow y_0} \langle \nabla f_i, \nabla v_k \rangle(x) = 0, \quad i = n+1, \dots, m, \quad k = 1, \dots, n. \quad (4.19)$$

Thus (4.16) and (4.19) yield that $|\nabla f_i|(y_0) = 0$ ($i = n+1, \dots, m$). From the definition of the local Lipschitz constant of a Lipschitz function, we get

$$\frac{1}{d(y_t, y_0)} \left((u_i(y_t) - u_i(y_0)) - \sum_{j=1}^n \langle \nabla u_i, \nabla v_j \rangle(y_0) (v_j(y_t) - v_j(y_0)) \right) \rightarrow 0, \quad \text{as } t \rightarrow 0^+.$$

Therefore

$$\begin{aligned}
\lim_{t \rightarrow 0^+} \frac{u_i(y_t) - u_i(y_0)}{\mathbf{d}(y_t, y_0)} &= \sum_{j=1}^n \langle \nabla u_i, \nabla v_j \rangle(y_0) \lim_{t \rightarrow 0^+} \frac{v_j(y_t) - v_j(y_0)}{\mathbf{d}(y_t, y_0)} \\
&= \sum_{j=1}^n b_{j1}(y_0) \langle \nabla u_i, \nabla v_j \rangle(y_0) \lim_{t \rightarrow 0^+} \frac{u_1(y_t) - u_1(y_0)}{\mathbf{d}(y_t, y_0)} \\
&= \sum_{j,k=1}^n b_{j1}(y_0) b_{jk}(y_0) \langle \nabla u_i, \nabla u_k \rangle(y_0) \lim_{t \rightarrow 0^+} \frac{t}{\mathbf{d}(y_t, y_0)}.
\end{aligned} \tag{4.20}$$

As a result of (4.18) and (4.20),

$$\lim_{t \rightarrow 0^+} \frac{u_i(y_t) - u_i(y_0)}{t} = \sum_{j,k=1}^n b_{j1}(y_0) b_{jk}(y_0) \langle \nabla u_i, \nabla u_k \rangle(y_0).$$

Analogously,

$$\lim_{t \rightarrow 0^-} \frac{u_i(y_t) - u_i(y_0)}{t} = \sum_{j,k=1}^n b_{j1}(y_0) b_{jk}(y_0) \langle \nabla u_i, \nabla u_k \rangle(y_0).$$

Hence for $i = n + 1, \dots, m$, $k = 1, \dots, n$, we get

$$\frac{\partial u_i}{\partial u_k}(x) = \sum_{j,l=1}^n b_{jk}(x) b_{jl}(x) \langle \nabla u_i, \nabla u_l \rangle(x), \quad \forall x \in B_r(x_0). \tag{4.21}$$

According to the fact that each ϕ_i is a linear combination of u_1, \dots, u_m with coefficients only dependent on x_0 , each $\frac{\partial \phi_i}{\partial u_j}$ is Lipschitz continuous on $B_r(x_0)$ and is also Lipschitz continuous on $\mathbf{x}_0(B_r(x_0))$ ($i = 1, \dots, m$, $j = 1, \dots, n$). If $B_r(x_{\gamma'}) \cap B_r(x_0) \neq \emptyset$ for some $\gamma' \in \Gamma \setminus \{0\}$, since each component of the coordinate function $\mathbf{x}_{\gamma'}$ is a linear combination of ϕ_1, \dots, ϕ_m , the transition function from $(B_r(x_0), \mathbf{x}_0)$ to $(B_r(x_{\gamma'}), \mathbf{x}_{\gamma'})$ is $C^{1,1}$ on $(B_r(x_0) \cap B_r(x_{\gamma'}), \mathbf{x}_0)$.

Therefore, $\{(B_r(x_\gamma), \mathbf{x}_\gamma)\}_{\gamma \in \Gamma}$ gives a $C^{1,1}$ differentiable structure of X . \square

Lemma 4.7. *For the sake of brevity, we only state the following assertions for $(B_r(x_0), \mathbf{x}_0)$ by using the notation of Lemma 4.5.*

1. For any $f_1, f_2 \in C^1(X)$, we have

$$\langle \nabla f_1, \nabla f_2 \rangle = \sum_{j,k=1}^n u^{jk} \frac{\partial f_1}{\partial u_j} \frac{\partial f_2}{\partial u_k} \quad \text{on } B_r(x_0). \tag{4.22}$$

$$2. (\mathbf{x}_0)_\#(\mathcal{H}^n \llcorner B_r(x_0)) = (\det(U))^{-\frac{1}{2}} \mathcal{L}^n \llcorner \mathbf{x}_0(B_r(x_0)).$$

Proof. Statement 1 follows directly from the chain rule of ∇ . As for statement 2, according to the bi-Lipschitz property of \mathbf{x}_0 , there exists a Radon-Nikodym derivative h of $(\mathbf{x}_0^{-1})_\# \left((\det(U))^{-\frac{1}{2}} \mathcal{L}^n \llcorner \mathbf{x}_0(B_r(x_0)) \right)$ with respect to $\mathcal{H}^n \llcorner B_r(x_0)$.

Again for any $B_{2s}(y_0) \subset B_r(x_0)$, we choose $\{v_i\}_{i=1}^n$ as in (4.15) and set

$$\begin{aligned} \mathbf{y}_0 : B_s(y_0) &\longrightarrow \mathbb{R}^n \\ x &\longmapsto (v_1(x), \dots, v_n(x)). \end{aligned}$$

By Theorem 4.3,

$$\lim_{\tau \rightarrow 0^+} \frac{\mathcal{L}^n(\mathbf{y}_0(B_\tau(y_0)))}{\mathcal{H}^n(B_\tau(y_0))} = 1. \quad (4.23)$$

Set $\tilde{B} = B(y_0)$. Then it follows from the choice of the matrix B that

$$\det(\tilde{B})^2 \det(U(y_0)) = 1. \quad (4.24)$$

Using the commutativity of the following diagram,

$$\begin{array}{ccc} B_s(y_0) & \xrightarrow{\mathbf{y}_0} & \mathbf{y}_0(B_s(y_0)) \\ & \searrow_{\mathbf{x}_0} & \downarrow_{\tilde{B}^{-1}} \\ & & \mathbf{x}_0(B_s(y_0)) \end{array}$$

for any $0 < \tau \leq s$, it holds that

$$\int_{\mathbf{x}_0(B_\tau(y_0))} (\det(U))^{-\frac{1}{2}} d\mathcal{L}^n = \int_{\mathbf{y}_0(B_\tau(y_0))} \left(\det(U) \left(\tilde{B}^{-1}(x) \right) \right)^{-\frac{1}{2}} \det(\tilde{B})^{-1} d\mathcal{L}^n(x). \quad (4.25)$$

Thus combining the continuity of $\det(U)$ with (4.23), (4.24) and (4.25) implies

$$\lim_{\tau \rightarrow 0^+} \frac{1}{\mathcal{H}^n(B_\tau(y_0))} \int_{\mathbf{x}_0(B_\tau(y_0))} (\det(U))^{-\frac{1}{2}} d\mathcal{L}^n = 1.$$

Therefore, $h = 1$ \mathcal{H}^n -a.e. on $B_r(x_0)$, which suffices to conclude. \square

Proof of Theorem 1.16. We start by improving the regularity of each ϕ_i on each coordinate chart $(B_r(x_\gamma), \mathbf{x}_\gamma)$. It suffices to verify the case $\gamma = 0$.

We still use the notation in Lemma 4.5. For any fixed $B_{2s}(y_0) \subset B_r(x_0)$, without loss of generality, assume that $\mathbf{x}_0(y_0) = 0_n$ and $B_s(0_n) \subset \mathbf{x}_0(B_{2s}(y_0))$.

We first claim that for $j = 1, \dots, n$,

$$\sum_{k=1}^n \frac{\partial}{\partial u_k} \left(u^{jk} \det(U)^{-\frac{1}{2}} \right) = \Delta u_j \det(U)^{\frac{1}{2}} \quad \mathcal{L}^n\text{-a.e. in } B_s(0_n). \quad (4.26)$$

Notice that for any $\varphi \in C_c(B_s(0_n)) \cap C^1(X)$, in view of Lemma 4.7, we have

$$\begin{aligned} \int_{B_s(0_n)} \varphi \Delta u_j \det(U)^{-\frac{1}{2}} d\mathcal{L}^n &= \int_{\mathbf{x}_0^{-1}(B_s(0_n))} \varphi \Delta u_j d\mathcal{H}^n \\ &= - \int_{\mathbf{x}_0^{-1}(B_s(0_n))} \langle \nabla u_j, \nabla \varphi \rangle d\mathcal{H}^n \\ &= - \int_{B_s(0_n)} \sum_{k=1}^n u^{jk} \frac{\partial \varphi}{\partial u_k} \det(U)^{-\frac{1}{2}} d\mathcal{L}^n, \end{aligned}$$

which suffices to show (4.26) since each u^{jk} is Lipschitz continuous on $B_s(0_n)$. Similarly, for $i = 1, \dots, m$ and any $\varphi \in C_c(B_s(0_n)) \cap C^1(X)$, it holds that

$$\int_{B_s(0_n)} \varphi \mu_i \phi_i \det(U)^{-\frac{1}{2}} d\mathcal{L}^n = \int_{B_s(0_n)} \sum_{j,k=1}^n u^{jk} \frac{\partial \phi_i}{\partial u_j} \frac{\partial \varphi}{\partial u_k} \det(U)^{-\frac{1}{2}} d\mathcal{L}^n. \quad (4.27)$$

Therefore the $C^{1,1}$ -regularity of ϕ_i as well as (4.26), (4.27) gives a PDE as follows.

$$\sum_{j,k=1}^n u^{jk} \frac{\partial^2 \phi_i}{\partial u_j \partial u_k} + \sum_{j=1}^n \Delta u_j \frac{\partial \phi_i}{\partial u_j} + \mu_i \phi_i = 0 \quad \mathcal{L}^n\text{-a.e. in } B_s(0_n). \quad (4.28)$$

Since each Δu_j is some linear combination of ϕ_1, \dots, ϕ_m , it is also $C^{1,1}$ with respect to $\{(B_r(x_\gamma), \mathbf{x}_\gamma)\}_{\gamma \in \Gamma}$. From the classical PDE theory (see for instance [GT01, Theorem 6.13]), $\phi_i \in C^{2,\alpha}(B_s(0_n))$ for any $\alpha \in (0, 1)$. Hence, X admits a $C^{2,\alpha}$ differentiable structure $\{(B_r(x_\gamma), \mathbf{x}_\gamma)\}_{\gamma \in \Gamma}$.

Let us use this differentiable structure to define the following $(0, 2)$ -type symmetric tensor:

$$\tilde{g} := \sum_{i=1}^m \tilde{d}\phi_i \otimes \tilde{d}\phi_i,$$

which is $C^{1,\alpha}$ with respect to $\{(B_r(x_\gamma), \mathbf{x}_\gamma)\}_{\gamma \in \Gamma}$. We claim that \tilde{g} is a Riemannian metric. Again it suffices to prove this statement on $(B_r(x_0), \mathbf{x}_0)$.

Set

$$\begin{aligned} \mathcal{U} : X &\longrightarrow \mathbf{M}_{m \times m}(\mathbb{R}) \\ x &\longmapsto (\langle \nabla u_i, \nabla u_j \rangle). \end{aligned}$$

For any $x \in X$, rewrite $\mathcal{U}(x)$ as the following block matrix

$$\mathcal{U}(x) := \begin{pmatrix} U(x) & U_1(x) \\ U_1^T(x) & U_2(x) \end{pmatrix}.$$

The choice of $\{u_i\}_{i=1}^m$ implies that \tilde{g} has a local expression as

$$\tilde{g} = \sum_{i=1}^m \tilde{d}u_i \otimes \tilde{d}u_i = \sum_{i=1}^n \tilde{d}u_i \otimes \tilde{d}u_i + \sum_{i=n+1}^m \sum_{k,l=1}^n \frac{\partial u_i}{\partial u_k} \frac{\partial u_i}{\partial u_l} \tilde{d}u_k \otimes \tilde{d}u_l.$$

By (4.21), for $i = n+1, \dots, m$, $l = 1, \dots, n$ and any $x \in B_r(x_0)$, we have

$$\frac{\partial u_i}{\partial u_l}(x) = \sum_{j,k=1}^n b_{jl}(x) b_{jk}(x) \langle \nabla u_i, \nabla u_k \rangle(x) = (B^T B U_1(x))_{li} = (U^{-1} U_1(x))_{li},$$

which implies that

$$\tilde{g}(x) = \sum_{i=1}^n \tilde{d}u_i \otimes \tilde{d}u_i + \sum_{k,l=1}^n (U^{-1} U_1 U_1^T U^{-1}(x))_{kl} \tilde{d}u_k \otimes \tilde{d}u_l, \quad \forall x \in B_r(x_0). \quad (4.29)$$

Since $\mathcal{U}^2 - \mathcal{U} \equiv 0$ on $B_r(x_0)$, $U^2 + U_1 U_1^T - U \equiv 0$ on $B_r(x_0)$. By (4.29),

$$\tilde{g}(x) = \sum_{j,k=1}^n (U^{-1})_{jk}(x) \tilde{d}u_j \otimes \tilde{d}u_k, \quad \text{on } B_r(x_0), \quad (4.30)$$

which is positive definite on $B_r(x_0)$. Moreover, $u^{jk} \in C^{1,\alpha}(B_r(x_0))$ ($j, k = 1, \dots, n$). Applying the regularity theorem for second order elliptic PDE (for example [GT01, Theorem 6.17]) to (4.28), we see that $\phi_i \in C^{3,\alpha}(B_r(x_0))$ ($i = 1, \dots, m$). Thus the regularity of \tilde{g} can be improved to $C^{2,\alpha}$. Then (4.30) shows that $u^{jk} \in C^{2,\alpha}(B_r(x_0))$ ($j, k = 1, \dots, n$).

Applying a proof by induction, $\tilde{g} = g$ is actually a smooth Riemannian metric with respect to the smooth differentiable structure $\{(B_r(x_\gamma), \mathbf{x}_\gamma)\}_{\gamma \in \Gamma}$. This implies that (X, d) is isometric to an n -dimensional smooth Riemannian manifold (M^n, g) . To see that (M^n, g) is a closed Riemannian manifold, it suffices to use Theorem 4.3 again to show that the tangent space at any point is not isometric to the upper plane \mathbb{R}_+^n . \square

Proof of Corollary 1.18. Without loss of generality, we may assume that $\mathfrak{m}(X) = 1$. Among lines in the proof, each limit process and each convergence of the series is guaranteed by Proposition 2.10, which can be checked via similar estimates in Lemma 3.10.

First calculate that

$$n = \langle g, g \rangle = \langle c(t)g_t, g \rangle = c(t) \sum_{i=1}^{\infty} e^{-2\mu_i t} |\nabla \phi_i|^2. \quad (4.31)$$

Integrating (4.31) on X , we have

$$n = c(t) \sum_{i=1}^{\infty} e^{-2\mu_i t} \mu_i.$$

Let ϕ_1, \dots, ϕ_m be an $L^2(\mathbf{m})$ -orthonormal basis of the eigenspace corresponding to the first eigenvalue μ_1 . Then

$$\left| \sum_{i=1}^m d\phi_i \otimes d\phi_i - \frac{e^{2\mu_1 t}}{c(t)} g \right|_{\text{HS}} \leq \sum_{i=m+1}^{\infty} e^{2\mu_1 t - 2\mu_i t} |d\phi_i \otimes d\phi_i|_{\text{HS}} = \sum_{i=m+1}^{\infty} e^{2\mu_1 t - 2\mu_i t} |\nabla \phi_i|^2. \quad (4.32)$$

Again the integration of (4.32) on X gives

$$\int_X \left| \sum_{i=1}^m d\phi_i \otimes d\phi_i - \frac{e^{2\mu_1 t}}{c(t)} g \right|_{\text{HS}} d\mathbf{m} \leq \sum_{i=m+1}^{\infty} e^{2\mu_1 t - 2\mu_i t} \mu_i. \quad (4.33)$$

Since

$$\lim_{t \rightarrow \infty} \frac{e^{2\mu_1 t}}{c(t)} = \frac{\mu_1}{n} + \lim_{t \rightarrow \infty} \frac{1}{n} \sum_{i=2}^{\infty} e^{2\mu_1 t - 2\mu_i t} \mu_i = \frac{\mu_1}{n},$$

(4.33) implies that

$$\int_X \left| \sum_{i=1}^m d\phi_i \otimes d\phi_i - \frac{\mu_1}{n} g \right|_{\text{HS}} d\mathbf{m} = 0.$$

In other words,

$$\sum_{i=1}^m d\phi_i \otimes d\phi_i = \frac{\mu_1}{n} g.$$

For other eigenspaces, it suffices to use a proof by induction to conclude. \square

5 Harmonic RCD(K, N) spaces

This section is aimed at proving regularity results for strongly harmonic RCD(K, N) spaces and radically symmetric RCD(K, N) spaces.

We first prove Theorem 1.22. We use the notation of (1.7). We let μ_i be the corresponding eigenvalue of ϕ_i ($i = 1, \dots, m$) and use C to denote a constant with

$$C = C \left(K, m, n, \text{diam}(X, d), \mathcal{H}^n(X), \mu_1, \dots, \mu_m, \|\phi_1\|_{L^2(\mathcal{H}^n)}, \dots, \|\phi_m\|_{L^2(\mathcal{H}^n)} \right),$$

which may vary from line to line.

Proof of Theorem 1.22. Let us first show that

$$\left| \frac{F(0) - F(\mathbf{d}(x, y))}{\mathbf{d}^2(x, y)} \right| \leq C, \quad \forall x, y \in X. \quad (5.1)$$

Letting $x = y$ in (1.7) we know

$$\sum_{i=1}^m \phi_i^2(x) = F(0), \quad \forall x \in X. \quad (5.2)$$

Therefore it clearly follows from (1.7) and (5.2) that

$$\sum_{i=1}^m (\phi_i(x) - \phi_i(y))^2 = 2(F(0) - F(\mathbf{d}(x, y))), \quad \forall x, y \in X. \quad (5.3)$$

As a result, we have

$$\frac{F(0) - F(\mathbf{d}(x, y))}{\mathbf{d}^2(x, y)} = \frac{1}{2} \sum_{i=1}^m \left(\frac{\phi_i(x) - \phi_i(y)}{\mathbf{d}(x, y)} \right)^2, \quad \forall x, y \in X,$$

which together with the Lipschitz continuity (Proposition 2.10) of ϕ_i ($i = 1, \dots, m$) implies (5.1).

From now on let us take an arbitrary but fixed

$$x_0 \in \mathcal{R}_n(X) \cap \bigcap_{i,j=1}^m \text{Leb}(\langle \nabla \phi_i, \nabla \phi_j \rangle),$$

where $\text{Leb}(\langle \nabla \phi_i, \nabla \phi_j \rangle)$ is the Lebesgue point of the function $\langle \nabla \phi_i, \nabla \phi_j \rangle$.

We claim that

$$\lim_{r \rightarrow 0} \frac{F(0) - F(r)}{r^2} = 2c, \quad (5.4)$$

for some constant $c > 0$.

For any $\{r_l\} \subset (0, \infty)$ with $r_l \rightarrow 0$, after passing to a subsequence, consider the following pmGH convergence

$$(X_l, \mathbf{d}_l, \mathcal{H}^n, x_0) := \left(X, \frac{1}{r_l} \mathbf{d}, \frac{1}{r_l^n} \mathcal{H}_d^n, x_0 \right) \xrightarrow{\text{pmGH}} \left(\mathbb{R}^n, \mathbf{d}_{\mathbb{R}^n}, \frac{1}{\omega_n} \mathcal{L}^n, 0_n \right).$$

For notation convenience, we denote by Δ_l, ∇_l the gradient and the Laplacian on $(X_l, \mathbf{d}_l, \mathcal{H}^n)$ respectively, and by $B_r^l(x_0) := B_r^{X_l}(x_0)$.

For $i = 1, \dots, m$ and $l \in \mathbb{N}_+$, set

$$\varphi_{i,l} := \frac{\phi_i - \phi_i(x_0)}{r_l}.$$

Then we have

$$|\nabla_l \varphi_{i,l}| = |\nabla \phi_i|, \quad \Delta_l \varphi_{i,l} = r_l \Delta \phi_i = -r_l \mu_i \phi_i.$$

In particular, we obtain the following estimates directly from Proposition 2.10:

$$\|\nabla_l \varphi_{i,l}\|_{L^\infty(\mathcal{H}^n)} \leq C, \quad (5.5)$$

$$\|\Delta_l \varphi_{i,l}\|_{L^\infty(\mathcal{H}^n)} \leq C r_l \rightarrow 0 \quad \text{as } l \rightarrow \infty. \quad (5.6)$$

According to the Arzela-Ascoli Theorem (Theorem 2.29), for every $i = 1, \dots, m$, $\{\phi_{i,l}\}$ uniformly converges to φ_i on any $B_R(0_n) \subset \mathbb{R}^n$. Moreover, (5.5), (5.6), Theorem 2.33 and Theorem 2.34 imply that each φ_i is a harmonic function with $|\nabla \varphi_i| \leq C$, and thus a linear function on \mathbb{R}^n .

Since $x_0 \in \mathcal{R}_n(X) \cap \bigcap_{i,j=1}^m \text{Leb}(\langle \nabla \phi_i, \nabla \phi_j \rangle)$, we have

$$\begin{aligned} \langle \nabla \phi_i, \nabla \phi_j \rangle(x_0) &= \lim_{r \downarrow 0} \int_{B_r(x_0)} \langle \nabla \phi_i, \nabla \phi_j \rangle d\mathcal{H}^n \\ &= \frac{1}{\omega_n} \lim_{l \rightarrow \infty} \int_{B_l^1(x_0)} \langle \nabla_l \varphi_{i,l}, \nabla_l \varphi_{j,l} \rangle d\mathcal{H}^n = \langle \nabla \varphi_i, \nabla \varphi_j \rangle. \end{aligned}$$

In particular, for any $y \in \mathbb{R}_n$, by taking $y_l \in X_l$ such that $y_l \rightarrow y$, we see from (5.3) and the fact $d_l(y_l, x_0) \rightarrow d_{\mathbb{R}^n}(y, 0_n)$ that

$$\begin{aligned} \lim_{l \rightarrow \infty} \frac{F(0) - F(d(x_0, y_l))}{d^2(x_0, y_l)} &= 2 \lim_{l \rightarrow \infty} \left(\frac{r_l}{d(x_0, y_l)} \right)^2 \sum_{i=1}^m \left(\frac{\phi_i(x_0) - \phi_i(y_l)}{r_l} \right)^2 \\ &= 2 (d_{\mathbb{R}^n}(0_n, y))^{-2} \sum_{i=1}^m \varphi_i^2(y). \end{aligned} \quad (5.7)$$

From our construction it is clear that $\varphi_i(0_n) = 0$ ($i = 1, \dots, m$). Because each φ_i is a linear function, we know

$$\sum_{i=1}^m \varphi_i^2(y) = \sum_{i=1}^m |\nabla \varphi_i|^2 d_{\mathbb{R}^n}^2(0_n, y) = \sum_{i=1}^m |\nabla \phi_i|^2(x_0) d_{\mathbb{R}^n}^2(0_n, y).$$

This together with (5.7) implies that

$$\lim_{r \downarrow 0} \frac{F(0) - F(r)}{r^2} = 2 \sum_{i=1}^m |\nabla \phi_i|^2(x_0) := 2c > 0,$$

because the sequence $\{r_l\}$ is taken to be arbitrary and each ϕ_i is a non-constant eigenfunction.

Finally, we claim that

$$\left| \sum_{i=1}^m d\phi_i \otimes d\phi_i - cg \right|_{\text{HS}} = 0, \quad \mathbf{m}\text{-a.e.} \quad (5.8)$$

for some constant $c > 0$, where g is the canonical Riemannian metric on $(X, \mathbf{d}, \mathcal{H}^n)$.

Let x_0 be an arbitrary but fixed point in $\text{Leb} \left(\left| g - \sum_{i=1}^m d\phi_i \otimes d\phi_i \right|_{\text{HS}}^2 \right) \cap \mathcal{R}_n$.

Then for any $y_1, y_2 \in \mathbb{R}^n$, combining (5.3) with (5.4) yields that

$$c \mathbf{d}_{\mathbb{R}^n}^2(y_1, y_2) = \sum_{i=1}^m (\varphi_i(y_1) - \varphi_i(y_2))^2.$$

Therefore, $c^{-1}(\varphi_1, \dots, \varphi_m)$ is a linear isometry from \mathbb{R}^n to \mathbb{R}^n , which shows that

$$c g_{\mathbb{R}^n} = \sum_{i=1}^m d\varphi_i \otimes d\varphi_i.$$

For each i , the $H^{1,2}$ -strong convergence of $\{\varphi_{i,l}\}$ on any $B_R(0_n) \subset \mathbb{R}^n$ as well as (5.5) implies that

$$\begin{aligned} \lim_{r \rightarrow 0} \int_{B_r(x_0)} \left| cg - \sum_{i=1}^m d\phi_i \otimes d\phi_i \right|_{\text{HS}}^2 d\mathcal{H}^n &= \frac{1}{\omega_n} \lim_{l \rightarrow \infty} \int_{B_1^l(x_0)} \left| cg_{X_l} - \sum_{i=1}^m d\varphi_{i,l} \otimes d\varphi_{i,l} \right|_{\text{HS}}^2 d\mathcal{H}^n \\ &= \int_{B_1(0_n)} \left| cg_{\mathbb{R}^n} - \sum_{i=1}^m d\varphi_i \otimes d\varphi_i \right|_{\text{HS}}^2 d\mathcal{L}^n = 0. \end{aligned}$$

Hence (5.8) follows from the arbitrary of $x_0 \in \text{Leb} \left(\left| g - \sum_{i=1}^m d\phi_i \otimes d\phi_i \right|_{\text{HS}}^2 \right) \cap \mathcal{R}_n$.

Now it suffices to apply Theorem 1.16 to conclude. \square

Remark 5.1. Actually, the radically symmetric condition Theorem 1.22 can be reduced to that there exists a real valued function $F : [0, \infty) \times [0, \infty) \rightarrow \mathbb{R}$ and non-constant eigenfunctions $\{\phi_i\}_{i=1}^m$ such that for any $x \in X$ there exists $\epsilon_x > 0$ such that

$$\sum_{i=1}^m \phi_i(x)\phi_i(y) = F(\mathbf{d}(x, y)), \quad \forall y \in B_{\epsilon_x}(x).$$

Next let us deal with strong harmonic $\text{RCD}(K, N)$ spaces. Let us fix a strong harmonic $\text{RCD}(K, N)$ space $(X, \mathbf{d}, \mathbf{m})$ with $\dim_{\mathbf{d}, \mathbf{m}}(X) = n$. Let us recall the definition of strong harmonic $\text{RCD}(K, N)$ space as follows: there exists a real

valued function $H : [0, \infty) \times [0, \infty) \rightarrow \mathbb{R}$ such that the heat kernel ρ of $(X, \mathbf{d}, \mathbf{m})$ satisfies

$$\rho(x, y, t) = H(\mathbf{d}(x, y), t), \quad \forall x, y \in X, \quad \forall t > 0. \quad (5.9)$$

We start with the proof of Theorem 1.20, which is similar to the proof of Theorem 1.13.

Proof of Theorem 1.20. Let $n = \dim_{\mathbf{d}, \mathbf{m}}(X)$. We claim that

$$\lim_{t \downarrow 0} t^n H(rt, t^2) = \tilde{c} (4\pi)^{-\frac{n}{2}} \exp\left(-\frac{r^2}{4}\right), \quad (5.10)$$

for some constant $\tilde{c} > 0$.

Take an arbitrary but fixed $x_0 \in \mathcal{R}_n^*(X)$. For any $\{r_i\} \subset \mathbb{R}$ with $r_i \rightarrow 0$, we consider the following pmGH convergence.

$$(X_i, \mathbf{d}_i, \mathbf{m}_i, x_0) := \left(X, \frac{1}{r_i} \mathbf{d}, \frac{\mathbf{m}}{\mathbf{m}(B_{r_i}(x_0))}, x_0 \right) \xrightarrow{\text{pmGH}} \left(\mathbb{R}^n, \mathbf{d}_{\mathbb{R}^n}, \frac{1}{\omega_n} \mathcal{L}^n, 0_n \right).$$

On each $(X_i, \mathbf{d}_i, \mathbf{m}_i)$, the heat kernel ρ_i satisfies that

$$\rho_i(x_i, y_i, 1) = \mathbf{m}(B_{r_i}(x_0)) \rho(x_i, y_i, r_i^2), \quad \forall x_i, y_i \in X_i. \quad (5.11)$$

For any $s > 0$, on each $(X_i, \mathbf{d}_i, \mathbf{m}_i)$ we can take $x_i, y_i \in B_{2s}^{X_i}(x_0)$ such that $\mathbf{d}_i(x_i, y_i) = s$. Then after passing to a subsequence, we may assume that $x_i \rightarrow x \in \mathbb{R}^n$ and $y_i \rightarrow y \in \mathbb{R}^n$.

Due to Theorem 2.35, we have

$$\lim_{i \rightarrow \infty} \rho_i(x_i, y_i, 1) = \rho_{\mathbb{R}^n}(x, y, 1) = (4\pi)^{-\frac{n}{2}} \exp\left(-\frac{\mathbf{d}_{\mathbb{R}^n}^2(x, y)}{4}\right). \quad (5.12)$$

Combining (5.9) with (5.11) and (5.12) then gives

$$\begin{aligned} & \vartheta_n(X, \mathbf{d}, \mathbf{m})(x_0) \lim_{i \rightarrow \infty} r_i^n H(r_i \mathbf{d}_{\mathbb{R}^n}(x, y), r_i^2) \\ &= \lim_{i \rightarrow \infty} \mathbf{m}(B_{r_i}(x_0)) H(r_i \mathbf{d}_{\mathbb{R}^n}(x, y), r_i^2) = (4\pi)^{-\frac{n}{2}} \exp\left(-\frac{\mathbf{d}_{\mathbb{R}^n}^2(x, y)}{4}\right). \end{aligned} \quad (5.13)$$

Since the above equality does not depend on the choice of the sequence $r_i \downarrow 0$, and the limit $\lim_{t \downarrow 0} t^n H(rt, t^2)$ does not depend on the choice of $x_0 \in \mathcal{R}_n^*(X)$, we complete the proof of (5.10). Indeed, we have also proved that

$$\vartheta_n(X, \mathbf{d}, \mathbf{m})(x) = \tilde{c}^{-1}, \quad \mathbf{m}\text{-a.e. } x \in \mathcal{R}_n^*(X).$$

Moreover, if we first take $x, y \in \mathbb{R}^n$ and then choose sequences $\{x_i\}, \{y_i\}$ such that $X_i \ni x_i \rightarrow x \in \mathbb{R}^n$, $X_i \ni y_i \rightarrow y \in \mathbb{R}^n$ in the above argument, we may have that

$$\frac{d(x_i, y_i)}{r_i} = \mathbf{d}_i(x_i, y_i) = \mathbf{d}_{\mathbb{R}^n}(x, y) + o(1).$$

As a result, by calculating as (5.13), (5.10) can be improved to

$$\lim_{t \downarrow 0} t^n H(rt + o(t), t^2) = \tilde{c} (4\pi)^{-\frac{n}{2}} \exp\left(-\frac{r^2}{4}\right) \quad (5.14)$$

If x_0 does not satisfy $\vartheta_n(X, \mathbf{d}, \mathbf{m})(x_0) = \tilde{c}$, then for any $r_i \downarrow 0$, after passing to a subsequence, we consider the following pmGH convergence.

$$(X_i, \mathbf{d}_i, \mathbf{m}_i, x_0) := \left(X, \frac{1}{r_i} \mathbf{d}, \frac{\mathbf{m}}{\mathbf{m}(B_{r_i}(x_0))}, x_0 \right) \xrightarrow{\text{pmGH}} (X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty, x_\infty).$$

Let ρ_∞ be the heat kernel on $(X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty)$. For any $z_\infty, w_\infty \in X_\infty$, by Gromov-Hausdorff approximation, we can take $X_i \ni z_i \rightarrow z_\infty$, $X_i \ni w_i \rightarrow w_\infty$ such that

$$\mathbf{d}_i(z_i, w_i) \rightarrow \mathbf{d}_\infty(z_\infty, w_\infty).$$

Similarly we can show that the heat kernel satisfies that

$$\begin{aligned} \rho_\infty(z, w, 1) &= \lim_{i \rightarrow \infty} \rho_i(z_i, w_i, 1) \\ &= \lim_{i \rightarrow \infty} \mathbf{m}(B_{r_i}(x_0)) \rho(z_i, w_i, r_i^2) \\ &= \lim_{i \rightarrow \infty} \mathbf{m}(B_{r_i}(x_0)) H(r_i \mathbf{d}_i(z_i, w_i), r_i^2). \end{aligned} \quad (5.15)$$

Owing to (5.14) and Theorem 2.8, by letting $z = x_\infty$ and taking $w_\infty \in \partial B_1(x_\infty)$, we see from (5.15) that

$$\tilde{c}^{-1} C^{-1} \leq \lim_{i \rightarrow \infty} \frac{\mathbf{m}(B_{r_i}(x_0))}{r_i^n} \leq \tilde{c}^{-1} C,$$

for some $C = C(K, N)$ (we may take $\epsilon = 1$ in Theorem 2.8). As a result, we know

$$\tilde{c}^{-1} C^{-1} \leq \liminf_{r \rightarrow 0} \frac{\mathbf{m}(B_r(x_0))}{r^n} \leq \limsup_{r \rightarrow 0} \frac{\mathbf{m}(B_r(x_0))}{r^n} \leq \tilde{c}^{-1} C.$$

Therefore, applying [AT04, Theorem 2.4.3] implies that $\mathbf{m} = c\mathcal{H}^n$ for some $c > 0$. Finally, it follows from [BGHZ23, Theorem 1.5 and Theorem 2.22] that $(X, \mathbf{d}, \mathcal{H}^n)$ is a non-collapsed $\text{RCD}(K, n)$ space. \square

Proof of Corollary 1.23. According to Theorem 1.20, $\mathbf{m} = c\mathcal{H}^n$ for some $c > 0$, and $(X, \mathbf{d}, \mathcal{H}^n)$ is an $\text{RCD}(K, n)$ space. Since the space can be rescaled, without loss of generality we may assume that $\mathcal{H}^n(X) = 1$.

We now claim that $(X, \mathbf{d}, \mathcal{H}^n)$ is a radically symmetric $\text{RCD}(K, n)$ space.

For any $x, y \in X$ any $t > 0$, by our assumption we know

$$\sum_{i=0}^{\infty} e^{-\mu_i t} \phi_i(x) \phi_i(y) = \rho(x, y, t) = H(\mathbf{d}(x, y), t).$$

Let ϕ_1, \dots, ϕ_m be the L^2 -orthonormal basis of the eigenspace with corresponding eigenvalue μ_1 . Given any two points $x, y \in X$, we set $r_0 = \mathbf{d}(x, y)$. Then for any $t > 0$ we calculate that

$$\sum_{i=1}^m \phi_i(x) \phi_i(y) = e^{\mu_1 t} (H(r_0, t) - 1) - \sum_{i=m+1}^{\infty} e^{(\mu_1 - \mu_i)t} \phi_i(x) \phi_i(y). \quad (5.16)$$

Let N_0 be the integer such that

$$\mu_i \geq 2C_1(K, n)i^{\frac{2}{n}} \geq 2\mu_1, \quad \forall i \geq N_0.$$

Then the second term of the right hand side of (5.16) satisfies that

$$\begin{aligned} \left| \sum_{i=m+1}^{\infty} e^{(\mu_1 - \mu_i)t} \phi_i(x) \phi_i(y) \right| &\leq C_2(K, N) \sum_{i=m+1}^{\infty} e^{(\mu_1 - \mu_i)t} i^{\frac{n}{2}} \\ &= \sum_{i=m+1}^{N_0} e^{(\mu_1 - \mu_i)t} i^{\frac{n}{2}} + \sum_{i=N_0+1}^{\infty} e^{(\mu_1 - \mu_i)t} i^{\frac{n}{2}} \\ &\leq \sum_{i=m+1}^{N_0} e^{(\mu_1 - \mu_i)t} i^{\frac{n}{2}} + \sum_{i=N_0+1}^{\infty} e^{C_1(K, N)i^{-\frac{2}{n}} i^{\frac{n}{2}}} \rightarrow 0 \quad \text{as } t \rightarrow \infty. \end{aligned} \quad (5.17)$$

As a result, (5.16) and (5.17) yield that

$$\sum_{i=1}^m \phi_i(x) \phi_i(y) = \lim_{t \rightarrow \infty} e^{\mu_1 t} (H(r_0, t) - 1) = \lim_{t \rightarrow \infty} e^{\mu_1 t} (H(\mathbf{d}(x, y), t) - 1) := F(\mathbf{d}(x, y)),$$

which shows that $(X, \mathbf{d}, \mathcal{H}^n)$ is a radically symmetric $\text{RCD}(K, n)$ space. This completes the proof. \square

Remark 5.2. Inductively, one can show that, given any non-zero eigenvalue μ of $-\Delta$, any $L^2(\mathcal{H}^n)$ -orthonormal basis $\{f_1, \dots, f_l\}$ of the corresponding eigenspace E_μ ($l = \dim(E_\mu)$) satisfies

$$\sum_{i=1}^l f_i(x) f_i(y) = H_\mu(\mathbf{d}(x, y)), \quad \forall x, y \in X,$$

for some real-valued function H_μ . Then from the proof of Theorem 1.22 we know there exists a constant c_μ such that

$$c_\mu g = \sum_{i=1}^l df_i \otimes df_i,$$

which means that $(X, \mathbf{d}, \mathcal{H}^n)$ is an IHKI RCD(K, n) space.

To end this section we prove Theorem 1.24, the proof of which almost the same as the proof of Theorem 1.13. We omit some details.

Proof of Theorem 1.24. According to Theorem 1.20, $\mathbf{m} = c\mathcal{H}^n$ for some $c > 0$ and $(X, \mathbf{d}, \mathcal{H}^n)$ is a non-collapsed RCD($0, n$) space. Without loss of generality, we may assume that $\mathbf{m} = \mathcal{H}^n$.

Fix a point $x_0 \in X$. Now for any $r_i \rightarrow \infty$, by passing to a subsequence, consider the following pmGH convergence:

$$(X_i, \mathbf{d}_i, \mathbf{m}_i, x_0) := \left(X, \frac{1}{r_i} \mathbf{d}, \frac{\mathbf{m}}{\mathbf{m}(B_{r_i}(x_0))}, x_0 \right) \xrightarrow{\text{pmGH}} (X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty, x_0),$$

where $(X_\infty, \mathbf{d}_\infty, \mathbf{m}_\infty, x_0)$ is a pointed RCD($0, n$) space.

Let ρ_i be the corresponding heat kernel of $(X_i, \mathbf{d}_i, \mathbf{m}_i)$ ($i \in \mathbb{N} \cup \{\infty\}$). Then by (5.9) we know

$$\rho_i(x_i, y_i, t) = \mathbf{m}(B_{r_i}(x_0)) H(\mathbf{d}_\infty(x_i, y_i), r_i^2 t), \quad \forall x_i, y_i \in X_i, \quad \forall t > 0. \quad (5.18)$$

For any $x_\infty, y_\infty \in X_\infty$, by taking $\{x_i\}, \{y_i\}$ such that $X_i \ni x_i \rightarrow x_\infty$, $X_i \ni y_i \rightarrow y_\infty$ and $\mathbf{d}_i(x_i, y_i) \rightarrow \mathbf{d}_\infty(x_\infty, y_\infty)$. Then it follows from Theorem 2.35 and (5.18) that

$$\begin{aligned} \rho_\infty(x_\infty, y_\infty, t) &= \lim_{i \rightarrow \infty} \mathbf{m}(B_{r_i}(x_0)) H(r_i \mathbf{d}_\infty(x_\infty, y_\infty), r_i^2 t) \\ &:= \tilde{H}(\mathbf{d}_\infty(x_\infty, y_\infty), t). \end{aligned} \quad (5.19)$$

As a result of Theorem 1.20, $\mathbf{m}_\infty = \tilde{c}\mathcal{H}^n$ for some $\tilde{c} > 0$. Now using [BGHZ23, Theorem 1.6] implies that $\mathbf{m}_i = \tilde{c}_i \mathcal{H}^n$ for any sufficiently large i , where $\{\tilde{c}_i\}$ is a sequence of positive constants such that $\lim_{i \rightarrow \infty} \tilde{c}_i = \tilde{c}$.

Hence we have

$$\frac{\mathbf{m}(B_{2r_i}(x_0))}{\mathbf{m}(B_{r_i}(x_0))} = \mathbf{m}_i(B_2^{X_i}(x_0)) = \tilde{c}_i \mathcal{H}^n(B_2^{X_i}(x_0)) = \tilde{c}_i \frac{1}{r_i^n} \mathbf{m}(B_{2r_i}(x_0)),$$

which shows that

$$\lim_{i \rightarrow \infty} \frac{\mathbf{m}(B_{r_i}(x_0))}{r_i^n} = \tilde{c}^{-1}. \quad (5.20)$$

Applying [DG16, Theorem 1.1] we know $(X_\infty, \mathbf{d}_\infty, \mathcal{H}^n)$ is a metric cone with x_0 being its origin. Moreover, from (5.19) we see that $(X_\infty, \mathbf{d}_\infty, \mathcal{H}^n)$ is a harmonic $\text{RCD}(0, n)$ space.

Arguing as in the proof of Theorem 1.20, and combining with [CT22, Theorem 1.1], any tangent cone at x_0 must be isometric to $(\mathbb{R}^n, \mathbf{d}_{\mathbb{R}^n}, 0_n)$. The metric cone structure of $(X_\infty, \mathbf{d}_\infty, \mathcal{H}^n)$, indicating that any tangent cone at x_0 is isometric to itself, tells us that $(X_\infty, \mathbf{d}_\infty)$ is isometric to $(\mathbb{R}^n, \mathbf{d}_{\mathbb{R}^n})$. Finally, it suffices to use [DG18, Theorem 1.6] to conclude. \square

6 Diffeomorphic finiteness theorems

This section is dedicated to proving Theorem 1.27 and Theorem 1.29. To fix the notation, for a Riemannian manifold (M^n, g) , denote by vol_g its Riemannian volume measure, by K_g its sectional curvature, by Ric_g its Ricci curvature tensor, by $\text{inj}_g(p)$ the injectivity radius at p and by $(\nabla^g)^k$, Δ^g the k -th covariant derivative and the Laplacian with respect to g , by \mathbf{d}_g the metric induced by g .

We are now in the position to prove the following theorem.

Theorem 6.1. *$\mathcal{M}(K, n, D, \tau)$ has only finitely many members up to diffeomorphism.*

Proof. Assume the contrary, i.e. there exists a sequence of Riemannian manifolds $\{(M_i^n, g_i)\} \subset \mathcal{M}(K, n, D, \tau)$, which are pairwise non-diffeomorphic.

On each (M_i^n, g_i) , there exists $m_i \in \mathbb{N}$, such that

$$g_i = \sum_{j=1}^{m_i} d\phi_{i,j} \otimes d\phi_{i,j}, \quad (6.1)$$

where $\phi_{i,j}$ is a non-constant eigenfunction of $-\Delta^{g_i}$ with the corresponding eigenvalue $\mu_{i,j}$ and satisfies that $\|\phi_{i,j}\|_{L^2(\text{vol}_{g_i})} \geq \tau > 0$ ($i \in \mathbb{N}$, $j = 1, \dots, m_i$). By taking trace of (6.1) with respect to g_i , we know

$$n = \sum_{j=1}^{m_i} |\nabla^{g_i} \phi_{i,j}|^2. \quad (6.2)$$

Integration of (6.2) on (M_i^n, g_i) shows that

$$n \text{vol}_{g_i}(M_i^n) \geq \tau^2 \sum_{j=1}^{m_i} \mu_{i,j}.$$

The Bishop-Gromov volume comparison theorem and Li-Yau's first eigenvalue lower bound [LY80, Theorem 7] imply that

$$C_1(K, n)D^n \geq n \text{vol}_{g_i}(M_i^n) \geq \tau^2 \sum_{j=1}^{m_i} \mu_{i,j} \geq C_2(K, n, D)\tau^2 m_i \geq C_2(K, n, D)\tau^2. \quad (6.3)$$

Moreover, for each $\phi_{i,j}$,

$$\|\phi_{i,j}\|_{L^2(\text{vol}_{g_i})}^2 = \mu_{i,j}^{-1} \int_{M_i^n} |\nabla^{g_i} \phi_{i,j}|^2 d\text{vol}_{g_i} \leq n \mu_{i,j}^{-1} \text{vol}_{g_i}(M_i^n) \leq C(K, n, D, \tau). \quad (6.4)$$

Since (6.3) implies that $1 \leq \inf_i m_i \leq \sup_i m_i \leq C(K, n, D, \tau)$, after passing to a subsequence, we may take $m \in \mathbb{N}$ such that

$$g_i = \sum_{j=1}^m d\phi_{i,j} \otimes d\phi_{i,j}, \quad \forall i \in \mathbb{N}. \quad (6.5)$$

Moreover, by (6.3), we may assume that

$$\lim_{i \rightarrow \infty} \mu_{i,j} = \mu_j \in [C_2(K, n, D), \tau^{-2}C_1(K, n)D^n], \quad j = 1, \dots, m. \quad (6.6)$$

According to Theorem 2.23 and (6.3), $\{(M_i^n, g_i)\}$ can also be required to satisfy

$$(M_i^n, \mathbf{d}_{g_i}, \text{vol}_{g_i}) \xrightarrow{\text{mGH}} (X, \mathbf{d}, \mathcal{H}^n)$$

for some non-collapsed $\text{RCD}(K, n)$ space $(X, \mathbf{d}, \mathcal{H}^n)$. In particular, combining (6.3)-(6.6) with Theorems 2.33 and 2.34, we know that on $(X, \mathbf{d}, \mathcal{H}^n)$,

$$g = \sum_{j=1}^m d\phi_j \otimes d\phi_j,$$

where each ϕ_j is an eigenfunction of $-\Delta$ with the eigenvalue μ_j . Therefore, from Theorem 1.16, we deduce that (X, \mathbf{d}) is isometric to an n -dimensional smooth closed Riemannian manifold (M^n, g) . However, due to [ChCo1, Theorem A.1.12], M_i^n is diffeomorphic to M^n for any sufficiently large i . A contradiction. \square

The proof of Theorem 1.27 mainly uses the estimates in Section 4 and a stronger version of Gromov convergence theorem given by Hebey-Herzlish [HH97]. For reader's convenience, Hebey-Herzlish's theorem is stated below.

Theorem 6.2. *Let $\{(M_i^n, g_i)\}$ be a sequence of n -dimensional closed Riemannian manifolds such that*

$$\sup_i \text{vol}_{g_i}(M_i^n) < \infty, \quad \inf_i \inf_{p \in M_i^n} \text{inj}_{g_i}(p) > 0,$$

and for all $k \in \mathbb{N}$,

$$\sup_i \sup_{M_i^n} |(\nabla^{g_i})^k \text{Ric}_{g_i}| < \infty.$$

Then there exists a subsequence which is still denoted as $\{(M_i^n, g_i)\}$, such that it C^∞ -converges to a closed Riemannian manifold (M^n, g) .

The following Cheeger-Gromov-Taylor's estimate of the injectivity radius is also necessary for the proof of Theorem 1.27.

Theorem 6.3 ([CGT82, Theorem 4.7]). *Let (M^n, g) be a complete n -dimensional Riemannian manifold with $|K_g| \leq \kappa < \infty$. Then there exists a constant $c_0 = c_0(n) > 0$, such that for any $0 < r \leq \frac{\pi}{4\sqrt{\kappa}}$,*

$$\text{inj}_g(p) \geq c_0 r \frac{\text{vol}(B_r(p))}{\int_0^r V_{-(n-1)\kappa, n} dt}, \quad \forall p \in M^n.$$

Proof of Theorem 1.27. By Theorem 6.1, without loss of generality, we may take a sequence $\{(M^n, g_i)\} \subset \mathcal{M}(K, n, D, \tau)$ such that $\{(M^n, g_i)\}$ mGH converges to (M^n, g) and that (6.3)-(6.6) still hold. Denote by $B_r^i(p)$ the r -radius ball (with respect to \mathbf{d}_{g_i}) centered at $p \in M^n$ for notation convenience.

Step 1 Uniform two-sided sectional curvature bound on (M^n, g_i) .

According to the estimates in Section 4, combining (6.3)-(6.6), we may choose a uniform $r > 0$, such that for every arbitrary but fixed $B_{4096r}^i(p) \subset M^n$, there exists a coordinate function $\mathbf{x}^i = (u_1^i, \dots, u_n^i) : B_{4096r}^i(p) \rightarrow \mathbb{R}^n$ satisfying the following properties.

1. \mathbf{x}^i is $\frac{3}{2}$ -bi-Lipschitz from $B_{4096r}^i(p)$ to $\mathbf{x}^i(B_{4096r}^i(p))$ (by Lemma 4.5).
2. Set $(g_i)_{jk} := g_i \left(\frac{\partial}{\partial u_j^i}, \frac{\partial}{\partial u_k^i} \right)$. Then it holds that

$$\frac{1}{2}I_n \leq (g_i)_{jk} \leq 2I_n, \quad \text{on } B_{4096r}^i(p) \quad (\text{by Lemma 4.5 and (4.30)}). \quad (6.7)$$

We first give a $C^{2,\alpha}$ -estimate of g_i on each (M^n, g_i) for any $\alpha \in (0, 1)$. Applying (4.13) and (6.7) implies that on $B_{4096r}^i(p)$

$$C \geq |\nabla^{g_i}(g_i)^{jk}|^2 = \sum_{\beta, \gamma=1}^n (g_i)^{\beta\gamma} \frac{\partial}{\partial u_\beta^i}(g_i)^{jk} \frac{\partial}{\partial u_\gamma^i}(g_i)^{jk} \geq \frac{1}{2} \sum_{\beta=1}^n \left(\frac{\partial}{\partial u_\beta^i}(g_i)^{jk} \right)^2, \quad (6.8)$$

for some $C = C(K, n, D, \tau)$ which may vary from line to line.

Then $\|(g_i)^{jk}\|_{C^\alpha(B_{4096r}^i(p))} \leq C$ follows from (6.8) and the local bi-Lipschitz property of \mathbf{x}^i ($j, k = 1, \dots, n$).

For $j = 1, \dots, n$, $|\nabla^{g_i} \phi_{i,j}| \leq C$ yields that $\|\phi_{i,j}\|_{C^\alpha(B_{4096r}^i(p))} \leq C$. This implies that $\|\Delta^{g_i} u_{i,j}\|_{C^\alpha(B_{4096r}^i(p))} \leq C$ since each $u_{i,j}$ is the linear combination of $\phi_{i,j}$ constructed as in Lemma 4.5. Then the the classical Schauder interior estimate (see for example [GT01, Theorem 6.2]), together with the PDE (4.28) implies that $\|\phi_{i,j}\|_{C^{2,\alpha}(B_{256r}^i(p))} \leq C$ since $\mathbf{x}^i(B_{256r}^i(p)) \subset B_{512r}(\mathbf{x}^i(p)) \subset \mathbf{x}^i(B_{1024r}^i(p)) \subset$

$B_{2048r}(\mathbf{x}^i(p)) \subset \mathbf{x}^i(B_{4096r}^i(p))$. As a result, $\|\Delta^{g_i} u_{i,j}\|_{C^{2,\alpha}(B_{256r}^i(p))} \leq C$. Moreover, (6.5) shows that

$$\|(g_i)_{jk}\|_{C^{1,\alpha}(B_{256r}^i(p))}, \|(g_i)^{jk}\|_{C^{1,\alpha}(B_{256r}^i(p))} \leq C, \quad j, k = 1, \dots, n.$$

Applying again the Schauder interior estimate to $\phi_{i,j}$ in the PDE (4.28), we know $\|\phi_{i,j}\|_{C^{3,\alpha}(B_{16r}^i(p))} \leq C$. Consequently,

$$\|(g_i)_{jk}\|_{C^{2,\alpha}(B_{16r}^i(p))}, \|(g_i)^{jk}\|_{C^{2,\alpha}(B_{16r}^i(p))} \leq C, \quad j, k = 1, \dots, n.$$

Since the calculation of sectional curvature only involves the terms in form of $(g_i)_{jk}, (g_i)^{jk}, \frac{\partial}{\partial u_\beta^i}(g_i)^{jk}, \frac{\partial}{\partial u_\beta^i}(g_i)_{jk}, \frac{\partial^2}{\partial u_\beta^i \partial u_\gamma^i}(g_i)_{jk}$ ($j, k, \beta, \gamma = 1, \dots, n$), $|K_{g_i}|$ has a uniform upper bound $C_0 = C_0(K, n, D, \tau)$.

Step 2 Uniform lower injectivity radius bound on (M^n, g_i) .

By Step 1, we may take $r' = \min\{r, C_0^{-1}\}$, which is still denoted as r . In order to use Theorem 6.3, we need nothing but the lower bound of $\text{vol}_{g_i}(B_r^i(p))$. It suffices to apply (6.3) and Bishop-Gromov volume comparison theorem again to show that

$$\tilde{C}(K, n, D, \tau)r^n \leq \text{vol}_{g_i}(B_r^i(p)) \leq C(K, n)D^n, \quad (6.9)$$

because (6.9), Theorem 6.3 as well as the two-sided sectional curvature bound obtained in Step 1 then imply that $\inf_{p \in M^n} \text{inj}_{g_i}(p) \geq \tilde{C}(K, n, D, \tau)$.

Step 3 Improvement of the regularity.

In order to apply Theorem 6.2, it suffices to show that for any $k \geq 0$, there exists $C_k(K, n, D, \tau)$ such that $|(\nabla^{g_i})^k \text{Ric}_{g_i}|(p) \leq C_k(K, n, D, \tau)$ holds for any arbitrary but fixed $p \in M^n$. Since the case $k = 0$ is already proved in Step 1, we prove the case $k = 1$.

Using the Schauder interior estimate again and an argument similar to Step 1 gives the following $C^{4,\alpha}$ -estimate of $\phi_{i,j}$:

$$\|\phi_{i,j}\|_{C^{4,\alpha}(B_r^i(p))} \leq C_1(K, n, D, \tau),$$

which implies that

$$\|(g_i)_{jk}\|_{C^{3,\alpha}(B_r^i(p))}, \|(g_i)^{jk}\|_{C^{3,\alpha}(B_r^i(p))} \leq C_1(K, n, D, \tau), \quad j, k = 1, \dots, n.$$

Therefore, we see

$$\sup_{M^n} |\nabla^{g_i} \text{Ric}_{g_i}| \leq C_1(K, n, D, \tau).$$

Now by using the proof by induction, for any $k \geq 2$, there exists $C_k = C_k(K, n, D, \tau)$ such that

$$\sup_{M^n} |(\nabla^{g_i})^k \text{Ric}_{g_i}| \leq C_k(K, n, D, \tau),$$

which suffices to conclude. □

Proof of Theorem 1.29. The proof is almost the same as that of Theorem 6.1, and we omit some details. Assume the contrary, i.e. there exists a sequence of pairwise non-diffeomorphic Riemannian manifolds $\{(M_i^n, g_i)\}$ such that $(M_i^n, g_i) \in \mathcal{N}(K, n, D, i^{-1}, \tau)$ for any $i \in \mathbb{N}$. Then for each $\{(M_i^n, g_i)\}$, the almost isometric immersion condition ensures the existence of some $m_i \in \mathbb{N}$, such that

$$\frac{1}{\text{vol}_{g_i}(M_i^n)} \int_{M_i^n} \left| \sum_{j=1}^{m_i} d\phi_{i,j} \otimes d\phi_{i,j} - g_i \right| d\text{vol}_{g_i} \leq \frac{1}{i}. \quad (6.10)$$

Thus

$$\begin{aligned} \frac{\tau^2 \mu_{i,j}}{\text{vol}_{g_i}(M_i^n)} &\leq \frac{1}{\text{vol}_{g_i}(M_i^n)} \int_{M_i^n} |\nabla^{g_i} \phi_{i,j}|^2 d\text{vol}_{g_i} \\ &\leq \frac{1}{\text{vol}_{g_i}(M_i^n)} \int_{M_i^n} \left(\sum_{j,k=1}^{m_i} \langle \nabla^{g_i} \phi_{i,j}, \nabla^{g_i} \phi_{i,k} \rangle^2 \right)^{\frac{1}{2}} d\text{vol}_{g_i} \\ &\leq \frac{1}{\text{vol}_{g_i}(M_i^n)} \int_{M_i^n} \left| \sum_{j=1}^{m_i} d\phi_{i,j} \otimes d\phi_{i,j} - g_i \right| d\text{vol}_{g_i} + \frac{1}{\text{vol}_{g_i}(M_i^n)} \int_{M_i^n} |g_i| d\text{vol}_{g_i} \\ &\leq \frac{1}{i} + \sqrt{n}. \end{aligned} \quad (6.11)$$

Applying Li-Yau's first eigenvalue lower bound [LY80, Theorem 7] and Bishop-Gromov volume comparison theorem to (6.11) shows that

$$C_1(K, n, D) \leq \mu_{i,j} \leq C_2(K, n, D, \tau). \quad (6.12)$$

It then follows from (6.11) and (6.12) that

$$C_3(K, n, D, \tau) \leq \text{vol}_{g_i}(M_i^n) \leq C_4(K, n, D) \text{ and } \tau \leq \|\phi_{i,j}\|_{L^2(\text{vol}_{g_i})} \leq C_5(K, n, D). \quad (6.13)$$

To see $\{m_i\}$ has an upper bound, it suffices to notice that

$$\begin{aligned}
& \left| \sum_{j=1}^{m_i} \|\phi_{i,j}\|_{L^2(\text{vol}_{g_i})}^2 \mu_{i,j} - n \text{vol}_{g_i}(M_i^n) \right| \\
&= \left| \int_{M_i^n} \left\langle \sum_{j=1}^{m_i} d\phi_{i,j} \otimes d\phi_{i,j} - g_i, g_i \right\rangle d\text{vol}_{g_i} \right| \\
&\leq \sqrt{n} \int_{M_i^n} \left| \sum_{j=1}^{m_i} d\phi_{i,j} \otimes d\phi_{i,j} - g_i \right| d\text{vol}_{g_i} \leq \sqrt{n} C_4(K, n, D) \frac{1}{i}
\end{aligned}$$

As a result, $m_i \leq C_6(K, n, D, \tau)$. Therefore there exists $m \in \mathbb{N}$ and a subsequence of $\{(M_i^n, g_i)\}$ which is still denoted as $\{(M_i^n, g_i)\}$, such that each (M_i^n, g_i) admits an i^{-1} -almost isometrically immersing eigenmap into \mathbb{R}^m . In addition, $\{(M_i^n, g_i)\}$ can also be required to satisfy

$$(M_i^n, \mathbf{d}_{g_i}, \text{vol}_{g_i}) \xrightarrow{\text{mGH}} (X, \mathbf{d}, \mathcal{H}^n)$$

for some non-collapsed $\text{RCD}(K, n)$ space $(X, \mathbf{d}, \mathcal{H}^n)$. Again combining (6.10)-(6.13) with Theorems 2.33 and 2.34, we see that on $(X, \mathbf{d}, \mathcal{H}^n)$,

$$g = \sum_{j=1}^m d\phi_j \otimes d\phi_j,$$

where each ϕ_j is an eigenfunction of $-\Delta$ with the eigenvalue $\mu_j := \lim_{i \rightarrow \infty} \mu_{i,j}$. Finally, it suffices to apply Theorem 1.16 and [ChCo1, Theorem A.1.12] to deduce the contradiction. \square

7 Examples

In this section, some examples about the IHKI condition of Riemannian manifolds are provided. Let us first emphasize that if (M^n, g) is an n -dimensional compact IHKI Riemannian manifold, then it follows from Corollary 1.18 and Takahashi theorem [Ta66, Theorem 3] that for any $t > 0$, $\rho_t^{M^n} : (p \mapsto \rho^{M^n}(p, p, t))$ is a constant function. By Lemma 3.11, we see that

1. For any $k, n \in \mathbb{N}$, $\underbrace{\mathbb{S}^n \times \cdots \times \mathbb{S}^n}_{2^k \text{times}}$ is IHKI.
2. For any $p, q \in \mathbb{N}$, the compact Lie group $\text{SO}(2p+q)/\text{SO}(2p) \times \text{SO}(q)$ with a constant positive Ricci curvature is IHKI since it is homogeneous and irreducible.

Example 7.3 gives the sharpness of Theorem 1.11. The construction of Example 7.3 needs the following two lemmas.

Lemma 7.1. *Let (M^m, g) , (N^n, h) , $(M^m \times N^n, \tilde{g})$ be $m, n, (m+n)$ -dimensional IHKI Riemannian manifolds respectively, where \tilde{g} is the standard product Riemannian metric. Then for any $t > 0$, it holds that $(\rho_t^{M^m \times N^n})^n = (\rho_t^{N^n})^m$.*

Proof. Owing to Lemmas 3.11 and 3.12, we have

$$\begin{aligned} c^{M^m \times N^n}(t) g_t^{M^m \times N^n}(p, q) &= c^{M^m \times N^n}(t) \rho_{2t}^{M^m} g_t^{N^n}(q) + c^{M^m \times N^n}(t) \rho_{2t}^{N^n} g_t^{M^m}(p) \\ &= \rho_{2t}^{M^m} \frac{c^{M^m \times N^n}(t)}{c^{N^n}(t)} h(q) + \rho_{2t}^{N^n} \frac{c^{M^m \times N^n}(t)}{c^{M^m}(t)} g(p) \\ &= \tilde{g}(p, q). \end{aligned} \quad (7.1)$$

Then from (7.1), $\rho_{2t}^{N^n} c^{N^n}(t) = \rho_{2t}^{M^m} c^{M^m}(t)$ for any $t > 0$. Moreover, for any $p \in M^m$, we calculate that

$$\begin{aligned} \frac{\partial}{\partial t} \rho_{2t}^{M^m}(p) &= \frac{\partial}{\partial t} \int_{M^m} (\rho^{M^m}(p, p', t))^2 \text{dvol}_g(p') \\ &= 2 \int_{M^m} \Delta_{p'}^{M^m} \rho^{M^m}(p, p', t) \rho^{M^m}(p, p', t) \text{dvol}_g(p') \\ &= -2 \int_{M^m} |\nabla_{p'}^{M^m} \rho^{M^m}(p, p', t)|^2 \text{dvol}_g(p') = -2 \langle g_t^{M^m}, g \rangle(p) = -\frac{2m}{c^{M^m}(t)}. \end{aligned}$$

Analogously $\frac{\partial}{\partial t} \rho_{2t}^{N^n} = -\frac{2n}{c^{N^n}(t)}$, and thus $n \rho_{2t}^{N^n} \frac{\partial}{\partial t} \rho_{2t}^{M^m} = m \rho_{2t}^{M^m} \frac{\partial}{\partial t} \rho_{2t}^{N^n}$. Therefore there exists $\tilde{c} > 0$, such that

$$(\rho_t^{M^m \times N^n})^n = \tilde{c} (\rho_t^{N^n})^m, \quad \forall t > 0.$$

To see $\tilde{c} = 1$, it suffices to use a blow up argument and Theorem 2.36 to show that $\lim_{t \rightarrow 0} t^{\frac{m}{2}} \rho_t^{M^m} = (4\pi)^{-\frac{m}{2}}$ and $\lim_{t \rightarrow 0} t^{\frac{n}{2}} \rho_t^{N^n} = (4\pi)^{-\frac{n}{2}}$. \square

Lemma 7.2. *Let (M^n, g) be an n -dimensional closed IHKI Riemannian manifold. Then it holds that*

$$\lim_{t \rightarrow \infty} \frac{t}{c^{M^n}(t) \rho_{2t}^{M^n}} = 0.$$

Proof. Set $0 = \mu_0 < \mu_1 \leq \dots \rightarrow +\infty$ as the eigenvalues of $-\Delta$ counting with multiplicities. Then it suffices to notice that

$$\frac{1}{c^{M^n}(t)} = \frac{1}{n \text{vol}_g(M^n)} \sum_{i=1}^{\infty} e^{-2\mu_i t} \mu_i, \quad \rho_{2t}^{M^n} = \frac{1}{\text{vol}_g(M^n)} \sum_{i=0}^{\infty} e^{-2\mu_i t}$$

and let $t \rightarrow \infty$. \square

Example 7.3. Set $\mathbb{S}^n(k) := \{(x_1, \dots, x_{n+1}) \in \mathbb{R}^{n+1} : x_1^2 + \dots + x_{n+1}^2 = k^2\}$. Observe that $c^{\mathbb{S}^n(k)}(1) = k^{n+2} c^{\mathbb{S}^n}(k^{-2})$, $\rho_2^{\mathbb{S}^n(k)} = k^{-n} \rho_{2k^{-2}}^{\mathbb{S}^n}$. By Lemma 7.2,

$$\lim_{k \rightarrow 0} c^{\mathbb{S}^n(k)}(1) \rho_2^{\mathbb{S}^n(k)} = \infty.$$

This implies that for any small $r > 0$, there exists $s = s(r)$ such that

$$c^{\mathbb{S}^1(r)}(1) \rho_2^{\mathbb{S}^1(r)} = c^{\mathbb{S}^2(s)}(1) \rho_2^{\mathbb{S}^2(s)}.$$

Consider the product Riemannian manifold $(\mathbb{S}^1(r) \times \mathbb{S}^2(s), g_{\mathbb{S}^1(r) \times \mathbb{S}^2(s)})$. By (7.1), there exists $c(r) > 0$, such that $c(r) \Phi_1^{\mathbb{S}^1(r) \times \mathbb{S}^2(s)}$ realizes an isometric immersion into $L^2(\text{vol}_{g_{\mathbb{S}^1(r) \times \mathbb{S}^2(s)}})$.

If $(\mathbb{S}^1(r) \times \mathbb{S}^2(s), g_{\mathbb{S}^1(r) \times \mathbb{S}^2(s)})$ is IHKI, then by Proposition 7.1, it holds that

$$\rho_t^{\mathbb{S}^2(s)} = \left(\rho_t^{\mathbb{S}^1(r)} \right)^2 = \rho_t^{\mathbb{S}^1(r) \times \mathbb{S}^1(r)}, \quad \forall t > 0. \quad (7.2)$$

Therefore by taking integral of (7.2), we see that for any $t > 0$,

$$\text{vol}(\mathbb{S}^2(s)) \sum_{i=0}^{\infty} \exp\left(-r^{-2} \mu_i^{\mathbb{S}^1 \times \mathbb{S}^1} t\right) = \text{vol}(\mathbb{S}^1(r) \times \mathbb{S}^1(r)) \sum_{i=0}^{\infty} \exp\left(-s^{-2} \mu_i^{\mathbb{S}^2} t\right). \quad (7.3)$$

Then $\text{vol}(\mathbb{S}^2(r_2)) = \text{vol}(\mathbb{S}^1(r_1) \times \mathbb{S}^1(r_1))$ follows by letting $t \rightarrow 0$ in (7.3), which implies that $s(r) = r$. (7.3) then becomes

$$\sum_{i=1}^{\infty} \exp\left(-r^{-2} \mu_i^{\mathbb{S}^1 \times \mathbb{S}^1} t\right) = \sum_{i=1}^{\infty} \exp\left(-r^{-2} \mu_i^{\mathbb{S}^2} t\right), \quad \forall t > 0. \quad (7.4)$$

Since $\mu_1^{\mathbb{S}^1 \times \mathbb{S}^1} = \mu_4^{\mathbb{S}^1 \times \mathbb{S}^1} = 2 < \mu_5^{\mathbb{S}^1 \times \mathbb{S}^1}$ and $\mu_1^{\mathbb{S}^2} = \mu_3^{\mathbb{S}^2} = 2 < \mu_4^{\mathbb{S}^2}$, multiplying $\exp(2r^{-2}t)$ to both sides of (7.4) and letting $t \rightarrow \infty$, the right hand side of (7.4) converges to 3, while the left hand side of (7.4) converges to 4. A contradiction.

There is also a simple example which does not satisfy the condition 2 in Corollary 3.13.

Example 7.4. Consider the product manifold $(\mathbb{S}^1 \times \mathbb{R}, g_{\mathbb{S}^1 \times \mathbb{R}})$. It is obvious that

$$\begin{aligned} \pi g_t^{\mathbb{S}^1 \times \mathbb{R}} &= \frac{1}{(4\pi t)^{\frac{1}{2}}} \sum_{i=1}^{\infty} e^{-i^2 t} g_{\mathbb{S}^1} + \frac{c_1^{\mathbb{R}}}{t^{\frac{3}{2}}} \sum_{i=0}^{\infty} e^{-i^2 t} i^2 g_{\mathbb{R}} \\ &\geq \frac{1}{(4\pi t)^{\frac{1}{2}}} g_{\mathbb{S}^1} + \frac{c_1^{\mathbb{R}}}{t^{\frac{3}{2}}} g_{\mathbb{R}}, \end{aligned}$$

As a result, $g_t^{\mathbb{S}^1 \times \mathbb{R}} \geq \frac{c_1^{\mathbb{R}}}{\pi} t^{-\frac{3}{2}} g_{\mathbb{S}^1 \times \mathbb{R}}$ for any sufficiently large $t > 0$ but

$$\lim_{t \rightarrow \infty} t^{-2} c(t) = \lim_{t \rightarrow \infty} t^{-2} \frac{\pi}{c_1^{\mathbb{R}}} t^{\frac{3}{2}} = 0.$$

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